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(19) **United States**(12) **Patent Application Publication**
Stone et al.(10) **Pub. No.: US 2021/0361286 A1**(43) **Pub. Date: Nov. 25, 2021**(54) **SOFT TISSUE REPAIR DEVICE AND METHOD**(71) Applicant: **Biomet Sports Medicine, LLC**,
Warsaw, IN (US)(72) Inventors: **Kevin T. Stone**, Winona Lake, IN (US);
Nathan M. Sautter, North Manchester, IN (US); **Brian K. Berelsman**, Warsaw, IN (US); **Jeffery D. Arnett**, Gilbert, AZ (US); **Joshua A. Butters**, Chandler, AZ (US); **Dylan M. Hushka**, Chandler, AZ (US); **Nicholas R. Slater**, Chandler, AZ (US)(21) Appl. No.: **17/392,971**(22) Filed: **Aug. 3, 2021****Related U.S. Application Data**

(60) Continuation of application No. 16/255,300, filed on Jan. 23, 2019, now Pat. No. 11,109,857, which is a continuation of application No. 15/332,590, filed on Oct. 24, 2016, now Pat. No. 10,265,064, which is a continuation of application No. 13/645,964, filed on Oct. 5, 2012, now Pat. No. 9,504,460, which is a division of application No. 12/570,854, filed on Sep. 30, 2009, now Pat. No. 8,303,604, which is a continuation-in-part of application No. 12/489,181, filed on Jun. 22, 2009, now Pat. No. 8,298,262, which is a continuation-in-part of application No. 12/474,802, filed on May 29, 2009, now Pat. No. 8,088,130, which is a continuation-in-part of application No. 11/541,506, filed on Sep. 29, 2006, now Pat. No. 7,601,165, which is a continuation-in-part of application No. 11/541,505, filed on Sep. 29, 2006, now Pat. No. 7,658,751, said application No. 13/645,964, said application No. 13/045,691 is a continuation-in-part of application No. 12/014,399, filed on Jan. 15, 2008, now Pat. No. 7,909,851, said application No. 13/645,964, said application No. 13/045,689 is a continuation-in-part of application No. 12/014,340, filed on Jan. 15, 2008, now Pat. No. 7,905,904, which is a continuation-in-part of application No. 11/935,681,

filed on Nov. 6, 2007, now Pat. No. 7,905,903, which is a continuation-in-part of application No. 11/869,440, filed on Oct. 9, 2007, now Pat. No. 7,857,830, which is a continuation-in-part of application No. 11/408,282, filed on Apr. 20, 2006, now abandoned, which is a continuation-in-part of application No. 11/784,821, filed on Apr. 10, 2007, now Pat. No. 9,017,381, which is a continuation-in-part of application No. 11/347,661, filed on Feb. 3, 2006, now Pat. No. 7,749,250, which is a continuation-in-part of application No. 11/347,662, filed on Feb. 3, 2006, now abandoned, which is a continuation-in-part of application No. 10/983,236, filed on Nov. 5, 2004, now abandoned, said application No. 13/645,964 is a continuation-in-part of application No. 12/489,168,

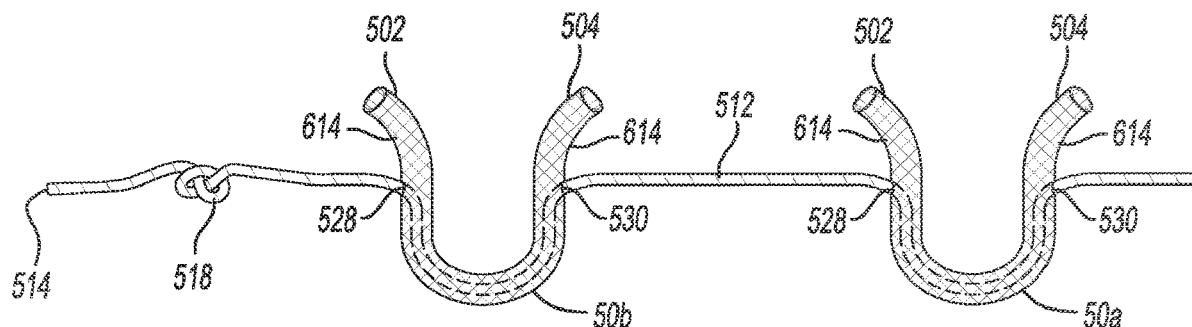
(Continued)

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(57)

ABSTRACT

A soft tissue repair device can include a housing having a handle, a deployment system having an actuation member, and an insertion system having an inserter and a slider. The slider can be coupled to the actuation member and movable relative to the inserter between deployed and retracted positions. First and second anchors can be carried on an external surface of the slider such that the anchors are spaced apart and portions of the anchors are coaxial with the slider and each other. A flexible strand can couple the anchors. The insertion system can cooperate with the deployment system to move the slider to the deployed position to deploy the first anchor upon activating the actuation member a first time, and to move the slider to the deployed position from the retracted position to deploy the second anchor upon actuating the actuation member a second time after the first time.



Related U.S. Application Data

filed on Jun. 22, 2009, now Pat. No. 8,361,113, which is a continuation-in-part of application No. 12/196,405, filed on Aug. 22, 2008, now Pat. No. 8,128,658, which is a continuation-in-part of application No. 12/196,407, filed on Aug. 22, 2008, now Pat. No.

8,137,382, which is a continuation-in-part of application No. 12/196,410, filed on Aug. 22, 2008, now Pat. No. 8,118,836.

- (60) Provisional application No. 60/885,062, filed on Jan. 16, 2007, provisional application No. 60/885,057, filed on Jan. 16, 2007.

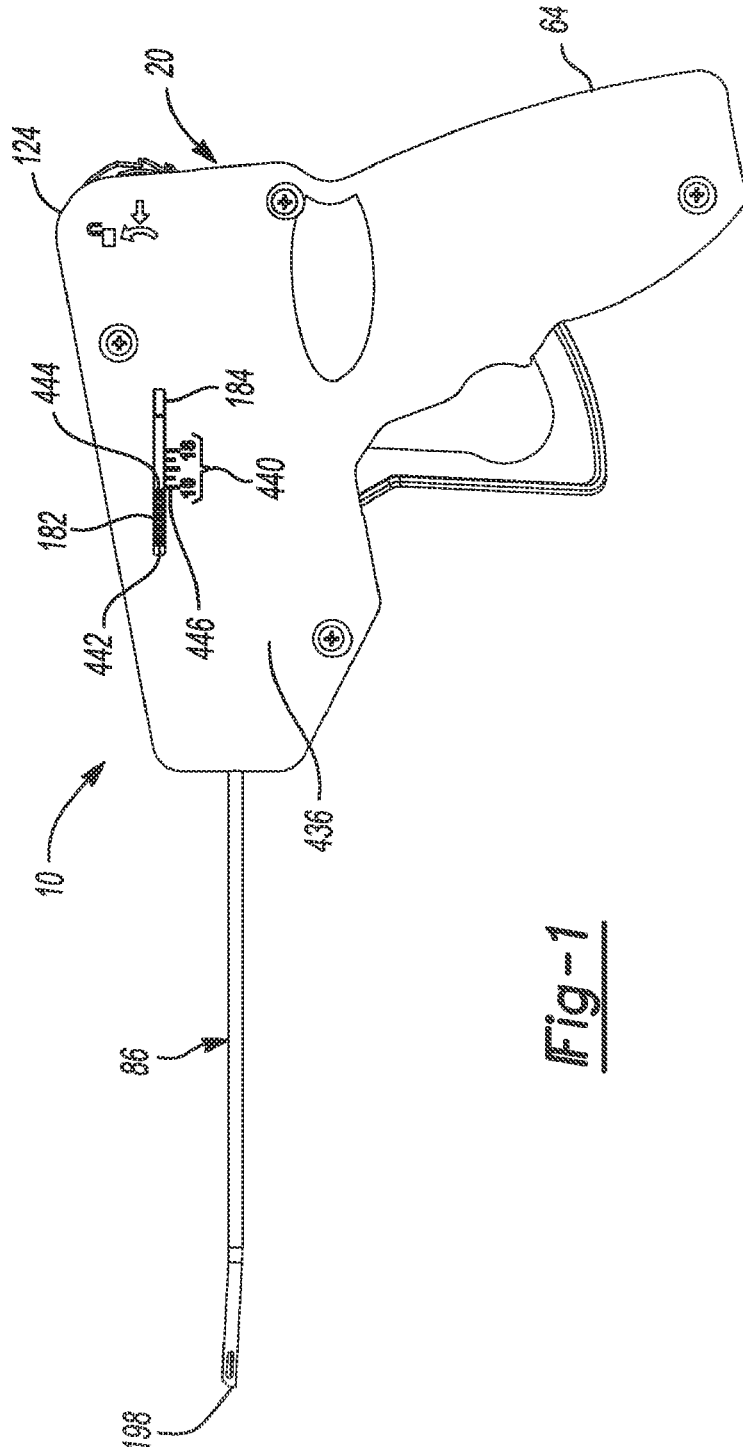


Fig-1

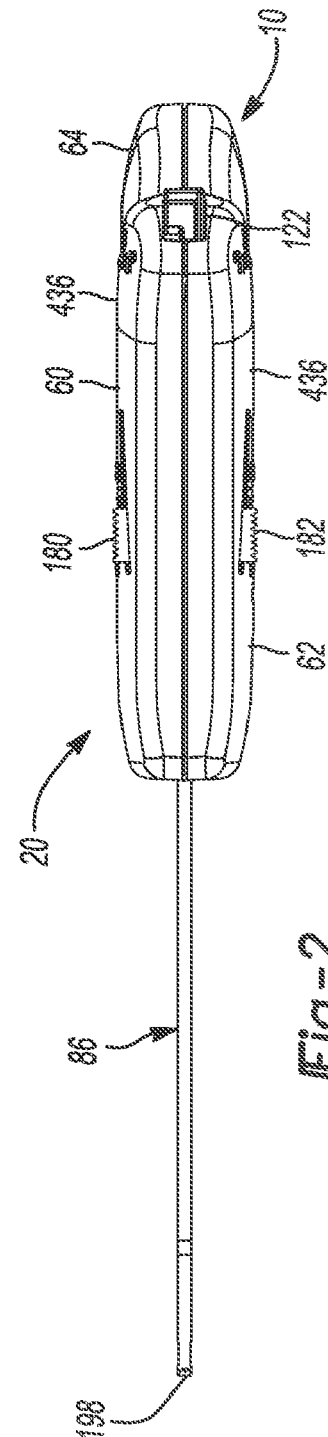
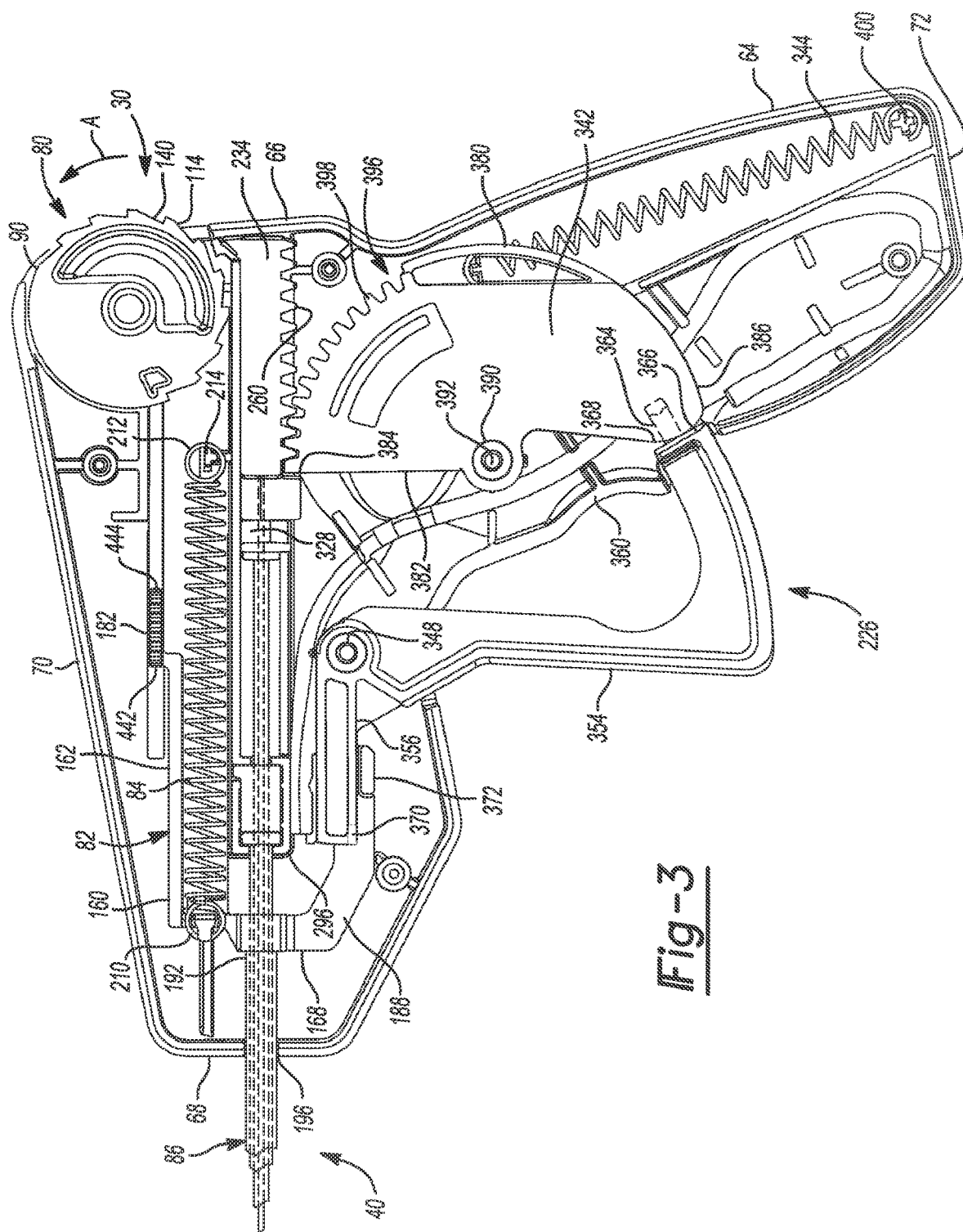
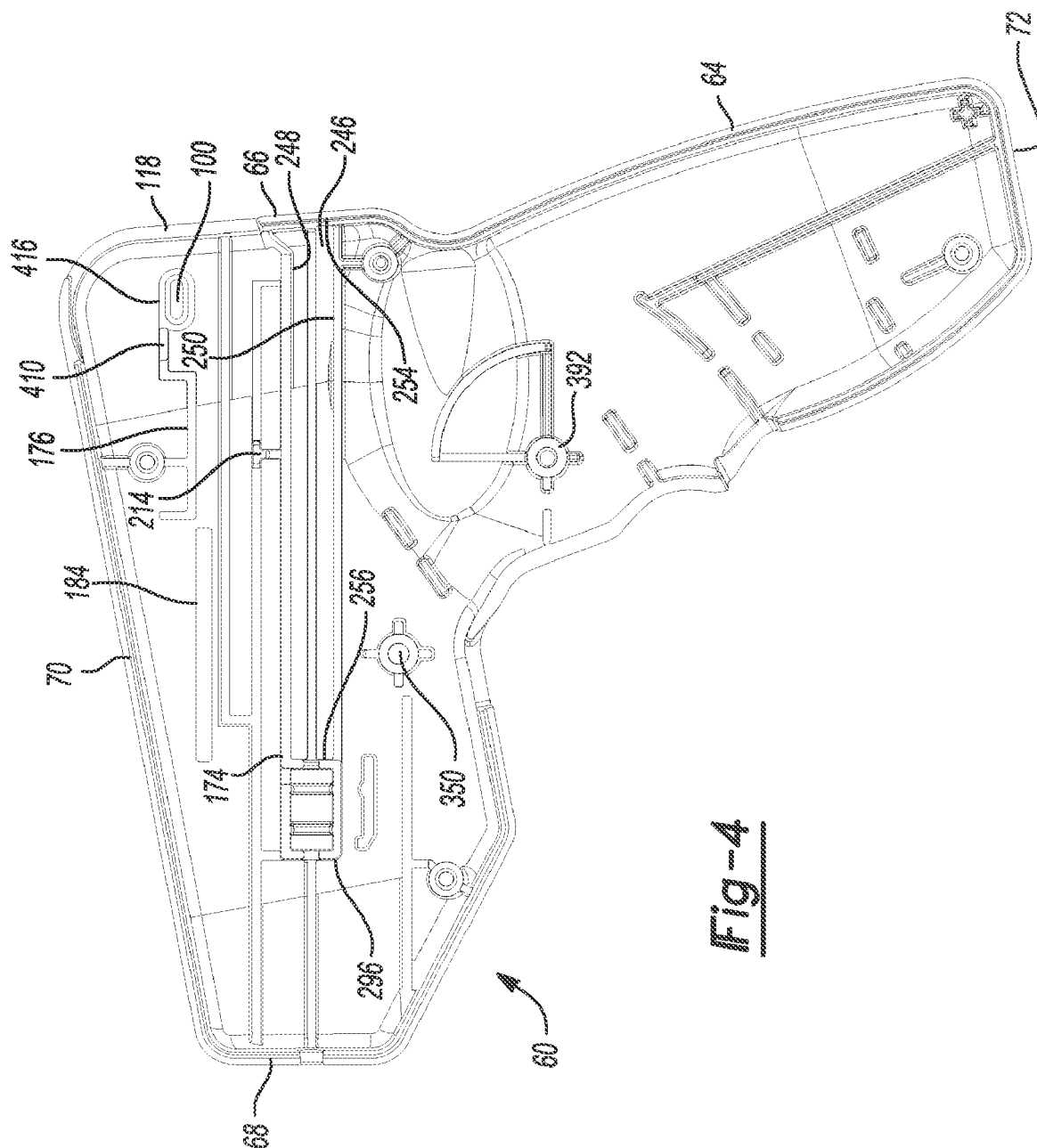
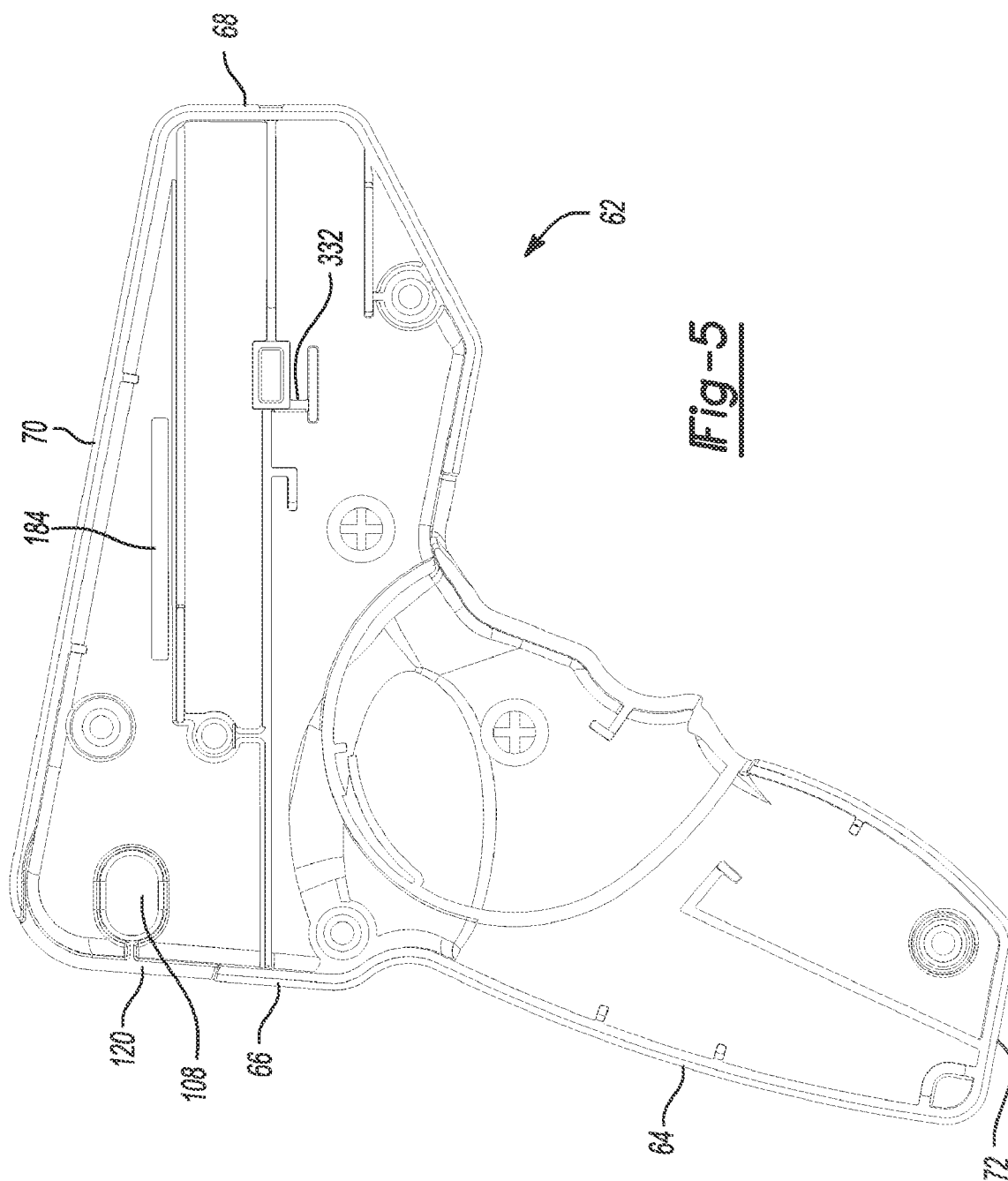
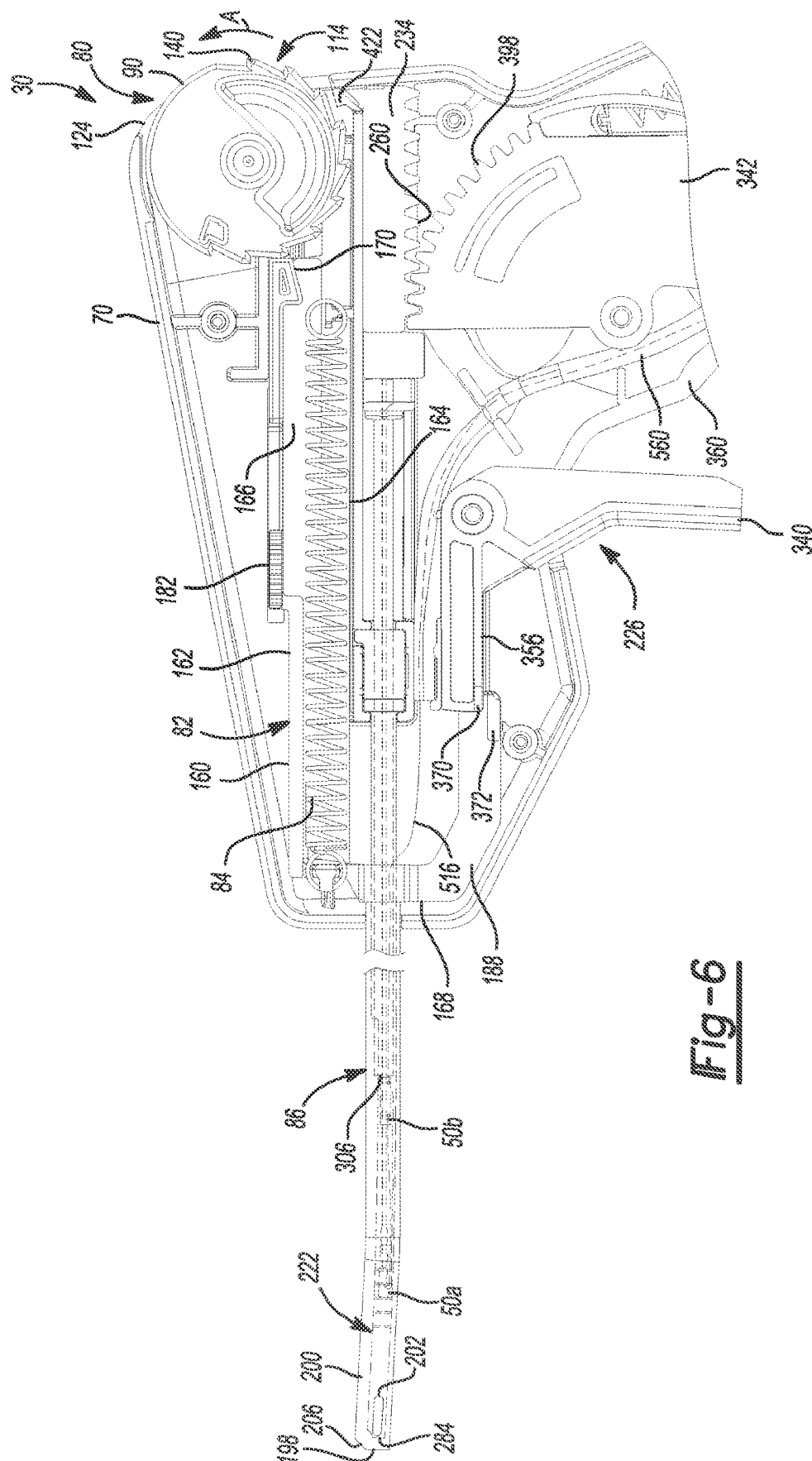


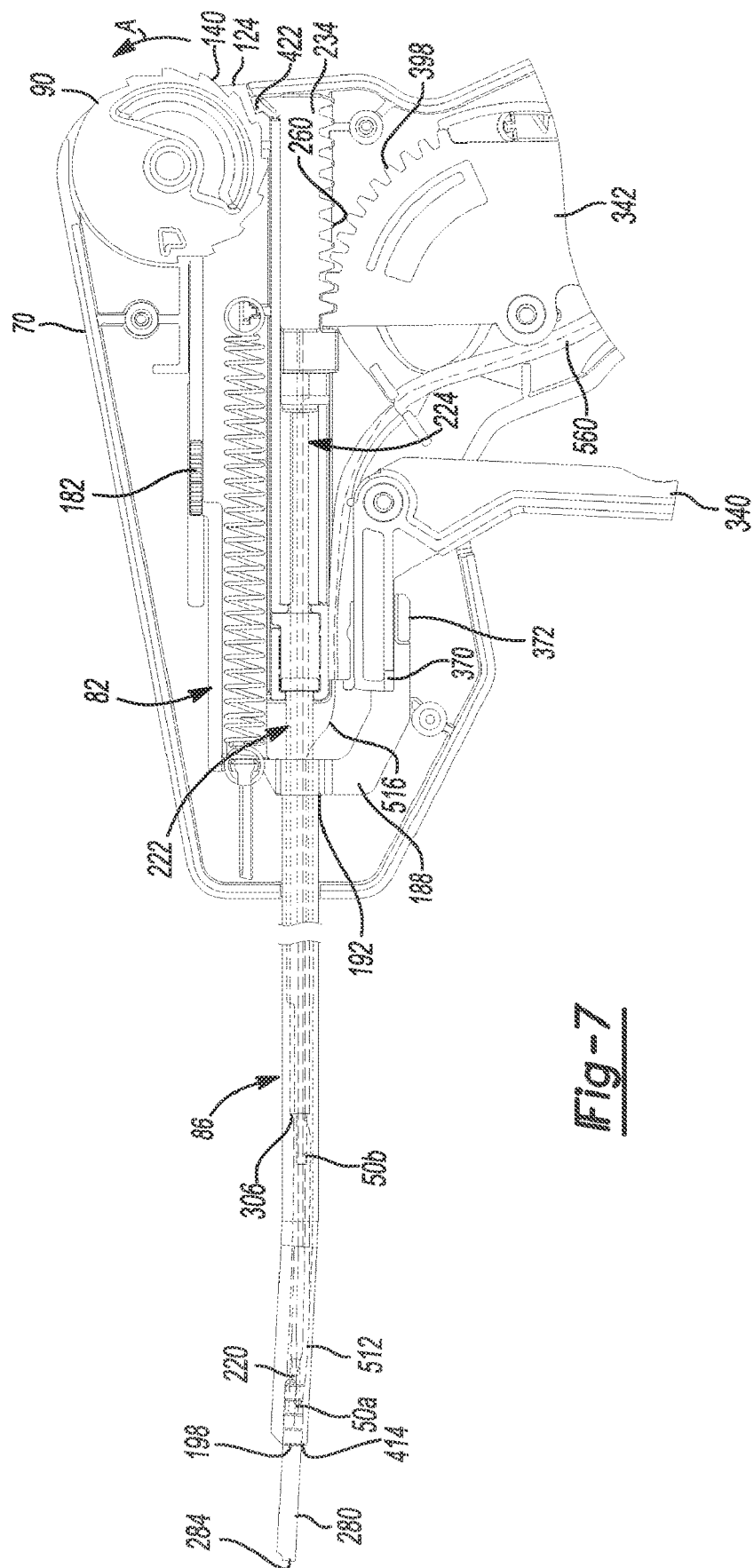
Fig-2

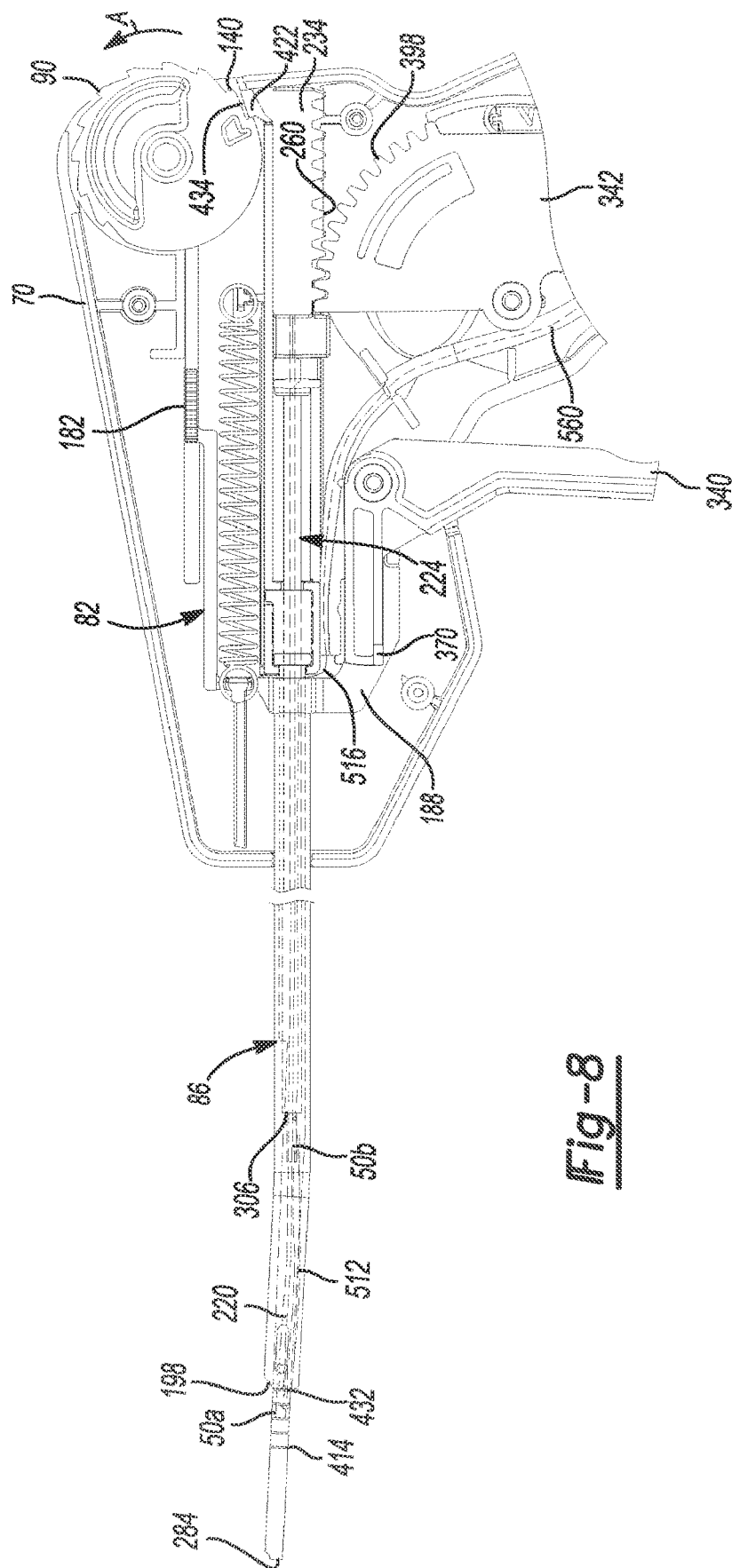












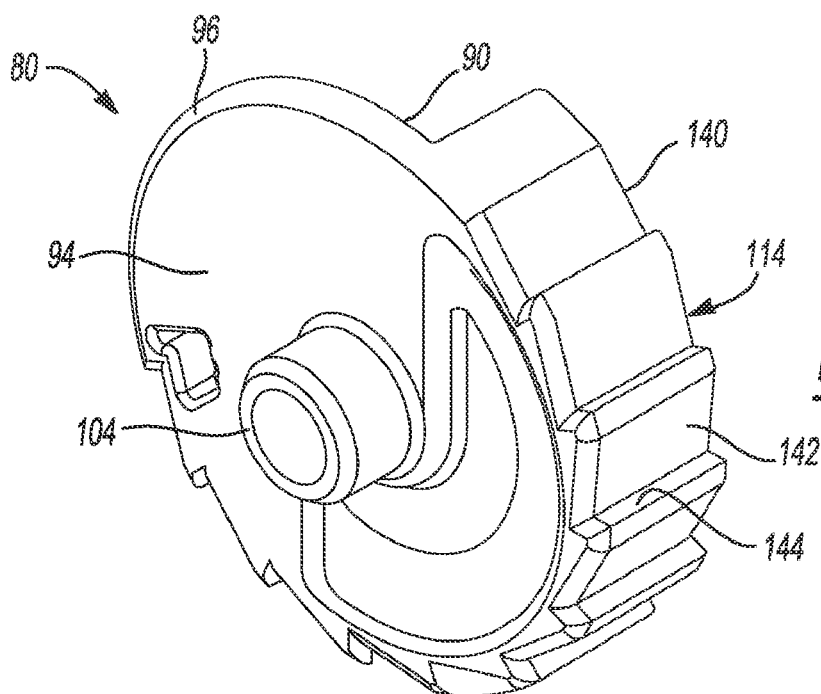


Fig-9A

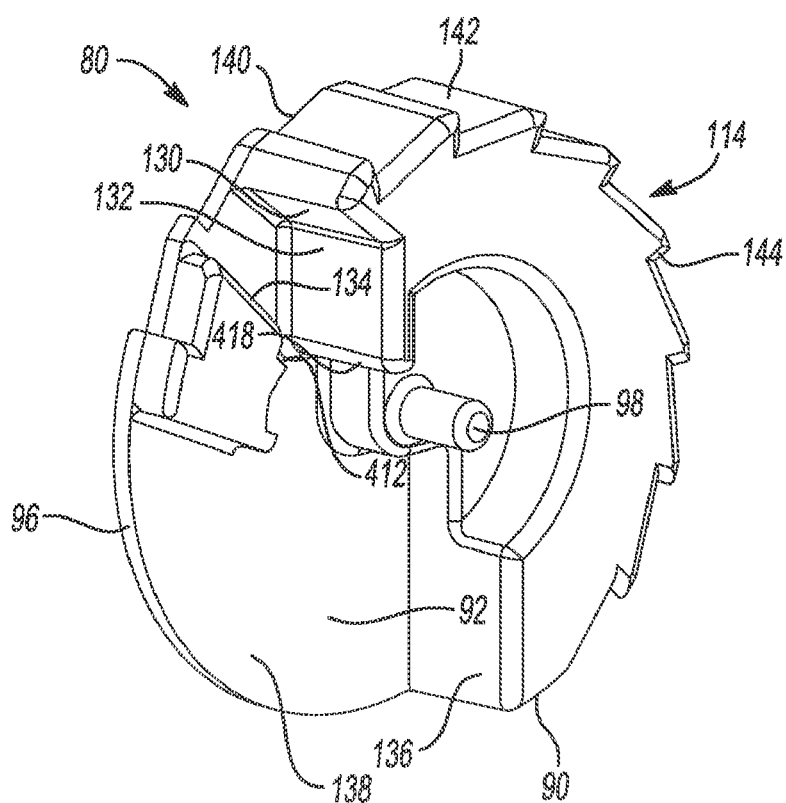
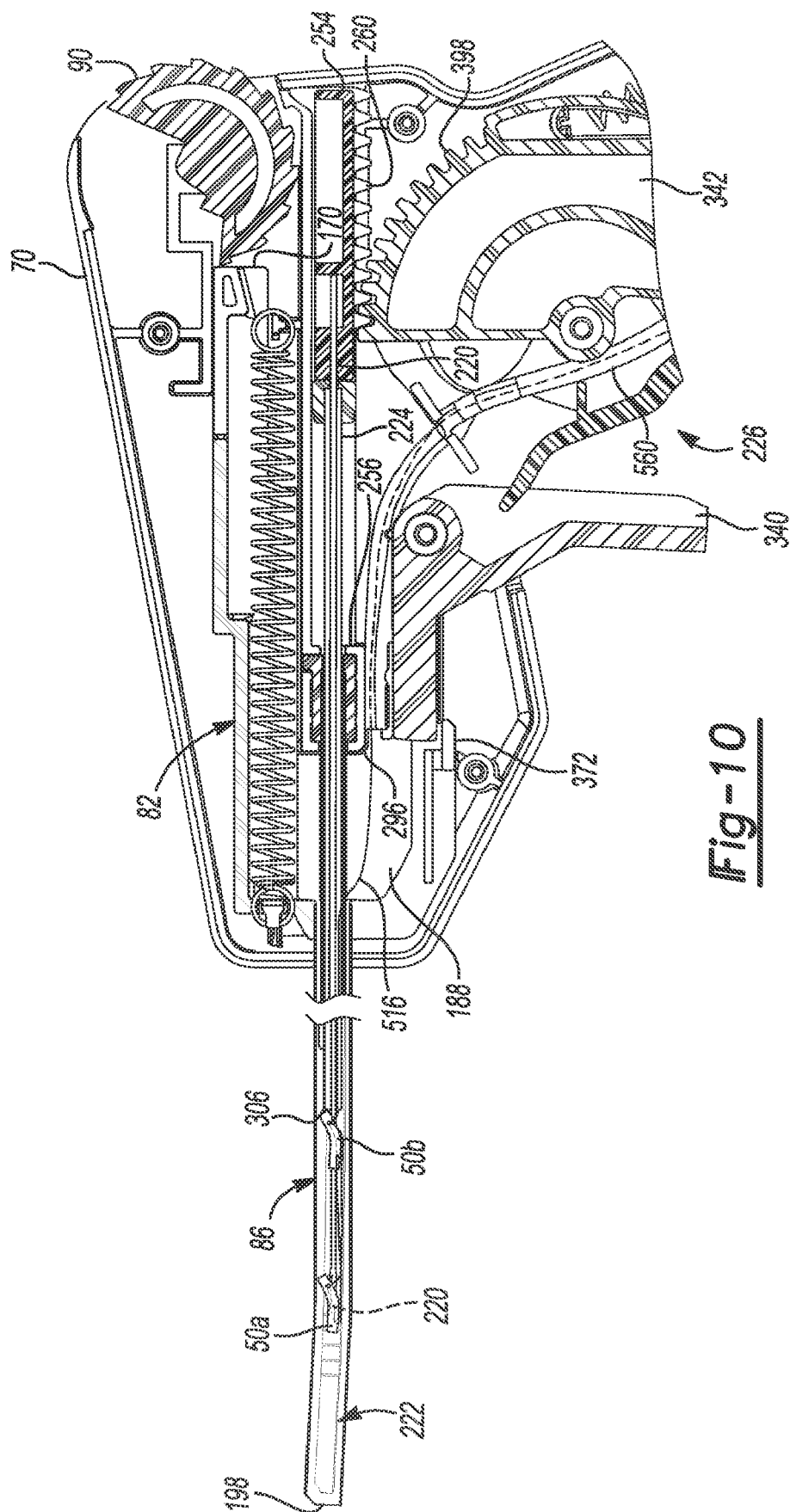


Fig-9B



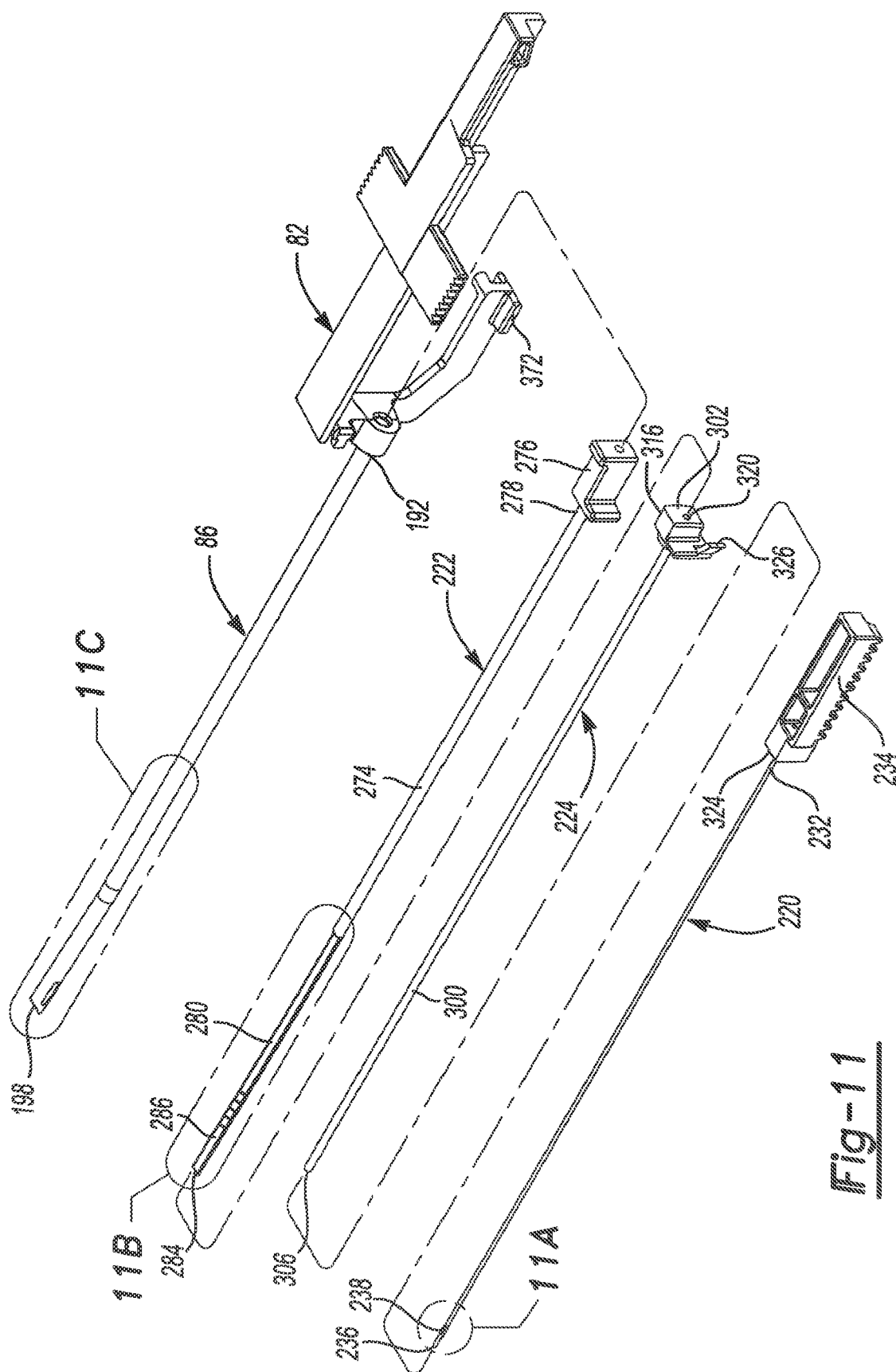


Fig-11

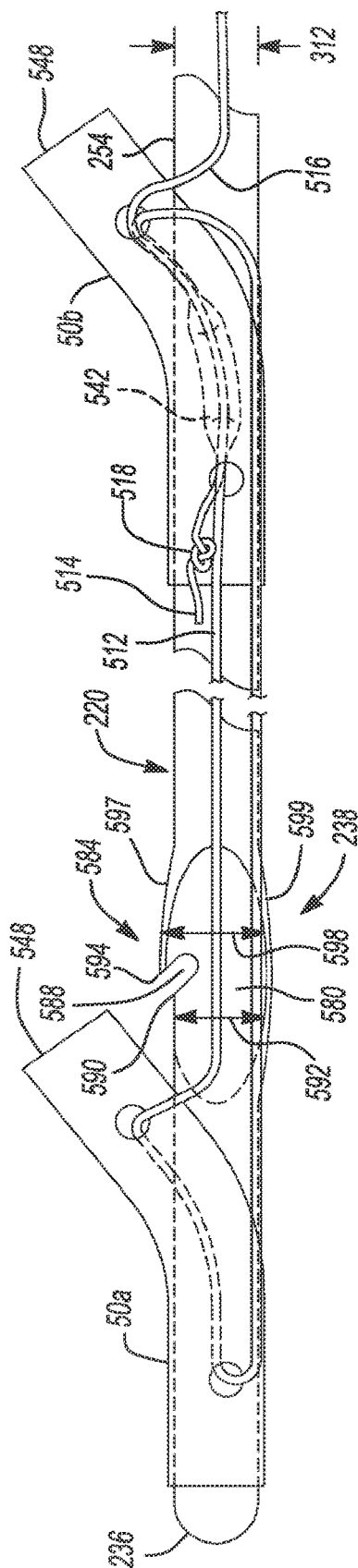


Fig-11A

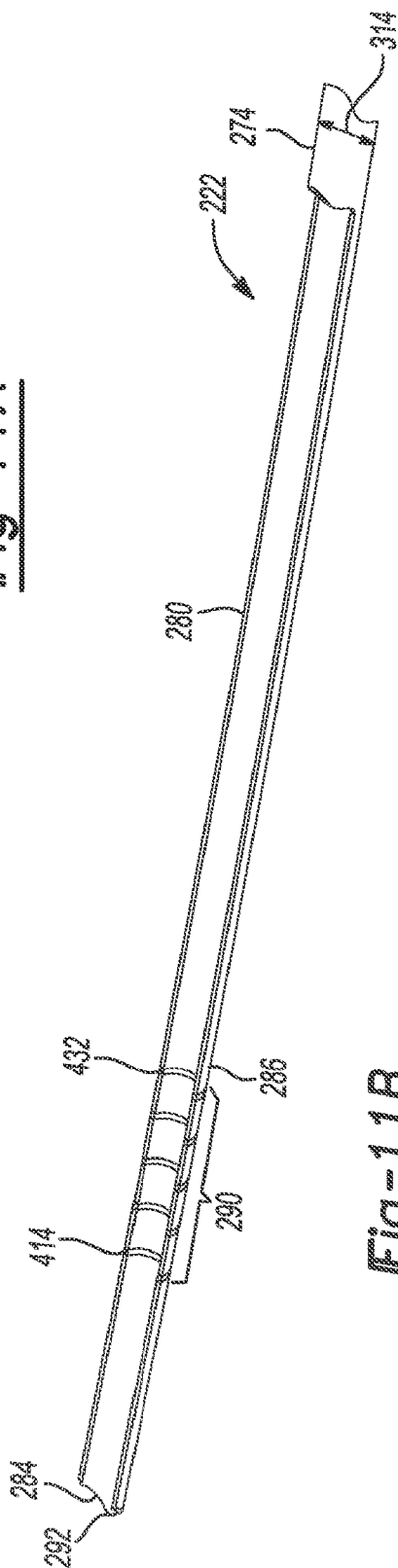


Fig-11B

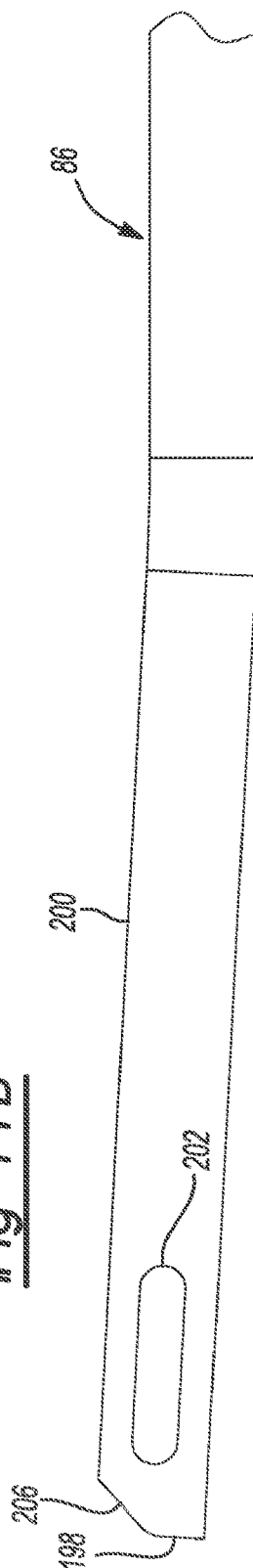


Fig-11C

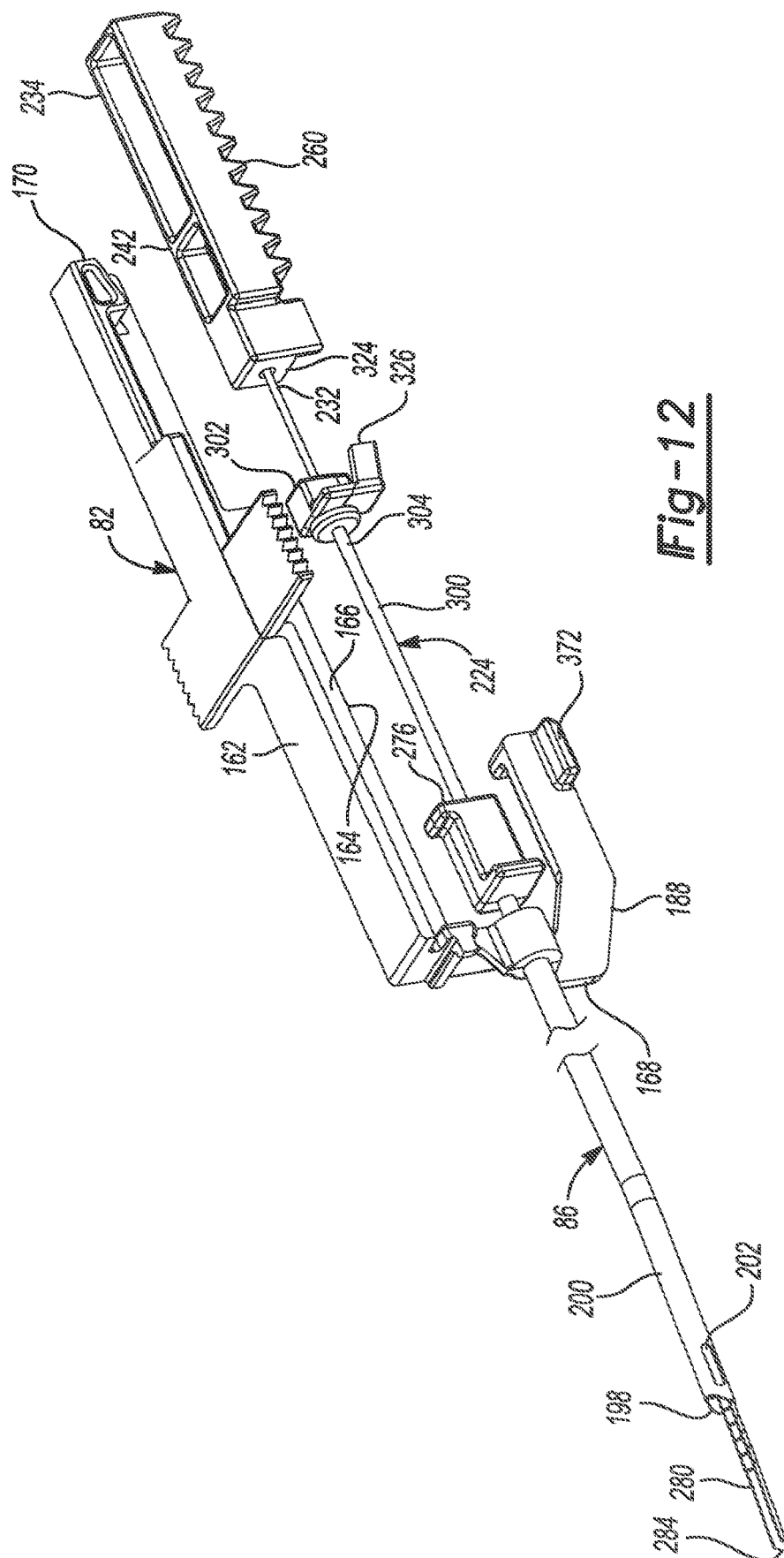


Fig-12

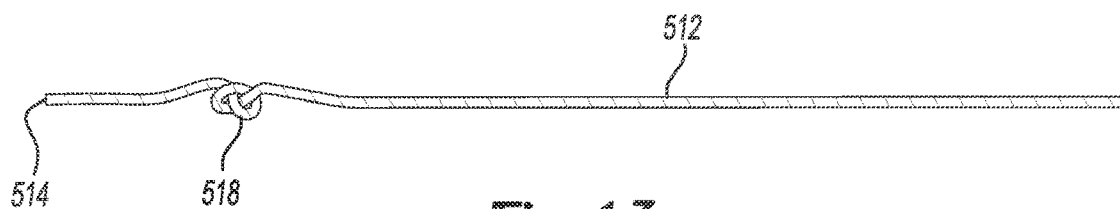


Fig-13

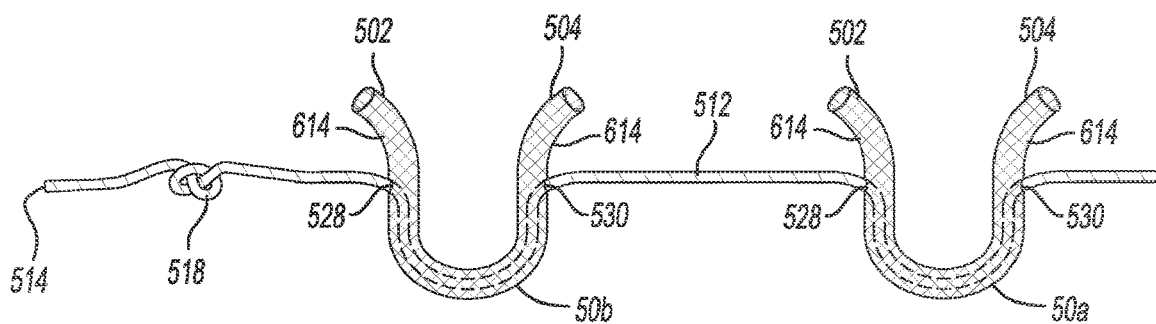


Fig-14

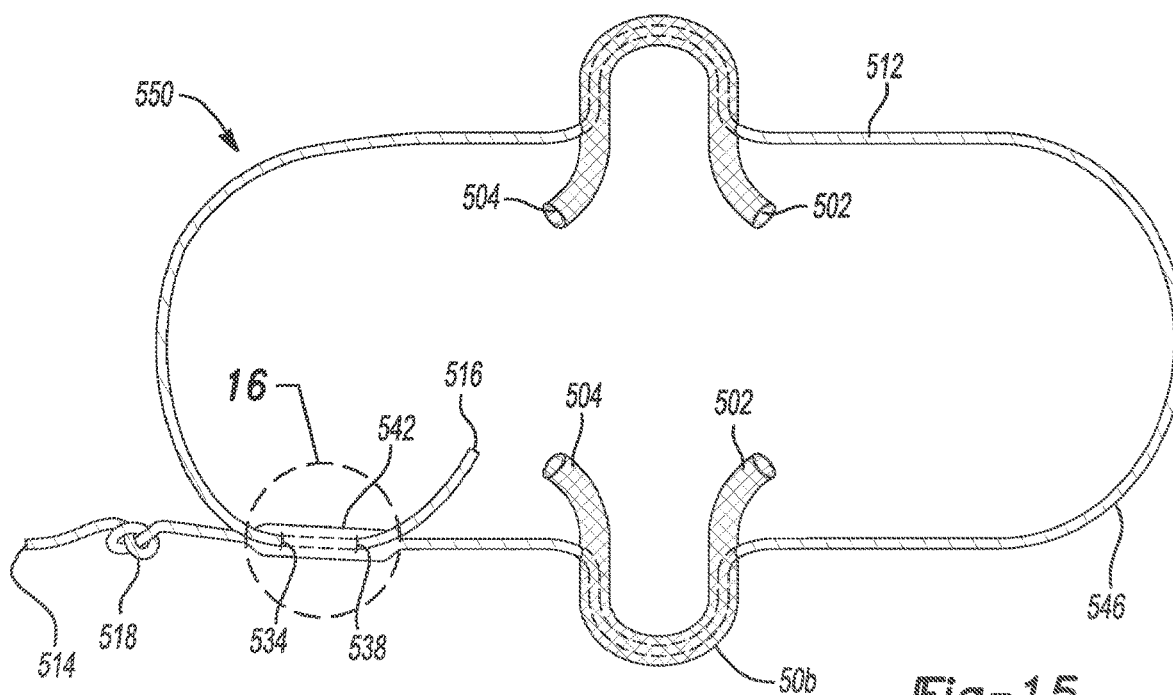


Fig-15

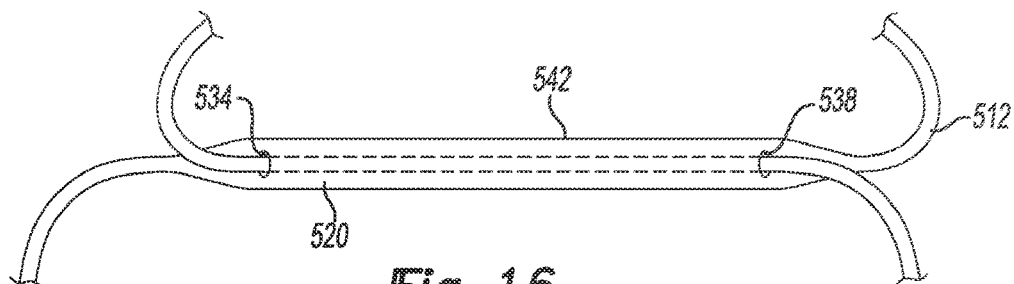


Fig-16

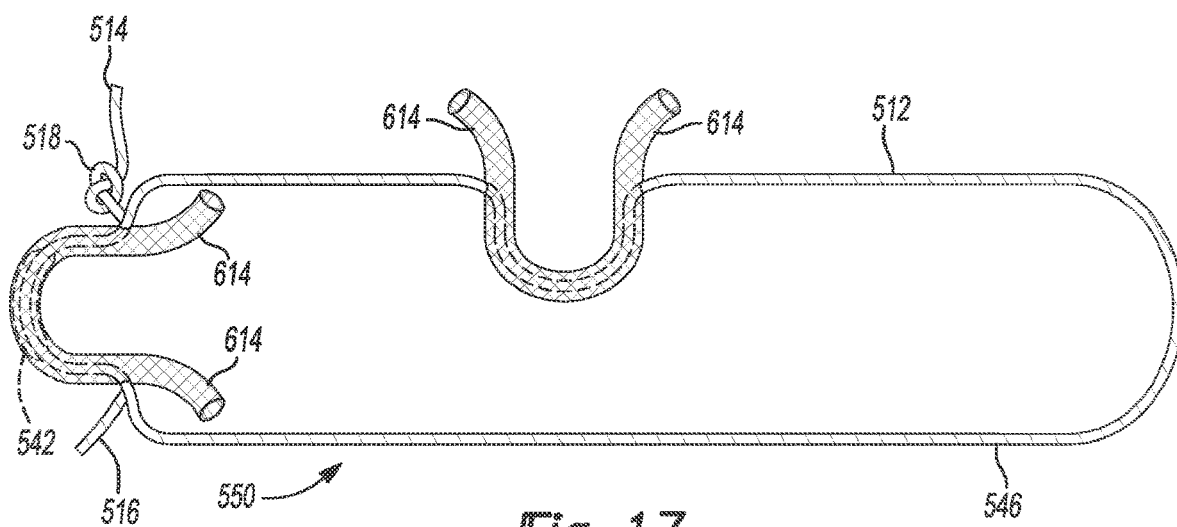


Fig-17

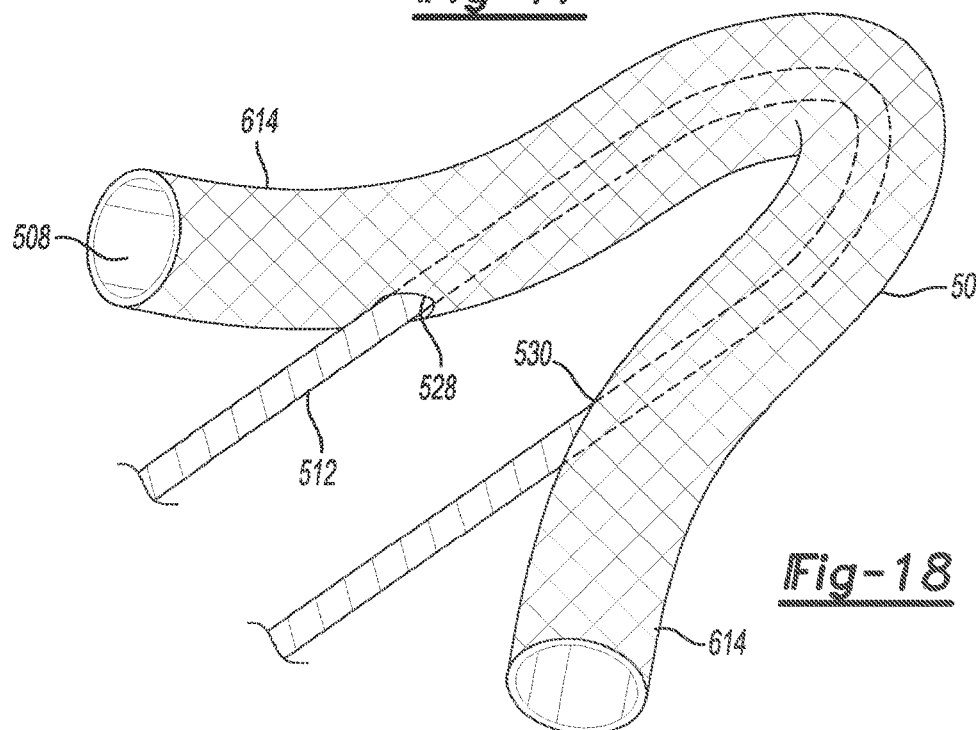
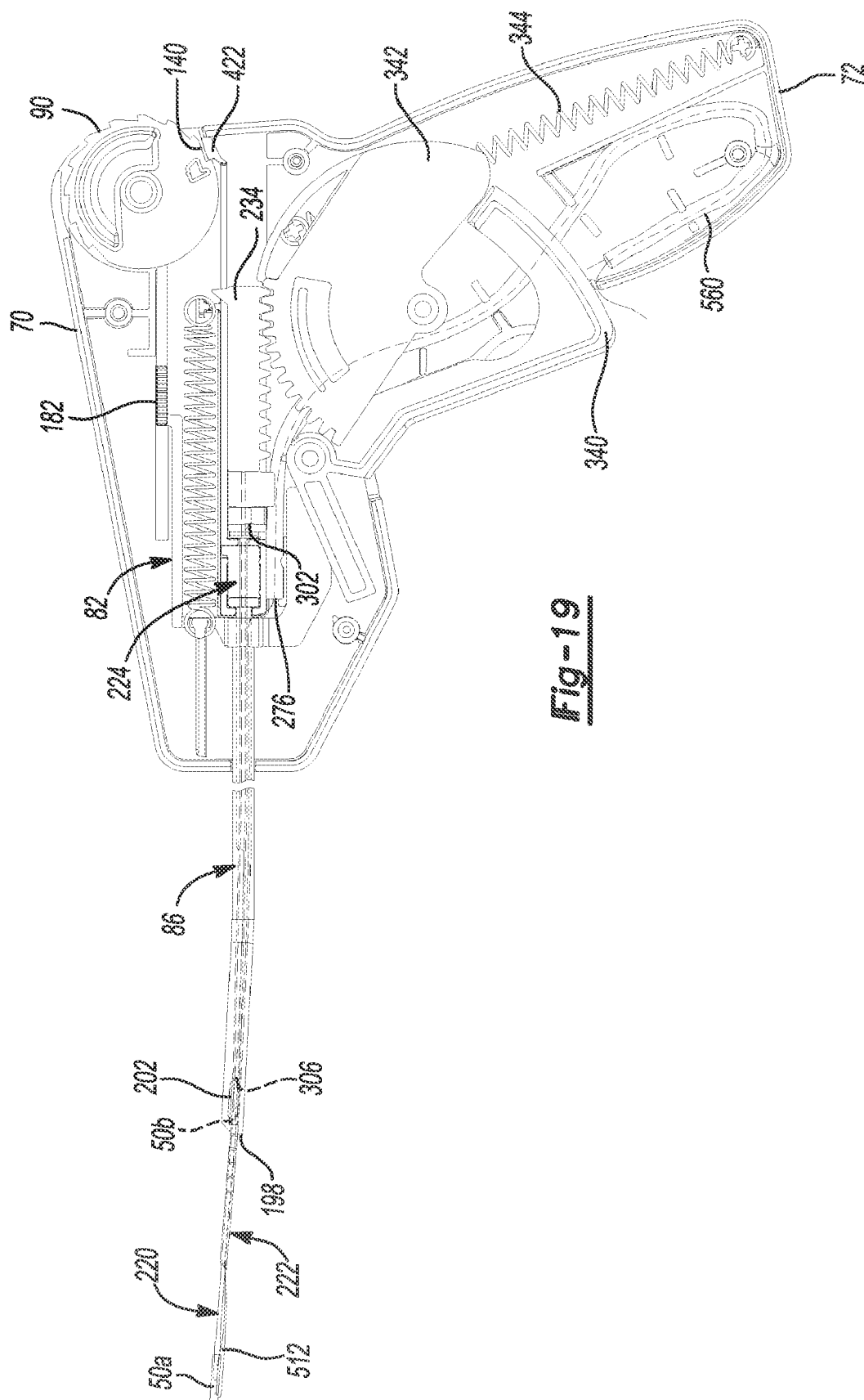


Fig-18



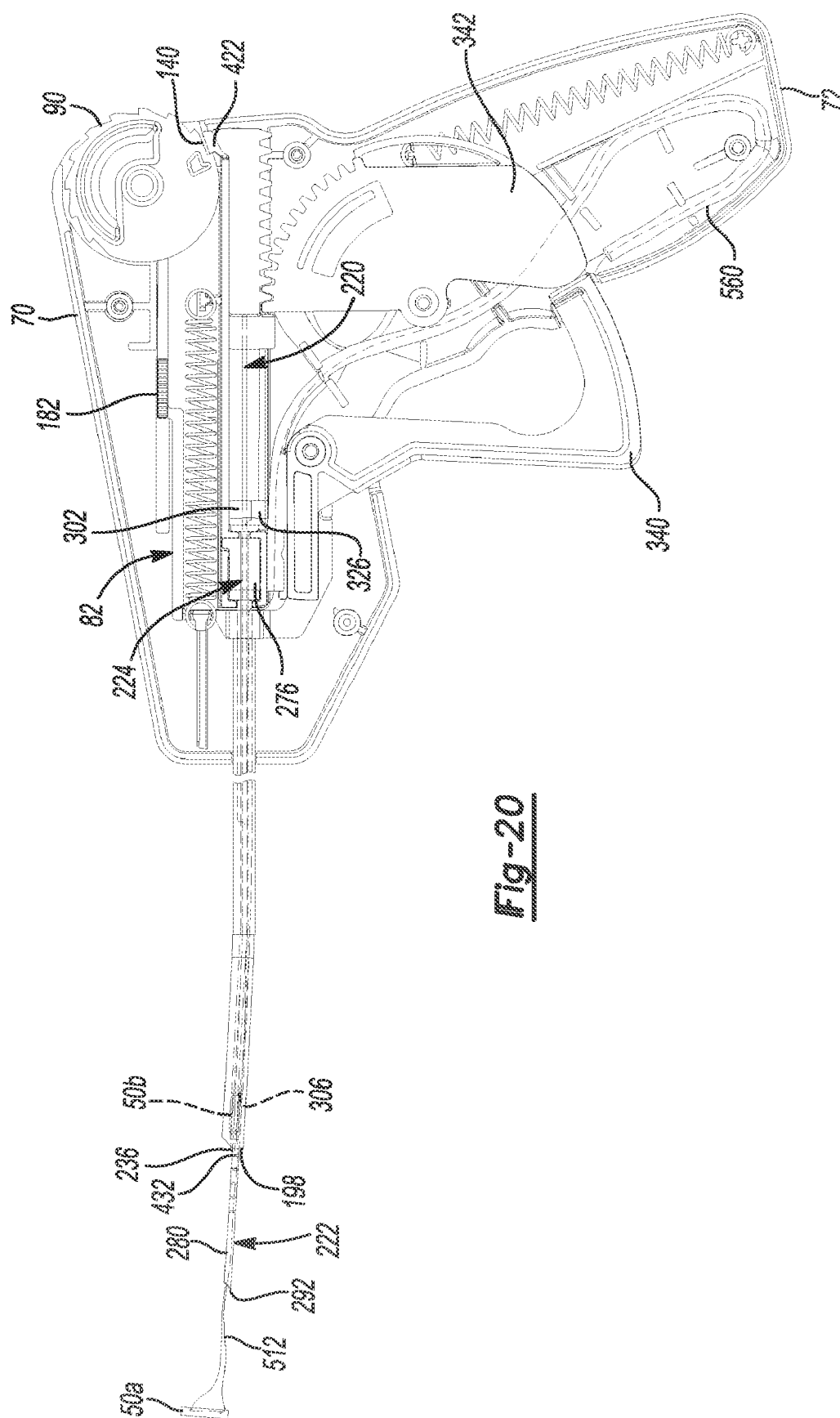
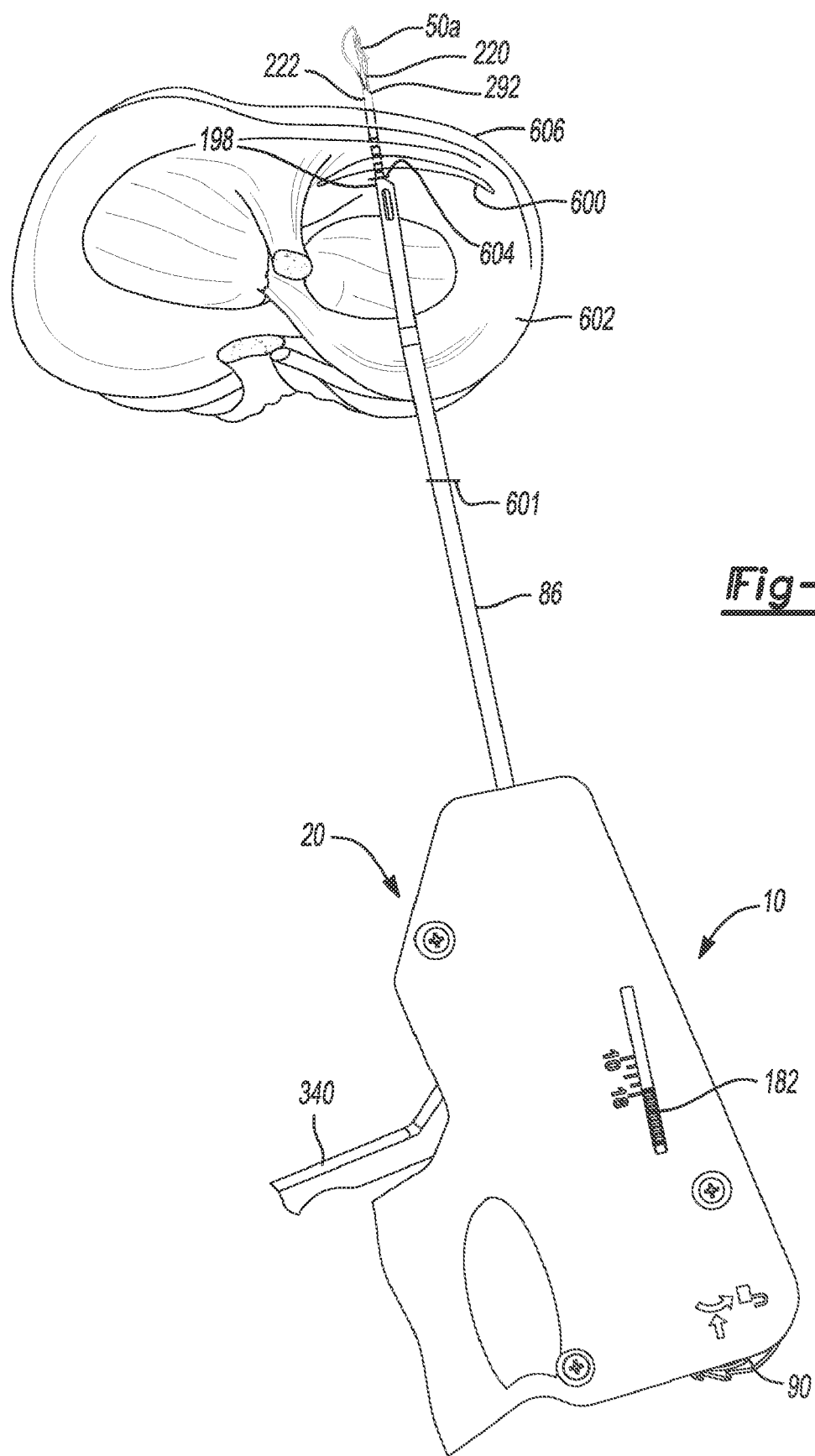
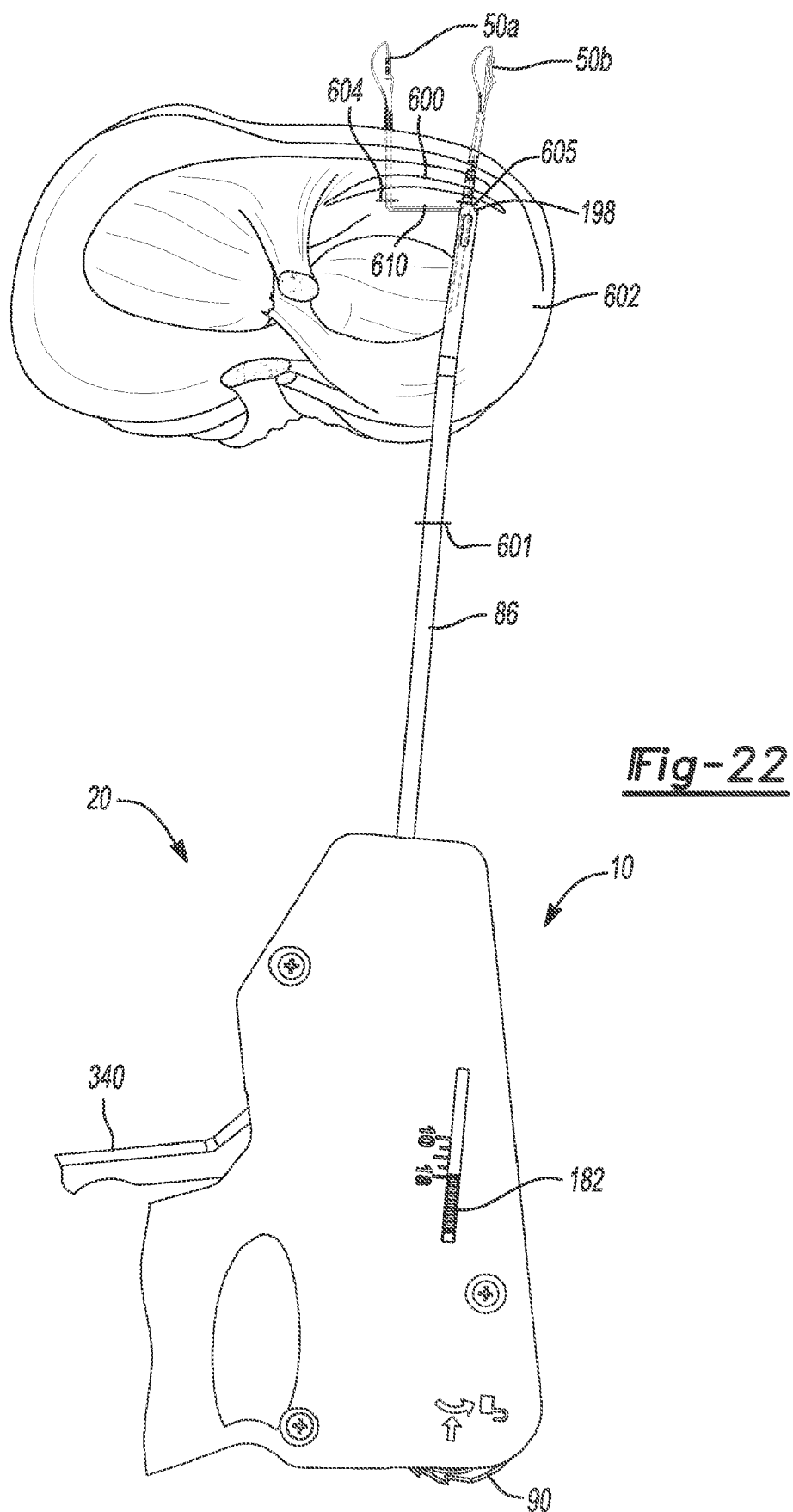


Fig-20





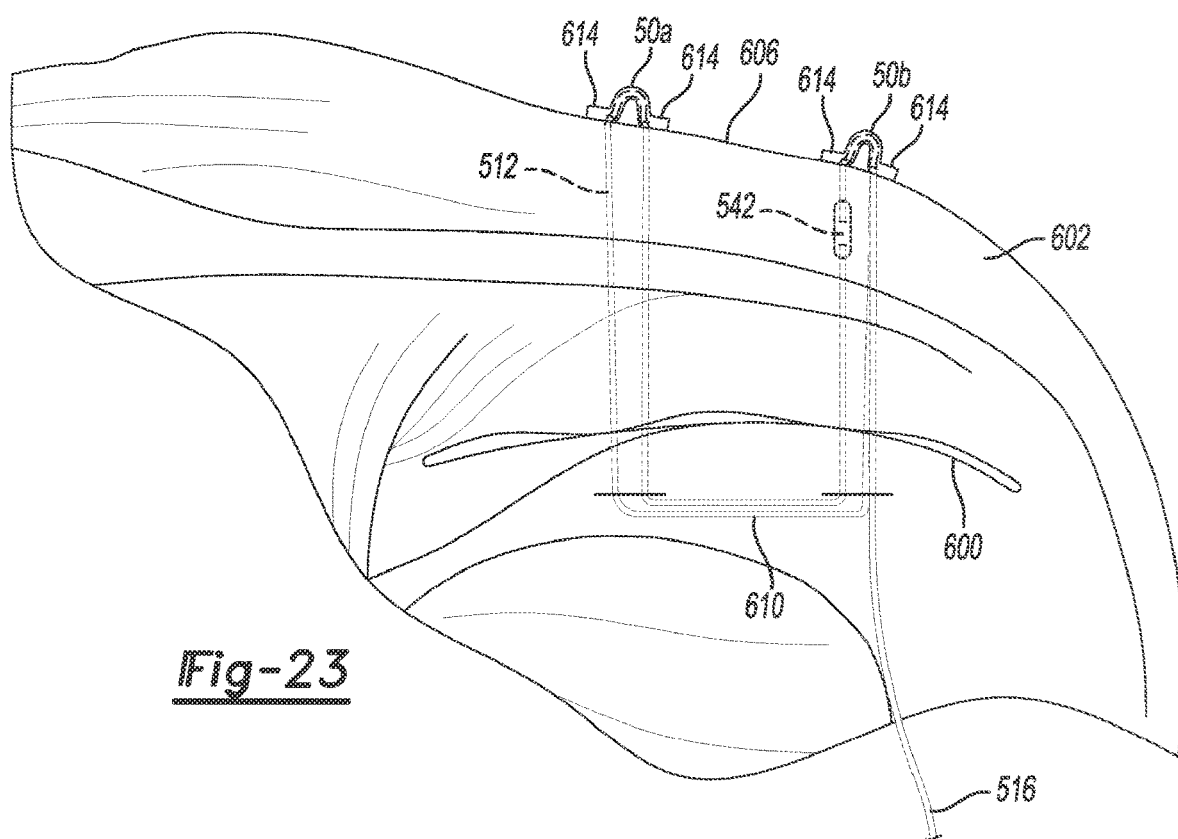


Fig-23

SOFT TISSUE REPAIR DEVICE AND METHOD

CROSS-REFERENCE TO RELATED APPLICATIONS

[0001] This application is a divisional of U.S. patent application Ser. No. 12/570,854 filed Sep. 30, 2009, which is a continuation-in-part application of U.S. patent application Ser. No. 12/489,181 filed Jun. 22, 2009, which is a continuation-in-part application of U.S. patent application Ser. No. 12/474,802 filed on May 29, 2009, now U.S. Pat. No. 8,088,130 issued on Jan. 3, 2012, which is a continuation-in-part application of: (1.) U.S. patent application Ser. No. 11/541,506 filed on Sep. 29, 2006, now U.S. Pat. No. 7,601,165 issued on Oct. 13, 2009, and (2.) U.S. patent application Ser. No. 11/541,505 filed on Sep. 29, 2006, now U.S. Pat. No. 7,658,751 issued on Feb. 9, 2010.

[0002] This application is a divisional of U.S. patent application Ser. No. 13/045,691 filed on Mar. 11, 2011, which is a continuation-in-part application of U.S. patent application Ser. No. 12/014,399 filed on Jan. 15, 2008, now U.S. Pat. No. 7,909,851 issued on Mar. 22, 2011, which claims the benefit of: (1.) U.S. Provisional Application No. 60/885062, filed on Jan. 16, 2007, and (2.) U.S. Provisional Application No. 60/885057, filed on Jan. 16, 2007.

[0003] This application is a divisional of United States Patent Application No. 13/045,689 filed on Mar. 11, 2011, which is a continuation-in-part application of U.S. patent application Ser. No. 12/014,340 filed on Jan. 15, 2008, now U.S. Pat. No. 7,905,904 issued on Mar. 15, 2011, which is a continuation-in-part application of: (1.) U.S. patent application Ser. No. 11/935,681 filed on Nov. 6, 2007, now U.S. Pat. No. 7,905,903 issued on Mar. 15, 2011, and (2.) U.S. patent application Ser. No. 11/869,440 filed on Oct. 9, 2007, now U.S. patent application Ser. No. 7,857,830 issued on Dec. 28, 2010, which is a continuation-in-part of: (1.) U.S. patent application Ser. No. 11/408,282 filed on Apr. 20, 2006 and is now abandoned, (2.) U.S. patent application Ser. No. 11/784,821 filed on Apr. 10, 2007, (3.) U.S. patent application Ser. No. 11/347,661 filed on Feb. 3, 2006 now U.S. Pat. No. 7,749,250 issued on Jul. 6, 2010, (4.) U.S. patent application Ser. No. 11/347,662 filed on Feb. 3, 2006 and is now abandoned, which is a continuation-in-part of U.S. patent application Ser. No. 10/983,236 filed on Nov. 5, 2004 and is now abandoned.

[0004] This application is also a continuation-in-part of U.S. patent application Ser. No. 12/489,168 filed Jun. 22, 2009, which is a continuation-in-part of: (1.) U.S. patent application Ser. No. 12/196,405 filed on Aug. 22, 2008, now U.S. Pat. No. 8,128,658 issued on Mar. 5, 2009, U.S. patent application Ser. No. 12/196,407 filed on Aug. 22, 2008, now U.S. Pat. No. 8,137,382 issued on Mar. 20, 2012, and (3.) U.S. patent application Ser. No. 12/196,410, filed on Aug. 22, 2008, now U.S. Pat. No. 8,118,836 issued on Feb. 21, 2012.

[0005] The disclosures of all of the above applications are hereby incorporated by reference.

FIELD

[0006] The present teachings relate generally to soft tissue repair and, more particularly, to a device and associated method for repairing a tear in soft tissue.

INTRODUCTION

[0007] Tears caused by trauma or disease in soft tissue, such as cartilage, ligament, or muscle, can be repaired by suturing. Various repair devices have been developed for facilitating suturing and are effective for theft intended purposes. Nevertheless, tissue repair devices for facilitating suturing are still desirable.

SUMMARY

[0008] This section provides a general summary of the disclosure, and is not a comprehensive disclosure of its full scope or all of its features.

[0009] According to one aspect, the present teachings provide a soft tissue repair device. The device can include a housing having a handle, a deployment system having an actuation member, and an insertion system having an inserter and a slider. The slider can be coupled to the actuation member and movable relative to the inserter between deployed and retracted positions. At least a portion of a first anchor can be carried on an external surface of the slider in a first position, and at least a portion of a second anchor can be carried on the external surface of the slider in a second position that is longitudinally spaced apart from the first anchor position such that the portions of the first and second anchors are co-axial with the slider and each other. A flexible strand can couple the first and second anchors. The insertion system can be operable to cooperate with the deployment system to move the slider from the retracted position to the deployed position to deploy the first anchor upon actuating the actuation member at a first time, and to move the slider from the retracted position to the deployed position to deploy the second anchor upon actuating the actuation member a second time after the first time.

[0010] According to another aspect, the present teaching provide a method for repairing a tear in soft tissue. The method can include coupling first and second flexible anchors with a flexible strand, providing an insertion device having a housing with a pistol grip handle, an inserter and a slider carried in the inserter such that the inserter and the slider each have a distal end extending from the housing. The first and second coupled anchors can be loaded on an external surface of the slider, and the inserter can be inserted through the soft tissue from a first side of the tear to a second side of the tear. An actuation member protruding from the pistol grip handle can be actuated at a first time to translate a distal end of the slider beyond a distal end of the inserter so as to deploy the first anchor. The actuation member can be released after deploying the first anchor, the inserter can be inserted through the soft tissue for a second time in a second position, and the actuation member can be actuated at a second time after the first time to extend the distal end of the slider beyond the distal end of the inserter and deploy the second anchor. The method can further include removing the inserter from the soft tissue, tensioning the flexible strand and reducing the tear.

[0011] Further areas of applicability will become apparent from the description provided herein. The description and specific examples in this summary are intended for purposes of illustration only and are not intended to limit the scope of the present disclosure.

BRIEF DESCRIPTION OF THE DRAWINGS

[0012] The present teachings will become more fully understood from the detailed description, the appended

claims and the following drawings. The drawings are for illustrative purposes only and are not intended to limit the scope of the present disclosure.

[0013] FIG. 1 is a side view of an exemplary tissue repair device according to the present teachings;

[0014] FIG. 2 is a top view of the exemplary tissue repair device according to the present teachings;

[0015] FIG. 3 is a partial side view of an exemplary configuration of the tissue repair device shown with a portion of the casing removed according to the present teachings;

[0016] FIG. 4 is a side view of a portion of the casing of the device of FIG. 1 according to the present teachings;

[0017] FIG. 5 is a side view of another portion of the casing of the device of FIG. 1 according to the present teachings;

[0018] FIG. 6 is a partial side view of the device of FIG. 1, shown in exemplary configuration according to the present teachings;

[0019] FIG. 7 is a partial side view of the device of FIG. 1, shown in another exemplary configuration according to the present teachings;

[0020] FIG. 8 is a partial side view of the device of FIG. 1, in another exemplary configuration according to teachings;

[0021] FIGS. 9A and 9B are perspective views of a cam member of the device of FIG. 1 according to the present teachings;

[0022] FIG. 10 is a partial sectional view of device of FIG. 1, shown in an exemplary configuration according to the present teachings;

[0023] FIG. 11 is an exploded perspective view of an exemplary carrying wire, positioning member, insertion member and outer cannula of the device of FIG. 1 according to the present teachings;

[0024] FIG. 11A is a partial exploded perspective view of the carrying wire of FIG. 11 having a pair of pre-loaded anchors according to the present teachings;

[0025] FIG. 11B is a partial exploded perspective view of the insertion member of FIG. 11 according to the present teachings;

[0026] FIG. 11C is a partial exploded perspective view of the outer cannula of FIG. 11 according to the present teachings;

[0027] FIG. 12 is a perspective view of the components of FIG. 11, shown in an exemplary assembled configuration according to the present teachings;

[0028] FIGS. 13, 14, 15 and 17 are sequential views illustrating an exemplary method and arrangement for coupling first and second flexible anchors with a flexible strand, and FIG. 16 shows a detail of FIG. 15 according to the present teachings;

[0029] FIG. 18 is a perspective view of a flexible anchor coupled with a flexible strand according to the present teachings;

[0030] FIG. 19 is a partial side view of the device of FIG. 1, shown in an exemplary configuration according to the present teachings;

[0031] FIG. 20 is a partial side view of the device of FIG. 1, shown in another exemplary configuration according to the present teachings;

[0032] FIG. 21 is an exemplary environmental view showing a first anchor being deployed outside of soft tissue according to the present teachings;

[0033] FIG. 22 is an exemplary environmental view showing first and second anchors being deployed outside of soft tissue according to the present teachings; and

[0034] FIG. 23 is another exemplary environmental view showing first and second anchors being deployed outside of soft tissue according to the present teachings.

DESCRIPTION OF VARIOUS ASPECTS

[0035] The following description is merely exemplary in nature and is in no way intended to limit the present disclosure, its application, or uses. For example, although the present teachings are illustrated in an application for meniscus repair in knee surgery, the present teachings can also be used for repairing any fibrous tissue, such as muscle, ligament or tendon in an arthroscopic or other open procedure, including rotator cuff reconstruction, acromioclavicular (AC) reconstruction, anterior cruciate ligament reconstruction (ACL) and generally for fastening tendons, grafts, or strands to fibrous tissue and bone.

[0036] With initial reference to FIGS. 1-6, an exemplary tissue repair device 10 according to the present teachings is illustrated. As will be further described below, the device 10 can include a casing 20 housing a depth limiting or positioning system 30 that cooperates with an insertion system 40, which can be preloaded with one or more flexible suture anchors 50 configured to be delivered into soft tissue. Two flexible suture anchors 50 are illustrated in various Figures, including FIG. 6, and will be generally referred to hereinafter as first and second flexible anchors 50a, 50b for clarification purposes. The casing 20 can include a two-part casing having a first half portion 60 arranged to engage a second half portion 62, such that together the half portions 60, 62 can form a pistol grip handle portion 64. Each casing portion 60, 62 can include a proximal end 66, a distal end 68, a top 70 and a bottom 72 generally located at a distal end of pistol grip handle portion 64. Casing 20 can be formed from plastic or any other suitable material.

[0037] The depth positioning system 30 can include a rotatable cam member 80, an axially moving translation member 82, a biasing member 84, and an axially moveable outer cannula 86. With continuing reference to FIGS. 1-6 and additional reference to FIGS. 7-9B, cam member 80 can include a thumbwheel 90 having a first side 92, a second side 94 and an outer periphery 96. The first side 92 can include a central first projection or post 98 extending from a center thereof that can be positioned in a corresponding slot 100 in first casing portion 60. In a similar manner, second side 94 can likewise include a central second projection or post 104 extending therefrom in an opposite direction as post 98 and can be positioned in a corresponding slot 108 in second casing portion 62. Slots 100, 108 can have a longitudinal length greater than a diameter of respective posts 98, 104 so as to provide for both translation and rotation of thumbwheel 90, as will be described in greater detail below.

[0038] Thumbwheel 90 can further include a toothed portion 114 disposed around a portion of outer periphery 96 and configured to be engagable by a user of the device 10. Casing portions 60, 62 can each include respective recesses 118, 120 that together form an opening 122 to facilitate a portion of thumbwheel 90 extending through the opening 122 and beyond a periphery 124 of casing 20, as shown for example in FIGS. 1 and 3. First side 92 can further include a first rotation limiting surface 130, a first cam surface 132 positioned adjacent thereto, and second and third rotation

limiting surfaces **134** and **136** respectively, the operation of which will be described in greater detail below. A recess area **138** can be formed in outer periphery **96** so as to provide access to surfaces **130-136**.

[0039] The toothed portion **114** can include a plurality of teeth **140** with each tooth having an inclined or ramped surface **142** that mates with second surface **144** orientated generally normal to the outer periphery **96** of thumbwheel **90**. The ramped surfaces **142** can be orientated such that they incline away from the outer periphery in a counter-clockwise direction shown by arrow **A** in FIG. 3.

[0040] Translation member **82** can include a longitudinally extending portion **160** having a top **162**, a bottom **164**, a side portion **166** connecting the top and bottom **162**, **164**, a distal end **168** and a proximal end **170**, as shown for example in FIG. 6. Translation member **82** can be positioned in casing **20** such that bottom **164** is adjacent a flange portion **174** of first casing portion **60** and top **162** is adjacent a flange portion **176** also of first casing portion **60**, as generally shown in FIG. 4 with reference to FIG. 6. Flange portions **174**, **176** can form a channel that guides translation member **82** during translation. A pair of position indication members **180**, **182** can extend transversely in opposite directions from top **162** so as to extend through slots **184** in respective casing portions **60**, **62** as shown in FIGS. 1 and 2.

[0041] Translation member **82** can further include an L-shaped portion **188** extending from distal end **168**, as shown for example in FIG. 6. A proximal end **192** of outer cannula **86** can be coupled to L-shaped portion **188** such that outer cannula **86** can slidably protrude through an aperture **196** formed by casing portions **60**, **62**. A distal end **198** of outer cannula **86** can include a curved or inclined portion **200** as well as a pair of elongated apertures **202** positioned in alignment on opposite sides of cannula **86**, as shown for example in FIG. 11C. Outer cannula **86** can also include a beveled or chamfered end **206** at a distal most end thereof adjacent to apertures **202**. Chamfered end **206** can include a rounded or smooth end for placement adjacent to or abutting tissue without piercing the tissue. It should be appreciated that distal end **198** of outer cannula **86** can also be straight or non-inclined, arcuate, angled, etc. depending on a desired use or application, and can also be provided with or without apertures **202** and chamfered end **206**.

[0042] Biasing member **84** can be connected at a first end **210** to the distal end **168** of translation member **82** and at a second end **212** to a tab **214** fixed to first casing portion **60**. Biasing member **84** can be any suitable device, such as a coil spring, configured for expanding and contracting while also exerting a biasing force that biases the proximal end **170** of translation member **82** into engagement with thumbwheel **90**.

[0043] With additional reference to FIGS. 10-12, the insertion system **40** will now be described. Insertion system **40** can include a slider or carrying wire **220**, an insertion member **222**, a loading or positioning member **224**, and a deployment system **226**. Carrying wire **220** can include a solid, semi-rigid construction **230** with a proximal end **232** fixedly coupled to a cam follower **234** and a distal end **236** having a suture anchor engagement portion **238**. Cam follower **234** can include a generally rectangular shape **242** that can be configured to translate in a track **246** defined by flanges **248** and **250** in first casing portion **60**. Track **246** can further include proximal and distal ends **254** and **256** serving to limit travel of the cam follower **234** therebetween, as

shown in FIGS. 4 and 10. A lower surface of cam follower **234** can include a plurality of gear teeth **260** configured for meshing engagement with a cam member **342** to translate carrying wire **220** between a stowed position where cam follower **234** abuts proximal end **254** and a deployed position where cam follower **234** abuts distal end **256**, as will be further described below.

[0044] The insertion member **222** can include a tubular portion **274** extending from a body member **276** at a proximal end **278** and a trough portion **280** mating with the tubular portion **274** and extending therefrom to a distal end **284**. The trough portion **280** can include an inclined portion **286** complimentary to the inclined portion **200** of cannula **86**. It should be appreciated that insertion member **222** can be provided with a straight or non-inclined distal end that could correspond to a straight distal end of outer cannula **86**. Inclined portion **286** can include depth indicator markers **290**, as well as a pointed and chamfered distal most end **292** capable of piercing skin and soft tissue. Body member **276** can be configured for positioning in a correspondingly shaped cavity **296** to fix insertion member **222** relative to casing **20** and outer cannula **86**. The distal end **284** of insertion member **222** can be received in outer cannula **86** such that at least a portion of trough portion **280** and tubular portion **274** can reside within cannula **86** as shown for example in FIGS. 11 and 12.

[0045] The positioning member **224** can include a tubular portion **300** fixedly coupled to an engagement member **302** at a proximal end **304**, and a distal end **306** configured to engage suture anchor **506**, as will be described greater detail below in connection with the operation of device **10**. Tubular portion **300** can include an inside diameter larger than the suture engagement portion **238** of carrying wire **220** but an outside diameter less than an inside diameter **314** of insertion member **222**. Engagement member **302** can include a generally square or rectangular shape **316** configured to mate with the dimensions of track **246** such that engagement member **302** can be slidably received within track **246**. Tubular portion **300** can be slidably received within the tubular portion **274** of insertion member **222** such that distal end **306** and a portion of tubular portion **300** are slidably housed within insertion member **222**, as shown in FIGS. 11 and 12.

[0046] Carrying wire **220** can be inserted through positioning member **224** via aperture **320** such that positioning member **224** can translate on and relative to carrying wire **220**. With carrying wire **220** disposed through positioning member **224**, engagement member **302** and cam follower **234** can be positioned in track **246** such that engagement member **302** abuts a distal end **324** of cam follower **234** when cam follower **234** is in the stowed position. A retention tab **326** can also extend from a top portion **328** of engagement member **302**. Retention tab **326** can be configured to engage a flange **332** extending from casing portion **62** so as to retain engagement member **302** relative to flange **332** when cam follower **234** is translated to the deployed position, as shown in FIG. 19 with reference to FIGS. 5 and 12.

[0047] Deployment system **226** can include a trigger **340**, a cam member **342** and a biasing member **344**. Trigger **340** can include an aperture **348** for pivotally coupling trigger **340** to a pivot post **350** of first casing portion **60**, a user engageable portion **354** and a flange member **356**. User engageable portion **354** can protrude through an aperture **360** formed by respective casing portions **60**, **62** so as to be

accessible by a user, as will be further described below. A coupling member 364 can extend from an end 366 of trigger 340 that is configured to abut cam member 342 so as to engage and couple trigger 340 to an end 368 of cam member 342. Range member 356 can extend from aperture 348 in a direction substantially orthogonal to user engageable portion 354. Flange member 356 can include a tab 370 protruding from a distal end thereof and configured to engage a corresponding tab 372 protruding from L-shaped portion 188, as shown for example in FIG. 6. When tabs 370 and 372 align, trigger 340 is locked such that it can not be rotated from the non-deployed position shown in FIG. 6.

[0048] Cam member 342 can include a generally semicircular shaped portion 380 and a generally planer portion 382 spanning between respective ends 384, 386 of portion 380. An aperture 390 can be centrally positioned between ends 384, 386 and configured to engage a pivot post 392 protruding from first casing portion 60 such that cam member 342 can pivot about post 392. Arcuate portion 380 can include a portion 306 having a plurality of gear teeth 398 adjacent to and configured for meshing engagement with the plurality of gear teeth 260 of cam follower 234. Biasing member 344 can be coupled at one end to a retention tab proximate arcuate portion 380 and at another end to a retention post 400 protruding from first casing portion 60. Biasing member 344 can include a coil spring or other device suitable for imparting a biasing force onto cam member 342 to bias trigger 340 to the non-deployed position, as shown for example in FIG. 6.

[0049] User engageable portion 354 of trigger 340 can be grasped by a user and squeezed or depressed so as to rotate trigger 340 about pivot post 350. Upon such rotation, trigger end 366 can drive cam member 342 to rotate about pivot post 392, which in turn will drivingly engage cam member gear teeth 398 with cam follower gear teeth 260 and translate cam follower 234 and carrying wire 220 forward from the stowed position to the deployed position, as generally shown in FIG. 19. Upon the user releasing trigger 340, the biasing force exerted by biasing member 344 can return cam follower 234, cam member 342 and trigger 340 to the non-deployed positions, as generally shown in FIGS. 6 and 20.

[0050] Returning to FIGS. 6-9B, operation of the depth positioning system 30 in connection with the insertion system 40 and trigger lock feature will now be described in greater detail. Thumbwheel 90 can be used to adjust a position of the outer cannula 86 relative to casing 20 and insertion member 222. More specifically, outer cannula 86 can be axially adjusted from a sheathed position to several use positions such that insertion member 222 extends at predetermined lengths relative to distal end 198 of outer cannula 86.

[0051] In the sheathed position, thumbwheel 90 can be positioned such that an engagement tab 410 protruding from first casing portion 60 is positioned between a projecting member 412 of rotation limiting surface 134 and an edge 418 of cam surface 132, as generally shown in FIG. 9B with reference to FIG. 4. In this position, thumbwheel 90 can be prevented from rotating and can engage the distal end of translation member 82 at the outer periphery 96 thereby positioning outer cannula 86 to a fully deployed or sheathed position, as shown in FIG. 6. In the sheathed position, outer cannula 86 can fully cover insertion member 222, carrying wire 220 and positioning member 224, as also shown in FIG. 6.

[0052] To move the depth positioning system 30 from the sheathed position to an initial use position, a user can push thumbwheel 90 to linearly translate thumbwheel 90 forward towards distal end 68 such that posts 98, 104 slide and translate forward in their respective slots 100, 108 and protection member 412 is disengaged from tab 410. Upon disengagement, thumbwheel 90 can be rotated counter-clockwise in the direction of arrow A such that recessed area 138 is now aligned with the proximal end 170 of translation member 82, as shown in FIG. 7. Biasing member 84 can then urge translation member 82 rearward into recess area 138 such that proximal end 170 engages first cam surface 132, as generally shown in FIG. 7 with additional reference to FIG. 9B. Cam surface 132 can be configured with a shape as shown that cooperates with proximal end 170 of translation member 82 and biasing member 84 to urge thumbwheel 90 to rotate in the direction of arrow A from the sheathed position to the initial use position. In the initial use position, the distal end 198 of outer cannula 86 can align with a first marker 414 of depth markers 290, and a tooth of the plurality of teeth 140 can engage a cooperating projection 422 of first casing portion 60, as also shown in FIG. 7.

[0053] In the initial use position, outer cannula 86 can be partially translated rearward into casing 20 such that a distal end 284 of insertion member 222 is exposed. A user can now rotate thumbwheel 90 to adjust outer cannula 86 to a desired position relative to distal end 84 of insertion member 222. For example, a user could adjust outer cannula 86 relative to distal end 284 such that distal end 284 protrudes a predetermined distance that corresponds to a desired distance in which insertion member 222 can be inserted into the anatomy. In one exemplary configuration, thumbwheel 90 can be used to adjust outer cannula 86 relative to insertion member 222 by 8 millimeters in 2 millimeter increments from first marker 414 to fifth marker 432, as generally shown in FIG. 8. It should be appreciated that the depth and positioning system 30 can be configured to provide various amounts of adjustment as may be desired for various procedures. In this regard, thumbwheel 90 can include a plurality of discrete positions and/or infinite adjustment configurations as may be desired for various procedures.

[0054] With continuing reference to FIGS. 6-9B and additional reference to FIGS. 1 and 11B, depth markers 290 can be used to aid a user in positioning outer cannula 86 relative to insertion member 222. In an exemplary configuration, markers 290 can include five discrete markers or indicia, with the first marker 414 corresponding to a distance of 10 millimeters from the distal end 284 of insertion member 222 to the distal end 198 of outer cannula 86. Each successive marker in a rearward direction towards casing 20 can be separated by 2 millimeters such that the fifth marker 432 can correspond to a distance of 18 millimeters from distal end 284 to distal end 198.

[0055] In addition, respective sides 436 of casing 20 can also include depth indicator markings or indicia 440, as shown in FIG. 1. Markings 440 can similarly include five markers that correspond to the same five positions as the markers 290 on insertion member 222. A distal side 442 of position indicator members 180, 182 can be configured to align with markings 440 to provide a visual indication on casing 20 of a position of the distal end 284 of insertion member 222 relative to outer cannula 86, as shown for example in FIG. 1. It should also be noted that when insertion system 40 is in the sheathed position, a proximal

side 444 of position indicator members 180, 182 can align with a first marker 446 of markings 440, as shown in FIG. 1.

[0056] Each tooth of the plurality of teeth 140 on thumbwheel 90 can be correspondingly spaced apart such that thumbwheel 90 can be used to advance or retract outer cannula 86 in the 2 millimeter increments described above. More specifically, to retract outer cannula 86 away from distal end 284 of insertion member 222, thumbwheel 90 can be pressed forward, such that teeth surfaces 144 clear cooperating projection 422, and then rotated in the counter-clockwise direction of arrow A. For example, thumbwheel 90 can be translated forward and simultaneously rotated in the direction of arrow A to retract outer cannula 86 from the first marker 414 to the fifth marker 432 such that the distal end of insertion member 222 extends beyond outer cannula 86 by a distance of 18 millimeters, as shown in FIG. 8. In this position, second surface 144 adjacent an end of tooth 434 can engage cooperating projection 422 and rotation limiting surface 130 can engage surface 416 of first casing portion 60 adjacent engagement tab 410, as generally shown in FIGS. 8 and 9B. On the other hand, to advance outer cannula 86 towards distal end 284, thumbwheel 90 can be rotated in a direction opposite of arrow A with ramped surfaces 142 ratcheting against cooperating projection 422 to a desired position.

[0057] With reference to FIGS. 13-18, the flexible suture anchors 50a, 50b will now be described in greater detail. Each flexible anchor 50a, 50b can be an elongated member having first and second ends 502, 504. The first and second ends 502, 504 can be substantially perpendicular to the longitudinal axis of the flexible anchors 50a, 50b. The flexible anchors 50a, 50b can be made of resorbable or non-resorbable materials, including braided suture, sponges and sponge-like materials in solid form, perforated materials, woven/braided from biocompatible materials or fibers, such as, for example, polymer, polyester, polyethylene, cotton, silk, or other natural or synthetic materials, including sponges and sponge-like materials. The flexible anchors 50a, 50b can have any properties that allow the flexible anchors 50a, 50b to change shape. The flexible anchors 50a, 50b can be, for example, compliant, flexible, foldable, squashable, squeezable, deformable, limp, flaccid, elastic, low-modulus, soft, spongy, perforated or any other flexible member which can change shape. In some aspects, the flexible anchors 50a, 50b can be coated with biological or biocompatible coatings, and can also be soaked in platelets and other biologics, which can be easily absorbed by the flexible anchors 50a, 50b in particular when, for example, the flexible anchors 50a, 50b are made from spongy, absorbent material.

[0058] It should be understood by the above description that the flexible anchors 50a, 50b are not configured to pierce or otherwise penetrate tissue either with the first and second ends 502, 504, which are blunt or with any other portion thereof. The flexible anchors 50a, 50b can be loaded on the exterior of the distal end 256 of carrying wire 220, as will be discussed in greater detail below. The flexible anchors 50a, 50b can be in the form of an elongate flexible tube defining a bore 508 along their length, as shown in FIG. 18.

[0059] The first and second flexible suture anchors 50a, 50b can be coupled together with a flexible suture or strand 512. The flexible strand 512 can have first and second ends

514, 516 and can be made of braided filaments or fibers of biocompatible material, including natural and synthetic fibers, such as cotton, silk, polymer, polyester, polyethylene, thin wire, suture, and other materials. The flexible strand 512 can be braided in a tubular or hollow form such that it forms an internal passage 520 between the first and second ends 514, 516.

[0060] A small knot or other retaining device 518 can be optionally formed adjacent the first end 514. The flexible strand 512 can be passed through a first opening 528 of each of the flexible anchors 50a, 50b, guided along the corresponding bore 508 and passed through a second opening 530 of each flexible anchor 50a, 50b, as for example shown in FIG. 18. The openings 528, 530 can be positioned intermediately between the first and second ends 502, 504 of each flexible anchor 50a, 50b at a distance of, for example, one-quarter length from the ends 502, 504 of each flexible anchor 50b. Furthermore, it will be appreciated that the openings 528, 530 can be apertures or voids in the woven fabric of the flexible anchors 50a, 50b, such that the openings 528, 530 do not disrupt or break the weave of flexible anchors 50a, 50b, when the flexible anchor 50a, 50b are made of braided or woven material.

[0061] After the flexible anchors 50a, 50b are mounted on the flexible strand 512, the second end 516 of the flexible strand 512 can be inserted into the internal passage 520 of the flexible strand 512 at an aperture 534, guided longitudinally along the passage 520, and led out of the passage 520 of the flexible strand 512 at an aperture 538. The portion of the strand 512 between apertures 534 and 538 can form an adjustment portion 542 between the optional knot 518 and the opening 528 of the second flexible anchor 50b, such that the flexible strand 512 defines a single adjustable knotless loop 546, as shown in FIGS. 15 and 16. The second flexible anchor 50b can be slidably moved along the flexible strand 512 until the adjustment portion 542 is within the bore 508 of the second flexible anchor 50b and the knot 518 is adjacent the opening 528 of the second flexible anchor 50b, as shown in FIG. 17. It will be appreciated, however, that the adjustment portion 542 can remain in the position shown in FIG. 15 outside of bore 508. The adjustable knotless loop 546 is self-locking and does not require the surgeon to tie a knot during a surgical procedure for securing the flexible strand 512. Further, once the adjustable knotless loop 546 is self-locked by pulling the second end 516 of the flexible strand 512 and tensioning the flexible strand 512, friction prevents the adjustable knotless loop 546 from being loosened, thereby providing a secure lock. Additional details regarding forming the knotless adjustable loop 546, and additional adjustable knotless loop configurations are disclosed in co-pending and commonly assigned U.S. patent application Ser. No. 11/541506, filed on Sep. 29, 2006, the disclosure of which is incorporated herein by reference.

[0062] For discussion purposes, the anchors 50a, 50b, together with flexible strand 512 configured in the knotless loop 546 can be hereinafter referred to as the anchor system 550. With reference to FIGS. 6 and 11A, the anchor system 550 can be pre-loaded in an in-line configuration on the carrying wire 220 such that anchor 50a is positioned before flexible anchor engagement portion 238 and second anchor 50b is positioned after engagement portion 238. In the in-line configuration, carrying wire 220 can extend through a portion of bore 508 of anchors 50a, 50b and then pierce through each anchor thereby creating a tail portion 548 that

is not coaxial with carrying wire 220, as shown for example in FIG. 11A. In this configuration, the anchors 50a, 50b can reside in the trough portion 280 of insertion member 222. The flexible strand 512 can be packaged within outer cannula 86 along side insertion member 222 and positioning member 224. Second end 516 of flexible strand 512 can extend out of outer cannula 86 through aperture 196 and into a tubular housing member 560 positioned in a handle portion of first casing portion 60, as shown for example in FIG. 6.

[0063] Returning to FIGS. 11 and 11A, the suture anchor engagement portion 238 of carrying wire 220 will now be described in greater detail. Suture engagement portion can have a flattened area 580 having a thickness less than the outside diameter 312 of carrying wire 220. Flattened area 580 can be formed so as to maintain the same cross-sectional area as a cross section through a non-flattened portion of carrying wire 220, thereby providing for the suture anchors 50a, 50b to be sized relative to the diameter of carrying wire 220 while ensuring that they can slide over the engagement portion 238, as will be further described below.

[0064] The engagement portion 238 can further include a one-way barb 584 configured such that flexible anchors 50a, 50b can slide or travel over barb 584 in only one direction of travel from the proximal end 254 of carrying wire 220 to the distal end 236 thereof. One-way barb 584 can be defined by a recess or cut-out 588 formed in the flattened section such that a distal end 590 of an open end of recess 588 mates with a portion of flattened area 580 having a first width 592. A proximal end 594 of the recess 588 also adjacent the opening can mate with another portion of the flattened area 580 having a second width 598 greater than the first width 592. Flattened area 580 can also include curved transition areas 597, 599 between the flattened area 580 and a non-flattened area of the carrying wire on a proximal side thereof, as shown in FIG. 11A.

[0065] In use, the larger second width 598 of flattened area 580 and the angled nature of one-way barb 584 provides for suture anchor 50b to be able to slide or travel over the barb 584 in a proximal to distal direction without being caught or stopped by barb 584. In a similar manner, carrying wire 220 can slide or travel relative to suture anchor 50b in a distal to proximal direction without barb 584 catching or stopping flexible anchor 50b. Conversely, the smaller first width 592 of flattened area 580 in cooperation with barb 584 provides for catching an interior surface of bore 508 of suture anchor 50b when carrying wire 220 moves in a proximal to distal direction relative to flexible anchor 50b.

[0066] Referring now to FIGS. 6-8 and 19-23, the soft tissue repair device 10 pre-loaded with suture anchors 50a, 50b can be used to repair a soft tissue defect 600, such as, for example, a tear, or other weakness in fibrous soft tissue 602, such as in meniscal tissue, cartilage, muscle or other fibrous tissue under the skin. An outer incision 601 can be made through the skin to access the soft tissue 602 and a user can insert the distal end 198 of outer cannula 86 to the surgical site. An appropriate insertion depth can be determined for the insertion member 222 and the user can translate and rotate thumbwheel 90, as discussed above, to unlock the depth and positioning system 30 from the sheathed position to the initial use position. The outer cannula 86 can then be adjusted relative to insertion member 222 such that distal end 284 extends beyond outer cannula 86 a distance corresponding to the desired insertion depth.

[0067] The exposed distal end 284 of insertion member 222 can be inserted through first entry point 604 into soft tissue 602 from a first side of the defect 600 until the distal end 284 can exit a second side 606 of the fibrous soft tissue 602, such as an outer surface or back side of a meniscus of a knee joint or other outer surface of a fibrous tissue. In this position, the distal end 198 of outer cannula 86 can be adjacent to or abutting the first entry point 604. It should be appreciated that the chamfered end 292 of insertion member 222 could alternatively be used to pierce the skin without requiring an incision 604.

[0068] With distal end 284 of insertion member 222 appropriately positioned, the trigger 340 can be squeezed or depressed to translate carrying wire 220 forward relative to insertion member 222 such that one-way barb 584 engages first flexible suture anchor 50a and delivers anchor 50a on the second side 606 of the soft tissue 602 at a first location, as shown in FIGS. 19 and 21. It should be appreciated that the manner and structure of the pre-assembled anchor system 550 in-line on carrying wire 220 allows the anchor 50a to pass through a narrow opening or slit, first entry point 604, formed in the tissue 602 by the chamfered end 292 of insertion member 222. It should also be appreciated that the U-shaped trough portion 280 of insertion member 222 requires a smaller insertion area than a fully enclosed, circular shaped insertion member would require and will not core a plug of tissue.

[0069] As cam follower 234 translates carrying wire 220 forward to deploy first anchor 50a in connection with depressing trigger 340, cam follower 234 also simultaneously translates positioning member 224 forward such that distal end 306 engages second flexible anchor 50b and moves anchor 50b forward towards distal end 198 of outer cannula 86, as shown in FIGS. 19 and 20. Tubular portion 300 of positioning member 224 can have a length such that when trigger 340 is fully depressed to deploy first anchor 50a, second anchor 50b will be carried forward to a position adjacent apertures 196 and distal end 198 of outer cannula 86. In this position, retention tab 326 can engage flange 332 to retain positioning member 224 and thus anchor 50b in this advanced position when trigger 340 is released. After the first anchor 50a has been deployed, the trigger 340 can be released thereby retracting the distal end 284 of insertion member 222 such that one-way barb 584 is positioned rearward of or within bore 508 of suture anchor 50b, as generally shown in FIGS. 19 and 21. When insertion member 222 is retracting, the tail portion 548 of suture anchor 50a can engage the soft tissue side 606 such that it will be removed from insertion member 222 as insertion member 220 retracts to the stowed position.

[0070] With the first anchor 50a deployed, the insertion device 10 can be removed from the soft tissue 602 while portions 610 of the knotless loop 546 can slide out from insertion device 10 as flexible anchor is retained in soft tissue 602. Insertion device 10 can then be inserted at a second location or entry point 605 on a second side of the soft tissue defect 600, as shown in FIG. 22. Once distal end 284 of insertion member 222 is appropriately positioned, such as beyond second side 606, trigger 340 can again be squeezed or depressed to deploy second anchor 50b adjacent to first anchor 50a. Depressing trigger 340 again translates carrying wire 220 forward such that one-way barb 584 engages an interior of bore 508 and deploys second flexible anchor 50b at the second location such that tail portion 548

of anchor **50b** can engage soft tissue side **606** upon retraction on insertion member **222**, as also generally shown in FIG. **22**. Insertion device **10** can then be removed from the soft tissue **602** and the skin incision **601** with the second end **516** of the flexible strand **512** being removed from the soft tissue **602** along with insertion device **10**, as also shown in FIG. **22**. Once second anchor **50b** is implanted and insertion device **10** removed from the soft tissue **602**, any remaining portion of second flexible strand end **516** not removed from outer cannula **86** and housing member **560** can be subsequently removed.

[0071] Pulling the second, free end **516** of the flexible strand **512** can tighten the adjustable knotless loop **546**, secure the first and second flexible anchors **50a**, **50b** against the second side surface **606** of the soft tissue **602**, and reduce the defect **600**. Further, portions **614** of the anchors **50a**, **50b** between the first and second ends **502**, **504** and the corresponding first and second openings **528**, **530**, can define anchoring leg portions **614** that can provide additional resistance for securing the flexible anchors **50a**, **50b** on the surface **606** of the soft tissue **602**, as these leg portions can be forced against surface **606** for anchoring, as shown for example in FIG. **23**.

[0072] It will be appreciated from the above description and drawings that the present teachings provide flexible anchors that can be passed through tissue easily in a compact or low profile configuration and or orientation and then positioned outside tissue in a second orientation that provides anchoring without tissue penetration, preventing withdrawal from the tissue and reducing tissue injury. Further, the use of an inserter provided with preassembled anchors can help reduce the time length of the procedure and simplify manipulations required during the procedure.

[0073] It will be further understood that the various aspects of the depth positioning system, insertion system, deployment system and anchors can be mixed and matched or combined in ways other than those explicitly discussed above, without departing from the scope of the present teachings.

[0074] The foregoing discussion discloses and describes merely exemplary arrangements of the present disclosure. One skilled in the art will readily recognize from such discussion, and from the accompanying drawings and claims, that various changes, modifications and variations can be made therein without departing from the spirit and scope of the present teachings as defined in the following claims.

1.-20. (canceled)

21. A meniscal tissue repair device, comprising:

a housing;

an inserter extending from the housing, the inserter including an open distal end and a longitudinal bore that extends through the inserter to the open distal end;

a first flexible suture anchor deployable from the inserter at first location along an outer surface of a meniscus;

a second flexible suture anchor deployable from the inserter at a second location along the outer surface of the meniscus, wherein, in a pre-deployment condition of the meniscal tissue repair device, the second flexible suture anchor is located proximal of the first flexible suture anchor along the inserter;

a suture coupling the first flexible suture anchor to the second flexible suture anchor;

a cam pivotable about a pivot point that is located within the housing, the cam including a first plurality of teeth that extend in an arcuate manner along the cam;

a cam follower including a second plurality of teeth that extend in a linear manner along the cam follower, the second plurality of teeth meshing with the first plurality of teeth such that pivoting the cam about the pivot point causes the cam follower to move linearly within the housing; and

a slider slidably received in the longitudinal bore of the inserter, the slider including a proximal portion coupled to the cam follower such that linear movement of the cam follower within the housing causes the slider to move linearly within the longitudinal bore of the inserter, the slider further comprising an anchor engagement portion that includes a flattened area distal of the proximal portion, the flattened area having a thickness that is less than an outside diameter of a first portion of the slider adjacent the flattened area, wherein, in the pre-deployment condition of the meniscal tissue repair device, the slider extends distally past the second flexible suture anchor toward the first flexible suture anchor to position the flattened area between the second flexible suture anchor and the first flexible suture anchor in the longitudinal bore of the inserter,

wherein, from the pre-deployment condition of the meniscal tissue repair device, the cam is pivotable about the pivot point in a first rotational direction to advance the slider within the longitudinal bore of the inserter to a first deployment position and thereby force the first flexible suture anchor from the inserter via an engagement of the first flexible suture anchor with the anchor engagement portion,

wherein the cam is pivotable about the pivot point in a second rotational direction opposite the first rotational direction to retract the slider within the longitudinal bore of the inserter from the first deployment position to a second deployment position and thereby move the anchor engagement portion proximally past at least part of the second flexible suture anchor; and

wherein the cam is pivotable about the pivot point in the first rotational direction to advance the slider within the longitudinal bore of the inserter from the second deployment position to a third deployment position and thereby force the second flexible suture anchor from the inserter via an engagement of the second flexible suture anchor with the anchor engagement portion.

22. The meniscal tissue repair device of claim **21**, wherein the slider has a first width at the first portion of the slider that is adjacent the flattened area and a second width at the flattened area that is greater than the first width.

23. The meniscal tissue repair device of claim **21**, wherein the slider has a first cross-sectional area at the first portion of the slider that is adjacent the flattened area and a second cross-sectional area at the flattened area that is equal to the first width.

24. The meniscal tissue repair device of claim **21**, wherein, in the pre-deployment condition of the meniscal tissue repair device, the slider extends through the second flexible suture anchor.

25. The meniscal tissue repair device of claim **21**, wherein the engagement of the first flexible suture anchor with the anchor engagement portion includes the anchor engagement portion contacting an intermediate portion of the first flex-

ible suture anchor, the intermediate portion located between a first end and a second end of the first flexible suture anchor.

26. A meniscal tissue repair device, comprising:

- a housing;
- an inserter extending from the housing, the inserter including an open distal end and a longitudinal bore that extends through the inserter to the open distal end;
- a first flexible suture anchor deployable from the inserter at a first location along an outer surface of a meniscus;
- a second flexible suture anchor deployable from the inserter at a second location along the outer surface of the meniscus, wherein, in a pre-deployment condition of the meniscal tissue repair device, the second flexible suture anchor is located proximal of the first flexible suture anchor along the inserter;
- a suture coupling the first flexible suture anchor to the second flexible suture anchor;
- a cam pivotable about a pivot point that is located within the housing, the cam including a first plurality of teeth that extend in an arcuate manner along the cam;
- a cam follower including a second plurality of teeth that extend in a linear manner along the cam follower, the second plurality of teeth meshing with the first plurality of teeth such that pivoting the cam about the pivot point causes the cam follower to move linearly within the housing; and
- a slider slidably received in the longitudinal bore of the inserter, the slider including a proximal portion coupled to the cam follower such that linear movement of the cam follower within the housing causes the slider to move linearly within the longitudinal bore of the inserter, the slider further including an anchor engagement portion distal of the proximal portion, wherein, in the pre-deployment condition of the meniscal tissue repair device, the slider extends distally past the second flexible suture anchor toward the first flexible suture anchor to position the anchor engagement portion between the second flexible suture anchor and the first flexible suture anchor in the longitudinal bore of the inserter,

wherein, from the pre-deployment condition of the meniscal tissue repair device, the cam is pivotable about the pivot point in a first rotational direction to advance the slider within the longitudinal bore of the inserter to a first deployment position and thereby force the first flexible suture anchor from the inserter via an engagement of the first flexible suture anchor with the anchor engagement portion,

wherein the cam is pivotable about the pivot point in a second rotational direction opposite the first rotational direction to retract the slider within the longitudinal bore of the inserter from the first deployment position to a second deployment position and thereby move the anchor engagement portion proximally past at least part of the second flexible suture anchor, and

wherein the cam is pivotable about the pivot point in the first rotational direction to advance the slider within the longitudinal bore of the inserter from the second deployment position to a third deployment position and thereby force the second flexible suture anchor from the inserter via an engagement of the second flexible suture anchor with the anchor engagement portion.

27. The meniscal tissue repair device of claim **26**, wherein the second plurality of teeth correspond to predetermined translation distances of the slider.

28. The meniscal tissue repair device of claim **26**, wherein, in the pre-deployment condition of the meniscal tissue repair device, the slider extends through the second flexible suture anchor.

29. The meniscal tissue repair device of claim **26**, wherein the anchor engagement portion includes a flattened area.

30. The meniscal tissue repair device of claim **29**, wherein the flattened area has a thickness that is less than an outside diameter of a first portion of the slider adjacent the flattened area.

31. The meniscal tissue repair device of claim **30**, wherein the slider has a first width at the first portion of the slider that is adjacent the flattened area and a second width at the flattened area that is greater than the first width.

32. The meniscal tissue repair device of claim **31**, wherein the slider has a first cross-sectional area at the first portion of the slider that is adjacent the flattened area and a second cross-sectional area at the flattened area that is the same as the first width.

33. The meniscal tissue repair device of claim **26**, wherein the engagement of the first flexible suture anchor with the anchor engagement portion includes the anchor engagement portion contacting an intermediate portion of the first flexible suture anchor, the intermediate portion located between a first end and a second end of the first flexible suture anchor.

34. A meniscal tissue repair device, comprising:

- a housing;
- an inserter extending from the housing, the inserter including an open distal end and a longitudinal bore that extends through the inserter to the open distal end;
- a first flexible suture anchor deployable from the inserter at a first location along an outer surface of a meniscus;
- a second flexible suture anchor deployable from the inserter at a second location along the outer surface of the meniscus, wherein, in a pre-deployment condition of the meniscal tissue repair device, the second flexible suture anchor is located proximal of the first flexible suture anchor along the inserter;
- a suture coupling the first flexible suture anchor to the second flexible suture anchor;
- a cam pivotable about a pivot point that is located within the housing, the cam including a first plurality of teeth that extend in an arcuate manner along the cam;
- a cam follower including a second plurality of teeth that extend in a linear manner along the cam follower, the second plurality of teeth meshing with the first plurality of teeth such that pivoting the cam about the pivot point causes the cam follower to move linearly within the housing; and
- a slider slidably received in the longitudinal bore of the inserter and including a proximal portion coupled to the cam follower such that linear movement of the cam follower within the housing causes the slider to move linearly within the longitudinal bore of the inserter, wherein, in the pre-deployment condition of the meniscal tissue repair device, the slider extends distally past the second flexible suture anchor toward the first flexible suture anchor in the longitudinal bore of the inserter, the slider further comprising an anchor engagement portion that includes a flattened area distal of the proximal portion, wherein the slider has a first

width at a first portion of the slider adjacent the flattened area and a second width at the flattened area that is greater than the first width,

wherein the cam is pivotable about the pivot point: (i) a first time and in a first rotational direction to advance the slider within the longitudinal bore of the inserter for deploying the first flexible suture anchor from the inserter at the first location along the outer surface of the meniscus; (ii) a second time and in a second rotational direction opposite the first rotational direction to retract the slider relative to the second flexible suture anchor within the longitudinal bore of the inserter; and (iii) a third time and back in the first rotational direction to advance the slider within the longitudinal bore of the inserter for deploying the second flexible suture anchor from the inserter at the second location along the outer surface of the meniscus.

35. The meniscal tissue repair device of claim **34**, wherein the flattened area has a thickness that is less than an outside diameter of the first portion of the slider that is adjacent the flattened area.

36. The meniscal tissue repair device of claim **34**, wherein the slider has a first cross-sectional area at the first portion of the slider that is adjacent the flattened area and a second cross-sectional area at the flattened area that is equal to the first width.

37. The meniscal tissue repair device of claim **34**, wherein the cam follower has a rectangular shape.

38. The meniscal tissue repair device of claim **34**, wherein, in the pre-deployment condition of the meniscal tissue repair device, the slider extends longitudinally through a longitudinal bore of the second flexible suture anchor.

39. The meniscal tissue repair device of claim **34**, wherein, in the pre-deployment condition of the meniscal tissue repair device, the flattened area is positioned between the second flexible suture anchor and the first flexible suture anchor in the longitudinal bore of the inserter.

40. The meniscal tissue repair device of claim **39**, wherein the cam is pivotable about the pivot point the second time to retract the slider within the longitudinal bore of the inserter and move the flattened area in a proximal direction past at least part of the second flexible suture anchor.

41. The meniscal tissue repair device of claim **34** further comprising an outer tube, the outer tube comprising an open distal end and a longitudinal bore that extends through the outer tube to the open distal end, the inserter received in the longitudinal bore of the outer tube.

42. The meniscal tissue repair device of claim **34** further comprising a stop located in the longitudinal bore of the inserter, and wherein, in the pre-deployment condition of the meniscal tissue repair device, the second flexible elongated tube anchor is located between the first flexible elongated tube anchor and the stop.

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