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(54) Title: A JAM DETECTING DEVICE, A METHOD FOR DETECTING DEFECTIVE PACKAGES IN A FILLING MACHINE, A FOLDING UNIT FOR PRODUCING PACKAGES OF POURABLE FOOD PRODUCTS IN A FILLING MACHINE, AND A FILLING MACHINE

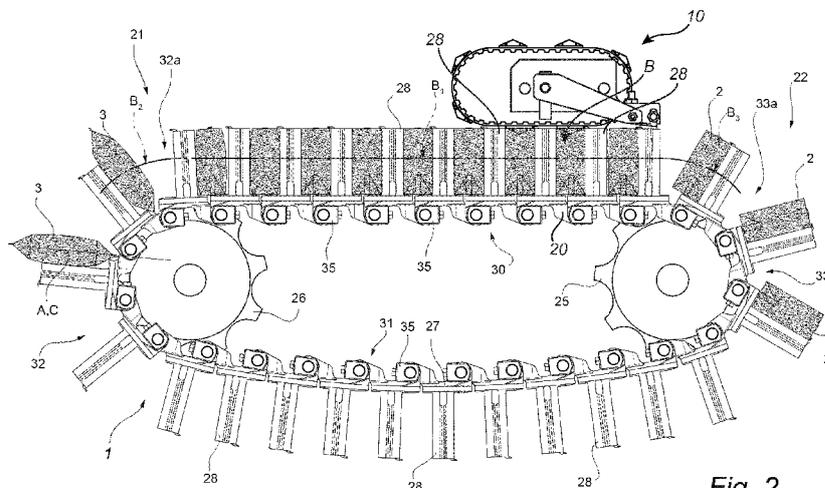


Fig. 2

(57) Abstract: The invention relates to a jam detecting device (10) for detecting defective packages in a filling machine. The jam detecting device (10) comprises a movable element (12), and a sensor (13) connected to the movable element (12). The jam detecting device (10) is adapted to be positioned in the filling machine such that any defective package will mechanically raise the movable element (12) when passing the same and thereby trigger the sensor (13). The invention also relates to a method for detecting defective packages in a filling machine, and a folding unit (1) and a filling machine for producing packages (2) of pourable food products from sealed packs (3).

A JAM DETECTING DEVICE, A METHOD FOR DETECTING DEFECTIVE PACKAGES IN A FILLING MACHINE, A FOLDING UNIT FOR PRODUCING PACKAGES OF POURABLE FOOD PRODUCTS IN A FILLING MACHINE, AND A FILLING MACHINE

Technical field

The invention relates to a jam detecting device and a method for detecting defective packages in a filling machine. The invention is also related to a folding unit
5 and a filling machine for producing packages of pourable food products from sealed packs.

Background art

As is known, many food products, such as fruit
10 juice, pasteurized or UHT (ultra-high-temperature treated) milk, wine, tomato sauce, etc., are sold in packages made of sterilized packaging material.

A typical example of this type of package is the parallelepiped-shaped package for liquid or pourable food
15 products known as Tetra Brik Aseptic (registered trademark), which is made by folding and sealing laminated strip packaging material.

The packaging material has a multilayer structure substantially comprising a base layer for stiffness and
20 strength, which may comprise a layer of fibrous material, e.g. paper, or of mineral-filled polypropylene material, and a number of layers of heat-seal plastic material, e.g. polyethylene film, covering both sides of the base layer.

25 In the case of aseptic packages for long-storage products, such as UHT milk, the packaging material also comprises a layer of gas- and light-barrier material, e.g. aluminium foil or ethyl vinyl alcohol (EVOH), which

is superimposed on a layer of heat-seal plastic material, and is in turn covered with another layer of heat-seal plastic material forming the inner face of the package eventually contacting the food product.

5 As is known, packages of this sort are produced on fully automatic packaging machines, on which a continuous tube is formed from the web-fed packaging material, the web of packaging material is sterilized on the packaging machine, e.g. by applying a chemical sterilizing agent,
10 such as a hydrogen peroxide solution, which, once sterilization is completed, is removed from the surfaces of the packaging material, e.g. evaporated by heating, and the web of packaging material so sterilized is maintained in a closed, sterile environment, and is
15 folded and sealed longitudinally to form a vertical tube.

The tube is filled continuously downwards with the sterilized or sterile-processed food product, and is sealed and then cut along equally spaced cross sections to form pillow packs, which are then fed to a folding
20 unit to form the finished packages, e.g. substantially parallelepiped-shaped packages.

More specifically, the pillow packs substantially comprise a parallelepiped-shaped main portion, and opposite top and bottom end portions projecting laterally
25 on opposite sides of the main portion and defining respective triangular end flaps to be folded onto the main portion.

A longitudinal sealing strip, formed when sealing the packaging material to form the vertical tube, extends
30 along the pillow packs, and the end portions of each pillow pack have respective transverse sealing strips perpendicular to the relative longitudinal sealing strip

and defining respective end tabs projecting from the top and bottom of the pack.

The end portions of each pillow pack taper towards the main portion from the respective end tabs, and are
5 pressed towards each other by the folding unit to form flat opposite end walls of the pack, while at the same time folding the end flaps onto respective walls of the main portion.

Packaging machines of the above type are known which
10 comprises a folding unit where pillow packs are turned into folded packages by folding means, and a transferring and up-ending unit for tipping the folded packages.

The folding unit substantially comprises a chain conveyor feeding the pillow packs along a forming path
15 from a supply station to an output station, a fixed elongated guide member, which is positioned facing and at a distance from the chain conveyor and cooperates cyclically with each pillow pack to flatten a first end portion of the pillow pack and so fold respective tab
20 onto such first end portion, and folding elements cooperating cyclically with each pillow pack to flatten a second end portion of the pillow pack and so fold respective tab onto such second end portion.

The transferring and up-ending unit is arranged
25 downstream from the folding unit. The transferring and up-ending unit transfers the packages successively along a conveying path from an in-feed station to an out-feed station, and simultaneously up-ends the packages from an in-feed position, in which the packages are positioned
30 with their axis tilted to the horizontal, into an out-feed position, in which the packages are positioned with their axis substantially vertical.

The transferring and up-ending unit receives the packages at the in-feed station from the chain conveyor of the folding unit, and feeds them to a further conveyor at the out-feed station.

5 More specifically, the chain conveyor supplies the unit with packages in the in-feed position, and the further conveyor withdraws the packages from the unit in the out-feed position.

The transferring and up-ending unit substantially
10 comprises a rotary member having a number of push arms which cooperate with respective packages to remove the packages from the folding unit and push the packages along the conveying path. The transferring and up-ending unit further comprises a fixed guide extending
15 substantially along the conveying path and cooperating with the packages to ease them from the tilted in-feed position to the out-feed position.

More specifically, the conveying path along which the packages are fed is substantially in the form of an
20 arc of circumference, at the end of which, the packages are fed to the further conveyor.

A drawback of the known packaging machines is that it may be difficult to control the transfer of the packages from the folding unit to the transferring and
25 up-ending unit, especially at high output rates of the packaging machines, i.e. when the packages are advanced at high speed.

If the packages carried by the chain conveyor of the folding unit are not in the right position when the push
30 arms of the transferring and up-ending unit interact with them, the push arms are not able to remove the packages from the folding unit in the proper way. In this case, package jams may occur that lead to packaging machine

stops, and so to a reduction of the packaging machine efficiency.

Another potential problem is the presence of defective packages. If a defective package is out-fed
5 from the folding unit to the transferring and up-ending unit, there is a risk of breakage of the push arms or other parts of the unit.

Summary of the invention

10 It is an object of the present invention to mitigate, alleviate or eliminate one or more of the above-identified deficiencies in the art and disadvantages singly or in any combination and solve at least the above mentioned problem.

15 According to a first aspect, these and other objects are achieved in full, or at least in part, by a jam detecting device for detecting defective packages in a filling machine. The jam detecting device comprises a
20 movable element and a sensor connected to the movable element. The sensor is triggered by movement of the movable element due to mechanical impact from a passing defective package. More in detail, the jam detecting device is positioned in the filling machine such that any defective package passing the movable element will
25 mechanically raise the same and thereby trigger the sensor.

Owing to the jam detecting device, it is possible to detect any defective package in the filling machine and directly trigger the sensor which in turn may initiate an
30 immediate stop of the filling machine, or at least a part, or unit, of the filling machine. In this way, it will also be possible to better locate the underlying problem that caused the defective package.

The jam detecting device is preferably arranged at the output station of the folding unit of the filling machine. Such an arrangement will make it possible to prevent defective packages from reaching the transferring
5 and up-ending unit of the filling machine and thus minimize the risk of breakage of the push arms or other parts of the unit.

The jam detecting device will also to some extent give information about some of the components arranged
10 upstream of the same in the filling machine, which may have caused the defect in the packages, such as, for example the sharpness of the knives of the forming unit in which the packs have been formed, etc.

The jam detecting device may further comprise a
15 shaft element arranged in connection with the movable element to ensure a free movement of the movable element. The movable element may be rotationally attached to the shaft.

The jam detecting device may further comprise an
20 adjustment element adapted to adjust a maximum clearance between the movable element and any non-defective packages passing the same, in order to control the sensitivity of the jam detecting device.

The jam detecting device may further comprise a
25 control unit connected to the sensor. In turn, the control unit may be adapted to stop at least a part, or unit, of the filling machine when the sensor is triggered. The sensor is preferably constituted by an optical sensor or an inductive sensor. Also, the jam
30 detecting device may further comprise a connector through which the sensor is connected to the jam detecting device in order to facilitate replacement of the sensor.

According to a second aspect of the invention, the objects are achieved in full, or at least in part, by a folding unit for a filling machine for producing packages of pourable food products from sealed packs. The folding
5 unit comprises a movable conveying member, and folding means arranged for folding at least one end portion of said packs, whilst the packs are conveyed by the conveying member, to obtain said packages. The conveying member carries a plurality of plates, each plate being
10 configured to receive a pack and to deliver a package to a transferring and up-ending unit arranged downstream of the folding unit. The folding unit is characterised in that it further comprises a jam detecting device as described above.

15 The jam detecting device is preferably arranged at an output station of the folding unit. More specifically, the jam detecting device may be arranged downstream a top squeezer belt and upstream a top brush of the folding unit.

20 Furthermore, the movable element of the jam detecting device may be arranged above the uppermost plates of the conveying member in the folding unit. More specifically, the movable element of the jam detecting device may be arranged at a predetermined distance from
25 the uppermost plates to create a clearance between the movable element and any non-defective packages passing the same.

According to a third aspect of the invention, the objects are achieved in full, or at least in part, by a
30 filling machine for producing packages of pourable food products from sealed packs, comprising a jam detecting device as described above or a folding unit as described above.

According to a fourth aspect of the invention, the objects are achieved in full, or at least in part, by a method for controlling the operation of a filling machine for producing packages of pourable food products. The method comprises the steps of detecting any defective package by means of a sensor triggered by movement of a movable element due to mechanical impact from a passing defective package, and stopping at least a part of the filling machine based on information from the sensor.

Generally, all terms used in the claims are to be interpreted according to their ordinary meaning in the technical field, unless explicitly defined otherwise herein. All references to "a/an/the [element, device, component, means, step, etc.]" are to be interpreted openly as referring to at least one instance of the element, device, component, means, step, etc., unless explicitly stated otherwise.

Brief description of the drawings

The above objects, as well as additional objects, features and advantages of the present invention, will be more fully appreciated by reference to the following illustrative and non-limiting detailed description of preferred embodiments of the present invention, when taken in conjunction with the accompanying drawings, wherein:

Figure 1 is a perspective view of a jam detecting device according to one exemplary embodiment of a first aspect of the present invention.

Figure 2 is a side view of a folding unit according to one exemplary embodiment of a second aspect of the present invention.

Figure 3 is a partial side view of the folding unit and of a transferring and up-ending unit, with parts removed for clarity.

Figure 4 is a partial perspective view of the
5 folding unit and of the transferring and up-ending unit of Figure 3, with parts removed for clarity.

Detailed description of preferred embodiments of the invention

10 Figure 1 illustrates a jam detecting device 10 for detecting defective packages in a filling machine according to one exemplary embodiment of the invention. The jam detecting device 10 comprises a movable element 12 and a sensor 13 which is connected to the movable
15 element 12. The sensor 13 is triggered by movement of the movable element 12 due to mechanical impact from a passing defective package. The jam detecting device 10 has four main support members 14, 15, 16, 17. The support member 17 is constituted by a shaft that is provided
20 between two of the other support members 14, 16 to ensure a free movement of the movable element 12. That is, the shaft 17 will make sure that the two support members 14, 16, between which the movable element 12 extends in its longitudinal direction, do not interfere with the
25 rotational movement of the movable element 12 around the shaft 17. Specifically, the shaft 17 comprises two stoppers (not shown) that limit the closure between the two support members 14, 16 at a distance which is larger than the length of the movable element 12. In this
30 specific embodiment, the movable element 12 is rotationally attached to the shaft 17.

The jam detecting device 10 further comprises an adjustment element 18 which is able to adjust a maximum

clearance between movable element 12 and any non-defective packages passing the same. Specifically, the adjustment element 18 is movable in a vertical direction to engage with a portion of the movable element 12, 5 thereby limiting its movement in the same vertical direction. In this way, the clearance between the movable element 12 and any non-defective packages passing the same can be adjusted and thus sensitivity of the jam detecting device 10 controlled.

10 The jam detecting device 10 further comprises a control unit (not shown) which is connected to the sensor 13. When the sensor 13 is triggered due to movement of the movable element 12, the control unit can be programmed to stop at least a part, or unit, of the 15 filling machine.

With reference to Figures 2, 3 and 4, a folding unit 1 substantially comprises a conveyor 20 for feeding packs 3 continuously along a predominantly straight horizontal forming path B from a supply station 21 to an output 20 station 22 (both shown only schematically) and folding means for folding packs 3, in particular at least one end portion of packs 3, whilst packs 3 are carried by the conveyor 20, to obtain packages 2. The folding means are known from prior art and, therefore, they are not shown 25 and disclosed in detail. For example, the folding means may comprise a fixed elongated guide member and folding elements as explained above.

Conveyor 20 comprises at least one gear and, in the example shown, a drive gear 25 and a driven gear 26, and 30 an articulated chain 27 looped about and meshing with gears 25, 26, and supporting a number of plates 28, for example flat rectangular plates, each of which projects from chain 27 and cooperates with and pushes a pack 3 to

feed it along path B.

Chain 27 comprises a straight horizontal top branch 30, a bottom branch 31 substantially parallel to branch 30, and two curved C-shaped portions 32, 33, which are
5 positioned with their concavities facing each other, connect branches 30 and 31, and the middle portions of which define supply station 21 and output station 22 respectively.

Path B comprises a straight main portion B_1 defined
10 by branch 30 of chain 27, and two, respectively supply and output, curved end portions B_2 , B_3 defined by respective top portions 32a, 33a of portions 32, 33 of chain 27 extending between corresponding stations 21, 22 and branch 30. Branch 30 and portions 32a, 33a of
15 portions 32, 33 therefore define a conveying portion of chain 27 to convey packs 3 from station 21 to station 22, while branch 31 and the remaining portions of portions 32, 33 define a return portion of chain 27 to feed plates 28 from station 22 to station 21.

20 Chain 27 comprises a number of articulated links 35 defined by substantially flat rectangular bodies, from which respective plates 28 project perpendicularly.

Given the structure of conveyor 20, plates 28 are positioned vertically along portion B_1 of path B.

25 At supply station 21, each pack 3 is fed onto conveyor 20 in a feed direction C, coaxial with an axis A of pack 3.

Between supply station 21 and output station 22, the jam detecting device 10 is arranged above the uppermost
30 plates 28 of the conveyor 20. In this way, the movable element 12 of the jam detecting device 10 is arranged at a predetermined distance from the uppermost plates 28 to create a clearance between the movable element 12 and any

non-defective packages 2 passing the same.

With reference to Figures 3 and 4, number 100 indicates as a whole a transferring and up-ending unit for tipping the packages 2.

5 Transferring and up-ending unit 100 is known and, therefore, it will be described only to the extent that is necessary for the understanding of the invention.

Transferring and up-ending unit 100 feeds a succession of packages 2 continuously along a path P
10 extending from an in-feed station 104 to an out-feed station 105, and simultaneously up-ends packages 2 continuously from an in-feed position, in which they are positioned with axes A oriented in a direction K, into an out-feed position, in which they are positioned with
15 respective axes A oriented in a direction L crosswise to direction K. With reference to the embodiment shown, direction K is sloped relative to a horizontal plane and direction L is vertical.

Transferring and up-ending unit 100 receives
20 packages 2 continuously and successively at in-feed station 104 from conveyor 20, and feeds them, in the out-feed position, to an output conveyor 108 at out-feed station 105. Output conveyor 108 moves the packages 2 along a substantially straight path R tangent to an end
25 portion of path P.

Transferring and up-ending unit 100 comprises a number of push arms 115 for removing respective packages 2 from conveyor 20 at in-feed station 104 and feeding them along path P to out-feed station 105, and a guide
30 117 which cooperates with packages 2 along path P to up-end them from the in-feed position to the out-feed position.

Path P is arc-shaped about an axis E and extends

along an angle of about 90° from in-feed station 104 to out-feed station 105.

Transferring and up-ending unit 100 also comprises a drive shaft 111 rotating continuously about axis E and
5 powered by an electric motor of the packaging machine in known manner not shown, and a wheel 114 of axis E, fitted to shaft 111 rotatably about axis E, and supporting the push members 115, which are hinged to wheel 114.

Push arms 115 rotates together with wheel 114 around
10 axis E and oscillate with respect to wheel 114 between a first operating position, in which they remove the packages 2 from folding unit 1, to a second operating position, in which - after delivering the packages 2 to the conveyor 108 - are received into slots 116, obtained
15 in the wheel 114.

Push arms 115 are provided at their ends opposite to the ends which interact with packages 2 with cam followers (not shown) that interact with a fixed cam (not shown), so that the fixed cam drives the push arms 115.

20 Guide 117 is curved, extends substantially along path P, on the outside of wheel 114, and cooperates with packages 2 to ease them from the in-feed to the out-feed position.

Furthermore, guide 117 defines a supporting and
25 slide surface T for packages 2, which extends substantially along path P and slopes gradually from a portion T1, parallel to direction B and adjacent to in-feed station 104, to a substantially flat, vertical out-feed portion T2 parallel to direction L and adjacent to
30 out-feed station 105.

During operation, packs 3 are fed to conveyor 20 and - as conveyor 20 carries them along path P - the folding means fold packs 3, in particular end portions thereof,

so as to form packages 2.

When a package 2 reaches output station 22, i.e. the region where the folding unit 1 cooperates with the transferring and up-ending unit 100, a push arm 115
5 interacts with the package 2 in order to remove the package 2 from the corresponding plate 28. Subsequently, the push arm 115 delivers the package 2 to the output conveyor 108.

If a defective pack reaches the conveyor 20, or if
10 it is damaged and becomes defective when folded into a package within the folding unit 1, the plates 28, between which it is constrained, will force the defective package to rise above the plates 28. Thus, when a defective package travels in the conveyor 20 and reaches the jam
15 detecting device 10, it will mechanically impact the movable element 12 when passing under the same. In turn, the sensor 13 will be triggered by the movement of the movable element 12 which is recognized by the control unit. The control unit can thereby stop the folding unit
20 1 before the defective package reaches the output station 22. In this way, the defective packages can be removed before the folding unit 1 is restarted and no defective packages will ever reach the transferring and up-ending unit 100.

25 It is understood that other variations in the present invention are contemplated and in some instances, some features of the invention can be employed without a corresponding use of other features. Accordingly, it is appropriate that the appended claims be construed broadly
30 in a manner consistent with the scope of the invention.

CLAIMS

1. Jam detecting device (10) for detecting defective packages in a filling machine, comprising
5 a movable element (12), and
a sensor (13) connected to said movable element (12), wherein said sensor (13) is triggered by movement of said movable element (12) due to mechanical impact from a passing defective package.
- 10 2. The jam detecting device (10) according to claim 1, wherein said jam detecting device (10) is adapted to be positioned in said filling machine such that any defective package will mechanically raise said movable element (12) when passing the same and
15 thereby trigger said sensor (13).
3. The jam detecting device (10) according to claim 1 or 2, and further comprising a shaft (17) arranged in connection with said movable element (12) to ensure a free movement of the movable element (12).
- 20 4. The jam detecting device (10) according to claim 3, wherein said movable element (12) is rotationally attached to said shaft (17).
5. The jam detecting device (10) according to any one of the preceding claims, and further comprising an
25 adjustment element (18) adapted to adjust a maximum clearance between said movable element (12) and any non-defective packages passing the same, in order to control the sensitivity of the jam detecting device (10).
- 30 6. The jam detecting device (10) according to any one of the preceding claims, and further comprising a control unit connected to said sensor (13), wherein said control unit is adapted to stop at least a part

of said filling machine when said sensor (13) is triggered.

7. The jam detecting device (10) according to any one of the preceding claims, wherein said sensor (13) is an optical sensor or an inductive sensor.
8. The jam detecting device (10) according to any one of the preceding claims, and further comprising a connector through which said sensor (13) is connected to said jam detecting device (10).
9. Folding unit (1) in a filling machine for producing packages (2) of pourable food products from sealed packs (3), comprising a movable conveying member (20), folding means arranged for folding at least one end portion of said packs (3), whilst said packs (3) are conveyed by said conveying member (20), to obtain said packages (2), wherein said conveying member (20) carries a plurality of plates (28), each plate (28) being configured to receive a pack (3) and to deliver a package (2) to a transferring and up-ending unit (100) arranged downstream of said folding unit (1), characterised in that said folding unit (1) further comprises a jam detecting device (10) according to any one of claims 1-8.
10. The folding unit (1) according to claim 9, wherein said jam detecting device (10) is arranged upstream an output station (22) of said folding unit (1).
11. The folding unit (1) according to claim 9 or 10, wherein said jam detecting device (10) is arranged downstream a top squeezer belt and upstream a top brush of said folding unit (1).
12. The folding unit according to any one of claims 9-11, wherein said movable element (12) of said jam detecting device (10) is arranged above the uppermost

plates (28) of said conveying member (20) in said folding unit (1).

13. The folding unit (1) according to claim 12, wherein said movable element (12) of said jam detecting device (10) is arranged at a predetermined distance from said uppermost plates (28) to create a clearance between said movable element (12) and any non-defective packages (12) passing the same.
14. A filling machine for producing packages of pourable food products from sealed packs, comprising a jam detecting device (10) according to any one of claims 1-8 or a folding unit (1) according to any one of claims 9-13.
15. Method for controlling the operation of a filling machine for producing packages (12) of pourable food products, comprising the steps of detecting any defective package by means of a sensor (13) triggered by movement of a movable element (12) due to mechanical impact from a passing defective package, and stopping at least a part of said filling machine based on information from said sensor (13).

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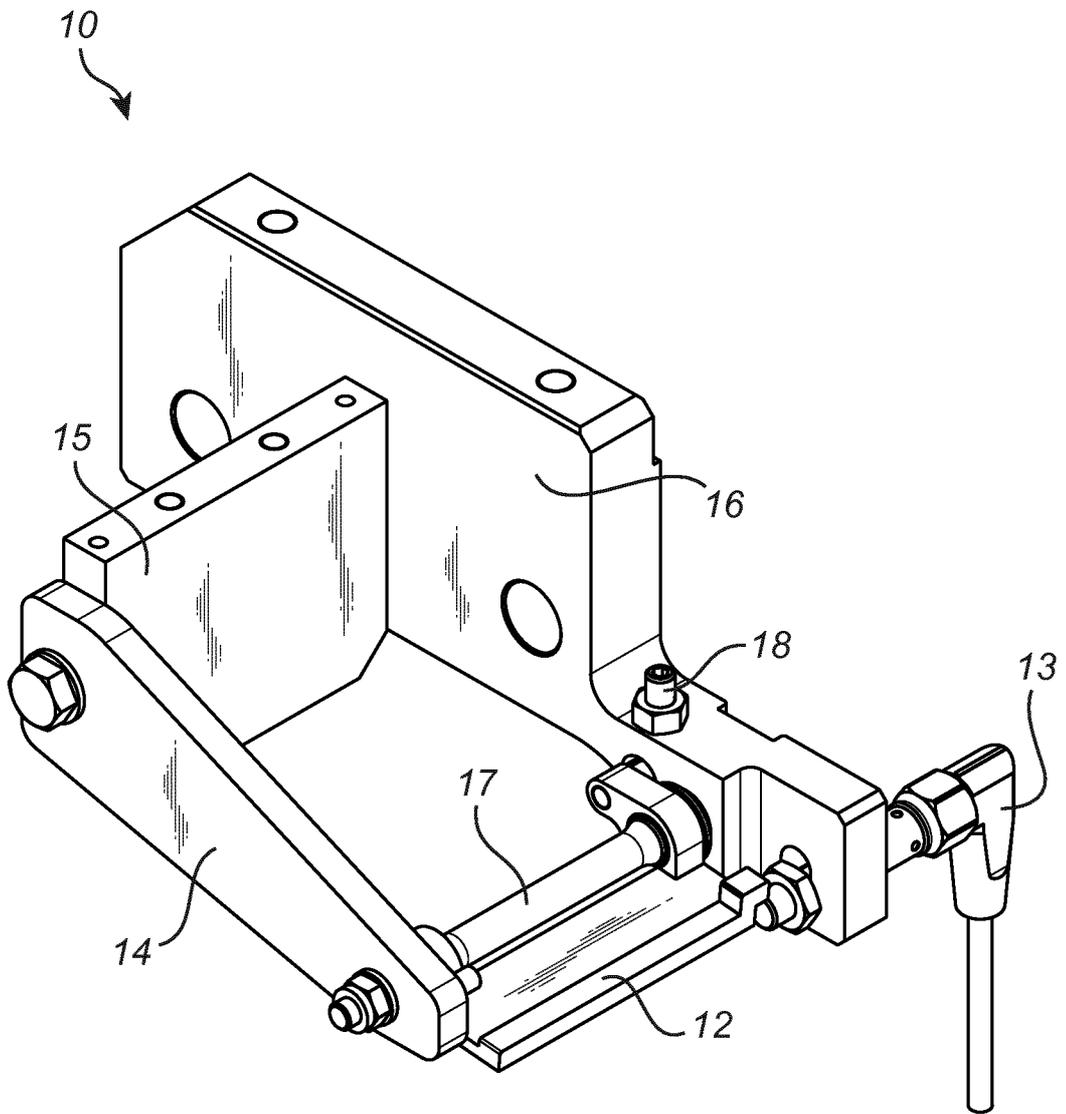
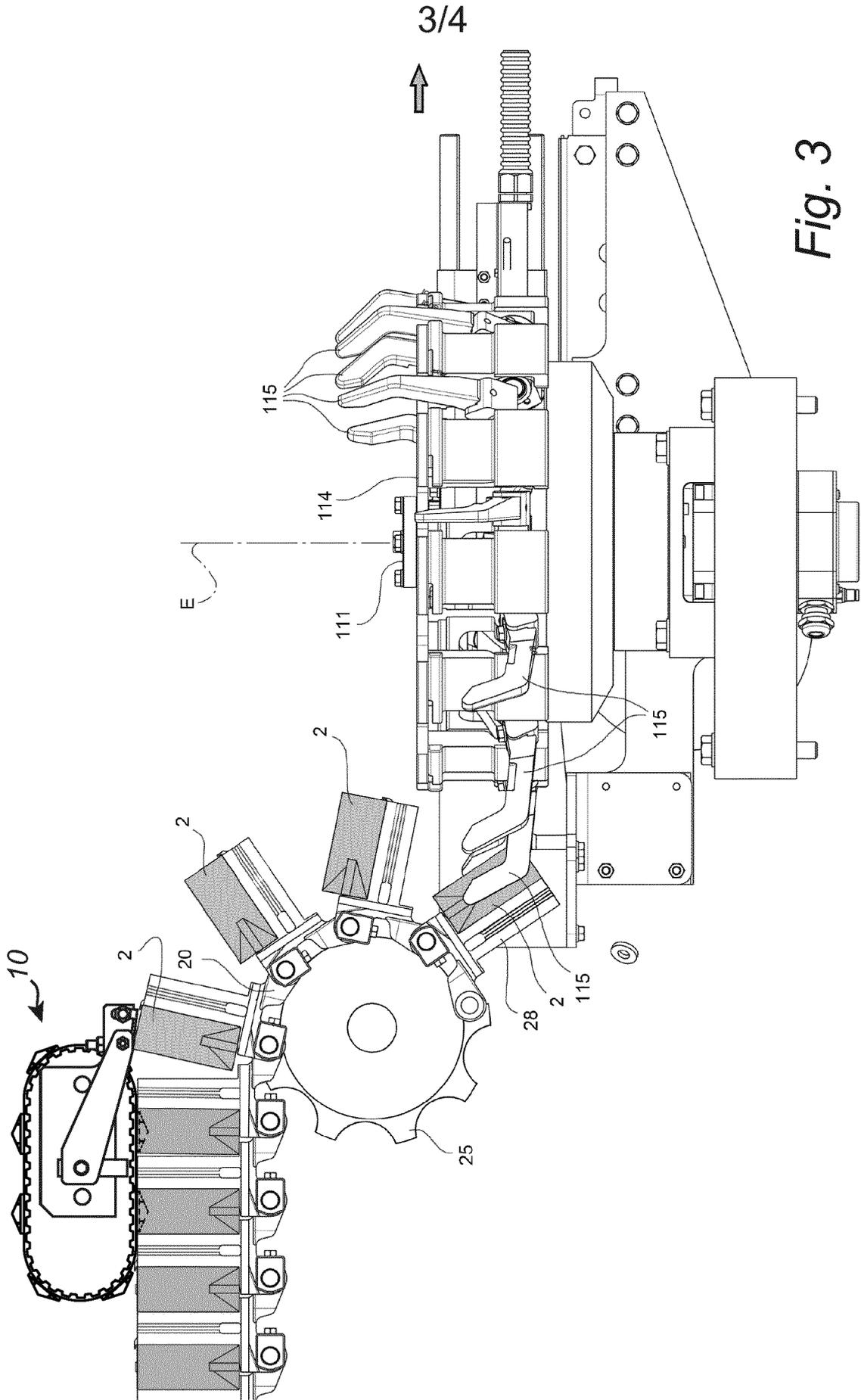


Fig. 1



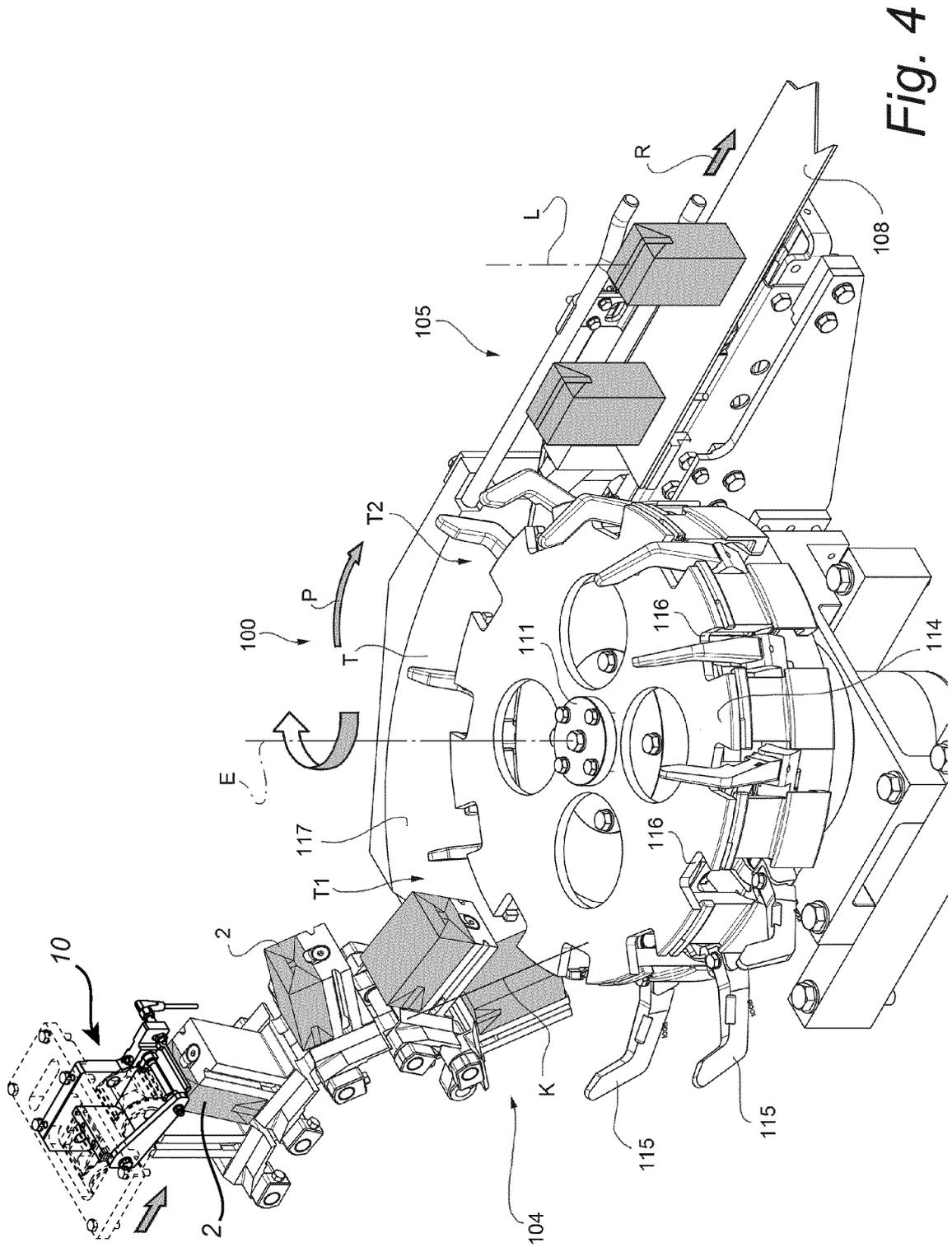


Fig. 4

INTERNATIONAL SEARCH REPORT

International application No
PCT/EP2017/050640

A. CLASSIFICATION OF SUBJECT MATTER
 INV. B65B57/10 B65B61/28
 ADD.
 According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED
 Minimum documentation searched (classification system followed by classification symbols)
 B65B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)
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C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
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Y	the whole document	9-15
Y	EP 2 746 170 A1 (TETRA LAVAL HOLDINGS & FINANCE [CH]) 25 June 2014 (2014-06-25) the whole document	9-15
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A	US 4 593 515 A (MARGRAF DALLAS A [US]) 10 June 1986 (1986-06-10)	1-8

Further documents are listed in the continuation of Box C.

See patent family annex.

* Special categories of cited documents :

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Date of the actual completion of the international search 10 April 2017	Date of mailing of the international search report 24/04/2017
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Name and mailing address of the ISA/ European Patent Office, P.B. 5818 Patentlaan 2 NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Fax: (+31-70) 340-3016	Authorized officer Ungureanu, Mirela
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INTERNATIONAL SEARCH REPORT

Information on patent family members

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