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**EUROPEAN PATENT APPLICATION**

21 Application number : **92302263.6**

51 Int. Cl.<sup>5</sup> : **E04H 12/18, H01Q 1/12, E05F 15/12**

22 Date of filing : **16.03.92**

30 Priority : **20.03.91 GB 9105917**

43 Date of publication of application : **23.09.92 Bulletin 92/39**

84 Designated Contracting States : **BE CH DE ES FR GB IT LI NL**

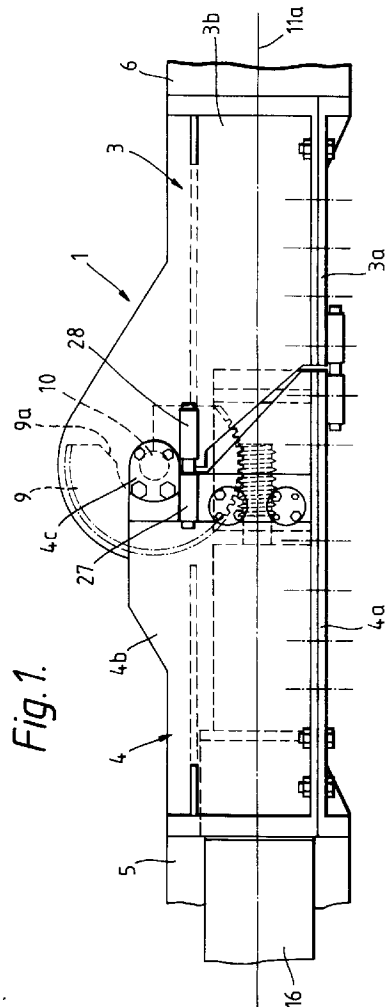
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54 **A power actuatable, openable and closeable, lockable and unlockable, hinge assembly.**

57 A power actuatable, openable and closable, lockable and unlockable, hinge assembly (1) is provided having pivot means (2), two hinge members (3, 4) pivotally interconnectable by the pivot means (2) for relative angular movement between an open position in which the hinge members (3, 4) extend substantially co-axially in end-to-end relationship and a closed position in which one hinged member is angularly displaced, with respect to the other hinge member, about the pivot means (2) out of the end-to-end relationship. Power drivable actuator locking means (7) are included having a first movable portion (8, 29) carried on one of the hinge members (3, 4) and a second co-operating movable portion (9, 30) carried on the other of the hinge members (3, 4) which power drivable actuator locking means (7) is selectively operable to open and lock the hinge members (3, 4) together in the substantially co-axial end-to-end open position relationship, and to unlock and close the hinge members (3, 4).



This invention relates to a power actuatable, openable and closable, lockable and unlockable, hinge assembly having two pivotally interconnected hinge members.

Hinge assemblies are known having two pivotally interconnected hinge members but such assemblies are conventionally openable by a spring acting between the members to bias them apart into an open position. These conventional assemblies are normally locked in the open position by means of a pin which drops into apertures on the members in the open position. With such known assemblies no provision is made for unlocking or closing the assembly and this presents a serious drawback for some applications such as where it is necessary to open and close a hinge assembly at a position or location remote from the operator.

For use on a deployable articulated mast or boom a hinge assembly requires to be strong and to afford the possibility of opening and closing by powered actuation so that the mast or boom can be collapsed into individual sections and extended as desired. Such a hinge assembly should be strong enough to withstand side forces on the mast or boom when it is in the deployed extended position and should be capable of being lockable in the open position corresponding to extension of the mast or boom and unlockable when it is desired to close the hinge assembly and thereby collapse the mast or boom.

According to the present invention there is provided a power actuatable, openable and closable, lockable and unlockable, hinge assembly characterised by having pivot means, two hinge members pivotally interconnectable by the pivot means for relative angular movement between an open position in which the hinge members extend substantially co-axially in end-to-end relationship and a closed position in which one hinged member is angularly displaced, with respect to the other hinge member, about the pivot means out of the end-to-end relationship, power drivable actuator locking means having a first movable portion carried on one of the hinge members and a second co-operating movable portion carried on the other of the hinge members and in engagement with said first movable portion, which power drivable actuator locking means is selectively operable to open and lock the hinge members together by pivoting one of the hinge members from the closed position about the pivot means into the substantially co-axial end-to-end relationship of the open position and then causing one of said movable portions to move in one direction relative to the other of said movable portions to lock the hinge members together, and to unlock and close the hinge members by unlocking the end-to-end hinge members by causing one of said movable portions to move in the opposite direction relative to said other movable portion and then to pivot one of the hinge members about the pivot means angularly with respect to the

other of the hinge members out of the end-to-end relationship into the closed position.

Conveniently the pivot means includes a pivot pin and the hinge members are each of substantially elongated channel form and substantially U shaped in cross-section with a base web and two spaced apart side webs, which side webs each have an apertured pivot lug at or near the outermost corner thereof remote from the base web for receiving the pivot pin, and with the hinge members being dimensioned such that the base web of one or inner hinge member is smaller in width than the base web of the other or outer hinge member at the pivot lugs with the pivot pin passing through the aligned lug apertures.

Preferably the actuator locking means includes a rotatable drive shaft rotatably carried in the outer hinge member to extend substantially transversely to the longitudinal axis of the pivot pin, a screw threaded worm, forming the first of said movable portions, carried on the drive shaft adjacent a free end thereof which is adjacent the open pivot pin end of the outer hinge member, for rotation with the drive shaft, a screw threaded worm wheel, forming the second of said movable portions, in mesh with the worm, which worm wheel is rotationally mounted on the pivot pin and fixed to the inner hinge member for rotation therewith and which worm is mounted for axial slidable movement along said drive shaft against pre-load biasing means, upon continued rotation of the drive shaft with the worm wheel in a stopped position corresponding to the open position of the hinge members, to lock the worm and worm wheel together, rotation of the drive shaft in the other direction initially displacing the worm back along the stationary worm wheel and shaft under the assistance of the pre-load biasing means to unlock the worm wheel and hinge member and then rotating the worm wheel to move the inner hinge member relative to the outer hinge member between the open and closed position.

Advantageously the assembly includes an Acme externally screw threaded nose portion fixed to and projecting from the free end of the actuator means drive shaft for rotation therewith and a complementary Acme internally screw threaded lock nut non-rotatably but axially movably mounted on the inner hinge member.

Conveniently the lock nut is axially movably mounted in one end of a sleeve to which it is connected for axial but not rotative relative movement, with the other end of the sleeve being axially slidably mounted on a spigot fixedly attached to the inner hinge member.

Preferably a first spring means is provided between the spigot and the sleeve resiliently to bias the sleeve axially away from the spigot, and wherein a second spring means is provided between the other end of the sleeve and the end face of the nut innermost in the sleeve to bias the nut axially away from the

sleeve, with deflector means being associated with the nose portion on the actuator means drive shaft to contact the leading end of the lock nut during angular pivoting movement of the inner hinge member, displace the nut rearwardly against the biasing force of the second spring means until the nose portion and nut are in axial alignment whereupon the second spring means biasing force re-urges the nut into contact with the nose portion for screw threaded engagement therewith on continued rotation of the actuator means drive shaft.

Advantageously wherein the actuator locking means includes a rotatable drive shaft rotatably carried in the outer hinge member to extend substantially transversely to the longitudinal axis of the pivot pin, a screw threaded worm fixedly carried on the drive shaft adjacent a free end thereof which is adjacent the open pivot pin end of the outer hinge member for rotation with the drive shaft, an externally and internally screw threaded worm wheel, which together with the worm forms the first of said movable portions, which worm wheel is in mesh with the worm, is mounted for rotational but no substantial axial movement in the outer hinge member about a rotational axis substantially parallel to that of the drive shaft, and a flexible rod or strip-like screw member, forming the second of said movable portions, secured at one end to the pivot pin end of the inner hinge member to project therefrom towards the pivot pin end of the outer hinge member so that the other end of the screw member projects into the worm wheel in screw threaded engagement with the internal screw thread thereof, the arrangement being such that rotation of the drive shaft, and hence of the worm and worm wheel, in one direction pulls the flexible screw member through the worm wheel into the outer hinge member to pull the inner hinge member into the open position and rotation of the drive shaft, and hence of the worm and worm wheel, in the opposite direction pushes the flexible screw member in a direction away from the worm wheel and outer hinge member to push the inner hinge member into the closed position.

For a better understanding of the present invention, and to show how the same may be carried into effect, reference will now be made, by way of example, to the accompanying drawings, in which;

Figure 1 is a diagrammatic side view of a hinge assembly according to a first embodiment of the invention shown in an open position,

Figure 2 is a plan view from above of the hinge assembly of Figure 1,

Figure 3 is a partially sectioned side view of the hinge assembly of Figures 1 and 2 shown in a fully closed position,

Figure 4 is a view similar to that of Figure 3, but showing the hinge assembly in the fully open position,

Figure 5 is a partially sectioned side view similar

to that of Figure 3 showing a hinge assembly according to a second embodiment of the invention in a closed position,

Figure 6 is a view similar to that of Figure 5 showing the hinge assembly rotated through an angle of 163° with a lock nut on one hinge member of the assembly contacting a housing collar on the other hinge member,

Figure 7 is a view, similar to that of Figure 6, but showing the hinge assembly after rotation through 180° with the lock nut on one hinge member contacting a nose portion on the other hinge member,

Figure 8 is a view of the hinge assembly of Figure 7 shown in the fully open position with the lock nut and nose portion fully engaged,

Figure 9 is a diagrammatic partially sectioned side view from above of a hinge assembly according to a third embodiment of the present invention shown in a fully closed position, and

Figure 10 is a side view of the hinge assembly of Figure 9 shown in a fully open position.

A power actuatable, openable and closable, lockable and unlockable, hinge assembly as generally indicated at 1 in the accompanying drawings is intended primarily for use to interconnect two sections of a collapsible and extensible boom or mast. However although described in the following in terms of its use with such a boom or mast it is to be understood that the hinge assembly of the invention can be used for any other purposes as desired.

The hinge assembly 1 according to a first embodiment of the invention as shown in Figures 1 to 4 has pivot means 2 and two hinge members, namely an inner hinge member 3 and an outer hinge member 4 pivotally interconnected by the pivot means 2 for relative angular movement between an open position as shown in Figures 1, 2 and 4 in which the hinge members 3 and 4 extend substantially co-axially in end-to-end relationship and a closed position shown in Figure 3, in which the inner hinge member 3 is angularly displaced, with respect to the outer hinge member 4 about the pivot means 2 out of the end-to-end relationship. As shown in Figure 3, the open position is pivoted through 180° from the closed position for the purpose of stowing in side by side relationship sections 5 and 6 of a mast or boom assembly (see Figure 1), but for alternative uses of the hinge assembly 1 the open position could be at any angular relationship to the closed position such as a 90° position.

The hinge assembly 1 of the present invention also includes a power drivable actuator locking means generally indicated at 7 having a first movable portion 8 carried on the outer hinge member 4 and a second co-operating movable portion 9 carried on the inner hinge member 3. The first and second movable portions 8 and 9 are in engagement with one another.

The actuator locking means 7 is selectively oper-

able to open and lock the hinge members 3 and 4 together by pivoting one of the hinge members, preferably the inner hinge member 3, from the closed position about the pivot means 2 into the substantially coaxial end-to-end relationship of the open position and then causing one of the movable portions 8, 9 to move in one direction relative to the other of said movable portions to lock the hinge members 3 and 4 together as will be later described in more detail in respect of Figures 3 and 4. The actuator locking means 7 is also operable selectively to unlock and close the hinge members 3 and 4 by unlocking the end to end hinge members by causing one of the movable portions 8, 9 to move in the opposite direction relative to the other movable portion and then to pivot one of the hinge members, preferably the inner hinge member 3, about the pivot means 2 angularly with respect to the outer hinge member 4 out of the end-to-end relationship into the closed portion.

The pivot means 2 includes a pivot pin 10 supported by bearings which may be plain, ball or pre-loaded angular contact bearings, in the outer hinge member 4. The hinge members 3 and 4 are each of substantially elongated channel form and substantially U shaped in cross section with a base web 3a and 4a and two spaced apart side webs 3b and 4b. The side webs 3b and 4b each have an apertured pivot lug 3c and 4c at or near the outermost corner thereof, as can be seen in Figures 1 and 2, remote from the base web 3a, 4a for receiving the pivot pin 10. The hinge members 3 and 4 are dimensioned such that the base web 3a of the inner hinge member 3 is smaller in width than the base web 4a of the outer hinge member 4 so that the inner hinge member 3 fits within the outer hinge member 4 at the pivot lugs 3c and 4c with the pivot pin 10 passing through the aligned lug apertures.

The outer hinge member 4 is fixedly attached to the hinge pin 10 to rotate therewith.

The inner hinge member 3 is rotationally supported by bearings which may be plain, ball or pre-loaded angular contact bearings, on the pivot pin 10 for pivotal rotational movement relative thereto.

As can be seen from Figures 1 to 4 the actuator locking means 7 includes a rotatable drive shaft 11 rotatably carried at bearings 12 in the outer hinge member 4 to extend substantially transversely to the longitudinal axis of the pivot pin 10. Also forming part of the means 7 is a screw threaded worm, forming the first movable portion 8, carried on the drive shaft 11 adjacent a free end thereof which is adjacent the open pivot pin end of the outer hinge member 4 for rotation with the drive shaft 11. Preferably the worm 8 is a single start worm.

Also forming part of the actuator locking means 7 is a screw threaded worm wheel, forming the second movable portion 9, which may be peripherally interrupted as at 9a. The worm wheel 9 is in mesh with the worm 8 and is rotationally mounted on the pivot pin 10

via bearings to rotate with the inner hinge member 3.

The worm 8 is mounted for axial slidable movement along the shaft 11 against pre-load biasing means such as compression spring 13 mounted on the shaft 11 between a collar 14 fixed to the shaft 11 and a shoulder 15 fixed relative to the outer hinge member 4.

The actuator locking means 7 includes a drive motor connected to the end of the drive shaft 11 remote from the free end. This drive motor preferably is an electric motor 16 with gearbox housed in and attached to the outer hinge member 4 which drives the shaft 11 by means of a motor output shaft 17 which is flexibly coupled to the adjacent end of the drive shaft 11. This form of construction allows for a degree of end float between the motor 16 and shaft 11 if necessary. Although the motor 16 has been shown as integral with the hinge assembly member 4 it is alternatively possible to provide a drive motor externally of the assembly so that a plurality of hinge assemblies can be actuated by means of a single drive motor in communication with the individual drive assemblies in a multi section boom or mast via a control drive cable passing through the sections.

The hinge assembly 1 according to the first embodiment of the invention as illustrated in Figures 1 to 4 operates in the following way. With the hinge assembly in the closed position as shown in Figure 3 rotation of the drive shaft 11 by the electric motor and gear box 16 transmits rotary motion to the worm 8 which in turn, being in mesh with the worm wheel 9, transmits rotary motion to the worm wheel 9. This causes the hinge member 3 to pivot about the pivot pin 10 into the fully closed end-to-end position of the hinge members 3 and 4 as shown in Figures 4, 1 and 2. In this position no further movement of the worm wheel 9 is possible due to end-to-end contact between the hinge members and continued rotation of the drive shaft 11 by means of the motor and gear box assembly 16 causes the worm 8 to move axially slidably along the drive shaft 11 against the pre-load biasing means formed by the spring 13 to the extreme position shown in Figure 4 in which the worm and worm wheel are locked together. Rotation of the drive shaft 11 in the opposite direction initially displaces the worm 8 back along the stationary worm wheel 9 and shaft 11 under the assistance of the pre-load bias spring 13 to unlock the worm wheel 9 and hinge members 3 and 4. This moves the worm 8 into the position shown in Figure 3 and continued rotation of the shaft 11 and worm 8 then rotates the worm wheel 9 to move the inner hinge member 3 relative to the outer hinge member 4 back into the closed position as shown in Figure 3.

In general terms the direction of movement of the hinge member 3 relative to the hinge member 4 depends on the direction of rotation of the worm 8 and on whether or not the worm thread left or right handed. As shown in the accompanying drawings, particularly

in Figures 3 and 4 thereof, the worm 8 is mounted on a sleeve 18 which is slidably movable on the drive shaft 11 under axial restraint of the compression spring 13. When the hinge assembly is to be moved from the closed position of Figure 3 to the fully open position of Figure 4 if the hinge assembly movement resistance torque is less than the pre-load effect of the spring 13 the worm 8 will not move axially. However if the resistance torque is higher then the hinge members will not be displaced until the worm 8 has been displaced axially towards the right into the position shown in Figure 4 where the pre-load in the spring 13 is equal to the hinge resistance torque.

The locking action of the worm 8 and worm wheel 9 is as follows. When the hinge assembly 1 is in the fully open position of Figures 1, 2 and 4 the hinge torque resistance is much higher in the opening direction than the pre-load on the worm 8. Thus if the worm 8 is rotated further in the opening direction, it is axially displaced towards the right into the position shown in Figure 4 and the pre-load in the spring 13 is increased. This increase in the spring pre-load causing the hinge assembly itself to be pre-loaded. The hinge pre-load is dependent on the spring pre-load, the size of the worm/worm wheel gear set and the geometry of contact points or stops 19 on the hinge members 3 and 4. Conveniently the worm/worm wheel gear set is non-back drivable so that when the worm 8 is pre-loaded against its spring 13 the pre-load in the hinge assembly 1 is maintained after the drive torque is removed from the worm 8. Thus controllable compliance is built into the worm/worm wheel gear set so that a controllable and predictable pre-load is achievable simply by tightening up the gear set. A separate pre-loading or locking mechanism is thus not necessary. The compliance within the gear set makes the hinge assembly 1 partially back drivable which is an advantage during vibration or loading. Additionally the hinge assembly 1 according to the embodiment of Figures 1 to 4 can be pre-loaded in the open condition or the closed condition.

Preferably the worm 8 and worm wheel 9 are each Acme threaded.

A hinge assembly according to the second embodiment of the invention as illustrated in Figures 5 to 8 of the present application basically is similar to that of the first embodiment of Figures 1 to 4 and like parts have been given like reference numerals and will not be further described in detail. For the sake of convenience the hinge members 3 and 4 have been shown in Figure 5 only and not in Figures 6 to 8.

However the embodiment of Figures 5 to 8 also includes an Acme externally screw threaded nose portion 20 fixed to and projecting from the free end of the drive shaft 11. Conveniently the nose portion 20 may be formed integrally with the drive shaft 11 by machining therefrom. However the shaft 11 and nose portion 20 are formed they are formed so as to rotate

together. Also provided is a complementary Acme internally screw threaded lock nut 21 non-rotatably but axially movably mounted on the inner hinge member 3. The nut 21 is axially movable along its longitudinal axis, which, in the open position of the assembly 1, is coaxial with the longitudinal axis of the drive shaft 11 and Acme nose portion 20. As can be seen from the drawings, particularly from Figure 1 thereof, the longitudinal axis 11a of the drive shaft 11 preferably is not coaxial with the longitudinal axis of the hinge member 4 but preferably is slightly spaced from the longitudinal axis of the hinge member 4 on the side thereof remote from the pivot pin 10. Similarly the longitudinal axis of the nut 21 is not coincident with the longitudinal axis of the hinge member 3 but preferably is spaced slightly therefrom on the side thereof remote from the pivot pin 10. This offset location of the axes is to improve the locking and unlocking action of the nut 21.

The nut 21 is axially movably mounted in one end of a sleeve 22 to which it is connected for axial but not rotative relative movement in any convenient manner. The other end of the sleeve 22 is axially slidably mounted on a spigot fixedly attached to the inner hinge member 3.

As can be seen from Figure 7 in particular a first spring means in the form of a disc spring 24 is provided between a shoulder portion 23a of the spigot 23 and the sleeve end face 22a. The disc spring 24 acts as a pre-load compliance spring. A second spring means in the form of a light compression spring preferably is provided within the sleeve between the facing end of the nut 21 and an internal shoulder provided on the sleeve at the end 22a thereof. This compression spring acts to bias the nut 21 axially away from the sleeve.

Deflector means, in the form of a collar 25 surrounding the nose portion 20, are provided on the hinge member 4 or on a housing 26 of the worm 8 to contact the leading end 21a of the nut 21, as illustrated in Figure 6, during angular pivoting movement of the inner hinge member 3. This contact is such that the collar 25 acts as a cam face which displaces the nut 21 rearwardly against the biasing force of the spring 24 until the nose portion 20 and nut 21 are in axial alignment whereupon the spring 24 re-urges the nut 21 into contact with the nose portion 20 so that on continued rotation of the actuator means drive shaft 11 the screw thread of the nose portion 20 engages the screw thread in the nut 21 drawing the nut 21 onto the nose portion 20.

The operation of a hinge assembly 1 according to the second embodiment will now be described with reference to Figures 5 to 8 of the accompanying drawings. With the two hinge members 3 and 4 in the closed position as shown in Figure 5 switching on the drive motor 16 rotates the worm wheel 9 through 163° via the worm 8, so that the hinge member 3 moves into

the position shown in Figure 6. After rotation of about 163° the leading end of 21a of the nut 21 contacts the collar 25 as shown in Figure 6 and the nut 21 begins to move axially rearwardly towards the spigot shoulder 23a against the action of the return spring with disc spring 24 being lightly compressed between the sleeve 22 and spigot shoulder 23a.

The hinge member 3 continues to open as shown in Figure 7 and the nut 21 is further displaced axially into the sleeve 22 against the spring. At full rotation through 180° as shown in Figure 8 the screw thread on the nose portion 20 starts to engage the internal screw thread on the nut 21 and with the worm wheel 9 at the end of its permitted travel the worm 8 runs along the worm wheel 9 towards the right said side of Figure 8.

The drive motor 16 continues to run and the worm 8 and nose portion 20 continue to rotate so that the nut 21 is drawn onto the nose portion 20 with the assistance of the compression spring. By virtue of the attachment of the nut 21 to the spigot 23, the spigot 23 is pulled axially forward with the nut 21 until the disc spring 23 is clamped tight between the spigot shoulder 23a and the sleeve end face 22a as shown in Figure 8. This provides the desired pre-load which can be used to initiate a switch off of the drive motor 16, preferably by means of a microswitch on the spring 23. The degree of pre-load can be varied by appropriate choice of the configuration and/or number of elements in the disc spring 23. Alternatively, and not shown, the drive motor 16 could be a stepper motor programmed to rotate the nut 21 by a predetermined number of steps to achieve the correct degree of pre-load on the spring 23. Thus Figure 8 represents the hinge assembly 1 in the fully locked open position.

Reclosure is effected by operating the assembly in the reverse direction. Initial rotation of the motor 16 drives the worm 8 along the stationary worm wheel 9 so freeing, i.e. unscrewing, the nose portion 20 from the lock nut 21 and returning the assembly to the Figure 7 position. Continued operation of the motor 16 rotates the worm wheel 9 and displaces the hinge member 3 through the Figure 6 position back into the fully closed position of Figure 5.

Complementary finger and recessed means preferably are provided on the two hinge members 3 and 4 with the finger means projecting substantially parallel to the longitudinal axes of the two hinge members. The finger means may be provided on one hinge member and the recess means on the other hinge member or some of the finger means may be provided on one hinge member and some on the other hinge member with the recess means being distributed accordingly on the two hinge members. The purpose of the finger and recess means is that the finger means engage in the appropriate complementary recesses in the open position of the hinge assembly 1 to improve the rigidity and transverse load carrying

capability of the assembly in the open position.

As shown in Figure 1 the complementary finger and recess means conveniently take the form of a cylindrical, or tapered, finger 27 mounted on the side web 4b of the outer hinge member 4 to project proud of the end thereof towards the inner hinge member 3, and a recessed member 28 having a complementary shaped recess for receiving the leading end of the finger 27. The member 28 is mounted on the inner hinge member side web 3b with the mouth of the recess opening towards the outer hinge member 4.

The third embodiment of the hinge assembly according to the present invention is shown in Figures 9 and 10 in which the actuator locking means includes the drive shaft 11 and drive motor 16 carried in the outer hinge member 4 to extend substantially transversely to the longitudinal axis of the pivot pin 10. The worm 8 is fixedly carried on the drive shaft 11 adjacent to the free end thereof which is adjacent to the open pivot pin end of the outer hinge member 4 for rotation with the drive shaft 11. However in this embodiment the worm wheel is an externally and internally screw threaded worm wheel 29 which together with the worm 8 forms the first of the movable portions. The worm wheel 29 is in mesh with the worm 8 and is mounted for rotational, but no substantial axial, movement in the outer hinge member 4 about a rotational axis substantially parallel to that of the drive shaft 11.

The second movable portion is provided in the form of a flexible rod or strip like screw member 20 made of any convenient material, preferably plastics. This member 30 may be of strip like form with the screw thread provided on the two longitudinal edges thereof. This member 30 is secured at one end 30a to the pivot pin end of the inner hinge member 3 either fixedly as illustrated in Figures 9 and 10 or pivotally. The flexible screw member 30 projects from the inner hinge member 3 towards the pivot pin end of the outer hinge member 4 so that the other end 30b projects into the worm wheel 29 in screw threaded engagement with the internal screw thread thereof. A spring loaded support arm 31 is provided which is pivotally mounted at 32 on the outer hinge member 4 to provide support for the flexible screw member 30 such as to prevent it from bending through too similar a radius.

Thus with the hinge assembly in the fully closed position as shown in Figure 9 rotation of the drive shaft 11 and hence of the worm 8 and worm wheel 29 in one direction pulls the flexible screw member 30 through the worm wheel 29 into the outer hinge member 4 to pull the inner hinge member 3 into the open position as shown in Figure 10 where it is held in position by the pre-load between the motor 16, worm 8, worm wheel 29 and screw thread on the screw member 30. In the fully open position of Figure 10 the flexible screw member 30 has moved into a substantially linear condition from the substantially arcuate condition shown in Figure 9. In the position of Figure 10 the

spring loaded support arm 31 has folded back so that it lies within the inner hinge member 3. Rotation of the drive shaft 11, and hence of the worm 8 and worm wheel 29 in the opposite direction pushes the flexible screw member 30 in a direction away from the worm wheel 29 and outer hinge member 4 to push the inner hinge member back into the closed position as shown in Figure 9. Preferably the worm 8 and worm wheel 29 are each Acme threaded and the drive motor 16 is an electric motor.

### Claims

1. A power actuable openable and closable, lockable and unlockable, hinge assembly, characterised by having pivot means (2), two hinge members (3, 4) pivotally interconnectable by the pivot means (2) for relative angular movement between an open position in which the hinge members (3, 4) extend substantially co-axially in end-to-end relationship and a closed position in which one hinged member (3) is angularly displaced, with respect to the other hinge member (4), about the pivot means (2) out of the end-to-end relationship, power drivable actuator locking means (7) having a first movable portion (8, 29) carried on one of the hinge members (4) and a second co-operating movable portion (9, 30) carried on the other of the hinge members (3) and in engagement with said first movable portion (8, 29) which power drivable actuator locking means (7) is selectively operable to open and lock the hinge members (3, 4) together by pivoting one of the hinge members (3) from the closed position about the pivot means (2) into the substantially co-axial end-to-end relationship of the open position and then causing one of said movable portions (8, 29, 9, 30) to move in one direction relative to the other of said movable portions to lock the hinge members (3, 4) together, and to unlock and close the hinge members (3, 4) by unlocking the end-to-end hinge members (3, 4) by causing one of said movable portions (8, 29, 9, 30) to move in the opposite direction relative to said other movable portion and then to pivot one of the hinge members (3) about the pivot means (2) angularly with respect to the other of the hinge members (4) out of the end-to-end relationship into the closed position.
2. An assembly according to claim 1 wherein, the pivot means (2) includes a pivot pin (10) and wherein the hinge members (3, 4) are each of substantially elongated channel form and substantially U shaped in cross-section with a base web (3a, 4a) and two spaced apart side webs (3b, 4b), which side webs (3b, 4b) each

have an apertured pivot lug (3c, 4c) at or near the outermost corner thereof remote from the base web (3a, 4a) for receiving the pivot pin (10), and with the hinge members (3, 4) being dimensioned such that the base web (3a) of one or the inner hinge member (3) is smaller in width than the base web (4a) of the other or outer hinge member (4) so that the inner hinge member (3) fits within the outer hinge member (4) at the pivot lugs (3c, 4c) with the pivot pin (10) passing through the aligned lug apertures.

3. An assembly according to claim 2, wherein the outer hinge member (4) is fixedly attached to the hinge pin (10) to rotate therewith.
4. An assembly according to claim 2 or claim 3, wherein the inner hinge member (3) is rotationally supported by bearings on the pivot pin (10) for pivotal rotational movement relative thereto.
5. An assembly according to any one of claims 2 to 4, wherein the actuator locking means (7) includes a rotatable drive shaft (11) rotatably secured in the outer hinge member (4) to extend substantially transversely to the longitudinal axis of the pivot pin (10), a screw threaded worm, forming the first (8) of said movable portions, carried on the drive shaft (11) adjacent a free end thereof which is adjacent the open pivot pin end of the outer hinge member (4), for rotation with the drive shaft (11), a screw threaded worm wheel, forming the second (9) of said movable portions, in mesh with the worm, which worm wheel (9) is rotationally mounted on the pivot pin (10) and fixed to the inner hinge member (3) for rotation therewith, and which worm (8) is mounted for axial slidable movement along said drive shaft (11) against pre-load biasing means (13), upon continued rotation of the drive shaft (11) with the worm wheel (9) in a stopped position corresponding to the open position of the hinge members (3, 4), to lock the worm (8) and worm wheel (9) together, and thereby the open position, end-to-end hinge members (3, 4) together, rotation of the drive shaft (11) in the other direction initially displacing the worm (8) back along the stationary worm wheel (9) and shaft (11) under the assistance of the pre-load biasing means (13) to unlock the worm wheel (9) and hinge members (3, 4) and then rotating the worm wheel (9) to move the inner hinge member (3) relative to the outer hinge member (4) between the open and closed position.
6. An assembly according to claim 5, wherein the pre-load biasing means is a compression spring (13) mounted on the drive shaft (11) between a

- collar (14) fixed to the shaft (11) and a shoulder (15) fixed relative to the outer hinge member (4).
7. An assembly according to claim 5 or claim 6, wherein the worm (8) and worm wheel (9) are each Acme threaded.
8. An assembly according to any one of claims 5 to 7, wherein the actuator means (7) includes a drive motor connected to the end of the drive shaft (11) remote from the free end.
9. An assembly according to claim 8, wherein the drive motor is an electric motor (16) housed in and attached to the outer hinge member (4).
10. An assembly according to any one of claims 5 to 9, including an Acme externally screw threaded nose portion (20) fixed to and projecting from the free end of the actuator means drive shaft (11) for rotation therewith and a complementary Acme internally screw threaded lock nut (21) non-rotatably but axially movably mounted on the inner hinge member (3).
11. An assembly according to claim 10, wherein the lock nut (21) is axially movable along its longitudinal axis, which, in the open position of the assembly (1), is coaxial with the longitudinal axis of the drive shaft (11) and Acme nose portion (20).
12. An assembly according to claim 11, wherein the lock nut (21) is axially movably mounted in one end of a sleeve (22) to which it is connected for axial but not rotative relative movement with the other end of the sleeve (22) being axially slidably mounted on a spigot fixedly attached to like inner hinge member (3).
13. An assembly according to claim 12, wherein a first spring means (24) is provided between the spigot (23) and the sleeve (22) resiliently to bias the sleeve (22) axially away from the spigot (23), and wherein a second spring means is provided between the other end of the sleeve (22) and the end face of the nut (21) innermost in the sleeve (22) to bias the nut (21) axially away from the sleeve (22) with deflector means (25) being associated with the nose portion (20) on the actuator means drive shaft (11) to contact the leading end (21a) of the lock nut (21) during angular pivoting movement of the inner hinge member (3), displace the nut (21) rearwardly against the biasing force of the second spring means until the nose portion (20) and nut (21) are in axial alignment whereupon the second spring means biasing force re-urges the nut (21) into contact with the nose portion (20) for screw threaded engagement therewith on continued rotation of the actuator means drive shaft (11).
14. An assembly according to any one of claims 2 to 4, wherein the actuator locking means (7) includes a rotatable drive shaft (11) rotatably carried in the outer hinge member (4) to extend substantially transversely to the longitudinal axis of the pivot pin (10), a screw threaded worm (8) fixedly carried on the drive shaft (11) adjacent a free end thereof which is adjacent the open pivot pin end of the outer hinge member (4) for rotation with the drive shaft (11), an externally and internally screw threaded worm wheel (29), which together with the worm (8) forms the first of said movable portions, which worm wheel (29) is in mesh with the worm (8), is mounted for rotational but no substantial movement in the outer hinge member (4) about a rotational axis substantially parallel to that of the drive shaft (11), and a flexible rod or strip-like screw member (30), forming the second of said movable portions, secured at one end (30a) to the pivot pin end of the inner hinge member (3) to project therefrom towards the pivot pin end of the outer hinge member so that the other end (30b) of the screw member (30) projects into the worm wheel (29) in screw threaded engagement with the internal screw thread thereof, the arrangement being such that rotation of the drive shaft, and hence of the worm (8) and worm wheel (29), in one direction pulls the flexible screw member (30) through the worm wheel (29) into the outer hinge member (4) to pull the inner hinge member (3) into the open position and rotation of the drive shaft (11), and hence of the worm (8) and worm wheel (29), in the opposite direction pushes the flexible screw member (30) in a direction away from the worm wheel (29) and outer hinge member (4) to push the inner hinge member (3) into the closed position.
15. An assembly according to claim 14, wherein the worm (8) and worm wheel (29) are each Acme threaded and the drive motor (16) is an electric motor housed in and attached to the outer hinge member (4).
16. An assembly according to any one of claims 1 to 15, including complementary finger and recess means (27, 28) provided on the two hinge members (3, 4) for engagement in the open position of the assembly (1) for improving the rigidity and transverse load carrying capability of the assembly (1) in the open position.
17. A collapsible boom or mast having a plurality of elongated sections (5, 6) and at least one hinge

assembly (1) according to any one of claim 1 to 16, with the or each assembly (1) interconnecting two adjoining sections (5, 6).

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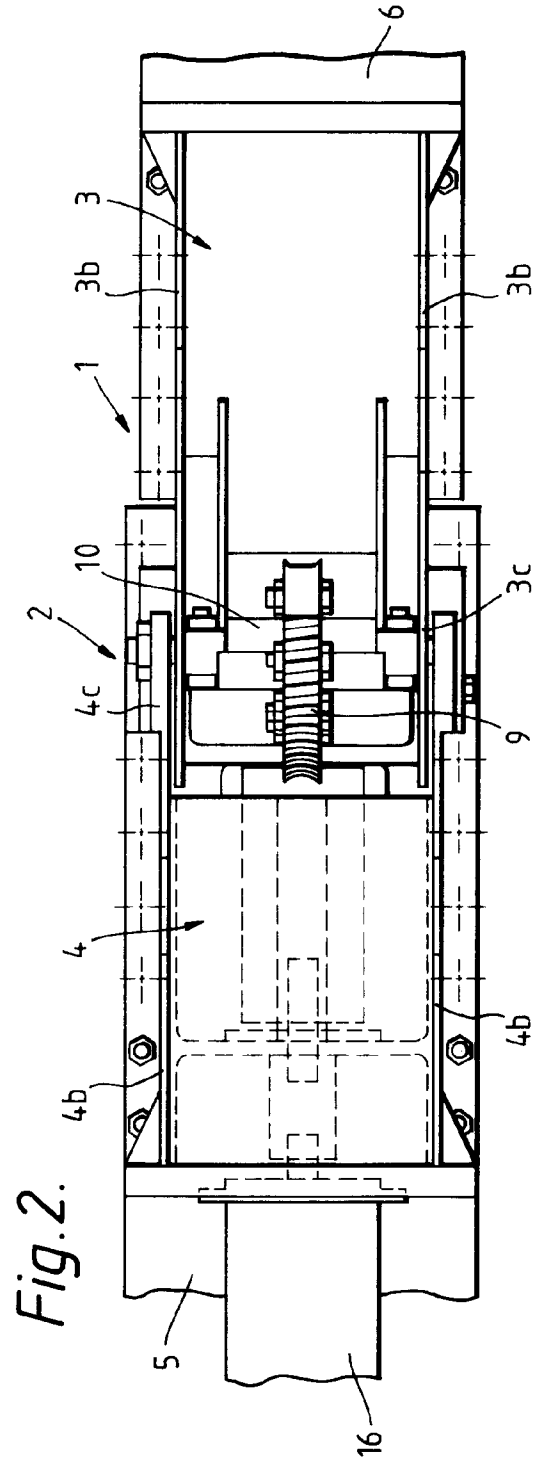
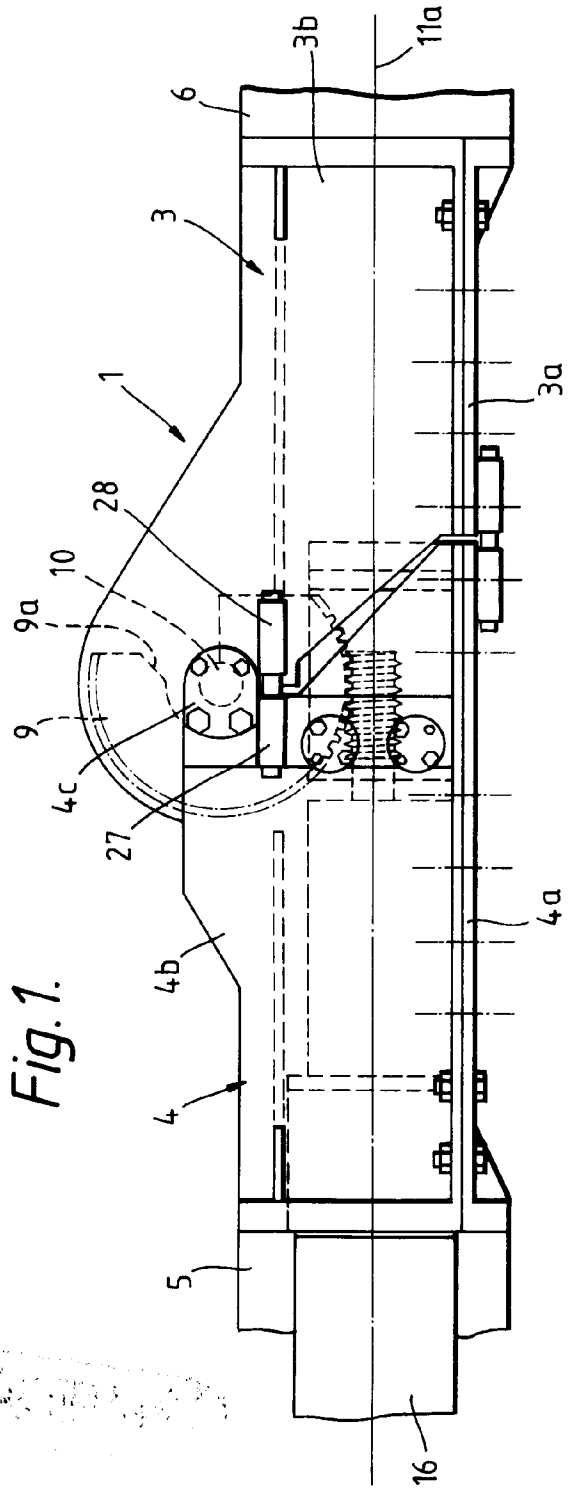


Fig. 3.

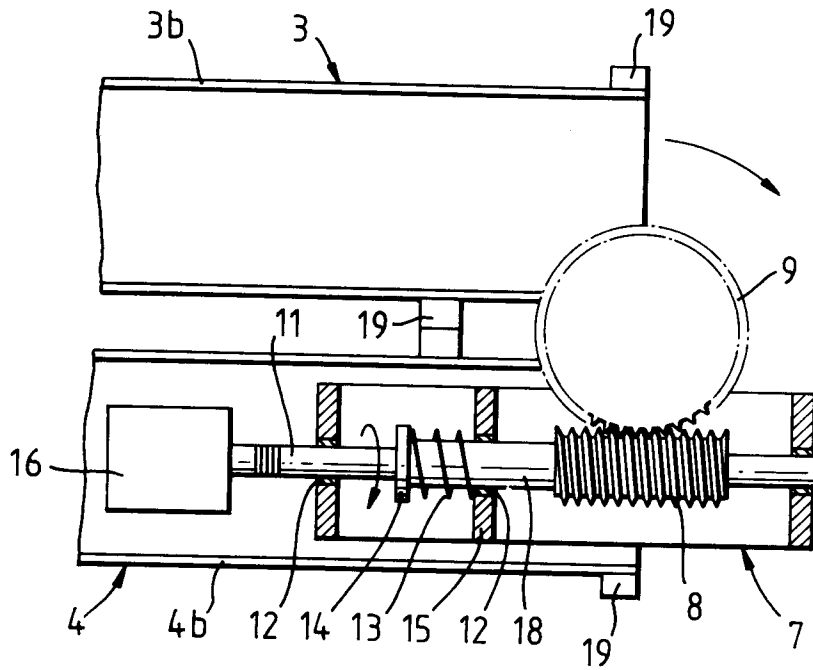


Fig. 4.

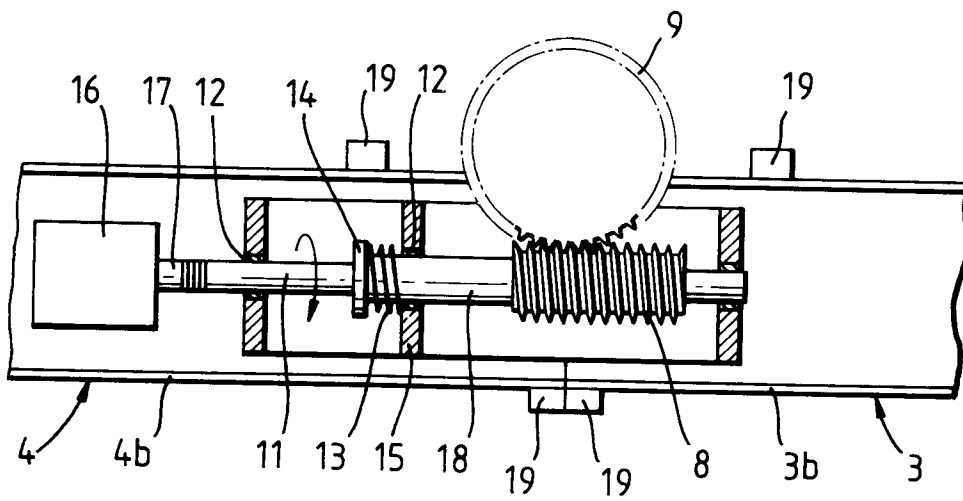


Fig. 5.

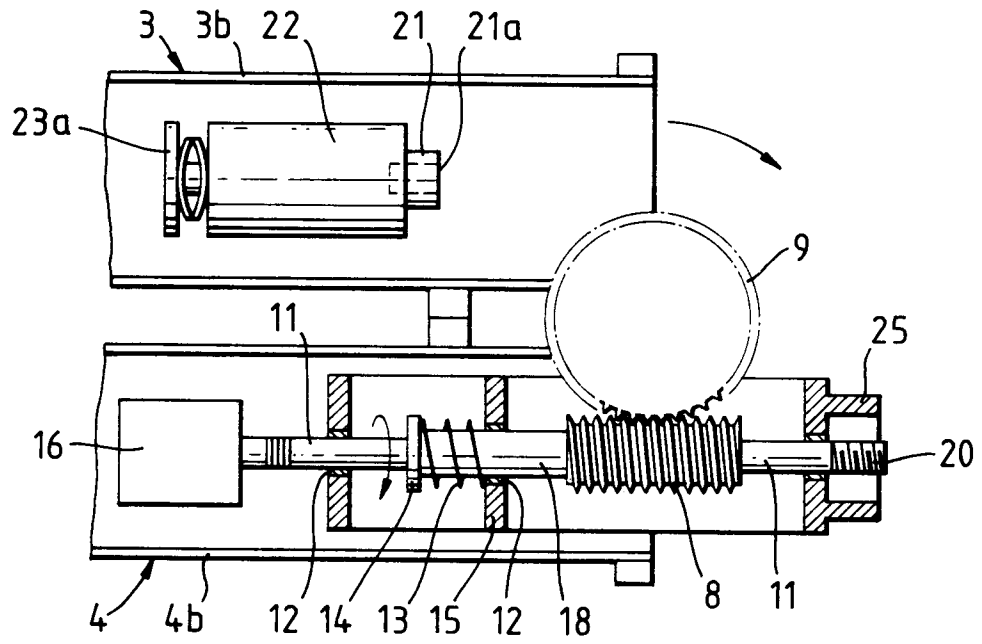


Fig. 6.

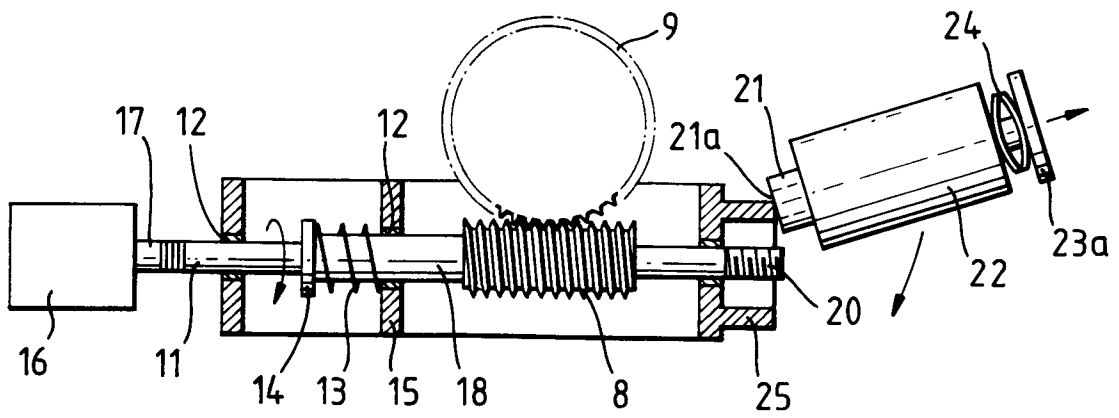


Fig. 7.

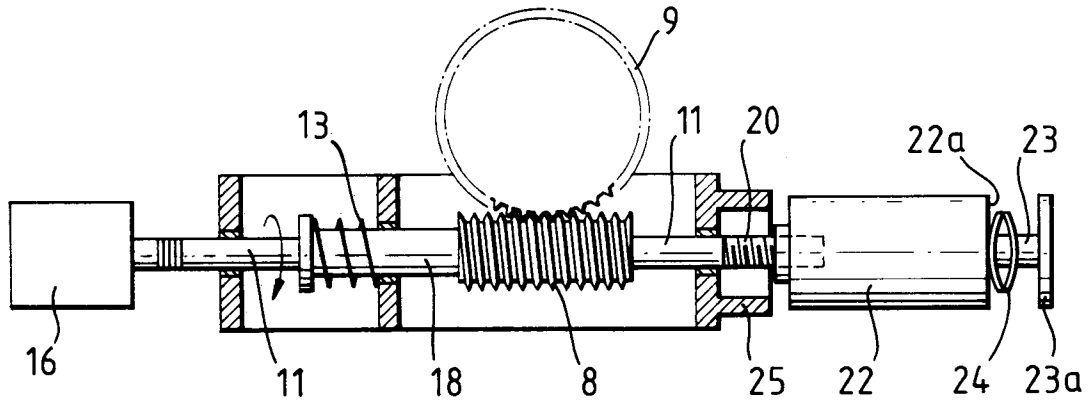


Fig. 8.

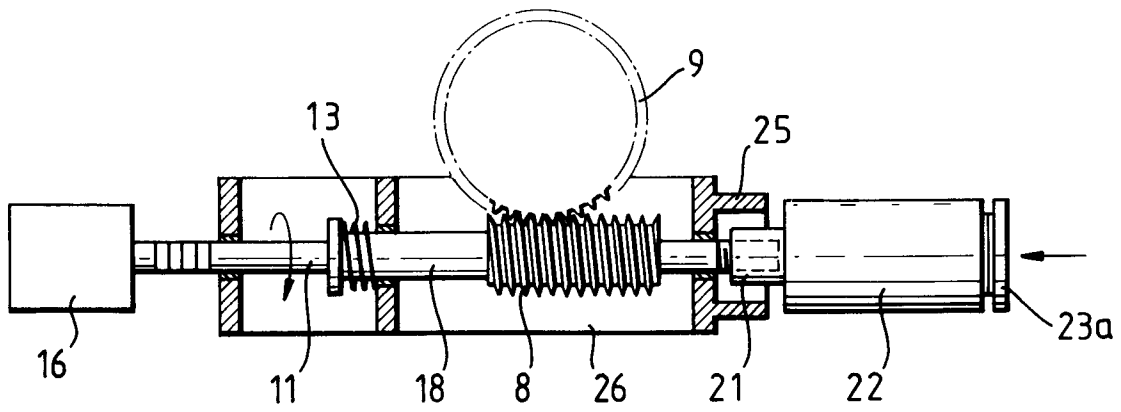


Fig. 9.

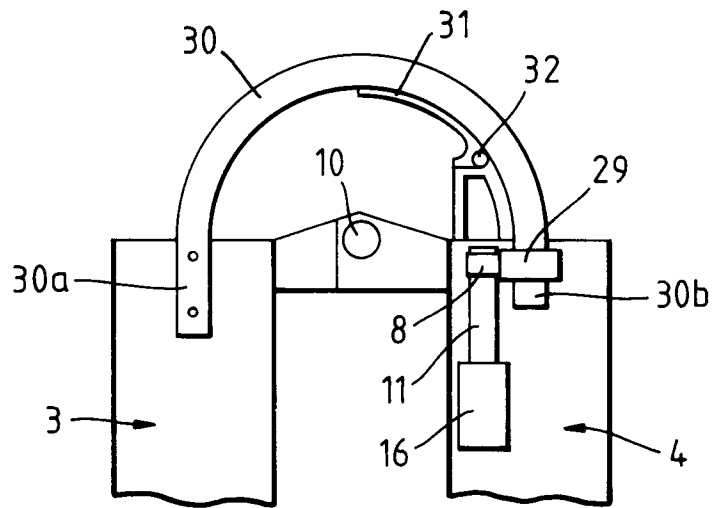
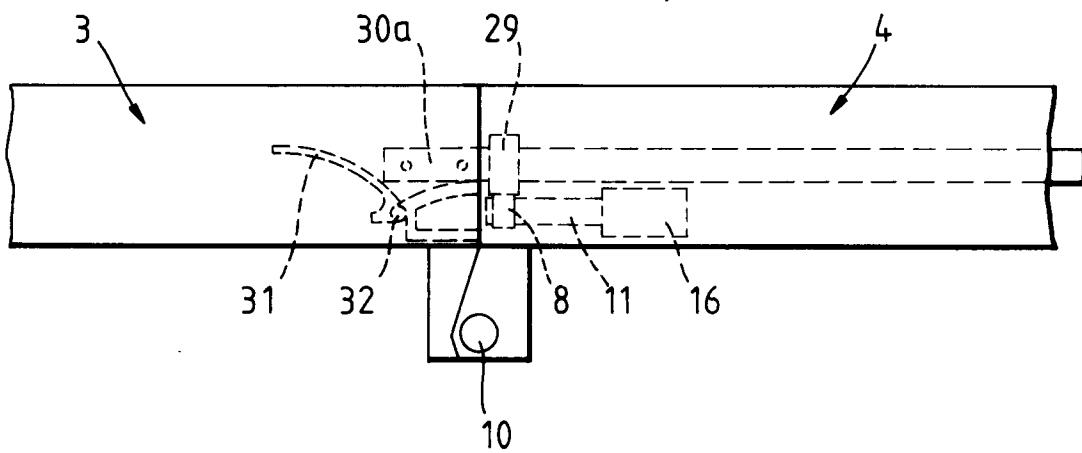


Fig. 10.





European Patent Office

EUROPEAN SEARCH REPORT

Application Number

EP 92 30 2263

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl.5)
Y	US-A-3 296 757 (GOODMAN) * column 3, line 35 - line 69; figures 1,6-8 * ---	1,17	E04H12/18 H01Q1/12 E05F15/12
Y	DE-C-653 755 (FLYNN)	1,17	
A	* page 2, line 9 - line 64; figures 1-5 * ---	5,6	
P,A	EP-A-0 430 410 (BRITISH AEROSPACE)  * the whole document * ---	1-13,16, 17	
A	AU-B-603 797 (FLETSCHER) * page 10, line 11 - page 11, line 15; figures 1-3 * ---	2-4	
A	EP-A-0 169 296 (POULIN)  * page 1, line 1 - line 14 * * page 4, line 18 - page 6, line 25; figures 1,2 * ---	1,5,6,8, 9	
A	US-A-3 295 699 (BAUERNSCHUB)  * column 3, line 3 - line 33 * * column 5, line 57 - line 59; figures 1-10 * ---	2-4,14, 16,17	TECHNICAL FIELDS SEARCHED (Int. Cl.5)
A	DE-A-3 731 931 (PFLEIDERER) * column 4, line 1 - line 62; figures 3,4 * -----	14	E04H H01Q E05F E04C E06C
The present search report has been drawn up for all claims			
Place of search THE HAGUE		Date of completion of the search 11 JUNE 1992	Examiner VAN KESSEL J.
<b>CATEGORY OF CITED DOCUMENTS</b> X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document		T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons ..... & : member of the same patent family, corresponding document	

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