



INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

(51) International Patent Classification 5 : H04N 1/46, G03F 3/08	A1	(11) International Publication Number: WO 92/06557 (43) International Publication Date: 16 April 1992 (16.04.92)
(21) International Application Number: PCT/US91/06911 (22) International Filing Date: 25 September 1991 (25.09.91) (30) Priority data: 590,375 28 September 1990 (28.09.90) US 717,099 18 June 1991 (18.06.91) US (71) Applicant: EASTMAN KODAK COMPANY [US/US]; 343 State Street, Rochester, NY 14650-2201 (US). (72) Inventors: NEWMAN, Gary, H. ; 115 North Branch Road, Concord, MA 01742 (US). ENSCOE, Christopher, J. ; RD 1, P.O. Box 60, Earleville, NY 13332 (US). POE, Ro- bert, F. ; 5 Russell Street, Charlestown, MA 02129 (US). GREGORY, H., Scott, Jr. ; 31 Meadowbrook Road, Bedford, MA 01730 (US). SCHWARTZ, Michael, S. ; 88 Park Avenue, Apt. 305, Arlington, MA 02174 (US).		(74) Agent: DUGAS, Edward; 343 State Street, Rochester, NY 14650-2201 (US). (81) Designated States: AT (European patent), BE (European patent), CH (European patent), DE (European patent), DK (European patent), ES (European patent), FR (Eu- ropean patent), GB (European patent), GR (European patent), IT (European patent), JP, KR, LU (European patent), NL (European patent), SE (European patent). Published <i>With international search report.</i> <i>Before the expiration of the time limit for amending the</i> <i>claims and to be republished in the event of the receipt of</i> <i>amendments.</i>
(54) Title: COLOR IMAGE PROCESSING SYSTEM FOR PREPARING A COMPOSITE IMAGE TRANSFORMATION MODULE FOR PERFORMING A PLURALITY OF SELECTED IMAGE TRANSFORMATIONS <div data-bbox="446 1209 1244 1747"> </div>		

FOR THE PURPOSES OF INFORMATION ONLY

Codes used to identify States party to the PCT on the front pages of pamphlets publishing international applications under the PCT.

AT	Austria	ES	Spain	MG	Madagascar
AU	Australia	FI	Finland	ML	Mali
BB	Barbados	FR	France	MN	Mongolia
BE	Belgium	GA	Gabon	MR	Mauritania
BF	Burkina Faso	GB	United Kingdom	MW	Malawi
BG	Bulgaria	GN	Guinea	NL	Netherlands
BJ	Benin	GR	Greece	NO	Norway
BR	Brazil	HU	Hungary	PL	Poland
CA	Canada	IT	Italy	RO	Romania
CF	Central African Republic	JP	Japan	SD	Sudan
CG	Congo	KP	Democratic People's Republic of Korea	SE	Sweden
CH	Switzerland			SN	Senegal
CI	Côte d'Ivoire	KR	Republic of Korea	SU ⁺	Soviet Union
CM	Cameroon	LI	Liechtenstein	TD	Chad
CS	Czechoslovakia	LK	Sri Lanka	TG	Togo
DE*	Germany	LU	Luxembourg	US	United States of America
DK	Denmark	MC	Monaco		

⁺ Any designation of "SU" has effect in the Russian Federation. It is not yet known whether any such designation has effect in other States of the former Soviet Union.

-1-

**COLOR IMAGE PROCESSING SYSTEM
FOR PREPARING A COMPOSITE IMAGE
TRANSFORMATION MODULE FOR PERFORMING A
PLURALITY OF SELECTED IMAGE TRANSFORMATIONS**

5

Background of The Invention

The invention relates generally to color image processing systems, and in particular to color image processing systems employing look-up tables for transforming from a first coordinate space to a second coordinate space.

Color image processing systems typically include an input device for generating an electronic representation of a color image. The input device provides the electronic image representation to a computer workstation which processes the image in accordance with a user's instructions and forwards the processed image to a high resolution color monitor for display. The user interacts with the workstation, repeatedly instructing it to adjust the electronic image until the monitor displays a desired image. The user can also generate a hard copy of the image by instructing the workstation to provide the processed electronic image to a selected printing device.

The electronic image processed by the workstation consists of a two dimensional array of picture elements (pixels). The color of each pixel may be represented in any of a variety of color notations or "color spaces." For example, the RGB color space represents pixel colors according to the relative contributions of three primary colors, red, green and blue. This color notation is commonly used by color monitors since the three parameters (R, G, B) correspond to the mechanism by which the monitor generates color. more specifically, each pixel of the monitor's display contains three primary color phosphors. To generate a color defined by a set of RGB

values, the monitor stimulates each primary phosphor with an intensity determined by the corresponding R, G, B value.

Similarly, the CMYK color space represents
5 color using four variables, C, M, Y, K, each
corresponding to the relative (subtractive)
contribution of the colorants, cyan, magenta, yellow
and black. This notation is commonly used by printing
10 devices since each parameter C, M, Y and K determines
the amount of a colorant (e.g. ink, dye) used by the
printer in producing a desired color.

Color spaces such as linear RGB and CMYK are
useful for image scanning devices and image printing
15 devices, respectively, since each parameter of the
color space closely corresponds to a physical mechanism
by which these devices measure and generate color.
However, for a variety of reasons, these color spaces
may not be well suited for processing color images.
For example, as shown in Figure 1, the three parameters
20 R, G, B define a three dimensional, linear color space,
each point within the space corresponding to a unique
color. At various points within the space, a selected
change in the values of the parameters may not result
in a commensurate change in the perceived color. For
25 example, at one location in the space, increasing the
parameter R by n units yields little perceived change
in color. Yet, at another point in the space,
increasing R by the same n units yields a dramatic
change in the perceived color. Accordingly, it may be
30 difficult for a user to manipulate the primaries R, G,
B, to achieve a desired change in color.

In response to this problem, a variety of
perceptually based color spaces have been proposed for
defining color in terms of parameters which more
35 closely correspond to the manner in which humans
perceive color. The most prominent perceptually based
standards for color representation are collectively

referred to as the CIE system promulgated by the International Commission on Illumination.

5 The "u'v'L*" space, for example, is a three dimensional color space defined by the parameters u', v', L*. The chromaticity of each color in this space is uniformly characterized by the parameters u', v'. The third parameter, L*, denotes perceptually uniform variations in the lightness of the color, (e.g., L*=0 is black, L*=100 is white).

10 To process a color image in the "u'v'L*" color space, the workstation simply maps each point u'_0, v'_0, L^*_0 in the color space to a new point u'_1, v'_1, L^*_1 . For example, if the user desires to display the image on a monitor, he may wish to adjust the
15 colors of the image to compensate for lighting conditions of the room. Accordingly, the user selects a transform which maps each point u'_0, v'_0, L^*_0 to a new point having the same values u'_0, v'_0 but having greater luminance value L^*_1 .

20 The image processing system typically contains a predetermined transform definition for each such color image transformation. Based on a selected definition, the system maps certain points of the color space to new points. Accordingly, the color at each
25 pixel of an electronic image is sequentially mapped in accordance with the transform definition to yield the desired visual effect. To perform another image transformation, the system remaps the color values to yet another point in accordance with a second transform
30 definition. Any number of transformations can thus be performed by sequentially mapping color values according to the available predetermined transform definitions. However, such sequential processing of images can be extremely time consuming, particularly if
35 a large number of predetermined transforms are selected.

-4-

Therefore, one object of the present invention is to enable the user of an image processing system to dynamically create a single transform definition embodying a plurality of selected image transformations. A further object of the present invention is to build such a composite transform definition using the plurality of predetermined transform definitions. Yet a further object of the invention is to provide a new format definition for the transformation for easily defining the color processing requirements between hardware systems.

Summary of The Invention

The invention relates to a method and apparatus for generating an array of modified pixel values in response to an array of input pixel values.

The method features the steps of receiving a user's selection of an image transformation to be performed on the array of input pixel values. In response to the user's selections, a plurality of transform definitions are automatically selected from stored transform definitions. Each transform definition includes sample values representing an input/output relation of a predetermined image transformation. From these selected transform definitions, a composite transform definition is generated containing sample values of an input/output relation of a composite image transformation which is equivalent to the several image transformations effectively selected by the user. The composite transform is preferably compiled and implemented sufficiently quickly (e.g., in real time) to allow the user to interactively change his selections until a desired composite transformation is created.

Preferred aspects of the invention include the step of generating the composite transform definition by preparing at least one multidimensional

grid table containing the sample values of the composite transform definition. Further, at least one input table is prepared containing, for each input color value, a grid table address of a corresponding entry of the grid table. The input table additionally contains, for each input color value, at least one distance value. Finally, at least one output table is prepared, specifying for each processed color value, a corresponding modified color value.

10 To prepare a multidimensional composite grid table, the selected transform definitions are ordered in a specified sequence such that the pixel values generated by each transform are in the color space and have the quantization required by the next transform in the sequence. A plurality of representative values are then selected and sequentially processed according to the specified sequence of transform definitions.

To implement a composite transform definition, at least one sample value is selected from the composite transform definition, based on the value of an input color to be modified. A processed color value is then determined based on the at least one selected sample value. For example, in one embodiment, a nearest neighbor of the input color value is selected as the sample value. In another embodiment, a plurality of sample values are selected and the processed color value is determined by interpolating between these values.

In another aspect of the invention, the stored transform definitions may include predetermined transform definitions and custom transform definitions made in accordance with a user's instruction. A user's instructions specifying desired color changes are received. A custom transform definition is then prepared for implementing the selected color changes. Such custom transforms may be created by modifying predetermined transforms or be generating entirely new

transforms based on the user's input.

Other objects, features and advantages of the invention are apparent from the following description of particular preferred embodiments taken together with
5 the drawings.

Brief Description of the Drawings

Figure 1 is a diagram of the RGB color space.

Figure 2 is a block diagram of an image
10 processing system in accordance with the claimed invention.

Figure 3(a) is a flow chart illustrating the implementation of a sequence of predetermined transform definitions.

15 Figure 3(b) is a flow chart illustrating the implementation of a composite transform definition.

Figure 4 is a block diagram of a sequence of transform operations.

Figure 5 is a block diagram of a transform
20 processor.

Figure 6 is a more detailed block diagram of a single channel of a transform processor.

Figure 7(a) is a diagram illustrating the mapping of a first point in $u'v'L^*$ space to a new point
25 in the same space.

Figure 7(b) is a diagram of a set of reference points in the $u'v'L^*$ color space.

Figures 8(a) and 8(b) are diagrams illustrating the implementation of a sequence of
30 transform definitions.

Figure 8(c) is a diagram of a composite transform which is equivalent to the sequential implementation of the transforms illustrated in Figures 8(a) and 8(b).

35 Figure 9 is a block diagram of a composite transform definition and a processor for implementing the composite transform definition.

Figure 10 is a block diagram illustrating the loading of the grid tables of the composite transform definition illustrated in Figure 8(c).

Figure 11 is a block diagram of a set of
5 identity transform definitions and a processor for implementing them.

Figures 12(a) 12(b) and 12(c) are diagrams illustrating an alternative technique for computing sample values of a composite transform and loading the
10 sample values into the grid tables of a composite transform definition.

Figure 13 is a diagram illustrating a technique for simultaneously loading the grid tables of all channels of a composite transform definition.

Figure 14 is a diagram of a format for
15 communicating a transform definition.

Description of The Preferred Embodiments

Referring to Figure 2, an image processing
20 system 8 includes a plurality of input devices 10 for scanning a source image (such as a photograph, film, or a scene within the view of a camera) to create an electronic digital representation of the image. The electronic representation is provided to an image
25 processor 14 which adjusts the colors of the electronic image and either stores the adjusted image on storage device 17 (e.g., for later retrieval and processing) or forwards it to various output devices 16 for printing, display or transmission over a network 15 or any other
30 communication channel.

Image processor 14 is connected to a user interface 22 through which a user indicates the desired transformations to be performed on an electronic image. In general, image processor 14 and user interface 22
35 are implemented with a properly programmed general purpose computer or computer workstation.

In response to the user's request, in one mode of operation, a transform controller 20 selects a set of transform definitions from a collection 19 of stored predetermined transform definitions. Each
5 predetermined transform definition describes a unique transform for mapping the values representing each color of an image in a first color space to a different set of values (e.g., a different color in a different color space) thus yielding a desired image
10 transformation. The user can also create his own custom transform definition in accordance with the invention. For example, the user interface allows the user to select a set of colors to be changed (e.g., from a palette of possible colors). The user can then
15 specify the desired changes to these colors, (e.g., a specific increase in the brightness). In response to these selections, the controller can then prepare a custom transform definition corresponding to the user's selections. Such custom transforms may be created by
20 modifying predetermined transforms or by generating entirely new transforms based on the user's input.

In accordance with the user's instructions, controller 20 can compose the selected transform definitions into a single composite transform
25 definition 28 as illustrated in Figures 3a, 3b for processing and displaying (or printing) the image from the input device without intermediate storage of the image. This selection and composition is performed with sufficient speed to allow the user to interact
30 with the system, altering his selections until the system displays a desired image.

Alternatively, as shown in Figure 4, controller 20 can process an image in accordance with an input transform definition and store the processed
35 image on storage device 17. Controller 20 can then compose the remaining selected transform definitions for processing the stored image at a later time.

Referring again to Figure 2, controller 20 provides the composite transform definition 28 to transform processor 18 which implements the transform in accordance with the composite transform definition

5 28. Transform processor 18 may be implemented in software on a general purpose computer, performing any transform specified in a given transform definition.

Referring to Figures 3(a), 3(b), the user, for example, may instruct image processor 14 to accept

10 an electronic image from scanner 10(a), perform selected transformations of the image, and display the transformed image on color monitor 16(a). In response, controller 20 first (and preferably automatically) selects input transform definition 12(a) for converting

15 the electronic image from scanner 10(a) into a "reference" color space used in performing subsequent transformations. More specifically, the defined input transform maps each point in the scanner's RGB space to a corresponding point in the perceptually based color

20 space, u' , v' , L^* (i.e., the "reference" space). In performing this translation, the input transform compensates for idiosyncrasies of the associated scanner 10(a). For example, in response to a given color, each scanner 10(a), 10(b) may generate different

25 coordinates in the RGB space. Accordingly, the input transform definitions 12(a), 12(b) (see Fig. 4) are calibrated to compensate for idiosyncrasies of each scanner such that each scanner generates the same point in the reference space $u'v'L^*$ when scanning a given

30 color.

After selecting input transform definition 12(a), controller 20 next selects transform definitions 24 and 26 corresponding to the color transformations requested by the user. Pleasing transform definition

35 24, for example, increases the luminance parameter L of certain blue colors in the image. Room light transform definition 26 adjusts all colors to compensate for the

ambient lighting conditions surrounding display 16(a).

Controller 20 finally selects (again automatically in the illustrated embodiment) output transform definition 15(a) to convert the thus
5 processed image from the reference color space to the RGB color space required by color monitor 16(a).

As shown in Figure 3(a), the selected transformations could be performed sequentially by processing the image with each transform definition in
10 the sequence. However, to expedite processing according to the invention, controller 20 dynamically composes the four transform definitions 12(a), 24, 26 and 15(a) into the composite transform definition 28. The electronic image from scanner 10(a) is then
15 processed in a single transformation step in accordance with composite transform definition 28 and thereafter is displayed on color monitor 16(a).

Referring to Figure 4, the user may alternatively request that the image from scanner
20 10(a), after calibration and with or without further "input" processing, be stored on storage device 17 before being further processed and displayed. Accordingly, controller 20 instructs transform processor 18 to process the electronic image according
25 to input transform definition 12(a) and store the resultant calibrated image in a storage device 17.

At a later time, the user instructs controller 20 to modify the image with a "pleasing" transform and display the modified image on monitor
30 16(a) as it would appear if printed on printer 16(b). Accordingly, controller 20 automatically selects three transform definitions 24, 30, and 15(a) required to implement the task. Pleasing transform definition 24 is designed to adjust the colors to make them more
35 pleasing (e.g., enhance certain blue colors). Gamut compression transform definition 30 is designed to modify the image so that it will appear the same on

-11-

monitor 16(a) as if printed on printer 16(b). For example, if the electronic image contains colors which the printer cannot display, the gamut compression transform maps these colors to similar colors within the printer's gamut. Finally, display calibration transform definition 15(a) is designed to convert the image into the RGB color space required by monitor 16(a), calibrating the image to compensate for the characteristics of the monitor.

10 Controller 20 composes the three selected transform definitions into a single composite transform definition 29. It then fetches the previously stored image from storage 17 and instructs processor 18 to process the image according to composite transform definition 29 for display on monitor 16(a).

 The user, satisfied with the displayed image, next instructs the controller to generate a hard copy of the image on printer 16(b). Accordingly, the controller selects the three transform definitions 24, 20 30, 15(b). The first two of the three definitions, pleasing transform definition 24 and gamut compression definition 30, are identical to the pleasing and gamut transform definitions used in generating the display image above. Printer calibration transform definition 25 15(b) however, is designed to convert the image into the CMYK color space, calibrating the image to compensate for characteristics of printer 16(b).

 The controller 20 composes the selected transform definitions into a composite transform definition 32. The stored image (in u'v'L* color space) is then processed in accordance with composite transform definition 32 for printing (in the CMYK color space) by printer 16(b).

 The contents of a transform definition and a means for implementing that definition are illustrated by the following description of a transform for mapping color values of an image in u'v'L* color space to

-12-

modified color values in the same $u'v'L^*$ color space. It will be apparent to those skilled in the art that the same techniques can be used to prepare and implement transform definitions for translating from one color space to another color space (e.g.,
5 converting color values in the $u'v'L^*$ color space to color values in the CMYK color space).

Referring to Figure 7(a), the coordinates u' , v' , L^* identify the color of a single pixel of the
10 image to be transformed, corresponding, for example, to point 42 in the reference color space. To process this color value, transform processor 18 maps point 42, in accordance with a selected transform definition, to a new point 44 having the coordinates u'_1 , v'_1 , L^*_1 . In
15 the same manner, the color coordinates u' , v' , L^* for each pixel of the input image are sequentially applied to transform processor 18 and are mapped to corresponding new points in the reference color space.

In the preferred embodiment of the invention,
20 each coordinate of a point in the reference color space is represented by an eight bit value. Accordingly, the three coordinates u' , v' , L^* can identify 224 points in the color space. Since storing a unique mapped transform output value for each of the 224 points
25 requires a prohibitively large memory, each transform definition (e.g., transform definitions 28, 29 and 32 of Figs. 3, 4) instead stores a set of sample values. For example, Figure 7(b) illustrates eight points
47(u_1 - u_8) in the uvL space for which sample values are
30 stored. The coordinates for which a sample value is stored define a point in the color space herein referred to as a "reference point."

A variety of techniques may be used for approximating the mapped transform output value of a
35 point 44 from one or more sample values. For example, according to a simple technique, transform processor 18 fetches from the transform definition the sample value

for the reference point 47(u_i) which is nearest the input point 42 and uses it as the point 44. (This is called a "nearest neighbor" approximation.) More sophisticated techniques call for fetching a plurality of sample values corresponding to the plurality of reference points 47(u_i) surrounding input point 42. The transform output value of point 44 is then estimated by interpolating between these fetched values.

For example, referring to Figure 7(b), to transform a given input color value 42, transform processor 18 fetches the stored sample values for each of the eight reference points 47 ($u_1 - u_8$) which surround point 42 in the color space. By interpolating between these eight sample values, transform processor 18 computes a color value which approximates the operation of the transform on the input color value 42. As will be explained in more detail below, some transform definitions require an additional mapping of this color value to determine the final transform output color value (i.e., the color value having the coordinates of point 44).

Referring to Figure 5, transform definition 36 is defined in part by the sample values stored in a collection of sample look-up tables 46, 48, 50. Table 46, for example, contains the sample value " u_s " for each reference point 47(u_i). In response to the u' , v' , L^* coordinates of point 42, sample table 46 locates the sample value " u_s " for each surrounding reference point 47($u_1 - u_8$) (see Fig. 7(b)). In addition, sample look-up table 46 determines the distance values $d_{uu'}$, $d_{uv'}$, d_{uL^*} which represent the position of point 42 relative to the corner reference point 47(u_1). Each of the eight sample values, $u_{s1} - u_{s8}$, is provided to a trilinear interpolator 52 along with the distance values $d_{uu'}$, $d_{uv'}$, d_{uL^*} . Trilinear interpolator 52 interpolates, as is well known in the field, between

-14-

the eight sample values based on the distances d_{uu} , d_{uv} , d_{uL} to derive the processed value u'_p . Output table 51, also from transform definition 36, completes the transform by mapping the processed value u'_p to the modified value u_1 , corresponding to point 44.

Sample table 46, trilinear interpolator 52, and output table 51 comprise one channel of the transform processor 18. Transform processor 18 contains a different channel for computing each parameter of the transform processor's output. Accordingly, a second channel (comprising sample table 48, interpolator 54, and output table 53) computes the value v'_1 and a third channel (comprising sample table 50, interpolator 56 and output table 55) computes the value L'_1 . As another example, if transform processor 18 is provided with transform definition 15(b) for converting from $u_1v'_1L'$ space to CMYK space (see Fig. 4), four channels are required, each channel for computing one of the four output variables C, M, Y, K. As another example, if transform processor 18 is provided with a transform definition for converting CMYK data to RGB data, three channels are required, each for computing one of the three output variables R, G, B. Each channel, in this example, preferably has a four dimensional grid table, one dimension for each input variable, C, M, Y, K. In this example, quadrilinear interpolation is preferably used to interpolate between sample values at selected reference points in the four dimensional CMYK space.

In populating the sample tables, it is critical to carefully choose the coordinates of the reference points at which sample values of the transform are precomputed. For example, a given image transform may vary linearly in a certain region of the color space. In the case where the transform definition uses linear interpolation to estimate between points, very few sample values may be

sufficient to describe the mapping of all colors in this region. However, in other regions of the color space, the image transform may vary in a non-linear manner. In such regions, a large number of sample values are required to accurately represent the transformation of all pixels (if linear interpolation of samples values is the chosen approximation technique). To provide such a non-uniform distribution of reference points throughout the reference space, each sample table employs a collection of one-dimensional input tables for applying a non-linear transformation to the input variable to enable a non-uniform distribution of reference points in the multidimensional transform definition.

Referring to Figures 6 and 7(b), for example, the sample values of sample tables 46, 48, 50 are stored in a grid tables 61, 63, 65 respectively. Upon receipt of the coordinates u'_0 , v'_0 , L_0^* of an input color value, input tables 60, 62, 64 of the first channel provide the coordinates $G_{uu'}$, $G_{uv'}$, G_{uL^*} (6 bits each) to select the entry in grid table 61 containing the sample value for the corner reference point 47(u_1). By selectively incrementing each coordinate $G_{uu'}$, $G_{uv'}$, G_{uL^*} , by one, grid table 61 provides trilinear interpolator 52 with the sample values of each of the other surrounding points 47(u_2 - u_8) (12 bit values).

Input tables 60, 62, 64 further provide the distance values $d_{uu'}$, $d_{uv'}$, d_{uL^*} (12 bits each) to trilinear interpolator 52. More specifically, input table 60 provides the distance $d_{uu'}$ representing the distance of input color value (e.g. point 42) from the point 47(u_1) as a fraction of the total distance in the u_1 axis direction between points 47(u_1) and 47(u_2) (see Fig. 7(b)). Similarly, input tables 62, 64 provide the distances $d_{uv'}$, d_{uL^*} representing the fractional distances of the input color value (point 42) from the corner reference points along the v' and L^* axes

-16-

respectively.

Trilinear interpolator 52 then computes the weighted average of the eight sample values based on the distances values $d_{uu'}$, $d_{uv'}$, d_{uL*} to provide a
 5 twelve bit processed value u_p . More specifically, trilinear interpolator evaluates the following functions.

$$u_p = L (B(u_1, u_2, u_3, u_4, d_u, d_L) \mid B(u_5, u_6, u_7, u_8, d_u, d_L), d_v)$$

where the operator "L" represents linear interpolation between two values according to the equation $L(a,b,I) = I (b) + (1-I) a$; and where the operator "B" represents bilinear interpolation between four values according to
 15 the equation:

$$B(c, d, e, f, I_{cd}, I_{ef}) = L(L(c, d, I_{cd}), L(e, f, I_{cd}), I_{ef}).$$

For some transforms, the 12 bit output of
 20 interpolator 52 is applied to a one-dimensional output table 51 for further transforming the twelve bit processed value from interpolator 52 to the modified value u_{11} . For example, assume that the modified value u_{11} is related to the input color value by the
 25 following function:

$$u_{11} = \text{SQRT} (\log u_o + \log v_o + \log L_o)$$

where SQRT refers to the square root of the value
 30 within the parenthesis. The input and grid tables may be loaded to compute the value: $\log u_o + \log v_o + \log L_o$. The output table is accordingly populated to effectively compute the square root of this value, thereby deriving the final modified value u_{11} . The
 35 result is that the grid tables contain linearly varying data.

As shown in Figure 6, the other two channels have the same architecture and operate in the same manner as described above to compute the coordinates $v_1' L_1^*$.

- 5 The composition of a plurality of transform definitions into a composite transform definition is now illustrated with the following description of the composition of three transform definitions 24, 30, 15(a) into a single composite transform definition 29.
- 10 Referring to Figure 9, a composite transform definition 29 has the same architecture as other transform definitions. For example, composite transform definition 29 includes three sets of input tables 141, 143, 145, each set for indexing into a cor-
15 responding composite grid table 140, 142, 144. Definition 29 typically also includes a set of output tables 151, 153, 155 for generating an output value in response to a processed value derived from
interpolating between several grid table entries.
- 20 The tables of the composite definition are designed such that, when implemented by a processor 118, they yield an input/ output relation which is equivalent to (through not necessarily identical too) the successive operation of the transform definitions
25 being composed. As will be explained more fully below, transform controller 20, successively implements each of the transform definitions 24, 30, 15(a) on a set of reference points in the color space and uses the results to determine the contents of the composite
30 transform definition.
- 35 To simulate this successive operation, the controller first determines a sequence in which to compose the transform definitions 24, 30, 15(a). It is essential that the color values produced by the output tables of
each transform definition in the sequence are in a format compatible with that expected by the input tables of the next transform definition in the

sequence. Obviously, the output and input must be in the same color space (e.g., both in the $u\ v\ L^*$ color space). For example, the RGB output produced when implementing output calibration definition 15(a) is clearly incompatible with the u' , v' , L^* values expected by the input tables of the gamut compression definition.

The output and inputs must also employ the same quantization for corresponding coordinates of the color space. For example, the output of the output tables of pleasing transform definition 24 and the input of the input tables of gamut compression transform definition 30 both employ the same number of bits for representing values of the coordinate u' . Further, both employ the same scale (i.e., the same range of possible u values). The number of bits in the output can of course be reduced to match a succeeding coarser quantization input. However, the input and output tables of many transform definitions employ eight bits to represent each color coordinate. Depending on the application, it may also be desirable to increase the resolution of each transform definition (e.g. :from eight bits to twelve bits) for purposes of composition. This may be achieved for example, by linearly interpolating between eight bit values.

Based on the above criteria, controller 20 chooses to implement the definitions in the following sequence, pleasing definition 24, gamut compression definition 30 and output calibration definition 15(a). For purposes of illustrating the sequential implementation of the transform definitions, Figure 8(a) depicts a set of processors 124, 130, and 115(a), each for implementing one of the transform definitions. However, as explained above, each transform definition may be implemented by a common processor which includes any combination of hardware and software. Accordingly, processors 124, 130 and 115(a) are also representative

-19-

of the sequential implementation of transform definition, 24, 30 and 15(a) by a single general processor.

Referring to Figures 8(b) and 8(c), in one
5 embodiment, the controller 20 selects the input tables 141, 143, 145 of the first transform in the sequence (i.e., pleasing transform) as the input tables of the composite transform definition 29. Similarly, it selects the output tables 151, 153, 155 of the last
10 transform in the sequence, (output calibration transform 115(a)) as the output tables of the composite. The contents of composite grid tables 140, 142, 144 are then computed as described below.

Figure 10 illustrates a technique for
15 computing the contents of the composite grid tables when the input tables 141, 143, 145 of Fig. 8(c) are identical. To compute a grid table entry, an addressing unit 106 generates a three dimensional grid table address $G_u' G_v' G_L^*$ and applies the address
20 directly to all three grid tables 170, 172, 174 of pleasing transform 124. In response, the grid tables 170, 172, 174 each provide a corresponding entry directly to output tables 178 of the pleasing transform. (Note that no interpolation is used. Thus,
25 the system is in effect simulating the processing of a sample color value which was precomputed for pleasing transform 124.) The resultant color value u_1', v_1', L_1^* produced by output tables 178 is processed by gamut compression transform 130 to yield a color value u_2'
30 $v_2' L_2^*$ which in turn is processed by output calibration transform 115(a).

The output calibration transform 115(a) generates a processed color value R_p, G_p, B_p which, when passed through the output tables 151, 153, 155,
35 yields the final processed value R G B Since a composite transform 29 includes the identical output tables 151, 153, 155, controller 20 stores the

processed color values R_p , G_p , B_p in the composite grid tables 140, 142, 144 at the same address G_u' , G_v' , G_L^* applied to grid tables 170, 172, 174. To populate the remaining locations in the composite grid tables, the address sequencer 106 repeats this process, stepping through the entire grid table address space until each location in the composite grid tables 140, 142, 144 is filled with a processed color value R_p , G_p , B_p .

Referring to Figures 11 and 12, a more general technique is now described for selecting input tables and populating grid tables for a composite transform 29. To understand this technique, it is useful to keep in mind that the input tables of a transform in effect define the locations in the color space for which sample values of the transform are precomputed and stored in the grid tables. Accordingly, before describing the general technique, the following first briefly describes this aspect of the input tables. Referring to Fig. 8(c), the processed value R_p of the first channel of the composite transform is a function of the input color value u_o' , v_o' , L_o^* (i.e., $R_p = f_R(u_o', v_o', L_o^*)$). Grid table 140 stores sample values of the function f_R taken at various points in the color space. As explained above, it is desirable to take many samples of the function in regions of the color space wherein the function is highly nonlinear. Fewer samples are needed in regions of the space where the function is linear since the values of the function in this region can accurately be estimated by linearly interpolating between neighboring samples.

Referring to Figures 5-7, recall that each channel in a transform definition has a set of three input tables. In response to the u -coordinates of a color value (e.g. point 42 in the color space) the input tables identify the grid table entry containing the sample value of the channel function (e.g. f_R)

taken at the neighboring reference point in the color space $47(u_1)$. The input tables also provide the distance values d_u , d_v , d_L indicating the distance of the color value from the neighboring reference point
5 $47(u_1)$. Thus, each entry in the input tables is determined by the location in the color space of the reference points at which the channel's transform function was sampled.

Because the other channels of the composite
10 transform may be entirely different functions of the input color value, i.e., $G_p = f_G(u_o', v_o', L_o^*)$ and $B_p = f_B(u_o', v_o', L_o^*)$, they may require samplings at different locations in the color space than f_R . If so, each channel must have a unique set of input tables
15 which reflect the desired sampling.

The reference points for a given channel of the composite should ideally be distributed throughout the color space to account for nonlinearities in the channel's transform definition. However, the linearity
20 of each channel of the composite is generally not known at the time of composition since the characteristics of the composite vary with the user's selection of transforms to be composed. Accordingly, rather than custom selecting a set of reference points for each
25 channel of the composite transform and generating corresponding sets of input tables, the controller typically uses the input tables of the first transform definition in the sequence as the input tables of the composite as described above (See Figures 8a-8c). The
30 reference points defined by these tables are then used as the reference points for purposes of computing entries i-n the composite grid tables. However, if another of the transforms in the sequence is highly nonlinear (e.g., the gamut compression transform), the
35 controller may choose the input tables of this definition for use in the composite transform definition. Otherwise, much of the information

contained in the samples of the highly nonlinear transform may be lost during composition. Finally, the controller may also prepare a new set of input tables which reflect a sampling unique to the composite.

5 Referring to Figures 11 and 12, the following describes a technique for generating reference points of the color space from a selected set of input tables, and for loading processed reference points into the appropriate locations of the composite grid tables.

10 This is accomplished by first preparing, for each channel of the composite, an identity transform definition from the selected set of input tables for that channel. An identity transform definition has the same architecture as other transform definitions, and

15 includes the selected input tables, a set of grid tables, and optionally a set of output tables. The grid tables (and output tables if any) are designed to perform the inverse of the operation of the input tables. Accordingly, the identity transform

20 definition, when implemented by a processor, generates the identical color value at the output as applied to the input.

Figure 11 depicts three identity transform definitions 112(a), 112(b), 112(c), each corresponding

25 to one channel of the composite. The input tables 141 of the identity transform definition 112(a) are identical to the input tables chosen for the u channel of the composite. The inverse grid tables 118(a), 120(a), 122(b) and the inverse output tables 119(a),

30 121(a), 123(a) (optional) are populated to collectively perform the inverse of the input tables 141. Accordingly, in response to a given input value u' , v' , L^* , the processor 110 (which implements these definitions) provides the same coordinates u' , v' , L^* .

35 As shown in figures 11(b) and 11(c), similar identity transforms are generated for the v' and L^* channels using the input tables 143 and 145 respectively. As

described below, the reference points corresponding to each channel's input tables can now be readily generated from the inverse grid tables and the inverse output tables of the channel's identity transform

5 112(a), 112(b), 112(c).

Referring to Figure 12(a), to generate a first reference point u_o' , v_o' , L_o^* of the u channel, an addressing unit 106(a) generates a grid table address G_{uu}' , G_{uy}' , G_{uL}^* , thereby selecting the first
10 entry in each of the inverse grid tables 118(a), 120(a), 122(a). The grid table entries are provided directly to the corresponding inverse output tables 119(a), 121(a), 123(a). The output tables respond by providing the sample color value (i.e., reference
15 point) u'_o , v'_o , L^*_o . This color value is sequentially processed by the three transforms 124, 130 and 115(a). The value R_p generated by the u channel of the output calibration processor 115(a) is stored in grid table 140 at the address G_{uu}' , G_{uv}' , G_{uL}^* .

20 To populate the grid table 140, addressing unit 106 simply steps through each combination of grid table addresses (G_{uu}' , G_{uv}' , G_{uL}^*). Accordingly, the grid table is loaded with sample values of an input/output relation of the u channel which (coupled
25 with the relation provided by the output tables 151) is equivalent to (though not necessarily identical to) the successive operation of the transform definitions being composed.

Referring to Figures 12(b) and 12(c), the
30 same technique described above is used to populate the grid tables 142, 144 of the remaining channels of the composite transform. More specifically, using the inverse grid tables and inverse output tables from the identity transforms 112(b), 112(c), address unit 106
35 walks through each grid table address space in the same manner described above to fully populate the new composite grid tables 142, 144.

It should be noted that independently populating each grid table 140, 142, 144 in the above described manner can expend large amounts of the controller's time. Accordingly, it is often desirable
5 to select input tables 141, 143, 145 which are identical across all channels. In this situation, a single identity transform is prepared for all three channels using the set of input tables common to all channels. As shown in Figure 13, all three grid tables
10 140, 142, 144 can then be loaded using the inverse grid tables and inverse output tables of the same identity transform 186.

Referring to Figure 14, in accordance with the invention, a transform definition 230 is
15 communicated to a processor for implementation (or to any other destination device such as a remote device across a communication network) using a standard protocol or format. According to this standard communication protocol, each transform definition
20 includes three sections, a header 232, an optional id string 234, and a table field 236 containing the input, output and grid tables.

The header 232, in the illustrated embodiment, is five hundred bytes long and begins with
25 a four byte identification field 238 for storing a number which identifies the format as that of a transform definition file. Identification field 238 is followed by a four byte version field 240 for storing a version number which distinguishes the current file
30 from earlier versions. A four byte Idstr-length field 242 follows the version field 240 and is used to specify the length of the optional Id string 234.

Next, a four byte order field 244 specifies the default approximation method to be used when
35 evaluating the transform definition (e.g., the nearest neighbor technique, linear interpolation, or cubic interpolation). An I-code field 246 contains a four

byte code word for each common input table of the transform definition (i.e., an input table which is used by more than one of the transform definition's channels). The code word 246 contains two sub-fields, a code number field 248 and a code data field 250. The code number field 248 identifies the type of the associated input table. For example, in this illustrated embodiment, a 00 Hex in the code number field indicates that the input table is null and is therefore not defined in the file. The code number 01 Hex indicates that the input table is also used by other transform definitions and therefore is contained in a common list of shared input tables 270 stored in table field 236. An address, identifying this common list and the specific entry containing the shared input table, is specified in the code data field 250. The code number 02 Hex indicates that the input table is a simple, linear ramp function which maps the input values into a grid size specified in the code-data field 250. Accordingly, the input table is not stored in the file since it can be readily constructed when needed. Finally, the code number 04 Hex indicates that the input table is unique and therefore is stored in field 236 of file 230.

An array 252 of channel headers follows the common input table codes 246. Array 252 includes a 56 byte header 254 for each output channel of the transform definition. Each header 254 begins with an array of two byte "size" fields 256. Each entry of the array specifies the size of a corresponding channel's grid table in one of the grid tables' dimensions. For example, an entry of 00 Hex or 01 Hex in one element of the array indicates that the grid table does not use the dimension corresponding to the entry.

Size field 256 is followed by an I-code field 258 which contains a four byte code for each of the channel's private input tables (i.e., input tables not

used by other channels of the transform definition). Each four byte code identifies the type of input table using the same codes used in I-code field 246. In the same manner, o-code field 260 and g-code field 262
5 identify the type of output table and grid table associated with the channel (e.g., null, linear ramp, or unique).

Finally, an extension field 264 follows the channel headers 252, to provide a mechanism for
10 expanding the header information while allowing forward and backward compatibility.

The optional Id string field 234 may be used for storing ASCII text for identifying a particular transform or describing other application specific
15 attributes that the transform may have. In this case, the Idstr-length field 242 of header 232 is filled with a number representing the length of the desired optional Id string field 234.

The table field 236 contains the data of each
20 of the input, output and grid tables stored in the file. The input, grid and output tables which are shared by more than one channel (the shared tables 270) are listed first. The shared tables 270 are then followed by the private tables unique to each channel.
25 For example, the table depicted in Figure 12 has three sets of private tables 272, 274, 276, each set containing the private tables corresponding to one of the three channels, u', v', and L*.

Within a given set of private tables, the
30 input tables 278 are listed first, followed by the output tables 280 and the grid tables 282.

Each input table contains a four byte type field 286 containing a number identifying the format of the input table. The type field is followed by a four
35 byte reference field 288 and a four byte Id field 290. These fields are reserved for use when the definition is loaded into physical memory. A size field 292

specifies the size of the grid table dimension into which the input table indexes. For example, the size field of input table 60 (Figure 6) indicates that the input table indexes the variable u' into a five bit grid dimension GU. Finally, the above header information (286-292) is followed by the data field 294 containing the two hundred and fifty-seven entries of the input table. In the present embodiment, each entry is thirty-two bits wide, the high order bits containing a grid table address (e.g., GU) the lower sixteen bits containing a distance values (e.g, du).

Each output table contains a type field 296, a reference field 298 and an Id field 300 containing the same type of header information as fields 286, 288 and 290 of the input table. These header fields are followed by four thousand and ninety-six (4096) output table entries 302. Each entry is sixteen bits wide. However, in the present embodiment, only the lower twelve bits are used.

Finally, each grid table contains header fields 310, 312, 314 containing the same type of information as type field 286, reference field 288, and id field 290 described above with respect to the input tables. The header of the grid tables further include a table field 316, a table size field 318 and a size field 320.

Table field 316 is reserved for future use. The table size field 318 specifies the number of bytes in the grid table (two bytes per entry in the illustrated embodiment). This field is followed by the table size field 320 which contains an array of two byte entries, each entry specifying the size of the grid table in each of its dimensions. This size information should match the size information in each of the size fields 292 of each of the input tables which index the grid table.

Finally, the above header information is

followed by the data field 322 containing the sixteen bit grid table entries. In the present embodiment, however, only twelve of the bits **are** used.

5 Additions, subtractions, deletions and other modifications of the preferred particular embodiments of the invention will be apparent to those practiced in the art and are within the scope of the following claims.

What is claimed is:

1. An image processing system for generating an array of modified pixel values in response to an array of input pixel values, comprising:
 - 5 a user interface means for receiving a user's selection of at least one image transformation to be performed on said array of input pixel values,
 - a storage means for storing a plurality of transform definitions, each transform definition
 - 10 comprising sample values representing an input/output relation of an image transformation, and
 - a transform controller means for selecting a plurality of transform definitions in response to said user's selection of at least one image transformation,
 - 15 and generating therefrom a composite transform definition comprising sample values of an input/output relation of a composite image transformation, said composite image transformation being equivalent to said at least one image transformation selected by said
 - 20 user.
2. The image processing system of claim 1 wherein said plurality of transform definitions stored by said storage means comprise a plurality of predetermined transform definitions.
- 25 3. The image processing system of claim 1 further comprising a means for preparing a custom transform definition in accordance with a users instructions and wherein said plurality of transform definitions stored by said storage means includes at
- 30 least one said custom transform definition.
4. The image processing system of claim 2 wherein said user interface means is further for receiving a user's instructions for modifying a selected predetermined transform definition, said image
- 35 processing system further comprising a transform definition modification means for altering said selected predetermined transform definition in

accordance with said user's instructions.

5 5. The image processing system of claim 1 wherein said transform controller means operates in essentially real time, implementing said user's
5 selections sufficiently quickly to allow said user to interact with said image processing system until a desired array of modified pixel values are obtained.

10 6. The image processing system of claim 1 further comprising an approximation means for
10 calculating a processed pixel value, said approximation means comprising:

15 addressing means for selecting at least one sample value from said selected transform definition, said at least one selected sample corresponding to an
15 input pixel value to be modified, and

 approximation means for determining said processed pixel value based on said at least one selected sample value.

20 7. The image processing system of claim 6 wherein said at least one selected sample value is a nearest neighbor of said input pixel value.

 8. The image processing system of claim 6 wherein said approximation means interpolates between a plurality of selected sample values to determine said
25 processed pixel value.

 9. The image processing system of claim 6 wherein each transform definition comprises;

 at least one multidimensional grid table containing said sample values, and

30 at least one input table containing for each input pixel value, the grid table address of a corresponding entry of said grid table.

 10. The image processing system of claim 9 wherein said at least one input table additionally
35 contains, for each input pixel value, at least one distance value.

11. The image processing system of claim 10 wherein each transform definition further comprises at least one output table specifying for each said processed pixel value, a corresponding modified pixel value.

12. The image processing system of claim 11 wherein said transform controller means comprises:
sequencing means for ordering said selected transform definitions in a specified sequence such that the modified pixel values generated by each transform are in the same color space and quantization required by the next transform in said sequence.

13. The image processing system of claim 12 wherein said transform controller means generates said composite transform definition by:

a) selecting said at least one input table, and
b) selecting said at least one output table of a last transform definition in said sequence for use as at least one output table of said composite transform definition.

14. The image processing system of claim 13 wherein said transform controller means derives said sample values of said multidimensional composite grid tables from sample values of said plurality of transform definitions.

15. A method for generating an array of modified pixel values in response to an array of input pixel values, comprising the steps of:

receiving a user's selection of at least one image transformation to be performed on said array of input pixel values,

storing a plurality of transform definitions, each transform definition comprising sample values representing an input/output relation of an image transformation,

selecting a plurality of said stored

-32-

transform definitions, and

generating from said selected transform definitions, a composite transform definition comprising sample values of an input/output relation of a composite image transformation, said composite image transformation being equivalent to said at least one image transformation selected by said user.

16. The method of claim 15 wherein said plurality of stored transform definitions comprise a plurality of predetermined transform definitions, and wherein said method further comprises the steps of: receiving a user's instructions for modifying a selected predetermined transform definition, and altering said selected predetermined transform definition in accordance with said user's instructions to form a custom transform definition.

17. The method of claim 15 further comprising the steps of selecting at least one sample value from said composite transform definition, said at least one selected sample corresponding to an input pixel value to be modified, and

determining a processed pixel value based on said at least one selected sample value.

18. The method system of claim 17 wherein said at least one selected sample value is a nearest neighbor of said input pixel value.

19. The method of claim 18 wherein determining said processed pixel value comprises interpolating between a plurality of selected sample values.

20. The method of claim 19 wherein generating said composite transform definition comprises the steps of:

preparing at least one multidimensional grid table containing said sample values of said composite transform definition, and

preparing at least one input table containing

-33-

for each input pixel value, a grid table address of a corresponding entry of said grid table.

21. The method of claim 20 wherein said at least one input table additionally contains, for each
5 input pixel value, at least one distance value.

22. The method of claim 21 wherein generating said composite transform definition further comprises the step of:

preparing at least one output table
10 specifying for each said processed pixel value, a corresponding modified pixel value.

23. The method of claim 22 wherein generating said composite transform definition further comprises:

15 ordering said selected transform definitions in a specified sequence such that the pixel values generated by each transform are in the same color space and quantization required by the next transform in said sequence.

20 24. The method of claim 23 wherein generating said composite transform definition further comprises: selecting a plurality of representative pixel values, and sequentially processing each representative pixel value according to said specified
25 sequence of transform definitions.

25. The method of claim 24 wherein sequentially processing each representative pixel value comprises:

a) selecting at least two sample values of
30 a first image transform definition in said sequence,

b) interpolating between said at least two sample values to derive an intermediate sample value,

c) selecting at least two sample values of a second image transform definition based on the value
35 of said intermediate sample value, and

d) interpolating between said at least two sample values of said second image transform definition

to derive a second intermediate sample value, and

e) repeating steps c and d for each image transform definition in said sequence.

26. A method for combining a plurality of
5 image transform definitions to form a composite transform definition, each predetermined image transform definition containing sample values representing an input/output relation of an image transformation, said composite transform definition
10 containing sample values representing an input/output relation of a composite image transformation, said composite image transformation being equivalent to the successive operation of said plurality of image transformations, said method comprising the steps of:
- 15 a) selecting at least two sample values of a first image transform definition,
b) interpolating between said at least two sample values to derive an intermediate sample value,
c) selecting at least two sample values of
20 a second image transform definition based on the value of said intermediate sample value, and
d) interpolating between said at least two sample values of said second image transform definition to derive a sample value of said composite transform
25 definition.

27. A method for communicating a transform definition to a destination device, said transform definition comprising sample values representing an input/output relation of an image transformation, said
30 method comprising,
providing said destination device with identification data identifying the communication as that of a transform definition,
providing said destination device with
35 version data for distinguishing the transform definition from other versions of the transform definition,

-35-

- providing the destination device with size data specifying for each channel's grid table, the size of each of the grid table's dimensions,
- providing the destination device with input
- 5 table data of any input table which is shared by a plurality of channels of said transform definition,
- providing the destination device with output table data of any output table which is shared by a plurality of channels of said transform definition,
- 10 providing the destination device with grid table data of any grid table which is shared by a plurality of channels of said transform definition,
- providing said destination device the input table data of any private input tables,
- 15 providing said destination device the output table data of any private output tables, and
- providing said destination device the grid table data of any private grid tables.
28. The method of claim 27 further
- 20 comprising the step of: providing the destination device with input code data identifying the type of private input tables for each channel of the transform definition,
- providing the destination device with output
- 25 code data identifying the type of private output tables for each channel of the transform definition, and
- providing the destination device with grid code data identifying the type of private grid table for each channel of the transform definition.
- 30 29. The method of claim 27 wherein providing input table data comprises,
- providing type information identifying the type of input table,
- providing size data specifying the size of
- 35 the grid table dimension into which the input table indexes, and
- providing a plurality of data entries of said

input table, each data entry specifying an index to a grid table dimension.

30. The method of claim 27 wherein providing output table data comprises,

- 5 providing type information identifying the type of output table,
 providing a plurality of data entries of said output table.

10 31. The method of claim 25 wherein providing grid table data comprises,

- providing type information identifying the type of grid table,
 providing size data specifying the size of each grid table dimension, and
15 providing a plurality of data entries of said grid table, each data entry specifying at least one said sample value.

20 32. The method of claim 27 further comprising the step of: providing the destination device with a code word data identifying each common input table used by a plurality of the transform definition's channels.

25 33. The method of claim 32 wherein providing a code data word identifying a common input table, comprises:

 providing a code number for each common input table, specifying the type of the common input table.

30 34. The method of claim 33 wherein said code number specifies one type from a group of types comprising a null table, a linear ramp table, and a unique table.

35 35. The method of claim 27 further comprising the step of: providing said destination device with order information specifying the default approximation method to be used when evaluating the transform definition.

36. The method of claim 27 further comprising the steps of, providing the destination device with length data specifying the length of optional identification data, and

5 providing the destination with any optional identification data.

37. A method for communicating a transform definition to a destination device, said transform definition comprising sample values representing an
10 input/output relation of an image transformation, said method comprising,

providing said destination device with identification data identifying the communication as that of a transform definition,

15 providing said destination device with version data for distinguishing the transform definition from other versions of the transform definition,

20 providing the destination device with length data specifying the length of optional identification data,

providing said destination device with order information specifying the default approximation method to be used when evaluating the transform definition,

25 providing the destination device with code word data identifying each input table used by a plurality of the transform definition's channels,

30 providing the destination device with size data specifying for each channel's grid table, the size of each of the grid table's dimensions,

providing the destination device with input code data identifying the type of private input tables for each channel of the transform definition,

35 providing the destination device with output code data identifying the type of private output tables for each channel of the transform definition,

providing the destination device with grid

-38-

- code data identifying the type of private grid table
for each channel of the transform definition,
providing the destination with any optional
identification data,
- 5 providing the destination device with the
input table data of any input table which is shared by
a plurality of channels of said transform definition,
and
- 10 providing the destination device with the
output table data of any output table which is shared
by a plurality of channels of said transform
definition, and
- 15 providing the destination device with the
grid table data of any grid table which is shared by a
plurality of channels of said transform definition,
providing said destination device the input
table data of any private input tables,
providing said destination device the output
table data of any private output tables, and
- 20 providing said destination device the grid
table data of any private grid tables.
38. A method for storing a transform
definition in a storage file, said transform definition
comprising sample values representing an input/output
25 relation of an image transformation, said method
comprising,
- storing in an identification field,
identification data identifying the communication as
that of a transform definition,
- 30 storing in a version field, version data for
distinguishing the transform definition from other
versions of the transform definition,
- storing in a size field, size data specifying
for each channel's grid table, the size of each of the
35 grid table's dimension,
- storing in a shared input data field, input
table data of any input table which is shared by a

plurality of channels of said transform definition,
storing in a shared output data field, output
table data of any output table which is shared by a
plurality of channels of said transform definition,
5 storing in a shared grid data field, grid
table data of any grid table which is shared by a
plurality of channels of said transform definition,
storing in a private input data field, input
table data of any private input tables,
10 storing in a private output data field,
output table data of any private output tables, and
storing in a private grid table field, grid
table data of any private grid tables.

39. The method of claim 38 further
15 comprising the step of: storing in an input code field,
data identifying the type of private input tables for
each channel of the transform definition,
storing in an output code field, data
identifying the type of private output tables for each
20 channel of the transform definition, and
storing in a grid-code field, data
identifying the type of private grid table for each
channel of the transform definition.

40. The method of claim 38 wherein each said
25 private input data field and each said shared input
data field comprises,
a type sub-field, containing data identifying
the type of input table,
a size sub-field containing data specifying
30 the size of the grid table dimension into which the
input table indexes, and
a data sub-field, containing a plurality of
data entries of said input table, each data entry
specifying an index to a grid table dimension.

35 41. The method of claim 38 wherein each said
private output data field and each said shared output
data field comprises,

-40-

a type field containing data identifying the type of output table,

a data field, containing a plurality of data entries of said output table.

5 42. The method of claim 38 wherein each said private grid data field and each said shared grid data field comprises,

a type sub-field containing data identifying the type of grid table,

10 a size sub-field containing data specifying the size of each grid table dimension, and

a data sub-field containing a plurality of data entries of said grid table, each data entry specifying at least one said sample value.

15 43. The method of claim 38 further comprising the step of:

storing in a code word field, data identifying each common input table used by a plurality of the transform definition's channels.

20 44. The method of claim 43 wherein said code word field comprises:

a code number sub-field for each common input table, containing type data specifying the type of the common input table.

25 45. The method of claim 44 wherein said type data specifies one type from a group of types comprising a null type table, a linear ramp type table, and a unique type table.

30 46. The method of claim 45 further comprising the step of: storing in an order field, data specifying the default approximation method to be used when evaluating the transform definition.

47. The method of claim 46 further comprising the steps of,

35 storing in a lengthy field, data specifying the length of optional identification data, and
storing in an optional identification field,

-41-

any optional identification data,

48. A method for storing a transform definition in a storage file, said transform definition comprising sample values representing an input/output
5 relation of an image transformation, said method comprising,

storing in an identification field, data identifying the communication as that of a transform definition,

10 storing in a version field, data for distinguishing the transform definition from other versions of the transform definition,

storing in a lengthy field, data specifying the length of optional identification data,

15 storing in an order field, data specifying the default approximation method to be used when evaluating the transform definition,

storing in a code word field, data identifying each input table used by a plurality of the
20 transform definition's channels,

storing in a size field, data specifying for each channel's grid table, the size of each of the grid table's dimensions,

storing in an input code field, data
25 identifying the type of private input tables for each channel of the transform definition,

storing in an output code field, data identifying the type of private output tables for each channel of the transform definition,

30 storing in a grid code field, data identifying the type of private grid table for each channel of the transform definition,

storing in an option field, any optional identification data,

35 storing in a shared input table field, data of any input table which is shared by a plurality of channels of said transform definition, and storing in a

shared output table field, data of any output table which is shared by a plurality of channels of said transform definition, and

5 storing in a shared grid table field, data of any grid table which is shared by a plurality of channels of said transform definition,

storing in a private input table field, data of any private input tables,

10 storing in a private output table field, data of any private output tables, and

storing in a private grid table field, data of any private grid tables.

49. A storage device for storing a transform definition in a storage file, said transform definition
15 comprising sample values representing an input/output relation of an image transformation, said storage device comprising,

20 means for storing in an identification field, identification data identifying the communication as that of a transform definition,

means for storing in a version field, version data for distinguishing the transform definition from other versions of the transform definition,

25 means for storing in a size field, size data specifying for each channel's grid table, the size of each of the grid table's dimensions,

30 means for storing in a shared input data field, input table data of any input table which is shared by a plurality of channels of said transform definition,

means for storing in a shared output data field, output table data of any output table which is shared by a plurality of channels of said transform definition,

35 means for storing in a shared grid data field, grid table data of any grid table which is shared by a plurality of channels of said transform

definition,

means for storing in a private input data field, input table data of any private input tables,

5 means for storing in a private output data field, output table data of any private output tables, and

means for storing in a private grid table field, grid table data of any private grid tables.

10 50. The storage device of claim 49 further comprising: means for storing in an input code field, data identifying the type of private input tables for each channel of the transform definition,

15 means for storing in an output code field, data identifying the type of private output tables for each channel of the transform definition, and

means for storing in a grid code field, data identifying the type of private grid table for each channel of the transform definition.

20 51. The storage device of claim 49 wherein each said private input data field and each said shared input data field comprises,

a type sub-field, containing data identifying the type of input table,

25 a size sub-field containing data specifying the size of the grid table dimension into which the input table indexes, and

a data sub-field, containing a plurality of data entries of said input table, each data entry specifying an index to a grid table dimension.

30 52. The storage device of claim 49 wherein each said private output data field and each said shared output data field comprises,

a type field containing data identifying the type of

35 output table,

a data field, containing a plurality of data entries of said output table.

53. The storage device of claim 49 wherein each said private grid data field and each said shared grid data field comprises,

5 a type sub-field containing data identifying the type of grid table,

a size sub-field containing data specifying the size of each grid table dimension, and

10 a data sub-field containing a plurality of data entries of said grid table, each data entry specifying at least one said sample value.

54. The storage device of claim 49 further comprising:

15 means for storing in a code word field, data identifying each common input table used by a plurality of the transform definition's channels.

55. The storage device of claim 54 wherein said code word field comprises:

20 a code number sub-field for each common input table, containing type data specifying the type of the common input table.

56. The storage device of claim 55 wherein said type data specifies one type from a group of types comprising a null type table, a linear ramp type table, 25 and a unique type table.

57. The storage device of claim 56 further comprising:

30 means for storing in an order field, data specifying the default approximation method to be used when evaluating the transform definition.

58. The storage device of claim 57 further comprising:

35 means for storing in a lengthy field, data specifying the length of optional identification data, and

means for storing in an optional identification field,

any optional identification data.

59. A storage device for storing a transform definition in a storage file, said transform definition comprising sample values representing an input/output relation of an image transformation, said storage device comprising:

means for storing in an identification field, data identifying the communication as that of a transform definition,

10 means for storing in a version field, data for distinguishing the transform definition from other versions of the transform definition,

means for storing in a lengthy field, data specifying the length of optional identification data,

15 means for storing in an order field, data specifying the default approximation method to be used when evaluating the transform definition,

means for storing in a code word field, data identifying each input table used by a plurality of the transform definition's channels,

20 means for storing in a size field, data specifying for each channel's grid table, the size of each of the grid table's dimensions,

means for storing in an input code field, data identifying the type of private input tables for each channel of the transform definition,

means for storing in an output code field, data identifying the type of private output tables for each channel of the transform definition,

30 means for storing in a grid code field, data identifying the type of private grid table for each channel of the transform definition,

means for storing in an option field, any optional identification data,

35 means for storing in a shared input table field, data of any input table which is shared by a plurality of channels of said transform definition, and

- means for storing in a shared output table field, data of any output table which is shared by a plurality of channels of said transform definition, and
- means for storing in a shared grid table
- 5 field, data of any grid table which is shared by a plurality of channels of said transform definition,
- means for storing in a private input table field, data of any private input tables,
- means for storing in a private output table
- 10 field, data of any private output tables, and
- means for storing in a private grid table field, data of any private grid tables.

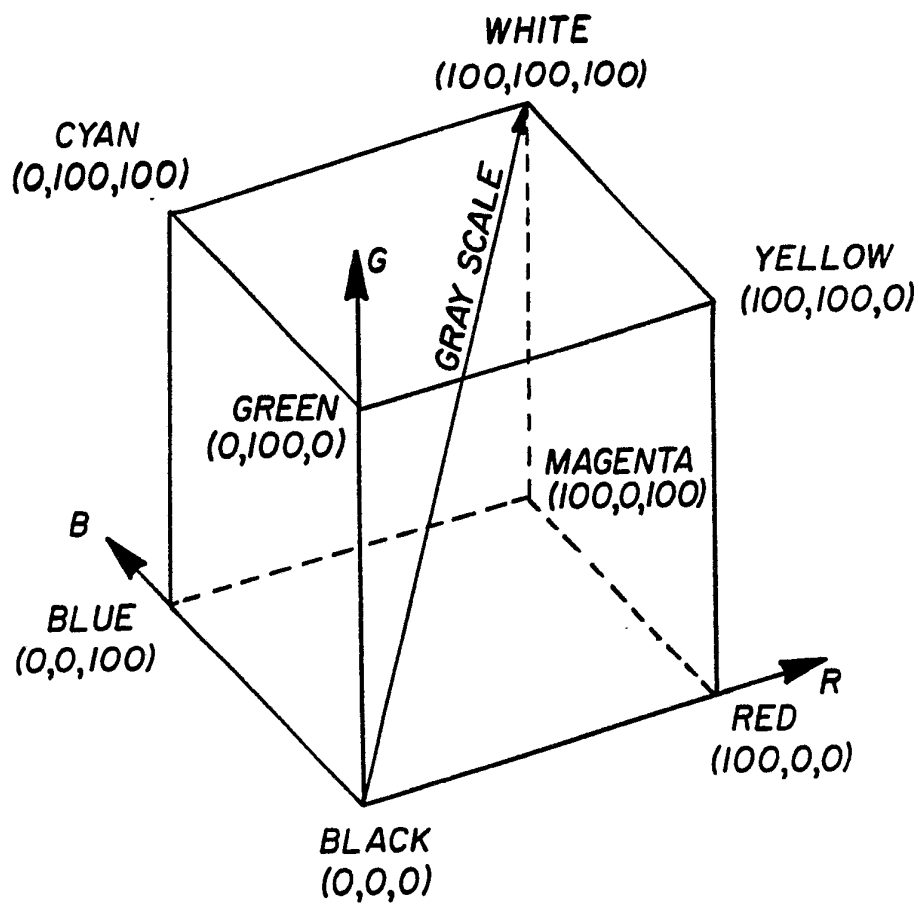


FIG. 1

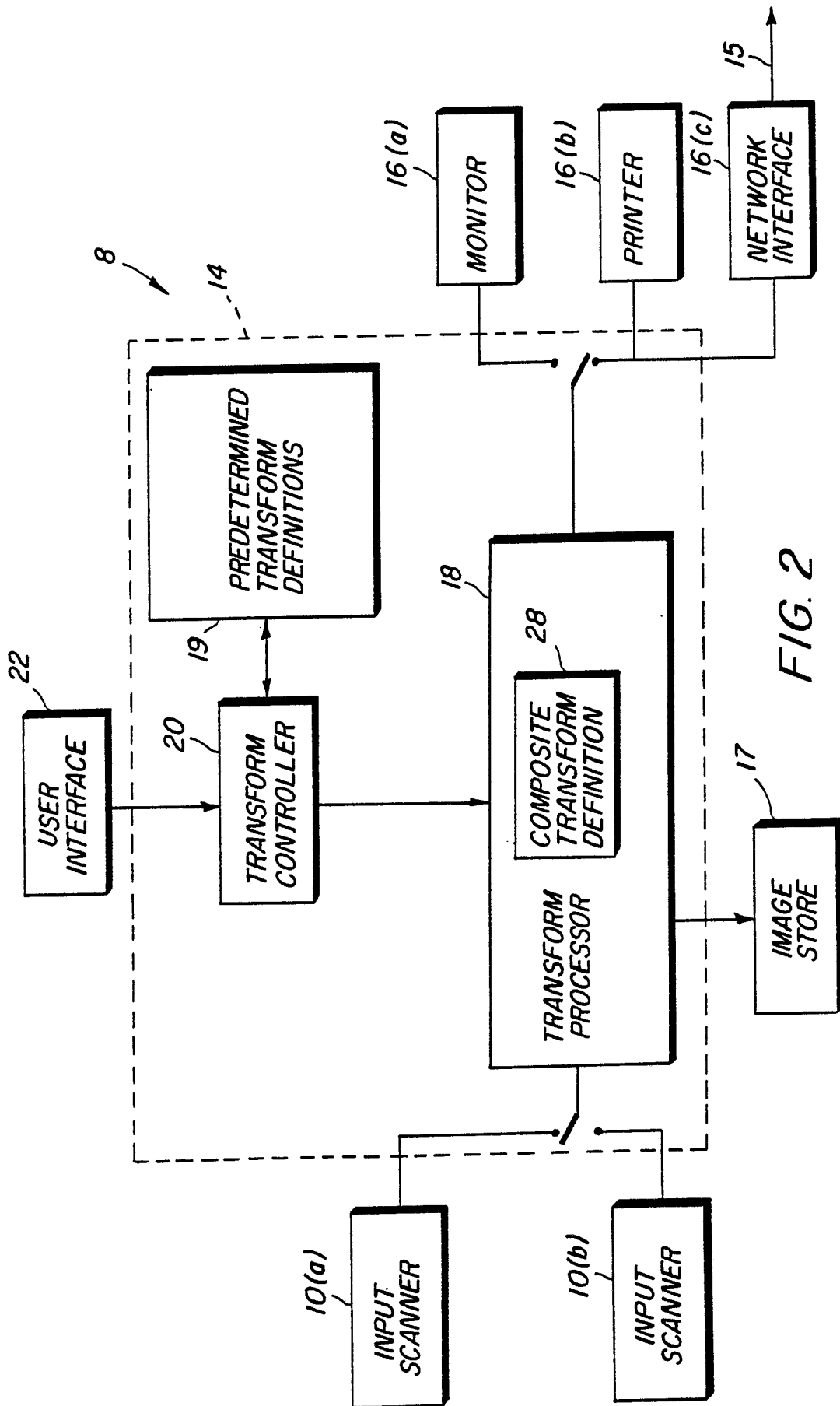


FIG. 2

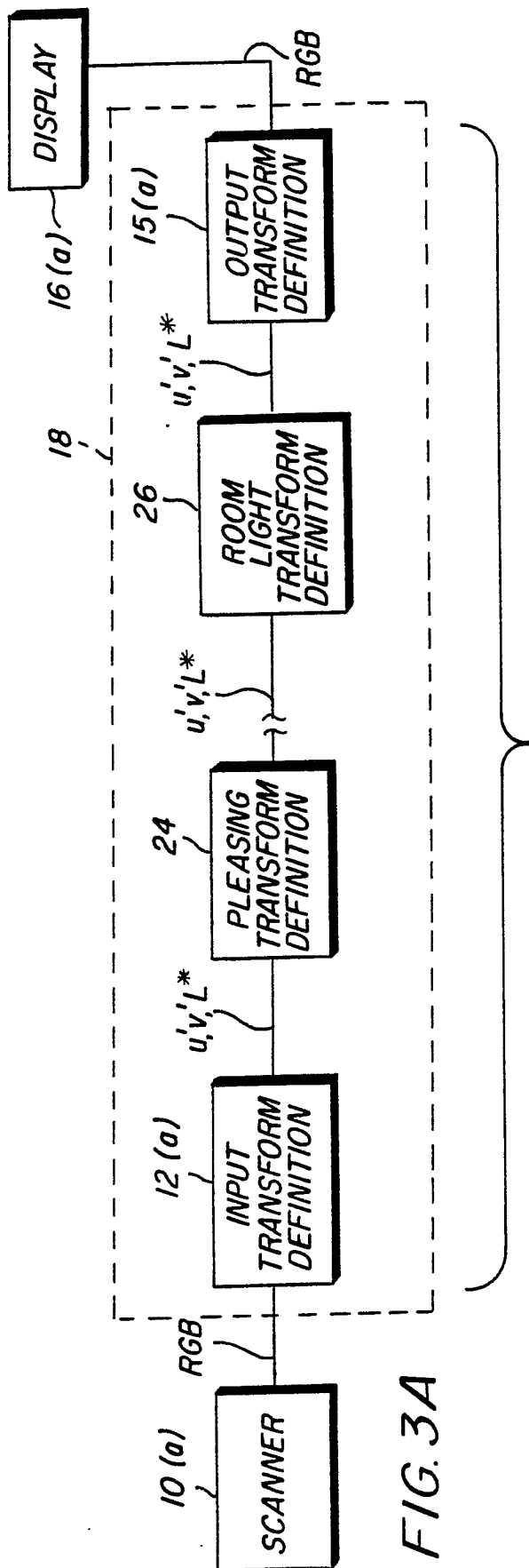


FIG. 3A

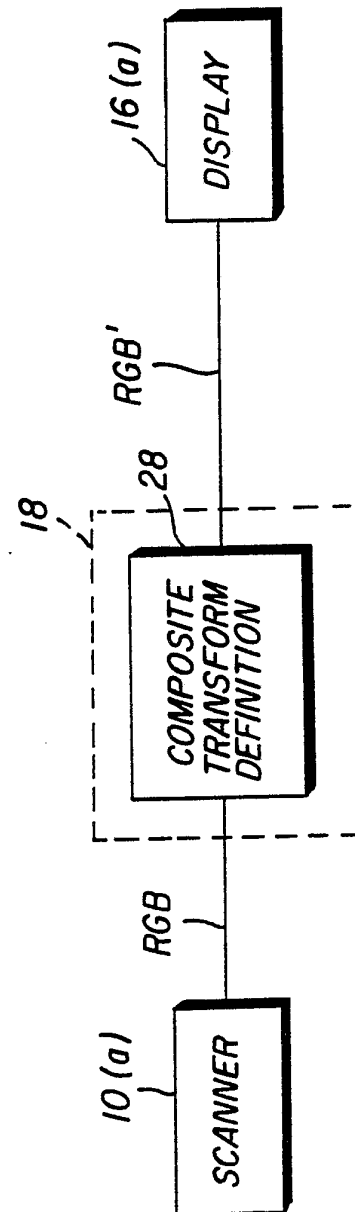


FIG. 3B

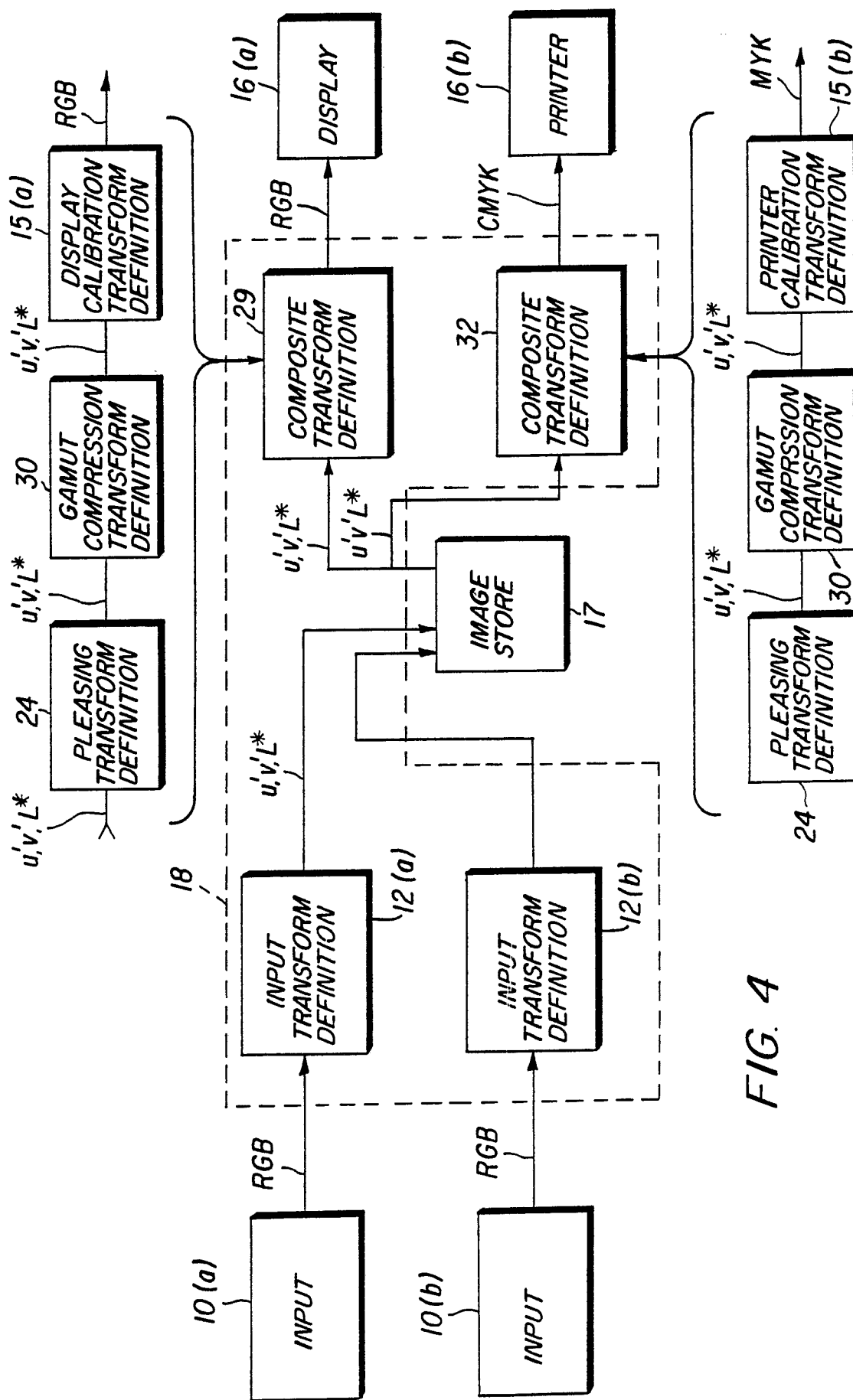


FIG. 4

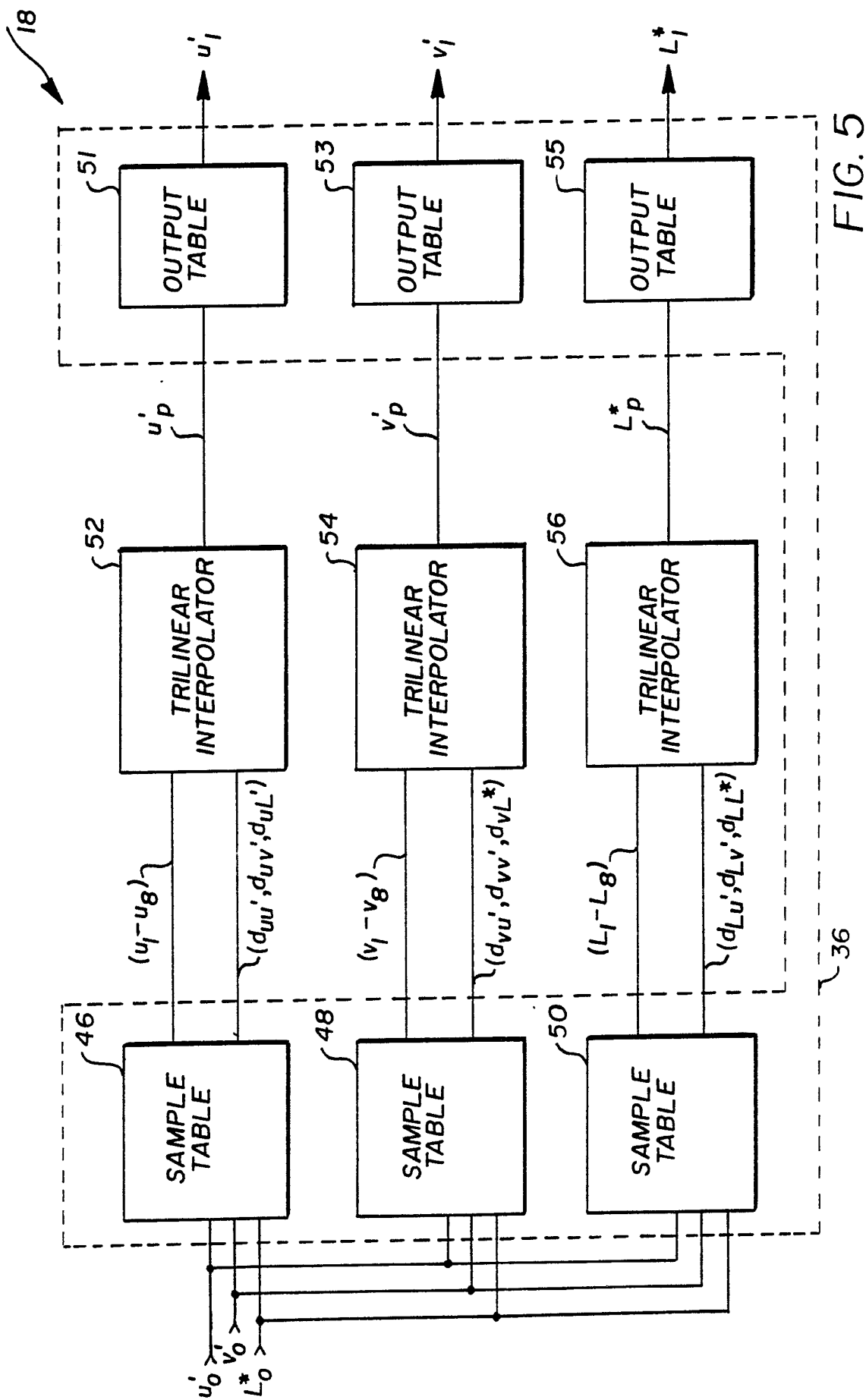


FIG. 5

6/17

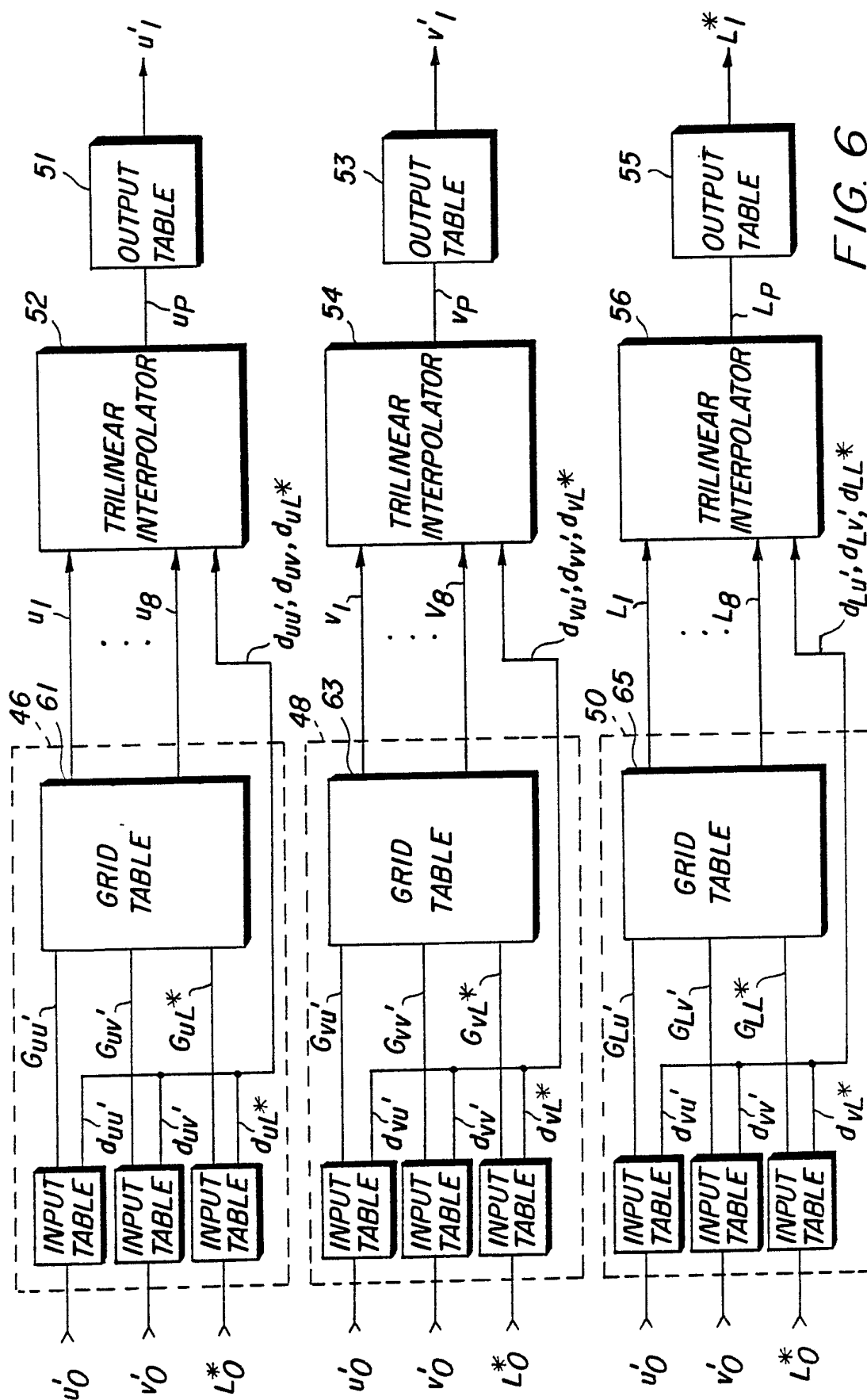


FIG. 6

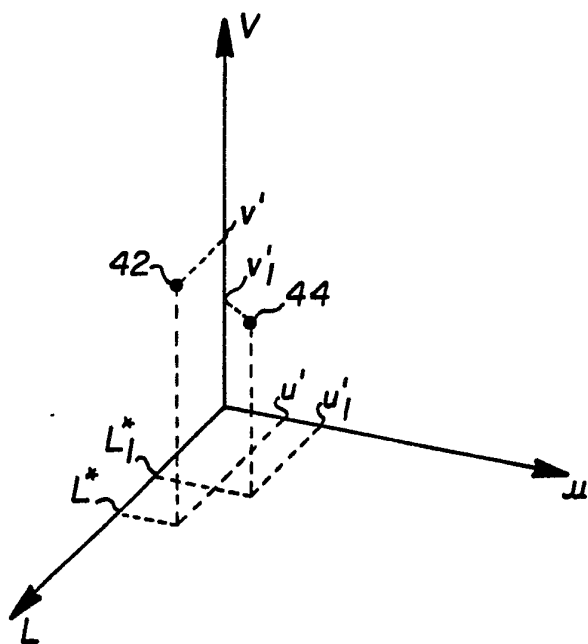


FIG. 7A

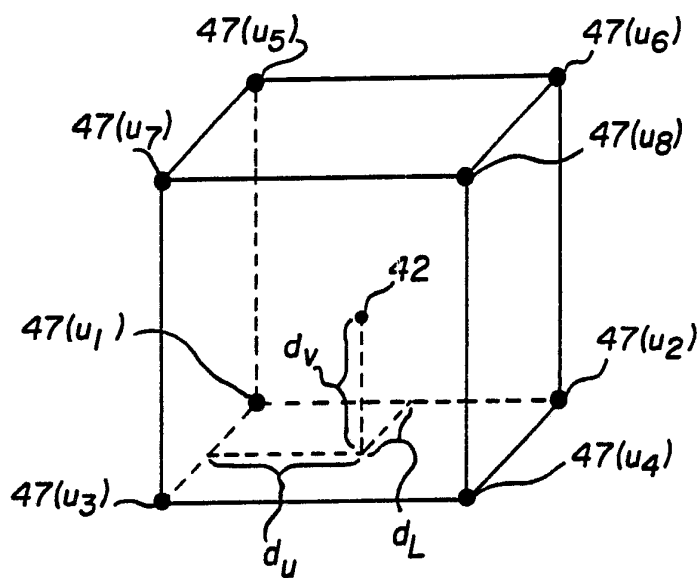
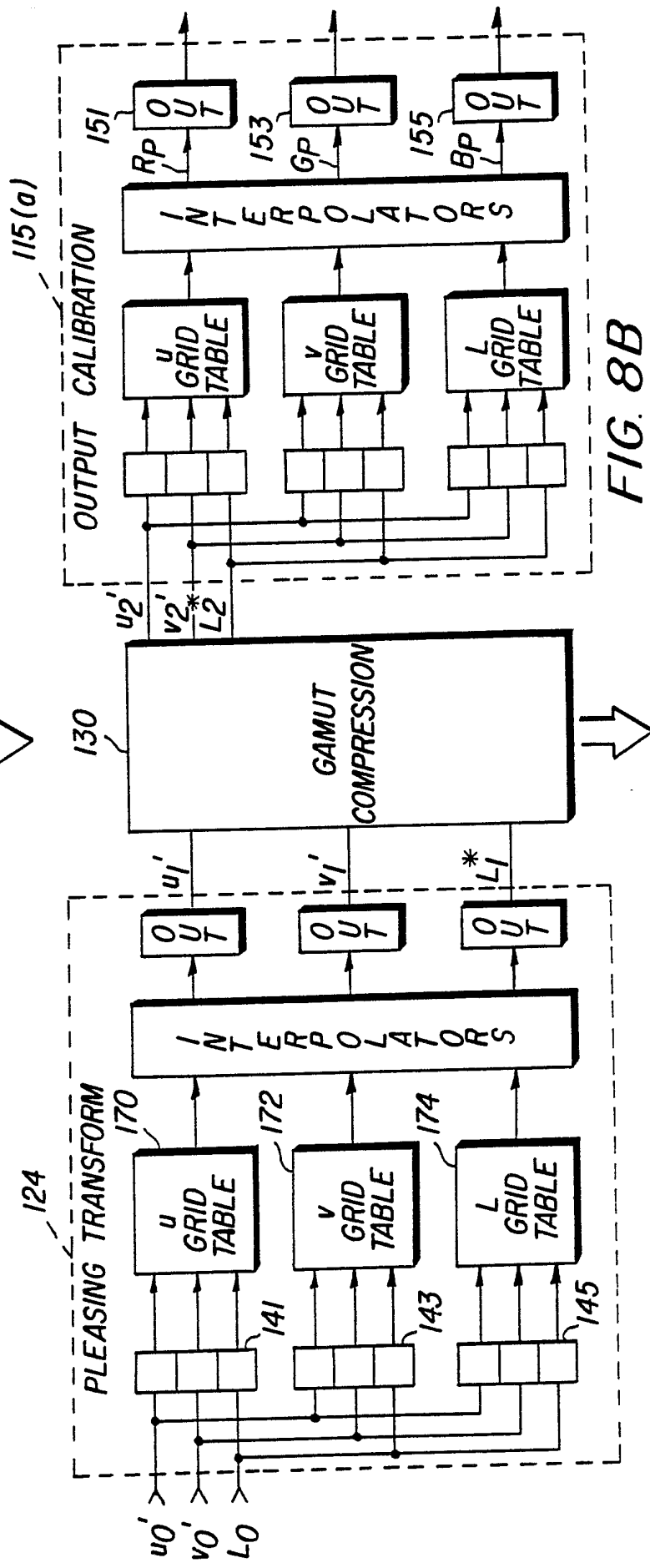
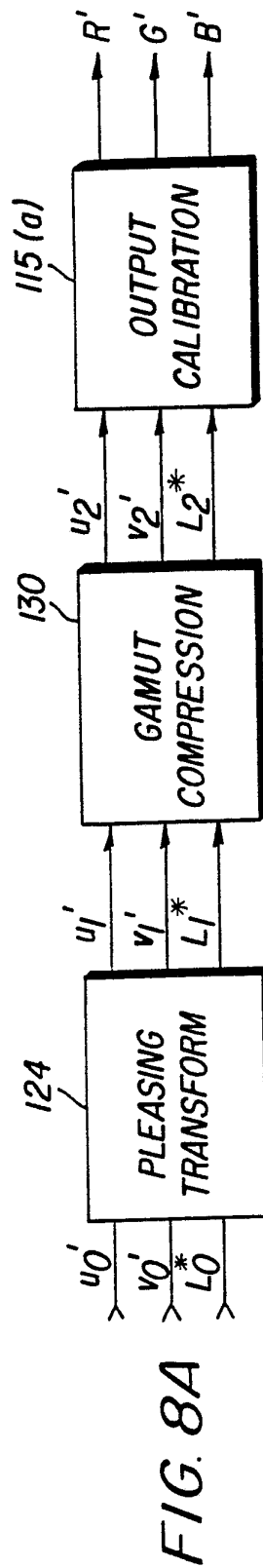


FIG. 7B



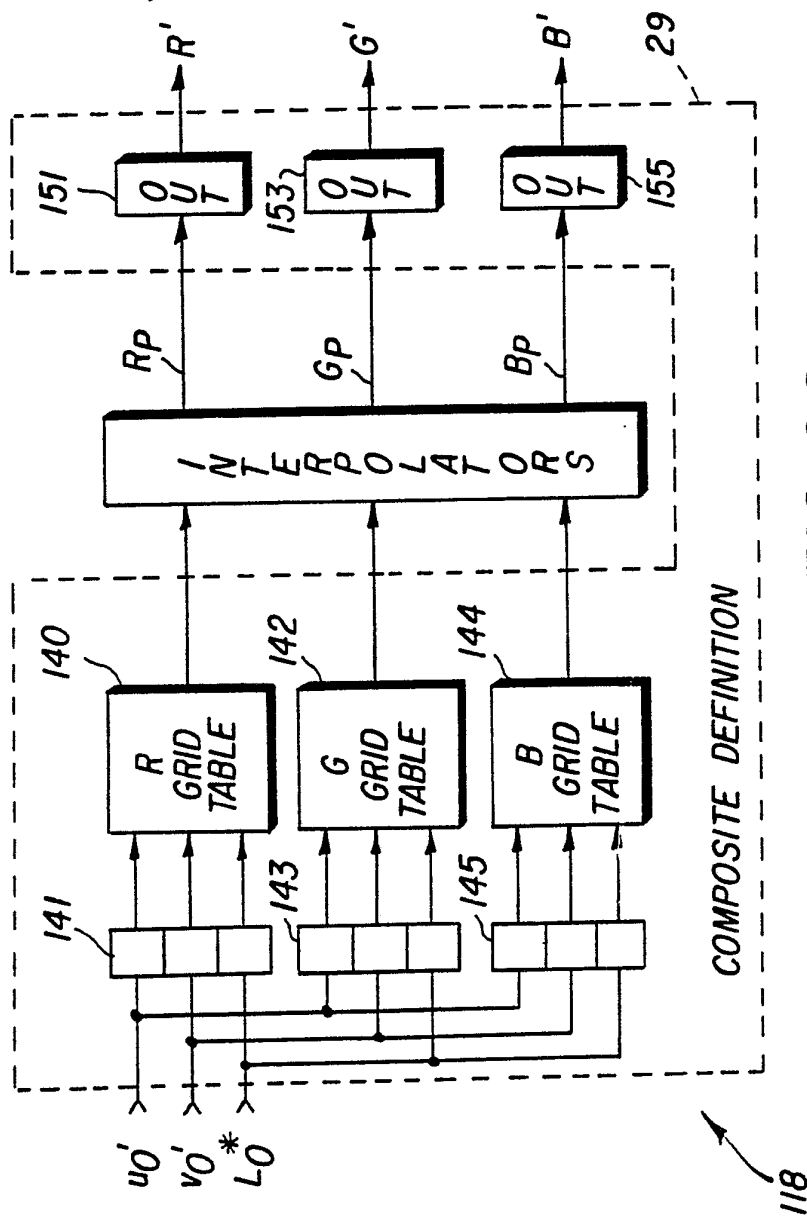
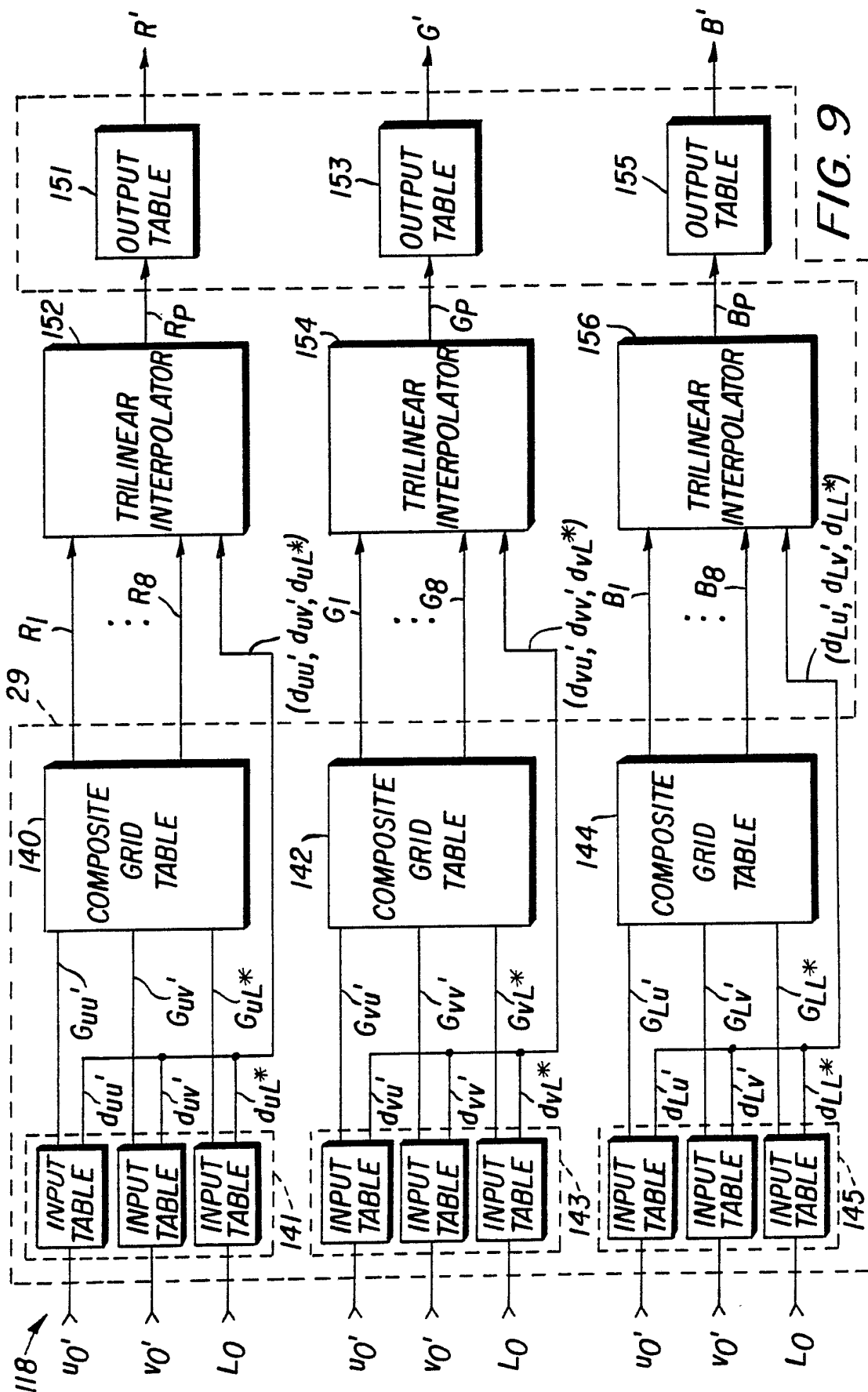


FIG. 8C

10/17



11/17

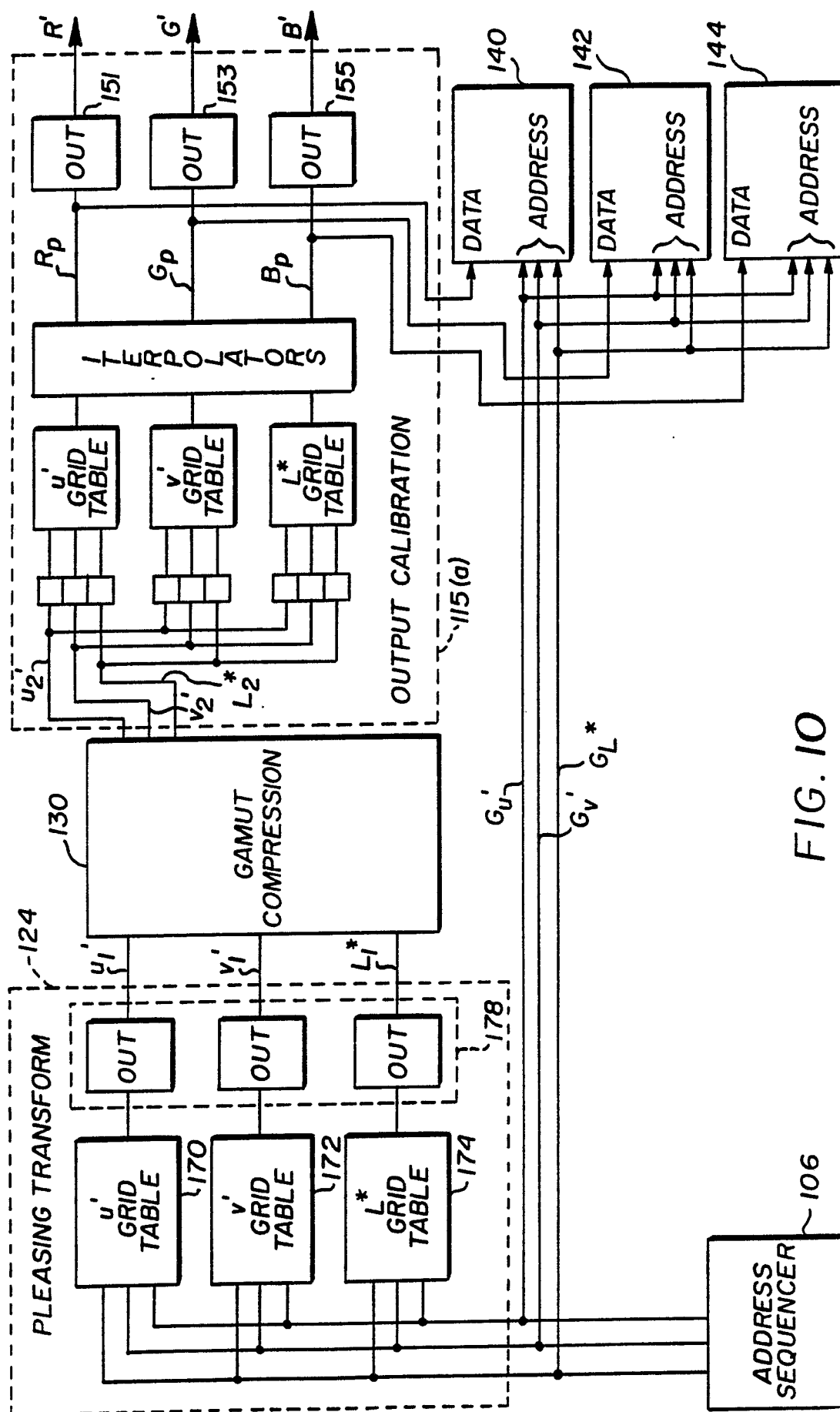
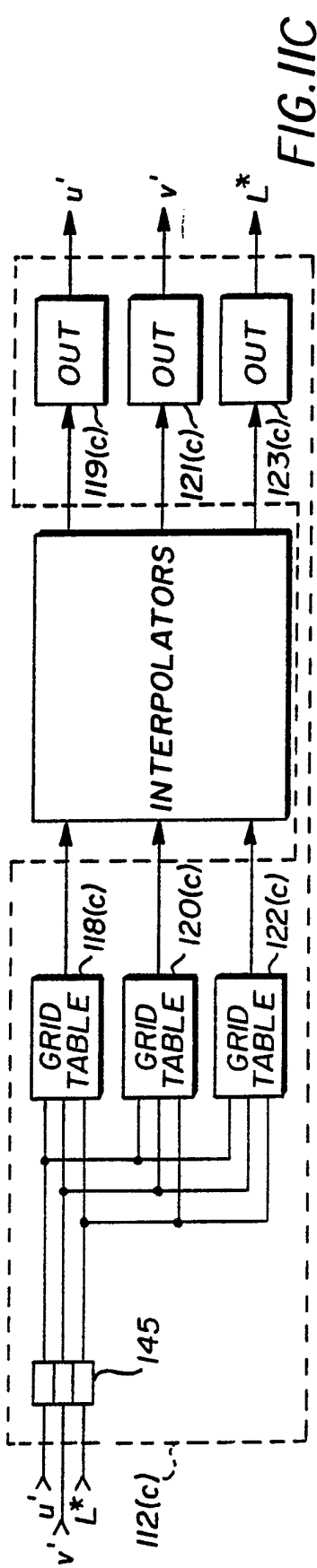
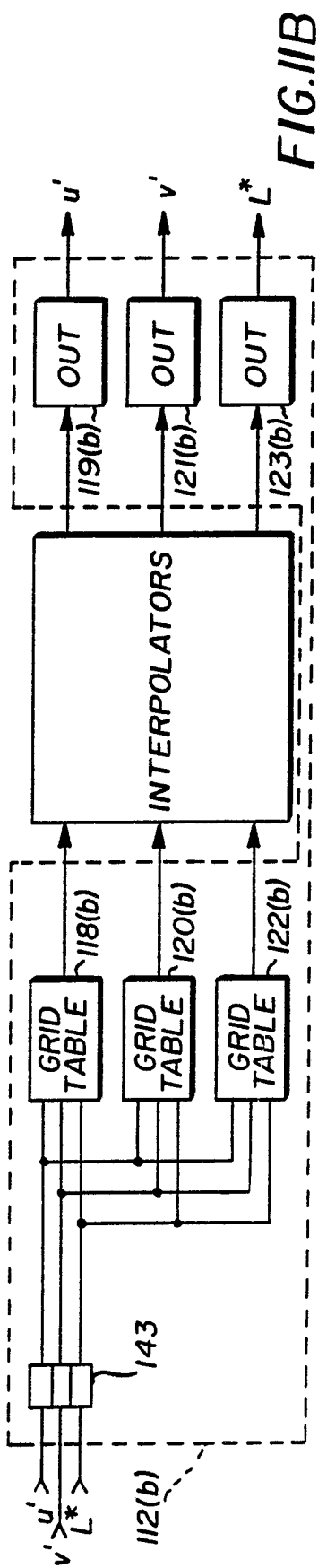
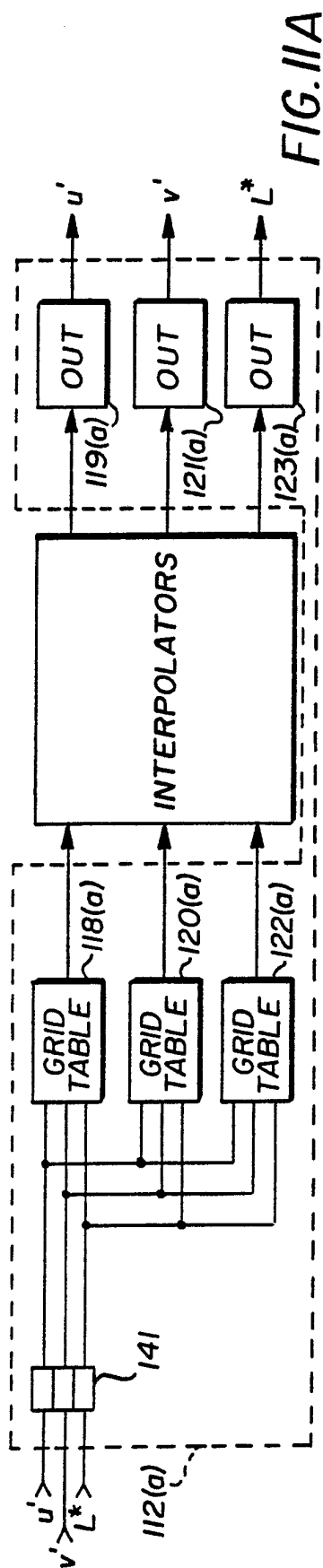


FIG. 10

12/17



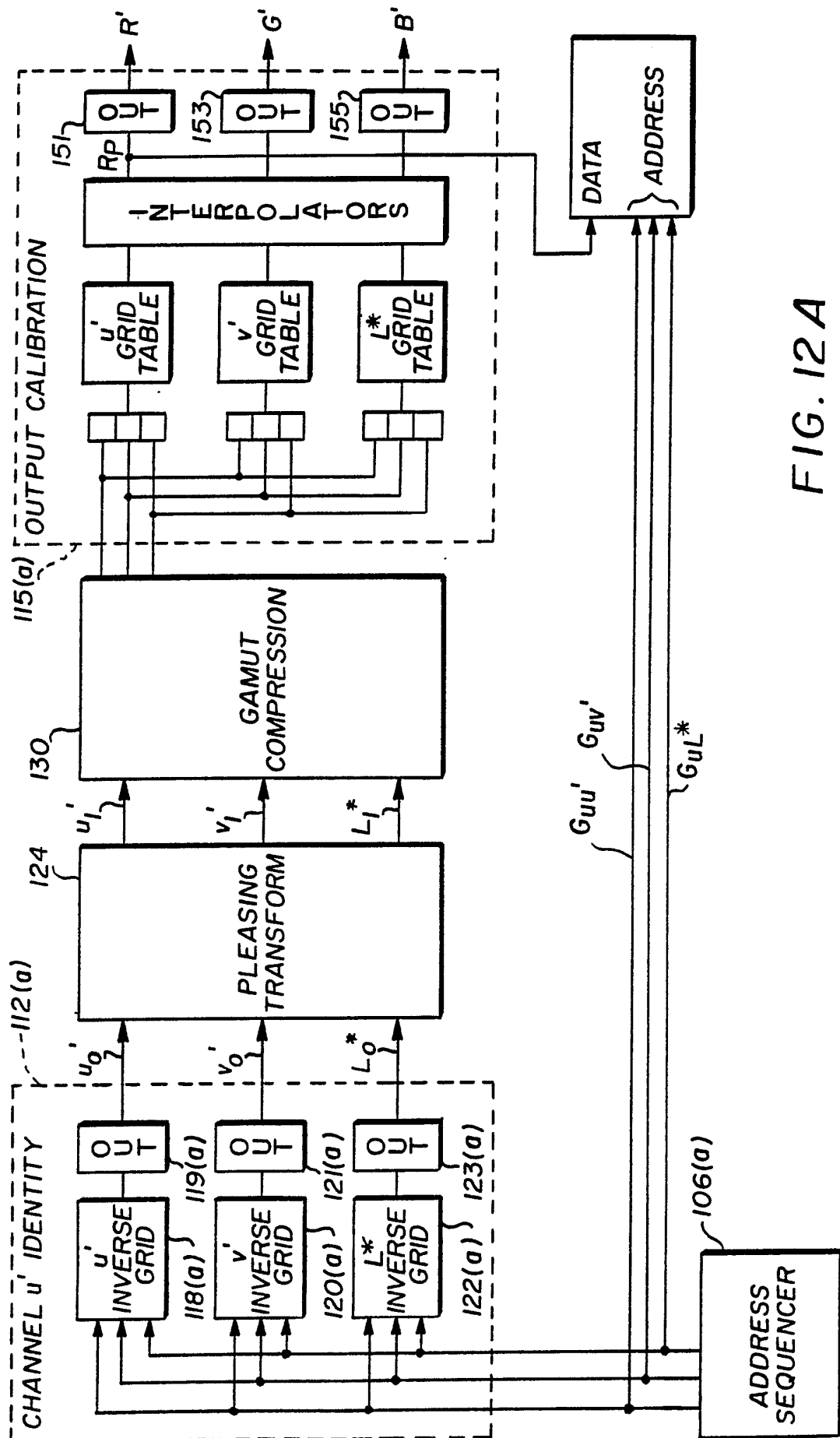


FIG. 12A

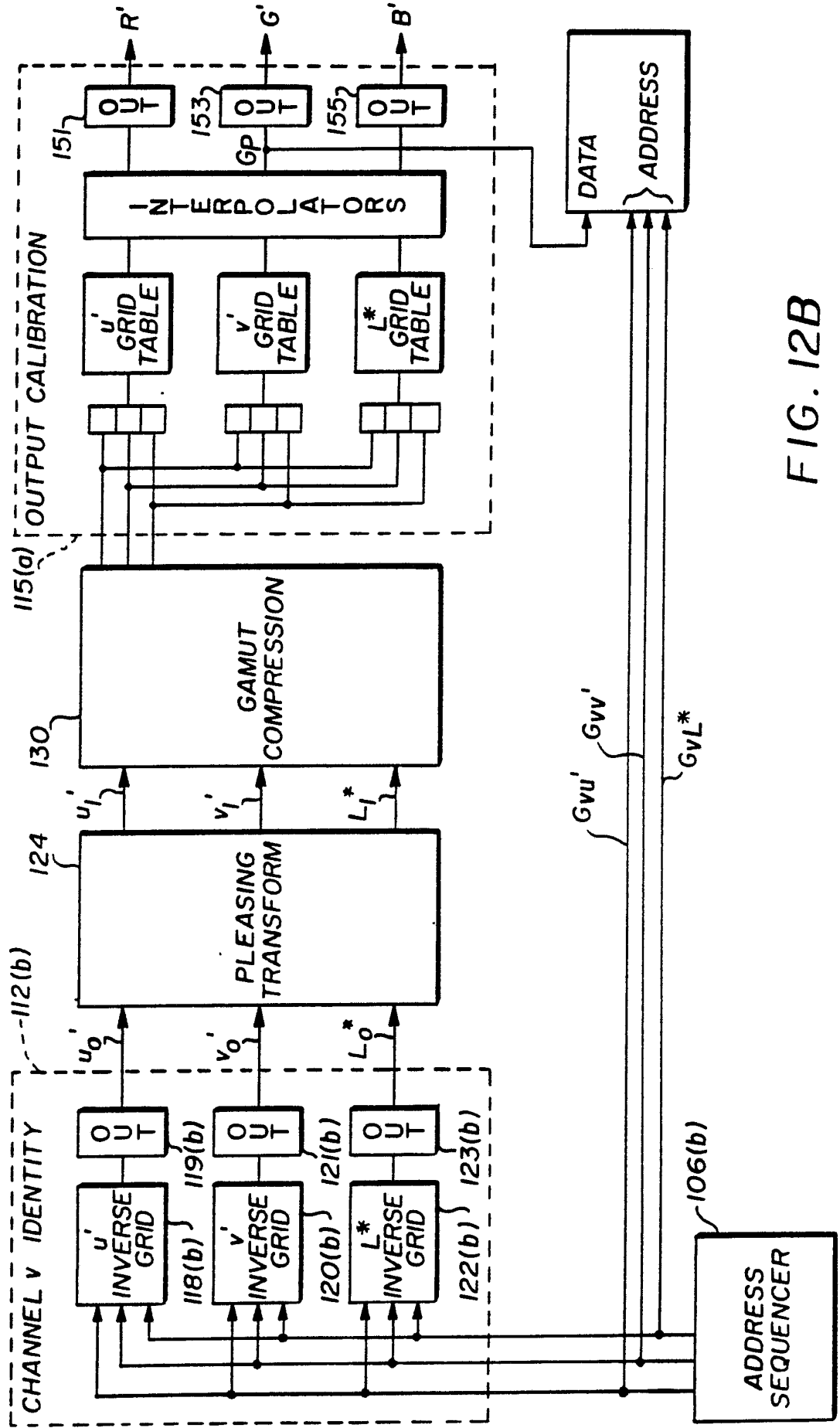


FIG. 12B

15/17

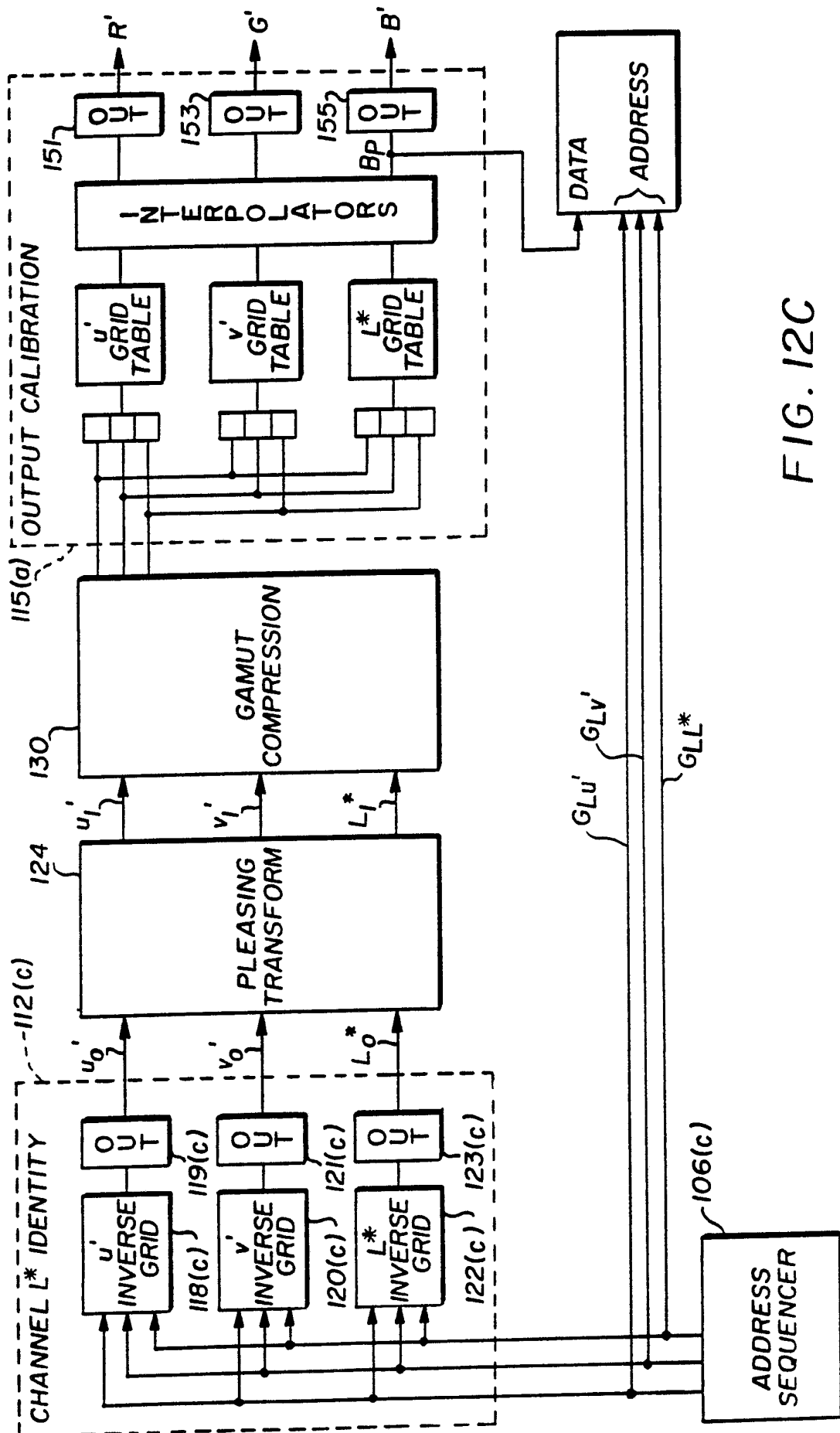


FIG. 12C

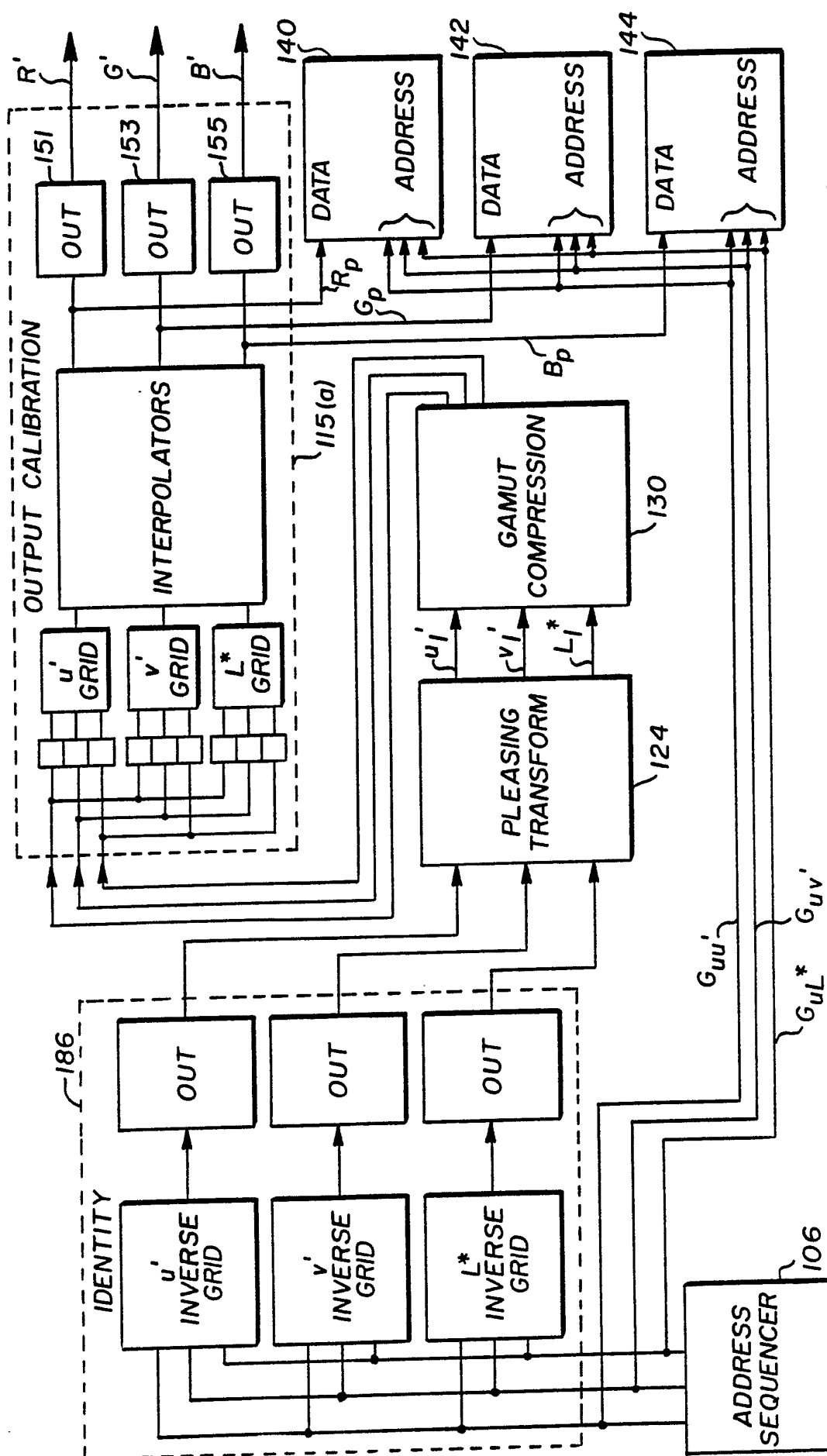
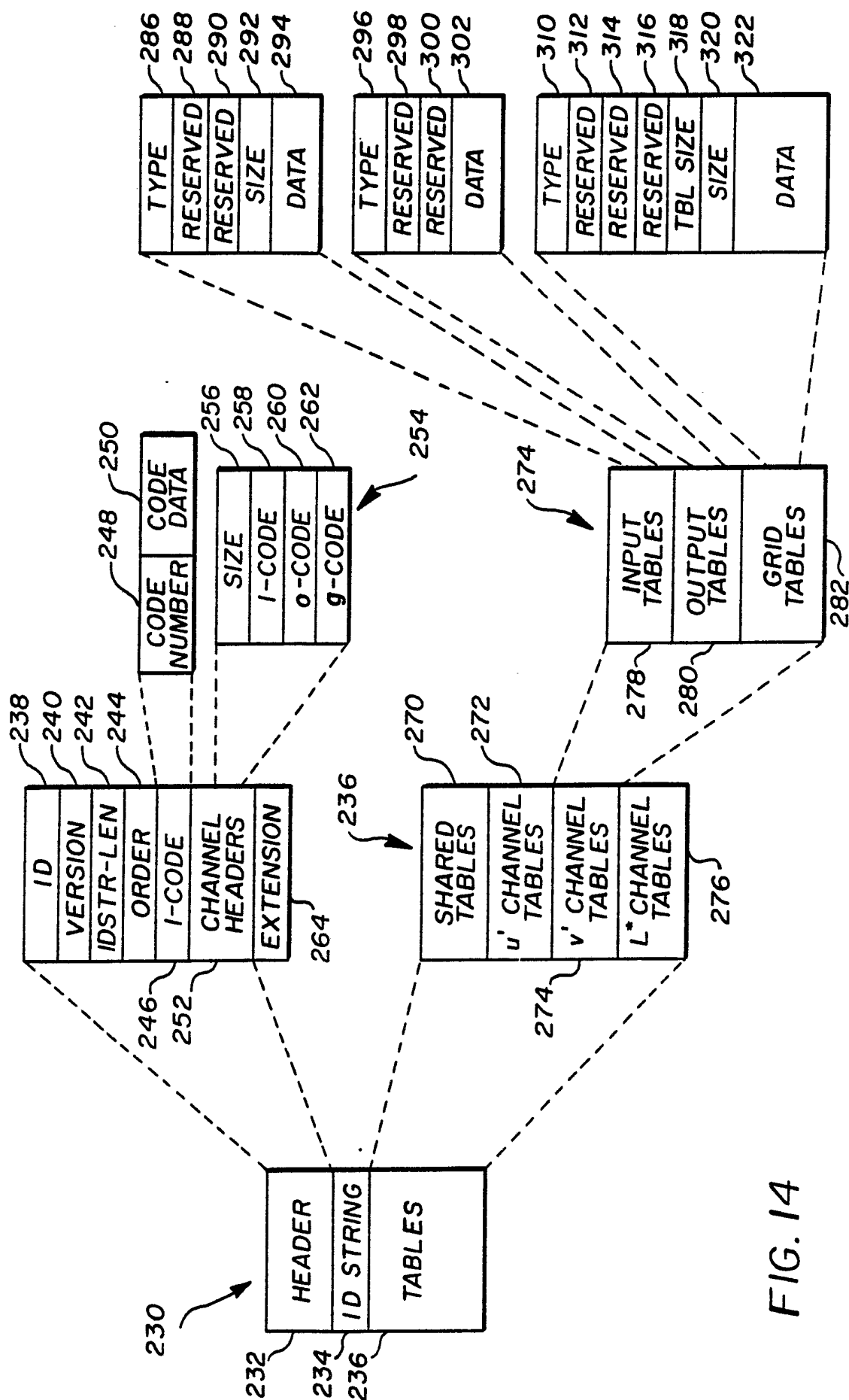


FIG. 13



INTERNATIONAL SEARCH REPORT

International Application No PCT/US 91/06911

I. CLASSIFICATION OF SUBJECT MATTER (if several classification symbols apply, indicate all) ⁶ According to International Patent Classification (IPC) or to both National Classification and IPC IPC5: H 04 N 1/46, G 03 F 3/08		
II. FIELDS SEARCHED Minimum Documentation Searched ⁷		
Classification System	Classification Symbols	
IPC5	H 04 N, G 03 F	
Documentation Searched other than Minimum Documentation to the Extent that such Documents are Included in Fields Searched ⁸		
III. DOCUMENTS CONSIDERED TO BE RELEVANT⁹		
Category *	Citation of Document, ¹¹ with indication, where appropriate, of the relevant passages ¹²	Relevant to Claim No. ¹³
X	EP, A1, 188098 (CROSFIELD ELECTRONICS LIMITED) 23 July 1986, see page 2, line 23 - line 25; page 3, line 24 - line 31; page 5, line 5 - line 29; page 7, line 12 - line 22; figure 1; claim 1 SEE PAGE 7, LINE 30-32	1,2, 15
A		3-14
A	--	16-59
X	EP, A1, 90596 (CROSFIELD ELECTRONICS LIMITED) 5 October 1983, see page 5, line 5 - line 11; page 7, line 3 - line 20; page 12, line 6 - line 12; figure 1; claims 10-12	1-15
	--	
* Special categories of cited documents: ¹⁰ "A" document defining the general state of the art which is not considered to be of particular relevance "E" earlier document but published on or after the international filing date "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "O" document referring to an oral disclosure, use, exhibition or other means "P" document published prior to the international filing date but later than the priority date claimed "T" later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle or theory underlying the invention "X" document of particular relevance, the claimed invention cannot be considered novel or cannot be considered to involve an inventive step "Y" document of particular relevance, the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such docu- ments, such combination being obvious to a person skilled in the art. "&" document member of the same patent family		
IV. CERTIFICATION		
Date of the Actual Completion of the International Search	Date of Mailing of this International Search Report	
6th February 1991	14 FEB 1992	
International Searching Authority	Signature of Authorized Officer	
EUROPEAN PATENT OFFICE	H. T. TAZELAAR	

III. DOCUMENTS CONSIDERED TO BE RELEVANT (CONTINUED FROM THE SECOND SHEET)		
Category *	Citation of Document, with indication, where appropriate, of the relevant passages	Relevant to Claim No
X	EP, A2, 321983 (MINOLTA CAMERA KABUSHIKI KAISHA) 28 June 1989, see page 5, line 5 - line 14; page 9, line 19 - line 54; figure 9	1,15
A	--	2-14
A	US, A, 4941039 (JOHN R. E'ERRICO) 10 July 1990, see figure 4	1-59
A	--	
A	EP, A2, 173032 (POLAROID CORPORATION) 5 March 1986, see page 24, line 19 - page 25, line 16; figure 1; claims 15,16	1-59
A	--	
A	US, A, 4893181 (ANDREW J. V. YEOMANS) 9 January 1990, see column 3, line 10 - line 16; figure 1	1-26
A	--	
A	US, A, 4899216 (TATSUMI ET EL) 6 February 1990, see column 7, line 58 - column 9, line 61	1-59
	--	

**ANNEX TO THE INTERNATIONAL SEARCH REPORT
ON INTERNATIONAL PATENT APPLICATION NO. PCT/US 91/06911**

SA 52419

This annex lists the patent family members relating to the patent documents cited in the above-mentioned international search report.
The members are as contained in the European Patent Office EDP file on 31/10/91
The European Patent office is in no way liable for these particulars which are merely given for the purpose of information.

Patent document cited in search report	Publication date	Patent family member(s)	Publication date
EP-A1- 188098	23/07/86	NONE	
EP-A1- 90596	05/10/83	NONE	
EP-A2- 321983	28/06/89	NONE	
US-A- 4941039	10/07/90	NONE	
EP-A2- 173032	05/03/86	NONE	
US-A- 4893181	09/01/90	EP-A- 0310388	05/04/89
		JP-A- 1163879	28/06/89
US-A- 4899216	06/02/90	EP-A- 0258740	09/03/88
		JP-A- 63061578	17/03/88
		JP-A- 63061579	17/03/88
		JP-A- 63061580	17/03/88
		JP-A- 63061591	17/03/88

For more details about this annex : see Official Journal of the European patent Office, No. 12/82