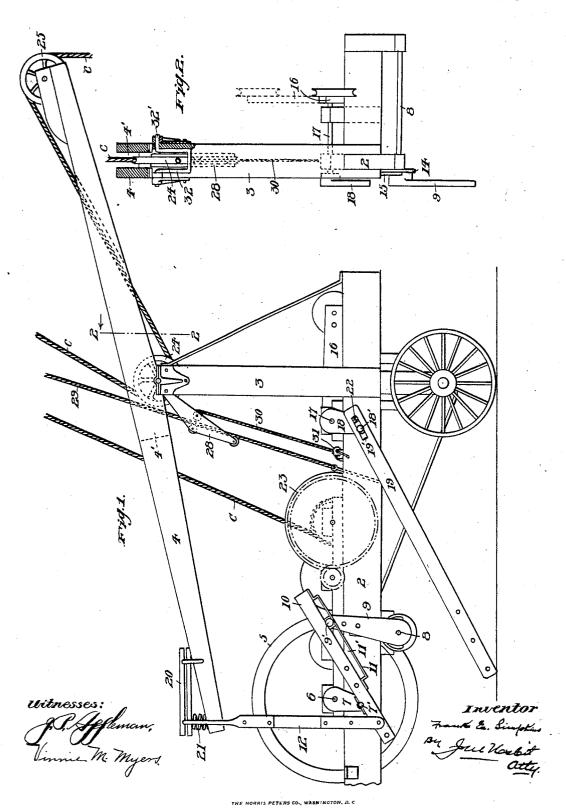
# F. E. SIMPKINS. WELL DRILLING MACHINE. APPLICATION FILED FEB. 14, 1906.

4 SHEETS-SHEET 1.

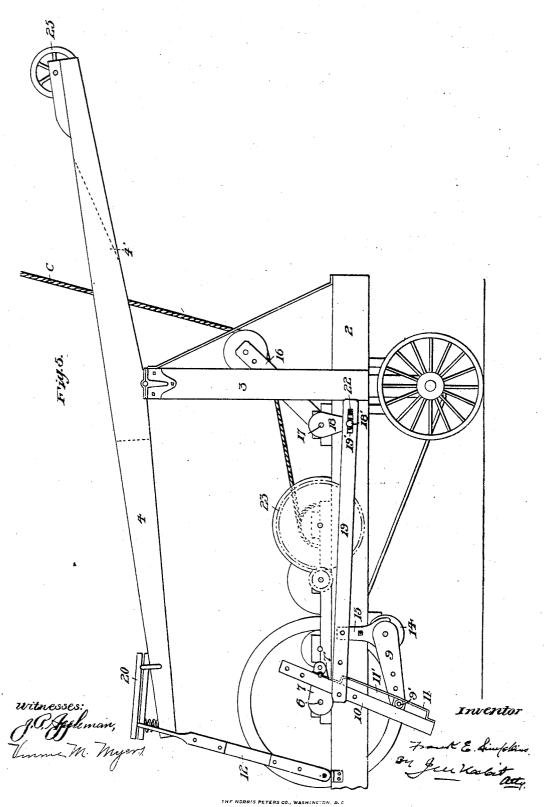


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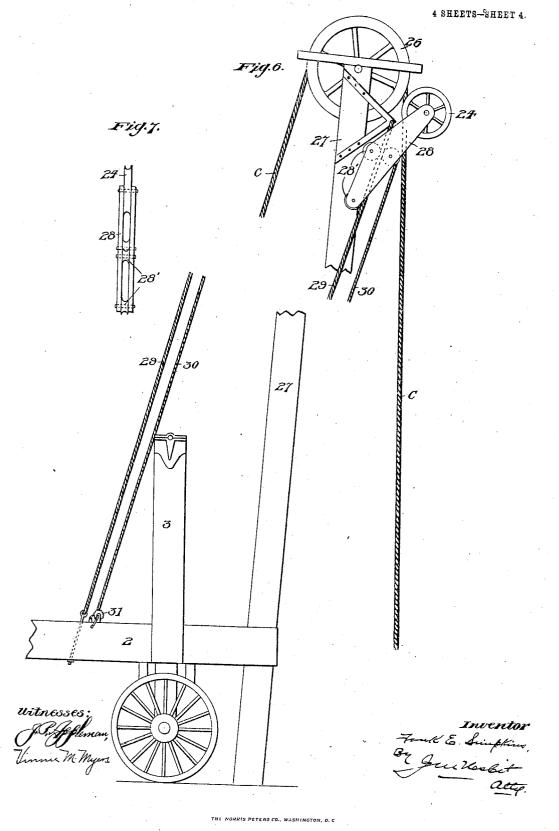
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4 SHEETS-SHEET 3.



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## UNITED STATES PATENT OFFICE.

FRANK E. SIMPKINS, OF ALLEGHENY, PENNSYLVANIA.

#### WELL-DRILLING MACHINE.

No. 835,368.

Specification of Letters Patent.

Patented Nov. 6, 1906.

Application filed February 14, 1906. Serial No. 300,952.

To all whom it may concern:

Be it known that I, Frank E. Simpkins, a citizen of the United States, residing at Allegheny, in the county of Allegheny and State of Pennsylvania, have invented certain new and useful Improvements in Well-Drilling Machines, of which the following is a specification, reference being had therein to the accompanying drawings.

This invention relates to well-drilling apparatus; and the primary object is to provide mechanism of improved construction for so transmitting the power that the cable is moved more rapidly during the downstroke 15 of the drilling-tools than during the upstroke.

A further object is to provide for varying the speed or throw of the actuating mechanism without changing the speed of the actuating crank-shaft.

A further object is to provide variable-speed mechanism adapted for beam drilling and spudding interchangeably.

The invention further relates to improved means for holding the cable drawn backward 25 coincident with the beam-axis and for drawing the same backward from its normal posi-

tion when hanging suspended from the crown-

In the accompanying drawings, Figure 1 is 30 a side elevation of a portion of well-drilling apparatus embodying the invention, the same being arranged for beam-drilling. Fig. 2 is a front end view of a portion of the same, showing the beam in section on line 2 2 of Fig. 35 1. Fig. 3 is a detail view illustrating the movement of the power-transmitting mechanism, and Fig. 4 is a similar view of the same mechanism arranged to operate in a slightly different manner. Fig. 5 is a view similar to 40 to Fig. 1, illustrating the mechanism connected for spudding. Fig. 6 is a broken side elevation of the front portion of the apparatus. Fig. 7 is a detail view of the sheavecarrier. Fig. 8 is a detail view of the power-

similar views of the locking device for the adjustable arm-support. Referring to the drawings, 2 designates the

45 transmitting arm, and Figs. 9 and 10 are

machine-frame, 3 the samson-post, and 4 the 50 walking-beam.

5 indicates the band-wheel, carried by one end of shaft 6, the opposite end of the shaft having the usual crank 7. Mounted in the under portion of the frame is shaft 8, carry-55 ing crank 9. This crank comprises a support for power-transmitting arm 10, the latter be- | faster strokes in the arrangement of Figs. 1

ing secured to wrist 7' of crank 7 and movable positively with the said crank. Arm 10 is here shown provided on one side with the elongated offset plate or keeper 11, which 60 forms longitudinal slot or passage-way 11' for confining wrist 9' of crank 9.

In the adaptation shown in Figs. 1, 3, and 5 the rear end of arm 10 is pivotally connected to the lower end of beam-pitman 12, wrist 65 7' being connected to the arm at a point inward from the pitman connection.

With the power-transmitting arm 10 arranged as shown it is given a combined reciprocating and oscillating movement when 70 crank 7 is rotated, the arrangement being such that pitman 12 is moved more rapidly through its upstroke than when moving downward, thereby securing the advantage of a quick drop of the tools and a relatively 75 slower upward movement, which prevents too sudden strains upon the mechanism and avoids injury to the drilling-cable.

The arrangement may be such that crank 9 oscillates with arm 10, at which time crank- 80 wrist 9' is held fixed in slot or passage-way 11', or crank 9 may be held fixed and arm 10 caused to move backward and forward over wrist 9'. Either arrangement affords the desired power-transmitting motion for 85

In the adaptation shown in Figs. 1 and 3 crank 9 is free to oscillate, wrist 9' being clamped against arm 10 by slot-forming keeper 11. The movement of the parts 90 when thus arranged is clearly indicated by the full and dotted line positions shown in Fig. 3.

In Fig. 4 crank 9 is shown in fixed position with arm 10 free to move longitudinally on 95 wrist 9', spacing-strips 13 being inserted between the arm and keeper for preventing the latter from binding and holding said wrist. For locking crank 9 the base thereof is provided with annular shoulder 14, which is 100 adapted to be engaged by friction-yoke 15, secured to frame 2 by bolt 15a, and when this yoke is tightened up by means of said bolt shoulder 14 is clamped between it and the bearing of shaft 8, and thus the shaft and 105 crank are prevented from turning.

In both adaptations the stroke of arm 10 may be varied for the purpose of varying the speed of pitman 12, causing the up and down strokes of the latter to be either faster or 110 slower, as may be desired. To secure the

and 3, wrist 9' is confined in the inner portion of slot or passage-way 11', or nearer wrist 7' than when the slower motion is desired. In the arrangement shown in Fig. 4 crank 9 is secured in such position as will afford the desired speed, wrist 9' thereof being nearer wrist 7' for a faster motion than for the slower motion.

In Fig. 5 the mechanism is shown con-10 nected up for actuating the spudding-arm 16, the latter being mounted on shaft 17, carrying crank 18, and the wrist of this crank is connected by pitman 19 with arm 10. In this adaptation, as in the beam-drilling 15 operations above described, arm 10 so operates as to permit the drilling-cable to drop suddenly, its movement being faster than when rising and carrying the weight of the Also in this adaptation crank 9 may 20 be held immovable, or it may be free to oscillate with arm 10, as above described. the speed may be varied for affording pitman 19 either a faster or slower motion by varying the position of wrist 9' when fixed in keeper 11 with crank 9 loose and when the wrist is loose by varying the fixed position of crank 9.

The offset plate or keeper 11 is preferably secured to arm 10 by bolts 10' and may be positioned at either edge thereof, so that the 30 arm will always exert its pressure directly on wrist 9' and not through the medium of the keeper. Thus for the beam-drilling operation keeper 11 is secured to the edge opposite that to which wrist 7' is connected, while 35 in the spudding arrangement said wrist con-

nection and keeper are on the same edge of the arm. To make the change, it is only necessary to remove bolts 10' and reverse the

position of the keeper.

For cushioning pitman 12 at the beginning of its downstroke, at which time the weight of the tools is thrown upon the walkingbeam, pitman 12 is connected to plate 20, pivoted to play vertically on the upper edge
of the beam and held normally raised by spring 21, the pitman being thus afforded slight downward movement, which is resisted by said spring at the beginning of the downstroke. For the spudding operation pitman 19 is similarly cushioned by spring 22 in the outer end of the pitman-slot 19', in which slot wrist 18' of crank 18 is in slight longitudinal play.

The improved machine is designed to op55 erate without the usual temper-screw and
clamp mechanism, the drilling-cable C being
paid out as needed directly from spool 23.
In order to impart the motion of the beam to
the cable, the latter is caused to pass around
60 a sheave 24, the axis of which is preferably
coincident with the beam-axis, and then outward over a sheave 25, carried by the outer
end of the beam. However, as the beam is
inactive during the spudding operation the
65 cable should depend from the crown-pulley

26, supported by mast 27, directly into the In order to effect the change necessary for the two operations, sheave 24 is mounted in buggy 28, provided with rollers 28', which travel on the track-forming guy- 7° line 29, the latter extending from the upper end of mast 27 downwardly and backwardly through the longitudinal recess 4' of the beam, its lower end being anchored to frame Line 30, secured to the buggy, operates 75 to draw the same downwardly on track 29, the line being operated by suitable winding device 31, positioned on frame 2. When the mechanism is in the position indicated in Fig. 6, the drilling-cable depends directly 80 into the well, sheave 24 at such time being raised and closely adjacent crown-pulley 26. For beam-drilling buggy 28 is drawn downward and through beam-recess 4' to the position shown in Fig. 1, with the axis of sheave 85 24 coincident with the beam-axis, the lowering of the buggy operating to deflect cable C backwardly, as will be understood. To make the change for the spudding operation, it is only necessary to release line 30, when 9c the pull of the drilling-cable will cause the buggy to move upward on track 29 to the position shown in Fig. 6, in which it is held by the resistance of the cable to lateral deflection.

To provide the necessary space for the sheave 24 at the beam-axis, the upper end of the samson-post is recessed, as shown in Fig. 2, and may be provided with the **U**-shaped bearing member 32 within said recess, having the outwardly - extending bearing - forming

extremities 32'.

While the variable-power-transmitting mechanism and the mechanism just described for manipulating the drilling-cable are preferably embodied in the same machine, it will be understood that either may be used alone without departing from the invention.

 ${
m I~claim}$ 

1. The combination of a shaft having a 110 crank, an arm, a support adapted to afford the arm a combined reciprocating and oscillating movement, a pivotal connection between the arm and crank, and cable-actuating means connected to the arm.

2. The combination of a shaft having a crank, an arm, a support adapted to afford the arm a combined reciprocating and oscillating movement, a pivotal connection between the arm and crank, and cable-actuat- 120

ing means connected to the arm.

3. The combination of a shaft having a crank, an arm, an arm-support adjustable with relation to the shaft and adapted to afford the arm a combined reciprocating and 125 oscillating movement, a pivotal connection between the arm and crank, and cable-actuating means connected to the arm.

4. The combination of a shaft having a crank, an arm, an arm-support adapted to af-

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ford the arm a combined reciprocating and oscillating movement, means for positioning the support at different distances from the crank-shaft for the purpose of varying the 5 oscillations of the arm, a pivotal connection between the arm and crank, and cable-actuating means connected to the arm.

5. The combination of a shaft having a crank, an arm having a longitudinal passagevay, an arm-support adjustable in the passage-way, a pivotal connection between the arm and said crank, and cable-actuating

means connected to the arm.

6. The combination of a walking-beam, a beam-axis, a cable-guide at the outer end of the beam, a crown-pulley, a crown-pulley support, a drilling-cable, a cable-engaging sheave movable beneath the crown-pulley, and means for positioning said sheave at the beam-axis.

7. The combination of a walking-beam, a cable-guide at the outer end of the beam, a crown-pulley, a crown-pulley support, a trackway extending from said support down-25 wardly past the beam, a drilling-cable, a cable-engaging sheave and a sheave-carrier movable on the trackway.

8. The combination of a walking-beam, a

beam-axis, a cable-guide at its outer end, a crown-pulley, a crown-pulley support, a 30 backwardly-inclined trackway extending downwardly from the support past the walking-beam, a cable-engaging sheave, a sheave-carrier movable on the trackway, and means for drawing downward the carrier for the purpose of causing the sheave to deflect the drilling-cable inwardly and for holding the sheave coincident with the beam-axis.

9. The combination of a walking-beam having a vertical recess, a beam-axis, a cable-40 guide at the outer end of the beam, a crown-pulley, a crown-pulley support, a backwardly-inclined trackway extending downwardly from said support and through the beam-recess, a drilling-cable, a cable-engaging sheave, 45 a sheave-carrier movable on the trackway, and means for moving the carrier downward for the purpose of positioning said sheave at the beam-axis.

In testimony whereof I affix my signature 50 in presence of two witnesses.

### FRANK E. SIMPKINS.

Witnesses:

C. A. GODELAND, W. E. DEMMING.