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[Continued on next page]

(54) Title: ROTARY PISTON TYPE ACTUATOR WITH A CENTRAL ACTUATION ASSEMBLY

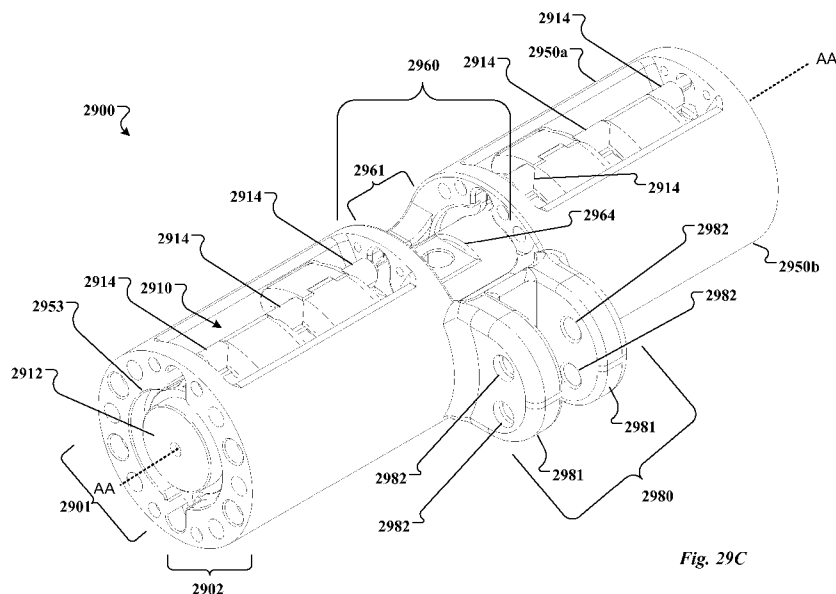


Fig. 29C

(57) Abstract: A rotary actuator (2900) includes a housing, a rotor assembly rotatably journaled in said housing and including a rotary output shaft (2912), a central actuation assembly (2960) including a central mounting point formed in an external surface of the rotary output shaft, said central mounting point proximal to the longitudinal midpoint of the rotary output shaft, a mounting assembly (2980) adapted for attachment to an external mounting connector of a mounting surface of an aircraft structural member, and an actuation arm removably attached at a proximal end to the central mounting point, said actuation arm adapted at a distal end for attachment to an external mounting feature of an aircraft assembly to be actuated.

**Declarations under Rule 4.17:**

- *as to applicant's entitlement to apply for and be granted a patent (Rule 4.17(ii))*
- *as to the applicant's entitlement to claim the priority of the earlier application (Rule 4.17(iii))*

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Rotary Piston Type Actuator With A Central Actuation Assembly

CROSS REFERENCE TO RELATED APPLICATIONS

[0001] This application claims the benefit of the priority of U.S. Patent
5 Application No. 13/778,561, filed February 27, 2013 and entitled "ROTARY
PISTON TYPE ACTUATOR", U.S. Patent Application No. 13/831,220, filed
March 14, 2013 and entitled "ROTARY PISTON TYPE ACTUATOR WITH A
CENTRAL ACTUATION ASSEMBLY", and U.S. Patent Application No.
13/921,904, filed June 19, 2013 and entitled "ROTARY PISTON TYPE
10 ACTUATOR WITH A CENTRAL ACTUATION ASSEMBLY", the disclosures of
which are incorporated by reference in their entirety.

TECHNICAL FIELD

[0002] This invention relates to an actuator device and more particularly to
a rotary piston type actuator device wherein the pistons of the rotor are moved
15 by fluid under pressure and wherein the actuator device includes a central
actuation assembly adapted for attachment to and external mounting feature
on a member to be actuated.

BACKGROUND

[0003] Rotary hydraulic actuators of various forms are currently used in
20 industrial mechanical power conversion applications. This industrial usage is
commonly for applications where continuous inertial loading is desired without
the need for load holding for long durations, e.g. hours, without the use of an
external fluid power supply. Aircraft flight control applications generally

implement loaded positional holding, for example, in a failure mitigation mode, using substantially only the blocked fluid column to hold position.

[0004] In certain applications, such as primary flight controls used for aircraft operation, positional accuracy in load holding by rotary actuators is
5 desired. Positional accuracy can be improved by minimizing internal leakage characteristics inherent to the design of rotary actuators. However, it can be difficult to provide leak-free performance in typical rotary hydraulic actuators, e.g., rotary "vane" or rotary "piston" type configurations.

SUMMARY

10 **[0005]** In general, this document relates to rotary actuators.

[0006] In aspect 1, a rotary actuator includes a housing, a rotor assembly rotatably journaled in said housing and including a rotary output shaft, a central actuation assembly including a central mounting point formed in an external surface of the rotary output shaft, said central mounting point proximal to the
15 longitudinal midpoint of the rotary output shaft, a mounting assembly adapted for attachment to an external mounting connector of a mounting surface of an aircraft structural member, and an actuation arm removably attached at a proximal end to the central mounting point, said actuation arm adapted at a distal end for attachment to an external mounting feature of an aircraft
20 assembly to be actuated.

[0007] In aspect 2 according to aspect 1, the central actuation assembly further includes a radial recess formed in an external peripheral surface of the housing proximal to the central mounting point of the rotary output shaft, and wherein said actuation arm extends through the radial recess.

[0008] Aspect 3 according to aspect 2, wherein the mounting assembly comprises a radially projecting portion of the housing disposed at a midpoint of the housing, said mounting assembly disposed about 180 degrees from the radial recess of the central actuation assembly.

5 **[0009]** Aspect 4 according to any one of aspects 1 to 3, wherein: the housing defines a first arcuate chamber including a first cavity, a first fluid port in fluid communication with the first cavity, and an open end; the rotor assembly further includes a first rotor arm extending radially outward from the rotary output shaft; and the rotary actuator further comprises an arcuate-
10 shaped first piston disposed in said housing for reciprocal movement in the first arcuate chamber through the open end, wherein a first seal, the first cavity, and the first piston define a first pressure chamber, and a first portion of the first piston contacts the first rotor arm.

[0010] Aspect 5 according to aspect 4, wherein the housing further defines
15 a second arcuate chamber comprising a second cavity, and a second fluid port in fluid communication with the second cavity; the rotor assembly further comprises a second rotor arm; and the rotary actuator further comprises an arcuate-shaped second piston disposed in said housing for reciprocal movement in the second arcuate chamber, wherein a second seal, the second
20 cavity, and the second piston define a second pressure chamber, and a first portion of the second piston contacts the second rotor arm.

[0011] Aspect 6 according to aspect 5, wherein the central actuation assembly further includes a radial recess formed in an external peripheral surface of the housing proximal to the central mounting point of the rotary

output shaft, and wherein said actuation arm extends through the radial recess.

[0012] Aspect 7 according to any one of aspects 1 to 6, further comprising a rotary actuator comprising a stator mounted to the housing and a rotor
5 coupled to the rotary output shaft.

[0013] Aspect 8 according to aspect 7, wherein the rotary actuator is one of a rotary piston type actuator, a rotary vane type actuator, or a rotary fluid type actuator, or wherein the rotary actuator is an electromechanical actuator.

[0014] In aspect 9, a rotary actuator comprising: a housing comprising a
10 mounting assembly; a rotor assembly rotatably journaled in said housing and including a rotary output shaft; a central actuation assembly including a central mounting point formed in an external surface of the rotary output shaft, said central mounting point proximal to the longitudinal midpoint of the rotary output shaft; an an actuation arm removably attached at a proximal end to the central
15 mounting point, said actuation arm adapted at a distal end for attachment to an external mounting feature of a member to be actuated.

[0015] Aspect 10 according to aspect 9, the central actuation assembly further includes a radial recess formed in an external peripheral surface of the housing proximal to the central mounting point of the rotary output shaft, and
20 wherein said actuation arm extends through the radial recess.

[0016] Aspect 11 according to aspect 10, wherein the mounting assembly comprises a radially projecting portion of the housing, said mounting assembly disposed about 180 degrees from the radial recess of the central actuation

assembly, said mounting assembly adapted for attachment to an external mounting connector of a mounting surface.

[0017] Aspect 12 according to aspect 11, wherein the radially projecting portion of the housing is a radially projecting central portion of the housing.

5 **[0018]** Aspect 13 according to any one of aspects 9 to 12, wherein the housing defines a first arcuate chamber including a first cavity, a first fluid port in fluid communication with the first cavity, and an open end; the rotor assembly further includes a first rotor arm extending radially outward from the rotary output shaft; and the rotary actuator further comprises an arcuate-
10 shaped first piston disposed in said housing for reciprocal movement in the first arcuate chamber through the open end, wherein a first seal, the first cavity, and the first piston define a first pressure chamber, and a first portion of the first piston contacts the first rotor arm.

[0019] Aspect 14 according to aspect 13, wherein the housing further
15 defines a second arcuate chamber comprising a second cavity, and a second fluid port in fluid communication with the second cavity; the rotor assembly further comprises a second rotor arm; and the rotary actuator further comprises an arcuate-shaped second piston disposed in said housing for reciprocal movement in the second arcuate chamber, wherein a second seal,
20 the second cavity, and the second piston define a second pressure chamber, and a first portion of the second piston contacts the second rotor arm.

[0020] Aspect 15 according to aspect 14, wherein the central actuation assembly further includes a radial recess formed in an external peripheral surface of the housing proximal to the central mounting point of the rotary

output shaft, and wherein said actuation arm extends through the radial recess.

[0021] Aspect 16 according to any one of aspects 9 to 15, further comprising a linear actuator mounted at a first end to the housing, and a
5 second end mounted to a first rotor arm extending radially outward from the rotary output shaft.

[0022] Aspect 17 according to any one of aspects 9 to 16, further comprising a rotary actuator comprising a stator mounted to the housing and a rotor coupled to the rotary output shaft.

10 **[0023]** Aspect 18, according to aspect 17, wherein the rotary actuator is one of a rotary piston type actuator, a rotary vane type actuator, or a rotary fluid type actuator.

[0024] Aspect 19 according to aspect 17, wherein the rotary actuator is an electromechanical actuator.

15 **[0025]** Aspect 20 according to aspect 17, wherein the rotary actuator comprises a linear actuator and a linear-to-rotary motion conversion assembly coupled to the rotor.

[0026] Aspect 21 according to any one of aspects 9 to 20, wherein the housing is formed as a one-piece housing.

20 **[0027]** Aspect 22 according to any one of aspects 9 to 21, wherein the external mounting feature is attached to one of an aircraft structural member or an external mounting connector of an external surface, and the mounting assembly is attached to the other of the aircraft structural member or the external mounting connector.

[0028] In aspect 23, a method of rotary actuation comprises: providing a rotary actuator comprising: a housing; a rotor assembly rotatably journaled in said housing and including a rotary output shaft; a central actuation assembly including a central mounting point formed in an external surface of the rotary
5 output shaft, said central mounting point proximal to the longitudinal midpoint of the rotary output shaft; and an actuation arm removably attached at a proximal end to the central mounting point, said actuation arm adapted at a distal end for attachment to an external mounting feature of a member to be actuated; energizing the rotor assembly; urging rotation of the rotary output
10 shaft; urging rotation of the actuation arm; urging motion of the member to be actuated.

[0029] Aspect 24 according to aspect 23, wherein the central actuation assembly further includes a radial recess formed in an external peripheral surface of the housing proximal to the central mounting point of the rotor shaft,
15 and wherein said actuation arm extends through the radial recess.

[0030] Aspect 25 according to any one of aspects 23 to 24, wherein the mounting assembly further comprises a radially projecting portion of the housing, said mounting assembly disposed about 180 degrees from the radial recess of the central actuation assembly, said mounting assembly adapted for
20 attachment to an external mounting connector of a mounting surface.

[0031] Aspect 26 according to any one of aspects 23 to 25, wherein the radially projecting portion of the housing is a radially projecting central portion of the housing.

[0032] Aspect 27 according to any one of aspects 23 to 26, wherein the central actuation assembly further includes a radial recess formed in an external peripheral surface of the housing proximal to the central mounting point of the rotary output shaft, and wherein said actuation arm extends
5 through the radial recess.

[0033] Aspect 28 according to any one of aspects 23 to 27, further comprising a rotary actuator comprising a stator mounted to the housing and a rotor coupled to the rotary output shaft.

[0034] Aspect 29 according to aspect 28, wherein the rotary actuator is one
10 of a rotary piston type actuator, a rotary vane type actuator, or a rotary fluid type actuator.

[0035] Aspect 30 according to any one of aspects 28 to 29, wherein the rotary actuator is an electromechanical actuator.

[0036] Aspect 31 according to any one of aspects 28 to 30, wherein the
15 rotary actuator comprises a linear actuator and a linear-to-rotary motion conversion assembly coupled to the rotor. The systems and techniques described herein may provide one or more of the following advantages. First, the system can provide an actuator that is mounted and/or actuated at a midpoint of the actuator. Second, the system can provide rotary actuation in a
20 compact space. Third, the system can provide the aforementioned rotary actuation with reduced deformation between the mounting point of the rotary actuator and the assembly to be actuated. Fourth, the system can provide the aforementioned advantages as an actuator that is implemented in an aircraft wing application, including aircraft wings made of composite materials.

[0037] The details of one or more implementations are set forth in the accompanying drawings and the description below. Other features and advantages will be apparent from the description and drawings, and from the claims.

5

DESCRIPTION OF DRAWINGS

[0038] FIG. 1 is a perspective view of an example rotary piston-type actuator.

[0039] FIG. 2 is a perspective view of an example rotary piston assembly.

[0040] FIG. 3 is a perspective cross-sectional view of an example rotary
10 piston-type actuator.

[0041] FIG. 4 is a perspective view of another example rotary piston-type actuator.

[0042] FIGs. 5 and 6 are cross-sectional views of an example rotary piston-type actuator.

15 [0043] FIG. 7 is a perspective view of another embodiment of a rotary piston-type actuator.

[0044] FIG. 8 is a perspective view of another example of a rotary piston-type actuator.

[0045] FIGs. 9 and 10 show an example rotary piston-type actuator in
20 example extended and retracted configurations.

[0046] FIG. 11 is a perspective view of another example of a rotary piston-type actuator.

[0047] FIGs. 12-14 are perspective and cross-sectional views of another example rotary piston-type actuator.

[0048] FIGs. 15 and 16 are perspective and cross-sectional views of another example rotary piston-type actuator that includes another example rotary piston assembly.

[0049] FIGs. 17 and 18 are perspective and cross-sectional views of
5 another example rotary piston-type actuator that includes another example rotary piston assembly.

[0050] FIGs. 19 and 20 are perspective and cross-sectional views of another example rotary piston-type actuator.

[0051] FIGs. 21A-21C are cross-sectional and perspective views of an
10 example rotary piston.

[0052] FIGs. 22 and 23 illustrate a comparison of two example rotor shaft embodiments.

[0053] FIG. 24 is a perspective view of another example rotary piston.

[0054] FIG. 25 is a flow diagram of an example process for performing
15 rotary actuation.

[0055] FIG. 26 is a perspective view of another example rotary piston-type actuator.

[0056] FIG. 27 is a cross-sectional view of another example rotary piston assembly.

[0057] FIG. 28 is a perspective cross-sectional view of another example
20 rotary piston-type actuator.

[0058] FIG. 29A is a perspective view from above of an example rotary-piston type actuator with a central actuation assembly.

[0059] FIG. 29B is a top view of the actuator of FIG 29A.

[0060] FIG. 29C is a perspective view from the right side and above illustrating the actuator of FIG. 29A with a portion of the central actuation assembly removed for illustration purposes.

[0061] FIG. 29D is a lateral cross section view taken at section AA of the
5 actuator of Fig 29B.

[0062] FIG. 29E is a partial perspective view from cross section AA of FIG. 29B.

[0063] FIG. 30A is a perspective view from above of an example rotary actuator with a central actuation assembly.

10 [0064] FIG. 30B is another perspective view from above of the example rotary actuator of FIG. 30A.

[0065] FIG. 30C is a top view of the example rotary actuator of FIG. 30A.

[0066] FIG. 30D is an end view of the example rotary actuator of FIG. 30A.

[0067] FIG. 30E is a partial perspective view from cross section AA of FIG.
15 30C.

[0068] FIG. 31A is a perspective view from above of another example rotary actuator with a central actuation assembly.

[0069] FIG. 31B is another perspective view from above of the example rotary actuator of FIG. 31A.

20 [0070] FIG. 31C is a top view of the example rotary actuator of FIG. 31A.

[0071] FIG. 31D is an end view of the example rotary actuator of FIG. 31A.

[0072] FIG. 31E is a partial perspective view from cross section AA of FIG. 31C.

DETAILED DESCRIPTION

[0073] This document describes devices for producing rotary motion. In particular, this document describes devices that can convert fluid displacement
5 into rotary motion through the use of components more commonly used for producing linear motion, e.g., hydraulic or pneumatic linear cylinders. Vane-type rotary actuators are relatively compact devices used to convert fluid motion into rotary motion. Rotary vane actuators (RVA), however, generally use seals and component configurations that exhibit cross-vane leakage of the
10 driving fluid. Such leakage can affect the range of applications in which such designs can be used. Some applications may require a rotary actuator to hold a rotational load in a selected position for a predetermined length of time, substantially without rotational movement (e.g., less than 5 degrees of movement), when the actuator's fluid ports are blocked. For example, some
15 aircraft applications may require that an actuator hold a flap or other control surface that is under load (e.g., through wind resistance, gravity or g-forces) at a selected position when the actuator's fluid ports are blocked. Cross-vane leakage, however, can allow movement from the selected position.

[0074] Linear pistons use relatively mature sealing technology that exhibits
20 well-understood dynamic operation and leakage characteristics that are generally better than rotary vane actuator type seals. Linear pistons, however, require additional mechanical components in order to adapt their linear motions to rotary motions. Such linear-to-rotary mechanisms are generally larger and heavier than rotary vane actuators that are capable of providing

similar rotational actions, e.g., occupying a larger work envelope. Such linear-to-rotary mechanisms may also generally be installed in an orientation that is different from that of the load they are intended to drive, and therefore may provide their torque output indirectly, e.g., installed to push or pull a lever arm
5 that is at a generally right angle to the axis of the axis of rotation of the lever arm. Such linear-to-rotary mechanisms may therefore become too large or heavy for use in some applications, such as aircraft control where space and weight constraints may make such mechanisms impractical for use.

[0075] In general, rotary piston assemblies use curved pressure chambers

10 and curved pistons to controllably push and pull the rotor arms of a rotor assembly about an axis. In use, certain embodiments of the rotary piston assemblies described herein can provide the positional holding characteristics generally associated with linear piston-type fluid actuators, to rotary applications, and can do so using the relatively more compact and lightweight
15 envelopes generally associated with rotary vane actuators.

[0076] FIGs. 1-3 show various views of the components of an example rotary piston-type actuator 100. Referring to FIG. 1, a perspective view of the example rotary piston-type actuator 100 is shown. The actuator 100 includes a rotary piston assembly 200 and a pressure chamber assembly 300. The
20 actuator 100 includes a first actuation section 110 and a second actuation section 120. In the example of actuator 100, the first actuation section 110 is configured to rotate the rotary piston assembly 200 in a first direction, e.g., counter-clockwise, and the second actuation section 120 is configured to

rotate the rotary piston assembly 200 in a second direction opposite the first direction, e.g., clockwise.

[0077] Referring now to FIG. 2, a perspective view of the example rotary piston assembly 200 is shown apart from the pressure chamber assembly 300.

5 The rotary piston assembly 200 includes a rotor shaft 210. A plurality of rotor arms 212 extend radially from the rotor shaft 210, the distal end of each rotor arm 212 including a bore (not shown) aligned within +/- 5 degrees the axis of the rotor shaft 210 and sized to accommodate one of the collection of connector pins 214.

10 **[0078]** As shown in FIG. 2, the first actuation section 110 includes a pair of rotary pistons 250, and the second actuation section 120 includes a pair of rotary pistons 260. While the example actuator 100 includes two pairs of the rotary pistons 250, 260, other embodiments can include greater and/or lesser numbers of cooperative and opposing rotary pistons. Examples of other such
15 embodiments will be discussed below, for example, in the descriptions of FIGs. 4-25.

[0079] In the example rotary piston assembly shown in FIG. 2, each of the rotary pistons 250, 260 includes a piston end 252 and one or more connector arms 254. The piston end 252 is formed to have a generally semi-circular
20 body having a substantially smooth surface (e.g., a surface quality that can form a fluid barrier when in contact with a seal). Each of the connector arms 254 includes a bore 256 substantially aligned (e.g., +/- two degrees) with the axis of the semi-circular body of the piston end 252 and sized to accommodate one of the connector pins 214.

[0080] The rotary pistons 260 in the example assembly of FIG. 2 are oriented opposite each other in the same rotational direction. The rotary pistons 250 are oriented opposite each other in the same rotational direction, but opposite that of the rotary pistons 260. In some embodiments, the actuator
5 100 can rotate the rotor shaft 210 about 60 degrees total (e.g., 50-70 degrees).

[0081] Each of the rotary pistons 250, 260 of the example assembly of FIG. 2 may be assembled to the rotor shaft 210 by aligning the connector arms 254 with the rotor arms 212 such that the bores (not shown) of the rotor arms 212 align with the bores 265. The connector pins 214 may then be inserted
10 through the aligned bores to create hinged connections between the pistons 250, 260 and the rotor shaft 210. Each connector pin 214 is slightly longer than the aligned bores. In the example assembly, about the circumferential periphery of each end of each connector pin 214 that extends beyond the aligned bores is a circumferential recess (not shown) that can accommodate a
15 retaining fastener (not shown), e.g., a snap ring or spiral ring.

[0082] FIG. 3 is a perspective cross-sectional view of the example rotary piston-type actuator 100. The illustrated example shows the rotary pistons 260 inserted into a corresponding pressure chamber 310 formed as an arcuate cavity in the pressure chamber assembly 300. The rotary pistons 250 are also
20 inserted into corresponding pressure chambers 310, not visible in this view.

[0083] In the example actuator 100, each pressure chamber 310 includes a seal assembly 320 about the interior surface of the pressure chamber 310 at an open end 330. In some implementations, the seal assembly 320 can be a circular or semi-circular sealing geometry retained on all sides in a standard

- seal groove. In some implementations, commercially available reciprocating piston or cylinder type seals can be used. For example, commercially available seal types that may already be in use for linear hydraulic actuators flying on current aircraft may demonstrate sufficient capability for linear load and
- 5 position holding applications. In some implementations, the sealing complexity of the actuator 100 may be reduced by using a standard, e.g., commercially available, semi-circular, unidirectional seal designs generally used in linear hydraulic actuators. In some embodiments, the seal assembly 320 can be a one-piece seal.
- 10 **[0084]** In some embodiments of the example actuator 100, the seal assembly 320 may be included as part of the rotary pistons 250, 260. For example, the seal assembly 320 may be located near the piston end 252, opposite the connector arm 254, and slide along the interior surface of the pressure chamber 310 to form a fluidic seal as the rotary piston 250, 260
- 15 moves in and out of the pressure chamber 310. An example actuator that uses such piston-mounted seal assemblies will be discussed in the descriptions of FIGs. 26-28. In some embodiments, the seal 310 can act as a bearing. For example, the seal assembly 320 may provide support for the piston 250, 260 as it moves in and out of the pressure chamber 310.
- 20 **[0085]** In some embodiments, the actuator 100 may include a wear member between the piston 250, 260 and the pressure chamber 310. For example, a wear ring may be included in proximity to the seal assembly 320. The wear ring may act as a pilot for the piston 250, 260, and/or act as a bearing providing support for the piston 250, 260.

[0086] In the example actuator 100, when the rotary pistons 250, 260 are inserted through the open ends 330, each of the seal assemblies 320 contacts the interior surface of the pressure chamber 310 and the substantially smooth surface of the piston end 252 to form a substantially pressure-sealed region within the pressure chamber 310 (e.g., less than 10% leakage rate per hour). Each of the pressure chambers 310 may include a fluid port 312 formed through the pressure chamber assembly 300, through which pressurized fluid may flow. Upon introduction of pressurized fluid, e.g., hydraulic oil, water, air, gas, into the pressure chambers 310, the pressure differential between the interior of the pressure chambers 310 and the ambient conditions outside the pressure chambers 310 causes the piston ends 252 to be urged outward from the pressure chambers 310. As the piston ends 252 are urged outward, the pistons 250, 260 urge the rotary piston assembly 200 to rotate.

[0087] In the example of the actuator 100, cooperative pressure chambers may be fluidically connected by internal or external fluid ports. For example, the pressure chambers 310 of the first actuation section 110 may be fluidically interconnected to balance the pressure between the pressure chambers 310. Similarly the pressure chambers 310 of the second actuation section 120 may be fluidically interconnected to provide similar pressure balancing. In some embodiments, the pressure chambers 310 may be fluidically isolated from each other. For example, the pressure chambers 310 may each be fed by an independent supply of pressurized fluid.

[0088] In the example of the actuator 100, the use of the alternating arcuate, e.g., curved, rotary pistons 250, 260 arranged substantially opposing

each other (e.g., +/- 5 degrees) operates to translate the rotor arms in an arc-shaped path about the axis of the rotary piston assembly 200, thereby rotating the rotor shaft 210 clockwise and counter-clockwise in a substantially torque balanced arrangement. Each cooperative pair of pressure chambers 310
5 operates uni-directionally in pushing the respective rotary piston 250 outward, e.g., extension, to drive the rotor shaft 210 in the specific direction. To reverse direction, the opposing cylinder section's 110 pressure chambers 260 are pressurized to extend their corresponding rotary pistons 260 outward.

[0089] The pressure chamber assembly 300, as shown, includes a
10 collection of openings 350. In general, the openings 350 provide space in which the rotor arms 212 can move when the rotor shaft 210 is partly rotated. In some implementations, the openings 350 can be formed to remove material from the pressure chamber assembly 300, e.g., to reduce the mass of the pressure chamber assembly 300. In some implementations, the openings 350
15 can be used during the process of assembly of the actuator 100. For example, the actuator 100 can be assembled by inserting the rotary pistons 250, 260 through the openings 350 such that the piston ends 252 are inserted into the pressure chambers 310. With the rotary pistons 250, 260 inserted into the pressure chambers 310, the rotor shaft 210 can be assembled to (e.g.,
20 rotatably journaled within) the actuator 100 by aligning the rotor shaft 210 with an axial bore 360 formed along the axis of the pressure chamber assembly 300, and by aligning the rotor arms 212 with a collection of keyways 362 formed along the axis of the pressure chamber assembly 300. The rotor shaft 210 can then be inserted into the pressure chamber assembly 300. The rotary

pistons 250, 260 can be partly extracted from the pressure chambers 310 to substantially (e.g., +/- 5 degrees) align the bores 256 with the bores of the rotor arms 212. The connector pins 214 can then be passed through the keyways 362 and the aligned bores to connect the rotary pistons 250, 260 to the rotor shaft 210. The connector pins 214 can be secured longitudinally by inserting retaining fasteners through the openings 350 and about the ends of the connector pins 214. The rotor shaft 210 can be connected to an external mechanism as an output shaft in order to transfer the rotary motion of the actuator 100 to other mechanisms. A bushing or bearing 362 is fitted between the rotor shaft 210 and the axial bore 360 at each end of the pressure chamber assembly 300.

[0090] In some embodiments, the rotary pistons 250, 260 may urge rotation of the rotor shaft 210 by contacting the rotor arms 212. For example, the piston ends 252 may not be coupled to the rotor arms 212. Instead, the piston ends 252 may contact the rotor arms 212 to urge rotation of the rotor shaft as the rotary pistons 250, 260 are urged outward from the pressure chambers 310. Conversely, the rotor arms 212 may contact the piston ends 252 to urge the rotary pistons 250, 260 back into the pressure chambers 310.

[0091] In some embodiments, a rotary position sensor assembly (not shown) may be included in the actuator 100. For example, an encoder may be used to sense the rotational position of the rotor shaft 210 relative to the pressure chamber assembly or another feature that remains substantially stationary (e.g., +/- 5 degrees) relative to the rotation of the shaft 210. In some implementations, the rotary position sensor may provide signals that indicate

the position of the rotor shaft 210 to other electronic or mechanical modules, e.g., a position controller.

[0092] In use, pressurized fluid in the example actuator 100 can be applied to the pressure chambers 310 of the second actuation section 120 through the fluid ports 312. The fluid pressure urges the rotary pistons 260 out of the pressure chambers 310. This movement urges the rotary piston assembly 200 to rotate clockwise. Pressurized fluid can be applied to the pressure chambers 310 of the first actuation section 110 through the fluid ports 312. The fluid pressure urges the rotary pistons 250 out of the pressure chambers 310. This movement urges the rotary piston assembly 200 to rotate counter-clockwise. The fluid conduits can also be blocked fluidically to cause the rotary piston assembly 200 to substantially maintain its rotary position relative to the pressure chamber assembly 300 (e.g., stay within 5 degrees of the selected position).

[0093] In some embodiments of the example actuator 100, the pressure chamber assembly 300 can be formed from a single piece of material. For example, the pressure chambers 310, the openings 350, the fluid ports 312, the keyways 362, and the axial bore 360 may be formed by molding, machining, or otherwise forming a unitary piece of material.

[0094] FIG. 4 is a perspective view of another example rotary piston-type actuator 400. In general, the actuator 400 is similar to the actuator 100, but instead of using opposing pairs of rotary pistons 250, 260, each acting unidirectionally to provide clockwise and counter-clockwise rotation, the actuator 400 uses a pair of bidirectional rotary pistons.

[0095] As shown in FIG. 4, the actuator 400 includes a rotary piston assembly that includes a rotor shaft 412 and a pair of rotary pistons 414. The rotor shaft 412 and the rotary pistons 414 are connected by a pair of connector pins 416.

- 5 **[0096]** The example actuator shown in FIG. 4 includes a pressure chamber assembly 420. The pressure chamber assembly 420 includes a pair of pressure chambers 422 formed as arcuate cavities in the pressure chamber assembly 420. Each pressure chamber 422 includes a seal assembly 424 about the interior surface of the pressure chamber 422 at an open end 426.
- 10 The seal assemblies 424 contact the inner walls of the pressure chambers 422 and the rotary pistons 414 to form fluidic seals between the interiors of the pressure chambers 422 and the space outside. A pair of fluid ports 428 is in fluidic communication with the pressure chambers 422. In use, pressurized fluid can be applied to the fluid ports 428 to urge the rotary pistons 414 partly
- 15 out of the pressure chambers 422, and to urge the rotor shaft 412 to rotate in a first direction, e.g., clockwise in this example.

- [0097]** The pressure chamber assembly 420 and the rotor shaft 412 and rotary pistons 414 of the rotary piston assembly may be structurally similar to corresponding components found in the second actuation section 120 of the
- 20 actuator 100. In use, the example actuator 400 also functions similarly to the actuator 100 when rotating in a first direction when the rotary pistons 414 are being urged outward from the pressure chambers 422. e.g., clockwise in this example. As will be discussed next, the actuator 400 differs from the actuator

100 in the way that the rotor shaft 412 is made to rotate in a second direction, e.g., counter-clockwise in this example.

[0098] To provide actuation in the second direction, the example actuator 400 includes an outer housing 450 with a bore 452. The pressure chamber assembly 420 is formed to fit within the bore 452. The bore 452 is fluidically sealed by a pair of end caps (not shown). With the end caps in place, the bore 452 becomes a pressurizable chamber. Pressurized fluid can flow to and from the bore 452 through a fluid port 454. Pressurized fluid in the bore 452 is separated from fluid in the pressure chambers 422 by the seals 426.

10 **[0099]** Referring now to FIG. 5, the example actuator 400 is shown in a first configuration in which the rotor shaft 412 has been rotated in a first direction, e.g., clockwise, as indicated by the arrows 501. The rotor shaft 412 can be rotated in the first direction by flowing pressurized fluid into the pressure chambers 422 through the fluid ports 428, as indicated by the arrows 502. The pressure within the pressure chambers 422 urges the rotary pistons 414 partly outward from the pressure chambers 422 and into the bore 452. Fluid within the bore 452, separated from the fluid within the pressure chambers 422 by the seals 424 and displaced by the movement of the rotary pistons 414, is urged to flow out the fluid port 454, as indicated by the arrow 503.

20 **[00100]** Referring now to FIG. 6, the example actuator 400 is shown in a second configuration in which the rotor shaft 412 has been rotated in a second direction, e.g., counter-clockwise, as indicated by the arrows 601. The rotor shaft 412 can be rotated in the second direction by flowing pressurized fluid into the bore 452 through the fluid port 454, as indicated by the arrow 602.

The pressure within the bore 452 urges the rotary pistons 414 partly into the pressure chambers 422 from the bore 452. Fluid within the pressure chambers 422, separated from the fluid within the bore 452 by the seals 424 and displaced by the movement of the rotary pistons 414, is urged to flow out
5 the fluid ports 428, as indicated by the arrows 603. In some embodiments, one or more of the fluid ports 428 and 454 can be oriented radially relative to the axis of the actuator 400, as illustrated in FIGs. 4-6, however in some embodiments one or more of the fluid ports 428 and 454 can be oriented parallel to the axis of the actuator 400 or in any other appropriate orientation.

10 **[00101]** FIG. 7 is a perspective view of another embodiment of a rotary piston assembly 700. In the example actuator 100 of FIG. 1, two opposing pairs of rotary pistons were used, but in other embodiments other numbers and configurations of rotary pistons and pressure chambers can be used. In the example of the assembly 700, a first actuation section 710 includes four
15 rotary pistons 712 cooperatively operable to urge a rotor shaft 701 in a first direction. A second actuation section 720 includes four rotary pistons 722 cooperatively operable to urge the rotor shaft 701 in a second direction.

[00102] Although examples using four rotary pistons, e.g., actuator 100, and eight rotary pistons, e.g., assembly 700, have been described, other
20 configurations may exist. In some embodiments, any appropriate number of rotary pistons may be used in cooperation and/or opposition. In some embodiments, opposing rotary pistons may not be segregated into separate actuation sections, e.g., the actuation sections 710 and 720. While cooperative pairs of rotary pistons are used in the examples of actuators 100,

400, and assembly 700, other embodiments exist. For example, clusters of two, three, four, or more cooperative or oppositional rotary pistons and pressure chambers may be arranged radially about a section of a rotor shaft.

As will be discussed in the descriptions of FIGs. 8-10, a single rotary piston

5 may be located at a section of a rotor shaft. In some embodiments, cooperative rotary pistons may be interspersed alternately with opposing rotary pistons. For example, the rotary pistons 712 may alternate with the rotary pistons 722 along the rotor shaft 701.

[00103] FIG. 8 is a perspective view of another example of a rotary piston-
10 type actuator 800. The actuator 800 differs from the example actuators 100 and 400, and the example assembly 700 in that instead of implementing cooperative pairs of rotary pistons along a rotor shaft, e.g., two of the rotary pistons 250 are located radially about the rotor shaft 210, individual rotary pistons are located along a rotor shaft.

15 **[00104]** The example actuator 800 includes a rotor shaft 810 and a pressure chamber assembly 820. The actuator 800 includes a first actuation section 801 and a second actuation section 802. In the example actuator 800, the first actuation section 801 is configured to rotate the rotor shaft 810 in a first direction, e.g., clockwise, and the second actuation section 802 is configured
20 to rotate the rotor shaft 810 in a second direction opposite the first direction, e.g., counter-clockwise.

[00105] The first actuation section 801 of example actuator 800 includes a rotary piston 812, and the second actuation section 802 includes a rotary piston 822. By implementing a single rotary piston 812, 822 at a given

longitudinal position along the rotor shaft 810, a relatively greater range of rotary travel may be achieved compared to actuators that use pairs of rotary pistons at a given longitudinal position along the rotary piston assembly, e.g., the actuator 100. In some embodiments, the actuator 800 can rotate the rotor
5 shaft 810 about 145 degrees total (e.g., 135-155 degrees).

[00106] In some embodiments, the use of multiple rotary pistons 812, 822 along the rotor shaft 810 can reduce distortion of the pressure chamber assembly 820, e.g., reduce bowing out under high pressure. In some embodiments, the use of multiple rotary pistons 812, 822 along the rotor shaft
10 810 can provide additional degrees of freedom for each piston 812, 822. In some embodiments, the use of multiple rotary pistons 812, 822 along the rotor shaft 810 can reduce alignment issues encountered during assembly or operation. In some embodiments, the use of multiple rotary pistons 812, 822 along the rotor shaft 810 can reduce the effects of side loading of the rotor
15 shaft 810.

[00107] FIG. 9 shows the example actuator 800 with the rotary piston 812 in an extended configuration. A pressurized fluid is applied to a fluid port 830 to pressurize an arcuate pressure chamber 840 formed in the pressure chamber assembly 820. Pressure in the pressure chamber 840 urges the rotary piston
20 812 partly outward, urging the rotor shaft 810 to rotate in a first direction, e.g., clockwise.

[00108] FIG. 10 shows the example actuator 800 with the rotary piston 812 in a retracted configuration. Mechanical rotation of the rotor shaft 810, e.g., pressurization of the actuation section 820, urges the rotary piston 812 partly

inward, e.g., clockwise. Fluid in the pressure chamber 840 displaced by the rotary piston 812 flows out through the fluid port 830.

[00109] The example actuator 800 can be assembled by inserting the rotary piston 812 into the pressure chamber 840. Then the rotor shaft 810 can be inserted longitudinally through a bore 850 and a keyway 851. The rotary piston 812 is connected to the rotor shaft 810 by a connecting pin 852.

[00110] FIG. 11 is a perspective view of another example of a rotary piston-type actuator 1100. In general, the actuator 1100 is similar to the example actuator 800, except multiple rotary pistons are used in each actuation section.

[00111] The example actuator 1100 includes a rotary piston assembly 1110 and a pressure chamber assembly 1120. The actuator 1100 includes a first actuation section 1101 and a second actuation section 1102. In the example of actuator 1100, the first actuation section 1101 is configured to rotate the rotary piston assembly 1110 in a first direction, e.g., clockwise, and the second actuation section 1102 is configured to rotate the rotary piston assembly 1110 in a second direction opposite the first direction, e.g., counter-clockwise.

[00112] The first actuation section 1101 of example actuator 1100 includes a collection of rotary pistons 812, and the second actuation section 1102 includes a collection of rotary pistons 822. By implementing individual rotary pistons 812, 822 at various longitudinal positions along the rotary piston assembly 1110, a range of rotary travel similar to the actuator 800 may be achieved. In some embodiments, the actuator 1100 can rotate the rotor shaft 1110 about 60 degrees total (e.g., 50-70 degrees).

[00113] In some embodiments, the use of the collection of rotary pistons 812 may provide mechanical advantages in some applications. For example, the use of multiple rotary pistons 812 may reduce stress or deflection of the rotary piston assembly, may reduce wear of the seal assemblies, or may provide
5 more degrees of freedom. In another example, providing partitions, e.g., webbing, between chambers can add strength to the pressure chamber assembly 1120 and can reduce bowing out of the pressure chamber assembly 1120 under high pressure. In some embodiments, placement of an end tab on the rotor shaft assembly 1110 can reduce cantilever effects experienced by the
10 actuator 800 while under load, e.g., less stress or bending.

[00114] FIGs. 12-14 are perspective and cross-sectional views of another example rotary piston-type actuator 1200. The actuator 1200 includes a rotary piston assembly 1210, a first actuation section 1201, and a second actuation section 1202.

15 **[00115]** The rotary piston assembly 1210 of example actuator 1200 includes a rotor shaft 1212, a collection of rotor arms 1214, and a collection of dual rotary pistons 1216. Each of the dual rotary pistons 1216 includes a connector section 1218 a piston end 1220a and a piston end 1220b. The piston ends 1220a-1220b are arcuate in shape, and are oriented opposite to each other in
20 a generally semicircular arrangement, and are joined at the connector section 1218. A bore 1222 is formed in the connector section 1218 and is oriented substantially parallel (e.g., +/- 5 degrees) to the axis of the semicircle formed by the piston ends 1220a-1220b. The bore 1222 is sized to accommodate a connector pin (not shown) that is passed through the bore 1222 and a

collection of bores 1224 formed in the rotor arms 1213 to secure each of the dual rotary pistons 1216 to the rotor shaft 1212.

[00116] The first actuation section 1201 of example actuator 1200 includes a first pressure chamber assembly 1250a, and the second actuation section
5 1202 includes a second pressure chamber assembly 1250b. The first pressure chamber assembly 1250a includes a collection of pressure chambers 1252a formed as arcuate cavities in the first pressure chamber assembly 1250a. The second pressure chamber assembly 1250b includes a collection of pressure chambers 1252b formed as arcuate cavities in the first pressure
10 chamber assembly 1250b. When the pressure chamber assemblies 1250a-1250b are assembled into the actuator 1200, each of the pressure chambers 1252a lies generally in a plane with a corresponding one of the pressure chambers 1252b, such that a pressure chamber 1252a and a pressure chamber 1252b occupy two semicircular regions about a central axis. A
15 semicircular bore 1253a and a semicircular bore 1253b substantially align (e.g., +/- 5 degrees) to accommodate the rotor shaft 1212.

[00117] Each of the pressure chambers 1252a-1252b of example actuator 1200 includes an open end 1254 and a seal assembly 1256. The open ends 1254 are formed to accommodate the insertion of the piston ends 1220a-
20 1220b. The seal assemblies 1256 contact the inner walls of the pressure chambers 1252a-1252b and the outer surfaces of the piston ends 1220a-1220b to form a fluidic seal.

[00118] The rotary piston assembly 1210 of example actuator 1200 can be assembled by aligning the bores 1222 of the dual rotary pistons 1216 with the

bores 1224 of the rotor arms 1214. The connector pin (not shown) is passed through the bores 1222 and 1224 and secured longitudinally by retaining fasteners.

[00119] The example actuator 1200 can be assembled by positioning the
5 rotor shaft 1212 at least partly within the semicircular bore 1253a and rotating it to insert the piston ends 1220a substantially fully into the pressure chambers 1252a. The second pressure chamber 1252b is positioned abutting the first pressure chamber 1252a such that the rotor shaft 1212 is positioned at least partly within the semicircular bore 1253b. The rotary piston assembly 1210 is
10 then rotated to partly insert the piston ends 1220b into the pressure chambers 1252b. An end cap 1260 is fastened to the longitudinal ends 1262a of the pressure chambers 1252a-1252b. A second end cap (not shown) is fastened to the longitudinal ends 1262b of the pressure chambers 1252a-1252b. The end caps substantially maintain the positions of the rotary piston assembly
15 1210 and the pressure chambers 1252a-1252b relative to each other (e.g., +/- 2 degrees of rotation). In some embodiments, the actuator 1200 can provide about 90 degrees (e.g., 80-100 degrees) of total rotational stroke.

[00120] In operation, pressurized fluid is applied to the pressure chambers 1252a of example actuator 1200 to rotate the rotary piston assembly 1210 in a
20 first direction, e.g., clockwise. Pressurized fluid is applied to the pressure chambers 1252b to rotate the rotary piston assembly 1210 in a second direction, e.g., counter-clockwise.

[00121] FIGs. 15 and 16 are perspective and cross-sectional views of another example rotary piston-type actuator 1500 that includes another

example rotary piston assembly 1501. In some embodiments, the assembly 1501 can be an alternative embodiment of the rotary piston assembly 200 of FIG. 2.

[00122] The assembly 1501 of example actuator 1500 includes a rotor shaft 1510 connected to a collection of rotary pistons 1520a and a collection of rotary pistons 1520b by a collection of rotor arms 1530 and one or more connector pins (not shown). The rotary pistons 1520a and 1520b are arranged along the rotor shaft 1510 in a generally alternating pattern, e.g., one rotary piston 1520a, one rotary piston 1520b, one rotary piston 1520a, one rotary piston 1520b. In some embodiments, the rotary pistons 1520a and 1520b may be arranged along the rotor shaft 1510 in a generally intermeshed pattern, e.g., one rotary piston 1520a and one rotary piston 1520b rotationally parallel to each other, with connector portions formed to be arranged side-by-side or with the connector portion of rotary piston 1520a formed to one or more male protrusions and/or one or more female recesses to accommodate one or more corresponding male protrusions and/or one or more corresponding female recesses formed in the connector portion of the rotary piston 1520b.

[00123] Referring to FIG. 16, a pressure chamber assembly 1550 of example actuator 1500 includes a collection of arcuate pressure chambers 1555a and a collection of arcuate pressure chambers 1555b. The pressure chambers 1555a and 1555b are arranged in a generally alternating pattern corresponding to the alternating pattern of the rotary pistons 1520a-1520b. The rotary pistons 1520a-1520b extend partly into the pressure chambers 1555a-1555b. A seal assembly 1560 is positioned about an open end 1565 of

each of the pressure chambers 1555a-1555b to form fluidic seals between the inner walls of the pressure chambers 1555a-1555b and the rotary pistons 1520a-1520b.

[00124] In use, pressurized fluid can be alternatingly provided to the

5 pressure chambers 1555a and 1555b of example actuator 1500 to urge the rotary piston assembly 1501 to rotate partly clockwise and counterclockwise. In some embodiments, the actuator 1500 can rotate the rotor shaft 1510 about 92 degrees total (e.g., 82-102 degrees).

[00125] FIGs. 17 and 18 are perspective and cross-sectional views of

10 another example rotary piston-type actuator 1700 that includes another example rotary piston assembly 1701. In some embodiments, the assembly 1701 can be an alternative embodiment of the rotary piston assembly 200 of FIG. 2 or the assembly 1200 of FIG. 12.

[00126] The assembly 1701 of example actuator 1700 includes a rotor shaft

15 1710 connected to a collection of rotary pistons 1720a by a collection of rotor arms 1730a and one or more connector pins 1732. The rotor shaft 1710 is also connected to a collection of rotary pistons 1720b by a collection of rotor arms 1730b and one or more connector pins 1732. The rotary pistons 1720a and 1720b are arranged along the rotor shaft 1710 in a generally opposing, 20 symmetrical pattern, e.g., one rotary piston 1720a is paired with one rotary piston 1720b at various positions along the length of the assembly 1701.

[00127] Referring to FIG. 18, a pressure chamber assembly 1750 of

example actuator 1700 includes a collection of arcuate pressure chambers 1755a and a collection of arcuate pressure chambers 1755b. The pressure

chambers 1755a and 1755b are arranged in a generally opposing, symmetrical pattern corresponding to the symmetrical arrangement of the rotary pistons 1720a-1720b. The rotary pistons 1720a-1720b extend partly into the pressure chambers 1755a-1755b. A seal assembly 1760 is positioned about an open
5 end 1765 of each of the pressure chambers 1755a-1755b to form fluidic seals between the inner walls of the pressure chambers 1755a-1755b and the rotary pistons 1720a-1720b.

[00128] In use, pressurized fluid can be alternatingly provided to the pressure chambers 1755a and 1755b of example actuator 1700 to urge the
10 rotary piston assembly 1701 to rotate partly clockwise and counterclockwise. In some embodiments, the actuator 1700 can rotate the rotor shaft 1710 about 52 degrees total (e.g., 42-62 degrees).

[00129] FIGs. 19 and 20 are perspective and cross-sectional views of another example rotary piston-type actuator 1900. Whereas the actuators
15 described previously, e.g., the example actuator 100 of FIG. 1, are generally elongated and cylindrical, the actuator 1900 is comparatively flatter and more disk-shaped.

[00130] Referring to FIG. 19, a perspective view of the example rotary piston-type actuator 1900 is shown. The actuator 1900 includes a rotary
20 piston assembly 1910 and a pressure chamber assembly 1920. The rotary piston assembly 1910 includes a rotor shaft 1912. A collection of rotor arms 1914 extend radially from the rotor shaft 1912, the distal end of each rotor arm 1914 including a bore 1916 aligned substantially parallel (e.g., +/- 5 degrees)

with the axis of the rotor shaft 1912 and sized to accommodate one of a collection of connector pins 1918.

[00131] The rotary piston assembly 1910 of example actuator 1900 includes a pair of rotary pistons 1930 arranged substantially symmetrically opposite each other (e.g., +/- 20 degrees) across the rotor shaft 1912. In the example of the actuator 1900, the rotary pistons 1930 are both oriented in the same rotational direction, e.g., the rotary pistons 1930 cooperatively push in the same rotational direction. In some embodiments, a return force may be provided to rotate the rotary piston assembly 1910 in the direction of the rotary pistons 1930. For example, the rotor shaft 1912 may be coupled to a load that resists the forces provided by the rotary pistons 1930, such as a load under gravitational pull, a load exposed to wind or water resistance, a return spring, or any other appropriate load that can rotate the rotary piston assembly. In some embodiments, the actuator 1900 can include a pressurizable outer housing over the pressure chamber assembly 1920 to provide a back-drive operation, e.g., similar to the function provided by the outer housing 450 in FIG. 4. In some embodiments, the actuator 1900 can be rotationally coupled to an oppositely oriented actuator 1900 that can provide a back-drive operation.

[00132] In some embodiments, the rotary pistons 1930 can be oriented in opposite rotational directions, e.g., the rotary pistons 1930 can oppose each other push in the opposite rotational directions to provide bidirectional motion control. In some embodiments, the actuator 100 can rotate the rotor shaft about 60 degrees total (e.g., 50-70 degrees).

[00133] Each of the rotary pistons 1930 of example actuator 1900 includes a piston end 1932 and one or more connector arms 1934. The piston end 1932 is formed to have a generally semi-circular body having a substantially smooth surface. Each of the connector arms 1934 includes a bore 1936 (see FIGs.

5 21B and 21C) substantially aligned (e.g., +/- 5 degrees) with the axis of the semi-circular body of the piston end 1932 and sized to accommodate one of the connector pins 1918.

[00134] Each of the rotary pistons 1930 of example actuator 1900 is assembled to the rotor shaft 1912 by aligning the connector arms 1934 with
10 the rotor arms 1914 such that the bores 1916 of the rotor arms 1914 align with the bores 1936. The connector pins 1918 are inserted through the aligned bores to create hinged connections between the pistons 1930 and the rotor shaft 1912. Each connector pin 1916 is slightly longer than the aligned bores. About the circumferential periphery of each end of each connector pin 1916
15 that extends beyond the aligned bores is a circumferential recess (not shown) that can accommodate a retaining fastener (not shown), e.g., a snap ring or spiral ring.

[00135] Referring now to FIG. 20 a cross-sectional view of the example rotary piston-type actuator 1900 is shown. The illustrated example shows the
20 rotary pistons 1930 partly inserted into a corresponding pressure chamber 1960 formed as an arcuate cavity in the pressure chamber assembly 1920.

[00136] Each pressure chamber 1960 of example actuator 1900 includes a seal assembly 1962 about the interior surface of the pressure chamber 1960 at an open end 1964. In some embodiments, the seal assembly 1962 can be a

circular or semi-circular sealing geometry retained on all sides in a standard seal groove.

[00137] When the rotary pistons 1930 of example actuator 1900 are inserted through the open ends 1964, each of the seal assemblies 1962 contacts the interior surface of the pressure chamber 1960 and the substantially smooth surface of the piston end 1932 to form a substantially pressure-sealed region (e.g., less than 10% pressure loss per hour) within the pressure chamber 1960. Each of the pressure chambers 1960 each include a fluid port (not shown) formed through the pressure chamber assembly 1920, through with pressurized fluid may flow.

[00138] Upon introduction of pressurized fluid, e.g., hydraulic oil, water, air, gas, into the pressure chambers 1960 of example actuator 1900, the pressure differential between the interior of the pressure chambers 1960 and the ambient conditions outside the pressure chambers 1960 causes the piston ends 1932 to be urged outward from the pressure chambers 1960. As the piston ends 1932 are urged outward, the pistons 1930 urge the rotary piston assembly 1910 to rotate.

[00139] In the illustrated example actuator 1900, each of the rotary pistons 1930 includes a cavity 1966. FIGs. 21A-21C provide additional cross-sectional and perspective views of one of the rotary pistons 1930. Referring to FIG. 21A, a cross-section the rotary piston 1930, taken across a section of the piston end 1932 is shown. The cavity 1966 is formed within the piston end 1932. Referring to FIG. 21B, the connector arm 1934 and the bore 1936 is shown in perspective. FIG. 21C features a perspective view of the cavity 1966.

[00140] In some embodiments, the cavity 1966 may be omitted. For example, the piston end 1932 may be solid in cross-section. In some embodiments, the cavity 1966 may be formed to reduce the mass of the rotary piston 1930 and the mass of the actuator 1900. For example, the actuator

5 1900 may be implemented in an aircraft application, where weight may play a role in actuator selection. In some embodiments, the cavity 1966 may reduce wear on seal assemblies, such as the seal assembly 320 of FIG. 3. For example, by reducing the mass of the rotary piston 1930, the amount of force the piston end 1932 exerts upon the corresponding seal assembly may be

10 reduced when the mass of the rotary piston is accelerated, e.g., by gravity or G-forces.

[00141] In some embodiments, the cavity 1966 may be substantially hollow in cross-section, and include one or more structural members, e.g., webs, within the hollow space. For example, structural cross-members may extend

15 across the cavity of a hollow piston to reduce the amount by which the piston may distort, e.g., bowing out, when exposed to a high pressure differential across the seal assembly.

[00142] FIGs. 22 and 23 illustrate a comparison of two example rotor shaft embodiments. FIG. 22 is a perspective view of an example rotary piston-type

20 actuator 2200. In some embodiments, the example actuator 2200 can be the example actuator 1900.

[00143] The example actuator 2200 includes a pressure chamber assembly 2210 and a rotary piston assembly 2220. The rotary piston assembly 2220

includes at least one rotary piston 2222 and one or more rotor arms 2224. The rotor arms 2224 extend radially from a rotor shaft 2230.

[00144] The rotor shaft 2230 of example actuator includes an output section 2232 and an output section 2234 that extend longitudinally from the pressure chamber assembly 2210. The output sections 2232-2234 include a collection of splines 2236 extending radially from the circumferential periphery of the output sections 2232-2234. In some implementations, the output section 2232 and/or 2234 may be inserted into a correspondingly formed splined assembly to rotationally couple the rotor shaft 2230 to other mechanisms. For example, by rotationally coupling the output section 2232 and/or 2234 to an external assembly, the rotation of the rotary piston assembly 2220 may be transferred to urge the rotation of the external assembly.

[00145] FIG. 23 is a perspective view of another example rotary piston-type actuator 2300. The actuator 2300 includes the pressure chamber assembly 2210 and a rotary piston assembly 2320. The rotary piston assembly 2320 includes at least one of the rotary pistons 2222 and one or more of the rotor arms 2224. The rotor arms 2224 extend radially from a rotor shaft 2330.

[00146] The rotor shaft 2330 of example actuator 2300 includes a bore 2332 formed longitudinally along the axis of the rotor shaft 2330. The rotor shaft 2330 includes a collection of splines 2336 extending radially inward from the circumferential periphery of the bore 2332. In some embodiments, a correspondingly formed splined assembly may be inserted into the bore 2332 to rotationally couple the rotor shaft 2330 to other mechanisms.

[00147] FIG. 24 is a perspective view of another example rotary piston 2400.

In some embodiments, the rotary piston 2400 can be the rotary piston 250, 260, 414, 712, 812, 822, 1530a, 1530b, 1730a, 1730b, 1930 or 2222.

[00148] The example rotary piston 2400 includes a piston end 2410 and a
5 connector section 2420. The connector section 2420 includes a bore 2430 formed to accommodate a connector pin, e.g., the connector pin 214.

[00149] The piston end 2410 of example actuator 2400 includes an end taper 2440. The end taper 2440 is formed about the periphery of a terminal end 2450 of the piston end 2410. The end taper 2440 is formed at a radially
10 inward angle starting at the outer periphery of the piston end 2410 and ending at the terminal end 2450. In some implementations, the end taper 2440 can be formed to ease the process of inserting the rotary piston 2400 into a pressure chamber, e.g., the pressure chamber 310.

[00150] The piston end 2410 of example actuator 2400 is substantially
15 smooth. In some embodiments, the smooth surface of the piston end 2410 can provide a surface that can be contacted by a seal assembly. For example, the seal assembly 320 can contact the smooth surface of the piston end 2410 to form part of a fluidic seal, reducing the need to form a smooth, fluidically sealable surface on the interior walls of the pressure chamber 310.

[00151] In the illustrated example, the rotary piston 2400 is shown as having
20 a generally solid circular cross-section, whereas the rotary pistons piston 250, 260, 414, 712, 812, 822, 1530a, 1530b, 1730a, 1730b, 1930 or 2222 have been illustrated as having various generally rectangular, elliptical, and other shapes, both solid and hollow, in cross section. In some embodiments, the

cross sectional dimensions of the rotary piston 2400, as generally indicated by the arrows 2491 and 2492, can be adapted to any appropriate shape, e.g., square, rectangular, ovoid, elliptical, circular, and other shapes, both solid and hollow, in cross section.. In some embodiments, the arc of the rotary piston

5 2400, as generally indicated by the angle 2493, can be adapted to any appropriate length. In some embodiments, the radius of the rotary piston 2400, as generally indicated by the line 2494, can be adapted to any appropriate radius. In some embodiments, the piston end 2410 can be substantially solid, substantially hollow, or can include any appropriate hollow

10 formation. In some embodiments, any of the previously mentioned forms of the piston end 2410 can also be used as the piston ends 1220a and/or 1220b of the dual rotary pistons 1216 of FIG. 12.

[00152] FIG. 25 is a flow diagram of an example process 2500 for performing rotary actuation. In some implementations, the process 2500 can

15 be performed by the rotary piston-type actuators 100, 400, 700, 800, 1200, 1500, 1700, 1900, 2200, 2300, and/or 2600 which will be discussed in the descriptions of FIGs. 26-28.

[00153] At 2510, a rotary actuator is provided. The rotary actuator of example actuator 2500 includes a first housing defining a first arcuate chamber

20 including a first cavity, a first fluid port in fluid communication with the first cavity, an open end, and a first seal disposed about an interior surface of the open end, a rotor assembly rotatably journaled in the first housing and including a rotary output shaft and a first rotor arm extending radially outward from the rotary output shaft, an arcuate-shaped first piston disposed in the first

housing for reciprocal movement in the first arcuate chamber through the open end. The first seal, the first cavity, and the first piston define a first pressure chamber, and a first connector, coupling a first end of the first piston to the first rotor arm. For example, the actuator 100 includes the components of the

5 pressure chamber assembly 300 and the rotary piston assembly 200 included in the actuation section 120.

[00154] At 2520, a pressurized fluid is applied to the first pressure chamber. For example, pressurized fluid can be flowed through the fluid port 320 into the pressure chamber 310.

10 **[00155]** At 2530, the first piston is urged partially outward from the first pressure chamber to urge rotation of the rotary output shaft in a first direction. For example, a volume of pressurized fluid flowed into the pressure chamber 310 will displace a similar volume of the rotary piston 260, causing the rotary piston 260 to be partly urged out of the pressure cavity 310, which in turn will

15 cause the rotor shaft 210 to rotate clockwise.

[00156] At 2540, the rotary output shaft is rotated in a second direction opposite that of the first direction. For example, the rotor shaft 210 can be rotated counter-clockwise by an external force, such as another mechanism, a torque-providing load, a return spring, or any other appropriate source of

20 rotational torque.

[00157] At 2550, the first piston is urged partially into the first pressure chamber to urge pressurized fluid out the first fluid port. For example, the rotary piston 260 can be pushed into the pressure chamber 310, and the

volume of the piston end 252 extending into the pressure chamber 310 will displace a similar volume of fluid, causing it to flow out the fluid port 312.

[00158] In some embodiments, the example process 2500 can be used to provide substantially constant power over stroke to a connected mechanism.

5 For example, as the actuator 100 rotates, there may be substantially little position-dependent variation in the torque delivered to a connected load.

[00159] In some embodiments, the first housing further defines a second arcuate chamber comprising a second cavity, a second fluid port in fluid communication with the second cavity, and a second seal disposed about an interior surface of the open end, the rotor assembly also includes a second rotor arm, the rotary actuator also includes an arcuate-shaped second piston disposed in said housing for reciprocal movement in the second arcuate chamber, wherein the second seal, the second cavity, and the second piston define a second pressure chamber, and a second connector coupling a first end of the second piston to the second rotor arm. For example, the actuator 100 includes the components of the pressure chamber assembly 300 and the rotary piston assembly 200 included in the actuation section 110.

[00160] In some embodiments, the second piston can be oriented in the same rotational direction as the first piston. For example, the two pistons 260 are oriented to operate cooperatively in the same rotational direction. In some embodiments, the second piston can be oriented in the opposite rotational direction as the first piston. For example, the rotary pistons 250 are oriented to operate in the opposite rotational direction relative to the rotary pistons 260.

[00161] In some embodiments, the actuator can include a second housing and disposed about the first housing and having a second fluid port, wherein the first housing, the second housing, the seal, and the first piston define a second pressure chamber. For example, the actuator 400 includes the outer
5 housing 450 that substantially surrounds the pressure chamber assembly 420. Pressurized fluid in the bore 452 is separated from fluid in the pressure chambers 422 by the seals 426.

[00162] In some implementations, rotating the rotary output shaft in a second direction opposite that of the first direction can include applying pressurized
10 fluid to the second pressure chamber, and urging the second piston partially outward from the second pressure chamber to urge rotation of the rotary output shaft in a second direction opposite from the first direction. For example, pressurized fluid can be applied to the pressure chambers 310 of the first actuation section 110 to urge the rotary pistons 260 outward, causing the
15 rotor shaft 210 to rotate counter-clockwise.

[00163] In some implementations, rotating the rotary output shaft in a second direction opposite that of the first direction can include applying pressurized fluid to the second pressure chamber, and urging the first piston partially into the first pressure chamber to urge rotation of the rotary output shaft in a
20 second direction opposite from the first direction. For example, pressurized fluid can be flowed into the bore 452 at a pressure higher than that of fluid in the pressure chambers 422, causing the rotary pistons 414 to move into the pressure chambers 422 and cause the rotor shaft 412 to rotate counter-clockwise.

[00164] In some implementations, rotation of the rotary output shaft can urge rotation of the housing. For example, the rotary output shaft 412 can be held rotationally stationary and the housing 450 can be allowed to rotate, and application of pressurized fluid in the pressure chambers 422 can urge the rotary pistons 414 out of the pressure chambers 422, causing the housing 450 to rotate about the rotary output shaft 412.

[00165] FIGs. 26-28 show various views of the components of another example rotary piston-type actuator 2600. In general, the actuator 2600 is similar to the example actuator 100 of FIG. 1, except for the configuration of the seal assemblies. Whereas the seal assembly 320 in the example actuator 100 remains substantially stationary (e.g., +/- 5 degrees) relative to the pressure chamber 310 and is in sliding contact with the surface of the rotary piston 250, in the example actuator 2600, the seal configuration is comparatively reversed as will be described below.

[00166] Referring to FIG. 26, a perspective view of the example rotary piston-type actuator 2600 is shown. The actuator 2600 includes a rotary piston assembly 2700 and a pressure chamber assembly 2602. The actuator 2600 includes a first actuation section 2610 and a second actuation section 2620. In the example of actuator 2600, the first actuation section 2610 is configured to rotate the rotary piston assembly 2700 in a first direction, e.g., counter-clockwise, and the second actuation section 2620 is configured to rotate the rotary piston assembly 2700 in a second direction opposite the first direction, e.g., clockwise.

[00167] Referring now to FIG. 27, a perspective view of the example rotary piston assembly 2700 is shown apart from the pressure chamber assembly 2602. The rotary piston assembly 2700 includes a rotor shaft 2710. A plurality of rotor arms 2712 extend radially from the rotor shaft 2710, the distal end of
5 each rotor arm 2712 including a bore (not shown) substantially aligned (e.g., +/- 2 degrees) with the axis of the rotor shaft 2710 and sized to accommodate one of a collection of connector pins 2714.

[00168] As shown in FIG. 27, the first actuation section 2710 of example rotary piston assembly 2700 includes a pair of rotary pistons 2750, and the
10 second actuation section 2720 includes a pair of rotary pistons 2760. While the example actuator 2600 includes two pairs of the rotary pistons 2750, 2760, other embodiments can include greater and/or lesser numbers of cooperative and opposing rotary pistons.

[00169] In the example rotary piston assembly shown in FIG. 27, each of the
15 rotary pistons 2750, 2760 includes a piston end 2752 and one or more connector arms 2754. The piston end 252 is formed to have a generally semi-circular body having a substantially smooth surface. Each of the connector arms 2754 includes a bore 2756 substantially aligned (e.g., +/- 2 degrees) with the axis of the semi-circular body of the piston end 2752 and sized to
20 accommodate one of the connector pins 2714.

[00170] In some implementations, each of the rotary pistons 2750, 2760 includes a seal assembly 2780 disposed about the outer periphery of the piston ends 2752. In some implementations, the seal assembly 2780 can be a circular or semi-circular sealing geometry retained on all sides in a standard

seal groove. In some implementations, commercially available reciprocating piston or cylinder type seals can be used. For example, commercially available seal types that may already be in use for linear hydraulic actuators flying on current aircraft may demonstrate sufficient capability for linear load and position holding applications. In some implementations, the sealing complexity of the actuator 2600 may be reduced by using a standard, e.g., commercially available, semi-circular, unidirectional seal designs generally used in linear hydraulic actuators. In some embodiments, the seal assembly 2780 can be a one-piece seal.

10 **[00171]** FIG. 28 is a perspective cross-sectional view of the example rotary piston-type actuator 2600. The illustrated example shows the rotary pistons 2760 inserted into a corresponding pressure chamber 2810 formed as an arcuate cavity in the pressure chamber assembly 2602. The rotary pistons 2750 are also inserted into corresponding pressure chambers 2810, not visible
15 in this view.

[00172] In the example actuator 2600, when the rotary pistons 2750, 2760 are each inserted through an open end 2830 of each pressure chamber 2810, each seal assembly 2780 contacts the outer periphery of the piston end 2760 and the substantially smooth interior surface of the pressure chamber 2810 to
20 form a substantially pressure-sealed (e.g., less than 10% pressure drop per hour) region within the pressure chamber 2810.

[00173] In some embodiments, the seal 2780 can act as a bearing. For example, the seal 2780 may provide support for the piston 2750, 2760 as it moves in and out of the pressure chamber 310.

[00174] FIGs. 29A-29E are various views of another example rotary piston-type actuator 2900 with a central actuation assembly 2960. For a brief description of each drawing see the brief description of each of these drawings included at the beginning of the Description of the Drawings section of this document.

[00175] In general, the example rotary piston-type actuator 2900 is substantially similar to the example rotary piston-type actuator 1200 of FIGs. 12-14, where the example rotary piston-type actuator 2900 also includes a central actuation assembly 2960 and a central mounting assembly 2980.

Although the example rotary piston-type actuator 2900 is illustrated and described as modification of the example rotary piston-type actuator 1200, in some embodiments the example rotary piston-type actuator 2900 can implement features of any of the example rotary piston-type actuators 100, 400, 700, 800, 1200, 1500, 1700, 1900, 2200, 2300, and/or 2600 in a design that also implements the central actuation assembly 2960 and/or the central mounting assembly 2980.

[00176] The actuator 2900 includes a rotary actuator assembly 2910, a first actuation section 2901 and a second actuation section 2902. The rotary piston assembly 2910 includes a rotor shaft 2912, a collection of rotor arms 2914, and the collection of dual rotary pistons, e.g., the dual rotary pistons 1216 of FIGs. 12-14.

[00177] The first actuation section 2901 of example actuator 2900 includes a first pressure chamber assembly 2950a, and the second actuation section 2902 includes a second pressure chamber assembly 2950b. The first

pressure chamber assembly 2950a includes a collection of pressure chambers, e.g., the pressure chambers 1252a of FIGs. 12-14, formed as arcuate cavities in the first pressure chamber assembly 2950a. The second pressure chamber assembly 2950b includes a collection of pressure chambers, e.g., the pressure chambers 1252b of FIGs. 12-14, formed as arcuate cavities in the second pressure chamber assembly 2950b. A semicircular bore 2953 in the housing accommodates the rotor shaft 2912.

[00178] The central mounting assembly 2980 is formed as a radially projected portion 2981 of a housing of the second pressure chamber assembly 2950b. In some embodiments, the central mount point 2964 can be positioned at a location within the central 1/3 of the longitudinal length of the second pressure chamber assembly 2950b. The central mounting assembly 2980 provides a mounting point for removably affixing the example rotary piston-type actuator 2900 to an external surface, e.g., an aircraft frame. A collection of holes 2982 formed in the radially projected section 2981 accommodate the insertion of a collection of fasteners 2984, e.g., bolts, to removably affix the central mounting assembly 2980 to an external mounting feature 2990, e.g., a mounting point (bracket) on an aircraft frame.

[00179] The central actuation assembly 2960 includes a radial recess 2961 formed in a portion of an external surface of a housing of the first and the second actuation sections 2901, 2902 at a midpoint along a longitudinal axis AA to the example rotary piston-type actuator 2900. An external mounting bracket 2970 that may be adapted for attachment to an external mounting feature on a member to be actuated, (e.g., aircraft flight control surfaces) is

connected to an actuation arm 2962. The actuation arm 2962 extends through the recess 2961 and is removably attached to a central mount point 2964 formed in an external surface at a midpoint of the longitudinal axis of the rotor shaft 2912.

- 5 **[00180]** Referring more specifically to FIGs. 29D and 29E now, the example rotary piston-type actuator 2900 is shown in cutaway end and perspective views taken though a midpoint of the central actuation assembly 2960 and the central mounting assembly 2980 at the recess 2961. The actuation arm 2962 extends into the recess 2961 to contact the central mount point 2964 of the
- 10 rotor shaft 2912. The actuation arm 2962 is removably connected to the central mount point 2964 by a fastener 2966, e.g., bolt, that is passed through a pair of holes 2968 formed in the actuation arm 2962 and a hole 2965 formed through the central mount point 2964. A collection of holes 2969 are formed in a radially outward end of the actuation arm 2962. A collection of fasteners
- 15 2972, e.g., bolts, are passed through the holes 2969 and corresponding holes (not shown) formed in an external mounting feature (bracket) 2970. As mentioned above, the central actuation assembly 2960 connects the example rotary piston actuator 2900 to the external mounting feature 2970 to transfer rotational motion of the rotor assembly 2910 to equipment to be moved
- 20 (actuated), e.g., aircraft flight control surfaces.

[00181] In some embodiments, one of the central actuation assembly 2960 or the central mounting assembly 2980 can be used in combination with features of any of the example rotary piston-type actuators 100, 400, 700, 800, 1200, 1500, 1700, 1900, 2200, 2300, and/or 2600. For example, the example

rotary piston-type actuator 2900 may be mounted to a stationary surface through the central mounting assembly 2980, and provide actuation at one or both ends of the rotor shaft assembly 2910. In another example, the example rotary piston assembly 2900 may be mounted to a stationary surface through
5 non-central mounting points, and provide actuation at the central actuation assembly 2960.

[00182] FIGs. 30A-30E are various views of an example rotary actuator 3000 with a central actuation assembly 3060. For a brief description of each drawing see the brief description of each of these drawings included at the beginning of
10 the Description of the Drawings section of this document.

[00183] In general, the example rotary actuator 3000 is substantially similar to the rotary piston-type actuator 2900 of FIGs. 29A-29E, where the example rotary actuator 3000 also includes a central actuation assembly 3060 and a central mounting assembly 3080. In some embodiments, the example rotary
15 actuator 3000 can be a modification of the example rotary piston-type actuator 2900 in which rotational action can be performed by a mechanism other than a rotary piston-type actuator. For example, the example rotary actuator 3000 can include a rotary vane type actuator, a rotary fluid type actuator, an electromechanical actuator, a linear-to-rotary motion actuator, or combinations
20 of these or any other appropriate rotary actuator. Although the example rotary actuator 3000 is illustrated and described as modification of the example rotary piston-type actuator 2900, in some embodiments the example rotary actuator 3000 can implement features of any of the example rotary piston-type actuators 100, 400, 700, 800, 1200, 1500, 1700, 1900, 2200, 2300, 2600

and/or 2900 in a design that also implements the central actuation assembly 3060 and/or the central mounting assembly 3080.

[00184] The actuator 3000 includes a rotary actuator section 3010a and a rotary actuator section 3010b. In some embodiments, the rotary actuator
5 sections 3010a and 3010b can be rotary vane type actuators, a rotary fluid type actuators, electromechanical actuators, a linear-to-rotary motion actuators, or combinations of these or any other appropriate rotary actuators. The rotary actuator section 3010a includes a housing 3050a, and the rotary actuator section 3010b includes a housing 3050b. A rotor shaft 3012a runs
10 along the longitudinal axis of the rotary actuator section 3010a, and a rotor shaft 3012b runs along the longitudinal axis of the rotary actuator section 3010b.

[00185] The central mounting assembly 3080 is formed as a radially projected portion 3081 of the housings 3050a and 3050b. The central
15 mounting assembly 3080 provides a mounting point for removably affixing the example rotary actuator 3000 to an external surface or an external structural member, e.g., an aircraft frame, an aircraft control surface. A collection of holes 3082 formed in the radially projected section 3081 accommodate the insertion of a collection of fasteners (not shown), e.g., bolts, to removably affix
20 the central mounting assembly 3080 to an external mounting feature, e.g., the external mounting feature 2090 of FIG. 29, a mounting point (bracket) on an aircraft frame or control surface.

[00186] The central actuation assembly 3060 includes a radial recess 3061 formed in a portion of an external surfaces of the housings 3050a, 3050b at a

midpoint along a longitudinal axis AA to the example rotary actuator 3000. In some implementations, an external mounting bracket, such as the external mounting bracket 2970, may be adapted for attachment to an external mounting feature of a structural member or a member to be actuated, (e.g., aircraft flight control surfaces) can be connected to an actuation arm 3062. An actuation arm, such as the actuation arm 2962, can extend through the recess 3061 and can be removably attached to a central mount point 3064 formed in an external surface at a midpoint of the longitudinal axis of the rotor shafts 3012a and 3012b.

10 **[00187]** Referring more specifically to FIGs. 30D and 30E now, the example rotary piston-type actuator 3000 is shown in end and cutaway perspective views taken through a midpoint of the central actuation assembly 3060 and the central mounting assembly 3080 at the recess 3061. The actuation arm (not shown) can extend into the recess 3061 to contact the central mount point 3064 of the rotor shafts 3012a, 3012b. The actuation arm can be removably connected to the central mount point 3064 by a fastener, e.g., bolt, that can be passed through a pair of holes (e.g. the holes 2968 formed in the actuation arm 2962) and a hole 3065 formed through the central mount point 3064. Similarly to as was discussed in the description of the rotary piston-type actuator 2900 and the central actuation assembly 2960, the central actuation assembly 3060 connects the example rotary actuator 3000 to an external mounting feature or structural member to impart rotational motion of the actuator sections 3010a, 3010b to equipment to be moved (actuated), e.g.,

aircraft flight control surfaces, relative to structural members, e.g., aircraft frames.

[00188] In some embodiments, one of the central actuation assembly 3060 or the central mounting assembly 3080 can be used in combination with
5 features of any of the example rotary piston-type actuators 100, 400, 700, 800, 1200, 1500, 1700, 1900, 2200, 2300, 2600 and/or 2900. For example, the example rotary actuator 3000 may be mounted to a stationary surface through the central mounting assembly 3080, and provide actuation at one or both ends of the rotor shafts 3012a, 3012b. In another example, the example rotary
10 actuator 3000 may be mounted to a stationary surface through non-central mounting points, and provide actuation at the central actuation assembly 3060. In another example, the rotary actuator 3000 may be mounted to a stationary surface through the central mount point 3064, and provide actuation at the central mounting assembly 3080.

15 **[00189]** FIGs. 31A-31E are various views of an example rotary actuator 3100 with a central actuation assembly 3160. For a brief description of each drawing see the brief description of each of these drawings included at the beginning of the Description of the Drawings section of this document.

[00190] In general, the example rotary actuator 3100 is substantially similar
20 to the rotary actuator 3000 of FIGs. 30A-30E, where the example rotary actuator 3100 also includes a central actuation assembly 3160 and a central mounting assembly 3180. In some embodiments, the example rotary actuator 3100 can be a modification of the example rotary piston-type actuator 3000 in which rotational action can be performed by a mechanism other than a rotary

fluid actuator. The example rotary actuator 3100 is an an electromechanical actuator. Although the example rotary actuator 3100 is illustrated and described as modification of the example rotary actuator 3000, in some embodiments the example rotary actuator 3100 can implement features of any
5 of the example rotary piston-type actuators 100, 400, 700, 800, 1200, 1500, 1700, 1900, 2200, 2300, 2600 and/or 2900 and/or the rotary actuator 3000 in a design that also implements the central actuation assembly 3160 and/or the central mounting assembly 3180.

[00191] The actuator 3100 includes a rotary actuator section 3110a and a
10 rotary actuator section 3110b. In some embodiments, the rotary actuator sections 3110a and 3110b can be electromechanical actuators. The rotary actuator section 3110a includes a housing 3150a, and the rotary actuator section 3110b includes a housing 3150b. A rotor shaft 3112a runs along the longitudinal axis of the rotary actuator section 3110a, and a rotor shaft 3112b
15 runs along the longitudinal axis of the rotary actuator section 3110b.

[00192] The central mounting assembly 3180 is formed as a radially projected portion 3181 of the housings 3150a and 3150b. The central mounting assembly 3180 provides a mounting point for removably affixing the example rotary actuator 3100 to an external surface or an external structural
20 member, e.g., an aircraft frame, an aircraft control surface. A collection of holes 3182 formed in the radially projected section 3181 accommodate the insertion of a collection of fasteners (not shown), e.g., bolts, to removably affix the central mounting assembly 3180 to an external mounting feature, e.g., the

external mounting feature 2090 of FIG. 29, a mounting point (bracket) on an aircraft frame or control surface.

[00193] The central actuation assembly 3160 includes a radial recess 3161 formed in a portion of an external surfaces of the housings 3150a, 3150b at a midpoint along a longitudinal axis AA to the example rotary actuator 3100. In some implementations, an external mounting bracket, such as the external mounting bracket 2970, may be adapted for attachment to an external mounting feature of a structural member or a member to be actuated, (e.g., aircraft flight control surfaces) can be connected to an actuation arm 3162. An actuation arm, such as the actuation arm 2962, can extend through the recess 3161 and can be removably attached to a central mount point 3164 formed in an external surface at a midpoint of the longitudinal axis of the rotor shafts 3112a and 3112b.

[00194] Referring more specifically to FIGs. 31D and 31E now, the example rotary piston-type actuator 3100 is shown in end and cutaway perspective views taken through a midpoint of the central actuation assembly 3160 and the central mounting assembly 3080 at the recess 3161. The actuation arm (not shown) can extend into the recess 3161 to contact the central mount point 3164 of the rotor shafts 3112a, 3112b. The actuation arm can be removably connected to the central mount point 3164 by a fastener, e.g., bolt, that can be passed through a pair of holes (e.g. the holes 2968 formed in the actuation arm 2962) and a hole 3165 formed through the central mount point 3164. Similarly to as was discussed in the description of the rotary piston-type actuator 2900 and the central actuation assembly 2960, the central actuation

assembly 3160 connects the example rotary actuator 3100 to an external mounting feature or structural member to impart rotational motion of the actuator sections 3110a, 3110b to equipment to be moved (actuated), e.g., aircraft flight control surfaces, relative to structural members, e.g., aircraft frames.

[00195] In some embodiments, one of the central actuation assembly 3160 or the central mounting assembly 3180 can be used in combination with features of any of the example rotary piston-type actuators 100, 400, 700, 800, 1200, 1500, 1700, 1900, 2200, 2300, 2600 and/or 2900 and/or the rotary actuator 3000. For example, the example rotary actuator 3100 may be mounted to a stationary surface through the central mounting assembly 3180, and provide actuation at one or both ends of the rotor shafts 3112a, 3112b. In another example, the example rotary actuator 3100 may be mounted to a stationary surface through non-central mounting points, and provide actuation at the central actuation assembly 3160. In another example, the rotary actuator 3100 may be mounted to a stationary surface through the central mount point 3164, and provide actuation at the central mounting assembly 3180.

[00196] Although a few implementations have been described in detail above, other modifications are possible. For example, the logic flows depicted in the figures do not require the particular order shown, or sequential order, to achieve desirable results. In some examples, the terms “about”, “proximal”, “approximately”, “substantially”, or other such terms in association with a position or quantity, can mean but are not limited to, the described position or

quantity plus or minus 10% of the described quantity or length of the major dimension of the described position, unless specified otherwise. In addition, other steps may be provided, or steps may be eliminated, from the described flows, and other components may be added to, or removed from, the

5 described systems. Accordingly, other implementations are within the scope of the following claims.

WHAT IS CLAIMED IS:

1. A rotary actuator comprising:
 - a housing;
 - a rotor assembly rotatably journaled in said housing and including a
 - 5 rotary output shaft;
 - a central actuation assembly including a central mounting point formed in an external surface of the rotary output shaft, said central mounting point proximal to the longitudinal midpoint of the rotary output shaft;
 - a mounting assembly adapted for attachment to an external mounting
 - 10 connector of a mounting surface of an aircraft structural member; and
 - an actuation arm removably attached at a proximal end to the central mounting point, said actuation arm adapted at a distal end for attachment to an external mounting feature of an aircraft assembly to be actuated.
- 15 2. The rotary actuator of claim 1 wherein the central actuation assembly further includes a radial recess formed in an external peripheral surface of the housing proximal to the central mounting point of the rotary output shaft, and wherein said actuation arm extends through the radial recess.
3. The rotary actuator of claim 1 wherein the mounting assembly comprises a
- 20 radially projecting portion of the housing disposed at a midpoint of the housing, said mounting assembly disposed about 180 degrees from the radial recess of the central actuation assembly.

4. The rotary actuator of claim 1, wherein:
- the housing defines a first arcuate chamber including a first cavity, a first fluid port in fluid communication with the first cavity, and an open end;
- the rotor assembly further includes a first rotor arm extending radially
- 5 outward from the rotary output shaft; and
- the rotary actuator further comprises an arcuate-shaped first piston disposed in said housing for reciprocal movement in the first arcuate chamber through the open end, wherein a first seal, the first cavity, and the first piston define a first pressure chamber, and a first portion of the
- 10 first piston contacts the first rotor arm.
5. The rotary actuator of claim 4, wherein the housing further defines a second arcuate chamber comprising a second cavity, and a second fluid port in fluid communication with the second cavity;
- the rotor assembly further comprises a second rotor arm; and
- 15 the rotary actuator further comprises an arcuate-shaped second piston disposed in said housing for reciprocal movement in the second arcuate chamber, wherein a second seal, the second cavity, and the second piston define a second pressure chamber, and a first portion of the second piston contacts the second rotor arm.
- 20 6. The rotary actuator of claim 5 wherein the central actuation assembly further includes a radial recess formed in an external peripheral surface of the housing proximal to the central mounting point of the rotary output shaft, and wherein said actuation arm extends through the radial recess.

7. The rotary actuator of claim 1, further comprising a rotary actuator comprising a stator mounted to the housing and a rotor coupled to the rotary output shaft.
8. The rotary actuator of claim 7, wherein the rotary actuator is one of a rotary piston type actuator, a rotary vane type actuator, or a rotary fluid type actuator.
9. The rotary actuator of claim 7, wherein the rotary actuator is an electromechanical actuator.
10. A rotary actuator comprising:
- a housing comprising a mounting assembly;
 - a rotor assembly rotatably journaled in said housing and including a rotary output shaft;
 - a central actuation assembly including a central mounting point formed in an external surface of the rotary output shaft, said central mounting point proximal to the longitudinal midpoint of the rotary output shaft; and
 - an actuation arm removably attached at a proximal end to the central mounting point, said actuation arm adapted at a distal end for attachment to an external mounting feature of a member to be actuated.
11. The rotary actuator of claim 10 wherein the central actuation assembly further includes a radial recess formed in an external peripheral surface of the housing proximal to the central mounting point of the rotary output shaft, and wherein said actuation arm extends through the radial recess.

12. The rotary actuator of claim 11 wherein the mounting assembly comprises a radially projecting portion of the housing, said mounting assembly disposed about 180 degrees from the radial recess of the central actuation assembly, said mounting assembly adapted for attachment to an external
5 mounting connector of a mounting surface.

13. The rotary actuator of claim 12, wherein the radially projecting portion of the housing is a radially projecting central portion of the housing.

14. The rotary actuator of claim 10, wherein:
the housing defines a first arcuate chamber including a first cavity, a
10 first fluid port in fluid communication with the first cavity, and an open end;
the rotor assembly further includes a first rotor arm extending radially outward from the rotary output shaft; and
the rotary actuator further comprises an arcuate-shaped first piston disposed in said housing for reciprocal movement in the first arcuate
15 chamber through the open end, wherein a first seal, the first cavity, and the first piston define a first pressure chamber, and a first portion of the first piston contacts the first rotor arm.

15. The rotary actuator of claim 14, wherein the housing further defines a second arcuate chamber comprising a second cavity, and a second fluid
20 port in fluid communication with the second cavity;
the rotor assembly further comprises a second rotor arm; and
the rotary actuator further comprises an arcuate-shaped second piston disposed in said housing for reciprocal movement in the second arcuate

chamber, wherein a second seal, the second cavity, and the second piston define a second pressure chamber, and a first portion of the second piston contacts the second rotor arm.

16. The rotary actuator of claim 15 wherein the central actuation assembly
5 further includes a radial recess formed in an external peripheral surface of the housing proximal to the central mounting point of the rotary output shaft, and wherein said actuation arm extends through the radial recess.

17. The rotary actuator of claim 10, further comprising a linear actuator mounted at a first end to the housing, and a second end mounted to a first
10 rotor arm extending radially outward from the rotary output shaft.

18. The rotary actuator of claim 10, further comprising a rotary actuator comprising a stator mounted to the housing and a rotor coupled to the rotary output shaft.

19. The rotary actuator of claim 18, wherein the rotary actuator is one of a
15 rotary piston type actuator, a rotary vane type actuator, or a rotary fluid type actuator.

20. The rotary actuator of claim 18, wherein the rotary actuator is an electromechanical actuator.

21. The rotary actuator of claim 18, wherein the rotary actuator comprises a
20 linear actuator and a linear-to-rotary motion conversion assembly coupled to the rotor.

22. The rotary actuator of claim 10, wherein the housing is formed as a one-piece housing.

23. The rotary actuator of claim 10, wherein the external mounting feature is attached to one of an aircraft structural member or an external mounting connector of an external surface, and the mounting assembly is attached
5 to the other of the aircraft structural member or the external mounting connector.

24. A method of rotary actuation comprising:

providing a rotary actuator comprising:

10 a housing;

a rotor assembly rotatably journaled in said housing and

including a rotary output shaft;

a central actuation assembly including a central mounting point

formed in an external surface of the rotary output shaft, said central

15 mounting point proximal to the longitudinal midpoint of the rotary output shaft; and

an actuation arm removably attached at a proximal end to the central mounting point, said actuation arm adapted at a distal end for attachment to an external mounting feature of a member to be actuated;

20 energizing the rotor assembly;

urging rotation of the rotary output shaft;

urging rotation of the actuation arm;

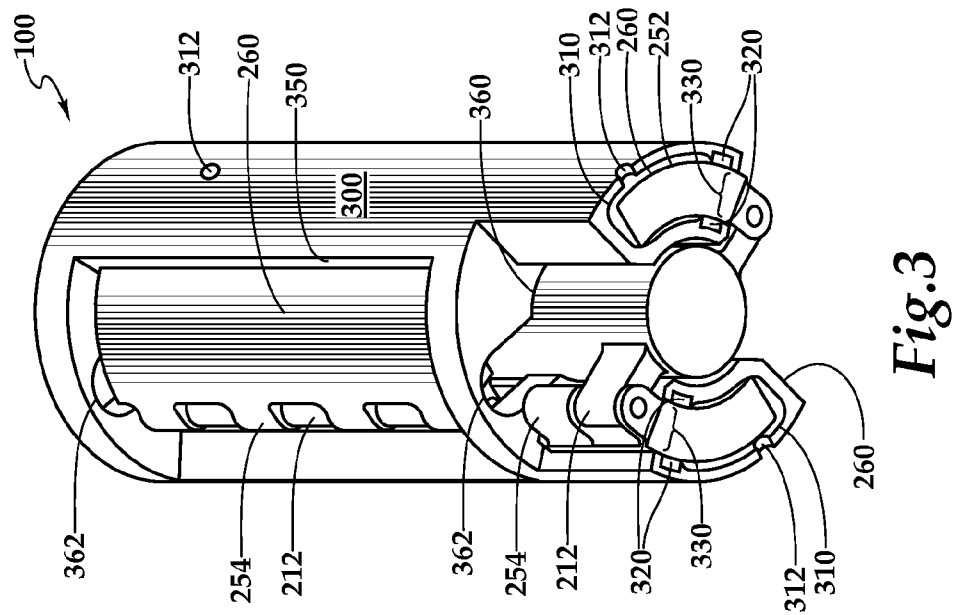
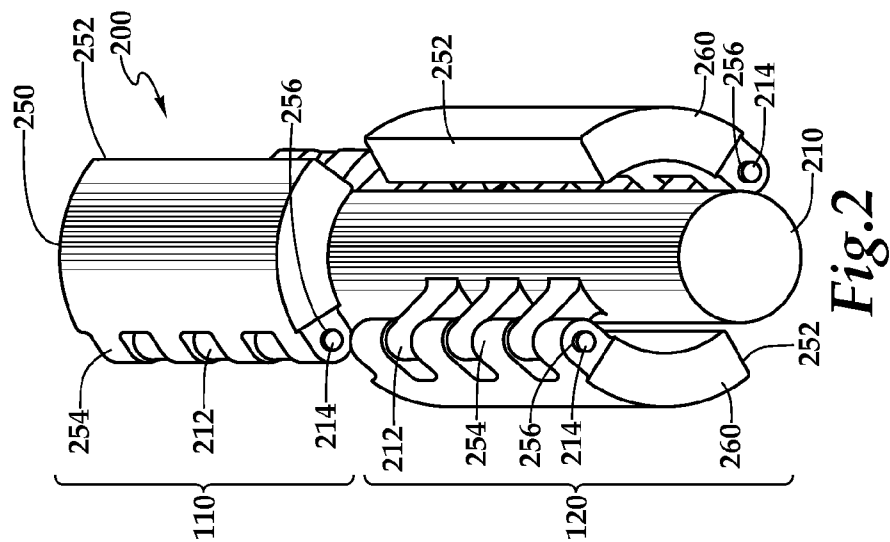
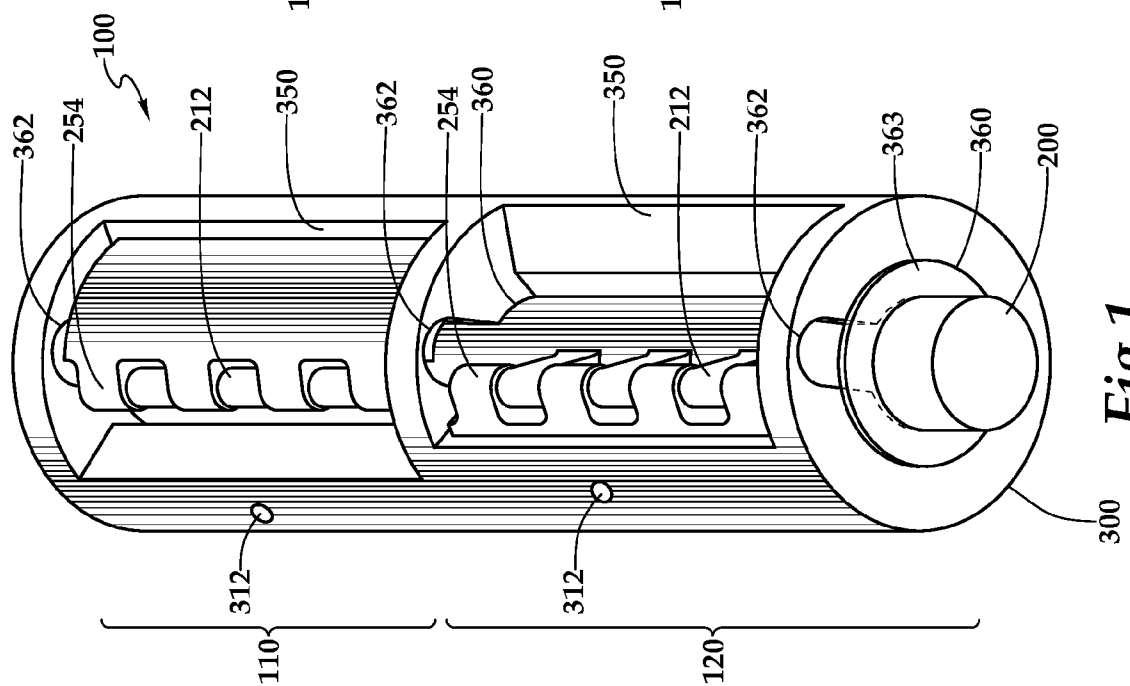
urging motion of the member to be actuated.

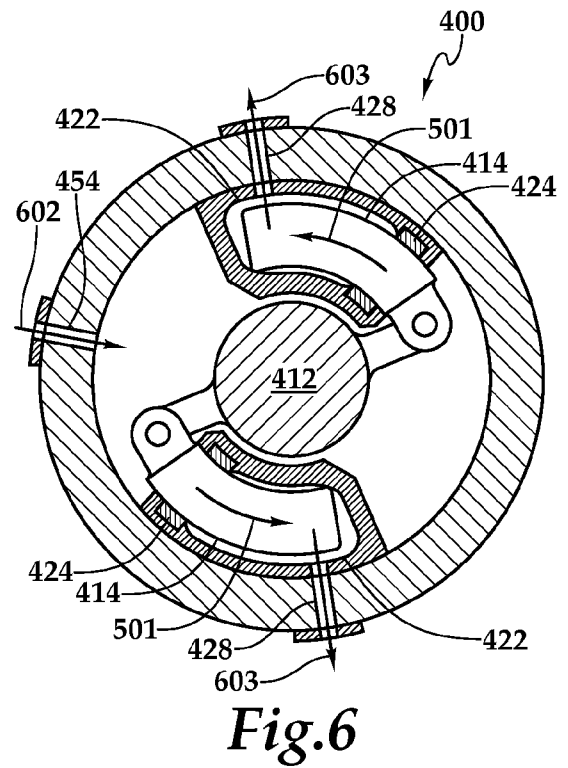
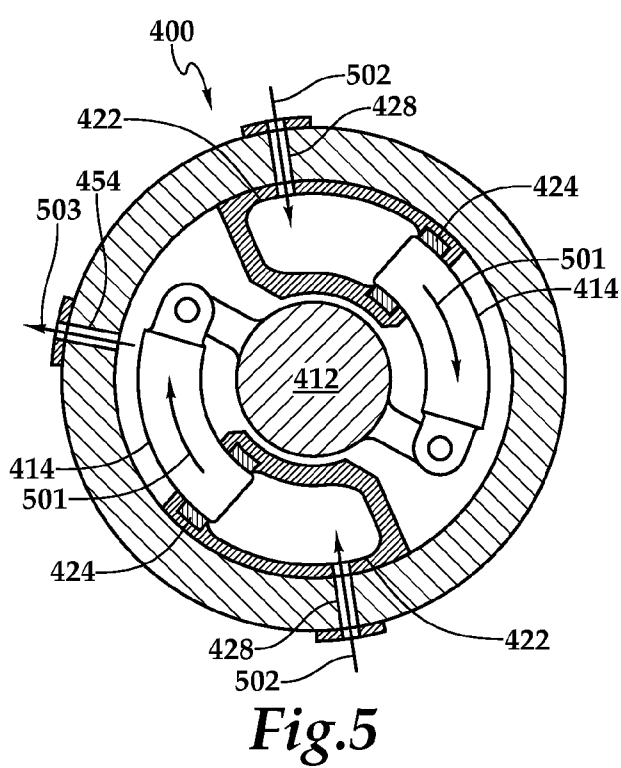
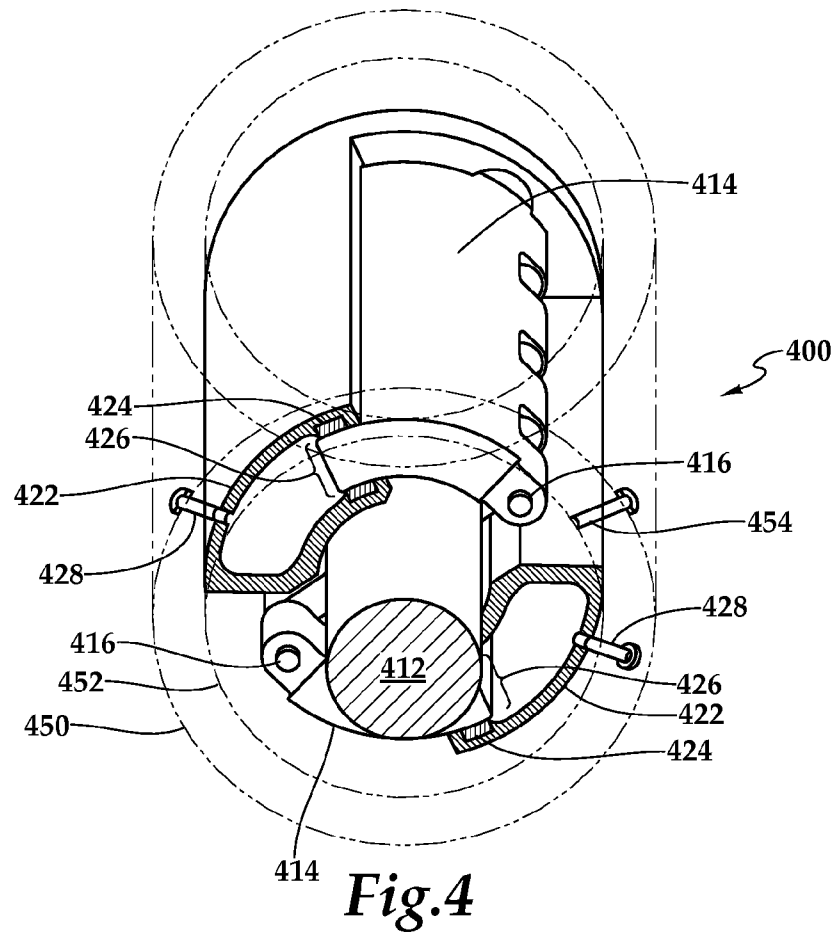
25. The method of claim 24, wherein the central actuation assembly further includes a radial recess formed in an external peripheral surface of the housing proximal to the central mounting point of the rotor shaft, and wherein said actuation arm extends through the radial recess.
- 5 26. The method of claim 24, wherein the mounting assembly further comprises a radially projecting portion of the housing, said mounting assembly disposed about 180 degrees from the radial recess of the central actuation assembly, said mounting assembly adapted for attachment to an external mounting connector of a mounting surface.
- 10 27. The method of claim 24, wherein the radially projecting portion of the housing is a radially projecting central portion of the housing.
28. The method of claim 24 wherein the central actuation assembly further includes a radial recess formed in an external peripheral surface of the housing proximal to the central mounting point of the rotary output shaft, and wherein said actuation arm extends through the radial recess
- 15 29. The method of claim 24, further comprising a rotary actuator comprising a stator mounted to the housing and a rotor coupled to the rotary output shaft.
30. The method of claim 29, wherein the rotary actuator is one of a rotary piston type actuator, a rotary vane type actuator, or a rotary fluid type actuator.
- 20

31. The method of claim 29, wherein the rotary actuator is an electromechanical actuator.

32. The method of claim 29, wherein the rotary actuator comprises a linear actuator and a linear-to-rotary motion conversion assembly coupled to the rotor.

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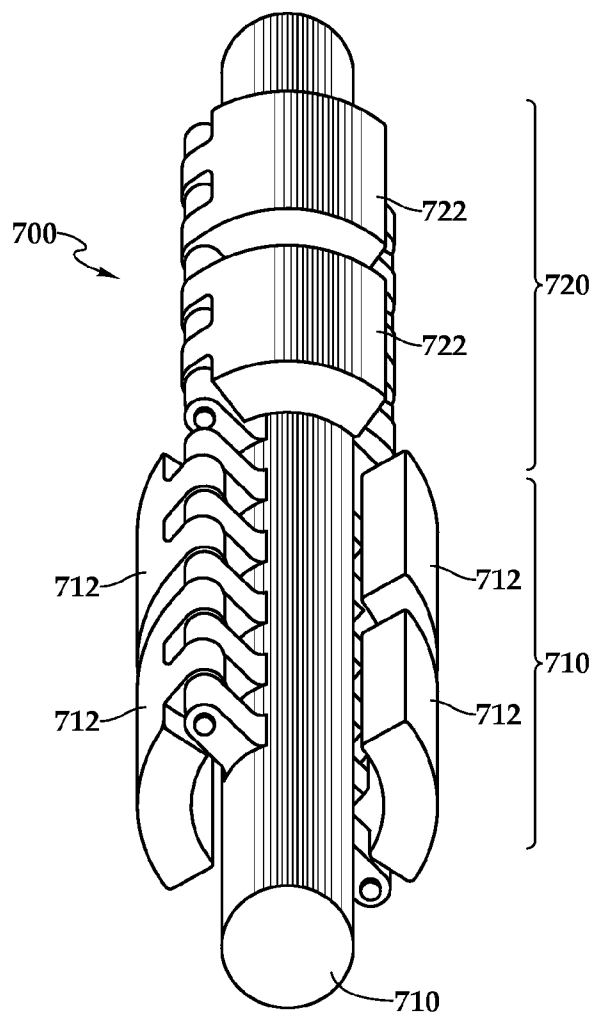


Fig. 7

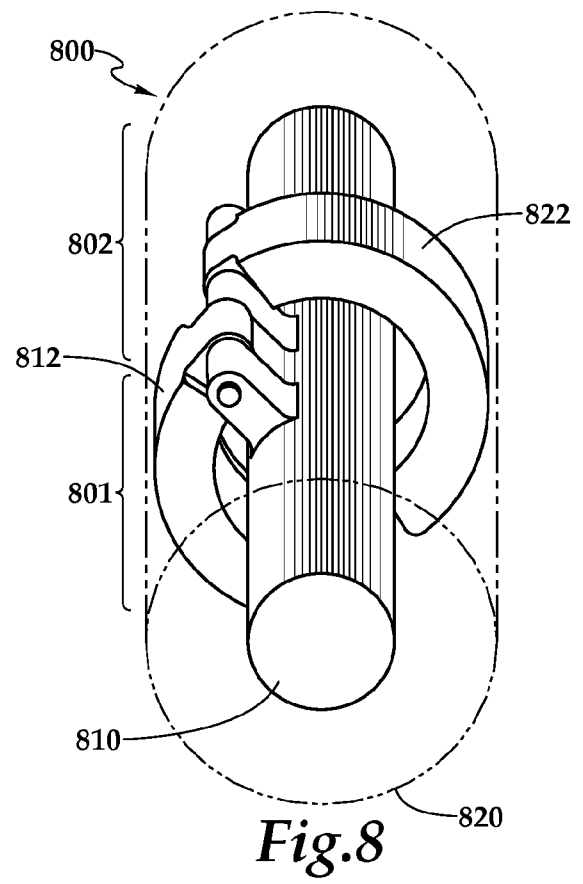


Fig. 8

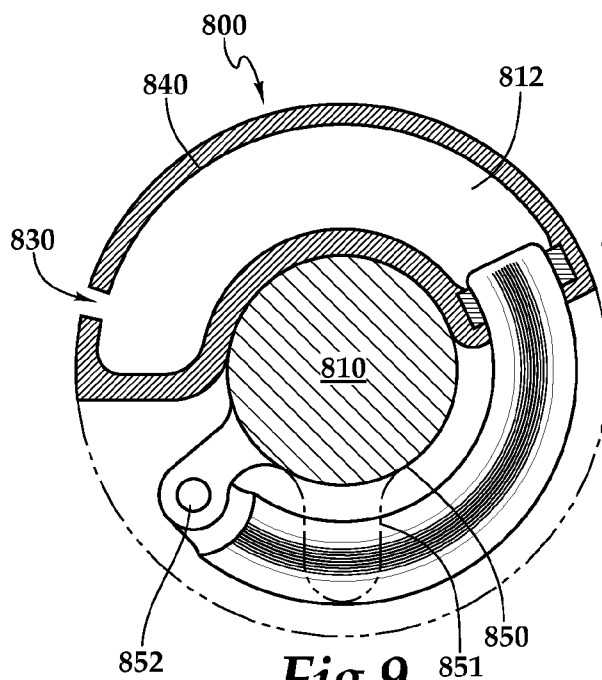


Fig. 9

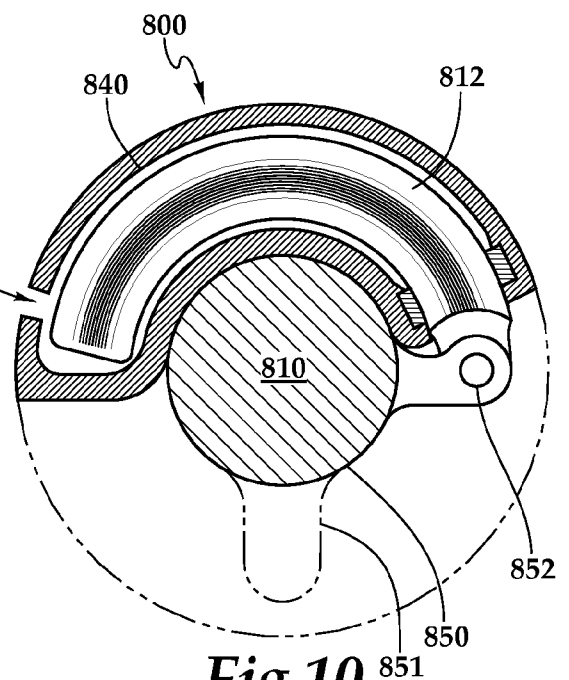


Fig. 10

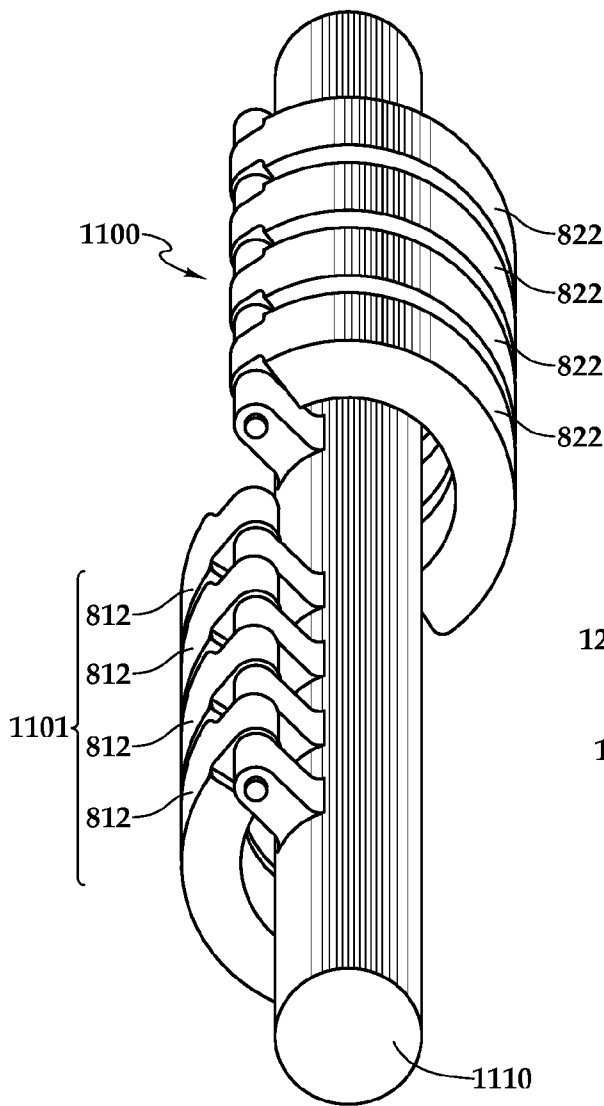


Fig.11

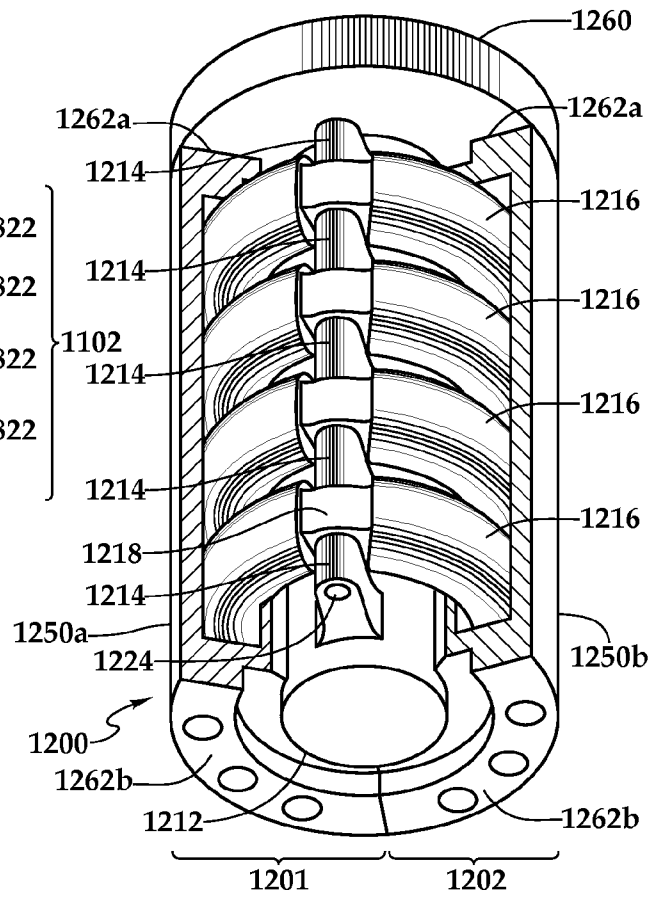


Fig.12

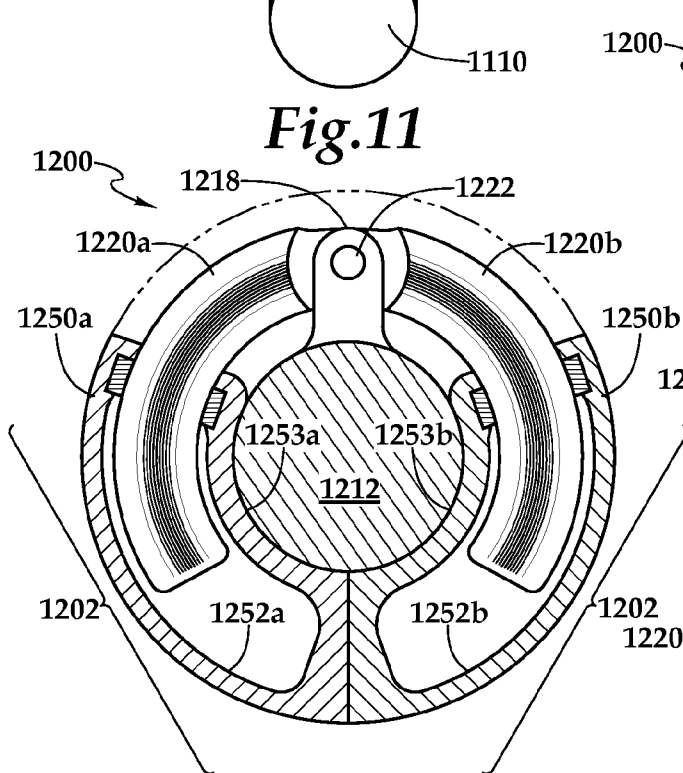


Fig.14

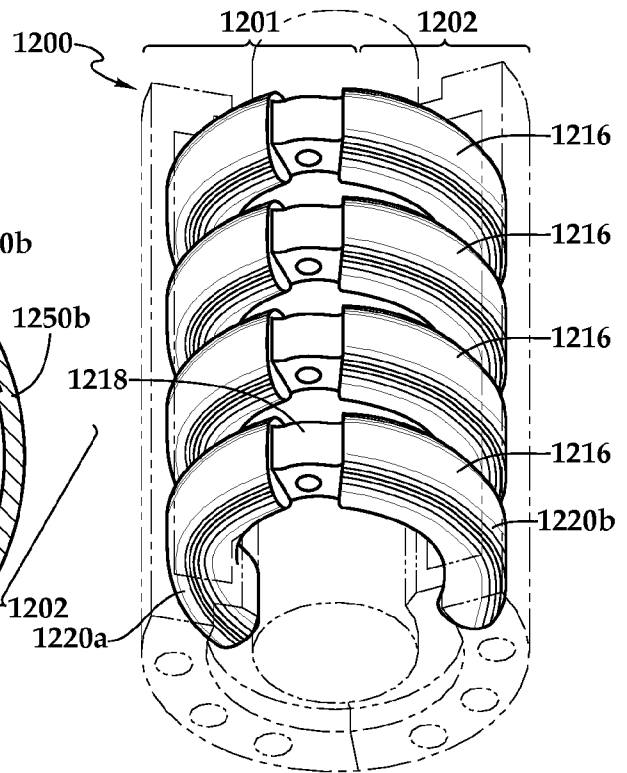


Fig.13

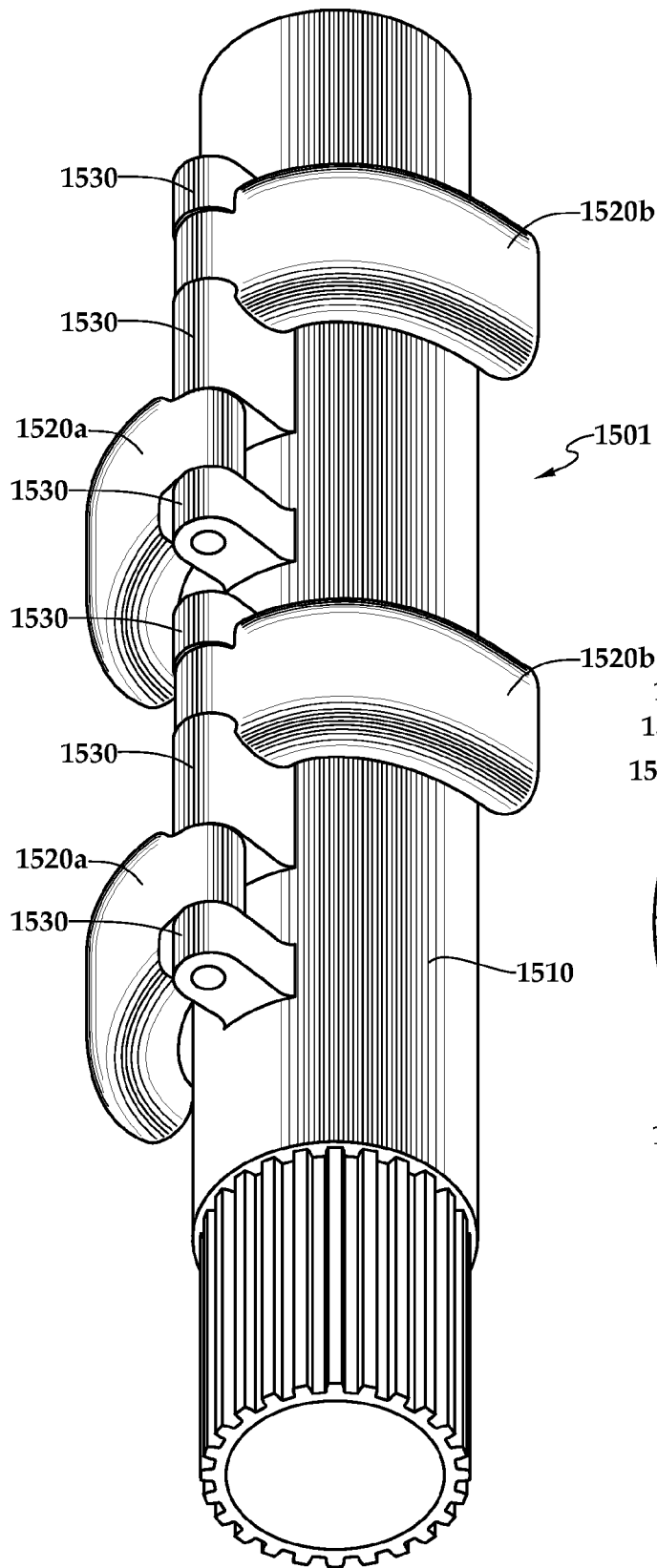


Fig.15

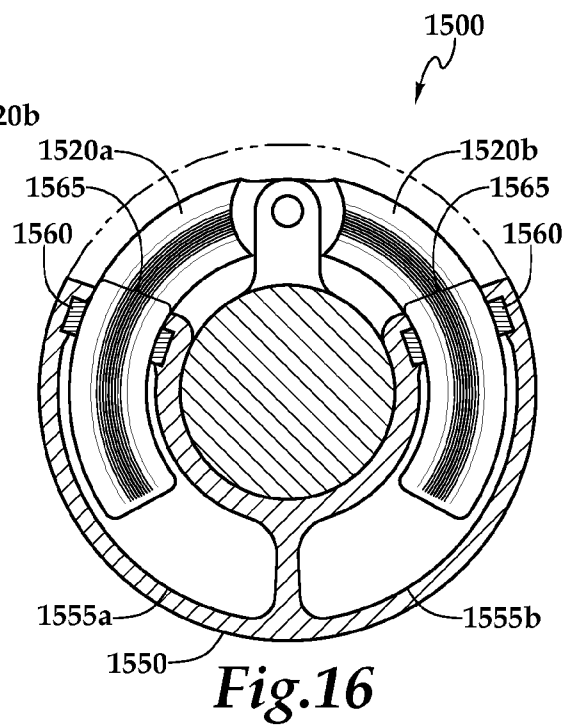
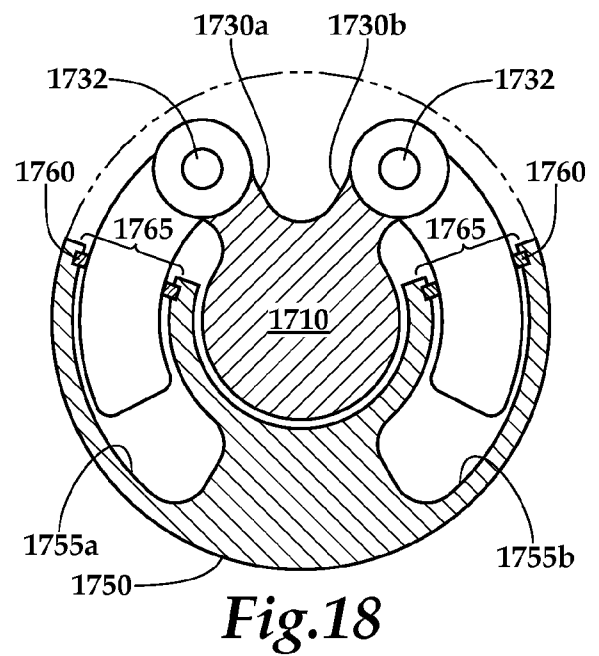
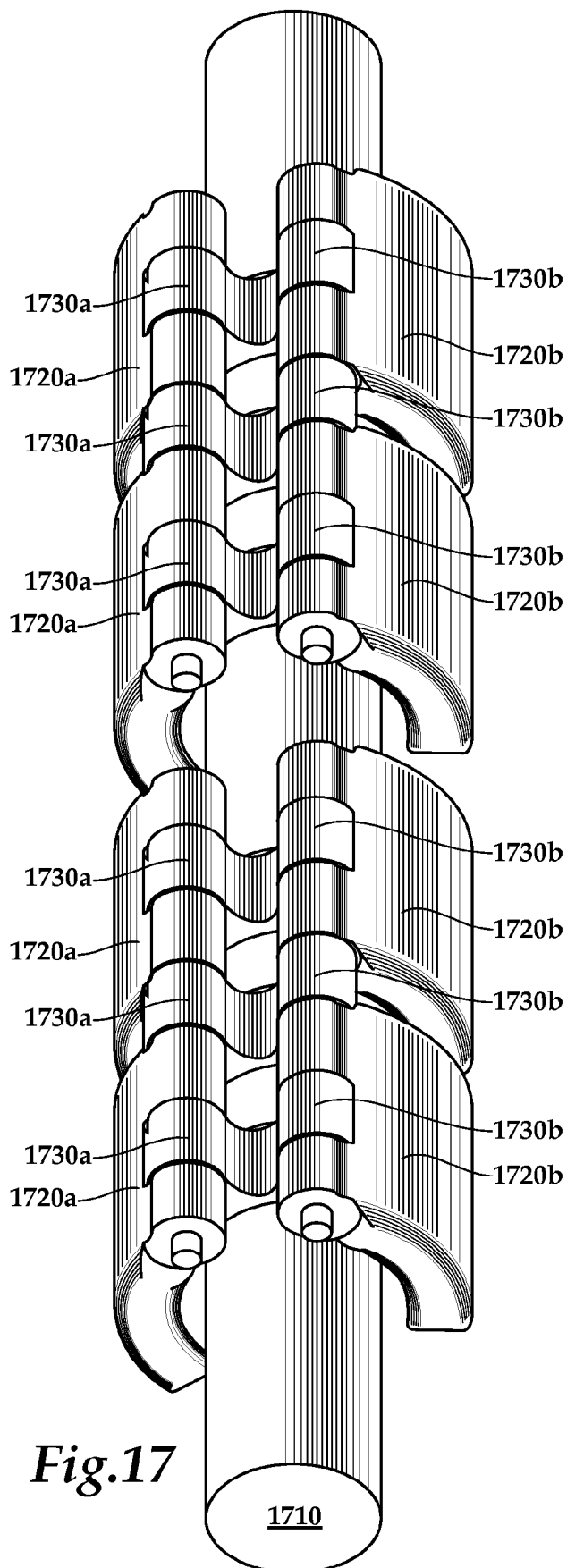
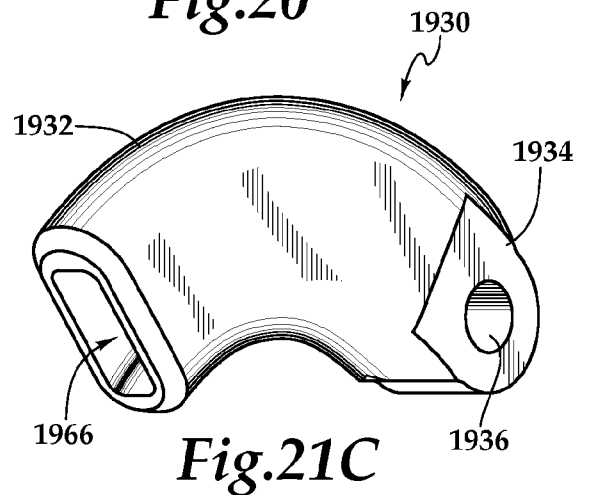
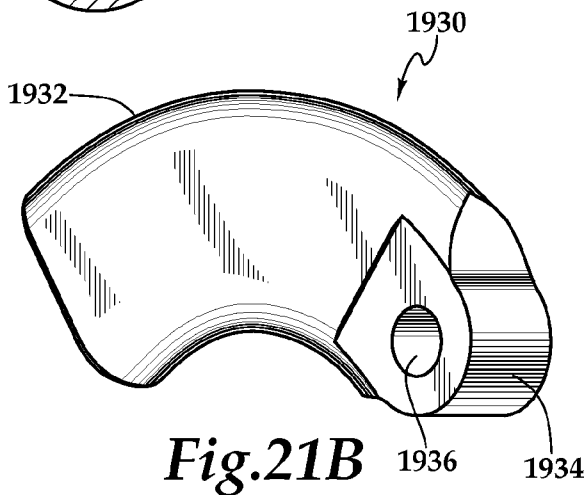
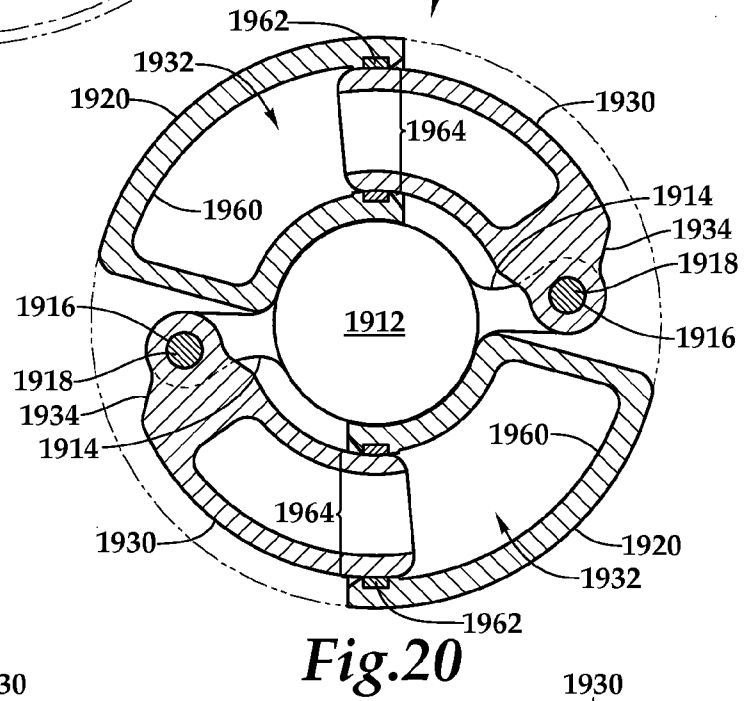
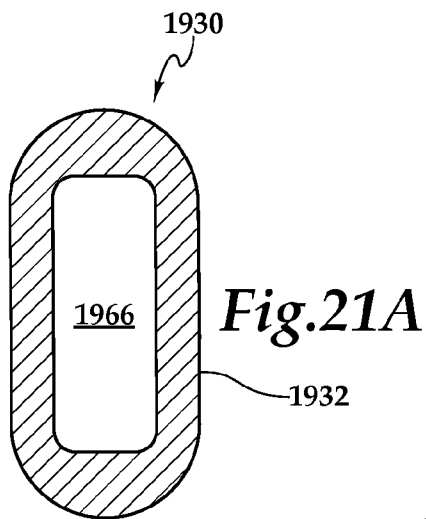
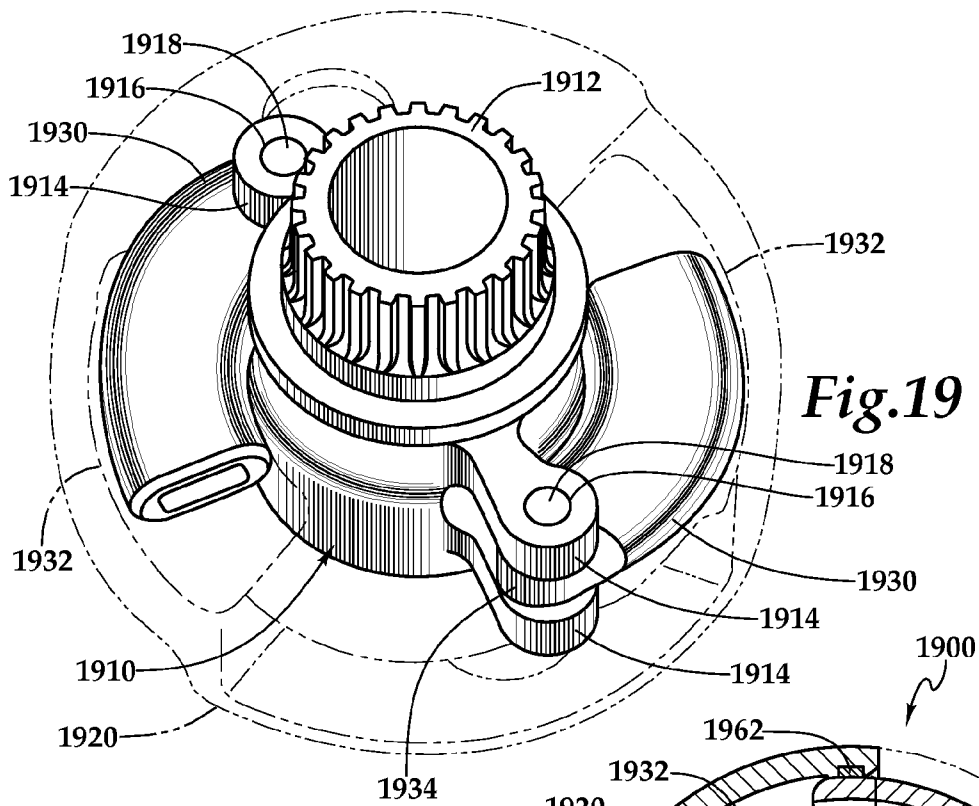


Fig.16





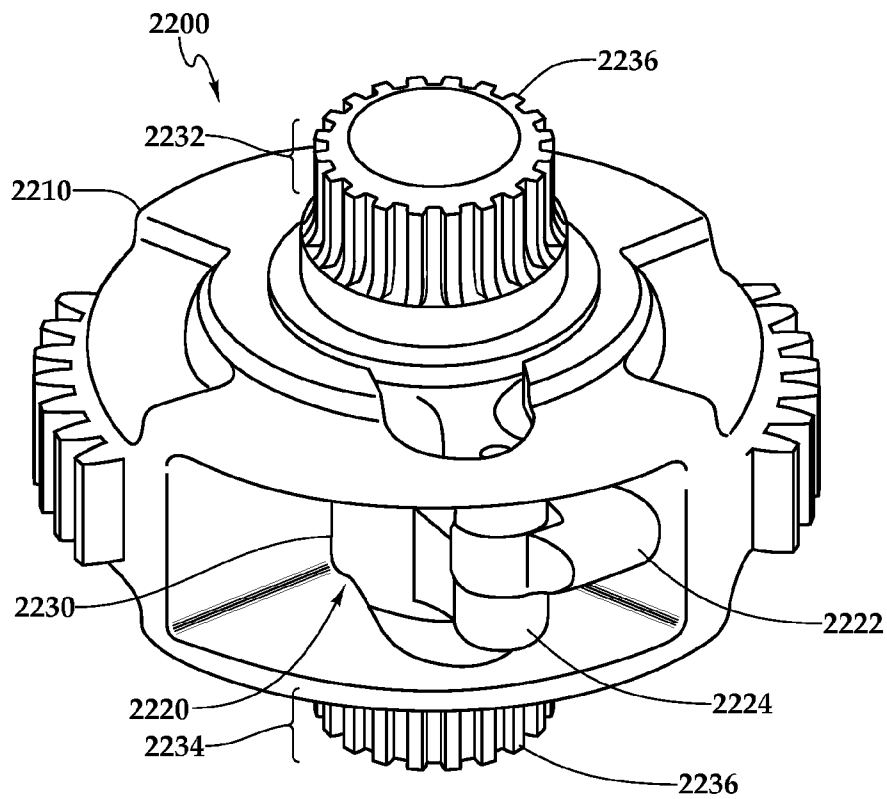


Fig. 22

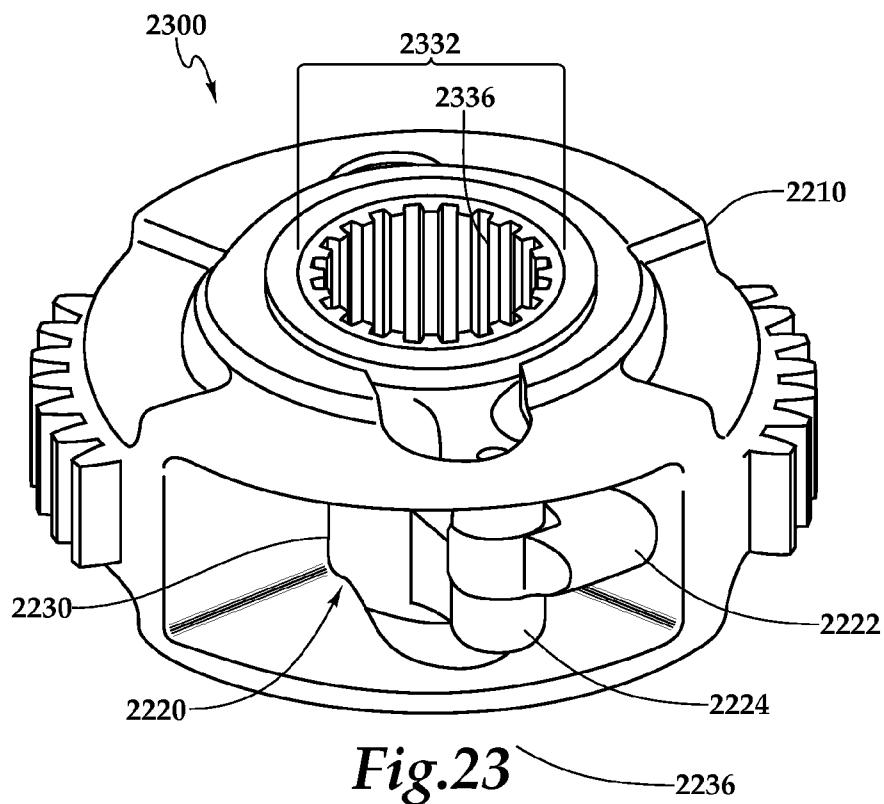
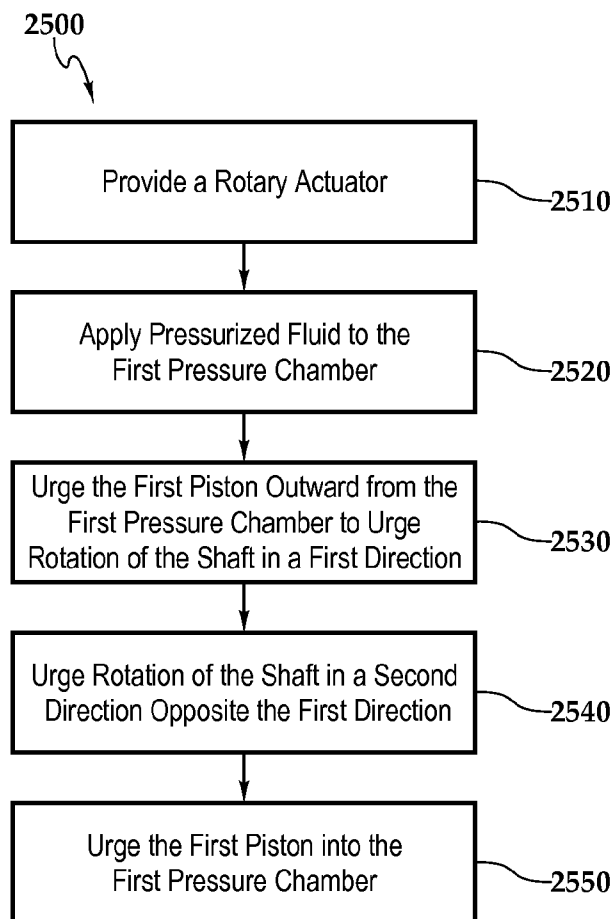
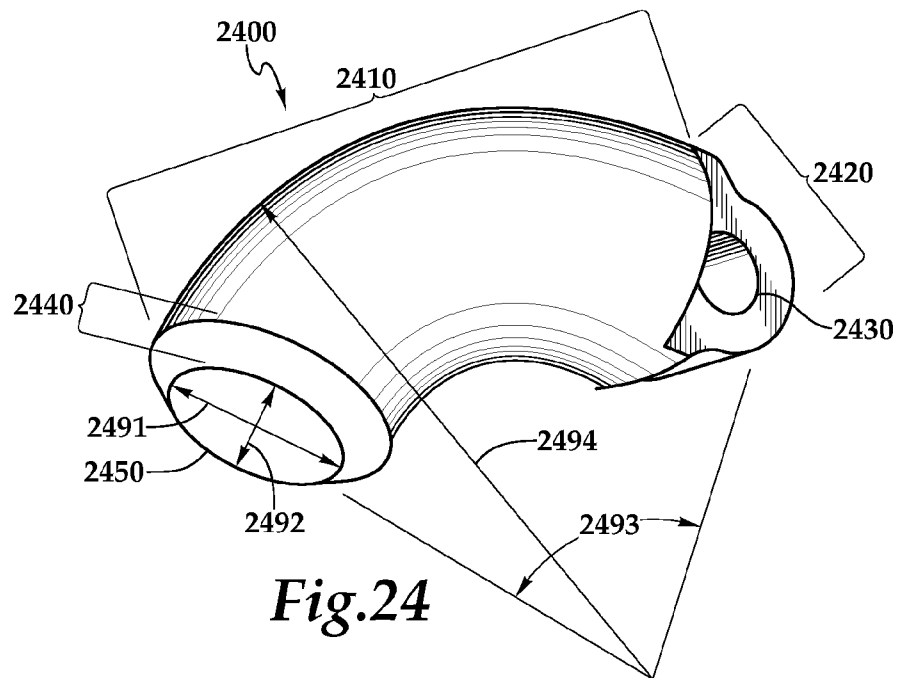
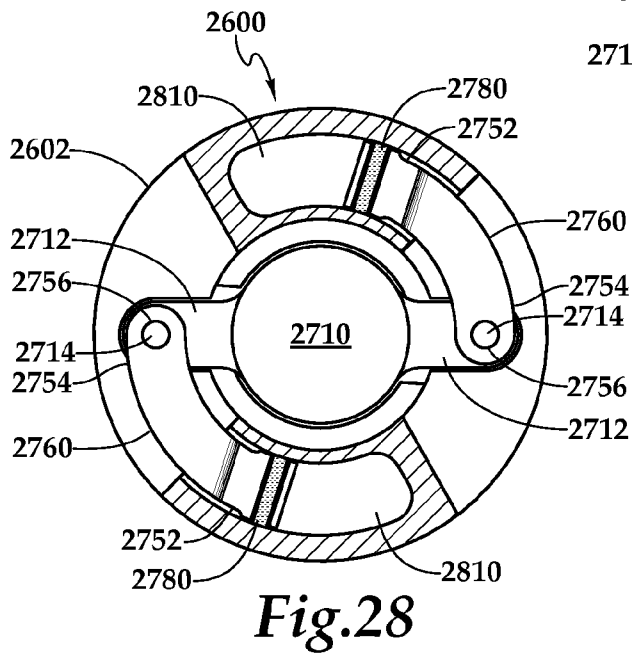
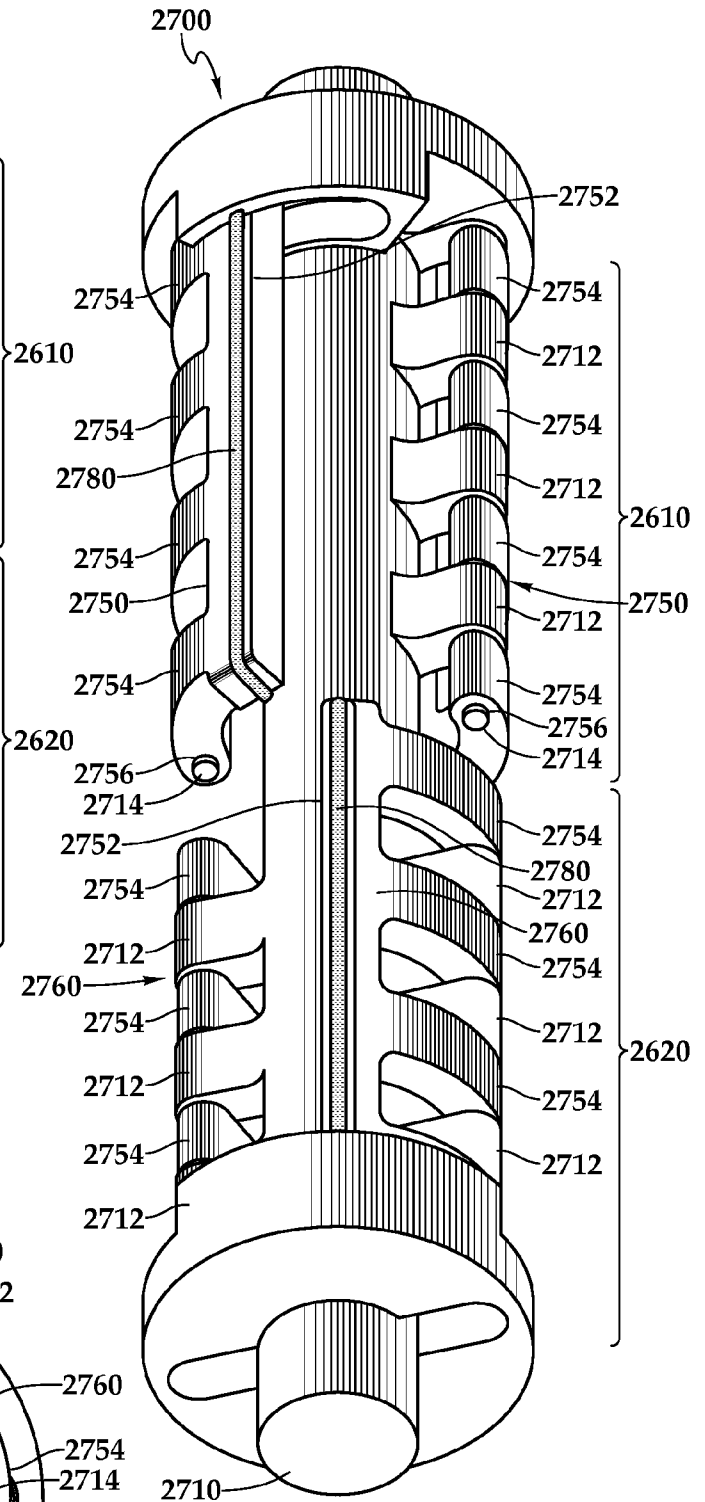
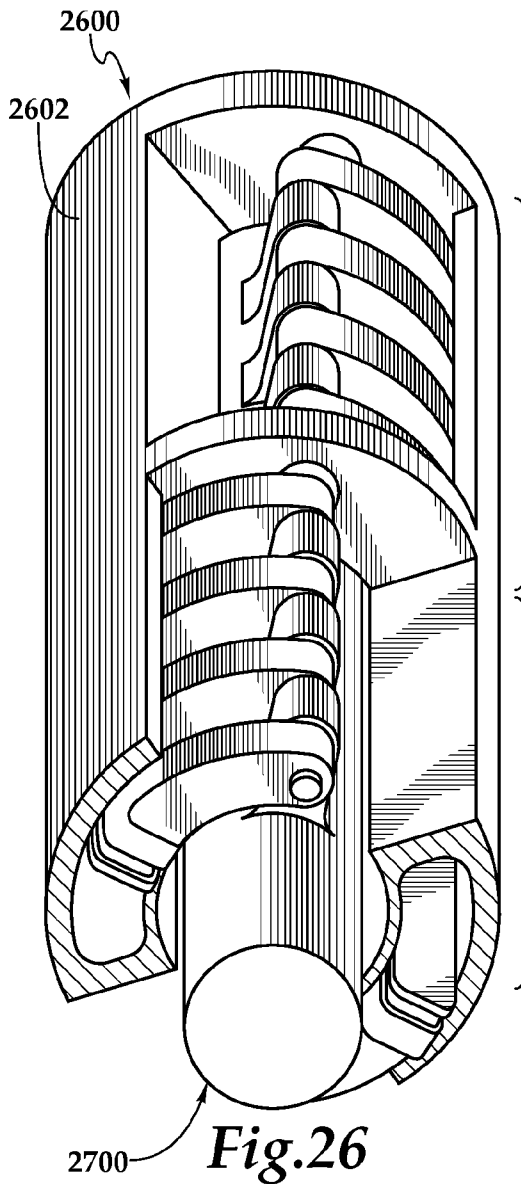
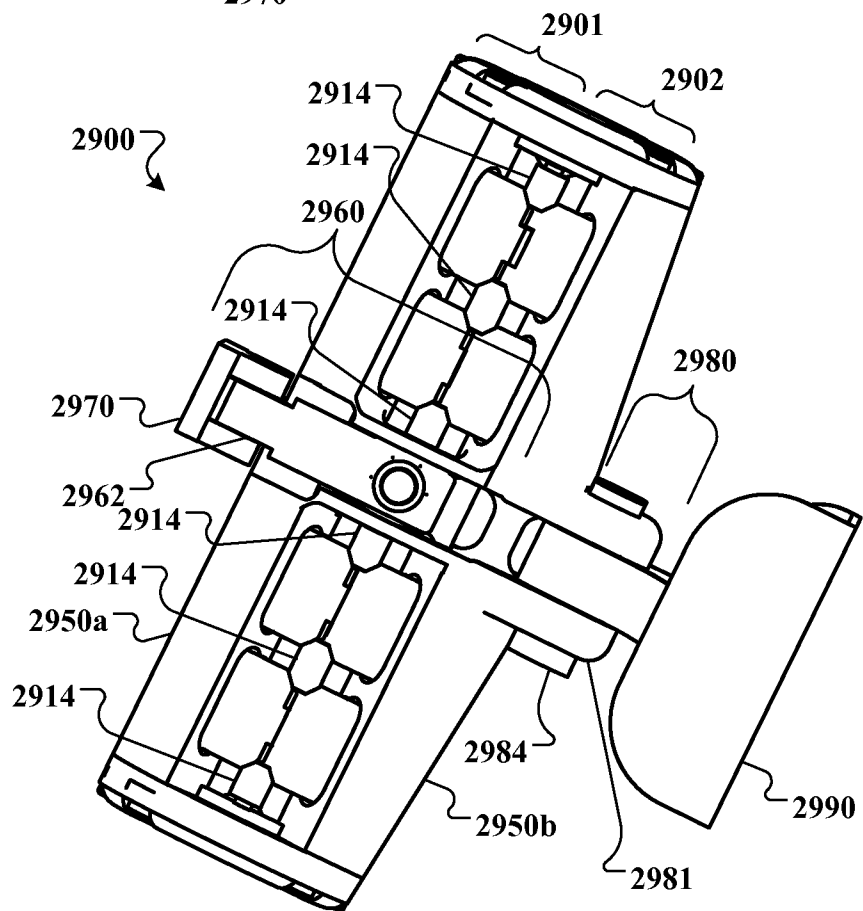
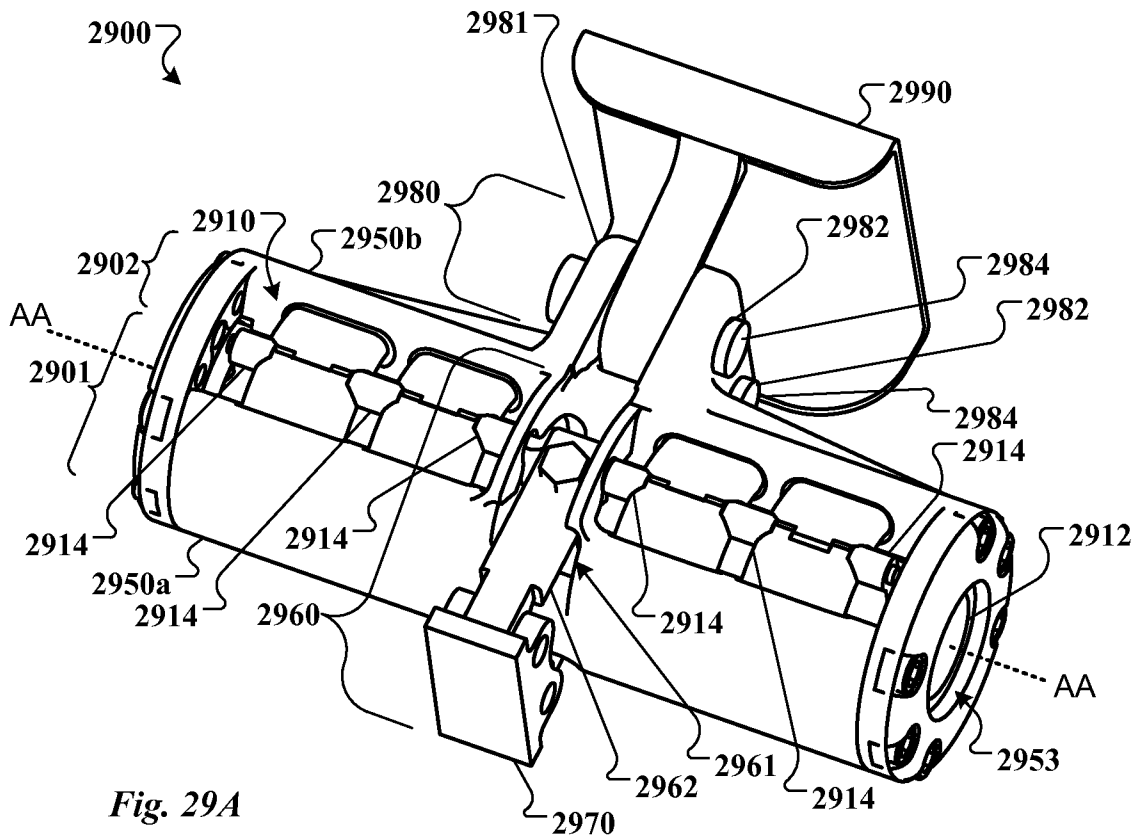


Fig. 23







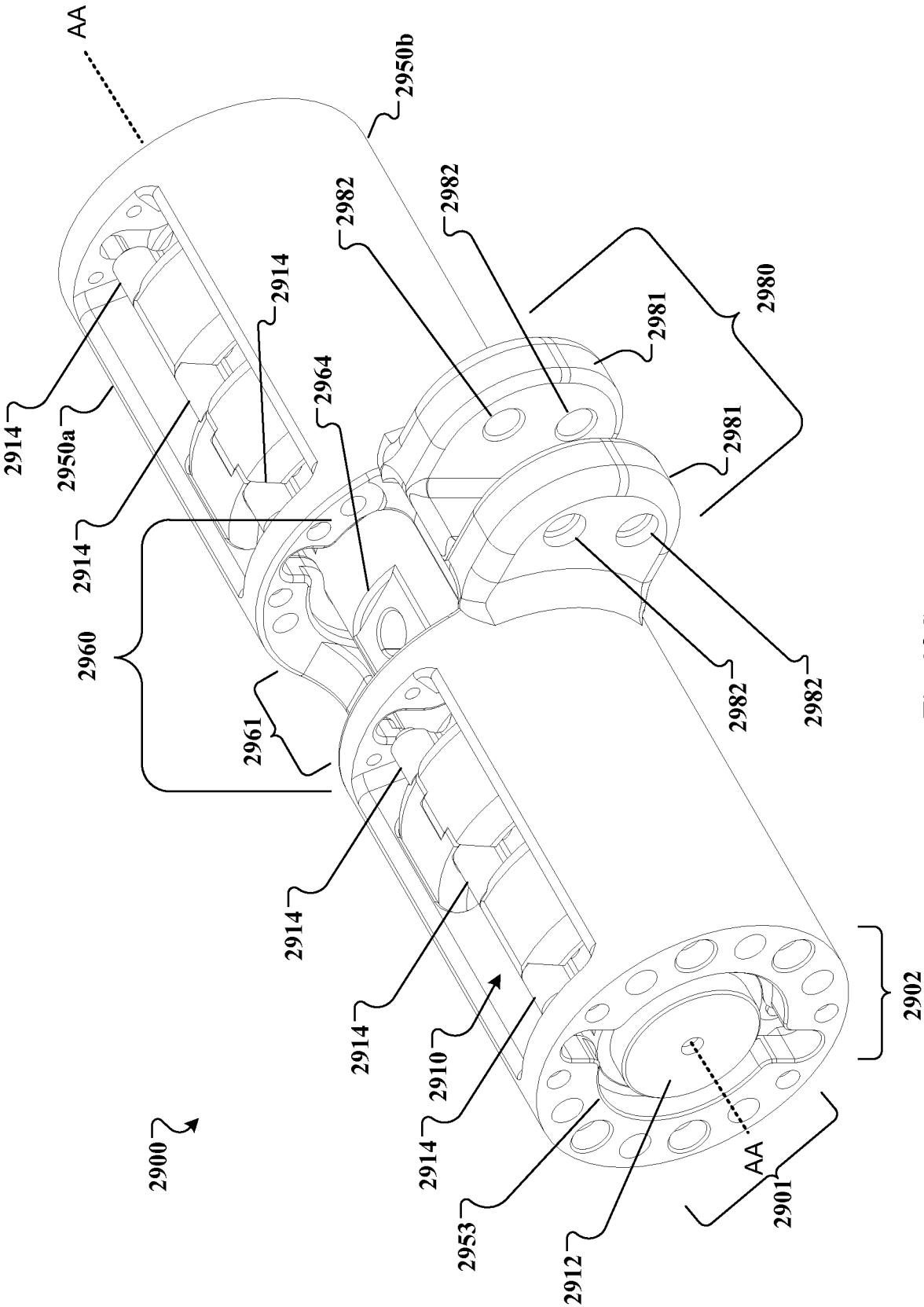


Fig. 29C

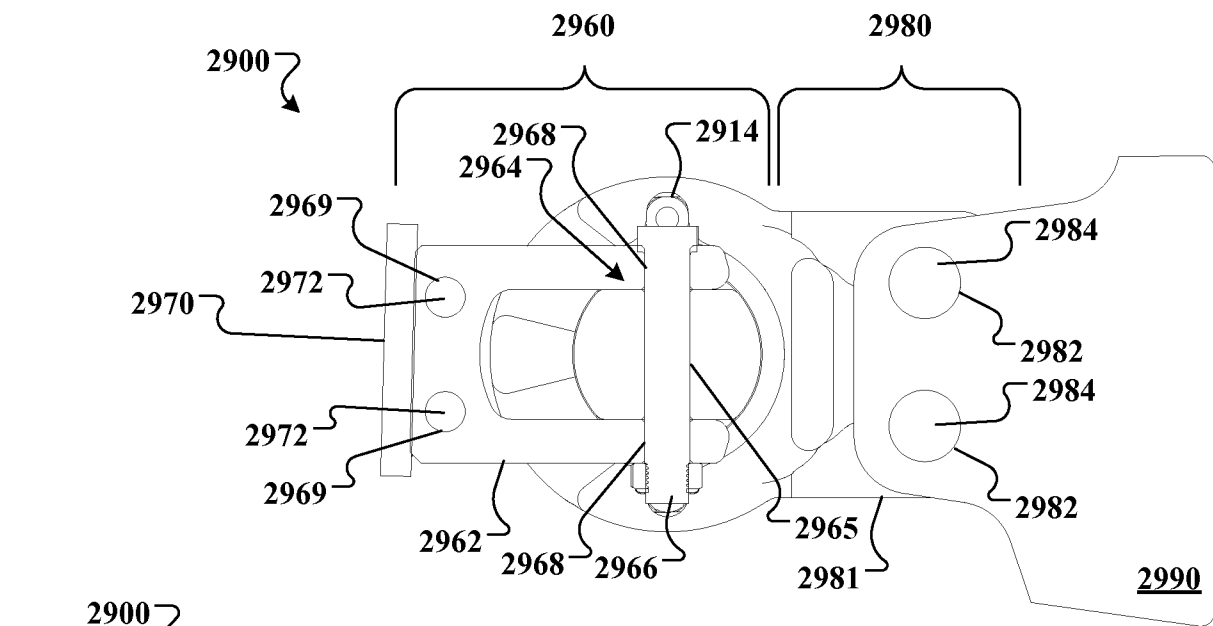


Fig. 29D

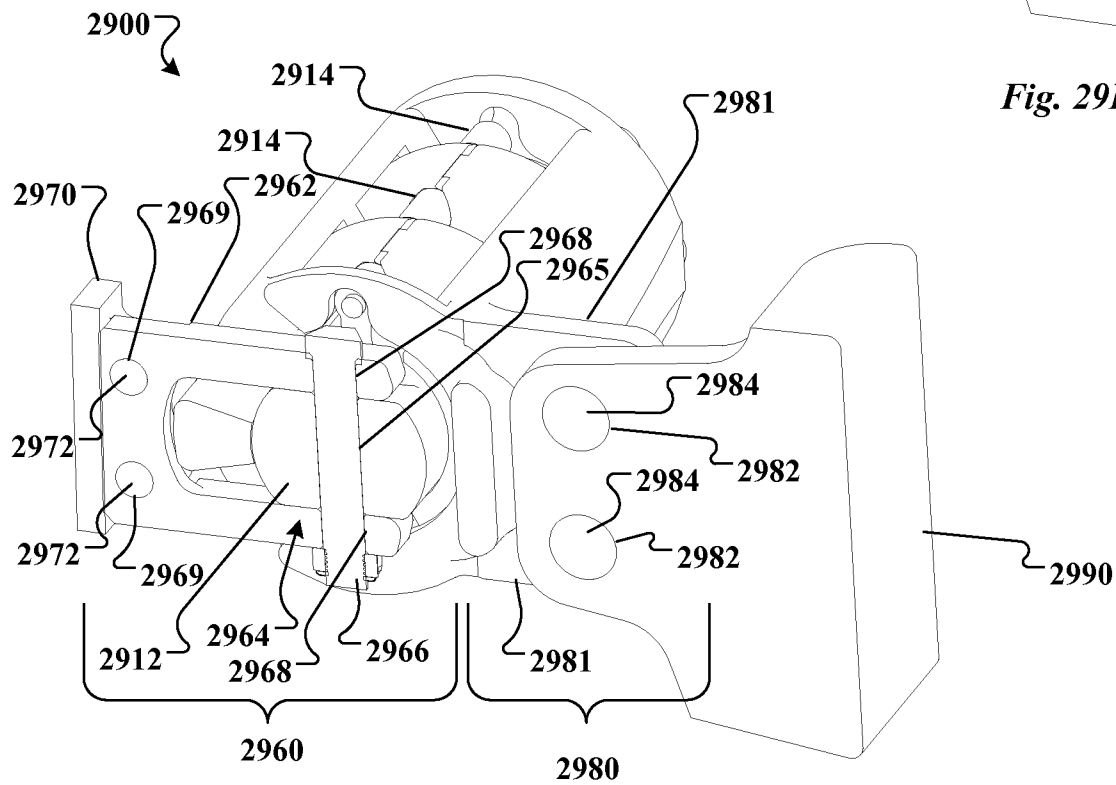
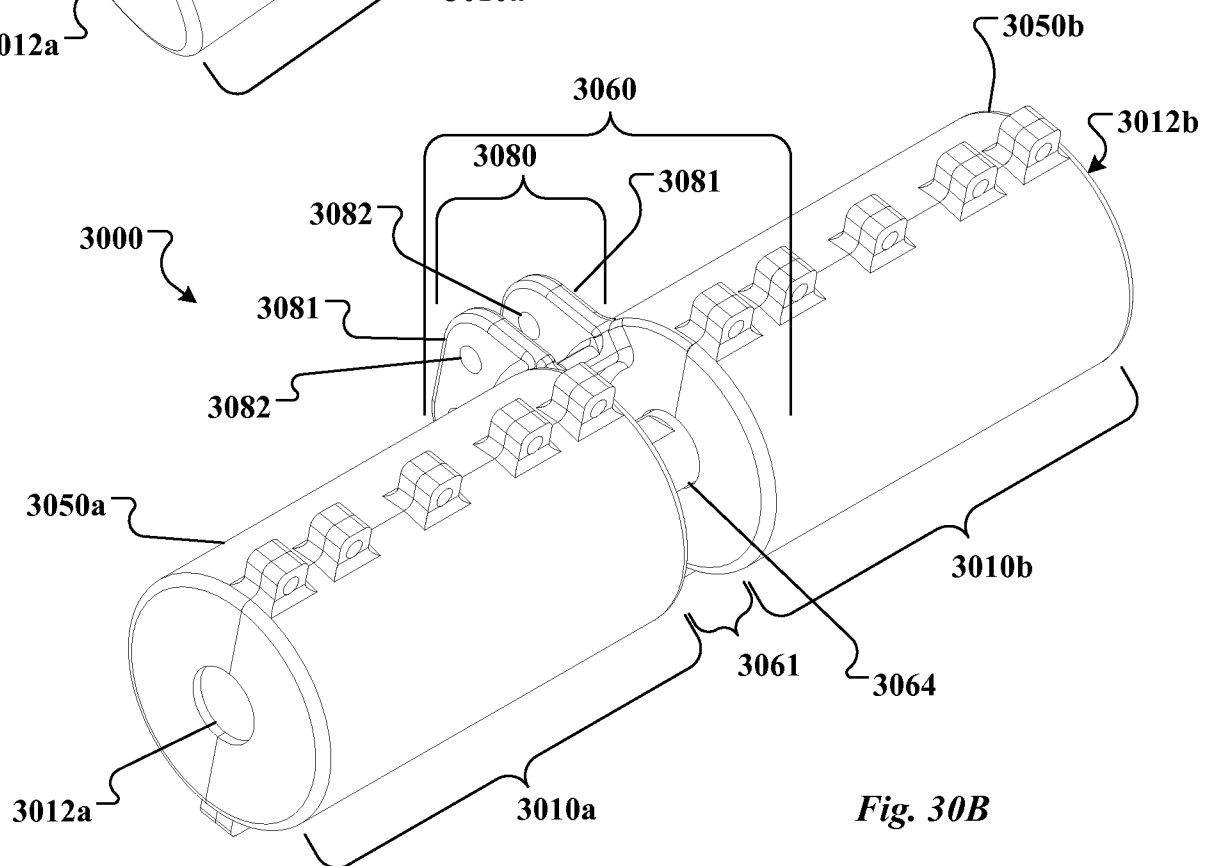
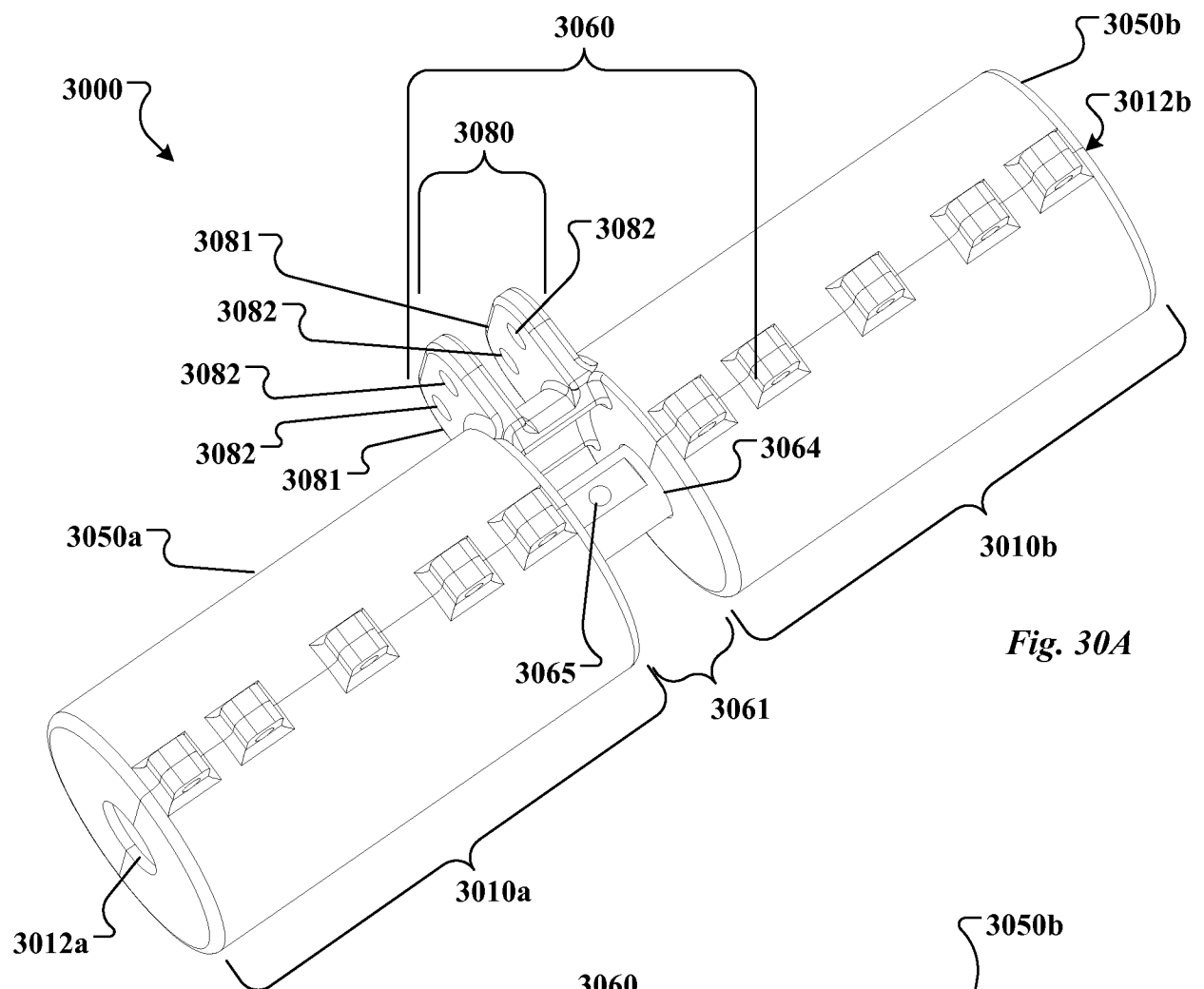


Fig. 29E



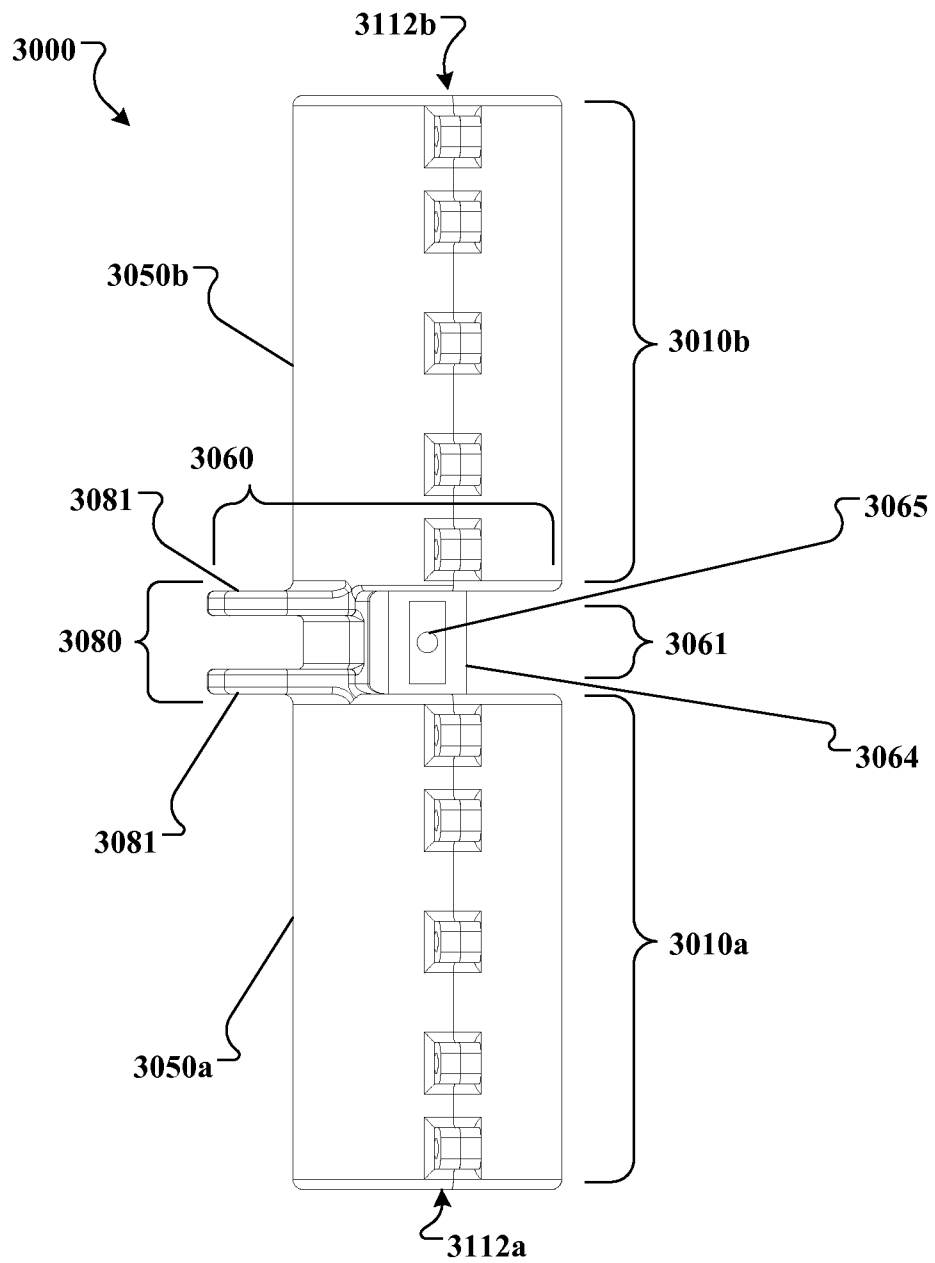


Fig. 30C

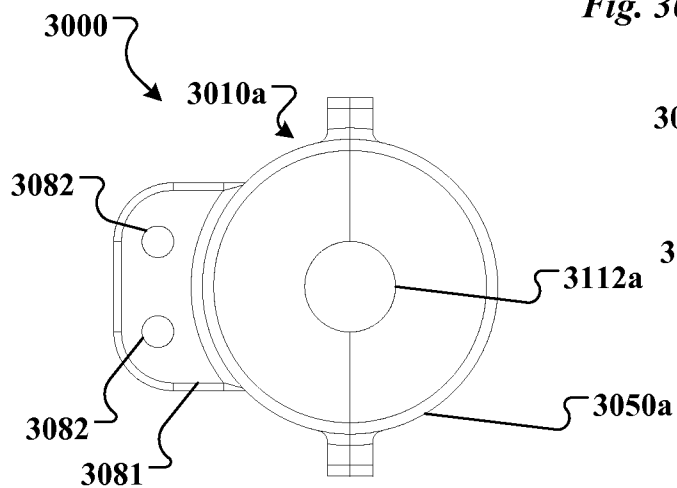


Fig. 30D

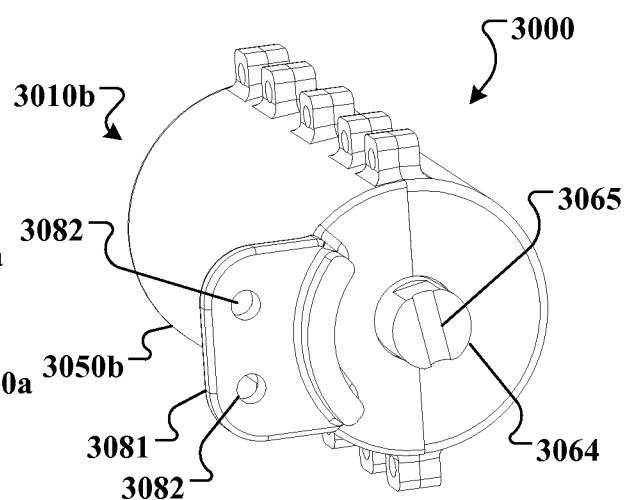
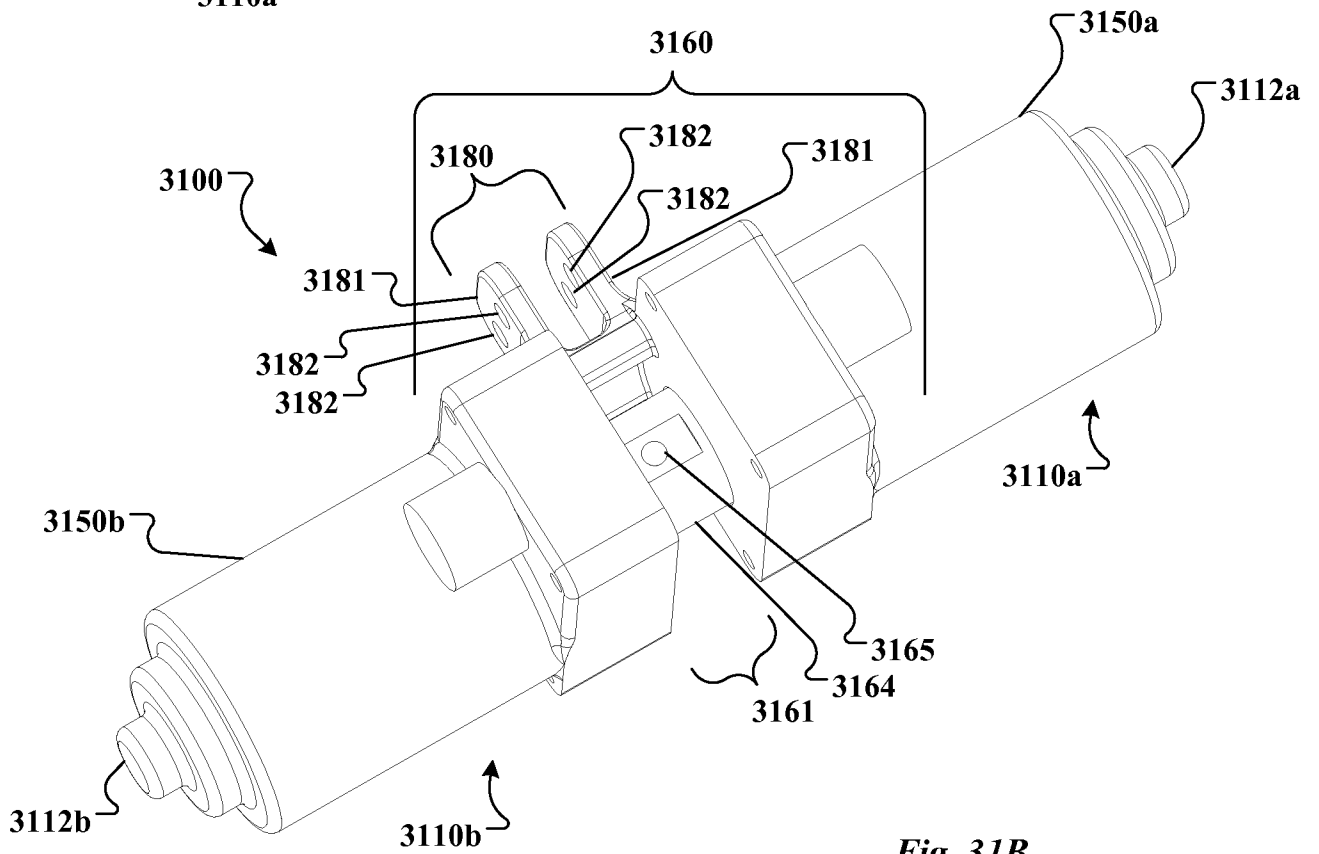
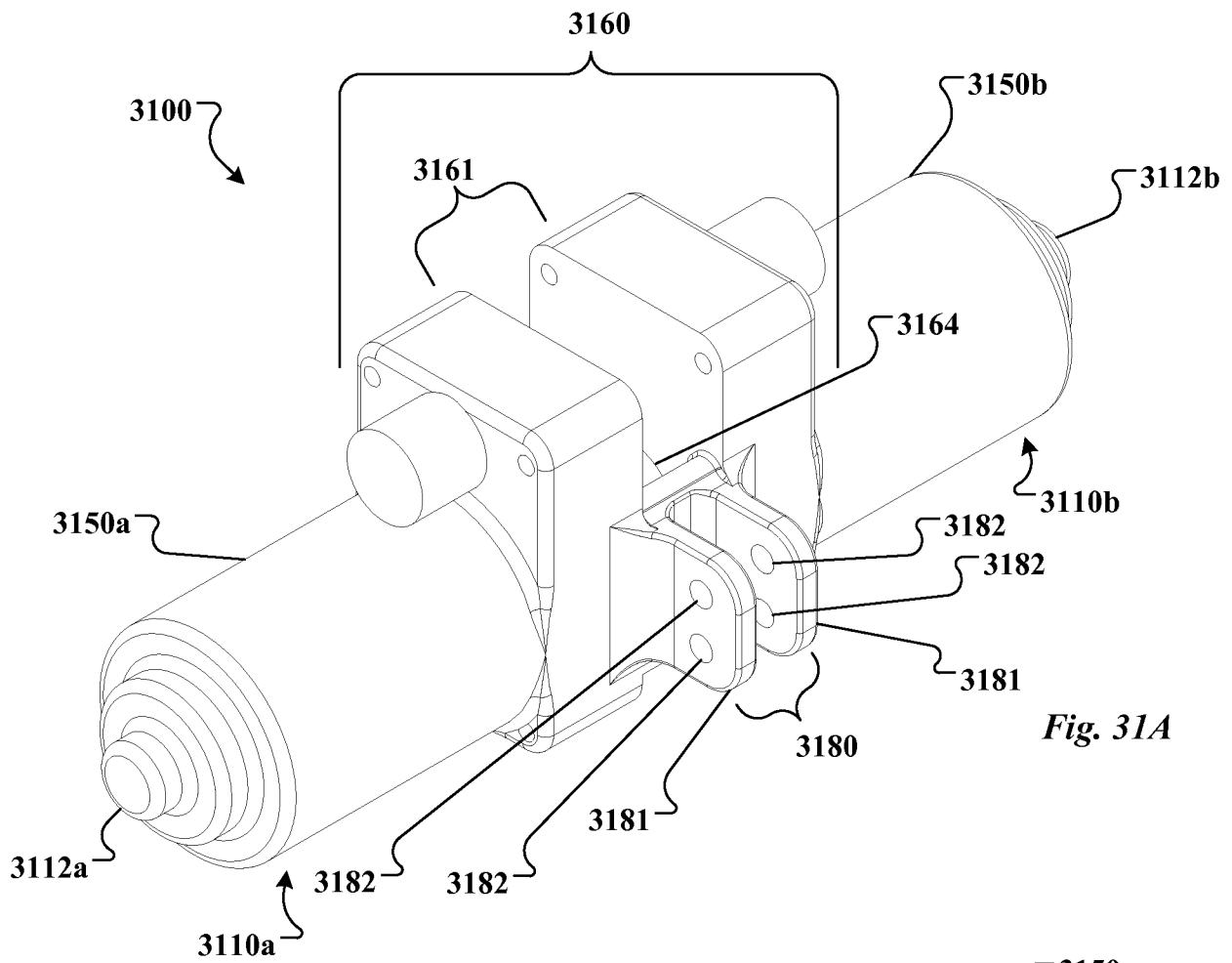
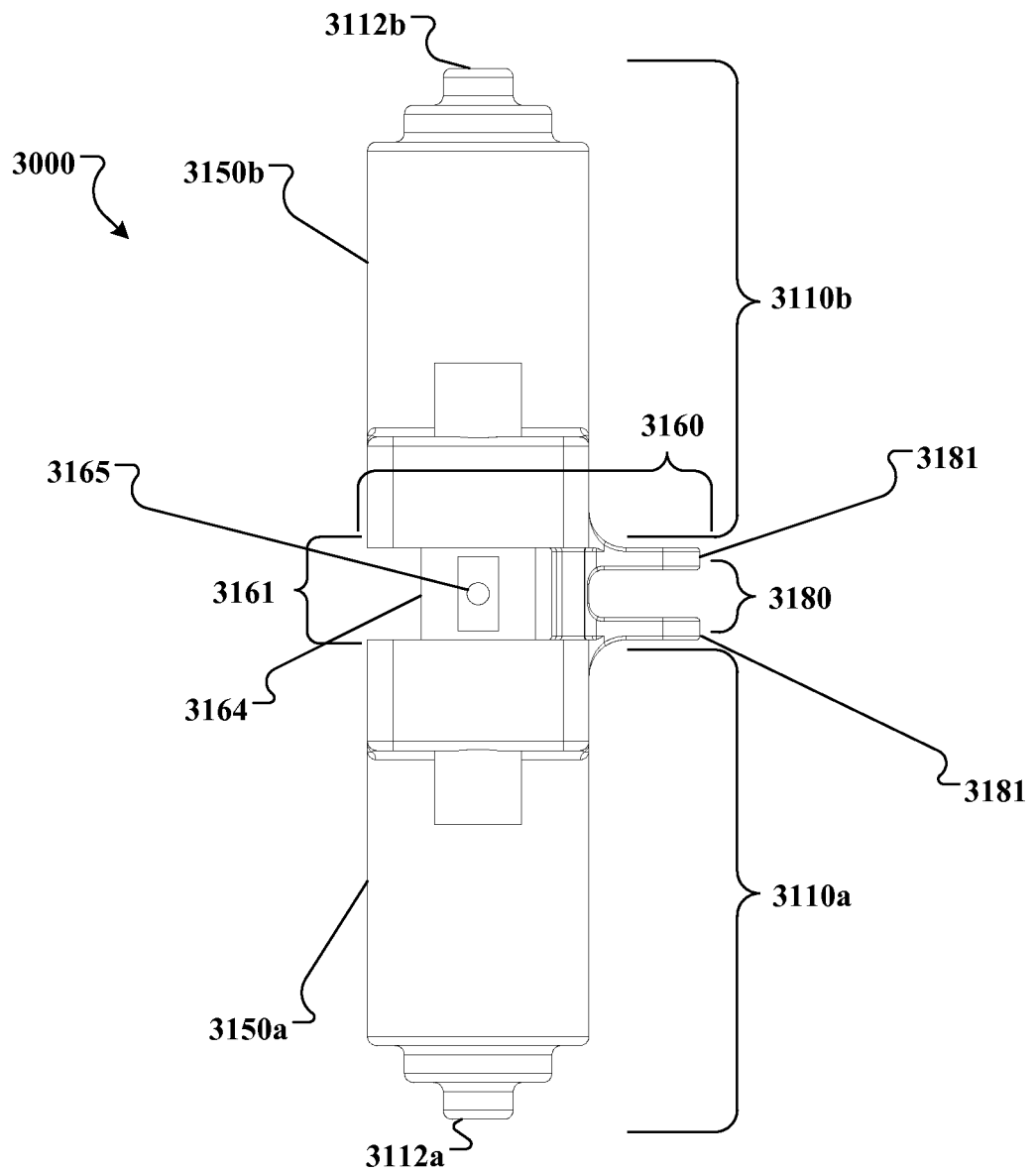
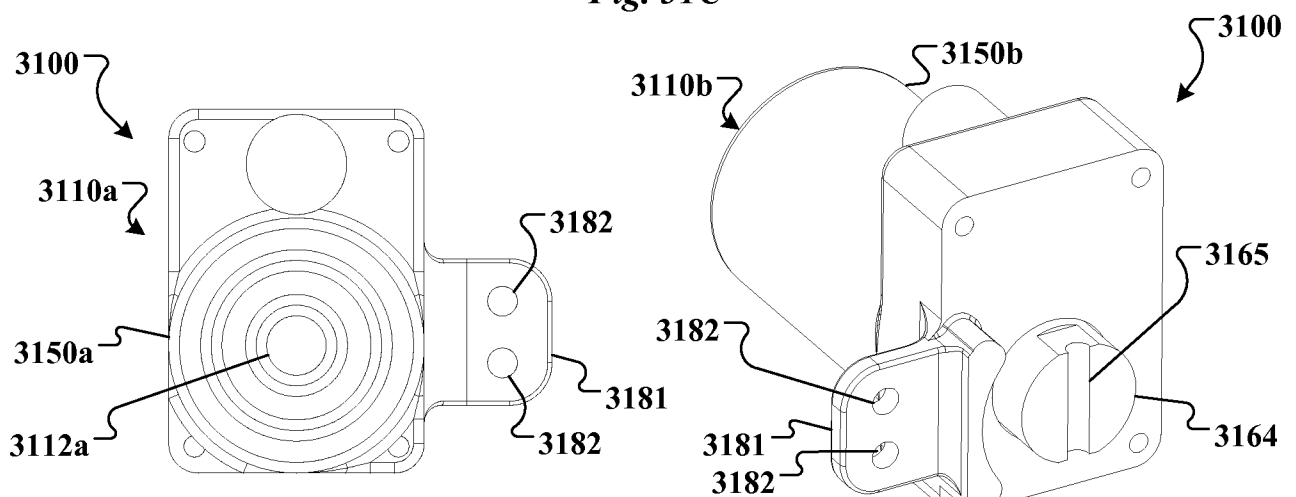


Fig. 30E



*Fig. 31C**Fig. 31D**Fig. 31E*

INTERNATIONAL SEARCH REPORT

International application No

PCT/US2014/017473

A. CLASSIFICATION OF SUBJECT MATTER
 INV. F15B15/12
 ADD.

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)
 F15B B64C

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched

Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)

EPO-Internal, WPI Data

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	US 2 936 636 A (WACHT ANDREW J) 17 May 1960 (1960-05-17) column 3, line 61 - column 7, line 53; figures 1-17	1-4, 7-14, 17-21, 24-32
X	DE 624 423 C (STOCKERT METALLWARENFABRIK GEB) 20 January 1936 (1936-01-20) the whole document	1,4,5, 7-10,14, 15, 17-21, 24,29-32



Further documents are listed in the continuation of Box C.



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Date of the actual completion of the international search

30 April 2014

Date of mailing of the international search report

13/05/2014

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Bindreiff, Romain

INTERNATIONAL SEARCH REPORT

International application No

PCT/US2014/017473

C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
X	GB 893 361 A (FAIREY COMPANY LTD) 11 April 1962 (1962-04-11) page 1, line 74 - page 3, line 23; figures 1-3 -----	1,7-10, 17-22, 24,29-32
X	US 2 649 077 A (MEHM JOSEPH A) 18 August 1953 (1953-08-18) column 2, line 23 - column 4, line 31; figures 1-7 -----	1,7-10, 17-21, 23,24, 29-32
A	WO 82/00045 A1 (BRIDWELL J; DOYLE J) 7 January 1982 (1982-01-07) the whole document -----	1-32

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No

PCT/US2014/017473

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