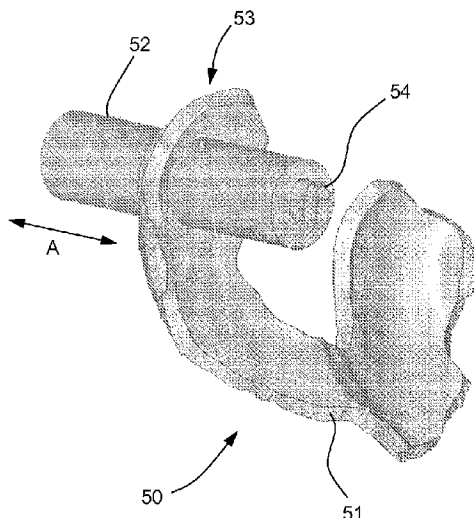




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 (54) Title: METHOD AND SYSTEM FOR CREATING PATIENT-SPECIFIC INSTRUMENTATION FOR CHONDRAL GRAFT TRANSFER



(57) **Abrégé/Abstract:**

A system for creating a patient-specific instrument model for chondral graft plugging comprises a bone model generator for producing a bone/cartilage model of an articular region of a bone from images thereof. A defect geometry identifier identifies a graft geometry from a defect region of said bone/cartilage model. A donor locator locates an autograft at a donor site or identifies an allograft from a database, using said bone/cartilage model and the graft geometry. A patient-specific instrument model generator creates a model of a graft-plugging patient-specific instrument from said bone/cartilage model, and the graft geometry, the graft-plugging patient-specific instrument model comprising a bone/cartilage interface surface shaped as a function of the bone/cartilage model for the at least one graft-plugging patient-specific instrument to be selectively positioned on the bone/cartilage to pose the autograft or the allograft at the defect region.

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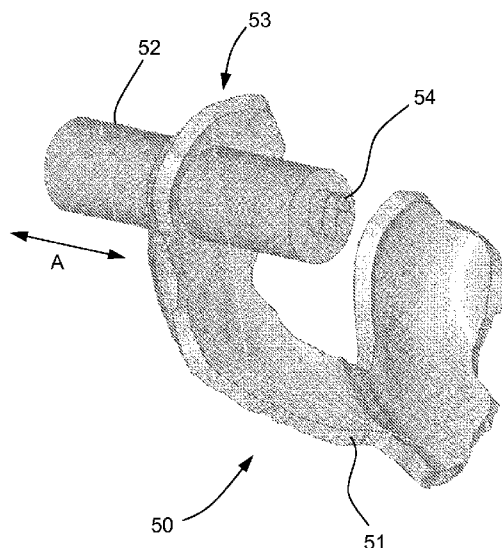


Fig. 3

(57) Abstract: A system for creating a patient-specific instrument model for chondral graft plugging comprises a bone model generator for producing a bone/cartilage model of an articular region of a bone from images thereof. A defect geometry identifier identifies a graft geometry from a defect region of said bone/cartilage model. A donor locator locates an autograft at a donor site or identifies an allograft from a database, using said bone/cartilage model and the graft geometry. A patient-specific instrument model generator creates a model of a graft-plugging patient-specific instrument from said bone/cartilage model, and the graft geometry, the graft-plugging patient-specific instrument model comprising a bone/cartilage interface surface shaped as a function of the bone/cartilage model for the at least one graft-plugging patient-specific instrument to be selectively positioned on the bone/cartilage to pose the autograft or the allograft at the defect region.

METHOD AND SYSTEM FOR CREATING PATIENT-SPECIFIC  
INSTRUMENTATION FOR CHONDRAL GRAFT TRANSFER

## CROSS-REFERENCE TO RELATED APPLICATION

**[0001]** The present application is a National Phase Entry of PCT application number PCT/US2013/022894.

## FIELD OF THE APPLICATION

**[0002]** The present application relates to chondral graft transfer, and more particularly to a method and system for the creation of patient-specific instrumentation for performing chondral graft transfer, for instance in an osteoarticular transfer procedure for the knee.

## BACKGROUND OF THE ART

**[0003]** In pre-knee replacement treatment for arthritis, cartilage replacement is often used on some patients (e.g., younger active patients) as a stopgap measure to delay the need for a complete total knee arthroplasty (a.k.a, total knee replacement). There are numerous possible treatments involving replacement of the cartilage with autografts or with allografts.

**[0004]** One such autograft treatment is the osteoarticular transfer, referred to as OATS, designed to remove cartilage from one area and graft it onto another. One consideration in such treatment is the need to match both cartilage thickness and curvature between donor location and graft location, to ensure an optimal graft. Indeed, with improper graft shapes, there may result some difficulties in aligning the hyaline cartilage in thickness and/or curvature.

## SUMMARY OF THE APPLICATION

**[0005]** It is therefore an aim of the present disclosure to provide a novel method and system to create patient-specific instrumentation to perform chondral graft transfer.

**[0006]** Therefore, in accordance with a first embodiment of the present application, there is provided a method for creating at least one patient-specific instrument model for chondral graft removal, comprising: determining a graft geometry from a defect region in a bone/cartilage model of an articular region of a bone; identifying at least one donor location from the bone/cartilage model, using the graft geometry; and creating a model of at least one graft-removal patient-specific instrument using the at least one donor location, the graft geometry, and the bone/cartilage model, the graft-removal patient-specific instrument model comprising a bone/cartilage interface surface shaped as a function of the bone/cartilage model for the at least one graft-removal patient-specific instrument to be selectively positioned on the bone/cartilage to remove cartilage from the at least one donor location.

**[0007]** Further in accordance with the first embodiment, creating the model of the at least one graft-removal patient-specific instrument comprises creating the bone/cartilage interface surface for contacting the bone, and a tooling end positioned relative to the bone/cartilage interface surface for removing cartilage at the donor location.

**[0008]** Still further in accordance with the first embodiment, creating the model of the at least one graft-removal patient-specific instrument comprises creating a joint between the bone/cartilage interface surface and the tool for guiding the tool toward the donor location.

**[0009]** Still further in accordance with the first embodiment, creating a model of a graft-plugging patient-specific instrument adapted to plug the defect region with at

least one graft, using the bone/cartilage model of the articular region of the bone and the graft geometry, the graft-plugging patient-specific instrument model comprising a bone/cartilage interface surface shaped as a function of the bone/cartilage model for the at least one graft-plugging patient-specific instrument to be selectively positioned on the bone/cartilage to pose a graft at the defect region.

**[0010]** Still further in accordance with the first embodiment, creating the model of the at least one graft-plugging patient-specific instrument comprises creating the bone/cartilage interface surface for contacting the bone, and a tooling end positioned relative to the bone/cartilage interface surface for posing the graft at the defect region.

**[0011]** Still further in accordance with the first embodiment, creating the model of the at least one graft-plugging patient-specific instrument comprises creating a joint between the bone/cartilage interface surface and the tool for guiding the tool in posing the graft at the defect region.

**[0012]** Still further in accordance with the first embodiment, the bone/cartilage model is created from imaging of the bone and cartilage.

**[0013]** Still further in accordance with the first embodiment, the method is performed pre-operatively.

**[0014]** Further in accordance with a second embodiment of the present disclosure, there is provided a system for creating a patient-specific instrument model for chondral graft plugging, comprising: a bone model generator for producing a bone/cartilage model of an articular region of a bone from images thereof; a defect geometry identifier for identifying a graft geometry from a defect region of said bone/cartilage model; a donor locator for locating an autograft at at least one donor site or identifying an allograft from a database, using said bone/cartilage model and

the graft geometry; and a patient-specific instrument model generator for creating a model of a graft-plugging patient-specific instrument from said bone/cartilage model, and the graft geometry, the graft-plugging patient-specific instrument model comprising a bone/cartilage interface surface shaped as a function of the bone/cartilage model for the at least one graft-plugging patient-specific instrument to be selectively positioned on the bone/cartilage to pose at least one of the autograft and the allograft at the defect region.

**[0015]** Further in accordance with the second embodiment, the patient-specific instrument model generator creates the bone/cartilage interface surface of the graft-plugging patient-specific instrument model for contacting the bone/cartilage, and a tooling end positioned relative to the bone/cartilage interface surface for posing the graft at the defect region.

**[0016]** Still further in accordance with the second embodiment, the patient-specific instrument model generator creates a joint in graft-plugging patient-specific instrument model the between the bone/cartilage interface surface and the tool for guiding the tool in posing the graft at the defect region

**[0017]** Still further in accordance with the second embodiment, the patient-specific instrument model generator creates a model of a graft-removal patient-specific instrument from said bone/cartilage model, the donor site and the graft geometry, the graft-removal patient-specific instrument model comprising a bone/cartilage interface surface shaped as a function of the bone/cartilage model for the at least one graft-removal patient-specific instrument to be selectively positioned on the bone/cartilage to remove the autograft from the at least one donor location.

**[0018]** Still further in accordance with the second embodiment, the patient-specific instrument model generator

creates the bone/cartilage interface surface of the graft-removal patient-specific instrument model for contacting the bone/cartilage, and a tooling end positioned relative to the bone/cartilage interface surface for removing the autograft at the donor location.

**[0019]** Still further in accordance with the second embodiment, the patient-specific instrument model generator creates a joint in graft-removal patient-specific instrument model between the bone/cartilage interface surface and the tool for guiding the tool toward the donor location.

**[0020]** Still further in accordance with the present disclosure, there is provided a method for creating at least one patient-specific instrument model for chondral graft plugging, comprising: determining a graft geometry from a defect region in a bone/cartilage model of an articular region of a bone; identifying at least one of a corresponding allograft and autograft with a donor location from the bone/cartilage model, using the graft geometry; and creating a model of at least one graft-plugging patient-specific instrument using the graft geometry, and the bone/cartilage model, the at least one graft-plugging patient-specific instrument adapted to plug at least one of an autograft and an allograft at the defect region.

**[0021]** Further in accordance with the third embodiment, the graft-plugging patient-specific instrument model comprises a bone/cartilage interface surface shaped as a function of the bone/cartilage model for the at least one graft-plugging patient-specific instrument to be selectively positioned on the bone/cartilage to pose at least one of the autograft and allograft at the defect region.

**[0022]** Still further in accordance with the third embodiment, creating the model of the at least one graft-plugging patient-specific instrument comprises creating the bone/cartilage interface surface for contacting the bone, and

a tooling end positioned relative to the bone/cartilage interface surface for posing at least one of the autograft and allograft at the defect region.

**[0023]** Still further in accordance with the third embodiment, creating the model of the at least one graft-plugging patient-specific instrument comprises creating a joint between the bone/cartilage interface surface and the tool for guiding the tool in posing the graft at the defect region.

**[0024]** Still further in accordance with the third embodiment, the bone/cartilage model is created from imaging of the bone and cartilage.

**[0025]** Still further in accordance with the third embodiment, the method is performed pre-operatively.

#### BRIEF DESCRIPTION OF THE DRAWINGS

**[0026]** Fig. 1 is a flow chart of a method for creating patient-specific instrumentation for osteoarticular transfer surgery in accordance with the present disclosure;

**[0027]** Fig. 2 is a block diagram of a patient-specific instrumentation computer-assisted surgery system for osteoarticular transfer in accordance with the present disclosure; and

**[0028]** Fig. 3 is a perspective view of a patient-specific instrumentation graft remover in accordance with the present disclosure.

#### DESCRIPTION OF THE PREFERRED EMBODIMENTS

**[0029]** Referring to the drawings, and more particularly to Fig. 1, there is illustrated at 10 a method for performing osteoarticular transfer surgery, for instance in knee applications. The method 10 creates and uses patient-specific



instrumentation (hereinafter "PSI") to remove and/or graft cartilage.

**[0030]** According to 11, the graft geometry is determined from the recipient location, i.e., the chondral articular area requiring the graft. The graft geometry may comprise the dimensions of the required graft, the thickness of the required graft, and the curvature. The graft geometry may be identified by a preoperative step, with non-invasive or minimally invasive techniques being well suited for 11. For instance, imaging technologies such as magnetic-resonance imagery or contrast-enhanced computed tomography of the bone are two of numerous technologies that can be used to image chondral defects, by the imaging of bone and chondral tissue. Other methods are contemplated as well.

**[0031]** With the imaging, the chondral defect may be quantified with the geometric details set forth above. Moreover, data is obtained pertaining to the global geometry of the bone and cartilage. The data is used to create a model of an operated site portion of the bone and cartilage including that of an area surrounding the recipient location. Reference will be made hereinafter to the model obtained in 11 as the bone/cartilage model. This will refer to a model of a portion of a bone, with layers thereon distinguishing bone from cartilage.

**[0032]** According to 12, the model of the operated site portion is used to identify donor location. The donor location comprises cartilage that generally matches the geometric details of the required graft. Moreover, the donor location is selected for practical considerations, for instance to minimize post-surgery impact on articular integrity. The donor location may consist of numerous donor sublocations, to create a graft mosaic from cartilage sections that matches the geometry details of the required graft.

**[0033]** According to an embodiment, the graft geometry may match that of available allografts. The graft geometry may therefore be compared to geometries in a database of allografts to determine whether an allograft could be used instead of or in addition to an autograft. The comparison between the modeled graft geometry and the allograft geometry could find compatibility between geometries despite some deviations. Moreover, the allograft database may comprise allografts harvested from surfaces other than that matching the donor site. For example, if appropriate and if geometries match, allografts from shoulder, hip, ankle, and the like could be used for the tibial plateau, etc.

**[0034]** According to 13, PSI is created to remove a graft from the donor location, or to alter an allograft. An example of PSI is provided and detailed hereinafter. The PSI is manufactured specifically for the patient, using the model obtained from the imaging in 11, as well as graft geometry and donor location or sublocations. For autograft removal applications, the PSI has a geometry that is made for precisely and accurately engaging onto the bone and cartilage of the patient for the removal of the graft or graft portions from the donor location or sublocations.

**[0035]** According to 14, PSI may be created to plug the graft obtained from the donor location in the recipient location. Again, the PSI is manufactured specifically for the patient, using the model obtained from the imaging in step 11, as well as recipient location. The PSI has a geometry that is made for precisely and accurately engaging onto the bone and cartilage of the patient for plugging the graft or graft portions at the recipient location. The PSI according to 14 may be used to plug an allograft in the donor location.

**[0036]** Other PSI may be created to perform other tasks. For instance, an instrument could be used to clean (e.g., burr) chondral tissue in the defect region with a view to

receiving the graft. The PSI used for such purpose may include a support to hold the appropriate tools in a specific position and/or orientation relative to the tool, to control the cleaning procedure. PSI could be generated to modify allografts as well.

**[0037]** According to 15, graft surgery (i.e., osteoarticular transfer) is performed. Accordingly, steps 11-14 may be performed pre-operatively using proper imaging technologies, to minimize surgical time. Moreover, by the use of PSI, the surgical procedure is performed efficiently, as the PSI is already shaped to the bone model, whereby no extensive calibration is required.

**[0038]** Referring to Fig. 2, a computer-assisted surgery system (hereinafter "CAS system") for osteoarticular transfer is generally shown at 20. The CAS system 20 receives bone and cartilage imagery 30 from any appropriate imaging technology (e.g., MRI, enhanced-contrast CT). The imaging technology apparatus may be a part of the CAS system 20. The imagery 30 may comprise three-dimensional images of the articular region of the bone, with layers representative of the cartilage thereon, enabling to discriminate bone from cartilage.

**[0039]** The CAS system 20 comprises a CAS processor unit 40 that receives the bone images 30, and that will produce PSI models from the images 30. The CAS processor unit 40 has a processor to run the application that will generate the PSI models. Accordingly, the CAS processor unit 40 may be any appropriate computer or processing unit. User interfaces (e.g., monitor, screen, keyboard, mouse, touch-screen) are part of the CAS processor unit 40, for the involvement of an operator in the creation of the PSI models.

**[0040]** The CAS processor unit 40 comprises a bone model generator 41. The bone model generator 41 is used to interpret the images 30, and thus to create a model of the articular region of the bone. The model distinguishes

chondral tissue from the bone, thereby enabling to segment out the chondral tissue from the bone, effectively creating a model of the cartilage on its supporting structure, i.e., the bone. The operator's input may be required in distinguishing cartilage from bone and/or for confirming the proper segmentation between bone and cartilage. The interfaces may be used for this purpose.

**[0041]** A defect geometry identifier 42 uses the model of the cartilage to determine a graft geometry. The defect geometry identifier 42 defines the geometrical parameters of the graft, such as dimensions, thickness, curvature, etc. The operator's input may also be required, for instance to delimit chondral defect from the images.

**[0042]** A donor locator 43 then matches the graft geometry from the defect geometry identifier 42 to the cartilage model of the bone model generator 41. The donor locator 43 locates parts of the cartilage model that could be donor locations or sites, from the geometric data of the required graft. The donor locator 43 may also ensure that the donor site is indeed well suited for the removal of graft, without affecting the articular integrity. For instance, the donor locator 43 may relate the donor site to its location on the bone, with some regions of the bone being excluded from being donor sites.

**[0043]** The donor locator 43 may identify more than one potential donor location, with the operator selecting the donor location among the potential sites. Moreover, the donor locator 43 may identify a plurality of donor sublocations, which sublocations would produce a graft mosaic having the geometry of the defect, i.e., the graft geometry provided by the defect geometry identifier 42.

**[0044]** Still referring to Fig. 2, a PSI generator 44 uses the graft geometry, donor locations and bone/cartilage models to produce PSI models. The PSI models will be used to manufacture patient-specific instrumentation that will be used

to remove specific sizes and geometries of chondral tissue from the donor locations, that may be used to plug chondral defect, and that may be used to clean a defect zone with a view to receiving a graft. As seen hereinafter, the PSI must connect in a precise and accurate way to the bone/cartilage, whereby the PSI generator 44 uses the bone/cartilage models to produce the PSI models. The PSI models may be in any appropriate format to allow the manufacture of PSI. For instance, the PSI models are formatted into NC machine files, technical data, visual or digital models, etc.

**[0045]** As mentioned above, the graft geometry may be compared with the geometries of available allografts by the donor locator 43, as shown by 45. If a match is found, an allograft or allografts could be used instead or in addition to autografts. A PSI model or models may be produced for PSI that may alter an allograft or allografts into the graft having an appropriate geometry for the recipient location.

**[0046]** Referring concurrently to Figs. 2 and 3, an example of a PSI graft remover 50 is shown, the graft remover 50 having a similar configuration to a PSI graft plugger 60 (Fig. 2). The PSI graft remover 50 comprises a guide 51. The guide 51 is an arcuate plate or like PSI interface that is specifically shaped to geometrically correspond to a surface of the bone and/or cartilage surrounding the donor location, or recipient location in the case of the PSI graft plugger 60. Accordingly, when the guide 51 is applied against the bone/cartilage, a bone/cartilage interface surface thereof will be in flush contact with a surface of bone and/or cartilage adjacent to the donor location and/or the recipient location and therefore in a desired position and orientation relative to the bone/cartilage. Moreover, although the interface surface 51 is shown as being a single relatively large surface, the interface surface 51 may defined by the end

surfaces of a plurality of posts that are modeled as a function of a geometry of the bone/cartilage.

**[0047]** The guide 51 may have an opening slidably supporting a punch 52, thereby forming a sliding or translational joint 53. According to an embodiment, the translation joint 53 is a prismatic joint, or any appropriate joint that limits the movement of the punch 52 to one degree of freedom (DOF). As another example, a one-DOF pivot joint could relate the punch to the guide. In Fig. 3, the guide 51 moves along direction A. It is also considered that the guide 51 and tooling be in a fixed relation to one another, i.e., without any joint providing any DOF therebetween.

**[0048]** The PSI graft remover 50, the PSI graft plugger 60 and other PSI tools 70 have a tooling end at which a tool is located, for performing alterations on cartilage. In Fig. 3, the tool is a cutout 54 is located at the tooling end of the punch 52, in a predetermined position and orientation relative to the interface surface of the guide 51, to perform alterations at the donor location. The periphery of the cutout 54 (i.e., cutter) is selected as a function of the graft geometry, with the free edge of the cutout 54 being sharpened to cut through chondral tissue with a suitable force applied onto the punch 52. Moreover, the height of the cutout 54 may be defined so as to remove a desired thickness and geometry of cartilage. Therefore, the PSI graft remover 50 is specifically devised to cut out tightly controlled cartilage shapes. A tool with a geometry similar to the cutout 54 may be used in the PSI graft plugger 60 to releasably support graft during its plugging, in the case where the PSI graft plugger 60 has a configuration similar to that of the PSI graft remover 50. In such a case, the cutout-like tool is in a predetermined position and orientation relative to the interface surface of the guide 51, to pose the graft at the recipient location. As an alternative, the plugger 60 may

have any appropriate configurations to releasably hold the graft in the desired position and orientation on the guide 51.

**[0049]** Referring to Fig. 2, other similar PSI tools may be devised for other functions, such as graft plugging with a PSI graft plugger 60, other any other appropriate function via tools 70 (e.g. burring). Such other tools would have appropriate geometries to interact with the bone and cartilage. The other tools may be designed as a function of any one of the bone and cartilage models, donor location, graft geometry, recipient location, etc.

CLAIMS:

1. A method for creating at least one patient-specific instrument model for chondral graft removal, comprising:

determining with a computer-assisted surgery processor unit a graft geometry from a defect region in a bone and cartilage digital model of an articular region of a bone, the graft geometry having a non-circular periphery corresponding to a defect in cartilage;

identifying with the computer-assisted surgery processor unit at least one donor location from the bone and cartilage digital model, using the graft geometry;

creating with the computer-assisted surgery processor unit a digital model of at least one graft-removal patient-specific instrument using the at least one donor location, the graft geometry, and the bone and cartilage digital model, the graft-removal patient-specific instrument model comprising an interface surface shaped as a function of the bone and cartilage digital model for the at least one graft-removal patient-specific instrument to be configured to be selectively positioned on at least one of the bone and cartilage to remove cartilage from the at least one donor location, and a tooling end having a cutout with a geometry corresponding to the graft geometry for removing the cartilage with said graft geometry, the cutout having said non-circular periphery to match the defect; and

outputting with the computer-assisted surgery processor unit the digital model of the at least one graft-removal patient-specific instrument as a digital fabrication file.

2. The method according to claim 1, wherein creating the digital model of the at least one graft-removal patient-specific instrument comprises creating a translational joint



between the interface surface and the tooling end for guiding the tooling end toward the donor location.

3. The method according to any one of claims 1 and 2, further comprising creating a digital model of a graft-plugging patient-specific instrument adapted to plug the defect region with at least one graft, using the bone and cartilage digital model of the articular region of the bone and the graft geometry, the graft-plugging patient-specific instrument digital model comprising another interface surface shaped as a function of the bone and cartilage model for the at least one graft-plugging patient-specific instrument to be configured to be selectively positioned on at least one of the bone and cartilage to plug a graft at the defect region.

4. The method according to claim 3, wherein creating the digital model of the at least one graft-plugging patient-specific instrument comprises creating the other interface surface for contacting the bone, and a tooling end positioned relative to the other interface surface for plugging the graft at the defect region.

5. The method according to claim 4, wherein creating the digital model of the at least one graft-plugging patient-specific instrument comprises creating a translational joint between the other interface surface and the tooling end for guiding the tooling end in plugging the graft at the defect region.

6. The method according to claim 3, wherein:

the other interface surface is distinct from the interface surface, and

the other interface surface corresponds to a single surface of the at least one patient-specific instrument that is

configured to be in flush contact with a surface of tissue adjacent to the defect region.

7. The method according to claim 3, wherein creating the digital model of the at least one graft-removal patient-specific instrument comprises:

creating, with the computer-assisted surgery processor unit, the interface surface of the digital model of the at least one graft-removal patient-specific instrument; and

creating, with the computer-assisted surgery processor unit, the tooling end of the digital model of the at least one graft-removal patient-specific instrument.

8. The method according to any one of claims 1 to 7, further comprising creating the bone and cartilage digital model from imaging of the bone and cartilage.

9. The method according to any one of claims 1 to 8, wherein the method is performed pre-operatively.

10. The method according to any one of claims 1 to 9, further comprising manufacturing the at least one graft-removal patient-specific instrument specifically for a patient using the digital fabrication file.

11. The method according to any one of claims 1 to 10, wherein:

the interface surface is shaped as a function of a portion of the bone and cartilage digital model that corresponds to the at least one donor location; and

the interface surface corresponds to a single surface of the at least one patient-specific instrument that is configured to be in flush contact with a surface of tissue adjacent to the at least one donor location.

12. The method according to claim 11, wherein the interface surface is shaped to position and orientation the at least one graft-removal patient-specific instrument in a desired position and orientation relative to the at least one donor location.

13. A system for creating a patient-specific instrument model for chondral graft plugging, the system including a computer-assisted surgery processor unit comprising:

a bone model generator for producing a bone and cartilage digital model of an articular region of a bone from images thereof; a defect geometry identifier for identifying a graft geometry from a defect region of said bone and cartilage digital model, the graft geometry having a non-circular periphery corresponding to a defect in cartilage;

a donor locator for locating an autograft at at least one donor site or identifying an allograft from a database, using said bone and cartilage digital model and the graft geometry; and

a patient-specific instrument model generator for creating a digital model of a graft-plugging patient-specific instrument from said bone and cartilage digital model, and the graft geometry, the graft-plugging patient-specific instrument digital model comprising an interface surface shaped as a function of the bone and cartilage digital model for the at least one graft-plugging patient-specific instrument to be configured to be selectively positioned on at least one of the bone and cartilage to plug at least one of the autograft and the allograft at the defect region, a tooling end having a periphery to attach to the non-circular periphery of the defect and positioned relative to the interface surface for plugging at least one of the autograft and allograft at the defect region, and a translational joint between the interface

surface and the tool for guiding the tool in plugging the graft at the defect region.

14. The system according to claim 13, wherein the patient-specific instrument model generator creates a model of a graft-removal patient-specific instrument from said bone and cartilage model, the donor site and the graft geometry, the graft-removal patient-specific instrument model comprising another interface surface shaped as a function of the bone and cartilage digital model for the at least one graft-removal patient-specific instrument to be configured to be selectively positioned on at least one of the bone and cartilage to remove the autograft from the at least one donor location.

15. The system according to claim 14, wherein the patient-specific instrument model generator creates the other interface surface of the graft-removal patient-specific instrument model for contacting at least one of the bone and cartilage, and a tooling end positioned relative to the interface surface for removing the autograft at the donor location, the tooling end having a cutout with a geometry corresponding to the graft geometry for removing the cartilage with said graft geometry, the cutout having said non-circular periphery to match the defect.

16. The system according to claim 15, wherein the patient-specific instrument model generator creates a translational joint in graft-removal patient-specific instrument model between other interface surface and the tool for guiding the tool toward the donor location.

17. A method for creating at least one patient-specific instrument model for chondral graft plugging, comprising:

determining with a computer-assisted surgery processor unit a graft geometry from a defect region in a bone and cartilage digital model of an articular region of a bone, the graft geometry having a non-circular periphery corresponding to a defect in cartilage;

identifying with the computer-assisted surgery processor unit at least one of a corresponding allograft and autograft with a donor location from the bone and cartilage digital model, using the graft geometry;

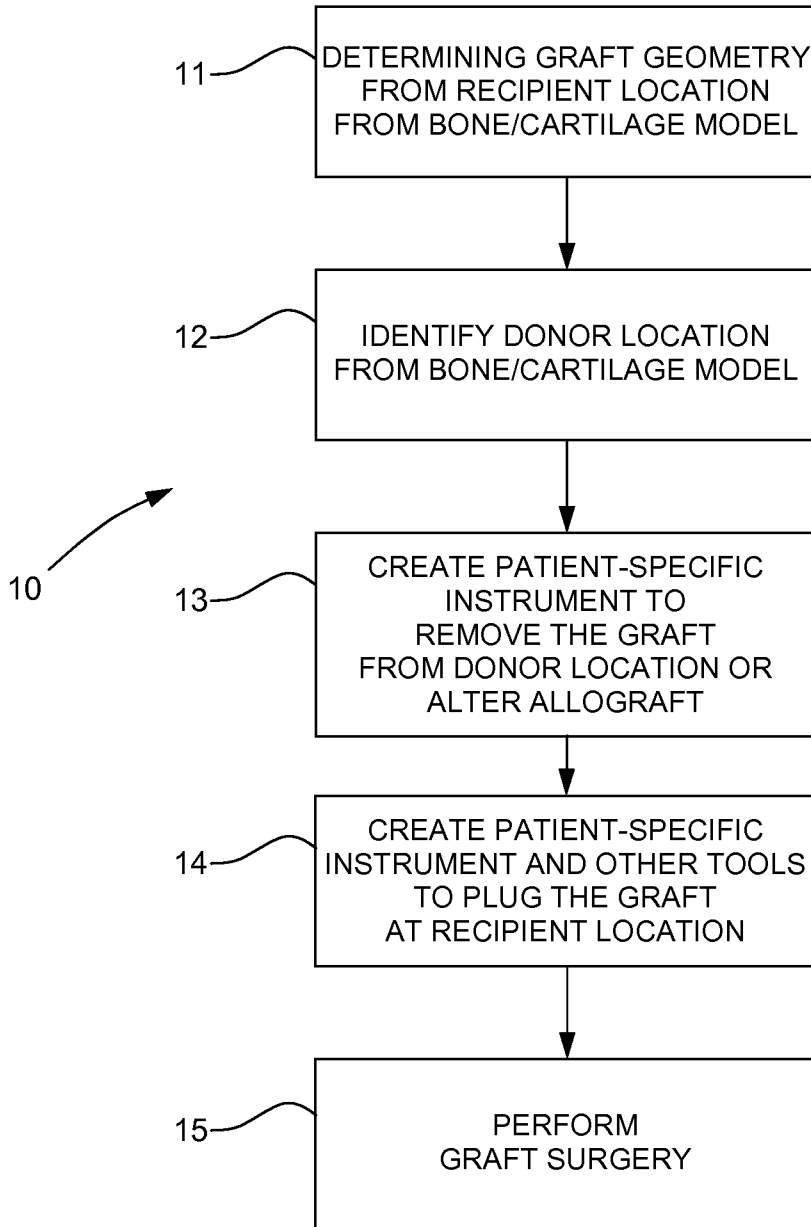
creating with the computer-assisted surgery processor unit a digital model of at least one graft-plugging patient-specific instrument using the graft geometry, and the bone and cartilage digital model, the at least one graft-plugging patient-specific instrument adapted to plug at least one of an autograft and an allograft at the defect region, the graft-plugging patient-specific instrument digital model comprising an interface surface shaped as a function of the bone and cartilage digital model for the at least one graft-plugging patient-specific instrument to be configured to be selectively positioned on at least one of the bone and cartilage to plug at least one of the autograft and allograft at the defect region, a tooling end having a periphery to attach to the non-circular periphery of the defect and positioned relative to the interface surface for plugging at least one of the autograft and allograft at the defect region, and a translational joint between the interface surface and the tool for guiding the tool in plugging the graft at the defect region; and

outputting with the computer-assisted surgery processor unit the digital model of the at least one graft-plugging patient-specific instrument as a digital fabrication file.

18. The method according to claim 17, further comprising creating the bone and cartilage digital model from imaging of the bone and cartilage.

19. The method according to any one of claims 17 and 18, wherein the method is performed pre-operatively.

20. The method according to any one of claims 17 to 19, further comprising manufacturing the at least one graft-plugging patient-specific instrument specifically for a patient using the digital fabrication file.



**Fig. 1**

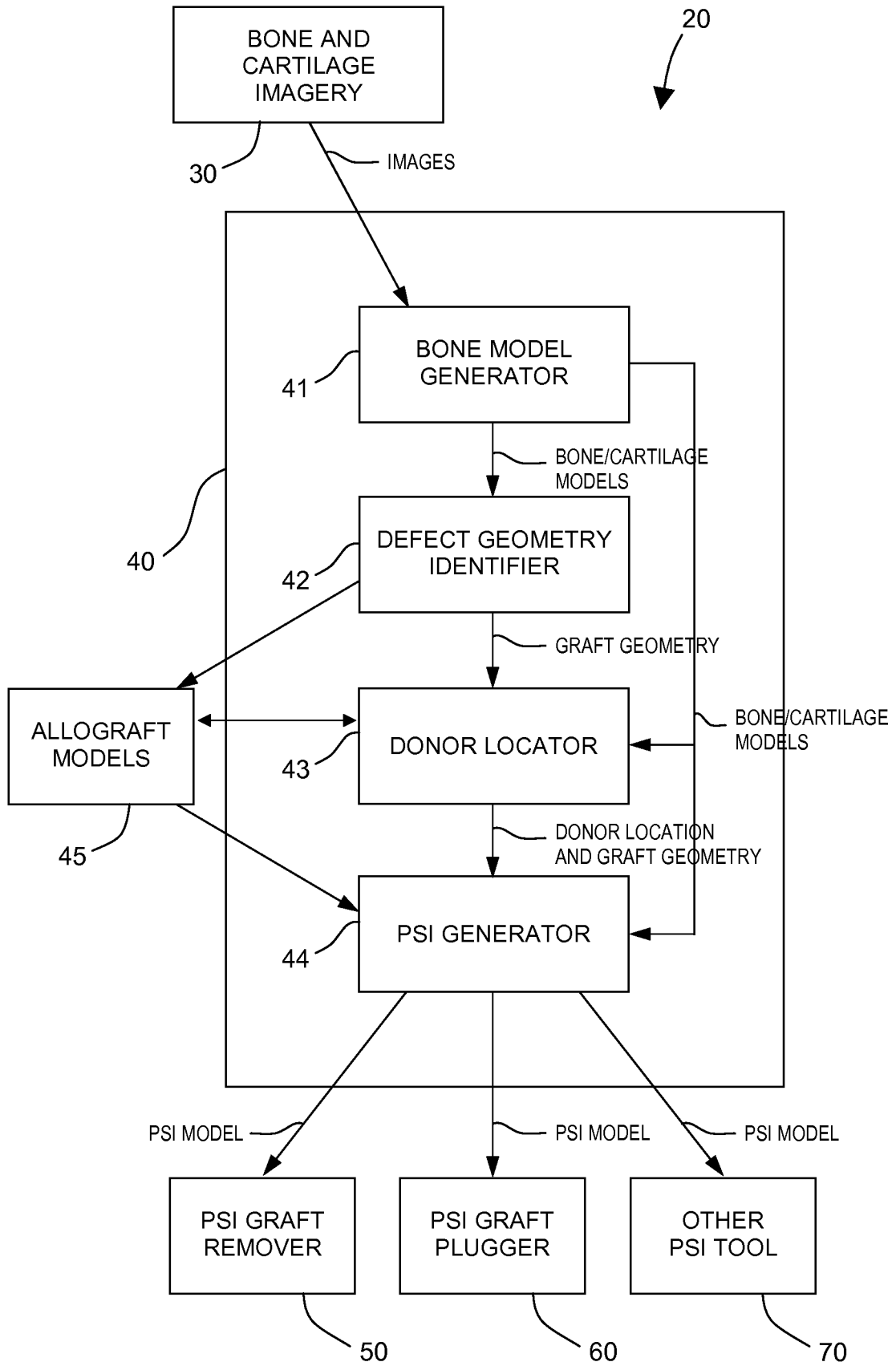
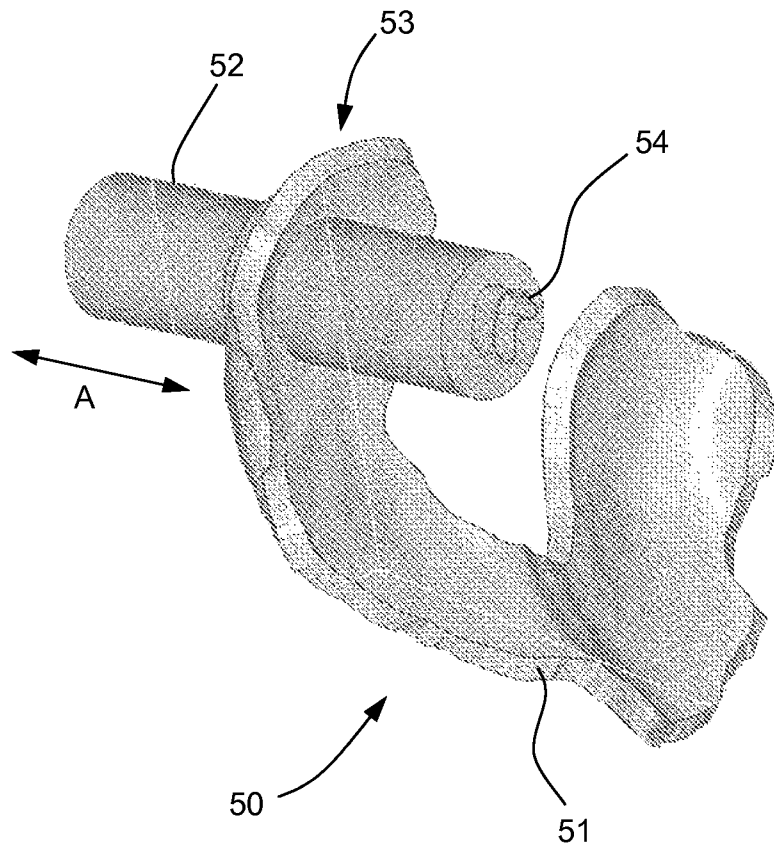


Fig. 2





**Fig. 3**

