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(54) EFFICIENT MOTION VECTOR CODING FOR VIDEO COMPRESSION

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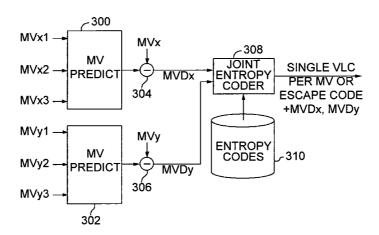
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(57) ABSTRACT

Video coding efficiency is improved by jointly coding the x and y components of motion vectors with a single variable length code. The motion vector components for a block of pixels are predicted based on motion vectors of neighboring blocks of pixels. The predicted x and y components are then jointly coded by assigning a single variable length code corresponding to the pair of components, rather than a separate code for each component. If the x and y components do not have a corresponding entry in the coding table, they are coded with an escape code followed by fixed length codes.

20 Claims, 4 Drawing Sheets



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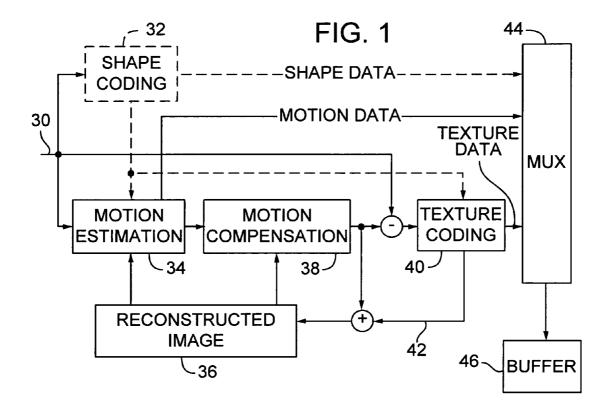
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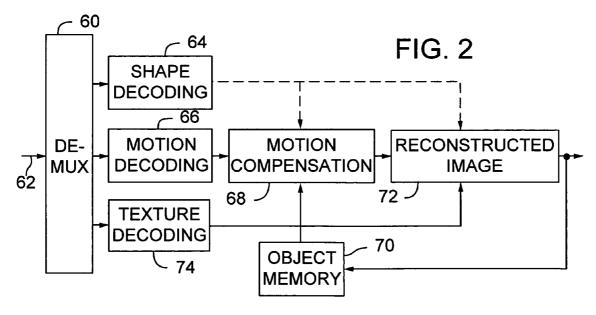
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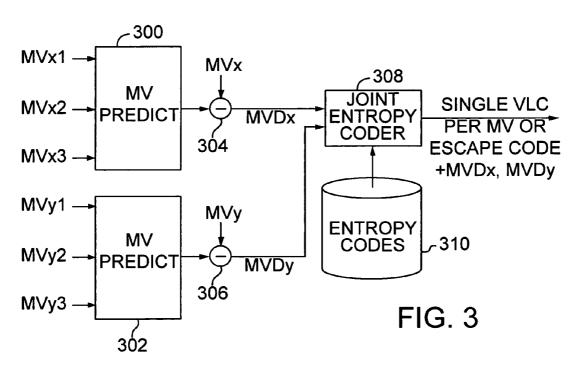
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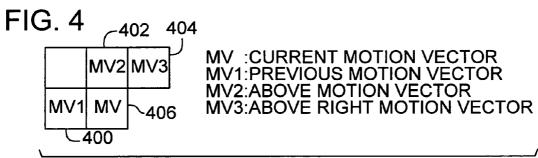
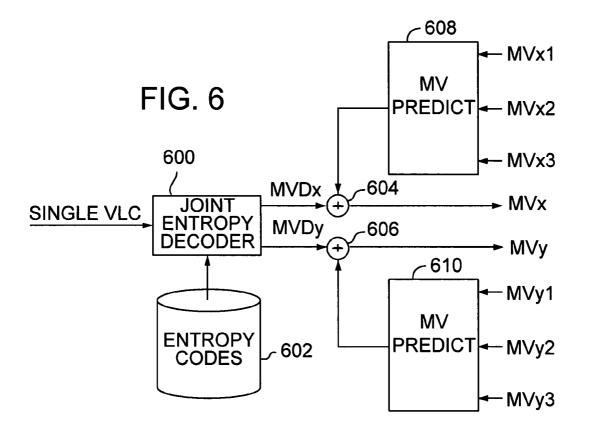
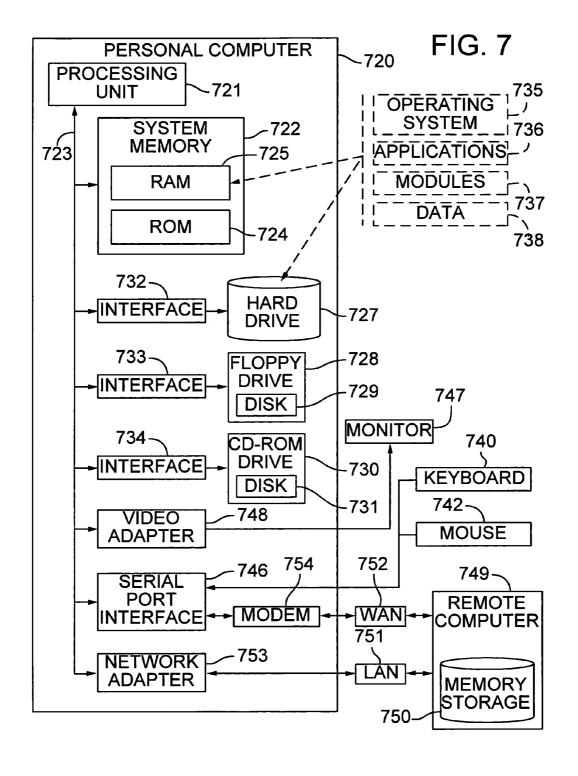


FIG. 5 522 512 514 -502 504 524 MV1 MV2 MV1 $(0,0)^{|}MV$ MV1 MV 506 -516 -510 520-500-: PICTURE BORDER





EFFICIENT MOTION VECTOR CODING FOR VIDEO COMPRESSION

FIELD OF THE INVENTION

The invention relates to video coding, and specifically, to an improved method for coding motion vectors.

BACKGROUND OF THE INVENTION

Full-motion video displays based upon analog video signals have long been available in the form of television. With recent advances in computer processing capabilities and affordability, full-motion video displays based upon digital video signals are becoming more widely available. Digital video systems can provide significant improvements over conventional analog video systems in creating, modifying, transmitting, storing, and playing full-motion video sequences.

Digital video displays include large numbers of image frames that are played or rendered successively at frequencies of between 30 and 75 Hz. Each image frame is a still image formed from an array of pixels based on the display resolution of a particular system. As examples, VHS-based systems have display resolutions of 320×480 pixels, NTSCbased systems have display resolutions of 720×486 pixels, and high-definition television (HDTV) systems under development have display resolutions of 1360×1024 pixels.

The amounts of raw digital information included in video sequences are massive. Storage and transmission of these amounts of video information is infeasible with conventional personal computer equipment. Consider, for example, a digitized form of a relatively low resolution VHS image motion picture of two hours in duration at this resolution corresponds to 100 gigabytes of digital video information. By comparison, conventional compact optical disks have capacities of about 0.6 gigabytes, magnetic hard disks have capacities of 1-2 gigabytes, and compact optical disks under 40 development have capacities of up to 8 gigabytes.

To address the limitations in storing or transmitting such massive amounts of digital video information, various video compression standards or processes have been established, including MPEG-1, MPEG-2, and H.26X. These video 45 compression techniques utilize similarities between successive image frames, referred to as temporal or interframe correlation, to provide interframe compression in which motion data and error signals are used to encode changes between frames.

In addition, the conventional video compression techniques utilize similarities within image frames, referred to as spatial or intraframe correlation, to provide intraframe compression in which the image samples within an image frame are compressed. Intraframe compression is based upon con- 55 ventional processes for compressing still images, such as discrete cosine transform (DCT) encoding. This type of coding is sometimes referred to as "texture" or "transform" coding. A "texture" generally refers to a two-dimensional array of image sample values, such as an array of chromi- 60 nance and luminance values or an array of alpha (opacity) values. The term "transform" in this context refers to how the image samples are transformed into spatial frequency components during the coding process. This use of the term "transform" should be distinguished from a geometric trans- 65 form used to estimate scene changes in some interframe compression methods.

Interframe compression typically utilizes motion estimation and compensation to encode scene changes between frames. Motion estimation is a process for estimating the motion of image samples (e.g., pixels) between frames. Using motion estimation, the encoder attempts to match blocks of pixels in one frame with corresponding pixels in another frame. After the most similar block is found in a given search area, the change in position of the pixel locations of the corresponding pixels is approximated and represented as motion data, such as a motion vector. Motion compensation is a process for determining a predicted image and computing the error between the predicted image and the original image. Using motion compensation, the encoder applies the motion data to an image and computes a predicted image. The difference between the predicted image and the input image is called the error signal. Since the error signal is just an array of values representing the difference between image sample values, it can be compressed using the same texture coding method as used for intraframe coding of image samples.

Although differing in specific implementations, the MPEG-1, MPEG-2, and H.26X video compression standards are similar in a number of respects. The following description of the MPEG-2 video compression standard is generally applicable to the others.

MPEG-2 provides interframe compression and intraframe compression based upon square blocks or arrays of pixels in video images. A video image is divided into image sample blocks called macroblocks having dimensions of 16×16 pixels. In MPEG-2, a macroblock comprises four luminance blocks (each block is 8×8 samples of luminance (Y)) and two chrominance blocks (one 8×8 sample block each for Cb and Cr).

In MPEG-2, interframe coding is performed on macrobformat having a 320×480 pixel resolution. A full-length 35 locks. An MPEG-2 encoder performs motion estimation and compensation to compute motion vectors and block error signals. For each block MN in an image frame N, a search is performed across the image of a next successive video frame N+1 or immediately preceding image frame N-1 (i.e., bi-directionally) to identify the most similar respective blocks \mathbf{M}_{N+1} or \mathbf{M}_{N-1} . The location of the most similar block relative to the block MN is encoded with a motion vector (DX,DY). The motion vector is then used to compute a block of predicted sample values. These predicted sample values are compared with block MN to determine the block error signal. The error signal is compressed using a texture coding method such as discrete cosine transform (DCT)

> Object-based video coding techniques have been proposed as an improvement to the conventional frame-based coding standards. In object-based coding, arbitrary shaped image features are separated from the frames in the video sequence using a method called "segmentation." The video objects or "segments" are coded independently. Objectbased coding can improve the compression rate because it increases the interframe correlation between video objects in successive frames. It is also advantageous for variety of applications that require access to and tracking of objects in a video sequence.

> In the object-based video coding methods proposed for the MPEG-4 standard, the shape, motion and texture of video objects are coded independently. The shape of an object is represented by a binary or alpha mask that defines the boundary of the arbitrary shaped object in a video frame. The motion of an object is similar to the motion data of MPEG-2, except that it applies to an arbitrary-shaped image of the object that has been segmented from a rectangular

frame. Motion estimation and compensation is performed on blocks of a "video object plane" rather than the entire frame. The video object plane is the name for the shaped image of an object in a single frame.

The texture of a video object is the image sample information in a video object plane that falls within the object's shape. Texture coding of an object's image samples and error signals is performed using similar texture coding methods as in frame-based coding. For example, a segmented image can be fitted into a bounding rectangle formed of macroblocks. The rectangular image formed by the bounding rectangle can be compressed just like a rectangular frame, except that transparent macroblocks need not be coded. Partially transparent blocks are coded after filling in the portions of the block that fall outside the object's shape 15 boundary with sample values in a technique called "padding."

In both frame-based and object-based video coding, the encoded bit stream typically includes many interframe-coded frames (P frames). Each of these P frames includes at 20 least one motion vector per macroblock, and each motion vector includes X and Y components that coded independently. As such, motion vectors contribute a significant amount of data for each coded P frame. There is a need, therefore, for more efficient motion vector coding schemes. 25

SUMMARY OF THE INVENTION

The invention provides an improved method of coding motion vectors for video coding applications. One aspect of 30 the invention is a method for jointly coding a motion vector with a single entropy code. This method is based on the discovery that the probability of the X and Y components of the motion vector are not totally independent. To exploit the correlation between the motion vector components, the 35 method uses entropy coding to assign a single variable length code to a joint parameter representing the combined X and Y components of the motion vector. Motion vector component pairs that are more likely are assigned a shorter length code, while less likely component pairs are assigned 40 a longer length code or are coded with an escape code followed by a code for each component. This approach can be used in a variety of video coding applications, including both object-based and frame based coding. In addition, joint entropy coding of motion vectors can be used in combina- 45 tion with spatial prediction to code motion vectors more

For example, in one implementation, an encoder first computes a predictor for the motion vector, and then computes differential X and Y components from the X and Y 50 components of the vector currently being processed and its predictor. A joint entropy coder then computes a single variable length code for a joint parameter representing both the X and Y differential components.

The decoder performs the inverse of the encoder operations to reconstruct the motion vector from the variable length code. In particular, it computes the joint parameter from the variable length code, and then reconstructs the motion vector from the differential components and the components of the predictor.

Additional features of the invention will become more apparent from the following detailed description and accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

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FIG. 2 is a block diagram of a video decoder.

FIG. 3 is a block diagram illustrating how an implementation of the invention jointly codes motion vector components for a macroblock with a single entropy code.

FIG. 4 is a diagram illustrating how a predictor for the motion vector of a current block is selected from motion vectors of neighboring macroblocks.

FIG. 5 is a diagram illustrating how a motion vector predictor is selected in cases where one or more neighboring macroblocks are outside the picture.

FIG. 6 is a block diagram illustrating how an implementation of the invention decodes a jointly coded motion vector

FIG. 7 is a diagram of a computer system that serves as an operating environment for a software implementation of the invention.

DETAILED DESCRIPTION

Introduction

The first section below provides a description of a video encoder and decoder. Subsequent sections describe how to improve coding of motion vectors by exploiting the correlation between the X and Y components of the vectors.

This approach for jointly coding the X and Y components of a motion vector applies to both frame-based and objectbased video coding. Both forms of video coding employ motion vectors to define the motion of a pixel or block of pixels from one frame to another. Typically, a motion vector is computed for regular sized blocks of pixels. In framebased coding, the frame is divided into regular sized blocks. In object-based coding, each video object plane is divided into blocks. Since the object represented in a video object plane usually has a non-rectangular shape, object-based coders use the shape to determine which pixels in each block fall within the boundaries of the object. While frame-based and object-based coding differ in this respect, both approaches use motion vectors that define the motion of pixels in a block. Thus, the correlation between the X and Y components of motion vectors in both types of coders can be exploited to improve coding efficiency.

While the encoder and decoder described in the next section are object-based, they provide a sufficient basis for explaining how to implement the invention in both framebased and object-based coding schemes.

Description of an Example Encoder and Decoder

FIG. 1 is a block diagram illustrating an implementation of an object-based video encoder. The input 30 to the encoder includes images representing the video objects in each frame, the shape of each video object and bounding rectangles. The shape information is available before the encoder codes texture or motion data. Frame-based coding differs in that the entire frame is coded without shape information, and the input 30 consists of a series of image frames.

The shape coding module 32 reads the definition of an object including its bounding rectangle and extends the bounding rectangle to integer multiples of macroblocks. The shape information for an object comprises a mask or "alpha plane." The shape coding module 32 reads this mask and compresses it, using for example, a conventional chain coding method to encode the contour of the object.

Motion estimation module 34 reads an object including its bounding rectangle and a previously reconstructed image 36 and computes motion estimation data used to predict the motion of an object from one frame to another. The motion

estimation module **34** searches for the most similar macroblock in the reconstructed image for each macroblock in the current image to compute a motion vector for each macroblock. The specific format of the motion vector from the motion estimation module **34** can vary depending on the 5 motion estimation method used. In the implementation described below, there is a motion vector for each macroblock, which is consistent with current MPEG and H26X formats.

The motion compensation module 38 reads the motion 10 vectors computed by the motion estimation module and the previously reconstructed image 36 and computes a predicted image for the current frame. Each pixel in the predicted image is constructed by using the motion vector for the macroblock that it resides in to find the corresponding pixel 15 in the previously reconstructed image 36. The encoder then finds the difference between the image sample values in the input image block as specified in the input 30 and the corresponding sample values in the predicted image block as computed in the motion compensation module 38 to determine the error signal for the macroblock.

Texture coding module **40** compresses this error signal for inter-frame coded objects and compresses image sample values for the object from the input data stream for intra-frame coded objects. The feedback path **42** from the texture 25 coding module **40** represents the error signal. The encoder uses the error signal blocks along with the predicted image blocks from the motion compensation module to compute the previously reconstructed image **36**.

The texture coding module **40** codes intra-frame and error 30 signal data for an object using any of a variety of still image compression techniques. Example compression techniques include DCT, wavelet, as well as other conventional image compression methods.

The bit stream of the compressed video sequence includes 35 the shape, motion and texture coded information from the shape coding, motion estimation, and texture coding modules. Multiplexer 44 combines and formats this data into the proper syntax and outputs it to the buffer 46. As explained in more detail below, the encoder also includes a motion 40 vector encoder that uses entropy coding to jointly code the x and y components of the motion vector for each macroblock. The motion vector encoder may be implemented as part of the motion estimation module 34 or as part of the data formatting functions in the multiplexer 44.

While the encoder can be implemented in hardware or software, it is most likely implemented in software. In a software implementation, the modules in the encoder represent software instructions stored in memory of a computer and executed in the processor, and the video data stored in 50 memory. A software encoder can be stored and distributed on a variety of conventional computer readable media. In hardware implementations, the encoder modules are implemented in digital logic, preferably in an integrated circuit. Some of the encoder functions can be optimized in special-purpose digital logic devices in a computer peripheral to off-load the processing burden from a host computer.

FIG. 2 is a block diagram illustrating a decoder for an object-based video coding method. A demultiplexer 60 receives a bit stream representing a compressed video 60 sequence and separates shapes, motion and texture encoded data on an object by object basis. The demultiplexer also includes a motion vector decoder that reconstructs the motion vector for each macroblock from a single variable length code.

Shape decoding module **64** decodes the shape or contour for the current object being processed. To accomplish this,

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it employs a shape decoder that implements the inverse of the shape encoding method used in the encoder of FIG. 1. The resulting shape data is a mask, such as a binary alpha plane or gray scale alpha plane representing the shape of the object.

The motion decoding module 66 decodes the motion information in the bit stream. The decoded motion information includes the motion vectors for each macroblock that are reconstructed from entropy codes in the incoming bit-stream. The motion decoding module 66 provides this motion information to the motion compensation module 68, and the motion compensation module 68 uses the motion vectors to find predicted image samples in the previously reconstructed object data 70.

The texture decoding module 74 decodes error signals for inter-frame coded texture data and an array of color values for intra-frame texture data and passes this information to a module 72 for computing and accumulating the reconstructed image. For inter-frame coded objects, this module 72 applies the error signal data to the predicted image output from the motion compensation module to compute the reconstructed object for the current frame. For intra-frame coded objects the texture decoding module 74 decodes the image sample values for the object and places the reconstructed object in the reconstructed object module 72. Previously reconstructed objects are temporarily stored in object memory 70 and are used to construct the object for other frames.

Like the encoder, the decoder can be implemented in hardware, software or a combination of both. In software implementations, the modules in the decoder are software instructions stored in memory of a computer and executed by the processor, and video data stored in memory. A software decoder can be stored and distributed on a variety of conventional computer readable media. In hardware implementations, the decoder modules are implemented in digital logic, preferably in an integrated circuit. Some of the decoder functions can be optimized in special-purpose digital logic devices in a computer peripheral to off-load the processing burden from a host computer.

Improved Coding of Motion Vectors

The coding efficiency of motion vectors can be improved by exploiting the correlation between the X and Y components of a motion vector. Traditional coding methods code the X and Y components separately based on the premise that the probability distribution of the X and Y components are independent. We have discovered that the X and Y components are not totally independent, but instead, have a correlation.

To take advantage of this correlation, an implementation of the invention assigns a single entropy code to the joint X and Y components of a motion vector. Before coding, sample video data for a target bit rate and content scenario is used to generate a codebook. This codebook assigns a single variable length code to pairs of X and Y components based on their frequency of occurrence. More frequent, and therefore statistically more probable pairs, are assigned shorter length codes, while less frequent pairs are assigned longer length codes. A statistical analysis program computes the probability of each of the joint X and Y components by extracting the motion vector data generated from an encoder for several example video sequences that have the desired type of content. The program creates a probability distribution for pairs of motion vectors (namely, differential motion vectors) and then assigns codes to a subset of the motion vectors that are most probable.

To limit the size of the codebook, low probability pairs need not be assigned a code. Instead, these pairs can be coded by using an escape code to indicate that the motion vector components follow in fix length bit fields. Pairs are excluded from the codebook based on where they fall in the 5 probability distribution.

While not required, the coding of motion vectors can be improved by using a differential coding process that takes advantage of the spatial dependency of motion vectors. In particular, a motion vector for a small block of pixels is 10 likely to point in a similar direction as the motion vector for a neighboring block, especially if both the current block and its neighbor are in a region of the frame having nearly uniform motion. One way to take advantage of this spatial dependency is to code the difference between a motion 15 vector for the current block and the motion vector for a neighboring block, called the predictor. The implementation uses a form of spatial prediction to encode the X and Y components before assigning a joint entropy code.

FIG. 3 is a block diagram illustrating how our implementation encodes motion vectors. The features shown in FIG. 3 are implemented in the encoder and operate on the motion vectors computed in the motion estimation block 34. First, the motion estimation block computes a motion vector for each macroblock in the frame. When a frame consists of 25 more than one video object plane, the motion estimation block computes motion vectors for the macroblocks of each video object plane.

The encoder begins coding the motion vector for each macroblock by computing a predictor for the current motion 30 vector. The implementation shown in FIG. 3 selects a predictor from among neighboring macroblocks. FIG. 4 shows an example of the positioning of the candidates for the predictor relative to the current macroblock for which the motion vector is being encoded. In this example, the 35 candidate macroblocks include the ones to the left 400, above 402, and above-right 404 relative to the current macroblock 406. The motion vectors for the candidate macroblocks are referred to as MV1, MV2, and MV3, respectively.

As shown in FIG. 3, the encoder computes the predictor separately for the X and Y components of the current macroblock. In particular, the motion vector predictors 300, 302 compute the median of the X and Y components for the candidate macroblocks. The median of these three values is chosen as the predictor for the X and Y components. The precise method of computing the predictor is not critical to the invention and other ways of selecting a predictor are possible. One alternative is to select a neighboring block located in the direction of the lowest gradient of the neighboring motion vectors. Another alternative is to compute an average of motion vectors of neighboring blocks.

Once the motion vector predictor selects the predictor, the encoder computes differential motion vector components. For each X and Y component, the encoder computes the 55 difference between the component of the current motion vector and the corresponding component of the predictor. As reflected by subtractor units 304, 306 in FIG. 3, the X component of the predictor is subtracted from the X component of the current vector MVx, and the Y component of the predictor is subtracted from the Y component of the current vector MVy.

The resulting differential X and Y components (MVDx and MVDy) are then formed into a joint parameter that is coded with a single variable length code, or an escape code 65 followed by fixed code word for each differential component. The implementation uses a joint Huffman coding table

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that is trained for a target bit rate and video content. The joint entropy coder 308 looks up the joint parameter in the table to find a corresponding variable length code. If the coder finds a match in the table, it codes the joint parameter with a single variable length code. Otherwise, it codes an escape code followed by a fixed length code word for each component.

The entropy codes 310 shown in FIG. 3 refer to the Huffman coding table. An example of a Huffman coding table trained for low bit rate, talking head applications is set forth at the end of this section in Table 1. Following Table 1, Table 2 is an example of a Huffman table trained for more general video applications. While our implementation uses Huffman coding tables, the entropy codes can be computed using other forms of entropy coding such as arithmetic coding.

Since the predictor is selected from motion vectors of neighboring blocks of pixels, the encoder applies special rules to address the situation where one or more neighboring blocks are outside the picture. FIG. 5 illustrates cases where a neighboring block is outside the picture and shows the motion vectors that are used to predict the motion vector in the current macroblock.

If one neighboring block is outside the picture (e.g., block 500 in FIG. 5), a zero motion vector (0,0) is used in its place. The predictor of the current macroblock 506 is computed as the median of the zero motion vector, and motion vectors MV2 and MV3 for the other two neighboring macroblocks 502, 504. As another example, the configuration on the far right of FIG. 5 shows the case where the above-right macroblock 524 is out of the picture. In this case, MV1 and MV2 for the other two macroblocks 520, 522 inside the picture are used along with the zero motion vector for the third macroblock 524 to predict the motion vector for the current macroblock 526.

If two candidate macroblocks 512, 514 are out of the picture (as shown in the middle diagram of FIG. 5), then the motion vector for the third neighboring macroblock 510 is selected as the predictor for the current macroblock 516.

FIG. 6 is a diagram illustrating an implementation of a decoder for decoding a single variable length code representing joint motion vector components into X and Y motion vector components. The joint entropy decoder 600 reads the variable length code as input and finds the corresponding differential X and Y components in the entropy codes 602. In the current implementation, the entry codes are in the form of a Huffman table (e.g., tables 1 or 2 listed below). As noted above, the encoder can also use an alternative entropy coding scheme, in which case, the decoder would have the appropriate codebook to correspond with the codebook used in the encoder.

In some cases, the motion vector may be coded with an escape code followed by two fixed length codes representing the differential motion vector components. In this case, the joint entropy decoder 600 recognizes the escape code and interprets the following data as differential motion vectors instead of a variable length code. It then passes the differential X and Y components to the next stage.

Next, the decoder forms the motion vector from the differential motion vector components MVDx, MVDy and the X and Y components of the predictor. In particular the decoder adds each differential motion vector component MVDx, MVDy and the X and Y components of the predictor (see adders 604, 606, FIG. 6). The decoder computes the predictor components in the same way as the encoder. In particular, it has a motion vector predictor that computes the predictor of the motion vectors previously decoded for the

Index

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56

57

58

59

60

61

62

63

64

65

 Mv_x

-1.5

0

-1.5

-1

-1.5

2.5 -2.5 2 3 2.5 0.5

TABLE 1-continued

XY Joint VLC Motion Vector Table for Talking Head Video

-3.5

 $^{-1}$

-1.5

1.5

0.5

-0.5

-0.5

0

-0.5

-2

Number of bits Code

10

10

10

10

11

11

11

11

11

11

11

0110000110

0110001000

0110001001

0110001111

00001000001

00001100001

00001100010

00001111101

00011001000

00011010011

00011100100

three neighboring macroblocks (MVx1, MVy), (MVx2, MVy2) and (MVx3, MVy3). In the implementation, the motion vector predictor blocks 608, and 610 represent the computation of the median of the X and Y components, respectively, of the neighboring macroblocks. As noted 5 above, other ways of computing the predictor are possible. Regardless of the specific form of prediction, the decoder performs inverse prediction according to the prediction scheme used in the encoder.

Once the motion vector for the current macroblock (MVx, 10 MVy) is reconstructed, it is stored and used to decode the motion vector for neighboring macroblocks according to the prediction scheme.

The following tables provide examples of Huffman coding tables trained for talking head video (Table 1) and more 15 general video content (Table 2)

ing tabl	es trained	for talkir	ng head video (Table 1) and more	15	65	0.5	-2	11	00011100100
	video co					66	0	3.5	11	00011100111
8						67	-0.5	-2	11	00100000100
		-				68	-1.5	-1.5	11	00100000101
		T	ABLE 1			69	-0.5	2.5	11	00100100100
						70	-2	-0.5	11	00100100101
$\underline{\mathbf{x}}$	Y Joint VLC	Motion Ve	ctor Table for Talk	ing Head Video	20	71	2	0.5	11	00100111100
						72	0.5	-2.5	11	00100111101
Index	Mv_x	Mv_y	Number of bits	Code		73	-1	2	11	00101001111
0	0	0	1	1		74 75	1 0.5	-2 2	11	00101111100
1	0	-0.5	1 4	0011		76	0.5	2.5	11 11	00101111101 00101111110
2	-0.5	-0.5 0	4	0101		70	-2	0.5	11	0101111110
3	-0.3 0	0.5	4	0101	25	78	-2 -2.5	0.5	11	01001000000
4	0.5	0.5	5	00010		79	-2.3 -3.5	-0.5	11	01001001100
5	-0.5	-0.5	5	01000		80	-0.5	-2.5	11	01001001111
6	0.5	-0.5	5	01101		81	-3	0	11	01001010110
7	-0.5	0.5	6	000000		82	3.5	-0.5	11	01001011100
8	0.5	0.5	6	000000		83	0	3	11	01001110001
9	0.5	1	6	011001	30	84	0	-3	11	01100010110
10	1	0	7	0000101	20	85	-0.5	-3.5	11	01100010111
11	0	-1	7	0001111		86	0.5	-3.5	11	01100010111
12	-1	Ô	7	0010110		87	3.5	0.5	11	01100011100
13	ō	1.5	8	00001001		88	-0.5	3.5	12	000010000100
14	-0.5	1	8	00001101		89	3	-0.5	12	000010000101
15	1	-0.5	8	00001110	35	90	-2	1	12	000010000111
16	1.5	0	8	00011011	33	91	2	-1	12	000011001000
17	0	-1.5	8	00011101		92	-5.5	0	12	000011001001
18	1	0.5	8	00100001		93	-4.5	0	12	000011001010
19	0.5	-1	8	00100110		94	5.5	0	12	000011001011
20	-1.5	0	8	00101000		95	2	1	12	000011110001
21	0.5	1	8	00101010	40	96	1	2	12	000011110010
22	-1	0.5	8	00101110	40	97	4.5	0	12	000011111000
23	-1	-0.5	8	01001100		98	-1	-2	12	000110010101
24	-0.5	-1	8	01001101		99	-3.5	0.5	12	000110100101
25	-0.5	1.5	9	000010001		100	-2	-1	12	000111001101
26	1.5	-0.5	9	000110000		101	-0.5	3	12	001000001101
27	-1.5	-0.5	9	000110001	45	102	-1	2.5	12	001001000111
28	0.5	-1.5	9	000110011	45	103	1	-2.5	12	001001001101
29	1.5	0.5	9	000110101		104	3	0.5	12	001010011101
30	0.5	1.5	9	001000000		105	1.5	-2	12	001010111000
31	1	-1	9	001001010		106	14.5	0	12	001010111110
32	-0.5	-1.5	9 9	001001011		107	1 -2	2.5	12	010010011010
33 34	-1.5	0.5	9	001010010	50	108	-2 -1	1.5 3	12 12	010010011100
34 35	-1 1	1 1	9	001011110 010010010	50	109 110	-1 2.5	-1.5	12	010010100111 010010101000
36	-1	-1	9	0110010010		111	2.5	-1.3 1	12	010010101000
37	2	0	10	0000110011		112	1.5	-2.5	12	010010101011
38	-2	0	10	0000110011		113	-2.5	-1.5	12	010010101110
39	0	2	10	000111111		114	2.3	-1.5	12	010010101111
40	1	-1.5	10	0001110000		115	-14.5	0	12	010010110110
41	2.5	0	10	0001110001	55	116	13.5	ō	12	010010110111
42	-1	1.5	10	0010010000		117	3	1	12	010010111100
43	-2.5	0	10	0010011100		118	2.5	1.5	12	010010111110
44	0	-2	10	0010011101		119	0	-14.5	12	010010111111
45	-3.5	0	10	0010011111		120	-0.5	-3	12	010011100001
46	3.5	0	10	0010101100		121	-1.5	2	12	010011111100
47	0	-2.5	10	0010101101	60	122	-3	-0.5	12	010011111101
48	1	1.5	10	0100100010		123	0.5	3	12	010011111111
49	0	2.5	10	0100100011		124	2.5	-1	12	011000001000
50	1.5	1	10	0100101000		125	0.5	-3	12	011000001001
51	1.5	-1.5	10	0100111001		126	-2.5	1.5	12	011000001010
52	1.5	-1	10	0100111011		127	-2.5	1	12	011000001011
53	-0.5	2	10	0110000011	65	128	1.5	2.5	12	011000010000
54	1.5	1.5	10	0110000101		129	1	-3	12	011000011100

TABLE 1-continued

TABLE 1-continued

					_	THE TOTAL COMMISSION					
X	Y Joint VLC	Motion Ve	ctor Table for Talk	ing Head Video		XY Joint VLC Motion Vector Table for Talking Head Video					
Index	Mv_x	Mv_y	Number of bits	Code	5	Index	Mv_x	Mv_y	Number of bits	Code	
130	1	-3.5	12	011000011110		205	-1.5	-3	14	00001100000100	
131	4	0	12	011000011111		206	3	-2	14	00001100000101	
132	5	0	12	011000101010		207	5.5	-0.5	14	00001100011000	
133	0.5	3.5	12	011000101011	40	208	-3	-2	14	00001100011001	
134 135	0 -1.5	-4.5 2.5	12 12	011000110000 011000110111	10	209 210	0 0.5	5 -4.5	14 14	00001100011010 00001100011011	
136	-1.5 -14	0	12	011000110111		211	5	-4.5 -0.5	14	00001100011011	
137	-13.5	0	13	0000100000000		212	-4	0.5	14	00001111011010	
138	-2	-1.5	13	0000100000001		213	4	-0.5	14	00001111011011	
139	-4	0	13	0000100001100		214	-2	3.5	14	00001111011100	
140	-3.5	-1.5 2	13 13	0000110000011	15	215	0 0	-15.5 13.5	14 14	00001111011101 00011001001000	
141 142	1.5 3.5	-1.5	13	0000110001110 0000111100000		216 217	0	15.5 -5	14	00011001001000	
143	3	-1	13	0000111100001		218	2	-2.5	14	000110010111110	
144	0	4.5	13	0000111101111		219	0	-14	14	00011001011111	
145	-4.5	-0.5	13	0000111110010		220	5.5	0.5	14	00011010010000	
146	-2.5	-1	13	0000111110011	20	221	-3.5	1	14	00011010010001	
147 148	0 -1	-5.5 3.5	13 13	0001100100101 0001100100110		222 223	-5.5 -0.5	0.5 -4	14 14	00011100101101 00011100101110	
149	1.5	-3.5	13	0001100100110		224	-1	4.5	14	00011100101111	
150	-3	1	13	0001100101000		225	-0.5	-14.5	14	00011100110000	
151	1	3	13	0001100101001		226	4.5	1.5	14	00011100110001	
152	14	0	13	0001101001001	25	227	-1.5	4.5	14	00100100011010	
153 154	2 -1.5	1.5 3.5	13 13	0001110010100 0001110010101	23	228 229	0.5 2.5	4.5 -2	14 14	00100100011011 00100100111010	
155	-1.5 -5	0	13	0001110010101		230	-3	2	14	00100100111010	
156	-3	0.5	13	0010000011000		231	2.5	2	14	00101001100010	
157	4.5	0.5	13	0010010011000		232	-2.5	-2	14	00101001110001	
158	-12.5	0	13	0010010011001		233	13.5	0.5	14	00101001110010	
159 160	-1 3	-2.5 -1.5	13 13	0010010011100	30	234 235	-4.5 0.5	1.5 -5.5	14 14	00101001110011	
161	-1	-1.5 -3.5	13	0010010011110 0010010011111		235 236	1.5	-3.5 -4.5	14 14	00101011100100 00101011100101	
162	2	-2	13	001010011111		237	-0.5	-5.5	14	00101011101101	
163	-1.5	-2.5	13	0010100110010		238	-0.5	-5	14	00101011101110	
164	-1	-3	13	0010101110011		239	2.5	2.5	14	00101011101111	
165	4.5	-0.5	13	0010101110100	35	240	3 3.5	-2.5 -2.5	14	00101011110000	
166 167	-3 -3.5	-1 1.5	13 13	0010101110101 0010101111011		241 242	3.3 0	-2.5 5.5	14 14	00101011110001 001010111110010	
168	0	-4	13	0010101111111		243	-4.5	-1.5	14	00101011110010	
169	1	-4	13	0010111111100		244	0	14	14	00101011110100	
170	-4	-0.5	13	0100100001111		245	-2.5	3.5	14	00101011110101	
171 172	3.5 -15.5	1 0	13 13	0100100110110 0100101001010	40	246 247	2.5 2	-2.5 -3.5	14 14	00101011111100 01001000010101	
173	-13.5 -3.5	-1	13	0100101001010		247	-0.5	-3.5 13.5	14	01001000010101	
174	3.5	1.5	13	0100101001011		249	4	1	14	01001000010111	
175	0	4	13	0100101010010		250	-3.5	-2.5	14	01001000011000	
176	-2	-2	13	0100101010011		251	-2.5	-2.5	14	01001000011001	
177	-1.5	3 -13.5	13 13	0100101010100	45	252 253	3 -0.5	-3 4	14	01001000011010 01001000011011	
178 179	0 3	-13.3 1.5	13	0100101010101 0100101101000		253 254	-0.3 2	2.5	14 14	01001000011011	
180	-3	-1.5	13	0100101101000		255	-2	-2.5	14	01001000011100	
181	2	2	13	0100101110101		256	-0.5	14.5	14	01001001101111	
182	-2	2	13	0100101110110		257	2	-3	14	01001001110100	
183	15.5	0	13	0100101110111	50	258	-3.5	3.5	14	01001001110101	
184 185	-2 3.5	3 -1	13 13	0100101111011 0100111000000	50	259 260	6.5 -14.5	0.5 -0.5	14 14	01001001110110 01001001110111	
186	-4.5	0.5	13	0100111000000		261	1	-5	14	01001001110111	
187	-5.5	-0.5	13	0100111110110		262	3	2.5	14	01001010010001	
188	-3	1.5	13	0100111110111		263	3.5	-3.5	14	01001010010010	
189	1.5	-3	13	0100111111100		264	4	-1	14	01001010010011	
190 191	-0.5 1.5	-4.5 3	13 13	0100111111101 0110000100110	55	265 266	3 -1	-3.5 -4	14 14	01001010011010 01001011001010	
191	12.5	0	13	0110000100110		267	0	14.5	14	01001011001010	
193	-0.5	4.5	13	0110000111010		268	-6.5	-0.5	14	01001011001100	
194	-1.5	-2	13	0110001010000		269	-4	1	14	01001011001101	
195	-1.5	-3.5	13	0110001010001		270	-3.5	-3.5	14	01001011001110	
196	-2	2.5	13	0110001010010	60	271	-3 6.5	3	14	01001011001111	
197 198	-1 -2.5	4 2.5	13 13	0110001010011 0110001110110		272 273	6.5 -6	0 0	14 14	01001011101000 01001011101001	
199	1.5	3.5	14	00001000000100		274	-0 -4	-1	14	01001011101001	
200	-15	0	14	00001000000101		275	0.5	-14.5	14	01001011110101	
201	3	2	14	00001000000110		276	0.5	14.5	14	01001111011101	
202	4	0.5	14	00001100000001	65	277	-0.5	5.5	14	01001111011110	
203 204	1 2.5	3.5 -3.5	14 14	00001100000010 00001100000011	0.5	278 279	4.5 1	-1.5 -4.5	14 14	01001111011111 01001111100000	
204	2.3	-5.5	74	20001100000011		217	1	-4.5	74	0.100.1111100000	

TABLE 1-continued

TABLE 1-continued

<u>XX</u>	Y Joint VLC	Motion Ve	ctor Table for Talk	ing Head Video	•	XY Joint VLC Motion Vector Table for Talking Head Video					
Index	Mv_x	Mv_y	Number of bits	Code	5	Index	Mv_x	Mv_y	Number of bits	Code	
280	3.5	-2	14	01001111100001		355	1.5	4.5	15	001010011001100	
281	7.5 4	0 -2	14	01001111100010 01001111100011		356	-1.5	5.5	15 15	001010011001101	
282 283	13	-2 0	14 14	01001111100011		357 358	-3 -5	3.5 -1.5	15	001010011001110 001010011001111	
284	13.5	-0.5	14	01001111100100	10	359	0	-12.5	15	00101001101111	
285	4.5	1	14	01001111100110		360	-6.5	-1.5	15	001010011010001	
286	0.5	-13.5	14	01001111100111		361	0	-7.5	15	001010011010010	
287 288	-14.5 -7.5	0.5 0	14 14	01001111101000 01001111101001		362 363	-3.5 -0.5	-2 -6.5	15 15	001010011010011 001010011010100	
289	14.5	0.5	14	01001111101001		364	4.5	-0.5 -2	15	00101001101010	
290	5	0.5	14	01001111101011	15	365	8.5	-0.5	15	001010011010110	
291	-1	5	14	01100001000100		366	-2	-3.5	15	001010011010111	
292 293	−3 −1.5	2.5 -4.5	14 14	01100001000101 01100001000110		367 368	1 -2	-6.5 4	15 15	001010011011000	
293 294	-1.5 2	-4.3 3	14	01100001000110		369	3.5	-3	15	001010011011001 001010011011010	
295	14.5	-0.5	14	01100001001000		370	1	-5.5	15	001010011011011	
296	0.5	4	14	01100001001001	20	371	-6.5	0.5	15	001010011011100	
297	2.5	-3	14	01100001001010	20	372	2.5	3.5	15	001010011011101	
298 299	15 -2	0 -3	14 14	01100001001011 01100001110110		373 374	3 -1.5	-4.5 4	15 15	001010011011110 001010011011111	
300	-3.5	2.5	14	01100001110110		375	-5.5	-1	15	001010011011111	
301	3	3	14	01100011011010		376	2	3.5	15	001010011100001	
302	-3.5	2	14	01100011011011	25	377	5	1	15	001010111011000	
303 304	3 -7.5	-4 -1.5	14 14	01100011101110 01100011101111	25	378 379	-4 8	1.5 0	15 15	010010000011011	
304	-7.5 -4.5	-1.3 -1	15	000010000001110		380	-8	0	15	010010000011100 010010000011101	
306	1	-6	15	0000100000001111		381	-2	-4	15	010010000011101	
307	0.5	-5	15	000010000110100		382	8.5	0.5	15	010010000011111	
308	-5.5	-1.5	15	000010000110101	20	383	-5	-1	15	010010000100000	
309 310	0.5 8.5	-4 0	15 15	000010000110110 000010000110111	30	384 385	1 -0.5	4 7.5	15 15	010010000100001 010010000100010	
311	-2.5	4.5	15	000010000110111		386	3	3.5	15	010010000100010	
312	0	-15	15	000011000000001		387	3.5	2.5	15	010010000100100	
313	-4.5	1	15	000011110101001		388	6	0	15	010010000100101	
314 315	-2.5 -5	-3.5 0.5	15 15	000011110101010 000011110101011		389 390	-10.5 1.5	0.5 -4	15 15	010010000100110 010010000100111	
316	-3 -4	-1.5	15	000011110101011	35	391	-1.5	-4 -4.5	15	010010000100111	
317	-5	-0.5	15	000011110101101		392	0.5	6.5	15	010010000101001	
318	3.5	3.5	15	000011110101110		393	0.5	7.5	15	010010011011100	
319 320	5.5 -2.5	1.5 2	15 15	000011110101111 000011110110000		394 395	-4.5 -2	-2.5 -4.5	15 15	010010011011101 010010100110110	
320	-2.5 2.5	-4	15	000011110110000		393 396	0.5	-4.3 5	15	010010100110110	
322	-13	Ö	15	000011110110010	40	397	7	Ö	15	010010110000000	
323	5	-1	15	000011110110011		398	-8.5	0	15	010010110000001	
324	7.5	0.5	15	000110010110000		399	-9.5	0.5	15	010010110000010	
325 326	-3 -1	-2.5 6	15 15	000110010110001 000110010110010		400 401	-4 4.5	2 2.5	15 15	010010110000011 010010110000100	
327	-0.5	14	15	000110010110011		402	-4	2.5	15	010010110000100	
328	4.5	-1	15	000110010110100	45	403	1	-7.5	15	010010110000110	
329	3.5	2	15	000110010110101		404	1	-7 -	15	010010110000111	
330 331	0.5 -5	-6.5 1	15 15	000110010110110 000110010110111		405 406	-1 -3	-5 4	15 15	010010110001000 010010110001001	
332	6.5	-0.5	15	000110010110111		407	-4	3	15	010010110001001	
333	2	-4	15	000110010111001		408	-9	0	15	010010110001011	
334	0	-8	15 15	000110010111010	50	409	14	-0.5	15	010010110001100	
335 336	6.5 -6.5	1.5 0	15 15	000110010111011 000111001011000		410 411	−5.5 −1.5	1.5 -4	15 15	010010110001101 010010110001110	
337	-5.5	3	15	001001001001000		412	3.5	-7.5	15	010010110001110	
338	-1	-5.5	15	001001000100101		413	-4.5	-3.5	15	010010110010000	
339	-13.5	0.5	15	001001000100110		414	1.5	-7.5	15	010010110010001	
340 341	-13.5 -7.5	-0.5 -0.5	15 15	001001000100111 001001000101000	55	415 416	2.5 15.5	-4.5 0.5	15 15	010010110010010 010010110010011	
341	-7.5 -1.5	-0.3 -5.5	15	001001000101000		417	6.5	1	15	010010110010011	
343	-5	1.5	15	001001000101010		418	0.5	9.5	15	010011110100011	
344	-0.5	-13.5	15	001001000101011		419	1	5	15	010011110100100	
345 346	-0.5	-7.5	15 15	001001000101100		420	7.5	-0.5	15 15	010011110100101	
346 347	5.5 2.5	-1.5 3	15 15	001001000101101 001001000101110	60	421 422	4.5 -5	2 2	15 15	010011110100110 010011110100111	
348	-2.5	3	15	001001000101110		423	-5 5	-1.5	15	010011110100111	
349	0	-7	15	001001000110000		424	1.5	-5.5	15	010011110101001	
350	0	13	15	001001000110001		425	1.5	-5 2.5	15	010011110101010	
351 352	0 0.5	-6.5 5.5	15 15	001001000110010 001001000110011		426 427	-4.5 0	2.5 6	15 15	010011110101011 010011110101100	
353	1	4.5	15	0010100110011	65	428	1.5	5.5	15	010011110101100	
354	5.5	-1	15	001010011000111		429	5.5	-3.5	15	0100111101011110	

TABLE 1-continued

TABLE 1-continued

					_					
X	Y Joint VLC	Motion Ve	ctor Table for Talk	ing Head Video		<u>X</u>	ing Head Video			
Index	Mv_x	Mv_y	Number of bits	Code	5	Index	Mv_x	Mv_y	Number of bits	Code
430	0	7.5	15	010011110101111	•	505	4	1.5	16	0000111101010000
431	-12.5	0.5	15	010011110110000		506	6	0.5	16	0000111101010001
432	-0.5	6.5	15	010011110110001		507	2	-4.5	16	0001110010110010
433 434	4.5	-2.5 -0.5	15 15	010011110110010	10	508 509	-0.5 3.5	8.5 4.5	16 16	0001110010110011 0010000011001000
434	-6 -0.5	-0.3 13	15	010011110110011 010011110110100	10	510	-6	-2	16	0010000011001000
436	-8	-0.5	15	010011110110101		511	-6	-1.5	16	0010000011001011
437	-9.5	0	15	010011110110110		512	6	1	16	0010000011001011
438	15.5	-0.5	15	010011110110111		513	-4.5	3	16	0010000011001100
439	-3.5 -1	3	15 15	010011110111000		514 515	0.5	-12.5	16	0010000011001101
440 441	-1 0	5.5 -6	15 15	010011110111001 011000011101110	15	515 516	$\frac{1}{1.5}$	14.5 -10.5	16 16	0010000011001110 0010000011001111
442	1.5	7.5	15	011000011101111		517	0.5	9	16	001000001100111
443	-1	6.5	15	011000110001000		518	0.5	-9.5	16	0010000011100001
444	-1	11	15	011000110001001		519	-2	4.5	16	0010000011100010
445	-0.5	-15.5	15	011000110001010		520	4.5	-6.5	16	0010000011100011
446 447	5 7.5	-3 1	15 15	011000110001011 011000110001100	20	521 522	-4.5 4.5	7.5 -3.5	16 16	0010000011100100 0010000011100101
448	3.5	3	15	011000110001100		523	4.5	-3.5	16	0010000011100101
449	3	-9	15	011000110001110		524	-1.5	-8.5	16	0010000011100111
450	4	-5	15	011000110001111		525	-3.5	5	16	0010000011101000
451	4	-4	15	011000110100000		526	-3	4.5	16	0010000011101001
452 453	9.5 11.5	0.5 1	15 15	011000110100001 011000110100010	25	527 528	8.5 -1.5	-1.5 6.5	16 16	0010000011101010
454	12.3	0	15	011000110100010		529	-1.5 -4	-2.5	16	0010000011101011 0010000011101100
455	-7	0	15	01100011010011		530	2.5	-7.5	16	0010000011101101
456	-5.5	2.5	15	011000110100101		531	8.5	1.5	16	0010000011101110
457	3.5	-5.5	15	011000110100110		532	9	0	16	0010000011101111
458 459	3.5 0.5	-4.5 8.5	15 15	011000110100111	30	533 534	9.5 9.5	-1.5 0	16 16	0010000011110000
460	-7.5	1.5	15	011000110101000 011000110101001	30	535	-3	-4	16	0010000011110001 0010000011110010
461	4.5	-4.5	15	0110001101010101		536	3.5	-9.5	16	0010000011110010
462	-4.5	-2	15	011000110101011		537	-3.5	-3	16	0010000011110100
463	-4	3.5	15	011000110101100		538	-3	-3	16	0010000011110101
464	5.5	3.5	15	011000110101101		539	-8.5	-0.5	16	0010000011110110
465 466	-3.5 -0.5	-4.5 11.5	15 15	011000110101110 011000110101111	35	540 541	3.5 -7	-4 0.5	16 16	0010000011110111 0010000011111000
467	-6	0.5	15	011000110101111		542	5	-2	16	0010000011111000
468	-6.5	-1	15	011000110110001		543	-7.5	-1	16	0010000011111010
469	6.5	-1	16	0000110001111100		544	-14	-0.5	16	0010000011111011
470	-15.5	15.5	16	0000110001111101		545	-0.5	-10.5	16	0010000011111100
471 472	1 -0.5	-8 5	16 16	0000110001111110 0000110001111111	40	546 547	0	6.5 7	16 16	0010000011111101 0010000011111110
473	-5.5	-2	16	000011000111111		548	14	0.5	16	0010000011111111
474	1.5	-9.5	16	0000111100110001		549	-15.5	0.5	16	0010010001000000
475	-8.5	0.5	16	0000111100110010		550	5	1.5	16	0010010001000001
476	7	0.5	16	0000111100110011		551	0	12.5	16	0010010001000010
477 478	7 1.5	1.5 -6.5	16 16	0000111100110100 0000111100110101	45	552 553	-16 -10	0 0	16 16	0010010001000011 0010010001000100
479	-0.5	-0.3 7	16	0000111100110101		554	-10 -6.5	1.5	16	0010010001000100
480	-2	5.5	16	0000111100110111		555	1.5	6.5	16	0010010001000101
481	-1.5	-7.5	16	0000111100111000		556	-5.5	1	16	0010010001000111
482	-1.5	-6.5	16	0000111100111001		557	4.5	-10.5	16	0010101110110010
483 484	-4.5 4.5	2	16 16	0000111100111010 0000111100111011	50	558 550	-7.5	2.5 5	16	0010101110110011 00101011111110100
485	-2.5	3.5 -4	16	0000111100111011	50	559 560	-3 -6	3.5	16 16	0010101111110100
486	-9	-0.5	16	0000111100111100		561	6.5	2.5	16	0010101111110101
487	10.5	0	16	0000111100111110		562	7	-0.5	16	0010101111110111
488	10.5	0.5	16	0000111100111111		563	0	8.5	16	0010111111101000
489	-2.5	-3	16	0000111101000000		564	2.5	-5.5	16	0010111111101001
490 491	-4 0	-2 15	16 16	0000111101000001 0000111101000010	55	565 566	-5 7.5	-2.5 -1.5	16 16	0010111111101010 00101111111101011
492	12.5	0.5	16	0000111101000010		567	-1.5	-1.3 7.5	16	0010111111101011
493	0	15.5	16	0000111101000100		568	-0.5	10.5	16	0010111111101101
494	-7.5	0.5	16	0000111101000101		569	-2.5	4	16	0010111111101110
495	5	3.5	16	0000111101000110		570	-1.5	9.5	16	0010111111101111
496 497	2.5	-6.5	16	0000111101000111	60	571 572	-1 5.5	-8	16	0010111111110000
497 498	-1.5 0.5	8.5 -7.5	16 16	0000111101001000 0000111101001001		572 573	-5.5 0.5	−3 −15.5	16 16	0010111111110001 0010111111110010
499	-15.5	-7.3 -0.5	16	0000111101001001		574	1.5	-13.3 4	16	0010111111110010
500	-3.5	5.5	16	0000111101001011		575	-7	-1	16	0010111111110100
501	0	-9.5	16	0000111101001100		576	-3.5	4.5	16	0010111111110101
502	0	-8.5	16	0000111101001101	65	577 570	0.5	6	16	0010111111110110
503 504	15.5 -3	-1.5 -3.5	16 16	0000111101001110 0000111101001111	U.S	578 579	9 9.5	1 -3.5	16 16	0010111111110111 00101111111111000
504	-3	-3.3	10	5500111101001111		517	7.3	-3.3	10	0010111111111000

TAR	$\mathbf{I} \mathbf{E}$	1-continued

TABLE 1-continued

		TI IDEI	£ 1-continued		_	TABLE 1-continued					
X	Y Joint VLC	Motion Ve	ctor Table for Talk	ing Head Video		<u>X</u>	Y Joint VLC	Motion Ve	ctor Table for Talk	ing Head Video	
Index	Mv_x	Mv_y	Number of bits	Code	5	Index	Mv_x	Mv_y	Number of bits	Code	
580	5	-2.5	16	0010111111111001		655	-0.5	8	16	0100111100001110	
581	-15	-0.5	16	00101111111111010		656	-6	1	16	0100111100001111	
582	-8.5	1.5	16	00101111111111011		657	0	10	16	0100111100010000	
583	9.5	1.5	16	00101111111111100		658	7.5	1.5	16	0100111100010001	
584	10.5	-0.5	16	00101111111111101	10	659	7.5	7.5	16	0100111100010010	
585	0.5	-8.5	16	0010111111111110		660	7.5	8.5	16	0100111100010011	
586	-3.5	8.5	16	0010111111111111		661	0	11	16	0100111100010100	
587	-1.5	-15.5	16	0100100000100000		662	8.5	-15	16	0100111100010101	
588	11.5	1.5	16	0100100000100001		663	8.5	-9.5	16	0100111100010110	
589	2.5	4	16	0100100000100010		664	8.5	-4.5	16	0100111100010111	
590 591	3 0.5	-13.5 13	16 16	0100100000100011 0100100000100100	15	665 666	-0.5 -15.5	10 -1.5	16 16	0100111100011000 0100111100011001	
592	3	-5.5	16	0100100000100100		667	-13.5 -2.5	6.5	16	0100111100011001	
593	13.5	-1.5	16	0100100000100101		668	-2	-5	16	0100111100011010	
594	3	-5	16	0100100000100111		669	3.5	8.5	16	0100111100011100	
595	0.5	13.5	16	0100100000101000		670	3.5	11	16	0100111100011101	
596	3.5	6.5	16	0100100000101001	• •	671	-5.5	-5.5	16	0100111100011110	
597	-9.5	-0.5	16	0100100000101010	20	672	2	4	16	0100111100011111	
598	0	-11.5	16	0100100000101011		673	-4.5	5	16	0100111100100000	
599	4	-3	16	0100100000101100		674	9.5	-0.5	16	0100111100100001	
600	14.5	-11.5	16	0100100000101101		675	-15	-1	16	0100111100100010	
601	14.5	-1.5	16	0100100000101110		676	4	-1.5	16	0100111100100011	
602	0	-10.5	16	0100100000101111	25	677	9.5	1	16	0100111100100100	
603	-11.5	0	16	0100100000110000	25	678	0	-16	16	0100111100100101	
604	6	-1	16	0100100000110001		679	10.5	-3.5	16	0100111100100110	
605	-14.5	-14.5	16	0100100000110010		680	-4	-4.5	16	0100111100100111	
606	-0.5	-9.5	16	0100100000110011		681	-1	9.5	16	0100111100101000	
607 608	-1.5 -3.5	-6 -7	16 16	0100100000110100 0100100000110101		682 683	-4 -1	-4 13.5	16 16	0100111100101001 0100111100101010	
609	-3.5 -0.5	-7 -6	16	0100100000110101	30	684	-1 -5.5	13.5 -2	16	0100111100101010	
610	-0.5 -2.5	-10.5	16	0100111010100000	30	685	-3.3 4	3	16	0100111100101011	
611	-4.5	-14.5	16	0100111010100001		686	12.5	-1.5	16	0100111100101100	
612	-11.5	-1.5	16	0100111010100010		687	12.5	-0.5	16	0100111100101110	
613	-3.5	4	16	0100111010100100		688	-0.5	-15	16	0100111100101111	
614	-11.5	-0.5	16	0100111010100101		689	4.5	-9.5	16	0100111100110000	
615	-1.5	10.5	16	0100111010100110	35	690	13	-0.5	16	0100111100110001	
616	-6	-1	16	0100111010100111	00	691	0	-12	16	0100111100110010	
617	-1	-7.5	16	0100111010101000		692	-10	-0.5	16	0100111100110011	
618	-1	-6	16	0100111010101001		693	-14	0.5	16	0100111100110100	
619	5	2.5	16	0100111010101010		694	0	-10	16	0100111100110101	
620	-7	-0.5	16	0100111010101011		695	1	6.5	16	0100111100110110	
621	-2	5	16	0100111010101100	40	696	13.5	4.5	16	0100111100110111	
622	-3.5	7.5	16	01001110101011101		697	-0.5	-12.5	16	0100111100111000	
623 624	-2 -2	7.5 11	16 16	01001110101011110		698 699	0 -9.5	-9 -1	16 16	0100111100111001	
625	-5.5	3	16	0100111010101111 0100111010110000		700	-9.5 -11.5	-1 -3.5	16	0100111100111010 0100111100111011	
626	-1.5	-11.5	16	0100111010110000		701	1.5	-3.3 -7	16	0100111100111011	
627	5.5	1	16	0100111010110001		701	-3	5.5	16	0100111100111100	
628	-1.5	-9.5	16	0100111010110011	45	702	1.5	-6	16	0100111100111101	
629	5.5	2.5	16	0100111010110100		703	2.5	5.5	16	0100111100111110	
630	-3	-5.5	16	0100111010110101		705				0.000.000.00000000000000000000000000000	
631	6	-3.5	16	0100111010110110		703 706	14.5 2.5	1.5 6	16 16	0100111101000000 0100111101000001	
632	6	-2.5	16	0100111010110111		707	2.5 15.5	-15.5	16	0100111101000001	
633	-5.5	5.5	16	0100111010111000		707	-3	-13.3 8.5	16	0100111101000010	
634	3	5	16	0100111010111001	50	709	ESC	ESC	7	0010001	
635	-5.5	6.5	16	0100111010111010		100	Loc	LSC	,	0010001	
636	-4	4	16	0100111010111011							
637	6.5	-3.5	16	01001110101111100							
638	6.5	-2.5	16	0100111010111101							
639 640	1.5 3.5	7 -5	16 16	0100111010111110 0100111010111111				T	ADLE 2		
641	-5	-3.5	16	0100111010111111	55			17	ABLE 2		
642	-3 1.5	-3.3 10.5	16	0100111100000000			VV Iolat V	T C Matian	Vector Table for G	eneral Video	
643	2	-6	16	0100111100000001			AI JOINT V	LC MOUON	vector radie for G	cherat video	
644	1	-15	16	0100111100000010		Index	Mv_x	Mv_y	Number of bits	Code	
645	1	- 9	16	0100111100000011		Index	**1 vY	.т. v <u></u> у	ramoer or oils		
646	6.5	3.5	16	0100111100000101		0	0	0	1	0	
647	1	-8.5	16	0100111100000110	60	1	-0.5	Ō	5	10011	
648	-1.5	-5	16	0100111100000111		2	0	-0.5	5	10101	
649	-0.5	6	16	0100111100001000		3	0.5	0	5	11001	
650	7	1	16	0100111100001001		4	-0.5	-0.5	5	11011	
651	-3.5	-5.5	16	0100111100001010		5	0	0.5	6	100100	
652	7	3	16	0100111100001011	25	6	0.5	-0.5	6	111000	
653	-8	0.5	16	0100111100001100	65	7	0.5	0.5	6	111001	
654	-7.5	-2.5	16	0100111100001101		8	-0.5	0.5	6	111101	

TABLE 2-continued

TABLE 2-continued

		40-02			-	The East of Continued						
-	XY Joint V	LC Motion	Vector Table for G	eneral Video		XY Joint VLC Motion Vector Table for General Video						
Index	Mv_x	Mv_y	Number of bits	Code	5	Index	Mv_x	Mv_y	Number of bits	Code		
9	1	0	7	1011101	•	84	-2	1	11	10100101100		
10	-1	0	7	1101000		85	0	-6.5	11	10100110000		
11	0	-1	7	1110110		86	0	-4	11	10100110110		
12	0	1	8	10010111	4.0	87	1.5	1.5	11	10100111101		
13 14	1 -1	-0.5 -0.5	8 8	10111101 11000111	10	88 89	1 -3.5	1.5 -0.5	11 11	10100111110 10100111111		
15	1.5	0.5	8	11010111		90	-3.5 -1.5	1.5	11	101100111111		
16	-1	0.5	8	11101010		91	-3.5	0.5	11	10110000110		
17	-0.5	-1	8	11101110		92	0.5	-3.5	11	10110000111		
18	0.5	-1	8	11110000		93	0.5	2	11	10110001101		
19 20	-1.5	0 0.5	8 8	11110001	15	94 95	-5.5	0 0	11	10110010111		
20	1 0	-1.5	9	11111010 100101010		93 96	5.5 -0.5	3.5	11 11	10110011001 10110100000		
22	0.5	1	9	100101100		97	-4	0	11	10110100001		
23	-0.5	1	9	101000000		98	-1	2	11	10110101011		
24	-1	-1	9	101001000		99	3	-0.5	11	10110110101		
25 26	0 1	1.5 -1	9 9	101100010	20	100 101	-3 -0.5	-0.5 -3	11 11	10110111000		
27	-0.5	-1 -1.5	9	101101001 101111100		101	-0.5 2	-3 1	11	10110111010 10110111011		
28	-1.5	-0.5	9	101111110		103	3.5	0.5	11	10110111100		
29	2	0	9	110000001		104	-9.5	0	11	10110111110		
30	1.5	-0.5	9	110000011		105	3	-1	11	10111000010		
31	-1	1	9 9	110001010	25	106	3	0.5	11	10111001000		
32 33	0.5 -2	-1.5 0	9	110001100 110001101	20	107 108	0.5 -14.5	3.5 0	11 11	10111001100 10111001101		
34	1	1	9	1101001101		109	9.5	0	11	10111001101		
35	0	-2	9	110101001		110	4	0	11	10111100110		
36	1.5	0.5	9	111100110		111	9	0	11	10111110101		
37	-1.5	0.5	9	111110000	20	112	-0.5	3	11	11000000010		
38 39	-0.5 0.5	1.5 1.5	9 10	111110110 1001010011	30	113 114	3.5 5	-0.5 0	11 11	11000001010 11000010000		
40	0.5	2	10	1010001011		115	6	0	11	11000010000		
41	-2.5	0	10	1010010011		116	4.5	Ö	11	11000010011		
42	0	-2.5	10	1010010111		117	0	-9.5	11	11000100010		
43	2.5	0	10	1010011100		118	-3	-1	11	11000100100		
44 45	0 0	-3.5 2.5	10 10	1011010100	35	119 120	-4.5 -6	0	11 11	11000100101 11000101110		
45 46	-2	-0.5	10	1011010111 1011100000		120	-0 -1	-3	11	1101010101110		
47	2	-0.5	10	1011100111		122	14.5	Ö	11	11010101001		
48	-1	-1.5	10	1011111111		123	-15.5	0	11	11010101011		
49	3	0	10	1100000000		124	0	-4.5	11	11010101100		
50 51	-1.5 -0.5	-1 -2	10 10	1100001010 1100001100	40	125 126	0 -5	6.5 0	11 11	110101011111		
52	0.3	3.5	10	1100001100		120	-3 0	-14.5	11	11101000010 11101000101		
53	0	-3	10	1100011110		128	1	2	11	11101000101		
54	1.5	-1	10	1100010011		129	8.5	0	11	11101001001		
55	-3	0	10	1101001011		130	-3.5	-1.5	11	11101001010		
56 57	-1 0	-2 3	10 10	1101010000	45	131 132	3 -11.5	1 0	11 11	11101001011		
58	0.5	-2	10	1101011100 1101011111		133	-11.5 0	5.5	11	11101001111 111011111100		
59	-2.5	-0.5	10	1110100110		134	-2	-1.5	11	11110010001		
60	-2	0.5	10	1110101100		135	0.5	-3	11	11110010011		
61	1	-1.5	10	1110101110		136	-2	-2	11	11110010100		
62 63	-2 2	-1 0.5	10 10	1110101111 1110111101	50	137 138	0 -15	-15.5 0	11 11	11110010101 11110010110		
64	-1.5	1	10	11101111111	30	139	-13	-6	11	11110010110		
65	-0.5	-2.5	10	1111100100		140	-8.5	0	11	11110011101		
66	2	-1	10	1111100110		141	-9	0	11	11110011110		
67	-3.5	0	10	1111101111		142	-3	0.5	11	11110011111		
68 69	-0.5 3.5	2 0	10 10	1111110010		143	15.5 0	0 4	11 11	11111000101 11111000111		
70	3.3 1	-2	10	1111110100 1111110111	55	144 145	11.5	0	11	11111000111		
71	1.5	1	10	11111110111		146	-3.5	1.5	11	11111031111		
72	-2.5	0.5	10	1111111110		147	0.5	3	11	11111100001		
73	-1.5	-1.5	11	10010100100		148	-7	0	11	11111100011		
74 75	-6.5	0	11	10010110101		149	2.5	-1	11	11111100111		
75 76	0.5 -0.5	-2.5 -3.5	11 11	10010110111 10100001000	60	150 151	-6.5 0	-0.5 -5.5	11 11	11111101010 11111101100		
70 77	1.5	-3.3 -1.5	11	10100001000		152	-2.5	-3.3 -1	11	1111111110000		
78	-0.5	2.5	11	10100001101		153	0	-5	11	11111110010		
79	2.5	-0.5	11	10100010001		154	-1	3	11	11111110100		
80	6.5	0	11	10100010111		155	-3	1	11	111111111010		
81	2.5	0.5	11	10100011001	65	156 157	0	6 1.5	12 12	100101000001		
82 83	0.5 -1	2.5 1.5	11 11	10100100101 10100101010	00	157 158	2.5 0	-1.5 -9	12 12	100101000110 100101001010		
33	1	1.0	11	10100101010		130	J	,	12	100101001010		

TABLE 2-continued

TABLE 2-continued

			commada								
	XY Joint V	LC Motion	Vector Table for G	eneral Video		XY Joint VLC Motion Vector Table for General Video					
Index	Mv_x	Mv_y	Number of bits	Code	5	Index	Mv_x	Mv_y	Number of bits	Code	
159	-0.5	-6.5	12	100101011001		234	15	0	12	101110001111	
160	2	-2	12	100101011010		235	-0.5	5.5	12	101110010010	
161	-1.5	-2	12	100101011111		236	-12	0	12	101110010011	
162	0	4.5	12	100101101000		237	1.5	2	12	101110010100	
163	-4	-0.5	12	100101101001	10	238	8	0	12	101110010111	
164 165	-3.5 -4	1 -1	12 12	100101101101 101000001010		239 240	-0.5 -11	-4.5 0	12 12	101111000010 101111000100	
166	0	5	12	101000001010		241	0	-16	12	101111000100	
167	-6.5	0.5	12	101000010010		242	4	0.5	12	101111000110	
168	1	-3	12	101000010101		243	-14.5	0.5	12	101111000111	
169	-1	-4	12	101000011100	15	244	-1	-3.5	12	101111001011	
170	-16	0	12	101000011110		245	-0.5	-5.5	12	101111001110	
171 172	-1 -3.5	-2.5 -1	12 12	101000011111 101000100101		246 247	0 7	-7.5 0	12 12	101111001111 101111101000	
173	1.5	-2	12	101000100101		248	5	-1	12	101111101000	
174	2	-1.5	12	101000101100		249	1.5	-2.5	12	101111101101	
175	3.5	-1.5	12	101000110110	20	250	14	0	12	101111101110	
176	-0.5	-4	12	101000110111	20	251	-3	-2	12	101111111000	
177	-4	1	12	101000111000		252	-11.5	-0.5	12	101111111001	
178 179	0 0	-11.5 9.5	12 12	101000111010 101000111100		253 254	0 0	-10 11.5	12 12	101111111011 110000000110	
180	3.5	1.5	12	101000111101		255	-7	-0.5	12	110000000110	
181	0	8.5	12	101001010000		256	-0.5	6.5	12	110000010011	
182	-9.5	-0.5	12	101001010011	25	257	-15.5	15.5	12	110000100100	
183	-4	0.5	12	101001011011		258	13.5	0	12	110000100101	
184	-10	0	12	101001100010		259	-15.5	-0.5	12	110000101101	
185 186	-2.5 -4.5	1.5 0.5	12 12	101001100100 101001101010		260 261	-0.5 5	4.5 -0.5	12 12	110000101110 110000101111	
187	6.5	-0.5	12	101001101010		262	-5	-0.5 -0.5	12	110000101111	
188	-5.5	0.5	12	1010011111000	30	263	0.5	5.5	12	110000110101	
189	4.5	0.5	12	101100000001		264	-14	0	12	110000110111	
190	0.5	-4	12	101100000100		265	0	-11	12	110000111100	
191	3	-1.5	12	101100000101		266	0.5	-5.5	12	110000111110	
192 193	-2.5 -2	-1.5 1.5	12 12	101100000110 101100001000		267 268	-5 -6	1 -0.5	12 12	110001000110 110001000111	
194	2.5	1.5	12	101100001000	35	269	8.5	-0.5 -0.5	12	110001000111	
195	6.5	0.5	12	101100011101	33	270	-1.5	2	12	110001011001	
196	-5.5	-0.5	12	101100011110		271	1	-3.5	12	110001011010	
197	-2.5	1	12	101100011111		272	-1.5	2.5	12	110001011111	
198	1	3	12	101100100001		273	15.5	-0.5	12	110100100010	
199 200	0 0.5	-8.5 -6.5	12 12	101100100010 101100100011		274 275	-0.5 14.5	-14.5 -0.5	12 12	110100100011 110100100101	
201	-7.5	0	12	101100100011	40	276	-15.5	-15.5	12	110100100101	
202	3	-2	12	101100100101		277	0.5	6.5	12	110100101011	
203	-10.5	0	12	101100101000		278	1	2.5	12	110100111000	
204	6	-0.5	12	101100101010		279	-13.5	0	12	110100111100	
205 206	5.5 3.5	-0.5 -1	12 12	101100101101 101100110100		280 281	-4 15.5	-1.5 -15.5	12 12	110100111101 110100111110	
207	-4.5	-0.5	12	101100110100	45	282	0	-13.3 -8	12	110100111111	
208	2	2	12	101100111001		283	4	1	12	110101000111	
209	0	-15	12	101100111010		284	0	15.5	12	110101010000	
210	1	-2.5	12	101100111100		285	3	1.5	12	110101010101	
211 212	0 2.5	-7 1.5	12 12	101100111101 101100111110		286 287	-5 -5	0.5 -1	12 12	110101011011 110101011100	
212	0	1.3 9	12	101100111110	50	288	-3 1.5	2.5	12	110101011100	
214	11	Ó	12	101101000101	50	289	-2	-3	12	11010111101	
215	-1	2.5	12	101101000110		290	-15.5	0.5	12	110101110110	
216	-14.5	-0.5	12	101101000111		291	-3	-1.5	12	110101110111	
217	4	-1	12	101101010101		292	0	-14	12	110101111000	
218 219	0.5 -9.5	-4.5 0.5	12 12	101101011001 101101011010		293 294	-8.5 -0.5	-0.5 4	12 12	110101111010 110101111011	
220	10.5	0.5	12	101101011010	55	295	9.5	0.5	12	1110101111011	
221	5.5	0.5	12	1011011100010		296	2.5	-2	12	1110100000111	
222	9.5	-0.5	12	101101100011		297	14.5	0.5	12	111010001000	
223	0	14.5	12	101101100101		298	-0.5	-6	12	111010001110	
224	4.5	-0.5	12	101101101000		299	0.5	4.5	12	111010001111	
225 226	3.5 7.5	1 0	12 12	101101101100 101101101110	60	300 301	-0.5 0	-15.5 -12	12 12	111010010000 111010010001	
227	-0.5	-9.5	12	101101101110		302	11.5	-12 -0.5	12	111010010001	
228	-8	0	12	1011011110011		303	10	0	12	111010111110	
229	2	1.5	12	101101111011		304	-4	-2	12	111010110111	
230	-1.5	-2.5	12	101110000110		305	-15	-0.5	12	1110111110010	
231 232	-2 4	2 -0.5	12 12	101110000111 101110001011	65	306 307	-0.5 -1.5	-11.5 -3.5	12 12	111011111010 111011111011	
232	4 1	-0.5 -4	12 12	101110001011	55	307	-1.5 1.5	-3.5 3.5	12 12	1111011111011	
200	1	7	12	101110001110		230	1.0	5.5	12	111100100001	

TABLE 2-continued

TABLE 2-continued

TABLE 2-continued						TABLE 2-continued					
XY Joint VLC Motion Vector Table for General Video						XY Joint VLC Motion Vector Table for General Video					
Index	Mv_x	Mv_y	Number of bits	Code	5	Index	Mv_x	Mv_y	Number of bits	Code	
309	0	8	12	111100100101		384	10.5	-0.5	13	1010011010000	
310	9	-0.5	12	111100111000		385	-2.5	2.5	13	1010011010001	
311	-0.5	6	12	111110001001		386	-4.5	1	13	1010011010010	
312	-0.5	8.5	12	111110010100		387	1	3.5	13	1010011010011	
313	-12.5	0	12	111110010101	10	388	3	-3	13	1010011010110	
314	2	-3	12	111110010111		389	5.5	-1	13	1010011011111	
315	8.5	0.5	12	111110011100		390	8	-0.5	13	1010011101000	
316	-8.5	0.5	12	111110011101		391	-10.5	-0.5	13	1010011101001	
317 318	1.5 0.5	-3.5 -9.5	12 12	111110111001 111111000000		392 393	3.5 4.5	2.5 -1.5	13 13	1010011101010 1010011101011	
319	-2	-9.3 3	12	111111000000	4.5	393	3.5	-1.3 -2	13	1010011101011	
320	0	10.5	12	111111000001	15	395	-16	-2 -1	13	1011000000000	
321	-1	3.5	12	111111000101		396	-7.5	-0.5	13	1011000000101	
322	0	7.5	12	111111001101		397	-10.5	0.5	13	1011000000110	
323	-3.5	-2	12	111111010110		398	-0.5	-7	13	1011000000111	
324	6	-1	12	111111010111		399	2	-4	13	1011000001110	
325	-0.5	9.5	12	111111011011	20	400	-6	-1	13	1011000001111	
326	-1.5	3.5	12	111111100111	20	401	-2.5	2	13	1011000010010	
327	0	13.5	12	111111101010		402	0.5	14.5	13	1011000010011	
328 329	-0.5 -2.5	14.5 -2.5	12 12	111111101011 111111110000		403 404	-16 -3	-0.5 2	13 13	1011000110000 1011000110001	
330	-2.3 1	-2.3 4	12	111111110000		405	-3 12	0	13	1011000110001	
331	0.5	-5	12	111111110001		406	-3.5	2.5	13	1011000111000	
332	-2.5	-2	12	111111110011	25	407	1.5	4.5	13	10110010100000	
333	-6	0.5	12	111111111100		408	2	-2.5	13	1011001000001	
334	0.5	4	12	111111111101		409	0.5	-11.5	13	1011001001100	
335	5	0.5	12	111111111110		410	15	-0.5	13	1011001001101	
336	15.5	0.5	12	111111111111		411	-3.5	-2.5	13	1011001001110	
337	15.5	15.5	13	1001010000000		412	-5.5	-1	13	1011001001111	
338	-3.5	-3.5	13	1001010000001	30	413	-1	5	13	1011001010010	
339 340	1 3	-5 2	13 13	1001010000100 1001010000111		414 415	0 0.5	-12.5 11.5	13 13	1011001010011 1011001010110	
341	-2	-2.5	13	1001010000111		416	2	2.5	13	1011001010110	
342	-1	4	13	1001010001000		417	-1	-6	13	1011001010111	
343	0	-10.5	13	1001010001010		418	1.5	3	13	1011001011001	
344	-3	1.5	13	1001010001011	35	419	-11	-0.5	13	1011001100000	
345	-11.5	0.5	13	1001010001111		420	13	0	13	1011001100001	
346	-0.5	-5	13	1001010010111		421	-5.5	1.5	13	1011001100010	
347 348	$-1 \\ 0.5$	-5 8.5	13 13	1001010110111 10010101111000		422 423	-6 -0.5	1 -15	13 13	1011001100011 1011001101010	
349	-10	-0.5	13	10010101111000		423 424	-0.5 -3.5	3.5	13	1011001101010	
350	-12	-0.5	13	10010101111011		425	-0.5	-16	13	10110011011110	
351	0.5	-14.5	13	1001010111100	40	426	4.5	1	13	1011001101111	
352	2.5	-2.5	13	1001010111101		427	-7.5	0.5	13	1011001110000	
353	-7	-1	13	1010000010000		428	-0.5	-9	13	1011001110001	
354	-4.5	1.5	13	1010000010011		429	-10	-1	13	1011001110110	
355	12.5	0	13	1010000010111		430	3	-4	13	1011001110111	
356 357	-0.5 0.5	5 -6	13 13	1010000011000 1010000011001	45	431 432	4 -1	-1.5 -7	13 13	1011010001000	
358	2.5	2.5	13	1010000011001	10	433	0.5	6	13	1011010001001 1011010101000	
359	3	3	13	1010000011111		434	-13	0	13	1011010101000	
360	0	11	13	1010000101000		435	11	-0.5	13	1011010110000	
361	0	-13.5	13	1010000101101		436	1	-6	13	1011010110001	
362	-3	-3	13	1010000101110		437	14	-0.5	13	1011011000000	
363	11.5	0.5	13	1010000101111	50	438	3.5	3.5	13	1011011000001	
364	-9	-0.5	13	1010000111010		439	-0.5	-7.5	13	1011011000010	
365	-4	1.5	13	1010000111011 1010001000011		440	-14.5	-14.5	13	1011011000011	
366 367	2 4	3 -2	13 13	1010001000011		441 442	-0.5 -7	9 0.5	13 13	1011011001000 1011011001001	
368	-2	-2 -4	13	1010001001000		443	3.5	-3.5	13	1011011001001	
369	0	14	13	1010001001001	55	444	-15.5	-1.5	13	1011011001100	
370	2.5	2	13	1010001100010	33	445	-1	-4.5	13	1011011001110	
371	-1.5	-3	13	1010001101000		446	-1.5	3	13	1011011001111	
372	0.5	9.5	13	1010001101001		447	-4	3	13	1011011010010	
373	-4.5	-1.5	13	1010001101011		448	-2	2.5	13	1011011010011	
374	4.5	-1	13	1010001110010		449	7.5	-0.5	13	1011011011010	
375 376	1.5	-3	13	1010001110111	60	450 451	3	-2.5	13	1011011011011	
376 377	-15 -0.5	-1 -8.5	13 13	1010001111100 1010010010010		451 452	-2.5 0.5	-3.5 5	13 13	1011011100100 1011011100101	
378	-0.5 -0.5	-0.3 11.5	13	1010010010010		453	7	-0.5	13	10110111100101	
379	0.5	-15.5	13	1010010010011		454	-15	0.5	13	1011011110100	
380	-4.5	-1	13	10100101011100		455	-14	-0.5	13	10110111111100	
381	6	0.5	13	1010010110101		456	7.5	0.5	13	1011011111101	
382	0	7	13	1010011000110	65	457	4.5	1.5	13	1011011111110	
383	5	1	13	1010011001101		458	-3	3	13	1011011111111	

TABLE 2-continued

TABLE 2-continued

						II III II VOIIIII V					
	XY Joint VLC Motion Vector Table for General Video					XY Joint VLC Motion Vector Table for General Video					
Index	Mv_x	Mv_y	Number of bits	Code	5	Index	Mv_x	Mv_y	Number of bits	Code	
459	-3	-2.5	13	1011100010000		534	-1.5	-5.5	13	1101010101001	
460	-1.5	-4.5	13	1011100010001		535	12.5	-15.5	13	11010101010100	
461	-5.5	1	13	1011100010010		536	5	-1.5	13	1101010110101	
462	-4	2	13	1011100010011		537	8	-1	13	1101011101010	
463	1	-4.5	13	1011100010100	10	538	-3.5	-3	13	1101011101011	
464	-14.5	14.5	13	1011100010101		539	-6.5	-1	13	1101011110010	
465 466	-2 -12	4 -1	13 13	1011100011000 1011100011001		540 541	2.5 -3	3 -3.5	13 13	11010111110011 1110100000000	
467	-0.5	15.5	13	1011100011001		542	-13.5	-0.5	13	1110100000000	
468	-4	-3	13	1011100011011		543	0.5	-10.5	13	11101000000010	
469	2.5	-3	13	1011100101010	15	544	-8	-1	13	1110100000011	
470	14.5	-14.5	13	1011100101011		545	-3	-4	13	1110100000110	
471	-8	-0.5	13	1011100101100		546	-6.5	3.5	13	1110100000111	
472 473	9 0	-1 10	13 13	1011100101101		547 548	-16	0.5 5.5	13 13	1110100001100	
474	1	5	13	1011110000000 1011110000001		549	-1 15.5	3.3 1.5	13	1110100001101 1110100010010	
475	1.5	-4	13	1011110000001		550	0.5	13.5	13	1110100010010	
476	-0.5	-10	13	1011110000011	20	551	3.5	3	13	1110100111010	
477	0	15	13	1011110000110		552	2	-3.5	13	1110100111011	
478	-1	-5.5	13	1011110000111		553	-2.5	-3	13	1110101101000	
479	5	-2	13	1011110010100		554 555	3	2.5	13	1110101101001	
480	1.5 -2	-4.5	13	10111110010101		555 556	-16	1	13	1110101101010	
481 482	3	-3.5 -3.5	13 13	1011111010010 1011111010011	25	556 557	15 4	-1 2	13 13	1110101101011 11101111100000	
483	-1.5	4.5	13	1011111010011		558	10	-1	13	1110111100000	
484	3.5	-2.5	13	1011111011111		559	-2.5	3.5	13	11101111100010	
485	-5	-1.5	13	1011111110100		560	-1	-10	13	11101111100011	
486	-1	4.5	13	1011111110101		561	0.5	15.5	13	11101111100110	
487	-1	6	13	1100000001110	20	562	- 9	0.5	13	1110111100111	
488 489	13.5 -5	-0.5 -2	13 13	1100000001111 1100000100000	30	563 564	11 -3.5	-1 -9.5	13 13	1111001000000 1111001000001	
490	-3 9	0.5	13	1100000100000		565	-0.5	-9.3 -11	13	1111001000001	
491	-11	-1	13	1100000100001		566	3	4	13	1111001001000	
492	1	4.5	13	1100000100011		567	7	0.5	13	1111001110010	
493	-0.5	10.5	13	1100000101100		568	-10	0.5	13	1111001110011	
494	-5.5	-1.5	13	1100000101101	35	569	-3	2.5	13	1111100010000	
495	14	-1	13	1100000101110		570	7	-1 15.5	13	1111100010001	
496 497	-9 -4	-1 -4	13 13	1100000101111 1100001011000		571 572	-6.5 -3.5	-15.5 3	13 13	1111100011000 1111100011001	
498	2.5	-3.5	13	1100001011000		573	-3.3 -2	-5	13	1111100011001	
499	0.5	10.5	13	1100001101000		574	-6	-1.5	13	1111100011011	
500	2.5	3.5	13	1100001101001	40	575	0	-13	13	1111100101100	
501	15.5	-1.5	13	1100001111010	40	576	1.5	-5.5	13	1111100101101	
502	5.5	-1.5	13	1100001111011		577 570	-0.5	14	13	1111101110000	
503 504	4 13.5	1.5 0.5	13 13	1100001111110 1100001111111		578 579	-6.5 -15.5	-3.5 -1	13 13	1111101110001 1111110011000	
505	5.5	1	13	1100001111111		580	-13.5 -12.5	-0.5	13	1111110011000	
506	-3.5	2	13	1100010110111		581	5	2	13	1111110110100	
507	3.5	2	13	1100010111100	45	582	1.5	5.5	13	1111110110101	
508	-1.5	-4	13	1100010111101		583	3	3.5	13	1111111000100	
509	10.5	0.5	13	1101001000000		584	4	3	13	1111111000101	
510 511	-1.5 1	4 -5.5	13 13	1101001000001 1101001000010		585 586	13 -5	-0.5 1.5	13	1111111000110 1111111000111	
512	-0.5	13.5	13	1101001000010		587	-3 -1	-6.5	13 13	1111111000111	
513	0.5	-8.5	13	1101001000011	50	588	0	13	13	1111111001100	
514	-0.5	11	13	1101001001001		589	12.5	-0.5	13	1111111101100	
515	8	0.5	13	1101001001100		590	15	-15.5	13	1111111101101	
516	-0.5	-12	13	1101001001101		591	-0.5	-8	13	1111111101110	
517	-0.5	8	13	1101001001110		592	-14.5	-5.5	13	11111111101111	
518 519	-8 -0.5	0.5 -10.5	13 13	1101001001111 1101001010000		593 594	14.5 -11.5	-5.5 11.5	14 14	10010100001010 10010100001011	
520	10	-0.5	13	1101001010000	55	595	1.5	4	14	10010100001011	
521	-15.5	1.5	13	1101001010001		596	12.5	15.5	14	10010100001100	
522	-13.5	0.5	13	1101001010011		597	3.5	-4	14	10010100011100	
523	-9.5	-3.5	13	1101001110010		598	0	12	14	10010100011101	
524	0	12.5	13	1101001110011		599	-4	-2.5	14	10010100101100	
525 526	-0.5	7.5	13	1101001110100	60	600	-11.5	-11.5	14	10010100101101	
526 527	14.5 0.5	14.5 -7.5	13 13	1101001110101 1101001110110		601 602	2 -1.5	-6 15.5	14 14	10010101100000 10010101100001	
528	0.5	-7.3 -7	13	1101001110110		603	-1.5 -16	-2	14	10010101100001	
529	-0.5	-13.5	13	1101010001100		604	4.5	-2.5	14	10010101100011	
530	-4	-3.5	13	1101010001101		605	-15.5	3.5	14	10010101101100	
531	-1.5	-15.5	13	1101010100010	65	606	-9.5	-1	14	10010101101101	
532	1	-7 15	13	1101010100011	65	607	-0.5	7	14	10010101110010	
533	-1	-15	13	1101010101000		608	-14.5	4.5	14	10010101110011	

TABLE 2-continued					_	TABLE 2-continued					
	XY Joint VLC Motion Vector Table for General Video					XY Joint VLC Motion Vector Table for General Video					
Index	Mv_x	Mv_y	Number of bits	Code	5	Index	Mv_x	Mv_y	Number of bits	Code	
609	5	-3	14	10010110110000		684	2	5	14	10100110010	
610	-3.5	-4.5	14	10010110110001		685	3.5	8.5	14	10100110011	
611	4	-4	14	10010110110010		686	-5	3	14	10100110011	
612 613	0.5 -15	−9 −15	14 14	10010110110011 10100000100010	10	687 688	-11.5 -9	-3.5 -3	14 14	10100110011 10100110011	
614	-13 1	5.5	14	10100000100010	10	689	-6	2	14	10100110011	
615	-14.5	-1	14	10100000100011		690	1.5	6.5	14	10100110011	
616	-15	-15.5	14	10100000100101		691	-14.5	-10.5	14	10100110101	
617	5.5	3.5	14	10100000101100		692	5.5	-3.5	14	10100110101	
618	-5.5	-14.5	14	10100000101101		693	-12.5	-15.5	14	10100110111	
619	-1.5	5.5	14	10100000111000	15	694	-4.5	-3.5	14	10100110111	
620	-11	0.5	14	10100000111001		695	-4.5	-2.5	14	10100110111	
621 622	0.5 -12.5	-13.5 0.5	14 14	10100000111010 10100000111011		696 697	-9.5 -14.5	3.5 15.5	14 14	10100110111 10100110111	
623	-0.5	-14	14	10100000111011		698	9.5	8.5	14	10100110111	
624	15	0.5	14	10100000111101		699	6.5	2.5	14	10100111011	
625	-6	-3	14	10100001001110	20	700	-1.5	-6.5	14	10100111011	
626	4.5	-2	14	10100001001111	20	701	-10	-3	14	10100111011	
627	-4	2.5	14	10100001010010		702	-11.5	3.5	14	10100111011	
628	-14.5	5.5	14	10100001010011		703	-2.5	3	14	10100111100	
629	14.5	4.5	14	10100001011000		704	-2	5	14	10100111100	
630 631	5.5 -15	1.5 -5	14 14	10100001011001 101000100000000		705 706	-5.5 9.5	-3.5 3.5	14 14	10100111100 10100111100	
632	0.5	-10	14	10100010000000	25	707	1.5	-15.5	14	10100111100	
633	-2	-6	14	1010001000001		708	6	1	14	10110000000	
634	-1	9	14	10100010000011		709	Esc	Esc	4	1000	
635	13.5	-15.5	14	10100010000100							
636	-9.5	-9.5	14	10100010000101							
637	-15.5	8.5	14	10100010011010							
638	-14 10	-1	14	10100010011011	30	Brief O	verview o	of a Comi	outer System		
639 640	10 2	0.5 -5	14 14	10100010110100 10100010110101					ring discussion	- oro inton	
641	15.5	-6.5	14	10100010110101							
642	2	4	14	10100010110111					scription of a s		
643	-1	-12	14	10100011000000					invention may		
644	0.5	7.5	14	10100011000001	35				aspects of it ma		
645	0.5	-16	14	10100011000010		in a ha	rdware de	evice, the	encoder and	decoder des	
646	-14.5	10.5	14	10100011000011		above a	re implen	nented in	computer-exec	utable instri	
647 648	6.5 -1.5	-3.5 5	14 14	10100011000110 10100011000111		organiz	ed in pr	ogram m	odules. The	program m	
649	1	6	14	10100011000111					rams, objects,		
650	-0.5	15	14	10100011010101					the tasks and i		
651	6.5	-1	14	10100011100110	40		escribed a		the tubile uner	impromoni t	
652	11.5	11.5	14	10100011100111							
653	-14.5	-15.5	14	10100011101100					ypical configur		
654	9.5	-9.5	14	10100011101101					ay be impleme		
655 656	-2 15.5	3.5 -14.5	14 14	10100011111010 10100011111011					ns, including h		
657	0.5	-15	14	10100011111011					icroprocessor-		
658	0.5	-8	14	10100011111101		mable	consumer	electron	ics, minicomp	outers, main	
659	14.5	-15.5	14	10100011111110					he invention m		
660	6	3	14	10100011111111					rironments wh		
661	-6	-2	14	10100100100000					ng devices that		
662	11	0.5	14	10100100100001	50				rk. In a distr		
663 664	-4.5 0.5	2.5	14 14	10100100100010	50						
665	-5.5	8 3.5	14	10100100100011 10100101000100					lules may be lo	cated III bot	
666	11.5	-11.5	14	10100101000100					ge devices.		
667	13.5	-14.5	14	10100101001000		FIG.	7 illustra	tes an exa	imple of a con	nputer syste	
668	6.5	-15.5	14	10100101001001		serves a	as an ope	rating env	vironment for	the inventio	
669	-14.5	9.5	14	10100101001010	55		-	_	a personal com		
670	6.5	3.5	14	10100101001011					, a system me		
671	15.5	-11.5	14	10100101011010					connects various		
672 673	-5 5	-4 1.5	14 14	10100101011011 101001010111100					memory to the		
674	3	-5	14	10100101011100			_	•	•	•	
675	-1	-15.5	14	101001010111101					comprise any		
676	-9.5	3	14	10100101011111	60	ous stru	ictures inc	ciuding a	memory bus o	r memory c	

2.5 2.5 -5 -4.5

cal configuration of a desktop be implemented in other comincluding hand-held devices, oprocessor-based or program-, minicomputers, mainframe invention may also be used in onments where tasks are perdevices that are linked through In a distributed computing es may be located in both local devices.

ple of a computer system that onment for the invention. The ersonal computer 720, includsystem memory 722, and a nects various system componemory to the processing unit mprise any of several types of 60 bus structures including a memory bus or memory controller, a peripheral bus, and a local bus using a bus architecture such as PCI, VESA, Microchannel (MCA), ISA and EISA, to name a few. The system memory includes read only memory (ROM) 724 and random access memory (RAM) 65 725. Abasic input/output system 726 (BIOS), containing the basic routines that help to transfer information between elements within the personal computer 720, such as during

er System g discussion are intended to iption of a suitable computing vention may be implemented. ects of it may be implemented ncoder and decoder described mputer-executable instructions

ules. The program modules ns, objects, components, and e tasks and implement the data

start-up, is stored in ROM 724. The personal computer 720 further includes a hard disk drive 727, a magnetic disk drive 728, e.g., to read from or write to a removable disk 729, and an optical disk drive 730, e.g., for reading a CD-ROM disk 731 or to read from or write to other optical media. The hard 5 disk drive 727, magnetic disk drive 728, and optical disk drive 730 are connected to the system bus 723 by a hard disk drive interface 732, a magnetic disk drive interface 733, and an optical drive interface 734, respectively. The drives and their associated computer-readable media provide nonvola- 10 tile storage of data, data structures, computer-executable instructions (program code such as dynamic link libraries, and executable files), etc. for the personal computer 720. Although the description of computer-readable media above refers to a hard disk, a removable magnetic disk and a CD, 15 it can also include other types of media that are readable by a computer, such as magnetic cassettes, flash memory cards, digital video disks, Bernoulli cartridges, and the like.

Anumber of program modules may be stored in the drives and RAM 725, including an operating system 735, one or 20 more application programs 736, other program modules 737, and program data 738. A user may enter commands and information into the personal computer 720 through a keyboard 740 and pointing device, such as a mouse 742. Other input devices (not shown) may include a microphone, joy- 25 stick, game pad, satellite dish, scanner, or the like. These and other input devices are often connected to the processing unit 721 through a serial port interface 746 that is coupled to the system bus, but may be connected by other interfaces, such as a parallel port, game port or a universal serial bus 30 (USB). A monitor 747 or other type of display device is also connected to the system bus 723 via an interface, such as a display controller or video adapter 748. In addition to the monitor, personal computers typically include other peripheral output devices (not shown), such as speakers and 35

The personal computer 720 may operate in a networked environment using logical connections to one or more remote computers, such as a remote computer 749. The remote computer 749 may be a server, a router, a peer device 40 or other common network node, and typically includes many or all of the elements described relative to the personal computer 720, although only a memory storage device 750 has been illustrated in FIG. 7. The logical connections depicted in FIG. 7 include a local area network (LAN) 751 45 and a wide area network (WAN) 752. Such networking environments are commonplace in offices, enterprise-wide computer networks, intranets and the Internet.

When used in a LAN networking environment, the personal computer 720 is connected to the local network 751 50 through a network interface or adapter 753. When used in a WAN networking environment, the personal computer 720 typically includes a modem 754 or other means for establishing communications over the wide area network 752, such as the Internet. The modem 754, which may be internal 55 corresponds to a macroblock in a video frame divided into or external, is connected to the system bus 723 via the serial port interface 746. In a networked environment, program modules depicted relative to the personal computer 720, or portions thereof, may be stored in the remote memory storage device. The network connections shown are merely 60 examples and other means of establishing a communications link between the computers may be used.

CONCLUSION

While the invention has been illustrated using a specific implementation as an example, the scope of the invention is 30

not limited to the specific implementation described above. Spatial prediction effectively exploits the spatial dependency of motion vectors and improves the efficiency of jointly coding motion vectors with a single entropy code. However, the specific form of prediction used on the motion vectors is not critical to the invention. In fact, it is possible to implement the invention without using a prediction scheme.

The implementation described above specifically uses a Huffman coding scheme to compute entropy codes for a joint motion vector parameter. As noted, it is also possible to use other forms of entropy coding to encode the joint parameter with a single entropy code.

In view of the many possible implementations of the invention, it should be recognized that the implementation described above is only examples of the invention and should not be taken as a limitation on the scope of the invention. Rather, the scope of the invention is defined by the following claims. We therefore claim as our invention all that comes within the scope and spirit of these claims.

1. In a video coder for coding video images in a block format, a method for improving compression of the video images comprising:

predicting x and y motion vector components for a current block of pixels based on a motion vector of at least one neighboring block of pixels to compute x and y components of a predictor motion vector;

computing differential x and y components from the x and y components of the predictor and x and y components of a motion vector for the current block; and

- assigning a single variable length code to joint x and y differential motion vector components, wherein the single variable length code is assigned from a variable length code table, the table comprising a list of pairs of joint differential motion vector components and a corresponding variable length code for each pair, such that shorter variable length codes are assigned to joint differential motion vector components that have a higher probability of occurrence in the video images, and longer variable length codes are assigned to joint differential motion vector components that have a lower probability of occurrence, wherein the table includes the most probable pairs of joint differential motion vector components as computed by statistical analysis of example video sequences.
- 2. The method of claim 1 wherein the assigning includes: looking up the joint differential motion vector components in the table;
- when no match is found in the table, coding an escape code along with a fixed length code for each differential motion vector component.
- 3. The method of claim 1 wherein the block of pixels fixed-sized, rectangular macroblocks, and the predicting, computing, and assigning are repeated for the macroblocks in the video frame.
- 4. The method of claim 1 wherein the block of pixels corresponds to a macroblock of a video object plane in a video frame having two more video object planes, and the video object planes are each divided into fixed-sized, rectangular macroblocks; and

the predicting, computing and assigning are repeated for the macroblocks in the video object planes.

5. A computer readable medium having instructions for performing the method of claim 1.

6. In a video decoder, a method for decoding macroblocks of a predicted video frame comprising:

receiving a single variable length code representing joint x and y components of a motion vector for each of the macroblocks;

for each of the macroblocks, searching for a single entry in an entropy codebook corresponding to the variable length code and including the x and y components of the motion vector, wherein training determines which x and y components to include in the entropy codebook; 10 and

using the x and y components of the motion vector from the codebook to define motion of pixels in a corresponding macroblock.

7. The method of claim 6 wherein the x and y components of the motion vector in the codebook comprise x and y differential motion vector components, and the method comprises:

reconstructing the motion vector from the differential motion vector components and x and y components of a predictor motion vector.

- 8. The method of claim 6 wherein the codebook is a Huffman table trained for a target bit rate and content type from a statistical analysis of example video sequences having the content type.
- 9. A computer readable medium having instructions for performing the method of claim 6.
 - 10. A motion vector encoder comprising:
 - a motion vector predictor for computing a motion vector ³⁰ predictor for a motion vector of a block of pixels from at least one motion vector for a neighboring block of pixels;
 - a subtractor for computing differential motion vector components from motion vector components of the ³⁵ predictor and the motion vector of the block of pixels; and
 - a joint entropy coder for jointly coding the differential motion vector components with a single variable length code, wherein statistical analysis indicates which differential motion vector components to represent with variable length codes and which differential motion vector components to represent with an escape code followed by fixed length codes.
- 11. The encoder of claim 10 wherein the joint entropy coder computes the single variable length code by searching for the code in a Huffman coding table comprising a list of joint differential motion vectors and a corresponding variable length code for each of the joint differential motion vectors.
 - 12. A motion vector decoder comprising:
 - a motion vector predictor for computing a motion vector predictor for a motion vector of a block of pixels from at least one motion vector for a neighboring block of 55 pixels;
 - a joint entropy decoder for decoding a single variable length code into joint differential motion vector components, wherein the joint entropy decoder decodes the single variable length code by searching for the code in 60 a Huffman coding table comprising a list of variable length codes and corresponding joint differential motion vector components for each of the variable length codes, wherein training determines which joint differential motion vector components to include in the 65 table and which joint differential motion vector components to exclude from the table; and

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an adder for reconstructing X and Y motion vector components from the joint differential motion vector components and X and Y components of the motion vector predictor.

13. The decoder of claim 12 wherein the joint entropy decoder is operable to detect an escape code indicating that two fixed length codes representing X and Y differential motion vector components follow the escape code.

14. In a video coder for coding video images in a block format, a method for improving compression of the video images comprising:

computing x and y motion vector components for a block; forming the x and y motion vector components into a joint parameter representing joint x and y motion vector components; and

assigning a single variable length code to the joint x and y motion vector components, the single variable length code selected from a set of available variable length codes, such that shorter variable length codes are assigned to joint motion vector components that have a higher probability of occurrence in the video images, and longer variable length codes are assigned to joint differential motion vector components that have a lower probability of occurrence, wherein training determines which joint x and y motion vector components to represent in the set of available variable length codes.

15. The method of claim 14 further including spatially predicting the x and y motion vector components from a neighboring block of the block; and using spatially predicted components as the joint x and y motion vector components.

16. The method of claim 15 wherein the spatially predicted components are differential motion vector components computed as a difference between x and y components of the motion vector for the block and x and y components of a predictor motion vector.

17. In a video decoder, a method for decoding macroblocks of a predicted video frame comprising:

receiving a single variable length code representing joint differential x and y components of a motion vector for each of the macroblocks;

for each of the macroblocks, searching for a single entry in a Huffman table corresponding to the variable length code and including the joint differential x and y components of the motion vector, wherein the Huffman table includes variable length codes for the most probable joint differential x and y components as computed by statistical analysis of example video sequences;

computing x and y components of a predictor motion vector from neighboring macroblocks to the macroblock currently being decoded; and

reconstructing the motion vector from the differential components obtained from the Huffman table and the x and y components of the predictor motion vector.

18. In a video coder for coding video images in a block format, a method for variable length coding block motion information of the video images, wherein a joint parameter represents x and y motion vector components for a block, the method comprising:

assigning a single variable length code selected from a set of available variable length codes to the joint x and y motion vector components, wherein training determines which joint x and y motion vector components to represent in the set of available variable length codes.

19. The method of claim 18 wherein the block is a 16×16 macroblock of pixels, and wherein each of the x and y motion vector components comprises a differential value.

20. A video decoder including computer-executable instructions for causing a computer programmed thereby to perform a method for variable length decoding macroblock motion information of a predicted video frame, wherein a single variable length code represents joint differential x and 5 y components of a motion vector for each of plural macroblocks, the method comprising:

for each of the plural macroblocks, searching for a single entry in a Huffman table corresponding to the variable length code for the macroblock, wherein the single 10 entry includes the joint differential x and y components 34

of the motion vector for the macroblock, wherein the joint differential x and y components are combinable with predictor x and y components to reconstruct the motion vector for the macroblock, and wherein the Huffman table includes variable length codes for the most probable joint differential x and y components as computed by statistical analysis of example video sequences.

* * * * *

UNITED STATES PATENT AND TRADEMARK OFFICE **CERTIFICATE OF CORRECTION**

PATENT NO. : 6,983,018 B1 Page 1 of 1

APPLICATION NO.: 09/201278
DATED: January 3, 2006
INVENTOR(S): Lin et al.

It is certified that error appears in the above-identified patent and that said Letters Patent is hereby corrected as shown below:

In column 2, line 37, delete "MN" and insert -- M_N --, therefor.

In column 2, line 42, delete "MN" and insert -- M_N --, therefor.

In column 2, line 45, delete "MN" and insert -- $\ensuremath{M_{\mathrm{N}}}$ --, therefor.

In column 5, line 24, after "stream" insert -- 30 --.

Signed and Sealed this

Twenty-fifth Day of August, 2009

Varid J. Kappas

David J. Kappos

Director of the United States Patent and Trademark Office