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(71) Applicant (for all designated States except US): **CIR-**

CUITREE LIMITED [GB/GB]; Consett Innovation Centre, Ponds Court Business Park, Consett, CO Durham DH8 5XP (GB).

(72) Inventors; and

(75) Inventors/Applicants (for US only): **ROBINSON, Craig** [GB/GB]; 209 Durham Road, Spennymoor DL16 6JU (GB). **LAM, Ee, Beng** [MY/GB]; 2 Caithness Court, Cambridge CB4 2UU (GB).

(74) Agent: **KENNEDYS PATENT AGENCY LIMITED;**

185 St. Vincent Street, Glasgow G2 5QD (GB).

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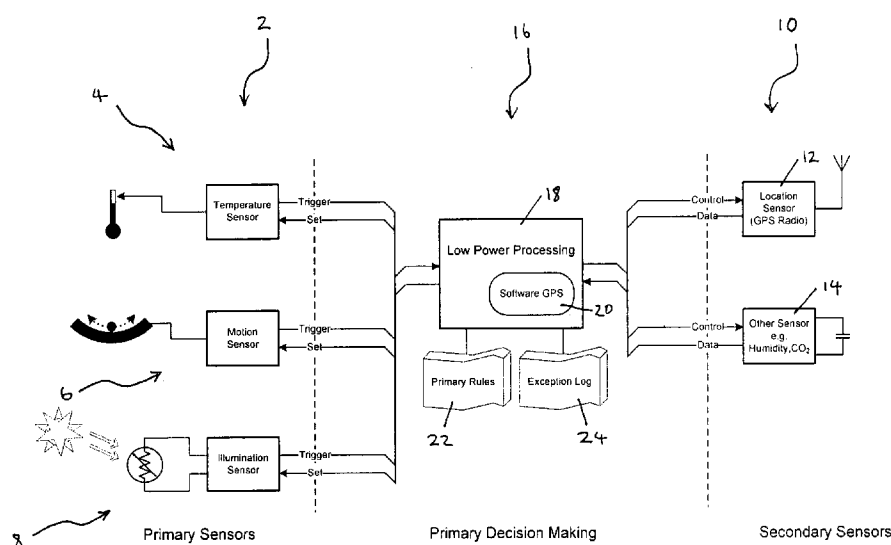
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(54) Title: CONTEXT MONITORING FOR REMOTE SENSOR PLATFORMS



(57) Abstract: A remote sensor platform for asset tracking monitors the context of the local environment to conserve power. Primary sensors (2) monitor local environment stimuli such as temperature (4), pressure or illumination (8). A low-power processor (16) uses the primary sensors (2) to monitor the environment and thereby determine whether to activate a secondary high power sensor (10), such as a GPS unit (12) or humidity or gas sensor (14). The low power processor may be triggered by the primary sensors (2) and may use configurable rules (22) for decision making. It may log exceptions (24) and sensor data for further decision making. A high-power processor (28) sends sensor data via a reporting means (34) to a server (40) using secondary configurable rules (3) conditionally on the primary (2) and secondary (10) sensor inputs. The server (40) can update the rules (22,30).

1 Context Monitoring for Remote Sensor Platforms

2
3 The present invention relates to the control of sensors,
4 in particular the control of the activation of sensors.

5
6 In the field of remote sensor platforms, tracking devices
7 may be used to secure a valuable object, for example a
8 painting, against theft. Small tracking devices have the
9 advantage that they can be concealed on or in objects,
10 however the small size restricts the battery capacity.

11
12 A typical conventional tracking device incorporates a GPS
13 (global positioning system) location sensor and a means
14 for reporting position and/or exception data to a control
15 centre. For the example of a painting, with the
16 assumption that the GPS receiver works in the painting's
17 normal environment such as a gallery, then a decision has
18 to be made about how often the tracking device is to wake
19 up and check its location. The problem is that if the
20 tracking device wakes frequently into the relatively high
21 power state in which it is determining its location using
22 the GPS sensor, this will quickly run down its battery. A
23 flat battery will limit or cease the tracking function of

1 the device. However if the tracking device is woken less
2 frequently to save draining the battery then there is a
3 delay in the reporting of the sensor and/or exception
4 data. Thus there is a compromise between the lifetime of
5 the tracking device's battery and the proper reporting of
6 the sensor data, affecting for example the time it takes
7 to realise that a theft has taken place.

8
9 WO9529410 in the name General Electric Company discloses
10 a tracking unit using a motion sensor as a primary sensor
11 to control the activation of a GPS navigation set as a
12 secondary sensor. A problem with using a motion sensors
13 as the primary sensor is that the activation of the
14 secondary sensor requires movement of the tracking unit.
15 Furthermore, the context of the local environment or
16 changes in the context are ignored by a motion sensor.

17
18 It is the object of an aspect of the present invention to
19 optimise the activation of a secondary sensor.

20
21 It is a further object of an aspect of the present
22 invention to optimise the reporting of sensor data.

23
24 According to the first aspect of the present invention
25 there is provided an apparatus comprising:

26 a primary sensor operable to sense a local
27 environment stimulus;
28 a primary sensor input operable to receive a
29 signal from the primary sensor;
30 a secondary sensor output operable to send an
31 activation signal to a secondary sensor; and
32 a primary processing means operable to use the
33 signal received from the primary sensor to monitor

1 the environment of the primary sensor and thereby
2 determine whether to activate the secondary sensor
3 and operable to cause the secondary sensor output to
4 send an activation signal to the secondary sensor.

5
6 Preferably, the apparatus comprises a plurality of the
7 primary sensors each operable to sense a different local
8 environment stimulus and the primary processing means is
9 operable to use signals received from the plurality of
10 the primary sensors to monitor the environment of the
11 plurality of primary sensors and thereby determine
12 whether to activate the secondary sensor.

13
14 This allows low power primary sensors to monitor the
15 environment and only activate higher power secondary
16 sensors when needed, thus providing longer battery life.

17
18 Preferably, the local environment stimulus comprises
19 temperature.

20
21 Preferably, the local environment stimulus comprises
22 illumination.

23
24 Preferably, the local environment stimulus comprises one
25 of: humidity, gas concentration, barometric pressure,
26 mechanical pressure, gas concentration, electrical
27 fields, magnetic fields electromagnetic field strength at
28 a particular frequency, and electromagnetic field
29 strength at a range of frequencies.

30
31 Preferably, the operation of the primary processing means
32 is triggered by a signal received from the primary
33 sensor.

1

2 This further prolongs battery life as only the primary
3 sensor, or sensors, need to be powered up.

4

5 Optionally, the primary sensor is operable to be
6 periodically powered down.

7

8 Operation is then that of sampling and the arrangement of
9 the sampling of the primary parameters is arranged so
10 that the effect of continuous monitoring is maintained.

11

12 Optionally, the periodic powering down of the primary
13 sensor is under the control of the primary processing
14 means.

15

16 Preferably, the primary processing means is configurably
17 operable to determine whether to activate the secondary
18 sensor.

19

20 Preferably, the primary processing means is remotely
21 configurable.

22

23 Optionally, the configuration of the primary processing
24 means is active for a predetermined period.

25

26 Optionally, the configuration of the primary processing
27 means is selected from a set of predetermined
28 configurations.

29

30 Preferably, the configurable operation of the primary
31 processing means uses configurable primary rules.

32

1 This allows the primary rules to be changed so that they
2 may develop over time for more optimised operation of the
3 apparatus.

4

5 Preferably, the configurable primary rules are remotely
6 configurable.

7

8 This also allows the primary rules to be changed to
9 account for new environments as the object being tracked
10 is moved around, thus optimising battery life and the
11 reporting of sensor data.

12

13 Preferably, the apparatus further comprises a secondary
14 sensor input operable to receive a signal from the
15 secondary sensor and the primary processing means is
16 operable to use the signal received from the secondary
17 sensor to activate a secondary processing means.

18

19 Preferably, the primary processing means is operable to
20 log sensor data corresponding to the received signals
21 from one or more of the primary and secondary sensors.

22

23 This allows the storage of sensed conditions for
24 reference in future decision making.

25

26 Preferably, the operation of the primary processing means
27 uses the logged sensor data to determine whether to
28 activate the secondary sensor.

29

30 This allows the primary processing means to use values of
31 sensor data from the past to decide what to do now, thus
32 optimising its decision making.

33

1 Preferably, the operation of the primary processing means
2 uses the rate of change of the received signals from one
3 or more of the primary and secondary sensors to determine
4 whether to activate the secondary sensor.

5
6 Preferably, the apparatus further comprises a reporting
7 means operable to transmit a sensor data signal based on
8 the received signal from at least one of the primary and
9 secondary sensors and the apparatus further comprises the
10 secondary processing means operable to activate the
11 reporting means conditionally upon the received signal
12 from at least one of the primary and secondary sensors.

13
14 This allows further battery savings as the reporting
15 means will generally have a higher power consumption than
16 the sensors and primary processing means.

17
18 Preferably, the secondary processing means is
19 configurably operable to activate the reporting means.

20
21 Preferably, the secondary processing means is remotely
22 configurable.

23
24 Preferably, the operation of the secondary processing
25 means uses configurable secondary rules.

26
27 This allows the secondary rules to be changed so that
28 they may develop over time for more optimised operation
29 of the apparatus.

30
31 Preferably, the configurable secondary rules are remotely
32 configurable.

33

1 This also allows the secondary rules to be changed to
2 account for new environments as the object being tracked
3 is moved around, thus optimising battery life and the
4 reporting of sensor data.

5

6 Preferably, the secondary processing means is operable to
7 configure the primary rules.

8

9 This allows the primary rules to be changed so that they
10 may develop over time for more optimised operation of the
11 apparatus, thus optimising battery life and the reporting
12 of sensor data.

13

14 Preferably, the primary processing means is further
15 operable to activate the secondary processing means,
16 conditionally upon an output of at least one of the
17 primary and secondary sensors.

18

19 This optimises battery life by only activating the
20 secondary processing means when required.

21

22 Preferably, the apparatus further comprises the secondary
23 sensor that has a higher power consumption than the
24 primary sensor.

25

26 Preferably, the secondary sensor is operable to sense the
27 location of the apparatus.

28

29 This provides a sensor platform ideally suited to
30 tracking applications, where the context of the local
31 environment can be used to determine whether to activate
32 the generally higher power location sensing secondary
33 sensor.

1

2 Alternatively, the secondary sensor is operable to sense
3 a secondary local environment stimulus.

4

5 Preferably, the secondary local environment stimulus
6 comprises humidity.

7

8 Preferably, the secondary local environment stimulus
9 comprises gas concentration.

10

11 Preferably, the secondary local environment stimulus
12 comprises one of: temperature, illumination, barometric
13 pressure, mechanical pressure, gas concentration,
14 electrical fields, magnetic fields electromagnetic field
15 strength at a particular frequency, and electromagnetic
16 field strength at a range of frequencies..

17

18 According to the second aspect of the present invention
19 there is provided a server operable to communicate with a
20 plurality of the apparatus according to the first or
21 second aspect, so as to receive the transmitted sensor
22 data signal, and to configure at least one of the primary
23 and secondary rules.

24

25 The rules which govern the behaviour of a tracking device
26 monitor the current expected context of the object being
27 tracked. However, context will not be static, they will
28 change as the circumstances and use of the object
29 changes. This server allows the rules to be changed
30 remotely according to the changing expected context.

31

32 The present invention will now be described by way of
33 example only with reference to the figures in which:

1

2 Figure 1 illustrates, in schematic form, a remote sensor
3 platform according to the preferred embodiment of the
4 present invention;

5

6 Figure 2 illustrates, in schematic form, the sensor
7 platform with a secondary decision making and sensor data
8 reporting components; and

9

10 Figure 3 illustrates, in schematic form, a sensor device
11 management server.

12

13 The preferred embodiment of the present invention
14 provides an apparatus in a sensor platform having low and
15 high powered components that is configured to improve
16 both battery life and responsiveness of the sensor
17 platform. The sensor platform of this embodiment is
18 suitable for tracking objects such as valuables or
19 paintings.

20

21 With reference to figure 1, the primary sensors 2 are
22 used to monitor the environment of an object being
23 tracked (not shown) with the apparatus. The primary
24 sensors include a temperature sensor 4, a motion sensor 6
25 and an illumination sensor 8. A pressure sensor, such a
26 barometric (air) pressure sensor (not shown) can be used
27 as a primary sensor, or for example humidity or gas
28 concentration can be measured. The relatively high
29 powered secondary sensors 10 include a GPS radio location
30 sensor 12 and another sensor 14 e.g. for sensing humidity
31 or CO₂. The primary processing means 16 has a low power
32 processing module 18 that includes GPS software 20. The
33 processing means is a microcontroller, but may be a

1 computer or a software object within a computer or stored
2 on carrier such as computer memory. The low power
3 processing module of the primary processing means refers
4 to primary rules 22 and generates an exception log 24.
5 The primary sensors are those which would be active in a
6 normal or idle state of the tracker. The electronic
7 control circuitry associated with these sensors may be
8 very simple and consume very little power, meaning that
9 the tracker can remain in the idle state for periods of
10 several years. The primary sensors are configured to
11 produce a trigger if a stimulus that they are measuring
12 goes outside of preset boundaries. For example, this
13 could be a level of illumination indicating a move into
14 daylight, a rapid change of temperature indicating a move
15 into a different room, a series of sudden jerky movements
16 or an unusual change in air pressure. A trigger from any
17 one of the primary sensors causes the tracker to change
18 from its idle state into a slightly higher power mode, in
19 which the primary processing means 16 is activated.

20
21 The primary processing means has inputs operable to
22 receive trigger signals from the primary sensors. It uses
23 these signals to determine whether to activate a
24 secondary sensor using the primary rules. Based on this
25 decision, it may activate the secondary sensor by sending
26 an activation signal via an output to the secondary
27 sensor. In response to the primary sensor input signals
28 in some cases the primary processing means will do
29 nothing at all, in other cases a check of the secondary
30 sensors will be required, perhaps including the GPS
31 location sensor to verify that the object being tracked
32 is still where it is supposed to be. Additional secondary
33 sensors may need to be checked, for example a humidity

1 check if an old art work was being secured. Any other
2 local environmental stimulus can be sensed by a secondary
3 sensor to monitor the context of the local environment,
4 such as temperature, pressure, illumination, gas (e.g.
5 CO₂) concentration. If the primary and/or secondary
6 sensors indicate a problem, again according to the
7 primary rules, then the tracker may progress into the
8 next non idle state. The circumstances which caused the
9 move into the first non-idle state are logged as
10 exceptions for later reporting and reference. The primary
11 rules may also be reconfigured, for future use.
12 Additional control over the period for which a context is
13 active or the selection of an active context from a
14 plurality of predefined contexts may be provided. This
15 may require the selection of a set of rules.

16
17 The primary processing means may log sensor data from the
18 primary and/or secondary sensors to store sensed
19 conditions for reference in future decision making in
20 order to determine whether to activate the secondary
21 sensor.

22
23 The primary processing means can use the rate of change
24 of the received signals from one or more of the primary
25 and secondary sensors to determine whether to activate
26 the secondary sensor.

27
28 Other primary and secondary sensors could be used to
29 monitor the context of the local environment. For
30 example, chemical sensors (for example Volatile Organic
31 Chemicals (VOCs) such as those given off by paints).

32

1 Pressure in the mechanical sense of a weight on a surface
2 rather than barometric could be another type of primary
3 or secondary sensor.

4
5 Other potential parameters to sensed by the primary and
6 secondary sensors may include: electrical fields,
7 magnetic fields (for example by magnetometers used to
8 derive magnetic compass heading, similar effect to motion
9 sensing since movement will inevitably include some
10 rotation with respect to magnetic North etc.) and
11 electromagnetic fields. For example, in the latter case
12 the electromagnetic field strength on a particular
13 frequency or range of frequencies could be used to detect
14 a context change.

15
16 Any of these could be primary or secondary sensors and
17 the combination and use would depend upon the
18 application.

19
20 With reference to figure 2, the primary sensors 2 and
21 secondary sensors 10 are shown in communication with the
22 primary processing means 16. A secondary processing
23 means 26 has a relatively high power processing module 28
24 that refers to secondary rules 30 and generates an
25 exception log 32. A GSM (Global System for Mobile
26 communications) / GPRS (General Packet Radio Service)
27 modem 34 reports sensor data via the aerial 36 wirelessly
28 to the internet 38. Other reporting means may also be
29 used, using for example Zigbee, WLAN (Wireless Local Area
30 Network), UWB (Ultra-Wide Band), Bluetooth, 3G, 4G, EDGE,
31 etc. for transmitting the sensor data.

32

1 The secondary processing means 26 is operable to activate
2 the GSM/GPRS modem, conditionally upon an output of at
3 least one of the primary and secondary sensors. In this
4 embodiment, the data is prepared by the low power primary
5 processing means 16. The secondary processing means
6 operates using the configurable secondary rules 30, and
7 is also operable to configure the primary rules in the
8 primary processing means 16. The primary processing
9 means 16 is operable to activate the secondary processing
10 means 26, conditionally upon a trigger output of at least
11 one of the primary 2 and secondary 10 sensors.

12

13 When the secondary processing means 26 is active, the
14 tracker consults its secondary rules 30 about what to do,
15 given the data from the lower level functions which
16 caused it to wake up. For example, it may do nothing at
17 all and turn off all but the primary sensors, it may up-
18 date the primary rules and turn off all but the primary
19 sensors after logging the exception, it may monitor the
20 situation using some or all of the available sensors, or
21 it may activate the GSM/GPRS modem and report selected
22 sensor data via the internet to a server.

23

24 With reference to Figure 3 a server 40 is connected to
25 the internet 38 communicates with one or more of the
26 tracker devices. The server receives the sensor data
27 transmitted from the GSM/GPRS modem and configures at
28 least one of the primary and secondary rules. This
29 configuration may be conditional on the received
30 transmitted signal. It does this configuration with
31 reference to its own set of tertiary rules 42. The
32 server 40 generates further reports and management
33 information, which is distributed via the internet 38 to

1 users' terminals 44. In the embodiment being used to
2 track a painting, for example, the parameters describing
3 the context of the painting on display on a gallery will
4 be very different to those experienced when it is in
5 transit between exhibitions or in storage. Changing
6 between contexts and changing the primary and secondary
7 rules to match, may be governed by the users of the
8 tracking system, or automatically using the tertiary
9 rules and conditionally on the received transmitted
10 signal. Users will know if a painting is in transit and
11 they will also know where it is going and what the
12 environment will be in the new location. Therefore, for
13 example, if the tracker is working properly and the
14 painting is moved it will wake up and report the change.
15 At this point, the server, according to its own tertiary
16 rules, may accept the reports and up-date the primary and
17 secondary rules to conform to what it knows is happening.
18 It may request, for example, half-hourly location reports
19 whilst in transit with an increase in frequency to once
20 per minute if the additional sensors detect undue
21 temperature changes or lighting changes that may indicate
22 a problem with the transport.

23

24 In standard tracking or telematics there is little
25 opportunity for the server to influence the behaviour of
26 the remote device. It is an advantage of the present
27 invention that the server plays an important role and is
28 part of the overall capability of the remote tracker.
29 The inclusion of the server in this way means that the
30 tracking device can be thought of as partly the remote
31 sensor platform and partly the software running on the
32 device management server 40.

33

1 The present invention advantageously provides the
2 opportunity to embed the tracking device inside an item
3 with no, or a sparse, external power source. In this case
4 the device can be designed to use its power over a long
5 period, perhaps greater than the expected life of the
6 item into which it is embedded. This provides for context
7 monitoring of items by devices completely enclosed in the
8 fabric of an item and inaccessible without at least
9 partially destroying the item. Examples could be trackers
10 within the wall or floor of a caravan or built into the
11 casing of high value medical equipment.

12
13 The present invention, with its arrangement of rules,
14 processing means and sensors reduces the overall power
15 consumption of the remote device and increases the
16 relevance of information reported. The layers of
17 activity and intelligence ensure that the minimum amount
18 of power is being consumed at any time. The next stage
19 of the device is only woken up when absolutely needed.
20 Redundant information is also minimised. Rather than
21 many reports from a tracker, which amounts to "I am still
22 here and everything is fine", users may receive
23 information only when that information is important.
24 This feature is increasingly valuable as the number and
25 varieties of tracking devices expands. It would make a
26 great difference to a person responsible for hundreds of
27 tracked assets, if he only received reports from those
28 assets which required attention and not hundreds of
29 essentially information-free reports from all assets all
30 the time. In the latter situation, it is more the
31 absence of information which is significant, i.e. a
32 missed report, and not the presence of information as
33 provided by the present invention.

1

2 The decision making and configuration of rules uses
3 primary, secondary and tertiary rules. However, other
4 forms of logic or decision making may be used to achieve
5 the same effect.

6

7 The device management server may be integrated into
8 larger software applications used by businesses to
9 control their operations. In that case, a complete
10 automated asset management tool may be made available to
11 a wide variety of business, organisations and, through
12 service provision, to individuals.

13

14 Further modifications and improvements may be added
15 without departing from the scope of the invention
16 described by the claims.

1 Claims

2

3 1. An apparatus comprising:

4 a primary sensor operable to sense a local
5 environment stimulus;

6 a primary sensor input operable to receive a
7 signal from the primary sensor;

8 a secondary sensor output operable to send an
9 activation signal to a secondary sensor; and

10 a primary processing means operable to use the
11 signal received from the primary sensor to monitor
12 the environment of the primary sensor and thereby
13 determine whether to activate the secondary sensor
14 and operable to cause the secondary sensor output to
15 send an activation signal to the secondary sensor.

16

17 2. The apparatus of claim 1 wherein the apparatus
18 comprises a plurality of the primary sensors each
19 operable to sense a different local environment
20 stimulus and the primary processing means is
21 operable to use signals received from the plurality
22 of the primary sensors to monitor the environment of
23 the plurality of primary sensors and thereby
24 determine whether to activate the secondary sensor.

25

26 3. The apparatus of claim 1 or claim 2 wherein the
27 local environment stimulus comprises temperature.

28

29 4. The apparatus of any previous claim wherein the
30 local environment stimulus comprises illumination.

31

32 5. The apparatus of any previous claim wherein the
33 local environment stimulus comprises one of:

1 humidity, gas concentration, barometric pressure,
2 mechanical pressure, gas concentration, electrical
3 fields, magnetic fields electromagnetic field
4 strength at a particular frequency, and
5 electromagnetic field strength at a range of
6 frequencies.

7
8 6. The apparatus of any previous claim wherein the
9 operation of the primary processing means is
10 triggered by a signal received from the primary
11 sensor.

12
13 7. The apparatus of any previous claim wherein the
14 primary sensor is operable to be periodically
15 powered down.

16
17 8. The apparatus of claim 7 wherein the periodic
18 powering down of the primary sensor is under the
19 control of the primary processing means.

20
21 9. The apparatus of any previous claim wherein the
22 primary processing means is configurably operable to
23 determine whether to activate the secondary sensor.

24
25 10. The apparatus of claim 9 wherein the primary
26 processing means is remotely configurable.

27
28 11. The apparatus of claim 9 or claim 10 wherein the
29 configuration of the primary processing means is
30 active for a predetermined period.

31

1 12. The apparatus of any of claims 9 to 11 wherein the
2 configuration of the primary processing means is
3 selected from a set of predetermined configurations.
4

5 13. The apparatus of any of claims 9 to 12 wherein the
6 configurable operation of the primary processing
7 means uses configurable primary rules.
8

9 14. The apparatus of claim 13 wherein the configurable
10 primary rules are remotely configurable.
11

12 15. The apparatus of any previous claim further
13 comprising a secondary sensor input operable to
14 receive a signal from the secondary sensor and the
15 primary processing means is operable to use the
16 signal received from the secondary sensor to
17 activate a secondary processing means.
18

19 16. The apparatus of any previous claim wherein the
20 primary processing means is operable to log sensor
21 data corresponding to the received signals from one
22 or more of the primary and secondary sensors.
23

24 17. The apparatus of claim 16 wherein the operation of
25 the primary processing means uses the logged sensor
26 data to determine whether to activate the secondary
27 sensor.
28

29 18. The apparatus of any previous claim wherein the
30 operation of the primary processing means uses the
31 rate of change of the received signals from one or
32 more of the primary and secondary sensors to
33 determine whether to activate the secondary sensor.

1

2 19. The apparatus of any of claims 15 to 18 further
3 comprising a reporting means operable to transmit a
4 sensor data signal based on the received signal from
5 at least one of the primary and secondary sensors
6 and the apparatus further comprises the secondary
7 processing means operable to activate the reporting
8 means conditionally upon the received signal from at
9 least one of the primary and secondary sensors.

10

11 20. The apparatus of claim 19 wherein the secondary
12 processing means is configurably operable to
13 activate the reporting means.

14

15 21. The apparatus of claim 20 wherein the secondary
16 processing means is remotely configurable.

17

18 22. The apparatus of any of claims 19 to 21 wherein the
19 operation of the secondary processing means uses
20 configurable secondary rules.

21

22 23. The apparatus of claim 22 wherein the configurable
23 secondary rules are remotely configurable.

24

25 24. The apparatus of any of claims 19 to 23 wherein the
26 secondary processing means is operable to configure
27 the primary rules.

28

29 25. The apparatus of any of claims 19 to 24 wherein the
30 primary processing means is further operable to
31 activate the secondary processing means,
32 conditionally upon an output of at least one of the
33 primary and secondary sensors.

1

2 26. The apparatus of any of previous claims further
3 comprising the secondary sensor that has a higher
4 power consumption than the primary sensor.

5

6 27. The apparatus of claim 26 wherein the secondary
7 sensor is operable to sense the location of the
8 apparatus.

9

10 28. The apparatus of claim 26 or 27 wherein the
11 secondary sensor is operable to sense a secondary
12 local environment stimulus.

13

14 29. The apparatus of claim 28 wherein the secondary
15 local environment stimulus comprises humidity.

16

17 30. The apparatus of claim 28 or 29 wherein the
18 secondary local environment stimulus comprises gas
19 concentration.

20

21 31. The apparatus of any of claims 28 to 30 wherein the
22 secondary local environment stimulus comprises one
23 of: temperature, illumination, barometric pressure,
24 mechanical pressure, gas concentration, electrical
25 fields, magnetic fields electromagnetic field
26 strength at a particular frequency, and
27 electromagnetic field strength at a range of
28 frequencies.

29

30 32. A server operable to communicate with a plurality of
31 the apparatus according to any of claims 19 to 31,
32 so as to receive the transmitted sensor data signal,

- 1 and to configure at least one of the primary and
- 2 secondary rules.

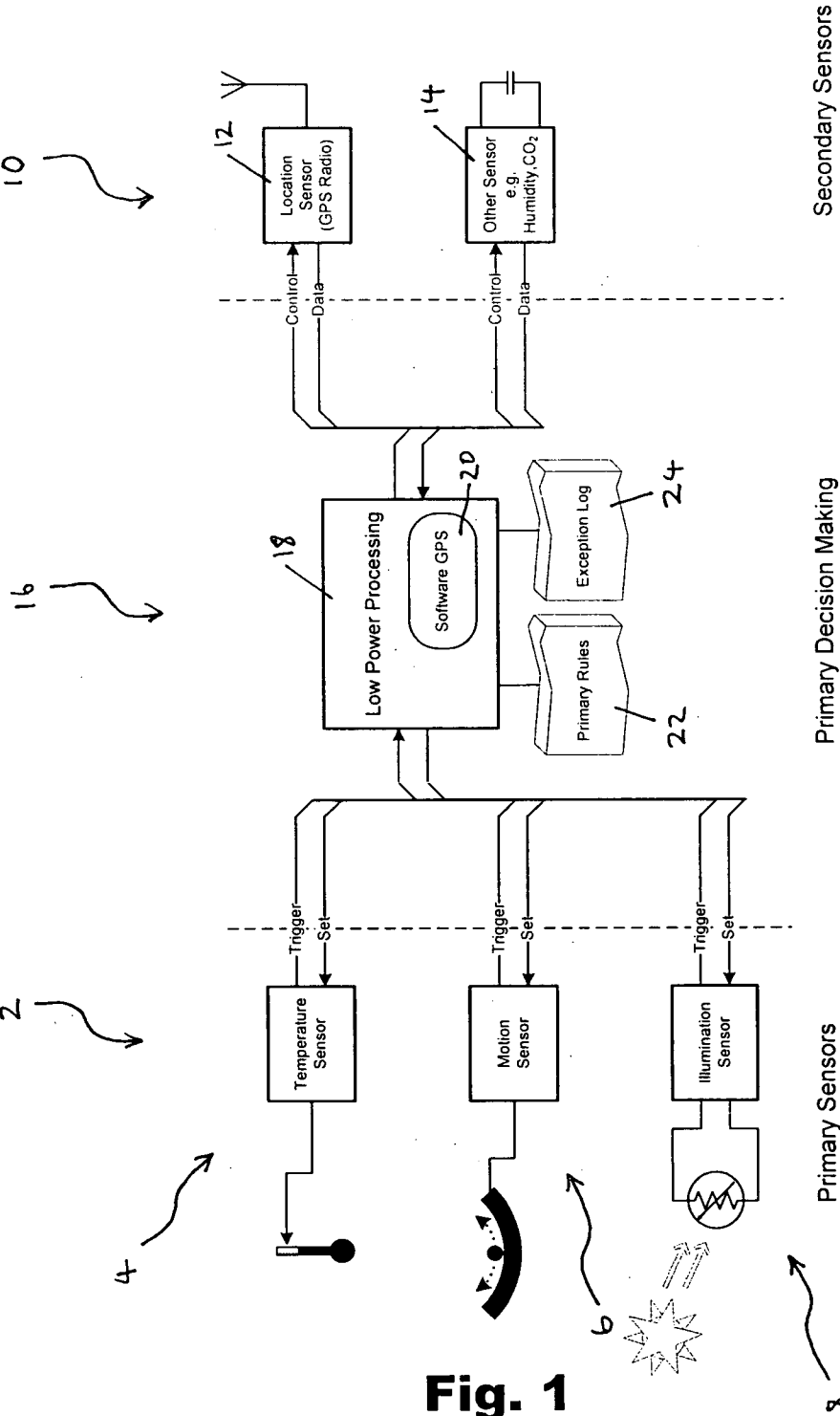


Fig. 1

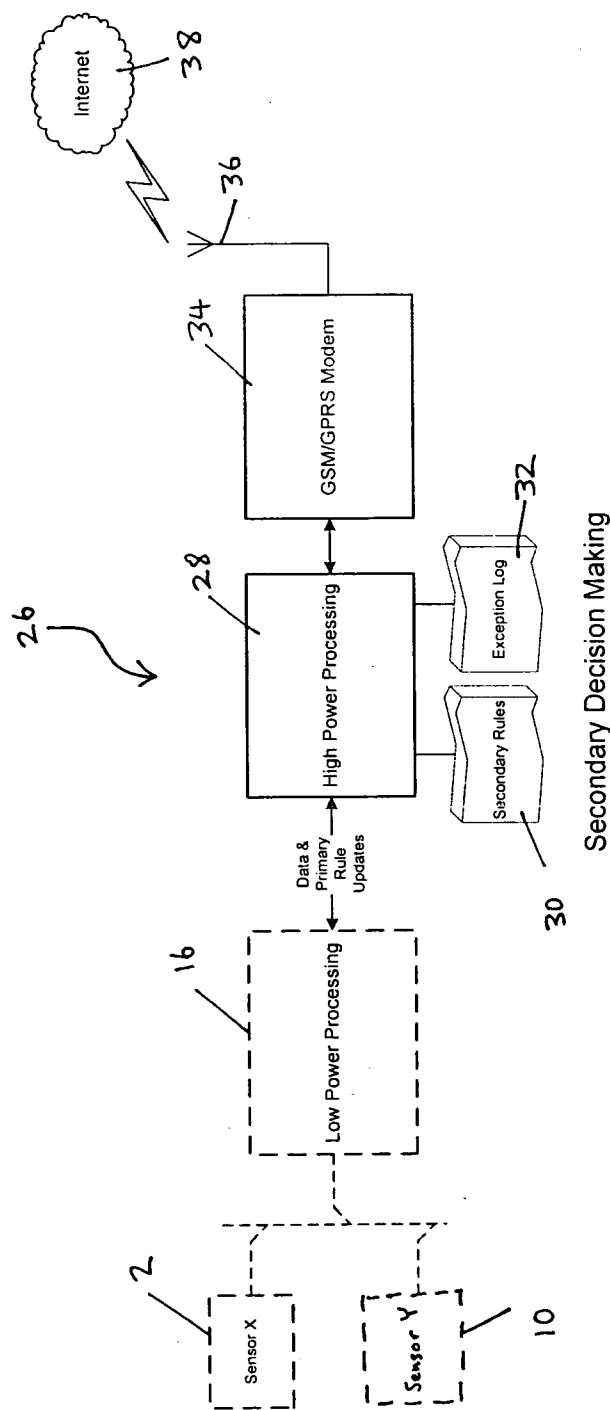


Fig. 2

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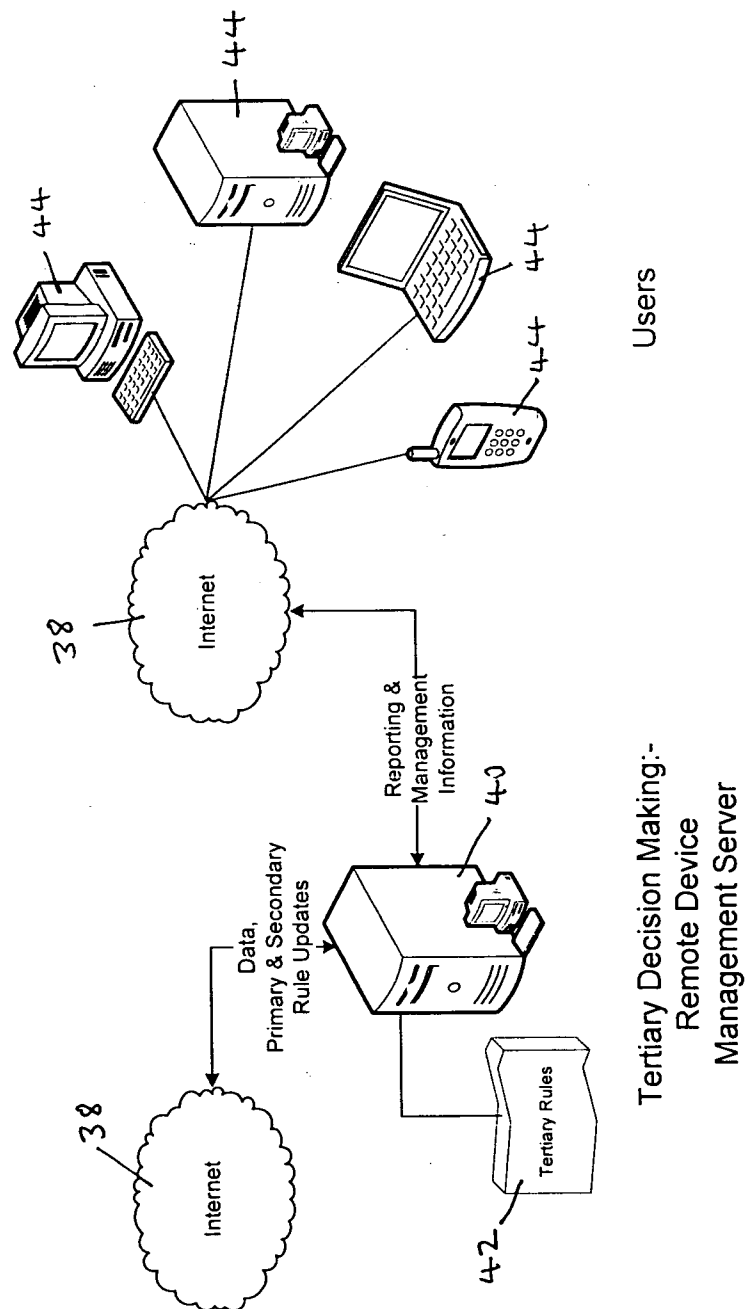


Fig. 3

INTERNATIONAL SEARCH REPORT

International application No
PCT/GB2007/003136

A. CLASSIFICATION OF SUBJECT MATTER
INV. G08B29/18

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
G08B H04M B60R G01S

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practical, search terms used)

EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 2004/176127 A1 (BALLANTYNE WAYNE WIGGINS [US] ET AL) 9 September 2004 (2004-09-09)	1-9, 11-14, 18,26-32
Y	paragraphs [0003], [0004] paragraph [0015] paragraph [0017] paragraph [0020] paragraphs [0024] - [0027] paragraphs [0032], [0033]	10, 15-17, 19-25
Y	US 2003/151501 A1 (TECKCHANDANI ASHOK [US] ET AL) 14 August 2003 (2003-08-14) paragraphs [0038], [0041], [0042] paragraph [0048]	10, 15-17, 19-25
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☒ Further documents are listed in the continuation of Box C.

☒ See patent family annex.

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- * & * document member of the same patent family

Date of the actual completion of the international search

19 December 2007

Date of mailing of the international search report

02/01/2008

Name and mailing address of the ISA/
European Patent Office, P.B. 5818 Patentlaan 2
NL - 2280 HV Rijswijk
Tel. (+31-70) 340-2040, Tx. 31 651 epo nl,
Fax: (+31-70) 340-3016

Authorized officer

DE LA CRUZ VALERA, D

INTERNATIONAL SEARCH REPORT

International application No
PCT/GB2007/003136

C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

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