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(54) **RESETTABLE VOLTAGE CONTROLLED OSCILLATORS (VCOS) FOR CLOCK AND DATA RECOVERY (CDR) CIRCUITS, AND RELATED SYSTEMS AND METHODS**

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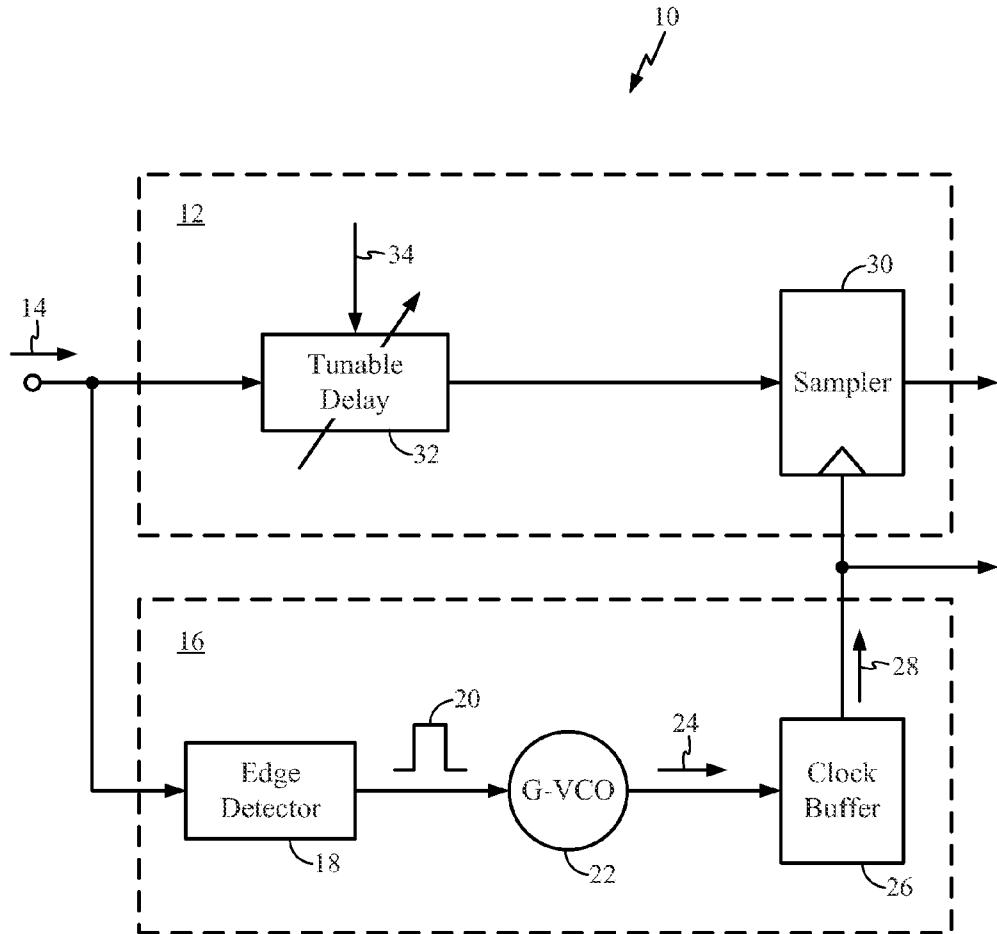
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(57)

ABSTRACT

Clock and data recovery (CDR) circuits and resettable voltage controlled oscillators (VCOs) are disclosed. In one embodiment, the CDR circuit includes a sampler configured to receive a data stream in a data path and sample the data stream. However, a clock signal of the data stream needs to be recovered to sample the data stream since the data stream may not be accompanied by the clock signal. To recover the clock signal from the data stream, the CDR circuit may have a resettable VCO configured to generate a clock output. The sampler and the resettable VCO may be operably associated so that the sampler samples the data stream in the data path based on the clock output. The resettable VCO can be reset to adjust a clock phase of the clock output and help reduce sampling errors resulting from drift of the clock output and/or the data stream.



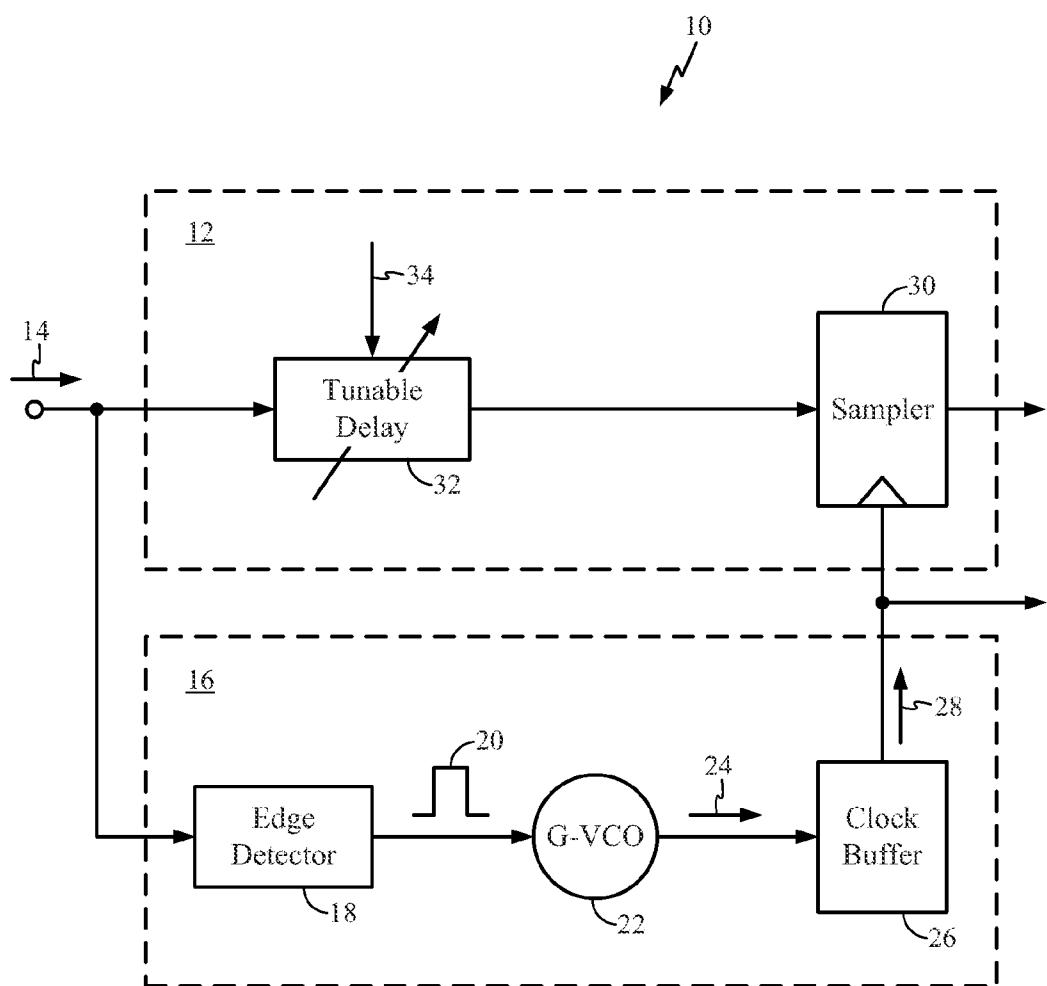


FIG. 1

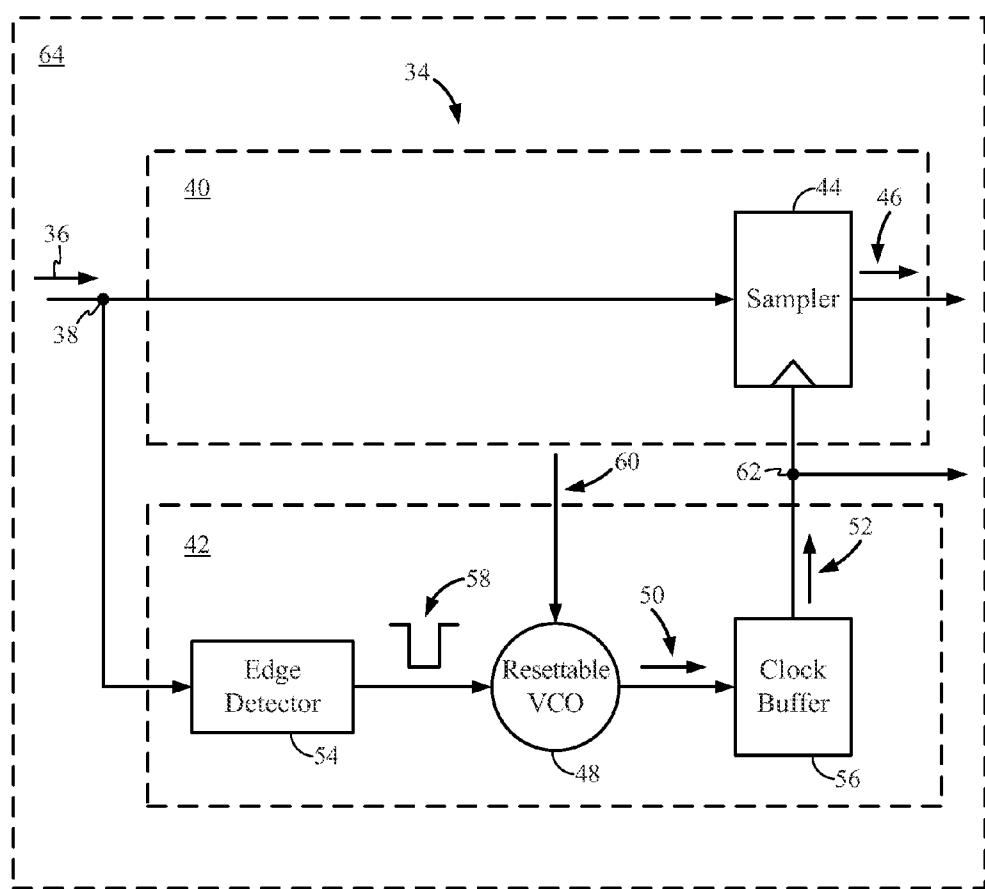


FIG. 2

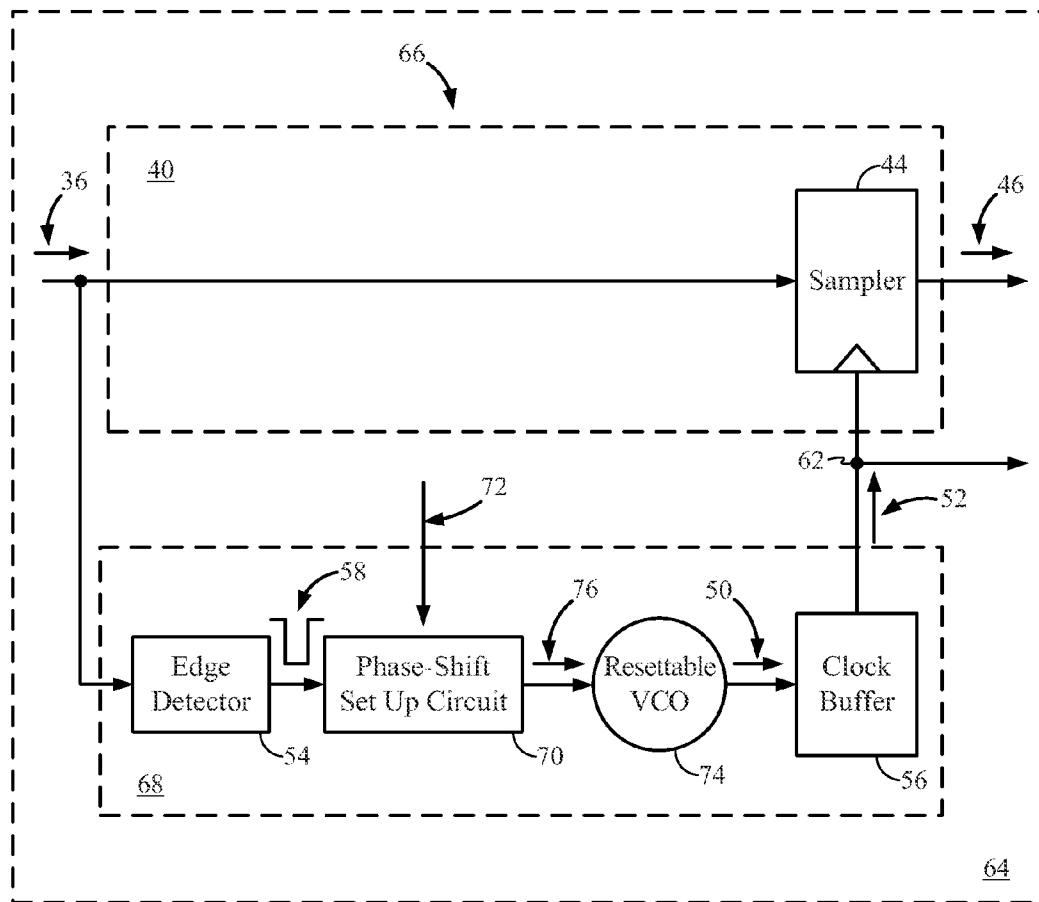
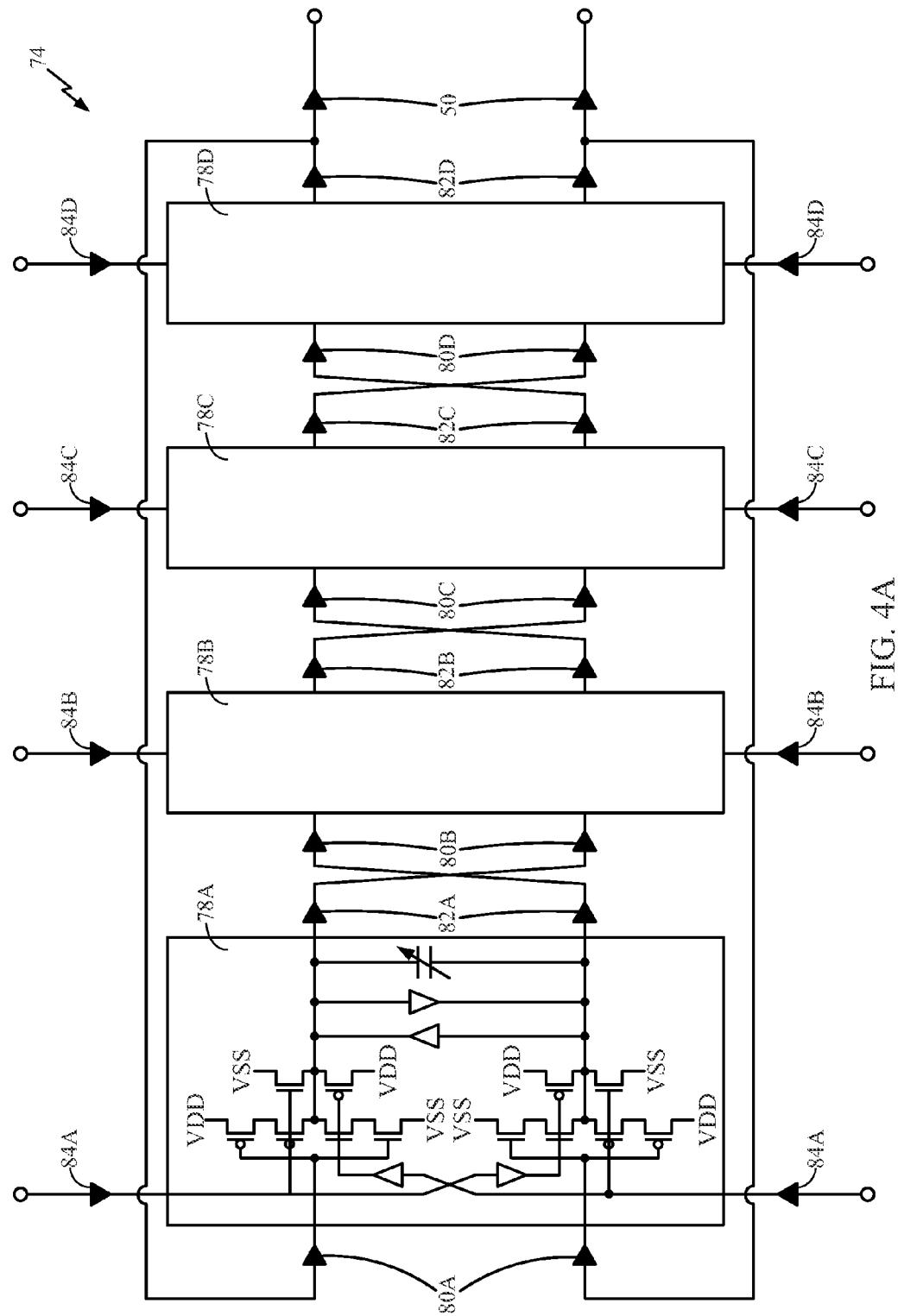


FIG. 3



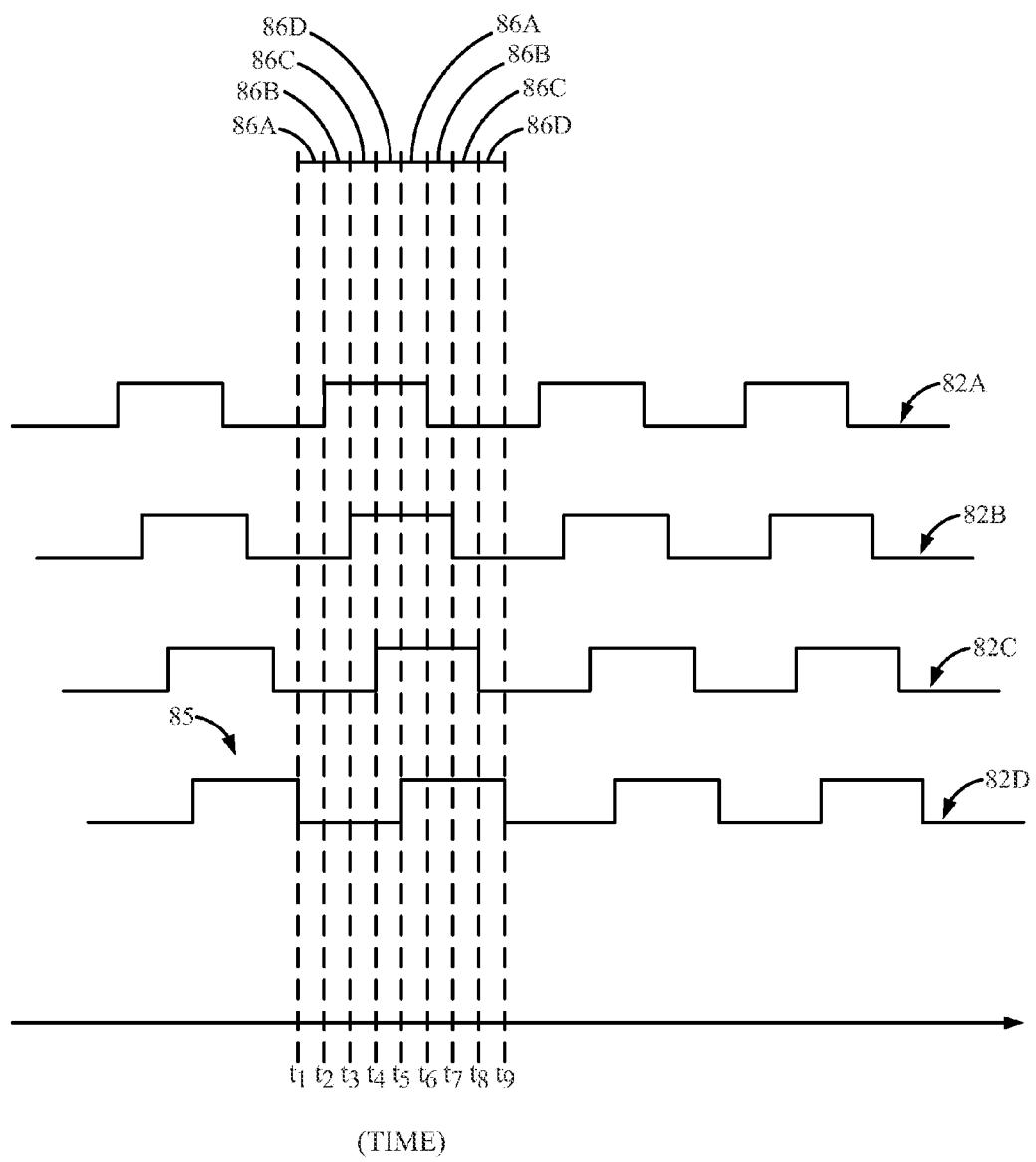


FIG. 4B

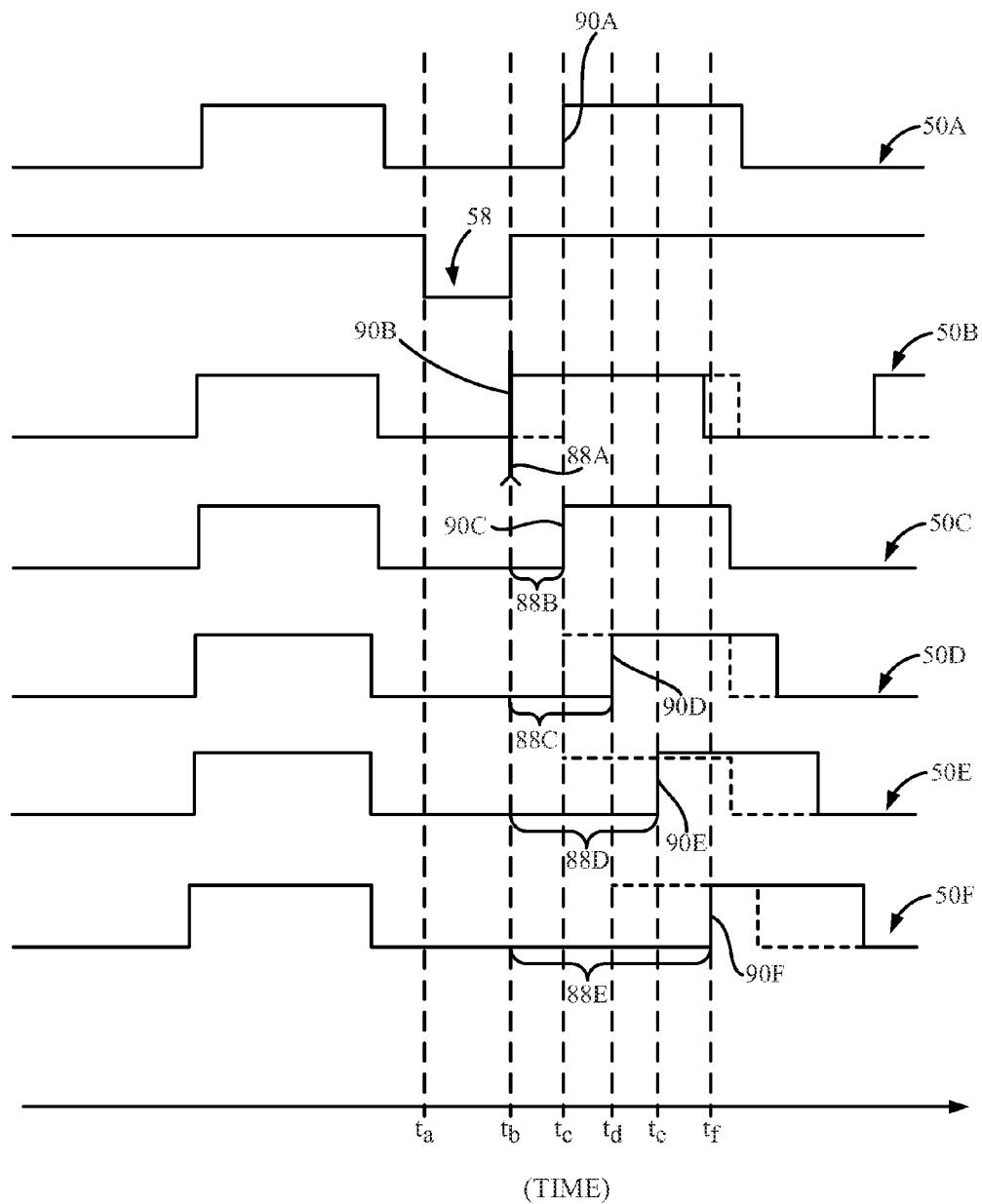


FIG. 4C

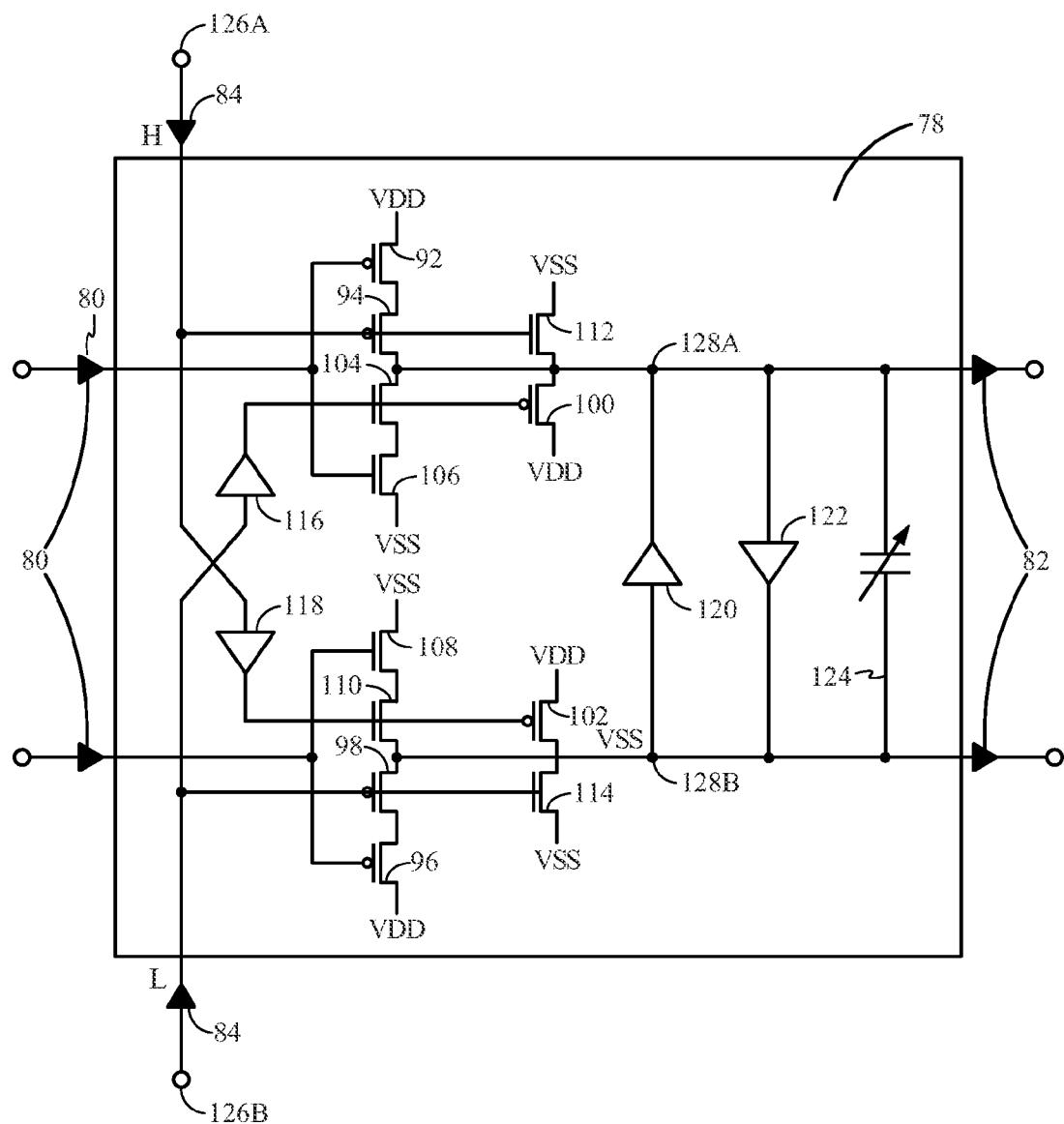


FIG. 4D

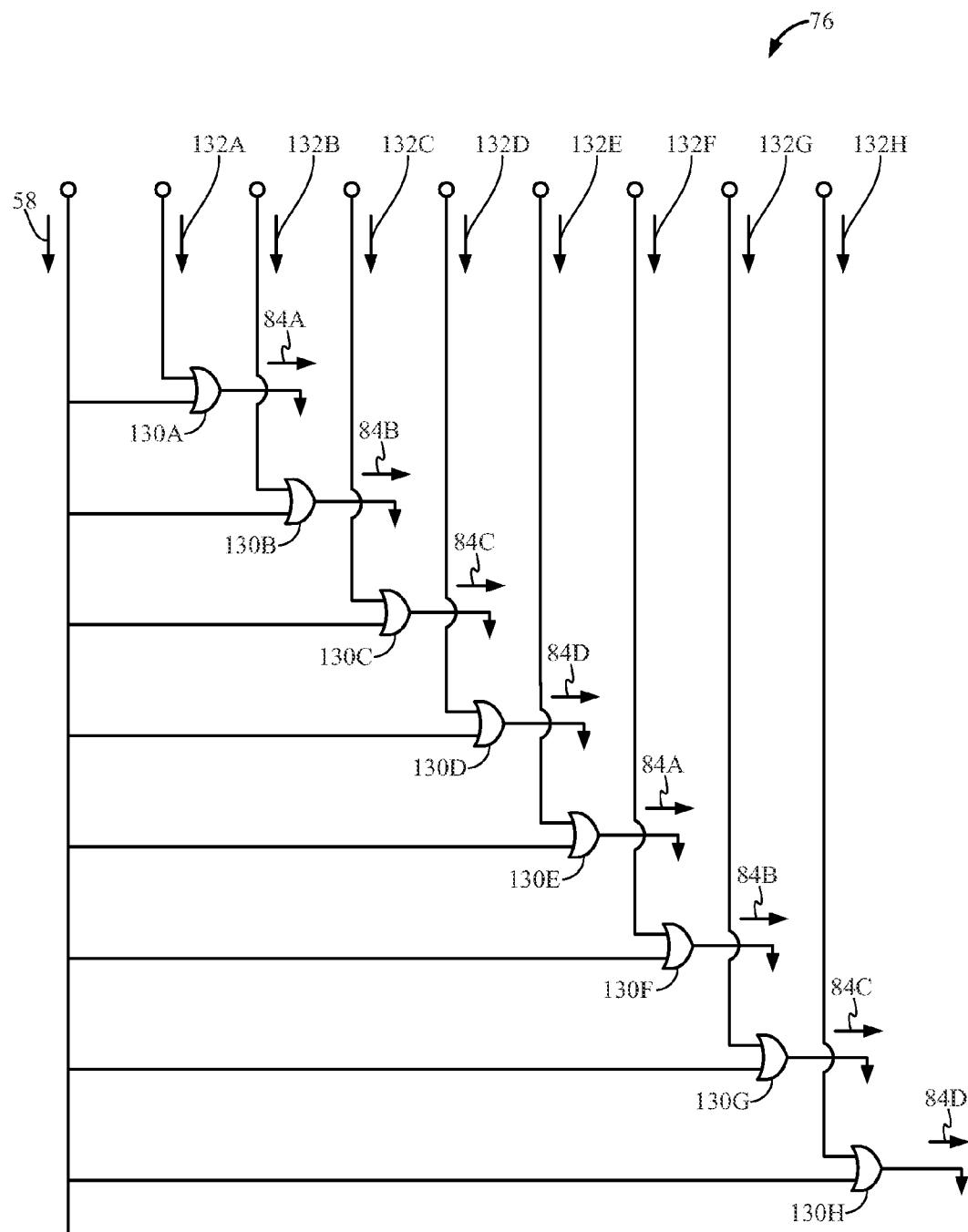


FIG. 5

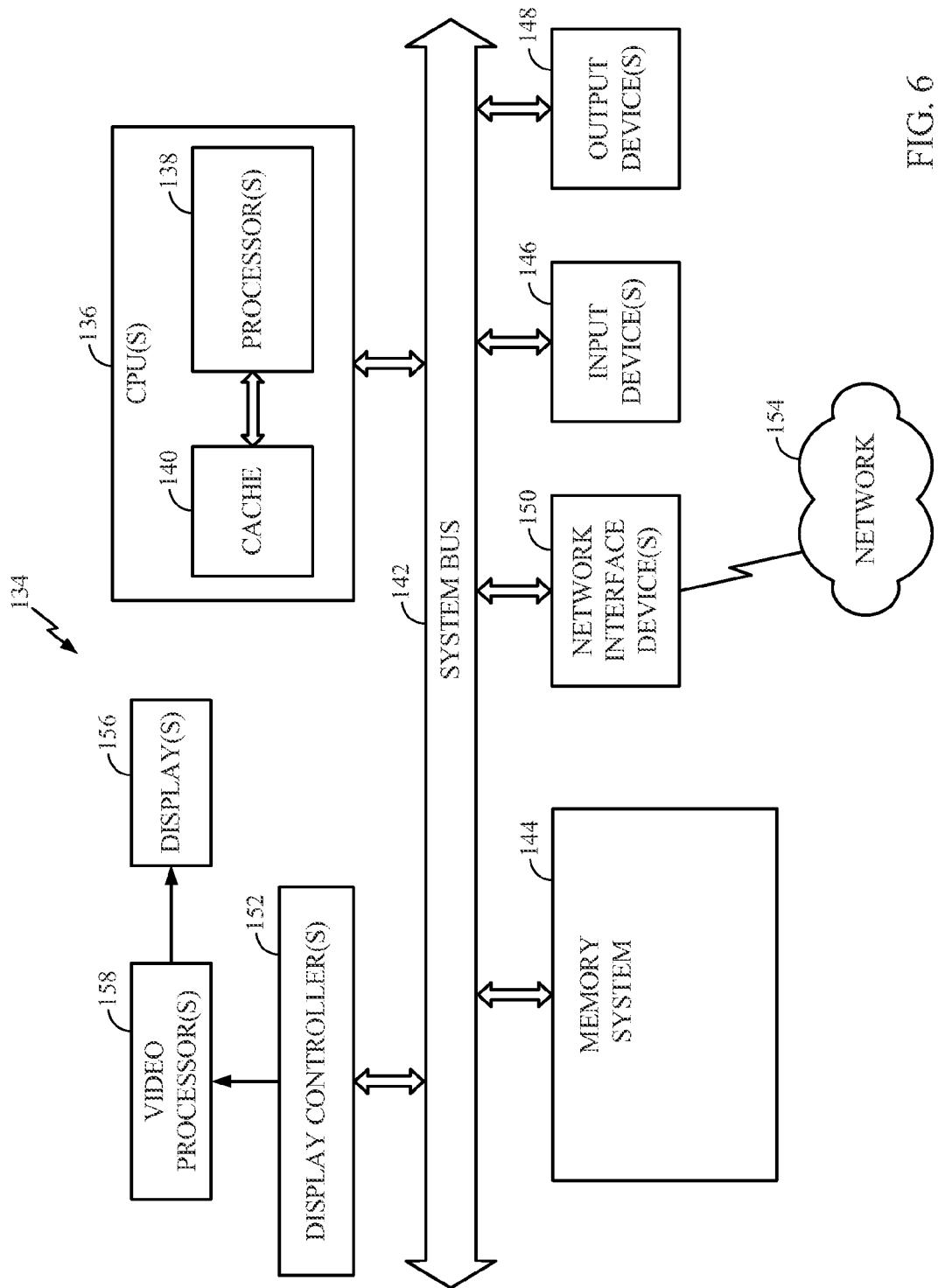


FIG. 6

RESETTABLE VOLTAGE CONTROLLED OSCILLATORS (VCOS) FOR CLOCK AND DATA RECOVERY (CDR) CIRCUITS, AND RELATED SYSTEMS AND METHODS

PRIORITY APPLICATION

[0001] The present application claims priority to U.S. Provisional Patent Application Ser. No. 61/599,692 entitled "RESETTABLE VOLTAGE CONTROLLED OSCILLATORS (VCOS) FOR CLOCK DATA RECOVERY (CDR), AND RELATED CDR CIRCUITS, SYSTEMS, AND METHODS" filed on Feb. 16, 2012, which is hereby incorporated herein by reference in its entirety.

BACKGROUND

[0002] I. Field of the Disclosure

[0003] The technology of the disclosure relates to clock and data recovery (CDR) circuits that recover a clock signal from data stream for sampling the data stream.

[0004] II. Background

[0005] A data stream is sometimes transmitted without an accompanying clock. Communicating the data stream without an accompanying clock signal reduces the bandwidth required to transmit the data stream. However, to recover bits from the data stream, the data stream is typically sampled by a sampler that needs a timing reference to sample the data stream appropriately. One way of providing this timing reference is to provide a clock and data recovery (CDR) circuit that recovers a clock signal from the data stream. CDR is the process of extracting and reconstructing a clock signal from a data stream unaccompanied by a clock signal. The generated clock signal is provided to the sampler to control when the data stream is sampled and recover data bits in the data stream.

[0006] FIG. 1 illustrates an example of a CDR circuit 10. In this regard, the CDR circuit 10 includes a data path 12 that carries a data stream 14. To recover a clock signal from this data stream 14, the CDR circuit 10 includes a clock path 16. The clock path 16 includes an edge detector 18 that detects an edge in the data stream 14 (i.e., a transition in bit values). In response to detection of the edge in the data stream 14, the edge detector 18 generates a reset pulse 20 to a gated voltage controlled oscillator (VCO) 22 in order to generate a clock output 24. The gated VCO 22 is reset on edge detection to avoid clock phase drift of the clock output 24. The clock output 24 generated by the gated VCO 22 is provided to a clock buffer 26 that provides a buffered clock output 28. The buffered clock output 28 is used by a sampler 30 in the data path 12 to control the time of the sampling of the data stream 14. In the data path 12, a tunable delay 32 is provided between the data input and the sampler 30. The tunable delay 32 phase shifts the data stream 14 relative to the clock output 24 so the sampler 30 samples the data at an optimal phase (e.g., the maximum opening of an eye pattern for the data stream 14). The amount of delay provided by the tunable delay 32 is controlled by a delay control code 34.

[0007] Providing the tunable delay 32 in the data path 12 of the CDR circuit 10 requires additional hardware and die area, and can increase power consumption.

SUMMARY OF THE DISCLOSURE

[0008] Embodiments disclosed in the detailed description include clock and data recovery (CDR) circuits and resettable

voltage controlled oscillators (VCOs). The CDR circuits and resettable VCOs disclosed herein do not require a tunable delay circuit in a data path. To recover bits communicated within a data stream, one embodiment of the CDR circuit includes a sampler configured to receive a data stream in a data path and sample the data stream. A clock signal recovered from the data stream is used by the sampler to sample the data stream. To recover the clock signal from the data stream, the CDR circuit includes a resettable VCO configured to generate a clock output. The sampler and the resettable VCO may be operably associated so that the sampler samples the data stream in the data path based on the clock output. To reduce errors during sampling, the resettable VCO is configured to phase shift the clock output so that the data stream and the clock output are appropriately phase aligned. In this manner, a tunable delay circuit is not needed in the data path to phase align the clock output and the data stream.

[0009] In one embodiment of the resettable VCO, the resettable VCO can be reset to phase shift the clock output and help reduce sampling errors resulting from drift in the CDR circuit. More particularly, the clock output generated by the resettable VCO has a clock phase. As the phase of the data stream and/or the clock phase of the clock output can experience drift, the resettable VCO may be configured to receive a phase control input indicative of a phase setting for the clock phase of the clock output. As a result of edge detection in the data stream, the resettable VCO adjusts the clock phase of the clock output based on the phase control input. As such, the clock phase of the clock output can be realigned with the phase of the data stream thereby reducing sampling errors caused by drift.

[0010] One embodiment of a CDR circuit has a clock path that includes the resettable VCO. The clock path of the CDR circuit also has an edge detector configured to receive the data stream. Upon detection of an edge in the data stream, the edge detector generates a reset pulse. The resettable VCO is configured to adjust the clock phase of the clock output based on the phase control input as a result of the reset pulse. In this manner, the clock output is phase shifted and a tunable delay circuit is not needed in the data path.

[0011] In another embodiment, a method for generating a clock output from a data stream in a CDR circuit is provided. The method allows for the phase alignment of the clock output and the data stream without tunably delaying the data stream in a data path. The method includes generating the clock output having a clock phase. The method also includes receiving a phase control input indicative of a phase setting for the clock phase of the clock output. To align the clock phase of the clock output with the phase of the data stream, the method also includes adjusting the clock phase of the clock output based on the phase control input as a result of edge detection in the data stream.

[0012] In yet another embodiment, a computer readable medium is provided. The computer readable medium stores computer executable instructions that may be implemented by a processor-based resettable VCO. The computer executable instructions are configured to cause the processor-based resettable VCO to generate a clock output having a clock phase. By implementing the computer executable instructions, the processor-based resettable VCO also is configured to receive a phase control input indicative of a phase setting for the clock phase. As a result of edge detection, the computer executable instructions cause the processor-based resettable VCO to adjust the clock phase of the clock output based

on the phase control input. By executing the computer executable instructions stored on the computer readable medium, the processor-based resettable VCO eliminates the need for a tunable delay circuit in a data path to phase align the clock output and the data stream.

BRIEF DESCRIPTION OF THE FIGURES

[0013] FIG. 1 is a block diagram of an exemplary clock and data recovery (CDR) circuit with a tunable delay including a data path and a gated voltage controlled oscillator (VCO) included in a clock path that generates a clock output to a sampler to control sampling of the data stream;

[0014] FIG. 2 is a block diagram of an exemplary CDR circuit including a data path that carries a data stream, and including a clock path having an exemplary resettable VCO configured to generate a clock output in the clock path for controlling sampling of the data stream in the data path;

[0015] FIG. 3 is a block diagram of another exemplary CDR circuit including a data path that carries a data stream, and including a clock path having another exemplary resettable VCO configured to generate a clock output in the clock path for controlling sampling of the data stream in the data path;

[0016] FIG. 4A is a diagram of internal circuitry of an exemplary resettable VCO having a plurality of delay stages;

[0017] FIG. 4B is a timing diagram illustrating exemplary differential outputs of the delay stages in the resettable VCO shown in FIG. 4A;

[0018] FIG. 4C is a timing diagram illustrating an exemplary reset pulse and phase-shifted clock outputs that can be provided by the resettable VCO in FIG. 4A;

[0019] FIG. 4D is an exemplary circuit diagram of a delay stage in the resettable VCO of FIG. 4A;

[0020] FIG. 5 is an exemplary circuit diagram of the phase-shift set up circuit in the clock path of the exemplary CDR circuit in FIG. 3, wherein the phase-shifting set up circuit is configured to generate a gated phase control input for the resettable VCO in FIG. 4A; and

[0021] FIG. 6 is a block diagram of an exemplary processor-based system that can include the CDR circuits of the present disclosure.

DETAILED DESCRIPTION

[0022] With reference now to the drawing figures, several exemplary embodiments of the present disclosure are described. The word "exemplary" is used herein to mean "serving as an example, instance, or illustration." Any embodiment described herein as "exemplary" is not necessarily to be construed as preferred or advantageous over other embodiments.

[0023] A data stream communicated to another device may be unaccompanied by a clock signal. Less bandwidth is required to transmit the data stream if an accompanying clock signal is not provided. Nevertheless, the data stream may need to be sampled to recover bits in the received data stream. Accordingly, a timing reference is needed to sample the data stream. One method of providing a timing reference is to recover a clock signal from the data stream by providing a clock and data recover (CDR) circuit.

[0024] Embodiments disclosed in the detailed description include clock and data recovery (CDR) circuits and resettable voltage controlled oscillators (VCOs). The CDR circuits and resettable VCOs disclosed herein do not require a tunable

delay circuit in a data path. To recover bits communicated within a data stream, one embodiment of the CDR circuit includes a sampler configured to receive a data stream in a data path and sample the data stream. A clock signal recovered from the data stream is used by the sampler to sample the data stream. To recover the clock signal from the data stream, the CDR circuit includes a resettable VCO configured to generate a clock output. The sampler and the resettable VCO may be operably associated so that the sampler samples the data stream in the data path based on the clock output. To reduce errors during sampling, the resettable VCO is configured to phase shift the clock output so that the data stream and the clock output are appropriately phase aligned. In this manner, a tunable delay circuit is not needed in the data path to phase align the clock output and the data stream.

[0025] In one embodiment of the resettable VCO, the resettable VCO can be reset to phase shift the clock output and help reduce sampling errors resulting from drift in the CDR circuit. More particularly, the clock output generated by the resettable VCO has a clock phase. As the phase of the data stream and/or the clock phase of the clock output can experience drift, the resettable VCO may be configured to receive a phase control input indicative of a phase setting for the clock phase of the clock output. As a result of edge detection in the data stream, the resettable VCO adjusts the clock phase of the clock output based on the phase control input. As such, the clock phase of the clock output can be realigned with the phase of the data stream thereby reducing sampling errors caused by drift.

[0026] One embodiment of a CDR circuit has a clock path that includes the resettable VCO. The clock path of the CDR circuit also has an edge detector configured to receive the data stream. Upon detection of an edge in the data stream, the edge detector generates a reset pulse. The resettable VCO is configured to adjust the clock phase of the clock output based on the phase control input as result of the reset pulse. In this manner, the clock output is phase shifted and a tunable delay circuit is not needed in the data path.

[0027] In this regard, FIG. 2 illustrates one embodiment of a CDR circuit 34 configured to recover a clock signal from a data stream 36 to be provided to a sampler to recover bits from the data stream 36. The CDR circuit 34 receives the data stream 36 at an input node 38. The input node 38 is operably associated with a data path 40 and a clock path 42 in the CDR circuit 34. The data stream 36 at the input node 38 is carried along the data path 40. To recover the bits from the data stream 36, the CDR circuit 34 includes a sampler 44 in the data path 40. The sampler 44 is configured to receive and sample the data stream 36 in the data path 40. The sampler 44 generates a data output 46 indicative of bits recovered from the data stream 36. In one embodiment, the data output 46 has an non-return to zero (NRZ) signal format. For instance, if the sample obtained by the sampler 44 is above a threshold voltage level, this indicates a logical "1". The sampler 44 generates the data output 46 as having a high voltage level to indicate that the bit recovered from the data stream 36 is a "1". If the sample obtained from the data stream 36 is below the threshold voltage level, no pulse is generated in the data output 46 to indicate that the bit recovered from the data stream 36 is a "0". In this manner, the sampler 44 generates the data output 46 representing the recovered bits from the data stream 36.

[0028] However, the sampler 44 has to sample the data stream 36 at an appropriate sampling phase. Since the data

stream **36** may be received unaccompanied by a clock signal, the CDR circuit **34** in FIG. 2 also includes the clock path **42**. The clock path **42** includes a resettable VCO **48** configured to generate a clock output **50** having a clock phase as the recovered clock signal from the data stream **36**. The sampler **44** in the data path **40** samples the data stream **36** based on the clock output **50**. In this embodiment, the sampler **44** receives a buffered clock output **52** based on the clock output **50**. Accordingly, the sampler **44** samples the data stream **36** based on the clock output **50** generated by the resettable VCO **48**.

[0029] To reduce sampling errors in the data output **46**, the clock phase of the clock output **50** is controlled according to the phase of the data stream **36**. An eye pattern of the data stream **36** may be utilized to determine the optimum phase for sampling the data stream **36**. The eye pattern of the data stream **36** provides traces of different symbols employed by the modulation technique of the data stream **36**. (The traces may show the signal levels of the different symbols when received by the sampler **44**.) Additionally, the traces may be plotted over a single symbol period so that differences in the signal levels of the different symbols can be readily observed from the eye diagram. In this particular example, the bit rate is assumed to be equal to the symbol rate. Alternative embodiments may implement schemes where different symbols represent groupings of one or more bits in the data stream **36**.

[0030] The symbol period may be determined from a symbol rate of the modulation technique, which is typically an integer multiple of a bit rate of the data stream **36**. In this example, the symbol rate is equal to the bit rate and thus the symbol period is equal to 1/bit rate. A maximum opening of the eye pattern indicates when sampling the data stream **36** is least likely to produce sampling errors. The maximum opening of the eye pattern is temporally positioned at a particular time (or at particular times) during the symbol period. This particular time (or particular times) corresponds to an optimum phase (or optimum phases) for sampling the data stream **36**.

[0031] With continuing reference to FIG. 2, the resettable VCO **48** may initially align the clock phase of the clock output **50**, (and thus the clock phase of the buffered clock output **52**) so the sampler **44** samples the data stream **36** at or close to optimum data phases. Even so, the clock output **50** can drift thereby modifying the phase alignment between the data stream **36** and the clock output **50**, which may increase the error rate of the data output **46**. In this regard, the resettable VCO **48** is configured to adjust the clock phase of the clock output **50** as a result of edge detection in the data stream **36**. This helps maintain sampling of the data stream **36** by the sampler **44** at or close to the optimum phase (or optimum phases) and reduces the error rate of the data output **46** generated by the sampler **44**. As the data stream **36** may be employed using any type of communication format, different embodiments of the resettable VCO **48** may be employed to phase align the clock output **50** and the data stream **36** depending on the particular communication format of the data stream **36**.

[0032] In this particular embodiment, the clock path **42** is also coupled to the input node **38** so as to receive the data stream **36** and recover the clock signal from the data stream **36**. The clock path **42** includes an edge detector **54**, the resettable VCO **48**, and a clock buffer **56**. The edge detector **54** is configured to receive the data stream **36** and generate a reset pulse **58** upon detection of an edge in the data stream **36**. The resettable VCO **48** is coupled to the edge detector **54** and

is configured to generate the clock output **50** having the clock phase. In particular, the resettable VCO **48** generates the clock output **50** such that the clock output **50** has a clock frequency based on the bit rate of the data stream **36**. Since the CDR circuit **34** may be configured to operate with the data stream **36** communicated over a particular communication channel, the bit rate of the data stream **36** may be inherently known. On the other hand, the bit rate of the data stream **36** may be determined by other devices upstream or downstream from the CDR circuit **34**, and the resettable VCO **48** may be adjusted to generate the clock output **50** with a clock frequency based on the bit rate. In one example, the clock frequency of the clock output **50** is approximately double the bit rate so that the sampler **44** samples the data stream **36** according to the Nyquist sampling rate. Alternatively, the resettable VCO **48** may be responsive to the timing of the reset pulses **58** from the edge detector **54** (or from another edge detector) in order to generate the clock output **50** with a clock frequency based on the bit rate of the data stream **36**.

[0033] The edge detector **54** may generate the reset pulse **58** upon detection of every edge in the data stream **36** or, alternatively, every n^{th} number of edges in the data stream **36**. This may depend on the particular characteristics of the data stream **36** and the desired sampling technique to be employed by the sampler **44**. For example, if the data stream **36** is a NRZ signal, each bit in the data stream **36** may not have complimentary edges. This occurs in an NRZ signal when consecutive bits have the same bit value. Accordingly, in one embodiment, the edge detector **54** generates the reset pulse **58** at every edge of the data stream **36**. In other words, reset pulses **58** are generated at both positive and negative transition edges, at only positive edges, or at only negative edges. This allows the resettable VCO **48** to provide phase alignment after every edge or at certain edges. For example, reset pulses **58** may be generated for every positive transition edges in the data stream **36**. Alternatively, reset pulses **58** may be generated for every negative transition edge in the data stream **36**.

[0034] The NRZ signal format is often utilized in data transmission since an NRZ signal with the same bit rate as an RZ signal requires less bandwidth. Different applications may employ the NRZ format, the RZ format, and any other format to represent bits within the data stream **36**. While the specific embodiments discussed herein employ a data stream having an NRZ signal format, other embodiments of the CDR circuit **34** and the components of the CDR circuit **34** may be configured to recover clock signals from data streams having any other format. With regard to the edge detector **54** shown in FIG. 2, the data stream **36** is presumed to have an NRZ signal format and the edge detector **54** is configured to generate reset pulses **58** in response to every edge of the data stream **36**. Alternatively, the edge detector **54** may be configured to generate the reset pulses **58** for only rising or falling edges. Still other embodiments of the CDR circuit **34** may be designed to generate reset pulses for data streams with other signal formats and for selected edges within the data stream in accordance with the signal format.

[0035] To prevent or correct drift of the data stream **36** and/or the clock output **50**, the resettable VCO **48** may be configured to receive a phase control input **60** indicative of a phase setting for the clock phase of the clock output **50**. The resettable VCO **48** adjusts the clock phase of the clock output **50** based on the phase control input **60**. Furthermore, the resettable VCO **48** is configured to adjust the clock phase of the clock output **50** as a result of edge detection in the data

stream 36. As such, the adjustments to the clock phase of the clock output 50 may be provided in response to the reset pulse 58. In this particular embodiment, the resettable VCO 48 operates in a reset mode in response to the reset pulse 58 from the edge detector 54. In the reset mode, the resettable VCO 48 resets so that the clock phase of the clock output 50 is provided in accordance to the phase setting indicated by the phase control input 60 upon release of the reset pulse 58. Once the reset pulse is released, the resettable VCO 48 operates in an oscillation mode where the resettable VCO 48 is simply configured to generate the clock output 50.

[0036] It should be noted that the CDR circuit 34 of FIG. 2 does not include a tunable delay circuit in the data path 40 to adjust the phases of the data stream 36. Rather, the clock path 42 shifts the clock output 50 to align the clock phase of the clock output 50 with the data stream 36. By utilizing the resettable VCO 48 to provide phase alignment, the hardware, die area, and power consumption of the CDR circuit 34 may be reduced.

[0037] During the oscillation mode, the resettable VCO 48 shown in FIG. 2 is unresponsive to the phase control input 60 regardless of whether the phase control input 60 is being received. However, when the reset pulse 58 is received, the resettable VCO 48 operates in the reset mode so the clock phase of the clock output 50 can be adjusted in accordance with the phase setting indicated by the phase control input 60. This allows the embodiment of the resettable VCO 48 in FIG. 2 to provide phase adjustments of the clock output 50 relative to the current phase of the data stream 36, as indicated by the reset pulse 58.

[0038] The clock path 42 and the data path 40 are coupled to the sampler 44. The sampler 44 samples the data stream 36 in the data path 40 based on the clock output 50. The sampler 44 may sample the data stream 36 based on the clock output 50 by directly receiving the clock output 50, by indirectly receiving the clock output 50, or by receiving another type of clock signal generated in accordance with the clock output 50. In this embodiment, the clock buffer 56 is coupled between the resettable VCO 48 and the sampler 44. The clock buffer 56 is configured to receive the clock output 50 from the resettable VCO 48 and provide a buffered clock output 52 to the sampler 44. In this example, the sampler 44 indirectly receives the clock output 50 since the buffered clock output 52 is a buffered version of the clock output 50. Additionally, the buffered clock output 52 is also independently transmitted from an output node 62 of the CDR circuit 34 so that the buffered clock output 52 can be utilized by downstream circuits coupled to the CDR circuit 34. In one embodiment, the sampler 44 generates the data output 46 as an NRZ signal. Accordingly, while the bit rate of the data output 46 and the data stream 36 may be equal, the frequency components of the data stream 36 and the data output 46 may be different. The data output 46 may be sent from the sampler 44 to downstream circuitry for further processing.

[0039] With continuing reference to FIG. 2, the phase control input 60 is utilized in order to correct misalignments due to drift between the clock phase of the clock output 50, the clock phase of the buffered clock output 52, and the data stream 36. In this regard, the phase setting indicated by the phase control input 60 realigns the clock phase of the clock output 50 to control sampling by the sampler 44 at or close to the optimum phase of the data stream 36, if possible.

[0040] As shown in FIG. 2, the CDR circuit 34 has been integrated into a semiconductor die 64. As such, the data path

40, the clock path 42, the sampler 44, the edge detector 54, the resettable VCO 48, and the clock buffer 56, are circuits that have been integrated into the semiconductor die 64. Alternatively, one or more of the components of the CDR circuit 34 may be provided on a separate semiconductor die(s). For instance, alternative embodiments of a resettable VCO may be implemented using general purpose computer hardware, such as a microprocessor. These processor-based resettable VCOs may be provided on a separate semiconductor die and are operable to implement computer-executable instructions. The computer-executable instructions cause the processor-based resettable VCOs to generate the clock output 50, receive the phase control input 60, and adjust the clock phase of the clock output 50 based on the phase control input 60 as a result of edge detection in the data stream 36. The processor-based resettable VCOs may thus be used in embodiments of the CDR circuit analogous to the CDR circuit 34 shown in FIG. 2. Computer-executable instructions may also be provided for other processor-based resettable VCOs configured to operate with other CDR circuits within the scope of this disclosure.

[0041] FIG. 3 illustrates another exemplary CDR circuit 66 in accordance with this disclosure. The CDR circuit 66 is also operable to recover bits and a clock signal from the data stream 36. However, a different exemplary clock path 68 is used in the CDR circuit 66 to control sampling of the sampler 44. Unlike the clock path 42 shown in FIG. 2, the clock path 68 includes a phase-shift setup circuit 70 configured to receive the reset pulse 58 from the edge detector 54 and a preliminary phase control input 72. Additionally, another exemplary resettable VCO 74 is provided in the clock path 68 to generate the clock output 50.

[0042] The phase-shift setup circuit 70 in FIG. 3 generates a phase control input 76 based on the preliminary phase control input 72 and the reset pulse 58. More specifically, the phase-shift setup circuit 70 gates the preliminary phase control input 72 with the reset pulse 58. Since the phase-shift setup circuit 70 gates the preliminary phase control input 72 with the reset pulse 58, the phase control input 76 is gated by the reset pulse 58. In this manner, the phase-shift setup circuit 70 generates the phase control input 76 as a gated phase control input. As explained in further detail below, one embodiment of the preliminary phase control input 72 may be provided as a preliminary phase control code and one embodiment of the phase control input 76 may be provided as a gated phase control code.

[0043] With continuing reference to FIG. 3, the resettable VCO 74 is configured to receive the phase control input 76 from the phase-shift setup circuit 70 and adjust the clock phase of the clock output 50 based on the phase control input. The phase control input 76 is indicative of a phase setting for the clock phase of the clock output 50. Since the phase control input 76 received by the resettable VCO 74 is gated by the reset pulse 58, the resettable VCO 74 is configured to adjust the clock phase as a result of edge detection in the data stream 36. In this manner, the clock output 50 (and thus also the buffered clock output 52) can be aligned so that the data stream 36 is sampled at or near the optimum data phase.

[0044] FIG. 4A is an exemplary circuit diagram of the resettable VCO 74 shown in FIG. 3. The resettable VCO 74 has a plurality of delay stages (referred to generically as element 78 and individually as elements 78A-78D) configured to generate the clock output 50. In particular, each delay stage 78 is configured to receive a differential input (referred

to generically as element **80** and individually as elements **80A-80D**) and generate a differential output (referred to generically as element **82** and individually as elements **82A-82D**). The resettable VCO **74** of FIG. 4A has four delay stages **78A-78D**. However, as will become apparent to one of ordinary skill in the art in light of this disclosure, alternative embodiments of the resettable VCO **74** may have any number of delay stages **78**.

[0045] The delay stages **78** are collectively configured in an oscillation loop, which allows the delay stages **78** to generate the clock output **50**. Each delay stage **78** is programmable to operate in an oscillation mode and a reset mode. The resettable VCO **74** operates in the oscillation mode when not receiving the phase control input **76** (shown in FIG. 3) and the differential inputs **80** determine the differential outputs **82** in the oscillation mode. However, when the phase control input **76** is being received by the resettable VCO **74** shown in FIG. 4A, the resettable VCO **74** operates in the reset mode and the differential outputs **82** are determined by a series of codes (referred to generically as element **84** and individually as elements **84A-84D**). The series of codes **84** shown in FIG. 4A make up one embodiment of the phase control input **76** shown in FIG. 3. In this embodiment, the phase control input **76** is presumed to be a gated phase control code gated by the reset pulse **58** and indicative of edge detection in the data stream **36**. Unlike the oscillation mode, the code **84** received by the delay stage **78** determines the differential output **82** in the reset mode, not the differential input **80**. The phase setting indicated by the gated phase control code may represent a phase delay.

[0046] In the particular embodiment illustrated in FIG. 4A, the resettable VCO **74** includes an initial delay stage **78A**, a first intermediary delay stage **78B**, a second intermediary delay stage **78C**, and a final delay stage **78D**. The initial delay stage **78A** is configured to receive an initial differential input **80A** and generate an initial differential output **82A**. Analogously, the first intermediary delay stage **78B** is configured to receive a first intermediary differential input **80B** and generate a first intermediary differential output **82B**. The second intermediary delay stage **78C** is configured to receive a second intermediary differential input **80C** and generate a second intermediary differential output **82C**. Finally, the final delay stage **78D** is configured to receive a final differential input **80D** and generate a final differential output **82D**. The final differential output **82D** generated by the final delay stage **78D** is the clock output **50**.

[0047] To form the oscillation loop, the initial delay stage **78A** is configured to receive the clock output **50** as the initial differential input **80A**. As the final differential output **82D** is fed back to the initial delay stage **78A**, the initial delay stage **78A** generates the initial differential output **82A** in response to feedback received during the oscillation mode. The final delay stage **78D** is configured to receive the final differential input **80D**, which is based on the initial differential output **82A**. From this, the final delay stage **78D** generates the final differential output **82D**.

[0048] All that is required to provide oscillation during the oscillation mode is that the clock output **50** fed back to the resettable VCO **74** results in an inversion of the clock output **50** by the resettable VCO **74**. In this example, the final differential output **82D** is the clock output **50** and the clock output **50** is fed back to the initial delay stage **78A** as the initial differential input **80A**. The inversion of the final differential output **82D** results in the inversion of the initial differential

input **80A** which again results in the inversion of the final differential output **82D**. As these inversions are continually repeated due to feedback, the oscillation of the clock output **50** is provided. The clock frequency of the clock output **50** is determined by a total propagation delay of the resettable VCO **74**. More specifically, the total propagation delay of the resettable VCO **74** may be equal to about half of a clock period since inversion of the clock output **50** takes place after the total propagation delay. FIG. 4A illustrates circuit components that may be utilized to form the initial delay stage **78A**. The functionality of these components will be explained in further detail in FIG. 4D. However, the first intermediary delay stage **78B**, the second intermediary delay stage **78C**, and the final delay stage **78D** are presumed to have the same components as the initial delay stage **78A**.

[0049] In the oscillation mode, when the delay stages **78** are not receiving the codes **84**, each delay stage **78A-78D** is configured to invert the differential inputs **80** so that the differential outputs **82** have an inverse polarity of the differential inputs **80**. However, each delay stage **78** has a delay stage propagation delay. The delay stage propagation delay determines the amount of time required by the delay stage **78** to generate the differential output **82** with the inverse polarity of the differential input **80**.

[0050] Referring now to FIG. 4B and with continuing reference to FIG. 4A, FIG. 4B illustrates embodiments of the differential outputs **82A-82D** which may be generated by the delay stages **78** during the oscillation mode. The final differential output **82D** is the clock output **50** in FIG. 4A. The explanation of the functionality of the resettable VCO **74** of FIG. 4A begins at time t_1 in FIG. 4B immediately after a clock pulse **85** when the final differential output **82D** has a low signal level. When the final differential output **82D** has the low signal level, a top polarity of the final differential output **82D** has a low signal level and a bottom polarity of the final differential output **82D** has a high signal level (see FIG. 4A). Accordingly, the initial differential input **80A** is received by the initial delay stage **78A** such that a top polarity of the initial differential input **80A** has a low signal level and a bottom polarity of the initial differential input **80A** has a high signal level. As explained above, the initial delay stage **78A** is configured to generate the initial differential output **82A** with an inverse polarity of the initial differential input **80A**. However, the initial delay stage **78A** has an initial delay stage propagation delay **86A** so that the initial differential output **82A** does not settle as having the inverse polarity of the initial differential input **80A** until time t_2 .

[0051] With continuing reference to FIG. 4B, at time t_2 , the initial differential output **82A** has a high signal level. Thus, a top polarity of the initial differential output **82A** has high signal level and a bottom polarity of the initial differential output **82A** has a low voltage level. The first intermediary delay stage **78B** is cross-coupled with the initial delay stage **78A**. As a result, a top polarity of the first intermediary differential input **80B** has the low signal level and a bottom polarity of the first intermediary differential input **80B** has the high signal level at time t_2 . The first intermediary delay stage **78B** is also configured to generate the first intermediary differential output **82B** as having an inverse polarity of the first intermediary differential input **80B**. However, the first intermediary delay stage **78B** has a first intermediary delay stage propagation delay **86B** such that the first intermediary differential output **82B** does not settle as having the inverse of the first intermediary differential input **80B** until time t_3 .

[0052] With continuing reference to FIG. 4B, at time t_3 , the first intermediary differential output **82B** has the high signal level and thus, a top polarity of the first intermediary differential output **82B** has the high signal level while a bottom polarity of the first intermediary differential output **82B** has the low signal level. The second intermediary delay stage **78C** is cross-coupled to the first intermediary delay stage **78B**. Thus, the top polarity of the second intermediary differential input **80C** has the low signal level and a bottom polarity of the second intermediary differential input **80C** has the high signal level at time t_3 . The second intermediary delay stage **78C** is also configured to generate the second intermediary differential output **82C** with an inverse polarity of the second intermediary differential input **80C**. However, the second intermediary delay stage **78C** has a second intermediary delay stage propagation delay **86C** so that the second intermediary differential output **82C** does not settle as the inverse polarity of the second intermediary differential input **80C** until time t_4 .

[0053] With continuing reference to FIG. 4B, at time t_4 , the second intermediary differential output **82C** has the high signal level and thus, a top polarity of the second intermediary differential output **82C** has the high signal level and a bottom polarity of the second intermediary differential output **82C** has the low signal level. The final delay stage **78D** is cross-coupled with the second intermediary delay stage **78C**. As a result, a top polarity of the final differential input **80D** has the low signal level and a bottom polarity of the final differential input **80D** has the high signal level at time t_4 . The final delay stage **78D** is configured to generate the final differential output **82D** with an inverse polarity of the final differential input **80D**. However, the final delay stage **78D** has a final delay stage propagation delay **86D** so that the final differential output **82D** does not settle as having the inverse polarity as having the inverse polarity of the final differential input **80D** until time t_5 .

[0054] With continuing reference to FIG. 4B, the final differential output **82D** and thus, the clock output **50** has the high signal level at time t_5 . As such, a top polarity of the final differential output **82D** has the high signal level and a bottom polarity of the final differential output **82D** has the low signal level at time t_5 . The clock output **50** has thus been inverted to the high signal level after half of a clock period. Half of the clock period is about equal to the aggregation of the initial delay stage propagation delay **86A**, the first intermediary delay stage propagation delay **86B**, the second intermediary delay stage propagation delay **86C**, and the final delay stage propagation delay **86D**.

[0055] With continuing reference to FIG. 4B, the final differential output **82D** is fed back to the initial delay stage **78A**. Thus, at time t_5 , the top polarity of the initial differential input **80A** has the high signal level and the bottom polarity of the initial differential output **82A** has the low signal level. As a result, after the initial delay stage propagation delay **86A**, the initial differential output **82A** inverts to the low signal level at time t_6 . Thus, at time t_6 , the top polarity of the initial differential output **82A** has the low signal level and the bottom polarity of the final differential output **82D** has the high signal level.

[0056] Due to cross coupling of the initial delay stage **78A** and the first intermediary delay stage **78B**, the top polarity of the first intermediary differential input **80B** has the high signal level and the bottom polarity of the first intermediary differential input **80B** has the low signal level at time t_6 . After the first intermediary delay stage propagation delay **86B**, the

first intermediary differential output **82B** inverts to the low signal level at time t_7 . As a result, the top polarity of the first intermediary differential output **82B** has the low signal level and the bottom polarity of the first intermediary differential output **82B** has the high signal level at time t_7 .

[0057] Due to cross coupling of the first intermediary delay stage **78B** and the second intermediary delay stage **78C**, the top polarity of the second intermediary differential input **80C** has the high signal level and the bottom polarity of the second intermediary differential input **80C** has the low signal level at time t_7 . After the second intermediary delay stage propagation delay **86C**, the second intermediary differential output **82C** inverts to the low signal level at time t_8 . As a result, the top polarity of the second intermediary differential output **82C** has the low signal level and the bottom polarity of the second intermediary differential output **82C** has the high signal level at time t_8 .

[0058] Due to the cross coupling of the second intermediary delay stage **78C** and the final delay stage **78D**, the top polarity of the final differential input **80D** has the high signal level and the bottom polarity of the final differential input **80D** has the low signal level at time t_8 . After the final delay stage propagation delay **86D**, the final differential output **82D** inverts to the low signal level at time t_9 . As a result, the top polarity of the final differential output **82D** has the low signal level and a bottom polarity of the final differential output **82D** has the high signal level at time t_9 . Thus, the clock output **50** is inverted back to low at time t_9 as it was at time t_1 . The clock output **50** has thus been again inverted to low after another half of a clock period. This other half clock period is again about equal to the aggregation of the initial delay stage propagation delay **86A**, the first intermediary delay stage propagation delay **86B**, the second intermediary delay stage propagation delay **86C**, and the final delay stage propagation delay **86D**. The clock period is thus about twice the aggregation of the initial delay stage propagation delay **86A**, the first intermediary delay stage propagation delay **86B**, the second intermediary delay stage propagation delay **86C**, and the final delay stage propagation delay **86D**. The above described process repeats so long as the resettable VCO **74** is in the oscillation mode.

[0059] In the embodiment of the resettable VCO **74**, the initial delay stage propagation delay **86A**, the first intermediary delay stage propagation delay **86B**, the second intermediary delay stage propagation delay **86C**, and the final delay stage propagation delay **86D**, are about the same and thus, are each equal to approximately one-eighth of a clock period. Alternative embodiments of the resettable VCO **74** may be configured so that the delay stage propagation delays **86A-86D** have a designed difference. In any case, the combination of the delay stage propagation delays **86A-86D** determine the temporal length of half of the clock period and thus, set the clock frequency of the differential outputs **82** and, as a result, the clock output **50**. The delay stages **78** may be programmable so as to vary their delay stage propagation delay **86** thereby allowing for the clock frequency of the differential outputs **82** (and thus also, the clock output **50**) to be varied.

[0060] Referring now to FIG. 4C and with continuing reference to FIG. 4A, FIG. 4C is an exemplary signal diagram illustrating an exemplary reset pulse **58** and various embodiments of the clock output (referred to individually in FIG. 4C as elements **50A-50F**). As a result of the reset pulse **58**, the resettable VCO **74** receives the phase control input **76** (shown in FIG. 3) as a gated phase control code. The gated phase

control code is indicative of a phase setting for the clock phase of the clock output **50**. The gated phase control code is received by the resettable VCO **74** shown in FIG. 4A as the first code **84A**, the second code **84B**, the third code **84C**, and the fourth code **84D**. When each of the delay stages **78** receives the codes **84**, the resettable VCO **74** operates in the reset mode. Rather than providing the differential outputs **82** in accordance with the differential inputs **80** as in the oscillation mode, each delay stage **78** is configured to receive the corresponding code **84** of the phase control input **76** (shown in FIG. 3) during the reset mode and provide the corresponding differential output **82** based on the corresponding code **84**.

[0061] Again as discussed above, the final differential output **82D** (shown in FIG. 4B) is the clock output **50** (shown in FIG. 4A) in this embodiment for the resettable VCO **74**. Thus, FIG. 4C illustrates various embodiments of the clock output **50** (and thus the final differential output **82D** in FIG. 4B) as clock outputs **50A-50F**. The clock output **50A** is shown without any adjustment due to the reset mode and is simply provided as a reference for the other clock outputs **50B-50F**. Each of the clock outputs **50B-50F** have been adjusted in accordance with different exemplary phase settings indicated by the gated phase control code. In this embodiment, the phase setting indicated by the gated phase control code is a phase delay (referred to generically as element **88** and individually as elements **88A-88E** in FIG. 4C). The resettable VCO **74** is configured to adjust the clock phase of the clock output **50** depending on the phase delay **88** indicated by the gated phase control code. The clock phase of the clock output **50** is adjusted by providing the phase delay **88** in response to release of the reset pulse **58**.

[0062] Referring again to FIGS. 4A and 4C, the reset pulse **58** begins at a time t_a when the clock outputs **50A-50F** are at the low signal level. Thus, at time t_a the top polarity of the clock output **50** (and thus the final differential output **82D** shown in FIG. 4B) has the low signal level and the bottom polarity of the clock output **50** has the high signal level. In essence, the gated phase control code selects a point in the oscillation of the differential outputs **82A-82D** (shown in FIG. 4B) so that the phase delay **88** is provided in response to release of the reset mode when the resettable VCO **74** is put back in the oscillation mode. The reset pulse **58** ends at time t_b . In response to release of the reset pulse **58**, the phase delay **88** is provided based on the point of the oscillation selected by the particular embodiment of the gated phase control code during the reset mode.

[0063] To further explain the operation of the resettable VCO **74**, the table below illustrates embodiments of the gated phase control code, the corresponding phase delay **88** indicated by that particular gated phase control code, and the phase adjustment provided by the corresponding phase delay **88** to the clock phase of the corresponding clock output **50** in FIG. 4C.

-continued

Gated Phase Control Code	Corresponding Phase Delay	Phase Adjustment
01111000	Phase Delay 88D = $\frac{3}{8}$ of a clock period	$\frac{1}{4}$ of a clock period for clock output 50E
11110000	Phase Delay 88E = $\frac{1}{2}$ of a clock period	$\frac{3}{8}$ of a clock period for clock output 50F

[0064] The logical bit “1” in the gated phase control codes of the table above represent a high signal level, while the logical bit “0” of the gated phase control codes represents a low signal level. The clock output **50A** shown in FIG. 4C is provided without any adjustments to the clock phase and is intended simply to provide a reference to help guide the explanation of the operation of the resettable VCO **74**. Since the reset pulse **58** is indicative of edge detection in the data stream **36** (shown in FIG. 3), the reset pulse **58** serves as a reference point with regard to the data phase of the data stream **36**. The reset mode allows for the clock phase of the clock output **50** to be adjusted in accordance with the gated phase control code, as shown by clock outputs **50B-50F** in FIG. 4C.

[0065] Referring again to FIGS. 4A and 4C, the initial delay stage **78A** is configured to receive the first code **84A** as the first bit and the fifth bit of the gated phase control code. More specifically, a top polarity of the first code **84A** is the first bit of the gated phase control code and a bottom polarity of the first code **84A** is the fifth bit of the gated phase control code. In the reset mode, the initial delay stage **78A** is configured to generate the initial differential output **82A** as a reverse polarity of the first code **84A** during the reset mode. For example, the top polarity of the first code **84A** may be provided having the high signal level (i.e., the first bit of the first code is “1”) and the bottom polarity of the first code **84A** may be provided having the low signal level (i.e., the fifth bit of the phase control code is “0”). In this case, the top polarity of the initial differential output **80B** is generated so that the top polarity of the initial differential output **80B** has the low signal level and the bottom polarity has the high signal level during the reset mode. However, the top polarity of the first code **84A** may be provided having the low signal level (i.e., the first bit of the gated phase control code is “0”) and the bottom polarity of the first code **84A** may be provided having the high signal level (i.e., the fifth bit of the gated phase control code is “1”). In this case, the initial delay stage **78A** generates initial differential output **82A** so that the top polarity of the initial differential output **82A** has the high signal level and the bottom polarity of the initial differential output **82A** has the low signal level.

[0066] The first intermediary delay stage **78B** receives the second code **84B** as the second bit and the sixth bit of the gated phase control code. More specifically, a top polarity of the second code **84B** is the second bit of the gated phase control code while a bottom polarity of the second code **84B** is the sixth bit of the gated phase control code. The first intermediary delay stage **78B** is configured to generate the first intermediary differential output **82B** as the reverse polarity of the second code **84B** during the reset mode. For example, the top polarity of the second code **84B** may be provided having the high signal level (i.e., the second bit of the gated phase control code is “1”) and the bottom polarity of the second code **84B** may be provided having the low signal level (i.e., the sixth bit of the gated phase control code is “0”).

Gated Phase Control Code	Corresponding Phase Delay	Phase Adjustment
00001111	Phase Delay 88A = 0 of a clock period	$-\frac{1}{8}$ of a clock period for clock output 50B
00011110	Phase Delay 88B = $\frac{1}{8}$ of a clock period for clock output 50C	0 of a clock period for clock output 50C
00111100	Phase Delay 88C = $\frac{1}{4}$ of a clock period	$\frac{1}{8}$ of a clock period for clock output 50D

In this case, the first intermediary delay stage **78B** generates the first intermediary differential output **82B** so that the top polarity of the first intermediary differential output **82B** has low signal level and the bottom polarity has the high signal level. However, the top polarity of the second code **84B** may be provided having the low signal level (i.e., the second bit of the gated phase control code is “0”) and the bottom polarity of the second code **84B** may be provided having the high signal level (i.e., the sixth bit of the gated phase control code is “1”). In this case, the second intermediary differential output **82C** is provided so that the top polarity of the second intermediary differential output **82C** has the high signal level and the bottom polarity has the low signal level.

[0067] Next, the second intermediary delay stage **78C** is configured to receive the third code **84C** as the third bit of the gated phase control code and the seventh bit of the gated phase control code. More specifically, a top polarity of the third code **84C** is the third bit of the gated phase control code and a bottom polarity of the third code **84C** is the seventh bit of the gated phase control code. The second intermediary delay stage **78C** is configured to generate the second intermediary differential output **82C** as a reverse polarity of the third code **84C** during the reset mode. For example, the top polarity of the third code **84C** may be provided having the high signal level (i.e., the third bit of the gated phase control code is “1”) and the bottom polarity of the third code **84C** may be provided having the low signal level (i.e., the seventh bit of the gated phase control code is “0”). In this case, the second intermediary delay stage **78C** generates the second intermediary differential output **82C** so that the top polarity of the second intermediary differential output **82C** has the low signal level and the bottom polarity has the high signal level. However, the top polarity of the third code **84C** may be provided having the low signal level (i.e., the third bit of the gated phase control code is “0”) and the bottom polarity of the third code **84C** may be provided having the high signal level (i.e., the seventh bit of the gated phase control code is “1”). In this case, the second intermediary delay stage **78C** generates the second intermediary differential output **82C** so that the top polarity of the second intermediary differential output **82C** has the high signal level and the bottom polarity of the second intermediary differential output **82C** has the low signal level.

[0068] Finally, the final delay stage **78D** is configured to receive the fourth code **84D** as the fourth bit and the eighth bit of the gated phase control code. More specifically, a top polarity of the fourth code **84D** is the fourth bit of the gated phase control code and a bottom polarity of the fourth code **84D** is the eighth bit of the gated phase control code. The final delay stage **78D** is configured to generate the final differential output **82D** and thus, the clock output **50**, as a reverse polarity of the fourth code **84D** during the reset mode. For example, the top polarity of the fourth code **84D** may be provided having the high signal level (i.e., the fourth bit of the gated phase control code is “1”) and the bottom polarity of the fourth code **84D** may be provided having the low signal level (i.e., the eighth bit of the gated phase control code is “0”). In this case, the final delay stage **78D** generates the final differential output **82D** so that the top polarity of the final differential output **82D** has the low signal level and the bottom polarity of the final differential output **82D** has the high signal level. However, the top polarity of the fourth code **84D** may be provided having the low signal level (i.e., the fourth bit of the gated phase control code is “0”) and the bottom polarity of the fourth code **84D** may be provided having the high signal level

(i.e., the eighth bit of the gated phase control code is “1”). In this case, the final delay stage **78D** generates the final differential output **82D** so that the top polarity of the final differential output **82D** has the high signal level and the bottom polarity has the low signal level.

[0069] Without no adjustments to the clock phase by the gated phase control code, the clock output **50A** shown in FIG. 4C demonstrates that a clock edge **90A** of the clock output **50A** occurs at time t_c . However, when the gated phase control code “00001111” is received during the reset pulse **58**, the delay stages **78** generate the differential outputs **82** in the same manner as shown at time t_s in FIG. 4B. Accordingly, upon release of the reset mode, an initial clock edge **90B** of the clock output **50B** follows the release of the reset mode after the phase delay **88A**. The clock phase has thus been adjusted by time t_b minus time t_c . This means that, in this embodiment, the clock phase of the clock output **50B** has been shifted up approximately one-eighth of the clock period. The gated phase control code “00001111” represents a phase delay **88A** equaling zero. However, due to the relationship between the reset pulse **58** and the clock phase of the clock output **50B** prior to the occurrence of the reset pulse **58**, the phase adjustment to the clock phase of the clock output **50B** is a shift upwards of one-eighth of the clock period. In other embodiments, the phase delay **88A** of zero (and the other phase delays **88B-88E**) may provide different phase adjustment depending on the temporal relationship between the clock phase and the reset pulse **58**.

[0070] Next, when the gated phase control code is “00011110,” the delay stages **78** provide the differential outputs **82** in the same manner as shown at time t_4 in FIG. 4B. In response to release of the reset pulse **58**, an initial clock edge **90C** of the clock output **50C** follows the release of the reset mode after the phase delay **88B**. The phase delay **88B** in this case is approximately equal to the final delay stage propagation delay **86D** and is thus about one-eighth of the clock period. The initial clock edge **90C** of the clock output **50C** is provided at time t_c and thus the phase adjustment to the clock phase is equal to t_c minus t_c , which is zero. The phase delay **88B** of one-eighth of the clock period thus provides a phase adjustment of zero in this embodiment.

[0071] With regard to the gated phase control code “00111100,” the delay stages **78** provide the differential outputs **82** in the same manner as shown at time t_3 in FIG. 4B. In response to release of the reset pulse **58**, an initial clock edge **90D** of the clock output **50D** follows the release of the reset mode after the phase delay **88C**. The phase delay **88C** is approximately equal to the aggregation of the final delay stage propagation delay **86D** and the second intermediary delay stage propagation delay **86C**. This means that the phase delay **88C** is about one-fourth of the clock period. The initial clock edge **90D** of the clock output **50D** is at time t_d . Accordingly, the phase adjustment to the clock phase is equal to $t_d - t_c$. This means the clock phase of the clock output **50D** has been shifted down about one-eighth of the clock period. Thus, the phase delay **88C** of one-fourth of the clock period shifts the clock phase of the clock output **50D** down by one-eighth of the clock period in this embodiment.

[0072] Next, when the gated control code is “01111000,” the delay stages **78** provide the differential outputs **82** in the same manner as shown at time t_2 in FIG. 4B. In response to the release of the reset pulse **58**, an initial clock edge **90E** of the clock output **50E** follows the release of the reset mode after the phase delay **88D**. The phase delay **88D** is thus approxi-

mately equal to an aggregation of the final delay stage propagation delay **86D**, the second intermediary delay stage propagation delay **86C** and the first intermediary delay stage propagation delay **86B**, which is equal to three-eighths of the clock period. The initial clock edge **90E** is at time t_e . Accordingly, the phase adjustment of the clock output **50E** is equal to t_e minus t_c and the clock phase has been shifted down about one-quarter of the clock period. Thus, the phase delay **88D** of three-eighths of the clock period shifts the clock phase of the clock output **50E** down by one-quarter of the clock period.

[0073] With regards to the gated phase control code "11110000," the delay stages **78** provide the differential outputs **82** in the same manner as shown at time t_1 in FIG. 4B. In response to the release of the reset pulse **58**, an initial clock edge **90F** of the clock output **50F** follows the release of the reset mode after the phase delay **88E**. The phase delay **88E** is equal to an aggregation of the final delay stage propagation delay **86D**, the second intermediary delay stage propagation delay **86C**, the first intermediary delay stage propagation delay **86B**, and the initial delay stage propagation delay **86A**, which is approximately equal to half the clock period. The initial clock edge **90F** of the clock output **50E** occurs at time t_f and thus the phase adjustment is equal to t_f minus t_c . The phase delay **88E** of half of the clock period has thus shifted down the clock phase of the clock output **50E** by approximately three-eighths of the clock period.

[0074] As discussed above, embodiments of the resettable VCO **74** may have any number of delay stages **78**. The example shown in FIG. 4A has four delay stages **78**, but may have any number less or greater than four. The number of delay stages **78** simply controls the number of phase delays **88** that can be provided to phase shift the clock output **50**.

[0075] FIG. 4D illustrates exemplary components that may be provided in one of the delay stages **78** shown in FIG. 4C. The delay stage **78** includes p-channel type field effect transistors (FETs) **92, 94, 96, 98, 100, 102**. Additionally, the delay stage **78** has n-channel type FETs **104, 106, 108, 110, 112** and **114**. Also provided are inverter gates **116, 118, 120**, and **122** along with a variable capacitive component **124**. In this exemplary embodiment, a DC-voltage VDD is provided to the delay stage **78**. The DC-voltage VDD provides the high voltage level. Another DC-voltage VSS is also provided to the delay stage **78**. The DC-voltage VSS may be at the ground to provide the low voltage level.

[0076] The differential input **80** and the differential output **82** are differential signals. Accordingly, when the differential output **82** has the high signal level, the voltage level of the differential output is about at VDD. Thus, the top polarity of the differential output **82** is about at VDD and the bottom polarity of the differential output **82** is about at VSS. However, if the differential output has the low signal level, the differential output has a voltage level of -VDD. Thus, the top polarity of the differential output **82** is at VSS and the bottom polarity of the differential output **82** is at VDD. The same goes for the differential input **80**.

[0077] In the oscillation mode, the code **84** is not received by the delay stage **78**. Accordingly, terminals **126A, 126B** are both low at about VSS. When terminals **126A, 126B** both have the low signal level, FETs **112, 100, 102**, and **114** are all switched off. The p-channel type FETs **94, 98** may be switched on if the p-channel type FETs **92, 96** are switched on. Similarly, the n-channel type FETs **104, 110** may be switched on when the n-channel type FETs **106, 108** are switched on. If a top polarity of the differential input **80** has

the low signal level and a bottom polarity of the differential input **80** has the high signal level, the p-channel type FET **92** and the n-channel type FET **108** are switched on while the p-channel type FET **96** and the n-channel type FET **106** are switched off. In this case, the high voltage level VDD appears at node **128A** and the low voltage level VSS appears at node **128B**. However, the inverter gates **120, 122**, and the variable capacitive component **124** form a memory cell and thus, the top polarity of the differential output **82** and the bottom polarity of the differential output **82** do not immediately appear at the high and low levels respectively. Instead, the variable capacitive component **124** must be charged accordingly and the delay stage propagation delay **86** of the delay stage **78** is provided by the variable capacitive component **124** (along with the switching transients of the other components). Thus, by varying the variable capacitance of the variable capacitive component **124**, the clock frequency of the clock output **50** (shown in FIG. 3) may be controlled and varied. Once the variable capacitive component **124** is charged accordingly, the top polarity of the differential output **82** is at VDD while the bottom polarity of the differential output **82** is at VSS. As a result, the differential output **82** has the high signal level at the voltage level VDD.

[0078] If the top polarity of the differential input **80** has the high signal level and the bottom polarity of the differential input **80** has the low signal level during the oscillation mode, the p-channel type FET **92** and the n-channel type FET **108** are off while the n-channel type FET **106** and the p-channel type FET **96** are on. In this case, the low voltage level VSS is provided at node **128A** while the high voltage level VDD is provided at node **128B**. Again, the top polarity of the differential output **82** is not immediately low and the bottom polarity of the differential output **82** is not immediately high. Rather, the variable capacitive component **124** must be charged accordingly to provide the appropriate values for the differential output **82**. Once the variable capacitive component **124** is charged accordingly, the top polarity of the differential output **82** is at VSS while the bottom polarity of the differential output **82** is at VDD. As a result, the differential output **82** has the low signal level at the voltage level -VDD.

[0079] However, in the reset mode, if the top polarity of the code **84** has the low signal level and the bottom polarity of the code **84** has the high signal level, the n-channel type FET **112** is off while the p-channel type FET **100** is on. Similarly in the reset mode, the p-channel type FET **102** is off while the n-channel type FET **114** is on. The p-channel type FET **94** may be switched on while the n-channel type FET **104** must be switched off. The p-channel type FET **98** must be switched off and the n-channel type FET **110** may be switched on. Thus, regardless of whether the top and bottom polarities of the differential input **80** are low or high, the high voltage level VDD is provided at node **128A** and the low voltage level VSS is provided at node **128B**. Once the variable capacitive component **124** is appropriately charged, the top polarity of the differential output **82** has the high signal level at VDD and the bottom polarity of the differential output **82** has the low signal level at VSS. As a result, the differential output **82** has the high signal level at the voltage level VDD.

[0080] In contrast, if the top polarity of the code **84** has the high signal level and the bottom polarity of the code **84** has the low signal level during the reset mode, the n-channel type FET **112** and the p-channel type FET **102** are switched on while the p-channel type FET **100** and the n-channel type FET **114** are switched off. Additionally, the p-channel type FET **94**

and the n-channel type FET **110** must be switched off while the n-channel type FET **104** and the p-channel type FET **98** may be switched on. Accordingly, regardless of whether the top polarity of the differential input **80** has the low signal level or high and the bottom polarity of the differential input **80** has the low signal level or high, the low voltage level VSS is provided at the node **128A** and the high voltage level VDD is provided at the node **128B**. Once the variable capacitive component **124** is appropriately charged, the top polarity of the differential output **82** has the low signal level and the bottom polarity of the differential output **82** has the high signal level. As a result, the differential output **82** has the low signal level at the voltage level -VDD.

[0081] FIG. 5 illustrates a circuit diagram of the phase-shift setup circuit **70** that provides the phase control input **76** (shown in FIG. 3) in the reset mode. The phase-shift setup circuit **70** includes a plurality of nor-gates (referred to generically as element **130** and individually as elements **130A-130H**). Each nor-gate **130** receives the reset pulse **58** and a bit (referred to generically as element **132** and individually as elements **132A-132H**) of a preliminary phase control code. In this example, the reset pulse **58** is provided as a negative pulse that is provided low. Therefore, when no pulse is provided each of the nor-gates **130** receives a high input and there must generate a low output regardless of the bits **132** of the preliminary phase control code. However, when the reset pulse **58** is provided, the input from the reset pulse **58** has the low signal level. Each nor-gate **130** generates a bit of the gated phase control code as an output. This bit of the gated phase control code is inverted with respect to the bit **132** of the preliminary phase control code.

[0082] In this embodiment, the nor-gate **130A** provides a top polarity of the first code **84A** (i.e., the first bit of the gated phased control code) as an inversion of the first bit **132A** of the preliminary phase control code. The nor-gate **130B** provides a top polarity of the second code **84B** (i.e., the second bit of the gated phased control code) as an inversion of the second bit **132B** of the preliminary phase control code. The nor-gate **130C** provides a top polarity of the third code **84C** (i.e., the third bit of the gated phased control code) as an inversion of the third bit **132C** of the preliminary phase control code. The nor-gate **130D** provides a top polarity of the fourth code **84D** (i.e., the fourth bit of the gated phased control code) as an inversion of the fourth bit **132D** of the preliminary phase control code. The nor-gate **130E** provides a bottom polarity of the first code **84A** (i.e., the fifth bit of the gated phased control code) as an inversion of the fifth bit **132E** of the preliminary phase control code. The nor-gate **130F** provides the bottom polarity of the second code **84B** (i.e., the sixth bit of the gated phased control code) as an inversion of the sixth bit **132F** of the preliminary phase control code. The nor-gate **130G** provides the bottom polarity of the third code **84C** (i.e., the seventh bit of the gated phased control code) as an inversion of the seventh bit **132G** of the preliminary phase control code. Finally, the nor-gate **130H** provides the bottom polarity of the fourth code **84D** (i.e., the eighth bit of the gated phased control code) as an inversion of the eighth bit **132H** of the preliminary phase control code.

[0083] The CDR circuits and resettable VCOs according to embodiments disclosed herein may be provided in or integrated into any processor-based device. Examples, without limitation, include a set top box, an entertainment unit, a navigation device, a communications device, a fixed location data unit, a mobile location data unit, a mobile phone, a

cellular phone, a computer, a portable computer, a desktop computer, a personal digital assistant (PDA), a monitor, a computer monitor, a television, a tuner, a radio, a satellite radio, a music player, a digital music player, a portable music player, a digital video player, a video player, a digital video disc (DVD) player, and a portable digital video player.

[0084] In this regard, FIG. 6 illustrates an example of a processor-based system **134** that can employ the CDR circuits disclosed herein. CDR circuits **34** and **66** shown in FIGS. 2 and 3 are not specifically shown but may generally be coupled to any particular component in the processor-based system **134**, included in any of the components, in interfaces, or interfaced between any components of the processor-based system **134**.

[0085] With continuing reference to FIG. 6, in this example, the processor-based system **134** includes one or more central processing units (CPUs) **136**, each including one or more processors **138**. The CPU(s) **136** may have cache memory **140** coupled to the processor(s) **138** for rapid access to temporarily stored data. The CPU(s) **136** is coupled to a system bus **142**. The system bus **142** provides a path and may coordinate internal communications between the devices of the processor-based system **134**. As is well known, the CPU(s) **136** communicates with these other devices by exchanging address, control, and data information over the system bus **142**. For example, the CPU(s) **136** can communicate requests to a memory system **144**. Although not illustrated in FIG. 6, multiple system buses **142** could be provided, wherein each system bus **142** constitutes a different fabric.

[0086] Other devices may be provided by the processor-based system **134** and connected to the system bus **142**. As illustrated in FIG. 6, these devices can include other memory systems **144**, one or more input devices **146**, one or more output devices **148**, one or more network interface devices **150**, and one or more display controllers **152**, as examples. The input device(s) **146** can include any type of input device, including but not limited to input keys, switches, voice processors, etc. The output device(s) **148** can include any type of output device, including but not limited to audio, video, other visual indicators, etc. The network interface device(s) **150** can be any devices configured to allow exchange of data to and from a network **154**. The network **154** can be any type of network, including but not limited to a wired or wireless network, private or public network, a local area network (LAN), a wide local area network (WLAN), and the Internet. The network interface device(s) **150** can be configured to support any type of communication protocol desired. The memory system **144** can include one or more memory units.

[0087] The CPU **136** may also be configured to access the display controller(s) **152** over the system bus **142** to control information sent to one or more displays **156**. The display controller(s) **152** sends information to the display(s) **156** to be displayed via one or more video processors **158**, which process the information to be displayed into a format suitable for the display(s) **156**. The display(s) **156** can include any type of display, including but not limited to a cathode ray tube (CRT), a liquid crystal display (LCD), a plasma display, etc.

[0088] Those of skill in the art would further appreciate that the various illustrative logical blocks, modules, circuits, and algorithms described in connection with the embodiments disclosed herein may be implemented as electronic hardware, instructions stored in memory or in another computer-readable medium and executed by a processor or other processing device, or combinations of both. The CDR circuits and reset-

table VCOs herein may be employed in any circuit, hardware component, integrated circuit (IC), or IC chip, as examples. Memory disclosed herein may be any type and size of memory and may be configured to store any type of information desired. To clearly illustrate this interchangeability, various illustrative components, blocks, modules, circuits, and steps have been described above generally in terms of their functionality. How such functionality is implemented depends upon the particular application, design choices, and/or design constraints imposed on the overall system. Skilled artisans may implement the described functionality in varying ways for each particular application, but such implementation decisions should not be interpreted as causing a departure from the scope of the present invention.

[0089] The various illustrative logical blocks, modules, and circuits described in connection with the embodiments disclosed herein may also be implemented or performed with a processor, a DSP, an Application Specific Integrated Circuit (ASIC), an FPGA or other programmable logic device, discrete gate or transistor logic, discrete hardware components, or any combination thereof designed to perform the functions described herein. A processor may be a microprocessor, but in the alternative, the processor may be any conventional processor, controller, microcontroller, or state machine. A processor may also be implemented as a combination of computing devices, e.g., a combination of a DSP and a microprocessor, a plurality of microprocessors, one or more microprocessors in conjunction with a DSP core, or any other such configuration.

[0090] The embodiments disclosed herein may be embodied in hardware and in instructions that are stored in hardware, and may reside, for example, in Random Access Memory (RAM), flash memory, Read Only Memory (ROM), Electrically Programmable ROM (EPROM), Electrically Erasable Programmable ROM (EEPROM), registers, hard disk, a removable disk, a CD-ROM, or any other form of computer readable medium known in the art. An exemplary storage medium is coupled to the processor such that the processor can read information from, and write information to, the storage medium. In the alternative, the storage medium may be integral to the processor. The processor and the storage medium may reside in an ASIC. The ASIC may reside in a remote station. In the alternative, the processor and the storage medium may reside as discrete components in a remote station, base station, or server.

[0091] It is also noted that the operational steps described in any of the exemplary embodiments herein are described to provide examples and discussion. The operations described may be performed in numerous different sequences other than the illustrated sequences. Furthermore, operations described in a single operational step may actually be performed in a number of different steps. Additionally, one or more operational steps discussed in the exemplary embodiments may be combined. It is to be understood that the operational steps illustrated in the flow chart diagrams may be subject to numerous different modifications as will be readily apparent to one of skill in the art. Those of skill in the art would also understand that information and signals may be represented using any of a variety of different technologies and techniques. For example, data, instructions, commands, information, signals, bits, symbols, and chips that may be referenced throughout the above description may be represented by voltages, currents, electromagnetic waves, magnetic fields or particles, optical fields or particles, or any combination thereof.

[0092] The previous description of the disclosure is provided to enable any person skilled in the art to make or use the disclosure. Various modifications to the disclosure will be readily apparent to those skilled in the art, and the generic principles defined herein may be applied to other variations without departing from the spirit or scope of the disclosure. Thus, the disclosure is not intended to be limited to the examples and designs described herein, but is to be accorded the widest scope consistent with the principles and novel features disclosed herein.

What is claimed is:

1. A resettable voltage controlled oscillator (VCO) for a clock and data recovery circuit, the resettable VCO configured to:

generate a clock output having a clock phase;
receive a phase control input indicative of a phase setting for the clock phase; and
adjust the clock phase of the clock output based on the phase control input as a result of edge detection in a data stream.

2. The resettable VCO of claim 1, wherein the phase control input comprises a phase control code indicative of the phase setting for the clock phase.

3. The resettable VCO of claim 1, wherein the phase control input comprises a gated phase control code indicative of the phase setting for the clock phase and gated by a reset pulse indicative of edge detection in the data stream.

4. The resettable VCO of claim 3, wherein the phase setting indicated by the gated phase control code represents a phase delay.

5. The resettable VCO of claim 4, wherein the resettable VCO is further configured to adjust the clock phase of the clock output by providing the phase delay in response to release of the reset pulse.

6. The resettable VCO of claim 1, further configured to generate the control output having a clock frequency based on a bit rate of the data stream.

7. The resettable VCO of claim 1, further comprising a plurality of delay stages configured to generate the clock output.

8. The resettable VCO of claim 7, wherein the plurality of delay stages are programmable in an oscillation mode and a reset mode.

9. The resettable VCO of claim 8, wherein the plurality of delay stages comprise:

an initial delay stage configured to receive the clock output as the initial differential input and generate an initial differential output; and

a final delay stage configured to receive a final differential input based on the initial differential output and generate the clock output.

10. The resettable VCO of claim 9, further comprising at least one intermediary delay stage disposed between the initial delay stage and the final delay stage, the at least one intermediary delay stage configured to receive at least one intermediary differential input and generate at least one intermediary differential output.

11. The resettable VCO of claim 9, wherein in an oscillation mode:

the initial delay stage is configured to generate the initial differential output having an inverse polarity of the initial differential input; and

the final delay stage is configured to receive the final differential input and generate the clock output having an inverse polarity of the final differential input.

12. The resettable VCO of claim **9** configured to operate in the oscillation mode when not receiving the phase control input.

13. The resettable VCO of claim **9**, wherein in a reset mode: the initial delay stage is configured to generate the initial differential output as a reverse polarity of a first code of the phase control input; and the final delay stage is configured to generate the clock output as a reverse polarity of a second code of the phase control input.

14. The resettable VCO of claim **7**, wherein during a reset mode, each of the plurality of delay stages is configured to: receive a corresponding code of the phase control input gated by a reset pulse; provide a corresponding differential output based on the corresponding code; and wherein the clock output is comprised of one of the differential outputs such that, upon release of the reset mode, an initial edge of the clock output follows the release of the reset mode after the phase delay.

15. The resettable VCO of claim **1** integrated into a semiconductor die.

16. The resettable VCO of claim **1** included in a device selected from a group consisting of a set top box, an entertainment unit, a navigation device, a communications device, a fixed location data unit, a mobile location data unit, a mobile phone, a cellular phone, a computer, a portable computer, a desktop computer, a personal digital assistant (PDA), a monitor, a computer monitor, a television, a tuner, a radio, a satellite radio, a music player, a digital music player, a portable music player, a digital video player, a video player, a digital video disc (DVD) player, and a portable digital video player.

17. A resettable voltage controlled oscillator (VCO) for a clock and data recovery circuit, the resettable VCO comprising:

means for generating a clock output having a clock phase; means for receiving a phase control input indicative of a phase setting for the clock phase; and means for adjusting the clock phase of the clock output based on the phase control input as a result of edge detection in the data stream.

18. A method for generating a clock output from a data stream in a clock and data recovery circuit, comprising:

generating a clock output having a clock phase; receiving a phase control input indicative of a phase setting for the clock phase; and adjusting the clock phase of the clock output based on the phase control input as a result of edge detection in a data stream.

19. The method of claim **18**, wherein receiving the phase control input comprises receiving a phase control code indicative of the phase setting for the clock phase.

20. The method of claim **18**, further comprising gating a preliminary phase control input with a reset pulse indicative of the edge detection in the data stream to generate the phase control input.

21. The method of claim **18**, further comprising providing the clock output so that a sampler samples the data stream based on the clock output.

22. A computer-readable medium having stored thereon computer executable instructions to cause a processor-based resettable voltage controlled oscillator to: generate a clock output having a clock phase; receive a phase control input indicative of a phase setting for the clock phase; and adjust the clock phase of the clock output based on the phase control input as a result of edge detection in a data stream.

23. A clock and data recovery circuit, comprising: a sampler configured to receive a data stream in a data path and sample the data stream based on a clock output; an edge detector configured to receive the data stream and generate a reset pulse upon detection of an edge in the data stream; a resettable voltage controlled oscillator (VCO) configured to: generate the clock output having a clock phase; receive a phase control input indicative of a phase setting for the clock phase; and adjust the clock phase of the clock output based on the phase control input as a result of the reset pulse.

24. The clock and data recovery circuit of claim **23** not including a tunable delay circuit in the data path to adjust a phase of the data stream.

25. The clock and data recovery circuit of claim **23**, further comprising a clock buffer configured to receive the clock output and provide a buffered clock output to the sampler.

26. The clock and data recovery circuit of claim **23**, wherein the clock path further comprises a phase-shift set up circuit configured to generate the phase control input in response to the reset pulse.

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