



(51) International Patent Classification:
G05F 1/575 (2006.01)

(21) International Application Number:
PCT/EP2018/050732

(22) International Filing Date:
12 January 2018 (12.01.2018)

(25) Filing Language: English

(26) Publication Language: English

(30) Priority Data:
17158151.5 27 February 2017 (27.02.2017) EP

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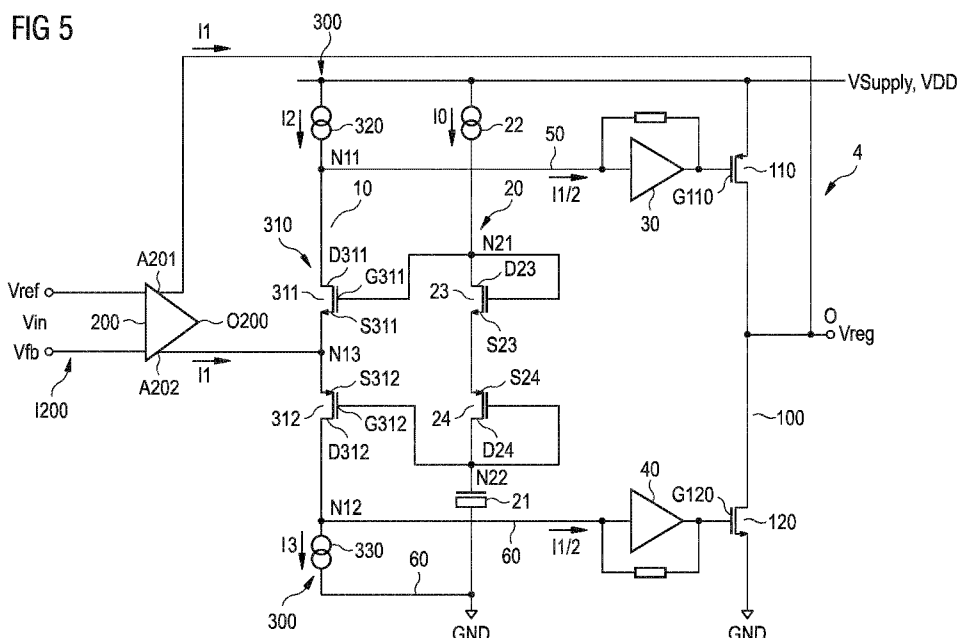
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(81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM, AO, AT, AU, AZ, BA, BB, BG, BH, BN, BR, BW, BY, BZ, CA, CH, CL, CN, CO, CR, CU, CZ, DE, DJ, DK, DM, DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IR, IS, JO, JP, KE, KG, KH, KN, KP, KR, KW, KZ, LA, LC, LK, LR, LS, LU, LY, MA, MD, ME, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PA, PE, PG, PH, PL, PT, QA, RO, RS, RU, RW, SA, SC, SD, SE, SG, SK, SL, SM, ST, SV, SY, TH, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.

(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, GH, GM, KE, LR, LS, MW, MZ, NA, RW, SD, SL, ST, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, RU, TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV,

(54) Title: LOW-DROPOUT REGULATOR HAVING SOURCING AND SINKING CAPABILITIES



(57) Abstract: A low-dropout regulator comprises an output current branch (100) in which a first output driver (110) and a second output driver (120) is arranged. An input amplifier stage (200) provides a first control current (I1) to control the operating state of the first and the second output driver (110, 120). A current generator unit (300) provides a second control current (I2) to operate the first output driver (110) in the second operating state and provides a third control current (I3) to operate the second output driver (120) in the second operating state, when the first control current (I1) of the input amplifier stage (200) is below a threshold level.

MC, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK, SM,
TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW,
KM, ML, MR, NE, SN, TD, TG).

Published:

— *with international search report (Art. 21(3))*

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Description

LOW-DROPOUT REGULATOR HAVING SOURCING AND SINKING
CAPABILITIES

5

Technical Field

The disclosure relates to a low-dropout regulator having sourcing and sinking capabilities.

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Background

A low-dropout regulator (LDO) is a DC linear voltage regulator that can regulate the output voltage even when the supply voltage is very close to the output voltage. The LDO provides a regulated output voltage at an output node that may be used to supply a load. LDOs are traditionally unidirectional power supplies, i.e. they usually source a current, if the LDO for example replaces a battery.

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The design of LDOs is a challenging task in most cases because of stability concerns. They are intrinsically associated with a device that must source a large current into a big load capacitor. To ensure the required drive capability for an output driver/transistor of the LDO, a large swing is needed at its gate. This automatically implies the presence of a (at least moderately) large impedance node. In addition, the parasitic at the gate of the output transistor is large. Thus, there are possibilities for a low frequency cut-off pole.

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At the same time, the output node of an LDO, loaded by a capacitor which might be as large as possible to ensure a

precise regulated voltage, fits well into the role of a dominating pole in the regulation loop. This means that the total phase margin of the circuit structure is expected to be quite poor.

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It is evident that it could be quite complicated to ensure that the LDO is endowed with a bidirectional current capability, i.e. not only the usual sourcing one but also a sinking capability. In fact, the circuitry to correlate the drive at a pull-up device of the LDO to a pull-down device of the LDO would unavoidably introduce other poles and other large parasitics because of the large size of the sinking element.

15 It is obvious that as soon as the output branch of an LDO is made by a series connection of two large devices, the need to keep their bias current under control is absolutely mandatory. Any offset or mismatching, even in a properly designed architecture, would make this value unacceptably
20 high because a key feature of an LDO is to dissipate as little power as possible if unloaded.

It is desired to provide a low-dropout regulator having sourcing and sinking capabilities, wherein the LDO has low
25 power consumption in the sourcing and sinking operation mode as well as in the unloaded state.

Summary

30 A low-dropout regulator having sourcing and sinking capabilities, wherein the regulator dissipates as little power as possible is specified in claim 1.

The low-dropout regulator comprises an output node to provide a regulated output voltage. The LDO further comprises an output current branch coupled to the output node, the output current branch comprising a first output driver and a second output driver. The first and the second output drivers are configured to be operated in a first and a second operating state. The respective conductivity of the first and the second output drivers is higher in the first operating state than in the second operating state.

The LDO further comprises an input amplifier stage having an input side to apply an input signal and an output side to provide a first control current to control the operating state of the first and the second output drivers. The input amplifier stage generates the first control current in dependence on the input signal. The LDO comprises a current generator unit to provide a second control current to operate the first output driver in the second operating state and to provide a third control current to operate the second output driver in the second operating state, when the first control current at the output side of the input amplifier stage is below a threshold level.

The structure of a traditional LDO just having a sourcing capability is doubled so that the output branch of the LDO comprises a first and an additional second output driver. The LDO has sourcing and sinking capabilities by providing the first and a second output drivers in the output current branch. In dependence on operating the LDO in the sourcing or sinking operation mode, only one of the two output drivers is operated in a high conductive state, whereas the other one of the two output drivers is operated with lower conductivity or even with no conductivity. That means that the LDO is

configured as a fully class AB approach unlike usual LDO solutions.

Furthermore, the current generator unit allows to operate
5 both of the first and second output drivers in the output
current branch with low or even no conductivity, when the
input signal applied to the input amplifier stage and the
first control current has a low level or the output node of
the LDO is unloaded. Only under a large signal condition of
10 the input signal at the input side of the input amplifier
stage is one of the output drivers of the output current
branch turned into the conductive state, while the other of
the first and second output drivers is turned in the low-
conductive or non-conductive state. Since in any case one or
15 both of the output drivers are turned into the low-/non-
conductive state, the LDO has a low power consumption. The
quiescent current is made minimal even in the presence of
large mismatching.

20 Brief Description of the Drawings

Figure 1 shows an embodiment of a transimpedance-based
regulator having sourcing capability.

25 Figure 2 illustrates a conceptual implementation of an LDO
having sourcing and sinking capabilities.

Figure 3 shows an embodiment of an LDO having sourcing and
sinking capabilities and a low power consumption by
30 minimizing crowbar.

Figure 4 shows an embodiment of an input amplifier stage of
an LDO.

Figure 5 shows another embodiment of an LDO having sourcing and sinking capabilities.

5 Figure 6 shows an embodiment of an LDO having sourcing and sinking capabilities with a feedback net to provide a feedback path from the output node of the LDO to the input amplifier stage.

10 Detailed Description

Figure 1 shows a transimpedance-based architecture 1 of an LDO comprising an output current branch 100 including an output driver 110 that is arranged between a supply line
15 V_{supply} and an output node O of the LDO to provide a regulated output voltage V_{reg} . The output driver 110 may be configured as an output transistor. The output node O is fed back by a feedback path comprising resistors 70 and 80 to an input side I200 of an input amplifier stage 200. The input
20 amplifier stage 200 has a first input node E200a to apply a reference signal V_{ref} and a second input node E200b to apply the fed back signal V_{fb} derived from the regulated output voltage V_{reg} .

25 An output side O200 of the input amplifier stage 200 is coupled to a transimpedance amplifier stage 30 that is arranged between a control connection of the output driver 110 and the output side O200 of the input amplifier stage 200. The transimpedance amplifier 30 comprises a transistor
30 33, a current source 34 and a resistor 35. The transistor 33 and the current source 34 are coupled in series between the supply line V_{supply} and a reference potential. The resistor

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35 is arranged between the drain connection of the transistor 33 and the output side O200 of the input amplifier stage 200.

5 The output driver 110 may be configured as a power transistor that is driven with a low impedance given by the transconductance of the transistor 33 for a fast drive of its parasitic. The large resistor 35 allows sufficient gain without cutting the large capacitance at the output transistor gate. This arrangement allows the dominant pole at 10 the output node with safe gain and phase margin values. Due to the large value for the transconductance of the transistor 33, the second loop pole can be shifted at a very high frequency and the dominant pole is at the output node. Hence an output capacitor can be increased without limitation to 15 make the regulated output voltage as precise as possible against load current fast variations.

Virtual ground of the transimpedance stage 30 is set to the gate-source voltage of the output transistor 110 for a given 20 current. This determines the load current value that gives the zero offset condition at the LDO input and sets the proper control in the output stage current.

In the implementation of the LDO shown in Figure 1, the 25 output transistor 110 and the transistor 33 of the transimpedance amplifier stage 30 are matched devices so that the output driver 110 will tend to drive n-times the current across the resistor 35 as soon as the drop across the resistor 35 is zero. As the output voltage V_{reg} is pulled 30 down by the load only, the current across the output driver 110 remains equal to a load current regardless of any offset between the output transistor 110 and the transistor 33 of

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the transimpedance amplifier stage 30 and any offset current from the input amplifier stage 200 to the resistor 35.

5 The advantages of the circuit structure shown in Figure 1 can be exploited by implementing a complementary LDO having both sourcing and sinking capabilities, according to the implementation shown in Figure 2.

Figure 2 shows a conceptual implementation of an LDO. The
10 circuit structure of the LDO illustrated in Figure 1 is doubled so that the LDO in Figure 2 comprises an LDO up-portion 2a and an LDO down-portion 2b. The LDO up-portion 2a comprises a first output driver 110 arranged between a supply line V_{supply} and an output node O. The output driver 110 may
15 be configured as an output transistor. The LDO up-portion further comprises an input amplifier stage 200a, and a transimpedance amplifier stage 30 comprising a transimpedance amplifier 31 and a resistor 32 that couples the output of the transimpedance amplifier 31 back to the input connection of
20 the transimpedance amplifier 31. The transimpedance amplifier stage 30 is coupled between a control connection G110 of the output driver 110 and the output side of the input amplifier stage 200a. A reference signal V_{ref} is applied at an input connection, for example a non-inverting input connection, of
25 the input amplifier stage 200a. A second connection, for example an inverting connection, of the input amplifier stage 200a is connected to the output node O of the LDO amplifier.

The LDO down-portion 2b comprises an output driver 120
30 arranged between the output node O and the reference potential. The output driver 120 may be configured as an output transistor. The LDO down-portion 2b further comprises an input amplifier stage 200b and a transimpedance amplifier

stage 40. The transimpedance amplifier stage 40 is arranged between a control connection G120 of the output driver 120 and an output side of the input amplifier stage 200b. The transimpedance stage 40 comprises a transimpedance amplifier 5 41 and a resistor 42 that couples the output of the transimpedance amplifier 41 back to the input connection of the transimpedance amplifier 41. The reference signal Vref is applied to a first input connection, for example a non-inverting input connection, of the input amplifier stage 10 200b. The output node O is connected to a second input connection, for example an inverting input connection, of the input amplifier stage 200b.

The output drivers 110 and 120 are connected in series in an 15 output branch 100 of the LDO regulator between a supply line Vsupply and a reference potential. The output drivers are configured as transistors of a different type of conductivity. The output driver 110 may be configured, for example, as a PMOS transistor, and the output driver 120 may 20 be configured, for example, as an NMOS transistor. The transimpedance 32, 42 can be set with different values, especially since the output driver 120, for example the NMOS transistor, asks for lower overdrive than the output driver 110, for example the PMOS counterpart.

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Figure 2 shows shows a unity gain for the LDO stage, as it is only conceptual. Of course a feedback net can be adopted to make the regulated output voltage Vreg higher than the value of the reference voltage Vref. In this case, one resistor 30 goes from the output side O of the LDO to the negative inputs (the same node is shared by both) of the amplifiers 200a and 200b and a second resistor from the shared input to ground.

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The implementation of the LDO amplifier shown in Figure 2 has some significant drawbacks in practical use. The offset in one stage, for example the LDO up-portion 2a or the LDO down-portion 2b, may cause large conduction in the associated power transistor. Assuming that the offset of the LDO portions 2a and 2b is uncorrelated, the offset of the other branch might be capable of fully absorbing this current increase. In this way the current in the output current branch 100 is no longer fixed by the load one only and unacceptably large value of power consumption might come even for light load values.

Figure 3 shows an improved embodiment of an LDO 3 having sourcing and sinking capabilities, wherein the crowbar issue, i.e. the contemporary conduction of the two output drivers/transistors 110 and 120, is avoided by adding a systematic offset at the input of the two LDO branches 50 and 60.

According to the embodiment of the LDO 3 of Figure 3, the LDO comprises an output node O to provide a regulated output voltage V_{reg} , wherein the output node O is arranged in an output current branch 100 of the LDO. The output current branch 100 comprises a first output driver 110 that may be configured as an output transistor and a second output driver 120 that may be configured as an output transistor. The output driver 110 and the output driver 120 are configured of a different type of conductivity. The output driver 110 may be configured as a PMOS transistor, and the output driver 120 may be configured as an NMOS transistor.

The first and the second output drivers 110, 120 are configured to be operated in a first and a second operating

state. The respective conductivity of the output driver 110 and the output driver 120 is higher in the first operating state than in the second operating state of the transistors. The first operating state may be the conductive state of the output drivers and the second operating state may be the non-conductive state.

The LDO 3 comprises an input amplifier stage 200 having an input side I200 to apply an input signal V_{in} and an output side O200 to provide a first control current I_1 to control the operating state of the output drivers 110 and 120. The input amplifier stage 200 generates the first control current I_1 in dependence on the input signal V_{in} being a differential signal derived from the reference signal V_{ref} and the feedback signal V_{fb} .

The LDO 3 comprises a current generator unit 300 to provide a second control current I_2 to operate the output driver 110 in the second operating state, for example the non-conductive operating state, and to provide a third control current I_3 to operate the output driver 120 in the second operating state, for example the low-conductive/non-conductive operating state, when the first control current I_1 at the output side O200 of the input amplifier stage 200 is below a threshold level, for example, is a zero signal.

The LDO 3 comprises a first transimpedance amplifier stage 30 being connected to a control connection G110 of the output driver 110. The LDO 3 further comprises a second transimpedance amplifier stage 40 being connected to a control connection G120 of the output driver 120. Each of the transimpedance amplifier stages 30 and 40 comprises a transimpedance amplifier 31, 41 and a resistor/transimpedance

32, 42 that is connected between the input and the output connection of the respective transimpedance amplifier 31, 41.

The input amplifier stage 200 has three output connections at its output side O200. The input amplifier stage 200 comprises a first output connection A201 to provide/receive the first control current I1. The first output connection A201 of the input amplifier 200 is connected to the output node O of the LDO 3. The input amplifier stage 200 comprises at the output side O200 a second output connection A202 and a third output connection A203 to provide/receive the first control current I1. The second output connection A202 of the input amplifier stage 200 is connected to the first transimpedance amplifier stage 30. The third output connection A203 of the input amplifier stage 200 is connected to the second transimpedance amplifier stage 40. The three current branches at the output side O200 must match precisely, but it is not necessary that they have the same nominal value. They can be different multiples from a unit value, this being especially true for the branch directly feeding the LDO output O.

The current generator unit 300 comprises a first current generator 340 and a second current generator 350. The first current generator 340 is connected to the first transimpedance amplifier stage 30 to provide the second control current I2 that causes to operate the output driver 110 in the second operating state, for example the non-conductive operating state. The second current generator 350 is connected to the second transimpedance amplifier stage 40 to provide the third control current I3 that causes to operate the output driver 120 in the second operating state, for example the non-conductive operating state.

The LDO 3 of Figure 3 is configured as a class AB regulator. The class AB property is ensured by the control current I1 being injected into the two transimpedance stages 30 and 40, both on the pull-up side represented by the transimpedance stage 30 and the pull-down side represented by the transimpedance stage 40.

In the case of a positive value of the control current I1, i.e. if the LDO is operated in the sourcing operation mode and the control current I1 is injected by the input amplifier stage 200 in the transimpedance stages 30 and 40, the output driver 110 is turned on, i.e. switched in a state of high conductivity, so that the current flowing through the output driver 110 is increased. On the other hand, the control current I1 injected in the transimpedance stage 40 has the effect that the output driver 120 moves to an even deeper turn-off status, i.e. to a state of low conductivity or no conductivity.

For a negative value of the control current I1, i.e. if the LDO 3 is operated in the sinking operation mode and the control current I1 exits the current generator unit 300 and is injected in input amplifier stage 200, the output driver 110 is turned off or turned in a low-conductive state/non-conductive state, while the output driver 120 is turned on or turned in a high conductive state.

When the input voltage of the input amplifier stage 200 is very small, the control current I2 provided by the current generator 340 turns the output driver 110 off, i.e. in an operation state of low conductivity or the non-conductive operation state, and the control current I3 provided by the current generator 350 turns the output driver 120 off, i.e.

in an operation state of low conductivity or the non-conductive operation state. That means that in the unloaded configuration both of the output drivers 110 and 120 are controlled by the control currents I2 and I3 so that both of
5 the output drivers are operated in an operation state of low conductivity or in a non-conductive state.

As for both branches, i.e. the pull-up and pull-down branch, the original structure shown in Figure 1 is preserved. The
10 stability concerns are unaltered, and in particular, a Miller compensation is not required. The output node A201 directly drives the output node O and ensures the loop closure when the control current I1 is zero or very small ($I1 < I2$ or $I1 < I3$). The LDO may be embodied such that the control currents
15 I2 and I3 are equal DC currents. Alternatively to the embodiment of the LDO shown in Figure 3 in which the control current I2 and I3 turn off the output drivers 110 and 120, the virtual ground of the two transimpedance stages 30 and 40 can be set slightly different from the gate source voltage
20 implemented in the embodiment shown in Figure 1 to achieve the same result.

Figure 4 shows a possible embodiment for the input amplifier stage 200 of the LDO 3 of Figure 3. The embodiment of the
25 input amplifier stage 200 shown in Figure 4 is configured to provide the three replicas of the three control currents I1 to drive the two transimpedance stages 30 and 40 as well as the output node O. The input amplifier stage 200 comprises an amplifier stage 210 that may be configured as an NMOS
30 amplifier stage or a PMOS amplifier stage, depending on the available dynamic range. The amplifier stage 210 comprises a transistor 211 to apply a feedback voltage Vfb derived from the regulated output voltage Vreg at the output node O and a

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transistor 212 to apply the reference voltage V_{ref} . The amplifier stage 210 is connected to a current source 220.

The input amplifier stage 200 further comprises PMOS mirror stages 230 and NMOS mirror stages 240. The control current I_1 provided at the output connection A201 is delivered at the connection between a PMOS transistor 234 of a first PMOS mirror stage 231 and an NMOS transistor 244 of a first NMOS mirror stage 241. The control current I_1 provided at the output connection A202 of the input amplifier stage 200 is delivered at the connection between a PMOS transistor 235 of a second PMOS mirror stage 232 and an NMOS transistor 245 of a second NMOS mirror stage 242. The control current I_1 provided at the output connection A203 of the input amplifier stage 200 is delivered at the connection between a PMOS transistor 236 of a third PMOS mirror stage 233 and an NMOS transistor 246 of a third NMOS mirror stage 243.

As described above, the embodiment of the input amplifier stage 200 shown in Figure 4 comprises a plurality of mirrors. The circuit configuration of Figure 4 may be critical in case of an offset between the mirrors. The offset can cause the control current I_1 being injected in the transimpedance stage 30 and the transimpedance stage 40, when the LDO of Figure 3 is operated in the unloaded operation state. In this case the control current I_1 may be so large so that the control current I_2 and the control current I_3 may be compensated. As a consequence, the output drivers 110 and 120 are controlled to be operated both in a conductive state. In this case an undesired crowbar condition in which both of the output drivers 110 and 120 are operated in the conductive state is recovered.

Figure 5 shows an improved embodiment of an LDO 4 having sourcing and sinking capabilities. The LDO 4 shown in Figure 5 comprises an output node O to provide a regulated output voltage V_{reg} . An output current branch 100 is coupled to the output node O between a supply line V_{supply} to provide a supply voltage VDD and a reference potential. The output current branch 100 comprises an output driver 110 that may be configured as an output transistor and an output driver 120 that may be configured as an output transistor. Both of the output drivers are configured to be operated in a first and a second operating state. When operated in the first operating state, the respective conductivity of the output driver 110 and the output driver 120 is higher than in the second operating state of the drivers. According to a possible embodiment, the first operating state of the output drivers 110 and 120 may be a conductive state of the transistors and the second operating state may be a non-conductive state of the output drivers.

The LDO 4 further comprises an input amplifier stage 200 having an input side I200 to apply an input signal V_{in} being a differential signal of the reference signal V_{ref} and the feedback signal V_{fb} that is derived from the regulated output signal V_{reg} . The input amplifier stage 200 has an output side O200 to provide a control current I1 to control the operating state of the output driver 110 and the output driver 120. The input amplifier stage 200 generates the control current I1 in dependence on the input signal V_{in} .

The LDO 4 further comprises a current generator unit 300 to provide a control current I2 to operate the output driver 110 in the second operating state, for example a state of low conductivity or a non-conductive state, and to provide a

control current I3 to operate the output driver 120 in the second operating state, for example a state of low conductivity or a non-conductive state, when the output current I1 at the output side O200 of the input amplifier stage 200 is below a threshold level or is a zero signal, i.e. a signal having a zero level. In particular, the current generator unit 300 generates the control current I2 and the control current I3 to operate the output drivers 110 and 120 in the low conductive or non-conductive state, when the LDO regulator is operated in the unloaded state or the control current I1 is zero or very small.

The current generator unit 300 comprises a current generator 310. The output side O200 of the input amplifier stage 200 is coupled to the current generator 310. The current generator 310 may be configured as a floating current generator. The current generator unit 300 further comprises a current generator 320 and a current generator 330 being coupled in series with the current generator 310 in a first current branch 10. The first current branch 10 is arranged between the supply line Vsupply to provide the supply potential VDD and a reference potential. The current generator 310 comprises a first transistor 311 and a second transistor 312. The first and the second transistors 311 and 312 of the first current generator 310 are of a different type of conductivity. The first transistor 311 may be configured as an NMOS transistor and the second transistor 312 may be configured as a PMOS transistor. The first transistor 311 and the second transistor 312 of the current generator 310 are connected in series such that the source node S311 of the first transistor 311 is connected to the source node S312 of the second transistor 312 of the current generator 310. The current generator 320 is connected to the drain connection

D311 of the first transistor 311 of the current generator 310. The current generator 330 is connected to the drain connection D312 of the second transistor 312 of the current generator 310.

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The LDO 4 further comprises a voltage source 21, a current generator 22, a transistor 23 and a transistor 24 being connected in series in a second current branch 20 between the supply line Vsupply and a reference potential. The

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transistors 23 and 24 are configured as transistors of a different type of conductivity. In particular, the transistor 23 may be configured as an NMOS transistor and the transistor 24 may be configured as a PMOS transistor. According to another possible embodiment for the second current branch,

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the positive terminal of the voltage source 21 is coupled to the supply potential and the current generator 22 is connected from a node N22 to ground GND.

The transistor 23 and the transistor 24 of the second current branch 20 are connected in series such that the source node S23 of the transistor 23 is connected to the source S24 of the transistor 24. The current generator 22 is connected to the drain connection D23 of the transistor 23. The drain connection D24 of the transistor 24 is connected to the voltage source 21. The second current branch 20 is coupled between the supply line Vsupply to provide the supply voltage VDD and a reference potential.

A control connection G311 of the transistor 311 is connected to a node N21 of the second current branch 20 between the drain connection D23 of the transistor 23 and the current generator 22. A control connection G312 of the transistor 312 is connected to a node N22 of the second current branch 20

between the drain connection D24 of the transistor 24 and the voltage source 21. The transistors 23 and 311 as well as the transistors 24 and 312 are matched to precisely set the current of the floating generator 310.

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The LDO 4 comprises a first transimpedance amplifier stage 30 being arranged between a control connection G110 of the output driver 110 and a first node N11 of the first current branch 10 between the current generator 310 and the current generator 320. In particular, the first node N11 of the first current branch 10 is arranged between the current generator 320 and the drain connection D311 of the transistor 311.

The LDO 4 further comprises a second transimpedance amplifier stage 40 being arranged between a control connection G120 of the output driver 120 and a second node N12 of the first current branch 10 between the current generator 310 and the current generator 330. In particular, the second node N12 of the first current branch 10 is arranged between the drain connection D312 of the transistor 312 of the current generator 310 and the current generator 330.

The input amplifier stage 200 comprises at the output side O200 a first output connection A201 to provide/receive the control current I1. The output connection A201 of the input amplifier stage 200 is coupled to the output node O of the LDO 4. The input amplifier stage 200 is configured to provide the control current I1 at the output connection A201, when the LDO is operated in the sourcing operation mode. The input amplifier stage 200 is configured to receive the control current I1 at the output connection A201, when the LDO 4 is operated in the sinking operation mode.

The input amplifier stage 200 further comprises at the output side 0200 an output connection A202 to provide/receive the control current I1. The output connection A202 of the input amplifier stage 200 is connected to a third node N13 of the first current branch 10 between the source connection S311 of the transistor 311 and the source connection S312 of the transistor 312. The input amplifier stage 200 is configured to provide the control current I1 at the output connection A202, when the LDO 4 is operated in the sourcing operation mode. The input amplifier stage 200 is further configured to receive the control current I1 at the output connection A202, when the LDO 4 is operated in the sinking operation mode.

The output driver 110 is operated in the first operating state, i.e. in the operating state in which the output driver 110 has a high conductivity, and the output driver 120 is operated in the second operating state, in which the output driver 120 has a low conductivity or is in the non-conductive state, when the control current I1 provided at the output connection A202 of the input amplifier stage 200 enters the current generator 310.

The output driver 110 is operated in the second operating state in which the output driver 110 has a low conductivity or is operated in the non-conductive state, and the output driver 120 is operated in the first operating state, in which the output driver 120 has a high conductivity, when the control current I1 received at the output connection A202 of the input amplifier stage 200 exits the current generator 310.

The input amplifier stage 200 can be any kind of differential pair that generates a control current I1 under an input

signal V_{in} . According to a possible embodiment, the input amplifier stage can be configured as shown in Figure 4, where only two matched paths for the control current I_1 are needed.

5 Figure 6 shows the LDO 4 with an embodiment of the input amplifier stage 200 in greater detail. The input amplifier stage 200 comprises an amplifier stage 210 that is connected to a current source 220. The amplifier stage 210 may be configured as an NMOS stage comprising a transistor 211 to
10 receive a feedback signal/voltage V_{fb} derived from the regulated output signal/voltage V_{reg} and a transistor 212 to apply a reference signal/voltage V_{ref} . The feedback voltage V_{fb} received at a control terminal of transistor 211 is derived from the regulated output voltage V_{reg} by means of a
15 feedback net comprising a resistor divider of the resistors 70 and 80.

The input amplifier stage 200 further comprises PMOS mirror stages 230 and NMOS mirror stages 240. The control current I_1
20 provided at the output connection A201 of the input amplifier stage is delivered at the connection between a transistor 234, for example a PMOS transistor, of a first PMOS mirror stage 231, and a transistor 244, for example an NMOS transistor, of a first NMOS mirror stage 241. The output
25 connection A202 of the input amplifier stage 200 to provide/receive the control current I_1 is located at a connection between a transistor 235, for example a PMOS transistor, of a second PMOS mirror stage 232 and a transistor 245, for example an NMOS transistor, of a second
30 NMOS mirror stage 242. Regarding the other components of the LDO regulator 4 shown in Figure 6, reference is made to Figure 5.

The LDO regulator 4 shown in Figures 5 and 6 is configured as a class AB LDO. Depending on the input range, the input amplifier stage 200 can comprise either a P-MOS or N-MOS differential pair and may be even a folded solution.

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A very low impedance set by the transconductance of the transimpedance amplifier stages 30 and 40, drives the large gates of the output transistors 110 and 120. In addition the shared signal I1 to drive both pullup and pulldown sections comes as a current mode one, hence no high impedance nodes are present in the loop: Miller compensation is not required and the associated constraints about a load cap and current vanish. In addition, the transimpedance stages 30 and 40 offer a minimum number of high order poles to ensure excellent phase margin to the structure. In this way, the regulated output might play the role of the dominant pole.

A small offset current, injected in the transimpedance stages 30 and 40 by the floating generator represented by the transistors 311, 312 and 23, 24, brings the power devices 110 and 120 in the low-conductive-state/off-state, when no current I1 comes from the input amplifier stage 200. A current which is matched to the one generated by the input pair closes the loop in this operating condition with minimal drive capability. The LDO stability is enforced by exploiting the benefits of the transimpedance amplifier stages 30 and 40 in both senses of the load current.

According to the embodiment of the LDO 4 shown in Figures 5 and 6, the input amplifier stage 200 is a transconductance stage having two output connections A201, A202 only instead of three output connections, as shown for the embodiment of the LDO 3 of Figure 3. The offset in the transimpedance

stages 30 and 40 is obtained via a series combination of a floating generator, i.e. the transistors 311 and 312, plus two current generators 320 and 330. Assuming the current generator 22 provides a current $I_0 = I_a$, the current
5 generator 320 provide the control current $I_2 = I_a - \varepsilon$ and the current generator 330 provides the control current $I_3 = I_b$. Of course, to have a symmetrical offset for equal resistors in the transimpedance stage, it is possible to set the control current I_3 provided by the current generator 330
10 equal to $I_a - \varepsilon$, i.e. equal to the control current I_2 provided by the current generator 320.

The transistors 311 and 23 are a matched pair as well as the transistors 312 and 24. In this way they force a current I_a
15 in the absence of any contribution of the control current I_1 . As soon as the parameter ε is set to $\varepsilon > 0$, a residual current $\varepsilon * I_a$ is injected in both the transimpedance stages 30 and 40 to turn off the output drivers 110 and 120.

20 At the same time, the floating generator acts as a control current splitter as well. Assuming that the same impedance is seen at the source connections of the transistors 311 and 312, the control current I_1 provided at the output connection A202 of the input amplifier stage 200 is split half in the
25 upper LDO branch 50, i.e. to the control connection of the output driver 110 and half in the lower LDO branch 60, i.e. to the control connection of the output driver 120.

If the control current I_1 is entering the current generator
30 310, it would tend to subtract current in the LDO lower branch 60 to the control connection of the output driver 120 and increase current in the LDO upper branch 50 to the control connection of the output driver 110. In this case the

LDO 4 is operated in the sourcing operating state in which the output driver 110 is operated in the conductive state and the output driver 120 is operated in a low-conductive/non-conductive state. On the other hand, if the control current I1 is exiting the current generator 310, it would tend to increase the current in the lower LDO branch 60 to the control connection of the output driver 120 and subtract current in the upper LDO branch 50 to the control connection of the output driver 110. In this case the LDO 4 is operated in the sinking operation mode in which the output driver 110 is operated in a low conductive state/non-conductive state and the output driver 120 is operated in a high conductive state.

In this way, the implementation of the current splitter makes any offset internal to the input amplifier stage 200 ineffective to crowbar generation. This is an advantage in comparison to the embodiment of the LDO 3 shown in Figure 3 with the input amplifier stage 200 shown in Figure 4, where the control current I1 for the pull-up device 110 and the pull-down device 120 are obtained via replica mirrors. According to the embodiment of the LDO 3 shown in Figures 3 and 4, the transistors in the P-MOS mirror stages and the N-MOS mirror stages might generate DC contributions forcing conduction in both of the driver sections 110 and 120.

Thus, according to the embodiment of the LDO 4, a large degree of matching is not needed in the mirrors of the input amplifier stage 200. As a result, smaller and less, i.e. two instead of three, replica current generators that make the overall signal path faster, are obtained. On the other side, it is clear that crowbar minimization asks for the highest degree of matching between the three series current

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generators of the current splitter, i.e. the current generator 310, 320 and 330.

Anyhow, the current generators 320 and 330 do not belong to
5 the signal paths 50, 60 and even if they are very large
signal speed is not significantly affected for extreme
matching characteristic. In fact, the impedance at the source
connections of the transistors 311 and 312 is one of the
lowest in the loop as given by the parallel connection of two
10 transconductances, unlike the mirrors in Figure 4. Hence, it
can be fast enough even if highly loaded by a large
parasitic.

List of Reference Signs

	1, 2, 3	embodiments of LDO regulators
	10, 20	current branches of the LDO
5	21	voltage source
	22	current generator
	23, 24	transistors
	30, 40	transimpedance amplifier stages
	50, 60	upper and lower LDO branch
10	70, 80	resistors
	100	output current branch
	110, 120	output drivers
	200	input amplifier stage
	210	amplifier stage
15	220	current generator
	230	PMOS mirrors
	240	NMOS mirrors
	300	current generator unit
	310, 320, 330	current generators
20	0	output node
	I1, I2, I3	control currents
	Vreg	regulated output voltage
	Vin	input signal
	Vref	reference signal
25	Vfb	feedback signal

Claims

1. A low-dropout regulator, comprising:

- an output node (O) to provide a regulated output voltage (Vreg),
 - an output current branch (100) coupled to the output node (O), the output current branch comprising a first output driver (110) and a second output driver (120), wherein the first and the second output driver (110, 120) are configured to be operated in a first and a second operating state, wherein the respective conductivity of the first and the second output driver (110, 120) is higher in the first operating state than in the second operating state,
 - an input amplifier stage (200) having an input side (I200) to apply an input signal (Vin) and an output side (O200) to provide a first control current (I1) to control the operating state of the first and the second output driver (110, 120), wherein the input amplifier stage (200) generates the first control current (I1) in dependence on the input signal (Vin),
 - a current generator unit (300) to provide a second control current (I2) to operate the first output driver (110) in the second operating state and to provide a third control current (I3) to operate the second output driver (120) in the second operating state, when the first control current (I1) at the output side (O200) of the input amplifier stage (200) is below a threshold level.
2. The low-dropout regulator of claim 1,
- wherein the current generator unit (300) comprises a first current generator (310),

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- wherein the output side (O200) of the input amplifier stage (200) is coupled to the first current generator (310).

- 5 3. The low-dropout regulator of claim 2,
wherein the first current generator (310) is configured
as a floating current generator.
4. The low-dropout regulator of claims 2 or 3,
10 - wherein the first output driver (110) is operated in the
first operating state and the second output driver (120)
is operated in the second operating state, when the first
control current (I1) enters the first current generator
(310),
15 - wherein the first output driver (110) is operated in the
second operating state and the second output driver (120)
is operated in the first operating state, when the first
control current (I1) exits the first current generator
(310).
20
5. The low-dropout regulator of claims 1 to 4, comprising:
 - a first current branch (10),
 - wherein the current generator unit (300) comprises a
second current generator (320) and a third current
25 generator (330) being coupled in series with the first
current generator (310) in the first current branch (10).
6. The low-dropout regulator of claims 2 to 5,
wherein the first current generator (310) comprises a
30 first transistor (311) and a second transistor (312)
being of a different type of conductivity.
7. The low-dropout regulator of claim 6,

wherein the first transistor (311) and the second transistor (312) are connected in series such that the source node (S311) of the first transistor (311) is connected to the source node (S312) of the second transistor (312).

8. The low-dropout regulator of claim 7, comprising:

- a second current branch (20),
- wherein the second current branch (20) comprises a voltage source (21) and a fourth current generator (22) and third transistor (23) and a fourth transistor (24) being connected in series in the second current branch (20), the third and fourth transistor (23, 24) being of a different type of conductivity.

9. The low-dropout regulator of claim 8,

wherein the third transistor (23) and the fourth transistor (24) are connected in series such that the source node (S23) of the third transistor (23) is connected to the source node (S24) of the fourth transistor (24).

10. The low-dropout regulator of claims 8 or 9,

- wherein a control connection (G311) of the first transistor (311) is connected to a first node (N21) of the second current branch (20) between the drain connection (D23) of the third transistor (23) and the fourth current generator (22),
- wherein a control connection (G312) of the second transistor (312) is connected to a second node (N22) of the second current branch (20) between the drain connection (D24) of the fourth transistor (24) and the voltage source (21).

11. The low-dropout regulator of claims 5 to 10, comprising:
- a first transimpedance amplifier stage (30) being arranged between a control connection (G110) of the first output driver (110) and a first node (N11) of the first current branch (10) between the first current generator (310) and the second current generator (320),
 - a second transimpedance amplifier stage (40) being arranged between a control connection (G120) of the second output driver (120) and a second node (N12) of the first current branch (10) between the first current generator (310) and the third current generator (330).
12. The low-dropout regulator of claims 5 to 11,
- wherein the input amplifier stage (200) comprises at the output side (O200) a first output connection (A201) to provide/receive the first control current (I1), wherein the first output connection (A201) of the input amplifier stage (200) is coupled to the output node (O) of the low-dropout regulator,
 - wherein the input amplifier stage (200) comprises at the output side (O200) a second output connection (A202) to provide/receive the first control current (I1), wherein the second output connection (A202) of the input amplifier stage (200) is coupled to a third node (N13) of the first current branch (10) between the source connection (S311) of the first transistor (311) and the source connection (S312) of the second transistor (312).
13. The low-dropout regulator of claim 1, comprising:
- a first transimpedance amplifier stage (30) being connected to a control connection (G110) of the first output driver (110),

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- a second transimpedance amplifier stage (40) being connected to a control connection (G120) of the second output driver (120),
 - wherein the input amplifier stage (200) comprises at the
5 output side (O200) a first output connection (A201) to provide/receive the first control current (I1), wherein the first output connection (A201) of the input amplifier (200) is connected to the output node (O) of the low-dropout regulator,
 - 10 - wherein the input amplifier stage (200) comprises at the output side (O200) a second output connection (A202) and a third output connection (A203) to provide/receive the first control current (I1), wherein the second output connection (A202) of the input amplifier stage (200) is
15 connected to the first transimpedance amplifier stage (30) and the third output connection (A203) of the input amplifier stage (200) is connected to the second transimpedance amplifier stage (40).
- 20 14. The low-dropout regulator of claim 13,
- wherein the current generator unit (300) comprises a first current generator (340) and a second current generator (350),
 - wherein the first current generator (340) is connected to
25 the first transimpedance amplifier stage (30) to provide a second control current (I2) to operate the first output driver (110) in the second operating state,
 - wherein the second current generator (350) is connected to the second transimpedance amplifier stage (40) to
30 provide a third control current (I3) to operate the second output driver (120) in the second operating state.
15. The low-dropout regulator of claims 1 to 14,

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wherein the first output driver (110) is configured as a transistor of a first type of conductivity and the second output driver (120) is configured as a transistor of a second type of conductivity being different from the first type of conductivity.

5

FIG 1

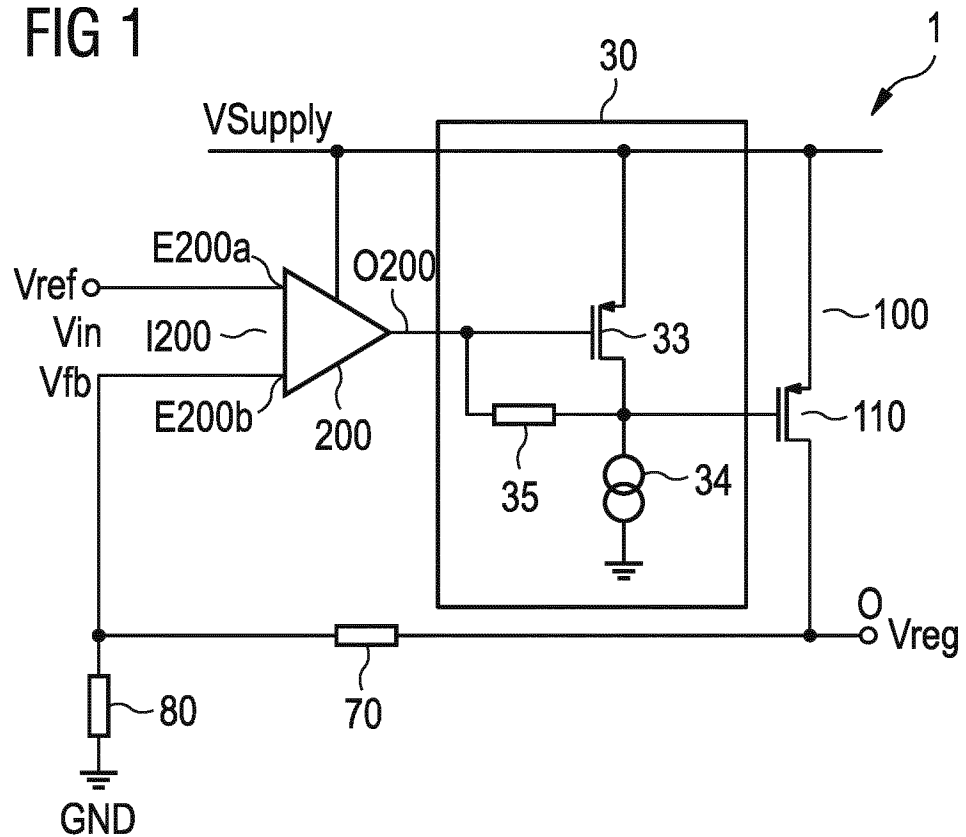


FIG 2

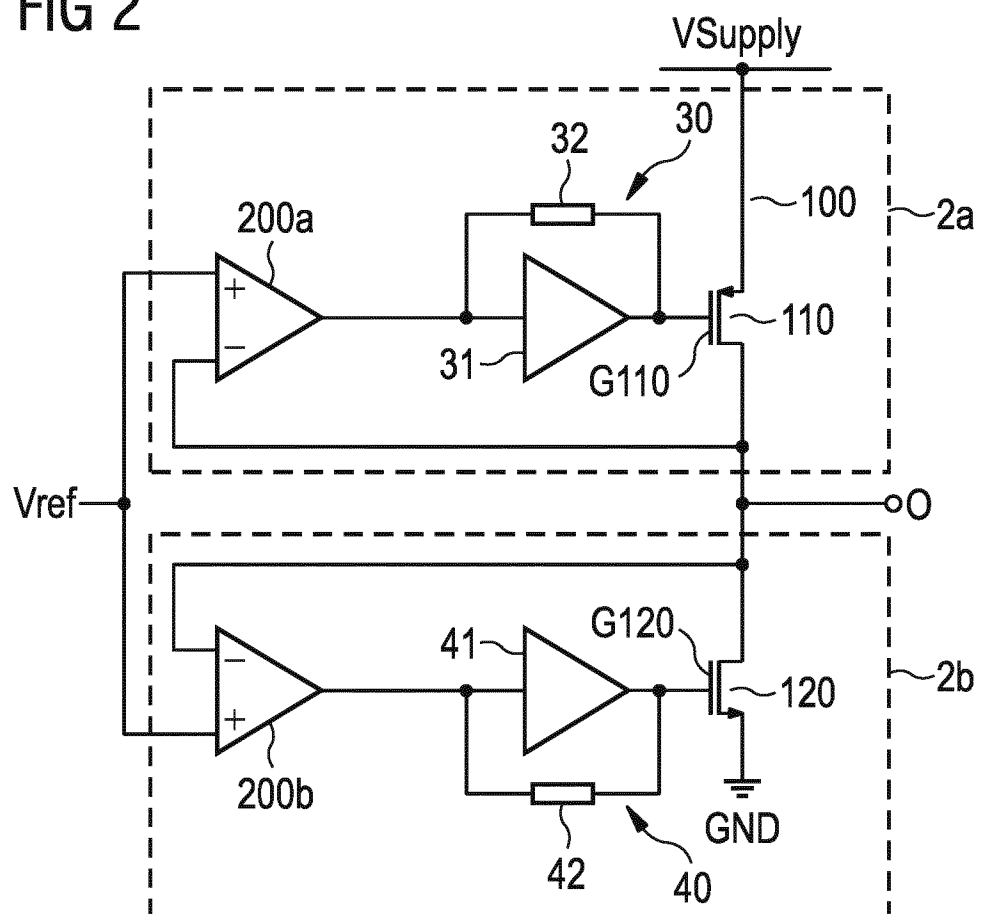


FIG 3

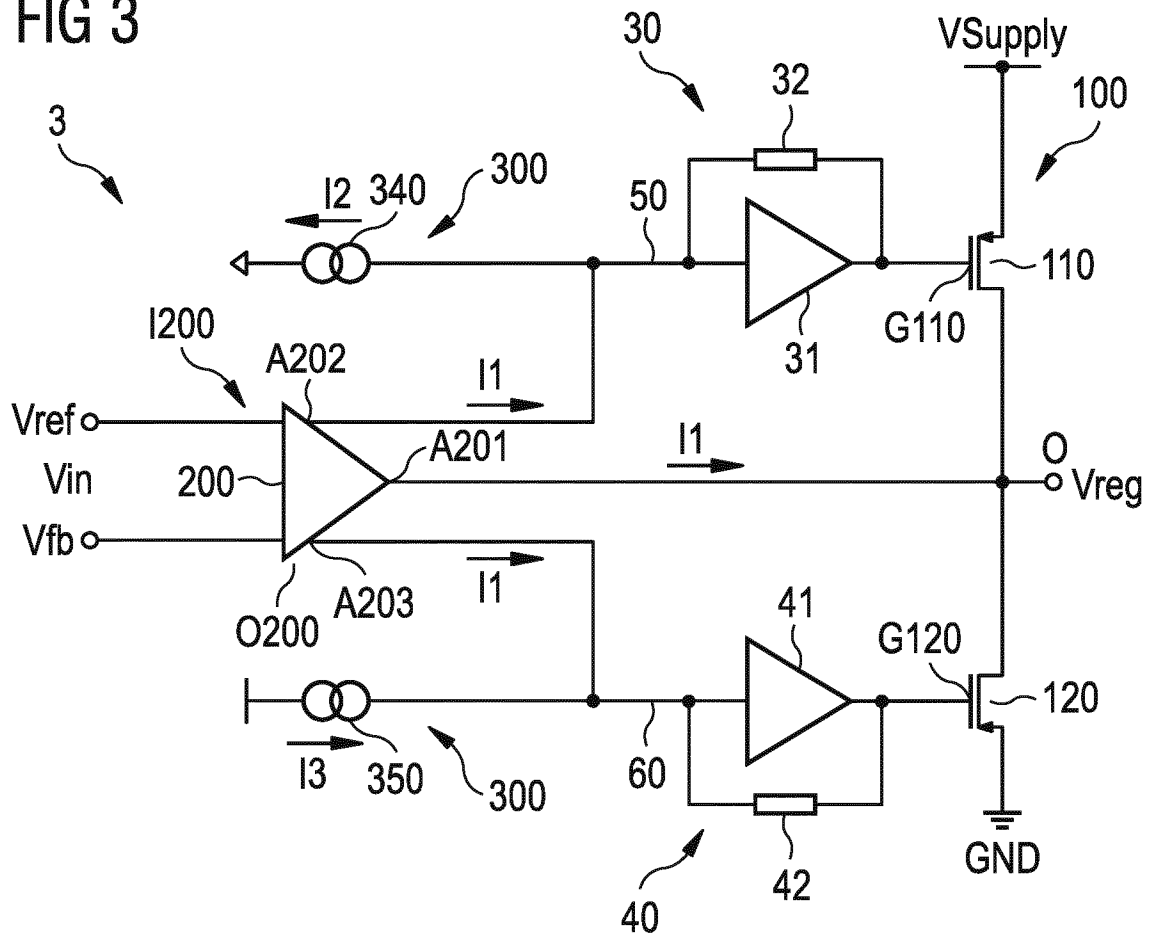


FIG 4

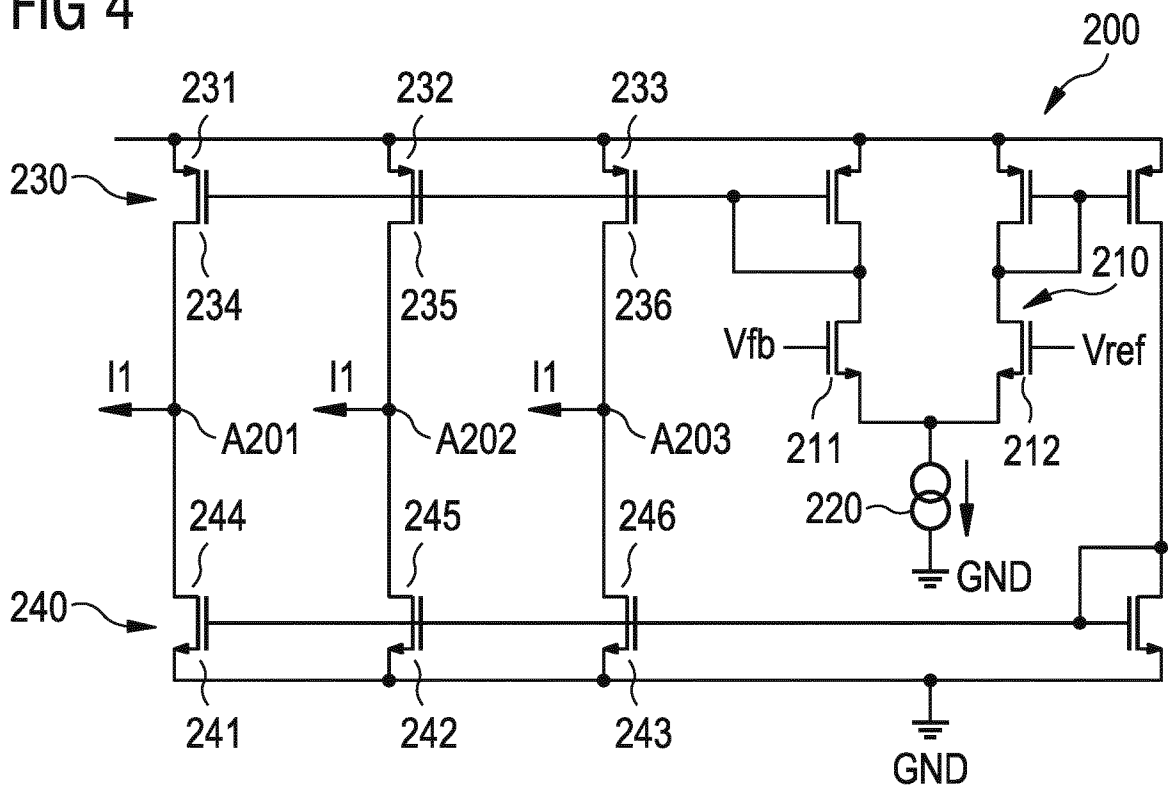


FIG 5

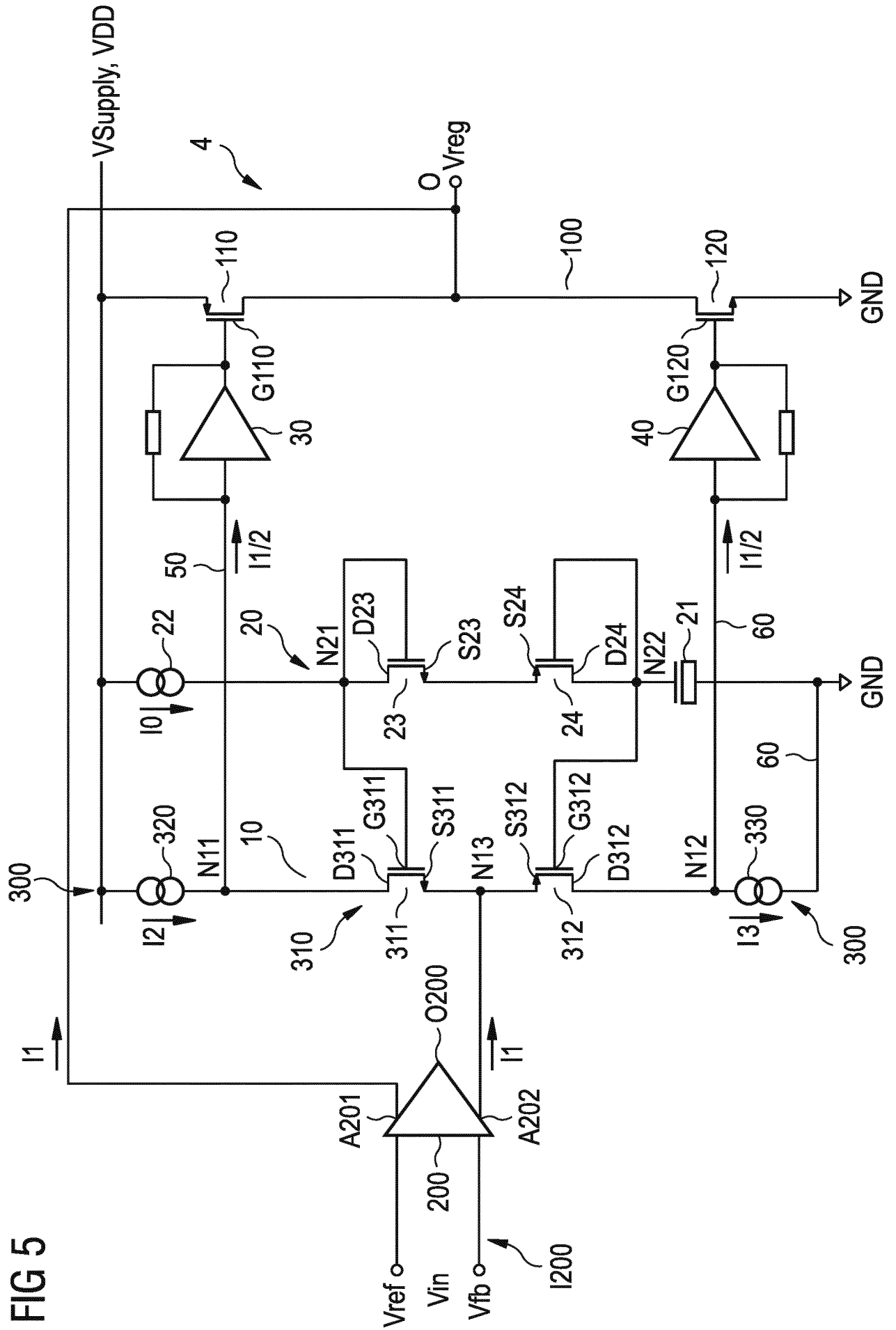
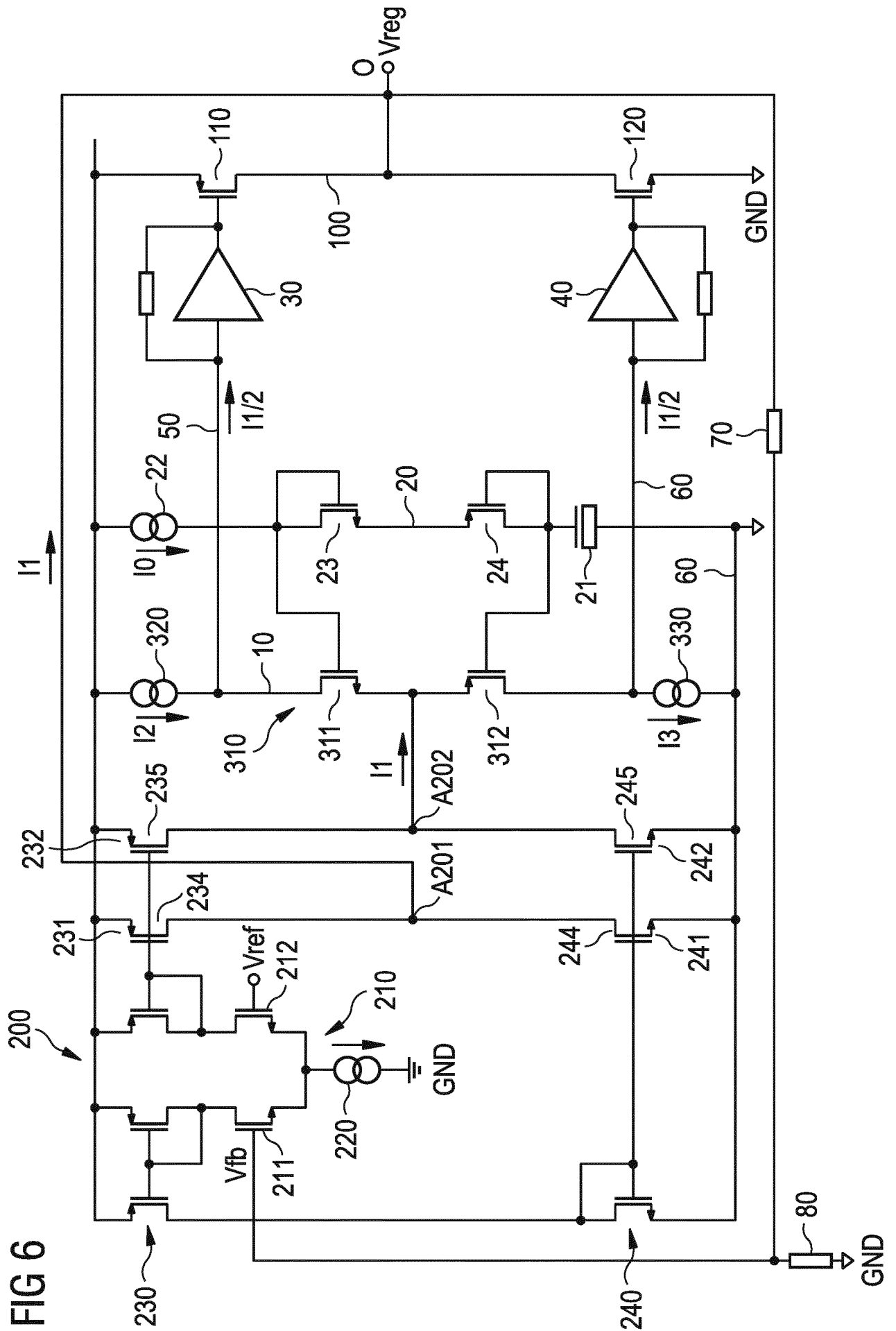


FIG 6



INTERNATIONAL SEARCH REPORT

International application No
PCT/EP2018/050732

A. CLASSIFICATION OF SUBJECT MATTER
INV. G05F1/575
ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
G05F

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EP0-Internal

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Further documents are listed in the continuation of Box C.



See patent family annex.

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Date of the actual completion of the international search

12 March 2018

Date of mailing of the international search report

20/03/2018

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INTERNATIONAL SEARCH REPORT

International application No

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