



(51) International Patent Classification:
G01V 1/30 (2006.01) **G06F 19/00** (2006.01)
G01V 1/28 (2006.01)

(21) International Application Number:
PCT/US2010/041740

(22) International Filing Date:
12 July 2010 (12.07.2010)

(25) Filing Language: English

(26) Publication Language: English

(30) Priority Data:
61/225,109 13 July 2009 (13.07.2009) US
12/643,360 21 December 2009 (21.12.2009) US

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(81) Designated States (unless otherwise indicated, for every
kind of national protection available): AE, AG, AL, AM,
AO, AT, AU, AZ, BA, BB, BG, BH, BR, BW, BY, BZ,
CA, CH, CL, CN, CO, CR, CU, CZ, DE, DK, DM, DO,
DZ, EC, EE, EG, ES, FI, GB, GD, GE, GH, GM, GT,
HN, HR, HU, ID, IL, IN, IS, JP, KE, KG, KM, KN, KP,
KR, KZ, LA, LC, LK, LR, LS, LT, LU, LY, MA, MD,
ME, MG, MK, MN, MW, MX, MY, MZ, NA, NG, NI,
NO, NZ, OM, PE, PG, PH, PL, PT, RO, RS, RU, SC, SD,
SE, SG, SK, SL, SM, ST, SV, SY, TH, TJ, TM, TN, TR,
TT, TZ, UA, UG, US, UZ, VC, VN, ZA, ZM, ZW.

(84) Designated States (unless otherwise indicated, for every
kind of regional protection available): ARIPO (BW, GH,

[Continued on next page]

(54) Title: TAR ESTIMATION

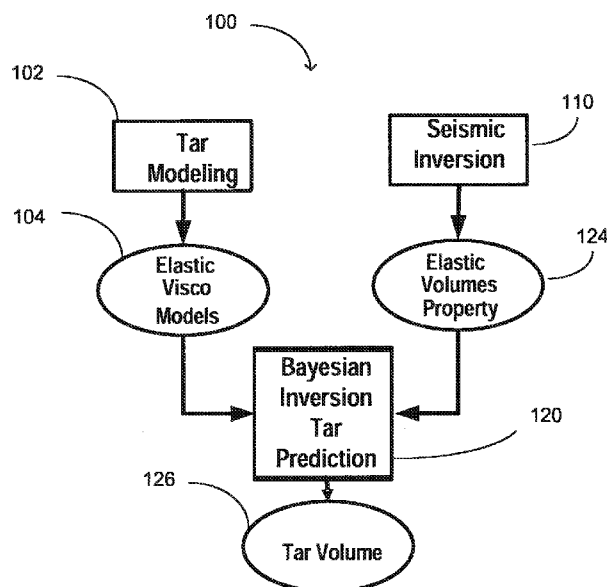


Fig. 1

(57) Abstract: A method to predict tars and tar sands in petroleum exploration and production in a subsurface volume by building a viscoelastic property model of the volume using rock behavior including tars together with seismic inversion to derive a lithology volume identifying tars.



GM, KE, LR, LS, MW, MZ, NA, SD, SL, SZ, TZ, UG, ZM, ZW), Eurasian (AM, AZ, BY, KG, KZ, MD, RU, TJ, TM), European (AL, AT, BE, BG, CH, CY, CZ, DE, DK, EE, ES, FI, FR, GB, GR, HR, HU, IE, IS, IT, LT, LU, LV, MC, MK, MT, NL, NO, PL, PT, RO, SE, SI, SK, SM, TR), OAPI (BF, BJ, CF, CG, CI, CM, GA, GN, GQ, GW, ML, MR, NE, SN, TD, TG).

Published:

— *without international search report and to be republished upon receipt of that report (Rule 48.2(g))*

TAR ESTIMATION

CROSS-REFERENCE TO RELATED APPLICATIONS

[0001] The present application claims priority under 35 U.S.C. §119(e) to United States Provisional Application Serial Number 61/225,109 filed on 7/13/2009, with the same title and by the same inventors (Attorney Docket No. 594-25672-US-PRO).

STATEMENT REGARDING FEDERALLY SPONSORED RESEARCH OR DEVELOPMENT

[0002] Not applicable.

BACKGROUND OF THE INVENTION

Field of the Invention

[0003] This invention disclosure relates to petroleum exploration and production, a method of tar/tar sand prediction to reduce cost and risk of oil exploration and production.

Discussion of Related Art

[0004] This section of this document is intended to introduce various aspects of the art that may be related to various aspects of the present invention described and/or claimed below. This section provides background information to facilitate a better understanding of the various aspects of the present invention. As the section's title implies, this is a discussion of *related* art. That such art is related in no way implies that it is also prior art. The related art may or may not be *prior* art. It should therefore be understood that the statements in this section of this document are to be read in this light, and not as admissions of prior art.

[0005] Tar is a dark brown or black bituminous usually odorous viscous liquid obtained by destructive distillation of organic material. It constitutes the heavy end of hydrocarbon with high content of asphaltenes. In one form, tar and residue oil are found in petroleum reservoirs. These tars often affect oil productivity due to their low permeability. Tars are also found in the porous sands near fault zones or in the vicinity of base of salt. These tars or tar sands are usually pressurized and some of them are mobile once being penetrated by drilling. As the viscous tar fluid flows into the borehole, it may be very

difficult to drill through, thus, causing serious problem for drilling and often resulting loss of operation time and money.

[0006] Tars are present in many oil reservoirs throughout the world. They are quite common in carbonate reservoirs in the Middle-East, including several of the ten largest reservoirs in the world. Tars are usually – but not always – located at or near present-day oil/water contacts. The tar saturation is commonly unpredictable, at least at the level of detail needed to effectively place injection wells to minimize loss of mobile oil above the tar and to minimize the risk of sidetracking wells to get back above the tar.

[0007] To gain full control of these issues, many questions need to be answered: where are the tars (tar sands, tar mats) located? How many are there? What is their horizontal distribution? Do they constitute strong permeability barriers or only partial ones? Can we predict and model tar distribution in a reservoir? Placing horizontal injectors just above tar may require specific real-time geosteering technology.

[0008] Numerous cases of tar encounters during petroleum drilling were reported in the deepwater of Gulf of Mexico (Rohleder et al., 2003; Romo et al., 2007; Weatherl, 2007; Gang Han et al., 2008). The tar problem has become a technical challenge and economic risk for the deepwater drilling especially in the Gulf of Mexico. For this reason, extensive studies have been done on the physical property and diagnostic signature of tars/tar sands. However, technique for seismic-based pre-drill (prior to drilling a well) prediction is rare. In fact, some authors even indicate that the “presence of tar cannot be predicted with current seismic technology and there is not a recognized seismic signature” (Romo and others, 2007).

[0009] There is an acute need for the industry to find a way to predict the “unpredictable” tar or tar sands on a pre-drilling basis such that drilling through tar can be avoided.

[0010] **References:**

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BRIEF SUMMARY OF THE INVENTION

[0011] Methods of predicting the existence of tar/tar sands through the integration of visco-elastic modeling of tar/tar sands, and seismic inversion are disclosed. These methods delineate tar/tar sands, and other rock types in basin-scale through the integration of basin deposition and compaction history analysis, tar modeling, and simultaneous seismic inversion. The methods work in various geological formations.

BRIEF DESCRIPTION OF THE SEVERAL VIEWS OF THE DRAWINGS

[0012] A better understanding of the invention can be had when the following detailed description of the preferred embodiments is considered in conjunction with the following drawings, in which:

[0013] Figure 1 depicts a conceptual model of the tar prediction in one implementation.

[0014] Figure 2 depicts another flow chart of seismic-based tar estimation used for tar prediction.

[0015] Figure 3 depicts an example of tar prediction, a section of tar map.

[0016] Figure 4 depicts a P-wave/S-wave velocity plot in terms of temperature, which is used in a tar prediction model.

[0017] Figure 5 depicts a processing system executing the tar prediction model.

DETAILED DESCRIPTION OF THE INVENTION

[0018] The methods disclosed here use the combination of tar modeling, which describes the visco-elastic properties of the tars and tar-bearing sands in formation, and seismic inversion which describes the similar properties in the formation.

[0019] Although the methods are developed from the Gulf of Mexico deep water fields and all examples discussed below are deep water fields, the methods themselves are not limited to the Gulf of Mexico or the deep water fields. It is straight forward to adapt the method to other operation environment, such as on-shore fields or in transition fields.

[0020] Referring for Figure 1, in one embodiment, the method 100 includes Seismic Inversion 110, Tar Modeling 102 and Tar Prediction 120. The Tar Modeling 102, which is a viscoelastic property model of the interested subsurface volume, describes the viscoelastic behavior 104 of tars and tar-bearing sands in relation to the tar composition, temperature and

pressure conditions, and the background rock property calibrated with measurements if available. The model may also include viscoelastic behavior of other rocks. The Seismic Inversion 110 uses seismic survey data to derive seismic elastic property model 124 of the same subsurface volume where tar prediction is needed and where Tar Modeling 102 is done. The viscoelastic property model 104 and seismic elastic property model 124 each may have many attributes and some of which can be common. Some of the common attributes include acoustic impedance, shear impedance, Poisson's ratio, density, V_p or V_s . From these at least two models, a likelihood probability density function $p(d/m)$ of tar/tar sands and other lithology members is generated based on the modeling result 104. Posterior probability density function $p(m/d)$ is estimated through Bayesian inversion and the maximum a posteriori (MAP) rule is applied for tar/tar sands and other lithology definition in the Tar Prediction 120. As a result, the output lithology volume 126 is the lithology definition, including tars, tar sands, and other rock types (shale, sand etc.) with their associated posterior probability. When tars or tar sands are highlighted in this lithology volume, it may be referred to as a tar volume or a tar map. One such result is illustrated in Figure 3, which is discussed in more details below.

[0021] In another embodiment, referring to Figure 2, a method for pre-drill tar prediction through the integration of tar modeling and prestack seismic inversion is used. This method 200 may include some of the 7 major components. A first component 210 P/T Modeling is to model pore pressure, overburden pressure, and formation temperature with burial depth. A second component 220 Tar ViscoElastic Modeling is to model the viscoelastic property of tar as a function of tar composition, temperature and pressure conditions. One simple way of doing this is to adopt the method as described by Han et al. (2008) [4]. A third component 230 Compaction Analysis is to model and construct local lithology trends (porosity, sand/shale trends) based on compaction analysis and reference to basin deposition history. A fourth component 240 is to estimate tar-bearing sands property using the generalized Gassmann equation. An example is shown in Ciz and Shapiro, 2007 [5]. A fifth component 250 is to sample and construct the probability density function (pdf) of tar, or other rock types from the modeling result. A sixth component 260 is to derive seismic elastic property model using simultaneous prestack inversion, for example as discussed in Rasmussen, 2004 [6]. This seismic elastic property model contains many elastic attributes, similar to the attributes in the models of tars, tar sands. Finally, a seventh component 270 is to generate a lithology volume, which defines lithology type, including

tars, tar sands and other rock types through Bayesian inversion. The MAP estimation is obtained using the likelihood pdf 252 generated from fifth component 250 and the elastic attributes 262 derived from sixth component 260 as input. The end result is a lithology volume 272, including tars, tar sands, and other rock types such as sand or shale, with their corresponding a-posterior probability. The lithology volume can identify various types of rocks and is not limited to tars or tar sands.

[0022] Method 200 may assume that tars are either as porous space infill or as homogenous layers. In the former case, the tar is considered as infilling solid, viscous fluid or standard fluid depending on the tar composition and temperature and pressure condition. For the later case, the tar is considered as a homogeneous body and it supports the overburden.

[0023] Method 200 may assume that the tar behaves in a similar way as reported on the property of extremely heavy oil (Han et al., 2008 [4]), its effect on bearing rock property can be characterized by the Generalized Gassmann equation (Ciz and Shapiro, 2007 [5]). Method 200 works better if, for example, the properties of tars or tar sands are very different from other rock members, and sizable enough to be resolved from seismic measurements. The resolution of the tar volume is directly related to the resolution of the seismic measurement.

[0024] As stated above, the methods of tar estimation using seismic information may include some of the 7 major components: 210, overburden pressure, and formation temperature with burial depth; 220, viscoelastic modeling for tars; 230, basin-scale lithology trends analysis (e.g., porosity, sand/shale trends) based on compaction analysis; 240, tar-bearing sands property estimation using the generalized Gassmann equation; 250, sampling and constructing the pdf for tar (sands) based on the modeling result; 260, elastic attributes derivation using simultaneous prestack inversion; and 270, tar (sands) estimation using Bayesian inversion. The following describes each of the possible major components.

[0025] 1. Basin-scale temperature and pore pressure estimation:

[0026] Formation temperature, T_z , is estimated as a function of a reference temperature at seafloor, T_{ml} , local geothermal gradient, T_{grad} , and the burial depth ΔZ (below mudline) :

$$T_z = T_{ml} + T_{grad} \Delta Z \quad (1.1)$$

[0027] Pore pressure, P_{z_pore} , is estimated assuming hydrostatic pressure :

$$P_{z_pore} = \int_0^z \rho_{fl}(z) g(z) dz + p_0 \quad (1.2)$$

where ρ_{fl} is the pore fluid density, g is the gravity, and p_0 is the atmospheric pressure at the sea level.

[0028] The overburden pressure, $P_{z_overburden}$, is estimated using

$$P_{z_overburden} = \int_0^z \rho(z) g(z) dz + p_0 \quad (1.3)$$

where ρ is the rock bulk density.

[0029] These estimations will be calibrated whenever measurements are available. It is noted that there are other ways to estimate these parameters, which is well known to a person with ordinary skills of art in this field.

[0030] 2. Viscoelastic modeling for tars:

[0031] The tar modeling may follow the concept as laid out by Han and others (2008) among others. In reference to Figure 4, the tar (bitumen or extremely heavy oil) 400 may be divided into glassy solid state 410, quasi-solid (viscous) state 420, and liquid state 430 based on glass point (GP) and liquid point (LP) temperatures. The solid state 410 refers to the interval when temperature is lower than the GP. The viscous state 420 refers to the tar when temperature is higher than GP temperature and lower than LP temperature and the liquid state

430 refers to the state when temperature is higher than LP temperature. It is noticed that these characteristic temperatures of a certain tar/bitumen may vary with both measurement frequency and pressure.

[0032] Liquid State: $T > T_{lp}$

$$V_p \approx V_{p_{lq}} + B(T - T_{lp}) \quad (2.1)$$

$$V_s \approx 0 \quad (2.2)$$

where V_p and V_s are the P-wave and S-wave velocities, $V_{p_{lq}}$ is the V_p of the bitumen at LP temperature, and B is the slope.

[0033] Quasi-Solid State: $T_{gp} < T < T_{lp}$

$$V_p \approx V_{p_{lq}} + B(T - T_{lp}) + C(\eta(API, T), f) \quad (2.3)$$

$$V_s \approx V_s(\eta(API, T), f) \quad (2.4)$$

where η is the viscosity and C is the coefficient for the viscosity term.

[0034] Glassy-Solid State: $T_{gp} < T$

[0035] Both V_p and V_s increases quasi-linearly with the decrease of the temperature. When this tar model is used, the determination of the coefficients can be calibrated with measurements when available or cross-checked with other means of estimates. The state and viscoelastic property of a tar with certain composition, API value, temperature and pressure conditions can be estimated accordingly.

[0036] 3. Compaction analysis

[0037] The subject of compaction has been well studied and there exists multiple methods for constructing the compaction trends of different rock groups. A good review on the subject of compaction can be found in Dutta (2002) [2]. In general, the compaction is defined by trends through the integration of Athy (1930)-type [1] of regression and effective theory modeling (ETM) and is calibrated with available log and seismic information. This is fairly straight forward. This analysis provides the local lithology trends.

[0038] 4. Tar-baring sands property estimation

[0039] Tar-baring sands property estimation may be done using generalized Gassmann equation (Ciz and Shapiro, 2007 [5]):

$$K_{sat}^{*-1} = K_{dry}^{-1} - \frac{(K_{dry}^{-1} - K_{gr}^{-1})^2}{\phi(K_{if}^{-1} - K_{\phi}^{-1}) + (K_{dry}^{-1} - K_{gr}^{-1})} \quad (4.1)$$

$$\mu_{sat}^{*-1} = \mu_{dry}^{-1} - \frac{(\mu_{dry}^{-1} - \mu_{gr}^{-1})^2}{\phi(\mu_{if}^{-1} - \mu_{\phi}^{-1}) + (\mu_{dry}^{-1} - \mu_{gr}^{-1})} \quad (4.2)$$

Where K_{sat}^* and a μ_{sat}^* are solid saturated bulk and shear moduli, K_{dry} and a μ_{dry} denote drained bulk and shear moduli of the porous frame, K_{gr} and a μ_{gr} represent bulk and shear moduli of the grain material of the frame K_{ϕ} and a μ_{ϕ} are bulk and shear moduli related to the pore space of the frame, and K_{if} and a μ_{if} are the newly defined bulk and shear moduli related to the solid body of the pore infill. Equations 4.1 and 4.2 represent the isotropic Gassmann equations for a solid-saturated porous rock (in this case it is glassy solid). For viscoelastic material filling the pore space:

$$\mu_{if}(\omega) = \frac{\mu_{\infty}}{\frac{-i\mu_{\infty}}{\omega\eta} + 1} \quad (4.3)$$

$$V_s = \left(\frac{\mu_{sat}^*}{\rho}\right)^{\frac{1}{2}} \quad (4.4)$$

[0040] Equations (4.1) and (4.2) are used to estimate the bulk and shear moduli assuming glassy solid tar infill the pore space. For viscous sate, equation (4.3) for Maxwell fluid model is used to estimate the shear moduli. Equation (4.4) shows the relation between shear velocity and shear moduli.

[0041] For homogeneous porous frame, $K_\phi = K_{gr}$ and $\mu_\phi = \mu_{gr}$. For the liquid state, when $\mu_{if} = 0$, equation (4.1) and (4.2) reduce to standard Gassmann equation.

[0042] Combining the results (212, 222, 232) from the first three components (210, 220, 230) via general Gassmann equation (240), a tar sand viscoelastic property model 242 is derived.

[0043] 5. Tar pdf generation

[0044] Sampling and generating likelihood pdf for the tar model, $p(d|m)$ 252 is done here. The likelihood pdf includes tar/tar sands, wet-sands, shale, and other rock members based on the modeling results as discussed above 2 through 4, as shown in Fig. 2, where the results include Tar ViscoElastic Property 222, Tar sand ViscoElastic Property 242. This likelihood pdf refers to a particular or combination of multi-attributes, including acoustic impedance, shear impedance/Poisson's ratio, and/or density or their combination. In generating the likelihood $p(d|m)$ of an attribute or combination of attributes (d refers to the attributes), large samples (usually several to tens of millions) are drawn randomly from the corresponding model to ensure the statistical stability of the pdf. The multi-dimensional likelihood pdf 252 is constructed from the sampled data. The pdf 252 may be referred to as Tar pdf, if tar is the main interest.

[0045] 6. Elastic property derivation from simultaneous prestack inversion:

[0046] The seismic elastic property model of the volume 262 (i.e., acoustic impedance, shear impedance/Poisson's ratio, and/or density) are derived from simultaneous prestack seismic inversion 260. The resolution of this model is determined by the resolution of the seismic data used. One such inversion is discussed in Rasmussen et al., 2004 [6]. Simultaneous inversion is an industry-leading seismic inversion technology for inversion of elastic parameters from prestack seismic data. Preconditioned seismic data are input as multiple angle stacks. Prior models for P-wave velocity V_p , S-wave velocity V_s (or Poisson Ratio V_p/V_s), and density are the a priori models for elastic parameters and form a basis for

the objective and the cost functions for inversion. The prior models are usually derived from seismic velocity, interpreted seismic horizons, and available well information. A simulated annealing method may be used to generate and update model parameters. The forward modeling may be done using the linearized Zoeppritz equation based reflection coefficient series convolved with angle-dependent wavelets. The wavelets may vary spatially and temporally for each angle stack. It is a multi-trace inversion method, which uses a global error minimization algorithm and yields a robust inversion result.

[0047] 7. Tar mapping: a Bayesian statistical approach

[0048] The probability of the occurrence of certain rock type including tars and tar sands for a given attribute or combination of attributes (d , which can be acoustic impedance, shear impedance/Poisson's ratio, and/or density or their combination as generated in step 6), $p(m|d)$ is calculated through Bayesian's method as expressed in equation (7.1).

$$p(m|d) = p(m) * p(d|m) / p(d) \quad (7.1)$$

where $p(m)$, $p(d)$ are the prior probability for a model and the summation of the probability for all the models. The numerator on the right hand side of the equation is the product of the likelihood term and the prior term of a model and the term on the left hand side is the posterior probability. The rock types including tars and tar sands for a given attribute or combination of attributes (d) is defined by the maximum posteriori probability (MAP). In situations where the prior probabilities are not known, a probability equal to 1 divided by the total number of models may be used for the prior probability for all the models.

[0049] The rock type for each cube within the volume is determined following the maximum a posteriori (MAP) rule such that the occurrence of tar/tar sands from the output volume indicates the probability for tar/tar sands is the highest among the rest of the rock groups. The same volume also includes other rock types, as shown in the example in Figure 3. The resulting volume showing the rock type at any location within the volume may be referred to lithology volume. When tar or tar sand is highlighted, it may be referred to as tar volume.

[0050] Figure 3 illustrates a sample tar volume resulting from method 100 or 200. For simplicity, the tar volume 310 shown on the left hand side in Figure 3 is only a 2D cross-

section map of a 3D tar volume of the subsurface structure of interest. Tar map 310 is actually a total lithology map, which can identify all rock types within the volume. Because tar or tar sand is the main interest, only tar or tar sand is pointed out and discussed here. Most other rock types are not shown or discussed. The right hand chart 350 illustrates a well log. The tar sands (e.g. 322) are characterized by low GR and very high resistivity log responses 352 as shown in chart 350. A 3D volume produced from one of the methods indicates the various subsurface rock types, such as shale (342), sand (344) or tar/or tar sands (322, 324, 326 and 328) and several fault lines (e.g. 332, 334 and 336). In this example, tar map 310 clearly captures the tar anomaly 322, which is encountered by the drilling of well 302 at the depth indicated. Tar map 310 resulting from a method also predicts some other anomalies (324, 326 and 328) in the vicinity of the same drilling location and at deeper depth than the encountered tar anomaly 322.

[0051] In an actual exploration or production drilling, using the tar map 310, the drilling team could have altered the drilling trajectory 304 to avoid drilling through the tar/tar sands 322 while still drilling through the hydrocarbon depository. If drilling through the tar/tar sands 322 is not avoidable, the drilling team can be prepared with special equipment, material or techniques to minimize the detrimental effects of tars/tar sands. The drilling plan may be switched to this “tar-drilling” mode around the tars or tar sands.

[0052] The tar map generated from the above methods can be used for pre-drilling planning to design a well trajectory that avoids locations where tars or tar sands are predicted. The tar map may also be updated during drilling when new data are made available from well log or other measurement while drilling. The updated tar map can further guide the drilling operation. After a well is put into production, the tar map may still be used for applying other remedial methods to minimize the effects of tar on oil production.

[0053] The methods described above are typically implemented in a computer system 1900, one of which is shown in Figure 5. The system computer 1930 may be in communication with disk storage devices 1929, 1931, 1933 and 1935, which may be external hard disk storage devices. It is contemplated that disk storage devices 1929, 1931, 1933 and 1935 are conventional hard disk drives, and as such, will be implemented by way of a local area network or by remote access. Of course, while disk storage devices are illustrated as separate devices, a single disk storage device may be used to store any and all of the program instructions, measurement data, and results as desired.

[0054] In one implementation, seismic data from the seismic receivers may be stored in disk storage device 1931. Various non-seismic data from different sources may be stored in disk storage device 1933. The system computer 1930 may retrieve the appropriate data from the disk storage devices 1931 or 1933 to process data according to program instructions that correspond to implementations of various techniques described herein. The program instructions may be written in a computer programming language, such as C++, Java and the like. The program instructions may be stored in a computer-readable medium, such as program disk storage device 1935. Such computer-readable media may include computer storage media. Computer storage media may include volatile and non-volatile, and removable and non-removable media implemented in any method or technology for storage of information, such as computer-readable instructions, data structures, program modules or other data. Computer storage media may further include RAM, ROM, erasable programmable read-only memory (EPROM), electrically erasable programmable read-only memory (EEPROM), flash memory or other solid state memory technology, CD-ROM, digital versatile disks (DVD), or other optical storage, magnetic cassettes, magnetic tape, magnetic disk storage or other magnetic storage devices, or any other medium which can be used to store the desired information and which can be accessed by the system computer 1930. Combinations of any of the above may also be included within the scope of computer readable media.

[0055] In one implementation, the system computer 1930 may present output primarily onto graphics display 1927, or alternatively via printer 1928 (not shown). The system computer 1930 may store the results of the methods described above on disk storage 1929, for later use and further analysis. The keyboard 1926 and the pointing device (e.g., a mouse, trackball, or the like) 1925 may be provided with the system computer 1930 to enable interactive operation.

[0056] The system computer 1930 may be located at a data center remote from an exploration field. The system computer 1930 may be in communication with equipment on site to receive data of various measurements. The system computer 1930 may also be located on site in a field to provide faster feedback and guidance for the field operation. Such data, after conventional formatting and other initial processing, may be stored by the system computer 1930 as digital data in the disk storage 1931 or 1933 for subsequent retrieval and processing in the manner described above. While Figure 19 illustrates the disk storage, e.g.

1931 as directly connected to the system computer 1930, it is also contemplated that the disk storage device may be accessible through a local area network or by remote access. Furthermore, while disk storage devices 1929, 1931 are illustrated as separate devices for storing input seismic data and analysis results, the disk storage devices 1929, 1931 may be implemented within a single disk drive (either together with or separately from program disk storage device 1933), or in any other conventional manner as will be fully understood by one of skill in the art having reference to this specification.

[0057] The particular embodiments disclosed above are illustrative only, as the invention may be modified and practiced in different but equivalent manners apparent to those skilled in the art having the benefit of the teachings herein. Furthermore, no limitations are intended to the details of construction or design herein shown, other than as described in the claims below. It is therefore evident that the particular embodiments disclosed above may be altered or modified and all such variations are considered within the scope of the invention. Accordingly, the protection sought herein is as set forth in the claims below.

CLAIMS

WE CLAIM:

1. A method to predict tars and tar sands in petroleum exploration and production in a subsurface volume, comprising:
 - building a viscoelastic property model of the volume using rock behavior including tars;
 - building a seismic elastic property model of the volume using seismic inversion; and
 - deriving a lithology volume by combining the property models from rock behavior and seismic inversion.
2. The method as in claim 1, wherein the lithology volume identifies a tar in the volume if the tar exists within the volume.
3. The method as in claim 2, wherein the viscoelastic property model of tars and the seismic elastic property model share common attributes, wherein the common attributes comprises some of the following: acoustic impedance, shear impedance, Poisson's ratio, density, V_p and V_s .
4. The method as in claim 3, wherein viscoelastic property model of the volume using rock behavior including tars comprising probability density function (pdf) of the volume, wherein pdf is a function of the attributes.
5. The method as in claim 1, wherein deriving a lithology volume by combining the property models from rock behavior and seismic inversion comprises Bayesian method.
6. The method as in claim 1, wherein building a viscoelastic property model of the volume comprising:
 - modeling the viscoelastic property of tar as a function of tar composition, temperature and pressure conditions;
 - modeling pore pressure, overburden pressure and formation temperature with burial depth; and

modeling and constructing local lithology trends based on compaction analysis and reference to basin deposition history.

7. The method as in claim 6 further comprising:
sampling and constructing a probability density function (pdf) of tar from the modeling.
8. The method as in claim 1, wherein building a seismic elastic property model of the volume via seismic inversion comprising deriving elastic attributes using simultaneous prestack inversion.
9. The method as in claim 8, wherein the elastic attributes comprising some of the following: acoustic impedance, shear impedance, Poisson's ratio, density, V_p and V_s .
10. The method as in claim 7 further comprising deriving lithology volume using the pdf and the elastic attributes.
11. The method as in claim 7 wherein deriving the lithology volume using the pdf and the elastic attributes comprising using Bayesian inversion.
12. The method as in claim 2 further comprising:
changing drilling plan to avoid the identified tar.
13. The method as in claim 2 further comprising:
changing drilling plan to tar-drilling mode around identified tar.
14. A system for petroleum exploration and production in a subsurface volume, comprising:
a processor,
a computer readable media containing instructions when executed by the processor, to predict tars and tar sands by performing a method as in claims 1-13.

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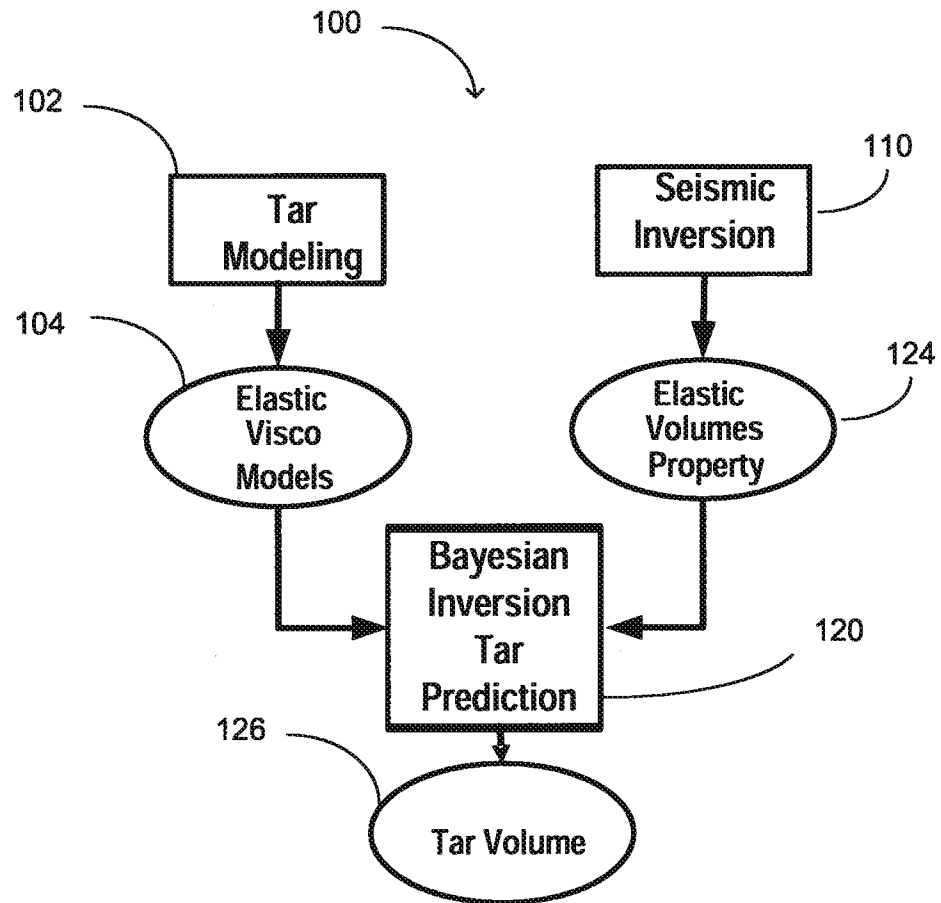


Fig. 1

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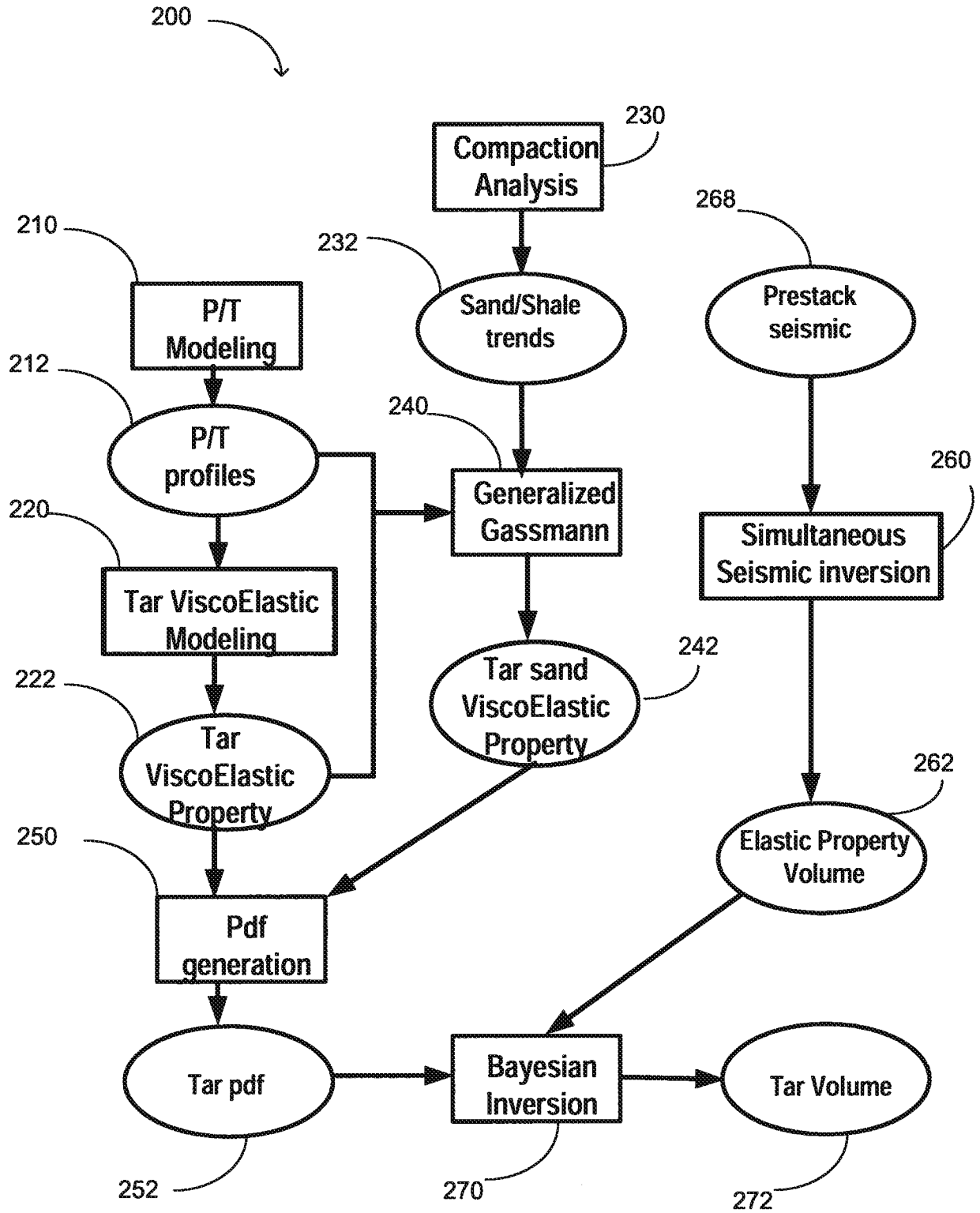


Fig. 2

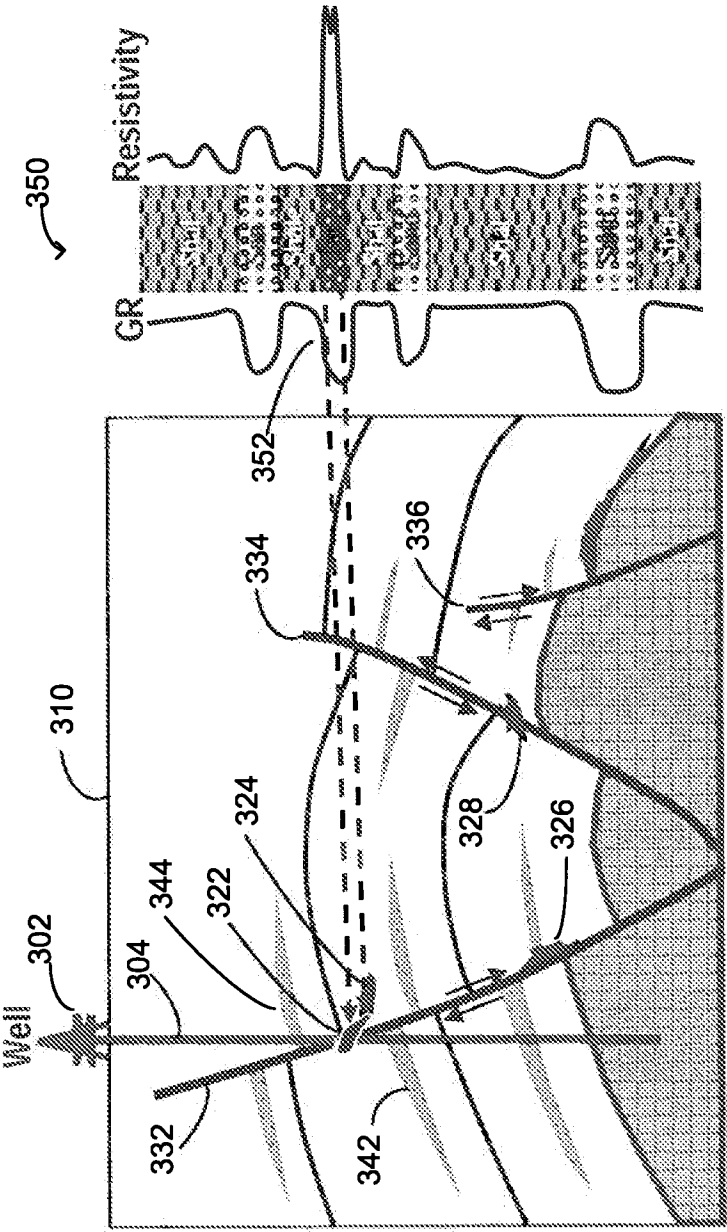


Fig. 3

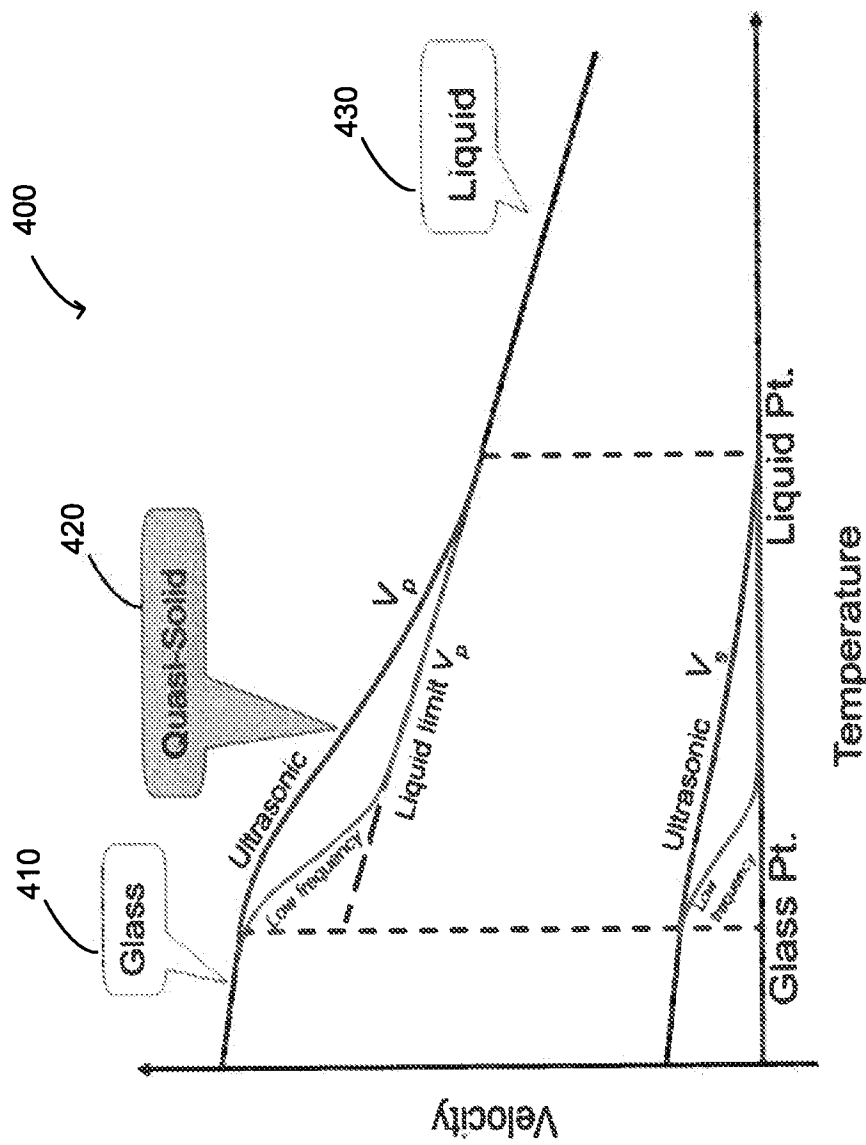


Fig. 4 (Prior Art)

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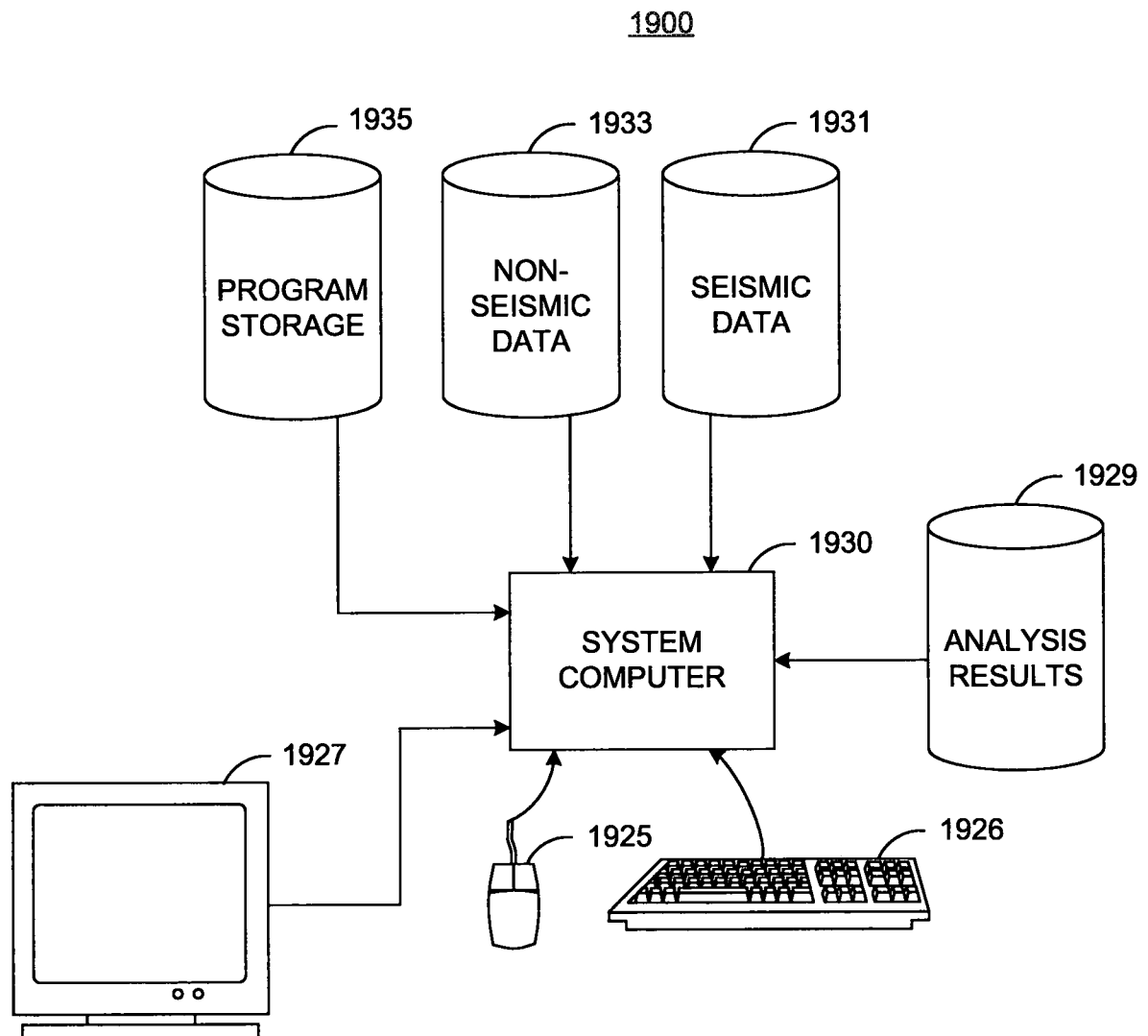


Fig. 5