



US 2003009208A1

(19) **United States**

(12) **Patent Application Publication**

**Snyder et al.**

(10) **Pub. No.: US 2003/0009208 A1**

(43) **Pub. Date:**

**Jan. 9, 2003**

(54) **TORQUEABLE SOFT TIP MEDICAL DEVICE AND METHOD OF USAGE**

**Related U.S. Application Data**

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(60) Provisional application No. 60/302,685, filed on Jul. 5, 2001.

**Publication Classification**

(51) **Int. Cl.<sup>7</sup>** ..... A61N 1/05  
(52) **U.S. Cl.** ..... 607/116

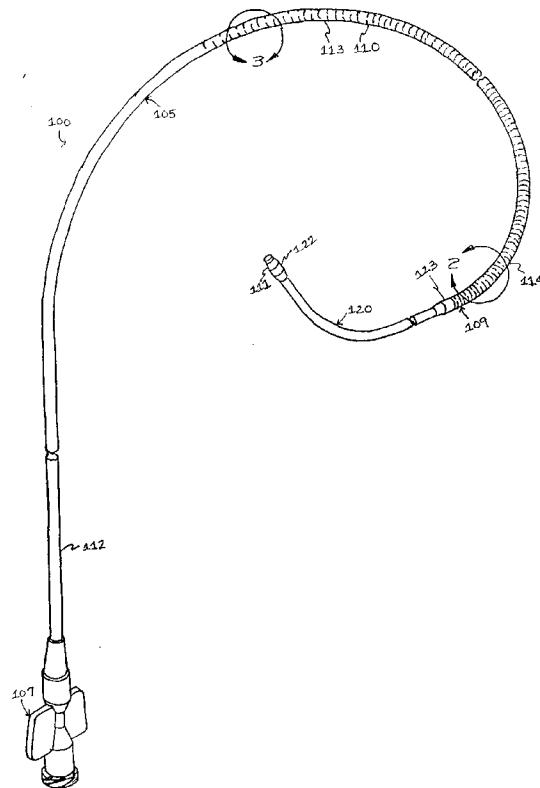
**ABSTRACT**

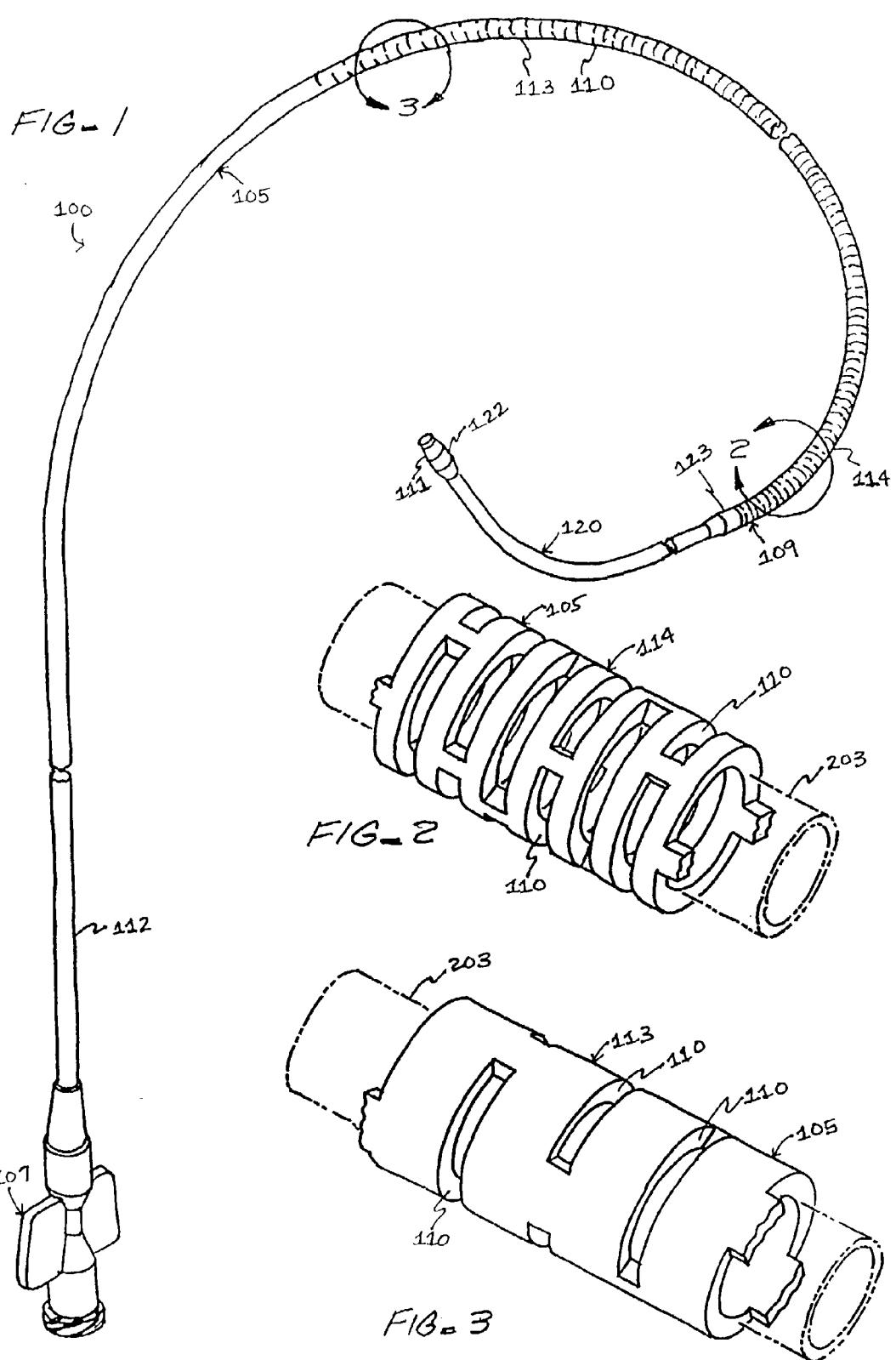
A medical device or intravascular device, and methods of use. The devices may be tubular and may have a flexible polymer tip. The body may be nitinol and may have cuts part way through along its length to facilitate bending. The device may have a liner which may extend through the tip or form the tip. The device may have markers readily visible on an X-ray viewer during insertion. The tip may have an anti-collapsing structure and may be shaped before use to perform a medical procedure such as treating an aneurysm. The device may have a strong fiber through it for complete removal. The method may include selecting the device, bending the tip, setting the shape, and inserting the device into the patient's anatomy. The shape of the tip may be set by heating with steam and then removing a mandrel.

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(21) Appl. No.: **10/188,929**

(22) Filed: **Jul. 3, 2002**





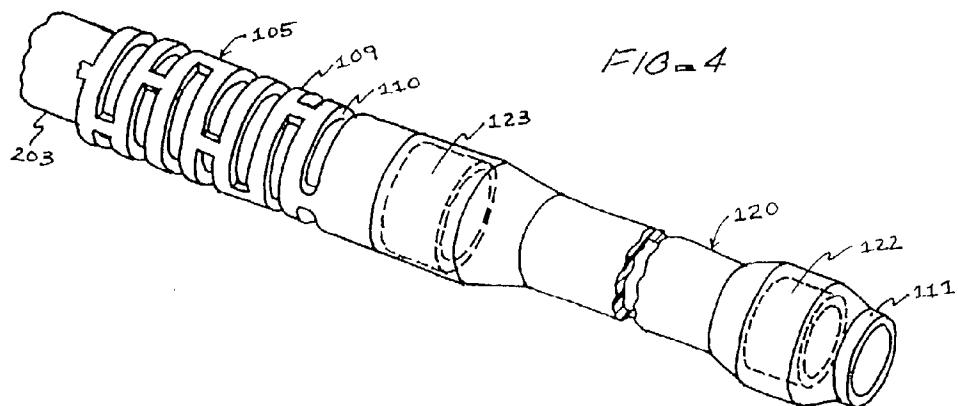


FIG. 5

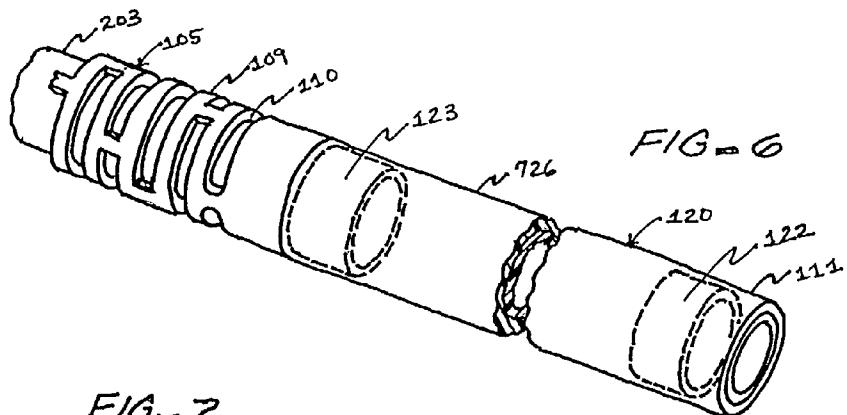
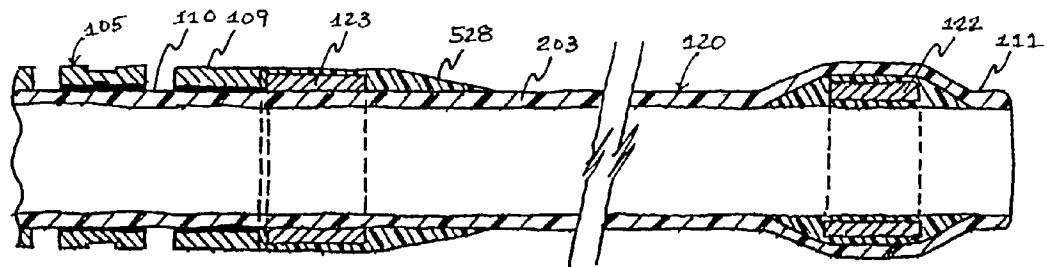
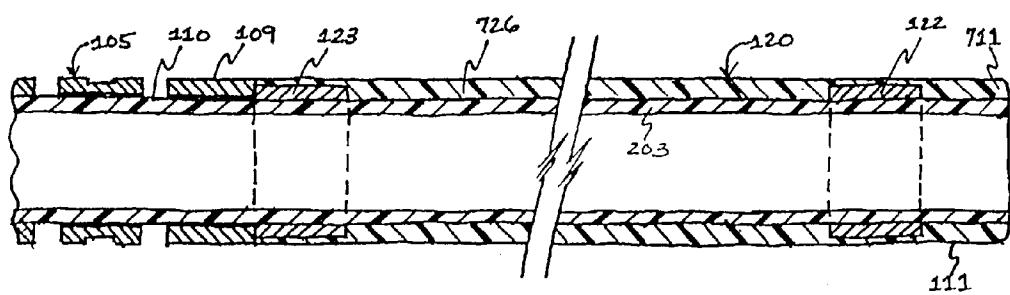


FIG. 7



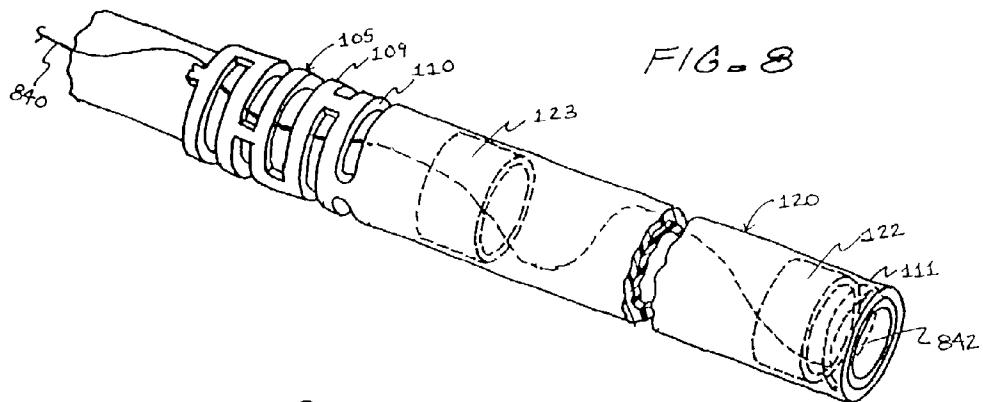


FIG. 8

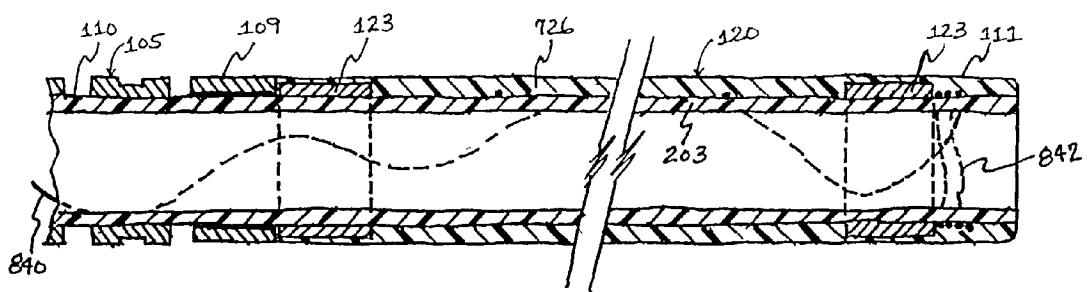


FIG. 9

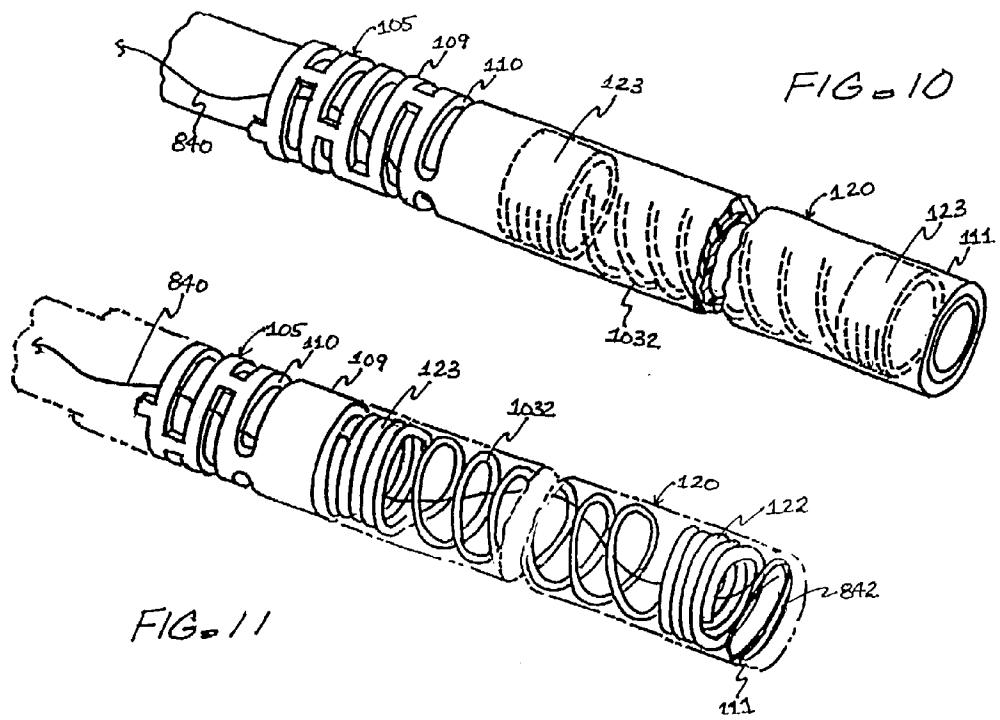


FIG. 10

FIG. 11

FIG - 12

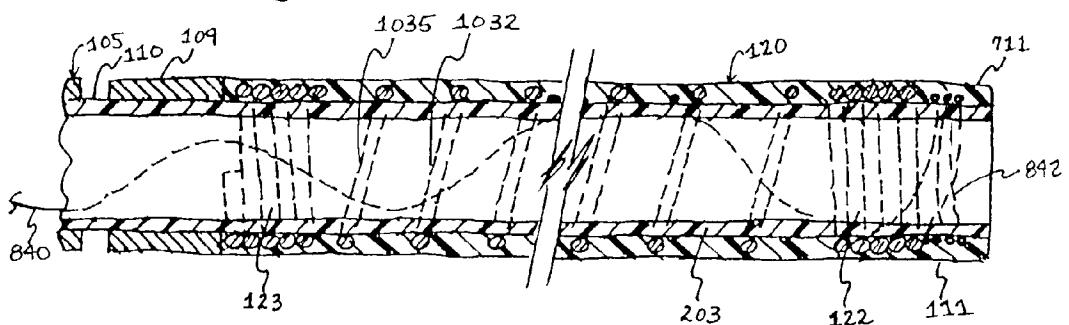


FIG - 14

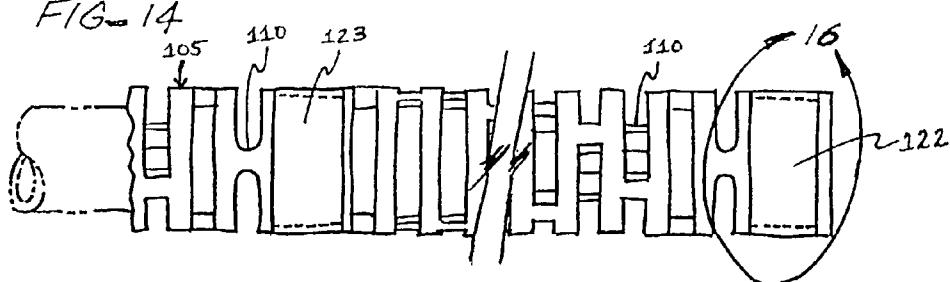
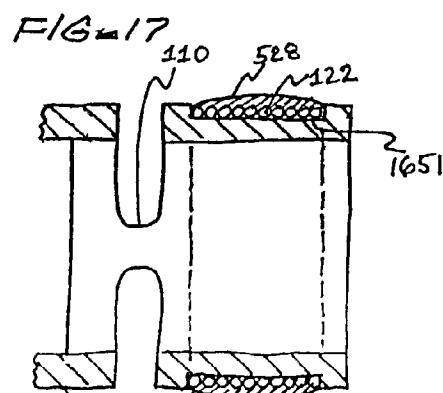
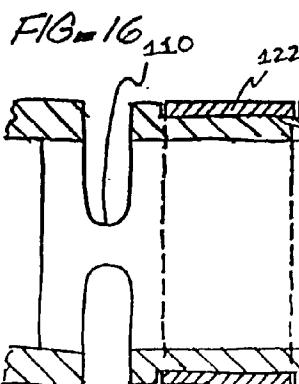
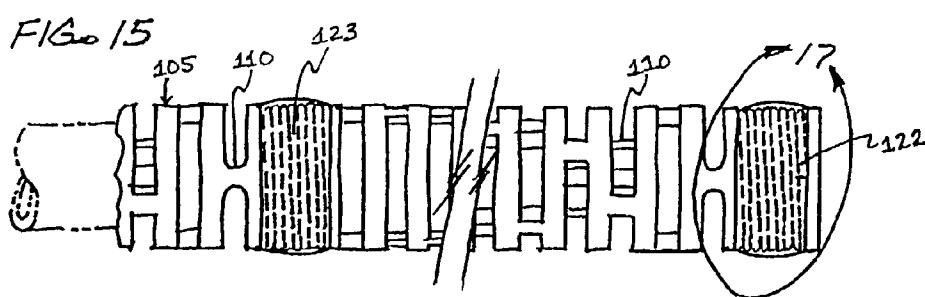


FIG - 15



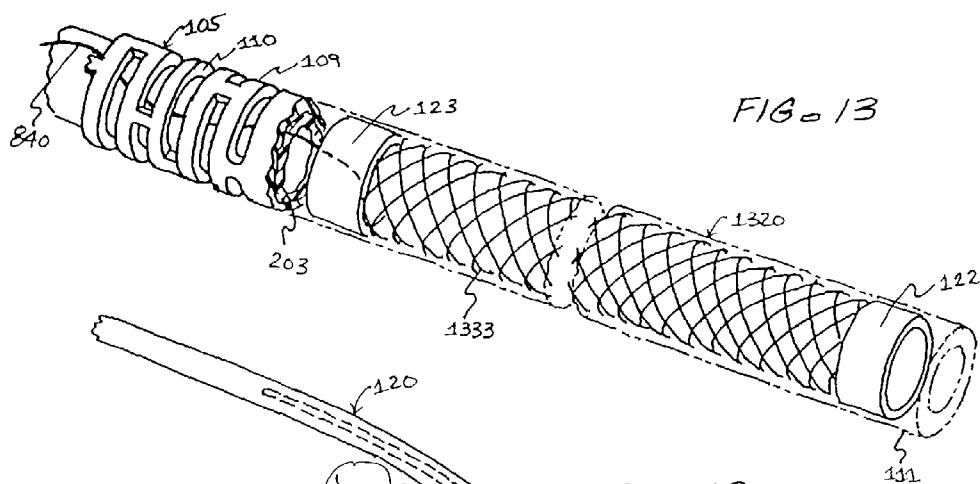


FIG. 18

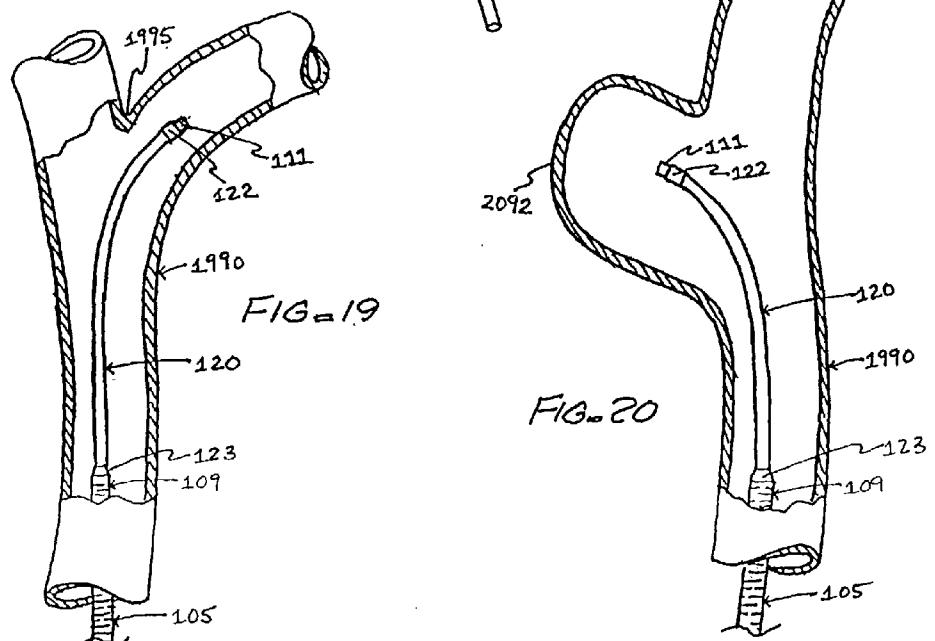
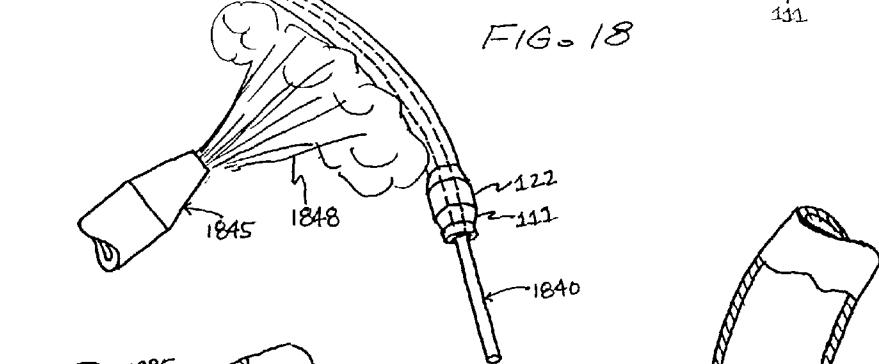
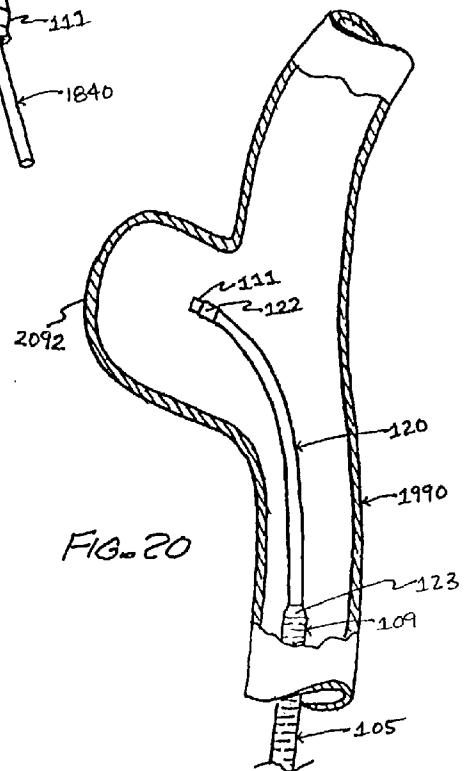


FIG. 20



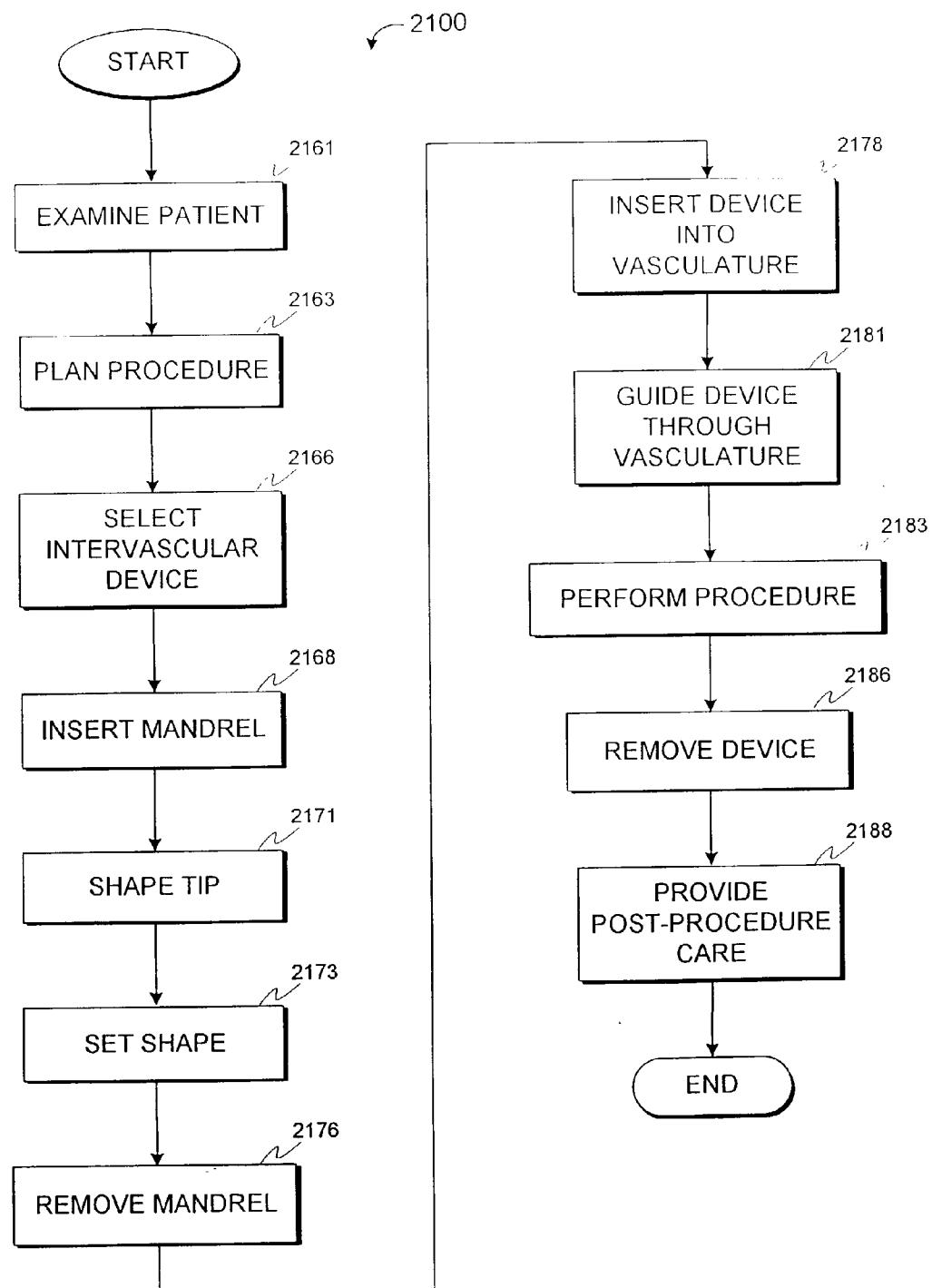


FIG. 21

**TORQUEABLE SOFT TIP MEDICAL DEVICE AND METHOD OF USAGE****CROSS REFERENCE TO RELATED APPLICATIONS**

**[0001]** This application claims priority to U.S. Provisional Application Serial No. 60/302,685, filed Jul. 5, 2001, entitled "Catheter Guidewire Apparatus."

**FIELD OF INVENTION**

**[0002]** This invention relates generally to flexible medical devices and methods of using them.

**BACKGROUND OF THE INVENTION**

**[0003]** Medical devices such as endovascular or intravascular devices have been used for many years for purposes such as performing medical procedures, including treating aneurysms. A medical device such as an intravascular device may be introduced into a patient's anatomy or vasculature at a relatively accessible location, and guided through the patient's anatomy to the desired location. X-ray fluoroscopy has been used to observe the tip of the medical device and the device has been rotated at bifurcations in the anatomy or vasculature before being pushed further to guide the device to the desired location. Medical devices of this type may be solid, for example, a guide wire, or may be hollow and tubular, for example, a catheter. Guide wires may be used to guide one or more tubular intravascular devices to a particular location, and catheters may be used, for instance, to deliver fluids, extract fluids, or deliver various objects, agents, or devices to the particular location.

**[0004]** In many applications it is desirable that a medical device or intravascular device bend easily in order to allow it to make the various bends and turns that are necessary to navigate through the anatomy or vasculature, and in some cases also to minimize trauma to the anatomy or vasculature. However, in many applications it is desirable that the medical device be relatively stiff in torsion in order to allow precise control of rotation in order to guide the device through bifurcations in vasculature or around obstacles. Accordingly, medical and intravascular devices have been described that contain numerous cuts along their length to obtain the desired flexibility in bending while maintaining relative stiffness in torsion. Examples of such devices are described in U.S. Pat. Nos. 5,690,120 and 5,833,632, both of which are incorporated herein by reference in their entirety. An example of a method of making such devices is described in U.S. Pat. No. 6,260,485 B1, which is also incorporated herein by reference in its entirety.

**[0005]** In many applications, it is desirable that the tip of a medical device be soft and bendable so as to minimize trauma to the patient's anatomy and further facilitate negotiating bends and turns in the anatomy or vasculature. Thus, a need exists for such a soft and bendable tip. In addition, the tip of a medical device may be bent or curved so that when the device approaches a bifurcation, or other location where direction needs to be selected, the device may be steered in the correct direction. In the past, tips were bent or curved during initial fabrication of the device. However, in at least some applications, a greater or lesser curvature may be desirable. Accordingly, a need exists for a device wherein the angle or radius of bending or curvature of the tip may be

selected by the operator of the medical device, for instance, by the medical doctor performing a medical procedure with the medical device.

**[0006]** Furthermore, in many applications, it is desirable and important that the entire device be removed after the procedure is completed. Thus, it is desirable that the device have a strong and reliable tensile strength throughout its length so that it does not come apart when pulled out of the patient's anatomy or vasculature. Accordingly, a need exists to improve and provide redundancy in the tensile strength of a medical device to assure complete removal of the device.

**SUMMARY OF THE INVENTION**

**[0007]** The present invention provides medical devices including intravascular devices and methods of using medical devices and intravascular devices. Medical devices in accordance with the present invention may be, for example, a guide wire that may be hollow. Features and objects of various embodiments of the present invention include that the devices are flexible in bending, the devices and methods minimize trauma to the patient's anatomy, and the devices and methods assure complete removal of the medical device.

**[0008]** Accordingly, in at least partial fulfillment of these objects, an exemplary embodiment of the present invention includes a medical device that may be an intravascular device, that has a body with a proximal end and a distal end. The body may have a plurality of cuts part way through. The device may also have a tip extending from the distal end of the body, which may be substantially made of a non-metallic material. The tip may be more flexible in bending than the body, and may be configured to be custom shaped by the person who will operate the device. The body may be substantially comprised of metal, which may be super-elastic nitinol. The body may be substantially tubular, and may have at least one substantially tubular liner. The liner may extend from the proximal end of the body to the distal end of the body, and may further extend distal to the body. In some embodiments, the liner may be inside the body and extend through the body, and in some embodiments may further extend through the tip. In some embodiments, the tip may be essentially the distal end of the liner. In other embodiments, the tip may further have a tubular end sleeve, which may be substantially comprised of polymer. The tip may also have an anti-collapsing structure, which may be a groove, a coil, or a braid. The device may also have at least one marker. Some embodiments of the present invention include a fiber extending through the body, which may be configured to increase the device's tensile strength. The fiber may be substantially comprised of a high-strength material, and may zigzag between the body and the liner.

**[0009]** A further exemplary embodiment of the present invention includes a method of treating a patient with a medical device. The method may include the steps of selecting a medical device, which may have a flexible tip; shaping the tip, for instance by bending it; and inserting the device into the anatomy or vasculature. The step of inserting the device may include axially translating the device, rotating the device, and monitoring the distal end or tip. The tip may be made of a nonmetallic material and may have at least one marker to facilitate monitoring by observing it, for instance, with X-ray fluoroscopy. The method may also have the step, after the step of shaping, of setting the shape of the

tip, for example, by heating the tip. The device may be substantially tubular, and the method may also include the step, after the step of shaping, of removing a mandrel from the tip that had been previously inserted. After the device is inserted into the anatomy or vasculature, the method may include the step of performing a medical procedure using the device, for example, treating an aneurysm. The method may further include the step of removing the device, which may involve using a fiber running substantially through the device. The fiber may accordingly be configured to assure complete removal of the device.

#### BRIEF DESCRIPTION OF THE DRAWINGS

[0010] The figures in this document illustrate various exemplary embodiments of the present invention. Embodiments of the present invention may include part or all of the features shown in one of these drawings, or may include features from two or more figures. Embodiments of the present invention may also include features described in the specification, or limitations to features described in the specification. Furthermore, embodiments of the present invention may include features that would be familiar to a person of ordinary skill in the art having studied this document.

[0011] FIG. 1 is a side view illustrating an embodiment of a medical device in accordance with the present invention;

[0012] FIG. 2 is a detail isometric view illustrating a portion of the body and liner of the medical device illustrated in FIG. 1;

[0013] FIG. 3 is a detail isometric view illustrating another portion of the body and liner of the medical device illustrated in FIG. 1;

[0014] FIG. 4 is an isometric view showing an exemplary embodiment of the tip of a medical device in accordance with the present invention;

[0015] FIG. 5 is a sectional side view further illustrating the exemplary embodiment of the tip of the medical device shown in FIG. 4, illustrating the tip substantially comprising the liner;

[0016] FIG. 6 is an isometric view showing another exemplary embodiment of the tip of a medical device in accordance with the present invention;

[0017] FIG. 7 is a sectional side view further illustrating the exemplary embodiment of the tip of the medical device shown in FIG. 6, illustrating, among other things, an end sleeve;

[0018] FIG. 8 is an isometric view showing additional features that may be part of the tip of the medical device shown in FIG. 6, including a fiber;

[0019] FIG. 9 is a sectional side view further illustrating the additional features shown in FIG. 8;

[0020] FIG. 10 is an isometric view showing an exemplary embodiment of an anti-collapsing structure and markers that may be part of the tip of a medical device in accordance with the present invention;

[0021] FIG. 11 is an isometric view showing another exemplary embodiment of an anti-collapsing structure and

markers that may be part of the tip of a medical device in accordance with the present invention;

[0022] FIG. 12 is a sectional side view further illustrating the anti-collapsing structure and markers shown in FIG. 11;

[0023] FIG. 13 is an isometric view showing another exemplary embodiment of an anti-collapsing structure and markers that may be part of the tip of a medical device in accordance with the present invention;

[0024] FIG. 14 is a side view illustrating an embodiment of markers in accordance with the present invention;

[0025] FIG. 15 is a side view illustrating another embodiment of markers in accordance with the present invention;

[0026] FIG. 16 is a detail sectional side view showing the embodiment of markers illustrated in FIG. 14;

[0027] FIG. 17 is a detail sectional side view showing the embodiment of markers illustrated in FIG. 15;

[0028] FIG. 18 is a side view illustrating setting the tip of an exemplary embodiment of the present invention;

[0029] FIG. 19 is a cut-a-way side view illustrating using the bend in the tip of a medical device in accordance with an exemplary embodiment of the present invention to facilitate navigation through a bifurcation in vasculature;

[0030] FIG. 20 is a cut-a-way side view illustrating using the bend in the tip of a medical device in accordance with an exemplary embodiment of the present invention to treat an aneurysm; and

[0031] FIG. 21 is a flow chart illustrating steps of an exemplary embodiment of a method in accordance with the present invention.

#### DETAILED DESCRIPTION

[0032] The present invention provides medical devices and intravascular devices such as hollow guide wires, and methods of using medical devices and intravascular devices. Exemplary embodiments of medical devices in accordance with the present invention may be flexible in bending, minimize trauma to the patient's anatomy or vasculature, assure complete removal of the medical device, or provide a combination of these features. Other features may also be provided.

[0033] Accordingly, FIG. 1 illustrates an embodiment of a medical device 100 in accordance with the present invention that includes a body 105 that has a proximal end 107, a distal end 109, and an axis (longitudinal axis) extending through the proximal end 107 and the distal end 109. Medical device 100 may be, for example, an endovascular or intravascular device. The body 105 may have a plurality of cuts 110 (one of which is labeled 110 on FIG. 1) part way through the body 105, and the cuts 110 may be approximately or substantially perpendicular to the axis. The body 105 may have a portion 112 without any cuts 110, a portion 113 with cuts 110 relatively far apart, and a portion 114 with cuts 110 relatively close together. Exemplary embodiments of portions 113, and 114, and cuts 110 are illustrated in more detail in FIGS. 2 and 3. Cuts 110 may be saw cut, notched, laser cut, ground, EDMed, etched, forged, molded, or formed by another method suitable for shaping the material from which body 105 is made. The geometry of cuts 110

may be as shown, or in various embodiments may be of other geometries forming openings through the wall of body 105. Returning to FIG. 1, the spacing of cuts 110 may vary gradually from portion 113 to portion 114, or the spacing may vary discreetly. In some embodiments, the spacing of cuts 110 may be substantially uniform throughout all or part of body 105. In some embodiments, the geometry of cuts 110 may vary, for example, in width (in the direction of the axis of body 105) or depth.

[0034] Still referring to FIG. 1, medical device 100 may further include a tip 120 on the distal end of medical device 100, which may extend from the distal end 109 of body 105. As will be described in further detail below, tip 120 may substantially comprise one or more non-metallic materials, for example, a polymer material. Due in some embodiments to the properties of the material from which it is made, its dimensions, or both, tip 120 may be more flexible in bending than body 105. In other words, tip 120 may be a flexible tip. In addition, as will be described in more detail below, tip 120 may be configured to be custom shaped by the person who will operate the device 100, for example, to perform a medical procedure. Tip 120 may have its own distal end 111, for example on the far distal end of device 100. Tip 120 may be marked, for example, on the distal end 111 of tip 120, for example, with a marker band, or other indication. The presence of this marking or indication may be checked upon removal of device 100 from the patient to verify that all of device 100 has been completely removed. Tip 120 may be flared at distal end 111, for example, on the inside, or may be rounded, for example to minimize trauma to the anatomy or vasculature.

[0035] Referring to FIGS. 2 and 3, body 105 may be substantially comprised of metal, which may be a nickel-titanium alloy (nitinol). The nitinol may be a super-elastic nitinol, meaning its transition temperature may be below the use temperature. In many embodiments of the present invention, the use temperature may be human body temperature or room temperature. In other embodiments, body 105 may be a polymer material or stainless steel, or another material suitable for the application. Body 105 may be substantially tubular as shown, or in some embodiments, may be solid. Medical device 100 may further comprise a substantially tubular liner 203, which may extend the length of body 105, for example from proximal end 107 at least to distal end 109. Liner 203 may be located inside body 105 (as shown) or may be located outside body 105. Liner 203 may be located inside body 105, for example, to make the inside of device 100 smoother to reduce friction or abrasiveness, for example, for passing objects through the interior of device 100. Liner 203 may be located outside body 105, for example, to make the outside of device 100 smoother to reduce friction, abrasiveness, and trauma to the anatomy or vasculature. Some embodiments of the present invention may have two liners 203, one inside body 105 and one outside body 105.

[0036] Liner 203 may lack many or all of the cuts 110 of body 105, thus forming a barrier that may reduce or eliminate leakage between the interior and exterior of body 105. In other words, liner 203 may seal cuts 110. Liner 203 may be made of an elastomeric material. Liner 203 may be made of a polymer, such as a polyethylene blend, or PTFE. Liner 203 may further extend distal to body 105 (for example beyond distal end 109), for example, through tip 120, and,

as illustrated best in FIG. 5, in some embodiments, may substantially comprise or form tip 120. As used herein, tip 120 substantially comprises liner 203 in embodiments where tip 120 is comprised of part of liner 203, but tip 120 does not include a separate end sleeve 726 (illustrated in FIG. 7). As used herein, the statement that tip 120 substantially comprises liner 203 does not mean that tip 120 does not have markers 122 and 123, or an anti-collapsing structure (e.g. coil 1032 or braid 1333) (described below).

[0037] End sleeve 726 may be substantially tubular and is illustrated in FIGS. 6-13, and is a component of some embodiments of medical device 100. End sleeve 726 may have the same or a similar inside and outside diameter as distal end 109 of body 105 (illustrated best in FIG. 7), and may substantially comprise a polymer material. End Sleeve 726 may, for example, be a lamination of PEBAK, for instance, and may have a durometer hardness of 85A. Various hardnesses may be preferred for various applications and embodiments. End sleeve 726 may, in some embodiments, be attached to body 105, for example, with an adhesive. In some embodiments of tip 120, liner 203 and end sleeve 726 may be attached to each other, for example with an adhesive (e.g. cyanoacrylate), or may not be attached to each other, e.g. to promote flexibility of tip 120. Embodiments having two liners 203 (for example, a first liner 203 inside the body and a second liner 203 outside the body) may have an end sleeve 726 disposed between the two liners 203. In embodiments with either one or more liners, the end sleeve 726 may extend beyond (distal to) the end or ends of one or more liners 203. In other words, one or more liners 203 may terminate substantially proximal to the distal end 711 of end sleeve 726. As used here, substantially proximal means at least 10 percent of the length of tip 120 from the distal end 711 of end sleeve 726.

[0038] As illustrated in FIGS. 10-13, tip 120 of medical device 100 may further comprise an anti-collapsing structure, which may be coil 1032 as illustrated in FIGS. 10-12 or braid 1333 as illustrated in FIG. 13. The anti-collapsing structure (e.g. coil 1032 or braid 1333) may be located between liner 203 and end sleeve 726 as illustrated best in FIG. 12. In some embodiments, the anti-collapsing structure may be one or more grooves 1035 as illustrated in FIG. 12. Groove 1035 may be a helical groove (shown), or may be a plurality of circular grooves, for example circumferential to the axis of body 105 or medical device 100. Groove 1035 may be cut in part of tip 120, for example, liner 203 or end sleeve 726 (shown). Groove 1035 may be cut on the inside (shown) or the outside, depending on the embodiment. As would be apparent to a person skilled in the art, the outside may be more accessible for cutting groove 1035, particularly in smaller diameter embodiments of device 100. Coil 1032 may be located inside groove 1035 (for example, where groove 1035 is helical). In other embodiments, groove 1035 may be hollow or may contain another component or material. For example, in embodiments having a plurality of circumferential grooves 1035, rings may be disposed in grooves 1035, e.g. rings comprised of a metal or polymer, which may have a substantially higher stiffness (e.g., modulus of elasticity) than liner 203 or end sleeve 726.

[0039] Medical device 100 may comprise at least one tip marker 122 or 123 as illustrated in FIGS. 1 and 4-20. As illustrated, many embodiments include two markers, marker 122 at the distal end 111 of tip 120 and marker 123 at the

base of tip **120**, for example, near distal end **109** of body **105**. As used herein, the statement that tip **120** substantially comprises a non-metallic material means, for example, that liner **203** and exterior portion **726** (in embodiments where provided) are not made of metal, but markers **122** and **123**, and anti-collapsing structure (e.g. coil **1032** or braid **1333**) may be any material including a metal. Markers **122** and **123** may be made of a material such as platinum that is readily distinguishable with X-ray fluoroscopy. Markers **122** and **123** may be short tubular sleeves or bands as illustrated in FIGS. 4-10, 13, 14, and 16, or may be coils as illustrated in FIGS. 11, 12, 15, and 17. In some embodiments having an anti-collapsing structure that is a coil **1032**, markers **122**, **123**, or both, may be formed from the same wire as coil **1032**, and may be integral therewith. For illustration, see FIG. 11. In other embodiments, markers **122** and **123** may be coils but may be separate components from coil **1032**. The coils of markers **122** and **123** may be closer together (i.e. in the axial direction) than the coils of coil **1032** as shown. The coils of markers **122** and **123** may, in fact, be touching each other or nearly touching. The markers **122** and **123** may be located between liner **203** and end sleeve **726** as illustrated best in FIGS. 7, 9, and 12. Markers **122** and **123** may be covered all or in part by a material **528** (as illustrated best in FIG. 5 for marker **123**) that may be smooth, soft, slippery, or some combination thereof to minimize trauma to the patient's anatomy or vasculature **1990**. Material **528** may be an adhesive, for example, a UV adhesive. In some embodiments, for example, not having an end sleeve **726**, markers **122** and **123** may be located inside liner **203** (as illustrated in FIG. 5 for marker **122**).

[0040] There may be an interference fit between marker **122** or **123** and liner **203**. And, there may be an interference fit between marker **122** or **123** and end sleeve **726**. Such interference fits may hold markers **122** and **123** in place. Markers **122** and **123** may also be held in place with an adhesive, or may be thermally fused, i.e. by melting a polymer such as a thermal plastic around marker **122** or **123**. Material **528** shown in FIG. 5, for example, may be an adhesive or a polymer. In some embodiments, markers **122**, **123**, or both may be recessed in a groove **1651** as illustrated in FIGS. 14-17. Groove **1651** may be cut, for example, in body **105** as shown, but may alternatively be cut in liner **203** or end sleeve **726**, for further example. Markers **122** and **123** may be short cylinders or sleeves as illustrated in FIGS. 14 and 16, which may be crimped or swaged into groove **1651**. In another embodiment, illustrated in FIGS. 15 and 17, markers **122** and **123** may be coils, which may be expanded to install them in groove **1651**. Markers **122** and **123** may be covered with a material **528** as described above and as illustrated in FIGS. 15 and 17 to help hold markers **122** and **123** in place or to minimize trauma to the patient's anatomy or vasculature **1990**.

[0041] As illustrated in FIGS. 8-13, medical device **100** may have a fiber **840** extending through body **105**. Fiber **840** may be configured to provide tensile strength (for example, redundant tensile strength) to medical device **100** or increase its tensile strength, for example, to assure complete removal of device **100** from the patient. As used herein, being configured to increase the tensile strength of device **100** includes increasing device **100**'s ultimate tensile strength, and providing redundancy in the tensile strength of device **100**, for example, in case body **105**, liner **203**, or another component or joint has less tensile strength than anticipated.

Thus, in some embodiments, fiber **840** may have a greater tensile strength than the remainder of medical device **100**, but in other embodiments fiber **840** may have a lower tensile strength than a properly manufactured and undamaged device **100**. Fiber **840** may substantially comprise a material selected for its high tensile strength. Fiber **840** may be a polymer, a metal, a carbon fiber, a ceramic fiber, or a combination of fibers. Fiber **840** may be formed from a composite material, and the fibers of the composite material may be substantially aligned in the axial direction of fiber **840**. Fiber **840** may, for example, be made of KEVLAR.

[0042] Fiber **840** may be located between body **105** and liner **203**, and may bend back and forth or zigzag, for example in a somewhat sinusoidal pattern, be bunched, or wound in a spiral, so as to avoid or minimize increasing the bending stiffness of medical device **100** or maintain symmetrical bending properties of medical device **100** around its longitudinal axis. For example, fiber may zigzag back and forth over approximately  $\frac{1}{2}$  of the diameter of device **100**. This zigzag pattern may, for instance, continue along one side of device **100**, or may gradually spiral around device **100**. Fiber **840** may wind (for example winds **842**) around at least part of the components of tip **120**, for instance, to help secure tip **120** to fiber **840**. For example, fiber **840** may wind (winds **842**) around liner **203** (shown) or end sleeve **726**. Fiber **840** may be secured, for instance, to tip **120**, for example, by being glued, twisted, or tied. Some embodiments may have a plurality of fibers **840**. For example, in one embodiment device **100** may have two fibers **840** that may zigzag, for example, on opposite sides, or may spiral in opposite directions.

[0043] Various dimensions of tip **120** may be desirable for various embodiments of the present invention. Specifically, in various embodiments, tip **120** may be from as little as 1 millimeter in length to as long as 1500 millimeters in length. Other embodiments may even be outside of this range. Shorter lengths (e.g. as short as 1 millimeter long) may, for example, provide a soft tip **120** for medical device **100**, which may reduce trauma to the patient's anatomy, for example, compared with having no tip **120** at all. Longer tips **120** may offer the other advantages described herein. Some embodiments of the present invention may have a tip **120** that is 10 to 40 millimeters long. For instance, embodiments of the present invention may have a tip **120** that is 31 millimeters long, and markers **122** and **123** may be 30 millimeters apart on embodiments having such markers. Such lengths may offer the various features and advantages described herein.

[0044] In addition, various outside diameters of medical device **100** may be desirable for various embodiments of the present invention. Generally, body **105** may have an outside diameter in the range of 0.010 to 0.500 inches. Other embodiments may even be outside of this range. For instance, some embodiments may be larger in diameter. However, within the range identified, some embodiments of the present invention may have a body with an outside diameter in the range of 0.030 to 0.040 inches. For example, embodiments of the present invention may have a body **105** with an outside diameter of 0.033 inches. Other embodiments may have a body with an outside diameter in the range of 0.020 to 0.040 inches. Still other embodiments may have a body with an outside diameter in the range of 0.015 to 0.040 inches. In some embodiments, the diameter of body

**105** may vary along its length, for example, with the largest diameter at the proximal end **107** and the smallest diameter at the distal end **109**. The outside diameter of tip **120** may be similar or less than the outside diameter of body **105**, for instance, 0.033 inches.

[0045] Furthermore, various lengths of medical device **100** may be desirable for various embodiments of the present invention. Medical device **100** may be, for example, 155 centimeters long. Referring to FIG. 1, portions **112** and **113** with cuts **110**, and tip **120**, may total, for example, 48 centimeters long.

[0046] Turning now to methods of using, for example, medical device **100**, FIG. 18 illustrates how tip **120** of medical device **100** may be set in shape with steam **1848** and mandrel **1840** prior to using medical device **100**. FIG. 19 illustrates how the shape or curvature of tip **120** may be used to navigate medical device **100** through a bifurcation **1995** in the patient's anatomy or vasculature **1990**. FIG. 20 further illustrates how the shape or curvature of tip **120** may be used to treat an aneurysm **2092** in the patient's vasculature **1990**. Even further, FIG. 21 illustrates various steps of an exemplary embodiment of a method in accordance with the present invention, method **2100**.

[0047] Method **2100** illustrates a method of treating a patient with a medical device (e.g. device **100**). First, the physician, for example, may examine the patient (step **2161**) to determine what the problem is (e.g. an aneurysm) and plan the procedure (step **2163**), for example, to correct the problem. Method **2100** then generally includes the step of selecting a medical device (step **2166**), which may have various attributes of medical device **100**, described above such as having a tip **120** or cuts **110**. Selecting medical device **100** may include, for example, choosing the desired diameter and length of device **100**. Various other features may be selected, including those features and embodiments described herein. Method **2100** also includes shaping (step **2171**) tip **120**, which may comprise bending tip **120**; and inserting (step **2178**) medical device **100** into anatomy or vasculature **1990**. Then the physician or operator may guide (step **2181**) the device **100** through the anatomy or vasculature (e.g. **1990**). Inserting (step **2178**) or guiding (step **2181**) may comprise axially translating medical device **100**, rotating medical device **100**, and monitoring the distal end **109** or tip **120** (e.g. distal end **111**) of medical device **100**. For example, as illustrated in FIG. 19, when medical device **100** approaches a bifurcation **1995**, for instance, in vasculature **1990**, the operator may rotate the proximal end **107** (shown in FIG. 1) of device **100** while monitoring or observing marker **122** on distal end **111** of tip **120**, and possibly also marker **123**, for example, with an X-ray viewer. When marker **122**, and thus distal end of device **100** and tip **120** (distal end **111**), is pointed toward the desired passageway of vasculature **1990**, the operator may then push medical device **100** further into vasculature **1990** so that tip **120** goes into the desired passageway.

[0048] Method **2100** may further comprise the step, after shaping tip **120** (step **2171**), of setting (step **2173**) the shape of tip **120**. Setting (step **2173**) the shape may comprise heating tip **120**, as illustrated in FIG. 18. Medical device **100** may be substantially tubular, and method **2100** may further comprise the step, after shaping tip **120** (step **2171**), of removing (step **2176**) a mandrel **1840** from tip **120**. Thus,

tip **120** may be shaped (step **2171**) by bending tip **120** while a mandrel **1840** is inside tip **120**. The mandrel **1840**, which may be wire, for example, stainless steel, will then hold the shape of tip **120** while tip **120** is heated, for instance, with steam **1848** produced by steam source **1845**. Thus, the operator or physician who is about to perform the medical procedure (step **2183**) with medical device **100**, may bend (step **2171**) tip **120** based on the shape needed for the particular procedure and the patient's particular anatomy. The physician may then set the shape (step **2173**) by heating tip **120** with a steam source **1845** that may be readily available. Then the physician may remove mandrel **1840** (step **2176**), leaving tip **120** with the desired shape, but flexible. Mandrel **1840** may have been inserted (step **2168**) by the physician, or may have been inserted by the manufacturer of device **100** before shipment to the physician.

[0049] Method **2100** may further comprise the step, after inserting medical device **100** into the anatomy or vasculature **1990** (step **2178**), of performing a medical procedure step **2183** using medical device **100**. The medical procedure (of step **2183**) may be, for example, treatment of aneurisms, AVMs, bleeds, tumors, embolisms, embolic stroke thrombolysis, and thrombolectomy. In an exemplary embodiment, the procedure (of step **2183**) may include treating an aneurysm **2092** as illustrated in FIG. 20, for example, a cerebral or brain aneurysm. Such a treatment may involve, for example, introduction of an agent such as a glue material through device **100**, stenting, installation of a graft, or balloon immobilization. Other procedures (of step **2183**) may include obtaining access to the uterus, fallopian tubes, urinary tract, sinuses, esophagus, lungs, vertebroplasty, and gastroenterology. A gradual curvature of tip **120** is shown in FIG. 20; however, tip **120** may be shaped in radial bends, for example from 5 degrees to 120 degrees or in other complex shapes as needed by the physician. The length of tip **120** extending distal to the bend may be selected based on the size of the aneurysm **2092**, the size of the vasculature **1990**, and other factors.

[0050] Method **2100**, may further comprise the step of removing medical device **100** (step **2186**). This may involve using fiber **840** described above, for example, running substantially through medical device **100**. To remove medical device **100**, the operator or physician may pull on the proximal end **107** of medical device **100**. If medical device **100** should pull apart or break, for example, tip **120** should separate from body **105**, then fiber **840** may be utilized to facilitate or assure complete removal of medical device **100**, including tip **120**. To do so, the operator or physician may continue pulling on proximal end **107**. After the slack is taken up from fiber **840**, fiber **840** will then pull on tip **120**. Accordingly, Fiber **840** may be configured to facilitate or assure complete removal of medical device **100**. The physician may also provide post-procedure care (step **2188**) to the patient, for example, verifying that the problem is corrected and that no complications have developed.

[0051] The above embodiments are illustrative of the present invention, but are not intended to limit its scope. Numerous modifications and alternative arrangements may be devised by those skilled in the art without departing from the spirit and scope of the present invention, and the appended claims are intended to cover such modifications and arrangements.

What is claimed is:

1. A medical device comprising:
  - a body having a proximal end and a distal end, said body having a plurality of cuts part way through said body; and
  - a tip extending from said distal end of said body, said tip substantially comprising a non-metallic material
2. The device of claim 1, said tip being more flexible in bending than said body.
3. The device of claim 1:
  - said tip having a length that is greater than one millimeter; and
  - said tip having a length that is less than 1500 millimeters.
4. The device of claim 1:
  - said tip having a length that is greater than 10 millimeters, and said tip having a length that is less than 40 millimeters
5. The device of claim 1:
  - said tip having an outside diameter that is greater than 0.01 inches; and
  - said tip having an outside diameter that is less than 0.5 inches.
6. The device of claim 1:
  - said tip having an outside diameter that is greater than 0.030 inches; and
  - said tip having an outside diameter that is less than 0.040 inches.
7. The device of claim 1:
  - said tip having an outside diameter that is greater than 0.020 inches; and
  - said tip having an outside diameter that is less than 0.030 inches.
8. The device of claim 1:
  - said tip having an outside diameter that is greater than 0.015 inches; and
  - said tip having an outside diameter that is less than 0.025 inches.
9. The device of claim 1, said tip being configured to be custom shaped by a person who will operate said device to perform a medical procedure.
10. The device of claim 1, said body being substantially comprised of metal.
11. The device of claim 10, said metal being super-elastic nitinol
12. The device of claim 1:
  - said body being substantially tubular; and
  - the device further comprising a substantially tubular liner
13. The device of claim 12:
  - said liner extending at least from said proximal end to said distal end; and
  - said liner further extending distal to said body.
14. The device of claim 13, said tip substantially comprising said liner.
15. The device of claim 13, said liner being inside said body.

16. The device of claim 13:
  - said tip further comprising a substantially tubular end sleeve; and
  - said end sleeve substantially comprising polymer.
17. The device of claim 16:
  - said end sleeve having a distal end;
  - said liner terminating substantially proximal to said distal end of said end sleeve.
18. The device of claim 1:
  - further comprising a substantially tubular liner and said body being inside said liner
19. The device of claim 1:
  - said body being substantially tubular;
  - the device further comprising a first liner and a second liner;
  - said first liner being inside said body; and
  - said body being inside said second liner.
20. The device of claim 19, said device further having an end sleeve:
  - said end sleeve being between said first liner and said second liner.
21. The device of claim 1, said tip further comprising an anti-collapsing structure.
22. The device of claim 21, said anti-collapsing structure comprising at least one groove.
23. The device of claim 21, said anti-collapsing structure comprising a coil
24. The device of claim 21:
  - said anti-collapsing structure comprising a coil; and
  - said coil being at least partially in a groove.
25. The device of claim 21, said anti-collapsing structure comprising a braid.
26. The device of claim 1, said device comprising at least one marker.
27. The device of claim 1, said device comprising two markers.
28. A medical device having a tensile strength, the device comprising:
  - a body having a proximal end and a distal end, said body having a plurality of cuts part way through said body, and
  - a fiber extending through said body, said fiber being configured to increase the tensile strength of the device.
29. The device of claim 28, said fiber substantially comprising one or more materials selected from the group consisting of: polymers, metals, carbon fibers, and ceramic fibers.
30. The device of claim 28:
  - the device further comprising at least one substantially tubular liner;
  - said liner extending from said proximal end at least to said distal end;
  - said fiber being located between said body and said liner.
31. The device of claim 30, said fiber being arranged substantially in a zigzag configuration.

**32.** A method of treating a patient with a tubular medical device, the patient having anatomy, the method comprising the steps of:

selecting a medical device, the device having a flexible tip;

shaping the tip, said shaping comprising bending, and inserting the device into the anatomy, said inserting comprising axially translating the device, rotating the device, and monitoring the distal end.

**33.** The method of claim 32, the device having:

a body having a proximal end and a distal end, the body having a plurality of cuts part way through the body; and

the tip extending from the distal end of the body, the tip substantially comprising a non-metallic material.

**34.** The method of claim 32 further comprising the step, after said shaping, of setting the shape of the tip.

**35.** The method of claim 34 said setting the shape comprising heating the tip.

**36.** The method of claim 32 the device being substantially tubular and comprising at least one substantially tubular liner, the liner extending from the proximal end to the distal end.

**37.** The method of claim 32, the device being substantially tubular, the method further comprising the step, after said shaping, of removing a mandrel from the tip.

**38.** The method of claim 32 further comprising the step, after said inserting, of performing a medical procedure using the device.

**39.** The method of claim 39, the procedure comprising treating an aneurysm.

**40.** The method of claim 32, the tip having at least one marker, said monitoring comprising observing the marker

**41.** The method of claim 32, further comprising the step of removing the device, the device having a fiber running substantially through the device, the fiber being configured to assure complete removal of the device.

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