(12) INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(19) World Intellectual Property Organization

International Bureau





(10) International Publication Number WO 2016/203481 A1

(43) International Publication Date 22 December 2016 (22.12.2016)

(51) International Patent Classification: *F41H 13/00* (2006.01)

(21) International Application Number:

PCT/IL2016/050643

(22) International Filing Date:

19 June 2016 (19.06.2016)

(25) Filing Language:

English

(26) Publication Language:

English

(30) Priority Data:

239522

18 June 2015 (18.06.2015)

IL

- (72) Inventor; and
- (71) Applicant: COHEN, David [IL/IL]; 2/4 HaEtrog Street, 4630902 Herzeliya (IL).
- (74) Agents: FUERST, Zadok et al.; Luzzatto & Luzzatto, P.O. Box 5352, 8415202 Beer Sheva (IL).
- (81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM, AO, AT, AU, AZ, BA, BB, BG, BH, BN, BR, BW, BY, BZ, CA, CH, CL, CN, CO, CR, CU, CZ, DE, DK, DM,

DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IR, IS, JP, KE, KG, KN, KP, KR, KZ, LA, LC, LK, LR, LS, LU, LY, MA, MD, ME, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PA, PE, PG, PH, PL, PT, QA, RO, RS, RU, RW, SA, SC, SD, SE, SG, SK, SL, SM, ST, SV, SY, TH, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.

(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LR, LS, MW, MZ, NA, RW, SD, SL, ST, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, RU, TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV, MC, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK, SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, KM, ML, MR, NE, SN, TD, TG).

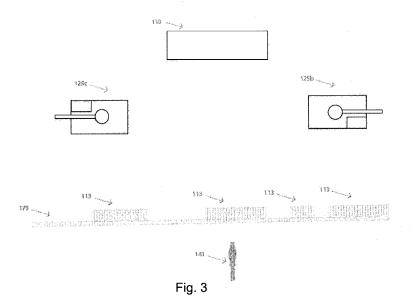
Declarations under Rule 4.17:

of inventorship (Rule 4.17(iv))

Published:

— with international search report (Art. 21(3))





(57) Abstract: 33765-WO-1 -11- ABSTRCT The invention relates to a single system that can simultaneously protects a plurality of assets, such as soldiers, vehicles and structures in a given perimeter. The assets are, for example, vehicles and structures that could not otherwise be protected due to tactical and mechanical limitations.



Portable Active Protection System

Field of the Invention

The field of the invention relates in general to portable active protection systems for protecting assets, including soldiers, vehicles and structures from incoming missiles and rockets. More specifically, the invention relates to an active protection system which can be handheld.

Background of the Invention

Known in the art are variety of systems that are designed to intercept and destroy incoming missiles and rockets with a shotgun-like blast that ejects a plurality of particles towards the incoming object with the intent of jeopardizing its structure integrity to the point of rendering it useless or impairing its functionality. For example, a system known in the art by its commercial name "Trophy", is a military system for active protection for vehicles, such as light and heavy armored fighting vehicles and vehicles in general. Developed by Rafael Advanced Defense Systems and Israel Aircraft Industries' Elta Group, the system intercepts and destroys incoming missiles and rockets with the abovementioned shotgun-like blast, as to supplement the fighting vehicles' armor.

The above prior art systems are designed to protect the vehicle that they are placed on, and as the systems are highly expensive, their deployment is limited to a select few only. Furthermore, as the system is deployed on vehicles that are already fitted with a variety of other systems such as radar, electro-optics, communication, and weapons systems, the deployment on the vehicles poses a great engineering challenge, as well as a tactical handicap, as the systems activation in battle conditions is limited by the need to avoid damage to all other existing systems.

Summary of the Invention

It is an object of the invention to provide a single system that can simultaneously protect a plurality of assets, such as soldiers, vehicles and structures in a given perimeter.

It is another object of the invention to significantly reduce the costs involved in protecting a plurality of vehicles.

It is still another object of the invention to enable protection of assets, such as vehicles and structures that could not otherwise be protected due to tactical and mechanical limitations as mentioned above.

It is still another object of the invention to reduce the likelihood of collateral damage of charge activation to the carrying platform.

It is still another object of the invention to increase the likelihood of a successful interception, relative to systems of the prior art, especially when a large number of missiles and rockets are fired at a designated spot or a perimeter, either simultaneously or consecutively.

According to one aspect of the present embodiments, there is provided an interception device for protecting assets from incoming missiles, which device is autonomous of the asset being protected.

According to a further aspect of the present embodiments, there is provided a vehicular interception device for protecting assets from incoming missiles, the vehicular interception device comprising autonomous positioning for positioning said vehicle in relation to said assets and an expected threat.

According to an yet further aspect of the present embodiments, there is provided an interception device for protecting assets from incoming missiles, which device is man-portable for positioning to protect a perimeter.

An embodiment may be configured to track the location of at least one asset and to intercept an incoming missile threatening said asset.

An embodiment may be configured to track the locations of a plurality of assets as said assets move and to intercept an incoming missile threatening any one of said plurality of assets.

An embodiment may be configured to track the locations of a plurality of assets as said assets move, to move to a position to defend said assets against threats and to intercept an incoming missile threatening any one of said plurality of assets.

An embodiment may comprise a detection unit configured to detect incoming threats and a plurality of reaction units configured to intercept said incoming threats, and a control unit configured to select a best located reaction unit to react to a given incoming threat.

An embodiment may comprise a plurality of control units and a plurality of reaction units configured to intercept said incoming threats, said control units configured to communicate with each other to select a best located reaction unit to react to a given incoming threat.

An embodiment may comprise a radar unit configured to detect incoming threats, said radar unit associated with one of said control units.

An embodiment may relate to a system for protecting mobile or stationary objects from incoming missiles or rockets, which comprises: (a) a detection unit for detecting an incoming object; (b) a computing unit for: (i) receiving information relating to the detection of said incoming object, and location information from said plurality of assets (ii) calculating the trajectory of said incoming object, and (iii) analyzing said information to timely activate one or more of interceptor modules to at least damage said incoming object. The assets may be provided respectively with a positioning unit and a communication unit that are used for determining and transmitting, respectively, position data of each of the assets to ensure they are protected.

Brief Description of the Drawings

In the drawings:

- Fig. 1 shows in block diagram form the structure of a typical protection unit;
- Fig. 2a shows how a central protection unit according to the invention may be used to protect plurality of assets in a perimeter;
- Fig. 2b shows in block diagram form the structure of one embodiment of the system of the invention;
- Fig. 3 shows another embodiment of the system of the invention; and

- Figs. 4a, 4b, and 4c show respectively still another embodiment of the invention, where one or more of portable protection units are used.

Detailed Description of Preferred Embodiments

As noted, active protection systems utilizing the concept embodied by the Trophy system and the like are designed to protect the vehicle that they are mounted on. The radar of said systems (may it be an RF, optical or the like) is designed to scan the theater in which it operates, as to detect an incoming object, that is likely to hit the vehicle on which the radar and system are deployed. When the likelihood of a hit is established, the system is operated so as to intercept the incoming object as set forth. If, however, the system determines that the incoming object will not hit the vehicle or structure on which it is mounted, the system is not activated, even though the inbound object may eventually hit another friendly asset.

As will be shown, the present invention drastically increases the survivability of friendly assets in the battlefield, even when the assets are not equipped with a system-type as described above.

The present invention provides a method and system for protecting multiple assets, such as vehicles or structures, even when the assets themselves are not fitted with all or any of the systems components, i.e., the radar or the interceptors.

Fig. 1 shows a basic structure of a typical active protection system 10 (such as a Trophy-type system). The system comprises a detection unit 11 (such as electro-optic or RF radar), a computing unit 12, and one or more interception modules 13. Typically, the detection unit 11 continuously scans the perimeter around the vehicle. The scan readings are analyzed by the computing unit 12, so as to detect an incoming object that may pose a threat to the protected vehicle. Upon such detection, the computing unit 12 may activate the one or more interceptor modules in a manner that will assure the highest chance of intercepting the incoming object. However, if the computing unit 12 determines that the incoming object is not likely to hit the vehicle, it will avoid activation.

Figs. 2a and 2b illustrate a deployment of the system of the present invention in battle conditions, according to a first embodiment. An active protection system 110 is mounted on a Main Protection Vehicle (MPV) 115. The structure of system 110 (shown in Fig. 2b) is in fact similar to the structure of the system 10 of Fig. 1. In addition, MPV 115 comprises a positioning unit (such as GPS) 121a that determines its own position. In addition, MPV 115 comprises a communication unit (receiver or transceiver) 123. In addition, each of the other friendly assets 125b-125e in the perimeter of the MPV 115 comprises its own positioning unit 131b – 131e, and its own communication unit 133b-133e, respectively.

Each of the assets 125b-125e continuously transmits its own position via its own communication unit 133a-133d, respectively. Optionally, each of the assets might transmit additional asset data such as a unique ID, as well as its functionality, number of occupants, urgency and status of mission, acceleration readings, and any type of data that can be collected via sensors array, etc. The MPV 115 receives the transmitted locations, respectively from all of the assets 125, and optionally any additional asset data. The received information is analyzed by the computing unit 112 (shown in Fig. 2b) at the MPV 115, to determine which of the assets can be protected by the MPV 115. This determination process is based on the capability of the MPV to protect each of the assets, by analyzing the MPV's interceptor range, terrain (for example, by analyzing known Digital Elevation Maps), etc. Moreover, the received assets data can be taken into account to establish protection priorities for each of the assets 125. As the MPV's protected assets list is established, the MPV 115 may transmit its own list of protected assets (as well as any additional data related to the assets) to one or more of similar MPV's 115 in the battlefield. As other MPV's computing units 112 receive said list of protected assets (via their own communication unit 123), they can determine their own list of protected assets, respectively, taking into account their ability to protect assets in an optimal way. Furthermore, an MPV might take into account the amount of interceptor modules available to it, as well as any other relevant data.

As an MPV 115 establishes its own list of protected assets in the perimeter, inbound missiles that poses a threat to said list of protected assets may be intercepted by said MPV by initiation of its one or more interception modules 113.

In another embodiment, each of the various assets 125 might be equipped with its own interceptor modules 113b-113e, respectively, however without a detection unit (such as detection unit 111 of Fig. 2b), while in this case the MPV itself may be in charge of activating the interceptor modules 113 of each of the protected assets 125, accordingly.

It should be noted that the computing unit 112 of the MPV 115 may calculate a geographic location which is optimal for it to protect the assets existing in its own list. Once this geographic location is established, the MPV moves to this optimal calculated location. The MPV may further receive via its communication unit 123 real time intelligence driven data by which it may position or reposition itself, or it may amend its assets list. In still another alternative, the one or more MPVs 115 positions, and their asset lists, respectively, may be transmitted to a command and control center (not shown) as to allow a commanding body to assign each of a plurality of MPVs to secure a geographic perimeter, respectively, regardless of their own-calculated assets lists.

In still another embodiment, the MPV 115 may be of robotic type. In such a case, the MPV may use robotic driving capabilities known in the art to position itself within a military formation, such as a column of vehicles, so as to provide protection to the formation, which protection is updated as it moves.

In still another embodiment an MPV may be guided to a position either manually or robotically. On the MPV there are only interceptor modules 113 that are remotely activated by a remote detection unit 111 and a related computing unit 112 so as to secure friendly assets in a perimeter.

In still another embodiment shown in Fig. 3, the protection unit 110 is stationary. In some embodiments the unit may be man portable and in other embodiments may be

WO 2016/203481 PCT/IL2016/050643 -7-

provided by a vehicle. The protection unit scans via its detection unit 111 (not shown) a given terrain as to detect inbound missiles 141 aimed at friendly assets 125. The friendly assets may be moving vehicles or stationary structures or soldiers or formations of soldiers or vehicles. Stationary interceptors 113 may be positioned for example at predetermined geographical locations (such as next to a border 170) so as to achieve in very inexpensive way a very large scale perimeter protection of friendly assets. Likewise portable units may be positioned by soldiers engaged in operations to protect themselves from missile fire. Interceptors 113 may be positioned in large clusters so as to defeat an attempt to pierce the perimeter protection (such as border 170) by firing a large number of missiles to an exact point, the missiles being intended to exhaust the interceptors supply. In a preferred embodiment, large charges, for example, 25 Kg of composite B and 20 Kg of rigid fragments, such as metal balls, may be positioned in known positions, wherein the charges may be angled towards the direction from which the inbound missile is expected to come, and then the system may activates them as to destroy inbound missiles that are shot from hostile locations, for example, across the border line 170. The exact coordinates of each of the charge interceptors (charges)113 may be verified manually, for example, by use of GPS or surveying equipment, wherein the coordinates are fed into the computing unit 112 (not shown) of protecting system 110 as to enable it to timely activate one or more of the interceptors 113 to detonate appropriate charges.

In still another embodiment, the location of the assets 125 may be detected using a detection unit such as radar, camera, etc., while the asset location data is conveyed to the computing unit 112 (not shown) within the respective protecting unit 110. The radar may be mounted on an MPV 115, or may be static or may be man-portable.

In still another embodiment shown in Figs 4a, 4b, and 4c, a crucial battle zone problem is solved. In numerous events, soldiers in close quarter combat end up barricading themselves in a building. In events graphically depicted in the movie "Black Hawk Down", insurgents used RPG7 shoulder-mounted rockets to attack barricaded soldiers as the soldiers were unable to evacuate the compound in which they were besieged. As to secure a perimeter against shoulder mounted rockets, a portable interception unit 180 is provided to defeat incoming missiles. As shown in

Fig. 4b (showing the cross section of the portable interception unit 180), the charge within the interception unit 180 is comprised of rigid particles 181 (such as ball bearings), high explosive 182, and a detonation circuit (not shown). The charge is associated with a small short range detection unit 183 (such as optical, electromagnetic, RF radar, etc.), which may be housed within the casing of portable unit 180, or external thereof - as shown in Fig. 4c which shows a protection unit 110 which operates centrally to control one or more of units 180a-180d. Upon detection of an incoming missile by a detection unit 183, a blast sequence is initiated, ejecting the rigid particles towards the incoming missile to render it ineffective. As shown in Fig. 4c, a single protection unit 180 may control and activate a plurality of portable interceptors 180, via a physical line or wireless (using communication units 123). In the case where a plurality of portable interceptors are associated with a single protection unit 180 (as shown in Fig. 4c), the interceptors may be scattered at a distance from one another.

As activation of charges may be expected to coincide with an exact location of a charge in relation to an incoming missile trajectory, the portable interceptors 180, are equipped with a positioning unit 121, enabling the computing unit within the portable unit 180 to timely activate the blast sequence by the interceptors.

The different units 180, 180a, 180b etc may communicate with each other to ensure that only the most appropriately placed unit reacts to any given incoming threat.

In an embodiment, the MPV 115 may be sent ahead of a tank or other asset and provide a buffer zone or safety zone in which incoming missiles are destroyed ahead of the assets. Such a buffer zone may be useful in the case of soft assets such as soldiers being located in the vicinity of hard assets such as tanks.

The present embodiments may be able to provide protection at angles which the geometry of a tank makes difficult to protect.

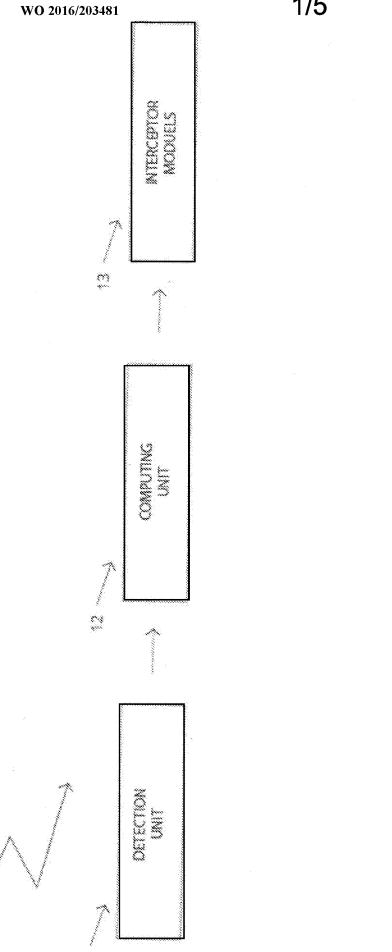
The MPV may be a vehicle dedicated to missile interception and may thus contain more interception capacity than can be carried on the asset itself. Furthermore detonation of the interception device may be distanced from the asset itself, thus avoiding damage to the asset. In this way, violent interception devices may be used to

WO 2016/203481 PCT/IL2016/050643 -9-

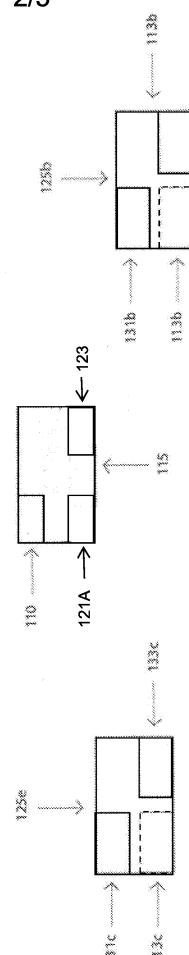
protect soft assets such as soldiers. The interception devices may be any kind of device and independent of the interception system.

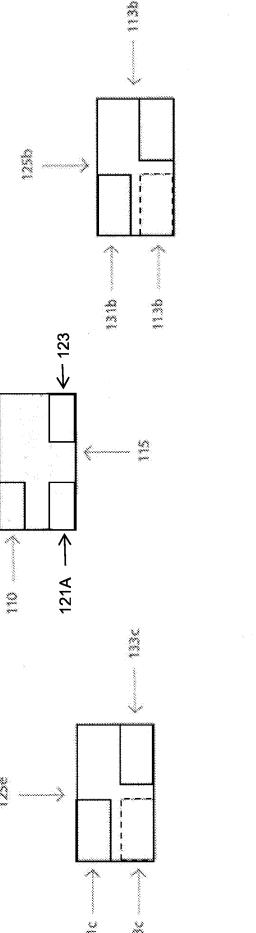
CLAIMS

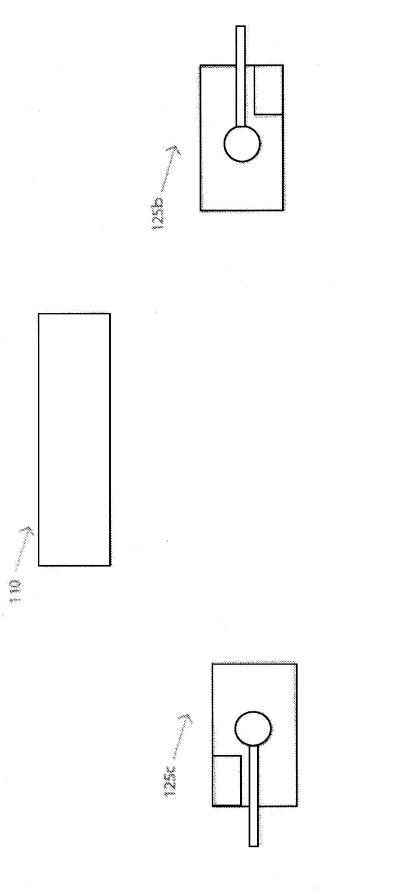
- 1. An interception device for protecting assets from incoming missiles, which device is autonomous of the asset being protected.
- 2. A vehicular interception device for protecting assets from incoming missiles, the vehicular interception device comprising autonomous positioning for positioning said vehicle in relation to said assets and an expected threat.
- 3. An interception device for protecting assets from incoming missiles, which device is man-portable for positioning to protect a perimeter.
- 4. The interception device of any one of claims 1 to 3, configured to track the location of at least one asset and to intercept an incoming missile threatening said asset.
- 5. The interception device of claim 4, configured to track the locations of a plurality of assets as said assets move and to intercept an incoming missile threatening any one of said plurality of assets.
- 6. The vehicular interception device of claim 2, configured to track the locations of a plurality of assets as said assets move, to move to a position to defend said assets against threats and to intercept an incoming missile threatening any one of said plurality of assets.
- 7. The interception device of any one of the preceding claims, comprising a detection unit configured to detect incoming threats and a plurality of reaction units configured to intercept said incoming threats, and a control unit configured to select a best located reaction unit to react to a given incoming threat.
- 8. The interception device of any one of claims 1 to 6, comprising a plurality of control units and a plurality of reaction units configured to intercept said incoming threats, said control units configured to communicate with each other to select a best located reaction unit to react to a given incoming threat.
- 9. The interception device of claim 8, further comprising a radar unit configured to detect incoming threats, said radar unit associated with one of said control units.

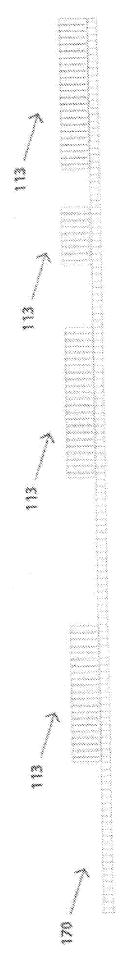


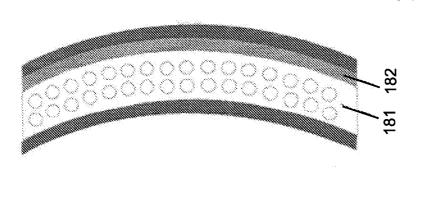












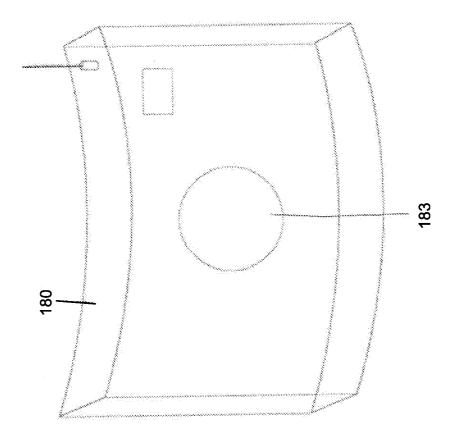


Fig. 4a

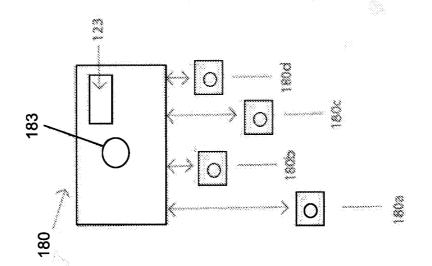


Fig. 4c

INTERNATIONAL SEARCH REPORT

International application No.

PCT/IL2016/050643

A. CLASSIFICATION OF SUBJECT MATTER

IPC (2016.01) F41H 13/00

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC (2016.01) F41H 5/007, H04H 20/59, G01S 7/02, F41C 27/06, F41G 5/08, G01V 1/18, F42B 12/00, G01S 13/00, F41G 7/00, F41H 11/02

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

Databases consulted: THOMSON INNOVATION, FamPat database

Search terms used: network, autonomous, active, defense, intecrcept, handheld, tactical, countermeasure

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 7077049 B2 SHUMOV SA [UA] 18 Jul 2006 (2006/07/18) Entire document	1,3,4,7-9
Y	Entire document	5
A	Entire document	2,6
Y	US 2008291075 A1 RAPANOTTI JOHN [CA] 27 Nov 2008 (2008/11/27) Entire document	5
A	Entire document	1-4,6-9
A	US 2007060045 A1 PRAUTZSCH FRANK R [US] 15 Mar 2007 (2007/03/15) Entire document	1-9

X Further documents are listed in the continuation of Box C.

X See patent family annex.

- * Special categories of cited documents:
- "A" document defining the general state of the art which is not considered to be of particular relevance
- "E" earlier application or patent but published on or after the international filing date
- "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)
- "O" document referring to an oral disclosure, use, exhibition or other means
- "P" document published prior to the international filing date but later than the priority date claimed
- "T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
- "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
- "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art
- "&" document member of the same patent family

Date of the actual completion of the international search	Date of mailing of the international search report
12 Sep 2016	13 Sep 2016
Name and mailing address of the ISA:	Authorized officer
Israel Patent Office	CHOVER Nimrod Israel
Technology Park, Bldg.5, Malcha, Jerusalem, 9695101, Israel	
Facsimile No. 972-2-5651616	Telephone No. 972-5651692

INTERNATIONAL SEARCH REPORT

International application No.
PCT/IL2016/050643

C (Continua			
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No	
A	US 2014138474 A1 SHARPIN DAVID [US]; KOLANEK JIM [US]; CVETNIC MARK A [US]; HUTCHINGS MIKE [US]; TENNISON JAMES [US]; NELSON KENT CARL [US]; HUNSBERGER HAROLD KREGG [US]; BASEGHI BEHSHAD [US]; ALLIANT TECHSYSTEMS INC [US] 22 May 2014 (2014/05/22) Entire document	1-9	
A	EP 2482026 A2 DIEHL BGT DEFENCE GMBH & CO KG [DE] 01 Aug 2012 (2012/08/01) Entire document	1-9	

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No.
PCT/IL2016/050643

Pat _	ent document c report	ited search	Publication date	P	atent family mem	iber(s)	Publication Date
US	7077049	B2	18 Jul 2006	US	2006107829	A1	25 May 2006
				US	7077049	B2	18 Jul 2006
				AT	320584	T	15 Apr 2006
				DE	602004000482	D1	11 May 2006
				DE	602004000482	T2	16 Nov 2006
				EP	1467171	A1	13 Oct 2004
				EP	1467171	В1	15 Mar 2006
				ES	2260729	Т3	01 Nov 2006
				WO	2004090459	A1	21 Oct 2004
us	2008291075	A1	27 Nov 2008	US	2008291075	A1	27 Nov 2008
us	2007060045	A1	15 Mar 2007	US	2007060045	A1	15 Mar 2007
				WO	2007084147	A2	26 Jul 2007
				WO	2007084147	A3	07 Sep 2007
US	2014138474	A1	22 May 2014	us	2014138474	A1	22 May 2014
				US	9170070	B2	27 Oct 2015
				US	2016047628	A1	18 Feb 2016
				US	2016048129	A1	18 Feb 2016
				US	2016178331	Al	23 Jun 2016
				WO	2013130518	Al	06 Sep 2013
				WO	2014093462	Al	19 Jun 2014
				WO	2014197038	A1	11 Dec 2014
EP	2482026	A2	01 Aug 2012	EP	2482026	A2	01 Aug 2012
				EP	2482026	A 3	15 Apr 2015
				DE	102011009460	A1	26 Jul 2012
				DE	102011009460	B4	20 Aug 2015
				ΙL	217147	D0	28 Jun 2012