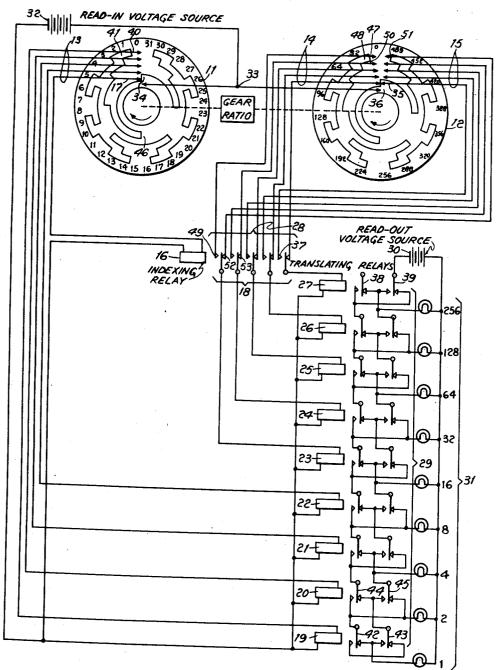
ANALOG-TO-DIGITAL TRANSLATOR

Filed Jan. 7, 1957



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2,943,311

ANALOG-TO-DIGITAL TRANSLATOR

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> Filed Jan. 7, 1957, Ser. No. 633,173 2 Claims. (Cl. 340-347)

translation devices and in particular to a device for translating the value of angular shaft positions into coded electrical pulses.

In analog-to-digital translation devices, it becomes necessary to channel the energy pulses from the shaft read-out elements to some means which is capable of translating these pulses into the language of the machine for computation or storage purposes. In the prior art, such a translation has been accomplished by means of banks of relays or switching matrices. The use of banks of relays in the prior art involved holding circuits which were operated for switching advantage by having one relay drop out another relay as the first relay was picked. There very often is a chain reaction with this arrangement or a series of relay actions, to wit: picking, holding and 30 12. dropping, for a single data bit change. It is obvious that such a chain reaction of the relays results in relatively slow operation and a requisite sensitive timing.

It also has been necessary in the translation operation to assure a non-ambiguous read-out from the shaft elements. For instance, in reading out the numbers 39, 40 and 31 and assuming a separate read-out positoin for the units and tens position, it is conceivable that if the brushes did not read exactly together, but instead one brush led or 39, 49, 40 and 41. To overcome this problem, there is brought into use the lead and the lag brush. The lead and lag brushes are set respectively far ahead and far behind the normal read-out point; and by reading from brush at and beyond the "carry" time, there is insured a non-ambiguous read-out. It is clear that to accomplish the lead and lag read-out there must be a controlling device. In certain translation devices the controls are accomplished by having conductive strips of 180 degrees 50 added to the shafts. By controlling relays with these commutator straps and having the read-out pass through these relays, it is possible to have either lead or lag readout for one-half the shaft rotation. It also becomes clear herent mechanical characteristics in combination with the relays, gives rise to considerations of mechanical tolerance and speed limitations, the improvement of which is desirable for the higher speed operations such as those desired in analog computers or high-speed control sys- 60

It is therefore the object of this invention to provide an improved analog-to-digital translation device.

It is a further object of this invention to provide a translation device which provides an output digital change 65 of "one" or one bit by means of transferring only one relay.

It is a further object of this invention to provide a translation device wherein the tolerances for the read-out means associated with the shaft rotating elements is not 70 critical.

In accordance with the above objects the invention

features logical relay circuitry which provides for adding or subtracting from the translation answer one digit value at a time while only requiring one relay operation at a time to accomplish the change. A relay may be "picked" to add an additional single digit value or "dropped out" to add a single digit value depending on its energized or deenergized status before the addition is sensed. The invention further features coded wheels attached to the shaft which serves as a primary source of shaft position 10 information. An additional feature of the invention is the provision of lead and lag readout means to insure a non-ambiguous readout. In conjunction with the coded wheels and the lead and lag readout the invention further features that the code inscription itself serves as a control This invention relates generally to analog-to-digital 15 for the lead and lag readout. Conductive material on a lower ordered wheel is arranged to be operative in conjunction with a control brush for a certain portion of the lower ordered wheel's rotation to effect a lead and lag readout control. As higher ordered wheels are 20 added to the device, the lower ordered wheels act in this control capacity as well as a source of shaft angular position information.

> The above mentioned and other features and objects of this invention will become more apparent by reference 25 to the following description taken in conjunction with the accompanying drawing in which the figure is a combination schematic and circuit representation of an analog-todigital translation device.

In the figure there are shown two code wheels 11 and On code wheel 11 there is a set of read-out brushes 13. On code wheel 12 there is a set of lead read-out brushes 14 and a set of lag read-out brushes 15. The index relay coil 16 is connected to the read-out brush 17. The movable contacts 18 are connected mechanically with and actuated by the relay coil 16. The relay coils 19 through 27 are connected through the movable contacts 18 and points 28 to the lead and lag readout brushes 14 and 15. The relay points 29 are coupled to the read-out voltage source 30 and to the output means the other, the translation might read 39, 30, 40 and 41 40 31 shown as light bulbs in the figure reading in binary number notation. A more comprehensive understanding of the invention will result from the following discussion taken in conjunction with the figure.

The figure shows the device reading 511. On wheel the lag brush up to a "carry" time and from the lead 45 11 only brush 17 is resting on conductive material. A circuit from the read-in supply 32, to junction 33, to conductive strip 34, through brush 17, through coil 16, to the other side of the supply 32 causes coil 16 to be energized. With coil 16 energized, the movable contacts 18 are attracted to rest on the normally open points of 28. On wheel 12 the only read-out brush on the conductive material is brush 35. A circuit from the read-in supply 32, through junction 33, to segment 36, through brush 35, through normally open point 37, through coil that the above-mentioned commutator strap, with its in- 55 27, to the other side of the supply 32 serves to energize coil 27 and thus transfer the movable contacts 38 and 39. With movable contacts 38 and 39 transferred, all the bulbs are illuminated, which results in a device reading additively, in binary numbers, the value 511. As the wheels 11 and 12 rotate clockwise, the brush 17 moves off the segment 34, and the relay coil 16 becomes deenergized dropping out the movable contacts 18. The transfer of the movable contacts 18 results in the deenergization of coil 27 which, in turn, causes the movable contacts 38 and 39 to shift to their unenergized position. With the movable contacts 38 and 39 now resting on the normally closed points, the circuits for lighting the bulbs have been opened; and hence, none of the bulbs are illuminated. As wheel 11 continues to rotate clockwise, brush 40 comes in contact with the segment at 41. A circuit from the read-in supply 32 through brush 40 causes the relay coil 19 to be energized, and thus the straps 42 and 43 are

transferred. With the straps 42 and 43 resting on the normally open side, the light bulb number 1 is illuminated, giving a correct reading of the shaft position. By following the rotation of wheel 11 and noting the position of the brushes on the segment, it becomes clear that relay coil 20 will next be energized, which will transfer the movable contacts 44 and 45. transfer of the movable contacts 44 and 45, the circuit continuity to light bulb 1 is opened, and simultaneously the circuit continuity to light bulb 2 is closed. It is 10 significant that the output value has been changed by one bit with only one relay action. At the time that the number 2 bulb is glowing, relay 19 is still energized; and as wheel 11 approaches the value 3, relay 19 is deenergized. With the deenergization of relay 19 and the 15 dropping out of the movable contacts 42 and 43, the bulb 1 is again illuminated, thus having bulbs 1 and 2 glowing at the same time to give the correct additive answer of 1+2=3. This circuitry pattern follows, and the next significant step in the discussion occurs at the 20 time that wheel 11 reaches the value 16. When wheel 11 reaches the value 16, brush 17 makes contact with the conductive material at 46 and thereby causes relay coil 16 to be energized. At this same time, wheel 12 has moved to a position where brush 47 is making contact 25 with the conductive segment at 48. Coil 16 having been energized, the straps 18 are transferred and brush 47 reads out through the normally open point 49 and the relay coil 23 is energized to light up bulb 16. As wheel 11 continues to rotate until brush 17 leaves the segment 30 at 34, wheel 12 will have moved into a position where brushes 48, 50 and 51 will be on the conductive segment. When brush 17 leaves the segment 34 and coil 16 is deenergized, the lag brush 51 will read through the normally closed brush 53, thus energizing the coil 24 to permit the bulb 32 to remain illuminated. The operation of the circuit continues in this same fashion, changing the value of the output by one digit at a time with a single relay action at a time. The device as shown here will continue to shift the read-out of the higher ordered wheel 12 from 40 lead to lag, thus insuring non-ambiguity of read-out.

I claim:

1. A translation device for translating angular shaft positions into coded electrical pulses comprising an input shaft, first and second code wheels, means coupling said code wheels to said shaft for rotation therewith whereby said first code wheel rotates a smaller amount than said second code wheel for the same amount of shaft rotation, lead and lag readout means coupled with said first code wheel, single readout means coupled with said second code wheel, an indexing relay having a plurality of normally open points, normally closed points and movable contacts coupled to said lead and lag readout means, indexing relay control means coupled to said second wheel to control the transfer of the readout from said first wheel between said lead and lag readout means for a particular angular rotation of said second wheel, output means for representing said shaft angular positions in coded form, a plurality of output relays arranged in two groups, each group coupled respectively to a corresponding code wheel, and each assigned a different order

of value, each output relay having a pair of movable contacts, each of said movable contacts having an associated normally open point and normally closed point, connecting means associated with each output relay coupling the normally associated open point of one of said movable contacts to the normally associated closed point of the other of said movable contacts, logical circuitry means coupling each of said movable contacts to an associated one of said connecting means of the next higher ordered output relay, and circuitry means coupling said logical circuitry means between said output means and both said single and said lead and lag readout means to effect a change of one digit value in said translation output by a single transfer of said movable contacts.

2. A translation device for translating angular shaft positions into coded electrical pulses comprising an input shaft, first and second code wheels, means coupling said code wheels to said shaft for rotation therewith whereby said first code wheel rotates a smaller amount than said second code wheel for the same amount of shaft rotation, lead and lag readout brushes coupled with said first code wheel, single readout brushes coupled with said second code wheel, a transfer relay with a plurality of normally open points, normally closed points and movable contacts, said transfer relay points coupled to said leadlag brushes whereby each pair of lead-lag brushes for any coded bit is coupled to the normally open and normally closed points associated with a particular movable contact, a transfer relay control circuit coupled to said single set of readout brushes to control the transfer of the readout from said first wheel between said lead and lag readout brushes for a particular angular rotation of said second wheel, a plurality of devices for representing said shaft angular positions in coded form, a plurality of output relays arranged in two groups, each group coupled respectively to a corresponding code wheel, and each assigned a different order of value, each output relay having a pair of movable contacts, each of said movable contacts having an associated normally open point and normally closed point, connecting means associated with each output relay coupling the normally associated open point of one of said movable contacts to the normally associated closed point of the other of said movable contacts, logical circuitry means coupling each of said movable contacts to an associated one of said connecting means of the next higher ordered output relay, and circuitry means coupling said logical circuitry means between said means and both said single and said lead-lag readout means to effect a change of one digit value in said translation output by a single transfer of said movable contacts.

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