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(54) Title: A GYRATORY CRUSHER SHELL LIFTING TOOL

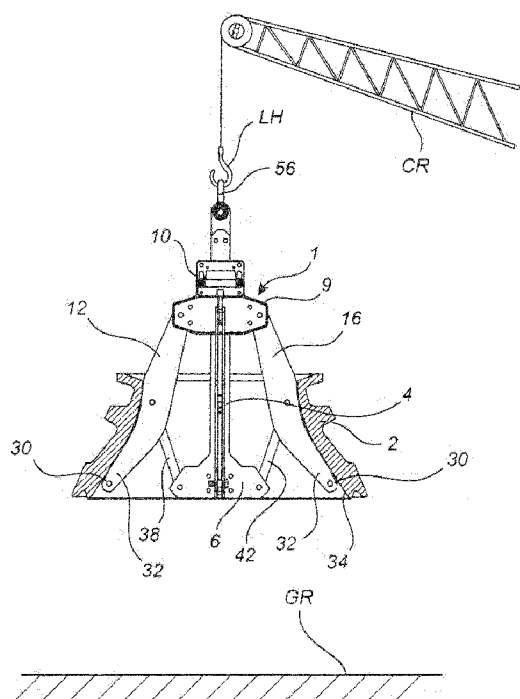


Fig. 5b

(57) Abstract: A gyratory crusher shell lifting tool (1) adapted for lifting a gyratory crusher shell (2) comprises: a generally vertical central bar (4), a lower hub (6) arranged at a lower end (8) of the central bar (4), an upper hub (9) arranged at the central bar (4) above the lower hub (6), at least one locking mechanism (10) arranged on at least one of the upper and lower hubs (9, 6) to make that hub (9) releasably fixed to the central bar (4), a first lifting leg (12) and a second lifting leg (16) provided with a respective outwardly directed lifting portion (30) adapted to come into contact with an inner periphery (34) of the crushing shell (2), wherein the respective outwardly directed lifting portion (30) is moved away from the central bar (4) when one hub (9) is moved in the direction of the other hub (6).



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A GYRATORY CRUSHER SHELL LIFTING TOOL

Technical Field of the Invention

The present invention relates to a gyratory crusher shell lifting tool
15 adapted for lifting a gyratory crusher shell.

Still further, the invention relates to a method of lifting a gyratory
crusher shell.

Background of the Invention

20 A gyratory crusher may be utilized for efficient crushing of material,
such as stone, ore, etc. into smaller sizes. The gyratory crusher is provided
with an inner crusher shell and an outer crusher shell forming between them a
crushing chamber. The outer crusher shell is mounted in a frame of the
crusher. The inner crusher shell is arranged on a crushing head, which is
25 made to perform a gyratory movement to effect crushing of material in the
crushing chamber.

WO 2014/019762 A1 discloses a gyratory crusher outer crushing shell
for being mounted in a frame of a gyratory crusher. The crushing shell is a
heavy wear part, which could often have a weight of half a metric ton and
30 more. When lifting the crushing shell, for example when lifting the crushing
shell into its position in the crusher frame, it is common practice to weld a
plurality of lifting eyes to the upper edge of the crushing shell and then use a
hoisting crane for lifting the crushing shell by those lifting eyes. When the
crushing shell is in place and fixed to the crusher frame, the lifting eyes are
35 cut off from the crushing shell by means of a cutting torch.

Summary of the Invention

An object of the present invention is to provide a gyratory crusher shell lifting tool which is more efficient than the lifting eyes used in the prior art.

- 5 This object is achieved by means of a gyratory crusher shell lifting tool adapted for lifting a gyratory crusher shell, the shell lifting tool comprising:
- a generally vertical central bar,
- a lower hub arranged at a lower end of the central bar,
- an upper hub arranged at the central bar above the lower hub,
- 10 at least one locking mechanism arranged on at least one of the upper and lower hubs to make the at least one of the upper and lower hubs releasably fixed to the central bar,
- at least a first lifting leg and a second lifting leg that are provided with a respective outwardly directed lifting portion adapted to come into contact with
- 15 an inner periphery of a gyratory crusher shell, wherein each of the first and second lifting legs are mounted to the upper hub and being journalled therein to be turnable in a vertical direction relative to the upper hub, and wherein each lifting leg is journalled to a respective link extending to the lower hub, said respective link being adapted to move the respective outwardly directed
- 20 lifting portion of the respective leg away from the central bar when at least one of the lower and upper hubs is moved in the direction of the other one of the lower and upper hubs.

- An advantage of this gyratory crusher shell lifting tool is that it can be mounted easily and quickly to the crusher shell, with very limited efforts and
- 25 without health risks to the operating personnel. Thereby, a gyratory crusher shell can be lifted and moved from one place to another efficiently and with low risks to personnel and materials.

- According to one embodiment the at least a first lifting leg and a second lifting leg are evenly distributed around the periphery of the central
- 30 bar. An advantage of this embodiment is that a crushing shell can be lifted in a safe manner, without tipping to one side during the lifting.

According to one embodiment the shell lifting tool comprises at least three lifting legs. An advantage of this embodiment is that the crusher shell can be lifted in an even safer and more stable manner.

According to one embodiment the shell lifting tool comprises 3 - 8 lifting
5 legs. This number of lifting legs has proven to provide for efficient lifting of the crusher shell without adding undue cost and complexity to the shell lifting tool. More preferably the shell lifting tool comprises 4 – 5 lifting legs. This number of lifting legs has been found to provide for excellent stability and safety when lifting a crusher shell, and also a low cost for manufacturing the shell lifting
10 tool.

According to one embodiment the respective outwardly directed lifting portions of the lifting legs are arranged at respective lower ends of the respective legs. This provides for stable and safe lifting of a gyratory crusher shell, since it is lifted at its lower portion, where the gyratory crusher shell
15 normally has its widest inner width.

According to one embodiment each lifting leg is journalled to the respective link extending to the lower hub at a respective central portion of the respective lifting leg. An advantage of this embodiment is that the lifting legs can be turned in a vertical plane within a large angular span, to thereby
20 make it possible to adjust the shell lifting tool to shells of largely varying sizes. Preferably, the central portion of the respective lifting leg is positioned within a central location CL of the full length FL of the lifting leg, wherein the central location CL starts at a distance from the upper end of the leg corresponding to about 5% of the full length FL of the lifting leg, and ends at a distance from
25 the upper end of the leg corresponding to about 75% of the full length FL of the lifting leg. An advantage of this embodiment is that a suitable combination of high movability of the legs and good physical strength of the legs is achieved.

According to one embodiment the upper hub is provided with the
30 locking mechanism and is releasably fixed to the vertical central bar, and wherein the lower hub is fixedly mounted to a lower end of the vertical central bar. An advantage of this embodiment is that it becomes easy and efficient to handle the lifting tool and to adjust the legs to a suitable position, since the

locking mechanism is arranged at the upper hub, which is normally easily accessible. Preferably, the locking mechanism is integrated into the upper hub. This provides for an efficient and compact arrangement.

According to one embodiment the locking mechanism comprises at least one locking member which is adapted to co-operate with the vertical central bar in a tooth-and-groove arrangement in a locked state of the locking mechanism. An advantage of this embodiment is that a tooth-and-groove arrangement provides for a reliable, strong and thereby safe locking mechanism.

According to one embodiment a control handle of the locking mechanism is adapted for switching the position of at least one locking member between a locked state in which the locking member co-operates with the vertical central bar and a released state in which the locking member and the vertical central bar are released from each other. An advantage of this embodiment is that controlling the locking mechanism and its current state becomes easy and safe.

According to one embodiment the locking mechanism is provided with a fail-safe device, such as a spring device, which is adapted to bring the locking mechanism to a released state unless a securing mechanism of the locking mechanism has been properly installed to hold the locking mechanism in a locked state. An advantage of this embodiment is that accidents are prevented, since the locking mechanism is either safely held in its locked state, and is, if not safely locked, automatically returned to the released state.

According to one embodiment the vertical central bar is provided with a lifting device, such as a lifting eye, arranged in an upper end thereof. An advantage of this embodiment is that standard lifts, such as cranes with lifting hooks, can be used for lifting the lifting tool and the crusher shell.

Furthermore, the vertical central bar is normally a mechanically strong device that can support the load of the crusher shell.

A further object of the present invention is to provide a method of lifting a gyratory crusher shell which is more efficient than the methods of the prior art.

This object is achieved by means of a method comprising

placing a gyratory crusher shell lifting tool inside the gyratory crusher shell, the shell lifting tool comprising:

- a generally vertical central bar,
- a lower hub arranged at a lower end of the central bar,
- 5 an upper hub arranged at the central bar above the lower hub, at least a first lifting leg and a second lifting leg that are provided with a respective outwardly directed lifting portion, wherein each of the first and second lifting legs are mounted to the upper hub and being journalled therein to be turnable in a vertical direction relative to the upper hub, and wherein
- 10 each lifting leg is journalled to a respective link extending to the lower hub, the method further comprising:
 - moving at least one of the lower and upper hubs in the direction of the other
 - one of the lower and upper hubs to make the outwardly directed lifting portions of the legs come into contact with an inner periphery of the gyratory
 - 15 crusher shell,
 - locking at least that hub that has been moved to the vertical central bar, such that both hubs become fixed to the vertical central bar, and
 - lifting the shell lifting tool and thereby lifting the gyratory crusher shell together with it.
- 20 An advantage of this method is that a gyratory crusher shell can be lifted very quickly and in a very safe manner.

According to one embodiment said step of moving at least one of the lower and upper hubs in the direction of the other one of the lower and upper hubs includes moving the upper hub downwardly in the direction of the lower

25 hub, and wherein said step of locking that hub that has been moved to the vertical central bar includes locking the upper hub to the central bar. An advantage of this embodiment is that locking the hub becomes easy, thereby making the handling of the lifting tool more efficient.

According to one embodiment the method further comprises lifting the

30 shell lifting tool by connecting a lift to a lifting device arranged at an upper end of the vertical central bar. An advantage of this embodiment is that the shell lifting tool can be lifted in a safe and efficient manner.

Further objects and features of the present invention will be apparent from the following detailed description and claims.

Brief description of the Drawings

5 The invention is described in more detail below with reference to the appended drawings in which:

Fig. 1 is a schematic three-dimensional view illustrating a gyratory crusher shell lifting tool placed inside of an outer crushing shell.

Fig. 2 is a schematic side view of a locking mechanism of the shell
10 lifting tool of Fig. 1, wherein the locking mechanism is in a locked state.

Fig. 3 is a schematic side view of the locking mechanism of Fig. 2 wherein the locking mechanism is in a released state.

Fig. 4 is a schematic side view of the shell lifting tool in a passive mode.

15 Fig. 5a is a schematic side view of the shell lifting tool in an active mode.

Fig. 5b is a schematic side view of the shell lifting tool in the active mode and when being used for lifting an outer crushing shell.

20 Fig. 6 is a schematic side view of a shell lifting tool being used for lifting a large outer crushing shell.

Description of Preferred Embodiments

Fig. 1 illustrates a gyratory crusher shell lifting tool 1 arranged inside a circular gyratory crusher outer crushing shell 2 for making it possible to lift the
25 latter. In Fig. 1 the shell 2 is shown in cross-section to better illustrate the details of the shell lifting tool 1.

The gyratory crusher shell lifting tool 1 comprises a generally vertical central bar 4, a lower hub 6 fixedly mounted at a lower end 8 of the central bar 4, and an upper hub 9 arranged on the vertical central bar 4 above the
30 lower hub 6 and comprising a locking mechanism 10. By means of the locking mechanism 10 the upper hub 9 is releasably fixed to the central bar 4 and can be moved to various positions along the central bar 4, above the lower hub 6.

First, second, third and fourth lifting legs 12, 14, 16, 18 are, at respective upper ends 20 thereof, mounted to the upper hub 9. The legs 12, 14, 16, 18 are, at their respective upper ends 20, journalled in respective upper hub bracket and bearing devices 22, 24, 26, 28 of the upper hub 9, meaning that the legs 12, 14, 16, 18 may be turned in a vertical direction relative to the upper hub 9. The four lifting legs 12, 14, 16, 18 are evenly distributed around the periphery of the central bar 4, meaning that when viewed from above, since there are four legs, the legs 12, 14, 16, 18 are at a 90° angle to each other.

Each leg 12, 14, 16, 18 is provided with a respective outwardly directed lifting portion 30 arranged at a respective lower end 32, opposite to the respective upper end 20, of the respective leg 12, 14, 16, 18. The respective lifting portion 30 is adapted to come into contact with an inner periphery 34 of the gyratory crusher outer crushing shell 2 when lifting the latter.

Each leg 12, 14, 16, 18 is, preferably at a respective central portion 36 thereof, journalled to a respective link 38, 40, 42, 44 extending from the respective central portion 36 to the lower hub 6. By "central portion 36" is meant a portion that is positioned within a central location CL of the full length FL of the respective lifting leg 12, 14, 16, 18. The central location CL preferably starts at a distance from the upper end 20 corresponding to about 5% of the full length FL of the lifting leg 12, 14, 16, 18, and ends at a distance from the upper end 20 corresponding to about 75% of the full length FL of the lifting leg 12, 14, 16, 18. In the embodiment of Fig. 1 the central portion 36 is located in the absolute middle of the lifting leg, i.e. exactly in the middle between the upper end 20 and the lower end 32, meaning a location of the central portion 36 corresponding to 50% of the full length FL of the respective lifting leg 12, 14, 16, 18. At the lower hub 6, the respective link 38, 40, 42, 44 is journalled in respective lower hub bracket and bearing devices 46, 48, 50, 52 of the lower hub 6.

The respective link 38, 40, 42, 44 is adapted for moving the respective outwardly directed lifting portion 30 of the respective leg 12, 14, 16, 18 away from the central bar 4 when the upper hub 9 is moved downwards in the direction of the lower hub 6. Such movement downwards of the upper hub 9

is performed when the lifting tool 1 is adjusted to the crushing shell 2, by the lifting portions 30 being brought into contact with the inner periphery 34 of the outer crushing shell 2, just prior to lifting the crushing shell 2.

Similarly, the respective link 38, 40, 42, 44 is adapted for moving the
5 respective outwardly directed lifting portion 30 of the respective leg 12, 14, 16, 18 toward the central bar 4 when the upper hub 9 is moved vertically upwards and away from the lower hub 6. Such movement upwards of the upper hub 9 is performed when the lifting tool 1 is to be released from the outer crushing shell 2, by the lifting portions 30 being released from contact
10 with the inner periphery 34 of the crushing shell 2, after having lifted the crushing shell 2.

The vertical central bar 4 comprises, at an upper end 54 thereof, a lifting device, which in this embodiment has the form of a lifting eye 56. A crane or similar device can be connected to the lifting eye 56 to lift the
15 gyratory crusher shell lifting tool 1 and the gyratory crusher outer crushing shell 2.

Fig. 2 illustrates the vertical central bar 4 and the upper hub 9 with its locking mechanism 10 in more detail. The locking mechanism 10 is integrated into the upper hub 9 which provides for an efficient design with few parts. In
20 the perspective illustrated in Fig. 2 a cover plate and the bracket and bearing device 24 are not illustrated to show the relevant internal details of the locking mechanism 10 more clearly.

The purpose of the locking mechanism 10 is to enable adjustment of the vertical position of the upper hub 9 along the vertical central bar 4 and to
25 thereby adjust the vertical turning position of the legs 12, 14, 16, 18 between a passive mode, and a lifting, or active, mode.

In the passive mode the legs 12, 14, 16, 18 are close to parallel to the vertical central bar 4, such that the gyratory crusher shell lifting tool 1 can be inserted into, or removed from, the interior of the gyratory crusher outer
30 crushing shell 2, as will be described hereinafter with reference to Fig. 4. In this passive mode, as will be described in more detail hereinafter, the upper hub 9 and the locking mechanism 10 have been slid to an upper position along the vertical central bar 4.

In the active mode the legs 12, 14, 16, 18 are inclined, in relation to the vertical central bar 4, similar as is disclosed in Fig. 1, to make the respective outwardly directed lifting portion 30 at the respective lower end 32 of the respective leg 12, 14, 16, 18 come into contact with the inner periphery 34 of the gyratory crusher outer crushing shell 2 such that the crushing shell 2 can be lifted. In this active mode, as will be described in more detail hereinafter with reference to Figs. 5a, 5b and 6, the upper hub 9 and the locking mechanism 10 have been slid to a lower position along the vertical central bar 4, wherein the exact position along the vertical central bar 4 depends on the particular inner width of that crushing shell 2 that should be lifted.

The vertical central bar 4 comprises a first and a second row 58, 60 of alternating horizontal teeth 62 and horizontal grooves 64 extending in opposite directions. The locking mechanism 10 comprises a first locking member 66 and a second locking member 68. Each locking member 66, 68 comprises horizontal teeth 70 and horizontal grooves 72 that are adapted to co-operate with the horizontal teeth 62 and horizontal grooves 64 of the vertical central bar 4 in a tooth-and-groove arrangement.

The locking mechanism 10 comprises a release mechanism 74, which in Fig. 2 is shown in a locked state. The release mechanism 74 comprises a first and a second slide plate 76, 78. The slide plates 76, 78 can be moved upwards in a vertical direction, shown by arrows RV, by means of a control handle 80, also shown in Fig. 1. Each slide plate 76, 78 is provided with inclined guiding tracks 82 cooperating with corresponding pins 84 of the locking members 66, 68. Upon lifting the control handle 80 upwardly the slide plates 76, 78 will move vertically upwards, in the direction of the arrows RV. As an effect of such upward movement, the inclined guiding tracks 82 of the respective first and second slide plate 76, 78 will cooperate with the pins 84 of the respective locking member 66, 68 and press the locking members 66, 68 horizontally, in the direction of arrows RH, away from the vertical central bar 4, thereby disengaging the teeth 70 and grooves 72 of the locking members 66, 68 from the teeth 62 and grooves 64 of the vertical central bar 4.

The locking mechanism 10 is provided with a fail-safe device comprising, in this embodiment, two springs 85. The springs 85 are

connected to the respective slide plates 76, 78 and are adapted to bring the locking mechanism 10 from the locked state of Fig. 2 to a released state, described hereinafter with reference to Fig. 3, unless a securing mechanism of the locking mechanism 10 has been properly installed to hold the locking mechanism 10 in the locked state. In Fig. 2 the securing mechanism 86 is schematically illustrated as two securing pins 86 that extend through the respective slide plates 76, 78 and further through a side wall 87 of the locking mechanism 10 to secure the slide plates 76, 78 in the locked position. Hence, when setting the locking mechanism 10 to its locked state, the control handle 80 is pressed downwards, against the action of the springs 85, until the securing pins 86 can be inserted, and in this locked state the locking members 66, 68 engage the vertical central bar 4 as illustrated in Fig. 2.

Fig. 3 illustrates the vertical central bar 4 and the upper hub 9, wherein the release mechanism 74 of the locking mechanism 10 is in the released state. This state has been reached by removing the securing pins 86, illustrated in Fig. 2, after which the springs 85 have forced the slide plates 76, 78 upwards, thereby urging the locking members 66, 68 away from the vertical central bar 4. In this released state, when the locking members 66, 68 have been pressed horizontally away from engagement with the vertical central bar 4, the locking mechanism 10, and thereby the upper hub 9 and the upper hub bracket and bearing devices 22, 24, 26, 28, can be moved freely along the vertical central bar 4 to set the desired inclination of the legs 12, 14, 16, 18, as will be described in more detail hereinafter.

Fig. 4 illustrates how the gyratory crusher shell lifting tool 1 has been set to the passive mode, wherein the legs 12, 14, 16, 18 are close to parallel to the vertical central bar 4, by transferring the locking mechanism 10 to its released state, illustrated in Fig. 3, and moving the upper hub 9 and the locking mechanism 10 upwards to its upper position, adjacent to the upper end 54 of the vertical central bar 4, and then returning the locking mechanism 10 to its locked state, illustrated in Fig. 2, and inserting the securing pins 86. The upper hub 9 may be provided with a lifting handle 88 to make it easier to move the upper hub 9 to its desired position. In this passive state the gyratory

crusher shell lifting tool 1 has been inserted into the interior of the gyratory crusher outer crushing shell 2, which lies on the ground GR.

Fig. 5a illustrates, in a perspective which is turned 90° compared to the perspective of Fig. 4, how the gyratory crusher shell lifting tool 1 has been set to the active mode. The setting to the active mode has been made by transferring the locking mechanism 10 to its released mode, illustrated in Fig. 3, moving the upper hub 9 with the locking mechanism 10 vertically downwards along the vertical central bar 4, in a direction towards the lower hub 6, thereby making the lifting legs 12, 14, 16, 18 turn outwardly in a vertical direction relative to the upper hub 9, such that the respective lower ends 32 of the legs 12, 14, 16, 18 move outwardly until the respective outwardly directed lifting portions 30 come into contact with the inner periphery 34 of the crushing shell 2, and then returning the locking mechanism 10 to its locked state, illustrated in Fig. 2. In this active state the angle α between the vertical plane and the respective legs 12, 14, 16, 18 of the lifting tool 1 is, in this particular case, about 20°.

Fig. 5b illustrates how a crane CR having a lifting hook LH has been connected to the lifting eye 56 of the gyratory crusher shell lifting tool 1 and lifts the crushing shell 2 from the ground GR.

When the shell lifting tool 1 and the crushing shell 2 have been lifted to the intended position for the crushing shell 2, for example another position on the ground GR, or to its intended position on a gyratory crusher, the locking mechanism 10 is adjusted to its released state and the lifting tool 1 is set to the passive mode illustrated in Fig. 4, and the shell lifting tool 1 may then be removed from the interior of the crusher shell 2.

Fig. 6 illustrates how the gyratory crusher shell lifting tool 1 is utilized for lifting a circular gyratory crusher outer crushing shell 102 that is considerably larger in inner diameter than the crushing shell 2 shown in Figs. 4, 5a and 5b. Similar as with the above description, the gyratory crusher shell lifting tool 1 has been set to the active mode, by transferring the locking mechanism 10 to its released mode, moving the upper hub 9 and the locking mechanism 10 vertically downwards along the vertical central bar 4, in the direction towards the lower hub 6, thereby making the respective lower ends

32 of the legs 12, 14, 16, 18 move outwardly until the respective outwardly directed lifting portions 30 come into contact with the inner periphery 134 of the crushing shell 102, and then returning the locking mechanism 10 to its locked state, whereby the crushing shell 102 can now be lifted from the
5 ground. In this state the angle α between the vertical plane and the respective leg 12, 14, 16, 18 is about 50°.

Hence, one size of gyratory crusher shell lifting tool 1 can be utilized for lifting gyratory crusher crushing shells having sizes that vary within wide ranges, from relatively small crushing shells 2, as shown in Figs. 4, 5a and
10 5b, to relatively large crushing shells 102, as shown in Fig. 6.

It will be appreciated that numerous variants of the embodiments described above are possible within the scope of the appended claims.

Hereinabove a lifting tool 1 having four lifting legs 12, 14, 16, 18 has
15 been described. It will be appreciated that a lifting tool can also be arranged with other numbers of lifting legs, as long as there are two or more lifting legs. For example 3-8 lifting legs, more preferably 4-5 lifting legs have proven to result in an efficient lifting tool 1 with low cost and safe properties when it comes to lifting a crushing shell 2.

20 Hereinbefore it has been described that the gyratory crusher shell lifting tool 1 comprises a lower hub 6, which is fixed to a lower end 8 of the vertical central bar 4, and an upper hub 9, which is arranged on the vertical central bar 4 above the lower hub 6 and which comprises a locking mechanism 10, making it possible to move the upper hub 9 to various
25 positions along the central bar 4 to turn the lifting legs 12, 14, 16, 18 to suitable angular positions to obtain a passive mode or various active modes suitable for various sizes of crushing shells 2. It will be appreciated that as alternative to the lower hub 6 being fixed to the central bar 4 and the upper hub 9 being releasably fixed to the central bar 4 by means of the locking
30 mechanism 10, it is also possible, according to an alternative embodiment, to arrange the upper hub 9 fixedly to the central bar 4, at an upper end thereof, and arrange the lower hub 6 releasably fixed to the central bar 4 by means of a locking mechanism, whereby the lower hub 6 can be moved along the

central bar 4, below the upper hub 9, after the locking mechanism has been set to a released state. Furthermore, it is also possible to arrange both the upper hub 9 and the lower hub 6 with a respective locking mechanism, such that each of the upper hub 9 and the lower hub 6 can be moved along the
5 central bar 4 when the respective locking mechanism has been set to the released state.

To summarize, a gyratory crusher shell lifting tool (1) adapted for lifting a gyratory crusher shell (2) comprises:

a generally vertical central bar (4),
10 a lower hub (6) arranged at a lower end (8) of the central bar (4),
an upper hub (9) arranged at the central bar (4) above the lower hub (6),

at least one locking mechanism (10) arranged on at least one of the upper and lower hubs (9, 6) to make that hub (9) releasably fixed to the
15 central bar (4),

a first lifting leg (12) and a second lifting leg (16) provided with a respective outwardly directed lifting portion (30) adapted to come into contact with an inner periphery (34) of the crushing shell (2), wherein the respective outwardly directed lifting portion (30) is moved away from the central bar (4)
20 when one hub (9) is moved in the direction of the other hub (6).

CLAIMS

1. A gyratory crusher shell lifting tool adapted for lifting a gyratory
5 crusher shell (2), c h a r a c t e r i s e d in comprising:
a generally vertical central bar (4),
a lower hub (6) arranged at a lower end (8) of the central bar (4),
an upper hub (9) arranged at the central bar (4) above the lower
hub (6),
10 at least one locking mechanism (10) arranged on at least one of the
upper and lower hubs (9, 6) to make the at least one of the upper
and lower hubs (9, 6) releasably fixed to the central bar (4),
at least a first lifting leg (12) and a second lifting leg (16) that are
provided with a respective outwardly directed lifting portion (30)
15 adapted to come into contact with an inner periphery (34) of a
gyratory crusher shell (2), wherein each of the first and second
lifting legs (12, 16) are mounted to the upper hub (9) and being
journalled therein to be turnable in a vertical direction relative to the
upper hub (9), and wherein each lifting leg (12, 16) is journalled to a
20 respective link (38, 42) extending to the lower hub (6), said
respective link (38, 42) being adapted to move the respective
outwardly directed lifting portion (30) of the respective leg (12, 16)
away from the central bar (4) when at least one of the lower and
upper hubs (6, 9) is moved in the direction of the other one of the
25 lower and upper hubs (6, 9).
2. A shell lifting tool according to claim 1, wherein the at least a first
lifting leg (12) and a second lifting leg (16) are evenly distributed
around the periphery of the central bar (4).
- 30 3. A shell lifting tool according to any one of the preceding claims,
wherein the shell lifting tool (1) comprises at least three lifting legs
(12, 14, 16).

- 5
4. A shell lifting tool according to any one of the preceding claims, wherein the shell lifting tool (1) comprises 3 - 8 lifting legs (12, 14, 16, 18), more preferably 4 – 5 lifting legs (12, 14, 16, 18).
- 10
5. A shell lifting tool according to any one of the preceding claims, wherein the respective outwardly directed lifting portions (30) of the lifting legs (12, 16) are arranged at respective lower ends (32) of the respective legs (12, 16).
- 15
6. A shell lifting tool according to any one of the preceding claims, wherein each lifting leg (12, 16) is journalled to the respective link (38, 42) extending to the lower hub (6) at a respective central portion (36) of the respective lifting leg (12, 16).
- 20
7. A shell lifting tool according to any one of the preceding claims, wherein the upper hub (9) is provided with the locking mechanism (10) and is releasably fixed to the vertical central bar (4), and wherein the lower hub (6) is fixedly mounted to a lower end (8) of the vertical central bar (4).
- 25
8. A shell lifting tool according to claim 7, wherein the locking mechanism (10) is integrated into the upper hub (9).
- 30
9. A shell lifting tool according to any one of the preceding claims, wherein the locking mechanism (10) comprises at least one locking member (66, 68) which is adapted to co-operate with the vertical central bar (4) in a tooth-and-groove arrangement (62, 64, 70, 72) in a locked state of the locking mechanism (10).
- 35
10. A shell lifting tool according to any one of the preceding claims, wherein a control handle (80) of the locking mechanism (10) is adapted for switching the position of at least one locking member (66, 68) between a locked state in which the locking member (66, 68) co-operates with the vertical central bar (4) and a released state

in which the locking member (66, 68) and the vertical central bar (4) are released from each other.

- 5 11. A shell lifting tool according to any one of the preceding claims, wherein the locking mechanism (10) is provided with a fail-safe device, such as a spring device (85), which is adapted to bring the locking mechanism (10) to a released state unless a securing mechanism (86) of the locking mechanism (10) has been properly installed to hold the locking mechanism (10) in a locked state.
- 10 12. A shell lifting tool according to any one of the preceding claims, wherein the vertical central bar (4) is provided with a lifting device (56), such as a lifting eye, arranged in an upper end (54) thereof.
- 15 13. A method of lifting a gyratory crusher shell, the method comprising:
- placing a gyratory crusher shell lifting tool (1) inside the gyratory crusher shell (2), the shell lifting tool (1) comprising:
a generally vertical central bar (4),
a lower hub (6) arranged at a lower end (8) of the central bar (4),
20 an upper hub (9) arranged at the central bar (4) above the lower hub (6),
at least a first lifting leg (12) and a second lifting leg (16) that are provided with a respective outwardly directed lifting portion (30), wherein each of the first and second lifting legs (12, 16) are
25 mounted to the upper hub (9) and being journalled therein to be turnable in a vertical direction relative to the upper hub (9), and wherein each lifting leg (12, 16) is journalled to a respective link (38, 42) extending to the lower hub (6), the method further comprising:
30 - moving at least one of the lower and upper hubs (6, 9) in the direction of the other one of the lower and upper hubs (6, 9) to make the outwardly directed lifting portions (30) of the legs (12, 16) come into contact with an inner periphery (34) of the gyratory crusher shell (2),

- locking at least that hub (6, 9) that has been moved to the vertical central bar (4), such that both hubs (6, 9) become fixed to the vertical central bar (4), and
 - lifting the shell lifting tool (1) and thereby lifting the gyratory crusher shell (2) together with it.
- 5

14. A method according to claim 13, wherein said step of moving at least one of the lower and upper hubs (6, 9) in the direction of the other one of the lower and upper hubs (6, 9) includes moving the upper hub (9) downwardly in the direction of the lower hub (6), and wherein said step of locking at least that hub (6, 9) that has been moved to the vertical central bar (4) includes locking the upper hub (9) to the central bar (4).

10

15. A method according to any one of claims 13-14, further comprising lifting the shell lifting tool (1) by connecting a lift (CR) to a lifting device (56) arranged at an upper end (54) of the vertical central bar (4).

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1/6

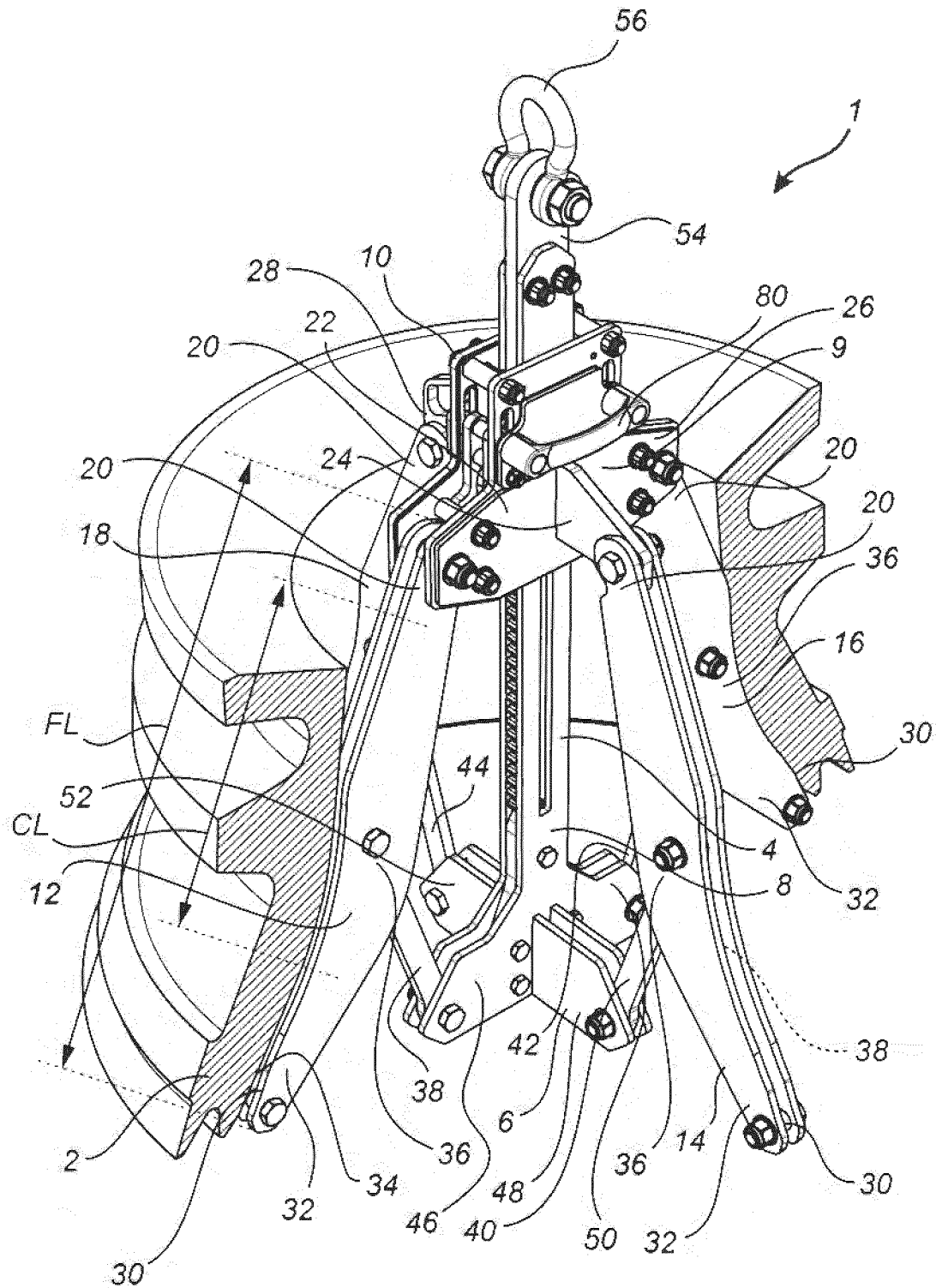
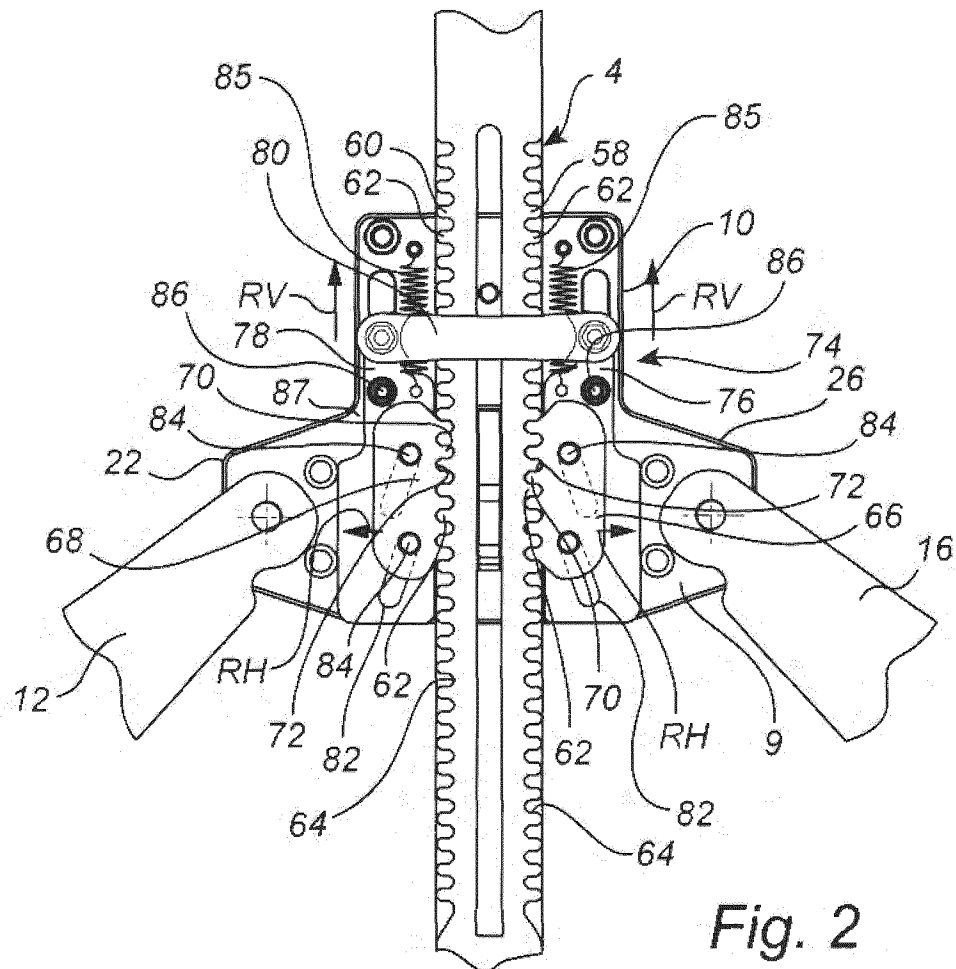


Fig. 1

2/6



3/6

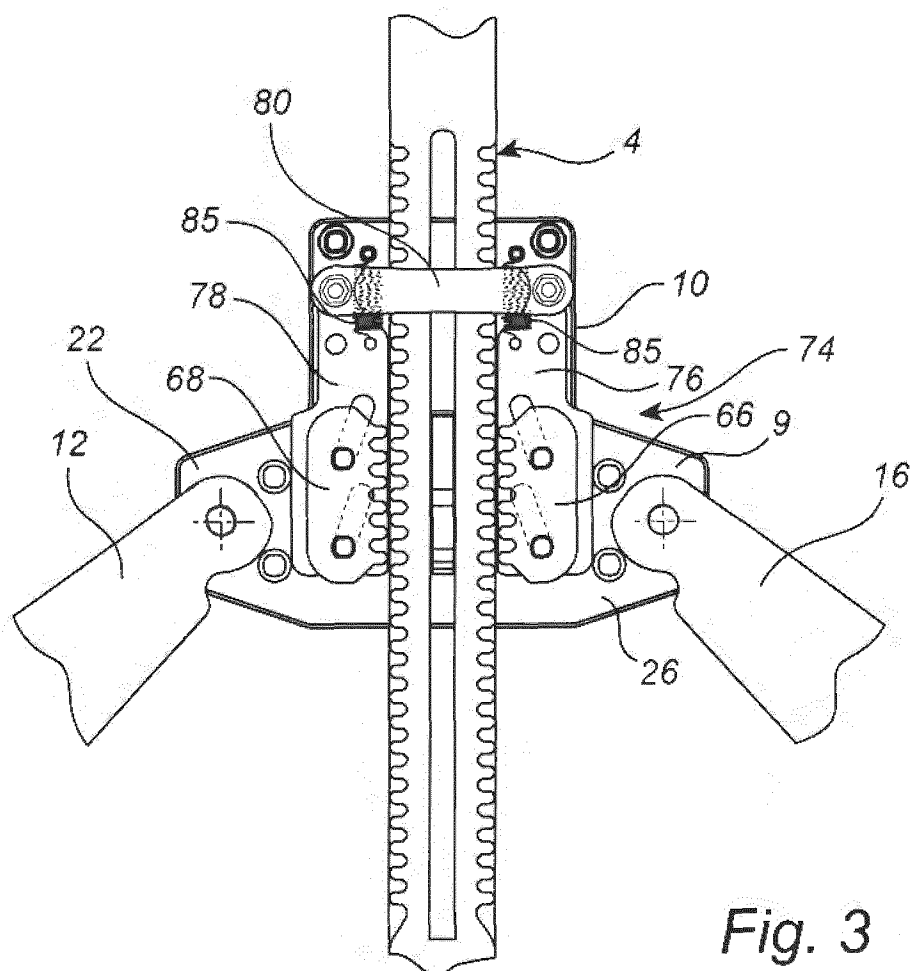
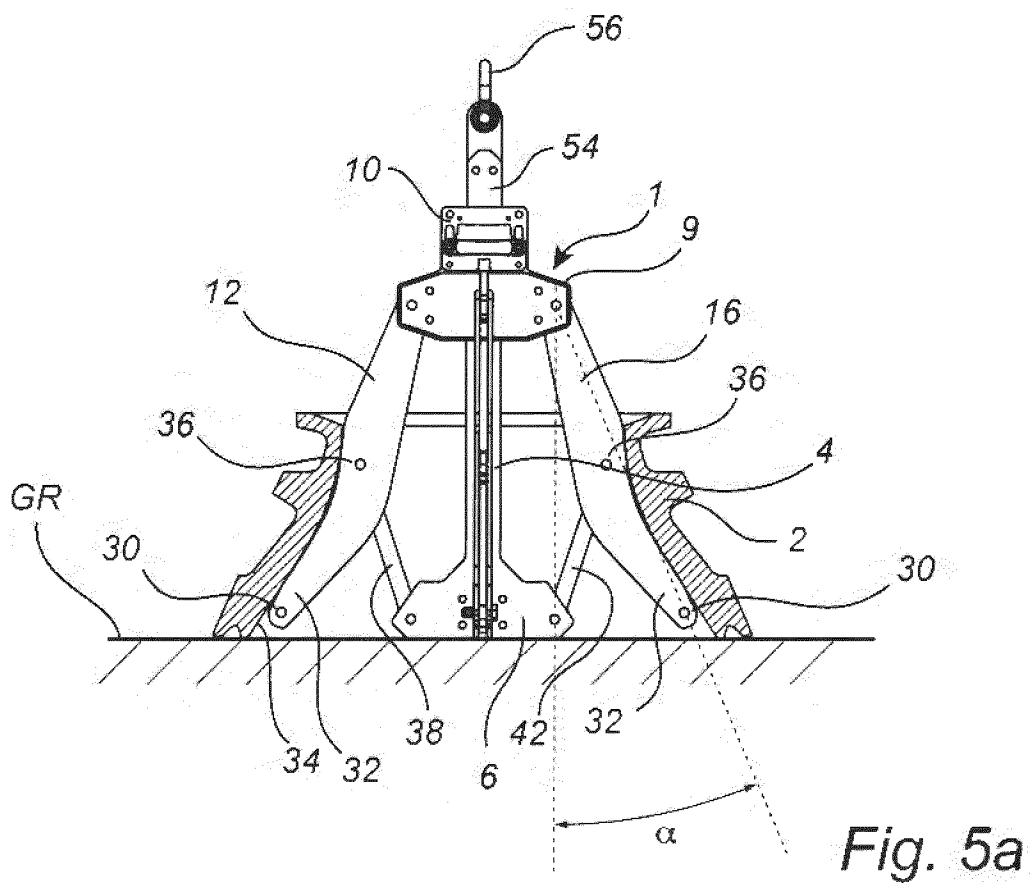
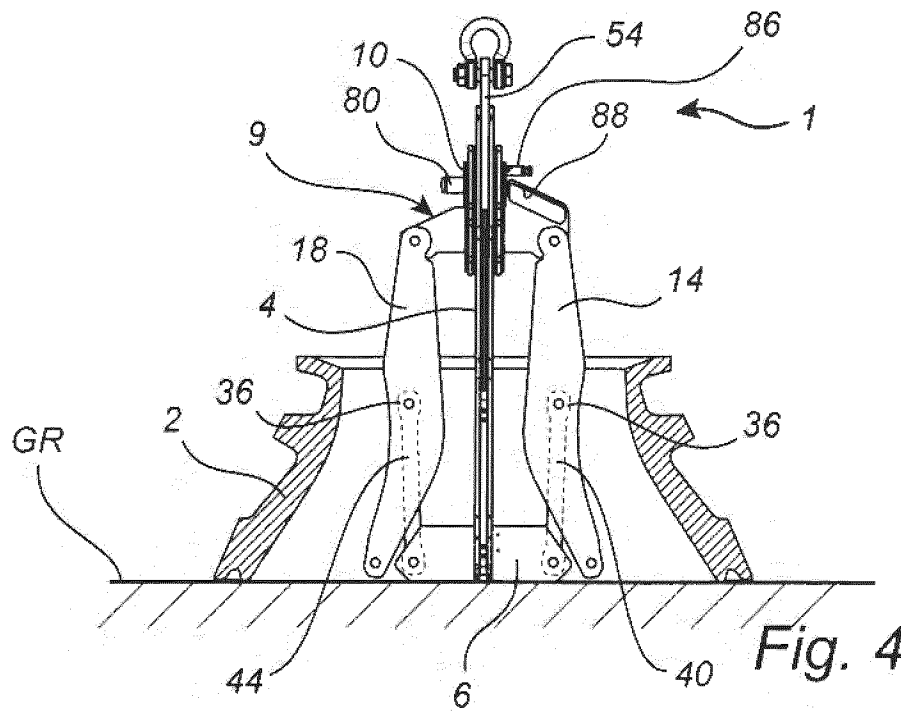


Fig. 3

4/6



5/6

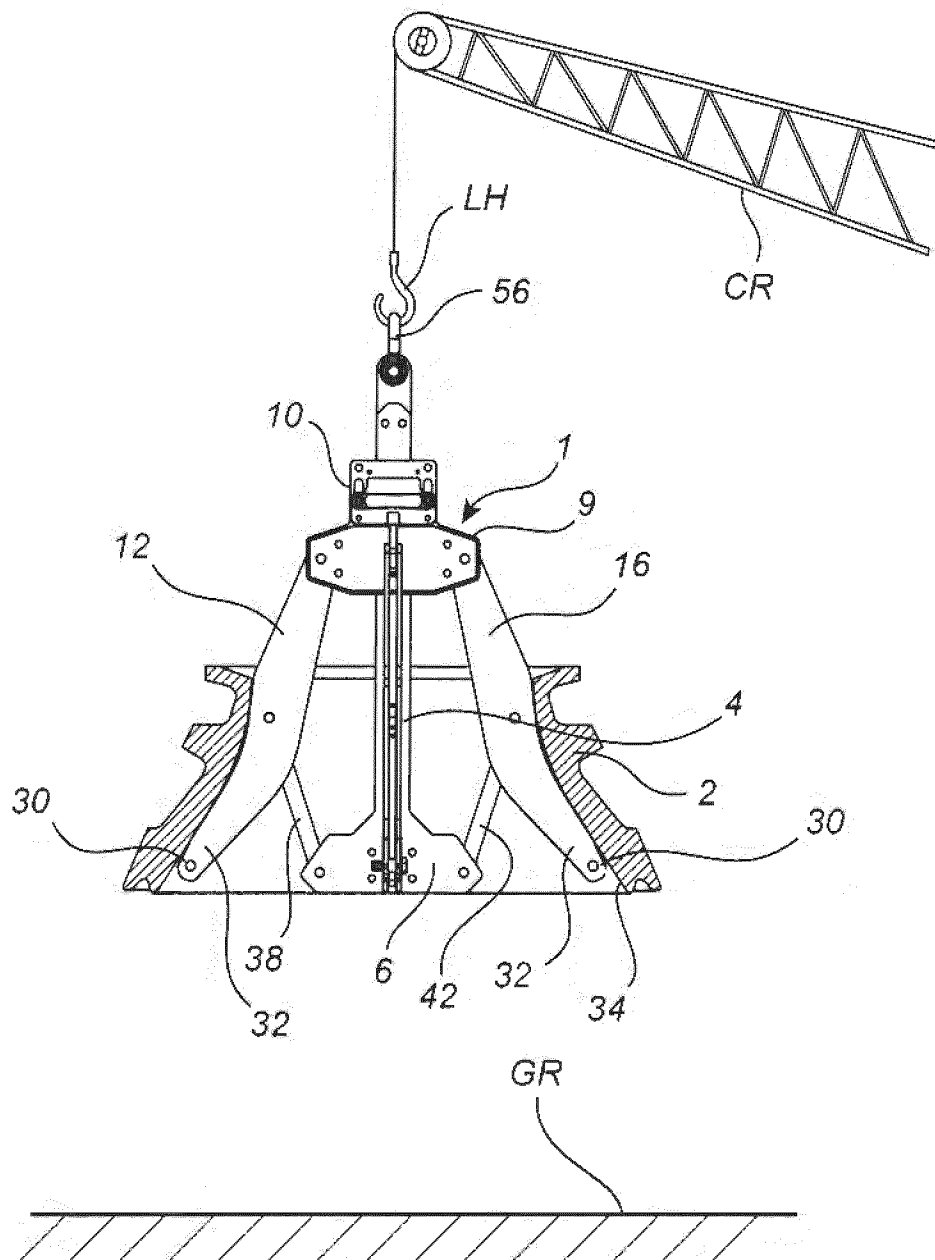


Fig. 5b

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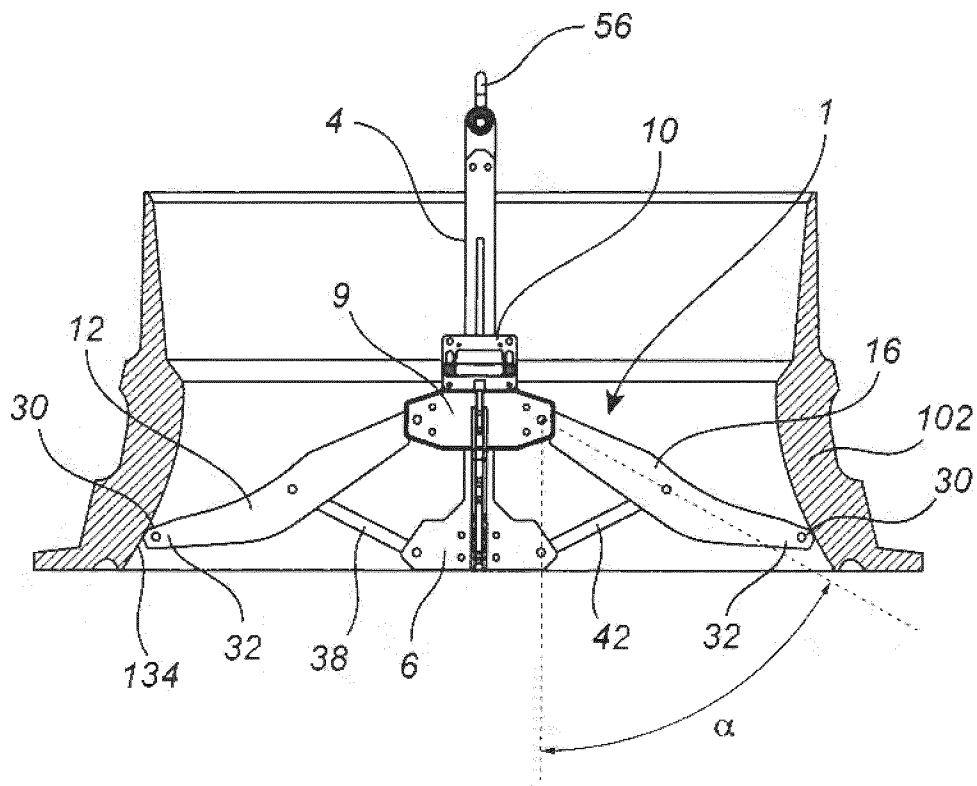


Fig. 6

INTERNATIONAL SEARCH REPORT

International application No

PCT/EP2015/053179

A. CLASSIFICATION OF SUBJECT MATTER

INV. B02C2/00 B02C2/04
ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

B02C B66C

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-Internal

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	GB 886 706 A (STANDARD TELEPHONES CABLES LTD) 10 January 1962 (1962-01-10)	1,2,5,7
Y	the whole document	13-15
A		3,4,6, 8-12
Y	----- EP 2 692 442 A1 (SANDVIK INTELLECTUAL PROPERTY [SE]) 5 February 2014 (2014-02-05) cited in the application	13-15
A	abstract figures 2-5	1
X	----- US 3 088 769 A (RICHARDSON WILLIAM F) 7 May 1963 (1963-05-07)	1-4,7,12
A	column 1, line 9 - line 25 column 1, line 51 - column 4, line 63 figures 1-6 ----- -/-	13



Further documents are listed in the continuation of Box C.



See patent family annex.

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"&" document member of the same patent family

Date of the actual completion of the international search

12 May 2015

Date of mailing of the international search report

20/05/2015

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INTERNATIONAL SEARCH REPORT

International application No

PCT/EP2015/053179

C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 2 951 725 A (ST JEAN ROBERT R)	1,2,7,8
A	6 September 1960 (1960-09-06) page 1, line 15 - line 18 column 3, line 1 - column 4, line 21 figures 1-3 -----	13

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No

PCT/EP2015/053179

Patent document cited in search report		Publication date	Patent family member(s)	Publication date
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EP 2692442	A1	05-02-2014	EP 2692442 A1	05-02-2014
			WO 2014019762 A1	06-02-2014

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US 2951725	A	06-09-1960	NONE	
