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CA 2811105 A1 2013/09/29

(21) 2 811 105

(12) DEMANDE DE BREVET CANADIEN
CANADIAN PATENT APPLICATION

(13) A1

(22) Date de dépôt/Filing Date: 2013/03/27

(41) Mise à la disp. pub./Open to Public Insp.: 2013/09/29

(30) Priorité/Priority: 2012/03/29 (US61/617,332)

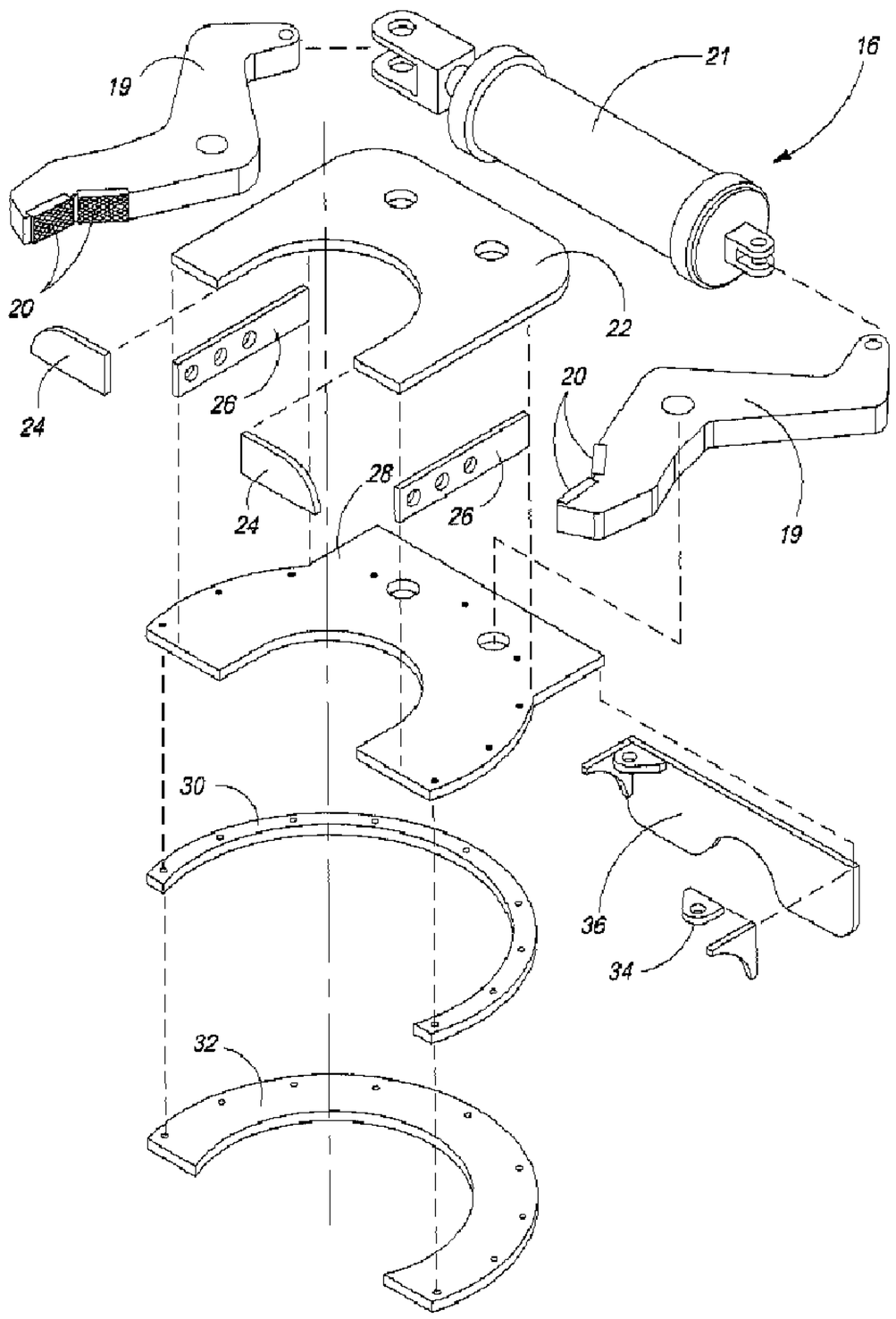
(51) Cl.Int./Int.Cl. *B25B 13/50* (2006.01),
E21B 19/16 (2006.01)

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(54) Titre : CLES DE DEVISSAGE ET PROCEDES
(54) Title: BREAKOUT WRENCH ASSEMBLIES AND METHODS



(57) Abrégé/Abstract:
Break out wrench assemblies are provided that can include: a first subassembly, the first subassembly including a first pair of opposing arms linked by a first actuator configured to extend or compress a distance between the first pair of opposing arms; a

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(57) Abrégé(suite)/Abstract(continued):
second subassembly aligned with the first subassembly to receive a longitudinal member there between and rotate axially along the longitudinal member in relation to the first subassembly, the second subassembly including a second pair of opposing arms linked by a second actuator configured to extend or compress another distance between the second pair of opposing arms; at least one axial actuator coupled to the second subassembly and configured to rotate the second subassembly axially in relation to the first subassembly along the longitudinal member; and a controller coupled to the actuators and mechanically coupled to at least one of the subassemblies. Methods for separating linked longitudinal sections are also provided.

ABSTRACT

Break out wrench assemblies are provided that can include: a first subassembly, the first subassembly including a first pair of opposing arms linked by a first actuator configured to extend or compress a distance between the first pair of opposing arms; a second subassembly aligned with the first subassembly to receive a longitudinal member there between and rotate axially along the longitudinal member in relation to the first subassembly, the second subassembly including a second pair of opposing arms linked by a second actuator configured to extend or compress another distance between the second pair of opposing arms; at least one axial actuator coupled to the second subassembly and configured to rotate the second subassembly axially in relation to the first subassembly along the longitudinal member; and a controller coupled to the actuators and mechanically coupled to at least one of the subassemblies. Methods for separating linked longitudinal sections are also provided.

Breakout Wrench Assemblies and Methods

CROSS REFERENCE TO RELATED APPLICATION

[0001] This application claims priority to U.S. Provisional Patent Application Serial No. 61/617,332 which was filed on March 29, 2012, the entirety of which is incorporated by reference herein.

TECHNICAL FIELD

[0002] The present disclosure relates to the field of well drilling and well maintenance activities that utilize multiple pipe components that are linked together by some type of threaded connection. In particular embodiments, the present disclosure relates to breakout wrenches that may be utilized to break apart these pipe components.

BACKGROUND

[0003] In the field of well drilling, oil, gas, or water well drilling, it is becoming a necessity to drill wells deeper than ever before. As a result, more power is needed to rotate the multiple lengths of drill pipe that are utilized to reach these depths during well drilling. These lengths of pipe are connected to one another via a threaded fitting. Upon removing the pipe from the well, it is necessary to break the pipe components or lengths apart at the well head. This can be an extraordinarily dangerous action, as it requires operators to exert a tremendous amount of force in a sometimes unsafe manner to break apart these components. The present disclosure provides breakout wrench assemblies and methods that can be utilized to

assist operators in breaking apart pipe components safely, as well as torquing them up to proper specifications.

SUMMARY OF THE DISCLOSURE

[0004] Break out wrench assemblies are provided that can include: a first subassembly, the first subassembly including a first pair of opposing arms linked by a first actuator configured to extend or compress a distance between the first pair of opposing arms; a second subassembly aligned with the first subassembly to receive a longitudinal member there between and rotate axially along the longitudinal member in relation to the first subassembly, the second subassembly including a second pair of opposing arms linked by a second actuator configured to extend or compress another distance between the second pair of opposing arms; at least one axial actuator coupled to the second subassembly and configured to rotate the second subassembly axially in relation to the first subassembly along the longitudinal member; and a controller coupled to the actuators and mechanically coupled to at least one of the subassemblies. Break out wrench assemblies can also include: a first subassembly coupled to a second subassembly via an arcuate rail, the second subassembly being rotatable along the rail in relation to the second subassembly.

[0005] Methods for separating linked longidutinal sections are provided with at least some of the methods including: providing at least two linked longitudinal sections; with a controller mechanically linked to a break out wrench assembly, actuating a first pair of opposing arms to secure at least

one of the sections; with the same controller, actuating a second pair of opposing arms to secure at least another section; and with the same controller, actuating a rotation of the second pair of opposing arms in relation to the first pair of opposing arms to separate the one section from the other section.

BRIEF DESCRIPTION OF THE DRAWINGS

[0006] Embodiments of the disclosure are described below with reference to the following accompanying drawings.

[0007] Fig. 1 is an exploded view of one subassembly of a breakout wrench according to an embodiment.

[0008] Fig. 2 is an exploded view of another subassembly of a breakout wrench according to an embodiment.

[0009] Fig. 3 is an exploded view of the two subassemblies of Fig. 1 and Fig. 2 according to an embodiment.

[0010] Fig. 4 is a breakout wrench at one stage of operation according to an embodiment.

[0011] Fig. 5 is a breakout wrench at another stage of operation according to an embodiment.

[0012] Fig. 6 is a breakout wrench at another stage of operation according to an embodiment.

[0013] Fig. 7 is a breakout wrench at another state of operation according to an embodiment.

[0014] Fig. 8 is a top view of a breakout wrench at a stage of operation according to an embodiment.

[0015] Fig. 9 is a breakout wrench at another stage of operation according to an embodiment.

[0016] Fig. 10 is a hydraulic schematic of a controller as it relates to the breakout wrench of the present disclosure.

[0017] Fig. 11 is a depiction of the breakout wrench according to an embodiment.

[0018] Figs. 12A-12B depict a series of breakout wrench operations according to an embodiment.

DESCRIPTION

[0019] This disclosure is submitted in furtherance of the constitutional purposes of the U.S. Patent Laws "to promote the progress of science and useful arts" (Article 1, Section 8).

[0020] The present disclosure will be described with reference to Figs. 1-12B. Referring first to Fig. 1, a subassembly 16 of breakout wrench assembly 12 (shown in Fig. 11) is depicted. As can be seen, this subassembly includes an actuator 21 that can be coupled to opposing arms

19 having teeth 20. Upper plate 22 and side walls 26 and 24 as well as bottom plate 28 can form a housing that encloses arms 19 and provides pivot rotation for arms 19 within this housing. This housing can be engaged to a rail 30 which is mounted to a rotation plate 32 to form recess 31 (Fig. 3). Recess 31 can form a track configured to receive rail 46. Below actuator 21 can be a pivot housing that includes back plate 34 as well as eyelets 36 and 38 respectively. Actuators can include hydraulic cylinders.

[0021] Referring to Fig. 2, another subassembly 18 is shown that includes an actuator 40 coupled to opposing arms 42 having teeth 44 associated therewith. Upper plate 48 as well as side walls 50 and front walls 56 and bottom plate 52 can form a housing that encloses arms 42 and engages them in a pivotable rotation therewith. Above upper plate 48 of subassembly 18 can be rail 46 which is engaged to couple with recess 31. At opposing sides of subassembly 12 can be one or more actuators 58 and 60, respectively. Acutator 58 can pivotably couple with eyelet 54 as shown and actuator 60 can couple with opposing eyelet 54. These actuators cylinders can have opposing ends, and one opposing end can be configured to couple to eyelet 36 as shown in Fig. 1. Actuator 60 can be configured to couple with eyelet 38 as shown in Fig. 1 as well.

[0022] Referring to Fig. 3, the subassemblies are shown in a subset exploded view associated with one another as subassembly 16 is shown associated with subassembly 18. Posts 43 can support the second subassembly above the first subassembly via rail 46 and recess 31.

[0023] Referring to Fig. 4, operation of the wrench can include configuring the wrench to couple with a pipe 23 as shown in Fig. 5. Pipe 23 can be at least a pair of longitudinal sections configured to releasably couple. Examples include sections of drilling pipe. As can be seen, wrench 10 is in an operable position 25 proximate pipe 23 rather than another position away from pipe 23. According to this stage of operation, the assembly 18 would engage the arms to engage a section of pipe. Referring to Fig. 5, a top view of this engagement is shown with the upper assembly rotated at least slightly askew from the lower assembly.

[0024] Referring to Fig. 6, at this stage, both the upper and lower arms of the assembly would engage the pipe with the upper assembly askew to the lower assembly, engaging an upper length of pipe, and as Fig. 7 demonstrates, at this stage of operation, the upper assembly can be utilized to grip and move the upper length of pipe in a direction unlocking or unscrewing the upper length of pipe from the lower length of pipe.

[0025] Referring to Fig. 8, another view of the disclosure shows the upper sub assembly in an opposing or counterclockwise skew to the lower sub assembly and in Fig. 9, this is depicted as well.

[0026] Fig. 10 demonstrates the schematic for the depicted control panel. This schematic aligns the pressure regulation of the three various valves that control the upper wrench to rotate or upper assembly and lower

assembly clamping force, respectively. This schematic can include gauges that have respective control pressure valves residing therewith.

[0027] Fig. 11 is a depiction of the completed sub assembly, and Fig. 13 is a series of rotations indicating the use of the arms and the rotation of the pipes associated therewith with arms 4 and 5, indicating the upper arms of the upper sub assembly and arms 1 and 2 indicating the lower arms of the lower sub assembly. Controller 14 and wrench assemblies 12 and 18 can be supported and/or mechanically connected via platform 112. Controller 14 can provide hydraulic fluid control of actuators via lines 110. Platform 112 may be coupled to one or more wheels 114 configured to engage support and movement of the breakout wrench between operational and non-operational locations. As is depicted, this series indicates the different stages that the wrench utilizes to break apart the pipe sections.

[0028] In compliance with the statute, embodiments of the invention have been described in language more or less specific as to structural and methodical features. It is to be understood, however, that the entire invention is not limited to the specific features and/or embodiments shown and/or described, since the disclosed embodiments comprise forms of putting the invention into effect.

CLAIMS

1. A break out wrench assembly comprising:

a first subassembly, the first subassembly comprising a first pair of opposing arms linked by a first actuator configured to extend or compress a distance between the first pair of opposing arms;

a second subassembly aligned with the first subassembly to receive a longitudinal member therebetween and rotate axially along the longitudinal member in relation to the first subassembly, the second subassembly comprising a second pair of opposing arms linked by a second actuator configured to extend or compress another distance between the second pair of opposing arms;

at least one axial actuator coupled to the second subassembly and configured to rotate the second subassembly axially in relation to the first subassembly along the longitudinal member; and

a controller coupled to the actuators and mechanically coupled to at least one of the subassemblies.

2. The break out wrench assembly of claim 1 wherein one or more of the actuators are hydraulic cylinders, the hydraulic cylinders being in fluid communication with the controller.

3. The break out wrench assembly of claim 1 wherein the first subassembly is mechanically coupled to the second subassembly via a track.

4. The break out wrench assembly of claim 3 wherein the track is arcuate.

5. The break out wrench assembly of claim 4 wherein the track extends at least 180 degrees having portions opposing one another.

6. The break out wrench assembly of claim 4 wherein the track comprises a rail.

7. The break out wrench assembly of claim 6 wherein the rail is coupled to the first subassembly via a plurality of posts.

8. The break out wrench assembly of claim 6 wherein the second subassembly defines a recess configured to receive the track.

9. The break out wrench assembly of claim 1 further comprising a platform supporting both the first and second subassemblies as well as the controller.

10. The break out wrench assembly of claim 9 further comprising one or more wheels supporting the platform configured to provide mobility to the break out wrench.

11. A method separating linked longitudinal sections, the method comprising:

providing at least two linked longitudinal sections;

with a controller mechanically linked to a break out wrench assembly, actuating a first pair of opposing arms to secure at least one of the sections;

with the same controller, actuating a second pair of opposing arms to secure at least another section; and

with the same controller, actuating a rotation of the second pair of opposing arms in relation to the first pair of opposing arms to separate the one section from the other section.

12. The method of claim 11 wherein the actuating the rotation of the second pair of opposing arms in relation to the first pair of opposing arms rotates the second pair of opposing arms along a rail in relation to the first pair of opposing arms.

13. The method of claim 12 wherein the relational rotation is at least 5 degrees.

14. The method of claim 11 further comprising, prior to securing at least one of the sections, moving the break out wrench assembly from a first position away from the longitudinal sections to a second position proximate the longitudinal sections.

15. The method of claim 11 further comprising, after separating the one section from the other section, moving the break out wrench assembly from a second position proximate the longitudinal sections to a first position away from the longitudinal sections.

16. The method of claim 11 wherein the longitudinal sections are sections of drilling pipe.

17. The method of claim 11 wherein the actuating is hydraulic actuation.

18. The method of claim 11 further comprising operating the controller from the standing position.

19. The method of claim 11 further comprising guiding the breakout wrench assembly into or out of operating position along one or more wheels.

20. A break out wrench assembly comprising:

a first subassembly coupled to a second subassembly via an arcuate rail, the second subassembly being rotatable along the rail in relation to the first subassembly;

the first subassembly comprising a first pair of opposing arms linked by a first actuator configured to extend or compress a distance between the first pair of opposing arms;

the second subassembly being aligned with the first subassembly to receive a longitudinal member therebetween, the second subassembly comprising a second pair of opposing arms linked by a second actuator configured to extend or compress another distance between the second pair of opposing arms;

a pair of axial actuators coupled to the second subassembly and configured to rotate the second subassembly axially in relation to the first subassembly along the rail; and

a controller coupled to the actuators and mechanically coupled to at least one of the subassemblies.

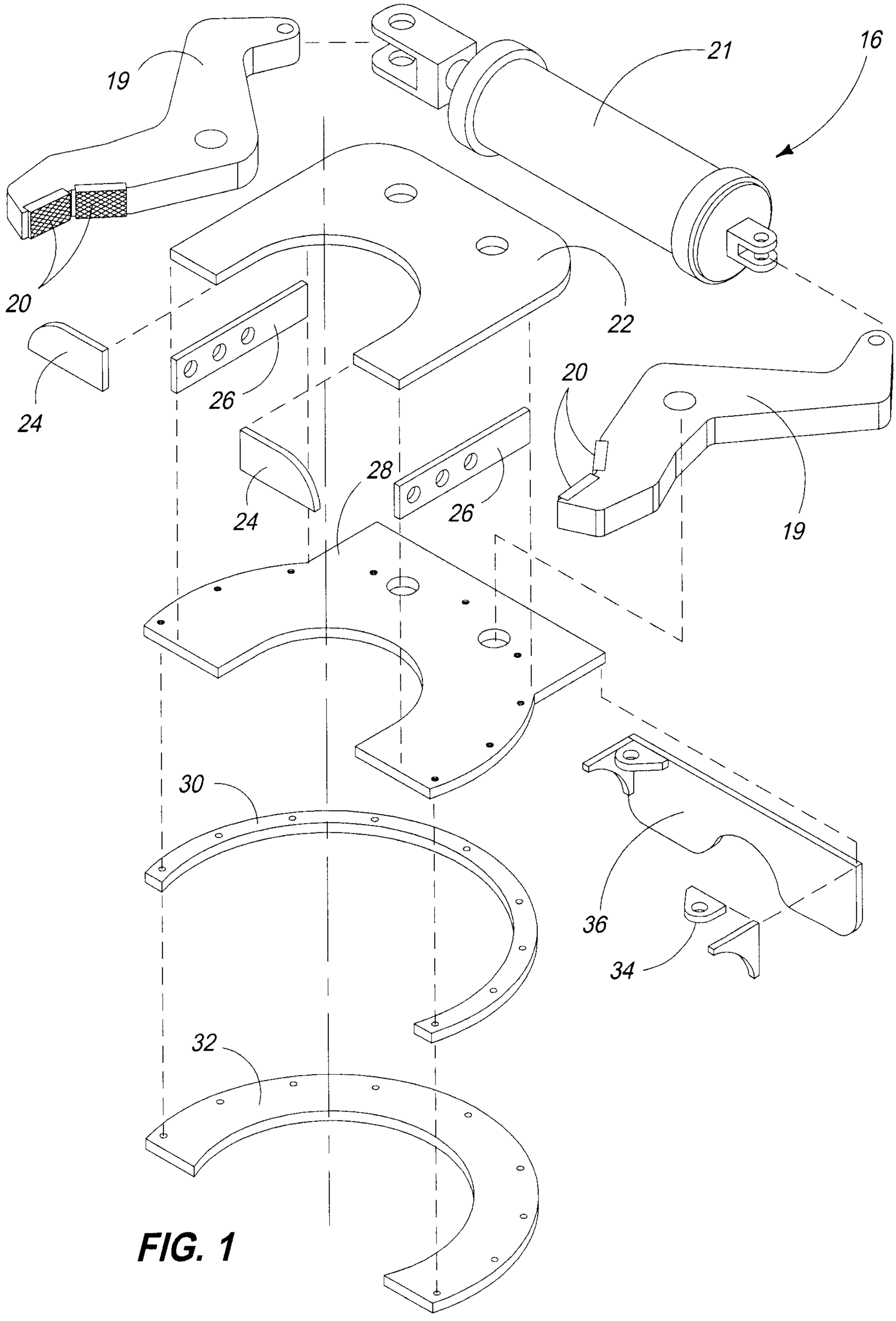


FIG. 1

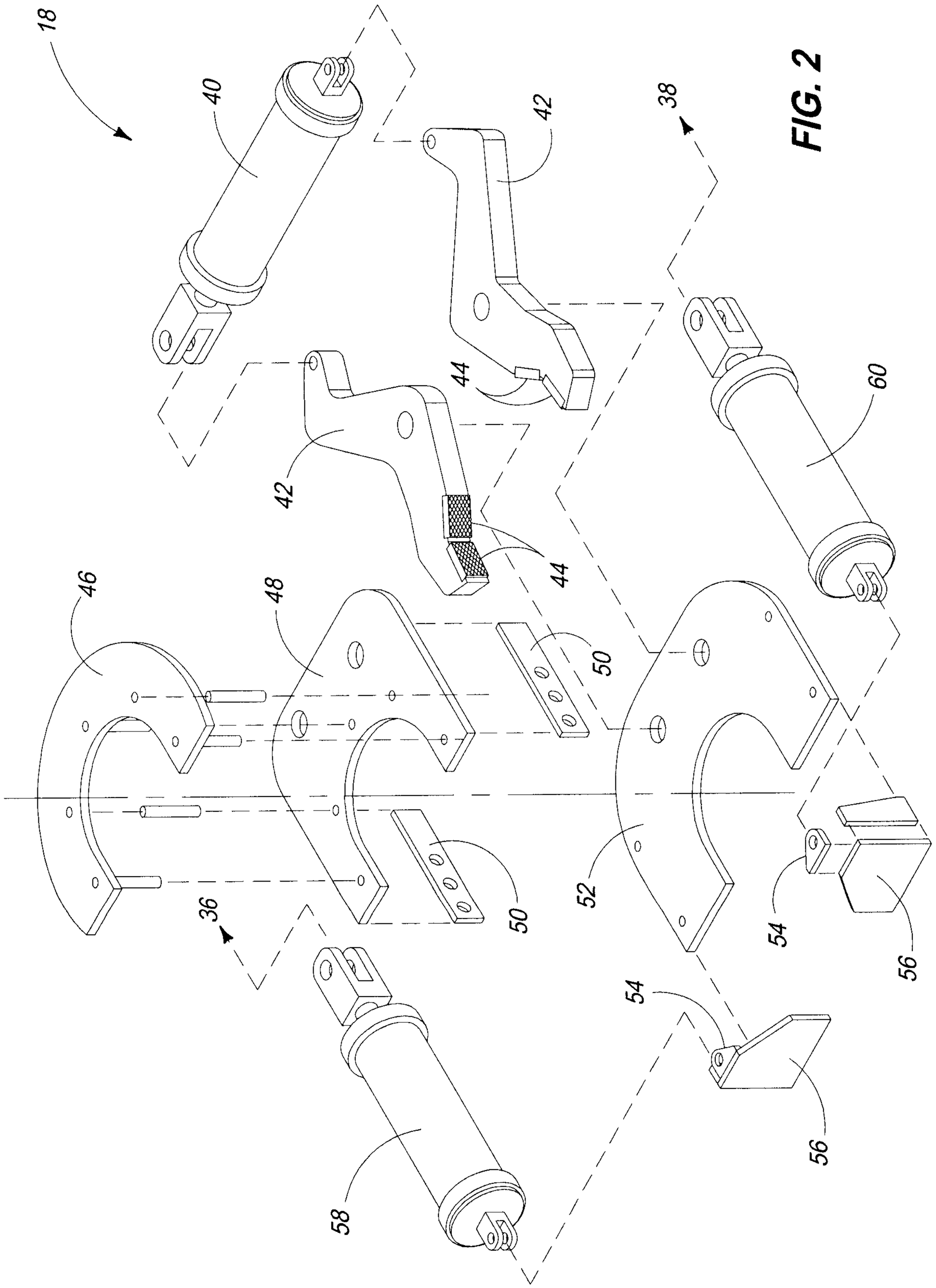


FIG. 2

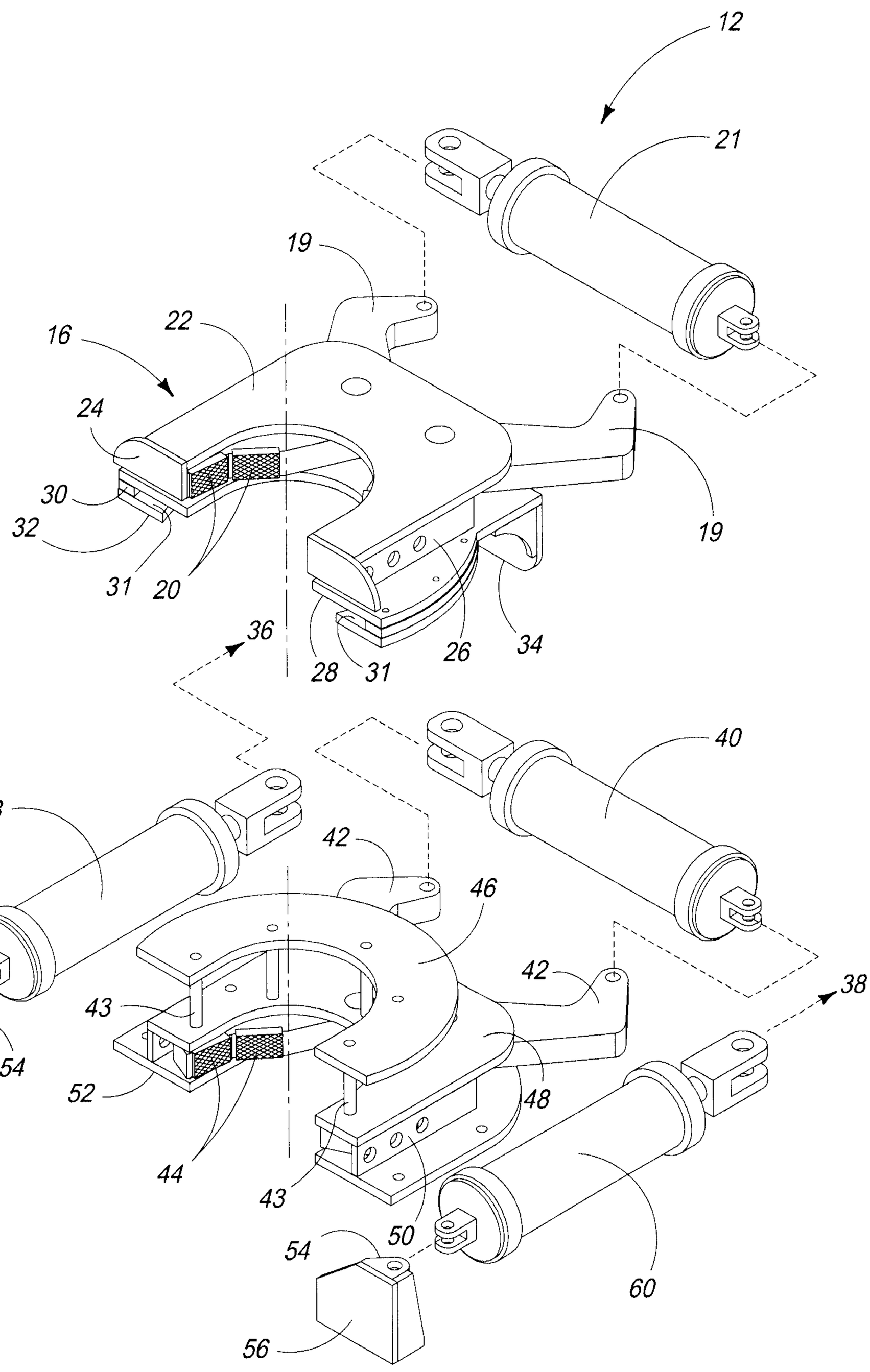
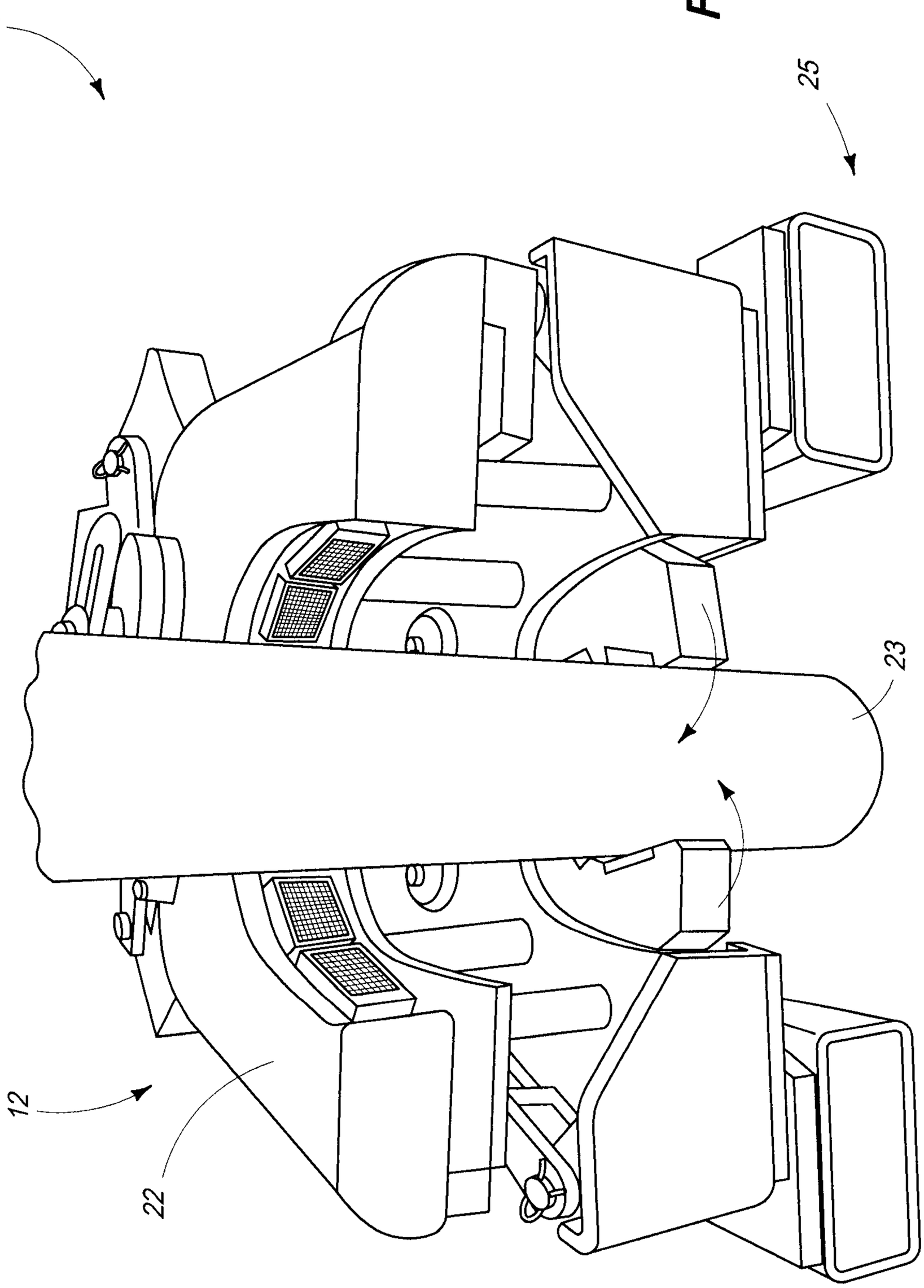

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FIG. 3

FIG. 4



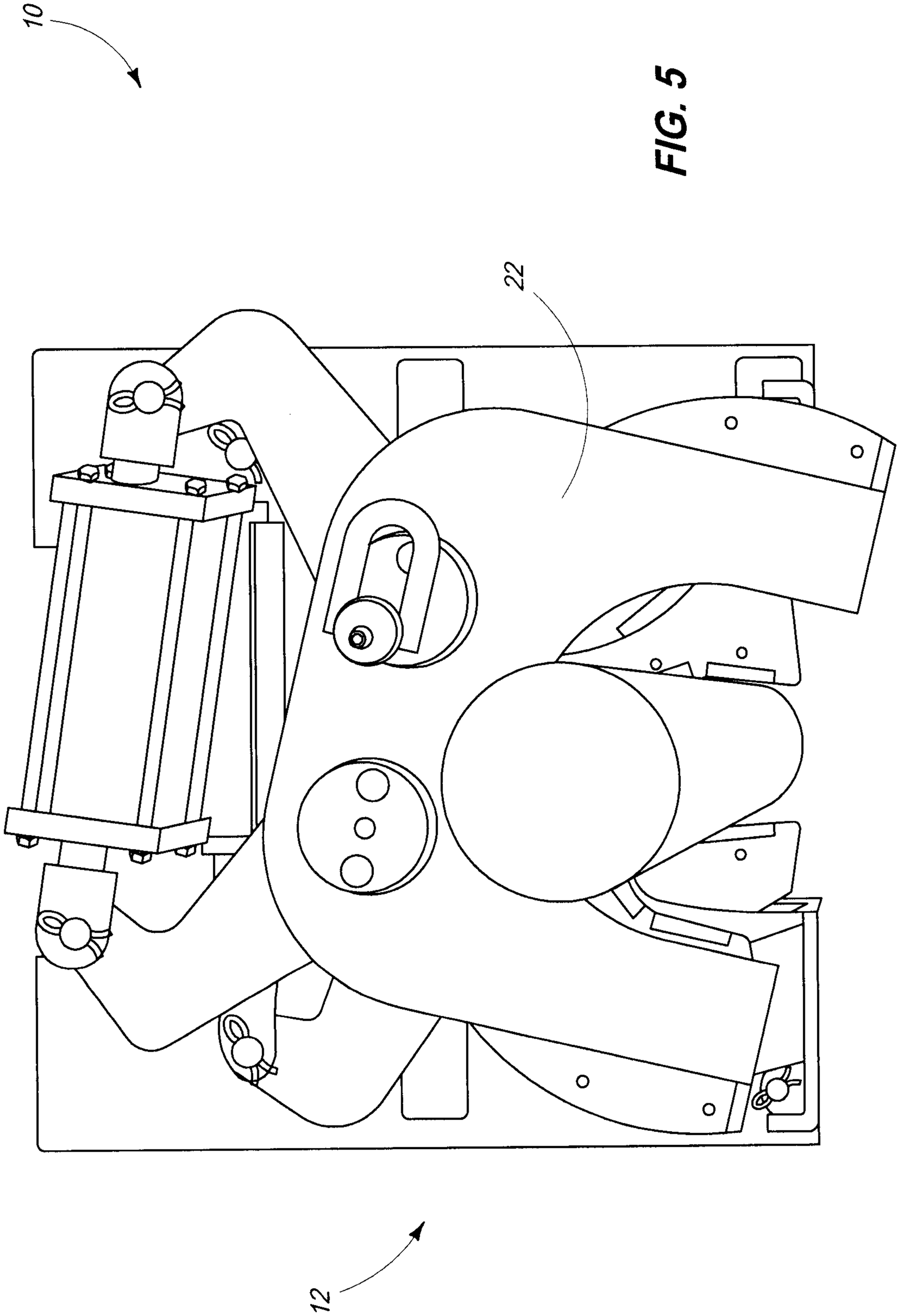


FIG. 5

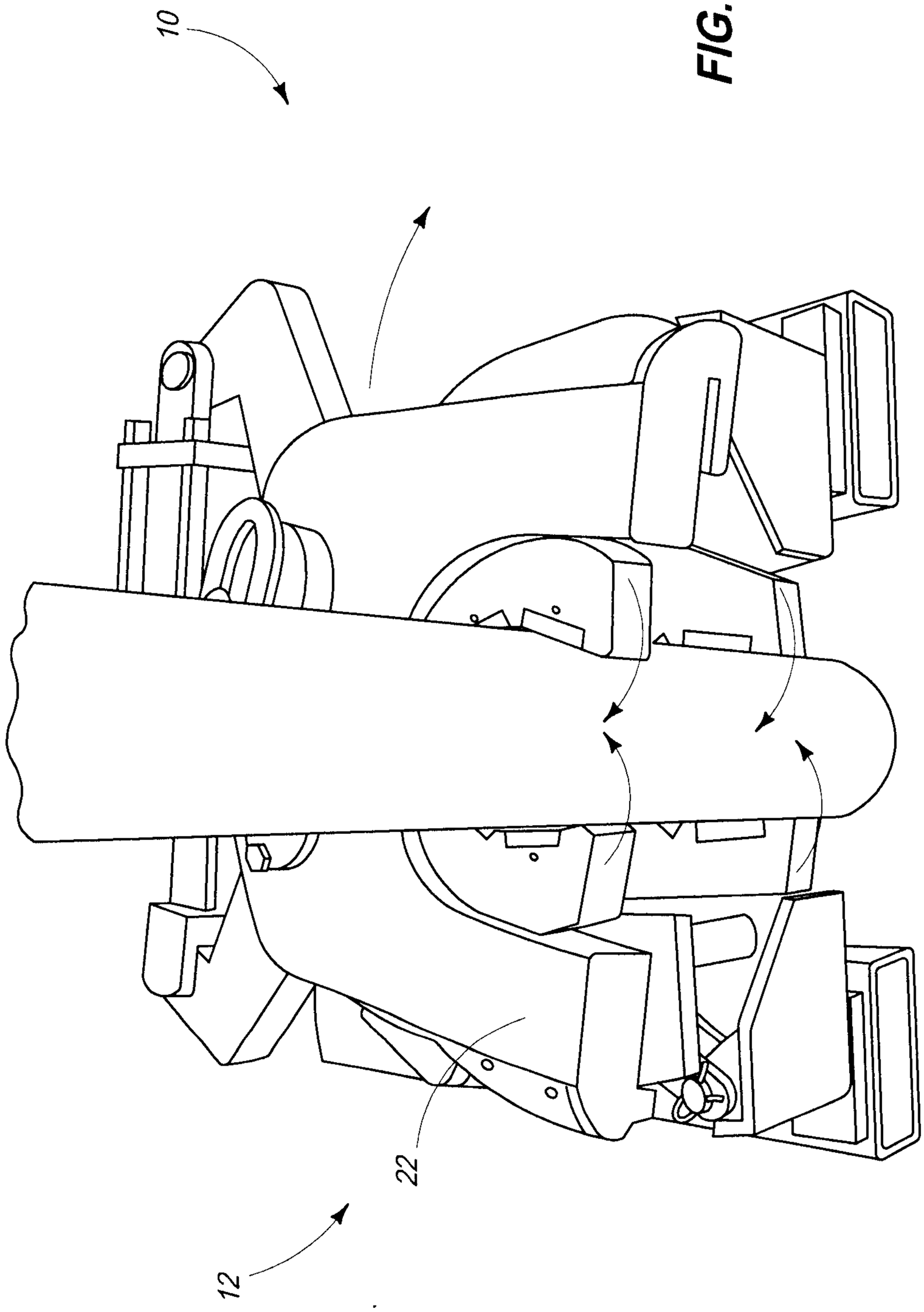


FIG. 6

FIG. 1

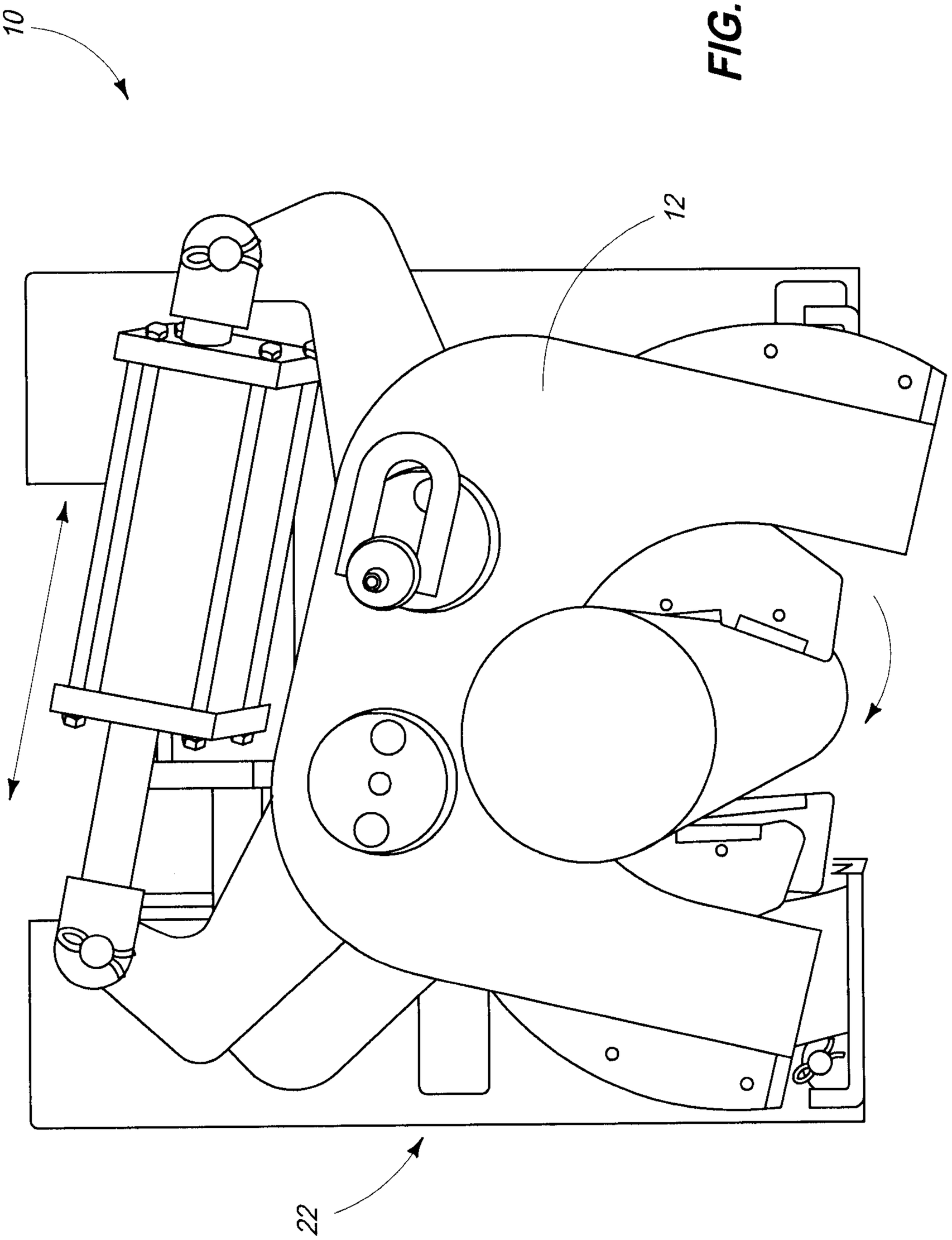


FIG. 8

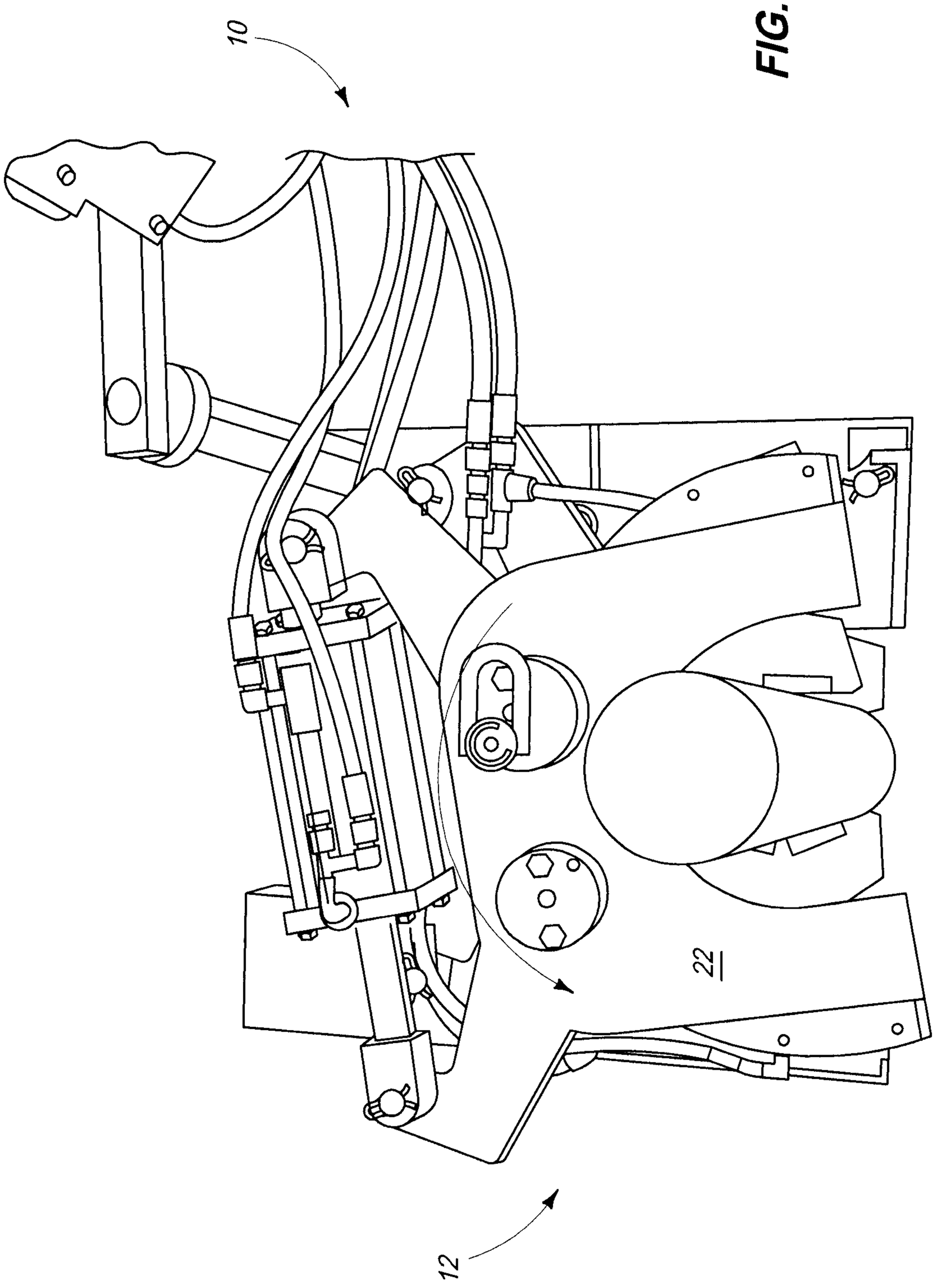
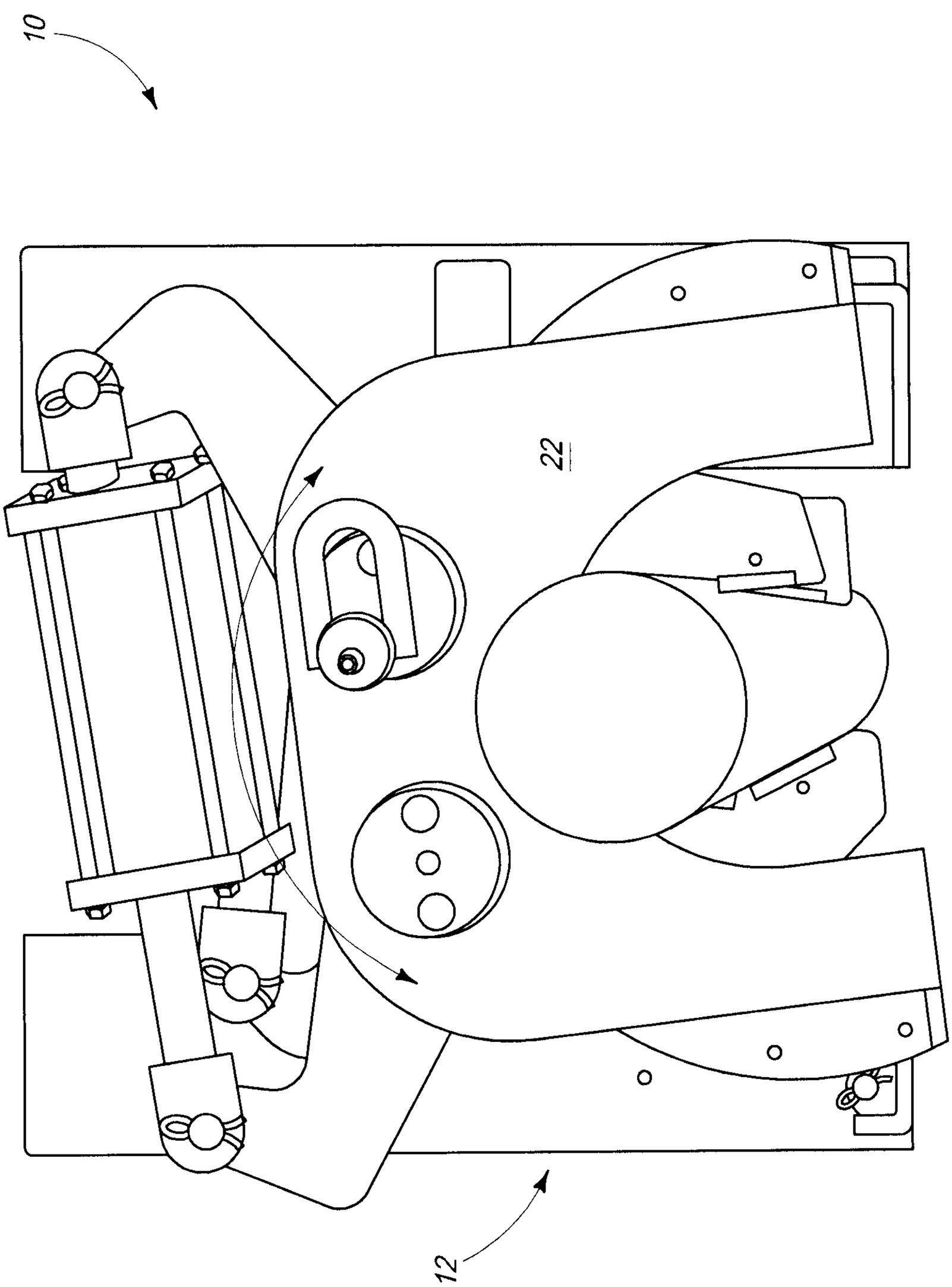


FIG. 9



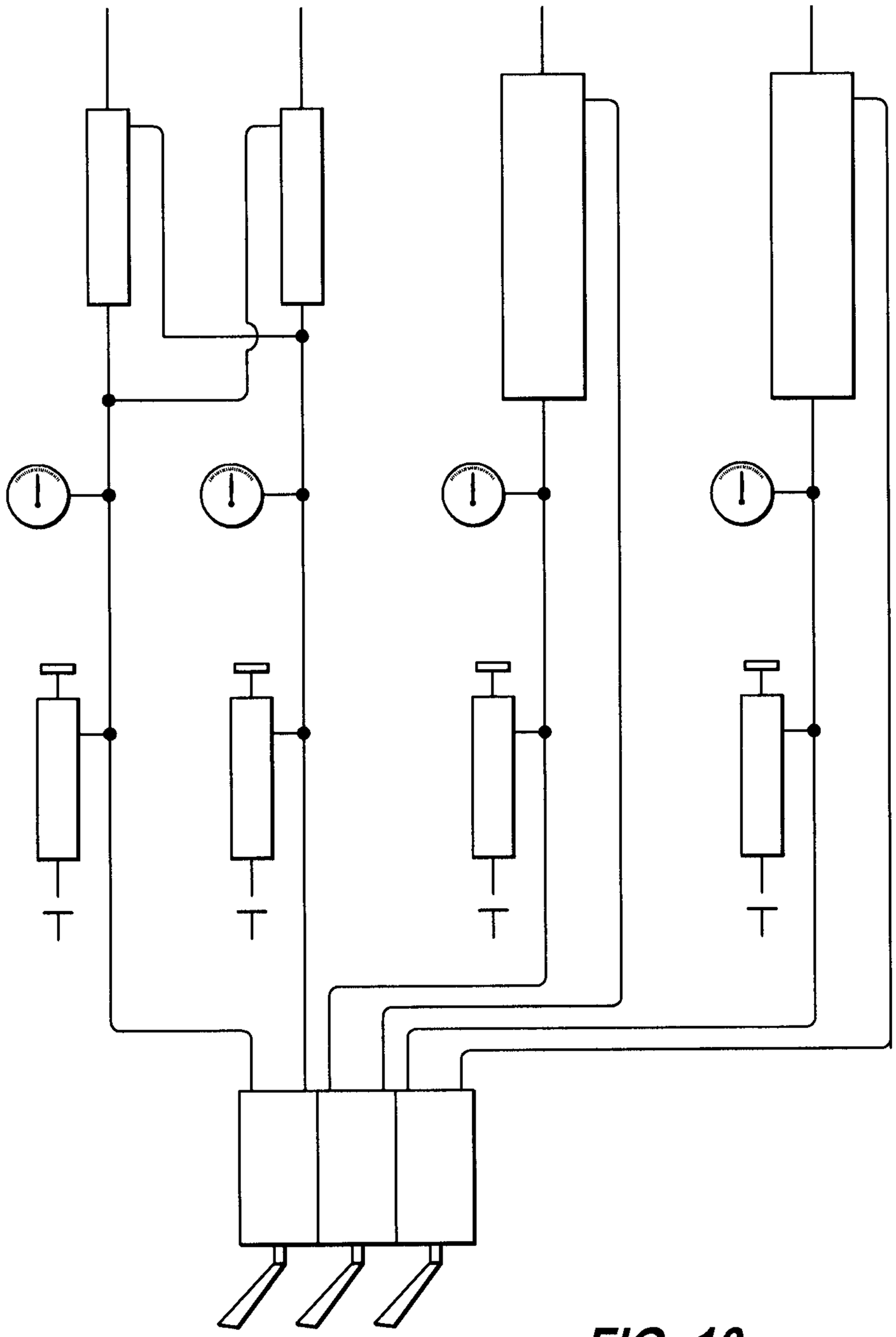


FIG. 10

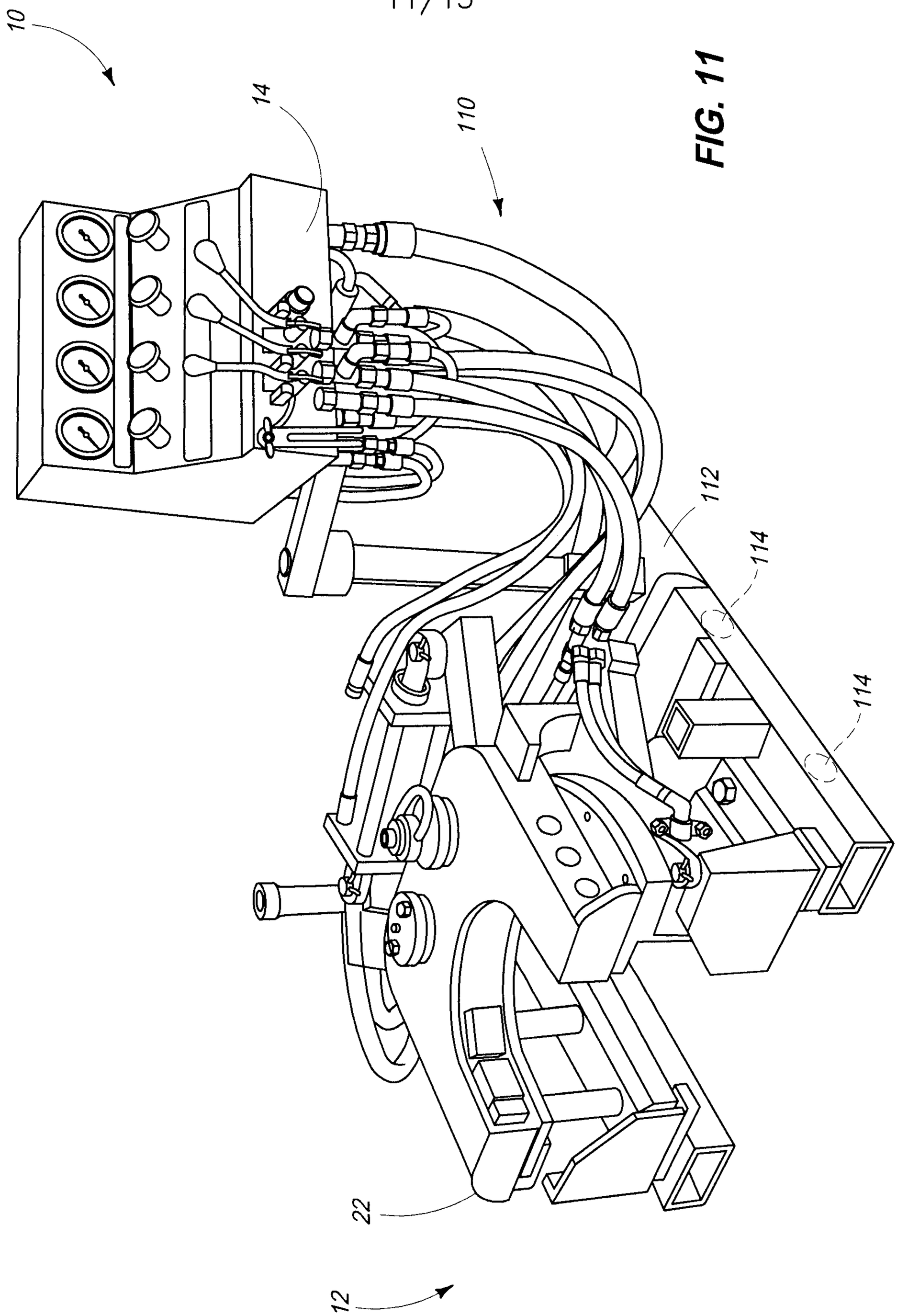


FIG. 11

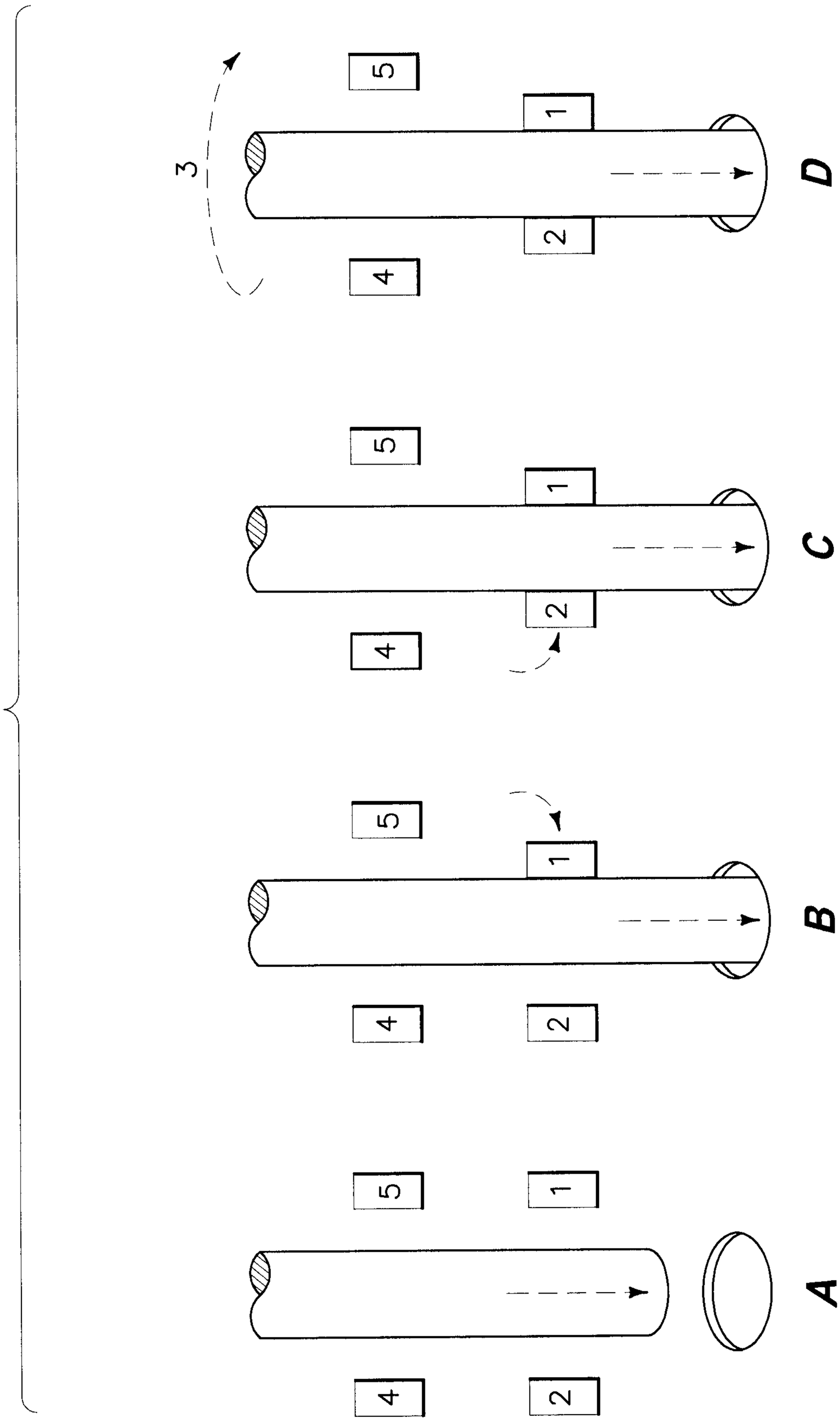


FIG. 12A

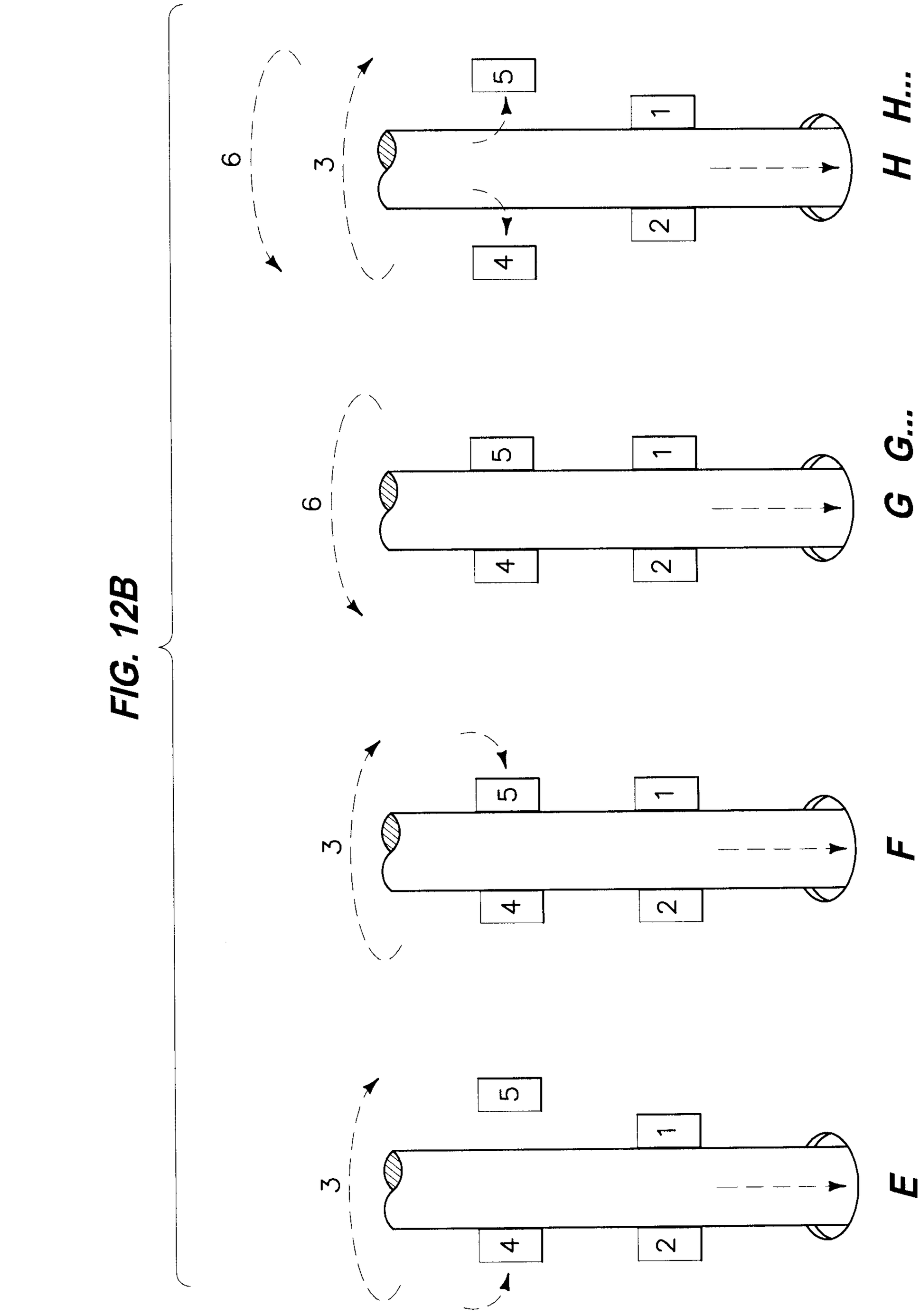
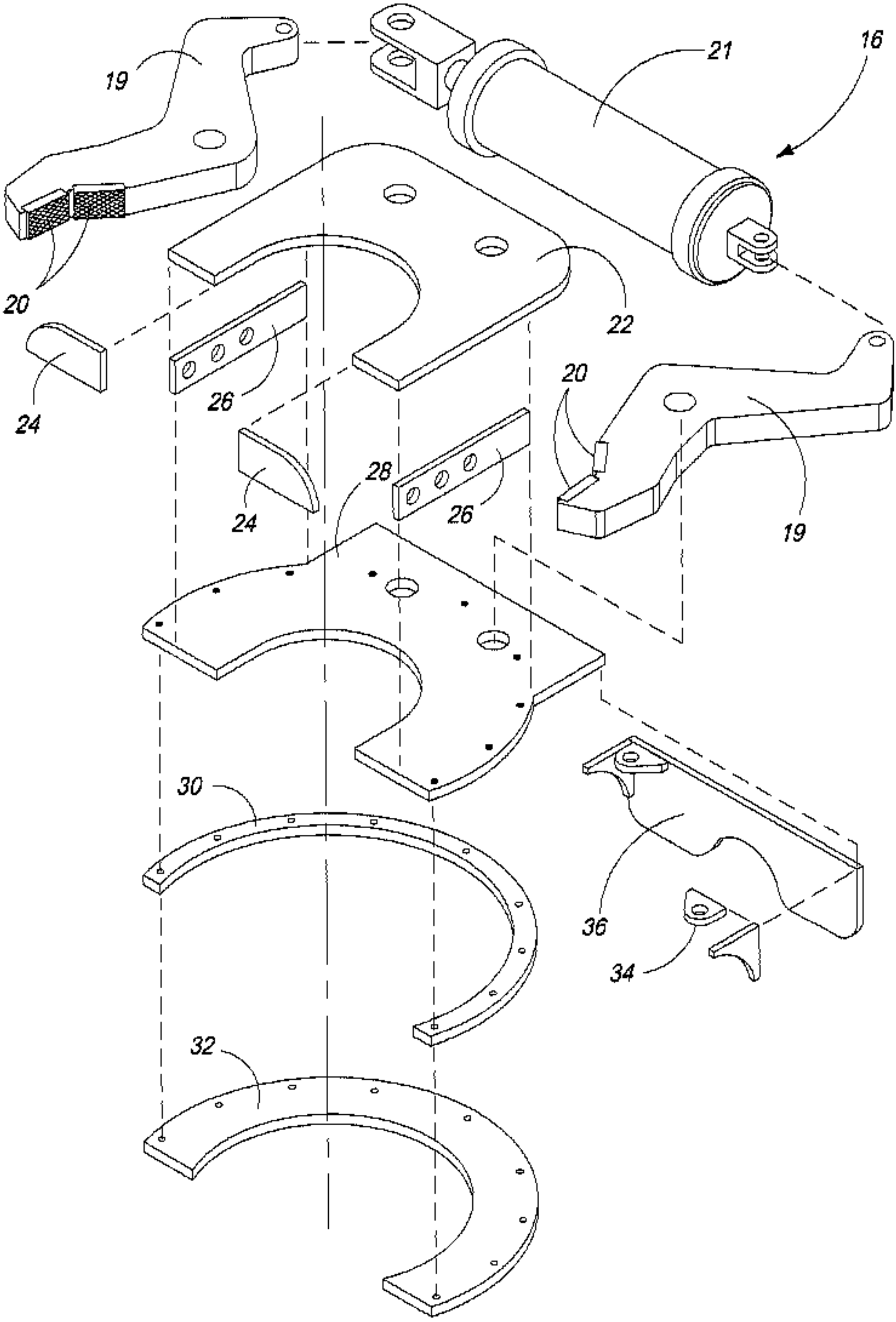


FIG. 12B


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