PATENT SPECIFICATION

(21) Application No. 48991/77

(22) Filed 24 Nov. 1977

(31) Convention Application No. 744 670

(32) Filed 24 Nov. 1976 in

(33) United States of America (US)

(44) Complete Specification published 22 Oct. 1980

(51) INT. CL.³ H02P 3/00

(52) Index at acceptance

G3N 262 CA2

H1S 20 6A3 8B 9E1 FD

H2A TK VT

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(54) ADJUSTABLE STROKE ELECTRIC MOTOR

We, Honeywell Inc., a Cor-(71)poration organised and existing under the laws of the State of Delaware, United States of America, of Honeywell Plaza, 5 Minneapolis, Minnesota 55408, United States of America, do hereby declare the invention for which we pray that a patent may be granted to us, and the method by which it is to be performed to be particu-10 larly described in and by the following statement:

This invention relates to an adjustable stroke electric motor device such as used for positioning of control equipment, such 15 as dampers, valves, through angular rota-

tions of less than 360°.

According to the invention, there is provided an adjustable stroke electric motor device, comprising an electric motor; an 20 adjustable limit switch responsive to motor rotation to limit angular rotation thereof to a preset amount; an electric circuit for controlling the energisation of the motor, said circuit including an adjustable resist-25 ance for enabling the circuit to adjustably control the angular rotation of the motor to said preset amount; and a linkage connecting the limit switch and the resistance for simultaneous adjustment thereof.

An embodiment of the invention will now be described by way of example with reference to the accompanying drawings, in

which:-

Figure 1 is a schematic representation of 35 the control circuit of an adjustable stroke electric motor device according to the invention.

Figure 2 is a top view of the motor device;

Figure 3 is a cross section of the motor device along lines 3-3 of Figure 2;

Figure 4 is a cross section of the motor device along lines 4-4 of Figure 2;

Figure 5 is an elevation of a potentio-45 meter wiper and camming arrangement as viewed along lines 5-5 of Figure 2;

Figure 6A is a side view of the camlike member, and

Figure 6B is an additional view of the

cam-like member.

Referring to Figure 1, the control system of the motor device is of the bridge balance, closed loop type. The present invention can most simply be understood if the system is considered to be a two-position 55 system, wherein the control motor drives from a first extreme position which can be considered the closed position for the system to a second extreme position which can be considered the open position for 60 the system. The terms open and closed generally refer to the load being operated by the motor and are common to the heating and air conditioning industry in which the present motor has great utility. The 65 system could be a system in which the motor drives in one direction electrically and is spring returned in the reverse direction, a system in which the motor is electrically operated for rotation in either 70 direction between the open and closed positions, or could be a completely modulating type of system.

Electric power is supplied between terminals 10 and 11 and is of a voltage com- 75 patible with the particular motor and electronics to be used. A typical control motor would operate from a 24 volt, 60 hertz supply. Connected across the terminals 10 and 11 is a winding 12 that operates an 80 electromagnetic braking mechanism when the system is used with a spring return arrangement. Also connected across the terminals 10 and 11 are a resistor 13, a diode 14 and a capacitor 15 which supplies 85 an appropriate direct current potential to terminals 16 and 17 of an electric or electronic circuit generally disclosed at 18. The specific electronics of circuit 18 are

not material and, therefore, this portion of 90

the system has been shown in block form. The electric circuit 18 has a pair of terminals 20 and 21 that are connected to an external potentiometer 22 that provides an 5 input set point for the system. A typical system would include a potentiometer 22 that is responsive to temperature, or some other condition to be controlled. The electric circuit 18 has a further pair of ter-10 minals 23 and 24, with terminal 23 connected to a conductor 25, a rebalance potentiometer 26, a bridge resistor 27, and a conductor 28 which is connected back to the terminal 24. Connected between the 15 conductors 25 and 28 are a resistor 30 and a stroke adjusting resistance 31. The stroke adjusting resistance 31 has been disclosed as a potentiometer with a resistance portion 32 and an adjustable wiper element 20 33. While the stroke adjusting resistance 31 has been shown as a potentiometer, this element could be a rheostat by omitting the connections between the end of the resistance element 32 and the conductor

The potentiometers 22, 26 and the resistance elements 27, 30 and 32 form part of a conventional bridge circuit of a closed loop motor control arrangement which is 30 well known in the control art. The balance of the bridge resistance network is not shown and is included in the electric circuit 18, as is well understood in the art. The use of a stroke adjusting resistance 31 35 provides a motor control system wherein the motor rotation has one fixed, extreme position (referred to as the closed position) and a variable second position (referred to as the open position). By varying the 40 potentiometer 31 the amount of rotation at the open end of rotation can be varied, typically between 90 and 160 degrees of angular rotation of the output shaft of the motor.

A further pair of terminals 35 and 36 are provided from the electric circuit 18 and these terminals are bridged by resistor 40 in series with a capacitor 41. The resistor 40 and capacitor 41 form a snubber 50 network to protect the solid state switching devices that are contained in the electric circuit 18. Also connected to terminal 35 is a conventional closed limit switch 42 that is in series with a first motor winding 43 55 that is connected by conductor 44 to terminal 10 of the electric source. The conductor 44 is then connected through a second motor winding 45 to an adjustable limit switch 46 that is connected to the 60 terminal 36. The adjustable limit switch 46 and the fixed limit switch 42 generally make up a limit switch for the device which will provide safety for the electric motor control and the load being driven by that 65 motor. The details of the adjustable limit switch 46 will be disclosed in substantial detail, as its structure and operation are important to the present motor.

2:

The electric motor structure is completed by providing a capacitor 50 and a series 70 resistance 51 connected across the windings 43 and 45 in a conventional delta configuration. The motor has an armature and gear reduction mechanism 52 that drives an output shaft and feedback 53 to 75 potentiometer 26. The potentiometer 26 is driven to rebalance the bridge network in accordance with the setting of the potentiometer 22, in a manner that is well understood in the electric closed loop motor 80 control art. The disclosure of Figure 1 is completed by providing a stroke adjusting linkage 54 that connects the adjustable limit switch 46 and the potentiometer wiper 33 of the stroke adjusting potentiometer 85 means 31. The stroke adjusting linkage 54 is arranged to concurrently adjust the posi-tion of the potentiometer 31 and the limit switch 46 so that the number of angular degrees of rotation that are predetermined 90 by the setting of the wiper 33 is brought into conformance with the position of the limit switch 46 to protect the motor and any driven load in the event of an electrical failure. That failure could be of the 95 bridge network that forms an input to the electric circuit 18, or any of the interior components of the electric circuit 18 that would cause the motor to drive the load in such a way as to rotate a greater number 100 of angular degrees than the predetermined number of angular degrees selected by the setting of the potentiometer wiper 33. The mechanical structure that makes up the stroke adjusting linkage 54 is disclosed in 105 substantial detail in the remaining figures of the present disclosure.

In Figure 2 a top view of the physical structure of an adjustable stroke electric motor is disclosed with its top removed to 110 expose a terminal board 55 which is recessed in a chamber 56. The terminal board 55 has a plurality of terminals that correspond to the terminals 10, 11, 17, 20 and 21 of Figure 1. These five terminals 115 allow for the introduction of the necessary electric power and for the connection of a three terminal potentiometer 22 which is normally mounted remote from the motor itself.

The terminal board 55 further has a slot 57 which has the stroke adjusting linkage 54 slideably mounted therein. The stroke adjusting linkage 54 includes a locking means in the form of a screw 60 and a 125 clamp-like member 61. The tightening and loosening of screw 60 provides a clamping motion between the clamp-like member 61 and the terminal board 55 so that the stroke adjusting linkage 54 can be posi- 130

tioned in the slot 57 between the minimum and maximum positions, which have been noted on the slot. These two positions would generally correspond to a 90 degree 5 angular rotation of the shaft 53 and a 160 degree angular rotation. The shaft 53 is shown extending through the adjustable stroke electric motor which is generally encased in a housing 62. The electric 10 motor and its housing 62 are shown in the form typical of a device which is commercially available and marketed by Honeywell Inc., and which is known as an M955 type of Modutrol motor. The dis-15 closure in Figure 2 has been provided to show the terminal board slot 57, the locking means 60 and 61, and the terminal arrangement, as well as providing the basis of the cross sections of the motor which 20 are disclosed in greater detail in connections with Figures 3, 4 and 5.

In Figure 3 there is disclosed a sectional view of the adjustable stroke motor device along the lines 3-3 of Figure 2. This sec-25 tional view generally discloses an elevation of the control motor housing 62 wherein the chamber 56 is disclosed as having a fluid tight chamber 62 that is oil filled and contains the basic motor elements includ-30 ing the windings 43 and 45, the armature 52, and the gear reduction mechanism which is mechanically terminated in the shaft 53 and electrically terminated to a terminal means 63. This structure is all 35 conventional in electric control motors and is only incidental to the details of the present invention. The output shaft 53 is sealed by a conventional packing and hub 64 around which is concentrically mounted 40 a rotatable member 65 so that the member 65 is capable of rotation with the shaft 53 being its center of rotation. Mounted on the rotatable member 65 is a snap-action switch 46' that forms part of the adjustable 45 limit switch 46. The switch 46' has a roller 66 connected to an arm 67 that can apply pressure to the switch operating mechanism 70. The switch 46' is attached to the rotatable member 65 in any convenient 50 manner, but would normally be attached so that the switch means 46' could be adjusted in position slightly as a final assembly procedure.

The rotatable member 65 has an elon55 gated projection 71 that contains a slot 72
wherein the elongated member 71 and the
slot 72 is a first of a pair of slotted arms
that engage a pin 73 that is attached to an
arm 74 that forms part of the stroke ad60 justing linkage 54. The arm 74 projects
through the slot 57 in the terminal board
55 and accepts the screw 60 which is part
of the locking means to position the stroke
adjusting linkage 54 in the slot 57 at any
65 selected location. The pin 73 also pro-

jects through a slot 75 in a second slotted arm 76 that forms part of the adjustable resistance 31 that has been disclosed as a potentiometer with the wiper 33. The wiper 33 is attached to the slotted arm 76 70 so that as the pin 73 moves in the slot 75, the slotted arm 76 is caused to rotate and thereby changes the position of the potentiometer wiper 33.

The adjustable resistance or potentio-75 meter 31 is mounted to a bracket 80 that is mounted by a pair of screws 81 into the chamber 56 so that the bracket 80 mounts the potentiometer 31 in a plane parallel to the limit switch member 46' so that as the 80 stroke adjusting linkage 54 is adjusted in the slot 57, both the potentiometer 31 and the limit switch 46 are adjusted concurrently to the same number of angular degrees of rotation desired from the output 85 shaft 53.

The chamber 56 has a number of mounting means that are utilized in connecting or supporting various other elements. Included in these mounting means are a 90 number of bosses 82 that are used to support an insulating or printed circuit board which mounts a number of other components used in the electric circuit 18. The details of the printed circuit board will not 95 be disclosed as they are not material to the present invention and it will be shown only as mounting the necessary portions of the present control system to explain the present invention, as will be brought out in 100 more detail in connection with Figures 4, 5 and 6.

In Figure 4 an elevation along lines 4-4 of Figure 2 of a printed circuit board 83 is disclosed. The printed circuit board 83 105 is inserted over the bosses 82 and into projections from the terminals 10, 11, 17, 20 and 21 which project down from the terminal board 55. A hole 84 in the printed circuit board 83 is concentric with the 110 output shaft 53 for the motor means and the printed circuit board 83 is quite rigidly held in place by these described members and screws 82'. As has been previously indicated, the printed circuit board 83 and 115 the electronic components that make up the electric control circuit 18 are not disclosed for the sake of clarity. Mounted on the printed circuit board 83 is the follow up potentiometer resistor 26' and it is 120 formed concentrically with the output shaft 53 so that as the output shaft 53 rotates it can drive a potentiometer wiper that rides on the potentiometer resistor 26' as will be described in connection with Figure 125 Also mounted on the printed circuit board 83 is a conductive area 85 that forms part of the potentiometer 26. The potentiometer 26 completes a circuit from the resistance element 26' to the conductive area 130 85. These elements have been shown only for continuity of disclosure of the total motor structure.

The limit switch 42 is also disclosed as 5 two elements 42' and 42" which are mounted on the printed circuit board 83. This limit switch is fixed in position and is operated by a rotating member that will be disclosed in detail in connection with 10 Figures 5, 6A and 6B. This limit switch construction is again a conventional limit switch that is fixed in position and is operated by a member which is attached

and driven on the output shaft 53. In the 15 hole 84 in the printed circuit board 83 there is disclosed the output shaft 53 and the hub 64 which holds the rotatable member 65 in place. Once again the roller 66 of switch 46' can just be seen through the

20 opening 84.

In Figure 5 there is disclosed an elevation of the printed circuit board 83 along the line 5-5 as disclosed in Figure 2. In this particular view a further assembly 25 generally disclosed at 86 is detailed. The assembly 86 is a potentiometer wiper assembly along with a cam-like projection that is curved and which cooperates with the electrical switch 46' to form the ad-30 justable limit switch 46. The details of an elevation of potentiometer wiper assembly 86 are shown in Figure 5 with the potentiometer wiper assembly 86 mounted on the output shaft 53, and in 35 much greater detail in two views by itself in Figures 6A and 6B. In Figure 5, the potentiometer wiper assembly 86 includes a potentiometer wiper 26" which slides on the resistance element 26' and cooperates 40 with a slideable contact 26" to form the potentiometer 26 that is the follow up potentiometer as disclosed in Figure 1.

The potentiometer wiper assembly 86 rotates with the shaft 53 and provides the 45 close loop follow up for the system. This particular structure is held in place by a set screw 87 that locks the potentiometer wiper assembly 86 into its proper place on the shaft 53.

Attached to the potentiometer wiper assembly 86 is a limit switch operating means 42". The limit switch operating means 42" rotates with the potentiometer wiper assembly 86 until it engages part of 55 the fixed limit switch 42 when the motor has rotated in a full clockwise direction as viewed in Figure 5. The projection 42" comes into contact with a projection 88 on the fixed limit switch 42 and causes an 60 open circuit to stop the motor in a full clockwise direction as viewed in Figure 5. To this point, the follow up potentiometer arrangement and the limit switch arrangement is part of a conventional electrical

65 control motor. A curved, cam-like mem-

ber is attached to the potentiometer wiper means 86 on the side reverse from that disclosed in Figure 5 and that element will be described in detail in connection with Figures 6A and 6B.

In Figure 6A a side view of the potentiometer wiper assembly 86 is disclosed wherein the wiper elements 26" and 26" are disclosed as riveted as at 90 to an insulating board 91 that is attached to a frame 75 92 that includes the set screw 87. A further insulating member 93 is riveted at 94 to the frame 92 and carries the projection 42" in an electrically insulated mode from the balance of the structure. The frame 80 92 carries a further mounting member 95 that is shown held by a pair of rivets 96 thereto. The rivets pass through a curved, cam-like member 97 that forms part of the adjustable limit switch 46. The curved, 85 cam-like member 97 operates against the roller 66 of the snap switch 46 to form the operating member for the limit switch

As will be seen in Figure 6B, the curved, 90 cam-like member 97 is attached by an arm 98 to a support 99 that is riveted at 96 to the insulating member 91. The curved, cam-like member 97 further has a hole 100 that is positioned around the shaft 53 so 95 that the entire potentiometer wiper assembly 86 can be mounted on the shaft 53 by the screw 87 and will rotate with the shaft 53 to act as the operating member for the follow up potentiometer 26 and as the 100 limit switch means for both the clockwise and counterclockwise operation of the device.

In referring to Figure 3, it will be understood that as the stroke adjusting linkage 105 54 is slid in the slot 57 in the terminal board 55 that the pin 73 moves in a linear motion. As this linear motion occurs, the arms 71 and 76 of the limit switch 46 and the stroke adjusting potentiometer 31 also 110 move. The movement of the switch 46' along with the adjustment of the potentiometer 31 sets into the control system, as described in Figure 1, the open position for the rotation of the motor. The con- 115 current adjustment of the potentiometer wiper 33 and the position of the switch 46' keep the electrical and mechanical limits of the system together.

In order to properly operate the switch 120 46' at any of its rotational positions as adjusted by the movement of pin 73, the curved, cam-like member 97 has a curved portion that is equivalent to the number of angular degrees through which the present 125 device can be adjusted so that the switch 46' can be operated by the cam-like member 97 contacting the roller 66 through the entire adjustment range.

By providing a potentiometer and a 130

rotatable limit switch that are mechanically linked together, the present adjustable stroke electric motor device can have its adjustment accomplished by the movement

5 of a single adjusting linkage which concurrently adjusts both the resistance and the limit switch for the motor by the same number of angular degrees of rotation so that the operation of the motor, as dic-

10 tated by the electric circuitry is mechanically protected or backed up by the mechanical limit switch being adjusted to prevent any accidental rotation beyond that desired. Without the above mentioned

of this type of motor could fail in such a manner as to call for continued rotation of the control motor, and if the mechanical limit switch were not adjusted to compen-

20 sate for the electrically called for limit, a failure could cause the motor to be energized beyond the desired turn off point with quite a disastrous effect. In this type of situation, either the motor structure must

25 give, or the mechanical load must give. In either case an expensive failure occurs. The present device allows for a single adjustment mechanism to concurrently adjust the electrical and mechanical limits so

30 that an inadvertent electrical failure is backed up by a mechanical limit switch to protect either the load or the motor itself depending on the type of installation involved.

35 The present device could include any number of different types of mechanical connecting structures between the potentiometer 31 and the limit switch 46. One particular construction that has been found

40 to be particularly desirable has been disclosed in great detail. Other structures could readily be accomplished and the present invention is limited solely by the scope of the appended claims.

45 WHAT WE CLAIM IS:

1. An adjustable stroke electric motor device comprising an electric motor; an adjustable limit switch responsive to motor rotation to limit angular rotation thereof

to a preset amount; an electric circuit for 50 controlling the energisation of the motor, said circuit including an adjustable resistance for enabling the circuit to adjustably control the angular rotation of the motor to said preset amount; and a linkage connecting the limit switch and the resistance for simultaneous adjustment thereof.

2. The device of claim 1, wherein the motor includes an output shaft, and wherein the limit switch includes an electric 60 switch and a switch operating member which are moved relatively to each other by said shaft to limit angular rotation of the motor and shaft to said preset amount.

3. The device of claim 2, wherein the 65 electric switch is mounted for angular adjustment about said shaft and is connected to said linkage which enables said angular adjustment of the switch.

4. The device of claim 2 or 3, wherein 70 the switch is a snap-action switch and wherein the operating member is mounted for angular rotation with the shaft, the operating member having a curved switch engaging portion, the angular extent of the 75 curved portion determining the number of degreees through which the motor can be adjusted.

5. The device of claim 3 or claim 4 as appendant to claim 3, wherein the linkage 80 includes a slider mounted for sliding movement in a slot in a terminal board, said slider being interconnected with the electric switch and with the resistance via a pin and slotted arm arrangement, and including locking means for locking the slider in

6. The device of any one of the preceding claims including a fixed limit switch for defining one limit position of the motor, 90 the adjustable limit switch defining the other limit position.

7. An adjustable stroke electric motor device, substantially as herein described with reference to the accompanying draw- 95

ings.

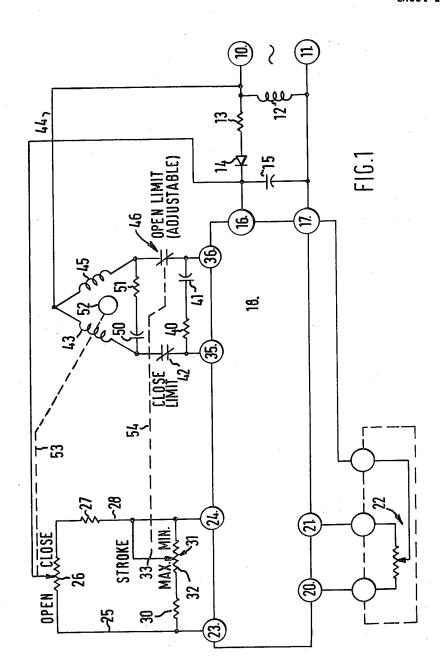
JOHN RIDDLE, Chartered Patent Agent.

Printed for Her Majesty's Stationery Office by The Tweeddale Press Ltd., Berwick-upon-Tweed, 1980.

Published at the Patent Office, 25 Southampton Buildings, London, WC2A 1AY, from which copies may be obtained.

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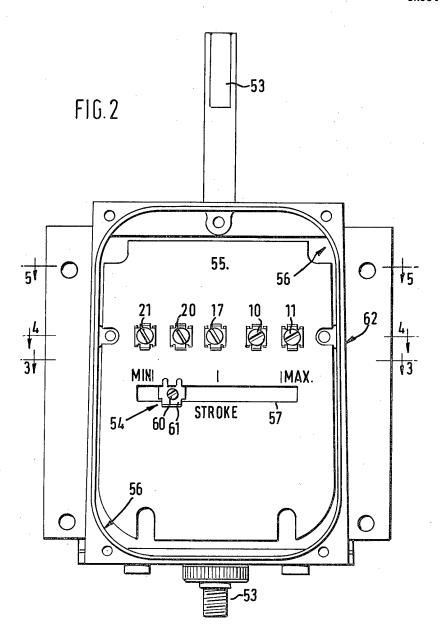
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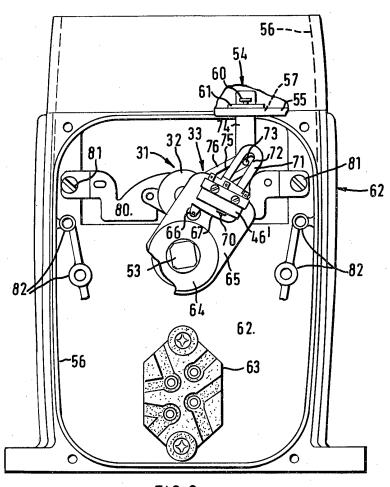


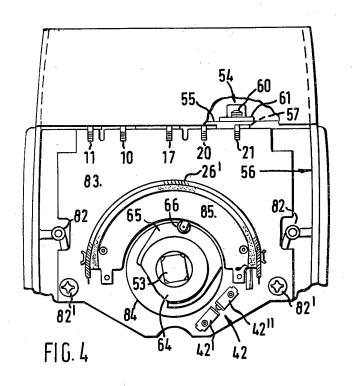
FIG.3

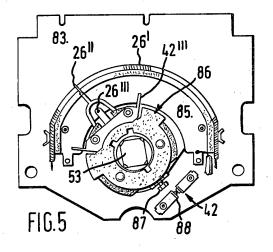
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