



(22) Date de dépôt/Filing Date: 2003/07/18

(41) Mise à la disp. pub./Open to Public Insp.: 2004/02/27

(30) Priorités/Priorities: 2002/08/27 (2002 1461/02) CH;  
2002/10/30 (2002 1825/02) CH

(51) Cl.Int.<sup>7</sup>/Int.Cl.<sup>7</sup> B65B 43/18

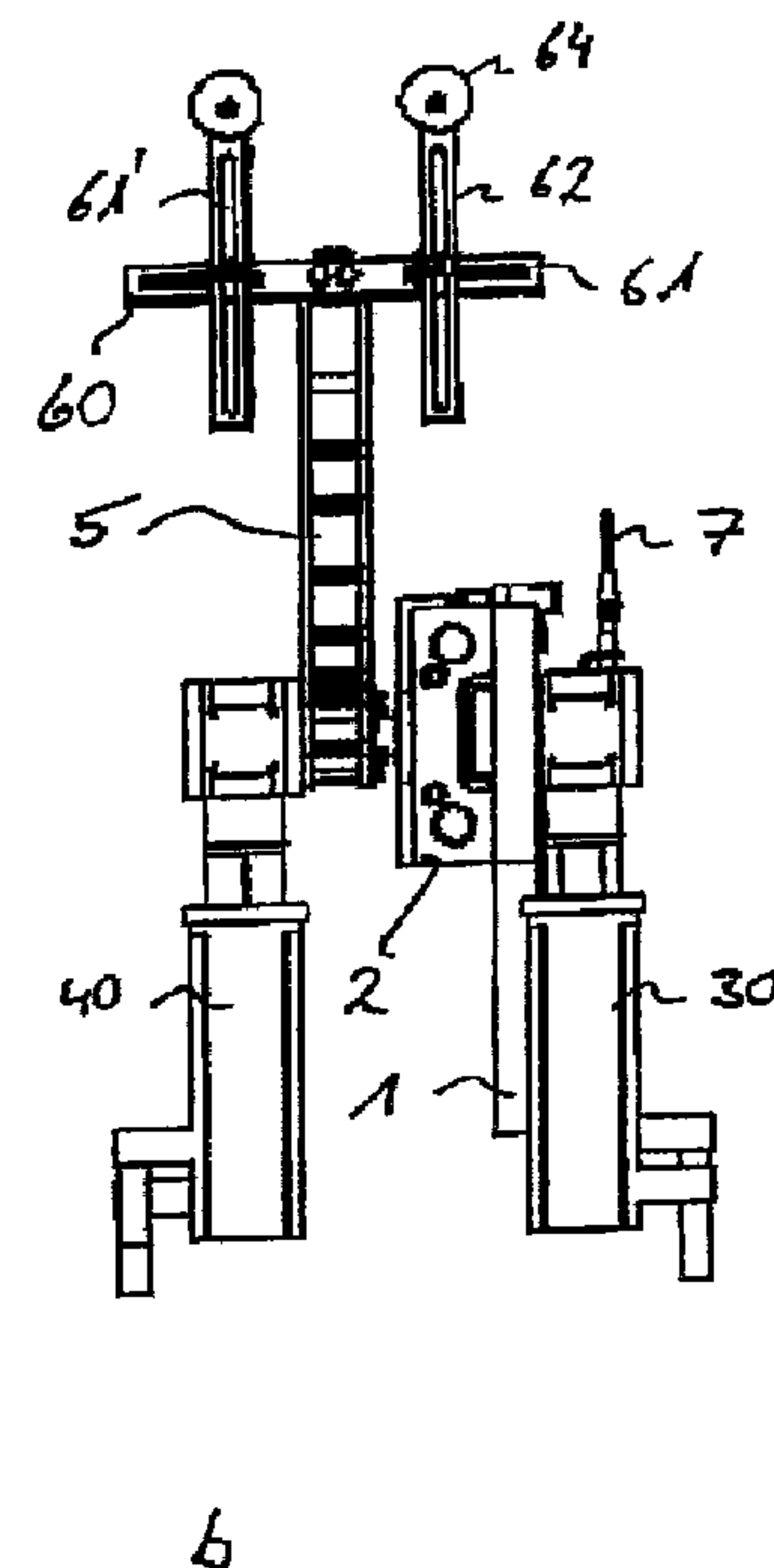
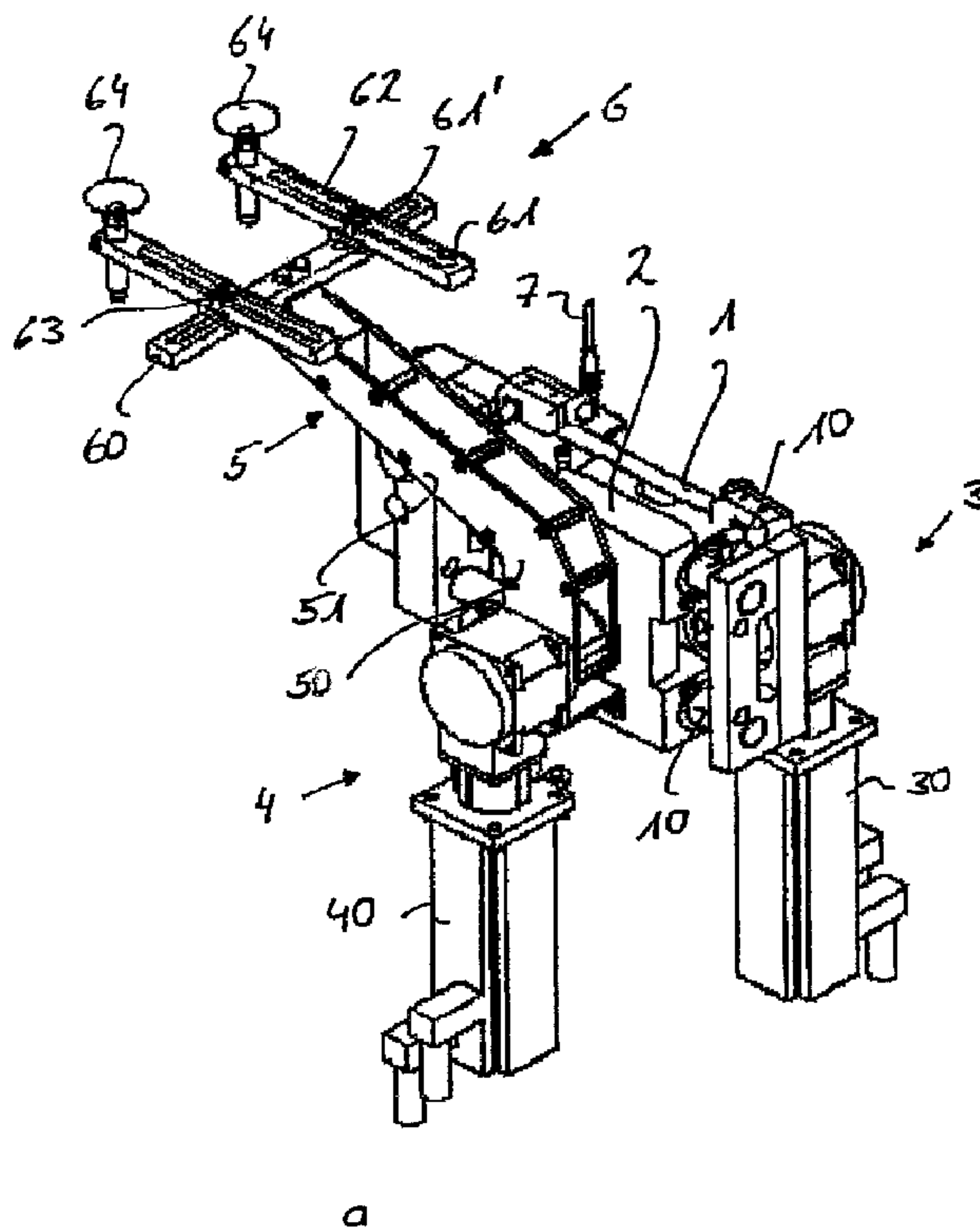
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(54) Titre : DISPOSITIF DE SEPARATION POUR MACHINE A FORMER DES BOITES

(54) Title: SEPARATING ARRANGEMENT FOR A CARTONING MACHINE



(57) Abrégé/Abstract:

A separating arrangement for the individual removal of carton blanks (Z) from a magazine (M) and for shifting the removed carton blank (Z) from a removal position into a transfer position has a motor-driven pivoting arm (5) and means (6) arranged thereon for removing the carton blank (Z) on its own. The pivoting arm (5) is arranged on a carriage (2) which can be displaced in a rectilinear manner, it being the case that, as the carton blank (Z) is removed and shifted, a pivoting movement of the pivoting arm (5) is superposed by a rectilinear movement of the carriage (2). This arrangement thus allows space-saving and efficient shifting of individual carton blanks and, in addition, can be integrated in a flexible manner in cartoning machines.



**Abstract**

A separating arrangement for the individual removal of carton blanks (Z) from a magazine (M) and for shifting the removed carton blank (Z) from a removal position into a transfer position has a motor-driven pivoting arm (5) and means (6) arranged thereon for removing the carton blank (Z) on its own. The pivoting arm (5) is arranged on a carriage (2) which can be displaced in a rectilinear manner, it being the case that, as the carton blank (Z) is removed and shifted, a pivoting movement of the pivoting arm (5) is superposed by a rectilinear movement of the carriage (2). This arrangement thus allows space-saving and efficient shifting of individual carton blanks and, in addition, can be integrated in a flexible manner in cartoning machines.

(Figure 1)

**Separating arrangement for a cartoning machine****Technical Field**

5 The invention relates to a separating arrangement for a cartoning machine, in particular a carton erector.

**Prior Art**

10 A wide range of different cartoning machines for forming boxes from carton blanks are known in the prior art. Use is usually made of so-called carton erectors in which the carton blanks are bent into the desired shape from a horizontal starting position. These  
15 machines essentially comprise a magazine, in which the carton blanks are stacked, a separating arrangement for the removal of individual carton blanks, and an erecting mechanism with a forming ram for forming the blank into the desired box. Conveyors are usually  
20 provided upstream and downstream of the erecting mechanism in order to convey the carton blank into the erecting mechanism and to convey the finished box out of the erecting mechanism.

25 The carton blanks are located either more or less horizontally or more or less vertically in the magazine stack. In the latter case, they each have to be pivoted through 90° into a horizontal position by means of the separating arrangement before they can be transferred  
30 to the erecting mechanism. Since the amount of time required for transferring the carton blanks from the magazine to the erecting mechanism has a significant influence on the output capacity of the machine as a whole, this shifting operation should be as  
35 straightforward as possible but, nevertheless, should allow shifting which is as precise as possible.

EP-A-1,184,161 thus discloses a machine which is intended for erecting boxes from carton blanks and of

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which the separating arrangement has a rotatable, two-part arm. The axis of rotation of the arm is located beneath the transporting path, with the result that it does not collide with other machine components.

5 The two parts of the arm are connected to one another in an articulated manner and can be pivoted in relation to one another by means of a controlled drive. The free arm part is provided with vacuum suckers and only serves for withdrawing the carton blank from the stack,

10 that is to say for separating purposes. The second arm part only serves for transferring the blank into a horizontal position. In this position, the vacuum suckers release the carton blank, with the result that the latter can be deposited on a conveying path leading

15 to the erecting mechanism. The endless circular operation of the separating arrangement does indeed reduce the amount of time required for shifting the carton blanks. The arrangement, however, has the disadvantage that, as before, a relatively large amount

20 of space is required for separating and transfer purposes. In addition, the separating arrangement is of non-flexible configuration, with the result that the following conveying path has to be adapted in order to allow the arrangement to be integrated in the machine

25 as a whole.

EP-A-0,825,111 discloses a machine which is intended for erecting boxes and in the case of which the separating arrangement likewise has a multi-part arm. A

30 bottom arm part moves up and down along a curved path. In addition, it is connected via a strut, which can be changed in length, to a top, pivotable arm which is provided with vacuum suckers, in order to remove a carton blank from the magazine stack and pivot it into

35 a horizontal position.

Furthermore, EP-A-0,761,535 discloses a packaging machine for erecting, filling and closing cartons. In this case, either straightforward carton blanks or

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carton blanks which have already been adhesively bonded, but are folded flat, are transported into a filling station by way of a removal arrangement. In first embodiments, the removal arrangement has a two-armed removal framework which is provided with a vacuum sucker and is fastened on a carrying arm. The carrying arm is mounted such that it can be pivoted through approximately 90° in a carriage which can be displaced in the horizontal direction, and serves for conveying the already shifted blank to the filling station. The pivoting arm is thus pivoted in the first instance, and only then does the displacement of the carriage take place. In the other embodiments, the removal framework, for shifting purposes, is moved up and down rather than being pivoted. These removal arrangements require a relatively large amount of space. Since they additionally transport the blanks to the filling station, the output capacity of the packaging machine is seriously limited.

20

### **Description of the Invention**

It is an object of the invention to provide a separating arrangement for a cartoning machine, in particular a carton erector, which is of space-saving design, can be integrated in a flexible manner in the cartoning machine and allows efficient shifting of carton blanks.

30 This object is achieved by an arrangement having the features of patent claim 1.

The separating arrangement according to the invention serves for the individual removal of carton blanks from a magazine and for shifting the removed carton blank from a removal position into a transfer position. The arrangement has a motor-driven pivoting arm and means arranged thereon for removing the carton blank on its own, and is defined in that the pivoting arm is

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arranged on a carriage which can be displaced in a  
rectilinear manner, it being the case that, as the  
carton blank is removed and shifted, a pivoting  
movement of the pivoting arm is superposed by a  
5 rectilinear movement of the carriage.

The arrangement according to the invention thus  
simultaneously combines a pivoting movement with a  
translatory movement. The act of removing and shifting  
10 an individual carton blank is a flowing movement in the  
case of which the pivoting arm is rotated through the  
desired angle and simultaneously pushed back and forth.  
It is thus possible for its position in relation to the  
remaining stack to be adjusted in each case such that  
15 that edge of the removed carton blank which is located  
closest to the stack is always as close as possible to  
the top surface of the stack. In addition, the shifting  
movement, that is to say the pivoting movement, may be  
started just after the removal. The act of shifting the  
20 carton blank from its vertical position into a  
horizontal position can thus be realized within a  
minimal amount of space, since it can move over an  
optimized three-dimensional curve. The separating  
installation may thus be of space-saving and compact  
25 design. In addition, the amount of time required for  
removal and shifting purposes is also minimized.

The path of the carriage may be any desired length,  
with the result that, following rotation of the arm,  
30 the carriage can additionally execute a purely  
translatory movement in order to bring the removed  
carton blank to the desired transfer location. The  
separating arrangement can thus be integrated  
straightforwardly in cartoning machines.

35

Superposing a pivoting movement with a translatory  
movement, in addition, has the advantage that this is  
easy to realize in control terms.

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In a preferred embodiment, the pivoting arm is of rigid, in particular angled, design. This simplifies the activation and additionally reduces the production costs.

5

In order for the separating arrangement to be flexible in respect of changing the carton-blank shapes, the means arranged on the pivoting arm are preferably arranged such that they can be displaced and fixed in  
10 their respective position.

The means are preferably arranged such that the carton blank is gripped at at least four, preferably precisely four, locations. This allows better destacking and good  
15 guidance when the blank is shifted. The destacking is also, or additionally, improved by the means being resiliently mounted.

Further advantageous embodiments can be gathered from  
20 the dependent patent claims.

#### **Brief Description of the Drawing**

The subject matter of the invention is explained  
25 hereinbelow with reference to preferred exemplary embodiments which are illustrated in the attached drawing, in which:

figure 1a shows a perspective illustration of a first  
30 embodiment of the separating arrangement according to the invention;

figure 1b shows a front view of the arrangement according to figure 1a;

figure 2a shows a side view of the arrangement  
35 according to figure 1a in a first position;

figure 2b shows the arrangement according to figure 1a in a second position;

figure 2c shows the arrangement according to figure 1a in a third position;

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figure 2d shows different positions superposed;  
figure 3a shows a perspective illustration of a second  
embodiment of the separating arrangement  
according to the invention;  
5 figure 3b shows the arrangement according to figure 3a  
from above;  
figure 4 shows a perspective illustration of a third  
embodiment of the separating arrangement  
according to the invention;  
10 figure 5a shows the arrangement according to figure 4  
in a first position;  
figure 5b shows the arrangement according to figure 4  
in a second position;  
figure 5c shows the arrangement according to figure 4  
15 in a third position;  
figure 5d shows the arrangement according to figure 4  
in a fourth position;  
figure 5e shows the arrangement according to figure 4  
in a fifth position; and  
20 figure 6 shows a perspective illustration of a  
preferred embodiment of a vacuum sucker.

#### **Methods of Implementing the Invention**

25 The separating arrangement described hereinbelow is a  
constituent part of a cartoning machine, in particular  
of a carton erector and/or lidder. Such cartoning  
machines are known in the prior art and are thus not  
described in detail hereinbelow. As mentioned in the  
30 introduction, they essentially comprise a magazine with  
a stack of flat carton blanks, a separating  
arrangement, an erecting mechanism and at least one  
conveyor. The separating arrangement is generally  
arranged on a framework of the machine. It is also  
35 possible, however, to provide it with a dedicated  
framework. These frameworks are neither shown nor  
described hereinbelow.

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Figures 1a and 1b illustrate a first embodiment of the separating arrangement according to the invention. It has a carriage frame 1 which can be fastened on the abovementioned framework. The carriage frame 1 has at least one guide rod 10. In this case, there are two guide rods 10. A carriage 2 is mounted such that it can be displaced in a rectilinear manner on said guide rods 10. The carriage 2 is driven by means of a translatory drive unit 3. This drive unit 3 has a first motor 30, of which the drive shaft is connected to a first drive roller 31, preferably a gearwheel. The first motor 30 is preferably a servomotor with an angular drive. A first endless belt 33, preferably a first toothed belt, connects the first drive roller 31 to a first deflecting roller 32, which is likewise preferably a gearwheel. The carriage 2 is firmly connected to the first endless belt 33. Other known kinds of translatory drive for the carriage, however, are also possible.

In this example, the drive shaft of the first motor 30 runs perpendicularly to the displacement direction of the carriage 2, that is to say the carriage 2 moves back and forth at least more or less horizontally and the drive shaft runs vertically. The basic position of the carriage 2 is detected by means of a sensor 7.

A motor-driven pivoting arm 5 is arranged on the carriage 2. The pivoting arm 5 is driven by means of a rotary drive unit 4, which is likewise fastened on the carriage 2. This unit 4 has a second motor 40, preferably likewise a servomotor with angular drive. In the example illustrated here, the drive shaft of the second motor 40 runs in the vertical direction and the pivoting arm 5 is connected to a horizontally running deflecting spindle. The two motors 30, 40 are connected to a control means S of the cartoning machine. If the cartoning machine is operated cyclically, then the drives of the pivoting arm 5 and of the carriage 2 are

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also operated cyclically, preferably in time with the rest of the machine and/or of the erecting mechanism.

The pivoting arm 5 is preferably of rigid design and of angled form. The arm 5 here has two legs of different length, the first, shorter leg 50 being connected to the drive. The second, longer and free leg 51 projects beyond the carriage 2 and is provided with means for removing carton blanks. For this purpose, use may be made of all means which are suitable for gripping and for securing the carton blank as it is shifted. Use is preferably made, however, of vacuum suckers connected to a negative-pressure source. In this example, the abovementioned means thus comprise a sucker mount 6 and at least one vacuum sucker 64. In order for it to be possible to adapt the position of the at least one vacuum sucker 64, in particular in accordance with the type of cartoning machine and the shape of the carton blanks, the sucker mount 6 has a carrier bar 60 and at least one sucker strip 62. In this case, there are two sucker strips 62, each having at least one, in this case precisely one, suction cup 64. The carrier bar 60 is fixed to the free end of the pivoting arm 5 such that it runs transversely to the longitudinal direction of the latter. The sucker strips 62 are arranged on the carrier bar 60 such that they run parallel to the longitudinal direction of the pivoting arm 5, it being possible for them to be displaced, within displacement grooves 61, 61', in two perpendicular directions and to be fixed in their respective position by a fastening means 63, preferably by a screw connection.

Figures 2a to 2d show the arrangement according to the invention in operation. M designates a magazine with carton blanks stacked therein. Z designates the uppermost carton blank just removed from the stack. The stacked carton blanks run at least more or less vertically or, as is illustrated here, are inclined in the direction of the arrangement at a small angle in

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relation to the vertical and, as they are shifted, are brought into an at least more or less horizontal position.

5 As can be seen in figure 2a, the pivoting arm 5 is pivoted up and the suction cups 64 are brought into abutment against the foremost carton blank Z, in order to remove this carton blank Z. The carriage 2 is then moved a short distance away from the top surface of the  
10 stack in order to withdraw the carton blank Z, as is illustrated in figure 2a. Immediately following this withdrawal movement, the arm 5 starts to pivot. During the subsequent pivoting movement, the carriage 2 is moved again in the direction of the top surface of the  
15 stack, as can be seen in figure 2b. It can be seen in figure 2c that the carriage 2 moves ever closer to the top surface of the stack the more the arm 5 shifts the carton blank Z and the latter approaches the at least more or less horizontal transfer position. In the  
20 transfer position, the carton blank Z is usually deposited on a conveyor, and by virtue of the pressure being raised, released from the vacuum sucker. In figure 2d, the movement sequence has been frozen in individual positions, which are illustrated in  
25 superposed form. It can be seen that the pivoting movement of the pivoting arm 5 and the rectilinear movement of the carriage 2 are superposed, the carriage 2 first of all being moved away from the stack and then being moved toward it. In this case, the lowermost edge  
30 K of the carton blank Z is always located as closely as possible to the top surface of the stack. It is worth noting that, for this specific and space-saving shifting operation, no vertical translatory displacement of the pivoting arm 5 is necessary. If the  
35 transfer location is located further away, for example on a conveyor, then the carriage 2 can subsequently be displaced by the desired distance without any pivoting movement of the arm 5.

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Figures 3a and 3b illustrate a second exemplary embodiment. This is constructed in essentially the same way as the first example. The same parts have thus been provided with the same designations and will not be described in detail here. The significant difference is that, in this case, the motors 30, 40 are oriented horizontally. Deflection is no longer required for the carriage drive. The drive roller 31 may be connected directly to the motor shaft. In contrast, the rotary drive unit 4 here has a second drive roller 41, which is connected to the motor shaft of the second motor 40, a second deflecting roller 42 and a second endless belt 43, which connects the two rollers. Here too, use is preferably made of a toothed-belt drive. The two rollers 41, 42 are mounted in the carriage 2. In both exemplary embodiments, the second motor 40 is moved along with the carriage 2.

It is also possible, however, to have embodiments in which the rotary drive unit is arranged separately from the carriage and is not displaced along therewith.

It is preferred for the carton blanks to be oriented at least more or less vertically and to be shifted into an at least more or less horizontal position. Other arrangements, however, are also possible. For example, the pivoting arm 5 may also be pivoted through an angle which is greater than or less than the angle of 90° shown here. The displacement direction of the carriage 2 is also selected in accordance with the arrangement of the stack and the desired orientation of the transfer position. It is thus also possible for it to run along a slanting plane or to run vertically. In the case of a horizontal transfer position, the axis of rotation is preferably located at a lower level than this position, with the result that it does not collide with other machine components and the pivoting angle is minimized. In a different location of the transfer position, the axis is arranged analogously.

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Furthermore, in order to reduce mass and/or specifically to increase rigidity, it is possible to use moving parts for the arrangement which are made of composite materials, e.g. fiber-reinforced plastics or, in particular, carbon-fiber-reinforced plastics.

Figures 4 and 5a to 5e illustrate a third embodiment, which includes parts of the abovementioned variants. For example, the rotary drive unit 4 is arranged in a fixed position and does not move along with the carriage 2. A connecting rod 44 is provided in order to transmit the rotary movement of the drive motor of the rotary drive unit 4 to the pivoting arm 5. It can be seen in figures 5a to 5e that, here too, the carriage 2 is moved transversely in the forward or rearward direction, depending on the destacking position, and that a corresponding pivoting movement of the pivoting arm 5 is superposed. The displacement direction of the carriage 2 is preferably in a slanting plane here, the carriage assuming its highest position adjacent to the magazine M.

In the embodiment which is illustrated in figure 4, at least four, preferably precisely four, vacuum suckers 64 are arranged on the pivoting arm 5. For this purpose, in each case two vacuum suckers 64 are arranged, such that they can be displaced relative to one another, at each end of a sucker strip 62. Using at least four vacuum suckers has the advantage that the carton blanks Z are retained and guided in a reliable manner. Destacking in particular is simplified as a result.

Figure 6 illustrates a preferred embodiment of a vacuum sucker 64. It has a fastening block 65, for releasable fastening on the sucker strip 62, and a suction head 67, which is fastened resiliently thereon via a spring 66. The resilient design of the vacuum sucker 64 simplifies the operation of withdrawing the carton

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blank Z from the stack since it is possible to bridge tolerances in the advancement of the carriage and reliable abutment of all the suction cups against the carton blank Z is ensured.

5

The arrangement according to the invention thus allows space-saving and efficient shifting of individual carbon blanks and, in addition, can be integrated in a flexible manner in cartoning machines.

**List of designations**

|     |                          |
|-----|--------------------------|
| S   | Control means            |
| Z   | Carton blank             |
| K   | Edge                     |
| M   | Magazine                 |
| 1   | Carriage frame           |
| 10  | Guide rod                |
| 2   | Carriage                 |
| 3   | Translatory drive unit   |
| 30  | First motor              |
| 31  | First drive roller       |
| 32  | First deflecting roller  |
| 33  | First endless belt       |
| 4   | Rotary drive unit        |
| 40  | Second motor             |
| 41  | Second drive roller      |
| 42  | Second deflecting roller |
| 43  | Second endless belt      |
| 44  | Connecting rod           |
| 5   | Pivoting arm             |
| 50  | First leg                |
| 51  | Second leg               |
| 6   | Sucker mount             |
| 60  | Carrier bar              |
| 61  | Displacement groove      |
| 61' | Displacement groove      |
| 62  | Sucker strip             |
| 63  | Fixing means             |
| 64  | Vacuum sucker            |
| 65  | Fastening block          |
| 66  | Spring                   |
| 67  | Suction head             |
| 7   | Sensor                   |

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Patent Claims

1. A separating arrangement for a cartoning machine for the individual removal of carton blanks from a magazine and for shifting the removed carton blank from a removal position into a transfer position, the arrangement having a motor-driven pivoting arm and means arranged thereon for removing the carton blank on its own, wherein the pivoting arm is arranged on a carriage which can be displaced in a rectilinear manner, it being the case that, as the carton blank is removed and shifted, a pivoting movement of the pivoting arm is superposed by a rectilinear movement of the carriage.
2. The arrangement as claimed in claim 1, wherein the transfer position is at least more or less horizontal, and wherein the carriage can be displaced back and forth in an at least more or less horizontal direction.
3. The arrangement as claimed in either of claims 1 and 2, wherein the pivoting arm is of rigid, in particular angled, design.
4. The arrangement as claimed in one of claims 1 to 3, wherein the means arranged on the pivoting arm, for removing the carton blank on its own, can be displaced and fixed in relation to the pivoting arm.
5. The arrangement as claimed in claim 4, wherein the means are constituted by a sucker mount with a carrier bar, which is firmly connected to the pivoting arm, and at least one sucker strip, which is arranged such that it can be displaced and fixed on the carrier bar and has in each case at least one vacuum sucker.
6. The arrangement as claimed in claim 5, wherein in each case two sucker strips each with a vacuum sucker are provided.

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7. The arrangement as claimed in one of claims 1 to 5, wherein the pivoting arm can be pivoted by means of a drive, in particular a servomotor, which is arranged on the carriage and preferably has a vertically running drive shaft.

8. The arrangement as claimed in one of claims 1 to 6, wherein the carriage is operated by means of an endless belt, the endless belt being driven by means of a drive with a preferably vertically running drive shaft.

9. The arrangement as claimed in one of claims 1 to 7, wherein a control means is provided, this coordinating the movements of the carriage with the pivoting movements of the pivoting arm.

10. The arrangement as claimed in one of claims 1 to 9, wherein the pivoting arm and the carriage are driven cyclically.

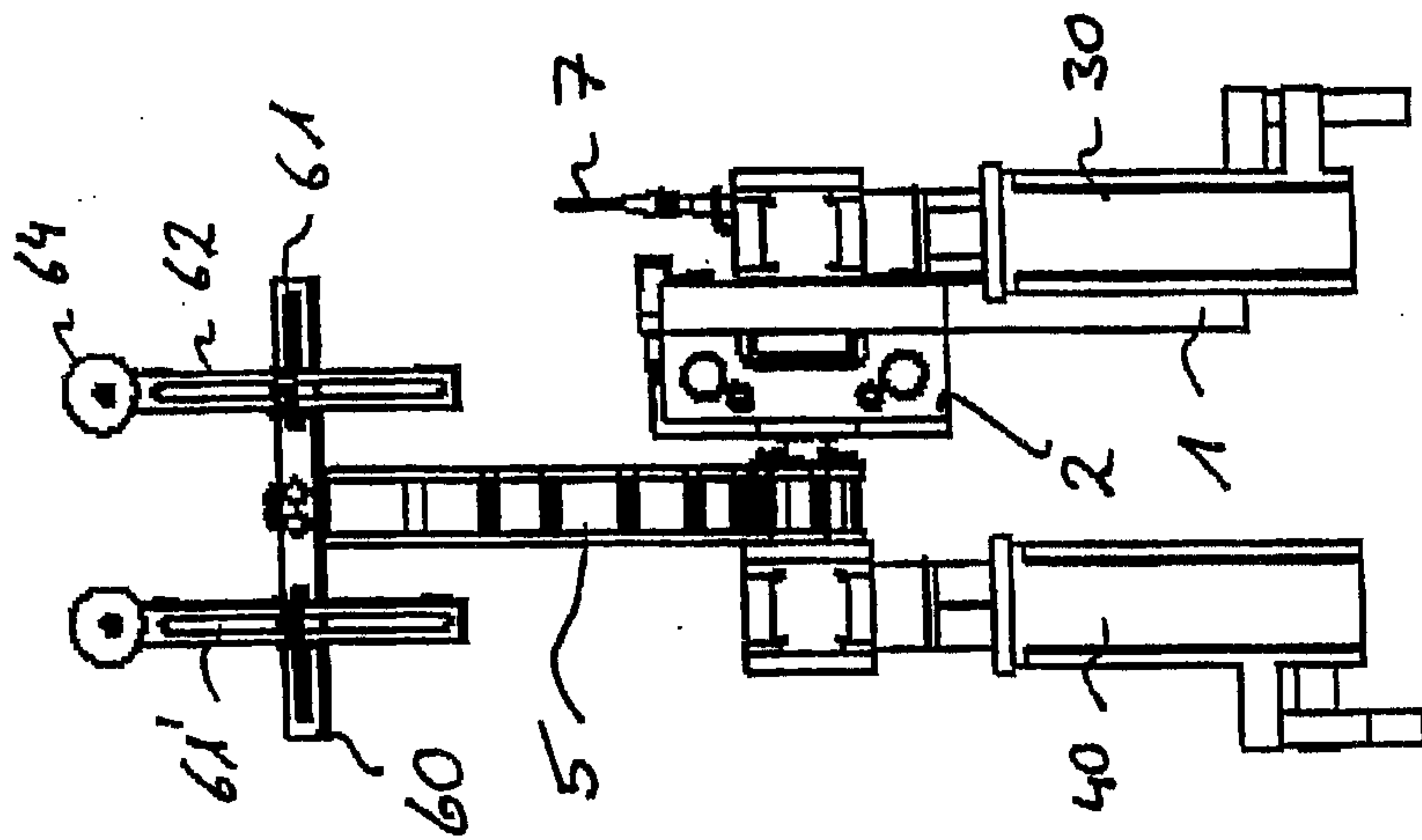


Fig. 1b

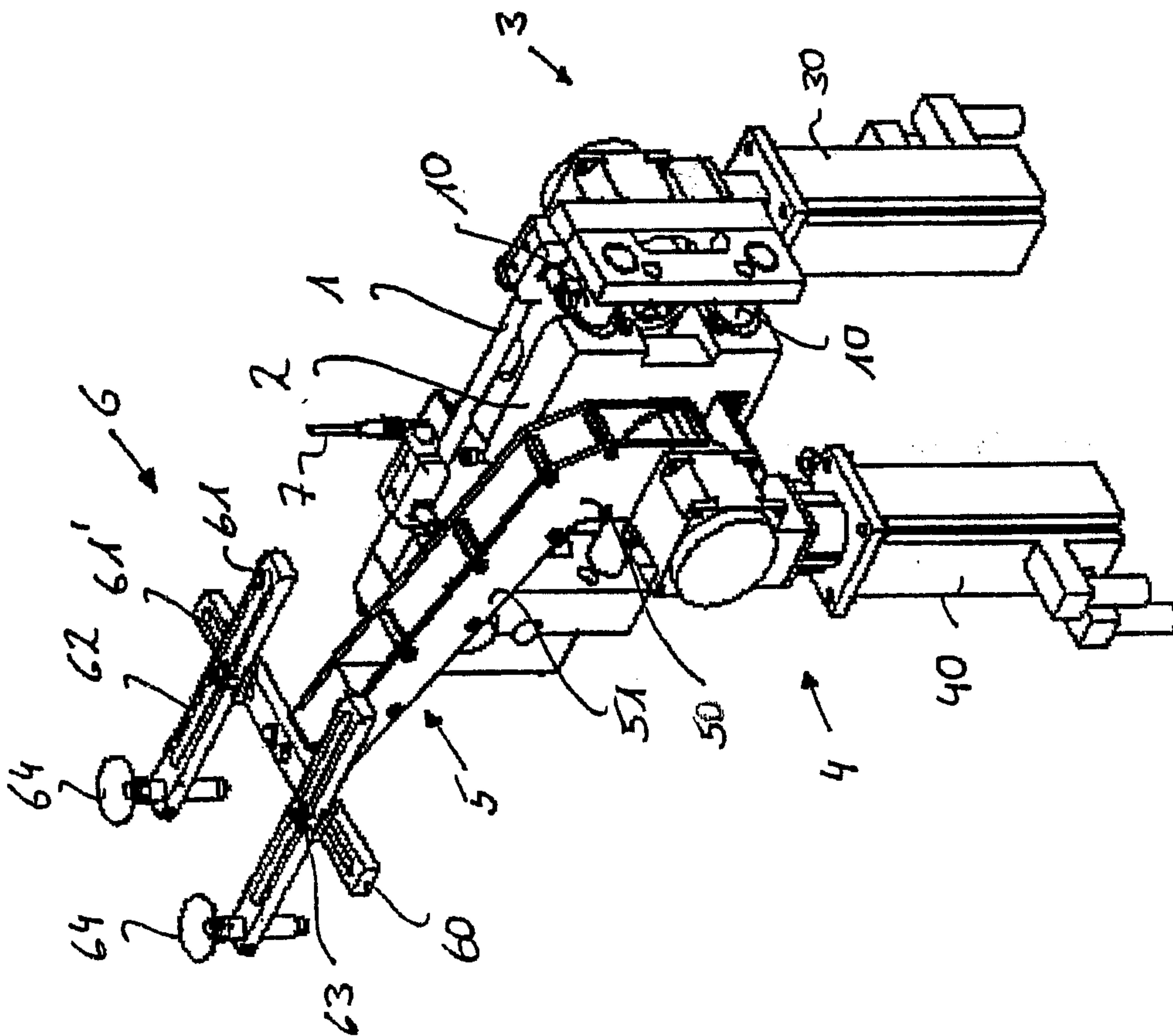


Fig. 1a

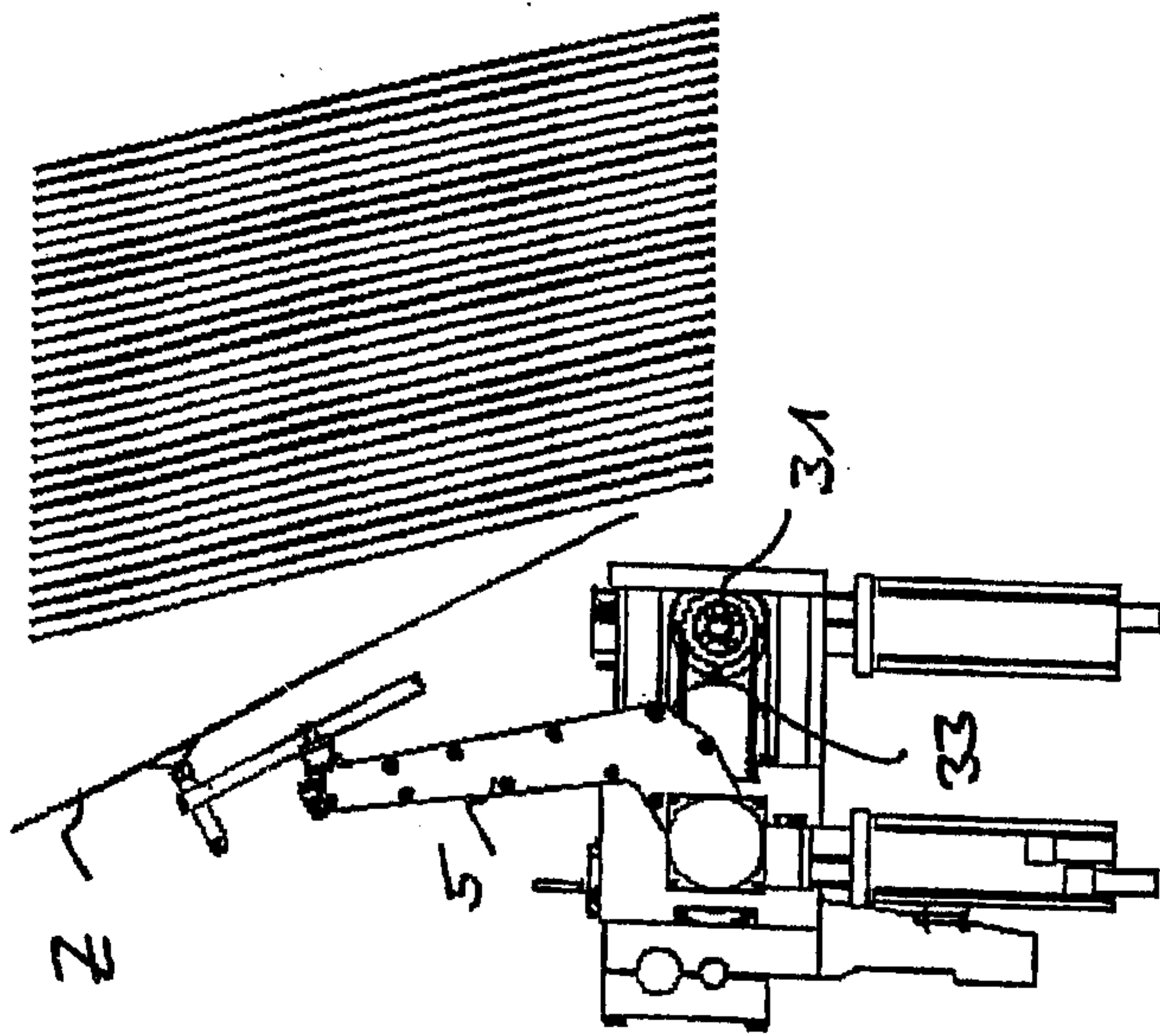


Fig. 26

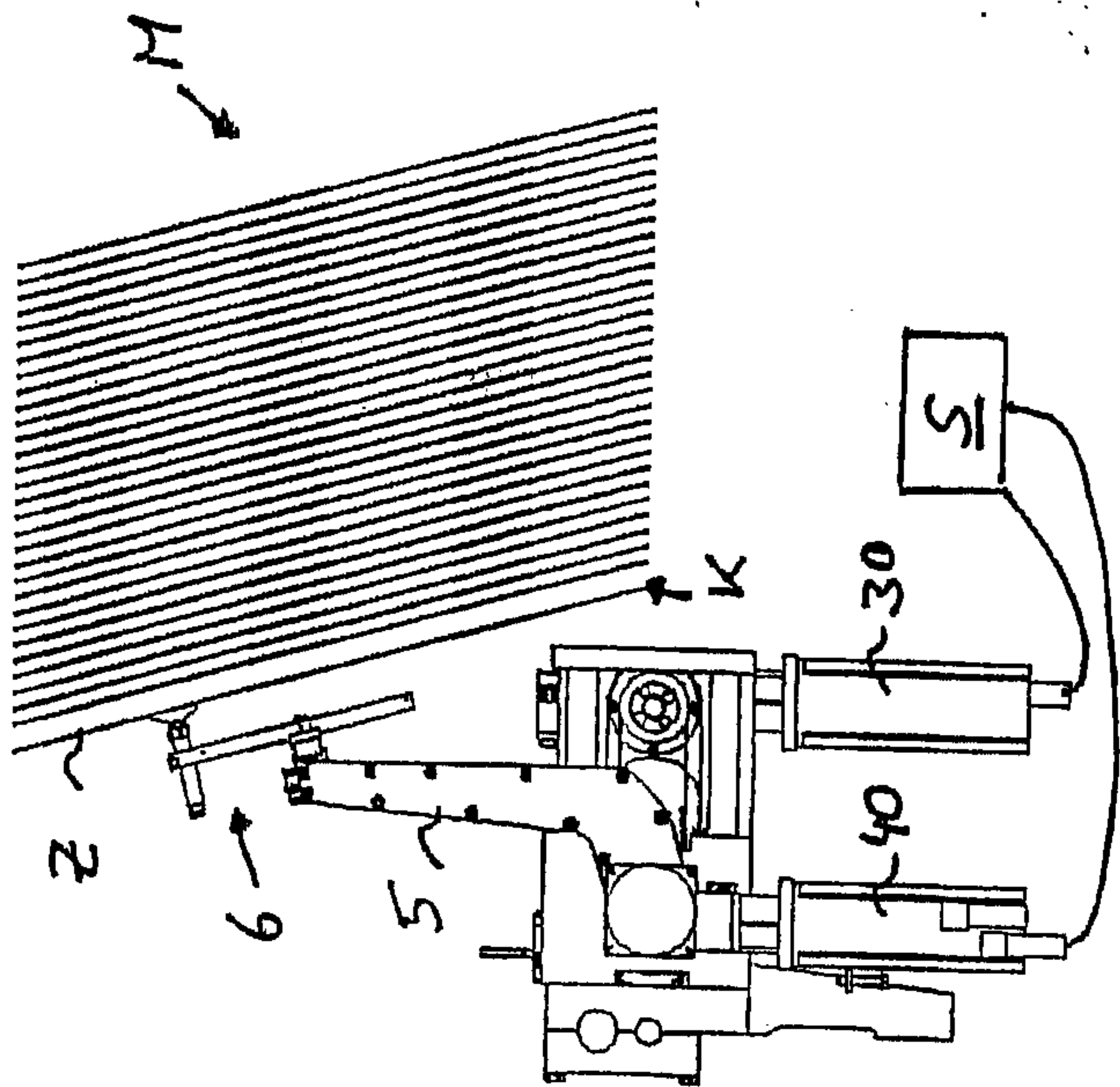


Fig. 2a

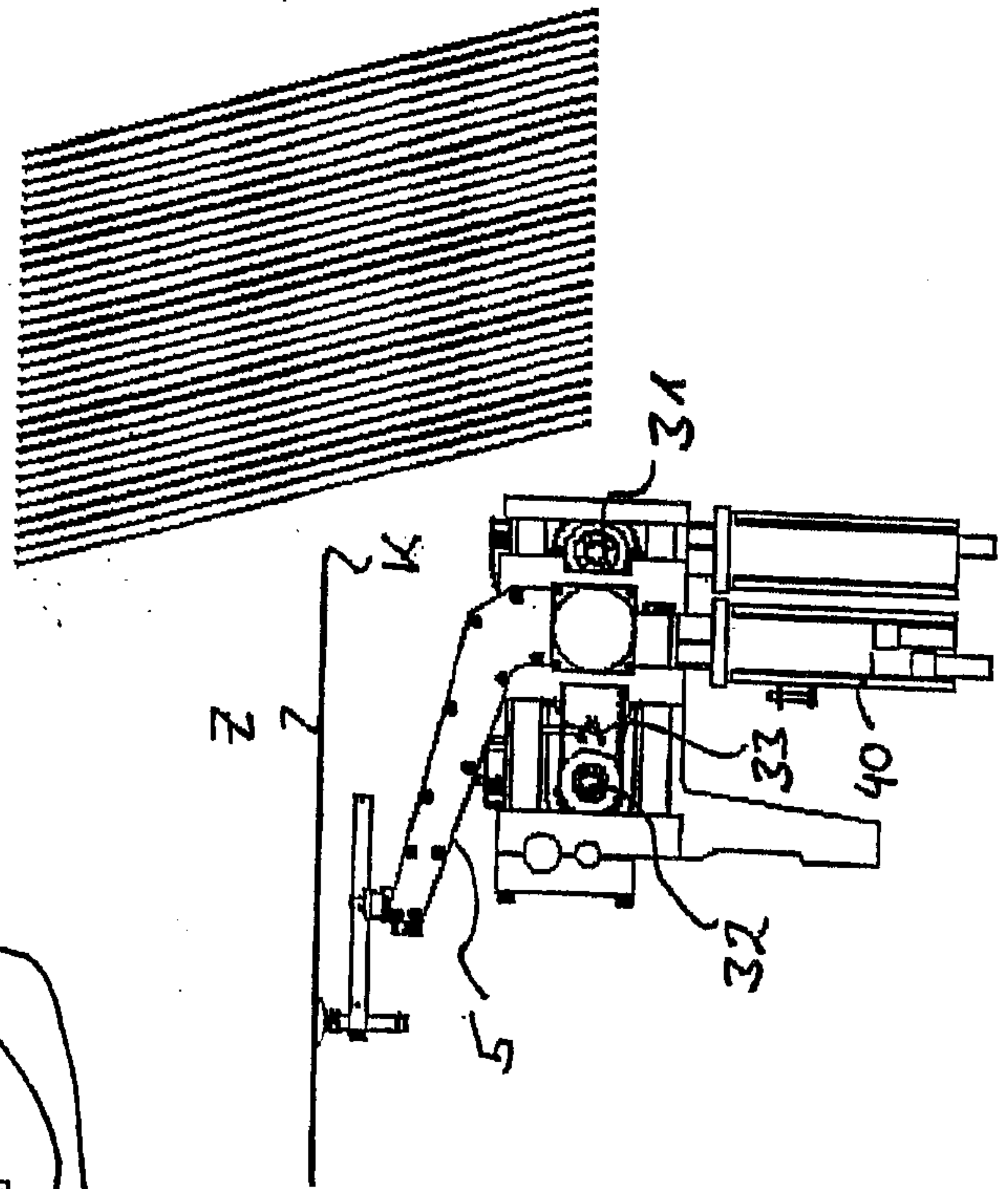
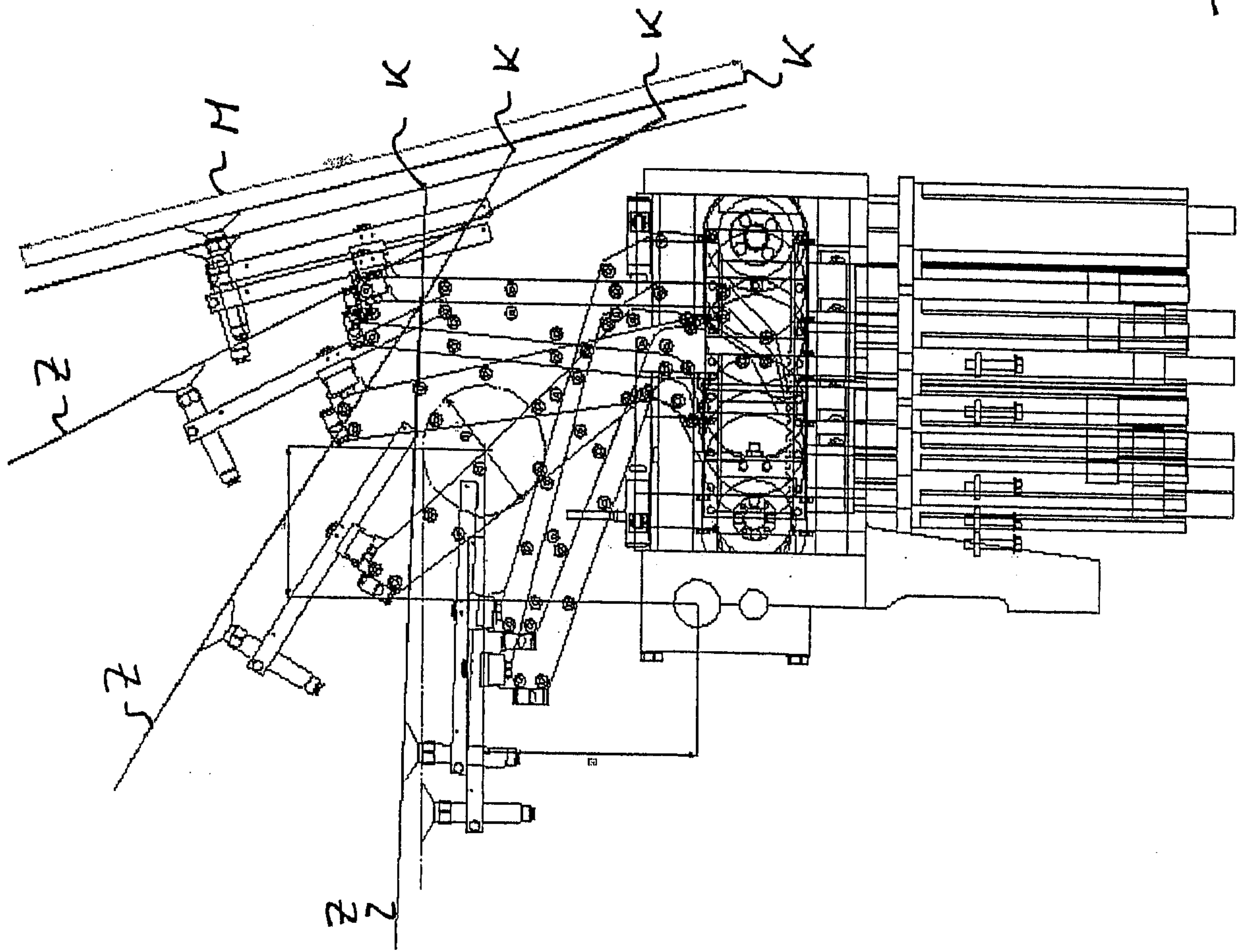


Fig. 2c

fig. 2d



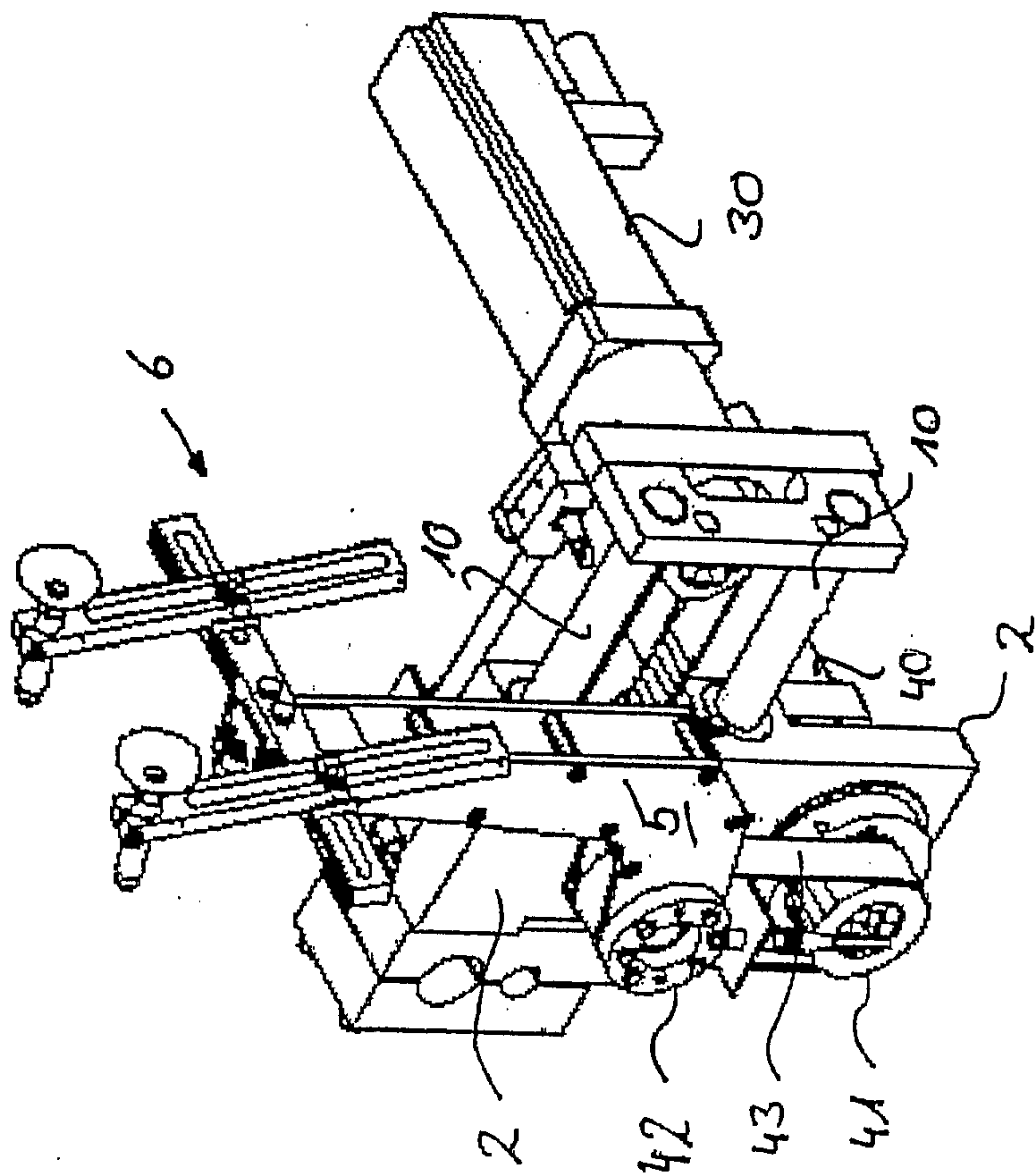
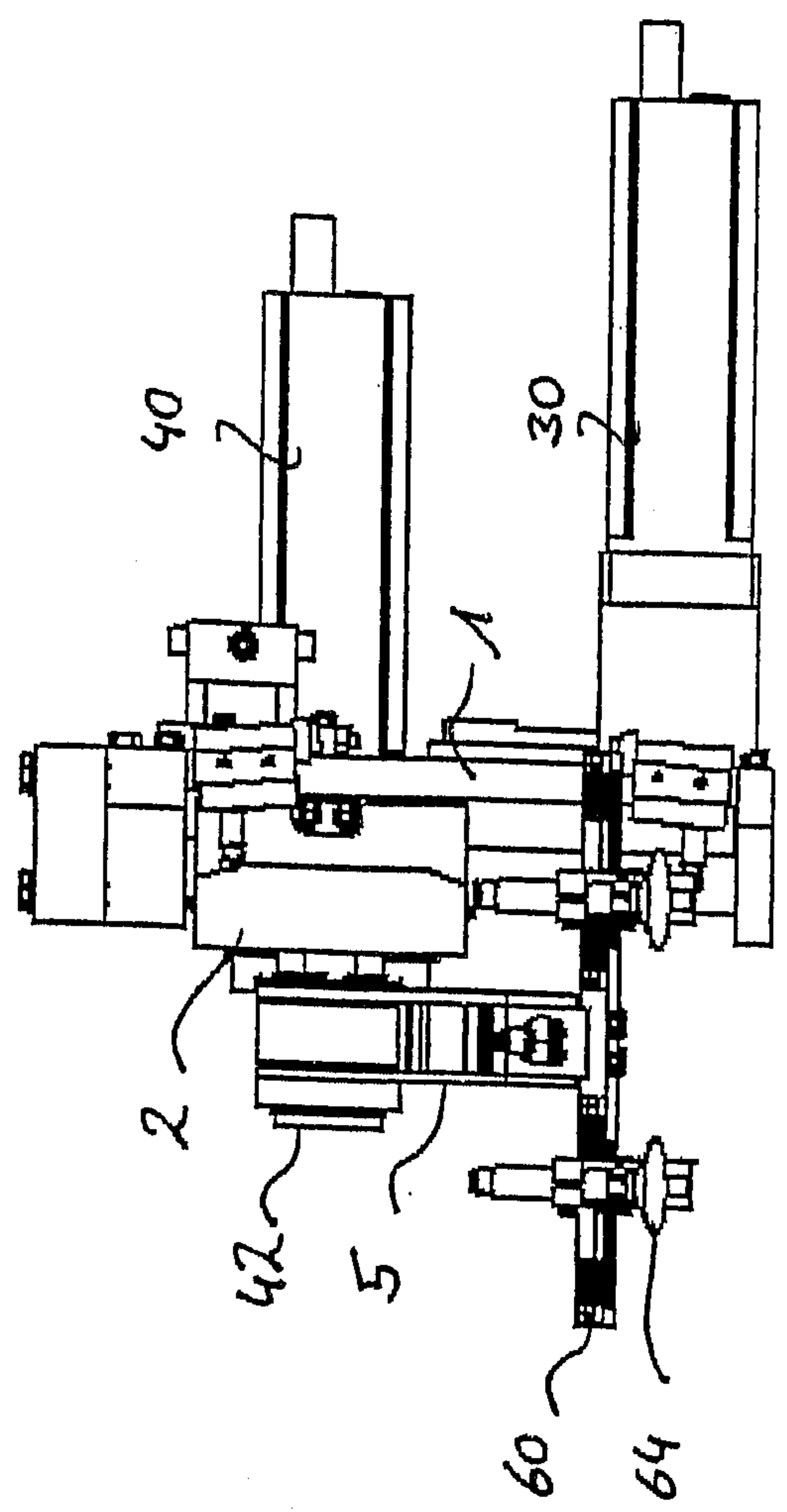


Fig. 3a

Fig. 3b



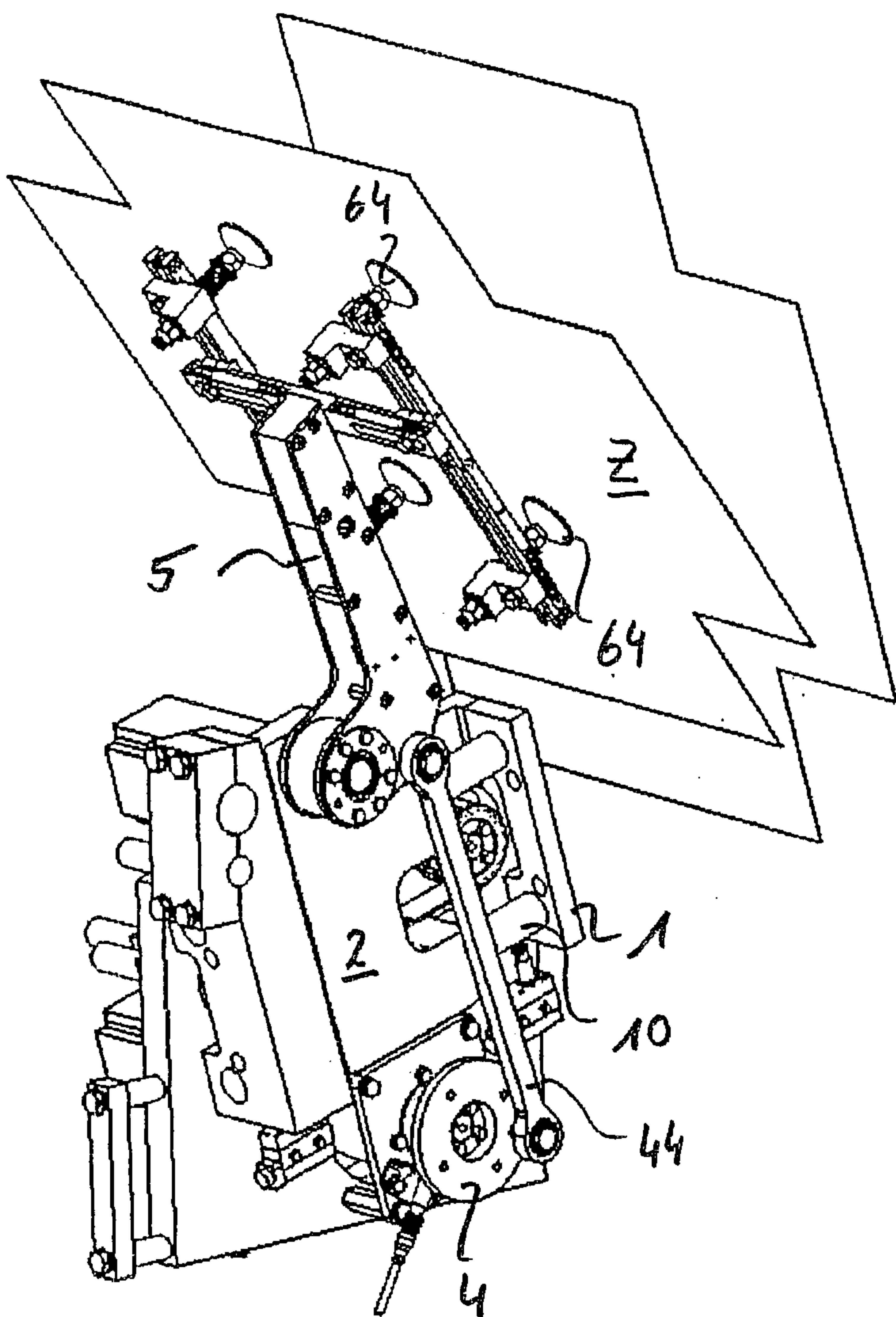


Fig. 4

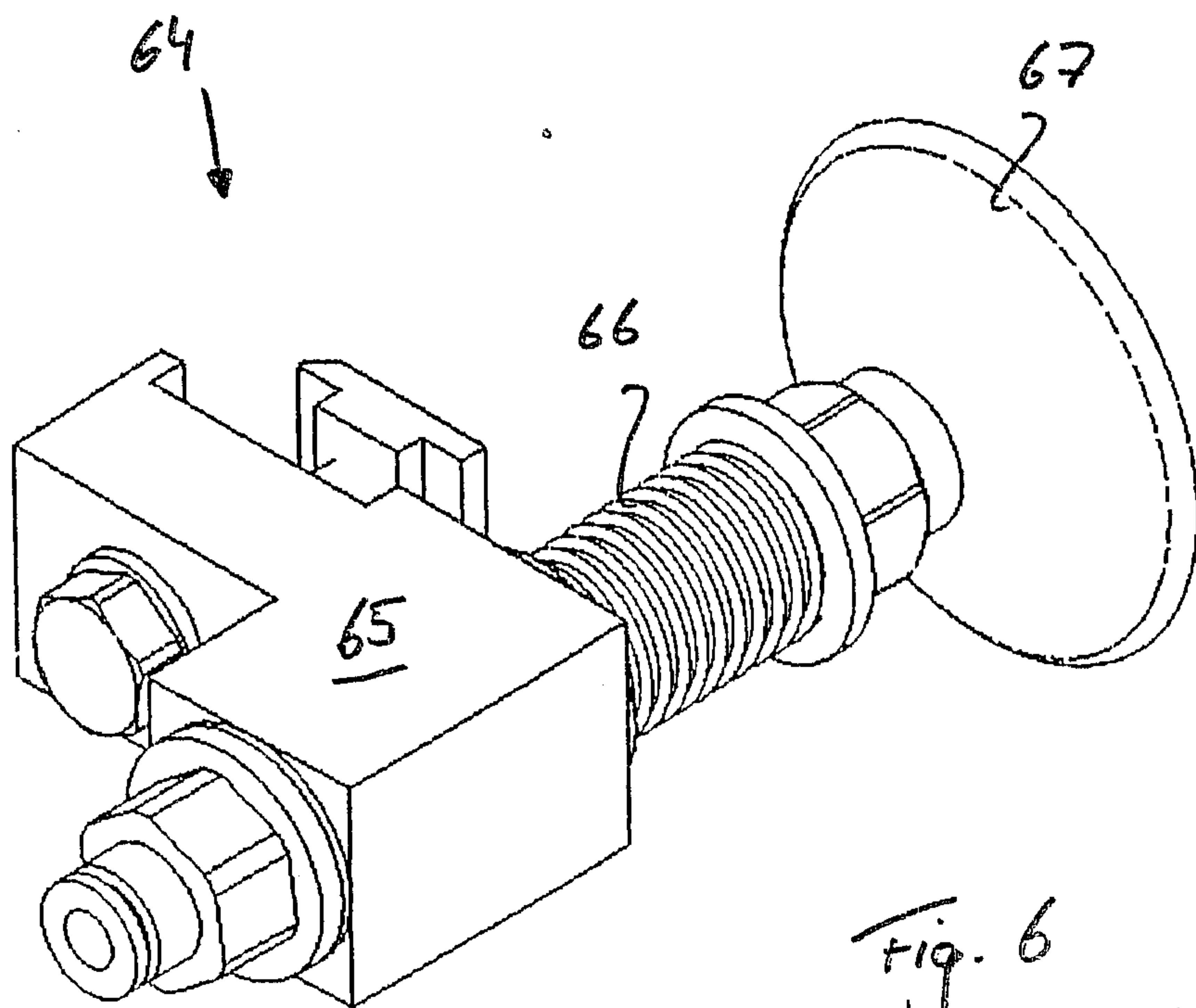


Fig. 6

Fig. 5c

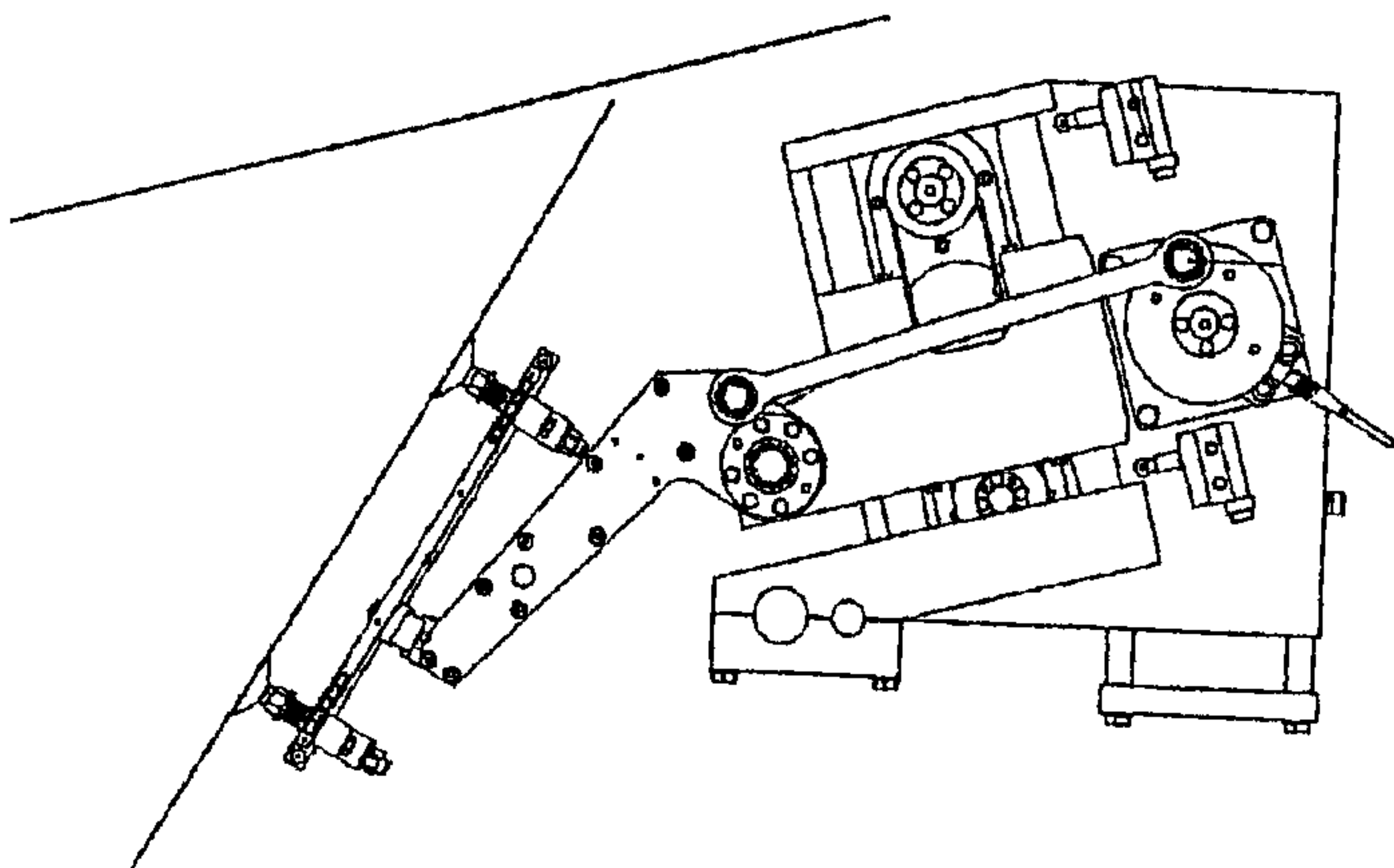


Fig. 5e

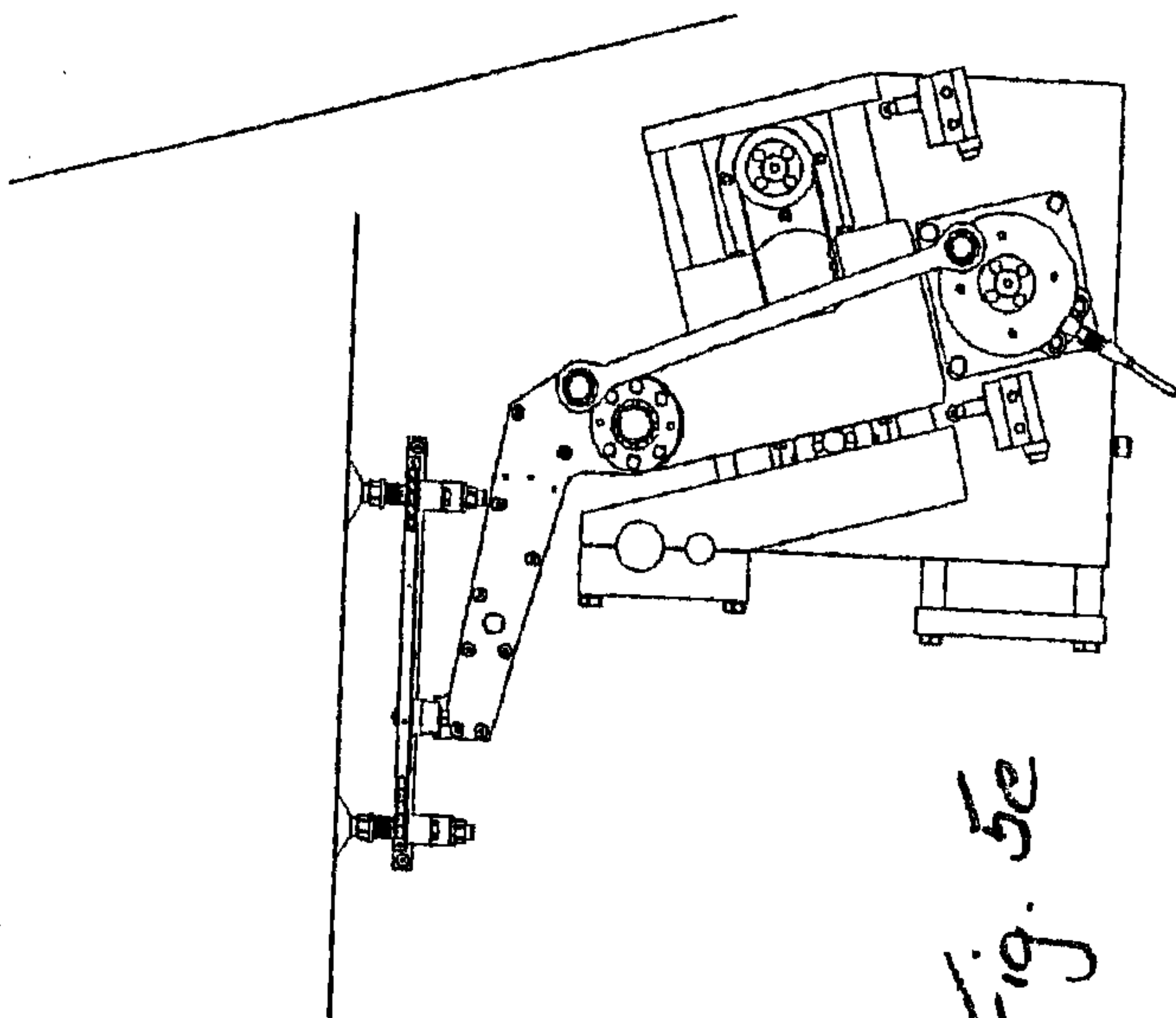


Fig. 5b

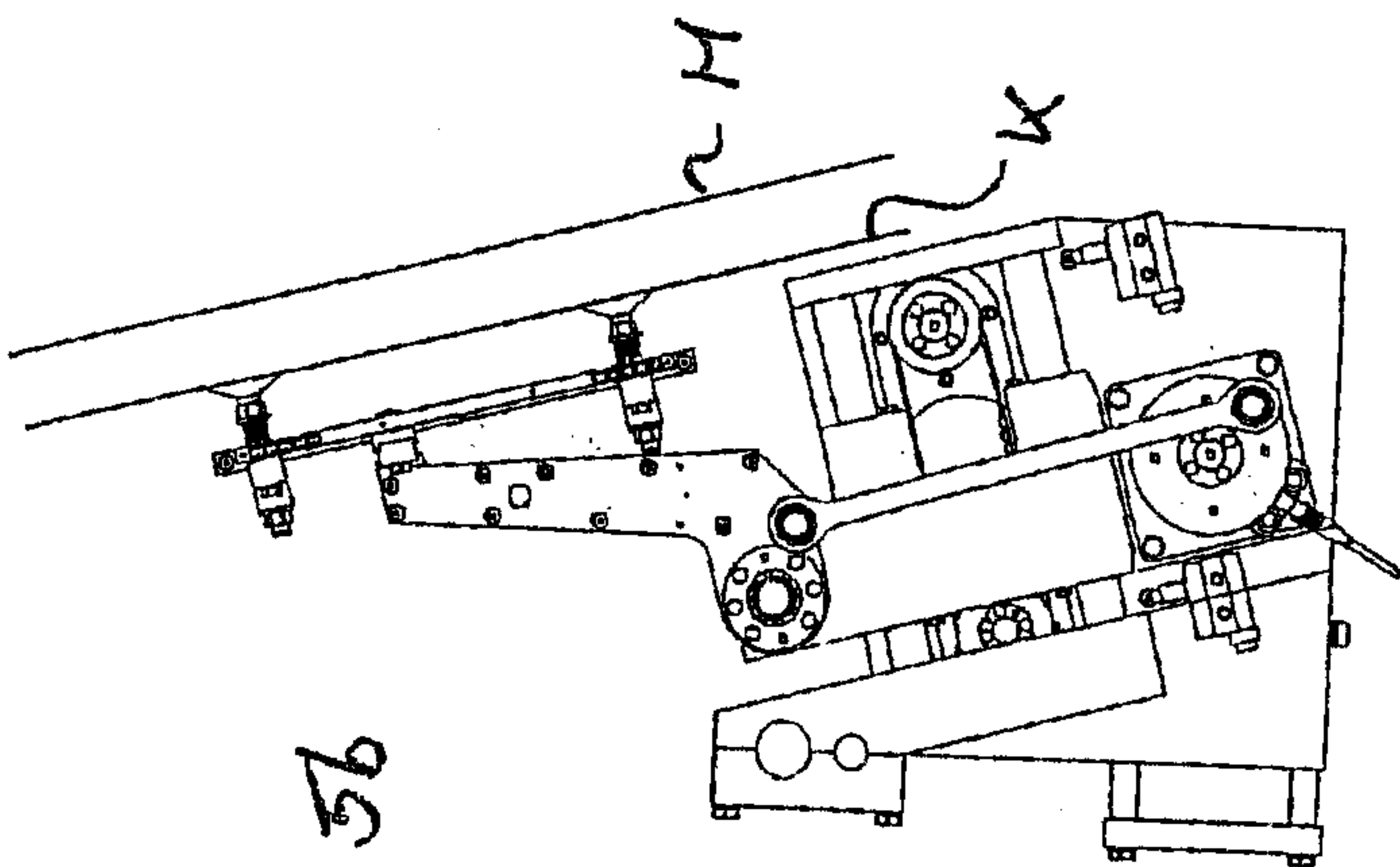


Fig. 5d

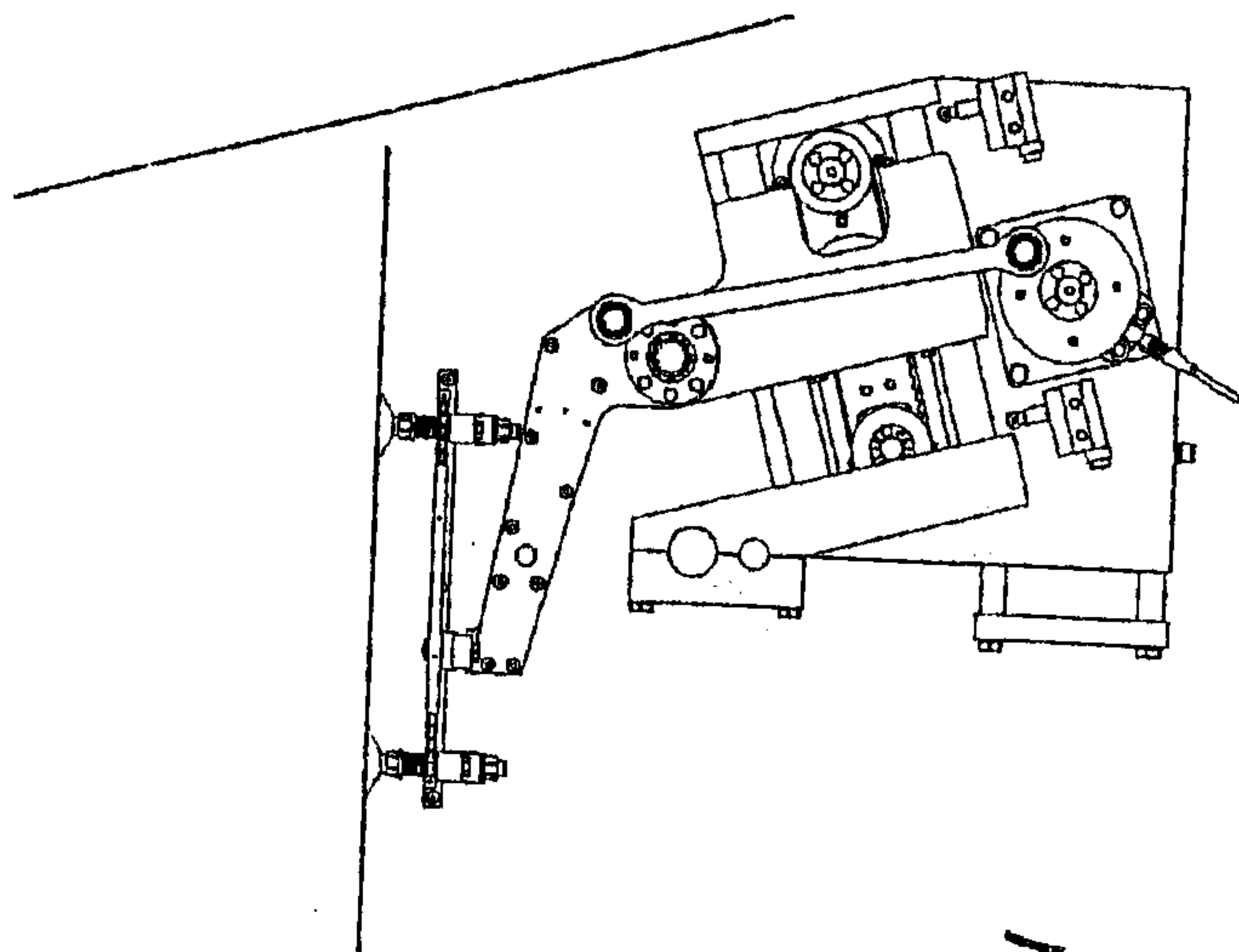
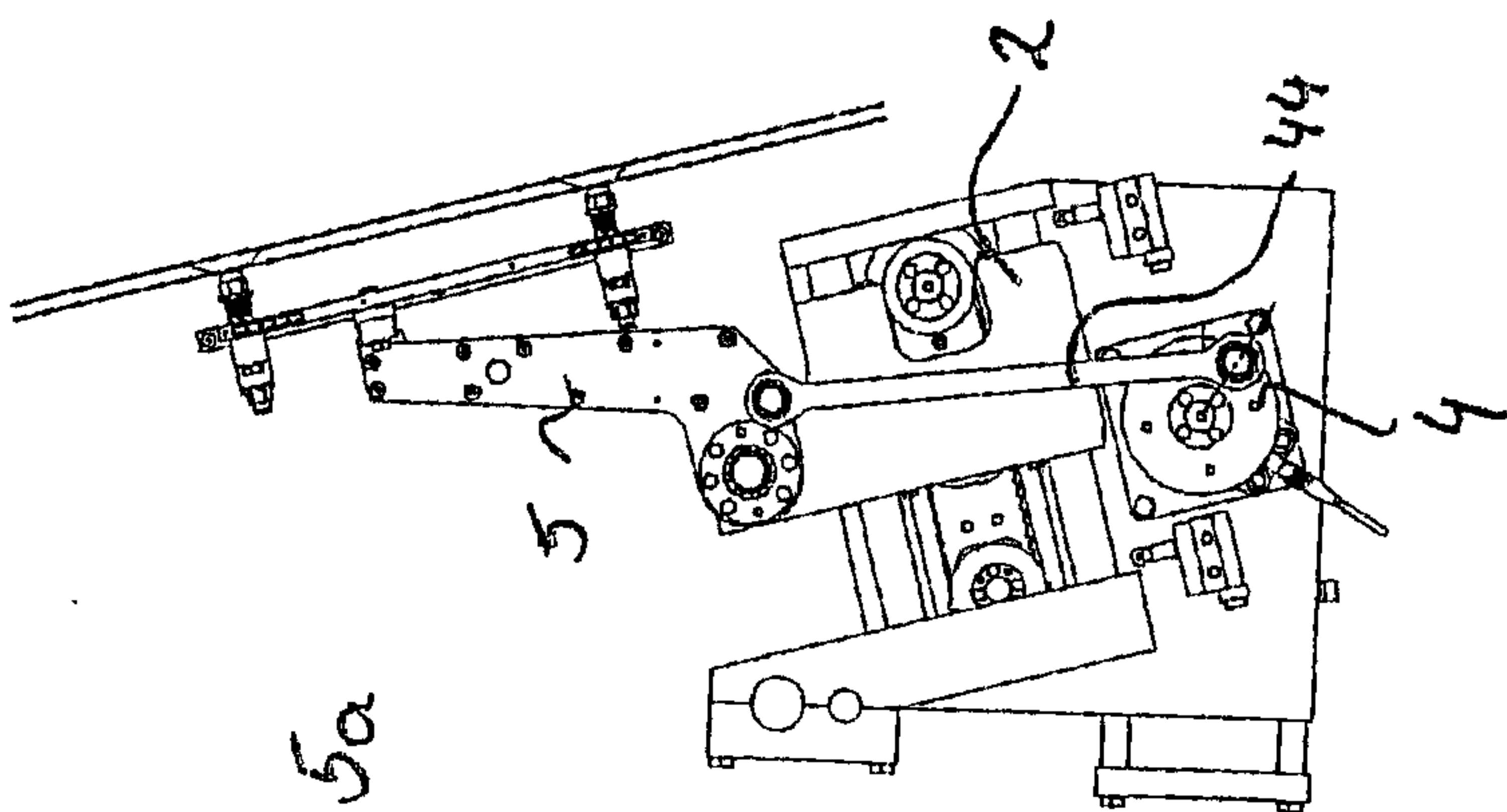
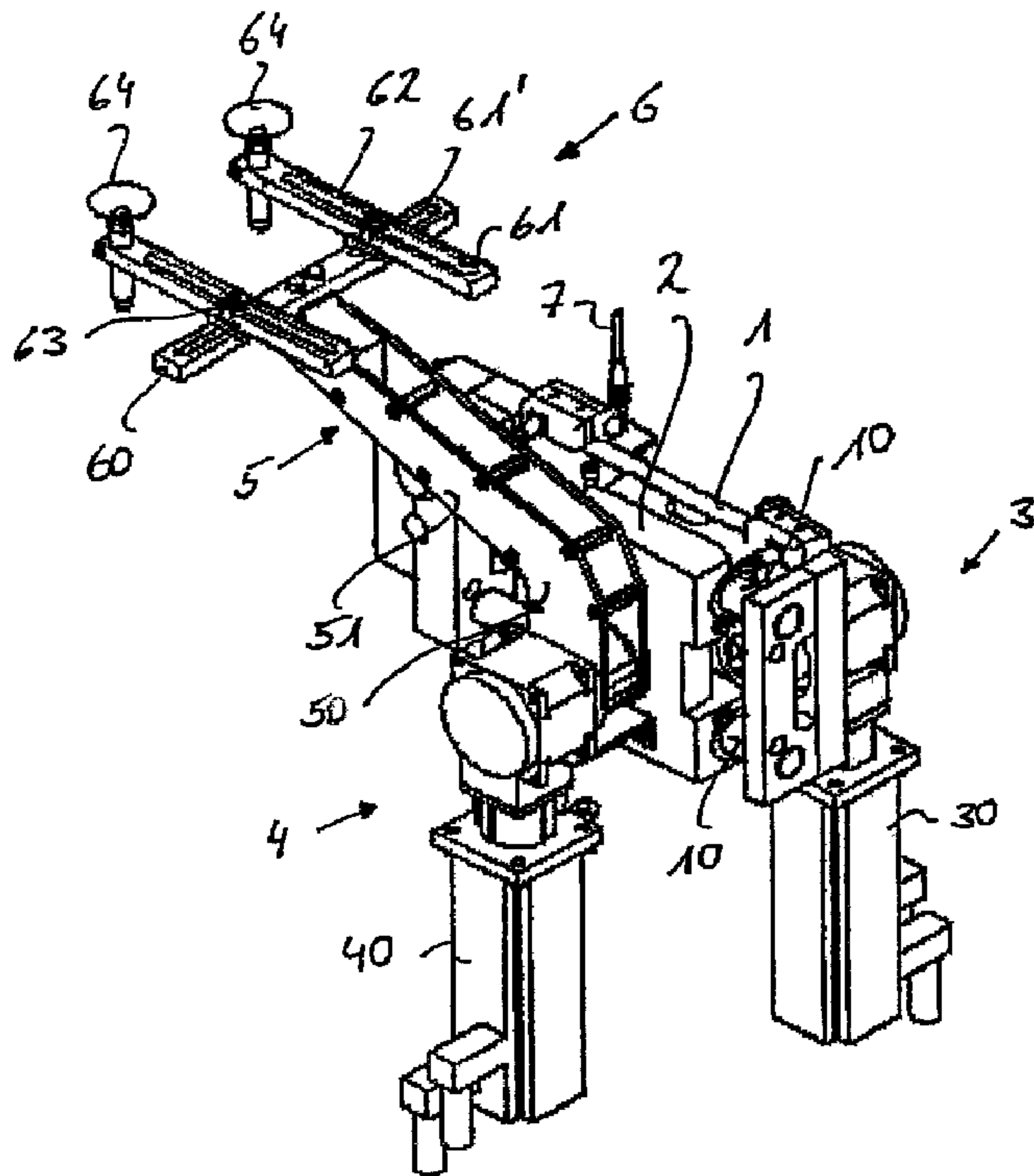
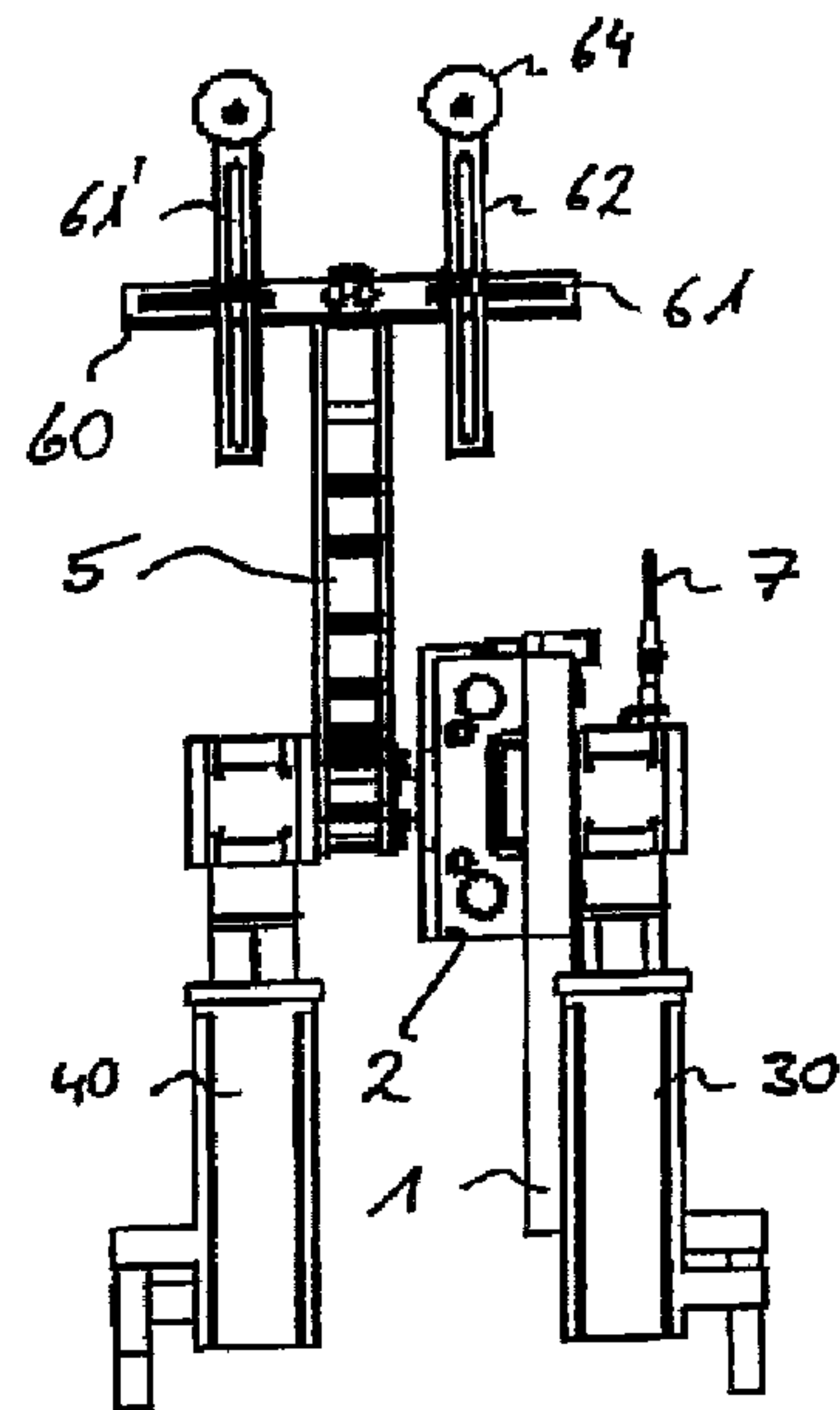


Fig. 5a





a



b