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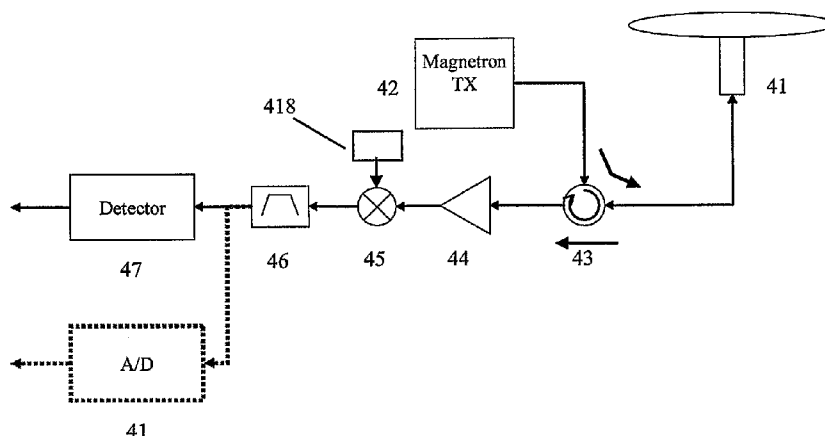
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(54) Title: A METHOD AND RADAR SYSTEM FOR COHERENT DETECTION OF MOVING OBJECTS



(57) Abstract: The present invention provides a coherent radar system based on a modification of standard non-coherent radar without Moving Target Indication. Typical radars in this class are Navigation radars which are mass produced with low cost components. These radars utilize a magnetron in the transmitter which is a random phase device. In the present invention, the received signal is extracted just prior to amplitude detection process (where phase information is lost), and digitized using an analogue to digital converter providing coherent detection based on correlation between the transmitted pulse and the received signal.

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A METHOD AND RADAR SYSTEM FOR COHERENT DETECTION OF MOVING OBJECTS

Technical field

The present invention relates to the field of target
5 detection, in particular by means of radar systems and in
more particular by using radars for coherent detection of
moving targets.

Background

Radars without moving target indication use a directional
10 antenna and transmit pulses when scanning the horizon. The
time from transmission to reception of a pulse provides the
range to a reflecting target. By drawing the received
signal power versus antenna angle, the resulting image is a
representation of the surrounding environment. Navigation
15 radars use this principle to draw land area and other ships
on the screen.

Fig. 1 shows a conventional navigation radar system as used
on most ships. This system employs a magnetron 12 as the
transmitter source. A magnetron is a self-oscillating tube
20 that may deliver a strong signal at a low cost. This is a
random phase device, as the heating of the tube during the
transmitting pulse will change its resonant frequency and
shift the phase of the emitted signal. The signal from the
magnetron 12 is lead to a scanning antenna 11. The
25 corresponding reflected or back-scattered signals are
received by the antenna 11 and processed in a receiving
channel including the components RF amplifier 14, mixer 15,
local oscillator 18, Intermediate Frequency amplifier and
filter 16, and detector 17. The detector 17 is normally a
30 crystal (diode) amplitude detector. The signals from the
detector 17 may be observed on an old fashioned Plan
Projection Indicator (not shown), or digitized and observed
on a raster display device (computer screen).

To protect the receiving channel from the strong transmitter signal, the signals are routed through a circulator 13. In addition, the receiving channel will be muted or turned off during the transmitting period.

5 In order to detect targets in a cluttered environment (e.g. over land), a radar has to include means for extracting moving targets from the surrounding clutter. Multiple methods have been used, but may be divided into two main categories:

- 10 • Non-coherent detection where the detected video (amplitude) signal from two or more antenna scans are compared in amplitude to detect changes, thus not utilising signal phase
- 15 • Coherent detection where signal phase changes from pulse to pulse is used to extract

The system illustrated in Fig. 1 may to be used for detecting moving targets, i.e. according to the first alternative, if received signals are stored during a receiving period (scan), and compared with signals received
20 during the subsequent receiving period.

Non coherent moving target indication (MTI) typically is slow (as at least two complete scans of the antenna is needed for detection) and requires that the target moves in the order of one or more resolution cell within the antenna
25 scan time. The sensitivity is also quite low due to the fact that only detected video is used.

Most modern radar systems utilize coherent detection where the signal phase from two or more pulses is compared for detection of target radial speed towards or away from the
30 radar. These systems employ a stable oscillator that is used both for generation of the transmitter carrier frequency and for receiver down conversion. Thus the

intermediate frequency signal in the receiver is coherent with the transmitted pulse signal and the received signal phase depends on the target distance. A movement of the target towards or away from the radar corresponding to a fraction of a wavelength will result in a change in the received signal phase.

Fig. 2 shows the elements of such a coherent radar system. Here radar pulses are produced in a signal generator source 28. The generated pulses are modulating the signal from a stable carrier oscillator 212 in a mixer 29. The transmitter pulses are then amplified in a power amplifier 210 filtered in a filter 211 and delivered to the antenna 21 via the circulator 23. On receive the signals are down-converted in the mixer 25 using the carrier oscillator 212. In this way received signals will be coherent with the transmitted pulses. Subsequent pulses are compared after detection in detector 27. This system also includes an RF amplifier 24 following the circulator 23, a mixer 25 and an IF amplifier/filter 26. A moving target will show up as a phase difference between subsequent pulses. Movements as small as a fraction of the carrier wavelength may be detected.

Construction of coherent radars is costly due to the need of phase stability in high power components. Therefore a scheme of coherent-on-receive MTI has previously been employed, especially in high power radars. In this system a fast local oscillator is locked to transmitter phase and frequency during the short period of transmission. After the transmitter pulse, the oscillator system is designed to hold the phase constant in the subsequent receive period. This oscillator is used for down-conversion of the received signal, and thus provides coherent detection even if the transmitter has random phase.

Fig. 3 illustrates this concept in more detail. This system uses a free-running transmitter source 313. Phase coherence

is established during receive, as the receiving channel uses a local oscillator 318 that is synchronized with the phase of the transmitting source 313. Also this system includes an RF amplifier 34, mixer 35 and IF
5 filter/amplifier 36.

Coherent-on-receive systems require a phase locking mechanism that is fast enough to lock within the duration of a pulse and is stable enough to provide correct phase in the entire reception period. This is usually done by means
10 of a quite complex phase lock mechanism. The system also requires a stable phase within the pulse, thus increasing the requirements to the expensive transmitter subsystem.

As explained above, existing coherent radar systems are very expensive restricting their use to e.g. surveillance
15 of the airspace around airports. However, coherent radar systems could be very useful in other fields as well, and thus, there is a need for a radar system with similar properties, but at a lower cost.

Summary

20 The present invention provides a method and system for detection of moving targets. In a particular application, the invention provides a coherent radar system based on a modification of standard non-coherent radar without MTI. Typical radars in this class are Navigation radars which
25 are mass produced with low cost components. These radars utilize a magnetron in the transmitter which not only has random phase from pulse to pulse, but the phase varies throughout the pulse.

The concept is based on extracting the received signal just
30 prior to amplitude detection process (where phase information is lost) and digitising this signal using an analogue to digital converter providing coherent detection

based on correlation between the transmitted pulse and the received signal.

The method provides a cost-efficient way to achieve coherent detection and moving target indication using off the shelf low cost components.

Existing methods for coherent radars utilise complex hardware and specially designed electronics in order to achieve the necessary phase stability. This solution puts none of these requirements to the radar system.

In addition, the inventive system may be made more compact than prior art coherent radar systems. This is mainly due to the use of the magnetron, which delivers a large power in a small space. This may allow the use of coherent radar systems in confined spaces that normally will not room such equipment, such as in aeroplanes.

Additionally target detection is enhanced, due to matched filter processing of the received echoes, thus allowing for unintentional or intentional modulation of the pulse.

In particular the invention relates to a method for coherent detection of moving targets, said method including transmitting random phase pulsed signals towards the targets, receiving echo signals produced by said pulsed signals and finally correlating the pulsed signals with the echo signals, as claimed in claim 1 below.

The invention also includes a system with an antenna, a random phase transmitting unit, a signal coupling unit, a receiving unit adapted to transpose received signals to intermediate frequency signals, an A/D (Analogue/Digital) converter adapted to digitize the intermediate frequency signals, and a processing unit adapted to correlate signals emitted by said transmitting unit with received echo signals, as claimed in claim 5.

Brief description of the drawings

The invention will now be described in detail in reference to the appended drawings, in which:

Fig. 1 is a schematic drawing of the main components of a
5 conventional navigation radar (prior art),

Fig. 2 is a schematic drawing of the main components of a coherent source radar (prior art),

Fig. 3 is a schematic drawing of the main components of a coherent-on receive radar (prior art),

10 Fig. 4 is a schematic drawing of a radar system according to the present invention.

Detailed description

The concept of the present invention is based on extracting the received signal just prior to amplitude detection
15 process (where phase information is lost) and digitising this signal using an analogue to digital converter.

Fig. 4 illustrates the invention. The system shown in the figure reuses all components of the conventional navigation radar of Fig. 1, such as antenna 41, magnetron 42,
20 circulator 43, pre-amplifier 44, mixer 45, local oscillator 28 and IF filter 46. The amplitude detector 47 may be retained in the system, even though it will have no function regarding the invention.

The inventive system has two important differences from the
25 prior art navigation radar in Fig.1:

The addition of an A/D converter 415 (shown in stippled outline on Fig. 4) digitizing the IF signal, and the receiving chain being turned on even during the transmit period.

Due to the high power in the transmitter system, some of the transmitter signal will leak through the receiver system and arrive at the A/D converter 415. Thus, by starting digitisation just prior to start of transmission and stopping transmission when echoes from the furthest
5 range has been received, the resulting data array output from the A/D converter will contain:

- Digitised transmitted pulse (in the start of the array)
- 10 • Digitised echo reception (in the rest of the array)

By correlating the Digitised echo reception part of the array with the Digitised transmitted pulse part of the array an echo-array with phase intact is provided. This array may then be used for pulse-to-pulse MTI with any
15 coherent MTI method.

The correlation in question is a standard cross correlation product z_k :

$$z_k = \sum_{i=1}^N x_i \cdot y_{i-k}$$

Where x is the reception part and y is the transmitted
20 pulse part of the array; i and k are indexes in the respective data arrays.

The invention provides a cost-effective coherent radar system with small dimensions. This may enlarge the application of coherent radar systems to e.g. weather
25 radars used in aeroplanes.

In general, the invention may be used in any motion detecting system using self-oscillating transmitters working on any frequency and in any medium. One particular application is in sonar systems using self-oscillating
30 transducers. In many ways such systems correspond closely

to navigation radars, and will thus not be described in detail here. By reading the description above, any person skilled in the art will understand how the invention may be utilized in this field as well.

C l a i m s

1. A method for coherent detection of moving targets, said method including:
transmitting random phase pulsed signals towards the
5 targets,
receiving echo signals produced by said pulsed signals,
characterized in correlating the pulsed signals
with the echo signals.
2. A method as claimed in claim 1, wherein said signals
10 are radar signals.
3. A method as claimed in claim 1, wherein said signals
are sonar signals.
4. A method as claimed in claim 1, wherein said signals
are correlated using cross correlation.
- 15 5. A method as claimed in claim 1, wherein signals are
received both during transmitting and receiving periods.
6. A method as claimed in claim 1, the method including
to digitize the signals.
7. A method as claimed in claim 1, the method including
20 transposing the signals to an intermediate frequency and
digitizing the signals.
8. A system for coherent detection of moving targets,
said system including:
an antenna (41),
25 a random phase transmitting unit (42),
a signal coupling unit (43),
a receiving unit adapted to transpose received signals to
intermediate frequency signals,
characterized in an A/D converter (415) adapted to
30 digitize the intermediate frequency signals,

a processing unit adapted to correlate signals emitted by said transmitting unit (42) with received echo signals.

9. A system as claimed in claim 8, wherein the system is a radar system.

5 10. A system as claimed in claim 8, wherein the system is a sonar system.

11. A system as claimed in claim 9, wherein the transmitting unit (42) is a magnetron.

10 12. A system as claimed in claim 8, wherein the signal coupling unit (43) is a circulator.

13. A system as claimed in claim 8, wherein said transmitting unit (42) and receiving unit are components in a conventional navigation radar device.

15 14. A system as claimed in claim 8, wherein the receiving unit is adapted to receive signals both during transmitting and receiving periods.

15. A system as claimed in claim 8, wherein the processing unit is adapted to correlate said signals using cross correlation.

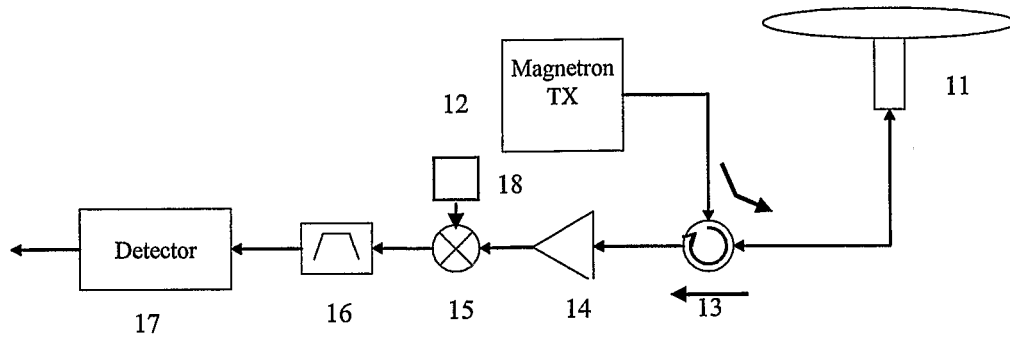


Fig. 1

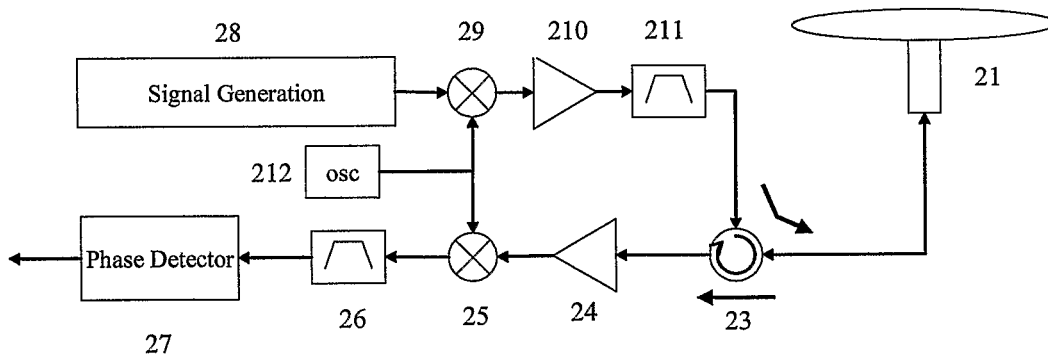


Fig. 2

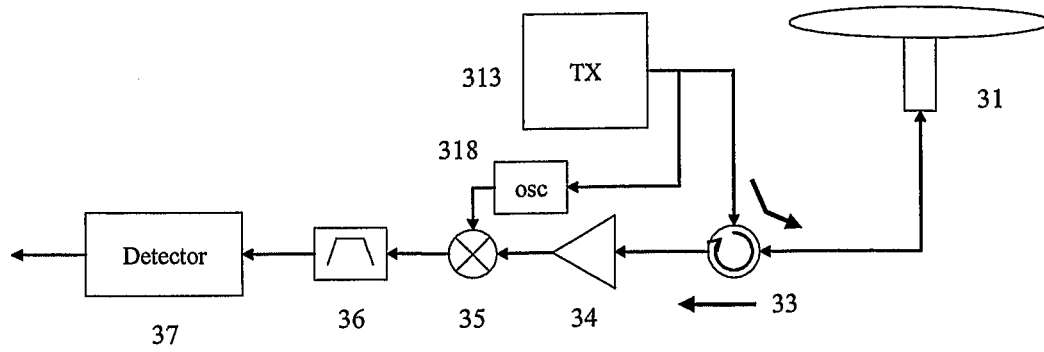


Fig. 3

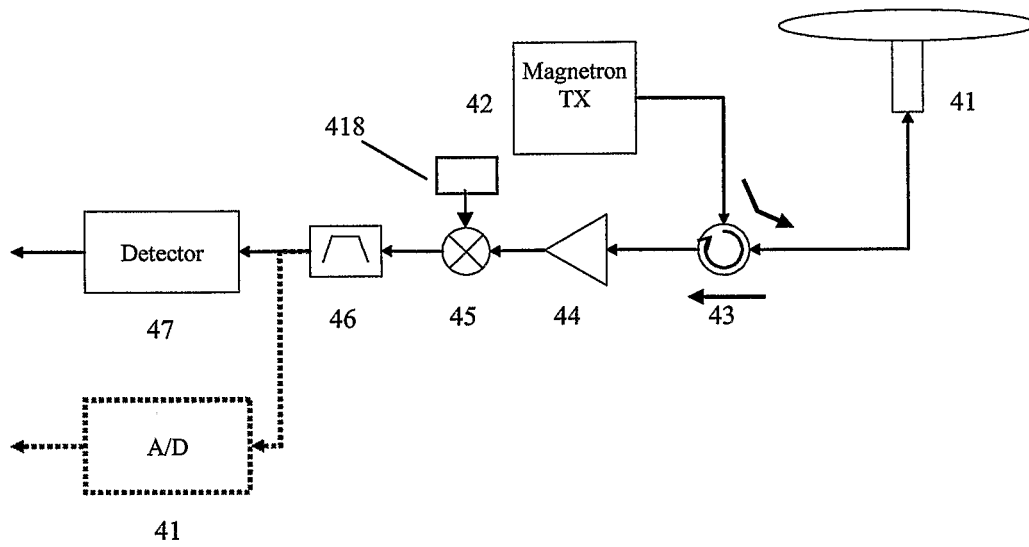


Fig. 4

INTERNATIONAL SEARCH REPORT

International application No
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A. CLASSIFICATION OF SUBJECT MATTER INV. G01S13/10 G01S13/524		
According to International Patent Classification (IPC) or to both national classification and IPC		
B. FIELDS SEARCHED Minimum documentation searched (classification system followed by classification symbols) G01S		
Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched		
Electronic data base consulted during the international search (name of data base and, where practical, search terms used) EPO-Internal, WPI Data		
C. DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 4 768 035 A (THURBER ROBERT E [US] ET AL) 30 August 1988 (1988-08-30) column 2, line 42 - column 4, line 59 abstract; figure 2	1-15
X	US 4 626 856 A (PIERSON WILLIS A [US] ET AL) 2 December 1986 (1986-12-02) column 1, line 59 - line 67 column 3, line 26 - column 8, line 21; figures 1,2,6,7	1-15
X	US 3 903 525 A (MULLINS WILLIAM H ET AL) 2 September 1975 (1975-09-02) column 5, line 32 - line 53; figure 2 column 6, line 39 - line 48; figure 3 column 7, line 7 - line 38 column 27, line 40 - line 43	1-15
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Date of the actual completion of the international search 17 November 2006		Date of mailing of the international search report 27/11/2006
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International application No

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C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 4 040 055 A (DONAHUE THOMAS H ET AL) 2 August 1977 (1977-08-02) column 5, line 4 - column 7, line 38 abstract; figure 2 -----	1-15

INTERNATIONAL SEARCH REPORT

information on patent family members

International application No

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Patent document cited in search report	Publication date	Patent family member(s)	Publication date
US 4768035	A	30-08-1988	NONE
US 4626856	A	02-12-1986	NONE
US 3903525	A	02-09-1975	NONE
US 4040055	A	02-08-1977	NONE