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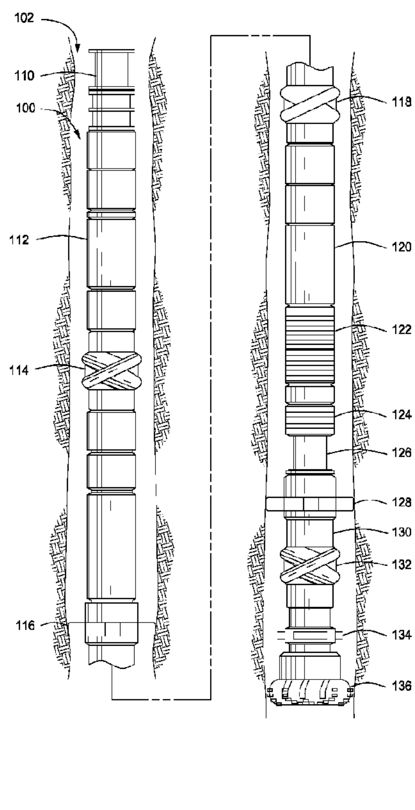

(57) Abrégé/Abstract:
An underreamer for increasing a diameter of a wellbore. The underreamer includes a body having an axial bore extending at least partially therethrough. A mandrel is disposed within the bore of the body and has a port formed radially therethrough. A sleeve is disposed radially-outward from the mandrel. The sleeve blocks fluid flow through the port in the mandrel when the sleeve is in a first position, and the sleeve is axially-offset from the port in the mandrel when the sleeve is in a second position. A flow tube is coupled to the mandrel. The sleeve moves from the first position to the second position when fluid flows through the flow tube and through a channel disposed in the mandrel. A cutter block is movably coupled to the body and is responsive to fluid flow from the axial bore through the port in the mandrel.

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(54) Title: UNDERREAMER FOR INCREASING A WELLBORE DIAMETER

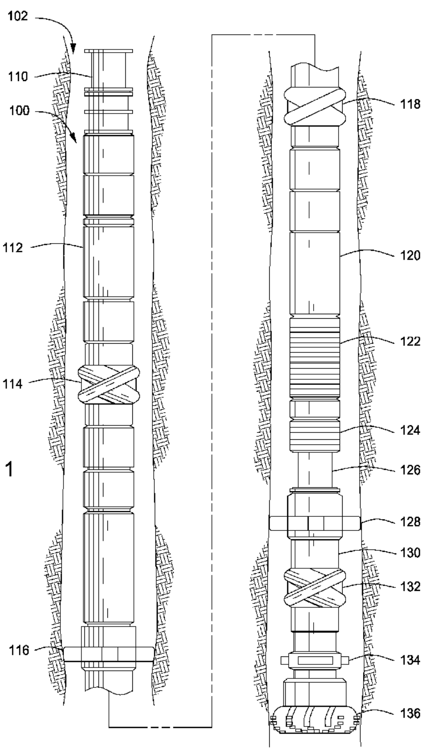

FIG. 1

(57) Abstract: An underreamer for increasing a diameter of a wellbore. The underreamer includes a body having an axial bore extending at least partially therethrough. A mandrel is disposed within the bore of the body and has a port formed radially therethrough. A sleeve is disposed radially-outward from the mandrel. The sleeve blocks fluid flow through the port in the mandrel when the sleeve is in a first position, and the sleeve is axially-offset from the port in the mandrel when the sleeve is in a second position. A flow tube is coupled to the mandrel. The sleeve moves from the first position to the second position when fluid flows through the flow tube and through a channel disposed in the mandrel. A cutter block is movably coupled to the body and is responsive to fluid flow from the axial bore through the port in the mandrel.

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UNDERREAMER FOR INCREASING A WELLBORE DIAMETER

FIELD OF THE INVENTION

[0001] Embodiments described herein generally relate to downhole tools. More particularly, such embodiments relate to underreamers for enlarging the diameter of a wellbore.

BACKGROUND INFORMATION

[0002] Wellbores are drilled by a drill bit coupled to the end portion of a drill pipe. The drill bit drills the wellbore to an original "pilot hole" diameter. During or after the drilling of the wellbore to the pilot hole diameter, an underreamer is oftentimes also used to enlarge the diameter of the wellbore. The underreamer is run into the wellbore on the drill pipe in an inactive state. In the inactive state, cutter blocks on the underreamer are folded or retracted inwardly into the body of the underreamer such that the cutter blocks are positioned radially-inward from the surrounding casing or wellbore wall. Once the underreamer reaches the desired depth in the wellbore, the underreamer is actuated to an active state. In the active state, the cutter blocks move radially-outward and into contact with the wellbore wall. The cutter blocks are then used to increase the diameter of the wellbore.

[0003] Underreamers are generally spaced axially apart from the drill bit on the drill pipe. For example, the underreamer may be positioned "above" the drill bit by between about 30 m and about 60 m. As such, the underreamer is not able to increase the diameter of this lower portion (30 m – 60 m) of the wellbore because the drill bit contacts subterranean formation proximate the base of the wellbore, thereby preventing further downward movement of the underreamer. This portion of the wellbore that remains at the pilot hole diameter is oftentimes referred to as the "rat hole." What is needed is an improved system and method for increasing the diameter of the rat hole.

SUMMARY

[0004] This summary is provided to introduce a selection of concepts that are further described below in the detailed description. This summary is not intended to identify key or essential features of the claimed subject matter, nor is it intended to be used as an aid in limiting the scope of the claimed subject matter.

[0005] An underreamer for increasing a diameter of a wellbore is disclosed. The underreamer may include a body having an axial bore extending at least partially therethrough. A mandrel may be disposed within the bore of the body and have a port formed radially therethrough. A sleeve may be disposed radially-outward from the mandrel and move axially with respect to the mandrel from a first position to a second position. The sleeve may block fluid flow through the port in the mandrel when in the first position, and the sleeve may be axially-offset from the port in the mandrel when in the second position. A flow tube may be coupled to the mandrel. The sleeve may move from the first position to the second position when fluid flows through the flow tube. A cutter block may be movably coupled to the body. An outer surface of cutter block may be aligned with, or positioned radially-inward from, an outer surface of the body when the sleeve is in the first position, and the outer surface of the cutter block may be moved or positioned radially-outward from the outer surface of the body when the sleeve is in the second position. The outer surface of the cutter block may be moved or positioned radially-outward from the outer surface of the body in response to the fluid flow through the port.

[0006] In another embodiment, the underreamer includes a body having an axial bore extending at least partially therethrough. A control unit may be disposed within the bore of the body. The control unit may include a sensor, a valve seat, and a plunger. The sensor may receive a signal transmitted through the wellbore. The plunger may move axially with respect to the valve seat in response to the signal received by the sensor. The plunger may block fluid flow through the valve seat when in a first position, and the plunger may be axially-offset from the valve seat when in the second position. A flow tube may be coupled to the valve seat and have fluid flow therethrough when the plunger is in the second position. A mandrel may be coupled to the flow tube. The mandrel may have a first port formed radially therethrough in fluid communication with the flow tube. The mandrel may also have a second port formed radially therethrough. A sleeve may be disposed radially-outward from the mandrel and move axially with respect to the mandrel from a first position to a second position when the fluid flows through the flow tube and the first port. The sleeve may block fluid flow through the second port in the mandrel when in the first position, and the sleeve may be axially-offset from the second port in the mandrel when in the second position. A cutter block may be movably coupled to the body. An outer surface of cutter block may be aligned with, or positioned radially-inward from, an outer surface of the body when the sleeve is in the first position, and the outer surface of the cutter block may be positioned radially-outward from the outer surface of the body when the sleeve is in the second position.

[0007] A method for increasing a diameter of a wellbore is also disclosed. The method includes running a downhole tool into the wellbore. The downhole tool may include an underreamer having a body and a mandrel disposed within a bore of the body. A signal may be transmitted through the wellbore to a sensor disposed within the bore of the body. A plunger disposed within the bore of the body may move from a first position to a second position in response to the signal received by the sensor. The plunger may block fluid flow through a valve seat when in the first position, and the plunger may be axially-offset from the valve seat when in the second position. Fluid may flow through the valve seat, through a flow tube fluidly coupled to the valve seat, and through a channel disposed in the mandrel fluidly coupled to the flow tube when the plunger is in the second position. A sleeve disposed radially-outward from the mandrel may move from a first position to a second position in response to the fluid flowing into the mandrel from the flow tube. The sleeve may block a port formed radially through the mandrel when in the first position, and the sleeve may be axially-offset from the port in the mandrel when in the second position. A cutter block coupled to the body may move radially-outward in response to the sleeve moving from the first position to the second position.

[0007a] In another embodiment, there is provided an underreamer for increasing a diameter of a wellbore, comprising: a body having an axial bore extending at least partially therethrough; a mandrel disposed within the bore of the body and having a port formed radially therethrough; a sleeve disposed radially-outward from the mandrel and configured to move axially with respect to the mandrel from a first position to a second position, the sleeve blocking fluid flow through the port in the mandrel when in the first position and the sleeve allowing fluid flow through the port in the mandrel when in the second position; a flow tube coupled to the mandrel, the sleeve arranged and designed to move axially from the first position to the second position when fluid flows through the flow tube; a piston disposed radially-outward from the mandrel and proximate to the sleeve, wherein a chamber is defined between the piston and the mandrel, and a channel is defined through the mandrel and

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provides a path of fluid communication between the flow tube and the chamber, wherein the piston includes a port formed radially therethrough, and wherein the port in the piston is aligned with the port in the mandrel when the sleeve is in the second position; and a cutter block movably coupled to the body, an outer surface of cutter block being aligned with, or positioned radially-inward from, an outer surface of the body when the sleeve is in the first position, and the outer surface of the cutter block being positioned radially-outward from the outer surface of the body when the sleeve is in the second position.

[0007b] In another embodiment, there is provided an underreamer for increasing a diameter of a wellbore, comprising: a body having an axial bore extending at least partially therethrough; a control unit disposed within the bore of the body, the control unit comprising: a sensor configured to receive a signal transmitted through the wellbore; a control electronic system capable of processing the signal transmitted through the wellbore and received by the sensor; a valve seat; and a plunger operated by the control electronic system and configured to move axially with respect to the valve seat in response to the signal received by the sensor, the plunger blocking fluid flow through the valve seat when in a first position, and the plunger allowing fluid flow through the valve seat when in a second position; a flow tube coupled to the valve seat and configured to have fluid flow therethrough when the plunger is in the second position; a mandrel coupled to the flow tube, the mandrel having a first port disposed radially therethrough in fluid communication with the flow tube, the mandrel also having a second port formed radially therethrough; a sleeve disposed radially-outward from the mandrel and configured to move axially with respect to the mandrel from a first position to a second position when the fluid flows through the flow tube and the first port, the sleeve blocking fluid flow through the second port in the mandrel when in the first position, and the sleeve allowing fluid flow through the second port in the mandrel when in the second position; and a cutter block movably coupled to the body, an outer surface of cutter block being aligned with, or positioned radially-inward from, an outer surface of the body when the sleeve is in the first position, and the outer surface of the cutter block being positioned radially-outward from the outer surface of the body when the sleeve is in the second position.

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[0007c] In another embodiment, there is provided a method for increasing a diameter of a wellbore, comprising: running a downhole tool into a wellbore, the downhole tool including an underreamer having a body and a mandrel disposed within a bore of the body; transmitting a signal through the wellbore to a sensor disposed within the bore of the body; moving a plunger disposed within the bore of the body from a first position to a second position in response to the signal received by the sensor, the plunger blocking fluid flow through a valve seat when in the first position and the plunger allowing fluid flow through the valve seat when in the second position; flowing fluid through the valve seat, through a flow tube fluidly coupled to the valve seat, and through a channel disposed in the mandrel fluidly coupled to the flow tube when the plunger is in the second position; moving a sleeve disposed radially-outward from the mandrel from a first position to a second position in response to the fluid flowing through the channel disposed in the mandrel from the flow tube, the sleeve blocking a port formed radially through the mandrel when in the first position, and the sleeve allowing fluid flow through the port in the mandrel when in the second position; flowing the fluid from the flow tube, through the channel disposed through the mandrel, and into a first chamber defined between the mandrel and a piston; moving the piston in response to the fluid flowing into the first chamber, wherein the piston moves the sleeve from the first position to the second position; and aligning a port formed radially through the piston with the port in the mandrel when the sleeve is in the second position; and moving a cutter block coupled to the body radially-outward in response to the sleeve moving from the first position to the second position.

BRIEF DESCRIPTION OF THE DRAWINGS

[0008] So that the recited features may be understood in detail, a more particular description, briefly summarized above, may be had by reference to one or more embodiments, some of which are illustrated in the appended drawings. It is to be noted, however, that the appended drawings are illustrative embodiments, and are, therefore, not to be considered limiting of its scope.

[0009] FIG. 1 depicts an illustrative downhole tool disposed within a wellbore, according to one or more embodiments disclosed.

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[0010] FIG. 2 depicts a partial cross-sectional view of an illustrative underreamer, according to one or more embodiments disclosed.

[0011] FIG. 3 depicts a partial cross-sectional view of an illustrative control unit in a second underreamer, according to one or more embodiments disclosed.

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[0012] FIG. 4 depicts a partial cross-sectional view of an illustrative actuator unit when the second underreamer is in an inactive state, and Figure 5 depicts a partial cross-sectional view of the actuator unit when the second underreamer is in an active state, according to one or more embodiments disclosed.

[0013] FIGs 6 and 7 depict partial cross-sectional views of the second underreamer in an inactive state, according to one or more embodiments disclosed.

[0014] FIGs 8 and 9 depict partial cross-sectional views of the second underreamer in an active state, according to one or more embodiments disclosed.

[0015] FIGs 10, 11 and 12 depict the first and second underreamers increasing the diameter of the wellbore, according to one or more embodiments disclosed.

DETAILED DESCRIPTION

[0016] FIG. 1 depicts an illustrative downhole tool **100** disposed within a wellbore **102**, according to one or more embodiments. The downhole tool **100** may be run into the wellbore **102** using drill pipe **110**. The downhole tool **100** may include a drill collar **112**, one or more stabilizers (three are shown: **114**, **118**, **132**), a first underreamer **116**, a measuring-while-drilling ("MWD") tool **120**, a logging-while-drilling ("LWD") tool **122**, a communication device **124**, a flexible joint **126**, a second underreamer **128**, a rotary steerable system (RSS), and a drill bit **136**. In at least one embodiment, the rotary steerable system may include a control unit **130** and a bias unit **134**.

[0017] The measuring-while-drilling tool **120** may include navigation sensors and communicate to the surface (*e.g.*, via mud pulse telemetry). The measuring-while-drilling tool **120** may also include one or more sensors configured to measure loads acting on the drill pipe **110**, such as weight on the drill bit **136** ("WOB"), torque on the drill bit **136** ("TOB"), and/or bending moments. The measuring-while-drilling tool **120** may also measure axial, lateral, and/or torsional vibrations in the drill pipe **110** as well as the azimuth and inclination of the drill bit **136**, and the temperature and pressure of the fluids in the wellbore **102**. The logging-while-drilling tool **122** may include one or more sensors configured to measure properties of the formation and its contents such as formation porosity, density, lithology, dielectric constants, formation layer interfaces, and the pressure and permeability of the fluid in the formation.

[0018] The second underreamer **128** may be positioned along the downhole tool **100** between the measuring-while-drilling tool **120** and the drill bit **136**, between the logging-while-drilling tool **122** and the drill bit **136**, between the communication device **124** and the drill bit **136**, between the flexible joint **126** and the drill bit **136**, between the control unit **130** and the drill bit **136** (not shown), or between the bias unit **134** and the drill bit **136** (not shown). In at least one embodiment, a distance between the second underreamer **128** and the drill bit **136** may be less than about 50 m, less than about 40 m, less than about 30 m, less then about 20 m, less than about 15 m, less than about 10 m, less than about 7.5 m, less than about 5 m, or less than about 2.5 m.

[0019] FIG. 2 depicts a partial cross-sectional view of the second underreamer **128**, according to one or more embodiments. The second underreamer **128** includes a substantially cylindrical body **200** having an axial bore **206** extending at least partially (*e.g.*, completely) therethrough. The body **200** may be a single component, or the body **200** may be two or more components coupled together. The body **200** has a first or "upper" end portion **202** and a second or "lower" end portion **204**.

[0020] One or more cutter blocks **220** are movably coupled to the body **200**. Although a single cutter block **220** is shown, the number of cutter blocks **220** may range from a low of about 1, 2, 3, or 4 to a high of about 5, 6, 7, 8, or more. For example, the body **200** may have three cutter blocks **220** movably coupled thereto.

[0021] The second underreamer **128** is configured to actuate from an inactive state (as shown in FIG. 2) to an active state. When the second underreamer **128** is in the inactive state, the outer (radial) surfaces **222** of the cutter blocks **220** are aligned with, or positioned radially-inward from, the outer (radial) surface **208** of the body **200**. The external surface of the body **200** may have an overall shape of an undergage stabilizer, and the cutter blocks **220** may be contained in the blade of the undergage stabilizer. When in the inactive state, the outer radial surface **222** of the cutter blocks **220** may be retracted inside of the surface of the stabilizer blade. Such design/shape of the second underreamer **128**, similar to the design/shape of an undergage stabilizer, may permit sufficient annular flow passage along the second underreamer **128**. In another embodiment, when the second underreamer **128** is in the inactive state, the outer (radial) surfaces **222** of the cutter blocks **220** may be positioned radially-outward from the outer (radial) surface **208** of the body **200**. In this embodiment, a ratio of the diameter of the outer (radial) surfaces **222** of the cutter blocks **220** to the outer (radial) surface **208** of the body **200** may be between about 1.01:1 and about 1.03:1, between about 1.02:1 and about 1.05:1, between about 1.05:1 and about 1.1:1, between about 1.1:1 and about 1.15:1, between about 1.01:1 and about 1.15:1, or more. When the cutter blocks **220** are positioned radially-outward from the body **200** in the inactive state, the cutter blocks **220** may stabilize the body **200** in the wellbore **102**.

[0022] The cutter blocks **220** have a plurality of splines (also known as a "Z-drive") **224** formed on the outer (side) surfaces thereof. The splines **224** may be or include offset ridges or protrusions configured to engage corresponding grooves or channels in the body **200**. The splines **224** on the cutter blocks **220** (and the corresponding grooves) are oriented at an angle with respect to a longitudinal axis through the body **200**. The angle may range from a low of about 10°, about 15°, or about 20° to a high of about 25°, about 30°, about 35°, or more. For example, the angle may be between about 15° and about 25°, or about 17° and about 23°. Although four splines **224** are shown, it will be appreciated that the number of splines **224** may range from a low of about 1, 2, 3, 4, or 5 to a high of about 10, about 15, about 20, about 25, about 30, or more.

[0023] When the second underreamer **128** transitions from the inactive state to the active state, the engagement of the splines **224** on the cutter blocks **220** and the grooves in the body **200** cause the cutter blocks **220** to simultaneously move axially toward the first end portion **202** of the body **200** and radially-outward with respect to the body **200**. The resultant movement may be at an angle between about 15° and about 25°, or about 17° and about 23° with respect to the longitudinal axis through the body **200**. This movement of the cutter blocks **220** transitions the second underreamer **128** into the active state.

[0024] When the second underreamer **128** is in the active state, the outer (radial) surfaces **222** of the cutter blocks **220** are positioned radially-outward from the outer (radial) surface **208** of the body **200** by a distance **226** (see FIG. 8). A ratio of the diameter of the outer (radial) surfaces **222** of the cutter blocks **220** to the outer (radial) surface **208** of the body **200** may be between about 1.1:1 and about 1.2:1, between about 1.15:1 and about 1.25:1, between about 1.2:1 and about 1.3:1, between about 1.25:1 and about 1.35:1, between about 1.3:1 and about 1.4:1 or more. In addition, a ratio of the distance **226** (see FIG. 8) to the diameter of the body **200** may range from a low of about 1:4, about 1:5, about 1:6, or about 1.7 to a high of about 1:8, about 1:9, about 1:10, about 1:12, or more.

[0025] The cutter blocks **220** each have a plurality of cutting contacts or elements disposed on the outer (radial) surface **222** thereof. In at least one embodiment, the cutting contacts of the cutter blocks **220** may be or include polycrystalline diamond compact ("PDC") or the like. The cutting contacts on the cutter blocks **220** are configured to cut, grind, shear, and/or crush the wall of the wellbore **102** to increase the diameter thereof when the second underreamer **128** is in the active state. The cutter blocks **220** may also include a plurality of stabilizer pads (not shown) disposed on the outer (radial) surface **222** thereof. When the cutter blocks **220** include cutting contacts and stabilizer pads, the cutter blocks **220** may function as a cleanout stabilizer. When the cutter blocks **220** include stabilizer pads but no cutting contacts, the cutter blocks **220** may function as an expandable stabilizer.

[0026] In at least one embodiment, a first cutter block **220** of the second underreamer **128** may have a different height (as measured radially outward from the body **200**) than a second cutter block (not shown). For example, the first cutter block **220** may have a greater height than the second cutter block. In this embodiment, the first cutter block **220** may act as a stabilizer when the second underreamer **128** is in the inactive state, and the first cutter block **220** may push the body **200** off the longitudinal axis of the wellbore **102** when the second underreamer **128** is in the active state to allow bi-centric cutting to occur. A control unit **210**, *e.g.*, a remote control unit, is disposed within the bore **206** of the body **200**. The control unit **210** is configured to actuate the cutter blocks **220** from the inactive state to the active state and *vice versa*, as described in greater detail below.

[0027] FIG. 3 depicts a partial cross-sectional view of the control unit **210**, according to one or more embodiments. The control unit **210** may include one or more sensors (one is shown: **310**), one or more batteries **320** to provide electrical power, an electronics unit **330**, and an actuator unit **340**. The sensor **310** is configured to receive one or more signals, *e.g.*, hydraulic signals, transmitted through the wellbore **102**, *e.g.*, via the drill pipe **110**, from the surface that direct the control unit **210** to actuate the second underreamer **128** from the inactive state to the active state, or *vice versa*. In at least one embodiment, the downhole tool **100** (FIG. 1) may include a plurality of control units, and each control unit may send and/or receive different signals. Each control unit may be used to actuate a different component (e.g., underreamer) of the downhole tool **100**.

[0028] The sensor **310** may be or include a flow sensor, a pressure sensor, a vibration sensor, or the like, and the signals may be in the form of flow pulses/variations, pressure pulses/variations, or vibration pulses/variations. The electronics unit **330** may interpret the signals received by the sensor **310**. In response to the signals, the electronics unit **330** may control the actuator unit **340**.

[0029] FIG. 4 depicts a partial cross-sectional view of the actuator unit **340** when the second underreamer **128** is in the inactive state, and FIG. 5 depicts a partial cross-sectional view of the actuator unit **340** when the second underreamer **128** is in the active state, according to one or more embodiments. The actuator unit **340** may include a solenoid **410** having a shaft **412** coupled thereto. A plunger or valve **414**, *e.g.*, a poppet valve, on an end portion of the shaft **412** is configured to sealingly engage a valve seat **420** to prevent fluid flow therethrough when the second underreamer **128** is in the inactive state (see FIG. 4). The plunger **414** and/or the valve seat **420** may be made of ceramic transition-toughened zirconia, tungsten carbide, polycrystalline diamond, or the like.

[0030] When the control unit **210** determines that the second underreamer **128** is to actuate into the active state, the control unit **210** directs, *e.g.*, by supplying electrical current to, the solenoid **410** and the shaft **412** to move axially with respect to the valve seat **420** to allow fluid flow through the valve seat **420**. As shown, the solenoid **410** and the shaft **412** move toward the first end portion **202** of the body **200** (to the left as shown in FIG. 5) a small distance. The distance may be from about 0.5 mm to about 5 mm or about 1 mm to about 2.5 mm. In other embodiments, the distance may be from about 5 mm to about 10 mm, about 10 mm to about 20 mm, about 20 mm to about 40 mm, or more. A position sensor **430** may be used to determine the position of the solenoid **410** and the shaft **412** and, thus, the state of the second underreamer **128**. The position sensor **430** may communicate the position back to the electronics unit **330** in the control unit **210**. Such position information permits the control unit **210** to lower the current applied to the solenoid **410** after opening the valve **414**. The action of valve opening uses a larger pull force (and current applied to solenoid **410**) than maintaining the valve in the open position. This selective reduction in current applied to the solenoid **410** lowers the energy consumption from the one or more batteries **320**. The heat output from the electronics unit **330** and solenoid **410** are also reduced. Based on feedback from the position sensor **430**, the electronics unit **330** may reapply current to the solenoid **410** to open the valve when the actuator unit **340** closes at least partially due to external perturbations, such as shocks, flows or pressure conditions, or other causes, such as spring bias. The status of the position sensor **430** may be conveyed from the control unit **210** to the measuring-while-drilling tool **120** (see FIG. 1) for transmission uphole, *e.g.*, via mud pulse telemetry, such that underreamer setting may be monitored.

[0031] The position of the plunger or valve **414** should correspond to the last successfully received signal/command received from uphole. Under high-shock drilling conditions, the plunger or valve **414** may be inadvertently set in an undesired position (*e.g.*, when there is little to no fluid flow through axial bore **106**). The electronics unit **330** monitors and/or verifies the position of plunger or valve **414** via the position sensor **430** and compares the sensed position to the desired/expected position. If the electronics unit **330** determines that the plunger or valve **414** is in an undesired position, then the electronics unit **330** initiates a new actuation of the actuator **340**.

[0032] The actuator **340** may be arranged and designed such that actuation to the open position occurs when there is little to no fluid flow through the axial bore **206**. When there is little to no fluid flow through the axial bore **206**, there may also be little to no pressure differential between the axial bore **206** and the well annulus. Thus, the valve **414** experiences minimal, if any, self-closing effects due to pressure differential. The actuation of the actuator **340** under minimal self-closing effects is advantageous because smaller currents and smaller components may be used.

[0033] When the solenoid **410** and the shaft **412** move toward the first end portion **202** of the body **200**, the solenoid **410** compresses a spring **440**. In at least one embodiment, a locking unit **450** may secure or "lock" the solenoid **410** and the shaft **412** in place when the second underreamer **128** is in the active state, thereby maintaining the spring **440** in the compressed state. Thus, the actuator **340** may remain in the open position without the application of a current. A short duration current pulse may control the locking unit **450** during in the opening of the actuator **340**. In another embodiment, the solenoid **410** may stay energized until a deactivate command is received. Nevertheless, even if a constant or near constant current is used to energize the solenoid to maintain the actuator **340** in an open position, the current to maintain the open position will be less than the current to actuate the plunger or valve **414** to the open position, *e.g.*, from closed or near closed position.

[0034] Once the second underreamer **128** is in the active state, fluid may flow radially-inward through a filter **460**. The filter **460** is configured to prevent particles (*e.g.*, sand, drilling fluid additives such as LCM, and other contaminants) from flowing therethrough to the control unit **210**. More particularly, the filter **460** is configured to prevent particles from passing therethrough that would prevent the plunger or valve **414** from sealing against the valve seat **420** or would plug the channel or port **234** (see FIG. 6). The filter **460** may be constructed of a wrapper trapezoid wire, as used in sand control. The external surface of the filter **460** may be kept clean by ensuring that mud velocity around the filter **460** is sufficient (*e.g.*, above 20 feet/second). Thus, the flow restrictor may be chosen in accordance with the fluid flow rate to keep the flow velocity sufficient for filter self-cleaning. Once through the filter 460, the fluid may then flow toward the first end portion **202** of the body **200**, through the valve seat **420** (now unobstructed by the plunger **414**), and through a flow tube **470** toward the second end portion **204** of the body **200**. The flow path of the fluid is indicated by the arrows **472** in FIG. 5.

[0035] When the control unit **210** determines that the second underreamer **128** is to actuate back into the inactive state, the control unit **210** de-energizes the solenoid **410** (or the locking unit **450** releases the solenoid **410**), and the compressed spring **440** moves the solenoid **410** and the shaft **412**, thereby moving the plunger **414** back into sealing engagement with the valve seat **420** to once again prevent fluid flow through the valve seat **420** and the flow tube **470**.

[0036] In another embodiment, rather than a shaft **412** and a plunger **414** that move axially with respect to a valve seat **420**, a rotary valve (not shown) may be used to block and/or allow fluid to flow therethrough and into the flow tube **470**. For example, the rotary valve may include first and second components that each have axial openings formed therethrough that are circumferentially offset from one another. When the control unit **210** determines that the second underreamer **128** is to actuate into the active state, the control unit **210** causes the first component to rotate with respect to the second component such that the openings in the first and second components become aligned, thereby forming a flow path therethrough into the flow tube **470**. When the control unit **210** determines that the second underreamer **128** is to actuate back into the inactive state, the control unit **210** causes the first component to rotate with respect to the second component such that the openings in the first and second components are no longer aligned, thereby obstructing the flow of fluid into the flow tube **470**.

[0037] FIGS. 6 and 7 depict partial cross-sectional views of the second underreamer **128** in the inactive state, according to one or more embodiments. The flow tube **470** may be coupled to and in fluid communication with a mandrel **230** disposed within the bore **206** of the body

200. The mandrel **230** may have one or more ports **232** formed radially therethrough. For example, mandrel **230** may include a plurality of ports **232** that are circumferentially-offset from one another. When the second underreamer **128** is in the inactive state, an annular sleeve **240** disposed radially-outward from the mandrel **230** is axially aligned with the ports **232** and prevents fluid flow therethrough. This causes the cutter blocks **220** to be positioned in the inactive state, as shown in FIG. 6.

[0038] FIGS. 8 and 9 depict partial cross-sectional views of the second underreamer **128** in the active state, according to one or more embodiments. When the second underreamer **128** is actuated into the active state, fluid flows through the valve seat **420** (see FIG. 5) and the flow tube **470** toward the second end portion **204** of the body **200** (to the right as shown in FIGS. 8 and 9). The fluid then flows radially-outward through a channel **234** formed in the mandrel **230** into a first chamber **236**. As the fluid flows into the first chamber **236**, the pressure in the first chamber **236** increases. This increase in pressure causes a first piston **242** to move axially toward the second end portion **204** of the body **200** (to the right as shown in FIGS. 8 and 9). The movement of the first piston **242** causes the sleeve **240** to also move axially toward the second end portion **204** of the body **200**, thereby compressing a spring **246**. In at least one embodiment, the first piston **242** and the sleeve **240** may be a single component.

[0039] A plurality of seals (five are shown: **248-1**, **248-2**, **248-3**, **248-4**, **248-5**) may prevent the fluid from leaking between adjacent components. The seals **248-1**, **248-2**, **248-3**, **248-4**, **248-5** may be dynamic and configured to move with the first piston **242** and/or the sleeve **240**.

[0040] When the first piston **242** and the sleeve **240** move toward the second end portion **204** of the body **200**, the sleeve **240** uncovers the one or more ports **232** in the mandrel **230**, and one or more ports **244** formed radially through the first piston **242** become aligned with the one or more ports **232** in the mandrel **230**. When the ports **232**, **244** are aligned, fluid may flow from a bore **238** in the mandrel **230** through the ports **232**, **244**, and into a second chamber **250**. As the fluid flows into the second chamber **250**, the pressure in the second chamber **250** increases. The pressure in the first chamber **236** and the second chamber **250** may equalize, and the flow in the flow tube **470** may become stagnant. The increase in pressure causes a second piston **252** to move axially toward the first end portion **202** of the body **200** (to the left as shown in FIGS. 8 and 9). The movement of the second piston **252**

causes a drive ring **254** to also move axially toward the first end portion **202** of the body **200**. The drive ring **254** exerts a force on the cutter blocks **220** in a direction toward the first end portion **202** of the body **200**.

[0041] When the drive ring **254** exerts the axial force on the cutter blocks **220** in a direction toward the first end portion **202** of the body **200**, the engagement of the splines **224** on the cutter blocks **220** and the grooves in the body **200** cause the cutter blocks **220** to simultaneously move axially toward the first end portion **202** of the body **200** and radially outward. The resultant movement may be at an angle between about 15° and about 25°, or about 17° and about 23° with respect to the longitudinal axis through the body **200**. This movement of the cutter blocks **220** transitions the second underreamer **128** into the active state. When the second underreamer **128** is in the active state, the cutter blocks **220** are positioned as shown in FIG. 8 such that the outer (radial) surfaces **222** of the cutter blocks **220** are radially-outward from the outer (radial) surface **208** of the body **200**.

[0042] FIGS. 10, 11, and 12 depict the first and second underreamers **116**, **128** increasing the diameter of the wellbore **102**, according to one or more embodiments. In operation, the drill pipe **110** runs the downhole tool **100** with the first and second underreamers **116**, **128** coupled thereto into the wellbore **102**. The first and second underreamers **116**, **128** may be in the inactive state as the drill bit **136** drills the wellbore **102** to a first "pilot hole" diameter **140**. The first diameter **140** may be between about 5 cm and about 15 cm, between about 10 cm and about 20 cm, between about 15 cm and about 25 cm, between about 20 cm and about 30 cm, between about 25 cm and about 35 cm, or more. For example, the first diameter 140 may be between about 16 cm and about 20 cm, between about 18 cm and about 22 cm, between about 20 cm and about 24 cm, between about 22 cm and 26 cm, or between about 24 cm and about 28 cm.

[0043] After the drill bit **136** drills the wellbore **102** to the desired depth, the first underreamer **116** may be actuated into the active state, as shown in FIG. 10. When the first underreamer **116** is in the active state, the drill pipe **110** may pull the downhole tool **100** back toward the surface (*i.e.*, upward, as shown by arrow **146**). As the first underreamer **116** moves upward, the cutter blocks **117** (now expanded radially-outward) cut or grind the wall of the wellbore **102** to increase the diameter of a first portion **150** of the wellbore **102** from the first diameter **140** to a second diameter **142**. The first portion **150** of the wellbore **102** extends upward from the position of the first underreamer **116** when the drill bit **136** is positioned proximate the base **103** of the wellbore **102**. The second diameter **142** may be between about 10 cm and about 20 cm, between about 15 cm and about 25 cm, between about 20 cm and about 30 cm, between about 25 cm and about 35 cm, between about 30 cm and about 40 cm, or more.

[0044] Although not shown, in another embodiment, after the drill bit **136** drills the wellbore **102** to the desired depth, the drill pipe **110** may pull the downhole tool **100** back toward the surface (i.e., upward, as shown by arrow **146**). The first underreamer **116** may then be actuated into the active state, and the drill pipe **110** may then lower the downhole tool **100**. As the first underreamer **116** moves downward, the cutter blocks **117** (now expanded radially-outward) cut or grind the wall of the wellbore **102** as described above.

[0045] Although not shown, in yet another embodiment, the first underreamer **116** may be in the active state as the drill bit **136** drills the wellbore **102** to the first "pilot hole" diameter **140** – *i.e.*, one-pass underreaming (also known as hole enlargement while drilling or "HEWD"). The second underreamer **128** may be in the inactive state during this initial drilling phase.

[0046] After the first underreamer **116** has increased the diameter of the first portion **150** of the wellbore **102** (e.g., during or after drilling of the wellbore **102** with drill bit **136**), the first underreamer **116** may be actuated into the inactive state, and the second underreamer **128** is actuated into the active state, as shown in FIG. 11. The second underreamer **128** may be positioned within the first portion **150** of the wellbore **102** when actuated into the active state; however, in another embodiment, the second underreamer **128** may also be positioned within a second portion **152** of the wellbore **102** when actuated into the active state. The second portion **152** of the wellbore **102** extends from the position of the first underreamer **116** to the position of the second underreamer **128** when the drill bit **136** is positioned proximate the base **103** of the wellbore **102**. The second portion **152** of the wellbore **102** is also known as the "rat hole."

[0047] Still referring to FIGS. 10, 11, and 12, with additional reference now to FIGS. 1-9, to actuate the second underreamer **128** into the active state, one or more signals are sent down the wellbore **102** from the surface and received by the sensor **310** in the control unit **210**. In at least one embodiment, the fluid flow rate through axial bore **106** is reduced considerably (or even stopped) after receiving the required signals to the control unit **210**. Such flow condition may be maintained for a short time period, *e.g.*, for as long as about 15 minutes. The electronics unit **330** interprets the signals and causes the solenoid **410** and the shaft **412**

to move away from the valve seat **420**, thereby removing the sealing engagement between the plunger **414** and the valve seat **420**. Fluid may then flow through the filter **460**, the valve seat **420** (now unobstructed), the flow tube **470**, and the channel **234**. As the fluid enters the first chamber **236**, the fluid causes the first piston **242** and the sleeve **240** to move such that the sleeve **240** uncovers the ports **232** in the mandrel **230**. The ports **232** in the mandrel **230** become aligned with the ports **244** in the first piston **242** so that fluid flows from the bore **238** in the mandrel **230** through the ports **232**, **244** and into the second chamber **250**. The fluid flowing into the second chamber **250** causes the second piston **252** to move the drive ring **254**. The drive ring **254** moves the cutter blocks **220** axially toward the first end portion **202** of the body **200** and radially-outward, thereby transitioning the second underreamer **128** in the active state.

[0048] Once the second underreamer **128** is in the active state, the drill pipe **110** may move the downhole tool **100** away from the surface (*e.g.*, downward, as shown by arrow **148**). As the second underreamer **128** moves downward, the cutter blocks **220** (now expanded radially-outward) cut or grind the wall of the wellbore **102** to increase the diameter of the second portion **152** of the wellbore **102** from the first diameter **140** to a third diameter **144**, as shown in FIG. 12. The third diameter **144** may be between about 10 cm and about 20 cm, between about 15 cm and about 25 cm, between about 20 cm and about 30 cm, between about 25 cm and about 35 cm, between about 30 cm and about 40 cm, or more. For example, the third diameter **144** may be between about 19 cm and about 23 cm, between about 21 cm and about 25 cm, between about 23 cm and about 27 cm, between about 25 cm and about 29 cm, or between about 27 cm and about 31 cm. A ratio of the second and/or third diameters **142**, **144** to the first diameter **140** may be between about 1.05:1 and about 1.15:1, between about 1.1:1 and about 1.2:1, between about 1.15:1 and about 1.25:1, between about 1.2:1 and about 1.3:1, between about 1.25:1 and about 1.35:1, between about 1.3:1 and about 1.5:1, or more. As shown, the second and third diameters **142**, **144** are the same; however, in another embodiment, they may be different.

[0049] The first and second underreamers **116**, **128** may be operated independently or together. The order in which the first and second underreamers **116**, **128** are actuated into the active state is merely illustrative. For example, in another embodiment, the second underreamer **128** may be actuated into the active state before the first underreamer **116**, or the first and second underreamers **116**, **128** may be actuated simultaneously. Moreover, the (axial) direction in which the downhole tool **100** moves when the first and second underreamers **116**, **128** are in the active state is merely illustrative. For example, in another embodiment, the downhole tool **100** may move away from the surface (*i.e.*, downward, as shown by arrow **148**) to increase the diameter of the first portion **150** of the wellbore **102** when the first underreamer **116** is in the active state, and/or the downhole tool **100** may move toward the surface (*i.e.*, upward, as shown by arrow **146**) to increase the second portion **152** of the wellbore **102** when the second underreamer **128** is in the active state. Thus, as may be appreciated, there are many possible methods to expand the second portion **152** of the wellbore **102** by combining or modifying the direction of drilling with the controlling of one or both underreamers **116**, **128**.

[0050] After the second underreamer **128** has increased the diameter of the second portion **152** of the wellbore **102**, the second underreamer **128** is actuated into the inactive state. To actuate the second underreamer **128** back to the inactive state, one or more signals are sent down the wellbore **102** from the surface and received by the sensor **310**. The electronics unit **330** interprets the signals and causes the solenoid **410** and the shaft **412** to move back toward from the valve seat **420** such that the plunger **414** sealingly engages with valve seat **420**, thereby preventing fluid flow through the valve seat **420** and the flow tube **470**.

[0051] With the fluid flow to the channel **234** and the first chamber **236** cut off, the force exerted by the compressed spring **246** overcomes the force exerted by the (now decreasing) pressure in the first chamber **236**. This causes the first piston **242** and the sleeve **240** to move toward the first end portion **202** of the body **200** such that the sleeve **240** blocks fluid flow through the ports **232** in the mandrel **230**. With the fluid flow to the second chamber **250** cut off, the force exerted by the compressed spring **260** (see FIG. 8) overcomes the force exerted by the (now decreasing) pressure in the second chamber **250**. This causes a compressed spring **260** and a stop ring **262** (see FIG. 8) to move the cutter blocks **220** axially toward the second end portion **204** of the body **200** and radially-inward, thereby transitioning the second underreamer **128** back into the inactive state.

[0052] As used herein, the terms "inner" and "outer"; "up" and "down"; "upper" and "lower"; "upward" and "downward"; "above" and "below"; "inward" and "outward"; and other like terms as used herein refer to relative positions to one another and are not intended to denote a particular direction or spatial orientation. The terms "couple," "coupled," "connect," "connection," "connected," "in connection with," and "connecting" refer to "in direct connection with" or "in connection with via one or more intermediate elements or members."

[0053] While the foregoing is directed to embodiments of the present invention, other and further embodiments of the invention may be devised without departing from the basic scope thereof.

CLAIMS:

1. An underreamer for increasing a diameter of a wellbore, comprising:

a body having an axial bore extending at least partially therethrough;

a mandrel disposed within the bore of the body and having a port formed radially therethrough;

a sleeve disposed radially-outward from the mandrel and configured to move axially with respect to the mandrel from a first position to a second position, the sleeve blocking fluid flow through the port in the mandrel when in the first position and the sleeve allowing fluid flow through the port in the mandrel when in the second position;

a flow tube coupled to the mandrel, the sleeve arranged and designed to move axially from the first position to the second position when fluid flows through the flow tube;

a piston disposed radially-outward from the mandrel and proximate to the sleeve, wherein a chamber is defined between the piston and the mandrel, and a channel is defined through the mandrel and provides a path of fluid communication between the flow tube and the chamber, wherein the piston includes a port formed radially therethrough, and wherein the port in the piston is aligned with the port in the mandrel when the sleeve is in the second position; and

a cutter block movably coupled to the body, an outer surface of cutter block being aligned with, or positioned radially-inward from, an outer surface of the body when the sleeve is in the first position, and the outer surface of the cutter block being positioned radially-outward from the outer surface of the body when the sleeve is in the second position.

2. The underreamer of claim 1, wherein the piston moves the sleeve from the first position to the second position when the fluid flows from the flow tube, though the channel, and into the chamber.

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3. The underreamer of claim 2, further comprising first and second seals disposed between the piston and the mandrel, wherein the chamber is disposed between the first and second seals.

4. The underreamer of claim 1, further comprising first and second seals disposed between the sleeve and the mandrel, wherein the port in the mandrel is disposed between the first and second seals when the sleeve is in the first position.

5. The underreamer of claim 1, wherein the port in the mandrel comprises a plurality of ports that are circumferentially-offset from one another.

6. The underreamer of claim 1, further comprising a spring disposed between the mandrel and the body, wherein the spring is compressed when the sleeve moves from the first position to the second position.

7. The underreamer of claim 1, wherein the cutter block is configured to expand the diameter of the wellbore from a first diameter when the sleeve is in the first position to a second diameter when the sleeve is in the second position, and wherein a ratio of the second diameter to the first diameter is between 1.15:1 and 1.30:1.

8. An underreamer for increasing a diameter of a wellbore, comprising:

a body having an axial bore extending at least partially therethrough;

a control unit disposed within the bore of the body, the control unit comprising:

a sensor configured to receive a signal transmitted through the wellbore;

a control electronic system capable of processing the signal transmitted through the wellbore and received by the sensor;

a valve seat; and

a plunger operated by the control electronic system and configured to move axially with respect to the valve seat in response to the signal received by the sensor, the plunger

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blocking fluid flow through the valve seat when in a first position, and the plunger allowing fluid flow through the valve seat when in a second position;

a flow tube coupled to the valve seat and configured to have fluid flow therethrough when the plunger is in the second position;

a mandrel coupled to the flow tube, the mandrel having a first port disposed radially therethrough in fluid communication with the flow tube, the mandrel also having a second port formed radially therethrough;

a sleeve disposed radially-outward from the mandrel and configured to move axially with respect to the mandrel from a first position to a second position when the fluid flows through the flow tube and the first port, the sleeve blocking fluid flow through the second port in the mandrel when in the first position, and the sleeve allowing fluid flow through the second port in the mandrel when in the second position; and

a cutter block movably coupled to the body, an outer surface of cutter block being aligned with, or positioned radially-inward from, an outer surface of the body when the sleeve is in the first position, and the outer surface of the cutter block being positioned radially-outward from the outer surface of the body when the sleeve is in the second position.

9. The underreamer of claim 8, further comprising a solenoid configured to move the plunger axially with respect to the valve seat in response to the signal received by the sensor.

10. The underreamer of claim 8, wherein fluid flows through the bore of the body to a drill bit coupled to the body regardless of the position of the sleeve.

11. The underreamer of claim 8, further comprising a filter disposed radially-outward from the flow tube, wherein the fluid flows through the filter and the valve seat when the plunger is in the second position.

12. The underreamer of claim 8, wherein the sensor is selected from the group consisting of a flow sensor, a pressure sensor, a vibration sensor, and a combination thereof.

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13. A method for increasing a diameter of a wellbore, comprising:

running a downhole tool into a wellbore, the downhole tool including an underreamer having a body and a mandrel disposed within a bore of the body;

transmitting a signal through the wellbore to a sensor disposed within the bore of the body;

moving a plunger disposed within the bore of the body from a first position to a second position in response to the signal received by the sensor, the plunger blocking fluid flow through a valve seat when in the first position and the plunger allowing fluid flow through the valve seat when in the second position;

flowing fluid through the valve seat, through a flow tube fluidly coupled to the valve seat, and through a channel disposed in the mandrel fluidly coupled to the flow tube when the plunger is in the second position;

moving a sleeve disposed radially-outward from the mandrel from a first position to a second position in response to the fluid flowing through the channel disposed in the mandrel from the flow tube, the sleeve blocking a port formed radially through the mandrel when in the first position, and the sleeve allowing fluid flow through the port in the mandrel when in the second position;

flowing the fluid from the flow tube, through the channel disposed through the mandrel, and into a first chamber defined between the mandrel and a piston;

moving the piston in response to the fluid flowing into the first chamber, wherein the piston moves the sleeve from the first position to the second position; and

aligning a port formed radially through the piston with the port in the mandrel when the sleeve is in the second position; and

moving a cutter block coupled to the body radially-outward in response to the sleeve moving from the first position to the second position.

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14. The method of claim 13, further comprising:

flowing the fluid through the port in the mandrel and the port in the piston and into a second chamber; and

equalizing a pressure of the fluid in the first chamber and the fluid in the second chamber.

15. The method of claim 13, further comprising moving a solenoid coupled to the plunger in response to the signal received by the sensor, wherein the solenoid moves the plunger from the first position to the second position.

16. The method of claim 13, wherein the underreamer is configured to stabilize the downhole tool within the wellbore when the sleeve is in the first position, and wherein the underreamer is configured to increase the diameter of the wellbore when the sleeve is in the second position.

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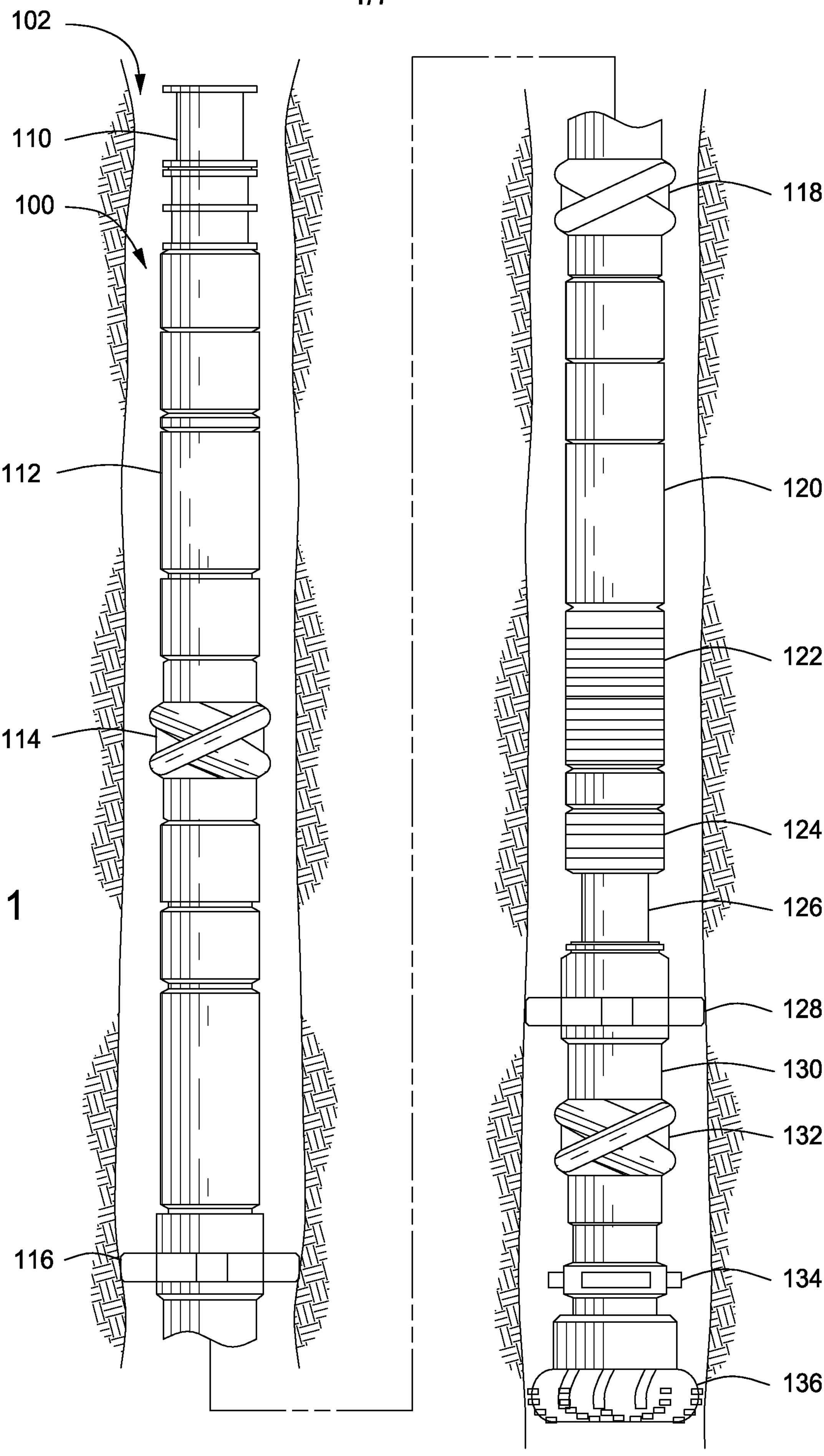


FIG. 1

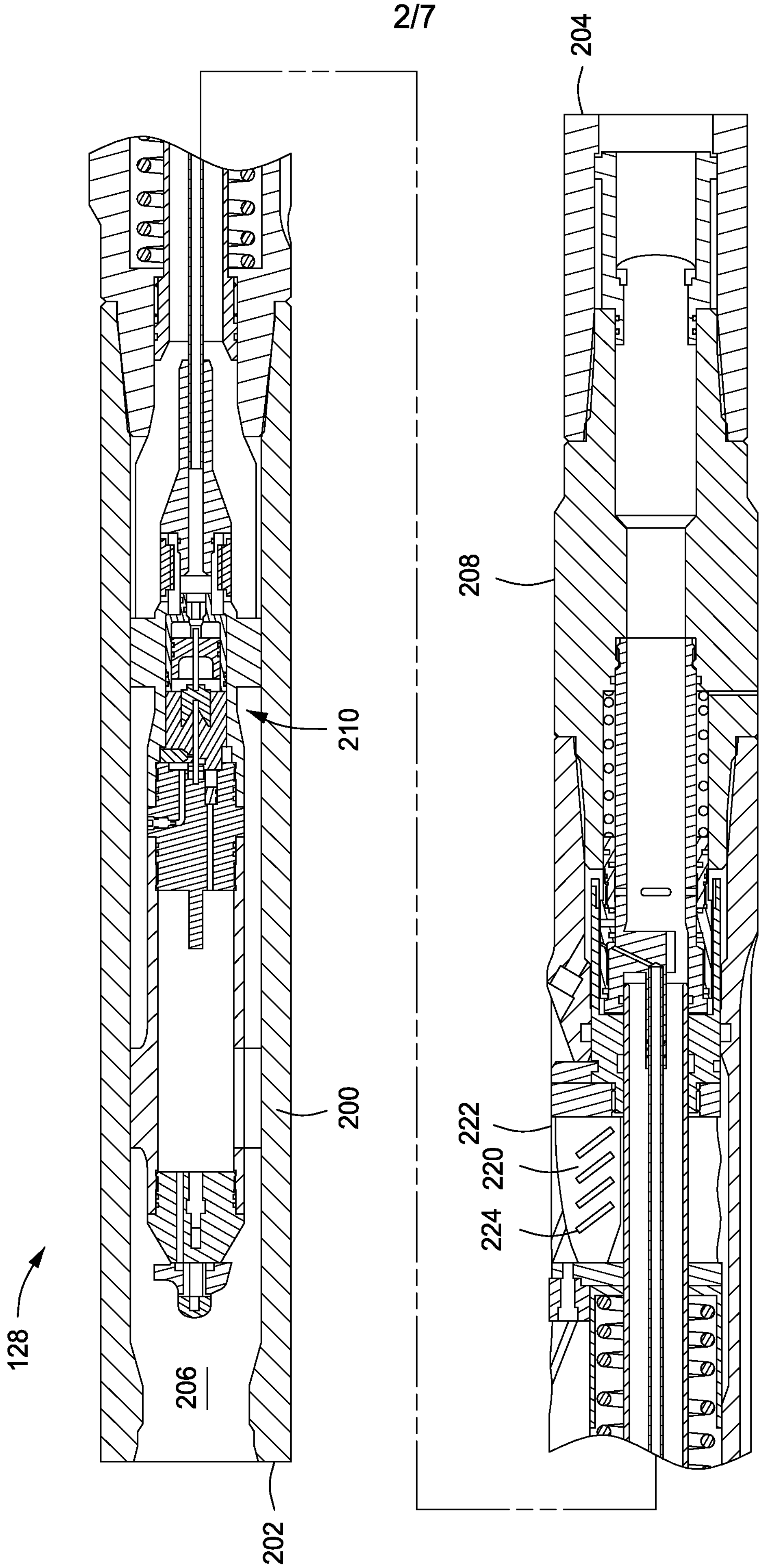


FIG. 2

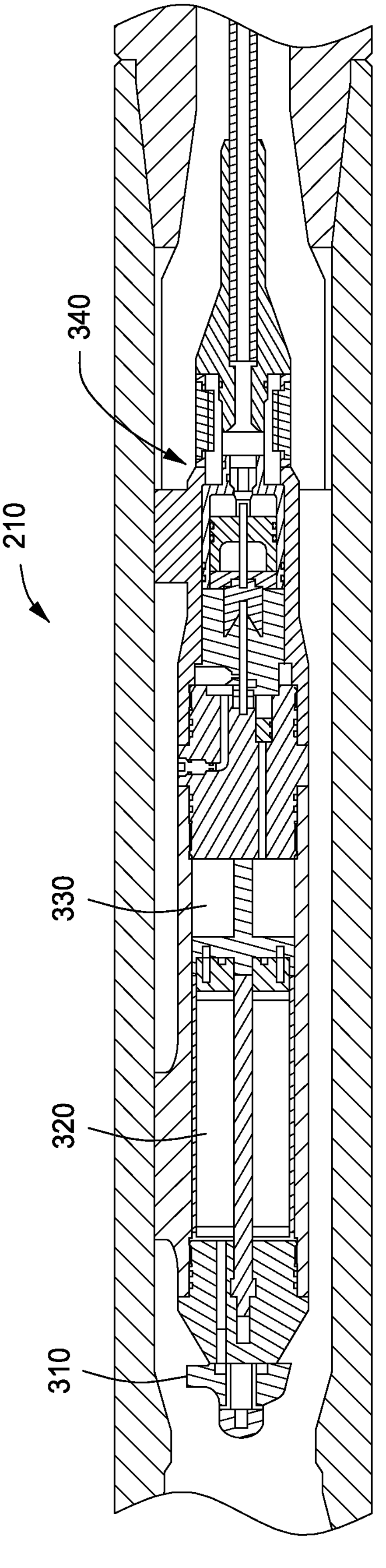


FIG. 3

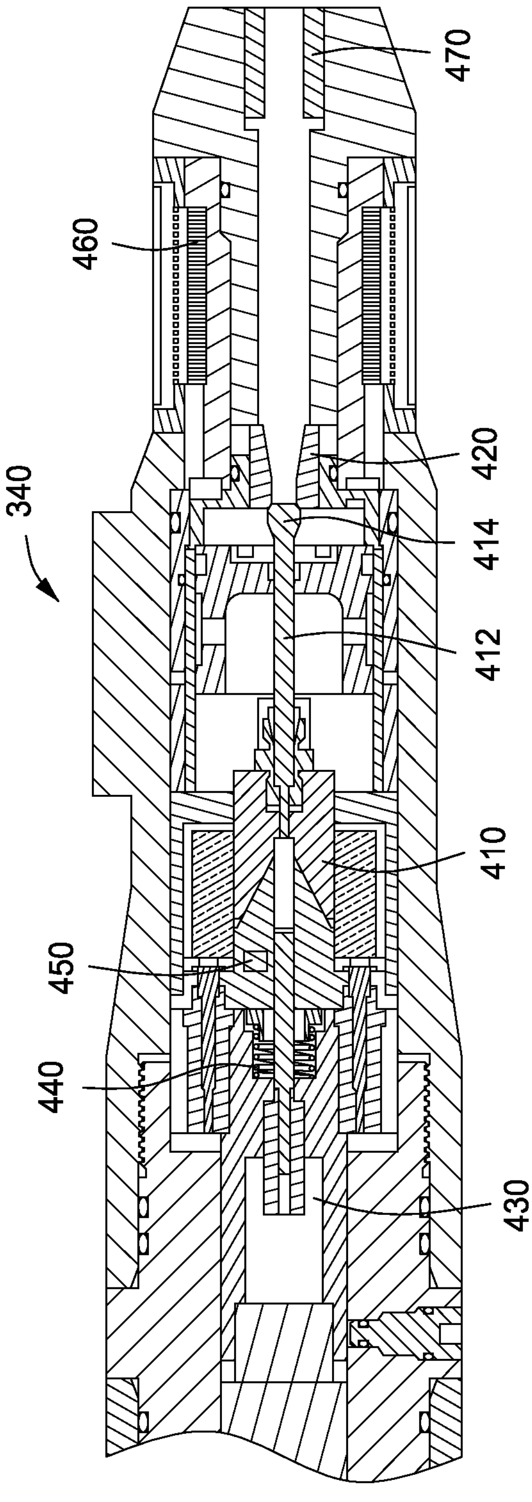


FIG. 4

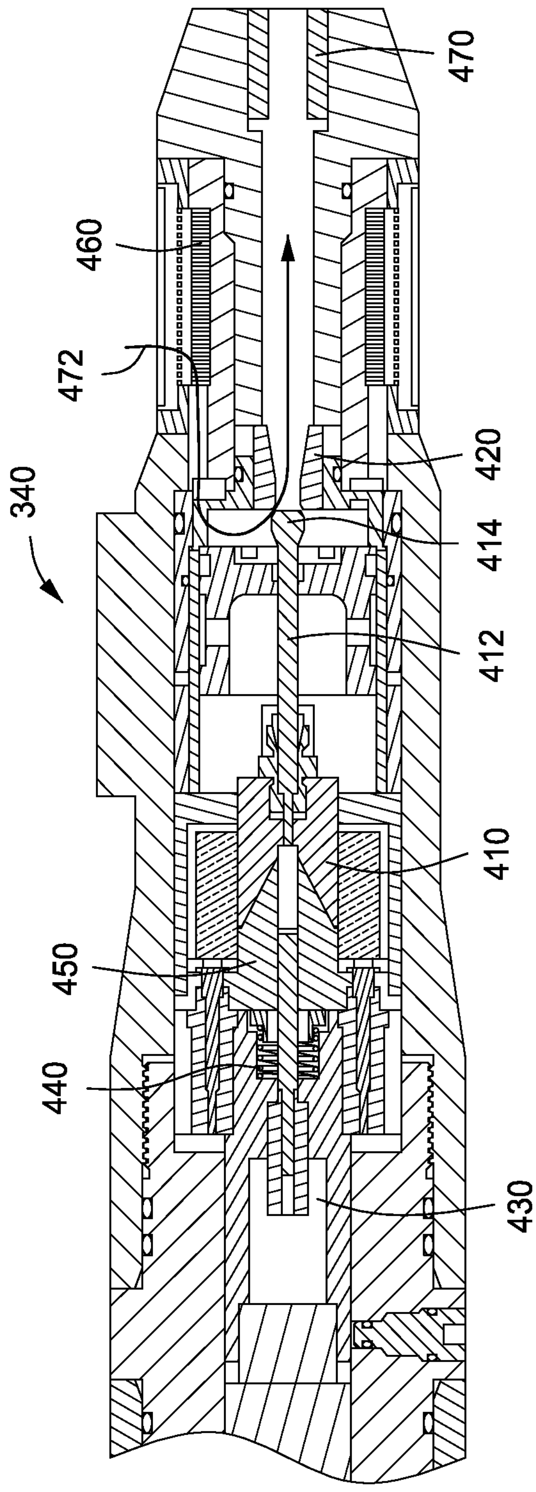
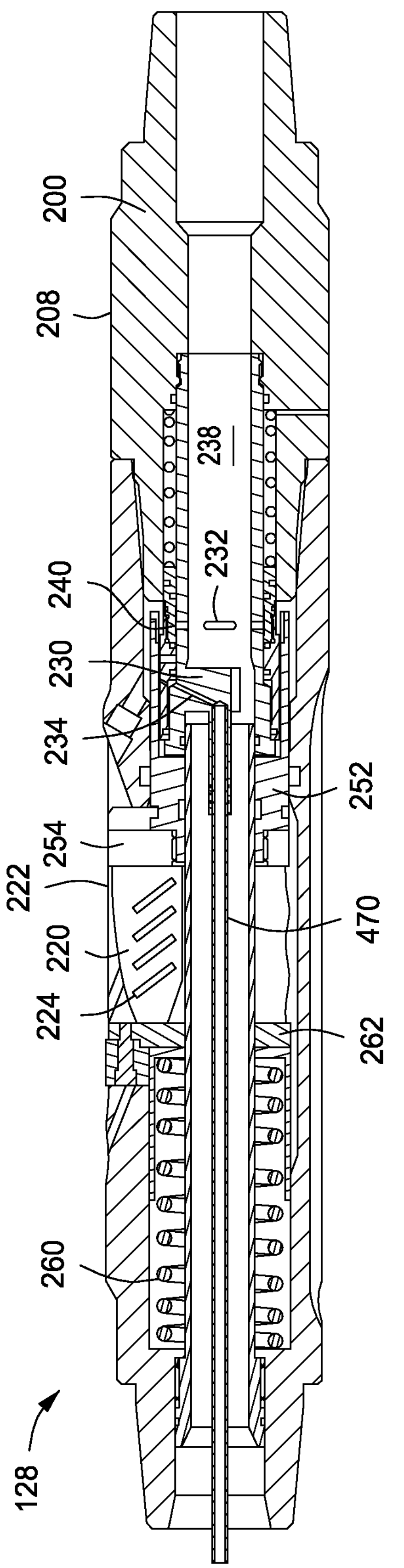

470
460
472
420
340
414
412
410
450
440
430

FIG. 5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232
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252
254
222
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262
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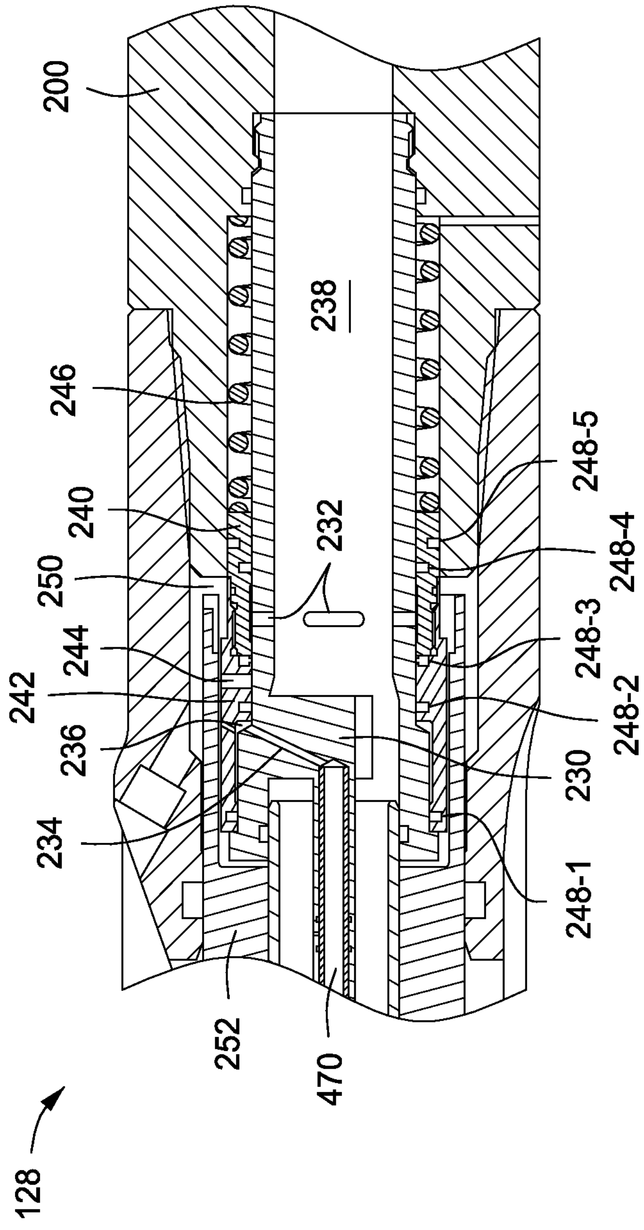
FIG. 6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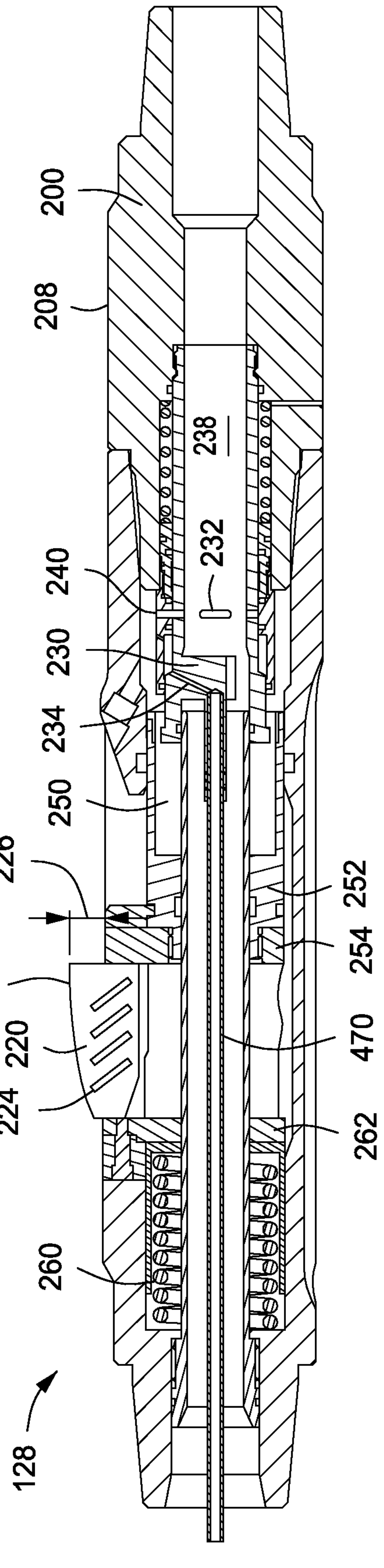
252
470
248-5
248-4
248-3
248-2
230
248-1
128

FIG. 7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224
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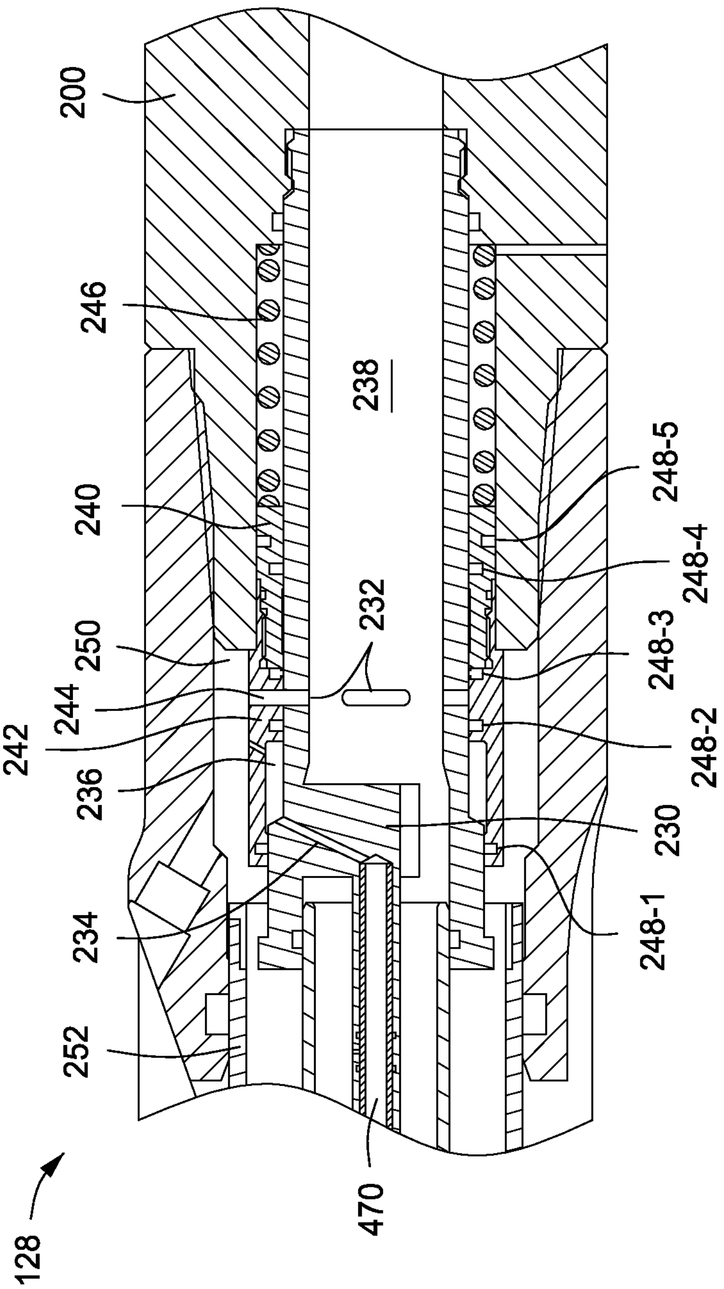
128

FIG. 8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128
248-5
248-4
248-3
248-2
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248-1

FIG. 9

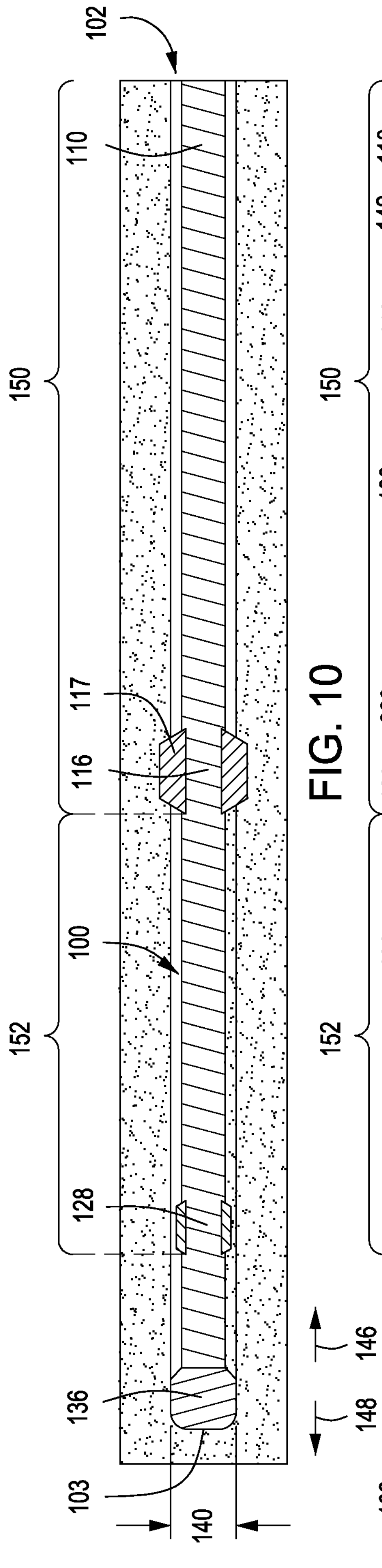


FIG. 10

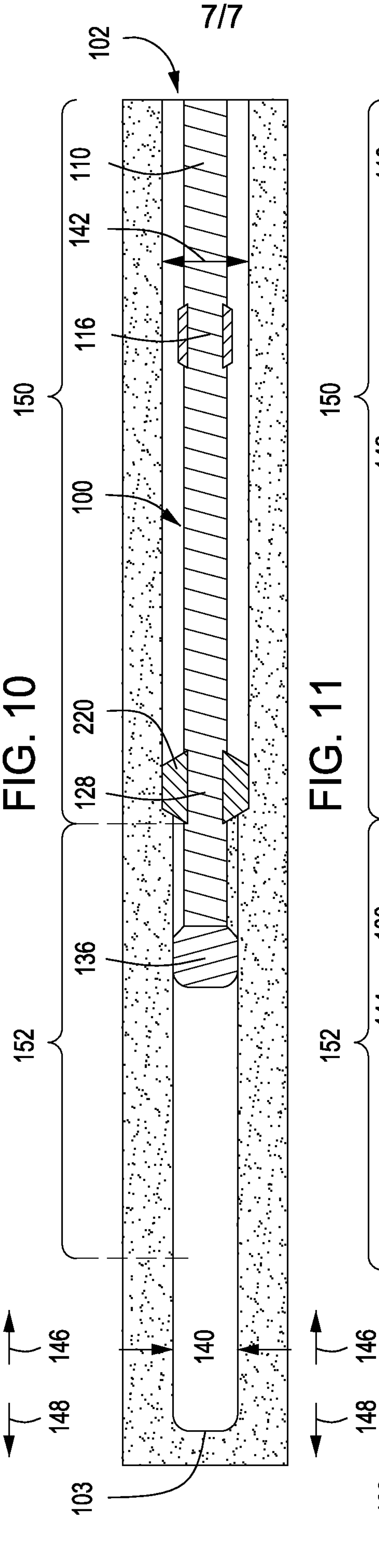


FIG. 11

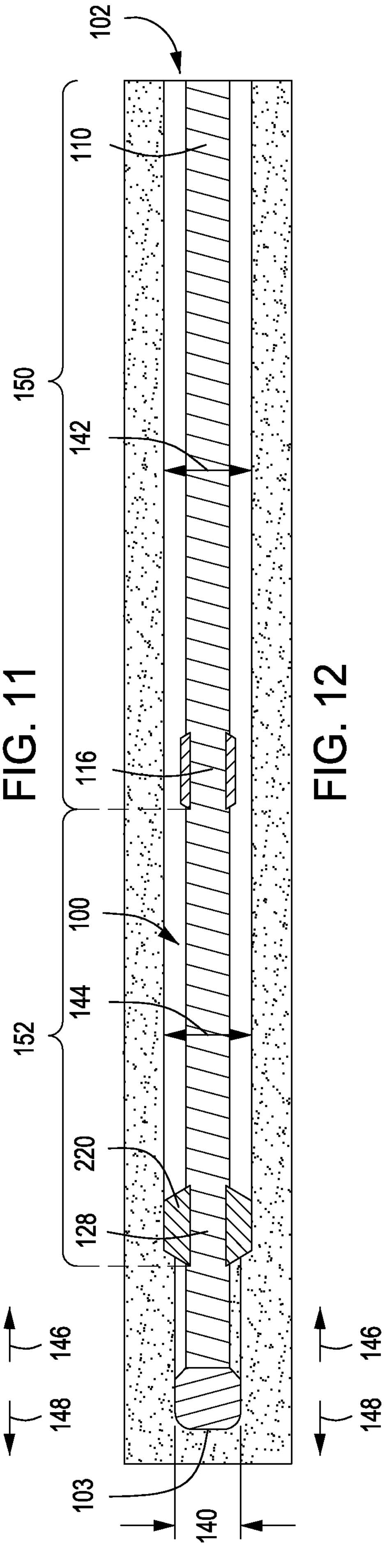
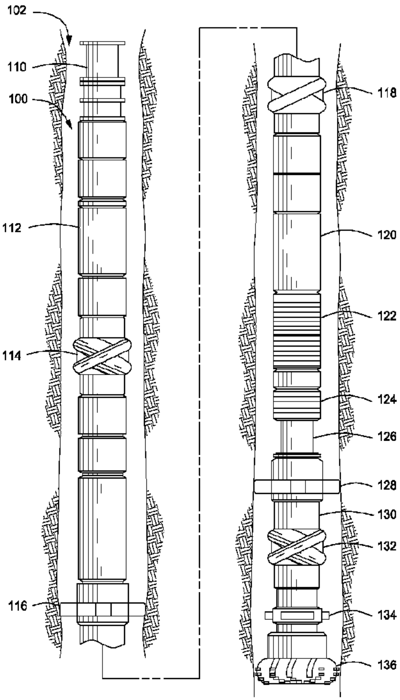


FIG. 12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