

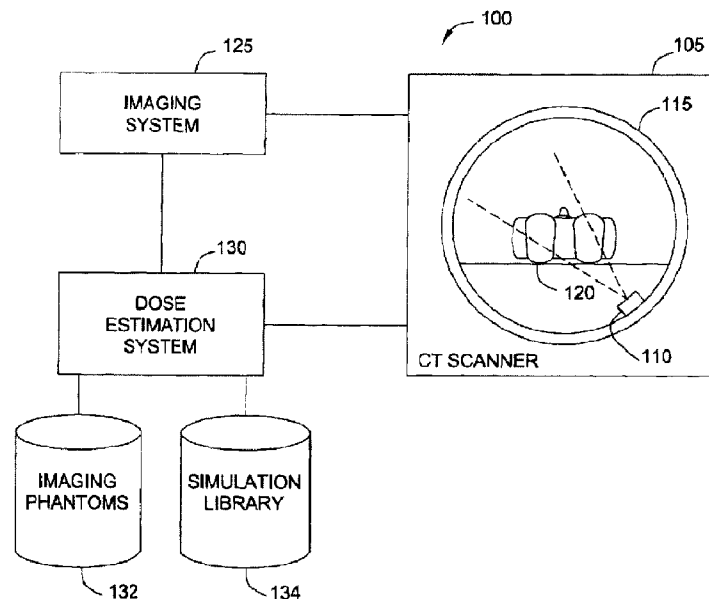


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(54) Titre : GENERATION D'UNE ESTIMATION D'UNE DOSE DE RAYONNEMENT D'UN PATIENT RESULTANT D'EXAMENS D'IMAGERIE MEDICALE

(54) Title: GENERATING AN ESTIMATE OF PATIENT RADIATION DOSE RESULTING FROM MEDICAL IMAGING SCANS



(57) **Abstré/Abstract:**

Techniques are disclosed for estimating patient radiation exposure during computerized tomography (CT) scans. More specifically, embodiments of the invention provide efficient approaches for generating a suitable patient model used to make such an estimate, to approaches for estimating patient dose by interpolating the results of multiple simulations, and to approaches for a service provider to host a dose estimation service made available to multiple CT scan providers.



*Bureau canadien des brevets*

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Certificat de correction

Certificate of Correction

**Canadian Patent No. 2,819,331**  
**Granted: 12 January 2021 (12-01-2021)**

Les corrections suivantes sont faites en raison de  
l'article 109 des *Règles sur les brevets* et le brevet  
doit être lu tel que corrigé.

The following corrections are made pursuant to  
section 109 of the *Patent Rules* and the patent  
should read as corrected.

**In the Patent Grant:**

**1. The attached pages 12 to 15, 18, 21 & 24  
should be read in place of pages 12 to 15, 18,  
21 & 24 in the description.**

**2. The attached drawing pages 5/11, 9/11 &  
11/11 should be read in place of pages 5/11,  
9/11 & 11/11.**

**27 January 2022 (27-01-2022)**

Date

1 gender. However, as noted above, the virtual geometry and body shape of an imaging phantom  
 2 selected based on just age and/or gender may (or may not) correspond to the size, shape and  
 3 organ positions of an actual person having a CT procedure. Accordingly, in one embodiment,  
 4 the dose estimation system 130 may be configured to deform a virtual phantom to better model  
 5 a particular patient. Example embodiments for deforming a virtual imaging phantom 132 are  
 6 discussed in greater detail below.

7 **[0047]** Once an imaging phantom is deformed to model a particular individual, dose  
 8 estimation system 130 may perform a simulation to estimate an amount of first pass dose  
 9 deposition resulting from a given CT scanning procedure. For example, in one embodiment, a  
 10 Monte Carlo simulation may be performed using the CT scanning parameters, CT procedure  
 11 parameters, and the deformed phantom to arrive at an estimation of dose. However, other  
 12 simulation approaches could be used as well. The results of a given dose estimation simulation  
 13 may be stored in the simulation library 134.

14 **[0048]** For example, the CT scanner may be parameterized for a simulation based on X-ray  
 15 tube current and voltage, CT Scanner mode, kVp, X-ray generator target angle, fan angle,  
 16 collimation, slice thickness, focus to axis distance, flat filters (material and thickness), beam  
 17 shaping filters (material and geometry). While a variety of approaches may be used in the  
 18 simulation process, in one embodiment, kVp, target angle and filtration are used to model the  
 19 X-ray spectrum as described in "Computation of bremsstrahlung X-ray spectra over an energy  
 20 range 15 KeV to 300 KeV," W. J. Iles, Regne Unit. National Radiological Protection Board,  
 21 NRPB, 1987.

22 **[0049]** In addition, focus to axis distance determines the distance of the X-ray source to the  
 23 axis of rotation and fan angle determines how widely the beam spreads on the slice plane. Of  
 24 course, these (and other parameters) may be selected as available or as needed to suit the  
 25 needs of a particular case. Typically however, energy deposition is stored per slice for each  
 26 anatomical region defined in the phantom. A normalization simulation of a CTDIvol phantom  
 27 may be performed for each CT model. This per-slice energy deposition information, combined  
 28 with the masses for each anatomical region is sufficient for calculating absorbed dose to each  
 29 region for a given scan region (using a sub-set of our full body simulation).

30 **[0050]** However, performing a Monte Carlo simulation typically requires substantial  
 31 processing time to complete – much longer than performing the CT scan itself. Accordingly, in

one embodiment, the dose estimation system 130 estimates dose by interpolating between two (or more) simulations in the simulation library 134. For example, a first pass patient dose may be calculated using multivariate scatter interpolation of existing simulation data. Patient dose information is refined as more applicable simulations are added. Similarly, new scanner models may be added to the simulation library 134 as calibration measurements and specifications of these scanners are obtained.

**[0051]** The simulation library 134 provides a database of Monte Carlo simulation results. In one embodiment, the simulation library 134 stores information on the dose/energy deposition to a set of phantoms, both as supplied and as deformed for individual patients, for a collection of supported medical imaging scanners, e.g., CT, RF, XA imaging modalities, among others. In one embodiment, the simulation library 134 is used to provide real time look-up and/or calculations of dose distributions given acquisition parameters, patient description, and scan region.

**[0052]** As noted, the simulation library 134 may be augmented automatically over time as additional Monte Carlo simulations are completed. For example, simulations to perform may be added to a queue as CT scan examinations occur. Priority may be given to simulations in an area with sparse existing data points. Doing so improves the probability of identifying simulations to interpolate, i.e., improves the simulation “space” covered by the simulation library 134. Similarly, more simulations available in simulation library 134 allow more stringent thresholds for selecting simulations to interpolate in a given case – leading to greater accuracy in dose estimates.

**[0053]** Note, while shown in Figure 1 as part of a CT scanning environment 100, the dose estimation system 130 (and phantoms 132 and library 134) may be provided as a hosted service accessed by/from the a CT scanning environment 100. For example, an imaging center may use a client interface on the imaging system 125 (e.g., a secure web portal or dedicated client application) to interact with a hosted dose estimation provider. An example of such an embodiment is discussed in greater detail below with respect to Figures 11 and 12.

**[0054]** Figure 2 illustrates an example an imaging system 125 used to obtain CT scan data and manage estimates of patient dose, according to one embodiment. As shown, the imaging system 125 includes, without limitation, a central processing unit (CPU) 205, a network interface 215, an interconnect 217, a memory 220 and storage 230. The

1 Imaging system 125 may also include an I/O device interface 210 connecting I/O devices 212  
2 (e.g., keyboard, display and mouse devices) to the imaging system 125.

3 **[0055]** CPU 205 retrieves and executes programming instructions stored in the memory  
4 220. Similarly, the CPU 205 stores and retrieves application data residing in the memory 220.  
5 The interconnect 217 facilitates transmission of programming instructions and application data  
6 between the CPU 205, I/O devices interface 210, storage 230, network interface 215, and  
7 memory 220. CPU 205 is included to be representative of a single CPU, multiple CPUs, a  
8 single CPU having multiple processing cores, and the like. And the memory 220 is generally  
9 included to be representative of a random access memory. The storage 230 may be a disk  
10 drive storage device. Although shown as a single unit, the storage 230 may be a combination of  
11 fixed and/or removable storage devices, such as disc drives, solid state storage devices (SSD),  
12 network attached (NAS), or a storage area-network (SAN). Further, storage 230 (or  
13 connections to storage repositories) may conform to a variety of standards for data storage  
14 related to health care environments (e.g., a PACS repository).

15 **[0056]** As shown, the memory 220 includes an imaging control component 222, an image  
16 storage component 224, and a dose estimation interface 226. And the storage 230 imaging  
17 protocols 232 and alarm thresholds 234. The imaging control component 222 corresponds to  
18 software applications used to perform a given CT scanning procedure – as specified by an  
19 imaging protocol 232. The imaging protocols 232 generally specify position, time, and duration  
20 for performing a specific CT procedure using a particular scan modality. The image storage  
21 component 224 provides software configured to store images and CT data derived while  
22 performing a given CT procedure or that interacts with a suitable storage repository to store  
23 such images and data. For example, CT scan data may be sent over a TCP/IP connection (via  
24 network interface) to/from a PACS repository.

25 **[0057]** The dose estimation interface 226 provides software components configured to  
26 interface with the dose estimation system 130 to obtain an estimate of patient dose that may  
27 result from a particular CT procedure. As noted, in one embodiment, the dose estimation  
28 interface 226 may interact with systems local to the CT imaging environment. However, in an  
29 alternative embodiment, the dose estimation interface 226 may interact with a hosted service  
30 provider. In such a case, the interface 226 may send requests for estimates of patient dose to  
31 the hosted service provider. Further, such request may indicate an imaging phantom,

transforms to that phantom, and the CT scanning equipment and protocols being followed for a given imaging scan. In either case, when being used in a predictive sense (i.e., before performing a procedure), the estimate of patient dose may be compared against alarm thresholds and rules to determine whether any alarms should issue prior to a given procedure being performed (e.g., an alarm indicating that a given procedure will (or would be likely to) exceed a cumulative dose limit for a given patient, organ or body part, etc.

**[0058]** Figure 3 illustrates an example of a dose estimation system 130 used to estimate and track cumulative patient dose, according to one embodiment. As shown, the dose estimation system 130 includes, without limitation, a central processing unit (CPU) 305, a network interface 315, an interconnect 317, a memory 320 and storage 330. The dose estimation system 130 may also include an I/O devices interface 310 connecting I/O devices 312 (e.g., keyboard, display and mouse devices) to the dose estimation system 130.

**[0059]** Like CPU 205, CPU 305 is included to be representative of a single CPU, multiple CPUs, a single CPU having multiple processing cores, etc., and the memory 320 is generally included to be representative of a random access memory. The interconnect 317 is used to transmit programming instructions and application data between the CPU 305, I/O devices interface 310, storage 330, network interface 315 and memory 320. The network interface 315 is configured to transmit data via the communications network, e.g., to receive requests from an imaging system for dose estimation. Storage 330, such as a hard disk drive or solid state (SSD) storage drive, may store non-volatile data.

**[0060]** As shown, the memory 320 includes a dose estimation tool 321, which provides a set of software components. Illustratively, the dose estimation tool 321 includes a Monte Carlo simulation component 322, a simulation selection component 324, an image registration/segmentation component 326, and a dose interpolation component 328. And storage 330 contains imaging phantom data 332, CT imaging protocols 334 and simulation library 335.

**[0061]** The Monte Carlo simulation component 322 is configured to estimate patient radiation dose based on a simulation using imaging phantom data 332 and a particular set of CT imaging equipment and a specified imaging protocol 334. As noted, in one embodiment, the imaging phantom data 332 may be deformed or otherwise transformed to better match the physical characteristics of a given patient.

1 images may be selected based on the relevant regions of the patient to be scanned. For  
 2 example, for a patient who will receive (or who received) a chest CT scan, the selected  
 3 reference image may depict this region of an individual with a body geometry that closely  
 4 matches the virtual phantom.

5 **[0068]** Figure 5A illustrates an example image representing a deformable phantom,  
 6 according to one embodiment. As shown, image 500 provides an anterior/posterior view 501  
 7 and a lateral view 502 of a virtual image phantom. As shown in views 501 and 502, the geometry  
 8 of this phantom includes a bone structure representing ribs 505, spine 515 and legs 522.  
 9 Additionally, the views 501 and 502 include geometry representing organs, including a stomach  
 10 510 and a kidney 520. The virtual phantom (as depicted in views 501 and 502 provides a rough  
 11 approximation of the size, shape, and positioning of human organs, tissues and structures.

12 **[0069]** While clearly a rough approximation of actual human anatomy, virtual phantoms are  
 13 generally accepted as providing reasonably accurate estimates of dose absorption. Figure 5B  
 14 illustrates an example of a 2D reference image of a portion of a human body corresponding to  
 15 the phantom shown in Figure 5A, according to one embodiment. As shown, the relative  
 16 positions, size, shape of the bones, tissues, organs, in the reference image match well to the  
 17 corresponding positions in the virtual phantom.

18 **[0070]** Referring again to the method 400, at step 420, the dose estimation tool performs an  
 19 image registration process to determine a transformation between the scout images of the  
 20 patient and the reference images used to represent the virtual phantom. The result of the  
 21 image registration is a mapping from points in the 2D scout localizer to points in the reference  
 22 image (or vice-versa). Similarly, in cases of a 3D scout image of the patient (i.e., a current or  
 23 prior CT scan), 3D image registration techniques may map points between the 3D scout image  
 24 of the patient and points in a reference image corresponding to the phantom in a 3D coordinate  
 25 space.

26 **[0071]** At step 425, this same transformation is used to deform the geometry representing  
 27 the virtual phantom. By deforming the virtual phantom using transformations obtained from the  
 28 image registration process, the size, shape, and organ positions represented by the geometry of  
 29 the virtual phantom matches the geometry of the actual patient much more accurately. For  
 30 example, performing an image registration process using the reference image shown in 5B and  
 31 a scout localizer of a patient provides a transformation can be used to deform the virtual

phantom deformed using the segmentation approach are tailored to the patient, resulting in more accurate and more consistent dose estimates, both for individual and multiple scans.

**[0079]** Figure 8 illustrates an example of a transverse slice of an imaging phantom superimposed over a corresponding transverse CT slice of a patient, according to one embodiment. In this example, a transverse view 800 corresponds to view 710 of Figure 7 and a transverse view 805 corresponds to view 730 of Figure 7. The transverse view is created by compositing a linear section of individual slices to create a longitudinal image. As shown, transverse views 800 and 805 provide a full length view including components not present in the superimposed CT image of the patient, e.g., brain 801 and kidney 802. As shown in view 800, a boundary 810 of the virtual phantom does not correspond well with the outline of the patient (i.e., with the body size bounded by the patient's skin). However, in view 805, a boundary 815 of the phantom has been displaced to better match the reference CT scan data of this patient. Similarly, internal organs, structures and other tissues may be displaced as well.

**[0080]** Importantly, this example illustrates that displacement may occur for elements of the virtual phantom that are not part of the CT scan data of the patient. For example, the kidney 802 could be displaced by the movement of other organs for which CT scan data is available, as shown by the displaced position of kidney 802' in view 805. Further, this example illustrates that a virtual phantom is required to estimate patient dose even where CT scan data is available. This occurs as although the CT scan in this example was limited to the chest and abdomen, X-ray scatter will result in some absorption by the brain, kidneys, and other organs and tissues of this patient. Stated differently, the virtual phantom is required to estimate organ dose absorption for organs not imaged as part of a given CT scan or procedure.

**[0081]** Figure 9 illustrates another example of a CT image segmentation and organ volume displacement for an imaging phantom, according to one embodiment. In this example, a CT volume 900 corresponding to an imagining includes a set of bounding boxes representing a segmented image position for a variety of organs, e.g., liver 905, gall bladder 910, and right adrenal gland 915. Additionally, volume 900 shows arrows representing the displacement of these organs based on an image segmentation of CT scan data. In this particular example, the liver 905 has been displaced down and to the right, while gall bladder 910 has been displaced up and to the front of the liver 905 and right adrenal 915 has moved up and to the left into the space formerly occupied by the liver 905. Further, in this example, the organs are represented



system at an imaging facility). At the client a dose management system tracks patient organ equivalent dose, effective dose, CTDI, DLP, DAP down to the examination level. This information is also summed up to provide cumulative tracking of organ equivalent dose, effective dose, CTDI, DLP, DAP for a given patient's history. Further aggregation of this information is used to provide institution-wide presentation of per capita organ equivalent dose, patient effective dose, CTDI, DLP, DAP. Thus, the dose estimation service may provide an imaging facility with a broad variety of . This same information is available to an imaging facility that runs a local instance of the dose estimation system.

**[0090]** Figure 11 illustrates an example computing infrastructure 1100 for a patient dose estimation service system configured to support multiple CT scan providers, according to one embodiment. As shown, a cloud based provider 1125 hosting a dose estimation service system 1130 receives requests for dose estimates over network 1120 from imaging facilities 1105<sub>1-2</sub>. At each imaging facility 1105, a CT system 1110 is used to provide imaging services for patients. An imaging /dose client 1115 communicates with the dose estimation service system 1130 to request and receive estimates of patient dose, where the dose estimates are tailored based on the procedure and patient. As noted, the request may include parameters for a CT procedure, scanning equipment and modality, and a deformed phantom (or transformations used to deform a phantom) based on the body morphology of the particular patient.

**[0091]** At the dose estimation service system 1130, a simulation library 1135 is used to select simulations for interpolating an amount of patient dose using data in the request and modules of a CT scanner and procedures (shown in Figure 11 a phantom/CT system data 1140). If no good candidate simulations are available for interpolation, then the service system 1130 may add the request to a queue of simulations to perform. Monte Carlo simulations are then performed in response to the request, providing both an estimate of patient dose for a given patient and imaging procedure as well as a new simulation data point to add to the library 1135.

**[0092]** Advantageously, embodiments of the invention provide a variety of techniques for estimating radiation doses that result from CT (and other) X-ray imaging techniques. As described, image registration techniques and/or image segmentation techniques may be used to create a hybrid imaging phantom that more accurately matches an individual's body size shape. Doing so improves the accuracy of dose estimates determined from a simulation. That

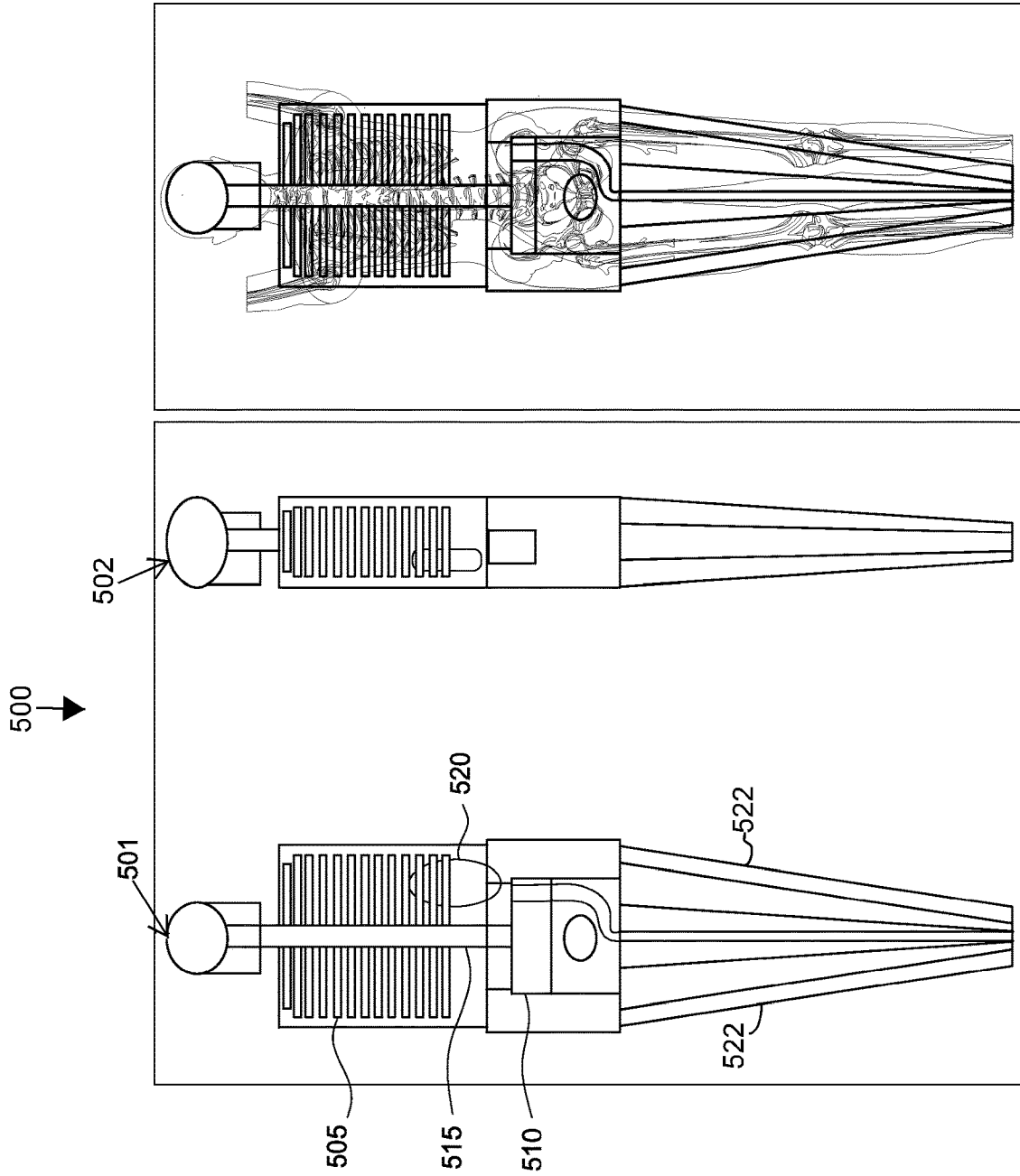


FIG. 5B

FIG. 5A

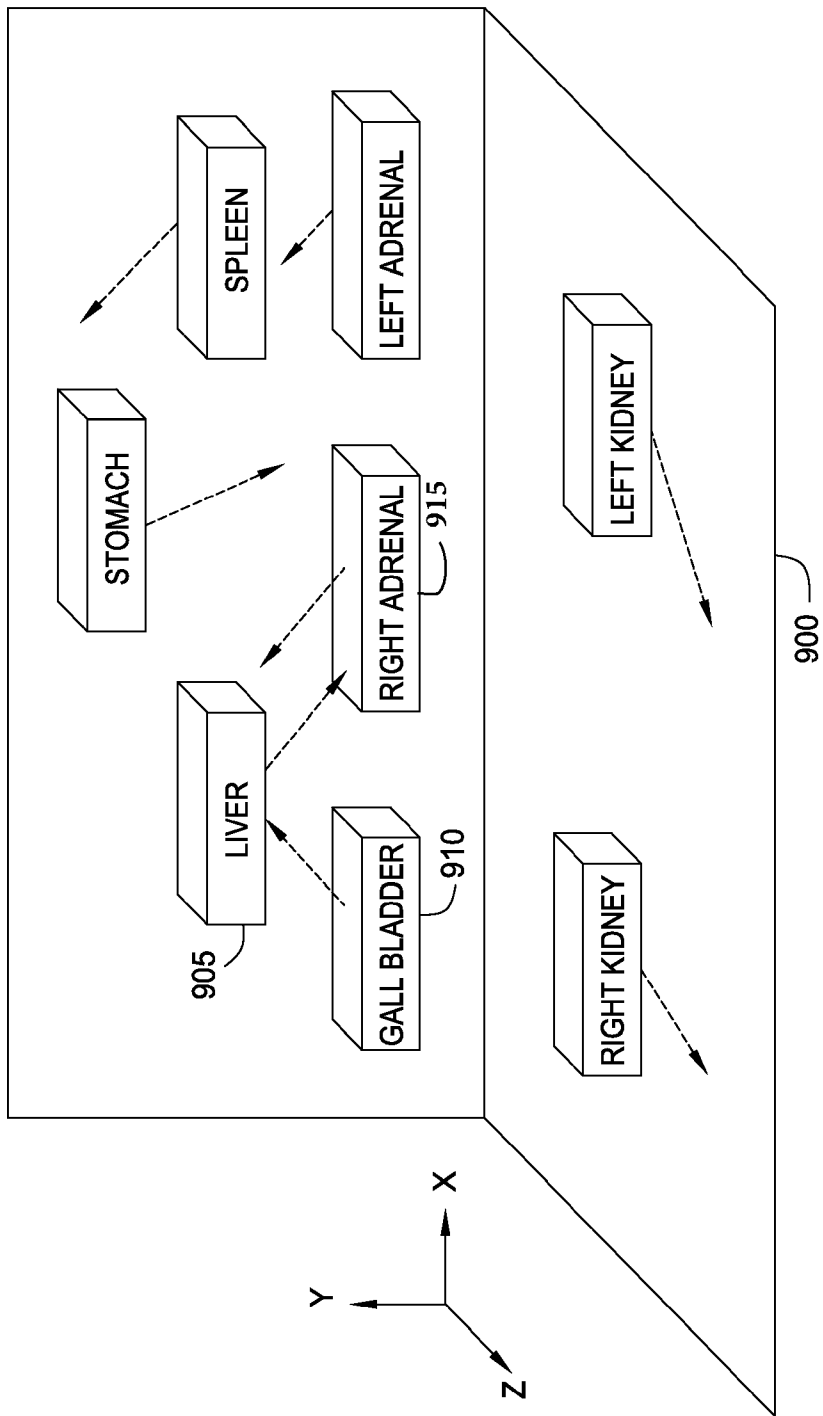


FIG. 9

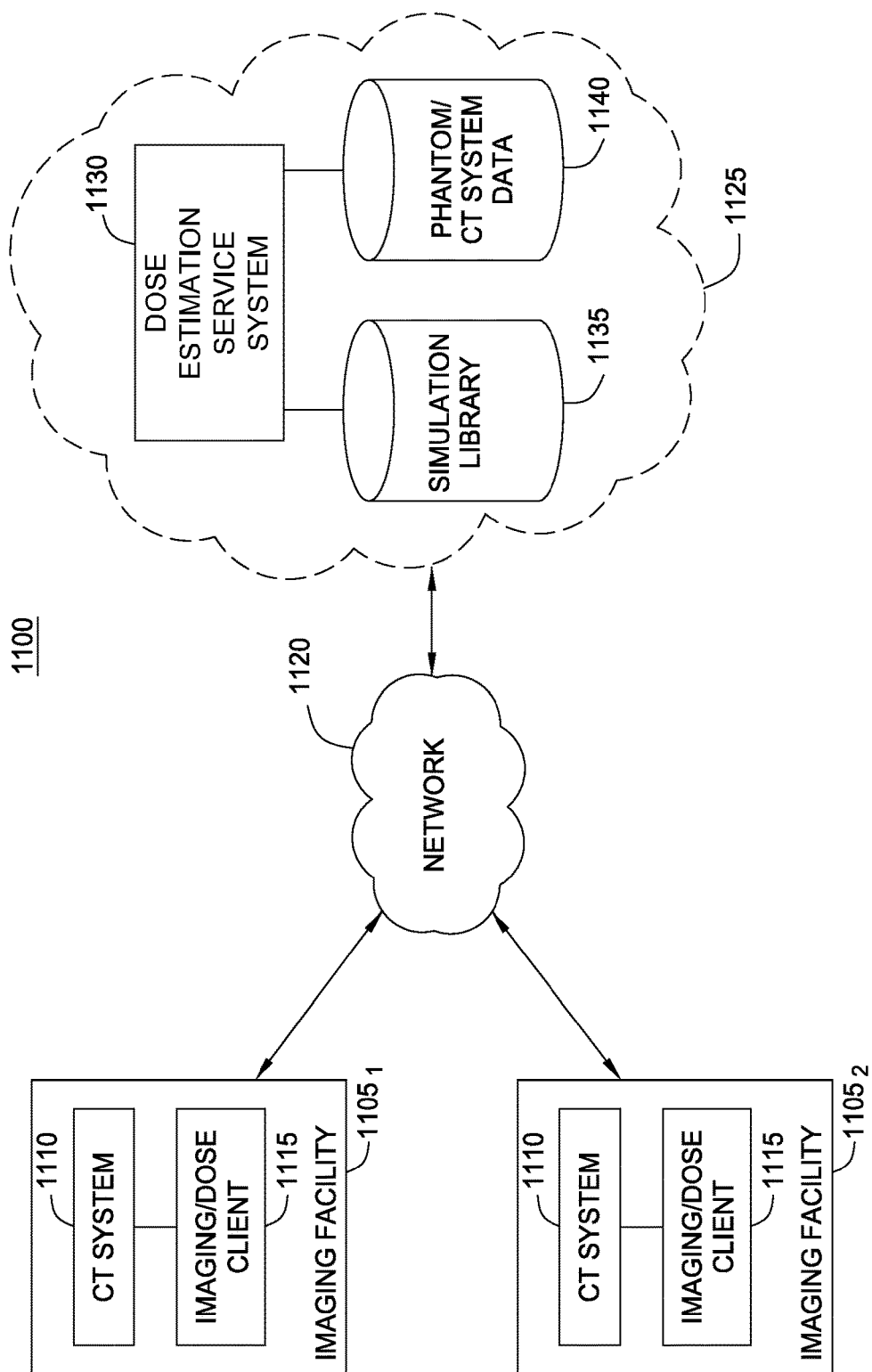


FIG. 11

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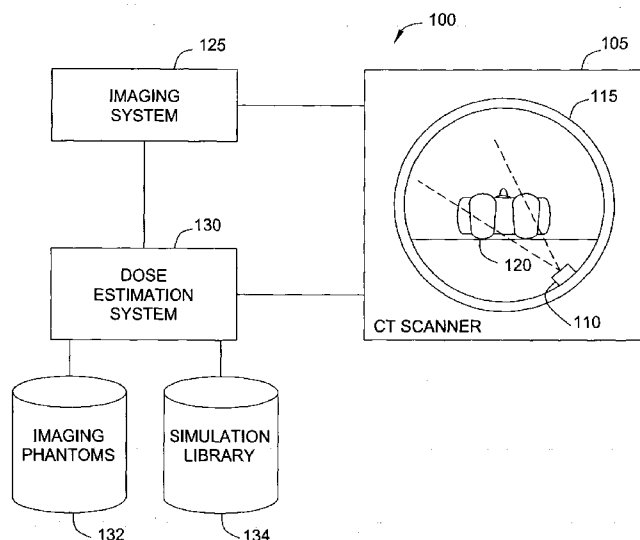


FIG. 1

(57) Abstract: Techniques are disclosed for estimating patient radiation exposure during computerized tomography (CT) scans. More specifically, embodiments of the invention provide efficient approaches for generating a suitable patient model used to make such an estimate, to approaches for estimating patient dose by interpolating the results of multiple simulations, and to approaches for a service provider to host a dose estimation service made available to multiple CT scan providers.

5   **[0001]**   Embodiments of the invention are generally directed to approaches for estimating  
6   patient radiation exposure during computerized tomography (CT) scans.

8 [0002] As is known, a CT scanning system uses ionizing radiation (X-rays) to generate  
9 images of tissues, organs, and other structures within a body. The X-ray data resulting from a  
10 CT scan may be converted into images on a computer display screen. For example, the CT  
11 scan provides a collection of data used to create a three dimensional (3D) volume  
12 corresponding to the scanned portion of a patient's body. The 3D volume is then sliced to  
13 create images of body tissue at small intervals along an axis of the patient's body. Such slices  
14 may include both lateral and transverse slices (as well as other slices) depending on the tissues  
15 or structures being imaged.

24 **[0004]** Despite the increased use of CT scans (and resulting exposure to radiation) the  
25 amount of radiation a patient is exposed to during a procedure, and importantly, the cumulative  
26 dose over many procedures are not parameters that are regularly tracked for a patient, and nor are  
27 these parameters readily accessible part of the patient's medical records. This occurs in part  
28 because the amount of radiation absorbed by internal organs and tissues cannot be measured  
29 in live patients directly as part of a CT exam, and results obtained from cadavers, while more  
30 accurate, do not correspond well to dose absorption in live tissues.

1 [0005] Similarly, approaches for estimating dose used currently also provide inaccurate  
2 results. For example, one approach is to rely on a limited number of physical imaging phantoms  
3 to represent a given patient. However, the available imaging phantoms do not adequately  
4 represent the broad variation in people's size and weight in the population of individuals  
5 receiving CT scans. As a result, single point surface measurements are what is currently done  
6 in the majority of cases where dose is estimated at all. However, this leads to both poor and  
7 widely varying results, depending on where the single point dose is measured. More generally,  
8 surface measurements of radiation exposure do not provide an accurate measure of actual  
9 absorption for internal tissues, organs, and structures.

## 10 SUMMARY

11 [0006] Embodiments provide techniques for estimating patient radiation exposure during  
12 computerized tomography (CT) scans. One embodiment includes a computer-implemented  
13 method for generating an imaging model corresponding to an individual. This method may  
14 generally include selecting an initial imaging phantom for an individual receiving an imaging  
15 scan, wherein the imaging phantom has one or more associated localizer images and receiving  
16 one or more scout images of individual. This method may further include determining a  
17 transformation between at least one of the localizer images associated with the imaging  
18 phantom and deforming the initial imaging phantom based on the transformation.

19 [0007] In a particular embodiment, the imaging scan is a computerized tomography (CT)  
20 scan, in other cases the imaging scan is a fluoroscopy scan, a PET scan, an angiography scan,  
21 etc. This method may further include receiving a set of parameters describing the imaging scan  
22 and CT scanning apparatus being used to perform the CT scan, simulating the imaging scan  
23 using the deformed imaging phantom and the received set of parameters, and estimating,  
24 based on the simulation, amounts of radiation absorbed by the individual as a result of  
25 performing the imaging scan. In a particular embodiment, the simulation is a Monte Carlo  
26 simulation.

27 [0008] Another embodiment includes a method for generating an imaging model  
28 corresponding to an individual. This method may generally include selecting an initial imaging  
29 phantom for an individual receiving a computerized tomography (CT) scan and segmenting a  
30 reference CT scan associated with the individual to identify a three-dimensional (3D) volume of

1 a plurality of anatomical landmarks of the individual present in the reference CT scan.  
2 This method may also include matching one or more of the identified anatomical  
3 landmarks in the segmented reference CT scan to corresponding anatomical landmarks  
4 in the initial imaging phantom and deforming the initial imaging phantom based on the  
5 matched anatomical landmarks.

6 **[0009]** Additional embodiments include a computer-readable storage medium storing  
7 an application, which, when executed on a processor, performs the above recited  
8 method as well as a system having a processor and a memory storing an enterprise  
9 information asset management application program, which, when executed on the  
10 processor, performs the above recited method.

11 **[0009a]** According to one embodiment of the present invention, there is provided a  
12 computer-implemented method for determining an estimate of radiation dose absorbed  
13 by an individual in receiving an imaging scan, the method comprising: receiving a set of  
14 parameters describing the imaging scan and an image scanning apparatus being used to  
15 perform the imaging scan; receiving a deformed mathematical phantom corresponding to  
16 the individual; evaluating a plurality of previously completed simulations estimating  
17 radiation dose absorption; and upon determining, based on the evaluation, that two or  
18 more of the plurality of previously completed simulations match the received set of  
19 parameters and the received deformed mathematical phantom within a specified  
20 tolerance measure, interpolating the estimates of radiation dose in the two or more  
21 simulations to determine the estimate of radiation dose absorbed by the individual in  
22 receiving the imaging scan.

23 **[0009b]** According to another embodiment of the present invention, there is provided a  
24 system, comprising: a processor; and a memory storing an application program  
25 configured to perform an operation for determining an estimate of radiation dose  
26 absorbed by an individual in receiving an imaging scan, the operation comprising:  
27 receiving a set of parameters describing the imaging scan and an image scanning  
28 apparatus being used to perform the imaging scan; receiving a deformed mathematical  
29 phantom corresponding to the individual, evaluating a plurality of previously completed  
30 simulations estimating radiation dose absorption, and upon determining, based on the



1 evaluation, that two or more of the plurality of previously completed simulations match  
2 the received set of parameters and the received deformed mathematical phantom within  
3 a specified tolerance measure, interpolating the estimates of radiation dose in the two or  
4 more simulations to determine the estimate of radiation dose absorbed by the individual  
5 in receiving the imaging scan.

6 **[0009c]** According to still another embodiment of the present invention, there is  
7 provided a non-transitory computer-readable storage medium storing one or more  
8 application programs, which, when executed by a processor performs an operation for  
9 determining an estimate of radiation dose absorbed by an individual in receiving an  
10 imaging scan, the operation comprising: receiving a set of parameters describing the  
11 imaging scan and an image scanning apparatus being used to perform the imaging scan;  
12 receiving a deformed mathematical phantom corresponding to the individual; evaluating  
13 a plurality of previously completed simulations estimating radiation dose absorption; and  
14 upon determining, based on the evaluation, that two or more of the plurality of previously  
15 completed simulations match the received set of parameters and the received deformed  
16 mathematical phantom within a specified tolerance measure, interpolating the estimates  
17 of radiation dose in the two or more simulations to determine the estimate of radiation  
18 dose absorbed by the individual in receiving the imaging scan.

## 19 **BRIEF DESCRIPTION OF THE DRAWINGS**

20 **[0010]** So that the manner in which the above recited aspects are attained and can  
21 be understood in detail, a more particular description of embodiments of the invention,  
22 briefly summarized above, may be had by reference to the appended drawings. Note  
23 however, the appended drawings illustrate only typical embodiments of the invention and  
24 are therefore not limiting of its scope, for the invention may admit to other equally  
25 effective embodiments.

26 **[0011]** Figure 1 illustrates an example of a CT scanning system and related  
27 computing systems configured to provide estimates of patient radiation dose, according  
28 to one embodiment of the invention.

- 1   **[0012]**     Figure 2 illustrates an example of an imaging system used to obtain CT scan  
2   data, according to one embodiment.
- 3   **[0013]**     Figure 3 illustrates an example of a dose estimation system used to estimate  
4   and track cumulative patient dose, according to one embodiment.
- 5   **[0014]**     Figure 4 illustrates a method for generating a suitable model for estimating  
6   patient radiation dose resulting from CT scans, according to one embodiment.
- 7   **[0015]**     Figure 5A illustrates an example image representing a deformable phantom,  
8   according to one embodiment.

1 [0016] Figure 5B illustrates an example of a two-dimensional (2D) reference image of a  
2 portion of a human body corresponding to the phantom shown in Figure 5A, according to one  
3 embodiment.

4 [0017] Figure 6 illustrates another method for generating a suitable model for estimating  
5 radiation dose resulting from CT scans, according to one embodiment.

6 [0018] Figure 7 illustrates an example slice of a phantom superimposed over a  
7 corresponding CT slice of a patient, according to one embodiment.

8 [0019] Figure 8 illustrates an example of a transverse slice of an imaging phantom  
9 superimposed over a corresponding transverse CT slice of a patient, according to one  
10 embodiment.

11 [0020] Figure 9 illustrates an example of a CT image segmentation and organ volume  
12 displacement for an imaging phantom, according to one embodiment.

13 [0021] Figure 10 illustrates a method for a dose estimation service to provide patient dose  
14 estimates to multiple CT scan providers, according to one embodiment.

15 [0022] Figure 11 illustrates an example computing infrastructure for a patient dose  
16 estimation service system configured to support multiple CT scan providers, according to one  
17 embodiment.

## 18 DETAILED DESCRIPTION

19 [0023] Embodiments of the invention are generally directed to approaches for estimating  
20 patient radiation exposure during computerized tomography (CT) scans. More specifically,  
21 embodiments of the invention provide efficient approaches for generating a suitable patient  
22 model used to make such an estimate, to approaches for estimating patient dose by  
23 interpolating the results of multiple simulations, and to approaches for a service provider to host  
24 a dose estimation service made available to multiple CT scan providers. As described in detail  
25 below, the dose management system provides a single system for tracking radiation dose  
26 across modalities and to present information to practitioners in a meaningful and easily  
27 understood format. Routine consideration of cumulative dose in ordering diagnostic imaging

1 tests may lead to a more informed decision-making process and ultimately benefit patient safety  
2 and care.

3 **[0024]** In one embodiment, a virtual imaging phantom is generated to model a given patient  
4 receiving a CT scan. The virtual imaging phantom may be generated by deforming an existing  
5 mathematical phantom to better match the size, shape, and/or organ positions of a patient being  
6 exposed to radiation in a CT scan. Initially, a mathematical phantom may be selected based on,  
7 e.g., an age and gender of the patient. Patient specific geometry may be achieved by  
8 deforming the selected mathematical phantom using transformations obtained by analyzing  
9 scout image localizers of that patient. Note, in this context, as understood by one of ordinary  
10 skill in the art, a "localizer" generally refers to a 2D image projection of a patient (typically an  
11 anterior/posterior X-ray image and/or a lateral X-ray image). In such an approach, the selected  
12 mathematical phantom may have its own reference set of localizer images. The reference  
13 images for a given virtual phantom are selected to match the geometry, size and positioning of  
14 that phantom (e.g., arms up or at the side) and may be selected from imaging obtained from  
15 multiple individuals.

16 **[0025]** Image registration techniques are then used to map points in the localizer image of  
17 the patient to points in the reference image (or images) associated with the virtual phantom.  
18 Doing so results in a set of transformations that can be used to deform the virtual phantom to  
19 better match the geometry of the patient. A similar approach involves using a reference set of  
20 3D data (selected CT scans) for the phantom and using 3D image registration techniques to  
21 map points in a CT scan of a given patient to points in reference CT scans associated with a  
22 given phantom.

23 **[0026]** Similarly, image segmentation may be used to identify a 3D volume within a CT scan  
24 corresponding to organs, tissues, or structures of interest in a CT scan of a patient. The 3D  
25 volume may be a bounding box, or a more precise 3D volume believed to represent an organ,  
26 etc. Once identified, a displacement may be determined between the position of the organ in  
27 the phantom and the corresponding position in the patient's CT scan. Instead of working on  
28 individual image points (as in the 2D/3D image registration techniques) the image segmentation  
29 approach works by using larger 3D volumes from the CT image as data points to determine a  
30 transformation from a virtual phantom and a given patient.

1 [0027] In each of these cases, the resulting hybrid phantom provides a much more accurate  
2 mathematical representation of a particular patient to use in a dose simulation than the  
3 unmodified phantoms alone. Once the transformations are determined, the hybrid virtual  
4 phantom may be used to simulate a given CT procedure for the patient. For example, well  
5 known Monte Carlo simulation techniques have been developed for estimating organ absorbed  
6 dose for a virtual phantom. Such simulation techniques use the virtual phantom (as transformed  
7 relative to a given patient), along with a number of settings related to the CT scanner model and  
8 procedure to be performed in order to compute accurate estimates of organ absorbed dose.  
9 For example, a CT scanner may be modeled using kVp, i.e., peak kilovoltage, X-ray generator  
10 target angle, fan angle, collimation, slice thickness, focus to axis distance, flat filters (material  
11 and thickness), and beam shaping filters (material and geometry). Of course, these (and other  
12 parameters) may be selected as available or as needed to suit the needs of a particular case.

13 [0028] However, estimating organ absorbed organ dose using a Monte Carlo simulation can  
14 require significant amounts of computing time, much longer than required to perform an actual  
15 CT scan. Given the high utilization of CT scanning systems at many imaging facilities, in cases  
16 where an estimate of total cumulative dose should not exceed a prescribed maximum, this delay  
17 is simply not tractable. Even in cases where the estimate is not used prior to performing a given  
18 procedure, unless the estimates of patient dose can be determined in relatively the same order  
19 of time as required to perform a procedure, then maintaining a record of dose estimation for a  
20 given scanning system becomes intractable – as the simulations will simply fall further and  
21 further behind the current scans being performed. This problem grows exponentially for a SaaS  
22 provider hosting a dose estimation service in the cloud for multiple imaging facilities.

23 [0029] Accordingly, in one embodiment, estimates of patient dose determined for a given  
24 procedure may be generated by interpolating between two (or more) previously completed  
25 simulations. If no “close” simulations are available, then the hybrid virtual phantom, CT scanner  
26 and procedure data may be added to a queue of full Monte Carlo simulations to be performed.  
27 Over time, a large library of simulations allows for dose estimates to be provided in real time as  
28 procedures are scheduled and preformed. Doing so allows cumulative dose amounts for a  
29 given patient to be captured, as well as cumulative dose limits to be observed.

30 [0030] Further, in one embodiment, a Software as a service (SaaS) or cloud provider model  
31 may be used to perform the dose estimates, maintain a library of computed simulations, as well

1 as run the Monte Carlo simulations. In such a case, a CT scan provider may supply the SaaS  
2 provider with the parameters of a given CT procedure. For example, client software (or even a  
3 secure web-based portal) at an imaging center may be used to supply the SaaS provider with a  
4 selected virtual phantom, along with transforms used to create a hybrid phantom modeling a  
5 particular individual and the equipment and protocol to be used in performing a CT procedure.  
6 Once received, the service provider can select the appropriate simulations from the library to  
7 interpolate and return an estimate of patient organ absorbed dose to the imaging center.

8 **[0031]** Importantly, the SaaS provider need not receive any actual identifying information  
9 about a given individual or patient receiving a CT scan. Instead, the SaaS provider receives only  
10 information related to a virtual phantom and a CT system/procedure. As a result, the operations  
11 of the service provider may not require compliance with a variety of laws and/or regulations  
12 related to the privacy of personal health information. Further, by providing dose estimates for  
13 multiple imaging centers, the resulting simulation library becomes more diverse and much more  
14 likely to find candidates for interpolation than a simulation library generated solely from scanning  
15 procedures performed by a single imaging center. Further still, centralizing the simulation  
16 library and Monte Carlo simulations allows improvements to the phantoms, a Monte Carlo  
17 simulation engine, and interpolation techniques to be shared by all imagining centers using the  
18 cloud based service. Lastly, this approach leaves it to the imaging center to maintain  
19 information tying cumulative dose to specific patients allowing actual patient data to remain with  
20 each individual provider. At the same time, the SaaS provider may, of course, communicate  
21 with the imaging centers using a variety of standardized protocols for image and data exchange,  
22 including, e.g., digital Imaging and Communications in Medicine (DICOM), Picture Archiving and  
23 Communication Systems (PACS), Health Level Seven International (HL7) standards, ICD-9,  
24 ICD-10 diagnosis and procedure codes, etc.

25 **[0032]** Additionally, the following description references embodiments of the invention.  
26 However, it should be understood that the invention is not limited to specific described  
27 embodiments. Instead, any combination of the following features and elements, whether related  
28 to different embodiments or not, is contemplated to implement and practice the invention.  
29 Furthermore, although embodiments of the invention may achieve advantages over other  
30 possible solutions and/or over the prior art, whether or not a particular advantage is achieved by  
31 a given embodiment is not limiting of the invention. Thus, the following aspects, features,  
32 embodiments and advantages are merely illustrative and are not considered elements or

1 limitations of the appended claims except where explicitly recited in a claim(s). Likewise,  
2 reference to "the invention" shall not be construed as a generalization of any inventive subject  
3 matter disclosed herein and shall not be considered to be an element or limitation of the  
4 appended claims except where explicitly recited in a claim(s).

5 **[0033]** As will be appreciated by one skilled in the art, aspects of the present invention may  
6 be embodied as a system, method or computer program product. Accordingly, aspects of the  
7 present invention may take the form of an entirely hardware embodiment, an entirely software  
8 embodiment (including firmware, resident software, micro-code, *etc.*) or an embodiment  
9 combining software and hardware aspects that may all generally be referred to herein as a  
10 "circuit," "module" or "system." Furthermore, aspects of the present invention may take the form  
11 of a computer program product embodied in one or more computer readable medium(s) having  
12 computer readable program code embodied thereon.

13 **[0034]** Any combination of one or more computer readable medium(s) may be utilized. The  
14 computer readable medium may be a computer readable signal medium or a computer readable  
15 storage medium. A computer readable storage medium may be, for example, but not limited to,  
16 an electronic, magnetic, optical, electromagnetic, infrared, or semiconductor system, apparatus,  
17 or device, or any suitable combination of the foregoing. More specific examples (a non-  
18 exhaustive list) of the computer readable storage medium would include the following: an  
19 electrical connection having one or more wires, a portable computer diskette, a hard disk, a  
20 random access memory (RAM), a read-only memory (ROM), an erasable programmable read-  
21 only memory (EPROM or Flash memory), an optical fiber, a portable compact disc read-only  
22 memory (CD-ROM), an optical storage device, a magnetic storage device, or any suitable  
23 combination of the foregoing. In the context of this document, a computer readable storage  
24 medium may be any tangible medium that can contain, or store a program for use by or in  
25 connection with an instruction execution system, apparatus or device.

26 **[0035]** The flowchart and block diagrams in the Figures illustrate the architecture,  
27 functionality and operation of possible implementations of systems, methods and computer  
28 program products according to various embodiments of the present invention. In this regard,  
29 each block in the flowchart or block diagrams may represent a module, segment or portion of  
30 code, which comprises one or more executable instructions for implementing the specified  
31 logical function(s). In some alternative implementations the functions noted in the block may

1 occur out of the order noted in the figures. For example, two blocks shown in succession may,  
2 in fact, be executed substantially concurrently, or the blocks may sometimes be executed in the  
3 reverse order, depending upon the functionality involved. Each block of the block diagrams  
4 and/or flowchart illustrations, and combinations of blocks in the block diagrams and/or flowchart  
5 illustrations can be implemented by special-purpose hardware-based systems that perform the  
6 specified functions or acts, or combinations of special purpose hardware and computer  
7 instructions.

8 **[0036]** Embodiments of the invention may be provided to end users through a cloud  
9 computing infrastructure. Cloud computing generally refers to the provision of scalable  
10 computing resources as a service over a network. More formally, cloud computing may be  
11 defined as a computing capability that provides an abstraction between the computing resource  
12 and its underlying technical architecture (*e.g.*, servers, storage, networks), enabling convenient,  
13 on-demand network access to a shared pool of configurable computing resources that can be  
14 rapidly provisioned and released with minimal management effort or service provider interaction.  
15 Thus, cloud computing allows a user to access virtual computing resources (*e.g.*, storage, data,  
16 applications, and even complete virtualized computing systems) in "the cloud," without regard  
17 for the underlying physical systems (or locations of those systems) used to provide the  
18 computing resources.

19 **[0037]** Typically, cloud computing resources are provided to a user on a pay-per-use basis,  
20 where users are charged only for the computing resources actually used (*e.g.*, an amount of  
21 storage space consumed by a user or a number of virtualized systems instantiated by the user).  
22 A user can access any of the resources that reside in the cloud at any time, and from anywhere  
23 across the Internet. In context of the present invention, a service provider may provide imaging  
24 centers with estimates of patient dose in both predictive and reporting perspectives. For  
25 example, a dose estimation interface may be used to submit virtual phantom and CT data to the  
26 cloud based provider.

27 **[0038]** The flowchart and block diagrams in the Figures illustrate the architecture,  
28 functionality, and operation of possible implementations of systems, methods and computer  
29 program products according to various embodiments of the present invention. In this regard,  
30 each block in the flowchart or block diagrams may represent a module, segment or portion of  
31 code, which comprises one or more executable instructions for implementing the specified



1 logical function(s). It should also be noted that, in some alternative implementations, the  
2 functions noted in the block may occur out of the order noted in the figures. For example, two  
3 blocks shown in succession may, in fact, be executed substantially concurrently, or the blocks  
4 may sometimes be executed in the reverse order, depending upon the functionality involved. It  
5 will also be noted that each block of the block diagrams and/or flowchart illustration, and  
6 combinations of blocks in the block diagrams and/or flowchart illustration, can be implemented  
7 by special purpose hardware-based systems that perform the specified functions or acts, or  
8 combinations of special purpose hardware and computer instructions.

9 **[0039]** Further, particular embodiments of the invention described below rely on a particular  
10 example of a computed tomography CT scanning system using a client-server architecture to  
11 provide dose estimation to a set of imaging. It should be understood, however, that the  
12 techniques described herein may be adapted for use with other medical imaging technology  
13 relying on exposing individuals to limited radiation doses as part of the imaging procedure (e.g.,  
14 PET scans, conventional X-ray imaging, and fluoroscopy and angiography, etc.).

15 **[0040]** Figure 1 illustrates an example of a CT scanning environment 100 and related  
16 computing systems configured to provide estimates of patient radiation dose, according to one  
17 embodiment of the invention. As shown, the CT scanning environment 100 includes a CT  
18 scanning system 105, an imaging system 125, and a dose estimation system 130. Additionally,  
19 the dose estimation system 130 includes a database of imaging phantoms 132 and a simulation  
20 library 134.

21 **[0041]** As is known, the CT scanner 105 provides a device used to bombard a subject 120  
22 with X-rays from an X-ray source 110. The X-rays emitted from X-ray source 110 pass through  
23 tissues, organs, and structures of the subject 120 at different rates (some of which is absorbed  
24 by such tissues organs and structures) depending on the density and type of matter which the  
25 X-rays pass through. Sensors disposed with a ring 115 detect the amount of radiation that  
26 passes through the subject 120. The resulting sensor information is passed to imaging system  
27 125. The imaging system 125 provides a computing device configured to receive, store, and  
28 generate images from the sensor data obtained from the CT scanner.

29 **[0042]** The imaging system 125 allows an operator to perform a given CT procedure as well  
30 as receive data obtained carrying out CT scans. For example, the imaging system 125 may be  
31 configured to "window," various body structures, based on their ability to block X-rays emitted

1 from source 110. CT scanning images (often referred to as "slices") are typically made relative  
2 to an axial or transverse plane, perpendicular to the long axis of the body. However, CT  
3 scanner 105 may allow the imaging data to be reformatted in various planes or as volumetric  
4 (3D) representations of structures. Once a CT scan is performed, the imaging data generated  
5 by CT scanner 105 may be stored allowing the resulting scan images to be reviewed or  
6 evaluated in other ways. In one embodiment, imaging data may be formatted using the well  
7 known DICOM standard and stored in a PACS repository.

8 **[0043]** In one embodiment, the dose estimation system 130 provides a computing system  
9 and software applications configured to estimate an amount of patient absorbed dose for a  
10 given patient receiving a given CT scan. Note, such an estimate may be made in a predictive  
11 sense (i.e., before performing a scan) but may be made after the fact as well.

12 **[0044]** In the predictive case, the dose estimation system 130 may provide an estimate of  
13 patient dose prior to performing a CT scan. Further, in one embodiment, dose estimation  
14 system 130 may be configured to automatically generate alerts based on configurable  
15 thresholds. The criteria for the generating an alert may use a rule engine that can take into  
16 account age, gender, ICD9/ICD10 encoding, and other information about a given patient or  
17 procedure (e.g., a specified cumulative dose limit). More generally, dose thresholds may be  
18 flexible enough to reflect any legislative, institutional, or treatment requirements for dose  
19 monitoring. In one embodiment, the resulting dose estimates may be stored as part of a  
20 patient's medical records/history maintained by an imaging center, hospital, or other provider.

21 **[0045]** Further, dose thresholds may optionally be used to create an incident reports routed  
22 to the appropriate practitioners. Incident reports may include a description of a procedure and  
23 any dose estimates that exceed a rule or threshold along with any supplementary information  
24 needed to provide context for practitioner intervention or decision making. In one embodiment,  
25 such a report may be printed/emailed using a customizable XML template.

26 **[0046]** Imaging phantoms 132 may provide accepted mathematical models of portions of  
27 human tissue, organs, structures, etc. For example, imaging phantoms 132 may provide a set  
28 of non-uniform rational basis spline (NURBS) used to create a three dimensional (3D) model of  
29 a human body (or portion thereof). Alternatively, the imaging phantoms may be represented  
30 using constructive solid geometry (CSG) or other mathematical representation. Different  
31 imaging phantoms 132 may be provided to generally model individuals based on age and

1 gender. However, as noted above, the virtual geometry and body shape of an imaging phantom  
2 selected based on just age and/or gender may (or may not) correspond to the size, shape and  
3 organ positions of an actual person having a CT procedure. Accordingly, in one embodiment,  
4 the dose estimation system 130 may be configured to deform a virtual phantom to better model  
5 a particular patient. Example embodiments for deforming a virtual imaging phantom 122 are  
6 discussed in greater detail below.

7 **[0047]** Once an imaging phantom is deformed to model a particular individual, dose  
8 estimation system 130 may perform a simulation to estimate an amount of first pass dose  
9 deposition resulting from a given CT scanning procedure. For example, in one embodiment, a  
10 Monte Carlo simulation may be performed using the CT scanning parameters, CT procedure  
11 parameters, and the deformed phantom to arrive at an estimation of dose. However, other  
12 simulation approaches could be used as well. The results of a given dose estimation simulation  
13 may be stored in the simulation library 134.

14 **[0048]** For example, the CT scanner may be parameterized for a simulation based on X-ray  
15 tube current and voltage, CT Scanner mode, kVp, X-ray generator target angle, fan angle,  
16 collimation, slice thickness, focus to axis distance, flat filters (material and thickness), beam  
17 shaping filters (material and geometry). While a variety of approaches may be used in the  
18 simulation process, in one embodiment, kVp, target angle and filtration are used to model the  
19 X-ray spectrum as described in "Computation of bremsstrahlung X-ray spectra over an energy  
20 range 15 KeV to 300 KeV," W. J. Iles, Regne Unit. National Radiological Protection Board,  
21 NRPB, 1987.

22 **[0049]** In addition, focus to axis distance determines the distance of the X-ray source to the  
23 axis of rotation and fan angle determines how widely the beam spreads on the slice plane. Of  
24 course, these (and other parameters) may be selected as available or as needed to suit the  
25 needs of a particular case. Typically however, energy deposition is stored per slice for each  
26 anatomical region defined in the phantom. A normalization simulation of a CTDIvol phantom  
27 may be performed for each CT model. This per-slice energy deposition information, combined  
28 with the masses for each anatomical region is sufficient for calculating absorbed dose to each  
29 region for a given scan region (using a sub-set of our full body simulation).

30 **[0050]** However, performing a Monte Carlo simulation typically requires substantial  
31 processing time to complete – much longer than performing the CT scan itself. Accordingly, in

one embodiment, the dose estimation system 130 estimates dose by interpolating between two (or more) simulations in the simulation library 134. For example, a first pass patient dose may be calculated using multivariate scatter interpolation of existing simulation data. Patient dose information is refined as more applicable simulations are added. Similarly, new scanner models may be added to the simulation library 134 as calibration measurements and specifications of these scanners are obtained.

**[0051]** The simulation library 134 provides a database of Monte Carlo simulation results. In one embodiment, the simulation library 134 stores information on the dose/energy deposition to a set of phantoms, both as supplied and as deformed for individual patients, for a collection of supported medical imaging scanners, e.g., CT, RF, XA imaging modalities, among others. In one embodiment, the simulation library 134 is used to provide real time look-up and/or calculations of dose distributions given acquisition parameters, patient description, and scan region.

**[0052]** As noted, the simulation library 134 may be augmented automatically over time as additional Monte Carlo simulations are completed. For example, simulations to perform may be added to a queue as CT scan examinations occur. Priority may be given to simulations in an area with sparse existing data points. Doing so improves the probability of identifying simulations to interpolate, i.e., improves the simulation "space" covered by the simulation library 134. Similarly, more simulations available in simulation library 134 allow more stringent thresholds for selecting simulations to interpolate in a given case – leading to greater accuracy in dose estimates.

**[0053]** Note, while shown in Figure 1 as part of a CT scanning environment 100, the dose estimation system 130 (and phantoms 132 and library 134) may be provided as a hosted service accessed by/from the a CT scanning environment 100. For example, an imaging center may use a client interface on the imaging system 125 (e.g., a secure web portal or dedicated client application) to interact with a hosted dose estimation provider. An example of such an embodiment is discussed in greater detail below with respect to Figures 11 and 12.

**[0054]** Figure 2 illustrates an example an imaging system 125 used to obtain CT scan data and manage estimates of patient dose, according to one embodiment. As shown, the imaging system 125 includes, without limitation, a central processing unit (CPU) 205, a CT system interface 214 network interface 215, an interconnect 217, a memory 225 and storage 230. The

1 Imaging system 125 may also include an I/O device interface 210 connecting I/O devices 212  
2 (e.g., keyboard, display and mouse devices) to the imaging system 125.

3 **[0055]** CPU 205 retrieves and executes programming instructions stored in the memory  
4 225. Similarly, the CPU 205 stores and retrieves application data residing in the memory 225.  
5 The interconnect 217 facilitates transmission of programming instructions and application data  
6 between the CPU 205, I/O devices interface 210, storage 230, network interface 215, and  
7 memory 225. CPU 205 is included to be representative of a single CPU, multiple CPUs, a  
8 single CPU having multiple processing cores, and the like. And the memory 225 is generally  
9 included to be representative of a random access memory. The storage 230 may be a disk  
10 drive storage device. Although shown as a single unit, the storage 230 may be a combination of  
11 fixed and/or removable storage devices, such as disc drives, solid state storage devices (SSD),  
12 network attached (NAS), or a storage area-network (SAN). Further, storage 230 (or  
13 connections to storage repositories) may conform to a variety of standards for data storage  
14 related to health care environments (e.g., a PACS repository).

15 **[0056]** As shown, the memory 220 includes an imaging control component 222, an image  
16 storage component 224, and a dose estimation interface 226. And the storage 235 imaging  
17 protocols 232 and alarm thresholds 234. The imaging control component 222 corresponds to  
18 software applications used to perform a given CT scanning procedure – as specified by an  
19 imaging protocol 232. The imaging protocols 232 generally specify position, time, and duration  
20 for performing a specific CT procedure using a particular scan modality. The image storage  
21 component 224 provides software configured to store images and CT data derived while  
22 performing a given CT procedure or that interacts with a suitable storage repository to store  
23 such images and data. For example, CT scan data may be sent over a TCP/IP connection (via  
24 network interface) to/from a PACS repository.

25 **[0057]** The dose estimation interface 226 provides software components configured to  
26 interface with the dose estimation system 130 to obtain an estimate of patient dose that may  
27 result from a particular CT procedure. As noted, in one embodiment, the dose estimation  
28 interface 226 may interact with systems local to the CT imaging environment. However, in an  
29 alternative embodiment, the dose estimation interface 226 may interact with a hosted service  
30 provider. In such a case, the interface 226 may send requests for estimates of patient dose to  
31 the hosted service provider. Further, such request may indicate an imaging phantom,

1 transforms to that phantom, and the CT scanning equipment and protocols being followed for a  
2 given imaging scan. In either case, when being used in a predictive sense (i.e., before  
3 performing a procedure), the estimate of patient dose may be compared against alarm  
4 thresholds and rules to determine whether any alarms should issue prior to a given procedure  
5 being performed (e.g., an alarm indicating that a given procedure will (or would be likely to)  
6 exceed a cumulative dose limit for a given patient, organ or body part, etc.

7 **[0058]** Figure 3 illustrates an example of a dose estimation system 130 used to estimate  
8 and track cumulative patient dose, according to one embodiment. As shown, the dose  
9 estimation system 130 includes, without limitation, a central processing unit (CPU) 305, a  
10 network interface 315, an interconnect 320, a memory 325 and storage 330. The dose  
11 estimation system 130 may also include an I/O devices interface 310 connecting I/O devices  
12 312 (e.g., keyboard, display and mouse devices) to the dose estimation system 130.

13 **[0059]** Like CPU 205, CPU 305 is included to be representative of a single CPU, multiple  
14 CPUs, a single CPU having multiple processing cores, etc., and the memory 325 is generally  
15 included to be representative of a random access memory. The interconnect 317 is used to  
16 transmit programming instructions and application data between the CPU 305, I/O devices  
17 interface 310, storage 330, network interface 315 and memory 325. The network interface 315  
18 is configured to transmit data via the communications network, e.g., to receive requests from an  
19 imaging system for dose estimation. Storage 330, such as a hard disk drive or solid state (SSD)  
20 storage drive, may store non-volatile data.

21 **[0060]** As shown, the memory 320 includes a dose estimation tool 321, which provides a set  
22 of software components. Illustratively, the dose estimation tool 321 includes a Monte Carlo  
23 simulation component 322, a simulation selection component 324, an image  
24 registration/segmentation component 326, and a dose interpolation component 328. And  
25 storage 330 contains imaging phantom data 332, CT imaging protocols 334 and simulation  
26 library 336.

27 **[0061]** The Monte Carlo simulation component 322 is configured to estimate patient  
28 radiation dose based on a simulation using imaging phantom data 322 and a particular set of  
29 CT imaging equipment and a specified imaging protocol 334. As noted, in one embodiment, the  
30 imaging phantom data 332 may be deformed or otherwise transformed to better match the  
31 physical characteristics of a given patient.

1   **[0062]**     The image registration/segmentation component 326 may be configured to  
2   determine a set of transforms for deforming the imaging phantom data 332 prior to performing a  
3   Monte Carlo simulation using that phantom. For example, the image registration/segmentation  
4   component 326 may evaluate a reference or localizer image associated with a phantom along  
5   with a scout localizer image of a patient using image registration techniques. Image  
6   registration is the process for aligning two images into a common coordinate system. An image  
7   registration algorithm determines a set of transformations to set a correspondence between the  
8   two images. Once the transforms between the scout image of the patient and a reference  
9   image of a phantom is determined, the same transformations may be used to deform the  
10   phantom. Such deformations may scale, translate and rotate the geometry of the virtual  
11   phantom to correspond to the patient.

12   **[0063]**     In another embodiment, image segmentation is used to identify a size and a relative  
13   position of organs, tissues, and anatomical structures of a patient. In such a case, available CT  
14   scan data for a patient may be segmented to identify geometric volumes believed to correspond  
15   to an organ (or other structure of interest). For example, in one embodiment, image  
16   segmentation may be used to identify a bounding box believed to contain a particular organ or  
17   structure. Other segmentation approaches may be used to provide a more definitive 3D  
18   volumetric region corresponding to an organ or structure. Once identified, this information is  
19   used to displace the geometry of the corresponding organ (or structure of interest) in the virtual  
20   phantom.

21   **[0064]**     Note, although shown as part of the dose estimation server 130, in one embodiment,  
22   the image registration/segmentation component 326 is part of the imaging system 125, or  
23   otherwise part of the computing infrastructure at an imaging facility. Doing so allows a provider  
24   hosting a dose estimation service to receive transforms for deforming a given virtual phantom,  
25   without also receiving any information that could be used to identify a patient receiving a CT  
26   scan at an imaging facility. This approach may simplify (or eliminate) certain legal or regulatory  
27   requirements associated with entities processing protected health information or medical  
28   records.

29   **[0065]**     After completing a Monte Carlo simulation, the resulting estimates of patient dose,  
30   along with the parameters supplied to the simulation component 322 are stored in the simulation  
31   library 335. In turn, the dose interpolation component 328 is used to determine an estimate of

1 patient dose from the simulations in the simulation library 335, without performing a complete  
2 Monte Carlo simulation. To do so, the simulation selection component 324 may compare the  
3 parameters of a CT scan, the equipment used to perform the CT scan, and the imaging  
4 phantom deformed to represent a particular individual. This information is used to identify a set  
5 of two or (or more) simulations to interpolate. While a variety of approaches may be used, in  
6 one embodiment, the selection component 324 may use a distance measure to compare the  
7 deformed phantom, the CT procedure, and CT equipment with ones in the simulation library  
8 335. In one embodiment, the top 2 (or top N) choices are selected for interpolation.  
9 Alternatively, any simulations with an overall similarity measure within a specified threshold are  
10 selected for interpolation. In such a case, by tuning the thresholds more, or less, simulations  
11 are used for interpolation.

12 **[0066]** Given the set of parameters describing the scanner and patient for an examination,  
13 (kVp, target angle, gantry tilt, height, weight, etc.) the system allows customizable tolerances to  
14 be set for each variable (e.g., actual kVp is within 10kV of simulation). When searching for  
15 simulations, only those simulations within tolerance for all given parameters will be factored into  
16 the calculation. In one embodiment, the simulation results may be interpolated using the known  
17 Shepard's method. The standard deviation across the set of simulation results is used as a  
18 measure of uncertainty (e.g. for the set of 5 simulations used, absorbed dose to the breasts has  
19 a SD of 0.2 mSv and absorbed dose to the liver has a SD of 0.15 mSv).

20 **[0067]** Figure 4 illustrates a method 400 for generating a suitable model for estimating  
21 patient radiation dose resulting from CT scans, according to one embodiment. More  
22 specifically, method 400 illustrates an example embodiment where image registration  
23 techniques are used to deform a virtual phantom. As shown, the method 400 begins at step  
24 405, where the dose estimation tool selects a virtual phantom with pre-mapped localizer  
25 images. As noted, the virtual phantom may be selected based on the age and gender of an  
26 individual receiving the CT scan procedure in question. At step 410, the dose estimation tool  
27 receives a scout image of the individual for whom the dose estimation is being performed. The  
28 scout image provides a 2D image projection of the individual, such as an anterior/posterior  
29 and/or lateral scout image taken by the CT scanning system prior to performing a full CT  
30 procedure. Alternatively, the scout image could be a 3D volume of the individual obtained as  
31 part of a prior CT scanning procedure. At step 415, the pre-mapped localizer images  
32 corresponding to use to deform the selected virtual phantom are obtained. The pre-mapped



1 images may be selected based on the relevant regions of the patient to be scanned. For  
2 example, for a patient who will receive (or who received) a chest CT scan, the selected  
3 reference image may depict this region of an individual with a body geometry that closely  
4 matches the virtual phantom.

5 **[0068]** Figure 5A illustrates an example image representing a deformable phantom,  
6 according to one embodiment. As shown, image 500 provides an anterior/posterior view 501  
7 and a lateral view 502 of a virtual image phantom. As shown in views 501 and 502, the geometry  
8 of this phantom includes a bone structure representing ribs 505, spine 515 and legs 522.  
9 Additionally, the views 501 and 502 include geometry representing organs, including a stomach  
10 510 and a kidney 515. The virtual phantom (as depicted in views 501 and 502 provides a rough  
11 approximation of the size, shape, and positioning of human organs, tissues and structures.

12 **[0069]** While clearly a rough approximation of actual human anatomy, virtual phantoms are  
13 generally accepted as providing reasonably accurate estimates of dose absorption. Figure 5B  
14 illustrates an example of a 2D reference image of a portion of a human body corresponding to  
15 the phantom shown in Figure 5A, according to one embodiment. As shown, the relative  
16 positions, size, shape of the bones, tissues, organs, in the reference image match well to the  
17 corresponding positions in the virtual phantom.

18 **[0070]** Referring again to the method 400, at step 420, the dose estimation tool performs an  
19 image registration process to determine a transformation between the scout images of the  
20 patient and the reference images used to represent the virtual phantom. The result of the  
21 image registration is a mapping from points in the 2D scout localizer to points in the reference  
22 image (or vice-versa). Similarly, in cases of a 3D scout image of the patient (i.e., a current or  
23 prior CT scan), 3D image registration techniques may map points between the 3D scout image  
24 of the patient and points in a reference image corresponding to the phantom in a 3D coordinate  
25 space.

26 **[0071]** At step 425, this same transformation is used to deform the geometry representing  
27 the virtual phantom. By deforming the virtual phantom using transformations obtained from the  
28 image registration process, the size, shape, and organ positions represented by the geometry of  
29 the virtual phantom matches the geometry of the actual patient much more accurately. For  
30 example, performing an image registration process using the reference image shown in 5B and  
31 a scout localizer of a patient provides a transformation can be used to deform the virtual

1 phantom shown in Figure 5A. The deformed virtual phantom may be used to estimate organ  
2 absorbed dose resulting from a given CT procedure (either before or after such a procedure is  
3 performed). That is, the dose estimations obtained from a Monte Carlo simulation are tailored  
4 to the patient, as well as more accurate and more consistent when used to estimate patient  
5 dose over multiple scans.

6 **[0072]** Figure 6 illustrates another method for generating a suitable model for estimating  
7 radiation dose resulting from CT scans, according to one embodiment. More specifically,  
8 method 600 illustrates an example embodiment where image segmentation techniques are  
9 used to deform a virtual phantom. Like method 400, method 600 begins where the dose  
10 estimation tool selects an imaging phantom to deform, e.g., based on an age and gender of a  
11 patient (step 605). However, instead of retrieving 2D image localizers of the patient, the dose  
12 estimation tool receives a 3D scan volume of some portion of the patient (at step 610), e.g., a  
13 CT scan from a prior chest and abdomen CT. Once obtained, image segmentation is used to  
14 identify tissues, organs, structures, or other landmarks in the image volume (step 615). While a  
15 variety of available segmentation approaches can be used, in one embodiment, the image  
16 segmentation provides a minimal bounding box surrounding each identified organ or structure.

17 **[0073]** At step 620, the dose estimation tool matches the organs and other anatomical  
18 landmarks (e.g., bone position) identified in the CT scan segmentation with corresponding  
19 landmarks in the virtual phantom. For example, Figure 7 illustrates an example slice of a CT  
20 scan superimposed over a corresponding slice of a virtual phantom, according to one  
21 embodiment. In this example, the virtual phantom slice 700 includes a line 702 representing the  
22 volume bounded by the phantom along with slice portions of a heart 701, lung 703, spine 704,  
23 and humerus bone 705. However, the location and position of the heart and lung organs in the  
24 virtual phantom do not correspond well with the position of these organs as depicted in the CT.  
25 For example, the open space region of the lungs (at 706) does not match the size or position of  
26 lungs 702 organs in the phantom. Similarly, the boundary line 702 of the phantom does not  
27 correspond well with the patient. Using this phantom to estimate dose, therefore, results in  
28 much greater dose absorption than would actually occur, because the phantom does not  
29 account for the large amounts of adipose tissues in this patient.

30 **[0074]** At the same time, other landmarks of the phantom line up well with the patient. For  
31 example, the spine and arms are generally collocated in both the phantom (spine 704 humerus

1 705) and CT. Accordingly, at step 625, the dose estimation system, determines a 3D  
2 displacement map based on the matched anatomical or structural landmarks.

3 **[0075]** For example, in Figure 7, phantom slice 700 shows an unmodified or un-deformed  
4 phantom and phantom slice 710 the same phantom slice after being displaced using the method  
5 of Figure 6 (or after being deformed using an image registration technique according to the  
6 method of Figure 4).

7 **[0076]** As shown in phantom slice 710, after being deformed using the identified organ  
8 volumes and displacement of a particular patient the boundary line 702' now more closely  
9 follows the contours of the patient CT scan, and the lungs 703' and heart 701' of the phantom  
10 have been displaced to better reflect the position of these organs in the scan. At the same time,  
11 other anatomical landmarks such as the spine and humerus bone remain in the same general  
12 position. The imaging phantom shown in slice 700 is shown superimposed over the  
13 corresponding CT scan slice of a patient in slice 720. Similarly, the deformed phantom shown  
14 in slice 710 is shown superimposed over the corresponding CT scan slice of a patient in slice  
15 730.

16 **[0077]** Referring again to Figure 6, at step 630, the dose estimation tool generates a  
17 rasterized 3D representation of the displaced organs, tissues, and structures of the virtual  
18 phantom. As noted, above, the virtual phantom may be described as a series of non-uniform  
19 rational basis splines (NURBS), while the CT scan data is typically represented as a series of  
20 3D coordinate single point values referred to as a "voxels" – short for "volume element," a voxel  
21 extends the concept of a pixel into a third dimension, and a variety of known approaches are  
22 available for "voxelizing" a collection of NURBs or CSG data. Doing so converts the geometric  
23 or mathematical representation of NURBs or CSG data into a 3D array of voxel values. In one  
24 embodiment, step 630 (the voxelization step) is performed in order to avoid discontinuities that  
25 often are a problem with Monte Carlo simulations in mathematical phantoms (whether NURB or  
26 CSG based). Further, voxel based models are well-suited to GPU-based computational  
27 methods to achieve improved speed.

28 **[0078]** Once the rasterized phantom is generated, it may be used to estimate organ  
29 absorbed dose resulting from a given CT procedure (either before or after such a procedure is  
30 performed). Like the image segmentation approaches, dose estimations performed using the

phantom deformed using the segmentation approach are tailored to the patient, resulting in more accurate and more consistent dose estimates, both for individual and multiple scans.

**[0079]** Figure 8 illustrates an example of a transverse slice of an imaging phantom superimposed over a corresponding transverse CT slice of a patient, according to one embodiment. In this example, a transverse view 800 corresponds to view 710 of Figure 7 and a transverse view 850 corresponds to view 730 of Figure 7. The transverse view is created by compositing a linear section of individual slices to create a longitudinal image. As shown, transverse views 800 and 805 provide a full length view including components not present in the superimposed CT image of the patient, e.g., brain 801 and kidney 802. As shown in view 800, a boundary 810 of the virtual phantom does not correspond well with the outline of the patient (i.e., with the body size bounded by the patient's skin). However, in view 850, a boundary 815 of the phantom has been displaced to better match the reference CT scan data of this patient. Similarly, internal organs, structures and other tissues may be displaced as well.

**[0080]** Importantly, this example illustrates that displacement may occur for elements of the virtual phantom that are not part of the CT scan data of the patient. For example, the kidney 802 could be displaced by the movement of other organs for which CT scan data is available, as shown by the displaced position of kidney 802' in view 850. Further, this example illustrates that a virtual phantom is required to estimate patient dose even where CT scan data is available. This occurs as although the CT scan in this example was limited to the chest and abdomen, X-ray scatter will result in some absorption by the brain, kidneys, and other organs and tissues of this patient. Stated differently, the virtual phantom is required to estimate organ dose absorption for organs not imaged as part of a given CT scan or procedure.

**[0081]** Figure 9 illustrates another example of a CT image segmentation and organ volume displacement for an imaging phantom, according to one embodiment. In this example, a CT volume 900 corresponding to an imagining includes a set of bounding boxes representing a segmented image position for a variety of organs, e.g., liver 905, gall bladder 910, and right adrenal gland 915. Additionally, volume 900 shows arrows representing the displacement of these organs based on an image segmentation of CT scan data. In this particular example, the liver 905 has been displaced down and to the right, while gall bladder 910 has been displaced up and to the front of the liver 905 and right adrenal 915 has moved up and to the left into the space formerly occupied by the liver 905. Further, in this example, the organs are represented

1 by bounding boxes, and are displaced based a geometric centroid. However, in an alternative  
2 embodiment image segmentation (for either the phantom or the CT image data of a patient)  
3 may provide a more accurate geometric volume representing an element of organ tissue or  
4 body structure. In such a case, the displacement could be based on a mass centroid of the  
5 organ, e.g., where the centroid of the liver is localized to one side based on mass or other  
6 approach that accounts for the topology of a given organ volume.

7 **[0082]** As illustrated in this example, displacing one organ (e.g., the liver 905) in a phantom  
8 based on its corresponding position in a CT reference scan, may require displacing other  
9 organs (e.g., the gall bladder 910 and right adrenal 915) as a result. This occurs as two organs  
10 plainly should not occupy the same physical volume when the phantom is used to perform a  
11 dose estimate analysis. Accordingly, in one embodiment, the dose estimation tool may displace  
12 organs, tissues or structures until reaching a "steady state."

13 **[0083]** Note, the example embodiments illustrated in Figures 4 and 6 may be used  
14 separately or in conjunction with one another to deform a virtual phantom. The particular  
15 approach or combination of approaches selected may be tailored to suit the needs in a  
16 particular case based on the available imaging phantoms, mapped 2D and/or 3D reference  
17 images, as well as on the availability and type of localizer scout images and/or prior CT scan  
18 data for a given patient.

19 **[0084]** In one embodiment, a cloud provider model host systems used to perform the dose  
20 estimates, maintain a library of computed simulations, as well as run the Monte Carlo  
21 simulations to augment the simulation library with new cases. For example, Figure 10 illustrates  
22 a method 1000 for a dose estimation service to provide patient dose estimates to multiple CT  
23 scan providers.

24 **[0085]** As shown, the method 1000 begins at step 1005 where the dose estimation service  
25 receives an image phantom (or a reference to an image phantom) along with 2D or 3D image  
26 registration transforms or 3D volumetric displacement field and phantom voxelization. In an  
27 alternative embodiment, the dose estimation service may receive data describing the deformed  
28 phantom such as the transformed NURBS resulting from the 2D or 3D image registration  
29 process or CT field displacement techniques described above.

30 **[0086]** At step 1010, the dose estimation services receives parameters of a CT scanning  
31 system and an imaging plan for a CT scan performed (or to be performed) on a patient. Once

1 the parameters of the patient, scanning equipment, and CT scan provider are received, the  
2 dose estimation service may identify two (or more) simulations in the library matching the  
3 transformed phantom, CT scanning system parameters and imaging plan (step 1015). The  
4 provider can set customizable tolerances to be set for each variable (e.g., actual kVp is within  
5 10kV of simulation). Further evaluating simulations, only simulations within tolerance for all (or  
6 specied set) of the given parameters are factored into the calculation. In one embodiment, the  
7 simulation results may be interpolated using the known Shepard's method. The standard  
8 deviation across the set of simulation results is used as a measure of uncertainty (e.g. for the  
9 set of 5 simulations used, absorbed dose to the breasts has a SD of 0.2 mSv and absorbed  
10 dose to the liver has a SD of 0.15 mSv).

11 **[0087]** At step 1020, the dose estimation service determines whether the matching  
12 simulations identified at step 1015 are within a tolerance parameter (or meets other thresholds  
13 or criteria). If not, then the image phantom (and deformations/transformations) and received  
14 parameters are added to a queue of patient/scanner/image plan scenarios to simulate (step  
15 1025). As noted, the simulation may use Monte Carlo simulation techniques to determine  
16 estimates of organ absorbed dose tailored to both the individual patient (based on the deformed  
17 phantom and the particular imaging facility based on the CT scanner and calibration/setting  
18 data.

19 **[0088]** However, as the simulation library of a SaaS provider grows, most requests should  
20 identify a set of simulations to interpolate. At step 1030, the dose estimation service performs a  
21 multivariate scatter interpolation using the matching simulations identified at step 1015 to  
22 estimate organ absorbed dose for a particular patient and associated CT scanning procedure.  
23 Note, such an analysis may be performed much more quickly than a full Monte Carlo simulation,  
24 allowing dose estimates to keep pace with a sequence of procedures performed at a given  
25 imaging facility (or facilities) as well as being provided concurrent with a given procedure (e.g.,  
26 to ensure cumulative dose limits are not exceeded). In one embodiment, the multivariate  
27 scatter interpolation method currently used is referred to as 'Shepard's method'. Examples of  
28 this method are described in Shepard, Donald (1968). "A two-dimensional interpolation function  
29 for irregularly-spaced data". *Proceedings of the 1968 ACM National Conference*. pp. 517-524.

30 **[0089]** At step 1035, once the interpolation process is complete, dose estimates are  
31 returned to a requesting system (e.g., a dose estimate client program running on a computing

1 system at an imaging facility). At the client a dose management system tracks patient organ  
2 equivalent dose, effective dose, CTDI, DLP, DAP down to the examination level. This  
3 information is also summed up to provide cumulative tracking of organ equivalent dose,  
4 effective dose, CTDI, DLP, DAP for a given patient's history. Further aggregation of this  
5 information is used to provide institution-wide presentation of per capita organ equivalent dose,  
6 patient effective dose, CTDI, DLP, DAP. Thus, the dose estimation service may provide an  
7 imaging facility with a broad variety of . This same information is available to an imaging facility  
8 that runs a local instance of the dose estimation system.

9 **[0090]** Figure 11 illustrates an example computing infrastructure 1100 for a patient dose  
10 estimation service system configured to support multiple CT scan providers, according to one  
11 embodiment. As shown, a cloud based provider 1125 hosting a dose estimation service 1130  
12 receives requests for dose estimates over network 1120 from imaging facilities 1105<sub>1,2</sub>. At each  
13 imaging facility 1105, a CT system 1110 is used to provide imaging services for patients. An  
14 imaging /dose client 1115 communicates with the dose estimation service 1130 to request and  
15 receive estimates of patient dose, where the dose estimates are tailored based on the  
16 procedure and patient. As noted, the request may include parameters for a CT procedure,  
17 scanning equipment and modality, and a deformed phantom (or transformations used to deform  
18 a phantom) based on the body morphology of the particular patient.

19 **[0091]** At the dose estimation service 1130, a simulation library 1135 is used to select  
20 simulations for interpolating an amount of patient dose using data in the request and modules of  
21 a CT scanner and procedures (shown in Figure 11 a phantom/CT system data 1140). If no  
22 good candidate simulations are available for interpolation, then the service 1130 may add the  
23 request to a queue of simulations to perform. Monte Carlo simulations are then performed in  
24 response to the request, providing both an estimate of patient dose for a given patient and  
25 imaging procedure as well as a new simulation data point to add to the library 1125.

26 **[0092]** Advantageously, embodiments of the invention provide a variety of techniques for  
27 estimating radiation doses that result from CT (and other) X-ray imaging techniques. As  
28 described, image registration techniques and/or image segmentation techniques may be used  
29 to create a hybrid imaging phantom that more accurately matches an individual's body size  
30 shape. Doing so improves the accuracy of dose estimates determined from a simulation. That

1 is, the resulting hybrid phantom provides a much more accurate mathematical representation of  
2 a particular patient to use in a dose simulation than the unmodified phantoms alone.

3 **[0093]** Once the transformations are determined, the hybrid virtual phantom may be used to  
4 simulate a given CT procedure for the patient. For example, Monte Carlo simulation techniques  
5 may be used to estimate organ absorbed dose for a virtual phantom. Such simulation  
6 techniques use the virtual phantom (as transformed relative to a given patient), along with a  
7 number of parameters related to the CT scanner model and procedure to be performed in order  
8 to compute accurate estimates of organ absorbed dose. However, estimating organ absorbed  
9 organ dose using a Monte Carlo simulation can require significant amounts of computing time,  
10 much longer than required to perform an actual CT scan. Accordingly, in one embodiment,  
11 estimates of patient dose determined for a given procedure may be generated by interpolating  
12 between two (or more) previously completed simulations. If no "close" simulations are available,  
13 then the hybrid virtual phantom, CT scanner and procedure data may be added to a queue of  
14 full Monte Carlo simulations to be performed. Over time, a large library of simulations allows for  
15 dose estimates to be provided in real time as procedures are scheduled and performed. Doing  
16 so allows cumulative dose amounts for a given patient to be captured, as well as cumulative  
17 dose limits to be observed. Further, in one embodiment, a SaaS provider is a hosted dose  
18 estimation service provided to multiple imaging facilities. In such a case, the service provider  
19 may have a robust library of simulations to use in interpreting dose estimates for the imaging  
20 providers.

21 **[0094]** While the foregoing is directed to embodiments of the present invention, other and  
22 further embodiments of the invention may be devised without departing from the basic scope  
23 thereof, and the scope thereof is determined by the claims that follow.



1 CLAIMS:

2  
3 1. A computer-implemented method for determining an estimate of  
4 radiation dose absorbed by an individual in receiving an imaging scan, the method  
5 comprising:

6 receiving a set of parameters describing the imaging scan and an image  
7 scanning apparatus being used to perform the imaging scan;

8 receiving a deformed mathematical phantom corresponding to the individual;

9 evaluating a plurality of previously completed simulations estimating radiation  
10 dose absorption; and

11 upon determining, based on the evaluation, that two or more of the plurality of  
12 previously completed simulations match the received set of parameters and the  
13 received deformed mathematical phantom within a specified tolerance measure,  
14 interpolating the estimates of radiation dose in the two or more simulations to  
15 determine the estimate of radiation dose absorbed by the individual in receiving the  
16 imaging scan.

17  
18 2. The computer-implemented method of claim 1, further comprising:

19 upon determining, based on the evaluation, that the plurality of previously  
20 completed simulations do not include at least two simulations matching the received  
21 set of parameters and the received deformed mathematical phantom within the  
22 specified tolerance measure:

23 performing a simulation of the imaging scan using the received  
24 deformed mathematical phantom and the received set of parameters;

25 estimating, based on the simulation, amounts of radiation absorbed by  
26 the individual as a result of performing the imaging scan; and

27 adding the performed simulation to the plurality of previously completed  
28 simulations.

1 3. The computer-implemented method of claim 1, wherein the received  
2 deformed mathematical phantom is deformed by determining, via an image  
3 registration process, a transformation between at least one localizer image  
4 associated with an initial mathematical phantom and at least one scout image of the  
5 individual.

6 4. The computer-implemented method of claim 1, wherein the received  
7 deformed mathematical phantom is deformed by:

8 segmenting a reference scan associated with the individual to identify a three-  
9 dimensional (3D) volume of a plurality of anatomical landmarks of the individual  
10 present in the reference scan;

11 for at least one of the plurality of anatomical landmarks, determining a centroid  
12 of the 3D volume;

13 matching one or more of the identified anatomical landmarks in the segmented  
14 reference scan to corresponding anatomical landmarks in an initial mathematical  
15 phantom, the initial mathematical phantom being selected based on at least one of an  
16 age, a gender, a weight and a height of the individual;

17 determining a three dimensional (3D) displacement map representing  
18 displacement from the centroid of the matched anatomical landmarks in the  
19 segmented reference scan to a centroid of the corresponding anatomical landmarks  
20 in the initial mathematical phantom;

21 voxelizing the initial mathematical phantom; and

22 transforming the voxelized mathematical phantom to match the displacement  
23 map.

24  
25 5. The computer-implemented method of claim 1, wherein the received  
26 deformed mathematical phantom is generated by:

27 selecting an initial mathematical phantom for the individual, the selecting being  
28 based on at least one of an age, a gender, a weight and a height of the individual;

29 receiving one or more scout images of the individual;

1 selecting from images obtained from multiple individuals a reference set of  
2 localizer images, the selecting being based on a similarity of a body geometry, size  
3 and positioning to that of the initial mathematical phantom;

4 determining a transformation between at least one of the localizer images and  
5 at least one of the scout images of the individual; and

6 deforming the initial mathematical phantom based on the transformation  
7 whereby the deformed mathematical phantom resulting from the transformation has a  
8 greater similarity than the initial mathematical phantom to a size, a shape and organ  
9 positions of the individual.

10  
11 6. The computer-implemented method of claim 1, wherein the estimate of  
12 radiation dose absorbed by the individual provides estimates of an organ absorbed  
13 dose for one or more organs of the individual.

14  
15 7. A system, comprising:

16 a processor; and

17 a memory storing an application program configured to perform an operation  
18 for determining an estimate of radiation dose absorbed by an individual in receiving  
19 an imaging scan, the operation comprising:

20 receiving a set of parameters describing the imaging scan and an  
21 image scanning apparatus being used to perform the imaging scan;

22 receiving a deformed mathematical phantom corresponding to the  
23 individual,

24 evaluating a plurality of previously completed simulations estimating  
25 radiation dose absorption, and

26 upon determining, based on the evaluation, that two or more of the  
27 plurality of previously completed simulations match the received set of  
28 parameters and the received deformed mathematical phantom within a  
29 specified tolerance measure, interpolating the estimates of radiation dose in

1 the two or more simulations to determine the estimate of radiation dose  
2 absorbed by the individual in receiving the imaging scan.

3  
4 8. The system of claim 7, further comprising:

5 upon determining, based on the evaluation, that the plurality of previously  
6 completed simulations do not include at least two simulations matching the received  
7 set of parameters and the received deformed mathematical phantom within the  
8 specified tolerance measure:

9 performing a simulation of the imaging scan using the received deformed  
10 mathematical phantom and the received set of parameters;

11 estimating, based on the simulation, amounts of radiation absorbed by the  
12 individual as a result of performing the imaging scan; and

13 adding the performed simulation to the plurality of previously completed  
14 simulations.

15  
16 9. The system of claim 7, wherein the received deformed mathematical  
17 phantom is deformed by determining, via an image registration process, a  
18 transformation between at least one localizer image associated with an initial  
19 mathematical phantom and at least one scout image of the individual.

20  
21 10. The system of claim 7, wherein the received deformed mathematical  
22 phantom is deformed by:

23 segmenting a reference scan associated with the individual to identify a three-  
24 dimensional (3D) volume of a plurality of anatomical landmarks of the individual  
25 present in the reference scan;

26 for at least one of the plurality of anatomical landmarks, determining a centroid  
27 of the 3D volume;

28 matching one or more of the identified anatomical landmarks in the segmented  
29 reference scan to corresponding anatomical landmarks in an initial mathematical

phantom, the initial mathematical phantom being selected based on at least one of an age, a gender, a weight and a height of the individual;

determining a three dimensional (3D) displacement map representing displacement from the centroid of the matched anatomical landmarks in the segmented reference scan to a centroid of the corresponding anatomical landmarks in the initial mathematical phantom;

voxelizing the initial mathematical phantom; and

transforming the voxelized mathematical phantom to match the displacement map.

11. The system of claim 7, wherein the received deformed mathematical phantom is generated by:

selecting an initial mathematical phantom for the individual, the selecting being based on at least one of an age, a gender, a weight and a height of the individual;

receiving one or more scout images of the individual;

selecting from images obtained from multiple individuals a reference set of localizer images, the selecting being based on a similarity of a body geometry, size and positioning to that of the initial mathematical phantom;

determining a transformation between at least one of the localizer images and at least one of the scout images of the individual; and

deforming the initial mathematical phantom based on the transformation whereby the deformed mathematical phantom resulting from the transformation has a greater similarity than the initial mathematical phantom to a size, a shape and organ positions of the individual.

12. The system of claim 7, wherein the estimate of radiation dose absorbed by the individual provides estimates of an organ absorbed dose for one or more organs of the individual.

1 13. A non-transitory computer-readable storage medium storing one or  
2 more application programs, which, when executed by a processor performs an  
3 operation for determining an estimate of radiation dose absorbed by an individual in  
4 receiving an imaging scan, the operation comprising:

5 receiving a set of parameters describing the imaging scan and an image  
6 scanning apparatus being used to perform the imaging scan;

7 receiving a deformed mathematical phantom corresponding to the individual;

8 evaluating a plurality of previously completed simulations estimating radiation  
9 dose absorption; and

10 upon determining, based on the evaluation, that two or more of the plurality of  
11 previously completed simulations match the received set of parameters and the  
12 received deformed mathematical phantom within a specified tolerance measure,  
13 interpolating the estimates of radiation dose in the two or more simulations to  
14 determine the estimate of radiation dose absorbed by the individual in receiving the  
15 imaging scan.

16  
17 14. The non-transitory computer-readable storage medium of claim 13,  
18 wherein the operation further comprises:

19 upon determining, based on the evaluation, that the plurality of previously  
20 completed simulations do not include at least two simulations matching the received  
21 set of parameters and the received deformed mathematical phantom within the  
22 specified tolerance measure:

23 performing a simulation of the imaging scan using the received  
24 deformed mathematical phantom and the received set of parameters;

25 estimating, based on the simulation, amounts of radiation absorbed by  
26 the individual as a result of performing the imaging scan; and

27 adding the performed simulation to the plurality of previously completed  
28 simulations.

1 15. The non-transitory computer-readable storage medium of claim 13,  
2 wherein the imaging scan is a computerized tomography (CT) scan.

3  
4 16. The non-transitory computer-readable storage medium of claim 13,  
5 wherein the interpolation is a multivariate scatter interpolation.

6  
7 17. The non-transitory computer-readable storage medium of claim 14,  
8 wherein the simulation is a Monte Carlo simulation.

9  
10 18. The non-transitory computer-readable storage medium of claim 13,  
11 wherein the received deformed mathematical phantom is selected based on at least  
12 one of an age, a weight, a height and a gender of the individual.

13  
14 19. The non-transitory computer-readable storage medium of claim 13,  
15 wherein the received deformed mathematical phantom is deformed by determining,  
16 via an image registration process, a transformation between at least one localizer  
17 image associated with an initial mathematical phantom and at least one scout image  
18 of the individual.

19  
20 20. The non-transitory computer-readable storage medium of claim 13,  
21 wherein the received deformed imaging phantom is deformed by:

22 segmenting a reference CT scan associated with the individual to identify a  
23 three-dimensional (3D) volume of a plurality of anatomical landmarks of the individual  
24 present in the reference CT scan;

25 for at least one of the plurality of anatomical landmarks, determining a centroid  
26 of the 3D volume;

27 matching one or more of the identified anatomical landmarks in the segmented  
28 reference CT scan to corresponding anatomical landmarks in an initial mathematical  
29 phantom, the initial mathematical phantom being selected based on at least one of an  
30 age, a gender, a weight and a height of the individual;

1       determining a three dimensional (3D) displacement map representing  
2 displacement from the centroid of the matched anatomical landmarks in the  
3 segmented reference scan to a centroid of the corresponding anatomical landmarks  
4 in the initial mathematical phantom;  
5       voxelizing the initial mathematical phantom; and  
6       transforming the voxelized mathematical phantom to match the displacement  
7 map.

8  
9       21.       The non-transitory computer-readable storage medium of claim 13,  
10 wherein the received deformed mathematical phantom is generated by:

11       selecting an initial mathematical phantom for the individual, the selecting being  
12 based on at least one of an age, a gender, a weight and a height of the individual;

13       receiving one or more scout images of the individual;

14       selecting from images obtained from multiple individuals a reference set of  
15 localizer images, the selecting being based on a similarity of a body geometry, size  
16 and positioning to that of the initial mathematical phantom;

17       determining a transformation between at least one of the localizer images and  
18 at least one of the scout images of the individual; and

19       deforming the initial mathematical phantom based on the transformation  
20 whereby the deformed mathematical phantom resulting from the transformation has a  
21 greater similarity than the initial mathematical phantom to a size, a shape and organ  
22 positions of the individual.

23  
24       22.       The non-transitory computer-readable storage medium of claim 13,  
25 wherein the estimate of radiation dose absorbed by the individual provides estimates  
26 of an organ absorbed dose for one or more organs of the individual.



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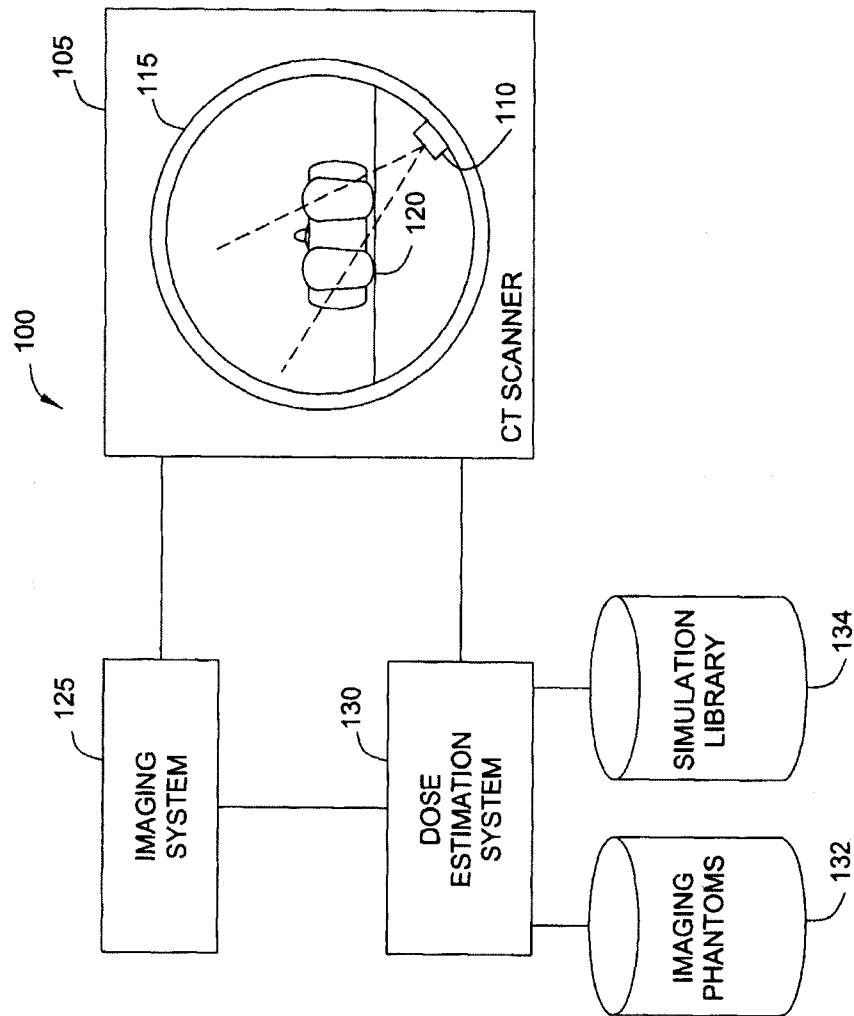


FIG. 1

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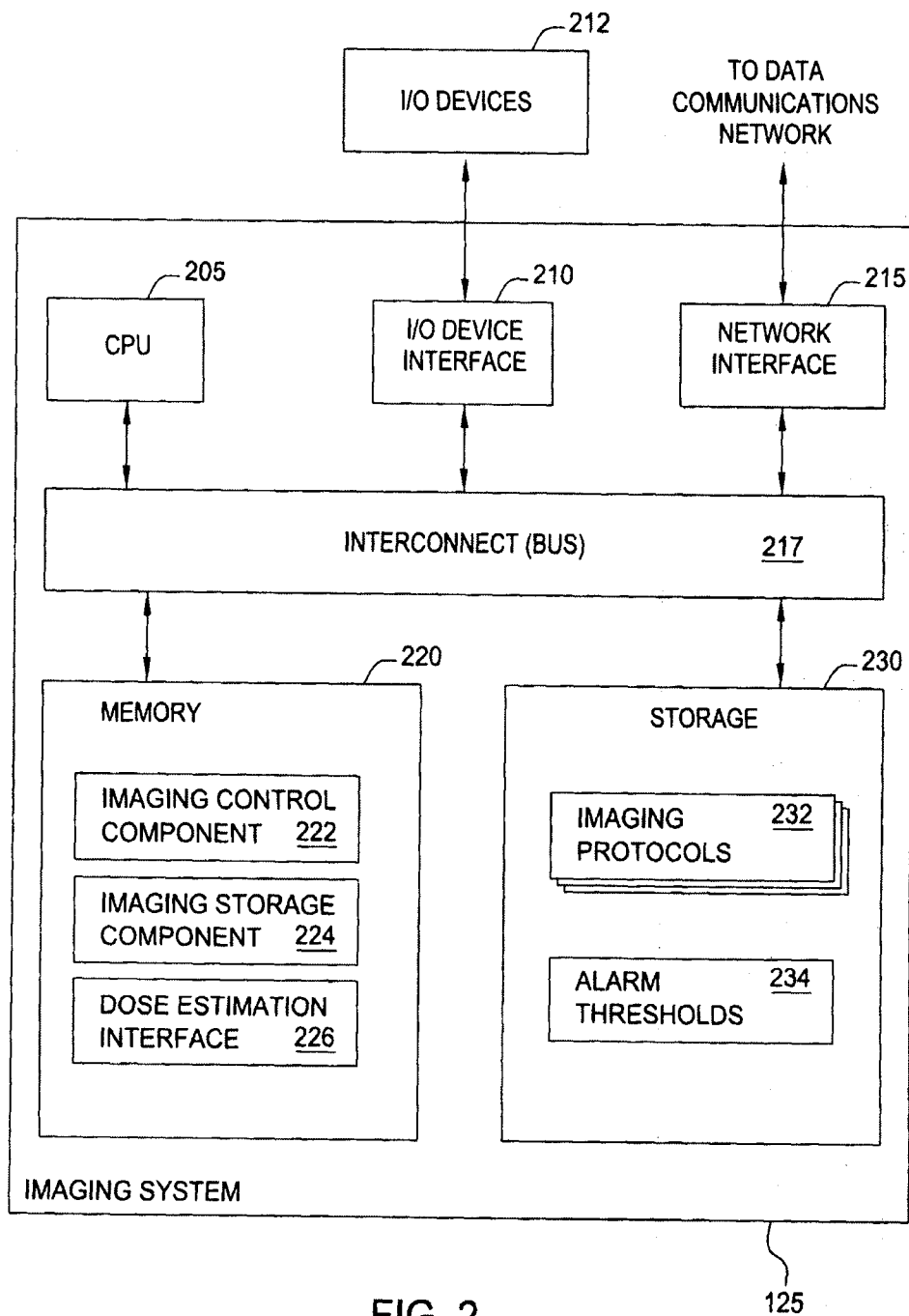


FIG. 2

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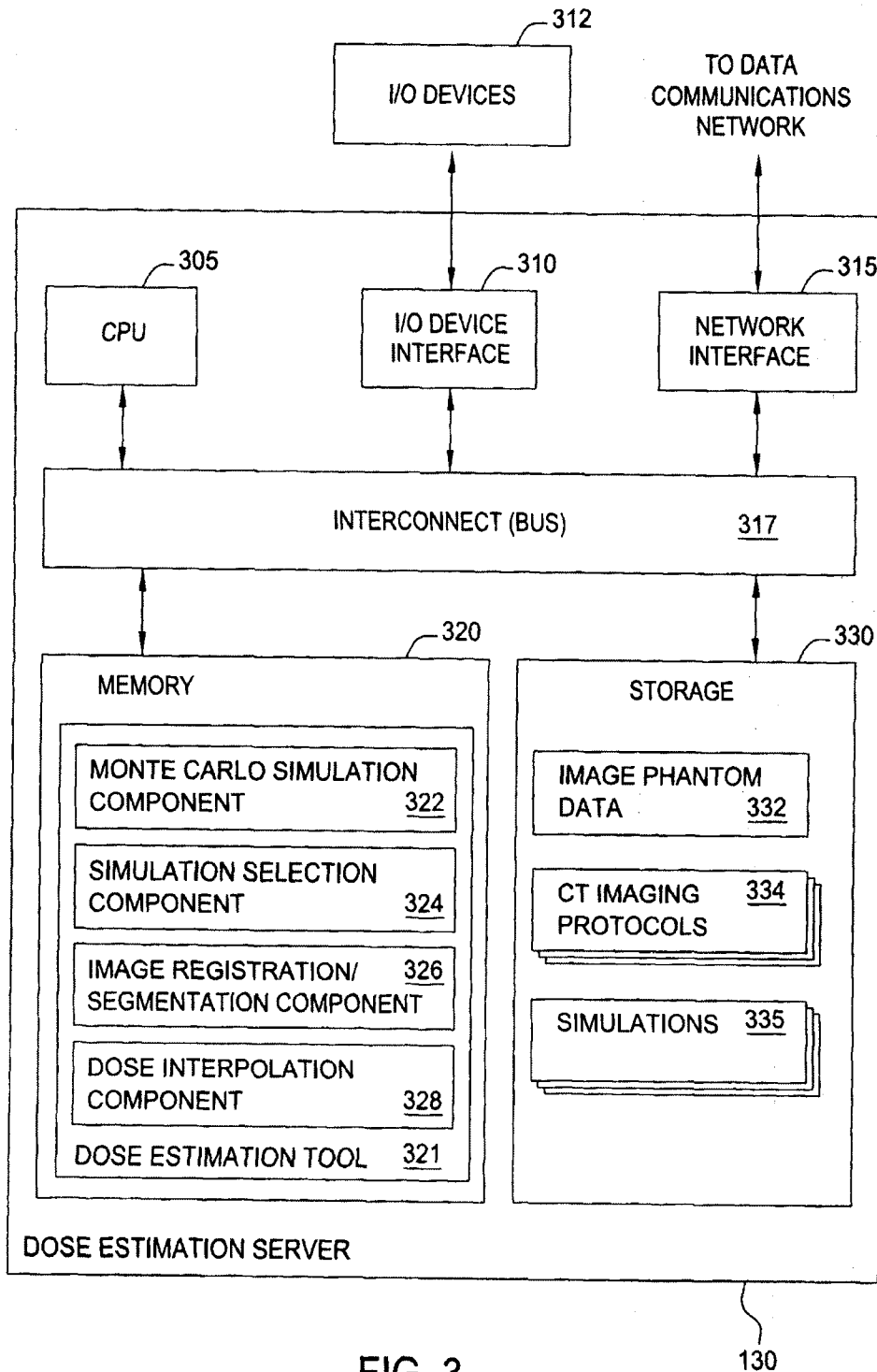


FIG. 3

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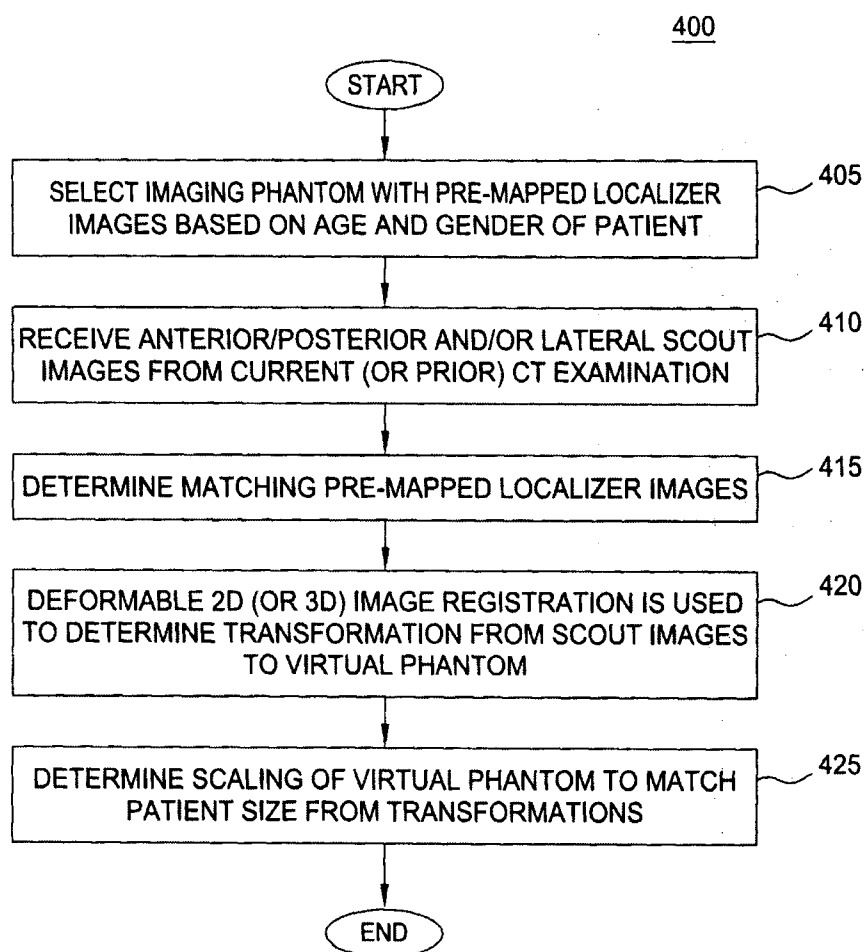
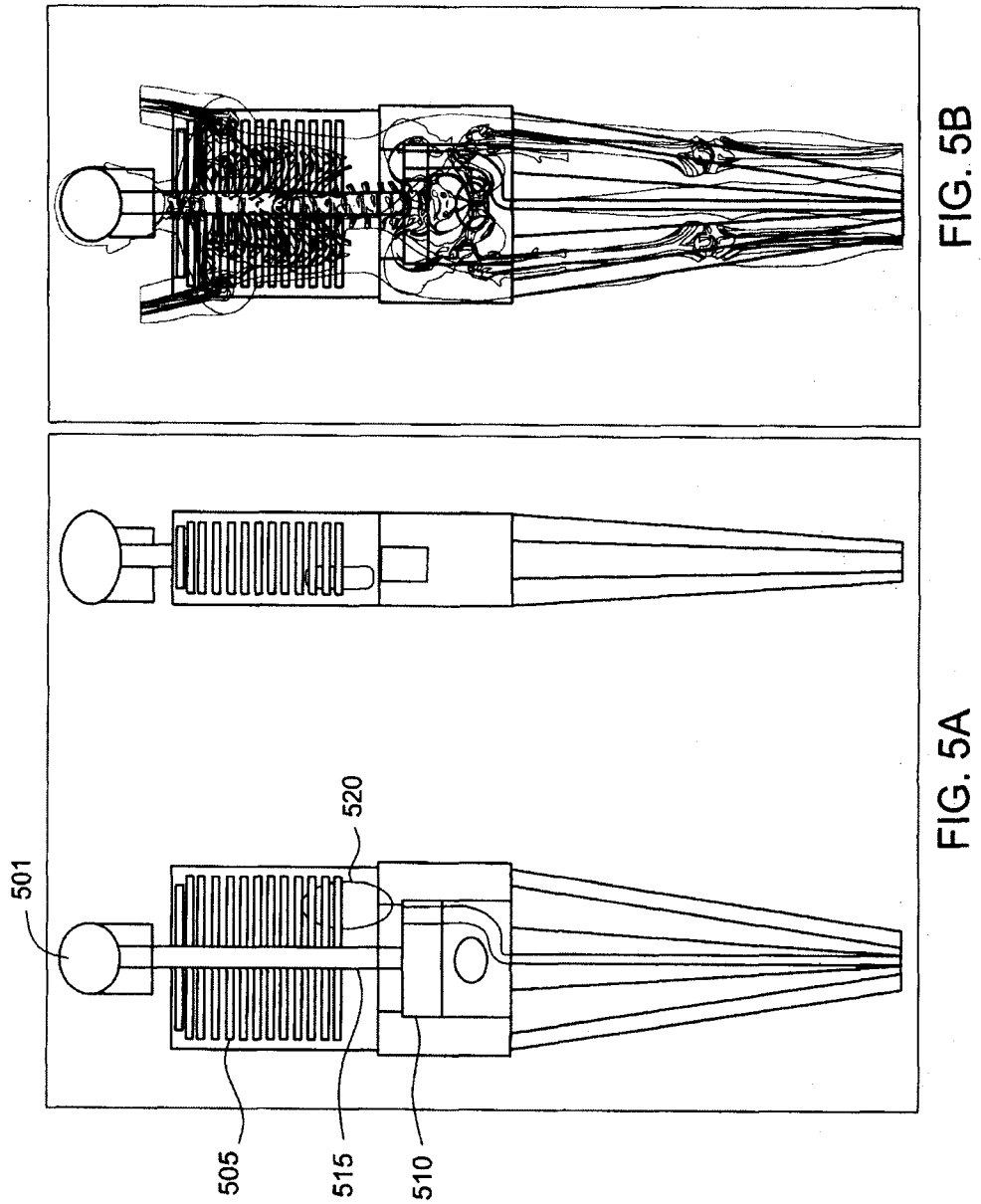


FIG. 4

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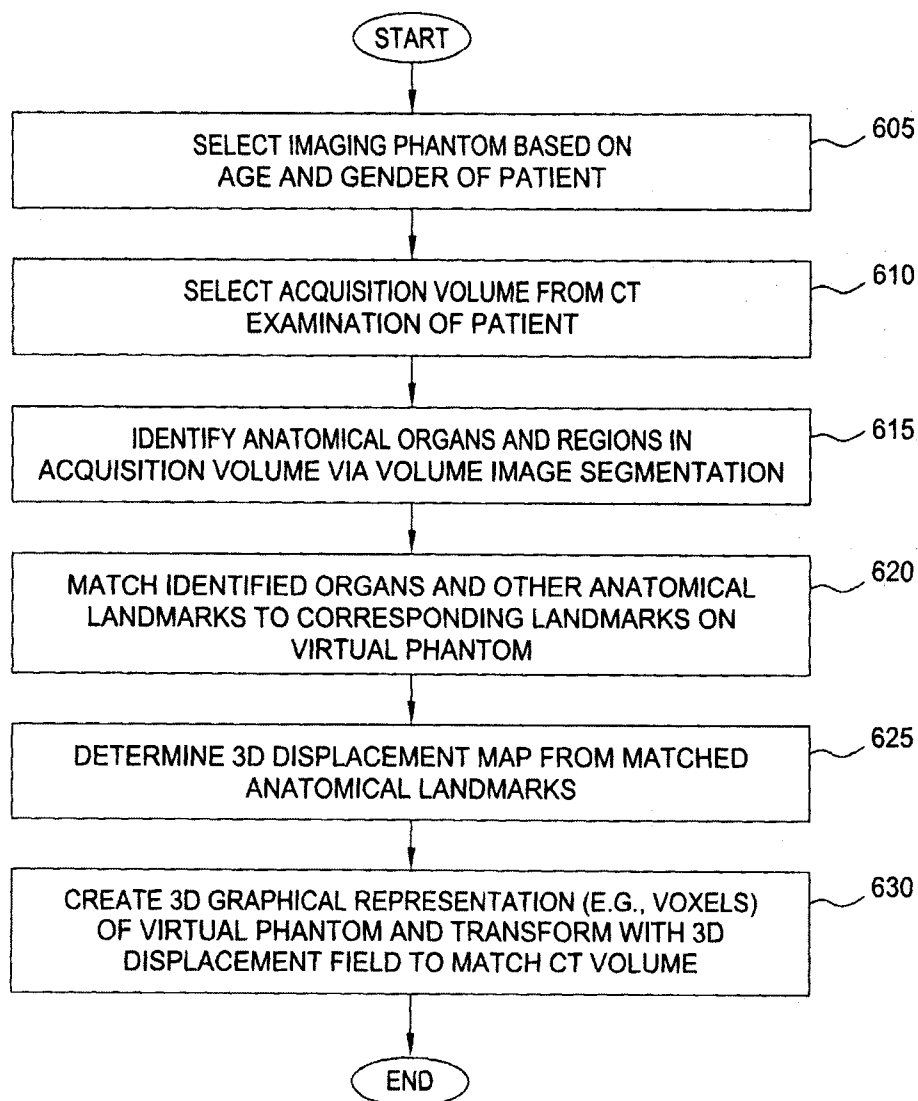
600

FIG. 6

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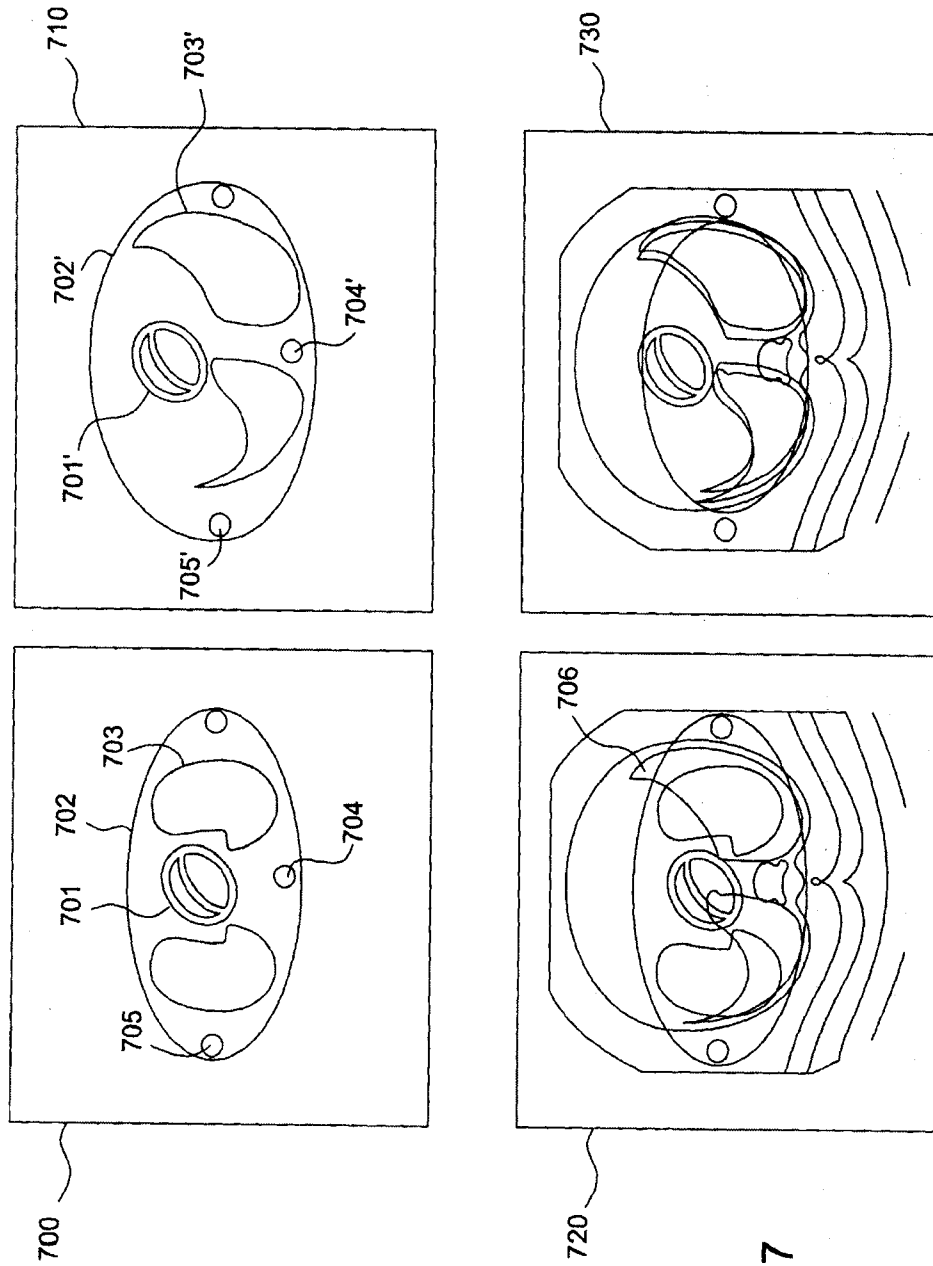


FIG. 7

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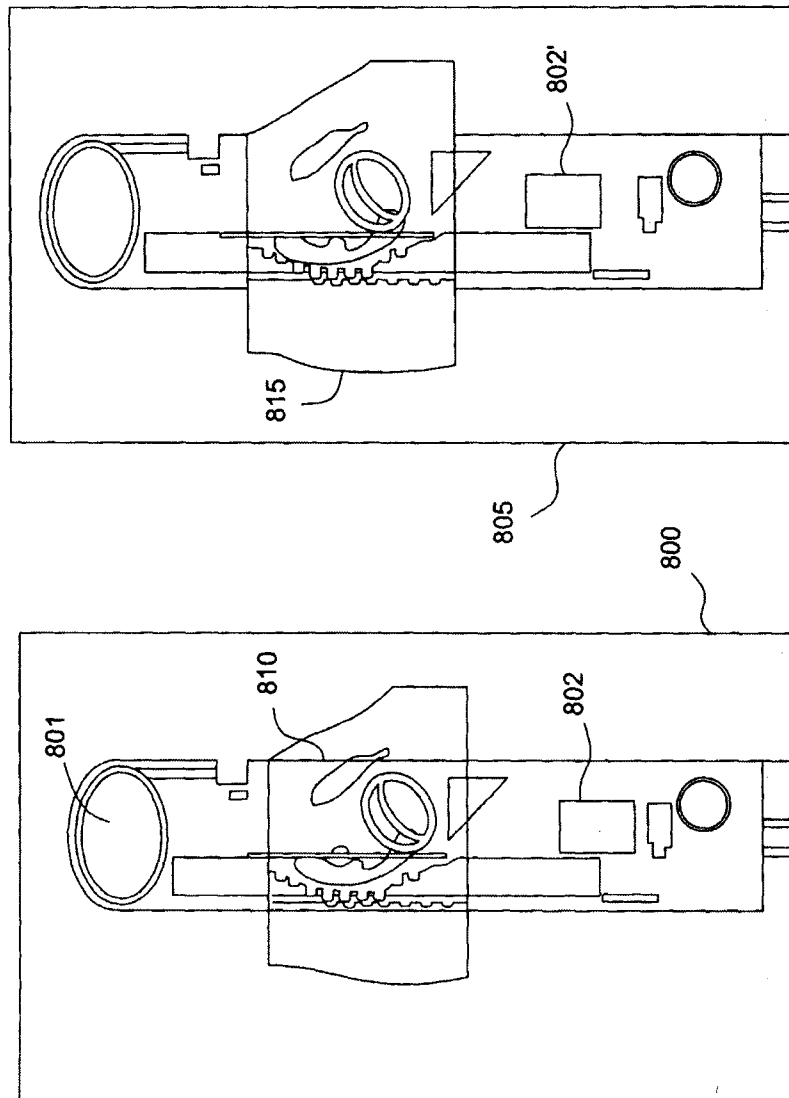


FIG. 8



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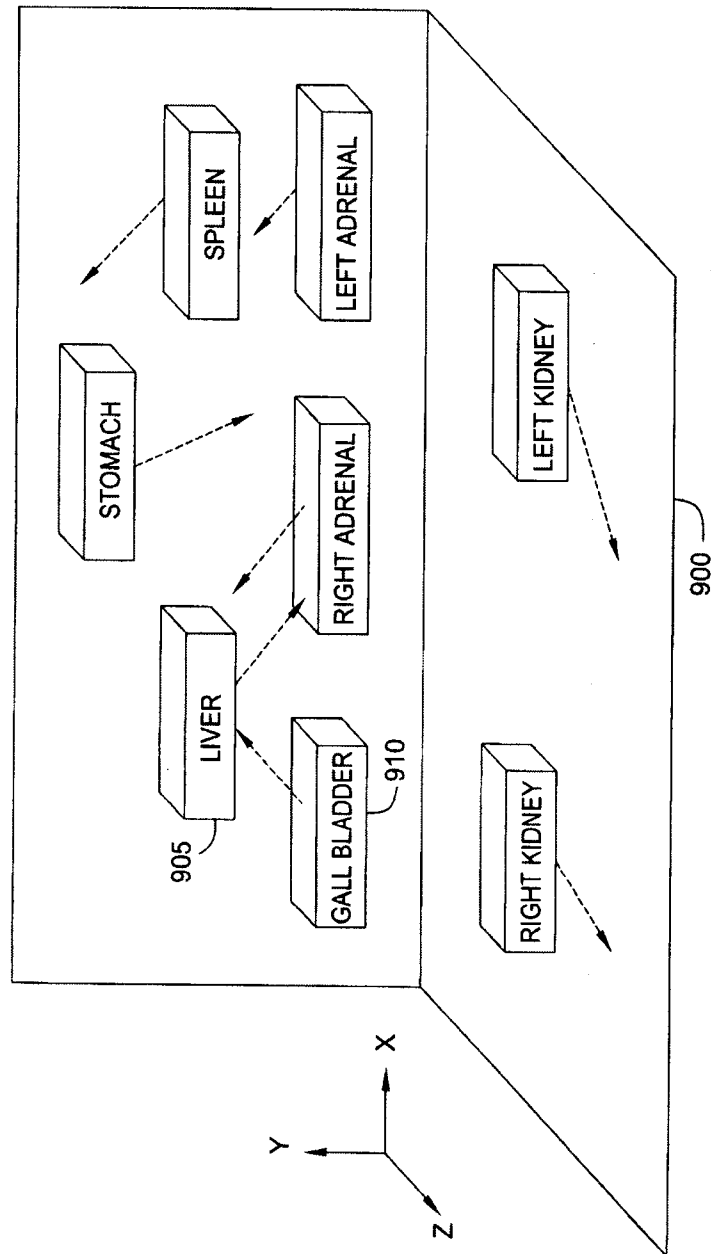


FIG. 9

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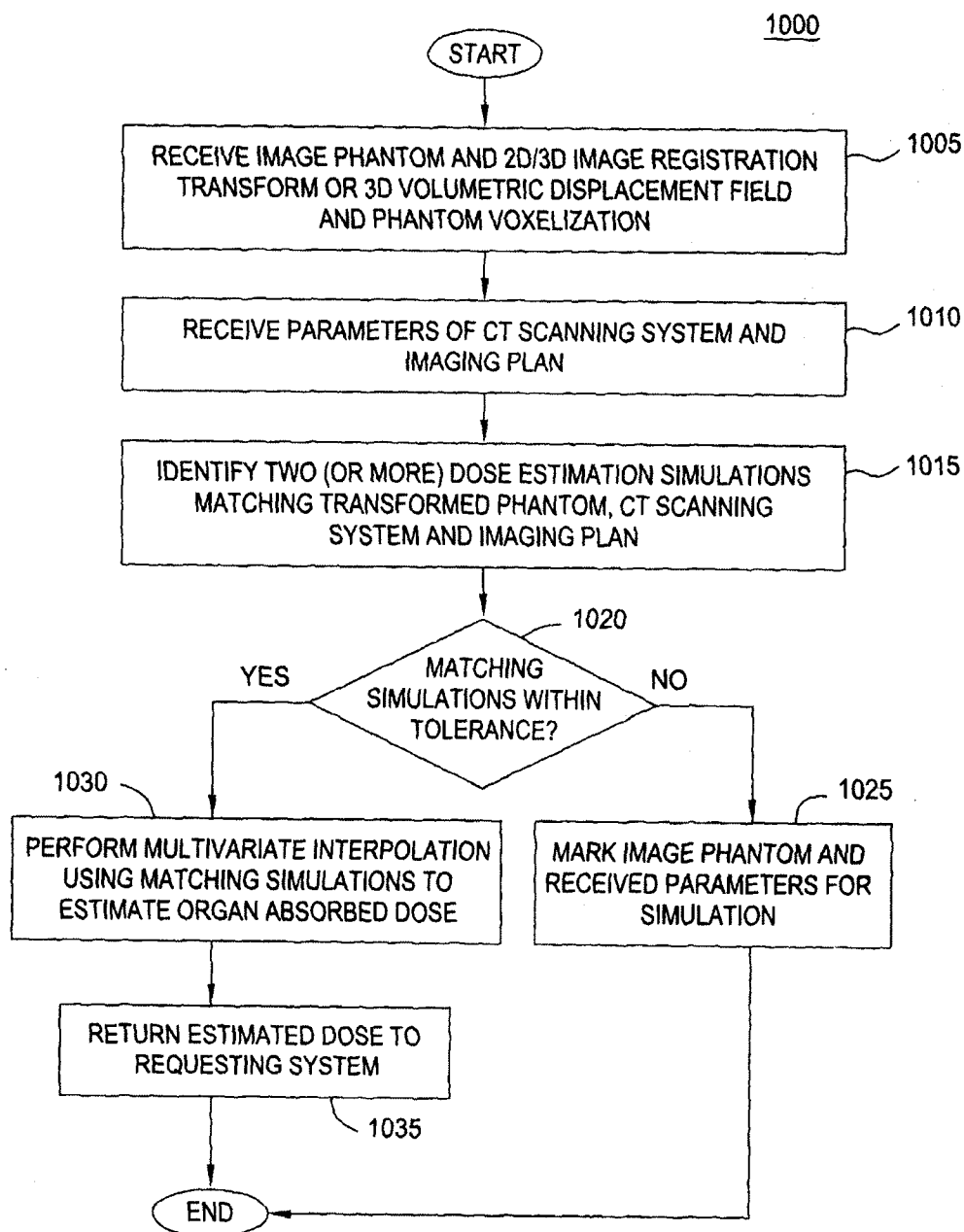


FIG. 10

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