

Cross-Reference to Related Applications

[0001] [None].

Field of the Disclosure

[0002] The present disclosure relates generally to drilling rigs, and specifically to telescoping rig structures for land drilling in the petroleum exploration and production industry.

Background of the Disclosure

[0003] Land-based drilling rigs may be configured to be moved from location to location to drill multiple wells within the same area known as a wellsite. In certain situations, movement across an already drilled well for which there is a well-head in place may be desirable. Further, mast placement on land-drilling rigs may have an effect on drilling activity. For example, depending on mast placement on the drilling rig, an existing well-head may interfere with the location of land-situated equipment such as, for instance, existing wellheads, and may also interfere with raising and lowering of equipment for operations.

US 5921336 A disclose a walking substructure device having a drilling rig substructure. A plurality of lifting jacks is provided, each lifting jack having an upper end and a lower end, the upper end connected to the drilling rig substructure. A plurality of roller assemblies is provided, each roller assembly connected to the lower end of one of the jacks, each roller assembly pivotal radially about an axis of the lifting jack. A plurality of jack pads is provided, with each jack pad having a center beam wherein one of the roller assemblies engages the center beam and rolls thereon. A push-pull mechanism extends between each jack pad and each roller assembly in order to move the shoe assemblies in relation to the drilling substructure.

Summary

[0004] The present disclosure provides for a land-based drill rig as disclosed in claim 1

[0005] The present disclosure provides for methods as disclosed in claim 8 and 17

Brief Description of the Drawings

[0006] The summary and the detailed description are further understood when read in conjunction with the appended drawings. For the purpose of illustrating the present disclosure, there are shown in the drawings exemplary embodiments of said disclosure; however, the disclosure is not limited to the specific methods, compositions, and devices disclosed. In addition, the drawings are not necessarily drawn to scale. In the drawings:

[0007] FIG. 1 is a perspective view of a land-based drilling rig in a raised position consistent with at least one embodiment of the present disclosure.

[0008] FIG. 2 is a side view of a land-based drilling rig in a raised position consistent with at least one embodiment of the present disclosure.

[0009] FIG. 3 is a perspective view of a land-based drilling rig in a raised position consistent with at least one embodiment of the present disclosure.

[0010] FIG. 4 is a side elevation of a drilling rig consistent in a lowered position consistent with at least one embodiment of the present disclosure.

[0011] FIGs. 5A - 5D are side schematic views of a walking land-based drilling rig consistent with at least one embodiment of the present disclosure.

[0012] FIG. 6 is a perspective view of a land-based drilling rig in a raised position consistent with at least one embodiment of the present disclosure.

Detailed Description

[0013] The present disclosure may be understood more readily by reference to the following detailed description, taken in connection with the accompanying figures, which form a part of this disclosure. It is to be understood that this disclosure is not limited to the specific devices, methods, applications, conditions or parameters described and/or shown herein, and that the terminology used herein is for the purpose of describing particular embodiments by way of example only and is not intended to be limiting of the present disclosure. Also, as used in the specification, including the appended claims, the singular forms “a,” “an,” and “the” include the plural, and reference to a particular numerical value includes at least that particular value, unless the context clearly dictates otherwise. The term “plurality,” as used herein, means more than one.

[0014] FIGs. 1 and 6 are perspective views of different embodiments of land-based drilling rig 10 in a raised position. Land-based drilling rig 10 may include drill rig floor 30. Drill rig floor 30 is defined by V-door side 58, having V-door or opening 60 positioned thereon. V-door side 58 of drill rig floor 30 is adjacent slide 25 and catwalk 20. Drill rig floor 30 includes driller's side 152, on which driller's cabin 154 is positioned or cantilevered from.

[0015] Choke house 180 may be positioned on or cantilevered to drill rig floor 30. In certain embodiments, choke house 180 may be positioned on choke house skid 182. Choke house 180 may include choke manifold 184. A drawworks may be positioned on drill rig floor 30, a drawworks skid, or choke house skid 182.

[0016] In some embodiments, additional equipment including, for example and without limitation, mud tanks, trip tanks, process tanks, mud process equipment, compressors, variable

frequency drives, or drill line spoolers, may be coupled to land-based drilling rig 10, such as positioned on or cantilevered from drill rig floor 30.

[0017] Drill rig floor 30 may be supported by a plurality of telescoping support arms 50. Each telescoping support arm 50 may be mechanically connected to a respective support base 62 forming support 65. In certain embodiments, support bases 62 may be square. In other embodiments, support bases 62 may be cylindrical.

[0018] As shown in the embodiment of FIG. 1, at least three supports 65 may be arranged along V-door side edge 70 forming V-door support row 66 and at least three supports 65 may be arranged opposite V-door side edge 80 of drill rig floor 30 forming opposite V-door support row 68. Thus, V-door side 58 is parallel to V-door support row 66 and opposite V-door support row 68.

[0019] In the embodiment shown in FIG. 6, land-based drilling rig 10 has only four supports 65. Each of the four supports 65 may be located at or near a corner of drill rig floor 30. In this embodiment, V-door 60 may be positioned between at least two of supports 65 on drill rig floor 30. As exemplified by FIG. 6, supports 65 are positioned such that distance A, A' (wherein distance A is the distance between supports 65 positioned on V-door side 58 of land-based drilling rig 10 and A' is the distance between supports 65 positioned on the driller's side or off-drillers side) between any supports 65 is sufficient to allow wellhead 130 to pass between supports 65 when land-based drilling rig 10 is moved within the wellsite. Distances A, A' may be the same or different.

[0020] As shown in FIG. 3, each telescoping support arm 50 may include hydraulic cylinder 52 for raising and lowering drill rig floor 30 using telescoping support arm 50 from a lowered position, as shown in FIG. 4 to an upright position as shown in FIGs. 1-3.

[0021] With further attention to FIG. 1, mast 90 may be fixedly or pivotably coupled to drill rig floor 30. Mast 90 may include mast V-door side 92, which faces V-door side 58. Mast V-door side 92 is an open side of mast 90. Equipment positioned within mast 90 may include travelling block 94. Crown block 96 may be positioned on top of mast 90 and pipe rack 98 mechanically attached to mast 90.

[0022] Land-based drilling rig 10 is shown in FIG. 1 positioned within wellsite 100 having wells 110 arranged in row 120. Land-based drilling rig 10 may be moved, such as by walking or skidding to different wells 110 in row 120 without breaking down land-based drilling rig 10. V-door support row 66 and opposite V-door support row 68 are spaced apart such that, as shown in FIGs. 1-4, when traveling, wells 110 may pass between V-door support row 66 and opposite V-door support row 68. As shown in FIGs. 1-3, when in the raised position, drill rig floor 30 is positioned using telescoping support arms 50 such that wellhead 130 may pass thereunder.

[0023] In some embodiments, as depicted in the figures, land-based drilling rig 10 may include one or more hydraulic walkers 140. Hydraulic walkers 140 may, in some embodiments, be positioned within one or more support bases 62. In some embodiments, hydraulic walkers 140 may be hydraulically actuatable to move or walk land-based drilling rig 10 to a different location in the wellsite. In some embodiments, hydraulic walkers 140 may be operable to move or walk land-based drilling rig 10 in any direction.

[0024] A non-limiting embodiment of a hydraulic walker for use with land-based drilling rig 10 is shown in FIGs. 5A – 5D. Hydraulic walkers 140 may include walking foot 105 and hydraulic lift assembly 107 as depicted in FIG. 5A. Walking foot 105 may be a pad or any other structure configured to support the weight of land-based drilling rig 10 and associated equipment during a walking operation as discussed herein below. Hydraulic lift assembly 107 may include one or more hydraulic cylinders 108 positioned to move hydraulic walker 140 between a retracted position, as depicted in FIG. 5A, and an extended position, as depicted in FIG. 5B. Hydraulic lift assembly 107 may be mechanically coupled to column 40 by mounting structure 111. Mounting structure 111 may include any mechanical fasteners, plates, or other adapters to couple between hydraulic lift assembly 107 and column 40. In some embodiments, mounting structure 111 may be an outrigger structure. In a walking operation, depicted in FIGs. 5A-5D, hydraulic walkers 140 may be positionable in a retracted position as shown in FIG. 5A. In the retracted position, column 40 may be in contact with the ground 115, allowing the weight of land-based drilling rig 10 to be supported by column 40. When hydraulic walker 140 is in the extended position, as depicted in FIG. 5B, walking foot 105 may support column 40 above ground 115.

[0025] Once hydraulic walker 140 is in the extended position, sliding actuator 109 may be actuated to move walking foot 105 laterally relative to hydraulic lift assembly 107 from a first position to a second position as depicted in FIG. 5C. In some embodiments, one or more bearing surfaces, linear bearings, ball bearings, or roller bearings may be positioned between walking foot 105 and hydraulic lift assembly 107 as understood in the art to, for example and without limitation, bear the weight of land-based drilling rig 10 and any equipment thereon during a walking operation. Sliding actuator 109 may include one or more hydraulic cylinders or other linear actuators 114 used to move walking foot 105 horizontally relative to drilling rig 10. For

example, when walking foot 105 is in contact with ground 115 as depicted in FIG. 5B, the movement of walking foot 105 by sliding actuator 109 may cause land-based drilling rig 10 to move along ground 115 to a position as shown in FIG. 5C. Hydraulic lift assembly 107 may retract, lifting walking foot 105 from ground 115 and allowing land-based drilling rig 10 to contact the ground 115 as depicted in FIG. 5D. Sliding actuator 109 may be reactuated with walking foot 105 off ground 115 to cause walking foot 105 to be returned to its original position, resetting hydraulic walkers 140 to the first position as depicted in FIG. 5A.

Claims

1. A land-based drilling rig (10) comprising:

a drill rig floor (30), the drill rig floor (30) including a V-door (60), a side of the drill rig floor (30) having the V-door (60) defining a V-door side (58) of the drill rig floor (30) and an opposite V-door side of the drill rig floor (30) opposite the V-door side (58) of the drill rig floor (30);

a mast (90), the mast (90) mechanically coupled to the drill rig floor (30);

characterized in that the land-based drilling rig (10) further comprises

at least four support bases (62), each support base (62) coupled to the drill rig floor (30) by a telescoping support arm (50), the support base (62) and telescoping arm (50) forming a support (65), wherein the support bases (62) are polyhedrons having a square base or are cylindrical, wherein the weight of the land-based drilling rig (10) is born by the at least four support bases (62) when the land-based drilling rig (10) is stationary; and

at least one hydraulic walker (140), the at least one hydraulic walker (140) positioned within a support base (62).

2. The land-based drilling rig (10) of claim 1, wherein the mast (90) includes a V-door side (92), the V-door side (92) of the mast facing the V-door side (58) of the drill rig floor (30), wherein the V-door side (92) of the mast (90) is an open side.

3. The land-based drilling rig (10) of claim 1, wherein the V-door (60) is positioned between at least two supports (65).

4. The land-based drilling rig (10) of claim 3, wherein each of the supports (65) is positioned at or near edges (80) of the drill rig floor (30).
5. The land-based drilling rig (10) of claim 3, wherein the distance between two adjacent supports (65) is A and the distance between two other adjacent supports (65) is A', wherein A and A' are greater than the diameter of a wellhead (130).
6. The land-based drilling rig (10) of claim 1, further comprising one or more of drill line spooler, hydraulic power unit, compressor, variable frequency drive, mud process equipment, choke manifold (184), accumulator, mud gas separator, process tank, or trip tank positioned on or cantilevered from the drill rig floor (30).
7. The land-based drilling rig (10) of claim 1 further comprising a choke manifold (184), the choke manifold (184) positioned on an off-driller's side of the drill rig floor (30).
8. A method for placement of land-drilling telescoping rigs (10) and movement of said rigs (10) across an already drilled well (110) for which there is a well-head (130) in place comprising:

supplying a land-based drilling rig (10), the land-based drilling rig (10) comprising:

a drill rig floor (30), the drill rig floor (30) including a V-door (60), a side of the drill rig floor (30) having the V-door (60) defining a V-door side (58) of the drill rig floor (30) and an opposite V-door side of the drill rig floor (30) opposite the V-door side (58) of the drill rig floor (30), the drill rig floor (30) in a lowered position; and

a mast (90), the mast (90) mechanically coupled to the drill rig floor (30);

positioning the land-based drilling rig (10) within a wellsite (100), the wellsite (100) having at least one row of wells (120), at least one well (110) having a wellhead (130);

characterized by the land-based drilling rig further comprising:

at least four support bases (62), each support base (62) coupled to the drill rig floor (30) by a telescoping support arm (50), the support base (62) and telescoping arm (50) forming a support (65), wherein the support bases (62) are polyhedrons having a square base or are cylindrical, wherein the weight of the land-based drilling rig (10) is borne by the at least four support bases (62) when the land-based drilling rig (10) is stationary; and

at least one hydraulic walker (140), the at least one walker (140) positioned within a support base (62);

raising the drill rig floor (30) from the lowered position to a raised position using the telescoping support arms (50); and

moving the land-based drilling rig (10) over the wellhead (130) using the at least one hydraulic walker (140).

9. The method of claim 8, wherein the step of moving the land-based drilling rig comprises:

actuating the at least one hydraulic walker (140); and

walking the land-based drilling rig (10).

10. The method of claim 9, wherein the hydraulic walker comprises:
 - a walking foot (105);
 - a hydraulic lift assembly (107) including a hydraulic cylinder (108) coupled to the walking foot (105); and
 - a sliding actuator (109) including one or more hydraulic cylinders (114) coupled to the walking foot (105).
11. The method of claim 10, wherein the step of walking the land-based drilling rig further comprises:
 - positioning the land-based drilling rig (10) at a first position in a wellsite (100);
 - extending the hydraulic lifts (107) of the hydraulic walker (105);
 - lifting the land-based drilling rig (10) off the ground;
 - actuating the sliding actuators (109) to move the walking feet (105) from a first position to a second position;
 - moving the land-based drilling rig (10) in a first direction;
 - retracting the hydraulic lifts (107);
 - placing the land-based drilling rig (10) on the ground; and
 - actuating the sliding actuators (109) to return the walking feet (105) to the first position.
12. The method of claim 11 further comprising:

rotating the hydraulic walkers (105);

repeating the extending, lifting, actuating, retracting, and reactuating operations; and

moving the land-based drilling rig (10) in a second direction.

13. The method of claim 11, further comprising:

repeating the extending, lifting, actuating, retracting, and reactuating operations until the land-based drilling rig (10) is at a desired second position in the wellsite (100).

14. A method for placement of land-drilling telescoping rigs (10) and movement of said rigs (10) across an already drilled well (110) for which there is a wellhead (130) in place comprising:

supplying a land-based drilling rig (10), the land-based drilling rig (10) comprising:

a drill rig floor (30), the drill rig floor (30) including a V-door (60), a side of the drill rig floor (30) having the V-door (60) defining a V-door side (58) of the drill rig floor (30) and an opposite V-door side of the drill rig floor (30) opposite the V-door side (58) of the drill rig floor (30), the drill rig floor (30) in a lowered position; and

a mast (90), the mast (90) mechanically coupled to the drill rig floor (30);

positioning the land-based drilling rig (10) within a wellsite (100), the wellsite (100) having at least one row of wells (110), at least one well (110) having a wellhead (130);

characterized by the land-based drilling rig (10) further comprising:

at least four support bases (62), each support base (62) coupled to the drill rig floor (30) by a telescoping support arm (50), the support base (62) and telescoping arm (50) forming a

support (65), wherein the support bases (62) are polyhedrons having a square base or are cylindrical;

wherein the support bases (62) are arranged in a V-door support row (66) and an opposite V-door support row (68), each row of support bases (62) having at least three support bases (62), the V-door support row (66) arranged along the V-door side (58) of the drill rig floor (30) and the opposite V-door support row arranged opposite (68) the V-door side of the drill rig floor (30) or

wherein the V-door (60) is positioned between at least two supports (65), each of the supports (65) is positioned at or near edges (80) of the drill rig floor (30), and an opening distance between two adjacent supports (65) is A and an opening distance between two other adjacent supports (65) is A', wherein A and A' are greater than the diameter of a wellhead (130); and

raising the drill rig floor (30) from the lowered position to a raised position using the telescoping support arms (50); and moving the land-based drilling rig (10) over the wellhead (130).

15. The method of claim 14, wherein the land-based drilling rig further comprises at least one walker (140), the at least one walker (140) positioned within a support base (62).

16. The method of claim 15, wherein the step of moving the land-based drilling rig comprises: actuating the at least one walker (140); and walking the land-based drilling rig (10).

17. The method of claim 16, wherein the hydraulic walker (140) comprises:

a walking foot (105);

a hydraulic lift assembly (107) including a hydraulic cylinder (108) coupled to the walking foot (105); and

a sliding actuator (109) including one or more hydraulic cylinders (114) coupled to the walking foot (105).

18. The method of claim 17, wherein the step of walking the land-based drilling rig (10) further comprises:

positioning the land-based drilling rig (10) at a first position in a wellsite (100);

extending the hydraulic lifts (107) of the hydraulic walker (140);

lifting the land-based drilling rig (10) off the ground;

actuating the sliding actuators (109) to move the walking feet (105) from a first position to a second position;

moving the land-based drilling rig (10) in a first direction;

retracting the hydraulic lifts (107);

placing the land-based drilling rig (10) on the ground; and

actuating the sliding actuators (109) to return the walking feet (105) to the first position.

19. The method of claim 18 further comprising:

rotating the hydraulic walkers (105);

repeating the extending, lifting, actuating, retracting, and reactuating operations; and

moving the land-based drilling rig (10) in a second direction.

20. The method of claim 19, further comprising:

repeating the extending, lifting, actuating, retracting, and reactuating operations until the land-based drilling rig (10) is at a desired second position in the wellsite.

Krav

1. Landbasert borerigg (10), omfattende:
borerigg-gulv (30), borerigg-gulvet (30) inkluderer en V-dør (60), en side av borerigg-gulvet (30) som har V-døren (60) som definerer en V-dørside (58) av borerigg-gulvet (30) og en motstående V-dørside av borerigg-gulvet (30) motstående V-dørsiden (58) av borerigg-gulvet (30);
mast (90), masten (90) mekanisk koblet til borerigg-gulvet (30);
karakterisert ved at den landbaserte boreriggen (10) videre omfatter
minst fire støtteunderlag (62), hvert støtteunderlag (62) koblet til borerigg-gulvet (30) via en teleskopisk støttearm (50), støtteunderlaget (62) og den teleskopiske armen (50) danner en støtte (65), hvori støtteunderlagene (62) er polyedre som har et firkantet underlag eller er sylindriske, hvori vekten av den landbaserte boreriggen (10) bæres av de minst fire støtteunderlagene (62) når den landbaserte boreriggen (10) er stasjonær; og
minst én hydraulisk vandrer («hydraulic walker») (140), den minst ene hydrauliske vandreren (140) posisjonert innenfor et støtteunderlag (62).
2. Den landbaserte boreriggen (10) ifølge krav 1, hvori masten (90) inkluderer en V-dørside (92), V-dørsiden (92) av masten er vendt mot V-dørsiden (58) av borerigg-gulvet (30), hvori V-dørsiden (92) av masten (90) er en åpen side.
3. Den landbaserte boreriggen (10) ifølge krav 1, hvori V-døren (60) er posisjonert mellom minst to støtter (65).
4. Den landbaserte boreriggen (10) ifølge krav 3, hvori hver av støttene (65) er posisjonert på eller nær kantene (80) av borerigg-gulvet (30).
5. Den landbaserte boreriggen (10) ifølge krav 3, hvori avstanden mellom to tilstøtende støtter (65) er A og avstanden mellom to andre tilstøtende støtter (65) er A', hvori A og A' er større enn diameteren til et brønnhode (130).

6. Den landbaserte boreriggen (10) ifølge krav 1, videre omfattende én eller flere av boreledningsspolemaskin, hydraulisk kraftenhet, kompressor, variabel frekvens-drivverk, slamprosessutstyr, strupemanifold (184), akkumulator, slamgass-separator, prosesstank eller etterfyllingstank posisjonert på eller utkraget fra borerigg-gulvet (30).
7. Den landbaserte boreriggen (10) ifølge krav 1, videre omfattende en strupemanifold (184), strupemanifolden (184) posisjonert på en side av borerigg-gulvet (30) der man ikke borer.
8. Fremgangsmåte for å plassere landborende teleskopiske rigger (10) og bevege riggene (10) over en allerede boret brønn (110) for hvilken det er et brønnhode (130) på plass, omfattende:
tilføre en landbasert borerigg (10), den landbaserte boreriggen (10) omfattende:
borerigg-gulv (30), borerigg-gulvet (30) inkluderer en V-dør (60), en side av borerigg-gulvet (30) som har V-døren (60) som definerer en V-dørside (58) av borerigg-gulvet (30) og en motstående V-dørside av borerigg-gulvet (30) motstående V-dørsiden (58) av borerigg-gulvet (30), borerigg-gulvet (30), i en senket posisjon; og
mast (90), masten (90) mekanisk koblet til borerigg-gulvet (30);
posisjonere den landbaserte boreriggen (10) innenfor et brønnområde (100),
brønnområdet (100) har minst én rad av brønner (120), minst én brønn (110) som har et brønnhode (130);
karakterisert ved at den landbaserte boreriggen videre omfatter:
minst fire støtteunderlag (62), hvert støtteunderlag (62) koblet til borerigg-gulvet (30) via en teleskopisk støttearm (50), støtteunderlaget (62) og den teleskopiske armen (50) danner en støtte (65), hvori støtteunderlagene (62) er polyedrer som har et firkantet underlag eller er sylindriske, hvori vekten av den landbaserte boreriggen (10) bæres av de minst fire støtteunderlagene (62) når den landbaserte boreriggen (10) er stasjonær; og
minst én hydraulisk vandrer (140), den minst ene vandreren (140) posisjonert innenfor et støtteunderlag (62);

heve borerigg-gulvet (30) fra den senkede stillingen til en hevet stilling ved hjelp av de teleskopiske støttearmene (50); og
bevege den landbaserte boreriggen (10) over brønnhodet (130) ved hjelp av den minst ene hydrauliske vandrer (140).

9. Fremgangsmåten ifølge krav 8, hvori trinnet med å bevege den landbaserte boreriggen omfatter:
aktuere den minst ene hydrauliske vandrer (140); og
vandre den landbaserte boreriggen (10).
10. Fremgangsmåten ifølge krav 9, hvori den hydrauliske vandrer omfatter:
vandrende fot (105);
hydraulisk løft-montasje (107) som inkluderer en hydraulisk sylinder (108) koblet til den vandrende foten (105); og
glidende aktuator (109) som inkluderer én eller flere hydrauliske sylindere (114) koblet til den vandrende foten (105).
11. Fremgangsmåten ifølge krav 10, hvori trinnet med å vandre den landbaserte boreriggen videre omfatter:
posisjonere den landbaserte boreriggen (10) i en første posisjon i et brønnområde (100);
forlenge de hydrauliske løftene (107) til den hydrauliske vandrer (105);
løfte den landbaserte boreriggen (10) fra bakken;
aktuere de glidende aktuatorer (109) til å bevege de vandrende føttene (105) fra en første posisjon til en andre posisjon;
bevege den landbaserte boreriggen (10) i en første retning;
trekke tilbake de hydrauliske løftene (107);
plassere den landbaserte boreriggen (10) på bakken; og
aktuere de glidende aktuatorer (109) til å returnere de vandrende føttene (105) til den første posisjonen.
12. Fremgangsmåten ifølge krav 11, videre omfattende:

rotare de hydrauliske vandrerne (105);

gjenta forlengelses-, løfte-, aktuerings-, tilbaketrekking- og reaktueringsoperasjonene; og bevege den landbaserte boreriggen (10) i en andre retning.

13. Fremgangsmåten ifølge krav 11, videre omfattende:

gjenta forlengelses-, løfte-, aktuerings-, tilbaketrekking- og reaktueringsoperasjonene inntil den landbaserte boreriggen (10) er i en ønsket andre posisjon i brønnområdet (100).

14. Fremgangsmåte for å plassere landborende teleskopiske rigger (10) og bevegelse av riggene (10) over en allerede boret brønn (110) for hvilken det er et brønnhode (130) på plass, omfattende:

tilveiebringe en landbasert borerigg (10), den landbaserte boreriggen (10), omfattende: borerigg-gulv (30), borerigg-gulvet (30) inkluderer en V-dør (60), en side av borerigg-gulvet (30) som har V-døren (60) som definerer en V-dørside (58) av borerigg-gulvet (30) og en motstående V-dørside av borerigg-gulvet (30) motstående V-dørsiden (58) av borerigg-gulvet (30), borerigg-gulvet (30), i en senket posisjon; og mast (90), masten (90) mekanisk koblet til borerigg-gulvet (30); posisjonere den landbaserte boreriggen (10) innenfor et brønnområde (100), brønnområdet (100) har minst én rad av brønner (110), minst én brønn (110) som har et brønnhode (130);

karakterisert ved at den landbaserte boreriggen (10) videre omfatter:

minst fire støtteunderlag (62), hvert støtteunderlag (62) koblet til borerigg-gulvet (30) via en teleskopisk støttearm (50), støtteunderlaget (62) og den teleskopiske armen (50) danner en støtte (65), hvori støtteunderlagene (62) er polyedrer som har et firkantet underlag eller er sylindriske;

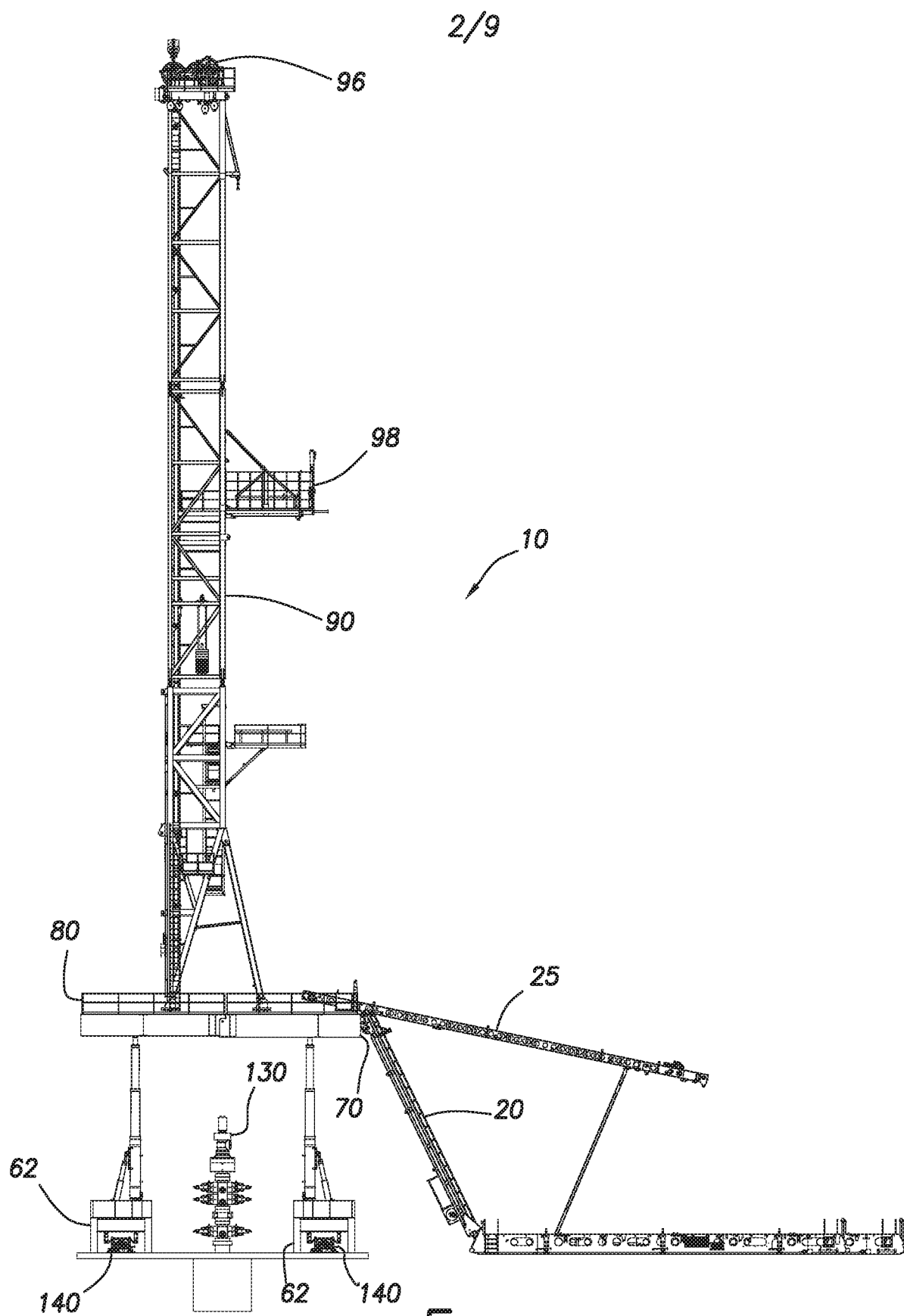
hvor støtteunderlagene (62) anordnes i en V-dørstøtterad (66) og en motstående V-dørstøtterad (68), hver rad av støtteunderlagene (62) har minst tre støtteunderlag (62), V-dørstøtteraden (66) anordnet langs V-dørsiden (58) av borerigg-gulvet (30) og den motstående V-dørstøtteraden anordnet motstående (68) V-dørsiden av borerigg-gulvet (30) eller

hvor V-døren (60) er posisjonert mellom minst to støtter (65), hver av støttene (65) er posisjonert på eller nær kantene (80) av borerigg-gulvet (30), og en åpningsavstand mellom to tilstøtende støtter (65) er A og en åpningsavstand mellom to andre tilstøtende støtter (65) er A', hvor A og A' er større enn diameteren til et brønnhode (130); og heve borerigg-gulvet (30) fra den senkede stillingen til en hevet stilling ved hjelp av de teleskopiske støttearmene (50); og bevege den landbaserte boreriggen (10) over brønnhodet (130).

15. Fremgangsmåten ifølge krav 14, hvor den landbaserte boreriggen videre omfatter minst én vandrer (140), den minst ene vandreren (140) posisjonert innenfor et støtteunderlag (62).
16. Fremgangsmåten ifølge krav 15, hvor trinnet med å bevege den landbaserte boreriggen omfatter: aktuere den minst ene vandreren (140); og vandre den landbaserte boreriggen (10).
17. Fremgangsmåten ifølge krav 16, hvor den hydrauliske vandreren (140) omfatter: vandrende fot (105); hydraulisk løft-montasje (107) som inkluderer en hydraulisk sylinder (108) koblet til den vandrende foten (105); og glidende aktuator (109) som inkluderer én eller flere hydrauliske sylindere (114) koblet til den vandrende foten (105).
18. Fremgangsmåten ifølge krav 17, hvor trinnet med å vandre den landbaserte boreriggen (10) videre omfatter: posisjonere den landbaserte boreriggen (10) på en første posisjon i et brønnområde (100); forlenge de hydrauliske løftene (107) til den hydrauliske vandreren (140); løfte den landbaserte boreriggen (10) fra bakken; aktuere de glidende aktuatorene (109) for å bevege de vandrende føttene (105) fra en første posisjon til en andre posisjon; bevege den landbaserte boreriggen (10) i en første retning; trekke tilbake de hydrauliske løftene (107);

plassere den landbaserte boreriggen (10) på bakken; og
aktuere de glidende aktuatorene (109) for å returnere de vandrende føttene (105) til den første posisjonen.

19. Fremgangsmåten ifølge krav 18, videre omfattende:
rotare de hydrauliske vandrerne (105);
gjenta forlengelses-, løfte-, aktuerings-, tilbaketrekkings- og reaktueringsoperasjonene; og
bevege den landbaserte boreriggen (10) i en andre retning.
20. Fremgangsmåten ifølge krav 19, videre omfattende:
gjenta forlengelses-, løfte-, aktuerings-, tilbaketrekkings- og reaktueringsoperasjonene
inntil den landbaserte boreriggen (10) er på en ønsket andre posisjon i brønnområdet.



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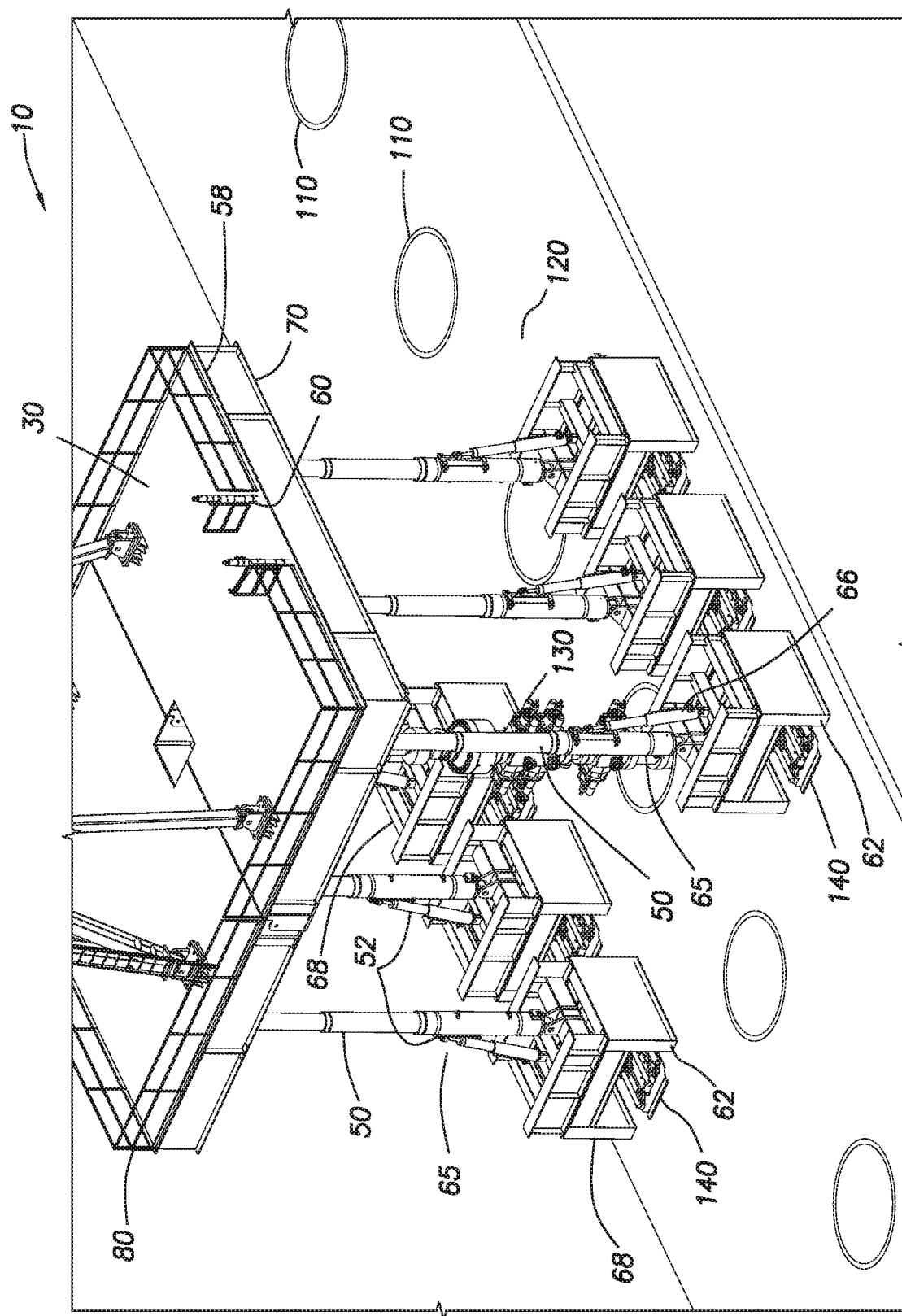


FIG. 3

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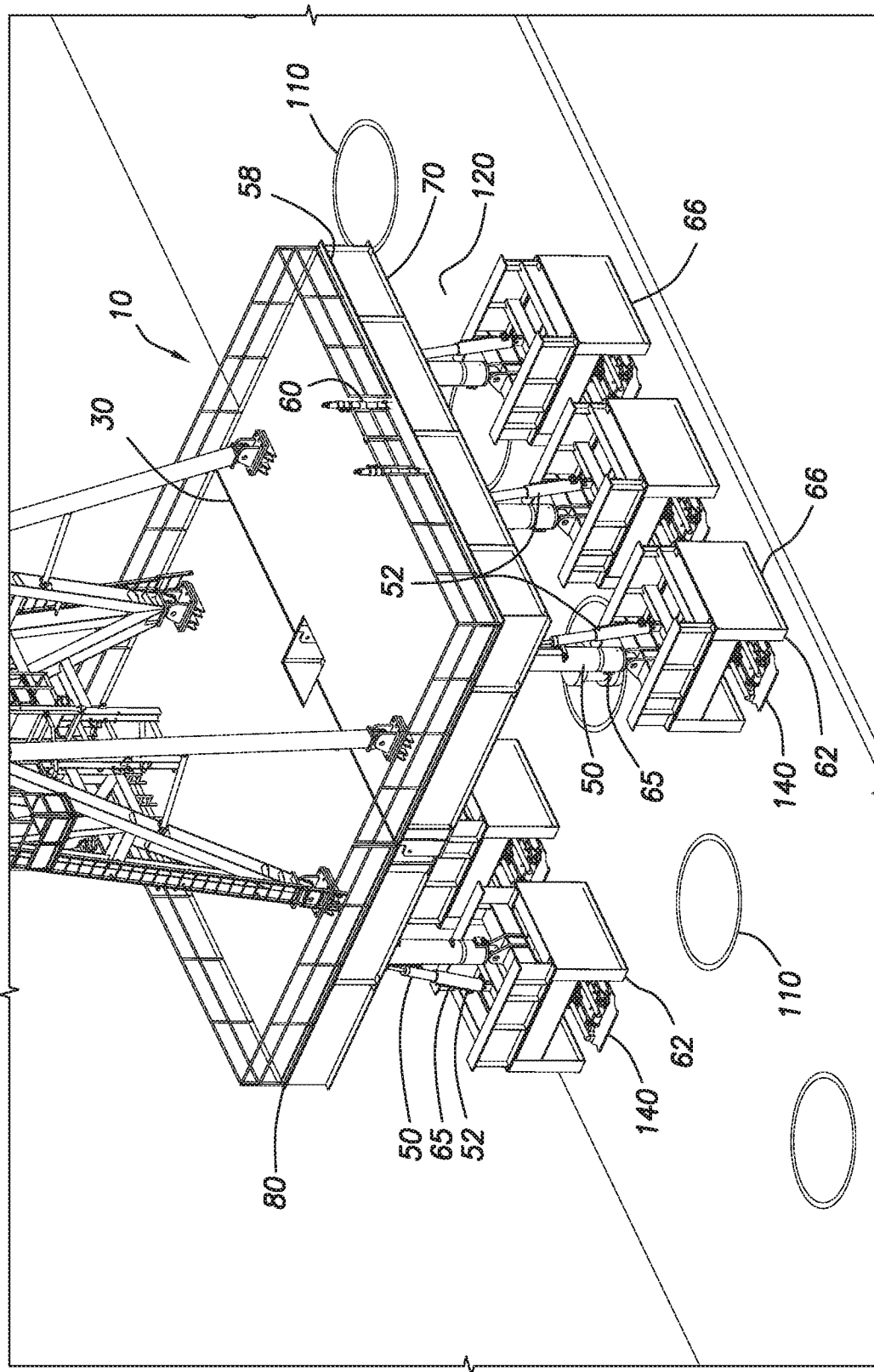
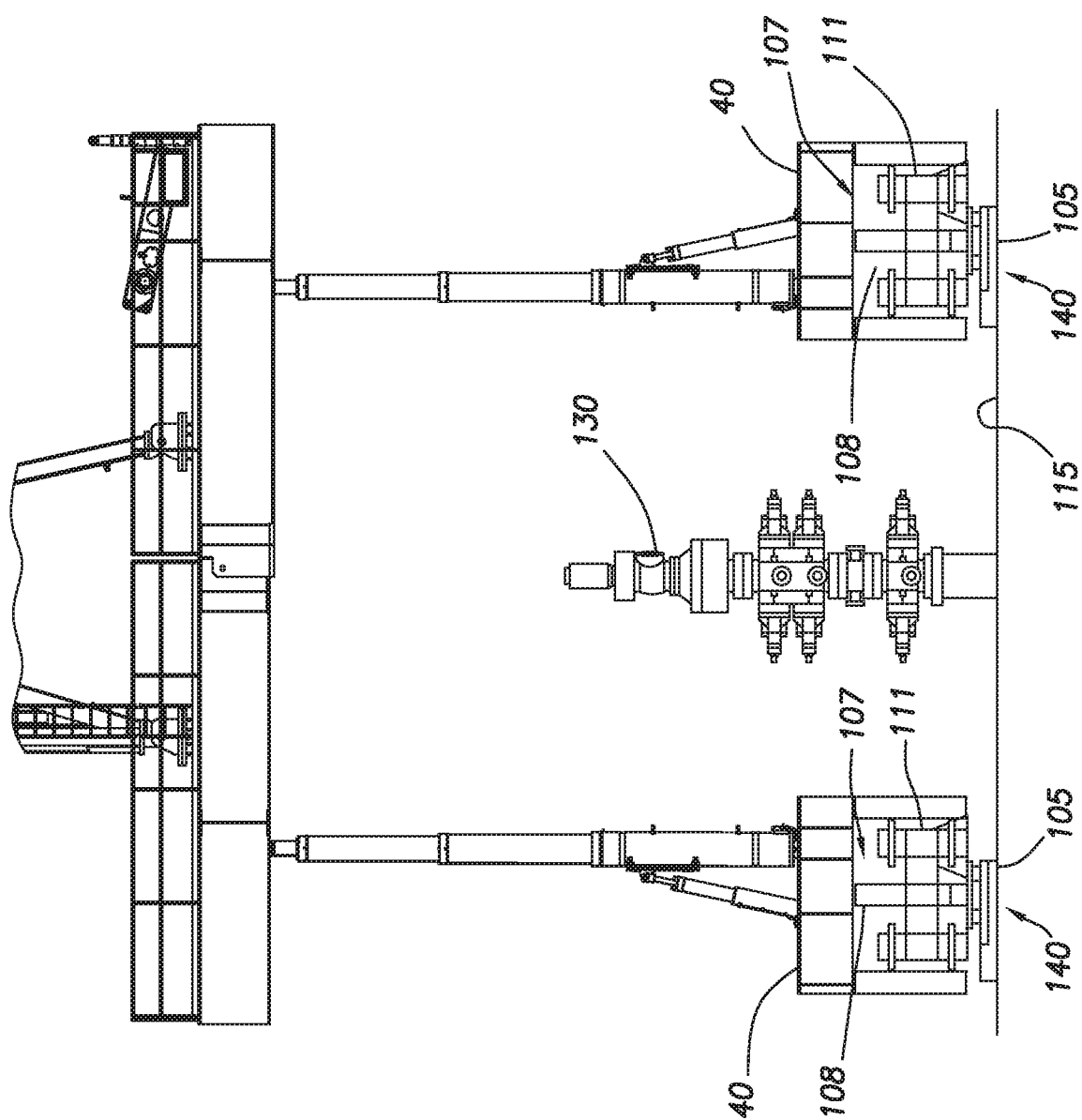
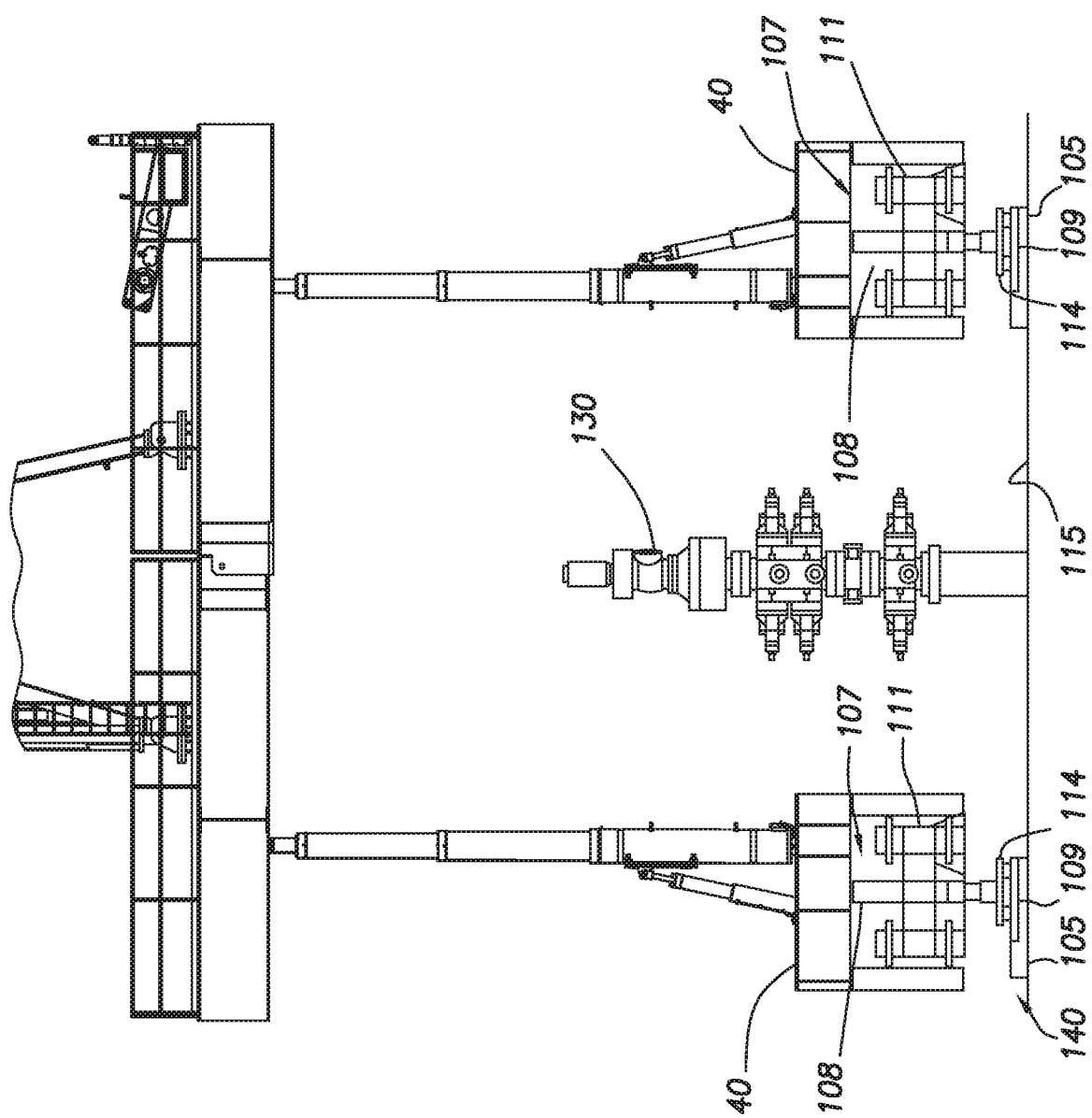


FIG. 4

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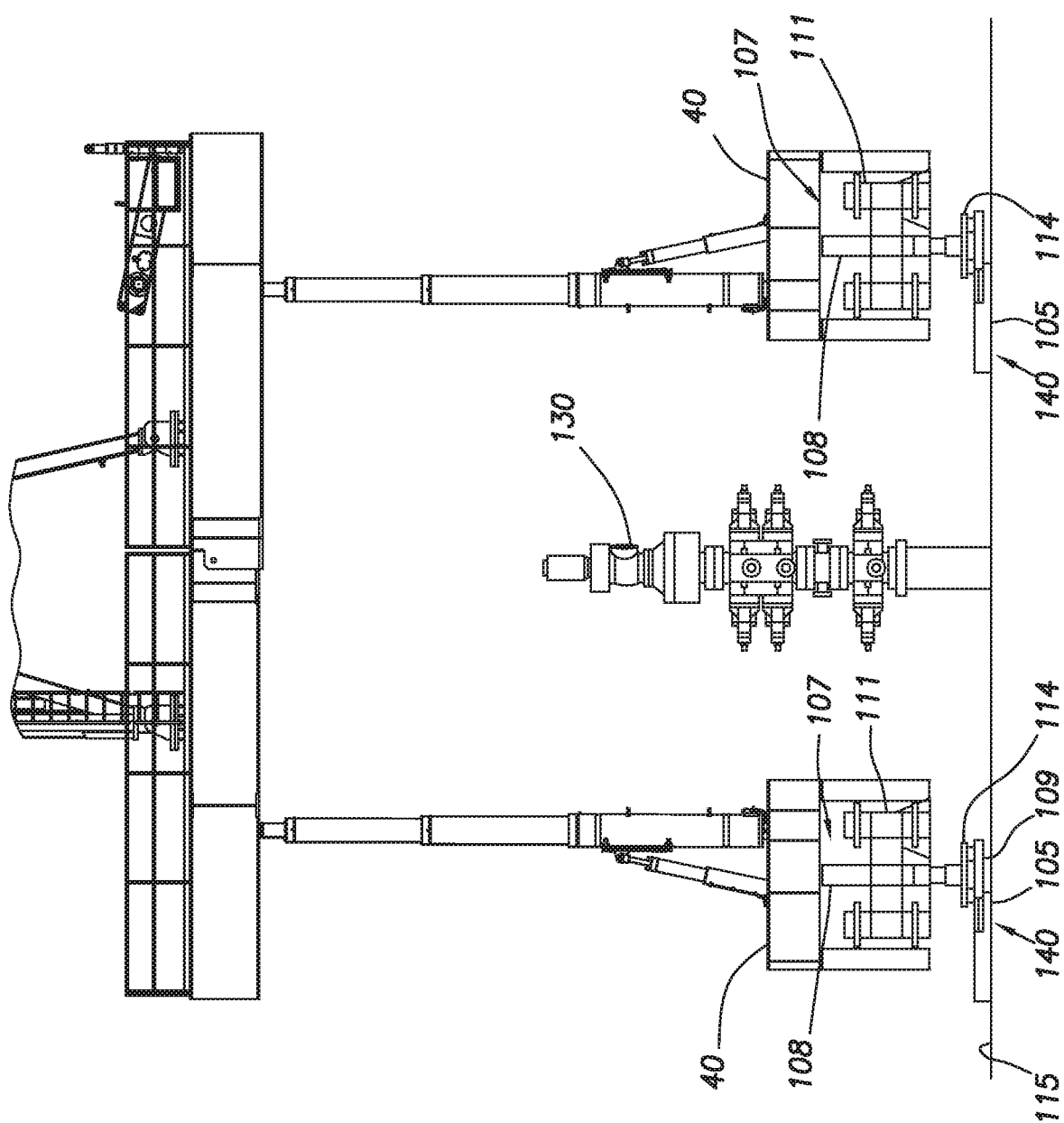


FIG. 5C

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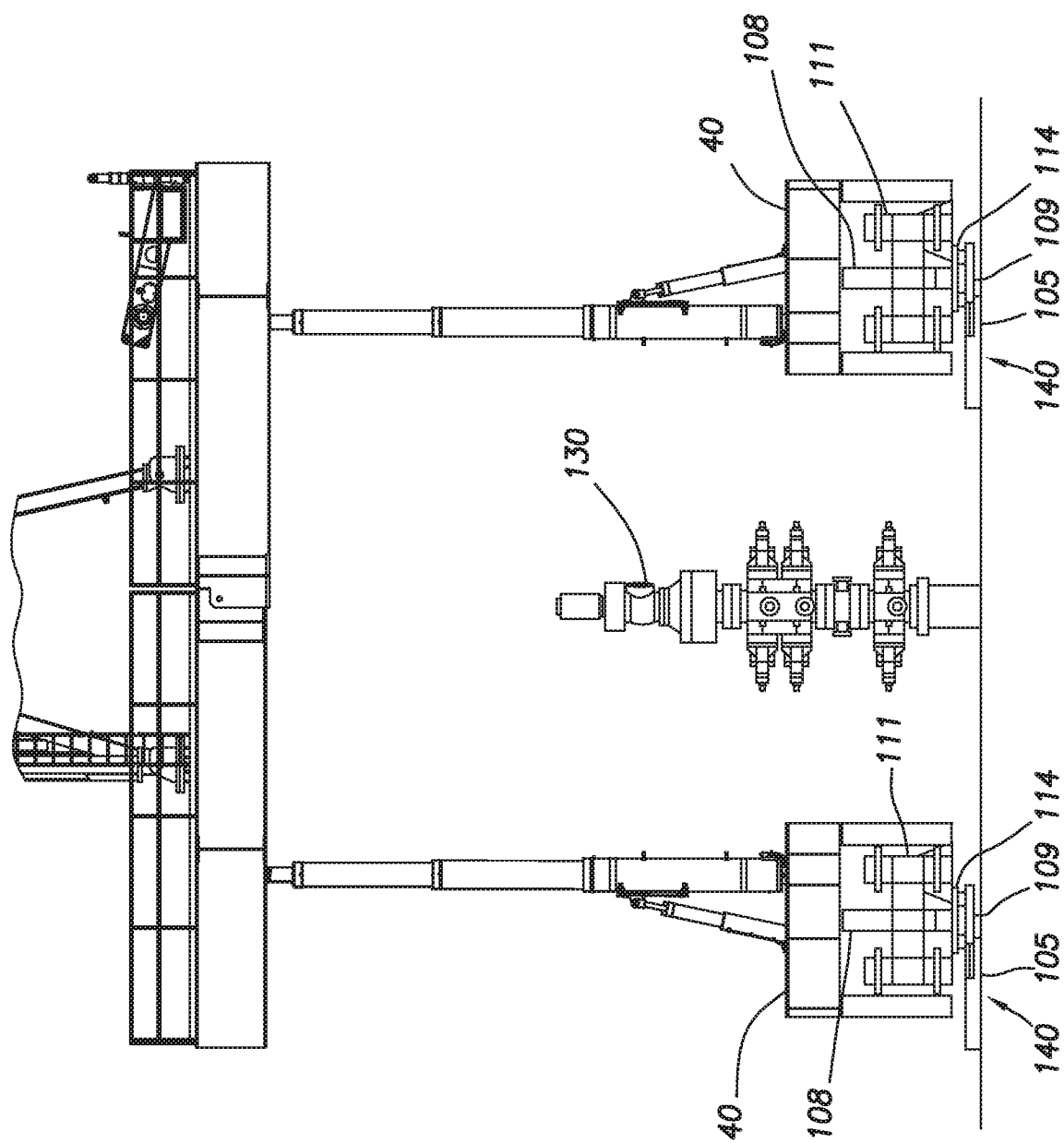


FIG. 5D

