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- (71) Applicant: KETER PLASTIC LTD [IL/IL]; 2 Sapir St., Industrial Area, 646766 Herzlyia (IL).
- (72) Inventor: BRUNNER, Yaron; 31 Halivne Street, 36576 Timrat (IL).
- (74) Agent: DE VRIES, Savid; Reinhold Cohn And Partners, P.O.Box 13239, 61131 Tel Aviv (IL).
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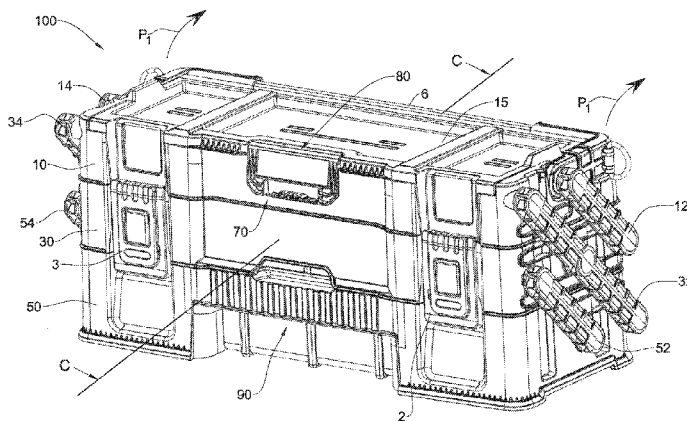


Fig. 1

(57) Abstract: A cantilever box (100) comprising: at least two trays (10,30,50), including a lowermost tray (50) and an uppermost tray (10), interconnected therebetween by cantilever links (12,14,32,34,52,54) pivotally secured to said trays. The trays are convertible at least between a stacked position, and an extended position; a first gripping portion (80), disposed at the uppermost tray (10), configured for being gripped by a user for converting the trays between their extended position and their stacked position; and a securing mechanism (70) switchable between a locked state in which when the trays are at their extended position, the securing mechanism is configured for arresting a locking member (60), thereby locking the trays at their extended position; and an unlocked state in which the securing mechanism is disengaged from said locking member (60), thereby facilitating displacement of the trays from their extended position into their stacked position. The securing mechanism is disposed in proximity to the first gripping portion, or integrated therein, so that the user is required to switch the securing mechanism from its locked state to its unlocked state by his first hand while gripping the first gripping portion by the same hand, thereby displacing the uppermost tray (10) for converting the trays from their extended position to their stacked position.



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## CANTILEVER BOX

### TECHNICAL FIELD

The presently disclosed subject matter relates to boxes, and more particularly to boxes having a cantilever mechanism.

The term '**cantilever box**' as used herein the specification and claims denotes a box (e.g., a toolbox, a tackle box) in which a cantilever mechanism connecting a plurality of trays, is implemented.

### BACKGROUND

Cantilever boxes of different sizes and constructions are well known in the art. One well known type of a cantilever box is a tackle box. Cantilever boxes generally comprises a plurality of compartmentalized trays and linkage elements interconnecting the trays so that they can be moved from a superimposed stacked condition to an expanded cantilevered condition in which the trays are vertically offset whereby access can be obtained to each tray. The trays are designed to receive and store various tools, such as working tools, screws, nuts, small boxes, etc.

Cantilever boxes are basically designed to allow the storage of numerous items of varying size and shape in a convenient and orderly manner which provides maximum access to the items contained.

### SUMMARY OF THE PRESENTLY DISCLOSED SUBJECT MATTER

According to the presently disclosed subject matter, there is provided a cantilever box comprising:

at least two trays, including a lowermost tray and an uppermost tray, interconnected therebetween by cantilever links pivotally secured to said trays. The trays are convertible at least between a stacked position, and an extended position;

a first gripping portion, disposed at the uppermost tray, configured for being gripped by a user for converting the trays between their extended position and their stacked position; and

a securing mechanism switchable between a locked state in which when the trays are at their extended position, the securing mechanism is configured for arresting a

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locking member, thereby locking the trays at their extended position; and an unlocked state in which the securing mechanism is disengaged from said locking member, thereby facilitating displacement of the trays from their extended position into their stacked position;

The securing mechanism is disposed in proximity to the first gripping portion, or integrated therein, so that the user is required to switch the securing mechanism from its locked state to its unlocked state by his first hand while gripping the first gripping portion by the same hand, thereby displacing the uppermost tray for converting the trays from their extended position to their stacked position.

The first gripping portion and the securing mechanism are located at a safe location in the cantilever box, i.e., at the uppermost tray, which allows the user to convert the trays from their extended position to their stacked position in a controlled and a safe manner. This manner eliminates or reduces the likelihood of jamming the fingers of the user's first hand between the trays during the conversion between the positions.

The uppermost tray can be configured with a top wall, a front wall and a bottom wall. The top wall and the front wall are configured with a front edge therebetween, having a longitudinal axis.

The first gripping portion can be disposed at the middle of the front edge along its longitudinal axis.

Alternatively, the first gripping portion can be disposed at the top wall of the uppermost tray.

The securing mechanism can be disposed at the front wall of the uppermost tray.

The first gripping portion can have a first gripping recess disposed at the top wall of the uppermost tray.

The first gripping recess can be configured with shape and size for accommodating one or more of the following fingers of the user's first hand: index finger, middle finger, ring finger, and little finger.

The cantilever box can further include a cover member.

The cover member can be pivotally mounted to the uppermost tray and constitutes a portion of its top wall.

The first gripping recess can be disposed at the cover member.

The securing mechanism can be normally in its locked state.

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The term '**normally**' refers herein to usually, or most of the time.

The securing mechanism can comprise a sliding element having a first end configured with a biasing mechanism for outwardly biasing the sliding element by exerting thereon an outwardly biasing force and thereby causing it to be normally in its locked state; and a second end including a securing protrusion configured with a front face.

The first gripping portion can be configured with an interior section, which together with the sliding element constitutes the securing mechanism.

The sliding member can further comprise a middle portion configured with a thumb supporting element configured to provide support to a thumb of the user's first hand when switching the securing mechanism from its locked state to its unlocked state by applying an inwardly biasing force on the thumb supporting element.

The securing protrusion can be configured to be received at the locking member, and thereby arresting the locking member in the locked state of the securing mechanism.

The securing protrusion can normally project out of the surface of the bottom wall of the uppermost tray.

In the configuration in which the sliding element is disposed at an interior section of the first gripping portion, the interior section can be configured with a biasing wall configured for engaging the biasing mechanism and providing support thereto for exerting the outwardly biasing force on the sliding element.

The biasing mechanism can include at least one bendable element.

The biasing mechanism can include two bendable elements, the ends of which are configured to move away from each other and to slide on the biasing wall when the securing mechanism is switched from its normally locked state to its unlocked state.

The ends of the bendable elements are further configured to approach each other and to slide on the biasing wall when the securing mechanism is switched from its unlocked state to its normally locked state.

The biasing mechanism can be a compression spring.

The sliding element and the biasing mechanism can be integrated in a single element.

The sliding element and the biasing mechanism can be made of the same material.

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The cantilever box can further comprise a second gripping portion, disposed at the lowermost tray, configured for being gripped by a user's second hand for providing support to the cantilever box and holding it on place, when the trays are converted between their extended position and their stacked position.

The second gripping portion is located at a safe location in the cantilever box, i.e., at the lowermost tray, which allows the user to convert the trays between their extended position and their stacked position in a controlled and a safe manner. This manner eliminates or reduces the likelihood of jamming the fingers of the user's second hand between the trays during the conversion between the positions.

The lowermost tray can be configured with a front wall at which the second gripping portion can be disposed.

The second gripping portion can be configured with a second gripping recess configured with shape and size for accommodating one or more of the following fingers of the user's second hand: index finger, middle finger, ring finger, and little finger.

The second gripping portion can further be configured with a second gripping supporting surface configured for providing support to a palm and a thumb of the user's second hand.

The locking member can be disposed at one of the trays. More particularly, the locking member can be disposed at a secondary tray below the uppermost tray.

The secondary tray can be configured with a top wall and a rear wall, configured with a rear edge therebetween, having a longitudinal axis. The locking member can be disposed in the middle of the rear edge along said longitudinal axis.

Alternatively, the locking member can be disposed at one of the cantilever links.

The locking member can be a recess or any other fixing element which is configured to engage with the securing mechanism, and thereby to be arrested by the securing mechanism in its locked state.

The secondary tray can be configured with a biasing protrusion configured to engage the front face of the securing protrusion for exerting an inwardly biasing force on the sliding element during the conversion of the trays from the stacked position to their extended position.

The biasing protrusion can project out of the surface of the top wall of the secondary tray.

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In the process of the conversion of the trays from their stacked position to their extended position, the biasing protrusion can switch the securing mechanism from its normally locked state to its unlocked state upon the exertion of the inwardly biasing force on the sliding element, and then switching back to its normally locked state upon the exertion of the outwardly biasing force when it is greater than said inwardly biasing force.

The trays can include more than two trays, each of which is connected to at least two other trays by the cantilever links for allowing simultaneous displacement of the trays not including the lowermost tray, when converted between the stacked position and the extended position. Due to this simultaneous displacement, by arresting the securing mechanism to the locking member, all the trays can be locked in their extended position.

When the trays are at their stacked position, the securing mechanism can further be switchable between a locked state in which the securing mechanism is configured for arresting another locking member, thereby locking the trays at their stacked position; and an unlocked state in which the securing mechanism is disengaged from said another locking member, thereby facilitating displacement of the trays from their stacked position into their extended position.

The cantilever box can further comprise at least one latch configured for locking the trays at their stacked position.

The at least one latch can be pivotally mounted to the lowermost tray at a mounting portion.

The cover member can be configured with at least one first engagement portion and the mounting portion can be configured with at least one second engagement portion. When the cover is in its closed state, the latch can be mounted to the first and the second engagement portions, thereby locking the trays at their stacked position so that the uppermost tray and the middle tray are fixed between the cover member and the lowermost tray.

The cantilever box can further comprise at least one handle mounted to an uppermost tray of the trays. The handle can be used for holding and transporting the cantilever box from place to place. The handle can further be used for converting the trays from their stacked position to their extended position.

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The cantilever box can further include at least one supporting element, mounted to one of the trays, configured, at the extended position of the trays, for leaning on a surface on which said cantilever box is disposed, and thereby preventing the cantilever box from rolling over.

## **BRIEF DESCRIPTION OF THE DRAWINGS**

In order to understand the invention and to see how it can be carried out in practice, the embodiments will now be described, by way of non-limiting examples only, with reference to the accompanying drawings, in which:

**Fig. 1** is a perspective view of a cantilever box in its stacked position, in accordance with one example of the presently disclosed subject matter;

**Fig. 2** is the cantilever box of **Fig. 1** in its extended position;

**Fig. 3A** is a perspective view of an uppermost tray of the cantilever box of **Figs. 1** and **2**;

**Fig. 3B** is an enlarged view of a portion A1 of **Fig. 3A**;

**Fig. 3C** is the uppermost tray of **Fig. 3A** without a cover member and a handle of the cantilever box;

**Fig. 3D** is a cross-section along line A-A in **Fig. 3C**;

**Fig. 3E** is a perspective view of a sliding element of the securing mechanism of the cantilever box of **Figs. 1** and **2**;

**Fig. 3F** is a perspective view of a secondary tray of the cantilever box of **Figs. 1** and **2**;

**Fig. 3G** is an enlarged view of a portion A5 of **Fig. 3E**;

**Fig. 3H** is a perspective view of a lowermost tray of the cantilever box of **Figs. 1** and **2**;

**Fig. 3I** is a cross-section along line B-B in **Fig. 3H**;

**Fig. 4A** is a cross-section along line C-C in **Fig. 1**;

**Fig. 4B** is an enlarged view of a portion A2 of **Fig. 4A**;

**Fig. 5A** is a cross-section along line D-D in **Fig. 2**;

**Fig. 5B** is an enlarged view of a portion A3 of **Fig. 5A**;

**Fig. 5C** is a side view of **Fig. 5A**; and

**Fig. 5D** is an enlarged view of a portion A4 of **Fig. 5C**.

## DETAILED DESCRIPTION OF EMBODIMENTS

Attention is first directed to Figs. 1 and 2 of the drawings illustrating a cantilever box in accordance with one example of the presently disclosed subject matter, generally designated **100**. The cantilever box comprises three trays as follows: an uppermost tray **10**, a middle tray **30** and a lowermost tray **50**. The trays of the cantilever box **100** are interconnected therebetween by cantilever links, which are pivotally secured to the sidewalls of the trays as follows: a cantilever link **12** and a cantilever link **14** connect the uppermost tray **10** with the middle tray **30**, a cantilever link **32** and a cantilever link **34** connect the uppermost tray **10** with the middle tray **30** and the lowermost tray **50**, and a cantilever link **52** and a cantilever link **54** connect the middle tray **30** with the lowermost tray **50**.

The trays **10**, **30** and **50** have interior storage spaces **11**, **31** and **51** therein, respectively, in which tools and other goods can be stored. The interior storage spaces **11**, **31** and **51** can be divided to sub-sections by different dividers such as a divider **9** of the lowermost tray **50**.

The trays **10**, **30** and **50** are convertible between a stacked position (shown in Fig. 1), and an extended position (shown in Figs. 2, 5A and 5C). By converting the trays **10**, **30** and **50** from the stacked position to the extended position, the content of the interior storage spaces **31** and **51** can be exposed to the user.

The cantilever box **100** includes a cover **15** which is pivotally articulated to the uppermost tray **10**. In Fig. 1 the cover **15** is illustrated in its closed state and in Fig. 2 the cover **15** is illustrated in its open state. The cover has first engagement portions **11** and **13**.

The cantilever box **100** further includes two latches **2** and **3** which are configured for locking the trays at their stacked position by fixing the uppermost tray **10** to the lowermost tray **50**.

The latches **2** and **3** are pivotally mounted to the lowermost tray **50** at mounting portions **4** and **5**, respectively (shown in Fig. 2). The mounting portions **4** and **5** have second engagement portions **7** and **8**, respectively.

When the cover **15** is in its closed state, the latch **2** is mounted to the first and the second engagement portions **11** and **7**, respectively, and the latch **3** is mounted to the first and the second engagement portions **13** and **8**, respectively. This mounting of the latches **2** and **3** locks the trays at their stacked position so that the uppermost tray **10**

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and the middle tray **30** are fixed between the cover member **15** and the lowermost tray **50**.

The cantilever box **100** has a handle **6** pivotally mounted to the uppermost tray **10**. The handle **6** can be used for holding and transporting the cantilever box **100** from place to place when the latches **2** and **3** lock the trays at their stacked position.

When the latches do not fix the uppermost tray **10** to the lowermost tray **50**, the trays can be converted from their stacked position to their extended position. This can be performed by a user-actuated pulling force applied on the uppermost tray **10** in the direction of arrow  $P_1$  (shown in Figs. 1 and 4A) by one or two hands of the user. This pulling force can be applied on the handle **6** or on the uppermost tray **10**.

The cantilever box **100** further has two supporting elements **99** (shown in Fig. 5C), mounted to the bottom wall of middle tray **30** and configured, at the extended position of the trays, for leaning on a surface on which the cantilever box **100** is disposed, and thereby preventing the cantilever box **100** from rolling over.

In general, one way of converting the trays from their extended position to their stacked position is by applying a user-actuated pulling force on the uppermost tray **10** in the direction of arrow  $P_2$  (shown in Fig. 2) by a first hand of the user, while his second hand supports the lowermost tray **50** and provides contra to the pulling force.

In order to eliminate or reduce the likelihood of jamming the user's fingers between the trays (e.g., between the middle tray and the lowermost tray) during the conversion of the trays from their extended position and the stacked position (e.g. by applying a user-actuated pulling force on the middle tray **30** instead of on the uppermost tray **10** in the direction  $P_2$ ), it is important to lock the trays in the extended position, and to allow unlocking them from the extended position and converting them to the stacked position in a controlled and a safe manner. This controlled and safe manner includes forcing the user to locate his first hand (that actuates the pulling force in the direction  $P_2$ ) in a specific location at the uppermost tray **10**, and his second hand (that supports the lowermost tray and provides contra to the pulling force) in a specific location at the lowermost tray **50**.

For this reason, the cantilever box **100** is provided with a first gripping portion **80** which, as detailed below, is disposed at a specific safe location at the uppermost tray **10**. The first gripping portion **80** is configured for being gripped by the first hand of the user for converting the trays from their extended position to their stacked position.

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In addition, the first gripping portion **80** includes a securing mechanism **70** responsible for locking and unlocking the trays at their extended position. The securing mechanism **70** is switchable between a normally locked state (shown, for example, in Figs. 1 and 2) and an unlocked state (not shown), each of which is detailed below.

The securing mechanism **70** is integrated within the first gripping portion **80**, so that the user is required to switch the securing mechanism **70** from its normally locked state to its unlocked state by his first hand while gripping the first gripping portion by the same hand, thereby displacing the uppermost tray **10** for converting the trays **10**, **30** and **50** from their extended position to their stacked position.

The integration of the securing mechanism **70** in the first gripping portion **80** forces the user that converts the trays from their extended position into their stacked position, to locate his first hand at the first gripping portion **80** because the trays must be unlocked from their extended position via the securing mechanism **70** before the actuation of the pulling force on the uppermost tray **10** in the direction  $P_2$ .

In addition, the cantilever box **100** is provided with a second gripping portion **90** which is disposed at a specific safe location in the lowermost tray **10**, as detailed below with respect to Figs. 3H and 3I. The second gripping portion **90** is configured for providing space to the second hand of the user that supports the lowermost tray **50** and provides contra to the pulling force.

The fact that each one of the tray **10**, **30** and **50** is connected by respective cantilever links to the other two trays results in an arrangement according to which the trays are convertible between the stacked position and the extended position in a simultaneous manner. According to this arrangement of the cantilever box **100**, the middle tray **30** cannot be displaced without displacement of the uppermost tray **10**, and vice versa. Therefore, by arresting the uppermost tray **30** with respect to another element of the cantilever box **100**, i.e., a locking member, in the extended position thereof, all the trays will be locked in this position. According to the present example, the securing mechanism **70** arrests a locking member in the form of a first recess **60** disposed at the middle tray **30** (shown in Figs. 5A to 5D), thereby locking the trays at their extended position.

When the trays are converted from their stacked position to their extended position, due to its structure, the securing mechanism **70** is configured for automatically

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locking the trays at this position. This automatic manner of operation is explained below.

When the trays are disposed at their extended position, the securing mechanism **70** is in its normally locked state in which it arrests the first recess **60**, thereby locking the trays at this position. A detailed explanation of the extended position of the cantilever box **100** is detailed below with respect to Figs. 5A to 5D.

When the trays are at their stacked position shown in Fig. 1, the securing mechanism **70** is in its normally locked state, but in this position the trays are not locked. A detailed explanation of the stacked position of the cantilever box **100** is detailed below with respect to Figs. 4A and 4B.

When the trays are at their extended positions, by being switched to its unlocked state, the securing mechanism **70** disengages the first recess **60**, thereby unlocking the trays from their extended position, and facilitating displacement of the trays from their extended position to their stacked position.

Reference is now made to Figs. 3A to 3E, in which the first gripping portion **80** and the securing mechanism **70** are presented in a detailed manner. Figs. 3A to 3E illustrate an example of a safe location at which first gripping portion **80** and the securing mechanism **70** can be disposed in the cantilever box **100**. This safe location allows the user to convert the trays from their extended position to their stacked position in a controlled and a safe manner, which eliminates or reduces the likelihood of jamming the fingers of the user's first hand between the trays during the conversion between the positions.

As shown in Fig. 3A, the uppermost tray **10** has a top wall **16**, a front wall **18**, a bottom wall **20**, an upper perimetric edge **14** and a perimetric bottom edge **19**. The top wall **16** includes the cover **15**. The top wall **16** and the front wall **18** are configured with a front edge **17** therebetween. The front edge **17** constitutes a portion of the top edge **14**. The first gripping portion **80** is disposed at a portion of the top wall **16** and at a portion of the front wall **18**. Moreover, the first gripping portion **80** is disposed at the middle of the front edge **17**, so that the line A-A, which is taken at the middle of the uppermost tray, passes in the middle of the first gripping portion **80**. The first gripping portion **80** is disposed in the middle of the front edge **17** so that when gripped and pulled by the user, a substantially equal and symmetrical force will be applied to the uppermost tray **10**.

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As shown in Fig. 3B, in which an enlarged view of the first gripping portion **80** is presented, the first gripping portion **80** includes a first gripping recess **82** which is formed within the cover **15**, and it includes the securing mechanism **70** that is formed within a portion of the front wall **18**. The first gripping portion **80** is configured to be gripped by a first hand of the user, and particularly by five fingers of this hand. In particular, the first gripping recess **82** is configured to be gripped by the following four fingers of the user's first hand: the index finger, the middle finger, the ring finger, and the little finger. The securing mechanism **70** is configured to be gripped by the fifth finger, i.e., the thumb, as detailed below with respect to Fig. 3E. As shown in Fig. 3B, the first gripping recess **82** is characterized by shape and size which allow accommodation of the above four fingers along the length of the first gripping recess **82**. It should be indicated that although the first gripping recess **82** is configured to accommodate all the four fingers, not all of them are always required for the gripping and the pulling of the first gripping portion **80**. In addition, since the first gripping recess **82** is formed within the cover **15**, when the cover is in its open state, an internal portion **85** (shown in Fig. 3D) can be used instead of the first gripping recess **82** for accommodating the above four fingers therein.

The first gripping portion **80** further includes an interior section **84** (shown in Fig. 3D) which, together with a sliding element **71** constitutes the securing mechanism **70**.

As shown in Fig. 3E, the sliding element **71** has a first end **74**, a second end **75** and a middle portion **78** therebetween. The first end **74** is configured with a biasing mechanism in the form of two bendable elements **76** and **77**, which act as a compression spring. The bendable elements **76** and **77** have a first end **76'** and a second end **77'**, respectively. When the sliding element **71** is tightly received within the interior section **84**, the first end **76'** and the second end **77'** are engaging with and supported by an upper biasing wall **86** of the interior section **84**. This engagement outwardly biases the sliding element **71** in a downward direction indicated by an arrow **Z<sub>1</sub>** (in Fig. 3D) by exerting thereon an outwardly biasing force and thereby causing the securing mechanism to be normally in its locked state. The sliding element and the biasing mechanism can be integrated in a single element. The sliding element **71** and the bendable elements **76** and **77** are integrated in a single element and made of the same material.

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The middle portion **78** includes a thumb supporting element **72** having a bottom wall **73** (shown in Fig 3D). The bottom wall **73** is shaped so as to accommodate the fifth finger of the user's first hand, i.e., its thumb, when the first gripping portion **80** is gripped by the user's first hand.

The securing mechanism **70** is convertible from its normally locked state to its unlocked state when the sliding element **71** slides within the interior section **84** along an upward direction indicated by an arrow  $Z_2$ . The securing mechanism **70** can be switched from its locked state to its unlocked state upon application of an inwardly biasing force on the bottom wall **73** of the thumb supporting element **72** in the direction  $Z_2$ . Upon the sliding of the sliding element **71** in the direction  $Z_2$ , the bendable elements **76** and **77** are forced by the upper biasing wall **86** to be bent such that their ends **76'** and **77'** are forced to move in the directions  $Z_3$  and  $Z_4$ , respectively while sliding along the upper biasing wall **86** and moving away from each other.

When the inwardly biasing force is ceased from being applied, the bendable elements **76** and **77** revert to their original shape, thereby forcing the sliding element **71** to slide in the direction  $Z_1$ , and thereby causing the securing mechanism **70** to assume its normally locked state.

The first gripping portion **80** has dimensions which are configured to fit the size of an average hand of a user. These dimensions include a reasonable distance between the thumb supporting element **72** and the first gripping recess **82**.

The second end **75** has a securing protrusion **79** configured with a front face **79'**. As clearly shown in Fig. 3D, in the normally locked state of the securing mechanism **70**, the securing protrusion **79** protrudes out of the surface of the bottom wall **20**.

The securing protrusion **79** is configured to be received within the first recess **60** of the middle tray **30**, thereby locking the trays at their extended position.

Reference is now made to Fig. 3F and 3G in which the middle tray **30** is illustrated. The middle tray **30** is configured with a top wall **36**, a front wall **37**, a rear wall **38**, a perimetric bottom edge **34** and a perimetric top edge **35**. The top wall **36** and the rear wall **38** are configured with a rear edge **39** therebetween. The rear edge **39** constitutes a portion of the top edge **35**. The first recess **60** is disposed in the middle of the rear edge **39**, so that when the trays are in their extended position, the first recess **60** is located underneath the first gripping portion **80**, and more particularly under the securing protrusion **79**. The top wall **36** and the front wall **37** are further configured

with a front edge **40** therebetween. The middle tray **30** further has a second recess **62**. The second recess is disposed in the middle of the front edge **40**, so that when the trays are in their stacked position, the second recess **62** is located underneath the first gripping portion **80**, and more particularly under the securing protrusion **79**. In this position of the trays, the second recess **62** is configured to accommodate the securing protrusion **79** therein.

The middle tray **30** is further configured with a biasing protrusion **41** which protrudes out of the surface of the top wall **39**. Since securing protrusion **79** and the biasing protrusion **41** protrude out of their respective trays, they engage each other during the conversion of the trays from their stacked position to their extended position. When this engagement takes place, the biasing protrusion **41** exerts an inwardly biasing force on the front face **79'**, and thereby on the whole sliding element **71**, in the direction  $Z_2$ . This biasing force causes the sliding element **71** to be inwardly biased. When the front face **79'** passes through the securing protrusion **79** and disengaged therefrom, the outwardly biasing force applied by the bendable elements **76** and **77** is greater than said inwardly biasing force, which causes the sliding element **71** to slide downwards to its natural state. This results in causing the securing protrusion **79** to jump into the first recess **60**, thereby allowing the securing mechanism to arrest the first recess **60**.

Reference is now made to Figs. 3H and 3I, in which the lowermost tray **50** is illustrated with the second gripping portion **90**. Figs. 3H and 3I illustrate an example of a safe location at which second gripping portion **90** is located in the cantilever box **100**. This safe location allows the user to convert the trays from their extended position to their stacked position in a controlled and a safe manner which eliminates or reduces the likelihood of jamming the fingers of the user's second hand between the trays during the conversion between the positions.

As shown in Figs. 3H and 3I, the lowermost tray **50** has a front wall **56**, a rear wall **57**, a bottom wall **58**, a perimetric top edge **54** and a perimetric bottom edge **55**. The second gripping portion **90** is formed within the front wall **92**. The second gripping portion **90** has a second gripping recess **92** and a second gripping supporting surface **93**.

The second gripping portion **90** is configured to be gripped by a second hand of the user, and particularly by the five fingers and the palm of this hand, when the trays are converted from their extended position to their stacked position. This gripping is performed simultaneously the gripping of the first gripping portion **80** by the user's first

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hand. In particular, the second gripping recess **92** is configured to receive the following four fingers of the user's first hand: the index finger, the middle finger, the ring finger, and the little finger. The second gripping recess **92** is characterized by shape and size which allow accommodation of these four fingers along the length of the second gripping recess **92**. While the above four fingers are received within the second gripping recess **92**, the thumb and the palm of the user's second hand are configured to engage the second gripping supporting surface **93** so as to provide contra to the pulling force applied to the uppermost tray **10**.

Reference is now made to Figs. 4A, 4B and 5A to 5D which schematically illustrate different views of the cantilever box **100** in its stacked position and its extended position, respectively. The description below is provided for summarizing the operation of the cantilever box **100**.

As shown in Figs. 4A and 4B, the trays are in their stacked position, and the latch **3** is fixing the uppermost tray **10** to the lowermost tray **50**. In this position, the bottom edge **19** of the uppermost tray **10** rests on the top edge **35** of the middle tray **30**, and the bottom edge **34** of the middle tray **30** rests on the top edge **54** of the lowermost tray. As shown in Fig. 4B, the securing mechanism **70** is in its normally locked state while the securing protrusion **79** is freely accommodated within the second recess **62**.

In order to convert the trays from their stacked position to their extended position, the latches **2** and **3** have to be opened. Afterwards, the user can apply a pulling force on the uppermost tray **10** in the direction of arrow **P<sub>1</sub>** (shown in Fig. 1) by one or two hands of the user. This pulling force can be applied while the user pulls the handle **6** or while he grips the first gripping portion **80**. The user can also grip the second gripping portion **90** for holding the whole arrangement on place and preventing it from rolling over.

As shown in Figs. 5A to 5D, the trays **10**, **30** and **50** are locked at their extended position. At this position of the trays, a front portion of the bottom edge **19** rests on the rear edge **39** and a front portion of the bottom edge **34** rests on the rear edge **39**. In addition, the securing protrusion **79** is received within the first recess **60**, thereby locking the trays in their extended position. If the user will try to convert the trays to their stacked position without switching the securing mechanism to its unlocked state, the securing protrusion **79** will try to move in the direction **P<sub>3</sub>** (shown in Fig. 5D) and will immediately engage an internal wall **61** of the first recess **60**. This will arrest the

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securing protrusion **79** on place, and thereby will prevent displacement of the uppermost tray **10** with respect to the middle tray **30**, and consequently the conversion of the trays into their stacked position.

In order to close the cantilever box **100** by converting the trays **10**, **30** and **50** to their stacked position in a controlled and a safe manner, the following steps have to be performed by a user:

- a. closing the cover **15** (if it was previously opened). As indicated above, the cover can be left opened, and in this case the internal portion **85** will be used instead of the first gripping recess **82** in step 'b' below;
- b. gripping the first gripping portion **80** the user's first hand. The gripping is performed by placing the index finger, the middle finger, the ring finger and the little finger within the first gripping recess **82**, and by engaging the bottom wall **83** of the thumb supporting element **72** by the user's thumb of the first hand;
- c. gripping the second gripping portion **90** by the user's second hand. The gripping is performed by placing the index finger, the middle finger, the ring finger and the little finger within the second gripping recess **92**, and by engaging the second gripping supporting surface **93** by the thumb and the palm of the second hand;
- d. applying an inwardly biasing force on the bottom wall **83** by the thumb of the first hand in the direction  $Z_2$ , thereby switching the securing mechanism to its unlocked state and facilitating displacement of the trays from their extended position into their stacked position;
- e. while tightly gripping the second gripping portion **90** by the second hand and maintaining the application of the inwardly biasing force on the bottom wall **83**, applying a pulling force on the first gripping portion **80** in the direction  $P_2$ , and thereby displacing the uppermost tray **10** and the middle tray **30** towards the lowermost tray **50** until these trays are brought into their stacked position.

It should be indicated that the above description and its corresponding drawings present only one example of the location of the first gripping portion, the securing mechanism, and the second gripping portion at the cantilever box of the presently

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disclosed subject matter, for allowing safe and controlled conversion of the trays between their extended and their stacked positions.

**CLAIMS:**

1. A cantilever box comprising:
  - at least two trays, including a lowermost tray and an uppermost tray, interconnected therebetween by cantilever links pivotally secured to said trays. The trays are convertible at least between a stacked position, and an extended position;
  - a first gripping portion, disposed at the uppermost tray, configured for being gripped by a user for converting the trays between their extended position and their stacked position; and
  - a securing mechanism switchable between a locked state in which when the trays are at their extended position, the securing mechanism is configured for arresting a locking member, thereby locking the trays at their extended position; and an unlocked state in which the securing mechanism is disengaged from said locking member, thereby facilitating displacement of the trays from their extended position into their stacked position;
  - said securing mechanism being disposed in proximity to the first gripping portion, or integrated therein, so that the user is required to switch the securing mechanism from its locked state to its unlocked state by his first hand while gripping the first gripping portion by the same hand, thereby displacing the uppermost tray for converting the trays from their extended position to their stacked position.
2. The cantilever box according to Claim 1, wherein the uppermost tray is configured with a top wall, a front wall and a bottom wall, said top wall and said front wall being configured with a front edge therebetween, having a longitudinal axis, the first gripping portion being disposed at the middle of the front edge along its longitudinal axis.
3. The cantilever box according to Claim 2, wherein the securing mechanism is disposed at the front wall of the uppermost tray.
4. The cantilever box according to Claim 2 or 3, wherein the first gripping portion has a first gripping recess disposed at the top wall of the uppermost tray.
5. The cantilever box according to Claim 4, wherein the first gripping recess is configured with shape and size for accommodating one or more of the following

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fingers of the user's first hand: index finger, middle finger, ring finger, and little finger.

6. The cantilever box according to any one of the preceding claims, further comprising a cover member pivotally mounted to the uppermost tray and constitutes a portion of its top wall.
7. The cantilever box according to Claim 6, when dependent on Claim 4 or 5, wherein said first gripping recess is disposed at the cover member.
8. The cantilever box according to any one of the preceding claims, wherein said securing mechanism is normally in its locked state.
9. The cantilever box according to any one of the preceding claims, wherein said securing mechanism comprises a sliding element having a first end configured with a biasing mechanism for outwardly biasing the sliding element by exerting thereon an outwardly biasing force and thereby causing it to be normally in its locked state; and a second end including a securing protrusion configured with a front face.
10. The cantilever box according to Claim 9, wherein the first gripping portion is configured with an interior section, which together with the sliding element constitutes the securing mechanism.
11. The cantilever box according to Claim 9 or 10, wherein the sliding member further comprises a middle portion configured with a thumb supporting element configured to provide support to a thumb of the user's first hand when switching the securing mechanism from its locked state to its unlocked state by applying an inwardly biasing force on the thumb supporting element.
12. The cantilever box according to any one of Claims 9 to 11, wherein the securing protrusion is configured to be received at the locking member, and thereby arresting the locking member in the locked state of the securing mechanism.
13. The cantilever box according to any one of Claims 9 to 12, when dependent on Claim 2, wherein the securing protrusion normally projects out of the surface of the bottom wall of the uppermost tray.
14. The cantilever box according to Claim 10, wherein the sliding element is disposed within the interior section of the first gripping portion, the interior section being configured with a biasing wall configured for engaging the biasing

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mechanism and providing support thereto for exerting the outwardly biasing force on the sliding element.

15. The cantilever box according to any one of Claims 9, 10 and 14, wherein the biasing mechanism includes at least one bendable element.
16. The cantilever box according to Claim 14, wherein the biasing mechanism includes two bendable elements, the ends of which are configured to move away from each other and to slide on the biasing wall when the securing mechanism is switched from its normally locked state to its unlocked state.
17. The cantilever box according to Claim 16, wherein the ends of the bendable elements are further configured to approach each other and to slide on the biasing wall when the securing mechanism is switched from its unlocked state to its normally locked state.
18. The cantilever box according to any one of Claims 9 to 17, wherein the sliding element and the biasing mechanism are integrated in a single element.
19. The cantilever box according to any one of Claims 9 to 18, wherein the sliding element and the biasing mechanism are made of the same material.
20. The cantilever box according to any one of the preceding claims, further comprising a second gripping portion, disposed at the lowermost tray, configured for being gripped by a user's second hand for providing support to the cantilever box and holding it on place, when the trays are converted between their extended position and their stacked position.
21. The cantilever box according to Claim 20, wherein the lowermost tray is configured with a front wall at which the second gripping portion is disposed.
22. The cantilever box according to Claim 20 or 21, wherein the second gripping portion is configured with a second gripping recess configured with shape and size for accommodating one or more of the following fingers of the user's second hand: index finger, middle finger, ring finger, and little finger.
23. The cantilever box according to any one of Claims 20 to 22, wherein the second gripping portion is configured with a second gripping supporting surface configured for providing support to a palm and a thumb of the user's second hand.
24. The cantilever box according to any one of the preceding claims, wherein the locking member is disposed at a secondary tray below the uppermost tray.

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25. The cantilever box according to Claim 24, wherein the secondary tray is configured with a top wall and a rear wall, said rear wall being configured with a rear edge therebetween, having a longitudinal axis.
26. The cantilever box according to Claim 24 or 25, when dependent on Claim 9, wherein the secondary tray is configured with a biasing protrusion configured to engage the front face of the securing protrusion for exerting an inwardly biasing force on the sliding element during the conversion of the trays from the stacked position to their extended position.
27. The cantilever box according to Claim 26, wherein the biasing protrusion projects out of the surface of the top wall of the secondary tray.
28. The cantilever box according to Claim 25, wherein the locking member is disposed in the middle of the rear edge along said longitudinal axis.
29. The cantilever box according to any one of the preceding claims, wherein the locking member is a recess or a fixing element configured to engage with the securing mechanism, and thereby to be arrested by the securing mechanism in its locked state.
30. The cantilever box according to any one of the preceding claims, further comprising at least one latch configured for locking the trays at their stacked position.
31. The cantilever box according to Claim 30, wherein the at least one latch is pivotally mounted to the lowermost tray at a mounting portion.
32. The cantilever box according to Claim 31, when dependent on Claim 9, wherein the cover member is configured with at least one first engagement portion and the mounting portion is configured with at least one second engagement portion, when the cover is in its closed state, the latch is mounted to the first and the second engagement portions, thereby locking the trays at their stacked position so that the uppermost tray and the middle tray are fixed between the cover member and the lowermost tray.
33. The cantilever box according to any one of the preceding claims, further comprising at least one handle mounted to an uppermost tray of the trays.

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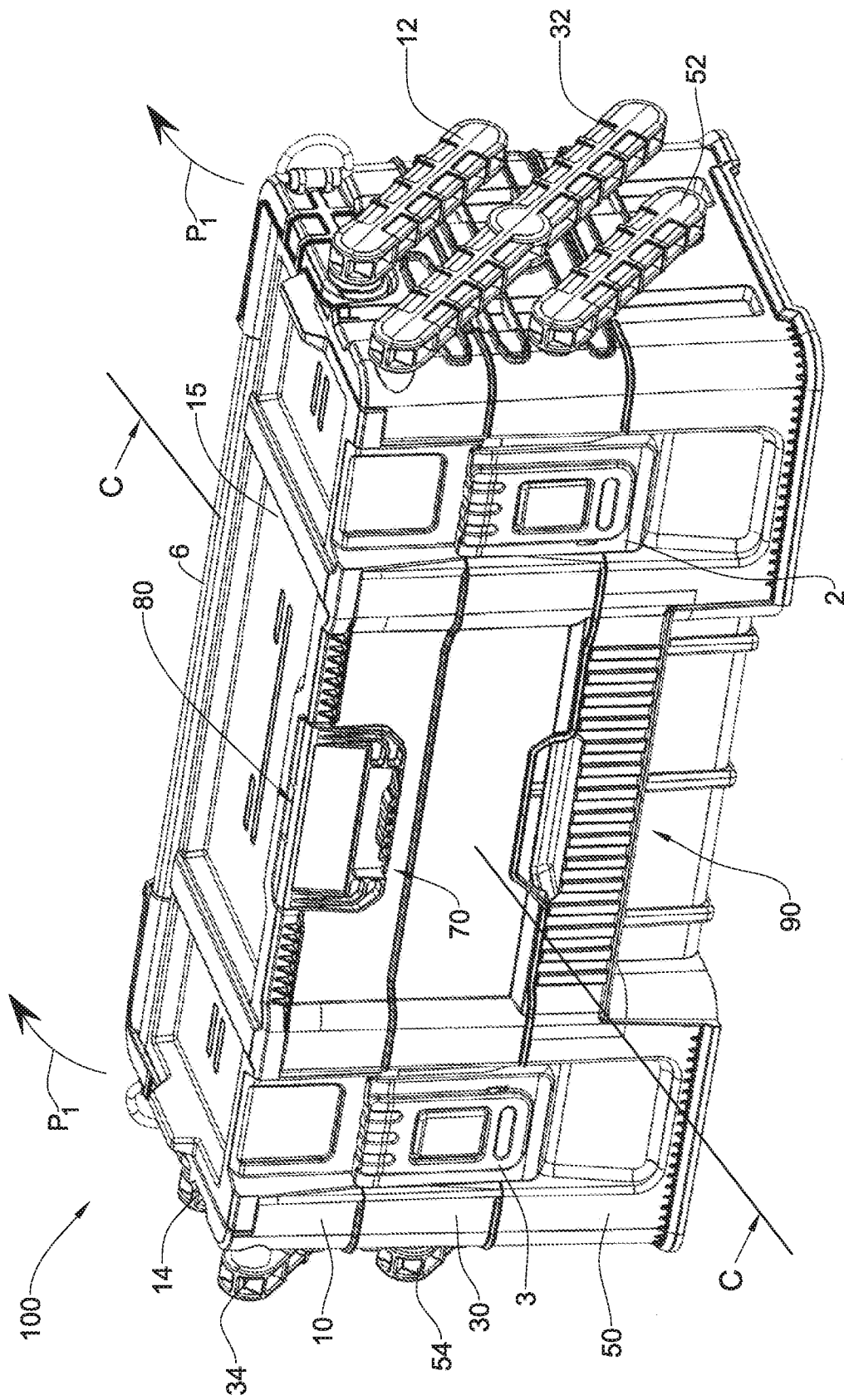


Fig. 1

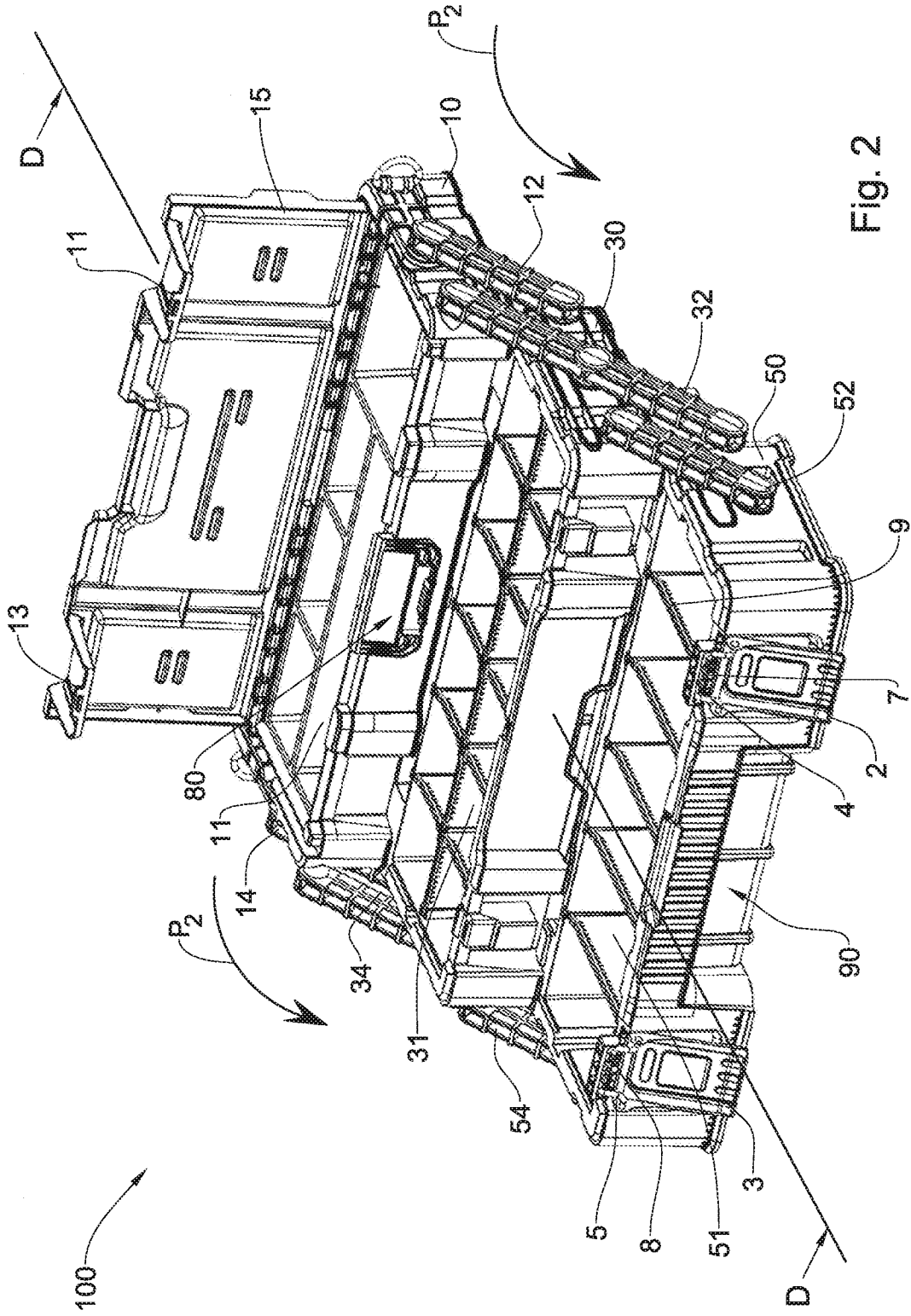


Fig. 2

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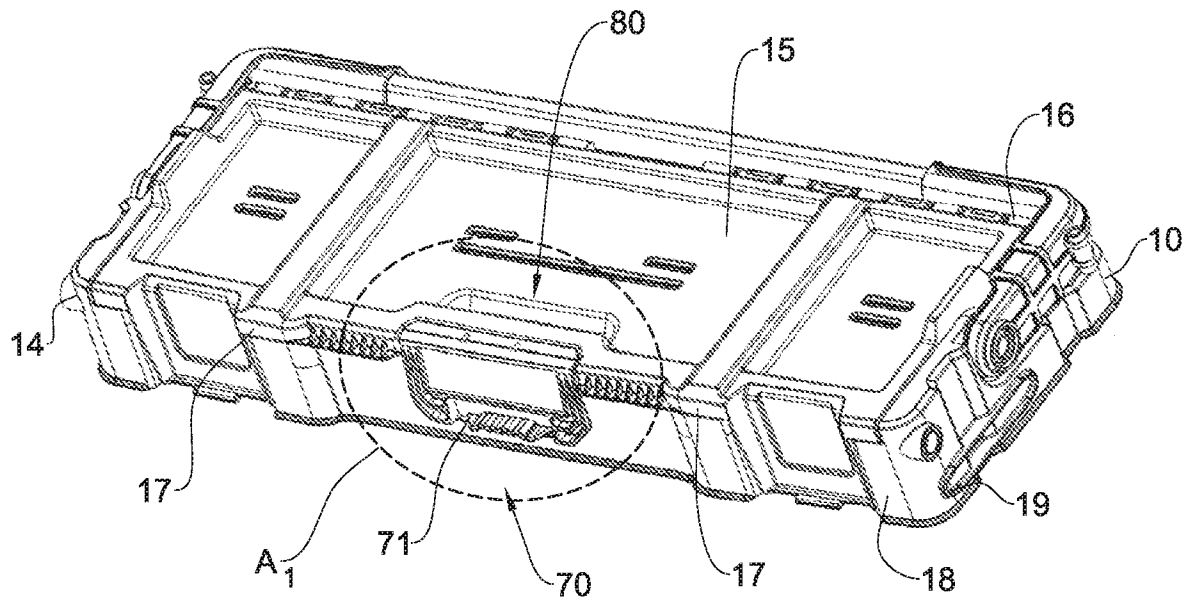


Fig. 3A

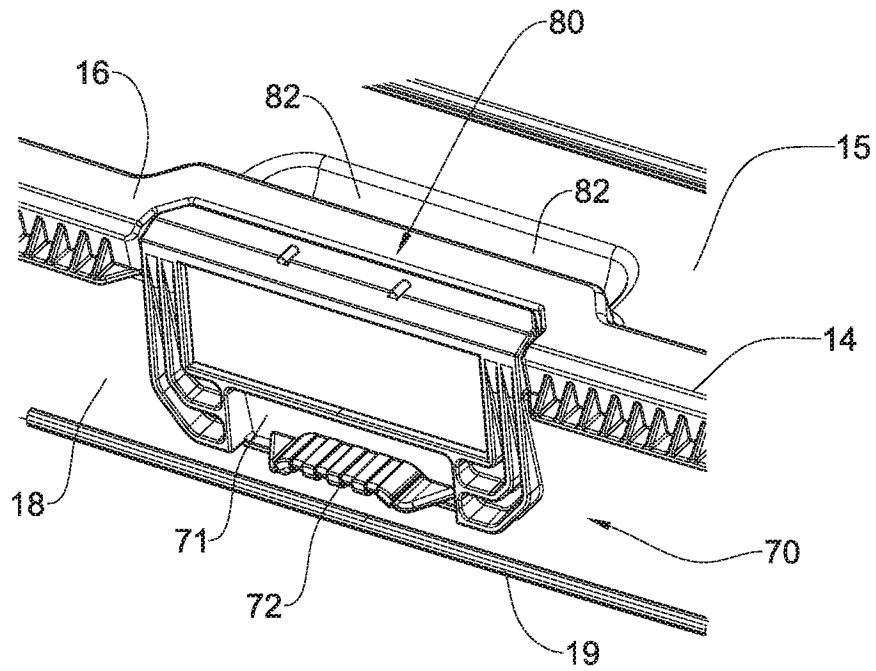


Fig. 3B

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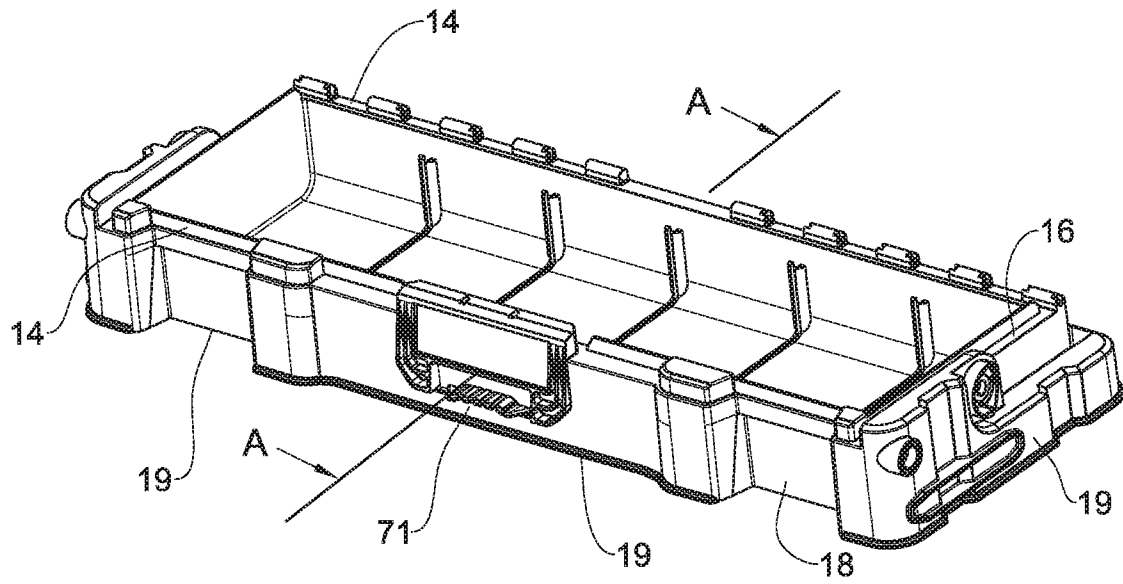


Fig. 3C

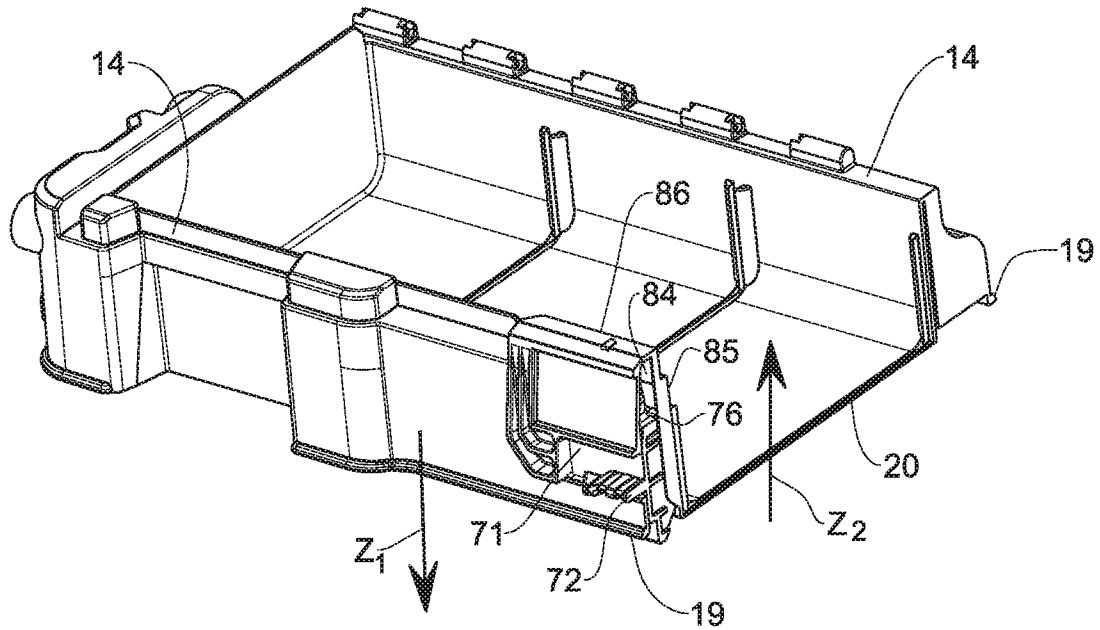


Fig. 3D

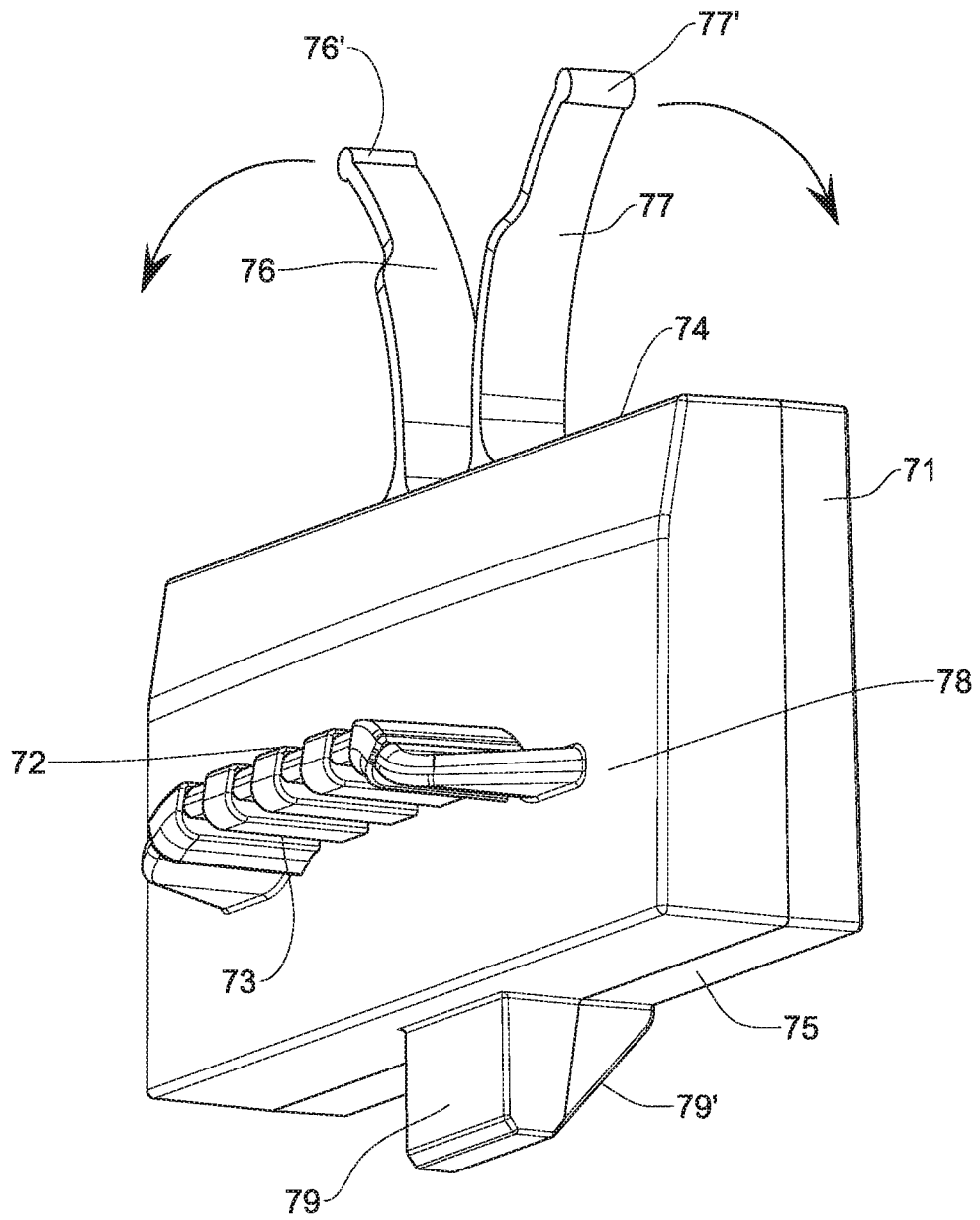


Fig. 3E

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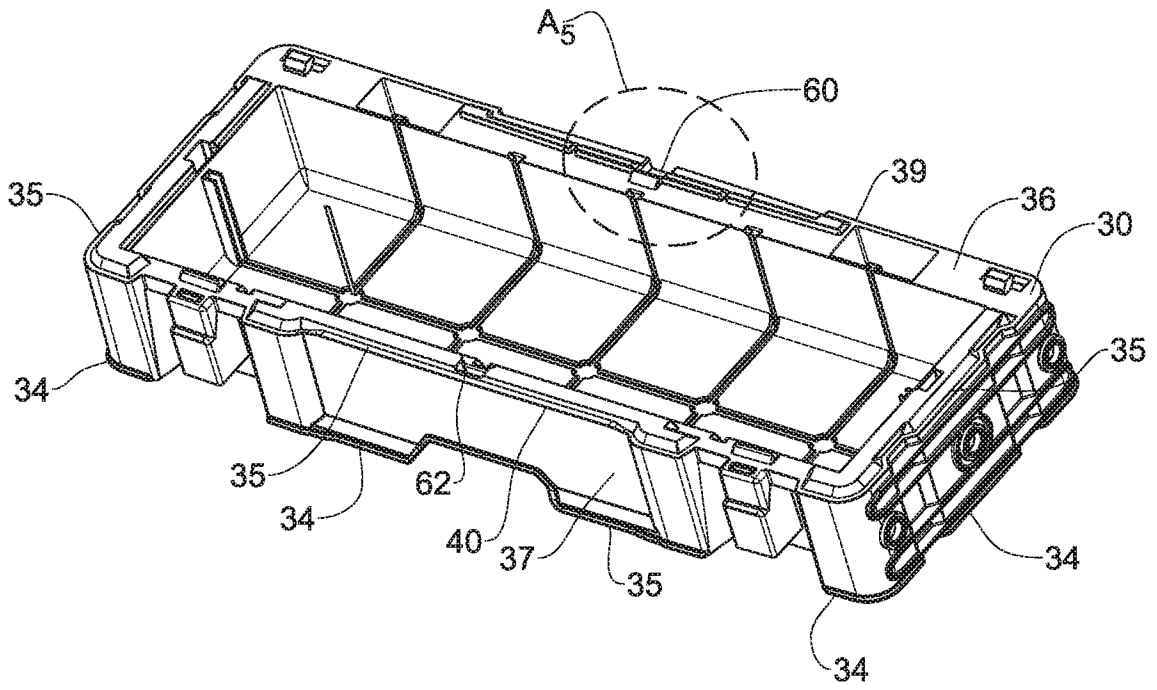


Fig. 3F

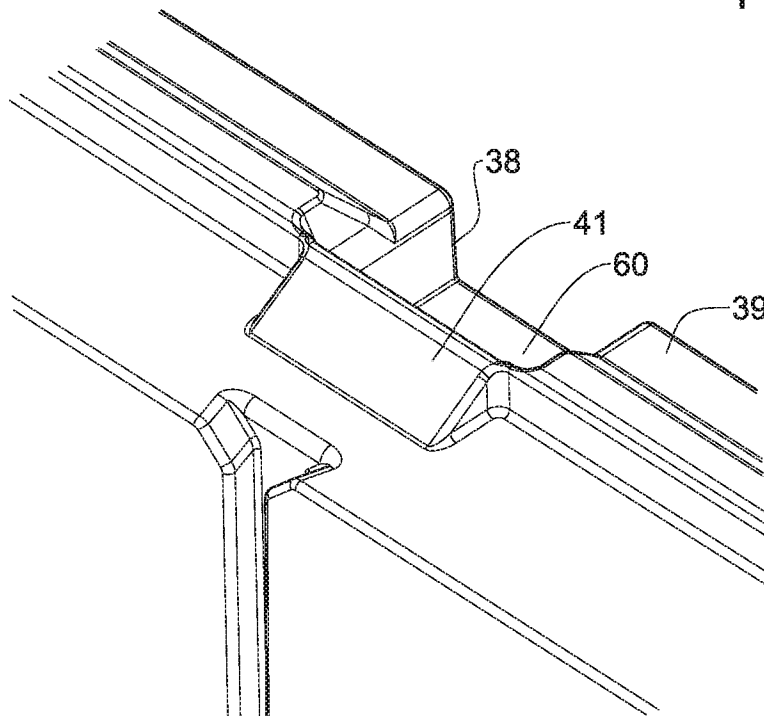


Fig. 3G

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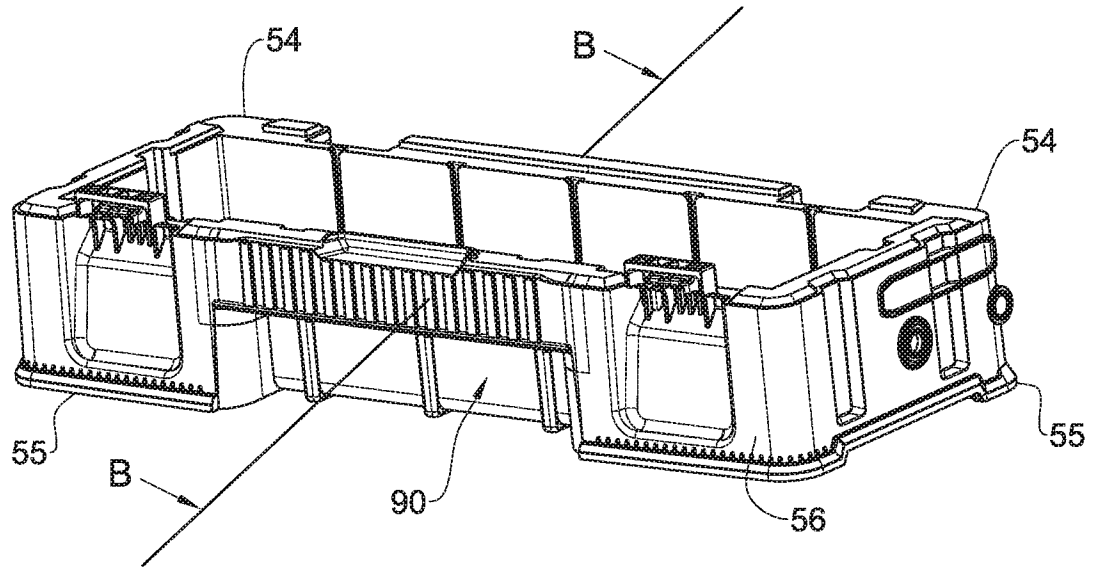


Fig. 3H

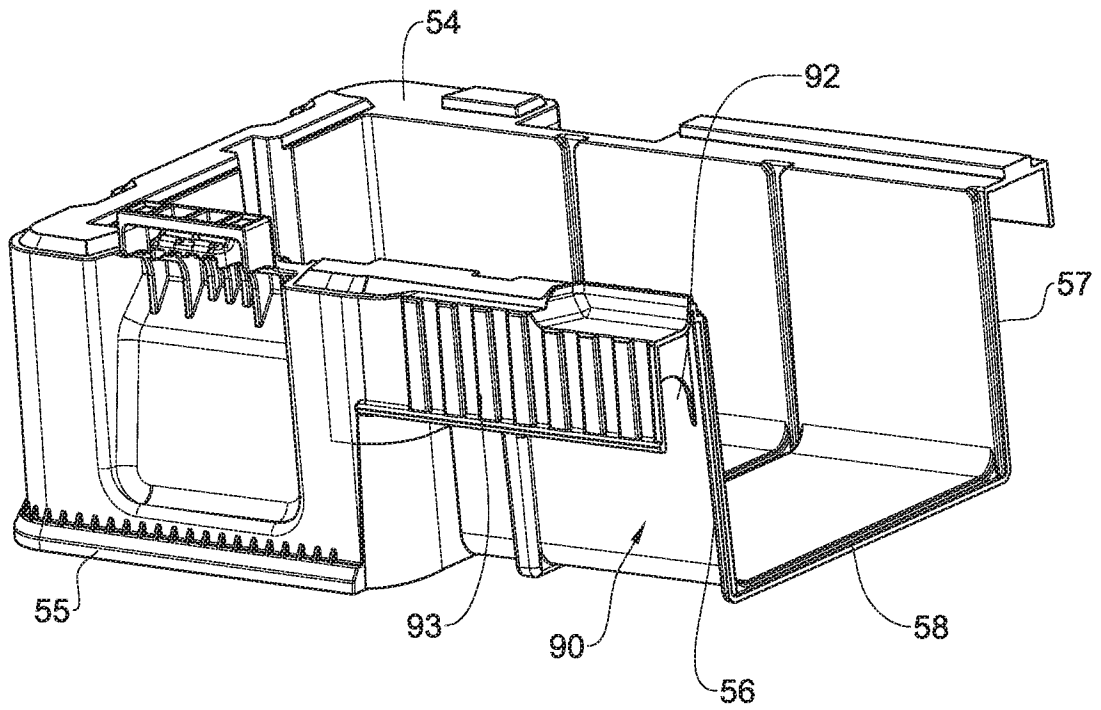


Fig. 3I

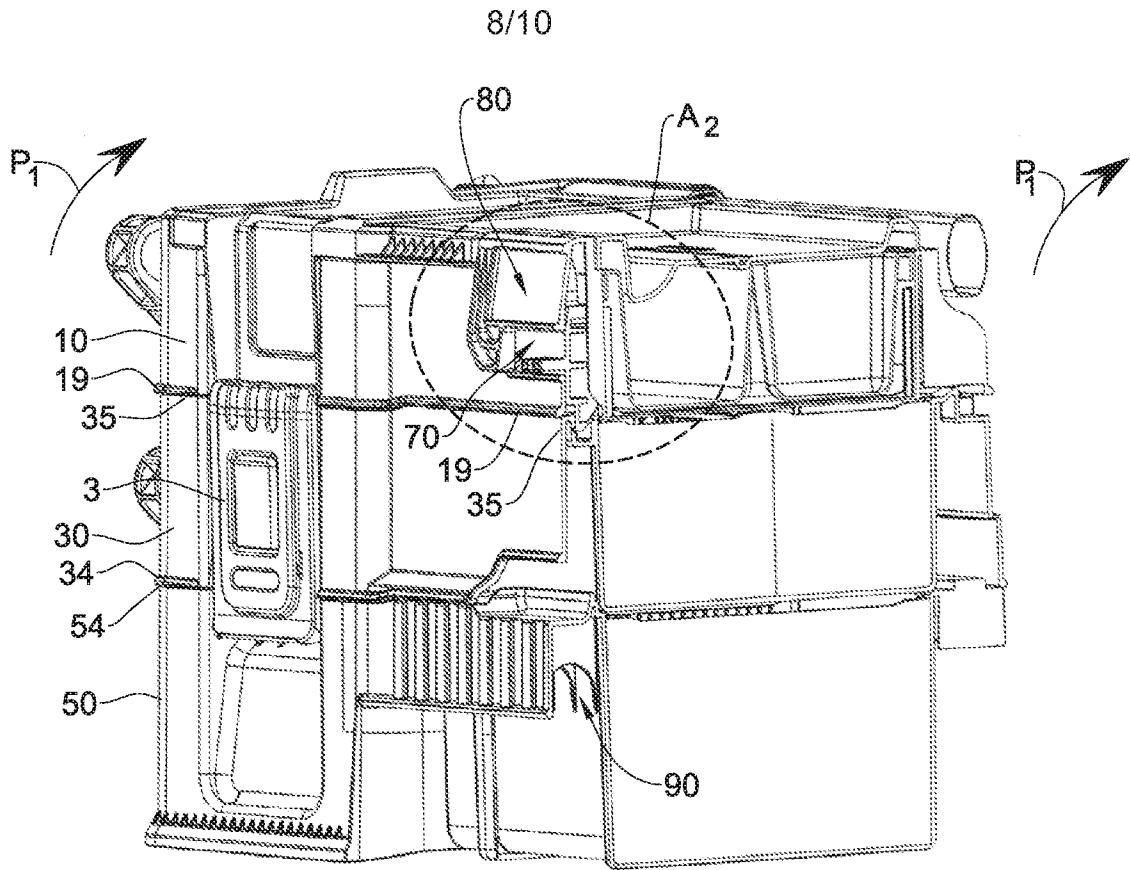


Fig. 4A

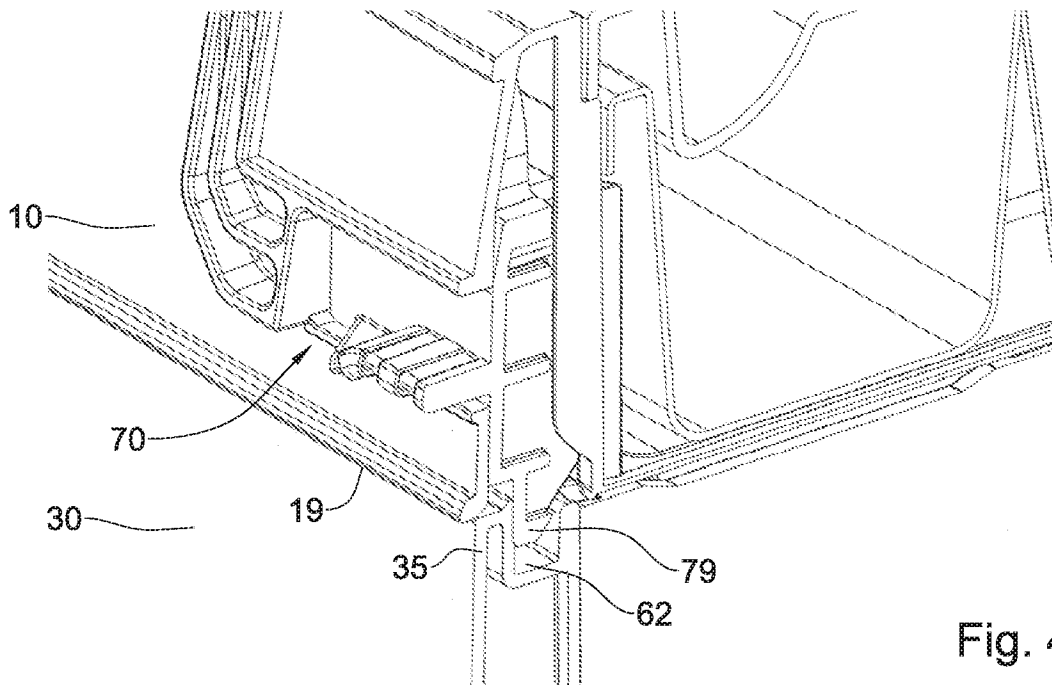


Fig. 4B

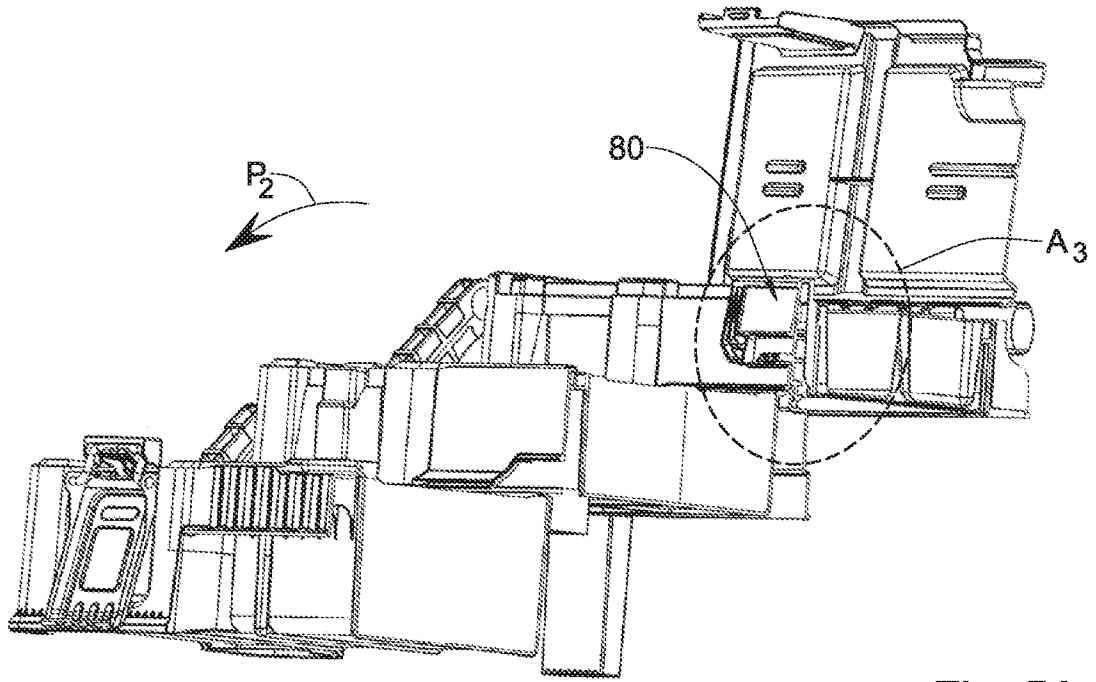


Fig. 5A

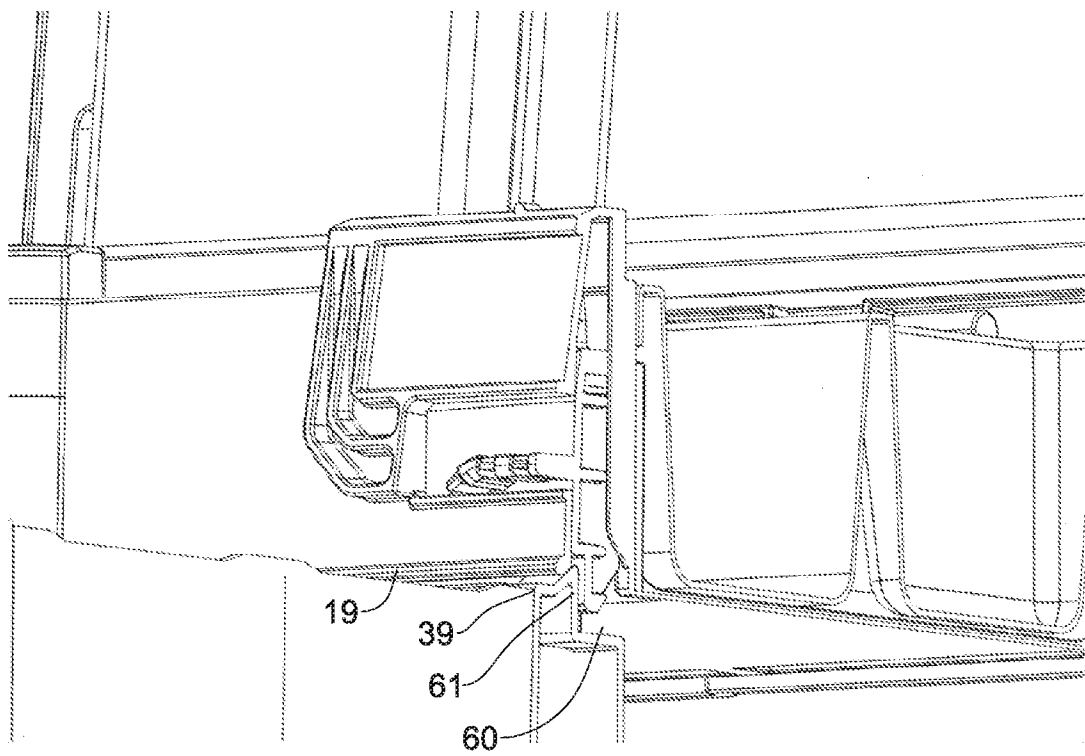
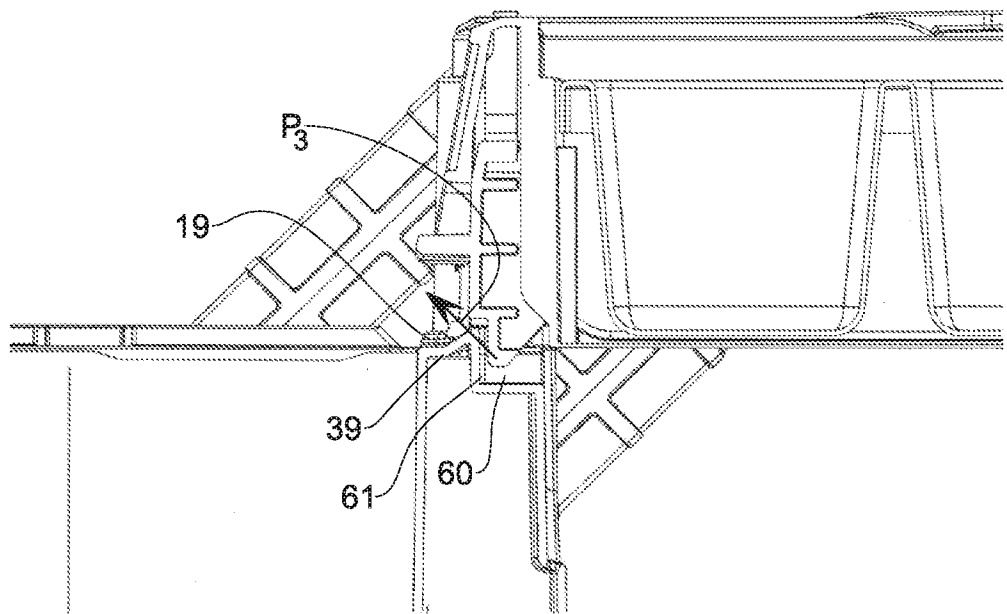
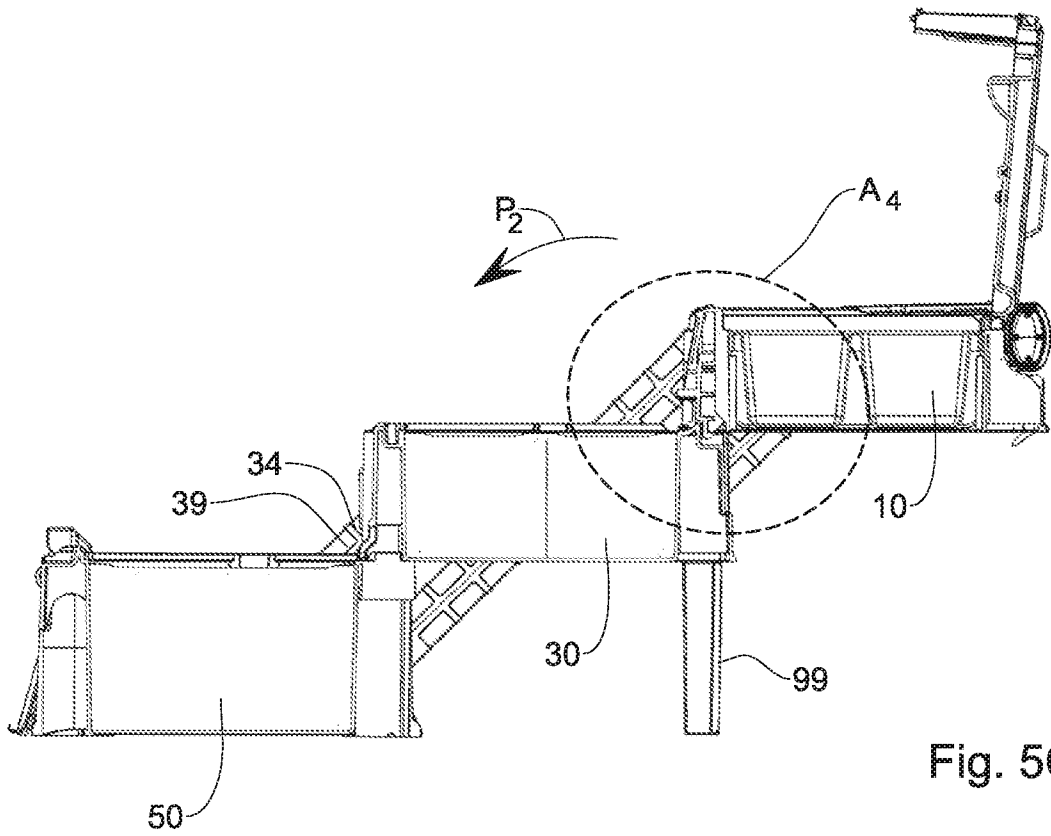


Fig. 5B

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INTERNATIONAL SEARCH REPORT

International application No  
PCT/IL2013/051063

A. CLASSIFICATION OF SUBJECT MATTER  
INV. B25H3/02  
ADD.  
According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED  
Minimum documentation searched (classification system followed by classification symbols)  
B25H

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)  
EPO-Internal

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
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X	US 1 882 756 A (BOYNTON CHARLES T) 18 October 1932 (1932-10-18) page 1, line 70 - page 2, line 27; figures -----	1,8,9, 30,33
A	EP 1 859 908 A1 (ZAG IND LTD [IL]) 28 November 2007 (2007-11-28) paragraphs [0015], [0019], [0023], [0029] - [0033]; figures -----	1-33
A	US 2 374 037 A (PIKER HERBERT M) 17 April 1945 (1945-04-17) page 2; figures -----  -/--	1-33

Further documents are listed in the continuation of Box C.

See patent family annex.

\* Special categories of cited documents :

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- "T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention
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Date of the actual completion of the international search  9 April 2014	Date of mailing of the international search report  24/04/2014
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Name and mailing address of the ISA/ European Patent Office, P.B. 5818 Patentlaan 2 NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Fax: (+31-70) 340-3016	Authorized officer  David, Radu
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## INTERNATIONAL SEARCH REPORT

International application No  
PCT/IL2013/051063

C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
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International application No

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US 2374037	A	17-04-1945	NONE
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US 2488067	A	15-11-1949	NONE
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