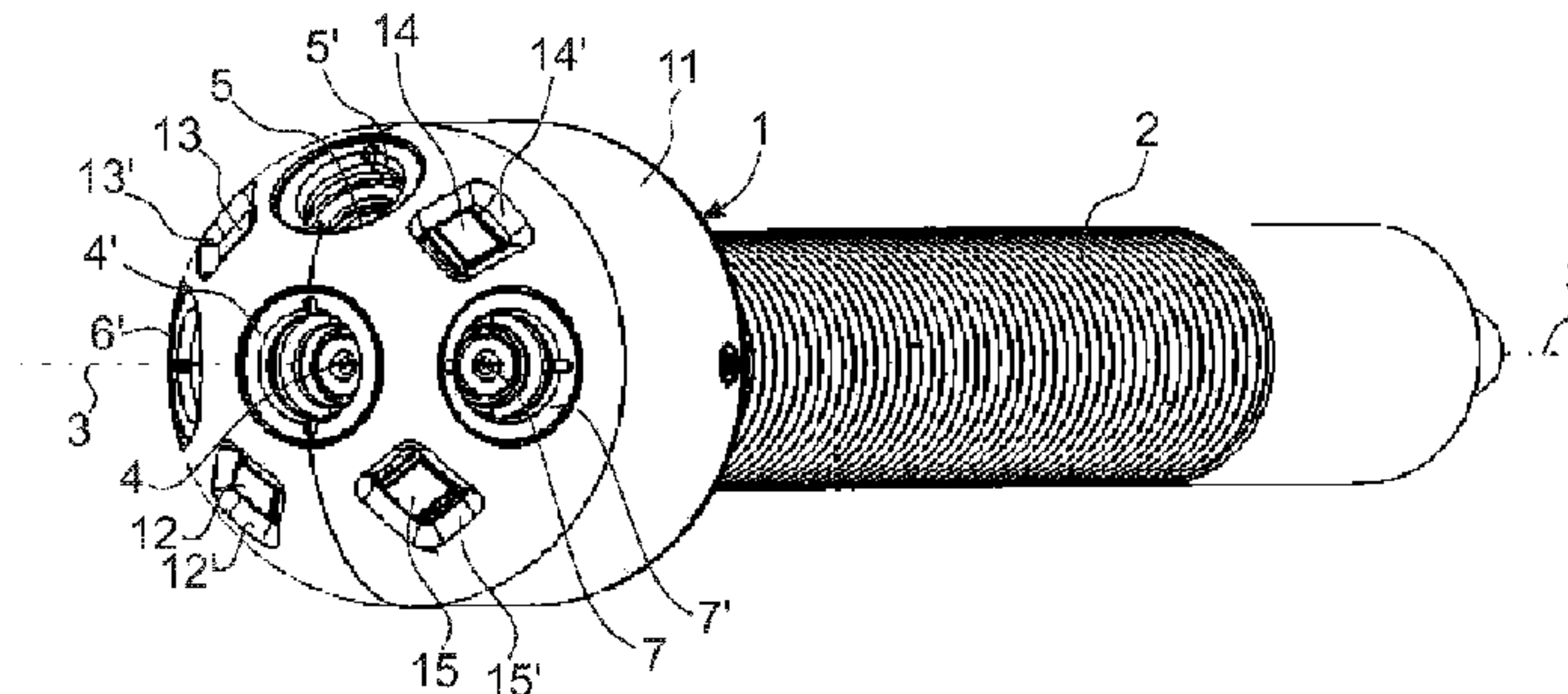




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(54) Title: PIPE INSPECTION DEVICE



(57) **Abrégé/Abstract:**

A pipe inspection device includes a housing (1) fixed to a semi-rigid rod (2) and having a longitudinal axis (3) and inside the housing a camera (4) having a forward-looking field of view and a camera (5) rotatable around said longitudinal axis (3) and having a field of view directed to permit closer inspection of an inner surface of the pipe, and means (17-24) for rotating the rotatable camera (5) to direct its field of view against an area of the inner surface of the pipe to be inspected more closely. To make it possible to inspect the inner surface of a pipe faster than with prior art devices, the inspection device has at least two cameras (5-7) in addition to the camera (4) having a forward-looking field. Said at least two cameras (5-7) are rotatable as an assembly around the longitudinal axis and have a field of view directed to permit closer inspection of an inner surface of the pipe. Further, the housing (1) has a fixed rear part (10) and a front part (11) that is carried by the rear part (10) and rotatable around said longitudinal axis (3), all of the cameras (4-7) being fixed in the rotatable front part (11) of the housing (1).

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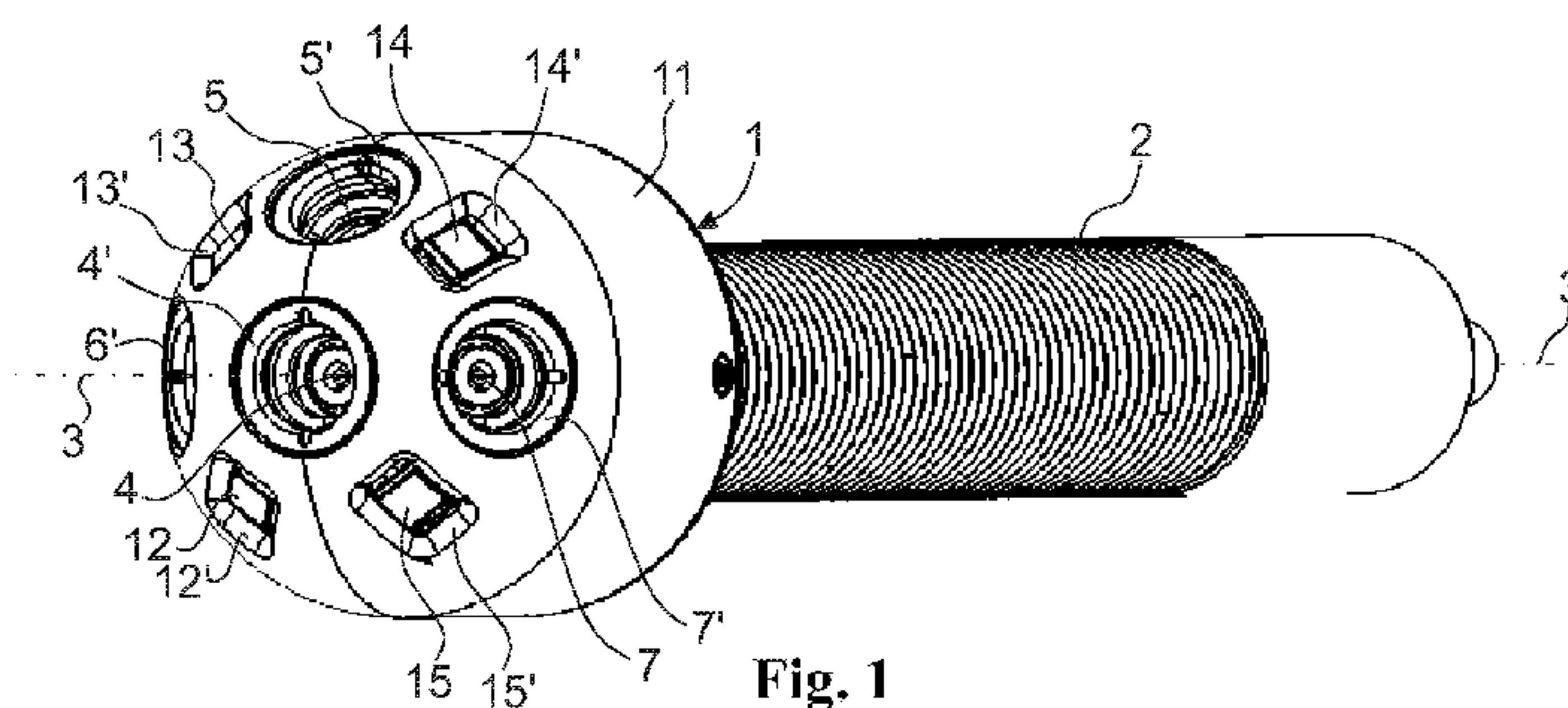


Fig. 1

(57) **Abstract:** A pipe inspection device includes a housing (1) fixed to a semi-rigid rod (2) and having a longitudinal axis (3) and inside the housing a camera (4) having a forward-looking field of view and a camera (5) rotatable around said longitudinal axis (3) and having a field of view directed to permit closer inspection of an inner surface of the pipe, and means (17-24) for rotating the rotatable camera (5) to direct its field of view against an area of the inner surface of the pipe to be inspected more closely. To make it possible to inspect the inner surface of a pipe faster than with prior art devices, the inspection device has at least two cameras (5-7) in addition to the camera (4) having a forward-looking field. Said at least two cameras (5-7) are rotatable as an assembly around the longitudinal axis and have a field of view directed to permit closer inspection of an inner surface of the pipe. Further, the housing (1) has a fixed rear part (10) and a front part (11) that is carried by the rear part (10) and rotatable around said longitudinal axis (3), all of the cameras (4-7) being fixed in the rotatable front part (11) of the housing (1).

WO 2014/200398 A1

PIPE INSPECTION DEVICE

DESCRIPTION

5

TECHNICAL FIELD

The present invention relates to a pipe inspection device including a housing fixed to a semi-rigid rod and having a longitudinal axis and inside the housing a camera having a forward-looking field of view and a camera rotatable around said longitudinal axis and
10 having a field of view directed to permit closer inspection of an inner surface of the pipe, and means for rotating the rotatable camera to direct its field of view against an area of the inner surface of the pipe to be inspected more closely.

BACKGROUND ART

15 Devices for inspecting the inner side of a pipe generally comprise a casing, inside which is mounted a camera having a forward-looking view and a separate light source. The device is fixed to one end of a semi-rigid rod, which is pushed down a pipe to be inspected. The rod encloses wires for supply of electrical power to the device from a supply outside the pipe and at the same time image signals from the camera to a monitor
20 outside the pipe. On pushing the camera along the pipe, the casing with the camera tends to rotate about its longitudinal axis, so that the image displayed on the monitor is similarly rotated, which makes it difficult to determine the orientation of an image.

To maintain the attitude of the camera it is suggested in US 6,611,661 B1 (Buck) and
25 US 2006/0275725 A1 (Olsson et al.) to make the camera self-leveling by using a leveling weight and mount the camera and the weight freely rotatable within the housing, such that gravitational forces maintain the rotational orientation (attitude) of the camera independent of the housing. None of these two documents discloses the use of a second camera directed to permit closer inspection of an inner surface of the pipe.

30

A pipe inspection device having two cameras, one for looking forward and one for looking sideways to inspect the inner wall of the pipe fore closely is disclosed in GB 2 342 419 A (Pearpoint Ltd.). The two cameras form an assembly that is rotatable around the longitudinal axis inside the housing, and the sideways looking camera is
35 directed strictly sideways, at a right angle to the longitudinal axis of the housing, and to make it possible for the camera to see the pipe wall, the housing has a circumferential window. The rotation is accomplished by a motor provided inside the casing and, if

desired, a sensor may be provided for driving the motor in response to changes in the attitude of the device.

To protect this circumferential window from getting scratched or mechanically damaged
5 in some other way during use of the inspection device, the outer diameter of the window is recessed in comparison with the outer diameter of adjacent portions of the housing. However, to form such a recess, the diameter of adjacent portions of the housing have to be increased, which is a drawback, since it is desirable to make the diameter of the housing as small as possible. Further, such a recess will increase the risk of the
10 inspection device getting stuck in the pipe during inspection thereof, and the recess will also be exposed to accumulation of dirt therein, and irrespective of any rotation of the camera, the rotatable camera cannot inspect pipe surface areas hidden behind the accumulated dirt on the window.

15 In addition, the camera assembly may require a rotation of up to 180° from a normal top position in order to inspect an area at the bottom of the pipe, and every rotation is time-consuming, even if the rotation is smaller than 180° . To cover an entire pipe a full rotation of 360° may be required.

20 In addition, the camera assembly may require a rotation of up to 180° from a normal top position in order to inspect an area at the bottom of the pipe, and every rotation is time-consuming, even if the rotation is smaller than 180° .

SUMMARY OF THE INVENTION

25 The main object of the present invention is to provide a pipe inspection device with reduced dimensions by means of which an inspection of the inner surface of a pipe can be carried out faster than with prior art devices.

The object is achieved in accordance with the present invention in that in a pipe
30 inspection device of the kind referred to in the first paragraph above:

- a) in addition to the camera having a forward-looking field, the inspection device has at least two cameras that are rotatable as an assembly around said longitudinal axis and have a field of view directed to permit closer inspection of an inner surface of the pipe; and
- 35 b) the housing has a fixed rear part and a front part that is carried by the rear part and rotatable around said longitudinal axis, all of the cameras being fixed in the rotatable front part of the housing.

By having at least two cameras for the closer inspection of the inner wall of the pipe, it is possible to inspect a larger area without any rotation at all, and if a rotation is necessary, the rotation angle required is much smaller than when a single camera is used. Thus, using the at least two cameras instead of just one is time-saving.

Said at least two rotatable cameras have their fields of view directed obliquely forward or perpendicularly to the longitudinal axis. By having the fields of view directed obliquely forward, the diameter of the housing may be reduced and the windows for the cameras are less exposed to mechanical damage and accumulation of dirt. This also makes it possible to make the exterior of the housing at the rear of the cameras even and streamlined, so that the risk of the inspection device getting stuck in the pipe will be reduced.

Suitably, the at least two rotatable cameras have their fields of view directed to be in the range of 20–90° from the forward direction, preferably 30–80°, more preferably 35–60°.

To simplify the structure of the inspection device, all of the cameras suitably are fixed on a transverse camera bracket, and the camera bracket is mounted on a printed circuit board fixed in the rotatable front part of the housing.

For rotating the front part of the housing in relation to the fixed rear part of the housing, it is suitable to mount an electric motor on the printed circuit board, and to provide a gear train that is driven by the motor to rotate the front part of the housing.

It is preferred that two of the rotatable cameras are located diametrically opposite each other in relation to the longitudinal axis. Thereby, these two cameras cover a large portion of the circumferential area of the adjacent inner wall of the pipe, and any rotation to necessary for covering any possibly remaining uncovered circumferential area will be comparatively small and quickly done.

When the rotatable cameras include a third camera, it suitably is located halfway between the two diametrically opposite rotatable cameras.

Preferably, the rotatable cameras are located on an imaginary circumferential circle in relation to the longitudinal axis, and on each side of each rotatable camera along the circumferential circle, an LED illumination assembly is provided for illuminating the

inner surface of the pipe obliquely forward. Thereby the LED illumination assemblies give sufficient light both for the camera having a forward-looking field of view and for the at least three cameras that have their fields of view directed obliquely forward.

5 The motor suitably is placed in a position that is diametrically opposite to that of a common center of gravity of the rotatable cameras in relation to the longitudinal axis. Thereby, gravitational forces will try to counteract any undesired rotation of the inspection device.

10 Further, it is suitable that the inspection device is adapted to be controlled from a control unit, and the device includes a microprocessor, preferably mounted on the printed circuit board, adapted to be controlled from the control unit for selecting and operating a desired one of the cameras, and for operating the LED illumination assemblies and the motor.

15 Still further, it is preferred that the inspection device includes a tilt sensor, preferably mounted on the printed circuit board, for sensing the attitude of the rotatable front part of the housing and, in case of detecting a deviation from a desired attitude, sending a signal to the processor to correct the deviation.

20 Further, each of the cameras suitably has an angular field of view in the range of 45–135°, preferably 60–120°, more preferably 80–100°, the rotatable cameras preferably are at least three, and the rotatable cameras preferably are set in the range of 60–120° apart from the closest located rotatable camera, preferably 80–90°. Thereby, the rotation
25 angle required for inspecting 360° is much smaller than when a single camera is used. Thus, using the at least three cameras instead of just one is time-saving.

Further, the rotatable cameras are preferably mounted within a semicircle of the cross-section of the device. Preferably one camera at respectively end of the semicircle and
30 any additional cameras equidistantly distributed within the semicircle. Preferably the opposite semicircle not containing cameras is arranged to face the bottom of a pipe when pushing or pulling the device in a pipe. Thereby the wear of the protective glass covering the camera lenses can be reduced. When the device has reached a point where it is desirable to look downward the cameras can be rotated.

35

BRIEF DESCRIPTION OF THE DRAWINGS

In the following, the invention will be described in more detail with reference to preferred embodiments and the appended drawings.

- 5 Fig. 1 is a perspective view of a pipe inspection device in accordance with a preferred embodiment of the present invention.

Fig. 2 is a side view of a front end of the device of Fig. 1.

- 10 Fig. 3 is a front view of the device of Figs. 1 and 2.

Fig. 4 is a longitudinal cross sectional view of the forward end of the device of Figs. 1–3.

- 15 Fig. 5 is a perspective view of some interior components of the inspection device of Figs. 1–4 and shows *inter alia* two cameras and four LED illumination assemblies attached to a printed circuit board, and the rear part of the housing partly surrounded by a pressure seal bushing.

- 20 Fig. 6 is a perspective view of some interior components of the inspection device of Figs. 1–4 and shows *inter alia* a camera mounted on a camera bracket, a printed circuit board, a motor, and a gear train.

- Fig. 7 is a perspective view of the internal components of Fig. 5 but viewed from an
25 opposite direction.

MODE(S) FOR CARRYING OUT THE INVENTION

- The pipe inspection device shown in the drawings includes a generally cylindrical housing **1** fixed to a semi-rigid rod **2** in the shape of a helical spring forming a
30 protective tube for a multi-wire cable for supply of electrical power to the device from a supply outside the pipe and at the same time image signals from a camera to a monitor outside the pipe. The housing **1** has a longitudinal axis **3** and inside the housing a camera **4** having a forward-looking field of view and a camera **5** that is rotatable around said longitudinal axis and has a field of view directed to permit closer inspection of an
35 inner surface of the pipe. Further, means that will be described below are provided for rotating the rotatable camera **5** to direct its field of view against an area of the inner surface of the pipe to be inspected more closely.

According to the present invention, in addition to the camera **4** having a forward-looking field, the inspection device has at least two cameras **5–7** that are rotatable as an assembly around said longitudinal axis **3** and have a field of view directed to permit
5 closer inspection of an inner surface of the pipe. The at least two rotatable cameras **5–7** have their fields of view directed obliquely forward or perpendicularly to the longitudinal axis **3**. In the preferred embodiment shown in the drawings, they have their fields of view directed obliquely forward, suitably in the range of 20–90° from the forward direction, preferably 30–80°, more preferably 35–60°. Thereby, the diameter of
10 the housing **1** may be reduced and windows for the cameras are less exposed to mechanical damage and accumulation of dirt. This also makes it possible to make the exterior of the housing **1** at the rear of the cameras even and streamlined, so that the risk of the inspection device getting stuck in the pipe will be reduced.

15 Preferably, three cameras **5**, **6**, and **7** are used, but if desired it is, of course, also possible to use four or more cameras. Two cameras may also be used. Further, the housing **1** has a fixed rear part **10** and a front part **11** that is carried by the rear part **10** and rotatable around said longitudinal axis **3**, all of the cameras **4–7** being fixed in the rotatable front part **11** of the housing **1**. By rotating the front part **11**, the field of view of
20 at least one of the cameras **6** and **7** can be directed toward the area to be inspected.

To avoid that liquid leaks into the housing **1**, a pressure seal bushing **8** with O-rings is interposed between the rotary front part **11** and the fixed rear part **10** as shown in Figs. 4 and 5. The pressure seal bushing **8** is fixed by screws in the rotary front part **11** and has
25 radial dowels (not shown) that project into a circumferential groove **9** in the fixed rear part **10** to lock the parts **10** and **11** to each other while permitting rotation.

As described above, said at least two rotatable cameras **6**, and **7** preferably have their fields of view directed obliquely forward, and the front part **11** of the housing **1** has a
30 generally half-spherical nose with windows **4'–7'** for the cameras **4–7**. In the shown preferred embodiment, two (**6**, and **7**) of the rotatable cameras are located diametrically opposite each other in relation to the longitudinal axis **3**. The possible third one **5** of the rotatable cameras, also having its field of view directed obliquely forward, is located halfway between them. Thereby, the fields of view of these three cameras **5–7** cover a
35 large portion of the circumferential area of the adjacent inner wall of the pipe, and any rotation to necessary for covering any possibly remaining uncovered circumferential area of the inner wall of the pipe will be small and quickly done. To protect the cameras

4–7, each window 4'–7' is covered by a sapphire glass (not shown) pressed against an O-ring (not shown) by a nut ring.

The rotatable cameras 5, 6, and 7 are located on an imaginary circumferential circle in relation to the longitudinal axis 3, and on each side of each rotatable camera 5, 6, and 7 generally along the circumferential circle, an LED illumination assembly 12–15 is provided for illuminating the inner surface of the pipe obliquely forward. Thereby the LED illumination assemblies 12–15 give sufficient light both for the camera 4 having a forward-looking field of view and for the at least three cameras 5–7 that have their fields of view directed obliquely forward. The generally half-spherical nose of the front part 11 of the housing 1 has window openings 12'–15' for the LED illumination assemblies 12–15.

In the preferred embodiment shown in the drawings, each of the cameras 4–7 has an angular field of view of 90°, the at least three rotatable cameras 5–7 are set 90° apart, and the rotary front part 11 of the housing 1 is rotatable $\pm 90^\circ$ in relation to the fixed rear part 10. Thus, without requiring any time-consuming rotation, they cover together an angle of 270°, and the rotary front part 11 of the housing 1 with the cameras can easily and quickly be rotated to cover the remaining 90° if necessary. Thereby, the rotation angle required is much smaller than when a single camera is used. Thus, using the at least three cameras 5–7 instead of just one is time-saving. In addition, when the inspection device is being moved through a pipe, and a wall area to be inspected more closely leaves the field of view of the front camera due to the forward motion of the inspection device, the wall area in question most likely will be visible in one of the at least three cameras 5–7, which together and without requiring any rotation cover an angle of 270°.

All of the cameras 4–7 are fixed on a transverse camera bracket 16, which is mounted on a printed circuit board 17 fixed in the rotatable front part 11 of the housing 1. The camera bracket 16 is best shown in Fig. 6, where, in order not to overcrowd the figure, only the camera 4 having a forward-looking field of view is shown mounted on the bracket 16. Fig. 6 also shows most of the means for rotating the front part 11 of the housing 1. These means comprise an electric motor 18 mounted in a holder 19 that is fixed to the printed circuit board 17. The motor 18 suitably is placed in a position that is diametrically opposite that of a common center of gravity of the rotatable cameras 5–7 in relation to the longitudinal axis 3, *i.e.* usually diametrically opposite the position of

the intermediate one **5** of the rotatable cameras **5–7**. Thereby, gravitational forces will try to counteract any undesired rotation of the inspection device.

A gear train is driven by the motor **18** for rotating the front part **11** of the housing **1** in relation to the fixed rear part **10** of the housing **1**. The gear train is best shown in Fig. 7 and comprises a first gear **20** fixed on the outgoing shaft of the motor **18**, a second gear **21** mounted on a support shaft **22** carried parallel to the motor **18** by the motor holder **19**, a third gear **23** coaxial and integral with the second gear **21**, and an internal fourth gear **24**. Thus, the motor **18** rotates the first gear **20** that drives the second gear **21**, which is larger than the first gear **20**. Thereby, the integral third gear **23**, which is smaller than the second gear **21**, is rotated, and as it is in meshing engagement with the internal fourth gear **24**, which is fixed in the rear part **10** of the housing **1**, the front part **11** of the housing **1** with the cameras **4–7** and the LED illumination assemblies **12–15** will be rotated in relation to the fixed rear part **10** of the housing **1**. As an example, the first gear **20** may have 20 teeth, the second gear **21** 30 teeth, the third gear **23** 12 teeth, and the internal fourth gear **24** 50 teeth to give a desired reduction of the motor rpm.

Suitably, as is well known in the art, the pipe inspection device is adapted to be controlled from a control unit (not shown), and the printed circuit board **17** includes a microprocessor (likewise not shown), which is adapted to be controlled via a multi-wire cable (not shown) from the control unit for selecting and operating a desired one of the cameras **4–7**, and for operating the LED illumination assemblies **12–15** and the motor **18**. In the shown preferred embodiment, the cable includes six parallel wires forming three pairs. One pair carries the image from the selected operative camera, another carries data communication to the microprocessor, and a third pair carries supply current. Conventional slip rings (not shown) are provided where necessary to permit the signals to pass through a rotary joint. The control unit is also connected to a monitor (not shown) for displaying the images from the cameras.

Further, each of the cameras **4–7** suitably has an angular field of view in the range of 45–135°, preferably 60–120°, more preferably 80–100°, the rotatable cameras **5–7** preferably are at least three, and the rotatable cameras **5–7** preferably are set in the range of 60–120° apart from the closest located rotatable camera, preferably 80–90°. Thereby, the rotation angle required for inspecting 360° is much smaller than when a single camera is used. Thus, using the at least three cameras **5–7** instead of just one is time-saving.

The control unit may as an example include the following functions:

- Selection of camera
- Rotation of the front part of the housing (overriding the tilt sensor) to view bottom areas of the pipe wall
- 5 • Auto mode (tilt sensor controlling the attitude of the cameras)
- Adjustment of light intensity of the LED illumination assemblies

The present invention is not restricted to the preferred embodiment described and shown in the drawing but may be modified with the scope of the appended claims. As
10 an example, it is possible to use more than three rotatable cameras **5–7** having their fields of view directed for close inspection of the inner wall of the tube, and each of them may have an angular field of view of other than 90°. Further, it would be possible to mount the at least three cameras **5–7** having their fields of view directed strictly sideways, *i.e.* perpendicularly to the longitudinal axis **3**. However, obliquely forward
15 directed fields of view are preferred in view of the advantages gained thereby as described above. It would also be possible to use another transmission than the described gear train to rotate the front part **11** with the cameras **4–7** in relation to the fixed rear part **10** of the housing **1**.

20 INDUSTRIAL APPLICABILITY

The pipe inspection device of the present invention is applicable for inspecting sewer, water and well pipes for blockages and defects. Electrical conduits and other long narrow passages may be similarly inspected.

CLAIMS:

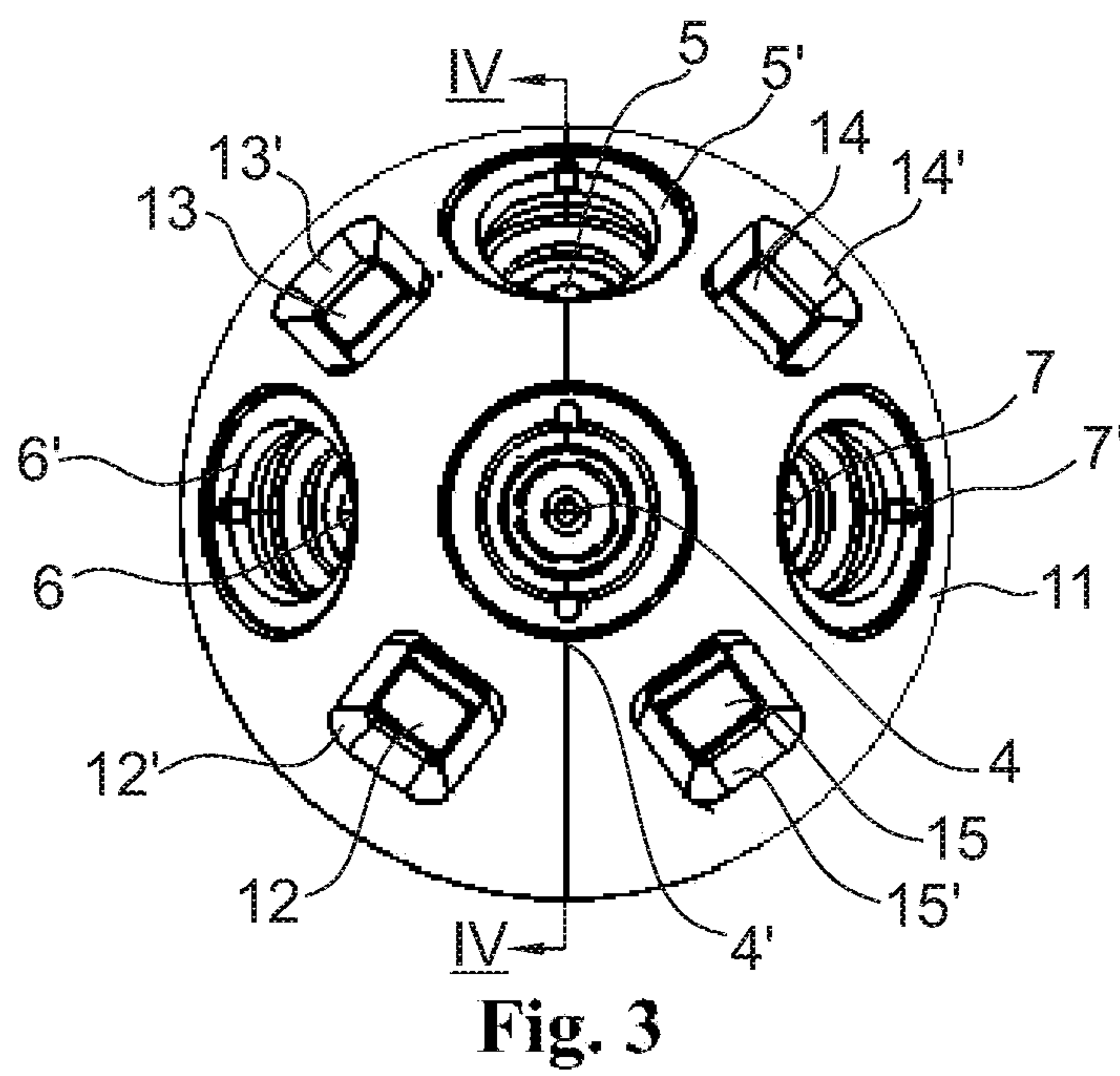
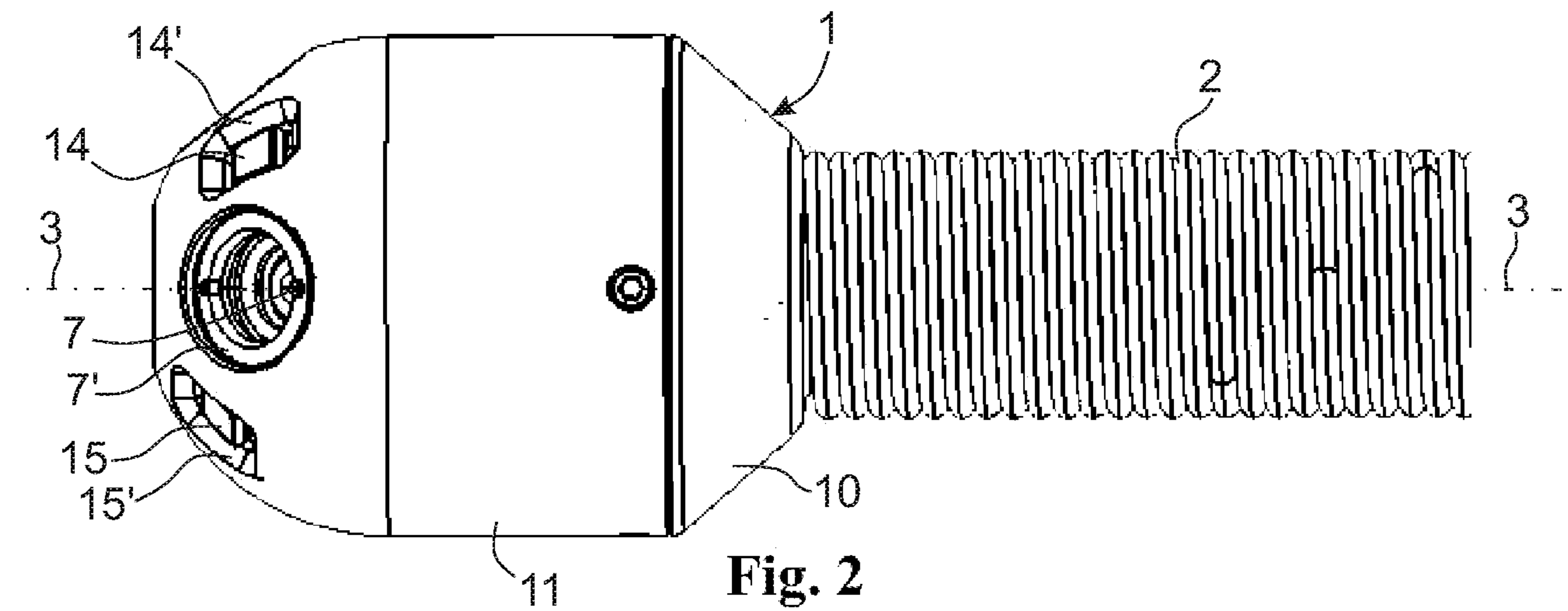
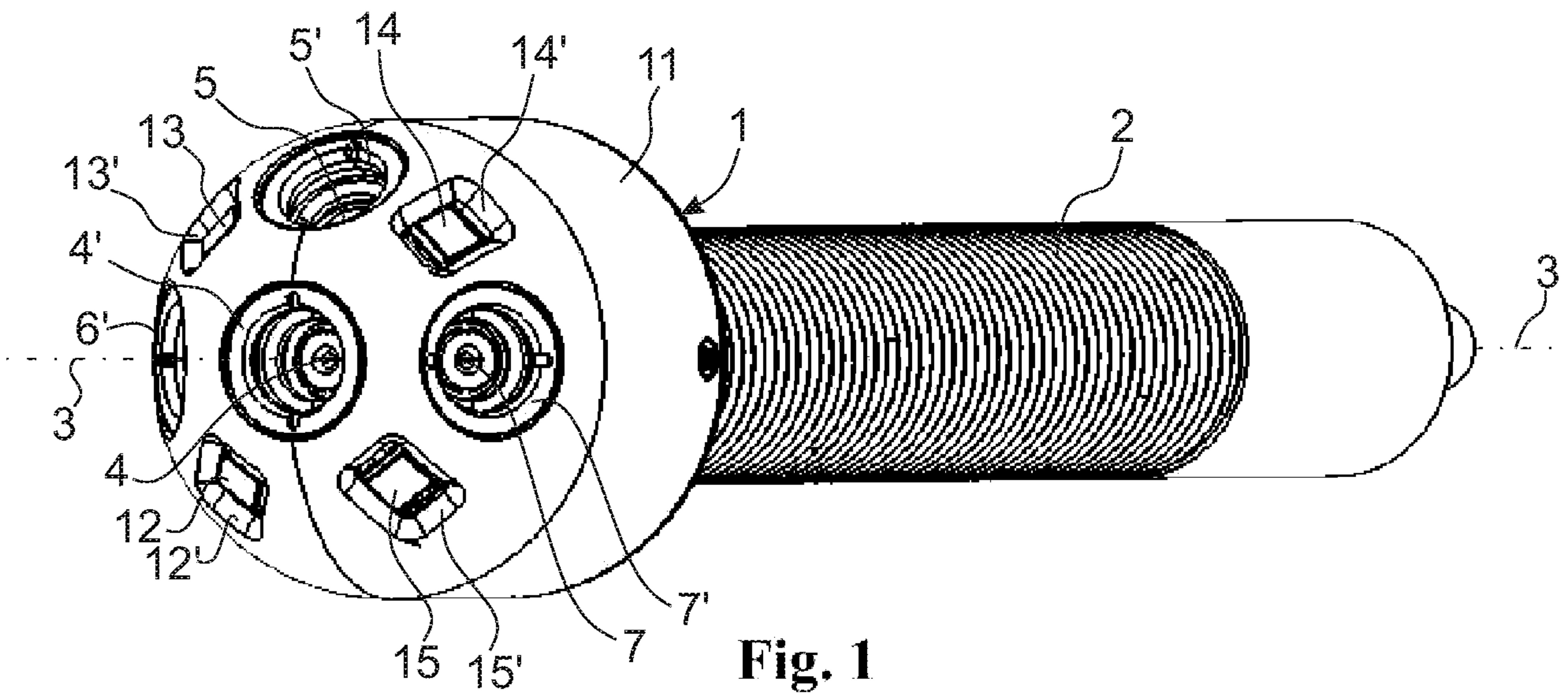
1. A pipe inspection device including a housing fixed to a semi-rigid rod and having a longitudinal axis and inside the housing a camera having a forward-looking field of view and at least two cameras that are rotatable as an assembly around said longitudinal axis and have a field of view directed to permit closer inspection of an inner surface of the pipe, and means for rotating the rotatable camera to direct its field of view against an area of the inner surface of the pipe to be inspected more closely, wherein
the housing has a fixed rear part and a front part that is carried by the rear part and is rotatable in relation to said rear part around said longitudinal axis, all of the cameras being fixed in the rotatable front part of the housing.
2. The device as claimed in claim 1, wherein said at least two rotatable cameras have their fields of view directed obliquely forward or perpendicularly to the longitudinal axis.
3. The device as claimed in claim 2, wherein said at least two rotatable cameras have their fields of view directed to be in the range of 20-90° from the forward direction.
4. The device as claimed in claim 2, wherein said at least two rotatable cameras have their fields of view directed to be in the range of 30-80° from the forward direction.
5. The device as claimed in claim 2, wherein said at least two rotatable cameras have their fields of view directed to be in the range of 35-60° from the forward direction.
6. The device as claimed in any one of claims 1-3, wherein all of the cameras are fixed on a transverse camera bracket.
7. The device as claimed in claim 6, wherein the camera bracket is mounted on a printed circuit board fixed in the rotatable front part of the housing.

8. The device as claimed in claim 7, wherein an electric motor is mounted on the printed circuit board, and a gear train is driven by the electric motor for rotating the front part of the housing in relation to the fixed rear part of the housing.
9. The device as claimed in any one of claims 1-3, wherein two of the rotatable cameras are located diametrically opposite each other in relation to the longitudinal axis.
10. The device as claimed in claim 9, wherein a third one of the rotatable cameras is located halfway between the diametrically opposite rotatable cameras.
11. The device as claimed in claim 8, wherein the rotatable cameras are located on an imaginary circumferential circle in relation to the longitudinal axis, and on each side of each rotatable camera along the circumferential circle, an LED illumination assembly is provided for illuminating the inner surface of the pipe obliquely forward.
12. The device as claimed in claim 8, wherein the electric motor is placed in a position that is diametrically opposite to that of a common center of gravity of the rotatable cameras in relation to the longitudinal axis.
13. The device as claimed in claim 11, wherein the device is adapted to be controlled from a control unit, and wherein the device includes a microprocessor adapted to be controlled from the control unit for selecting and operating a desired one of the cameras, and for operating the LED illumination assemblies and the motor.
14. The device as claimed in claim 13, further including a tilt sensor for sensing the attitude of the rotatable front part of the housing and in case of detecting a deviation from a desired attitude, sending a signal to the microprocessor to correct the deviation.
15. The device as claimed in any one of claims 1-3, wherein each of the cameras has an angular field of view in the range of 45-135°.

16. The device as claimed in any one of claims 1-3, wherein each of the cameras has an angular field of view in the range of 60-120°.
17. The device as claimed in any one of claims 1-3, wherein each of the cameras has an angular field of view in the range of 80-100°.
18. The device as claimed in any one of claims 1-3, wherein the rotatable cameras are at least three.
19. The device as claimed in claim 18, wherein the rotatable cameras are set in the range of 60-120° apart from the closest located rotatable camera.
20. A device as claimed in claim 18, wherein the rotatable cameras are set in the range of 80-90° apart from the closest located rotatable camera.
21. The device as claimed in any one of claims 1-3, wherein the rotary front part of the housing is rotatable at least $\pm 45^\circ$ in relation to the fixed rear part.
22. The device as claimed in any one of claims 1-3, wherein the rotary front part of the housing is rotatable at least $\pm 90^\circ$ in relation to the fixed rear part.
23. The device as claimed in any one of claims 1-3, wherein the rotatable cameras are set so that there is at least a 120° section void of rotatable cameras.
24. The device as claimed in any one of claims 1-3, wherein the rotatable cameras are set so that there is at least a 150° section void of rotatable cameras.
25. The device as claimed in any one of claims 1-3, wherein the rotatable cameras are set so that there is at least a 180° section void of rotatable cameras.

26. The device as claimed in any one of claims 1-3, wherein the rotatable cameras are mounted within a semicircle of the cross-section of the device.

1/3



2/3

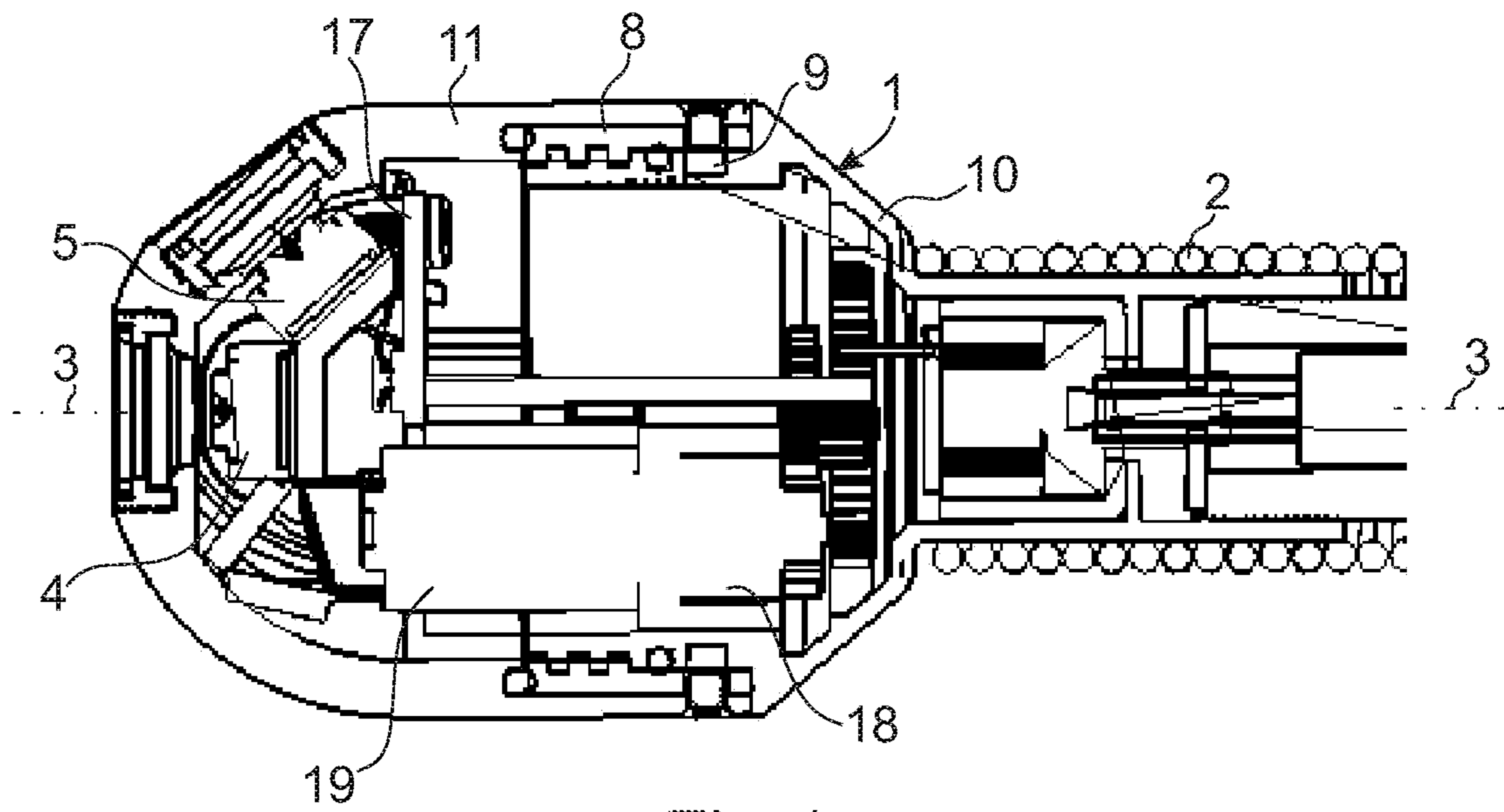


Fig. 4

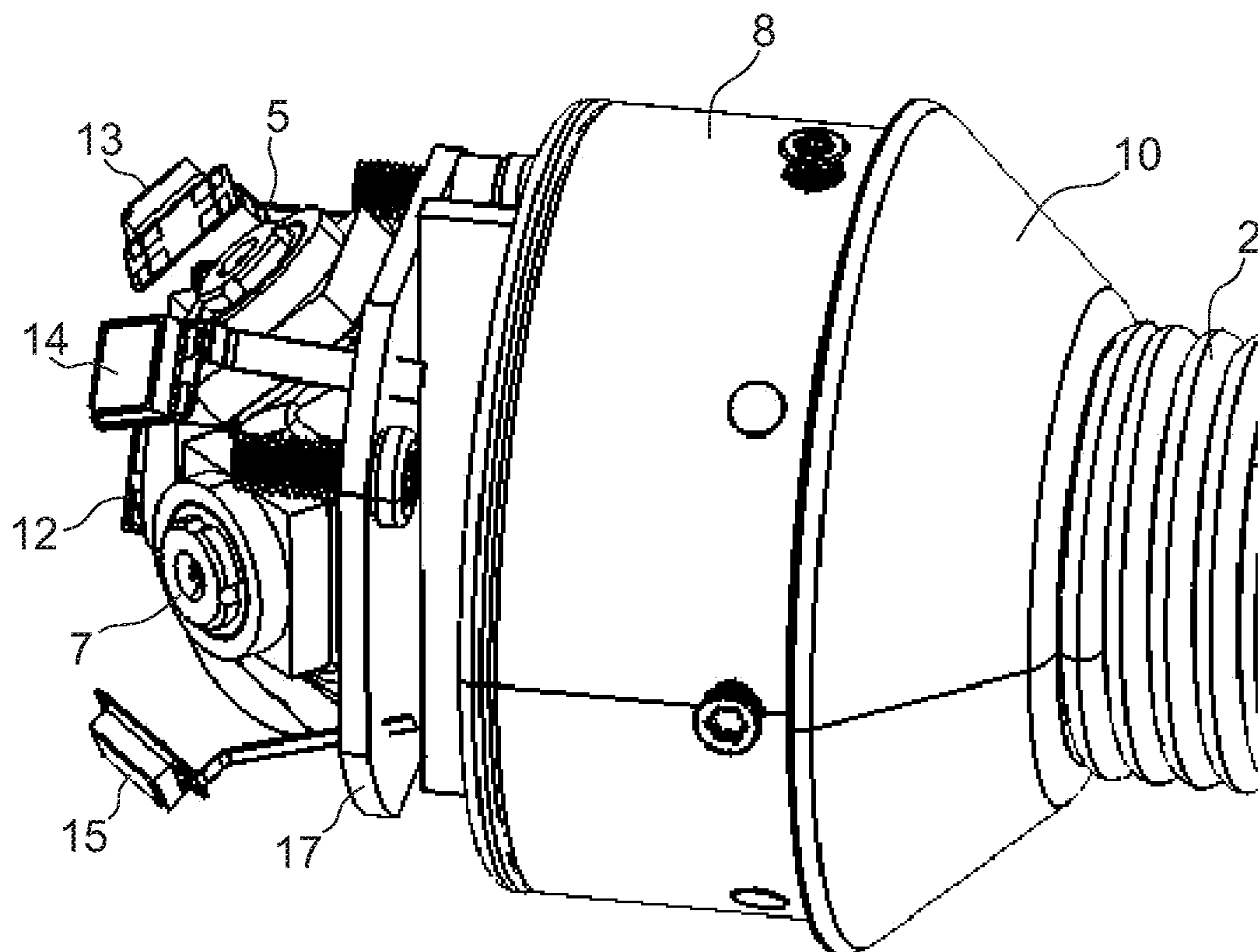


Fig. 5

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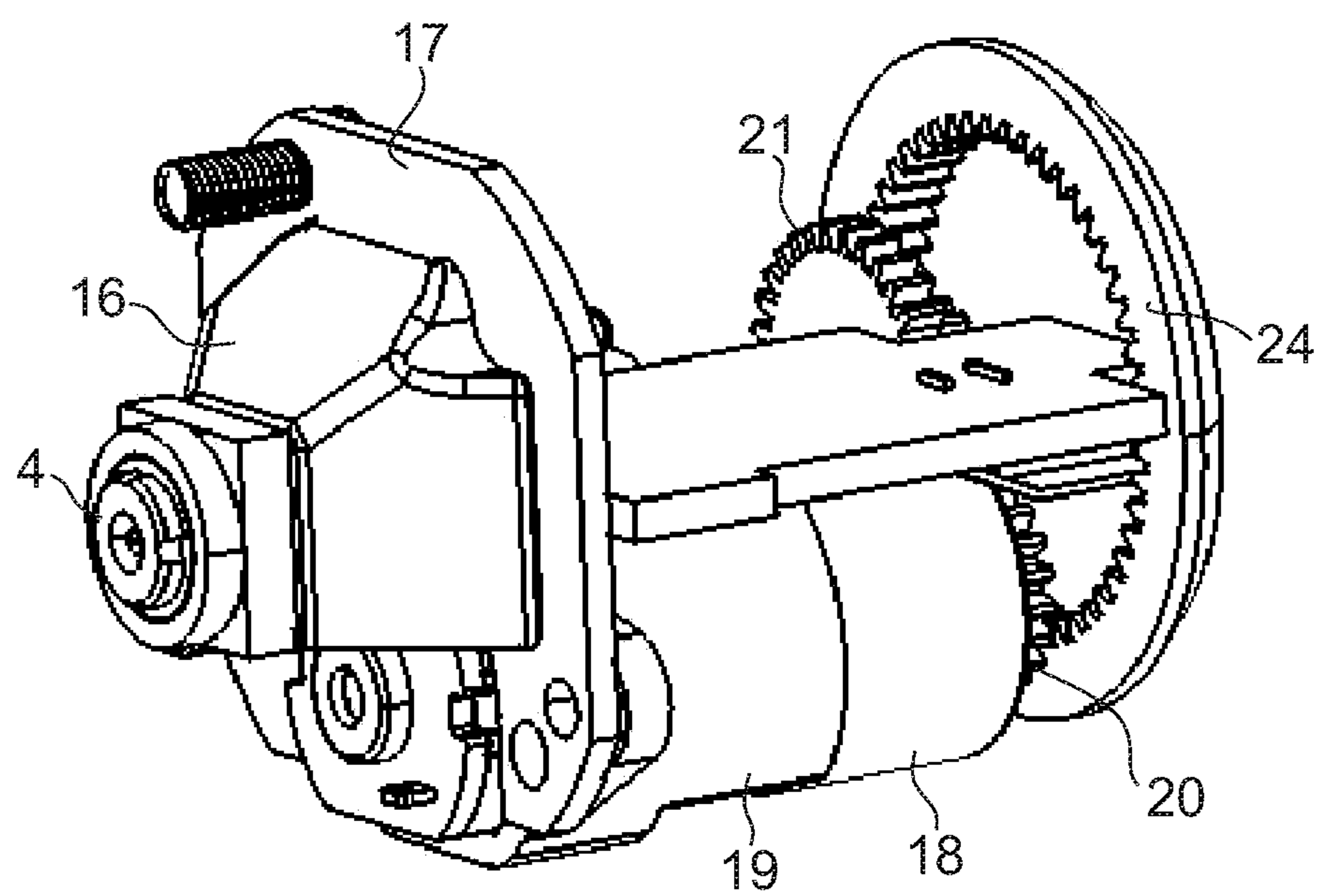


Fig. 6

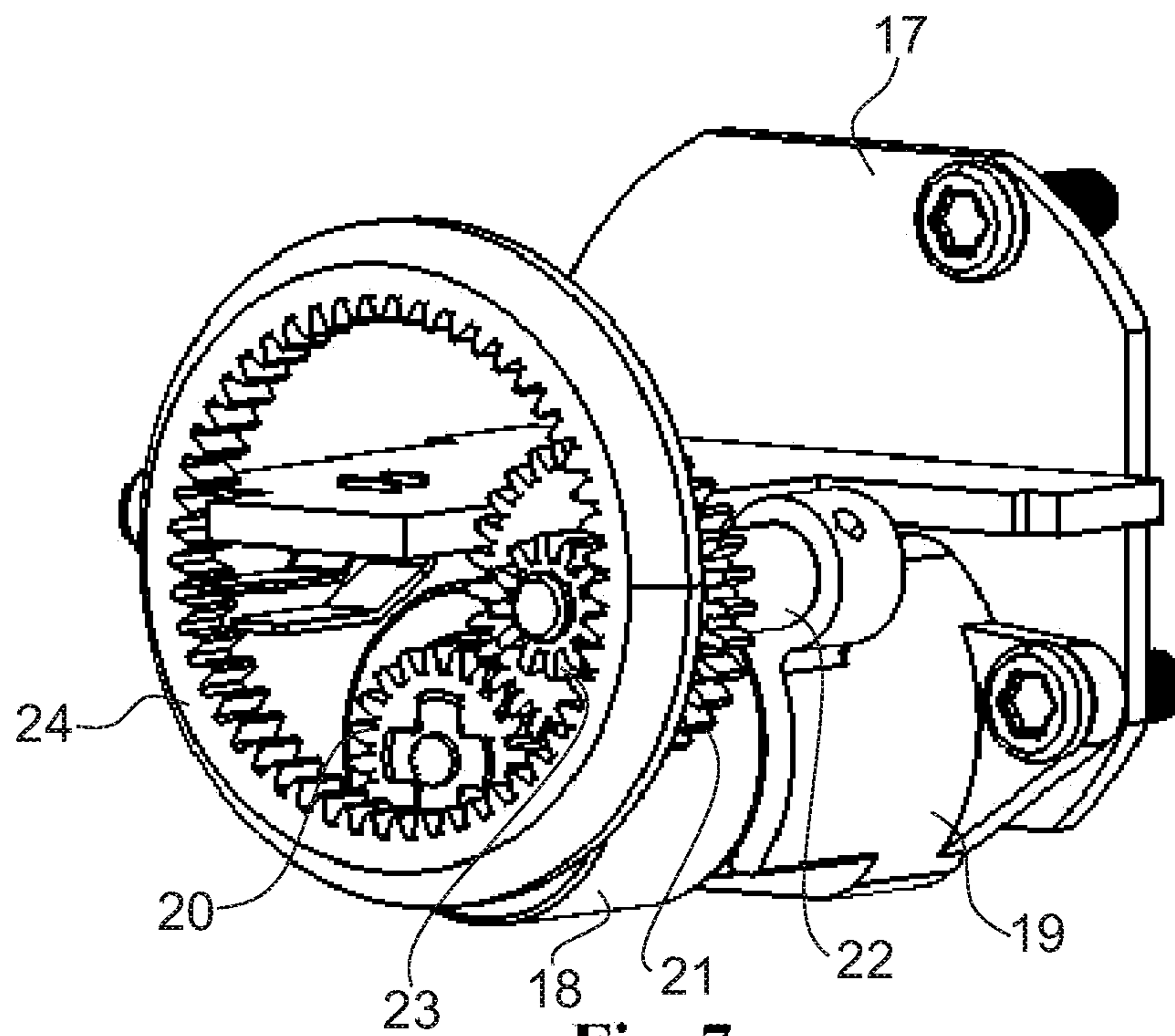


Fig. 7

