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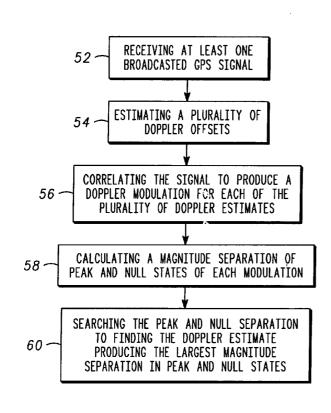
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(54) Title: OSCILLATOR FREQUENCY CORRECTION IN GPS SIGNAL ACQUISITION



(57) Abstract: A method (50) for correcting oscillator frequency error in GPS signal acquisition includes a first step (52) of receiving at least one broadcasted GPS signal. A next step (54) includes estimating a plurality of Doppler offsets. A next step (56) includes correlating the signal to produce a Doppler modulation for each of the plurality of Doppler estimates. A next step (58) includes calculating a magnitude separation of peak and null states of each modulation. A next step (60) includes searching the peak and null separation to finding the Doppler estimate producing the largest magnitude separation in peak and null states. The found Doppler estimate defines a frequency error estimate for the at least one broadcasted GPS signal, which will be common across all satellites.

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B. FIELDS SEARCHED				
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C. DOCUMENTS CONSIDERED TO BE RELEVANT				
Category *	Citation of document, with indication, where appropriate, of the relevant passages			Relevant to claim No.
Α	US 6,133,873 A (KRASNER) 17 October 2000 (17	ER) 17 October 2000 (17.10.2000), see Figures 5 and 6.		
Α	US 6,005,889 A (CHUNG et al) 21 December 1999 (21.12.1999), see col. 3, lines 55-67, Figures 3 and 4.			1-10
Α	US 5,943,606 A (KREMM et al) 24 August 1999 (24.08.1999), see entire document.			1-10
A	US 5,798,732 A (ESHENBACH) 25 August 1998 (25.08.1998), see col. 7, line 35 - col.			1-10
Α	10, line 14. US 4,578,678 A (HURD) 25 March 1986 (25.03.1986), see Figures 3 and 4			1-10
Further	documents are listed in the continuation of Box C.		See patent family annex.	
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