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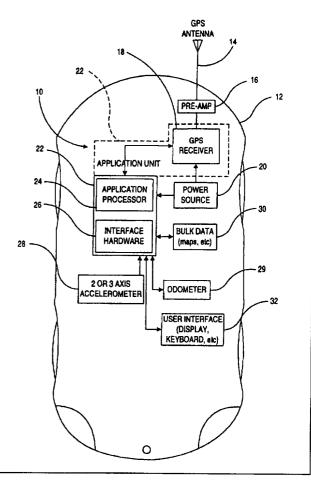
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(54) Title: IMPROVED VEHICLE NAVIGATION SYSTEM AND METHOD

#### (57) Abstract

The improved vehicle navigation system and method uses information from a Global Positioning System (GPS) to obtain velocity vectors, which include speed and heading components, for "dead reckoning" the vehicle position from a previous position. If information from the GPS is not available, then the improved vehicle navigation system uses information from an orthogonal axes accelerometer, such as two or three orthogonally positioned accelerometers, to propagate vehicle position. Because the GPS information should almost always be available, the improved vehicle navigation system relies less on its accelerometers. thereby allowing the use of less expensive accelerometers. The improved vehicle navigation system retains the accuracy of the accelerometers by repeatedly calibrating them with the velocity data obtained from the GPS information. The improved vehicle navigation system calibrates the sensors whenever GPS data is available (for example, once a second at relatively high speeds). Furthermore, the improved vehicle navigation system does not need to rely on map matching to calibrate sensors. System flexibility is improved because map matching is oblivious to the hardware, and the system hardware can be updated without affecting map matching or a change in the map database.



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Name and	mailing address of the ISA  European Patent Office, P.B. 5818 Patentiaan 2	Authorized officer		
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Inten. nal Application No PCT/US 96/20849

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	tion) DOCUMENTS CONSIDERED TO BE RELEVANT	Relevant to claim No.
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Υ	see figure 8	1-8
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Y	17 February 1993 see abstract; claim 4 see column 5, line 56 - column 6, line 31 see column 5, line 11 - line 20 see column 3, line 27 - line 55	13,28,29
Α	See column 5, Time 27 with 35	1,5,23, 24
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PCT/US 96/20849

Box I	Observations where certain claims were found unsearchable (Continuation of item 1 of first sheet)
This Inte	rnational Search Report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:
1.	Claims Nos.: because they relate to subject matter not required to be searched by this Authority, namely:
	Claims Nos.: because they relate to parts of the International Application that do not comply with the prescribed requirements to such an extent that no meaningful International Search can be carried out, specifically:
	Claims Nos.: because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a).
Box II (	Observations where unity of invention is lacking (Continuation of item 2 of first sheet)
This Inter	national Searching Authority found multiple inventions in this international application, as follows:
see	extra sheet
1. X A	s all required additional search fees were timely paid by the applicant, this International Search Report covers all archable claims.
2. A of	s all searchable claims could be searched without effort justifying an additional fee, this Authority did not invite payment any additional fee.
3. As	s only some of the required additional search fees were timely paid by the applicant, this International Search Report vers only those claims for which fees were paid, specifically claims Nos.:
4. No	o required additional search fees were timely paid by the applicant. Consequently, this International Search Report is tricted to the invention first mentioned in the claims; it is covered by claims Nos.:
Remark on i	The additional search fees were accompanied by the applicant's protest.  No protest accompanied the payment of additional search fees.

		International Application No. PCT/US 96/ 20849
Fl	URTHER INFORMATION CONTINUED FROM	РСТ//SA/210
	1. claims 1-8,13,14,20-24,28,29,3 improved navigation system using for improved accuracy	,32-37: g GPS velocity data & dead-reckoning system
	2. claims 9-12,15-19: accelerometer used to propagate a	a previous position to a current position
	3. claims 25-27,30,31: zero offset detection of motion of	detection sensor
	.a	

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