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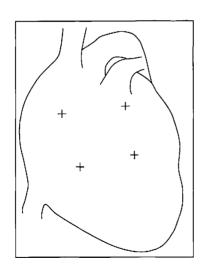
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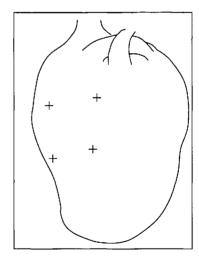
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(54) Title: SURGICAL NAVIGATION AND LOCALIZATION SYSTEM UTLIZING SCALE-INVARIANT REGISTRATION





(57) Abstract: A system for navigating a medical device through the lumens and cavities in an operating region in a subject, comprising an imaging system for displaying an image of the operating region, including a representation of the distal end of the medical device in the operating region. The system also includes a localization system for determining the position of the medical device in a frame of reference translatable to the displayed image. Finally, the system includes an algorithm for evaluating one or more rotation matrix using a cost function to determine an optimum rotation matrix for performing transformation of a vector in the local frame of the localization system to that of the reference frame of the navigation system. The rotation matrix can then provide a scale invariant transformation or "registration" of the coordinate systems of the localization system and the navigation system.. This allows navigation to be performed to a significant extent from the localization system display alone, which avoids the frequent x-ray irradiation that occurs during the use of fluoro imaging for navigation purposes.



# INTERNATIONAL SEARCH REPORT

International application No.

PCT/US05/30477

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Category *	Citation of document, with indication, where a	·····	Relevant to claim No.				
X	US 6,332,089 B1 (ACKER et al) 18 December 2001	(18.12.2001), see entire reference	1-9,17,23-30,32-42,44-				
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Y	Y US 6,774,624 B2 (ANDERSON et al) 10 August 2004 (10.08.2004), colu		10,13,31,43				
Y,P	US 2004/0176931 A1 (WRIGHT et al) 09 Septembe	r 2004 (09.09.2004), paragraphs 16 and	10-12,14-16,18-22				
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Further	documents are listed in the continuation of Box C.	See patent family annex.					
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