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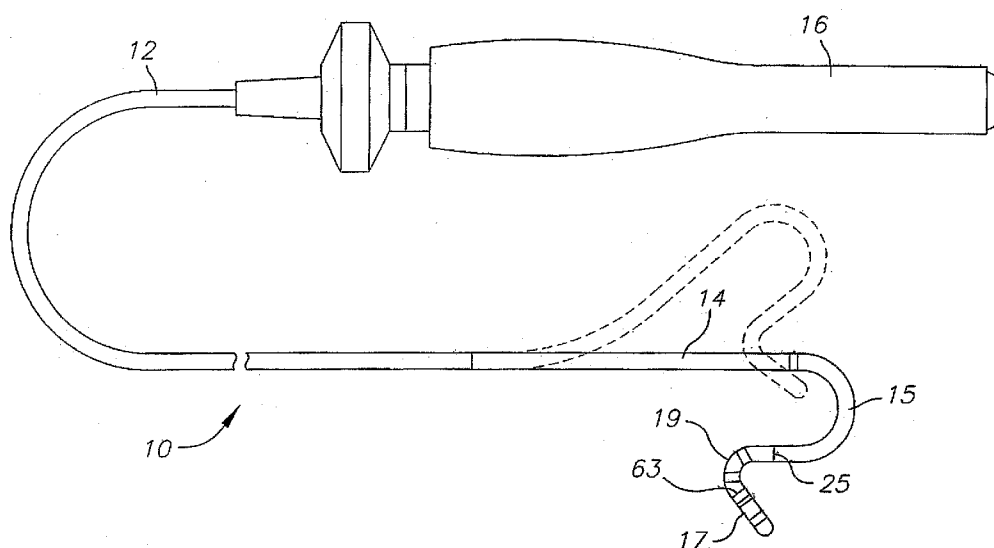
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(54) Title: CATHETER WITH FLEXIBLE PRE-SHAPED TIP SECTION



(57) Abstract: A catheter for mapping and/or ablating continuous linear or circumferential lesions at the intersection of a generally flat structure, such as the left atrium, and the ostium of generally cavernous regions of the heart, including pulmonary vein and the pulmonary venous antrum, comprises a catheter body with an intermediate section that is connected to a tip assembly by a highly flexible section. The intermediate section has at its distal end a preformed section, e.g., a curve, the intermediate section being deflectable in a direction opposite to the curve. The highly flexible section presets the tip assembly at an off-axis and/or off-plane angles from the preformed section.

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CATHETER WITH FLEXIBLE PRE-SHAPED TIP SECTION

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FIELD OF THE INVENTION

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The invention is directed to a catheter having a tip assembly for mapping and/or ablating regions of or near a heart, including an intersection between a generally flat region such as the body of the left atrium and a generally cavernous regions such as a pulmonary vein or the antrum of two or more pulmonary veins, the intersection being referred to as the ostium or opening of the generally cavernous region.

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BACKGROUND OF THE INVENTION

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Atrial fibrillation is a common sustained cardiac arrhythmia and a major cause of stroke. This condition is initiated by wavelets originating at or near the intersection of a generally cavernous region such as a pulmonary venous atrium or a pulmonary vein and a generally flat structure such as the left atrium. The condition is perpetuated by reentrant wavelets propagating in an abnormal atrial-tissue substrate. Various approaches have been developed to interrupt wavelets, including surgical or catheter-mediated atriotomy. A common procedure involves ablating a lesion to interrupt the wavelets using one or more electrodes mounted on the distal end of a generally-straight catheter. This procedure works well, for example, when ablating a line of block in the atria. In this case, the proximal portion and tip of the catheter are in contact with and supported/stabilized by the atria along the line of intended block. However, at the intersection of a generally

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cavernous or tubular region and a generally flat region in or around the heart, this procedure can be less effective.

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For example, when the line of block to be ablated is about the circumference of the cavernous or tubular region, the catheter is not stabilized or supported except at the tip where it contacts the heart making it is difficult to

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manipulate and control the distal end of a straight catheter for an effective ablation about the circumference.

Catheters have been developed for ablating about an inner circumference of the tubular region, for example the pulmonary vein. For example, catheters using ultrasound

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transducers surrounded by an inflatable balloon have been used. The balloon in such a catheter is positioned inside the pulmonary vein. Balloons have also been used for stable placement inside the pulmonary vein, while ablating outside the pulmonary vein. However, due to the shape and material of the balloon, the balloon often becomes dislodged, thereby adversely affecting the accuracy of the lesion created

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outside the ostium of the pulmonary vein or pulmonary venous antrum. Moreover, due to the shape of regions near the pulmonary vein and/or the antrum of pulmonary veins, where a generally flat structure joins a generally cavernous

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structure, it is difficult to maintain a catheter in stable position. When the tip of the catheter approaches the

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intersection of a generally cavernous structure from the region of the generally flat structure the catheter section proximal the tip is not in contact with or supported/stabilized by the flat structure. Without

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supportive contact between this proximal catheter section and the tissue, motion of the heart during systole, diastole and respiration is not transmitted to this catheter section

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except by contact between tissue and the catheter tip. As
the heart moves during systole, diastole and respiration,
5 the contact pressure at the tip of the catheter may vary
from excessive to nonexistent. In a catheter that
approaches the intersection of the ostium and the atrium in
a "forward" direction, the disparity between the generally
10 motionless (or out of synch) catheter and the heart makes it
difficult to maintain stable contact between the catheter
tip and the intersection of the flat and cavernous regions
in a beating moving heart. An unsupported and thus
15 unsynchronized catheter used in these regions may be
inadvertently advanced into the pulmonary vein or venous
antrum. Also, the nonuniform contours at the intersection
of the pulmonary vein or venous antrum and surrounding
tissue can make it difficult to contact recessed areas
20 without excess pressure on the protruding areas increasing
the risk of perforation. In addition, the catheter position
is maintained only by contact between the tip and the
nonuniform contours causing the catheter tip to frequently
25 lose contact with the tissue during ablation or mapping as
the heart moves independently during systole, diastole and
with respiration..

Accordingly, a need still exists for a catheter capable
of effectively mapping and ablating regions at or near the
30 intersection of the left atrium and the ostium of a
pulmonary vein or venous antrum, where the catheter is
better configured and adapted for use in such regions so as
to contact the nonuniform tissue surface without undue force
and maintain stability during ablation and mapping despite
35 the motion of beating heart in a breathing patient. A
catheter of such design improves precision of mapping and/or

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ablation and minimize risks of damage to the tissue,
including tissue perforation and inadvertent entry into the
5 pulmonary vein or pulmonary venous antrum causing stenosis
of the cavernous structure.

SUMMARY OF THE INVENTION

10 The present invention is directed to a catheter
configured for mapping and ablation at a junction of a
generally flat open region of the heart such as the left
atrium and a generally cavernous region of the heart, such
15 as a pulmonary vein or an antrum of several (more than one)
pulmonary veins, referred to as a pulmonary venous antrum.
In one embodiment, the catheter has an intermediate section
with a pre-shaped section at its distal end, and a tip
20 assembly adapted for mapping and/or ablation that is
attached distally to the pre-shaped section by a flexible
section that allows the tip assembly to be moved generally
independently of the intermediate section. In one
embodiment, the catheter comprises an elongated flexible
25 tubular catheter body having proximal and distal ends. The
deflectable intermediate section is mounted on the distal
end of the tubular body and comprises at its distal end the
pre-shaped curve whose curvature is generally opposite of
the direction of deflection and generally conforms to a
30 pulmonary vein or pulmonary venous antrum. The tip assembly
which can have a generally straight configuration is
attached to the end of the pre-shaped curve of the
intermediate section by the flexible section which is
35 configured with preset angles to extend the tip assembly
off-axis and/or off-plane relative to the pre-shaped curve
of the intermediate section. The intermediate section of

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the catheter is adapted to rest within the generally cavernous structure providing stability to the tip assembly. The flexible section improves the ability of the tip assembly to contact and remain in contact with surrounding tissues of variable contour without undue pressure. Moreover, the flexible tubing may be reinforced to provide the tip assembly with lateral stability. Accordingly, the catheter of the present invention has improved safety features and improved ablation and mapping capabilities.

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In one embodiment, the tip assembly is configured as an ablation assembly that may be irrigated, comprising a plurality of irrigation ports in between which an ablation coil electrode is wound. A porous covering, preferably made of expanded polytetrafluoroethylene, covers the coil electrode and irrigation ports. Fluid passes through the irrigation ports to the porous covering, which then disperses the fluid around the ablation assembly. This irrigation generally enables the creation of deeper lesions.

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In use, the distal end of the catheter is inserted into the heart of a patient. The pre-shaped section is deflected or otherwise positioned to sit in the generally cavernous region of the heart. The off-axis angle of the tip assembly readily allows the tip assembly to contact the surrounding tissue despite varied surface contour. As the user operates the catheter and maneuvers the tip assembly, the pre-shaped section advantageously maintains the tip assembly just outside the ostium of the cavernous region while the flexible section advantageously allows the tip assembly to flex from the preset off-axis angle as needed in order to remain in contact with the tissue. In one embodiment, as the tip assembly encounters protrusions and recesses outside

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the ostium of the pulmonary vein or pulmonary venous antrum, the tip assembly is jarred from its preset off axis angle but the flexible section allows the tip assembly to conform and ride along on the uneven surface without displacing the pre-shaped curve.

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By adjusting the preset angles of the flexible section, the off-axis and/or off-plane angles of the tip assembly relative to the pre shaped curve can be adapted to ablate and/or map most if not all regions around the ostium of the pulmonary vein, pulmonary venous antrum and other generally cavernous regions of the heart with uneven tissue surface. Accordingly, generally continuous linear and/or circumferential ablation and mapping can be accomplished by respectively dragging the catheter and/or rotating the catheter control handle despite uneven tissue surface.

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BRIEF DESCRIPTION OF THE DRAWINGS

These and other features and advantages of the present invention will be better understood by reference to the following detailed description when considered in conjunction with the accompanying drawings, wherein:

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FIG. 1 is an elevated side view of one embodiment of the catheter according to the invention;

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FIG. 1a is a schematic perspective view of the distal end of the intermediate section, the flexible section and the tip assembly of the catheter of **FIG. 1** positioned within a generally cavernous region of the heart, such as the pulmonary venous antrum;

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FIG. 2a is a side cross-sectional view of a catheter body according to the catheter of **FIG. 1**, including the junction between the catheter body and the intermediate

1 section;

5 **FIG. 2b** is a side cross sectional view taken of the side opposite that of **FIG. 2a** of the catheter body of **FIG. 2a**, including the junction between the catheter body and the intermediate section;

10 **FIG. 2c** is a side cross-sectional view of the intermediate section of the catheter of **FIGs. 2a** and **2b**, including the distal end of a puller wire and the proximal end of a shape memory support member;

15 **FIG. 3** is a side cross-sectional view of the intermediate section of the catheter of **FIG. 1**, including the junction between the intermediate section and the flexible section;

FIG. 3a is a longitudinal cross-sectional view of the intermediate section of **FIG. 3** taken along line 3a-3a;

20 **FIG. 3b** is a side cross-sectional view of the flexible section of the catheter of **FIG. 1**, including the junction between the flexible section and the tip assembly;

25 **FIG. 3c** is a longitudinal cross-section view of the flexible section of **FIG. 3** taken along line 3d-3d;

FIG. 4 is an enlarged side view of the distal end of the intermediate section, the flexible section and the tip assembly according to the embodiment of **FIG. 1**;

30 **FIG. 4b** is a bottom end view of the distal curve of the intermediate section, the flexible section and the tip assembly of **FIG. 4**, with the flexible section preset to support the tip assembly in-plane with the distal curve of the intermediate section;

35 **FIG. 4c** is a bottom end view of the distal curve of the intermediate section, the flexible section and the tip assembly of **FIG. 4b**, with the flexible section preset to

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support the tip assembly off-plane with the distal curve of
the intermediate section;

5 **FIG. 5a** is a close-up side view of an embodiment of an
irrigated ablation assembly;

FIG. 5b is a close-up longitudinal cross-sectional view
of the ablation assembly depicted in **FIG. 5a** taken along
10 line 5b-5b;

FIG. 6a is a schematic perspective view of **FIG. 1**, with
the distal end of the intermediate section positioned within
a pulmonary vein with the flexible section resting on the
ostium of the pulmonary vein and the tip assembly of the
15 catheter on the left atrium at the junction of the atria and
ostium of the pulmonary vein; and

FIG. 6b is a schematic perspective view of the distal
end of the intermediate section of **FIG. 1** in a deflected
20 position, positioned within a pulmonary vein. The flexible
section is at the ostium and the tip assembly is on the
generally flat atrium.

25 DETAILED DESCRIPTION OF THE INVENTION

Referring to **FIG. 1**, the present invention provides a
catheter **10** having a tip assembly **17** at its distal end. The
catheter comprises an elongated catheter body **12** having
proximal and distal ends, a deflectable intermediate section
30 **14** at the distal end of the catheter body **12**, and a control
handle **16** at the proximal end of the catheter body. In
accordance with a feature of the present invention, the tip
assembly **17** extends distally from a preformed section **15** at
35 the distal end of the intermediate section **14** and is
connected thereto by a flexible section **19**. In the
illustrated embodiment, the tip assembly **17** is adapted for

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ablation although it is understood by one of ordinary skill
in the art that the tip assembly may be adapted for mapping
5 applications, as well.

In the embodiment of **FIG. 1A**, the preformed section **15**
is a curve which enables the catheter distal end when
advanced and maneuvered in a generally cavernous region or
10 structure such as a PV ostium **31** or antrum **33** to sit in and
be cradled by the region with the tip assembly outside the
cavernous structure. Where the cavernous structure is a
pulmonary vein **35** or pulmonary venous antrum **33** the tip
assembly will rest generally outside the ostium at a
15 juncture of the pulmonary vein or venous antrum and the left
atrium. The curve **15** minimizes inadvertent entry of the tip
assembly into a pulmonary vein **35** or pulmonary venous antrum
33 especially where the curvature of the curve **15** is
20 generally opposite the deflection of the intermediate
section **14** (see **FIG. 1**). The curve **15** can therefore sit in
conformity with the generally concave configuration of the
ostium or antrum to urge the distal end of the catheter out
25 of and away from entering the pulmonary vein or pulmonary
venous antrum when a user advances the catheter in those
regions. Accordingly, a feature of the present invention
enables a user to approach the junction of the pulmonary
vein or pulmonary venous antrum and the left atrium from
30 more a "backward" direction or deflection. With the
intermediate section **14** cradled in the cavernous structure
the distal section of the catheter moves with the heart
during systole, diastole and respiration. The tip assembly
35 **17** is thus stable in a position at the junction of the left
atrium and the pulmonary antrum/vein. The more stable
backward approach with the intermediate section cradled in

1 the pulmonary vein or pulmonary venous antrum minimizes the risk of the tip assembly inadvertently entering the
5 pulmonary vein or pulmonary venous antrum causing damage to the veins or ineffective ablation.

Moreover, as another feature of the present invention, the flexible section **19** has a bending modulus greater than
10 that of the preformed section **15**, as discussed in detail further below. This greater flexibility enables the tip assembly **17** to flex and adjust to the contour of the tissue surface independently of the curve **15** of the intermediate
15 section **14**. As shown in **FIG. 1A**, the distal end of the catheter **10** is therefore better equipped to adjust to and withstand jarring of the tip assembly **17** as it comes into contact with protrusion **37** in the tissue surface when the tip assembly **17** is dragged along it. In addition, the
20 ablation to flex and adjust permits the tip assembly to contact tissue in recessed areas without exerting excess contact pressure in elevated areas reducing the risk of perforation. To that end, as also discussed in further
25 detail below, the flexible section **19** may be configured with an off axis angle and/or off-plane angle for use in the ostium of the pulmonary vein or ostium of the pulmonary venous antrum.

With reference to **FIGs. 2a** and **2b**, the catheter body **12**
30 comprises an elongated tubular construction having a single, axial or central lumen **18**. The catheter body **12** is flexible, i.e., bendable, but substantially non-compressible along its length. The catheter body **12** can be of any
35 suitable construction and made of any suitable material. A presently preferred construction comprises an outer wall **20** made of polyurethane or PEBAX. The outer wall **20** comprises

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an embedded braided mesh of stainless steel or the like to increase torsional stiffness of the catheter body **12** so that, when the control handle **16** is rotated, the intermediate section **14** of the catheter **10** is able to rotate in a corresponding manner.

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The outer diameter of the catheter body **12** is not critical, but is preferably no more than about 9 french, more preferably about 7 french. Likewise, the thickness of the outer wall **20** is not critical, but is thin enough so that the central lumen **18** can accommodate a puller wire, one or more lead wires, and any other desired wires, cables or tubes. If desired, the inner surface of the outer wall **20** is lined with a stiffening tube **21** to provide improved torsional stability. A particularly preferred catheter **10** has an outer wall **20** with an outer diameter of from about 0.090 inches to about 0.094 inches and an inner diameter of from about 0.061 inches to about 0.065 inches.

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The intermediate section **14** comprises a short section of tubing **22** having multiple lumens, as shown in **FIG. 3a**. In one embodiment, a first lumen **30** carries one or more lead wires **50** and any other components (e.g., thermocouple wires **53** and **54** for monitoring tissue temperature) extending along the catheter (**FIG. 2a, 2c and 3**). A second lumen **32** carries a puller wire **64** in the more proximal region (**FIGS. 2a and 2c**), and a support member **24** in the more distal region (**FIGS. 2c and 3**) which enables shape memory curvature of the pre-formed curve **15**. As also shown in **FIGS. 2b**, a third lumen **34** carries an electromagnetic sensor cable **74**, and a fourth lumen **35** carries an irrigation tube **61** for supplying fluid to the tip assembly **17**. The tubing **22** is made of a suitable non-toxic material that is preferably more flexible

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than the catheter body **12**. A presently preferred material for the tubing **22** is braided polyurethane, i.e., polyurethane with an embedded mesh of braided stainless steel or the like. The number of lumens or the size of each lumen is not critical, but is sufficient to house the lead wires, puller wire, electromagnetic sensor cable, thermal sensors and/or irrigation tube(s) depending on the embodiment.

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The useful length of the catheter **10**, i.e., that portion that can be inserted into the body excluding the tip assembly **17**, can vary as desired. Preferably the useful length ranges from about 110 cm to about 120 cm. The length of the intermediate section **14** is a relatively small portion of the useful length, and preferably ranges from about 3.5 cm to about 10 cm, more preferably from about 5 cm to about 6.5 cm.

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A preferred means for attaching the catheter body **12** to the intermediate section **14** is illustrated in **FIGs. 2a** and **2b**. The proximal end of the intermediate section **14** comprises an outer circumferential notch **26** that receives the inner surface of the outer wall **20** of the catheter body **12**. The intermediate section **14** and catheter body **12** are attached by glue or the like.

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If desired, a spacer (not shown) can be located within the catheter body between the distal end of the stiffening tube **21** and the proximal end of the intermediate section. The spacer provides a transition in flexibility at the junction of the catheter body and intermediate section, which allows the junction to bend smoothly without folding or kinking. A catheter having such a spacer is described in U.S. Patent No. 5,964,757, the entire disclosure of which is

1 incorporated herein by reference.

5 As shown in **FIG. 2a**, the puller wire **64** is provided for deflection of the intermediate section **14** (see **FIGS. 1** and **6b**). The puller wire **64** extends through the catheter body **12**, is anchored at its proximal end to the control handle **16**, and is anchored at its distal end to the intermediate
10 section **14**. The distal end of the puller wire **64** is anchored within the intermediate section **14** at about the location of the termination of the proximal end of the support member **24**. The puller wire **64** is made of any suitable metal, such as stainless steel or Nitinol, and is
15 preferably coated with Teflon® or the like. The coating imparts lubricity to the puller wire **64**. The puller wire **64** preferably has a diameter ranging from about 0.006 to about 0.010 inch.

20 A compression coil **66** is situated within the catheter body **12** in surrounding relation to the puller wire **64**, as shown in **FIG. 2a**. The compression coil **66** extends from the proximal end of the catheter body **12** to the proximal end of the intermediate section **14**. The compression coil **66** is
25 made of any suitable metal, preferably stainless steel. The compression coil **66** is tightly wound on itself to provide flexibility, i.e., bending, but to resist compression. The inner diameter of the compression coil **66** is preferably
30 slightly larger than the diameter of the puller wire **64**. The Teflon® coating on the puller wire **64** allows it to slide freely within the compression coil **66**. The outer surface of the compression coil **66** is covered by a flexible, non-
35 conductive sheath **68**, e.g., made of polyimide tubing.

The compression coil **66** is anchored to the outer wall of the catheter body **12** by proximal glue joint **70** and at its

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distal end to the intermediate section **14** by distal glue
joint **71**. Both glue joints **70** and **71** preferably comprise
5 polyurethane glue or the like. The glue may be applied by
means of a syringe or the like through a hole made between
the outer surface of the catheter body **12** and the central
lumen **18**. Such a hole may be formed, for example, by a
10 needle or the like that punctures the outer wall **20** of the
catheter body **12** which is heated sufficiently to form a
permanent hole. The glue is then introduced through the
hole to the outer surface of the compression coil **66** and
wicks around the outer circumference to form a glue joint
15 about the entire circumference of the compression coil.

Longitudinal movement of the puller wire **64** relative to
the catheter body **12**, which results in deflection of the
intermediate section **14** (**FIG. 1**), is accomplished by
20 suitable manipulation of the control handle **16**. Examples of
suitable control handles for use in the present invention
are disclosed in U.S. Patent Nos. Re 34,502 and 5,897,529,
the entire disclosures of which are incorporated herein by
reference. Deflection of the intermediate section **14** by
25 longitudinal movement of the puller wire **64** generally
results in deflection of the preformed shaped curve **15** of
the intermediate section **14**, as well as the entire tip
assembly **17**, without distortion of the curve **15**. Deflection
30 of the intermediate section **14** in this manner enables better
maneuverability of the curve **15** within the heart. In the
illustrated embodiment, the puller wire is configured to
deflect the intermediate section **14** in a direction away from
35 the curvature of the curve **15**. As understood by one of
ordinary skill in the art, the puller wire may be configured
as appropriate to enable deflection of the intermediate

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section 14 in other directions.

5 The distal portion of the intermediate section 14,
containing the support member 24, terminates in the
preformed curve 15, better shown in **FIGS. 4 and 4A**. The
support member 24 (shown in broken lines) is made of a
material having shape-memory, i.e., that can be straightened
10 or bent out of its original shape upon exertion of a force
and is capable of substantially returning to its original
shape upon removal of the force. A particularly preferred
material for the support member 24 is a nickel/titanium
alloy wire or ribbon. Such alloys typically comprise about
15 55% nickel and 45% titanium, but may comprise from about 54%
to about 57% nickel with the balance being titanium. A
preferred nickel/titanium alloy is Nitinol, which has
excellent shape memory, together with ductility, strength,
20 corrosion resistance, electrical resistivity and temperature
stability. As such, the support member 24 enables the
catheter to be advanced atraumatically in the patient's body
in a generally straight configuration through a vein or
artery and yet be able to assume its preformed shape when it
25 reaches the heart. The support member 24 extends proximally
from a junction 25 of the intermediate section 14 and the
flexible section 19, through the third lumen 34 (**FIG. 2c**) of
the intermediate section 14 and terminates at about a third
30 of the length of the intermediate section 14, so as not to
adversely affect the ability of the intermediate section 14
to deflect. The distal and proximal ends of the support
member 24 are anchored to the lumen 32 by any suitable
35 means, for example, adhesives forming glue joints 26 (**FIG.**
2c) and 27 (**FIG. 3**).

The preformed curve 15 is prepared by placing the

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support member **24** in a delrin mold and heating the support
member in the mold at about 550°C for about 15 minutes. The
5 tubing **22** of the intermediate section **14** is also preformed
to include the curve **15** by placing the tubing **22** in a
delrin mold and heating the mold at about 100°C for about 30
minutes. The length of the curve **15** of the intermediate
10 section **14** can vary as desired, but is preferably no longer
than about 33 mm, preferably about 10 mm.

The curvature of the preshaped section **15** enables it to
fit and sit within a generally cavernous structure such as a
15 pulmonary vein (**FIGS. 6a and 6b**) or a pulmonary venous
antrum (**FIG. 1A**) for pulmonary vein isolation. In the
illustrated embodiments, the pre-shaped curve **15** is
generally circular to conform to the overall shape and
cavity of the pulmonary vein and pulmonary venous antrum.
20 However, recognizing that pulmonary veins and pulmonary
venous antrums can come in different shapes and sizes, the
curve **15** may have a general diameter ranging between about
0.5 cm and 6.0 cm, more preferably between about 1.0 cm and
3.0 cm, and a curvature ranging between about 110 degrees
25 and 270 degrees (a more closed or "hook" shape as shown in
FIG. 4A). The preferred shape is a generally U shape as
shown in **FIG. 4** with a curvature of about 180 degrees. It
is understood that the curve **15** may assume a variety of
30 sizes and shapes as desirable or appropriate for the
intended region of ablation or mapping. By conforming
to the shape of the region, the curve **15** sits securely in
the region and transmits the motion of the heart during
35 systole, diastole and respiration to the entire catheter.
The tip of the catheter is thus both stable and moves in
synchrony with the heart. This allows the distal end of the

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catheter to be maneuvered with minimal risk of the tip assembly inadvertently entering a tubular region in communication with the region. In the illustrated embodiment, the curve **15** tends to guide the distal end of the catheter out of the vein or venous antrum when the catheter body is advanced at or near the treatment site. As shown in **FIGS. 1A, 6 and 6a**, as the catheter is advanced in the vein or venous antrum, the curve **15** being in conformity with the shape of the vein or venous antrum predisposes the distal end of the catheter to turn back or curl on itself (along direction **37**) and out of the vein **35** or venous antrum **33**, as opposed to advancing in an opposite direction from the curvature of the curve **15** (along direction **39**) which may lead the tip assembly **17** downwardly into a pulmonary vein **35** or pulmonary venous antrum **33**.

In accordance with another feature of the present invention, the tip assembly **17** is attached to the distal end of the curve **15** of the intermediate section **14** by the flexible section **19**. As shown in **FIGS 4 and 4A**, the flexible section **19** supports the tip assembly **17** at a preset off-axis from the distal end of the curve **15**. Using an angle θ to define the off-axis angle, the angle θ may range between about 10 degrees to about 180 degrees, preferably between about 70 degrees to 150 degrees, and more preferably about 120 degrees. In the embodiment of **FIG. 4**, the angle θ is about 120 degrees and in the embodiment of **FIG. 4A**, the angle θ is about 160 degrees. The angle θ generally allows the tip assembly to contact the surrounding tissue. The flexible section allows the angle θ to be varied from the initially set off axis angle to zero degrees with minimal force applied to the tip assembly through contact with the

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tissue.

5 To enable the tip assembly **17** to remain in or return to contact with the tissue outside the ostium of the pulmonary vein or the pulmonary venous antrum while the distal end of the catheter is advanced, withdrawn or otherwise maneuvered in the ostium or antrum, the flexible section **19** is
10 constructed with shape memory and/or sufficient flexibility and elasticity so that the tip assembly **17** can temporarily assume a different (greater or lesser) angle θ as needed for the tip assembly to pivot at its proximal end. The flexible section **19** can be sufficiently soft to allow the tip
15 assembly **17** to be displaced from its preset off-axis angle θ to an on-axis angle where θ is about zero, and sufficiently elastic to return (or at least bias the return of) the tip assembly **17** to its preset off-axis angle θ thereafter,
20 whether the displacement was caused by a formation **37** in the surrounding tissue, the tip assembly being caught or buried in the surrounding tissue, or a "steam pop" where a build up of pressure dislodges the tip assembly from contact with the surrounding tissue. To that end, the flexible section **19**
25 has a relatively high flexural modulus measuring on a Durometer scale no greater than about 25 D to 35D and/or no greater than about 1/2 to 1/4 of the Durometer measurement of the curve **15**. As shown in **FIG. 1A**, the flexible section
30 **19** acts as a "shock absorber" when the tip assembly is jarred or otherwise displaced from its preset position. The flexible section **19** enables the tip assembly **17** to pivot to away from the protrusion **37** independently of the
35 intermediate section **14** so that the tip assembly can remain in contact with the tissue. As the catheter **10** is advanced, withdrawn or otherwise maneuvered around the treatment site,

1 the tip assembly **17** moves between a resting position **A**
(solid lines) and a displaced position **B** (broken lines)
5 without significantly displacing the curve **15** of the
intermediate section **14** or changing its curvature. In one
embodiment, the tip assembly **17** can be displaced from its
preset off-axis angle (position **A**) under a force or weight
10 of merely about 0.25 to about 2.0 oz, and more preferably
about 1.0 ounce. As such, the flexible section **19** provides
sufficient flexibility to reduce the risk of injury that can
result from the tip assembly **17** inadvertently perforating
15 tissue or being buried in the tissue and overheating. As
understood by one of ordinary skill in the art, the force
required to displace or capable of displacing the tip
assembly from the preset off axis angle depends on the point
of application of the force to the tip assembly, as well as
20 the length of the tip assembly.

Referring to **FIGS. 4b** and **4c**, the highly flexible
section **19** may also be configured to support the tip
assembly **17** off-plane from the curve **15** at a variety of
25 radial angles. Using angle γ to define the radial angle
from a plane defined by the curve **15**, the angle γ may range
between about 0 to 360 degrees, preferably about 20 to 90
degrees, and more preferably about 40 degrees. As
understood by one of ordinary skill in the art, the angle γ
30 can be preset to any degrees depending on the location and
surrounding structures of the tissue to be ablated or
mapped. In the embodiment of **FIG. 4b**, the angle γ is about
zero degrees in that the tip assembly **17** lies in the plane
of the curve **15** with the flexible section **19** extending the
35 tip assembly in a direction or curvature generally opposite
to the curvature of the curve **15**. In the embodiment of **FIG.**

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4C, the angle γ is about 40 degrees. Moreover, to provide lateral stability in the tip assembly 17, struts or ribbons 51 may be provided in walls of the tubing 45, as shown in FIG. 3c, or elsewhere on or in the tubing as desirable. A pair of struts 51 can be aligned along a diameter that is generally perpendicular to a plane defined by the angle γ for maximum lateral stability while minimizing interference with movement of the tip assembly between the off-and on-axis positions.

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The flexible section 19 comprises a short section of tubing 45 with a central lumen 47 through which the lead wires 50, thermocouple wires 53 and 54, sensor cable 74 and irrigation tube 61 extend distally and connect to the tip assembly 17. A junction 25 of the intermediate section 14 and the flexible section 19 is shown in FIG. 3. The proximal end of the tubing 45 of the tip assembly 17 comprises an outer circumferential notch 49 that receives the inner surface of the tubing 22 of the intermediate section 14. The intermediate section 14 and the flexible section 19 are attached by glue or the like. The tubing 45 of the flexible section can be made of polyurethane, PEBAX, silicone or combinations thereof and is preformed (used generally interchangeably with "preshaped" herein) with shape memory by placing the tubing 45 in a delrin mold and heating the mold at about 100°C for about 30 minutes. The length of the flexible section 19 can vary as desired and can range between about 0.1 cm and 2.0 cm, preferably between about 0.2 cm and 1.0 cm, and more preferably about 5.0 cm.

In illustrated embodiment, the tip assembly 17 comprises a short section of tubing 61 (FIGs. 3b, 5a and 5b)

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comprising four lumens 30a, 32a, 34a and 35a, generally
corresponding to and aligned with the four lumens 30, 32, 34
5 and 35 respectively, of the intermediate section 14. The
length of the tip assembly 17 can vary as desired, but
preferably ranges between about 8 mm to about 15 mm, and
more preferably is about 10 mm. A junction 63 of the
10 flexible section 19 and the tip assembly 17 is shown in FIG.
3B. The proximal end of the tubing 61 of the tip assembly
17 comprises an outer circumferential notch 65 that receives
the inner surface of the tubing 45 of the flexible section
19. The flexible section 19 and tip assembly 17 are
15 attached by glue or the like.

FIG. 5a illustrates an embodiment of the tip assembly
17 configured as an ablation assembly. A coil electrode 82
is coiled around the length of the ablation assembly 17.
20 The longitudinal span of the coil electrode 82 may be made
of any suitable metal, preferably platinum/iridium and
ranges in length from about 6 to about 10 mm, preferably
about 8 mm to generally match the length of the ablation
assembly 17.
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In the disclosed embodiment, the ablation assembly 17
is irrigated and comprises a plurality of irrigation ports
80 disposed along most of the length of the ablation
assembly 17 through which fluid can pass to the outer
30 surface of the ablation assembly to cool the ablation site.
In the illustrated embodiment, the coil and the irrigation
ports 80 are arranged so that an irrigation port lies
between each wind of the coil electrode 82. The irrigation
35 ports may comprise round holes formed on the surface of the
tubing 61 on the side of the ablation assembly 17 in
communication with the fourth lumen 35a which is supplied

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fluid by the irrigation tube 61 whose distal end is slightly
proximal of the most proximal irrigation port. Any number
5 of irrigation ports 80 may be used. In the illustrated
embodiment, the tubing 61 of the ablation assembly 17 is
configured with about 10 irrigation ports 80. The
circumference of each round hole can measure about 20/1000
10 inch. As shown in FIGS. 5a and 5b, a porous protective
covering 84, of, for example, expanded
polytetrafluoroethylene (EPTFE), is disposed over the tubing
61 in surrounding relation to and covering the coil electrode
82 and irrigation ports 80

15 A tip electrode lead wire 50 (FIG. 5b) connects the
coil electrode 82 to a suitable source of ablation energy
(not shown), preferably radio frequency (RF) energy. The
distal end of the lead wire 50 is attached to the proximal
20 end of the coil electrode 82. The proximal end of the lead
wire 50 is electrically connected to the source of ablation
energy as is known in the art. The lead wire 50 extends
through the first lumen 30a of the ablation assembly 17, the
25 central lumen 47 of the flexible section 19, the first lumen
30 of the intermediate section 14, the central lumen 18 of
the catheter body 12, and the control handle 16, and
terminates at its proximal end in a connector (not shown).

30 As shown in FIG. 5a, if desired, mapping and/or
ablation ring electrodes 83a and 83b may be mounted on the
ablation assembly 17. The ring electrodes 83a and 83b can
be mounted over the coil electrode 82 and underneath the
porous covering 84. In the illustrated embodiment, the
35 first ring electrode 83a is positioned in between the two
distal most irrigation ports 80. The second ring electrode
83b is positioned in between the two proximal most

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irrigation ports **80**. The ring electrodes **83a** and **83b** are
mounted to the coil electrode **82** by any suitable means, for
5 example by welding, soldering or the like. As such, the
ring electrodes **83a** and **83b** are electrically connected to
the coil electrode **82** and its associated lead wire for
ablation purposes. The ring electrodes **83a** and **83b** serve in
10 part to hold the coil electrode **82** in place on the tubing **61**
of the ablation assembly. The ring electrodes **83a** and **83b**
also serve to flatten the coil electrode **82** on the surface
of the tubing **61**, thereby preventing any rough edges of the
coil electrode **82** from cutting into the porous covering **84**.

15 Any conventional temperature sensors, e.g.
thermocouples or thermistors, may be used. In the
embodiment shown in **FIGS. 2a, 3** and **5a**, the temperature
sensors comprise two thermocouples formed by two enameled
20 wire pairs. One wire of each wire pair is a copper wire **53**,
e.g., a number "40" copper wire. The other wire of each
wire pair is a constantan wire **54**. The wires **53** and **54** of
each wire pair are electrically isolated from each other
25 except at their distal ends where they are twisted together,
covered with a short piece of plastic tubing **55 (FIG. 5a)**,
e.g., polyimide, and covered with epoxy. The wires **53** and
54 of each wire pair extend out a hole in the side wall of
the tubing **61** and are anchored to the outer surface of tubing
30 **61**. The hole in the side wall of the distal region is
sealed by a plug. Any suitable seal may be used, for
example glue or the like. Each plastic tubing **55** is mounted
on the outer surface of the tubing **61** by polyurethane glue
35 or the like. One of the two thermocouples is anchored
immediately distal the distal most irrigation port **80**, as
shown in **FIG. 5a**. The second of the two thermocouples is

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anchored immediately proximal the proximal most irrigation port **80**. The wires **53** and **54** extend through the first lumen **30** in the ablation assembly **17** and intermediate section **14**, through the central lumen **18** of the catheter body **12** and out through the control handle **16** to a connector (not shown) connectable to a temperature monitor (not shown).

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If desired, one or more mapping and/or ablation ring electrodes can be mounted on the tubing **45** of the flexible section **19** and tubing **61** of the ablation assembly **17**, as shown in **FIGs. 4** and **5a**. These ring electrodes might be desirable, for example, for mapping the region to be ablated before ablation begins or after ablation to assure that the lesions blocked the electrical activity as desired. A ring electrode **85a** can be mounted on the proximal end of the tubing **61** of the ablation assembly **17** over the porous covering **84** so that the proximal end of the porous covering **84** can be tucked underneath the ring electrode **85a** to lock the proximal position of the porous covering **84**. Also, a second ring electrode **85b** can be mounted on the distal end of the tubing **61** so that the distal end of the porous covering **84** can be tucked underneath the ring electrode **85b** to lock the distal position of the porous covering **84**.

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In other embodiment, the tip assembly **17** whether adapted for mapping or ablation may be constructed with or without irrigation, with or without temperature sensors, using suitable ring electrodes for sensing and/or ablation, as understood by one of ordinary skill in the art. The relationship between the tip assembly and the flexible section remains generally as described herein.

In addition, as better shown in **FIGs. 4** and **4A**, two additional ring electrodes **86a** and **86b** for mapping are

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mounted on the flexible section **19**. The first ring
electrode **86a** is positioned approximately 5 mm proximal the
5 proximal locking ring electrode **85a** and is used to confirm
the position of the ablation assembly in the vein or venous
antrum. The second ring electrode **86b** is positioned
approximately 2.5 mm proximal the first ring electrode **86a**
10 and is also used to confirm the position of the ablation
assembly in the vein or venous antrum. If desired, an
additional ring electrode **86c** can be mounted on the
intermediate section **14** proximal the curve **15**, and distal
the junction of the intermediate section **14** and catheter
15 body **12**. This additional mapping ring electrode **86c** may be
used to assure that the curve **15** of the intermediate
section **14** is positioned in the desired location generally
within the vein or venous antrum. As understood by one of
20 ordinary skill in the art, the mapping electrodes may be
mounted at different locations on the ablation assembly **17**,
flexible section **19** and/or intermediate section **14** as
desired.

25 In **FIG. 3**, each ring electrode **85a**, **85b**, **86a**, **86b** and
86c is connected to a corresponding lead wire **50**. The
distal end of each lead wire **50** is attached to the
corresponding ring electrode. The proximal end of each lead
wire **50** is electrically connected to a suitable monitoring
30 device for monitoring electrical activity. Each lead wire
50 extends through the first lumen **30a** of the ablation
assembly **17**, the central lumen **47** of the tubing **45**, the
first lumen **30** of the intermediate section **14**, the central
35 lumen **18** of the catheter body **12**, and the control handle **16**,
and terminates at its proximal end in a connector (not
shown).

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As shown in **FIG. 2a**, the portion of each lead wire **50** extending through the control handle **16**, the central lumen **18** of the catheter body **12**, and at least the proximal section of the intermediate section **14** is enclosed within a protective sheath **62** to prevent contact with other lead wires or other components of the catheter. The protective sheath **62** can be made of any suitable material, preferably polyimide. The protective sheath **62** is anchored at its distal end to the proximal end of the intermediate section **14** by gluing it in the first lumen **30** with polyurethane glue or the like. As would be recognized by one skilled in the art, the protective sheath **62** can be eliminated if desired.

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As shown in **FIG. 5a**, an electromagnetic navigation sensor **72** may be contained within the ablation assembly **17**. The electromagnetic sensor **72** is preferably situated at the distal tip of the ablation assembly **17** and is approximately 5 mm long. The electromagnetic sensor **72** is positioned in the third lumen **34a** of the ablation assembly **17**. The electromagnetic sensor **72** is mounted to the tubing **61** of the ablation assembly **17** by any suitable means, e.g. by polyurethane glue or the like.

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The electromagnetic sensor **72** is connected to an electromagnetic sensor cable **74**, which extends through the third lumen **34a** in the ablation assembly **17**, the central lumen **47** of the flexible section **19**, the third lumen **34** of the intermediate section **14**, through the catheter body **12**, and out through the control handle **16**. The electromagnetic sensor cable **74** comprises multiple wires encased within a plastic covered sheath. In the control handle **16**, the sensor cable **74** is connected to a circuit board (not shown). The circuit board amplifies the signal received from the

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electromagnetic sensor **72** and transmits it to a computer in
a form understandable by the computer. Because the catheter
5 is designed for a single use only, the circuit board may
contain an EPROM chip which shuts down the circuit board
approximately 24 hours after the catheter has been used.
This prevents the catheter, or at least the electromagnetic
10 sensor from being used twice.

Suitable electromagnetic sensors for use with the
present invention are described, for example, in U.S. Patent
Nos. 5,558,091, 5,443,489, 5,480,422, 5,546,951, and
15 5,391,199, the disclosures of which are incorporated herein
by reference. A preferred electromagnetic sensor **72** has a
length of from about 6 mm to about 7 mm, preferably about 5
mm, and a diameter of about 1.3 mm.

In **FIG. 3a**, the irrigation tube **61** may be made of any
20 suitable material, and is preferably made of polyimide
tubing. A preferred irrigation tube has an outer diameter
of from about 0.032 inch to about 0.036 inch, and an inner
diameter of from about 0.028 inch to about 0.032 inch. The
25 irrigation tube **61** extends through the central lumen **18** of
the catheter body **12** (**FIG. 2b**), the fourth lumen **35** of the
intermediate section **14**, the central lumen **47** of the
flexible section **19**, and the fourth lumen **35a** of the
ablation assembly **17** (**FIG. 3a**), and terminates slight
30 proximal of the most proximal irrigation port **80** in the
ablation assembly **17**. The proximal end of the irrigation
tube **61** extends through the control handle **16** and terminates
in a luer hub or the like (not shown). Fluid is introduced
35 into the irrigation tube **61** through the luer hub. The
fluid, e.g. saline, is then introduced to the fourth lumen
35a of the ablation assembly **17** by the irrigation tube **61**

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and passes to the outer surface of the tubing 61 through the irrigation ports 80 (FIG. 5a). The fluid is then dispersed over generally the entire surface of the ablation assembly 17 by the porous covering 84. This irrigation enables creation of deeper lesions.

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In use, the catheter 10 is inserted into the patient through a suitable guiding sheath whose distal end is positioned at a desired mapping or ablating location. An example of a suitable guiding sheath for use in connection with the present invention is the Preface™ Braided Guiding Sheath, commercially available from Biosense Webster, Inc. (Diamond Bar, California). The distal end of the sheath is guided into one of the atria. A catheter in accordance with the present invention is fed through the guiding sheath until its distal end extends out of the distal end of the guiding sheath. As the catheter 10 is fed through the guiding sheath, the tip assembly 17, the flexible section 19 and the intermediate section 14 are generally straightened to fit through the sheath. Once the distal end of the catheter is positioned at the desired mapping or ablating location, the guiding sheath is pulled proximally, allowing the deflectable intermediate section 14, the flexible section 19 and the tip assembly 17 to extend outside the sheath, and return to their original preformed shapes with the tip assembly 17 extending from the curve 15 at a predetermined off-axis angle θ and/or off-plane angle γ .

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The curve 15 of the intermediate section 14 is then deflected or otherwise maneuvered to sit in the antrum (FIG. 1A) or vein (FIGS. 6a and 6b) which can be approached from a more "backward" direction being that the curvature of the curve 15 is generally opposite to the direction of

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deflection. The user can then position the catheter **10** with minimal risk of the tip assembly **17** entering a pulmonary vein.

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The curve **15** of the intermediate section **14** stabilizes the tip assembly **17** in the region and the tip assembly **17** makes contact with tissue in the region by means of the preset off-axis angle provided by the flexible section **19**. To create generally continuous lesions during ablation, the catheter is advanced, withdrawn and/or rotated to drag the tip assembly **17** along the tissue surface. As the ablation assembly encounters uneven formation such as a projection or recess in the tissue surface, the flexible section **19** flexes as the ablation assembly pivots from the preset off-axis angle to absorb the movement without displacing the curve **15** of the intermediate section **14** in the pulmonary venous antrum or pulmonary vein. Whether the tip assembly **17** is maneuvered linearly or rotated via the control handle **16** and/or the catheter body **12**, the tip assembly **17** maintains continuous contact with the tissue for improved mapping and/or creation of lesions. In the embodiment of the catheter for mapping applications, similar manipulations of the catheter and the control handle enable the mapping electrodes **85a**, **85b**, **86a**, **86b** and **86c** to map in a linear or circumferential pattern.

The preceding description has been presented with reference to presently preferred embodiments of the invention. Workers skilled in the art and technology to which this invention pertains will appreciate that the Figures are not necessarily to scale and alterations and changes in the described structure may be practiced without meaningfully departing from the principal spirit and scope

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of this invention. Accordingly, the foregoing description should not be read as pertaining only to the precise structures described and illustrated in the accompanying drawings, but rather should be read consistent with and as support for the following claims which are to have their fullest and fairest scope.

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WHAT IS CLAIMED IS:

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1. A catheter comprising:

an elongated flexible tubular catheter body having proximal and distal ends;

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an intermediate section attached to the distal end of the catheter body, the distal end of the intermediate section having a preformed curve, wherein the curve of the intermediate section is adapted to sit in a generally cavernous region of or near the heart;

a tip assembly; and

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a flexible section connecting the tip assembly to the preformed curve at a preset off-axis angle, the flexible section adapted to permit displacement of the tip assembly from the preset off-axis angle without displacement of the preformed curve in the generally cavernous region.

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2. The catheter of claim 1, wherein the flexible section connects the tip assembly to the preformed curve at a preset off-plane angle.

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3. The catheter of claim 2, wherein the flexible section comprises at least one lateral support structure to minimize movement of the tip assembly from the preset off-plane angle.

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4. The catheter of claim 1, wherein the intermediate section is more flexible than the catheter body.

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5. The catheter of claim 1, wherein the intermediate section is deflectable in a direction and the curve has a curvature generally opposite to said direction.

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6. The catheter of claim 1, wherein the flexible section is more flexible than the intermediate section.

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7. The catheter of claim 1, wherein the off-axis angle ranges between about 2 and 180 degrees.

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8. The catheter of claim 1, wherein the off-plane angle ranges between 2 and 360 degrees.

9. The catheter of claim 1, wherein the displacement of the tip assembly is between the preset off-axis position and an on-axis position.

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10. The catheter of claim 1, wherein the tip assembly is configured for mapping.

11. The catheter of claim 1, wherein the tip assembly is configured for ablation.

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12. The catheter of claim 1, further comprising:
a control handle connected to the proximal end of the catheter body; and

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a puller wire manipulated by the control handle and wire extending longitudinally relative to the catheter body, whereby longitudinal movement of the puller wire relative to the catheter body results in deflection of the intermediate section in a direction generally opposite to the preformed curve.

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13. A catheter comprising:

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an elongated flexible tubular catheter body having proximal and distal ends;

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an intermediate section attached to the distal end of the catheter body, the distal end of the intermediate section having a preformed section with a configuration that conforms to a generally cavernous region of or near the heart;

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a tip assembly; and

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a flexible section connecting the tip assembly to the preformed section, the flexible section having a flexibility greater than the preformed section and adapted to maintain the tip assembly in contact with the tissue during movement of the catheter without changing the configuration of the preformed curve in the generally cavernous region.

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14. A catheter of claim 13, wherein the configuration of the preformed section is substantially U shaped.

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15. A catheter of claim 13, wherein the configuration of the preformed section is substantially hook shaped.

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16. A catheter of claim 13, wherein the configuration of the preformed section generally conforms to a pulmonary vein.

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17. A catheter of claim 13, wherein the configuration of the preformed section generally conforms to a pulmonary venous antrum.

18. A catheter of claim 13, wherein contact between preformed section and the generally cavernous region

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synchronizes a distal portion of the catheter to heart
motion during systole, diastole or respiration.

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19. A catheter of claim 13, wherein contact between
preformed section and the generally cavernous region
stabilizes position of the tip assembly.

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20. A catheter of claim 13, wherein the tip assembly
includes an ablation electrode.

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21. A catheter of claim 13, wherein the tip assembly
includes a mapping electrode.

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22. The catheter of claim 13, further comprising:
a control handle connected to the proximal end of the
catheter body; and

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a puller wire manipulated by the control handle and
extending longitudinally relative to the catheter body,
whereby longitudinal movement of the puller wire relative to
the catheter body results in deflection of the intermediate
section in a direction generally opposite to the preformed
curve.

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23. A method for ablating tissue at an intersection of
a generally flat region and an ostium of a generally
cavernous region at or near the heart, the method
comprising:

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inserting into the heart a distal end of a catheter
according to claim 1;

deflecting the preformed curve to generally sit in the
generally cavernous region;

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applying energy to the tip assembly configured for ablation while moving the tip assembly along a surface at said intersection wherein the tip assembly maintains contact with the surface to form a generally continuous lesion despite variable contour of the generally flat region.

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24. A method of claim 23, wherein the tip assembly is dragged along the surface in a generally linear direction.

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25. A method of claim 23, wherein the tip assembly is rotated about its axis by rotating a control handle of the catheter to form a circumferential lesion at or near said intersection.

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26. A method for mapping tissue at an intersection of a generally flat region and an ostium of a generally cavernous region at or near the heart, the method comprising:

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inserting into the heart a distal end of a catheter according to claim 1;

deflecting the preformed curve to generally sit in the generally cavernous region;

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recording electrograms from the tip assembly configured for mapping while moving the tip assembly along a surface at said intersection wherein the tip assembly maintains contact with the surface despite variable contour of the generally flat region.

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27. A method of claim 26, wherein the tip assembly is dragged along the surface in a generally linear direction.

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28. A method of claim 26, wherein the tip assembly is rotated about its axis by rotating a control handle of the catheter at or near said intersection.

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29. A catheter comprising:

an elongated flexible tubular catheter body having proximal and distal ends;

an intermediate section attached to the distal end of the catheter body, the distal end of the intermediate section having a preformed curve, wherein the curve of the intermediate section is adapted to sit in a generally cavernous region of or near the heart;

an ablation assembly; and

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a flexible section connecting the ablation assembly to the preformed curve at a preset off-axis angle, the flexible section adapted to permit displacement of the ablation assembly from the preset off-axis angle without displacement of the preformed curve in the generally cavernous region.

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30. The catheter of claim 29, wherein the ablation assembly comprises:

a plurality of irrigation ports;

a coil electrode; and

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a porous covering in surrounding relation to the coil electrode and irrigation ports.

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31. The catheter of claim 30, wherein the coil electrode has a length ranging from about 8 mm to about 15 mm.

32. The catheter of claim 31, wherein the coil

1 electrode has a length of about 10 mm.

5 33. The catheter of claim 30, wherein the porous covering comprises expanded polytetrafluoroethylene.

10 34. The catheter of claim 29, further comprising a temperature sensor mounted in the ablation assembly.

15 35. The catheter of claim 30, further comprising:
a proximal locking ring electrode mounted on a proximal region of the ablation assembly over the coil electrode and the porous covering; and
a distal locking ring electrode mounted on a distal region of the ablation assembly over the coil electrode and the porous covering.

20 36. The catheter of claim 29, further comprising one or more ring electrodes proximal of the ablation assembly.

25 37. The catheter of claim 29, further comprising:
a puller wire having proximal and distal ends extending through the catheter body, the distal end of the puller wire being fixedly attached within the proximal end of the intermediate section; and

30 a control handle connected to the proximal ends of the catheter body and puller wire for moving the puller wire longitudinally relative to the catheter body, whereby longitudinal movement of the puller wire relative to the
35 catheter body results in deflection of the intermediate section.

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38. The catheter of claim 29, further comprising an
electromagnetic sensor mounted in the ablation assembly.

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39. The catheter of claim 29, wherein the intermediate
section further comprises a support member comprising a
material having shape-memory to provide the performed curve.

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40. The catheter of claim 29, further comprising an
irrigation tube extending into the ablation assembly.

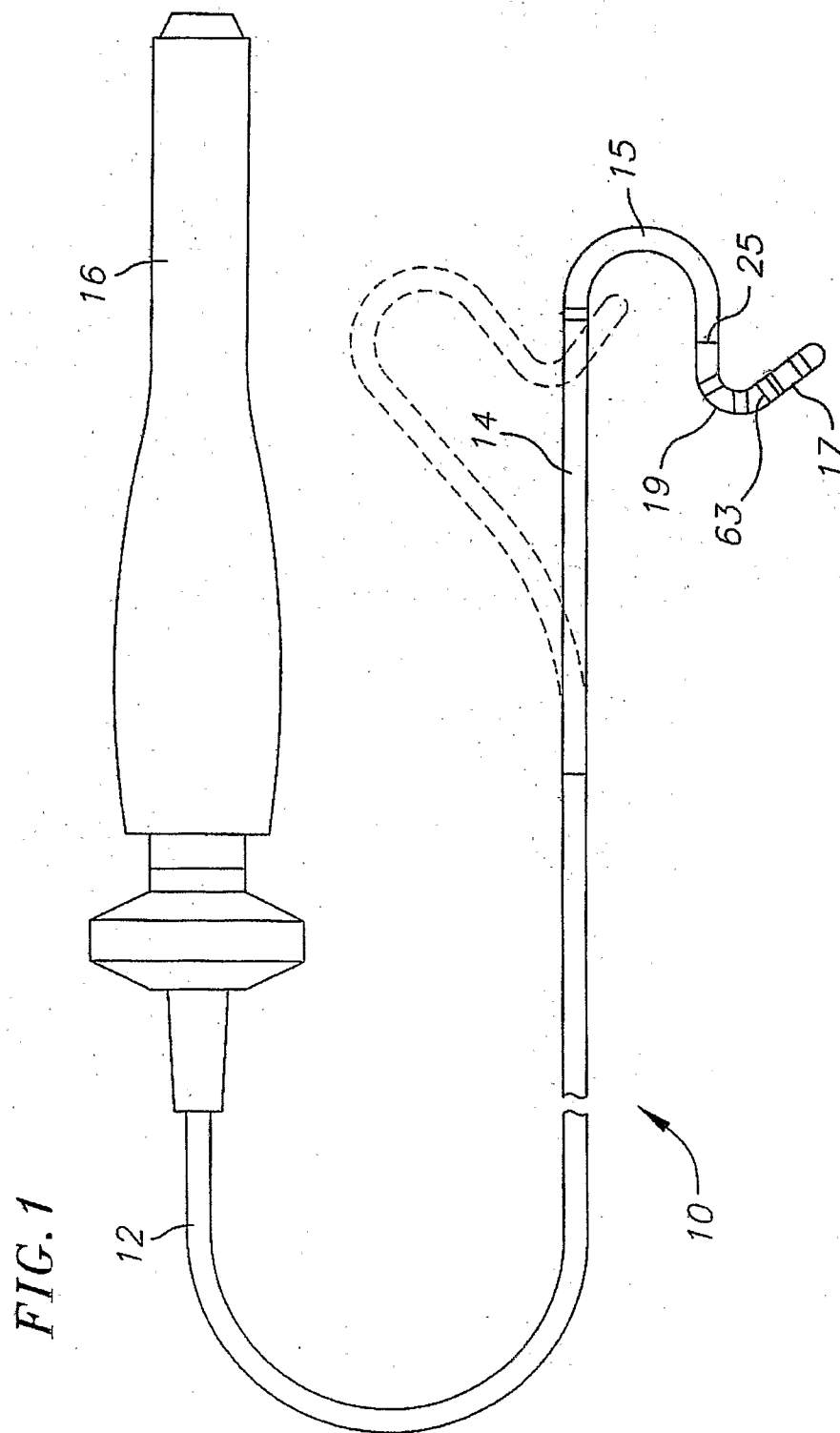
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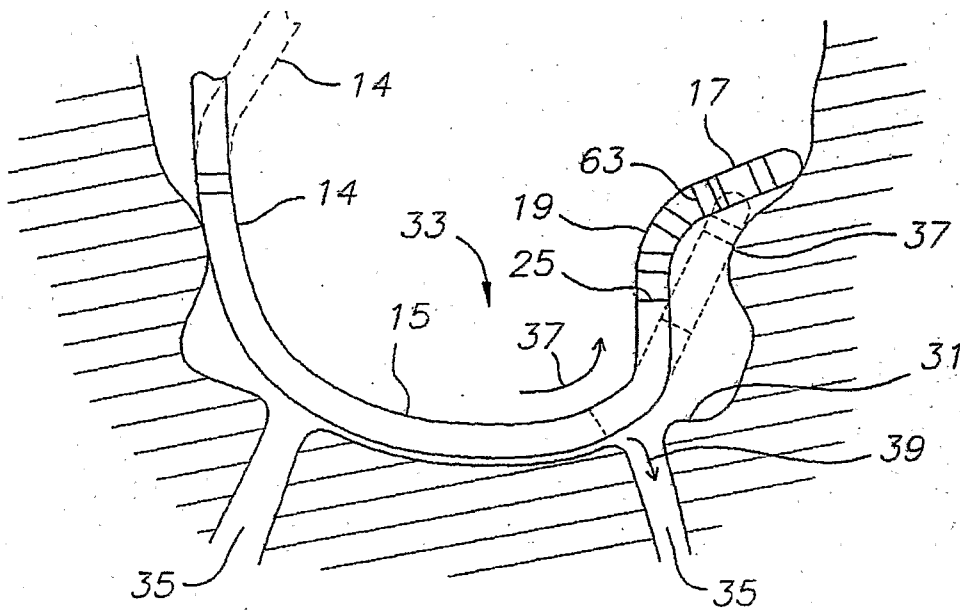


FIG. 1A

FIG. 2a

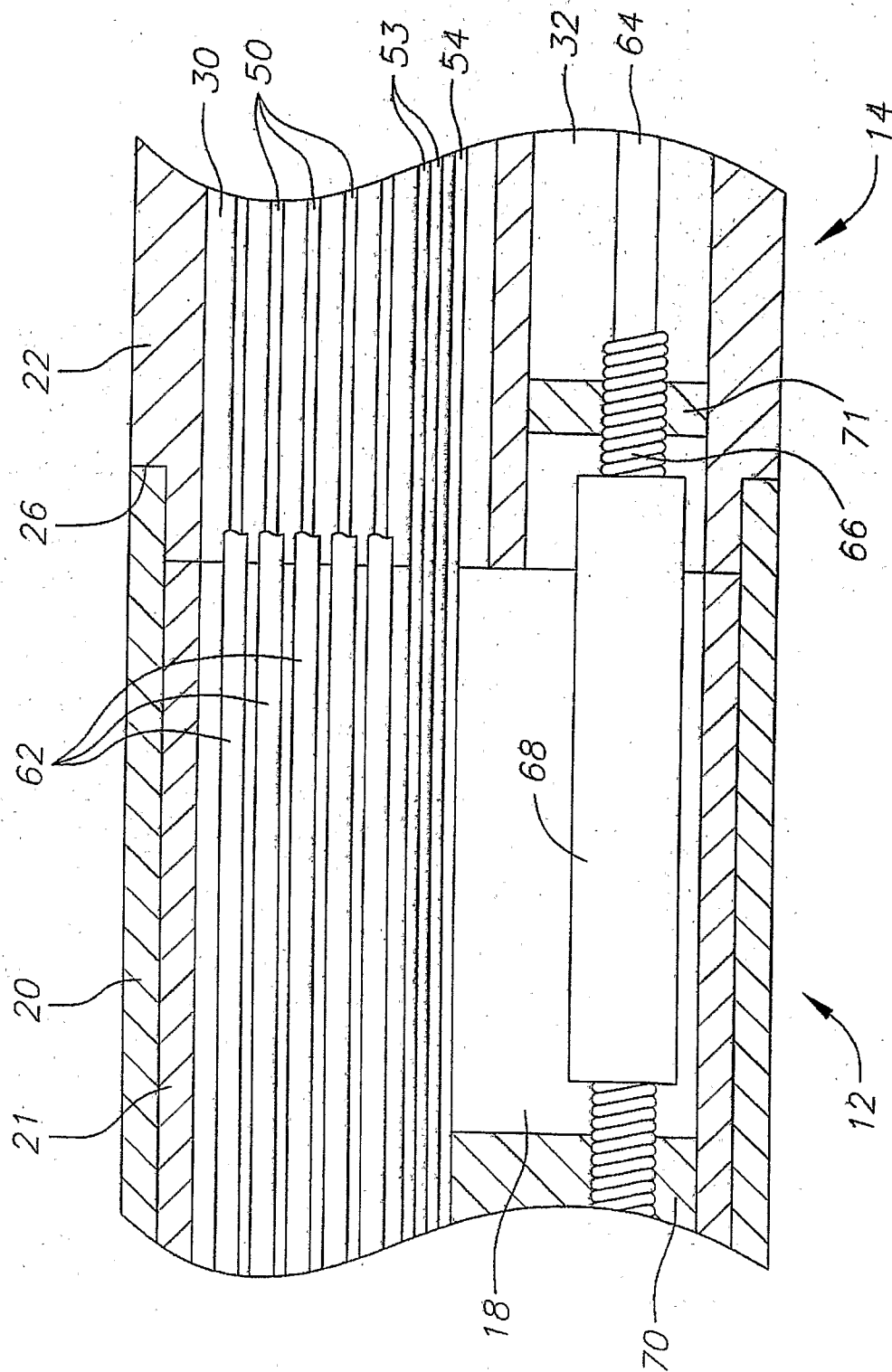


FIG. 2b

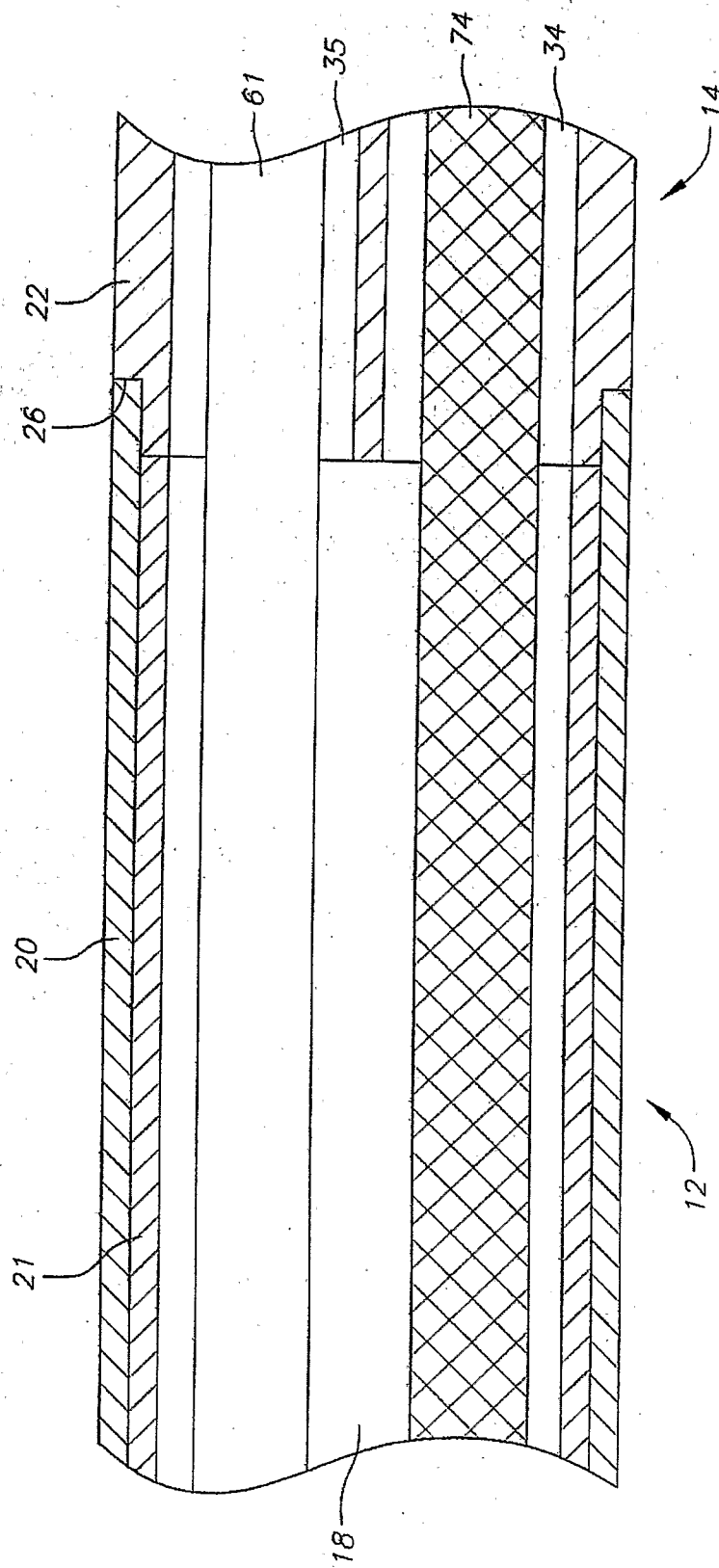


FIG. 2c

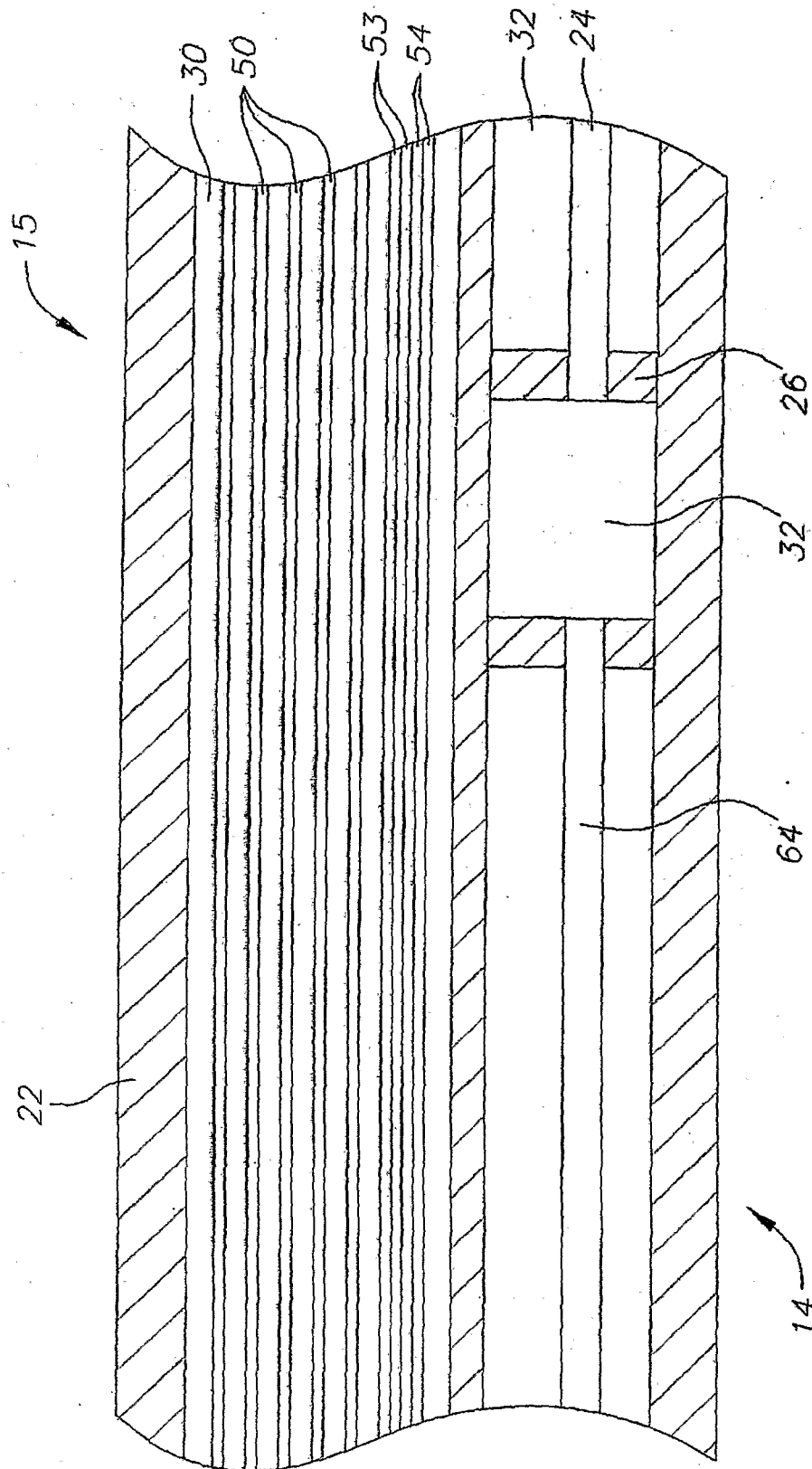


FIG. 3

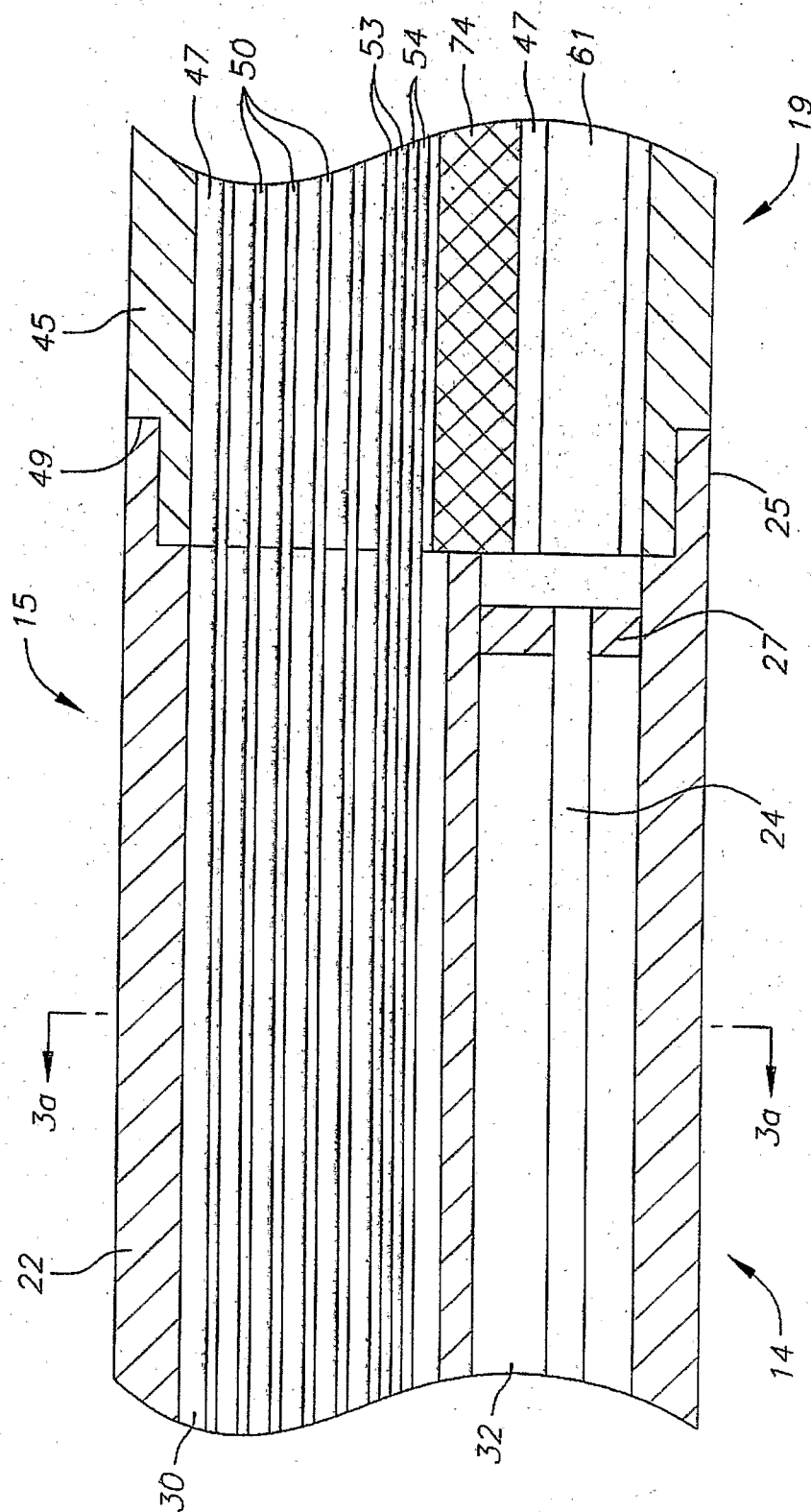


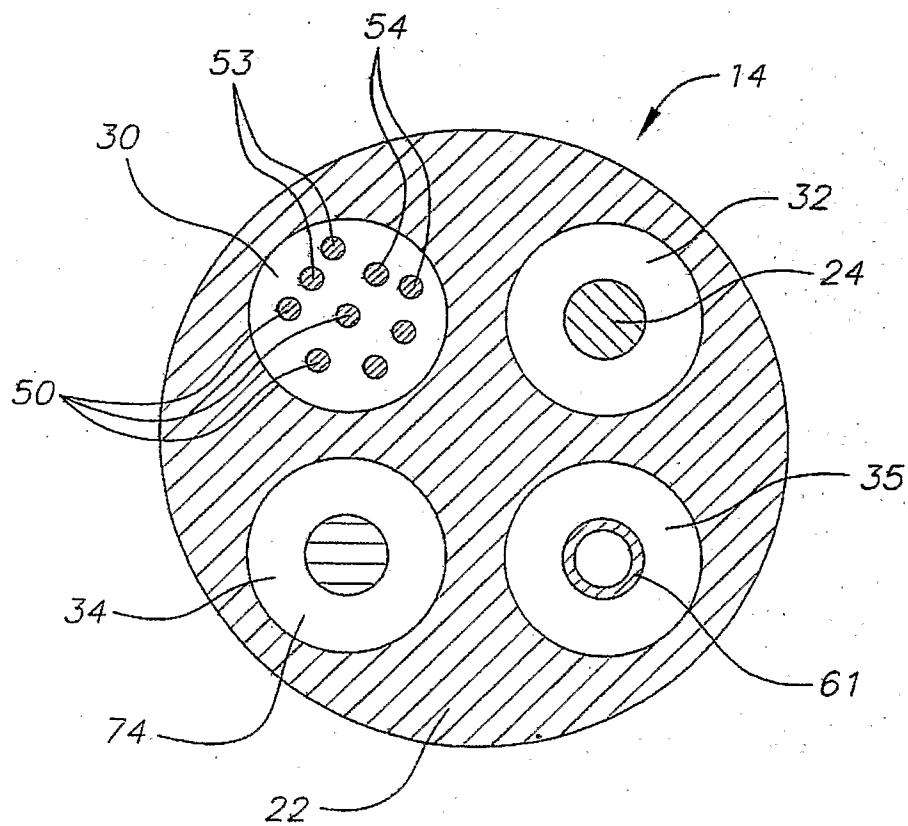
FIG. 3a

FIG. 3b

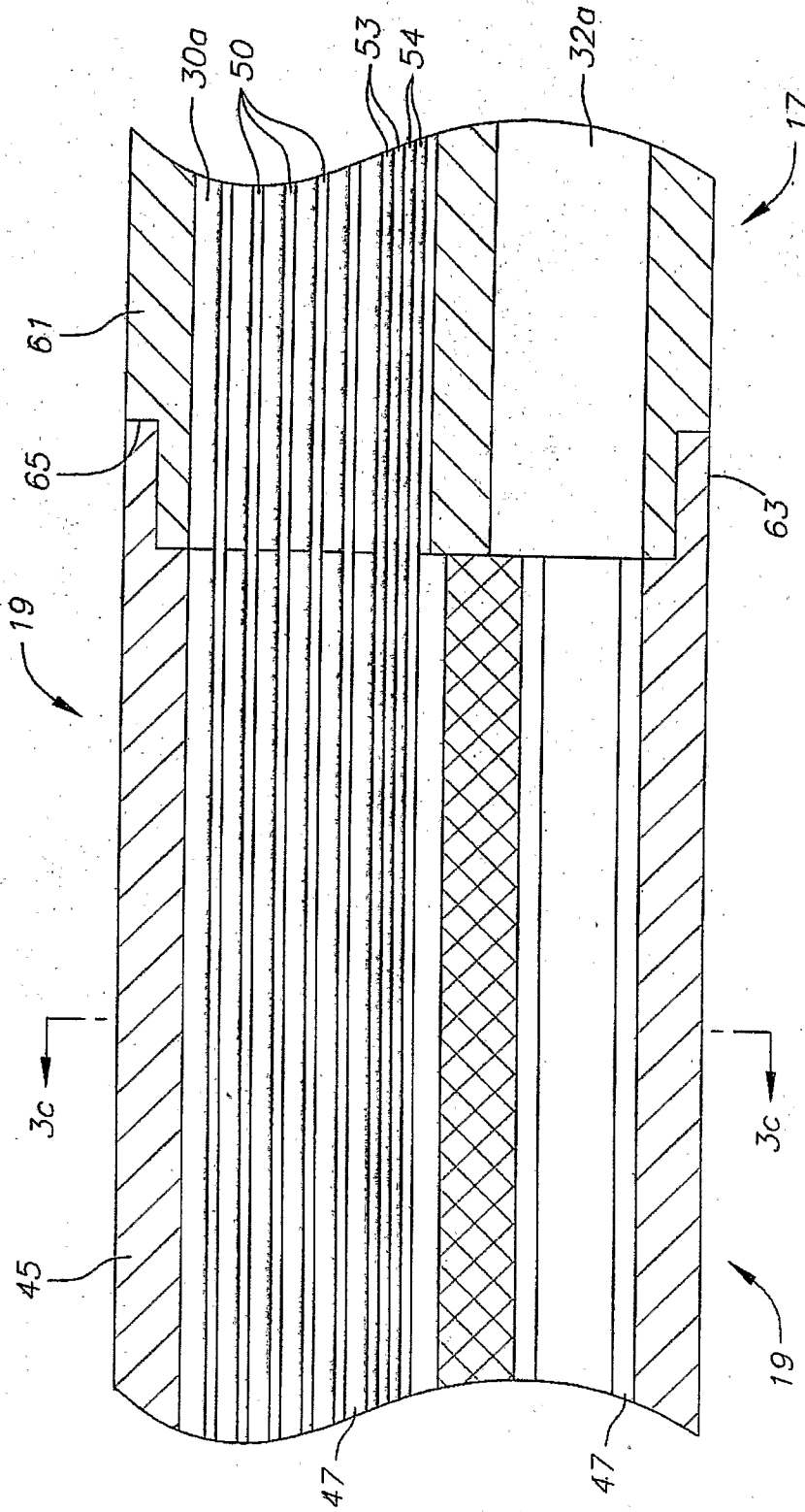


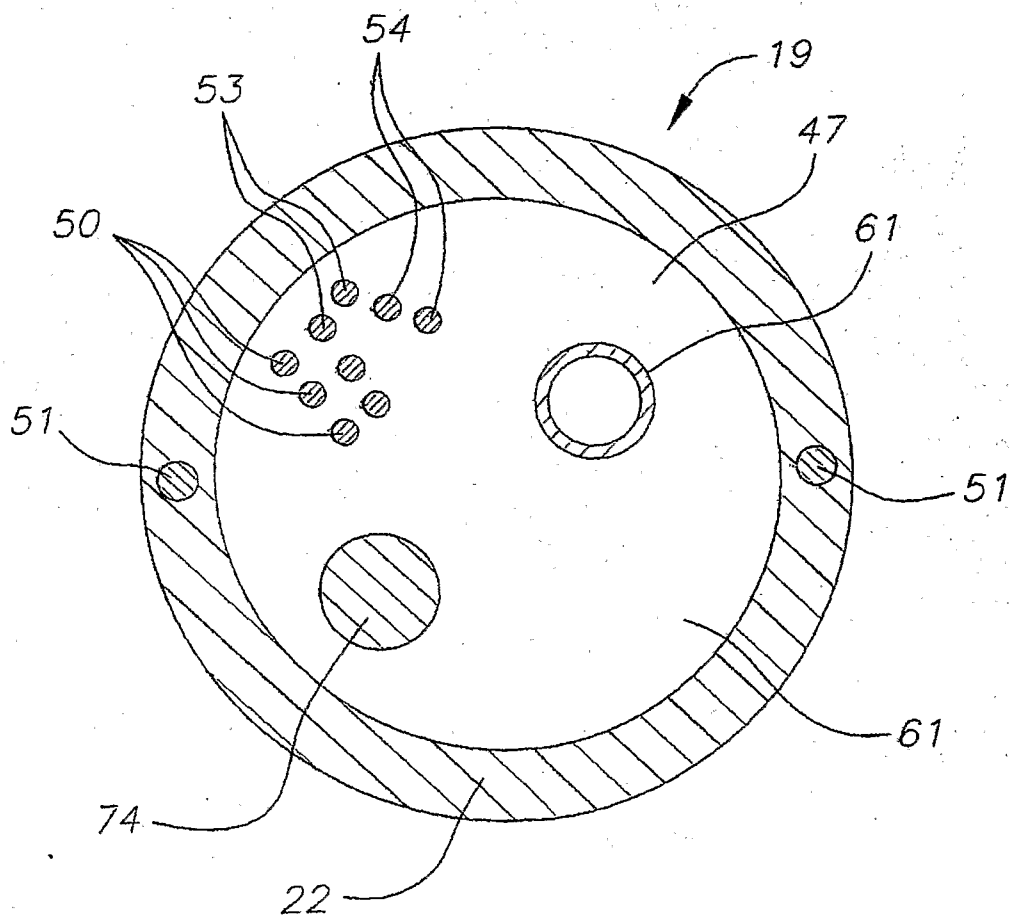
FIG. 3c

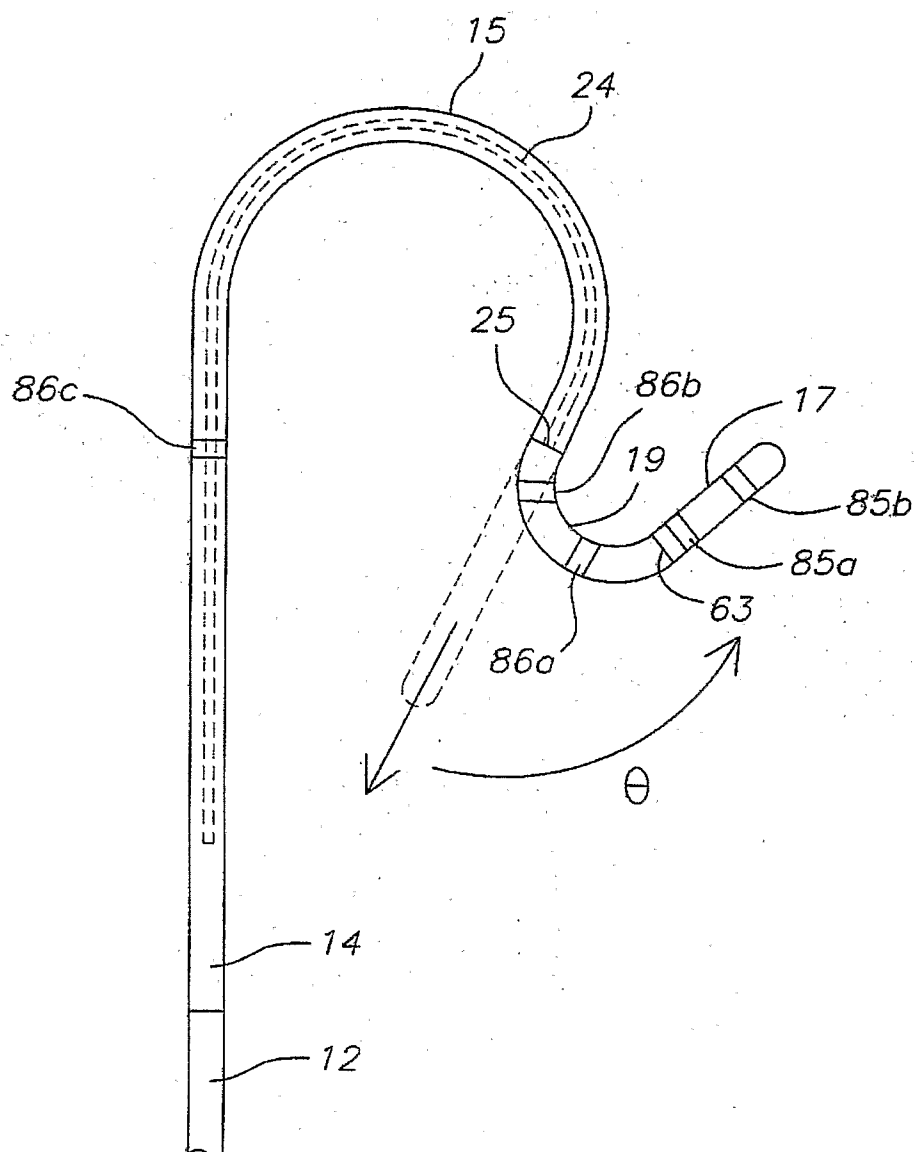
FIG. 4A

FIG. 4B

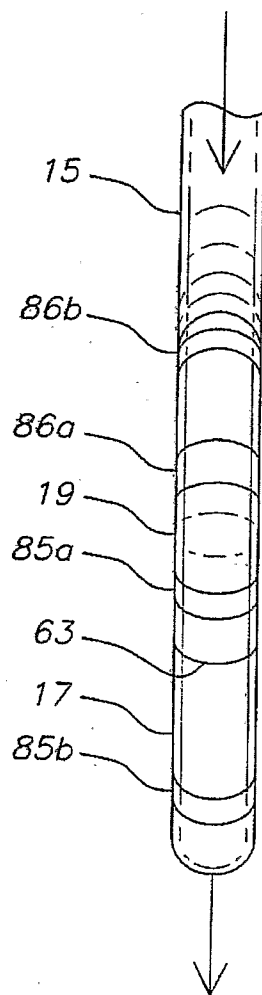


FIG. 4C

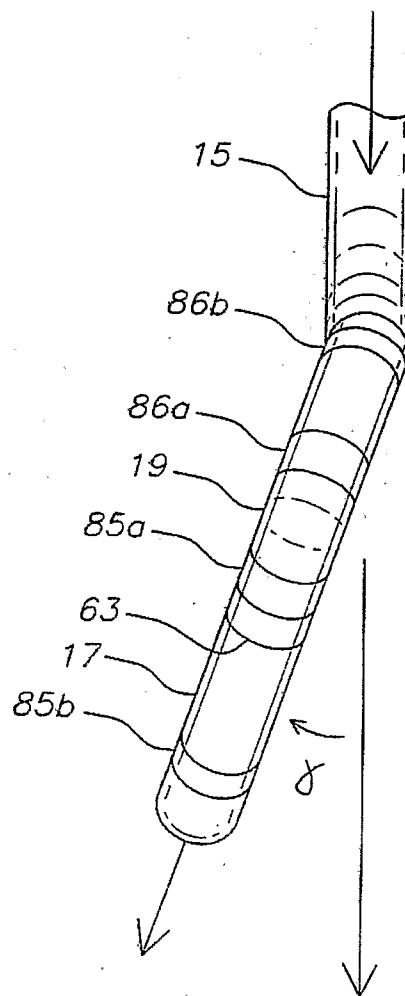


FIG. 5a

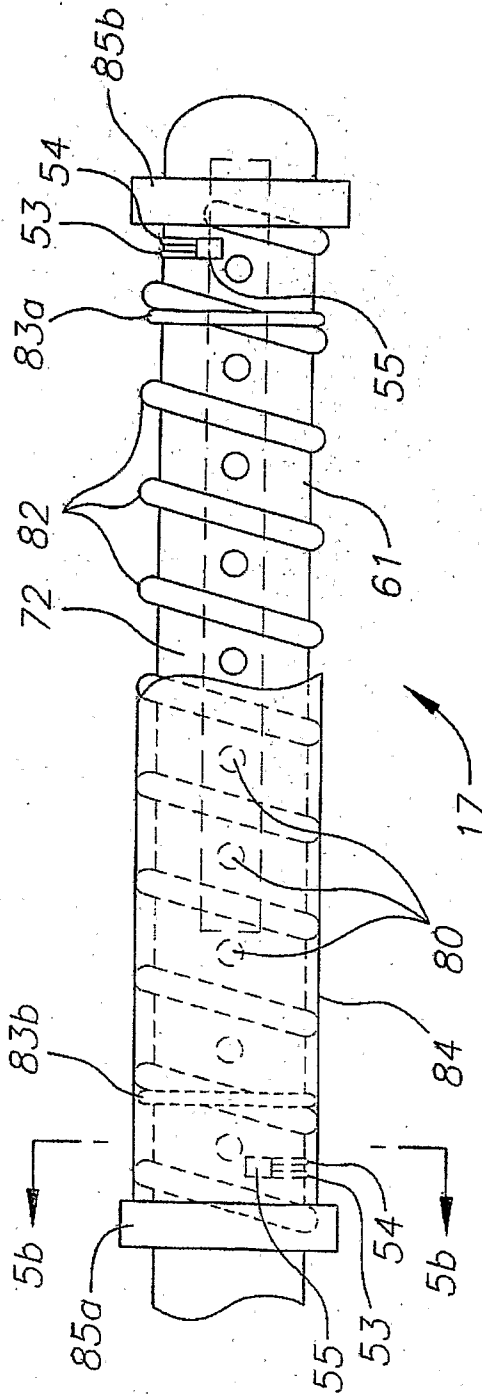


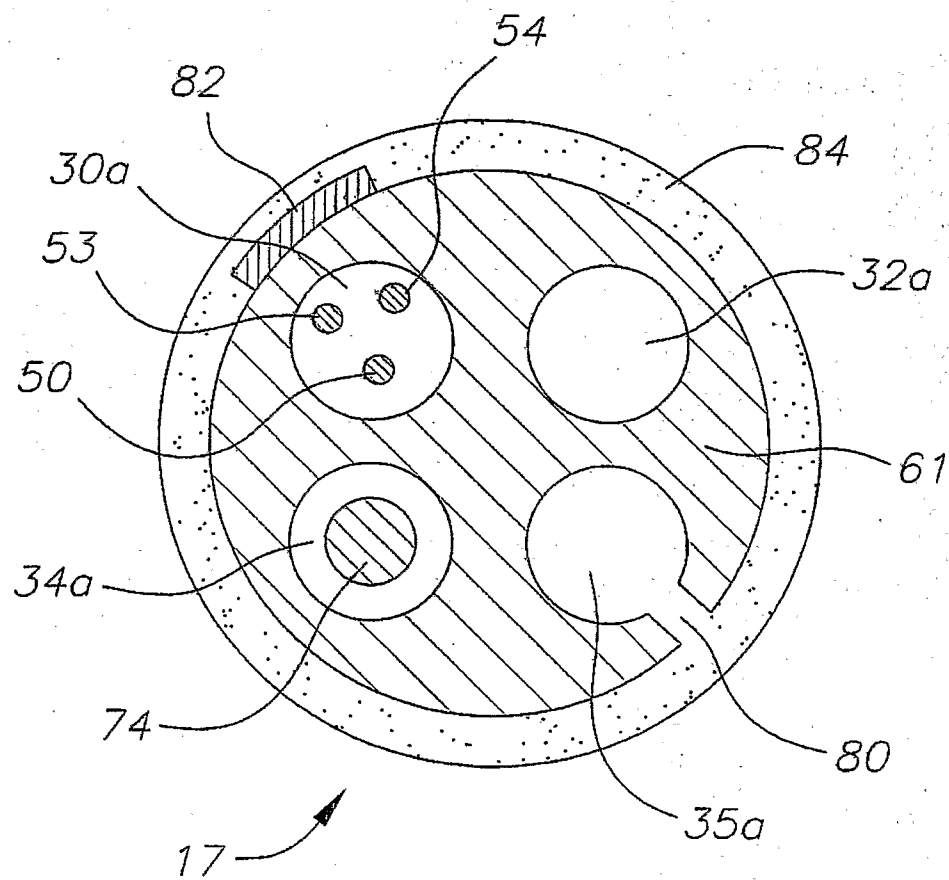
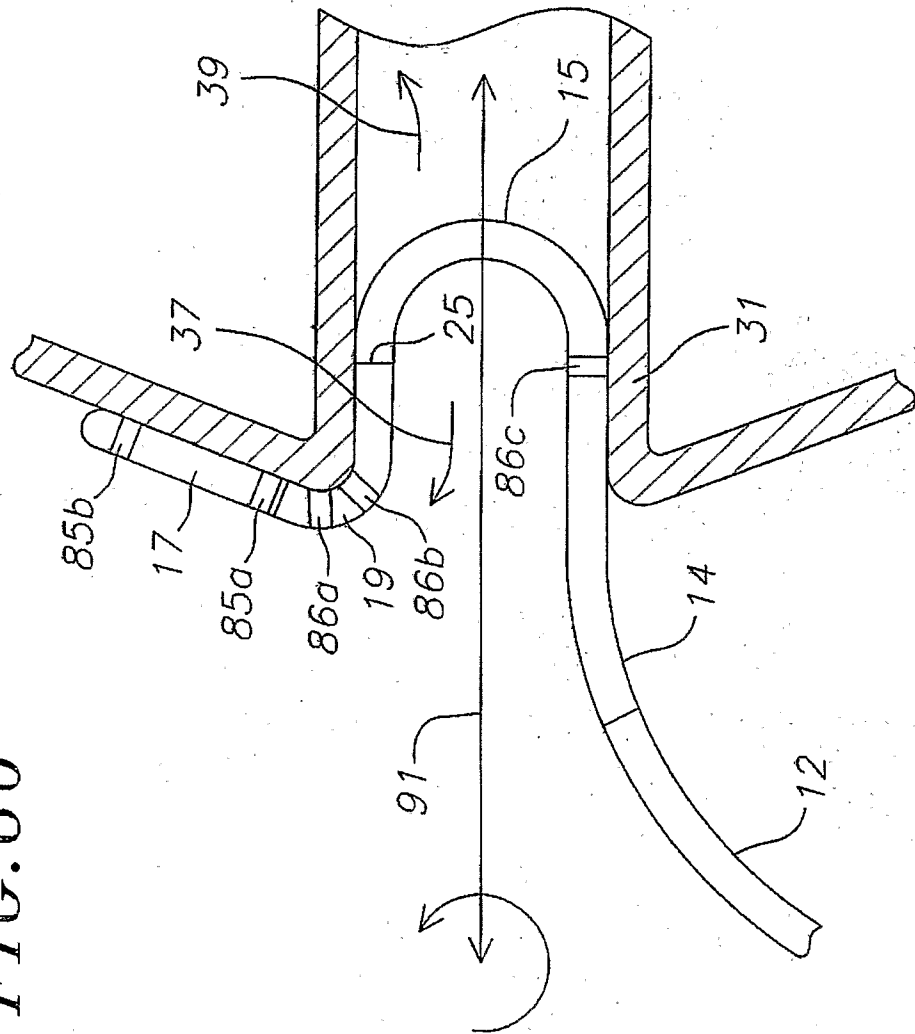
FIG. 5b

FIG. 6b



INTERNATIONAL SEARCH REPORT

International application No

PCT/US2006/036146

A. CLASSIFICATION OF SUBJECT MATTER

INV. A61M25/01 A61M15/00 A61B18/14

According to International Patent Classification (IPC) or to both national classification and IPC.

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

A61M A61B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

EP0-Internal

C. DOCUMENTS CONSIDERED TO BE RELEVANT

| Category* | Citation of document, with indication, where appropriate, of the relevant passages | Relevant to claim No. |
|-----------|--|--|
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| Y A | US 5 643 197 A (BRUCKER GREGORY G [US] ET AL) 1 July 1997 (1997-07-01) column 6, line 25 - column 11, line 43; figures 5-16 | 30-33, 35, 38, 40 1-22, 29, 34, 36, 37, 39 |
| X | US 2004/143175 A1 (COLEMAN JAMES H [US] ET AL) 22 July 2004 (2004-07-22) paragraphs [0029] - [0055]; figures 1-10 ----- -/-- | 1-22, 29, 36, 37, 39 |

☒ Further documents are listed in the continuation of Box C.

☒ See patent family annex.

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Date of the actual completion of the international search

24 January 2007

Date of mailing of the international search report

02/02/2007

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INTERNATIONAL SEARCH REPORT

International application No

PCT/US2006/036146

G(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

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INTERNATIONAL SEARCH REPORT

International application No.
PCT/US2006/036146

Box II Observations where certain claims were found unsearchable (Continuation of item 2 of first sheet)

This International Search Report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:

1. ☒ Claims Nos.: 23-28
because they relate to subject matter not required to be searched by this Authority, namely:
Rule 39.1(iv) PCT - Method for treatment of the human or animal body by surgery
2. ☐ Claims Nos.:
because they relate to parts of the International Application that do not comply with the prescribed requirements to such an extent that no meaningful International Search can be carried out, specifically:
3. ☐ Claims Nos.:
because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a).

Box III Observations where unity of invention is lacking (Continuation of item 3 of first sheet)

This International Searching Authority found multiple inventions in this international application, as follows:

1. ☐ As all required additional search fees were timely paid by the applicant, this International Search Report covers all searchable claims.
2. ☐ As all searchable claims could be searched without effort justifying an additional fee, this Authority did not invite payment of any additional fee.
3. ☐ As only some of the required additional search fees were timely paid by the applicant, this International Search Report covers only those claims for which fees were paid, specifically claims Nos.:
4. ☐ No required additional search fees were timely paid by the applicant. Consequently, this International Search Report is restricted to the invention first mentioned in the claims; it is covered by claims Nos.:

Remark on Protest

- ☐ The additional search fees were accompanied by the applicant's protest.
- ☐ No protest accompanied the payment of additional search fees.

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No

PCT/US2006/036146

| Patent document cited in search report | | Publication date | Patent family member(s) | Publication date |
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