



**WO 2014/025551 A1**



---

TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, **Published:**  
KM, ML, MR, NE, SN, TD, TG).

— *with international search report (Art. 21(3))*

## **MICROWAVE ABLATION CATHETER AND METHOD OF UTILIZING THE SAME**

### **CROSS REFERENCE TO RELATED APPLICATIONS**

[0001] The present application claims the benefit of and priority to U.S. Provisional Patent Application Serial No. 61/680,555 filed on August 7, 2012 by Brannan et al.; U.S. Provisional Patent Application Serial No. 61/783,921 filed on March 14, 2013 by Ladtkow et al.; U.S. Provisional Patent Application Serial No. 61/784,048 filed on March 14, 2013 by Ladtkow et al.; U.S. Provisional Patent Application Serial No. 61/784,176 filed on March 14, 2013 by Ladtkow et al.; U.S. Provisional Patent Application Serial No. 61/784,297 filed on March 14, 2013 by Ladtkow et al.; and U.S. Provisional Patent Application Serial No. 61/784,407 filed on March 14, 2013 by Ladtkow et al., the entire contents of each being incorporated herein by reference.

### **BACKGROUND**

#### **Technical Field**

[0002] The present disclosure relates to a microwave ablation catheter and method of utilizing the same. More particularly, the present disclosure relates to a microwave ablation catheter that is positionable through one or more branched luminal networks of a patient for treating tissue.

#### **Description of Related Art**

[0003] Microwave ablation may be utilized for treating various maladies, e.g., nodules, of different organs like the liver, brain, heart, lung and kidney. When a nodule is found, for example, within a lung, several factors are considered in making a diagnosis. For example, a biopsy of the nodule may be taken using a biopsy tool under CT guidance. If the biopsy reveals that the nodule is malignant, it may prove useful to ablate the nodule. In this instance, microwave ablation, which typically includes transmitting microwave energy to a

percutaneous needle, may be utilized to ablate the nodule. Under certain surgical scenarios, certain current percutaneous methods of microwave ablation procedures can result in pneumothoraces (air leaks) and a collection of air in the space around the lungs which if not appreciated by the clinician can ultimately lead to collapse of the lung or a portion thereof.

[0004] Endobronchial navigation uses CT image data to create a navigation plan to facilitate advancing a navigation catheter (or other suitable device) through a bronchoscope and a branch of the bronchus of a patient to the nodule. Electromagnetic tracking may also may be utilized in conjunction with the CT data to facilitate guiding the navigation catheter through the branch of the bronchus to the nodule. In certain instances, the navigation catheter may be positioned within one of the airways of the branched luminal networks adjacent to or within the nodule or point of interest to provide access for one or more tools. Once the navigation catheter is in position, fluoroscopy may be used to visualize biopsy tools, such as, for example, biopsy brushes, needle brushes and biopsy forceps as they are passed through the navigation catheter and into the lung and to the nodule or point of interest.

## **SUMMARY**

[0005] As can be appreciated, a microwave ablation catheter that is positionable through one or more branched luminal networks of a patient to treat tissue may prove useful in the surgical arena.

[0006] Aspects of the present disclosure are described in detail with reference to the drawing figures wherein like reference numerals identify similar or identical elements. As used herein, the term “distal” refers to the portion that is being described which is further from a user, while the term “proximal” refers to the portion that is being described which is closer to a user.

[0007] An aspect of the present disclosure provides a microwave ablation system configured for use in a luminal network. The microwave ablation system includes a microwave energy source and a tool for treating tissue. An extended working channel is configured to provide passage for the tool. A locatable guide, translatable through the extended working channel, is configured to navigate the extended working channel adjacent a target. The microwave ablation system may include a bronchoscope that is configured to receive the extended working channel and for providing access to the luminal network.

[0008] The tool may be a microwave ablation catheter. The microwave ablation catheter may include a coaxial cable that is connected at its proximal end to a microwave energy source and at its distal end to a distal radiating section. The coaxial cable includes inner and outer conductors and a dielectric positioned therebetween. The inner conductor extends distally past the outer conductor and is in sealed engagement with the distal radiating section. A balun is formed in part from a conductive material electrically connected to the outer conductor of the coaxial cable and extends along at least a portion of the coaxial cable. The conductive material has a braided configuration and is covered by at least one insulative material.

[0009] The extended working channel may include a closed distal end and a multi-lumen configuration configured to receive the ablation catheter. The extended working channel may further include a hub at a proximal end thereof. The hub may include a fluid intake port and a fluid return port configured to provide respective ingress and egress of a coolant to and from the extended working channel for cooling the ablation catheter.

[0010] An expandable member may be provided on an exterior of the extended working channel. The expandable member being movable to an inflated condition to create a tamponade when the microwave ablation catheter is positioned within the luminal network. The expandable member may be configured to control local properties of the luminal

network. The expandable member may be configured to anchor the extended working channel when the extended working channel is positioned within the luminal network to prevent the extended working channel from moving out of position when the locatable guide or the microwave ablation catheter are moved therein. The expandable member may be in the form of a balloon.

**[0011]** Alternatively, the balun may be movable to an inflated condition to create a tamponade when the microwave ablation catheter is positioned within the luminal network. The balun may be configured to anchor the microwave ablation catheter when the microwave ablation catheter is positioned within the luminal network to maintain the microwave ablation catheter in a relatively fixed configuration.

**[0012]** The distal radiating section of the microwave ablation catheter or a distal tip of the extended working channel may be selectively energizable to penetrate tissue. Moreover, the distal radiating section of the microwave ablation catheter may be covered with a temperature sensitive wax configured to melt when the microwave ablation catheter is activated. Further, a piston including a needle may be operably coupled to at least one fluid port of the extended working channel and is extendable from the distal end of the extended working channel for piercing tissue.

**[0013]** A distal end of the extended working channel may be energizable for penetrating target tissue. The distal end of the extended working channel may include one or more electrodes that extend at least partially along an outer peripheral surface of the extended working channel. The electrode(s) may be operable in a monopolar mode of operation.

**[0014]** The microwave ablation system may include a navigation system that is configured for guiding the tool, the extended working channel or the locatable guide through the luminal network following a predetermined determined pathway. The predetermined pathway may be generated based on computed tomographic (CT) data of the luminal

network, and may be displayed in a generated model. The predetermined pathway may be generated from CT data to identify a pathway to a target identified by a user in the CT data, and the pathway may be generated for acceptance by the user before use in the navigation system. The navigation system may include a head-up display.

## **BRIEF DESCRIPTION OF THE DRAWING**

[0015] Various embodiments of the present disclosure are described hereinbelow with references to the drawings, wherein:

[0016] Fig. 1 is a perspective view of a microwave ablation system including a microwave ablation catheter assembly configured for use with a microwave ablation system according to an embodiment of the instant disclosure;

[0017] Fig. 2 is a front view of an embodiment of a lumen configuration configured for use with the microwave catheter assembly shown in Fig. 1;

[0018] Fig. 3A is a front view of an another embodiment of a lumen configuration configured for use with the microwave catheter assembly shown in Fig. 1;

[0019] Fig 3B is a front view of an another embodiment of a lumen configuration configured for use with the microwave catheter assembly shown in Fig. 1;

[0020] Fig 3C is a front view of an another embodiment of a lumen configuration configured for use with the microwave catheter assembly shown in Fig. 1, whereby the lumen supporting the coaxial microwave structure also communicates cooling fluid with inflow or outflow ports;

[0021] Fig. 4 is a perspective view of a distal end of a microwave ablation catheter configured for use with the microwave ablation assembly shown in Fig. 1;

[0022] Fig. 5 is a cross-sectional view taken along line section 5-5 in Fig. 4;

[0023] Fig. 6 is a screen shot of a CT based luminal navigation system in accordance with an embodiment of the present disclosure;

[0024] Fig. 7 is a perspective view of a microwave ablation system and luminal navigation system configured for use the microwave ablation catheter assembly shown in Fig. 1 and microwave ablation catheter shown in Fig. 2 in accordance with an embodiment of the present disclosure;

[0025] Fig. 8 is a side view of a luminal catheter delivery assembly including an extended working channel and locatable guide catheter in accordance with an embodiment of the present disclosure;

[0026] Fig. 9 is a partial, perspective view of a distal end of the locatable guide catheter shown in Fig. 8;

[0027] Fig. 10 is a side view of the extended working channel shown in Fig. 8 with the microwave ablation catheter extending from a distal end thereof;

[0028] Fig. 11 is a screen shot of a CT based luminal navigation system in accordance with an embodiment of the present disclosure;

[0029] Fig. 12A is a schematic, plan view of the extended working channel positioned within a bronchoscope prior to being positioned within a trachea of a patient;

[0030] Fig. 12B is a schematic, plan view of the bronchoscope shown in Fig. 12A positioned within the trachea of the patient with the extended working channel extending distally therefrom;

[0031] Fig. 12C is a partial, cutaway view of the extended working channel and locatable guide positioned within the bronchoscope;

[0032] Fig. 13A is a schematic, plan view of the bronchoscope positioned within the trachea of the patient with the extended working channel extending distally therefrom;



[0033] Fig. 13B is a partial, cutaway view of the extended working channel and a biopsy tool positioned within the bronchoscope;

[0034] Fig. 14 is a schematic, plan view of the bronchoscope positioned within the trachea of the patient with the extended working channel removed from the bronchoscope;

[0035] Fig. 15A is a schematic, plan view of the bronchoscope positioned within the trachea of the patient with an extended working channel according to an alternate embodiment extending distally therefrom;

[0036] Fig. 15B is a partial, cutaway view of the extended working channel shown in Fig. 15A positioned within the bronchoscope;

[0037] Fig. 16A is a schematic, plan view of the bronchoscope positioned within the trachea of the patient with the extended working channel shown in Fig. 15A extending distally therefrom;

[0038] Fig. 16B is a schematic, plan view of the bronchoscope positioned within the trachea of the patient with the extended working channel shown in Fig. 15A extending distally therefrom and adjacent target tissue;

[0039] Fig. 16C is a partial, cutaway view of the extended working channel and the microwave ablation catheter shown in Fig. 2 coupled to one another and positioned within the bronchoscope;

[0040] Fig. 16D is a cross-sectional view taken along line section 16D-16D in Fig. 16C;

[0041] Fig. 17 is a schematic, plan view of another embodiment of the extended working shown in Figs. 9 and 15A with the extended working channel positioned within the lung of a patient and having a balloon coupled thereto in a deflated configuration;

[0042] Fig. 18 is an enlarged area of detail of Fig. 17 and showing the balloon in an inflated configuration;

[0043] Fig. 19A is a schematic, plan view of an alternate embodiment of a balun configured for use with the microwave ablation catheter shown in Fig. 2 with the balun shown in an expanded configuration;

[0044] Fig. 19B is a schematic, plan view of the balun shown in Fig. 19A in a non-expanded configuration;

[0045] Fig. 20 is a schematic, plan view of a distal tip configuration that may be utilized with the microwave ablation catheter assembly shown in Fig. 1, the microwave ablation catheter shown in Fig. 2 or the extended working channel shown in Fig. 15A;

[0046] Fig. 21 is a schematic, plan view of an alternate embodiment of the extended working channel shown in Fig. 15A;

[0047] Fig. 22 is a schematic, plan view of yet another embodiment of the extended working channel shown in Fig. 15A;

[0048] Fig. 23 is a perspective view of an alternate embodiment of the luminal navigation system shown in Fig. 7;

[0049] Fig. 24 is a partial, cutaway view of another embodiment of the microwave ablation catheter shown in Fig. 1;

[0050] Fig. 25 is a cross-sectional view taken along line section 25-25 in Fig. 24;

[0051] Fig. 26 is a cross-sectional view taken along line section 26-26 in Fig. 24;

[0052] Fig. 27 is a partial, cutaway view of yet another embodiment of the microwave ablation catheter shown in Fig. 1;

[0053] Fig. 28 is a schematic, plan view of still yet another embodiment of the microwave ablation catheter shown in Fig. 1;

[0054] Fig. 29 is a schematic, plan view illustrating a circulation feedback loop that is configured for use with the extended working channels shown in Figs. 15A, 17 and 21, and the microwave ablation catheter shown in Figs. 1, 24 and 27-28;

[0055] Fig. 30 is a schematic, plan view of still yet another embodiment of the extended working channel shown in Fig. 15A;

[0056] Fig. 31 is a schematic, plan view of still yet another embodiment of the extended working channel shown in Fig. 15A with the microwave ablation catheter shown in Fig. 2 in a retracted configuration;

[0057] Fig. 32 is a schematic, plan view of the extended working channel shown in Fig. 31 with the microwave ablation catheter shown in an extended configuration;

[0058] Fig. 33 is a schematic, plan view of still yet another embodiment of the extended working channel shown in Fig. 15A;

[0059] Fig. 34 is a schematic, plan view of still yet another embodiment of the extended working channel shown in Fig. 15A with the extended working channel shown in a non-expanded configuration;

[0060] Fig. 35 is a schematic, plan view of the extended working channel shown in Fig. 34 in an expanded configuration;

[0061] Fig. 36A is a front view of an alternate embodiment of the microwave ablation catheter shown in Fig. 2 including a conductive balloon coupled thereto and shown in a deflated configuration;

[0062] Fig. 36B is a front view of the microwave catheter shown in Fig. 36A with the conductive balloon shown in an inflated configuration;

[0063] Fig. 37A is a front view of an alternate embodiment of the microwave ablation catheter shown in Fig. 2 including a plurality of thermally conductive fins coupled thereto and shown in a non-deployed configuration;

[0064] Fig. 37B is a front view of the microwave catheter shown in Fig. 37A with the plurality of thermally conductive fins shown in a deployed configuration;

[0065] Fig. 38 is a schematic, plan view of still yet another embodiment of the extended working channel shown in Fig. 15A;

[0066] Fig. 39A is a schematic, plan view of an alternate embodiment of the microwave ablation catheter shown in Fig. 2 including a balloon coupled thereto and shown in a deflated configuration;

[0067] Fig. 39B is a schematic, plan view of the microwave catheter shown in Fig. 39A with the balloon shown in an inflated configuration;

[0068] Fig. 40A is a schematic, plan view of various fiducial markers configured for use with the microwave ablation system shown in Fig. 7, wherein the fiducial markers are shown adjacent target tissue that has not been ablated;

[0069] Fig. 40B is a schematic, plan view of the fiducial markers shown in Fig. 40A, wherein the fiducial markers are shown adjacent target tissue that has been ablated;

[0070] Fig. 41 is a schematic, plan view of a guide wire including a plurality of thermocouples configured for use with the microwave ablation system shown in Fig. 7;

[0071] Fig. 42 is a perspective view of an electrical measurement system configured for use with the microwave ablation system shown in Fig. 7;

[0072] Fig. 43 is a schematic, plan view of a feedback configuration configured for use with the microwave ablation system shown in Fig. 7;

[0073] Fig. 44 is a schematic, plan view of an another embodiment of a feedback configuration configured for use with the microwave ablation system shown in Fig. 7;

[0074] Fig. 45 is schematic, plan view of a yet another embodiment of a feedback configuration configured for use with the microwave ablation system shown in Fig. 7;

[0075] Fig. 46A is a fluoroscopic images of a patient, having a catheter placed therein; and

[0076] Fig. 46B is a virtual fluoroscopic image of a patient depicting a target.

**DETAILED DESCRIPTION**

[0077] Detailed embodiments of the present disclosure are disclosed herein; however, the disclosed embodiments are merely examples of the disclosure, which may be embodied in various forms. Therefore, specific structural and functional details disclosed herein are not to be interpreted as limiting, but merely as a basis for the claims and as a representative basis for teaching one skilled in the art to variously employ the present disclosure in virtually any appropriately detailed structure.

[0078] As can be appreciated an energy device, such as a microwave ablation catheter, that is positionable through one or more branched luminal networks of a patient to treat tissue may prove useful in the surgical arena and the present disclosure is directed to such apparatus, systems and methods. Access to lumeninal networks may be percutaneous or through natural orifice. In the case of natural orifice, an endobronchial approach may be particularly useful in the treatment of lung disease. Targets, navigation, access and treatment may be planned pre-procedurally using a combination of imaging and/or planning software. In accordance with these aspects of the present disclosure the planning software may offer custom guidance using pre-procedure images). Navigation of the luminal network may be accomplished using image-guidance. These image-guidance systems may be separate or integrated with the energy device or a separate access tool and may include MRI, CT, fluoroscopy, ultrasound, electrical impedance tomography, optical, and device tracking systems. Methodologies for locating the separate or integrated to the energy device or a separate access tool include EM, IR, echolocation, optical, and others. Tracking systems may integrated to imaging device, where tracking is done in virtual space or fused with preoperative or live images. In some cases the treatment target may be directly accessed from within the lumen, such as for the treatment of the endobronchial wall for COPD, Asthma, lung cancer, etc. In other cases, the energy device and/or an additional access tool

may be required to pierce the lumen and extend into other tissues to reach the target, such as for the treatment of disease within the parenchyma. Final localization and confirmation of energy device placement may be performed with imaging and/or navigational guidance using the modalities listed above. The energy device has the ability to deliver an energy field for treatment (including but not limited to electromagnetic fields) and may have the ability to monitor treatment during energy application. The monitoring of the treatment may include thermometry, electrical impedance, radiometry, density measurement, optical absorption, hydration, ultrasound, and others. Additionally or alternatively treatment may be monitored from within the lumen or extracorporeally using an additional device or the image-guidance modalities described above. After treatment, the energy device and/or an additional device may have the ability to confirm adequate treatment was performed, employing at least the techniques described above with respect to treatment monitoring. Further, treatment confirmation may be from within the lumen or extracorporeal. The long term treatment performance may be performed with imaging which may be integrated into a follow-up software application.

**[0079]** One embodiment of the present disclosure is directed, in part, to a microwave ablation catheter that is positionable through one or more branched luminal networks of a patient to treat tissue. The microwave ablation catheter is part of an ablation system that includes a microwave energy source and a planning and navigation system for the placement of the catheter at a desired location within the luminal network. Further, the system includes imaging modalities that can be employed to confirm placement of the catheter and the effect of the application of energy. The microwave catheter itself may include the capability to aide in the confirmation of the placement within the tissue to be treated, or additional devices may be used in combination with the microwave catheter to confirm placement within the tissue to be treated. Still further, one or more thermocouples or temperature sensors on the

microwave catheter detect the temperature of the microwave catheter or the tissue surrounding the catheter and enable monitoring of the microwave catheter temperature and the tissue temperature during and after treatment both for safety purposes and for dosage and treatment pattern monitoring purposes. The microwave catheter may also assist in the access to the target tissue, either intraluminal or outside the lumen. The microwave catheter may also assist in the monitoring of the treatment through various measurement techniques and may also be used for treatment confirmation, in addition to assistance from other monitoring and confirmation devices.

**[0080]** Figs. 1-5 depict various aspects of a microwave ablation system 10 (system 10). The system 10, as show in Fig. 1 includes a microwave ablation catheter assembly 12 (assembly 12) configured to house a microwave ablation catheter 14 (ablation catheter 14) (shown in Fig. 4). Assembly 12 and ablation catheter 14 are configured to couple to a microwave energy source (energy source 16) that is configured to transmit microwave energy to the catheter 14 to treat target tissue, e.g., lung tissue.

**[0081]** The assembly 12 shown in Fig. 1 is configured to receive the ablation catheter 14 and to provide a pathway for a cooling medium to circulate within the assembly 12 and cool the ablation catheter 14 when the ablation catheter 14 is energized. With these purposes in mind, assembly 12 is formed by overmolding plastic to form a generally elongated housing 23 having an outer sheath 18 (Fig. 2) and a plurality of lumens 19a, 19b, and 19c extending from a proximal end 20 to a distal end 22 that includes a relatively pointed or appropriately rounded distal tip 21. A hub portion 24 is provided at the proximal end 20 and includes ports 26a, 26b, 26c that couple to corresponding distal ends (not explicitly shown) of connection tubes 28a, 28b, 28c. Connection tubes 28a, 28c include respective proximal ends 30a, 30c that are configured to releasably couple either directly or indirectly to a fluid source 32 including hoses 31a, 31b that provide one or more suitable cooling mediums (e.g., water,

saline, air or combination thereof) to the ablation catheter 14. In embodiments, the fluid source 32 may be a component of a cooling system that is disclosed in U.S. Patent Application No. XX/XXX,XXX having attorney docket no. H-IL-00083, the entirety of which is incorporated herein by reference. A proximal end 30b of connection tube 28b is configured to couple either directly or indirectly to the energy source 16 to energize the ablation catheter 14. An optional pair of wings 34a, 34b may be provided at the proximal end 20 of the assembly 12. The wings 34a, 34b may extend laterally from respective right and left sides of the proximal end 20 and may be configured to rest on a patient or to be grasped by a clinician for manipulation of the assembly 12.

**[0082]** The ports 26a, 26c of the assembly 12 are in fluid communication with corresponding lumens 19a, 19c of the plurality of lumens 18 provided within the assembly 12 (Fig. 2) and are configured to provide one of the aforementioned cooling mediums to the assembly 12. In an embodiment, such as the embodiment illustrated in Fig. 2, port 26a is an outflow port and provides a point of egress for the cooling medium from outflow lumen 19a and port 26c is an inflow port and provides point of ingress for the cooling medium into the inflow lumen 19c.

**[0083]** Fig. 3A illustrates an alternate lumen configuration that may be utilized with the assembly 12. In this embodiment, two outflow lumens 19a' and one inflow lumen 19c' are provided and are in fluid communication with the respective ports 26a, 26c.

**[0084]** Fig. 3B illustrates an alternate lumen configuration that may be utilized with the assembly 12. In this embodiment, two outflow lumens 19a' and one inflow lumen 19c' are provided and are in fluid communication with the respective ports 26a, 26c. Additionally, the lumen supporting the coaxial microwave structure is also used for either fluid inflow or outflow.



[0085] Fig. 3C illustrates an alternate lumen configuration similar to Fig. 3a and 3b that may be utilized with the assembly 12. In this embodiment, two outflow lumens 19a' and two inflow lumens 19c' are provided and are in fluid communication with the respective ports 26a, 26c.

[0086] A third lumen 19b is provided within the assembly 12 and is configured to support the ablation catheter 14 when the ablation catheter 14 is coupled to the assembly 12. In the embodiment illustrated in Fig. 2, the outflow and inflow lumens 19a, 19c are formed above the lumen 19b. In the embodiment illustrated in Fig. 3A, the lumen 19b is centered between the outflow lumens 19a and inflow lumens 19c to provide two opposing outflow lumens 19a and two opposing inflow lumens 19c around the lumen 19b. In the embodiments illustrated in Figs 3A and 3B, the lumen 19b is centered between the outflow lumens 19a and inflow lumen 19c to provide two opposing outflow lumens 19a and one opposing inflow lumen 19c around the lumen 19b. The lumen configurations illustrated in Figs. 2 and 3A-3C provide the assembly 12 with the needed flexibility to move within the relatively thin conductive airways (and/or vessels) in the branch of the bronchus.

[0087] In an embodiment, the assembly 12 may include a 4 lumen configuration (not shown). In this embodiment, three (3) outer lumens (e.g., a combination of outflow and inflow lumens 19a, 19c, respectively) may be equally spaced around a center lumen (e.g., lumen 19b) that is configured to support the ablation catheter 14 when the ablation catheter 14 is coupled to the assembly 12. In one particular embodiment, the three (3) outer lumens may be configured to include two (2) inflow lumens 19c and one (1) outflow lumen 19a (or vice versa).

[0088] The outflow and inflow lumens 19a, 19c extend a predetermined distance within the assembly 12 and can function with various coolant feedback protocols (e.g., open or closed feedback protocols). In the embodiments illustrated in Figs. 2 and 3A-3C, the

inflow lumens 19c extend distally of the outflow lumens 19a to allow an adequate amount of cooling medium to circulate around the ablation catheter 14. It should be understood, regardless of the number of or configuration of lumens, space not filled within the lumen supporting the coaxial cable and radiating section may be used for additional fluid ingress or egress to improve fluid flow and directly cool through intimate fluid contact the coaxial microwave structures. In addition to supporting the ablation catheter, the lumen 19b may also support additional outflow or inflow of coolant, whereby lumen 19b may couple to connection tubes 28a, 28c and their respective proximal ends 30a, 30c.

[0089] Referring now to Figs. 4 and 5, the ablation catheter 14 is illustrated. Ablation catheter 14 includes a coaxial cable 36. Coaxial cable 36 includes a proximal end 38 that couples to port 26b (shown in Fig. 1) that provides electrical connection to the inner conductor 40 and outer conductor 48 of the coaxial cable 36 and the energy source 16.

[0090] A distal radiating section 42 is provided at a distal end 44 of the coaxial cable 36 and is configured to receive the inner conductor 40, as best seen in Fig. 5. The distal radiating section 42 may be formed from any suitable material. In embodiments, the distal radiating section 42 may be formed from ceramic or metal, e.g., copper, gold, silver, etc. The distal radiating section 42 may include any suitable configuration including but not limited to a blunt configuration, flat configuration, hemispherical configuration, pointed configuration, bar-bell configuration, tissue piercing configuration, etc. The distal radiating section 42 may couple to the distal end 44 of the coaxial cable via soldering, ultrasonic welding, adhesive, or the like. In one embodiment the distal radiating section 42 is sealed to the inner conductor 40 and a dielectric 50 to prevent fluid from contacting the inner conductor 40. As an alternative, the seal may be just between the inner conductor 40 and the dielectric 50.

[0091] An outer conductor 48 is braided and extends along the dielectric 50 positioned between the inner and outer conductors 40, 48, respectively (Fig. 5). As defined

herein braided means made by intertwining three or more strands, and while described as a braid, the actual construction is not so limited and may include other formations of outer conductors of coaxial cables as would be understood by those of ordinary skill in the art. One advantage of a braided configuration of the outer conductor 48 is that it provides the ablation catheter 14 with the flexibility to move within the relatively narrow luminal structures such as the airways of the lungs of a patient. Additionally, through the use of flat wire braiding and follow on braid compression with an appropriately sized die, the cross sectional dimension of the braided conductor may be minimized significantly in comparison to other conductive structures, such as a drawn copper tubing, while maintain an acceptable electrical performance.

[0092] A choke or balun 52 is formed in part of a conductive layer 51 that extends along a portion of the coaxial cable 36. The conductive layer 51 may be a braided material of similar construction as the outer conductor 48 and is connected to the outer conductor 48. Specifically, a portion of the outer conductor 48 is shorted (e.g., soldered, interbraided or otherwise affixed) to a proximal portion 54 of the conductive layer 51.

[0093] The balun 52 also includes an insulative layer 56, which may be formed of a polytetrafluoroethylene (PTFE). The insulative layer 56 is generally formed between the conductive material 52 and the outer conductor 48. The insulative layer 56 extends distally past a distal end of the conductive material 52. The insulative layer 56 and its orientation extending beyond the conductive layer can be adjusted during manufacture to control the overall phase, energy field profile, and temperature response of the coaxial cable 36.

[0094] The outer conductor 48 extends distally beyond the insulative layer 56. A portion of the outer conductor 48 is removed to expose the dielectric 50 of the coaxial cable 36 and form a feedgap 58. The feedgap 58 is located distally from the balun 52 and proximal of and immediately adjacent the distal radiating section 42. The feedgap 58 and distal

radiating section 42 are located and dimensioned to achieve a specific radiation pattern for the ablation catheter 14.

[0095] The ablation catheter 14 may optionally include an outer sheath 62 that extends to the proximal end 54 of the balun 52. Alternatively, no outer sheath 62 is employed and just a thin layer of insulative material 60 (e.g., a layer of polyethylene terephthalate (PET)) may be used to cover a portion of the outer conductor 48, and the balun 52 up to the point the insulative layer 56 extends beyond the conductive layer 51 of the balun 52 (Fig. 5). In yet a further embodiment the layer of PET 60 may be configured to extend proximally along the length of the coaxial cable 36 to assist in maintaining the braided configuration of the outer conductor 48 and conductive layer 51. As will be appreciated by those of skill in the art, removal of the outer sheath 62 and replacing it with a thin material, either along the length of the coaxial cable 36 or just at the balun 52 increases the flexibility of the ablation catheter 14. This added flexibility is beneficial for enabling greater ranges of movement when the ablation catheter 14 is used in luminal networks having small diameters and having a branched structure of multiple sharp turns, as will be described in greater detail below.

[0096] The flexibility of the ablation catheter 14 can be altered to accommodate a specific surgical procedure, a specific luminal structure, specific target tissue, a clinician's preference, etc. For example, in an embodiment, it may prove advantageous to have an ablation catheter 14 that is very flexible for movement through the relatively narrow airway of the lungs of a patient. Alternatively, it may prove advantageous to have an ablation catheter 14 that is only slightly flexible, e.g., where the ablation catheter 14 is needed to pierce or puncture target tissue. Still further, to achieve the desired amount of flexibility it may be desirable to form the balun 52 in a manner consistent with the disclosure of U.S. Patent Application Serial No. XX/XXX,XXX (Attorney Docket No. H-IL-00077 (1988-77))

entitled “Microwave Energy-Delivery Device and System” the entire contents of which is incorporated herein by reference. Still further, although the microwave ablation catheter described here may be specific, it should be understood to those of skill in the art that other microwave ablation catheter embodiments, either simplified or more complex in structural detail, may be employed without departing from the scope of the instant disclosure.

[0097] In embodiments, a temperature monitoring system 3 (Fig. 1), e.g., microwave thermometry, may be utilized with the ablation catheter 14 to observe/monitor tissue temperatures in or adjacent an ablation zone. In an embodiment, for example, one or more temperature sensors “TS” may be provided on the ablation catheter 14, e.g., adjacent the distal radiating section 42 (as shown in Fig. 5) and may be configured to measure tissue temperatures in or adjacent an ablation zone. The temperature monitoring system 3 can be, for example, a radiometry system, a thermocouple based system, or any other tissue temperature monitoring system known in the art. The temperature monitoring system 3 may be incorporated into the energy source 16 to provide feedback to the energy source, or alternatively be housed in a separate box providing audible or visual feedback to the clinician during use of the ablation catheter 14. In either embodiment, the temperature monitoring system 3 may be configured to provide tissue temperature and ablation zone temperature information to the energy source 16 (or other suitable control system). In embodiments, temperature sensors 3 may be included along the coaxial cable 36, or along assembly 12 (described with reference to Fig. 1), or along the EWC 90 to provide a greater array of temperature data collection points and greater detail on the temperature of the tissue following application of energy.

[0098] In at least one embodiment, the tissue temperature and/or ablation zone temperature information may be correlated to specific known ablation zone sizes or configurations that have been gathered through empirical testing and stored in one or more

data look-up tables and stored in memory of the temperature sensing monitoring system 3 and/or the energy source 16. The data look-up tables may be accessible by a processor of the temperature sensing monitoring system 3 and/or the energy source 16 and accessed by the processor while the distal radiating section 42 is energized and treating target tissue. In this embodiment, the temperature sensors “TS” provide tissue temperature and/or ablation zone temperature to the microprocessor which then compares the tissue temperature and/or ablation zone temperature to the known ablation zone sizes stored in the data look-up tables. The microprocessor may then send a command signal to one or more modules of the temperature sensing monitoring system 3 and/or the energy source 16 to automatically adjust the microwave energy output to the distal radiating section 42. Alternatively, a manual adjustment protocol may be utilized to control the microwave energy output to the distal radiating section 42. In this embodiment, the microprocessor may be configured to provide one or more indications (e.g., visual, audio and/or tactile indications) to a user when a particular tissue temperature and/or ablation zone temperature is matched to a corresponding ablation zone diameter or configuration.

**[0099]** System 10, depicted in Fig. 1 is configured to treat tissue, and as further set forth in Fig. 7 enables a method of identifying target tissue (hereinafter simply referred to as “a target”) utilizing computed tomographic (CT) images, and once identified further enables the use of a navigation or guidance system to place the catheter assembly 12 or other tools at the target. CT data facilitates the planning of a pathway to an identified target as well as providing the ability to navigate through the body to the target location, this includes a preoperative and an operative component (i.e., pathway planning and pathway navigation).

**[00100]** The pathway planning phase includes three general steps. The first step involves using software for generating and viewing a three-dimensional model of the bronchial airway tree (“BT”) and viewing the CT data to identify targets. The second step

involves using the software for selection of a pathway on the BT, either automatically, semi-automatically, or manually, if desired. The third step involves an automatic segmentation of the pathway(s) into a set of waypoints along the path that can be visualized on a display. It is to be understood that the airways are being used herein as an example of a branched luminal network. Hence, the term “BT” is being used in a general sense to represent any such luminal network (e.g., the circulatory system, or the gastro-intestinal tract, etc.)

**[00101]** Using a software graphical interface 64 as shown in Fig. 6, generating and viewing a BT, starts with importing CT scan images of a patient’s lungs into the software. The software processes the CT scans and assembles them into a three-dimensional CT volume by arranging the scans in the order they were taken and spacing them apart according to the setting on the CT when they were taken. The software uses the newly-constructed CT volume to generate a three-dimensional map, or BT, of the airways. The software then displays a representation of the three-dimensional map 66 on the software graphical interface 64. A user may be presented with various views to identify masses or tumors that the medical professional would like to biopsy or treat, and to which the medical professional would like to use the system 10 to navigate.

**[00102]** Next, the software selects a pathway to a target, e.g., target 68 identified by a medical professional. In one embodiment, the software includes an algorithm that does this by beginning at the selected target and following lumina back to the entry point. The software then selects a point in the airways nearest the target. The pathway to the target may be determined using airway diameter.

**[00103]** After the pathway has been determined, or concurrently with the pathway determination, the suggested pathway is displayed for user review. This pathway is the path from the trachea to the target that the software has determined the medical professional is to follow for treating the patient. This pathway may be accepted, rejected, or altered by the

medical professional. Having identified a pathway in the BT connecting the trachea in a CT image with a target, the pathway is exported for use by system 10 to place a catheter and tools at the target for biopsy of the target and eventually treatment if necessary. Additional methods of determining a pathway from CT images are described in commonly assigned U.S. Patent Application No. XX/XXX,XXX having attorney docket no. H-IL-00087 (1988-00087) entitled "Pathway Planning System and Method" the entirety of which is incorporated herein by reference.

**[00104]** Fig. 7 shows a patient "P" lying on an operating table 70 and connected to a system enabling navigation along the determined pathway within the luminal network to achieve access to the identified target. A bronchoscope 72 is inserted into the patient's lungs. Bronchoscope 72 is connected to monitoring equipment 74, and typically includes a source of illumination and a video imaging system. In certain cases, the devices of the present disclosure may be used without a bronchoscope, as will be described below. System 10 monitors the position of the patient "P", thereby defining a set of reference coordinates. Specifically, system 10 utilizes a six degrees-of-freedom electromagnetic position measuring system according to the teachings of U.S. Pat. No. 6,188,355 and published PCT Application Nos. WO 00/10456 and WO 01/67035, which are incorporated herein by reference. A transmitter arrangement 76 is implemented as a board or mat positioned beneath patient "P." A plurality of sensors 78 are interconnected with a tracking module 80 which derives the location of each sensor 78 in 6 DOF (degrees of freedom). One or more of the reference sensors 78 (e.g., 3 sensors 78) are attached to the chest of patient "P" and their 6 DOF coordinates sent to a computer 82 (which includes the software) where they are used to calculate the patient coordinate frame of reference.

**[00105]** Fig. 8 depicts a positioning assembly 84, constructed and operative according to the teachings of the present disclosure. Positioning assembly 84 includes a locatable guide



86 which has a steerable distal tip 88, an extended working channel 90 and, at its proximal end, a control handle 92.

**[00106]** There are several methods of steering the extended working channel 90. In a first method, a single direction of deflection may be employed. Alternatively, a multi-directional steering mechanism with a manual direction selector may be employed to allow selection of a steering direction by the practitioner without necessitating rotation of the catheter body. With multi-directional steering four elongated tensioning elements (“steering wires”) 98a are implemented as pairs of wires formed from a single long wire extending from handle 92 to distal tip 88. Steering wires 98a are bent over part of a base 98b and return to handle 92. Steering wires 98a are deployed such that tension on each wire individually will steer the distal tip 88 towards a predefined lateral direction. In the case of four steering wires 98a, the directions are chosen to be opposite directions along two perpendicular axes. In other words, the four steering wires 98a are deployed such that each wire, when actuated alone, causes deflection of the distal tip 98 in a different one of four predefined directions separated substantially by multiples of 90°.

**[00107]** Locatable guide 86 is inserted into the extended working channel 90 within which it is locked in position by a locking mechanism 94. A position sensor element 96 of system 10 is integrated with the distal tip 88 of the locatable guide 86 and allows monitoring of the tip position and orientation (6 DOF) relative to the reference coordinate system.

**[00108]** In embodiments, locatable guide 86 may have a curved or hooked configuration as shown in Fig. 10. This alternative is currently marketed by Covidien LP under the name EDGE®. In such a system, it is the extended working channel 90 that is formed with a curved tip 91. Differing amounts of pre-curve implemented in the extended working channel 90 can be used, however, common curvatures include 45, 90, and 180 degrees. The 180 degree extending working channel 90 has been found particular useful for

directing the locatable guide 86 to posterior portions of the upper lobe of the lung which can be particularly difficult to navigate. The locatable guide 86 is inserted into the extended working channel 90 such that the position sensor 96 projects from the distal tip 88 of the extended working channel 90. The extended working channel 90 and the locatable guide 86 are locked together such that they are advanced together into the lung passages of the patient “P.” In this embodiment, the extended working channel 90 may include a steering mechanism similar to the one already described above. As can be appreciated, certain modifications may need to be made to the extended working channel 90 in order for the extended working channel to function as intended.

**[00109]** In embodiments, an integrated radial ultrasound probe “US” (Fig. 10) may be provided on the extended working channel 90, the locatable guide 86, catheter assembly 12 and/or the ablation catheter 14. For illustrative purposes, the ultrasound probe “US” is shown disposed on the extended working channel 90 and the locatable guide 86. The ultrasound probe “US” may be configured to provide ultrasound feedback to one or more modules of the system 10 during navigation and insertion of the ablation catheter 14 to facilitate positioning the ablation catheter 14 adjacent target tissue. As will be appreciated a US probe may also be used without the extended working channel but in conjunction with an endoscope for imaging central lesions that would be accessible to the endoscope. Furthermore, the US probe may be used to monitor treatment progression and/or confirm treatment completion.

**[00110]** As noted above, the present disclosure employs CT data (images) for the route planning phase. CT data is also used for the navigation phase. Specifically, the CT system of coordinates is matched with the patient system of coordinates; this is commonly known as registration. Registration is generally performed by identifying locations in both the CT and on or inside the body, and measuring their coordinates in both systems. Manual, semi-automatic or automatic registration can be utilized with the system 10. For purposes herein,

the system 10 is described in terms of use with automatic registration. Reference is made to commonly assigned U.S. Patent Application No. 12/780,678, which is incorporated herein by reference, for a more detailed description of automatic registration techniques.

**[00111]** The automatic registration method includes moving locatable guide 86 containing position sensor 96 within a branched structure of a patient “P.” Data pertaining to locations of the position sensor 96 while the position sensor 96 is moving through the branched structure is recorded using the transmitter arrangement 80. A shape resulting from the data is compared to an interior geometry of passages of the three-dimensional model of the branched structure. And, a location correlation between the shape and the three-dimensional model based on the comparison is determined.

**[00112]** In addition to the foregoing, the software of the system 10 identifies non-tissue space (e.g. air filled cavities) in the three-dimensional model. Thereafter, the software records position data of the position sensor 96 of the locatable guide 86 as the locatable guide 86 is moved through one or more lumens of the branched structure. Further, the software aligns an image representing a location of the locatable guide 86 with an image of the three-dimensional model based on the recorded position data and an assumption that the locatable guide 86 remains located in non-tissue space in the branched structure.

**[00113]** Once in place in the patient “P,” a screen 93 will be displayed by the software on the monitoring equipment 74 (Fig. 11). The right image is the actual bronchoscopic image 95 generated by the bronchoscope 72. Initially there is no image displayed in the left image 97, this will be a virtual bronchoscopy generated from the CT image data once registration is complete.

**[00114]** Starting with the locatable guide 86, and specifically the position sensor 96 approximately 3-4 cm above the main carina, as viewed through the bronchoscope 72, the bronchoscope 72 is advanced into both the right and left lungs to, for example, the fourth

generation of the lung passages. By traversing these segments of the lungs, sufficient data is collected as described above such that registration can be accomplished.

[00115] Now that the targets have been identified, the pathway planned, the bronchoscope 72 including locatable guide 86 inserted into the patient "P," and the virtual bronchoscopy image registered with the image data of the bronchoscope 72, the system 10 is ready to navigate the position sensor 96 to the target 68 within the patient's lungs. The computer 80 provides a display similar to that shown in Fig. 11 identifying the target 68 and depicting the virtual bronchoscopy image 99. Appearing in each of the images on the display is the pathway from the current location of the position sensor 96 to the target 68. This is the pathway that was established during the pathway planning phase discussed above. The pathway may be represented, for example, by a colored line. Also appearing in each image is a representation of the distal tip 88 of the locatable guide 86 and position sensor 96. Once the pathway is established, a clinician may utilize system 10 to treat the target tissue 68.

[00116] Operation of the system 10 to treat target tissue is described with reference to Figs. 12A-16C. It is assumed the pathway to the target 68 had been ascertained via the methods described above. After, advancing the bronchoscope 72 including the extended working channel 90 and the locatable guide 86 to a point of being wedged within the luminal network, the extended working channel and locatable guide are further advanced along the identified pathway to the target 68 (see Figs. 12A-12C).

[00117] In some cases the target tissue may be directly accessed from within the lumen (such as for the treatment of the endobronchial wall for COPD, Asthma, lung cancer, etc.), however in other instances, the target is not in direct contact with the BT and use of the locatable guide alone does not achieve access to the target. Additional access tools may be required to cross the lumen and access the target tissue (such as for the treatment of disease within the parenchyma).

**[00118]** Final localization and confirmation of the locatable guide or access tool with extended working channel may be performed with imaging and/or navigational guidance (this may include the same or different combinations of imaging and navigation techniques listed above).

**[00119]** Once the locatable guide 86 or an additional access tool has successfully been navigated to the target 68 location, the locatable guide 86 or access tool may be removed, leaving the extended working channel 90 in place as a guide channel for a biopsy tool 84 to the target 68 location (Figs. 13A-13B). The medical tools may be biopsy tools that can be used to sample the target 68. Details of this system are included in U.S. Patent No. 7,233,820, already incorporated herein by reference.

**[00120]** Once the locatable guide 86 has successfully been navigated to the target 68 location, the locatable guide 86 may be removed, leaving the extended working channel 90 in place as a guide channel for bringing a tool 84 to the target 68 location (Figs. 13A-13B). The medical tools may be biopsy tools that can be used to sample the target 68. These samples are retrieved and sent to pathology for analysis to determine if treatment of the target is necessary. The biopsy analysis can happen in real time after the biopsy procedure such that the ablation can be performed immediately, or there can be some period of time, e.g., hours, days, weeks, between the time when the biopsy is taken and when the ablation procedure is performed.

**[00121]** If it is determined that the target 68 requires treatment (e.g., ablation), the assembly 12 including the ablation catheter 14 may be positioned through the bronchoscope 72 and the extended working channel 90 to enable treatment. Placement of the assembly may occur after the extended working channel 90 has been navigated to the target 68, or the extended working channel 90 may be navigated with the assembly 12 to reach the target 68. This second option may require a sensor providing 6 DOF positioning within either the

extended working channel 90 or the assembly 12. As noted above, the braided configuration of the outer conductor 48 and the conductive layer 51 of the balun 52 in combination with the lumen configurations depicted in Figs. 2-3, provides the assembly 12 with the needed flexibility to move within the relatively narrow airways.

**[00122]** In embodiments, the target tissue “T” may be pierced or penetrated to allow placement of the distal radiating section 42 within the target 68 (e.g., centered within the mass for treatment). For example, a guide wire, piercing tool, a biopsy tool 84 or the distal end 21 of the assembly 12 (described with reference to Fig. 1) may be utilized to pierce or penetrate the target 68. In the instance where the guide wire or piercing tool is utilized to penetrate or pierce tissue, the guide wire or piercing tool may be passed through the extended working channel 90 to penetrate the target 68. Once pierced, the extended working channel 90 may be held in place and the guide wire or piercing tool removed to allow the assembly 12, housing the ablation catheter 14, to be inserted into the opening created by the tool or the guide wire in the target 68. Alternatively, while the guide wire or piercing tool is in the target 68, the extended working channel 90 may be extended to place the distal end of the extended working channel 90 within the opening created in the target 68. Following placement of the extended working channel 90 within the target 68, the guide wire or piercing tool can be removed to allow for insertion of the assembly 12 including ablation catheter 14. This second method helps assure proper placement of the ablation catheter 14, housed within the assembly 12, into the target 68.

**[00123]** One or more imaging modalities may be utilized to confirm that the ablation catheter 14 has been properly positioned (e.g. within the target 68.) For example, computer tomography (CT), ultrasound, fluoroscopy, and other imaging modalities may be utilized individually or in combination with one another to confirm that the ablation catheter 14 has been properly positioned within the target 68. One methodology employing both CT and

fluoroscopy imaging modalities is described in commonly assigned U.S. Application Serial No. 12/056,123 entitled "CT-Enhanced Fluoroscopy," the contents of which is incorporated herein by reference.

**[00124]** Yet a further alternative method of ablation catheter 14 placement confirmation is disclosed herein. Fig. 46A represents a live fluoroscopic image depicting the placement of an extended working channel 90 and an ablation assembly 12 or biopsy tool 84 extending therefrom, after performing one of the navigation procedures described herein. Fig. 46B is a virtual fluoroscopic image depicting the same patient and displaying a target 68 thereon. The virtual fluoroscopic image is generated from the same CT data used in both the planning and navigation methods described above. The CT data is manipulated to create a computer model of a fluoroscopic image of the patient. The target 68 is the same target 68 identified in the planning phase, and the location of the target 68 in the virtual fluoroscopic image corresponds to the location of the target identified by the clinician during planning.

**[00125]** The virtual fluoroscopic image and the live fluoroscopic image may be registered to one another. This may be done using, for example, one or more fiducial markers placed either prior to the CT scan and that will also appear on the fluoroscopic image, or by identifying landmarks within the physiology that may act as fiducial markers (e.g., curvature and spacing of the rib cage). The two images, the live fluoroscopic image and the static virtual fluoroscopic image provide the clinician with the ability to compare placement of the extended working channel 90 and the ablation assembly 12 with the location of the target 68. This may be done in either a side by side comparison mode as shown in Figs. 46A and 46B. For example, in Fig. 46A, the live fluoroscopic image, a mass 67 that has been identified as the target 68 during the planning phase may only be lightly visible under fluoroscopy, often soft tissue is difficult to discern in fluoroscopic images, but by comparing the location of the extended working channel 90 and the ablation assembly 12 as

shown in Fig. 46A to the location of the target 68 shown in Fig. 46B, the necessary adjustments to positioning for proper ablation can be readily ascertained.

**[00126]** Alternatively, where the live and the virtual fluoroscopic images are registered to one another, comparison may be made by overlaying the virtual image (Fig. 46B) over the live image (Fig. 46 A) such that a composite image is created. This composite image then depicts the relative position of the target 68 to the placement of the ablation assembly 12 and extended working channel 90. By continuing live fluoroscopy visualization of the placement of the extended working channel 90 and/or the ablation assembly 12, or a biopsy tool 84 into the target 68 is enabled, thus enabling the clinician to actually see the proper placement into a target 68 in real time using a combination of a live fluoroscopic image and an overlaid virtual fluoroscopic image. Once placement of the ablation catheter 14 is confirmed within the target 68, microwave energy can be transmitted to the ablation catheter 14 to treat the target 68.

**[00127]** Following treatment of the target 68, one of the aforementioned imaging modalities may be utilized to confirm that a suitable ablation zone has been formed around the target 68 and to determine whether additional application of energy are necessary. These steps of treating and imaging may be repeated iteratively until a determination is made that the target has been successfully ablated. Moreover, the methodology described above using the imaging modalities to confirm the extent of treatment and determine whether additional application of energy is necessary can be combined with the radiometry and temperature sensing techniques described above to both confirm what is depicted by the imaging modality and to assist in determining treatment cessation points.

**[00128]** In an embodiment, such as, for example, when the target 68 is relatively close to a distal end of the bronchoscope 72, the extended working channel 90 may be removed (Fig. 14), or not used at all, and the bronchoscope 72 kept in place to visually guide access



tools and the assembly 12 including the ablation catheter 14 to target 68. Alternately, the extended working channel 90 and accompanying access tools may be placed without use of the bronchoscope 72, or the bronchoscope 72 can be removed after placement of the extended working channel 90 in combination with access tools at the target 68 and kept in place and the assembly 12 including the ablation catheter 14 can be extended through the extended working channel 90 to treat the target 68.

**[00129]** As noted above, temperature monitoring system 3 can be used to determine and monitor temperature of the target tissue 68, ablation zone size, etc. In embodiments, the temperature monitoring system 3 can be incorporated into one or more components (e.g., software graphical interface 64) that are configured for use with the system 10.

**[00130]** In embodiments, placement of the extended working channel 90 and/or the ablation catheter 14 within the luminal network may be accomplished without the use of the aforementioned pathway planning and pathway navigation methods. In this instance, computer tomography, ultrasound and/or fluoroscopy may be utilized to facilitate positioning the extended working channel 90, and/or access tools and/or the ablation catheter 14 within the luminal network.

**[00131]** In embodiments, the distal radiating section 42 may be covered by a temperature sensitive "wax" material "W" that melts when energy is applied to the inner conductor 20, thereby absorbing heat from the distal radiating section 42 by changing phase.

**[00132]** Moreover, in place of fluid cooling the distal radiation section 42 may be frozen to create an ice formation therearound. When the distal radiating section is energized, the ice turns to gas which may result in high heat dissipation, which, in turn, cools the distal radiating section 42.

**[00133]** Further, in accordance with the instant disclosure, it may prove advantageous to utilize the ablation catheter 14 without the assembly 12. In this particular embodiment, the

extended working channel 90 may be modified to provide for fluid cooling of the ablation catheter 14, for example one of the aforementioned lumen and port configurations and a closed distal tip. As can be appreciated, one or more other modifications may also have to be made to the extended working channel 90 in order for the extended working channel 90 to function as intended herein.

**[00134]** Figs. 15A-15B illustrate an extending working channel 190 having a closed distal end and a modified catheter assembly 12 inserted therein. Rather than a closed distal end as shown in Fig. 1, the catheter assembly 12 has an open distal end. A space between the inner surface of the extended working channel 190 and the catheter assembly 12 establishes a fluid inflow lumen 119a. A fluid outflow lumen 119c is exposed by the opening of the distal end of the catheter assembly 12. The lumens 119a and 119c allow for cooling fluid to flow in the extended working channel 190 and catheter assembly 12 to cool an the ablation catheter 14 located within the catheter assembly 12. A cross section of the extended working channel 190 with modified catheter assembly 12 is shown in Fig. 16D. The catheter assembly 12 may optionally include a position sensor 96 such that the catheter assembly 12 acts as a locatable guide 86 (Fig. 12) to assist in the positioning of the extended working channel at a target 68. The extended working channel 190 may be formed to meet the flexibility criteria described above. Alternatively, the extended working channel may be placed as described above using a locatable guide 86. Thereafter, the locatable guide 86 may be removed and the extended working channel 190 kept in place. With the locatable guide 86 removed, the modified catheter assembly 12 and ablation catheter 14 may be positioned within the extended working channel 190 (Fig. 16A) and energized to form an ablation zone “AB” suitable for treating target 68 (Fig. 16B). Fig. 16C shows yet another optional configuration, where the ablation catheter 14 is placed into the extended working channel 190 without any assembly following placement of the extended working channel 190 and removal of the locatable guide 86.

Water may be circulated within the extended working channel 190 to cool the distal radiating section in a manner as described above.

[00135] As can be appreciated, a result of the flexible assembly 12 including the ablation catheter 14 being inserted endobrachially is that the likelihood of pneumothoraces occurring is greatly reduced by navigating through the luminal branches of the lung. Moreover, the ability of the system 10 to create a pathway to target tissue takes the guess work out of positioning the locatable guide, the extended working channel and the assembly 12 including the ablation catheter 14.

[00136] From the foregoing and with reference to the various figure drawings, those skilled in the art will appreciate that certain modifications can also be made to the present disclosure without departing from the scope of the same. For example, one or modifications may be made in the way of device delivery and placement; device cooling and antenna buffering; and sensor feedback. The following are a variety of non-limiting examples of such modifications considered within the scope of the present disclosure.

## **I. Device Delivery and Placement**

[00137] In accordance with the instant disclosure, various methods may be utilized to deliver the ablation catheter 14 and/or the extended working channel 90/190 into a desired location in the target tissue 68.

[00138] For example, to address the occurrence of bleeding within the patient as a result of biopsy or ablation, the bronchoscope may be employed to create tamponade; that is, the bronchoscope can be wedged into the bronchus to stop the bleeding at points the bronchoscope can reach. However, in accordance with the instant disclosure, the extended working channels 90/190 could be navigated to the target 68 and one or more expandable

members may be provided on the extended working channels 90/190 to create tamponade. The expandable member, e.g., a balloon, can be inflated to stop bleeding at these remote locations.

**[00139]** Specifically, Figs. 17 and 18 illustrate the extended working channels 90/190 including a balloon “B” that is positioned on an exterior surface of the extended working channels 90/190. The balloon “B” is initially in a deflated configuration (Fig. 17) for navigating the extended working channel 90/190 through a conductive airway and positioning the extended working channels 90/190 adjacent the target 68. Subsequently, the balloon is inflated for anchoring the extended working channel 90/190 in place and to create a tamponade (Fig. 18).

**[00140]** In the embodiment where the balloon “B” is provided on the extended working channel 90, one or more lumens may be provided on the extended working channel 90 and may be in fluid communication with the balloon “B” to provide one or more suitable fluids from the fluid source 32 to the balloon “B” to move the balloon “B” from the inflated configuration to the deflated configuration (and vice versa). Moreover, in this embodiment, the balloon “B” may be configured to control local lung properties which change with respiration. For example, the relative permittivity of deflated lung tissue at 2450 MHz is 48 and the relative permittivity of inflated lung tissue at the same frequency is 20; this large permittivity range makes it difficult to tune an antenna to a single frequency. It has been found through empirical testing that by adding the balloon “B,” the lung can be locally isolated during an inflated or deflated state to produce one or more desired properties, e.g., electrical and thermal. Specifically, thermal conductivity changes with inflation and deflation of the lungs. For example, if local respiration was stopped with the lung inflated and the ablation catheter 14 was matched to the target 68 with a relative permittivity of 45, heating can be focused thermally and electrically to the target 68. Likewise, if the lung were

fixed in a deflated configuration, more lung tissue could be thermally treated to produce additional margin around the target 68.

**[00141]** Figs. 19A-19B illustrate an ablation catheter 214 according to another embodiment of the present disclosure. Ablation catheter 214 is similar to ablation catheter 14. Accordingly, only those features unique to ablation catheter 214 are described in detail. An expandable balloon 252 is provided on a coaxial cable 236. The balloon 252 functions in a manner as described above with respect to the balloon 52. Unlike balloon 52, however, the balloon 252 is expandable (air/fluid pressure) and configured to provide the functions of the balloon “B” as described above.

**[00142]** One or more lumens (not shown) may be provided on the ablation catheter 214 and configured to receive one or more suitable fluids from the fluid source 32 to move the balloon 252 between the deflated and inflated configurations, see Figs. 19A-19B. Alternatively, the lumens 19a, 19c of the assembly 12 may be in fluid communication with the balloon 252 and configured to provide one or more suitable fluids from the fluid source 32 to the balloon 252 to move the balloon 252 between inflated and deflated configurations. As can be appreciated, other methods and/or devices may be utilized to move the balloon 252 between inflated and deflated configurations.

**[00143]** Fig. 20 illustrates an extended working channel 290 according to another embodiment of the instant disclosure. In this embodiment, a closed distal tip 291 is energizable for penetrating tissue “T.” Specifically, an electrode 292 may be coupled at the distal tip 291 of the extending working channel 290. The electrode 291 may be in electrical communication with the energy source 16 via one or more leads or wires 293 that extend within the extended working channel 290. The electrode 292 may be configured for monopolar operation. A return pad (not shown) may be positioned on a patient and utilized as a return electrode. Alternatively, a second electrode (not shown) can be provided on the

extended working channel 290 to create a bipolar electrode configuration. In use, when the electrode 291 is energized, the distal tip 291 may be utilized to penetrate tissue to facilitate positioning the extended working channel 290 adjacent target tissue.

**[00144]** Fig. 21 illustrates an extended working channel 390 according to another embodiment of the instant disclosure. The extended working channel 390 includes a closed distal end and at least one water filled lumen or chamber (e.g., a lumen 319a of the cooling water loop utilized to cool the distal radiating section 42) that includes a piston assembly 321 including a base 323 and a needle 325 extending distally from the base and through an aperture (not shown) at a distal end of the lumen 319a. A seal (not shown) may be provided within the aperture of the lumen 319a to maintain the pressure within the lumen. An optional seal 327 may be provided at a distal tip of the extended working channel 390 and may be configured to maintain a fluid tight seal. The piston assembly 321 is movable within the lumen 319a to move the needle 325 from a retracted configuration to an extended configuration (shown in phantom in Fig. 21) through the seal 327. In the extended configuration, the needle 325 may be utilized to anchor the extended working channel 390 to tissue and/or penetrate tissue.

**[00145]** In use, water may be provided to the extended working channel 390 to move the needle 325 to the extended configuration for penetrating tissue; this may be done prior to energizing the distal radiating section 42 and/or when the distal radiating section 42 is energized. Thus, the cooling water loop serves a dual purpose (cooling of the distal radiating section and extension of the needle 325) and may eliminate the need for a separate push/pull member or sheath.

**[00146]** Fig. 22 illustrates an extended working channel 490 according to another embodiment of the instant disclosure. The extended working channel 490 includes an open distal end and an electrode 492 operably coupled thereto. Electrode 492 is similar to the

electrode 292 illustrated in Fig. 20. Unlike electrode 292, however, electrode 492 may extend along an outer peripheral surface of the extended working channel 490. Additionally, a pair of upright electrode extensions 494a, 494b may be provided on the electrode 492 and configured to function as a monopolar pencil to treat tissue.

[00147] The electrode 492 may be in electrical communication with the energy source 16 via one or more leads or wires 493 that extend within the extended working channel 490. The electrode 492 may be configured for monopolar operation. A return pad (not shown) may be positioned on a patient and utilized as a return electrode. Alternatively, a second electrode (not shown) can be provided on the extended working channel 490 to create a bipolar electrode configuration. In use, after tissue has been ablated, the upright extensions 494a, 494b may be utilized to transmit microwave energy (or RF) to neighboring tissue. After the tissue has been treated, the upright extensions 494a, 494b may be utilized to scrape the electrosurgically treated tissue. As can be appreciated, having the electrode 492 on the extended working channel 490, allows a user to treat tissue with the electrode 492 while leaving ablation catheter 14 in place within the extended working channel 490.

[00148] Fig. 23 illustrates a head-up display 81 (e.g., Google glasses) that communicates with the guidance system for providing a virtual internal image to a clinician. The virtual internal image includes information pertaining to planning the pathway to the target 68 and for guiding and navigating one of the aforementioned tools, extended working channels and the locatable guides through the lungs of a patient "P." The head-up display 81 may include one or more electromagnetic sensors 83 for providing a position of the head-up display 81 relative to a patient "P" for projecting the virtual internal image into a clinician's view of the patient "P" with the proper orientation.

## II. Device Cooling and Antenna Buffering

[00149] The following embodiments are configured to protect a patient from unintended heating from the coaxial cable 36 and/or the distal radiating section 42 and/or configured to provide dielectric buffering to the distal radiating section 42.

[00150] Figs. 24-26 illustrate an assembly 512 according to an embodiment of the instant disclosure. Assembly 512 is similar to assembly 12. Accordingly, only those features unique to assembly 512 are described in detail.

[00151] A partition 511 is provided within the housing 523 adjacent the distal end of the assembly 512 to provide a chamber 514 that is configured to isolate the distal radiating section 542 from the rest of the coaxial cable 536. A dielectric (e.g. ceramic, hydrogel, etc.) 513 is provided within the chamber 514 to cover the distal radiating section 542 and is configured to cool the distal radiating section 542 and the inner conductor 540 when contacted by fluid being transmitted through the lumens 519a, 519c and into contact with the partition 511. In accordance with the instant disclosure, the dielectric 513 is capable of withstanding heat without changing properties to buffer the distal radiating section 542 and create a separate active cooling system around the coaxial cable 536. This reduces, if not eliminates, phase changes around the distal radiating section 542 during activation thereof and may reduce the active cooling requirements on the coaxial cable 536.

[00152] Fig. 27 illustrates an assembly 612 according to an embodiment of the instant disclosure. A plurality of ceramic elements 613 extend at least partially along the coaxial cable 636 and form a nested configuration. The ceramic elements 613 serve as a heat sink to cool a distal radiating section 642 and an inner conductor 640. The ceramic elements 613 may be actuatable to move from a relaxed configuration wherein the plurality of ceramic elements 613 are spaced apart from one another (as shown in Fig. 27) to allow the coaxial cable 636 to flex, to a compressed configuration wherein the ceramic elements 613 are



moved towards one another to increase cooling of the distal radiating section 642 and the inner conductor 640, and to secure the position of the location of the assembly. A pair pull wire 617 operably couples to the ceramic elements 613 and is configured to move the ceramic elements 613 to the compressed configuration.

**[00153]** Fig. 28 illustrates an extended working channel 790 according to an embodiment of the instant disclosure. The extended working channel 790 functions as a structural thermal sink that is configured to sink heat either by itself or in conjunction with a cooling fluid. In the embodiment illustrated in Fig. 28, the extended working channel 790 is formed from a material that is a good thermal conductor to pull away heat from the distal radiating section 742. A heat sink 791 is operably coupled to a proximal end 793 of the extended working channel 790. For example, lumens 719a, 719c (shown in phantom) extend to a proximal end of a balun 752 to cool the proximal end 793 of the extended working channel 790. In this particular embodiment, the fluid may flow up to the proximal end of the balun 752 and turn around; this would keep the extended working channel 790 cool at the proximal end 793. Conduction is utilized to move cool air through a distal end of the extending working channel 790 distal to the balun 752 to the cooled proximal end 793 of the extended working channel 790 proximal to the balun 752. Additionally or alternatively, a ceramic paste “CP” may at least partially cover the distal radiating section 742 and may serve as a dielectric buffer to provide static cooling of the distal radiating section 742. Use of the ceramic paste “CP” may allow the extended working channel 790 to be formed without the lumens 719a, 719c, which, in turn, would allow the extended working channel 790 to remain flexible while providing static cooling and/or buffering.

**[00154]** Fig. 29 illustrates an extended working channel 890 according to an embodiment of the present disclosure. By using a vacuum pump to pull water through a the extended working channel 890, the boiling point of the water circulating through the

extended working channel 890 can be lowered. At this pressure water boils at about body temperature and the boiling water will rapidly vaporize and the change of phase results in cooling of the fluid and components adjacent to it and create an additional cooling effect for an ablation catheter 814. To this end, a vacuum pump 33 operably couples to a fluid return port (not shown) on the extended working channel to pressurize a fluid circulating through lumens 819c for lowering a boiling point of the fluid circulating through the lumens 819c. In embodiments, an air-mist mixture may be utilized as the cooling medium and circulated through the lumens 819a, 819c; this embodiment takes advantage of the large energy needed to change phase from liquid to vapor, even where temperature remains constant.

**[00155]** Fig. 30 illustrates an extended working channel 990. The extended working channel 990 may include a two lumen configurations (not explicitly shown). In this embodiment, one lumen is dedicated for communication with a fluid intake port (not shown) of the extended working channel 990 and one lumen dedicated to support the ablation catheter 914. Unlike the previous disclosed lumen configurations, the fluid intake port and the lumen are configured for an open loop cooling protocol. The open loop cooling protocol may improve fluid flow within the extended working channel 990. Moreover, energy delivery and microwave energy absorption may be improved by hydrating the target. Further, the open loop cooling protocol may be combined with expandable balloon “B” and/or expandable balloon 252 to lock the extended working channel 990 in place, which, in turn, may increase dielectric buffering around the distal radiating section 942.

**[00156]** In embodiments, the extended working channel 990 may include a fluid return port and a corresponding third lumen that is configured to provide suction for suctioning the cooling fluid dispensed from the extended working channel 990; this may provide a user with the ability to perform a Bronchoalveolar Lavage (BAL) at the end of the microwave ablation

procedure, i.e., by stopping fluid flow and sucking the fluid back to retrieve one or more tissue samples.

**[00157]** Figs. 31-32 illustrate an extended working channel 1090 according to another embodiment of the present disclosure. In this embodiment, the extended working channel 1090 may be utilized as a thermal and electrical control by extending the distal radiating section 1042 through a seal structure 1091 that is provided at a distal end of the extended working channel 1090. The seal structure 1091 is configured for sealed engagement with the distal radiating section 1042 to maintain a fluid tight seal when the distal radiating section 1042 is extended therethrough for treating tissue.

**[00158]** Fig. 33 illustrates an extended working channel 1190 according to another embodiment of the present disclosure. In this embodiment, no flow fluid buffering is utilized to cool the distal radiating section 1142. With this purpose in mind, a chamber 1191 is provided at a distal end of the extended working channel 1190 and is not in fluid communication with lumens 1119a, 1119c. The chamber 1191 surrounds the distal radiating section 1142 and configured to receive a high boiling point liquid (e.g., water, saline, etc.) being therein to cool the distal radiating section 1142. In this embodiment seal members 1121a, 1121b may be optionally provided at distal ends of the lumens 1119a, 1119c and are configured to maintain the high boiling point liquid within the chamber 1191. The higher boiling point liquid in chamber 1191 absorbs heat generated by the distal radiating section 1142 and transfers it to the fluid circulated through lumens 1119a and 1119c.

**[00159]** Figs. 34 and 35 illustrate an extended working channel 1290 according to another embodiment of the instant disclosure. In this embodiment, a heat sink 1291 having an accordion configuration is coupled to a distal end of the extended working channel 1290. The heat sink 1291 is configured to couple to the distal radiating section 1242 via one or more suitable coupling methods when the distal radiating section 1242 is extended through

the extended working channel 1290. In the illustrated embodiment, for example, a seal (not shown) may be provided at a distal end of the extended working channel 1290 and may be configured to releasably engage (via a press or friction fit) the distal radiating section 1242 as the distal radiating section is extended from the extended working channel 1290 (Fig. 34). As the heat sink heats, it begins to extend distally away from the extended working channel 1290 bringing the distal radiating section 1242 coupled thereto with it. In the extended configuration, the distal radiating section 1242 will have been moved away from surrounding tissue, which, in turn, may reduce collateral damage to the surrounding tissue (Fig. 35).

**[00160]** Figs. 36A and 36B illustrate an ablation catheter 1314 according to an embodiment of the instant disclosure. In the embodiment illustrated in Figs. 36A and 36B, a heat sink is created with the walls of a lung (“LW”), which, typically, include a temperature in the range of about 37°C. To this end, a thermally conductive balloon 1321 is positioned adjacent a distal radiating section (not explicitly shown) of the ablation catheter 1314 and is expandable (via one or more of the aforementioned lumen configurations) to dissipate heat from the distal radiating section into the wall of a lung “LW” of patient. Specifically, when the distal radiating section is energized, the conductive balloon 1321 is inflated and expands into contact with the wall of the lung “LW,” which, in turn sinks the heat absorbed by the thermally conductive balloon 1321.

**[00161]** Alternatively, a plurality of thermally conductive fins 1323 (Figs. 37A-37B) may be positioned adjacent the distal radiating section. In this embodiment, the fins 1323 are expandable to absorb and dissipate heat from the distal radiating section when the distal radiating section is energized. In the embodiment illustrated in Figs. 37A-37B, the fins 1323 are formed from a shape memory metal that is configured to move to an expanded configuration when heated as a result of the distal radiating section being energized. Once expanded, airflow may be introduced into the bronchus and across the plurality of thermally

conductive fins 1323 to cool the conductive fins 1323, which, in turn, will cool the distal radiating section.

[00162] Fig. 38 illustrates an extended working channel 1490 according to an embodiment of the instant disclosure. In this embodiment, the extended working channel 1490 includes a proximal end 1491 including a diameter “D1” that is larger than a tapered distal end 1492 that includes a diameter “D2.” The larger diameter D1 of the proximal end 1491 allows for more cooling for a given length of extended working channel 1490. In accordance with the instant disclosure, the diameter “D1” of the proximal end 1491 should be large enough to minimize coolant pressure drop but small enough to fit in airways.

[00163] Figs. 39A-39B illustrate an ablation catheter 1514 according to an embodiment of the instant disclosure. Specifically, a balloon 1515 may be positioned adjacent the radiating section 1542 (and/or the balun not shown) and may be in fluid communication with the lumens (not explicitly shown) within the ablation catheter 1514. The balloon 1515 is movable from a deflated configuration (Fig. 39A) for extending the ablation catheter 1514 through an extended working channel 1590 to an inflated configuration (Fig. 39B). In the inflated configuration, the balloon 1515 may serve to expand a buffering volume, i.e., there is more volume to heat. Moreover, the balloon 1515 may be configured to anchor the distal radiating section 1542 in an airway of the lung. Further, the balloon 1515 may be configured to increase flow rate around the balun of the ablation catheter 1514.

### **III. Sensor Feedback**

[00164] The following embodiments are configured to provide sensor and/or visual feedback to the system 10 or physician relating device placement (e.g., the extended working channel 90/190, the catheter assembly 12 and/or the ablation catheter 14), tissue environment, ablation progress, device performance, safety, etc.

**[00165]** In accordance with the instant disclosure, one or more feedback mechanisms may be utilized with the instant disclosure. For example, Figs. 40A-40B illustrate various fiducial markers that may be detectable by the system 10. Any of the aforementioned extended working channels that include an open distal end, e.g., the working channel 90, may be utilized as a conduit for the placement of one or more fiducial markers within the patient following removal of the locatable guide 86. These markers can be used for a variety of purposes including identifying tumors and lesions for follow-up analysis and monitoring, to identify locations that biopsy sampling has been undertaken, and to identify the boundaries or the center of a tumor or lesion for application of treatment. Other uses will be understood by those of skill in the art as falling within the scope of the present disclosure.

**[00166]** In embodiments, the fiducial markers may be formed from a shape memory alloy “SM.” In this embodiment, the fiducial markers “SM” are configured to change shape when heated to a predetermined temperature. Additionally or alternatively, the fiducial markers may be formed from poloxamers “PM.” Poloxamers can be transformed from liquid to solid using energy from the distal radiating section of the ablation catheter, e.g., distal radiating section 42. Once in the body, the fiducial markers “PM” cool to body temp and transform back to liquid and are dissolved in the bloodstream. In solid form, the fiducial markers “PM” may be visible under CT, ultrasound, and other imaging modalities to reveal the real time growth of the ablation zone “AZ.”

**[00167]** Fig. 41 illustrates another feedback mechanism that may be utilized with the system 10. In this embodiment, a guide wire 73 that is positionable within one of the aforementioned extended working channels (e.g., the extended working channel 90) and deployable therefrom may be utilized for measuring a temperature of the aforementioned distal radiating sections (e.g., distal radiating section 42). The guide wire 73 includes at least one thermocouple 75 at a distal end thereof. The thermocouples 75 may be configured to

capture temperature measurements when deployed from the extended working channel. The thermal couples 75 may be in communication with a microcontroller of the energy source 16 to monitor rate of change of the temperature of or surrounding the distal radiating section 42; the rate of change can be analyzed to correlate with a specific ablation size. In embodiments, the guide wire 73 may be utilized to deploy the ablation catheter 14 from the extended working channel 90.

**[00168]** Figs. 42-43 illustrate another feedback mechanism that may be utilized with the system 10. In the embodiment illustrate in Fig. 42, the system 10 is capable of detecting placement of an ablation catheter 1642 in healthy vs. tumor tissue or if bleeding occurs along the ablation catheter 1642. With this purpose in mind, one or more electrodes 1641 (two electrodes 1641 shown in Fig. 42) are provided adjacent a distal radiating section 1642 and are configured to detect data pertaining to the target tissue prior to, during or after activation of the distal radiating section 1642. The data pertaining to tissue may include electrical properties of the tissue, e.g., RF impedance.

**[00169]** In embodiments, the electrodes 1641 can be utilized to capture dielectric measurements of the surrounding tissue to ensure placement in tumor tissue. The amount and type of buffering of the distal radiating section 1642 will play a role in how well the electrodes 1641 can capture these measurements. With either of the RF or dielectric measurement types, a controller 17 (or another system 23, e.g., a laptop) connected to the ablation catheter 1614 will be needed to capture and analyze the data to interpret to the user. After the data is analyzed, the controller 17 provides the relevant information to a user, e.g., on a display 37.

**[00170]** In embodiments, the controller 17 may be configured to perform S-parameter (Fig. 43) analysis between input and output ports of the microwave energy source. In this embodiment, the S-parameter analysis is utilized to determine ablation size “AZ”, to control

operation of the energy source 16 and/or to detect damage to the distal radiating section 1642 in real-time.

[00171] In embodiments, one or more sensor configurations may be utilized with the system 10. For example, a hydration sensor “HS” (see Fig. 43 for example) may be utilized to measure the water content of the tissue at some distance from distal radiating section 42 to monitor ablation progress and/or completion. In this instance, the extended working channel 90 may be utilized to position the “HS” at a predetermined point away from where the distal radiating section 42 is going to be positioned. As moisture is driven out of the tissue, the sensor “HS” tracks the rate of change and can tell the user when the ablation is complete. Dielectric properties can be directly correlated with hydration levels of the tissue.

[00172] Moreover, one or more fiber optic cables “FC” may through the extended working channel 90 for positioning adjacent to target tissue for providing a visual perspective of the target tissue to a clinician. Alternately, the fiber optic cable “FC” may be provided adjacent to the distal radiating section 42 (see Fig. 5 for example). In this embodiment, one or more lenses (not shown) may be provided adjacent to the distal radiating section 42 and coupled to a distal end of the fiber optic cable “FC.” Further, one or more force sensor “FS” configured to provide feedback on force being applied by the distal radiating section 42 to penetrate tissue. In this instance, the force sensor “FS” may be operably coupled adjacent the distal radiating section (see Fig. 5 for example).

[00173] In embodiments, one or more chemical sensor “CS” may be configured to detect one or ore chemicals of tissue prior to, during or after activation of the distal radiating section 42 (see Fig. 5 for example). In this embodiment, the chemical sensor “CS” may be in operable communication with the microcontroller 17 that is configured to detect chemicals associated with the target tissue, e.g., acids and proteins. The chemicals detected may be



correlated to a progression of thermal ablation growth and stored in one or more data look-up tables (not shown) that is accessible to the microcontroller 17.

**[00174]** Fig. 44 illustrates a method of placement configuration for various sensor configurations. Specifically, alternate airways may be utilized to deploy sensors (e.g., acoustic, thermocouples, electrical sensors, etc). In one particular embodiment, the ablation catheter 14 may be extended through the extended working channel 90 and positioned in between two opposing sensors, e.g., acoustic sensors “AS” that are positioned in opposite airways. During operation of the distal radiating section 42, a ping across the airways can be generated to measure tissue properties, e.g., measure impedance, dielectric or temperature.

**[00175]** Fig. 45 illustrates another feedback mechanism that may be utilized with the system 10. In this embodiment, two antennas for ablation (e.g., procedural/completeness) monitoring are provided, a sensor patch 1840 and a distal radiating section 1842 of an ablation catheter 1814 (shown not positioned within an extended working channel for clarity). Sensor patch 1840 is positionable on a patient and configured to calibrate the ablation catheter 1814 prior to treating tissue and determine when the tissue has been adequately ablated. The sensor patch 1840 is in operable communication with controller 17 configured to monitor the amount of power received by the sensor patch 1840 as the distal radiating section 1842 is energized. The graph indicates received power at the sensor patch 1840 during both calibration (points A-B) and an ablation cycle (points C-D). The calibration cycle baselines transmission path. As ablation progresses, transmission path between distal radiating section 1842 and sensor patch 1840 becomes less lossy due to desiccation resulting in increasing received power. Ablation completeness is determined by amount of increased power received above calibration. For example, 1.5 cm ablation zone “AZ” increases power to sensor patch 1840 by approximately 15%. In an embodiment, when

the power at the sensor patch 1840 reaches the calibration level or surpasses the calibration level, the microcontroller 17 automatically shuts power off to ablation catheter 1814.

[00176] While several embodiments of the disclosure have been shown in the drawings, it is not intended that the disclosure be limited thereto, as it is intended that the disclosure be as broad in scope as the art will allow and that the specification be read likewise. Therefore, the above description should not be construed as limiting, but merely as exemplifications of particular embodiments. Those skilled in the art will envision other modifications within the scope and spirit of the claims appended hereto.

**WHAT IS CLAIMED IS:**

1. A microwave ablation system configured for use in a luminal network, comprising:
  - a microwave energy source;
  - a tool for treating tissue;
  - an extended working channel configured to provide passage for the tool; and
  - a locatable guide, translatable through the extended working channel, and configured to navigate the extended working channel adjacent a target.
2. The microwave ablation system according to claim 1, further including a bronchoscope configured to receive the extended working channel and for providing access to the luminal network.
3. The microwave ablation system according to claim 1, wherein the tool is a microwave ablation catheter comprising:
  - a coaxial cable connected at its proximal end to a microwave energy source and at its distal end to a distal radiating section, the coaxial cable including inner and outer conductors and a dielectric positioned therebetween, the inner conductor extending distally past the outer conductor and in sealed engagement with the distal radiating section; and
  - a balun formed in part from a conductive material electrically connected to the outer conductor of the coaxial cable and extending along at least a portion of the coaxial cable, the conductive material having a braided configuration and covered by at least one insulative material.
4. The microwave ablation system according to claim 3, wherein the extended working channel includes a closed distal end and a multi-lumen configuration configured to receive

the ablation catheter, the extended working channel further comprising a hub at a proximal end thereof, the hub including a fluid intake port and a fluid return port configured to provide respective ingress and egress of a coolant to and from the extended working channel for cooling the ablation catheter.

5. The microwave ablation system according to claim 4, further comprising an expandable member on an exterior of the extended working channel, the expandable member being movable to an inflated condition to create a tamponade when the microwave ablation catheter is positioned within the luminal network.

6. The microwave ablation system according to claim 5, wherein the expandable member is configured to control local properties of the luminal network.

7. The microwave ablation system according to claim 5, wherein the expandable member is configured to anchor the extended working channel when the extended working channel is positioned within the luminal network to prevent the extended working channel from moving out of position when the locatable guide or the microwave ablation catheter are moved therein.

8. The microwave ablation system according to claim 5, wherein the expandable member is in the form of a balloon.

9. The microwave ablation system according to claim 3, wherein the balloon is movable to an inflated condition to create a tamponade when the microwave ablation catheter is positioned within the luminal network.

10. The microwave ablation system according to claim 9, wherein the balun is configured to anchor the microwave ablation catheter when the microwave ablation catheter is positioned within the luminal network to maintain the microwave ablation catheter in a relatively fixed configuration.

11. The microwave ablation system according to claim 3, wherein one of the distal radiating section of the microwave ablation catheter and a distal tip of the extended working channel is selectively energizable to penetrate tissue.

12. The microwave ablation system according to claim 3, wherein the distal radiating section of the microwave ablation catheter is covered with a temperature sensitive wax configured to melt when the microwave ablation catheter is activated.

13. The microwave ablation system according to claim 3, wherein a piston including a needle is operably coupled to at least one fluid port of the extended working channel and is extendable from the distal end of the extended working channel for piercing tissue.

14. The microwave ablation system according to claim 1, wherein a distal end of the extended working channel is energizable for penetrating target tissue.

15. The microwave ablation system according to claim 14, wherein the distal end of the extended working channel includes at least one electrode extending at least partially along an outer peripheral surface of the extended working channel.

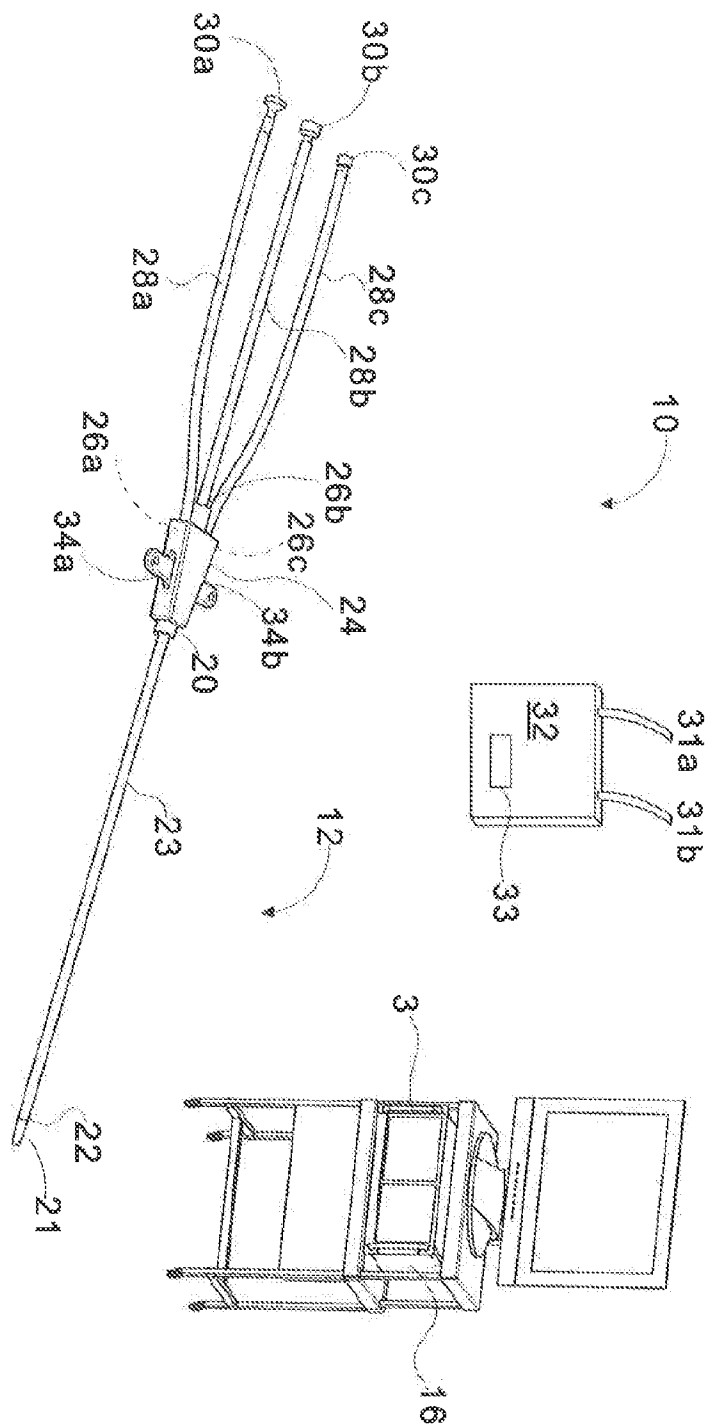
16. The microwave ablation system according to claim 14, wherein the at least one electrode is operable in a monopolar mode of operation.

17. The microwave ablation system according to claim 1, further including a navigation system for guiding at least one of a tool, the extended working channel or a locatable guide through the luminal network following a predetermined determined pathway.

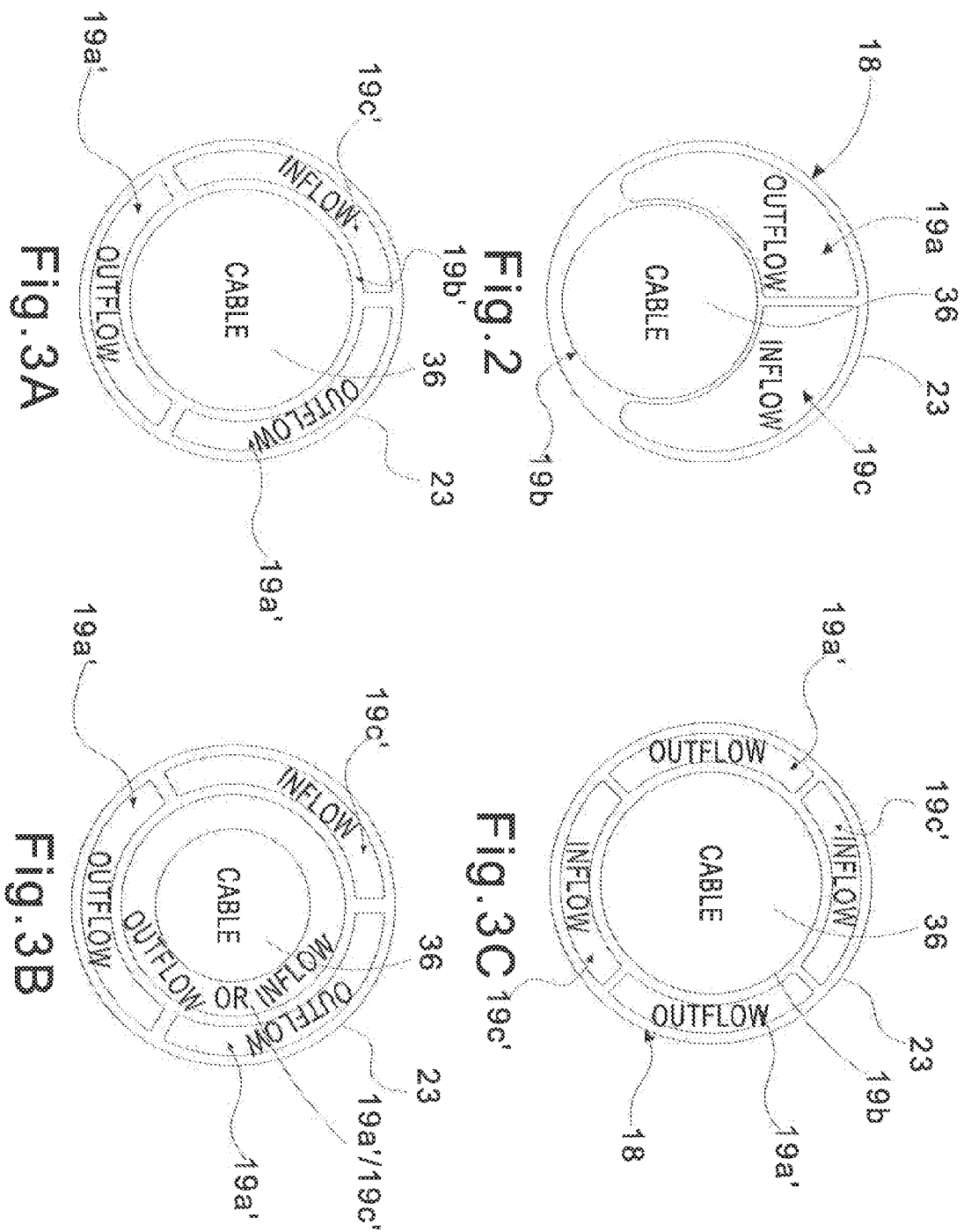
18. The microwave ablation system according to claim 17, wherein the predetermined pathway is generated based on computed tomographic (CT) data of the luminal network, and is displayed in a generated model.

19. The microwave ablation system according to claim 18, wherein the predetermined pathway is generated from CT data to identify a pathway to a target identified by a user in the CT data, and the pathway is generated for acceptance by the user before use in the navigation system.

20. The microwave ablation system according to claim 19, wherein the navigation system further includes a head-up display.



A 4x4 grid of 16 small squares, each containing a different geometric pattern of dots or lines. The patterns include various combinations of horizontal, vertical, and diagonal lines, as well as clusters of dots.





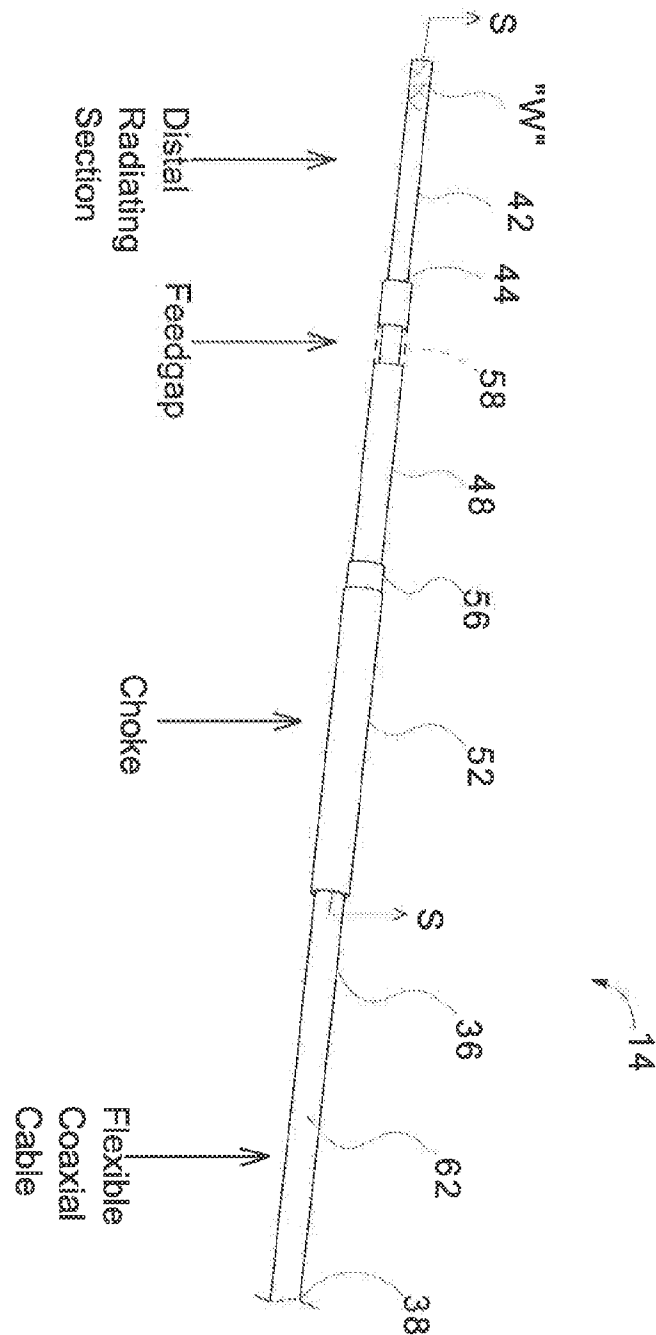


Fig. 4

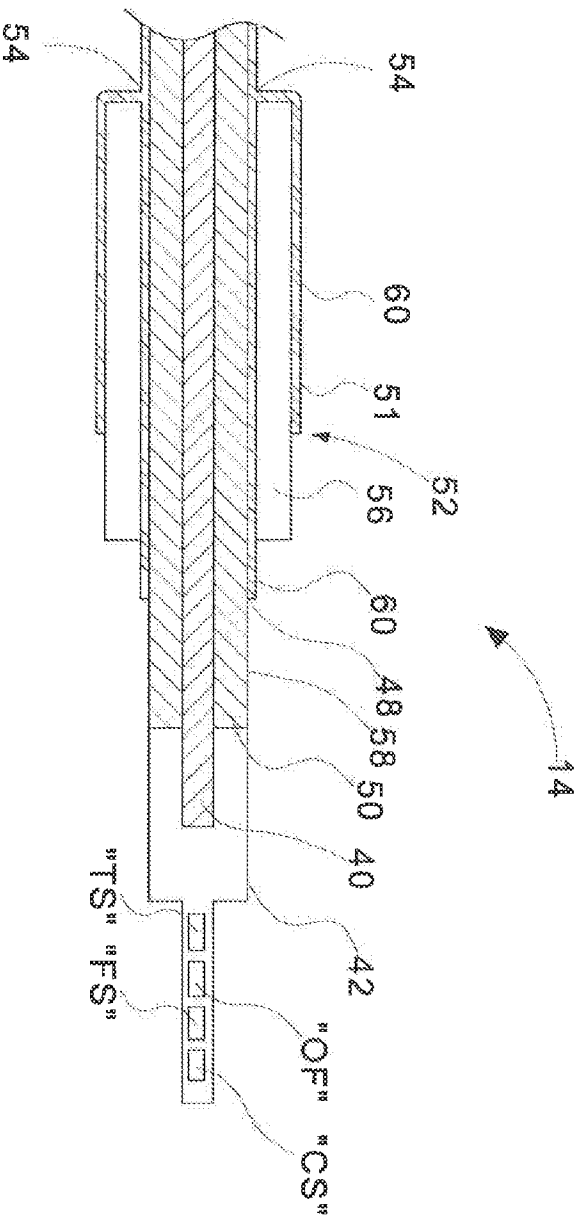
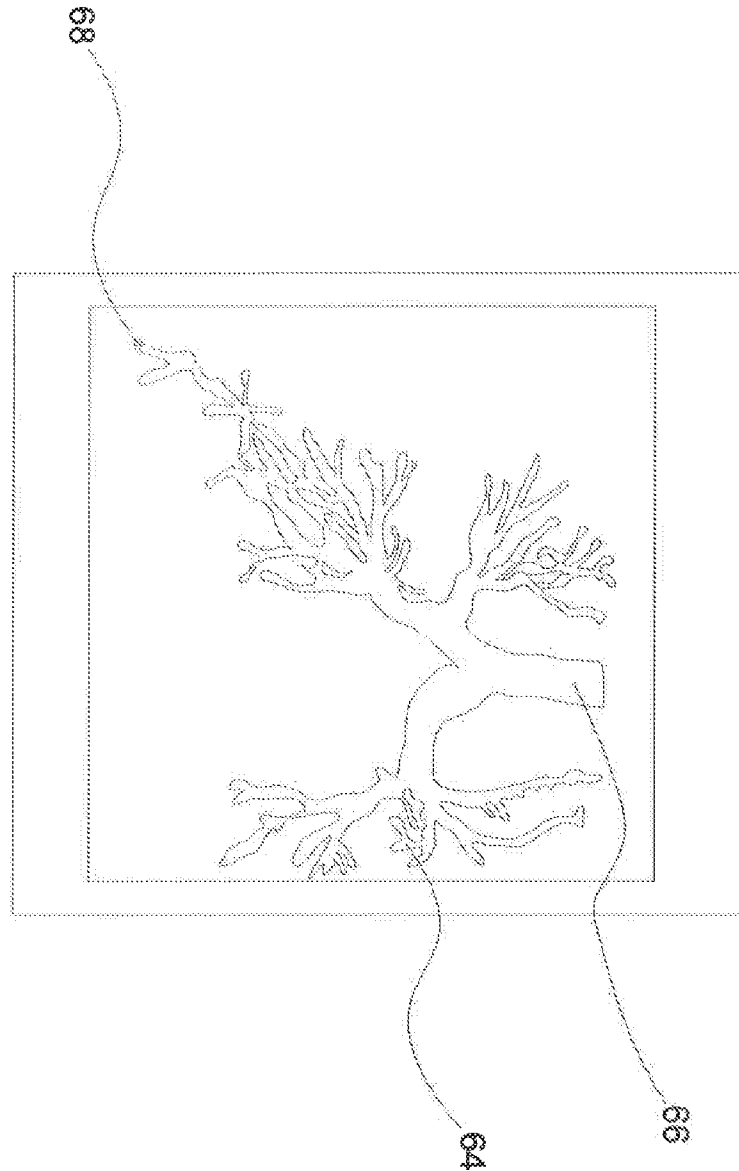


Fig. 5

Fig. 6



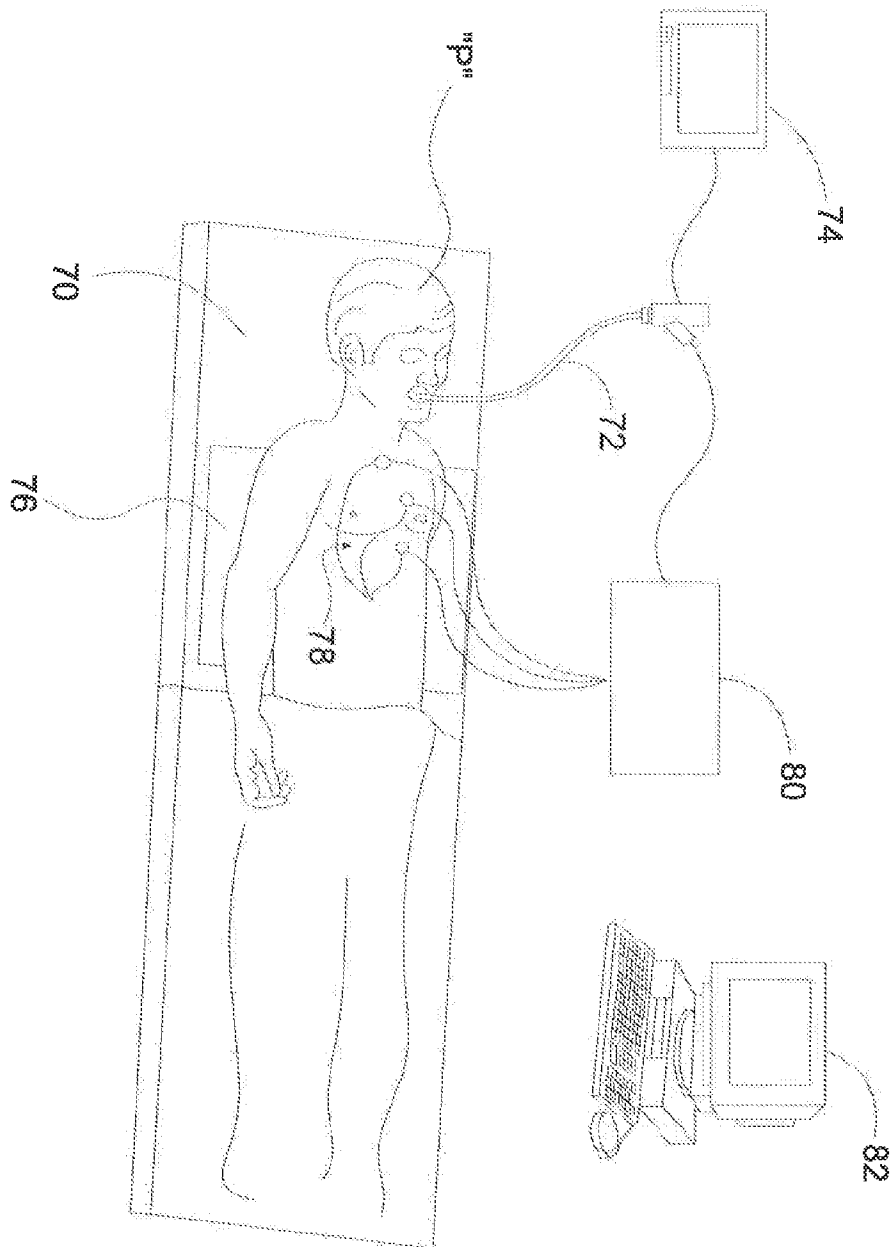


Fig. 7

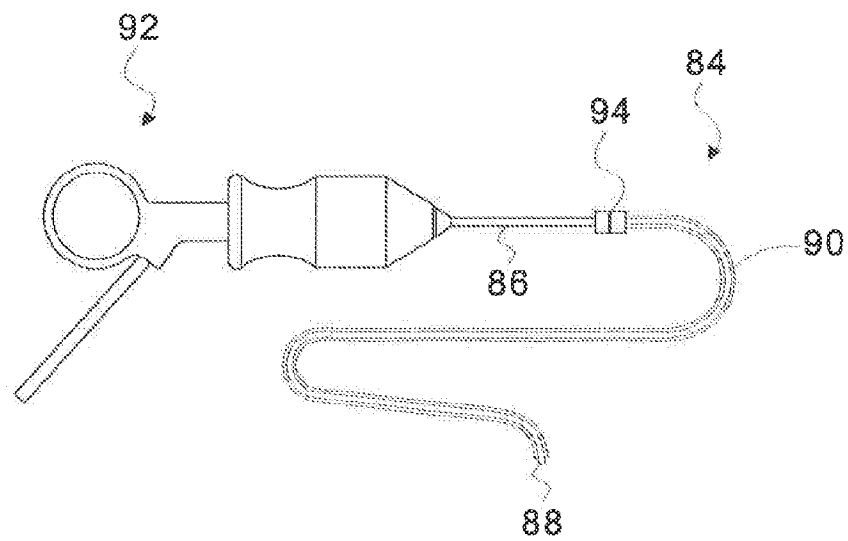


FIG. 8

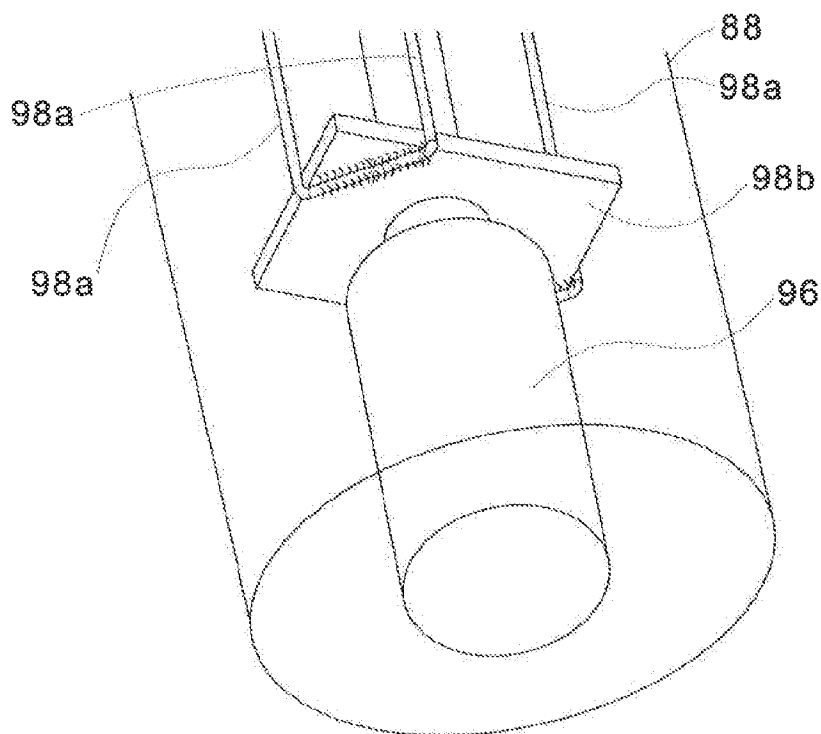


FIG. 9

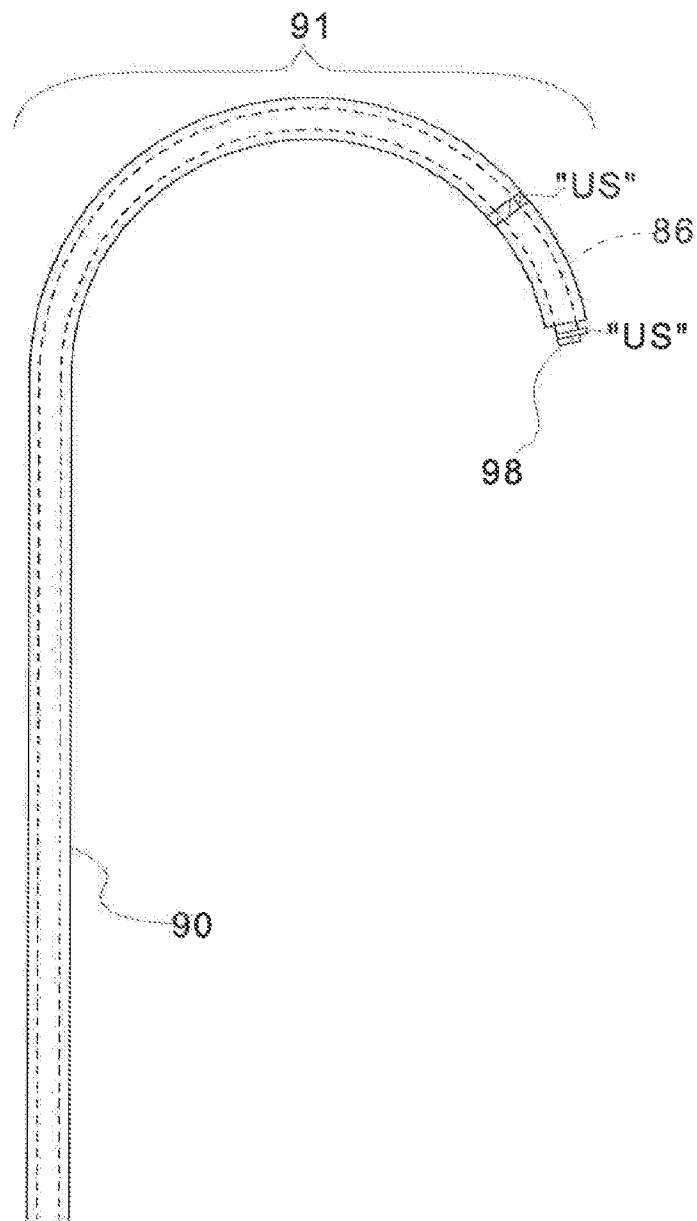


Fig. 10

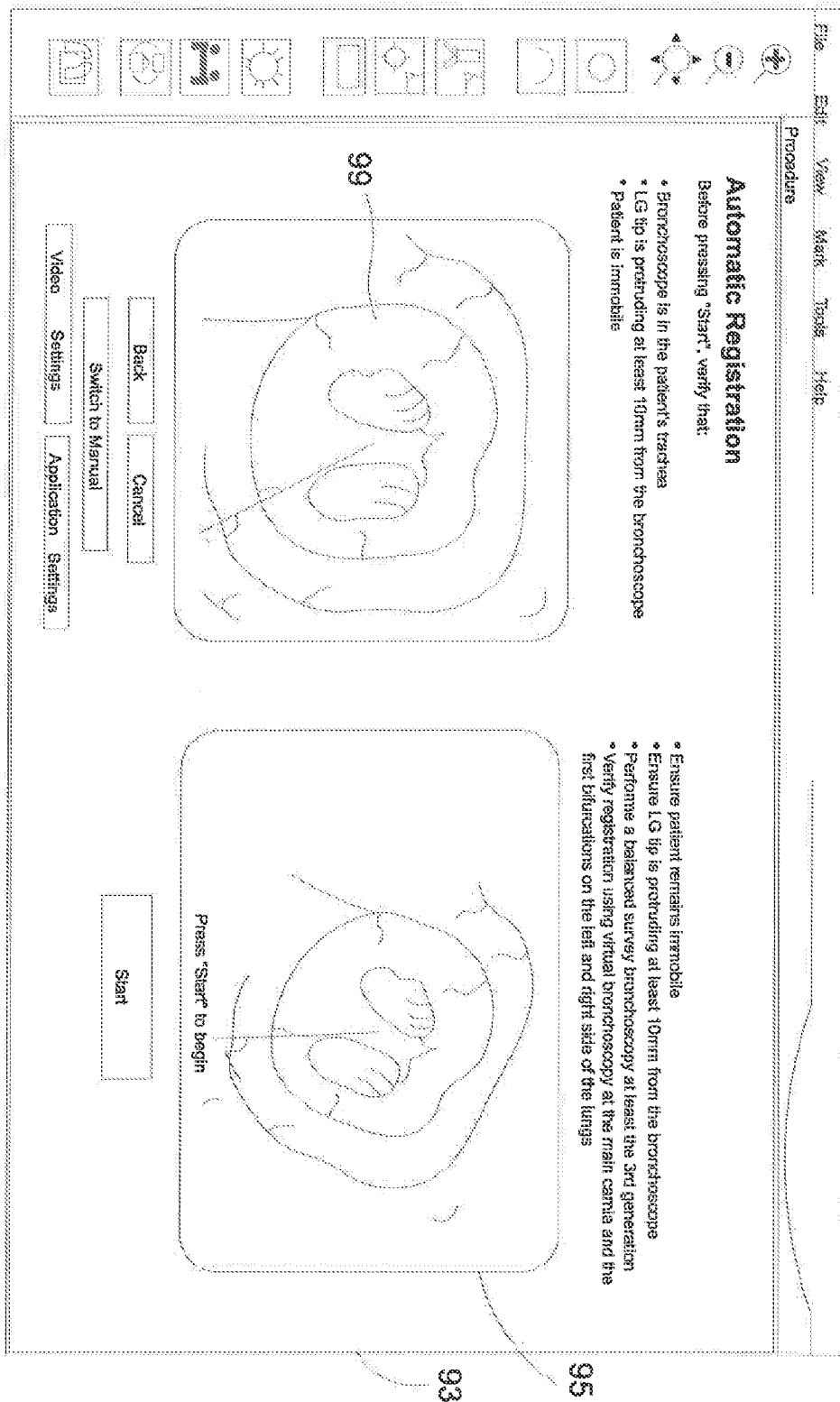


Fig. 11

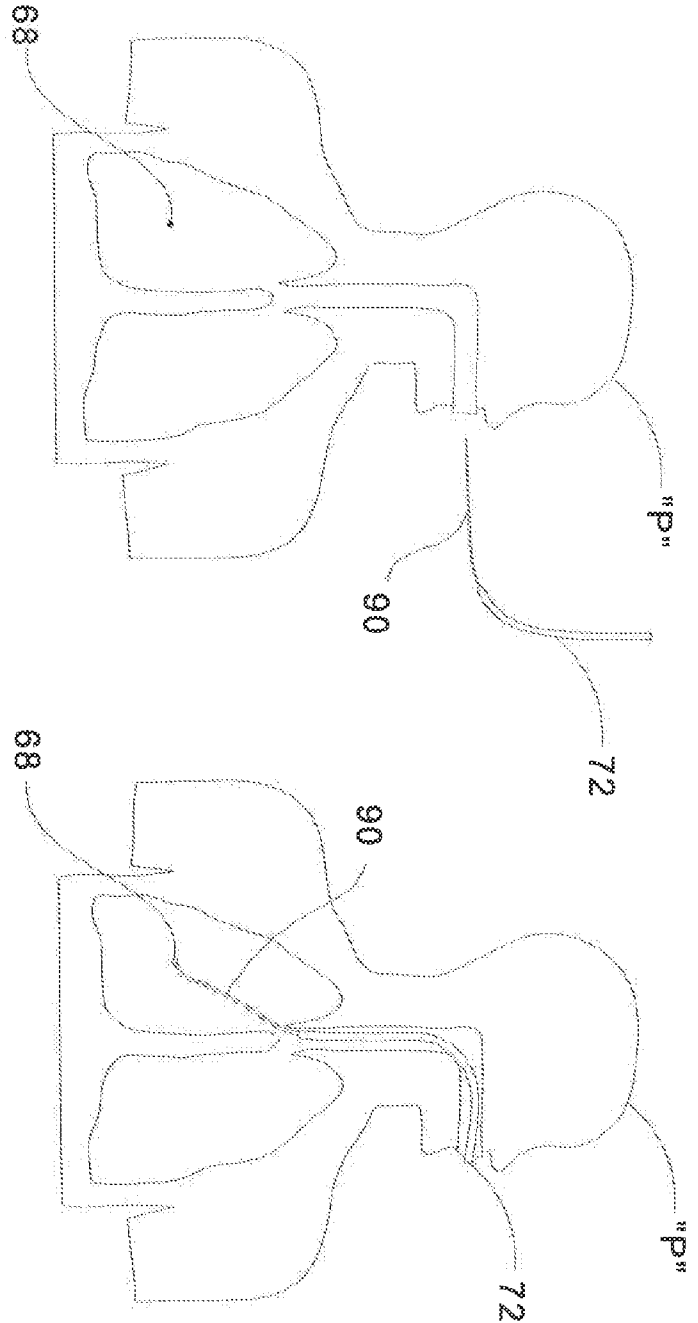


Fig. 12A

Fig. 12B

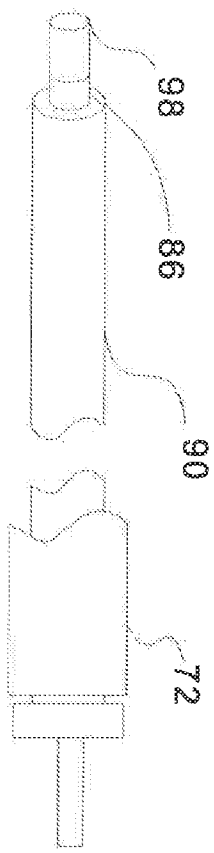


Fig. 12C



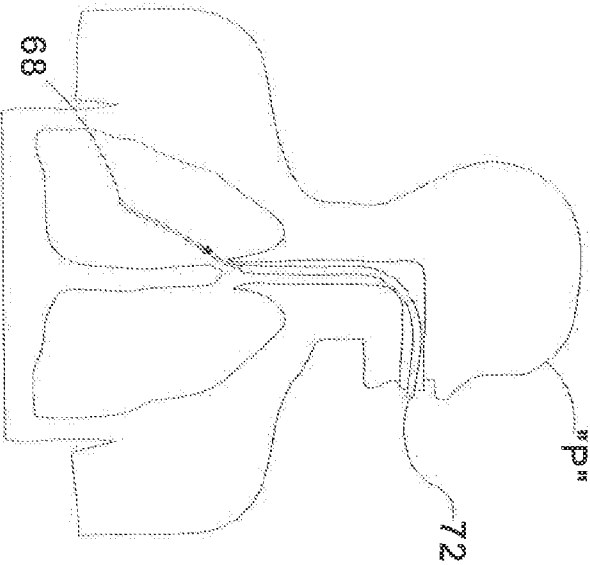


Fig. 13A

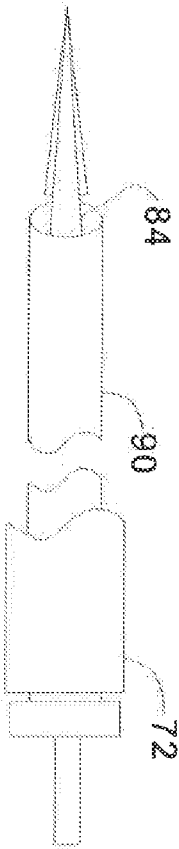


Fig. 13B

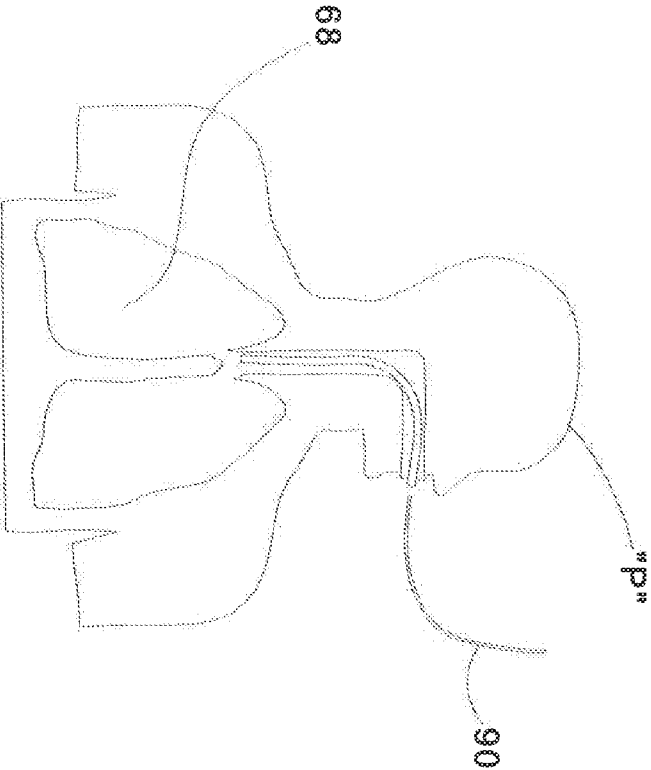


Fig. 14

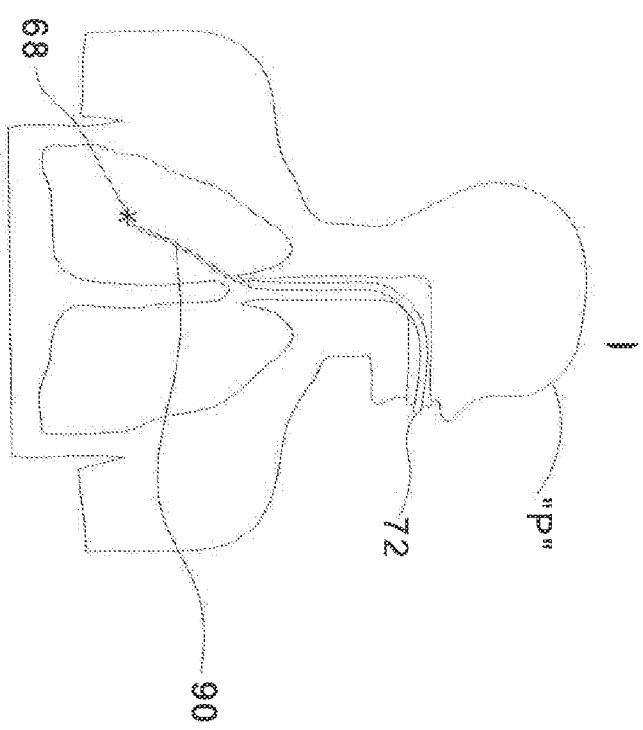


Fig. 15A

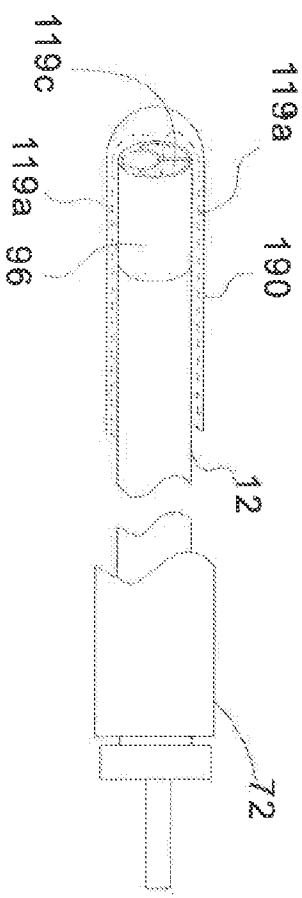


Fig. 15B

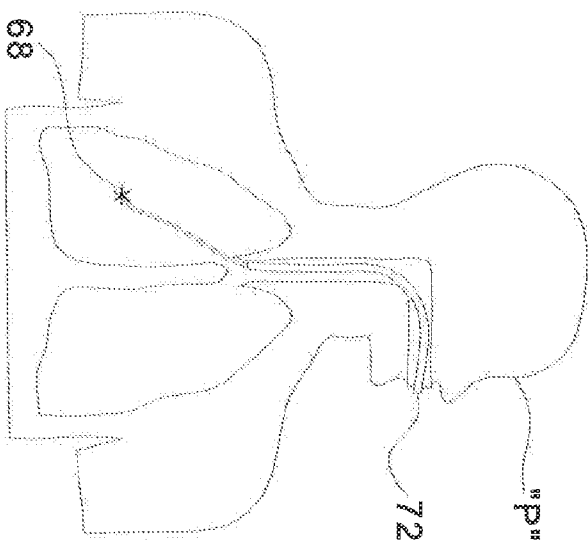


Fig. 16A

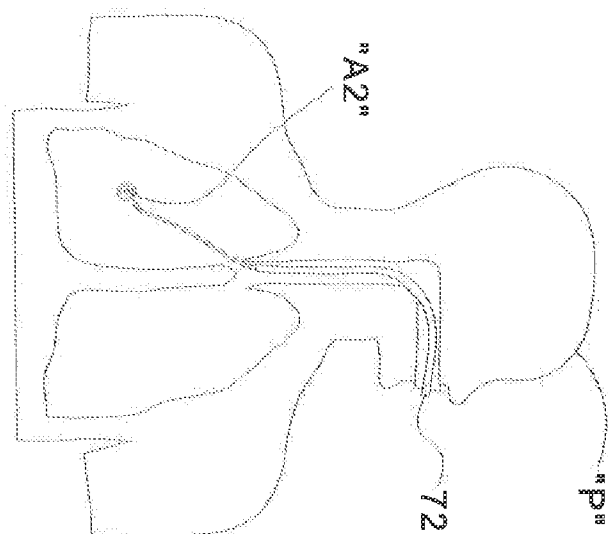


Fig. 16B

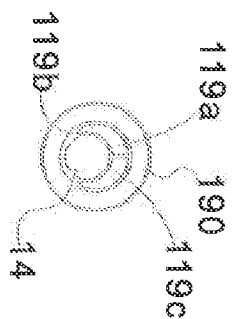


Fig. 16D

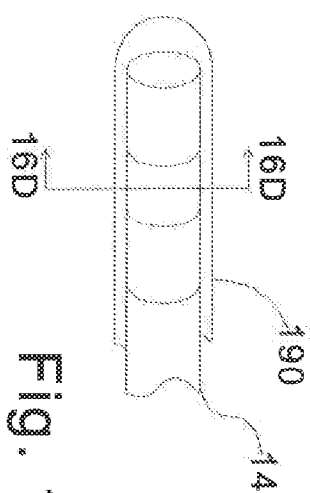
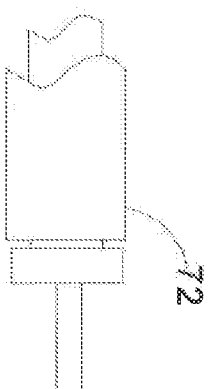


Fig. 16C



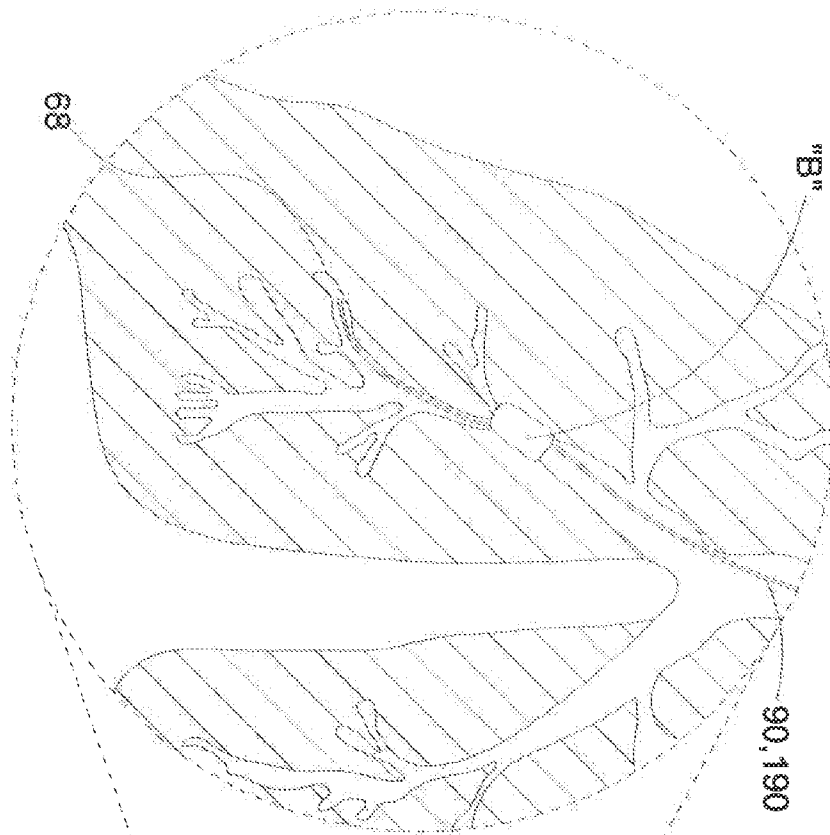


Fig. 18

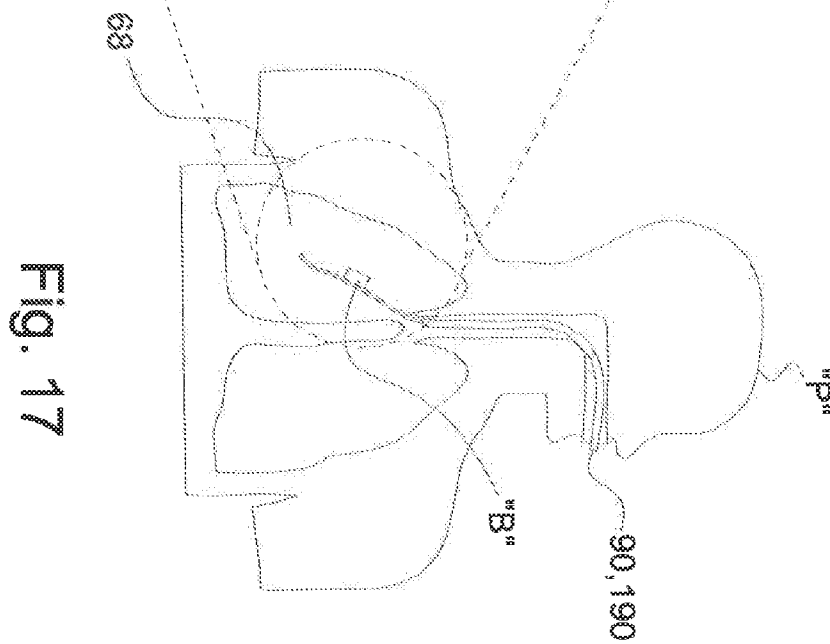


Fig. 17

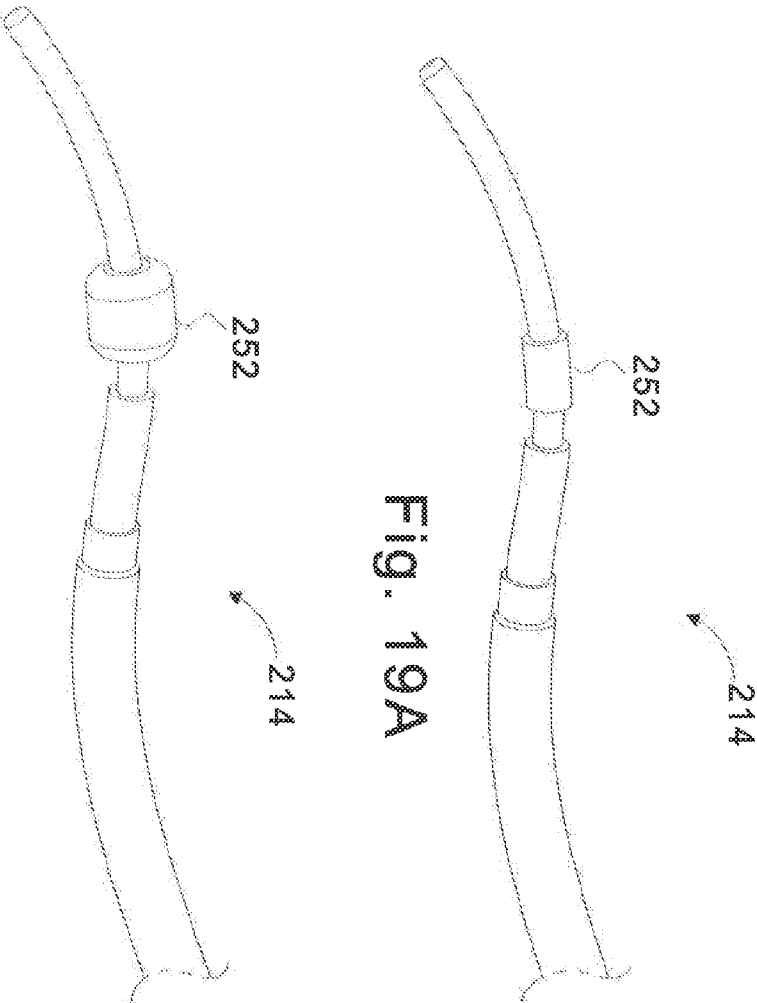


Fig. 19B

Fig. 19A

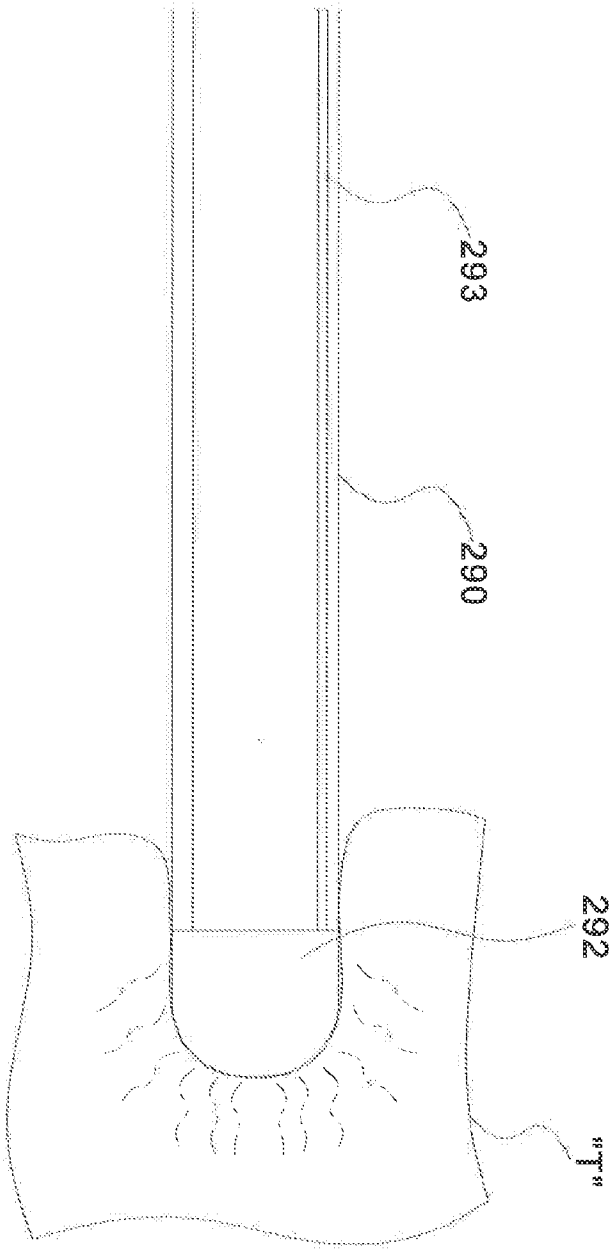


Fig. 20

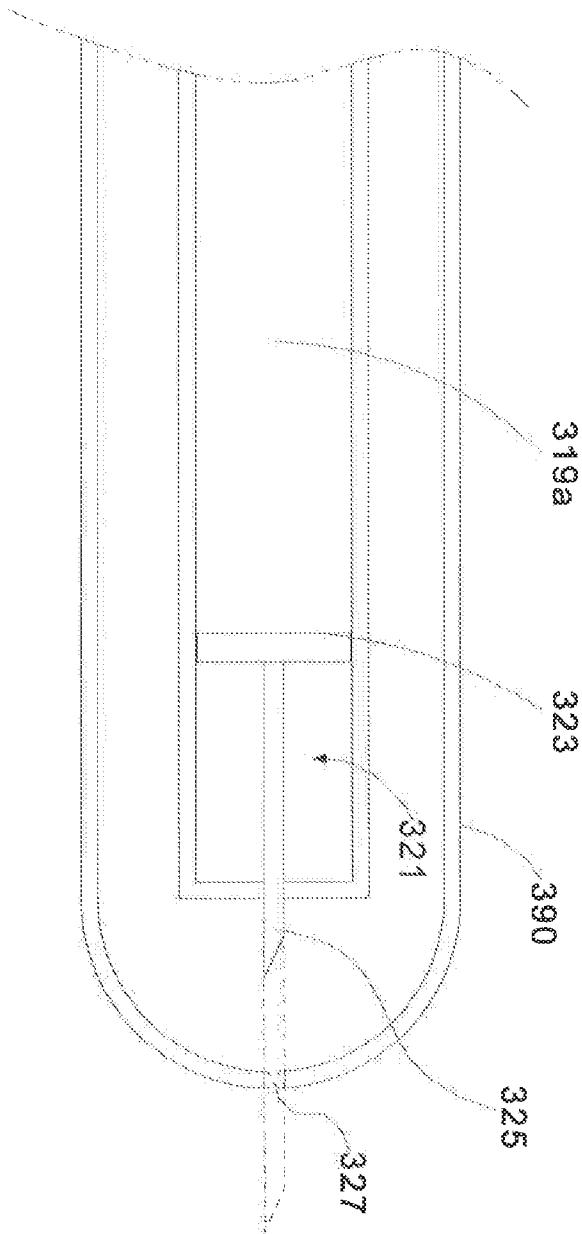
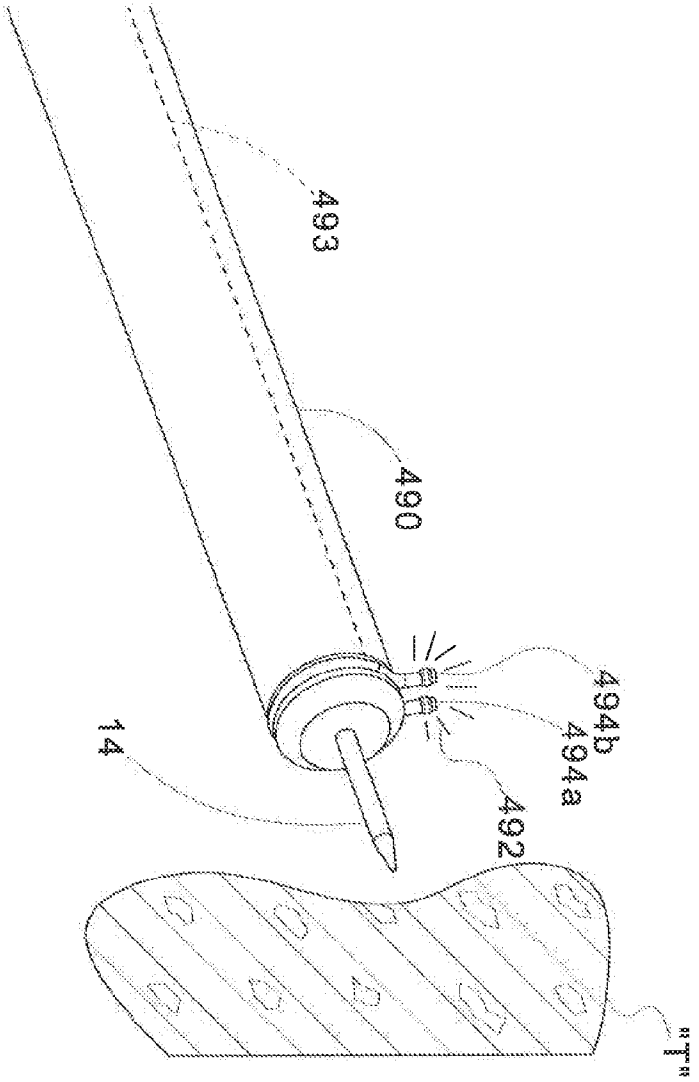
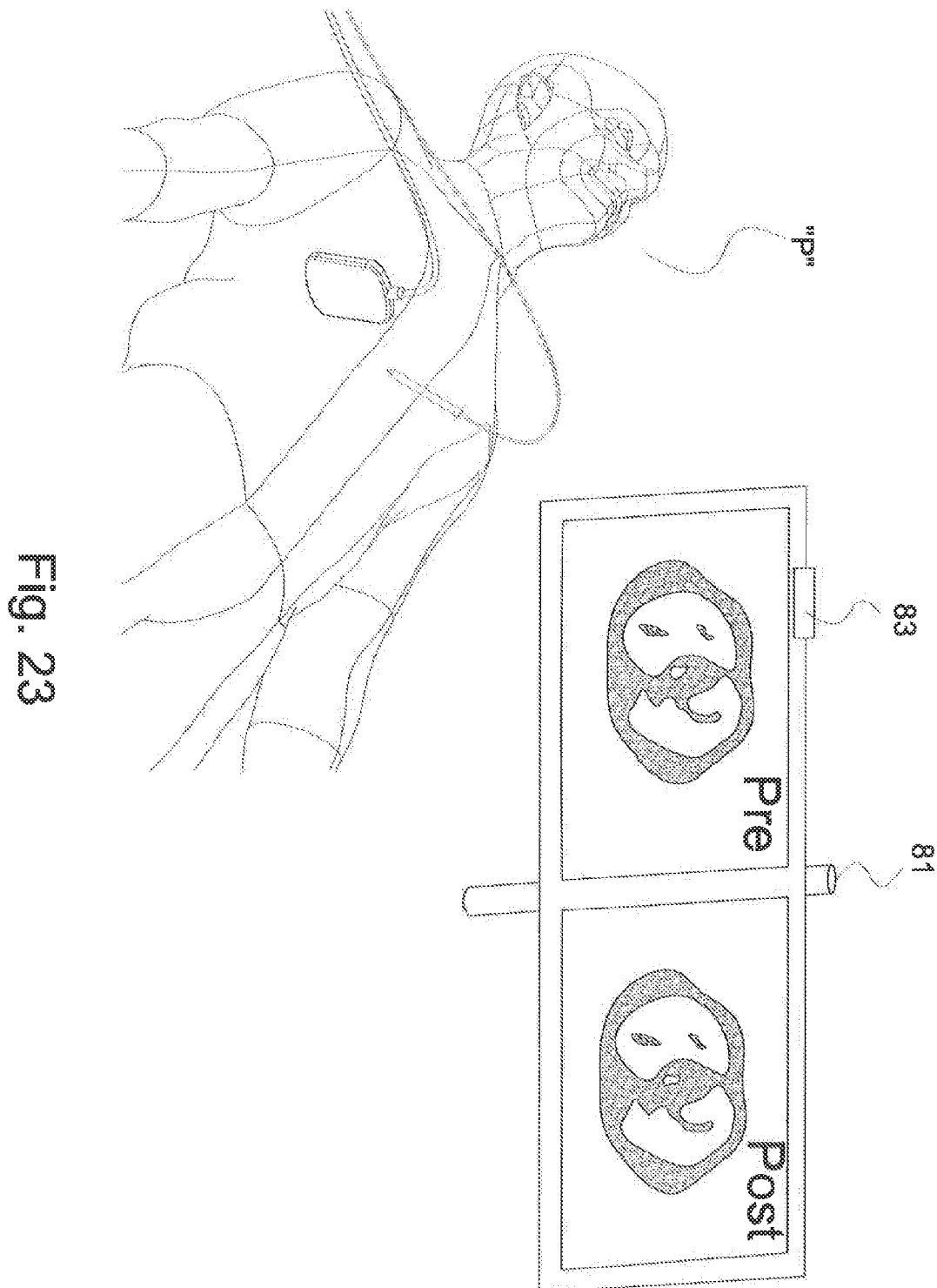


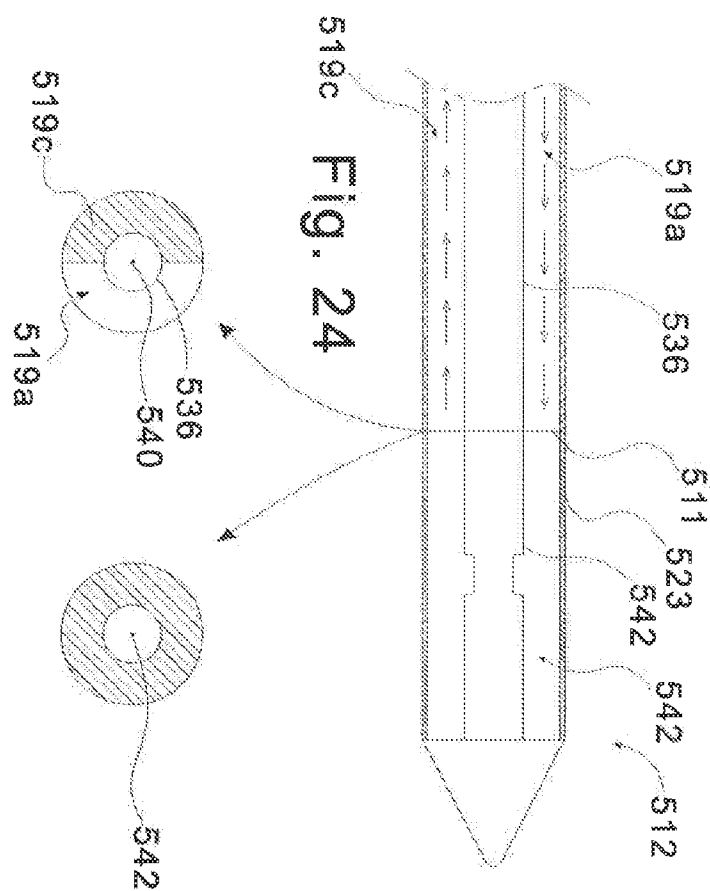
Fig. 21



Fig. 22







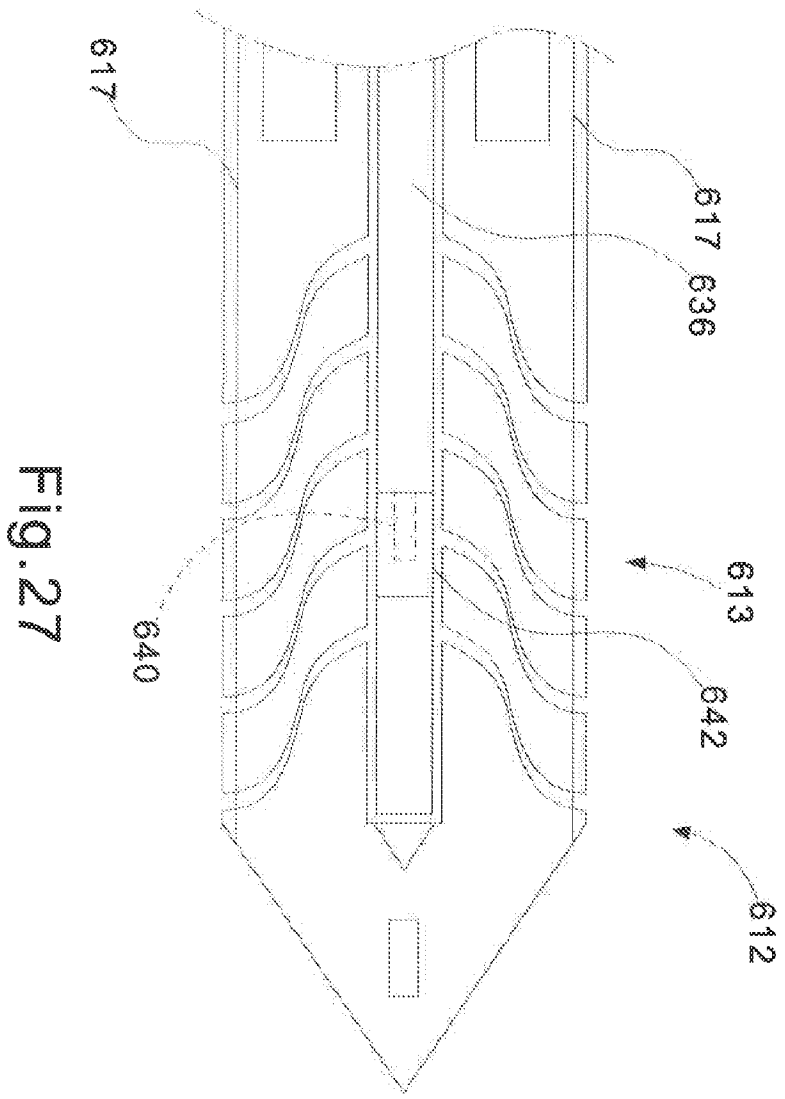
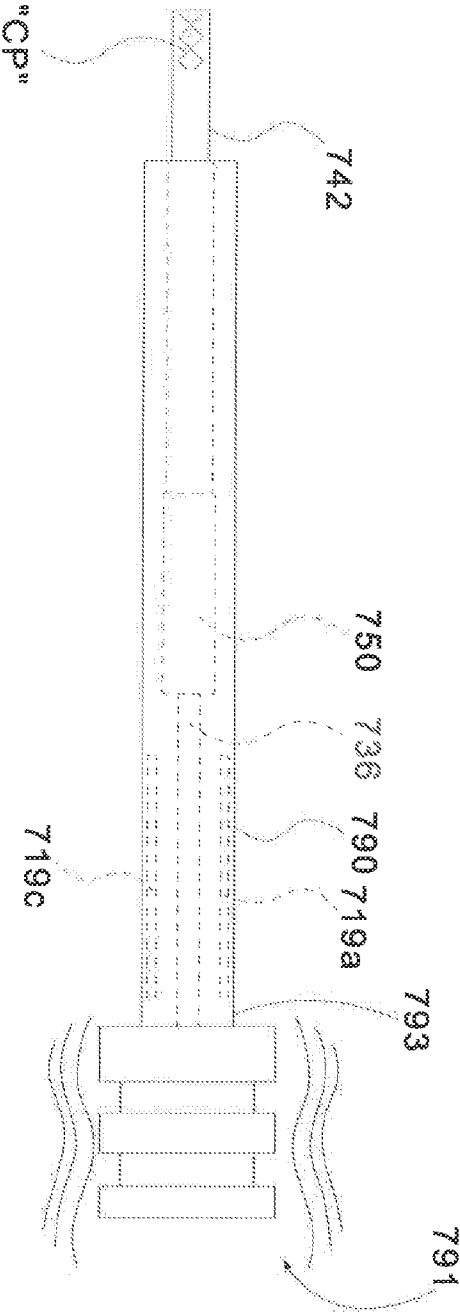


Fig.27

Fig.28



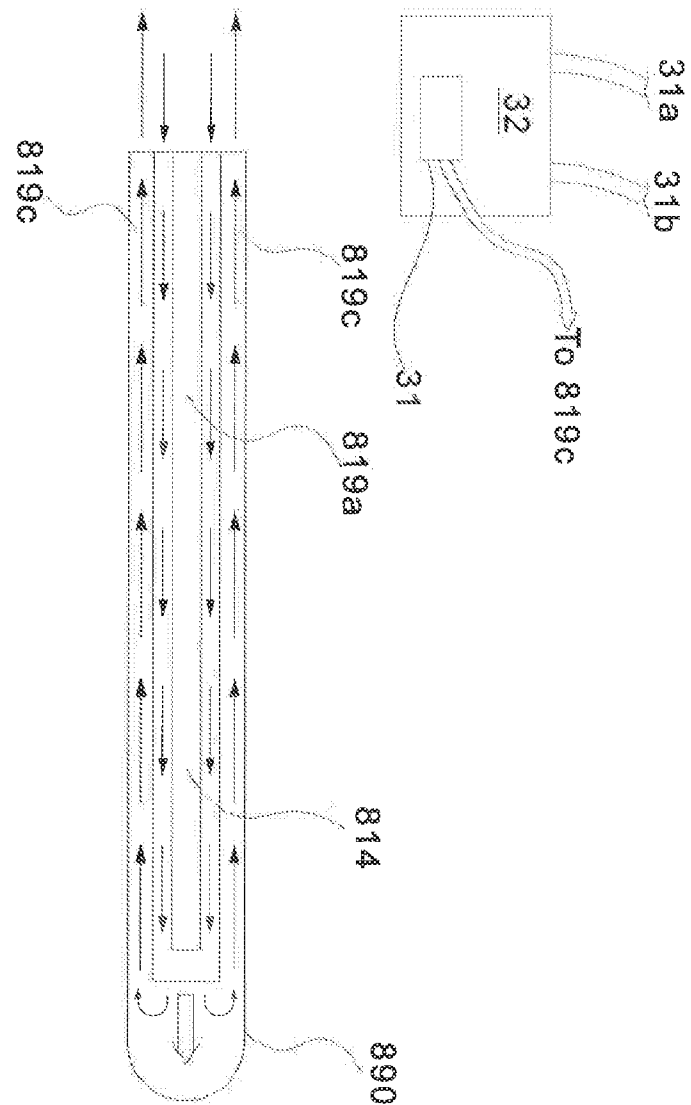
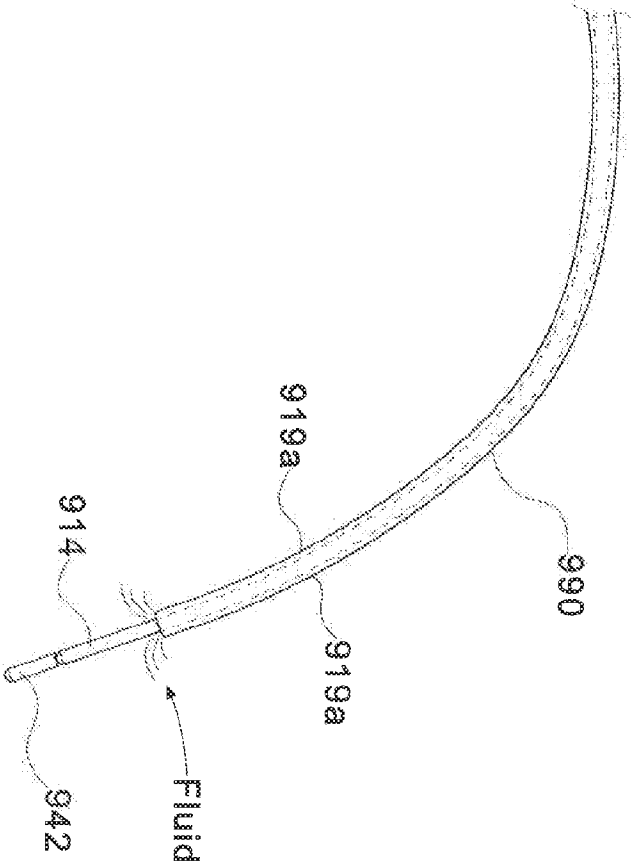


Fig.29

Fig.30



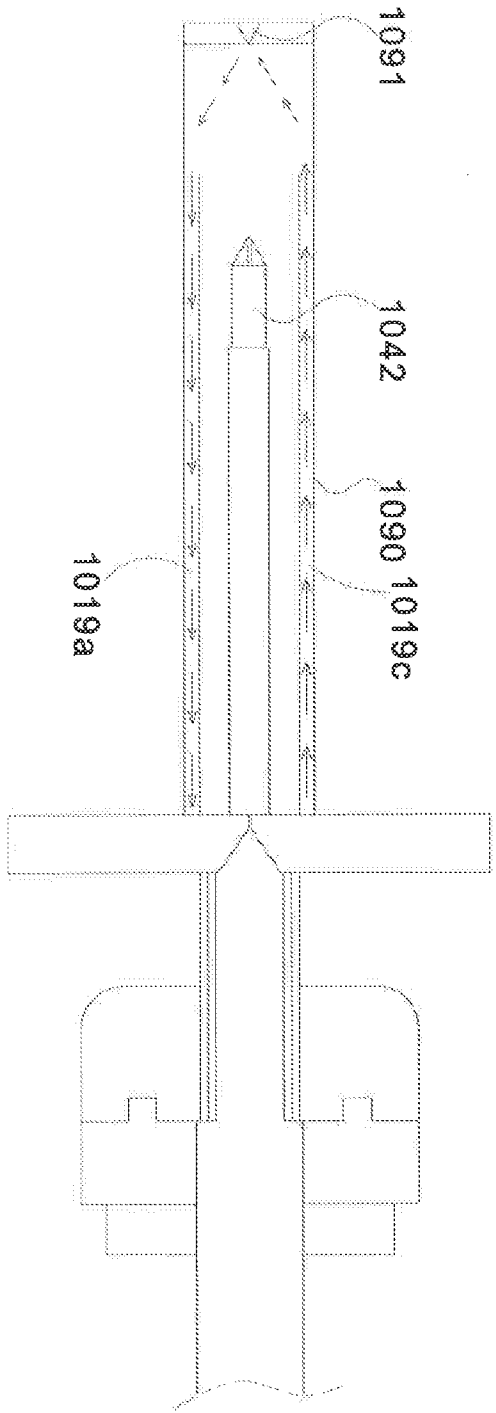


Fig. 31

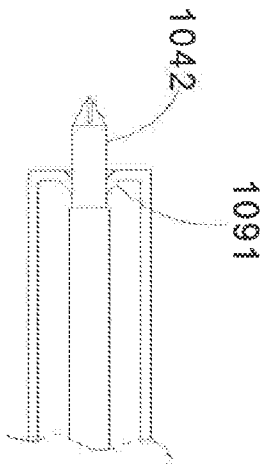


Fig. 32



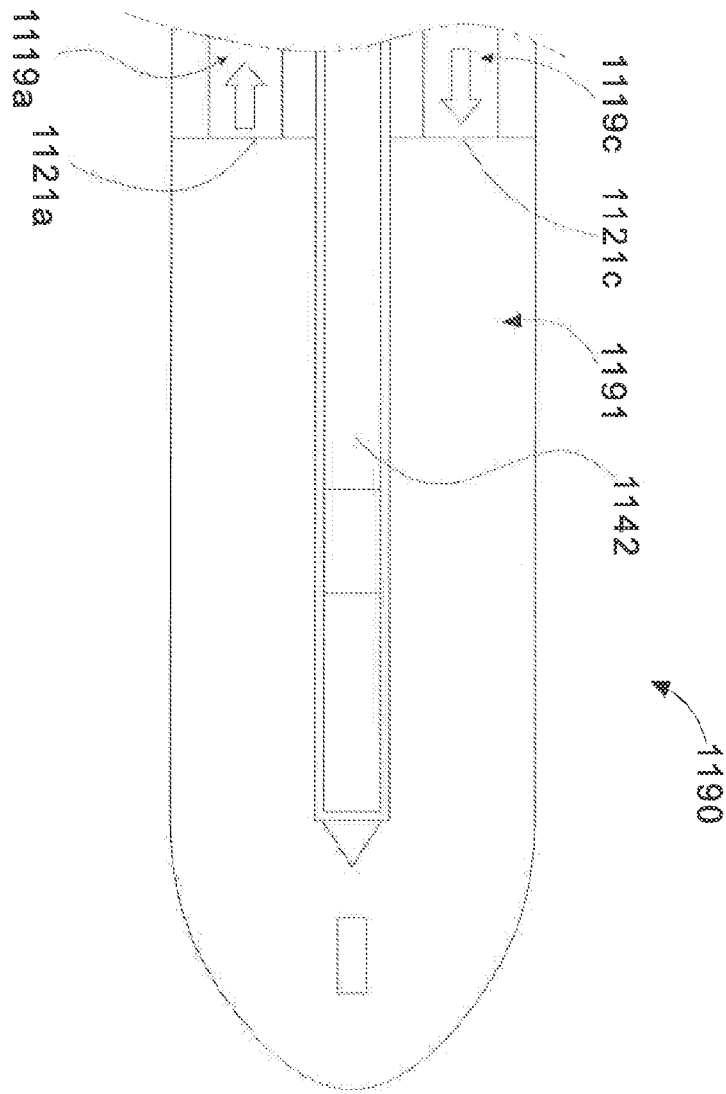


Fig. 33

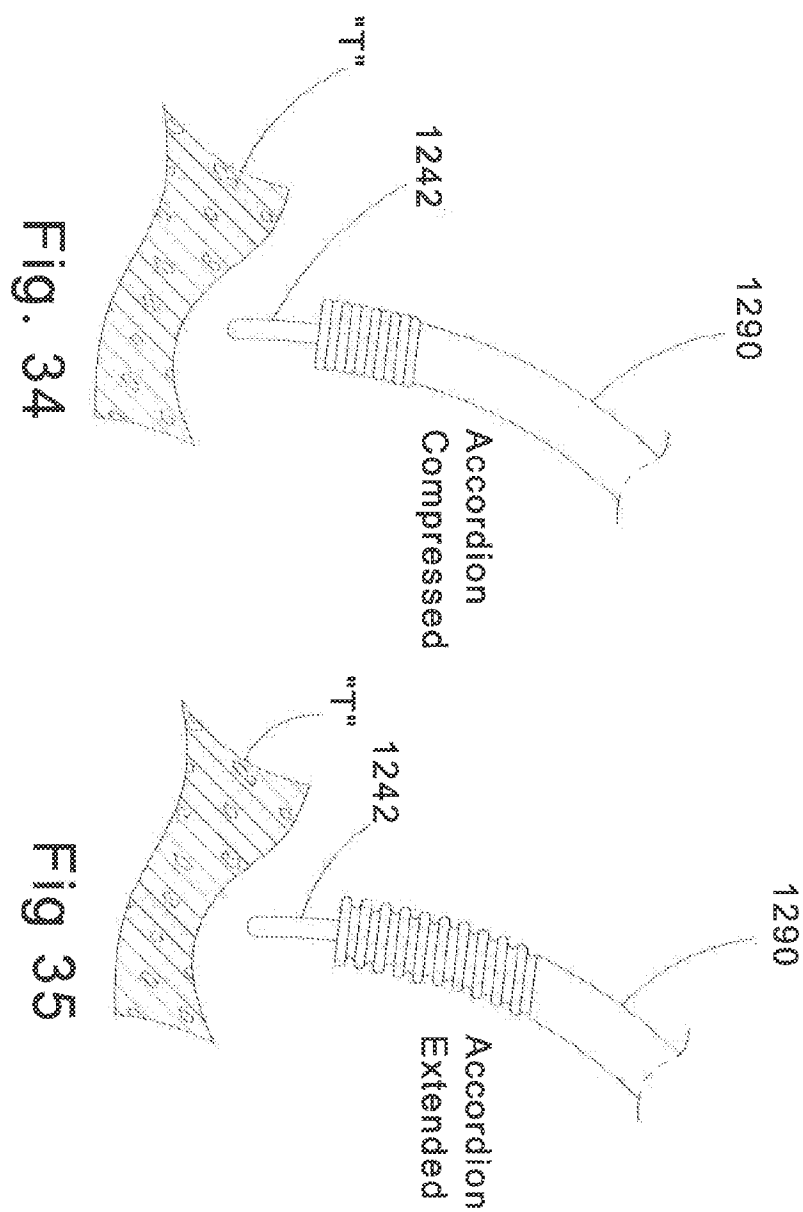


Fig. 36A

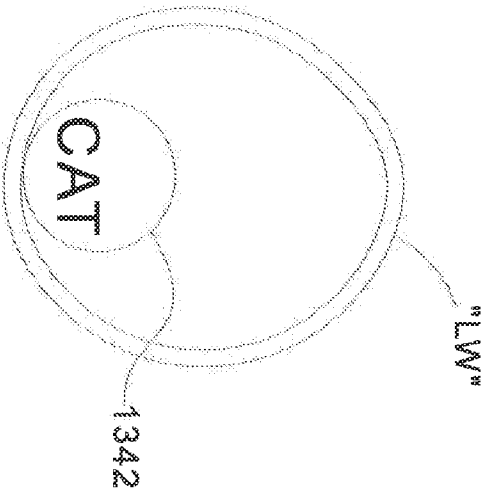


Fig. 36B

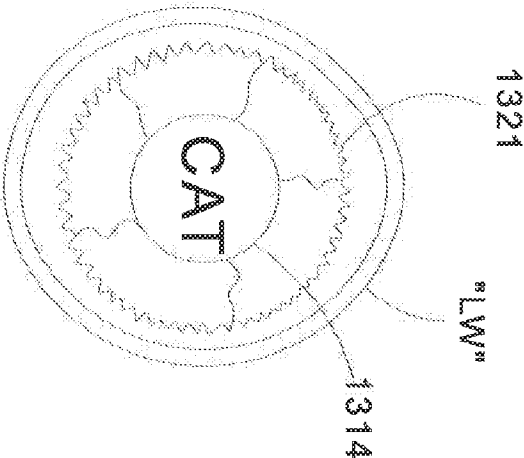


Fig.37A

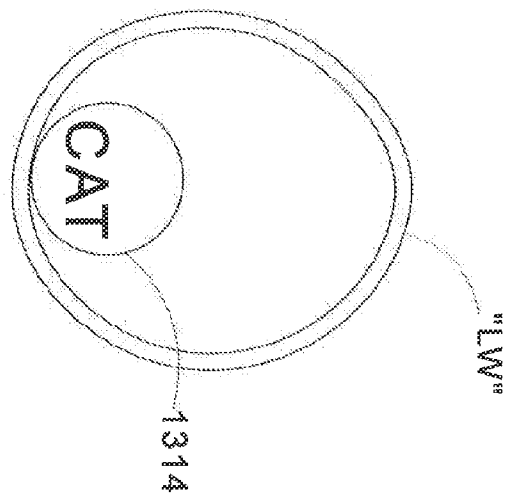
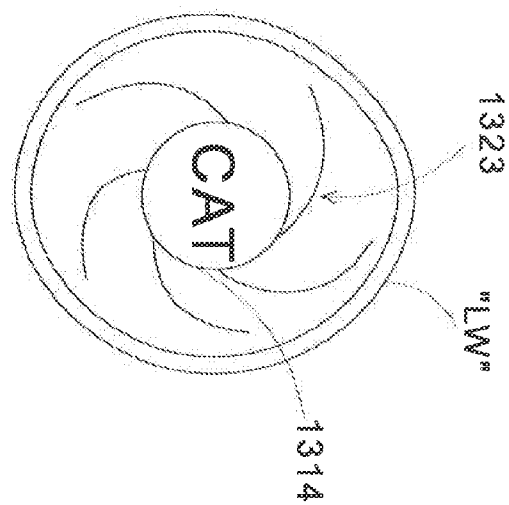


Fig.37B



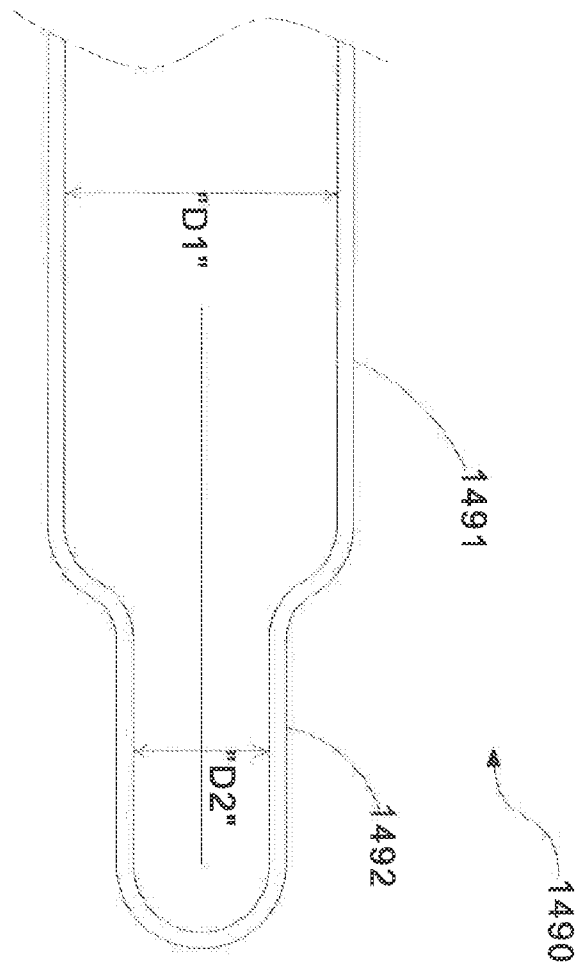
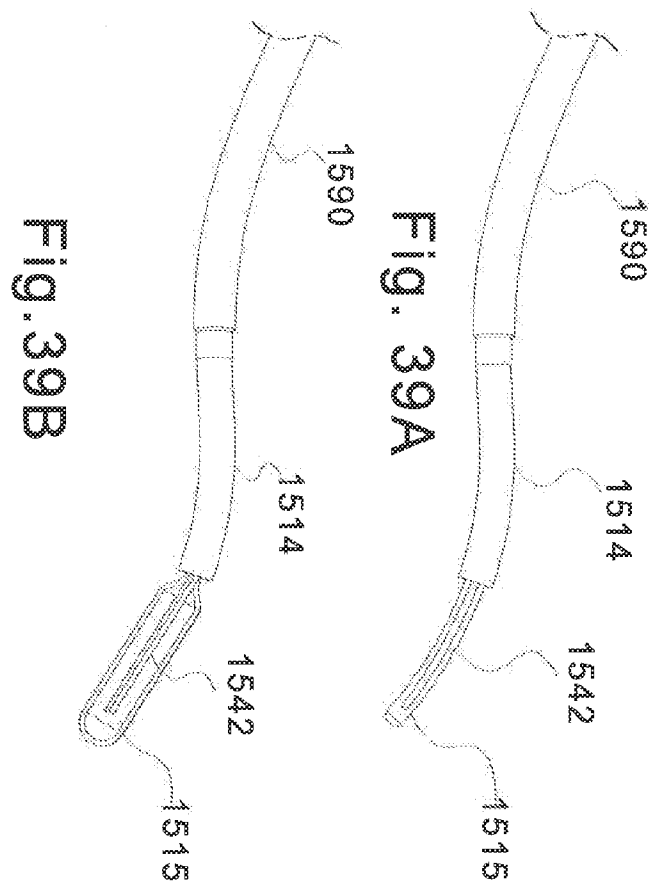


Fig. 38



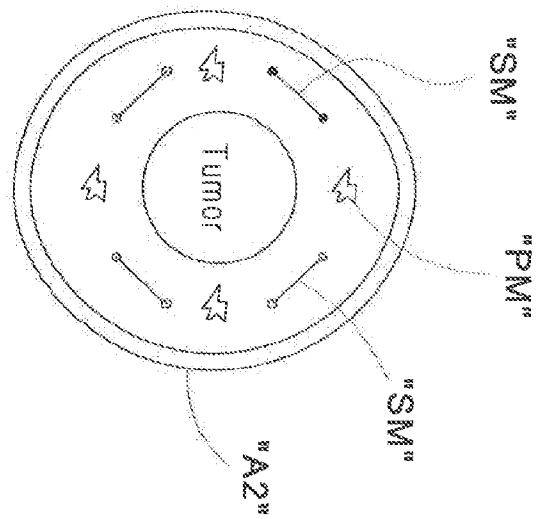


Fig. 40A

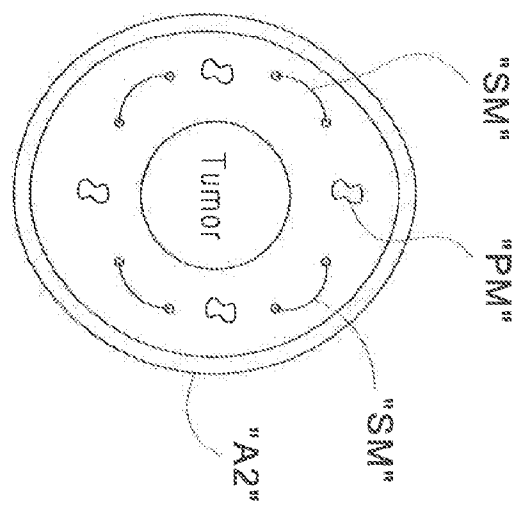
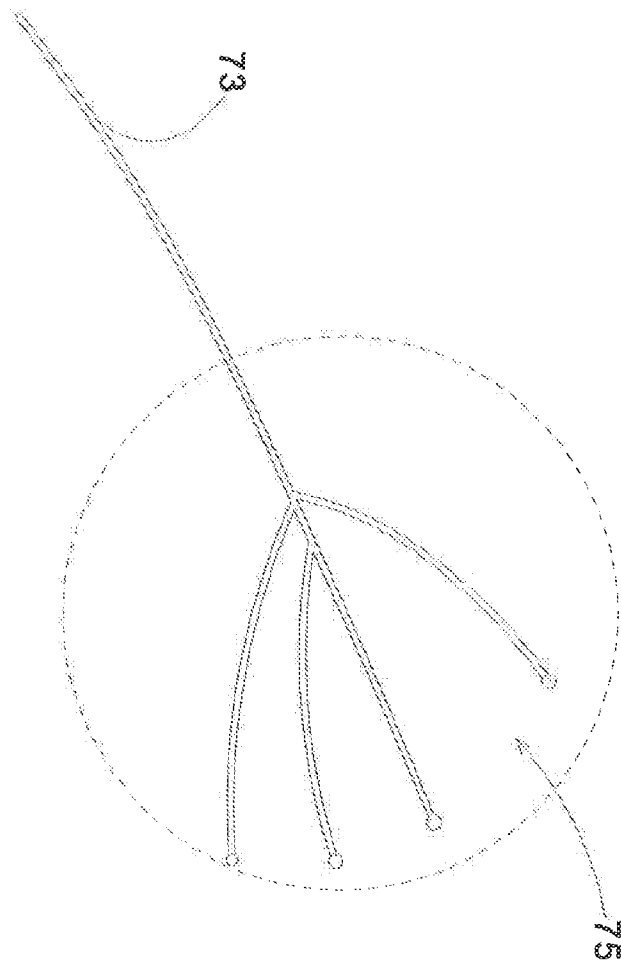


Fig. 40B

Fig. 41





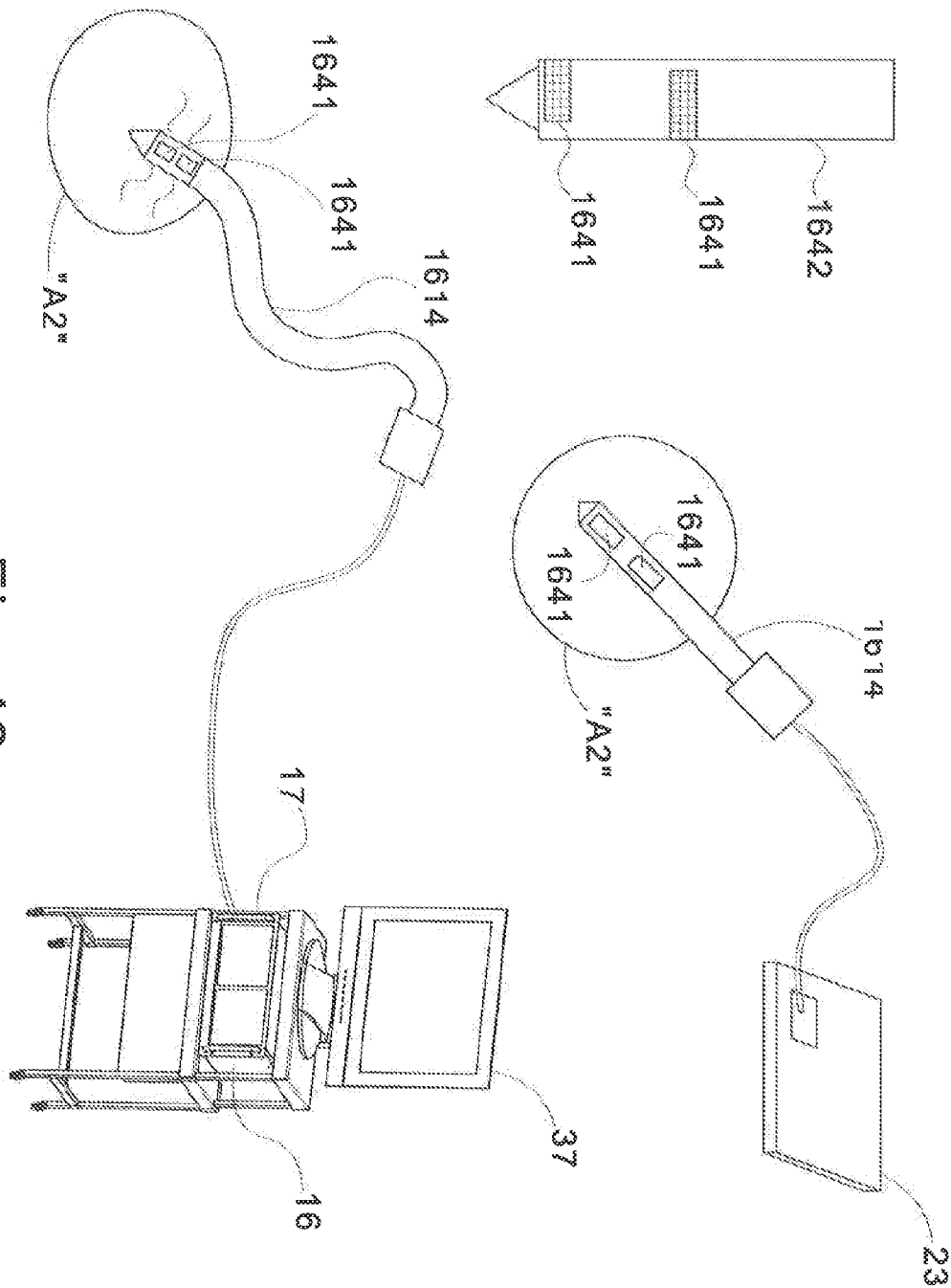


Fig. 42

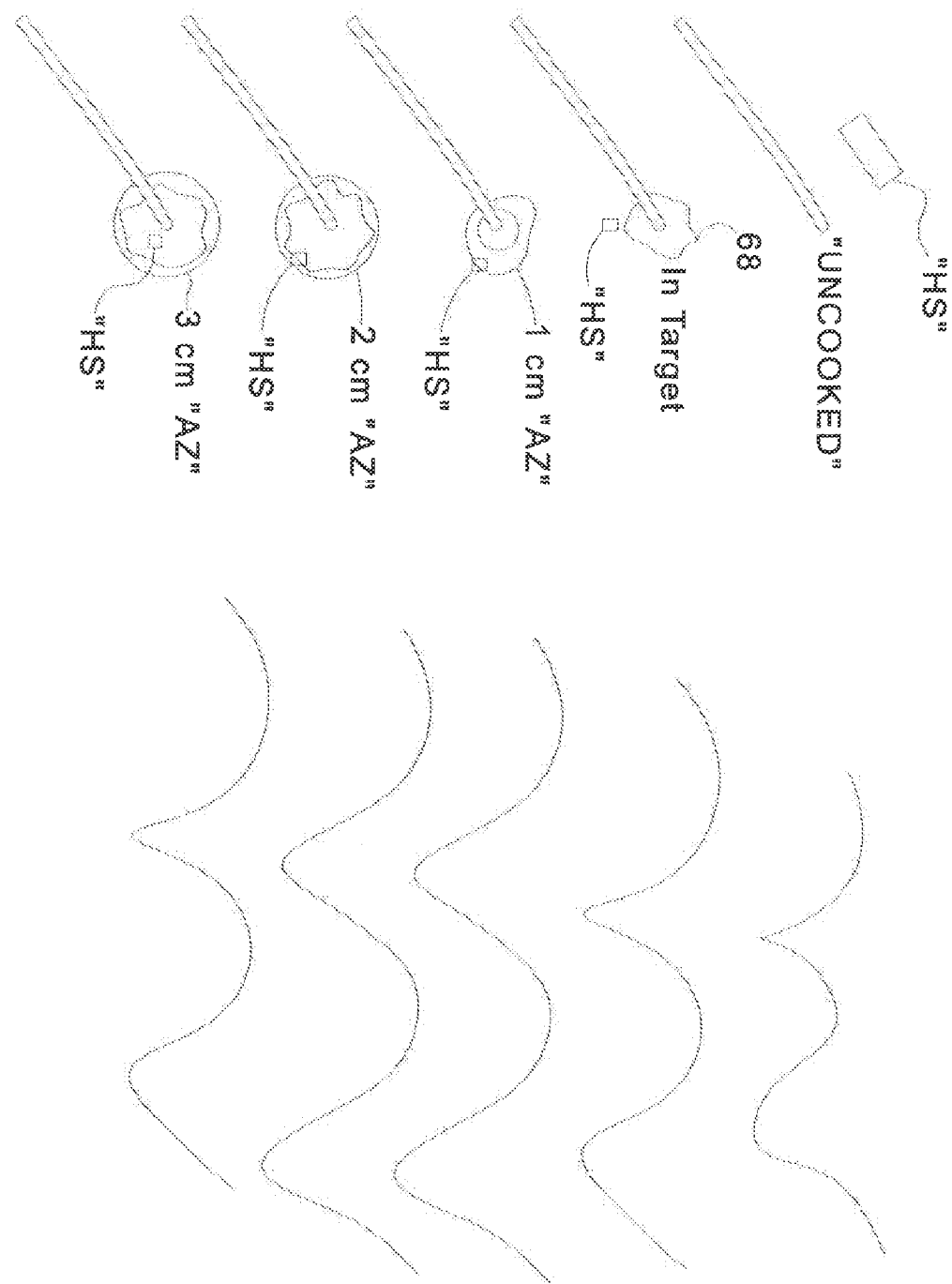


Fig. 43

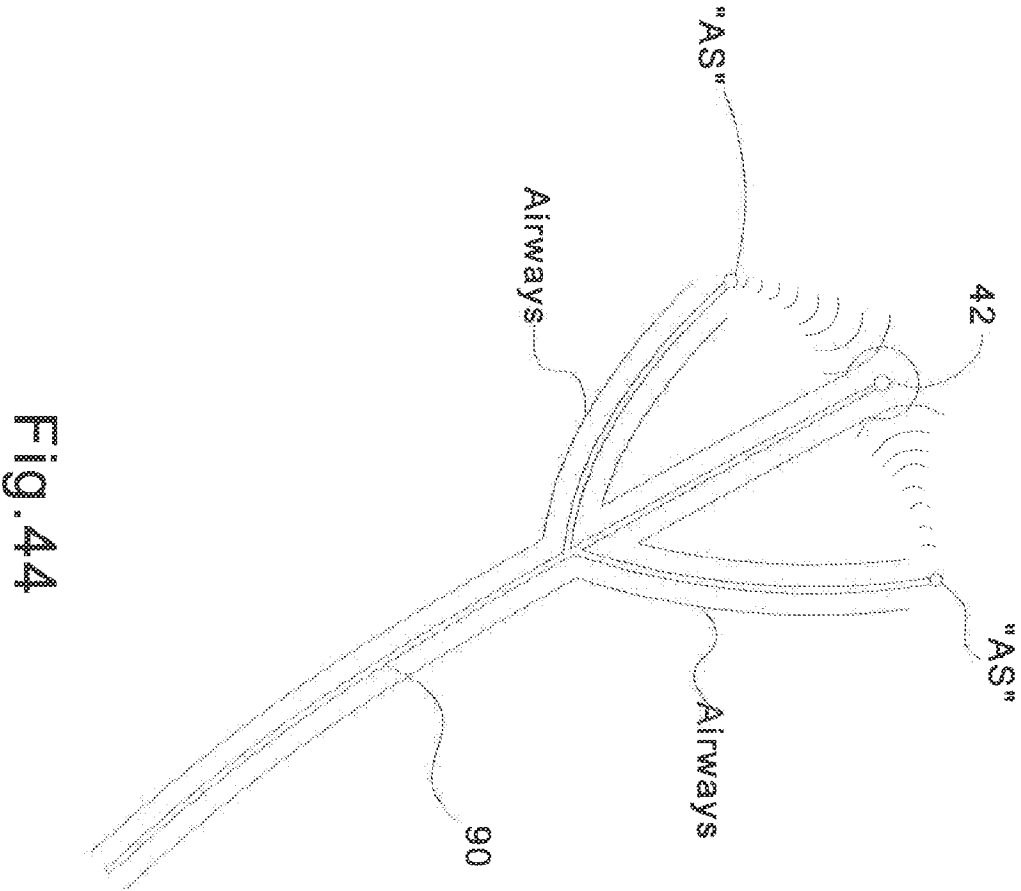


Fig. 44

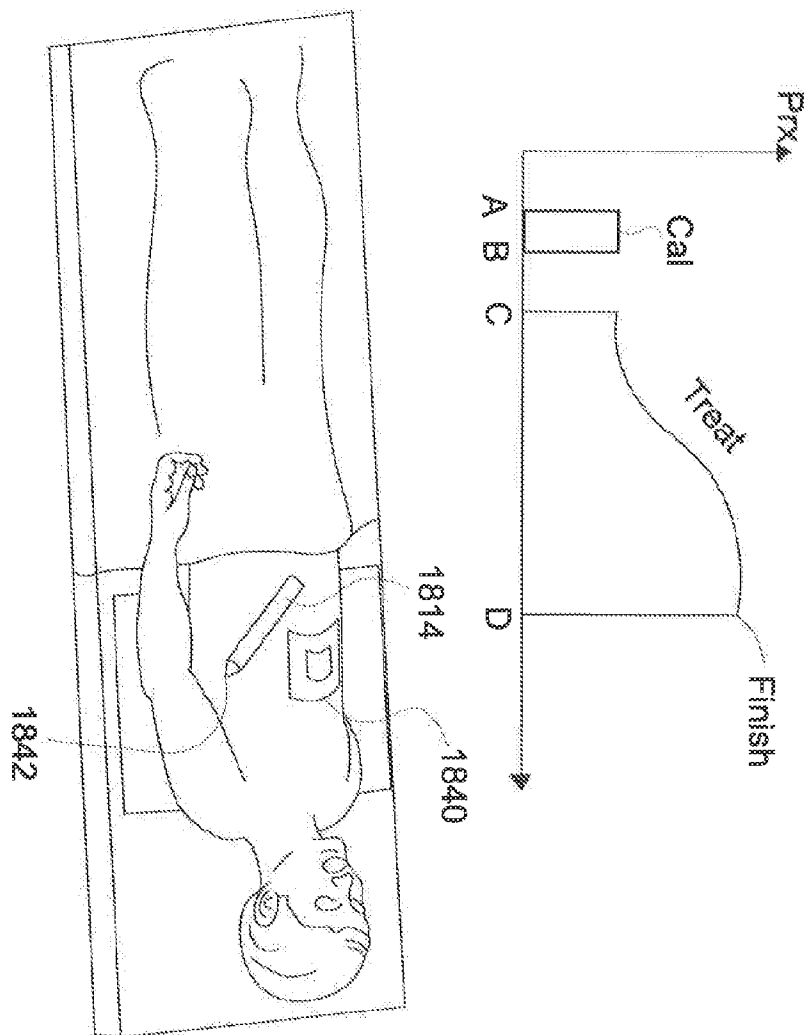


Fig. 45

Fig. 46A

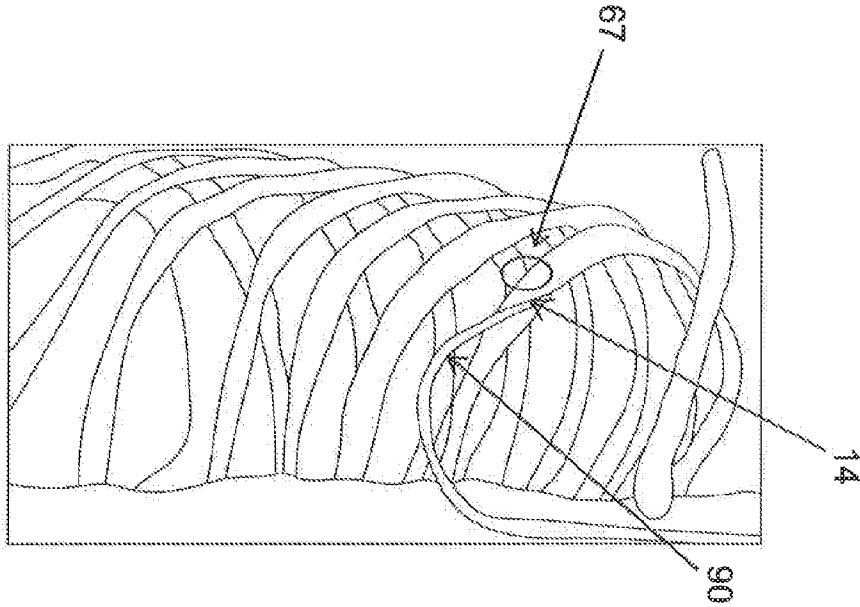
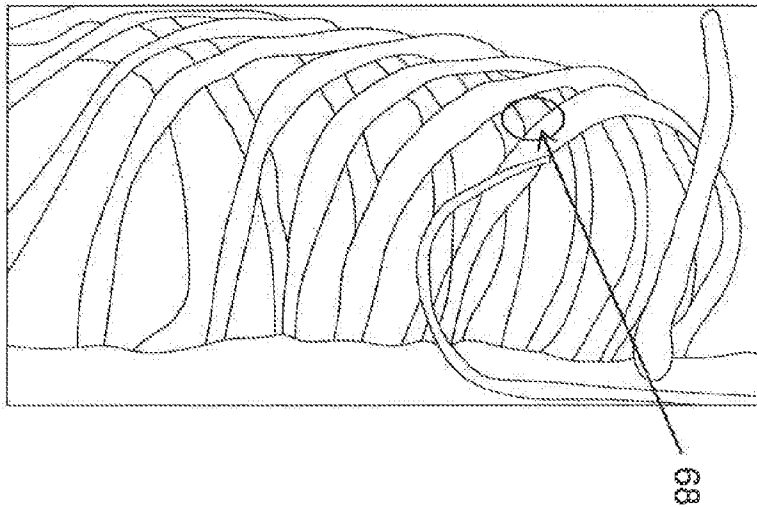


Fig. 46B



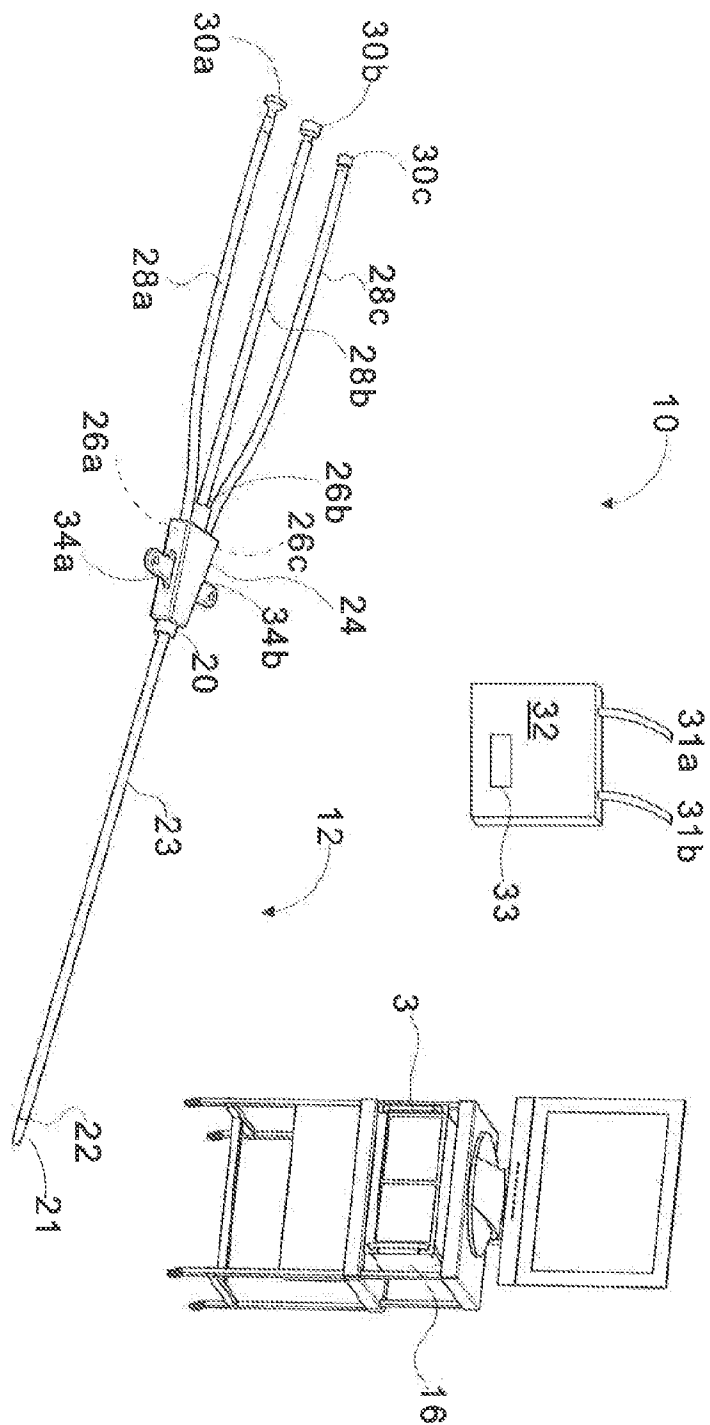
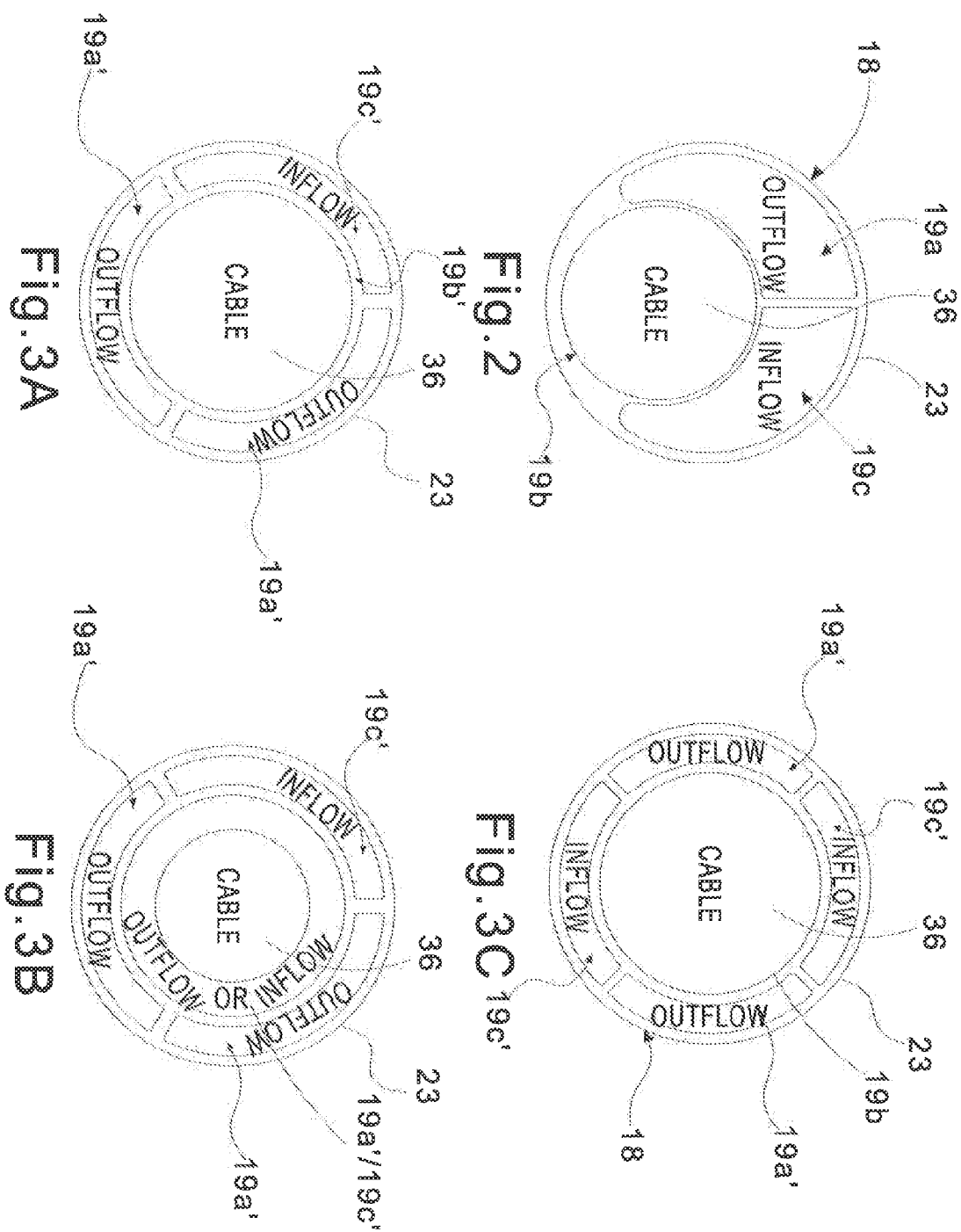


Fig. 1



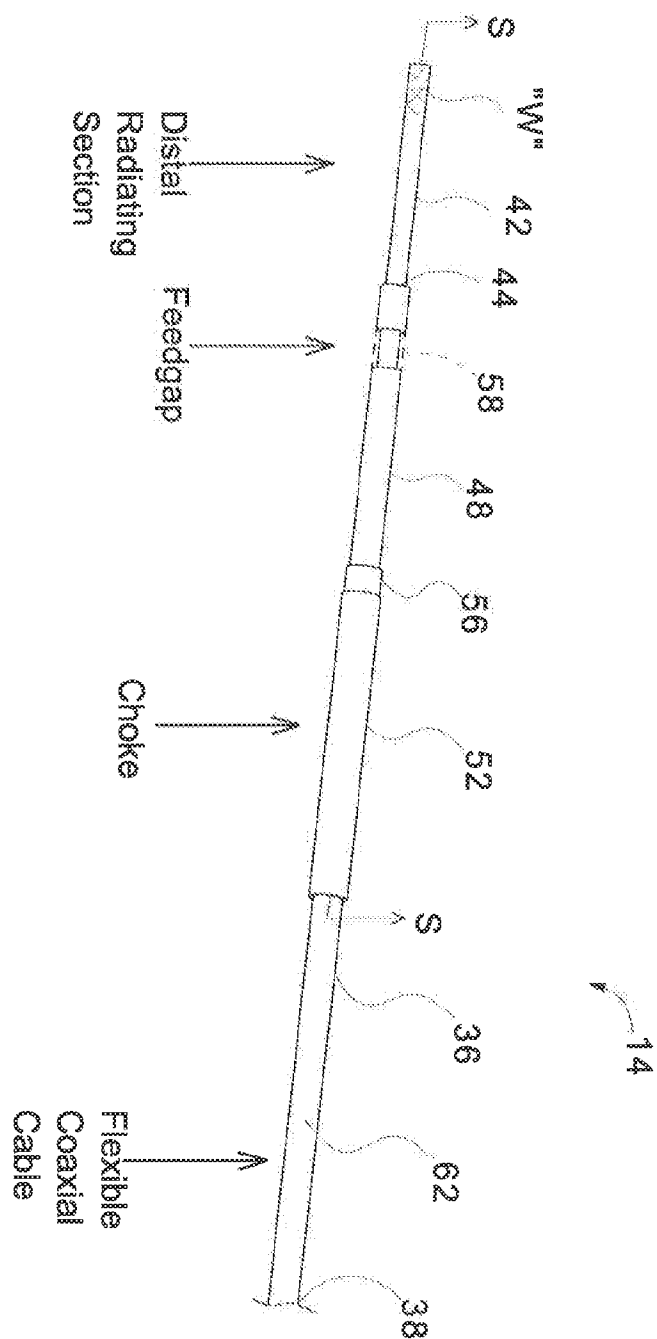


Fig. 4



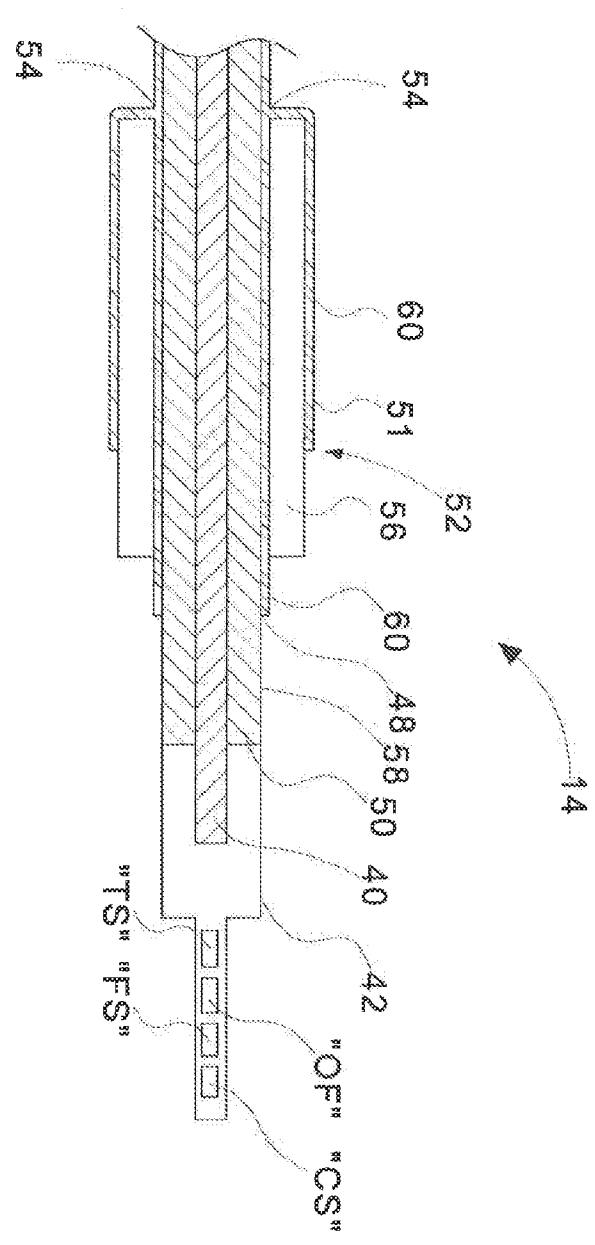
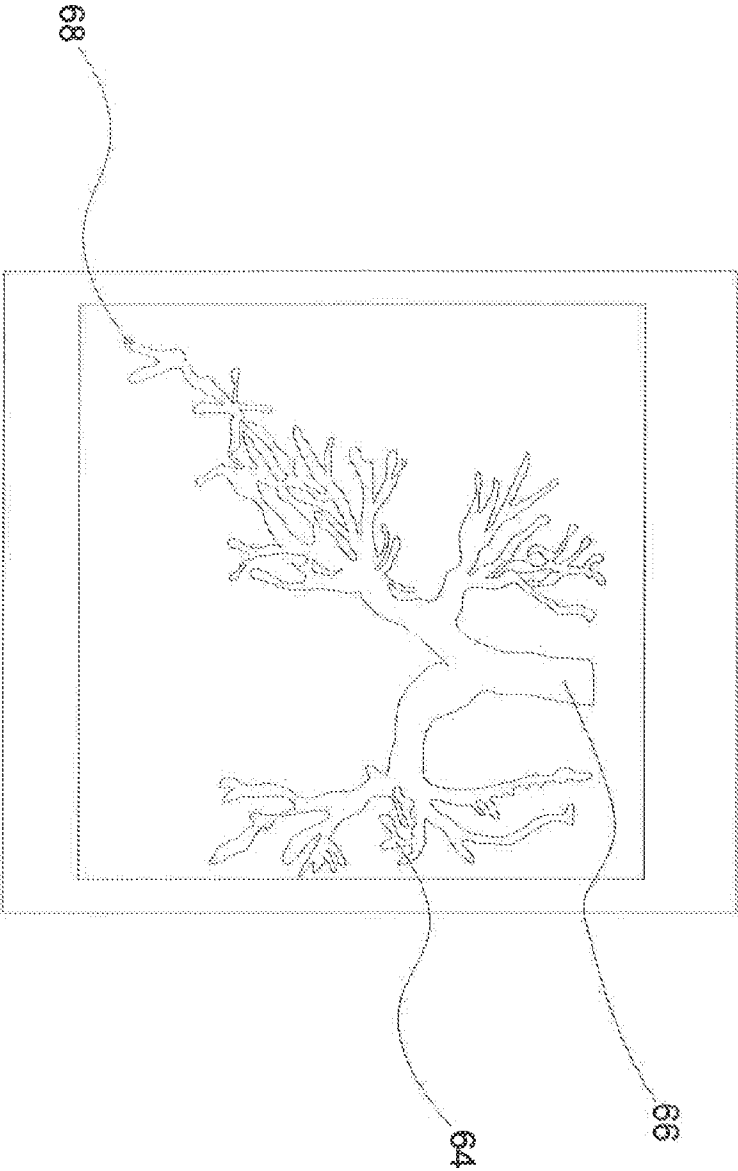


Fig. 5

Fig. 6



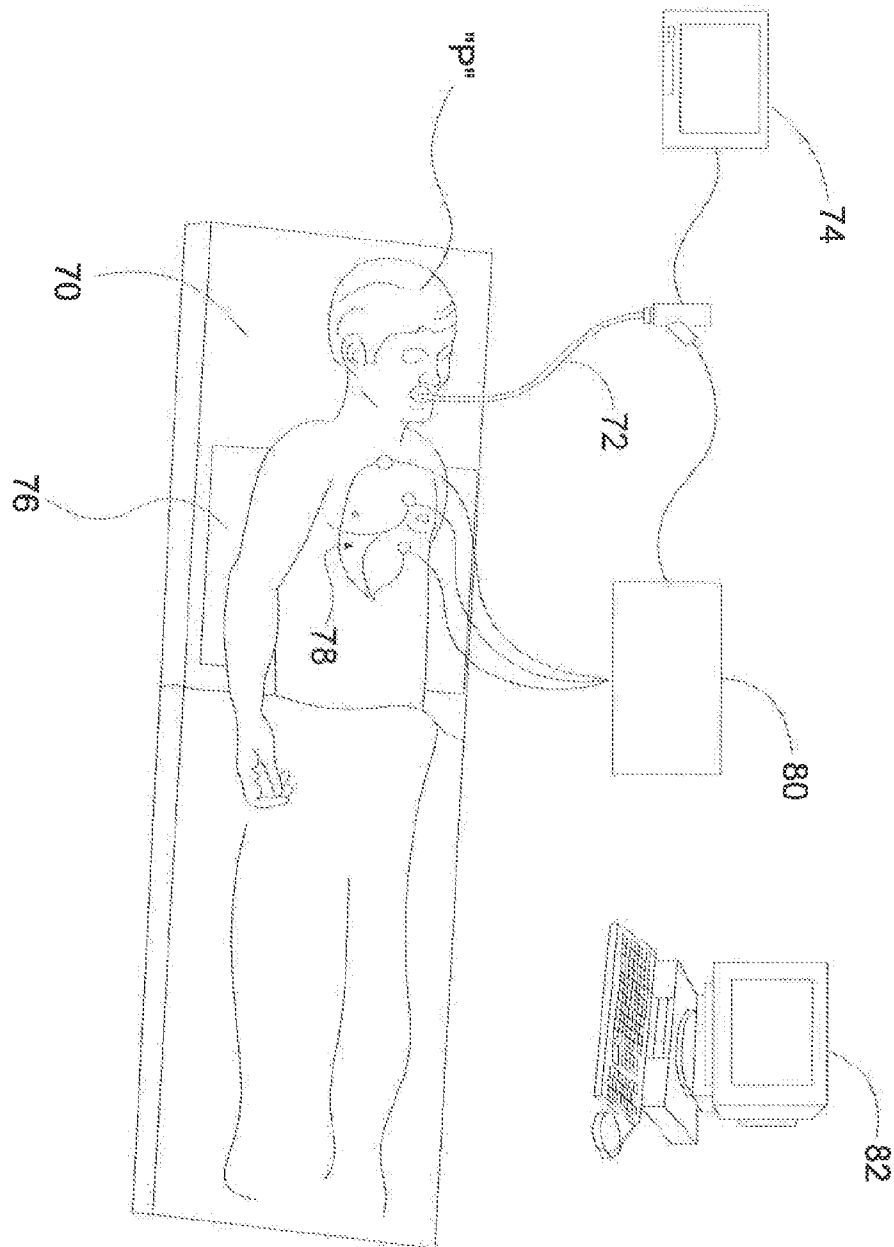


Fig. 7

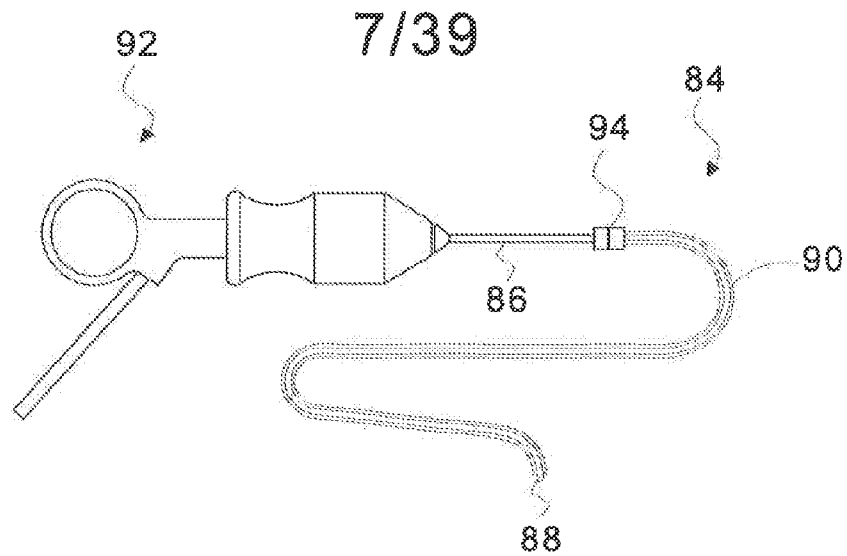


FIG. 8

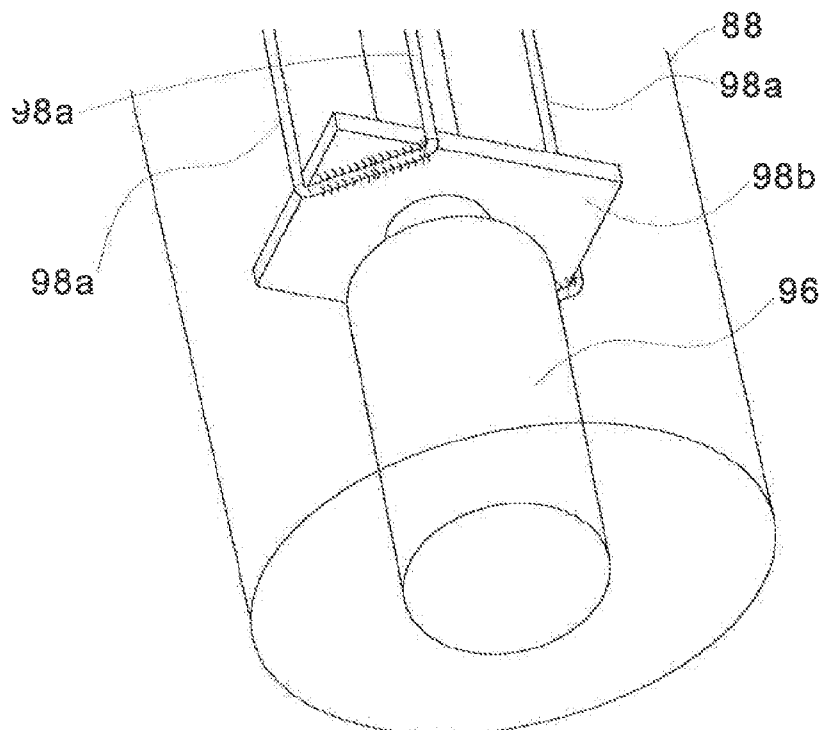


FIG. 9

8/39

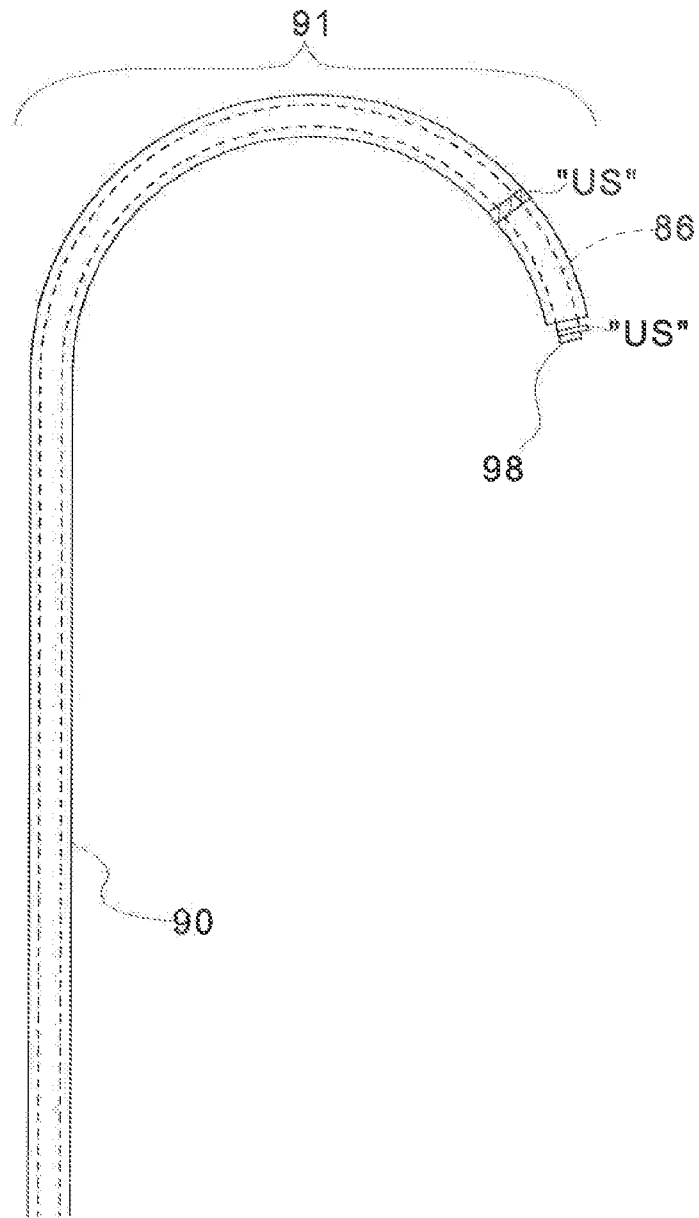


Fig. 10

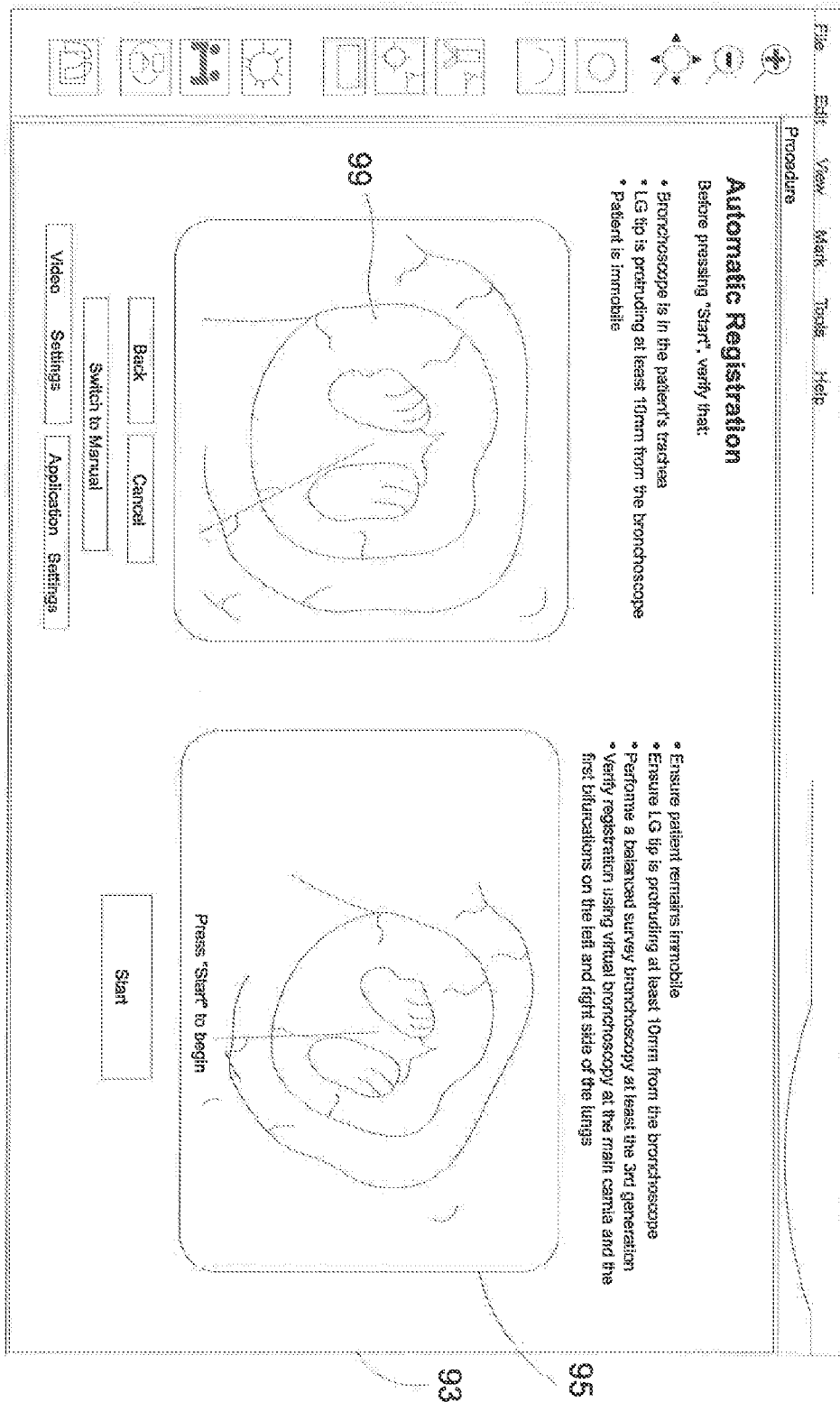


Fig. 11

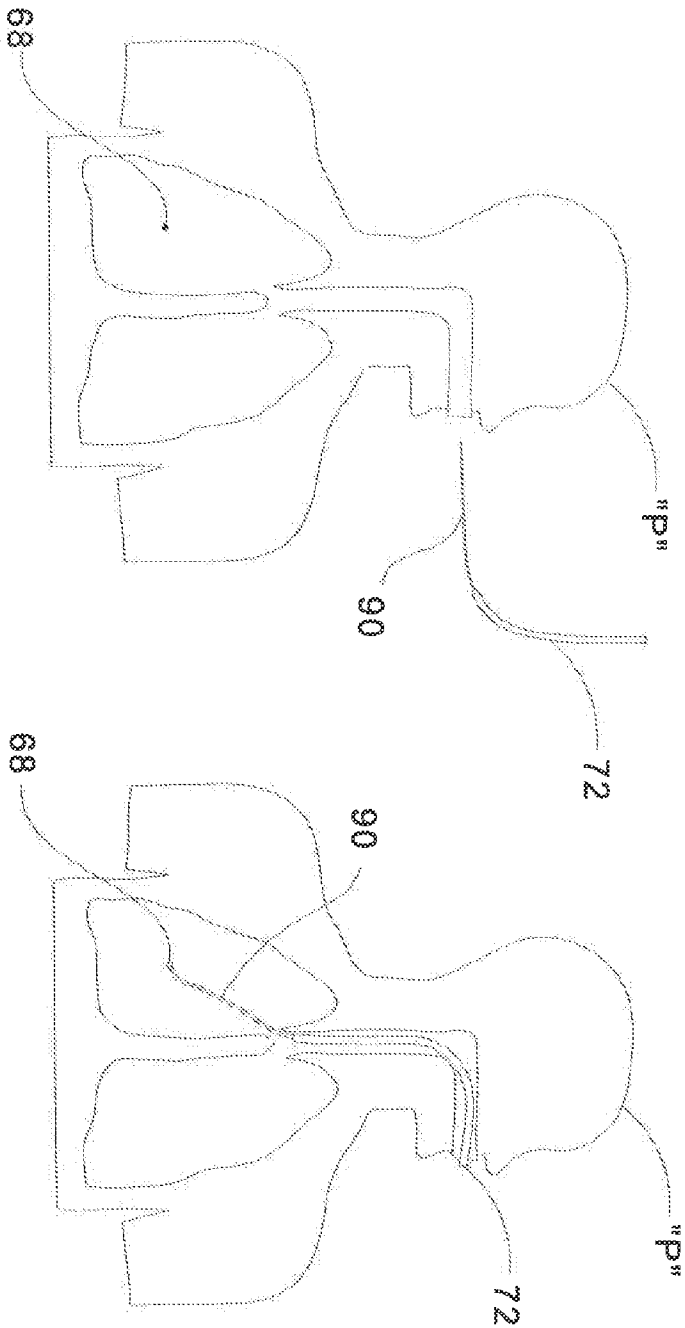


Fig. 12A

Fig. 12B

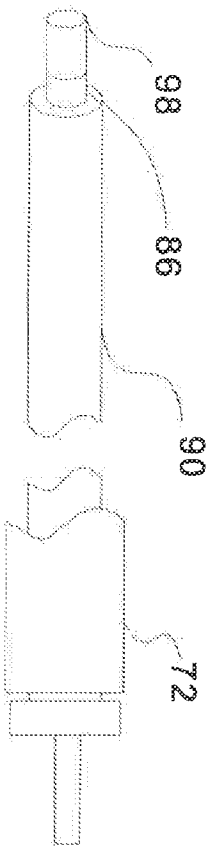


Fig. 12C

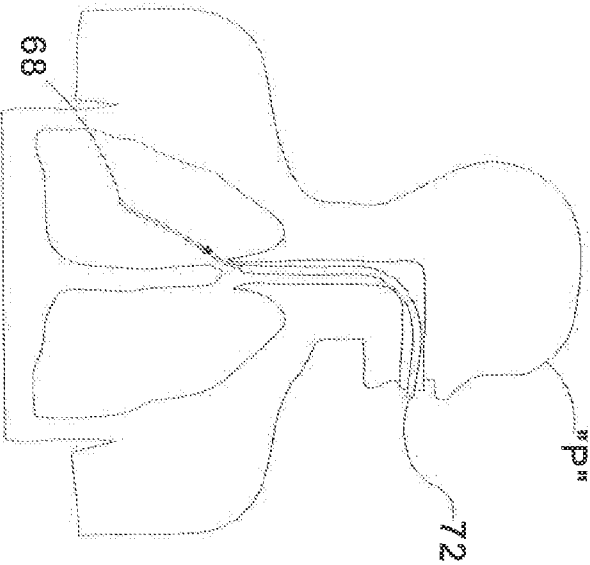


Fig. 13A

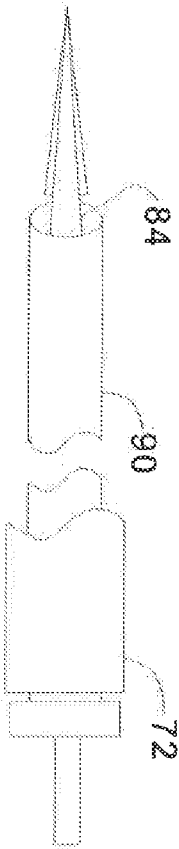


Fig. 13B



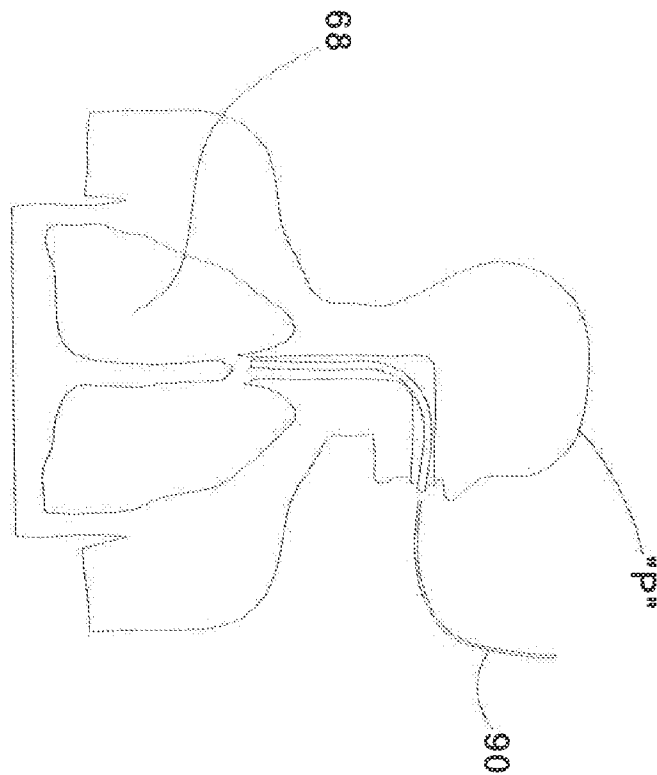
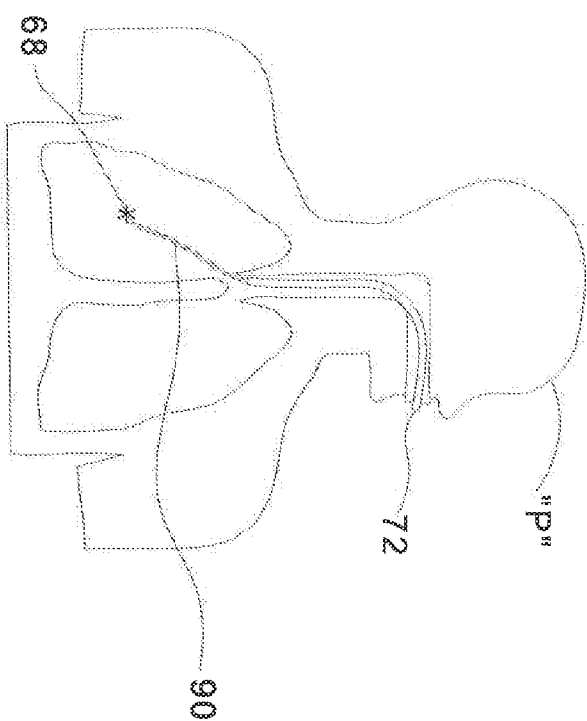
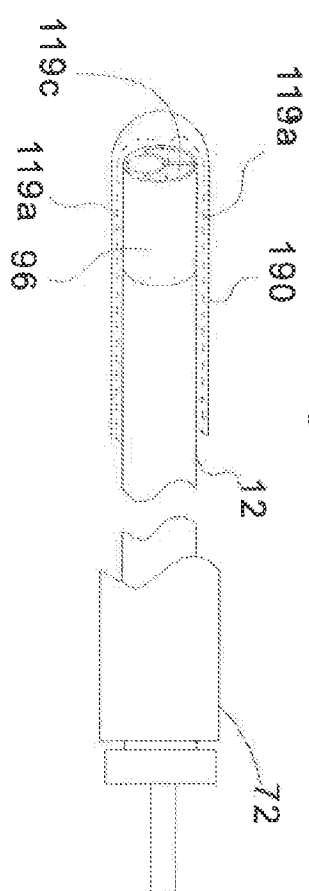


Fig. 14



F 9 15A



1997

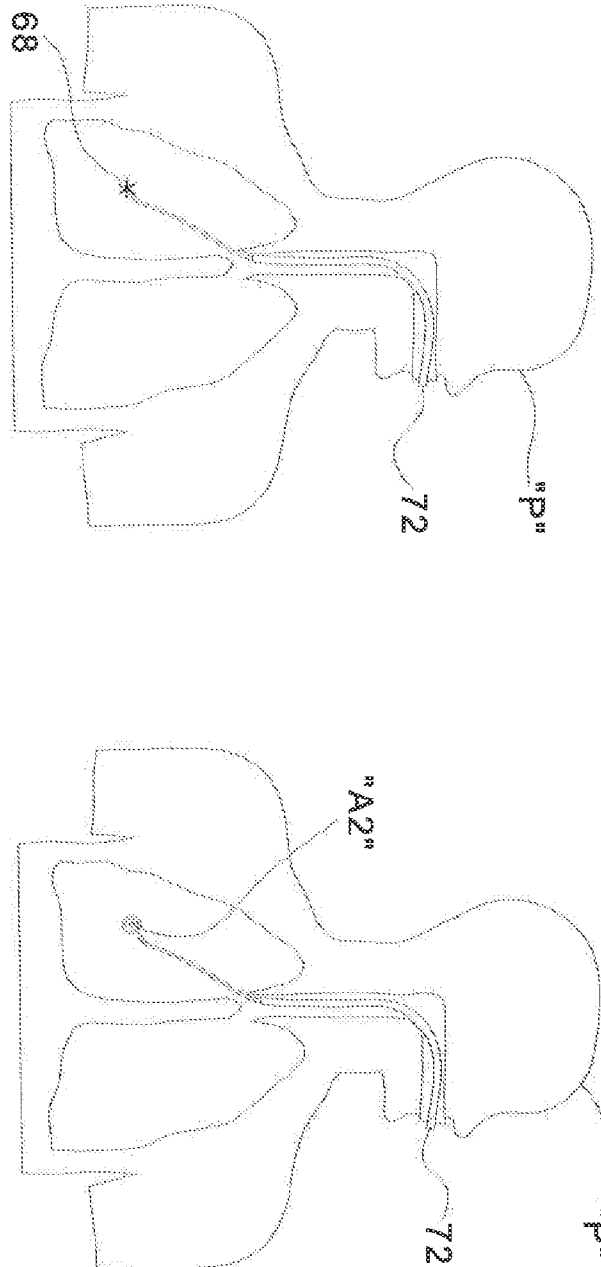


Fig. 16A

Fig. 16B

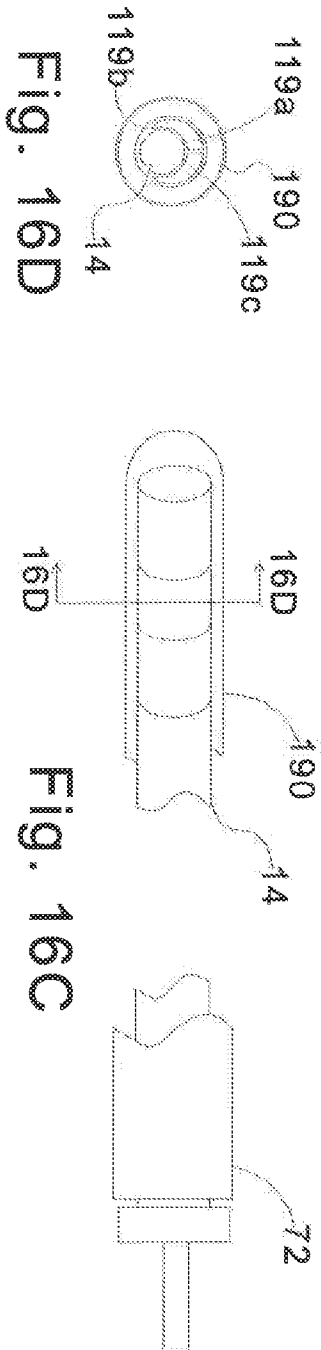


Fig. 16D

Fig. 16C

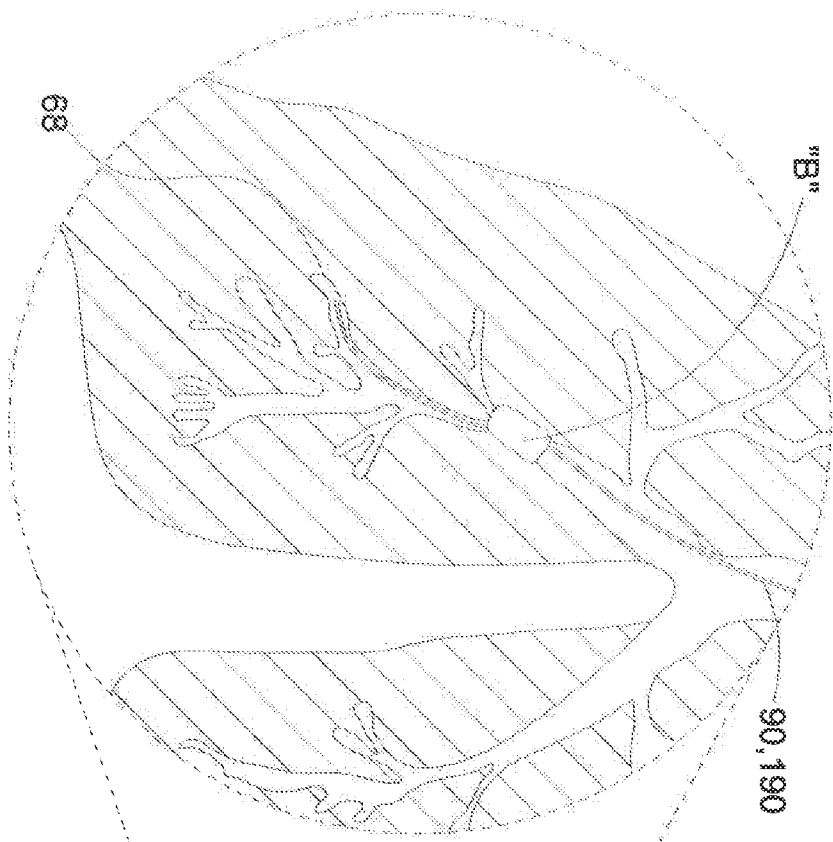


Fig. 18

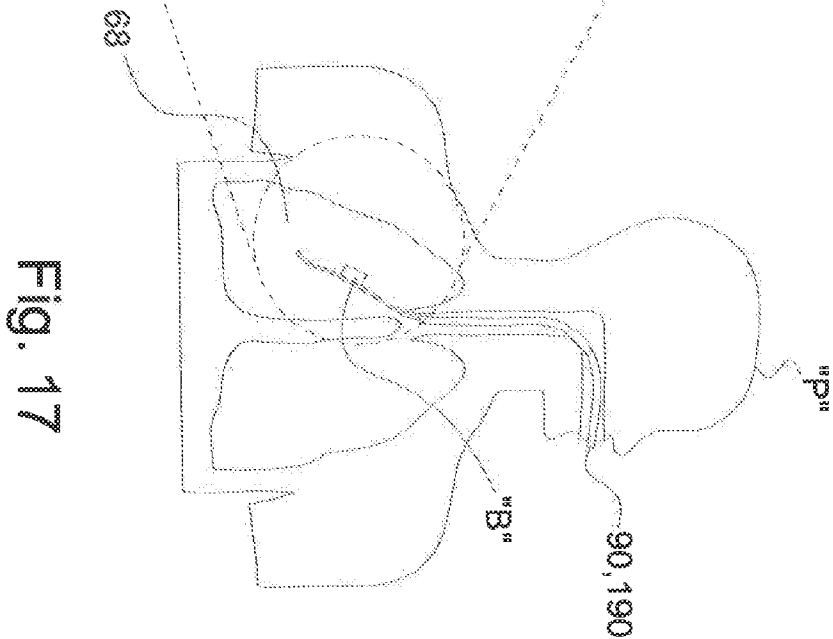


Fig. 17

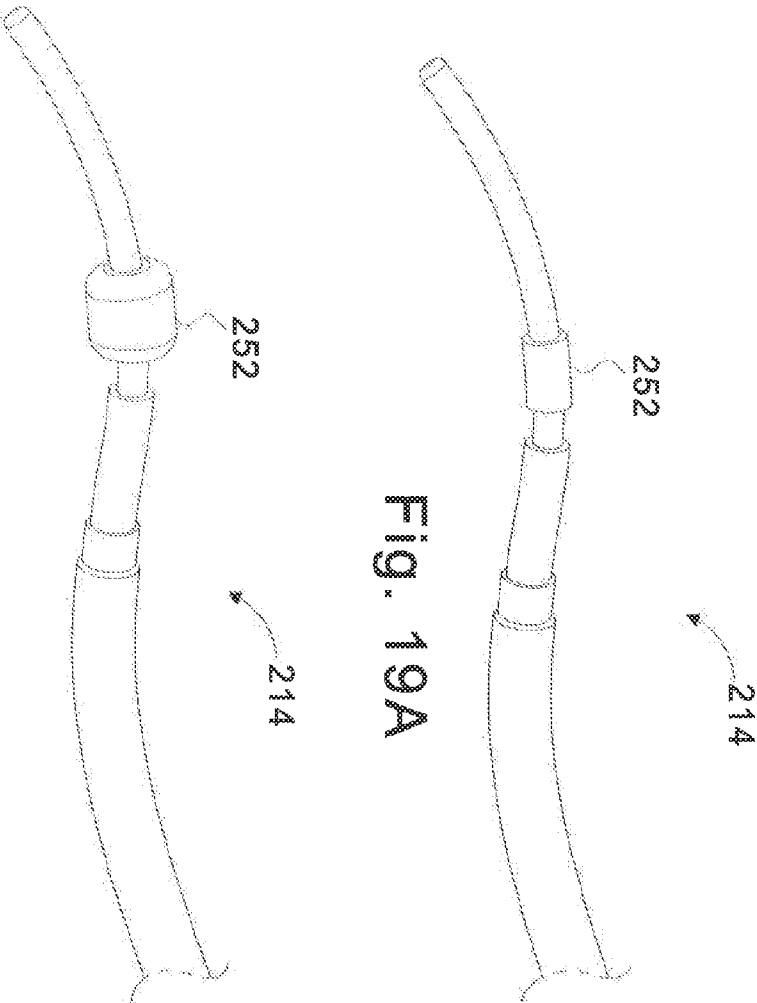


Fig. 19B

Fig. 19A

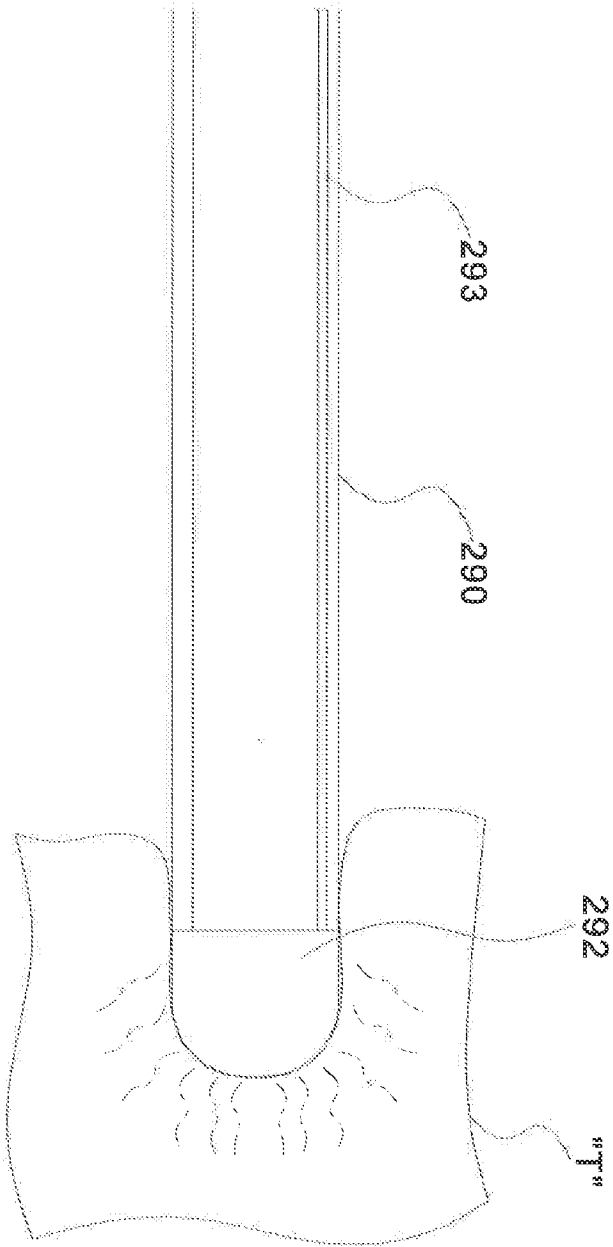


Fig. 20

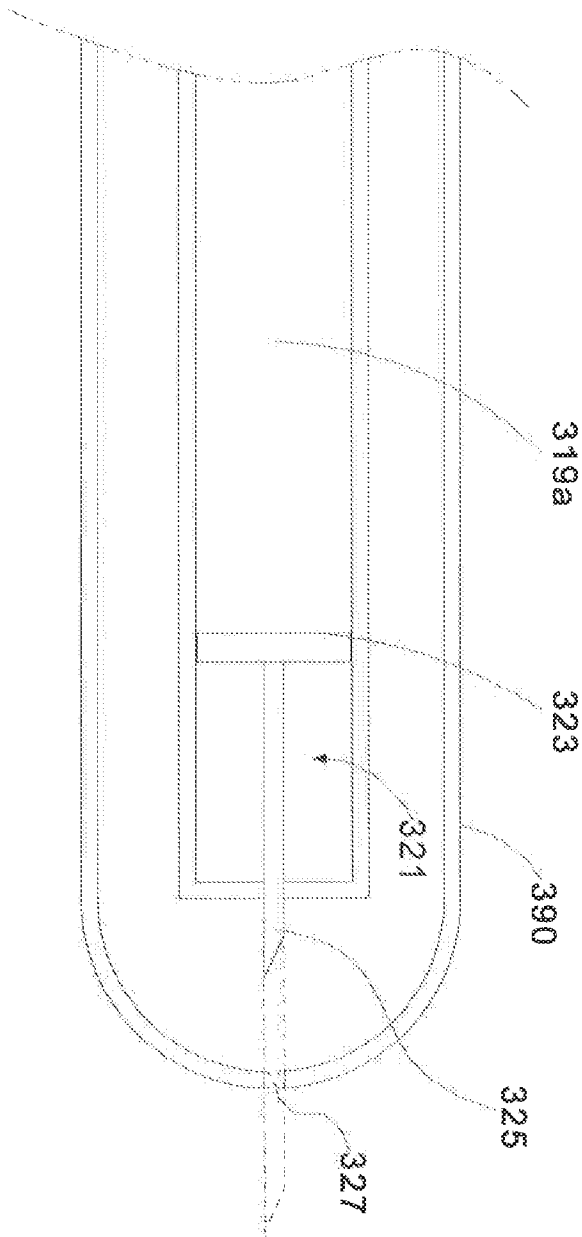
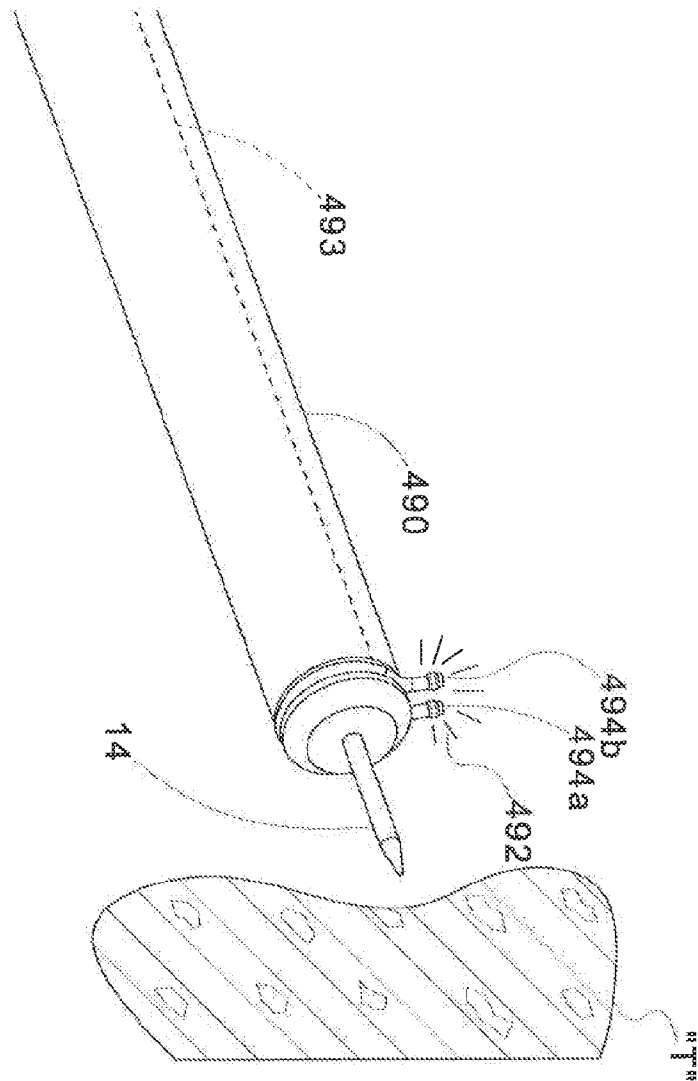
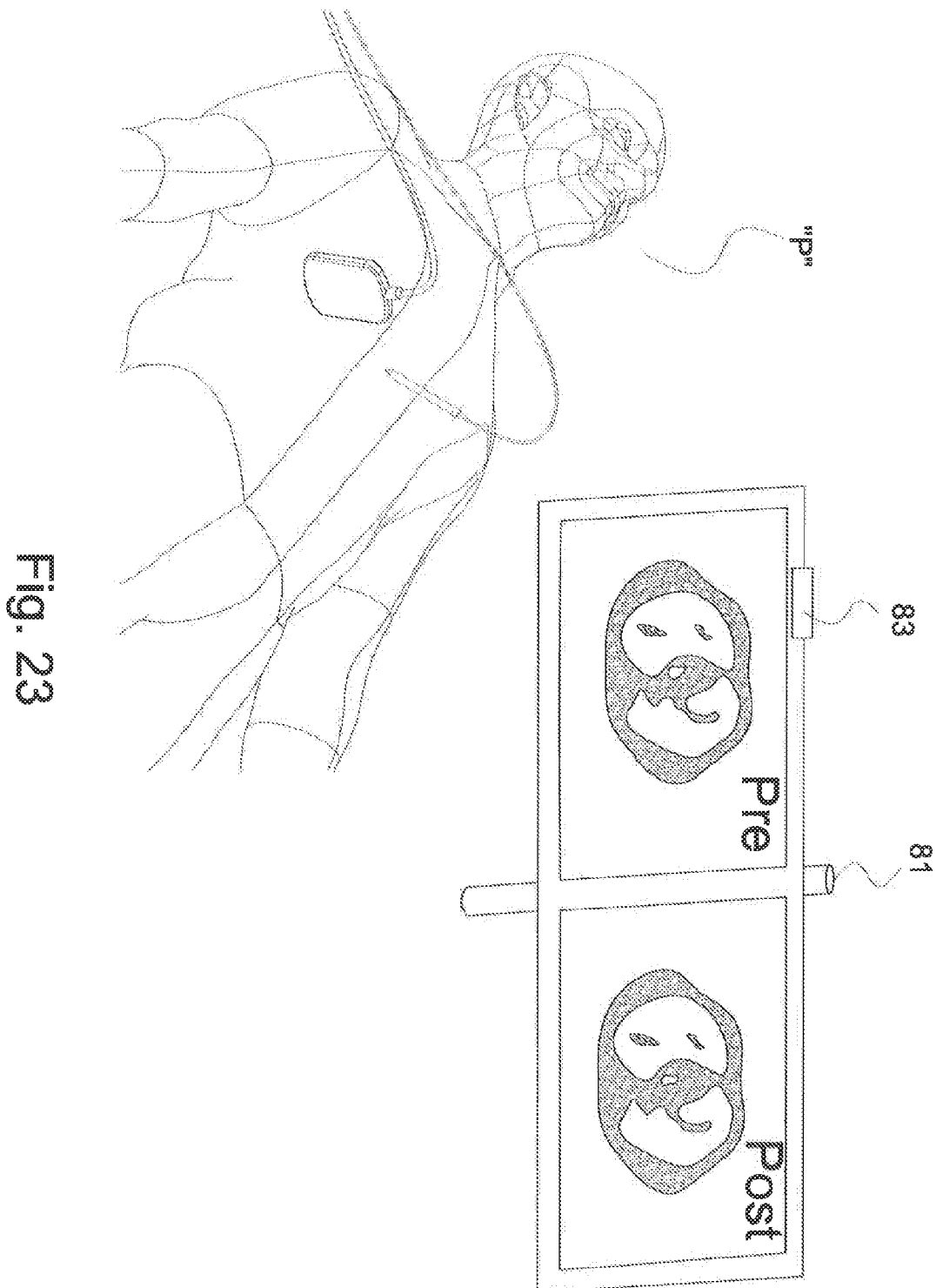


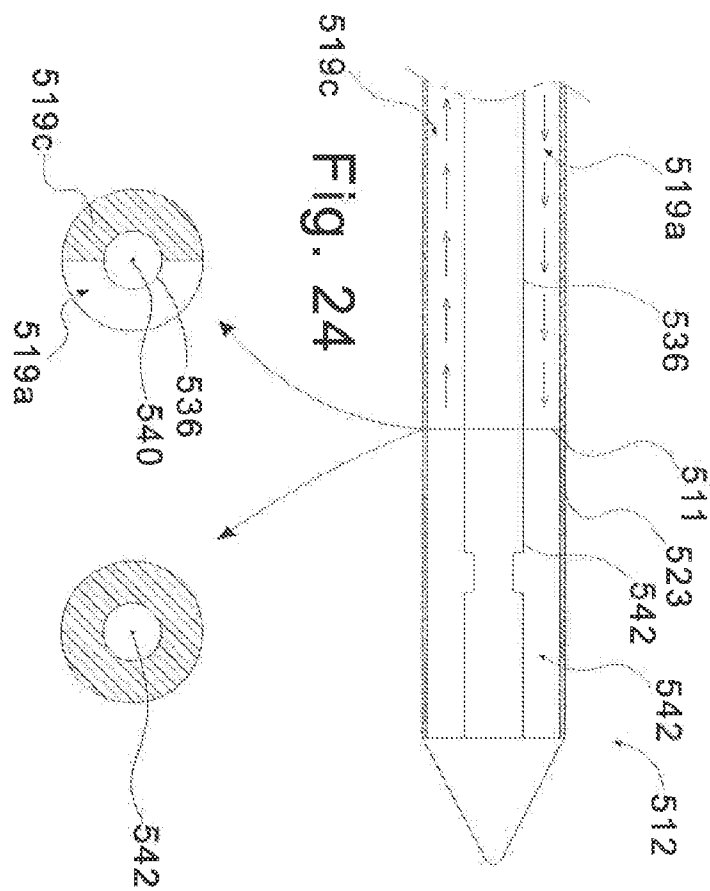
Fig. 21

Fig. 22









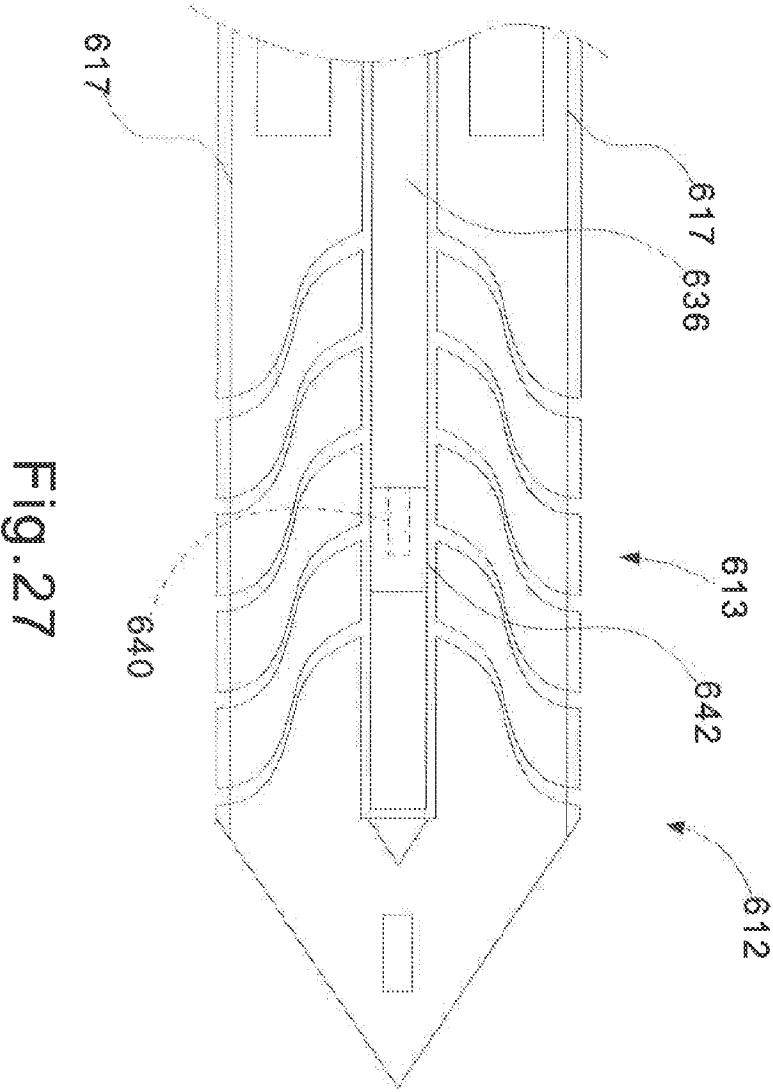
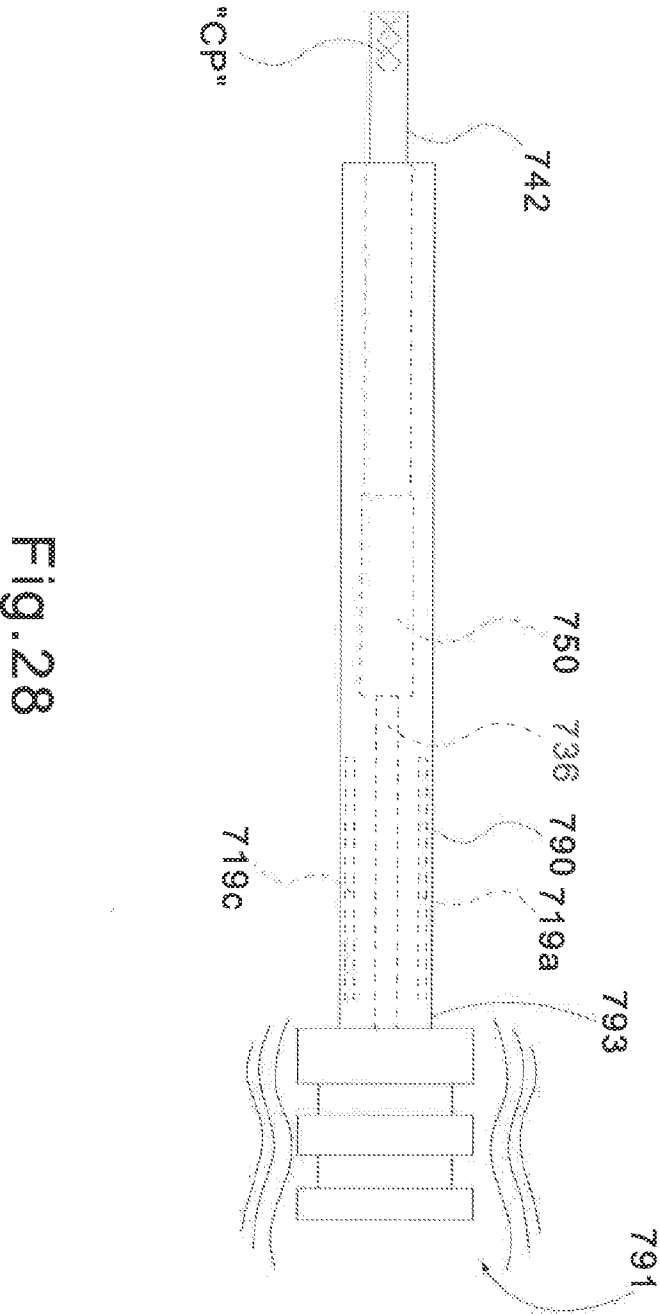


Fig. 27



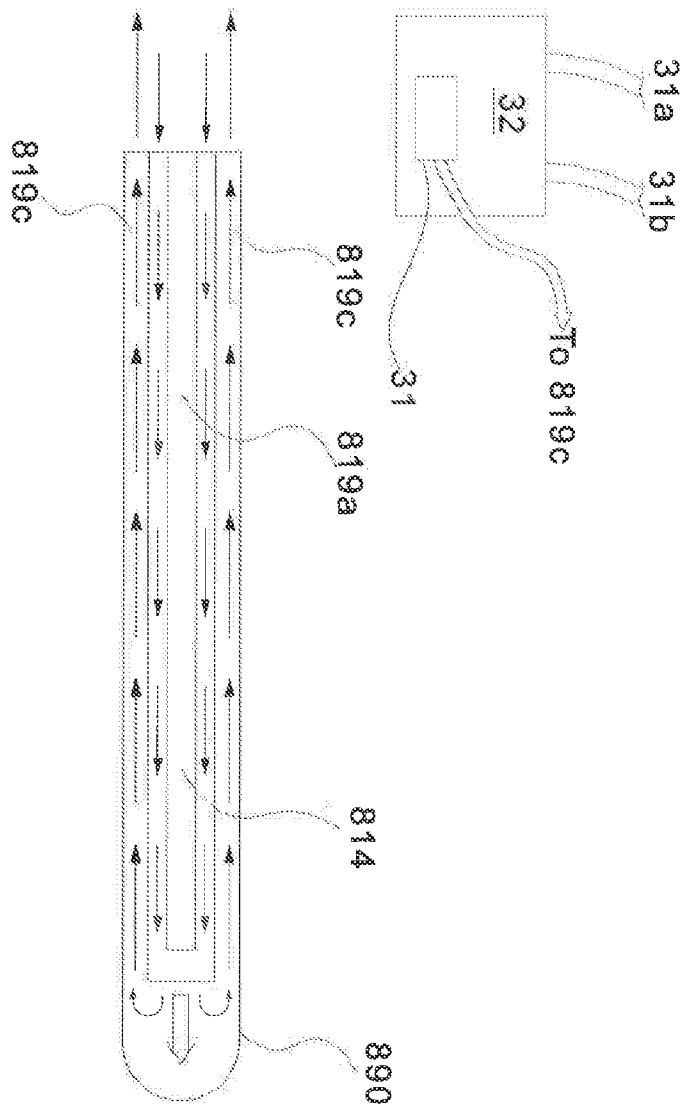
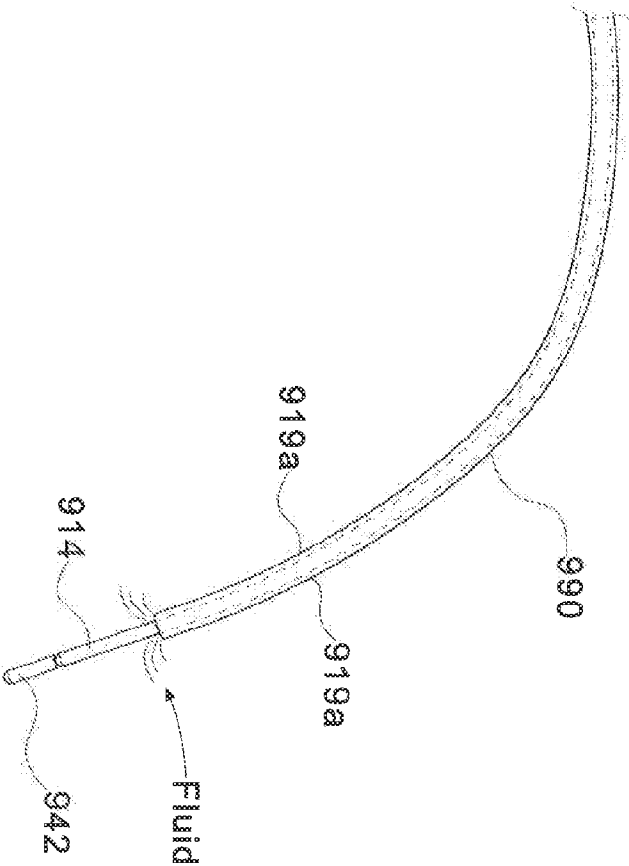


Fig.29

Fig.30



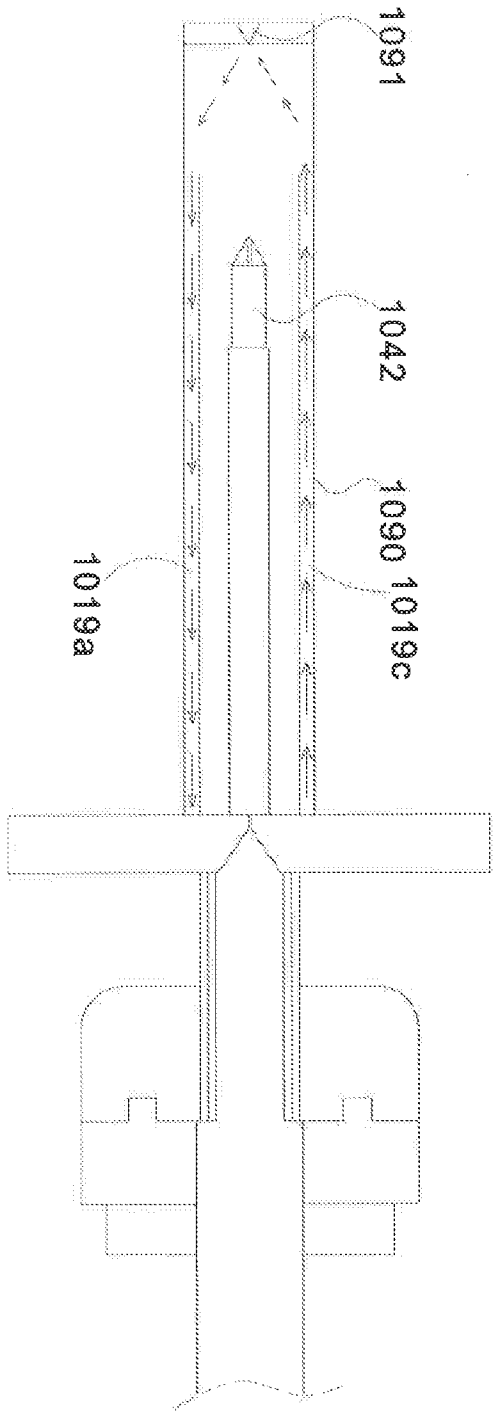


Fig. 31

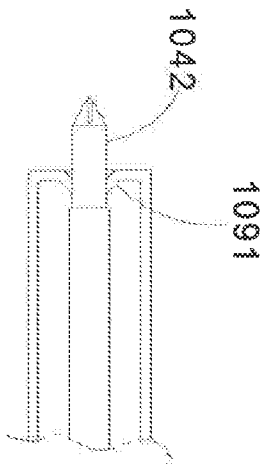


Fig. 32

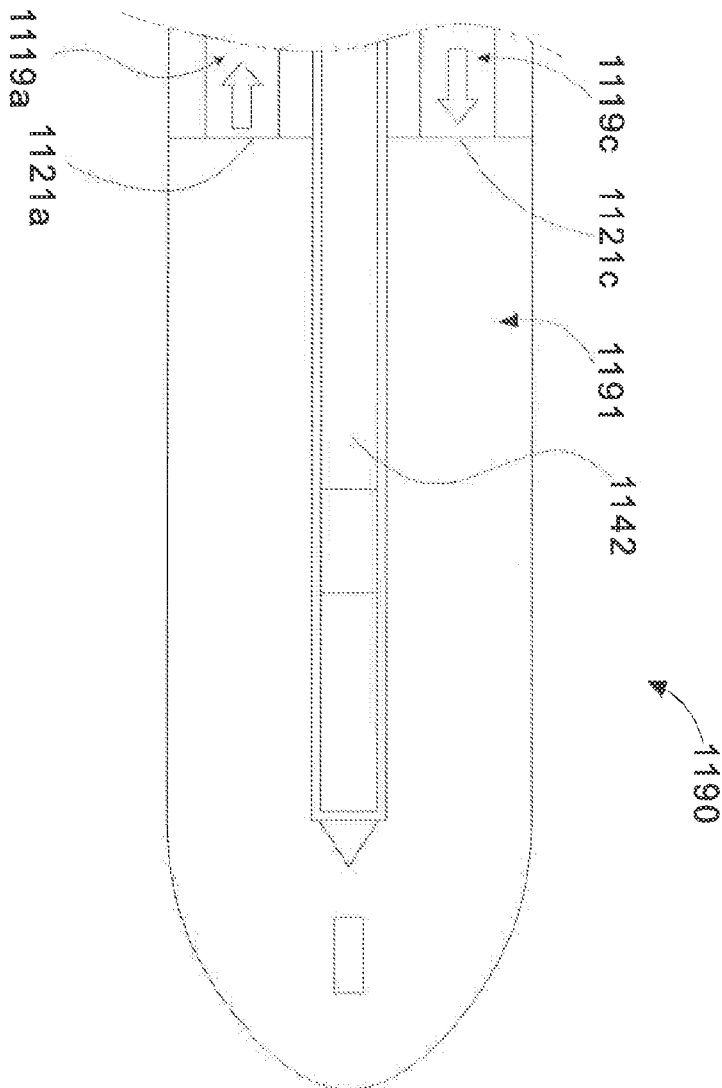


Fig. 33



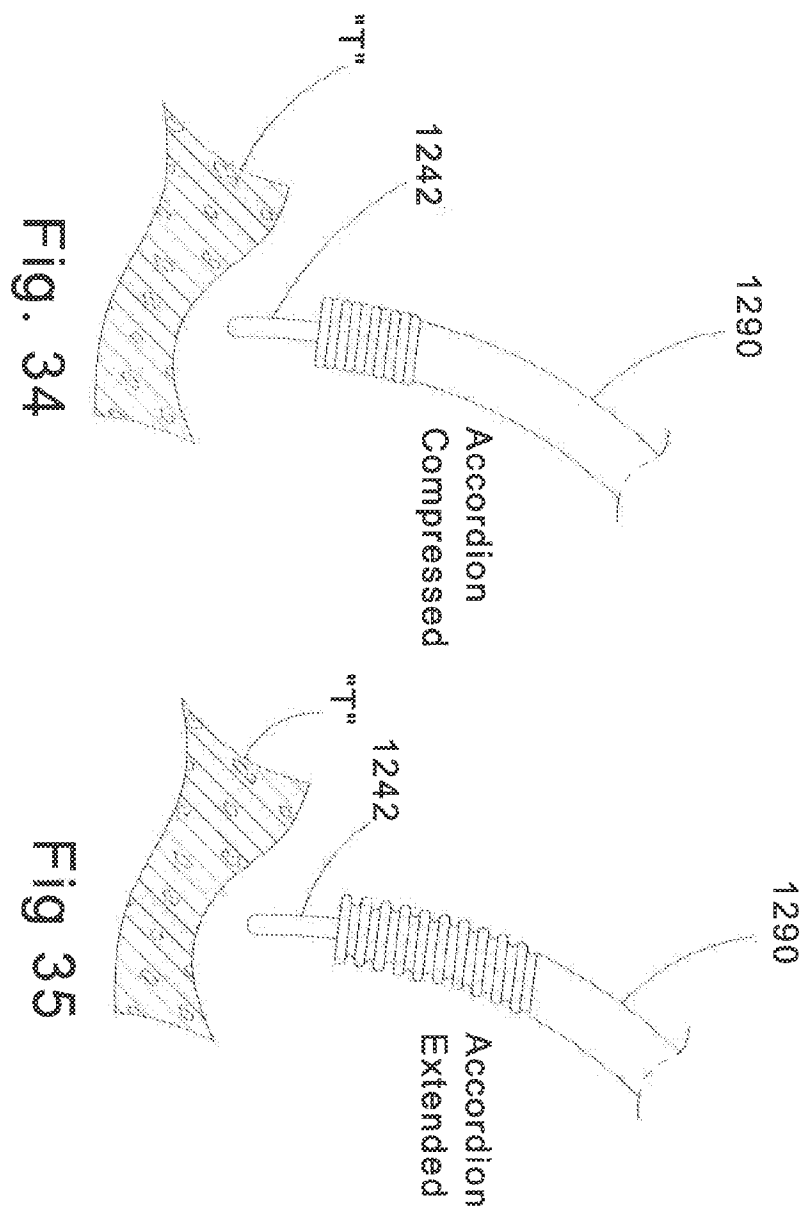


Fig. 36A

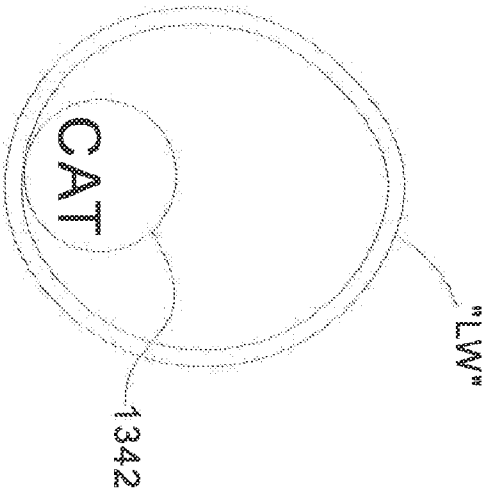


Fig. 36B

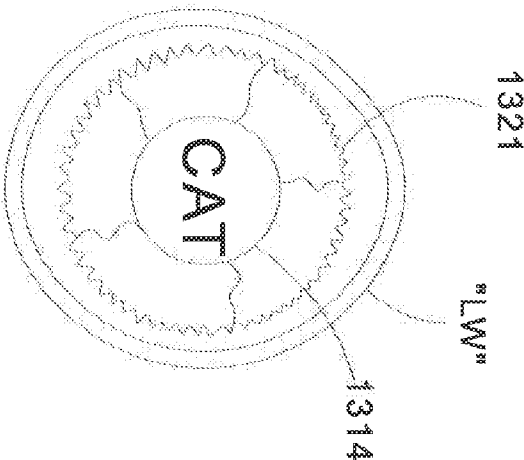


Fig.37A

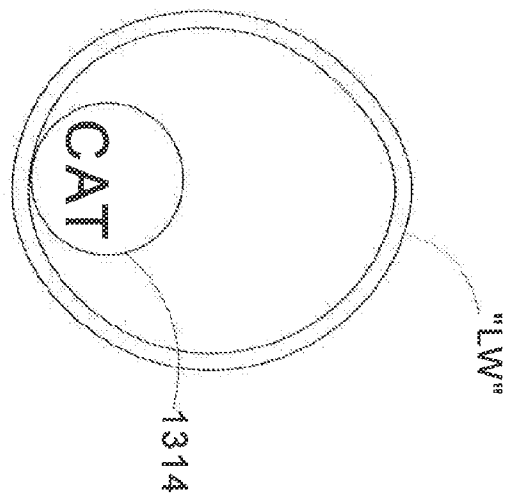
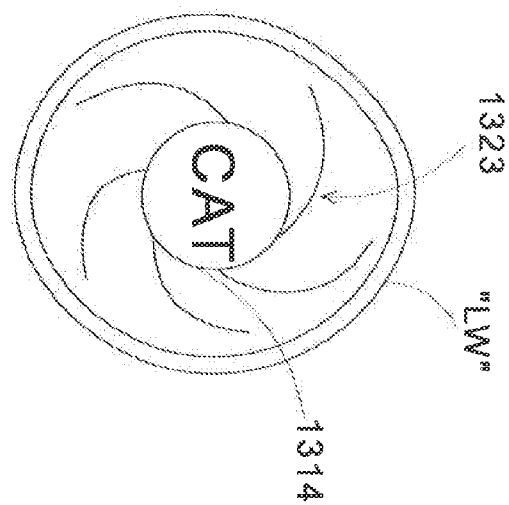


Fig.37B



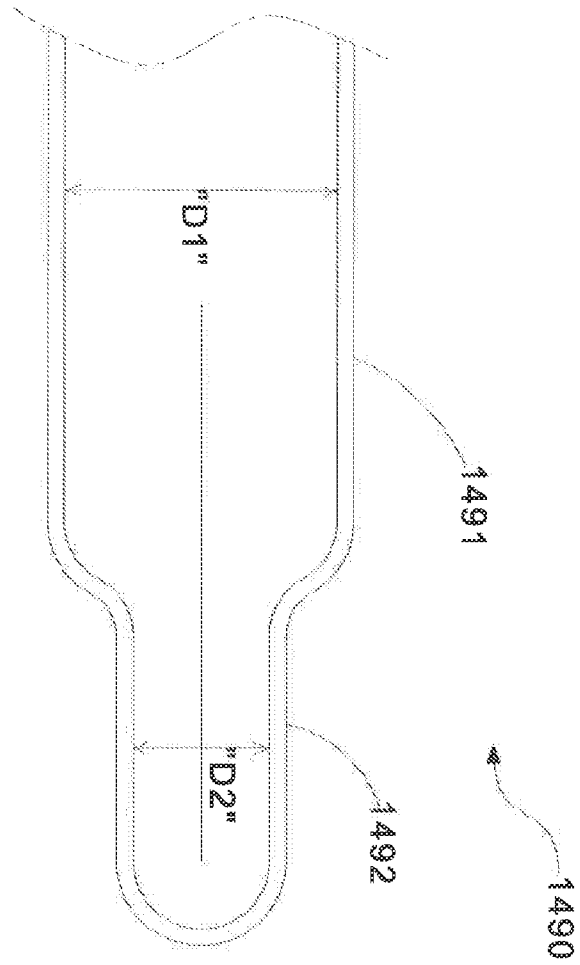
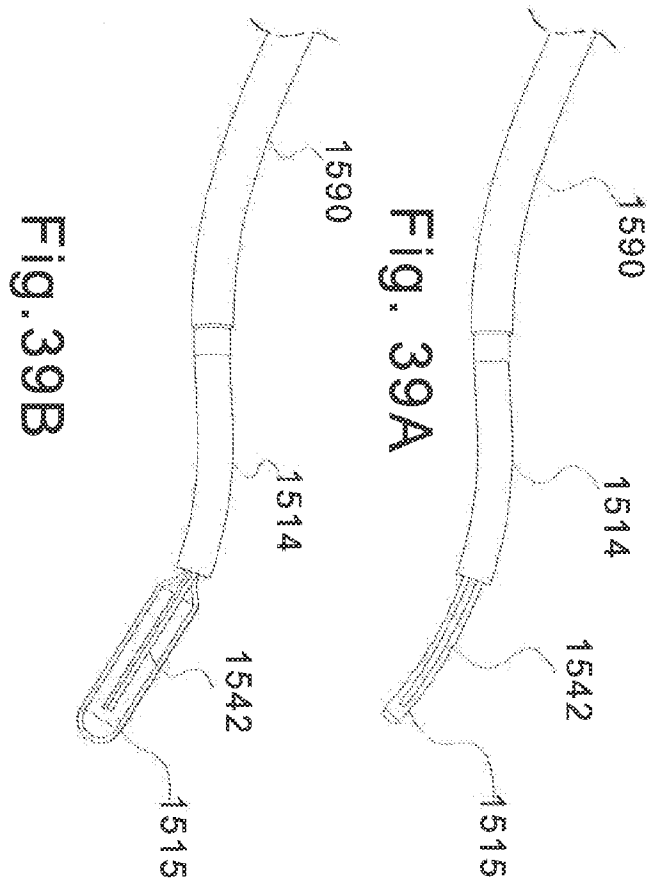


Fig. 38



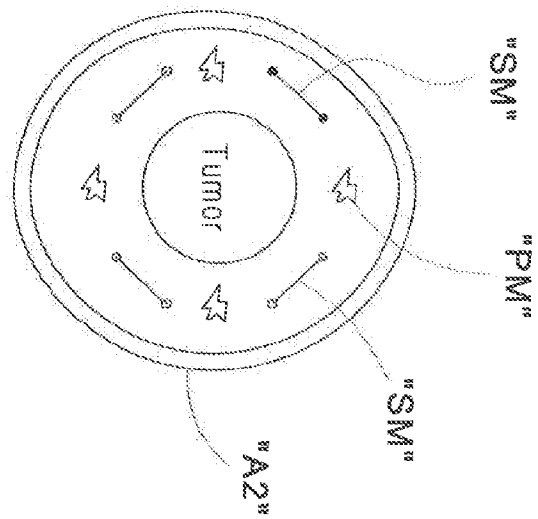


Fig. 40A

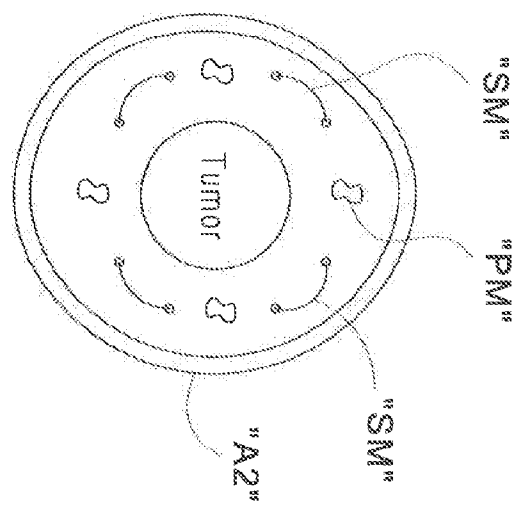
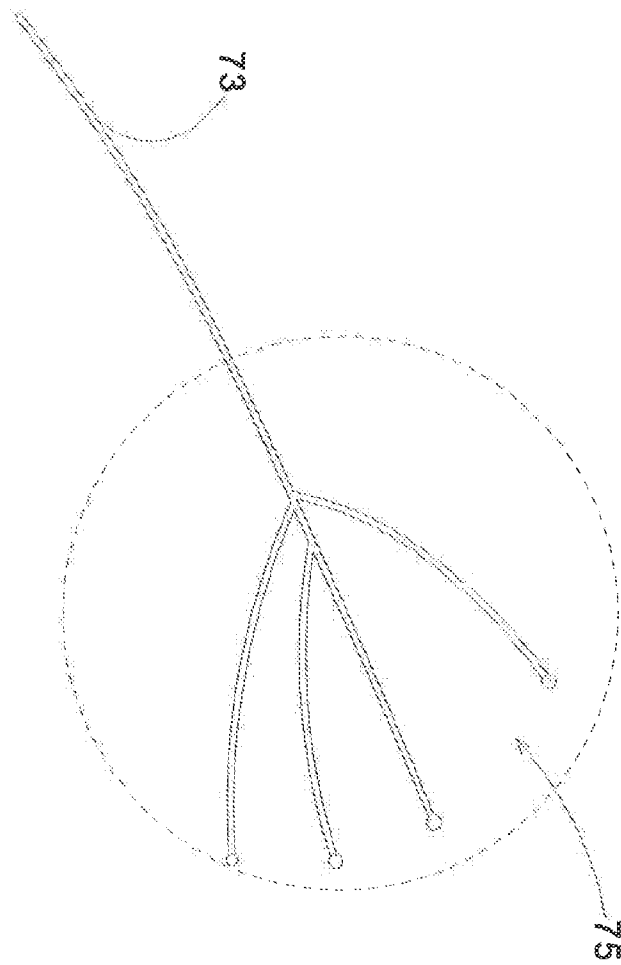
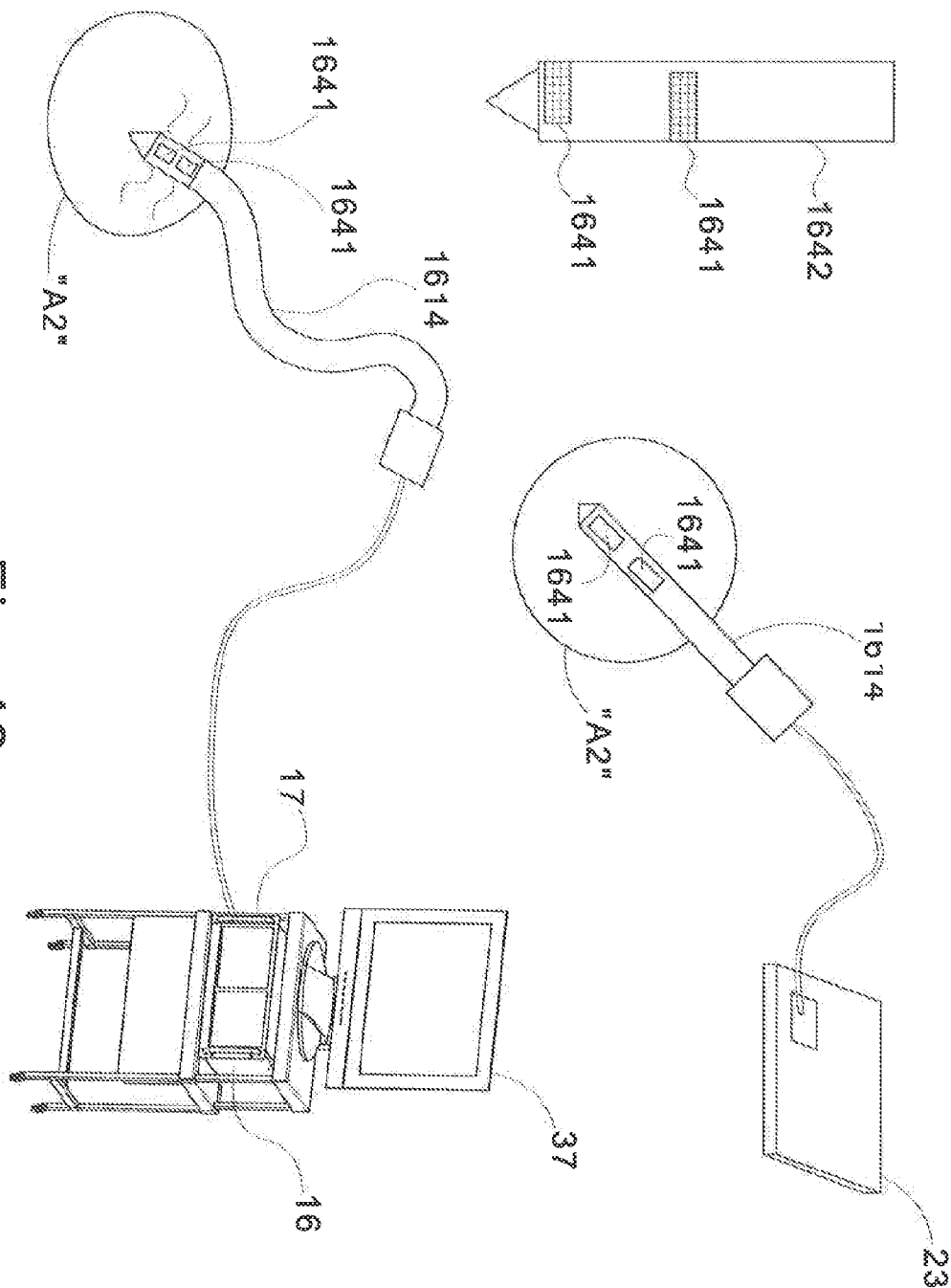


Fig. 40B

Fig. 41





7  
6  
4  
2



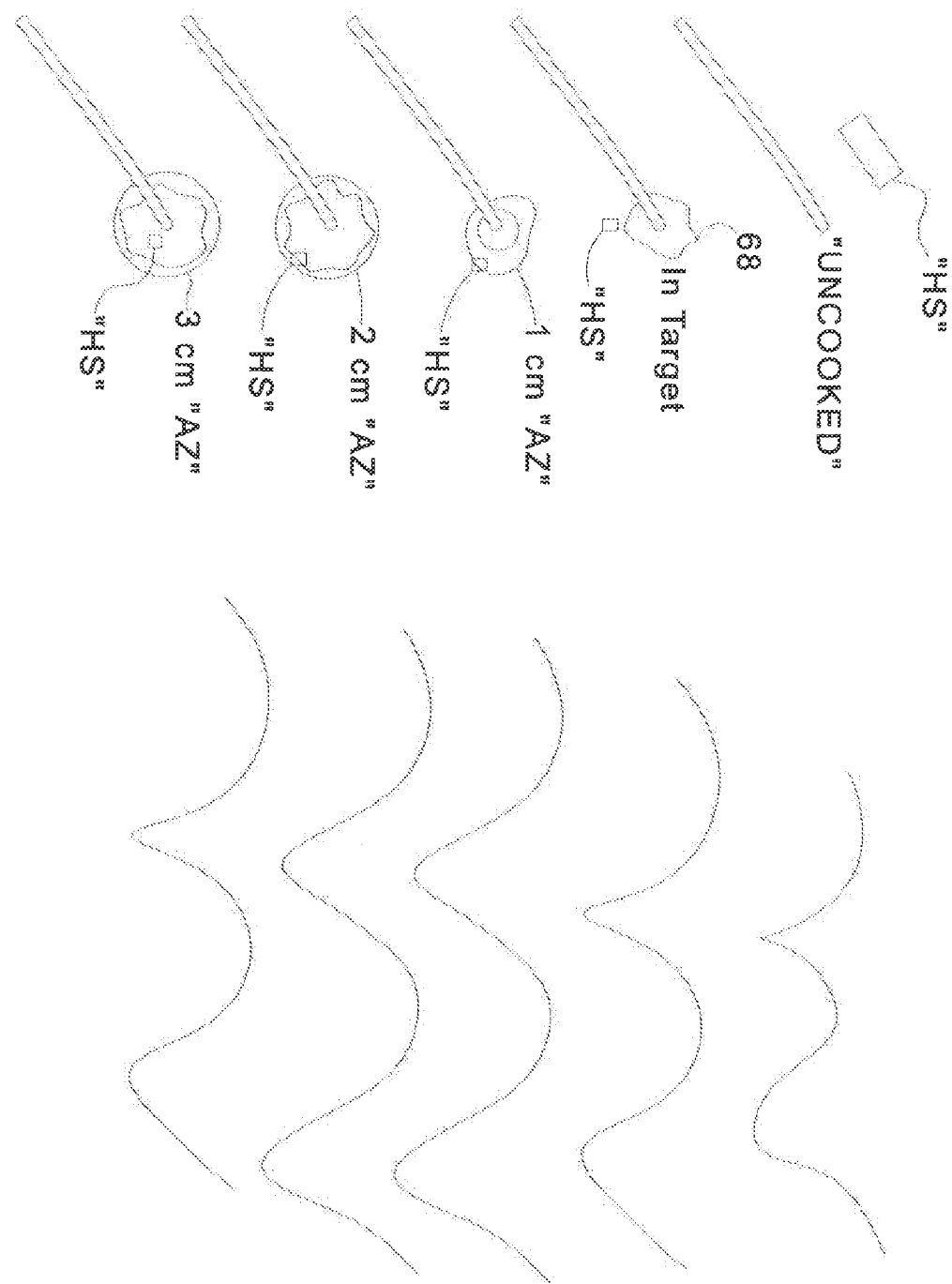
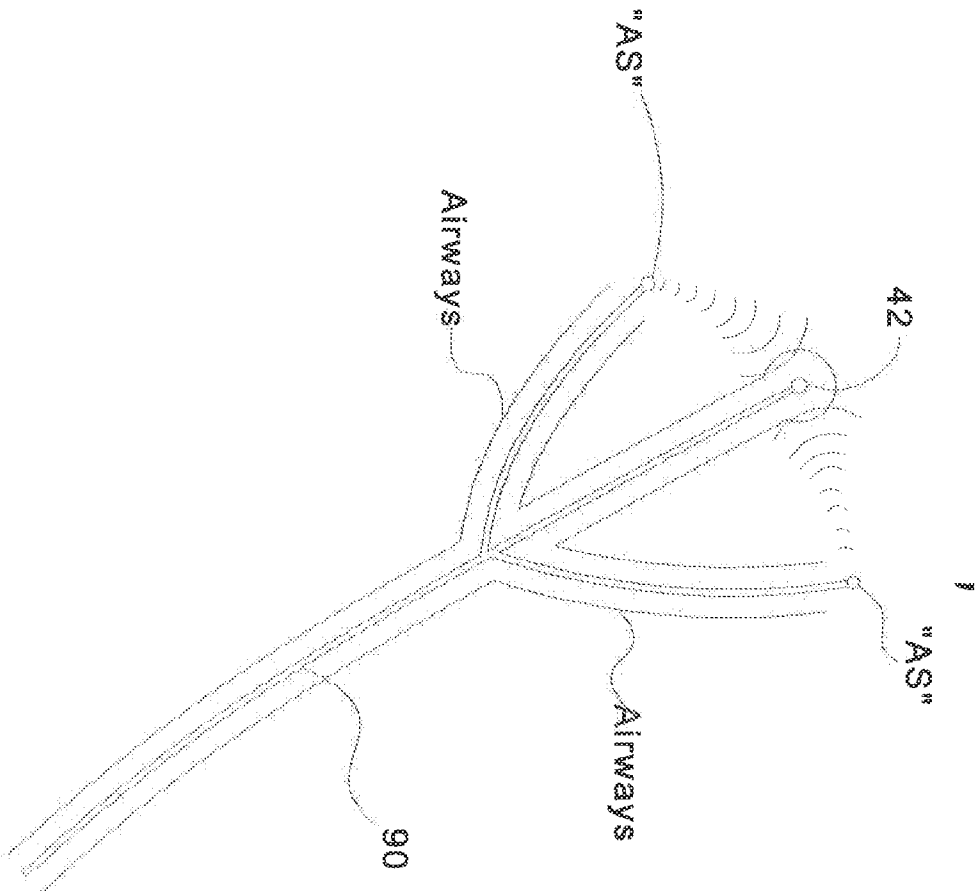


Fig. 43

Fig.44



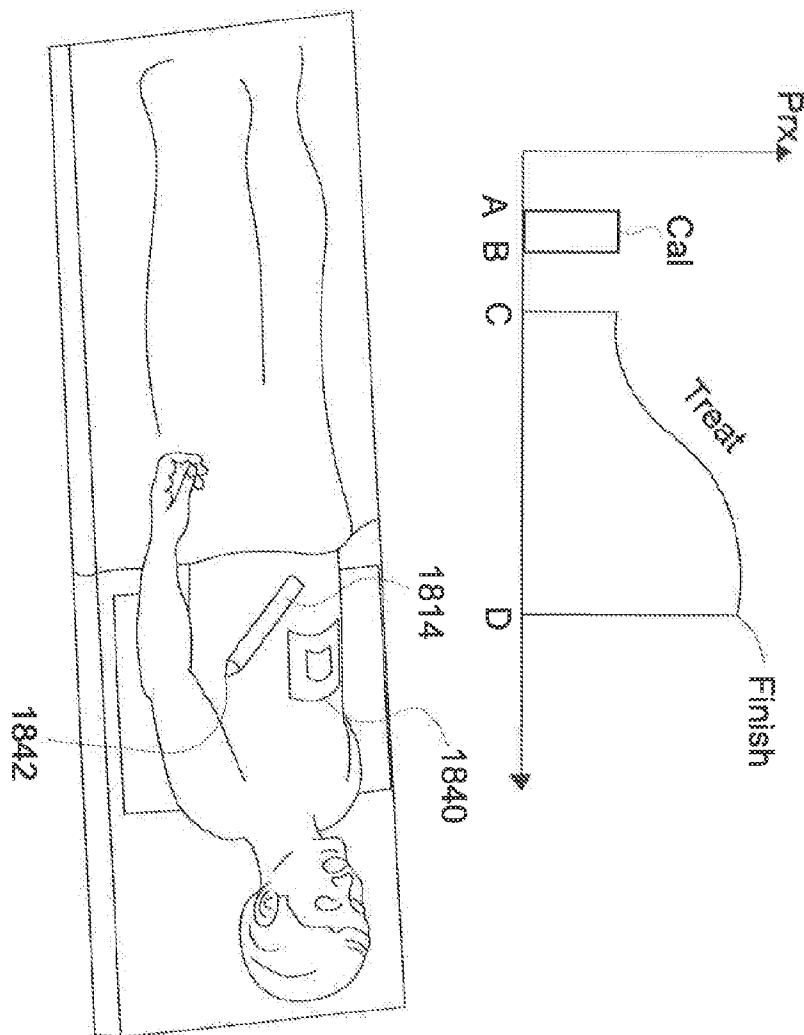


Fig. 45

Fig. 46A

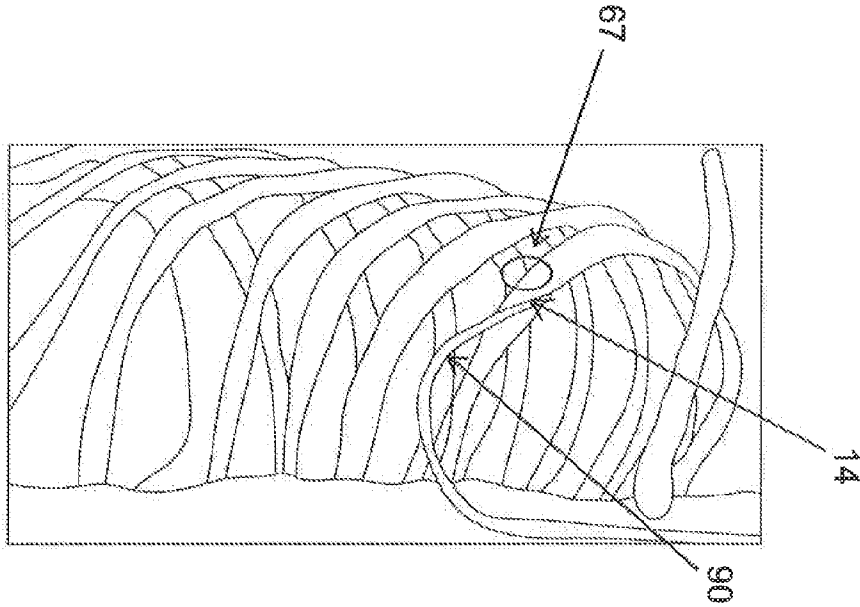
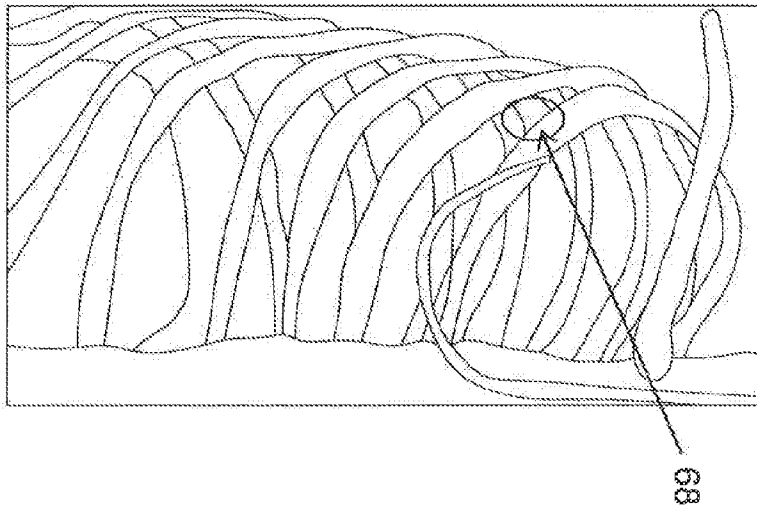


Fig. 46B



**A. CLASSIFICATION OF SUBJECT MATTER****A61M 25/16(2006.01)i, A61B 18/00(2006.01)i, A61B 17/225(2006.01)i**

According to International Patent Classification (IPC) or to both national classification and IPC

**B. FIELDS SEARCHED**

Minimum documentation searched (classification system followed by classification symbols)

A61M 25/16; A61N 1/39; A61M 31/00; A61M 37/00; A61K 9/127; A61B 18/18; A61B 18/00; A61B 17/225

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Korean utility models and applications for utility models

Japanese utility models and applications for utility models

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

**eKOMPASS(KIPO internal) & Keywords:** microwave, ablate, remove, catheter, lumen, channel, guide, navigate, balun, luminal, coolant, computed tomographic, CT**C. DOCUMENTS CONSIDERED TO BE RELEVANT**

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
Y	US 2010-0305559 A1 (BRANNAN, J. D. et al.) 2 December 2010 See abstract; claims 1, 7, 11; paragraphs [0029], [0033], [0036]; figures 2, 5A-5C.	1-20
Y	US 2007-0208301 A1 (EVARD, P. et al.) 6 September 2007 See abstract; claim 1; paragraph [0081]; figure 1A.	1-20
A	US 7559916 B2 (SMITH, K. W. et al.) 14 July 2009 See abstract; claim 1; figures 1-2.	1-20
A	US 8152795 B2 (FARR, N. E. et al.) 10 April 2012 See abstract; claim 1; figures 9-10.	1-20
A	US 2007-0077230 A1 (MON, J.) 5 April 2007 See abstract; paragraph [0077]; figure 1A-1.	1-20



Further documents are listed in the continuation of Box C.



See patent family annex.

\* Special categories of cited documents:

"A" document defining the general state of the art which is not considered to be of particular relevance

"E" earlier application or patent but published on or after the international filing date

"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of citation or other special reason (as specified)

"O" document referring to an oral disclosure, use, exhibition or other means

"P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

"&amp;" document member of the same patent family

Date of the actual completion of the international search

04 November 2013 (04.11.2013)

Date of mailing of the international search report

**04 November 2013 (04.11.2013)**

Name and mailing address of the ISA/KR

Korean Intellectual Property Office  
189 Cheongsa-ro, Seo-gu, Daejeon Metropolitan City,  
302-701, Republic of Korea

Facsimile No. +82-42-472-7140

Authorized officer

Han, Inho

Telephone No. +82-42-481-3362



**INTERNATIONAL SEARCH REPORT**

Information on patent family members

International application No.

**PCT/US2013/052187**

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
US 2010-0305559 A1	02/12/2010	AU 2010-202137 A1	16/12/2010
		CA 2705182 A1	27/11/2010
		EP 2255742 A1	01/12/2010
		JP 2010-274118 A	09/12/2010
		US 2013-085488 A1	04/04/2013
		US 8292881 B2	23/10/2012
US 2007-0208301 A1	06/09/2007	AU 2005-249376 A1	15/12/2005
		AU 2005-274794 A1	23/02/2006
		AU 2005-287050 A1	30/03/2006
		AU 2006-292818 A1	29/03/2007
		AU 2009-293312 A1	25/03/2010
		AU 2009-333010 A1	08/07/2010
		CA 2563711 A1	15/12/2005
		CA 2575361 A1	23/02/2006
		CA 2617054 A1	29/03/2007
		CA 2737804 A1	25/03/2010
		CA 2747982 A1	08/07/2010
		CN 101563019 A	21/10/2009
		CN 102159276 A	17/08/2011
		CN 102256658 A	23/11/2011
		EP 1744708 A2	24/01/2007
		EP 1778335 A2	02/05/2007
		EP 1778335 B1	12/06/2013
		EP 1789110 A2	30/05/2007
		EP 1789110 B1	07/08/2013
		EP 1838381 A2	03/10/2007
		EP 1879499 A2	23/01/2008
		EP 1896113 A2	12/03/2008
		EP 1916937 A2	07/05/2008
		EP 1926521 A2	04/06/2008
		EP 1991300 A2	19/11/2008
		EP 2024001 A2	18/02/2009
		EP 2024001 A4	09/03/2011
		EP 2068693 A2	17/06/2009
		EP 2068997 A2	17/06/2009
		EP 2068998 A2	17/06/2009
		EP 2068999 A2	17/06/2009
		EP 2185234 A1	19/05/2010
		EP 2258440 A2	08/12/2010
		EP 2258440 A3	02/11/2011
		EP 2263738 A2	22/12/2010
		EP 2263738 A3	09/11/2011
		EP 2263738 B1	05/06/2013
		EP 2323724 A1	25/05/2011
		EP 2373372 A1	12/10/2011
		EP 2491973 A1	29/08/2012
		EP 2491974 A1	29/08/2012
		EP 2508118 A1	10/10/2012

**INTERNATIONAL SEARCH REPORT**

Information on patent family members

International application No.

**PCT/US2013/052187**

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
		EP 2512578 A1	24/10/2012
		EP 2522272 A1	14/11/2012
		EP 2522386 A2	14/11/2012
		EP 2522386 A3	06/03/2013
		EP 2532300 A2	12/12/2012
		EP 2532300 A3	16/01/2013
		EP 2532383 A2	12/12/2012
		EP 2532383 A3	02/01/2013
		EP 2532384 A2	12/12/2012
		EP 2532384 A3	20/02/2013
		EP 2535079 A2	19/12/2012
		EP 2535079 A3	13/02/2013
		JP 03-181396 U	16/01/2013
		JP 2007-537784 A	27/12/2007
		JP 2008-508938 A	27/03/2008
		JP 2008-513125 A	01/05/2008
		JP 2009-500051 A	08/01/2009
		JP 2009-505691 A	12/02/2009
		JP 2012-192196 A	11/10/2012
		JP 2012-205930 A	25/10/2012
		JP 2012-502749 A	02/02/2012
		JP 2012-513253 A	14/06/2012
		JP 2013-078595 A	02/05/2013
		JP 2013-514829 A	02/05/2013
		KR 10-2011-0056409 A	27/05/2011
		KR 10-2011-0106413 A	28/09/2011
		US 2005-0240147 A1	27/10/2005
		US 2005-0245906 A1	03/11/2005
		US 2006-0004286 A1	05/01/2006
		US 2006-0004323 A1	05/01/2006
		US 2006-0063973 A1	23/03/2006
		US 2006-0095066 A1	04/05/2006
		US 2006-0106361 A1	18/05/2006
		US 2006-0210605 A1	21/09/2006
		US 2006-0284428 A1	21/12/2006
		US 2007-0129751 A1	07/06/2007
		US 2007-0135789 A1	14/06/2007
		US 2007-0167682 A1	19/07/2007
		US 2007-0208252 A1	06/09/2007
		US 2007-0249896 A1	25/10/2007
		US 2007-0270644 A1	22/11/2007
		US 2007-0282305 A1	06/12/2007
		US 2007-0293726 A1	20/12/2007
		US 2007-0293727 A1	20/12/2007
		US 2008-0015540 A1	17/01/2008
		US 2008-0082045 A1	03/04/2008
		US 2008-0097154 A1	24/04/2008
		US 2008-0097239 A1	24/04/2008
		US 2008-0097295 A1	24/04/2008
		US 2008-0097400 A1	24/04/2008

**INTERNATIONAL SEARCH REPORT**

Information on patent family members

International application No.

**PCT/US2013/052187**

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
		US 2008-0097514 A1	24/04/2008
		US 2008-0097515 A1	24/04/2008
		US 2008-0097516 A1	24/04/2008
		US 2008-0103361 A1	01/05/2008
		US 2008-0103521 A1	01/05/2008
		US 2008-0119693 A1	22/05/2008
		US 2008-0125626 A1	29/05/2008
		US 2008-0132938 A1	05/06/2008
		US 2008-0154237 A1	26/06/2008
		US 2008-0154250 A1	26/06/2008
		US 2008-0195041 A1	14/08/2008
		US 2008-0228085 A1	18/09/2008
		US 2008-0234720 A1	25/09/2008
		US 2008-0275483 A1	06/11/2008
		US 2008-0287908 A1	20/11/2008
		US 2008-0319424 A1	25/12/2008
		US 2009-0005763 A1	01/01/2009
		US 2009-0093823 A1	09/04/2009
		US 2009-0187098 A1	23/07/2009
		US 2009-0198216 A1	06/08/2009
		US 2009-0240112 A1	24/09/2009
		US 2009-0240237 A1	24/09/2009
		US 2009-0312745 A1	17/12/2009
		US 2010-0042046 A1	18/02/2010
		US 2010-0099946 A1	22/04/2010
		US 2010-0100181 A1	22/04/2010
		US 2010-0114066 A1	06/05/2010
		US 2010-0121308 A1	13/05/2010
		US 2010-0174138 A1	08/07/2010
		US 2010-0174308 A1	08/07/2010
		US 2010-0198247 A1	05/08/2010
		US 2010-0210901 A1	19/08/2010
		US 2010-0268245 A1	21/10/2010
		US 2010-0298862 A1	25/11/2010
		US 2011-0004057 A1	06/01/2011
		US 2011-0060214 A1	10/03/2011
		US 2011-0112512 A1	12/05/2011
		US 7361168 B2	22/04/2008
		US 7410480 B2	12/08/2008
		US 7419497 B2	02/09/2008
		US 7462175 B2	09/12/2008
		US 7500971 B2	10/03/2009
		US 7559925 B2	14/07/2009
		US 7641644 B2	05/01/2010
		US 7645272 B2	12/01/2010
		US 7654997 B2	02/02/2010
		US 7720521 B2	18/05/2010
		US 7727186 B2	01/06/2010
		US 7727226 B2	01/06/2010
		US 7771409 B2	10/08/2010



**INTERNATIONAL SEARCH REPORT**

Information on patent family members

International application No.

**PCT/US2013/052187**

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
		US 7785315 B1	31/08/2010
		US 7803150 B2	28/09/2010
		US 8080000 B2	20/12/2011
		US 8088101 B2	03/01/2012
		US 8090433 B2	03/01/2012
		US 8114062 B2	14/02/2012
		US 8123722 B2	28/02/2012
		US 8142422 B2	27/03/2012
		US 8146400 B2	03/04/2012
		US 8172828 B2	08/05/2012
		US 8414473 B2	09/04/2013
		US 8425457 B2	23/04/2013
		WO 2005-117755 A2	15/12/2005
		WO 2005-117755 A3	08/11/2007
		WO 2006-020180 A2	23/02/2006
		WO 2006-020180 A3	15/06/2006
		WO 2006-034008 A2	30/03/2006
		WO 2006-034008 A3	16/10/2008
		WO 2006-078884 A2	27/07/2006
		WO 2006-078884 A3	01/11/2007
		WO 2006-116597 A2	02/11/2006
		WO 2006-116597 A3	28/06/2007
		WO 2006-135853 A2	21/12/2006
		WO 2006-135853 A3	23/04/2009
		WO 2007-035204 A2	29/03/2007
		WO 2007-035204 A3	30/04/2009
		WO 2007-097924 A2	30/08/2007
		WO 2007-097924 A3	21/12/2007
		WO 2007-111636 A2	04/10/2007
		WO 2007-111636 A3	04/06/2009
		WO 2007-136584 A2	29/11/2007
		WO 2007-136584 A3	04/12/2008
		WO 2007-136589 A2	29/11/2007
		WO 2007-136589 A3	04/09/2008
		WO 2008-033179 A2	20/03/2008
		WO 2008-033179 A3	27/11/2008
		WO 2008-036148 A2	27/03/2008
US 7559916 B2	14/07/2009	EP 1804892 A2	11/07/2007
		US 2006-0069346 A1	30/03/2006
		US 2006-0211979 A1	21/09/2006
		US 2009-0299280 A1	03/12/2009
		US 2010-0280510 A1	04/11/2010
		US 7771411 B2	10/08/2010
		US 8083713 B2	27/12/2011
		US 8491520 B2	23/07/2013
		WO 2006-036915 A2	06/04/2006
		WO 2006-036915 A3	21/12/2006
		WO 2007-035931 A2	29/03/2007
		WO 2007-035931 A3	18/06/2009

**INTERNATIONAL SEARCH REPORT**

Information on patent family members

International application No.

**PCT/US2013/052187**

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
US 8152795 B2	10/04/2012	AU 1995-36269 B2	12/10/2000
		AU 2000-62151 A1	30/01/2001
		AU 2000-70762 A1	19/03/2001
		AU 2001-75938 A1	30/01/2002
		CA 2199384 A1	14/03/1996
		CA 2416242 A1	24/01/2002
		CA 2515029 A1	19/08/2004
		CN 1165485 A	19/11/1997
		EP 0781154 A2	30/03/2005
		EP 1200002 A2	02/05/2002
		EP 1200002 B1	12/04/2006
		EP 1301139 A1	16/04/2003
		EP 1527798 A2	04/05/2005
		EP 1527798 A3	04/04/2007
		EP 1592358 A2	09/11/2005
		EP 1679045 A2	12/07/2006
		EP 1679045 A3	30/09/2009
		EP 1679045 B1	27/03/2013
		EP 1866019 A1	19/12/2007
		JP 10-504989 A	19/05/1998
		JP 2003-518395 A	10/06/2003
		JP 2004-503326 A	05/02/2004
		JP 2006-516465 A	06/07/2006
		JP 2008-531086 A	14/08/2008
		KR 10-1997-0706039 A	03/11/1997
		US 2002-0068924 A1	06/06/2002
		US 2002-0077623 A1	20/06/2002
		US 2002-0183729 A1	05/12/2002
		US 2004-0006333 A1	08/01/2004
		US 2004-0059397 A1	25/03/2004
		US 2004-0147911 A1	29/07/2004
		US 2004-0147912 A1	29/07/2004
		US 2004-0147913 A1	29/07/2004
		US 2004-0167503 A1	26/08/2004
		US 2005-0065504 A1	24/03/2005
		US 2005-0171520 A1	04/08/2005
		US 2005-0222557 A1	06/10/2005
		US 2005-0222558 A1	06/10/2005
		US 2005-0234436 A1	20/10/2005
		US 2005-0234437 A1	20/10/2005
		US 2005-0267452 A1	01/12/2005
		US 2006-0253113 A1	09/11/2006
		US 2008-0195088 A1	14/08/2008
		US 2009-0221997 A1	03/09/2009
		US 2009-0275934 A1	05/11/2009
		US 2009-0299354 A1	03/12/2009
		US 2009-0326320 A1	31/12/2009
		US 5632767 A	27/05/1997
		US 5637877 A	10/06/1997
		US 5643253 A	01/07/1997

**INTERNATIONAL SEARCH REPORT**

Information on patent family members

International application No.

**PCT/US2013/052187**

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
		US 5908415 A	01/06/1999
		US 5947959 A	07/09/1999
		US 6102905 A	15/08/2000
		US 6168591 B1	02/01/2001
		US 6270492 B1	07/08/2001
		US 6423055 B1	23/07/2002
		US 6558375 B1	06/05/2003
		US 6572609 B1	03/06/2003
		US 6579285 B2	17/06/2003
		US 6626900 B1	30/09/2003
		US 6676656 B2	13/01/2004
		US 6942657 B2	13/09/2005
		US 6953457 B2	11/10/2005
		US 7207984 B2	24/04/2007
		US 7357796 B2	15/04/2008
		US 7935108 B2	03/05/2011
		US 8025661 B2	27/09/2011
		US 8241272 B2	14/08/2012
		US 8366705 B2	05/02/2013
		WO 01-03599 A2	18/01/2001
		WO 01-03599 A3	17/05/2001
		WO 01-13812 A1	01/03/2001
		WO 02-05722 A1	24/01/2002
		WO 2004-069072 A2	19/08/2004
		WO 2004-069072 A3	07/10/2004
		WO 2004-110258 A2	23/12/2004
		WO 2004-110258 A3	25/08/2005
		WO 2006-091597 A1	31/08/2006
		WO 2010-120881 A2	21/10/2010
		WO 2010-120881 A3	10/02/2011
		WO 2010-120883 A2	21/10/2010
		WO 2010-120883 A3	24/03/2011
		WO 96-07451 A3	23/05/1996
US 2007-0077230 A1	05/04/2007	CA 2602065 A1	28/09/2006
		EP 1877089 A2	16/01/2008
		US 2006-0216275 A1	28/09/2006
		US 8476242 B2	02/07/2013
		WO 2006-102471 A2	28/09/2006
		WO 2006-102471 A3	23/08/2007