

(12) INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(19) World Intellectual Property Organization  
International Bureau



(43) International Publication Date  
14 October 2010 (14.10.2010)

(10) International Publication Number  
WO 2010/117632 A1

(51) International Patent Classification:

A61B 8/12 (2006.01)

(74) Agent: BLACK, Bruce, E.; FROMMER LAWRENCE & HAUG LLP, 745 Fifth Avenue, New York, NY 10151 (US).

(21) International Application Number:

PCT/US2010/028442

(81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM, AO, AT, AU, AZ, BA, BB, BG, BH, BR, BW, BY, BZ, CA, CH, CL, CN, CO, CR, CU, CZ, DE, DK, DM, DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IS, JP, KE, KG, KM, KN, KP, KR, KZ, LA, LC, LK, LR, LS, LT, LU, LY, MA, MD, ME, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PE, PG, PH, PL, PT, RO, RS, RU, SC, SD, SE, SG, SK, SL, SM, ST, SV, SY, TH, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.

(22) International Filing Date:

24 March 2010 (24.03.2010)

(25) Filing Language:

English

(26) Publication Language:

English

(30) Priority Data:

12/415,807 31 March 2009 (31.03.2009) US

(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LR, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European (AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV, MC, MK, MT, NL, NO, PL, PT, RO, SE, SI, SK, SM,

(71) Applicant (for all designated States except US):  
BOSTON SCIENTIFIC SCIMED, INC. [US/US]; One Scimed Place, Maple Grove, MN 55311 (US).

(72) Inventor; and

(75) Inventor/Applicant (for US only): KNIGHT, Jon, M. [US/US]; 3372 Sagewood Ct., Pleasanton, CA 94588 (US).

[Continued on next page]

(54) Title: SYSTEMS AND METHODS FOR MAKING AND USING INTRAVASCULAR IMAGING SYSTEMS WITH MULTIPLE PULLBACK RATES

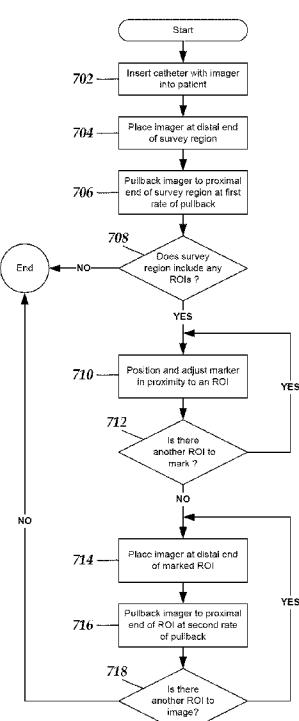


Fig. 7

(57) Abstract: A method of performing an intravascular imaging procedure includes inserting an imager at a first end of a survey region of patient vasculature to be imaged. The survey region is imaged to obtain a set of first images while pulling back the imager from the first end of the survey region to a second end of the survey region opposite the first end. The imager is pulled back at a first linear rate of pullback. The imager is positioned at a first end of a region of interest determined within the survey region. The region of interest is imaged to obtain a set of second images. The region of interest is imaged while pulling back the imager at a second linear rate of pullback that is less than the first linear rate of pullback. At least a portion of the set of second images is displayed.



TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, —

*before the expiration of the time limit for amending the claims and to be republished in the event of receipt of amendments (Rule 48.2(h))*

**Published:**

— *with international search report (Art. 21(3))*

SYSTEMS AND METHODS FOR MAKING AND USING  
IMAGING SYSTEMS WITH MULTIPLE PULLBACK RATES

CROSS REFERENCE TO RELATED APPLICATION

5 This application claims priority to United States Patent Application No. 12/415,807, filed March 31, 2009; the entire contents of which are incorporated herein by reference.

TECHNICAL FIELD

10 The present invention is directed to the area of intravascular imaging systems. The present invention is also directed to intravascular imaging systems configured and arranged to perform an intravascular imaging procedure using multiple linear rates of pullback, as well as methods of making and using the intravascular systems.

BACKGROUND

15 Intravascular ultrasound (“IVUS”) imaging systems have proven diagnostic capabilities for a variety of diseases and disorders. For example, IVUS imaging systems have been used as an imaging modality for diagnosing blocked blood vessels and providing information to aid medical practitioners in selecting and placing stents and other devices to restore or increase blood flow. IVUS imaging systems have been used to diagnose 20 atheromatous plaque build-up at particular locations within blood vessels. IVUS imaging systems can be used to determine the existence of an intravascular obstruction or stenosis, as well as the nature and degree of the obstruction or stenosis. IVUS imaging systems can be used to visualize segments of a vascular system that may be difficult to visualize using other intravascular imaging techniques, such as angiography, due to, for example, movement (*e.g.*, a beating heart) or obstruction by one or more structures (*e.g.*, one or more blood vessels not desired to be imaged). IVUS imaging systems can be used to monitor or assess ongoing 25 intravascular treatments, such as angiography and stent placement in real (or almost real) time. Moreover, IVUS imaging systems can be used to monitor one or more heart chambers.

30 IVUS imaging systems have been developed to provide a diagnostic tool for visualizing a variety of diseases or disorders. An IVUS imaging system can include a control module (with a pulse generator, an image processor, and a monitor), a catheter, and one or more transducers disposed in the catheter. The transducer-containing catheter can be positioned in a lumen or cavity within, or in proximity to, a region to be imaged, such as a

blood vessel wall or patient tissue in proximity to a blood vessel v  
the control module generates electrical pulses that are delivered to the one or more  
transducers and transformed to acoustic pulses that are transmitted through patient tissue.  
Reflected pulses of the transmitted acoustic pulses are absorbed by the one or more  
5 transducers and transformed to electric pulses. The transformed electric pulses are delivered  
to the image processor and converted to an image displayable on the monitor.

Optical Coherence Tomography (“OCT”) is another imaging modality with proven  
capabilities for use in diagnosing intravascular diseases and disorders. OCT uses optical  
signals to image patient tissue. Optical signals emitted from a an OCT system are reflected  
10 from patient tissue and collected and processed by the OCT system to form an image.

#### BRIEF SUMMARY

In one embodiment, a method of performing an intravascular imaging procedure  
includes inserting a catheter of an intravascular imaging system into patient vasculature such  
15 that an imager disposed in the catheter is positioned at a first end of a survey region of the  
patient vasculature to be imaged. The imager is coupled to a control module. The survey  
region is imaged to obtain a set of first images while pulling back the imager from the first  
end of the survey region to a second end of the survey region opposite the first end. The  
imager is pulled back at a first linear rate of pullback. A region of interest is determined  
20 within the survey region using at least a portion of the set of first images of the survey region.  
The imager is positioned at a first end of the region of interest. The region of interest is  
imaged to obtain a set of second images while pulling back the imager from the first end of  
the region of interest to a second end of the region of interest opposite the first end. The  
imager is pulled back at a second linear rate of pullback that is less than the first linear rate of  
25 pullback. At least a portion of the set of second images is displayed.

In another embodiment, a computer-readable medium includes processor-executable  
instructions for imaging tissue. The processor-executable instructions, when installed onto a  
device, enable the device to perform actions. The actions include imaging a survey region of  
30 patient vasculature with an intravascular imager to obtain a set of first images while pulling  
back the imager from the first end of the survey region to a second end of the survey region  
opposite the first end at a first linear rate of pullback. The actions also include imaging a

region of interest identified within the survey region to obtain a pulling back the imager from a first end of the region of interest to a second end of the region of interest opposite the first end. During imaging of the region of interest, the imager is pulled back at a second linear rate of pullback that is less than the first linear rate of pullback.

5 The actions also include displaying at least a portion of the set of second images.

In yet another embodiment, an intravascular imager includes at least one imager disposed in a catheter that is insertable into patient vasculature. The at least one imager is coupled to a control module. The intravascular imager also includes a processor disposed in the control module. The processor is for executing processor-readable instructions that enable actions. The actions include imaging a survey region of patient vasculature to obtain a set of first images while pulling back the imager from the first end of the survey region to a second end of the survey region opposite the first end at a first linear rate of pullback. The actions also include imaging a region of interest identified within the survey region to obtain a set of second images while pulling back the imager from a first end of the region of interest to a second end of the region of interest opposite the first end. During imaging of the region of interest, the imager is pulled back at a second linear rate of pullback that is less than the first linear rate of pullback. The actions also include displaying at least a portion of the set of second images.

20

#### BRIEF DESCRIPTION OF THE DRAWINGS

Non-limiting and non-exhaustive embodiments of the present invention are described with reference to the following drawings. In the drawings, like reference numerals refer to like parts throughout the various figures unless otherwise specified.

25 For a better understanding of the present invention, reference will be made to the following Detailed Description, which is to be read in association with the accompanying drawings, wherein:

FIG. 1 is a schematic view of one embodiment of an intravascular ultrasound imaging system, according to the invention;

30 FIG. 2 is a schematic side view of one embodiment of a catheter of an intravascular ultrasound imaging system, according to the invention;

FIG. 3 is a schematic perspective view of one embodiment of a catheter shown in FIG. 2 with an imaging core disposed in a lumen defined in the catheter, according to the invention;

5 FIG. 4 is a schematic longitudinal cross-sectional view of one embodiment of a portion of a catheter extending along a portion of a patient blood vessel having a plaque in a wall of the blood vessel, according to the invention;

FIG. 5A is a schematic representation of one embodiment of a set of images formed from a survey pullback of an imaging procedure, a marker in proximity to some of the images marks a region of interest contained on those images, according to the invention;

10 FIG. 5B is a schematic representation of one embodiment of a set of images formed from a survey pullback of an imaging procedure, markers in proximity to some of the images mark the end points of a region of interest contained on those images, according to the invention;

15 FIG. 6 is a schematic representation of one embodiment of the set of images formed from the survey pullback of FIG. 5A, another set of images formed from an inspection pullback is formed along the region of interest of FIG. 5A, according to the invention; and

FIG. 7 is a flow diagram showing one exemplary embodiment of an imaging procedure using an intravascular imaging system with multiple pullback rates, according to the invention.

20 DETAILED DESCRIPTION

The present invention is directed to the area of intravascular imaging systems. The present invention is also directed to intravascular imaging systems configured and arranged to perform an intravascular imaging procedure using multiple linear rates of pullback, as well as methods of making and using the intravascular ultrasound systems.

25 The methods, systems, and devices described herein may be embodied in many different forms and should not be construed as limited to the embodiments set forth herein. Accordingly, the methods, systems, and devices described herein may take the form of an entirely hardware embodiment, an entirely software embodiment or an embodiment combining software and hardware aspects. The methods described herein can be performed

using any type of computing device, such as a computer, that is a combination of computing devices where each device performs at least part of the process.

Suitable computing devices typically include mass memory and typically include communication between devices. The mass memory illustrates a type of computer-readable media, namely computer storage media. Computer storage media may include volatile, nonvolatile, removable, and non-removable media implemented in any method or technology for storage of information, such as computer readable instructions, data structures, program modules, or other data. Examples of computer storage media include RAM, ROM, EEPROM, flash memory, or other memory technology, CD-ROM, digital versatile disks (DVD) or other optical storage, magnetic cassettes, magnetic tape, magnetic disk storage or other magnetic storage devices, or any other medium which can be used to store the desired information and which can be accessed by a computing device.

Methods of communication between devices or components of a system can include both wired and wireless (e.g., RF, optical, or infrared) communications methods and such methods provide another type of computer readable media; namely communication media. Communication media typically embodies computer-readable instructions, data structures, program modules, or other data in a modulated data signal such as a carrier wave, data signal, or other transport mechanism and include any information delivery media. The terms “modulated data signal,” and “carrier-wave signal” includes a signal that has one or more of its characteristics set or changed in such a manner as to encode information, instructions, data, and the like, in the signal. By way of example, communication media includes wired media such as twisted pair, coaxial cable, fiber optics, wave guides, and other wired media and wireless media such as acoustic, RF, infrared, and other wireless media.

Suitable intravascular ultrasound (“IVUS”) imaging systems include, but are not limited to, one or more transducers disposed on a distal end of a catheter configured and arranged for percutaneous insertion into a patient. Examples of IVUS imaging systems with catheters are found in, for example, U.S. Patents Nos. 7,306,561; and 6,945,938; as well as U.S. Patent Application Publication Nos. 20060253028; 20070016054; 20070038111; 20060173350; and 20060100522, all of which are incorporated by reference.

Figure 1 illustrates schematically one embodiment of an IVUS imaging system 100. The IVUS imaging system 100 includes a catheter 102 that is coupleable to a control module

104. The control module 104 may include, for example, a processor 108, a motor 110, and one or more displays 112. In at least some embodiments, the pulse generator 108 forms electric pulses that may be input to one or more transducers (312 in Figure 3) disposed in the catheter 102. In at least some embodiments, mechanical energy 5 from the motor 110 may be used to drive an imaging core (306 in Figure 3) disposed in the catheter 102. In at least some embodiments, electric pulses transmitted from the one or more transducers (312 in Figure 3) may be input to the processor 106 for processing. In at least some embodiments, the processed electric pulses from the one or more transducers (312 in Figure 3) may be displayed as one or more images on the one or more displays 112. In at 10 least some embodiments, the processor 106 may also be used to control the functioning of one or more of the other components of the control module 104. For example, the processor 106 may be used to control at least one of the frequency or duration of the electrical pulses transmitted from the pulse generator 108, the rotation rate of the imaging core (306 in Figure 3) by the motor 110, the velocity or length of the pullback of the imaging core (306 in Figure 15 3) by the motor 110, or one or more properties of one or more images formed on the one or more displays 112.

Figure 2 is a schematic side view of one embodiment of the catheter 102 of the IVUS imaging system (100 in Figure 1). The catheter 102 includes an elongated member 202 and a hub 204. The elongated member 202 includes a proximal end 206 and a distal end 208. In 20 Figure 2, the proximal end 206 of the elongated member 202 is coupled to the catheter hub 204 and the distal end 208 of the elongated member is configured and arranged for percutaneous insertion into a patient. In at least some embodiments, the catheter 102 defines at least one flush port, such as flush port 210. In at least some embodiments, the flush port 210 is defined in the hub 204. In at least some embodiments, the catheter 102 does not use a 25 flush port 204. In at least some embodiments, the hub 204 is configured and arranged to couple to the control module (104 in Figure 1). In some embodiments, the elongated member 202 and the hub 204 are formed as a unitary body. In other embodiments, the elongated member 202 and the catheter hub 204 are formed separately and subsequently assembled together.

30 Figure 3 is a schematic perspective view of one embodiment of the distal end 208 of the elongated member 202 of the catheter 102. The elongated member 202 includes a sheath

302 and a lumen 304. An imaging core 306 is disposed in the lumen 302. The imaging core 306 includes an imaging device 308 coupled to a distal end of a rotatable driveshaft 310.

The sheath 302 may be formed from any flexible, biocompatible material suitable for insertion into a patient. Examples of suitable materials include, for example, polyethylene, polyurethane, plastic, spiral-cut stainless steel, nitinol hypotube, and the like or combinations thereof.

One or more transducers 312 may be mounted to the imaging device 308 and employed to transmit and receive acoustic pulses. In a preferred embodiment (as shown in Figure 3), an array of transducers 312 are mounted to the imaging device 308. In other embodiments, a single transducer may be employed. In yet other embodiments, multiple transducers in an irregular-array may be employed. Any number of transducers 312 can be used. For example, there can be two, three, four, five, six, seven, eight, nine, ten, twelve, fifteen, sixteen, twenty, twenty-five, fifty, one hundred, five hundred, one thousand, or more transducers. As will be recognized, other numbers of transducers may also be used. In at least some embodiments, the one or more transducers 312 are configured into an annular arrangement. In at least some embodiments, the one or more transducers 312 are fixed in place and do not rotate.

The one or more transducers 312 may be formed from one or more known materials capable of transforming applied electrical pulses to pressure distortions on the surface of the one or more transducers 312, and vice versa. Examples of suitable materials include piezoelectric ceramic materials, piezocomposite materials, piezoelectric plastics, barium titanates, lead zirconate titanates, lead metaniobates, polyvinylidenefluorides, and the like. Other transducer technologies include composite materials, single-crystal composites, and semiconductor devices (e.g., capacitive micromachined ultrasound transducers (“cMUT”), piezoelectric micromachined ultrasound transducers (“pMUT”), or the like)

The pressure distortions on the surface of the one or more transducers 312 form acoustic pulses of a frequency based on the resonant frequencies of the one or more transducers 312. The resonant frequencies of the one or more transducers 312 may be affected by the size, shape, and material used to form the one or more transducers 312. The one or more transducers 312 may be formed in any shape suitable for positioning within the catheter 102 and for propagating acoustic pulses of a desired frequency in one or more

selected directions. For example, transducers may be disc-shaped shaped, oval-shaped, and the like. The one or more transducers may be formed in the desired shape by any process including, for example, dicing, dice and fill, machining, microfabrication, and the like.

5 As an example, each of the one or more transducers 312 may include a layer of piezoelectric material sandwiched between a conductive acoustic lens and a conductive backing material formed from an acoustically absorbent material (e.g., an epoxy substrate with tungsten particles). During operation, the piezoelectric layer may be electrically excited by both the backing material and the acoustic lens to cause the emission of acoustic pulses.

10 In at least some embodiments, the one or more transducers 312 can be used to form a radial cross-sectional image of a surrounding space. Thus, for example, when the one or more transducers 312 are disposed in the catheter 102 and inserted into a blood vessel of a patient, the one or more transducers 312 may be used to form an image of the walls of the blood vessel and tissue surrounding the blood vessel.

15 In at least some embodiments, the imaging core 306 may be rotated about a longitudinal axis of the catheter 102. As the imaging core 306 rotates, the one or more transducers 312 emit acoustic pulses in different radial directions. When an emitted acoustic pulse with sufficient energy encounters one or more medium boundaries, such as one or more tissue boundaries, a portion of the emitted acoustic pulse is reflected back to the emitting 20 transducer as an echo pulse. Each echo pulse that reaches a transducer with sufficient energy to be detected is transformed to an electrical signal in the receiving transducer. The one or more transformed electrical signals are transmitted to the control module (104 in Figure 1) where the processor 106 processes the electrical-signal characteristics to form a displayable image of the imaged region based, at least in part, on a collection of information from each of 25 the acoustic pulses transmitted and the echo pulses received. In at least some embodiments, the rotation of the imaging core 306 is driven by the motor 110 disposed in the control module (104 in Figure 1).

As the one or more transducers 312 rotate about the longitudinal axis of the catheter 102 emitting acoustic pulses, a plurality of images are formed that collectively form a radial 30 cross-sectional image of a portion of the region surrounding the one or more transducers 312, such as the walls of a blood vessel of interest and the tissue surrounding the blood vessel. In

at least some embodiments, the radial cross-sectional image can be displayed 112. In at least some embodiments, the one or more transducers 312 are fixed in place and do not rotate during an imaging procedure. In at least some embodiments, at least one of the imaging core 306 or the one or more transducers 312 are manually rotated.

5 In at least some embodiments, the imaging core 306 may also move longitudinally along the blood vessel within which the catheter 102 is inserted so that a plurality of cross-sectional images may be formed along a longitudinal length of the blood vessel. In at least some embodiments, during an imaging procedure the one or more transducers 312 may be retracted (*i.e.*, pulled back) along the longitudinal length of the catheter 102. In at least some 10 embodiments, the catheter 102 includes at least one telescoping section that can be retracted during pullback of the one or more transducers 312. In at least some embodiments, the motor 110 drives the pullback of the imaging core 306 within the catheter 102. In at least some embodiments, the motor 110 pullback distance of the imaging core is at least 5 cm. In at least some 15 embodiments, the motor 110 pullback distance of the imaging core is at least 10 cm. In at least some embodiments, the motor 110 pullback distance of the imaging core is at least 15 cm. In at least some embodiments, the motor 110 pullback distance of the imaging core is at least 20 cm. In at least some embodiments, the motor 110 pullback distance of the imaging core is at least 25 cm. In at least some embodiments, the entire catheter 102 can be retracted 20 during an imaging procedure either with or without the imaging core 306 moving longitudinally independently of the catheter 102.

In at least some embodiments, when the imaging core 306 is retracted while rotating, the images collectively form a continuous spiral shape along a blood vessel. In at least some embodiments, when the imaging core 306 is retracted while rotating, a stepper motor may be used to pull back the imaging core 306. The stepper motor can pull back the imaging core 306 a short distance and stop long enough for the one or more transducers 306 to capture an image before pulling back the imaging core 306 another short distance and again capturing another image, and so on, either with or without being rotated.

The quality of an image produced at different depths from the one or more transducers 312 may be affected by one or more factors including, for example, bandwidth, transducer focus, beam pattern, as well as the frequency of the acoustic pulse. The frequency of the acoustic pulse output from the one or more transducers 312 may also affect the penetration depth of the acoustic pulse output from the one or more transducers 312. In general, as the 30

frequency of an acoustic pulse is lowered, the depth of the penet within patient tissue increases. In at least some embodiments, the IVUS imaging system 100 operates within a frequency range of 5 MHz to 100 MHz.

5 In at least some embodiments, one or more conductors 314 electrically couple the transducers 312 to the control module 104 (see *e.g.*, Figure 1). In at least some embodiments, the one or more conductors 314 extend along a longitudinal length of the rotatable driveshaft 310.

10 In at least some embodiments, the catheter 102 with one or more transducers 312 mounted to the distal end 208 of the imaging core 308 may be inserted percutaneously into a patient via an accessible blood vessel, such as the femoral artery, at a site remote from the selected portion of the selected region, such as a blood vessel, to be imaged. The catheter 102 may then be advanced through the blood vessels of the patient to the selected imaging site, such as a portion of a selected blood vessel.

15 Intravascular imaging techniques (*e.g.*, IVUS, OCT, or the like) are commonly used to diagnose patient diseases and disorders. Intravascular diseases and disorders may occur either at discrete locations within patient vasculature or be distributed over a larger intravascular region. In at least some embodiments, an imaging procedure includes a pullback of an imager within a catheter along a longitudinal portion of patient vasculature. A set of adjacent images are captured at a particular linear pullback rate along the portion of the 20 vasculature. The images are processed and displayed to a user. As an example, one particular IVUS system captures 30 images per second and has a linear pullback rate in the range of 0.5 mm/sec to 1.0 mm/sec. Thus, a pullback along 10 cm of vasculature takes 100 to 200 seconds and captures 3,000 to 6,000 images. Typically, the majority of the images and the time it takes to capture the images are associated with healthy portions of patient 25 vasculature not significant to the given diagnosis.

Systems and methods of using intravascular imaging systems to assess patient vasculature are described. In at least some embodiments, an imaging procedure includes a survey pullback and an inspection pullback. During the survey pullback, images are captured over a portion of patient vasculature. The locations of one or more regions of interest 30 (“ROI”), such as focal areas, identified during the survey pullback may be subsequently

imaged during the inspection pullback. In at least some embodiments, the ROI 416 is marked prior to the inspection pullback.

During the inspection pullback, marked ROIs are re-located and re-imaged. In at least some embodiments, the survey pullback and the inspection pullback are performed at different linear pullback rates. In at least some embodiments, the linear pullback rate of the survey pullback is greater than the linear pullback rate of the inspection pullback. In at least some embodiments, the amount of time it takes to perform an imaging procedure using a survey pullback and an inspection pullback of a portion of the survey pullback is less than the amount of time it takes to perform an imaging procedure using a single pullback with a conventional intravascular imaging system.

Figure 4 is a schematic longitudinal cross-sectional view of one embodiment of a portion of a catheter 402 extending along a portion of a patient blood vessel 404 having a plaque 406 in a wall of the blood vessel 404. The catheter 402 includes an imager 408 (e.g., imaging core 306 of Figure 3) configured and arranged for imaging a survey region 410 of the blood vessel 404 bounded on a distal end by dashed line 412 and on a proximal end by dashed line 414. In at least some embodiments, the catheter 402 is held in a constant position while the imager 408 images the survey region 410 by pullback of the imager 408 within the catheter 402. In at least some embodiments, the survey region 410 is imaged at a first linear pullback rate.

When, during the pullback of the survey region 410, a ROI 416 (e.g., the plaque 406, or the like) is identified, the imager 408 subsequently images just the ROI 416. In Figure 4, the ROI 416 is shown as the plaque 406 and the region of the blood vessel 404 flanking the plaque 406. The ROI 416 is bounded on a distal end by dotted line 418 and on a proximal end by dotted line 420. In at least some embodiments, the ROI 416 is re-imaged (i.e., inspected) at a second linear rate of pullback that is different from the linear rate of the survey pullback.

The survey pullback captures a set of images of the blood vessel 404. The set of images can be used to locate one or more ROIs for re-imaging at a different linear rate of pullback. The set of images captured during the survey pullback can include any number of images. The widths of the images is determined by the width of the imaging beam of the imager. The adjacent images can be separated from one another by any center-to-center

distance. In at least some embodiments, the center-to-center distances between adjacent images are overlapping. In at least some embodiments, the center-to-center distances are set such that adjacent images are non-overlapping. In some embodiments, the center-to-center distances are set such that all of the imaged length of the blood vessel 404 is imaged. In other embodiments, the center-to-center distances are set such that portions of the blood vessel 404 between adjacent images are not imaged.

Figures 5A-5B are schematic representations of one embodiment of a set of images, such as image 502, formed during a pullback of the survey region 410. In Figures 5A-5B, the images are shown as adjacent cylinders abutting one another. In at least some embodiments, the set of images are processed by the control module (104 in Figure 1). In at least some embodiments, the set of images is displayed on the one or more displays (112 of Figure 1). In other embodiments, the set of images is displayed on another device coupled to the imager (408 in Figure 4). In at least some embodiments, the survey pullback is automatically performed under the control of the control module (104 in Figure 1). In at least some embodiments, the survey pullback is performed by another device coupled to the intravascular imaging system (*e.g.*, the IVUS system 100 in Figure 1).

One or more ROIs may be identified in a variety of different ways. For example, in at least some embodiments, the ROIs are identified using software, such as tissue characterization software. Such software can identify regions containing, for example, normal tissue, necrotic tissue, calcified tissue, lipidic tissue, and fibrotic tissue. Additionally, software can be used to identify heterogeneous tissues (*e.g.*, fibrolipidic tissue, or the like), as well as blood and various forms of thrombus. It will be understood that the above-listed tissues (as well as blood) are merely exemplary. There are many different other possible tissue permutations that can be identified using software.

An ROI may be selected to be a significant amount of non-normal tissue (*e.g.*, lipidic tissue). In at least some embodiments, ROIs are identified manually by a health care provider. For example, a health care provider may look at one or more displayed images captured during the survey pullback of the survey region 410. In some embodiments, software identification and manual identification may both be used.

In some embodiments, when an ROI, such as ROI 416, is identified, the ROI 416 may be marked on a display. In other embodiments, the identified ROI 416 may be marked

internally by software. When the ROI 416 is marked on a c  
positioned on the display of the set of images in proximity to the location of the ROI 416  
(e.g., above the ROI, below the ROI, to the side of the ROI, over top of the ROI). In at least  
some embodiments, the marker 504 is automatically shown on a display by the control  
5 module (104 in Figure 1). In at least some embodiments, the marker 504 is applied to the  
display by a user of an intravascular imaging system. In at least some embodiments, at least  
one of the size or the location of the marker 504 can be adjusted by the user via the control  
module (104 in Figure 1). In at least some embodiments, as shown in Figure 5B, a plurality  
of markers 506 and 508 can be used to mark the ROI 416 in lieu of a single marker (504 in  
10 Figure 5A). In at least some embodiments, the markers 506 and 508 are positioned at the  
distal and proximal ends, respectfully, of the ROI 416.

In at least some embodiments, the survey region 410 is imaged using a linear pullback rate that is greater than the linear pullback rate used while imaging the ROI 416. In at least some embodiments, the survey region 410 is imaged using a linear pullback rate of no less than 2 mm/sec. In at least some embodiments, the survey region 410 is imaged using a linear pullback rate of no less than 5 mm/sec. In at least some embodiments, the survey region 410 is imaged using a linear pullback rate of no less than 10 mm/sec. In at least some embodiments, the survey region 410 is imaged using a linear pullback rate of no less than 15 mm/sec. In at least some embodiments, the survey region 410 is imaged using a linear pullback rate of no less than 20 mm/sec. In at least some embodiments, the survey region 410 is imaged using a linear pullback rate of no less than 30 mm/sec. In at least some embodiments, the survey region 410 is imaged using a linear pullback rate of no less than 40 mm/sec.

Once the ROI 416 is marked, the imager (408 in Figure 4) can be positioned at the distal end of the ROI 416. In some embodiments, the imager is automatically re-positioned at the distal end of the ROI 416, as marked on a display of the set of images of the survey region (410 in Figure 4) by one or more markers. In other embodiments, the imager is manually re-positioned at the distal end of the ROI 416 by a user of an intravascular imaging system. Once the imager is positioned at the distal end of the ROI 416, the imager can perform an inspection pullback from the distal end to the proximal end of the ROI 416. In at least some embodiments, the set of images captured by the inspection pullback include non-overlapping adjacent images. In at least some embodiments, the non-overlapping adjacent

5 images abut one another such that there are no gaps between adjacent embodiments, the adjacent images overlap one another. It may be an advantage to have adjacent images overlay to ensure that there are no gaps between adjacent images and also to allow the control module (104 in Figure 1) to perform one or more image processing algorithms (*e.g.*, correlation, or the like) on the data from the images.

10 Figure 6 is a schematic representation of one embodiment of a set of images, such as image 602, formed from an inspection pullback along the ROI 416. In Figure 6, the set of overlapping images from the inspection pullback is overlaid onto the set of images, such as image 502, formed during the survey pullback of Figure 5A. In Figure 6, the center-to-center distance between adjacent images captured during the inspection pullback is less than the center-to-center distance between adjacent images captured during the survey pullback.

15 In at least some embodiments, the survey pullback is automatically performed under the control of the control module (104 in Figure 1). In at least some embodiments, the inspection pullback is performed by another device coupled to the intravascular imaging system (*e.g.*, the IVUS system 100 in Figure 1). In at least some embodiments, the imaging of the ROI 416 is performed at a linear pullback rate of no greater than 2 mm/sec.

20 In preferred embodiments, the images obtained during the inspection pullback are displayed. In at least some embodiments, only the images obtained during the inspection pullback are displayed. In at least some embodiments, the images obtained during the survey pullback and the images obtained during the inspection pullback are both displayed. In at least some embodiments, the display of the set of images from the inspection pullback are combined with the set of images from the survey pullback to form a composite image. In at least some embodiments, displayed images can be edited (*e.g.*, cropped, filtered, or the like).

25 As discussed above, with conventional intravascular imaging techniques, a 10 cm pullback may take 100 to 200 seconds. In at least some embodiments, when the survey region has a longitudinal length of 10 cm and is imaged at a linear pullback rate of 40 mm/sec, the survey pullback is performed in no more than 2.5 seconds. In at least some embodiments, when the ROI has a longitudinal length of 1 cm and is imaged at a linear pullback rate of 1 mm/sec, the inspection pullback is performed in no more than 10 seconds. 30 Thus, even allowing for 30 seconds for placing the one or more markers in proximity to the

ROI and re-positioning the imager to the distal end of the ROI, totaling no more than 42.5 seconds, as compared to 100 to 200 seconds for conventional methods.

Additionally, as also described above, with conventional intravascular imaging techniques, a 10 cm pullback may capture 3,000 to 6,000 images. Moreover, the majority of the images and the time it takes to capture the images are associated with healthy portions of patient vasculature that are not significant to the given diagnosis. In at least some embodiments, the size of the data stored on the control module (104 in Figure 1) can be reduced by performing a survey pullback and an inspection pullback. For example, in at least some embodiments, at an imaging rate of 30 images per second, the number of frames stored during the survey pullback and the inspection pullback, respectively, is (2.5 seconds x 30 images per second) + (10 seconds x 30 images per second) = 375 images, as compared to 3,000 to 6,000 images for conventional methods.

Figure 7 is a flow diagram showing one exemplary embodiment of an imaging procedure using an intravascular imaging system with multiple pullback rates. In step 702, a catheter with an imager is inserted into patient vasculature. In step 704, the imager is positioned at a distal end of a survey region. In step 706, the imager is pulled back along the survey region to a proximal end of the survey region at a first linear rate of pullback. When, in step 708, the survey region does not include any ROIs, the imaging procedure ends. Otherwise, in step 710 one or more markers are positioned (and adjusted, if applicable) in proximity to a ROI identified during the survey pullback. When, in step 712, the survey region includes one or more additional ROIs, control is passed back to step 710. Otherwise, in step 714 the imager is positioned at the distal end of a marked ROI. In step 716, the imager is pulled back along the ROI to a proximal end of the ROI at a second linear rate of pullback that is different than the first rate of linear pullback. When, in step 718, the survey region includes one or more additional marked ROIs, control is passed back to step 714. Otherwise, the imaging procedure ends.

It will be understood that each block of the flowchart illustrations, and combinations of blocks in the flowchart illustrations, as well any portion of the tissue classifier, imager, control module, systems and methods disclosed herein, can be implemented by computer program instructions. These program instructions may be provided to a processor to produce a machine, such that the instructions, which execute on the processor, create means for implementing the actions specified in the flowchart block or blocks or described for the tissue

classifier, imager, control module, systems and methods disclosed. program instructions may be executed by a processor to cause a series of operational steps to be performed by the processor to produce a computer implemented process. The computer program instructions may also cause at least some of the operational steps to be performed in parallel. Moreover, some of the steps may also be performed across more than one processor, such as might arise in a multi-processor computer system. In addition, one or more processes may also be performed concurrently with other processes, or even in a different sequence than illustrated without departing from the scope or spirit of the invention.

The computer program instructions can be stored on any suitable computer-readable medium including, but not limited to, RAM, ROM, EEPROM, flash memory or other memory technology, CD-ROM, digital versatile disks (DVD) or other optical storage, magnetic cassettes, magnetic tape, magnetic disk storage or other magnetic storage devices, or any other medium which can be used to store the desired information and which can be accessed by a computing device.

It will be understood that pullback along one or more of the survey region or the ROI may be performed by pulling the imager from a proximal end to a distal end of the region being imaged. It will also be understood that the intravascular imaging techniques described above can also be used with other types of imaging techniques that use a catheter insertable into patient vasculature. For example, the intravascular imaging techniques can be used with any imaging techniques configured and arranged to assess one or more measurable characteristics of patient tissue (e.g., intravascular magnetic resonance imaging, spectroscopy, temperature mapping, or the like).

The above specification, examples and data provide a description of the manufacture and use of the composition of the invention. Since many embodiments of the invention can be made without departing from the spirit and scope of the invention, the invention also resides in the claims hereinafter appended.

## CLAIMS

1. A computer-readable medium having processor-executable instructions for imaging tissue, the processor-executable instructions when installed onto a device enable the device to perform actions, comprising:

imaging a survey region with an imager to obtain a set of first images while pulling back the imager from the first end of the survey region to a second end of the survey region opposite the first end, wherein the imager is pulled back at a first linear rate of pullback;

imaging a region of interest identified within the survey region to obtain a set of second images while pulling back the imager from a first end of the region of interest to a second end of the region of interest opposite the first end, wherein the imager is pulled back at a second linear rate of pullback that is less than the first linear rate of pullback; and

displaying at least a portion of the set of second images.

2. The computer-readable medium of claim 1, wherein the actions further comprise identifying the region of interest within the survey region using at least a portion of the set of first images of the survey region.

3. The computer-readable medium of any one of claims 1-2, wherein the actions further comprise positioning the imager at the first end of the identified region of interest.

4. The computer-readable medium of any one of claims 1-3, wherein the actions further comprise displaying at least a portion of the set of first images.

5. The computer-readable medium of claim 4, wherein the actions further comprise marking the identified region of interest on the displayed set of first images.

6. An imager comprising:

at least one imager disposed in a catheter, the at least one imager coupled to a control module; and

a processor disposed in the control module, the processor for executing processor-readable instructions that enable actions, including:

imaging a survey region to obtain a set of first images while pulling back the imager from the first end of the survey region to a second end of the survey region opposite the first end, wherein the imager is pulled back at a first linear rate of pullback;

imaging a region of interest identified within the survey region to obtain a set of second images while pulling back the imager from a first end of the region of interest to a second end of the region of interest opposite the first end, wherein the imager is pulled back at a second linear rate of pullback that is less than the first linear rate of pullback; and

displaying at least a portion of the set of second images.

7. The imager of claim 6, wherein the actions further comprise identifying the region of interest within the survey region using at least a portion of the set of first images of the survey region.

8. The imager of any one of claims 6-7, wherein the actions further comprise positioning the imager at the first end of the identified region of interest.

9. The imager of any one of claims 6-8, wherein the actions further comprise displaying at least a portion of the set of first images.

10. A method of operating an imaging system, the method comprising:  
providing an imager disposed in a catheter, the catheter configured and arranged for positioning at a first end of a survey region to be imaged, wherein the imager is coupled to a control module;

determining a region of interest within the survey region using at least a portion of a set of first images of the survey region obtained while pulling back the imager from the first end of the survey region to a second end of the survey region opposite the first at a first linear rate of pullback; and

displaying at least a portion of a set of second images obtained by positioning the imager at a first end of the determined region of interest and imaging the region of interest by

pulling back the imager at a second linear rate of pullback that is less than the first linear rate of pullback.

11. The method of claim 10, wherein the intravascular imaging system is one of an intravascular ultrasound system or an optical coherence tomography system.

12. The method of any one of claims 10-11, wherein determining the region of interest within the survey region comprises marking the region of interest.

13. The method of claim 12, wherein marking the region of interest comprises marking the region of interest on a displayed image of at least a portion of the survey region.

14. The method of claim 13, wherein marking the region of interest comprises placing at least one marker over top of, or in proximity to, at least a portion of the displayed region of interest.

15. The method of claim 14, wherein marking the region of interest comprises adjusting at least one of the length or the position of the displayed marker.

16. The method of claim 12, wherein marking the region of interest is performed by the control module.

17. The method of any one of the claims 10-16, wherein positioning the imager at the first end of the marked region of interest is performed by the control module.

18. The method of any one of the claims 10-16, wherein positioning the imager at the first end of the marked region of interest is performed manually by a user of the imaging system.

19. The method of claim 18, wherein positioning the imager at a first end of the marked region of interest is performed manually using one or more displayed markers as guides.

20. The method of any one of claims 10-19, further comprising combining at least some of the first set of images with at least some of the second set of images to form a composite image.

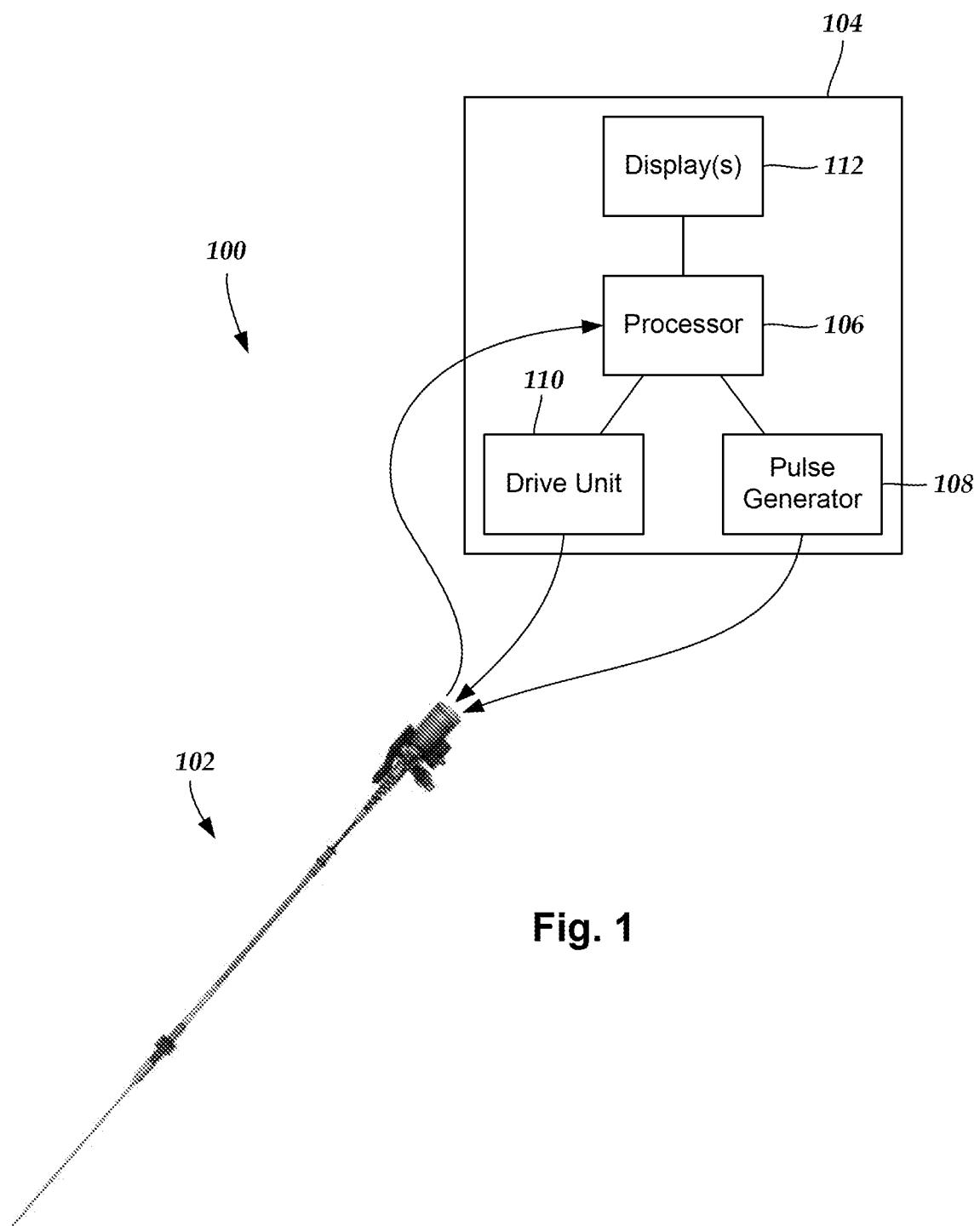
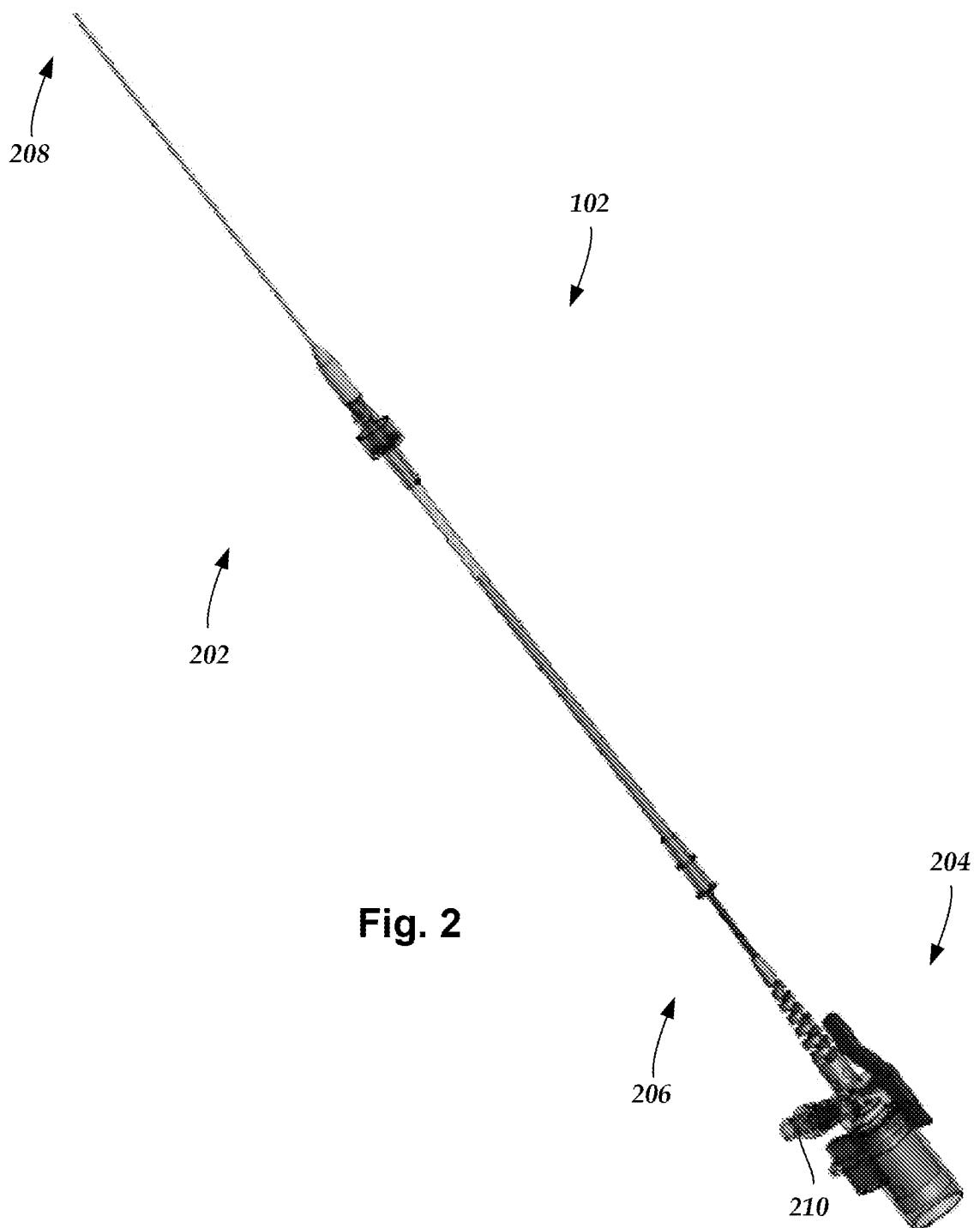
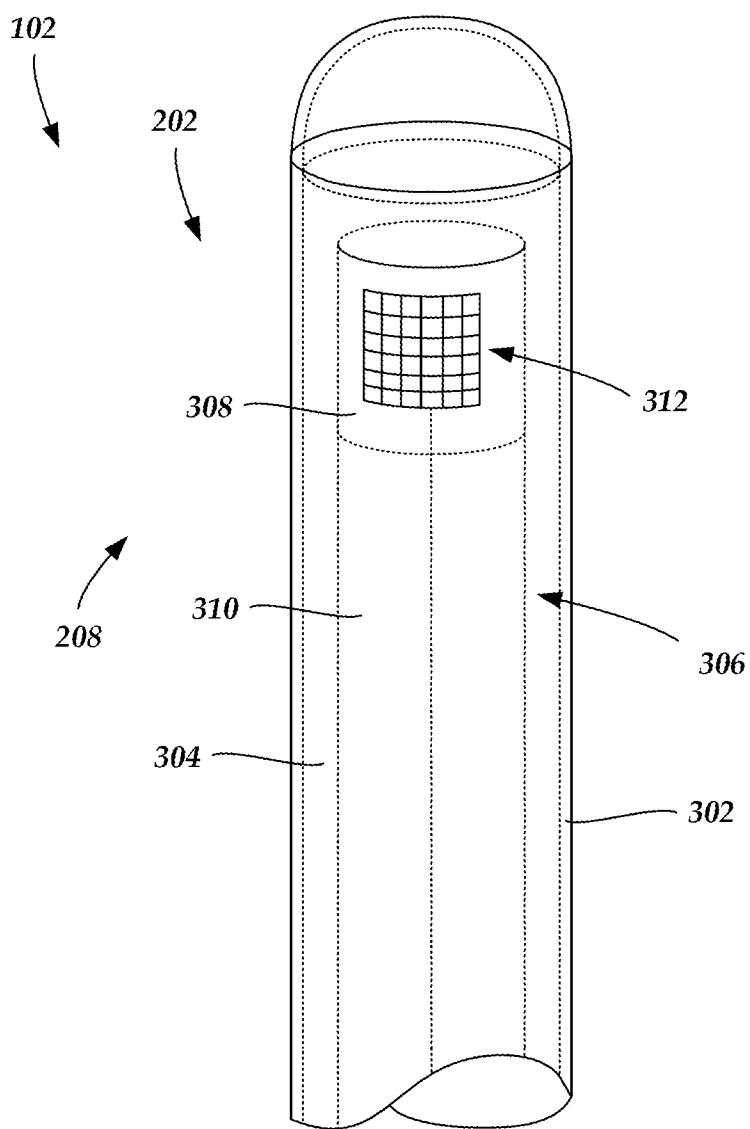
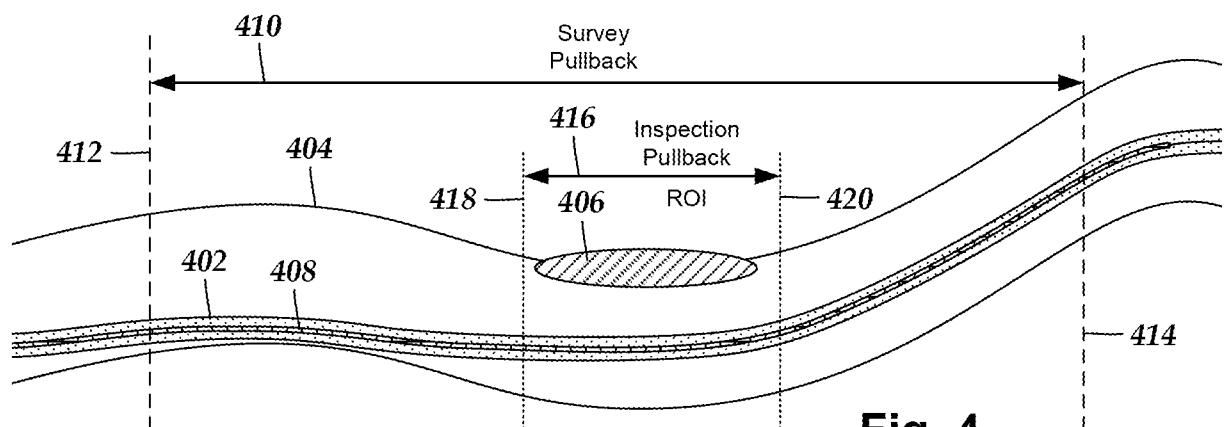
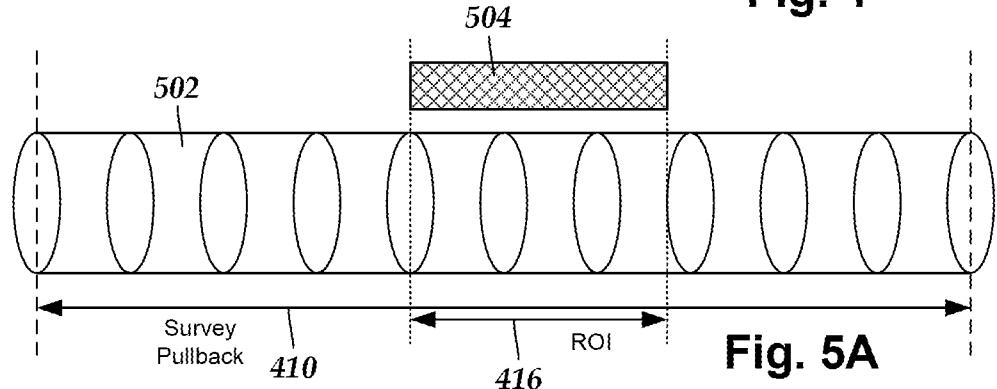
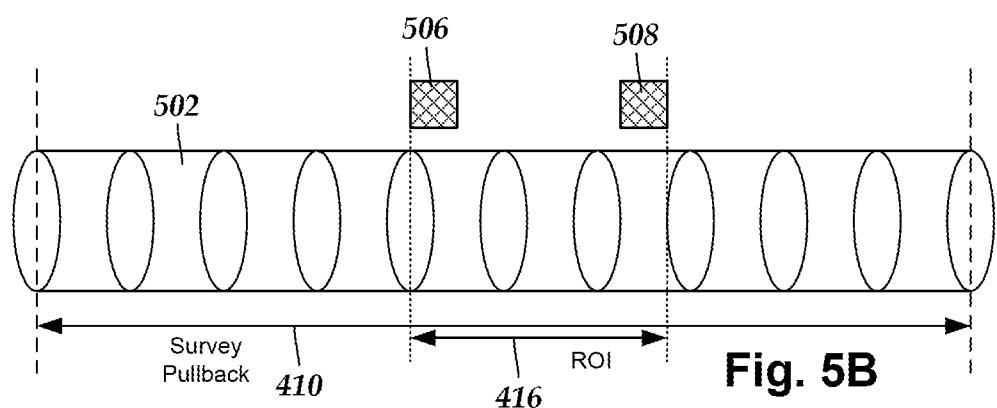
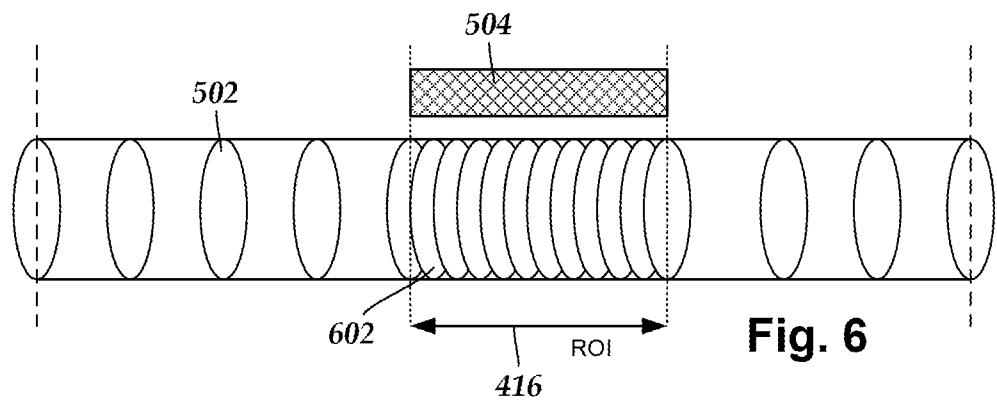


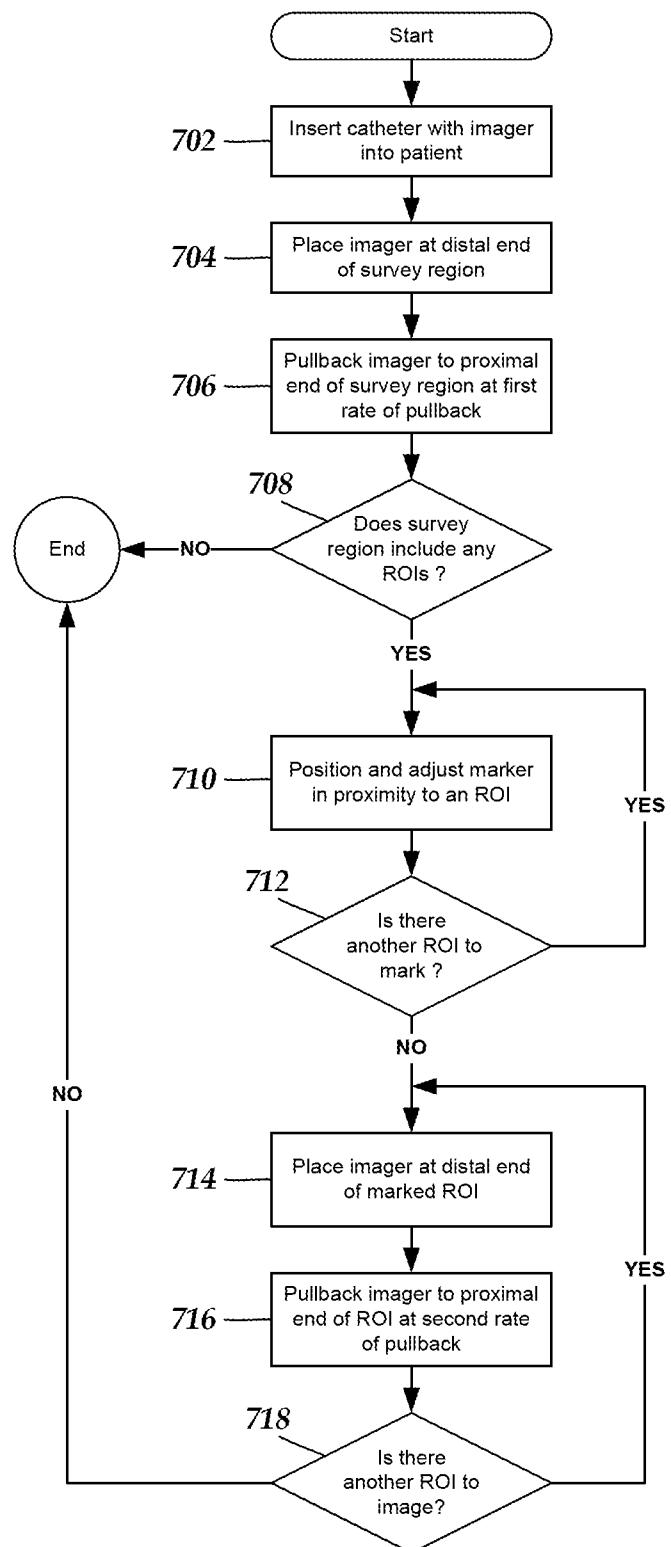
Fig. 1





**Fig. 3**

**Fig. 4****Fig. 5A****Fig. 5B****Fig. 6**

**Fig. 7**

## INTERNATIONAL SEARCH REPORT

International application No  
PCT/US2010/028442

<b>A. CLASSIFICATION OF SUBJECT MATTER</b> INV. A61B8/12 ADD.			
According to International Patent Classification (IPC) or to both national classification and IPC			
<b>B. FIELDS SEARCHED</b> Minimum documentation searched (classification system followed by classification symbols) <b>A61B</b>			
Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched			
Electronic data base consulted during the international search (name of data base and, where practical, search terms used) <b>EPO-Internal, WPI Data</b>			
<b>C. DOCUMENTS CONSIDERED TO BE RELEVANT</b>			
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.	
X	US 2006/052700 A1 (SVANERUDH JOHAN [SE]) 9 March 2006 (2006-03-09) * abstract paragraph [0008] paragraph [0011] – paragraph [0016] paragraph [0038] – paragraph [0048] claim 1 figures 1-4 -----	1-9	
X	SPE, PO BOX 10 BELLINGHAM WA 98227-0010 USA, 2 October 2007 (2007-10-02), XP040247973 * abstract 2. SYSTEM DESCRIPTION 3. SYSTEM CALIBRATION – Data acquisition figures 1,4 -----	1-9	
	-/--		
<input checked="" type="checkbox"/>	Further documents are listed in the continuation of Box C.	<input checked="" type="checkbox"/>	See patent family annex.
* Special categories of cited documents : "A" document defining the general state of the art which is not considered to be of particular relevance "E" earlier document but published on or after the international filing date "U" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "O" document referring to an oral disclosure, use, exhibition or other means "P" document published prior to the international filing date but later than the priority date claimed		"U" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art. "&" document member of the same patent family	
Date of the actual completion of the international search		Date of mailing of the international search report	
31 August 2010		06/09/2010	
Name and mailing address of the ISA/ European Patent Office, P.B. 5818 Patentlaan 2 NL – 2280 HV Rijswijk Tel. (+31-70) 340-2040, Fax: (+31-70) 340-3016		Authorized officer Marteau, Frédéric	

## INTERNATIONAL SEARCH REPORT

International application No  
PCT/US2010/028442

## C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	WO 2007/103726 A2 (BRIGHAM & WOMENS HOSPITAL [US]; UNIV NORTHEASTERN [US]; FELDMAN CHARLE) 13 September 2007 (2007-09-13) page 5, line 16 – page 6, line 5 page 9, line 1 – page 10, line 2 -----	1-9

**FURTHER INFORMATION CONTINUED FROM PCT/ISA/ 210**

Continuation of Box II.1

Claims Nos.: 10-20

Claims 10-20 relate to a method for treatment of the human or animal body surgery, because they all comprise the step of 'pulling back the imager' inside a body cavity per se requiring professional medical skills and involving health risks even when carried out with the required medical care and expertise. This Authority is not required to search the present application with respect to the aforementioned claims (Article 17(2)(b) PCT and Rule 39.1(iv) PCT). Consequently, no International Search Report and no Written Opinion (Rule 67.1 PCT in combination with Rule 43bis.1(b) PCT) have been established with respect to them.

## INTERNATIONAL SEARCH REPORT

International application No.  
PCT/US2010/028442

### Box No. II Observations where certain claims were found unsearchable (Continuation of item 2 of first sheet)

This international search report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:

1.  Claims Nos.: **10–20**  
because they relate to subject matter not required to be searched by this Authority, namely:  
see FURTHER INFORMATION sheet PCT/ISA/210
2.  Claims Nos.:  
because they relate to parts of the international application that do not comply with the prescribed requirements to such an extent that no meaningful international search can be carried out, specifically:
3.  Claims Nos.:  
because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a).

### Box No. III Observations where unity of invention is lacking (Continuation of item 3 of first sheet)

This International Searching Authority found multiple inventions in this international application, as follows:

1.  As all required additional search fees were timely paid by the applicant, this international search report covers all searchable claims.
2.  As all searchable claims could be searched without effort justifying an additional fees, this Authority did not invite payment of additional fees.
3.  As only some of the required additional search fees were timely paid by the applicant, this international search report covers only those claims for which fees were paid, specifically claims Nos.:
4.  No required additional search fees were timely paid by the applicant. Consequently, this international search report is restricted to the invention first mentioned in the claims; it is covered by claims Nos.:

#### Remark on Protest

The additional search fees were accompanied by the applicant's protest and, where applicable, the payment of a protest fee.

The additional search fees were accompanied by the applicant's protest but the applicable protest fee was not paid within the time limit specified in the invitation.

No protest accompanied the payment of additional search fees.

**INTERNATIONAL SEARCH REPORT**

## Information on patent family members

International application No  
PCT/US2010/028442

Patent document cited in search report	Publication date	Patent family member(s)		Publication date
US 2006052700	A1	09-03-2006	WO 2006041346	A1 20-04-2006
WO 2007103726	A2	13-09-2007	CA 2644319	A1 13-09-2007
			EP 1994492	A2 26-11-2008
			JP 2009528147	T 06-08-2009
			US 2008004530	A1 03-01-2008