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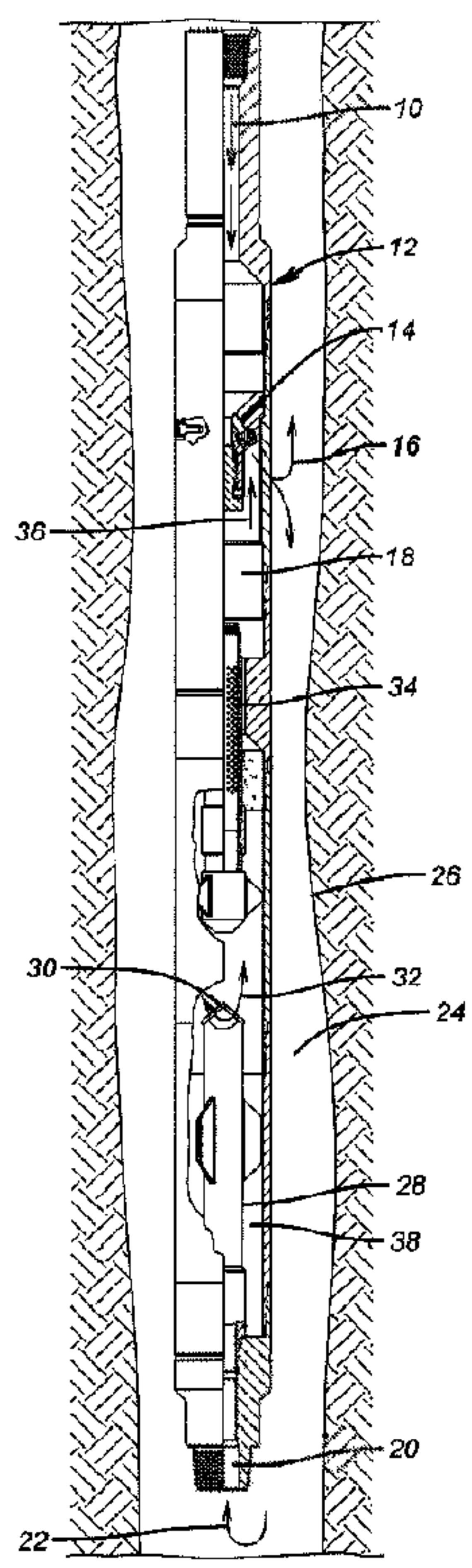
(54) Titre : OUTIL DE NETTOYAGE DE PUITS A RETOUR D'ETAT EN TEMPS REEL VERS LA SURFACE
(54) Title: WELL CLEANUP TOOL WITH REAL TIME CONDITION FEEDBACK TO THE SURFACE



(57) **Abrégé/Abstract:**
A flow sensor is incorporated into a junk basket to sense a flow stoppage due to a plugged screen or plugged cuttings ports in a mill. The sensor triggers a signal to the surface to warn personnel that a problem exists before the equipment is damaged. The sensor signal to the surface can take a variety of forms including mud pulses, a detectable pressure buildup at the surface, electromagnetic energy, electrical signal on hard wire or radio signals in a wifi system to name a few options. Surface personnel can interrupt the signal to take corrective action that generally involves pulling out of the hole or reverse circulating to try to clear the screen or mill cuttings inlets. Other variables can be measured such as the volume or weight or rate of change of either and a signal can be sent to the surface corresponding to one of those variables to allow them to be detected at the surface in near real time.

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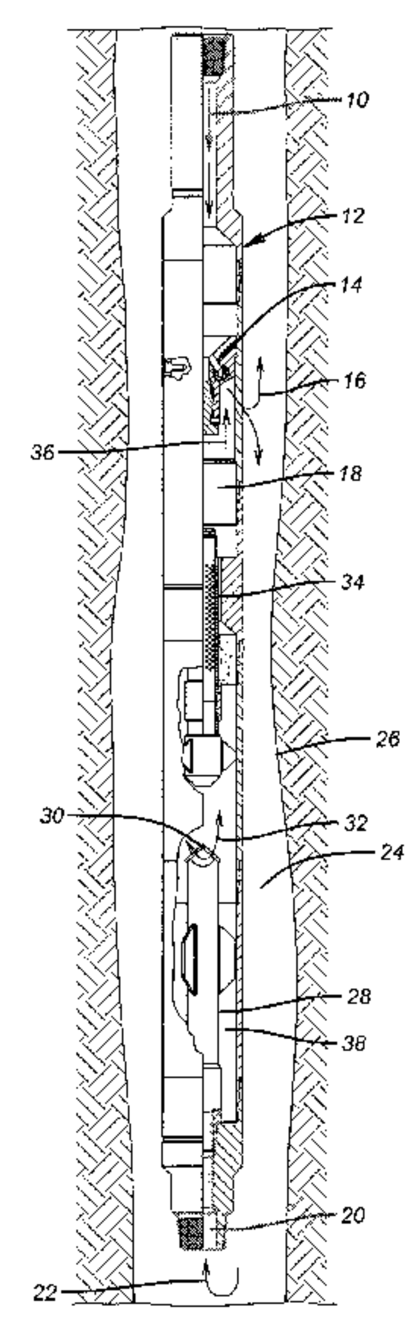
(54) Title: WELL CLEANUP TOOL WITH REAL TIME CONDITION FEEDBACK TO THE SURFACE



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APPLICATION FOR PATENT

Title: Well Cleanup Tool with Real Time Condition Feedback to the Surface

Inventors: Gerald D. Lynde; John P. Davis and Steve Rosenblatt

FIELD OF THE INVENTION

[0001] The field of this invention relates to well cleanup tools that collect debris and more particularly tools that collect cuttings from milling using an eductor to draw them into the tool body.

BACKGROUND OF THE INVENTION

[0002] When milling out a tool or pipe in the well cuttings are generated that need to be removed from the milling site and collected. The bottom hole assembly that includes the mill also has what is sometimes referred to as a junk basket. These tools operate on different principles and have the common objective of separation of circulating fluid from the cuttings. This is generally done by directing the flow laden with cuttings into the tool having a catch chamber. The fluid is directed through a screen, leaving the cuttings behind. At some point the cuttings fall down into the collection volume below and outside the screen.

[0003] The operation of one type of such tool is illustrated in Figure 1. In this known tool, flow comes from the surface through a string (not shown) and enters passage **10** in the tool **12**. Flow goes through the eductor **14** and exits as shown by two headed arrow **16**. Arrow **16** indicates that the exiting motive fluid can go uphole and downhole. The eductor **14** reduces pressure in chamber **18** all the way down to the lower inlet **20** on the tool **12**. Arrow **22** represents fluid indicated by arrow **16** that has traveled down the annulus **24** between tool **12** and tubular **26** as well as well fluid below tool **12** that is sucked in due to the venturi effect of the eductor **14**. Entering fluid at lower inlet **20** goes through a tube **28** that has a hat with openings under it **30**. Arrows **32** indicate the exiting flow out from under hat **30** that next goes to the outside of screen **34**. At this point the cuttings are stopped by the screen **34** while the fluid goes on through and into chamber **18** as indicated by arrow **36**. The stream indicated by arrow **36** blends and becomes part of as indicated by arrow **36**. The stream indicated by arrow **36** blends and becomes part of the stream exiting eductor **14** as indicted by arrow **16**. When flow into passage **10** is shut off, the accumulated debris on the outside of screen **34** simply falls down to around the outside of tube **28**. The presence of the hat **30** keeps the debris from falling into tube **28** deflecting debris that lands on it off to the side and into the annular catch area in the tool **38**.

[0004] This is how this tool is supposed to work when everything is going right. However, things don't always go right downhole and the operator at the surface using this tool in a milling operation had no information that things downhole may not be going according to plan. The main two things that can cause problems with this type of tool or any other junk basket tool is that the screen **34** can clog with debris. Those skilled in the art will appreciate that flow downhole in annulus **24** goes all the way down to the mill and enters openings in the mill to reach lower inlet **20** of the tool **12**. If the screen clogs the downhole component of the flow indicated by arrow **16** stops. As a result, there is a diminished or a total lack of flow into the mill ports to remove the cuttings and take away the heat of milling. The mill can overheat or get stuck in cuttings or both. If the mill sticks and turning force is still applied from the surface, the connections to the mill can fail. Sometimes, without clogging screen **34**, the mill can create cutting shapes that simply just ball up around the mill. Here again, if the balling up occurs, flow trying to go downhole in annulus **28** will be cut off. The inlet openings for the cuttings in the mill may become blocked limiting or cutting off flow into lower inlet **20**.

[0005] What the operator needs and currently doesn't have is a way to know that a condition has developed downhole at the mill or at the screen **34** that needs to be immediately addressed to avoid downhole equipment failure. While some operator with enough experience cleaning up a hole may be able to do this by gut feel in certain situations like removing sand, using gut feel is not reliable and in milling as opposed to simple debris cleanout, rules of thumb about how fast the bottom hole assembly moves into sand when removing it from the wellbore are simply useless.

[0006] What is needed and provided by the present invention is a real time way to know if anything has gone wrong downhole in time to deal with the issue before the equipment is damaged. The tool of the present invention is able to sense flow changes through it and communicate that fact in real time to the surface. Those and other aspects of the present invention will become apparent to those skilled in the art from a review of the description of the preferred embodiment, the drawings and the claims which outline the full scope of the invention.

SUMMARY OF THE INVENTION

[0007] A flow sensor is incorporated into a junk basket to sense a flow stoppage due to a plugged screen or plugged cuttings ports in a mill. The sensor triggers a signal to the surface to warn personnel that a problem exists before the equipment is damaged. The sensor signal to the surface can take a variety of forms including mud pulses, a detectable pressure buildup at the surface, electromagnetic energy, electrical signal on hard wire or radio signals in a WiFi system to name a few options. Surface personnel can interrupt the signal to take corrective action that generally involves pulling out of the hole or reverse circulating to try to clear the screen or mill cuttings inlets. Other variables can be measured such as the volume or weight or rate of change of either and a signal can be sent to the surface corresponding to one of those variables to allow them to be detected at the surface in near real time.

[0007a] Accordingly, in one aspect there is provided a milling debris catching tool for downhole use in a tubular string from the surface, comprising: a mill adapted to pass a predetermined fluid flow rate to remove cuttings from a milled object; a tool body having at least one inlet and outlet and a milling debris receptacle; a screen in a passage between said inlet and outlet to accept debris laden fluid and to prevent milling debris from passing through the tool so that it can be retained in said receptacle; and a sensor to detect how flow through said screen from said inlet to said outlet compares to the predetermined rate, said sensor operably connected to a valve member in said tool and selectively reconfiguring said passage for flow from said outlet to said inlet in an effort to unclog said screen if flow from said inlet to said outlet through said screen is below said predetermined rate.

[0007b] According to another aspect there is provided a milling debris catching tool for downhole use in a tubular string from the surface in conjunction with a mill, comprising a mill adapted to operate with a predetermined fluid stream for debris removal; a body having at least one inlet and outlet and a debris receptacle adjacent said screen; a screen in a passage between said inlet and outlet to prevent debris from passing through the tool and to direct it to said receptacle; and a sensor to detect the weight or volume or rate of change of debris, captured in said receptacle before it impedes said predetermined fluid stream through said mill.

[0007c] According to yet another aspect there is provided a debris catching tool for downhole use in a tubular string from the surface, comprising: a body having at least one inlet and outlet; a screen in a passage between said inlet and outlet to prevent debris from passing through the tool; a sensor to detect the weight or volume or rate of change of debris, captured in said body; a signal transmitter to transmit a signal responsive to the weight, volume or rate of change of debris, measured by said sensor, said signal comprising changing said pressure in a portion of said body that is in fluid communication with said string in a predetermined pattern to create a mud pulse signal interpretable into a surface reading of weight or volume or rate of change of debris; a port in said body in fluid communication with the string and aligned with said outlet, said aligned port and outlet spanning a portion of said passage that leads from a clean side of said screen where debris has been screened out to said outlet; and a valve member on at least one of said port and said outlet, said valve member movable in response to said sensor.

DETAILED DESCRIPTION OF THE DRAWINGS

[0008] Figure 1 is a section view of a prior art junk basket that uses an eductor to capture cuttings within;

[0009] Figure 2 shows how the junk basket of Figure 1 is modified to sense flow;

[0010] Figure 3 shows how the flow meter is operably connected to a movable sleeve shown in the Figure in its normal fully open position;

[0011] Figure 4 shows that a low flow condition causes the motor to move the sleeve to cover a port to give a pulse signal or a simple pressure spike signal to the surface;

[0012] Figure 5 shows a mud pulser assembly as the signaling to the surface of the flow through the tool measured in real time;

[0013] Figure 6 is an alternative to Figure 5 where a system of wireless communicators allows surface personnel to know the flow through the tool in real time;

[0014] Figure 7 shows an embedded electrical pathway as the way the flow is communicated to the surface in real time;

[0015] Figure 8 shows a combination of a pulser and an outlet valve to signal flow to the surface and to reverse flow the screen in an effort to resolve the problem;

[0016] Figure 9 is a view of the sleeve **54'** shown in Figure 8.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

[0017] The junk basket **12** of Figure 1 is modified as shown in Figures 2-4. A flow sensor **40** receives flow that has passed through the screen **34** leaving the cuttings outside the screen. After passing through the flow sensor that is designed to sense the flow while creating minimal additional pressure drop the flow goes through a crossover **42** and into annulus **44** within the tool **12**. Located above the crossover **42** is a battery pack and motor generally referred to as **46**. Figure 3 shows the entire flow regime. The fluid passes first through screen **34** with the cleaner fluid then passing through the flow sensor. Next the flow goes through the crossover and into annulus **44** inside the tool **12** while bypassing the battery pack and motor **46**. Passage **10** is illustrated at the left side of Figure 3. The eductor **14** comprises aligned and preferably inclined openings **46** and **48**. Normally pressurized flow from the surface enters passage **10** and rushes out through aligned ports **48** and **50**. That rushing flow reduces the pressure in annulus **44** and draws fluid through the screen **34**. In the preferred embodiment, the battery pack and motor are connected to a gear drive **52** that can selectively drive a movable sleeve **54** over ports **48**. Modulating sleeve **54** with respect to ports **48** using motor **46** and gear drive **52** sends a pressure pulse signal to the surface to indicate flow in near real time. Note that another sleeve **54'** can be constructed to block ports **50** as shown in Figures 3 and 8. It can reciprocate as shown in Figure 3 or rotate, as shown in Figure 8 using a spline or hex drive **69**, for example, shown in Figure 9. In that embodiment with pressure continuing from the surface at ports **48** any pressure buildup will first tend to reverse flow the screen **34** and the flow would go out the lower end **20**. The motor **46** can include a downhole processor that upon sensing a low flow will not only signal that condition to the surface through movement of sleeve **54** but will also try closing sleeve **54'** to create the aforementioned reverse flow through the screen **34** by closing valve **54'**.

[0018] With sleeve **54'** on ports **50**, closing of the ports **50** responsive to a sensed low flow will result in a reverse flow measured at sensor **40**. An electronic pulse generator mounted above eductor **14** can then be signaled by sensor **40**, now measuring a reverse flow, to send pulses to the surface to be interpreted there as an indication of reverse flow. A reverse flow signal indicates to surface personnel that the screen **34** has been cleared in a reverse direction and therefore should be operated again in the normal direction by opening valve **54'** using a surface signal or the processor associated with motor **46**. The operator can pick up and cut the pump off to reset the system and then kick the pump back on and set down weight to see if a positive direction flow is established.

[0019] When a low flow is sensed at flow sensor **40** the motor **46** runs and the sleeve **54** is driven over the ports **48** as shown in Figure 4. These Figures show two types of signals to the surface to warn of a low flow condition within the tool **12**. Depending on the speed of the sleeve **54** and whether or not it is programmed to reverse direction, the surface signal can be a rapid pressure buildup or it can be pulses through the well fluids picked up by a surface sensor and converted into a flow reading. If the sleeve simply moves to cover the ports **48** and a positive displacement pump is used at the surface, it will simply build up pressure at the surface. Upon seeing that, surface personnel will turn the pump off with the hope that the cuttings on the screen **34** or in the ports in the mill will simply fall into the annular catch region **38** or further downhole, respectively. At the same time as cutting off the surface pump, the operator can lift the mill to stop the milling process. The string can be rotated with the mill lifted to help cuttings come off the mill or settle down into the catch region **38**. After doing that the operator can resume pumping and look for feedback in the sensed flow transmitted to the surface as mud pulses and converted to flow readings by surface equipment. If flows resumes to normal levels after a system reset that pulls the sleeve **54** off of openings **48**, the milling can resume. If normal flow rates are not detected at flow meter **40** and the ports **48** continue to be obstructed, the operator will again see higher pressures than normal at the pump on the surface. This will tell the operator to pull the string out of the hole to see what the problem may be. Ideally, the flow rate through the tool **12** for carrying the cuttings to the screen is preferred to be in the order of about 150 feet per minute and this can realized with a flow from the surface of about 4-8 barrels a minute. At that flow rate from the surface the total flow rate through ports **50** is about twice the pump rate from the surface.

[0020] Apart from a pressure surge that can be seen at the surface from sleeve movement covering ports **48**, the sleeve **54** can be cycled over and then away from ports **48** to create a pattern of pressure pulses in the string going to the surface. A sensor can be placed on the string near the surface and the pulses can be converted into a visual and/audible signal that there is a flow problem downhole using currently available mud pulse technology.

[0021] Referring to Figures 3 and 4, the gear drive **52** can be a ball screw or a thread whose rotation results in translation of the sleeve **54** since sleeve **54** is constrained from rotating by pin **56** in groove **58**.

[0022] Signals of low flow can be communicated to the surface by wire in a variety of known techniques one of which is drill pipe telemetry **55** offered by IntelliServe a joint venture corporation of Grant Prideco and Novatek and shown schematically in Figure 7. Alternatively electromagnetic signals can be wirelessly sent to the surface to communicate the flow conditions downhole as shown schematically in item **57** in Figure 6. The flow sensing can be directly coupled to a signaling device. For example if the flow sensor is a prop mounted on a ball screw and acted on by a spring bias. The flow through the prop can push it against the spring bias and hold the ports **48** for the eductor **14** in the open position. If the flow slows or stops, the biasing member can back the prop assembly on the ball screw mount. The sleeve **54** can move in tandem with the prop on the ball screw mount so that a slowdown in flow closes openings **48** to give a surface signal as described above.

[0023] Figure 5 shows a pulser **59** in the form of a reciprocating valve member **61** that is operated to go on and off a seat **63** in response to a sensed flow as discussed before. In this embodiment a sliding sleeve such as **54** is not used because the pulser **59** is there. However, a sleeve **54'** can still be used to create a reverse flow to attempt to clear the screen, as discussed above.

[0024] Other indicators of potential problems can be the volume of cuttings being accumulated in the catch annular space **38** or their weight or the rate of change of either variable. A sensor **60** to detect the cuttings level or rate of change per unit time can be mounted near the screen **34** or in the space **38** to sense the level and trigger the same signal mechanism to alert surface personnel to pull out of the hole. Similarly, the annular space **38** can have a receptacle mounted on a weight sensor so that the accumulated weight or its rate of change can be detected. Signals can be sent if the weight increases to a predetermined amount or fails to change a predetermined amount over a predetermined time period. In either case the operator may know that the expected amount of debris has been collected or for some reason no debris is being collected. Signals such as mud pulses can differ depending on the condition sensed. The level or weight indication can be used alone or together with the flow sensing. If both are used one can back up the other because a high collected debris condition can also lead to flow reduction through the tool. In that sense, the reading of one can validate the other. Alternatively the reading of one can be a backup to the other if there is a failure in one of the systems.

[0025] The above description is illustrative of the preferred embodiment and many modifications may be made by those skilled in the art without departing from the invention whose scope is to be determined from the literal and equivalent scope of the claims below:

What is claimed is:

1. A milling debris catching tool for downhole use in a tubular string from the surface, comprising:

a mill adapted to pass a predetermined fluid flow rate to remove cuttings from a milled object;

a tool body having at least one inlet and outlet and a milling debris receptacle;

a screen in a passage between said inlet and outlet to accept debris laden fluid and to prevent milling debris from passing through the tool so that it can be retained in said receptacle; and

a sensor to detect how flow through said screen from said inlet to said outlet compares to the predetermined rate, said sensor operably connected to a valve member in said tool and selectively reconfiguring said passage for flow from said outlet to said inlet in an effort to unclog said screen if flow from said inlet to said outlet through said screen is below said predetermined rate.

2. The tool of claim 1, comprising:

a signal transmitter to transmit a signal responsive to the sensed flow from said sensor.

3. The tool of claim 2, wherein:

said signal comprises changing the pressure in a portion of said body that is in fluid communication with the string which is interpretable as an indication of low flow through said body.

4. The tool of claim 3, further comprising:

a port in said body in fluid communication with the string and aligned with said outlet, said aligned port and outlet spanning a portion of said passage that leads from a clean side of said screen where debris has been screened out to said outlet.

5. The tool of claim 4, wherein:

said valve member comprises a sleeve to selectively block said port, said sleeve driven by a motor responsive to said sensor.

6. The tool of claim 4, wherein:

said valve member comprises a sleeve to selectively block said outlet aligned with said port while still allowing flow through it, whereupon flow in said spanned portion of said passage can reverse back to said screen.

7. The tool of claim 6, wherein:

said sensor measures reverse flow when said sleeve selectively closes, said body further comprising a pulse generator responsive to a reverse flow measurement in said sensor to send a pulse signal related to the reverse flow rate measured.

8. The tool of claim 5, wherein:

movement of said sleeve with respect to said port creates a pulse signal indicative of the measured flow rate by said sensor.

9. The tool of claim 5, wherein:

movement of said sleeve with respect to said port creates a pressure spike in said body as a surface signal that sensed flow is low.

10. The tool of claim 2, wherein:

said signal comprises changing said pressure in a portion of said body that is in fluid communication with said string in a predetermined pattern to create a mud pulse signal interpretable into a surface flow reading.

11. The tool of claim 2, wherein:

said signal comprises an electrical signal and further comprising a conduit for said signal extending from said body to the surface.

12. The tool of claim 2, wherein:

said signal is at least one of an electromagnetic signal and a radio wave.

13. The tool of claim 2, further comprising:

a second sensor in said body to detect one of the volume and weight of the debris captured in said body; and

said signal transmitter transmitting a signal from said body responsive to the volume or weight of debris retained in said body or the rate of change thereof.

14. The tool of claim 13, wherein:

said second sensor comprises one of a proximity sensor and a weight sensor.

15. A debris catching tool for downhole use in a tubular string from the surface, comprising:

a body having at least one inlet and outlet;

a screen in a passage between said inlet and outlet to prevent debris from passing through the tool;

a sensor to detect the weight or volume or rate of change of debris, captured in said body;

a signal transmitter to transmit a signal responsive to the weight, volume or rate of change of debris, measured by said sensor, said signal comprising changing said pressure in a portion of said body that is in fluid communication with said string in a predetermined pattern to create a mud pulse signal interpretable into a surface reading of weight or volume or rate of change of debris;

a port in said body in fluid communication with the string and aligned with said outlet, said aligned port and outlet spanning a portion of said passage that leads from a clean side of said screen where debris has been screened out to said outlet; and

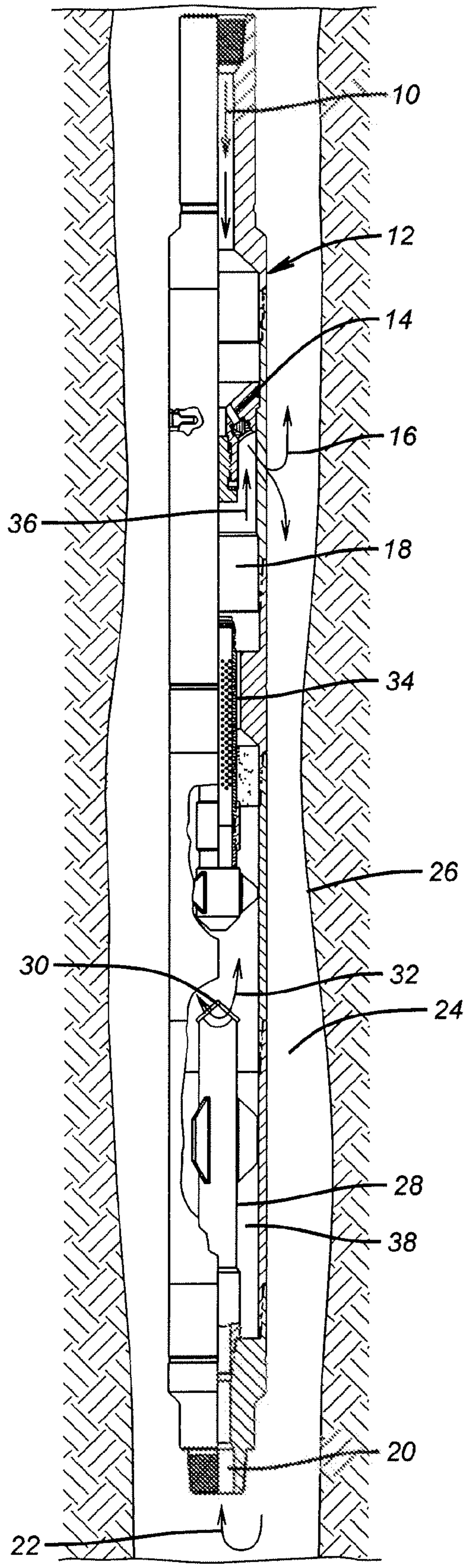
a valve member on at least one of said port and said outlet, said valve member movable in response to said sensor.

16. The tool of claim 15, wherein:

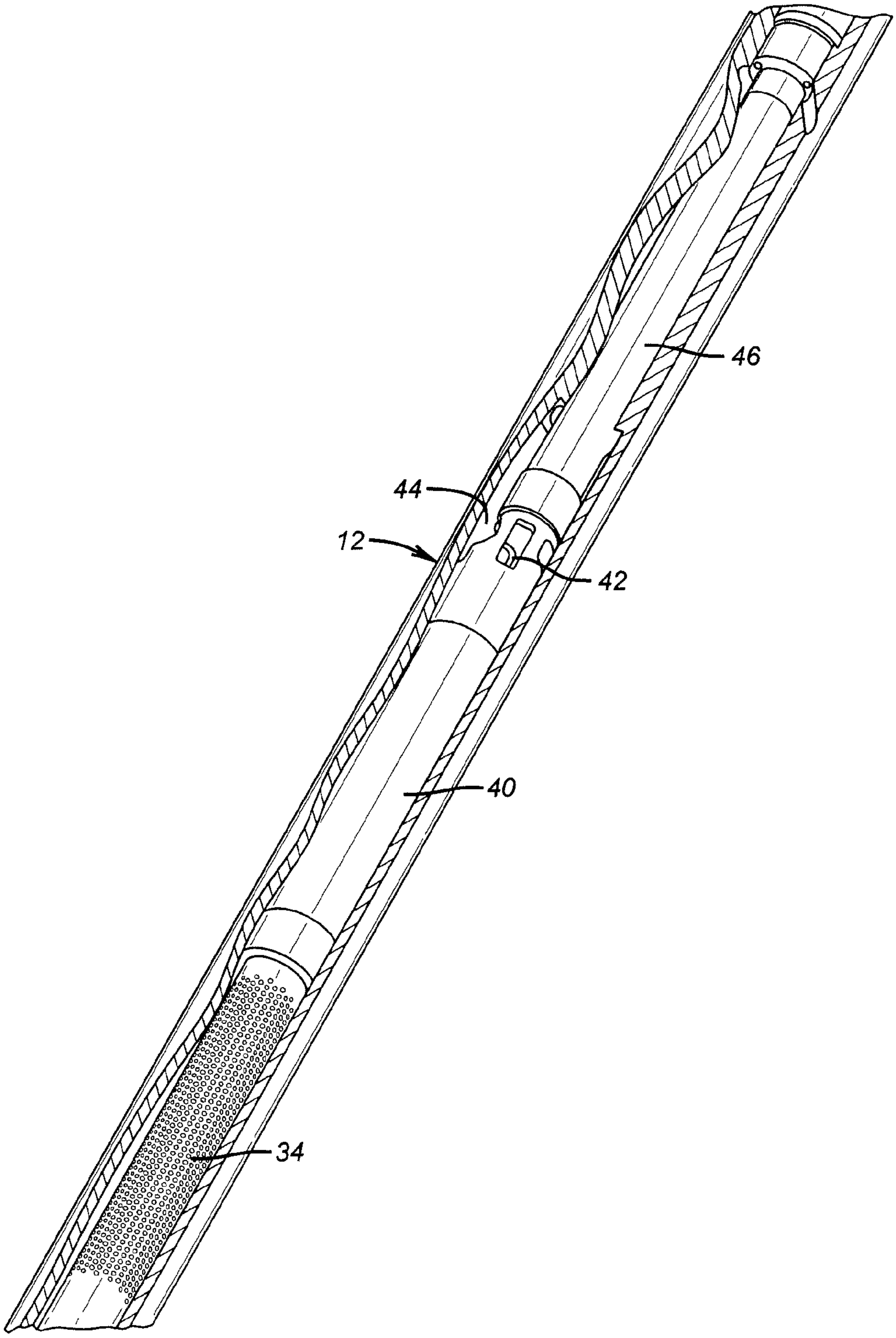
said valve member comprises a sleeve to selectively block said port, said sleeve driven by a motor responsive to said sensor.

17. The tool of claim 15, wherein:

said valve member comprises a sleeve to selectively block said outlet, said outlet, when closed, allowing reverse flow through said screen.



(PRIOR ART)
FIG. 1



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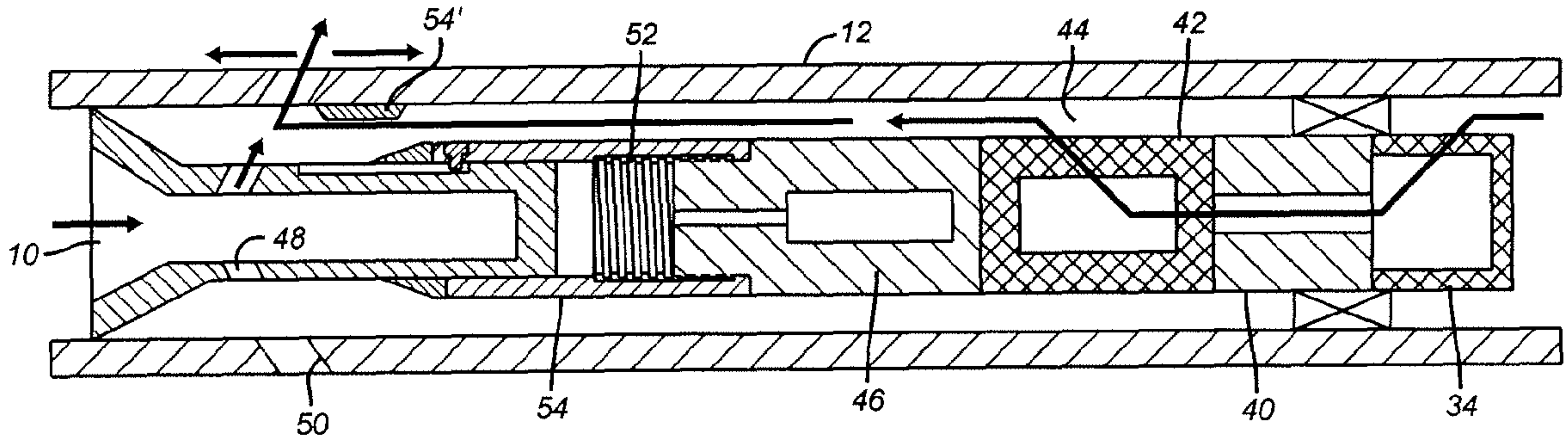


FIG. 3

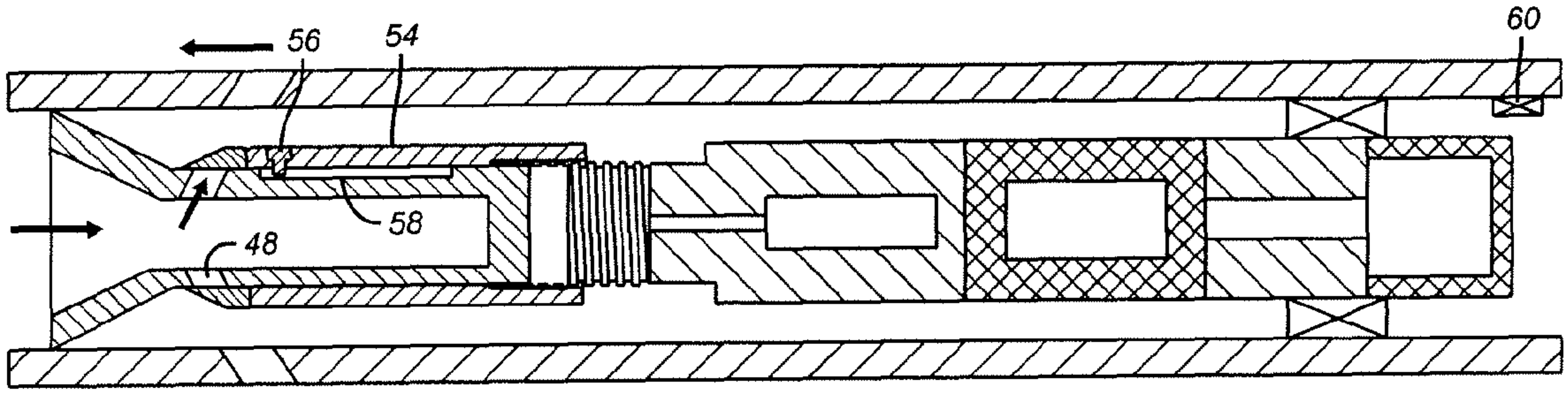


FIG. 4

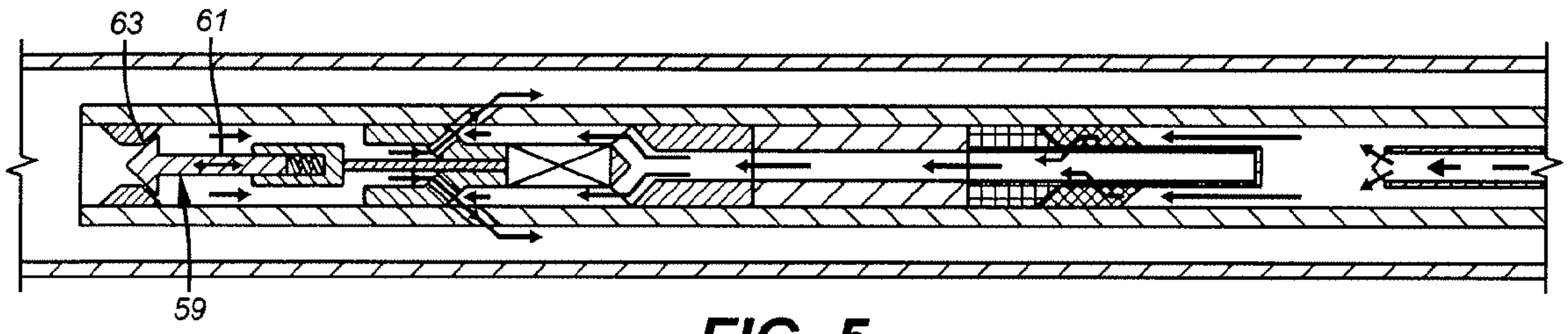


FIG. 5

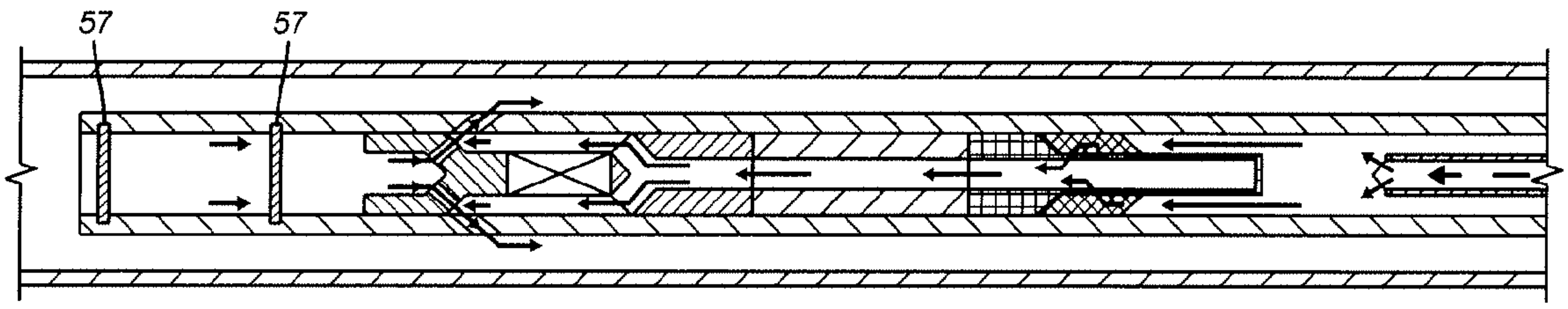


FIG. 6

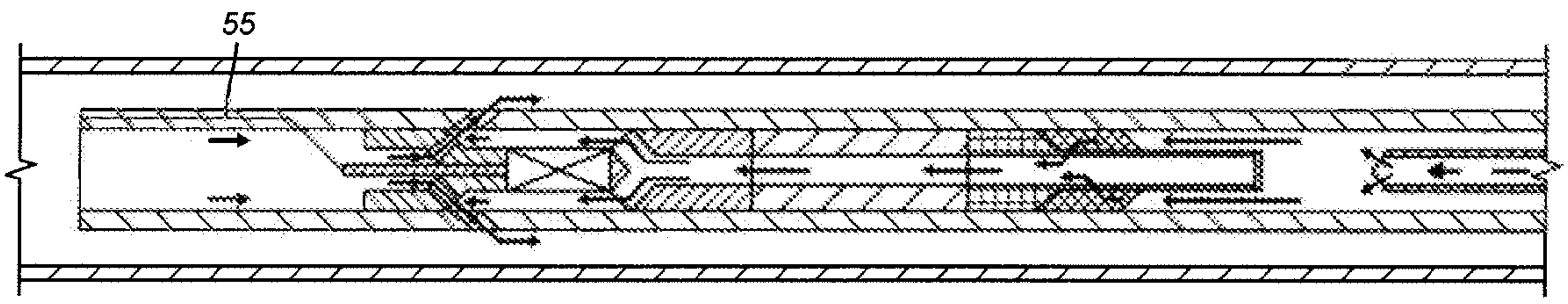


FIG. 7

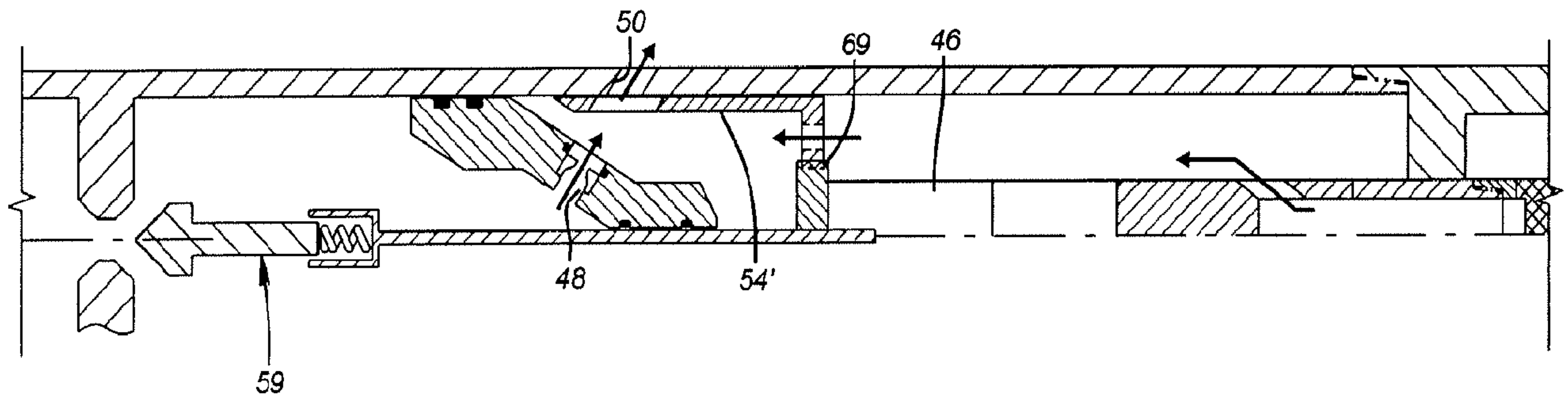


FIG. 8

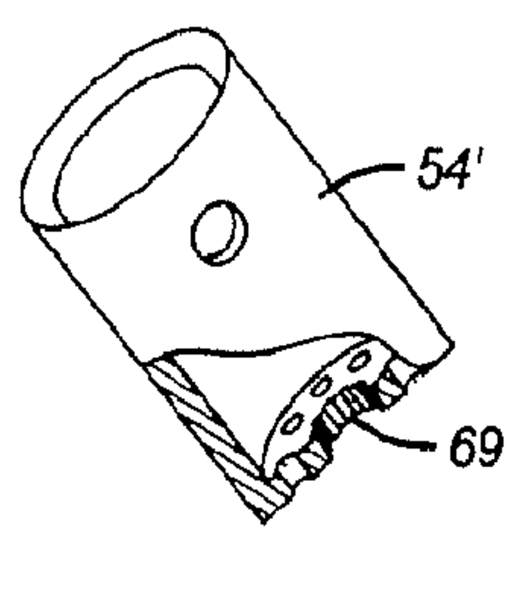
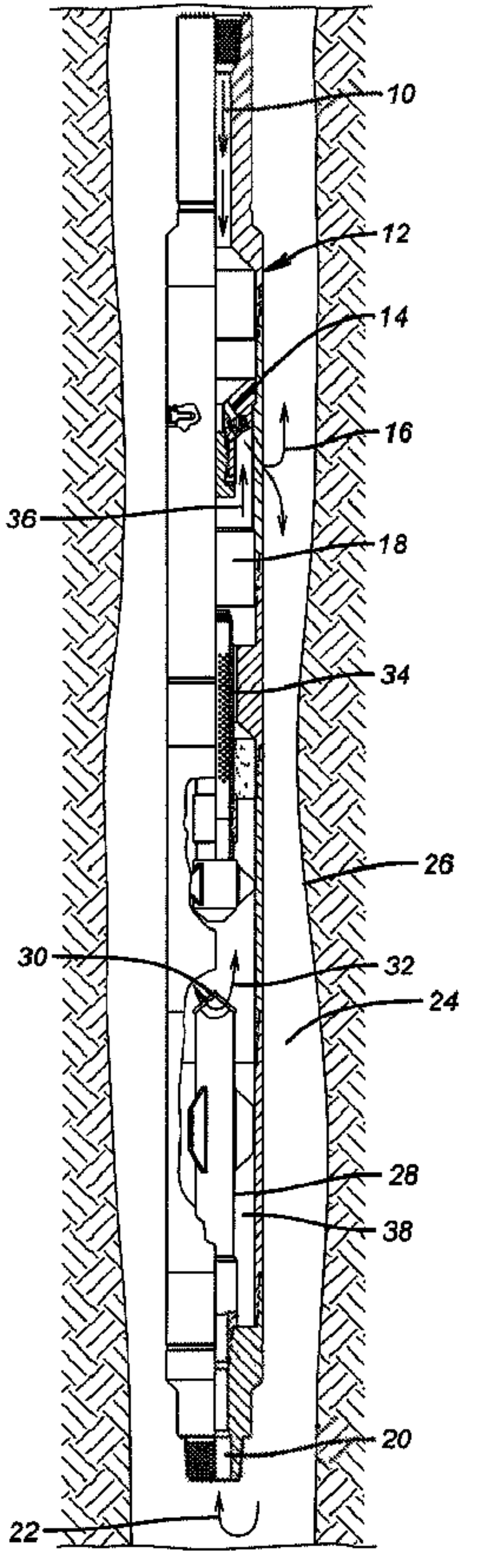


FIG. 9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