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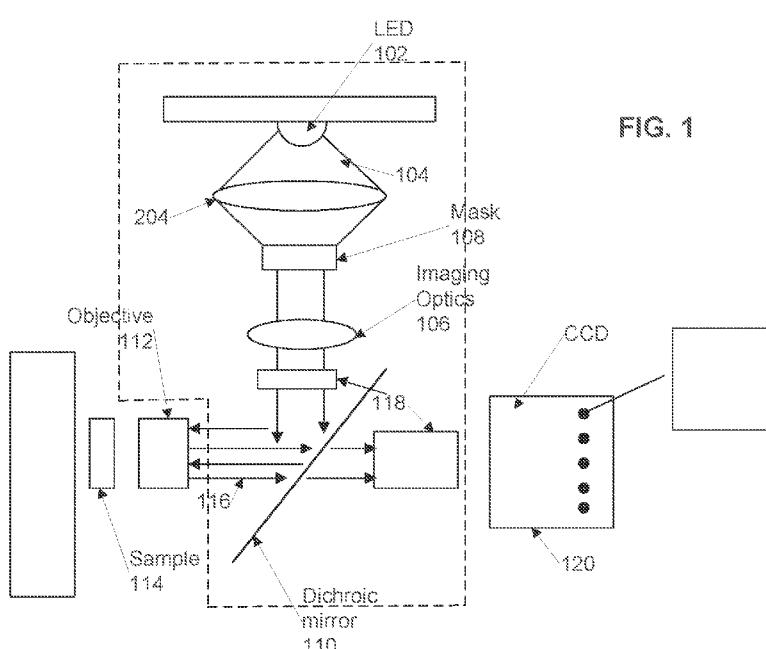


FIG. 1

(57) Abstract: A method for calibrating an imaging system, comprising: illuminating a sample through a pinhole mask using an excitation light; capturing an image of the sample using a sensor; converting the image into data; in a processing module: filtering the data using known spacing of pinholes in the pinhole mask to obtain data that corresponds to the spacing, using a threshold to identify regions of the remaining data that are bright enough to be associated with a pinhole, calculating the centroids of the regions, and fitting a known pattern for the pinhole mask to the regions in order to identify the best fit for the data; and storing, in a storage medium, the best fit data for use in a subsequent confocal capture routine.



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SYSTEMS AND METHODS FOR CALIBRATING A STRUCTURED
ILLUMINATION IMAGING SYSTEM AND FOR CAPTURING A STRUCTURED
ILLUMINATION IMAGE

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BACKGROUND

[0001] This application claims priority to U.S. application no. 62/169,675 filed June 2, 2015, which disclosure is herein incorporated by reference in its entirety.

Technical Field

10 [0002] The embodiments described herein are related to fluorescence imaging, and more particularly to generating a composite confocal image in a fluorescence imaging system, without the need for a pinhole mask in the emission path.

Related Art

15 [0003] A fluorescence microscope is a light microscope used to study properties of organic or inorganic substances using fluorescence instead of, or in addition to, reflection and absorption. The fluorescence microscope is based on the phenomenon that certain material emits energy detectable as visible light when irradiated with the light of a specific wavelength. The sample can either be fluorescing in its natural form (like chlorophyll) or it may be treated with a 20 fluorescing stain.

[0004] A basic widefield fluorescence microscope that is well known in the art includes a light source and several filters that correspond to a wavelength matching a fluorescence stain. An excitation filter is provided for selecting an excitation wavelength of light from the light source, and a dichroic beamsplitter 25 reflects light from the light source to illuminate the specimen. The illuminated light is separated from the much weaker emitted fluorescence with an emission filter. The fluorescing areas can be observed in the microscope and shine out against a dark background with high contrast.

30 [0005] A structured illumination imaging system uses much the same principle as the widefield imaging system described above, with the key that only a portion of the sample is illuminated at any one time. A large portion of the excitation light is blocked, while a pattern of unblocked illumination is swept over the entire sample such that each area of the sample receives approximately equal excitation light. Typically, multiple images are captured at discrete intervals in this process and

a single fully illuminated image is generated by an image processing algorithm which analyzes the discrete input images to construct a corresponding output image. This output image is superior to an image captured using simple widefield imaging techniques due to the reduction in light gathered from out of focus areas of the sample, resulting in improved signal to noise ratio, higher lateral and axial spatial resolution, or both.

5 [0006] A confocal imaging system is a type of structured illumination system. A confocal imaging system can be used to improve the signal to noise ratio or increase the optical resolution. In a confocal imaging system, the objective is to 10 image only the thin part of the sample that is in focus, rejecting all light from above and below the focus plane. This is in contrast to more basic wide-field imaging, where out-of-focus elements still appear as significant elements in the image.

15 [0007] Conventional confocal systems can be divided loosely into single-point confocal and multi-point confocal systems. In single-point confocal systems the illumination used to excite the dye is passed through a pinhole onto the sample, then the fluorescent emission from the sample is passed through another pinhole into a photodetector. The pinhole size and optics are designed to accept light back from only those photons emitted from the thin slice of the sample that is in focus.

20 [0008] The technique can only image one point. Accordingly, the beam or the sample must be scanned back and forth in two dimensions to construct a single 2D confocal image. The beam in such conventional systems is typically scanned over a fixed sample, which requires very fast, very accurate mirrors to be synchronized to the photodetector.

25 [0009] In a multi-point confocal system the operational principle is the same as above but multiple points are imaged in parallel. Typically a disk with a pattern of pinholes is spun such that the illumination is swept over the field of view during an exposure. An example spinning-disk confocal imaging system is illustrated in figure 7.

30 [0010] As can be seen in figure 7, light 802 from the light source is incident on a first disk 804 that includes a plurality of focusing lenses 806 that focus the light onto a pinhole mask 810 included in a second disk 808. Light 802 passing through pinhole mask 810 is then focused onto the specimen 814 via objective lens 812. The light 802 is absorbed by fluorophores, which causes them to emit light 816, which passes back through objective lens 812 and pinhole mask 810 and is incident on

mirror 818. Mirror 818 reflects the emitted light 816 onto a sensor 822, e.g., via optics 820, where it can be detected.

[0011] A system such as that illustrated in figure 7 can capture images faster than a single-point system but such a system also requires more complex 5 synchronization between pinholes and detectors.

[0012] Another issue with such conventional fluorescence imaging system is photobleaching. In such systems, viewing a sample causes the sample to become dimmer over time. This effect, known as photobleaching, is the result of the energy of the excitation light slowly damaging the molecules of the dye and consequently 10 reducing its fluorescent response. This effect is only evident in areas of the sample that have been exposed to excitation light and varies based on the duration and intensity of exposure. It is therefore possible for one area of the sample to be very dim (very photobleached) and another area to be very bright (not at all photobleached) even though there is no appreciable difference in the biology of the sample.

[0013] In structured illumination applications this effect can cause qualitative and quantitative problems. The basic concept of structured illumination is to light only a small portion of the sample at a time, then combine multiple partially lit views of the sample into one fully lit view with image processing software. This takes advantage of certain characteristics of light and optics to capture an image that would 20 not be possible with standard wide-field illumination. The sample is typically over-illuminated, so that more area than just the subset of the sample area being imaged at any one time is receiving light. This causes photobleaching in areas of the sample that may not yet have been imaged, so that when they are imaged the apparent brightness is less than it would have been had this area been imaged earlier in the 25 process. When the images are combined, this can cause strong artificial periodic trends in quantitative analysis and visually evident patterns in qualitative analysis.

[0014] There are several conventional ways of overcoming this problem. First, the capture settings can be changed as the capture process progresses in order to compensate for the lower brightness due to photobleaching. But this approach 30 requires all elements of the system to be very well quantified with respect to several variables and may need to be calibrated for the individual sample. Second, the brightness of individual images can be adjusted in post-processing to compensate for the decreasing brightness. Third, a more focused illumination source (such as a laser) can prevent much of the over-illumination that causes the extra photobleaching.

SUMMARY

5 [0015] Systems and methods for calibrating a fluorescence imaging system so that the system can be used to generate a structured illumination image without a pinhole mask in the emissions path are disclosed herein.

10 [0016] According to one aspect, a method for calibrating an imaging system comprises: illuminating a sample through a pinhole mask using an excitation light; capturing an image of the sample using a sensor; converting the image into data; in a processing module: filtering the data using known spacing of pinholes in the pinhole mask to obtain data that corresponds to the spacing, using a threshold to identify regions of the remaining data that are bright enough to be associated with a pinhole, calculating the centroids of the regions, and fitting a known pattern for the pinhole mask to the regions in order to identify the best fit for the data; and storing, in a storage medium, the best fit data for use in a subsequent confocal capture routine.

15 [0017] According to another aspect, a fluorescence imaging system comprises: an illumination source configured to illuminate a sample through a pinhole mask using an excitation light; a translation apparatus configured to move the pinhole mask or the sample to a first location; a sensor configured to capture an image of the sample at the first location and convert the image into data; an image processing 20 module configured to: filter the data using known spacing of pinholes in the pinhole mask to obtain data that corresponds to the spacing, use a threshold to identify regions of the remaining data that are bright enough to be associated with a pinhole, calculate the centroids of the regions, fit a known pattern for the pinhole mask to the regions in order to identify the best fit for the data; a storage medium configured to store the best 25 fit data; and a control module configured to use the best fit data to control the illumination source and the translation apparatus in order to obtain a plurality of images of the sample for use in a subsequent confocal capture routine.

30 [0018] According to another aspect, a method for capturing a composite confocal image obtained in a fluorescence imaging system comprises: illuminating a sample through a pinhole mask using an excitation light; moving the pinhole mask or the sample to a first location using a translation apparatus; capturing an image of the sample at the first location; convert the image into data; in an image processing module: filtering the data using known spacing of pinholes in the pinhole mask to obtain data that corresponds to the spacing, using a threshold to identify regions of the

remaining data that are bright enough to be associated with a pinhole, calculating the centroids of the regions, fitting a known pattern for the pinhole mask to the regions in order to identify the best fit for the data; storing in a storage medium the best fit data; and in a control module, using the best fit data to control the illumination source and the translation apparatus in order to obtain a plurality of images of the sample for use in a subsequent confocal capture routine.

5 [0019] These and other features, aspects, and embodiments are described below in the section entitled “Detailed Description.”

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BRIEF DESCRIPTION OF THE DRAWINGS

[0020] Features, aspects, and embodiments are described in conjunction with the attached drawings, in which:

15 [0021] Figure 1 is a diagram illustrating an example florescence imaging system configured in accordance with one embodiment;

[0022] Figure 2 is a diagram illustrating an example embodiment of a light cube implementation of at least some of the components of figure 1;

20 [0023] Figure 3 is a flow chart illustrating an example process for eliminating periodic artifacts such as those produced by photobleaching in images captured using the system of figure 1 in accordance with one embodiment;

[0024] Figure 4 is a diagram illustrating an example control system for controlling the operation of the illumination system of figure 1 in accordance with one embodiment;

25 [0025] Figure 5 is a diagram illustrating an example pinhole mask that can be used in the system of figure 1, and in particular in the light cube implementation of figure 2 in accordance with one embodiment;

[0026] Figure 6A illustrates an example wide-field image capture;

[0027] Figure 6B illustrates a corresponding pin-hole image capture;

[0028] Figures 6C and 6D illustrate a raster scanned confocal image capture;

30 [0029] Figures 6E and 6F illustrate a randomly scanned image capture performed in accordance with the process of figure;

[0030] Figure 7 is a diagram illustrating a conventional spinning-disk confocal imaging system;

[0031] Figure 8 is a block diagram illustrating an example wired or wireless system that can be used in connection with various embodiments described herein;

[0032] Figure 9 is a diagram illustrating an example translation apparatus that can be used with the system of figure 1, and in particular the light cube of figure 2 in 5 accordance with one embodiment;

[0033] Figure 10 is a diagram illustrating an example method for calibrating the system of figure 1 in order to eliminate the need for a emissions path pinhole mask in accordance with one embodiment;

[0034] Figure 11A shows the determined positions of the pinholes for an 10 image; and

[0035] Figure 11B shows a close-up of a portion of the image with the determined positions overlaid versus the raw data.

DETAILED DESCRIPTION

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[0036] In the embodiments described herein, systems and methods for producing a structured illumination image are disclosed. It will be understood that the embodiments described are by way of example only. Moreover, the figures are illustrative and intended to aid the description of the systems and methods disclosed.

20 Thus, the figures may not comprise all of the components, circuitry, elements, etc., needed to depict a complete system. Thus, the figures and the accompanying disclosure should not be viewed as limiting the embodiments to certain configurations, nor should they be viewed as foreclosing the inclusion of further components, etc., in the configurations disclosed, or of further configurations.

25 [0037] As noted above, a structured illumination system has certain advantages over a conventional widefield system. A confocal imaging system is a type of structured illumination system. A confocal imaging system can be used to increase the optical resolution and contrast and enable the reconstruction of three-dimensional structures from a series of obtained images. In a confocal imaging system, the objective is to image only the thin part of the sample that is in focus, 30 rejecting all light from above and below the focus plane. This is in contrast to more basic wide-field imaging, where out-of-focus elements still appear as significant elements in the image.

[0038] Conventional confocal systems can be divided loosely into single-point confocal and multi-point confocal systems. In single-point confocal systems the illumination used to excite the dye is passed through a pinhole onto the sample, then the fluorescent emission from the sample is passed through another pinhole into a photodetector, i.e., it is essentially a single pixel camera. The pinhole size and optics are designed to accept light back from only those photons emitted from the thin slice of the sample that is in focus.

[0039] The technique can only image one point, i.e., one pixel of an image, at a time. Accordingly, the beam or the sample must be scanned back and forth in two dimensions to construct a single 2D confocal image. The beam in such conventional systems is typically scanned over a fixed sample, which requires very fast, very accurate mirrors to be synchronized to the photodetector.

[0040] In a multi-point confocal system the operational principle is the same as above but multiple points are imaged in parallel. Typically a disk with a pattern of pinholes is spun such that the illumination is swept over the field of view during an exposure. An example spinning-disk confocal imaging system is illustrated in figure 7.

[0041] As can be seen in figure 7, light 802 from the light source is incident on a first disk 804 that includes a plurality of focusing lenses 806 that focus the light onto a pinhole mask 810 included in a second disk 808. Light 802 passing through pinhole mask 810 is then focused onto the specimen 814 via objective lens 812. The light 802 is absorbed by fluorophores, which causes them to emit light 816, which passes back through objective lens 812 and pinhole mask 810 and is incident on mirror 818. Mirror 818 reflects the emitted light 816 onto a sensor 822, e.g., via optics 820, where it can be detected.

[0042] A system such as that illustrated in figure 7 can capture images faster than a single-point system but such a system also requires more complex synchronization between pinholes and detectors.

[0043] Figure 1 is a diagram illustrating an example embodiment of a fluorescence imaging system 100 configured in accordance with the system and methods described herein. As can be seen, system 100 comprises a light source 104 configured to produce illumination light 104. The source 102 can for example be a Light Emitting Diode (LED) or a Laser, depending on the implementation. Pinhole optics 106 can then focus light 102 onto a pinhole mask 108. Light passing through

mask 108 is then incident on mirror 110, such as a dichroic mirror, which directs the light onto sample 114, e.g., via objective optics 112. The light 104 is absorbed by fluorophores, which causes them to emit light 116, which passes back through objective 112 and mirror 110 an onto sensor 120. A filter 118 can filter the emissions 5 prior the emissions being incident on sensor 120.

[0044] It should be noted that in certain embodiments, system 100 can include a pinhole mask in the path of light emissions 116 as in conventional systems; however, as explained in detail below, the emissions path pinhole mask can be eliminated in other embodiments.

10 [0045] Sensor 120 can, e.g., be a Charged Coupled Device (CCD) or CMOS device. Further, the pinhole mask can comprise a predictable pattern that can be defined by a coordinate system, such as a rectangular, square or cylindrical coordinate system. Thus, the mask can be moved in an x-y plane, e.g., as opposed to being rotated on a disk. Although, if a cylindrical coordinate system is used, then the mask 15 can still be spun. Figure 5 is a diagram illustrating an example mask 500 in accordance with one embodiment. As can be seen, mask 500 can comprise multiple pinhole masks, such as masks 501 and 502.

[0046] As illustrated in figure 2, the light source 102, imaging optics 106, mask 108, mirror 110 and filter 118 can be included in a very compact light cube 200. 20 The light cube can also include a circuit board 220 that can be configured to communicate with a control system and to control various aspects of the light cube 200. Thus, the mask 500 of figure 5 can be configured to be inserted into light cube 200.

[0047] As noted above, images captured via conventional systems, such as 25 disk-based raster scanning systems, can include periodic visual artifacts, e.g., such as those caused by photobleaching. While conventional methods for reducing these artifacts can be helpful, system 100 can be configured to reduce the effect of such artifacts by capturing the individual partially illuminated images in a random order each time.

30 [0048] Figure 3 is a flow chart illustrating an example process for eliminating periodic artifacts such as those produced by photobleaching. First, in step 305, an image control module 402, e.g., running on a control system 400 can determine the different physical locations that mask 106 must be located in order to properly construct a fully illuminated composite image. Normally, once these positions are

determined, the system 400 would then control the translation stage via translation control module(s) 406 to move in a linear fashion, i.e., it would move through each position in order and capture the images. Control module 402 would normally also determine capture settings for each position and control the illumination control 408 in order to capture the images using the capture settings.

[0049] But in the embodiment of figure 3, the control module 402 causes the translation stage to proceed to each one of the locations in a randomized order and capture the images in step 310. Further, the control module 402 can be configured to cause each image to be captured with the same capture settings each time. This allows for faster individual captures, since the camera or sensor and illumination control do not have to communicate with the control system 400 to confirm new settings before each capture.

[0050] Once the images have been captured in step 310, image processing module 404 can be used to generate the composite confocal image in step 315. The image processing module 404 can then be configured to differentiate signal from background information and measure the decrease in signal intensity at discrete steps in the capture process in step 320. A model, such as a curve that has been modeled to match the experimentally observed behavior of photobleaching, i.e., relative brightness as a function of time, can then be fit to the data points in step 325. From that curve, the brightness of all images in the sequence, except the first, can be adjusted in step 330 to eliminate some of the apparent effect of the photobleaching.

[0051] It should be noted that the composite image can be generated before or after the model is applied to the images and the brightness of various data points is adjusted.

[0052] It should also be noted that rigorously applying the process of figure 3 to all images can be computationally intensive and in certain instances would take too long given current processing power constraints. Thus, in certain embodiments, application of the model (step 325) can be applied to just a few images. Approximate correction of the brightness of the remaining images based on the application to a few images can then be performed as illustrated by optional step 335. For example, the model can be applied to an image at the beginning, middle and end of the order and then an exponential decay can be fit to these points. This modified process can result in a relatively quick acquisition of a good quality image.

[0053] Figure 4 is a diagram illustrating an example control system 400 for controlling the operation of illumination system 100. As can be seen, system 400 comprises an image authority 412. Image authority 412 can comprise all of the resources need to implement certain portions of the system sand methods described herein. Thus, authority 412 can comprise all of the hardware and software resources needed for those portions including one or more processors, including any signal processors, math co-processors, microcontrollers, etc., one or more servers, one or more routers, one or more terminals, one or more computers, including desk top or portable computers, and all the API's, programs, software modules, etc., needed to perform the those portions or aspects of the systems and methods described herein. Thus, a module such as those described herein can comprise the hardware and software resources needed to perform the specified function.

[0054] Specifically, authority 412 can comprise various modules configured to control the operation of system 100 and to process data obtained therefrom. As illustrated in figure 4, these modules can include an image control module 402, which can be configured to control the translation stages in system 100, e.g., via a translation control module 406. Control module 402 can also be configured to control the illumination via illumination control module 408.

[0055] Authority 410 can also comprise a processing module 404 configured to process the image data obtained by sensor 120.

[0056] It should be noted that some or all of translation control module 406 and illumination control module 408 can reside within system 100, e.g., within light cube 200 or within the translation stage to which cube 200 is interfaced.

[0057] Figures 6A and 6B illustrate an example wide-field image capture and a corresponding pin-hole image capture. As can be seen in figures 6C and D, a raster scanned confocal image can provide improved resolution and contrast; however, as illustrated in figures 6E and F, the randomly scanned image capture process of figure 3 can provide even better resolution and contrast in less time and with fewer processing resources.

[0058] As described above, the systems described herein are multi-point confocal systems. Instead of a spinning disk, as illustrated in figure 7, a pattern of pinholes is printed on a small, e.g., glass slide as illustrated in figure 5. This slide can be held in front of the excitation light source 102, e.g., as in the light cube configuration of figure 2. The mask is moved around using small translation stages

which position the mask in the appropriate location to illuminate a different part of the sample before each capture.

[0059] Figure 9 is a diagram illustrating an example configuration of the translation apparatus 900, including a plurality of translation stages 902a, b, and c as well as tip/tilt adjustment mechanism 904 in accordance with one embodiment. As can be seen, the translation stages 902 and the tip/tilt adjustment mechanism 904 can move and position the mask 108, e.g., under the control of control module 402 and translation control 406. This type of translation apparatus 900 in addition to the light cube 200 provides a simple and compact solution that allows for several different pinhole patterns, e.g., 501 and 502, to be printed on each slide. This allows for more flexibility, giving the user a choice between speed and quality.

[0060] Additionally, as noted above, in certain embodiments, the systems and methods described herein can be configured to eliminate the need for a pinhole mask on the emission path. Instead, the systems and methods described herein can be configured to use a high resolution sensor 120, such as a CCD or CMOS device, to virtually mask off the returned image, only recording data in the ‘good’ regions of the image. For system 100 to know the location of the good data, the locations of the pinholes 108 relative to the sensor 120 must be known. This is accomplished by taking a calibration image at the beginning of the confocal capture routine and using image processing, e.g., within processing module 404 to determine the location of the pinhole array 108 relative to the sensor 120. In this way the system is at least partially self-calibrating and can tolerate small errors in image-to-image system positioning, such as the position of a light cube 200, without significant loss of image quality.

[0061] In essence, the pinholes, i.e., the bright spots in the image of figure 11A, are identified and then the data from these locations are processed to generate a confocal image, while data outside these regions is ignored. The process that can be used to establish the location of the pinhole array relative to the camera sensor has several discrete steps as illustrated in figure 10. First, in step 1005, an image of the pinholes in the mask can be obtained. Then, in step 1010, various image processing techniques can be used to enhance the image of the mask to make it more suitable for quantitative analysis. Because the spacing of the pinholes is a known quantity, e.g., to processing module 404, a Fourier transform can be used to move the data into the frequency domain, in step 1015, where a bandpass filter can be used, in step 1020, to find data that corresponds with that spacing.

[0062] Noise can then be removed and brightness variation across the image accounted for in step 1025. For example and opening technique can be used in step 1025. The brightest data can then be selected in step 1030. For example, a histogram binning technique can be used to keep only the brightest of this data. At this point, 5 the pinholes in the enhanced image can be located in step 1035. For example, a threshold algorithm can be applied that identifies regions of signal that are bright enough to be considered pinholes. The centroids of these regions can then be calculated and stored for use in the next step.

[0063] Next, in step 1040, the known mask pattern can be fit to the observed 10 data, thereby relating the mask position to the sensor. For example, a Random Sample Consensus (RANSAC) method can be used to apply and test a variety of rotation, scale and offset factors to the known mask pattern against two centroids at a time. This iterative process can be parallelized to allow the testing of hundreds of possibilities in seconds or less. Once the best fit is determined, the mask pattern is 15 stored for use in the subsequent confocal capture routine.

[0064] Because the entire process of figure 10 can be completed in a matter of 20 seconds, while running on, e.g., a consumer grade computer it is possible and practical to run this calibration before each confocal capture. Further, since multiple pinholes are imaged at once, the system 100 can capture a high resolution image without the time penalty that would be incurred on a single-point system. Still further, compared to a spinning disk system the translating mask approach eliminates 25 the problems of blurring and vibration since the pinholes are stationary during image captures.

[0065] Figure 11A illustrated data captured for an image with the determined 25 pinholes overlaid, wherein the pinhole locations were determined using the process of figure 10. Figures 11B illustrates a close-up of the determined pinholes versus the raw data on the right.

[0066] Figure 8 is a block diagram illustrating an example wired or wireless 30 system 550 that can be used in connection with various embodiments described herein. For example the system 550 can be used as or in conjunction with one or more of the mechanisms or processes described above, and may represent components of system 100 or 400, the corresponding server(s), and/or other devices described herein. The system 550 can be a combination of one or more of the following: a server or any conventional personal computer, or any other processor-enabled device

that is capable of wired or wireless data communication. Other computer systems and/or architectures may be also used, as will be clear to those skilled in the art.

[0067] The system 550 preferably includes one or more processors, such as processor 560. Additional processors may be provided, such as an auxiliary processor 5 to manage input/output, an auxiliary processor to perform floating point mathematical operations, a special-purpose microprocessor having an architecture suitable for fast execution of signal processing algorithms (e.g., digital signal processor), a slave processor subordinate to the main processing system (e.g., back-end processor), an additional microprocessor or controller for dual or multiple processor systems, or a 10 coprocessor. Such auxiliary processors may be discrete processors or may be integrated with the processor 560. Examples of processors which may be used with system 550 include, without limitation, the Pentium® processor, Core i7® processor, and Xeon® processor, all of which are available from Intel Corporation of Santa Clara, California.

15 [0068] The processor 560 is preferably connected to a communication bus 555. The communication bus 555 may include a data channel for facilitating information transfer between storage and other peripheral components of the system 550. The communication bus 555 further may provide a set of signals used for communication with the processor 560, including a data bus, address bus, and control 20 bus (not shown). The communication bus 555 may comprise any standard or non-standard bus architecture such as, for example, bus architectures compliant with industry standard architecture (ISA), extended industry standard architecture (EISA), Micro Channel Architecture (MCA), peripheral component interconnect (PCI) local bus, or standards promulgated by the Institute of Electrical and Electronics Engineers 25 (IEEE) including IEEE 488 general-purpose interface bus (GPIB), IEEE 696/S-100, and the like.

[0069] System 550 preferably includes a main memory 565 and may also include a secondary memory 570. The main memory 565 provides storage of instructions and data for programs executing on the processor 560, such as one or 30 more of the functions and/or modules discussed above. It should be understood that programs stored in the memory and executed by processor 560 may be written and/or compiled according to any suitable language, including without limitation C/C++, Java, JavaScript, Pearl, Visual Basic, .NET, and the like. The main memory 565 is typically semiconductor-based memory such as dynamic random access memory

(DRAM) and/or static random access memory (SRAM). Other semiconductor-based memory types include, for example, synchronous dynamic random access memory (SDRAM), Rambus dynamic random access memory (RDRAM), ferroelectric random access memory (FRAM), and the like, including read only memory (ROM).

5 [0070] The secondary memory 570 may optionally include an internal memory 575 and/or a removable medium 580, for example a floppy disk drive, a magnetic tape drive, a compact disc (CD) drive, a digital versatile disc (DVD) drive, other optical drive, a flash memory drive, etc. The removable medium 580 is read from and/or written to in a well-known manner. Removable storage medium 580 may 10 be, for example, a floppy disk, magnetic tape, CD, DVD, SD card, etc.

[0071] The removable storage medium 580 is a non-transitory computer-readable medium having stored thereon computer executable code (i.e., software) and/or data. The computer software or data stored on the removable storage medium 580 is read into the system 550 for execution by the processor 560.

15 [0072] In alternative embodiments, secondary memory 570 may include other similar means for allowing computer programs or other data or instructions to be loaded into the system 550. Such means may include, for example, an external storage medium 595 and an interface 590. Examples of external storage medium 595 may include an external hard disk drive or an external optical drive, or an external 20 magneto-optical drive.

[0073] Other examples of secondary memory 570 may include semiconductor-based memory such as programmable read-only memory (PROM), erasable programmable read-only memory (EPROM), electrically erasable read-only memory (EEPROM), or flash memory (block oriented memory similar to EEPROM).

25 Also included are any other removable storage media 580 and communication interface 590, which allow software and data to be transferred from an external medium 595 to the system 550.

[0074] System 550 may include a communication interface 590. The communication interface 590 allows software and data to be transferred between 30 system 550 and external devices (e.g. printers), networks, or information sources. For example, computer software or executable code may be transferred to system 550 from a network server via communication interface 590. Examples of communication interface 590 include a built-in network adapter, network interface card (NIC), Personal Computer Memory Card International Association (PCMCIA) network card,

card bus network adapter, wireless network adapter, Universal Serial Bus (USB) network adapter, modem, a network interface card (NIC), a wireless data card, a communications port, an infrared interface, an IEEE 1394 fire-wire, or any other device capable of interfacing system 550 with a network or another computing device.

5 [0075] Communication interface 590 preferably implements industry promulgated protocol standards, such as Ethernet IEEE 802 standards, Fiber Channel, digital subscriber line (DSL), asynchronous digital subscriber line (ADSL), frame relay, asynchronous transfer mode (ATM), integrated digital services network (ISDN), personal communications services (PCS), transmission control 10 protocol/Internet protocol (TCP/IP), serial line Internet protocol/point to point protocol (SLIP/PPP), and so on, but may also implement customized or non-standard interface protocols as well.

15 [0076] Software and data transferred via communication interface 590 are generally in the form of electrical communication signals 605. These signals 605 are preferably provided to communication interface 590 via a communication channel 600. In one embodiment, the communication channel 600 may be a wired or wireless network, or any variety of other communication links. Communication channel 600 carries signals 605 and can be implemented using a variety of wired or wireless communication means including wire or cable, fiber optics, conventional phone line, 20 cellular phone link, wireless data communication link, radio frequency (“RF”) link, or infrared link, just to name a few.

25 [0077] Computer executable code (i.e., computer programs or software) is stored in the main memory 565 and/or the secondary memory 570. Computer programs can also be received via communication interface 590 and stored in the main memory 565 and/or the secondary memory 570. Such computer programs, when executed, enable the system 550 to perform the various functions of the present invention as previously described.

30 [0078] In this description, the term “computer readable medium” is used to refer to any non-transitory computer readable storage media used to provide computer executable code (e.g., software and computer programs) to the system 550. Examples of these media include main memory 565, secondary memory 570 (including internal memory 575, removable medium 580, and external storage medium 595), and any peripheral device communicatively coupled with communication interface 590 (including a network information server or other network device). These non-

transitory computer readable mediums are means for providing executable code, programming instructions, and software to the system 550.

[0079] In an embodiment that is implemented using software, the software may be stored on a computer readable medium and loaded into the system 550 by way of removable medium 580, I/O interface 585, or communication interface 590. In such an embodiment, the software is loaded into the system 550 in the form of electrical communication signals 605. The software, when executed by the processor 560, preferably causes the processor 560 to perform the inventive features and functions previously described herein.

10 [0080] In an embodiment, I/O interface 585 provides an interface between one or more components of system 550 and one or more input and/or output devices. Example input devices include, without limitation, keyboards, touch screens or other touch-sensitive devices, biometric sensing devices, computer mice, trackballs, pen-based pointing devices, and the like. Examples of output devices include, without 15 limitation, cathode ray tubes (CRTs), plasma displays, light-emitting diode (LED) displays, liquid crystal displays (LCDs), printers, vacuum fluorescent displays (VFDs), surface-conduction electron-emitter displays (SEDs), field emission displays (FEDs), and the like.

20 [0081] The system 550 also includes optional wireless communication components that facilitate wireless communication over a voice and over a data network. The wireless communication components comprise an antenna system 610, a radio system 615 and a baseband system 620. In the system 550, radio frequency (RF) signals are transmitted and received over the air by the antenna system 610 under the management of the radio system 615.

25 [0082] In one embodiment, the antenna system 610 may comprise one or more antennae and one or more multiplexors (not shown) that perform a switching function to provide the antenna system 610 with transmit and receive signal paths. In the receive path, received RF signals can be coupled from a multiplexor to a low noise amplifier (not shown) that amplifies the received RF signal and sends the amplified 30 signal to the radio system 615.

[0083] In alternative embodiments, the radio system 615 may comprise one or more radios that are configured to communicate over various frequencies. In one embodiment, the radio system 615 may combine a demodulator (not shown) and modulator (not shown) in one integrated circuit (IC). The demodulator and modulator

can also be separate components. In the incoming path, the demodulator strips away the RF carrier signal leaving a baseband receive audio signal, which is sent from the radio system 615 to the baseband system 620.

[0084] If the received signal contains audio information, then baseband system 620 decodes the signal and converts it to an analog signal. Then the signal is amplified and sent to a speaker. The baseband system 620 also receives analog audio signals from a microphone. These analog audio signals are converted to digital signals and encoded by the baseband system 620. The baseband system 620 also codes the digital signals for transmission and generates a baseband transmit audio signal that is routed to the modulator portion of the radio system 615. The modulator mixes the baseband transmit audio signal with an RF carrier signal generating an RF transmit signal that is routed to the antenna system and may pass through a power amplifier (not shown). The power amplifier amplifies the RF transmit signal and routes it to the antenna system 610 where the signal is switched to the antenna port for transmission.

[0085] The baseband system 620 is also communicatively coupled with the processor 560. The central processing unit 560 has access to data storage areas 565 and 570. The central processing unit 560 is preferably configured to execute instructions (i.e., computer programs or software) that can be stored in the memory 565 or the secondary memory 570. Computer programs can also be received from the baseband processor 610 and stored in the data storage area 565 or in secondary memory 570, or executed upon receipt. Such computer programs, when executed, enable the system 550 to perform the various functions of the present invention as previously described. For example, data storage areas 565 may include various software modules (not shown).

[0086] Various embodiments may also be implemented primarily in hardware using, for example, components such as application specific integrated circuits (ASICs), or field programmable gate arrays (FPGAs). Implementation of a hardware state machine capable of performing the functions described herein will also be apparent to those skilled in the relevant art. Various embodiments may also be implemented using a combination of both hardware and software.

[0087] Furthermore, those of skill in the art will appreciate that the various illustrative logical blocks, modules, circuits, and method steps described in connection with the above described figures and the embodiments disclosed herein

can often be implemented as electronic hardware, computer software, or combinations of both. To clearly illustrate this interchangeability of hardware and software, various illustrative components, blocks, modules, circuits, and steps have been described above generally in terms of their functionality. Whether such functionality is 5 implemented as hardware or software depends upon the particular application and design constraints imposed on the overall system. Skilled persons can implement the described functionality in varying ways for each particular application, but such implementation decisions should not be interpreted as causing a departure from the scope of the invention. In addition, the grouping of functions within a module, block, 10 circuit or step is for ease of description. Specific functions or steps can be moved from one module, block or circuit to another.

[0088] Moreover, the various illustrative logical blocks, modules, functions, and methods described in connection with the embodiments disclosed herein can be implemented or performed with a general purpose processor, a digital signal processor 15 (DSP), an ASIC, FPGA or other programmable logic device, discrete gate or transistor logic, discrete hardware components, or any combination thereof designed to perform the functions described herein. A general-purpose processor can be a microprocessor, but in the alternative, the processor can be any processor, controller, microcontroller, or state machine. A processor can also be implemented as a 20 combination of computing devices, for example, a combination of a DSP and a microprocessor, a plurality of microprocessors, one or more microprocessors in conjunction with a DSP core, or any other such configuration.

[0089] Additionally, the steps of a method or algorithm described in connection with the embodiments disclosed herein can be embodied directly in 25 hardware, in a software module executed by a processor, or in a combination of the two. A software module can reside in RAM memory, flash memory, ROM memory, EPROM memory, EEPROM memory, registers, hard disk, a removable disk, a CD-ROM, or any other form of storage medium including a network storage medium. An exemplary storage medium can be coupled to the processor such that the processor 30 can read information from, and write information to, the storage medium. In the alternative, the storage medium can be integral to the processor. The processor and the storage medium can also reside in an ASIC.

[0090] Any of the software components described herein may take a variety of forms. For example, a component may be a stand-alone software package, or it may

be a software package incorporated as a "tool" in a larger software product. It may be downloadable from a network, for example, a website, as a stand-alone product or as an add-in package for installation in an existing software application. It may also be available as a client-server software application, as a web-enabled software 5 application, and/or as a mobile application.

[0091] While certain embodiments have been described above, it will be understood that the embodiments described are by way of example only. Accordingly, the systems and methods described herein should not be limited based on the described embodiments. Rather, the systems and methods described herein 10 should only be limited in light of the claims that follow when taken in conjunction with the above description and accompanying drawings.

CLAIMS

1. A method for calibrating an imaging system, comprising:

illuminating a sample through a pinhole mask using an excitation light;

capturing an image of the sample using a sensor;

converting the image into data;

in a processing module:

filtering the data using known spacing of pinholes in the pinhole mask to obtain data that corresponds to the spacing,

using a threshold to identify regions of the remaining data that are bright enough to be associated with a pinhole,

calculating the centroids of the regions, and

fitting a known pattern for the pinhole mask to the regions in order to identify the best fit for the data with respect to the locations of the pinholes, and

storing, in a storage medium, the best fit data for use in a subsequent confocal capture routine.

2. The method of claim 1, further comprising, in the processing module, enhancing the data corresponding to the captured image.

3. The method of claim 2, wherein enhancing the data comprises boosting the sharpness and contrast of the data.

4. The method of claim 1, wherein filtering the data comprises transforming the data to the frequency domain and applying a bandpass filter to the transformed data.

5. The method of claim 1, further comprising, in the processing module, removing noise and accounting for brightness variation in the filtered data.

6. The method of claim 5, further comprising, in the processing module, keeping only the data in the filtered data that exceeds a brightness threshold.

7. The method of claim 6, wherein a histogram binning technique is used to identify data that exceeds the brightness threshold.

8. The method of claim 1, further comprising, in the processing module, applying at least one of rotation, scale and offset factors to pairs of centroids in an iterative process to aid in identifying the best fit.

9. The method of claim 1, further comprising using the best fit data for the location of the pinholes to obtain a confocal composite image of the sample, by processing data associated with the location of the pinholes and ignoring data not associated with the location of the pinholes.

10. A fluorescence imaging system, comprising:
an illumination source configured to illuminate a sample through a pinhole mask using an excitation light;
a translation apparatus configured to move the pinhole mask or the sample to a first location;
a sensor configured to capture an image of the sample at the first location and convert the image into data;
an image processing module configured to:
filter the data using known spacing of pinholes in the pinhole mask to obtain data that corresponds to the spacing,
use a threshold to identify regions of the remaining data that are bright enough to be associated with a pinhole,
calculate the centroids of the regions,
fit a known pattern for the pinhole mask to the regions in order to identify the best fit for the data with respect to the locations of the pinholes;
a storage medium configured to store the best fit data; and
a control module configured to control the illumination source and the translation apparatus in order to obtain a plurality of images of the sample for use in a subsequent confocal capture routine.

11. The system of claim 10, wherein the image processing module is further configured to enhance the data corresponding to the captured image.

12. The system of claim 11, wherein enhancing the data comprises boosting the sharpness and contrast of the data.

13. The system of claim 10, wherein filtering the data comprises transforming the data to the frequency domain and applying a bandpass filter to the transformed data.

14. The system of claim 10, wherein the image processing module is further configured to remove noise and account for brightness variation in the filtered data.

15. The system of claim 14, wherein the image processing module is further configured to keep only the data that exceeds a brightness threshold.

16. The system of claim 15, wherein the image processing module is further configured to apply a histogram binning technique to identify data that exceeds the brightness threshold.

17. The system of claim 10, wherein the image processing module is further configured to apply at least one of rotation, scale and offset factors to pairs of centroids in an iterative process to aid in identifying the best fit.

18. The system of claim 10, wherein the image processing module is further configured to use the best fit data for the location of the pinholes to obtain a confocal composite image of the sample, by processing data associated with the location of the pinholes and ignoring data not associated with the location of the pinholes.

19. The system of claim 10, wherein the sensor comprises a Charged Coupled Device (CCD) or a CMOS device.

20. The system of claim 10, wherein the imaging processing module is further configured to generate a composite, confocal image using the plurality of images and the best fit data.

21. The system of claim 10, wherein the pinhole mask is a rectangular, square, or cylindrical mask.

22. A method for capturing a composite confocal image obtained in a fluorescence imaging system, comprising:

illuminating a sample through a pinhole mask using an excitation light;

moving the pinhole mask or the sample to a first location using a translation apparatus;

capturing an image of the sample at the first location;

convert the image into data;

in an image processing module:

filtering the data using known spacing of pinholes in the pinhole mask to obtain data that corresponds to the spacing,

using a threshold to identify regions of the remaining data that are bright enough to be associated with a pinhole,

calculating the centroids of the regions,

fitting a known pattern for the pinhole mask to the regions in order to identify the best fit for the data with respect to locations of the pinholes;

storing in a storage medium the best fit data; and

in a control module, controlling the illumination source and the translation apparatus in order to obtain a plurality of images of the sample for use in a subsequent confocal capture routine.

23. The method of claim 22, further comprising, in the image processing module, enhancing the data corresponding to the captured image.

24. The method of claim 23, wherein enhancing the data comprises boosting the sharpness and contrast of the data.

25. The method of claim 22, wherein filtering the data comprises transforming the data to the frequency domain and applying a bandpass filter to the transformed data.

26. The method of claim 22, further comprising, in the image processing module, removing noise and accounting for brightness variation in the filtered data.

27. The method of claim 22, further comprising, in the image processing module, keeping only the data that exceeds a brightness threshold.

28. The method of claim 22, further comprising, in the image processing module, applying a histogram binning technique to identify data that exceeds the brightness threshold.

29. The method of claim 22, further comprising, in the image processing module, applying at least one of rotation, scale and

offset factors to pairs of centroids in an iterative process to aid in identifying the best fit.

30. The method of claim 22, further comprising, in the image processing module, using the best fit data for the location of the pinholes to obtain a confocal composite image of the sample, by processing data associated with the location of the pinholes and ignoring data not associated with the location of the pinholes.

31. The method of claim 22, further comprising, in the image processing module, generating a composite, confocal image using the plurality of images and the best fit data.

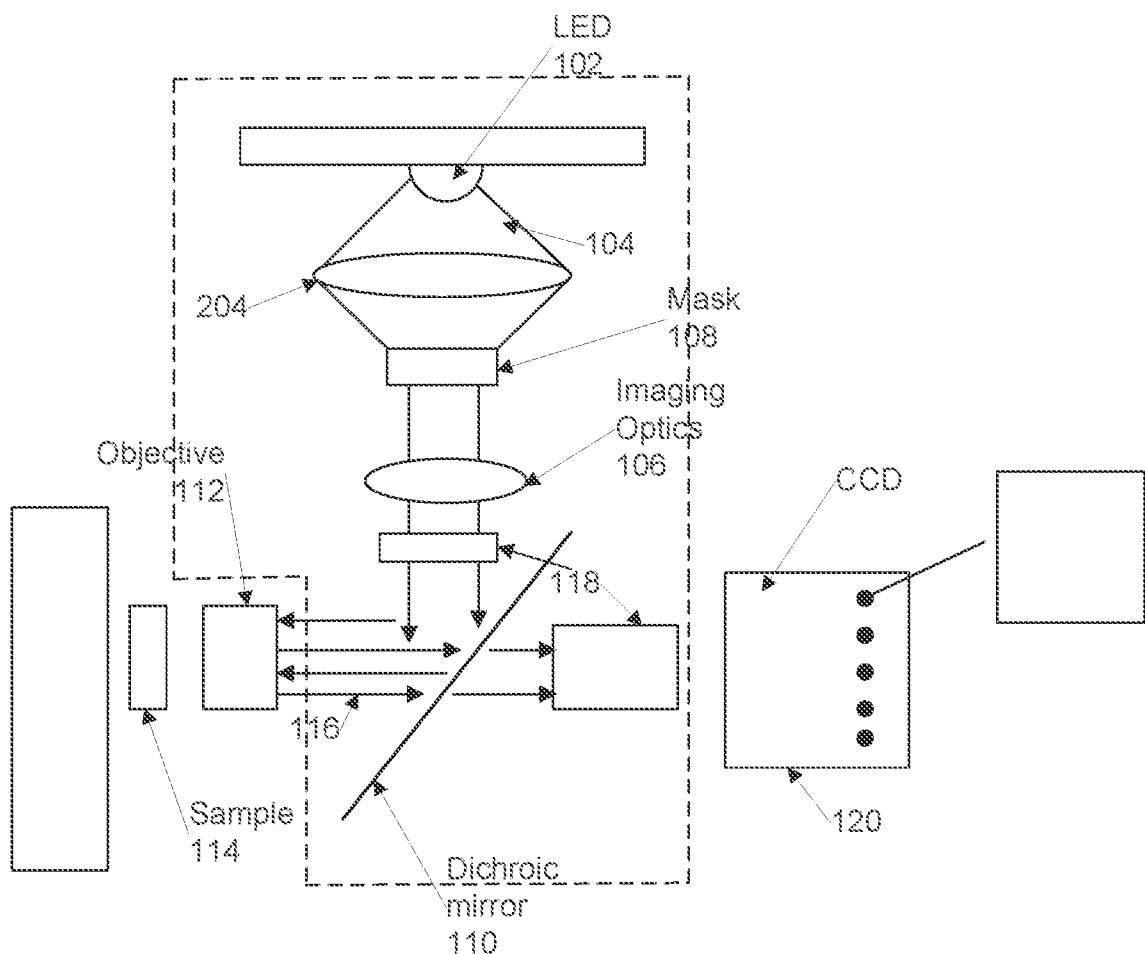


FIG. 1

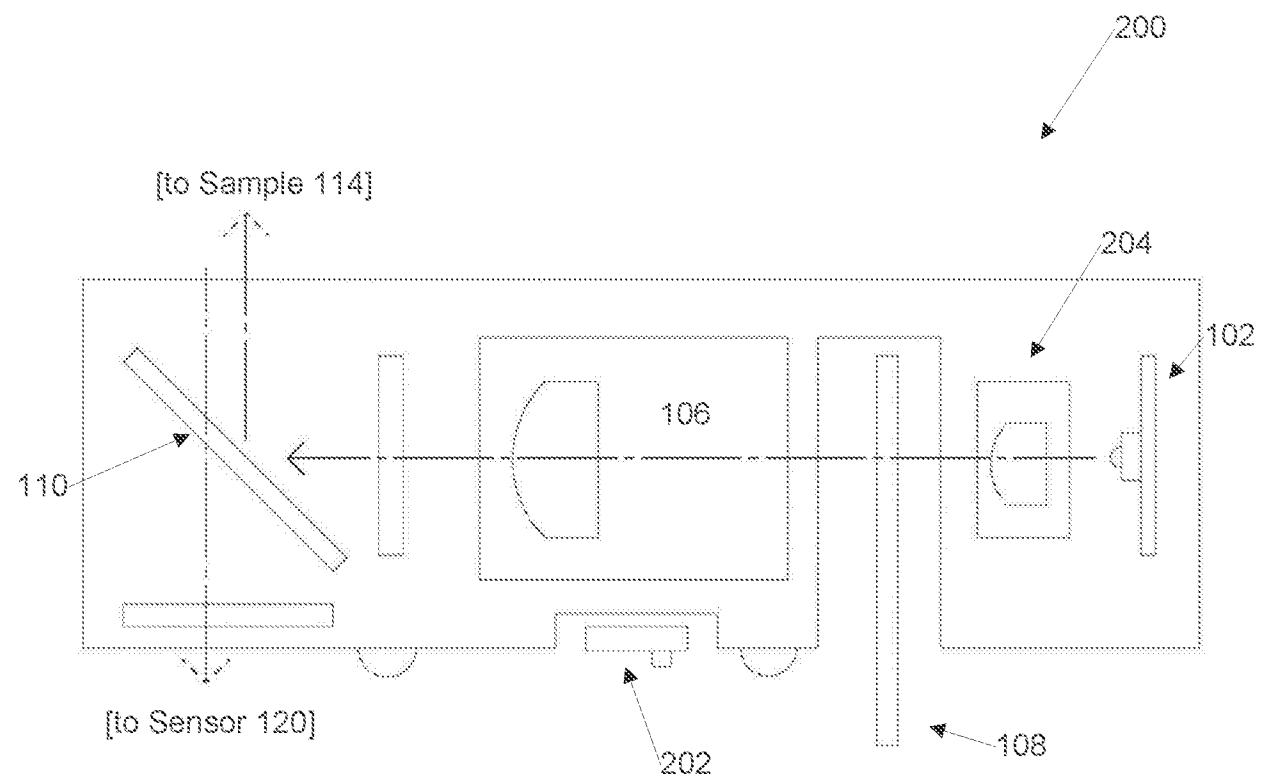


FIG. 2

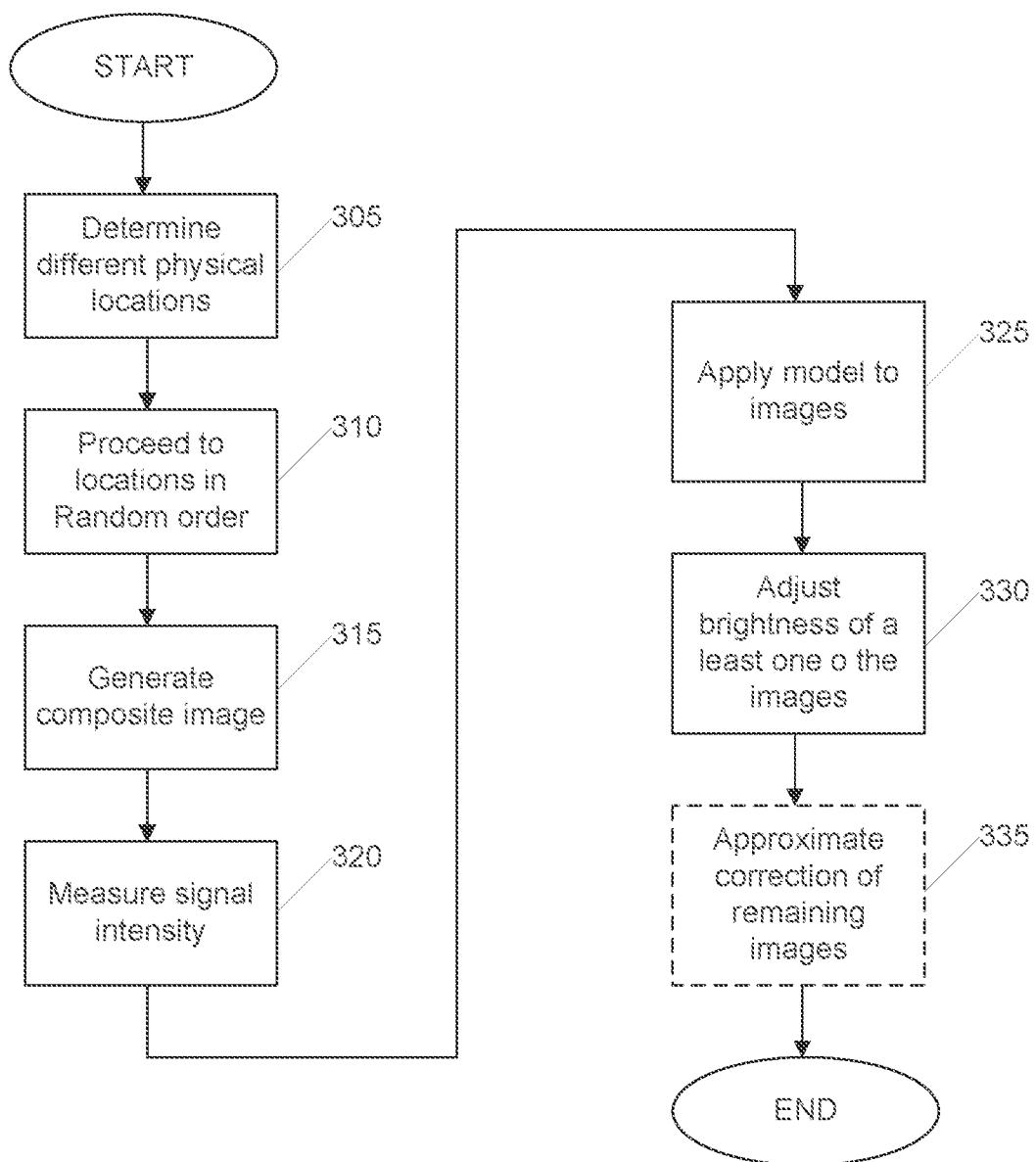


FIG. 3

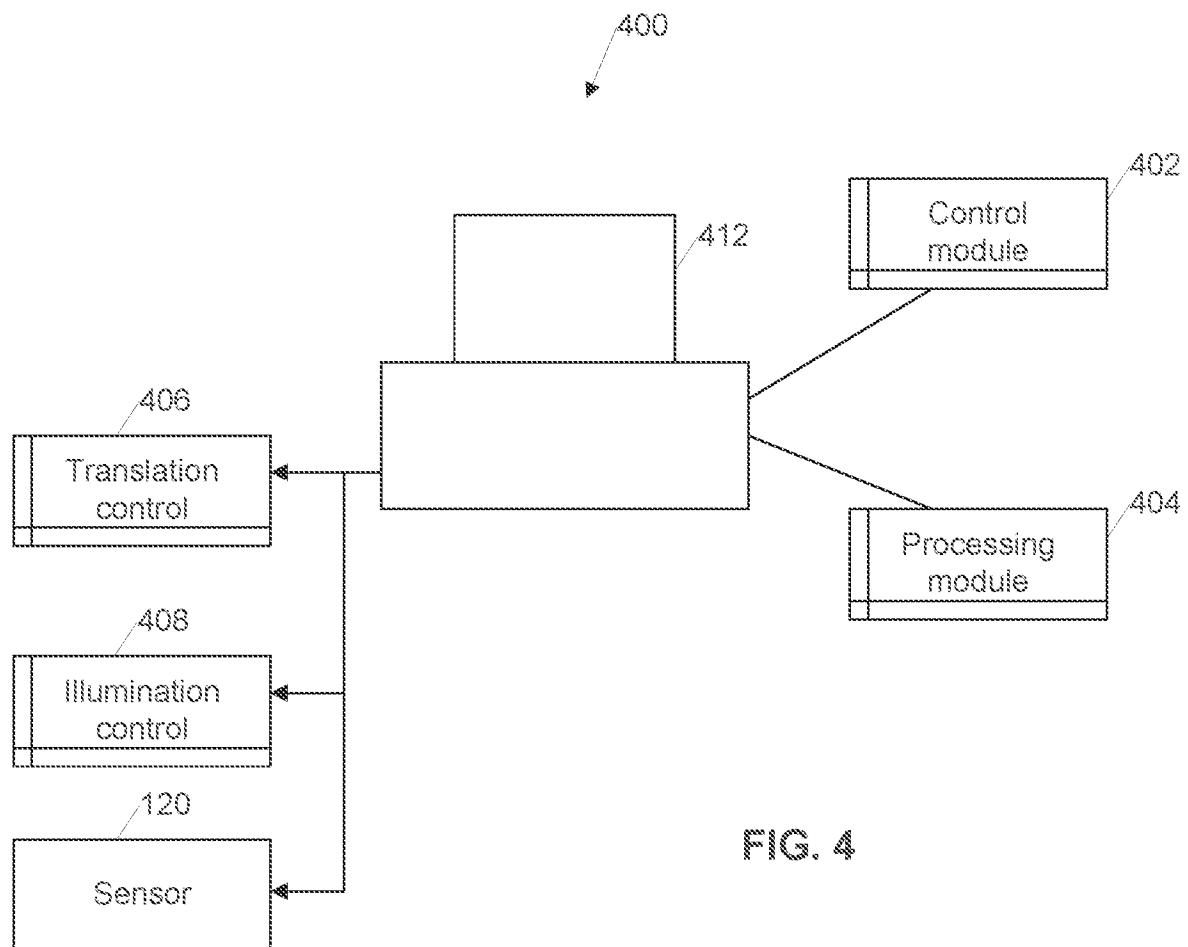


FIG. 4

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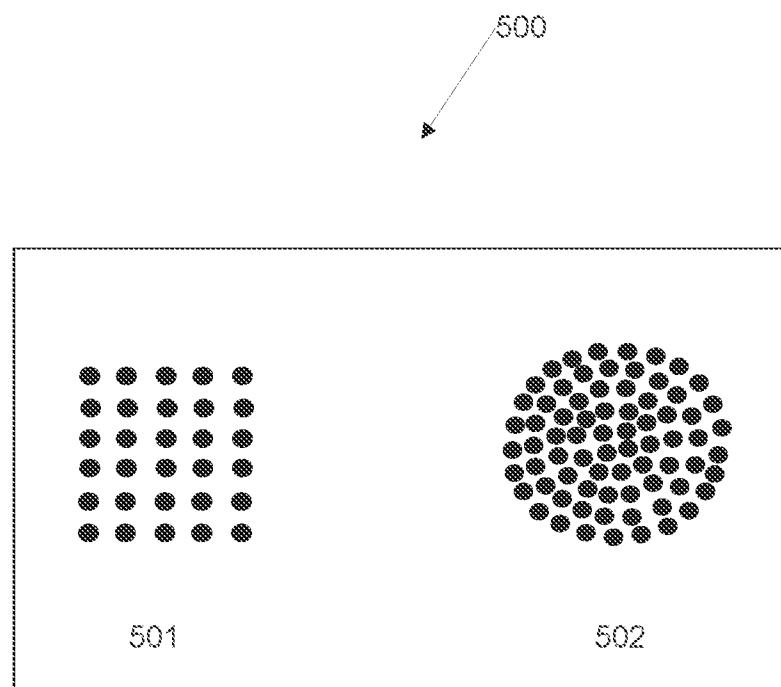


FIG.5

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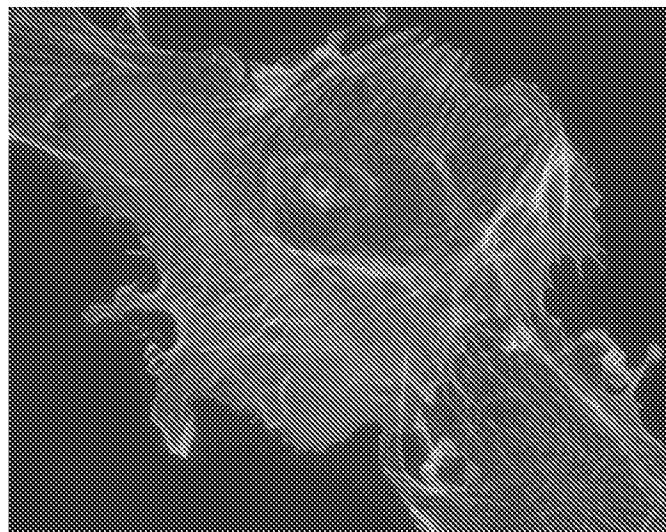


FIG. 6A

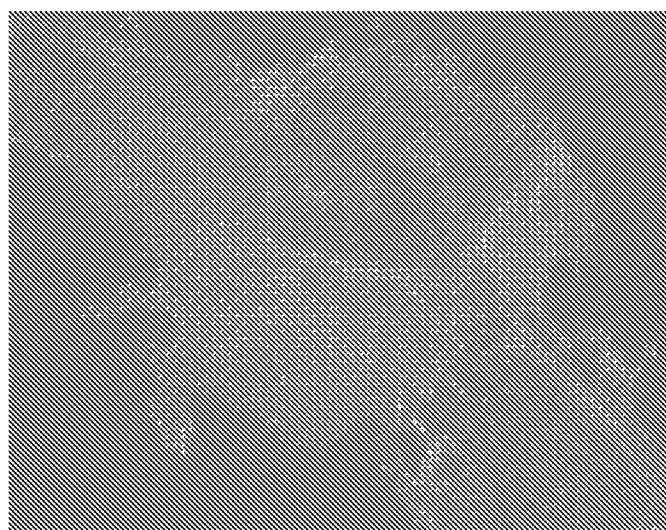


FIG. 6B

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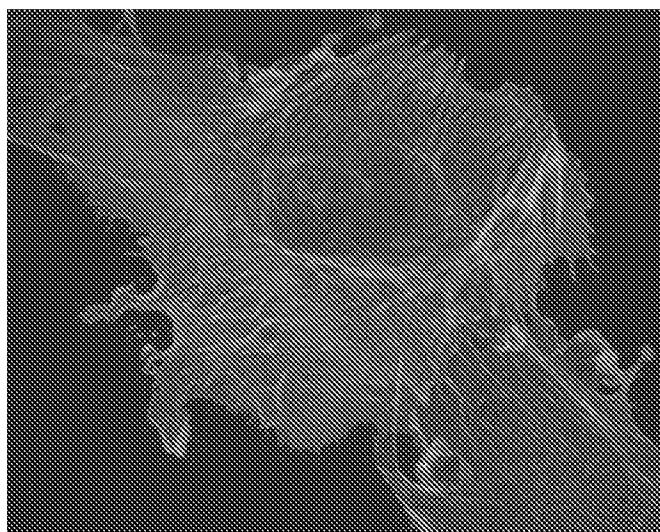


FIG. 6C

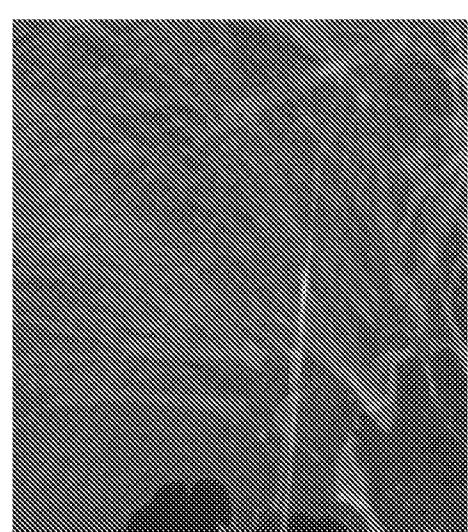


FIG. 6D

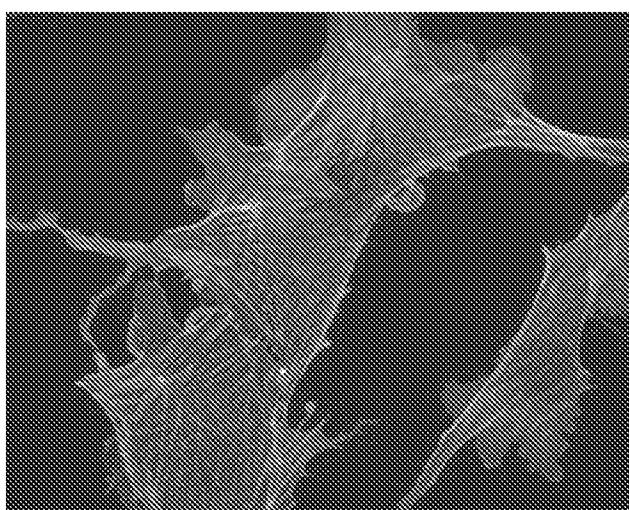


FIG. 6E

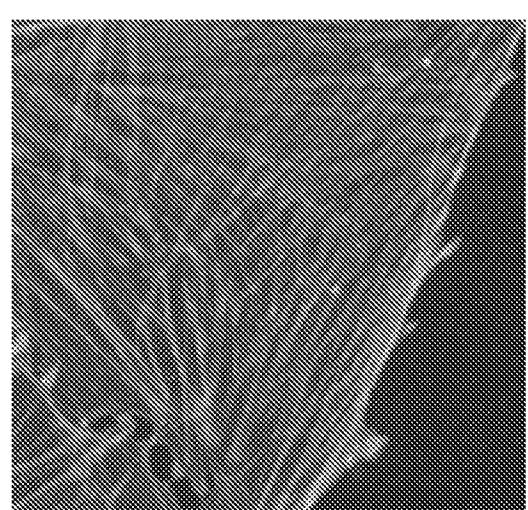


FIG. 6F

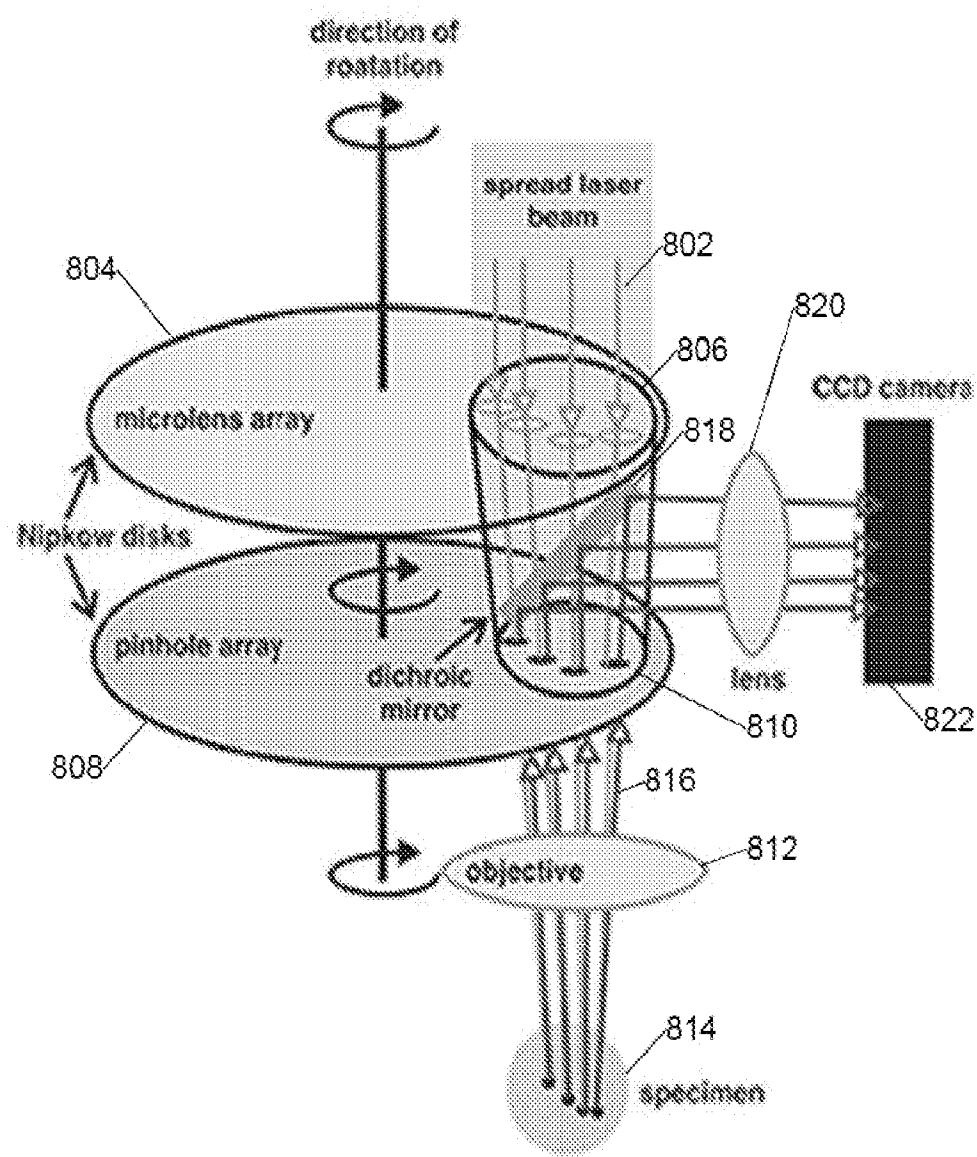


FIG. 7

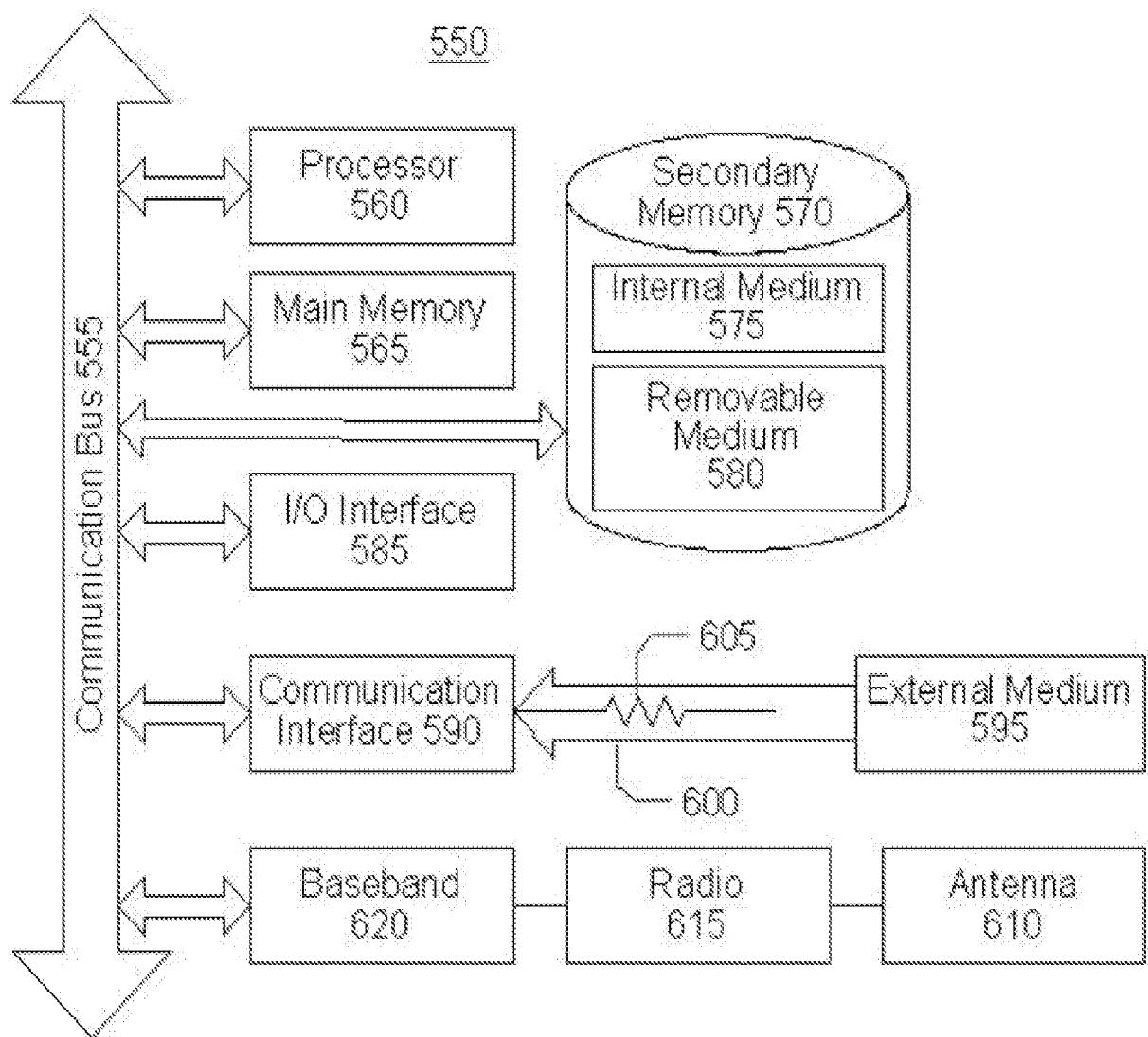


FIG. 8

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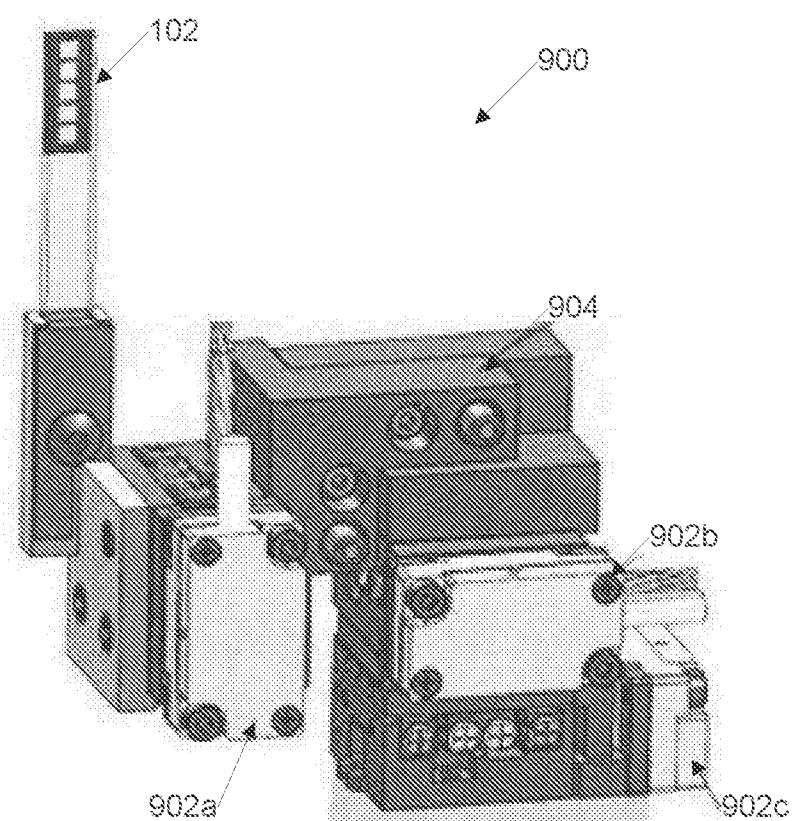


FIG. 9

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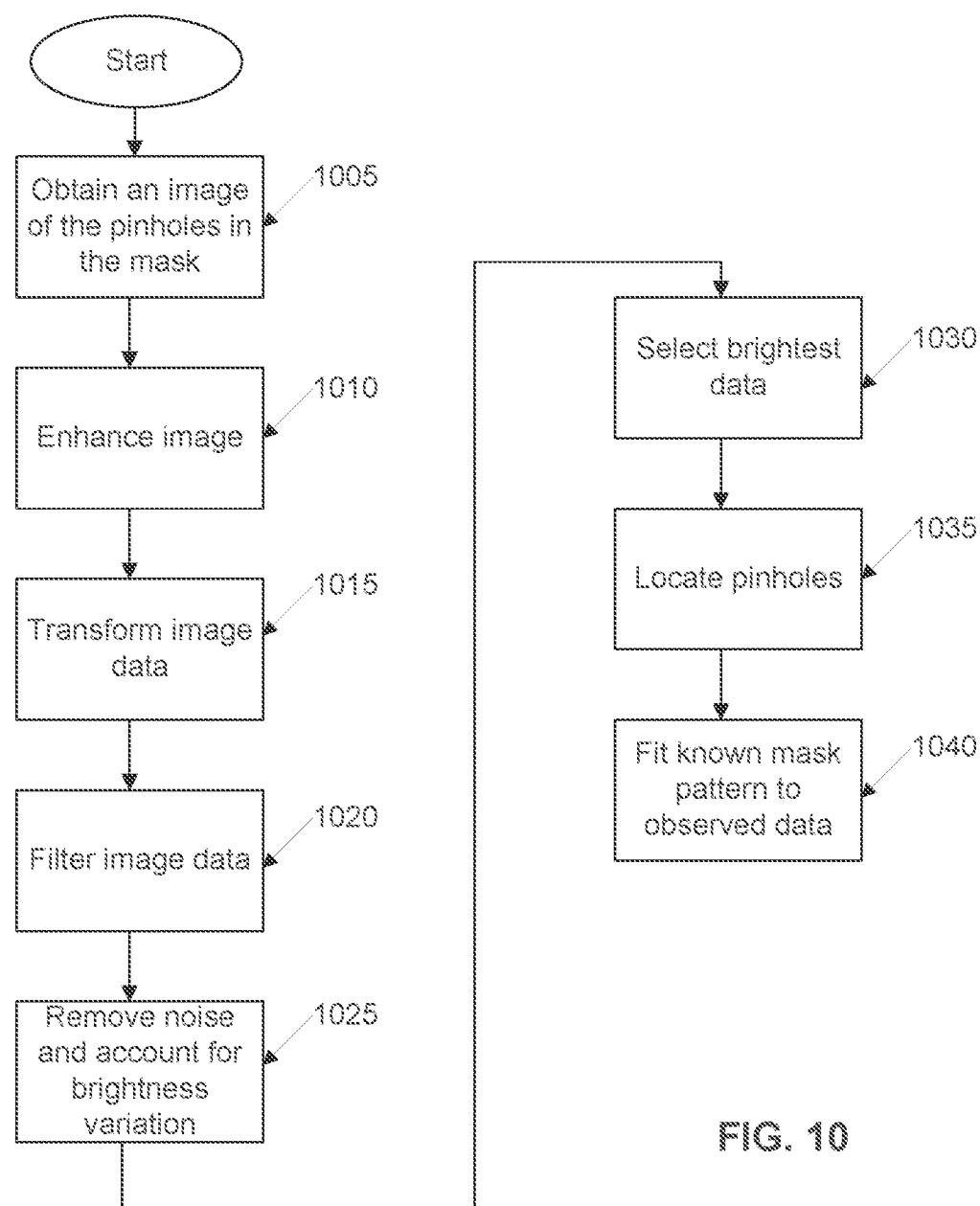


FIG. 10

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FIG. 11A

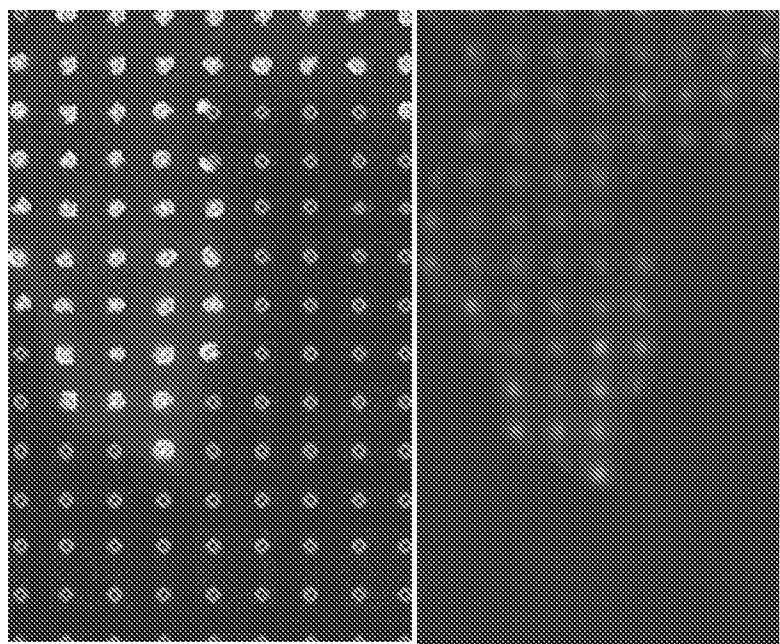


FIG. 11B

INTERNATIONAL SEARCH REPORT

International application No
PCT/US2016/031570

A. CLASSIFICATION OF SUBJECT MATTER
INV. G02B21/00 G01N21/27 G01N21/64
ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
G02B

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	WO 2013/126762 A1 (US OF AMERICA AS REPRESENTED BY THE SECRETARY DEPT OF HEALTH AND HUMAN) 29 August 2013 (2013-08-29) figure 4 page 13, line 28 - page 14, line 14 -----	1-5
Y	US 7 115 848 B1 (ZINTER J ROBERT [US] ET AL) 3 October 2006 (2006-10-03) column 5, line 53 - line 65 column 8, line 26 - line 32 -----	6-31
		6-31



Further documents are listed in the continuation of Box C.



See patent family annex.

* Special categories of cited documents :

- "A" document defining the general state of the art which is not considered to be of particular relevance
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- "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)
- "O" document referring to an oral disclosure, use, exhibition or other means
- "P" document published prior to the international filing date but later than the priority date claimed

"T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention

"X" document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone

"Y" document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art

"&" document member of the same patent family

Date of the actual completion of the international search 18 August 2016	Date of mailing of the international search report 26/08/2016
Name and mailing address of the ISA/ European Patent Office, P.B. 5818 Patentlaan 2 NL - 2280 HV Rijswijk Tel. (+31-70) 340-2040, Fax: (+31-70) 340-3016	Authorized officer Orignac, Xavier

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No
PCT/US2016/031570

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
WO 2013126762	A1 29-08-2013	CN 104471462 A EP 2817670 A1 JP 2015513671 A WO 2013126762 A1	25-03-2015 31-12-2014 14-05-2015 29-08-2013
US 7115848	B1 03-10-2006	NONE	