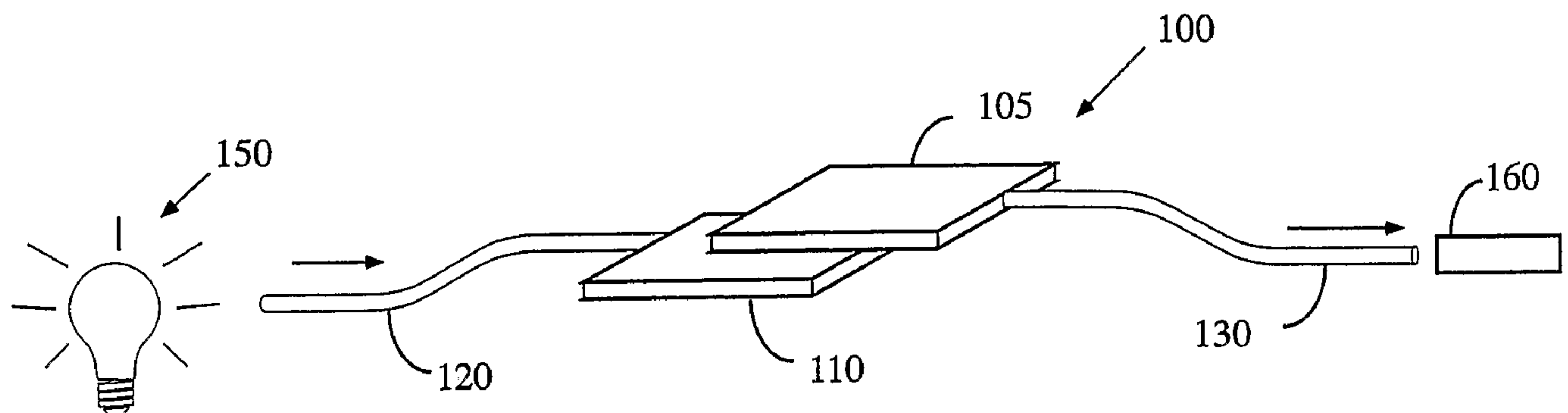




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(57) Abrégé/Abstract:

There is provided herein a sensor for determining relative displacement between two surfaces which utilizes two optically conductive members that have been mounted in proximity to each other, whereby the amount of displacement between the two surfaces may be determined by measurement of the magnitude of the intensity of light transmitted through them. The instant invention preferably utilizes two planar light transmitting surfaces - an emitter and a receiver - which are free to move laterally with respect to each other and are positioned so that when light is introduced into the emitter some proportion of that light falls on the receiver. By electronically monitoring the intensity of light impinging on the receiver an estimate of the amount of overlap between the two optical surfaces and, thus, an estimate of the relative displacement between them, may be obtained.

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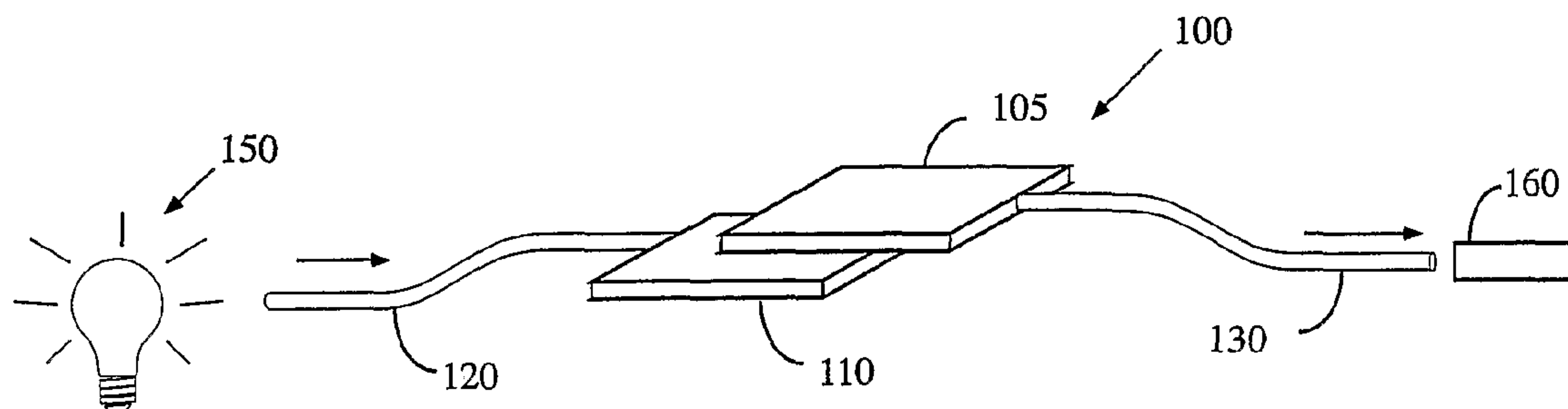
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(54) Title: DISPLACEMENT SENSOR APPARATUS



(57) Abstract: There is provided herein a sensor for determining relative displacement between two surfaces which utilizes two optically conductive members that have been mounted in proximity to each other, whereby the amount of displacement between the two surfaces may be determined by measurement of the magnitude of the intensity of light transmitted through them. The instant invention preferably utilizes two planar light transmitting surfaces - an emitter and a receiver - which are free to move laterally with respect to each other and are positioned so that when light is introduced into the emitter some proportion of that light falls on the receiver. By electronically monitoring the intensity of light impinging on the receiver an estimate of the amount of overlap between the two optical surfaces and, thus, an estimate of the relative displacement between them, may be obtained.

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DISPLACEMENT SENSOR APPARATUS

This invention relates generally to sensors for measuring the relative displacement between two surfaces or within a single surface under shear stress and, more particularly, to sensors that employ electrical or optical means to measure relative displacement.

5

BACKGROUND OF THE INVENTION

One of the world's most venerable technical problems is that of measuring displacement. Depending on the scale of the problem, any number of solutions have been proposed. With respect to large-scale measurements, rulers, tape measures and, more accurately, laser or other optical means have been used. For measurements of displacement that occur on a much smaller scale, optical interferometry or some other highly sensitive measurement method is often used.

Although there are many uses to which a measure of displacement might be applied, one that is of interest for purposes of the instant application is that of measuring the displacement that results from the application of force to a solid. That is, as is well known to those of ordinary skill in the art, strain results from the application of force to the external surface of a solid body. It is fundamental that given the force applied to the body and a measure of the amount of deformation, it is possible to calculate various physical parameters of the body including its shear modulus, Young's modulus, Poisson's ratio, etc.

However, many methods of calculating displacement under stress require expensive equipment and are not suitable for use in the field. Further, many of these measurement techniques are only applicable to measurement of a single axis of movement (e.g., longitudinally) and, thus, require multiple sensors to measure anything other than displacement along a single axis.

Optical methods are often preferred when making displacement measurements. Traditionally, methods of optical measurement of displacement fall into one of three categories: sensors that utilize interferometer techniques, sensors that employ optical gratings, and sensors that are based on the use of optical resonant cavities. As compared with electrical methods, optical methods do not require electrical wiring in order to transmit signals and, thus, they are not affected by electromagnetic interference which can cause measurement errors in electronic measurement methods. Further, electrical methods typically utilize a two element conductor to transmit signals and this conductor tends to be heavier than a corresponding capacity fiber optic line. This, of course, can pose a problem when the measuring device needs to move freely. As compared with mechanical measurement techniques, optical methods are preferred because of the increased accuracy that is possible. Further, optical methods are imminently suited for use in conjunction with a computer, whereas mechanical methods require some sort of translation / reformatting to make them into computer readable form. Finally, generally speaking optical methods do not traditionally require that contact be made between the sensor elements on the moving and stationary surfaces which can be an advantage in some settings.

However, optical measurement methods are not without their faults. This technology can require the use of large optical components such as beam-splitters, mirrors, lenses, etc., which can make application of this technology difficult outside of a laboratory.

Thus, what is needed is an improved optical method and apparatus of measuring displacement which is not unduly complex and which does not require an inordinate amount of support equipment. Preferably, this apparatus will be suited for use in measuring strain / shear in solids.

Heretofore, as is well known in the measurement arts, there has been a need for an invention to address and solve the above-described problems. Accordingly, it should now be recognized, as was recognized by the present inventors, that there exists, and has existed for some time, a very real need for such a system.

5 Before proceeding to a description of the present invention, however, it should be noted and remembered that the description of the invention which follows, together with the accompanying drawings, should not be construed as limiting the invention to the examples (or preferred embodiments) shown and described. This is so because those skilled in the art to which the invention pertains will be able to devise other
10 forms of this invention within the ambit of the appended claims.

SUMMARY OF THE INVENTION

According to a first preferred embodiment of the instant invention, there is provided a sensor for determining relative displacement which utilizes two optically conductive surfaces in proximity to each other, whereby the amount of displacement
15 between the two surfaces may be determined by measurement of the magnitude of the intensity of light transmitted through the apparatus. In brief, the instant invention consists of a light emitting member and a light receiving member proximate thereto, wherein at least a portion of the light that leaves the emitting member is absorbed by the receiving member and wherein the amount of light that is transmitted between the
20 two members is a function of their relative displacement.

Preferably, light from one or more light sources is transmitted, e.g. via a fiber optic line, to the emitting member. In the preferred embodiment this will be a rectangular optically conductive element. The receiving member is positioned proximate to the emitting member and is preferably identically dimensioned. The
25 receiving member has an optically conductive conduit (e.g., fiber optic line) affixed

thereto for purposes of receiving light which is collected by the receiving member.

When the emitting and receiving members are exactly aligned with each other, light will be maximally transmitted between them. However, when the emitting and receiving members are offset from each other, the amount of light captured by the receiving member will be lessened. Thus, by using a photoelectrical cell or similar device (e.g., a photodiode, a photo transistor, or a photo receptor, etc.) to monitor the intensity level of light that is captured by the receiving member, the amount of overlap between the two members and, hence, the amount of relative displacement between the two, may be quantitatively determined. It should be noted that in one preferred embodiment, this single sensor is capable of sensing displacement in any horizontal direction, where horizontal is measured with respect to the orientation of the emitting and receiving member faces.

According to another preferred embodiment, there is provided a displacement sensor substantially similar to that described above but which is suitable to measuring and quantifying displacement in any horizontal (i.e., 2-D) direction. In one preferred embodiment, a plurality of different colored lights (e.g., LEDs) will be arrayed in a grid to form a light source. The multi-color light source will then be transmitted through an optically transmissive element such as fiber optic cable to the emitting and receiving members described previously. On the receiver end, a plurality of photosensitive elements will be provided, each photosensitive element corresponding to one of the colors in the light array. Then, to the extent that one or more of the colored lights sources is obscured or its light intensity reduced in amplitude, such a change can be related to the movement direction of the sensor and, hence, displacement.

In another preferred embodiment, there is provided a displacement sensor substantially as described above wherein the emitting member has a plurality of different colored transparent regions on its receiving face. The purpose of each colored region is to restrict the frequencies of light passing therethrough to a relatively narrow band. Preferably, the light source will be white or broadband light. Then, light will be transmitted from the source through the emitting element and into the receiving element, at which time it will be filtered according to the chosen color scheme that has been imposed on its face. A photosensitive device will be placed in optical communication with the receiver that includes photoactive elements that are responsive to each of the transmitted colors. When the emitter and receiver are not in complete alignment it will be possible to determine the amount of displacement between the two elements by measuring the intensities of the transmitted colors of light.

In still another preferred embodiment, there is provided a displacement sensor that utilizes a plurality of spaced apart resistors or resistive elements to measure relative movement between two surfaces and/or expansion / contraction of a single surface. Preferably, as displacement occurs, a contact element will successively engage different ones of the resistive elements so that by measuring the resistance (or capacitance, etc.) within the circuit it will be possible to quantitatively determine the amount of displacement.

The foregoing has outlined in broad terms the more important features of the invention disclosed herein so that the detailed description that follows may be more clearly understood, and so that the contribution of the instant inventor to the art may be better appreciated. The instant invention is not to be limited in its application to the details of the construction and to the arrangements of the components set forth in

the following description or illustrated in the drawings. Rather, the invention is capable of other embodiments and of being practiced and carried out in various other ways not specifically enumerated herein. Further, the disclosure that follows is intended to apply to all alternatives, modifications and equivalents as may be included within the spirit and scope of the invention as defined by the appended claims. Finally, it should be understood that the phraseology and terminology employed herein are for the purpose of description and should not be regarded as limiting, unless the specification specifically so limits the invention.

In accordance with one aspect of the present invention, there is provided an optical displacement sensor, comprising: (a) a first optical line, said first optical line being positionable to be in optical communication with an illumination source; (b) a sensor emitter, said sensor emitter having at least one emitting surface, (b1) wherein said sensor emitter is in optical communication with said first optical line, (b2) wherein said sensor emitter is non-diffracting and optically conductive, and, (b3) wherein at least a portion of any light originating from said illumination source is emitted from said at least one emitting surfaces; (c) a sensor receiver, said sensor receiver having at least one receiving surface, said sensor receiver being positioned to be proximate to said sensor emitter and in optical communication therewith, (c1) wherein said sensor receiver is non-diffracting and optically conductive, (c2) wherein at least one of said receiving surfaces is in optical communication with at least one of said emitting surfaces, (c3) wherein at least a portion of any light emitted from said emitting surface is received by said receiving surface, and, (c4) wherein said sensor receiver and said sensor emitter are movable with respect to each other, wherein an amount of light received by said receiving surface varies with any such movement, and wherein said amount of light

received by said receiving surface is representative of an amount of displacement
between said emitting surface and said receiving surface; and, (d) a second optical line,
said second optical line being in optical communication with said sensor receiver, said
second optical line being at least for transmitting at least a portion of any light received
5 by said receiving surface.

While the instant invention will be described in connection with a preferred
embodiment, it will be understood that it is not intended to limit the invention to that
embodiment. On the contrary, it is intended to cover all alternatives, modifications and
equivalents as may be included within the spirit and scope of the invention as defined by
10 the appended claims.

BRIEF DESCRIPTION OF THE DRAWINGS

Other objects and advantages of the invention will become apparent upon
reading the following detailed description and upon reference to the drawings in which:

15 Figure 1 illustrates a preferred embodiment of the instant invention.

Figure 2 illustrates how the instant invention may be used to measure strain in a
solid body.

Figure 3 contains an illustration of a preferred method of measuring
displacement between two different surfaces.

20 Figure 4 is a schematic illustration of how the emitter/receiver portions of the
instant invention operate to signal their relative positions to an attached photo electric
element.

Figure 5 illustrates a preferred embodiment of the instant invention which utilizes multiple / different colored regions on the face of the emitter to increase the precision of the estimated displacement.

Figure 6 contains a diagram which generally illustrates how the embodiment of Figure 5 would respond to a relatively modest displacement.

Figure 7 illustrates how the embodiment of Figure 5 can be used to determine displacement along a single axis.

Figure 8 contains a diagram which generally illustrates how the embodiment of Figure 5 would respond to a relatively major displacement.

Figure 9 illustrates another preferred embodiment, wherein a bank of different colored light sources is utilized as an illumination source.

Figure 10 contains a preferred arrangement of the invention of Figure 9.

Figure 11 illustrates how the light sources of Figure 9 might appear on the face of the emitting element.

Figure 12 illustrates how the arrangement of Figure 11 can be used to determine the relative offset between the emitting and receiving members.

Figure 13 illustrates another preferred embodiment, wherein a multiplicity of separate optical pickups are used to determine relative displacement.

Figure 14 contains an illustration of still another preferred embodiment wherein separate optical pickups are used to determine relative displacement.

Figure 15 illustrates a preferred displacement sensor embodiment wherein a bank of contacts elements successively engage as a contact bar is displaced.

Figure 16 contains a preferred embodiment, wherein the changing electrical properties of an elastically deforming member is used to determine an amount of displacement.

Figure 17 illustrates a preferred embodiment where multiple ones of the displacement sensors of Figure 16 are combined to yield a more accurate estimate of the relative displacement preferably between two bodies.

Figure 18 contains an illustration of a preferred embodiment which utilizes two fiber optic cables placed end-to-end such that the intensity of the light which is transmitted therethrough is a measure of relative displacement.

DETAILED DESCRIPTION OF THE INVENTION

Optical Embodiments

According to a first preferred embodiment of the instant invention and as is generally set out in Figure 1, there is provided a sensor 100 for determining relative displacement which utilizes two optically conductive members (upper / receiving member 105 and lower / emitting member 110) that have been placed into proximity with each other in an approximately parallel configuration. Broadly speaking, this invention operates to sense a displacement between these two elements by determining the intensity (magnitude, etc.) of light from source 150 that is transmitted through the sensor 100 and is received by a light sensitive photoreceptor element 160. The amount of light received by the photoreceptor element 160 will be at a maximum when the upper 105 and lower 110 members are in perfect alignment and less so when one element is displaced relative to the other. Thus the intensity of the transmitted light as preferably measured by the receptor 160 can be used to calculate the amount of offset between the upper 105 and lower 110 members and, hence, the amount of relative displacement.

Figure 4 illustrates this concept in greater detail. In Figure 4A, the upper 105 and lower 110 members are in complete alignment. Light that is transmitted via optical line 120 into lower / emitting member 110 will be radiated to the maximum

extent possible into upper / receiving member **105** and, thereafter, via line **130** to a photoreceptor element **160**. Contrast this arrangement with that illustrated in Figure **4B**, where there is very little overlap between the upper **105** and lower **110** members. In this scenario, light that is radiated from lower member **110** will largely miss the
5 receptor / upper member **105**, thus reducing the amount of light that is captured and subsequently transmitted via optical line **130**. Methods for determining the amount of displacement given the measured light intensities at a photoreceptor element **160** will be discussed below.

Figure **3** illustrates how the instant invention can readily be adapted to
10 measure the amount of displacement caused by movement of two adjacent surfaces. In this preferred embodiment, support post **305** is affixed to surface **330** and support post **310** to surface **340**. Relative movement of the support surfaces will result in upper member **105** uncovering some or all of lower member **110**, which, in turn, results in a corresponding reduction in the amount of light captured by the upper
15 member **105**.

Figure **2** illustrates another preferred embodiment, wherein the instant invention **100** is used to measure the strain / elasticity on a single support surface **230**. For example, if the support surface **230** is at least somewhat elastic, putting tension (or compression) on opposite ends of this surface **230** will tend to change the spacing
20 between support posts **205** and **210** as the surface stretches (or compresses). Such a change will be reflected in the amount of overlap between the two optically conductive members **105** / **110** and, hence, the amount of light transmitted therethrough. By calculating the decrease in the amplitude of the light transmitted and comparing that with the maximum possible light intensity (as determined, e.g.,
25 empirically based on the maximum transmission configuration) it is readily possible

to determine how much the two members **105** and **110** have moved with respect to each other in absolute terms.

The members **105** / **110** will preferably be made of a light transmitting or optically transparent / translucent material such as polycarbonate. As a consequence,
5 when light is piped into member **105**, the light will propagate through it and tend to be emitted in large part from its top and bottom surfaces. In some preferred embodiments, the lower surface of interface member **105** which faces away from member **110** may be silvered or otherwise mirrored to increase the amount of light that is traveling toward member **110**. Light that is radiating from emitting member
10 **105** will travel toward the matching face of receiving member **110**, where it will be channeled to line conduit **130** and, ultimately, to photo receiver **160**.

Note that one feature of the invention as described previously is that it is responsive to displacement in any horizontal direction, assuming that the unit **100** is mounted horizontally, of course. More precisely, a decrease in the transmitted light
15 amplitude will be noted if the elements **105** / **110** are moved relative to each other while maintaining a constant distance between the two elements. However, if the elements **105** / **110** are constrained so that only movement along a single axis (e.g., left-and-right in Figure 3) is permitted, the variation in received light intensity through the unit is directly correlated to the amount of relative movement between the
20 two interface members (members **105** and **110**) and a simple calculation will yield an estimate of the relative amount of displacement. Thus, assuming that light is at least approximately uniformly distributed across the face of emitter **105**, if the length of the emitter / receiver is multiplied by the ratio of the measured light intensity to the
25 maximum possible light intensity, an estimate of the amount of displacement will be obtained.

On the other hand, if the two interface members **105** and **110** are allowed to move in any arbitrary horizontal direction the computation of the amount of displacement becomes problematic using the simple approach described previously unless additional steps are taking as is described below. That being said, even without
 5 customizing the sensor **100**, the raw computation of the amount of displacement still gives useful information about the gross amount of movement.

As a specific example of how displacement might be calculated using the instant embodiment, it will be assumed for the moment that the sensor members are constrained to move along one axis (e.g., longitudinally). In that instance, let I_o be the
 10 amount of light sensed by photoreceptor **160** when the upper **105** and lower **110** members are in exact alignment (e.g., Figure **4A**) and the light source **150** is activated. Supposing, for purposes of illustration, that each of the members **105** / **110** are squares one inch on a side. Finally, assuming that, after displacement, the reading on photo receptor **160** is $I_D = I_o / 2$, the actual amount of displacement would be
 15 calculated to be:

$$D = (1 \text{ inch}) * \left(\frac{I_D}{I_O} \right) = (1 \text{ inch}) * \left(\frac{I_O/2}{I_O} \right) = 0.5 \text{ inch}$$

Clearly, this calculation will only yield reliable estimates of displacement if the members **105** / **110** are constrained so that movement is allowed only in a single direction. It should be noted that the inventors have utilized a one-inch sensor in the
 20 previous calculations only for purposes of simplifying mathematics and that the use of sensors that are much larger or much smaller (depending, for example, on the magnitude of the displacement that is being measured) have been specifically contemplated by the instant inventors. Those of ordinary skill in the art will readily be able to select a sensor size that is appropriate for any particular application.

If it is desired to obtain measurements of offsets in any arbitrary two-dimensional direction, a modified version of the previous embodiment is preferred. As is generally illustrated in Figure 5, according to another preferred embodiment there is provided an optical sensor for determining displacement, wherein a pattern of
5 different colored regions have been added to the face of one of the sensor members **105 / 110**. Preferably regions A, B, C, and D of optical member **510** are each designed to pass a limited frequency range of light and could be, for example, gel-type filters, colored transparent glass, plastic, etc. Of course, those of ordinary skill in the art will recognize that it is not essential that the colored regions be added on top of
10 an existing clear sensor member **105**, but could instead be made to be integral to the sensor member **105** during the manufacturing process or, alternatively, could be implemented in the form of four discrete filters in an assembly. In terms of color choices, as an example only, region A might be colored orange, region B might be colored yellow, region C might be colored blue, and region D might be colored
15 indigo. The only requirement for this particular embodiment is that the colors that are applied to each region be differentiable by, for example, an individual photoreceptor. Alternatively, the photoreceptor can be sensitive to the specific light wavelength listed above with ABCD manufactured from clear lenses

The intent of the application of various colors to member **510** is to restrict the
20 frequencies of light passing through that portion of the sensor. When the light frequencies are so restricted, it is possible to determine via photoreceptor **160** the light intensity received in each of the passed wavelengths. Then, by comparing the received light intensity at each frequency with the known intensity when the upper and lower members are perfectly aligned, the amount of displacement may be
25 calculated.

The following simple calculations illustrate one method of determining the amount of offset given the intensities of light passing through the four regions of Figure 5. Consider the scenario of Figure 6. Here, the sensor consists of lower member **520** and upper member **510**. For purposes of illustration only, it will be
 5 assumed that the upper member **510** has moved upward and to the right with respect to the lower member **520**. Let I_{A0} , I_{B0} , I_{C0} , and I_{D0} be the fully-aligned light intensities received through the two sensors (i.e., the reference values) and let I_A , I_B , I_C , and I_D be as-measured light intensities after the upper member **520** has been offset by ΔX in the horizontal direction and ΔY in the vertical direction, with ΔX and ΔY being less than
 10 $L/2$, where each region A-D is identically sized and the members **510** / **520** are square with each side of dimension L . In such a scenario, from simple geometric arguments it follows that the received light intensities will be proportional or approximately equal to:

$$15 \quad I_A = \frac{(L/2 - \Delta Y) * (L/2)}{(L/2)^2} I_{A0}$$

$$I_B = \frac{(L/2 - \Delta Y) * (L/2 - \Delta X)}{(L/2)^2} I_{B0}$$

$$I_C = I_{C0}$$

$$I_D = \frac{(L/2 - \Delta X) * (L/2)}{(L/2)^2} I_{D0},$$

where the only unknown quantities are ΔX and ΔY . Note that there will be a slightly different (but comparable) set of equations which apply when the upper member **510** is moved toward each of the three other quadrants. Those of ordinary skill in the art will be readily able to derive such alternative equations. Note further that in this

5 example I_C should be equal to its reference intensity I_{C0} , which provides an easy way to determine, generally, which direction the upper member **510** has moved: the quadrant (or quadrants as discussed below) whose light intensity is unchanged from its reference value will be opposite to the direction of movement.

Clearly, the equations for I_A and I_D presented above can be directly solved for

10 ΔX and ΔY to yield:

$$\Delta Y = L/2 \left(1 - \frac{I_A}{I_{A0}} \right)$$

$$\Delta X = L/2 \left(1 - \frac{I_D}{I_{D0}} \right)$$

Thus, given the reduction in light intensities in each of the four quadrants, the actual amount of offset may readily be calculated according to the previous equations, given

15 the dimensions of the measuring device **100**. Note that by substituting ΔX and ΔY back into the equation for I_B a check may be performed on the overall quality of the calculations.

It is certainly possible that in some cases the two members **510** and **520** might be moved along a single coordinate axis, for example vertically, with respect to each

20 other as is illustrated in Figure 7 (i.e., $\Delta X = 0$). In that case, the rules and equations discussed above will still apply, except that I_D will also be equal to its reference value

I_{D0} . Thus, the previous equations could be used without change and should yield for this scenario and within measurement error, a value of ΔX equal to zero.

It should be noted that the equations offered above are, strictly speaking, only valid if ΔX and ΔY are less than $L/2$. However, it still may be possible to estimate the amount of offset if that inequality is exceeded (e.g., Figure 8). For example, in the event that the amount of displacement is being continuously monitored, it might be possible to establish a trajectory for the movement of the upper member **510** with respect to the lower member **520** and, using that trajectory together with the one or two remaining intensities that can still be measured, calculate an approximate amount of offset. Those of ordinary skill in the art will recognize readily how this might be done.

Another possible solution that might be considered if the ΔX and ΔY are expected to be greater than $L/2$ is to increase the dimensions of the members **510** / **520**, i.e., increase L . Still another possible solution would be to further subdivide the color member **510** into 9, 16, (e.g., if the members **510** / **520** are square) or any other arbitrary number of different color panels. This would provide higher resolution if the use required such increased resolution.

In another preferred arrangement, a bank of multi-colored lights (e.g., LEDs) will act as the illumination source, with displacement being determined by reductions in intensity of one or more of the light sources. As is generally indicated in Figure 9, the preferred illumination source **900** for this embodiment is an array of individual lights **905**, wherein each of the lights **905** radiates light at a different color / frequency. LEDs would be preferable for use as the illumination sources **905**. Of course, those of ordinary skill in the art will recognize that a prism which is used in combination with a white light source could also be used to create a multiplicity of

colored light sources, each confined to a particular region of the emitting surface **110**.

A preferred arrangement optionally includes diffuser **905** (Figure 10) which is designed to spread the light which emanates from the LEDs **905** more evenly so that the image of such lights will not appear as point sources on the face of the emitter

5 **110**.

As was described in connection with the previous embodiment, by choosing each of the light sources **905** to be a different light frequency, it is possible to determine at the photo receiver **160** which light(s) has been occluded by the displacement between the upper and lower members **105 / 110**. Those of ordinary
10 skill in the art will readily be able to devise many ways of making this determination. That being said, and by way of example, it should be clear that each time one of the light sources **905** disappears from the receiver's **160** view, that means the image of the corresponding light source – as it appears on member **110** – has been “shifted” from view. Thus, in simplest terms the array of lights **905** forms a kind of coordinate
15 system that yields at least approximate displacement values based on the presence / absence of a light frequency from the photo receptor **160**.

More generally, a computation analogous to that suggested above may be performed with respect to the light array **900**. More particularly, and turning now to Figures **11** and **12**, it is well known that light sources **905** will tend to illuminate
20 circular regions of lower member **110**. Note that the example of Figure **11** has been drawn to show gaps in the coverage of the illuminated portion of lower member **110** to make clearer the discussion that follows. In practice, there would preferably be no such gaps and the regions illuminated by the light sources **905** would overlap to the extent that they completely cover the face of lower unit **110**.

In practice, the logic utilized previously can be used again in this scenario to determine the relative offset between the two members **105** and **110**. Available to be used in the solution will be I_E through I_M , the measured intensities of each of the regions E – M , as well as I_{E0} through I_{M0} , the light intensities at the corresponding frequencies when the two members **105** and **110** are in perfect alignment. Preferably the method that is utilized will first determine which of the regions E-M are completely obscured or completely visible. Knowledge of that information will provide guidance in a general way as to the direction and magnitude of the displacement.

Then, given the previous information, those regions E-M that are partially obscured will be used to determine the actual amount of displacement ΔX and ΔY preferably by forming equations that express the amount of area each light source that is occluded as a function of the displacement. The formation and solution (which may require a numerical solution) of such equations is well within the ability of one of ordinary skill in the art and will not be discussed here. Note, however, that the intensities of the light that appears in regions F and G can each be used to provide independent estimates of ΔY and light in regions H and K can be used to provide independent estimates of ΔX .

Note that the foregoing computations assume that, as pictured in Figure **11**, the light sources appear on lower member **110** in approximately circular patterns. Clearly, the instant method could be adapted to work with light images of any arbitrary shape. It is also preferably assumed that the light energy is uniformly distributed throughout each circle E-M. That being said, those of ordinary skill in the art will understand how the previous analysis could readily be modified by alternative

assumptions, including the assumption that the intensity of the light source decreases as a function of the distance from the center of each of the regions E-F.

According to another preferred arrangement, there is provided an optical device for measuring displacement wherein a plurality of optical pickups are utilized.

5 As is indicated in Figures **13A** and **13C**, optical pickups **1305 – 1325** will preferably be affixed to the face the receiving member **1390** that is opposite the emitting member **1395**. That being said, those of ordinary skill in the art will understand that, depending on the transparency of the receiving member **1390** the optical pickups **1305 – 1325** could readily be mounted on the face opposite that of emitting member. The
10 purpose of the optical pickups **1305 – 1325** is to collect at least a portion of the light that falls on the receiving member and transmit that energy further to a corresponding number of photosensitive / photoreceptive elements. Note that the shape of the optical collectors **1305 – 1325** is immaterial to the operation of the instant invention, except that some shapes lend themselves more readily to calculation of the offset than
15 others.

Emitting member **1395** accepts light input (e.g., as indicated Figure **13C**) and then radiates at least a portion of that energy toward the receiving member **1390**. In this embodiment, a plurality of optically opaque blocking members (**1350 – 1365**) have been placed on the face of the emitting member **1395** that radiates light toward
20 the receiving member **1390**. Although there are many ways of doing this, one preferred method involves printing black regions directly on the emitting surface of member **1395**. that being said, there are certainly many other ways this could be implemented.

Figure **13B** provides a plan view of the instant sensor with both the receiving
25 member **1390** and the emitting member **1395** (hidden from view in this figure) in

place. Shown in phantom are the blocking members **1350-1365** which preferably are placed in proximity with the optical collectors **1305 – 1325**. Note that, in this embodiment, the blocking member that is associated with optical collector **1315** cannot be seen because it is positioned directly below it in this view. Note further
5 that, for purposes of clarity, the optical lines associated with each individual optical collector **1305 – 1325** have not been shown in Figures **13A** and **13B**.

In practice the embodiment of Figure **13** would be utilized as follows. Each optical collector will have an optical line associated with it (e.g., line **1375** in Figure **13C**) and, in optical communication with the optical lines will preferably be a same
10 number of photosensitive elements. Thus, displacement of member **1390** with respect to member **1395** will result in variations in the intensity of light collected by each of the photosensitive elements. For example, if in Figure **13B**, element **1390** were to move toward the north east (upper right corner) while element **1395** remained stationary, the light intensity associated with optical collector **1395** would tend to
15 increase as it moved from directly above its blocking member; the light intensity associated with optical collector **1305** would tend to decrease as it covered more of blocking member **1350**; the light intensity associated with optical collector **1325** would tend to increase as it will be blocked to a lesser extent by blocking member **1365**, etc.

20 Given the pattern of increases and decreases in light intensity and a knowledge of undisplaced light intensity to each collector, an estimate of the relative amount of displacement may be obtained according to methods well known to those of ordinary skill in the art. As has been explained previously, the precise equations which yield the offset in terms changing intensities will depend on the geometric shapes of the

collecting and blocking members. But, an analysis similar to that presented previously will yield the sought-after equations.

Turning now to Figure 14, there is provided an embodiment substantially similar to that discussed previously, except that different geometric shapes are utilized for the optical collectors and the emitting / masking members. As is indicated in Figure 14A, in a preferred embodiment the emitting member 1405 will be optically masked with a single blocking element 1408 which has been selected to be positioned to block light that is radiating toward receiving member 1410 and takes the shape of a square with a circular hole in the middle. In Figure 14B, Optical collectors 1450 – 1465 are positioned around the periphery of the receiving member 1410 and a circular collector 1470 is preferably positioned in the center of that element. Finally, Figure 14C illustrates a plan view of the combined sensor 1400, wherein the receiving member 1410 has been placed under the emitting member 1405. As can be seen, any horizontal displacement of one member 1405 / 1410 with respect to each other will result in a corresponding decrease (or increase) in the amount of light impinging on the optical collectors, depending on how the optical masking 1408 moves to covers or uncover the various optical collectors. Member 1470 will provide an absolute value for the displacement and evaluation of the light intensity within optical collectors 1450 – 1465 will give directional information.

Turning next to a discussion of photo receptor element 160, in a preferred arrangement a photoelectric cell or similar hardware that reacts to the presence and intensity of light is used. As is well known to those of ordinary skill in the art, a photoelectric cell or photocell is a device whose electrical characteristics (e.g., current, voltage, or resistance) vary when light is incident upon it. Further, it is well known in the optical communication industry that such elements are available

wherein they respond only to light in a relatively narrow wavelength frequency band and those skilled in the art will be readily able to select such sensors that would be suitable for use with the instant invention.

Finally, and as is generally illustrated in Figure 18, there is provided a displacement sensor 1800 which would likely be best suited for measuring relatively small amounts of displacement. In a preferred arrangement, the open end of an source optical fiber 1805 is placed in optical communication with (e.g., butted directly against) the open end of receiver optical fiber 1810. One of both of these optical fibers will be free to move with respect to the other. To the extent that the termini of the two ends are directly aligned, a maximum amount of light will be transmitted. However, even very small amounts of displacement (depending on the diameter of the optical lines) will reduce the amount of light that is transmitted between them. Thus, by measuring the intensity of light conveyed through receiver optical fiber 1810 and comparing that amount with a known maximum possible light intensity, an estimate can be made of the amount of overlap between the two termini and, hence, the amount of relative displacement that has occurred.

Electrical Embodiments

According to another preferred embodiment, there is provided a displacement sensor that does not utilize optical means but, instead, utilizes electrical means to determine and quantify an amount of movement. As is generally indicated in Figure 15, according to a this preferred embodiment there is provided an electrical circuit 1500 which includes a movable contact bar 1510 which is used in combination with spaced apart extensions 1520 to determine an amount of displacement, the contact bar 1510 and the extensions 1520 being configured to be movable with respect to each

other. Then, as the contact member **1500** moves downward (with respect to the extensions **1520** in the illustration), it will successively encounter additional ones of the extensions **1520**, each of which preferably is associated with one or more resistors **1530** as is pictured in Figure **15**. Engaging an extension **1520** preferable adds an
5 additional resistor **1530** to the circuit. Thus, by monitoring the resistance (or, alternatively, any other similar electrical property) of this circuit it will be possible to determine the number of extensions **1520** that have been contacted and, thus, at least the approximate location of the contact bar **1510** and, hence, the amount of displacement experienced by the elements of this circuit **1500**.

10 According to another electrical embodiment, there is provided a sensor substantially as described above, but wherein a plurality of circuits similar to circuit **1500** are arranged together in such a manner as to provide increased precision in measurement as compared with the embodiment of Figure **15**. In more particular, the instant embodiment features a plurality of contact bars **1710**, **1712**, and **1714**, each of
15 which is placed proximate to an electrically isolated bank of extensions. In the preferred embodiment, each of the contact bars **1710** – **1714** moves in tandem with the others. Further, in one preferred arrangement the lengths of the extensions are selected so as to provide greater precision in the measurement of displacement. That is, and by way of example only, the contact bar **1710** of switch **1780** in concert with
20 its extensions provides a first rough measure of the amount of displacement. That rough estimate is refined by switches **1785** and **1790**, depending on the position of the contact bar **1710**. For example, the lengths of the extensions of switch **1785** subdivide the length of the between extensions **1720** and **1725** so that when contact bar **1710** has made contact with extension **1720** but is not far enough advanced to be
25 in contact with extension **1725**, the contact bar **1712** will engage one or more of the

intermediate length extensions, thereby providing increased measurement resolution. Similarly in switch **1790**, its extensions are sized so as to subdivide the difference in length between extensions **1725** and **1728**. Contact bar **1714** thus provides additional resolution when bar **1710** is located between extensions **1725** and **1728**.

5 Finally, and turning now to Figure **16**, there is provided an apparatus for measuring displacement **1600**, which utilizes electrical properties that change with the stress that is placed thereon. Figure **16A** illustrates how one preferred embodiment of the instant device **1600** would appear in an unstressed condition. In a preferred arrangement, the upper surface of device **1600** will be affixed (e.g., via adhesion) to
10 one surface and the lower face of the device **1600** to another surface, such that any displacement between the two surfaces will be create stress within the instant device **1600**. Relative displacement between the two surfaces connected by the instant device **1600** will result in deformation of the sort generally depicted in Figure **16B**. In the event such distortion is experienced, in many materials the electrical properties
15 will correspondingly change. Thus, by positioning electrodes, say, on the upper and lower surface and measuring some electrical property (e.g., resistance, capacitance, etc.) of the instant device **1600**, it is possible to empirically determine how such a property varies with stress and, hence, displacement. Materials that would be suitable for use in constructing the instant device include, without limitation, PET (i.e.,
20 polyethylene). Additionally, the top surface (or, even just the “noses” on the ends of the device) could be made of a material such as piezoelectric film such that displacement (and concomitant shear / rotation of the device **1600**) would generate a voltage that is roughly proportional to the amount of displacement.

CONCLUSIONS

It should be noted that the instant invention is capable of many variations beyond those specifically disclosed herein. For example, although the preferred embodiments have utilized generally square or rectangular members as sensors, that is
5 clearly not required. With some modification the instant method could work with sensors of any shape including, without limitation, triangular, circular, etc.

It should be further be noted that, although the preferred embodiment utilizes to parallel plates as the core of sensor **100**, that is not strictly required. What is important is that the surfaces of the two sensor plates are preferably at least
10 approximately parallel with each other so as to maximize the exchange of light energy therebetween. Thus, it would be within the scope of the instant invention to use, for example, two curved sensor members if a measure of rotational displacement were sought.

Those of ordinary skill in the art will recognize that it is expected and
15 preferred that the instant sensor **100** be shielded from ambient light while it is in use to increase its accuracy. That might mean, for example, that it was positioned within a light-tight enclosure.

Additionally, it should be noted that although the instant invention is well suited to measure tension and shear in a solid, it has uses far beyond that application
20 area including, without limitation, the measurement of displacement between any two surfaces, the measurement of radial displacement, etc.

Finally, those of ordinary skill in the art will recognize that the calculations and equations presented herein are offered by way of example only and that, in practice, it might be necessary to calibrate the optical displacement switch
25 empirically. That is, the equations provided above are founded on the assumption that

light has been uniformly distributed across the face of the emitting member.

However, if that is not the case it would be well within the ability of one of ordinary skill in the art to devise an empirical means of calibrating any of the sensors disclosed herein.

5 Thus, it is apparent that there has been provided, in accordance with the invention, a patient sensor and method of operation of the sensor that fully satisfies the objects, aims and advantages set forth above. While the invention has been described in conjunction with specific embodiments thereof, it is evident that many alternatives, modifications and variations will be apparent to those skilled in the art
10 and in light of the foregoing description. Accordingly, it is intended to embrace all such alternatives, modifications and variations as fall within the spirit of the appended claims.

What is Claimed is:

1. An optical displacement sensor, comprising:
 - (a) a first optical line, said first optical line being positionable to be in optical communication with an illumination source;
 - (b) a sensor emitter, said sensor emitter having at least one emitting surface,
 - (b1) wherein said sensor emitter is in optical communication with said first optical line,
 - (b2) wherein said sensor emitter is non-diffracting and optically conductive, and,
 - (b3) wherein at least a portion of any light originating from said illumination source is emitted from said at least one emitting surfaces;
 - (c) a sensor receiver, said sensor receiver having at least one receiving surface, said sensor receiver being positioned to be proximate to said sensor emitter and in optical communication therewith,
 - (c1) wherein said sensor receiver is non-diffracting and optically conductive,
 - (c2) wherein at least one of said receiving surfaces is in optical communication with at least one of said emitting surfaces,
 - (c3) wherein at least a portion of any light emitted from said emitting surface is received by said receiving surface, and,
 - (c4) wherein said sensor receiver and said sensor emitter are movable with respect to each other, wherein an amount of light received by said receiving surface varies with any such movement, and wherein said amount of light received by said receiving surface is representative of an amount of displacement between said emitting surface and said receiving surface; and,

(d) a second optical line, said second optical line being in optical communication with said sensor receiver, said second optical line being at least for transmitting at least a portion of any light received by said receiving surface.

2. An apparatus according to claim 1, wherein said sensor receiver and said sensor emitter are both a same size.

3. An apparatus according to claim 1, wherein said sensor receiver and said sensor emitter are both a same size square.

4. An apparatus according to claim 1, wherein said receiving surface has a plurality of different colored regions thereon, each of said plurality of different colored regions permitting light of a different limited wavelength band to pass therethrough and to said second optical conduit.

5. An apparatus according to claim 1, wherein said emitting surface and said receiving surface are substantially parallel with each other.

6. An apparatus according to claim 1, further comprising:

(e) at least one photo sensitive element in optical communication with said second optical line, said photosensitive element for converting at least a portion of any light transmitted from said receiving surface into an electronic signal.

7. An apparatus according to claim 6, wherein said sensor receiver receiving surface includes a plurality of regions thereon, each of said different regions permitting a different

frequency band of light to pass therethrough.

8. An apparatus according to claim 7, wherein there are a plurality of photo sensitive elements in optical communication with said second optical line, and wherein each of said plurality of photo sensitive elements is responsive to a different band of light frequencies.

9. An optical displacement sensor, comprising:

(a) a first optical line, said first optical line being positionable to be in optical communication with at least one illumination source;

(b) a sensor emitter, said sensor emitter having at least one emitting surface,

(b1) wherein said sensor emitter is in optical communication with said first optical line,

(b2) wherein said sensor emitter is non-diffracting and optically conductive, and,

(b3) wherein at least a portion of any light originating from said illumination source is emitted from said at least one emitting surfaces;

(c) a sensor receiver, said sensor receiver having at least one receiving region, said sensor receiver being positioned to be proximate to said sensor emitter and in optical communication therewith,

(c1) wherein said sensor receiver is non-diffracting and optically conductive,

(c2) wherein at least one of said receiving regions is in optical communication with at least one of said emitting surfaces,

(c3) wherein at least a portion of any light emitted from said emitting surface is received by at least one of said receiving regions, and,

(c4) wherein said sensor receiver and said sensor emitter are movable with

respect to each other, wherein an amount of light received by said receiving region varies with any such movement, and wherein said amount of light received by said receiving surface is representative of an amount of displacement between said emitting surface and said receiving surface; and,

(d) at least one sensing optical line, said sensing optical line being in optical communication with said sensor receiver, said sensing optical line being at least for transmitting at least a portion of any light received by said receiving surface.

10. An apparatus according to claim 9, wherein there are a plurality of receiving regions on said receiving surface and wherein there are a corresponding plurality of sensing optical lines, each of said plurality of sensing optical lines being in optical communication with at least one of said receiving regions.

11. An apparatus according to claim 10, wherein each of said sensing optical lines is in optical communication with a photosensitive element, each of said photosensitive elements for converting at least a portion of any light transmitted from said receiving surface into an electronic signal.

12. An optical displacement sensor, comprising:

(a) a first optical line, said first optical line being positionable to be in optical communication with an illumination source;

(b) a non-diffracting and substantially translucent sensor emitter, said sensor emitter having at least one emitting surface,

(b1) wherein said sensor emitter is in optical communication with said first optical line,

- (b2) wherein said sensor emitter is optically conductive, and,
- (b3) wherein at least a portion of any light originating from said illumination source is emitted from said at least one emitting surfaces;
- (c) a non-diffracting and substantially translucent sensor receiver, said sensor receiver having at least one receiving surface, said sensor receiver being positioned to be proximate to said sensor emitter and in optical communication therewith,
 - (c1) wherein said sensor receiver is optically conductive,
 - (c2) wherein at least one of said receiving surfaces is in optical communication with at least one of said emitting surfaces,
 - (c3) wherein at least a portion of any light emitted from said emitting surface is received by said receiving surface, and,
 - (c4) wherein said sensor receiver and said sensor emitter are movable with respect to each other, wherein a magnitude of light received by said receiving surface varies with any such movement, and wherein said magnitude light received by said receiving surface is representative of an amount of displacement between said emitting surface and said receiving surface; and,
- (d) a second optical line, said second optical line being in optical communication with said sensor receiver, said second optical line being at least for transmitting at least a portion of any light received by said receiving surface.

13. An apparatus according to claim 12, wherein said sensor receiver and said sensor emitter are both a same size.

14. An apparatus according to claim 12, wherein said sensor receiver and said sensor emitter are both a same size square.

15. An apparatus according to claim 12, wherein said receiving surface has a plurality of different colored regions thereon, each of said plurality of different colored regions permitting light of a different limited wavelength band to pass therethrough and to said second optical conduit.

16. An apparatus according to claim 12, wherein said emitting surface and said receiving surface are substantially parallel with each other.

17. An apparatus according to claim 12, farther comprising:

(e) at least one photo sensitive element in optical communication with said second optical line, said photosensitive element for converting at least a portion of any light transmitted from said receiving surface into an electronic signal.

18. An apparatus according to claim 17, wherein said sensor receiver receiving surface includes a plurality of regions thereon, each of said different regions permitting a different frequency band of light to pass therethrough.

19. An apparatus according to claim 12, wherein there are a plurality of photo sensitive elements in optical communication with said second optical line, and wherein each of said plurality of photo sensitive elements is responsive to a different band of light frequencies.

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Figure 1

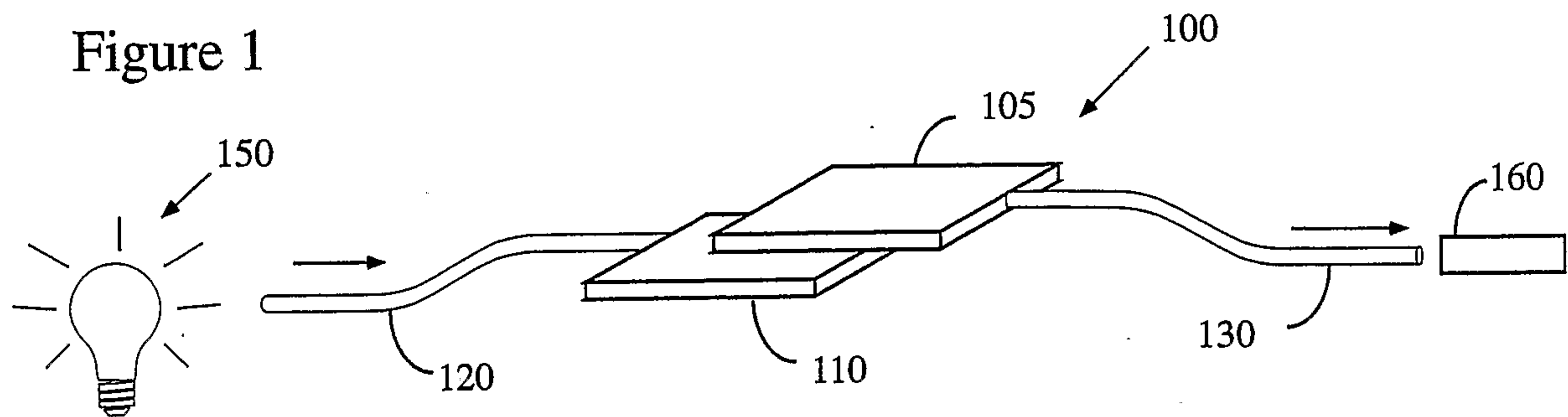


Figure 2

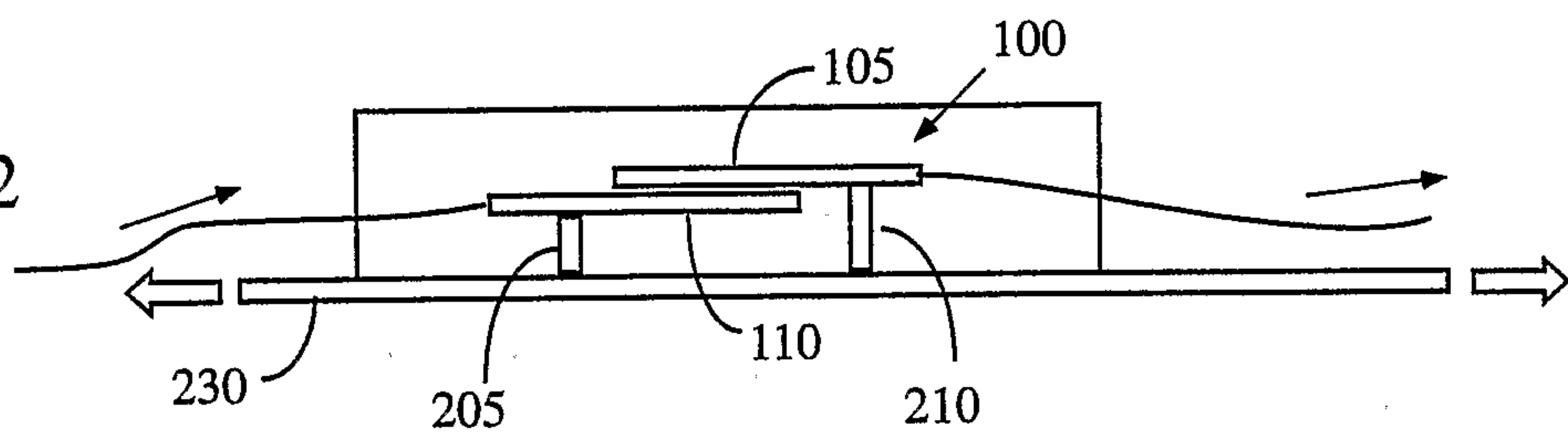


Figure 3

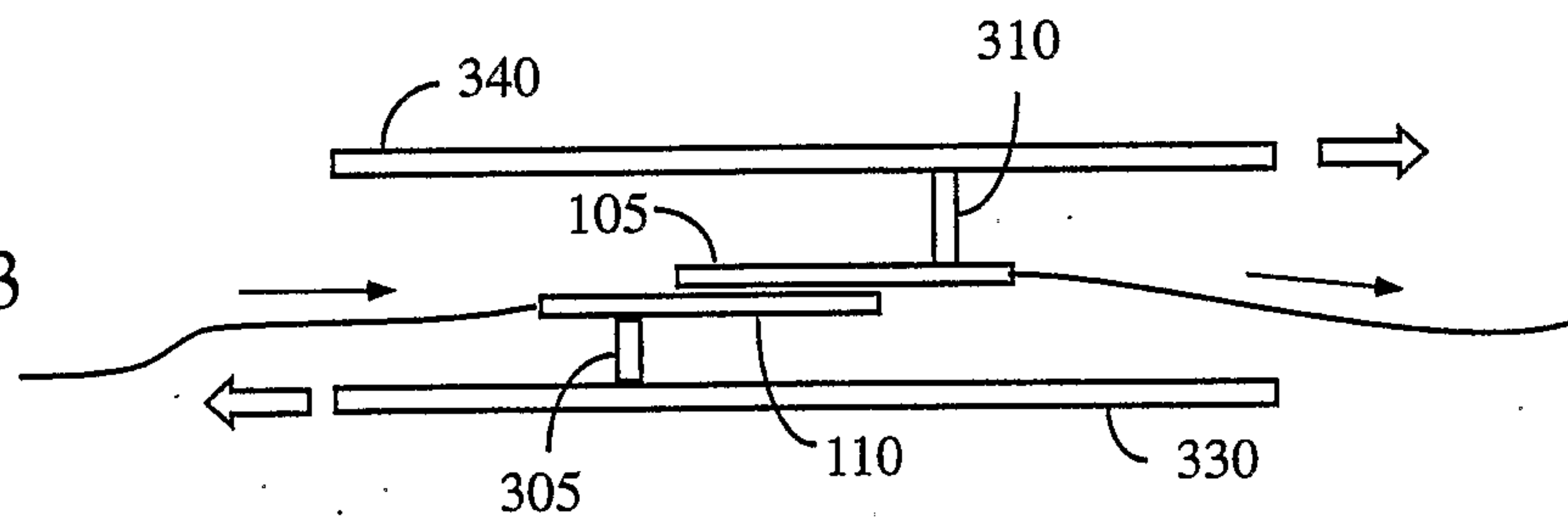


Figure 4A

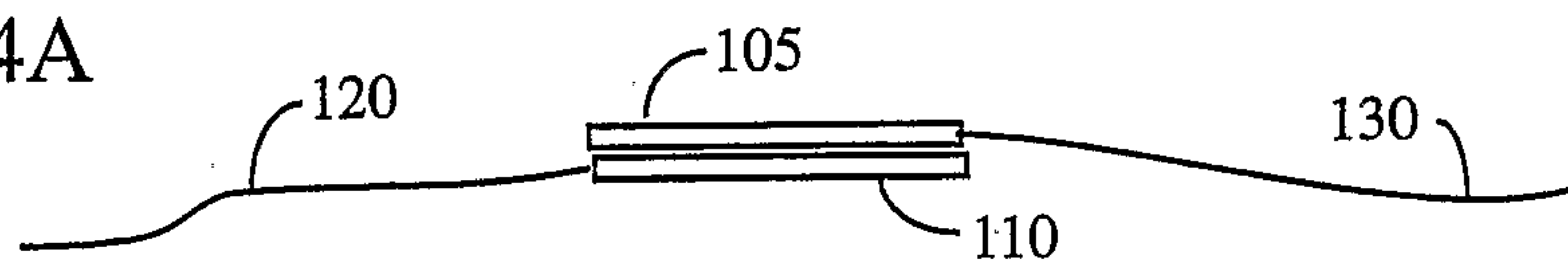
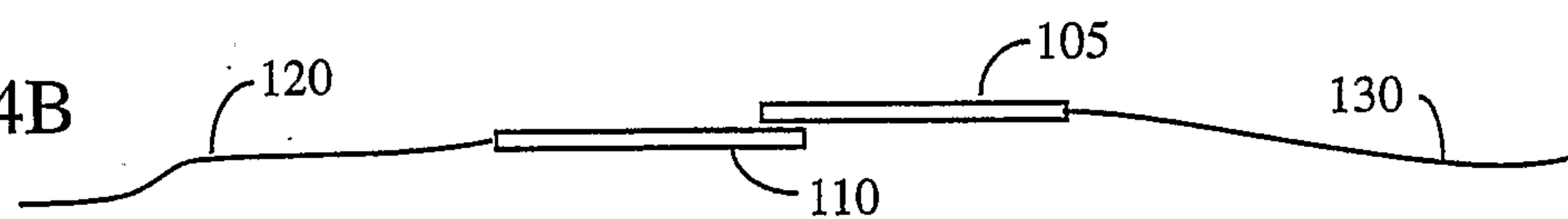


Figure 4B



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Figure 5

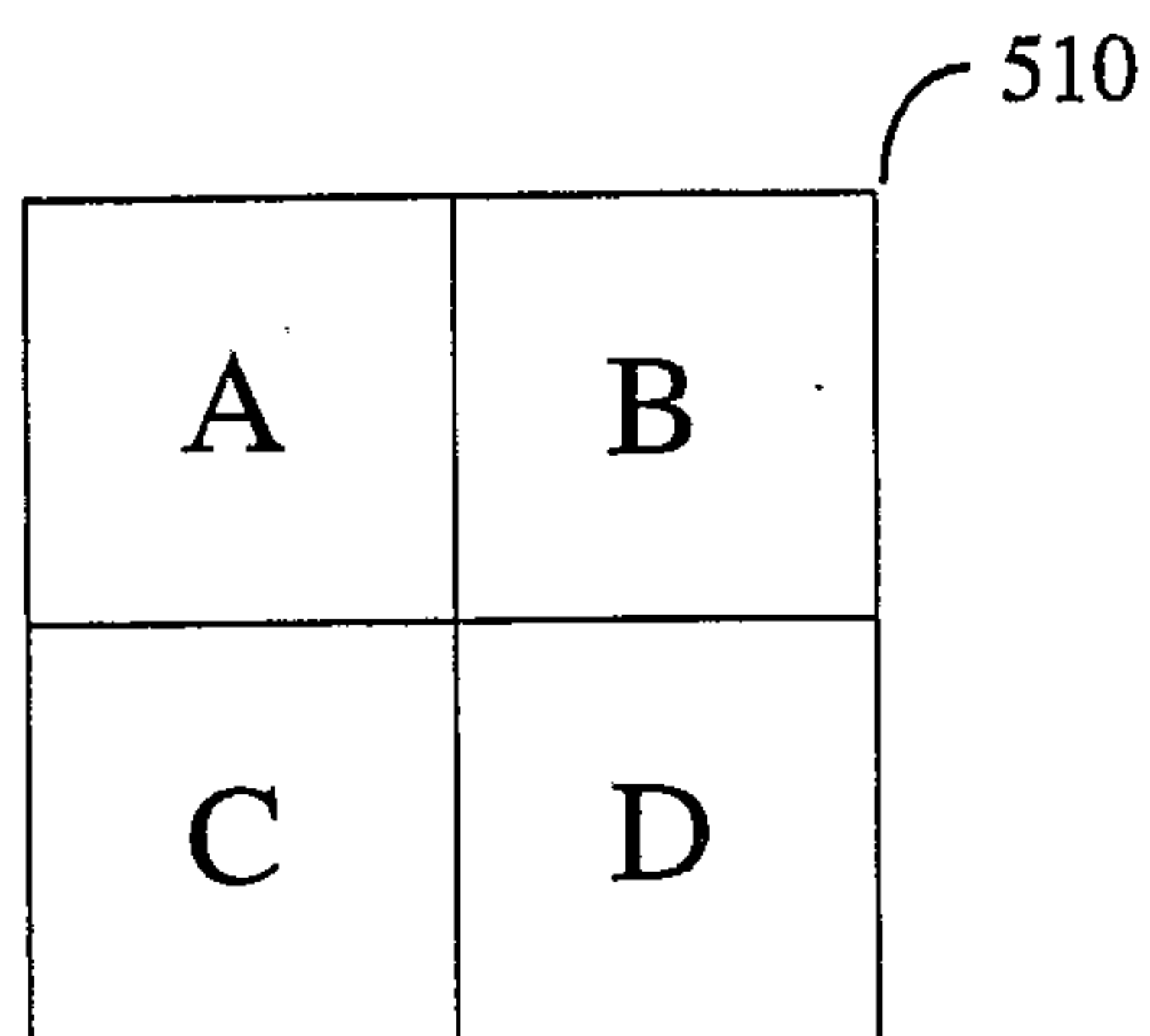


Figure 6

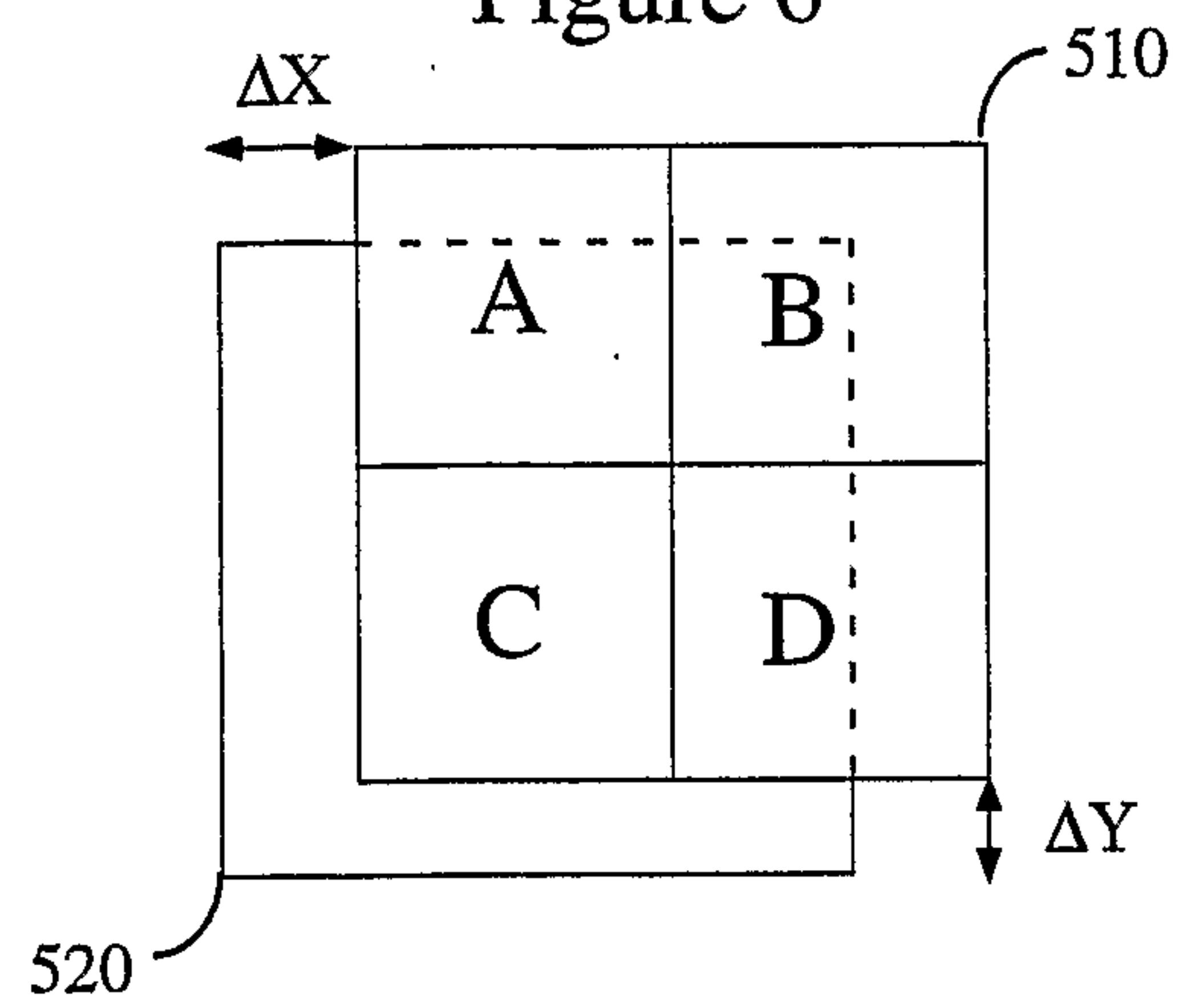


Figure 7

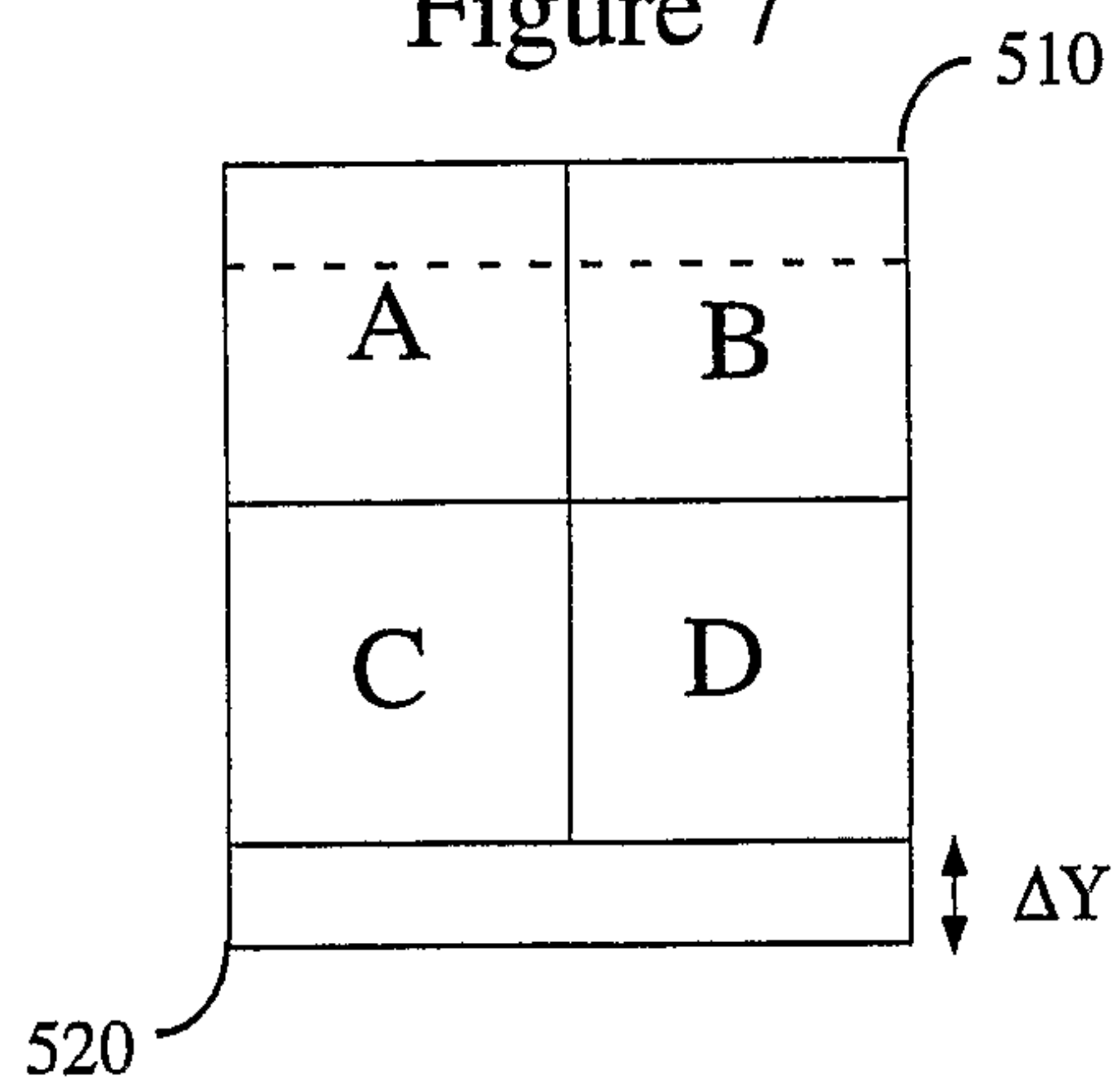
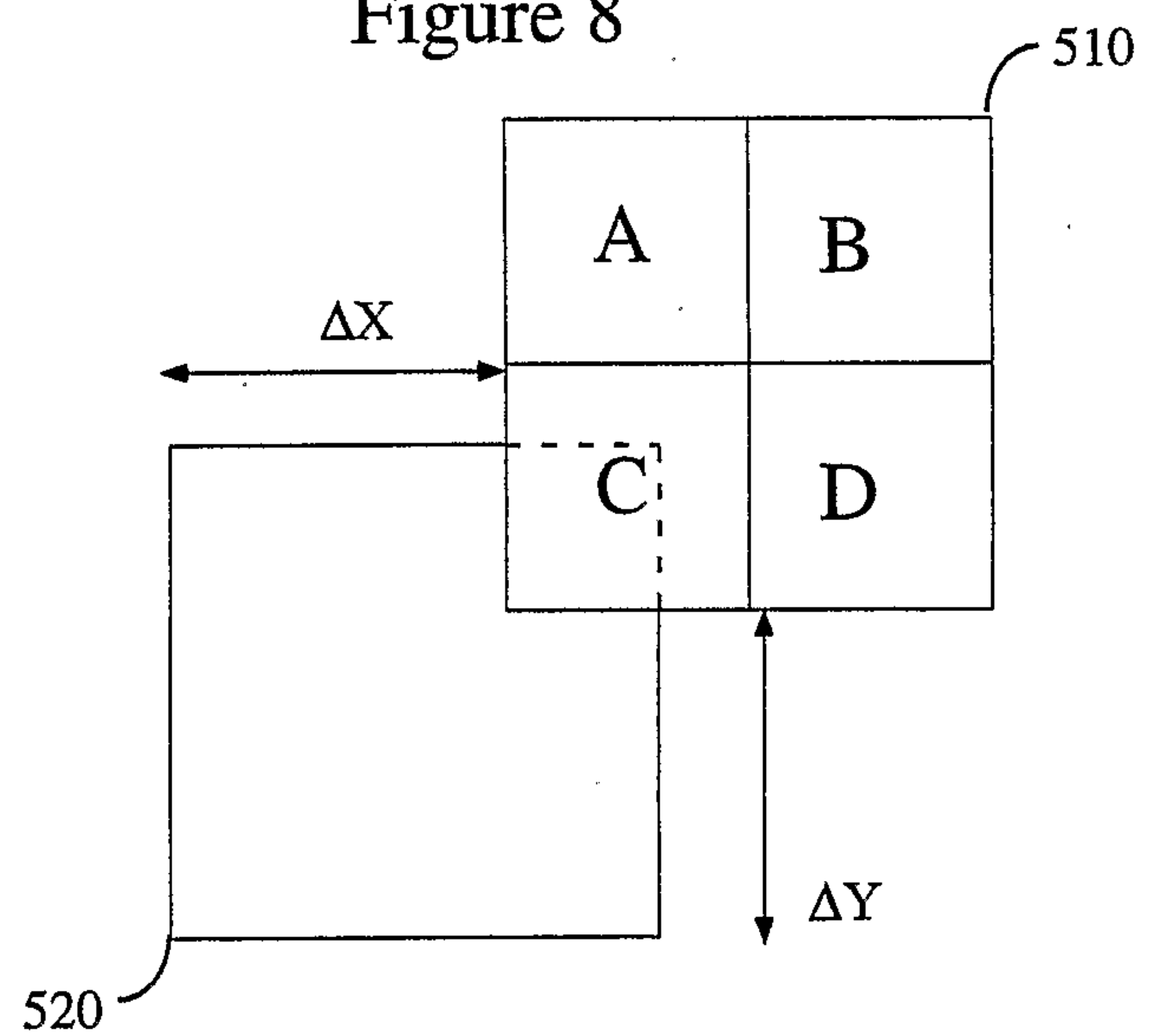


Figure 8



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Figure 9

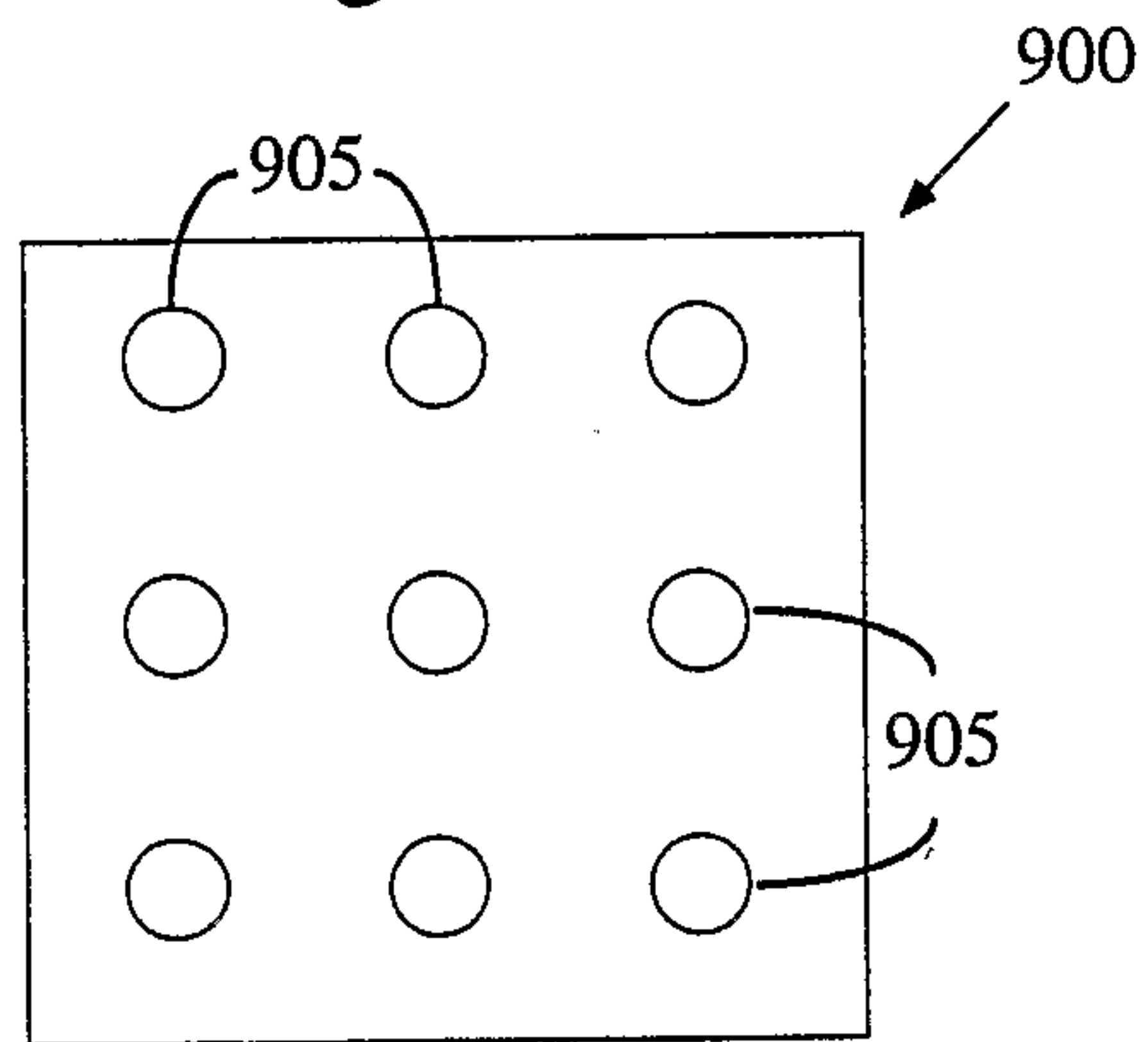


Figure 18

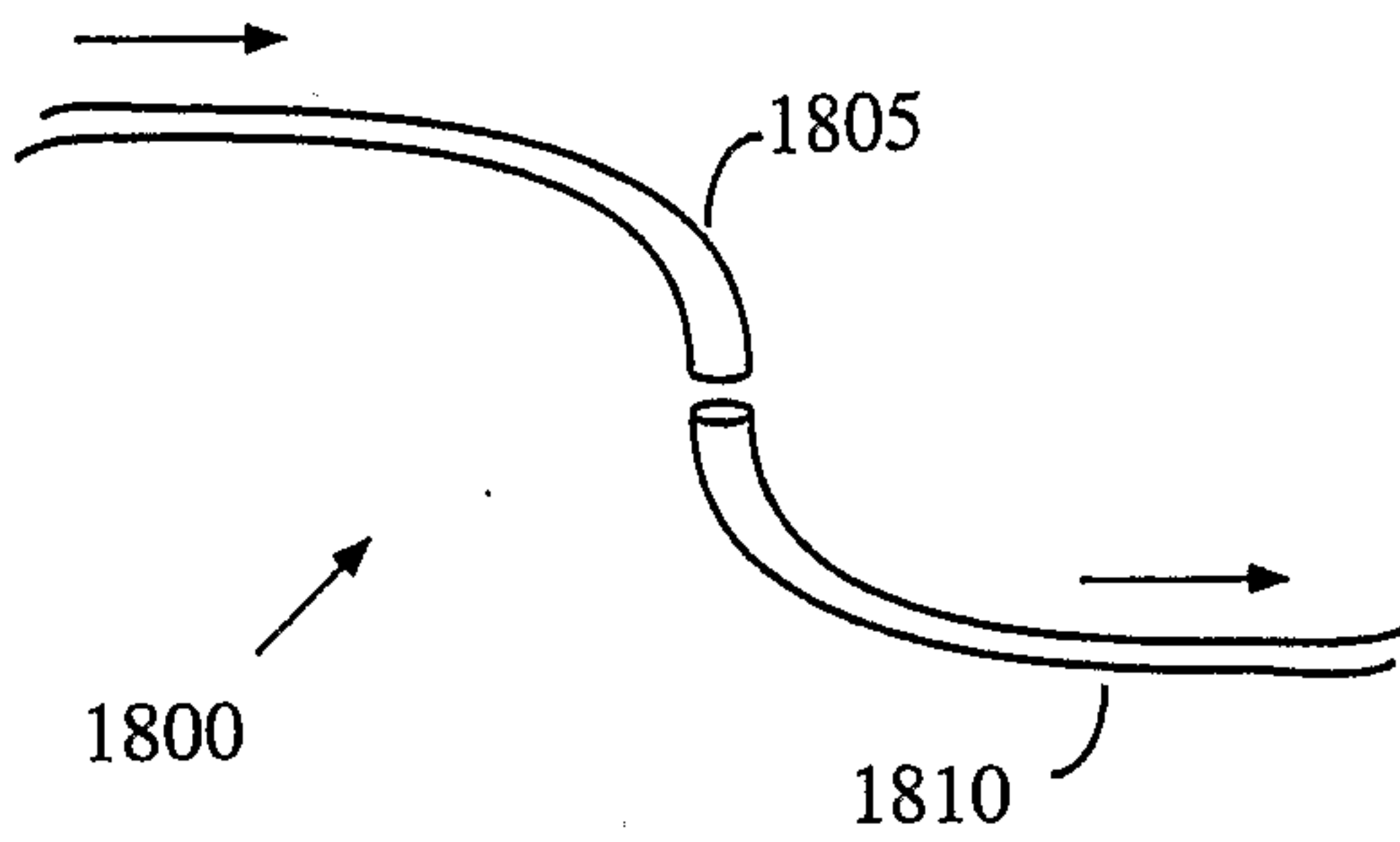


Figure 10

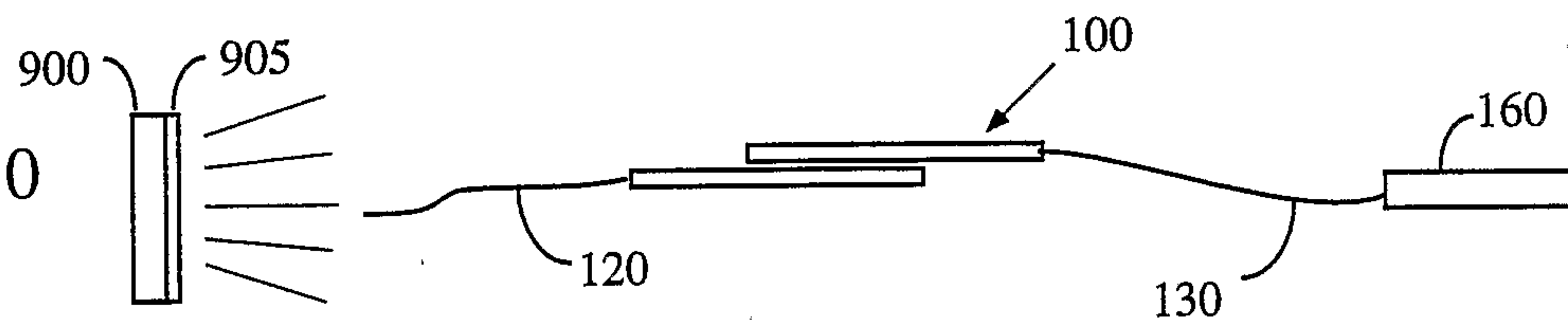


Figure 11

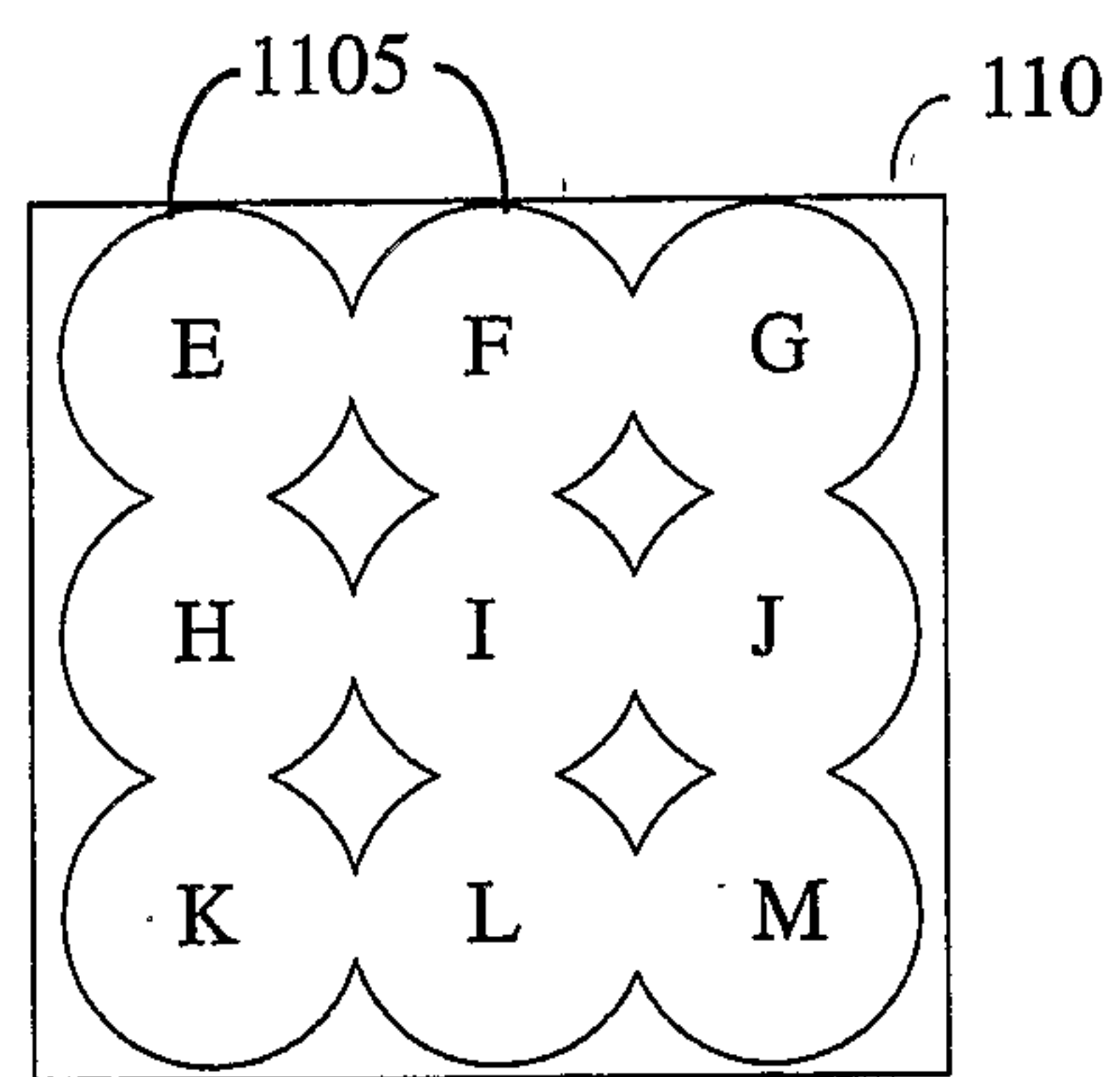
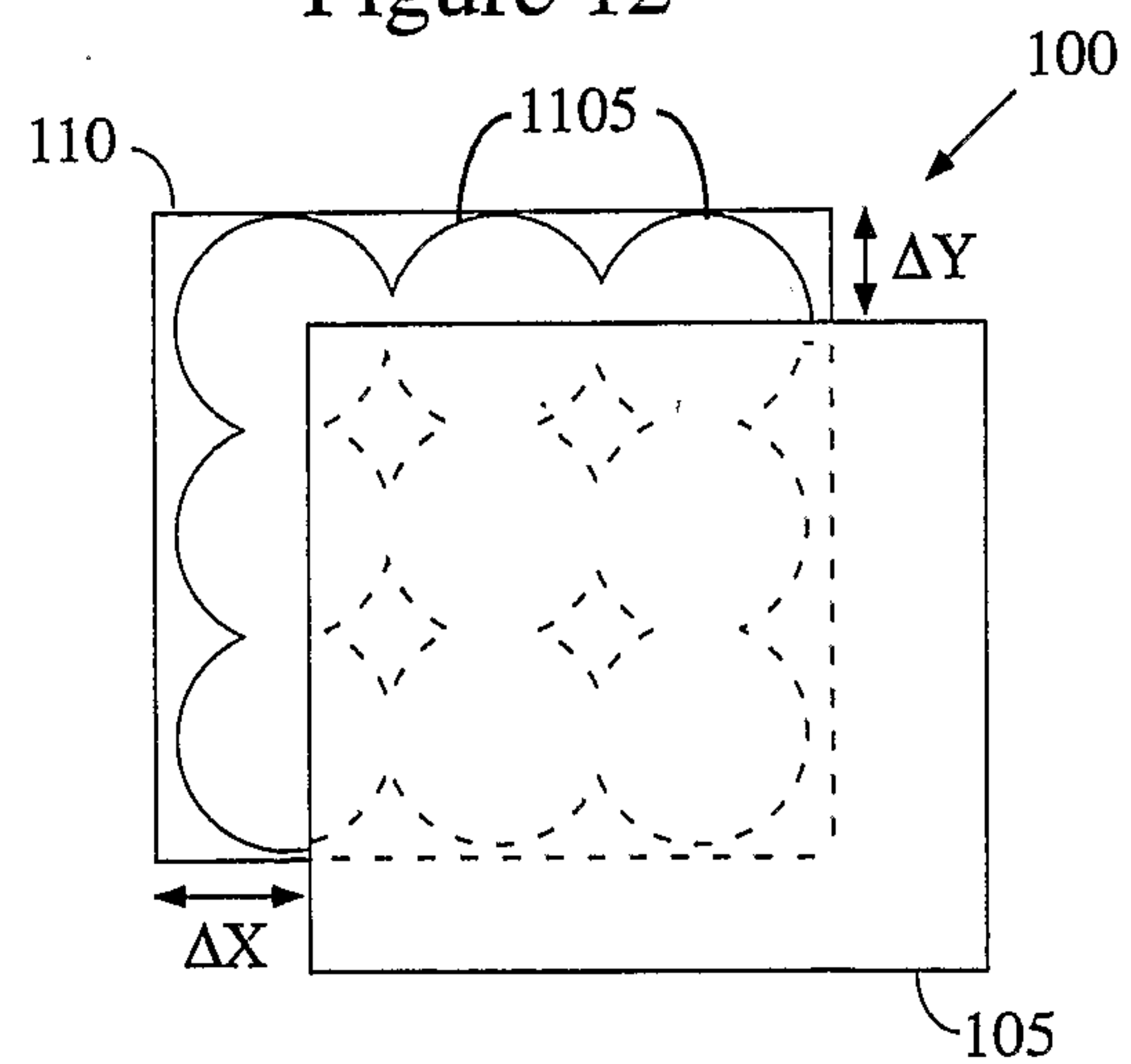


Figure 12



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Figure 13A

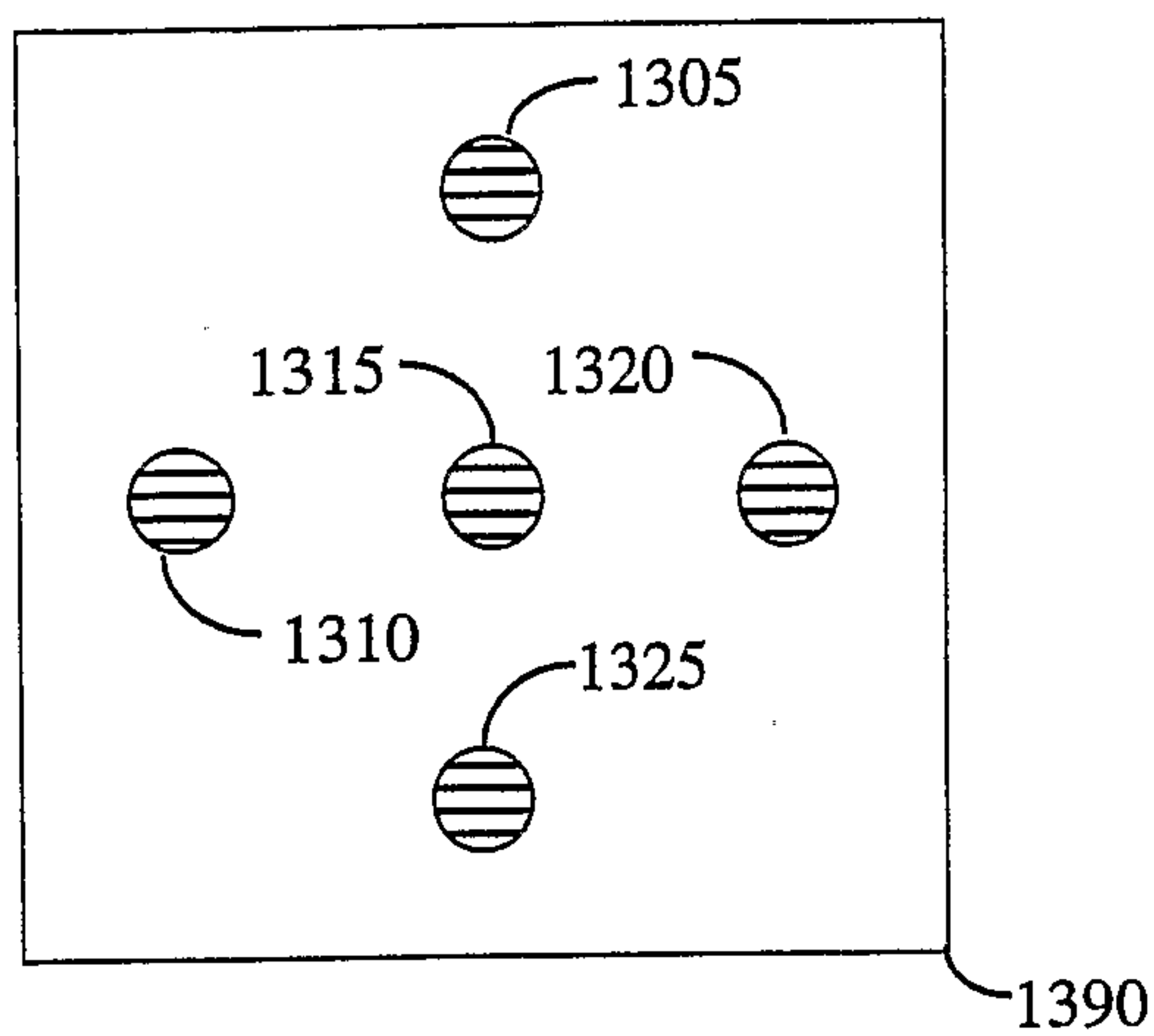


Figure 13B

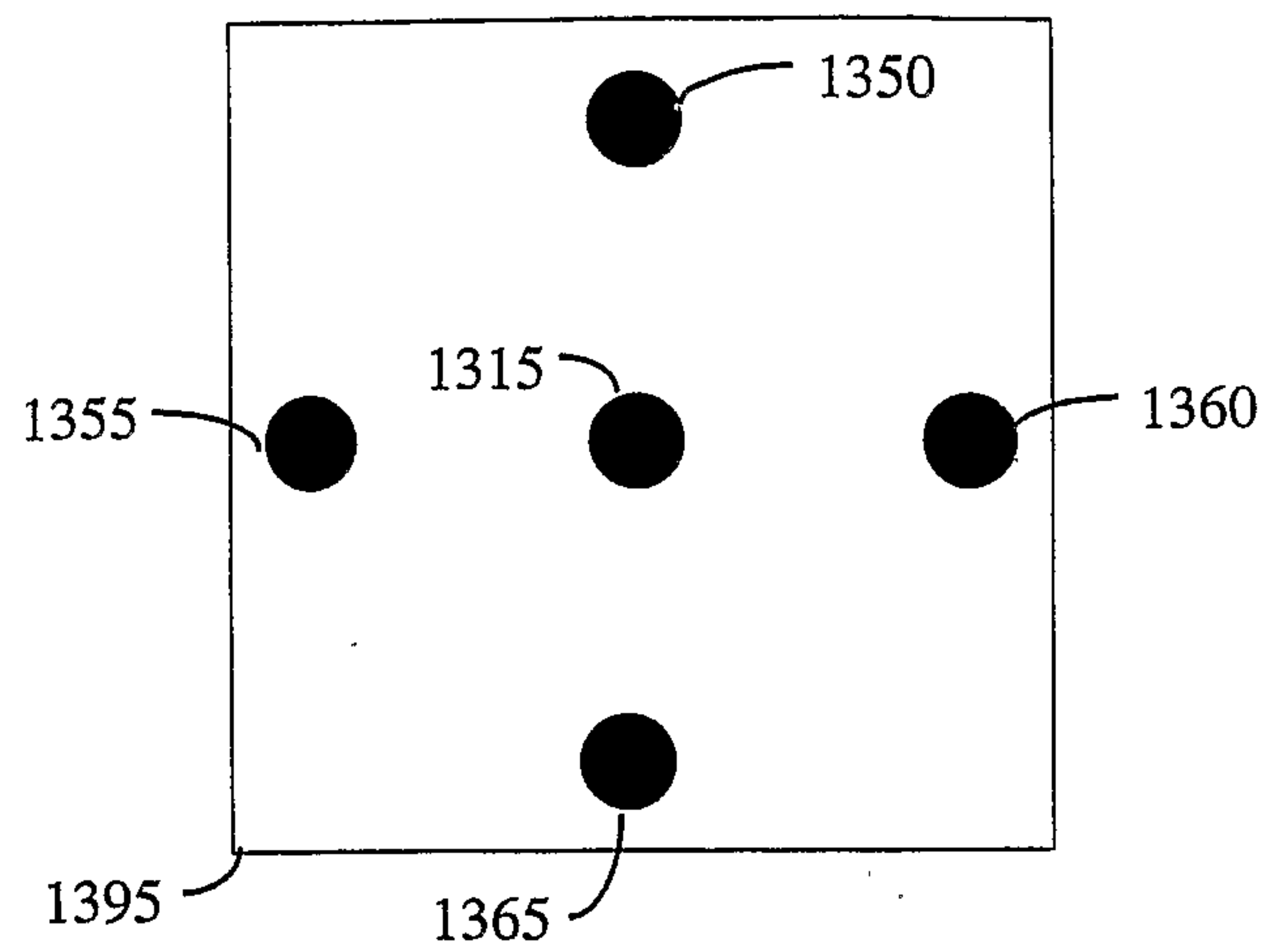


Figure 13C

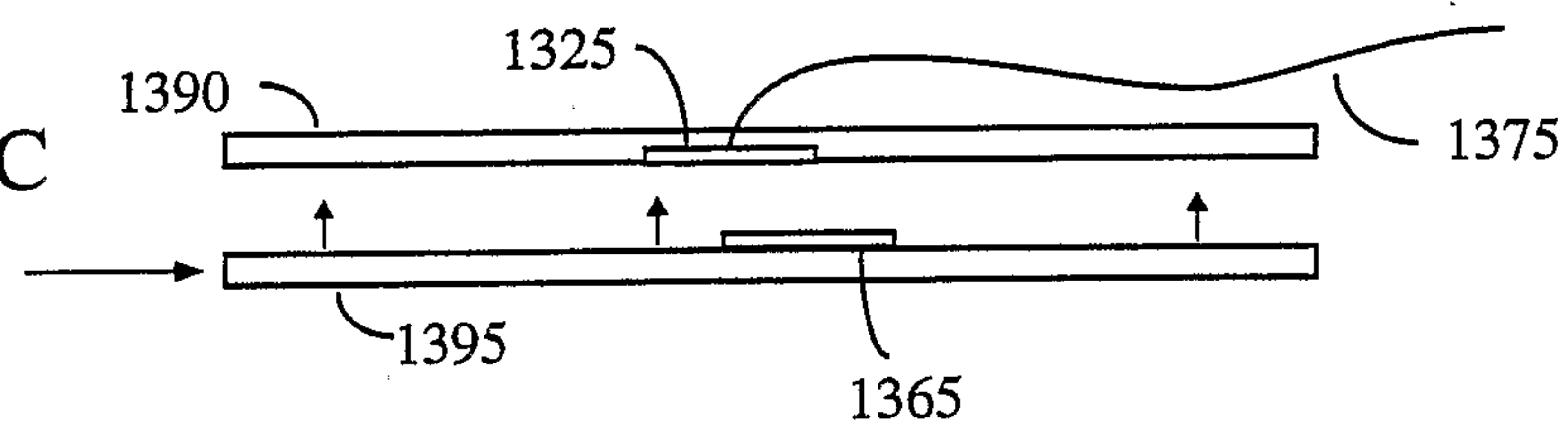


Figure 14A

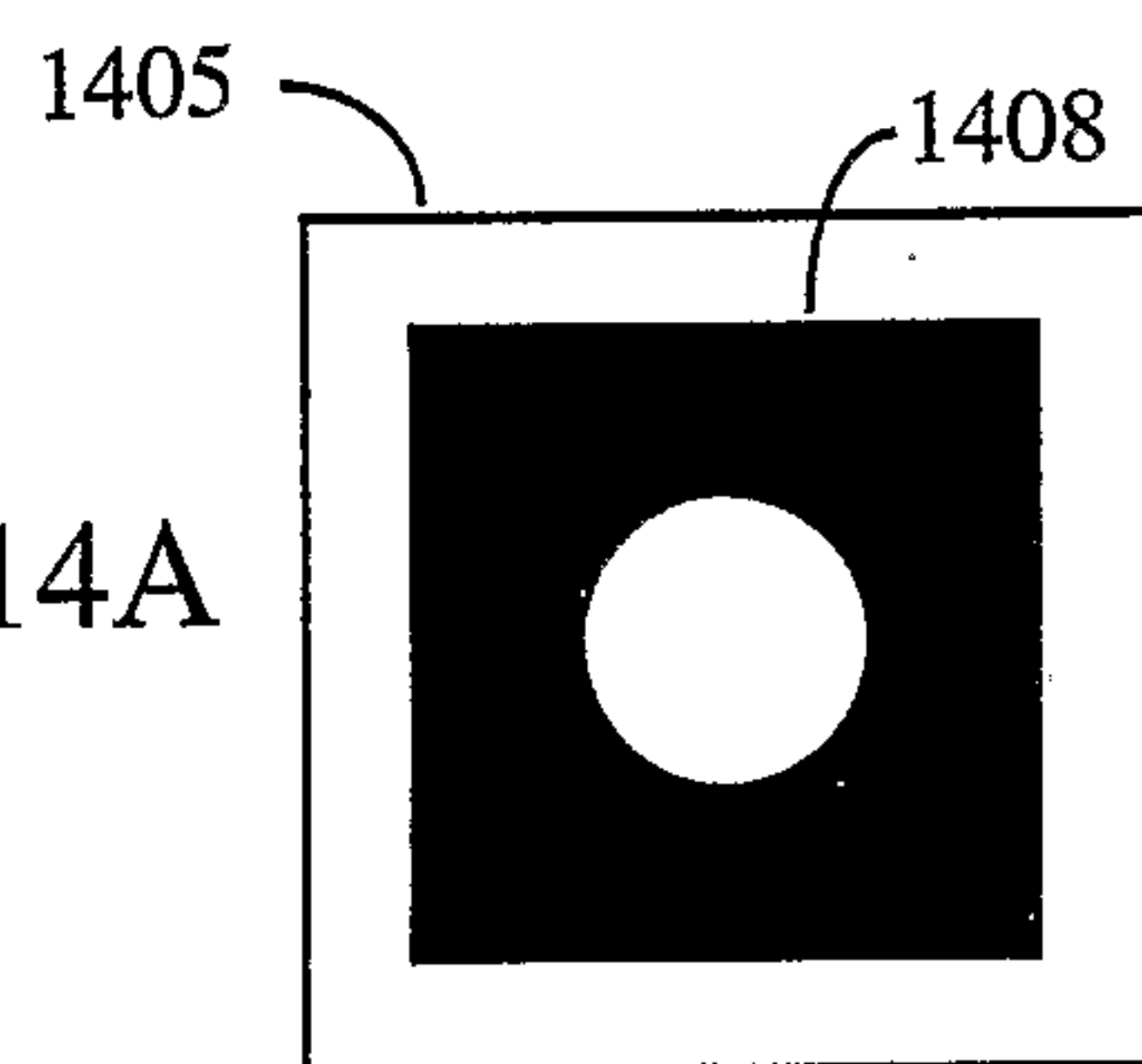


Figure 14B

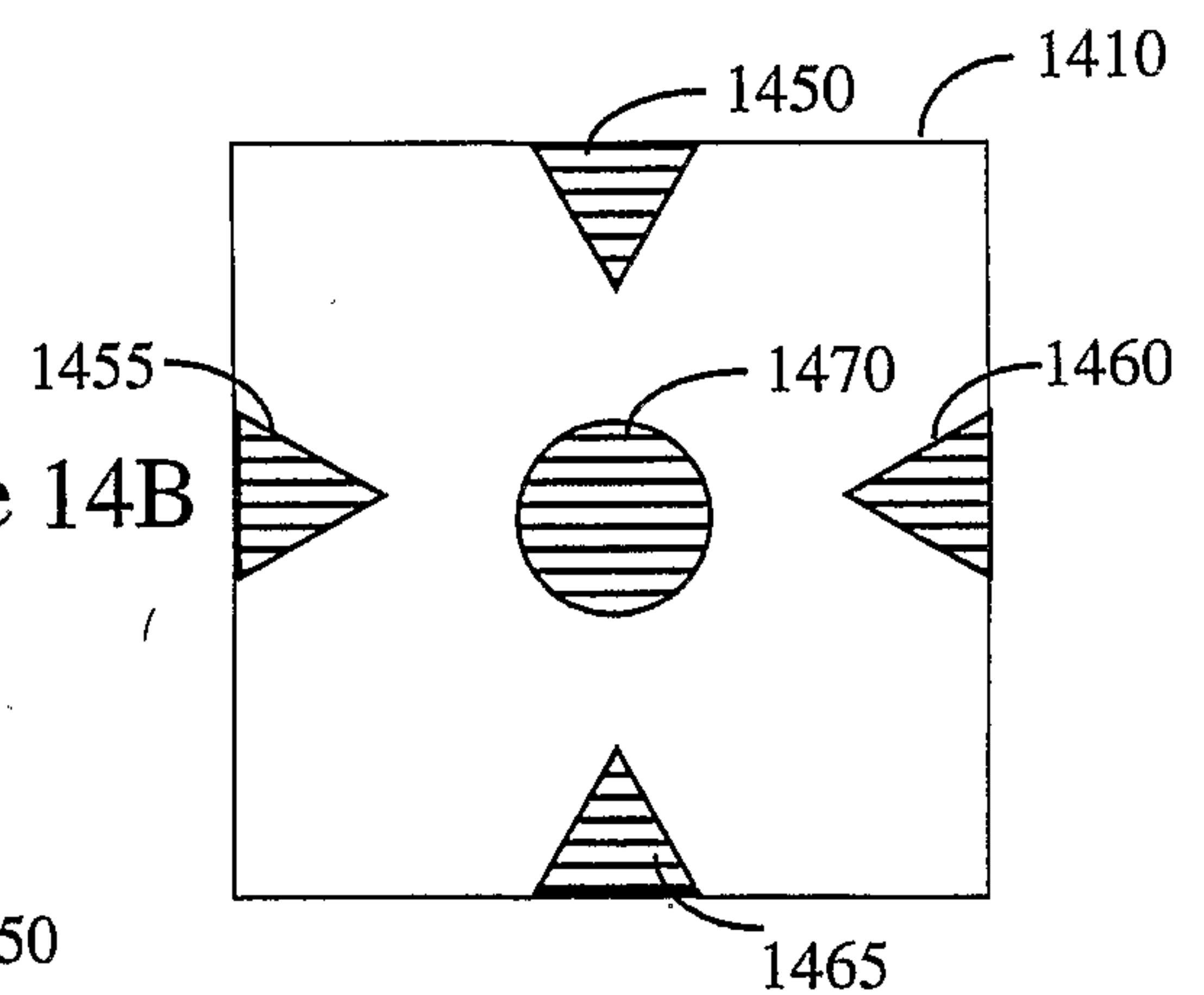
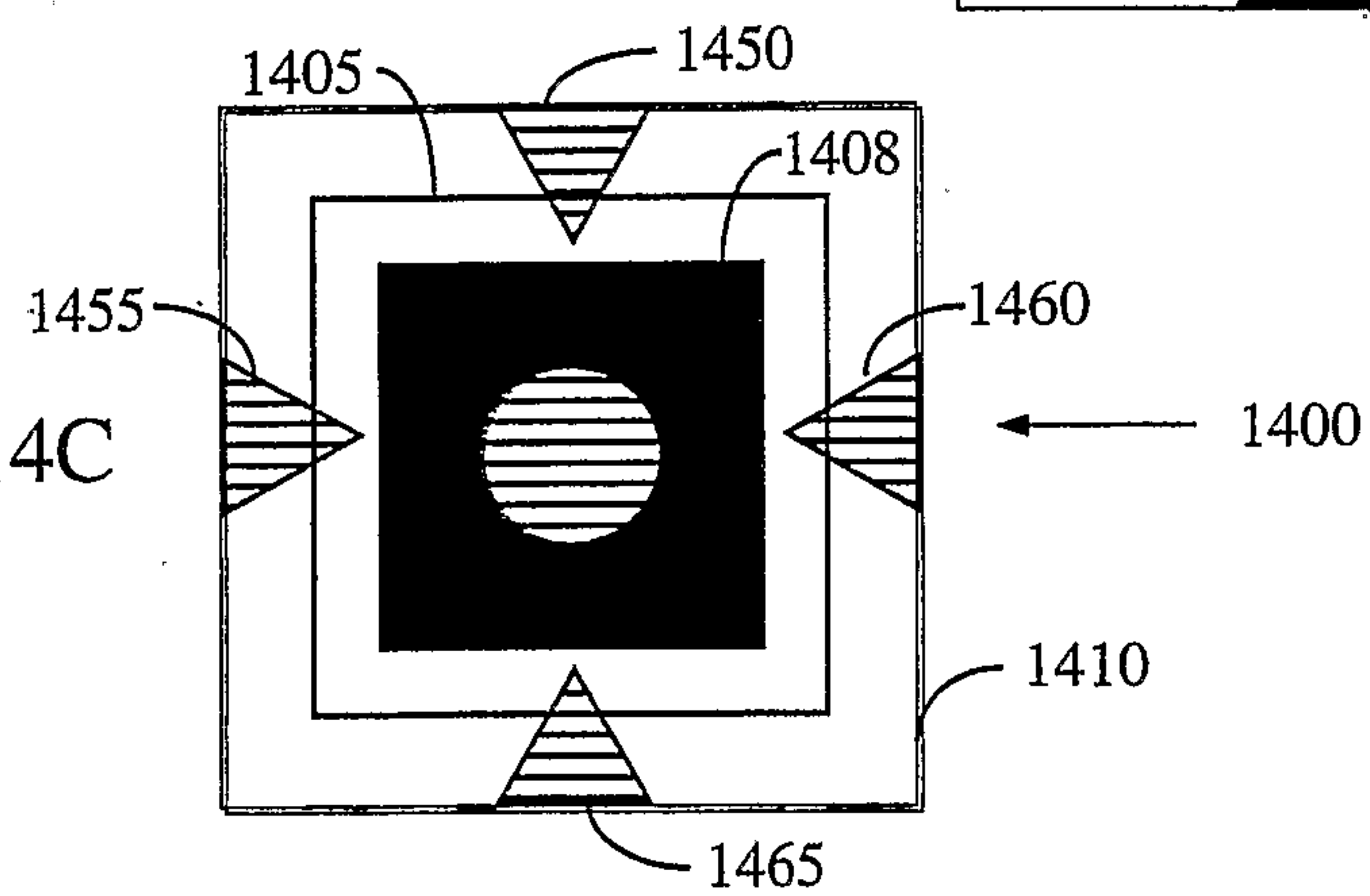


Figure 14C



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Figure 15

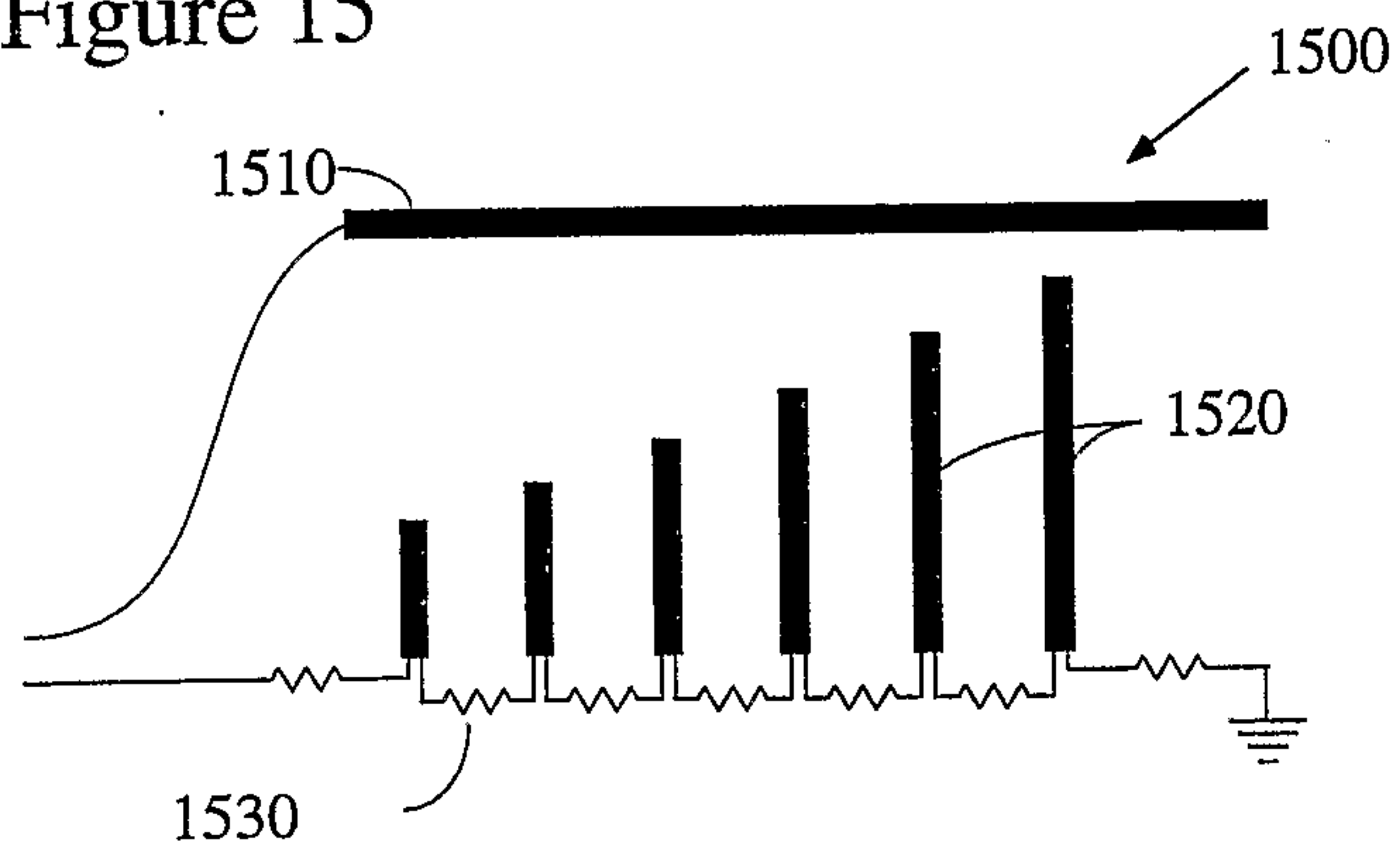


Figure 16A

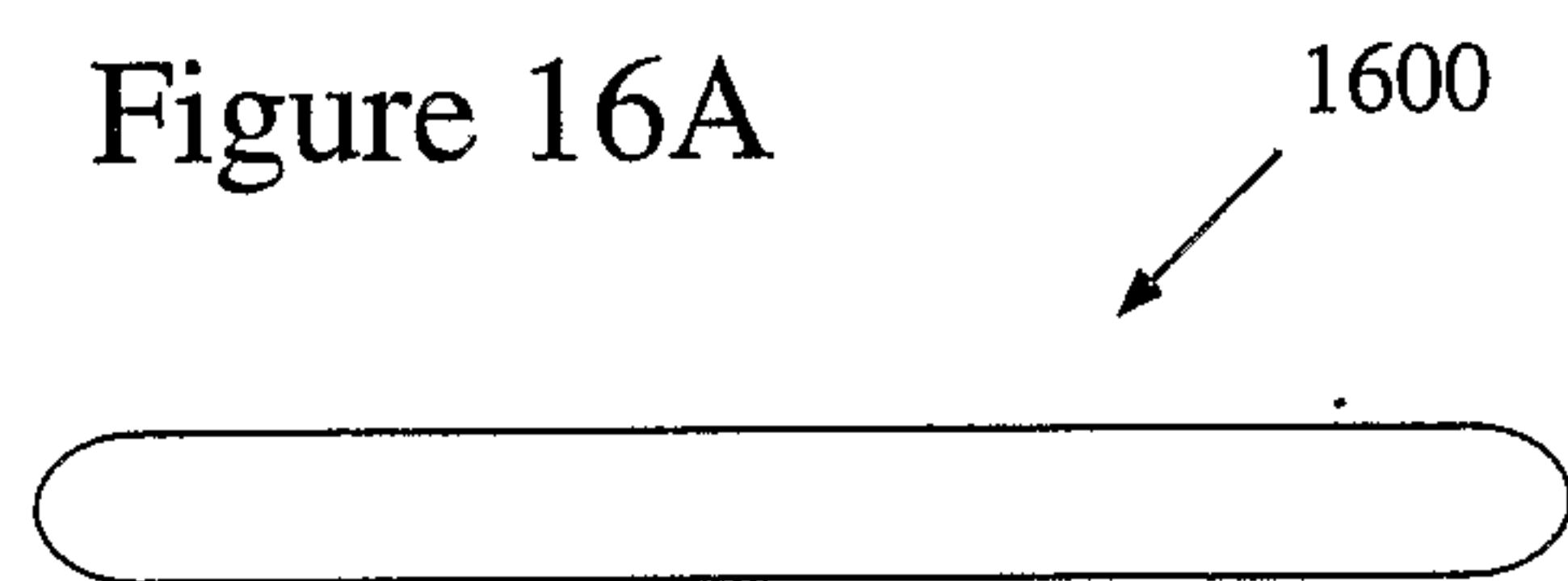


Figure 16B

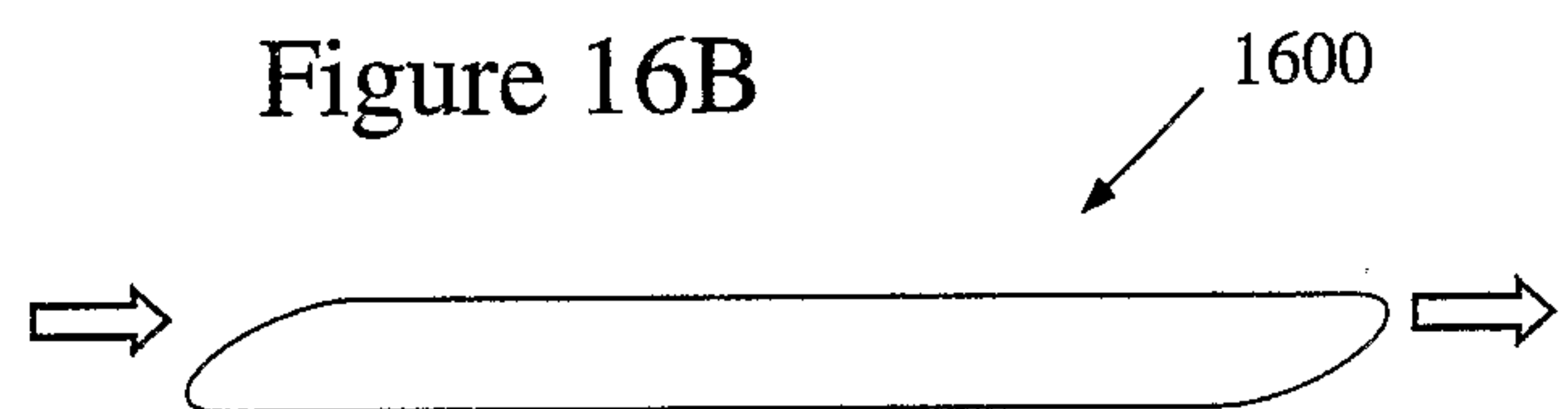


Figure 17

