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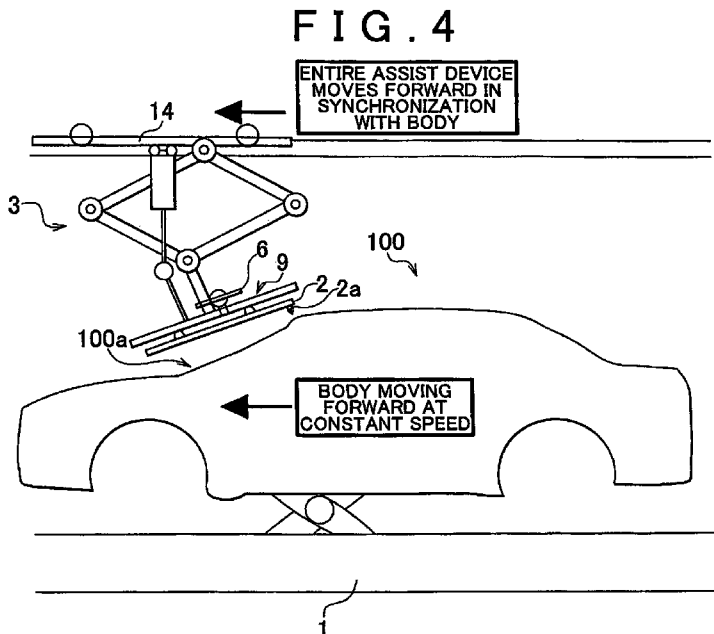
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(54) Title: POWER ASSIST DEVICE AND METHOD OF CONTROLLING THE POWER ASSIST DEVICE



(57) Abstract: A method of controlling a power assist device (50) that includes an operating handle (6), a force sensor (7), a robot arm (3), an actuator (11) that drives the robot arm (3), and conveying means (14) for conveying the robot arm (3). When a body (100) is in motion, the conveying means (14) is controlled to move in synchronization with the body, and when the motion of the body (100) is stopped or has resumed, the drive of the robot arm (3) is stopped for a predetermined time, and does not resume until after a predetermined time has elapsed.



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