Several motorized terrestrial transport units 701 are loaded into a mother vehicle 702 along with several items 703 to be delivered to various different recipients. The mother vehicle moves to a delivery location and a motorized transport unit is dispatched to deliver one or more items to a recipient. Before that transport unit returns to the mother vehicle for recovery, the mother vehicle moves to a second delivery location and dispatches a second motorized transport unit to deliver one or more different items to a second recipient. The mother vehicle subsequently recovers at least the first transport units at a recovery location. The items may be pre-loaded into lockers 132 that may be pre-attached to corresponding transport units. The lockers may be secured so that they can be opened only using an unlocking mechanism 704. The transport units may be guided to their respective recovery locations.
FIG. 4

- Housing
- Wireless Transceiver
- Control Circuit
- User Interface
- Motorized Wheel System
- Power Source
- Item Container Coupling Structure
- Audio Output
- Audio Input
- I/O Device
- Sensor
LOAD A PLURALITY OF MOTORIZED TERRESTRIAL TRANSPORT UNITS INTO A MOTHER VEHICLE

LOAD INTO THE MOTHER VEHICLE A PLURALITY OF ITEMS TO BE DELIVERED TO VARIOUS CORRESPONDING DIFFERENT RECIPIENTS

MOVE THE MOTHER VEHICLE TO A FIRST DELIVERY LOCATION

DISPATCH A FIRST OF THE MOTORIZED TERRESTRIAL TRANSPORT UNITS CARRYING AT LEAST A FIRST OF THE ITEMS TO LEAVE THE MOTHER VEHICLE AND TRANSPORT THE FIRST OF THE ITEMS TO EFFECT DELIVERY TO A FIRST OF THE RECIPIENTS

PRIOR TO THE FIRST OF THE MOTORIZED TERRESTRIAL TRANSPORT UNITS RETURNING TO THE MOTHER VEHICLE, MOVE THE MOTHER VEHICLE TO A SECOND DELIVERY LOCATION AND DISPATCH A SECOND OF THE MOTORIZED TERRESTRIAL TRANSPORT UNITS CARRYING AT LEAST A SECOND OF THE ITEMS TO LEAVE THE MOTHER VEHICLE AND TRANSPORT THE SECOND OF THE ITEMS TO EFFECT DELIVERY TO A SECOND OF THE RECIPIENTS

RECOVER AT LEAST THE FIRST OF THE MOTORIZED TERRESTRIAL TRANSPORT UNITS AT A FIRST RECOVERY LOCATION INTO THE MOTHER VEHICLE

FIG. 6
The following terms are registered trade marks and should be read as such wherever they occur in this document:

WiFi
Zigbee
Bluetooth
Diet Coke
SHOPPING FACILITY ASSISTANCE SYSTEMS, DEVICES, AND METHODS TO DISPATCH AND RECOVER MOTORIZED TRANSPORT UNITS THAT EFFECT REMOTE DELIVERIES

Cross-Reference To Related Application

[0001] This application claims the benefit of U.S. Provisional Application No. 62/194,121, filed July 17, 2015, and which is incorporated herein by reference.

Technical Field

[0002] These teachings relate generally to retail shopping services and more particularly to devices, systems, and methods for assisting customers and/or workers as regards those retail shopping services.

Background

[0003] In a modern retail store environment, there is a need to improve the customer experience and/or convenience for the customer. With increasing competition from non-traditional shopping mechanisms, such as online shopping provided by e-commerce merchants and alternative store formats, it can be important for all retailers (including but not limited to “bricks and mortar” retailers) to focus on improving the overall customer experience and/or convenience.

[0004] The foregoing can include providing and/or and enhancing home delivery service. Whether the customer buys a product in a traditional store, or via an online opportunity, many customers are seeking the convenience of having their purchases delivered to their homes, offices, hotel rooms, dormitories, or other places of residence or work. Making such a delivery typically entails either enlisting the services of one of the traditional delivery services (such as the United States Postal Service, United Parcel Service, FedEx, and so forth) or of maintaining a private delivery capability. While such options can be useful in some application settings, unfortunately all presently available options leave at least something to be desired by way of cost, timeliness, security, and so forth.
Brief Description of the Drawings

[0005] The above needs are at least partially met through provision of embodiments of systems, devices, and methods designed to provide assistance to customers and/or workers in a shopping facility, such as described in the following detailed description, particularly when studied in conjunction with the drawings, wherein:

[0006] FIG. 1 comprises a block diagram of a shopping assistance system as configured in accordance with various embodiments of these teachings;

[0007] FIGS. 2A and 2B are illustrations of a motorized transport unit of the system of FIG. 1 in a retracted orientation and an extended orientation in accordance with some embodiments;

[0008] FIGS. 3A and 3B are illustrations of the motorized transport unit of FIGS. 2A and 2B detachably coupling to a movable item container, such as a shopping cart, in accordance with some embodiments;

[0009] FIG. 4 comprises a block diagram of a motorized transport unit as configured in accordance with various embodiments of these teachings;

[0010] FIG. 5 comprises a block diagram of a computer device as configured in accordance with various embodiments of these teachings;

[0011] FIG. 6 comprises a flow diagram as configured in accordance with various embodiments of these teachings; and

[0012] FIG. 7 comprises a block diagram as configured in accordance with various embodiments of these teachings.

[0013] Elements in the figures are illustrated for simplicity and clarity and have not necessarily been drawn to scale. For example, the dimensions and/or relative positioning of some of the elements in the figures may be exaggerated relative to other elements to help to improve understanding of various embodiments of the present teachings. Also, common but well-understood elements that are useful or necessary in a commercially feasible embodiment are often not depicted in order to facilitate a less obstructed view of these various embodiments of the present teachings. Certain actions and/or steps may be described or depicted in a particular order of occurrence while those skilled in the art will understand that such specificity with respect to sequence is not actually required. The terms and expressions
used herein have the ordinary technical meaning as is accorded to such terms and expressions
by persons skilled in the technical field as set forth above except where different specific
meanings have otherwise been set forth herein.

Detailed Description

[0014] The following description is not to be taken in a limiting sense, but is made
merely for the purpose of describing the general principles of exemplary embodiments.
Reference throughout this specification to "one embodiment," "an embodiment," or similar
language means that a particular feature, structure, or characteristic described in connection
with the embodiment is included in at least one embodiment of the present invention. Thus,
appearances of the phrases "in one embodiment," "in an embodiment," and similar language
throughout this specification may, but do not necessarily, all refer to the same embodiment.

[0015] Generally speaking, pursuant to various embodiments, systems, devices and
methods are provided for assistance of persons at a shopping facility. Generally, assistance
may be provided to customers or shoppers at the facility and/or to workers at the facility. The
facility may be any type of shopping facility at a location in which products for display
and/or for sale are variously distributed throughout the shopping facility space. The shopping
facility may be a retail sales facility, or any other type of facility in which products are
displayed and/or sold. The shopping facility may include one or more of sales floor areas,
checkout locations (i.e., point of sale (POS) locations), customer service areas other than
checkout locations (such as service areas to handle returns), parking locations, entrance and
exit areas, stock room areas, stock receiving areas, hallway areas, common areas shared by
merchants, and so on. Generally, a shopping facility includes areas that may be dynamic in
terms of the physical structures occupying the space or area and objects, items, machinery
and/or persons moving in the area. For example, the sales floor area may include product
storage units, shelves, racks, modules, bins, etc., and other walls, dividers, partitions, etc. that
may be configured in different layouts or physical arrangements. In other example, persons
or other movable objects may be freely and independently traveling through the shopping
facility space. And in another example, the persons or movable objects move according to
known travel patterns and timing. The facility may be any size of format facility, and may
include products from one or more merchants. For example, a facility may be a single store
operated by one merchant or may be a collection of stores covering multiple merchants such
as a mall.
Generally, the system makes use of automated, robotic mobile devices, e.g., motorized transport units, that are capable of self-powered movement through a space of the shopping facility and providing any number of functions. Movement and operation of such devices may be controlled by a central computer system or may be autonomously controlled by the motorized transport units themselves. Various embodiments provide one or more user interfaces to allow various users to interact with the system including the automated mobile devices and/or to directly interact with the automated mobile devices. In some embodiments, the automated mobile devices and the corresponding system serve to enhance a customer shopping experience in the shopping facility, e.g., by assisting shoppers and/or workers at the facility.

In some embodiments, a shopping facility personal assistance system comprises: a plurality of motorized transport units located in and configured to move through a shopping facility space; a plurality of user interface units, each corresponding to a respective motorized transport unit during use of the respective motorized transport unit; and a central computer system having a network interface such that the central computer system wirelessly communicates with one or both of the plurality of motorized transport units and the plurality of user interface units, wherein the central computer system is configured to control movement of the plurality of motorized transport units through the shopping facility space based at least on inputs from the plurality of user interface units.

SYSTEM OVERVIEW

Referring now to the drawings, FIG. 1 illustrates embodiments of a shopping facility assistance system 100 that can serve to carry out at least some of the teachings set forth herein. It will be understood that the details of this example are intended to serve in an illustrative capacity and are not necessarily intended to suggest any limitations as regards the present teachings. It is noted that generally, FIGS. 1-5 describe the general functionality of several embodiments of a system, and FIGS. 6 and 7 expand on some functionalities of some embodiments of the system and/or embodiments independent of such systems.

In the example of FIG. 1, a shopping assistance system 100 is implemented in whole or in part at a shopping facility 101. Generally, the system 100 includes one or more motorized transport units (MTUs) 102; one or more item containers 104; a central computer system 106 having at least one control circuit 108, at least one memory 110 and at least one
network interface 112; at least one user interface unit 114; a location determination system 116; at least one video camera 118; at least one motorized transport unit (MTU) dispenser 120; at least one motorized transport unit (MTU) docking station 122; at least one wireless network 124; at least one database 126; at least one user interface computer device 128; an item display module 130; and a locker or an item storage unit 132. It is understood that more or fewer of such components may be included in different embodiments of the system 100.

[0021] These motorized transport units 102 are located in the shopping facility 101 and are configured to move throughout the shopping facility space. Further details regarding such motorized transport units 102 appear further below. Generally speaking, these motorized transport units 102 are configured to either comprise, or to selectively couple to, a corresponding movable item container 104. A simple example of an item container 104 would be a shopping cart as one typically finds at many retail facilities, or a rocket cart, a flatbed cart or any other mobile basket or platform that may be used to gather items for potential purchase.

[0022] In some embodiments, these motorized transport units 102 wirelessly communicate with, and are wholly or largely controlled by, the central computer system 106. In particular, in some embodiments, the central computer system 106 is configured to control movement of the motorized transport units 102 through the shopping facility space based on a variety of inputs. For example, the central computer system 106 communicates with each motorized transport unit 102 via the wireless network 124 which may be one or more wireless networks of one or more wireless network types (such as, a wireless local area network, a wireless personal area network, a wireless mesh network, a wireless star network, a wireless wide area network, a cellular network, and so on), capable of providing wireless coverage of the desired range of the motorized transport units 102 according to any known wireless protocols, including but not limited to a cellular, Wi-Fi, Zigbee or Bluetooth network.

[0023] By one approach the central computer system 106 is a computer based device and includes at least one control circuit 108, at least one memory 110 and at least one wired and/or wireless network interface 112. Such a control circuit 108 can comprise a fixed-purpose hard-wired platform or can comprise a partially or wholly programmable platform, such as a microcontroller, an application specification integrated circuit, a field programmable gate array, and so on. These architectural options are well known and
understood in the art and require no further description here. This control circuit 108 is configured (for example, by using corresponding programming stored in the memory 110 as will be well understood by those skilled in the art) to carry out one or more of the steps, actions, and/or functions described herein.

[0024] In this illustrative example the control circuit 108 operably couples to one or more memories 110. The memory 110 may be integral to the control circuit 108 or can be physically discrete (in whole or in part) from the control circuit 108 as desired. This memory 110 can also be local with respect to the control circuit 108 (where, for example, both share a common circuit board, chassis, power supply, and/or housing) or can be partially or wholly remote with respect to the control circuit 108 (where, for example, the memory 110 is physically located in another facility, metropolitan area, or even country as compared to the control circuit 108).

[0025] This memory 110 can serve, for example, to non-transitorily store the computer instructions that, when executed by the control circuit 108, cause the control circuit 108 to behave as described herein. (As used herein, this reference to “non-transitorily” will be understood to refer to a non-ephemeral state for the stored contents (and hence excludes when the stored contents merely constitute signals or waves) rather than volatility of the storage media itself and hence includes both non-volatile memory (such as read-only memory (ROM) as well as volatile memory (such as an erasable programmable read-only memory (EPROM)).)

[0026] Additionally, at least one database 126 may be accessible by the central computer system 106. Such databases may be integrated into the central computer system 106 or separate from it. Such databases may be at the location of the shopping facility 101 or remote from the shopping facility 101. Regardless of location, the databases comprise memory to store and organize certain data for use by the central control system 106. In some embodiments, the at least one database 126 may store data pertaining to one or more of: shopping facility mapping data, customer data, customer shopping data and patterns, inventory data, product pricing data, and so on.

[0027] In this illustrative example, the central computer system 106 also wirelessly communicates with a plurality of user interface units 114. These teachings will accommodate a variety of user interface units including, but not limited to, mobile and/or handheld
electronic devices such as so-called smart phones and portable computers such as tablet/pad-styled computers. Generally speaking, these user interface units 114 should be able to wirelessly communicate with the central computer system 106 via a wireless network, such as the wireless network 124 of the shopping facility 101 (such as a Wi-Fi wireless network). These user interface units 114 generally provide a user interface for interaction with the system. In some embodiments, a given motorized transport unit 102 is paired with, associated with, assigned to or otherwise made to correspond with a given user interface unit 114. In some embodiments, these user interface units 114 should also be able to receive verbally-expressed input from a user and forward that content to the central computer system 106 or a motorized transport unit 102 and/or convert that verbally-expressed input into a form useful to the central computer system 106 or a motorized transport unit 102.

[0028] By one approach at least some of the user interface units 114 belong to corresponding customers who have come to the shopping facility 101 to shop. By another approach, in lieu of the foregoing or in combination therewith, at least some of the user interface units 114 belong to the shopping facility 101 and are loaned to individual customers to employ as described herein. In some embodiments, one or more user interface units 114 are attachable to a given movable item container 104 or are integrated with the movable item container 104. Similarly, in some embodiments, one or more user interface units 114 may be those of shopping facility workers, belong to the shopping facility 101 and are loaned to the workers, or a combination thereof.

[0029] In some embodiments, the user interface units 114 may be general purpose computer devices that include computer programming code to allow it to interact with the system 106. For example, such programming may be in the form of an application installed on the user interface unit 114 or in the form of a browser that displays a user interface provided by the central computer system 106 or other remote computer or server (such as a web server). In some embodiments, one or more user interface units 114 may be special purpose devices that are programmed to primarily function as a user interface for the system 100. Depending on the functionality and use case, user interface units 114 may be operated by customers of the shopping facility or may be operated by workers at the shopping facility, such as facility employees (associates or colleagues), vendors, suppliers, contractors, etc.

[0030] By one approach, the system 100 optionally includes one or more video cameras 118. Captured video imagery from such a video camera 118 can be provided to the
central computer system 106. That information can then serve, for example, to help the central computer system 106 determine a present location of one or more of the motorized transport units 102 and/or determine issues or concerns regarding automated movement of those motorized transport units 102 in the shopping facility space. As one simple example in these regards, such video information can permit the central computer system 106, at least in part, to detect an object in a path of movement of a particular one of the motorized transport units 102.

[0031] By one approach these video cameras 118 comprise existing surveillance equipment employed at the shopping facility 101 to serve, for example, various security purposes. By another approach these video cameras 118 are dedicated to providing video content to the central computer system 106 to facilitate the latter’s control of the motorized transport units 102. If desired, the video cameras 118 can have a selectively movable field of view and/or zoom capability that the central computer system 106 controls as appropriate to help ensure receipt of useful information at any given moment.

[0032] In some embodiments, a location detection system 116 is provided at the shopping facility 101. The location detection system 116 provides input to the central computer system 106 useful to help determine the location of one or more of the motorized transport units 102. In some embodiments, the location detection system 116 includes a series of light sources (e.g., LEDs (light-emitting diodes)) that are mounted in the ceiling at known positions throughout the space and that each encode data in the emitted light that identifies the source of the light (and thus, the location of the light). As a given motorized transport unit 102 moves through the space, light sensors (or light receivers) at the motorized transport unit 102, on the movable item container 104 and/or at the user interface unit 114 receive the light and can decode the data. This data is sent back to the central computer system 106 which can determine the position of the motorized transport unit 102 by the data of the light it receives, since it can relate the light data to a mapping of the light sources to locations at the facility 101. Generally, such lighting systems are known and commercially available, e.g., the ByteLight system from ByteLight of Boston, Massachusetts. In embodiments using a ByteLight system, a typical display screen of the typical smart phone device can be used as a light sensor or light receiver to receive and process data encoded into the light from the ByteLight light sources.
In other embodiments, the location detection system 116 includes a series of low energy radio beacons (e.g., Bluetooth low energy beacons) at known positions throughout the space and that each encode data in the emitted radio signal that identifies the beacon (and thus, the location of the beacon). As a given motorized transport unit 102 moves through the space, low energy receivers at the motorized transport unit 102, on the movable item container 104 and/or at the user interface unit 114 receive the radio signal and can decode the data. This data is sent back to the central computer system 106 which can determine the position of the motorized transport unit 102 by the location encoded in the radio signal it receives, since it can relate the location data to a mapping of the low energy radio beacons to locations at the facility 101. Generally, such low energy radio systems are known and commercially available. In embodiments using a Bluetooth low energy radio system, a typical Bluetooth radio of a typical smart phone device can be used as a receiver to receive and process data encoded into the Bluetooth low energy radio signals from the Bluetooth low energy beacons.

In still other embodiments, the location detection system 116 includes a series of audio beacons at known positions throughout the space and that each encode data in the emitted audio signal that identifies the beacon (and thus, the location of the beacon). As a given motorized transport unit 102 moves through the space, microphones at the motorized transport unit 102, on the movable item container 104 and/or at the user interface unit 114 receive the audio signal and can decode the data. This data is sent back to the central computer system 106 which can determine the position of the motorized transport unit 102 by the location encoded in the audio signal it receives, since it can relate the location data to a mapping of the audio beacons to locations at the facility 101. Generally, such audio beacon systems are known and commercially available. In embodiments using an audio beacon system, a typical microphone of a typical smart phone device can be used as a receiver to receive and process data encoded into the audio signals from the audio beacon.

Also optionally, the central computer system 106 can operably couple to one or more user interface computers 128 (comprising, for example, a display and a user input interface such as a keyboard, touch screen, and/or cursor-movement device). Such a user interface computer 128 can permit, for example, a worker (e.g., an associate, analyst, etc.) at the retail or shopping facility 101 to monitor the operations of the central computer system 106 and/or to attend to any of a variety of administrative, configuration or evaluation tasks as
may correspond to the programming and operation of the central computer system 106. Such user interface computers 128 may be at or remote from the location of the facility 101 and may access one or more of the databases 126.

[0036] In some embodiments, the system 100 includes at least one motorized transport unit (MTU) storage unit or dispenser 120 at various locations in the shopping facility 101. The dispenser 120 provides for storage of motorized transport units 102 that are ready to be assigned to customers and/or workers. In some embodiments, the dispenser 120 takes the form of a cylinder within which motorized transports units 102 are stacked and released through the bottom of the dispenser 120. Further details of such embodiments are provided further below. In some embodiments, the dispenser 120 may be fixed in location or may be mobile and capable of transporting itself to a given location or utilizing a motorized transport unit 102 to transport the dispenser 120, then dispense one or more motorized transport units 102.

[0037] In some embodiments, the system 100 includes at least one motorized transport unit (MTU) docking station 122. These docking stations 122 provide locations where motorized transport units 102 can travel and connect to. For example, the motorized transport units 102 may be stored and charged at the docking station 122 for later use, and/or may be serviced at the docking station 122.

[0038] In accordance with some embodiments, a given motorized transport unit 102 detachably connects to a movable item container 104 and is configured to move the movable item container 104 through the shopping facility space under control of the central computer system 106 and/or the user interface unit 114. For example, a motorized transport unit 102 can move to a position underneath a movable item container 104 (such as a shopping cart, a rocket cart, a flatbed cart, or any other mobile basket or platform), align itself with the movable item container 104 (e.g., using sensors) and then raise itself to engage an undersurface of the movable item container 104 and lift a portion of the movable item container 104. Once the motorized transport unit is cooperating with the movable item container 104 (e.g., lifting a portion of the movable item container), the motorized transport unit 102 can continue to move throughout the facility space 101 taking the movable item container 104 with it. In some examples, the motorized transport unit 102 takes the form of the motorized transport unit 202 of FIGS. 2A-3B as it engages and detachably connects to a given movable item container 104. It is understood that in other embodiments, the motorized...
transport unit 102 may not lift a portion of the movable item container 104, but that it removably latches to, connects to or otherwise attaches to a portion of the movable item container 104 such that the movable item container 104 can be moved by the motorized transport unit 102. For example, the motorized transport unit 102 can connect to a given movable item container using a hook, a mating connector, a magnet, and so on.

In addition to detachably coupling to movable item containers 104 (such as shopping carts), in some embodiments, motorized transport units 102 can move to and engage or connect to an item display module 130 and/or an item storage unit or locker 132. For example, an item display module 130 may take the form of a mobile display rack or shelving unit configured to house and display certain items for sale. It may be desired to position the display module 130 at various locations within the shopping facility 101 at various times. Thus, one or more motorized transport units 102 may move (as controlled by the central computer system 106) underneath the item display module 130, extend upward to lift the module 130 and then move it to the desired location. A storage locker 132 may be a storage device where items for purchase are collected and placed therein for a customer and/or worker to later retrieve. In some embodiments, one or more motorized transport units 102 may be used to move the storage locker to a desired location in the shopping facility 101. Similar to how a motorized transport unit engages a movable item container 104 or item display module 130, one or more motorized transport units 102 may move (as controlled by the central computer system 106) underneath the storage locker 132, extend upward to lift the locker 132 and then move it to the desired location.

FIGS. 2A and 2B illustrate some embodiments of a motorized transport unit 202, similar to the motorized transport unit 102 shown in the system of FIG. 1. In this embodiment, the motorized transport unit 202 takes the form of a disc-shaped robotic device having motorized wheels (not shown), a lower body portion 204 and an upper body portion 206 that fits over at least part of the lower body portion 204. It is noted that in other embodiments, the motorized transport unit may have other shapes and/or configurations, and is not limited to disc-shaped. For example, the motorized transport unit may be cubic, octagonal, triangular, or other shapes, and may be dependent on a movable item container with which the motorized transport unit is intended to cooperate. Also included are guide members 208. In FIG. 2A, the motorized transport unit 202 is shown in a retracted position in which the upper body portion 206 fits over the lower body portion 204 such that the
motorized transport unit 202 is in its lowest profile orientation which is generally the preferred orientation for movement when it is unattached to a movable item container 104 for example. In FIG. 2B, the motorized transport unit 202 is shown in an extended position in which the upper body portion 206 is moved upward relative to the lower body portion 204 such that the motorized transport unit 202 is in its highest profile orientation for movement when it is lifting and attaching to a movable item container 104 for example. The mechanism within the motorized transport unit 202 is designed to provide sufficient lifting force to lift the weight of the upper body portion 206 and other objects to be lifted by the motorized transport unit 202, such as movable item containers 104 and items placed within the movable item container, item display modules 130 and items supported by the item display module, and storage lockers 132 and items placed within the storage locker. The guide members 208 are embodied as pegs or shafts that extend horizontally from the both the upper body portion 206 and the lower body portion 204. In some embodiments, these guide members 208 assist docking the motorized transport unit 202 to a docking station 122 or a dispenser 120. In some embodiments, the lower body portion 204 and the upper body portion are capable to moving independently of each other. For example, the upper body portion 206 may be raised and/or rotated relative to the lower body portion 204. That is, one or both of the upper body portion 206 and the lower body portion 204 may move toward/away from the other or rotated relative to the other. In some embodiments, in order to raise the upper body portion 206 relative to the lower body portion 204, the motorized transport unit 202 includes an internal lifting system (e.g., including one or more electric actuators or rotary drives or motors). Numerous examples of such motorized lifting and rotating systems are known in the art. Accordingly, further elaboration in these regards is not provided here for the sake of brevity.

[0041] FIGS. 3A and 3B illustrate some embodiments of the motorized transport unit 202 detachably engaging a movable item container embodied as a shopping cart 302. In FIG 3A, the motorized transport unit 202 is in the orientation of FIG. 2A such that it is retracted and able to move in position underneath a portion of the shopping cart 302. Once the motorized transport unit 202 is in position (e.g., using sensors), as illustrated in FIG. 3B, the motorized transport unit 202 is moved to the extended position of FIG. 2B such that the front portion 304 of the shopping cart is lifted off of the ground by the motorized transport unit 202, with the wheels 306 at the rear of the shopping cart 302 remaining on the ground. In this orientation, the motorized transport unit 202 is able to move the shopping cart 302
throughout the shopping facility. It is noted that in these embodiments, the motorized transport unit 202 does not bear the weight of the entire cart 302 since the rear wheels 306 rest on the floor. It is understood that in some embodiments, the motorized transport unit 202 may be configured to detachably engage other types of movable item containers, such as rocket carts, flatbed carts or other mobile baskets or platforms.

[0042] FIG. 4 presents a more detailed example of some embodiments of the motorized transport unit 102 of FIG. 1. In this example, the motorized transport unit 102 has a housing 402 that contains (partially or fully) or at least supports and carries a number of components. These components include a control unit 404 comprising a control circuit 406 that, like the control circuit 108 of the central computer system 106, controls the general operations of the motorized transport unit 102. Accordingly, the control unit 404 also includes a memory 408 coupled to the control circuit 406 and that stores, for example, operating instructions and/or useful data.

[0043] The control circuit 406 operably couples to a motorized wheel system 410. This motorized wheel system 410 functions as a locomotion system to permit the motorized transport unit 102 to move within the aforementioned retail or shopping facility 101 (thus, the motorized wheel system 410 may more generically be referred to as a locomotion system). Generally speaking, this motorized wheel system 410 will include at least one drive wheel (i.e., a wheel that rotates (around a horizontal axis) under power to thereby cause the motorized transport unit 102 to move through interaction with, for example, the floor of the shopping facility 101). The motorized wheel system 410 can include any number of rotating wheels and/or other floor-contacting mechanisms as may be desired and/or appropriate to the application setting.

[0044] The motorized wheel system 410 also includes a steering mechanism of choice. One simple example in these regards comprises one or more of the aforementioned wheels that can swivel about a vertical axis to thereby cause the moving motorized transport unit 102 to turn as well.

[0045] Numerous examples of motorized wheel systems are known in the art. Accordingly, further elaboration in these regards is not provided here for the sake of brevity save to note that the aforementioned control circuit 406 is configured to control the various
operating states of the motorized wheel system 410 to thereby control when and how the motorized wheel system 410 operates.

[0046] In this illustrative example, the control circuit 406 also operably couples to at least one wireless transceiver 412 that operates according to any known wireless protocol. This wireless transceiver 412 can comprise, for example, a Wi-Fi-compatible and/or Bluetooth-compatible transceiver that can communicate with the aforementioned central computer system 106 via the aforementioned wireless network 124 of the shopping facility 101. So configured the control circuit 406 of the motorized transport unit 102 can provide information to the central computer system 106 and can receive information and/or instructions from the central computer system 106. As one simple example in these regards, the control circuit 406 can receive instructions from the central computer system 106 regarding movement of the motorized transport unit 102.

[0047] These teachings will accommodate using any of a wide variety of wireless technologies as desired and/or as may be appropriate in a given application setting. These teachings will also accommodate employing two or more different wireless transceivers 412 if desired.

[0048] The control circuit 406 also couples to one or more on-board sensors 414. These teachings will accommodate a wide variety of sensor technologies and form factors. By one approach at least one such sensor 414 can comprise a light sensor or light receiver. When the aforementioned location detection system 116 comprises a plurality of light emitters disposed at particular locations within the shopping facility 101, such a light sensor can provide information that the control circuit 406 and/or the central computer system 106 employs to determine a present location and/or orientation of the motorized transport unit 102.

[0049] As another example, such a sensor 414 can comprise a distance measurement unit configured to detect a distance between the motorized transport unit 102 and one or more objects or surfaces around the motorized transport unit 102 (such as an object that lies in a projected path of movement for the motorized transport unit 102 through the shopping facility 101). These teachings will accommodate any of a variety of distance measurement units including optical units and sound/ultrasound units. In one example, a sensor 414 comprises a laser distance sensor device capable of determining a distance to objects in
proximity to the sensor. In some embodiments, a sensor 414 comprises an optical based
scanning device to sense and read optical patterns in proximity to the sensor, such as bar
codes variously located on structures in the shopping facility 101. In some embodiments, a
sensor 414 comprises a radio frequency identification (RFID) tag reader capable of reading
RFID tags in proximity to the sensor. Such sensors may be useful to determine proximity to
nearby objects, avoid collisions, orient the motorized transport unit at a proper alignment
orientation to engage a movable item container, and so on.

[0050] The foregoing examples are intended to be illustrative and are not intended to
convey an exhaustive listing of all possible sensors. Instead, it will be understood that these
teachings will accommodate sensing any of a wide variety of circumstances or phenomena to
support the operating functionality of the motorized transport unit 102 in a given application
setting.

[0051] By one optional approach an audio input 416 (such as a microphone) and/or an
audio output 418 (such as a speaker) can also operably couple to the control circuit 406. So
configured the control circuit 406 can provide a variety of audible sounds to thereby
communicate with a user of the motorized transport unit 102, other persons in the vicinity of
the motorized transport unit 102, or even other motorized transport units 102 in the area.
These audible sounds can include any of a variety of tones and other non-verbal sounds.
These audible sounds can also include, in lieu of the foregoing or in combination therewith,
pre-recorded or synthesized speech.

[0052] The audio input 416, in turn, provides a mechanism whereby, for example, a
user provides verbal input to the control circuit 406. That verbal input can comprise, for
example, instructions, inquiries, or information. So configured, a user can provide, for
example, a question to the motorized transport unit 102 (such as, “Where are the towels?”).
The control circuit 406 can cause that verbalized question to be transmitted to the central
computer system 106 via the motorized transport unit’s wireless transceiver 412. The central
computer system 106 can process that verbal input to recognize the speech content and to
then determine an appropriate response. That response might comprise, for example,
transmitting back to the motorized transport unit 102 specific instructions regarding how to
move the motorized transport unit 102 (via the aforementioned motorized wheel system 410)
to the location in the shopping facility 101 where the towels are displayed.
In this example the motorized transport unit 102 includes a rechargeable power source 420 such as one or more batteries. The power provided by the rechargeable power source 420 can be made available to whichever components of the motorized transport unit 102 require electrical energy. By one approach the motorized transport unit 102 includes a plug or other electrically conductive interface that the control circuit 406 can utilize to automatically connect to an external source of electrical energy to thereby recharge the rechargeable power source 420.

By one approach the motorized transport unit 102 comprises an integral part of a movable item container 104 such as a grocery cart. As used herein, this reference to "integral" will be understood to refer to a non-temporary combination and joinder that is sufficiently complete so as to consider the combined elements to be as one. Such a joinder can be facilitated in a number of ways including by securing the motorized transport unit housing 402 to the item container using bolts or other threaded fasteners as versus, for example, a clip.

These teachings will also accommodate selectively and temporarily attaching the motorized transport unit 102 to an item container 104. In such a case the motorized transport unit 102 can include a movable item container coupling structure 422. By one approach this movable item container coupling structure 422 operably couples to a control circuit 202 to thereby permit the latter to control, for example, the latched and unlatched states of the movable item container coupling structure 422. So configured, by one approach the control circuit 406 can automatically and selectively move the motorized transport unit 102 (via the motorized wheel system 410) towards a particular item container until the movable item container coupling structure 422 can engage the item container to thereby temporarily physically couple the motorized transport unit 102 to the item container. So latched, the motorized transport unit 102 can then cause the item container to move with the motorized transport unit 102. In embodiments such as illustrated in FIGS. 2A-3B, the movable item container coupling structure 422 includes a lifting system (e.g., including an electric drive or motor) to cause a portion of the body or housing 402 to engage and lift a portion of the item container off of the ground such that the motorized transport unit 102 can carry a portion of the item container. In other embodiments, the movable transport unit latches to a portion of the movable item container without lifting a portion thereof off of the ground.
In either case, by combining the motorized transport unit 102 with an item container, and by controlling movement of the motorized transport unit 102 via the aforementioned central computer system 106, these teachings will facilitate a wide variety of useful ways to assist both customers and associates in a shopping facility setting. For example, the motorized transport unit 102 can be configured to follow a particular customer as they shop within the shopping facility 101. The customer can then place items they intend to purchase into the item container that is associated with the motorized transport unit 102.

In some embodiments, the motorized transport unit 102 includes an input/output (I/O) device 424 that is coupled to the control circuit 406. The I/O device 424 allows an external device to couple to the control unit 404. The function and purpose of connecting devices will depend on the application. In some examples, devices connecting to the I/O device 424 may add functionality to the control unit 404, allow the exporting of data from the control unit 404, allow the diagnosing of the motorized transport unit 102, and so on.

In some embodiments, the motorized transport unit 102 includes a user interface 426 including for example, user inputs and/or user outputs or displays depending on the intended interaction with the user. For example, user inputs could include any input device such as buttons, knobs, switches, touch sensitive surfaces or display screens, and so on. Example user outputs include lights, display screens, and so on. The user interface 426 may work together with or separate from any user interface implemented at a user interface unit 114 (such as a smartphone or tablet device).

The control unit 404 includes a memory 408 coupled to the control circuit 406 and that stores, for example, operating instructions and/or useful data. The control circuit 406 can comprise a fixed-purpose hard-wired platform or can comprise a partially or wholly programmable platform. These architectural options are well known and understood in the art and require no further description here. This control circuit 406 is configured (for example, by using corresponding programming stored in the memory 408 as will be well understood by those skilled in the art) to carry out one or more of the steps, actions, and/or functions described herein. The memory 408 may be integral to the control circuit 406 or can be physically discrete (in whole or in part) from the control circuit 406 as desired. This memory 408 can also be local with respect to the control circuit 406 (where, for example, both share a common circuit board, chassis, power supply, and/or housing) or can be partially or wholly
remote with respect to the control circuit 406. This memory 408 can serve, for example, to non-transitorily store the computer instructions that, when executed by the control circuit 406, cause the control circuit 406 to behave as described herein. (As used herein, this reference to “non-transitorily” will be understood to refer to a non-ephemeral state for the stored contents (and hence excludes when the stored contents merely constitute signals or waves) rather than volatility of the storage media itself and hence includes both non-volatile memory (such as read-only memory (ROM) as well as volatile memory (such as an erasable programmable read-only memory (EPROM)).

[0060] It is noted that not all components illustrated in FIG. 4 are included in all embodiments of the motorized transport unit 102. That is, some components may be optional depending on the implementation.

[0061] FIG. 5 illustrates a functional block diagram that may generally represent any number of various electronic components of the system 100 that are computer type devices. The computer device 500 includes a control circuit 502, a memory 504, a user interface 506 and an input/output (I/O) interface 508 providing any type of wired and/or wireless connectivity to the computer device 500, all coupled to a communication bus 510 to allow data and signaling to pass therebetween. Generally, the control circuit 502 and the memory 504 may be referred to as a control unit. The control circuit 502, the memory 504, the user interface 506 and the I/O interface 508 may be any of the devices described herein or as understood in the art. The functionality of the computer device 500 will depend on the programming stored in the memory 504. The computer device 500 may represent a high level diagram for one or more of the central computer system 106, the motorized transport unit 102, the user interface unit 114, the location detection system 116, the user interface computer 128, the MTU docking station 122 and the MTU dispenser 120, or any other device or component in the system that is implemented as a computer device.

[0062] ADDITIONAL FEATURES OVERVIEW

[0063] Referring generally to FIGS. 1-5, the shopping assistance system 100 may implement one or more of several different features depending on the configuration of the system and its components. The following provides a brief description of several additional features that could be implemented by the system. One or more of these features could also be implemented in other systems separate from embodiments of the system. This is not
meant to be an exhaustive description of all features and not meant to be an exhaustive
description of the details any one of the features. Further details with regards to one or more
features beyond this overview may be provided herein.

[0064] Tagalong Steering: This feature allows a given motorized transport unit 102 to
lead or follow a user (e.g., a customer and/or a worker) throughout the shopping facility 101.
For example, the central computer system 106 uses the location detection system 116 to
determine the location of the motorized transport unit 102. For example, LED smart lights
(e.g., the ByteLight system) of the location detection system 116 transmit a location number
to smart devices which are with the customer (e.g., user interface units 114), and/or on the
item container 104/motorized transport unit 102. The central computer system 106 receives
the LED location numbers received by the smart devices through the wireless network 124.
Using this information, in some embodiments, the central computer system 106 uses a grid
placed upon a 2D CAD map and 3D point cloud model (e.g., from the databases 126) to
direct, track, and plot paths for the other devices. Using the grid, the motorized transport unit
102 can drive a movable item container 104 in a straight path rather than zigzagging around
the facility. As the user moves from one grid to another, the motorized transport unit 102
drives the container 104 from one grid to the other. In some embodiments, as the user moves
towards the motorized transport unit, it stays still until the customer moves beyond an
adjoining grid.

[0065] Detecting Objects: In some embodiments, motorized transport units 102 detect
objects through several sensors mounted on motorized transport unit 102, through
independent cameras (e.g., video cameras 118), through sensors of a corresponding movable
item container 104, and through communications with the central computer system 106. In
some embodiments, with semi-autonomous capabilities, the motorized transport unit 102 will
attempt to avoid obstacles, and if unable to avoid, it will notify the central computer system
106 of an exception condition. In some embodiments, using sensors 414 (such as distance
measurement units, e.g., laser or other optical-based distance measurement sensors), the
motorized transport unit 102 detects obstacles in its path, and will move to avoid, or stop until
the obstacle is clear.

[0066] Visual Remote Steering: This feature enables movement and/or operation of a
motorized transport unit 102 to be controlled by a user on-site, off-site, or anywhere in the
world. This is due to the architecture of some embodiments where the central computer
system 106 outputs the control signals to the motorized transport unit 102. These controls
signals could have originated at any device in communication with the central computer
system 106. For example, the movement signals sent to the motorized transport unit 102 may
be movement instructions determined by the central computer system 106; commands
received at a user interface unit 114 from a user; and commands received at the central
computer system 106 from a remote user not located at the shopping facility space.

[0067] Determining Location: Similar to that described above, this feature enables the
central computer system 106 to determine the location of devices in the shopping facility 101.
For example, the central computer system 106 maps received LED light transmissions,
Bluetooth low energy radio signals or audio signals (or other received signals encoded with
location data) to a 2D map of the shopping facility. Objects within the area of the shopping
facility are also mapped and associated with those transmissions. Using this information, the
central computer system 106 can determine the location of devices such as motorized
transport units.

[0068] Digital Physical Map Integration: In some embodiments, the system 100 is
capable of integrating 2D and 3D maps of the shopping facility with physical locations of
objects and workers. Once the central computer system 106 maps all objects to specific
locations using algorithms, measurements and LED geo-location, for example, grids are
applied which sections off the maps into access ways and blocked sections. Motorized
transport units 102 use these grids for navigation and recognition. In some cases, grids are
applied to 2D horizontal maps along with 3D models. In some cases, grids start at a higher
unit level and then can be broken down into smaller units of measure by the central computer
system 106 when needed to provide more accuracy.

[0069] Calling a Motorized Transport Unit: This feature provides multiple methods to
request and schedule a motorized transport unit 102 for assistance in the shopping facility. In
some embodiments, users can request use of a motorized transport unit 102 through the user
interface unit 114. The central computer system 106 can check to see if there is an available
motorized transport unit. Once assigned to a given user, other users will not be able to control
the already assigned transport unit. Workers, such as store associates, may also reserve
multiple motorized transport units in order to accomplish a coordinated large job.
Locker Delivery: In some embodiments, one or more motorized transport units 102 may be used to pick, pack, and deliver items to a particular storage locker 132. The motorized transport units 102 can couple to and move the storage locker to a desired location. In some embodiments, once delivered, the requestor will be notified that the items are ready to be picked up, and will be provided the locker location and locker security code key.

Route Optimization: In some embodiments, the central computer system automatically generates a travel route for one or more motorized transport units through the shopping facility space. In some embodiments, this route is based on one or more of a user provided list of items entered by the user via a user interface unit 114; user selected route preferences entered by the user via the user interface unit 114; user profile data received from a user information database (e.g., from one of databases 126); and product availability information from a retail inventory database (e.g., from one of databases 126). In some cases, the route intends to minimize the time it takes to get through the facility, and in some cases, may route the shopper to the least busy checkout area. Frequently, there will be multiple possible optimum routes. The route chosen may take the user by things the user is more likely to purchase (in case they forgot something), and away from things they are not likely to buy (to avoid embarrassment). That is, routing a customer through sporting goods, women’s lingerie, baby food, or feminine products, who has never purchased such products based on past customer behavior would be non-productive, and potentially embarrassing to the customer. In some cases, a route may be determined from multiple possible routes based on past shopping behavior, e.g., if the customer typically buys a cold Diet Coke product, children’s shoes or power tools, this information would be used to add weight to the best alternative routes, and determine the route accordingly.

Store Facing Features: In some embodiments, these features enable functions to support workers in performing store functions. For example, the system can assist workers to know what products and items are on the shelves and which ones need attention. For example, using 3D scanning and point cloud measurements, the central computer system can determine where products are supposed to be, enabling workers to be alerted to facing or zoning of issues along with potential inventory issues.

Phone Home: This feature allows users in a shopping facility 101 to be able to contact remote users who are not at the shopping facility 101 and include them in the shopping experience. For example, the user interface unit 114 may allow the user to place a
voice call, a video call, or send a text message. With video call capabilities, a remote person can virtually accompany an in-store shopper, visually sharing the shopping experience while seeing and talking with the shopper. One or more remote shoppers may join the experience.

[0074] Returns: In some embodiments, the central computer system 106 can task a motorized transport unit 102 to keep the returns area clear of returned merchandise. For example, the transport unit may be instructed to move a cart from the returns area to a different department or area. Such commands may be initiated from video analytics (the central computer system analyzing camera footage showing a cart full), from an associate command (digital or verbal), or on a schedule, as other priority tasks allow. The motorized transport unit 102 can first bring an empty cart to the returns area, prior to removing a full one.

[0075] Bring a Container: One or more motorized transport units can retrieve a movable item container 104 (such as a shopping cart) to use. For example, upon a customer or worker request, the motorized transport unit 102 can re-position one or more item containers 104 from one location to another. In some cases, the system instructs the motorized transport unit where to obtain an empty item container for use. For example, the system can recognize an empty and idle item container that has been abandoned or instruct that one be retrieved from a cart storage area. In some cases, the call to retrieve an item container may be initiated through a call button placed throughout the facility, or through the interface of a user interface unit 114.

[0076] Respond to Voice Commands: In some cases, control of a given motorized transport unit is implemented through the acceptance of voice commands. For example, the user may speak voice commands to the motorized transport unit 102 itself and/or to the user interface unit 114. In some embodiments, a voice print is used to authorize to use of a motorized transport unit 102 to allow voice commands from single user at a time.

[0077] Retrieve Abandoned Item Containers: This feature allows the central computer system to track movement of movable item containers in and around the area of the shopping facility 101, including both the sale floor areas and the back-room areas. For example, using visual recognition through store cameras 118 or through user interface units 114, the central computer system 106 can identify abandoned and out-of-place movable item containers. In some cases, each movable item container has a transmitter or smart device which will send a
unique identifier to facilitate tracking or other tasks and its position using LED geo-location identification. Using LED geo-location identification with the Determining Location feature through smart devices on each cart, the central computer system 106 can determine the length of time a movable item container 104 is stationary.

[0078] Stocker Assistance: This feature allows the central computer system to track movement of merchandise flow into and around the back-room areas. For example, using visual recognition and captured images, the central computer system 106 can determine if carts are loaded or not for moving merchandise between the back room areas and the sale floor areas. Tasks or alerts may be sent to workers to assign tasks.

[0079] Self-Docking: Motorized transport units 102 will run low or out of power when used. Before this happens, the motorized transport units 102 need to recharge to stay in service. According to this feature, motorized transport units 102 will self-dock and recharge (e.g., at a MTU docking station 122) to stay at maximum efficiency, when not in use. When use is completed, the motorized transport unit 102 will return to a docking station 122. In some cases, if the power is running low during use, a replacement motorized transport unit can be assigned to move into position and replace the motorized transport unit with low power. The transition from one unit to the next can be seamless to the user.

[0080] Item Container Retrieval: With this feature, the central computer system 106 can cause multiple motorized transport units 102 to retrieve abandoned item containers from exterior areas such as parking lots. For example, multiple motorized transport units are loaded into a movable dispenser, e.g., the motorized transport units are vertically stacked in the dispenser. The dispenser is moved to the exterior area and the transport units are dispensed. Based on video analytics, it is determined which item containers 104 are abandoned and for how long. A transport unit will attach to an abandoned cart and return it to a storage bay.

[0081] Motorized Transport Unit Dispenser: This feature provides the movable dispenser that contains and moves a group of motorized transport units to a given area (e.g., an exterior area such as a parking lot) to be dispensed for use. For example, motorized transport units can be moved to the parking lot to retrieve abandoned item containers 104. In some cases, the interior of the dispenser includes helically wound guide rails that mate with
the guide member 208 to allow the motorized transport units to be guided to a position to be dispensed.

[0082] Specialized Module Retrieval: This feature allows the system 100 to track movement of merchandise flow into and around the sales floor areas and the back-room areas including special modules that may be needed to move to the sales floor. For example, using video analytics, the system can determine if a modular unit it loaded or empty. Such modular units may house items that are of seasonal or temporary use on the sales floor. For example, when it is raining, it is useful to move a module unit displaying umbrellas from a back room area (or a lesser accessed area of the sales floor) to a desired area of the sales floor area.

[0083] Authentication: This feature uses a voice imprint with an attention code/word to authenticate a user to a given motorized transport unit. One motorized transport unit can be swapped for another using this authentication. For example, a token is used during the session with the user. The token is a unique identifier for the session which is dropped once the session is ended. A logical token may be a session id used by the application of the user interface unit 114 to establish the session id when user logs on and when deciding to do use the system 100. In some embodiments, communications throughout the session are encrypted using SSL or other methods at transport level.

[0084] FURTHER DETAILS OF SOME EMBODIMENTS

[0085] In accordance with some embodiments, further details are now provided for one or more of these and other features including particularly shopping facility assistance systems, devices, and methods to dispatch and recover motorized transport units that effect remote deliveries.

[0086] Generally speaking, in this particular example a plurality of motorized transport units (and to be clear, these are motorized terrestrial transport units) are loaded into a mother vehicle along with a plurality of items to be delivered to various corresponding different recipients. The mother vehicle moves to a first delivery location and a first one of the motorized transport units is dispatched to thereby effect delivery of a first one of the items to a first one of the recipients. Prior to that first dispatched motorized transport unit returning to the mother vehicle, the mother vehicle moves to a second delivery do location and dispatches a second one of the motorized transport units to carry a second one of the items to thereby effect delivery to a second one of the recipients. The mother vehicle then
subsequently recovers one or more of these dispatched motorized transport units at a recovery location.

[0087] The mother vehicle can comprise a manned vehicle or an unmanned vehicle as appropriate. The mother vehicle can transport as many of the motorized transport units as may be suitably accommodated thereby. By one approach at least some of the motorized transport units are pre-loaded with at least one item to be delivered as described above. By another approach a motorized transport unit is loaded with the item to be delivered while onboard the mother vehicle and prior to deployment.

[0088] By one approach the mother vehicle includes a wireless transceiver system that acts as a repeater to enable wireless communications between the individual motorized transport units and the aforementioned central computer system. So configured, the central computer system can provide the dispatching instructions (with or without other relevant information such as navigation information, recipient authentication information, and so forth as desired) to the motorized transport units prior to their deployment and/or during their deployment.

[0089] By one approach at least some of the items to be delivered are preloaded into corresponding lockers. These lockers are then either pre-attached to corresponding ones of the motorized transport units or attached thereto prior to deployment. So configured a deployed motorized transport unit carries such a locker to the recipient. The locker itself can be locked and configured to only be opened by a person who employs a pre-determined unlocking mechanism. So configured valuable and/or otherwise restricted or sensitive items can be reliably delivered to the appropriate recipient to the likely exclusion of any unauthorized persons.

[0090] So configured a number of motorized transport units can be deployed in a given neighborhood, apartment complex, industrial park, and so forth more or less at the same time. Such an approach can greatly reduce the overall amount of time that the mother vehicle itself must remain on task and dedicated to the delivery of a particular group of items. These approaches are highly flexible in practice and will accommodate a variety of real-time changes (such as changes with respect to deployment locations as well as recovery locations) to meet any number of real-world contingencies such as changing weather conditions, the presence of obstacles or closed pathways, and so forth.
[0091] Referring now to FIG. 6 and 7, an illustrative process 600 that accords with the foregoing will now be provided. It shall be understood that no particular limitations are intended by way of the specificity of this example.

[0092] At block 601 a plurality of motorized transport units 102 (specifically comprising, in this example, motorized terrestrial transport units 701 to make clear that this example does not encompass motorized airborne transport units) are loaded into a mother vehicle 702. Akin to a “mother ship,” this mother vehicle 702 comprises a vehicle having its own means of locomotion and directionality control and having a storage capability sufficient to retain and transport a plurality of the motorized terrestrial transport units 701.

[0093] These teachings are highly flexible in these regards and will accommodate a wide variety of form factors and designs in these regards. By one approach, for example, the motorized terrestrial transport units 701 are carried inside an enclosed or partially enclosed compartment. By another approach, the motorized terrestrial transport units 701 are carried partially or wholly exposed to the external environment during transport.

[0094] These teachings will also accommodate various ways to load and unload the motorized terrestrial transport unit 701. As one example, the mother vehicle includes a deployable ramp by which the motorized terrestrial transport units 701 can move themselves up into a storage area. By another example the mother vehicle 702 includes a crane or other lifting mechanism to thereby lift motorized terrestrial transport units 701 into the storage area. By yet another example the mother vehicle 702 includes openings within which the motorized terrestrial transport units 701 can interact to thereby lift themselves up into a storage area in the mother vehicle 702.

[0095] Generally speaking, for many application settings it will be beneficial for the mother vehicle 702 to meet all appropriate laws and regulations required to operate on a public street. Accordingly, the mother vehicle 702 can have a length, width, and height that will permit legal operation on a public street. Similarly, the mother vehicle 702 can be equipped with lights (including headlights, taillights, and brake lights) and other operating equipment as may be required by law. In the same regards the mother vehicle 702 can be registered and licensed with an appropriate state motor vehicle department to thereby permit lawful operation on public streets.
In addition to loading the motorized terrestrial transport unit 701, at block 602 a plurality of items 703 to be delivered to various corresponding different recipients are also loaded into the mother vehicle 702. By one approach these items are organized such that all items to be delivered to a single recipient are grouped together (for example, in a shared carton or box). There may or may not be a one-to-one correspondence between the number of motorized terrestrial transport units 701 and the number of deliveries to be made. These items 703 can be any of a wide variety of products including a variety of retail as well as wholesale or even customized items.

By one approach at least some of the items 703 are pre-loaded into corresponding lockers 132 as described above. Accordingly, these lockers 132 are each configured such that at least one of the motorized terrestrial transport units 701 can physically attach thereto to thereby move the locker 132. By one approach at least some of the motorized terrestrial transport units 701 are pre-attached to corresponding ones of these lockers 132, perhaps even before being loaded into the mother vehicle 702. By another approach one or more of the motorized terrestrial transport units 701 attach to corresponding ones of the lockers 132 subsequent to boarding the mother vehicle 702.

When using lockers 132, it may be expected that one or more of the items 703 are disposed within a corresponding locker 132. When a plurality of items 703 are to be delivered to a same recipient, it can be beneficial for a single locker 132 to so contain all such items 703 when physically possible.

By one approach the lockers 132 have a lockable door. In some cases items 703 may be pre-loaded into a locker 132 and locked therein before loading the lockers and items into the mother vehicle 702. In any event, such a locker 132 can have an unlocking mechanism 704 that is controlled by a corresponding control device 705. So configured, an authorized recipient who employs a pre-determined unlocking mechanism that is recognized and accepted by the control device 705 can cause the unlocking mechanism 704 to unlock and thereby permit the recipient to gain access to their items 703.

These teachings will accommodate a wide variety of approaches in these regards. As one simple example the control device 705 may include a keypad that the recipient employs to enter a predetermined numeric code. In such a case the control device 705 can be configured to detect the entry of that numeric code and determine whether that
recipient has entered an appropriate code. When true, the control device 705 can cause the unlocking mechanism 704 to unlock the locker 132 as described above.

[00101] At block 603 this process 600 provides for moving the mother vehicle 702 to a first delivery location. By one approach the central computer system 106 provides those instructions to, for example, a driver of the mother vehicle 702. This could comprise transmitting a destination to an on-board navigation unit that then calculates an appropriate route for the driver to follow. By another approach this can comprise transmitting the destination (with or without a corresponding route) to the driver via some appropriate user interface. When the mother vehicle 702 comprises an autonomous vehicle having no human driver, the central computer system 106 could transmit that destination directly to one or more navigation and/or control components of the mother vehicle 702.

[00102] The first delivery location itself can comprise, by one approach, a very specific location such as a street address or GPS coordinates. By another approach the first delivery location might simply comprise a street name, a subdivision name, a general address for multi-building campus, and so forth. If desired, the first delivery location could be even more general in nature and comprise, for example, a town, village, or city name.

[00103] When the mother vehicle 702 arrives at the first delivery location, pursuant to block 604 the process 600 provides for dispatching at least a first of the motorized terrestrial transport units 701 that carries at least a first of the items 703 to leave the mother vehicle 702 and transport the first of the items 703 to thereby effect delivery to a first of the scheduled recipients. When appropriate, this activity can include dispatching a second such motorized terrestrial transport unit 701 (or more) to similarly deliver other of the items 703 to other of the recipients.

[00104] By one approach the motorized terrestrial transport units 701 are pre-provisioned with their respective destination and/or route information. By another approach, either while en route to the first delivery location and/or upon being dispatched as described above, the central computer system 106 can provide such information to the motorized terrestrial transport units 701. When the mother vehicle 702 includes a wireless communications unit 706 that can communicate with the central computer system 106 via an intervening communications interface 707 (such as the aforementioned network interface 112) and also with onboard wireless transceivers 412 as comprise a part of each of the
motorized terrestrial transport units 701 (such that each of the motorized terrestrial transport units 701 can communicate separately with the central computer system 106 via that wireless communications unit 706 that acts as a repeater), and presuming a sufficient coverage range, the central computer system 106 can remain at least occasionally in contact with the motorized terrestrial transport units 701 even after the latter have been deployed and are in the process of carrying their respective items 703 to their respective recipients. In that case the central computer system 106 can continue to provide guidance information to the motorized terrestrial transport units 701 as they carry out their delivery tasks.

[00105] After having deployed this one or more motorized terrestrial transport units 701 at the first delivery location, and prior to any of those first deployed motorized terrestrial transport units 701 returning to the mother vehicle 702, at block 605 this process 600 provides for moving the mother vehicle 702 to a second delivery location that is different than the first delivery location. The distance between the first and second delivery locations can vary in accordance with the needs and/or circumstances of a given application setting. When the first delivery location comprises a first apartment complex, the second delivery location could comprise a second apartment complex that is, for example, within half a mile of the first apartment complex. When the first delivery location comprises a neighborhood street having a single-family homes located along that neighborhood street, the second delivery location could comprise another neighborhood street of single-family homes in that same neighborhood (for example, one or two blocks over from that first neighborhood street). Many other possibilities can be accommodated as well.

[00106] The mother vehicle 702 then dispatches at least a second of the motorized terrestrial transport units 701 that again carry at least a second of the items 703 to thereby leave the mother vehicle 702 and transport the second of the items 703 to thereby effect delivery to a second of the recipients. As before, this process 600 will accommodate so dispatching a plurality of motorized terrestrial transport units 701 at this second delivery location as appropriate to the needs of the present delivery assignment.

[00107] The illustrated process 600 only illustrates dispatching motorized terrestrial transport units 701 at either of two delivery locations for the sake of simplicity and clarity. If desired, this process 600 will readily accommodate stopping at any number of other delivery locations if and as needed.
At block 606 the mother vehicle 702 recovers at least the first of the motorized terrestrial transport units 701 at a first recovery location. This can comprise, for example, recovering a motorized terrestrial transport unit 701 in combination with its corresponding locker 132 after the motorized terrestrial transport unit 701 has effected delivery of its items 703 to its intended recipient. As before, and as desired, the central computer system 106 can serve to guide the motorized terrestrial transport unit 701 to that first recovery location.

These teachings are quite flexible in terms of accommodating a variety of different recovery locations. By one simple approach each motorized terrestrial transport unit 701 simply retraces its route to return to its respective aforementioned delivery location. In that case each delivery location serves as well as a recovery location. These teachings will readily accommodate other approaches in these regards, however. As one example in these regards, the mother vehicle 702 may drive down a street and stop at three different locations to deploy motorized terrestrial transport units 701 as described above. Notwithstanding that these motorized terrestrial transport units 701 were dropped off at three different locations, these teachings will readily accommodate having each of these motorized terrestrial transport units 701 return to a same recovery location (for example, at the end of the aforementioned street).

So configured, items can be delivered to any of a variety of customer-friendly locations in an efficient, safe, and secure manner.

Those skilled in the art will recognize that a wide variety of modifications, alterations, and combinations can be made with respect to the above described embodiments without departing from the scope of the invention, and that such modifications, alterations, and combinations are to be viewed as being within the ambit of the inventive concept.
What is claimed is:

1. A method comprising:
   loading a plurality of motorized terrestrial transport units into a mother vehicle;
   loading into the mother vehicle a plurality of items to be delivered to various corresponding different recipients;
   moving the mother vehicle to a first delivery location;
   dispatching a first of the motorized terrestrial transport units carrying at least a first of the items to leave the mother vehicle and transport the first of the items to effect delivery to a first of the recipients;
   prior to the first of the motorized terrestrial transport units returning to the mother vehicle, moving the mother vehicle to a second delivery location and dispatching a second of the motorized terrestrial transport units carrying at least a second of the items to leave the mother vehicle and transport the second of the items to effect delivery to a second of the recipients;
   recovering at least the first of the motorized terrestrial transport units at a first recovery location into the mother vehicle.

2. The method of claim 1 wherein at least some of the items to be delivered are pre-loaded into corresponding lockers.

3. The method of claim 2 wherein at least some of the lockers are pre-attached to corresponding ones of the plurality of motorized terrestrial transport units.

4. The method of claim 2 wherein the motorized terrestrial transport unit returns to the mother vehicle with its corresponding locker after effecting delivery of the item to the recipient.

5. The method of claim 2 wherein at least some of the lockers are locked and configured only to be opened by a person employing a pre-determined unlocking mechanism.
6. The method of claim 1 wherein the mother vehicle comprises one of a manned vehicle and an unmanned vehicle.

7. The method of claim 1 wherein the dispatching of both the first and the second motorized terrestrial transport units comprises using a central computer system to dispatch both the first and the second motorized terrestrial transport units.

8. The method of claim 7 wherein using a central computer system to dispatch both the first and the second motorized terrestrial transport units comprises using a central computer system that is not on-board the mother vehicle.

9. The method of claim 8 wherein the recovering of at least the first of the motorized terrestrial transport units comprises using the central computer system to at least assist guide the first of the motorized terrestrial transport units to the first recovery location.

10. An apparatus comprising:
    a mother vehicle;
    a plurality of motorized terrestrial transport units carried by the mother vehicle;
    a plurality of items carried by the mother vehicle to be delivered to various corresponding different recipients;
    a communications link to a central computer system wherein the central computer system is configured to:
    dispatch a first of the motorized terrestrial transport units carrying at least a first of the items to leave the mother vehicle and transport the first of the items to effect delivery to a first of the recipients;
    prior to the first of the motorized terrestrial transport units returning to the mother vehicle, and after moving the mother vehicle to a second delivery location, dispatch a second of the motorized terrestrial transport units carrying at least a second of the items to leave the mother vehicle and transport the second of the items to effect delivery to a second of the recipients;
recover at least the first of the motorized terrestrial transport units at a first recovery location into the mother vehicle.

11. The apparatus of claim 10 wherein at least some of the items to be delivered are pre-loaded into corresponding lockers.

12. The apparatus of claim 11 wherein at least some of the lockers are pre-attached to corresponding ones of the plurality of motorized terrestrial transport units.

13. The apparatus of claim 11 wherein the motorized terrestrial transport unit is configured to return to the mother vehicle with its corresponding locker after effecting delivery of the item to the recipient.

14. The apparatus of claim 11 wherein at least some of the lockers are locked and configured only to be opened by a person employing a pre-determined unlocking mechanism.

15. The apparatus of claim 10 wherein the mother vehicle comprises one of a manned vehicle and an unmanned vehicle.

16. The apparatus of claim 10 wherein the central computer system is not on-board the mother vehicle.

17. The apparatus of claim 10 wherein the communications link includes a wireless transceiver that is on-board each of the motorized terrestrial transport units such that each of the motorized terrestrial transport units communicates separately with the central computer system.

18. The apparatus of claim 10 wherein the communication link includes:
   a first wireless transceiver that is on-board the mother vehicle that communicates with the central computer system; and
   a second wireless transceiver that is on-board the mother vehicle that communicates with a wireless transceiver that is on-board each of the motorized terrestrial transport units;
such that the motorized terrestrial transport units communicate with the central computer system via the mother vehicle’s first wireless transceiver.
**Patents Act 1977: Search Report under Section 17**

**Documents considered to be relevant:**

<table>
<thead>
<tr>
<th>Category</th>
<th>Relevant to claims</th>
<th>Identity of document and passage or figure of particular relevance</th>
</tr>
</thead>
<tbody>
<tr>
<td>Y</td>
<td>1-18</td>
<td>US 2014/0081445 A1 (VILLAMAR) See figures 1, 4 and 10, and paragraphs [0032], [0041] and [0075] in particular.</td>
</tr>
<tr>
<td>X</td>
<td>1, 6-10 and 15-18</td>
<td>US 8511606 B1 (LUTKE at al.) See figures 1, 7 and 15 and column 1, lines 26-29, column 4 lines 53-58, column 5 lines 16-17, column 7 lines 1-15 and column 11 line 66 - column 12 line 2 in particular.</td>
</tr>
<tr>
<td>A</td>
<td>-</td>
<td>GB 2530626 A (CARRICONDE) See whole document.</td>
</tr>
</tbody>
</table>

**Categories:**

<table>
<thead>
<tr>
<th>X</th>
<th>Document indicating lack of novelty or inventive step</th>
</tr>
</thead>
<tbody>
<tr>
<td>Y</td>
<td>Document indicating lack of inventive step if combined with one or more other documents of same category. &amp; Member of the same patent family</td>
</tr>
<tr>
<td>A</td>
<td>Document indicating technological background and/or state of the art.</td>
</tr>
<tr>
<td>P</td>
<td>Document published on or after the declared priority date but before the filing date of this invention.</td>
</tr>
<tr>
<td>E</td>
<td>Patent document published on or after, but with priority date earlier than, the filing date of this application.</td>
</tr>
</tbody>
</table>

**Field of Search:**

Search of GB, EP, WO & US patent documents classified in the following areas of the UKC:

- Worldwide search of patent documents classified in the following areas of the IPC:
  - B60P; B64D; G05D; G06Q
The following online and other databases have been used in the preparation of this search report

| WPI, EPODOC, INTERNET |

**International Classification:**

<table>
<thead>
<tr>
<th>Subclass</th>
<th>Subgroup</th>
<th>Valid From</th>
</tr>
</thead>
<tbody>
<tr>
<td>G05D</td>
<td>0001/02</td>
<td>01/01/2006</td>
</tr>
<tr>
<td>B60P</td>
<td>0003/06</td>
<td>01/01/2006</td>
</tr>
<tr>
<td>G06Q</td>
<td>0010/08</td>
<td>01/01/2012</td>
</tr>
</tbody>
</table>