



(51) International Patent Classification:

E02F 9/20 (2006.01) *F04B 49/00* (2006.01)
E02F 9/22 (2006.01) *F04B 49/10* (2006.01)
E21B 7/02 (2006.01) *E02F 3/96* (2006.01)

(21) International Application Number:

PCT/EP2022/085194

(22) International Filing Date:

09 December 2022 (09.12.2022)

(25) Filing Language:

English

(26) Publication Language:

English

(30) Priority Data:

21213736.8 10 December 2021 (10.12.2021) EP

(71) Applicant: SANDVIK MINING AND CONSTRUCTION OY [FI/FI]; Pihtisulunkatu 9, 33330 Tampere (FI).

(72) Inventors: VERHO, Samuli; Sandvik Mining and Construction Oy, PL 100, 33311 Tampere (FI). VATANEN, Harri; Sandvik Mining and Construction Oy, PL 100, 33311 Tampere (FI).

(74) Agent: SANDVIK; Sandvik Mining and Construction Oy, Pihtisulunkatu 9, 33330 Tampere (FI).

(81) Designated States (unless otherwise indicated, for every kind of national protection available): AE, AG, AL, AM, AO, AT, AU, AZ, BA, BB, BG, BH, BN, BR, BW, BY, BZ, CA, CH, CL, CN, CO, CR, CU, CV, CZ, DE, DJ, DK, DM, DO, DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT, HN, HR, HU, ID, IL, IN, IQ, IR, IS, IT, JM, JO, JP, KE, KG, KH, KN, KP, KR, KW, KZ, LA, LC, LK, LR, LS, LU, LY, MA, MD, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI, NO, NZ, OM, PA, PE, PG, PH, PL, PT, QA, RO, RS, RU, RW, SA, SC, SD, SE, SG, SK, SL, ST, SV, SY, TH, TJ, TM, TN, TR, TT, TZ, UA, UG, US, UZ, VC, VN, WS, ZA, ZM, ZW.

(84) Designated States (unless otherwise indicated, for every kind of regional protection available): ARIPO (BW, CV, GH, GM, KE, LR, LS, MW, MZ, NA, RW, SD, SL, ST, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, RU, TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV, MC, ME, MK, MT, NL, NO, PL, PT, RO, RS, SE, SI, SK, SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, KM, ML, MR, NE, SN, TD, TG).

(54) Title: HYDRAULIC SYSTEM, WORKING VEHICLE AND METHOD

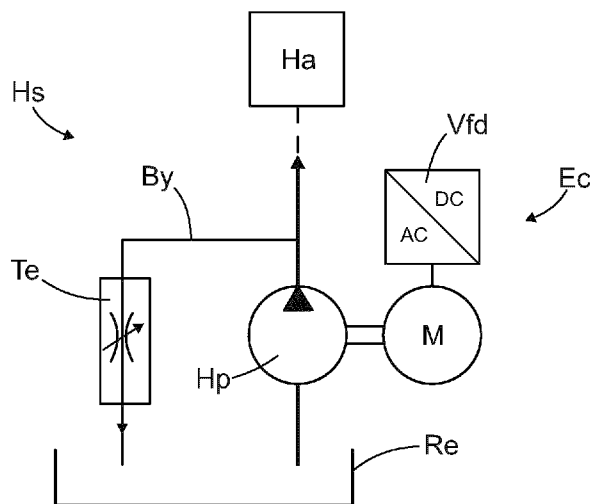


FIG. 4

(57) Abstract: A hydraulic system, working vehicle, and method for producing hydraulic power to a hydraulic system of a working vehicle. The hydraulic system (Hs) comprises a fixed displacement hydraulic pump (Hp) and a speed and torque controlled electric motor (M) for driving the hydraulic pump (Hp). An electric controller (Ec) is arranged to adjust the speed of the electric motor and to thereby adjust produced hydraulic fluid flow and pressure in the system. Further, there is a by-pass flow channel (By) comprising a throttle element (Te) for directing limited continuous discharge fluid flow from the system.



Published:

- *with international search report (Art. 21(3))*
- *in black and white; the international application as filed contained color or greyscale and is available for download from PATENTSCOPE*

Hydraulic system, working vehicle and method

Background of the invention

5 The invention relates to a hydraulic system of a working vehicle. The hydraulic system is provided with a fixed displacement pump, and a speed and torque controlled electric motor for producing hydraulic power. The electric motor is controlled by means of an electric controller.

10 The invention further relates to a working vehicle and to a method of producing hydraulic power to a hydraulic system of a working vehicle.

 The field of the invention is defined more specifically in the preambles of the independent claims.

15 At different work sites different working vehicles are used for executing work tasks. The working vehicles may comprise hydraulic actuators connected to hydraulic systems of the vehicles. In a modern hydraulic system, there may be a fixed displacement hydraulic pump driven by a speed and torque controlled electric motor for generating the needed hydraulic power. These types of systems have several advantages. However, the known solutions have shown to have some disadvantages especially in special situations when there is a need for pressure with no requirement for fluid flow.

20

25

Brief description of the invention

 An object of the invention is to provide a novel and improved hydraulic system, a working vehicle equipped with such hydraulic system and a method for producing hydraulic power to a hydraulic system of a working vehicle.

30

 The hydraulic system according to the invention is characterized by the characterizing features of the first independent apparatus claim.

The working vehicle according to the invention is characterized by the characterizing features of the second independent apparatus claim.

5 The method according to the invention is characterized by the characterizing features of the independent method claim.

An idea of the disclosed solution is that a hydraulic system of a working vehicle comprises one or more fixed displacement hydraulic pumps which are powered by one or more speed and torque controlled electric motors. The motors are controlled by means of one or more electric controllers for adjusting the speed of the electric motor and to thereby adjusting produced hydraulic fluid flow and pressure in the hydraulic system. Further, the hydraulic system is provided with one or more by-pass flow channels comprising one or more throttle elements for directing limited continuous discharge fluid flow from the hydraulic system.

In other words, the hydraulic system is provided with the throttle element arranged parallel to the hydraulic pump whereby there is a small hydraulic leak flow out of the hydraulic system to a hydraulic reservoir or tank. Purpose of the throttle element is to keep magnitude of the flow in the by-pass flow channel low so that energy consumption is not increased due to the by-pass flow.

25 An advantage of the disclosed solution is that the pump-motor arrangement, or hydraulic power unit, is driven continuously because of the by-pass flow and thereby the pressure output of the hydraulic pump can be stable. Thus, fluctuations in hydraulic output can be avoided and control of the hydraulic system can be smooth and improved.

In general, advantages of the disclosed arrangement comprising the fixed displacement pump and speed and torque controlled electric motor are that hydraulic system pressure can be controlled fast and accurately by means of the electrical controller. The system can keep the system pressure accurately on controlled values and can adapt quick

and automatically to different flow demands of the system by speed adaption of the motor and pump. The flow supplied to the system is always in accordance with need. Then the system can be energy efficient and provides accurate pressure control. However, an internal structure of the fixed displacement pump has small leakages and when the pump is driven in a special situation against a "blocked system" (pressure > 0 bar and flow = 0), then the small internal leakages may cause the pump to rotate periodically a bit for compensating the leakage. The internal leakage is so small that the hydraulic pump is not rotated continuously which causes unsmooth drive and pressure fluctuations in the system pressure. The disclosed by-pass flow channel and the continuous by-pass flow through it will provide the system with smooth drive.

According to an embodiment, the magnitude of the by-pass flow is dimensioned so that rotation of the hydraulic pump is always at least 30 - 200 rpm. In other words, the magnitude of the by-pass flow is dimensioned to be small by means of the throttle element, whereby no relevant power and energy consumption occurs due to the caused constant rotation of the pump-motor arrangement. In the solution low speed rotation of the motor and pump is implemented in situations when no fluid flow is needed in the system, but pressure request is on for the electric controller. The magnitude of the rotation speed may be dependent on power output grade of the hydraulic pump, for example.

According to an embodiment, the disclosed by-pass arrangement is adapted to generate slow speed rotation of the pump 150 rpm when no fluid flow request occurs in the electric controller. Then electric consumption of idle run of the motor may be low, for example 250 - 300 W.

According to an embodiment, the throttle element is an adjustable element whereby magnitude of the by-pass flow is adjustable. An advantage of the disclosed embodiment is that the by-pass flow and the followed continuous rotation

of the pump can be adjusted case by case to adapt different use cases and operational situations.

According to an embodiment, the throttle element may be a valve or orifice comprising an adjustable through
5 opening for the fluid flow passing through it.

According to an embodiment, the throttle element is a pressure compensated element whereby magnitude of the by-pass flow is configured to be adjusted automatically in response to magnitude of pressure prevailing in the hydraulic system. In other words, the by-pass flow system can adapt to different output pressure situations and can thereby keep the output of the pump stable in different operational situations. An advantage of this solution is that the pressure compensated throttle element can take care
10 of that the by-pass flow stays low also at high pressures and thereby ensures good energy efficiency.
15

According to an embodiment, the electric controller is a variable frequency drive serving as an electrical motor control device for controlling torque and rotation speed of
20 the electric motor. In other words, the disclosed solution aims to stabilize pressure of an inverter controlled hydraulic system.

According to an embodiment, the electric controller
25 is configured to control the torque and speed of the motor to adapt the speed of the hydraulic pump in accordance with needed fluid flow at requested pressure level.

According to an embodiment, the disclosed solution relates to a working vehicle. The working vehicle comprises:
30 a movable carrier; one or more work devices mounted on the carrier; and at least one hydraulic system. The hydraulic system is in accordance with the features and embodiments disclosed in this document.

According to an embodiment, the working vehicle is
35 a mining vehicle comprising at least one hydraulically operable mining actuator connected to the hydraulic system.

According to an embodiment, the above mentioned mining vehicle is a rock drilling rig, a loading vehicle, or a hauling vehicle.

According to an embodiment, the working vehicle is alternatively a forest machine, earth moving machine, or mobile crane.

According to an embodiment, the carrier of the working vehicle is provided with a brake system comprising spring loaded brakes openable with hydraulic brake actuators. Thus, the brakes are of normally on type. The disclosed solution is implemented for powering the hydraulic brake actuator keeping the brakes off during transfer drives. Then high pressure is needed for the brake actuators without a need for fluid flow since normal working actuators are not operable during the transfer drives.

According to an embodiment, the disclosed solution relates to a method of producing hydraulic power to a hydraulic system of a working vehicle. The method comprises: rotating a fixed displacement hydraulic pump by means of a speed and torque controlled electric motor; and controlling the rotation of the motor by means of an electric controller for adjusting the speed of the hydraulic pump and to thereby adjusting the produced hydraulic fluid flow and pressure in the hydraulic system. The method further comprises directing limited continuous discharge fluid flow via a by-pass flow channel and through a throttle element from an output side of the hydraulic pump to a reservoir whereby the hydraulic pump is driven continuously, and output of the hydraulic pump is stabilized.

According to an embodiment, the method comprises stabilizing pressure fluctuations in operational situations when pressure is needed for the output of the hydraulic pump and fluid flow is not.

According to an embodiment, the method comprises restricting magnitude of the by-pass flow by means of the throttle element for limiting hydraulic energy consumption.

According to an embodiment, the method comprises adjusting magnitude of the by-pass flow by means of the throttle element to correspond low speed rotation of the hydraulic pump at 30 - 200 rpm in situation where one or
5 more hydraulic actuators connected to the hydraulic system require no fluid flow but require pressure.

The above disclosed embodiments may be combined in order to form suitable solutions having those of the above features that are needed.

10 **Brief description of the figures**

Some embodiments are described in more detail in the accompanying drawings, in which

Figure 1 is a schematic side view of working vehicle provided with a hydraulic system,

15 Figure 2 is a schematic diagram showing some possible working vehicles wherein the disclosed solution can be implemented,

Figure 3 is a schematic view of a hydraulic diagram of the disclosed hydraulic system,

20 Figure 4 is a schematic view of an alternative hydraulic diagram of the disclosed hydraulic system,

Figure 5 is a schematic view of two graphs for illustrating sensed pressures as a function of time, and

25 Figure 6 is a schematic view of two graphs for illustrating sensed rotation speeds of a hydraulic pump as a function of time.

For the sake of clarity, the figures show some embodiments of the disclosed solution in a simplified manner. In the figures, like reference numerals identify like elements.
30

Detailed description of some embodiments

Figure 1 discloses a working vehicle 1 which comprises a movable carrier 2 and one or more work devices 3. In this case the working vehicle 1 is a rock drilling rig

for drilling drill holes to a rock surface. The rock drilling rig comprises one or more rock drilling units 4 arranged on one or more drilling booms 5. The drilling unit 4 comprises a rock drilling machine 6 which serves as a hydraulic actuator Ha connected to a hydraulic system Hs. There may be also other hydraulic actuators such as a feed device 7 and boom cylinders 8. Other hydraulic actuators on the carrier are also possible, such as breaking actuators. The hydraulic system Hs comprises a hydraulic pump Hp, an electric motor M and an electric controller Ec for controlling the motor M.

Figure 1 is only an example of the working vehicle 1. Figure 2 discloses a listing of some possible working vehicles wherein the hydraulic system according to this document can be implemented. As it is disclosed in Figure 2, the working vehicle may be a loading vehicle, or a hauling vehicle used for transporting removed broken rock material in mines. Further, the working machine may be an earthmoving machine or vehicle, such as an excavator, a wheel loader, a bulldozer, or a dumper. The disclosed solution can be utilized also in forest machines, such as in harvesters and forwarders. Different mobile cranes and container handling apparatuses may be provided with the disclosed hydraulic system. One more working apparatus to be mentioned, as an example of the working machine, is a pile-driving machine. All the mentioned working vehicles may have operational situations wherein the hydraulic system is subjected to requests for high fluid pressure with no fluid flow.

Figure 3 discloses a hydraulic system Hs comprising a fixed displacement hydraulic pump Hp rotatable with a speed and torque controlled electric motor M. The electric motor M is controlled by means of an electric controller Ec. The pump-motor combination generates hydraulic power for powering one or more hydraulic actuators Ha. For simplicity reasons only one hydraulic actuator Ha is presented. Further, there is a by-pass flow channel By comprising at

least one throttle element T_e for directing limited continuous discharge fluid flow to a reservoir R_e .

Figure 4 differs from the solution of Figure 3 only in that the throttling element T_e is adjustable and that
5 the electric controller E_c is a variable frequency drive V_{df} .

Figures 5 and 6 show first curves E of a hydraulic system with the disclosed solution, and second curves D of a substantially similar kind of hydraulic system without
10 the by-pass flow system. As can be seen in Figure 5, there occurs significant pressure fluctuation in the second curve D whereas in the hydraulic system implementing the present solution, the first curve E is stabilized. The stabilizing effect of the disclosed solution can also be seen when
15 comparing curves E and D in Figure 6 showing the rotation speed of the hydraulic pump. Stable and controlled rotation of the hydraulic pump is clearly shown by the curve E. In both Figures 5 and 6 the curves E are flat or almost flat.

The drawings and the related description are only
20 intended to illustrate the idea of the invention. In its details, the invention may vary within the scope of the claims.

Claims

1. A hydraulic system (Hs) of a working vehicle (1) comprising:
at least one fixed displacement hydraulic pump (Hp);
at least one speed and torque controlled electric motor (M) for driving the hydraulic pump (Hp);
at least one hydraulic actuator (Ha);
and at least one electric controller (Ec) for adjusting the speed of the electric motor (M) and to thereby adjusting produced hydraulic fluid flow and pressure in the hydraulic system (Hs); wherein
the hydraulic system (Hs) is provided with at least one by-pass flow channel (By) comprising at least one throttle element (Te) for directing limited continuous discharge fluid flow from the hydraulic system (Hs);
characterized in that
the throttle element (Te) is a pressure compensated element whereby magnitude of the by-pass flow is configured to be adjusted automatically in response to magnitude of pressure prevailing in the hydraulic system (Hs).
2. The hydraulic system as claimed in claim 1, characterized in that
the magnitude of the by-pass flow is dimensioned so that rotation of the hydraulic pump (Hp) is always at least 30 - 200 rpm.
3. The hydraulic system as claimed in claim 1 or 2, characterized in that
the electric controller (Ec) is a variable frequency drive (Vfd) serving as an electrical motor control device for controlling torque and rotation speed of the electric motor (M).

4. The hydraulic system as claimed in any one of the preceding claims 1 - 3, characterized in that

the electric controller (Ec) is configured to control the torque and speed of the motor (M) to adapt the speed of the hydraulic pump (Hp) in accordance with needed fluid flow at requested pressure level.

5. A working vehicle (1), comprising:

a movable carrier (2);

at least one work device (3) mounted on the carrier (2); and

at least one hydraulic system (Hs);

characterized in that

the hydraulic system (Hs) is in accordance with any one of the previous claims 1 - 4.

6. The working vehicle as claimed in claim 5, characterized in that

the working vehicle (1) is a mining vehicle comprising at least one hydraulically operable mining actuator (4) connected to the hydraulic system (Hs).

7. A method of producing hydraulic power to a hydraulic system (Hs) of a working vehicle (1),

wherein the method comprises:

rotating a fixed displacement hydraulic pump (Hp) by means of a speed and torque controlled electric motor (M); and

controlling the rotation of the motor (M) by means of an electric controller (Ec) for adjusting the speed of the hydraulic pump (Hp) and to thereby adjusting the produced hydraulic fluid flow and pressure in the hydraulic system (Hs); and

directing limited continuous discharge fluid flow via a by-pass flow channel (By) and through a throttle element (Te) from an output side of the hydraulic pump (Hp)

to a reservoir (Re) whereby the hydraulic pump (Hp) is driven continuously, and output of the hydraulic pump (Hp) is stabilized;

characterized by

- 5 restricting magnitude of the by-pass flow by means of the throttle element (Te) for limiting hydraulic energy consumption, wherein the magnitude of the by-pass flow is configured to be adjusted automatically in response to magnitude of pressure prevailing in the hydraulic system (Hs).

10

8. The method as claimed in claim 7, characterized by

- 15 stabilizing pressure fluctuations in operational situations when pressure is needed for the output of the hydraulic pump (Hp) and fluid flow is not.

9. The method as claimed in claim 7 or 8, characterized by

- 20 adjusting magnitude of the by-pass flow by means of the throttle element (Te) to correspond low speed rotation of the hydraulic pump (Hp) at 30 - 200 rpm in situation where one or more hydraulic actuators (Ha) connected to the hydraulic system (Hs) require no fluid flow but require pressure.

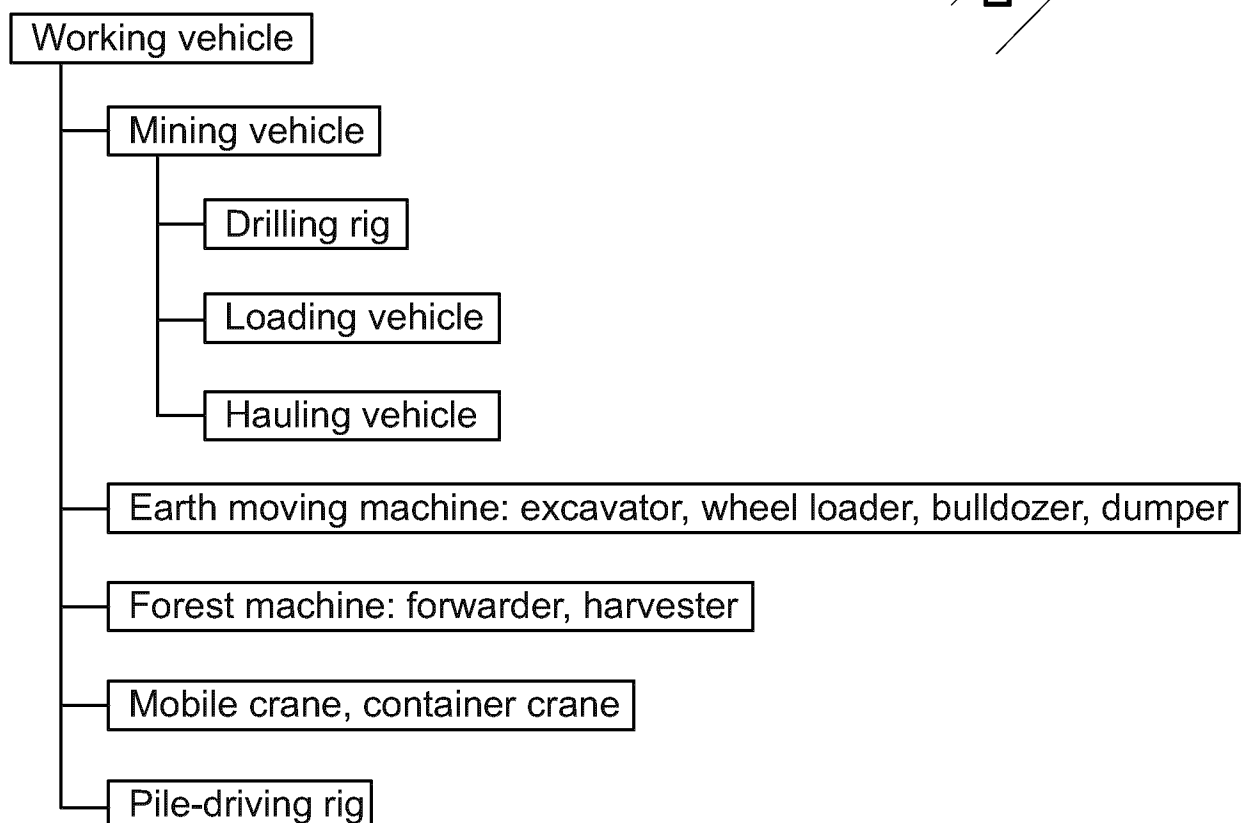
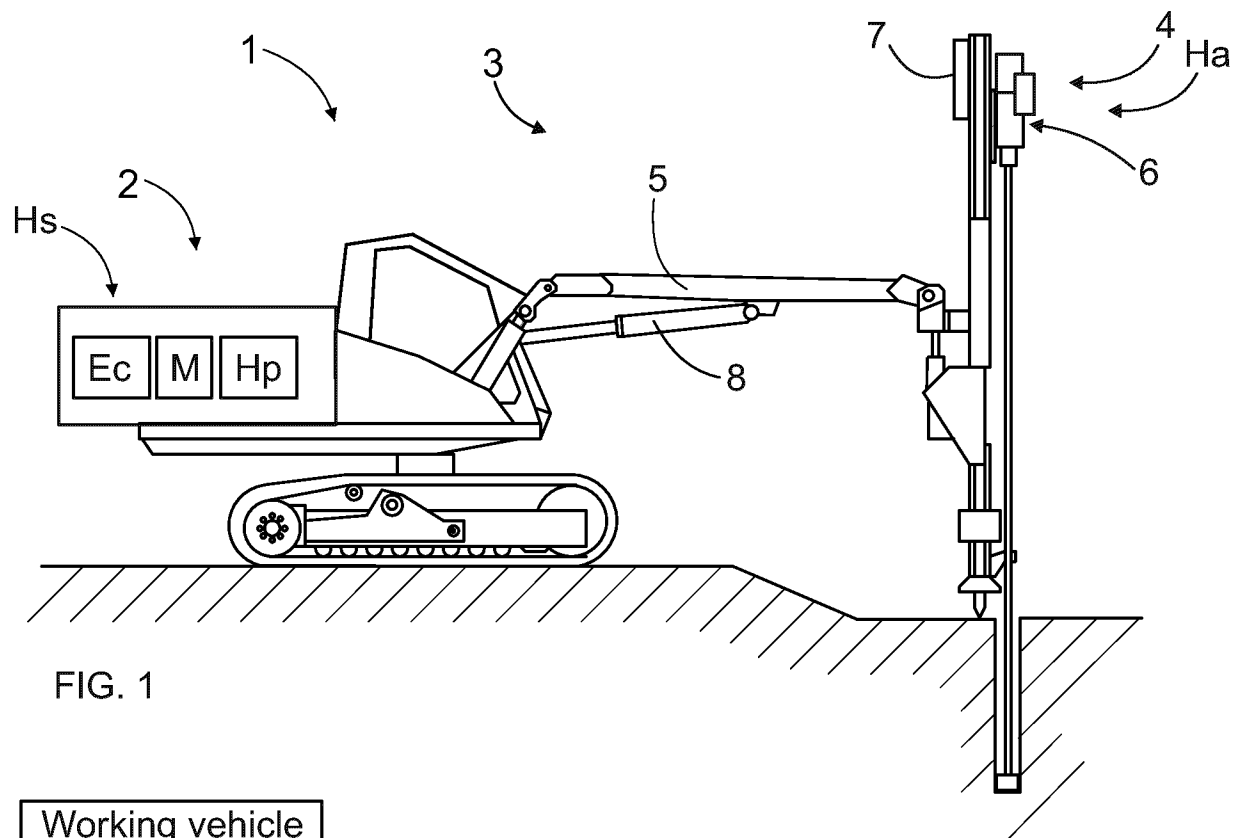


FIG. 2

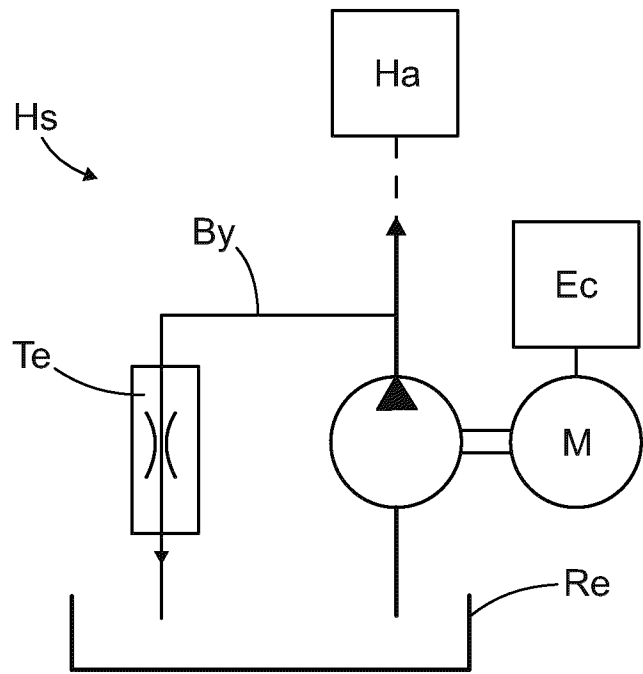


FIG. 3

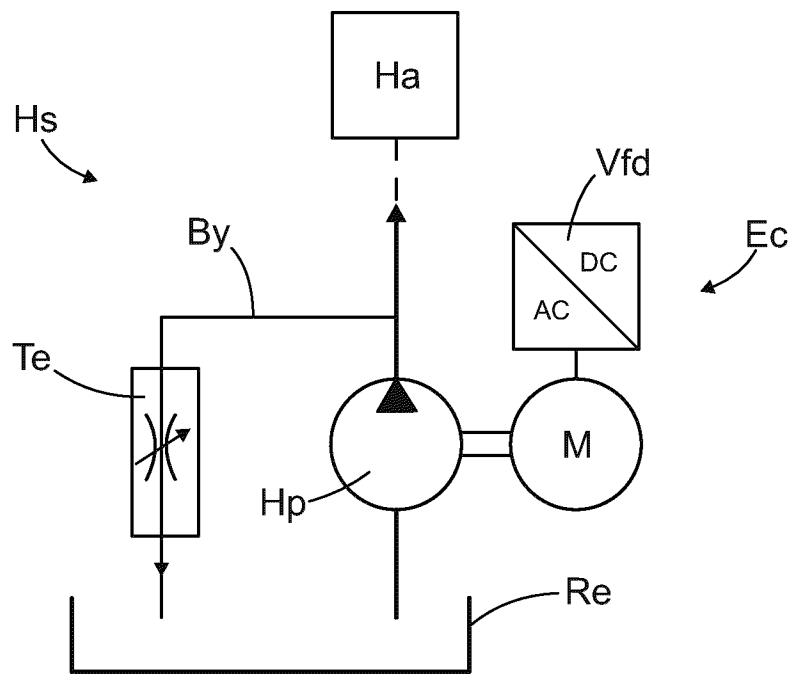


FIG. 4

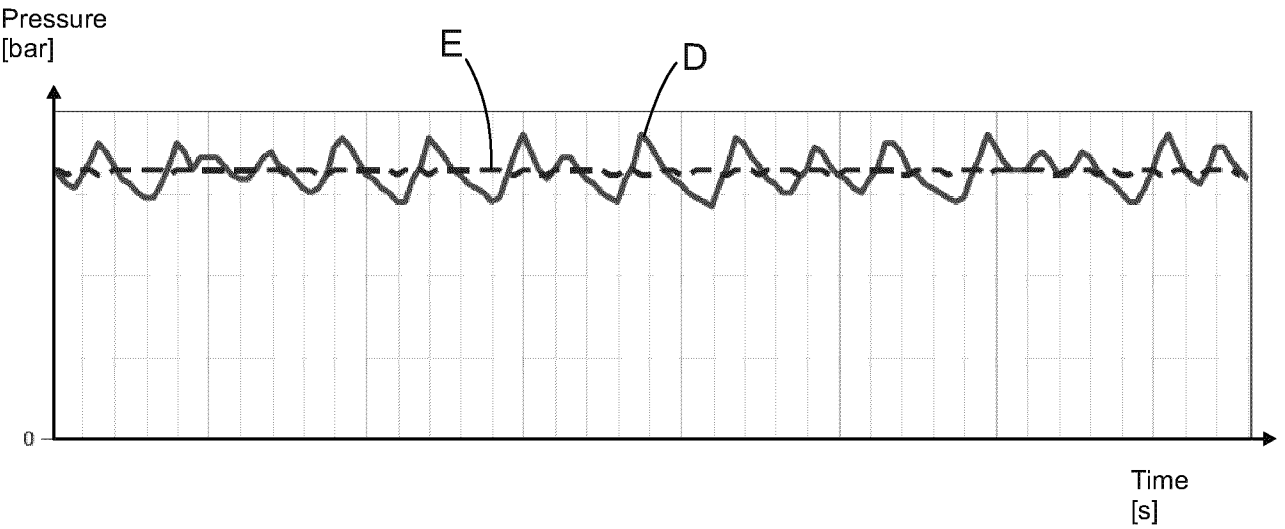


FIG. 5

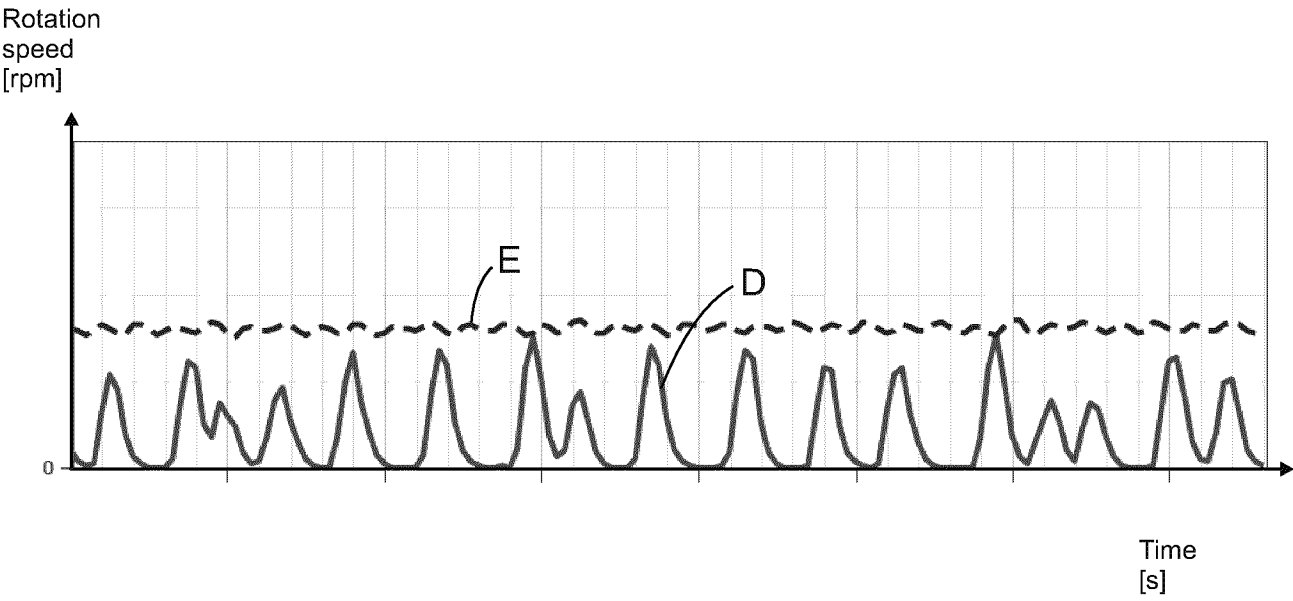


FIG. 6

INTERNATIONAL SEARCH REPORT

International application No
PCT/EP2022/085194

A. CLASSIFICATION OF SUBJECT MATTER INV. E02F9/20 E02F9/22 E21B7/02 F04B49/00 F04B49/10 E02F3/96 ADD. According to International Patent Classification (IPC) or to both national classification and IPC		
B. FIELDS SEARCHED Minimum documentation searched (classification system followed by classification symbols) E02F F15B E21B F04B Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched Electronic data base consulted during the international search (name of data base and, where practicable, search terms used) EPO-Internal, WPI Data		
C. DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
A	WO 2011/148051 A1 (SANDVIK MINING & CONSTR OY [FI]; OSARA JUKKA [FI] ET AL.) 1 December 2011 (2011-12-01) paragraph [0033]; figure 4 paragraphs [0028] - [0029]; figure 1 abstract -----	1-9
A	EP 0 300 080 A1 (KLEMM BOHRTECH [DE]) 25 January 1989 (1989-01-25) abstract; figure 1 column 9, line 14 - line 41 -----	1-9
A	US 2008/288115 A1 (RUSNAK DENNIS M [US] ET AL) 20 November 2008 (2008-11-20) paragraphs [0002] - [0003] -----	3
A	US 2012/090308 A1 (YUAN QINGHUI [US] ET AL) 19 April 2012 (2012-04-19) paragraphs [0017] - [0024]; figure 1 -----	3
☐ Further documents are listed in the continuation of Box C. ☒ See patent family annex.		
* Special categories of cited documents : "A" document defining the general state of the art which is not considered to be of particular relevance "E" earlier application or patent but published on or after the international filing date "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "O" document referring to an oral disclosure, use, exhibition or other means "P" document published prior to the international filing date but later than the priority date claimed "T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention "X" document of particular relevance;; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone "Y" document of particular relevance;; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art "&" document member of the same patent family		
Date of the actual completion of the international search 27 February 2023		Date of mailing of the international search report 13/03/2023
Name and mailing address of the ISA/ European Patent Office, P.B. 5818 Patentlaan 2 NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Fax: (+31-70) 340-3016		Authorized officer Ferrien, Yann

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No

PCT/EP2022/085194

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
WO 2011148051 A1	01-12-2011	AU 2011257102 A1 CA 2796474 A1 CL 2012003234 A1 CN 102947114 A EP 2576304 A1 FI 20105578 A JP 5613322 B2 JP 2013530323 A RU 2012156129 A US 2013056279 A1 WO 2011148051 A1 ZA 201208171 B	10-01-2013 01-12-2011 07-06-2013 27-02-2013 10-04-2013 26-11-2011 22-10-2014 25-07-2013 27-06-2014 07-03-2013 01-12-2011 26-06-2013
EP 0300080 A1	25-01-1989	NONE	
US 2008288115 A1	20-11-2008	NONE	
US 2012090308 A1	19-04-2012	BR 112013009154 A2 CA 2814728 A1 CN 103249950 A EP 2627906 A1 JP 2013545941 A KR 20130125757 A US 2012090308 A1 US 2015361996 A1 WO 2012051560 A1	24-09-2019 19-04-2012 14-08-2013 21-08-2013 26-12-2013 19-11-2013 19-04-2012 17-12-2015 19-04-2012