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(54) **Shedding control method and apparatus in a weaving machine**

Verfahren und Vorrichtung zur Fachbildungssteuerung in einer Webmaschine

Procédé et dispositif de commande de la formation de la foule pour métier à tisser

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(73) Proprietor: **Kabushiki Kaisha Toyota Jidoshokki
Kariya-shi, Aichi-ken (JP)**

(72) Inventors:

- **Sugiyama, Hiromasa, c/o Kabushiki Kaisha Toyoda Kariya-shi, Aichi-ken (JP)**
- **Toda, Motoaki, c/o Kabushiki Kaisha Toyoda Kariya-shi, Aichi-ken (JP)**
- **Hara, Shigeru, c/o Kabushiki Kaisha Toyoda Kariya-shi, Aichi-ken (JP)**

- **Tsuji, Yukihiro, c/o Kabushiki Kaisha Toyoda Kariya-shi, Aichi-ken (JP)**
- **Abe, Hironobu, c/o Kabushiki Kaisha Toyoda Kariya-shi, Aichi-ken (JP)**

(74) Representative: **HOFFMANN - EITLE
Patent- und Rechtsanwälte
Arabellastrasse 4
81925 München (DE)**

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- US-A- 3 557 842**
- **PATENT ABSTRACTS OF JAPAN vol. 1999, no. 08, 30 June 1999 (1999-06-30) & JP 11 061590 A (TOYOTA AUTOM LOOM WORKS LTD), 5 March 1999 (1999-03-05)**

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Description

BACKGROUND OF THE INVENTION

1. Field of the Invention

[0001] The present invention relates to a shedding control method and a shedding control apparatus in a weaving machine having a plurality of shedding drive motors provided independently of a weaving machine drive motor, and a plurality of heddle frames, each of the heddle frames corresponding to and driven by a single one of the shedding driving motors.

2. Description of the Related Art

[0002] The handling state of warp associated with the shedding formation of the warp influences weft insertion performance of weft, and the handling state of the warp is influenced by tension on the warp. If the warp tension is small, it is likely to cause the warp entanglement and thus the warp handling is deteriorated. In the case where the warp handling is deteriorated, it is likely to cause the weft insertion error in a jet loom, and in the case of a rapier weaving machine, the running performance of a rapier head for transportation of the weft is deteriorated, and a ratio of cutting the warp with the rapier head is increased.

[0003] The handling state of the warp can be changed by modifying a shedding curves, as disclosed, for instance, in Japanese Patent Laid-open No. 7-34355. In a conventional apparatus of Japanese Patent Laid-open No. 7-34355, heddle frames are driven by drive motors provided independently of a weaving machine drive motor, and the modification of the shedding curve is carried out to change a dowel (a stationary angle) or a shedding amount. If the dowel is increased, the tension on the warp from a closed position toward a maximum shedding position is rapidly increased, to provide the excellent warp handling. If the shedding amount is increased, the tension on the warp is increased, to provide the excellent warp handling.

[0004] However, as in the case of a dobby-weaving, there is such a weaving form that a heddle frame stays at the uppermost position or the lowermost position for one or more rotations of the weaving machine, and the number of vertical motion of that heddle frame is smaller than those of the other heddle frames. The warp vertically moved by the heddle frame which is smaller in the number of vertical motion than the others is less consumed than the warps vertically moved by the other heddle frames. This difference in the consumption amount between the warps causes the lowering of tension on the warp less consumed, and deteriorates the warp handling. The conventional apparatus disclosed in Japanese Patent Laid-open No. 7-34355 does not contain a concept of the warp handling taking into account the loosening of the warp associated with the consumption

amount difference among warps respectively corresponding to the heddle frames.

[0005] EP 0 513 728 relates to a shedding controlling apparatus for a loom wherein each of a plurality of heald frames is driven by a drive motor for the exclusive use therefore. During steady operation of the loom, when a crank angle is inputted to a position instructing section, the position instructing section produces an aimed amount of rotation, and a position controlling section controls the drive motor to rotate in accordance with the aimed amount of rotation to eliminate a deviation thereof from a crank shaft of the loom to establish a synchronized relationship between them.

[0006] When an operation instruction signal is generated during stopping of the loom, movement instructing means drives the drive motor by a predetermined amount of rotation by way of an OR gate and the position controlling section in accordance with a shedding pattern designated by way of shedding instructing means and shedding pattern instructing means so that a leveling operation of the heald frame, a pick finding operation and a starting preparing operation may be performed automatically.

SUMMARY OF THE INVENTION

[0007] An object of the present invention is to provide a shedding control method and a shedding control apparatus, each of which can attain the improved warp handling or effectively improve the textile quality.

[0008] A shedding control method according to the present invention is a method of controlling sheddings in a weaving machine having a plurality of shedding drive motors provided independently of a weaving machine drive motor, and a plurality of heddle frames, each of the heddle frames corresponding to and driven by a single one of the shedding driving motors, in which,

of shedding curves indicative of motion of the heddle frames, a shedding curve indicative of motion of one heddle frame for a time period where it is moved from one of the uppermost position or the lowermost position to the other is selected or set for each of the plurality of heddle frames independently on the basis of weave information including weft density, and

each of the shedding drive motors is drivingly controlled to cause the respective one of the plurality of heddle frames to make a motion along the shedding curve thus set or selected.

[0009] In the shedding control method in a weaving machine according to the present invention, the weave information may include shedding patterns respectively corresponding to the plurality of heddle frames.

[0010] In the shedding control method in a weaving machine according to the present invention, the weave information may include weft densities and shedding

patterns respectively corresponding to said plurality of heddle frames.

[0011] In the shedding control method in a weaving machine according to the present invention, at least two kinds of shedding curves distinguished one from the other by the magnitude of stationary angles may be prepared for the shedding curve to be set or selected.

[0012] A shedding control apparatus according to the present invention is an apparatus for controlling sheddings in a weaving machine having a plurality of shedding drive motors provided independently of a weaving machine drive motor, and a plurality of heddle frames, each of the heddle frames corresponding to and driven by a single one of the shedding driving motors, the shedding control apparatus including:

shedding curve setting means for storing shedding curves indicative of motion of the heddle frames therein, and selecting or setting, of the shedding curves, a shedding curve indicative of motion of one heddle frame for a time period where it is moved from one of the uppermost position and the lowermost position to the other for each of the plurality of heddle frames independently on the basis of weave information inputted therein from the external; and control means for drivingly controlling each of the shedding drive motors to cause the respective one of the plurality of heddle frames to make a motion along the shedding curve thus set or selected by the shedding curve setting means.

[0013] In the shedding control apparatus in a weaving machine according to the present invention, the weave information may include shedding patterns respectively corresponding to the plurality of heddle frames.

[0014] In the shedding control apparatus in a weaving machine according to the present invention, the weave information may include weft densities and shedding patterns respectively corresponding to said plurality of heddle frames.

[0015] In the shedding control apparatus in a weaving machine according to the present invention, the shedding curve setting means may select or set at least two kinds of shedding curves distinguished one from the other by the magnitude of stationary angles.

BRIEF DESCRIPTION OF THE DRAWINGS

[0016]

Fig. 1 is a schematic view, i.e. a combination of a schematic diagram of a shedding device according to a first embodiment of the present invention as viewed from a side, and a control block diagram; Fig. 2 is a schematic view, i.e. a combination of a schematic diagram of the shedding device as viewed from the front and the control block diagram; Figs. 3a to 3f are graphs each showing a shedding

curve;

Figs. 4a to 4d are graphs respectively showing shedding patterns for heddle frames 151, 152, 153 and 154, and Figs. 4e to 4h are sectional views of cloth, respectively showing interweaving states of wefts to warps T1, T2, T3 and T4;

Figs. 5a to 5f are graphs showing shedding curves in a second embodiment;

Fig. 6 is a schematic view, i.e. a combination of a schematic diagram of a shedding device and a control block diagram according to a third embodiment; Figs. 7a and 7b are graphs showing shedding curves;

Fig. 8 is a table indicating shedding patterns and stationary angles for respective heddle frames; and Fig. 9 is a table indicating shedding patterns and stationary angles for respective heddle frames.

DESCRIPTION OF THE PREFERRED EMBODIMENT

Embodiment 1

[0017] A first embodiment of the present invention will be described with reference to Figures 1 to 4.

[0018] Reference symbol Mo designates a weaving machine drive motor, which can rotate reversibly and is operatively controlled by a weaving machine control computer Co. A reversible feed motor 11, which is provided independently of the weaving machine drive motor Mo, drives a warp beam 12. Warps T1, T2, T3 and T4 are fed out from the warp beam 12 to be passed through a back roller 13, a tension roller 14, heddle frames 151, 152, 153 and 154 and a reed 16. A woven cloth W is passed through an extension bar 17, a surface roller 18, a press roller 19 and a crease removing guide member 20 to be wound onto a cloth roller 21. The surface roller 18 obtains a driving force from the weaving machine drive motor Mo to receive the woven cloth W in cooperation with the press roller 19, and the cloth roller 21 is linked with the surface roller 18.

[0019] The tension roller 14 is attached to one end portion of a tension lever 22, so that a predetermined tension to the warp T1, T2, T3 and T4 by the action of a tensile spring 23 attached to the other end portion of the tension lever 22. The tension lever 22 is rotatably supported at one end of a detection lever 24, and the other end of the detection lever 24 is connected to a tension detecting unit 25. The warp tension is transmitted through the tension roller 14, the tension lever 22 and the detection lever 24 to the tension detecting unit 25, and the tension detecting unit 25 outputs, to the weaving machine control computer Co, an electric signal in accordance with the warp tension. The weaving machine control computer Co controls a rotational speed of the feed motor 11 based on a comparison of a preset tension with a detected tension indicated by this input signal as well as on a warp beam diameter indicated by a detection signal received from a rotary en-

coder 26 for detecting a rotational angle of the weaving machine. With this rotational speed control, the warp tension during a normal operation is controlled to prevent a weaving bar from generating during weaving.

[0020] As shown in Fig. 1, shedding drive motor M1, M2, M3 and M4 are disposed below the heddle frames 151, 152, 153 and 154, respectively. Crank discs 29 are securely attached to the output shafts 28 of the shedding drive motors M1, M2, M3 and M4, and the crank discs 29 are connected through connecting rods 30 to lower frames of the heddle frames 151, 152, 153 and 154, respectively. The crank discs 29 and the connecting rods 30 constitute crank mechanisms, by which one-directional rotation of the shedding drive motors M1, M2, M3 and M4 are converted into vertical motion of the heddle frames 151, 152, 153 and 154, respectively. The shedding drive motors M1, M2, M3 and M4 follow command control given by a shedding control device CI. The shedding control device CI controls operation of the shedding drive motors M1, M2, M3 and M4 in synchronism with insertion of weft Y. As shown in Fig. 2, the weft Y is inserted into sheddings of the warps T1, T2, T3 and T4 by a weft insertion main nozzle 31.

[0021] The shedding control device CI includes a shedding curve memory circuit 33 that stores therein six shedding curves E1, E2, E3, E4, E5 and E6 shown in Figs. 3a to 3f, a control circuit 34 that selects a shedding curve from the shedding curve memory circuit 33 and outputs a control command, and a drive circuit 35 that controls the shedding drive motors M1, M2, M3 and M4 based on the control command received from the control circuit 34. The drive circuit 35 feed-back controls the shedding drive motors M1, M2, M3 and M4 based on rotational angle information obtained from rotary encoders 32 built into the shedding drive motors M1, M2, M3 and M4. In Fig. 3, an axis θ of abscissas represents a weaving machine rotational angle, and an axis H of ordinates represents a height of the heddle frame. The H1 represents the uppermost position, whereas the H2 represents the lowermost position. Each of the shedding curves E1, E2, E3, E4, E5 and E6 represents a part of shedding curves indicative of motion of the heddle frame 151, 152, 153 and 154, i.e. only for a time period where it is moved from one of the uppermost position and the lowermost position to the other.

[0022] The control circuit 34 is electrically connected to a weave information memory device 27. The weave information memory device 27 stores weave information therein. The weave information stored in the weave information memory device 27 includes shedding patterns of the respective heddle frames 151, 152, 153 and 154.

[0023] Fig. 4a represents a shedding pattern 1/1 of the heddle frame 151, Fig. 4b represents a shedding pattern 1/1 of the heddle frame 152. Fig. 4c represents a shedding pattern 2/2 of the heddle frame 153, and Fig. 4d represents a shedding pattern 6/1 of the heddle frame 154. Fig. 4e is a sectional view of a cloth, showing an interweaving state of the warp T1 and the wefts Y

corresponding to the shedding pattern 1/1 shown in Fig. 4a, and Fig. 4f is a sectional view of a cloth, showing an interweaving state of the warp T2 and the wefts Y corresponding to the shedding pattern 1/1 shown in Fig. 4b.

Fig. 4g is a sectional view of a cloth, showing an interweaving state of the warp T3 and the wefts Y corresponding to the shedding pattern 2/2 shown in Fig. 4c, and Fig. 4h is a sectional view of a cloth, showing an interweaving state of the warp T4 and the wefts Y corresponding to the shedding pattern 6/1 shown in Fig. 4d.

[0024] The weaving machine rotational angle detecting rotary encoder 26 is electrically connected to the control circuit 34. The control circuit 34 retrieves the shedding pattern information for each of the heddle frames 151, 152, 153 and 154 from the weave information memory device 27 for every single rotation of the weaving machine on the basis of weaving machine rotational angle information obtained from the rotary encoder 26. Concurrently, the control circuit 34 retrieves the transitional pattern for each of the heddle frames 151, 152, 153 and 154 in the next one rotation of the weaving machine.

[0025] Since the shedding pattern retrieved by the control circuit 34 for the heddle frame 151 is the shedding pattern 1/1, the control circuit 34 selects either one of the shedding curves E1 and E4. In the case where the next transitional pattern retrieved by the control circuit 34 from the weave information memory device 27 for the heddle frame 151 is the transitional pattern from the uppermost position to the lowermost position, the control circuit 34 selects the shedding curve E1 from the shedding curve memory circuit 33. In the case where the next transitional pattern retrieved by the control circuit 34 from the weave information memory device 27 for the heddle frame 151 is the transitional pattern from the lowermost position to the uppermost position, the control circuit 34 selects the shedding curve E4 from the shedding curve memory circuit 33.

[0026] Since the shedding pattern retrieved by the control circuit 34 for the heddle frame 152 is the shedding pattern 1/1, the control circuit 34 selects either one of the shedding curves E1 and E4. In the case where the next transitional pattern retrieved by the control circuit 34 from the weave information memory device 27 for the heddle frame 152 is the transitional pattern from the uppermost position to the lowermost position, the control circuit 34 selects the shedding curve E1 from the shedding curve memory circuit 33. In the case where the next transitional pattern retrieved by the control circuit 34 from the weave information memory device 27 for the heddle frame 152 is the transitional pattern from the lowermost position to the uppermost position, the control circuit 34 selects the shedding curve E4 from the shedding curve memory circuit 33.

[0027] Since the shedding pattern retrieved by the control circuit 34 for the heddle frame 153 is the shedding pattern 2/2, the control circuit 34 selects either one of the shedding curves E2 and E5. In the case where

the next transitional pattern retrieved by the control circuit 34 from the weave information memory device 27 for the heddle frame 153 is the transitional pattern from the uppermost position to the lowermost position, the control circuit 34 selects the shedding curve E2 from the shedding curve memory circuit 33. In the case where the next transitional pattern retrieved by the control circuit 34 from the weave information memory device 27 for the heddle frame 153 is the transitional pattern from the lowermost position to the uppermost position, the control circuit 34 selects the shedding curve E5 from the shedding curve memory circuit 33.

[0028] Since the shedding pattern retrieved by the control circuit 34 for the heddle frame 154 is the shedding pattern 6/1, the control circuit 34 selects either one of the shedding curves E3 and E6. In the case where the next transitional pattern retrieved by the control circuit 34 from the weave information memory device 27 for the heddle frame 154 is the transitional pattern from the uppermost position to the lowermost position, the control circuit 34 selects the shedding curve E3 from the shedding curve memory circuit 33. In the case where the next transitional pattern retrieved by the control circuit 34 from the weave information memory device 27 for the heddle frame 154 is the transitional pattern from the lowermost position to the uppermost position, the control circuit 34 selects the shedding curve E6 from the shedding curve memory circuit 33.

[0029] The control circuit 34 outputs control command to the drive circuit 35 so as to form the shedding curves selected from the shedding curve memory circuit 33. The drive circuit 35 operates the drive motors M1, M2, M3 and M4 so that the heddle frames 151, 152, 153 and 154 respectively provide the shedding curves thus selected correspondingly.

[0030] The disposition period of each heddle frame 151, 152 close to the uppermost position is defined by a period $\alpha_1 = \alpha_{11} + \alpha_{12}$ where each heddle frame 151, 152 is disposed within a range of a predetermined ratio $\Delta \cdot K$ (Δ is, for instance, 3%) relative to the vertical stroke K of each heddle frame 151, 152 from the uppermost position, as shown in Figs. 3a and 3d. Similarly, the disposition period of each heddle frame 151, 152 close to the lowermost position is defined by a period $\beta_1 = \beta_{11} + \beta_{12}$ where each heddle frame 151, 152 is disposed within a range of a predetermined ratio $\Delta \cdot K$ relative to the vertical stroke K of each heddle frame 151, 152 from the lowermost position, as shown in Figs. 3a and 3d. The disposition periods of the other heddle frames 153 and 154 close to the uppermost position are similarly defined by periods $\alpha_2 = \alpha_{21} + \alpha_{22}$ and $\alpha_3 = \alpha_{31} + \alpha_{32}$ where they are disposed within a range of a predetermined ratio $\Delta \cdot K$ relative to the vertical stroke K, as shown in Figs. 3b and 3e and Figs. 3c and 3f, respectively. The disposition periods of the heddle frames 153, and 154 close to the lowermost position are similarly defined by periods $\beta_2 = \beta_{21} + \beta_{22}$ and $\beta_3 = \beta_{31} + \beta_{32}$ where they are disposed within a range of a predetermined ratio $\Delta \cdot K$

relative to the vertical stroke K from the lowermost position as shown in Figs. 3b and 3e and Figs. 3c and 3f, respectively.

[0031] This definition reflects stationary status of each heddle frames 151, 152, 153 and 154 at the uppermost and lowermost positions during weaving. Hereafter, the disposition period $\alpha_1, \alpha_2, \alpha_3$ are referred to as stationary angles at the uppermost position side, and the disposition period $\beta_1, \beta_2, \beta_3$ are referred to as stationary angles at the lowermost position side. In this embodiment, formulae $\alpha_1 \approx \alpha_2 \approx \alpha_3 \ll \beta_1$ and $\beta_1 < \beta_2 < \beta_3$ stand in magnitude relationship.

[0032] The first embodiment provides the following effects:

(1-1) The control circuit 34, i.e. control means, selects the shedding curves respectively for the heddle frames 151, 152, 153 and 154 from the shedding curve memory circuit 33 on the basis of the weave information stored in the weave information memory device 27. The control circuit 34, which forms shedding curve setting means together with the shedding curve memory circuit 33, controls the operation of the shedding drive motors M1, M2, M3 and M4 driving the heddle frames 151, 152, 153 and 154 correspondingly to the selected shedding curves to provide the selected shedding curves.

The consumption amounts of the warps T1, T2, T3 and T4 differ from one another depending on the interweaving states to the wefts Y. As can be seen from Figs. 4e to 4h, the consumption amount of warp T3 is smaller than the consumption amount of each of the warps T1 and T2, and the consumption amount of the warp T4 is even smaller than the consumption amount of the warp T3. The respective shedding patterns of a plurality of the heddle frames 151, 152, 153 and 154 reflect the consumption amounts of the warps T1, T2, T3 and T4 corresponding to the heddle frames 151, 152, 153 and 154. The stationary angle α_1 in the pair of the shedding curves E1 and E4, the stationary angle α_2 in the pair of the shedding curves E2 and E5, and the stationary angle α_3 in the pair of the shedding curves E3 and E6 are set to small values, the differential between which is substantially zero. In contrast, the stationary angle β_1 in the pair of the shedding curves E1 and E4, the stationary angle β_2 in the pair of the shedding curves E2 and E5, and the stationary angle β_3 in the pair of the shedding curves E3 and E6 are set values different from one another and the differential therebetween is significant. Each of the stationary angles β_2 and β_3 is set to a relatively large value. These magnitude differences among the stationary angles β_1, β_2 and β_3 at the lowermost position side provide differences in rapidness of the tension increases on the warps T1, T2, T3 and T4 during the transition from the closed position to the lowermost position, thereby

preventing the loosening of the warp (T4 or T3) less consumed. Therefore, the handling of the warps is improved, and the insertion of the wefts is stabilized. That is, the warp handling can be enhanced by selecting the shedding curves respectively for the heddle frames taking into account the stationary angles correspondingly to ratio of one-way movement times, such that the shedding curve having the large stationary angle is prepared for the warp whose consumption amount is small, whereas the shedding curve having the small stationary angle or a zero stationary angle is prepared for the warp whose consumption amount is large. Here, the one-way movement time means the number of movement from the uppermost position to the lowermost position or from the lowermost position to the uppermost position in the shedding pattern.

(1-2) It is experimentally known that a larger stationary angle at the lowermost position side makes the textile quality good. The manner of setting numeric values for stationary angles β_1 , β_2 and β_3 at the lowermost side contributes to the improvement of the textile quality.

(1-3) Since the shedding amount of the warp does not change, there is no case that the tension variation of the warp is increased. Therefore, the textile quality is not degraded by the large tension variation, and it is optimal in view of the improvement of the warp handling to select the shedding curves respectively for the heddle frames taking into account the differences of the stationary angles.

Embodiment 2

[0033] As shown in Figs. 5a to 5f, a second embodiment may be adopted, using the shedding curves E1, E4, E7, E8, E9 and E10 that provide differences among the stationary angles at the uppermost position side, namely $\alpha_1 = \alpha_{11} + \alpha_{12}$, $\alpha_2 = \alpha_{21} + \alpha_{22}$ and $\alpha_3 = \alpha_{31} + \alpha_{32}$. This makes it possible to further enhance the warp handling.

Embodiment 3

[0034] Next, a third embodiment will be described with reference to Figs. 6 to 8. The same structures as those described in connection with the first embodiment are designated by the same reference symbols.

[0035] In the third embodiment, eight heddle frames 151, 152, 153, 154, 155, 156, 157 and 158 and eight shedding drive motors M1, M2, M3, M4, M5, M6, M7 and M8 are utilized. A reference shedding curve memory circuit 36 of a shedding control device C2 stores therein the reference shedding curve E1 shown in Fig. 3a and the reference shedding curve E4 shown in Fig. 3b. The symbol $\alpha_1 = \alpha_{11} + \alpha_{12}$ in each of the curves E4 and E1 represents the stationary angle at the uppermost position side, whereas the symbol $\beta_1 = \beta_{11} + \beta_{12}$ in each of

the curves E4 and E1 represents the stationary angle at the lowermost position side. The control circuit 37 of the shedding control device C2 retrieves, for each of the heddle frames 151 to 158, the shedding pattern information included in the weave information stored in the weave information memory device 27 for every single rotation of the weaving machine on the basis of weaving machine rotational angle information obtained from the rotary encoder 26. The control circuit 37 creates shedding curves from the reference shedding curves E4 and E1 on the basis of the shedding pattern information thus retrieved from the weave information memory device 27, and assigns thus created shedding curves respectively to the heddle frames 151 to 158. The creation of the shedding curves are carried out such that the disposition periods α_{11} , α_{12} , β_{11} and β_{12} of the reference shedding curves E4 and E1 are changed.

[0036] Fig. 8 shows shedding patterns for the heddle frames 151 to 158. In the illustrated example, the shedding patterns are repeated at sixteen rotation of the weaving machine as a unit cycle. In Fig. 8, the 1/1 pattern corresponds to the shedding patterns shown in Figs. 4a and 4b, and the 2/2 pattern corresponds to the shedding pattern shown in Fig. 4c. The 6/1 pattern corresponds to the shedding pattern shown in Fig. 4d, and the 1/6 pattern corresponds to a shedding pattern obtained by reversing the shedding pattern shown in Fig. 4d upside down. In the illustrated example, each of the heddle frames 151 and 152 makes the motion of the 2/2 pattern for eight times worth of the weft insertion, the motion of the 1/1 pattern for four times worth of the weft insertion, and then the motion of the 2/2 pattern for four times worth of the weft insertion. Each of the heddle frames 153 and 154 makes the motion of the 6/1 pattern for four times worth of the weft insertion, the motion of the 1/6 pattern for four times worth of the weft insertion, the motion of the 1/1 pattern for four times worth of the weft insertion, and then the motion of the 2/2 pattern for four times worth of the weft insertion. Each of the heddle frames 155 and 156 makes the motion of the 1/6 pattern for four times worth of the weft insertion, the motion of the 6/1 pattern for four times worth of the weft insertion, the motion of the 1/1 pattern for four times worth of the weft insertion, and then the motion of the 2/2 pattern for four times worth of the weft insertion. All the motions made by the heddle frames 157, 158 are of the 1/1 pattern.

[0037] In the case where the shedding pattern retrieved by the control circuit 37 is the 1/1 pattern, the control circuit 37 carries out such a setting that the reference shedding curves E4 and E1 are used as they are. In the case where the shedding pattern retrieved by the control circuit 37 is the 2/2 pattern, the control circuit 37 modifies the disposition periods α_{11} and β_{11} of the reference shedding curve E4 to be, for instance, α_{21} and β_{21} shown in Fig. 3e, as well as the disposition periods α_{12} and β_{12} of the reference shedding curve E1 to be, for instance, α_{22} and β_{22} shown in Fig. 3b, to

thereby create and set the shedding curves E5 and E2 for use. In the case where the shedding pattern retrieved by the control circuit 37 is the 6/1 pattern, the control circuit 37 modifies the disposition periods α_{11} and β_{11} of the reference shedding curve E4 to be, for instance, α_{31} and β_{31} shown in Fig. 3f, as well as the disposition periods α_{12} and β_{12} of the reference shedding curve E1 to be, for instance, α_{32} and β_{32} shown in Fig. 3c, to thereby create and set the shedding curves E6 and E3 for use. In the case where the shedding pattern retrieved by the control circuit 37 is the 1/6 pattern, the control circuit 37 modifies the disposition periods α_{11} and β_{11} of the reference shedding curve E4 to be, for instance, α_{41} and β_{41} shown in Fig. 7b, as well as the disposition periods α_{12} and β_{12} of the reference shedding curve E1 to be, for instance, α_{42} and β_{42} shown in Fig. 7a, to thereby create and set the shedding curves E12 and E11 for use.

[0038] In Fig. 8, the symbol $\alpha(1/1)$ represents the stationary angle at the uppermost position side corresponding to the 1/1 pattern, and the symbol $\beta(1/1)$ represents the stationary angle at the lowermost position side corresponding to the 1/1 pattern. The symbol $\alpha(2/2)$ represents the stationary angle at the uppermost position side corresponding to the 2/2 pattern, and the symbol $\beta(2/2)$ represents the stationary angle at the lowermost position side corresponding to the 2/2 pattern. The symbol $\alpha(6/1)$ represents the stationary angle at the uppermost position side corresponding to the 6/1 pattern, and the symbol $\beta(6/1)$ represents the stationary angle at the lowermost position side corresponding to the 6/1 pattern. The symbol $\alpha(1/6)$ represents the stationary angle at the uppermost position side corresponding to the 1/6 pattern, and the symbol $\beta(1/6)$ represents the stationary angle at the lowermost position side corresponding to the 1/6 pattern.

[0039] The control circuit 37 recognizes next transitional pattern for each of the heddle frames on the basis of the shedding pattern information retrieved from the weave information memory device 27. Assuming for convenience of explanation that the shedding patterns for the heddle frames 151 to 158 are those shown in Fig. 8, in the case where the next transitional pattern for the heddle frame 151 to which the 2/2 pattern is assigned is the transitional pattern from the uppermost position to the lowermost position, the control circuit 37 creates and uses the shedding curve E2. In the case where the next transitional pattern for the heddle frame 151 to which the 2/2 pattern is assigned is the transitional pattern from the lowermost position to the uppermost position, the control circuit 37 creates and uses the reference shedding curve E5. In the case where the next transitional pattern for the heddle frame 151 to which the 1/1 pattern is assigned is the transitional pattern from the uppermost position to the lowermost position, the control circuit 37 uses the reference shedding curve E1 as it is. In the case where the next transitional pattern for the heddle frame 151 to which the 1/1 pattern is as-

signed is the transitional pattern from the lowermost position to the uppermost position, the control circuit 37 uses the shedding curve E4 as it is. The similar setting of the shedding curve is carried out for the heddle frame 152.

[0040] In the case where the next transitional pattern for the heddle frame 153 to which the 6/1 pattern is assigned is the transitional pattern from the uppermost position to the lowermost position, the control circuit 37 creates and uses the shedding curve E3. In the case where the next transitional pattern for the heddle frame 153 to which the 6/1 pattern is assigned is the transitional pattern from the lowermost position to the uppermost position, the control circuit 37 creates and uses the shedding curve E6. In the case where the next transitional pattern for the heddle frame 153 to which the 1/6 pattern is assigned is the transitional pattern from the uppermost position to the lowermost position, the control circuit 37 creates and uses the shedding curve E11.

In the case where the next transitional pattern for the heddle frame 153 to which the 1/6 pattern is assigned is the transitional pattern from the lowermost position to the uppermost position, the control circuit 37 creates and uses the shedding curve E12. In the case where the next transitional pattern for the heddle frame 153 to which the 1/1 pattern is assigned is the transitional pattern from the uppermost position to the lowermost position, the control circuit 37 uses the shedding curve E1 as it is. In the case where the next transitional pattern for the heddle frame 153 to which the 1/1 pattern is assigned is the transitional pattern from the lowermost position to the uppermost position, the control circuit 37 uses the shedding curve E4 as it is. In the case where the next transitional pattern for the heddle frame 153 to which the 2/2 pattern is assigned is the transitional pattern from the uppermost position to the lowermost position, the control circuit 37 creates and uses the shedding curve E2. In the case where the next transitional pattern for the heddle frame 153 to which the 2/2 pattern is assigned is the transitional pattern from the lowermost position to the uppermost position, the control circuit 37 creates and uses the shedding curve E5. The similar setting of the shedding curve is carried out for the heddle frame 154.

[0041] In the case where the next transitional pattern for the heddle frame 155 to which the 1/6 pattern is assigned is the transitional pattern from the uppermost position to the lowermost position, the control circuit 37 creates and uses the shedding curve E11. In the case where the next transitional pattern for the heddle frame 155 to which the 1/6 pattern is assigned is the transitional pattern from the lowermost position to the uppermost position, the control circuit 37 creates and uses the shedding curve E12. In the case where the next transitional pattern for the heddle frame 155 to which the 6/1 pattern is assigned is the transitional pattern from the uppermost position to the lowermost position, the control circuit 37 creates and uses the shedding curve E3.

In the case where the next transitional pattern for the heddle frame 155 to which the 6/1 pattern is assigned is the transitional pattern from the lowermost position to the uppermost position, the control circuit 37 creates and uses the shedding curve E6. In the case where the next transitional pattern for the heddle frame 155 to which the 1/1 pattern is assigned is the transitional pattern from the uppermost position to the lowermost position, the control circuit 37 uses the reference shedding curve E1 as it is. In the case where the next transitional pattern for the heddle frame 155 to which the 1/1 pattern is assigned is the transitional pattern from the lowermost position to the uppermost position, the control circuit 37 uses the reference shedding curve E4 as it is. In the case where the next transitional pattern for the heddle frame 155 to which the 2/2 pattern is assigned is the transitional pattern from the uppermost position to the lowermost position, the control circuit 37 creates and uses the shedding curve E2. In the case where the next transitional pattern for the heddle frame 155 to which the 2/2 pattern is assigned is the transitional pattern from the lowermost position to the uppermost position, the control circuit 37 creates and uses the shedding curve E5. The similar setting of the shedding curve is carried out for the heddle frame 156.

[0042] In the case where the next transitional pattern for the heddle frame 157 to which the 1/1 pattern is assigned is the transitional pattern from the uppermost position to the lowermost position, the control circuit 37 uses the reference shedding curve E1 as it is. In the case where the next transitional pattern for the heddle frame 157 to which the 1/1 pattern is assigned is the transitional pattern from the lowermost position to the uppermost position, the control circuit 37 uses the reference shedding curve E4 as it is. The similar setting of the shedding curve is carried out for the heddle frame 158.

[0043] The control circuit 37 outputs control command to the drive circuit 35 so as to form the shedding curves thus set. The drive circuit 35 operates the shedding drive motor M1 to M8 so that the heddle frames 151 to 158 establish the respective shedding curves set correspondingly thereto.

[0044] The third embodiment provides the following effects:

(3-1) The control circuit 37, i.e. control means, sets the shedding curves respectively for the heddle frames 151 to 158 using the reference shedding curves E4 and E1 stored in the reference shedding curve memory circuit 36 on the basis of the shedding patterns for the heddle frames 151 to 158. The control circuit 37, which forms shedding curve setting means together with the reference shedding curve memory circuit 36, controls the operation of the shedding drive motors M1 to M8 driving the heddle frames 151 to 158 correspondingly to the thus set shedding curves to provide the thus set shedding curves.

[0045] The respective shedding patterns of a plurality of the heddle frames 151 to 158 reflect the consumption amounts of the warps corresponding to the heddle frames 151 to 158. The differences among the stationary angles based on the shedding patterns for the heddle frames 151 to 158 provide the differences in rapidness of the tension increases on the warps corresponding to the heddle frames 151 to 158 during the transition from the closed position to the uppermost or lowermost position, thereby preventing the loosening of the warp less consumed. Therefore, the handling of the warps is improved, and the insertion of the wefts is stabilized. That is, the warp handling can be enhanced by setting the shedding curves respectively for the heddle frames taking into account the stationary angles correspondingly to the shedding patterns, such that the shedding curve having the large stationary angle is prepared for the warp whose consumption amount is small, whereas the shedding curve having the small stationary angle is prepared for the warp whose consumption amount is large.

Embodiment 4

[0046] Next, a fourth embodiment shown in Fig. 9 will be described. The structures of the apparatus in the fourth embodiment are the same as those in the third embodiment, but the control circuit 37 of the shedding control apparatus C2 in the fourth embodiment differs in function from that in the third embodiment. The control circuit 37 in the fourth embodiment retrieves, for each of the heddle frames 151 to 158, the shedding pattern information included in the weave information stored in the weave information memory device 27 for every single rotation of the weaving machine on the basis of weaving machine rotational angle information obtained from the rotary encoder 26, and also retrieves weft density information included in the weave information. The control circuit 37 in the fourth embodiment creates shedding curves from the reference shedding curves E4 and E1 on the basis of the thus retrieved shedding pattern information and weft density information, and assigns thus created shedding curves respectively to the heddle frames 151 to 158. The creation of the shedding curves are carried out such that the disposition periods all, α_{12} , β_{11} and β_{12} of the reference shedding curves E4 and E1 are changed. Other functions of the control circuit 37 in the fourth embodiment are the same as those in the first embodiment. In the example shown in Fig. 9, the weft density is set to ρ_1 for eight times worth of the weft insertion, ρ_2 for four times worth of the weft insertion, and then ρ_3 for four times worth of the weft insertion. The densities ρ_1 , ρ_2 and ρ_3 meet, for instance, a relationship of $\rho_3 > \rho_1 > \rho_2$.

[0047] In Fig. 9, the symbol $\alpha(2/2, \rho_1)$ represents the stationary angle at the uppermost position side corresponding to the 2/2 pattern and the weft density ρ_1 , and the symbol $\beta(2/2, \rho_1)$ represents the stationary angle at the lowermost position side corresponding to the 2/2

pattern and the weft density ρ_1 . The symbol $\alpha(6/1, \rho_1)$ represents the stationary angle at the uppermost position side corresponding to the 6/1 pattern and the weft density ρ_1 , and the symbol $\beta(6/1, \rho_1)$ represents the stationary angle at the lowermost position side corresponding to the 6/1 pattern and the weft density ρ_1 . The symbol $\alpha(1/6, \rho_1)$ represents the stationary angle at the uppermost position side corresponding to the 1/6 pattern and the weft density ρ_1 , and the symbol $\beta(1/6, \rho_1)$ represents the stationary angle at the lowermost position side corresponding to the 1/6 pattern and the weft density ρ_1 . The symbol $\alpha(1/1, \rho_1)$ represents the stationary angle at the uppermost position side corresponding to the 1/1 pattern and the weft density ρ_1 , and the symbol $\beta(1/1, \rho_1)$ represents the stationary angle at the lowermost position side corresponding to the 1/1 pattern and the weft density ρ_1 . The symbol $\alpha(1/1, \rho_2)$ represents the stationary angle at the uppermost position side corresponding to the 1/1 pattern and the weft density ρ_2 , and the symbol $\beta(1/1, \rho_2)$ represents the stationary angle at the lowermost position side corresponding to the 1/1 pattern and the weft density ρ_2 . The symbol $\alpha(2/2, \rho_3)$ represents the stationary angle at the uppermost position side corresponding to the 2/2 pattern and the weft density ρ_3 , and the symbol $\beta(2/2, \rho_3)$ represents the stationary angle at the lowermost position side corresponding to the 2/2 pattern and the weft density ρ_3 . The symbol $\alpha(1/1, \rho_3)$ represents the stationary angle at the uppermost position side corresponding to the 1/1 pattern and the weft density ρ_3 , and the symbol $\beta(1/1, \rho_3)$ represents the stationary angle at the lowermost position side corresponding to the 1/1 pattern and the weft density ρ_3 .

[0048] For example, in Fig. 4, the warp T3 is smaller in consumption amount than each of the warps T1 and T2. As the weft densities are larger, the difference in consumption amount between the warp T3 and each of the warps T1 and T2 becomes larger. That is, the weft density influences the consumption amount of the warp. For this reason, the example shown in Fig. 9 carries out such a setting that the stationary angles meet, for instance, a relationship of $\beta(1/1, \rho_2) > \beta(1/1, \rho_1) > \beta(1/1, \rho_3)$. The setting of the shedding curves respectively for the heddle frames taking into account the shedding patterns and the weft densities effectively improves the warp handling.

[0049] In the present invention, the following embodiments can also be employed.

- (1) A plurality of shedding curves, which provide differences only to stationary angles at the uppermost position side, are prepared.
- (2) A plurality of shedding curves, which provide differences to shedding amounts, are prepared, and larger shedding amount is set for warp having smaller consumption amount.
- (3) A plurality of shedding curves having different timings at which heddle frames reach their respec-

tive uppermost or lowermost positions, and an earlier timing is set for warp having smaller consumption amount.

(4) Each of the functions of the weave information memory device 27, the shedding curve memory circuit 33 and the control circuit 37 is installed in the weaving machine control computer Co shown in Fig. 1.

(5) Shedding curves are selected or set respectively for respective heddle frames independently, in accordance with weave information, in order to improve feel and outward appearance of textile.

(6) Shedding curves are set for respective heddle frames independently, and stored in the shedding curve memory circuit 33. The shedding curves are automatically set and stored while referring to the weave information.

[0050] As has been described in detail, in the present invention, shedding curves are selected or set respectively for a plurality of heddle frames in accordance with weave information, and operation of shedding drive motors driving the heddle frames correspondingly to the respective shedding curves thus selected or set are controlled to provide the thus selected or set shedding curves. Therefore, it is possible to effectively improve the warp handling and the textile quality.

Claims

1. A method of controlling sheddings in a weaving machine having a plurality of shedding drive motors provided independently of a weaving machine drive motor, and a plurality of heddle frames, each of the heddle frames corresponding to and driven by a single one of the shedding driving motors, wherein a shedding curve indicative of motion of one heddle frame for a time period where it is moved from one of the uppermost position and the lowermost position to the other is selected or set for each of said plurality of heddle frames independently on the basis of weave information **characterized in that** said weave information includes weft density and where the respective shedding curves for the heddle frames are selected or set taking into account stationary angles, and **in that** each of said shedding drive motors is drivingly controlled to cause a respective one of said plurality of heddle frames to make a motion along said shedding curve thus set or selected.
2. The shedding control method in a weaving machine as set forth in claim 1, **characterized in that** said weave information includes shedding patterns respectively corresponding to said plurality of heddle frames.

3. The shedding control method in a weaving machine as set forth in any one of claims 1 and 2, **characterized in that** at least two kinds of shedding curves distinguished one for the other by the magnitude of stationary angles are beforehand prepared for said shedding curve to be set or selected.

4. An apparatus for controlling sheddings in a weaving machine having a plurality of shedding drive motors provided independently of a weaving machine drive motor, and a plurality of heddle frames, each of the heddle frames corresponding to and driven by a respective single one of the shedding driving motors, wherein said shedding control apparatus comprises:

shedding curve setting means for storing shedding curves indicative of motion of said heddle frames therein, and selecting or setting, of said shedding curves, a shedding curve indicative of motion of one heddle frame for a time period where it is moved from one of the uppermost position and the lowermost position to the other for each of said plurality of heddle frames independently on the basis of weave information **characterized in that** said weave information includes weft density inputted therein from the external and where the respective shedding curves for the heddle frames are selected or set taking into account stationary angles, and said shedding control apparatus further comprises:

control means for drivingly controlling each of said shedding drive motors to cause the respective one of said plurality of heddle frames to make a motion along said shedding curve thus set or selected by said shedding curve setting means.

5. The shedding control apparatus in a weaving machine as set forth in claim 4, **characterized in that** said weave information includes shedding patterns respectively corresponding to said plurality of heddle frames.

6. The shedding control apparatus in a weaving machine as set forth in any one of claims 3 to 5, **characterized in that** said shedding curve setting means selects or sets at least two kinds of shedding curves distinguished one from the other by the magnitude of stationary angles.

Patentansprüche

1. Verfahren zum Steuern von Fachbildungen in einer Webmaschine mit einer Vielzahl von Fachbildungs-Antriebsmotoren, die unabhängig von einem Web-

maschinen-Antriebsmotor vorgesehen sind, und einer Vielzahl von Einzugsrahmen, wobei jeder der Einzugsrahmen einem einzelnen der Fachbildungs-Antriebsmotoren entspricht und durch ihn angetrieben wird,

wobei eine Fachbildungskurve, die eine Bewegung von einem Einzugsrahmen für eine Zeitperiode anzeigt, in welcher er von einer der obersten Position und der untersten Position zur anderen bewegt wird, für jeden der Vielzahl von Einzugsrahmen unabhängig ausgewählt oder eingestellt wird, und zwar auf der Basis von Webinformation, **dadurch gekennzeichnet, dass** die Webinformation eine Gewebedichte enthält, und wobei die jeweiligen Fachbildungskurven für die Einzugsrahmen unter Berücksichtigung von stationären Winkeln ausgewählt oder eingestellt werden, und dass jeder der Fachbildungs-Antriebsmotoren antriebsmäßig gesteuert wird, um zu veranlassen, dass einer der Vielzahl von Einzugsrahmen eine Bewegung entlang der so eingestellten oder ausgewählten Fachbildungskurve durchführt.

2. Fachbildungs-Steuerverfahren bei einer Webmaschine nach Anspruch 1, **dadurch gekennzeichnet, dass** die Webinformation Fachbildungsmuster enthält, die jeweils der Vielzahl von Einzugsrahmen entsprechen.

3. Fachbildungs-Steuerverfahren bei einer Webmaschine nach einem der Ansprüche 1 und 2, **dadurch gekennzeichnet, dass** wenigstens zwei Arten von Fachbildungskurven, die durch die Größe von stationären Winkeln voneinander unterschiedlich sind, im Voraus für die Fachbildungskurve vorbereitet werden, die einzustellen oder auszuwählen ist.

4. Vorrichtung zum Steuern von Fachbildungen in einer Webmaschine mit einer Vielzahl von Fachbildungs-Antriebsmotoren, die unabhängig von einem Webmaschinen-Antriebsmotor vorgesehen sind, und einer Vielzahl von Einzugsrahmen, wobei jeder der Einzugsrahmen einem jeweiligen einzelnen der Fachbildungs-Antriebsmotoren entspricht und durch diesen angetrieben wird, wobei die Fachbildungs-Steuervorrichtung folgendes aufweist:

eine Fachbildungskurven-Einstelleinrichtung zum Speichern von Fachbildungskurven, die eine Bewegung der Einzugsrahmen anzeigt, darin und zum Auswählen oder Einstellen aus den Fachbildungskurven von einer Fachbildungskurve, die eine Bewegung von einem Einzugsrahmen für eine Zeitperiode anzeigt, bei welcher er von einer der obersten Position und der untersten Position zur anderen bewegt wird, für jeden der Vielzahl von Einzugsrahmen

unabhängig auf der Basis von Webinformation, **dadurch gekennzeichnet, dass** die Webinformation eine Gewebedichte enthält, die dort hinein von außen eingegeben ist, und wobei die jeweiligen Fachbildungskurven für die Einzugsrahmen unter Berücksichtigung von stationären Winkeln ausgewählt oder eingestellt werden; und wobei die Fachbildungs-Steuervorrichtung weiterhin folgendes aufweist:

eine Steuereinrichtung zum antriebsmäßigen Steuern von jedem der Fachbildungs-Antriebsmotoren, um zu veranlassen, dass ein jeweiliger der Vielzahl von Einzugsrahmen eine Bewegung entlang der durch die Fachbildungskurven-Einstelleinrichtung so eingestellten oder ausgewählten Fachbildungskurve durchführt.

5. Fachbildungs-Steuervorrichtung in einer Webmaschine nach Anspruch 4, **dadurch gekennzeichnet, dass** die Webinformation Fachbildungsmuster enthält, die jeweils der Vielzahl von Einzugsrahmen entsprechen.
6. Fachbildungs-Steuervorrichtung in einer Webmaschine nach einem der Ansprüche 3 bis 5, **dadurch gekennzeichnet, dass** die Fachbildungskurven-Einstelleinrichtung wenigstens zwei Arten von Fachbildungskurven auswählt, die durch die Größe von stationären Winkeln voneinander unterschiedlich sind.

Revendications

1. Procédé de commande des formations de foule dans une machine à tisser présentant une pluralité de moteurs d'entraînement de formation de foule prévus indépendamment d'un moteur d'entraînement de machine à tisser, et une pluralité de cadres de lisses, chacun des cadres de lisses correspondant à et entraîné par un seul des moteurs d'entraînement de formation de foule, dans lequel une courbe de formation de foule, indiquant le mouvement d'un cadre de lisses pour une durée alors qu'il est déplacé de l'une des positions la plus haute et la plus basse à l'autre, est sélectionnée ou réglée pour chacun de la pluralité de cadres de lisses indépendamment sur la base d'informations d'armure **caractérisé en ce que** lesdites Informations d'armure comprennent la densité de trame et où les courbes de formation de foule respectives pour les cadres de lisses sont sélectionnées ou réglées en prenant en compte les angles stationnaires, et **en ce que** chacun desdits moteurs d'entraînement de formation de foule est commandé par entraînement pour amener un cadre de lisses respectif de la plu-

ralité de cadres respectifs à exécuter un mouvement le long de ladite courbe de formation de foule ainsi réglée ou sélectionnée.

2. Procédé de commande de formation de foule dans une machine à tisser selon la revendication 1, **caractérisé en ce que** lesdites informations d'armure comprennent des dessins de formation de foule correspondant respectivement à ladite pluralité de cadres de lisses.

3. Procédé de commande de formation de foule dans une machine à tisser selon l'une quelconque des revendications 1 et 2, **caractérisé en ce qu'**au moins deux types de courbes de formation de foule différenciés l'un de l'autre par la grandeur des angles stationnaires sont préparés à l'avance pour que ladite courbe de formation de foule soit réglée ou sélectionnée.

4. Appareil destiné à commander des formations de foule dans une machine à tisser présentant une pluralité de moteurs d'entraînement de formation de foule prévus indépendamment d'un moteur d'entraînement de machine à tisser, et une pluralité de cadres de lisses, chacun des cadres de lisses correspondant à et entraîné par un seul moteur d'entraînement de formation de foule respectif parmi les moteurs d'entraînement de formation de foule, dans lequel ledit appareil de commande de formation de foule comprend :

des moyens de réglage de courbe de formation de foule destinés à stocker les courbes de formation de foule indiquant le mouvement desdites cadres de lisses à l'intérieur, et à sélectionner ou régler lesdites courbes de formation de foule, une courbe de formation de foule indiquant le mouvement d'un cadre de lisses pendant une durée alors qu'il est déplacé d'une des positions la plus haute et la plus basse à l'autre pour chacun de ladite pluralité de cadres de lisses indépendamment sur la base des informations d'armure **caractérisé en ce que** les informations d'armure comprennent une densité de trame saisie dans celle-ci de l'extérieur et alors que les courbes de formation de foule respectives pour les cadres de lisses sont sélectionnées ou réglées en prenant en compte les angles stationnaires ; et ledit appareil de commande de la formation de foule comprend en outre :

des moyens de commande destinés à commander par entraînement chacun desdits moteurs d'entraînement de formation de foule pour qu'ils amènent le cadre de lisses respectif de ladite pluralité de cadres

de lisses à exécuter un mouvement le long de ladite courbe de formation de foule ainsi réglée ou sélectionnée par lesdits moyens de réglage de courbe de formation de foule.

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5. Appareil de commande de formation de foule dans une machine à tisser selon la revendication 4, **caractérisé en ce que** lesdites informations d'armure comprennent des dessins de formation de foule correspondant respectivement à ladite pluralité de cadres de lisses.

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6. Appareil de commande de formation de foule dans une machine à tisser selon l'une quelconque des revendications 3 à 5, **caractérisé en ce que** lesdits moyens de réglage de courbe de formation de foule sélectionnent ou règlent au moins deux types de courbes de formation de foule différenciés l'un de l'autre par la grandeur des angles stationnaires.

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FIG. 1

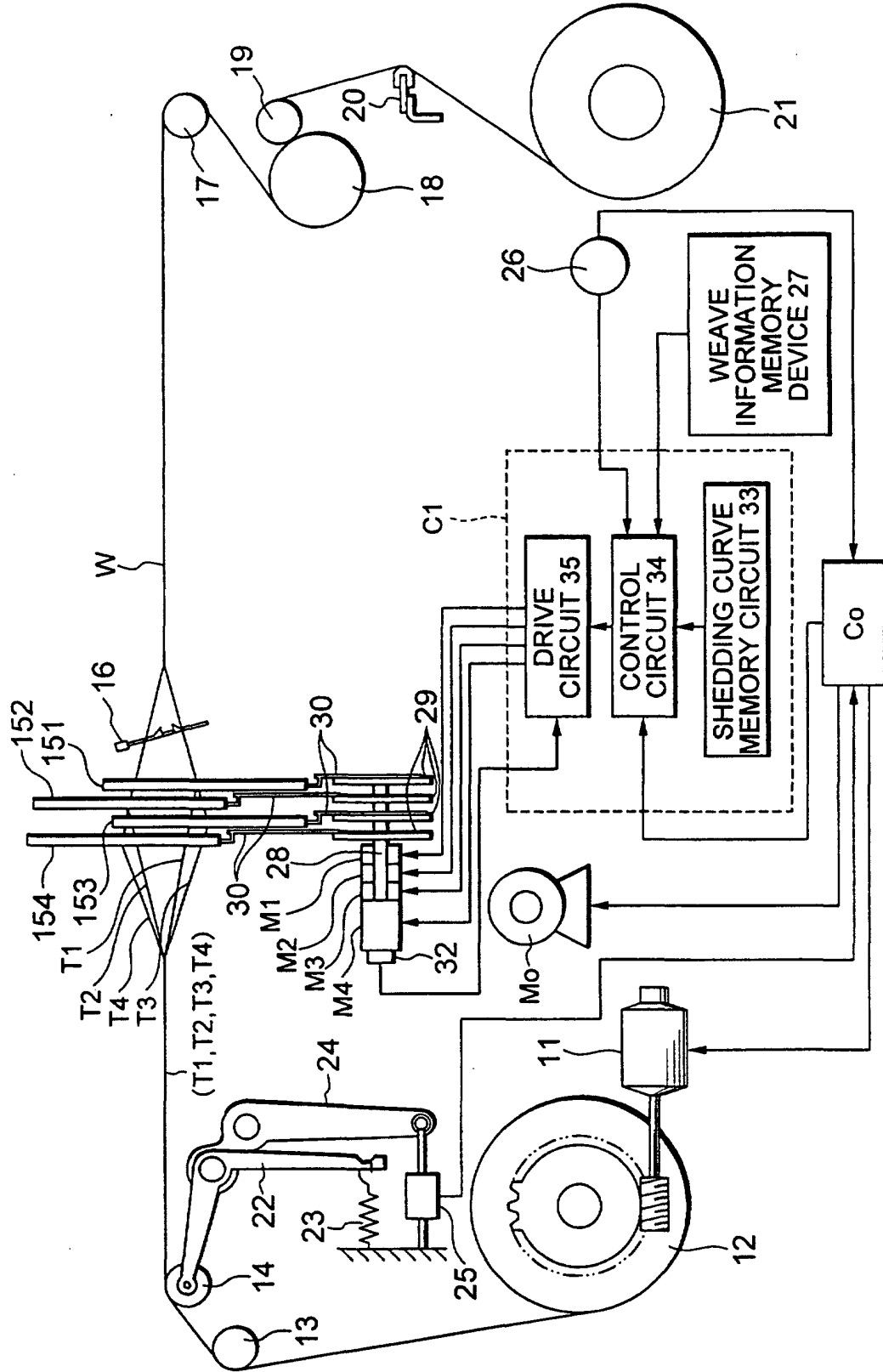


FIG. 2

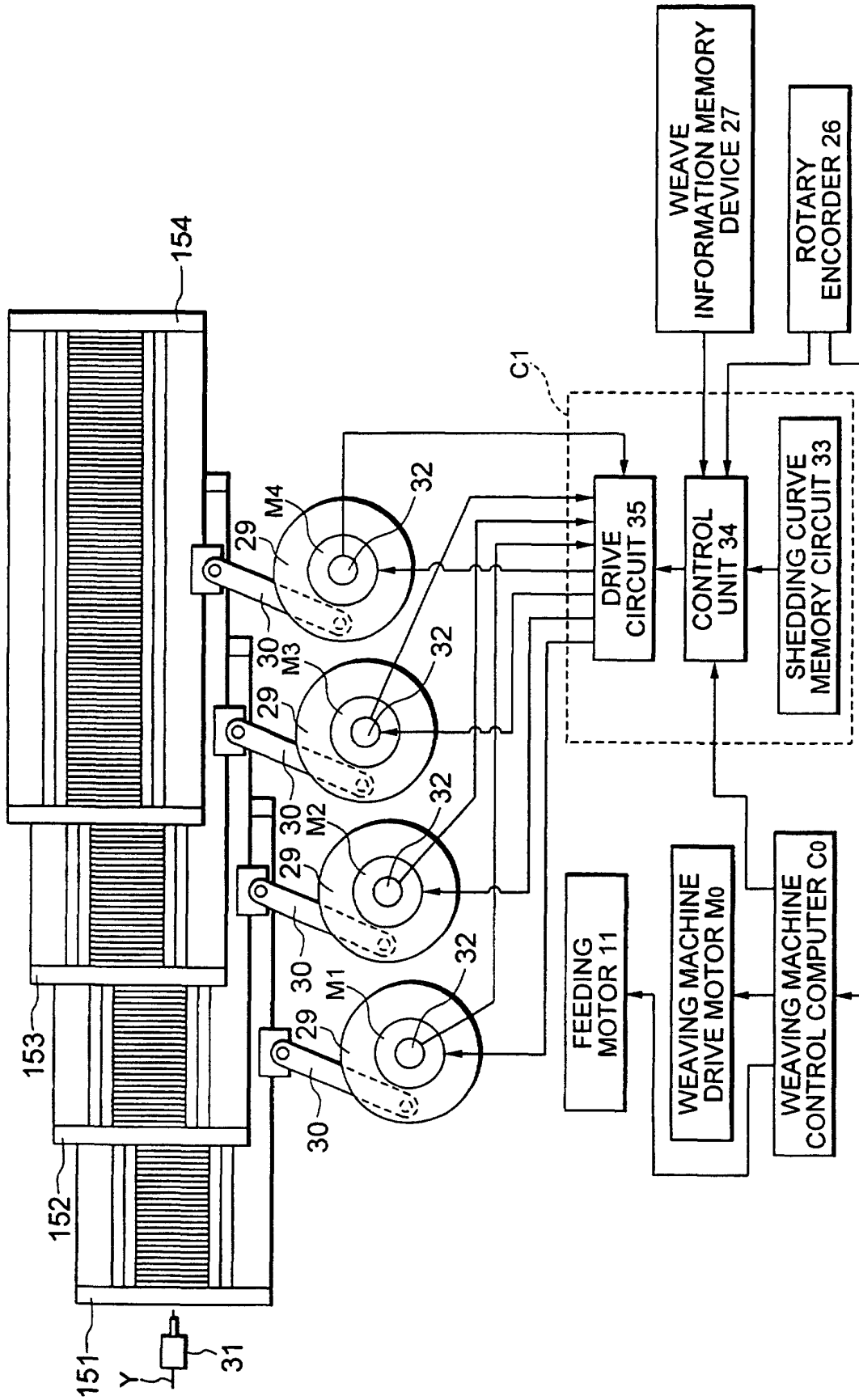


FIG. 3a

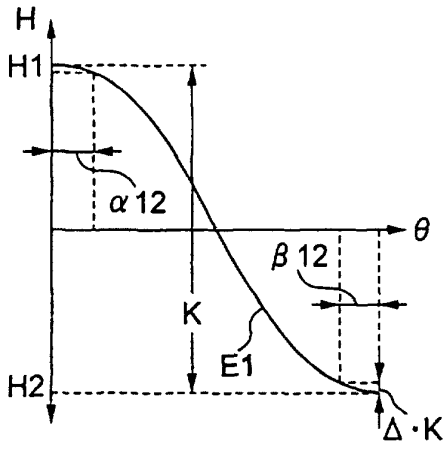


FIG. 3d

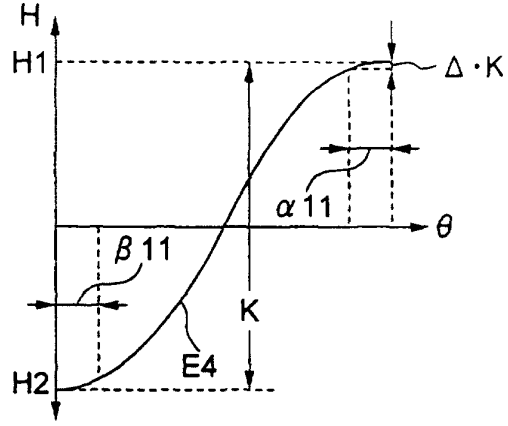


FIG. 3b

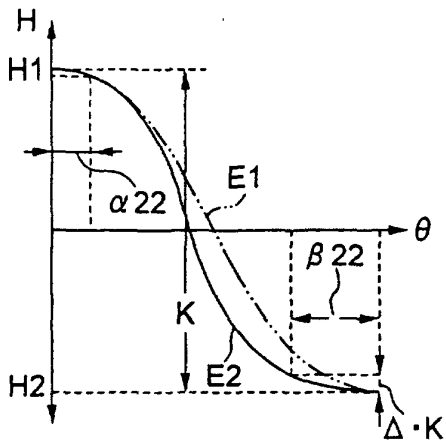


FIG. 3e

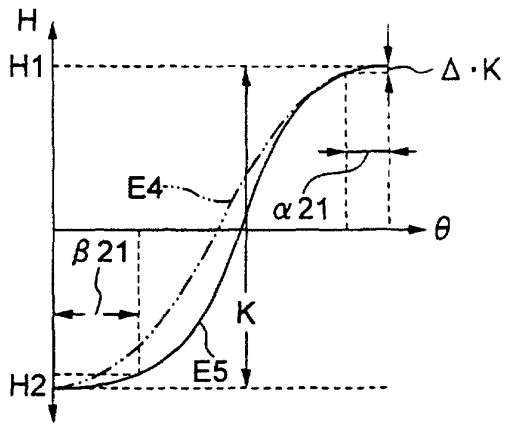


FIG. 3c

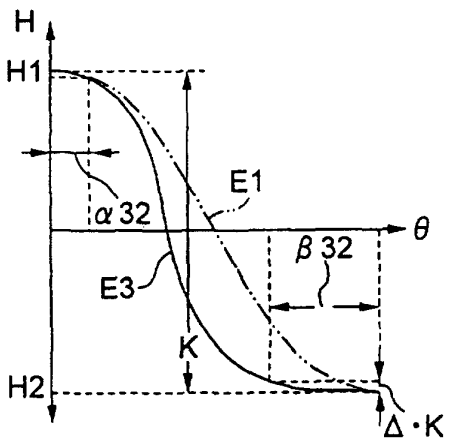


FIG. 3f

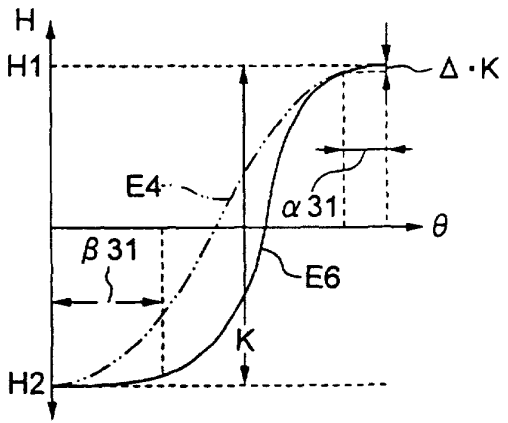


FIG. 4a

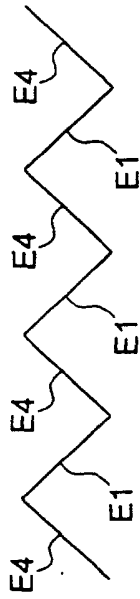


FIG. 4b

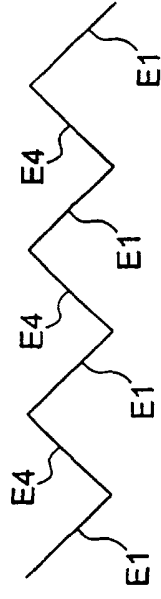


FIG. 4c

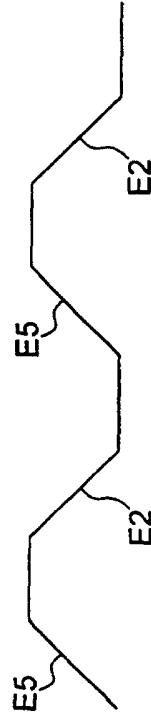


FIG. 4d



FIG. 4e

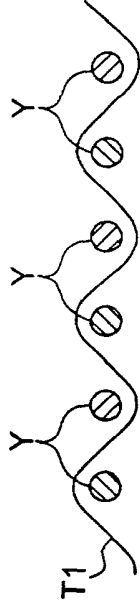


FIG. 4f

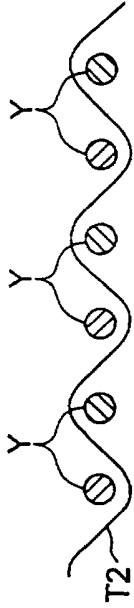


FIG. 4g

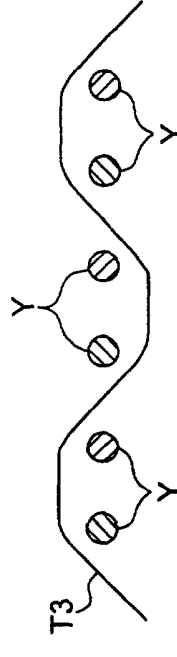


FIG. 4h

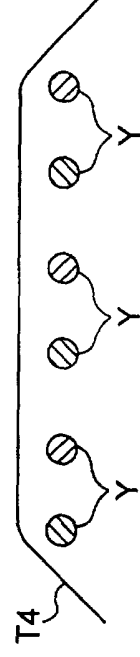


FIG. 5a

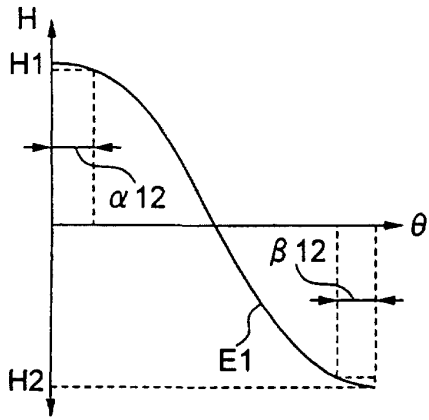


FIG. 5d

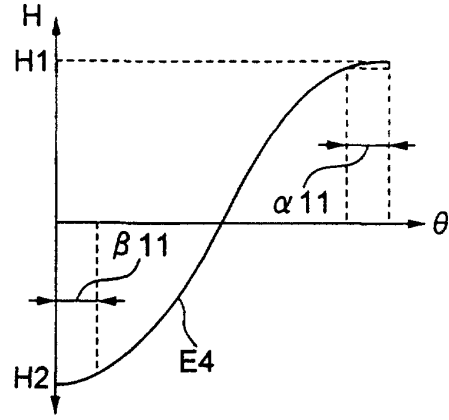


FIG. 5b

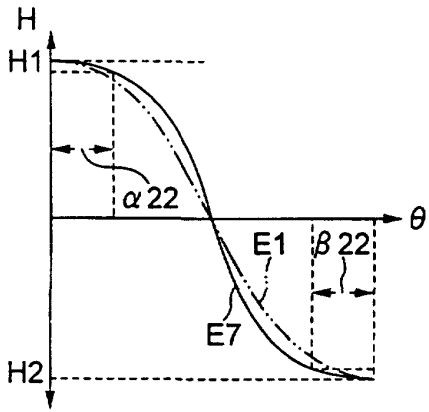


FIG. 5e

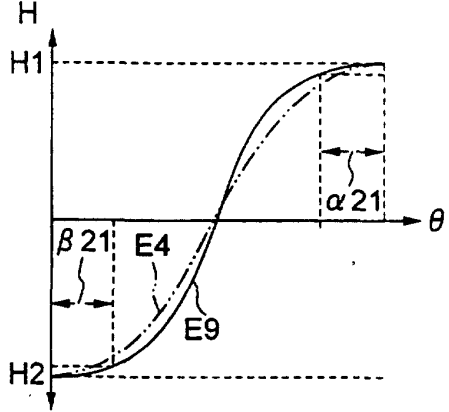


FIG. 5c

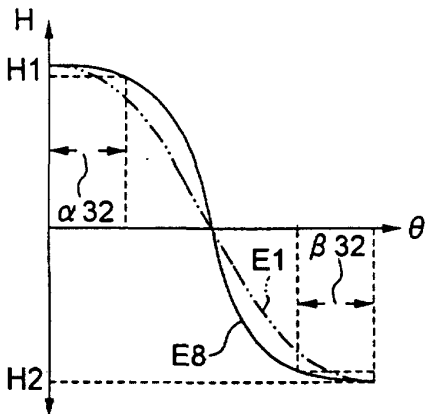


FIG. 5f

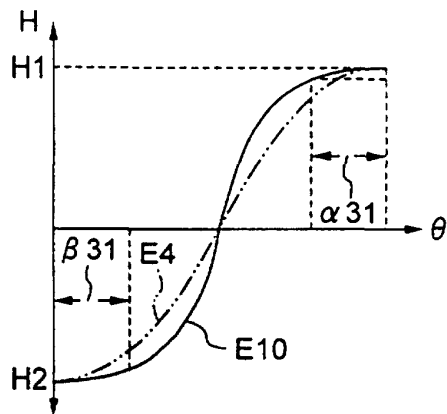


FIG. 6

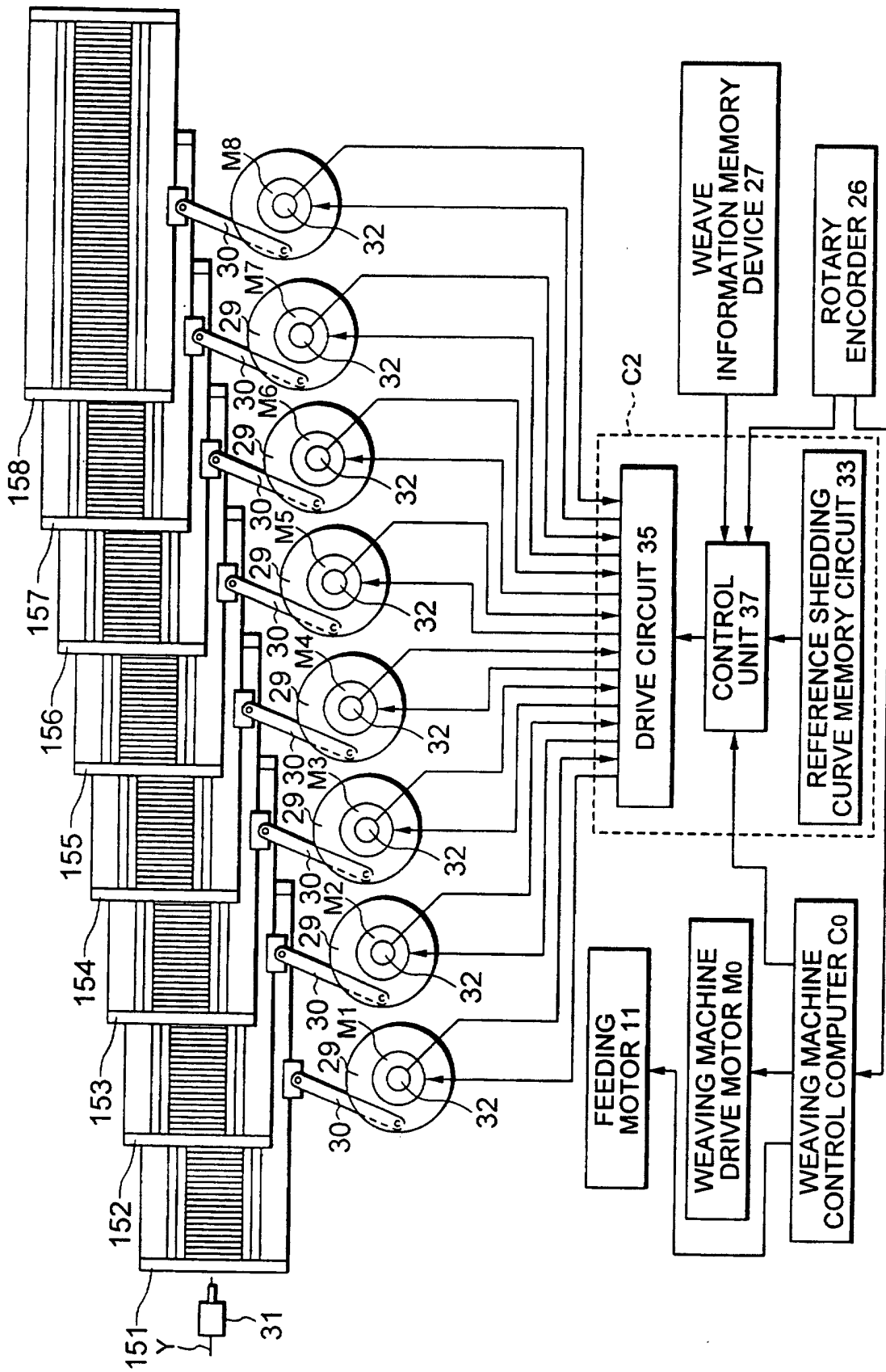


FIG. 7a

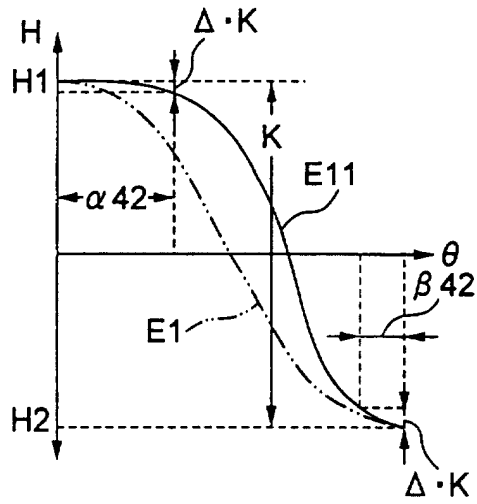


FIG. 7b

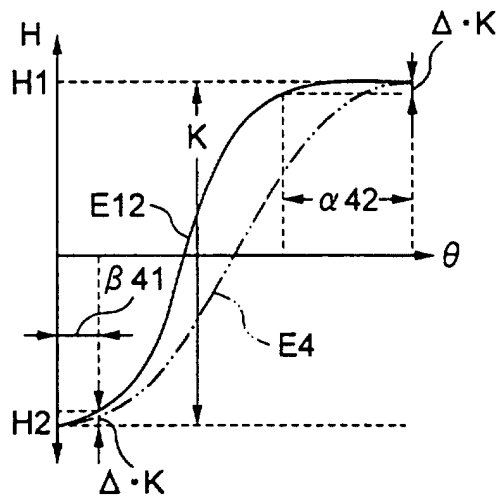


FIG. 8

16	2/2 PATTERN							
15	$\alpha (2/2), \beta (2/2)$							
14					1/1 PATTERN			
13					$\alpha (1/1), \beta (1/1)$			
12								
11								
10								
9								
8			1/6 PATTERN		6/1 PATTERN			
7			$\alpha (1/6)$		$\alpha (6/1)$			
6	2/2 PATTERN		$\beta (1/6)$		$\beta (6/1)$			
5	$\alpha (2/2)$							
4	$\beta (2/2)$		6/1 PATTERN		1/6 PATTERN			
3			$\alpha (6/1)$		$\alpha (1/6)$			
2			$\beta (6/1)$		$\beta (1/6)$			
1								
	151	152	153	154	155	156	157	158

HEDDLE FRAME NUMBER

FIG. 9

16	2/2 PATTERN				1/1 PATTERN		$\rho 3$	
15	$\alpha (2/2, \rho 3), \beta (2/2, \rho 3)$				$\alpha (1/1, \rho 3)$			
14					$\beta (1/1, \rho 3)$			
13							$\rho 2$	
12	1/1 PATTERN							
11	$\alpha (1/1, \rho 2), \beta (1/1, \rho 2)$							
10							$\rho 1$	
9								
8			1/6 PATTERN		6/1 PATTERN			
7			$\alpha (1/6, \rho 1)$		$\alpha (6/1, \rho 1)$			
6	2/2 PATTERN		$\beta (1/6, \rho 1)$		$\beta (6/1, \rho 1)$			
5	$\alpha (2/2, \rho 1)$				1/1 PATTERN			
4	$\beta (2/2, \rho 1)$		6/1 PATTERN		1/6 PATTERN			
3			$\alpha (6/1, \rho 1)$		$\alpha (1/6, \rho 1)$			
2			$\beta (6/1, \rho 1)$		$\beta (1/6, \rho 1)$			
1								
	151	152	153	154	155	156	157	158

HEDDLE FRAME NUMBER