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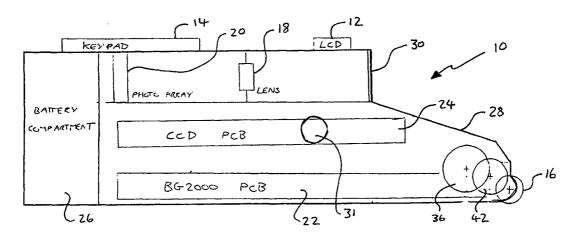
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(54) Title: CONTENTS MEASURING APPARATUS AND METHOD AND STOCK CONTROL SYSTEM



(57) Abstract

A hand-held device for measuring the contents of containers and for use as part of a stock control system includes a barcode reader and a friction roller (16) and associated rotary encoder for measuring the distance from the top or bottom of a container to the surface of contents stored within the container. The measured distance is correlated with barcode information to calculate the contents of the container. The device may include on-board data storage and data-processing to perform volume calculations, or barcode information and distance measurements may be transmitted to a host data-processing system. The device is particularly suited for stock control purposes in licensed premises.

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Contents Measuring Apparatus and Method and Stock 1 Control System 2 3 The present invention relates to apparatus and methods 4 for determining the contents of containers. 5 invention is intended particularly, but not 6 exclusively, for measuring the contents of containers 7 such as bottles for stock-taking purposes. 8 9 Effective stock control is a long-standing problem in 10 the licensed trade, particularly with regard to "broken 11 stock"; i.e. bottles of spirits or the like which have 12 been opened and partially used. Stock-taking methods 13 with regard to such stock generally involve visual 14 estimates of the remaining contents of partially-used 15 bottles, and are notoriously inaccurate. The adoption 16 of more accurate measurement methods is hampered by the 17 fact that the bottles in question are commonly stored 18 in gantries, fitted with "optic" dispensing devices, or 19 on shelves etc. 20 21 It is an object of the present invention to provide 22 improved apparatus and methods for measuring and 23 logging the contents of containers such as bottles. 24 25 In accordance with a first aspect of the invention, 26 there is provided apparatus for measuring the contents 27

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of containers comprising a unit adapted for hand-held 1 use and including: 2 measuring means for determining the distance from 3 the top or bottom of a container to the surface of 4 contents stored within the container; and 5 identifying means for identifying the type of a 6 particular container being measured; characterised in 7 that: 8 said measuring means comprises a friction roller 9 and rotary encoding means associated with said friction 10 11 roller. 12 Preferably, said identifying means comprises bar code 13 reading means for reading standard retail bar codes 14 applied to the containers to be measured. 15 16 Preferably, the bar code reading means is disposed in 17 fixed spatial relationship with the friction roller of 18 said measuring means. 19 20 Preferably, the apparatus further includes: 21 data storage means for storing data relating to a 22 plurality of different types of container the contents 23 of which the apparatus is to be used to measure; and 24 data processing means for calculating the amount 25 of the contents of said particular container from said 26 distance, the type of the container, and the stored 27 data relating to the relevant type of container. 28 29 Preferably, said data storage means comprises memory 30 means storing a database of information correlating 31 measured linear distances with equivalent volumes for 32 33 each type of container. 34 Preferably, the apparatus further includes wireless 35 transceiver means whereby said device may communicate 36

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1	with a host data processing system.
2	
3	Preferably, the apparatus is adapted to transmit data
4	representing said distance and/or the type of container
5	to said host system.
6	
7	In accordance with a second aspect of the invention,
8	there is provided a stock control system comprising
9	apparatus in accordance with the first aspect of the
10	invention, in combination with a host data processing
11	system.
12	
13	Preferably, said host system includes data storage
14	means for storing data relating to a plurality of
15	different types of container the contents of which the
16	apparatus is to be used to measure; and
17	data processing means for calculating the amount
18	of the contents of said particular container from said
19	distance, the type of the container, and the stored
20	data relating to the relevant type of container.
21	
22	Preferably, said data storage means is adapted to store
23	a database of information correlating measured linear
24	distances with equivalent volumes for each type of
25	container.
26	
27	In accordance with a third aspect of the invention,
28	there is provided a method of measuring the contents of
29	a container comprising:
30	measuring the depth of the contents of the
31	container by means of a friction roller and associated
32	rotary encoder means;
33	reading a bar code on the container to obtain
34	details of the container; and
35	correlating said measured depth and said details
36	with previously stored information regarding the

1	container type, and calculating the volume of said
2	contents therefrom.
3	
4	Preferably, the method is implemented by means of
5	apparatus in accordance with the first aspect of the
6	invention and/or a system in accordance with the second
7	aspect of the invention.
8	•
9	Embodiments of the invention will now be described, by
10	way of example only, with reference to the accompanying
11	drawings, in which:
12	
13	Fig. 1 is a schematic, sectional side view of a
14	first embodiment of a contents measuring device in
15	accordance with the invention;
16	
17	Fig. 2 is a schematic perspective view of the
18	device of Fig. 1;
19	
20	Fig. 3 is a block diagram illustrating the major
21	components of the device of Fig. 1;
22	
23	Figs. 4a, 4b and 4c are, respectively, plan, side
24	and front views of a gear train mechanism forming
25	part of the device of Fig. 1;
26	
27	Fig. 5 is a schematic, sectional side view of a
28	second embodiment of a contents measuring device
29	in accordance with the invention;
30	
31	Fig. 6 is a schematic plan view of the device of
32	Fig. 5; and
33	
34	Fig. 7 is a block diagram illustrating the major
35	components of the device of Fig. 5 and an
36	associated data processing system.

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Referring now to the drawings, a measuring device 1 embodying the invention comprises a battery powered, 2 hand-held unit 10 including a visual display 12, such 3 as a liquid crystal display (LCD), for data readout by 4 the user and a keypad 14 or the like for data input and 5 for controlling the operation of the device. 6 display 12 might suitably comprise a 16 character by 4 7 line display unit. 8 9 The device further includes distance measuring means 10 comprising a friction roller 16 forming part of a 11 rotary encoder assembly and bar code reading means 12 including a lens 18 and photo array 20. The main 13 electronic components for the device are mounted on a 14 first printed circuit board (PCB) 22, and the 15 electronics specific to the bar code reader are mounted 16 on a second PCB 24. Power is supplied by batteries 17 contained in a battery compartment 26. 18 19 The components of the device are enclosed in a housing 20 28, of a size and shape suitable for hand-held (single-21 handed) operation. The friction roller 16 is located 22 at the front and bottom edge of the housing 28, for 23 rotation about a horizontal, transverse axis. 24 code reading lens 18 and photo array 20 are located in 25 the top portion of the housing, with a protective 26 window 30 facing the front of the device (i.e. the 27 optical axis of the bar code reading optics is 28 substantially parallel to the longitudinal axis of the 29 device and at right angles to the axis of rotation of 30 the roller 16). The display 12 and keypad are located 31 on the top surface of the housing 28 and the battery 32 compartment 26 is in the rear portion of the housing 33 A control switch 31 is located on one side of the 34 housing 28 for controlling the operation of the device. 35 36

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Rotary encoders are well known and will not be 1 described in detail herein. The preferred embodiment 2 employs an optical type rotary encoder, using an infra 3 red transmitter device 32 and infra red receivers 34 4 (Fig. 3). A slotted wheel 36 is disposed between the 5 transmitter 32 and receivers 34, so that rotation of 6 the wheel results in a pulsed output from the receivers 7 The number of pulses output by the receivers 8 provides an indication of the number of revolutions of 9 the slotted wheel 36. 10 11 The friction roller 16 is coupled to the slotted wheel 12 36 so that rotation of the friction roller causes 13 rotation of the slotted wheel. Accordingly, the 14 distance travelled by the roller when the device 10 is 15 moved along a surface can be calculated from the number 16 of pulses output from the receivers 34. Preferably, 17 the roller 16 has a first toothed gear wheel 38 mounted 18 on its shaft 40 for rotation therewith (Figs. 4a, 4b, 19 4c). Rotational movement of the roller 16 is 20 transmitted to the slotted wheel 36 by the first gear 21 38 engaging a second toothed gear wheel 42 mounted on 22 second shaft 44, which in turn engages a third toothed 23 gear wheel 46 mounted on a third shaft 48 which also 24 mounts the slotted wheel 36. The shafts 40, 44 and 48 25 are all substantially parallel to one another. The 26 gear train connecting the roller to the slotted wheel 27 is advantageous in preventing dust or other debris or 28 contaminants picked up by the roller 16 being 29 transferred to the slotted wheel 36 and possibly 30 interfering with the optical path between the IR 31 transmitter 32 and receivers 34. 32 33 The bar code reader (collectively identified by numeral 34 50 in Fig. 3) comprises a standard set of components 35 for reading standard retail bar codes and will not be 36

1	described in detail herein. The bar code reading
2	optics are mounted in fixed spatial relationship with
3	the roller 16. If the roller 16 is placed in contact
4	with an object when a bar code on the object is to be
5	read, then the bar code reading optics will be
6	(approximately) at a known distance from the bar code.
7	This enables a relatively low-specification bar code
8	reading system to be employed, reducing the cost and
9	complexity of the device as a whole.
10	
11	The main PCB 22 includes a microprocessor 52 and memory
12	54. The IR transmitter 32 and receivers 34 may be
13	located on the PCB 22 at its forward edge, adjacent the
14	slotted wheel 36, together with associated amplifiers
15	56 for amplifying the outputs from the receivers 34.
16	The display 12, keypad 14, bar code reader 50 and
17	amplifiers 56 are all connected to the processor 52.
18	The memory 54 contains a database of information
19	correlated with bar code information and also acts as a
20	data-logging store.
21	
22	The roller 16 and rotary encoder can thus be used to
23	measure linear distances, calculated by the processor
24	52 from the pulsed output from the amplifiers 56.
25	These distances can be correlated with information
26	obtained from the bar code reader 50 and stored in the
27	memory 54 to calculate a volume corresponding to a
28	linear distance.
29	
30	For measuring the contents of bottles in a bar
31	environment or the like, the device is used as follows.
32	
33	The operator places the roller 16 in contact with the
34	surface of a bottle adjacent the standard retail bar
35	code label on the bottle and depresses the control
36	switch 31. The bar code is read and decoded, and the

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brand and package size can be displayed for 1 verification purposes. The roller 16 is then run 2 vertically along the surface of the bottle to measure 3 the distance between the top or bottom of the bottle 4 and the surface of the liquid contained therein. 5 system software is adapted to detect the direction of 6 motion of the roller, so that measurements can be made 7 of bottles mounted upside down in a gantry with an 8 optic dispensing device and bottles free-standing on a 9 supporting surface. 10 11 The bar code information yields the product brand and 12 the size of the bottle. The system database stores 13 information for each brand and bottle size, allowing a 14 volume to be calculated from a distance travelled along 15 the surface of the bottle. The calculated volume is 16 then stored along with the product brand and bottle 17 size, for stock control purposes. The software can 18 also allow for additional liquid volume held in the 19 optic dispenser of a gantry-mounted bottle. Reverse 20 movement of the device during a measurement can also be 21 detected and compensated for. 22 23 The bar code reader can also be used to collect data 24 relating to "unbroken" stock (unopened bottles) and any 25 other stock items having retail bar codes. Unreadable 26 bar codes can also be keyed in manually. Information 27 regarding bottles without bar codes can also be keyed 28 in manually, allowing at least an estimate to be made 29 of the contents of such bottles. Other stock control 30 data can also be input manually via the keypad. 31 device can thus be used as the basis of a complete 32 stock control system for a bar or similar business 33 34 operation. 35 For measuring the contents of bottles, the device

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relies on the liquid level within the bottle being 1 visible to the operator. A very few types of bottle 2 may be so opaque that this is not possible, requiring 3 manual input of an estimated volume. The device might 4 further be provided with a light source to illuminate 5 the bottle, to assist in viewing the liquid level in 6 semi-opaque bottles. However, the large majority of 7 brands encountered in practice will present no 8 difficulty in this regard. 9 10 The rotary encoder may be configured to provide any 11 required degree of resolution/accuracy. A system 12 providing 4 counts per millimetre is easily achievable, 13 giving accuracy substantially better than 1% for spirit 14 bottles and the like. The system software may also 15 compensate for the "dead zone" arising from the roller 16 16 abutting a horizontal supporting surface. The path 17 followed by the roller along the surface of the bottle 18 would have to deviate substantially from the vertical 19 before such deviation would have any significant 20 influence on the accuracy of the measurement. 21 22 The device may further be provided with standard data 23 ports (not shown) allowing connection to a separate 24 computer, printer or other device. This allows 25 collected data to be downloaded from the unit and new 26 database information to be uploaded to the device. 27 28 The use of a friction roller/rotary encoder to 29 determine the depth of liquid in the bottles is 30 particularly advantageous. Other possible distance 31 measuring techniques such as optical (laser) or 32 acoustic (ultrasonic) systems, or even manual 33 measurement have various disadvantages in practice. 34 The use of a friction roller is reliable and is 35 particularly suitable for measuring the contents of 36

10

gantry-mounted bottles. The device requires no 1 further tuning or calibration after manufacture. 2 3 The friction roller 16 of the described embodiment is a 4 free-wheeling roller. However, it could be positively 5 driven by an electric motor or the like if required. 6 7 Figs. 5 to 7 illustrate an alternative, preferred 8 embodiment of a measuring device in accordance with the 9 The basic principle of operation of this invention. 10 embodiment is substantially similar to the first 11 embodiment, but with a number of differences as shall 12 be described below. 13 14 The device again comprises a hand-held unit 110 having 15 a housing 128, visual display 112, keypad 114, friction 16 roller 116, bar code reader 118, a first, main PCB 122, 17 a second PCB 124 associated with the bar code reader 18 118, a battery compartment 126 and main control switch 19 131, broadly similar to those of the first embodiment. 20 21 In this case, the housing 128 has an enhanced ergonomic 22 design comprising a handle portion 202, a head portion 23 204 and a nose portion 206, suitably formed from 24 moulded plastic material. The visual display 112 is 25 located on a top surface of the head portion 204, the 26 keypad 114 on a top surface of the handle portion 202 27 and the control button 131 is located between the 28 visual display 112 and keypad 114. The contact wheel 29 116 is located in the nose portion 206 at the forward 30 and lowermost extremity of the unit 110. The bar code 31 reader 118, PCBs 122 and 124 and battery compartment 32 126 are enclosed within the housing 128. The friction 33 roller 116 again forms part of a rotary encoder 34 assembly which may be similar to that of the first 35 embodiment, including a similar gear train. 36

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embodiment, the slotted integrating wheel and 1 electronic components specific to the rotary encoder 2 are mounted on a further PCB 208, located in the nose 3 portion 206 of the housing 128, rather than being 4 incorporated into the main PCB 122. 5 6 In this embodiment, the window of the barcode reader 7 118 faces out of one side of the device (i.e. the 8 optical axis of the bar code reading optics is 9 substantially at right angles to the longitudinal axis 10 of the device and parallel to the axis of rotation of 11 the roller 16). This improves the ergonomics of the 12 device for efficient single-handed operation. 13 14 The present embodiment may include memory means 15 providing an on-board database of information 16 correlated with bar code information and acting as an 17 on-board data-logging store as in the previous 18 embodiment. However, it is preferred that the device 19 includes wireless transceiver means 210, including an 20 antenna 212, most preferably radio transceiver means, 21 whereby the device may communicate in a dynamic, 22 interactive manner with a host computer system or other 23 information processing system such as a "smart" till, 24 point-of-sale (POS) system or the like. In this way, 25 the device may form an integrated part of a 26 sophisticated stock control system, which may be 27 networked on a local or wide-area basis by any suitable 28 communications channels. RF screening such as 29 indicated at 213 may be incorporated into the device in 30 order to isolate the transceiver module 210 from the 31 other electronic components as required. 32 33 Fig. 7 is a block diagram illustrating the main 34 components of the device and of a host system. The 35 device includes the distance measuring means 116/208, 36

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barcode reader 118, keypad 114, display 112, CPU 152 1 and transceiver module 210. The host system might 2 typically comprise a computer having a CPU 214, local 3 data storage 216, input/output devices such as a 4 keyboard 218 and visual display unit (VDU) 220, a 5 transceiver module 222 for communicating with the hand-6 held device and, where applicable, onward connections 7 to local or wide-area networks 224. 8 9 In an integrated system of this type, it is unnecessary 10 for the hand-held device to store a complete database 11 of product information on-board, does not need to 12 calculate volumes from distance measurements, does not 13 need to store the results of such calculations, and 14 does not require periodic uploading and downloading of 15 data. The necessary database information, data-16 processing and data-logging can be performed by the 17 computer or wider system with which the device is in 18 communication. It is only necessary for the device to 19 transmit the relevant barcodes and associated 20 measurements to the local host (unbroken stock items 21 only require the barcode information or other data 22 identifying the item to be transmitted). Of course, 23 the device/system could operate in a variety of 24 different ways; e.g. with an on-board cache of database 25 information and limited on-board data processing and 26 logging, rather than being in constant two-way 27 communication with the local host. 28 29 In an alternative embodiment, the hand-held device 30 might be adapted simply to log distance measurements 31 and barcode data which can be downloaded periodically 32 to a host system by any suitable means (wireless or 33 otherwise), the host system containing the required 34 product information database and performing the 35 necessary data-processing to calculate volumes from 36

1	distance measurements.
2	
3	This type of interaction with a host system enables the
4	device to operate with an unlimited range of stock
5	without requiring expensive on-board memory and data-
6	processing resources.
7	
8	Improvements and modifications may be incorporated
9	without departing from the scope of the invention as
10	defined in the Claims appended hereto.
11	

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1	<u>Claims</u>
2	
3	1. Apparatus for measuring the contents of containers
4	comprising a unit adapted for hand-held use and
5	including:
6	measuring means for determining the distance from
7	the top or bottom of a container to the surface of
8	contents stored within the container; and
9 .	identifying means for identifying the type of a
10	particular container being measured; characterised in
11	that:
12	said measuring means comprises a friction roller
13	and rotary encoding means associated with said friction
14	roller.
15	
16	2. Apparatus as claimed in Claim 1, wherein said
17	identifying means comprises bar code reading means for
18	reading standard retail bar codes applied to the
19	containers to be measured.
20	
21	3. Apparatus as claimed in Claim 2, wherein the bar
22	code reading means is disposed in fixed spatial
23	relationship with the friction roller of said measuring
24	means.
25	
26	4. Apparatus as claimed in any preceding Claim,
27	further including:
28	data storage means for storing data relating to a
29	plurality of different types of container the contents
30	of which the apparatus is to be used to measure; and
31	data processing means for calculating the amount
32	of the contents of said particular container from said
33	distance, the type of the container, and the stored
34	data relating to the relevant type of container.
35	

36 5. Apparatus as claimed in any preceding Claim,

15 wherein said data storage means comprises memory means 1 storing a database of information correlating measured 2 linear distances with equivalent volumes for each type 3 of container. 4 5 Apparatus as claimed in any preceding Claim, 6 further including wireless transceiver means whereby 7 said device may communicate with a host data processing 8 system. 9

10

7. Apparatus as claimed in Claim 6, wherein the apparatus is adapted to transmit data representing said distance and/or the type of container to said host system.

15

8. A stock control system comprising apparatus as defined in any preceding Claim, in combination with a host data processing system.

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9. A system as claimed in Claim 8, wherein said host system includes data storage means for storing data relating to a plurality of different types of container the contents of which the apparatus is to be used to measure; and

data processing means for calculating the amount of the contents of said particular container from said distance, the type of the container, and the stored data relating to the relevant type of container.

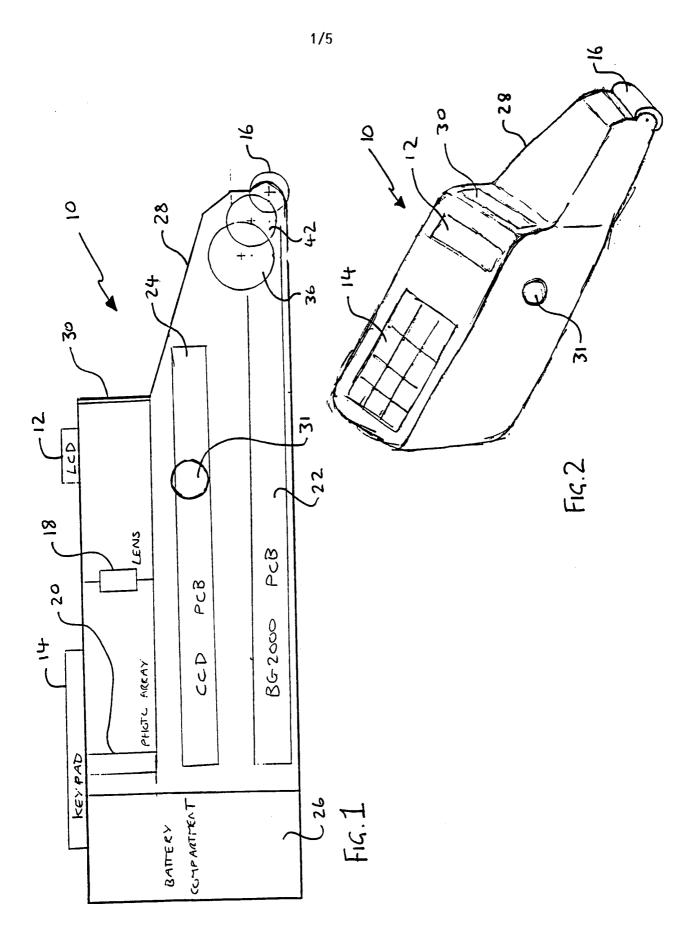
28 29

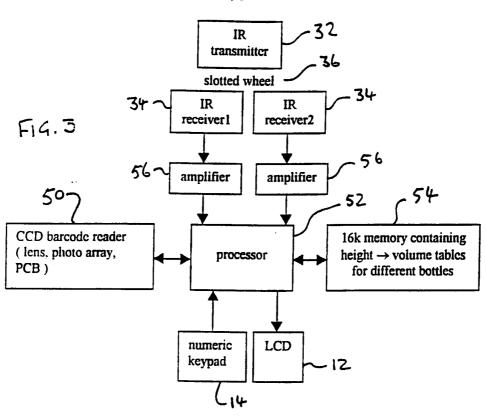
10. A system as claimed in 9, wherein said data 31 storage means is adapted to store a database of 32 information correlating measured linear distances with 33 equivalent volumes for each type of container.

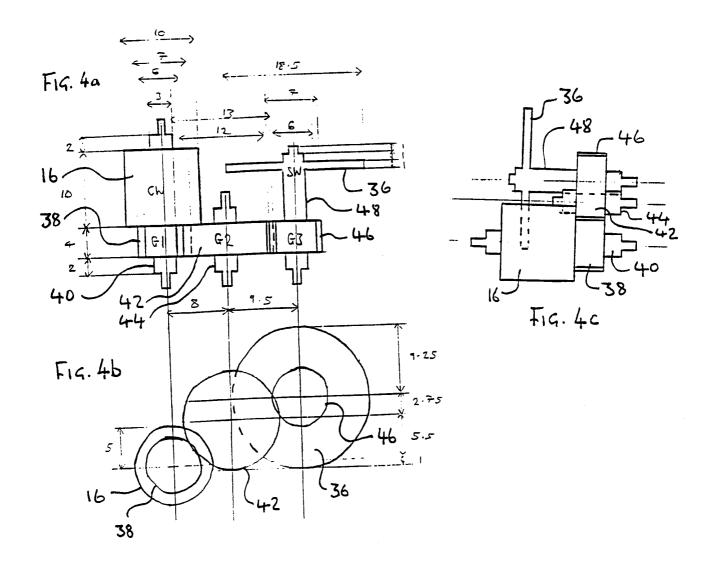
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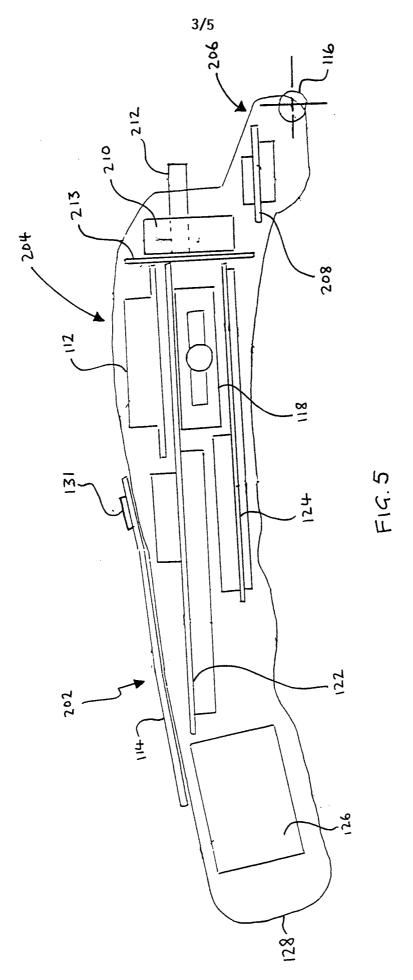
35 11. A method of measuring the contents of a container 36 comprising:

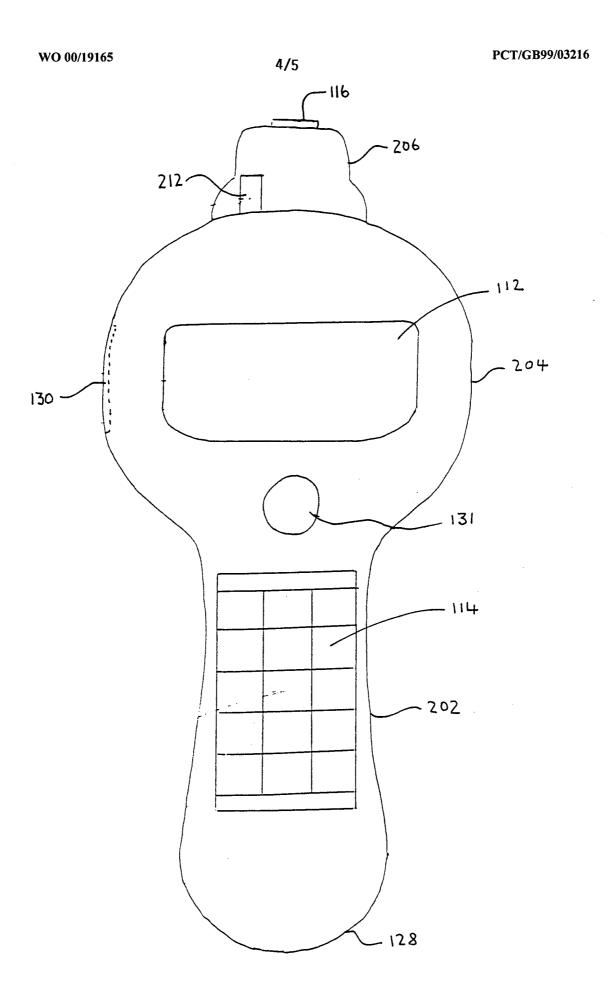
1	measuring the depth of the contents of the
2	container by means of a friction roller and associated
3	rotary encoder means;
4	reading a bar code on the container to obtain
5	details of the container; and
6	correlating said measured depth and said details
7	with previously stored information regarding the
8	container type, and calculating the volume of said
9	contents therefrom.
10	
11	12. A method as claimed in Claim 11, implemented by
12	means of apparatus as claimed in any one of Claims 1 to
13	7 and/or a system as claimed in any one of Claims 8 to
14	10.
15	











F14.6

F19.7 210 T/X 116/208 118 152 CPU 114 112 222 TX 214 216 224 LAN/WAN CPU 218 220

INTERNATIONAL SEARCH REPORT

Int tional Application No PCT/GB 99/03216

A. CLASSI IPC 7	FICATION OF SUBJECT MATTER G01B3/12 G06K7/10 G01F23	3/00	
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C. DOCUM	ENTS CONSIDERED TO BE RELEVANT		
Category *	Citation of document, with indication, where appropriate, of the	e relevant passages	Relevant to claim No.
X	US 5 755 918 A (CHRISTOPHER AM' 26 May 1998 (1998-05-26) column 2, line 26 - line 49 column 3, line 9 - line 41 column 4, line 37 - line 50 column 6, line 55 - line 67	Y S ET AL)	1-3,6-8
\ ,	figures 1-7		4,5,9-12
Y			
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Fur	ther documents are listed in the continuation of box C.	Patent family members are listed	l in annex.
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Name and	mailing address of the ISA European Patent Office, P.B. 5818 Patentlaan 2 NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Tx. 31 651 epo nl, Fax: (+31-70) 340-3016	Authorized officer de Ronde, J.	

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Information on patent family members

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