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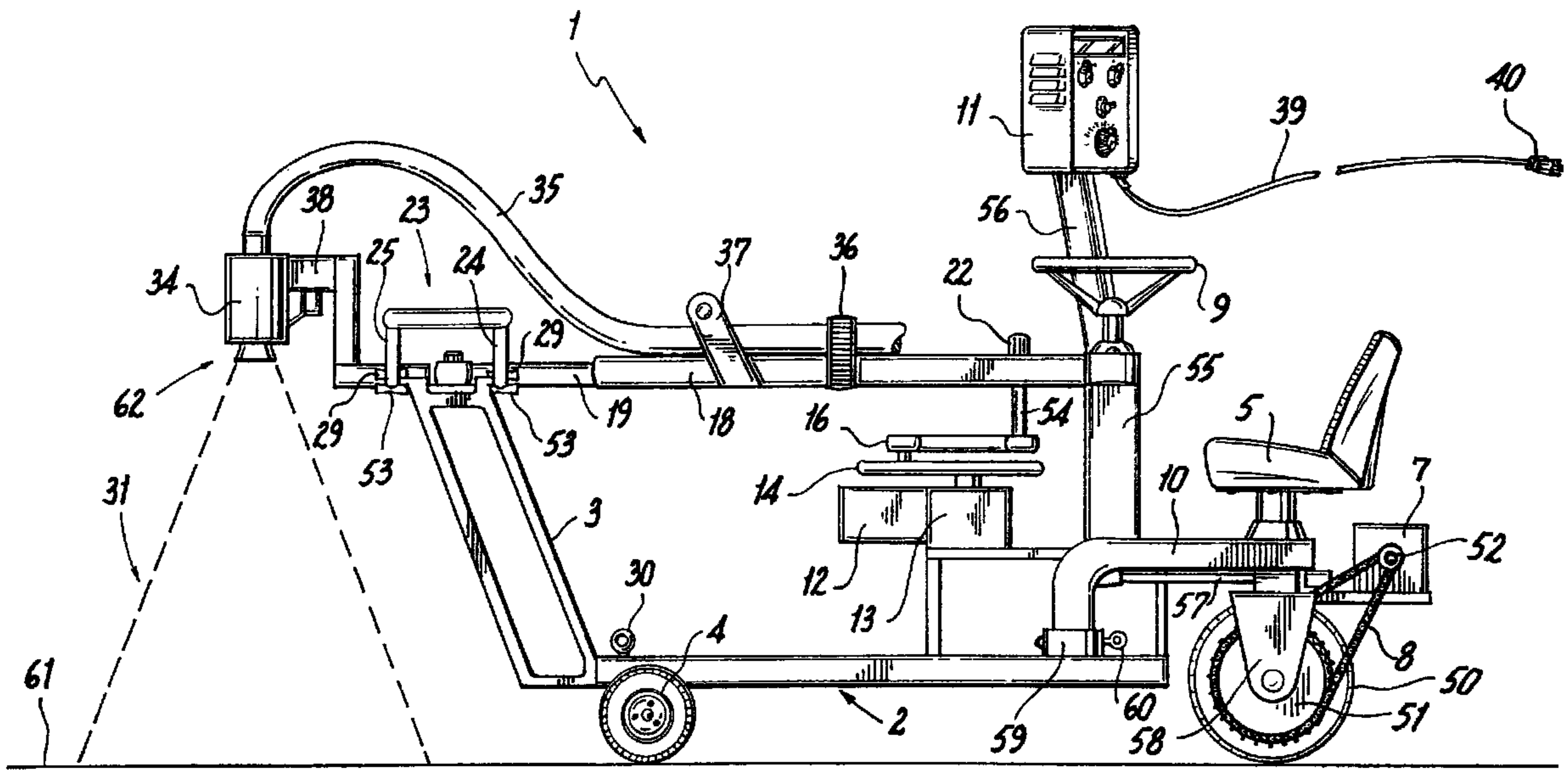

(57) Abrégé/Abstract:
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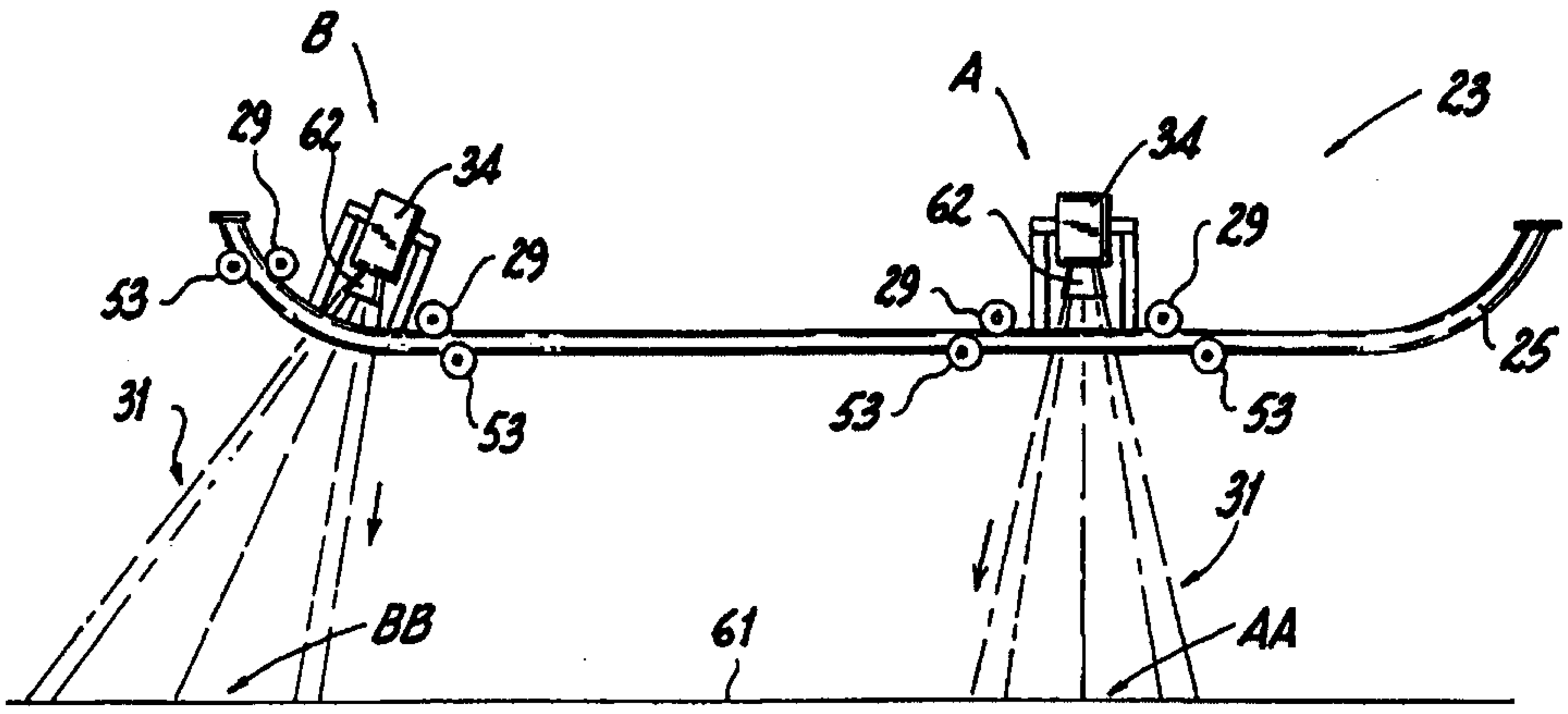

(57) Abstract

A method and an industrial vehicle (1) for uniformly applying coatings at appropriate thickness and pitch upon a surface wherein a nozzle holder assembly (34) moves between two parallel tracks or rails (24, 25) to dispense foam. The uniform application of foam at each pass is assured by accelerating the speed of the nozzle holder assembly at the end of each pass by providing respective curved, uphill distal ends of the tracks so that the nozzle holder assembly moves up the curved distal ends and returns quickly while changing speed and direction at the end of each pass.

SPRAY APPLICATOR FOR ROOFING AND OTHER SURFACES

FIELD OF THE INVENTION

The present invention relates to a new and useful method and industrial robotic device for applying coatings or other spray coated layers, in uniform thicknesses and at appropriate angles of pitch, in field applications, such as roofing applications or pavement applications.

BACKGROUND OF THE INVENTION

In the roofing applications, flat roofs are often made of polyurethane foam layers, which may be covered by various coatings, such as elastomeric coatings, such as silicone. It is difficult to maintain a uniform thickness when applying a foam or elastomeric material, which by its nature rises when applied to achieve a thickness above a roof base.

Furthermore, the faster that a foam applicator passes over a surface, the less volume of foam is applied, resulting in less of a thickness of the applied foam. To achieve thicker foam layers, a spray applicator is slowed down in velocity as it passes over the roof bases, so that more foam material is discharged per square unit of space of roof base being passed over by the spray applicator.

Various attempts have been made to apply foam uniformly, such as from an applicator moving at a uniform speed along a carriage track. However, at the end of each pass of an applicator over a portion of a roof base, the discharged foam is applied twice, i.e. once at the end of the pass to the edge, and again as it starts over above the previously applied foam, until the carriage can adjust to an unsprayed area.

Among prior art devices include U.S. Patent 5,381,597 of Petrove which describes a wheeled robotic device for installing shingles on roofs. While it does not concern spraying of urethane foam upon a flat roof, it does describe a movable, wheeled carriage for use upon a roof.

U.S. Patent 5,248,341 of Berry concerns the use of curved walls to accommodate spray paint applicators for curved surfaces, such as aircraft.

U.S. Patent 5,141,363 of Stephens describes a mobile train which rides on parallel tracks for spraying the inside of a tunnel.

U.S. Patent 5,098,024 of MacIntyre discloses a spray and effector which uses pivoting members to move an armature which holds a spray apparatus.

U.S. Patent 4,983,426 of Jordan discloses a method for the application of an aqueous coating upon a flat roof by applying a tiecoat to a mastic coat.

U.S. Patent 4,838,492 of Berry discloses a spray gun reciprocating device, wherein parallel tracks are used wherein each track is square in cross section, but further wherein each track guides a plurality of rollers thereon.

U.S. Patent 4,630,567 of Bambousek discloses a spray system for automobile bodies, including a paint booth, a paint robot apparatus movable therein, and a rail mechanism for supporting the apparatus thereat.

U.S. Patent 4,567,230 of Meyer describes a chemical composition for the application of a foam upon a flat roof.

U.S. Patent no. 4,167,151 of Muraoka discloses a spray applicator wherein a discharge nozzle is moved transversally upon a frame placed adjacent and parallel to the surface having the foam being applied thereto. However, the applicator of Muraoka `151 does not solve the problem of excess foam being applied at the end of each transverse pass of the discharge nozzle.

U.S. Patent no. 4,209,557 of Edwards describes a movable carriage for a nozzle applying adhesive to the back of a movably advancing sheet of carpeting. Similarly, Australian Patent no. 294,996 of Keith describes a movable carriage for a nozzle applying a polyurethane foam coating to a movably advancing sheet.

U.S. Patent 4,016,323 of Volovsek also discloses the application of foam to a flat roof.

U.S. Patent 3,786,965 and Canadian Patent no. 981,082, both of James et al, describe a self-contained trailer for environmentally containing a dispenser for uniformly dispensing urethane foam upon a terrestrial surface, wherein the problem of "skewing" occurs at the completion of each pass at the boundary edges of the surface to which are urethane foam is being applied. James `965 employs self-enclosed gantry robots to move the fluid discharge nozzle over the terrestrial surface.

U.S. Patent no. 3,667,687 of Rivking discloses a foam applicator device.

U.S. Patent no. 4,474,135 of Bellafiore discloses an apparatus for spraying a coating upon a spherical object supported by a post, which apparatus includes a curved track for providing orbital movement of a spray applicator about the exterior spherical surface of the sphere to be coated. While they are curved in nature, the curved tracks thereof are provided for orbital movement about the sphere, not to change the speed, tilt and direction of a linearly moving nozzle.

Another attempt to solve the problem of "double spraying" at a pass edge has been described in U.S. Patent no. 4,333,973 of Bellafiore, which describes a similar spray applicator, such as that of Autofoam® Company. This spray applicator includes a wheeled, self-movable vehicle having a carriage portion with a horizontal linear track thereon. The spray applicator moves from one end of the track to the other, opposite end of the track at the end of one pass, of the applicator, above a portion of a roof base, and then the applicator reverses direction upon the track.

However, to avoid the "double spraying" problem noted above, the Autofoam® device has an on-off switch which turns the applicator off at an appropriate time at the end of a pass while the applicator is reversing direction, and re-starts the applicator a short time later when the applicator has started to move in the opposite direction.

Moreover, there are severe problems with this approach, as the constant "on-off" starting and re-starting of the applicator causes fatigue to the metal or other material parts of the applicator, and a detrimental effect to the end product. In addition, the Bellafiore '973 and Autofoam® devices are bulky and complicated to use.

SUMMARY OF THE INVENTION

In accordance with one embodiment of the present invention there is provided a method of applying a spray-applied substance layer upon a structural surface, comprising the steps of: continuously applying the substance in liquid form in adjacent linearly extending bands from a spray applicator source moving on a track at a constant ground speed in alternate directions transverse to an axial direction of each band, each band having a predetermined width and axial length; subjecting the spray applicator source to an arcuate uphill movement by the bending of the track away from the surface at each end portion of each the transverse movement of the spray applicator source, wherein the transverse movement of the spray applicator source accelerates in speed along the track; the spray application source being tilted outward by the track and the spray applicator source moves uphill, thereby reducing the amount of the substance in liquid form being applied to the edge portions of each the band upon the structural surface.

In accordance with another embodiment of the present invention there is provided a spray applicator apparatus for applying spray coated layers in axially extending bands of predetermined widths, in uniform thicknesses upon a structural surface in field applications, comprising: a spray applicator vehicle having a frame; the frame supporting a movement power source, moving the vehicle, the frame further supporting at least one steerable powered wheel, and a swinging boom moving a liquid coating applicator source transversely along at least one straight track having first and second ends; the boom having a laterally movable telescoping end attachable to the liquid coating applicator source; and the at least one track constraining movement of the liquid coating applicator source in a linear path transverse to axial movement of the frame across the structural surface and shaped adjacent the ends to tilt the applicator source while maintaining a constant ground source.

A further embodiment of the present invention provides an industrial robotic device for applying coatings or other spray coated layers, in uniform thicknesses and at appropriate angles of pitch, in field applications comprising:

a movable spray applicator dispenser including at least one nozzle for discharge of at least one foam layer to a surface, the spray applicator movable along at least one linear track having a curved surface, the at least one linear track engageable with a corresponding curved surface of at least one wheel attached to the foam applicator, wherein transverse to the curved surface the at least one linear track has arcuate uphill distal end portions, wherein the movable spray applicator dispenser, moving along the at least one linear track, tilts and accelerates in speed as the movable spray applicator dispenser rolls up each respective the arcuate uphill portion, thereby reducing the amount of foam applied to an edge portion of the surface at the end of a pass of the movable spray applicator dispenser.

The present invention uses one or more track rails, such as a double linear track of round cross section, as shown in the drawings herein, wherein there is an arcuate uphill end portion of the track at each side, so that the spray applicator, which moves along the one or more linear tracks, will accelerate in speed and tilt the discharge nozzle outward as it rolls up the curved uphill portion, thereby reducing the amount of foam applied to the edge portion of the roof at the end of a pass of the applicator.

To obviate the complicated mechanisms of the Autofoam® device, the present invention uses simple mechanics to move the spray applicator. For example, a radially extending swinging arm is provided for the sideways movement of the applicator along the track. To eliminate arcuate movement of the pivoting arm, a telescoping mechanism is provided, so that the spray applicator moves linearly, instead of arcuately, as the swinging arm moves about a pivot fulcrum point.

To further insure uniform thickness, the present invention further comprises various speed controls, so that an appropriate thickness can be applied for each pass.

For example, a rheostat controls the speed of the movement of the spray applicator, and an LED readout tachometer has a display dial with appropriate readings for appropriate speeds for corresponding desired thicknesses. Since the rate of flow of foam-producing material emanating from the nozzle is fixed, the ground movement speed of the applicator determines the weight of the coating per unit area applied. This, in turn, determines the thickness.

When a slope is desired on a flat roof, such as toward a drainage line, the ground speed of the foam applicator can be reduced on each successive pass away and parallel to the drainage line. This will result in a stepwise slope approximating the desired contour.

It has been found that a nutating nozzle holder, which tilts the nozzle a small amount cyclically as it traverses the track, can be used to minimize the variations in foam thickness (in the form of rounded ridges) due to the hollow-cone pattern of the nozzle.

Accessories can be added to the spray applicator so that it can be adapted for spraying adhesive on a roof or for automatically laying an elastomeric sheet covering such as Sure-Seal™ Fleece Back 100 EPDM made by Carlisle SynTec Incorporated of Carlisle, PA over a polyurethane foam substrate. Accessories can also be added for imbedding reinforced fabric within the polyurethane foal substrate.

While the invention has been described for use in applying roofing materials on roofs, it is also usable for spray applications at ground level such as for pavement painting or sealing applications.

DESCRIPTION OF THE DRAWINGS

The present invention can best be described in conjunction with the accompanying drawings, in which:

Figure 1 is a top plan view of a spray applicator vehicle of the present invention;

Figure 2 is a side elevation of a spray applicator vehicle of the present invention;

Figure 3 is a side cross section detail of a transverse rail and carriage;

Figure 4 is an end elevation of a transverse rail and carriage;

Figure 5 is a block diagram of a spray applicator electrical system;

Figure 6 is an end cross section of a coated roof with a central drain ridge;

Figure 7 is a block diagram of a spray applicator .ectrical system using a hand-held remote control;

Figure 8 is a nozzle spray pattern and Figure 8A is the resultant foam cross section;

Figure 9 is a nutating spray nozzle feature with details thereof; wherein

Figure 9A is a side elevation of a nozzle holder and an actuator cable; and,

Figure 9B is a top plan view of a cam and cam follower;

Figure 10 is a side elevation of a spray applicator as adapted for laying elastomeric sheet roofing material; and,

Figure 11 is a side elevation of a spray application vehicle as adapted for applying fabric or mesh reinforced foam coating.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

As shown in Figures 1-2, spray applicator 1 is used for applying polyurethane foam coatings or other spray coated layers, in uniform thicknesses in field applications, such as roofing applications or pavement applications.

As shown in Figures 1 and 2, spray applicator vehicle 1 includes frame 2, operator seat 5, steerable powered single wheel 50, two unpowered side wheels 4, swinging boom 18, transverse rail subassembly 23 and various associated parts of nozzle 62 attached to carriage plate 26. Motor 6 drives sprocket 52 of chain 8 through gear reduction box 7 to provide vehicle motion via wheel sprocket 51. The operator steers the vehicle 1 by steering wheel 9, which moves steering linkage bar 57, thereby rotating wheel flange 58. Boom 18 is continuously reciprocated from pivot point 20 on tower 55 by crank arm 16 which is cyclically moved by reduction gear box 13 powered by motor 12, via adjustable linkage arm 14. Linkage arm 14 is attached to output shaft 17 and is rotated at a constant speed as determined by settings in control box 11. Slot 15 permits adjustment of the lateral movement limits of telescoping end 19 of boom 18. Rails 24 and 25 constrain the movement of carriage plate 26 to a linear path transverse to frame 2.

Control box 11 also sets the ground speed of vehicle 1. Hose 35, which may consist of two or more separate hoses or individual lumens, carries liquid materials for spraying through nozzle 62 from a remote pressurized source. For polyurethane foam, two chemicals supplied from separate hoses 35 are mixed at the nozzle 62 just prior to discharge. The two liquids interact chemically causing an exothermic foaming and hardening reaction. Hose 35 is retained in boom bracket 37 and may also be attached in one or more places by hook and loop straps 36. In normal use, a second (non-riding) work person guides hose 35. Solenoid 38, actuated by a switch in control unit 11, operates the discharge valve at nozzle 62.

It can be appreciated that vehicle 1 rolling at a constant speed with boom 18 reciprocating continuously is able to spray a continuous strip of coating on a surface. If the discharge rate at the nozzle is held constant, the amount of product sprayed on a surface per unit of sprayed area can be set by selecting ground speed.

Since the boom changes direction at the distal ends of its swings, a method is employed to limit the amount discharged to prevent "double coating" at the edges.

As noted before, prior art systems, such as described in Bellafoire `973 and of Autofoam® Company, shut the nozzle off at these portions of the cycle. However this action causes several problems.

For example, the on/off cycling has detrimental effects on spray material consistency from a chemical reaction point of view. The on/off cycling also causes mechanical wear and induces metal fatigue on brackets that must react to cyclic pressure loading.

In contrast to the devices of Bellafoire `973 and of the Autofoam® Company, the present invention uses a geometric arrangement and constant liquid product flow to prevent pattern edge build-up.

For example, Figure 3 shows a cross section of rails 24 and 25 in the middle of the transverse sweep. Carriage plate 26, driven by end bushing 27 on telescoping extension 19, is shown with brackets 65 and 66 attached. Brackets 65 secure top rollers 29 with concave "hourglass" contours. Similarly contoured bottom rollers 53 are secured by brackets 66. Thus rollers 29 and 53 capture rails 24 and 25 constraining plate 26 to roll along these rails. Plate 26 also supports nozzle holder assembly 34 (not shown in this figure).

Figure 4 shows an end view of rail subassembly 23. Both rails 24 and 25 are curved at their distal ends in a constant radius. Nozzle assembly 34 is shown in a flat vertical spray location at "A" and at an oblique spray location at the extreme limit of travel on the curved portion at "B". Top rollers 29 and bottom rollers 53 are offset from each other to facilitate easy rolling without binding on the curved portions. If boom 18 is reciprocated at an essentially constant rate, the carriage assembly is accelerated at the ends of travel due to the greater distance traveled per unit time on the curved end contour as well as the change in direction. Furthermore, the angle of nozzle 62 is tilted outward at the end so that the coverage area "BB" is larger than that of "AA". These end factors combine to reduce the thickness of the sprayed layer so that the "double layering" at the edge of each applied band of foam can be controlled to result in an edge thickness essentially the same as that of the center portion of a pass. This can be adjusted empirically based on the particular batch, temperature and other field conditions. The adjustment is the end limit position of nozzle 62 relative to the track end curve as determined by the adjustment of crank arm 16 in slot 15 of linkage arm 14.

Spray vehicle 1 is designed to be easily disassembled into four subassemblies for easy transport to the roof of a building on an elevator or by using a winch. Prior art systems require a crane. Booms 18 and 19 can be lifted off as a unit by removing spring pin 22 from upright link 54, spring pin 21 from pivot shaft 20 and spring pin 28 from carriage plate 26 coupling.

A front subassembly including of track subassembly 23 with uprights 3 can be removed by removing two spring pins 30 from frame member 2.

Central frame 2 subassembly including wheels 4 can be separated from the driven wheel subassembly (including seat 5 and steering wheel 9 by removing large spring pin 60 from socket member 59 on the frame subassembly. Then back chassis 10 can be lifted free. Electrical connections tying the various subassemblies have connectors which must be disconnected. The four subassemblies can then be reassembled on the rooftop.

Figure 5 shows a block diagram of the electrical system largely housed in control box 11. The spray applicator vehicle 1 is electrically operated by connection to standard AC mains (typically 115VAC at 60HZ) via plug 40 and extension cord 39. A portable engine operated generator can supply this power as an alternative. Although two separate modular AC/DC converters 76 and 83 are depicted, a single converter can supply current to all DC loads.

An AC power switch 75 controls power to the entire spray applicator vehicle 1. Converter 76 supplies DC to a unidirectional speed control 77 with digital speed indicator 78 and speed set control 79. For maximum consistency of application, speed control 77 is preferable a PID type of feedback servo control which maintains output speed of motor 12 (for swinging of boom 18) constant via feedback from encoder 80 mounted on motor 12.

Switch 81 controls power to a solenoid 82 which opens the discharge valve at nozzle 62. Converter 83 supplies DC power to a bi-directional PID speed control 84 with digital speed indicator 85 and speed set control 86. This control accurately and repeatedly maintains the ground speed in either direction of spray applicator vehicle 1 as set even under varying load conditions by virtue of feedback encoder 87 mounted on motor 6.

This operation is used during the spraying operation and determines the thickness of the resulting sprayed layer.

control switch 89 determines the direction of movement as forward or reverse.

A second manual bi-directional speed control 90 is used to quickly select the desired ground speed via alternate manual control 91 when it is desired to maneuver spray applicator vehicle 1 prior or after a spray application.

In this manner, the carefully selected "automatic" setting for spraying is not altered. Either automatic speed control 84 or manual speed control 90 is actively enabled at any one time via selector switch 88.

The repeatable application of a desired amount of coating per pass permits the type of roof foam surfacing depicted in Figure 6. This is an exaggerated cross section of the end of a roof 61 surface with a central drain 96 ditch with grate cover 95. If the roof 61 had a flat pitch, it would be desirable to create a pitch toward the drainage ditch for more effective drainage. This can be approximated by a stepped foam layer as shown, starting from lowest strip "A" and rising in thickness to strip "E" of the thickest cross section farthest from central drain 96. These strips can be applied in a single pass or in multiple passes by spray applicator vehicle 1 where the ground speed for layer "A" is fastest and the speed is reduced for each successive layer "B","C","D" "E" and "F".

For safety reasons, federal OSHA occupational safety regulations stipulate that a powered vehicle cannot be ridden by a workperson within ten feet of the edge of a roof. Also, a workperson is required to guide hose 35 while the operator rides and guides spray applicator vehicle 1. For these reasons, it would be desirable to operate spray applicator vehicle remotely. In this manner, a single workperson controls spray applicator vehicle 1 and guide hose 35.

Figure 7 shows such a remote control configuration. Control box 11 is replaced by a hand-held remote control box 100 with a face plate and several vehicle mounted functional units. Since the operator is no longer physically on spray applicator vehicle 1, electric steering ram 102 replaces the steering wheel. Electric steeling ram 102 is controlled by positional steering control 101, which sets the position of steered wheel 50 to match that of steering control wheel 106 on remote control box 100.

Communications between remote control box 100 and spray applicator vehicle 1 is via coiled cable 105, although a fail-safe radio communications channel can be used as well. To limit the number of individual conductors in cable 105, a multiplexor/demultiplexor module 103 and 104 is used at each end of cable 105 to facilitate the two way communications. The function of similarly numbered components is the same as that explained above in reference to Figure 5.

Hollow-cone nozzle 62 sprays a pattern 110 that impinges on the ground as shown in Figure 8. As this pattern is swept sideways in a single pass, it will lay material that is denser toward the top and bottom edges resulting in a cross section with ridges 111 and valley 112 in the "Y" direction from roof surface 61.

While multiple sweeps by boom 18 mitigate this effect somewhat, ridges in the final sprayed surface still persist. This problem is eliminated by nutating or cyclically rocking the nozzle mount 34 slightly at right angles to rails 24 and 25 several times during each sweep to even out the coverage of hollow-cone nozzle 62 over multiple sweeps.

Figure 9 shows optional modifications to accomplish this. The detail of Figure 9A shows modified bracket 120 with pivot 121 holding nozzle mount 34. Bracket 120 is fastened to carriage plate 26. A push-pull cable assembly including armored housing sleeve 123 with cable 122 within is used to actuate the cyclic motion illustrated by the phantom representation (shown in broken lines) of nozzle holder 34 at the extreme outward position. The detail of Figure 9B shows the powering end of cable 122. Bracket 126, attached to the frame of vehicle spray applicator 1 in the vicinity of gear box 13, retains sleeve 123. Cam follower 130 is pivoted at pivot point 128 within adjustment slot 127 and is biased toward multiple lobe cam 131 by spring 129. The stroke of wire 122 (and therefore the amount of cyclic tilt of nozzle holder 34) is determined by the dimensions and geometry of cam follower 130 and the depth of lobes on multiple lobe cam 131.

The proper centering of the motion of holder 34 is adjusted by moving pivot 128 within slot 127. Multiple lobe cam 131 is attached to the output shaft of gear box 13 under arm 14. It can be appreciated that cable wire 122 is cycled by each cam lobe as multiple lobe cam 131 rotates.

By moving cam follower 130 out of contact with multiple lobe cam 131 and tightening it in a locked position, to defeat the pivoting, nozzle holder 34 can be locked in a vertical position to defeat the nutating feature.

Alternatively, a separate small gear motor and crank coupling (not shown) mounted right on bracket 120 can be used to actuate the nutating action without need of cable 122.

Spray applicator vehicle 1 is easily modified to adhesively bond sheet elastomeric roofing material. As shown in Figure 10, side arms 141 are pivoted at pivot point 140 from side extensions (not shown) which are attached to frame 2. These arms 141 have telescoping extensions 142 which are locked with hand screws 143. A roll of elastomeric sheet 144 is pivoted at the end of arms 142 at pivot point 148, with sheet end 145 trailing roll 144 as vehicle spray applicator 1 moves in the direction of arrow 149. Also pivoted at pivot point 148 are side arms 146 which trail a weighted roller 147, which weighted roller 147 applies even pressure to sheet layer 145. Nozzle 62 sprays a layer of bonding adhesive which bonds sheet 145 to roof surface 61.

Alternately, roll 144 can be adjusted to apply a skin coating of rolled material over the solidified foam layer applied from nozzle 62 to a surface, such as a roof.

Adjustment of extensions 142 determine the distance X between the sheet contact and the sprayed roof surface a fixed distance from the center of the spray cone. Since the vehicle moves at a predetermined constant speed, distance X can be used to match the optimal delay from adhesive application to contact of the sheet roofing material.

A method for applying reinforced foam roofing involves the use of a reinforcing fabric or open fabric mesh. The fabric can be manufactured of a variety of fibers such as nylon, fiberglass, aramid, etc. The method involves spraying a foaming mixture and immediately imbedding the reinforcing fabric in the mixture before the foam rises so that the reinforcing fabric rises with the foam and is embedded in the foam layer.

Figure 11 shows modifications of the spraying applicator vehicle 1 for accomplishing this task. Side arms 160 are rigidly attached to frame 2 and uprights 3; they flare out at the distal end to lie outside of the spray pattern on each side. Roll 164 of lightweight reinforcing fabric is pivotly attached at the end of arms 160. The free end of fabric 165 is fed under light roller 162, which contacts surface 61 just at the edge of the foam adhesive spray pattern. Spring plunger 161 supported by brace 163 forces roller 162 into contact with roof surface 61. Foam spray 168, prior to rising, is contacted with fabric 165, which rises with foam 166 to embed itself in the foam layer as shown by the broken line.

It is further noted that other modifications may be made to the present invention without departing from the scope as noted in the appended claims.

CLAIMS:

1. A method of applying a spray-applied substance layer upon a structural surface, comprising the steps of:

continuously applying said substance in liquid form in adjacent linearly extending bands from a spray applicator source moving on a track at a constant ground speed in alternate directions transverse to an axial direction of each band, each said band having a predetermined width and axial length;

subjecting said spray applicator source to an arcuate uphill movement by the bending of said track away from said surface at each end portion of each said transverse movement of said spray applicator source, wherein said transverse movement of said spray applicator source accelerates in speed along said track;

said spray application source being tilted outward by said track and said spray applicator source moves uphill, thereby reducing the amount of said substance in liquid form being applied to the edge portions of each said band upon the structural surface.

2. A method of applying a solid roofing polyurethane foam layer upon a structural surface comprising the steps of:

continuously applying said foam layer in liquid form in adjacent linearly extending bands of foam as a coating of said solid foam layer upon said structural surface, from a foam applicator source moving on a track at a constant ground movement speed in alternate directions transverse to an axial direction of each band of said bands of said foam, each said band having a predetermined width and axial length;

subjecting said applicator source to an uphill movement by bending of said track at each end portion of each said transverse movement of said applicator source;

said foam applicator source being tilted outwardly by said track as said foam applicator source moves uphill on said track, thereby reducing the amount of said liquid foam being applied to said respective edge portions of each said band of foam upon the structural surface at an end of each pass of said liquid foam applicator source across each said linearly extending band of foam.

3. The method as in claim 2, wherein said foam applicator source is a nozzle.

4. The method as in claim 3, wherein a radially extending swinging arm with a telescoping slide mechanism provides said transverse movement of said foam applicator source along said track, so that said foam applicator source moves linearly instead of arcuately, as said swinging arm pivots about a pivot fulcrum point.

5. The method as in claim 4, further comprising the steps of controlling thickness of said liquid foam upon the structural surface by varying a rate of flow of discharge of said liquid foam emanating from said foam applicator source, whereby ground movement speed of said transverse movements of said foam applicator source determines a weight of said coating of foam per unit area applied, to determine a thickness of a resultant solid foam layer.

6. The method as in claim 5, further comprising the step of applying a slope on a portion of said resultant solid foam layer toward a drain, by reducing said ground movement speed of said foam applicator source on successive passes away and parallel to a drainage line of said drain, resulting in a stepwise slope approximating a predetermined contour of said drain.

7. The method as in claim 4, further comprising the step of tilting said foam applicator source a predetermined amount cyclically as said foam applicator source moves transversely along said track, thereby minimizing variation

in foam thickness in the form of rounded ridges due to a hollow-cone pattern of the application of said liquid foam from said foam applicator source.

8. The method as in claim 4, further comprising the step of applying a layer of fabric from a fabric roll to said layer of liquid foam, thereby reinforcing said solid foam layer with said fabric layer, whereby during solidification of said liquid foam, said fabric layer becomes imbedded in said resultant solid foam layer.

9. The method as in claim 4, further comprising the step of applying an elastomeric sheet covering over said liquid foam layer, thereby forming a coating skin over said resultant solid foam layer.

10. A spray applicator apparatus for applying spray coated layers in axially extending bands of predetermined widths, in uniform thicknesses upon a structural surface in field applications, comprising:

a spray applicator vehicle having a frame;

said frame supporting a movement power source, moving said vehicle, said frame further supporting at least one steerable powered wheel, and a swinging boom moving a liquid coating applicator source transversely along at least one straight track having first and second ends;

said boom having a laterally movable telescoping end attachable to said liquid coating applicator source; and

said at least one track constraining movement of said liquid coating applicator source in a linear path transverse to axial movement of said frame across said structural surface and shaped adjacent said ends to tilt said applicator source while maintaining a constant ground source.

11. The spray applicator as in claim 10, wherein said liquid coating applicator source comprises at least two separate conduits, each said conduit carrying a respective

liquid, said respective liquids being mixed within a mixing discharge valve of said liquid coating applicator source for spraying said liquid coating through a nozzle from a remote pressurized source to said structural surface.

12. The spray applicator apparatus as in claim 11, further comprising each said mixing discharge valve being located at each said nozzle just prior to a discharge output of said nozzle, wherein each said mixing valve mixes said liquids to chemically cause an exothermic foaming and hardening reaction of said spray coated layer of said liquid coating from a liquid foam into a resultant solid foam layer.

13. The spray applicator apparatus as in claim 12, further comprising a solenoid actuated by a switch in a control unit operating each said mixing discharge valve at each said nozzle.

14. The spray applicator apparatus as in claim 10, further comprising a means to limit the amount of liquid coating discharged to prevent a double coating at respective edges of a layer of said coating;

said means comprising at least one geometrically variable track having a linear portion extending transverse to said layer of coating in a middle of a transverse sweep of said liquid coating applicator source;

said at least one geometrically variable track being curved at respective distal ends thereof in a constant radius;

whereby said curved distal ends limit travel of said liquid coating applicator, whereby the speed of said liquid coating applicator source is accelerated at respective ends of transverse travel upon said at least one track due to the greater distance traveled per unit time on said curved distal ends of said at least one track, as well as due to change in direction.

15. The spray applicator apparatus as in claim 14, wherein said at least one track comprises a pair of rails, said liquid coating applicator source riding upon a carriage movable upon said pair of rails.

16. The spray applicator apparatus as in claim 11, further comprising a nutating means automatically moving said liquid coating applicator source through an adjustable stroke transverse to said at least one track several times on each pass of said liquid coating applicator to counteract variations in layer thicknesses resulting from a hollow cone spray pattern of said liquid coating applicator source.

17. The spray applicator apparatus as in claim 16, wherein said nutating means is an oscillator.

18. The spray applicator apparatus as in claim 16, wherein said nutating means comprises a first bracket with a pivot therein, said first bracket holding each said nozzle of said liquid foam applicator source, said first bracket fastenable to a carriage plate carrying each said nozzle;

said nutating means further having a push-pull coupling assembly including a housing with a coupling therein, said coupling actuating cyclic motion of a holder for each said nozzle;

said nutating means having a powering end connected to said coupling, said nutating means having a second bracket attached to said frame of said spray applicator apparatus in the vicinity of a gear box;

said nutating means further having a pivotable cam follower pivotable about a pivot point within an adjustment slot;

said cam follower biased toward a multiple lobe cam by a spring, wherein a stroke of said coupling controlling the amount of cyclic tilt of each said nozzle is determined by predetermined dimensions and geometry of said cam follower and a predetermined depth of each lobe on said cam;

wherein a predetermined centering of motion of each said nozzle is adjusted by moving said pivot point within said slot;

said cam being attachable to an output shaft of said gear box, each said nozzle being cycled by movement of each said cam lobe as said multiple lobe cam rotates;

wherein movement of said cam follower out of contact with said multiple lobe cam and tightening said cam follower in a locked position defeats said pivoting of each said nozzle, thereby locking each said nozzle in a vertical spray position to deactivate said nutating means.

19. The spray applicator apparatus as in claim 18, wherein said coupling is a cable wire.

20. The spray applicator apparatus as in claim 16, wherein said nutating means is a crank coupling and gear motor assembly connected to said liquid coating applicator source, wherein a stroke of said crank coupling controls the amount of cyclic tilt of each said nozzle of said liquid coating applicator source.

21. The spray applicator apparatus as in claim 11, wherein said movement power source further comprises a remote control communicating with said movement power source to move said spray applicator remotely.

22. The spray applicator apparatus as in claim 11, wherein said vehicle is assembled and disassembled as a modular unit for easy transport to the roof of a building on an elevator or by using a winch, further comprising:

said boom being alternately attachable to and removable from said frame of said vehicle by removal of a fastener therebetween;

said liquid coating applicator source being alternately attached to and removable from said at least one track;

said at least one track being removable from said frame by removing a first further fastener therebetween;

said at least one steerable powered wheel being attachable to a driven wheel subassembly including an operator seat and a steering wheel, said driven wheel subassembly being alternately attachable to and removable from said frame by removal of a second further fastener therebetween;

said power source having a plurality of electrical connections, connecting said applicator source, said power source and said at least one powered wheel;

wherein upon disassembly of said modular unit, said boom, said liquid coating applicator source, said at least one track, said frame, said at least one steerable powered wheel, said driven wheel subassembly, including said operator seat and said steering wheel, are transportable separately to said roof for reassembly of said modular unit thereat.

23. The spray applicator apparatus as in claim 11, wherein said power source comprises a control box removably attachable to said frame, said control box connectable to standard AC mains via an electrical connection, said power source further comprising a motor;

said control box having at least one AC/DC converter supplying current to at least one DC load;

said power source having an AC power switch controlling power to said spray applicator apparatus;

said at least one converter supplying DC power to a unidirectional speed control with a digital speed indicator and a speed set control, maintaining constant output speed of said motor for swinging of said boom via a feedback from a motor mounted encoder;

said power source having a switch controlling power to a solenoid which said solenoid opens said discharge valve of said nozzle of said liquid coating application source;

said power source having a further converter supply DC power to a bi-directional Proportional Integral and Differential (PID) speed control with a digital speed indicator and a speed set control, said speed set control accurately and repeatedly maintaining the ground speed in either direction of said spray applicator apparatus as set under varying load conditions by virtue of said motor mounted feedback encoder, for determining the thickness of the resulting sprayed layer of foam;

said power source having a further control switch determining the direction of movement as forward or reverse; and

said power source having a second bi-directional speed control for quickly selecting a desired ground speed via an optional manual control when it is desired to maneuver said spray applicator apparatus prior or after an application of said liquid coating.

24. The spray applicator apparatus as in claim 21, wherein said remote control comprises a hand-held remote control box with a face plate and a plurality of functional units;

said at least one steerable wheel being controllable by an electric steering ram, said electric steering ram controllable by a positional steering control setting the position of said at least one steerable wheel to match that of a steering control wheel connected to said at least one steerable wheel; and

said remote control communicating with said power source via a remote communications means.

25. The spray applicator apparatus as in claim 24,

wherein said remote communications means is a radio communications channel.

26. The spray applicator apparatus as in claim 24, wherein said remote communications means is a coiled cable.

27. The spray applicator apparatus as in claim 11, further comprising a means for adhesively bonding a sheet of an elastomeric roofing substrate layer.

28. The spray applicator apparatus as in claim 27, wherein said means for adhesively bonding a sheet of elastomeric roofing substrate layer comprises a roll of elastomeric sheet being pivotable at an end of a pair of linking arms connecting said roll to said frame;

said roll being urged flat by a trailing weighted roller applying even pressure to said sheet layer, said liquid coating applicator source spraying a layer of bonding adhesive, which said adhesive bonds said structural surface to said sheet.

29. The spray applicator apparatus as in claim 11, further comprising a means for reinforcing said liquid coating with reinforcing fabric, said means comprising a roll of fabric pivotable at an end of a pair of linking arms connecting said roll to said frame;

said fabric being urged flat by a trailing weighted roller applying even pressure to said fabric, said fabric being applied into said applied liquid foam before said coating rises to said resultant solid coating layer wherein said reinforcing fabric is embedded in said resultant solid coating layer.

30. The spray applicator apparatus as in claim 29, wherein said liquid coating is polyurethane foam.

31. An industrial robotic device for applying coatings or other spray coated layers, in uniform thicknesses and at appropriate angles of pitch, in field applications

comprising:

a movable spray applicator dispenser including at least one nozzle for discharge of at least one foam layer to a surface, said spray applicator movable along at least one linear track having a curved surface, said at least one linear track engageable with a corresponding curved surface of at least one wheel attached to said foam applicator, wherein transverse to said curved surface said at least one linear track has arcuate uphill distal end portions, wherein said movable spray applicator dispenser, moving along said at least one linear track, tilts and accelerates in speed as said movable spray applicator dispenser rolls up each respective said arcuate uphill portion, thereby reducing the amount of foam applied to an edge portion of the surface at the end of a pass of said movable spray applicator dispenser.

32. The device as in claim 31, wherein said at least one track and said at least one wheel comprise a pair of tracks and a pair of wheels.

33. The device as in claim 31, wherein said at least one wheel comprises a curved wheel when viewed in cross section, so that said curved wheel fits against and moves along said curved surface of an edge of said at least one track.

34. The device as in claim 31, further comprising a radially extending swinging arm providing transverse sideways movement of said movable spray applicator dispenser along said at least one track.

35. The device as in claim 34, wherein a telescoping slide mechanism is provided, so that said movable spray applicator dispenser moves linearly, instead of arcuately, as said swinging arm pivots about a pivot fulcrum point.

36. The device as in claim 31, further comprising a speed control controlling the speed of the movement of said movable spray applicator dispenser.

37. The device as in claim 36, further comprising a timer to vary the thickness of each layer of foam on a particular pass of said movable spray applicator dispenser over a predetermined portion of said surface.

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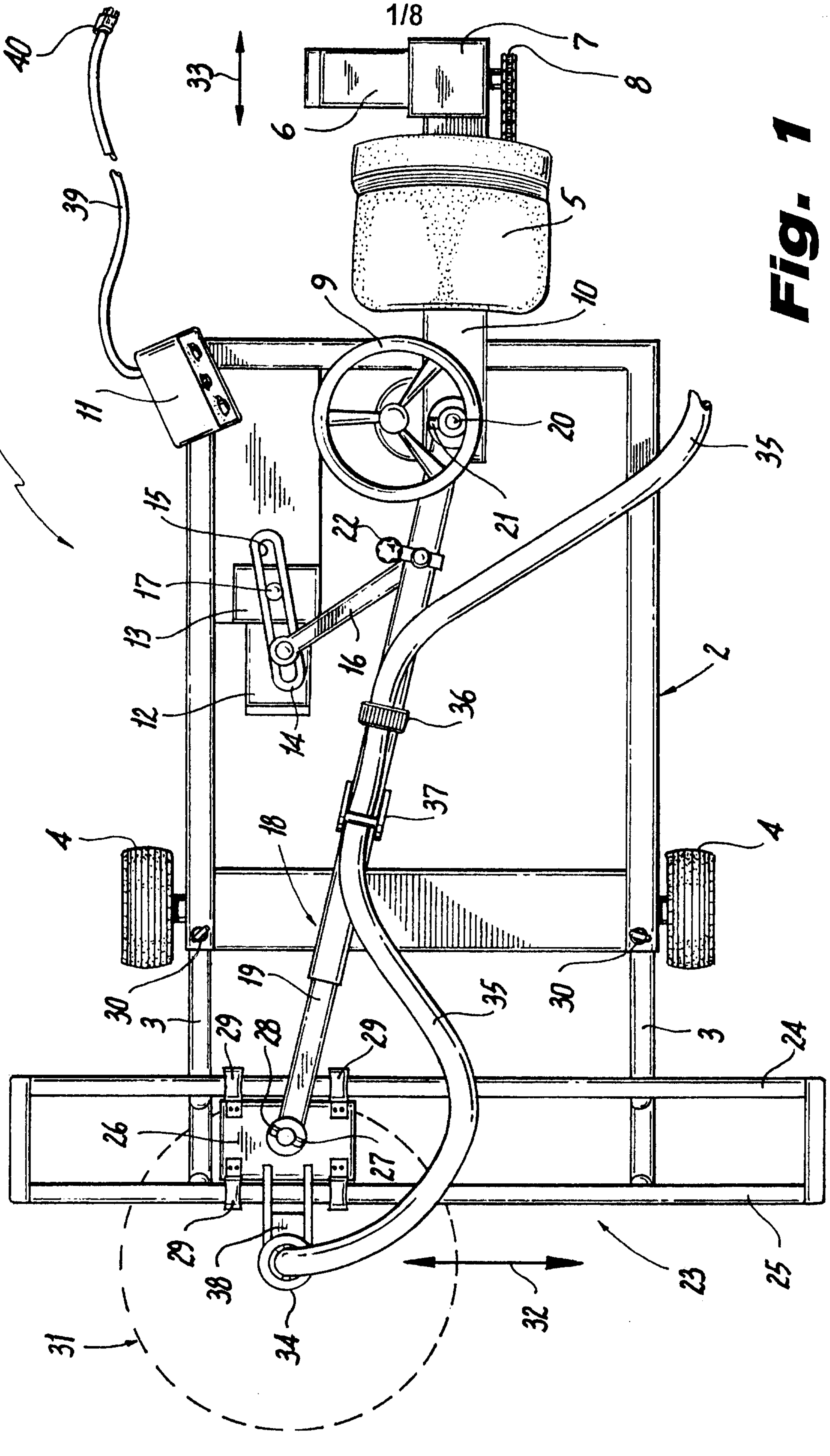
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Fig. 1

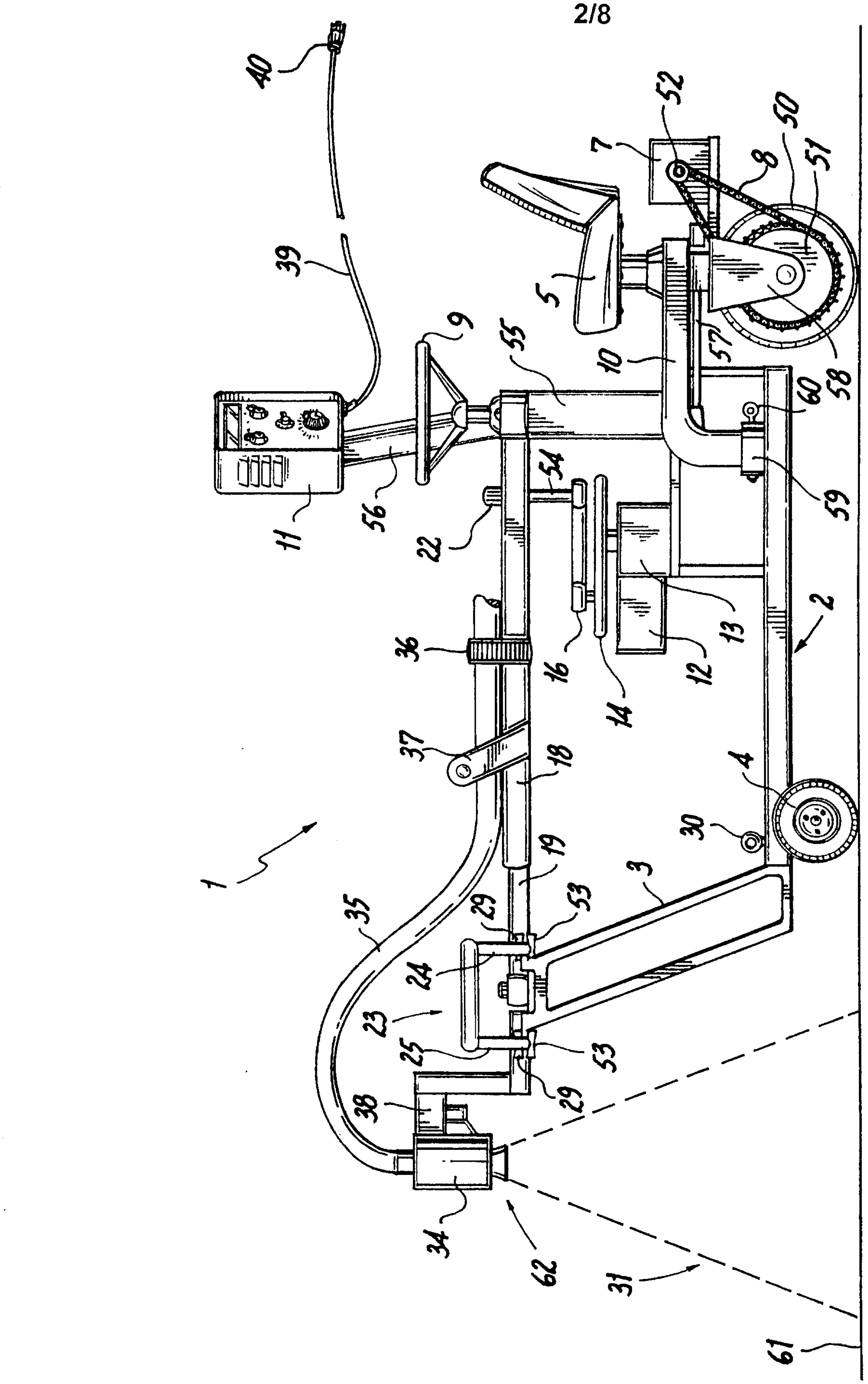
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Fig. 2

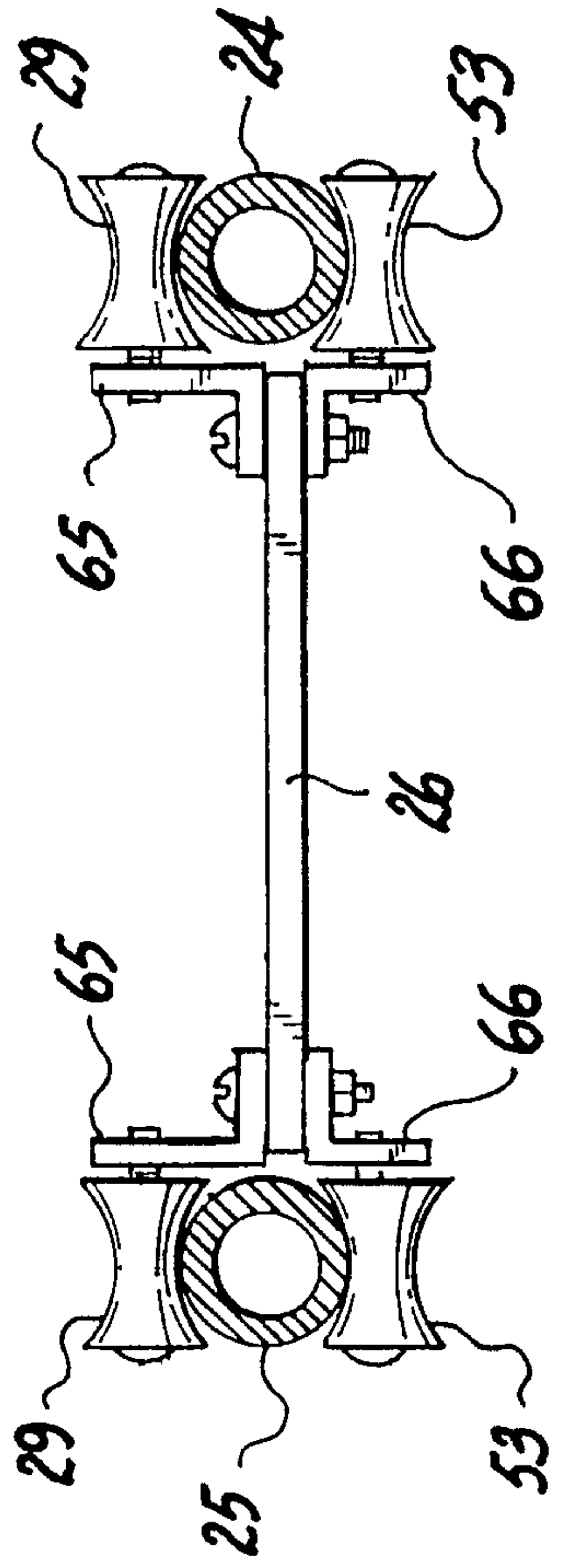
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Fig. 3

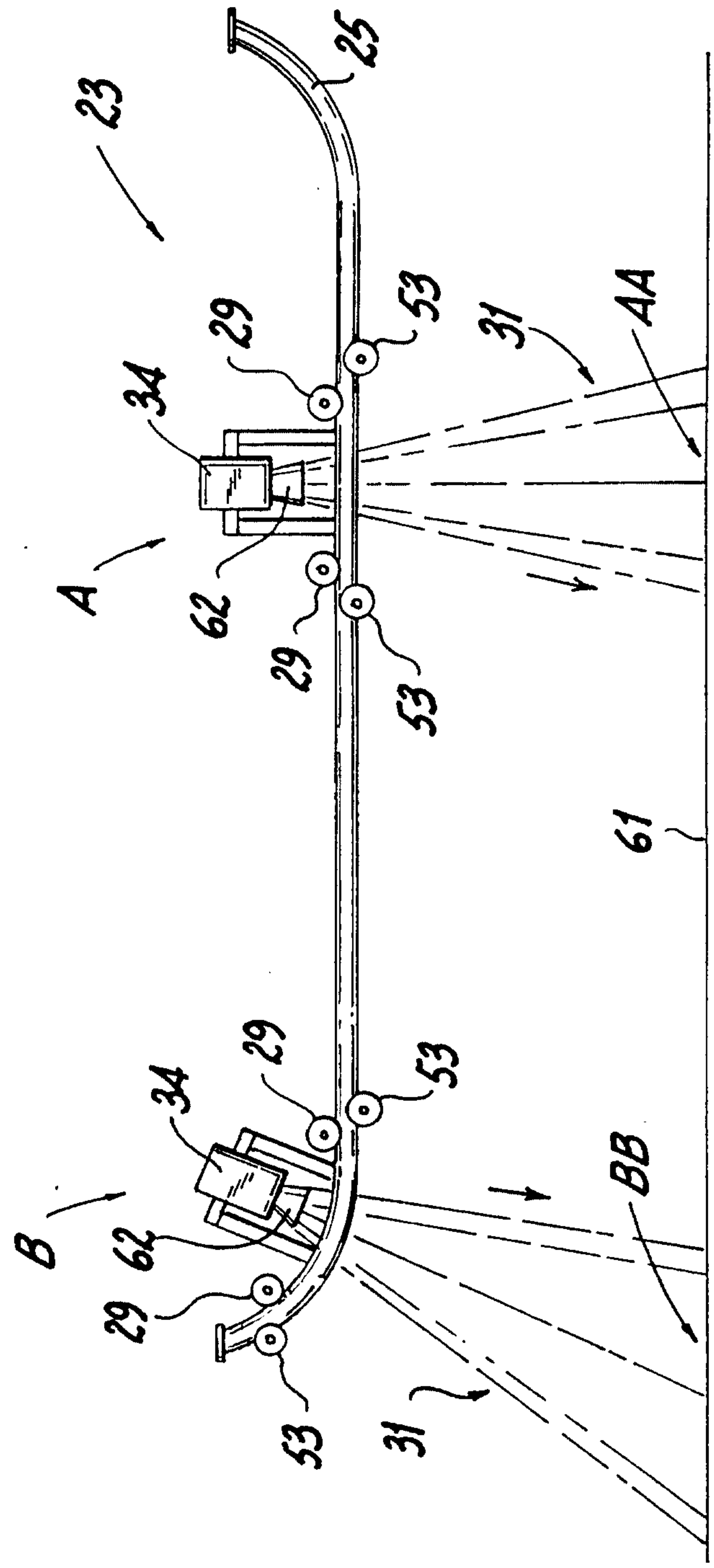
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Fig. 4

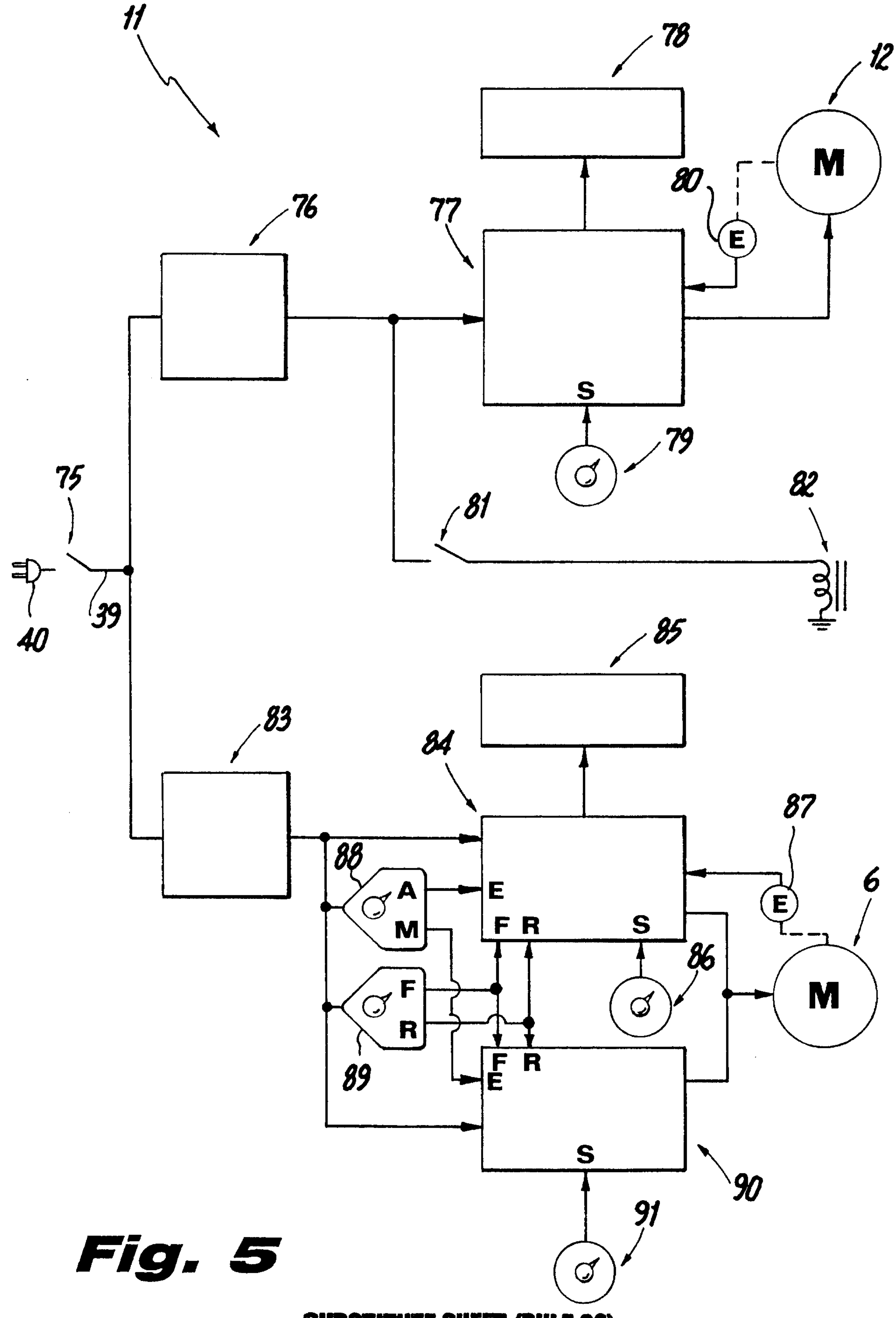
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Fig. 5

Fig. 6

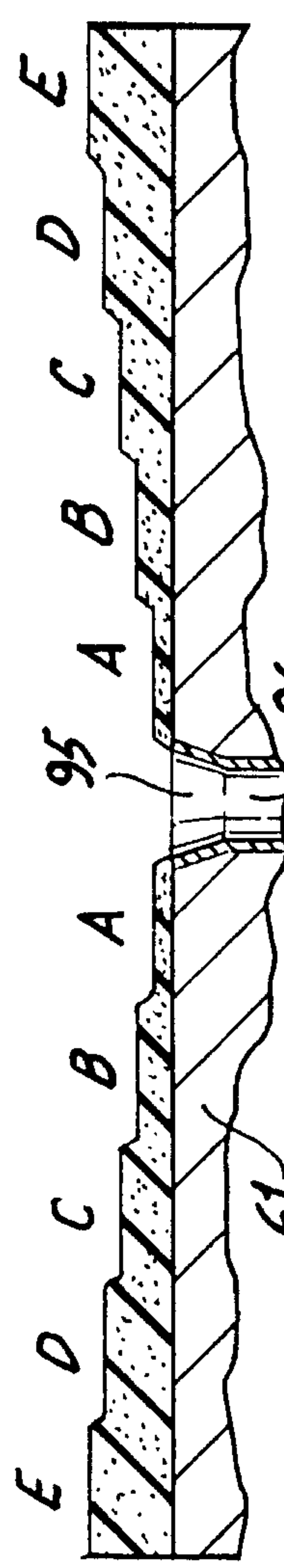
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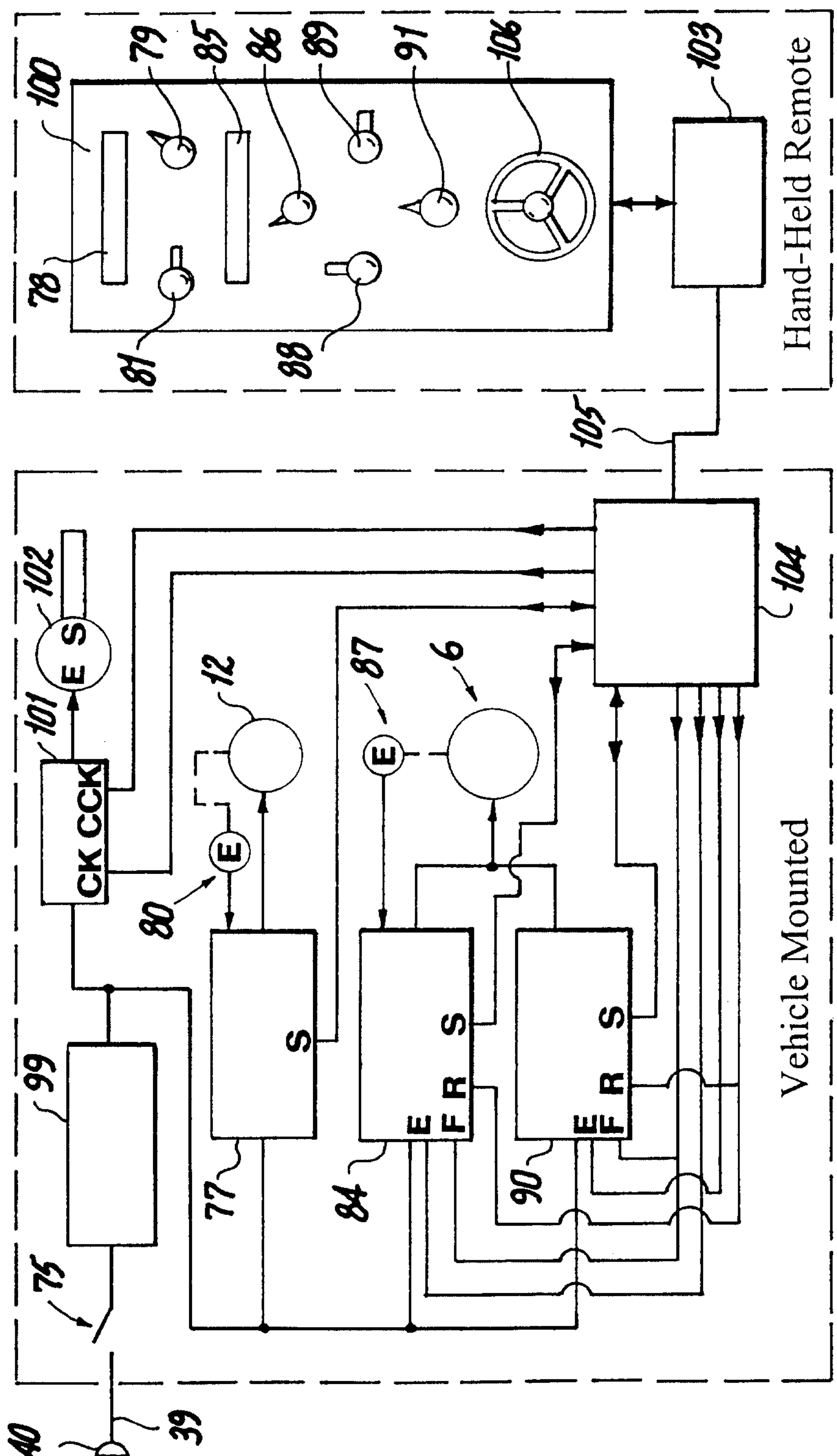
Fig. 7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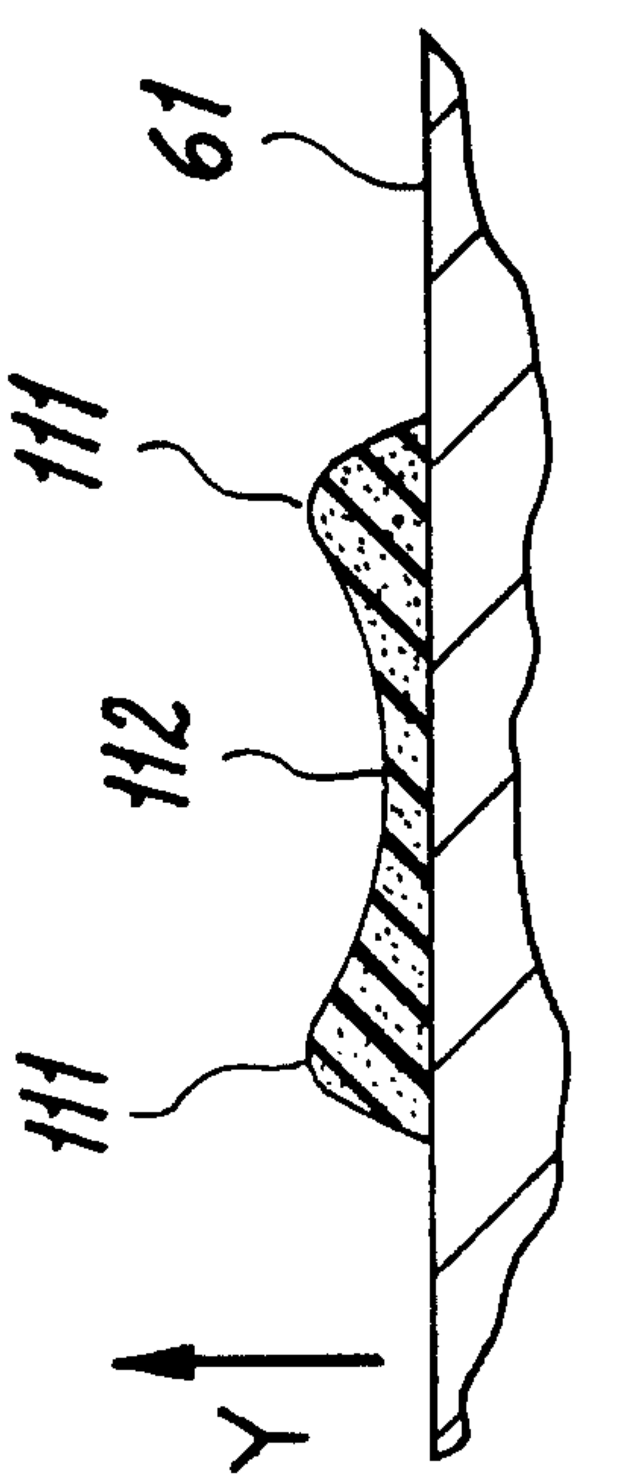

Fig. 8A

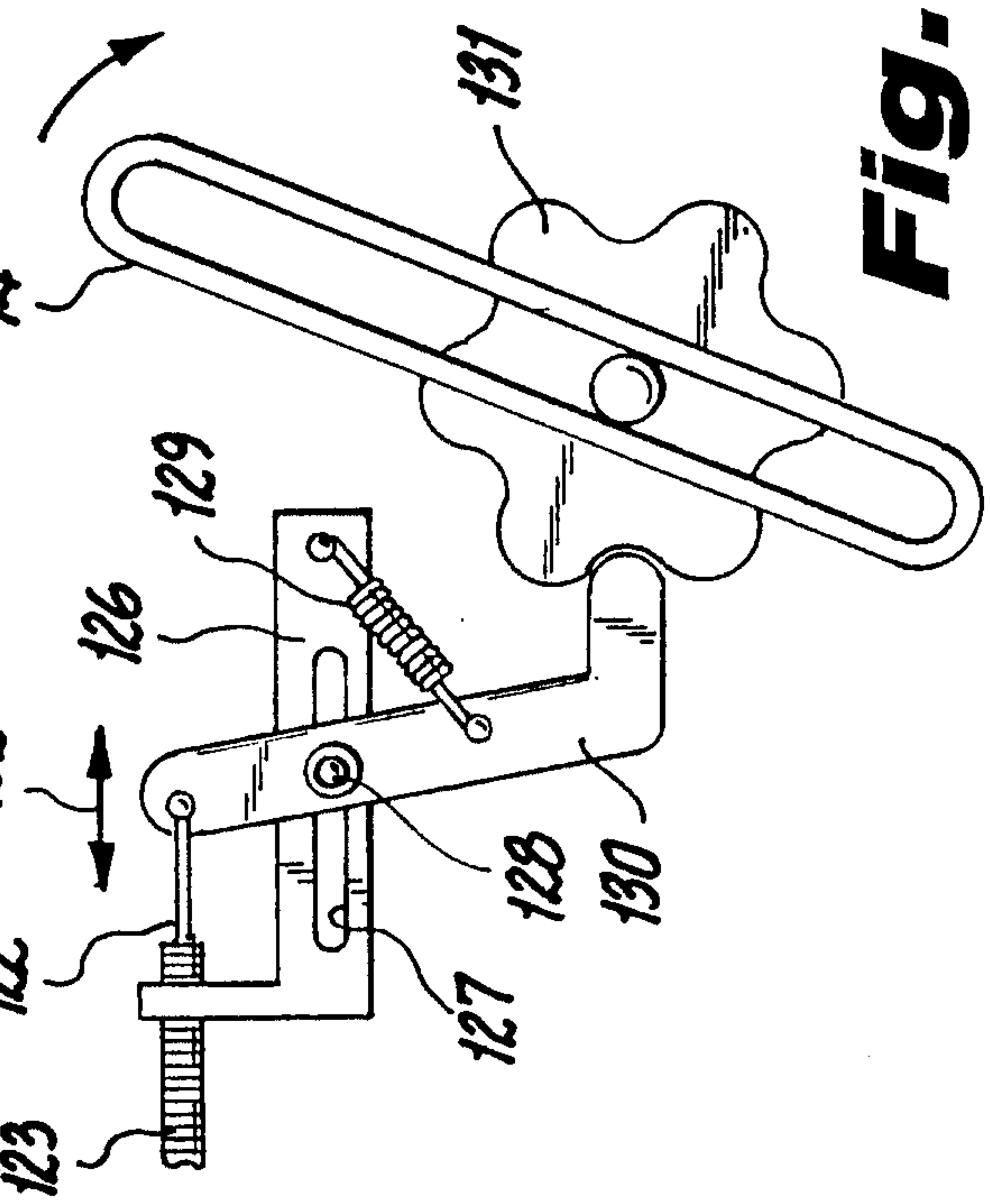

Fig. 9B

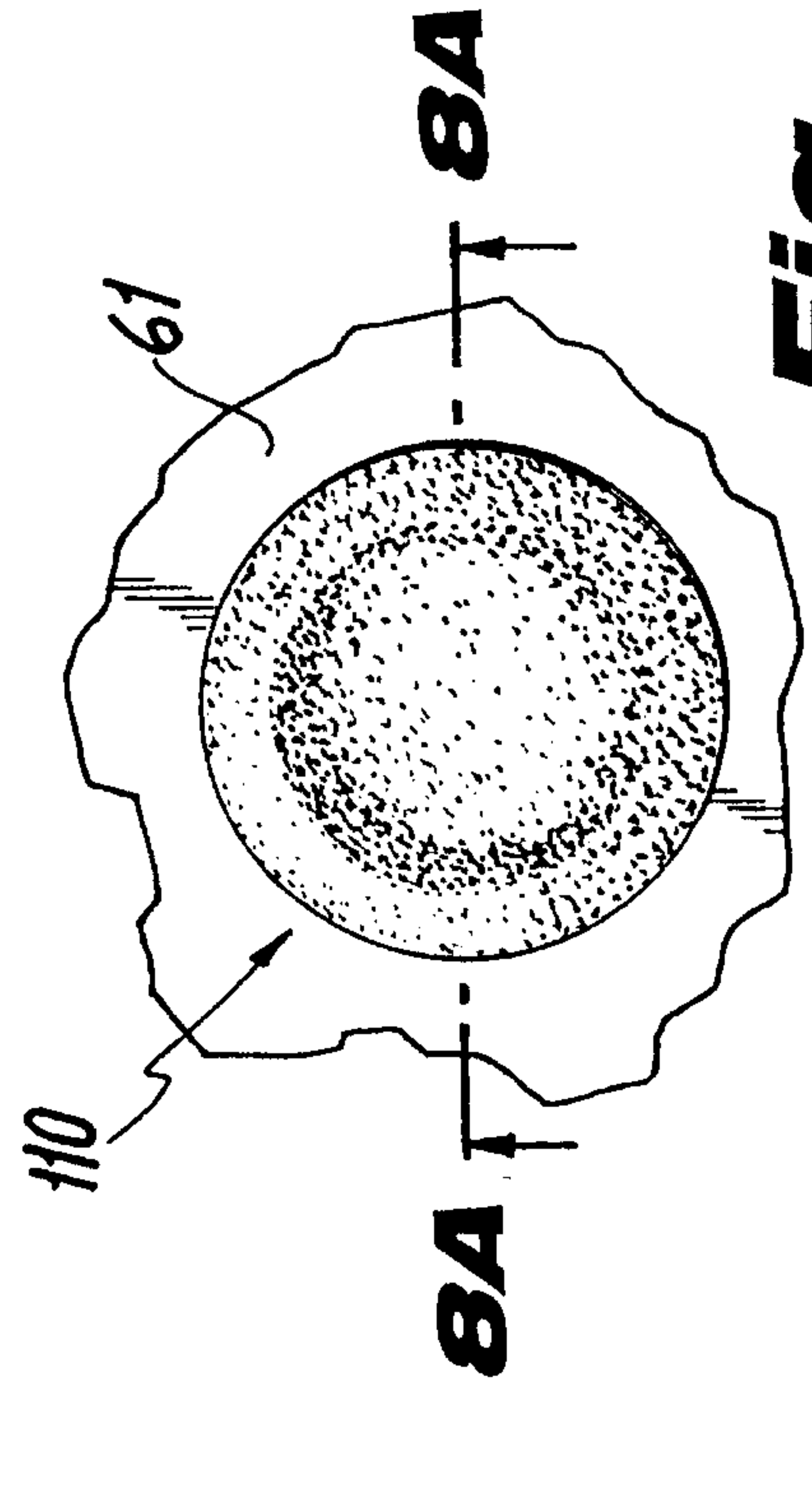

Fig. 8

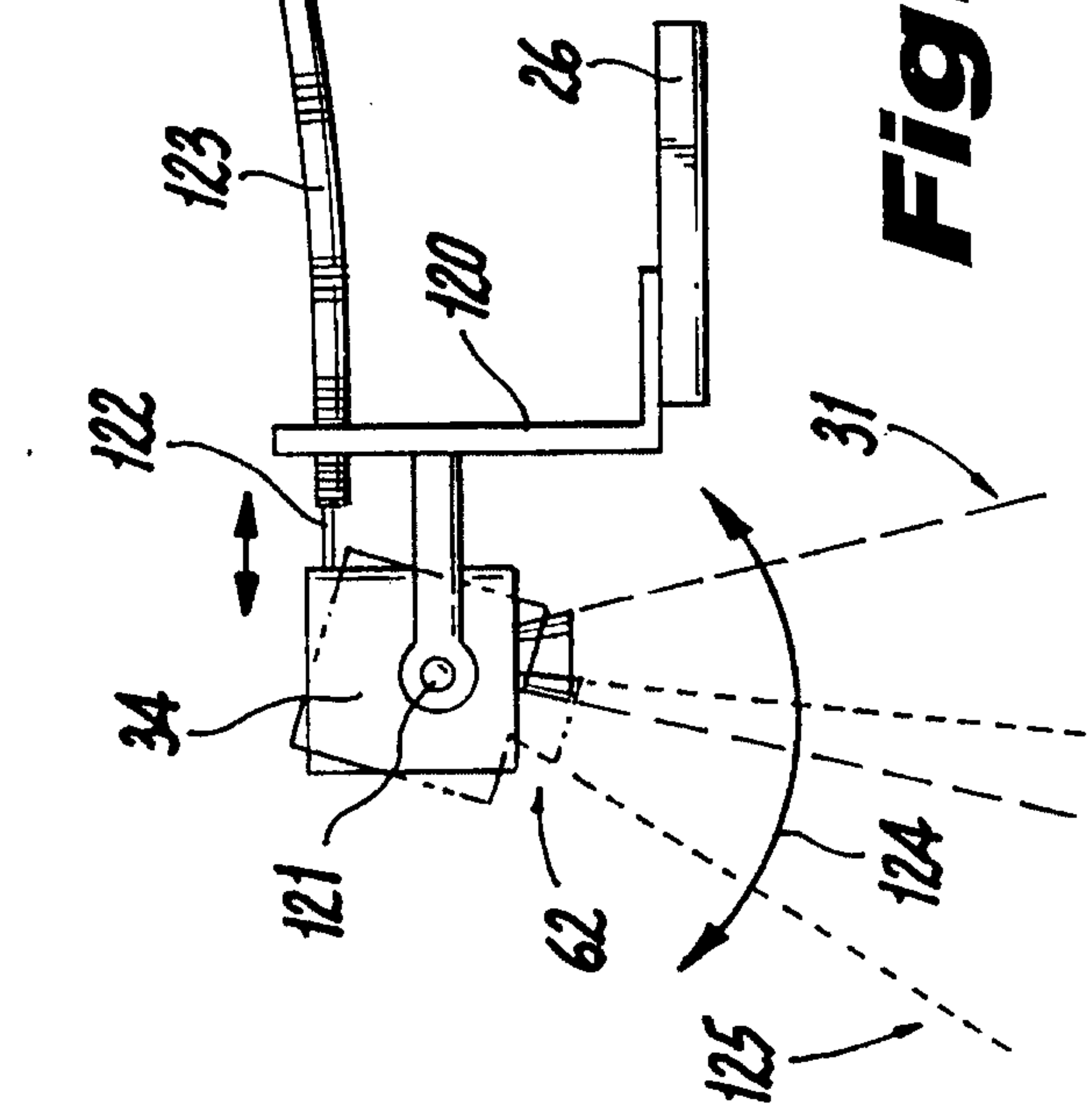

Fig. 9A

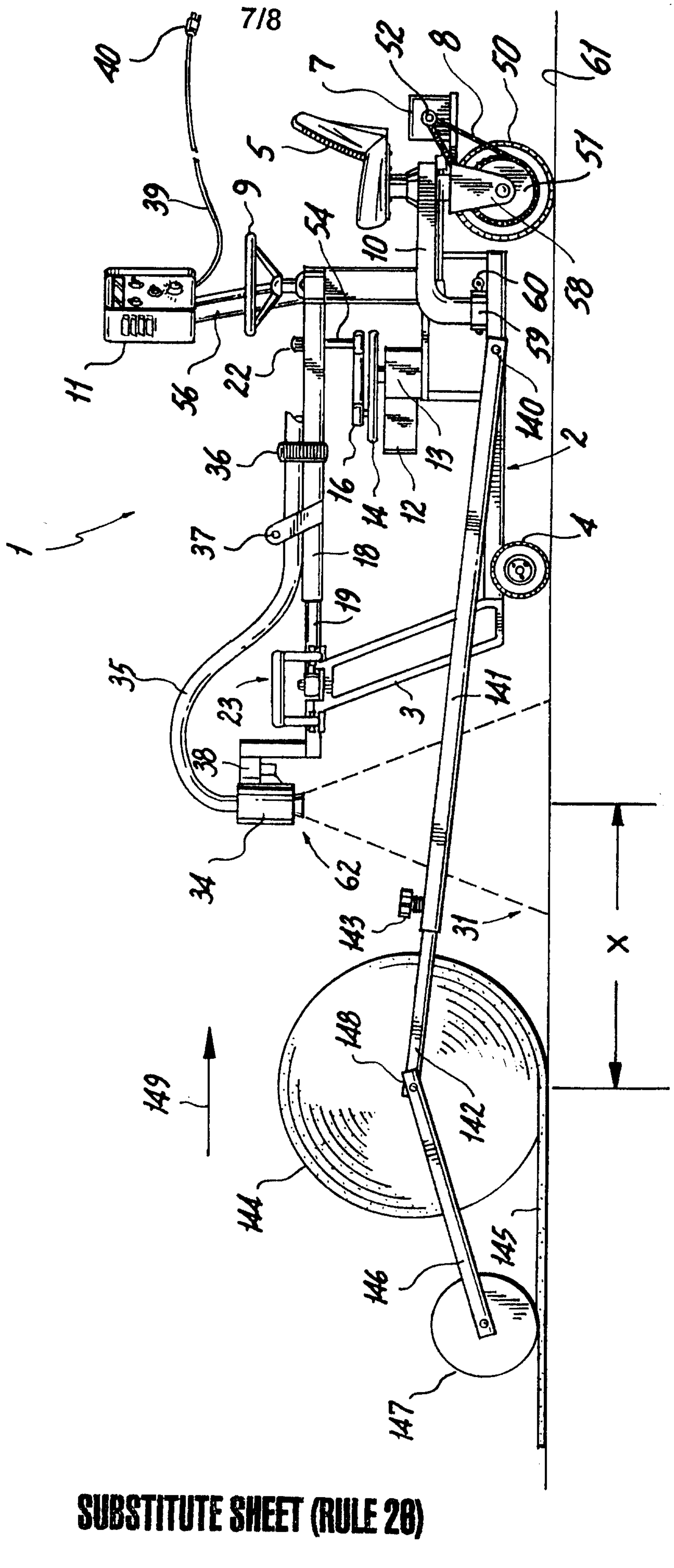
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Fig. 10

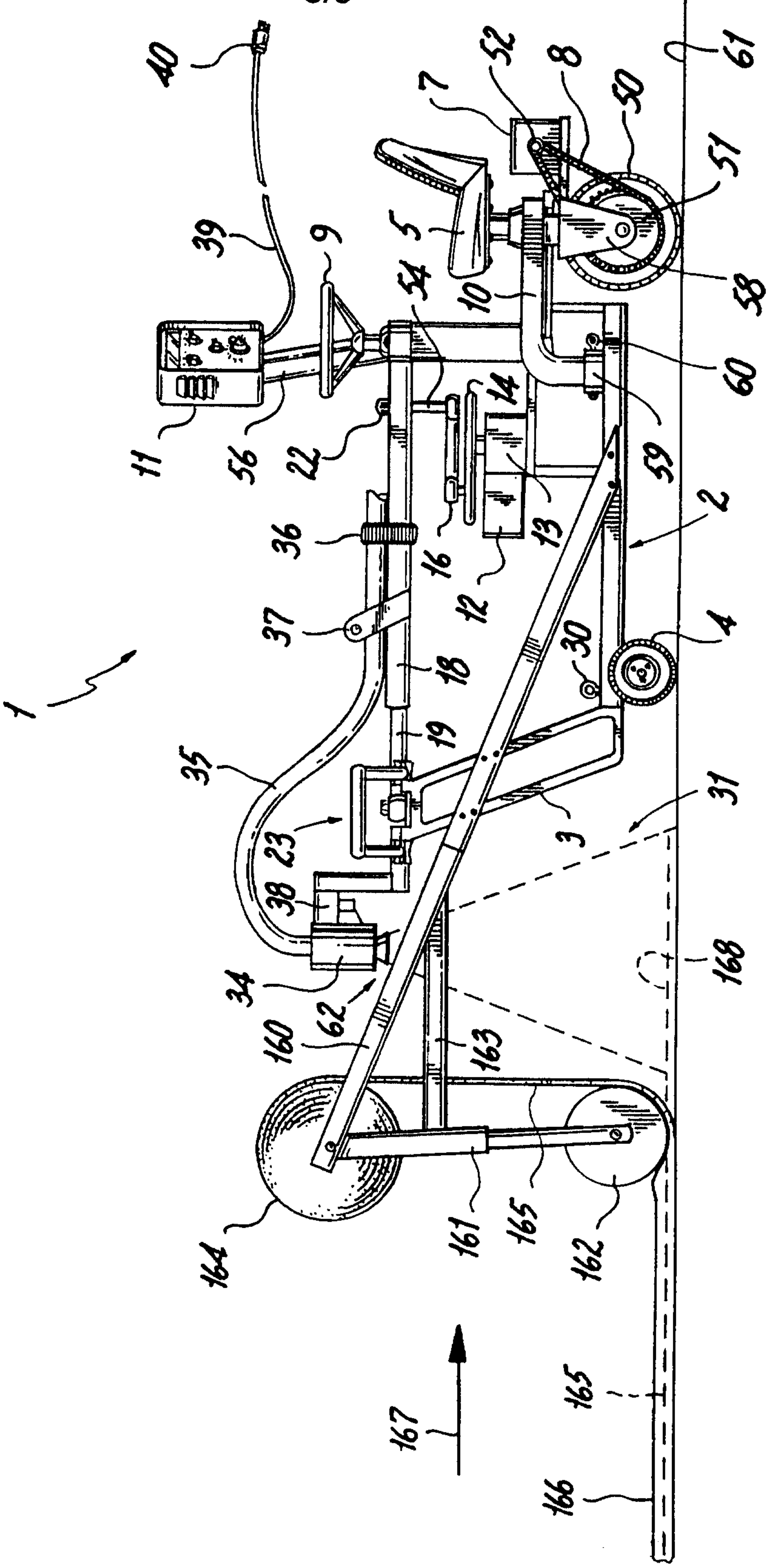
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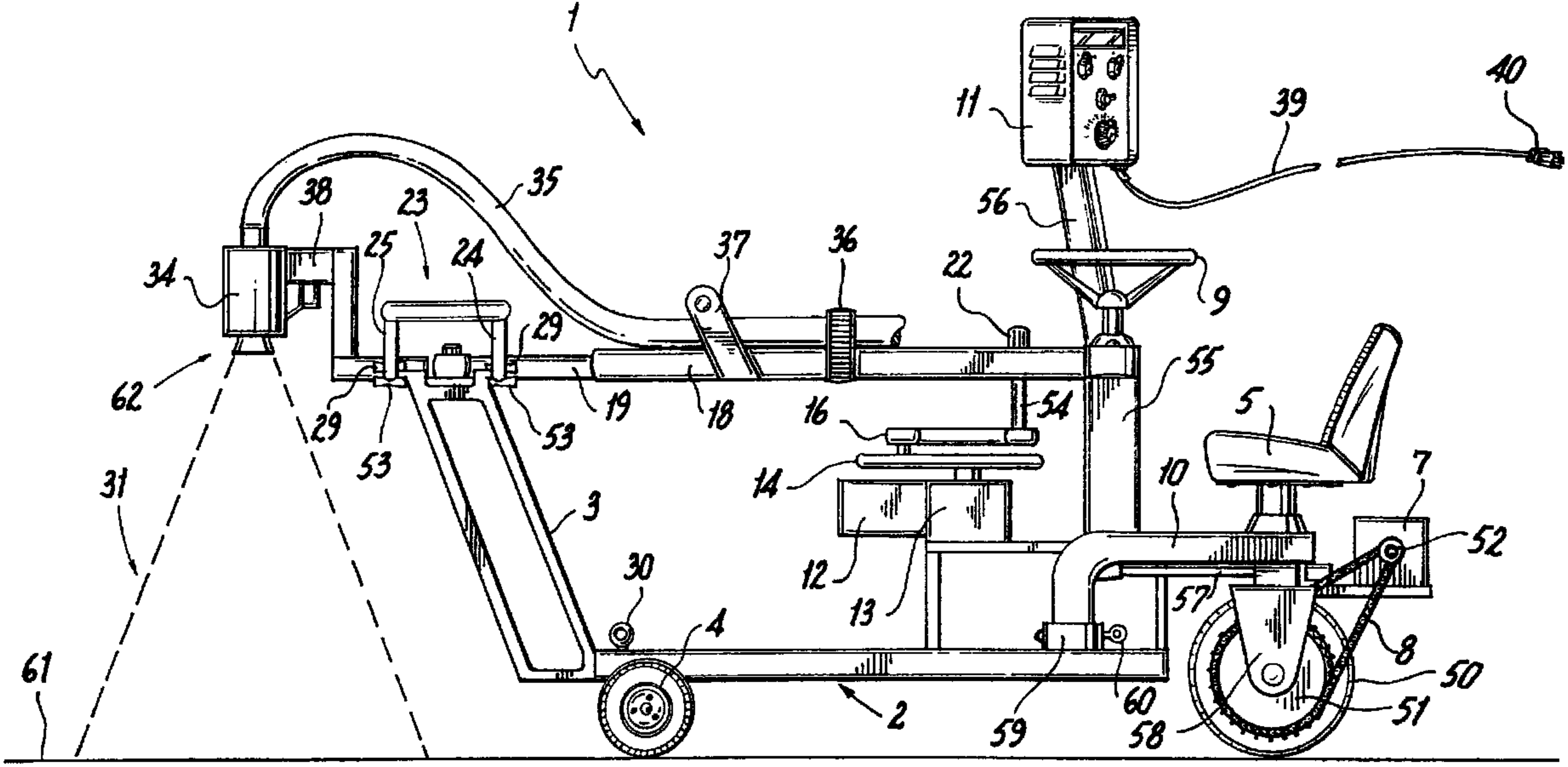
Fig. 11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