



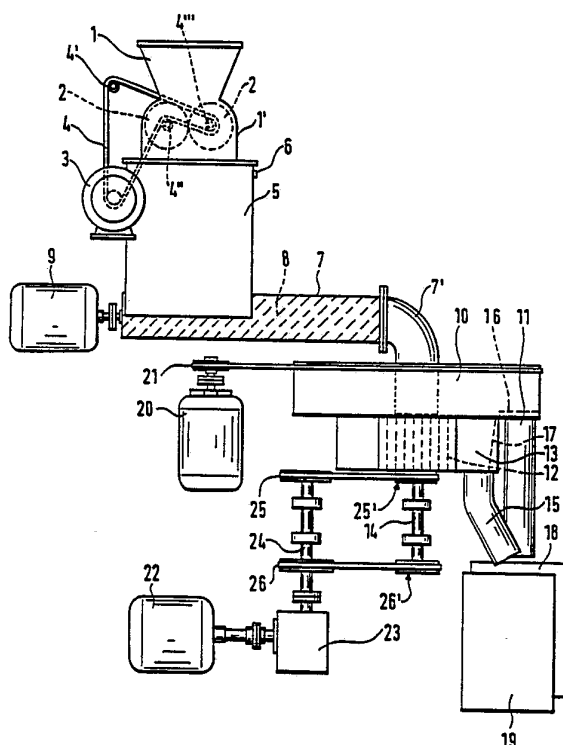
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(54) Title: A PROCESSING MACHINE FOR BOILED/COOKED CRAB

(57) Abstract

A processing machine particularly for boiled/cooked crab comprising a shell crusher means (2) and a subsequent separation means in which the crab meat is separated from the shell fragments. The separation means of the machine is novel in that it embraces a plurality of upright, spinning, screw-threaded spindles (12). These spindles are arranged in a circle in a spinning meat collection tray (13) for crab meat with just sufficient clearance between adjacent spindles that the crab medium which is discharged into the circular space defined by the said spindles (12) in the said spinning meat collection tray (13) is pressed, by centrifugal force, out against the said spindles (12), where it can pass between the adjacent spindles (12) aforesaid, while almost the entire bulk of hard shell fragments are prevented from passing between the said spindles (12). The gradient of the screw thread of the spindles and their direction of rotation combine to drive the shell fragments upward and into an overlying shell collection tray (10), while the crab meat makes its way to the outer portion of the said rotary meat collection tray (13) confining the ring of spindles (12) aforesaid.



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A PROCESSING MACHINE FOR BOILED/COOKED CRAB

BACKGROUND OF THE INVENTION1) Field of the invention

This invention relates to a processing machine for boiled/cooked crab, comprising a shell crusher means and a post-crusher separation means in which
5 the crab meat is separated from the shell fragments.

2) Description of the prior art

A number of crab processing and similar machines are known in the art for the manufacture of a refined product comprising crab meat or similar meat, for example meat of lobster or other crustacean.

10 One crab processing machine known in the art utilises a separation operation based on centrifugal techniques. This machine comprises a centrifuge the design of which is only intended to separate/cleanse the carapace (or "main body") of the shell. However, since separation is desirable, not only of the carapace, but also the major appendages (claws) and minor appendages (legs)
15 in one and the same separation operation, this known machine is clearly of limited application. Its processing capacity is also small, and the operation of the machine requires considerable manual effort.

Another crab processing machine known in the art utilises water jets by which to separate the crab meat from the shell fragments. The water consump-

tion of this machine is so great that the aromatic components of the crab meat are diluted by the rinse water and may even dissolve in it. After going through this separation operation the crab has therefore lost such a considerable portion of its natural and characteristic aroma and taste that a special crab concentrate
5 must be added, a step which generally impairs the meat's quality - including its taste quality - as the crab meat after addition of the concentrate has a "watery" or bland taste. This known machine, too, is dependent for its operation on considerable manual labour since it takes several persons to work it.

From US-PS 3.266.542 is known a machine which is designed to separate
10 fragments of bone, cartilage and sinew from finely ground meat. This known machine with its relatively complex design is set up for the processing of very finely ground meat of fowl, domestic animals or fish, and imparts an even finer grinding to the meat during processing. This additional fine-grinding operation is undesirable in the case of crab meat. Also, this known machine is far too
15 complicated for application to the present purpose.

US-PS 3.266.543 discloses a machine which structurally and functionally differs only in minor details from the machine disclosed in US-PS 3.266.542.

OBJECTIVE OF THE INVENTION

The objective of the present invention is to overcome the drawbacks of
20 the known art and thereby provide a processing machine for the stated purpose which leaves the crab meat with its taste and aroma components intact after the processing operation, being a machine having large capacity relative to its size and space requirements, and for which the requirement for human intervention is generally limited to the feeding of the machine with boiled crab in the form
25 of claws, minor appendages and "body shell/carapace". The separation operation must in addition be so effective that the crab meat subsequent to processing is completely or substantially uncontaminated by shell fragments.

This objective is realised in the processing machine of the design and arrangement of the claim hereinafter stated.

BRIEF DESCRIPTION OF THE DRAWINGS AND THE PREFERRED EMBODIMENTS

5 In one preferred embodiment of the crab processing machine considered below, which serves to illustrate the invention without being intended to limit its scope, reference is made to the figures enclosed, in which:

Figure 1 is a side elevation with cut-away views showing the crab processing machine complete, while;

10 Figure 2 shows in larger scale the separation means of the processing machine separately, again in a side view.

The crab processing machine depicted in the drawings comprises a feed hopper 1, which is supplied - for example from a conveyor belt (not shown) - with boiled crab in the form of claws, minor appendages and carapaces. At the
15 bottom of the feed hopper 1 is a widened portion 1' in which two co-operating crushing rollers 2 are provided. Serving to drive the crushing rollers 2 in opposite directions is a first drive motor 3, preferably electrically powered, which turns the crushing rollers 2 by means of a chain drive comprising chain 4 and sprockets 4', 4'' and 4'''.

20 DETAILED DESCRIPTION OF THE DRAWINGS AND THE PREFERRED EMBODIMENTS

Once the crab medium has passed through the shell crusher 2 it emerges into the underlying container 5. Near the top of this container 5 is provided a photoelectric cell 6 the purpose of which is to give a signal whenever the
25 container is becoming too full. This undesirable circumstance might result if feed rate were too great relative to the separation capacity of the machine. Once the container 5 fills to the level guarded by the photoelectric cell 6, the photo-

electric cell signals - through a transmission path, not shown - for the rotation of the crushing rollers to cease. This level regulation system is so arranged that the crushing rollers 2 are again set in rotation once the level in the container 5 has subsided to below the level guarded by the photoelectric cell 6.

5 Connected to the bottom of the container 5 is a horizontal pipe 7 in which is installed a transport auger (feed screw) 8 which is driven round by means of a second electric motor 9. This transport auger 8 has a dual purpose; firstly the purely transportive purpose of implementing the feed operation into the machine's separation means, secondly an aeration function by which the crab
10 medium is aerated or broken up, reducing the adhesion of the crab meat to the shell fragments. As a result the separation means is supplied with crab medium of lighter (airier) consistency, thereby serving to facilitate the subsequent special separation process of the invention.

 The transport pipe 7 is furnished at its outward end with a pipe bend 7'
15 which extends through the center of a spinning shell collection tray 10 for shell fragments and waste. This shell collection tray 10 is furnished with a peripherally located discharge pipe 11. The pipe bend 7' empties just above the separation means.

 The separation means comprises a plurality of spinning, screw-threaded
20 spindles 12 which, in the exemplary embodiment considered herein are vertically oriented, but which in alternative embodiments can be oriented at an angle to the vertical having a steep slope. These spindles 12, being a plurality - say sixteen - of spindles, are deployed in a ring in the spinning meat collection tray 13. The bearings and drive particulars of a single such spindle 12 are shown in
25 detail in Figure 2, described later. Note for now that the spindles 12 are driven by the underlying main shaft 14 which can rotate at a speed of, say, 1800

revolutions a minute; causing each spindle to rotate at, say, 700 revolutions a minute.

As the crab medium drops into the generally round space defined by the spindles 12 in the meat collection tray 13, the medium is flung radially outward
5 against the spindles 12 by the spinning of the meat collection tray 13. The spindles are deployed with a mutual separation distance (to be determined by experiment) which permits only the pliant crab meat to pass through the space between adjacent spindles. The crab shell fragments on the other hand are too big, and furthermore also too hard, to be squeezed and passed between the
10 spindles. The screw-thread orientation of the spindles and their direction of rotation impart an upward twisting motion, meaning that they drive the shell fragments upward, and as these separated shell fragments reach the top ends of the spindles, they collect in the spinning shell collection tray 10, whereupon they are flung outward to the tray periphery and tumble down the discharge
15 pipe 11. Once the crab meat has passed between the spindles and, consequently, been relieved of its shell fragments, it migrates to the periphery of the spinning meat collection tray 13 within which is deployed the ring of spindles 12. The meat collection tray 13 is likewise furnished with a discharge pipe 15.

In order to facilitate the migration of shell fragments and crab meat to
20 their respective discharge pipes 11 and 15, the respective spinning collection trays 10 and 13 can be fitted with suitably shaped stationary baffles, respectively 16 and 17, for example made of rubber.

Under the discharge pipes 11, 15 from the collection trays 10, 13 may be placed receiving receptacles, respectively 18 and 19, which may alternatively be
25 replaced by conveyor belts (not shown).

The upper collection tray 10 for shell and waste is caused to rotate by means of a third electric motor 20 via a toothed belt or chain drive 21.

A fourth electric motor 22 turns an intermediate shaft 24 running parallel to the main shaft 14 through a helical drive gearbox (whose casing is denoted 23); said parallel intermediate shaft 24 causing via two parallel drives, being either toothed-belt-and-pulley drives or chain-and-sprocket drives 25, 26 the rotation of the main shaft 14 (lower parallel drive) and sun gear assembly (upper parallel drive). The driven toothed belt drive pulleys, or driven chain drive sprockets, are denoted 25' and 26'.

The separation means of the crab processing machine, or more exactly the drive and bearing particulars of the spindles 12 and their main shaft 14, are illustrated in greater detail in Figure 2 in which only one spindle 12 is shown, the other spindles having similar drive and bearing arrangements.

The bearings of the main shaft 14 are indicated schematically by numbers 27 and 28.

The upper toothed belt pulley 25' and, above it, a sun gear 29 of larger diameter form an integral unit (the sun gear assembly) by virtue of a connector sleeve 30, and are (rotatably) mounted on the main shaft 14 by means of two ball bearings 31 and 31'. Reference numeral 32 denotes an oil seal (simmer) ring.

In order to turn the spindle 12, said spindle 12 is provided with a planetary gear 33 of substantially smaller diameter than the central sun gear 29 with which it meshes. The spindle 12 is supported below planetary gear 33 by, in downward order: needle bearing 34, retainer (seger) ring 35, axial (thrust) ball bearing 36 and securing nut 37. The spindle 12 is supported above planetary gear 33 by, in upward order: two axially mounted needle bearings 38 and 38' and a top oil seal (simmer) ring 39.

As already noted, the toothed belt pulley 25' and the central sun gear 29 are (rotatably) mounted on the main shaft 14 by means of two ball bearings

31, 31'. Consequently the central sun gear 29 rotates freely on the main shaft 14, permitting the speed of revolution of the spindles 12 to be regulated by varying the diameter of the toothed belt pulley 25'.

The axial ball bearing, needle bearings and sun and planetary gear sets
5 29, 33 should preferably run in an oil bath. In order to diminish the nutritional hazards associated with oil leaks a favourable choice of oil would be soya oil, for example.

In order to facilitate cleaning of the machine, steam jets or similar (not shown) can be incorporated. Any such cleaning devices are outside the realm
10 of this invention, concerning as it does principally the crab processing machine's crab separation facility comprising the rotating spindles 12 deployed in a ring. The actual perimeter shape of the "ring" defined by the mutually adjacent and co-operating spindles is not critical, but for reasons of symmetry, practical realisations will generally invoke a layout which, in plan, features generally
15 circular deployment of the spindles, which besides should make it easier to transmit power to the spindles by means of gearing. This advantage notwithstanding, the invention is not to be construed as being limited to geared transmissions to rotate the spindles 12.

CLAIMS

1. A processing machine for boiled crab, lobster and other crustacean comprising a shell crushing means (2) and a subsequent separation means in which the meat is separated from the shell fragments, *characterised in that* said separation means comprises a number of upright (vertical or steeply inclined), rotating, screw-threaded spindles (12) which are deployed in a ring within the confines of a spinning meat collection tray (13) for crab meat and spaced at such intervals from each other that the crab medium being fed into the circular space defined by the ring of said spindles (12) in said spinning meat collection tray (13) is pressed by centrifugal force outward against said spindles (12) where the crab meat can pass between said adjacent spindles (12), but where almost all the hard shell fragments are unable to pass between said adjacent spindles (12), since the screw-thread gradient and direction of rotation of said spindles (12) are deliberately selected so as to promote the upward twisting motion of the shell fragments into the overlying shell collection tray (10), while the meat makes its way to the outer periphery of said spinning meat collection tray (13) which surrounds the ring of spindles (12) aforesaid.
2. The processing machine of claim 1, *characterised in that* the said shell collection tray (10) may be caused to spin.
3. The processing machine of claim 1 in which between the shell crusher means (2) and the separation means (12) is provided a transport means (6, 7) with which to feed the separation means, *characterised in that* said transport means (6, 7) comprises a generally horizontal pipe (7) housing a rotating transport auger (feed screw) (8) which, besides serving as transport means, also

serves to aerate and break up the crushed crab medium, thereby tending to facilitate the initial separation of the meat from the shell.

4. The processing machine of claim 3, *characterised in that* said transport pipe (7) by virtue of the pipe bend (7') extends downward through the center
5 of said shell collection tray (10) where it discharges just above the generally circular space defined by said spindles (12) deployed in said meat collection tray (13).

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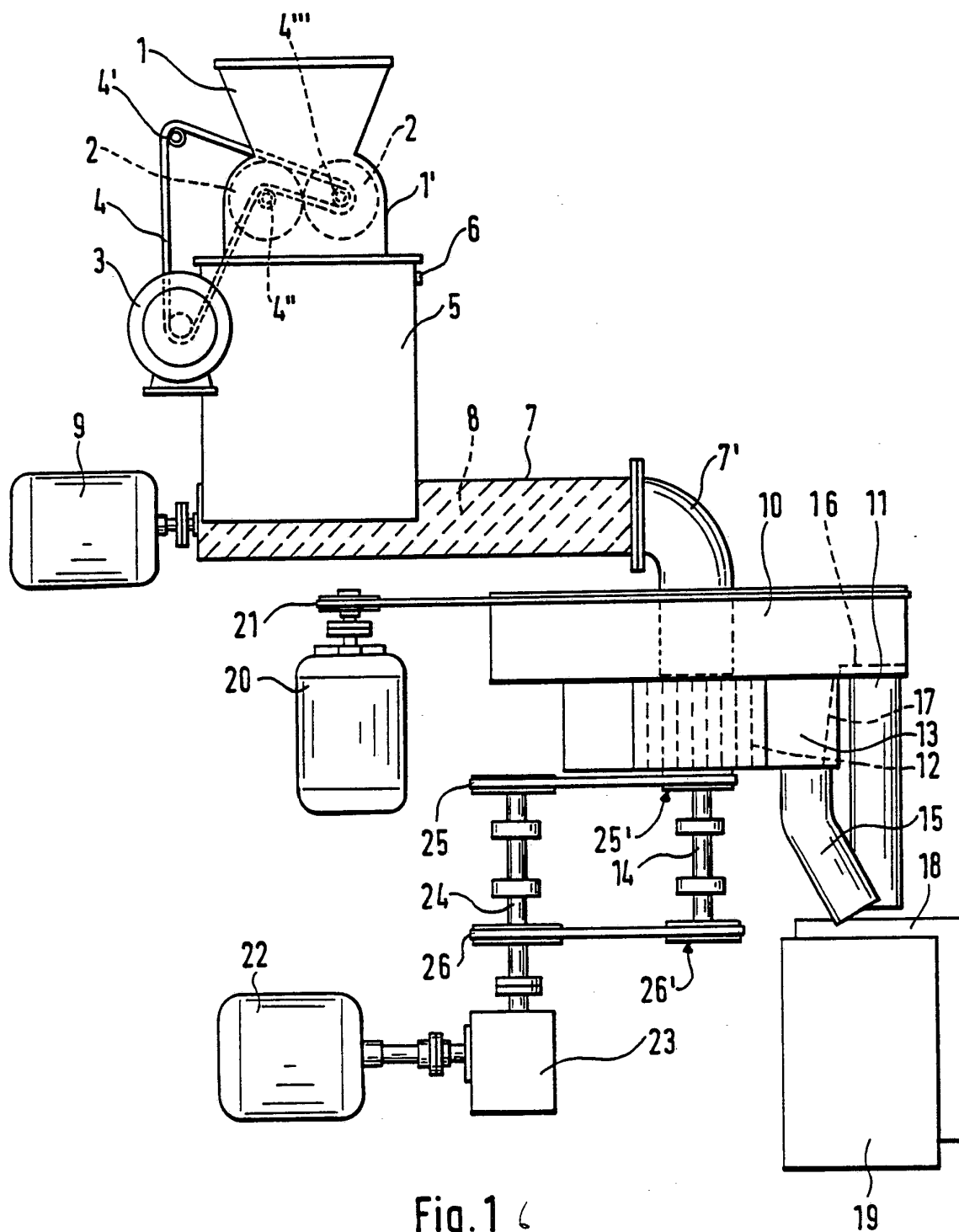
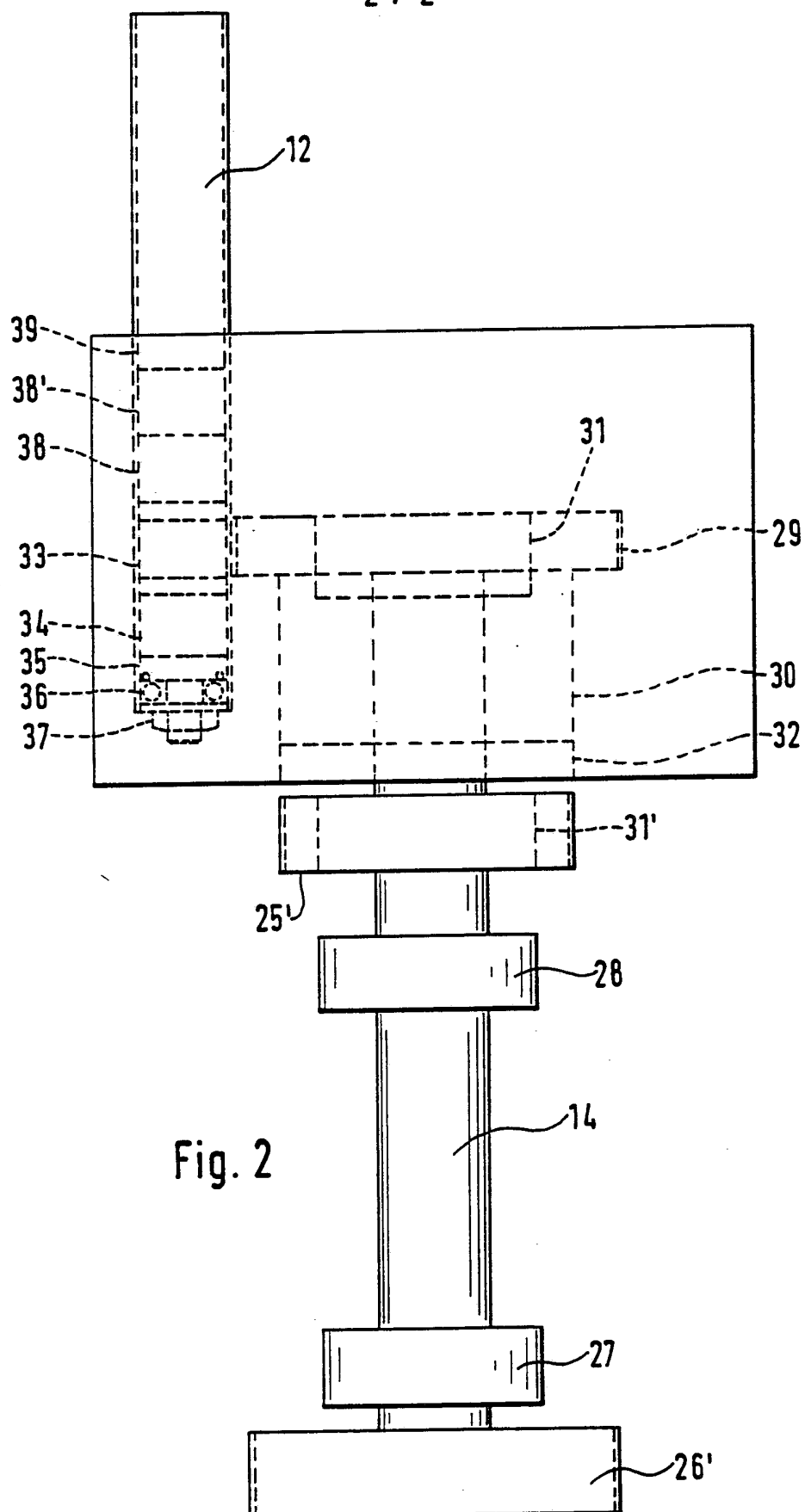


Fig. 1

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INTERNATIONAL SEARCH REPORT

International Application No PCT/NO 89/00120

I. CLASSIFICATION OF SUBJECT MATTER (If several classification symbols apply, indicate all) *	
According to International Patent Classification (IPC) or to both National Classification and IPC	
IPC5: A 22 C 29/00	
II. FIELDS SEARCHED	
Minimum Documentation Searched ?	
Classification System	Classification Symbols
IPC5	A 22 C
Documentation Searched other than Minimum Documentation to the extent that such Documents are Included in the Fields Searched *	
SE,DK,FI,NO classes as above	
III. DOCUMENTS CONSIDERED TO BE RELEVANT *	
Category *	Citation of Document, ** with Indication, where appropriate, of the relevant passages ¹² Relevant to Claim No. ¹³
A	FR, A, 2192771 (KONSORTIUM ENTWICKLUNG KRABBenENTSchÄLMACHINE ET AL) 15 February 1974, see figures 51,52 see detail 12 --
A	FR, A, 1380964 (MASCHINENFABRIK BUCKAU R. WOLF AG) 26 October 1964, see the whole document --
A	US, A, 3229325 (E.J. AMELANG) 18 January 1966, see the whole document --
A	US, A, 1565342 (KARL D. UMRATH) 15 December 1925, see the whole document -- -----
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IV. CERTIFICATION	
Date of the Actual Completion of the International Search	Date of Mailing of this International Search Report
15th February 1990	1990 -02- 20
International Searching Authority	Signature of Authorized Officer
SWEDISH PATENT OFFICE	Agneta Änggård

**ANNEX TO THE INTERNATIONAL SEARCH REPORT
ON INTERNATIONAL PATENT APPLICATION NO. PCT/NO 89/00120**

This annex lists the patent family members relating to the patent documents cited in the above-mentioned international search report.

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
FR-A- 2192771	15/02/74	NL-A- 7309912 DE-A- 2235066 BE-A- 802457	21/01/74 07/02/74 16/11/73
FR-A- 1380964	26/10/64	NONE	
US-A- 3229325	18/01/66	NONE	
US-A- 1565342	15/12/25	NONE	