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(54) CONVEYING SYSTEM OF AN ESCALATOR

FÖRDESYSTEM EINER ROLLTREPPE

SYSTÈME DE TRANSPORT D'UN ESCALIER ROULANT

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Description

[0001] The invention relates to a step for a conveying system of an escalator. Thereat, each step comprises a riser, a tread, a hinge connecting the riser and the tread, a tow roller, and at least a first supporting point and a second supporting point on each side of the step, wherein at the first supporting point the step is connected to the step chain. Further, each step is configured to be folded via the hinge at least during a turnaround in the transition area.

[0002] Further, the invention relates to a conveying system of an escalator and a process to turnaround a step within a conveying system.

[0003] An escalator as known from the state of the art comprises a lower transition area at the lower end of the escalator, an upper transition area at the upper end of the escalator and a transporting area in between the lower and the upper transition area, wherein in the transition areas the steps of the escalator are turned around.

[0004] To provide enough space for a turnaround of the steps the escalator requires a pit of approximately 1 meter in depth.

[0005] In some cases it could be necessary to reduce the pit size e.g. if there are specific installations underneath the escalator which require space such as a garage or a piping system, or if the escalator has to be installed in an existing building and the effort to provide a large pit is very high. It could also be very interesting to reduce the pit size of escalators used for barking and debarking passengers from an airplane, wherein the escalator is usually transported in a truck.

[0006] Therefore, it is desirable to reduce the depth of the pit, especially to reduce the turning radius of the turnaround of the steps within the pit, especially for the lower transition area of an escalator.

[0007] The WO 2010/115317 A1 discloses a step route structure for controlling the folding and unfolding of foldable steps comprises a main wheel rail, an auxiliary wheel control rail, a folding control rail and a stopper rail that pushes a latch hook stopper in the direction of a releasing lock of a latch hook. An inner lateral surface of the auxiliary wheel control rail facing the foldable steps is provided with a rail groove that is matched with an auxiliary wheel of the foldable steps. An inner lateral surface of the folding control rail is provided with a control pin sliding groove that is matched with a support arm control pin of the foldable steps. The stopper rail is provided opposite to the latch hook stopper of the foldable steps. The structure can control the folding and unfolding of the foldable steps, and ensures the surfaces of the steps maintain a horizontal state as the steps fold and unfold. In this state of the art the steps are folded twice via two different hinges at two different supporting points of the step. In this context, the riser shaft is attached to the riser. During folding the riser shaft is guided in a curved sliding guide, which is placed between a supporting point of the tread and a supporting point at the lower end of the riser. This

is therefore a structurally complicated design, with the step having to be folded twice, which increases the risk of material failure.

[0008] The EP 1 072 552 A1 discloses a conveying system constructed to reduce the depth of the pit in the lower transition area and the upper transition area of an escalator. Thereat, the steps of the conveying system are folded. In the transition areas, the steps are not turned around but guided in a way, that at any position the tread of a step faces upwards. By doing so, the depth of the pit can be reduced, but by guiding the steps in a way, that the tread of a step always faces upwards leads to an enormous increasing of the length of the pit.

[0009] Therefore, the objective task of the invention is to provide a conveying system for an escalator to reduce the depth of the pit of an escalator without increasing the length of the pit. Thereat, the construction of the escalator should be simple and should not require high costs. Especially, the construction of a typical escalator should not be changed in large parts, so a large part of standard components can be used.

[0010] To solve the problem a step for a conveying system of an escalator, a conveying system of an escalator, as well as a process to turnaround a step within a conveying system are proposed according the independent claims.

[0011] Further, advantageous arrangements of the invention are described in the dependent claims and the description as well as shown in the figures.

[0012] The solution of the problem provides a step for a conveying system of an escalator. Therein, each step comprises a riser, a tread, and a hinge connecting the riser and the tread. Further, each step comprises a tow roller, at least a first supporting point, and a second supporting point on each side of the step. At the first supporting point, the step is configured to be connected to a step chain of the escalator. Further, each step is configured to be folded via the hinge at least during a turnaround in a transition area of the escalator.

[0013] Especially, the riser of each step comprises at least a curved sliding guide to guide the riser in a predetermined curve while folding the step, especially while folding the step during the turnaround.

[0014] By guiding the riser in a predetermined curve by the curved sliding guide, collisions are avoided between adjacent steps.

[0015] In an arrangement, the tow roller is adjusted to the step at the second supporting point the step. Via the tow roller, the step is guided circulating along a tow roller guide of the conveying system.

[0016] In a further arrangement, the step is configured to be connected to the step chain in a fixed manner at the first supporting point.

[0017] In a further arrangement, each step comprises a third supporting point. Especially, at the third supporting point, the step is configured to be connected via a riser shaft to the step chain in a loose manner. This loose connection of the step to the step chain via the riser shaft

enables a controlled folding of the step, wherein the riser is folded towards the tread.

[0018] In a further arrangement the supporting points of the step are arranged at each side of the step. Especially, the first supporting point is arranged at a front edge of the tread. Especially, the second supporting point is arranged in a mid-region of the tread. Especially, the third supporting point is arranged at the riser, wherein the riser is arranged at a rear edge of the tread. Especially, the third supporting point is arranged at each side of the step and in a mid-region of the step width.

[0019] In a further arrangement, the riser shaft comprises a wheel. Especially, the wheel is configured to roll within the curved sliding guide of the riser.

[0020] So, the riser shaft is arranged within the curved sliding guide of the riser. The wheel adjusted to the riser shaft enables a frictionless sliding during folding of the step.

[0021] In a further arrangement, the riser shaft is configured to be connected to the step chain via a special fitting. The fitting comprises especially a threaded fixed to the step chain and a connecting nut, fitting on the threaded. This fitting enables a quick and easy mounting and dismounting of the step to the step chain.

[0022] In a further arrangement, the riser comprises a riser stiffener. Especially, the riser stiffener is arranged at the lower edge of the riser.

[0023] In case that the riser of a step is dented, a gap could appear between adjacent steps. The riser stiffener has the function to make the riser of the step more rigid to avoid a damage of the riser and thus an appearance of a gap between adjacent steps due to a damage.

[0024] Additionally or alternatively, the thickness of the riser can be increased to prevent a damage of the riser.

[0025] The solution of the problem further provides a conveying system of an escalator, wherein the conveying system comprises a transition area, a step chain, and a plurality of steps. Especially, the steps are connected to the step chain in a fixed manner at a first supporting point. Especially, the steps are connected via a riser shaft to the step chain in a loose manner at a third supporting point. Especially, the riser shaft connected to the step chain via a special fitting as described above.

[0026] In an arrangement, the step chain comprises inner rollers and outer rollers. Especially, an outer roller is adjusted to the step chain at least at the first supporting point of each step. Especially, the inner rollers and outer rollers are guided in a precision guide rail. Especially, the inner rollers are guided along an inner roller running surface of the precision guide rail. Especially, the outer rollers are spaced to an outer roller running surface of the precision guide rail. Especially, at least an outer roller gets in contact with the outer roller running surface in case of a rotation of a step.

[0027] In a further arrangement, the tow rollers adjusted to the second supporting point of the steps are guided by the precision guide rail.

[0028] Guiding the step chain via the inner rollers and

outer rollers, as well as guiding the tow rollers of the steps by the precision guide rail leads to an increasing of stability.

[0029] In case a user is standing over the rear edge of a step the main part of the weight force acting on the step due to the user is acting on the first supporting point in an upward direction and on the second supporting point in a downward direction creating a rotation momentum in the step. In case of an occurrence of a rotation of a step, at least an outer roller gets in contact with the outer roller running surface of the precision guide rail. Accordingly, the rotation is reduced by the precision guide rail, increasing significantly the stability of the step.

[0030] The solution of the problem further provides a process to turnaround a step configured as described above within a conveying system as described above, wherein for turnaround the step in the transition area the riser is fold towards the lower side of the tread via the hinge.

[0031] Especially, while folding, the riser is guided in a predetermined curve defined by the curved sliding guide of the riser. Especially, the riser is turned around the riser shaft, wherein the wheel of the riser shaft rolls within the curved sliding guide.

[0032] The step is connected to the step chain at the first supporting point in a fixed manner and at the third supporting point the step is connected to the step chain in a loose manner via the riser shaft. Due to the step chain trajectory during the turnaround within the transition area and the riser shaft sliding in the curved sliding guide, the riser of the step is fold automatically towards the lower side of the tread while entering into the turnaround.

[0033] Equivalent, when leaving the transition area, the step unfolds automatically due to the trajectory of the step chain.

[0034] In a further implementation during unfolding the step, the riser is guided in the predetermined curve defined by the curved sliding guide. Especially the riser shaft slides within the curved sliding guide.

[0035] In that way, collisions between adjacent steps are avoided.

[0036] The special arrangement of the step according the invention, wherein the riser of each step comprises at least a curved sliding guide to guide the riser in a predetermined curve while folding the step enables a turnaround in the transition area of an escalator with a very small turning radius, wherein the riser is kept in a controlled distance to an adjacent step during the folding and unfolding of the step. Thereat, most components of a typical escalator does not need to be changed when using the steps according the invention.

[0037] Further, positive details, features and functions of the invention are explained in association with the examples shown in the figures.

[0038] It is shown in:

Fig. 1 in a schematic diagram showing a transition area of a conveying system of an escalator;

Fig. 2 in schematic diagrams a step of the conveying system:

- a in an unfolded state;
- b in a folded state;

Fig. 3 in detailed diagrams the steps of the conveying system out of different perspectives, wherein the steps are shown:

- a in a side view;
- b in a detailed view the side view shown in Fig. 3a;
- c in a bottom-up view;
- d in a detailed view the bottom-up view shown in Fig. 3c;

Fig. 4 in a detailed view at the first supporting point of a step:

- a the connection of the outer roller and inner roller to the first supporting point;
- b the guidance of the inner roller and outer roller of the step chain, as well as the guidance of the tow roller of the step;

Fig. 5 in a closer more detailed view the steps shown in Fig. 3c;

Fig. 6 in a schematic diagram a transition area of the conveying system; and

Fig. 7 in a schematic diagram a fitting of a riser shaft.

[0039] Fig. 1 shows a schematic diagram of a conveying system 10 in the lower end of an escalator according to the invention.

[0040] The conveying system 10 comprises a transition area 11, a step chain 12 and a plurality of steps 20. In the transition area 11, the steps 20 of the escalator are turned around.

[0041] Each step 20 comprises a tread and a riser, wherein the tread and the riser are connected to each other via a hinge see Fig. 2.

[0042] When leaving a transporting area of the escalator and entering the transition area 11 at one end of the escalator the steps 20 are guided in a way, so the treads of the steps 20 are in a plane before they are turned around to be returned to the other end of the escalator.

[0043] Each step 20 is configured to be folded via the hinge at least during a turnaround in the transition area 11.

[0044] During a turnaround, especially during the turnaround in a lower transition area 11 at the lower end of the escalator, the riser of a step is folded towards the lower side of the tread of the step.

[0045] By folding the steps during the turnaround, the turning radius can be reduced. Accordingly, the depth of

the escalator pit can be reduced.

[0046] Fig. 2a and Fig. 2b show a step of the conveying system of Fig. 1. Thereat, Fig. 2a shows the step 20 in a transporting configuration, wherein the step 20 is unfolded. Fig. 2b shows the step 20 in a folded state.

[0047] The step 20 comprises a tread 21, a riser 22 and a hinge 23 connecting the tread 21 and the riser 22 to one another.

[0048] Fig. 3a to Fig. 3d show a detailed view of the steps 20. Thereat, Fig. 3a and Fig. 3b show the steps 20 from an upper side while Fig. 3c and Fig. 3d show the steps 20 from a lower side.

[0049] Each step 20 comprises a first supporting point 24 and a second supporting point 25 on each side of the step. At the first supporting point 24, the step 20 is connected to the step chain 12 in a fixed manner. At the second supporting point 25, a tow roller 251 is adjusted to the step 20.

[0050] The riser 22 of each step 20 comprises at least a curved sliding guide 221. The curved sliding guide 221 is configured to guide the riser 22 in a predetermined curve while folding the step 20 during the turnaround in the transition area.

[0051] The shape of the curved sliding guide 221 is adapted such that a controlled distance is kept between the riser 22 and the adjacent step 20 during the turnaround. In that way, collisions are avoided between adjacent steps 20 during the turnaround.

[0052] Further, each step 20 comprises a third supporting point 26, wherein at the third supporting point 26, the step 20 is connected via a riser shaft 261 to the step chain 12 in a loose manner.

[0053] The riser shaft 261 comprises a wheel 262, wherein the wheel 262 is configured to roll within the curved sliding guide 221 of the riser 22.

[0054] As can be seen in Fig. 3a, the step chain 12 comprises inner rollers 121 and outer rollers 122. The inner rollers 121 and outer rollers 122 are guided in a precision guide rail (see Fig. 4a and Fig. 4b).

[0055] Fig. 4a and Fig. 4b show a detailed view of the first supporting point 24 of a step 20. Thereat, Fig. 4a shows a detailed view of the connection of the outer roller 122 and inner roller 121 to the first supporting point 24 of the step 20. Fig. 4b shows a detailed view of the guidance of the inner roller 121 and outer roller 122 of the step chain 12, as well as the guidance of the tow roller 251 of the step 20.

[0056] At the first supporting point 24 of the step 20, an outer roller 122 is adjusted to the step chain 12. The inner rollers 121 and outer rollers 122 of the step chain 12 are guided in a precision guide rail 13. Thereat, the inner rollers 121 are in contact with the inner roller running surface 131. The outer rollers 122 are spaced to the outer roller running surface 132.

[0057] Further, the tow roller 251 adjusted to the second supporting point 25 of the step 25 is guided by the precision guide rail 13. The tow roller 251 is in contact with the inner roller running surface 131.

[0058] In case a user is standing over the rear edge of a step the main part of the weight force acting on the step due to the user is acting on the first supporting point in an upward direction and on the second supporting point in a downward direction creating a rotation momentum in the step.

[0059] In case of an occurrence of a rotation of a step 20, at least an outer roller 122 gets in contact with the outer roller running surface 132 of the precision guide rail 13.

[0060] Accordingly, the rotation of the step 20 is reduced by the precision guide rail 13, increasing significantly the stability of the step 20.

[0061] Fig. 5 shows a closer view of Fig. 3c. Thereat, the riser 22 of each step 20 comprises a riser stiffener 222.

[0062] The riser stiffener 222 has the function to make the riser 22 of the step 20 more rigid to avoid a damage of the riser 22 and thus an appearance of a gap between adjacent steps 20 due to a damage.

[0063] Additionally or alternatively, the thickness of the riser 22 can be increased to prevent a damage of the riser 22.

[0064] Fig. 6 shows a transition area 11 in which the steps 20 are turned around.

[0065] During the turnaround the tow rollers of the steps are guided around a curved guide rail of a small turning radius such that the depth of the pit can be reduced especially such that the depth d of the pit is reduced to $d < 1\text{m}$.

[0066] For turnaround a step 20 in the transition area 11 the riser 22 of the step 20 is fold towards the lower side of the tread 21 via the hinge. While folding, the riser 22 is guided in a predetermined curve defined by the curved sliding guide 221, wherein the wheel 262 of the riser shaft 261 rolls within the curved sliding guide 221.

[0067] The step 20 folds automatically when guided through the turnaround according the trajectory of the step chain 12 due to the step 20 is connected to the step chain at the first supporting point in a fixed manner and at the third supporting point the step is connected to the step chain 12 in a lose manner via the riser shaft 261.

[0068] Therefore, when entering the transition area 11, the riser 22 is folded towards the lower side of the tread 21. Equivalent, when leaving the transition area 11, the step 20 unfolds automatically due to the trajectory of the step chain 12.

[0069] During unfolding, the riser 22 guided is guided in the predetermined curve defined by the curved sliding guide 221 of the riser 22. Thereat, the riser 22 is turned around the riser shaft 261, wherein the wheel 262 of the riser shaft 261 rolls within the curved sliding guide 221.

[0070] As shown in Fig. 7, the riser shaft 261 is connected to the step chain 12 via a special fitting 263.

[0071] The fitting 263 comprises an outer thread 2631 fixed to the step chain 12 and a connecting nut 2632, fitting on the outer thread 2631.

[0072] The fitting 263 enables an easy connecting and

disconnecting of the riser shaft to the step chain and therefore an easy mount and dismount of the step to the conveying system of the escalator.

5 Reference numbers

[0073]

10	Conveying system
11	transition area
12	Step chain
	121 Inner roller
	122 Outer roller
13	Precision guide rail
15	131 Inner roller running surface
	132 Outer roller running surface
20	Step
21	Tread
22	Riser
20	221 Curved sliding guide
	222 Riser stiffener
23	Hinge
24	First supporting point
25	Second supporting point
25	251 Tow roller
26	Third supporting point
	261 Riser shaft
	262 Wheel
	263 Fitting
30	2631 Outer thread
	2632 Connecting nut

Claims

- 35 1. Step (20) for a conveying system (10) of an escalator, wherein

each step (20) comprises:

- 40 - a riser (22),
 - a tread (21),
 - a hinge (23) connecting the riser (22) and the tread (21),
 45 - a tow roller (251),
 - at least a first supporting point (24) and a second supporting point (25) on each side of the step (20), wherein
 at the first supporting point (24), the step (20) is configured to be connected to a step chain (12) of the escalator,

and wherein

each step (20) is configured to be folded via the hinge (23) at least during a turnaround in a transition area (11) of the escalator,

characterized in

that the riser (22) of each step (20) comprises

- at least a curved sliding guide (221) to guide the riser (22) in a predetermined curve while folding the step (20).
2. Step (20) of claim 1,
characterized in
that the tow roller (251) is adjusted to the step (20) at the second supporting point (25) of the step (20). 5
 3. Step (20) of claims 1 to 2,
characterized in
that at the first supporting point (24), the step (20) is configured to be connected to the step chain (12) in a fixed manner. 10
 4. Step (20) of one of the previous claims,
characterized in
that each step (20) comprises a third supporting point (26), wherein
at the third supporting point (26), the step (20) is configured to be connected via a riser shaft (261) to the step chain (12) in a loose manner. 15 20
 5. Step (20) of claim 4,
characterized in
that the riser shaft (261) comprises a wheel (262),
wherein the wheel (262) is configured to roll within the curved sliding guide (221) of the riser (22). 25 30
 6. Step (20) of one of the claims 4 or 5,
characterized in
that the riser shaft (261) is configured to be connected to the step chain (12) via a fitting (263), wherein the fitting (263) comprises
an outer thread (2631) fixed to the step chain (12) and
a connecting nut (2632), fitting on the outer thread (2631). 35 40
 7. Step (20) of one of the claims 4 to 6,
characterized in
that the first supporting point (24) is arranged at a front edge of the tread (21),
the second supporting point (25) is arranged in a mid-region of the tread (21), and
the third supporting point (26) is arranged at the riser (22), which is arranged at a rear edge of the tread (21). 45 50
 8. Step (20) of one of the previous claims,
characterized in
that the riser (22) comprises a riser stiffener (222). 55
 9. Escalator comprising
- a transition area (11)
- a step chain (12), and
- a plurality of steps (20) according one of the claims 1 to 8.
 10. Escalator of claim 9,
characterized in
that the step chain (12) comprises inner rollers (121) and outer rollers (122) guided by a precision guide rail (13), wherein
the inner rollers (121) are in contact with an inner roller running surface (131) of the precision guide rail (13), and
the outer rollers (121) are spaced to an outer roller running surface (132) of the precision guide rail (13).
 11. Escalator of one of the claims 9 to 10,
characterized in
that the tow rollers (251) adjusted to the second supporting point (25) to the steps (20) are guided by the precision guide rail (13), wherein
the tow rollers (251) are in contact with the inner roller running surface (131).
 12. Process to turnaround the step (20) of one of the claims 5 to 8, in the transition area (11) of the escalator of one of the claims 9 to 11, wherein
for turnaround the step (20) in the transition area (11) the riser (22) is fold towards the lower side of the tread (21) via the hinge (23)
characterized in
that while folding, the riser (22) is guided in a predetermined curve defined by the curved sliding guide (221) of the riser (22), wherein
the riser (22) is turned around the riser shaft (261), wherein
the wheel (262) of the riser shaft (261) rolls within the curved sliding guide (221).
 13. Process of claim 12,
characterized in
that the step (20) is folded when entering the transition area (11) according to a trajectory of the step chain (12) within the transition area (11).
 14. Process of one of the claims 12 to 13,
characterized in
that the step (20) unfolds when leaving the transition area (11).
 15. Process of one of the claims 12 to 14,
characterized in

that during unfolding the step (20), the riser (22) is guided in the predetermined curve defined by the curved sliding guide (221) of the riser (22).

Patentansprüche

1. Stufe (20) für ein Fördersystem (10) einer Fahrtreppe, wobei jede Stufe (20) aufweist:

eine Setzstufe (22);
eine Trittfläche (21);
ein die Setzstufe (22) und die Trittfläche (21) verbindendes Scharnier (23);
eine Schlepprolle (251); und
mindestens einen ersten Stützpunkt (24) und einen zweiten Stützpunkt (25) auf jeder Seite der Stufe (20),
wobei die Stufe (20) am ersten Stützpunkt (24) dafür konfiguriert ist, mit einer Stufenkette (12) der Fahrtreppe verbunden zu werden,
und wobei jede Stufe (20) dafür konfiguriert ist, über das Scharnier (23) zumindest während eines Umkehrvorgangs in einem Übergangsbereich (11) der Fahrtreppe geklappt zu werden,
dadurch gekennzeichnet, dass
die Setzstufe (22) jeder Stufe (20) zumindest eine gekrümmte Gleitführung (221) zum Führen der Setzstufe (22) in einer vorgegebenen Kurve, während die Stufe (20) geklappt wird, aufweist.

2. Stufe (20) nach Anspruch 1,
dadurch gekennzeichnet, dass
die Schlepprolle (251) am zweiten Stützpunkt (25) der Stufe (20) an die Stufe (20) angepasst ist.

3. Stufe (20) nach Anspruch 1 oder 2,
dadurch gekennzeichnet, dass
die Stufe (20) dafür konfiguriert ist, am ersten Stützpunkt (24) mit der Stufenkette (12) auf eine feste Weise verbunden zu werden.

4. Stufe (20) nach einem der vorhergehenden Ansprüche,
dadurch gekennzeichnet, dass
jede Stufe (20) einen dritten Stützpunkt (26) aufweist, wobei die Stufe (20) am dritten Stützpunkt (26) dazu konfiguriert ist, über eine Setzstufenwelle (261) mit der Stufenkette (12) lose verbunden zu werden.

5. Stufe (20) nach Anspruch 4,
dadurch gekennzeichnet, dass
die Setzstufenwelle (261) ein Rad (262) aufweist,
wobei das Rad (262) dafür konfiguriert ist, innerhalb der gekrümmten Gleitführung (221) der Setzstufe (22) zu rollen.

6. Stufe (20) nach Anspruch 4 oder 5,
dadurch gekennzeichnet, dass
die Setzstufenwelle (261) dafür konfiguriert ist, über ein Anschlussstück (263) mit der Stufenkette (12) verbunden zu werden, wobei das Anschlussstück (263) aufweist:

ein an der Stufenkette (12) befestigtes Außengewinde (2631); und
eine auf das Außengewinde (2631) aufschraubbare Verbindungsmutter (2632).

7. Stufe (20) nach einem der Ansprüche 4 bis 6,
dadurch gekennzeichnet, dass

der erste Stützpunkt (24) an einem vorderen Rand der Trittfläche (21) angeordnet ist;
der zweite Stützpunkt (25) in einem mittleren Bereich der Trittfläche (21) angeordnet ist; und
der dritte Stützpunkt (26) an der Setzstufe (22) angeordnet ist, die an einem hinteren Rand der Trittfläche (21) angeordnet ist.

8. Stufe (20) nach einem der vorhergehenden Ansprüche,
dadurch gekennzeichnet, dass
die Setzstufe (22) eine Setzstufenversteifung (222) aufweist.

9. Fahrtreppe mit:

einem Übergangsbereich (11);
einer Stufenkette (12); und
einer Vielzahl von Stufen (20) nach einem der Ansprüche 1 bis 8.

10. Fahrtreppe nach Anspruch 9,
dadurch gekennzeichnet, dass

die Stufenkette (12) innere Rollen (121) und äußere Rollen (122) aufweist, die durch eine Präzisionsführungsschiene (13) geführt werden, wobei
die inneren Rollen (121) mit einer inneren Rollenlauffläche (131) der Präzisionsführungsschiene (13) in Kontakt stehen, und
die äußeren Rollen (122) beabstandet von den inneren Rollen mit einer äußeren Rollenlauffläche (132) der Präzisionsführungsschiene (13) in Kontakt stehen.

11. Fahrtreppe nach Anspruch 9 oder 10,
dadurch gekennzeichnet, dass

die am zweiten Stützpunkt (25) an die Stufen (20) angepassten Schlepprollen (251) durch die Präzisionsführungsschiene (13) geführt werden, wobei

die Schlepprollen (251) mit der inneren Rollenlauffläche (131) in Kontakt stehen.

12. Verfahren zum Umkehren der Stufe (20) nach einem der Ansprüche 5 bis 8 im Übergangsbereich (11) der Fahrtreppe nach einem der Ansprüche 9 bis 11, wobei

zum Umkehren der Stufe (20) im Übergangsbereich (11) die Setzstufe (22) über das Scharnier (23) in Richtung zur Unterseite der Trittfläche (21) geklappt wird,

dadurch gekennzeichnet, dass

beim Klappen, die Setzstufe (22) in einer vorgegebenen Kurve geführt wird, die durch die gekrümmte Gleitführung (221) der Setzstufe (22) definiert ist, wobei die Setzstufe (22) um die Setzstufenwelle (261) gedreht wird, wobei das Rad (262) der Setzstufenwelle (261) innerhalb der gekrümmten Gleitführung (221) rollt.

13. Verfahren nach Anspruch 12, **dadurch gekennzeichnet, dass** die Stufe (20) beim Eintreten in den Übergangsbereich (11) entsprechend einer Bahn der Stufenkette (12) innerhalb des Übergangsbereichs (11) einge-klappt wird.

14. Verfahren nach Anspruch 12 oder 13, **dadurch gekennzeichnet, dass** die Stufe (20) beim Austreten aus dem Übergangsbereiche (11) aufgeklappt wird.

15. Verfahren nach einem der Ansprüche 12 bis 14, **dadurch gekennzeichnet, dass** die Setzstufe (22) beim Aufklappen der Stufe (20) in der vorgegebenen Kurve geführt wird, die durch die gekrümmte Gleitführung (221) der Setzstufe (22) definiert ist.

Revendications

1. Marche (20) pour un système de convoyage (10) d'un escalator, dans laquelle

chaque marche (20) comprend :

- une contremarche (22),
- un plat de marche (21),
- une charnière (23) reliant la contremarche (22) au plat de marche (21),
- un roulement de tirage (251),
- au moins un premier point de soutien (24) et un deuxième point de soutien (25) de chaque côté de la marche (20), dans laquelle

au niveau du premier point de soutien (24), la marche (20) est conçue pour être reliée à une chaîne de marches (12) de l'escalator, et dans laquelle

chaque marche (20) est configurée pour être repliée au moyen de la charnière (23) au moins pendant un revirement dans une zone de transition (11) de l'escalator,

caractérisée en ce que

la contremarche (22) de chaque marche (20) comprend au moins un guide de glissement incurvé (221) pour guider la contremarche (22) selon une courbe prédéterminée tout en repliant la marche (20).

2. Marche (20) selon la revendication 1, **caractérisée en ce que** le roulement de tirage (251) est ajusté à la marche (20) au niveau du deuxième point de soutien (25) de la marche (20).

3. Marche (20) selon les revendications 1 à 2, **caractérisée en ce que** au niveau du premier point de soutien (24), la marche (20) est conçue pour être reliée à la chaîne de marches (12) d'une manière fixe.

4. Marche (20) selon l'une des revendications précédentes, **caractérisée en ce que** chaque marche (20) comprend un troisième point de soutien (26), dans laquelle au niveau du troisième point de soutien (26), la marche (20) est conçue pour être reliée au moyen d'un arbre de contremarche (261) à la chaîne de marches (12) d'une manière lâche.

5. Marche (20) selon la revendication 4, **caractérisée en ce que**

l'arbre de contremarche (261) comprend un disque (262), dans laquelle le disque (262) est conçu pour tourner à l'intérieur du guide de glissement incurvé (221) de la contremarche (22).

6. Marche (20) selon l'une des revendications 4 ou 5, **caractérisée en ce que**

l'arbre de contremarche (261) est conçu pour être relié à la chaîne de marches (12) au moyen d'un raccord (263), dans laquelle le raccord (263) comprend un filetage externe (2631) fixé à la chaîne de marches (12) et un écrou de connexion (2632), ajusté sur le filetage externe (2631).

7. Marche (20) selon l'une des revendications 4 à 6,
caractérisée en ce que

le premier point de soutien (24) est disposé au
niveau d'un bord avant du plat de marche (21),
le deuxième point de soutien (25) est disposé
dans une région médiane du plat de marche
(21), et
le troisième point de soutien (26) est disposé au
niveau de la contremarche (22), qui est disposée
au niveau d'un bord arrière du plat de marche
(21).

8. Marche (20) selon l'une des revendications précé-
dentes,
caractérisée en ce que
la contremarche (22) comprend un contrefort de con-
tremarche (222).

9. Escalator comprenant

- une zone de transition (11)
- une chaîne de marches (12), et
- une pluralité de marches (20) selon l'une des
revendications 1 à 8.

10. Escalator selon la revendication 9,
caractérisé en ce que

la chaîne de marches (12) comprend des rou-
lements internes (121) et des roulements exter-
nes (122) guidés par un rail de guidage de pré-
cision (13), dans lequel
les roulements internes (121) sont en contact
avec une surface de parcours de roulements in-
ternes (131) du rail de guidage de précision (13),
et
les roulements externes (131) sont espacés sur
une surface de parcours de roulements exter-
nes (132) du rail de guidage de précision (13).

11. Escalator selon l'une des revendications 9 à 10,
caractérisé en ce que

les roulements de tirage (251) ajustés au
deuxième point de soutien (25) des marches
(20) sont guidés par le rail de guidage de préci-
sion (13), dans lequel
les roulements de tirage (251) sont en contact
avec la surface de parcours de roulements in-
ternes (131).

12. Procédé de revirement de la marche (20) selon l'une
des revendications 5 à 8, dans la zone de transition
(11) de l'escalator selon l'une des revendications 9
à 11, dans lequel pour le revirement de la marche
(20) dans la zone de transition (11) la contremarche
(22) est repliée vers le côté inférieur du plat de mar-

che (21) au moyen de la charnière (23)
caractérisé en ce que

pendant le repliement, la contremarche (22) est
guidée selon une courbe prédéterminée définie
par le guide de glissement incurvé (221) de la
contremarche (22), dans lequel
la contremarche (22) tourne autour de l'arbre de
contremarche (261), dans lequel
le disque (262) de l'arbre de contremarche (261)
roule à l'intérieur du guide de glissement incurvé
(221).

13. Procédé la revendication 12,

caractérisé en ce que

la marche (20) est repliée lorsqu'elle entre dans la
zone de transition (11) selon une trajectoire de la
chaîne de marches (12) à l'intérieur de la zone de
transition (11).

14. Procédé selon l'une des revendications 12 à 13,

caractérisé en ce que

la marche (20) se déplie lorsqu'elle quitte la zone de
transition (11).

15. Procédé selon l'une des revendications 12 à 14,

caractérisé en ce que

pendant le dépliement de la marche (20) la contre-
marche (22) est guidée selon la courbe prédétermi-
née définie par le guide de glissement incurvé (221)
de la contremarche (22).

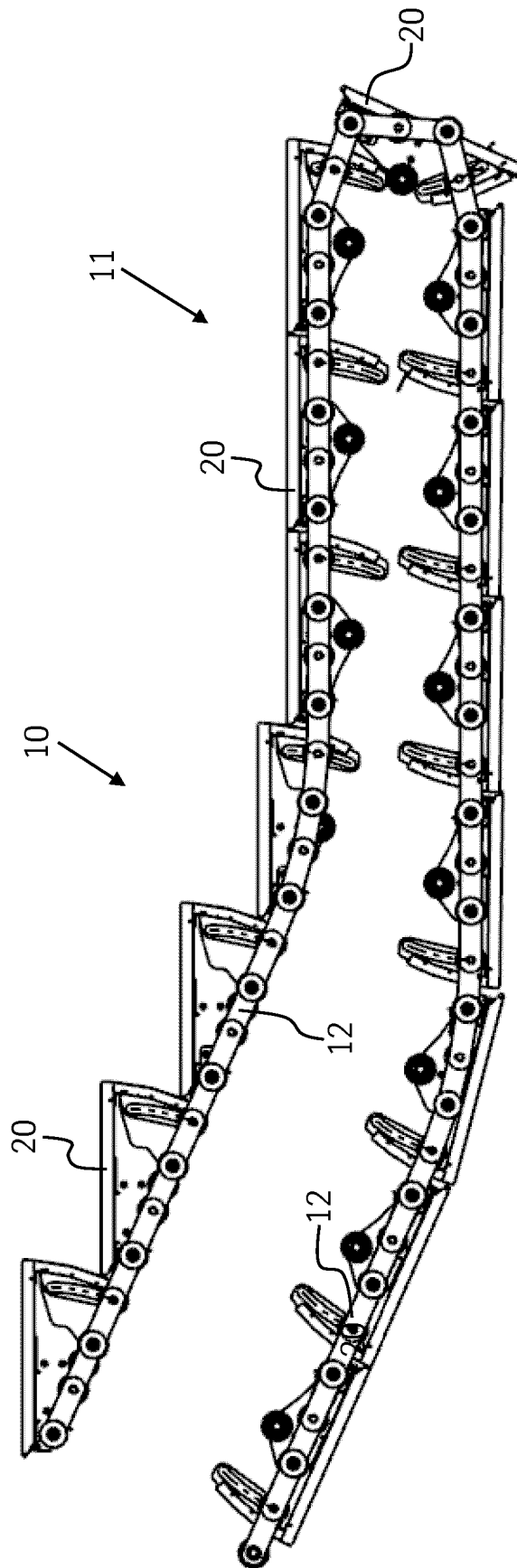


Fig. 1

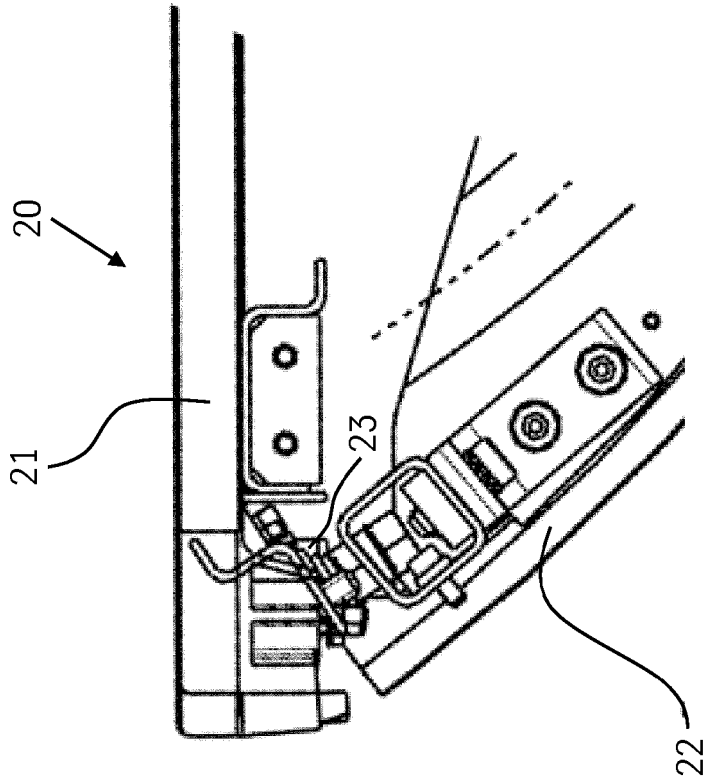


Fig. 2b

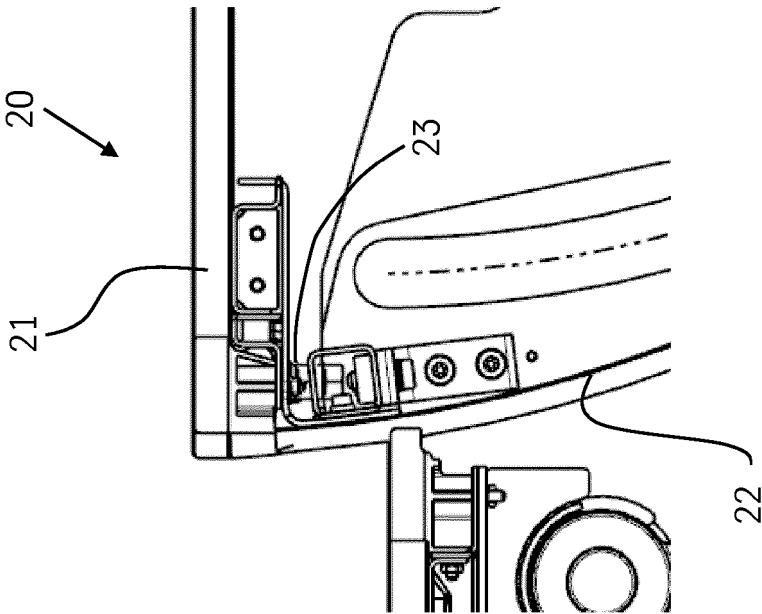
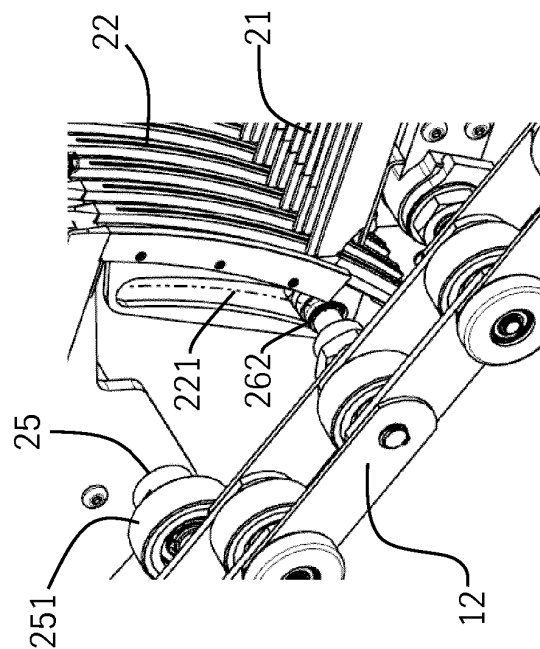
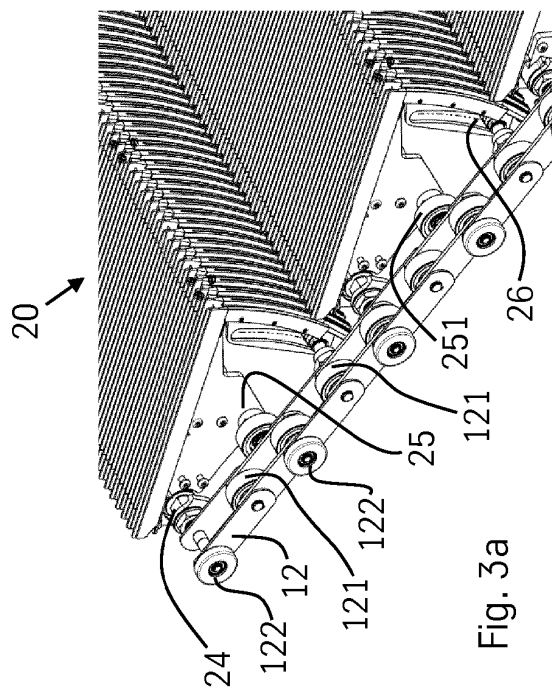
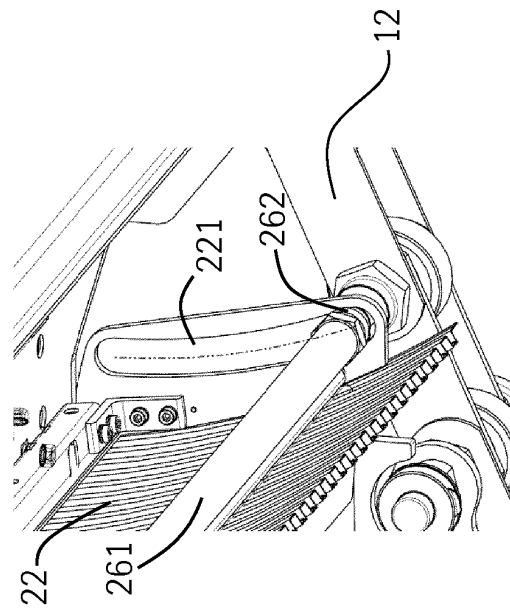
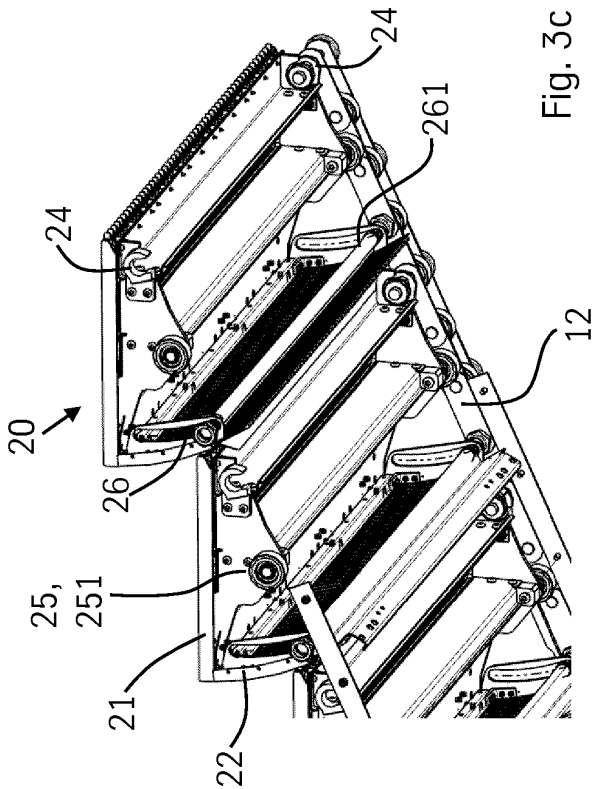


Fig. 2a



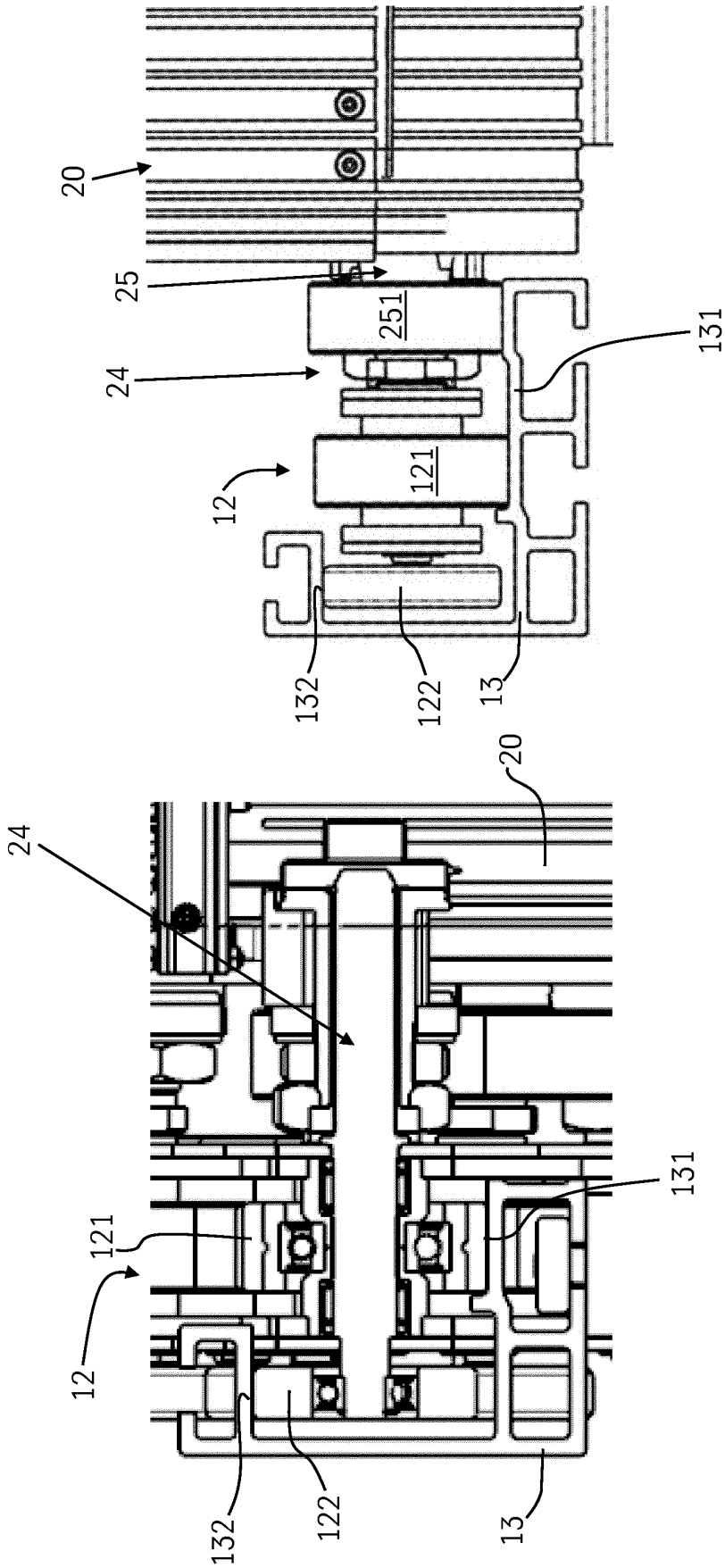


Fig. 4b

Fig. 4a

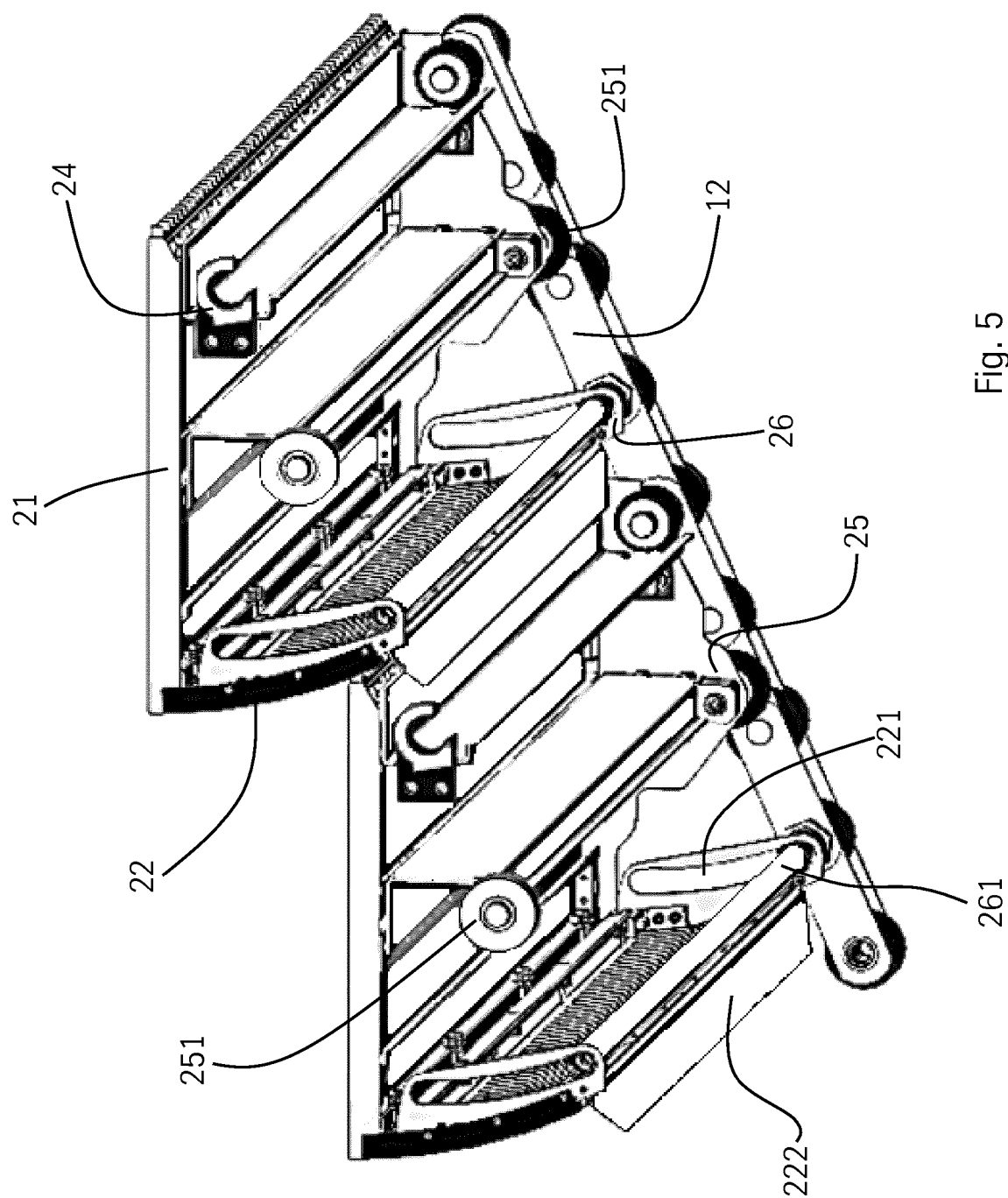


Fig. 5

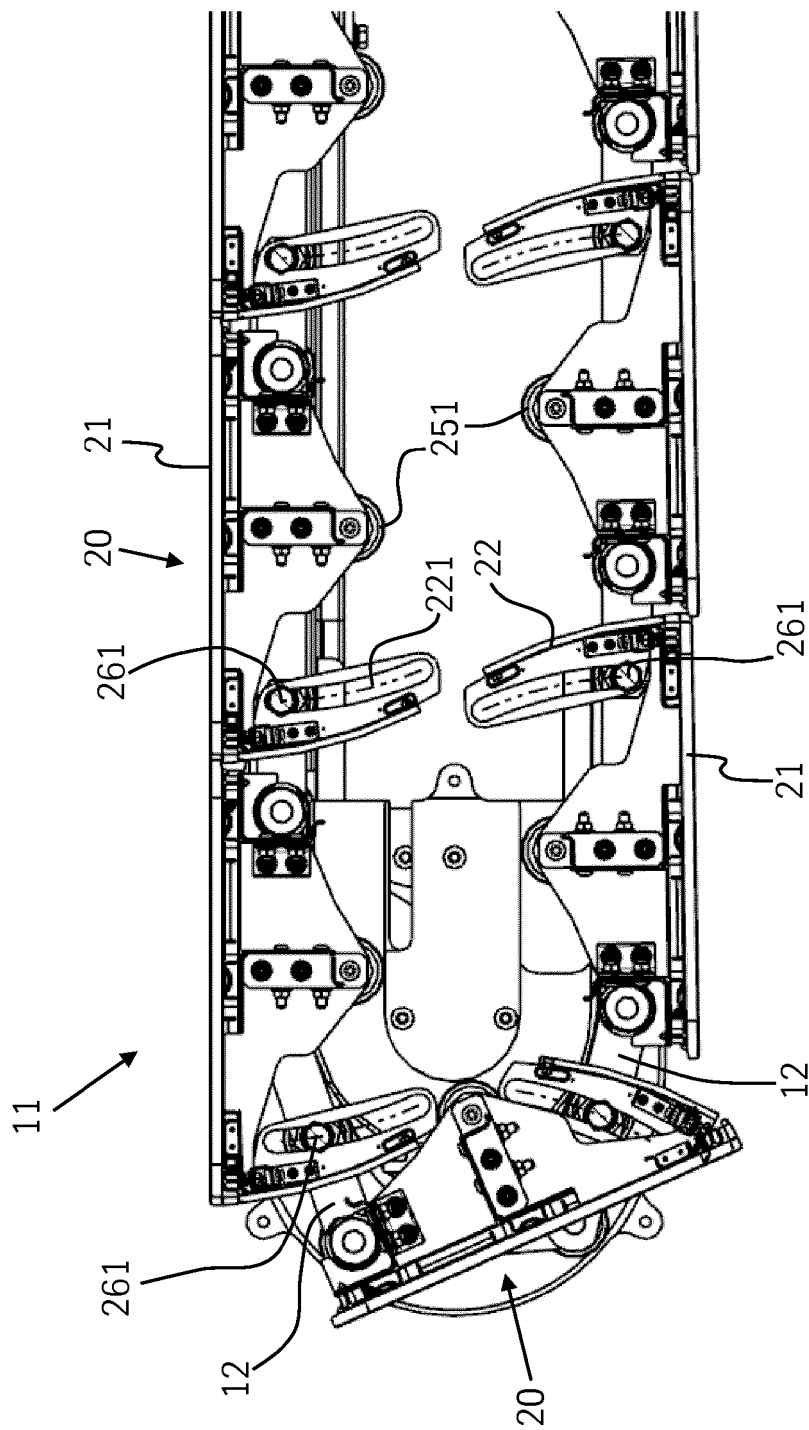


Fig. 6

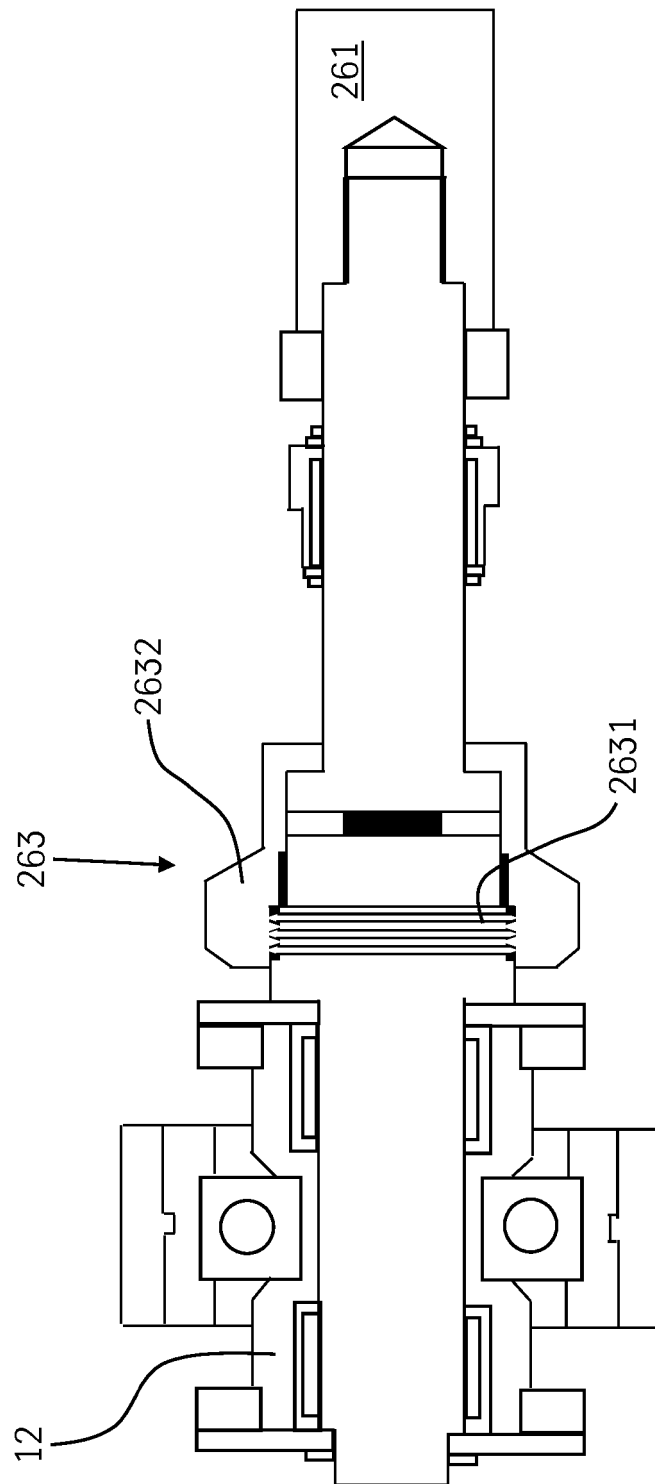


Fig. 7

REFERENCES CITED IN THE DESCRIPTION

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