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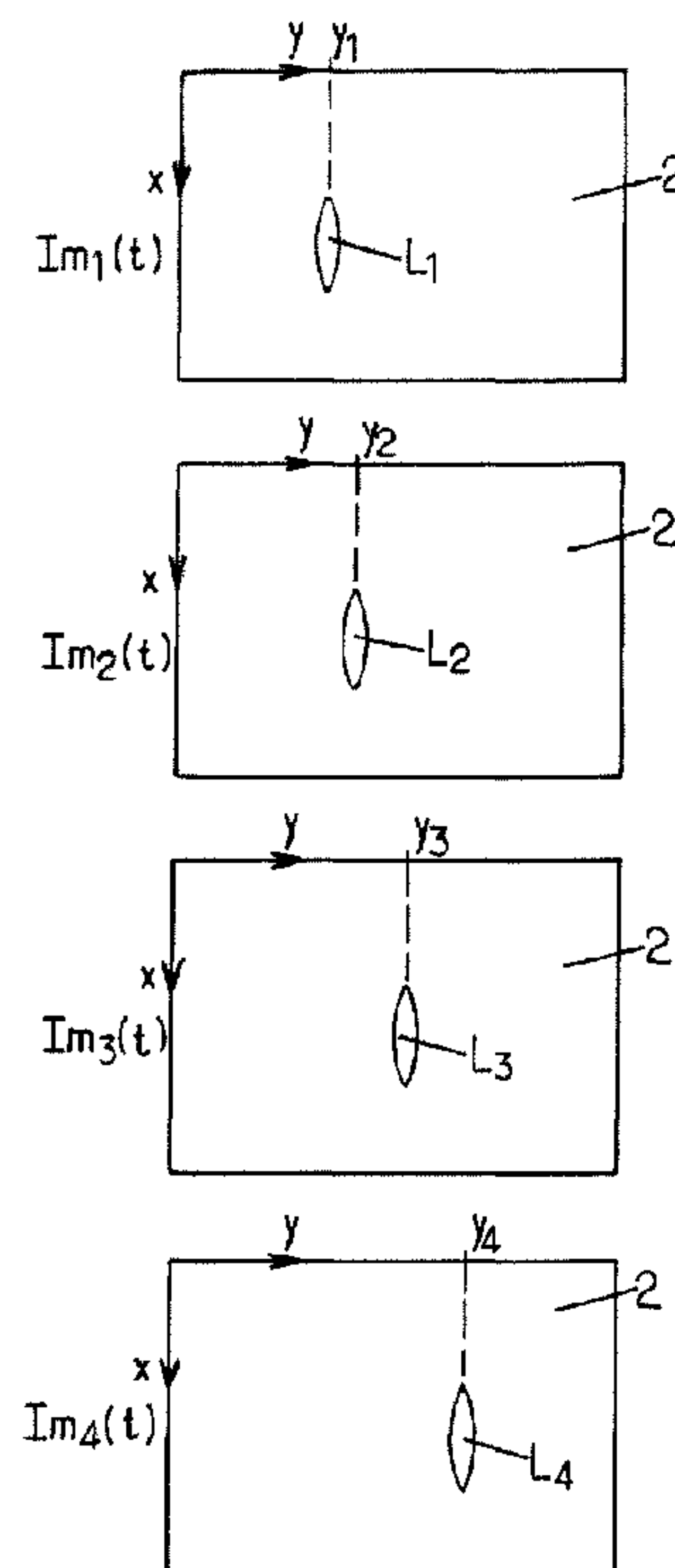
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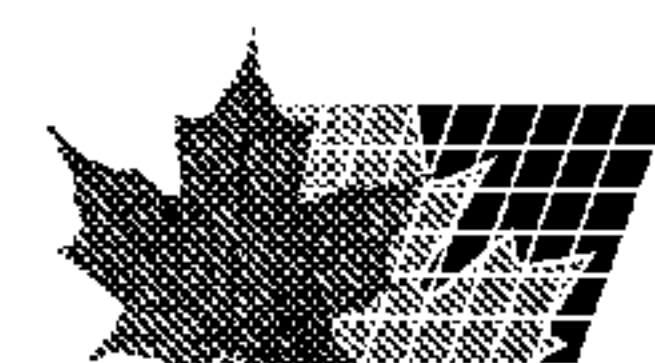
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(57) Abrégé/Abstract:

An imaging method using shear waves for observing a viscoelastic medium (2), comprising: several successive excitation steps j during which elastic shear waves are generated respectively at different excitation loci (L_j) in the viscoelastic medium (2) by an imaging device, the different excitation loci being separated from one another by a maximum distance D_m , - an imaging step corresponding to each excitation step j , in which a set j of successive raw images $Im_j(t_k)$ of the viscoelastic medium at times t_k are determined during propagation of the shear wave, the raw images having a resolution R which is larger than the maximum distance D_m , an averaging step in which raw images $Im_j(t_k)$ corresponding to the same relative time t_k are averaged to determine an average image $Im'(t_k)$.



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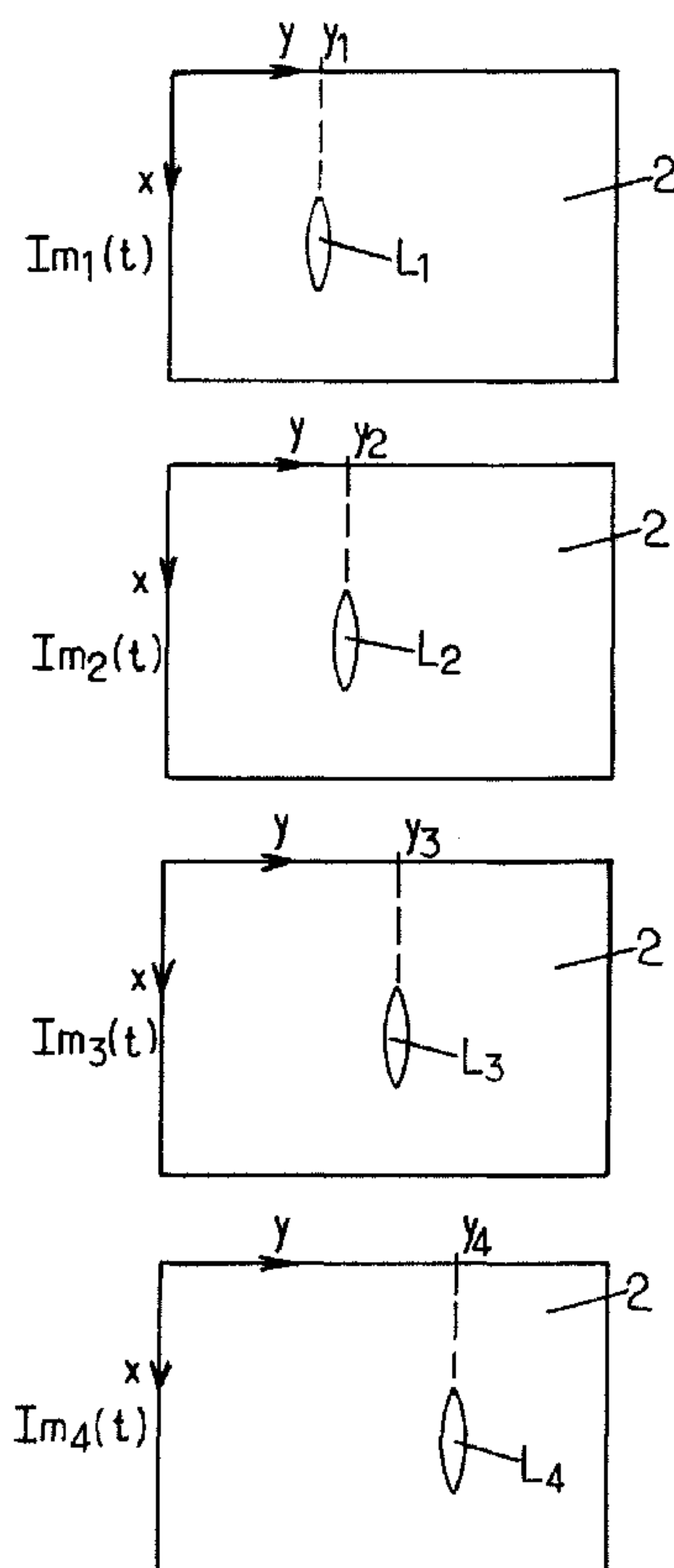


FIG.2.

(57) Abstract: An imaging method using shear waves for observing a viscoelastic medium (2), comprising: several successive excitation steps j during which elastic shear waves are generated respectively at different excitation loci (L_j) in the viscoelastic medium (2) by an imaging device, the different excitation loci being separated from one another by a maximum distance D_m , - an imaging step corresponding to each excitation step j , in which a set j of successive raw images $Im_j(t_k)$ of the viscoelastic medium at times t_k are determined during propagation of the shear wave, the raw images having a resolution R which is larger than the maximum distance D_m , an averaging step in which raw images $Im_j(t_k)$ corresponding to the same relative time t_k are averaged to determine an average image $Im'(t_k)$.

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IMAGING METHOD AND APPARATUS USING SHEAR WAVES

FIELD OF THE INVENTION

The present invention relates to imaging methods and apparatuses using shear waves.

5

BACKGROUND OF THE INVENTION

More particularly, the invention relates to an imaging method using shear waves for observing a viscoelastic medium, comprising:

10 - an excitation steps j during which elastic shear waves are generated at an excitation locus in the viscoelastic medium by an imaging device,

15 - an imaging step in which a set of successive images of the viscoelastic medium are determined by said imaging device during propagation of the shear wave in said viscoelastic medium.

Document US-B2-7 252 004 describes an example of such a method, in which the successive images, constituting a motion picture of the propagation of the shear wave, are used to map the viscoelastic medium, by
20 calculating at least one propagation parameter of the shear wave at one or several points in the viscoelastic medium.

Although this known method gives particularly good results, e.g. for spotting cancerous zones or the like,
25 such method may produce images having a relatively low signal-to-noise ratio in certain circumstances, for instance in biological mediums having very complex structures producing high attenuation and diffraction (e.g. animal muscle when the shear waves are propagated
30 transversely to muscle fibers).

OBJECTS OF THE INVENTION

A particular object of the present invention is to mitigate this drawback.

To this end, the invention proposes an imaging method using shear waves for observing a viscoelastic medium, comprising:

- several successive excitation steps j during
5 which elastic shear waves are generated respectively at different excitation loci in the viscoelastic medium by an imaging device, said different excitation loci being separated from one another by a maximum distance D_m ,
- an imaging step corresponding to each
10 excitation step j , in which a set j of successive raw images $Im_j(t_k)$ of the viscoelastic medium at times t_k are determined by said imaging device during propagation of the shear wave in said viscoelastic medium, said raw images having a resolution R which is at least equal to
15 said maximum distance D_m , t_k being a relative time counted from generation of the corresponding shear wave,
- an averaging step in which raw images $Im_j(t_k)$ corresponding to the same relative time t_k are averaged to determine an average image $Im'(t_k)$ corresponding to said
20 relative time t_k .

Thus, the invention enables to eliminate most of the noise in the raw images, and enables to obtain averaged images having a higher signal-to-noise ratio. Therefore, the averaged images can be more efficiently treated to
25 obtain a better mapping of a shear wave propagation parameter, and optionally to obtain a spectroscopy of said propagation parameter (i.e. values of said propagation parameter as a function of the frequency) which enable to obtain certain rheological values of the
30 viscoelastic medium and in particular the rheological values representing viscous effects.

In various implementations of the method of the invention, it is optionally possible also to have recourse to one or more of the following dispositions:

- the method further comprises, between the imaging step and the averaging step, a repositioning step in which the raw images $Im_j(t_k)$ are spatially repositioned so that the different excitation loci are positioned in mutual correspondence in the raw images $Im_j(t_k)$;
5
- said raw images $Im_j(t_k)$ are spatially repositioned by offsetting a coordinate system of each raw image so that the different excitation loci have the same coordinates in the raw images $Im_j(t_k)$;
- 10 - a number J of said sets j of successive raw images, is at least 5;
- each excitation locus is separated from adjacent excitation loci by a pitch which is at most $R/5$, and which preferably is at most $R/10$;
- 15 - the excitation locus is moved in the viscoelastic medium by the imaging device from one excitation step to the other;
- the viscoelastic medium is moved while the excitation locus remains fixed relative to the imaging device from one excitation step to the other, so that the excitation locus is moved in the viscoelastic medium from one excitation step to the other;
- 20
- said shear excitation is generated by at least one ultrasound wave emitted into the viscoelastic medium by an array of ultrasound transducers belonging to said imaging device;
- 25
- said shear excitation is generated by applying an outside mechanical force to the viscoelastic medium at each excitation locus;
- 30 - each raw image $Im_j(t_k)$ is obtained either by ultrasound imaging, or by IRM;
- the method comprises a characterizing step during which, based on said average images $Im'(t_k)$ over time, at least one shear wave propagation parameter is

calculated at at least one point of the viscoelastic medium;

- the shear wave propagation parameter which is calculated during the characterizing step, is selected
5 from shear wave speed, shear modulus, Young's modulus, shear wave attenuation, shear elasticity, shear viscosity, mechanical relaxation time and anisotropy;

- said excitation has a bandwidth of at least 500 Hz and said shear wave propagation parameter is
10 calculated at a plurality of frequencies in said bandwidth.

Furthermore, the invention also provides an imaging apparatus for implementing a method according to any preceding claim using shear waves to observe a
15 viscoelastic medium, said apparatus comprising at least one electronic central unit adapted:

- to generate elastic shear waves respectively at different excitation loci in the viscoelastic medium during several successive excitation steps j , said
20 different excitation loci being separated from one another by a maximum distance D_m ,

- to determine a set j of successive raw images $Im_j(t_k)$ of the viscoelastic medium at times t_k during propagation of the shear wave in said viscoelastic medium
25 respectively for each excitation step j , said raw images having a resolution R which is at least equal to said maximum distance D_m , t_k being a relative time counted from generation of the corresponding shear wave,

- to average raw images $Im_j(t_k)$ corresponding to
30 the same relative time t_k for determining an average image $Im'(t_k)$ for said relative time t_k .

In various implementations of the apparatus of the invention, it is optionally possible also to have recourse to one or more of the following dispositions:

- said electronic central unit is further adapted to spatially reposition said raw images $Im_j(t_k)$ before averaging said images so that the different excitation loci are positioned in mutual correspondence in the raw
5 images $Im_j(t_k)$;

- said electronic central unit is adapted to spatially reposition said raw images $Im_j(t_k)$ by offsetting a coordinate system of each raw image so that the different excitation loci have the same coordinates in
10 the raw images $Im_j(t_k)$;

- said electronic central unit is adapted to move the excitation locus in the viscoelastic medium from one excitation step to the other;

- said electronic central unit is adapted to
15 calculate at least one shear wave propagation parameter at at least one point of the viscoelastic medium based on successive average images over time, said shear wave propagation parameter being selected from shear wave speed, shear modulus, Young's modulus, shear wave
20 attenuation, shear elasticity, shear viscosity, mechanical relaxation time and anisotropy;

- said apparatus is adapted to apply said with a bandwidth of at least 500 Hz and said electronic central unit is adapted to calculate said shear wave propagation
25 parameter at a plurality of frequencies in said bandwidth.

Other characteristics and advantages of the invention appear from the following description of an embodiment thereof, given by way of non-limiting example
30 and with reference to the accompanying drawing.

BRIEF DESCRIPTION OF THE DRAWINGS

In the drawings:

- Figure 1 is a diagrammatic view of an example of a shear-wave imaging device in one embodiment of the
35 invention,

- Figure 2 illustrates an example of a set of successive raw images of the viscoelastic medium, determined by the imaging device of Figure 1, showing the excitation loci at which the shear waves are successively generated in the viscoelastic medium,

- Figure 3 illustrates a repositioning step in which the raw images are spatially repositioned so that the different excitation loci are positioned in mutual correspondence in the raw images,

10 - Figure 4 is an example of an average image obtained by averaging the various repositioned raw images of Figure 3, in a particular example,

- Figure 5 is a raw image corresponding to the average image of Figure 4,

15 - and Figure 6 is a diagram showing the shear wave speed as a function of the frequency, computed at one point of the viscoelastic medium from successive averaged images such as that of Figure 4.

MORE DETAILED DESCRIPTION

20 In the various figures, like references designate elements that are identical or similar.

The imaging device 1 shown in Figure 1 is for studying the propagation of elastic shear waves in a viscoelastic medium 2 that diffuses ultrasound waves in compression, and that may be constituted, for example:

- by an inert body, in particular for quality control in industrial applications; or

- a living body, for example a portion of the body of a patient, in medical applications.

30 By way of example, these movements are tracked by means of a microcomputer 4 (comprising at least an input interface 4b such as a keyboard, etc., and an output interface 4a such as a screen, etc.) or any other electronic central unit, serving to send ultrasound compression waves into the medium 2 from its outside

surface 3. These compression waves interact with
diffusing particles 5 contained in the medium 2, which
particles are reflective for ultrasound compression
waves. The particles 5 may be constituted by any non-
5 uniformity in the medium 2, and in particular, in a
medical application, they may be constituted by particles
of collagen present in human tissues (in echographic
images, such particles form points known as "speckle").

To observe the propagation of the shear wave, an
10 ultrasound probe 6 is used that is disposed against the
outside surface 3 of the observed medium 2. This probe
delivers ultrasound compression wave pulses along an axis
X, which pulses are of the type commonly used in
echography, for example having a frequency lying in the
15 range 0.5 MHz to 100 MHz, and preferably in the range
0.5 MHz to 15 MHz, e.g. being about 4 MHz.

The ultrasound probe 6 is constituted by an array of
n ultrasound transducers $T_1, T_2, \dots, T_i, \dots, T_n$, where n is an
integer not less than 1. By way of example, the probe 6
20 may be in the form of a linear strip of transducers
comprising, for example, $n=128$ transducers in alignment
along an axis Y that is perpendicular to the axis X.
However, the probe in question could equally be in the
form of a two-dimensional array of transducers (plane or
25 otherwise).

The transducers T_1-T_n are controlled independently of
one another by the microcomputer 4, possibly via a
central unit CPU which is contained for example in an
electronic rack 7 connected via a flexible cable to the
30 probe 6. The transducers T_1-T_n can thus emit
selectively:

- either an ultrasound compression wave that is
"plane" (i.e. a wave whose wave front is rectilinear in
the X,Y plane), or any other type of focused or unfocused
35 wave illuminating the entire observation field in the

medium 2, for example a wave generated by causing random sound signals to be emitted by the various transducers T_1 - T_n ;

5 - or else an ultrasound compression wave that is focused on one or more points of the medium 2.

To observe the propagation of the shear wave in the medium 2, several steps are performed in succession:

a) **an excitation step** during which the microcomputer 4 causes an elastic shear wave to be generated in the viscoelastic medium 2 by causing at least one ultrasound wave that is focused in the viscoelastic medium to be emitted by the probe 6;

b) **an observation step** during which the propagation of the shear wave is observed simultaneously at a multitude of observation field points in the viscoelastic medium 2,

c) and **an imaging step** during which the microcomputer 4 processes the sound signals received from the viscoelastic medium 2 during substep b2) in order to determine successive propagation images at successive instants t_k (t_k may be relative times, counted from the generation of the shear wave).

a) Excitation step

25 During the excitation step a), the shear excitation can be created by at least one focused ultrasound wave emitted into the viscoelastic medium 2 by the array of ultrasound transducers 6.

The focused ultrasound wave emitted during the excitation step a) may be a monochromatic wave of frequency f lying in the range 0.5 MHz to 15 MHz, for example being equal to about 4 MHz, which is emitted for a duration of p/f seconds, where p is an integer lying in the range 50 to 5000 (e.g. being about 500) and f is expressed in Hz. Such excitation in the form of a

rectangular signal or similar, may produce a shear wave with a relatively large bandwidth of at least 500 Hz (for instance a bandwidth of 0-1000 Hz).

The focused ultrasound wave emitted during
5 excitation step a) may be focused on a single focus point or on a plurality of focus points so that the shear wave as generated presents a desired wave shape and illuminates desired zones in the medium 2. The focus point(s) constitute the excitation locus, where the shear
10 wave is generated. For example, the excitation locus L may be in the form of a straight line obtained by quickly focusing several successive ultrasound waves along this straight line, in which case it is possible to generate a shear wave that is plane as explained for instance by
15 Bercoff et al. ["Supersonic Shear Imaging: a New Technique for Soft Tissue Elasticity Mapping", IEEE transactions on ultrasonics, ferroelectrics, and frequency control, vol. 51, no. 4, April 2004, p. 396-409].

20

b) Observation step

The observation step may comprise the following substeps:

b1) the microcomputer 4 causes the probe 6 to
25 emit into the viscoelastic medium a succession of ultrasound compression wave shocks, which may preferably be unfocussed or lightly focused, at a rate of at least 500 shots per second [the focusing and the timing of the focus ultrasound wave emitted in step a), and the timing
30 of said ultrasound waves are adapted so that at least some of said ultrasound waves reach the observation field during the propagation of the shear wave through the observation field, for at least some of the ultrasound wave emissions];

b2) the microcomputer 4 causes the probe 6 to detect and record in real time sound signals received from the viscoelastic medium 2, said signals comprising echoes generated by the ultrasound compression wave interacting with the reflecting particles 5 in the viscoelastic medium, these echoes corresponding (directly or indirectly) to successive images of the displacement of the viscoelastic medium.

During step b1), which may last for example for less than one second, it is possible to emit for instance unfocused ultrasound compression waves at a rate lying in the range 500 to 10,000 shots per second, and preferably in the range 1000 to 5000 shots per second (with this rate being limited by the go-and-return travel time for the compression wave through the medium 2, i.e. by the thickness of the medium 2 in the direction X: it is necessary for all of the echoes that are generated by the compression wave to have been received by the probe 6 before a new compression wave is sent).

Each unfocused ultrasound compression wave propagates through the medium 2 at a propagation speed that is much higher than that of shear waves (e.g. about 1500 meters per second (m/s) in the human body), and interacts with the reflecting particles 5, thereby generating echoes or other analogous disturbances in the signal that are known in themselves under the name "speckle noise" in the field of echography.

The speckle noise is picked up by the transducers T_1 - T_n during substep b2), after each shot k of an unfocused ultrasound compression wave. The signal $s_i(t_k)$ as picked up in this way by each transducer T_i after shot No. k is initially sampled at high frequency (e.g. 30 MHz to 100 MHz) and is digitized in real time (e.g. on 12 bits) by a sampler forming part of the rack 7 and connected to

said transducer, the samplers being referenced respectively $E_1, E_2, \dots, E_n$.

The signal $s_i(t_k)$ as sampled and digitized in this way is then stored, likewise in real time, in a memory M_i
5 belonging to the rack 7 and specific to the transducer T_i .

By way of example, each memory M_i presents a capacity of about 128 megabytes (MB), and contains all of the signals $s_i(t_k)$ received in succession for shots $k = 1$ to q where q is the total number of ultrasound shots.

10

c) Imaging step

The imaging step c) can be performed by microcomputer 4 for instance in deferred time, after all of the signals $s_i(t_k)$ corresponding to the same
15 propagation of a shear wave have been stored, the central unit CPU causes these signals to be reprocessed by a summing circuit S belonging to the rack 7 (or else it performs this treatment itself, or indeed the treatment may be performed in the microcomputer 4), using a
20 conventional path-forming step corresponding to substep c1), as explained for instance in US-B2-7 252 004.

This generates images $Im(t_k)$, e.g. 2D images in the present case, each in the form of a matrix corresponding to discrete positions of coordinates (x, y) in the
25 observation field, each corresponding to the image of the observation field after shot No. $\underline{k}$.

After the path-forming step, the central unit CPU stores the images $Im(t_k)$ in a central memory M forming part of the rack 7 or in the microcomputer 4.

30 Each image $Im(t_k)$ may have a resolution R of around 1 mm or less.

Reiteration of steps a-c

According to the present invention, steps a-c are
35 reiterated for a number of times J which can be for

instance comprised between 4 and 10. During the excitation steps $j=1$ to J , the excitation locus L_j is offset from one iteration j to the other by the imaging device 1 (by changing the focusing of the ultrasound waves transmitted by the transducer array 6, i.e. by changing the delays applied to the transducers T_1-T_n , as it is well known in the art). The successive excitation loci L_j are separated from one another by a maximum distance D_m which is at most equal to, preferably lower than, said resolution R . In a particular embodiment, each excitation locus L_j can be separated from adjacent excitation loci by a pitch which is at most $R/5$, and which preferably is at most $R/10$. For instance, one may use $J=7$ iterations and the excitation loci L_j may be offset of a pitch of $R/10$ at each iteration, so that the total offset D_m between the first iteration ($j=1$) to the last ($j=J$) is equal to $7R/10$.

When the excitation locus L_j is a straight line parallel to axis X as shown for instance on Figure 2, said excitation locus L_j can be offset of said pitch parallel to axis Y from one iteration to the following. The above offset can be obtained by the fact that the excitation locus L_j is moved in the viscoelastic medium 2 by the imaging device 1 from one excitation step a) to the other. When the excitation locus is a straight line, this line can also be offset from one iteration to the other by tilting this line of a small angle (a few degrees): in this case, the distance from each point of one excitation line to another excitation line (said distance is then measured perpendicularly to the excitation line where said point belongs) varies along said line and said maximum distance D_m is the maximum value of said distance from one point of one excitation locus to the other excitation locus.

In a variant, the viscoelastic medium 2 is moved from one excitation step to the other while the array 6 remains fixed and the excitation locus remains fixed relative to the transducer array 6, so that the
5 excitation locus L_j is moved in the viscoelastic medium 2 from one excitation step to the other. This may apply for instance when the medium 2 is part of the heart or of the liver of a living human or animal. In such a case, the successive excitation steps a) may be carried out at
10 times where the position of the medium 2 is very close to a reference position, so that the maximum distance D_m between the excitation loci remains less than the resolution R .

After each excitation step j , one obtains a set of
15 images $Im_j(t_k)$ as explained above, at successive instants t_k . These images $Im_j(t_k)$ will be called raw images hereafter.

d) Repositioning step

20 As shown on Figure 3, the raw images $Im_j(t_k)$ may be spatially repositioned so that the different excitation loci (L_j) are positioned in mutual correspondence in the various raw images $Im_j(t_k)$. This repositioning can be obtained for instance by offsetting the coordinate system
25 (x, y) [or a 3D coordinate system (x, y, z) in case of a 3D imaging] of the raw images $Im_j(t_k)$ so that the different excitation loci (L_j) have the same coordinates in all the raw images $Im_j(t_k)$. The repositioning step can be carried out either on each raw image after each imaging step c),
30 or on all raw images at the same time after all iterations of steps a-c.

This repositioning step may optionally be omitted. When the viscoelastic medium 2 is movable and the excitation locus remains fixed relative to the transducer
35 array as explained above, this repositioning step can be

preferably omitted; on the contrary, when the excitation locus L_j is moved relative to the transducer array from one iteration to the other, said repositioning is preferably used.

5

e) Averaging step

The raw images $Im_j(t_k)$ (after their repositioning if any) corresponding to the same relative time t_k are then averaged to determine an average image $Im'(t_k)$ corresponding to said relative time t_k . The average can be a simple arithmetic average of the pixel values $s_j(t_k)(x,y)$ of the raw images.

As shown on Figure 4, the averaging step enables to obtain an average image of much better quality than the raw images as that shown on Figure 5. In particular, the signal-to-noise ratio of the image is dramatically increased by the averaging step, which enables better characterization of the rheological features of the viscoelastic medium 2 at the next step.

At 2 mm lateral distance from the pushing area, the maximum shear wave frequency is 200 Hz (@ - 6 dB). All frequency components above 200 Hz have been attenuated by the tissue. When using the new averaging method, the maximum shear wave frequency is 500 Hz (@ - 6 dB) giving access, for a given location, to much more information about tissue viscoelasticity than in the conventional method.

f) Characterizing step

Based on the average images $Im'(t_k)$ over time, at least one shear wave propagation parameter is calculated at at least one point of the viscoelastic medium, preferably on the complete image to obtain a mapping of the viscoelastic medium. This shear wave propagation parameter can be selected for instance from shear wave

35

speed, shear modulus, Young's modulus, shear wave
attenuation, shear elasticity, shear viscosity,
mechanical relaxation time and anisotropy. Such parameter
can be determined for instance as explained in US-B2-7
5 252 004.

Further, due to the good signal-to-noise ratio of
the averaged images, it is possible to carry out a
spectrometric analysis of said parameter. For instance,
as shown on Figure 6, when said parameter is the speed v
10 of the shear waves, it is possible to determine said
speed v as a function of the frequency f in the bandwidth
of the shear wave.

When the measured parameter is shear wave
attenuation α , such attenuation may be considered as
15 varying according to a law such as (see for instance :

$$\alpha(f) = \alpha_0 + \alpha_1 f^a$$

where f is the shear wave frequency and a is a power
factor generally comprised between 0 and 2 for mechanical
waves in biological mediums. In this case, the present
20 invention can enable to assess the power factor a
precisely and to map y in the viscoelastic medium as
taught for instance in WO-A-2009/007582.

Variants

25 In a variant, the excitation of the shear waves
could be obtained by applying an outside mechanical force
to the viscoelastic medium at each excitation locus, for
instance thorough a vibrator controlled by the
microcomputer 4, as explained for instance in WO-A-
30 00/55616.

In another variant, each raw image $Im_j(t_k)$ is
obtained by IRM rather than by ultrasound imaging.

Claims

1. An imaging method using shear waves for observing a viscoelastic medium, the method comprising:
 - several successive excitations j during which elastic shear waves are generated respectively at different excitation loci (L_j) in the viscoelastic medium by an imaging device, any two of said different excitation loci being separated from one another by a maximum distance D_m ,
 - imaging each excitation step j , in which a set j of successive raw images $Im_j(t_k)$ of the viscoelastic medium at times t_k are determined by said imaging device during propagation of the shear wave in said viscoelastic medium, t_k being a relative time counted from generation of the corresponding shear wave, said raw images having a resolution R , and wherein the maximum distance D_m is lower or equal to the resolution R ,
 - averaging raw images $Im_j(t_k)$ corresponding to a same relative time t_k to determine an average image $Im_j(t_k)$ corresponding to said relative time t_k .
2. The imaging method according to claim 1, further comprising, between the imaging and the averaging, spatially repositioning the raw images $Im_j(t_k)$ by offsetting a coordinate system of each raw image so that the excitation loci (L_j) have same coordinates in the raw images $Im_j(t_k)$ and so that the excitation loci (L_j) are positioned in mutual correspondence in the raw images $Im_j(t_k)$.
3. The imaging method according to any one of claims 1 to 2, wherein a number J of said sets j of successive raw images, is at least 5.
4. The imaging method according to any one of claims 1 to 3, wherein each excitation locus (L_j) is separated from adjacent excitation loci by a pitch which is at most $R/5$.
5. The imaging method according to any one of claims 1 to 4, wherein the excitation locus (L_j) is moved in the viscoelastic medium by the imaging device from one excitation step to another.
6. The imaging method according to any one of claims 1 to 4, wherein the viscoelastic medium is moved while the excitation locus remains fixed relative to the imaging device from one excitation step to another, so that the excitation locus (L_j) is moved in the viscoelastic medium from one excitation step to another.
7. The imaging method according to any one of claims 1 to 6, wherein said shear excitation is generated by at least one ultrasound wave emitted into the viscoelastic medium by an array of ultrasound transducers belonging to said imaging device.

8. The imaging method according to any one of claims 1 to 6, wherein said shear excitation is generated by applying an outside mechanical force to the viscoelastic medium at each excitation locus.
9. The imaging method according to any one of claims 1 to 8, wherein each raw image $Im_j(t_k)$ is obtained by one of ultrasound imaging and magnetic resonance imaging.
10. The imaging method according to any one of claims 1 to 9, further comprising calculating at least one shear wave propagation parameter for at least one point of the viscoelastic medium based on said average images $Im_j(t_k)$ over time.
11. The imaging method according to claim 10, wherein the shear wave propagation parameter which is calculated is selected from shear wave speed, shear modulus, Young's modulus, shear wave attenuation, shear elasticity, shear viscosity, mechanical relaxation time and anisotropy.
12. The imaging method according to claim 10 or claim 11, wherein said excitation has a bandwidth of at least 500Hz and said shear wave propagation parameter is calculated at a plurality of frequencies in said bandwidth.
13. An imaging apparatus for implementing a method according to any one of claims 1 to 12 using shear waves to observe a viscoelastic medium, said apparatus comprising at least one electronic central unit adapted for:
 - generating elastic shear waves respectively at different excitation loci (L_j) in the viscoelastic medium during several successive excitation steps j , any two of said different excitation loci being separated from one another by a maximum distance D_m ;
 - determining a set j of successive raw images $Im_j(t_k)$ of the viscoelastic medium at times t_k during propagation of the shear wave in said viscoelastic medium respectively for each excitation step j , t_k being a relative time counted from generation of a corresponding shear wave, said raw images having a resolution R , and wherein the maximum distance D_m is lower or equal to the resolution R ; and
 - averaging raw images $Im_j(t_k)$ corresponding to a same relative time t_k for determining an average $Im_j(t_k)$ for said relative time t_k .
14. The apparatus according to claim 13, wherein said electronic central unit is further adapted to spatially reposition said raw images $Im_j(t_k)$ before averaging said images by offsetting a coordinate system of each raw image so that the excitation loci (L_j) have same coordinates in the raw images $Im_j(t_k)$ and so that the different excitation loci (L_j) are positioned in mutual correspondence in the raw images $Im_j(t_k)$.

15. The apparatus according to any one of claims 13 to 14, wherein said electronic central unit is adapted to move the excitation locus (L_j) in the viscoelastic medium from one excitation step to another.
16. The apparatus according to any one of claims 13 to 15, wherein said electronic central unit is adapted to calculate at least one shear wave propagation parameter for at least one point of the viscoelastic medium based on successive average images over time, said shear wave propagation parameter being selected from shear wave speed, shear modulus, Young's modulus, shear wave attenuation, shear elasticity, shear viscosity, mechanical relaxation time and anisotropy.
17. The apparatus according to claim 16, wherein said apparatus is adapted to apply said excitation with a bandwidth of at least 500Hz and said electronic central unit is adapted to calculate said shear wave propagation parameter at a plurality of frequencies in said bandwidth.
18. The imaging method according to claim 4, wherein the pitch is at most $R/10$.

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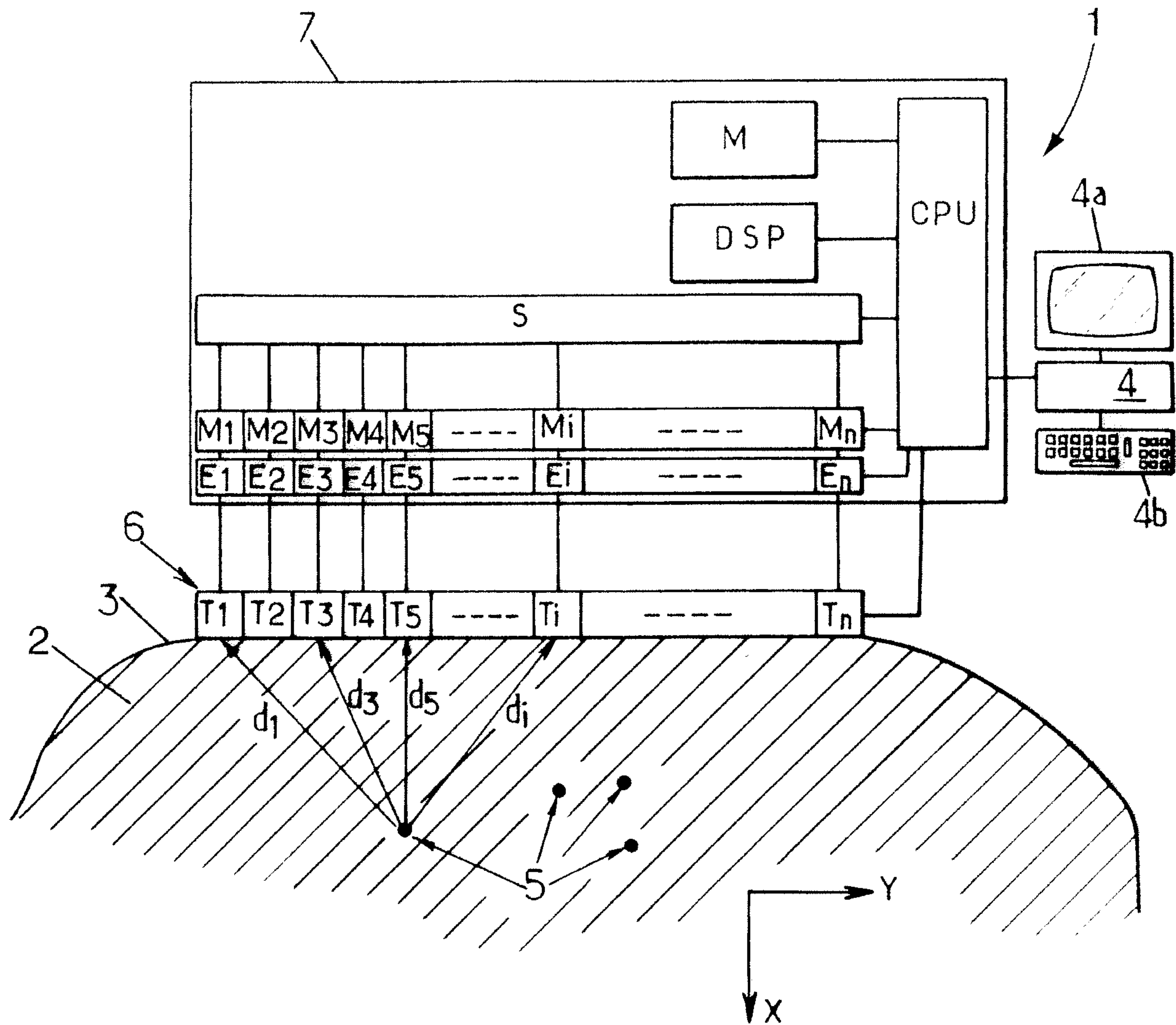


FIG.1.

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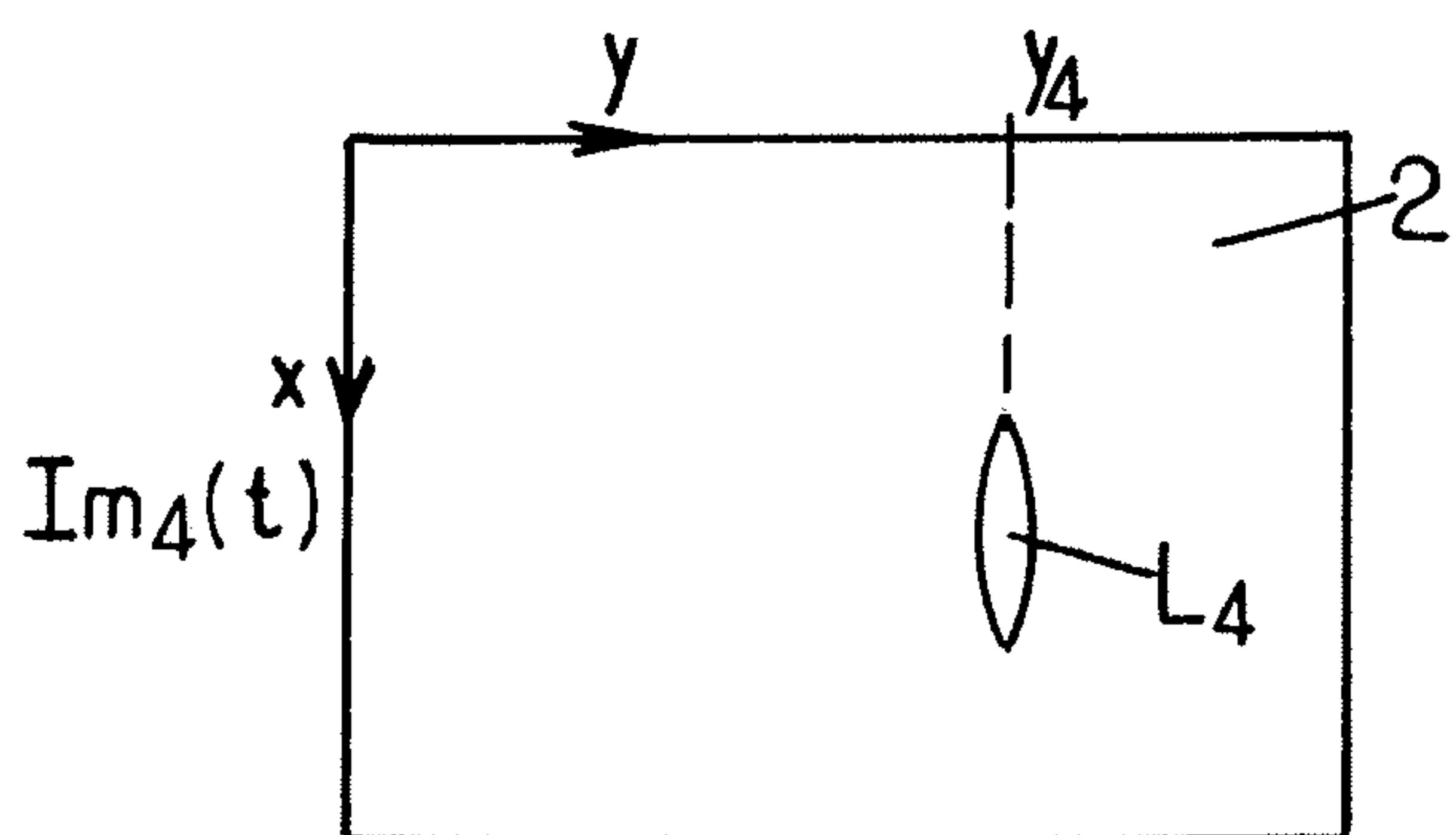
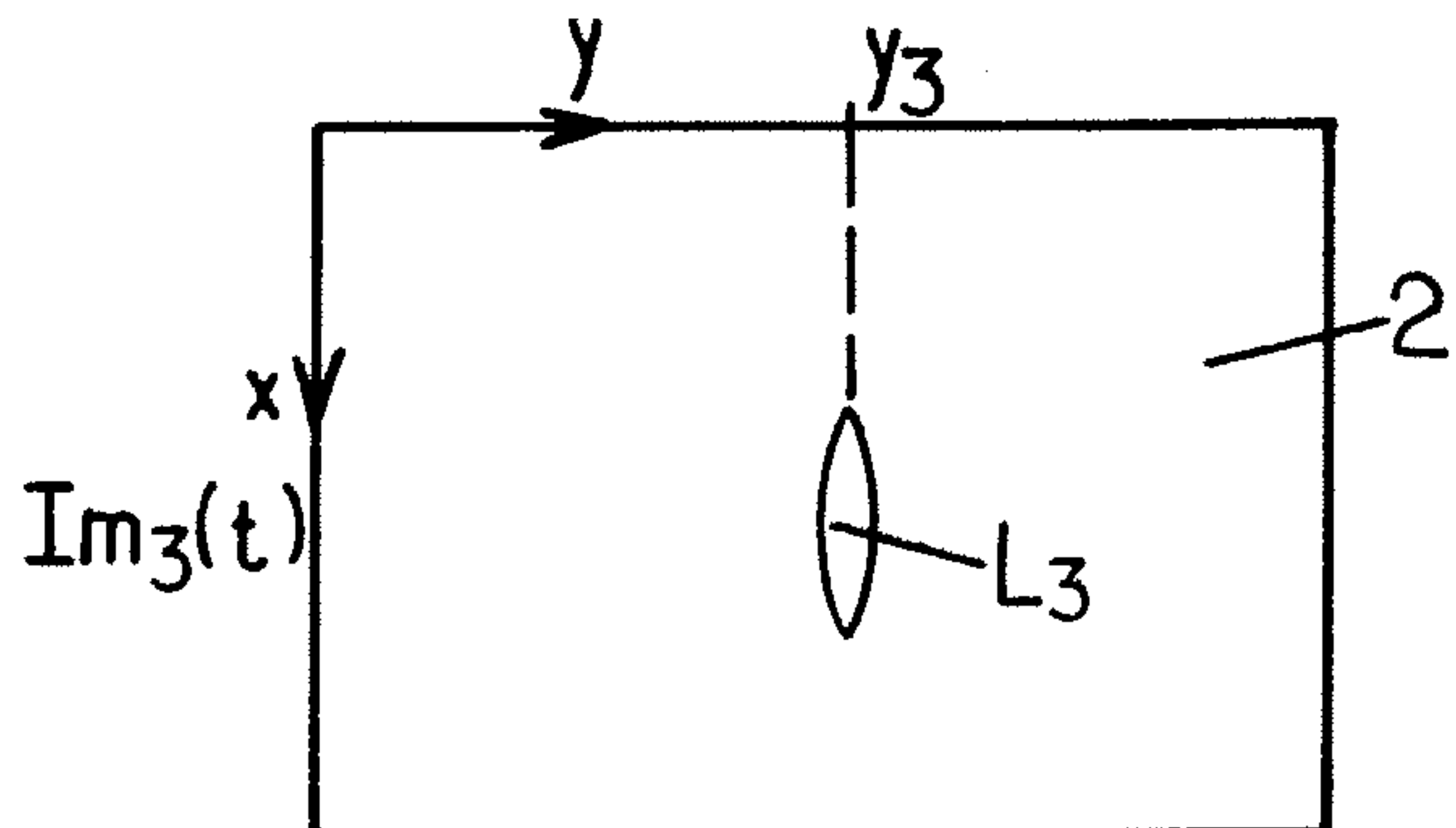
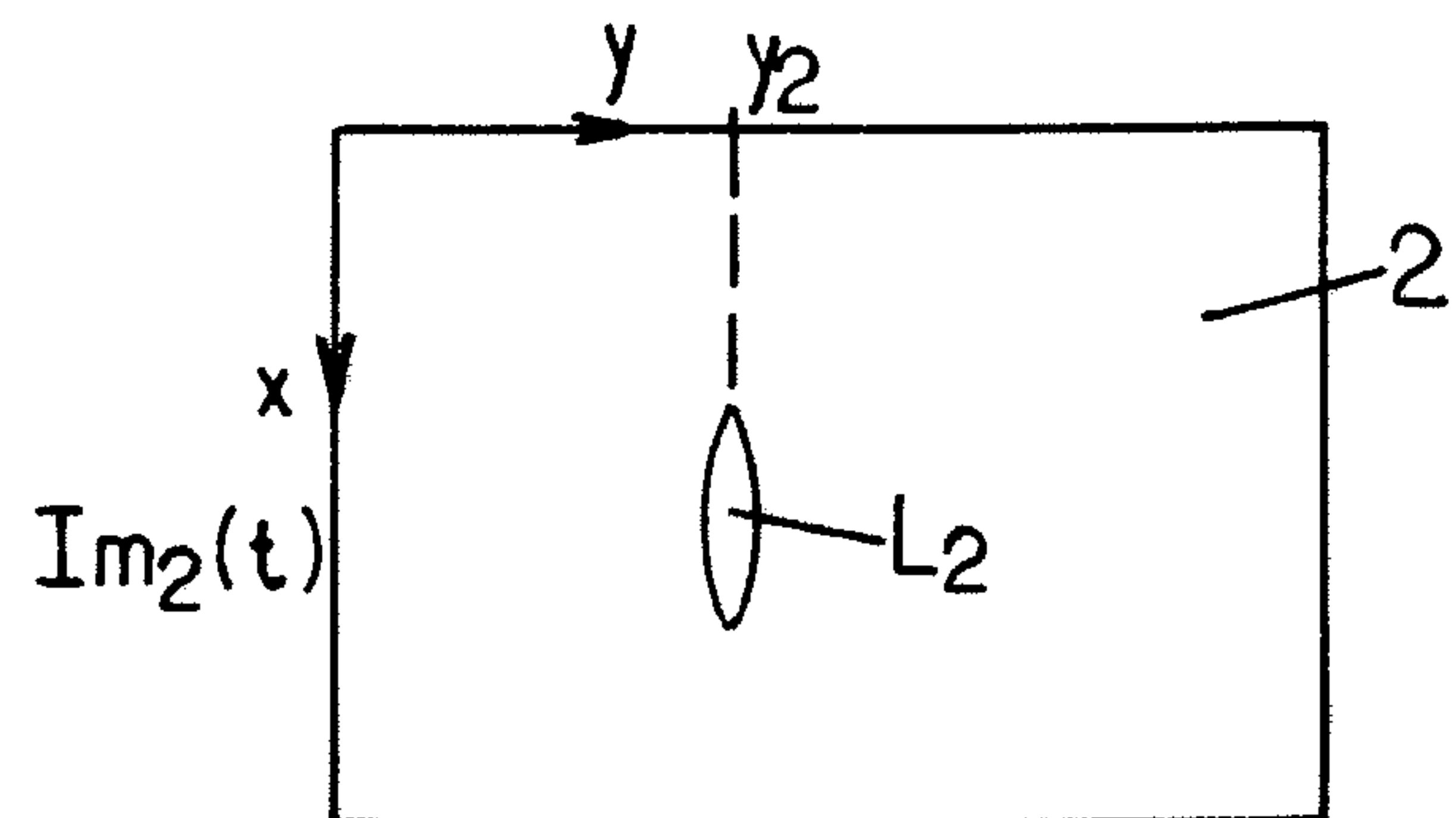
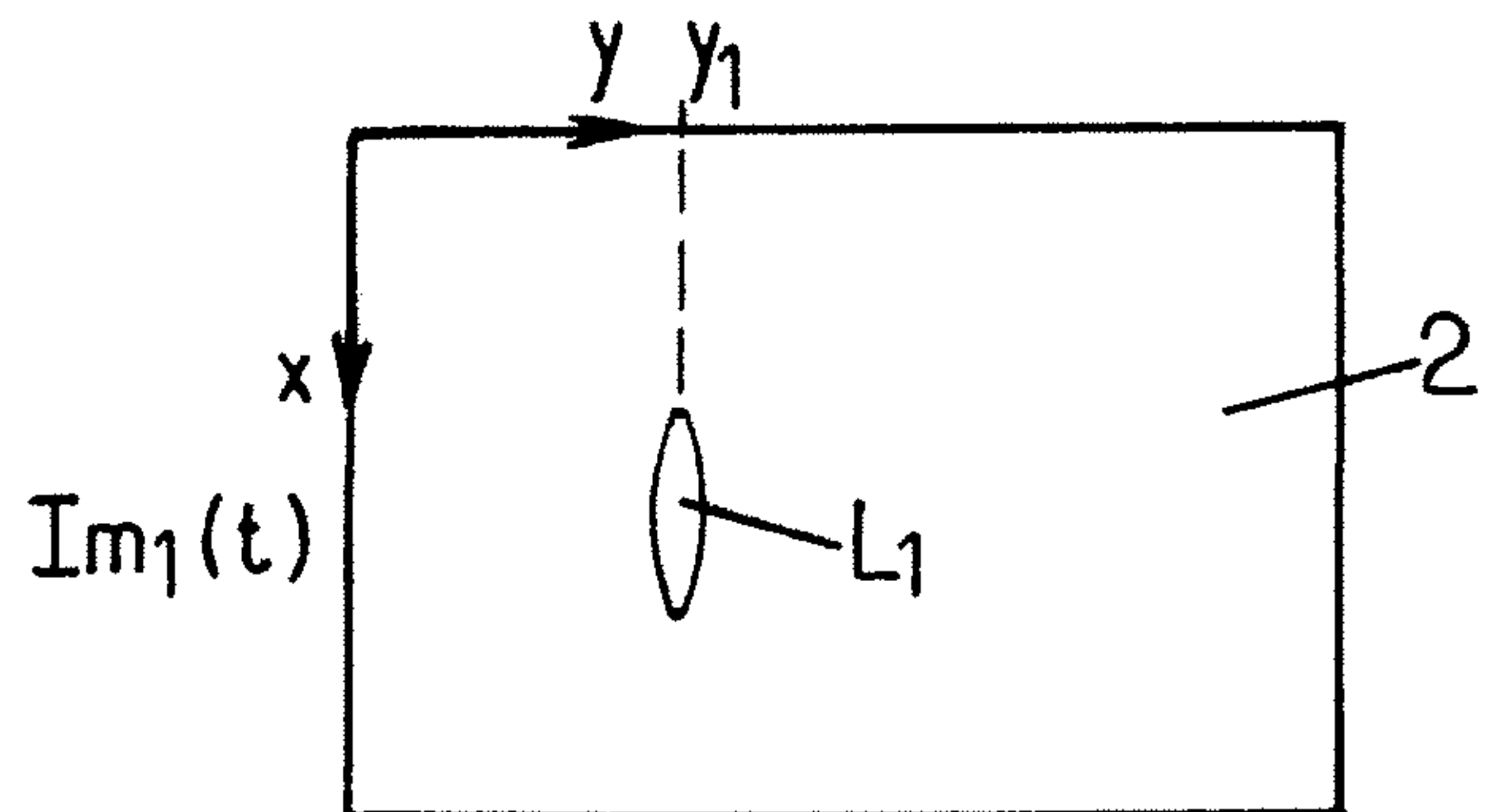


FIG.2.

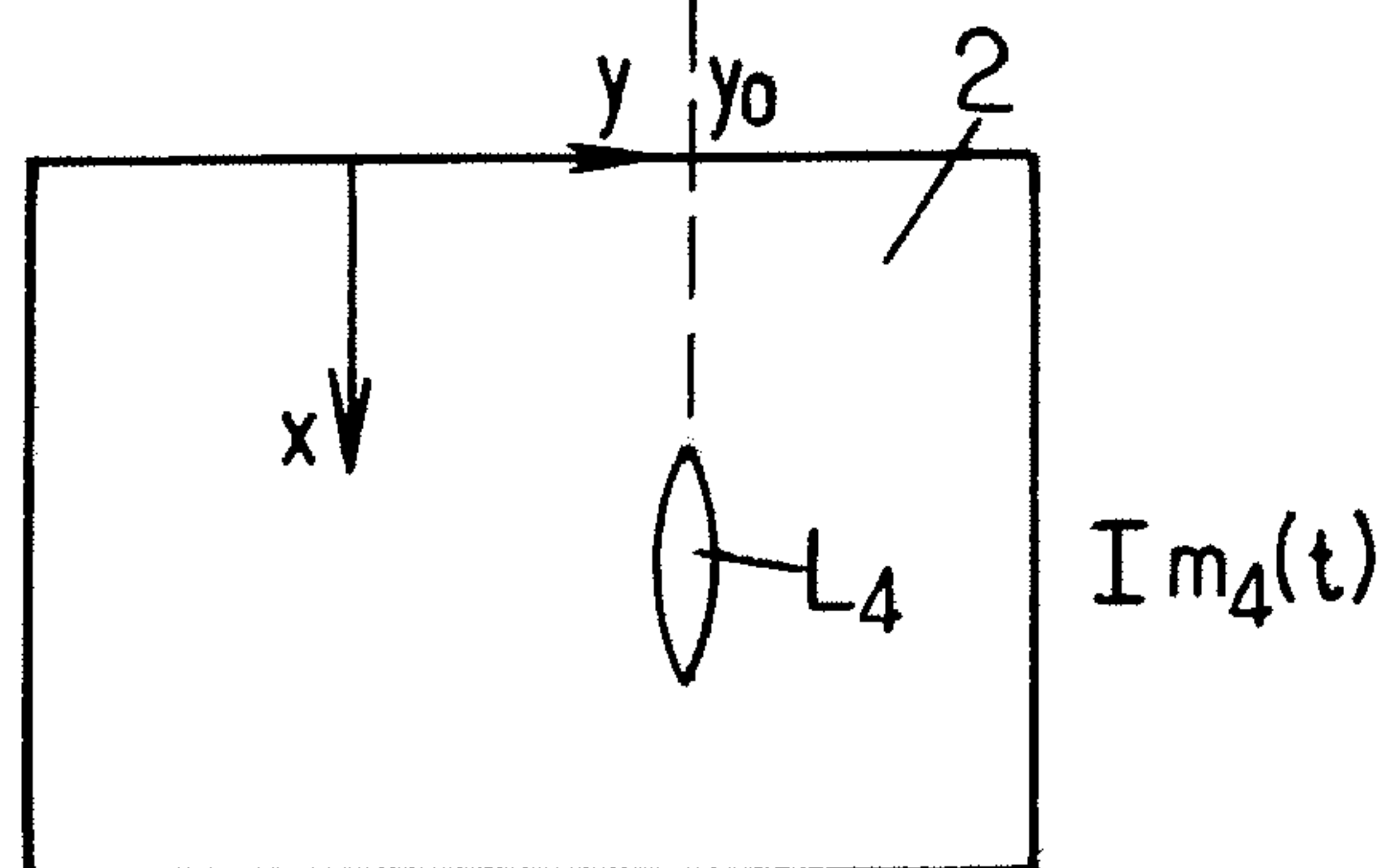
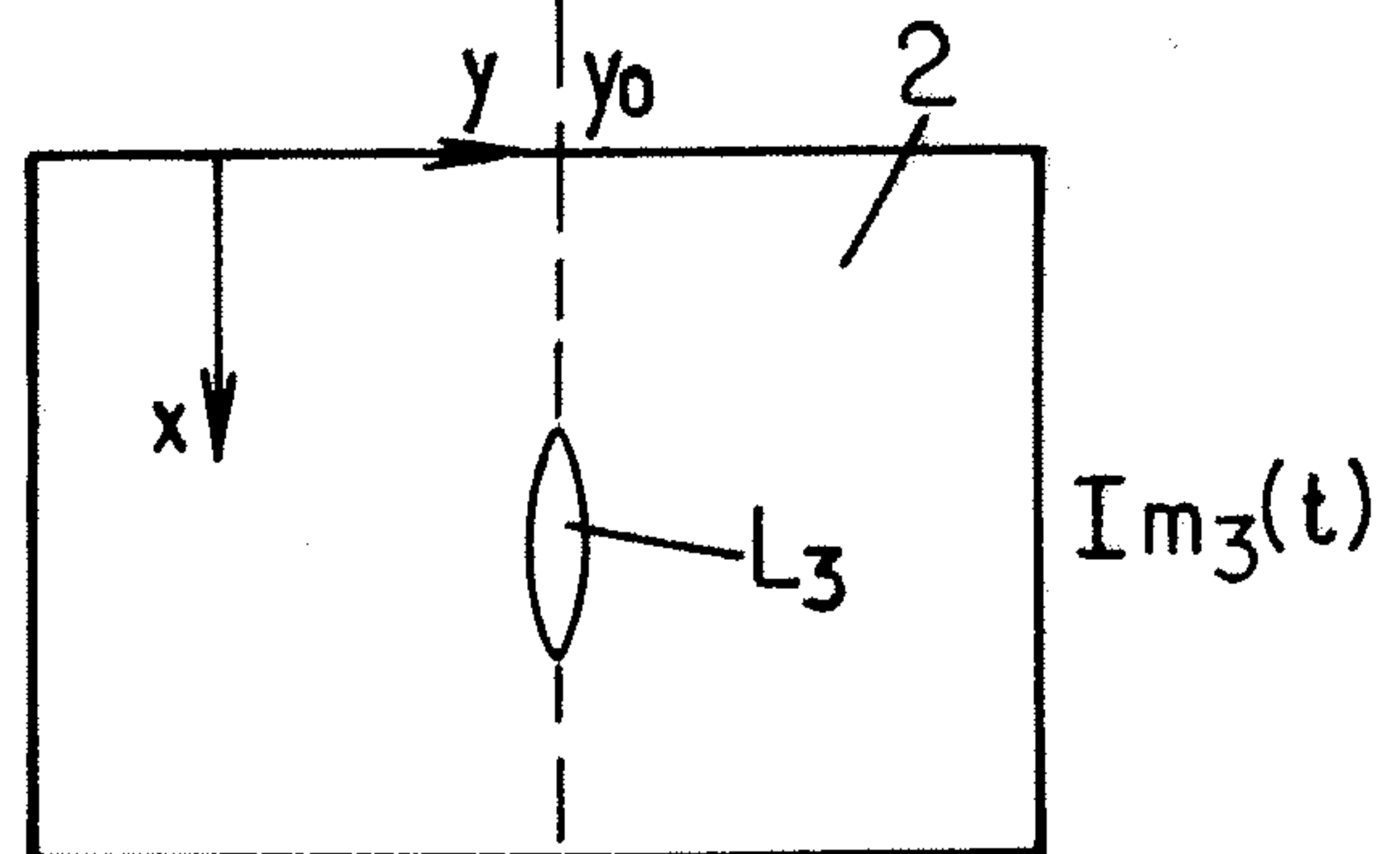
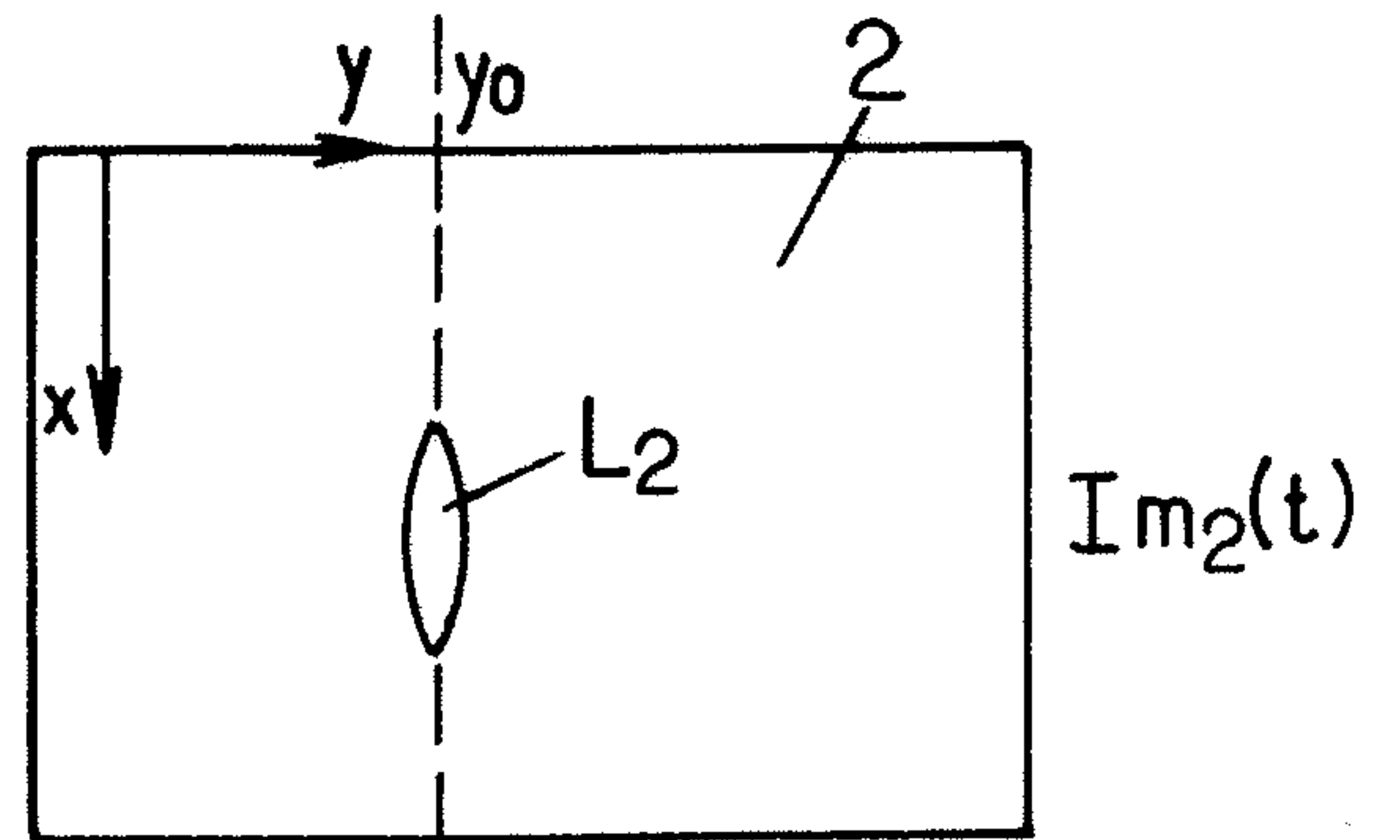
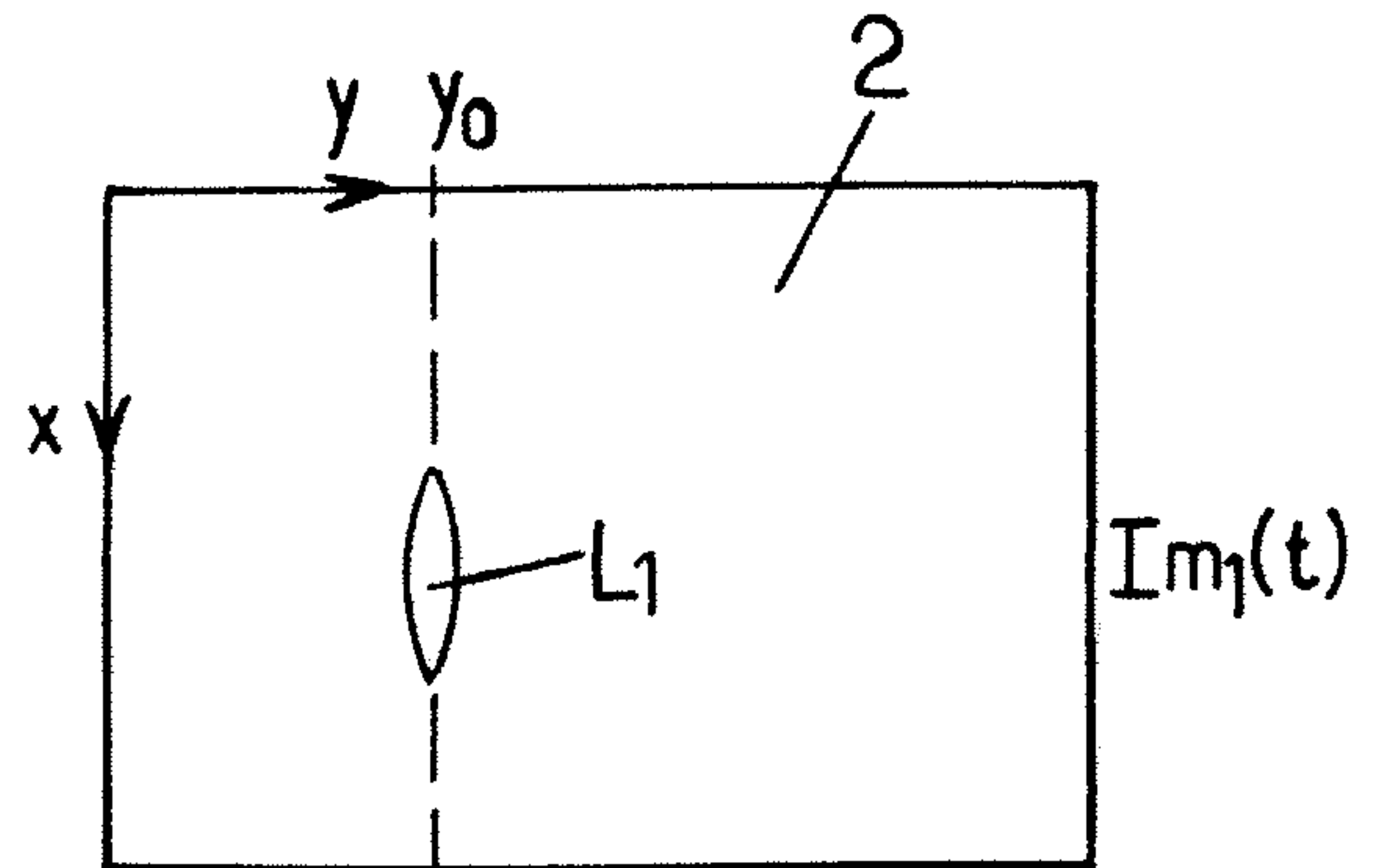


FIG.3.

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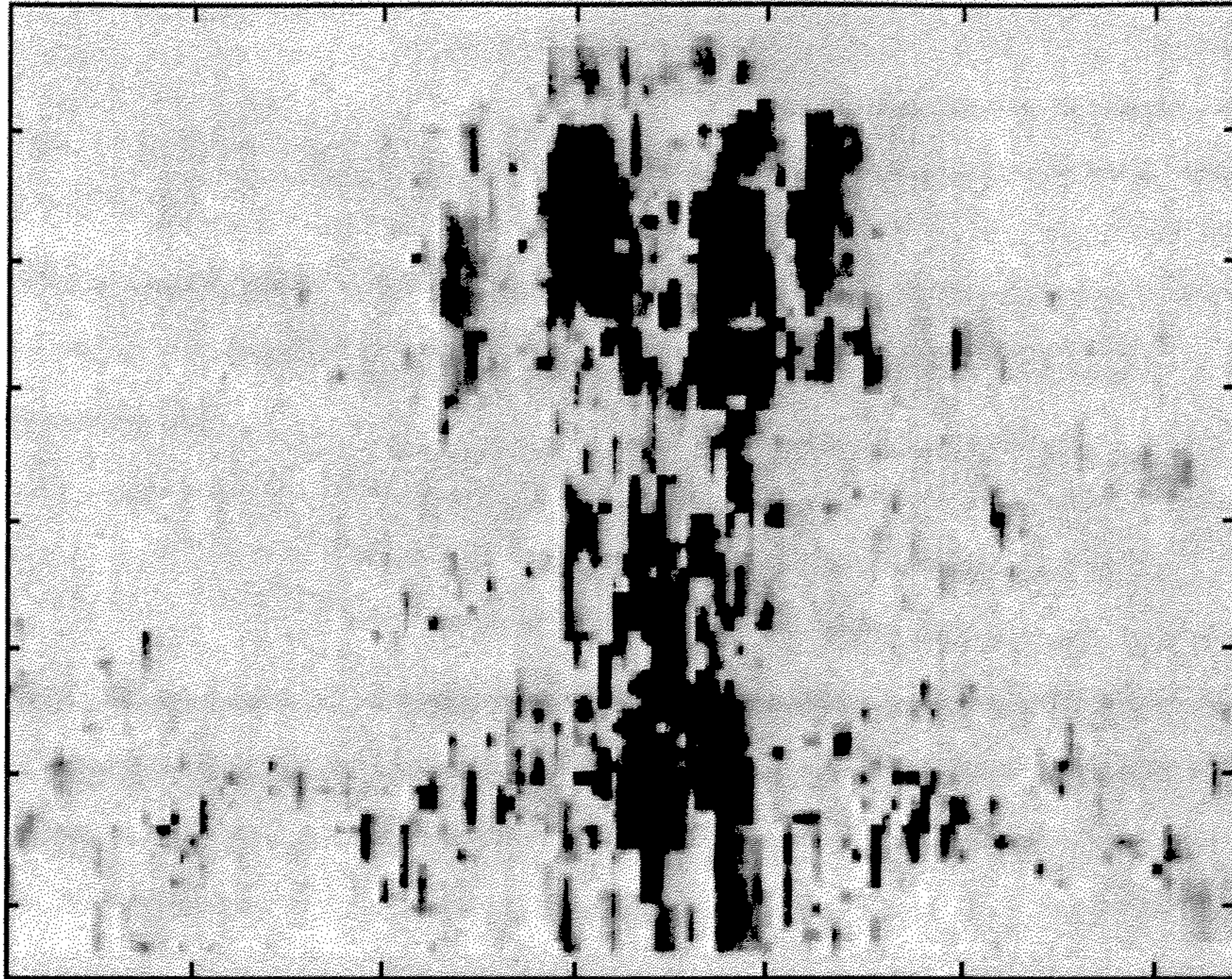


FIG. 5.

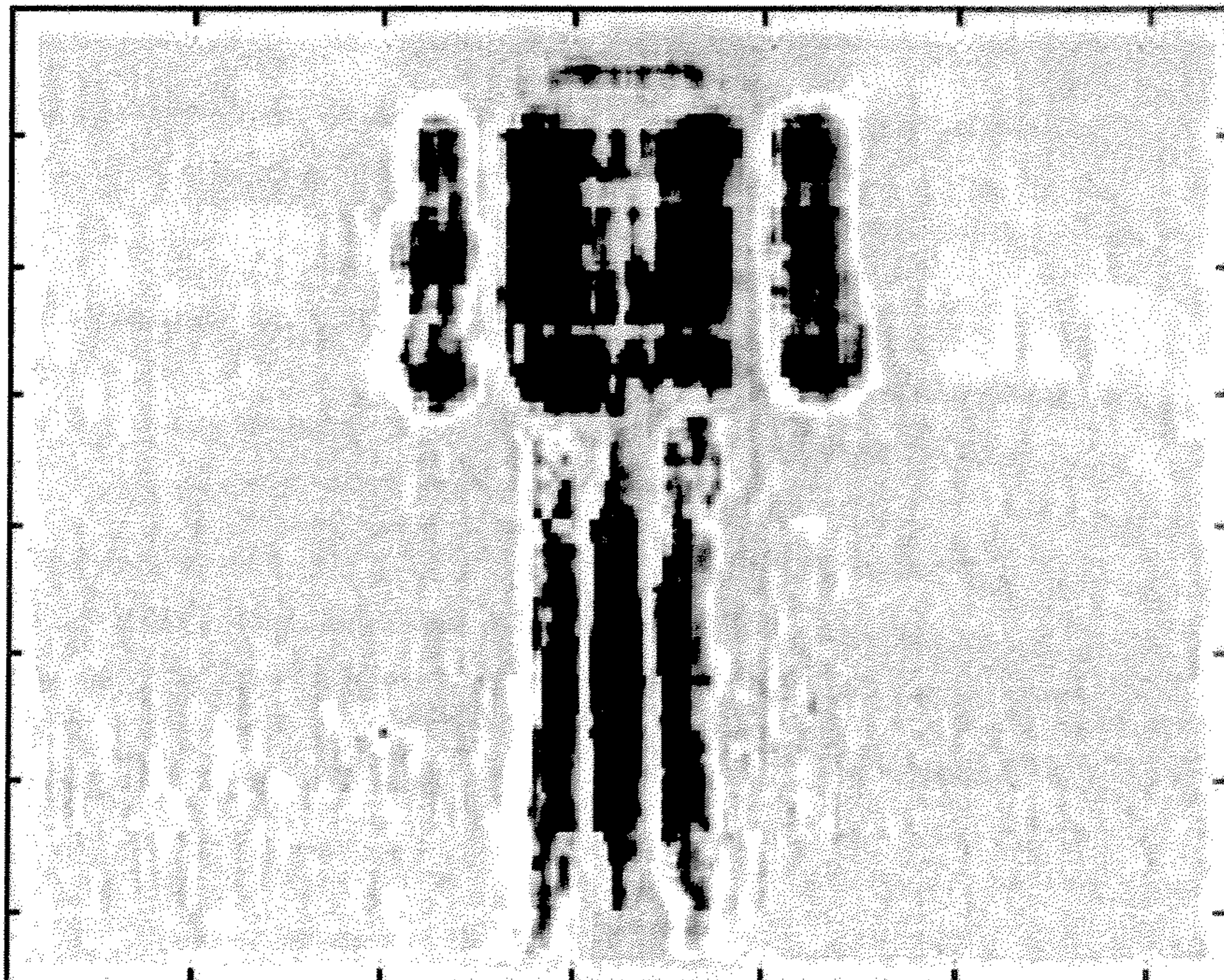


FIG. 4.

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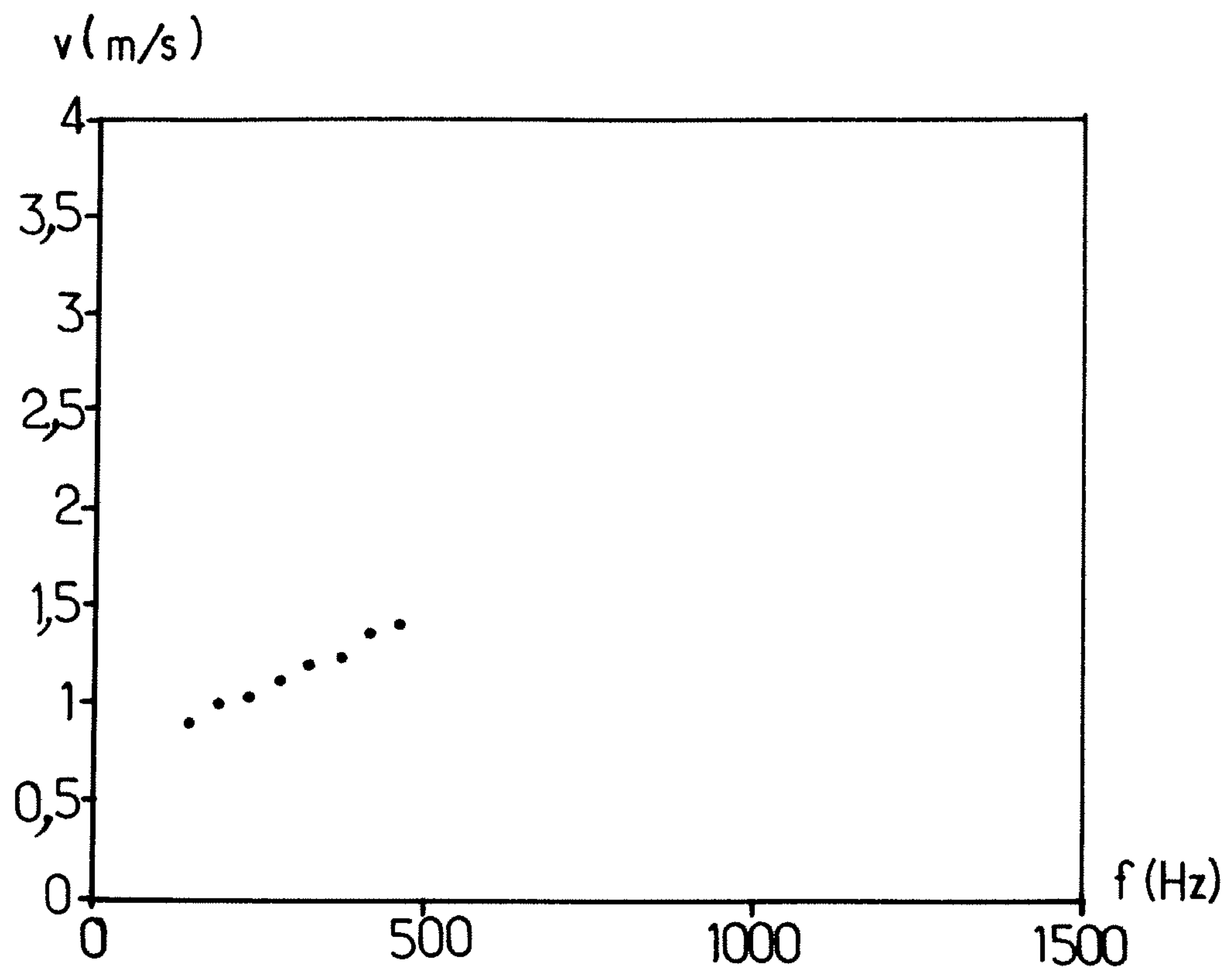


FIG.6.

