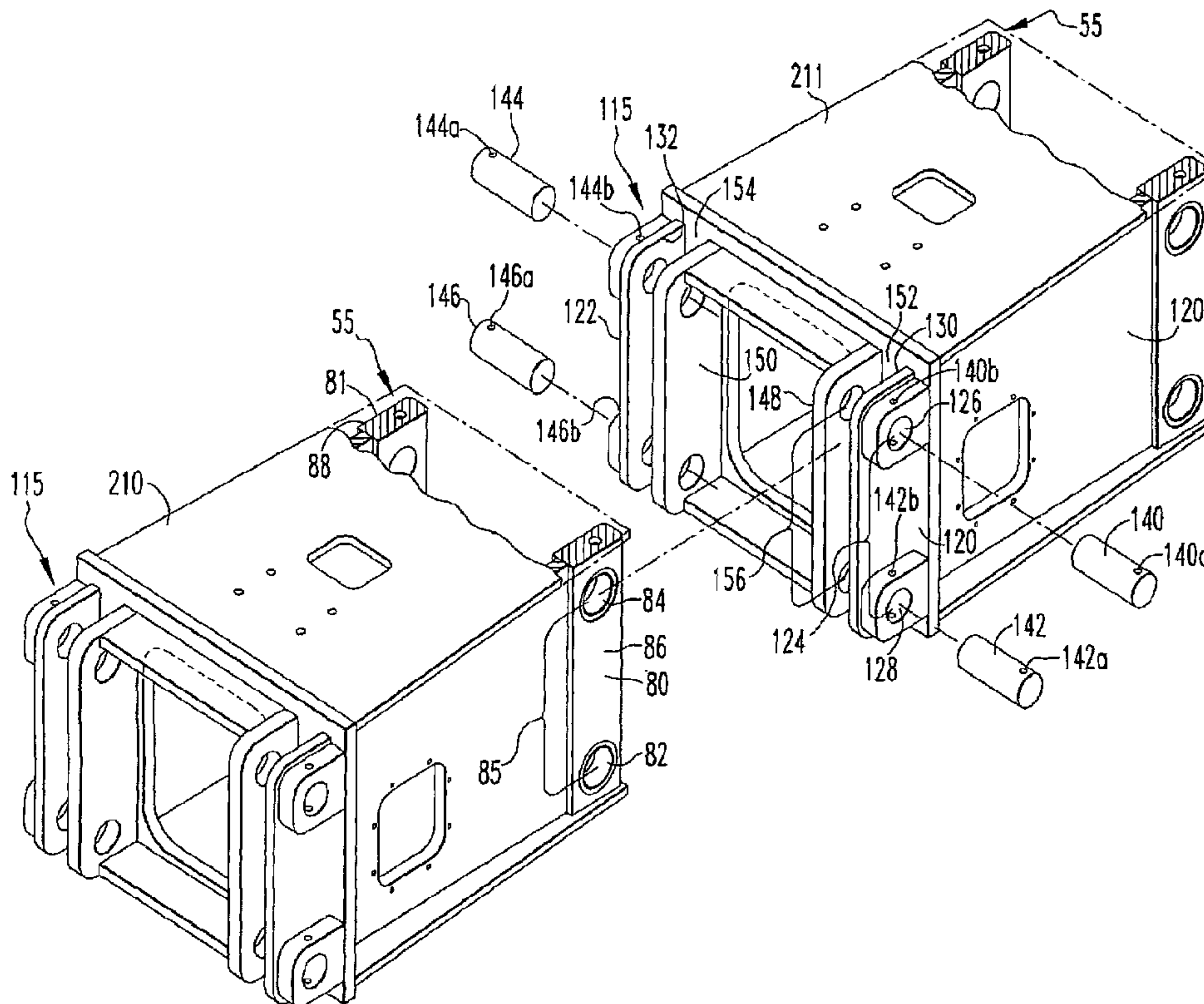




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(54) Titre : SYSTEME MODULAIRE POUR RACCORDER DES ACCESSOIRES A UN ENGIN DE TRAVAUX
 (54) Title: MODULAR SYSTEM FOR CONNECTING ATTACHMENTS TO A CONSTRUCTION MACHINE



(57) **Abrégé/Abstract:**

A modular system for connecting attachments (360,512,530,540) to the extension arm (15,20) of a construction machine (10) , wherein each module has a standardized coupling arrangement (55,115) . As a result, each module (55,115) is compatible with another module (55,115) to provide great versatility in configuring the machine (10) . Additionally, the system includes a variety of different modules and a mechanism for remotely activating the coupling between modules (55,115).

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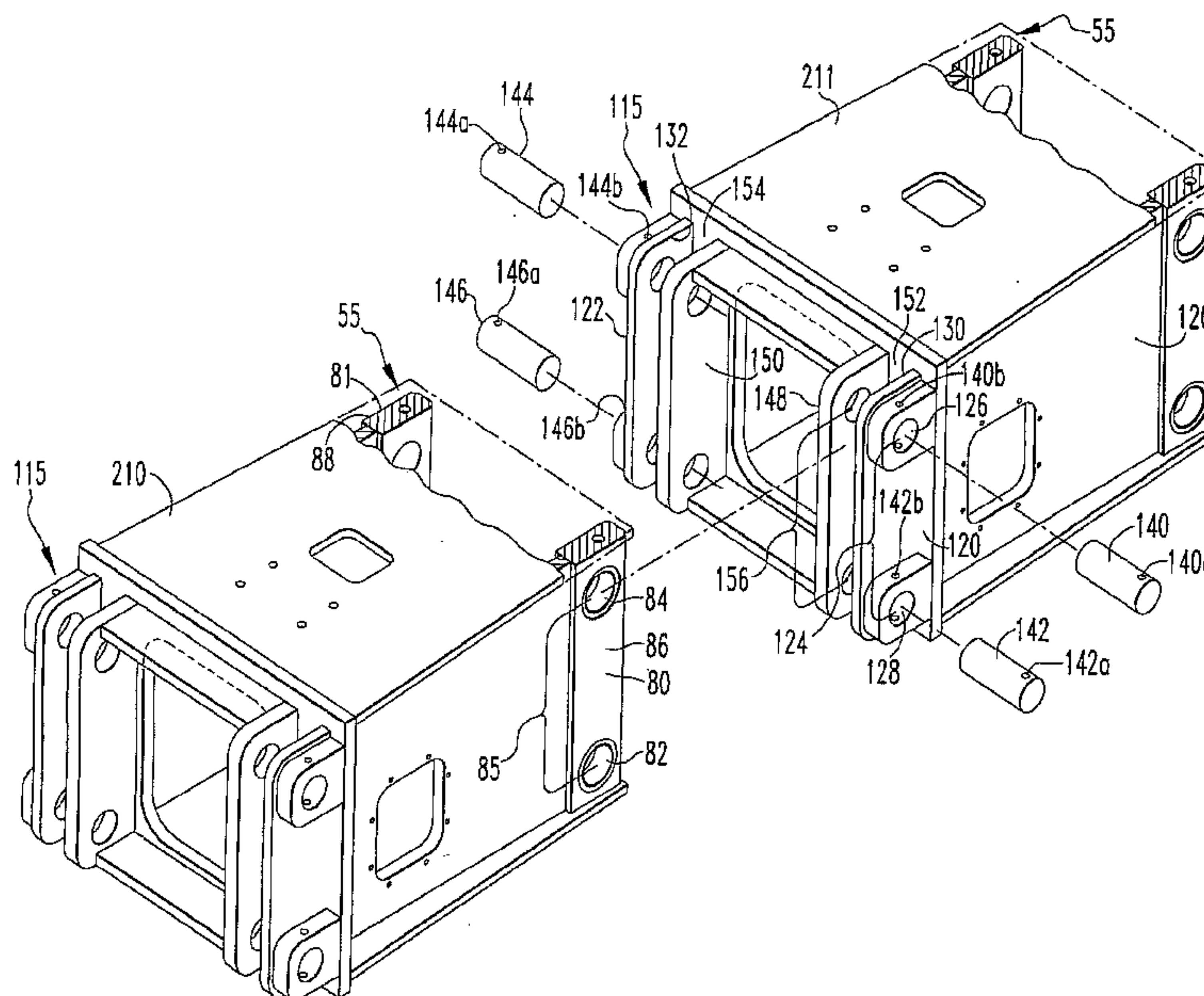
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(54) Title: MODULAR SYSTEM FOR CONNECTING ATTACHMENTS TO A CONSTRUCTION MACHINE



(57) Abstract: A modular system for connecting attachments (360,512,530,540) to the extension arm (15,20) of a construction machine (10), wherein each module has a standardized coupling arrangement (55,115). As a result, each module (55,115) is compatible with another module (55,115) to provide great versatility in configuring the machine (10). Additionally, the system includes a variety of different modules and a mechanism for remotely activating the coupling between modules (55,115).

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MODULAR SYSTEM FOR CONNECTING ATTACHMENTS TO A CONSTRUCTION MACHINE

BACKGROUND OF THE INVENTION

Field of the Invention

[0001] The present invention relates to a modular system for construction or demolition equipment which is adapted to be attached to a backhoe for attaching multiple tools, such as a heavy-duty metal cutting shear, a plate shear, a claw, a hammer, a bucket, a grapple or a concrete crusher.

[0002] While the discussion hereafter will make reference to construction equipment, such equipment is also referred to as demolition equipment, scrap handling equipment and the like. The description of construction equipment is not intended to be restrictive of the equipment being referenced. Demolition equipment, such as heavy-duty metal cutting shears, plate shears, claws, hammers, buckets, grapples and concrete crushers have been mounted on backhoes powered by hydraulic cylinders for a variety of jobs in the demolition field. This equipment provides for the efficient cutting and handling of scrap. For example, in the dismantling of an industrial building, metal scrap in the form of various diameter pipes, structural I-beams, channels, angles, sheet metal plates and the like, must be efficiently severed and handled by heavy-duty metal shears. Such metal shears can also be utilized for reducing automobiles, truck frames, railroad cars and the like. The shears must be able to move and cut the metal scrap pieces regardless of the size or shape of the individual scrap pieces and without any significant damage to the shears. In the demolition of an industrial building, concrete crushing devices such as a concrete pulverizer or concrete crackers are also used to reduce the structure to manageable components which can be easily handled and removed from the site. A grapple is often utilized where handling of debris or work pieces is a primary function of the equipment. Historically, all these pieces of equipment represent distinct tools having significant independent capital costs. Consequently, the demolition industry has tended to develop one type of tool that can have the greatest possible utility and application.

[0003] In general, construction equipment such as a backhoe is made up of a tractor having attached thereto a hydraulically operated boom and attached to the boom is a hydraulically operated stick. Each manufacturer of construction equipment provides a variety of attachments for their equipment, however, these attachments fit on only that manufacturer's equipment. As a result, the purchasing of such attachments not only requires a dedicated commitment to a single manufacturer of construction equipment, but furthermore, puts the

equipment owner at a significant disadvantage if the particular equipment manufacturer does not provide a particular attachment which may be needed by the equipment owner. It is inefficient and costly for an equipment owner to own and maintain two separate construction machines because certain attachments are made by one manufacturer and certain other attachments are made by another manufacturer.

[0004] Additionally, different construction tasks require different configurations of the construction machine and depending upon the equipment manufacturer, there may be only a limited number of configurations possible for a specific construction machine. In the event that the machine owner desires a different configuration, then it may be necessary to approach the equipment manufacturer and ask for the specialized services associated with a customized part. This may become prohibitively expensive.

[0005] A design is needed that will provide the machine owner with the flexibility of a single set of attachments that may be suitable for use with any of a variety of construction machines from different manufacturers. Furthermore, a design is needed whereby a machine owner may have the flexibility to configure the attachments in any desirable sequence thereby maximizing the efficiency of the construction machine. Finally, a design is needed whereby it is possible for the machine owner to maximize the versatility of a construction machine by utilizing a plurality of different attachments that may be attached to the construction machine.

SUMMARY OF THE INVENTION

[0006] A modular system for connecting any one of a plurality of modules to an extension arm of a construction machine comprising:

a) a wing secured to the end of the extension arm, wherein the wing has a standardized proximal mounting arrangement; and

b) a plurality of modules wherein each module has a first end with a standardized distal coupling arrangement adapted to be coupled with the standardized proximal coupling arrangement so that each module may be interchangeably secured to the wing.

[0007] For use in a modular system for connecting any one of a plurality of modules together to an extension arm of a construction machine, the subject invention is also directed to an automatically actuated coupling system for securing the modules.

[0008] Another embodiment of the subject invention is directed to a module for connecting to the extension arm of a construction machine. The module has a body with a first end and a

second end with a proximal coupling arrangement associated with the first end and a distal coupling arrangement associated with the second end. The distal coupling arrangement has a plate with a hole pattern and the proximal coupling arrangement has a mating plate with an aligned matching hole pattern. The mounting arrangements are complimentary such that a second module having an identical one of the distal mounting arrangement or proximal mounting arrangement may be secured thereto.

[0009] Another embodiment of the subject invention is directed to a method for remotely locking a structural module onto the extension arm of a construction tool. The arm and module each have matching hole patterns adapted to receive common retention pins moved by a hydraulic cylinder. The method comprises the steps of:

- a) aligning the hole patterns of the arm and module and
- b) activating the hydraulic cylinder to move the retention pins to engage the holes of each pattern, thereby securing the structural module to the extension arm.

[0010] Another embodiment of the subject invention is directed to a method of interchangeably securing structural modules to the extension arm of a construction machine, wherein each module has a standardized coupling arrangement comprising the steps of mounting a first module to the standardized coupling arrangement of the extension arm, removing the first module from the extension arm, and mounting a second module having an identical standardized coupling arrangement to the extension arm.

[0011] These and other advantages of the present invention will be clarified in the description of the preferred embodiments wherein like reference numerals represent like elements throughout.

BRIEF DESCRIPTIONS OF THE DRAWINGS

[0012] Figure 1 is a schematic of a construction machine with the stick positioned to receive an attachment;

[0013] Figure 2 is a schematic of the construction machine in Figure 1 with a stick wing mounted to the stick;

[0014] Figure 3 is a schematic of a construction machine with the boom positioned to receive an attachment;

[0015] Figure 4 is a schematic of the construction machine in Figure 3 with a boom wing attached to the boom;

[0016] Figures 5A and 5B are a side view and a front view of a stick wing;

[0017] Figures 6A and 6B are a side view and a top view of a boom wing;

[0018] Figure 7A is an exploded isometric view of one embodiment of the coupling arrangement in accordance with the subject invention;

[0019] Figure 7B is an assembled isometric view of the coupling arrangement illustrated in Figure 7A;

[0020] Figure 8 is a side view of an alternate embodiment of the coupling arrangement in accordance with the subject invention;

[0021] Figure 9 is a side view of another alternate coupling arrangement in accordance with the subject invention;

[0022] Figure 10 is an exploded view of a stick wing and a portion of an adapter;

[0023] Figure 11 is the view of the stick in Figure 10 along lines "XI - XI" in Figure 10;

[0024] Figure 12A is a view of the adapter illustrated in Figure 10 along lines "XII-XII" with the tie bars extended;

[0025] Figure 12B is a view of the adapter in Figure 12A with the tie bars retracted;

[0026] Figures 13A-13C illustrate the sequential steps for securing the stick wing to the adapter;

[0027] Figures 14A, 14B and 14C are front, top and left end views, respectively, of an adapter;

[0028] Figures 15, 16, 17 and 18 are exploded side views of different configurations of modules possible utilizing the design in accordance with the subject invention;

[0029] Figure 19 is an assembled view of the exploded element in Figure 18 excluding the multi-tool;

[0030] Figures 20A and 20B are side views of a folding adapter, in different positions, in accordance with the subject invention whereby the folding member and the adapter member are integral with one another;

[0031] Figures 21A-21D are sequential side views of the motion possible utilizing the arrangement in accordance with Figure 18;

[0032] Figure 22 is an exploded side view of a bucket associated with a stick wing and a rotator module therebetween;

[0033] Figure 23 is a side view of the arrangement illustrated in Figure 22 but in an assembled configuration;

[0034] Figures 24-26 are a side view, a left end view, and a right end view of a rotator module in accordance with the subject invention;

[0035] Figure 27 is an exploded side view similar to that of Figure 22, however, without the rotator module between the stick wing and bucket;

- [0036] Figure 28 is a side view of an assembled configuration of the elements in Figure 27;
- [0037] Figure 29 is an exploded side view of a claw associated with a stick wing;
- [0038] Figure 30 is a side view of the arrangement in Figure 29 but in an assembled configuration;
- [0039] Figure 31 is an exploded side view of a hammer associated with a stick wing;
- [0040] Figure 32 is the hammer illustrated in Figure 31, but assembled and mounted upon the stick of a construction machine;
- [0041] Figures 33 and 34 are a side view and a top view, respectively, of a reducer module;
- [0042] Figures 35 and 36 are a side view and a top view of an enlarger module;
- [0043] Figure 37 is a schematic of a construction machine whereby a supplemental extension member has been added to the stick for a system designed to be utilized with an electric magnet for retrieving scrap;
- [0044] Figure 38 is a modified extension arm having a portal extending therethrough for protecting the electric wire needed to control the magnet of the construction machine illustrated in Figure 37;
- [0045] Figures 39 and 40 are a top view and a side view, respectively, of the supplemental extension member;
- [0046] Figures 41A-41E illustrate a sequence of motion possible utilizing the elements illustrated on the construction machine in Figure 37;
- [0047] Figure 42 is a schematic of a construction machine whereby the supplemental extension member has been added to the boom for a system designed to be utilized with an electric magnet for retrieving scrap;
- [0048] Figures 43A-43C illustrate in different positions a telescopic adapter module mounted to the boom of a construction machine
- [0049] Figure 44 is an exploded top view of a stick wing and a portion of an adapter;
- [0050] Figure 45 is a side view of the stick wing illustrated in Figure 44;
- [0051] Figure 46 is an assembled top view of the arrangement illustrated in Figure 44, with the locking pins retracted; and
- [0052] Figure 47 is an assembled top view similar to the arrangement illustrated in Figure 46, but with the locking pins extended to engage the adapter.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

- [0053] Figure 1 illustrates a construction machine 10 including a tractor 12 having an extension arm or boom 15 mounted thereupon and pivoted upon the tractor 12 with a

hydraulic cylinder (not shown). Attached to the boom 15 is an extension arm or stick 20 operated by a hydraulic cylinder 25 attached between the boom 15 and the stick 20. A stick pivot attachment point 30 in conjunction with a stick linkage attachment point 35 provide points of attachment through which other tools and accessories may be attached to the stick 20. A hydraulic cylinder 40 in conjunction with a connecting linkage 45 act to move the stick linkage attachment point 35 to manipulate any accessory attached thereto. It is important to note that the stick pivot attachment point 30 and stick linkage attachment point 35 may significantly differ from one manufacturer to another such that one accessory or tool from a particular manufacturer may not be compatible to mount upon the stick of another manufacturer.

[0054] Directing attention to Figure 2, the subject invention is intended to overcome this deficit by providing a modular system comprised of different functional modules that may be attached to the stick 20 through the use of a stick wing 50. The proximal end 51 of the stick wing 50 is connected to the stick 20 at the stick pivot attachment point 30 and at the stick linkage attachment point 35. The distal end 52 of the stick wing 50 includes a standardized proximal coupling arrangement 55 which may be used as a base for mounting any number of modular accessories or tools.

[0055] Additionally, directing attention to Figures 3 and 4, which illustrates a construction machine 10 having a tractor 12 with only a boom 15 extending therefrom, a boom pivot attachment point 60 and a boom linkage attachment point 65, driven by the hydraulic cylinder 25, may be used as attachment points to receive the proximal end 71 of a boom wing 70 (Figure 4). Once again, a distal end 72 of the boom wing 70 has a standardized proximal coupling arrangement 75 adapted to receive a variety of different modular accessories and tools.

[0056] Through the use of the stick wing 50 and the boom wing 70 it is possible to adapt a large variety of different construction machines to accept a plurality of standardized attachments and tools thereby providing the maximum versatility for a construction machine 10 in the event a manufacturer does not provide a full complement of such attachments and/or tools, or, in the event a machine owner wishes to maximize the capacity of the machine.

[0057] In particular, the proximal end 51 of the stick wing 50 or the proximal end 71 of the boom wing 70 may be customized to accommodate the stick attachment points or the boom attachment points of any variety of different designs.

[0058] Figures 5A and 5B illustrate a front and side view of a stick wing 50. In particular, the stick wing 50 is comprised of at least two plates 80, 81, each having at least two holes 82, 84 extending therethrough and spaced apart to define a hole pattern 85. The at least two opposing plates 80, 81 have mounting surfaces 86, 88 thereupon. It is the location of these plates 80, 81 and the associated holes 82, 84, which define the proximal coupling arrangement associated with the stick wing 50. The opposing plates 80, 81 are connected together through the use of a connecting member 90.

[0059] Additionally, each opposing plate 80, 81 has therethrough connecting bores 92, 94 spaced apart from one another on each plate 80, 81. It is the location and design of each of these connecting bores 92, 94 which provides a connection to the stick wing 50 of one manufacturer or another manufacturer. The stick wing 50 may be designed such that the size and the location of the connecting bores 92, 94 accommodate the attachment of the stick for different construction machines. While it may be necessary for a machine owner to have in inventory a variety of different stick wings 50, each designed to adapt for different construction machinery, it will not be necessary for the machine owner to purchase customized tools for each construction machine because, as will be seen, the modular system in accordance with the subject invention permits the use of a single set of tools upon machines from different manufacturers.

[0060] Figures 6A and 6B illustrate a side view and a top view of a boom wing 70 having the standardized proximate coupling arrangement 75 and connecting bores 100, 102 extending through plates 104, 106 designed to be connected to the boom pivot attachment point 60 and boom linkage attachment point 65 illustrated in Figure 3. The standardized proximal coupling arrangement 75 is identical to the standardized proximal coupling arrangement 55 previously described in association with the stick wing 50. Additionally, the connecting bores 100, 102 may be sized and spaced appropriately to accommodate the attachment points for booms from manufactures of different construction machines. Just as with the stick wing 50, the boom wing 70 may be comprised of at least two opposing plates 104, 106 and each of these opposing plates 104, 106 may have mounting surfaces 108, 110.

[0061] A typical configuration for the proximal coupling arrangement and distal coupling arrangement herein discussed is illustrated in Figures 7A and 7B. Directing attention to Figure 7A, an adapter 210 having a standardized proximal coupling arrangement 55 is illustrated in an exploded isometric view relative to the standardized distal coupling arrangement 115 of another adapter 211. In particular, and using reference numbers already used with respect to the stick wing 50 and the boom wing 70, the distal coupling arrangement

55 is comprised of opposing plates 80, 81 with a hole pattern 85 defined by holes 82, 84 which extend through both plates 80, 81. Each plate 80, 81 has a mounting surface 86, 88.

[0062] The standardized distal coupling arrangement 115 is also comprised of at least two opposing plates 120, 122 with a hole pattern 124 defined by spaced-apart holes 126, 128. Each opposing plate 120, 122 has a mounting surface 130, 132 each which is generally aligned with mounting surface 86, 88 of the distal coupling arrangement 55. The opposing plates 80, 81 of the proximal coupling arrangement 55 are spaced in complimentary relationship with the opposing plates 120, 122 of the distal coupling arrangement 115 such that when the plates 80, 81 and 120, 122 are merged, the mounting surfaces 86, 130 and 88, 132 are adjacent to one another. Additionally, the hole pattern 85 of the distal coupling arrangement 55 identified by holes 82, 84 matches the hole pattern 124 of the distal coupling arrangement 115 defined by holes 126, 128. As a result, the proximal coupling arrangement 55 is mated with the distal coupling arrangement 115 and the hole patterns 85, 124 align such that the retention pins 140, 142, 144, 146 may be inserted within the holes thereby securing the proximal coupling arrangement 55 within the distal coupling arrangement 115 as illustrated in Figure 7B. The retention pins 140, 142, 144, 146 each have bores 140a, 142a, 144a, 146a extending diametrically therethrough to accept locking pins (not shown) which are engaged through the bores 140a, 142a, 144a, 146a and through matching bores 140b, 142b, 144b, 146b extending through the adapter.

[0063] It is also possible as illustrated in Figure 7A for the distal coupling arrangement 115 to further include with each opposing plate 120, 122 a reinforcement plate 148, 150 spaced next to the opposing plate 120, 122 to define slots 152, 154 therebetween. Each reinforcement plate 148, 150 has an identical hole pattern 156 to that of the hole pattern 124 associated with the opposing plate within the slot 152.

[0064] From inspection of Figure 7A it should be appreciated that each adapter modules 210, 211 has a standardized proximal coupling arrangement 55 and a standardized distal coupling arrangement 115 at each end. As a result, a plurality of adapter modules 210, 211 may be connected to one another in a string of modules. As will be discussed, each different type of module hereinafter discussed will have one or both of the proximal coupling arrangement 55 and the distal coupling arrangement 115. As a result, these modules may be selected and matched with one another to provide a nearly limitless combination of different modules.

[0065] Although throughout this application a specific configuration is described with respect to each distal coupling arrangement and each proximal coupling arrangement, it is

entirely possible for the configuration associated with one coupling arrangement to be associated with the other configuration. In particular, with respect to Figure 7A, it is entirely possible for the distal coupling arrangement to be associated with reference number 115 and the proximal coupling arrangement to be associated with reference number 55.

[0066] Although the proximal coupling arrangement and mating distal coupling arrangement heretofore disclosed will be the typical arrangement discussed throughout this application, it should be appreciated that there are multiple other coupling arrangements which may be used with the subject invention. In particular, as illustrated in Figure 8, a standardized distal coupling arrangement 155 is mateable with a standardized proximal coupling arrangement 215 whereby the arrangement 155 is comprised of a hooking plate 160 with a hole 162 therethrough and a spaced-apart hook 164. The proximal coupling arrangement 215 is comprised of a hooked plate 166 with a spaced-apart hole 168 therethrough and a pivot pin 170, such that the hook 164 of the hooking plate 160 may engage the pivot pin 170 of the hooked plate 166 and the spaced-apart holes 162, 168 aligned to receive a support pin 172 extending therethrough, thereby providing a secure coupling between the distal coupling arrangement 155 and the proximal coupling arrangement 215.

[0067] Figure 9 illustrates yet another coupling arrangement whereby a distal coupling arrangement 175 is connected to a proximal coupling arrangement 180. In particular, the distal coupling arrangement 175 is comprised of a plate 185 having a hole 187 extending therethrough and a wide protruding end 188. A projection 189 extends transversely to the end 188. The proximal coupling arrangement 180 is comprised of a plate 195 having a hole 197 extending therethrough and a matching wide receiving end 198. A recess 199 complimentary in shape to the projection 189 extends transversely within the end 198 in a direction corresponding to the projection 189. The wide protruding end 188 of the distal coupling arrangement 175 is brought into abutment with the matching wide receiving end 199 of the proximal coupling arrangement 215 wherein the holes 187, 197 are aligned and the projection 189 is engaged with the recess 199. A retention bolt 201 is then placed within the holes 187, 197 to provide a secure coupling between the two coupling arrangements 175, 180.

[0068] What has so far been described is a distal mounting arrangement secured to a proximal mounting arrangement through the use of pins which are secured within mating hole patterns between the proximal mounting arrangement and the distal mounting arrangement. While it is entirely possible to manually secure these pins within the holes of the matching hole patterns, it is also possible to automate this function so that the pins may be

hydraulically activated to be engaged or disengaged from the matching holes of the proximal mounting arrangement and distal mounting arrangement.

[0069] In particular and directing attention to Figures 10-13C, an automatically actuated coupling system 300 will be discussed. For purposes of discussion, as shown in Figure 10, a stick wing 305 will be attached to an adapter 310. The stick wing 305 is comprised of a base 312 having at least one plate 314 with at least two holes 316, 318 extending therethrough defining a hole pattern 319.

[0070] Directing attention to Figures 10 and 12A, and focusing on one half of a coupling arrangement 305, 310, at least two locking posts 320, 322 are aligned with the holes 316, 318 and secured to a tie bar 324. When the stick wing 305 is aligned with the adapter 310, the posts 320, 322 are slidable within the holes 316, 318 of the base plate 314. The adapter 310 is a module having a plate 328 with a hole pattern 330 extending therefrom matching that hole pattern 319 of the base plate 314 when the adapter 310 is positioned next to the stick wing 305. A manipulator rod 335 (Figure 11) is moved back and forth by an actuator 340. Figure 11 illustrates the manipulator rod 335 in a retracted position. The actuator 340 may be, among other things, a hydraulic cylinder or an electric solenoid capable of moving the manipulator rod 335 from a retracted position illustrated in Figure 11 to an extended position illustrated in Figure 13A. The manipulator rod 335 extends from the stick wing 305 to engage a slot 342 in the tie bar 324 as illustrated in Figures 10 and 13A. As illustrated in Figure 13B, once the manipulator rod 335 engages the slot 342 within the tie bar 324 the manipulator rod 335 may be retracted which at the same time will pull the tie bar 324 toward the adapter plate 328 thereby moving the locking posts 320, 322 (Figure 12A) into the holes 316, 318 (Figure 10) of the wing 305 to secure the adapter 310 within the wing 305. Figures 12A, 13A illustrate the adapter 310 with the tie-bar 324 and the pins 320, 322 in the extended position while Figure 13C illustrates the stick wing 305 secured to the adapter 310 when the tie bar 324 is positioned in the retracted manner. As a safety precaution, directing attention to Figure 13C, locking pins 344, 346 may be used to secure the manipulator rod 335 within its retracted position relative to the adapter 310. By utilizing such an arrangement, it is possible to automatically actuate retention pins to engage or disengage modules associated with one another.

[0071] It should be noted that in a preferred embodiment, the stick wing 305 and the adapter 310 have been discussed with a single based plate 314 and a single adapter plate 328. However, it should be understood and as illustrated in Figures 10-13C, that each stick wing 305 and adapter 310 has at least a pair of opposing plates to provide an arrangement which is

symmetrical about the center of each the stick wing 305 and the adapter 310. It should also be noted that while, with respect to Figures 10 – 13C, only one side of the arrangement was discussed, there are four retention pins in a typical adapter coupling in a symmetric arrangement to pins 320, 322 illustrated in Figure 12A.

[0072] Figures 10-13C illustrate what type of automatically actuated coupling system 300 whereby the locking posts mounted upon the adapter 310 are moved inwardly to engage the holes 316, 318 of the stick wing 305.

[0073] Directing attention to Figures 44-47, it is also possible for the locking posts to move outwardly. In particular, as automatically actuated coupling system 1300 will be discussed. For purposes of discussion as shown in Figure 44, a stick wing 1305 will be attached to an adapter 1310. The stick wing 1305 is comprised of a base 1312 having at least one plate 1314 with at least two holes 1316, 1318 extending therethrough defining a hole pattern 1319. At least two locking posts 1320, 1322 are aligned with the holes 1316, 1318 and slidably mounted within a guide 1324 attached to the stick wing base. When the stick wing 1305 is aligned with the adapter 1310, the posts 1320, 1322 are slideable within the holes 1316, 1318 of the base plate 1314. The adapter 1310 is a module having a plate 1328 with a hole pattern similar to that of hole pattern 1319 extending therefrom and matching the hole pattern 1319 of the base plate 1314 when the adapter 1310 is positioned next to the stick wing 1305. When the stick wing 1305 is properly positioned adjacent to the adapter 1310, the locking pins 1320, 1322 are expanded outwardly to engage the holes 1316, 1318 from the retracted position illustrated in Figure 46 to the extended position illustrated in Figure 47 where the locking posts 1320, 1322 engage the adapter 1310. The locking posts 1320, 1322 may be hydraulically activated within the guide 1324. It should be noted that while the locking posts 1320, 1322 within the guide 1324 are associated with the stick wing 1305, it is entirely possible for the locking posts 1320, 1322 within the guide 1324 to be associated instead with the adapter 1310.

[0074] Briefly returning to Figures 7A and 7B, described therein was a proximal coupling arrangement 55 mateable with a distal coupling arrangement 115. Figures 14A-14C illustrate a single adapter module 350 for connecting to a construction machine, wherein the module 350 has a body 352 with a first end 354 and a second end 356. A proximal coupling arrangement 55 similar to that illustrated in Figure 7A is associated with the first end 354 and a distal coupling arrangement 115 similar to that illustrated in Figure 7A is associated with the second end 356. The reference numbers applied in Figure 7A may also be applied to the elements in Figures 14A-14C. It should be appreciated that other modules having a proximal

coupling arrangement 55 on their first end and a distal coupling arrangement 115 on their second end may be arranged with one another and interlocked together in any desirable fashion. It is this interchangeability which provides the machine owner with maximum versatility and maximum efficiency in mixing and matching any number of a variety of different modules each having a proximal coupling arrangement and a distal coupling arrangement or both with each compatible with other modules.

[0075] The module 350 illustrated in Figures 14A-14C is an adapter module which, as will be discussed, is intended to attach to a multi-tool. The adapter module 350 at its first end 354 includes a sleeve 401 with a longitudinal axis 403 and a passageway 405 extending therethrough along the longitudinal axis 403. The sleeve 401 is adapted to encompass the hydraulic cylinder portion 362 (Figure 15) on the end of the multi-tool 360, which is used to operate the multi-tool 360.

[0076] Figure 15 is an exploded side view of an arrangement whereby a stick wing 50 may be secured to an adapter module 350 which itself may be secured to a multi-tool 360. The multi-tool 360 includes a distal coupling arrangement 115 similar to that illustrated in the adapter module 350 of Figures 14A-14C.

[0077] Briefly returning to Figures 14A-14C, the body 352 includes a window 358. When the adapter module 350 is secured to the multi-tool 360, the window 358 provides access for the hydraulic lines which operate the multi-tool 360.

[0078] Figure 16 illustrates the stick wing 50 with the adapter module 350 and a multi-tool 360 adjacent thereto. Between the stick wing 50 and the adapter module 350 is an extension module 365 which is similar to the adapter module 350 but exists purely to provide an extension between the stick wing 50 and another module. The extension module 365 includes a support structure 367 with a proximal coupling arrangement 55 associated with the first end 369 and a distal coupling arrangement 115 associated with the second end 371.

[0079] While the adapter module 350 and the extension module 365 provide rigid structures between the proximal coupling arrangement and the distal coupling arrangement of each of these modules, Figure 17 illustrates a folding module 375 which is capable of pivoting such that the proximal coupling arrangement 55 and distal coupling arrangement 115 may be oriented relative to one another at different angles. The folding module 375 illustrated in Figure 17 is attached to an adapter module 350 at the first end 377 and to a stick wing 50 at the second end 379. Just as before, the adapter module 350 is connected to the multi-tool 360.

[0080] The configuration illustrated in Figure 18 is identical to the configuration illustrated in Figure 17 with the exception that the stick wing 50 is replaced by the boom wing 70 previously described. With this interchangeability, it should be appreciated that any modules that may be attached to the stick wing 50 illustrated in Figure 2 may also be attached to the boom wing 70 illustrated in Figure 4. Nevertheless, returning to Figure 18, the folding module 375 as described with respect to Figure 17 is capable of orienting the proximal coupling arrangement 55 at a different angle relative to the distal coupling arrangement 115.

[0081] Directing attention to Figures 18 and 19, the folding module 375 is comprised of a two-part structure between the first end 377 and the second end 379. Figure 18 illustrates the folding adapter 375 in a straight pattern while Figure 19 illustrates the folding adapter 375 in a folded configuration. A first part 380 and a second part 382 are connected at one point 384 by a pivot 386 and are connected at a different point 388 by a driving cylinder 390 with a cylinder rod 392 such that the motion of the cylinder rod 392 changes the angular orientation of the first part 380 relative to the second part 382 and, as a result, changes the angular orientation of the adapter 350 relative to the boom wing 70 or to any other module to which the first part 380 may be attached.

[0082] The arrangement illustrated in Figure 18 and in Figure 19 is a boom wing 70 attached to a folding module 375 which itself is attached to an adapter module 350. To conserve space and to minimize the number of parts, it is entirely possible to consolidate the boom wing 70 and the folding module 375 illustrated in Figures 18 and 19 to generate a folding adapter module 395 illustrated in Figures 20A and 20B. The folding adapter module 395 is comprised of a two-part structure wherein the first part is an adapter part 397 similar to the adapter module 350 previously described, but now, as will be seen is an integral part of the folding adapter module 395. The adapter part 397 is at the module first end 409.

[0083] The folding adapter module 395 includes a first part 407 which has an adapter at the module first end 409 and includes similar features to the adapter module 350 described with respect to Figures 14A-14C. In particular, the first part 407 at the first end 409 includes a sleeve 401 with a longitudinal axis 403 and a passageway 405 extending therethrough along the longitudinal axis 403. The sleeve 401 is adapted to overlap a hydraulic cylinder portion 362 (Figure 15) on the end of a tool 360.

[0084] The second part is a folding member 411. The first part 407 and the second part 411 are connected to one another at one point 484 by a pivot 486 and at a different point 488 by a driving cylinder 490 with a cylinder rod 492 such that motion of the cylinder rod 492

changes the angular orientation of the first part 407 relative to the second part 411 and, as a result, changes the angular orientation of the boom wing 70 and the first end 409.

[0085] Figures 21A-21D illustrate the versatility of a multi-tool 360 attached to a boom wing 70 by way of the folding adapter module 395 just described. Not only may the multi-tool 360 be rotated by the motion of the boom 15 as it is pivoted about the tractor (not shown), but additionally, through the use of the folding adapter module 395, the multi-tool 360 may have an additional joint of rotation such that, as illustrated in the sequence of Figures 20A-20C, the multi-tool 360 may be rotated through an angular range of approximately 135°. While such a rotation may be available utilizing a standard boom/stick combination, the space required for this arrangement coupled with a multi-tool 360 would be prohibitive and, as a result, the folding adapter module 395 provides a solution not heretofore available in previous designs.

[0086] The modular design so far discussed is amenable to both a terminal module with a standardized coupling arrangement at only one end or an intermediate module which includes a standardized proximal coupling arrangement on one end and a distal coupling arrangement on another end.

[0087] Returning attention to Figure 16, the extension module 365 is one example of an intermediate module which, on a first end 369, includes a standardized proximal coupling 55 and, on the second end 371, includes a standardized distal coupling 115 such that the extension module 365 may be secured between two other modules having an identical distal coupling arrangement or proximal coupling arrangement. As illustrated in Figure 16, the stick wing 50 includes a proximal coupling arrangement 55 which is secured to the distal coupling arrangement 115 at one end 371 of the extension module 365 while the proximal coupling arrangement 55 at the other end 369 of the extension module 365 is secured to the distal coupling arrangement 115 of the adapter module 350. As such, the adapter module 350 is also an intermediate module used to accommodate the multi-tool 360.

[0088] In order to accommodate the proximal coupling arrangement 55 of the adapter module 350, the multi-tool 360 has a front end 500 (Figure 15) with a standardized proximal coupling arrangement 115 with the hydraulic cylinder portion 362 extending therefrom. As previously mentioned, the tool adapter 350 includes a sleeve 401 (Figure 14B) with a longitudinal axis 403 and a passageway 405 extending therethrough along the longitudinal axis 403. The sleeve 401 overlaps the hydraulic cylinder portion 362 (Figure 15) and has a standardized proximal coupling arrangement 55 secured to the standardized distal coupling arrangement 115 of the multi-tool 360. In this arrangement, the multi-tool 360, since it has

only a standardized distal coupling arrangement 115, is considered to be a terminal module. On the other hand, the tool adapter 350, since it has both a standardized proximal coupling arrangement 115 and a standardized distal coupling arrangement 55, is considered to be an intermediate module.

[0089] An intermediate module may also be the extension module 365 previously discussed with respect to Figure 16. An intermediate module may furthermore be the folding module 375 discussed with respect to Figures 17 and 18. Additionally, an intermediate module may be the folding adapter module 395 discussed with respect to Figures 19-20B.

[0090] Directing attention to Figures 22 and 23, the intermediate module may also be a rotator module 510 that may, for example, be secured between the stick wing 50 and a bucket 512 having a distal coupling arrangement 115 thereupon. Figure 23 illustrates this arrangement assembled.

[0091] Directing attention to Figures 24-26, the rotator module 510 is comprised of a rotator 514 between a first end 516 and a second end 518. The rotator 514 is comprised of a first part 520 rotatably connected to a second part 522 and further includes a driver 524 to mechanically rotate the first part 520 relative to the second part 522 thereby providing rotation between the module first end 516 and the module second end 518. The driver 524 rotates a driver gear which mates with an engaging gear on the second part 522 to provide relative rotation between the first part 520 and the second part 522. The driver 524 may be a hydraulically driven motor or in the alternative, may be an electric motor. The rotator module has a standardized distal coupling arrangement 115 at the first end 516 and a standardized proximal coupling arrangement 55 at the second end 518.

[0092] Although Figures 22 and 23 illustrated a bucket 512 secured to the stick wing 50 through a rotator module 510, as illustrated in Figures 27 and 28, it is entirely possible to mount the bucket 512 directly to the stick wing 50.

[0093] Figures 29 and 30 illustrate an exploded and an assembled view of a claw 530 secured to the stick wing 50 through a rotator module 510. The claw 530 may be comprised of two tines 532, 534 pivotally secured to the body 536 of the claw and operated by hydraulic cylinders (not shown).

[0094] Figures 31 and 32 illustrate a hammer 540 secured to the stick wing 50 in a typical manner discussed within this application. Depending upon the manufacturer of the hammer, 540, it may be necessary to install a fitting plate 542 which includes a distal coupling arrangement 115 similar to those discussed herein. With such an arrangement, the hammer

540 may be mounted via the stick wing 50 to the stick 20 of a construction machine. Note the hydraulic cylinder 40 (Figure 2) has been removed in Figure 32.

[0095] As previously stated, while a module having a proximal coupling arrangement on one end and a distal coupling arrangement on the opposing end has been referred to as an intermediate module, a module having only a standardized distal coupling arrangement at one end may be referred to as a terminal module. In particular, the multi-tool 360 (Figure 15) may be considered a terminal module as may the bucket 512 (Figure 27), claw 530 (Figure 29), and hammer 540 (Figure 31).

[0096] What has so far been discussed are proximal coupling arrangements and distal coupling arrangements all compatible with one another. Such arrangements may typically be associated with a construction machine having a specific design capacity. However, it is entirely possible, depending upon the intended loading of a construction machine, to mate a coupling arrangement of one size with a coupling arrangement of a different size. In particular and with attention directed to Figures 33 and 34, a reducer module 550 is comprised of a first end 552 having a distal coupling arrangement 115 and a second end 554 having a proximal coupling arrangement but proportionately smaller to accommodate a proximal coupling arrangement also proportionately smaller for an adjacent module. In particular, the distance between slots in the distal coupling arrangement 115 is $L1$ and the distance between the center lines of the protrusions 557, 558 for the proximal coupling arrangement 55, which normally would extend within the slots 555, 556, is $L2$ which, as illustrated in Figure 34, is less than $L1$.

[0097] In the alternative, an enlarger module 560 may have a first end 562 with a distal coupling arrangement having a distance between slots 566, 567 of $L3$ with a second end 564 having a distance $L4$ between protrusions 568, 569 wherein $L4$ is greater than $L3$ and the standardized proximal coupling arrangement 55 is proportionately smaller than the standardized distal coupling arrangement 115.

[0098] It should be noted that the size and the spacing of the mounting holes for each adapter will also change depending on the size of the coupling arrangement.

[0099] Figure 37 illustrates a construction machine 12 with a boom 15 and a stick 20 with a stick wing 50 attached thereto and a supplemental extension arm 570 attached to the wing 50. An electric magnet 575 is suspended by cables 577 from the supplemental extension arm 570. The electric magnet must be powered by an electric cable 578 extending all of the way from the tractor 12 to the magnet 575 and, as a result, the electrical cable 578 is exposed not only to the motion of the boom 15 and the stick 20, but furthermore, is exposed to the

environment which may include demolition debris contacting or severing the electrical cable 578. As a result, Figure 38 illustrates a modified extension arm 579 which is identical to the stick 20 previously described with the exception of access to the internal frame of the modified extension arm 579 to protect the electrical cable. In particular, the modified extension arm 579 includes a first window 581 which provides access to the internal frame of the modified extension arm 579 and a second window 583 which together provide an entrance point and an exit point for the electrical cable 578.

[00100] Supplemental extension arm 570 is illustrated in Figures 39 and 40 and just as with the modified extension arm 579, includes a first window 585 providing an entrance to the internal frame and a second window 587 providing an exit from the internal frame, thereby protecting the electrical cable 578 along the length of the supplemental extension arm 570. By doing so, the electrical cable 578 powering the magnet 575 is shielded along the segments of the construction machine where the cable 578 would normally be most vulnerable. The supplemental extension arm 570 has lifting slots 572, 573 extending therethrough suitable to accept the tines of a forklift or suitable to accept a cable sling for lifting. Such lifting slots may also be included in the modified extension arm 579 illustrated in Figure 38.

[00101] Figures 41A-41E illustrate the versatility of a construction machine 10 having a hydraulically activated boom 15, a hydraulically activated stick 20 and a hydraulically activated supplemental extension arm 570. As may be seen in the sequence presented in Figures 41A-41E, the end 589 of the supplemental extension arm 570 is capable of being rotated 360°. Such a range of motion provides a machine operator with tremendous flexibility and versatility.

[00102] Figure 42 illustrates a construction machine 12 with a boom 15 and a boom wing 70 attached thereto. The supplemental extension arm 570 is connected to the boom wing 70. Attached to the supplemental extension arm 570 through a support cable 577 is an electric magnet 575 powered by an electric cable 578. Therefore, it should be apparent that the supplemental extension arm 570 having an electric magnet 575 attached thereto may be secured to either the stick wing 50, as illustrated in Figure 37, or the boom wing 70 as illustrated in Figure 42.

[00103] Figures 43A-43C illustrate a telescopic adapter module 600 secured to the boom wing 70 of a construction machine 12. It should be appreciated that the telescopic adapter module 600 may also be mounted to a stick wing (not shown) or one of the intermediate adapters previously discussed herein.

[00104] The telescopic adapter module 600 is comprised of a base 605 with an axially moving nested segment 610 extending from the base 605. As can be seen in Figures 43A-43B, multiple nesting segments are possible. In particular, Figure 43C illustrates a second nested segment 615 extending from the first nested segment 610. At the furthest end of nested segment 615 is a standardized proximal coupling arrangement 55 of a particular size. A central cylinder 620 may be activated to extend the segments 610, 615 from the base 605. In one embodiment of the subject invention, nested segment 615 is the only segment that includes the standardized proximal coupling arrangement 55. However, in another embodiment, the base 605 includes a standardized proximal coupling arrangement 55 of one size, the first nested segment 610 includes a standardized proximal coupling arrangement 55 of another size and, as mentioned, the second nested segment 615 includes yet another standardized proximal coupling arrangement 55 of yet another size. As a result, the telescopic adapter module 600 functions not only as a telescoping unit, but furthermore, provides the versatility to connect any number of different sized standardized distal coupling arrangements to the telescopic adapter module. As seen in Figure 43C, the standardized proximal coupling arrangement 55 becomes progressively smaller in each segment 610, 615 extending away from the base 605. The embodiment illustrated in Figures 43A-43C includes two nested segments 610, 615 extending from a base 605 wherein, the furthest end of each segment 610, 615 has a standardized proximal coupling arrangement 55.

[00105] The subject invention is also directed to a method of interchanging one module with another module to provide versatility to a construction machine. In particular, and with attention directed to Figures 22-23, the rotator module 510 may be secured between the stick wing 50 and the bucket 512 with the standardized coupling arrangements mating with one another. Additionally, with attention directed to Figures 27-28, the bucket 512 may be attached directly to the stick wing 50. As a result, it should be apparent that the modules described throughout this application may be attached in any number of combinations to provide configurations desired by the machine owner. It is also possible to remotely lock and unlock these modules to one another by aligning the hole patterns between a standardized distal coupling arrangement and a standardized proximal coupling arrangement and securing retention pins through the matching holes as described herein.

[00106] It should now be appreciated that the system, in accordance with the subject invention, provides tremendous versatility for using the intermediate modules and the terminal modules to assemble from the stick or the boom of a construction machine and almost limitless number of different combinations to accommodate the needs of a machine

operator since all of the intermediate modules and the terminal modules are compatible with one another through the standardized coupling arrangements.

[00107] While specific embodiments of the invention have been described in detail, it will be appreciated by those skilled in the art that various modifications and alternatives to those details could be developed in light of the overall teachings of the disclosure. The presently preferred embodiments described herein are meant to be illustrative only and not limiting as to the scope of the invention which is to be given the full breadth of the appended claims and any and all equivalents thereof.

CLAIMS:

1. A modular system for connecting any one of a plurality of modules to an extension arm of a construction machine comprising:
 - a) a wing secured to the end of the extension arm, wherein the wing has a standardized proximal coupling arrangement with a pair of spaced-apart parallel plates having mounting surfaces;
 - b) a first plurality of modules, wherein each module has a first end adapted to be secured to the wing and comprises a standardized distal coupling arrangement with a pair of spaced-apart parallel plates having mounting surfaces adapted to be coupled with the standardized proximal coupling arrangement so that each module alone may be interchangeably secured to the wing;
 - c) wherein each of the pair of wing plate mounting surfaces associated with the proximal coupling arrangement is positioned adjacent to one of the pair of module plate mounting surfaces associated with the distal coupling arrangement;
 - d) at least one common mating hole extends through an adjacent wing plate and module plate mounting surfaces;
 - e) a pin adapted to slide into each of the at least one mating holes to restrict translation of the wing plate and the module plate relative to one another in a direction parallel to the plates;
 - f) wherein the mounting surface of the distal coupling arrangement has a hole pattern and the mounting surface of the proximal coupling arrangement has an aligned matching hole pattern;
 - g) wherein the plates are secured together with retention pins extending through matching holes; and wherein there are at least two spaced apart holes within each hole pattern;
 - h) wherein one of the coupling arrangements further includes with each opposing plate a reinforcement plate spaced next to the opposing plate to define a slot therebetween, wherein the reinforcement plate has an identical hole pattern such that the plate of the other coupling arrangement fits within the slot and is secured therebetween for improved support; and

i) wherein the first plurality of modules is one of a terminal module or an intermediate module, wherein the intermediate module has a whole pattern that is symmetric about a common longitudinal axis of that module.

2. The modular system according to claim 1, wherein the extension arm is a boom on the construction machine.

3. The modular system according to claim 1, wherein the extension arm is a stick on the construction machine.

4. The system according to claim 1, wherein either the distal coupling arrangement or the proximal coupling arrangement is comprised of a hooking plate with a hole therethrough and a spaced apart hook and the other coupling arrangement is comprised of a hooked plate with a spaced apart hole therethrough and a pivot pin, such that the hook of the hooking plate may engage the pivot pin of the hooked plate and the spaced apart holes aligned to receive a support pin, thereby providing a secure coupling between the two coupling arrangements.

5. The system according to claim 1, wherein either the distal coupling arrangement or the proximal coupling arrangement is comprised of a plate having a hole extending therethrough and a wide protruding end with a protrusion extending transversely therefrom and the other of the arrangements is comprised of a plate having a hole extending therethrough and a matching wide receiving end with a recess extending transversely therein, wherein the recess has a complimentary shape to the protrusion, such that when the wide end are brought in abutment with one another, the protrusion engages the recess, the holes are aligned and a retention bolt placed therein the holes to provide a secure coupling between the two coupling arrangements.

6. The system according to claim 1, wherein the module is a terminal module with a standardized distal coupling arrangement.

7. The system according to claim 6, wherein the terminal module is a multi-tool.

8. The system according to claim 6, wherein the terminal module is a bucket.
9. The system according to claim 6, wherein the terminal module is a claw.
10. The system according to claim 6, wherein the terminal module is a hammer.
11. The system according to claim 10, wherein the terminal module is a supplemental extension arm.
12. The system according to claim 11, further including an electric magnet suspended from the supplemental extension arm.
13. The system according to claim 12, wherein the supplemental extension arm has an internal opening extending along the length and further including an electrical wire extending therein and connected to the magnet to power the magnet.
14. The system according to claim 13, wherein the supplemental extension arm has lifting slots extending therethrough.
15. The system according to claim 1, wherein the module is an intermediate module which further includes a second end comprising a standardized distal coupling arrangement such that the module at the first end has a standardized proximal coupling and at the second end has a standardized proximal coupling arrangement, wherein the intermediate module may be secured between two other modules having an identical distal coupling arrangement or proximal coupling arrangement.
16. The system according to claim 15, wherein the intermediate module is a tool adapter to accommodate a multi-tool.

17. The system according to claim 16, wherein the multi-tool has a front end with a standardized proximal coupling arrangement and a hydraulic cylinder extending therefrom, wherein the tool adapter is comprised of a sleeve with a longitudinal axis and a passageway extending therethrough along the longitudinal axis, wherein the sleeve overlaps the hydraulic cylinder and has a standardized proximal coupling arrangement, and wherein the standardized proximal coupling arrangement is secured to the standardized distal coupling arrangement of the multi-tool.

18. The system according to claim 15, wherein the intermediate module is an extension module with a support structure between the first end and the second end.

19. The system according to claim 15, wherein the intermediate module is a folding module comprised of a two-part structure between the first end and the second end with a first part and a second part connected at one point by a pivot and at a different point by a driving cylinder such motion of the cylinder changes the angular orientation of the first part relative to the second part.

20. The system according to claim 15, wherein the intermediate module is a folding adapter module for securing to a multi-tool, wherein the multi-tool has a front end with a standardized proximal coupling arrangement and a hydraulic cylinder extending therefrom, wherein the folding adapter is comprised of:

a) an adapter having a sleeve with a longitudinal axis and a passageway extending therethrough along the longitudinal axis, wherein the sleeve overlaps the hydraulic cylinder and has a standardized distal coupling arrangement, and wherein the standardized distal coupling arrangement is secured to a standardized proximal coupling arrangement on the multi-tool; and

b) a folding member attached to the adapter, wherein the folding member is comprised of a two-part structure between the first end and the second end with a first part connected to the adapter and also connected to a second part, wherein the first part and second parts are connected to one another at one point by a pivot and at a different point by a driving cylinder such that motion of the cylinder changes the angular orientation of the first part relative

to the second part and as a result, changes the angular orientation of the adapter and the second part.

21. The system according to claim 15, wherein the intermediate module is a rotator module comprised of a rotator between the first end and the second end, wherein the rotator is comprised of a first part rotatively connected to a second part and further including a driver to mechanically rotate the first part relative to the second part, thereby providing rotation between the module first end and the module second end.

22. The system according to claim 15, wherein the intermediate module is a reducer module wherein the standardized proximal coupling arrangement is proportionately larger than the standardized distal coupling arrangement.

23. The system according to claim 15, wherein the intermediate module is an enlarger module wherein the standardized proximal coupling arrangement is proportionately smaller than the standardized distal coupling arrangement.

24. The system according to claim 15, wherein the intermediate module is a telescopic adapter module with at least one axially moving nested segment extending from the base and wherein the furthestmost extending segment is a standardized proximal coupling arrangement.

25. The system according to claim 24, wherein each nested segment has at its furthestmost end a standardized proximal coupling, wherein the standardized proximal coupling arrangement becomes progressively smaller in each segment extending away from the base.

26. The system according to claim 25, wherein the telescopic adapter module has at least two nested segments extending from a base and wherein the furthestmost end of each segment has a standardized proximal coupling arrangement.

27. The system according to claim 15, wherein the first plurality of modules are terminal modules from the group consisting of a multi-tool, a bucket, a claw, a hammer, and a supplemental extension arm, wherein the system further includes a second plurality of modules which are intermediate modules from the group consisting of an extension module, a folding module, a folding adapter module, a rotator module, a reducer module, an enlarger module and a telescopic adapter module, and wherein one of the intermediate modules is attached to the extension arm of the construction machine while one of the terminal modules is attached to the intermediate module.

28. A module for connecting to the extension arm of a construction machine, wherein the module has a body with a first end and a second end with a proximal coupling arrangement associated with the first end and a distal coupling arrangement associated with the second end, wherein the distal coupling arrangement is comprised of a pair of spaced-apart parallel plates, each plate with mounting surface having a hole pattern and the proximal coupling arrangement is comprised of a mating pair of spaced-apart parallel plates, each plate with a mounting surface having an aligned matching hole pattern, wherein the coupling arrangements are complimentary such that a second module having an identical one of the distal coupling arrangement or proximal coupling arrangement may be secured thereto with pins adapted to slide within the holes of the pattern, wherein the module is an extension module with a support structure between the first end and the second end.

29. The module according to claim 28 wherein the module is a folding module comprised of a two-part structure between the first end and the second end with a first part and a second part connected at one point by a pivot and at a different point by a driving cylinder such motion of the cylinder changes the angular orientation of the first part relative to the second part.

30. The module according to claim 28, wherein the module is a folding adapter module comprised of a two-part structure, wherein

a) the first part is an adapter at the module first end having a sleeve with a longitudinal axis and a passageway extending therethrough along the longitudinal axis, wherein the sleeve is adapted to overlap a hydraulic cylinder on the end of a tool; and

b) the second part is a folding member;

c) wherein the first part and second part are connected to one another at one point by a pivot and at a different point by a driving cylinder with a cylinder rod such that motion of the cylinder rod changes the angular orientation of the first part relative to the second part and as a result, changes the angular orientation of the first part to the second part.

31. The module according to claim 28, wherein the module is a rotator module comprised of a rotator between the module first end and the module second end, wherein the rotator has a first part rotatively connected to a second part and further including a driver to mechanically rotate the first part relative to the second part thereby providing rotation between the module first end and the module second end.

32. The module according to claim 28, wherein the module is a reducer module and wherein the standardized proximal coupling arrangement is proportionately larger than the standardized distal coupling arrangement.

33. The module according to claim 28, wherein the module is an enlarger module and wherein the standardized proximal coupling arrangement is proportionately smaller than the standardized distal coupling arrangement.

34. The module according to claim 28, wherein the module is a telescopic adapter module with at least one axially moving nested segment extending from the base and wherein the furthestmost extending segment is a standardized proximal coupling arrangement.

35. The system according to claim 34, wherein each nested segment has at its furthestmost end a standardized proximal coupling, wherein the standardized proximal coupling arrangement becomes progressively smaller in each segment extending away from the base.

36. The system according to claim 35, wherein the telescopic adapter module has at least two nested segments extending from a base and wherein the furthestmost end of each segment has a standardized distal coupling arrangement.

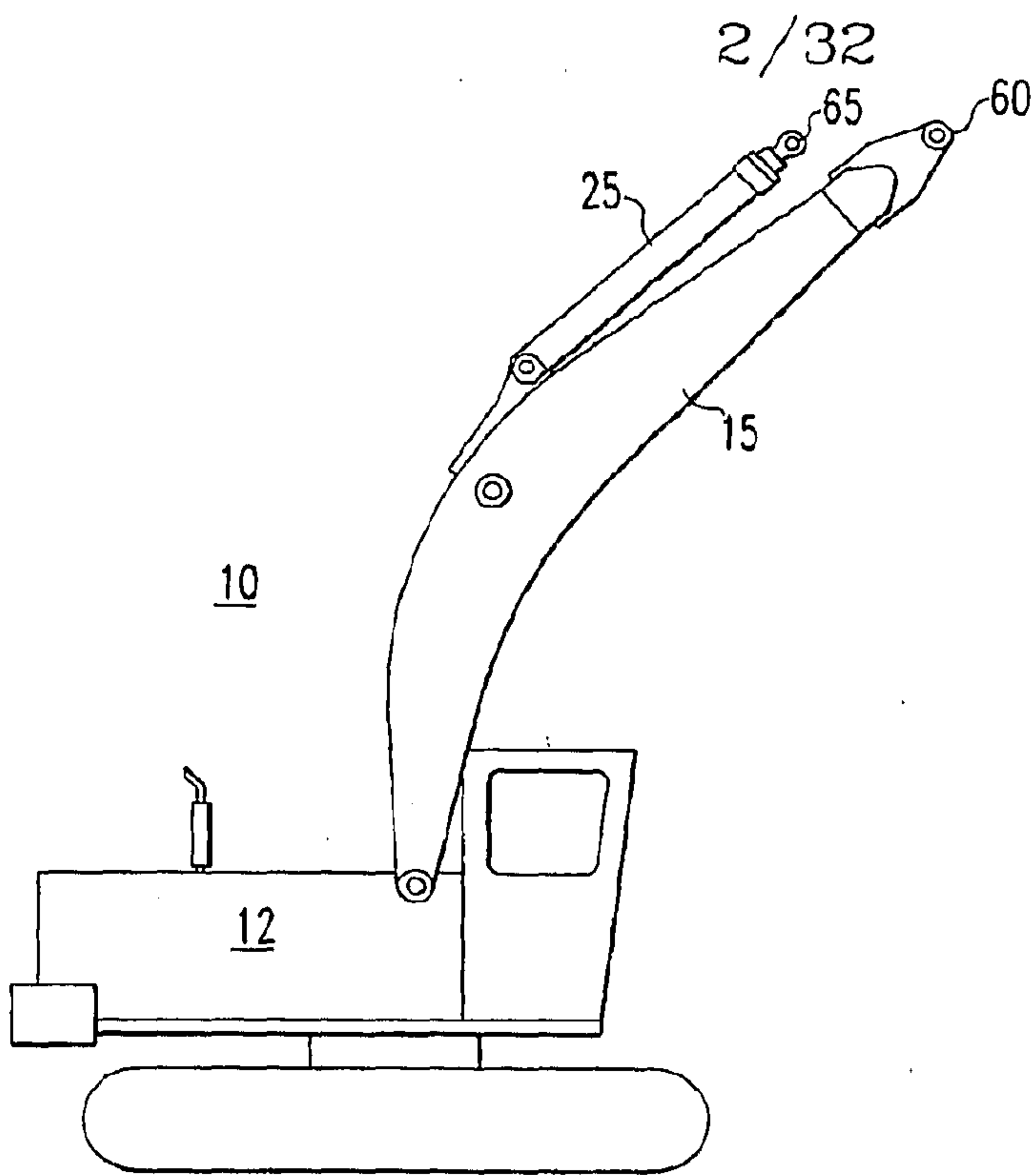


FIG. 3

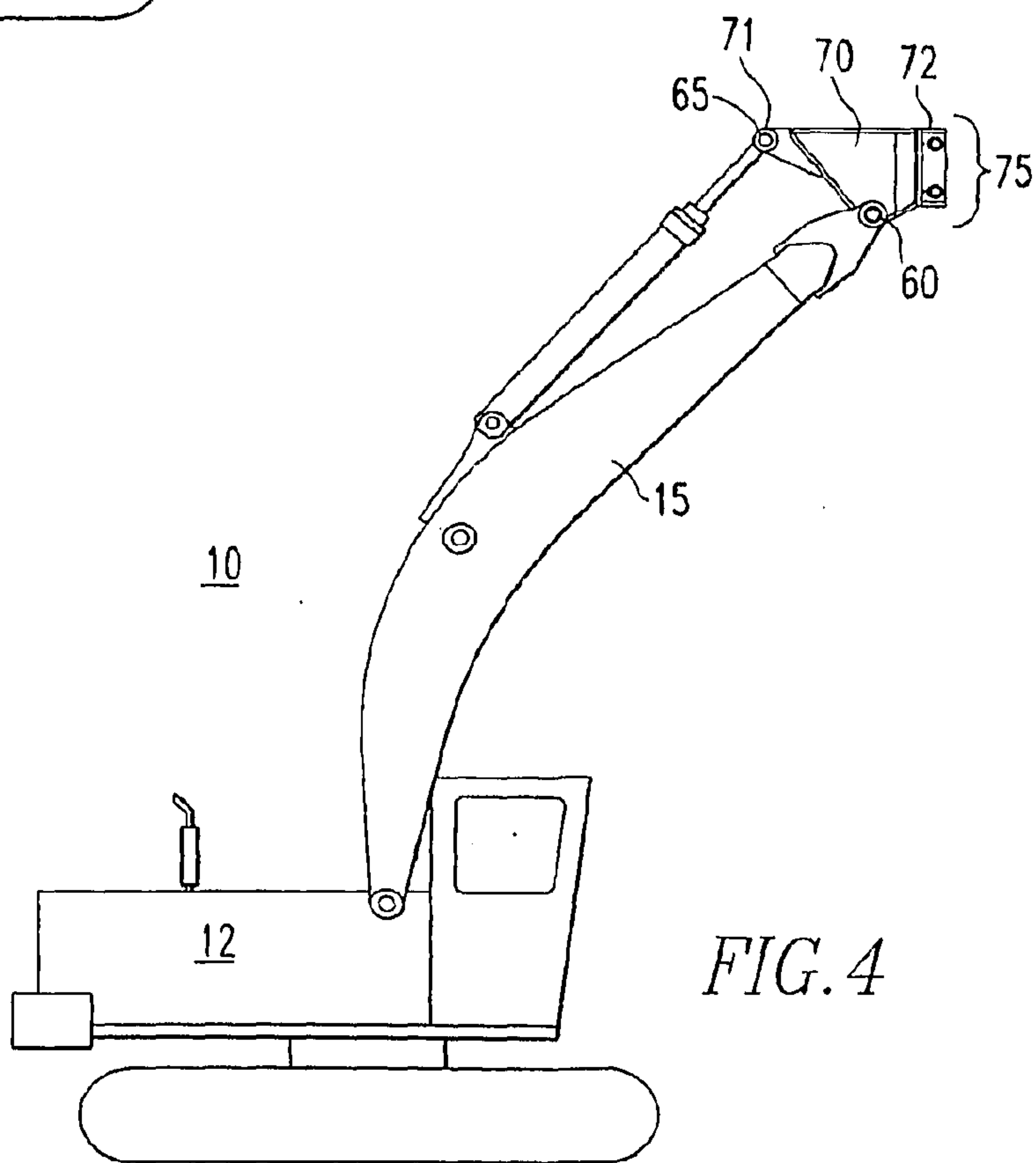


FIG. 4

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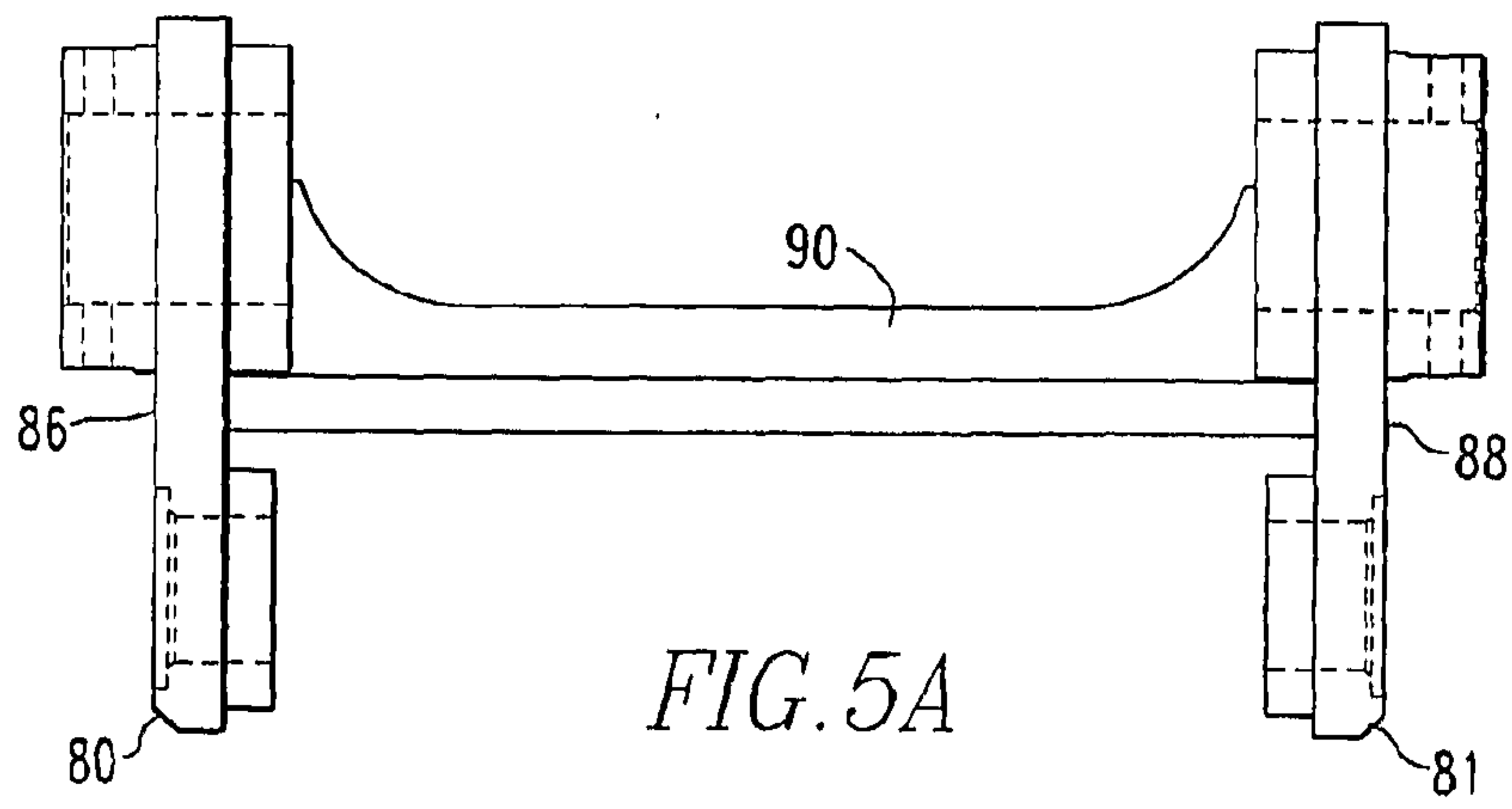


FIG. 5A

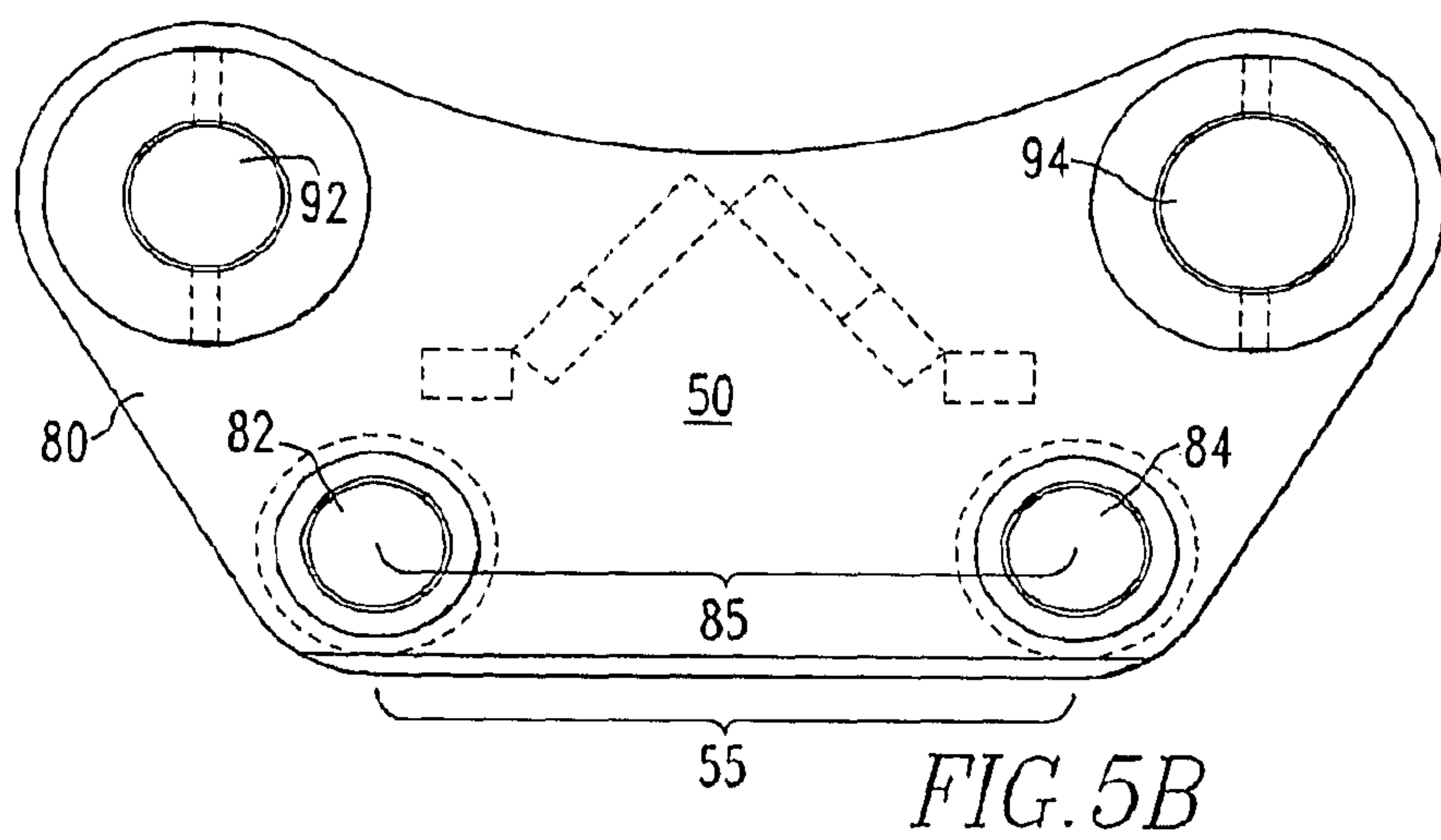
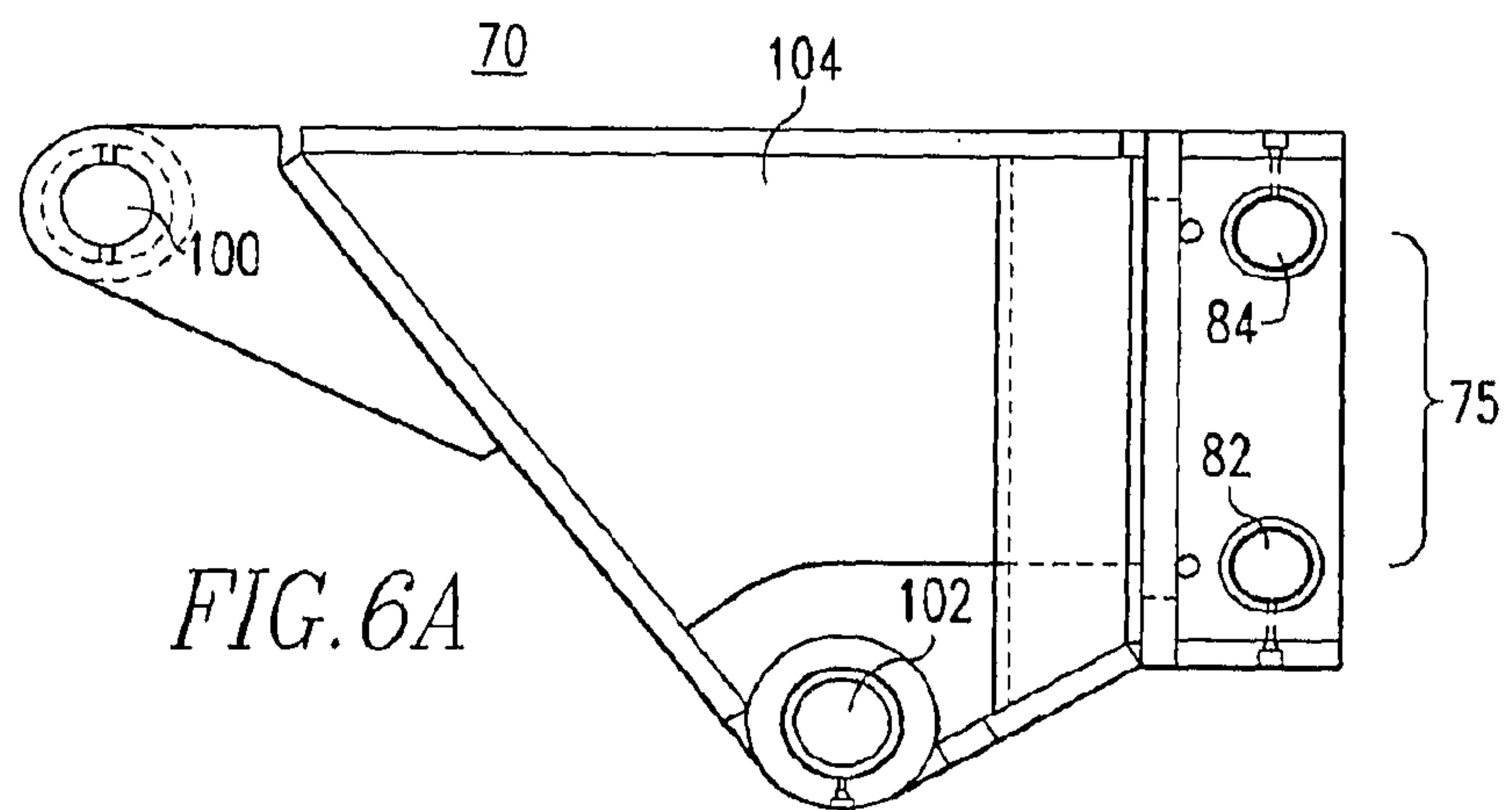
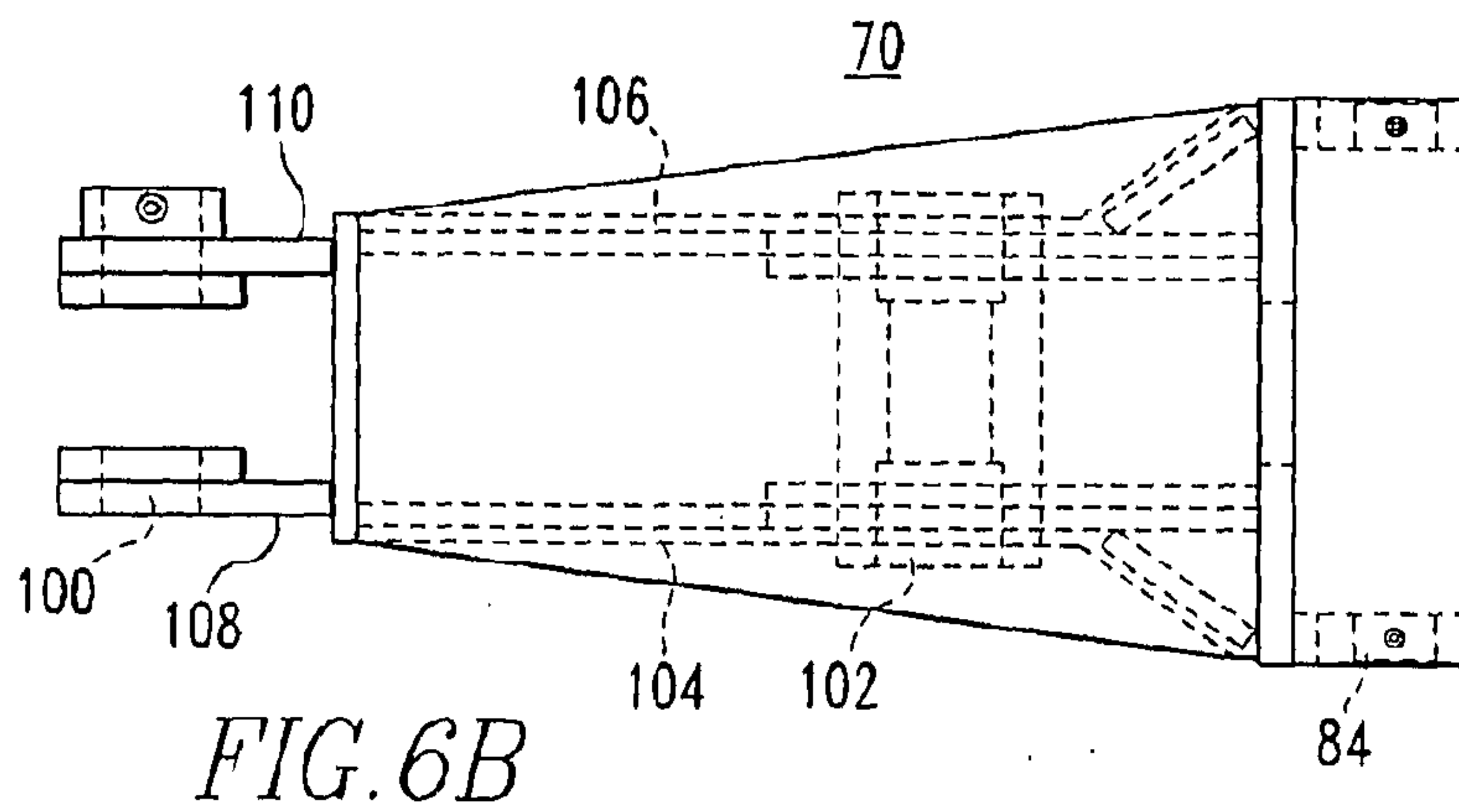


FIG. 5B

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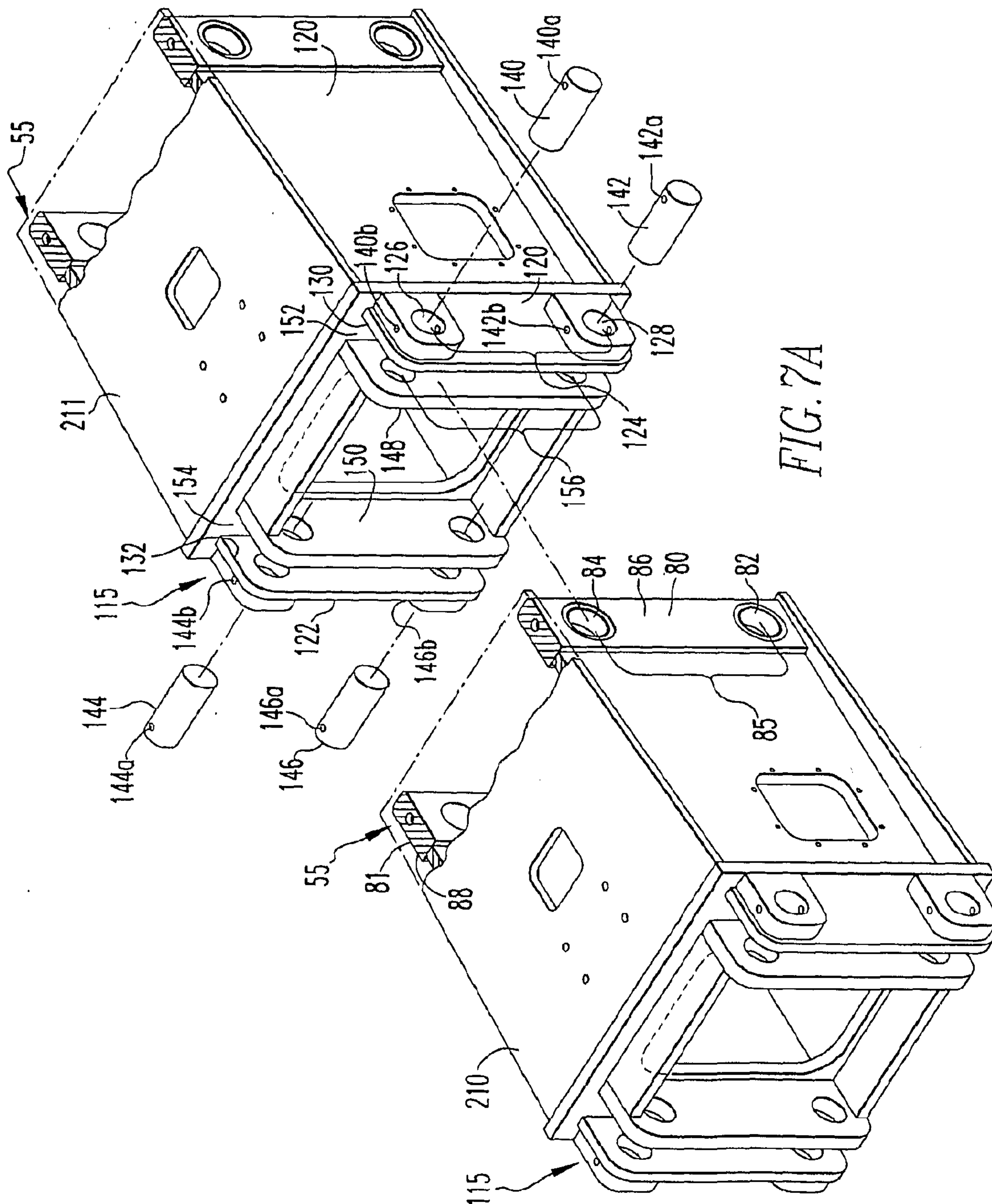
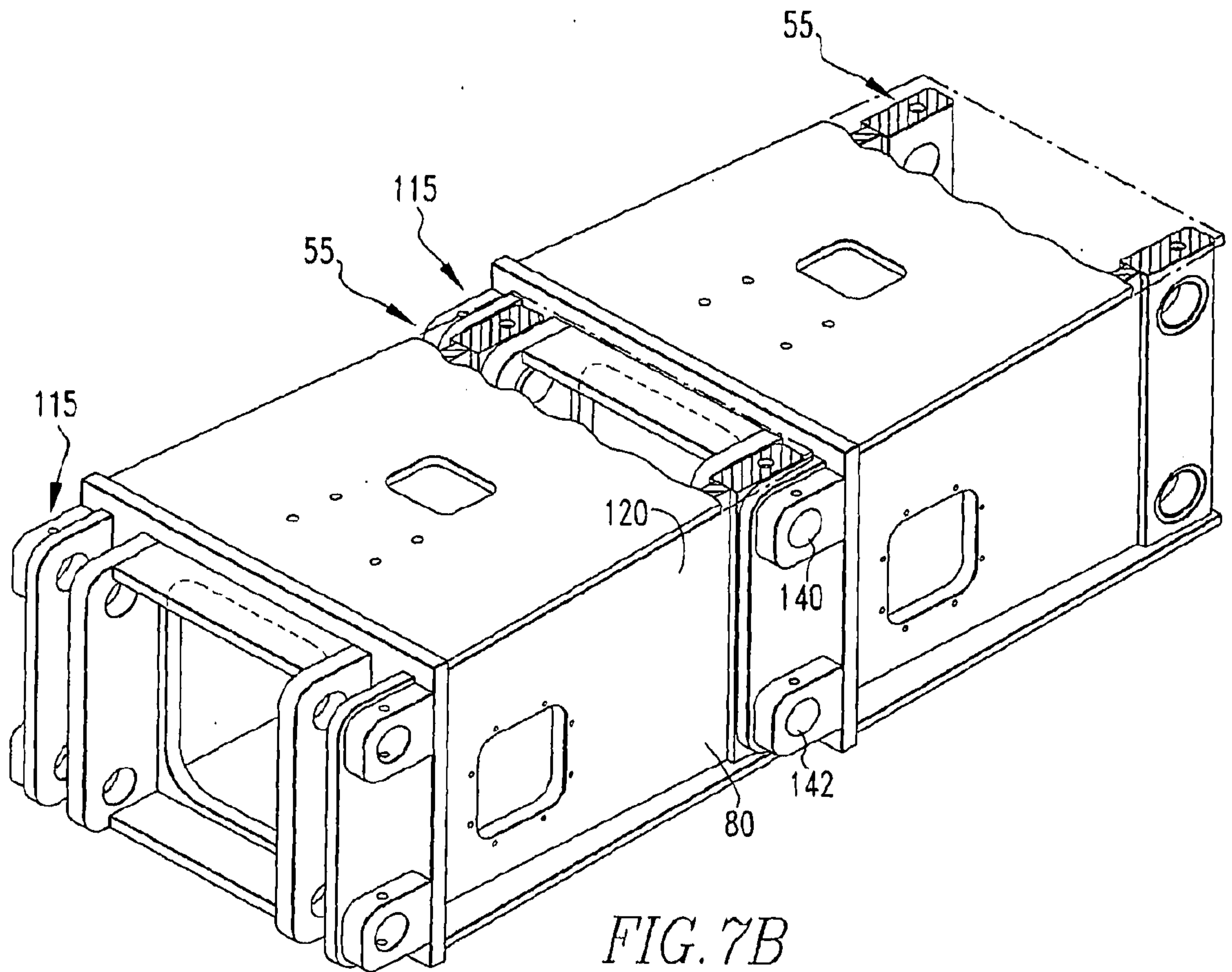


FIG. 7A

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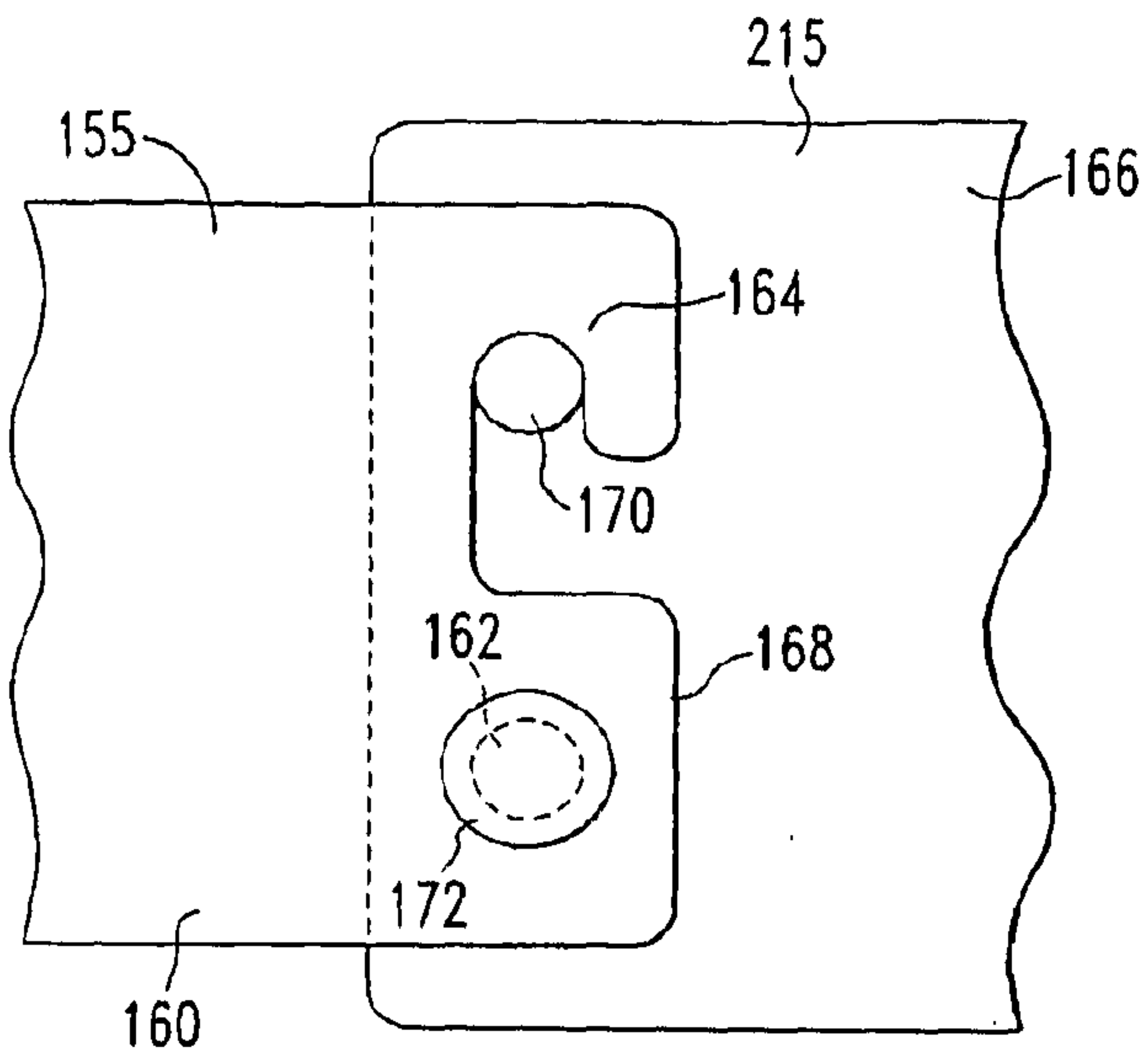


FIG. 8

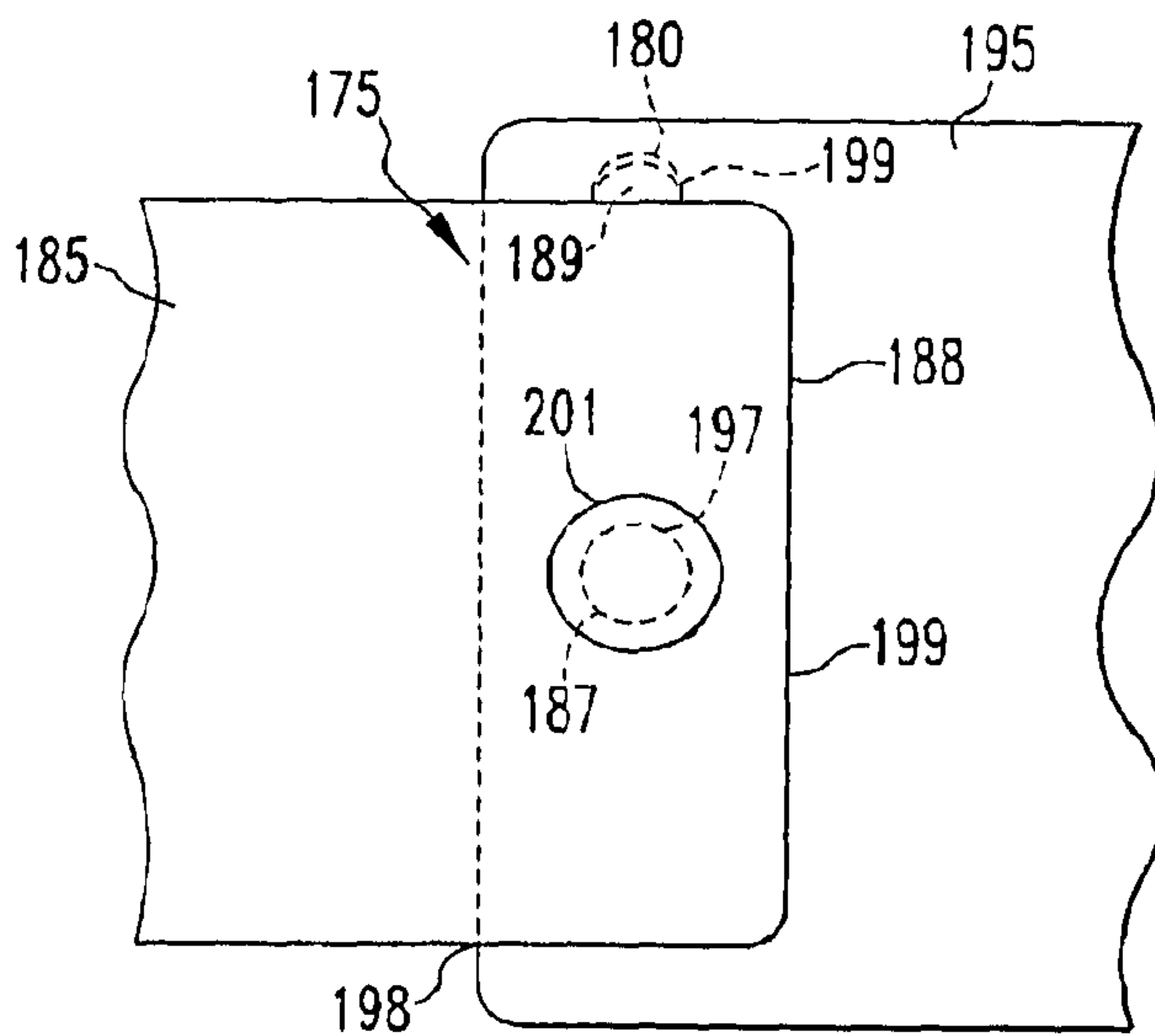


FIG. 9

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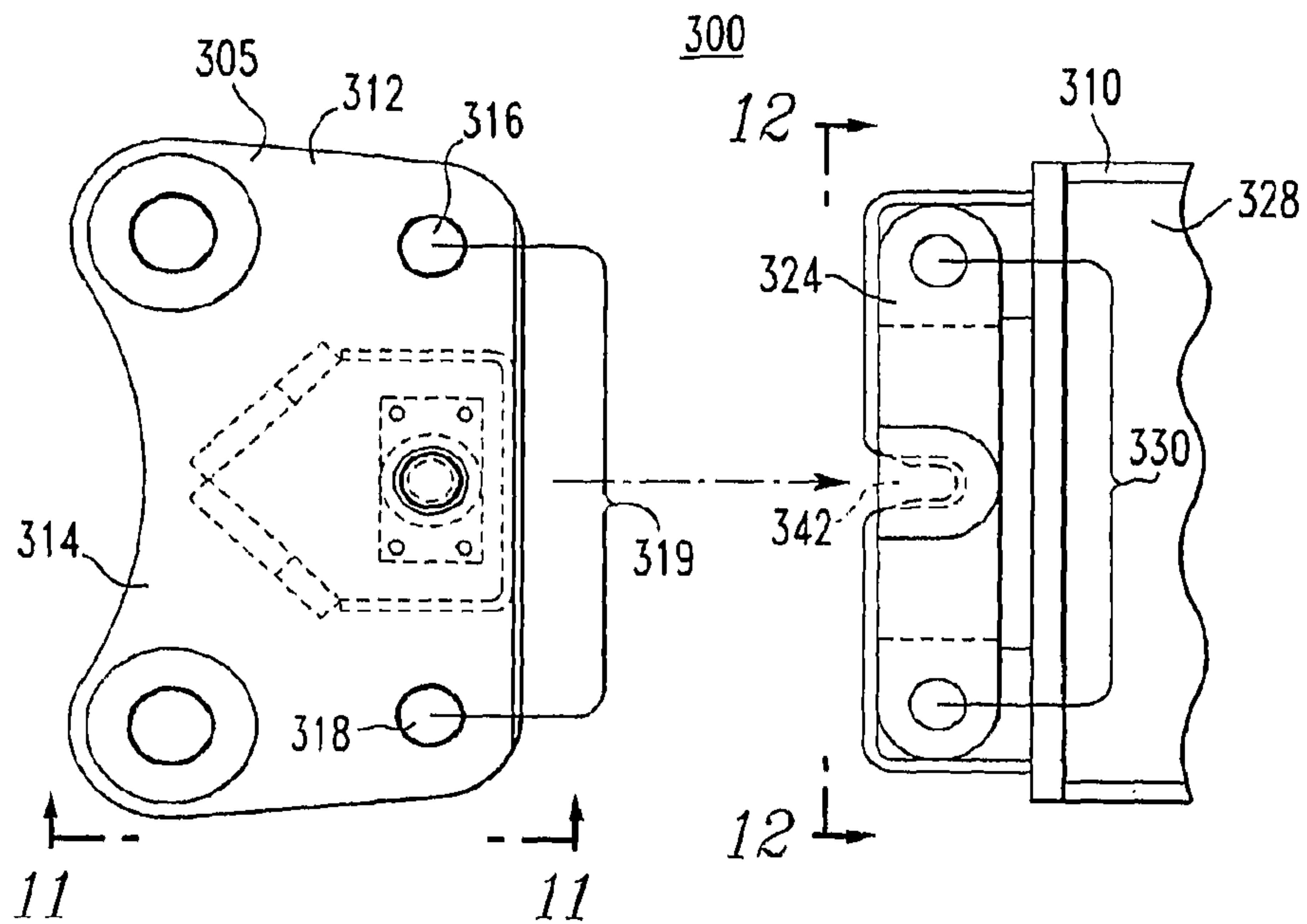


FIG. 10

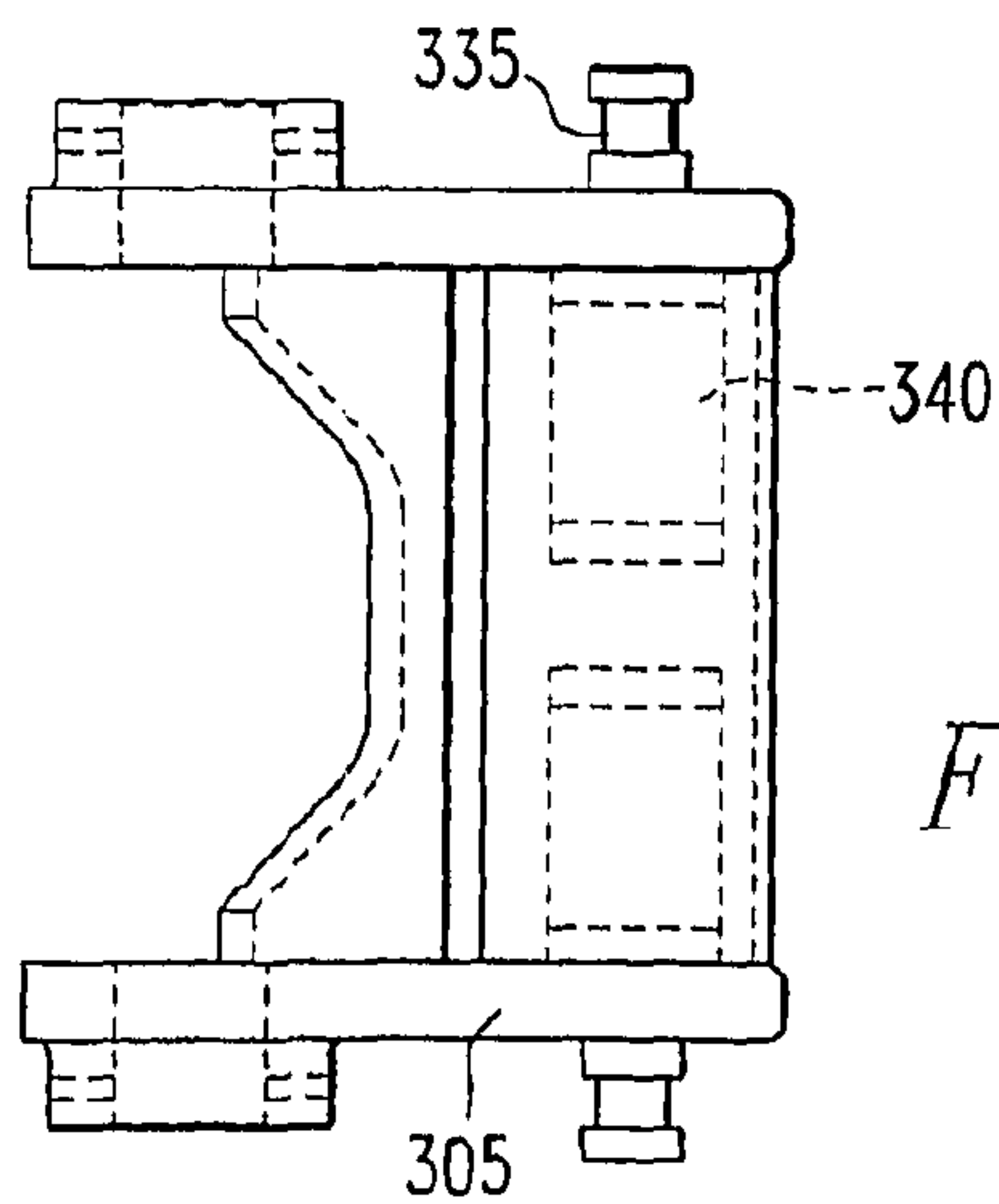


FIG. 11

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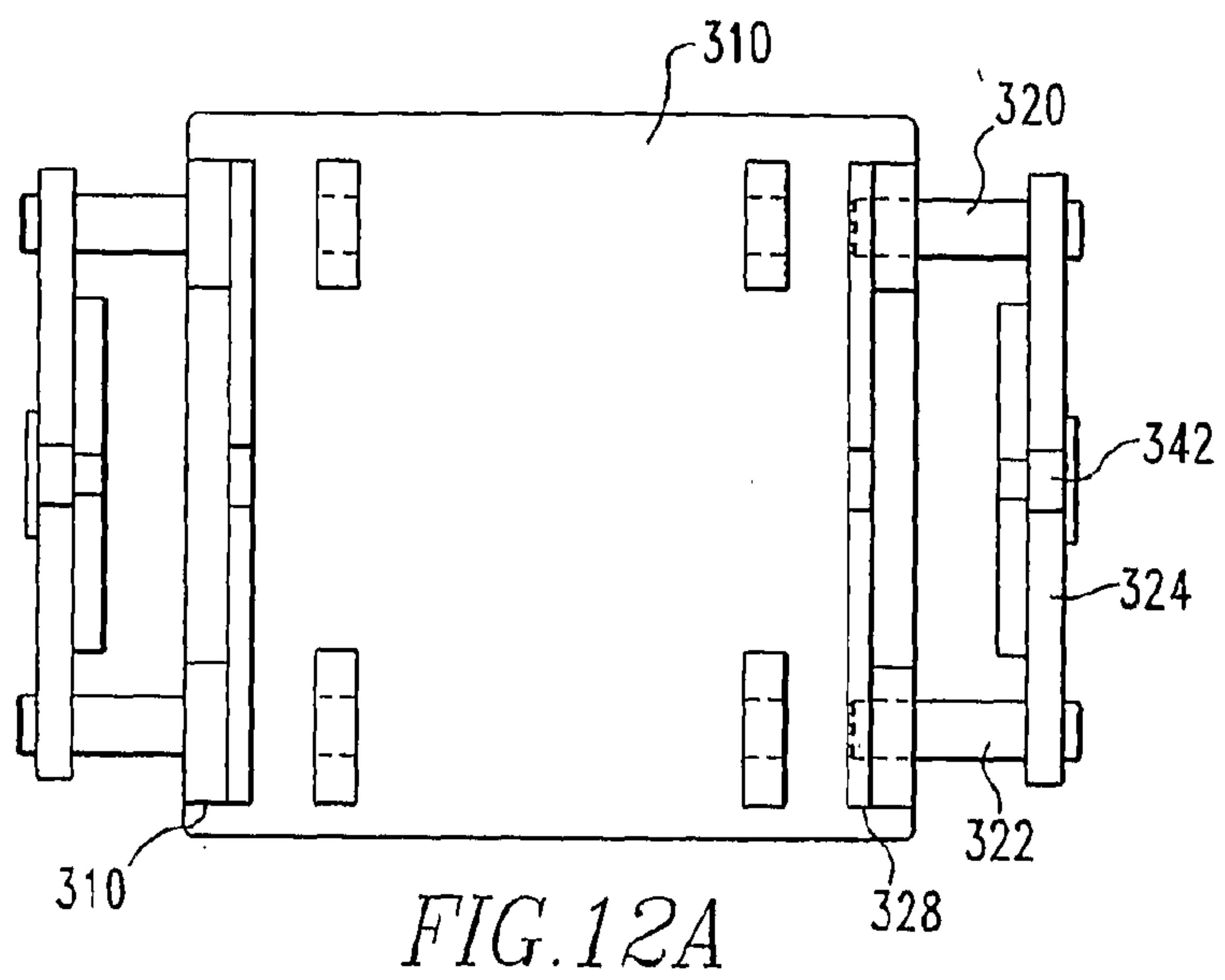


FIG. 12A

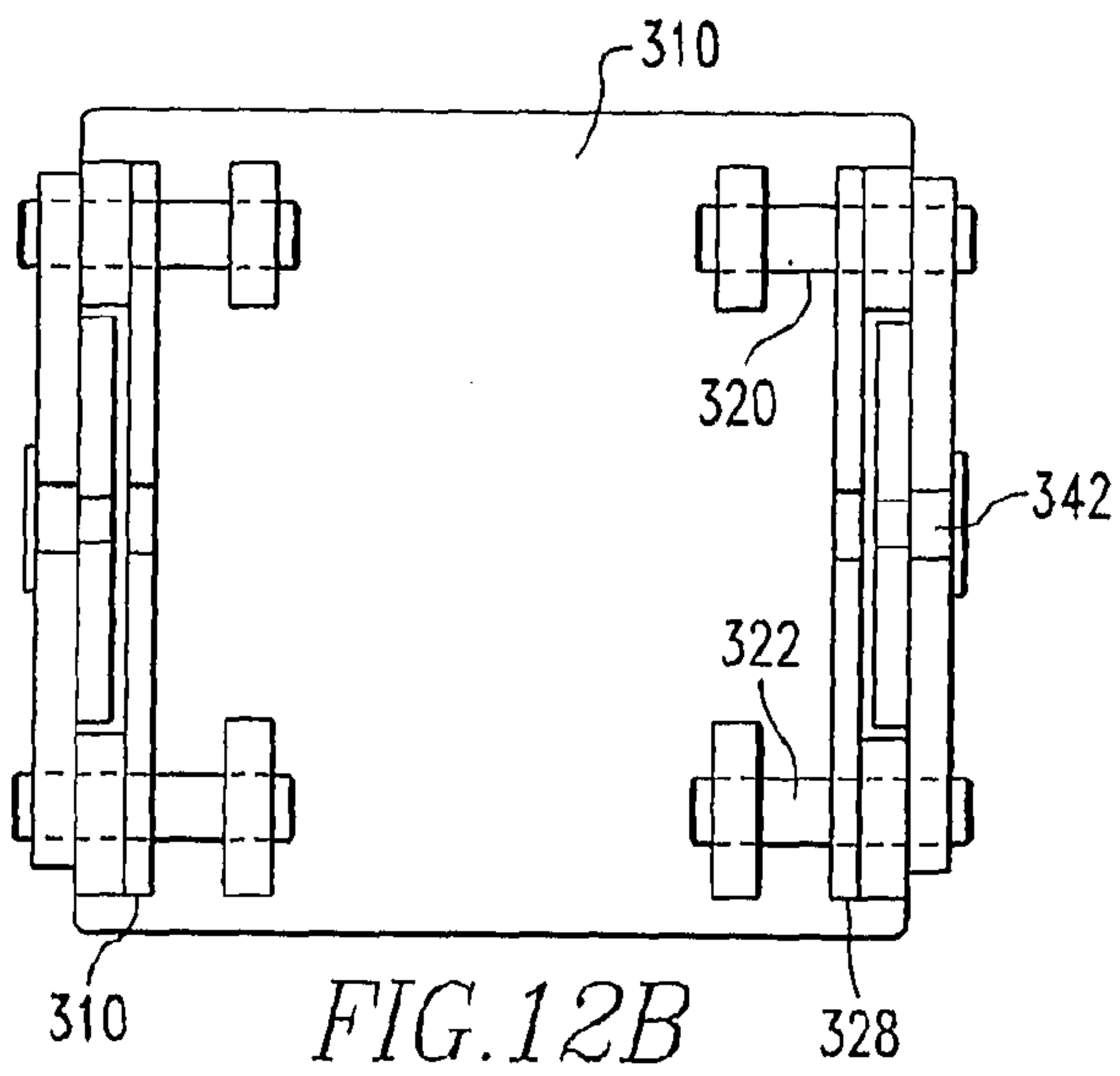


FIG. 12B

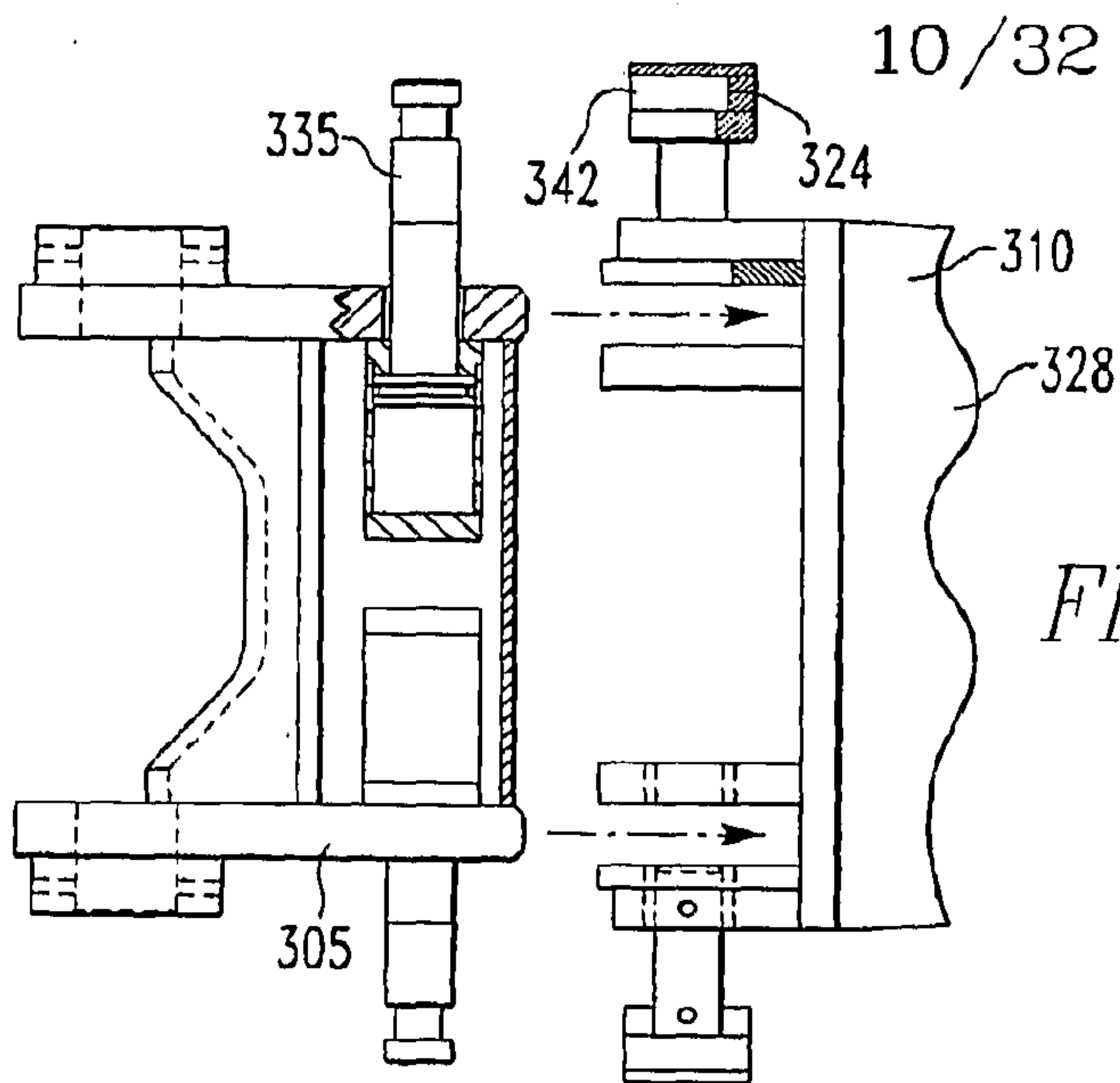


FIG. 13A

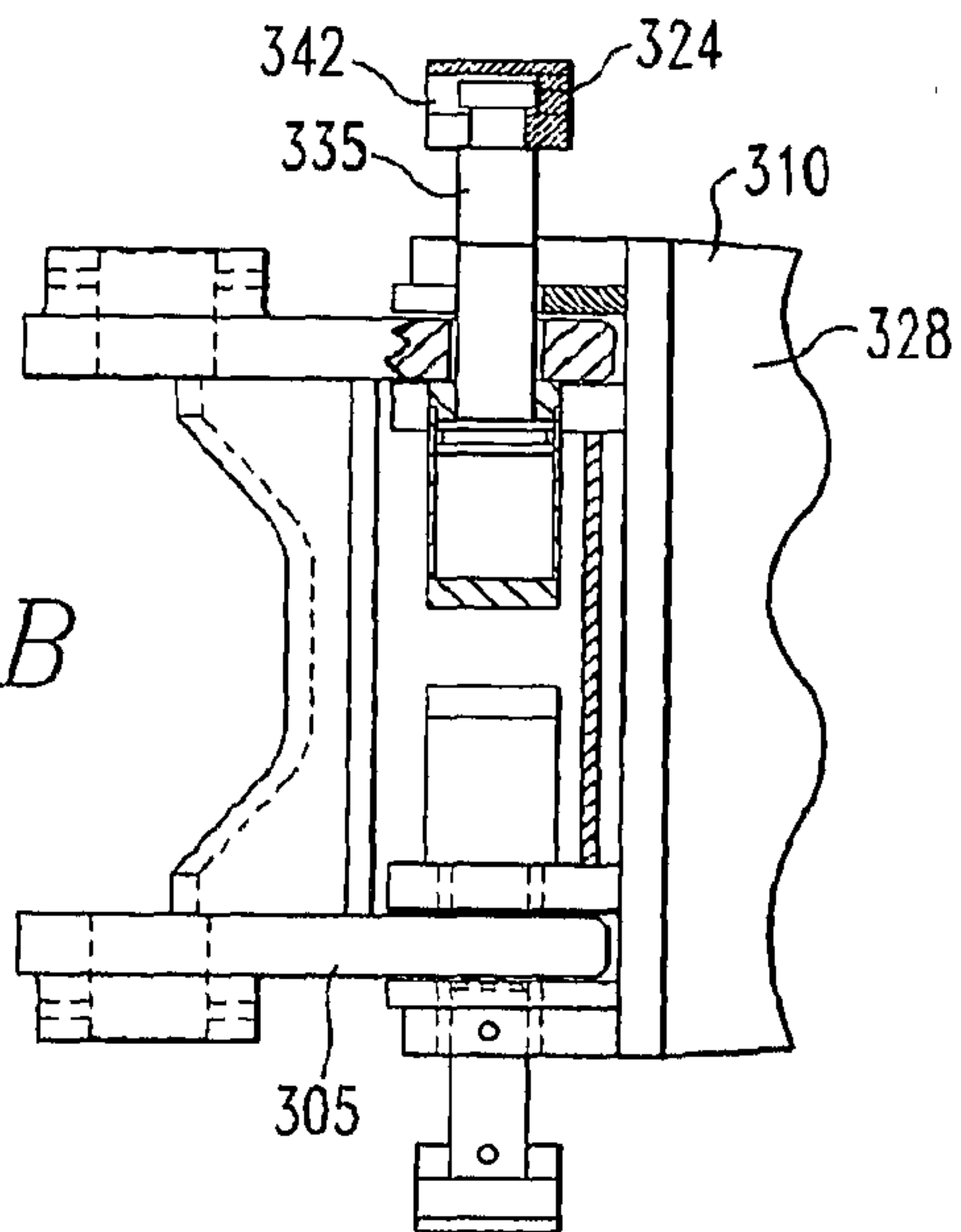


FIG. 13B

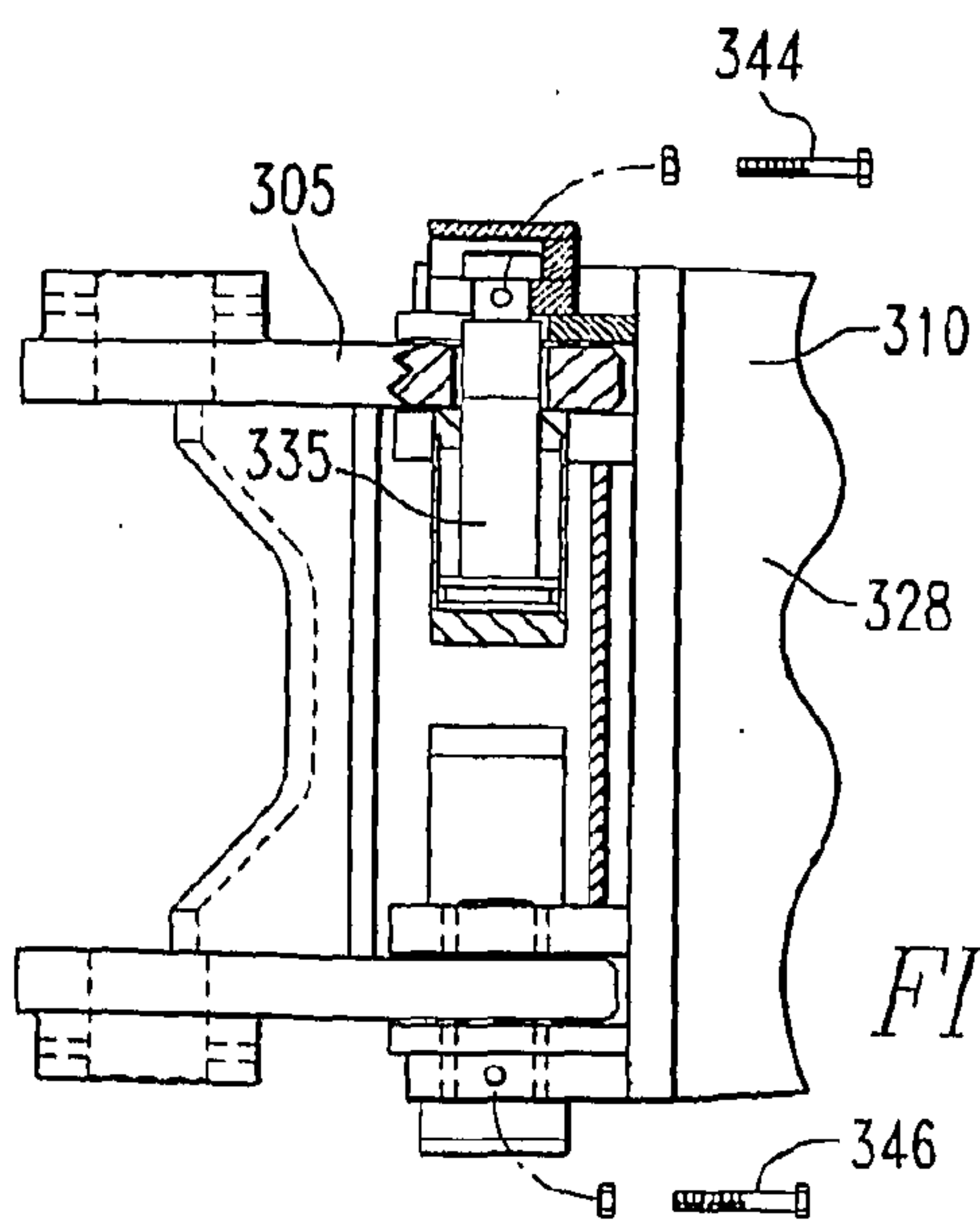
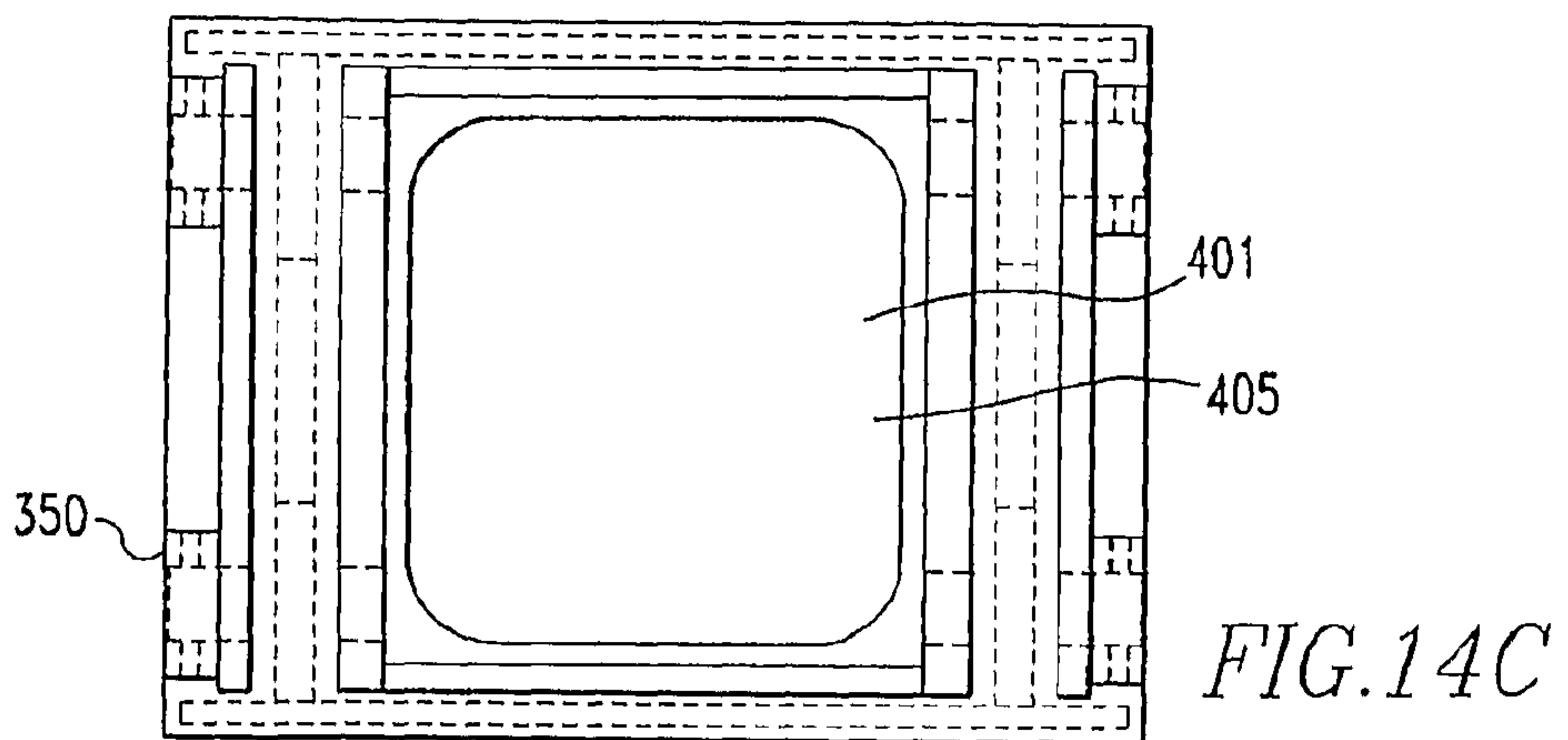
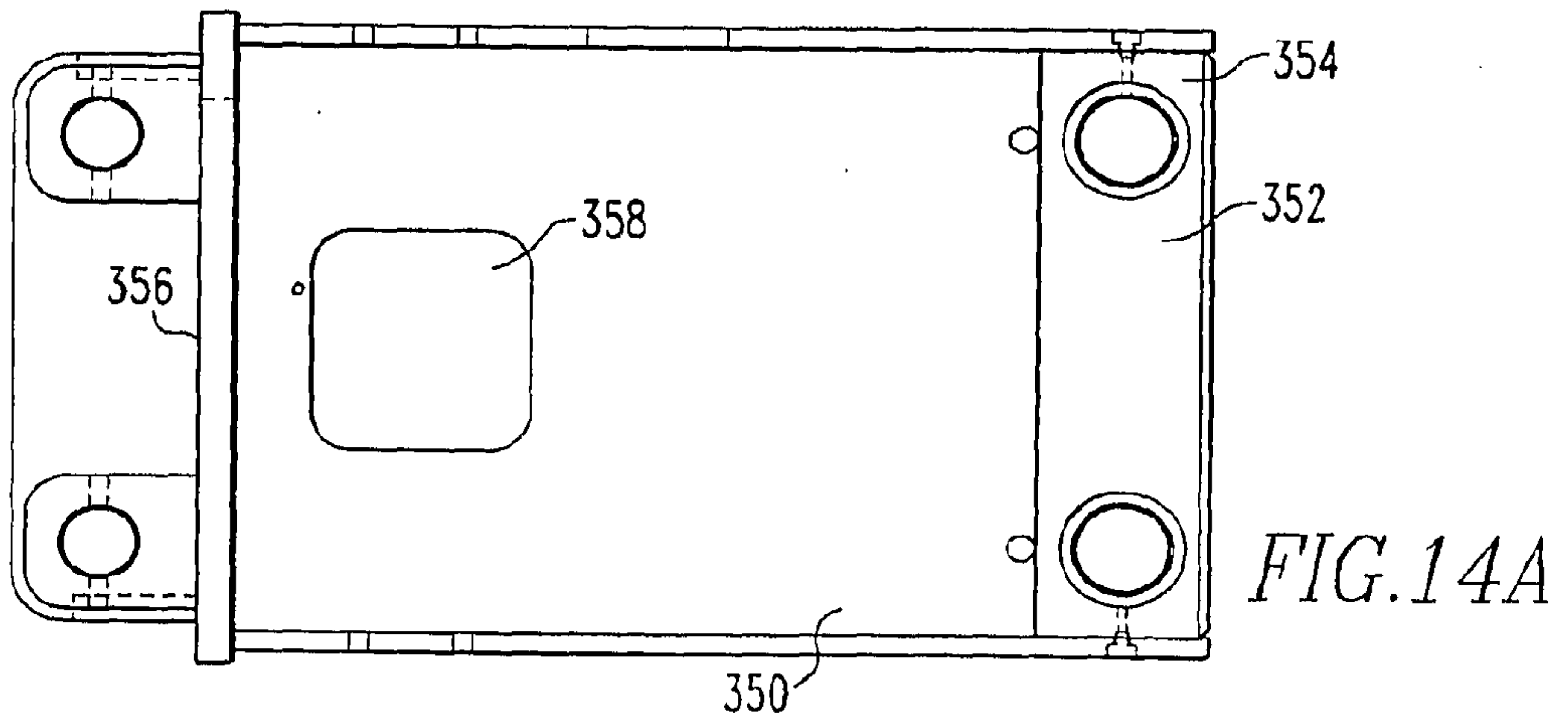
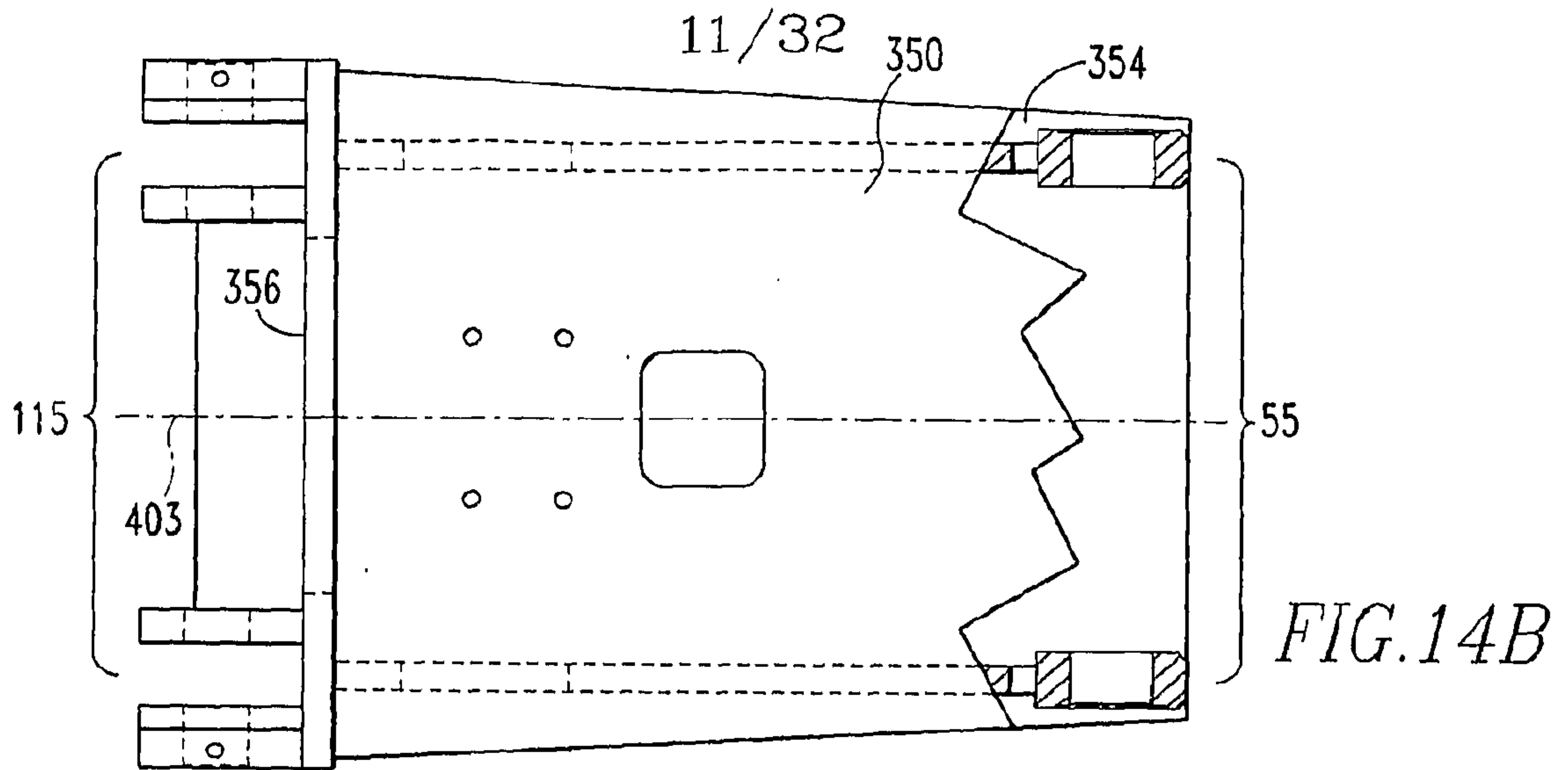


FIG. 13C



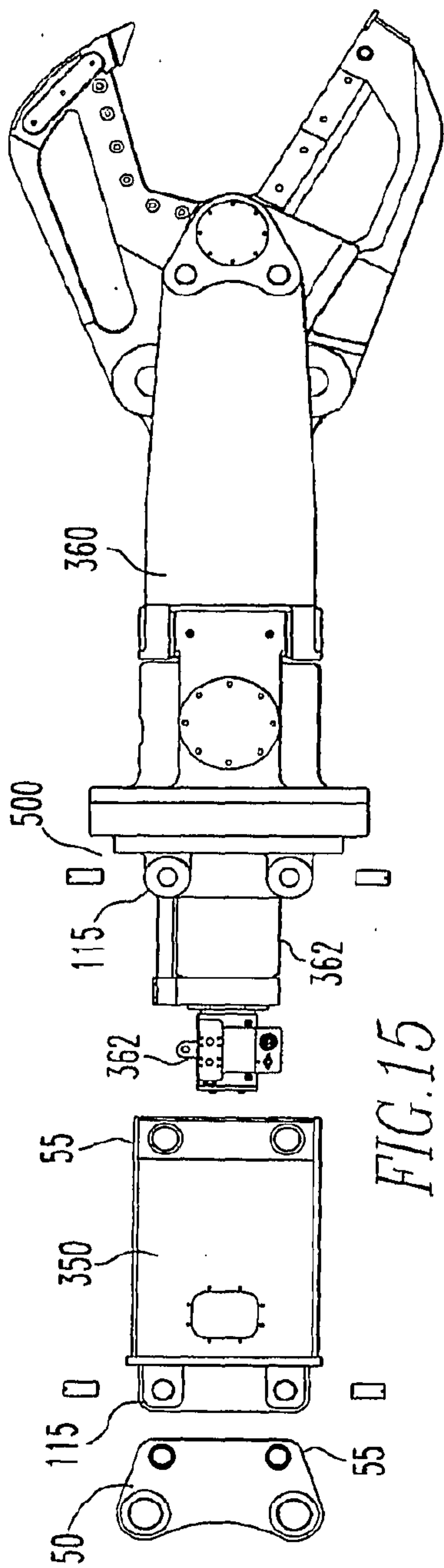


FIG. 15

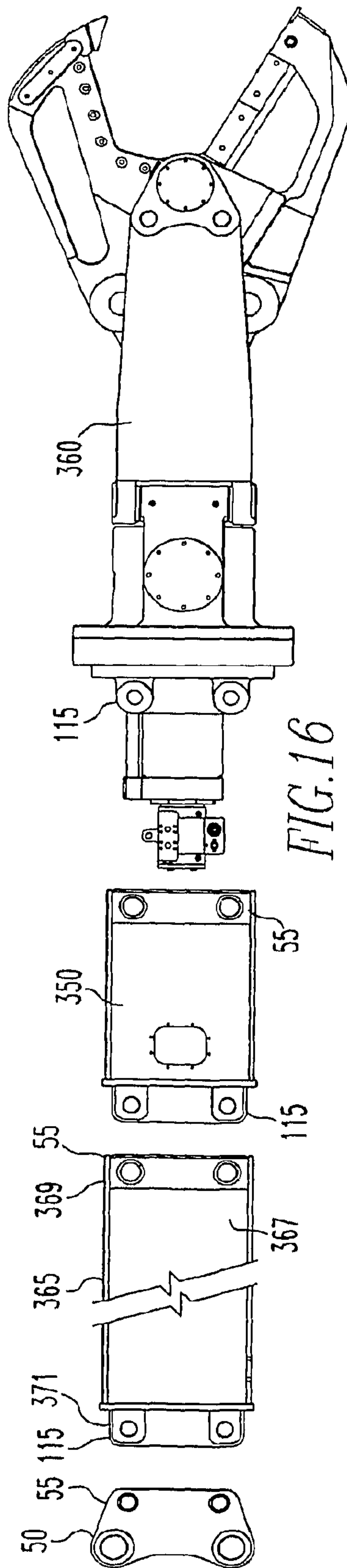


FIG. 16

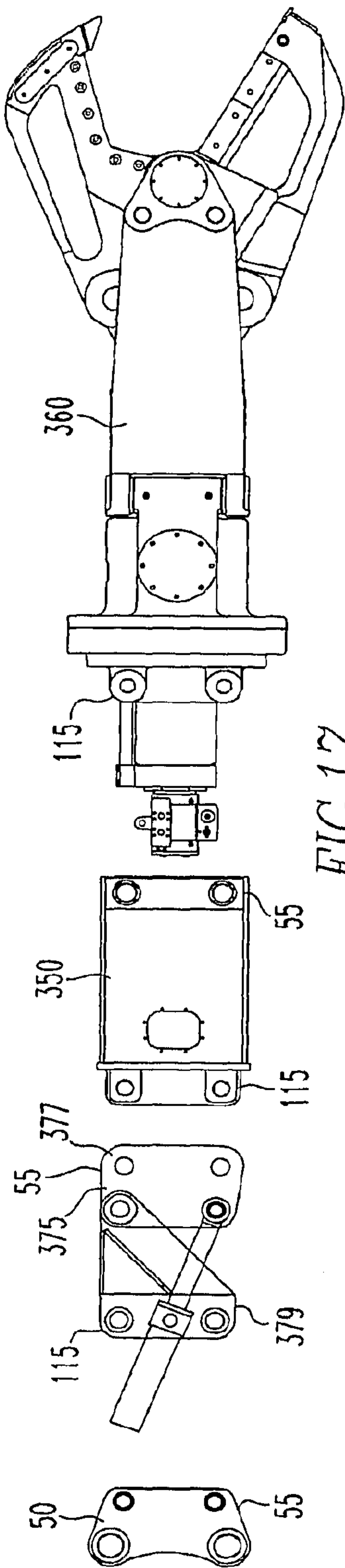


FIG. 17

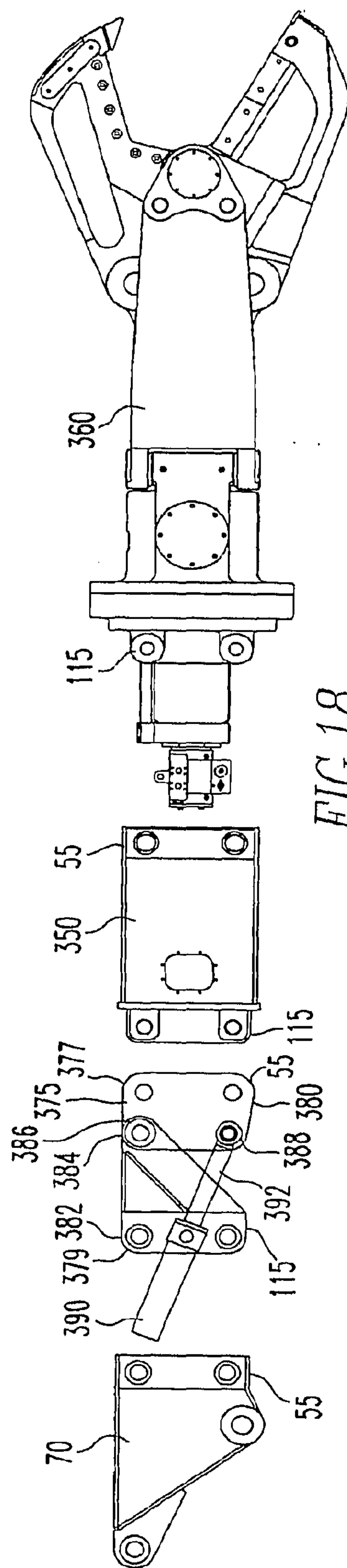


FIG. 18

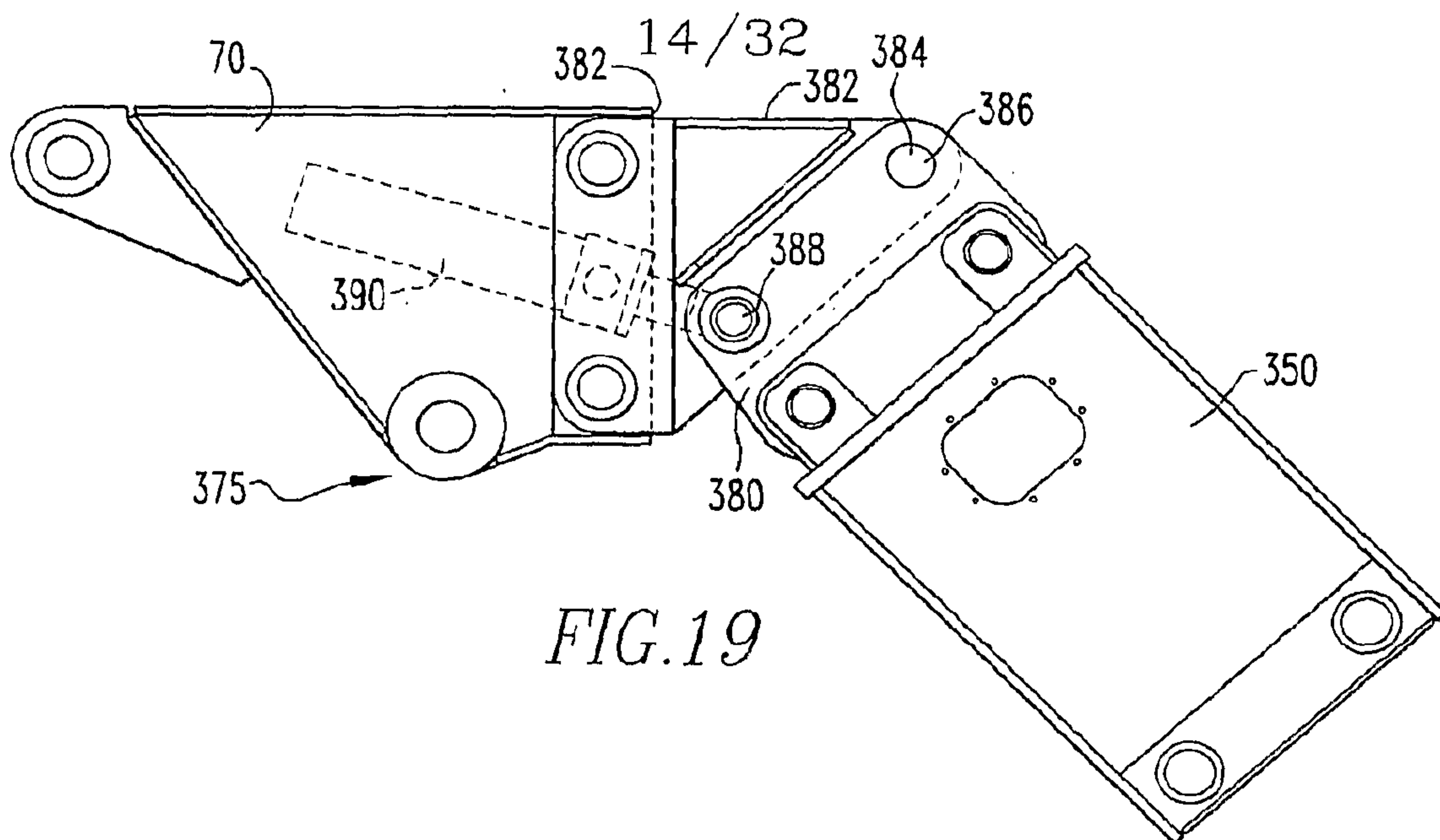


FIG. 19

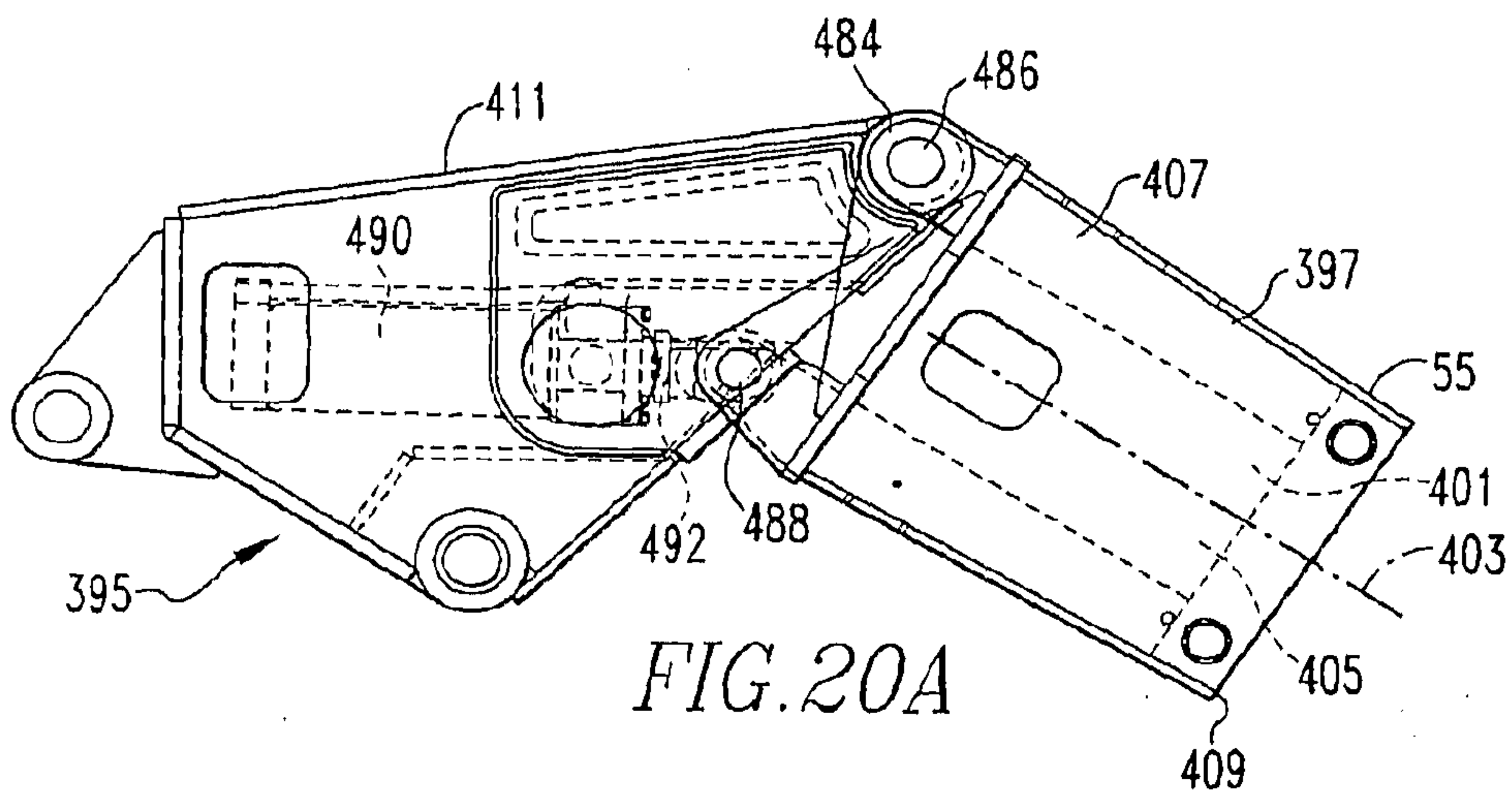


FIG. 20A

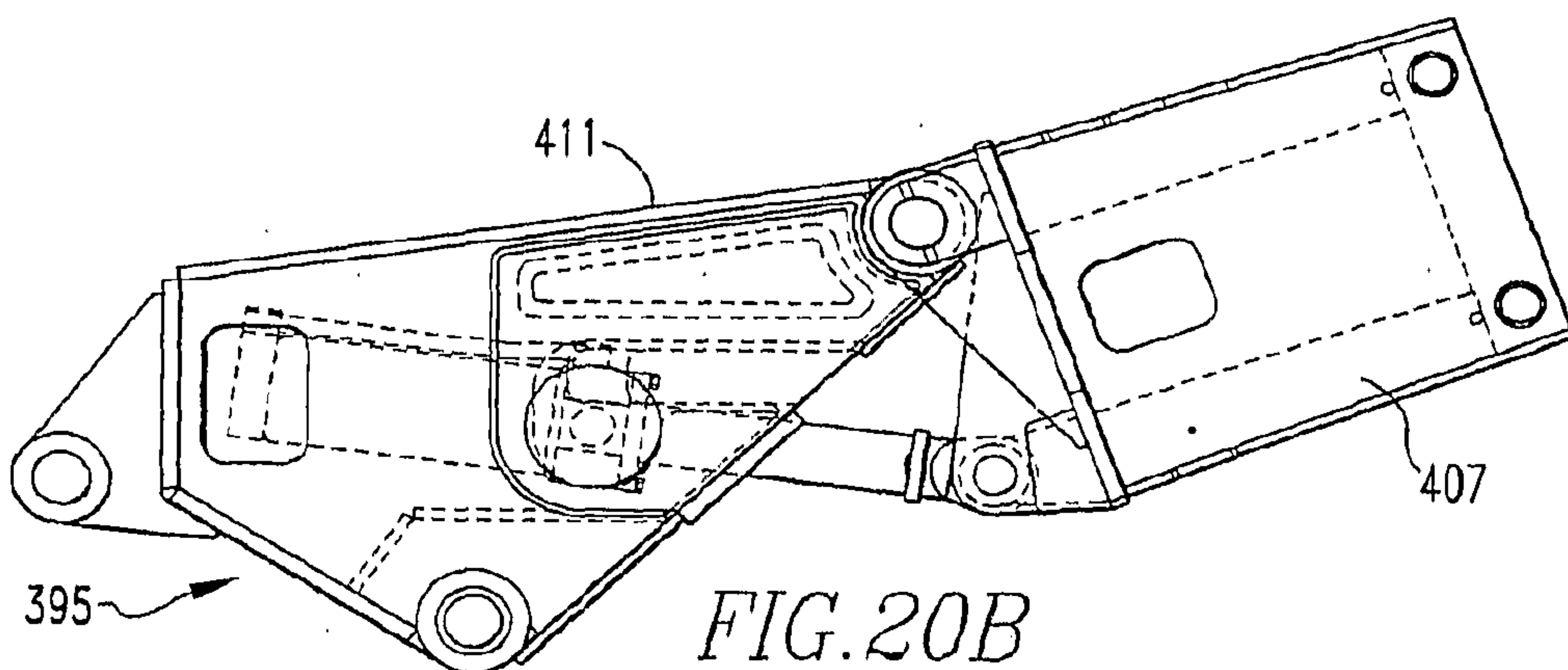


FIG. 20B

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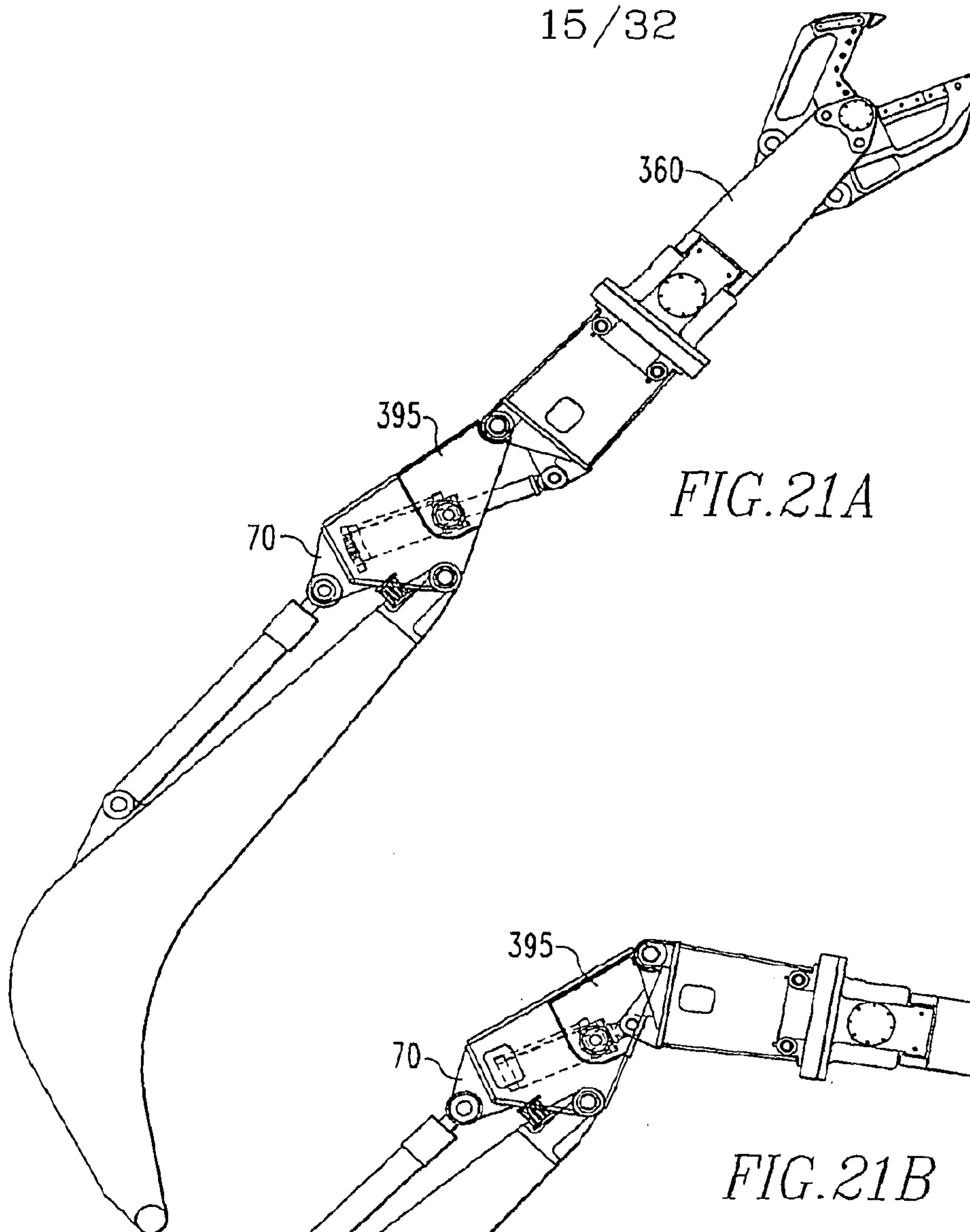


FIG. 21A

FIG. 21B

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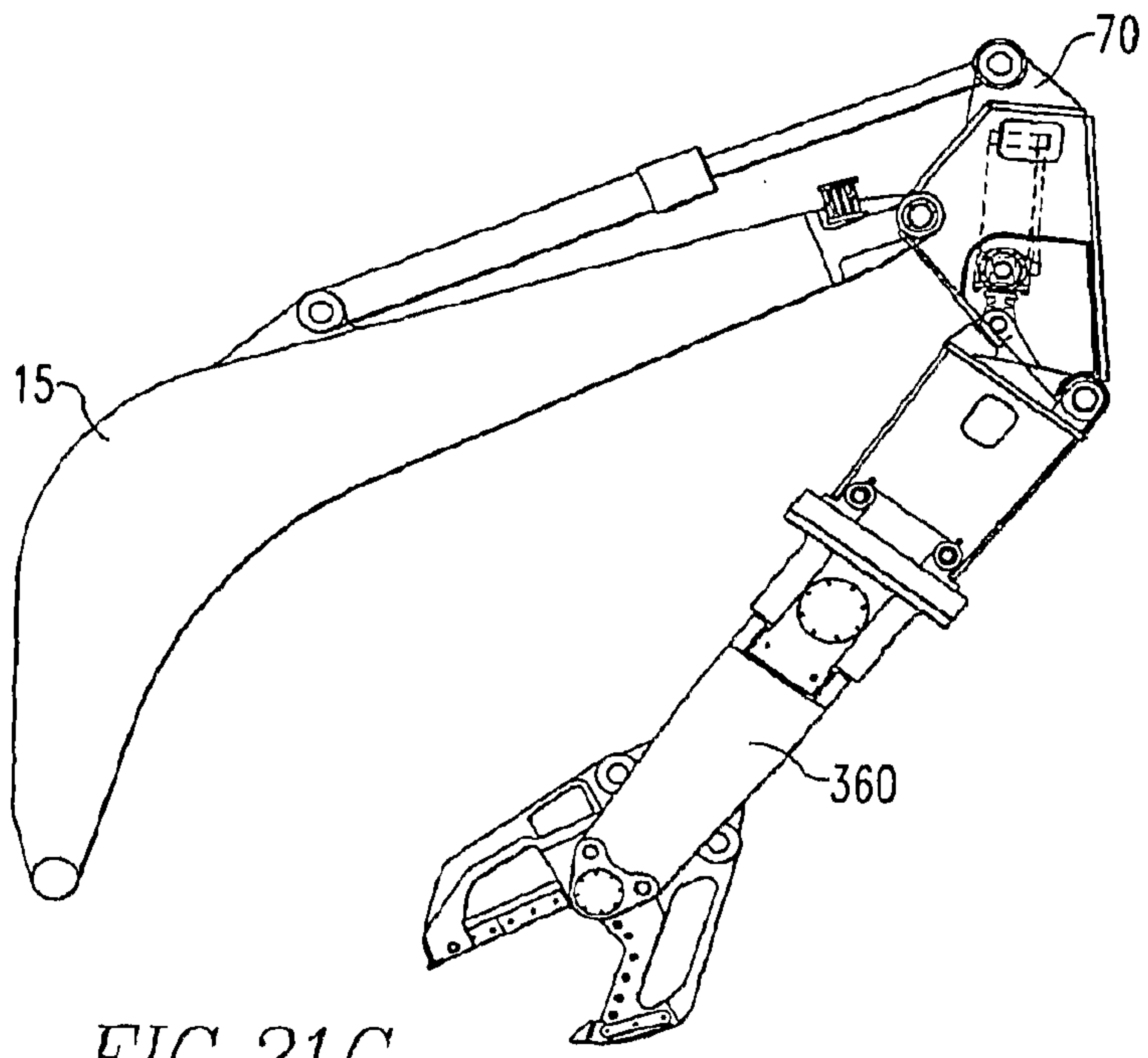


FIG. 21C

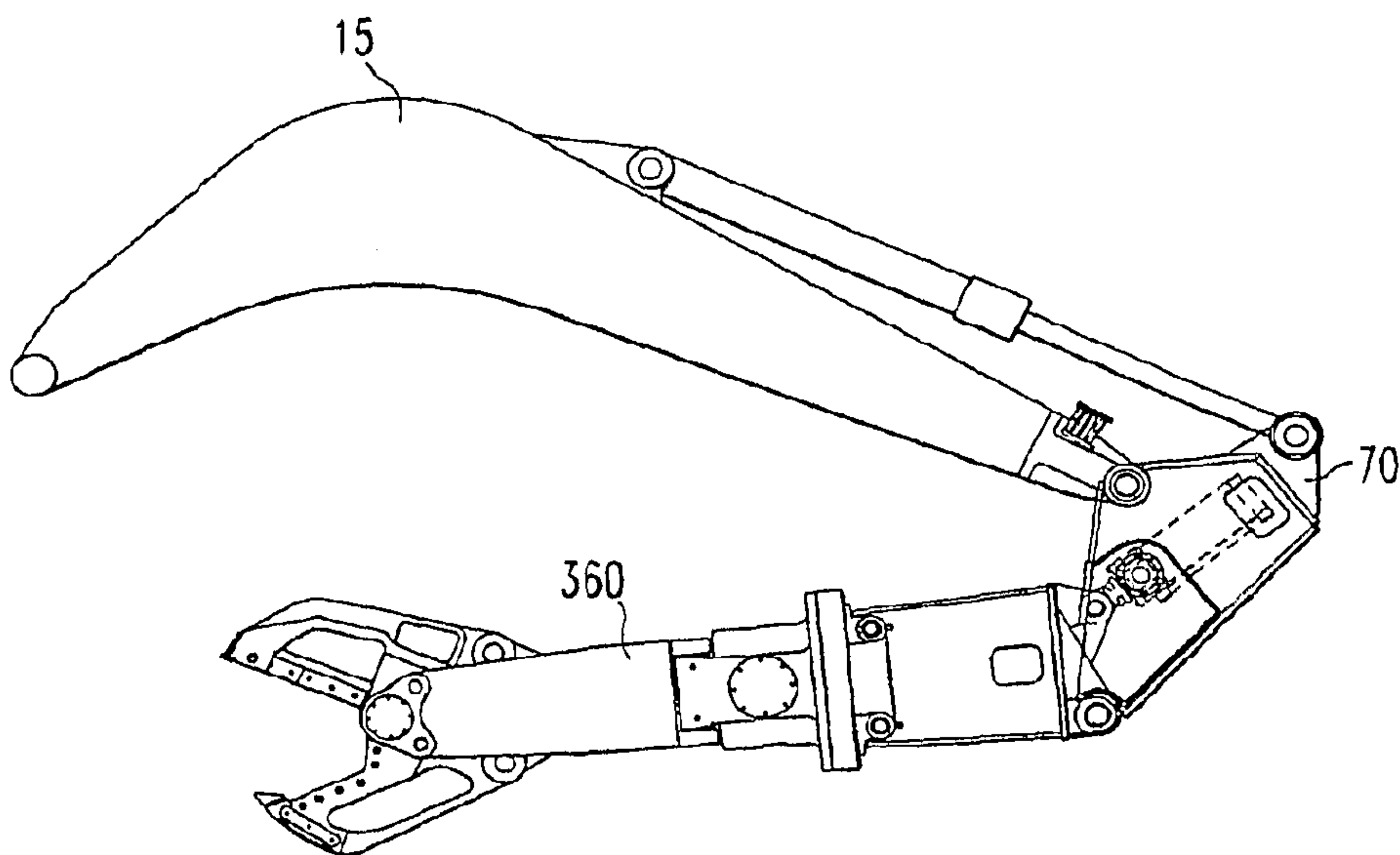
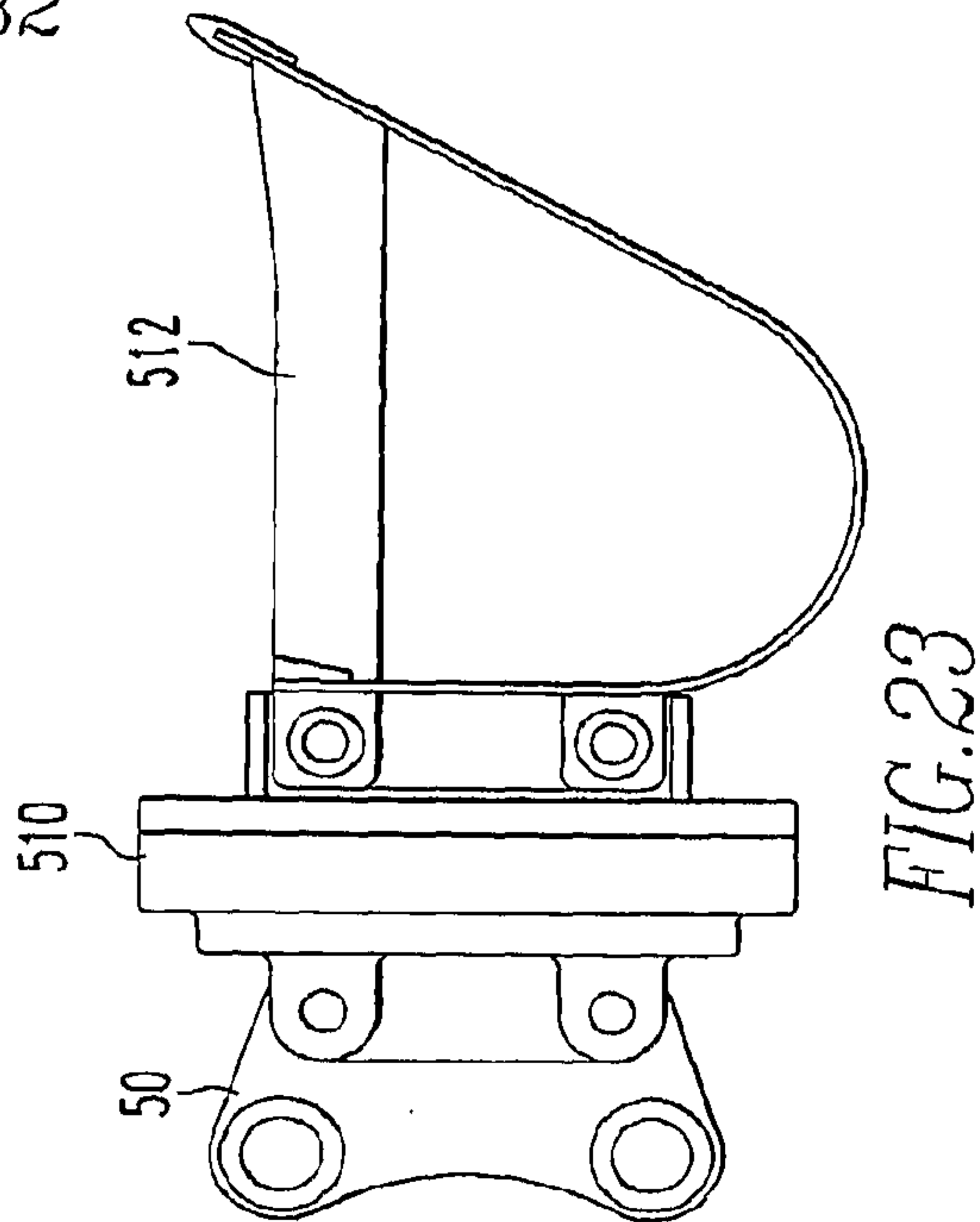
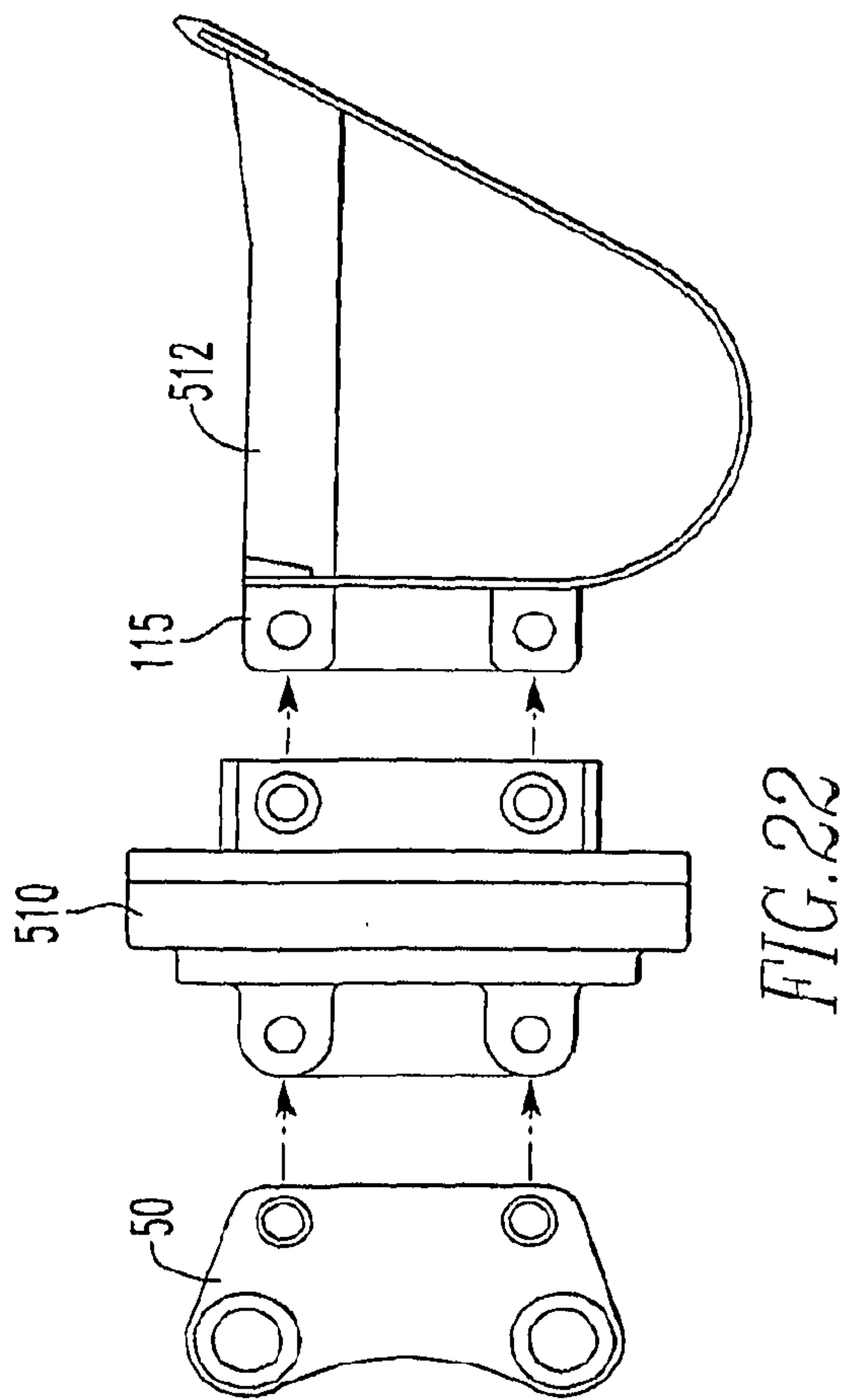
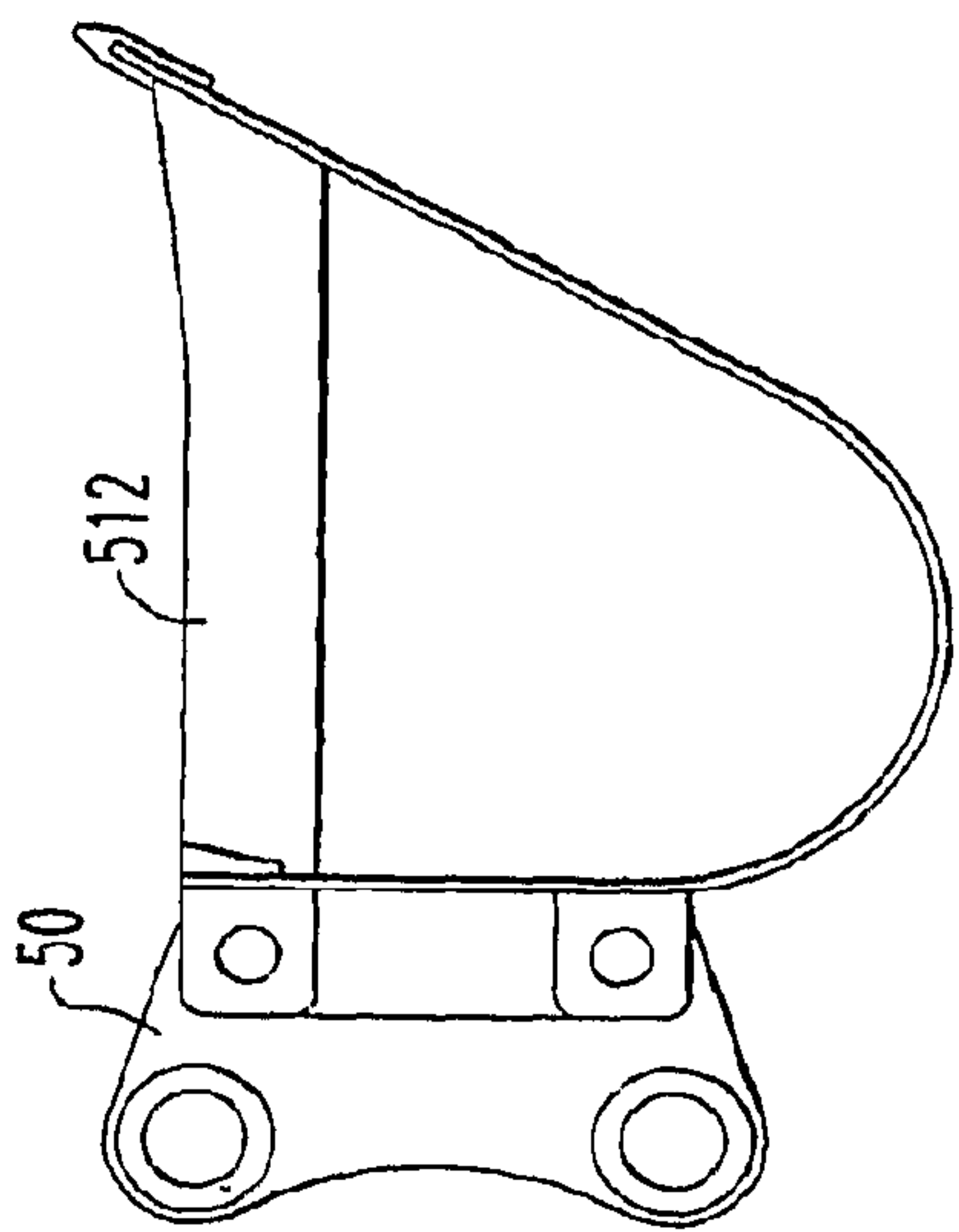
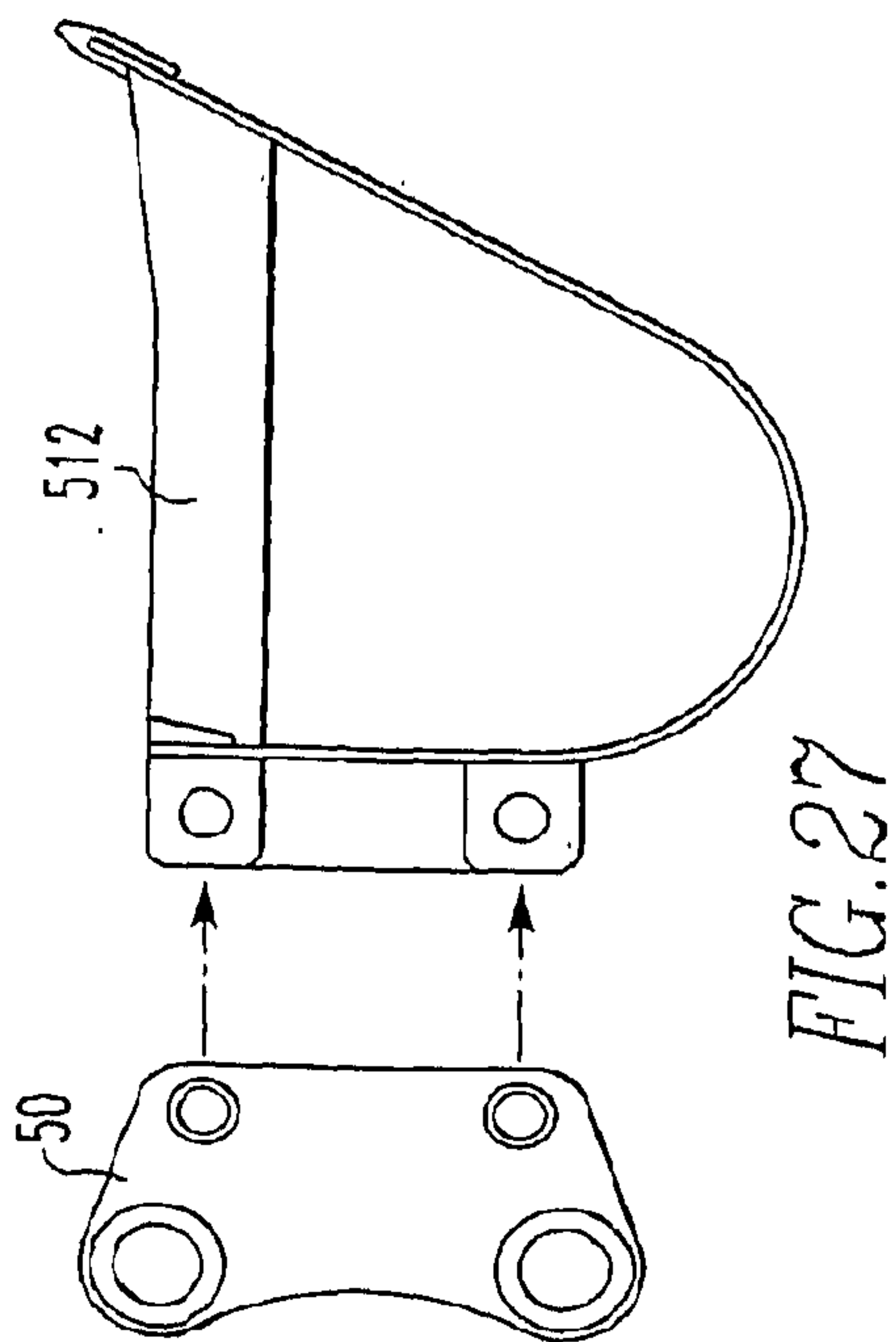


FIG. 21D



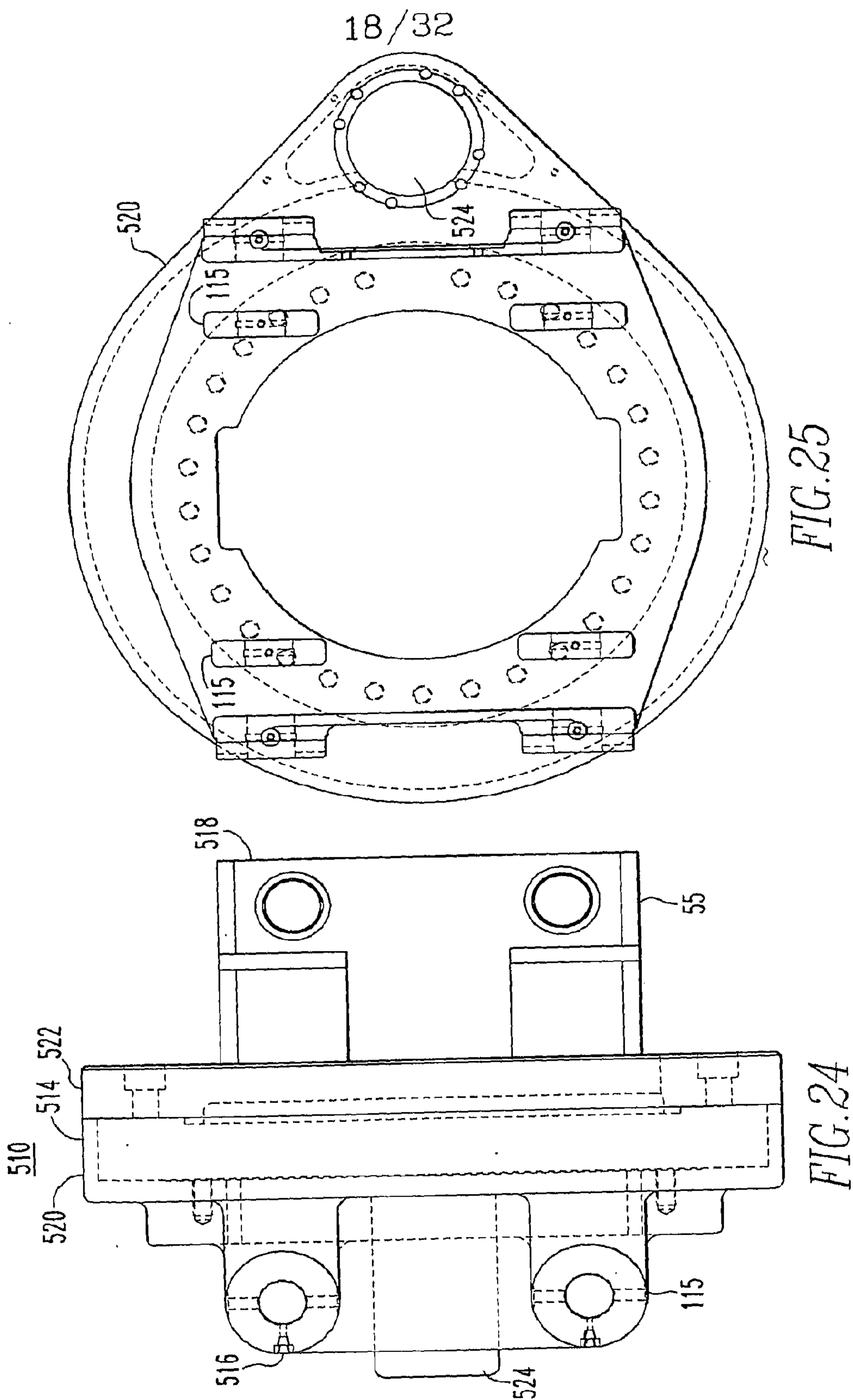


FIG. 25

FIG. 24

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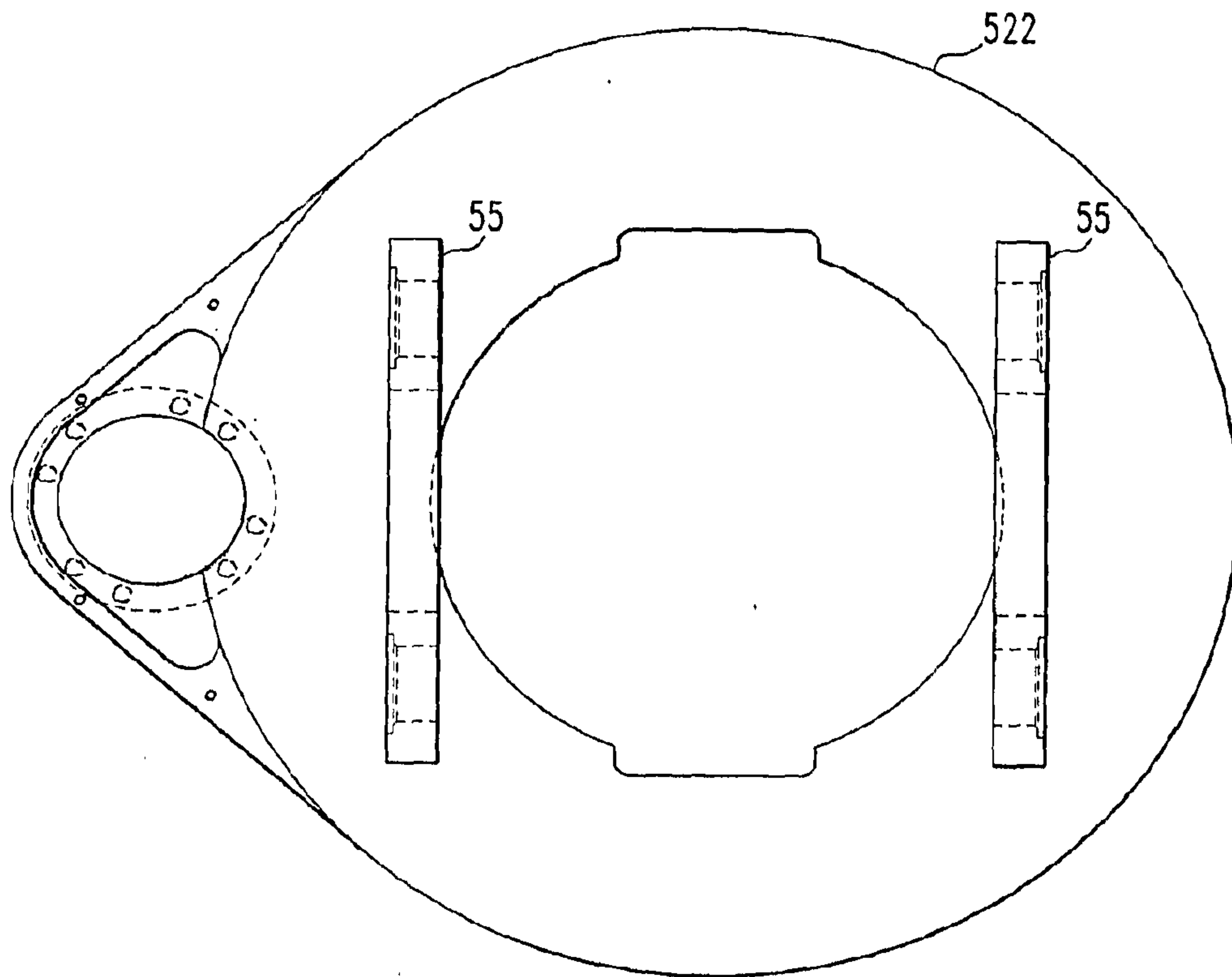


FIG. 26

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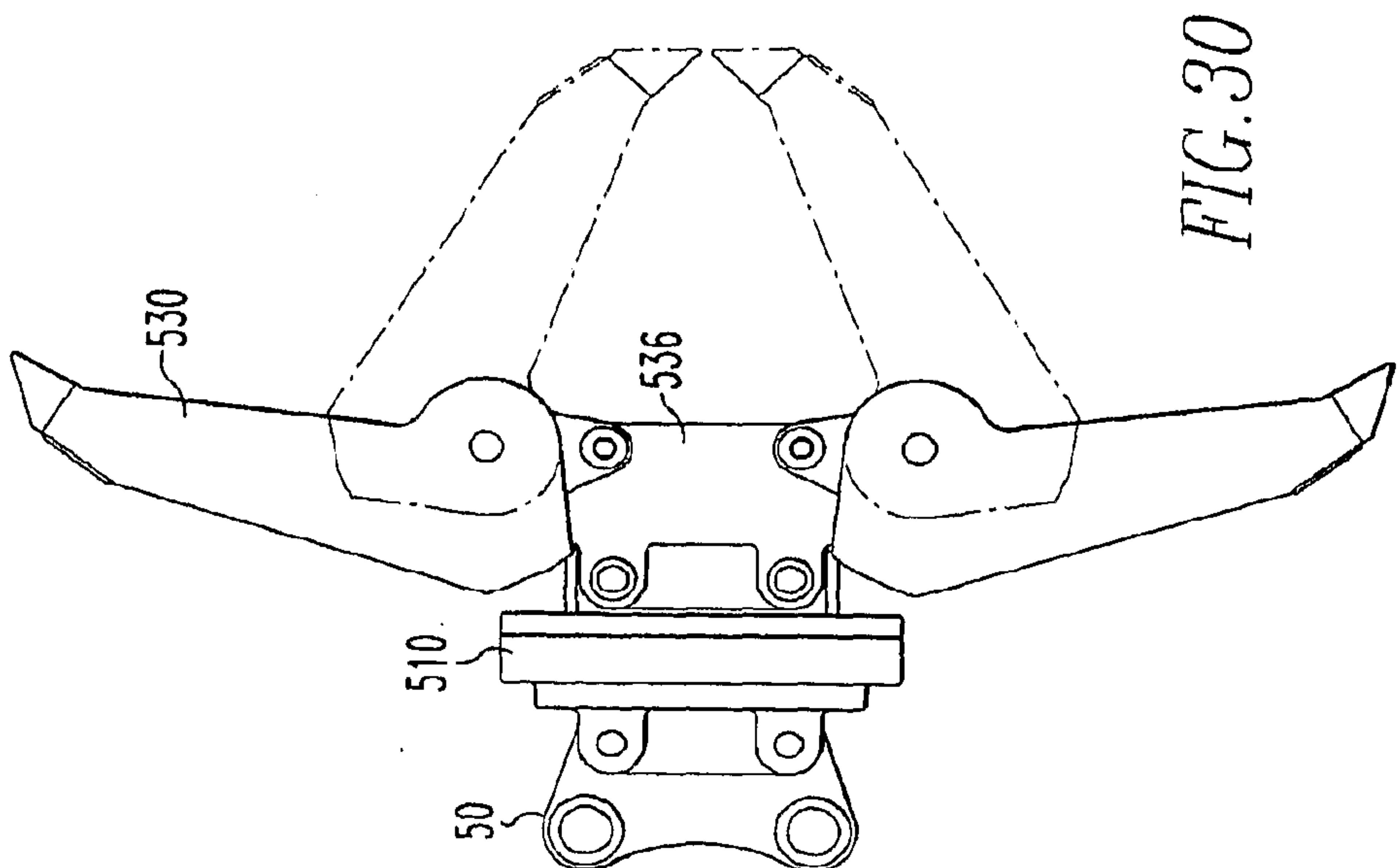


FIG. 30

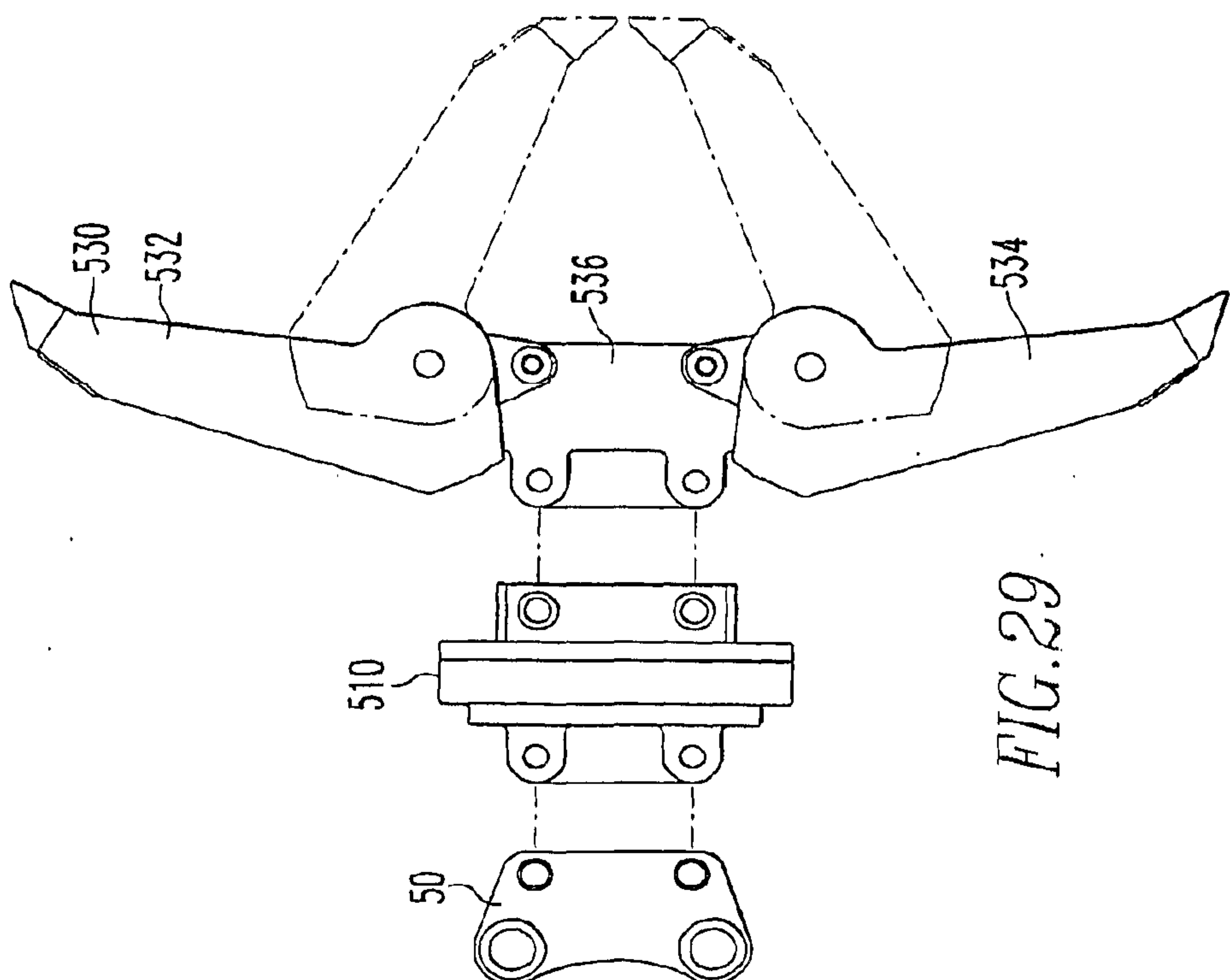


FIG. 29

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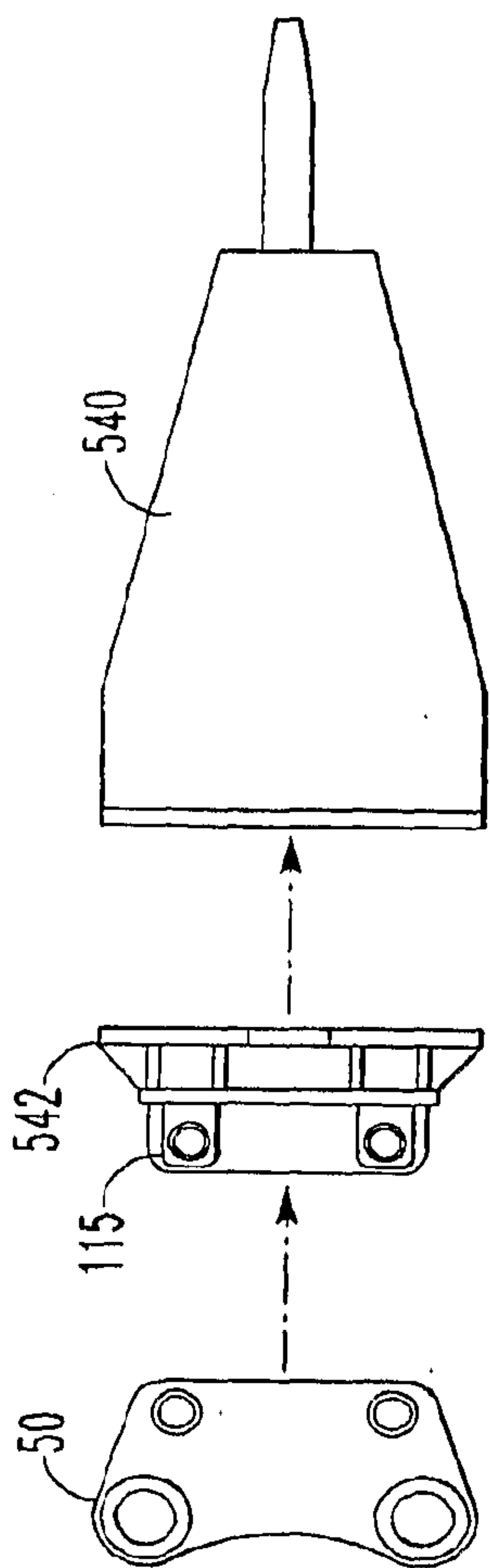


FIG. 31

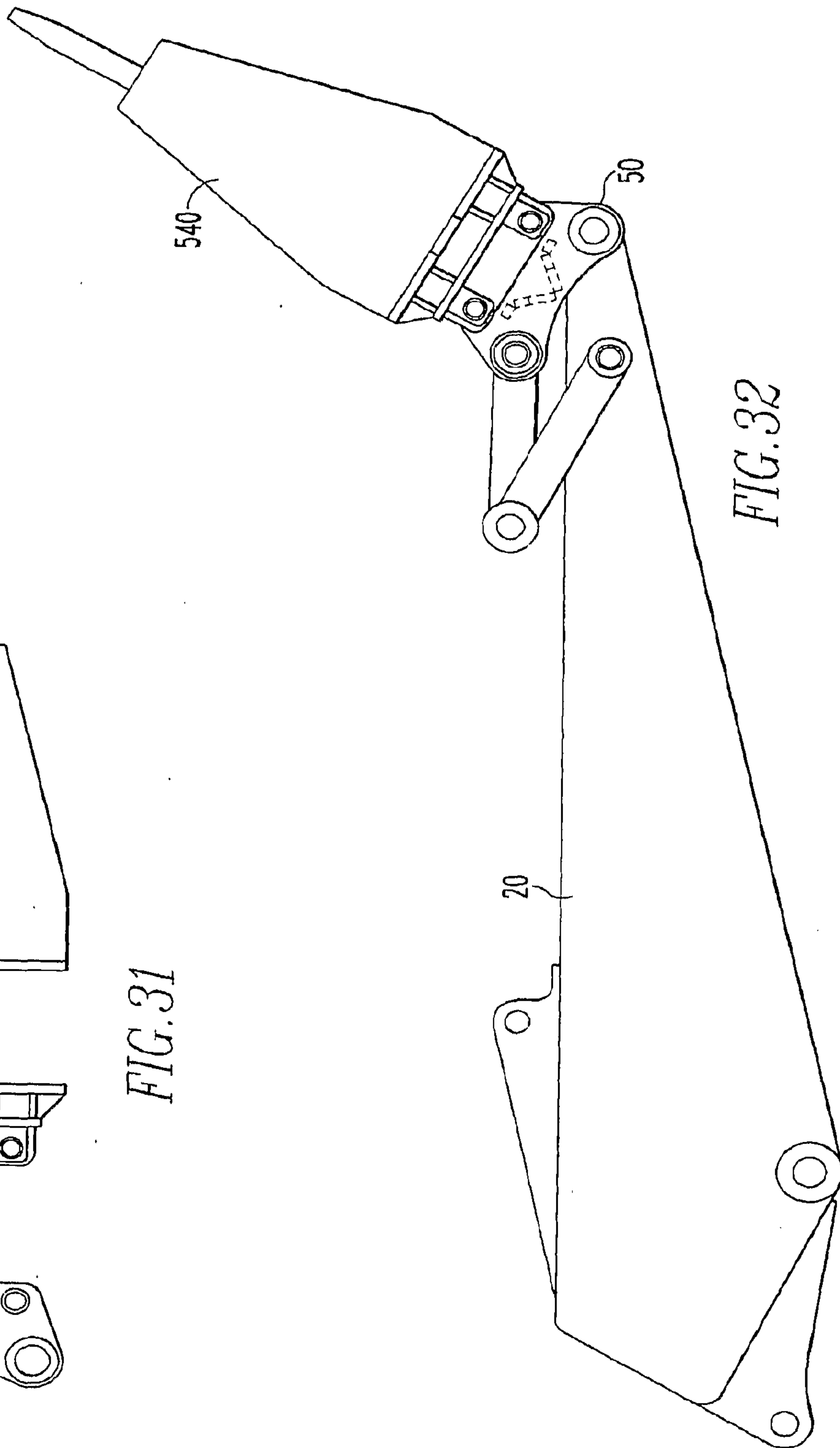
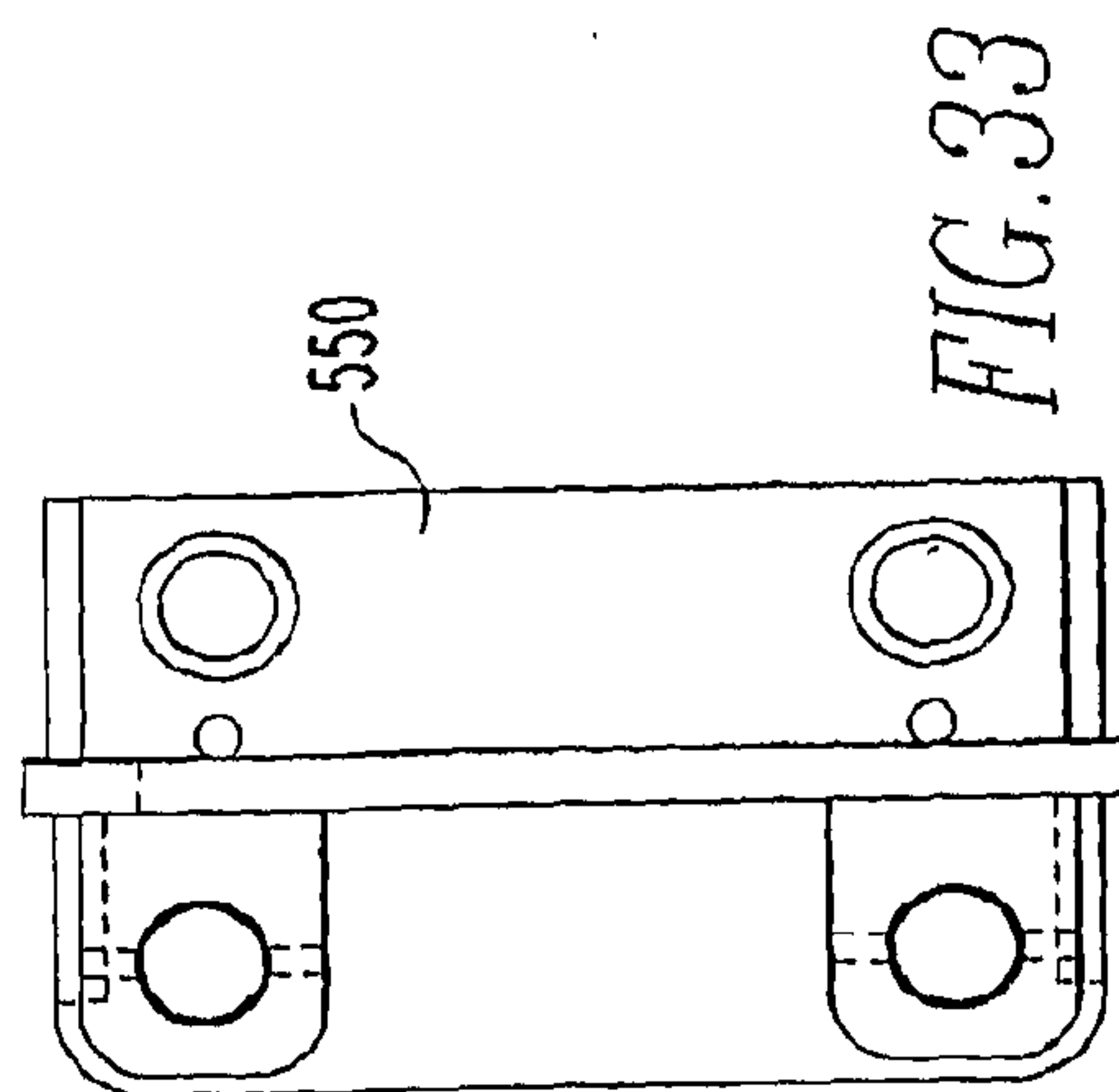
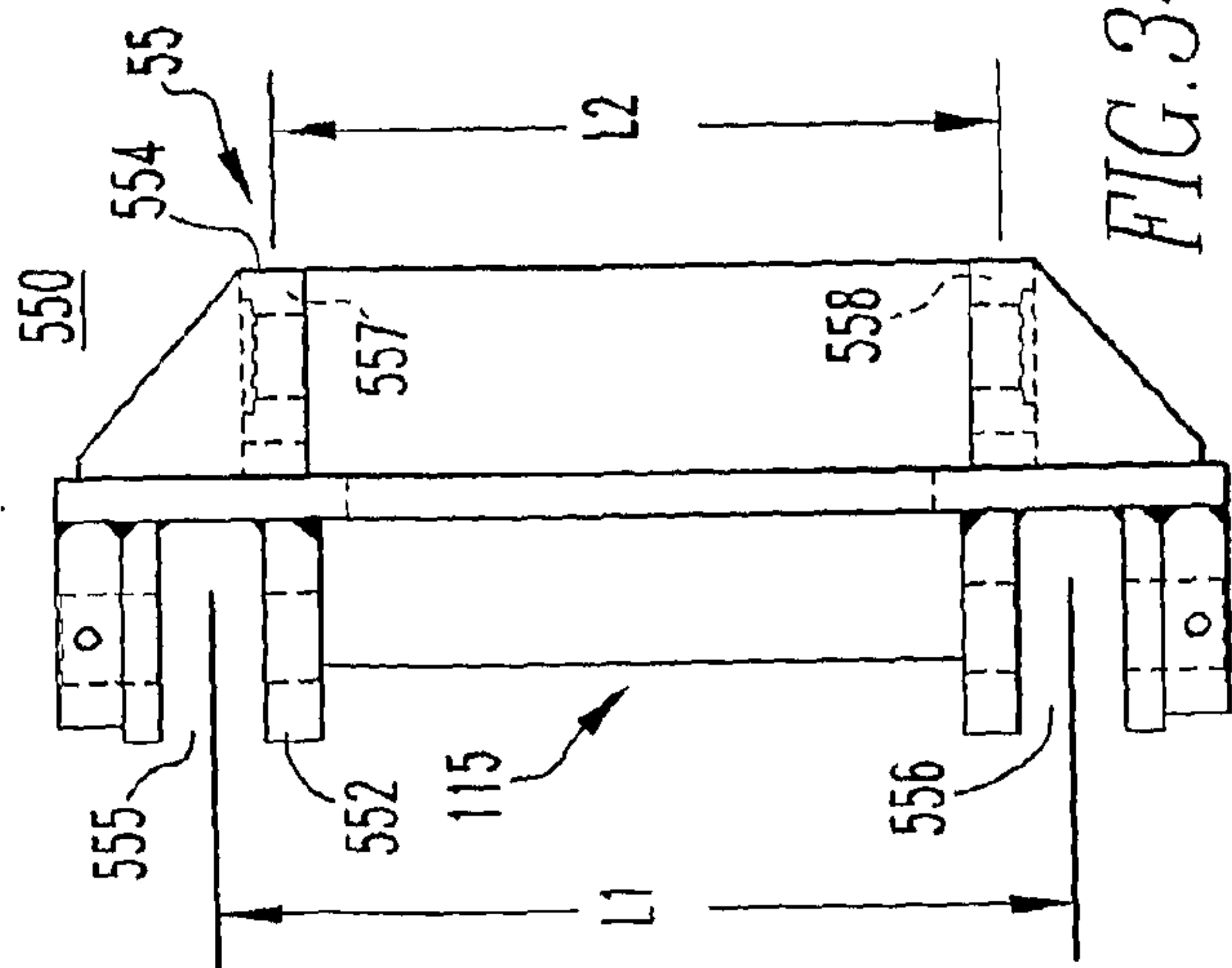
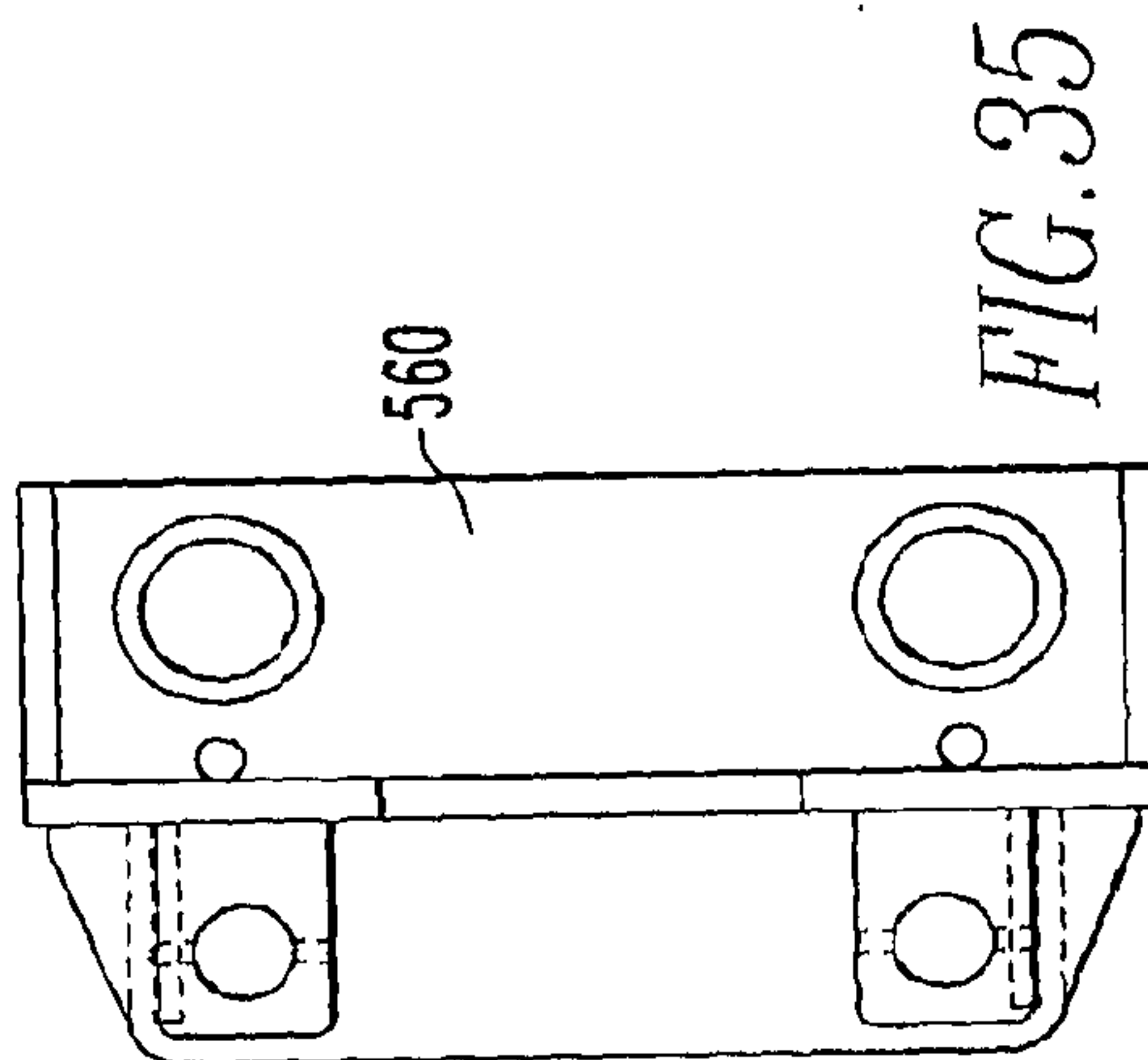
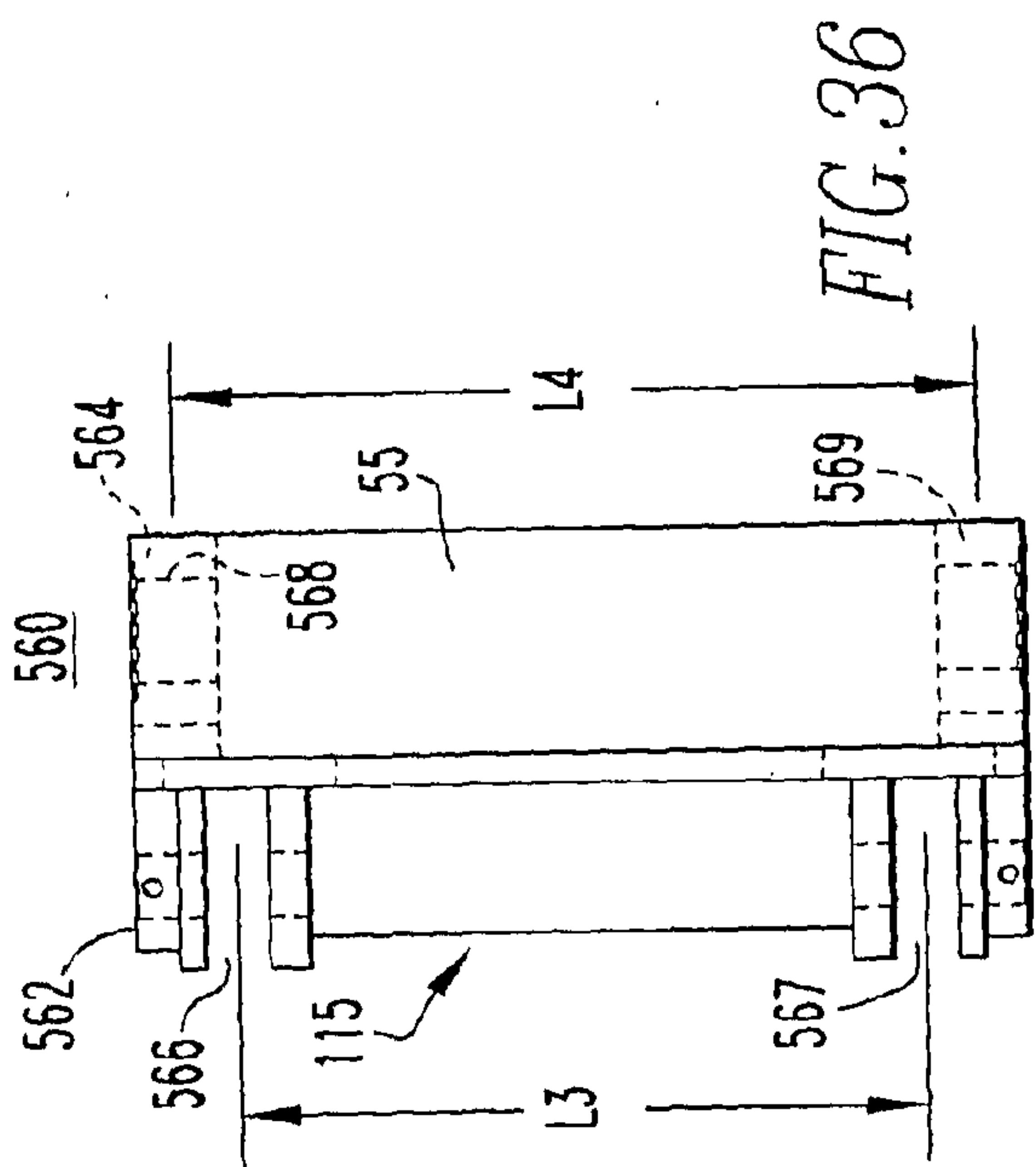


FIG. 32



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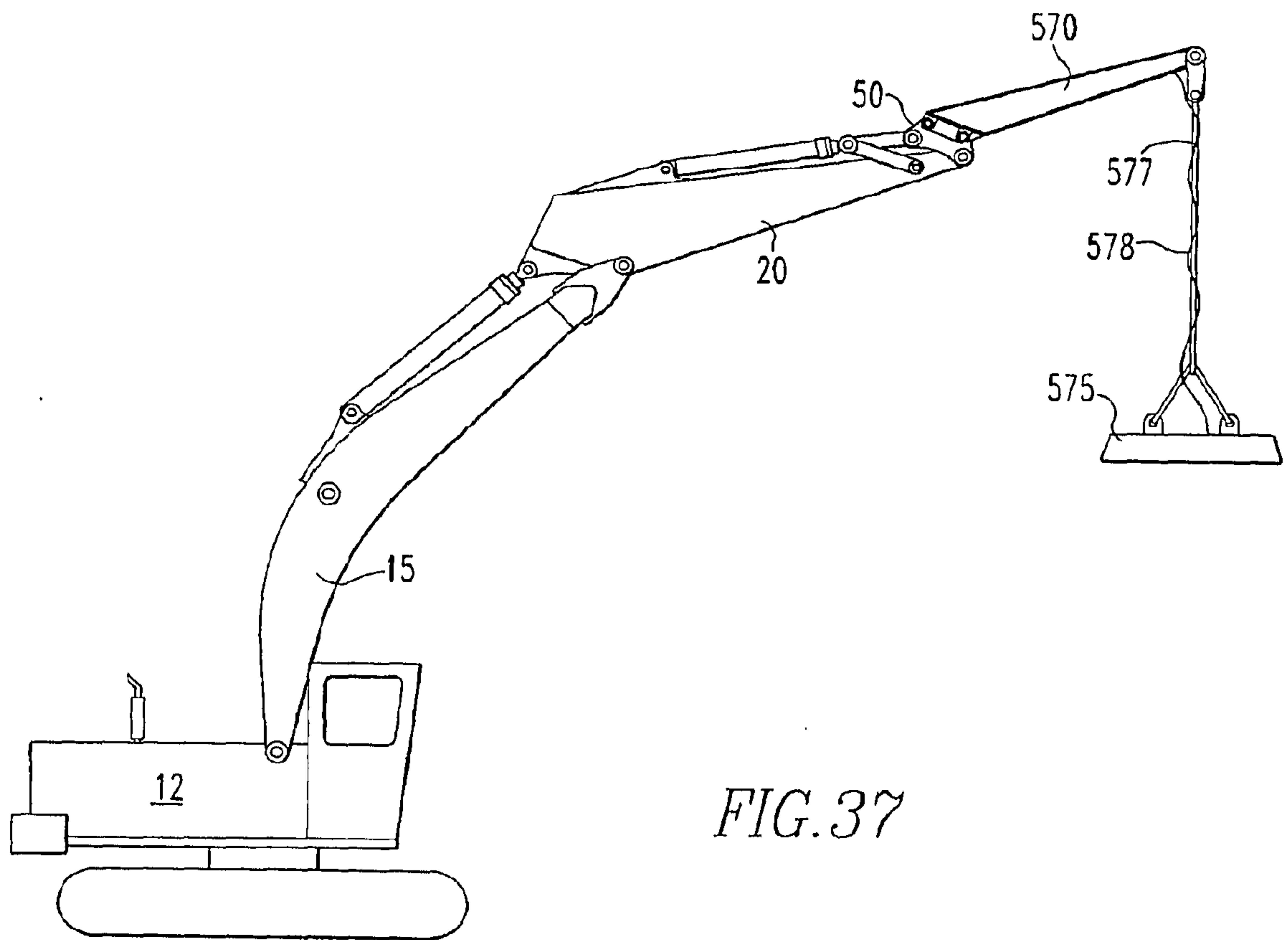
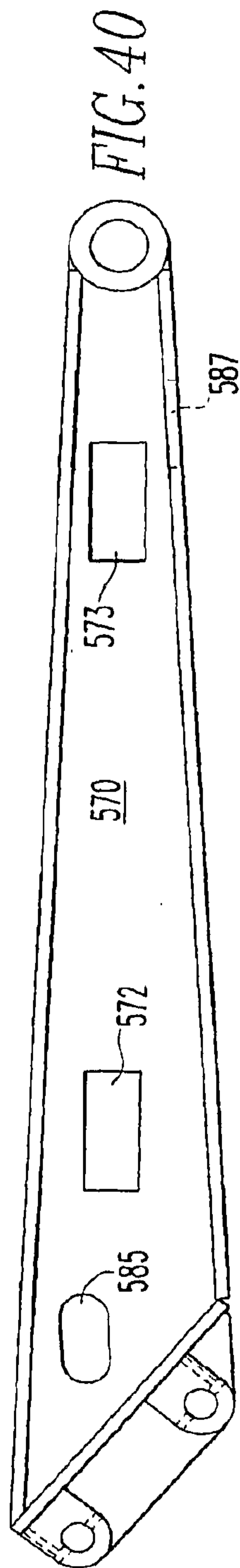
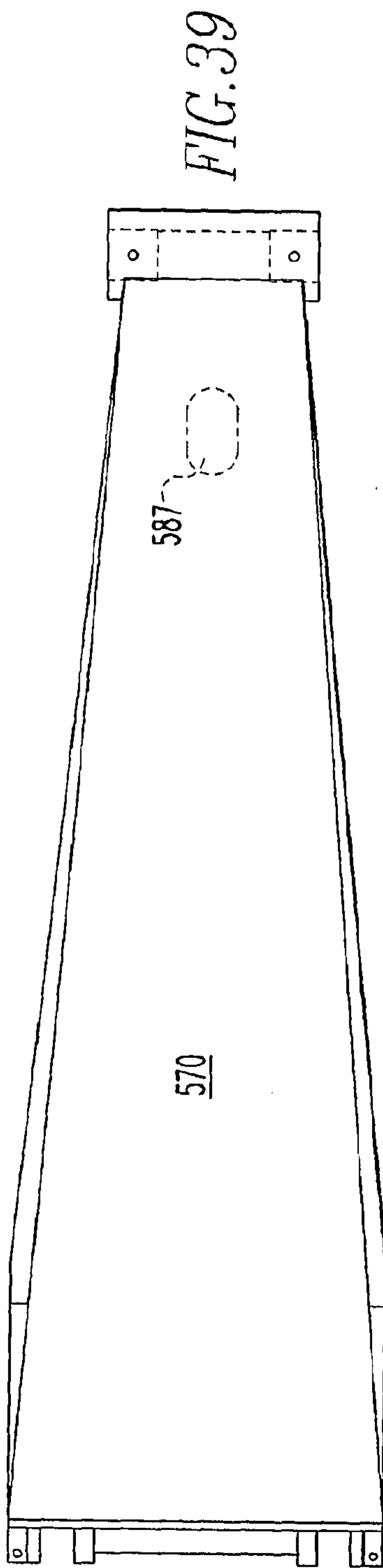
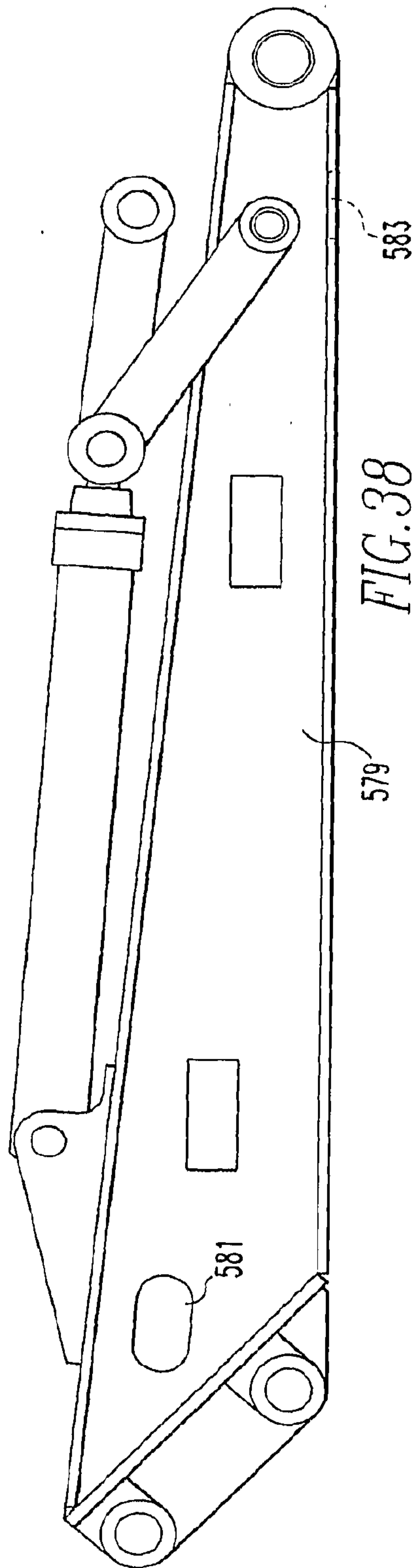
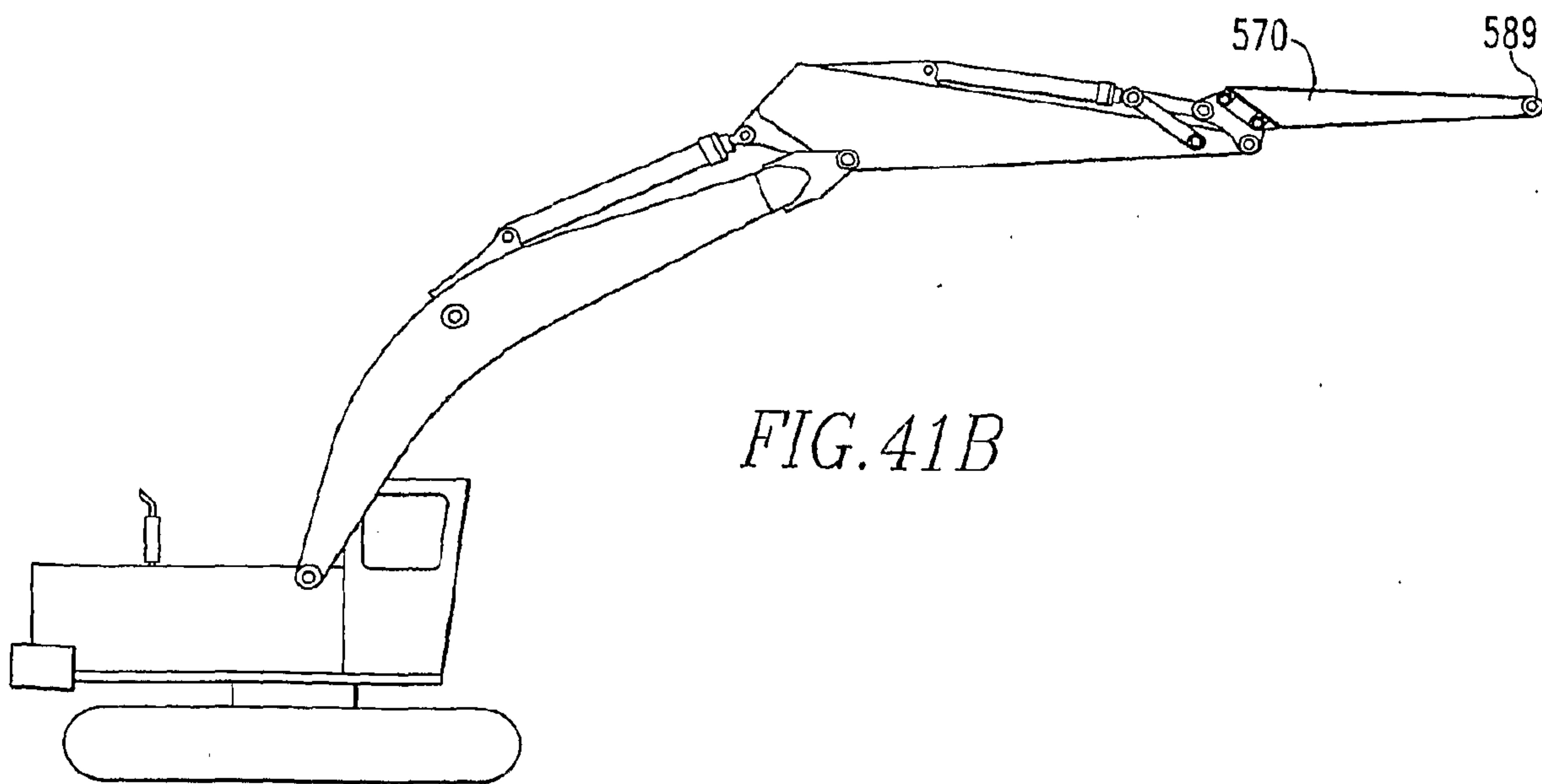
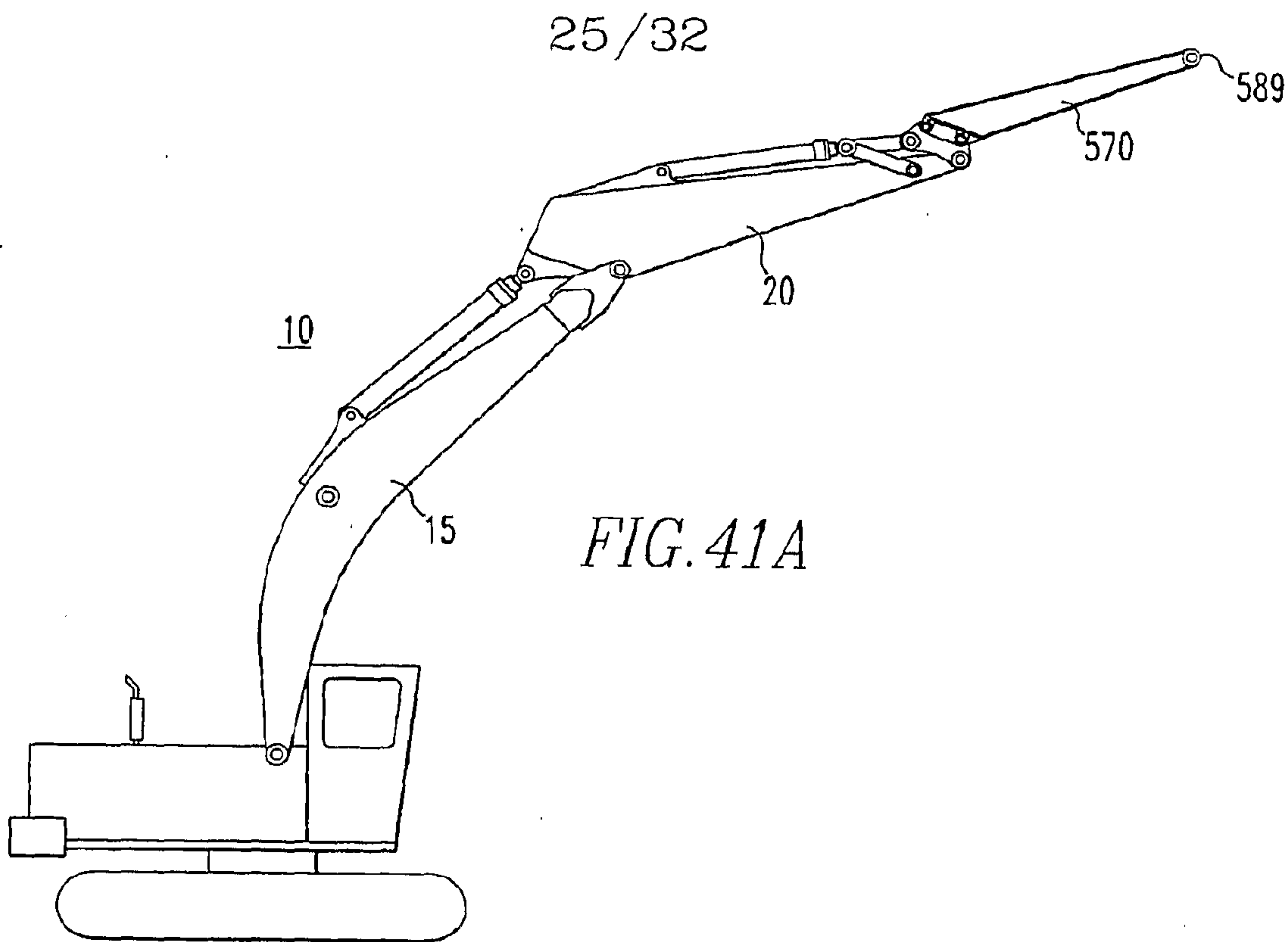


FIG. 37





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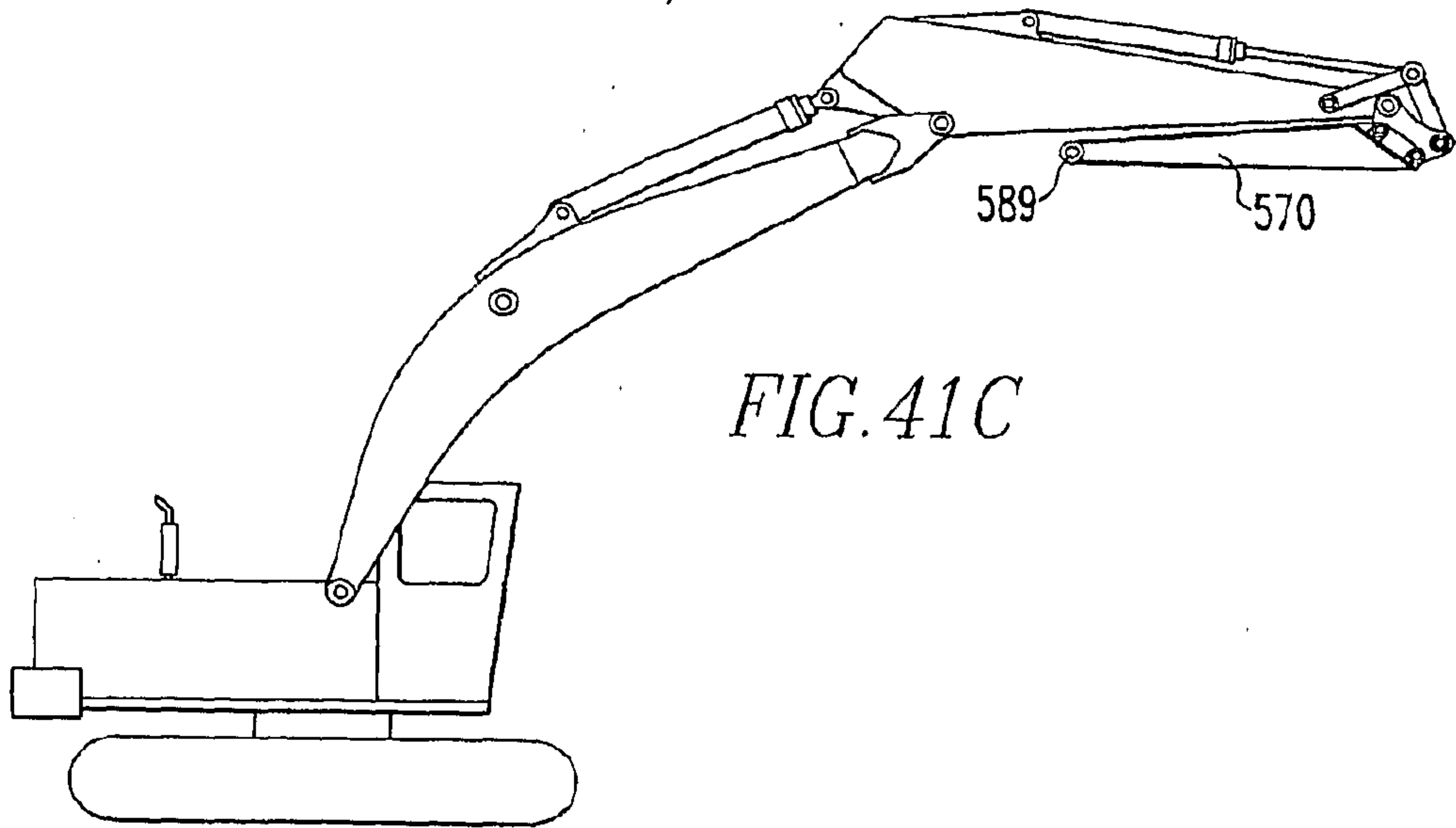


FIG. 41C

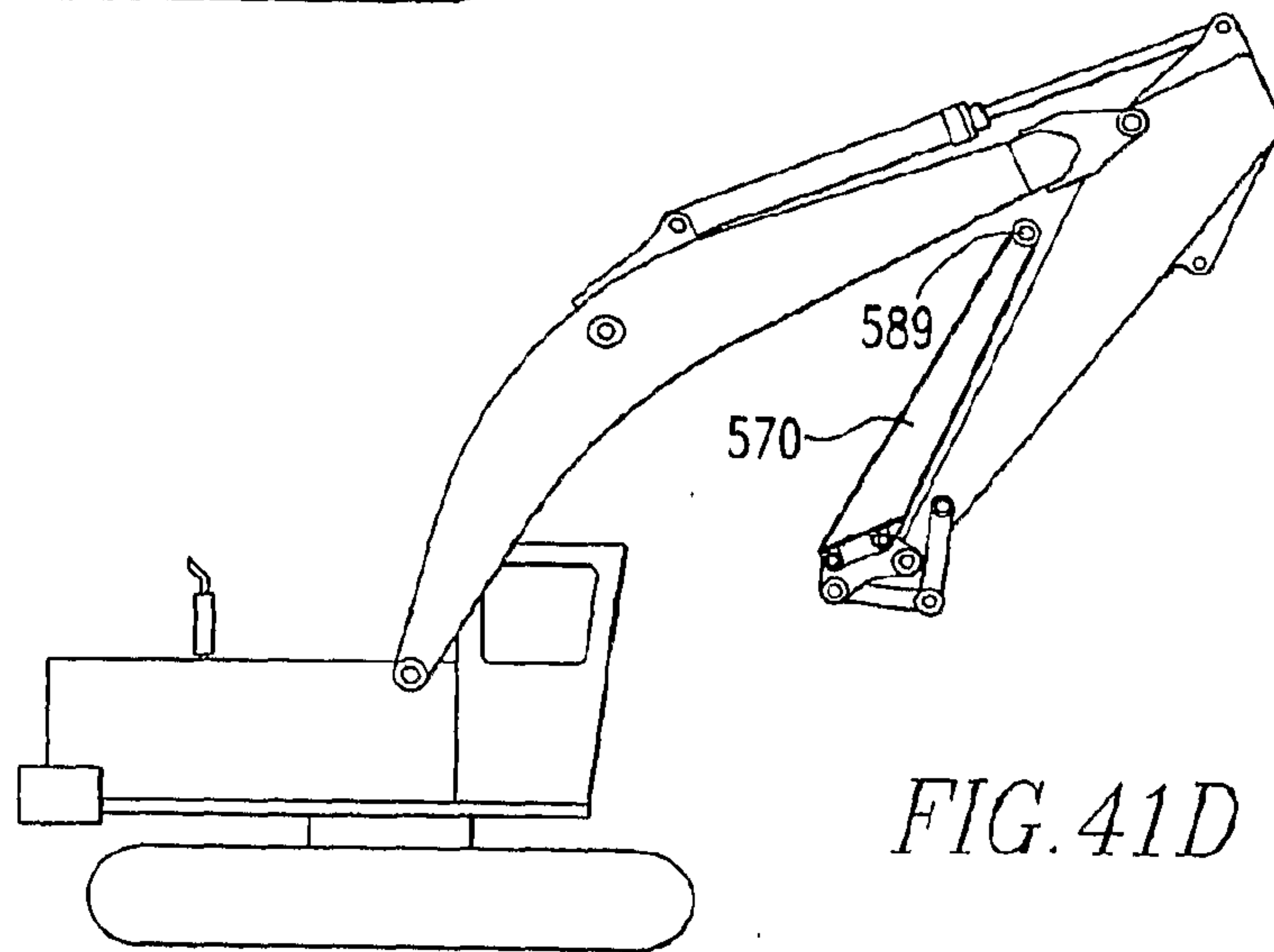


FIG. 41D

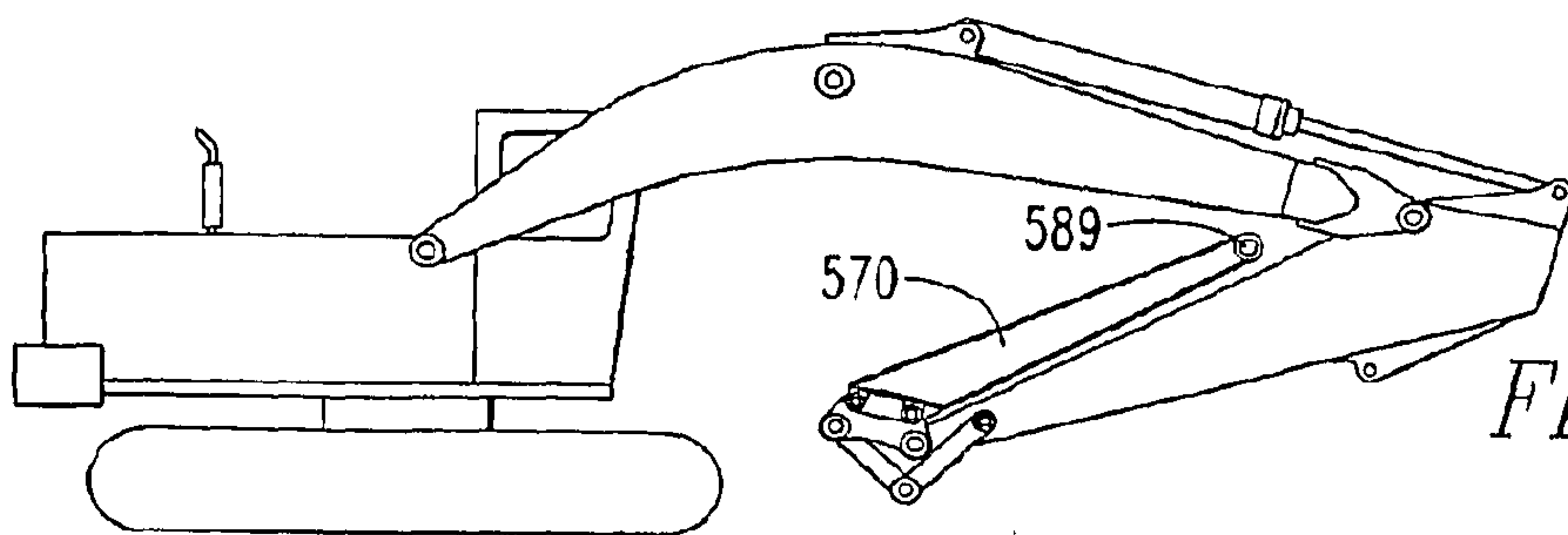


FIG. 41E

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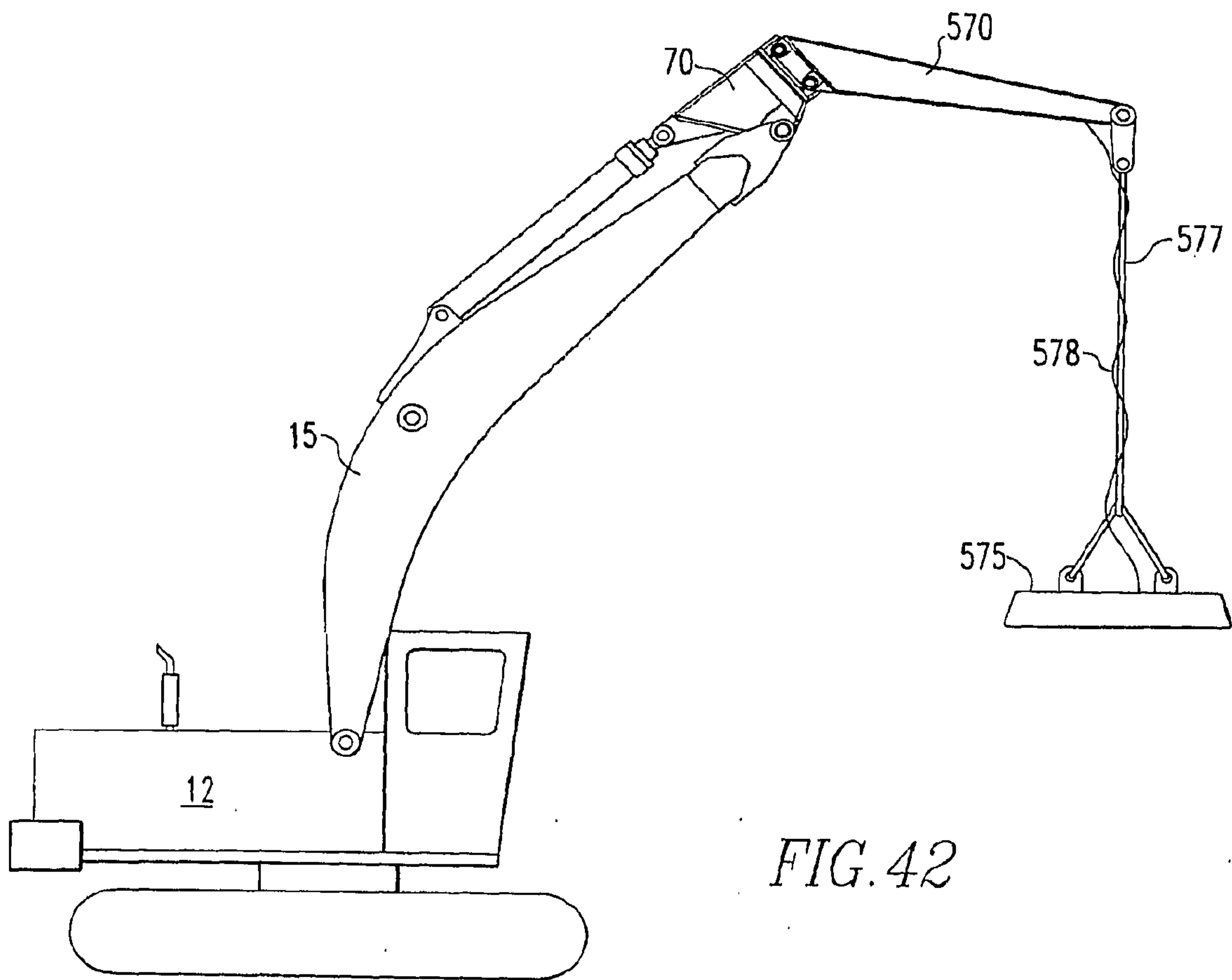


FIG. 42

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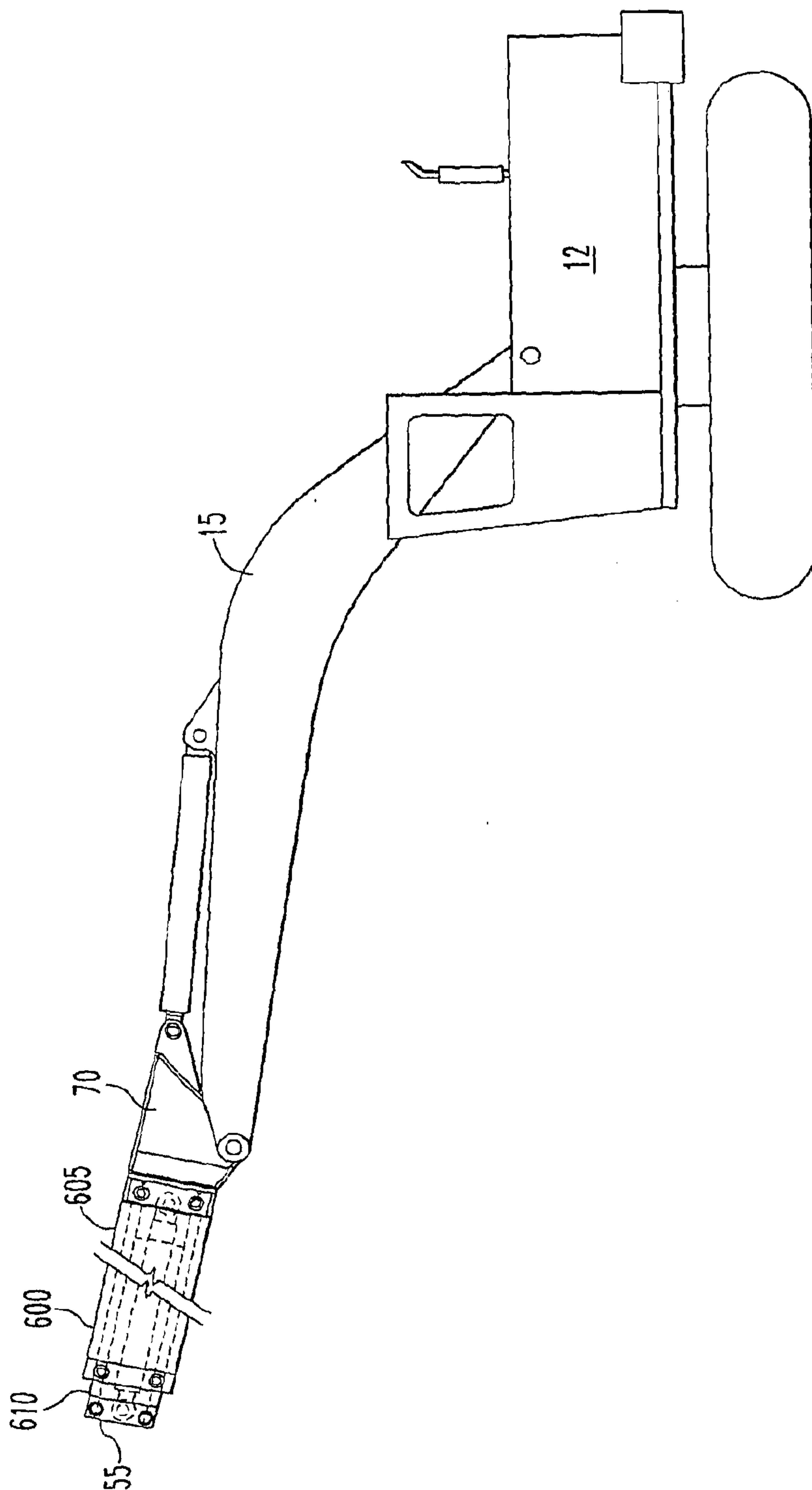


FIG. 43A

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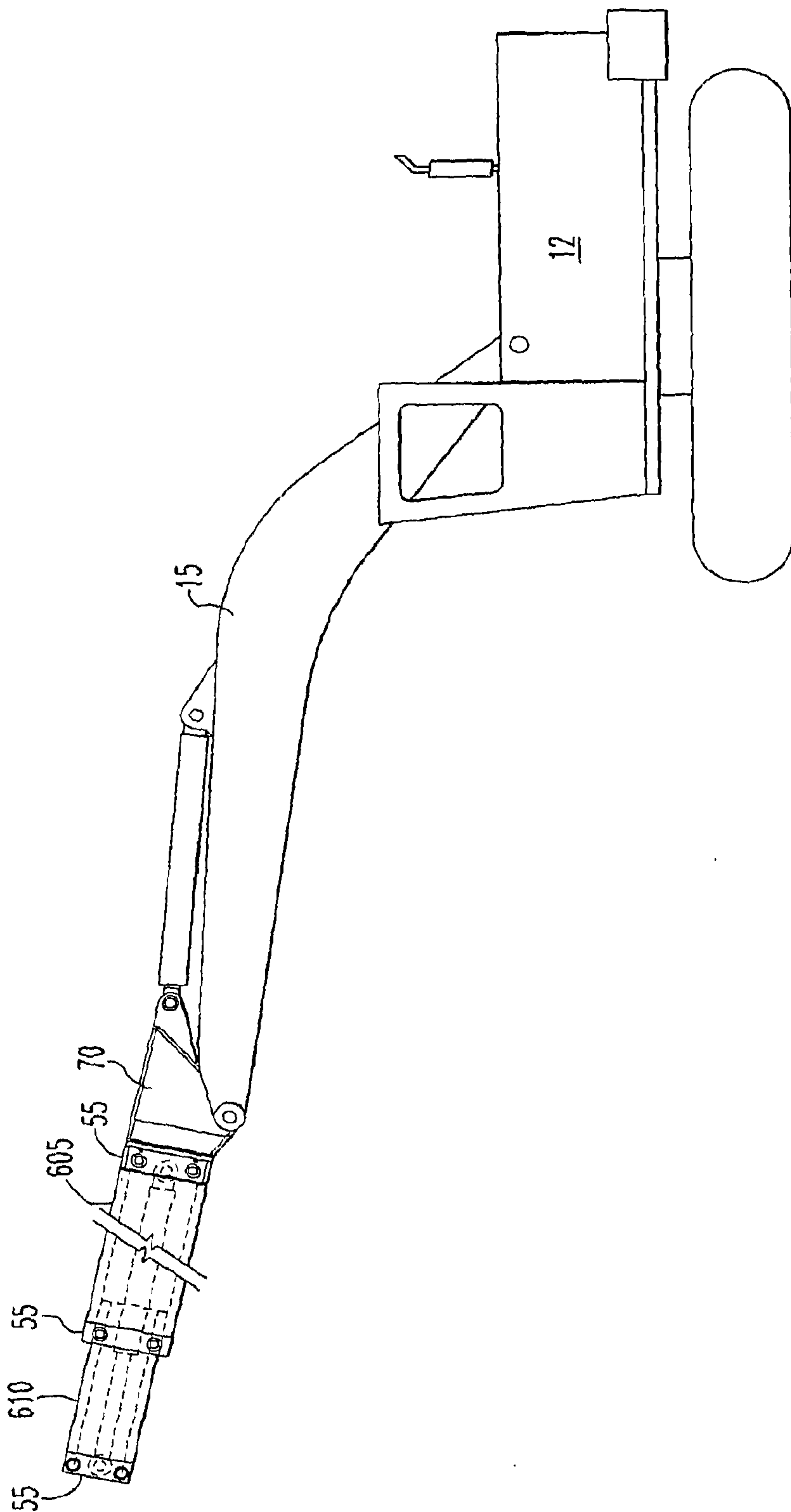


FIG. 43B

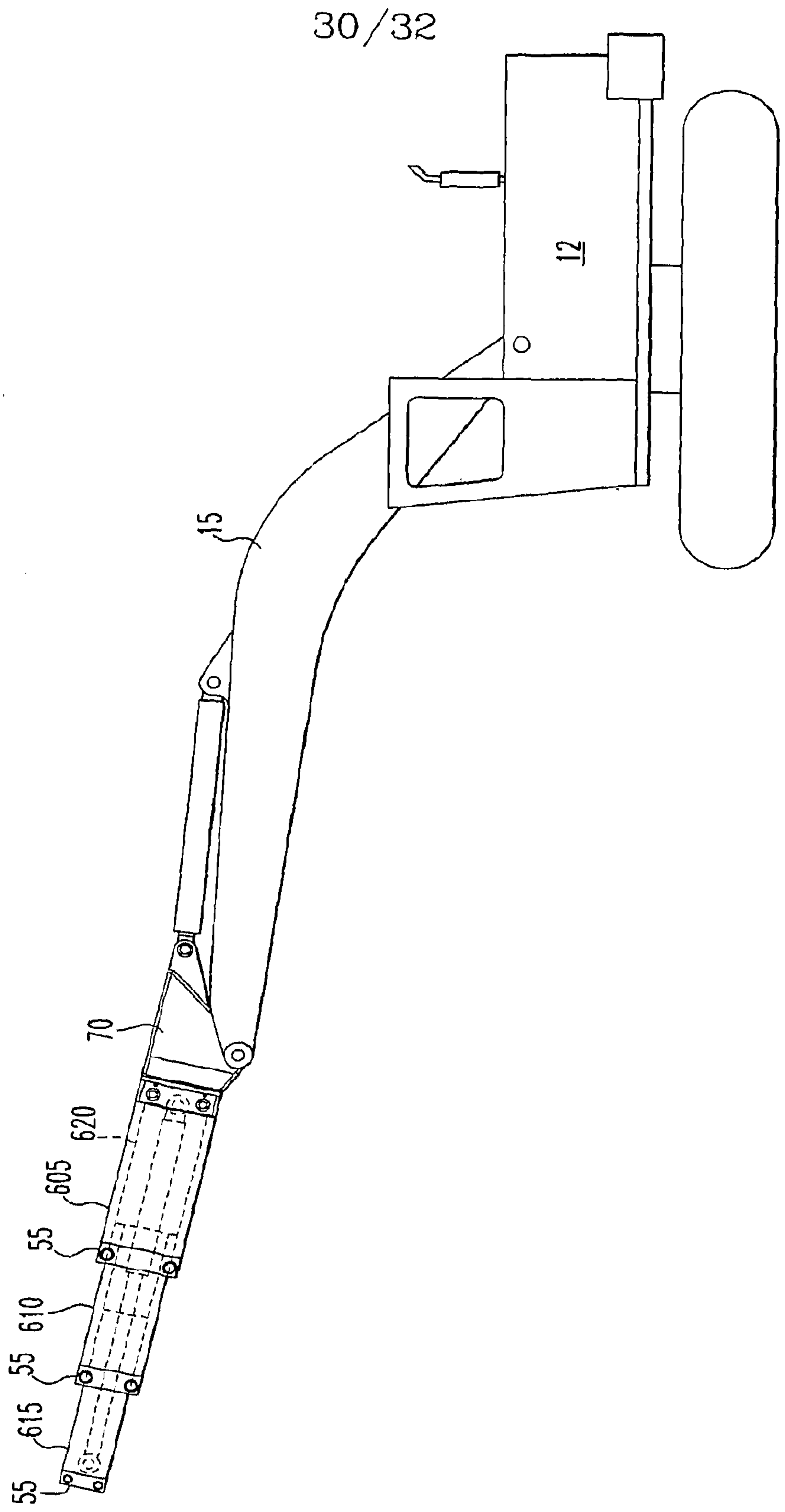


FIG. 43C

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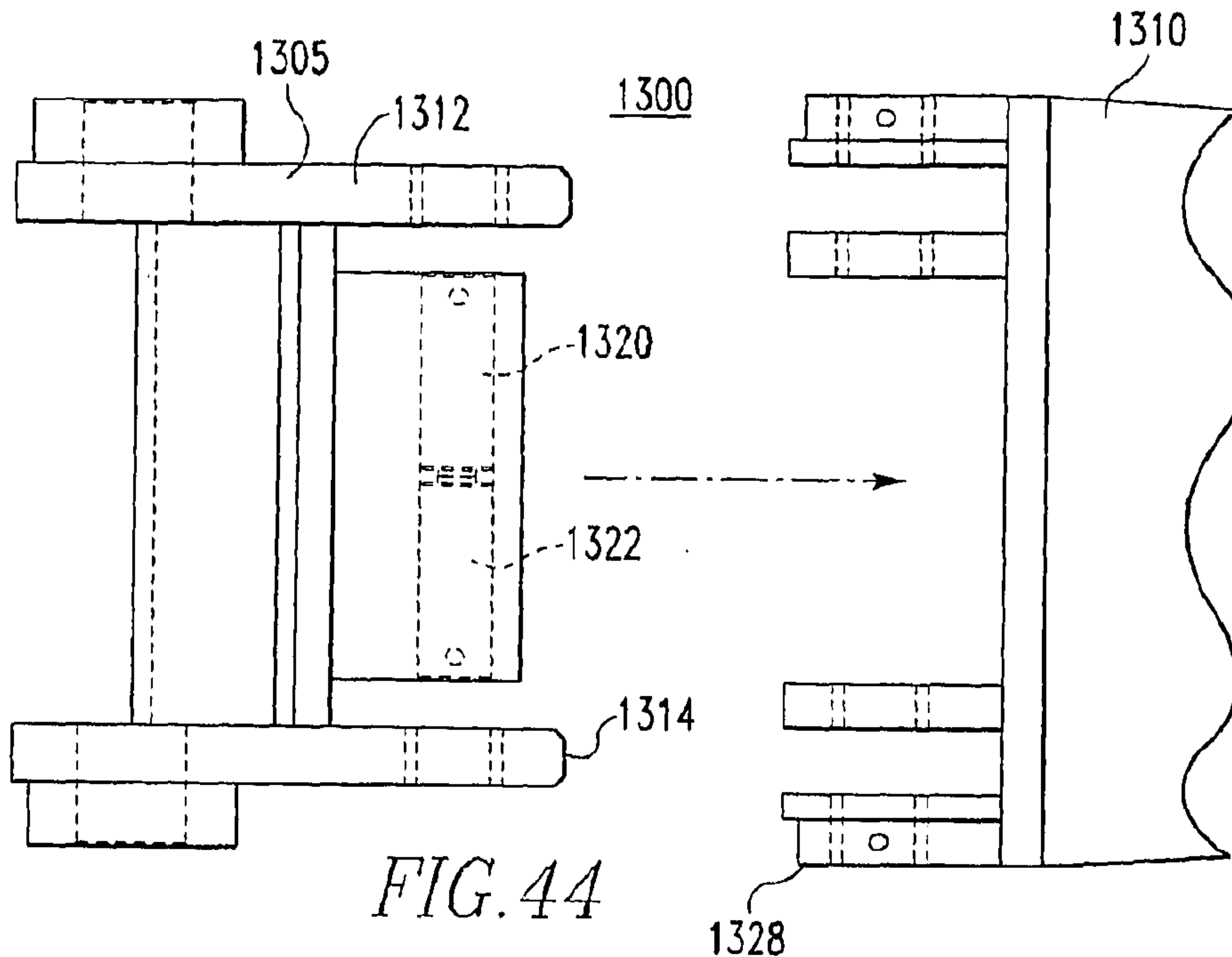


FIG. 44

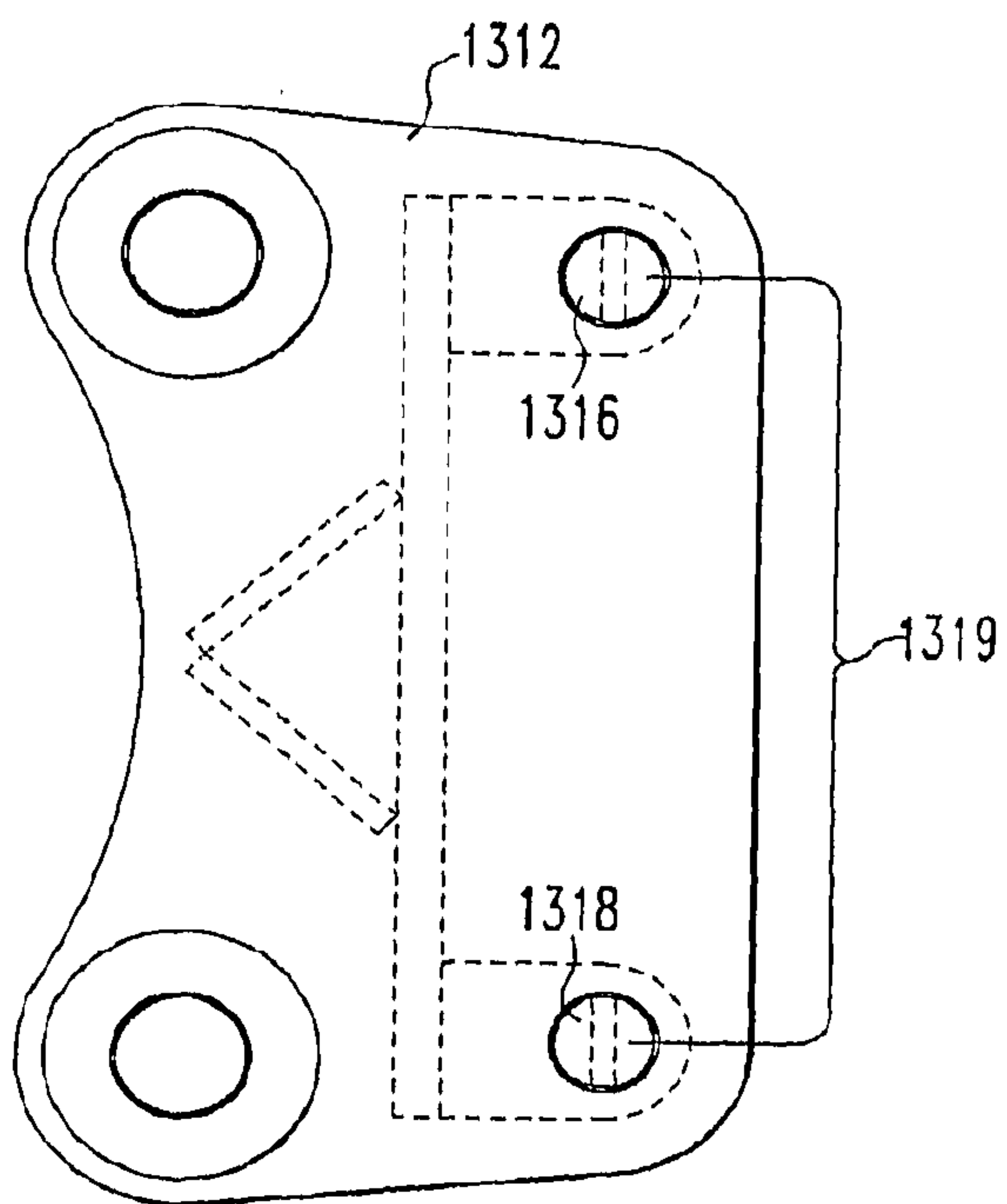


FIG. 45

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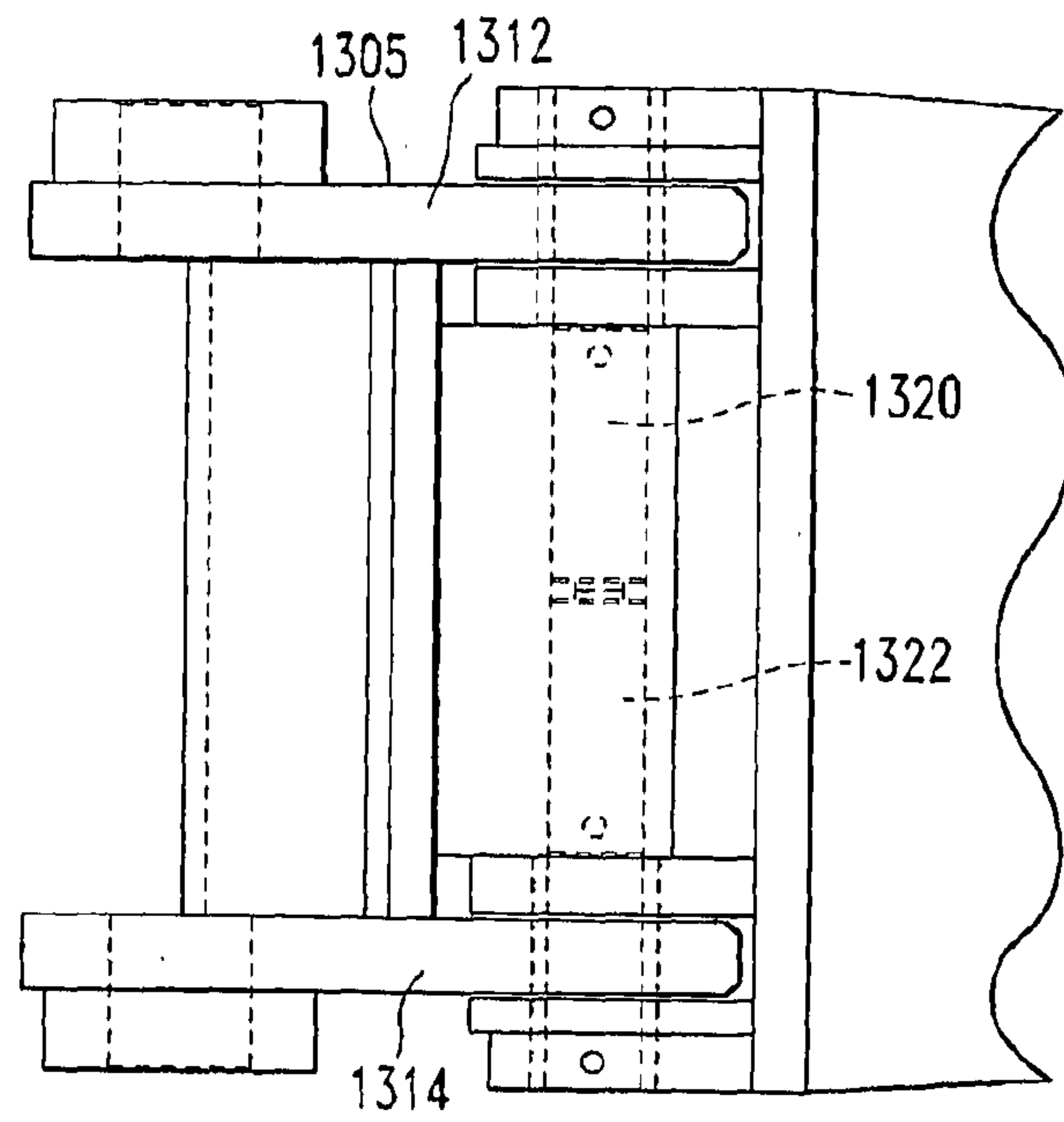


FIG. 46

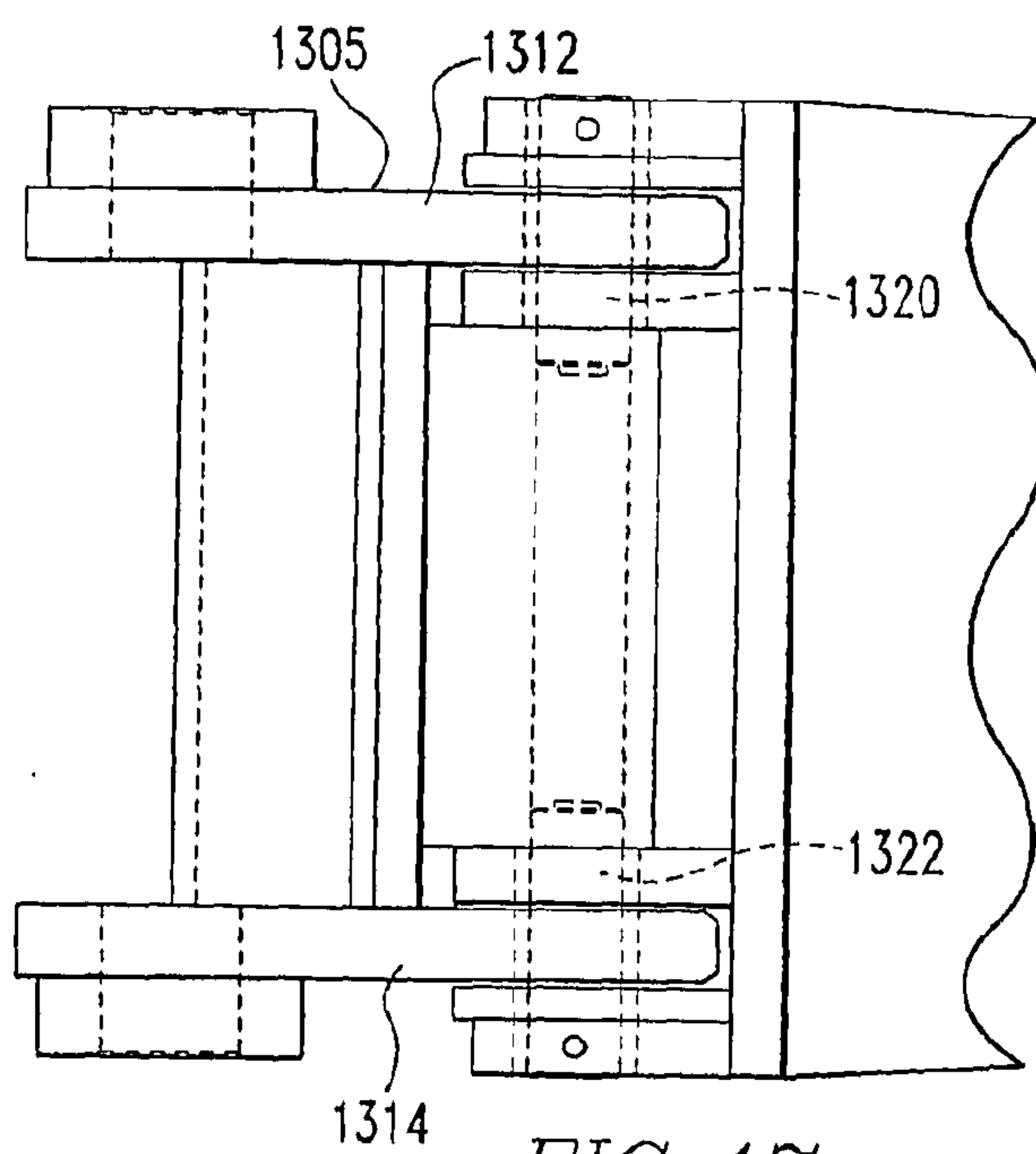


FIG. 47

