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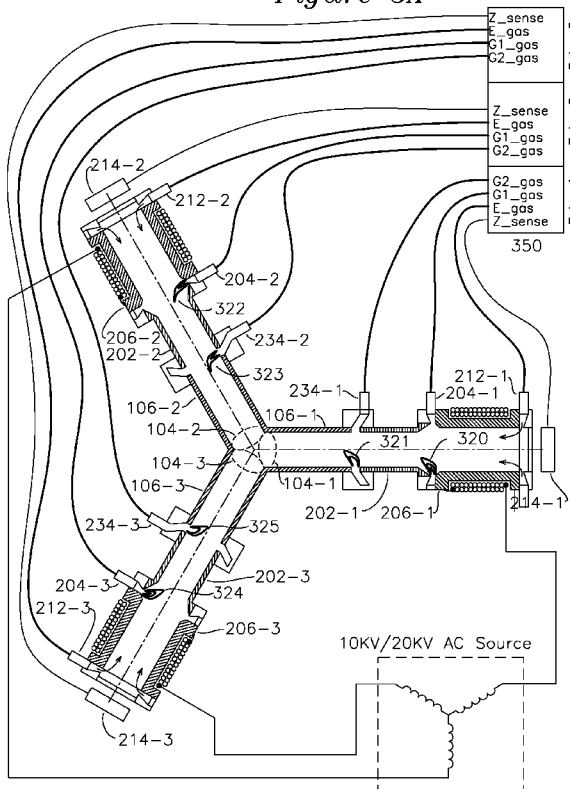
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(54) Title: SELF-IGNITING LONG ARC PLASMA TORCH

Figure 3A



(57) Abstract: A plasma torch is formed from a hollow electrode forming a first gap to an isolated plasma tube, the isolated plasma tube forming a second gap with a plasma outlet tube having electrically common plasma tubes which terminate into a plasma outlet. The first gap and second gap of the isolated plasma tubes are fed by a source of plasma gas such that when a voltage is applied across the electrodes, plasmas initially form across the first plasma gap and second plasma gap. The formed plasmas spread laterally until the plasmas are formed entirely from electrode to electrode and self-sustaining. Plasma gasses which are fed to the plasma torch can be metered on both sides of the electrodes to steer the plasma arc attachment axially over the extent of the hollow electrodes, thereby reducing surface wear and increasing electrode life.

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Self-Igniting Long Arc Plasma Torch

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Field of the Invention

10 The present invention relates to a plasma torch. In
11 particular, the present invention is a multi-phase plasma
12 torch for the generation of a plasma arc in excess of 0.3
13 meter (m) length which includes structures for the
14 automatic initiation of the plasma arc.

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Background of the Invention

17 Long arc plasma torches are commonly used in plasma
18 chemistry and metallurgy, in plasma coating processes,
19 plasma cutting and welding, and other industrial processes.
20 Plasma torches are also used for vitrification of ceramics
21 and hazardous wastes, in pyrolysis chambers, and in the
22 processing of waste and generation of synthetic fuels.
23 Plasma torches which can generate and deliver a high

1 temperature stream of ionized gas need to meet several
2 difficult requirements. One requirement is longevity of
3 the electrodes, which have a surface region in direct
4 contact with the plasma in a transient point known as the
5 arc attachment. One problem of high energy plasma torches
6 is that the high temperature arc attachment points at the
7 electrode surface are proximal to very high temperatures of
8 the reactive ionized gas, which can corrode the surface of
9 the electrode at the arc attachment point. This surface
10 corrosion subsequently leads to roughness of the electrode
11 surface, which then causes enhanced electric fields in the
12 corroded areas, which then encourages preferential plasma
13 formation in the corroded areas. Another problem inherent
14 in high energy long arc plasma torches is plasma arc
15 initiation. In one prior art device, an external source
16 introduces a plasma into the desired plasma arc extent,
17 after which the ionized gas of the introduced plasma forms
18 a plasma arc across the working electrodes of the plasma
19 torch. In another prior art device, a separate transformer
20 generates one or more areas of localized ionized gas along
21 the path of desired plasma formation between the working
22 electrode, which local plasmas combine upon application of
23 sufficient voltage to the working electrodes. In either

1 device, a separate plasma initiation structure is used at
2 start-up time.

3 It is desired to provide a long arc plasma torch which
4 self initializes and which provides improved electrode life
5 by ensuring uniform wear of the electrode surface.

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9 Objects of the Invention

10 A first object of the invention is a plasma torch
11 having a plurality of plasma tubes, each plasma tube having
12 a plasma outlet tube including a plasma exit aperture, the
13 plasma outlet tube including a shared plasma outlet which
14 is electrically common to the other outlet plasma tubes,
15 each plasma tube also having an electrically isolated
16 central plasma tube and an electrode termination, the
17 electrically isolated central plasma tube forming a first
18 gap and plasma initiation region with the adjacent
19 electrode termination and also a second gap plasma
20 initiation region with the commonly connected plasma outlet
21 tube, such that the application of a voltage across the
22 electrodes with an ionizing gas directed to the plasma exit

1 aperture causes a plasma to form in the first gap and also
2 in the second gap and thereafter fully extend to span the
3 electrodes of the plasma tubes, each electrode optionally
4 having a series of apertures for the introduction of a gas
5 having a circumferential velocity within the electrode for
6 circumferentially rotating the plasma attachment point to
7 the electrode, the electrode also having gas emitting
8 apertures on at least one end of the electrode to provide
9 for steering the arc attachment point axially over the
10 extent of the electrode, the electrode surrounded by a
11 coaxial coil for the generation of an axial magnetic field.

12 A second object of the invention is an arc attachment
13 control system having a hollow cylindrical electrode
14 carrying a plasma current and having a plasma arc
15 attachment on an inner surface of the electrode, the
16 electrode having a gas inlet port adjacent to a sealed
17 window axially located on one end of the electrode and a
18 plasma tube on the opposite side of the electrode, the
19 sealed window coupling optical energy from the plasma arc
20 attachment to an optical detector generating an electrical
21 response which is inversely proportional to the distance
22 from the arc attachment to the detector, the control system
23 estimating the axial distance of the arc attachment to the

1 electrode from the electrical response and thereafter
2 regulating the flow of gas into the gas inlet port to
3 provide for the arc spot uniformly traverse the axial
4 extent of the electrode.

5 A third object of the invention is an arc attachment
6 control system having a hollow cylindrical electrode
7 carrying a plasma current and having a plasma arc
8 attachment on an inner surface of the electrode, the
9 electrode having apertures along the axial extent of the
10 electrode and a series of optical detectors for determining
11 the axial position of the arc attachment to the electrode,
12 the electrode also having gas inlet ports adjacent to each
13 ends of the electrode for the introduction of gas, the flow
14 of gas at each electrode end regulated to place the arc
15 attachment in a preferred location based on the arc
16 attachment determined by the optical detectors, the flow of
17 gas at each electrode regulated to ensure uniform electrode
18 wear based on the estimated position of the arc attachment
19 provided by the optical detectors.

20 A third object of the invention is a self-igniting
21 plasma generator, the plasma generator having a plurality
22 of plasma tubes, each plasma tube having an electrically
23 common end leading to a plasma exit aperture adjacent to

1 the plasma exit aperture of other plasma tubes, each plasma
2 tube also having a conductive but electrically isolated
3 center section and an electrode end having a hollow
4 cylindrical electrode, the center section forming a first
5 gap with the hollow cylindrical electrode on one end and a
6 second gap with the common electrode on the opposite end,
7 the electrode having a provision for introducing a gas
8 adjacent to the electrode, where voltage applied to the
9 electrodes of the plasma tubes causes the gas to ionize in
10 each of the first and second gaps, the gas flow towards the
11 exit apertures causing the plasma to expand in extent until
12 the plasma is continuous between the electrodes.

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14 Summary of the Invention

15 The invention is a self-igniting plasma torch having a
16 plurality of plasma tubes, each plasma tube having an
17 electrode part having a hollow cylindrical electrode with
18 an electrode gas port and closed window on a first end of
19 the electrode and a first gap gas port on an opposite
20 second end of the electrode, the first gap gas port formed
21 by the gap between the second end of the hollow cylindrical
22 electrode and an electrically conductive but isolated
23 center plasma tube a first gap axial distance from the

1 second end of the hollow cylindrical electrode and thereby
2 forming the first gap, the center plasma tube having an
3 opposite end which forms a second gap with an outlet plasma
4 tube coupled to an exit aperture and electrically common
5 with other outlet plasma tubes, each of which are coupled
6 to a respective isolated center plasma tube having a
7 respective first gap and second gap and terminating in a
8 respective hollow cylindrical electrode. Each isolated
9 center plasma tube which forms the first gap and second gap
10 of each plasma tube is electrically isolated from other
11 center plasma tubes and other hollow electrodes. In a
12 plasma initiation mode, gas is introduced to each of the
13 electrode gas ports, first gap ports and second gap ports,
14 and a voltage is applied to each of the hollow cylindrical
15 electrodes of each plasma tube. The applied voltage causes
16 the gas at the first and second gaps to ionize, and the
17 direction of gas flow causes the ionized plasma to flow to
18 the exit aperture, where the plasma expands in extent
19 across each first gap and second gap until the plasma is
20 continuous and directly flowing from electrode to electrode
21 through the plasma tubes. Gas which is introduced into the
22 hollow cylindrical electrodes has an azimuthal velocity
23 component, which causes the plasma arc attachment to rotate

1 circumferentially within the hollow electrode.
2 Additionally, a coil is in series with each hollow
3 cylindrical electrode and surrounds the hollow cylindrical
4 electrode to generate an axial magnetic field to each
5 hollow electrode using the plasma current, and this
6 magnetic field causes the plasma arc attach at the
7 electrode surface to rotate circumferentially. An axial
8 position control system measures optical energy at each of
9 the electrode windows, or alternatively using a linear
10 array of sensors which estimates attach position based on
11 apertures in the hollow electrode, to estimate the axial
12 arc attach position over the hollow electrode extent, and
13 the gas flow to the electrode port and the first gap gas
14 port is regulated to cause the plasma arc attach to
15 uniformly move over the axial extent of the inner surface
16 of the hollow electrode to provide uniform electrode
17 surface wear. In addition to the axial position control
18 provided by the regulation of gas introduction between the
19 two ends of the hollow electrode, the gas which is
20 introduced circumferentially into the hollow electrode in
21 combination with the axial magnetic field generated by the
22 coil provides uniform wear of the arc attach point of the
23 inner surface of the hollow electrode.

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3 Brief Description of the Drawings

4 Figure 1 shows a perspective drawing of a plasma
5 torch.

6 Figure 2 shows a cross section view of a single plasma
7 tube.

8 Figures 3A, 3B, and 3C show a composite cross section
9 view of a three phase plasma torch in a first stage, second
10 stage, and final stage, respectively, of plasma initiation.

11 Figure 4 shows the cross section view of an electrode
12 with a plasma arc and arc axial position detector.

13 Figure 5 shows a plot of the response of the detector
14 of figure 4.

15 Figure 6 shows a plot of the axial arc position versus
16 flow F2.

17 Figure 7 shows a plot of arc attach angular velocity
18 versus gas flows.

19 Figure 8 shows a cross section diagram of a plasma
20 tube indicating dimensional relationships.

1 Figure 9 shows a cross section diagram of a gas inlet
2 port adjacent to an electrode.

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5 Detailed Description of the Invention

6 Figure 1 shows one example embodiment of a three phase
7 plasma torch 100. The plasma torch has a plurality of
8 plasma tubes equal in number to the number of electrical
9 phases driving the electrode of each plasma tube, and each
10 plasma tube has a local axis 112-1, 112-2, and 112-3. Each
11 plasma tube consists of a plasma tube electrode unit 110-1,
12 isolated plasma tube 108-1, and plasma outlet tube 106-1
13 which is electrically connected to other plasma outlet
14 tubes with shared plasma outlet 102. The associated
15 structure for this particular plasma tube indicated with a
16 "-1" suffix, and the plasma tubes for other phases are
17 correspondingly indicated with "-2" and "-3" suffixes. The
18 plasma tube axis 112-1, 112-2, 112-3 are separated from
19 each other by a solid angle with respect to a central axis
20 (not shown), such that the plasma tubes are separated from
21 each other in a plane normal to the central axis (not
22 shown) by an angle of $360/n$, where n is the number of

1 phases and plasma tubes. In the three phase example of
2 figure 1, the plasma tubes are separated from each other by
3 120 degrees circumferentially, and the angular separation
4 from the central axis to the local axis of each plasma tube
5 may vary from 5 to 30 degrees, as required by the
6 application. As will be described in detail later,
7 controller 120 has an electrode control part which provides
8 drive voltage to each plasma tube electrode, and a gas
9 control part which includes an optical arc measurement for
10 estimating the temporal plasma arc attachment axial
11 location in the electrode, a gas inlet and control for the
12 multiple locations in each plasma tube where ionizing gas
13 is introduced, and coolant for each electrode. The
14 electrical, fluid, and gas interconnects from each plasma
15 tube to controller 120 are shown for simplicity as single
16 interconnects 122-1, 122-2, and 122-3.

17 The plasma generator may be used with any combination
18 of ionizing and non-ionizing gases, including air,
19 nitrogen, carbon dioxide, hydrogen, and noble and inert
20 gasses. The plasma generator of the present invention is
21 suitable for generation of high energy plasmas with arc
22 lengths in excess of .3m, such as arc voltages of 1KV to
23 6KV, any number of electrical phases (equal in number to

1 the number of plasma tubes), and arc currents of 30A to
2 500A, resulting in high energy plasma in the range of 100KW
3 to 2500KW.

4 Figure 2 shows a cross section diagram for one of the
5 plasma tubes of figure 1. Plasma outlet tube 106-1 is
6 centered about local axis 112-1 and leads to the shared
7 plasma outlet 102 which terminates in plasma outlet
8 aperture 104-1, which is joined electrically and
9 mechanically to the other plasma outlet tubes 106-2 and
10 106-3. Adjacent to, and electrically isolated from plasma
11 outlet tube 106-1, is isolated central plasma tube 108-1,
12 which is also adjacent to and electrically isolated from
13 plasma tube electrode termination 110-1. Plasma initiation
14 first gap 228-1 with gap extent A1 and plasma initiation
15 second gap 230-1 with gap extent A2 are on opposite ends of
16 the isolated plasma tube 108-1, with first gap 228-1 formed
17 by the gap between conductive hollow cylindrical electrode
18 206-1 and the conductive sleeve 202-1 of isolated plasma
19 tube 108-1. Second gap 230-1 with gap extent A2 is formed
20 by the gap between the electrically conductive isolated
21 plasma tube 202-1 and electrically conductive plasma outlet
22 tube 106-1. The hollow cylindrical electrodes 206-1 may be
23 formed from any combination of copper, copper alloy,

1 graphites, or formed from any conductor suitable for use in
2 high temperature environments. Additionally, the hollow
3 cylindrical electrodes 206-1 may include water cooling
4 jackets (not shown) for heat removal such as with a coolant
5 such as water, or the water cooling jacket may be isolated
6 from the coolant using a suitable thermally conductive but
7 electrically insulating dielectric material. The plasma
8 outlet tube 106-1 and isolated plasma tube 108-1 may be
9 formed from any electrically conductive material, including
10 aluminum, copper, and copper alloys. As a rough guideline,
11 for optimum outlet tube 106 and plasma tube 108 life, is
12 preferred to use stainless steel for these components where
13 the plasma current is less than 60 amps, and copper and
14 copper alloys for currents above 60A.

15 Also located in the first gap 228-1 is a first gap gas
16 delivery structure 236-1 which includes gas inlet port 204-
17 1, and structure 236-1 may optionally direct the inlet gas
18 in a circular flow perpendicular to axis 112-1 to encourage
19 a circumferential trajectory of the arc attachment about
20 hollow cylindrical electrode 206-1. On the opposite end of
21 hollow cylindrical electrode 206-1 is an electrode gas port
22 212-1 which includes a similar structure and inlet
23 apertures 232-1 to encourage a circumferential trajectory

1 of the gas introduced into the region of the hollow
2 cylindrical electrode 206-1, with the introduced gas having
3 a circular trajectory with the same sense as was provided
4 by first gap gas delivery structure 236-1 through first gap
5 228-1. Controlling the relative gas flows between first
6 gap 228-1 and electrode gap 232-1 allows axial control of
7 the arc attachment point, and the measurement of axial arc
8 attachment is performed with optical arc attachment
9 estimator 214-1, which determines the attachment point
10 through transparent window 216-1, which isolates the
11 estimator 214-1 from the plasma and also encloses the gas
12 and plasma volume, thereby directing the introduced gas to
13 the exit aperture 104-1.

14 Voltage is applied to hollow cylindrical electrode
15 206-1 through lead 210-1, which passes first through
16 helical wound coil 208-1, and the opposite end of the
17 helically wound coil 208-1 which surrounds electrode 206-1
18 and is then electrically connected to the electrode 206-1,
19 such that plasma current which passes through the electrode
20 206-1 self-generates an axial magnetic field parallel to
21 local axis 112-1, which, along with the circumferential
22 velocity of gasses introduced to the electrode, also
23 encourages circumferential rotation of the arc attachment

1 point across the inner surface of electrode 206-1. In this
2 manner, the axial magnetic field generated by the plasma
3 current causes circumferential movement of the arc
4 attachment point, and differential control of gas flow
5 through electrode gas inlet 212-1 and first gap gas inlet
6 204-1 provides axial steering of the arc attachment point
7 over the inner surface of the hollow cylindrical electrode
8 206-1, with the differential gas flow rates determined from
9 measurement of the axial arc position using optical
10 measurement unit 214-1 through transparent circular window
11 216-1. Alternatively, axial arc attach position may be
12 determined using a linear array of sensors which are
13 positioned along the axial extent of electrode 106-1 and
14 are optically coupled through apertures in the hollow
15 electrode 206-1.

16 Second gap 230-1 also has a gas inlet port 234-1 which
17 directs gas into the plasma tube using housing 232-1. The
18 hollow electrode 206-1 has an axial extent L1 220-1, the
19 isolated plasma tube 202-1 has an axial extent L2 222-1,
20 and the plasma outlet tube 106-1 has an axial extent L3
21 from second gap 230-1 to outlet aperture 104-1 shown in
22 figure 1. The extent of each of these three sections is
23 selected in combination with first gap A1 and second gap A2

1 extents and operating voltage to provide for plasma
2 initiation upon application of voltage to the hollow
3 electrodes, as can be seen in figure 3A for two electrodes.

4 In a first interval of plasma initiation shown in
5 figure 3A, a voltage such as three phase voltage in the
6 example range of 10kV to 20kV is applied across annular
7 electrodes 206-1, 206-2, and 206-3 while ionizing gas is
8 introduced in the three ports (electrode gas port 212-1,
9 first gap gas port 204-1, and second gap gas port 234-1) of
10 each plasma tube. If the first gap extent A1 (shown in
11 figure 2 as 228-1) of each plasma tube is shorter than
12 second gap extent 230-1 A2, the electric field density will
13 be highest at the first gap extent, resulting in the
14 ionization of gas and subsequent formation of initial
15 plasma 320, 322, 324, followed almost instantaneously by
16 initial plasma formation 321, 323, 325, as shown in the
17 first gap and second gap regions, respectively, of the
18 three plasma tubes. The initial plasmas formed across the
19 first gap and second gap of each plasma tube spread along
20 the conductive walls or electrode surface of the respective
21 axial extents of each plasma tube, as shown in first gap
22 regions 330, 332, 334 arc extent from electrode to isolated
23 plasma tube wall and second gap regions 336, 338, and 340

1 from isolated plasma tube wall to shared plasma outlet
2 tubes of figure 3B, and each of the plasmas grows in
3 lateral extent and also in the direction of the plasma
4 outlet tube exit apertures 104-1, 104-2, 104-3 (shown for
5 reference in this composite cross section view) with the
6 introduction of pressurized gas in the electrode gap, first
7 gap, and second gap regions. As the extent of the plasmas
8 grows and follows the gas to the exit apertures, the plasma
9 regions between electrodes interconnect and interact until
10 each electrode has a single plasma path interconnecting
11 each of the electrodes of the respective plasma tubes, as
12 shown in figure 3C plasma 340, 342, 344, and the plasma
13 longer has attachment points to the conductive isolated
14 plasma tubes 202-1, 202-2, or 202-3 or to the shared plasma
15 outlet plasma tubes 106-1, 106-2, or 106-3. At this point,
16 the plasma is now flowing directly between electrodes 206-
17 1, 206-2, and 206-3 and is entirely contained within the
18 plasma tubes and directed to the exit apertures, with no
19 remaining plasma in the first and second gap regions. The
20 plasma torch has now completed plasma initiation and enters
21 a steady state operational mode.

22 Figure 3C also shows the gas controller 350 component
23 of the controller 120 of figure 1. Gas controller 350

1 includes an axial arc attachment sensor 214-1, 214-2, 214-3
2 and associated control valves (not shown) which regulate
3 the flow of gas to the electrode gas port 212-1, first gap
4 gas port 204-1, and second gap gas port 234-1 based on the
5 arc attachment local axial (Z) position, which position is
6 modulated cyclically from front to rear of the hollow
7 cylindrical electrode by regulation of the ratio of gas
8 flows into the electrode gas port on the rear of the
9 electrode and first gap gas line port on the front of the
10 electrode to minimize the single point surface wear.
11 Successful control of the axial arc attach position and
12 circumferential rotation rate of the arc attach can provide
13 a large increase in electrode usable life in the range of
14 thousands of hours of life. The arc attachment control for
15 each plasma tube operates independently of the arc attach
16 control of the other plasma tubes.

17 Figures 4 and 5 show one example embodiment for a
18 sensor system estimating the arc axial position. Arc axial
19 positional estimator 214-1 may use an omni-directional
20 optical sensor 410 which is responsive to the intensity of
21 the arc, such that when the near field arc intensity is
22 used as a calibration point, the separation distance may be
23 computed using the detector output and the inverse square

1 law which estimates intensity at a distance, in combination
2 with the near field arc intensity measurement. The arc
3 attachment point 404 rotates circumferentially over the
4 inside surface of electrode 206-1 at a particular distance
5 406, with a high rate of circumferential rotation compared
6 to axial movement, so that as the arc spot 404 rotates, the
7 fixed circumferential distance 406 to detector 410 produces
8 a relatively fixed detector response at output 412. The
9 detector response for arc spot 404 is shown in 506 of
10 figure 5, with the distance response shown with the inverse
11 square response plot 504, such that an arc attachment at
12 point 402, which is a separation distance 408 from detector
13 410 produces the response shown in point 502. Window 216-1
14 provides optical coupling from detector 410 to resolve the
15 range of arc spot attachment from 402 to 404 while
16 providing mechanical and electrical isolation of the
17 detector from the ionized gas and plasma arc. Detector 410
18 may be operative in the infrared, visible, or ultraviolet
19 wavelengths, and window 216-1 may be constructed of a
20 material with matching wavelength characteristics.

21 One of the advantages of the present invention is the
22 independent control of arc attachment axial position, which
23 is controlled by the ratio of F_2 to total flow $F_t = F_1 + F_2$ and

1 control of the arc attachment circumferential rotation,
2 which is primarily controlled by the azimuthal velocity
3 component of the gas jets F1 and F2 at the hollow electrode
4 in combination with the magnetic field generated by the
5 coil which surrounds the electrode. It is desired to be
6 able to control these independent arc position parameters
7 to prevent excessive heat buildup on an electrode from a
8 stationary arc spot attachment, which would otherwise cause
9 destruction of the electrode surface.

10 In one example embodiment of the invention, a flow of
11 gas at a substantially fixed flow rate F_t is divided
12 between the front gas port 204-1 and rear gas port 212-1 of
13 the electrode. In this embodiment, the total flow of gas
14 is F_t ($F_t = F_1 + F_2$), where F_1 and F_2 are shown in figure 4
15 and the fraction of gas applied to the rear gas port of the
16 electrode may be expressed as $F_2 = K * F_t$ ($0 \leq K \leq 1$).
17 Figure 6 shows a plot for axial control of the arc
18 attachment point using the configuration of figures 4. As
19 was described in figure 2, electrode gas port 212-1 (shown
20 with flow rate F_2) and first gap gas port 204-1 (shown with
21 flow rate F_1) both support controllable gas flows, with the
22 gas flow F_2 of electrode port 212-1 passing over the
23 surface of electrode 206-1, and where the axial position of

1 the circumferentially rotating arc attach can be entirely
2 controlled by the ratio of gas flows for F1 and F2. In this
3 manner, the circumferential arc attachment can be varied
4 from 0 (arc attachment 404) to L1 (arc attachment 402)
5 through control of flows F2 and F1 at port 212-1 and 204-1,
6 respectively. This is illustrated in plot 602 of figure 6,
7 which shows that as flow F2 is increased from 0 to the
8 maximum flow rate F_t , the axial position of the arc
9 attachment point can be varied from 0 to L1.

10 In one "open loop arc attachment control" embodiment
11 of the invention, the required flow rates F1 and F2 (or
12 alternatively the required values of K for a particular F_t)
13 are determined which provide control of the plasma arc
14 attach position over the range 0-L for a particular
15 electrode configuration. Once these parameters are known,
16 it is possible to simply vary F1 and F2 (or K) in a
17 cyclical manner to ensure sufficient arc attachment
18 circumferential rotation and axial movement, which would
19 thereby eliminate the need for the arc position detector
20 214-1 of figure 4.

21 Independent from the axial position control, the
22 circumferential rotation of the arc attachment (for a fixed
23 axial position) can be controlled by the circumferential

1 velocity components of the gas flows F1 and F2 entering the
2 electrode, in addition to the JxB magnetic field generated
3 by the coil surrounding the electrode. In the embodiment
4 of the invention shown in figures 4 and 7, the magnetic
5 field generated by coil 208-1 (which carries the electrode
6 206-1 feed current) interacts with the plasma to cause a
7 JxB axial rotational force which is proportional to gas
8 flow.

9 In one embodiment of the invention, flow-directing
10 vanes may be present in the structures associated with
11 electrode gap 232-1 of figure 2 and first gap 228-1 (and
12 optionally electrode 206-1) which causes the gas entering
13 ports 212-1 and 204-1, respectively, to have a
14 circumferential velocity in the same direction as the
15 smaller circumferential velocity generated by the JxB field
16 within the electrode, and these two forces together
17 contribute to the circumferential rotation of the arc
18 attachment spot on the inner surface of the electrode.
19 Where such structure which cause circular rotation of the
20 gas are present, the circumferential rotational velocity of
21 the arc attachment spot may be controlled, as shown in
22 figure 7, by the combined flow F1 and F2 which enters the
23 electrode port and first gap port.

1 In one embodiment of the invention, 10% to 50% of the
2 gas flow through a particular plasma tube enters through
3 the first gap gas port and electrode gas port (for control
4 of the arc attach axial position), and in another
5 embodiment of the invention, the second gap gas port is
6 responsible for 50% to 90% of the gas flow in a plasma
7 tube.

8 The number of turns on coil 208-1 of figure 2 which is
9 in series with the electrode lead 210-1 are chosen to
10 provide a magnetic field strength sufficient to ensure
11 optimum plasma coherency, which provides for a high current
12 and high temperature plasma, while also providing minimal
13 wear to the surface of the hollow cylindrical electrode
14 206-1. As current density and electrode wear are competing
15 parameters, a tradeoff is made between these two objectives
16 in the selection of the coil. Since the gas entry at
17 electrode gap 232-1 and first gap 228-1 provides
18 circumferential velocity, it is also possible in one
19 embodiment of the invention to control plasma rotational
20 velocity using gas pressure alone. In another embodiment
21 of the invention, the plasma circumferential rotation is
22 achieved using the interaction between the magnetic field
23 generated by coil 208-1 and the self-current of the plasma

1 at the arc attach point, and in another embodiment of the
2 invention, the magnetic field of the coil, the self-current
3 of the plasma, and the circumferential velocity of the gas
4 provide rotation of the plasma arc spot attachment to the
5 electrode 206-1.

6 Figure 8 identifies particular structures with
7 dimensional notations provided, and in one embodiment of
8 the invention, the following preferred dimensional
9 relationships may be used:

10 D1 - inner diameter of the hollow cylindrical
11 electrode, selected on the basis of electrode life, current
12 density, and heat dissipation (in the range 20-200mm in one
13 embodiment);

14 L1 - hollow electrode length, in the range of $2 \cdot D1$ to
15 $10 \cdot D1$;

16 L2 - isolated plasma tube electrode length, in the
17 range of $5 \cdot D1$ to $30 \cdot D1$;

18 D2 - isolated plasma tube electrode inner diameter, in
19 the range of $0.5 \cdot D1$ to $D1$;

20 H1 - in the case where a vortex is used (where the
21 intermediate tube has a diameter $D2$ less than hollow

1 electrode diameter D_1) H_1 may be in the range of 20mm-
2 300mm;

3 L_3 - plasma outlet tube length, in the range of $5 \cdot D_1$
4 to $40 \cdot D_1$;

5 A_1 - first gap extent in the range 1mm to 10mm;

6 A_2 - second gap extent in the range of 1mm to 10mm.

7 Figure 9 shows a cross section diagram of the gas
8 inlet structures adjacent to the hollow electrode, such as
9 through section A-A of figure 8. Each gas inlet admits a
10 gas through an inlet port 902, where it encounters a series
11 of vane structure 906 or other structures which direct the
12 flow of the gas in a tangential circumferential flow 912,
13 as shown by flow trajectory 910. In a preferred
14 embodiment, the vanes 906 terminate outside the extent 908
15 of the hollow electrode so as to not interfere with plasma
16 initiation or generation, and the vanes 906 may be
17 fabricated from an insulating material to avoid
18 interference with the plasma initiation.

19 In one alternative embodiment of the plasma generator,
20 the individual outlet apertures of the shared plasma outlet
21 are collected together into a single plasma port for
22 transfer and delivery of the generated plasma. In another

1 embodiment of the invention, the electrodes are coupled to
2 a voltage source which provides alternating current (AC),
3 or the electrodes are coupled to a coil wound around the
4 hollow electrode, or to an alternating current voltage
5 source with series inductors which limit the plasma
6 current, or any combination of these. Additionally, the
7 example shown may be adapted to operate on any number of
8 electrical phases, although three phases is shown. In
9 other example embodiments for a single phase application,
10 there may be two plasma tubes, or alternatively, four
11 plasma tubes may be connected with same-phase electrodes
12 adjacent to each other and with 90 degree separation from a
13 common central axis.

14 Additionally, the controller 350 of figures 3A, 3B,
15 and 3C or the controller 120 of figure 1 may estimate axial
16 position of the arc attachment using an optical sensor, or
17 it may regulate gas flows such as F1 and F2 of figure 4
18 (G1_gas and E_gas, respectively, in figures 3A, 3B, and 3C)
19 for axial control based on device characteristics in
20 combination with the measurement of current and voltage
21 applied to each electrode, where the characterization also
22 indicates the amount of F1 and F2 gas flows required for
23 satisfactory operation and axial movement to achieve

1 uniform electrode wear. Similarly, the measurements of
2 electrode voltage and current may be used to regulate the
3 flows of E_gas, G1_gas, and G2_gas shown in figures 3A, 3B,
4 and 3C.

1

2 I claim:

3 1) A plasma torch comprising:

4 an outlet aperture formed by a plurality of plasma
5 outlet tubes which join to form a plurality of plasma
6 outlets;

7 a plurality of isolated plasma tubes, each having a
8 first gap end and a second gap end;

9 a plurality of hollow electrodes, each placed a first
10 gap distance from an associated end of said isolated plasma
11 tube first gap end, thereby forming a first gap;

12 each said isolated plasma tube second gap end placed a
13 second gap distance from an associated said plasma outlet
14 tube, thereby forming a second gap;

15 each said hollow electrode having a first gap gas
16 inlet surrounding said first gap, an electrode gas inlet on
17 the opposite end of said hollow electrode, and a second gap
18 gas inlet surrounding said second gap;

19 a plasma gas which enters said electrode gas inlet,
20 said first gap gas inlet, and said second gap gas inlet;

1 at least two said hollow electrodes energized with a
2 voltage from a voltage source sufficient to ionize said
3 plasma gas.

4

5 2) The plasma torch of claim 1 where said voltage is
6 a three phase voltage and the number of said plurality of
7 hollow electrodes and said plasma tubes is three.

8

9 3) The plasma torch of claim 1 where said first gap
10 distance and said second gap distance are selected to
11 initially ionize said plasma gas across said first gap and
12 said second gap, the plasma thereafter flowing directly
13 from one said hollow electrode to another said hollow
14 electrode.

15

16 4) The plasma torch of claim 1 where said electrode
17 gas inlet and said first gap gas inlet have a plurality of
18 vanes to cause circumferential gas flow across the inner
19 surface of said hollow electrode.

20

1 5) The plasma torch of claim 1 where at least one of
2 said electrode gas inlet or said first gap gas inlet
3 generates a circumferential gas flow adjacent to said
4 hollow electrode.

5

6 6) The plasma torch of claim 1 where said hollow
7 electrode includes a coil wound around the outer diameter
8 of said hollow electrode, said coil generating a
9 substantially axial magnetic field.

10

11 7) The plasma torch of claim 1 where said hollow
12 electrode includes a coil wound around the outer diameter
13 of said hollow electrode, said coil in series with said
14 voltage source and said electrode.

15

16 8) The plasma torch of claim 1 where said voltage
17 source is a three phase alternating current (AC) voltage
18 source.

19

20 9) The plasma torch of claim 1 where said voltage
21 source is current limited by a series inductance.

1

2 10) The plasma torch of claim 1 where said electrode
3 gas inlet includes an adjacent transparent aperture for the
4 examination of the axial location of a plasma arc
5 attachment within said hollow electrode, and the flow of
6 gas into said electrode gas inlet and said first gap gas
7 inlet is controlled to cyclically move an arc attachment
8 point over the axial extent of said hollow electrode.

9

10 11) A plasma torch having:

11 a plurality of hollow electrodes, each said hollow
12 electrode having an electrode gas inlet port and a first
13 gap gas inlet port on the opposite end from said electrode
14 gas inlet port;

15 a plurality of isolated plasma tubes, each said
16 isolated plasma tube placed a first gap distance from said
17 hollow electrode, thereby forming a first gap having a
18 first gap plasma initiation region, each said isolated
19 plasma tube having a second gap end opposite said first gap
20 plasma initiation region;

1 a plurality of electrically connected plasma tubes,
2 each said electrically connected plasma tube placed a
3 second gap distance from an associated isolated plasma tube
4 second gap end, thereby forming a second gap having a
5 second gap plasma initiation region, the opposite end of
6 said electrically connected plasma tubes having a plasma
7 outlet aperture which is adjacent to other electrically
8 connected plasma tubes and thereby forming a plasma outlet;

9 whereby upon the application of a gas to said
10 electrode gas inlet, said first gas inlet, and said second
11 gas inlet, and the application of an electrical voltage to
12 said electrodes, said first plasma initiation region and
13 said second plasma initiation region form localized plasmas
14 across said first gap and said second gap which join to
15 form a single plasma across said hollow electrodes.

16

17 12) The plasma torch of claim 11 where said electrode
18 gas inlet and said first gas inlet have respective gas
19 flows which are cyclically varied.

20

1 13) The plasma torch of claim 11 where said electrode
2 has a plurality of tangentially formed apertures which
3 cause the circumferential flow of said plasma gas.

4

5 14) The plasma torch of claim 11 where said gas
6 includes an ionizing or non-ionizing gas.

7

8 15) The plasma torch of claim 11 where said gas
9 includes at least one of nitrogen, carbon dioxide,
10 hydrogen, noble, or an inert gas.

11

12 16) The plasma torch of claim 11 where said hollow
13 electrode includes a co-axially wound coil which is in
14 series with said electrode and said voltage source for said
15 electrode.

16

17 17) The plasma torch of claim 11 where said electrode
18 gas inlet and said first gap gas inlet are fed with gasses
19 having a flow rate which is controlled based on axial arc
20 attachment position within an associated electrode.

21

1 18) The plasma torch of claim 11 where said electrode
2 gas inlet and said first gap gas inlet are fed with
3 substantially constant gas flow rate which is cyclically
4 varied proportionally between said electrode gas inlet and
5 said first gap gas inlet sufficient to move an arc
6 attachment location axially over said electrode surface.

7

8 19) The plasma torch of claim 11 where said source of
9 electrical voltage is a three phase alternating current
10 (AC) voltage.

11

12 20) The plasma torch of claim 19 where said source of
13 electrical voltage is current limited by a series inductor.

14

15

Figure 1
Plasma Torch

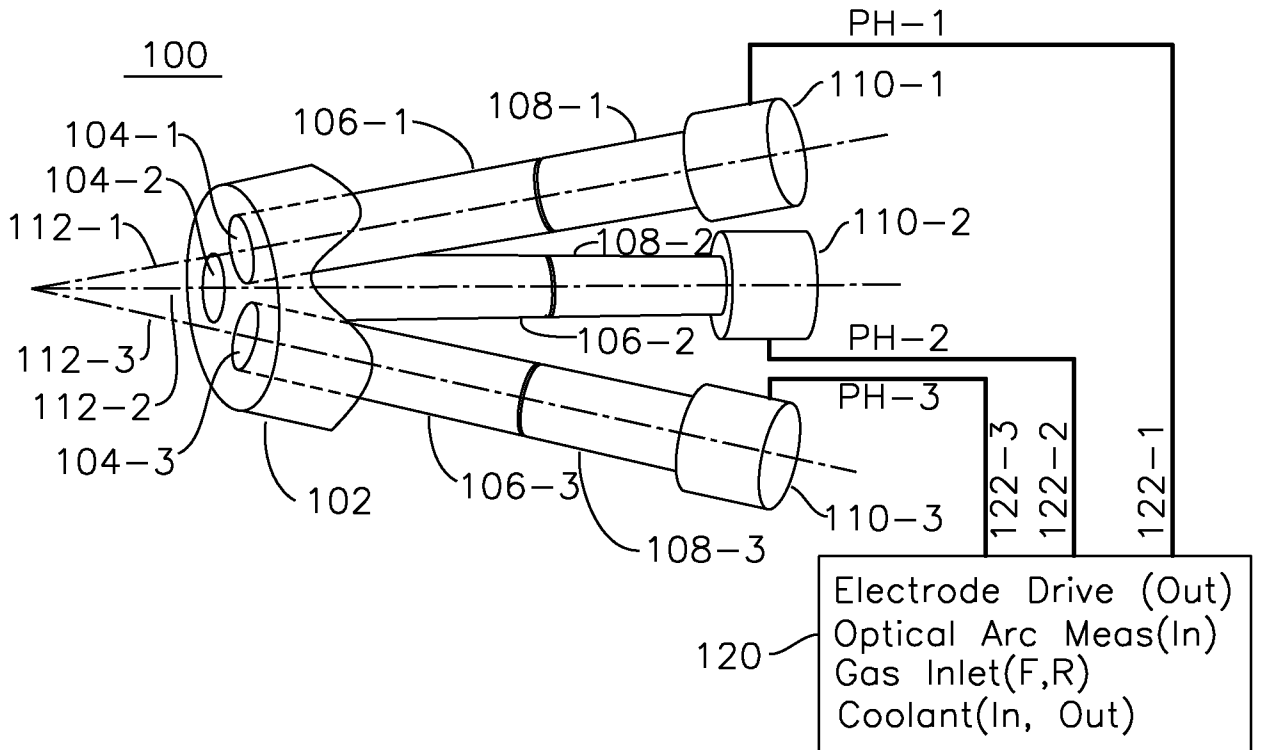
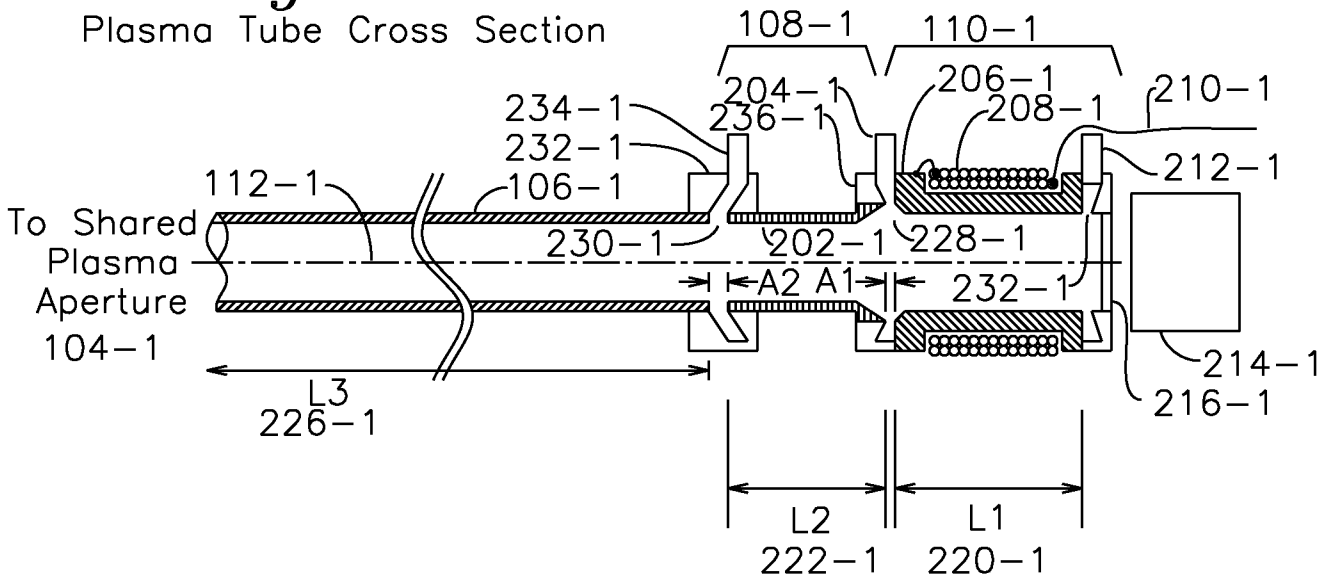
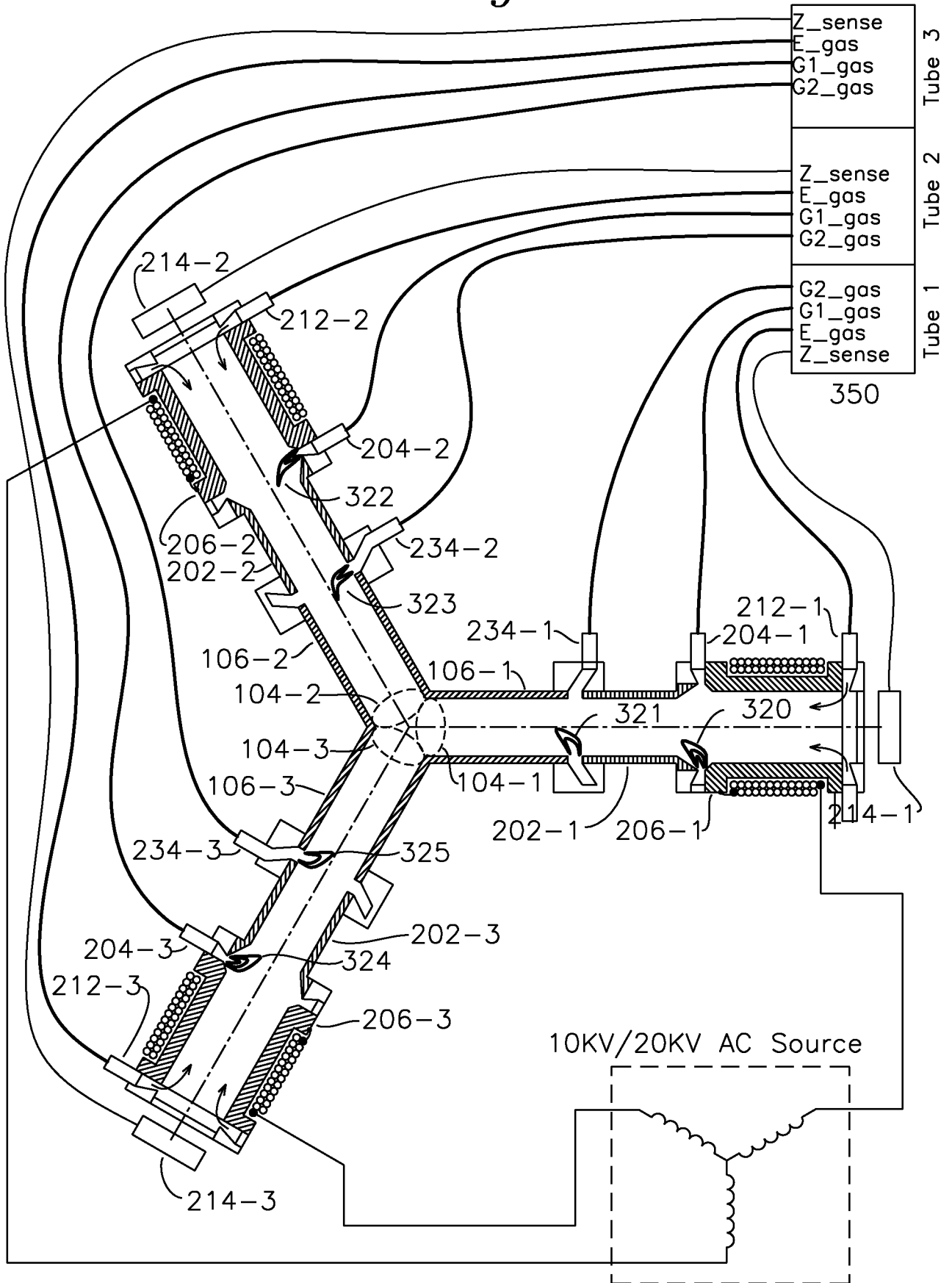


Figure 2
Plasma Tube Cross Section



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Figure 3A



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Figure 3B

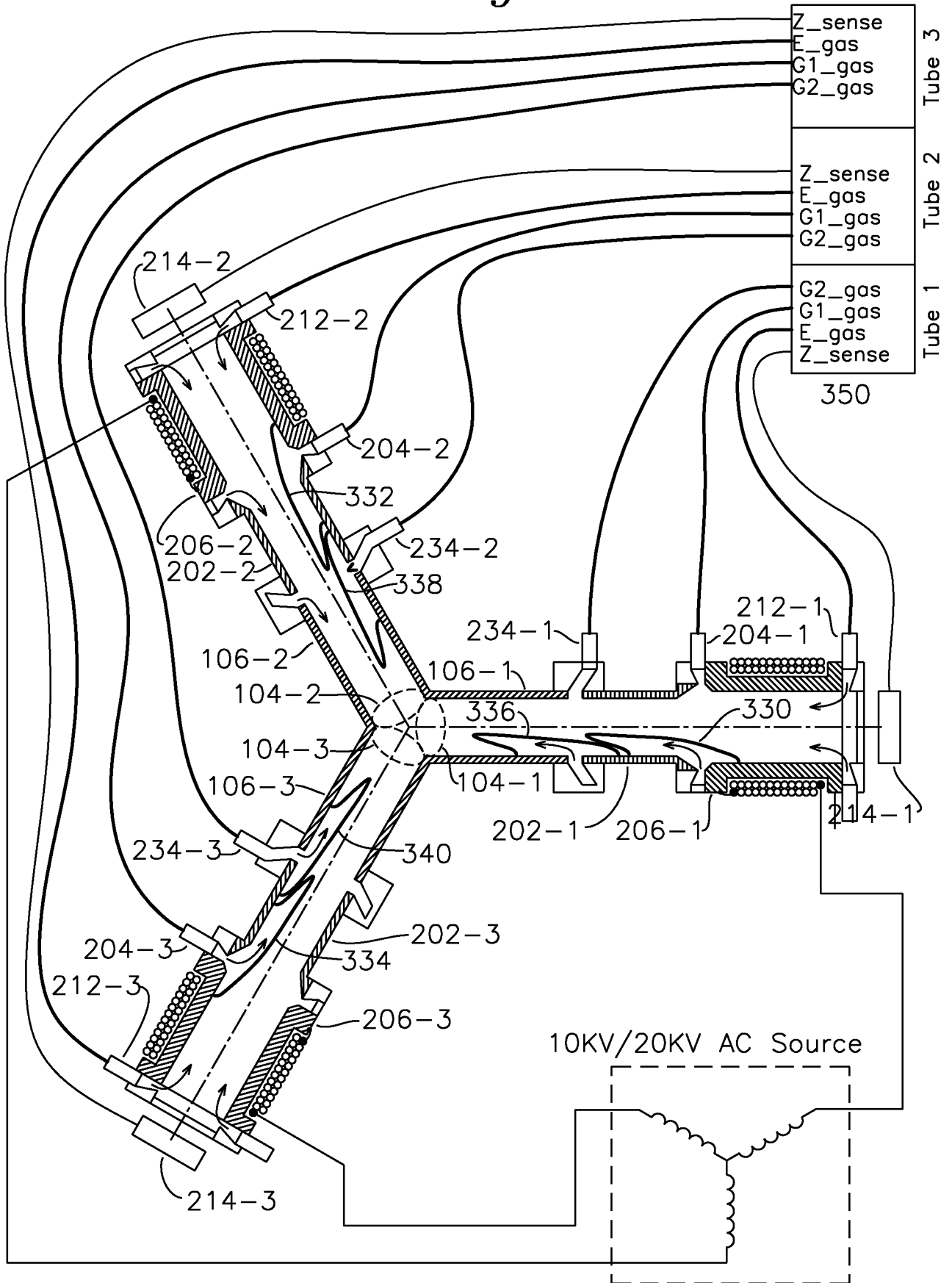


Figure 3C

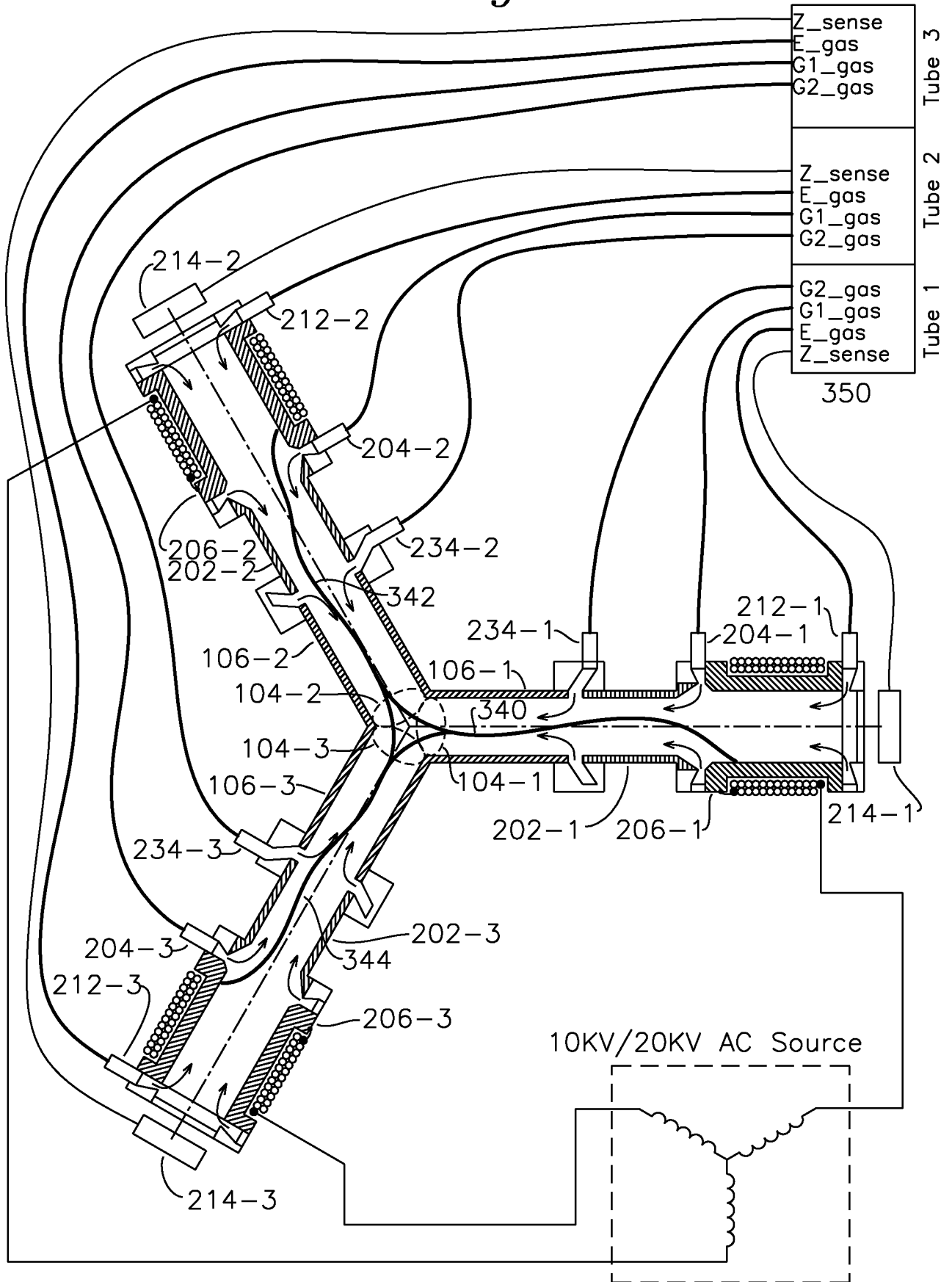


Figure 4

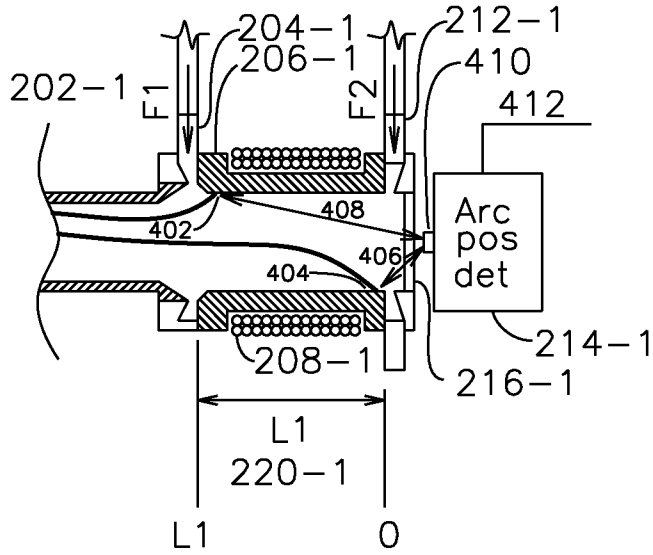


Figure 5

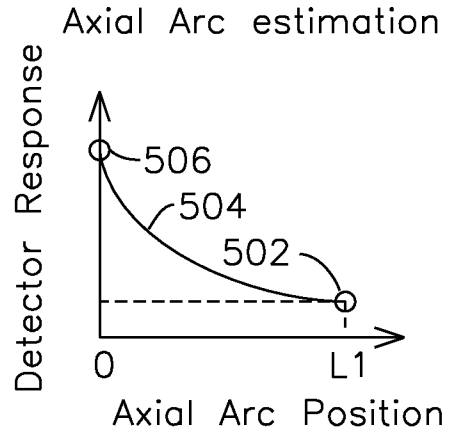


Figure 6

Axial arc position control using flow F2

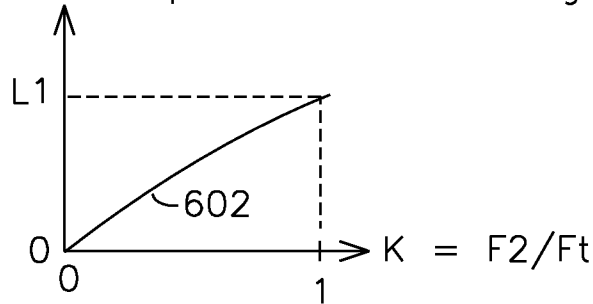
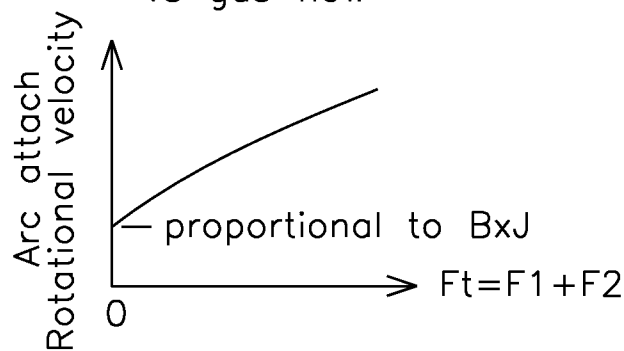


Figure 7

Arc attach angular velocity vs gas flow



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Figure 8
Plasma Tube Dimensions

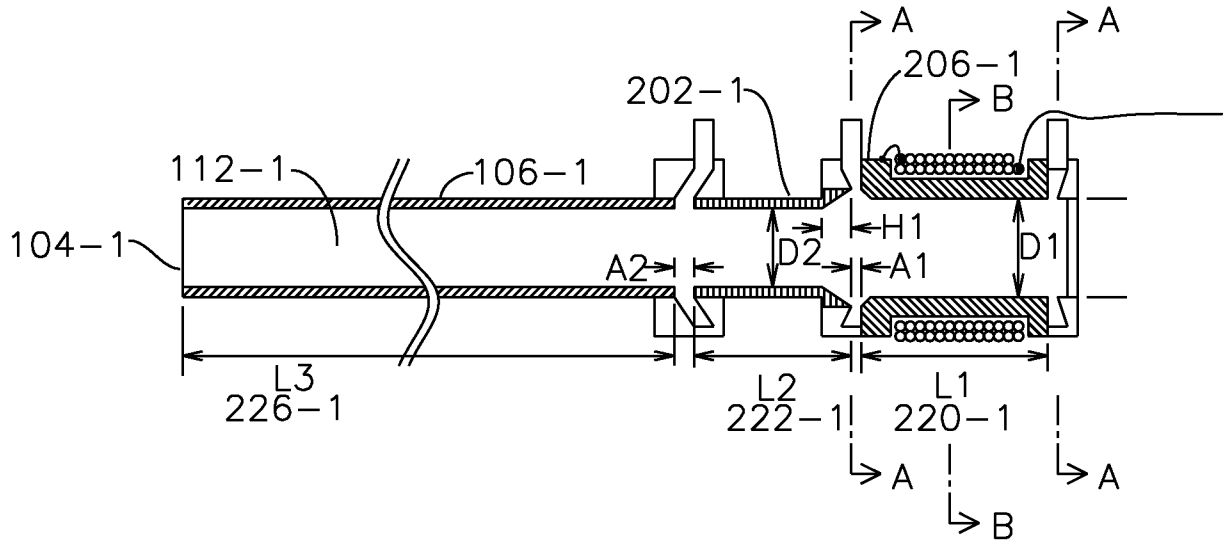
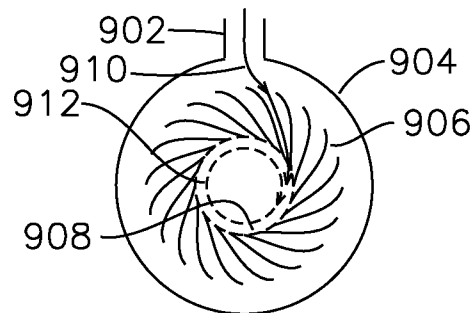


Figure 9
Gas Inlet cross section A-A



INTERNATIONAL SEARCH REPORT

International application No.

PCT/US 12/48575

<p>A. CLASSIFICATION OF SUBJECT MATTER IPC(8) - B23K 10/02 (2012.01) USPC - 219/121.48 According to International Patent Classification (IPC) or to both national classification and IPC</p>																																
<p>B. FIELDS SEARCHED</p> <p>Minimum documentation searched (classification system followed by classification symbols) IPC(8): B23K 10/02 (2012.01) USPC: 219/121.48</p> <p>Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched IPC(8): B23K 10/02 (2012.01) USPC: 219/121.48, 121.52, 121.55; 373/18</p> <p>Electronic data base consulted during the international search (name of data base and, where practicable, search terms used) PubWEST; PGPB, USPT, EPAB, JPAB; Google Scholar; Google Patent; Search Terms: Plasma ion hollow tube electrode swirl gap inlet gas argon noble poly-phase three-phase alternating current voltage inductance coil wound magnet micro-wave torch material hollow chamber three third 120 equidistant jet</p>																																
<p>C. DOCUMENTS CONSIDERED TO BE RELEVANT</p> <table border="1"> <thead> <tr> <th>Category*</th> <th>Citation of document, with indication, where appropriate, of the relevant passages</th> <th>Relevant to claim No.</th> </tr> </thead> <tbody> <tr> <td>Y</td> <td>US 4,517,495 A (Piepmeier) 14 May 1985 (14.05.1985) col 3 ln 14 to col 6 ln 65, Fig. 1-4.</td> <td>1-20</td> </tr> <tr> <td>Y</td> <td>US 2004/0256365 A1 (DePetrillo et al.) 23 December 2004 (23.12.2004) para. [0022]-[0025], [0029], [0033], [0035]-[0045], Fig. 1</td> <td>1-20</td> </tr> <tr> <td>Y</td> <td>US 5,906,757 A (Kong et al.) 25 May 1999 (25.05.1999) Fig. 4-6</td> <td>4, 5 and 13</td> </tr> <tr> <td>Y</td> <td>US 2011/0079506 A1 (Bijker et al.) 07 April 2011 (07.04.2011) para. [0033], [0045]</td> <td>10</td> </tr> <tr> <td>A</td> <td>US 2008/0145553 A1 (Boulos) 19 June 2008 (19.06.2008) entire document</td> <td>1-20</td> </tr> <tr> <td>A</td> <td>US 3,248,513 A (Sunnen) 26 April 1966 (26.04.1966) entire document</td> <td>1-20</td> </tr> <tr> <td>A</td> <td>US 3,541,297 A (Sunnet et al.) 17 November 1970 (17.11.1970) entire document</td> <td>1-20</td> </tr> <tr> <td>A</td> <td>US 4,564,740 A (Paton et al.) 14 January 1986 (14.01.1986) entire document</td> <td>1-20</td> </tr> <tr> <td>A</td> <td>US 3,578,943 A (Schoumaker) 18 May 1971 (18.05.1971) entire document</td> <td>1-20</td> </tr> </tbody> </table>			Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.	Y	US 4,517,495 A (Piepmeier) 14 May 1985 (14.05.1985) col 3 ln 14 to col 6 ln 65, Fig. 1-4.	1-20	Y	US 2004/0256365 A1 (DePetrillo et al.) 23 December 2004 (23.12.2004) para. [0022]-[0025], [0029], [0033], [0035]-[0045], Fig. 1	1-20	Y	US 5,906,757 A (Kong et al.) 25 May 1999 (25.05.1999) Fig. 4-6	4, 5 and 13	Y	US 2011/0079506 A1 (Bijker et al.) 07 April 2011 (07.04.2011) para. [0033], [0045]	10	A	US 2008/0145553 A1 (Boulos) 19 June 2008 (19.06.2008) entire document	1-20	A	US 3,248,513 A (Sunnen) 26 April 1966 (26.04.1966) entire document	1-20	A	US 3,541,297 A (Sunnet et al.) 17 November 1970 (17.11.1970) entire document	1-20	A	US 4,564,740 A (Paton et al.) 14 January 1986 (14.01.1986) entire document	1-20	A	US 3,578,943 A (Schoumaker) 18 May 1971 (18.05.1971) entire document	1-20
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<p>Date of the actual completion of the international search 29 November 2012 (29.11.2012)</p>		<p>Date of mailing of the international search report 19 DEC 2012</p>																														
<p>Name and mailing address of the ISA/US Mail Stop PCT, Attn: ISA/US, Commissioner for Patents P.O. Box 1450, Alexandria, Virginia 22313-1450 Facsimile No. 571-273-3201</p>		<p>Authorized officer: Lee W. Young PCT Helpdesk: 571-272-4300 PCT OSP: 571-272-7774</p>																														