We claim:

1. A remote actuator for a medical device, the remote actuator comprising:

a bellows comprising a lumen and a port that is pneumatically coupled to the lumen, wherein the bellows is configured such that walls of the bellows form a channel, which is pneumatically sealed from the lumen; and

an actuating tube pneumatically coupled to the port at a first end and configured to pneumatically couple at a second end to a pneumatic switch controlling the medical device, such that application of pressure to the bellows generates sufficient air pressure to actuate the. pneumatic switch.

2. A system, comprising:

the remote actuator of claim 1; and

a medical device that comprises a pneumatic switch, a medical tube and a treatment member.

3. A remote actuator for a medical device that comprises a pneumatic switch, a medical tube and a treatment member, the remote actuator comprising:

a bellows comprising a pneumatic port and first and second fluid ports and an internal conduit comprising a first lumen that is fluidly coupled to the medical tube and treatment member and a second lumen therebetween, wherein the fluid ports and internal conduit are configured to allow fluid coupling of the medical tube and the treatment member; and

an actuating tube pneumatically coupled to the pneumatic port of the bellows and configured to allow pneumatic coupling to the pneumatic switch , such that application of pressure to the bellows generates sufficient air pressure to actuate the pneumatic switch, wherein the second lumen comprises the pneumatic port within the bellows, and is pneumatically coupled to the actuating tube.

4. A remote actuator for a surgical laser that comprises a pneumatic switch, a medical tube having an optical fiber laser therein, and a laser treatment cannula, the remote actuator comprising:

a bellows comprising a pneumatic port and first and second laser ports and an internal conduit comprising a first lumen and a second lumen, wherein the first lumen is coupled to the medical tube and the treatment cannula, and wherein the

laser ports and internal conduit are configured to allow the optical fiber laser to traverse the bellows and emerge from the laser treatment cannula; and

an actuating tube pneumatically coupled to the pneumatic port of the bellows and configured to allow pneumatic coupling to the pneumatic switch on the surgical laser, such that application of pressure to the bellows generates sufficient air pressure to actuate the pneumatic switch, wherein the second lumen comprises the pneumatic port within the bellows, and is pneumatically coupled to the actuating tube.

5. The remote actuator of Claims 1, 2, 3 or 4, wherein at least the bellows of the remote actuator is sterile.

6. The remote actuator of Claims 1 to 5, wherein the remote actuator is configured for a single use.

7. The remote actuator of Claims 1 to 6, wherein the actuating tube further comprising an optical fiber coupled to a light source, such that the bellows can be illuminated based on the status of the pneumatic switch.

8. The remote actuator of Claims 1 to 7, further comprising a saleable package comprising an outer wrapper defining a sealed and sterile interior, wherein the remote actuator is located within said sealed and sterile interior.

9. The remote actuator of Claim 2, wherein the treatment member comprises an infiltration, infusion or suction cannula.

10. A multiple remote actuator for control of at least two surgical devices, each surgical device comprising a pneumatic switch and a medical tube, the multiple remote actuator comprising:

at least a first bellows comprising a pneumatic port and a second bellows comprising a pneumatic port, wherein the first and second bellows are coupled together in series, and wherein the coupled bellows further comprise at least first and second fluid ports and an internal conduit therebetween, wherein the internal conduit comprises a first lumen pneumatically coupled to the pneumatic port of the first bellows, a second lumen pneumatically coupled to the pneumatic port of

the second bellows, and at least a third lumen fluidly coupled to the fluid ports; and

a first actuating tube pneumatically coupled to the pneumatic port of the first bellows, wherein the first actuating tube is configured to allow pneumatic coupling to the pneumatic switch of the first surgical device, such that application of pressure to the first bellows generates sufficient air pressure to actuate the pneumatic switch of the first surgical device; and

a second actuating tube pneumatically coupled to the pneumatic port of the second bellows, wherein the second actuating tube is configured to allow pneumatic coupling to the pneumatic switch of the second surgical device, such that application of pressure to the second bellows generates sufficient air pressure to actuate the pneumatic switch of the second surgical device.

11. The multiple remote actuator of Claim 10, wherein the at least two surgical devices comprise a fluid pumping device and a fluid suctioning device.

12. The multiple remote actuator of Claim 10 or 11, further comprising a saleable package comprising an outer wrapper defining a sealed and sterile interior, wherein the multiple remote actuator is located within said sealed and sterile interior.