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(54) Title: MECHANISM AND CHAIR FOR POWERED COMBINED AND INDEPENDENT SEAT BACK AND LEG REST MOTION

(57) Abstract: A furniture member mechanism includes a first actuator device electrically operated to displace first and second seat back actuation links connected to and operating to rotate a seat back member between upright and fully reclined positions. A pantograph linkage set connected to a leg rest member is at least partially supported in an extended position by rotational contact with a support rod. A second actuator device identical to the first actuator device is electrically operated to axially rotate a drive rod connected to a drive link. The drive link is connected to and displaces the pantograph linkage set between the stowed and extended positions. A swing lever rotatably connected to the support rod is rotated during operation of the second actuator device to extend the pantograph linkage set. The swing lever in a fully rotated position displaces the support rod creating a furniture member tilt position.

MECHANISM AND CHAIR FOR POWERED COMBINED
AND INDEPENDENT SEAT BACK AND LEG REST MOTION

FIELD

5 [0001] The present disclosure relates to a furniture member mechanism providing for power combined or independent seat back and leg rest motions.

BACKGROUND

10 [0002] This section provides background information related to the present disclosure which is not necessarily prior art.

[0003] Furniture members such as chairs, sofas, loveseats, sectionals, and the like commonly include a mechanism that permits the occupant of the furniture member to manually move a leg rest member from a stowed to an 15 extended position to support the legs of the occupant. Occupant supplied weight/force is commonly required in these furniture members to rotate a seat back member between an upright and a fully reclined position, independent of the mechanism operation moving the leg rest member. Power actuators are also known which provide for powered or automatic operation of a leg rest member 20 followed sequentially by powered operation of a seat back member. These designs commonly require the leg rest member to extend first followed by rotation of the seat back member. To reverse the furniture member position, the power actuator is operated to rotate the seat back member forward followed sequentially by retraction of the leg rest member. Independent operation of the 25 leg rest member and seat back member are typically not provided in these designs.

SUMMARY

[0004] This section provides a general summary of the disclosure, and 30 is not a comprehensive disclosure of its full scope or all of its features.

[0005] According to several embodiments, a furniture member mechanism for power combined and independent seat back and leg rest motion

includes a first actuator device connected to and electrically operated to displace a seat back member between an upright position and a fully reclined position. A second actuator device is connected to and electrically operated to displace a leg rest member between a stowed and a fully extended position. The
5 mechanism is selectively operated either having one of the first and second actuator devices energized while the other one of the first and second actuator devices is de-energized, or having both the first and second actuator devices energized simultaneously.

10 [0006] According to further embodiments, a furniture member mechanism for power combined and independent seat back and leg rest motion includes a first actuator device electrically operated to displace first and second seat back actuation links connected to and operating to rotate a seat back member between an upright position and a fully reclined position. A second actuator device is electrically operated to rotate at least one drive link connected
15 to and displacing a leg rest member between a stowed and a fully extended position. The mechanism is selectively operated having one of the first and second actuator devices energized while the other one of the first and second actuator devices is de-energized, or having both the first and second actuator devices energized simultaneously.

20 [0007] According to other embodiments, a furniture member mechanism includes a first actuator device electrically operated to displace first and second seat back actuation links connected to and operating to rotate a seat back member between upright and fully reclined positions. A pantograph linkage set connected to a leg rest member is at least partially supported in an extended
25 position by rotational contact with a support rod. A second actuator device identical to the first actuator device is electrically operated to axially rotate a drive rod connected to a drive link. The drive link is connected to and displaces the pantograph linkage set between the stowed and extended positions. A swing lever rotatably connected to the support rod is rotated during operation of
30 the second actuator device to extend the pantograph linkage set. The swing lever in a fully rotated position displaces the support rod creating a furniture member tilt position.

[0008] According to still further embodiments, a furniture member includes a furniture frame assembly rotatably connected to a base member. A rocker spring assembly is connected to each of the furniture frame assembly and the base member permitting a rocking motion of the furniture frame assembly
5 with respect to the base member. A mechanism includes a first actuator device electrically operated to displace first and second seat back actuation links connected to and operating to rotate a seat back member between an upright position and a fully reclined position. A pantograph linkage set is connected to a leg rest member. The pantograph linkage set is at least partially supported in an
10 extended position by rotational contact with a support rod. The support rod is connected to opposite first and second side members of the furniture frame assembly. A second actuator device identical to the first actuator device is electrically operated to axially rotate a drive rod connected to at least one drive link, the drive link connected to and displacing the pantograph linkage set
15 between a stowed and the extended positions.

[0009] Further areas of applicability will become apparent from the description provided herein. The description and specific examples in this summary are intended for purposes of illustration only and are not intended to limit the scope of the present disclosure.

20

DRAWINGS

[0010] The drawings described herein are for illustrative purposes only of selected embodiments and not all possible implementations, and are not intended to limit the scope of the present disclosure.

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[0011] Figure 1 is a front right perspective view of a furniture member having a mechanism for powered combined or independent operation of a leg rest member and a seat back member;

[0012] Figure 2 is a right front perspective view of the furniture member of Figure 1 showing the leg rest member in a fully extended position;

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[0013] Figure 3 is right front perspective view of the furniture member of Figure 1 showing the leg rest member in a fully extended position and the seat back member in a fully reclined position;

[0014] Figure 4 is a right front perspective view of an extended pantograph linkage set of the mechanism of Figure 1 connected to both a drive rod and a support shaft;

5 **[0015]** Figure 5 is a right front perspective view of a portion of the mechanism of Figure 1;

[0016] Figure 6 is a right rear perspective view of the mechanism of Figure 5;

10 **[0017]** Figure 7 is a right rear perspective view of a portion of the furniture member of Figure 1 showing components operated to control seat back member rotation;

[0018] Figure 8 is a right rear perspective view of a drive and swing link portion of the mechanism operated to control leg rest member rotation;

15 **[0019]** Figure 9 is a right rear perspective view of a portion of the furniture member of Figure 1 showing components operated to control leg rest member rotation;

[0020] Figure 10 is a right side elevational view of a portion of the mechanism of Figure 6;

[0021] Figure 11 is a right side elevational view of area 11 of Figure 10 having the tilt swing lever removed for clarity;

20 **[0022]** Figure 12 is a front right perspective view of a swing lever and tilt swing lever combination of the mechanism of Figure 6;

[0023] Figure 13 is a right rear perspective view of the swing lever and tilt swing lever combination of Figure 12;

25 **[0024]** Figure 14 is a right side elevational view of the furniture member of Figure 2 having a furniture member right side member removed for clarity;

[0025] Figure 15 is a right side elevational view of area 15 of Figure 14;

30 **[0026]** Figure 16 is a right side elevational view modified from Figure 10 to show the mechanism in a leg rest extended and full rearward tilt position;

[0027] Figure 17 is a right side elevational view of area 17 of Figure 16;

[0028] Figure 18 is a right rear perspective view of the fully extended position of the pantograph linkage set in a object contact/release position; and

[0029] Figure 19 is a right rear perspective view of area 19 of Figure 18.

5 **[0030]** Corresponding reference numerals indicate corresponding parts throughout the several views of the drawings.

DETAILED DESCRIPTION

10 **[0031]** Example embodiments will now be described more fully with reference to the accompanying drawings.

[0032] Referring to Figure 1, a furniture member 10 includes a furniture frame assembly 12 which is rotatably supported with respect to a base member 14. A seat back member 16 is rotatably connected to furniture frame assembly 12 and can rotate from a fully upright position in a seat back recline direction "A" 15 or return from a fully reclined position in a seat back return direction "B" toward the fully upright position, or be positioned at any position therebetween. Seat back member 16 is rotatably connected to furniture frame assembly 12 using oppositely positioned rotational connectors 18 (only one of which is clearly visible in this view). Furniture frame assembly 12 includes a first side member 20 positioned with respect to an occupant's right hand side for an occupant seated on furniture member 10, and a second side member 22 positioned on the occupant's left hand side. A leg rest member 24 is extensible from a fully stowed position shown in a leg rest extension direction "C" and returnable in a leg rest retraction direction "D" using a mechanism 26 which is connected to each of the 25 furniture frame assembly 12 and base member 14. Movement of the seat back member 16 is also controlled at least in the seat back recline direction "A" by operation of mechanism 26.

30 **[0033]** Mechanism 26 includes each of a first actuator device 28 which is used to control rotation of the seat back member 16, and a second actuator device 30 which is used to extend or retract leg rest member 24 as well as to permit a tilting motion of furniture frame assembly 12 with respect to base member 14. The tilting motion of furniture frame assembly 12 is with respect to

a rear rotation direction "E" and a forward rotation direction "F". Operation of second actuator device 30 simultaneously controls displacement of leg rest member 24 as well as tilt rotation of furniture frame assembly 12. For example, as leg rest member 24 is extended in the leg rest extension direction "C", 5 furniture frame assembly 12 is tilted by rotation in the rear rotation direction "E". Opposite rotation of leg rest member 24 also causes an opposite rotation of furniture frame assembly 12 in the forward rotation direction "F".

[0034] First and second actuator devices 28, 30 are identical to each other, and each is rotatably connected to a rigid tube 32. Rigid tube 32 is fixedly 10 connected to each of the first and second side members 20, 22 to prevent axial rotation of rigid tube 32. This provides a fixed reference point for operation of either of the first or second actuator devices 28, 30. First actuator device 28 is connected to and operates a seat back operating portion 34 of mechanism 26. Seat back operating portion 34 includes each of a first seat back actuation link 15 35 positioned proximate to first side member 20 and a second seat back actuation link 36 positioned proximate to second side member 22. A lateral drive member 38, which according to several embodiments is a length of wood material, but can be any suitable material such as metal or plastic, is movably connected with respect to second side member 22 and connected by a seat 20 back linkage set 40 to seat back member 16. Displacement of lateral drive member 38 in a drive member powered motion direction "G" by operation of first actuator device 28 causes a reclining rotation of seat back member 16 in the seat back recline direction "A". To provide for rotation of seat back member 16, a rotational fastener 42 is used to rotatably connect seat back linkage set 40 to 25 seat back member 16. To structurally stiffen furniture frame assembly 12, a forward frame member 44 is oriented substantially perpendicular to and is fixedly connected to each of the first and second side members 20, 22. A frame brace 46, which is positioned in an orientation substantially parallel with respect to rigid tube 32 can also be provided, which is also fixedly connected to each of the first 30 and second side members 20, 22.

[0035] Referring to Figure 2, each of the first and second actuator devices 28, 30 include an actuator motor 48, 48' which is connected to and

provides energy of operation for an actuator drive member 50, 50'. According to several embodiments, actuator motor 48, 48' for each of the first and second actuator devices 28, 30 is operated using a 24-volt DC current. According to several embodiments, a rotary motion of actuator motor 48, 48' is converted to a 5 linear motion by actuator drive member 50, 50', for example using a gear such as a worm gear (not shown). An actuator displacement member 52 is connected to and linearly displaced by actuator drive member 50 and provides for opposing linear motions. Similar to seat back operating portion 34 which is connected to first actuator device 28, second actuator device 30 has a leg rest and tilt 10 operating portion 54 which converts the fore and aft sliding displacement of the actuator displacement member 52 into an axial rotation of a drive rod 56 which is supported by both first and second side members 20, 22 as well as further components, which will be described in greater detail herein. Included with these further support components are drive rod stiffening braces 58, 58' which 15 are connected to drive rod 56, permitting axial rotation of drive rod 56 while providing lateral support by connection of the drive rod stiffening braces 58, 58' to forward frame member 44. Drive rod stiffening braces 58, 58' therefore permit axial rotation of drive rod 56 while limiting or preventing longitudinal bending of drive rod 56. Axial rotation of drive rod 56 displaces both first and second 20 pantograph linkage sets 60, 62 in the leg rest extension direction "C" which is fixedly connected to leg rest member 24.

[0036] To provide additional occupant weight support for the weight of the occupant's legs on leg rest member 24, mechanism 26 further includes a support rod 64 which is oriented substantially parallel to drive rod 56 and is 25 positioned forward of drive rod 56 to provide additional support for first and second pantograph linkage sets 60, 62 in their extended positions. Support rod 64 does not axially rotate but is supported at opposite ends by first and second side members 20, 22. According to several embodiments, a drive rod free end 66 of drive rod 56 can extend partially outward with respect to first side member 30 20. Drive rod free end 66 can be provided for attachment of a lever (not shown) used for manual rotation of drive rod 56 when electrical power is not available for operation of the second actuator device 30.

[0037] Referring to Figure 3, furniture member 10 can be positioned having the seat back member 16 in the fully reclined position simultaneously with the leg rest member 24 being moved to the fully extended position by simultaneous operation of both the first and second actuator devices 28, 30. As 5 previously noted, as the leg rest member 24 extends in the leg rest extension direction "C", furniture frame assembly 12 is tilted rearwardly with respect to the rear rotation direction "E". In a furniture member frame tilt position, a frame assembly front corner 68 is elevated with respect to a frame assembly rear corner 70 of furniture frame assembly 12 when the leg rest member 24 is in any 10 extended position with respect to forward frame member 44. Mechanism 26 of furniture member 10 can also be operated by energizing only one of the first or second actuator devices 28, 30 independently of the other, to either rotate seat back member 16 or extend leg rest member 24.

[0038] Furniture member 10 further provides the option for the 15 operator to return the seat back member 16 to the fully upright position by independent powered operation of first actuator device 28, causing seat back member 16 to rotate in the seat back return direction "B" while the leg rest member 24 is still in any extended position. Conversely, the operator can also return the leg rest member 24 from any extended position to the fully stowed or 20 retracted position by movement in the leg rest retraction direction "D" by independent operation of second actuator device 30, while the seat back member 16 is retained in the upright or any reclined position. This optional operation of either the seat back member 16 or the leg rest member 24 is permitted by the independent connection and operation of the first and second 25 actuator devices 28, 30.

[0039] Referring to Figure 4, features relating to the drive rod 56, support rod 64, and each of the first and second pantograph linkage sets 60, 62 are shown in greater detail, having the first and second pantograph linkage sets 60, 62 in their fully extended positions. To extend the first and second 30 pantograph linkage sets 60, 62, drive rod 56 is rotated in a first drive rod rotation direction "H" which is counterclockwise as viewed in Figure 4. This counterclockwise rotation of drive rod 56 is caused by a counterclockwise

rotation of first and second leg rest drive links 74, 74'. It is noted that each of the components connected to and operating the first and second pantograph linkage sets 60, 62 are substantially opposite and mirror image configurations of each other; therefore, the following discussion of the connections and operation of first 5 pantograph linkage set 60 applies equally to second pantograph linkage set 62. The first leg rest drive link 74 is substantially triangular shaped and includes a drive link flange 76 which is fixedly connected to drive rod 56. Axial rotation of drive rod 56 therefore co-rotates the leg rest drive link 74. Rotation of first leg rest drive link 74 in the first drive rod rotation direction "H" also co-rotates a 10 swing link 78 which is rotatably connected to first pantograph linkage set 60. It should be evident that an opposite axial rotation of drive rod 56 in a clockwise rotation direction will cause retraction of the first and second pantograph linkage sets 60, 62.

[0040] A contact flange 80 of leg rest drive link 74, which is oriented 15 substantially perpendicular to a triangular shaped body of first leg rest drive link 74, directly contacts swing link 78 to cause rotation of swing link 78 thereby matching the first drive rod rotation direction "H". Swing link 78 is not directly connected to first leg rest drive link 74, but is induced to rotate when pushed by contact flange 80. Contact between swing link 78 and first leg rest drive link 74 20 is normally maintained by a biasing force created by a biasing member 82 which is connected to both first leg rest drive link 74 and swing link 78. Swing link 78 is rotatably connected to drive rod 56, and is therefore permitted to freely rotate with respect to drive rod 56.

[0041] A pantograph connecting link 84 is rotatably connected to first 25 pantograph linkage set 60 and rotatably connected to support rod 64. The weight of the occupant's legs carried by the leg rest member (not shown in this view) is therefore distributed through both swing link 78 and pantograph connecting link 84. This distributes the occupant's leg weight to each of the drive rod 56 and the support rod 64. First pantograph linkage set 60 further 30 includes a leg rest rotational fitting 86 acting as a bearing to permit reduced friction rotation of pantograph connecting link 84 with respect to support rod 64. A leg rest connecting flange 88 is provided at a free end of first pantograph

linkage set 60 which is used as a mounting surface for leg rest member 24 shown and described in reference to Figure 1.

[0042] Referring to Figure 5, the first and second actuator devices 28, 30 are individually rotatably connected to rigid tube 32 using either a first 5 actuator mount bracket 90 or a second actuator mount bracket 92. A first actuator mount pin 94 permits first actuator device 28 to rotate with respect to first actuator mount bracket 90. Similarly, a second actuator mount pin 96 permits second actuator device 30 to rotate with respect to second actuator mount bracket 92. According to several embodiments, a drive rod support brace 10 98 is connected to first actuator mount bracket 90 and also to drive rod 56 to provide additional support for drive rod 56.

[0043] Further components of seat back operating portion 34 include a swing connection tube 100 which is substantially U-shaped and is freely rotatably supported on drive rod 56. Swing connection tube 100 is rotated by 15 extension or retraction of a first actuator extension shaft 102, which is extendable or retractable from actuator displacement member 52' during operation of first actuator device 28. Swing connection tube 100 includes a first tube arm 104 oriented substantially parallel with respect to a second tube arm 106. First tube arm 104 is rotatably connected to drive rod 56 using a first arm 20 bracket 108. Similarly, second tube arm 106 is rotatably connected to drive rod 56 using a second arm bracket 110. First seat back actuation link 35 is rotatably connected to first tube arm 104 using a first spin fitting 112. Similarly, a second spin fitting 114 is used to rotatably connect second seat back actuation link 36 to second tube arm 106. Rotation of swing connection tube 100 with respect to 25 drive rod axis of rotation 72 therefore displaces first and second seat back actuation links 35, 36 which are individually connected to and displace each of a first mount plate 116 and a second mount plate 118. First mount plate 116 includes an elongated slot 120 which slidably receives support rod 64. Similarly, second mount plate 118 includes an elongated slot 122 to also slidably receive 30 support rod 64. Support rod 64 can therefore be substantially fixed in position with respect to drive rod 56 even as the first and second mount plates 116, 118

are displaced in either a forward or a rearward direction by rotation of swing connection tube 100.

[0044] With continuing reference to Figures 5 and 1, the lateral drive member 38 is fixed to a plate flange 124 extending from first mount plate 116.

5 The displacement of second mount plate 118 in a forward or rearward direction by rotation of swing connection tube 100 therefore longitudinally displaces lateral drive member 38, which thereby rotates the seat back member 16 via seat back linkage set 40. Support rod 64, which is fixed in position, extends through the individual elongated slots 120, 122. A length of each of the elongated slots 120, 10 122 is therefore predetermined to accommodate the total forward or rearward displacement of the first or second mount plates 116, 118.

[0045] The second actuator device 30 further includes a second actuator extension shaft 126 which extends in a forward or rearward general direction by operation of second actuator device 30. Second actuator extension

15 shaft 126 is connected to a drive toggle connector 128. Drive toggle connector 128 is connected to a drive toggle connector extension rod 130 such that drive toggle connector extension rod 130 is co-linearly displaced during displacement of drive toggle connector 128. A drive toggle 132 is connected to drive rod 56 and rotatably connected to drive toggle connector 128. Extension of drive toggle 20 connector 128 during extension or retraction of second actuator extension shaft 126 rotates drive toggle 132, thereby axially rotating drive rod 56. Because drive rod 56 is substantially square or rectangular in cross-sectional shape, the geometry of the connectors used between drive toggle 132 and drive rod 56 are also square or rectangular in shape, matching the geometry of drive rod 56.

[0046] A swing lever 134 is rotatably connected to support rod 64 at a swing lever rotation end 136 such that swing lever 134 is freely rotatable with respect to support rod 64. During powered operation of second actuator device

30 30, drive toggle connector 128 contacts swing lever 134 and thereby rotates swing lever 134 with respect to support rod 64. A tilt swing lever 137 is connected to base member 14 using a tilt swing mount bracket 138 and a tilt swing rotation pin 140. Tilt swing lever 137 is rotatably connected to swing lever 134. Rotation of swing lever 134 causes an oppositely directed rotation of tilt

swing lever 137. A force exerted by drive toggle connector 128 to swing lever 134 and tilt swing lever 137 causes furniture frame assembly 12 to rotate (tilt) during extension of the leg rest assembly (only partially shown with respect to second pantograph linkage set 62). Because support rod 64 is substantially 5 fixed in position with respect to furniture frame assembly 12, as the combination of swing lever 134 and tilt swing lever 137 rotate by displacement of drive toggle connector 128, the tilt swing lever 137 and the swing lever 134 will rotate into a substantially co-linear orientation as will be described in greater detail in reference to Figures 16 and 17. This linear alignment creates a lifting force 10 pushing upwardly and forwardly on support rod 64, causing rear rotation or tilt of furniture frame assembly 12.

[0047] Operation of first actuator device 28 causes rotation of swing connection tube 100 to displace the first and second mount plates 116, 118 but causes no axial rotation of drive rod 56. Rotation of drive rod 56 only occurs 15 during operation of second actuator device 30 to both extend the first and second pantograph linkage sets 60, 62 and to produce the rearward tilt of furniture frame assembly 12. The support rod 64 is not axially rotatable with respect to a support rod longitudinal axis 142 however support rod 64 is displaceable by the rotation of swing lever 134 and tilt swing lever 137 to 20 produce the rearward tilt of furniture frame assembly 12.

[0048] Referring to Figure 6, the distinct operational portions of mechanism 26 for controlling seat back rotation or leg rest and tilt movement are more clearly visible by removal of the furniture frame assembly 12. First actuator device 28 operates to rotate swing connection tube 100 which forwardly 25 displaces each of the first and second seat back actuation links 35, 36. Forward displacement of the first and second seat back actuation links 35, 36, in turn, forwardly and upwardly displace the first and second mount plates 116, 118. Reversing the operation of first actuator device 28 reverses the rotation of swing connection tube 100, thereby retracting the first and second seat back actuation 30 links 35, 36 and second mount plates 116, 118. As previously noted, the forward or rearward displacements of first or second mount plates 116, 118 occur independently of support rod 64 such that support rod 64 remains in position with

respect to support rod longitudinal axis 142 during the displacement of first or second mount plates 116, 118.

[0049] With continuing reference to Figures 6 and 1-3, independent operation of second actuator device 30 displaces the actuator displacement 5 member 52 thereby rotating drive toggle connector 128 and drive toggle 132. Rotation of drive toggle 132 axially rotates drive rod 56, thereby co-rotating both leg rest drive link 74 and swing link 78. First pantograph linkage set 60 is not shown for clarity, however it is noted that rotation of both leg rest drive links 74, 74' and swing links 78, 78' act to extend first and second pantograph linkage 10 sets 60, 62 to thereby extend the leg rest member. Because either first or second actuator device 28, 30 can be operated at any one time, or because both first and second actuator devices 28, 30 can be simultaneously operated, the occupant can choose either independent operation of the leg rest member or the seat back member, or simultaneous operation of both the leg rest member and 15 seat back member. Any position of either the leg rest member 24 or the seat back member 16 can therefore be selected by the occupant independent of the other.

[0050] The tilt swing lever 137 is rotatably connected to the swing lever 134 using a tilt swing lever pin 144. Tilt swing lever pin 144 therefore displaces 20 both the swing lever 134 and support rod 64 when tilt swing lever 137 is rotated. In the free position shown for tilt swing lever 137, tilt swing lever 137 is freely disposed on drive toggle connector extension rod 130 when the first and second pantograph linkage sets 60, 62 are substantially in their retracted positions. Limited extension of the first and second pantograph linkage sets 60, 62 can 25 occur before drive toggle connector 128 contacts tilt swing lever 137. Continued contact between drive toggle connector 128 and tilt swing lever 137 will thereafter rotate tilt swing lever 137 and swing lever 134, and cause displacement of support rod 64, thereby creating the tilt position of mechanism 26. This will be shown and described in greater detail in reference to Figures 14- 30 17.

[0051] Rotational bearings 146 are provided for each of the first and second arm brackets 108, 110 (only second arm bracket 110 is clearly visible in

this view). The rotational bearings 146 permit the axial rotation of drive rod 56 with respect to drive rod axis of rotation 72 independent of the rotation of swing connection tube 100. This allows the rotational axis of swing connection tube 100 to also be maintained coaxial with respect to drive rod axis of rotation 72

5 without requiring co-rotation of swing connection tube 100 as drive rod 56 rotates.

[0052] Referring to Figure 7, in addition to the capability of mechanism 26 to provide for leg rest extension and retraction and seat back rotation, mechanism 26 further provides for a rocking motion of furniture frame assembly 10 12 with respect to base member 14 by manual force/weight distribution of the occupant of furniture member 10, as commonly known. This rotation or rocking motion of furniture frame assembly 12 can be controlled using an opposed set of rocker spring assemblies 148, 148' (only second rocker spring assembly 148' is clearly visible in this view). The rocker spring assemblies 148, 148' are 15 connected to the first and second side members 20, 22 and to the base member 14. The axis of rotation for the rocking motion of furniture frame assembly 12 with respect to base member 14 is therefore determined by the position of the rocker spring assemblies 148, 148'. The rocking motion of furniture frame assembly 12 occurs with respect to a rearward rocking direction "J" and an 20 opposite forward rocking direction "K". These rocking direction motions are independent of rear and forward rotation directions "E", "F" because the rear and forward rotation directions "E", "F" are oriented with respect to drive rod axis of rotation 72.

[0053] As further shown in Figure 7, to return the seat back member 25 16 from the fully reclined to the upright position, first actuator device 28 is operated to retract first actuator extension shaft 102 with respect to actuator displacement member 52'. Because first actuator extension shaft 102 is rotatably connected to a first actuator connecting bracket 150, which is also connected to swing connection tube 100, this retraction of first actuator 30 extension shaft 102 rotates swing connection tube 100 in a swing rotation direction "L" with respect to drive rod axis of rotation 72. Again and as previously noted, rotation of swing connection tube 100 in the swing rotation direction "L"

[0054] With the first and second pantograph linkage sets 60, 62 positioned in the fully retracted positions (only second pantograph linkage set 62 is clearly visible in this view), the first and second pantograph linkage sets 60, 62 are each received in an individual one of a first pantograph clearance aperture 152 or a second pantograph clearance aperture 154. The first and second pantograph clearance apertures 152, 154 are each created in the forward frame member 44. When leg rest member 24 is positioned in the stowed position, leg rest member 24 contacts forward frame member 44. The first and second pantograph clearance apertures 152, 154 permit a continuous connection between first and second pantograph linkage sets 60, 62 and leg rest member 24 through forward frame member 44 in any position of leg rest member 24.

[0055] Referring to Figure 8, the leg rest drive link 74 is shown in the position corresponding to a fully retracted position of the first and second pantograph linkage sets 60, 62 (only first pantograph linkage set 60 is shown in this view). As drive rod 56 is axially rotated in the first drive rod rotation direction "H", leg rest drive link 74 is also co-rotated in the first drive rod rotation direction "H". The contact flange 80 of leg rest drive link 74 provides direct contact between leg rest drive link 74 and swing link 78 at an edge face 156 of swing link 78. This direct contact causes simultaneous rotation of swing link 78 as leg rest drive link 74 rotates in the first drive rod rotation direction "H". As previously noted, swing link 78 is freely rotationally positioned with respect to drive rod 56 and therefore does not directly rotate in response to rotation of drive rod 56. As

swing link 78 is directed to rotate by contact flange 80, a rotational fastener 158 connecting swing link 78 to a link connecting end 160 of first pantograph linkage set 60 transfers the rotational motion of swing link 78 to a forward translation of link connecting end 160 and therefore to first pantograph linkage set 60.

5 [0056] Referring to Figure 9 and again to Figure 8, leg rest drive link 74 is shown following rotation of drive rod 56 in the first drive rod rotation direction "H", causing full extension of both first and second pantograph linkage sets 60, 62. At this time, leg rest drive link 74 is rotated greater than 90 degrees and approximately 110 degrees with respect to its orientation in the leg rest fully
10 retracted position shown and described in Figure 8. As previously noted, in addition to the support provided for the occupant's leg weight by swing links 78, 78', pantograph connecting links 84, 84' also distribute a portion of the occupant's leg weight to support rod 64. The first and second pantograph clearance apertures 152, 154, provided in forward frame member 44, provide
15 clearance for maximum extension of first and second pantograph linkage sets 60, 62. Rotation of drive rod 56 in the first drive rod rotation direction "H" results from axial displacement in a substantially forward direction of second actuator extension shaft 126 which is displaced by operation of second actuator device 30. This displacement of second actuator extension shaft 126 causes rotation of
20 drive toggle connector 128 and drive toggle 132, which is directly connected to drive rod 56. As previously noted, extension or retraction of first and second pantograph linkage sets 60, 62 occurs independently of any motion imparted by operation of first actuator device 28.

25 [0057] Referring to Figure 10, a rotational pin 162 is provided to rotatably connect swing lever 134 to tilt swing lever 137. As previously noted, swing lever 134 is rotatably connected to support rod 64. The position shown for swing lever 134, with respect to drive toggle connector extension rod 130, permits free rotational displacement of swing lever 134 with respect to drive toggle connector extension rod 130. In this position, drive toggle connector 128
30 is spaced from swing lever 134, allowing free rotation of both swing lever 134 and tilt swing lever 137 without contact from and therefore in a non-powered manner with respect to drive toggle connector 128. The free rotation positions of

swing lever 134 and tilt swing lever 137 also permit rocking motion of furniture member 10.

[0058] Referring to Figure 11 and again to Figure 10, swing lever 134 includes a pin aperture 164 which receives the rotational pin 162. Swing lever 5 134 also includes a bulbous end 166 having a curved end face 168. Curved end face 168 is generally convex in shape and is positioned during operation predominantly below drive toggle connector extension rod 130. In the free position of swing lever 134 wherein drive toggle connector 128 is not in contact with curved end face 168, the bulbous end 166 of swing lever 134 is free to 10 displace in either of a first swing lever sliding direction "N" or an opposite second swing lever sliding direction "P" as swing lever 134 rotates with respect to support rod 64. This sliding motion in either of the first or second swing lever sliding directions "N", "P" permits rocking motion of furniture member 10 while maintaining drive toggle connector extension rod 130 sliding contact with swing 15 lever 134 in all rotated positions of swing lever 134. Drive toggle connector extension rod 130 acts as a guide to maintain swing lever 134 in a position for curved end face 168 to be contacted by drive toggle connector 128, shown and described in better detail in reference to Figures 16 and 17, for powered rotation of swing lever 134.

20 **[0059]** Referring to Figure 12 and again to Figures 10-11, swing lever 134 includes a rod clearance aperture 170 to allow the free sliding motion of drive toggle connector extension rod 130 with respect to swing lever 134 as swing lever 134 rotates. A longitudinal cavity 171 is also provided in tilt swing lever 137, which receives bulbous end 166 of swing lever 134, to provide further 25 support and sliding guidance for relative displacement between bulbous end 166 and tilt swing lever 137. This maintains alignment between swing lever 134 and tilt swing lever 137 during rotation.

[0060] Referring to Figure 13 and again to Figure 12, according to 30 several embodiments tilt swing lever 137 has a substantially U-shape and includes opposed first and second lever arms 172, 174. Longitudinal cavity 171 is created between first and second lever arms 172, 174. The first and second lever arms 172, 174 are both fixedly connected to a lever connecting member

176. The tilt swing rotation pin 140 is slidably received through lever connecting member 176. In addition to lever connecting member 176, tilt swing lever 137 further includes a lever post 178 which spans opposite ends of first and second lever arms 172, 174 with respect to the location of lever connecting member 176.

5 Lever post 178 creates a positive point of contact when contacting a swing lever face 180 of swing lever 134 to establish a maximum rotated position of tilt swing lever 137 and swing lever 134.

[0061] Referring to Figure 14, mechanism 26 is shown at the fully extended position of first and second pantograph linkage sets 60, 62 and also at 10 the point of contact between drive toggle connector 128 and swing lever 134. To reach this position, second actuator device 30 is operated, thereby axially extending second actuator extension shaft 126 in an extension shaft direction of extension "Q". Up until the point of contact is reached between drive toggle connector 128 and swing lever 134, the furniture frame assembly 12 is free to 15 rock in either of the rearward or forward rocking directions "J", "K" with respect to base member 14. Immediately upon contact between drive toggle connector 128 and swing lever 134, further free rocking motion of furniture frame assembly 12 is precluded.

[0062] Referring to Figure 15 and again to Figure 14, second actuator 20 extension shaft 126 is rotatably connected to drive toggle connector 128 using a pinned connection through a clevis 182. Drive toggle connector 128 is fixedly connected to drive toggle connector extension rod 130, therefore extension of second actuator extension shaft 126 co-extensively displaces each of drive toggle connector 128 and drive toggle connector extension rod 130. As this 25 displacement occurs, the curved end face 168 of drive toggle connector 128 is brought into direct contact with swing lever 134. Further subsequent extension of second actuator extension shaft 126 in extension shaft direction of extension "Q" causes a combined and oppositely directed rotation of swing lever 134 which rotates with respect to support rod 64, and tilt swing lever 137 which rotates with 30 respect to tilt swing rotation pin 140. The axis of common rotation between swing lever 134 and tilt swing lever 137 is with respect to rotational pin 162.

[0063] Referring to Figure 16 and again to Figure 15, during extension of second actuator extension shaft 126 in the extension shaft direction of extension "Q" curved end face 168 of bulbous end 166 contacts a second curved end face 184 of drive toggle connector 128. Because tilt swing lever 137 is 5 rotatably connected using tilt swing rotation pin 140 to tilt swing mount bracket 138, and tilt swing mount bracket 138 is fixedly connected to base member 14, a clockwise rotation of tilt swing lever 137 causes a corresponding counterclockwise rotation of swing lever 134 as viewed in Figure 16 with respect to the axis of rotational pin 162. As tilt swing lever 137 rotates in the clockwise 10 rotation direction, the tilt swing lever 137 approaches but does not reach co-axial alignment with a longitudinal axis of swing lever 134. This results in a net displacement in a tilt direction "Z" of support rod 64 because of the connection between swing lever rotation end 136 and support rod 64. Displacement in tilt direction "Z" of support rod 64 therefore provides a forward and upward motion 15 of the front corner 68 of furniture frame assembly 12 and a rearward rotational lowering of the frame assembly rear corner 70 as shown and described in reference to Figure 3. The weight of the occupant is therefore partially supported in the tilt position by swing lever 134, tilt swing lever 137, and rotational pin 162. Because the leg rest assembly can be in its fully extended 20 position during this tilt motion, the leg rest member 24 is further elevated with respect to a floor or planar surface upon which base member 14 is supported.

[0064] Referring to Figure 17 and again to Figure 16, to reduce friction between curved end face 168 and second curved end face 184 during rotation, these two curved surfaces share a substantially corresponding geometry. At the 25 tilt position of mechanism 26, a tilt swing lever longitudinal axis 186 is closely but not co-axially aligned with respect to a swing lever longitudinal axis 188 to prevent reaching a locking or over-center position of swing lever longitudinal axis 188.

[0065] Referring to Figure 18, mechanism 26 is also provided with a 30 release capability such that if an object 190 is encountered by either the leg rest member 24 or either of the first or second pantograph linkage sets 60, 62 when the leg rest member 24 is returned in the leg rest retraction direction "D", swing

link 78 will release from its contact position with leg rest drive link 74. Drive rod 56 will continue its axial rotation with respect to a second drive rod rotation direction "R" together with leg rest drive link 74 while swing link 78 rotatably separates with respect to contact flange 80 of leg rest drive link 74. This permits

5 the leg rest member 24 and each of the first and second pantograph linkage sets 60, 62 to remain substantially in the extended or partially extended position and in contact with the object 190 as the powered operation or rotation of drive rod 56 continues. After swing link 78 releases from leg rest drive link 74, only the biasing force of biasing member 82 acts to retract leg rest member 24. This

10 permits the subsequent lifting of leg rest member 24 by manual displacement in the leg rest extension direction "C" to remove object 190 although the leg rest drive link 74 may have continued its further rotation due to rotation of drive rod 56.

[0066] Referring to Figure 19, to provide for the release capability of

15 leg rest member 24 with respect to leg rest drive link 74, biasing member 82 is provided with a biasing member first hook end 192 which is received in an elongated slot 194 created in swing link 78. An opposite biasing member second hook end 196 is engaged in a link slot 198 created in leg rest drive link 74. A biasing force of biasing member 82 acts in a biasing force direction "S".

20 With continuing reference to Figures 18 and 19, as the object 190 is encountered by leg rest member 24 or either of the first or second pantograph linkage sets 60, 62, a gap "T" is created between contact flange 80 and edge face 156 of swing link 78. The distance of gap "T" can vary with the amount of continued rotation of leg rest drive link 74 in the second drive rod rotation direction "R".

25 **[0067]** With continuing reference to Figure 18 and Figure 1, because axial rotation of drive rod 56 is controlled by the occupant of furniture member 10 using second actuator device 30, axial rotation of drive rod 56 can be stopped as soon as the occupant becomes aware of contact with the object 190. Once the object 190 has been cleared, the first and second pantograph linkage sets 60, 62

30 will return by gravity until the edge face 156 of swing link 78 once again contacts contact flange 80 of leg rest drive link 74. This contact will occur at the rotated position reached for leg rest drive link 74. The leg rest member 24 can therefore

return to its fully retracted or stowed position or be retained in a partially extended position depending on where the rotation of leg rest drive link 74 was stopped. According to several embodiments, biasing member 82 can be a compression spring made from spring steel having the biasing force 5 predetermined to ensure the full return of leg rest member 24 to the fully stowed position should leg rest drive link 74 be fully rotated to the position shown and described with reference to Figure 8.

[0068] With continued reference to Figures 1-19, furniture member mechanism 26 for power combined and independent seat back and leg rest 10 motion includes first actuator device 28 electrically operated to displace first and second seat back actuation links 35, 36 which are connected to and operate to rotate seat back member 16 between an upright position (Figure 2) and a fully reclined position (Figure 3). Pantograph linkage set 60, 62 is connected to leg rest member 24. The pantograph linkage set 60, 62 is at least partially 15 supported in an extended position by rotational contact with support rod 64. Second actuator device 30 is identical to the first actuator device 28 and is electrically operated to axially rotate drive rod 56 connected to at least one leg rest drive link 74, 74'. The leg rest drive link 74, 74' is connected to and displaces the pantograph linkage set 60, 62 between stowed (Figure 1) and 20 extended (Figure 2) positions. The swing lever 134 is rotatably connected to the support rod 64 and rotated during operation of the second actuator device 30 to extend the pantograph linkage set 60, 62. The swing lever 134 in a fully rotated position displaces the support rod 64 thereby creating a furniture member tilt 25 position (Figure 3).

[0069] Mechanisms 26 of the present disclosure offer several 25 advantages. By separating the action of rotating seat back member 16 from the action of extending leg rest member 24 through the use of independently operated first and second actuator devices 28, 30, seat back member 16 can be moved independently with respect to leg rest member 24. By further including a 30 tilt control for furniture member 10 with the second actuator device 30, automatic tilt is provided when leg rest member 24 is extended. The provision of first and second actuator devices 28, 30 with the added capability of furniture member 10

to rock provides full rocking, seat back rotation, and independent leg rest extension operations in a single mechanism.

[0070] Example embodiments are provided so that this disclosure will be thorough, and will fully convey the scope to those who are skilled in the art.

5 Numerous specific details are set forth such as examples of specific components, devices, and methods, to provide a thorough understanding of embodiments of the present disclosure. It will be apparent to those skilled in the art that specific details need not be employed, that example embodiments may be embodied in many different forms and that neither should be construed to 10 limit the scope of the disclosure. In some example embodiments, well-known processes, well-known device structures, and well-known technologies are not described in detail.

[0071] The terminology used herein is for the purpose of describing particular example embodiments only and is not intended to be limiting. As used

15 herein, the singular forms "a," "an," and "the" may be intended to include the plural forms as well, unless the context clearly indicates otherwise. The terms "comprises," "comprising," "including," and "having," are inclusive and therefore specify the presence of stated features, integers, steps, operations, elements, and/or components, but do not preclude the presence or addition of one or more

20 other features, integers, steps, operations, elements, components, and/or groups thereof. The method steps, processes, and operations described herein are not to be construed as necessarily requiring their performance in the particular order discussed or illustrated, unless specifically identified as an order of performance. It is also to be understood that additional or alternative steps may be employed.

25 **[0072]** When an element or layer is referred to as being "on," "engaged to," "connected to," or "coupled to" another element or layer, it may be directly on, engaged, connected or coupled to the other element or layer, or intervening elements or layers may be present. In contrast, when an element is referred to as being "directly on," "directly engaged to," "directly connected to," or "directly

30 coupled to" another element or layer, there may be no intervening elements or layers present. Other words used to describe the relationship between elements should be interpreted in a like fashion (e.g., "between" versus "directly between,"

"adjacent" versus "directly adjacent," etc.). As used herein, the term "and/or" includes any and all combinations of one or more of the associated listed items.

[0073] Although the terms first, second, third, etc. may be used herein to describe various elements, components, regions, layers and/or sections, 5 these elements, components, regions, layers and/or sections should not be limited by these terms. These terms may be only used to distinguish one element, component, region, layer or section from another region, layer or section. Terms such as "first," "second," and other numerical terms when used herein do not imply a sequence or order unless clearly indicated by the context. 10 Thus, a first element, component, region, layer or section discussed below could be termed a second element, component, region, layer or section without departing from the teachings of the example embodiments.

[0074] Spatially relative terms, such as "inner," "outer," "beneath," "below," "lower," "above," "upper," and the like, may be used herein for ease of 15 description to describe one element or feature's relationship to another element(s) or feature(s) as illustrated in the figures. Spatially relative terms may be intended to encompass different orientations of the device in use or operation in addition to the orientation depicted in the figures. For example, if the device in 20 the figures is turned over, elements described as "below" or "beneath" other elements or features would then be oriented "above" the other elements or features. Thus, the example term "below" can encompass both an orientation of above and below. The device may be otherwise oriented (rotated 90 degrees or at other orientations) and the spatially relative descriptors used herein interpreted accordingly.

[0075] The foregoing description of the embodiments has been provided for purposes of illustration and description. It is not intended to be exhaustive or to limit the disclosure. Individual elements or features of a particular embodiment are generally not limited to that particular embodiment, but, where applicable, are interchangeable and can be used in a selected embodiment, even if not specifically shown or described. The same may also be varied in many ways. Such variations are not to be regarded as a departure from the disclosure, and all such modifications are intended to be included within the scope of the disclosure.

CLAIMS

What is claimed is:

1. A furniture member mechanism for power combined and independent seat back and leg rest motion, comprising:
 - a first actuator device connected to and electrically operated to displace a seat back member between an upright position and a fully reclined position; and
 - a second actuator device connected to and electrically operated to displace a leg rest member between a stowed and a fully extended position;
 - the mechanism selectively operated either having one of the first and second actuator devices energized while the other one of the first and second actuator devices is de-energized, or having both the first and second actuator devices energized simultaneously.
- 15 2. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 1, further including a drive rod connected to and axially rotated by operation of the second actuation device to extend or retract the leg rest member, wherein operation of the first actuation device does not axially rotate the drive rod.
3. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 2, further including:
 - first and second leg rest drive links connected to the drive rod and co-rotated by rotation of the drive rod during operation of the second actuator device; and
 - first and second swing links freely connected to the leg rest member and rotatably connected to the drive rod, the first and second swing links rotated by the first and second leg rest drive links only in a first drive rod rotation direction.

4. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 3, further including a contact flange extending from the first and second leg rest drive links individually directly contacting one of the first or second swing links acting to rotate the first and
5 second swing links together with the first and second leg rest drive links when the drive rod is rotated in the first drive rod rotation direction; wherein contact by the leg rest member with an object during return of the leg rest member from the fully extended to the stowed position creates a gap between the first and second swing links and the contact flange of the first and second leg rest drive links
10 permitting continued powered retraction of the first and second leg rest drive links without retraction of the leg rest member.

5. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 1, further including:
15 an actuator extension shaft connected to and axially displaced by operation of the second actuator device;
a drive toggle connector connected to the actuator extension shaft having an extension rod;
a support rod connected to a furniture frame assembly; and
20 a swing lever rotatably connected to the support rod and freely displaceable on the extension rod.

6. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 5, further including a tilt
25 swing lever rotatably connected to a base member of the furniture member and rotatably connected to the swing lever, wherein direct contact by the drive toggle connector and the swing lever causes opposite rotations of the swing lever and the tilt swing lever until substantial co-linear alignment of the tilt swing lever and the swing lever displace the support rod thereby rotating the furniture member
30 frame assembly to a tilt position.

7. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 6, wherein extension of the leg rest member and rotation of the furniture member frame assembly to the tilt position occur simultaneously during operation of the second actuator device.

5

8. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 1, further including:

first and second seat back actuation links connected to the first actuator device; and

10 first and second mount plates individually connected to one of the first and second seat back actuation links, the first mount plate connected to a lateral drive member operating to rotate the seat back member.

9. The furniture member mechanism for power combined and 15 independent seat back and leg rest motion of Claim 1, further including:

a drive rod axially rotated by the second actuation device to extend or retract the leg rest member;

20 such that axial rotation of the drive rod does not rotate the swing connection tube; and

25 first and second seat back actuation links connected to the swing connection tube, the first and second seat back actuation links connected to the seat back member such that displacement of the first and second seat back actuation links by rotation of the swing connection tube rotates the seat back member.

10. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 1, further including:

30 first and second seat back actuation links connected to the first actuator device and displaced to rotate the seat back member; and

a swing connection tube defining a substantially U-shape having first and second tube arms each rotatably connected to one of the first or second

seat back actuation links, the first actuator device connected to the swing connection tube and operating when energized to rotate the swing connection tube thereby displacing the first and second seat back actuation links.

5 11. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 1, further including:

a swing connection tube connected to the first actuator device and rotated by the first actuator device to rotate the seat back member; and

10 a first actuator connection bracket rotatably connecting the first actuator to the swing connection tube.

12. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 1, further including:

15 a first biasing member connecting a first leg rest drive link to a first swing link; and

a second biasing member connecting a second leg rest drive link to a second swing link;

wherein the first and second swing links are connected to the leg rest member and contact of the leg rest member with an object during return of

20 the leg rest member from the fully extended to the stowed position creates a gap between the first and second swing links and a contact flange of the first and second leg rest drive links and extension of the first and second biasing members, a biasing force of the first and second biasing members thereafter acting to return the first and second swing links into contact with the contact flanges of the first and second leg rest drive links following removal of the object.

25 13. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 1, wherein the first and second actuator devices each include a 24 volt DC current motor and an actuator drive member operating to transfer motor rotation to a linear drive direction.

14. A furniture member mechanism for power combined and independent seat back and leg rest motion, comprising:

a first actuator device electrically operated to displace first and second seat back actuation links connected to and operating to rotate a seat

5 back member between an upright position and a fully reclined position; and

a second actuator device electrically operated to rotate at least one drive link connected to and displacing a leg rest member between a stowed and a fully extended position;

the mechanism selectively operated having one of the first and
10 second actuator devices energized while the other one of the first and second actuator devices is de-energized, or having both the first and second actuator devices energized simultaneously.

15. The furniture member mechanism for power combined and
15 independent seat back and leg rest motion of Claim 14, further including:

a U-shaped swing connection tube having opposed first and second tube arms each rotatably connected to one of the first and second seat back actuation links; and

20 a first actuator extension shaft extended or retracted by operation of the first actuator device, the first actuator extension shaft rotatably connected to the swing connection tube such that extension of the first actuator extension shaft rotates the swing connection tube.

16. The furniture member mechanism for power combined and
25 independent seat back and leg rest motion of Claim 15, further including a rod freely rotatably supporting both the first and second tube arms of the swing connection tube, the rod axially rotated by operation of the second actuation device to extend the leg rest member without rotation of the swing connection tube.

30

17. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 14, further including an

actuator extension shaft extended or retracted by operation of the second actuator device, the actuator extension shaft rotatably connected to a drive toggle connector.

5 18. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 17, further including:

a drive rod; and

a drive toggle connected to drive rod and rotatably connected to the drive toggle connector, the drive toggle axially rotating the drive rod when 10 rotated by the drive toggle connector.

19. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 14, further including:

a pantograph linkage set connected to the leg rest member;

15 a leg rest drive link connected to the drive rod for co-rotation during axial rotation of the drive rod, and having a contact flange; and

a swing link freely rotatably supported by the drive rod and connected to the pantograph linkage set, the swing link directly contacted by the contact flange to co-rotate the swing link together with the leg rest drive link only 20 in a first drive rod rotation direction to extend the pantograph linkage set.

20. A furniture member mechanism for power combined and independent seat back and leg rest motion, comprising:

25 a first actuator device electrically operated to displace first and second seat back actuation links connected to and operating to rotate a seat back member between an upright position and a fully reclined position;

a pantograph linkage set connected to a leg rest member, the pantograph linkage set at least partially supported in an extended position by rotational contact with a support rod;

30 a second actuator device identical to the first actuator device and electrically operated to axially rotate a drive rod connected to at least one drive

link, the drive link connected to and displacing the pantograph linkage set between a stowed and the extended positions; and

5 a swing lever rotatably connected to the support rod and rotated during operation of the second actuator device to extend the pantograph linkage set, the swing lever in a fully rotated position displacing the support rod creating a furniture member tilt position.

21. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 20, further including:

10 a drive toggle connector connected to the second actuator device; and

15 a drive toggle connected to and co-rotatable with the drive rod and rotatably connected to the drive toggle connector, rotation of the drive toggle connector acting to rotate the drive toggle and thereby to axially rotate the drive rod.

22. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 21, further including an actuator extension shaft extended or retracted by operation of the second actuator device, the actuator extension shaft rotatably connected to a drive toggle connector.

23. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 20, wherein the mechanism is selectively operated in either a first or second mode, the first mode having one of the first and second actuator devices energized while the other one of the first and second actuator devices is de-energized, and the second mode having both the first and second actuator devices energized simultaneously.

30 24. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 20, further including a tilt swing lever rotatably connected to the swing lever and to a base member of the

furniture member, an axis of the tilt swing lever substantially aligned with an axis of the swing lever in the fully rotated position.

25. The furniture member mechanism for power combined and
5 independent seat back and leg rest motion of Claim 20, further including:

a bulbous end of the swing lever having a first curved end face defining a convex shape; and

10 a drive toggle connector connected to the second actuator device, the drive toggle connector including a second curved end face having a geometry defining a concave shape, the concave shape corresponding to convex shape such that a longitudinal displacement of the drive toggle connector causes rotation of the swing lever where the first and second curved end faces contact each other.

15 26. The furniture member mechanism for power combined and independent seat back and leg rest motion of Claim 20, further including:

an extension rod freely extending from the drive toggle connector; and

20 a rod clearance aperture created proximate the bulbous end of the swing lever, the extension rod slidably extending through the rod clearance aperture to maintain the first curved end face of the swing lever in alignment with the second curved end face of the drive toggle connector prior to contact between the first and second curved end faces.

25 27. A furniture member, comprising:

a furniture frame assembly rotatably connected to a base member;

a rocker spring assembly connected to each of the furniture frame assembly and the base member permitting a rocking motion of the furniture frame assembly with respect to the base member; and

a mechanism, including:

a first actuator device electrically operated to displace first and second seat back actuation links connected to and operating to rotate a seat back member between an upright position and a fully reclined position;

5 a pantograph linkage set connected to a leg rest member, the pantograph linkage set at least partially supported in an extended position by rotational contact with a support rod, the support rod connected to opposite first and second side members of the furniture frame assembly; and

10 a second actuator device identical to the first actuator device and electrically operated to axially rotate a drive rod connected to at least one drive link, the drive link connected to and displacing the pantograph linkage set between a stowed and the extended positions.

15 28. The furniture member of Claim 27, further including a swing lever rotatably connected to the support rod and rotated during operation of the second actuator device to extend the pantograph linkage set, the swing lever in a fully rotated position displacing the support rod lifting a front corner of the furniture frame assembly with respect to a rear corner of the furniture frame 20 assembly creating a furniture frame assembly tilt position.

29. The furniture member of Claim 28, further including:

a bulbous end of the swing lever having a first curved end face defining a convex shape; and

25 a drive toggle connector connected to the second actuator device, the drive toggle connector including a second curved end face having a geometry defining a concave shape, the concave shape corresponding to convex shape such that a longitudinal displacement of the drive toggle connector causes rotation of the swing lever where the first and second curved end faces 30 contact each other.

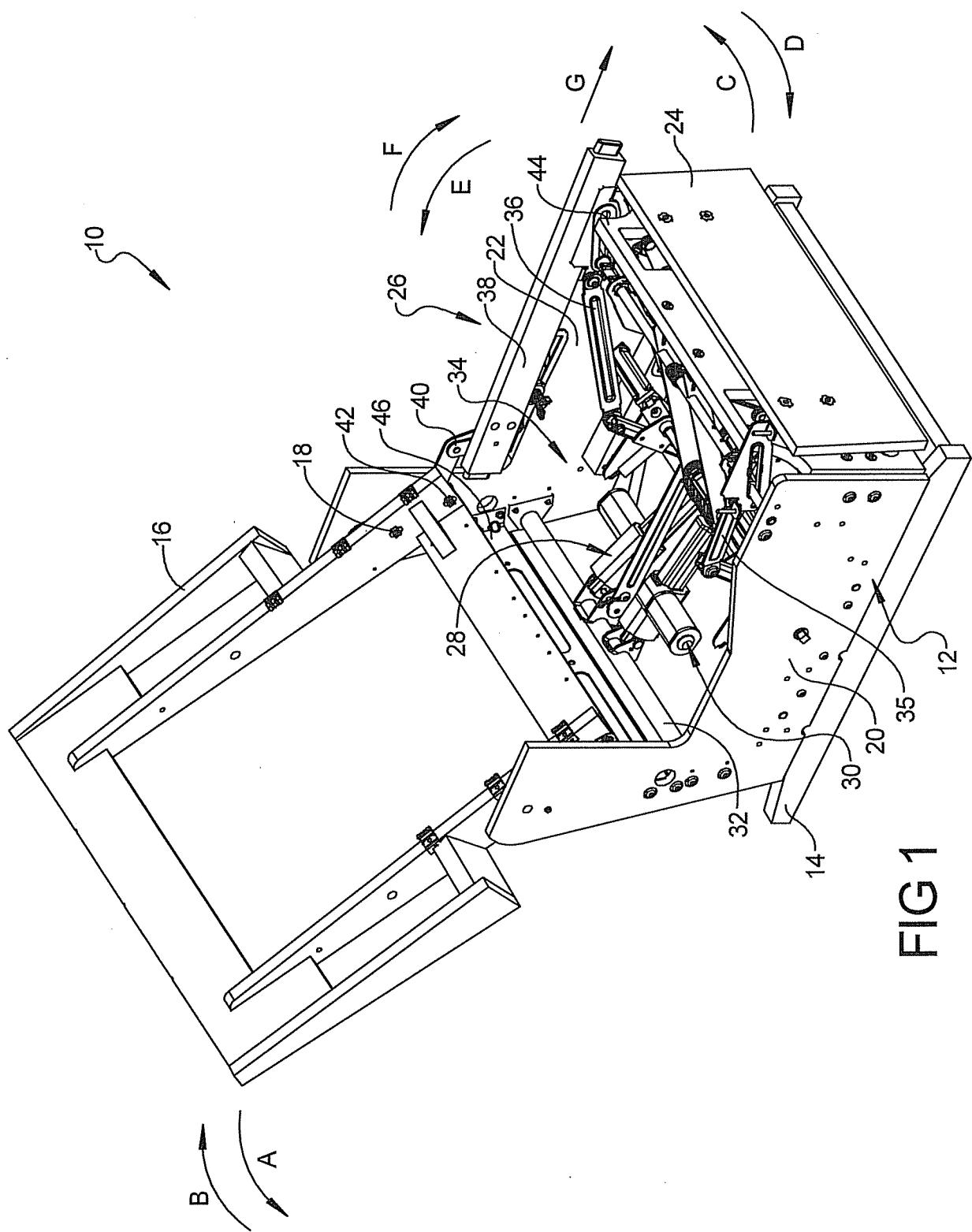
30. The furniture member of Claim 29, further including:
an extension rod freely extending from the drive toggle connector;
and
a rod clearance aperture created proximate the bulbous end of the
5 swing lever, the extension rod slidably extending through the rod clearance
aperture to maintain the first curved end face of the swing lever in alignment with
the second curved end face of the drive toggle connector prior to contact
between the first and second curved end faces, wherein contact between the
first and second curved end faces thereafter precludes the rocking motion of the
10 furniture frame assembly.

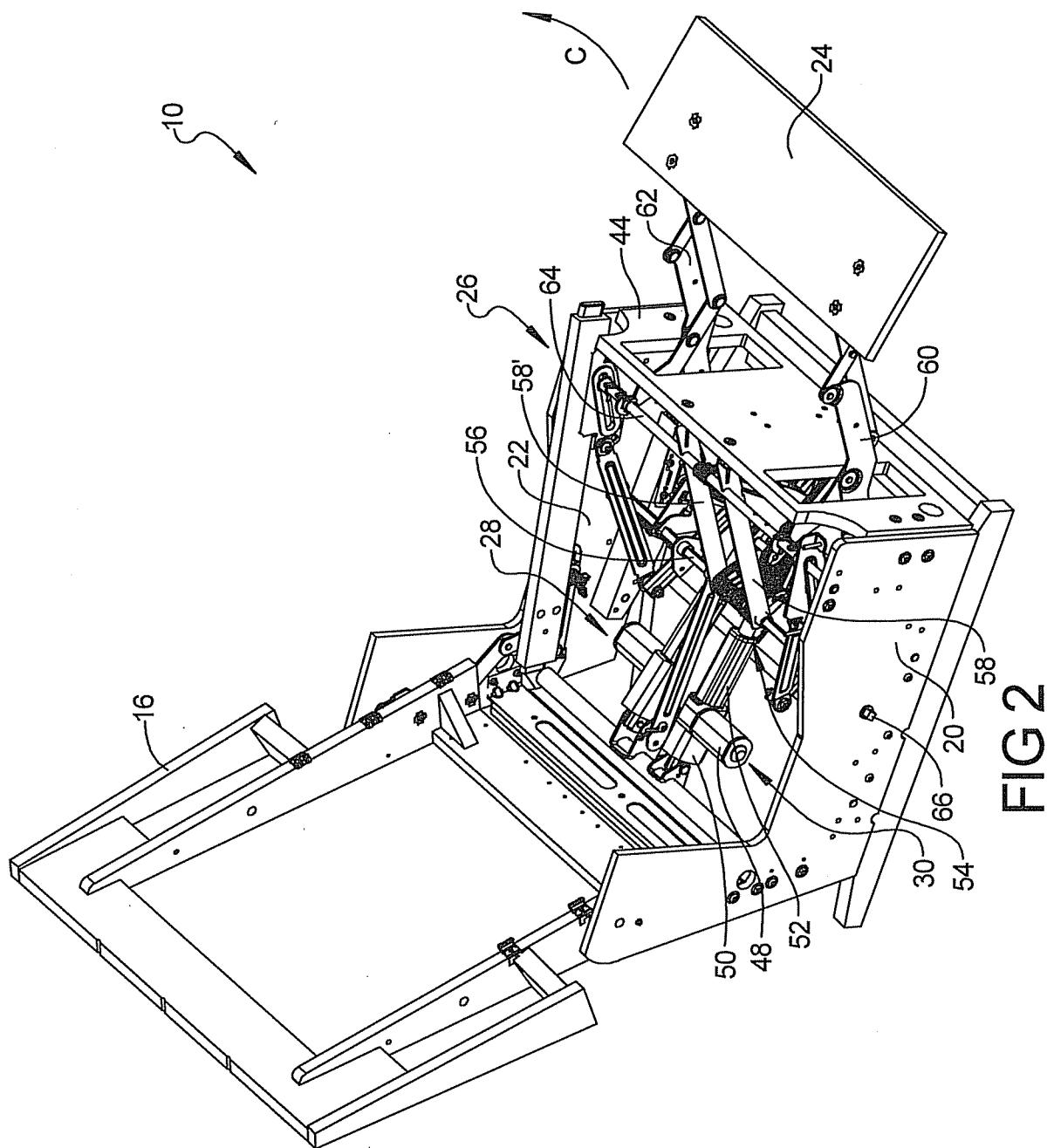
31. The furniture member of Claim 28, further including a tilt swing
lever rotatably connected to each of the swing lever and the base member, an
axis of the tilt swing lever substantially aligned with an axis of the swing lever in
15 the fully rotated position.

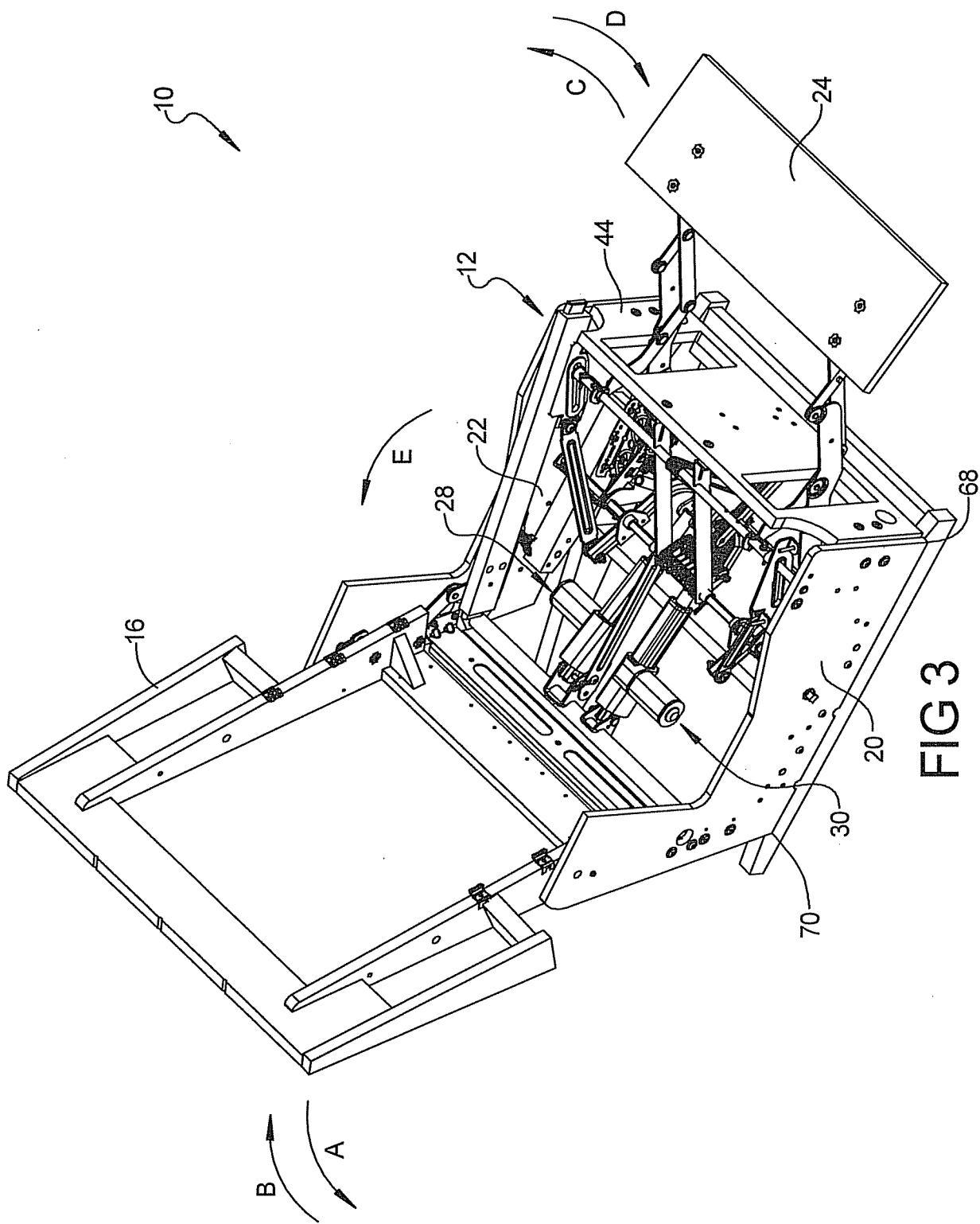
32. The furniture member of Claim 27, further including:
a drive toggle connector connected to the second actuator device;
and
20 a drive toggle connected to and co-rotatable with the drive rod and
rotatably connected to the drive toggle connector, rotation of the drive toggle
connector acting to rotate the drive toggle and thereby to axially rotate the drive
rod.

25 33. The furniture member of Claim 32, further including an actuator
extension shaft extended or retracted by operation of the second actuator
device, the actuator extension shaft rotatably connected to the drive toggle
connector.

34. The furniture member of Claim 27, wherein the mechanism is selectively operated in either a first or a second mode, the first mode having one of the first and second actuator devices energized while the other one of the first 5 and second actuator devices is de-energized, and the second mode having both the first and second actuator devices energized simultaneously.







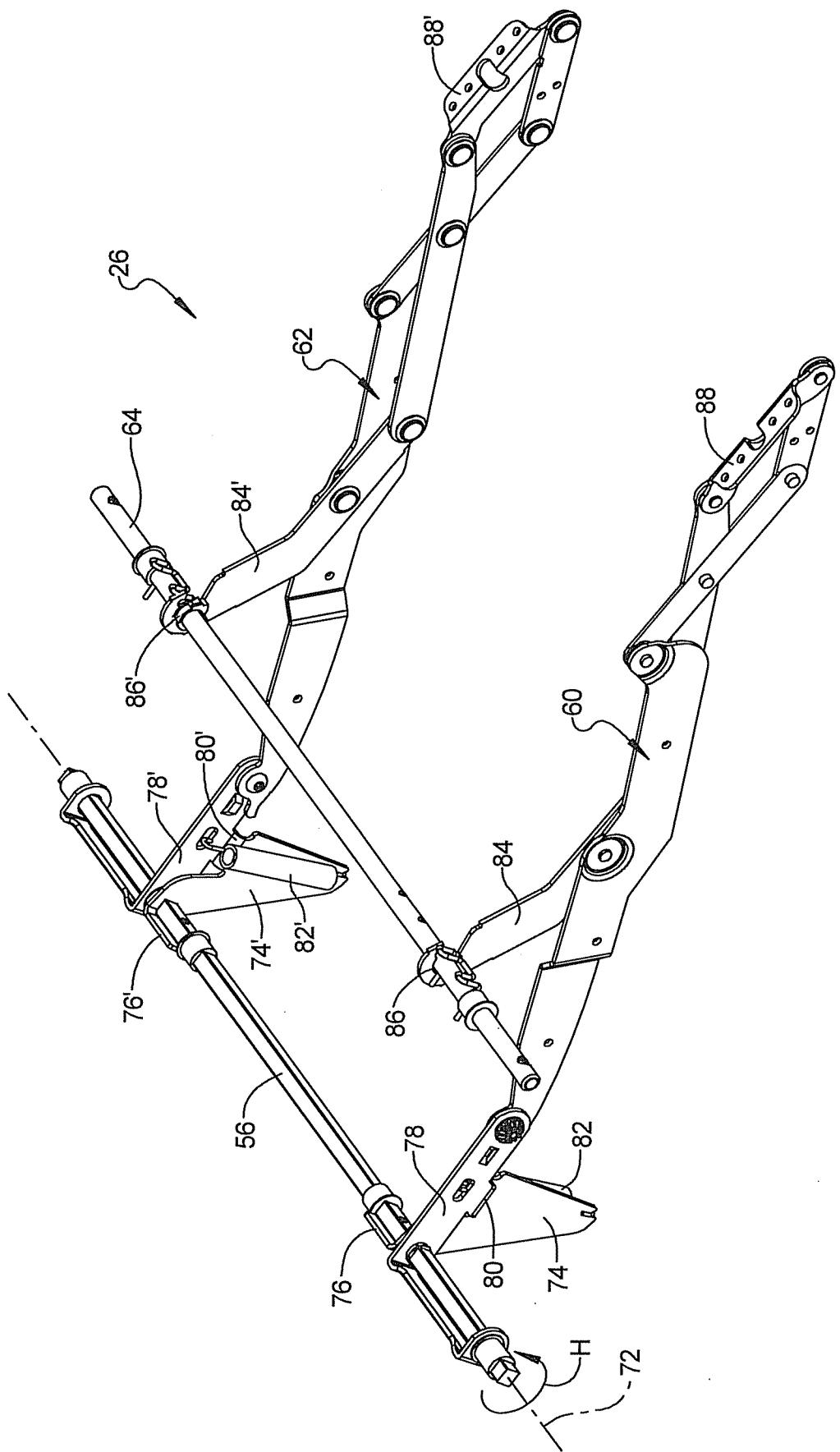


FIG 4

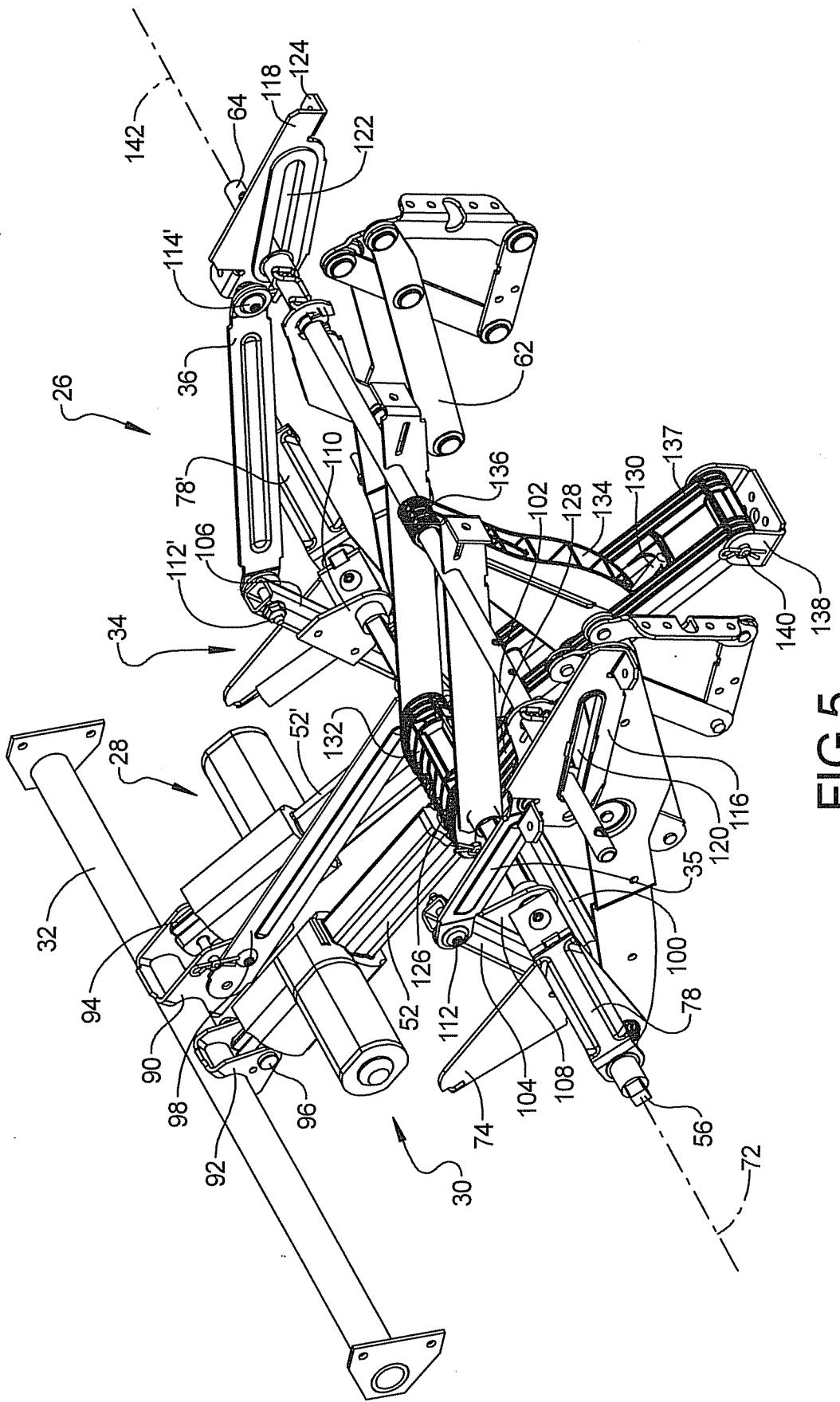
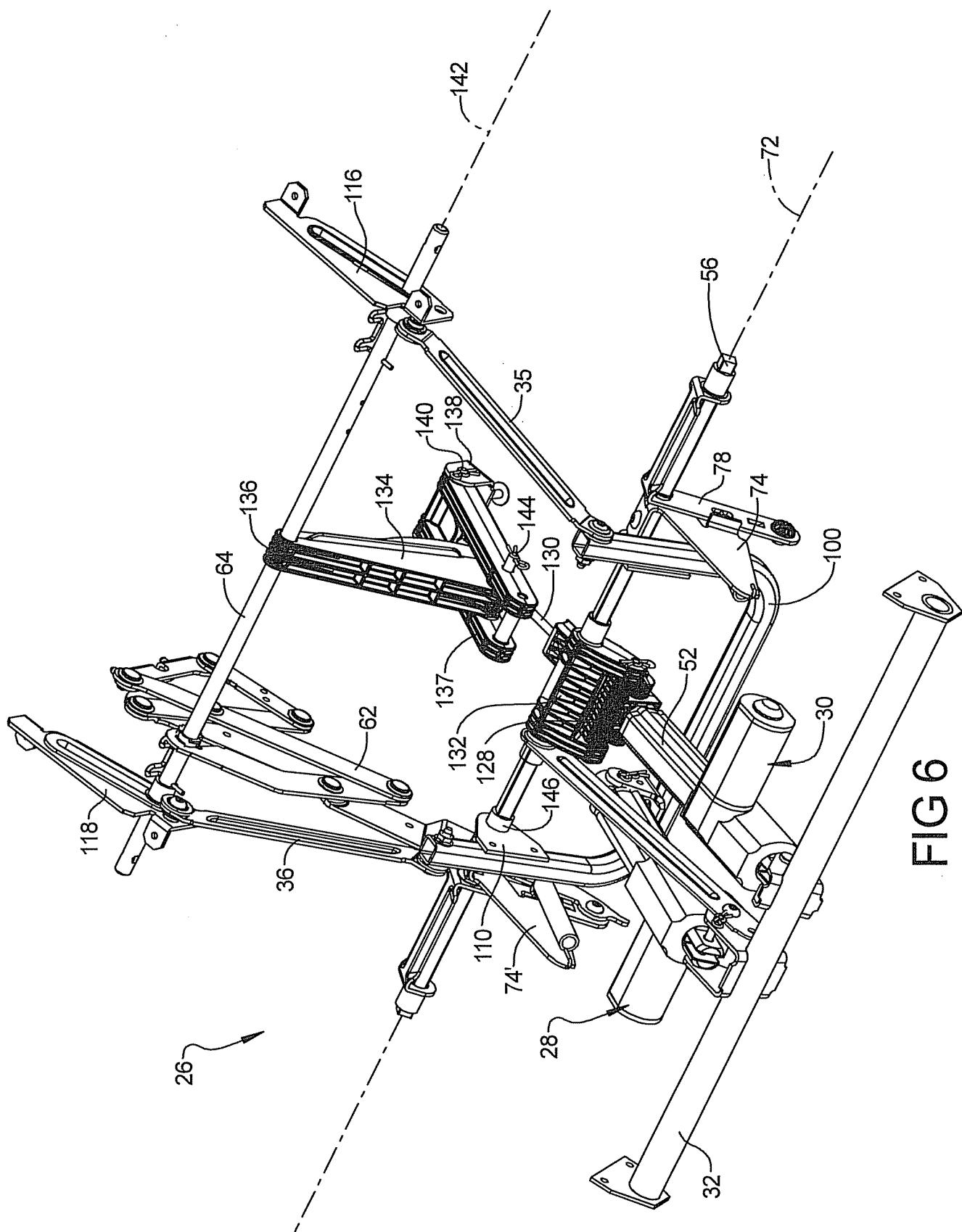
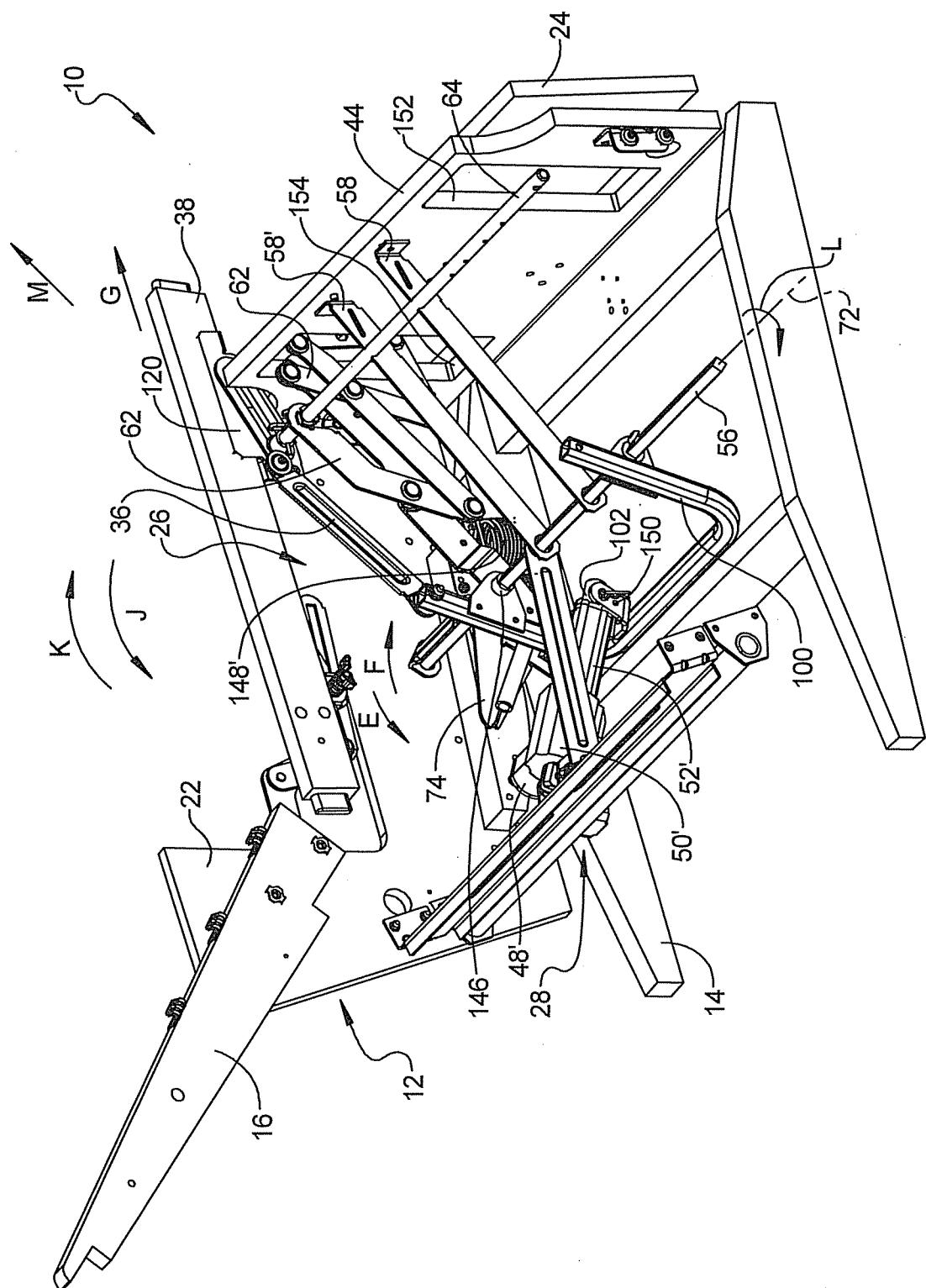


FIG 5





EIGHT

FIG 8

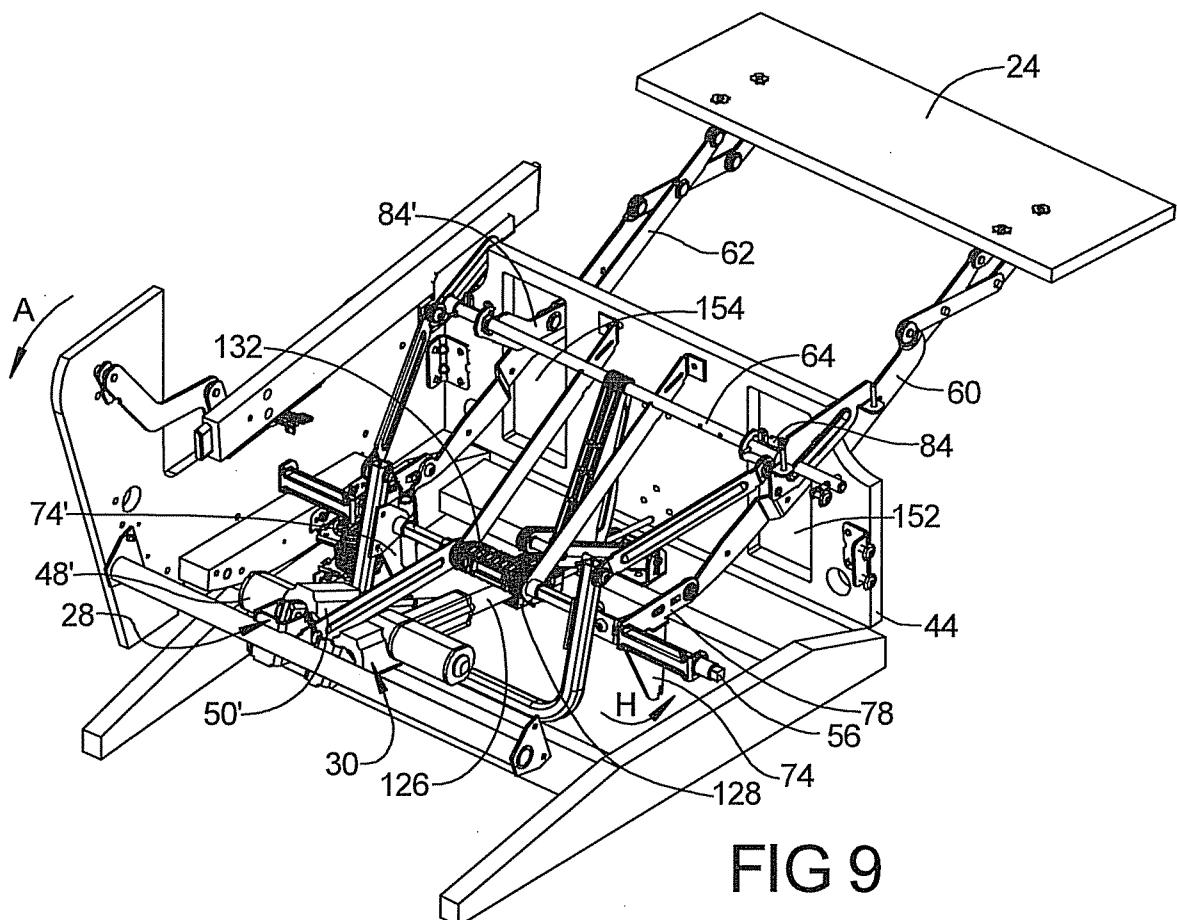
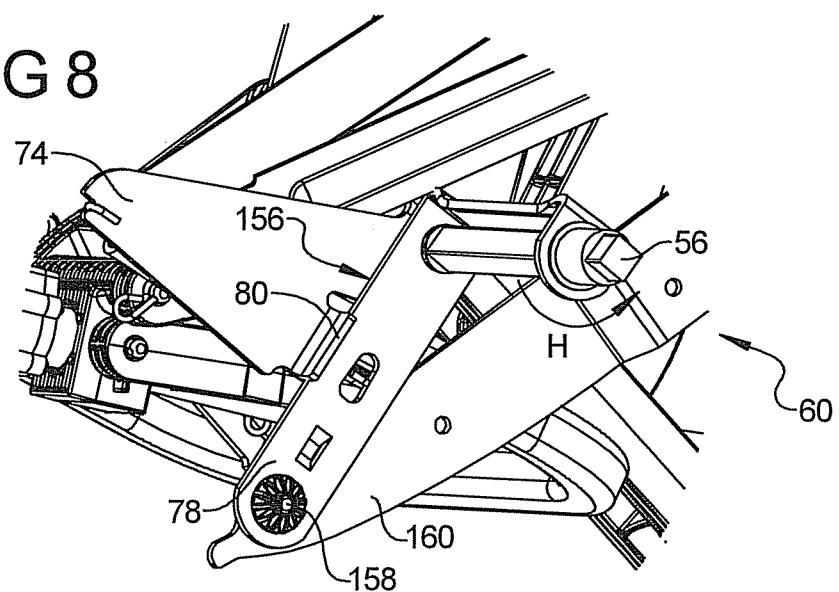


FIG 9

FIG 10

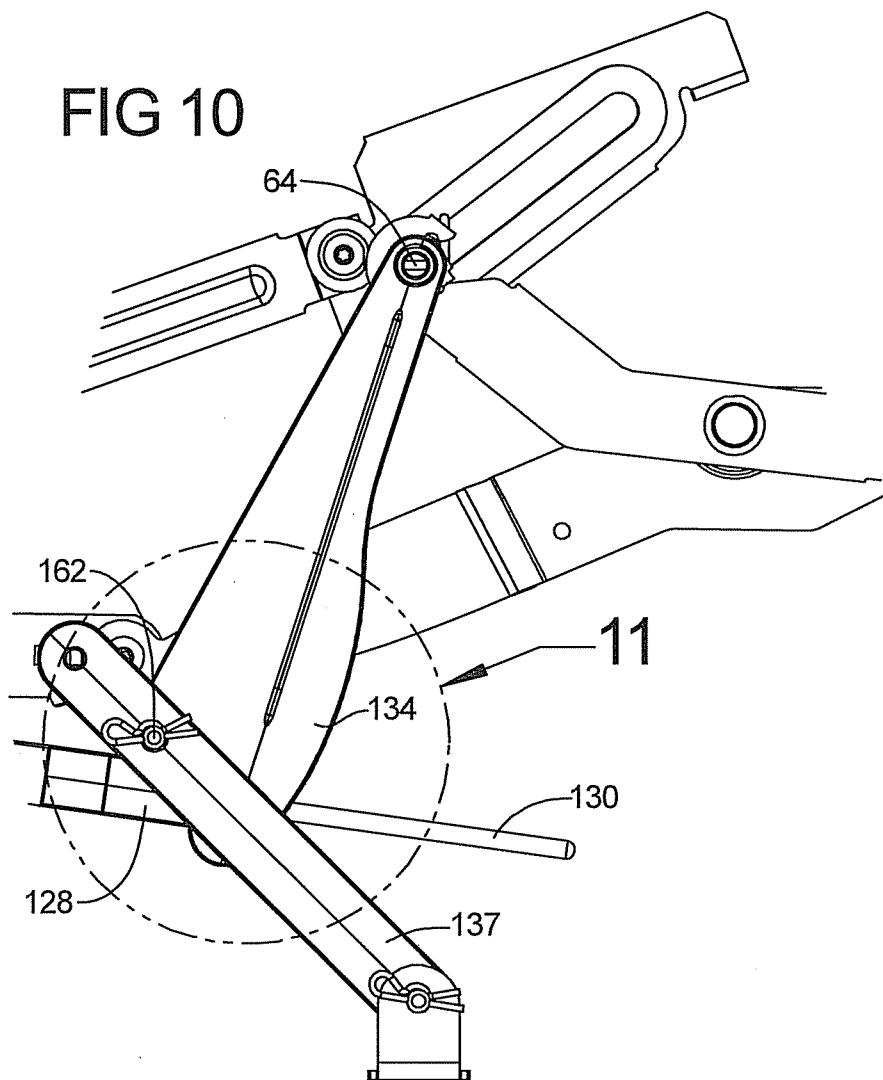
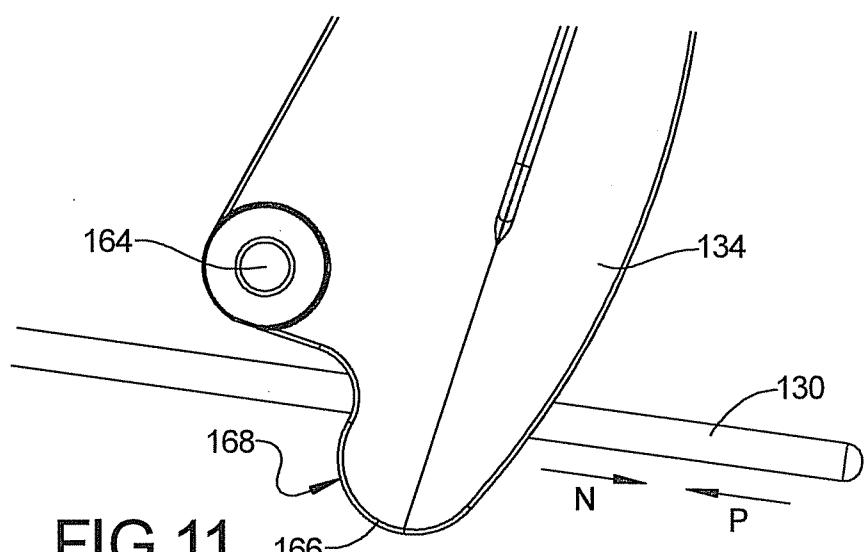


FIG 11



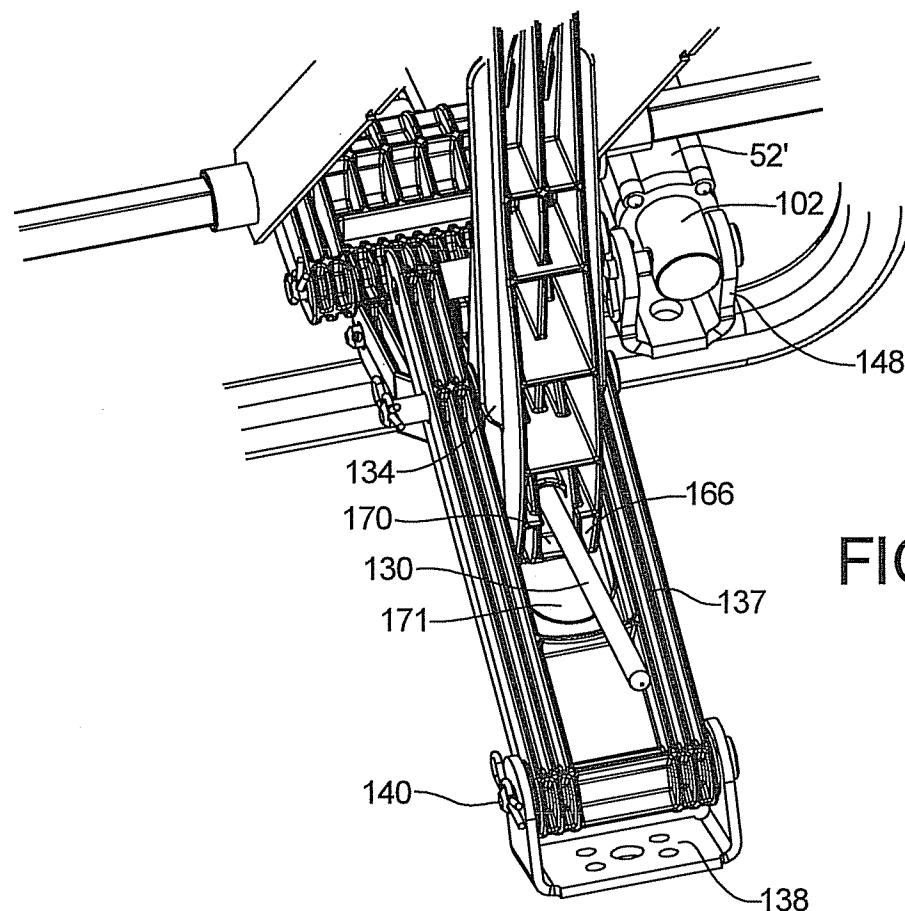


FIG 12

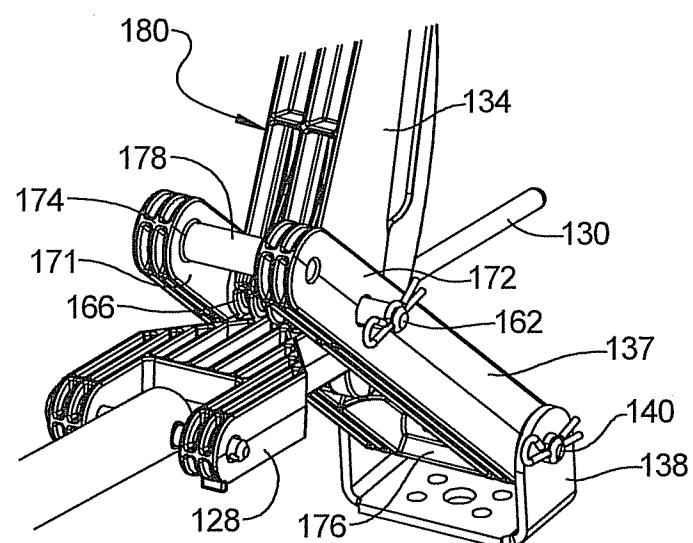


FIG 13

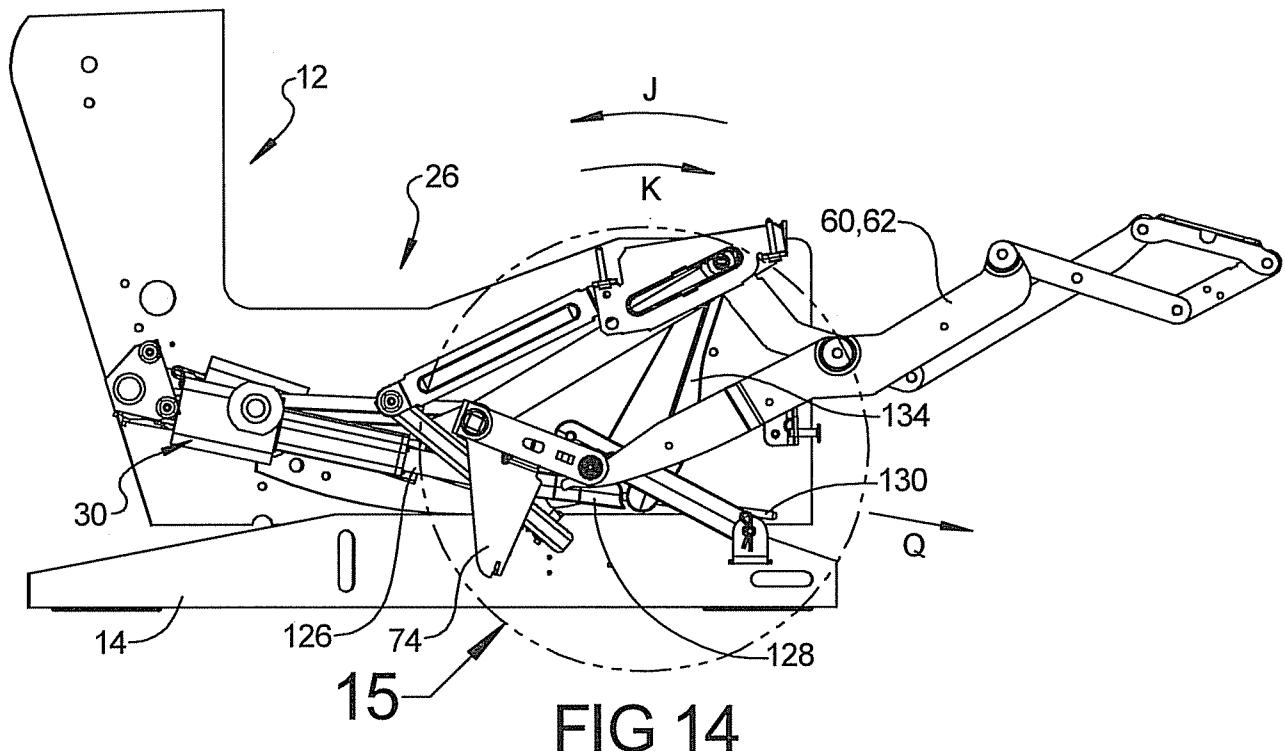


FIG 14

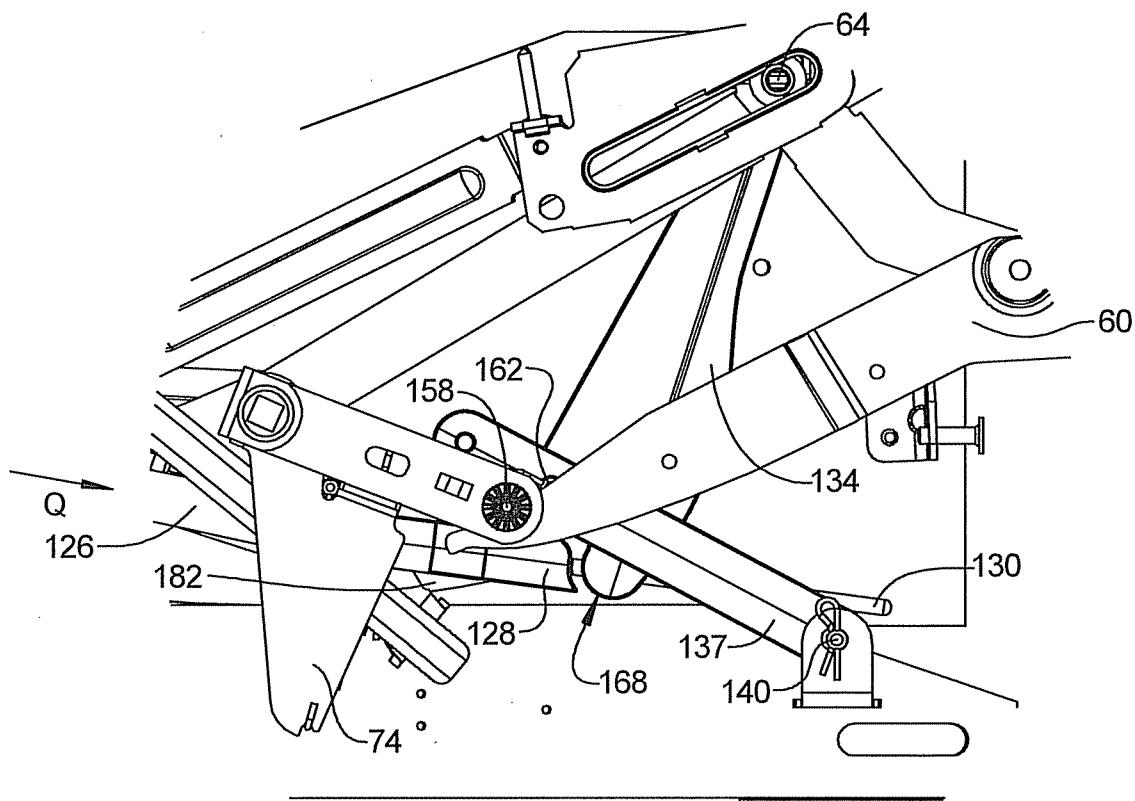
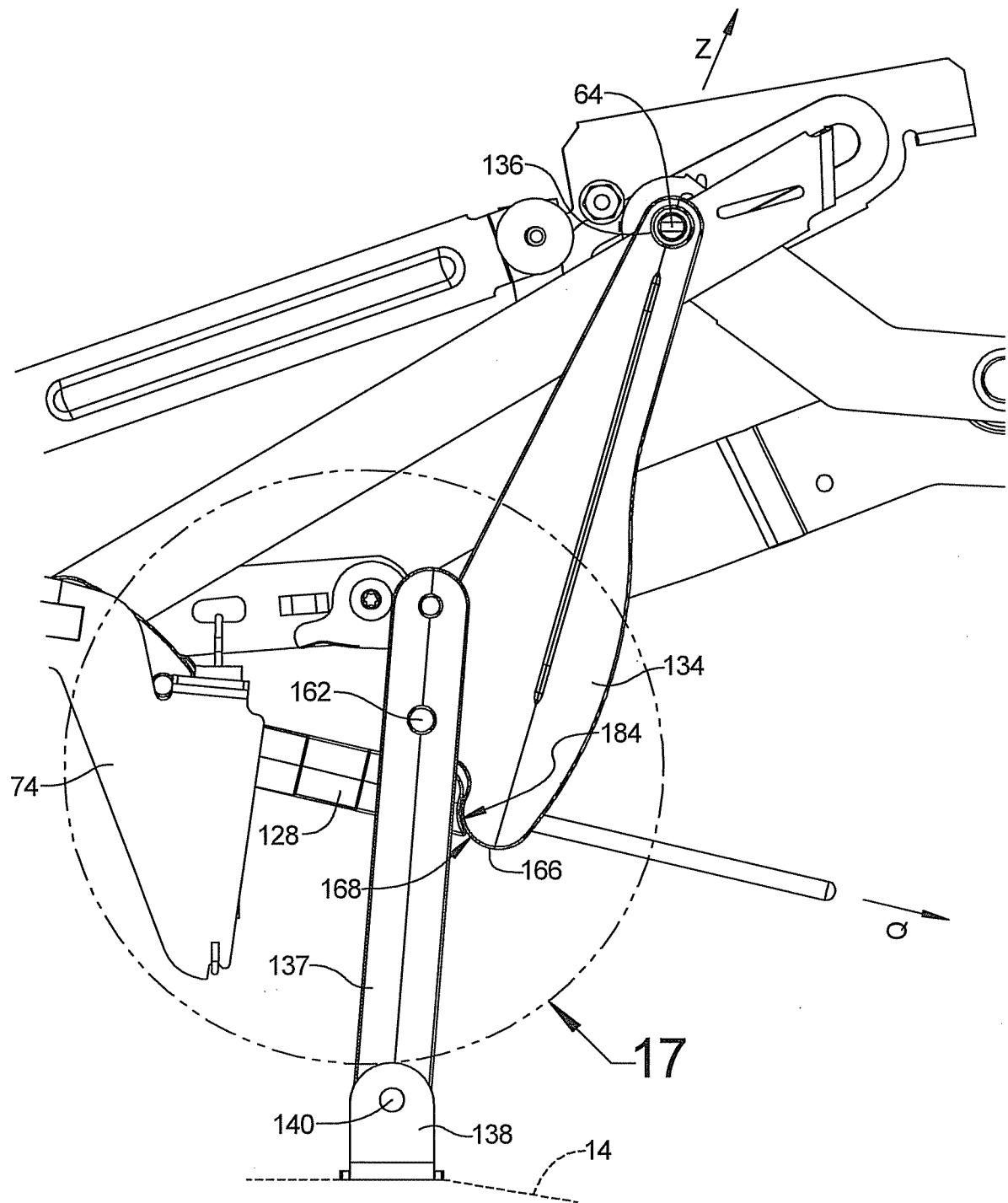


FIG 15



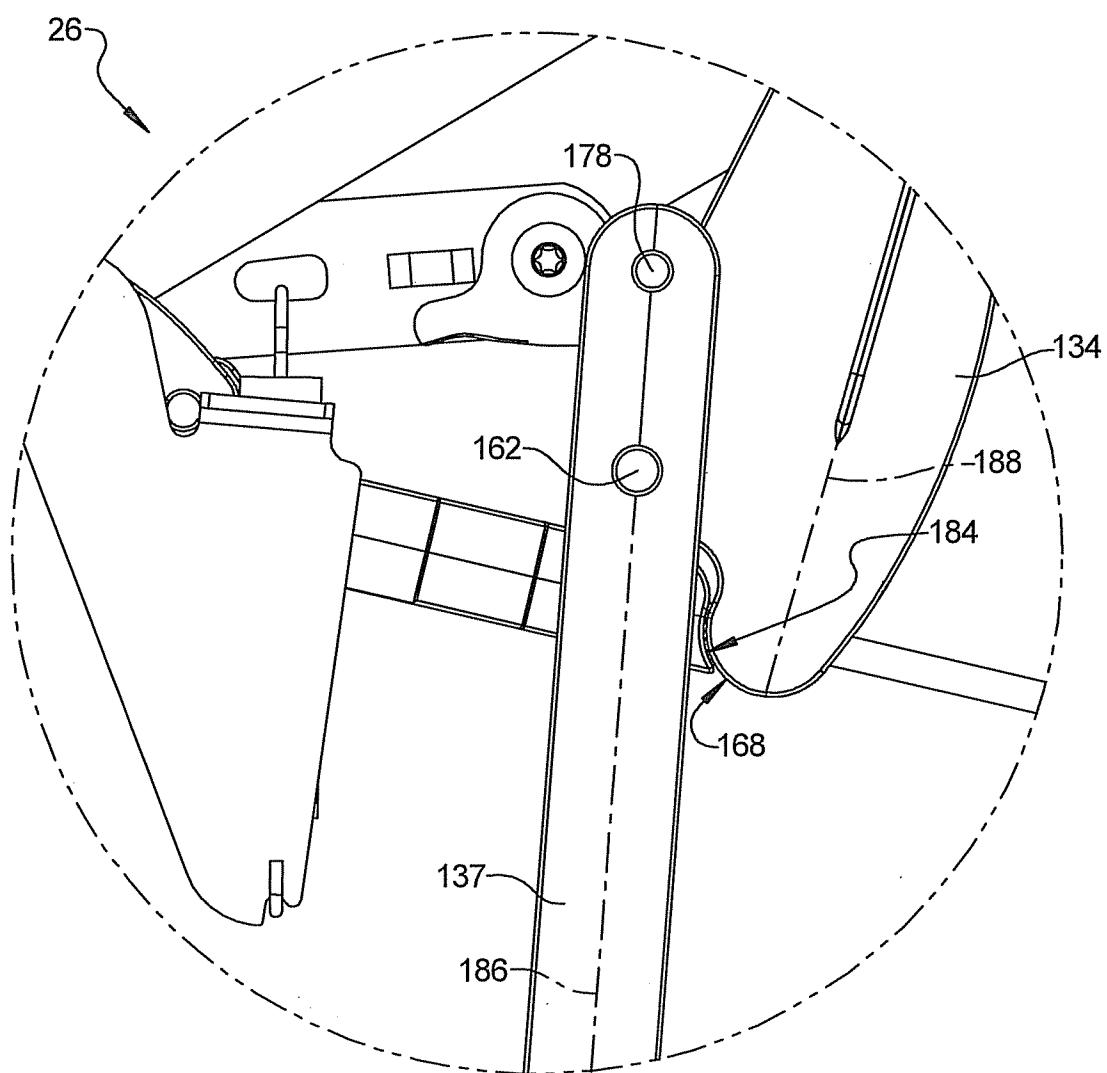
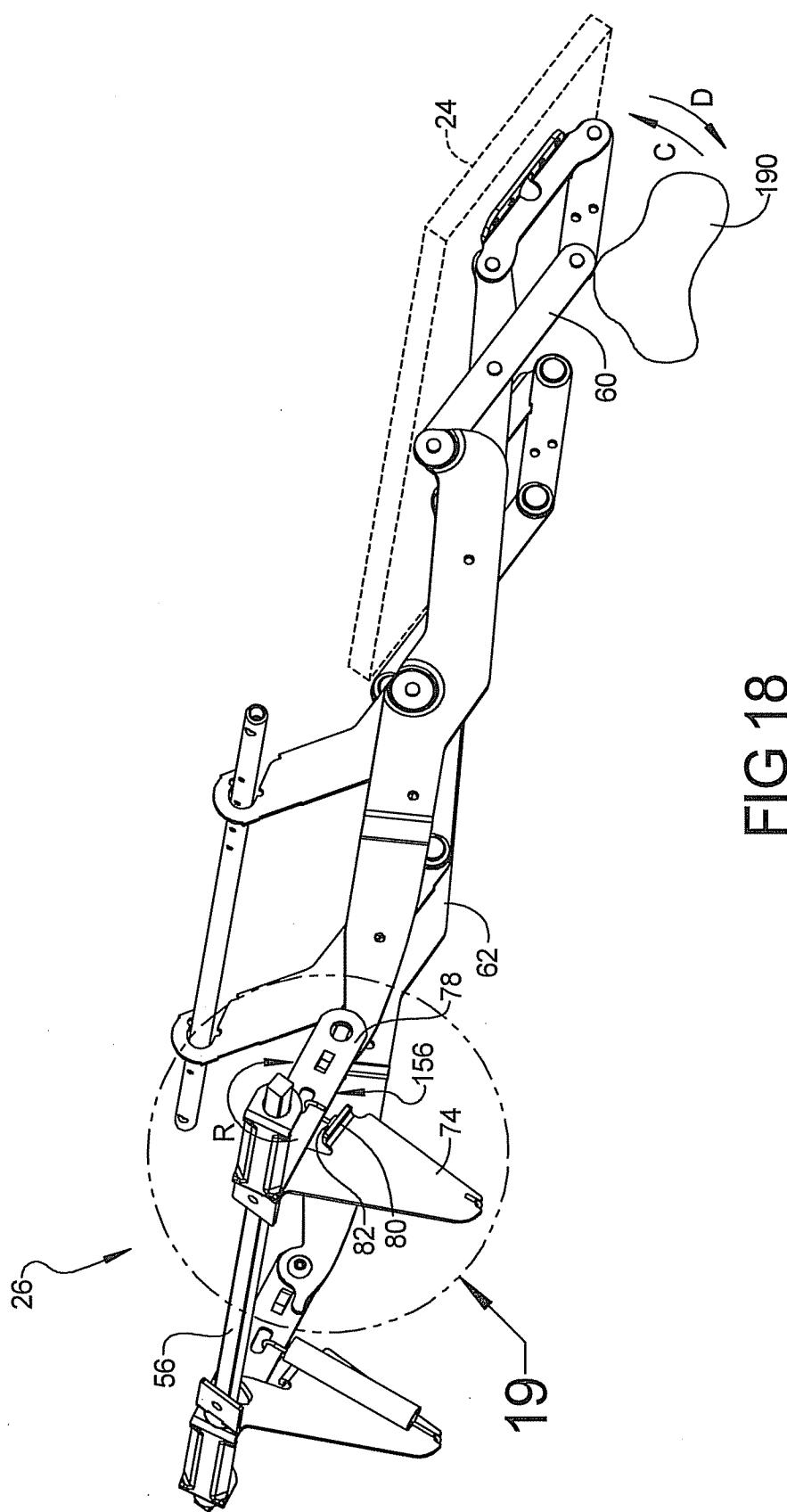


FIG 17



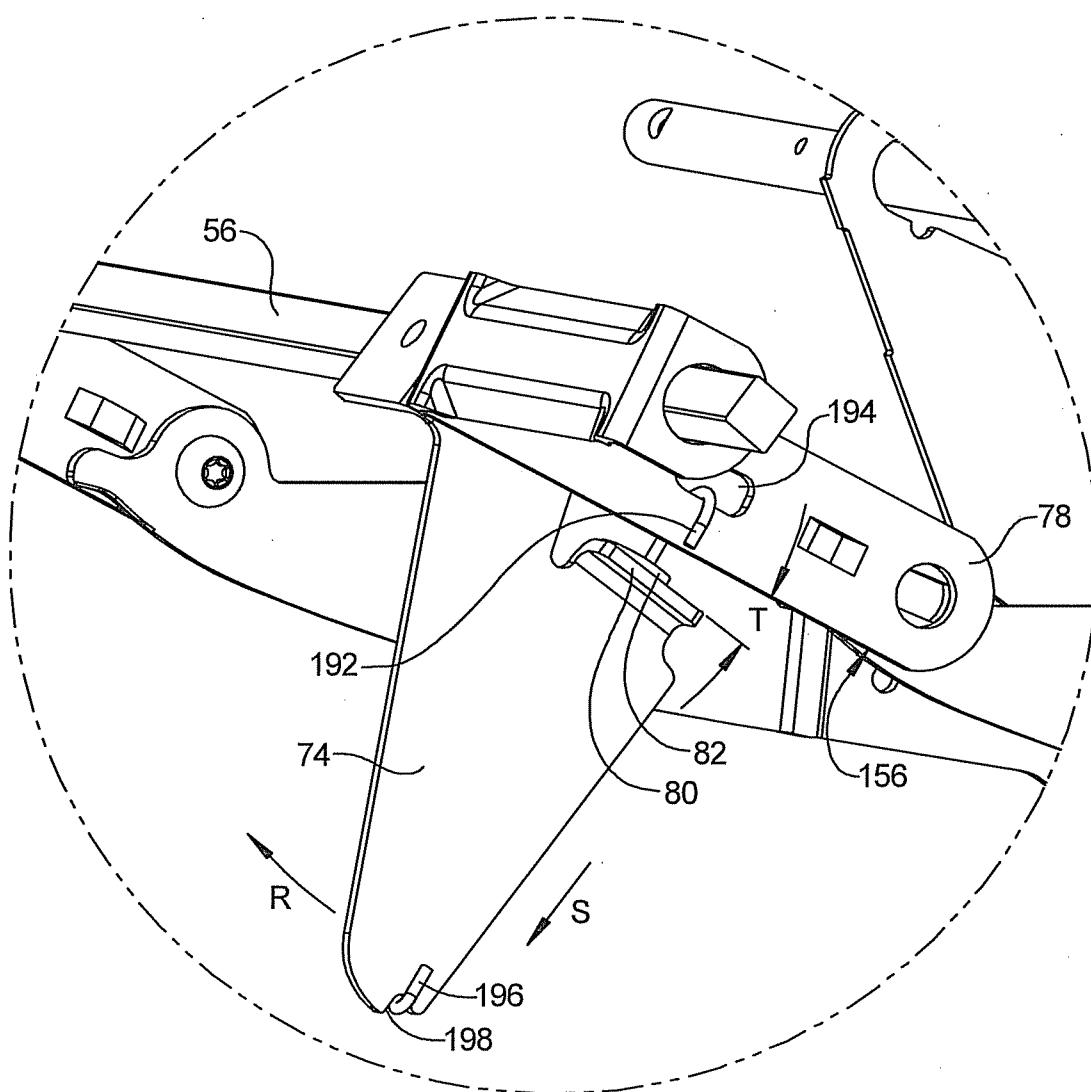


FIG 19

INTERNATIONAL SEARCH REPORT

International application No.
PCT/US2012/052090**A. CLASSIFICATION OF SUBJECT MATTER****A47C 17/04(2006.01)i, A47C 1/032(2006.01)i, A47C 1/034(2006.01)i**

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

A47C 17/04; A47C 20/00; A47C 1/02; A61H 7/00

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Korean utility models and applications for utility models

Japanese utility models and applications for utility models

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

eKOMPASS(KIPO internal) & Keywords: furniture, seat back, leg rest, actuator

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X A	US 6974186 B1 (HORNG JIUN CHANG) 13 December 2005 See column 3 and figures 1-3.	1 2-34
A	US 2005-0035632 A1 (CHUEN-JONG TSENG) 17 February 2005 See claim 1, paragraphs 31-32 and figure 8.	1-34
A	US 7828756 B2 (KAZUSHI KAMBA et al.) 09 November 2010 See claim 1, columns 2-3 and figure 1.	1-34
A	US 05992931 A (LARRY P. LAPOINTE et al.) 30 November 1999 See columns 3-8 and figure 2-4.	1-34

 Further documents are listed in the continuation of Box C. See patent family annex.

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Date of the actual completion of the international search
27 NOVEMBER 2012 (27.11.2012)

Date of mailing of the international search report

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Information on patent family members

International application No.

PCT/US2012/052090

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