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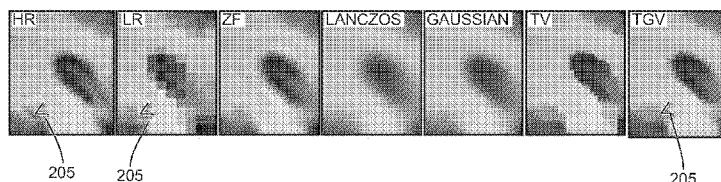
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(54) Title: SYSTEM, METHOD AND COMPUTER ACCESSIBLE MEDIUM FOR NOISE ESTIMATION, NOISE REMOVAL AND GIBBS RINGING REMOVAL

**FIG. 2**

(57) Abstract: An exemplary system, method and computer-accessible medium for removing noise and Gibbs ringing from a magnetic resonance ("MR") image(s), can be provided, which can include, for example, receiving information related to the MR image(s), receiving information related to the MR image(s), and removing the Gibbs ringing from the information by extrapolating data in a k-space from the MR image(s) beyond an edge(s) of a measured portion of the k-space. The data can be extrapolated by formatting the data as a regularized minimization problem(s). A first weighted term of the regularized minimization problem(s) can preserve a fidelity of the extrapolated data, and a second weighted term of the regularized minimization problem(s) can be a penalty term that can be based a norm(s) of the MR image(s), which can be presumed to be sparse

SYSTEM, METHOD AND COMPUTER ACCESSIBLE MEDIUM FOR NOISE ESTIMATION, NOISE REMOVAL AND GIBBS RINGING REMOVAL

CROSS-REFERENCE TO RELATED APPLICATION(S)

5 [0001] This application relates to and claims priority from U.S. Patent Application Nos. 62/162,164, filed on May 15, 2015, and 62/317,061, filed on April 1, 2016, the entire disclosures of which are incorporated herein by reference.

FIELD OF THE DISCLOSURE

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[0002] The present disclosure relates generally to the suppression of undesired signal fluctuations due to noise and/or Gibbs ringing in one or more images, and more specifically, to exemplary embodiments of exemplary system, method and computer accessible medium for, for example, performing noise estimation and removal, and Gibbs ringing removal from one or
15 more images.

BACKGROUND INFORMATION

[0003] Noise and Gibbs ringing that can corrupt magnetic resonance images can, for example, hamper visual and statistical inspection, and processing of the magnetic resonance
20 images and the derived parametric maps.

[0004] Thus, it may be beneficial to provide an exemplary system, method and computer-accessible medium for noise estimation and removal, and Gibbs ringing removal, which can overcome some deficiencies present in current magnetic resonance imaging (“MRI”) systems.
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SUMMARY OF EXEMPLARY EMBODIMENTS

[0005] An exemplary system, method and computer-accessible medium for removing Gibbs ringing from a magnetic resonance (“MR”) image(s), can be provided, which can include, for example, receiving information related to the MR image(s), and removing the
30 Gibbs ringing from the information by extrapolating data in a k-space from the MR image(s) beyond an edge(s) of a measured portion of the k-space based on a regularized minimization problem(s). A first weighted term of the regularized minimization problem(s) can preserve a fidelity of the measured portion of the k-space, and a second weighted term of the regularized minimization problem(s) can be a penalty term that can be based on a norm(s) of a

representation of the MR image(s), which can be presumed to be sparse. A regularization parameter(s) can be selected based on a discrepancy criterion (criteria) that can depend on the noise level. In some exemplary embodiments of the present disclosure, the data can be extrapolated using a second order total generalized variation (“TGV”) minimization(s), which
5 can implicitly assume one piecewise linear function.

[0006] An exemplary system, method and computer-accessible medium for estimating noise in a first image(s), can be provided, which can include, for example, receiving a plurality of second images, and estimating the noise in the first image(s) based on a principal component analysis (“PCA”) procedure on a subset of the plurality of second images. The noise level can
10 be estimated based on a set of eigenvalues resulting from the PCA procedure, and further estimated based on a noise-only distribution of a subset of the eigenvalues, which can be a Marchenko-Pastur distribution.

[0007] An exemplary system, method and computer-accessible medium for removing the noise in a first magnetic resonance (“MR”) image(s), can be provided, which can include, for
15 example, receiving a plurality of second images, and distinguish between the signal carrying principal components and those principal components that contribute to noise only using a PCA procedure on a subset of the plurality of second images. The Marchenko-Pastur distribution can provide an objective and user independent criterion to distinguish between the signal and noise carrying eigenvalues of, for example, the PCA procedure. The second images
20 can, for example, include diffusion-weighted magnetic resonance images, a set of images obtained from different coils or channels in multichannel MR imaging set-up, or any other plurality of redundant data series.

[0008] In some exemplary embodiments of the present disclosure, a threshold between only the noise and at least one principal component of the PCA procedure can be identified. The
25 threshold can be identified based on a noisy covariance matrix(es). The noise can be removed based on the threshold, which can include removing a noise-only component(s) of the first image(s). The noise can be removed using a Marchenko-Pastur distribution(s).

[0009] An exemplary system, method and computer-accessible medium for removing Gibbs ringing from a first magnetic resonance (“MR”) image(s), can be provided, which can
30 include, for example, receiving a plurality of second MR images, estimating and removing the noise in the first image(s) based on a principal component analysis (“PCA”) procedure on a subset of the second images, and removing the Gibbs ringing from the first MR image(s) by

extrapolating data in a k-space, based on the noise, from the first MR image(s) beyond an edge(s) of a measured portion of the k-space.

[0010] These and other objects, features and advantages of the exemplary embodiments of the present disclosure will become apparent upon reading the following detailed description of the exemplary embodiments of the present disclosure, when taken in conjunction with the appended claims.

BRIEF DESCRIPTION OF THE DRAWINGS

[0011] Further objects, features and advantages of the present disclosure will become apparent from the following detailed description taken in conjunction with the accompanying Figures showing illustrative embodiments of the present disclosure, in which:

[0012] Figure 1 is a set of graphs illustrating the over- and undershoots of the diffusion and kurtosis coefficients according to an exemplary embodiment of the present disclosure;

[0013] Figure 2 is a set of reconstruction MPRAGE images generated using the exemplary system, method and computer-accessible medium according to an exemplary embodiment of the present disclosure;

[0014] Figure 3 is a graph illustrating k-space energy density as function of the distance to the k-space center according to an exemplary embodiment of the present disclosure;

[0015] Figures 4(A)-4(D) are exemplary images of the exemplary mean kurtosis of an axial slice of HCP data according to an exemplary embodiment of the present disclosure;

[0016] Figures 5 (A)-4(D) are exemplary images of an axial slice of HCP data according to an exemplary embodiment of the present disclosure;

[0017] Figure 5 is a graph illustrating an eigenvalue spectrum of a sample covariance matrix of simulated diffusion-weighted data and Marchenko-Pastur distribution according to an exemplary embodiment of the present disclosure

[0018] Figure 6 is set of graphs and signal-to-noise ratio maps based on and/or generated by the exemplary, system and computer-accessible medium according to an exemplary embodiment of the present disclosure;

[0019] Figure 7 is a set of maps illustrating exemplary results produced by the exemplary system, method and computer-accessible medium according to an exemplary embodiment of the present disclosure compared to a previous method;

[0020] Figure 8A is an exemplary graph of a Marchenko Pastur distribution according to an exemplary embodiment of the present disclosure;

[0021] Figure 8B is an exemplary graph of the contribution of signal and noise eigenvalues to data variability according to an exemplary embodiment of the present disclosure;

[0022] Figure 9 is a set of graphs of a percent bias in the estimation of the free-noise signal according to an exemplary embodiment of the present disclosure;

5 [0023] Figure 10 is a set of exemplary denoised diffusion-weighted images according to an exemplary embodiment of the present disclosure;

[0024] Figure 11 A is a set of σ -normalized residual maps for a single diffusion-weighted image according to an exemplary embodiment of the present disclosure;

10 [0025] Figure 11B is a set of σ -normalized residual maps for an average of all diffusion-weighted images according to an exemplary embodiment of the present disclosure;

[0026] Figure 12 is a set of graphs of the logarithms of the distribution of normalized residuals $p(r)$ as function of r^2 for different b-values according to an exemplary embodiment of the present disclosure;

15 [0027] Figure 13 is a graph of k -space energy density as function of the distance to the k -space center according to an exemplary embodiment of the present disclosure;

[0028] Figure 14 is a further set of denoised diffusion-weighted images according to an exemplary embodiment of the present disclosure;

[0029] Figure 15 is a set of maps illustrating the effect of denoising according to an exemplary embodiment of the present disclosure;

20 [0030] Figure 16 is a further set of maps illustrating the effect of denoising according to an exemplary embodiment of the present disclosure;

[0031] Figure 17 is a set of graphs illustrating the effect of denoising on the angular precision according to an exemplary embodiment of the present disclosure;

25 [0032] Figure 18 is an image illustrating effect of denoising on the fiber orientation distribution function for a voxel with a three-fiber crossing according to an exemplary embodiment of the present disclosure;

[0033] Figure 19 is an exemplary image of the overlay of tractograms derived from a single repetition of the $M_b=2.5$ data subset before and after denoising according to an exemplary embodiment of the present disclosure;

30 [0034] Figure 20A is an exemplary flow diagram of an exemplary method for removing Gibbs ringing from a magnetic resonance image according to an exemplary embodiment of the present disclosure;

[0035] Figure 20B is an exemplary flow diagram of an exemplary method for estimating a noise in a first image according to an exemplary embodiment of the present disclosure;

[0036] Figure 20C is an exemplary flow diagram of an exemplary method for removing Gibbs ringing from a first magnetic resonance image according to an exemplary embodiment of the present disclosure; and

[0037] Figure 21 is an illustration of an exemplary block diagram of an exemplary system in accordance with certain exemplary embodiments of the present disclosure.

[0038] Throughout the drawings, the same reference numerals and characters, unless otherwise stated, are used to denote like features, elements, components or portions of the illustrated embodiments. Moreover, while the present disclosure will now be described in detail with reference to the figures, it is done so in connection with the illustrative embodiments and is not limited by the particular embodiments illustrated in the figures and the appended claims.

DETAILED DESCRIPTION OF EXEMPLARY EMBODIMENTS

[0039] MR images can be affected by the Gibbs ringing that can appear near sharp edges, due to truncation of the k-space. While introducing a bias of about 9% in the weighted images, the Gibbs effect can be amplified tremendously in the derived parametric maps, for example, in diffusion and kurtosis tensor components. The amplification can occur because the Gibbs oscillations in the $b=0$ and finite- b images can be out of phase due to relative difference in DW signal, $S(b)$, and intensities at different b -values. Figure 1 illustrates this phenomenon for realistic values on the cerebral spinal fluid (“CSF”)-Corpus Callosum border with diffusion and kurtosis estimated in the radial direction. This can create a concave (e.g., Figure 1 element 115), rather than convex (e.g., Figure 1 elements 105 and 110), $\log S(b)$, which can lead to extreme unphysical apparent diffusion coefficient (“ADC”) and apparent kurtosis coefficient (“AKC”) values. The fits can exceed the physically expected bounds (e.g. positive diffusivity and kurtosis), resulting in the “black voxels” (see, e.g., Figure 4A). Thus far, the Gibbs ringing bias has been ignored or reduced by isotropic smoothing at the expense of spatial resolution loss, and the introduction of partial volume effects. However, the exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can extrapolate the data in k-space beyond the maximally measured cutoff value k_c by using, for example, a second order total generalized variation (“TGV”) minimization (see, e.g., Reference 1), which can substantially reduce Gibbs ringing and noise of the MRI data,

without compromising the resolution. To perform such an exemplary procedure, the exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can depend on the independent determination of the noise level, such as the estimation procedure described below.

5 **[0040]** The exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can estimate a spatially varying noise level (*e.g.*, can plot the noise map) from a series of MR images in a model-independent way. As the noise in MR can generally be non-Gaussian, the importance to correct for, for example, Rician or non-central χ noise bias, can rely on an independent unbiased estimate for the noise map.

10 Estimating the noise can be challenging as MR images can suffer from low spatial resolution and involuntary motion. Moreover, the noise can generally be spatially varying due to the use of parallel imaging techniques. This can be the reason why noise estimation has remained a challenging problem, with only a few methods able to deal with the spatially varying nature of the noise.

15 **[0041]** The prior techniques depend on signal model assumptions, or the wavelet transformation, to decompose the data in low frequency (“signal”) and high frequency (“noise”) information. Wavelet-based methods tend to overestimate the noise level, as the high frequency sub-band can also contain residual signal due to actual sharp edges in the image. Physiological noise, image misalignment and model inaccuracies, all tend to bias the

20 model-based methods. In contrast, the exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can provide and/or facilitate a local noise estimation paradigm based on the random matrix theory (“RMT”) result for random covariance matrices. (*See, e.g.*, Reference 8). The exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present

25 disclosure, can be free of, and perform better than, the above prior systems and methods. For example, principal component analysis (“PCA”), coupled with RMT, can be used to exploit the redundancy in a MR data series for the robust, accurate, and precise estimation of the noise level in a number of MRI modalities, such as diffusion, perfusion, functional MRI, T2, and T2*, etc.

30 **[0042]** The exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can remove the noise by exploiting the fact that noise-only eigenvalues of a PCA can be expected to be described by the universal Marchenko-Pastur distribution, a result of the random matrix theory for noisy covariance

matrices. (See e.g., Reference 36). Nullification of all eigenvalues smaller than a threshold that can be a property of the Marchenko-Pastur distribution corresponding to suppression of the noise. The threshold can depend on the noise level, which can be estimated by evaluating the eigenspectrum using, for example, the Marchenko Pastur distribution. Therefore, one might

5 correct the denoised signal for Rician or non-central- χ distributed noise bias (see e.g., References 37 and 38) using the method of moments, which rely on the noise level. (See e.g., Reference 39). Furthermore, the exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can preserve the underlying signal better than other techniques on the level of the diffusion sensitized images and diffusion

10 MR parameters of general interest.

Exemplary Method

[0043] The exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can extrapolate k-space data beyond the

15 measured k-space edge k_c , in order to remove undesired signal fluctuations due to noise and Gibbs ringing. The extrapolation of the k-space can be formatted as a regularized minimization problem $\hat{u} = \arg \min_u \| \tilde{F}u - \tilde{k} \|_2^2 + \lambda \mathcal{R}(u)$. The 1st term can preserve the fidelity with the acquired data $\tilde{k}$ (e.g., here, $\tilde{F}$) can be the windowed Fourier transformation), and the penalty term $\mathcal{R}(u)$ can be based on the L_1 norm of the image u in the basis where it can be presumed to

20 be sparse, with a regularization parameter λ chosen according to the discrepancy criterion. (See, e.g., Reference 4). This exemplary criterion can include the noise level as an input. This noise level can be estimated, for instance, using a redundancy of oversampled data as described below, or using any suitable noise estimation method. (See, e.g., Reference 11). A challenge can be to find the “right” sparse basis. The second order TGV function (see, e.g., Reference 5):

25 $\mathcal{R}(u) = \arg \min_v a \int_{\Omega} \| \nabla u - v \|_1 dx + b \int_{\Omega} \| \nabla v \|_1 dx$ can be evaluated where v can be a vector field within a volume or a slice, whose components can be bounded by 0 and ∇u , and compare it to the more commonly used TV. The empirical parameters a and b can be set to, for instance, 2 and 1, respectively. (See, e.g., References 2 and 3). Unlike TV, the second order TGV can sparsify piecewise linear functions. The reduced penalty term for this non-constant

30 piecewise linear function can avoid the staircasing effect, which can often be observed in TV regularization. An exemplary primal dual procedure can be used to solve the optimization problem. (See, e.g., Reference 6).

[0044] The exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can be used to separate signal from noise without being dependent on an often unknown physical model of the signal, which can be performed utilizing the coupling of a PCA with RMT. If the noise-free signal can be characterized by only a *small number* $P \ll N, M$ of parameters, compared to the number M of diffusion acquisitions and number N of voxels, a lot of redundancy can be expected in the data – even if both the model and its parameters can be unknown. For example, PCA based on the singular value decomposition of the $M \times N$ matrix can typically show a few “significant” eigenvalues, and the vast majority of the others originating due to the noise. Unfortunately, distinguishing between the “significant” and “noise” eigenvalues can be far from trivial. While noise in each diffusion direction can be random, its contribution to the histogram of covariance matrix eigenvalues can become deterministic for $N, M \gg 1$. (See, e.g., Figure 8a). In the case of the noise realized via independent identically distributed random variables in each channel (e.g. each imaging voxel), the contribution of the noise to the histogram of the PCA eigenvalues can be given by the universal Marchenko-Pastur distribution (see, e.g., Reference 8), where, for example:

$$p(\lambda) = \frac{\sqrt{(\lambda_+ - \lambda)(\lambda - \lambda_-)}}{2\pi Q \sigma^2} \text{ if } \lambda_- \leq \lambda \leq \lambda_+ \text{ (0 otherwise)}$$

with $\lambda_{\pm} = \sigma^2(1 \pm \sqrt{Q})^2$, σ the standard deviation of the noise in each channel (e.g. imaging voxel), and $Q = \tilde{M}/N$ ($\tilde{M}$ can be the number of *noise-only* components). When the noise in each channel (e.g., imaging voxel) can be characterized by a variance, not necessarily the same for each channel, a generalization of the Marchenko-Pastur distribution can be obtained, analytically or numerically, which can be parameterized by a set of noise variances. The unknown parameters, σ and $\tilde{M}$, can, for example, be estimated by exploiting the following or other properties of the Marchenko-Pastur distribution: (i) the expectation value of the distribution is proportional to σ^2 , and (ii) the width of the Marchenko-Pastur distribution is proportional to σ^2 . Thus, the average and range of the $\tilde{M}$ smallest eigenvalues can be proportional to σ^2 . To correct for the potential of non-Gaussian MR data statistics, the “significant” eigenvalues, which can be determined as being above the edge of the bulk of the noise-only eigenvalues, can be used to estimate the underlying signal. Both this signal, and the Gaussian noise level(s) σ , can return the non-Gaussian noise level(s) using, for example, Koay’s inversion procedure. (See, e.g., Reference 9). The exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present

disclosure, can apply this procedure within a sliding window (*e.g.*, $N=7\times7\times7$), or in any other suitable manner of combining N voxels.

[0045] The exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can be used to estimate the noise level, for example, based on a grid search in function of $\tilde{M}$ to identify the subset of $\tilde{M}$ smallest eigenvalues that can meet the above-described, or complementary, properties of the Marchenko-Pastur distribution. Thus, the exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can combine the estimation of the noise level to adjust the regularization parameter λ utilized in the exemplary Gibbs ringing removal procedure. In particular, the optimally adjusted λ can, for example, preserve the data fidelity up to level of the noise variance scaled by the number of measured k-space samples.

[0046] The exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can be used to remove the noise of a redundant data matrix X , for example, based on a grid search in function of $\tilde{M}$ to identify the subset of $\tilde{M}$ smallest eigenvalues that can meet the above-mentioned, or complementary, properties of the Marchenko-Pastur distribution. Nullifying the $\tilde{M}$ smallest eigenvalues, and reconstructing the matrix, can result in a denoised matrix, where, for example: $\hat{X} = \sqrt{N}U\tilde{\Lambda}V^T$, with U and V unitary matrices whose columns can be the left-singular and right-singular vectors of the redundant data matrix X , respectively, and $\tilde{\Lambda}$ a diagonal matrix of the corresponding eigenvalues where the $\tilde{M}$ smallest eigenvalues can be set to zero. Since the exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can simultaneously output the denoised data and noise variance, the denoised data can, for example, be corrected for the Non-Gaussian noise biases using, for example, Koay's inversion procedure. (*See, e.g.*, Reference 9). The exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can apply this procedure within a sliding window (*e.g.*, $N=7\times7\times7$), or in any other suitable manner of combining N voxels.

Exemplary Simulation: Gibbs Ringing Removal

[0047] Truncating a high-resolution (*e.g.*, HR; 256x256) MPRAGE image in k -space (*e.g.*, cut-off frequency k_c) generated a simulated image that mimics a low-resolution "acquisition"

(e.g., LR; 96x96). A qualitative comparison of the different filtering and reconstruction procedures, for example, zero-filling (“ZF”), TV and TGV, applied on the single slice of a simulated image shows that Gibbs ringing can be strongly reduced by extrapolation of the k -space using second order TGV without the introduction of the staircase or loss of spatial resolution compared to LR acquisition. (See, e.g., Figure 2). However, fine anatomical details lost during LR acquisition cannot be recovered (see, e.g., Figure 2, arrows 205). This can be expected, as there may be no random sampling in the HR k -space for the compressed sensing reconstruction to work. Both the Lancsoz and Gaussian filters show significant spatial resolution loss. As shown in the graph of Figure 3, corresponding k -space filling, for example, the k -energy density as function of the distance to the k -space center shows that in contrast to window filtering, both TV (line 305) and TGV (line 310) hardly affect the actually measured k -space data, $k < k_c$. A good recovery of k -space filling beyond k_c for both TV and TGV can be observed. The broad peak at $k \sim 2k_c$ can be a signature of the nonlinear reconstruction (e.g., harmonic doubling). TV’s overestimation of high frequencies compared to the HR (line 315) data can explain the staircase artifact observed in the corresponding image, as it can model the image as a piecewise constant function. (See, e.g., References 2 and 3). The TGV reconstructed images do not show the staircase artifacts. The graph of Figure 3 also illustrates measure k -space data for ZF (line 320) Gaussian (line 325) and Lancsoz (line 330)

20 ***Exemplary Simulation: noise estimation***

[0048] Figure 6 shows a set of maps and graphs estimated from simulated data (e.g., average SNR of the non-DW image was 20 and 40). Noise-free (e.g., filtered) DW images (e.g., 90 gradient directions and $b = 1 \text{ ms}/\mu\text{m}^2$) were derived from Human Connectome Project dMRI data by fitting 4th order spherical harmonics and recomputing directional data; this can be used as ground truth. Rician noise with a uniform noise level was artificially added to compare the exemplary proposed local RMT-based method (e.g., PCA-RMT element 605), local wavelet-based noise map estimator (see, e.g., Reference 11) (“WAVELET”) (e.g., element 610), and its global counterpart. (See, e.g., Reference 10). Both wavelet approaches tend to overestimate the noise; this bias can depend on SNR. Moreover, its local version (see, e.g., Reference 11) shows structure, whereas the exemplary RMT method can show high accuracy and precision regardless of the underlying signal.

Exemplary Denoising Simulation

[0049] A set of 1000 Rician distributed $M \times N$ data matrices was computed by projecting N , ranging from about 100 to about 2500, axially symmetric diffusion tensors onto $M = 30, 60$, and 90 diffusion gradient directions with $b = 1 \text{ ms}/\mu\text{m}^2$. The underlying FA and MD for each tensor was sampled from a distribution with mean 0.6 and $0.8 \mu\text{m}^2/\text{ms}$, respectively, and standard deviation of 0.1. The accuracy of the denoising procedures, as a function of M and N , can be evaluated. In Figure 9, the average and standard deviation of the error, that can be the difference between denoised and noise-free signal, can be plotted as function of M , N and SNR. As shown in the graphs of Figure 9, M can equal 30 (e.g., element 905), 60 (element 910) or 90 (element 915). The overall accuracy of denoising can be very high. The error, normalized by noise-free data, can be unbiased with a significance of $\alpha = 0.05$ for $\text{SNR}=50$, whereas the underestimation of the signal for $\text{SNR}=25$ can be limited to about 0.01% after Rician bias correction. The standard deviation of the error, that can be the standard deviation of the non-suppressed noise, normalized by $\sigma\sqrt{p}$, can decay with M and N , $\sim \sqrt{\frac{M}{p}}$ for $N \rightarrow \infty$. A universal expression of the decay for finite N can be missing though.

Exemplary Diffusion-weighted MR: Noise Estimation

[0050] Diffusion-weighted MR data can be selected as an example of a redundant MR series. For a diffusion-weighted MR measurement (e.g., 12 repetitions of $b = 0, 60 \times b = 1 \text{ ms}/\mu\text{m}^2$, 12 repetitions of $1 \times b = 3 \text{ ms}/\mu\text{m}^2$), the exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present disclosure, can be applied to the $b = 1 \text{ ms}/\mu\text{m}^2$ shell, and can be compared to (i) the wavelet-based local noise map estimator applied on the same shell, and (ii) the noise maps derived from the repeated measurements. (See, e.g., Figure 7). (See, e.g., Reference 12). For example, the graph of Figure 7 shows the Bronze Standard versus noise map estimators for PCA_RMT 705 and WAVELET 710. The noise map derived from the $b = 0$ repetitions can be affected by pulsation artifacts. This effect may not be visible in the exemplary bronze standard based on 12 repetitions from the same $b = 3 \text{ ms}/\mu\text{m}^2$ image. Strong edges (e.g., high frequency information) in the dMRI images shine-through in the wavelet-based approach, whereas the exemplary system, method and computer-accessible medium shows a smooth, artifact-free, noise map that can be more consistent with the bronze standard than the

wavelet-based method (*e.g.*, correlation coefficient of 0.9951 and 0.9782, respectively; and Figure 3).

Exemplary Diffusion-weighted MRI: Gibbs Ringing Removal

5 [0051] Figures 4(A)-4(D) show mean kurtosis (“MK”) images and Figures 5A -5D show axonal water fraction (“AWF”) images of a detail, for example, the splenium, of a single axial slice of the Human Connectome Project (“HCP”) data, which was downsampled to 96x96 by truncation of the k -space and subsequently reconstructed to the original 144x174 resolution using ZF, TV, and TGV. (See, *e.g.*, Reference 7) Without smoothing and constraining the

10 kurtosis tensor fit, extreme negative MK values (*e.g.*, “black voxels”) and/or unexpected heterogeneity in AWF can be observed in regions of interest such as the Corpus Callosum. (See, *e.g.*, Figure 4(A)). Current practice can be to smooth and constraint the data fit. (See, *e.g.*, Figures 4(B) and 5 (B)). Both TV (*see, e.g.*, Figures 4(C) and 5 (C)) and TGV (*see, e.g.*, Figures 4(D) and 5 (D)) result in a more robust fit as they minimize the Gibbs effect and the

15 noise without manipulation of the resulting statistics and loss of spatial resolution. The exemplary regularization parameter can be chosen according to a various criteria based on the noise level, which can be estimated using the exemplary system, method and computer-accessible

20 ***Exemplary Diffusion-Weighted MRI Noise Removal***

[0052] A healthy volunteer underwent imaging on a Siemens Prisma (*e.g.*, 3T) MR scanner (*e.g.*, Siemens AG, Siemens Medical Solutions, Erlangen, Germany) after obtaining informed consent, using a 64-channel receiver head coil. The body coil was used for transmission. An EPI-DW sequence was used to acquire 3 repetitions of the following dMRI data. Besides the

25 acquisition of about 18 non-diffusion-weighted images, diffusion weighting was applied along about 90 isotropically distributed gradient directions with $b = 1$ and $2.5 \text{ ms}/\mu\text{m}^2$. The following imaging parameters were kept constant throughout the data acquisition sequences: TR/TE: 4000/76 ms, matrix: 92x92, voxel dimensions: 2.5x2.5mm, slice thickness: 2.5 mm, slices: 50, parallel imaging factor: GRAPPA with acceleration factor 2, reconstructed using the adaptive

30 combine procedure and simultaneous multislice factor 2. The subsets of this data can be referred to as follows: $M_{b=x} = y$ or $M_{b \leq x} = y$, with y the subset s number of dMRI encodings and x an experiment-specific b -value. The exemplary system, method and computer-accessible medium, according to an exemplary embodiment of the present

disclosure, can be applied to subset $M_{b \leq 2.5} = 120$ of the first repetition and can compare the result to ANLM and TGV. The resultant maps for a single dMRI image of $b = \{0, 1, 2.5\} \text{ ms}/\mu\text{m}^2$ are shown for qualitative comparison in Figure 10. The normalized residuals for those images, $r = (\hat{X} - X)/\hat{\sigma}$, are shown in Figure 11A. Although the anatomical structure can already be observed in the residual maps, normalized by noise map, of ANLM and TGV, these effects can mainly be visible after averaging the residual maps of all images per value. (See, e.g., Figure 11b). The lack of anatomical structure and zero-centered residuals can indicate good preservation of signal, and/or accuracy. The exemplary MPPCA outperforms ANLM and TGV in that respect.

[0053] The distribution of the σ -normalized residuals, r , resulting from denoising following subsets $M_{b=1} = 30, 60, \text{ and } 90$ of the first repetition of the clinical data are shown in Figure 12. The logarithm of the distribution $p(r)$ can be shown as function of r^2 . A zero-centered normal distribution with variance σ^2 can then be represented by a straight line with slope $1/\sigma^2$. Normalized residuals can be described by the standard normal distribution because only then all the noise can be accumulated in the residuals. The exemplary MPPCA (e.g., element 1205) and TGV (e.g., element 1210) can be well described by a normal distribution, whereas ANLM (e.g., element 1219) shows clear deviations. More importantly, MPPCA has a lower variance than unity, whereas TGV and ANLM have a higher variance. In the latter, the residuals contain more variance than explained by the noise. Genuine signal fluctuations (e.g. fine anatomical details) can be removed by ANLM and TGV and add to the variance of the residuals. Conversely, MPPCA does not remove anatomical details ; conservatively removing only noise. The variance of the exemplary MPPCA residuals can range from about 68% to about 89% of the estimated noise variance. This translates to an MPPCA induced SNR improvement of about 76% and about 200%, respectively.

[0054] The apparent blurring for ANLM and TGV (e.g., elements 1305 and 1310 of Figure 13) can be quantitatively confirmed by comparing the k -energy density (see, e.g., Reference 29) (integrated over a narrow square shell in 2d), as function of the distance to the k -space center k . Given the exemplary discrete k -space grid $\hat{u}_k$, $[n_x \times n_y]$, with frequency resolution Δk , the k -energy density can be computed as $\|\hat{u}_k(\Omega(n_k \Delta k))\|_2$ for $n_k = 1$ to $\min(n_x, n_y)$ with $\Omega(n \Delta k)$ being the 2d square shell centered around the k -space center. A reference energy density can be predicted by subtracting the noise power $N_\Omega \sigma^2$ with N_Ω the number of samples in Ω from the corresponding k -space density of the original data (e.g., element 1315 of Figure

13). This normalized quantity shows the observed loss of higher frequencies for ANLM and TV (*e.g.*, low-pass filtering). Spatial resolution loss and blur can be the direct consequence. The suppression of frequencies that may not be strictly rooted in thermal noise can also result in residuals that can follow a distribution with standard deviation exceeding the noise standard deviation (*e.g.*, meaning that they can be contaminated by signal). Thus, the exemplary MPPCA (*e.g.*, element 1320 of Figure 13) can preserve the actual signal better than competing methods (*e.g.*, element 1325). In Figure 14, denoised diffusion weighted images of the HCP data with $b = \{0, 1, 3, 5, \text{ and } 10\} \text{ ms}/\mu\text{m}^2$ are shown. The data quality enhancement can be visible in all methods. However, significant differences can be noticeable. Overall, MPPCA preserves anatomical detail better than ANLM and TGV. Moreover, artifactual features present in TGV at high b may not be shown in MPPCA. The MPPCA residuals do not show anatomical details. Indeed, only a spatially varying noise trend can be observed, and this can be in line with previous results as a marker for accuracy. Bootstrapping ($n = 500$) with replacement based on the 3 repetitions was used to assess the effect of the different denoising strategies on the variability in FA and MD maps. (*See, e.g.*, Figure 15). Note that the gradient directions for every single generated data set were the same. All denoising procedures improve the precision of diffusion parameter estimators, in all structures of the brain. The excellent results of ANLM in terms of precision can be superficial. It can look as if ANLM does a good job, however studying the residuals between the denoised results and a ground truth from $3 \times [5 \times b = 0]$ and $3 \times [90 \times b = 1 \text{ ms}/\mu\text{m}^2]$ ($M = 15 + 270$), severe biases are revealed. Indeed, by averaging the residual maps between parameters maps with and without denoising, the systematic differences for ANLM and TGV in every brain structure can be seen. (*See, e.g.*, Figure 16). The differences root in the accumulation of signal inaccuracies introduced during denoising of the individual images. The exemplary MPPCA shows structure-free, zero-centered residuals for MD and FA.

[0055] A similar bootstrapping approach can be used to evaluate the effect on the estimation of diffusion directions using constrained spherical convolution. The distribution of angular precision, probed by the coherence metric κ (Eq. [12]), and the angular deviation from original (*e.g.*, element 1705) data amongst white matter voxels is shown in the graphs Figure 17. Again, for all evaluated M , ANLM (*e.g.*, element 1710), MPPCA (*e.g.*, element 1715) and – to a lesser degree – TGV (*e.g.*, element 1720) improve the variability or dispersion in the primary and secondary diffusion directions. However, consistent with previous results, MPPCA can outperform all other methods in terms of accuracy. MPPCA shows minimal

angular deviation from the original data, whereas the deviations can be significantly higher for TGV, and more so for ANLM. In the image of Figure 18, the fODF corresponding to a single voxel is shown for each of the three repetitions (limited to $M_{b=2.5} = 60$), with and without applying the different denoising techniques. In the particular voxel, the callosal commissure, superior longitudinal fasciculus and corticospinal tract cross. This complex fiber crossing can be assumed to be represented by a fODF with three distinct lobes. The success rate to detect the third lobe can depend on the method used. MPPCA returns in about 98% of the $n = 500$ bootstrap realizations exactly three distinct peaks. The success rate lowers to about 65% and about 48% for ANLM and TGV, respectively, whereas no denoising results in a success rate of about 70%. A spurious fourth peak (around 1805 in Figure 18) can be detected in about 2%, about 30%, about 52% and about 28% of the cases for MPPCA, ANLM, TGV and original, respectively. Additionally, a probabilistic tractography was performed on the denoised images corresponding to one of the repetitions (again restricted to $M_{b=2.5} = 60$) to render digital reconstructions of the major fiber pathways as colorful tubes (*See, e.g.,* original data, 1905, ANLM 1920, 1915 and MPPCA 1920 in the image of Figure 19). (*See, e.g.,* Reference 52). Some obvious spurious fibers aside, all tractograms look perfectly plausible, yet very different, especially towards the cortical areas. Those differences reflect the differences in noise and signal patterns that depend on the used denoising technique. (*See e.g.,* Figures 10-13, 17 and 18).

Exemplary Conclusion

[0056] Promising results were obtained in suppressing the Gibbs artifact by extrapolation k -space data beyond the measurements by means of second order TGV minimization. The second order TGV framework inherently assumes that the underlying MR data can be modeled by a piecewise linear function. However, since the extrapolation of the k -space can be solely based on that model assumption, fine anatomical details that can be concealed in the unmeasured part of the k -space might not be recovered. Full recovery would need at least a random sampling of the k -space, including the high frequencies (*e.g.,* compared to Compressed Sensing theory). Nonetheless, it was shown signal model parameters can be estimated more robustly and accurately, for example, without violating physical constraints, using the TGV-based Gibbs ringing correction. Moreover, unlike filtering techniques, the exemplary

system, method and computer-accessible medium can affect the actually measured k-space data ($k < k_c$) and, as such, can maintain the acquisition resolution.

[0057] The exemplary system, method and computer-accessible medium can couple the local PCA/singular value decomposition (“SVD”) with the RMT results such as the one due to Marchenko and Pastur, in order to distinguish between the noise and signal components in a model-independent way, and without the need of an empirically set threshold value on eigenvalues of the principal components. (*See, e.g.,* Reference 13). The exemplary RMT-PCA procedure outperforms known spatially varying noise estimation methods, and does not need acquisition of repeated measurements, instead utilizing data redundancy. The results easily generalize onto a non-Gaussian MR distribution (*see, e.g.,* Reference 9), and can be applied in all redundant time series, such as diffusion-weighted MR, T2/T2*, functional MR, or dynamic contrast-enhanced / dynamic susceptibility contrast MRI.

[0058] The exemplary system, method and computer-accessible medium can couple the local PCA/singular value decomposition (“SVD”) with the RMT results such as the one due to Marchenko and Pastur, in order to distinguish between the noise and signal components in a model-independent way, and without the need of an empirically set threshold value on eigenvalues of the principal components. (*See, e.g.,* Reference 13). The noise components can be nullified as a result of which noise can be removed in the resulting data. The exemplary MPPCA procedure outperforms known denoising techniques in terms of accuracy as it has been shown to preserve the signal better than competing methods. The results easily generalize onto a non-Gaussian MR distribution (*see, e.g.,* Reference 9), and can be applied in all redundant time series, such as diffusion-weighted MR, T2/T2*, functional MR, or dynamic contrast-enhanced / dynamic susceptibility contrast MRI.

[0059] Figure 20A is an exemplary flow diagram of an exemplary method 2000 for removing Gibbs ringing from a magnetic resonance image according to an exemplary embodiment of the present disclosure. For example, at procedure 2005 at least one regularization parameter can be selected based on at least one discrepancy criteria that can depend on the noise level. At procedure 2010, information related to a at least one MR image can be received. At procedure 2015, data in a k-space can be extrapolated from the at least one MR image beyond at least one edge of a measured portion of the k-space. At procedure 2020, the Gibbs ringing can be removed from the information.

[0060] Figure 20B is an exemplary flow diagram of an exemplary method 2025 for estimating a noise in a first image according to an exemplary embodiment of the present disclosure. For example at procedure 2030, a plurality of second images can be received. At procedure 2035, the noise in the at least one first image can be estimated based on a principal component analysis procedure on a subset of the second images. At procedure 2040, the noise can be removed from the at least one first image.

[0061] Figure 20C is an exemplary flow diagram of an exemplary method 2045 for removing Gibbs ringing from a first magnetic resonance image according to an exemplary embodiment of the present disclosure. For example, at procedure 2050, a plurality of second magnetic resonance images can be received. At procedure 2055, the noise in the at least one first magnetic resonance image can be estimated based on a principal component analysis (“PCA”) procedure on a subset of the second magnetic resonance images. At procedure 2060, the Gibbs ringing can be removed from the at least one first magnetic resonance image by extrapolating data in a k-space, based on the noise, from the at least one first magnetic resonance image beyond at least one edge of a measured portion of the k-space

[0062] Figure 21 shows a block diagram of an exemplary embodiment of a system according to the present disclosure. For example, exemplary procedures in accordance with the present disclosure described herein can be performed by a processing arrangement and/or a computing arrangement 2102. Such processing/computing arrangement 2102 can be, for example entirely or a part of, or include, but not limited to, a computer/processor 2104 that can include, for example one or more microprocessors, and use instructions stored on a computer-accessible medium (*e.g.*, RAM, ROM, hard drive, or other storage device).

[0063] As shown in Figure 21, for example a computer-accessible medium 2106 (*e.g.*, as described herein above, a storage device such as a hard disk, floppy disk, memory stick, CD-ROM, RAM, ROM, etc., or a collection thereof) can be provided (*e.g.*, in communication with the processing arrangement 2102). The computer-accessible medium 2106 can contain executable instructions 2108 thereon. In addition or alternatively, a storage arrangement 2110 can be provided separately from the computer-accessible medium 2106, which can provide the instructions to the processing arrangement 2102 so as to configure the processing arrangement to execute certain exemplary procedures, processes and methods, as described herein above, for example.

[0064] Further, the exemplary processing arrangement 2102 can be provided with or include an input/output arrangement 2114, which can include, for example a wired network, a

wireless network, the internet, an intranet, a data collection probe, a sensor, etc. As shown in Figure 21, the exemplary processing arrangement 2102 can be in communication with an exemplary display arrangement 2112, which, according to certain exemplary embodiments of the present disclosure, can be a touch-screen configured for inputting information to the processing arrangement in addition to outputting information from the processing arrangement, for example. Further, the exemplary display 2112 and/or a storage arrangement 2110 can be used to display and/or store data in a user-accessible format and/or user-readable format.

[0065] The foregoing merely illustrates the principles of the disclosure. Various modifications and alterations to the described embodiments will be apparent to those skilled in the art in view of the teachings herein. It will thus be appreciated that those skilled in the art will be able to devise numerous systems, arrangements, and procedures which, although not explicitly shown or described herein, embody the principles of the disclosure and can be thus within the spirit and scope of the disclosure. Various different exemplary embodiments can be used together with one another, as well as interchangeably therewith, as should be understood by those having ordinary skill in the art. In addition, certain terms used in the present disclosure, including the specification, drawings and claims thereof, can be used synonymously in certain instances, including, but not limited to, for example, data and information. It should be understood that, while these words, and/or other words that can be synonymous to one another, can be used synonymously herein, that there can be instances when such words can be intended to not be used synonymously. Further, to the extent that the prior art knowledge has not been explicitly incorporated by reference herein above, it is explicitly incorporated herein in its entirety. All publications referenced are incorporated herein by reference in their entireties.

EXEMPLARY REFERENCES

[0066] The following references are hereby incorporated by reference in their entireties:.

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WHAT IS CLAIMED IS:

1. A non-transitory computer-accessible medium having stored thereon computer-executable instructions for removing Gibbs ringing from at least one magnetic resonance (“MR”) image, wherein, when a computer arrangement executes the instructions, the computer arrangement is
5 configured to perform procedures comprising:
 - receiving information related to the at least one MR image; and
 - removing the Gibbs ringing from the information by extrapolating data in a k-space from the at least one MR image beyond at least one edge of a measured portion of the k-space.
- 10 2. The computer-accessible medium of claim 1, wherein the computer extrapolates the data based on at least one regularized minimization problem.
3. The computer-accessible medium of claim 2, wherein a first weighted term of the at least one regularized minimization problem preserves a fidelity of the measured portion of the
15 k-space, and a second weighted term of the at least one regularized minimization problem is a penalty term that is based on at least one norm of a sparse representation of the at least one MR image.
4. The computer-accessible medium of claim 3, wherein the at least one representation of the
20 MR image(s) is presumed to be sparse.
5. The computer-accessible medium of claim 3, wherein the computer arrangement is further configured to select at least one regularization parameter based on at least one discrepancy criteria that depends on the noise level.
25
6. The computer-accessible medium of claim 1, wherein the computer arrangement extrapolates the data using at least one second order total generalization variation (“TGV”) minimization.
- 30 7. The computer-accessible medium of claim 6, wherein the TGV minimization implicitly assumes one piecewise linear function.

8. A system for removing Gibbs ringing from at least one magnetic resonance (“MR”) image, comprising:

a computer hardware arrangement configured to:

- receive information related to the at least one MR image; and
- 5 • remove the Gibbs ringing from the information by extrapolating data in a k-space from the at least one MR image beyond at least one edge of a measured portion of the k-space.

9. The system of claim 8, wherein the computer hardware arrangement extrapolates the data
10 based on at least one regularized minimization problem.

10. The system of claim 9, wherein a first weighted term of the at least one regularized minimization problem preserves a fidelity of the measured portion of the k-space, and a second weighted term of the at least one regularized minimization problem is a penalty term that is
15 based on at least one norm of a sparse representation of the at least one MR image.

11. The system of claim 10, wherein the at least one representation of the MR image(s) is presumed to be sparse.

20 12. The system of claim 10, wherein the computer hardware arrangement is further configured to select at least one regularization parameter based on at least one discrepancy criteria that depends on the noise level.

13. The system of claim 8, wherein the computer hardware arrangement extrapolates the data
25 using at least one second order total generalization variation (“TGV”) minimization.

14. The system of claim 13, wherein the TGV minimization implicitly assumes one piecewise linear function.

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15. A method for removing Gibbs ringing from at least one magnetic resonance (“MR”) image, comprising:

receiving information related to the at least one MR image; and

removing the Gibbs ringing from the information by extrapolating data in a k-space from the at least one MR image beyond at least one edge of a measured portion of the k-space.

16. The method of claim 15, wherein the computer extrapolates the data based on at least one
5 regularized minimization problem.

17. The method of claim 2, wherein a first weighted term of the at least one regularized
minimization problem preserves a fidelity of the measured portion of the k-space, and a second
weighted term of the at least one regularized minimization problem is a penalty term that is
10 based on at least one norm of a sparse representation of the at least one MR image.

18. The method of claim 17, wherein the at least one representation of the MR image(s) is
presumed to be sparse.

15 19. The method of claim 17, wherein the computer arrangement is further configured to select
at least one regularization parameter based on at least one discrepancy criteria that depends on
the noise level.

20. The method of claim 15, wherein the computer arrangement extrapolates the data using at
20 least one second order total generalization variation ("TGV") minimization.

21. The method of claim 20, wherein the TGV minimization implicitly assumes one piecewise
linear function.

25 22. A non-transitory computer-accessible medium having stored thereon computer-executable
instructions for estimating a noise in at least one first image, wherein, when a computer
arrangement executes the instructions, the computer arrangement is configured to perform
procedures comprising:

receiving a plurality of second images; and
30 estimating the noise in the at least one first image based on a principal component
analysis ("PCA") procedure on a subset of the second images.

23. The computer-accessible medium of claim 22, wherein the computer arrangement estimates the noise level based on a set of eigenvalues resulting from the PCA procedure.

24. The computer-accessible medium of claim 23, wherein the computer arrangement
5 estimates the noise level based on a noise-only distribution of a subset of the eigenvalues.

25. The computer-accessible medium of claim 24, wherein the noise-only distribution includes eigenvalues of a PCA Eigen spectrum that is described by a Marchenko-Pastur distribution.

10 26. The computer-accessible medium of claim 23, wherein the computer arrangement is further configured to remove the noise from the at least one first image using the set of eigenvalues.

27. The computer-accessible medium of claim 22, wherein the second images include, at least
15 one of diffusion-weighted magnetic resonance images, or a set of images obtained from different coils or channels in a multichannel magnetic resonance imaging apparatus..

28. The computer-accessible medium of claim 22, wherein the computer arrangement is further configured to remove the noise from the at least one first image.

20

29. The computer-accessible medium of claim 28, wherein the computer arrangement is configured to identify a threshold between only the noise and at least one principal component of the PCA procedure.

25 30. The computer-accessible medium of claim 29, wherein the computer arrangement is configured to identify the threshold based on at least one noisy covariance matrix.

31. The computer-accessible medium of claim 30, wherein the computer arrangement is configured to remove the noise based on the threshold.

30

32. The computer-accessible medium of claim 31, wherein the computer arrangement is configured to remove the noise by removing at least one noise-only component of the at least one first image.

33. The computer-accessible medium of claim 28, wherein the computer arrangement is configured to remove the noise using at least one Marchenko-Pastur distribution.

- 5 34. A system for estimating a noise in at least one first image, comprising:
a computer hardware arrangement configured to:
receive a plurality of second images; and
estimate the noise in the at least one first image based on a principal component
analysis ("PCA") procedure on a subset of the second images.

10

35. The system of claim 34, wherein the computer arrangement estimates the noise level based on a set of eigenvalues resulting from the PCA procedure.

15

36. The system of claim 35, wherein the computer arrangement estimates the noise level based on a noise-only distribution of a subset of the eigenvalues.

37. The system of claim 36, wherein the noise-only distribution includes eigenvalues of a PCA Eigen spectrum that is described by a Marchenko-Pastur distribution.

20

38. The system of claim 35, wherein the computer arrangement is further configured to remove the noise from the at least one first image using the set of eigenvalues.

25

39. The system of claim 34, wherein the second images include, at least one of
diffusion-weighted magnetic resonance images, or a set of images obtained from different coils
or channels in a multichannel magnetic resonance imaging apparatus..

40. The system of claim 34, wherein the computer arrangement is further configured to remove the noise from the at least one first image.

30

41. The system of claim 40, wherein the computer arrangement is configured to identify a threshold between only the noise and at least one principal component of the PCA procedure.

42. The system of claim 41, wherein the computer arrangement is configured to identify the threshold based on at least one noisy covariance matrix.

43. The system of claim 42, wherein the computer arrangement is configured to remove the noise based on the threshold.

44. The system of claim 43, wherein the computer arrangement is configured to remove the noise by removing at least one noise-only component of the at least one first image.

45. The system of claim 40, wherein the computer arrangement is configured to remove the noise using at least one Marchenko-Pastur distribution.

46. A method for estimating a noise in at least one first image, comprising:

receiving a plurality of second images; and

using a computer hardware arrangement, estimating the noise in the at least one first image based on a principal component analysis ("PCA") procedure on a subset of the second images.

47. The method of claim 46, wherein the computer arrangement estimates the noise level based on a set of eigenvalues resulting from the PCA procedure.

48. The method of claim 47, wherein the computer arrangement estimates the noise level based on a noise-only distribution of a subset of the eigenvalues.

49. The method of claim 48, wherein the noise-only distribution includes eigenvalues of a PCA Eigen spectrum that is described by a Marchenko-Pastur distribution.

50. The method of claim 47, wherein the computer arrangement is further configured to remove the noise from the at least one first image using the set of eigenvalues.

51. The method of claim 46, wherein the second images include, at least one of diffusion-weighted magnetic resonance images, or a set of images obtained from different coils or channels in a multichannel magnetic resonance imaging apparatus..

52. The method of claim 46, wherein the computer arrangement is further configured to remove the noise from the at least one first image.

5 53. The method of claim 52, wherein the computer arrangement is configured to identify a threshold between only the noise and at least one principal component of the PCA procedure.

54. The method of claim 53, wherein the computer arrangement is configured to identify the threshold based on at least one noisy covariance matrix.

10

55. The method of claim 54, wherein the computer arrangement is configured to remove the noise based on the threshold.

56. The method of claim 55, wherein the computer arrangement is configured to remove the noise by removing at least one noise-only component of the at least one first image.

15

57. The method of claim 52, wherein the computer arrangement is configured to remove the noise using at least one Marchenko-Pastur distribution.

20 58. A non-transitory computer-accessible medium having stored thereon computer-executable instructions for removing Gibbs ringing from at least one first magnetic resonance (MR) image, wherein, when a computer arrangement executes the instructions, the computer arrangement is configured to perform procedures comprising:

receiving a plurality of second MR images;

25 estimating the noise in the at least one first image based on a principal component analysis ("PCA") procedure on a subset of the second images; and

removing the Gibbs ringing from the at least one first MR image by extrapolating data in a k-space, based on the noise, from the at least one first MR image beyond at least one edge of a measured portion of the k-space.

30

59. A system for removing Gibbs ringing from at least one first magnetic resonance (MR) image, comprising:

a computer hardware arrangement configured to:

receive a plurality of second MR images;
estimate the noise in the at least one first image based on a principal component analysis (“PCA”) procedure on a subset of the second images; and
remove the Gibbs ringing from the at least one first MR image by extrapolating
5 data in a k-space, based on the noise, from the at least one first MR image beyond at least one edge of a measured portion of the k-space.

60. A method for removing Gibbs ringing from at least one first magnetic resonance (MR) image, comprising:

10 receiving a plurality of second MR images;
estimating the noise in the at least one first image based on a principal component analysis (“PCA”) procedure on a subset of the second images; and
using a computer hardware arrangement, removing the Gibbs ringing from the at least one first MR image by extrapolating data in a k-space, based on the noise, from the at least one
15 first MR image beyond at least one edge of a measured portion of the k-space.

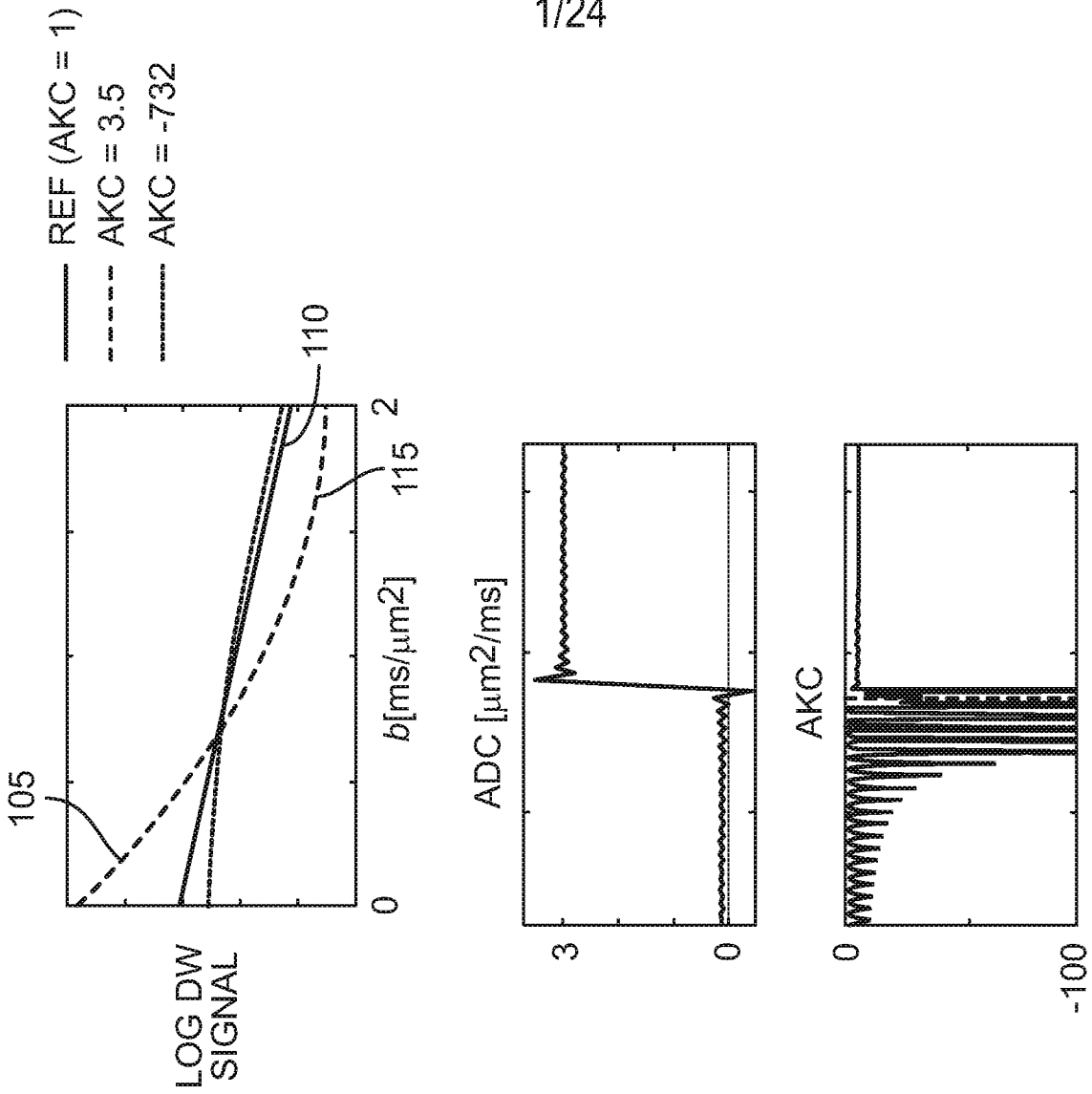


FIG. 1

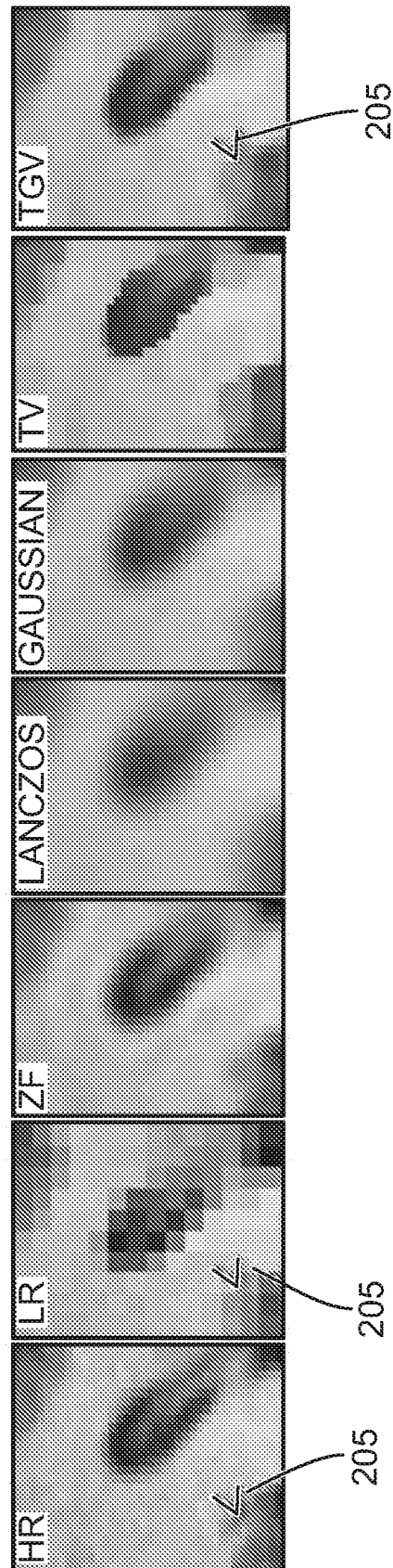


FIG. 2

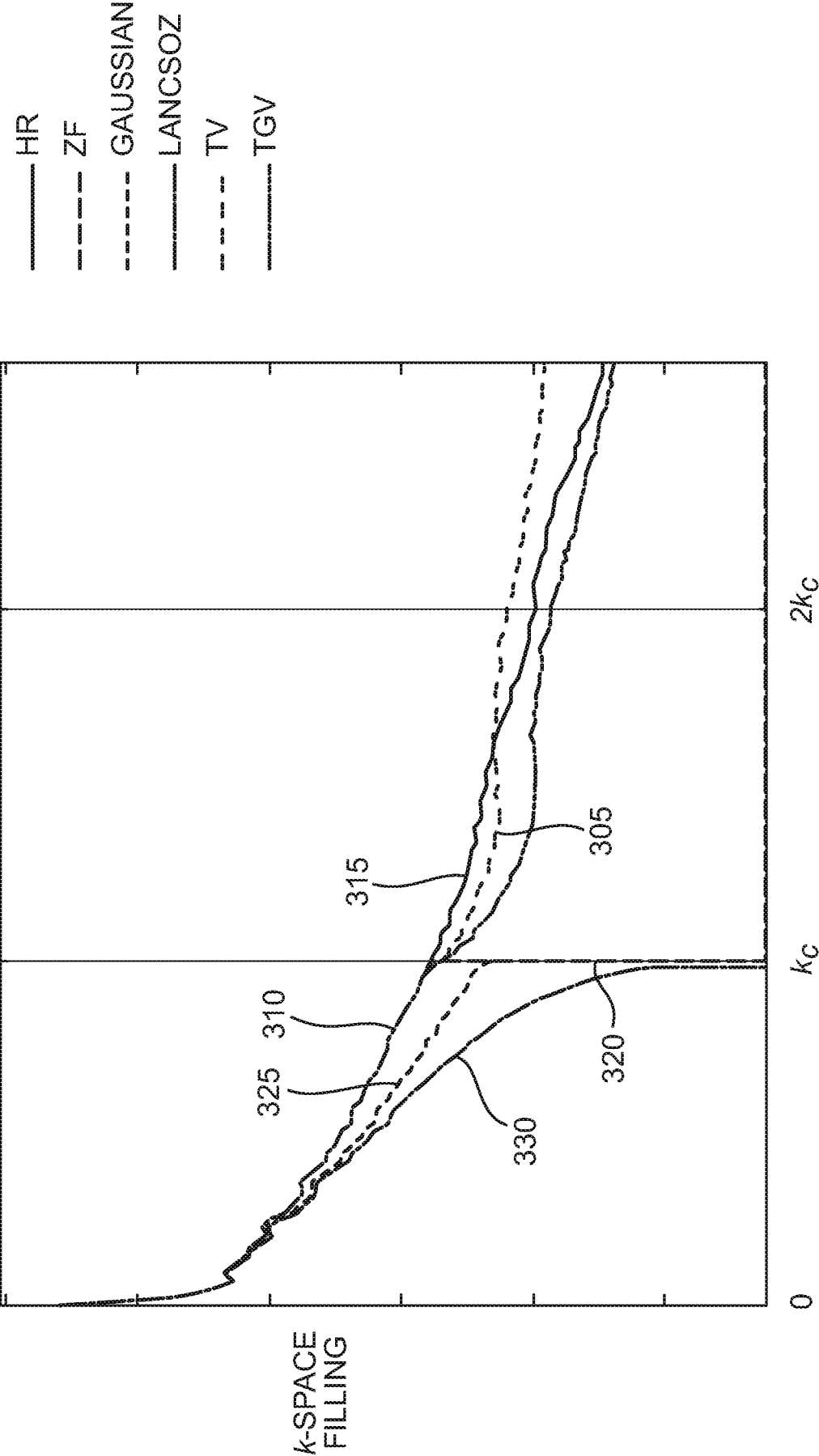


FIG. 3

FIG. 4A

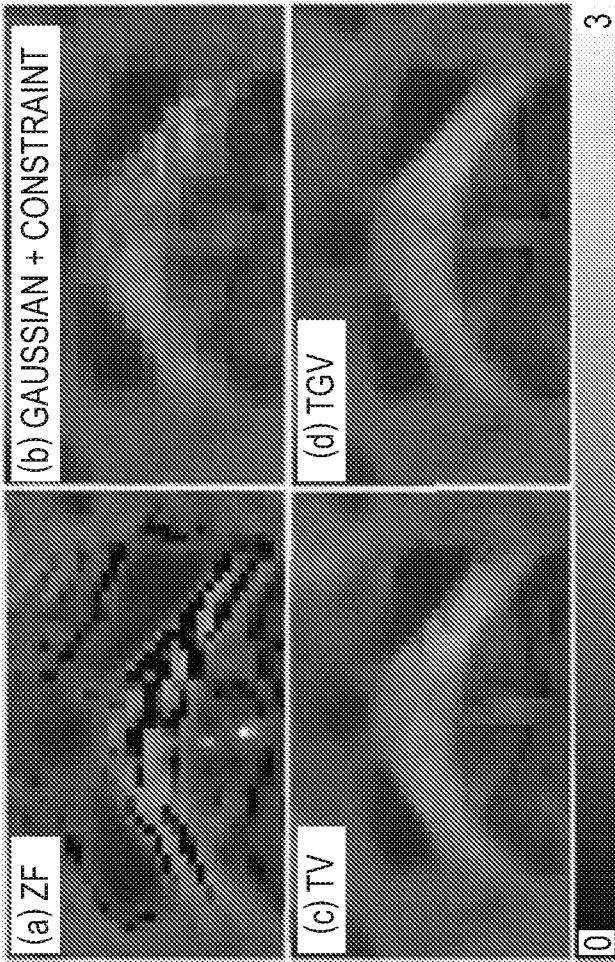


FIG. 4B

FIG. 4C

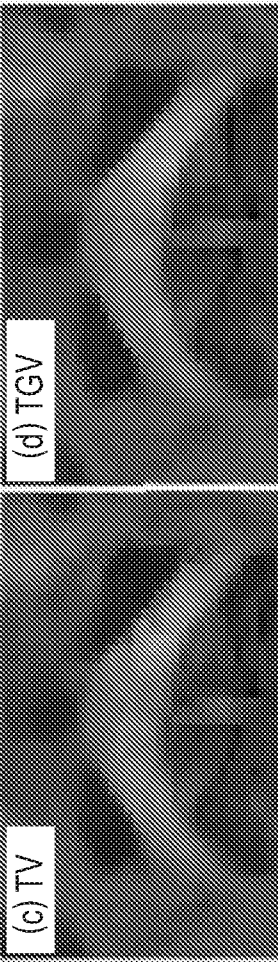


FIG. 4D

FIG. 5A

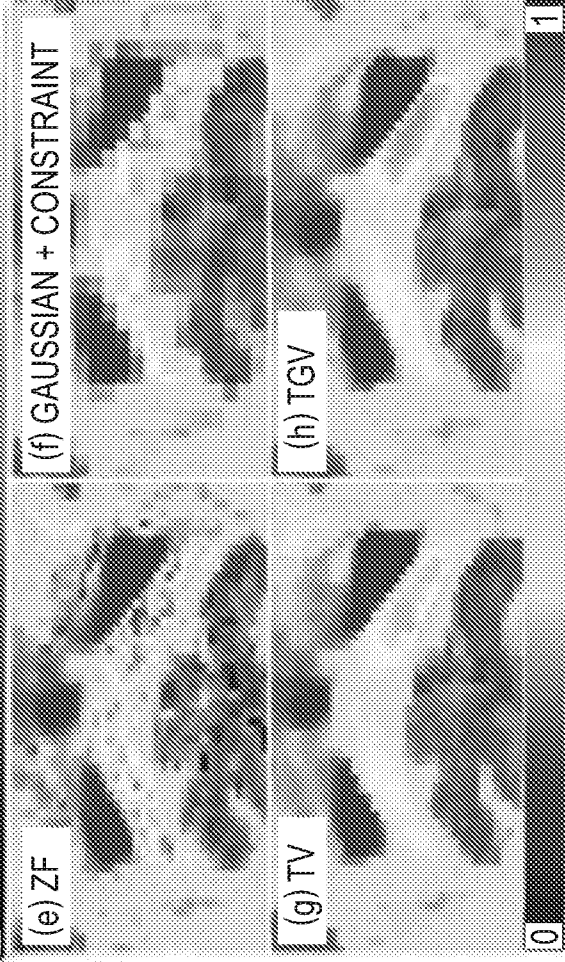


FIG. 5B

FIG. 5C

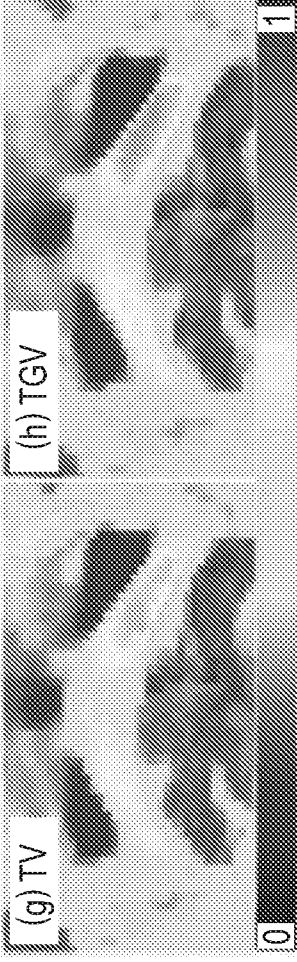


FIG. 5D

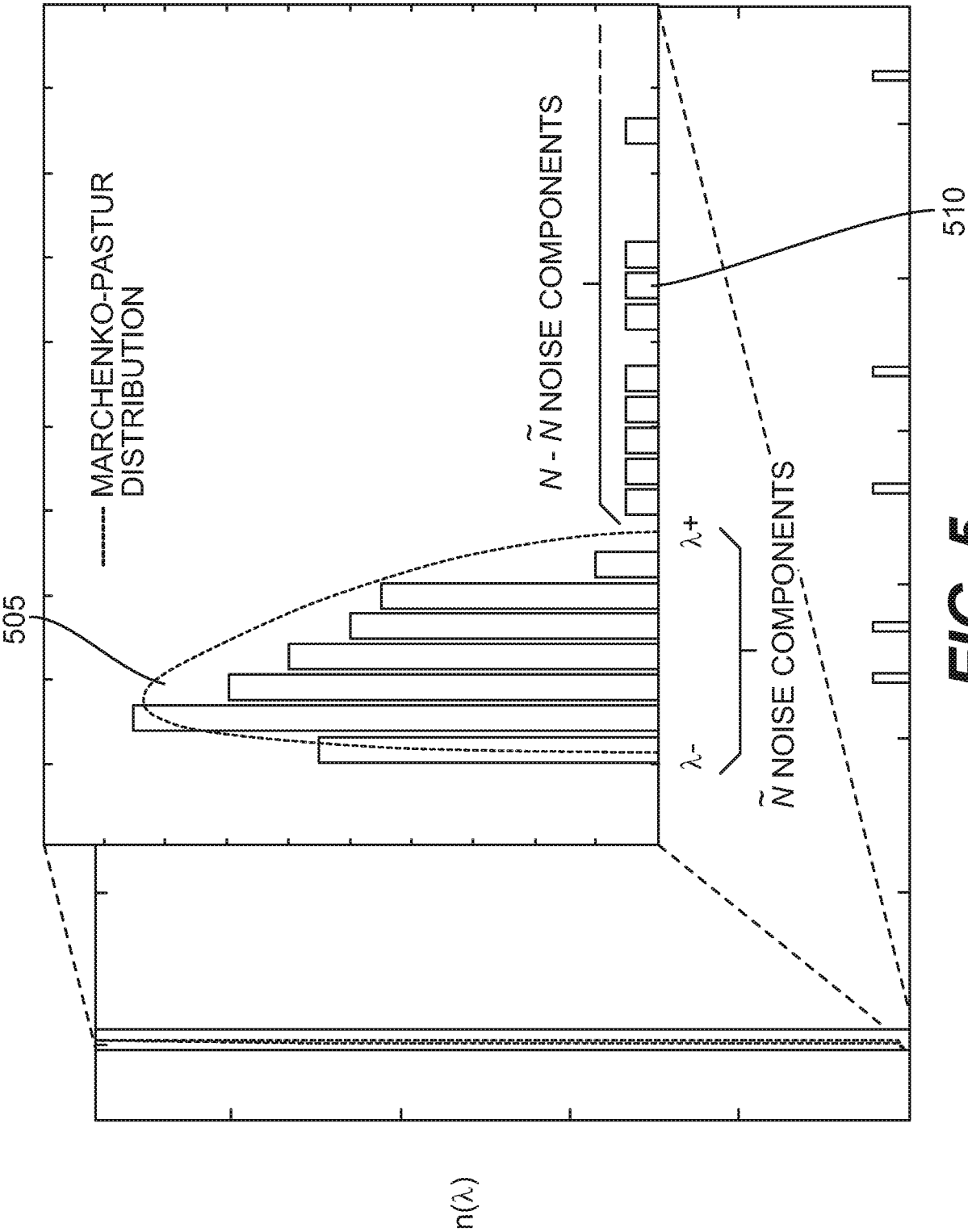


FIG. 5

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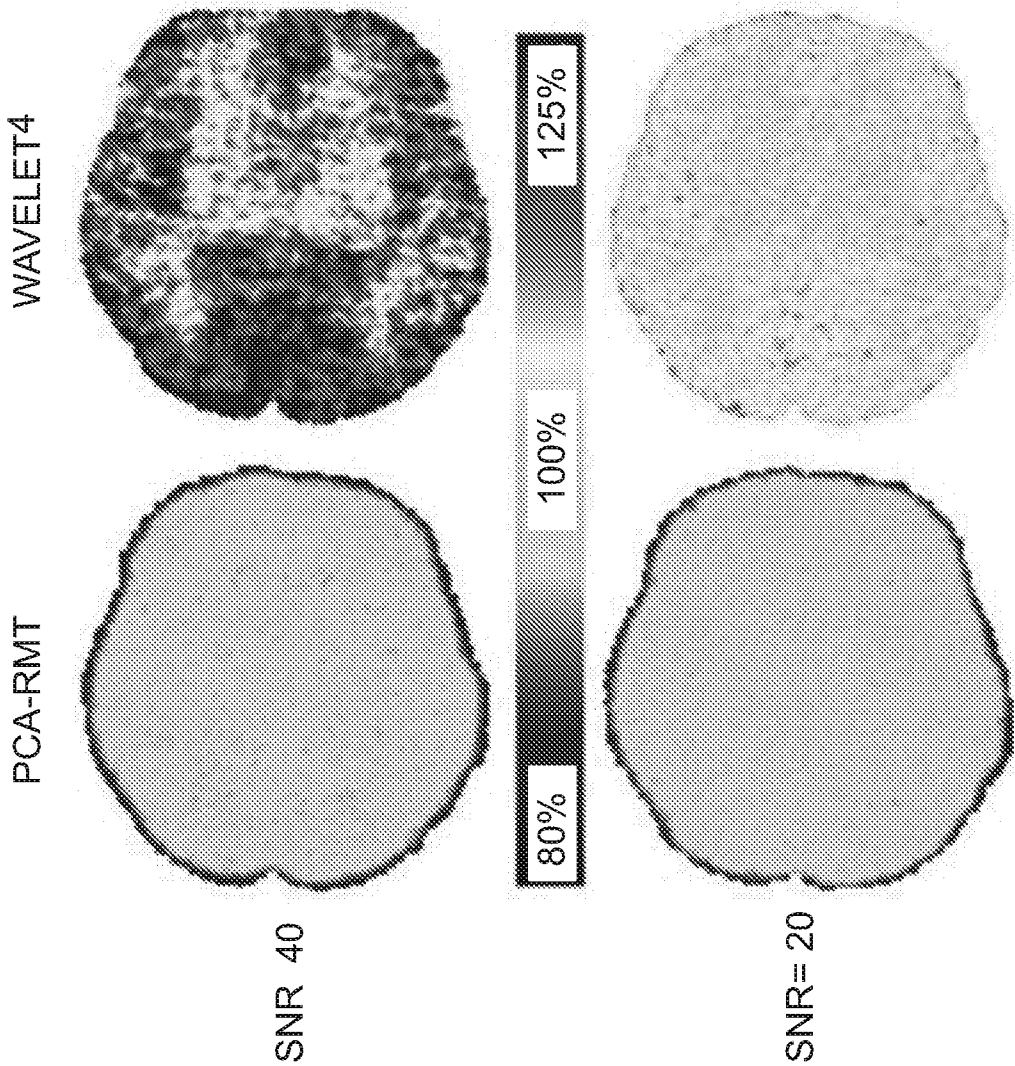
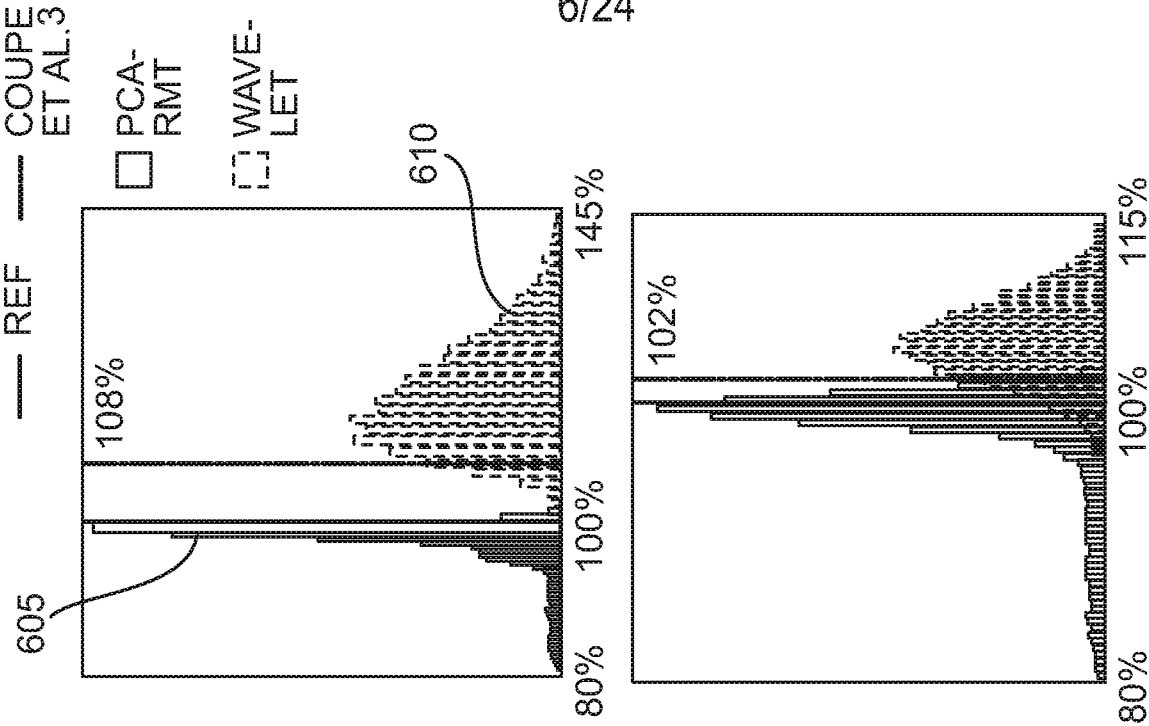
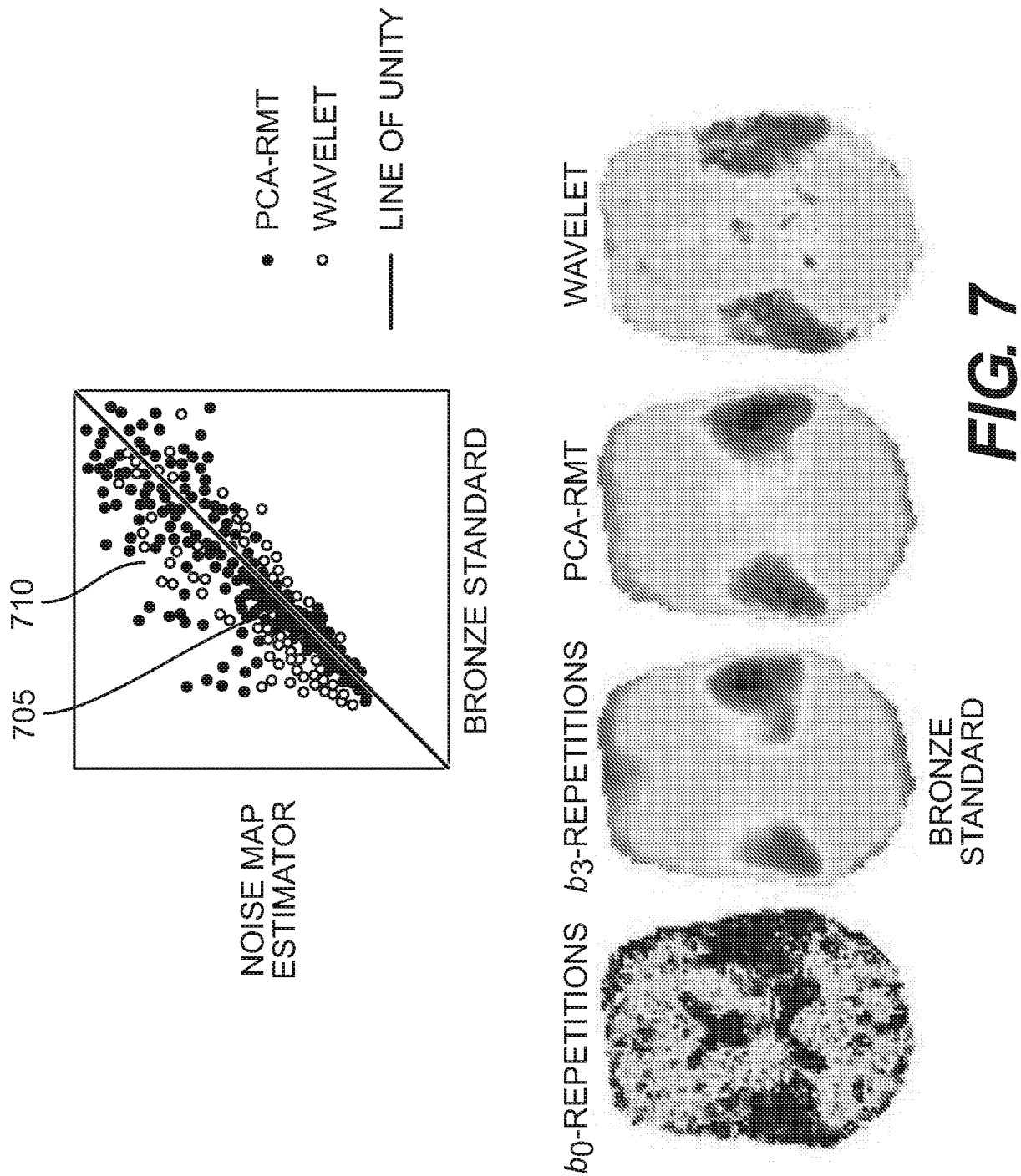
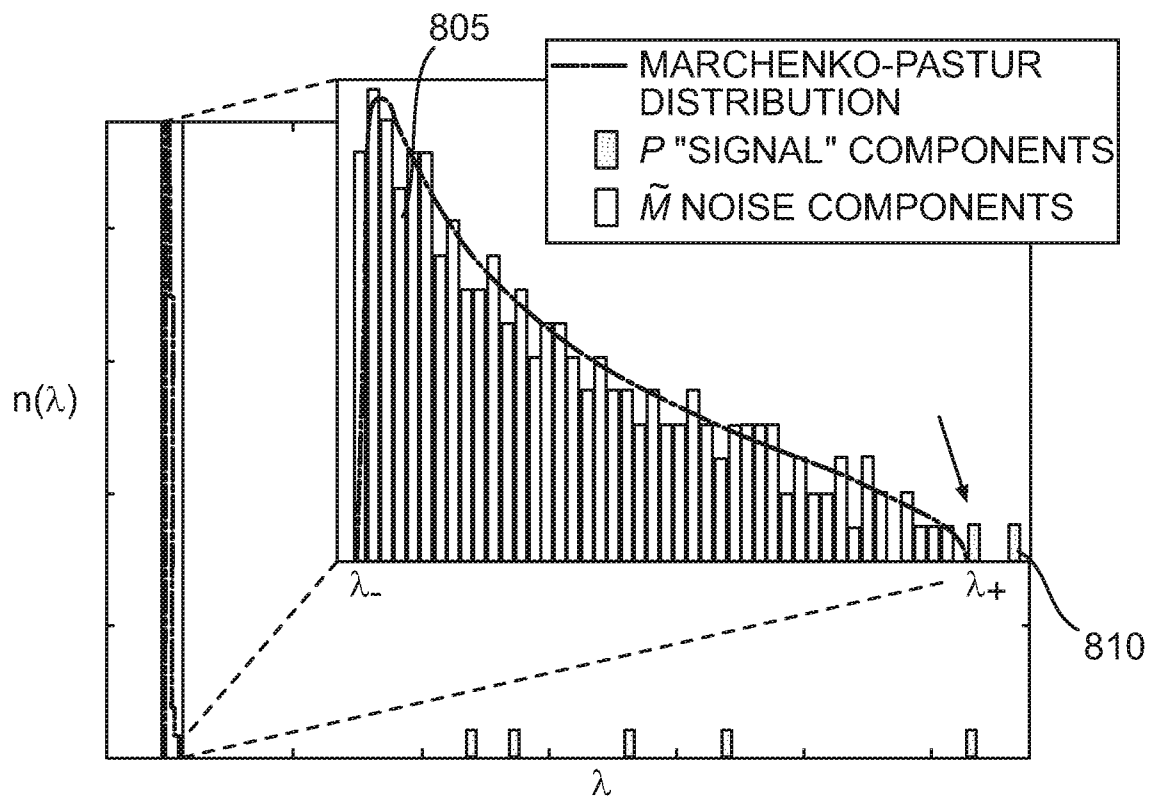
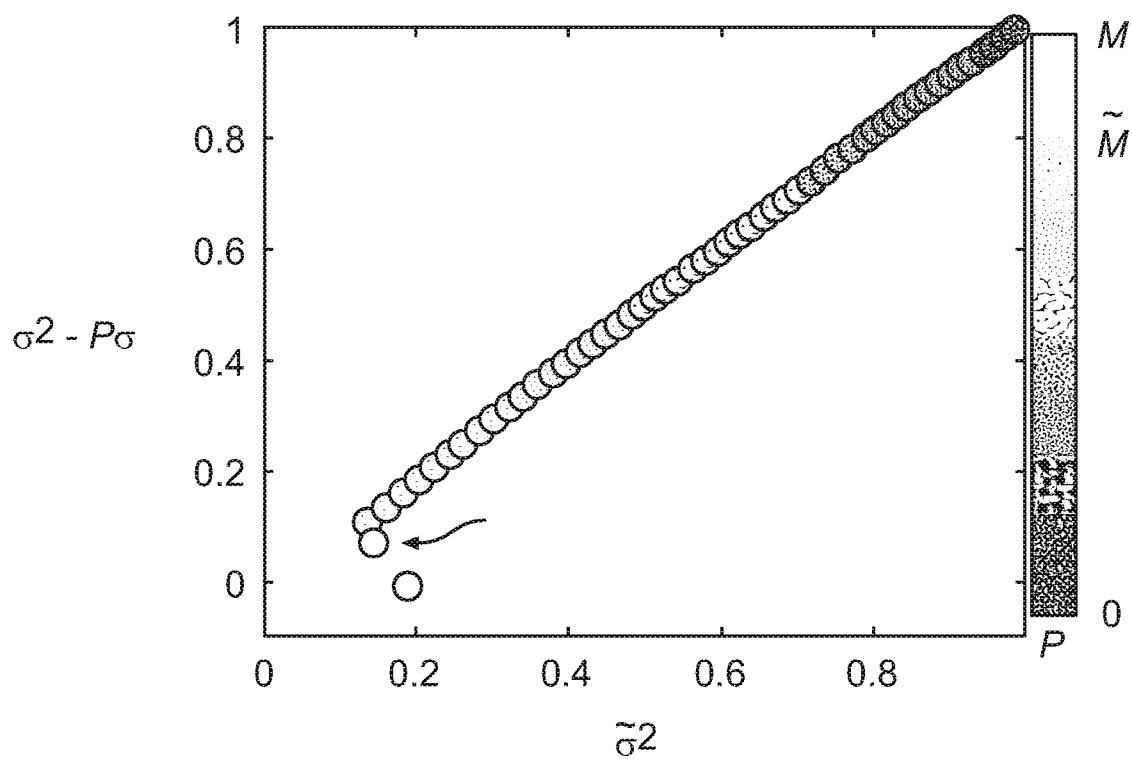


FIG. 6

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**FIG. 8A****FIG. 8B**

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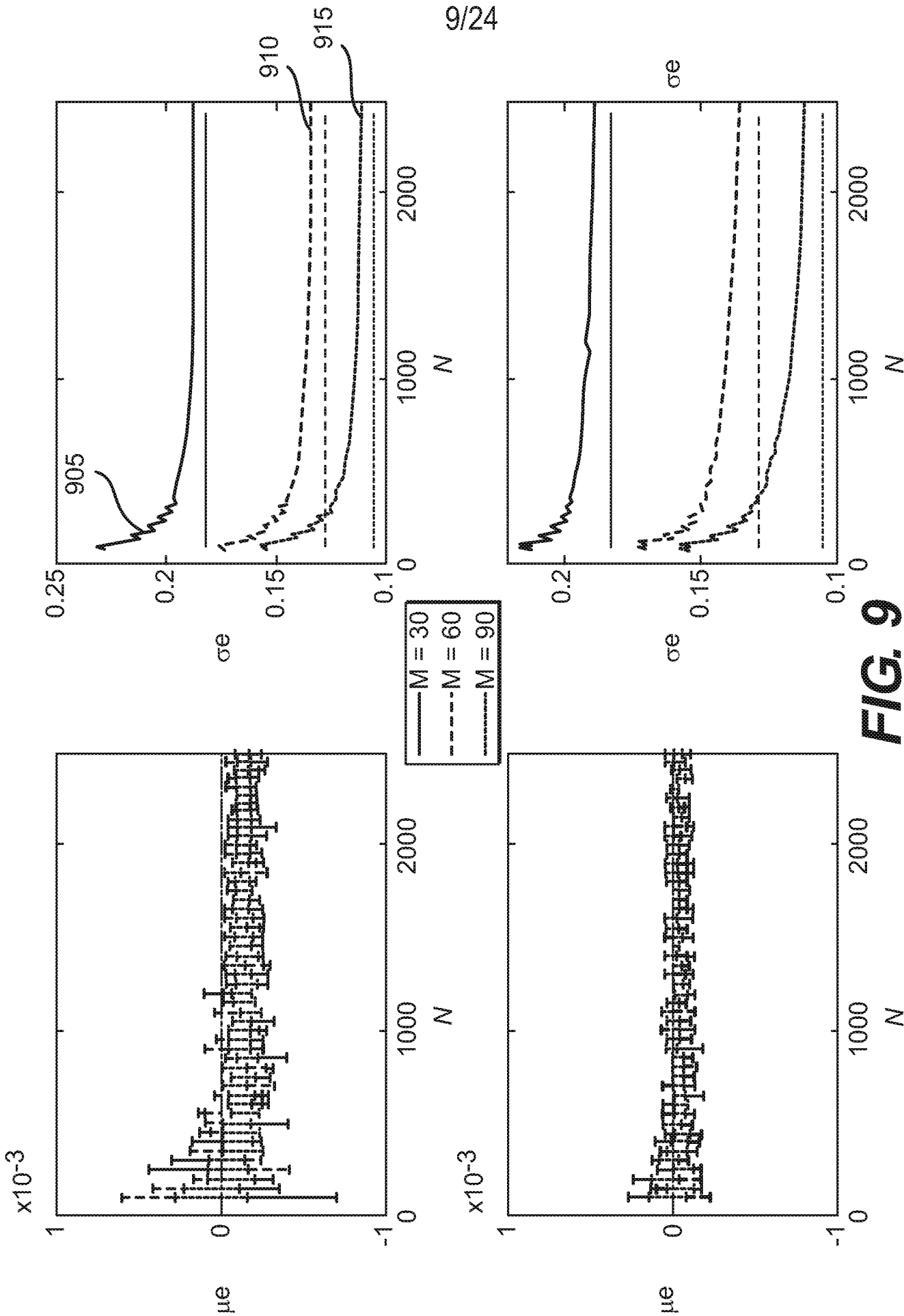
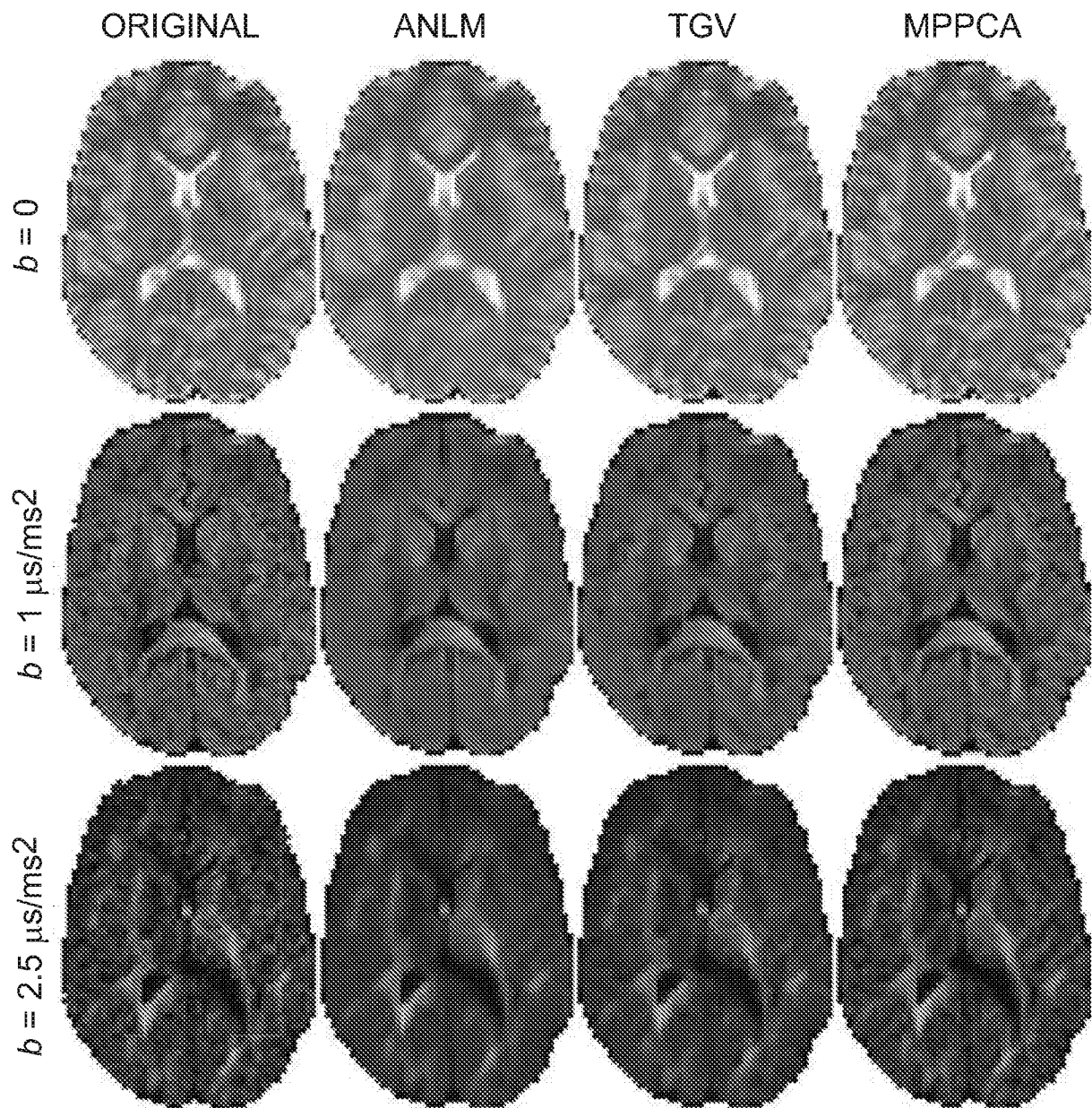
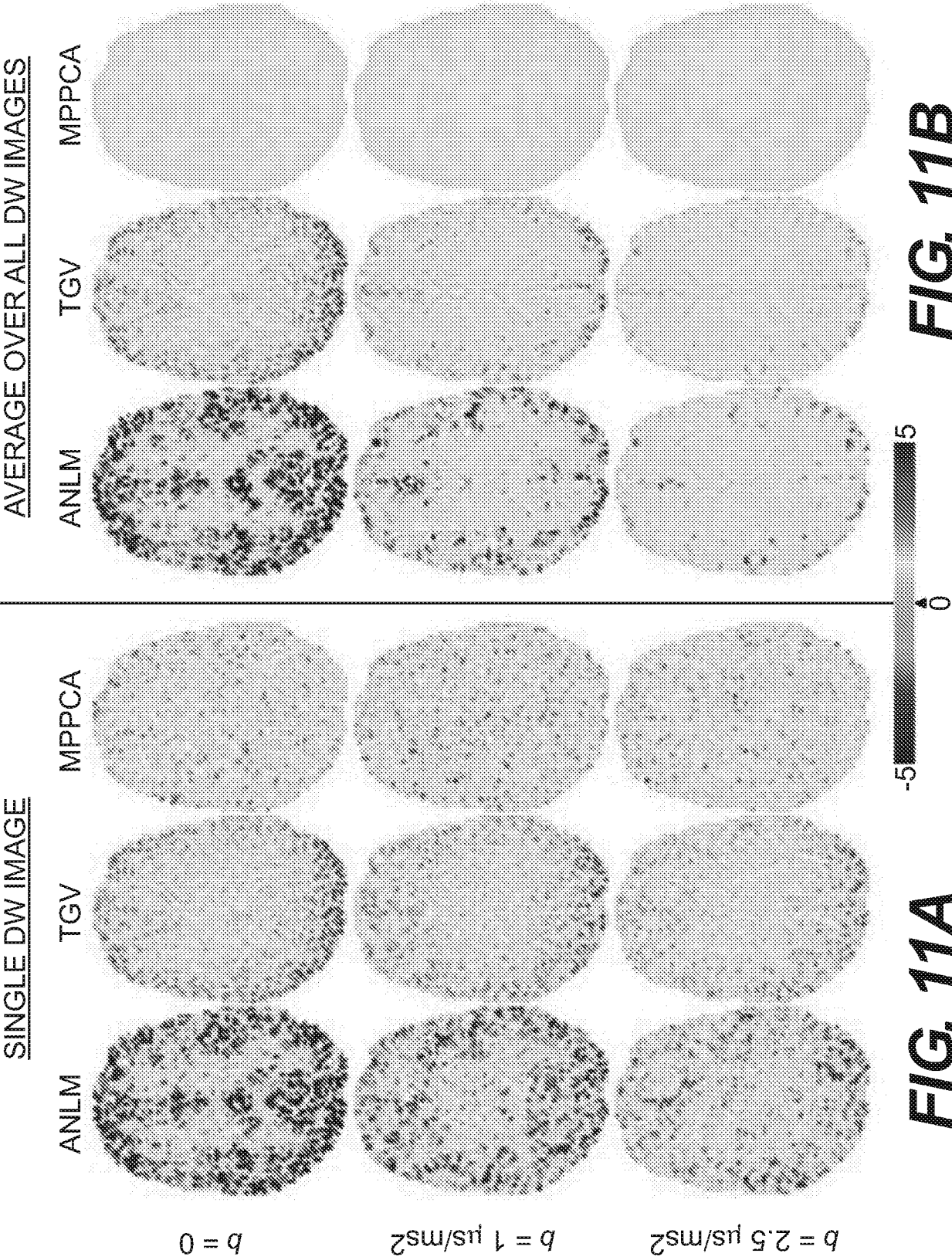


FIG. 9

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**FIG. 10**

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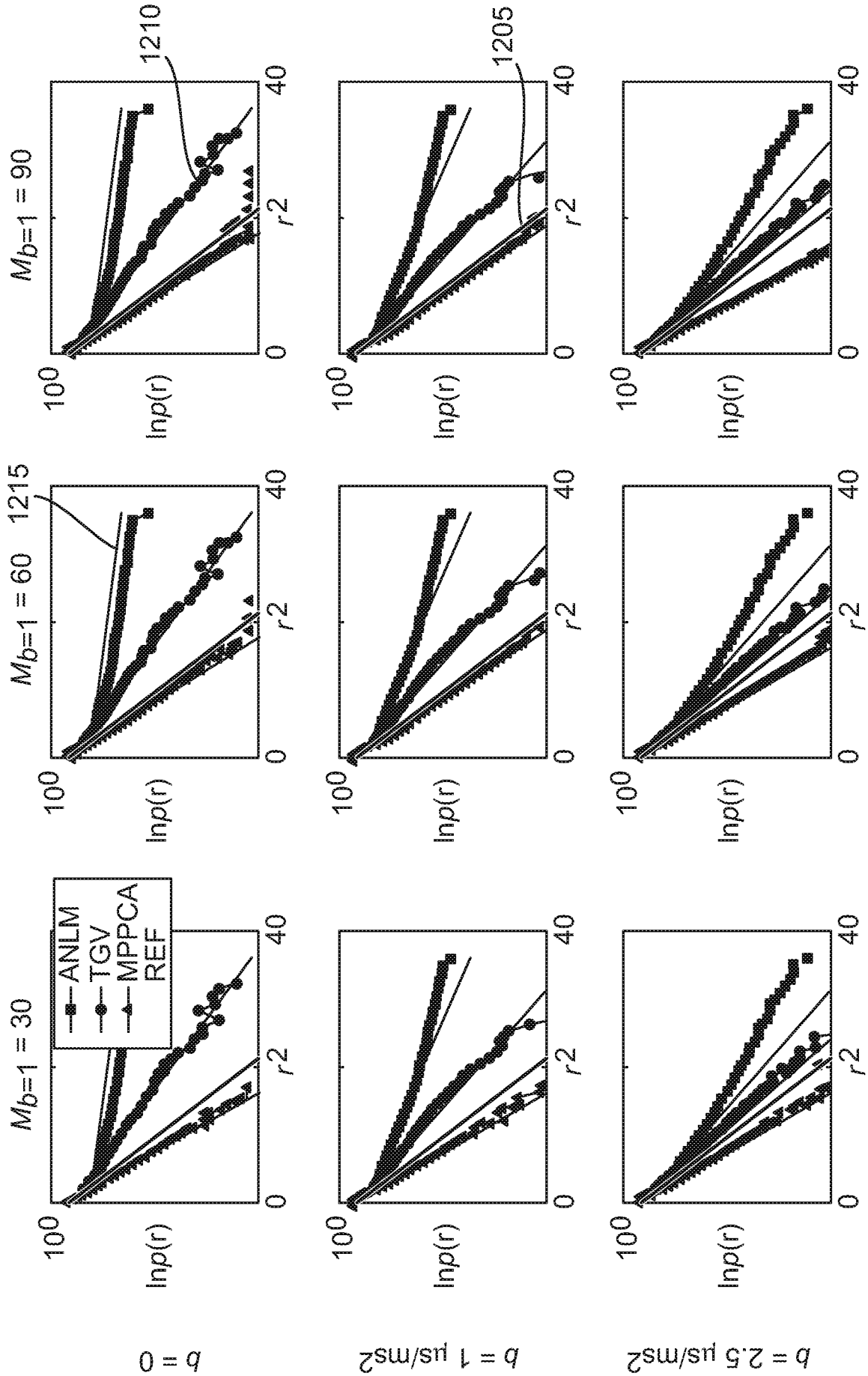


FIG. 12

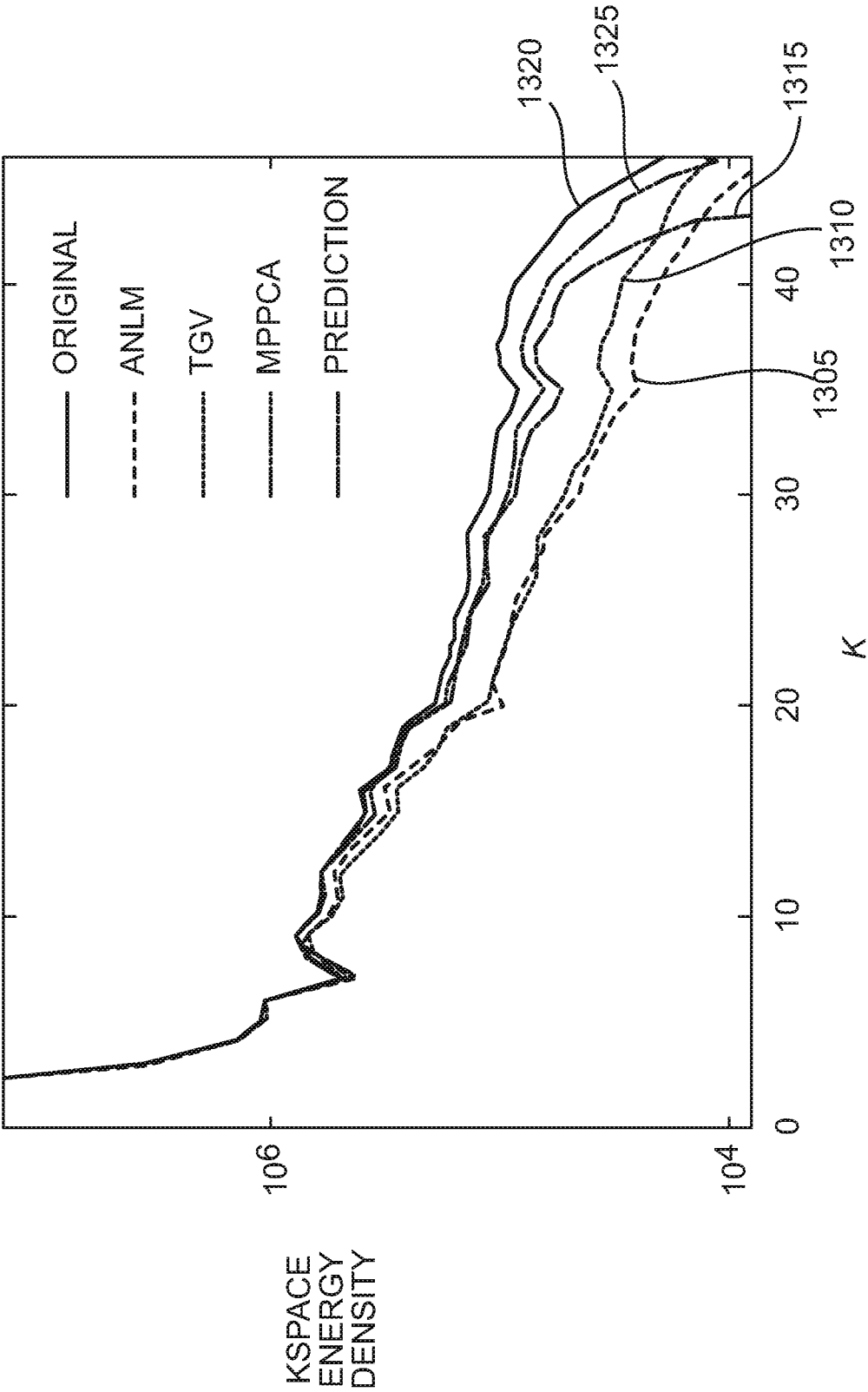
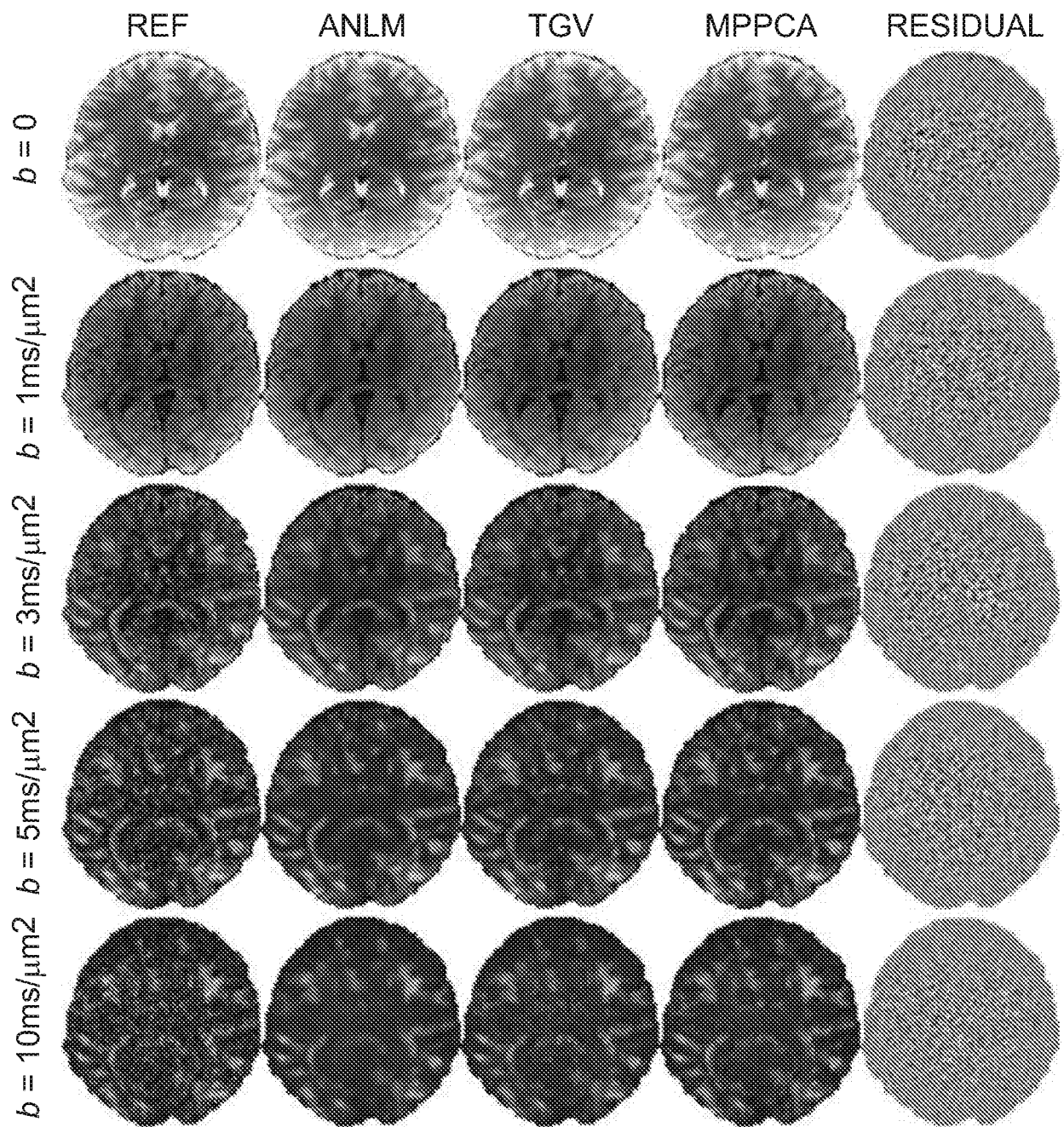
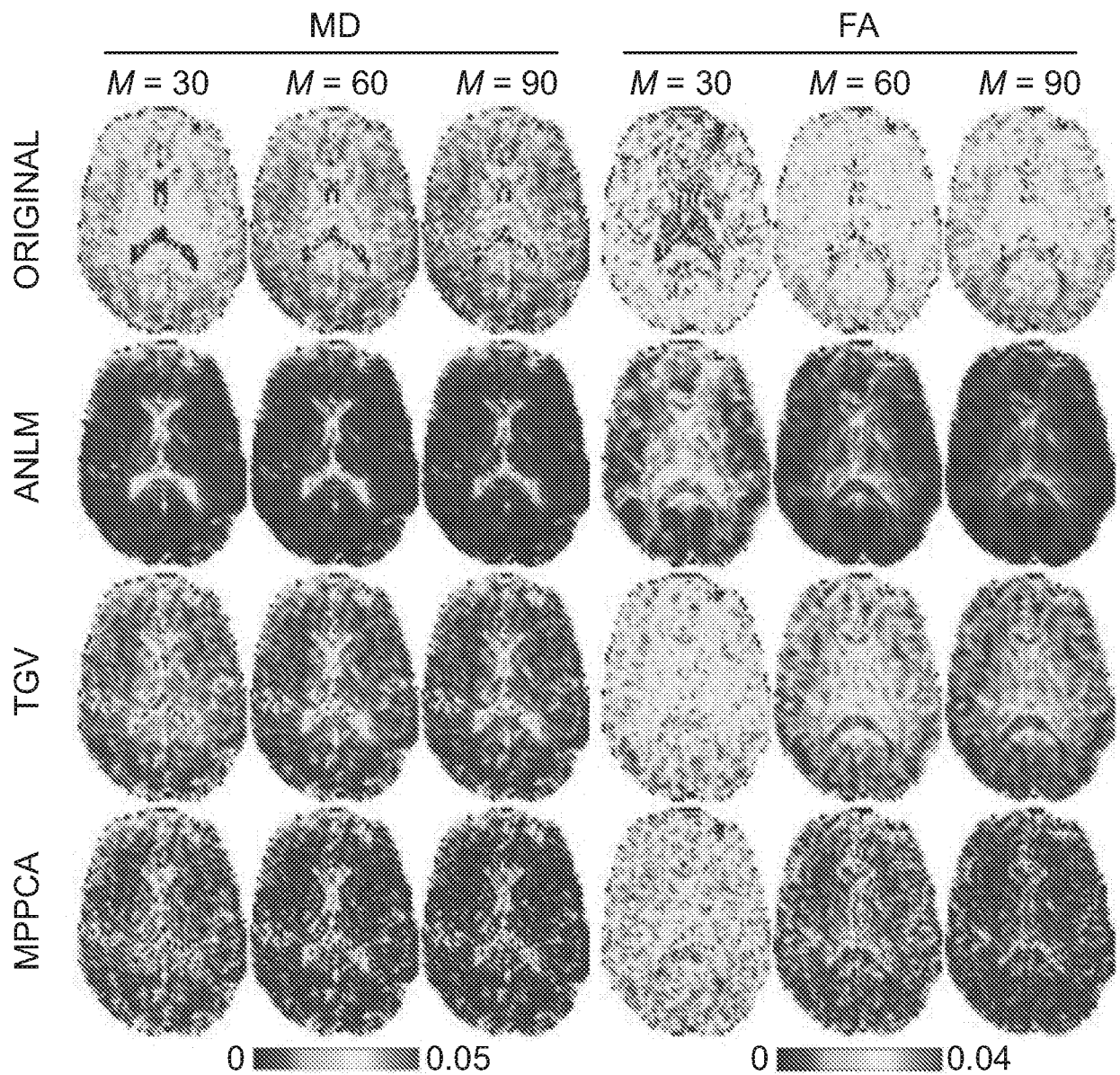


FIG. 13

**FIG. 14**

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**FIG. 15**

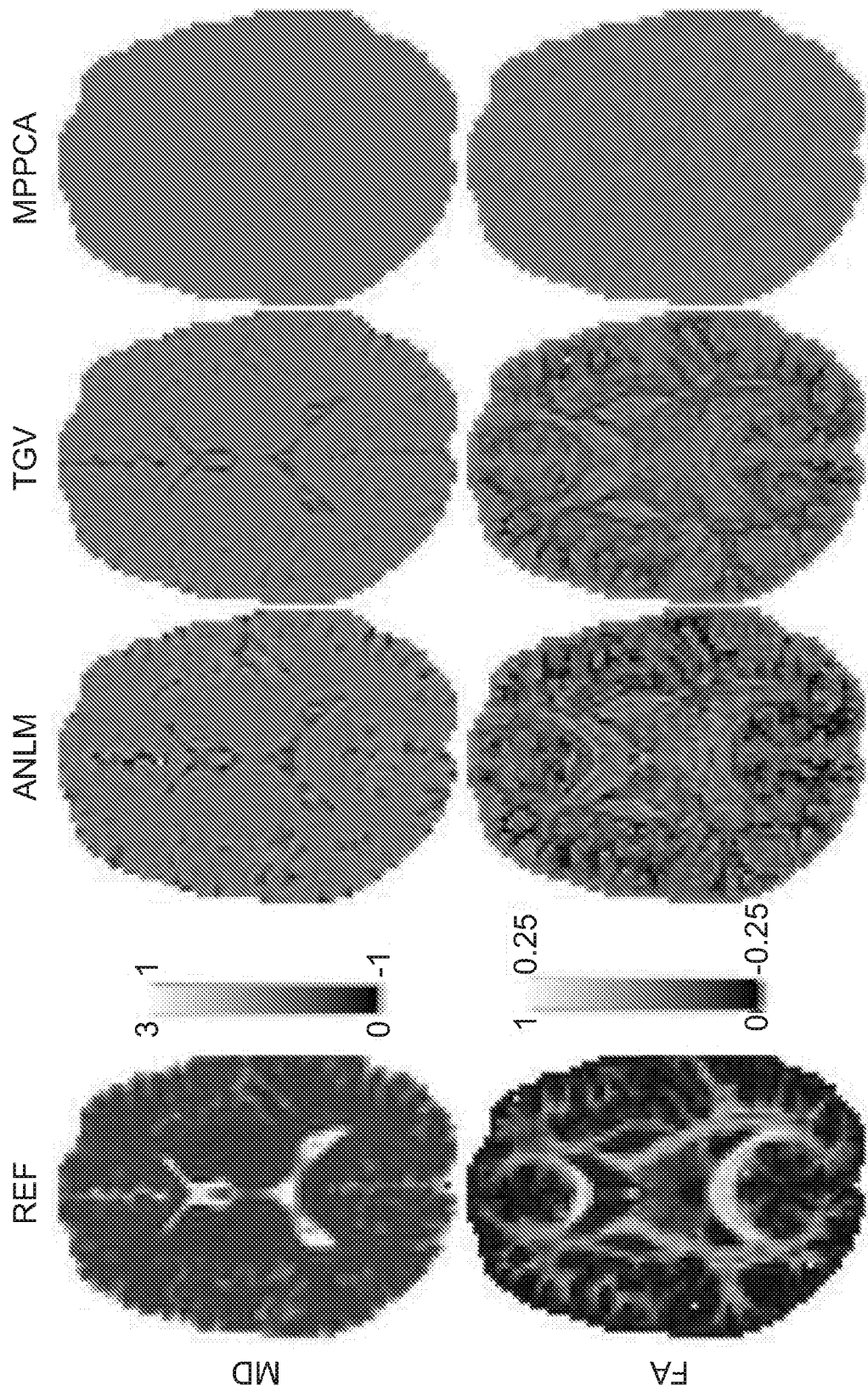


FIG. 16

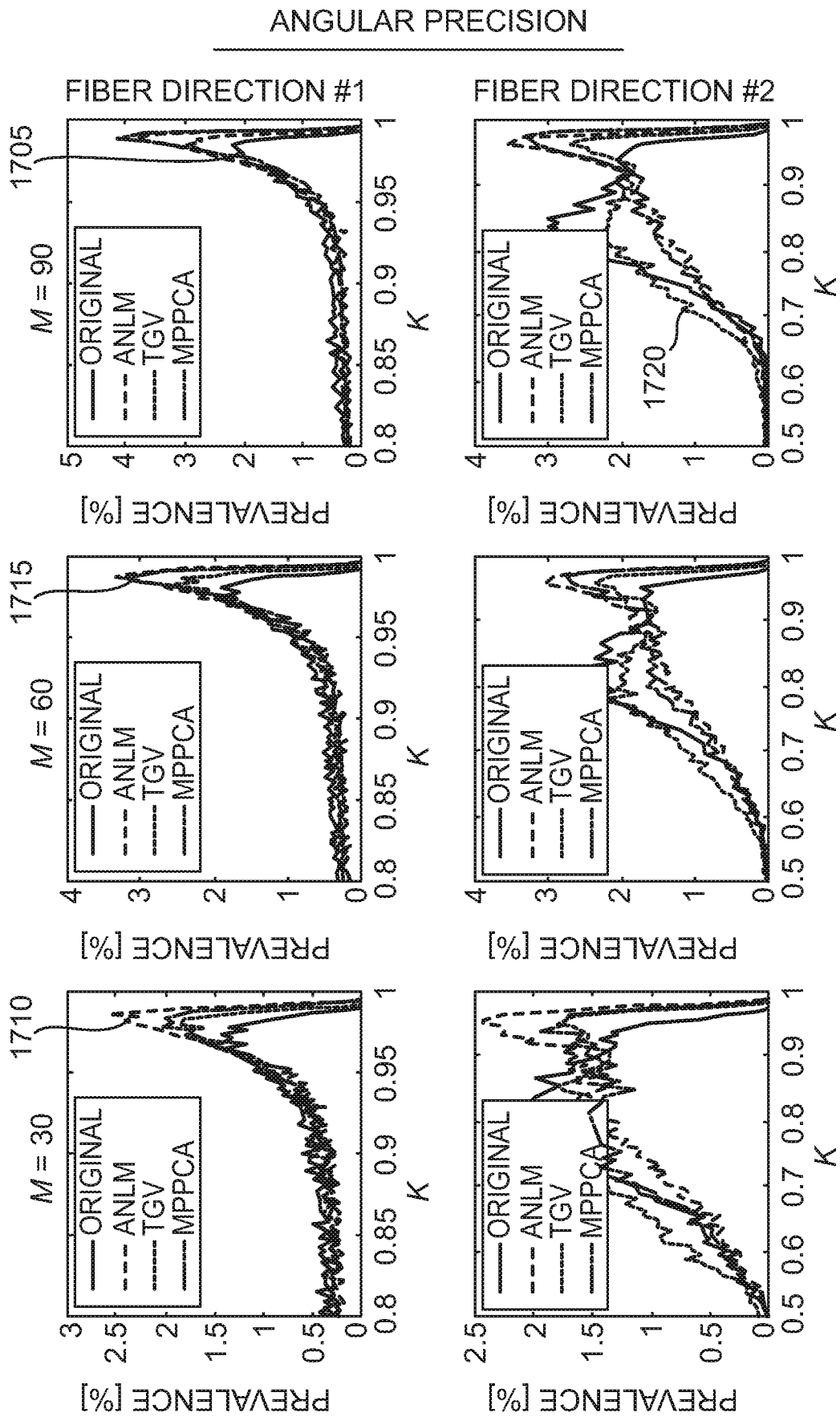
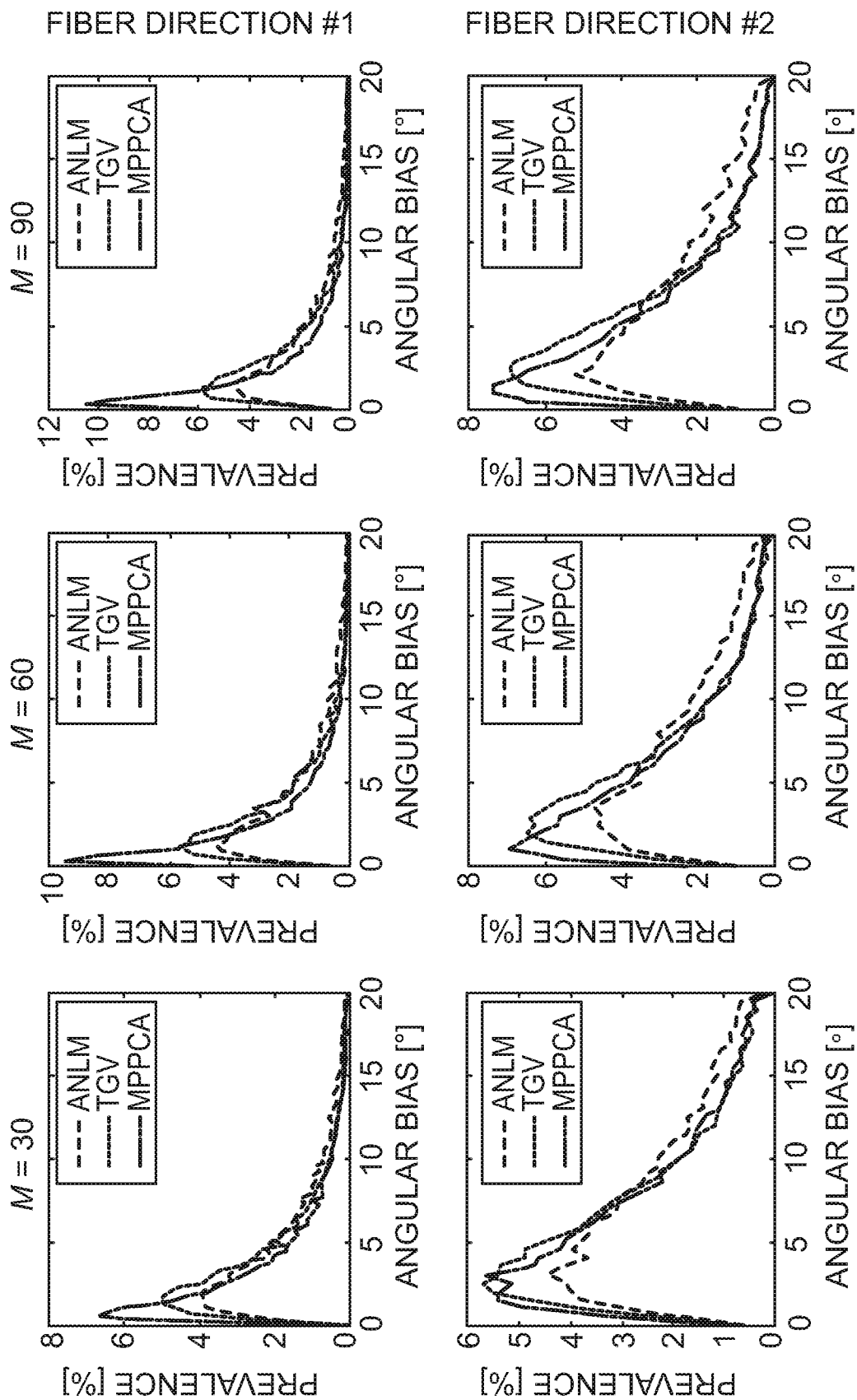


FIG. 17

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ANGULAR ACCURACY

**FIG. 17 CONT.**

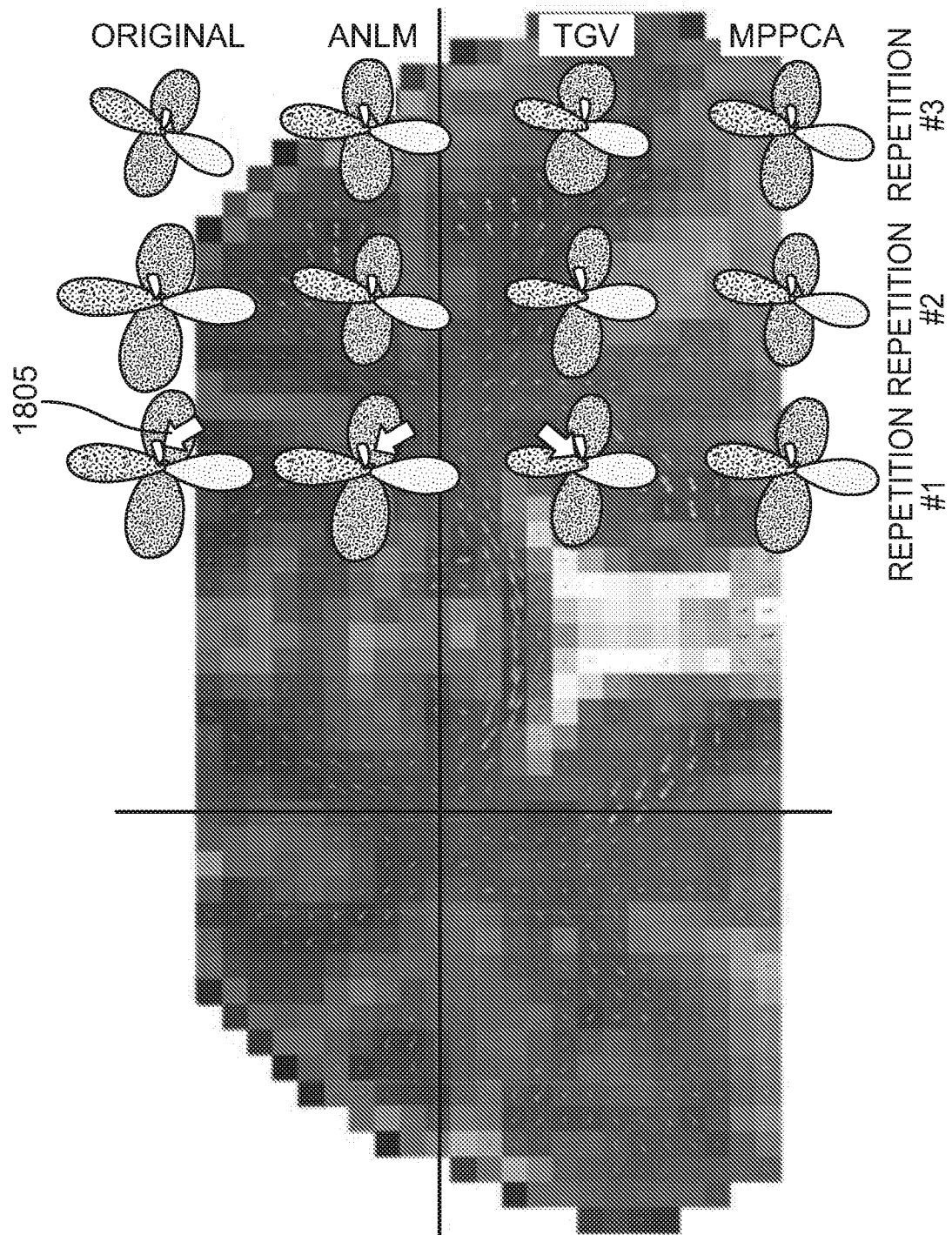


FIG. 18

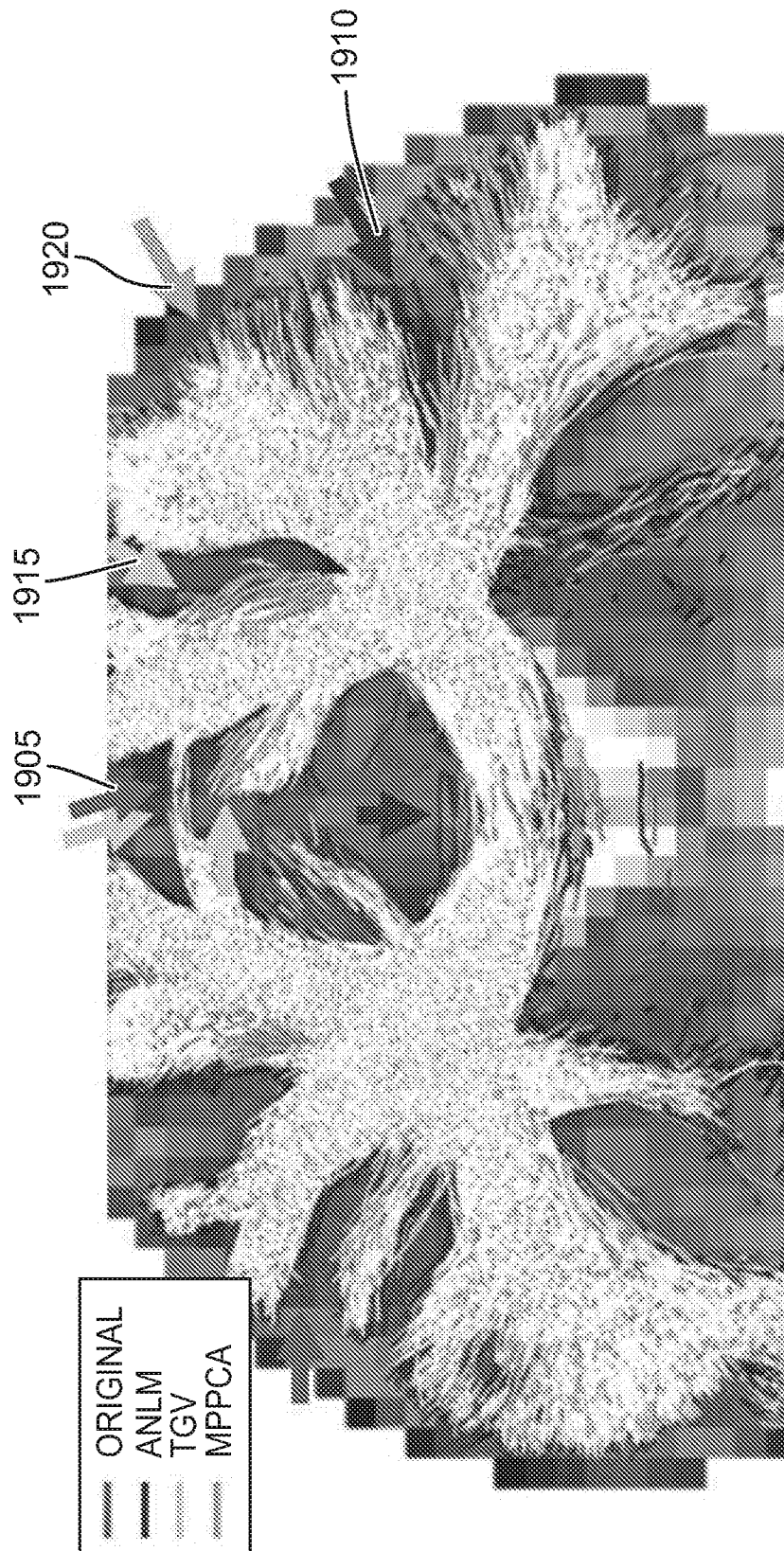
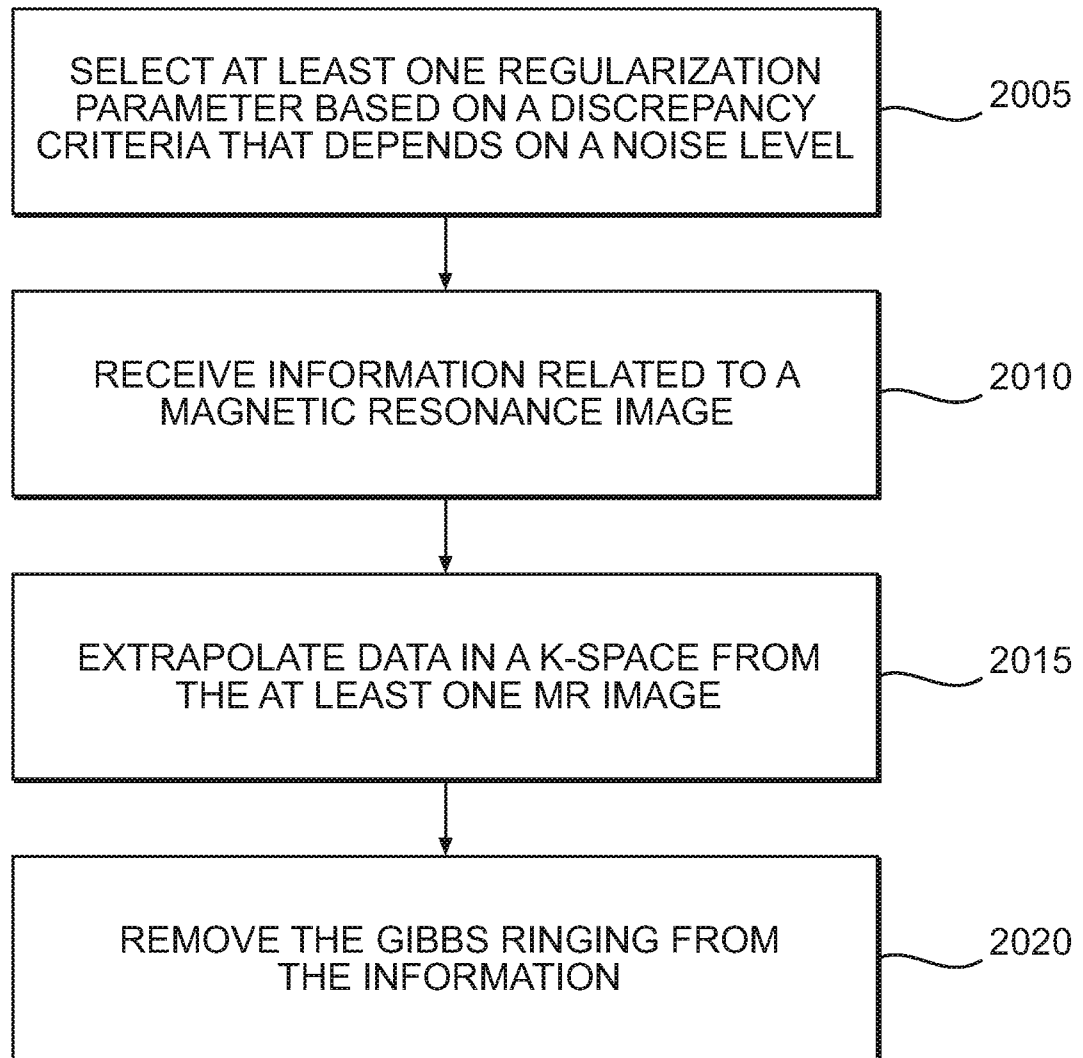
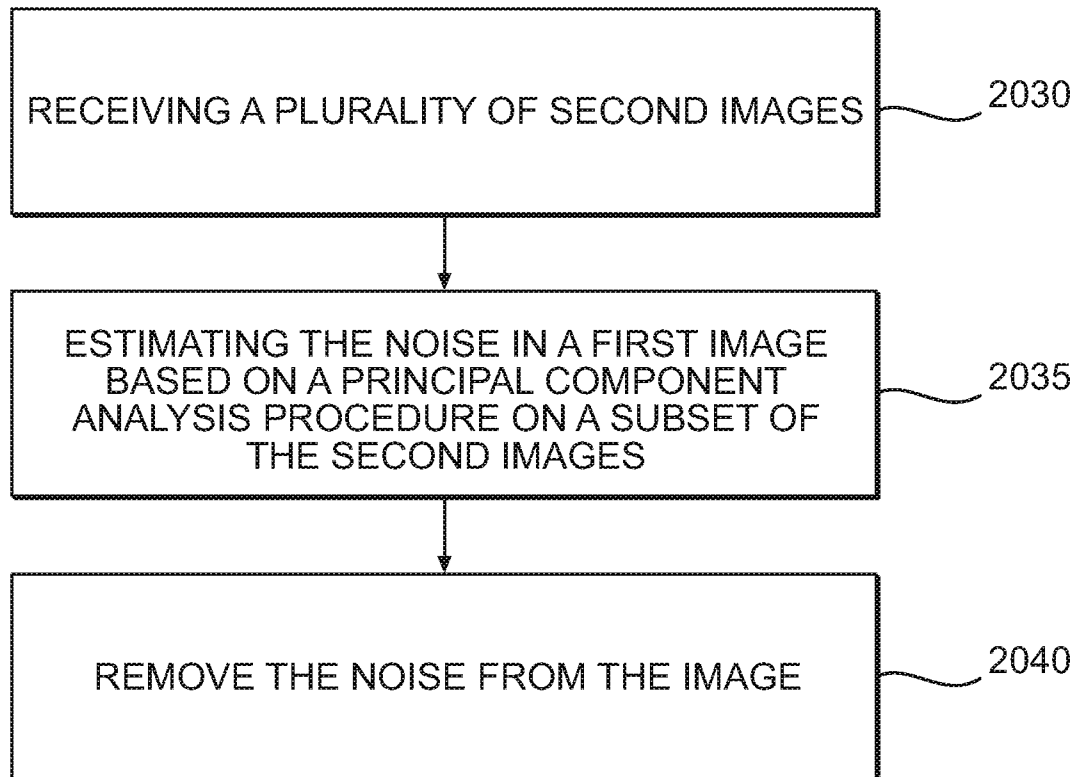
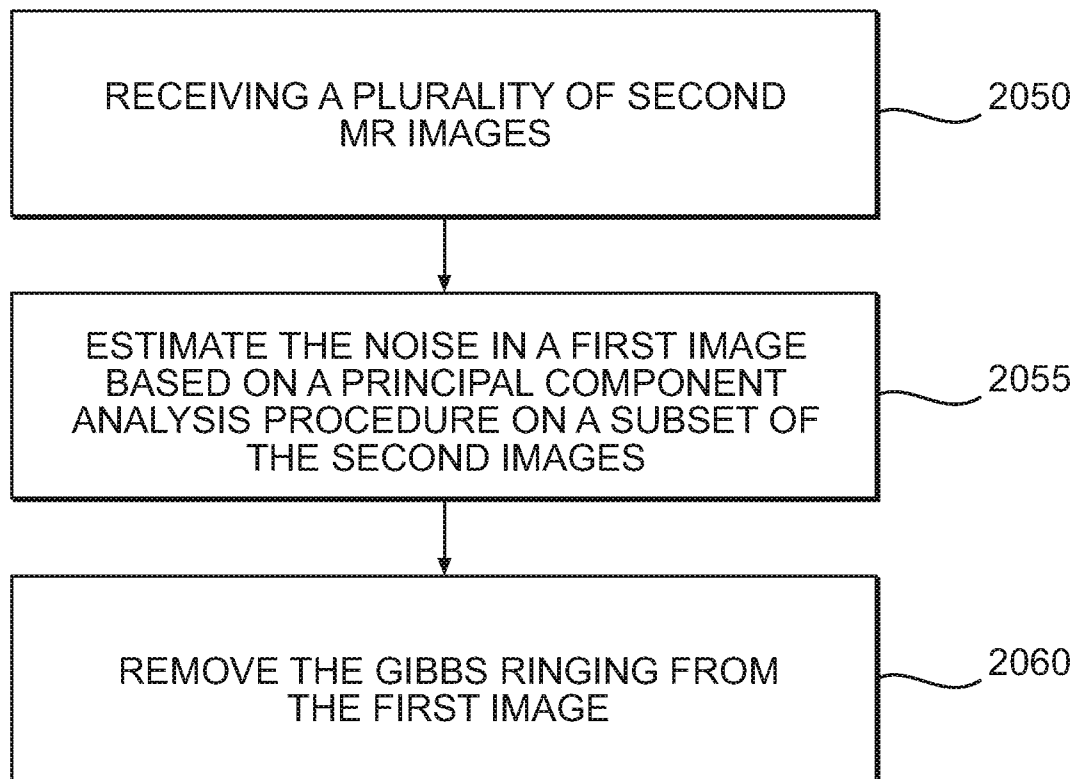
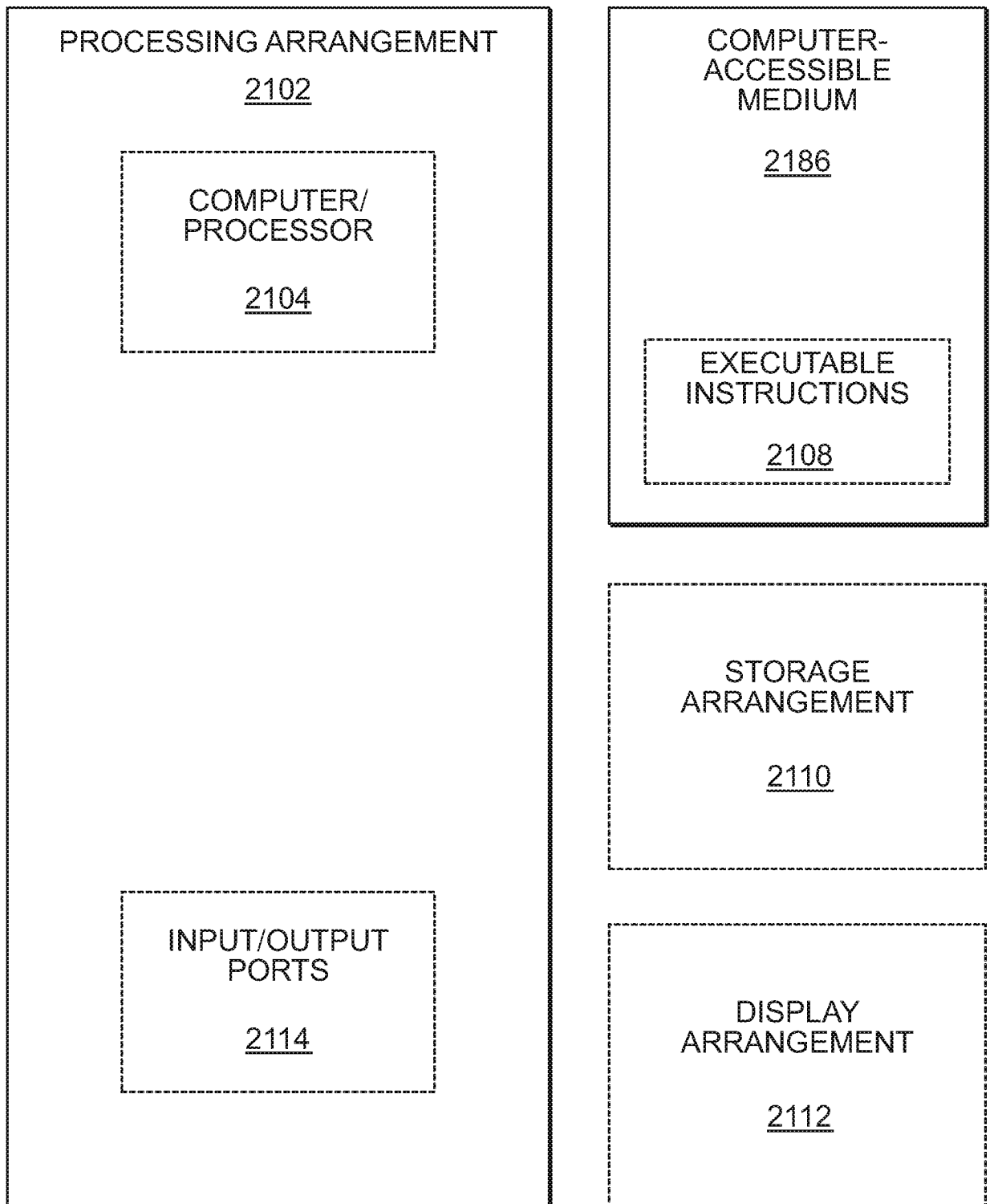


FIG. 19

2000**FIG. 20A**

2025***FIG. 20B***

2045**FIG. 20C**

**FIG. 21**

INTERNATIONAL SEARCH REPORT

International application No.

PCT/US2016/032761

A. CLASSIFICATION OF SUBJECT MATTER IPC(8) - G06K 9/40; A61B 5/055; G01R 33/56; G01R 33/565; G06T 5/10 (2016.01) CPC - G06T 5/002; A61B 5/055; G01R 33/56; G01R 33/565; G06T 2207/10088; G06T 2207/3000 (2016.05) According to International Patent Classification (IPC) or to both national classification and IPC		
B. FIELDS SEARCHED Minimum documentation searched (classification system followed by classification symbols) IPC - A61B 5/055; G01R 33/56; G01R 33/565; G06K 9/40; G06T 5/10 CPC - A61B 5/055; G01R 33/56; G01R 33/565; G01R 33/443; G01R 33/4818; G06K 9/40; G06T 5/10; G06T 2207/10088; G06T 2207/20056; G06T 2207/20192; G06T 2207/30004; G06T 5/002 Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched USPC - 382/254; 382/260; 382/275 (keyword delimited) Electronic data base consulted during the international search (name of data base and, where practicable, search terms used) Orbit, Google Patents, Google Scholar, Google, ProQuest. Search terms used: magnetic resonance imaging, noise, gibbs, pca, principal component, remove, estimate, extrapolate, computer.		
C. DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X --- Y	US 2012/0269414 A1 (ZHA et al) 25 October 2012 (25.10.2012) entire document	1-5, 8-12, 15-19 --- 6, 7, 13, 14, 20, 21, 58-60
X --- Y	US 2010/0260402 A1 (AXELSSON et al) 14 October 2010 (14.10.2010) entire document	22-26, 28-38, 40-50, 52-57 --- 27, 39, 51, 58-60
Y	Knoll et al. Second Order Total Generalized Variation (TGV) for MRI. 2010. [Retrieved on 2016-07-20]<URL:http://imsc.uni-graz.at/mobis/publications/SFB-Report-2010-023.pdf>	6, 7, 13, 14, 20, 21
Y	US 2009/0093709 A1 (PATEL et al) 09 April 2009 (09.04.2009) entire document	27, 30, 51
A	US 8,030,924 B2 (BITO et al) 04 October 2011 (04.10.2011) entire document	1-60
A	US 2014/0212015 A1 (THE OHIO STATE UNIVERSITY) 31 July 2014 (31.07.2014) entire document	1-60
A	US 2013/0096425 A1 (UUTELA et al) 18 April 2013 (18.04.2013) entire document	1-60
A	US 5,285,157 A (ZUR) 08 February 1994 (08.02.1994) entire document	1-60
☐ Further documents are listed in the continuation of Box C. ☐ See patent family annex.		
* Special categories of cited documents: "A" document defining the general state of the art which is not considered to be of particular relevance "E" earlier application or patent but published on or after the international filing date "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "O" document referring to an oral disclosure, use, exhibition or other means "P" document published prior to the international filing date but later than the priority date claimed "T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention "X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone "Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art "&" document member of the same patent family		
Date of the actual completion of the international search 21 July 2016		Date of mailing of the international search report 18 AUG 2016
Name and mailing address of the ISA/ Mail Stop PCT, Attn: ISA/US, Commissioner for Patents P.O. Box 1450, Alexandria, VA 22313-1450 Facsimile No. 571-273-8300		Authorized officer Blaine R. Copenheaver PCT Helpdesk: 571-272-4300 PCT OSP: 571-272-7774