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Concrete machine

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(71) Applicant(s)
CMI BELGIUM, naamloze vennootschap

(72) Inventor(s)
Not Given

(74) Agent / Attorney
Davies Collison Cave, Level 10 10 Barrack Street, Sydney, NSW, 2000

Concrete machine.

Concrete machine which is mainly composed of a chassis and of caterpillar drives, upon which the chassis is provided by means of arms, which arms can be adjusted in height, characterized in that the concrete machine (1) is provided with means for adjusting the chassis (4) in height in relation to the arms (3).

Figure 2.

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NAME OF APPLICANT(S)::

CMI BELGIUM, naamloze vennootschap

ADDRESS FOR SERVICE:

DAVIES COLLISON CAVE

Patent Attorneys

Level 10, 10 Barrack Street, Sydney, New South Wales, Australia, 2000

INVENTION TITLE:

Concrete machine

The following statement is a full description of this invention, including the best method of performing it known to me/us:-

Concrete machine.

The present invention concerns a concrete machine, more particularly a concrete machine which is provided with a height adjustment and which preferably
5 can be equipped with different tools for producing ditches, sidewalks, concrete paths or the like.

Such a concrete machine which is mainly composed of a caterpillar drive provided with several supporting
10 arms supporting a chassis is already known.

In this known concrete machine, the caterpillar drive is provided with means, for example a hydraulic piston, which makes it possible to move the above-mentioned supporting arms vertically or almost
15 vertically.

The chassis of the known concrete machine is further provided with means which make it possible to fix an aforesaid tool on a side of the chassis or under the chassis.

20 A disadvantage of this known concrete machine is that, in order to adjust the tool in height, the entire chassis always has to be adjusted together with the

above-mentioned arms.

This is disadvantageous in that the center of gravity of the concrete machine will be situated relatively high, when a tool is used which is relatively high itself or when there is a large difference in level between the working area and the driving area of the caterpillar drives, which results in a reduced stability of the concrete machine, so that, when constructing a road or the like, the finish of the road surface will be poor.

Another disadvantage is that the adjustment in height of the chassis is limited and in that the arms which support the chassis cannot be lowered under the level of the caterpillar drives, as a result of which, in order to work a surface situated under the level of the caterpillar drive, for example when working in ditches, the tool concerned must have a relatively large height, as it must bridge the distance between the chassis and the working area.

This is disadvantageous in that different tools must be provided having the same function but with a different height, so that not only a lot of tools will have to be acquired, but as a result of which, in many cases, the number of tools also forms a major disadvantage for the mobility of the concrete machine between for example different construction sites.

The present invention aims to remedy one or several of the above-mentioned and other disadvantages.

To this end, the invention concerns a concrete machine which is mainly composed of a chassis and of caterpillar drives, upon which the chassis is provided by means of arms, which arms can be adjusted in height, whereby the
5 concrete machine is provided with means for moving the chassis in height in relation to the arms.

Preferably, these above-mentioned means for moving the chassis in height mainly consist of at least one carriage which is provided such that it can shift on at
10 least one guide which is part of the chassis, and upon which one or several of the above-mentioned arms are fixed; and of a drive for moving the carriage.

An advantage of the concrete machine according to the invention is that the chassis can be moved in height in
15 relation to the arms which can be moved in height themselves in relation to the caterpillar drive, such that the concrete machine has more possibilities for adjusting the center of gravity than in the case of the known concrete machines, so that the lowest center of
20 gravity can at all times be set in order to obtain more stability.

An advantage of this double height adjustment is that the chassis can be lowered in between the caterpillar drive, as a result of which a tool can extend relatively
25 far under the caterpillar drive.

In order to better explain the characteristics of a concrete machine according to the invention, the

following preferred embodiment is described as an example only without being limitative in any way, with reference to the accompanying drawings, in which:

- 5 figure 1 schematically represents a concrete machine according to the invention;
figure 2 represents a view according to arrow F2 in figure 1;
figure 3 represents a section to a larger scale of
10 a part which is indicated by arrow F3 in figure 2;
figure 4 represents a view according to arrow F4 in figure 3;
figure 5 schematically represents the concrete machine from figure 1, but in another arrangement;
15 figure 6 schematically represents the concrete machine from figure 2, but in another arrangement.

Figures 1 and 2 schematically represent a concrete machine 1 according to the invention which is mainly composed of one or several caterpillar drives 2, upon
20 which a moving arm 3 is each time provided; and of a chassis 4, whereby means are provided between the chassis 4 and the arms 3 for moving the chassis 4 in height in relation to the above-mentioned arms 3.

The caterpillar drives 2 each contain, as is known, a
25 wheel house 5, upon which a bar 6 is centrally mounted which extends vertically or almost vertically upward.

Each of the above-mentioned arms 3 mainly consists of two parallel beams 7-8 which are equally long and which

are fixed to a mainly tubular part 9 on the one hand, and to a carriage 10 on the other hand, whereby the beams 7-8 are each provided with two passages 11-12, one on each far end, which extend in the vertical height of the beams 7-8.

The tubular part 9 consists of a hollow, cylindrical body and has a protrusion 14 on its outer side which is provided with two parallel ears 15-16 on its far end, in which are each time provided two holes 17-18.

Through each of the holes 17-18 and through the passages 11 in the beams 7-8 concerned, is each time provided a shaft 19, such that the beams 7-8 are fixed in a rotating manner between the ears 15-16.

Each of the above-mentioned tubular parts 9 is, as is known, provided on the bar 6 of the caterpillar drives 2 concerned in a rotating manner, whereby the bar 6 and the tubular part 9 are equipped with known means for moving the tubular part 9 in height in relation to the bar 6, for example in the shape of a cylinder, which means are not represented in the figures, however.

As represented in figure 3, each carriage 10 consists, in this case, of a pair of parallel plates 20-21, through which are each time provided three holes 22-23-24 which, in this case, are situated in a single line.

Through the central holes 23 in each pair of plates 20-

21, is each time fixed a bush with a co-axially provided nut 26.

On either side of the above-mentioned bush 25, the far ends of each of the beams 7-8 of the arm 3 concerned are provided between the pair of plates 20-21 concerned in a rotating manner, whereby the holes 22 and 24, in the plates 20-21, are situated in the prolongation of the passage 12 concerned in the above-mentioned beams 7-8.

According to the above-described embodiment, each pair of ears 15-16 forms a parallelogram, together with the beams 7-8 concerned and the carriage 10 concerned, in which, as is known, is provided a cylinder 27 in the diagonal direction, which cylinder 27 is preferably a hydraulic cylinder.

The chassis 4 mainly consists of two parallel frames 28-29, which are situated at a mutual distance which is substantially larger than the height of the beams 7-8 of the arms 3.

Both frames 28-29 are, in this case, made pentagonal with five sides, 30 to 34 respectively.

On the top frame 28 of the chassis 4 is provided a cockpit 35, whereas, in this case, in the sides 30, 31, 33 of both frames 28-29 are each time provided three holes 36-37-38, whereby the mutual distances between these holes 36-37-38 are equal to the mutual distances between the holes 22-23-24 in the plates 20-21 of the carriage

10.

The chassis 4 is further provided with guides 39-40 in the shape of bars, which are provided through each of the holes 36 and 38 in the frames 28-29, whereby the carriage
5 10 is mounted on these guides 39-40 by means of slide bearings 41 which are fixed in the passages 12 of the beams 7-8, such that said carriage can shift.

As represented in figures 3 and 4, a freely rotating gear wheel 42-43 is provided on a free end of and co-
10 axial with each of the above-mentioned guides 39-40.

Through each of the central holes 37 in the frames 28-29 and through the bush 25 concerned is provided a rotating threaded rod 44 which is equipped with a gear wheel 45, which gear wheel 45 is fixed in the
15 prolongation of said threaded rod 44.

An endless chain 46 which is equipped with a drive, not represented in the figures, is guided over the gear wheels 42-43-45 in a zigzag pattern.

The chain drive will preferably be common to all
20 threaded rods 44, whereby, in that case, the sole chain 46 is guided round the cockpit 35 over the gear wheels 42-43-45 of all guides and all the above-mentioned threaded rods 45.

For the use of the above-described concrete
25 machine 1, a tool holder 47 is fixed next to and/or

under the lower frame 29 of the chassis 4, which tool holder mainly consists of a frame 48 upon which are fixed different cylinders 49.

- 5 The bars 50 of the above-mentioned cylinders 49 carry supports 51 onto which can be fixed a tool 52, such as for example a gauge or a vibrating device.

10 In the case of figures 1, 2 and 5, a tool 52 is represented which is equipped with a device 53 for supplying concrete 54 or the like, which device 53 in this case consists of a supply 55 in which is provided an Archimedean screw 56, which supply 55 discharges into a conical funnel 57 which is provided in or in front of the tool 53.

- 15 The concrete machine 1 is provided in the known manner with a motor, not represented in the figures, for exciting a hydraulic circuit with a pump and control means for the drive of, respectively, the hydraulic motors of the caterpillar drives 2; the
20 cylinders 27 of the arms 3; the chain drive of the means for moving the chassis 4 in relation to the arms 3; the cylinders 49 of the tool holder 47; and the drive of the tools 53.

25 The working of the concrete machine 1 is simple and as follows.

Figure 2 represents the concrete machine 1 whereby the arms 3 are positioned more or less centrally in relation

to the bars 6 of the caterpillar drives 2.

In this arrangement, the carriages 10 are situated almost entirely at the bottom of the guides 39-40 of the chassis 4, such that the chassis is situated in a relatively high position in relation to the roadway of the caterpillar drives 2, and as a result of which the bars 50 of the cylinders 49 on the above-mentioned tool holder 47 extend relatively far out of the above-mentioned cylinders 50.

10 In the above-described arrangement, the center of gravity of the concrete machine 1 is situated relatively high above the roadway of the caterpillar drives 2, as a result of which the stability of the concrete machine 1 is rather low.

15 Figure 6, however, represents the same concrete machine 1 with an identical position of the arms 3 in relation to the caterpillar drives 2, but whereby the carriages 10 are situated practically entirely on top of the guides 39-40, such that the chassis 4 is situated in a relatively low position, as a result of which a better stability is
20 obtained in relation to the arrangement represented in figure 2.

The above-mentioned bars 50 are now situated relatively deep in the cylinders 49, in order to compensate for the difference in height between the working surface and the
25 level of the chassis 4.

The position of the chassis 4 is adjusted by driving the chain 46 which, in her movement, makes the gear wheels 45 of the threaded rods 44 rotate, as a result of which, thanks to the co-operation between the nuts 26 and
5 the threaded rods 44 concerned, the carriage 10 concerned is moved in relation to the guides 39-40.

By connecting all threaded rods 44 to one and the same chain 46, the same movement of the chassis 4 in relation to each of the arms 3 is always obtained, such that the
10 chassis 4 always moves horizontally.

A third height adjustment of the tool can be obtained by controlling the cylinders 49 which are fixed on the tool holder 47.

It should be noted that adjusting the tool 53 in
15 height in relation to the chassis 4 must not necessarily be done with cylinders 49, for also threaded rods and guides can be used to this end which are driven by a chain, similar to the above-described height adjustment for adjusting the chassis 4 in relation
20 to the arms 3.

These three above-mentioned height adjustments make it possible to always place the chassis 4 at a minimal height in relation to the basic plane, such that the center of gravity of the concrete machine 1 can
25 remain relatively low and the stability of the concrete machine 1 is relatively high, such that a good finish of the concrete product to be processed can at

all times be obtained.

It should be noted that several series of holes 36-37-38 can be provided in the frames 28-29 of the chassis 4, such that the guides 39-40 and threaded rods 44 can be fixed
5 in different positions in the chassis 4, such that also the arms 3 can be coupled to the chassis 4 in different positions, which makes it possible to always optimize the position of the caterpillar drives 2 as a function of the work to be carried out.

10 An additional advantage of these different series of holes 36-37-38 is that it also possible to provide one or several extra caterpillar drives 2. Thus, it is possible for example to provide four caterpillar drives 2, as opposed to the embodiments represented in the figures,
15 where only three caterpillar drives 2 are represented.

Providing a fourth caterpillar drive 2 offers the possibility, among others, to fix wide tools under the concrete machine 1, for example for concreting a lane that is 2.5 m wide.

20 As the concrete machine 1 is further preferably made symmetrical, it is possible to simultaneously carry out one and the same operation on both sides of the concrete machine 1, by fixing two similar tools 53 on both sides of the chassis 4.

25 Further, it should be noted that the chain must not necessarily drive all supporting bars 44, for this can

also be done by several chains 46, which all drive one or several threaded rods 44, and which are in turn driven by one or several chain drives, not represented in the figures.

- 5 Of course, it is also possible to provide other means between the arms 3 and the chassis 4 to move the chassis 4 up and down, such as for example hydraulic cylinders.

Finally, figure 6 represents the different height adjustments that are possible in a concrete machine 1
10 according to the invention, indicated by the double arrows A, B and C, whereby the height adjustment indicated by arrow A amounts to 60 cm, for example, whereas the maximum range of the height adjustments indicated by the arrows B and C amounts to 40 cm, for
15 example, such that the total height adjustment for the concrete machine 1 in this case amounts to 140 cm.

The present invention is by no means limited to the embodiment given as an example; on the contrary, such a concrete machine according to the invention can be made
20 according to different variants while still remaining within the scope of the invention.

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Throughout this specification and the claims which follow, unless the context requires otherwise, the word "comprise", and variations such as "comprises" or "comprising", will be understood to imply the inclusion of a stated integer or step or group of integers or steps but not the exclusion of any other integer or step or group of integers or steps.

5

The reference to any prior art in this specification is not, and should not be taken as, an acknowledgement or any form of suggestion that that prior art forms part of the common general knowledge in Australia.

- 10 The reference numerals in the following claims do not in any way limit the scope of the respective claims.

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The claims defining the present invention are as follows:

1.- Concrete machine which is mainly composed of a chassis and of caterpillar drives, upon which the chassis is provided by means of arms, which arms can be adjusted
5 in height, characterized in that the concrete machine (1) is provided with means for adjusting the chassis (4) in height in relation to the arms (3).

2.- Concrete machine according to claim 1, characterized in that the above-mentioned means for
10 moving the chassis (4) in height mainly consist of at least one carriage (10) which is provided such that it can shift on at least one guide (39-40) which is part of the chassis (4), and upon which one or several of the above-mentioned arms (3) are fixed; and of a drive for moving
15 the carriage (10).

3.- Concrete machine according to claim 2, characterized in that the above-mentioned drive consists of one or several chain drives with at least one chain (46) which is guided around a gear wheel (45) of at least
20 one threaded rod, which threaded rod (44) is provided through a nut (26) which is part of the above-mentioned carriage (10).

4.- Concrete machine according to claim 3, characterized in that each guide (39-40) is provided

with a freely rotating gear wheel (42-43), whereby the above-mentioned chain (46) is guided in a zigzag pattern over the gear wheels (42-43-45) of the guides (39-40) and the threaded rods (44).

5 5.- Concrete machine according to any one of claims 2 to 4, characterized in that each arm (3) is connected to any one of the above-mentioned carriages (10).

6.- Concrete machine according to any one of claims 3 to 5, characterized in that the chain drive consists of one
10 common chain (46) which is guided around the gear wheels (45) of the different threaded rods (44).

7.- Concrete machine according to any one of claims 2 to 6, characterized in that the guides (39-40) are provided through holes (36-38) which are provided in the
15 chassis (4), whereby different holes (36-38) are provided in the chassis (4) for every guide (39-40), such that the guides (39-40) can be moved.

8.- Concrete machine according to claim 7, characterized in that the threaded rods (44) are
20 provided through holes (37) in the chassis (4) whereby, for every threaded rod (44), different holes (37) are provided corresponding to the different holes (36-38) for the above-mentioned guides (39-40).

9.- Concrete machine according to any one of the
25 preceding claims, characterized in that the arms (3) are mainly formed of two parallel beams (7-8) having an

equal length, which are hinge-mounted with their far ends on the above-mentioned carriage (10) on the one hand, and on the caterpillar drives (2) on the other hand.

10.- Concrete machine according to claim 9,
5 characterized in that the arms (3) each have a cylinder (27) which extends between the carriage (10) and the caterpillar drives (2).

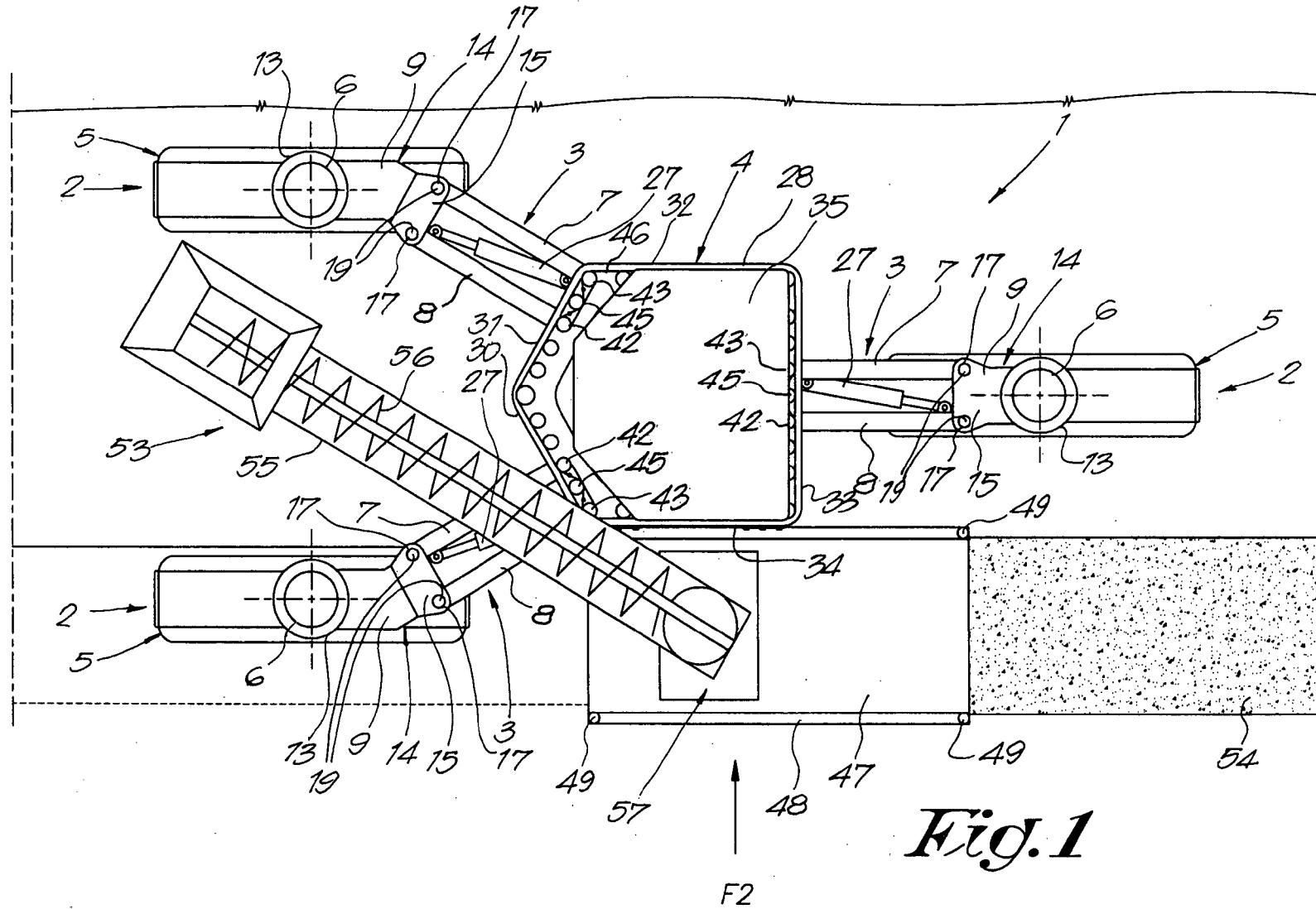
11. A concrete machine, substantially as herein described with reference to the accompanying drawings.

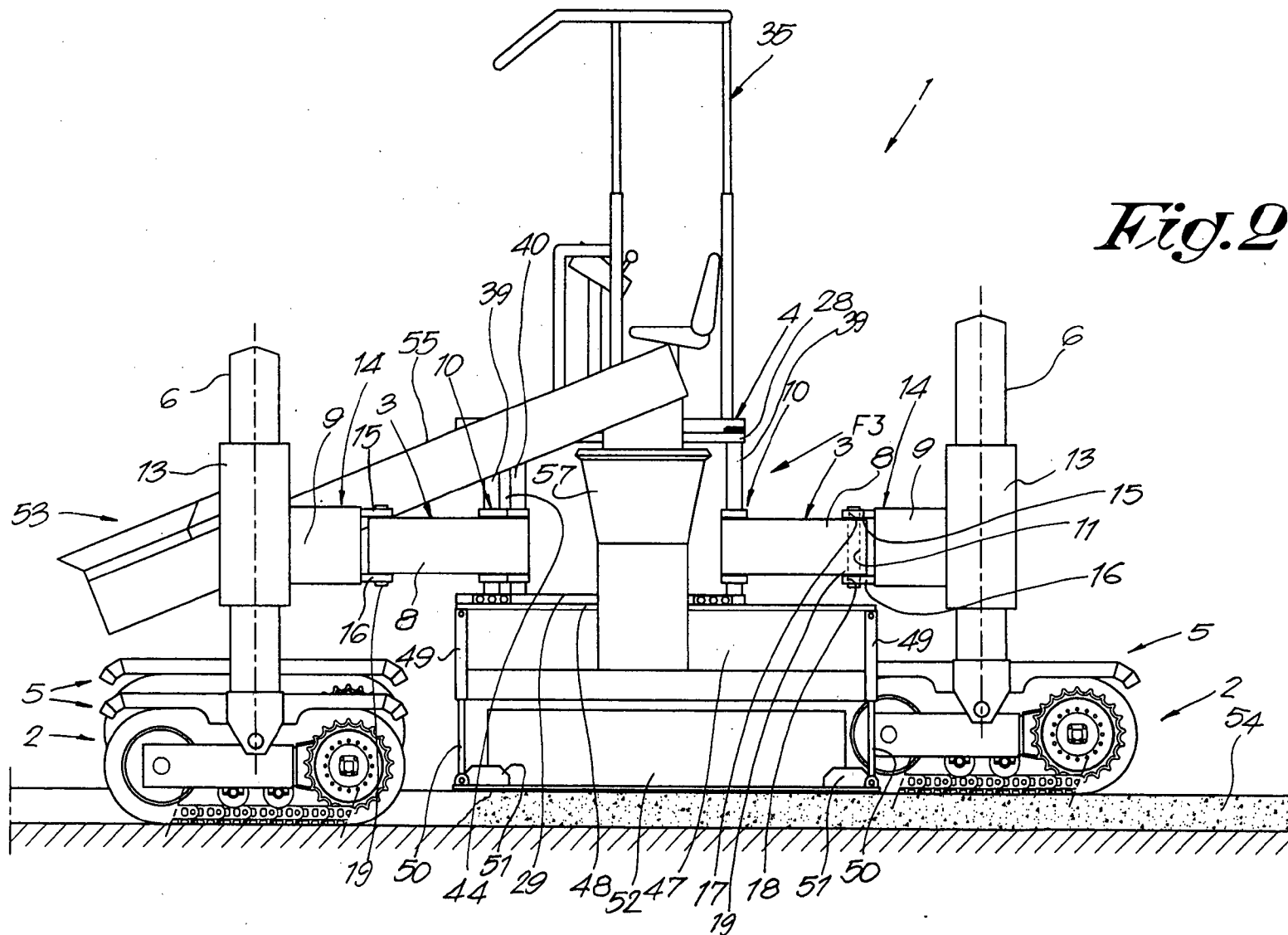
DATED this 24th day of November, 2004

CMI BELGIUM, NAAMLOZE VENNOOTSCHAP

By Their Patent Attorneys

DAVIES COLLISON CAVE





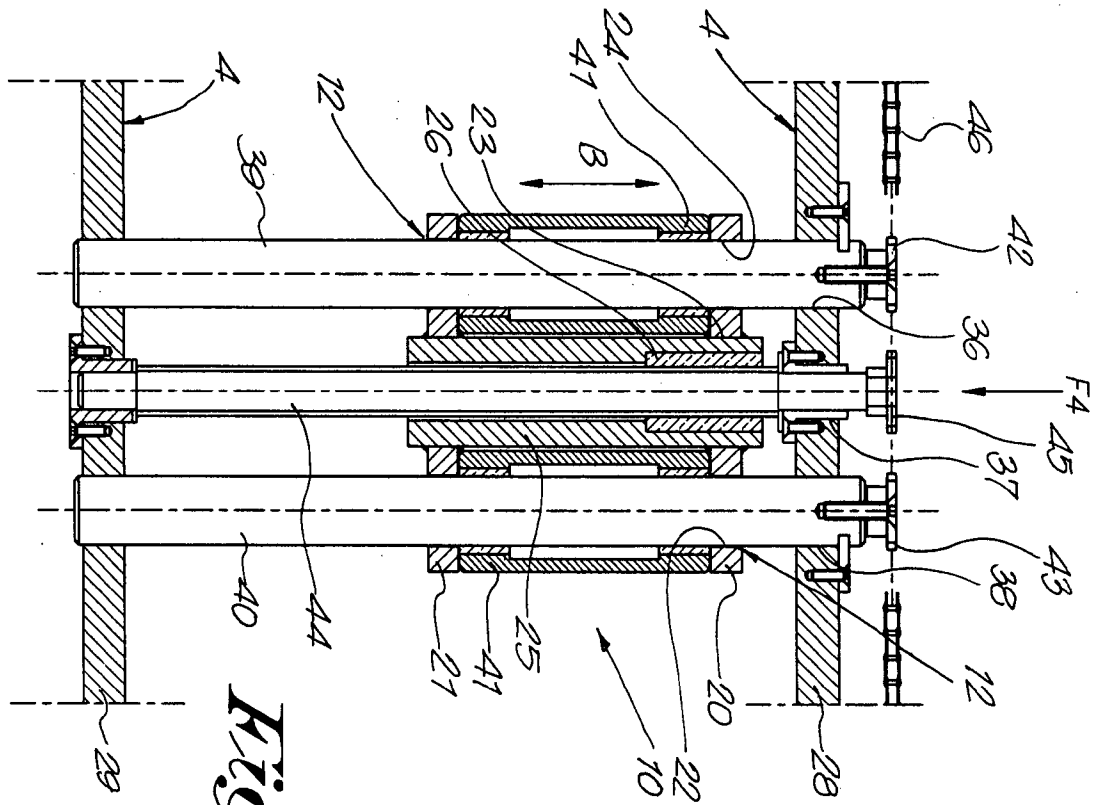


Fig. 3

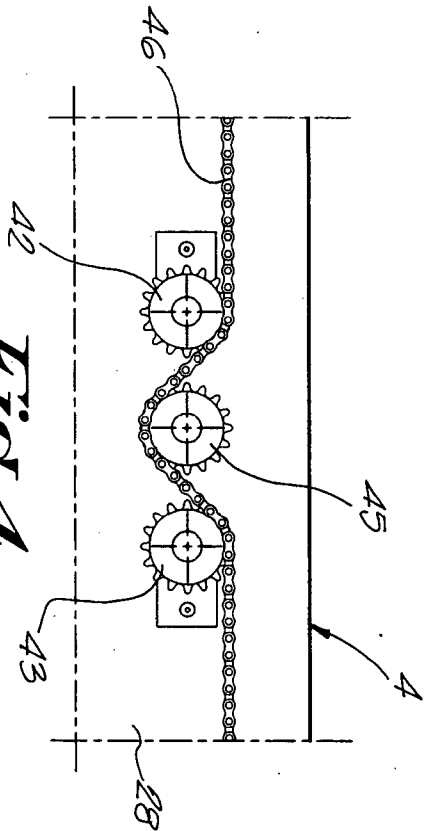


Fig. 4

