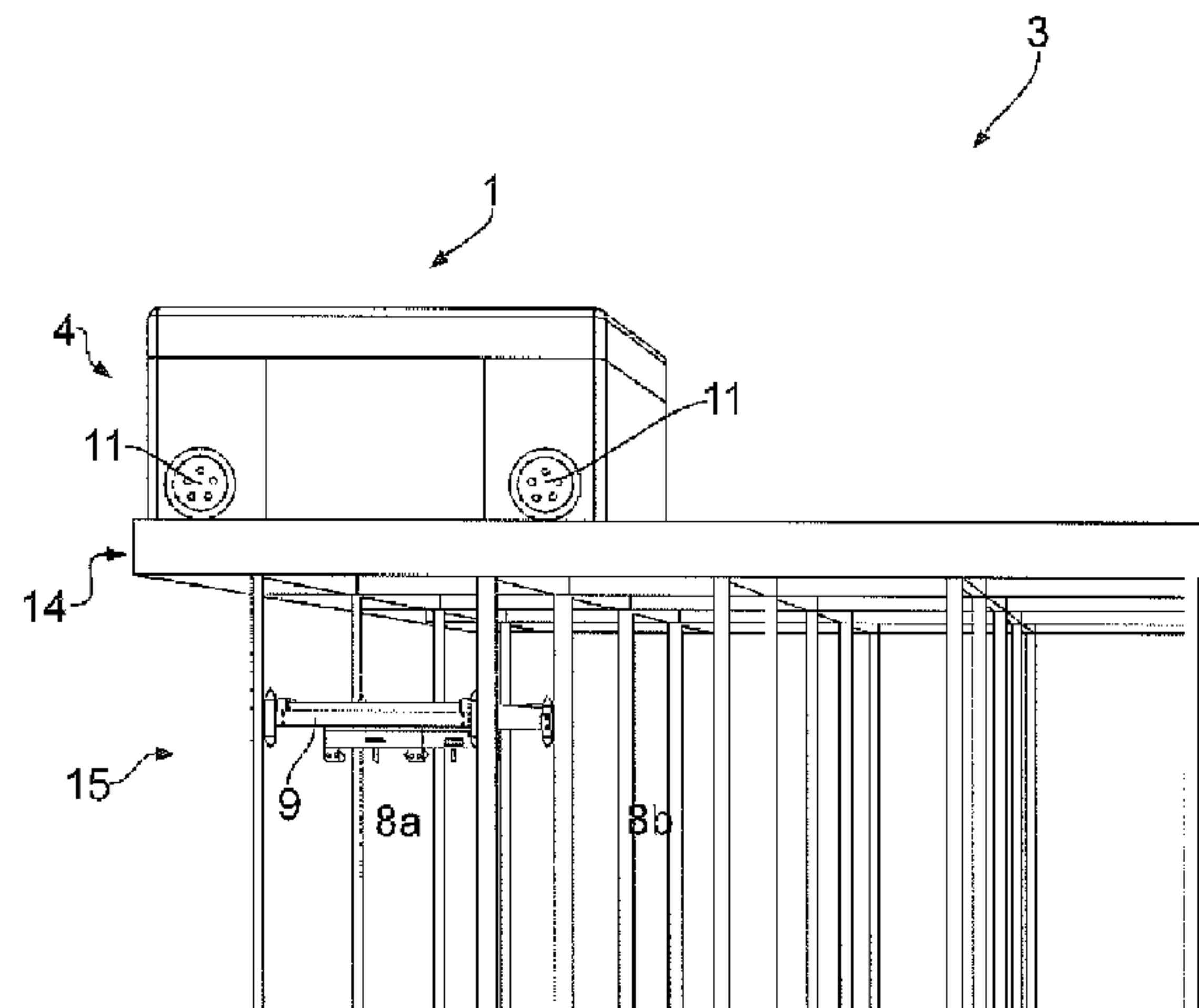




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(54) Title: ROBOT FOR TRANSPORTING STORAGE BINS



(57) **Abrégé/Abstract:**

The present invention concerns a remotely operated vehicle or robot for picking up storage bins from a storage system. The inventive vehicle or robot comprises a vehicle body, which vehicle body further comprises a first section for storing vehicle driving means and a second section for receiving any storage bin stored in a storage column within the storage system, a vehicle lifting device which is at least indirectly connected to the vehicle body in order to lift the storage bin into the second section, a first set of vehicle rolling means connected to the vehicle body in order to allow movement of the vehicle along a first direction (X) within the storage system during use and a second set of vehicle rolling means connected to the vehicle body in order to allow movement of the vehicle along a second direction (Y) in the storage system during use. The second direction (Y) is oriented perpendicular to the first direction (X). The inventive vehicle is characterized in that the second section comprises a cavity arranged centrally within the vehicle body. This cavity has at least one bin receiving opening facing towards the underlying storage columns during use. In addition, at least one of the two sets of vehicle rolling means is arranged fully within the vehicle body.

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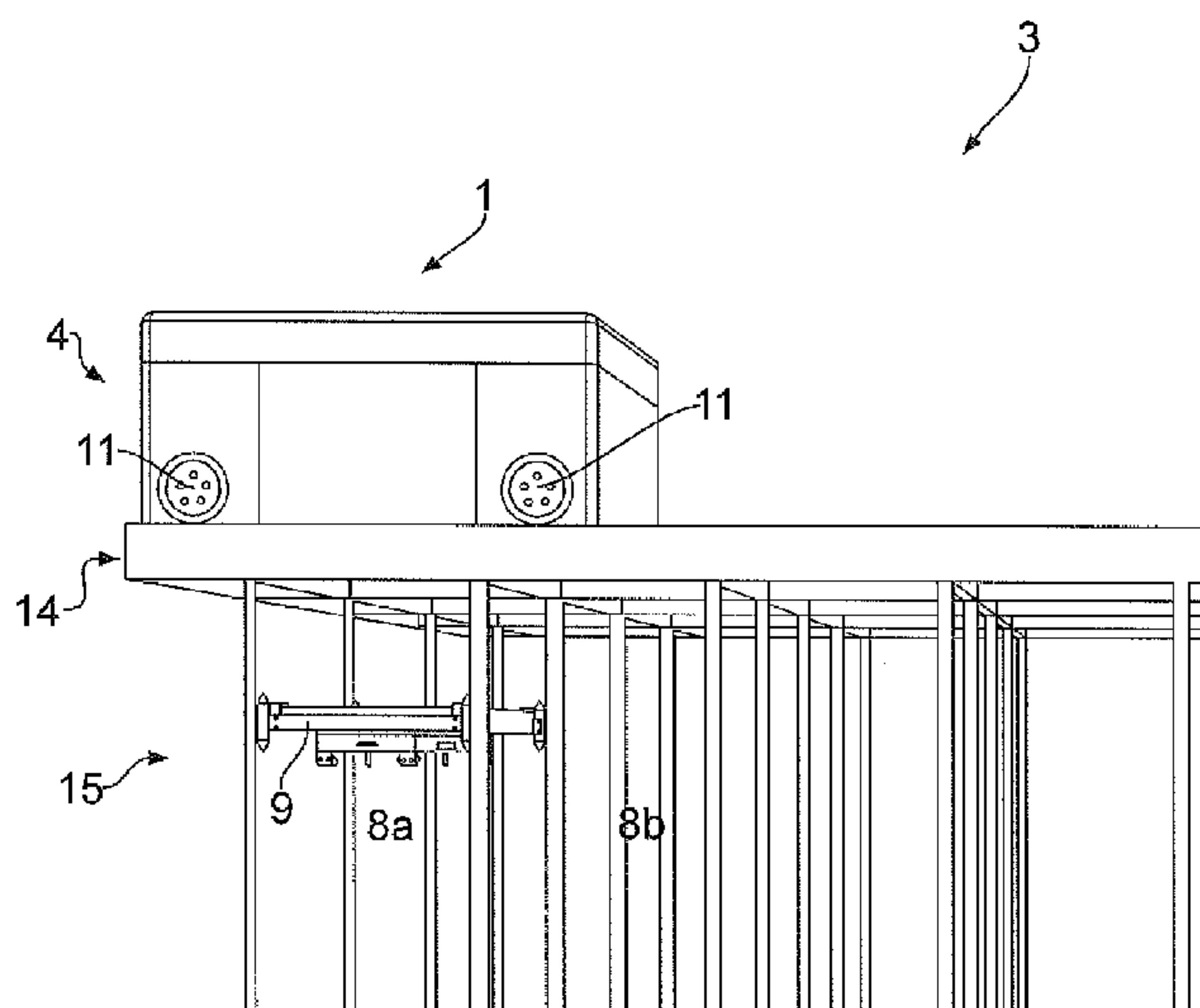


FIG. 8

(57) Abstract: The present invention concerns a remotely operated vehicle or robot for picking up storage bins from a storage system. The inventive vehicle or robot comprises a vehicle body, which vehicle body further comprises a first section for storing vehicle driving means and a second section for receiving any storage bin stored in a storage column within the storage system, a vehicle lifting device which is at least indirectly connected to the vehicle body in order to lift the storage bin into the second section, a first set of vehicle rolling means connected to the vehicle body in order to allow movement of the vehicle along a first direction (X) within the storage system during use and a second set of vehicle rolling means connected to the vehicle body in order to allow movement of the vehicle along a second direction (Y) in the storage system during use. The second direction (Y) is oriented perpendicular to the first direction (X). The inventive vehicle is characterized in that the second section comprises a cavity arranged centrally within the vehicle body. This cavity has at least one bin receiving opening facing towards the underlying storage columns during use. In addition, at least one of the two sets of vehicle rolling means is arranged fully within the vehicle body.

ROBOT FOR TRANSPORTING STORAGE BINS

The present invention relates to a remotely operated vehicle for picking up storage bins from a storage system as defined in the preamble of claim 1.

The invention also relates to a storage system using the inventive vehicle.

- 5 A remotely operated vehicle for picking up storage bins from a storage system is known. A detailed description of a relevant prior art storage system is given in WO 98/49075. Further, details of a prior art vehicle being suitable for such a storage system is disclosed in Norwegian patent NO317366. More specifically the prior art storage system comprises a three dimensional storage grid containing storage bins
10 that are stacked on top of each other to a certain height. The storage grid is normally constructed as aluminium columns interconnected by top rails. A number of remotely operated vehicles, or robots, are arranged on the top rails. Each vehicle is equipped with a lift for picking up, carrying, and placing bins that are stored inside the storage grid.
- 15 Such a prior art storage system and prior art robot is illustrated in figures 1 and 2, respectively. The storage system 3 comprises a robot 1 which is arranged to move on dedicated supporting rails 13 and to receive a storage bin 2 from a storage column 8 within a bin storing grid 15. The storage system 3 includes a plurality of such robots 1 and a dedicated bin lift device 50, the latter being arranged to receive
20 a storage bin 2 from the robot 1 at the top level of the bin storing grid 15 and to convey the storage bin 2 down in a vertical direction to a delivery station 60.

- However, the prior art robot 1 shown in both fig. 1 and fig. 2 suffers from several important disadvantages during their operation. Firstly, the particular design of the robot prevents access to all off the available storage columns in the storage
25 system. Furthermore, this particular design may cause an undesirable high torque during lifting and transportation of storage bins, thereby creating potential instability problems, as well as a clear limitation of the robots maximum handling weight. An additional disadvantage caused by the prior art robot design is the fact that only one particular bin and one particular bin height may be accepted for each
30 type of robot in order to ensure adequate stability. Finally, the presence of an integrated yoke / overhang in the upper part of the section receiving the storage bin necessitates an undesired speed reduction at the final stage of the lifting process performed by the yoke suspended vehicle lifting device.

- The object of the present invention is to solve, or at least substantially alleviate, the
35 above-described disadvantages, that is to provide a vehicle / robot with higher stability properties, higher maximum handling weights, a more effective use of available space during operation and a less time consuming lifting and transporting process of storage bins.

The above-identified objects are achieved by a remotely operated vehicle as defined in claim 1 and storage system as defined in claim 11. Further beneficial features are defined in the dependent claims.

5 In particular, the present invention concerns a remotely operated vehicle or robot for picking up storage bins from a storage system. The inventive vehicle or robot comprises a vehicle body, which vehicle body further comprises a first section for storing vehicle driving means and a second section for receiving any storage bin stored in a storage column within the storage system, a vehicle lifting device which is at least indirectly connected to the vehicle body in order to lift the storage bin
10 into the second section, a first set of vehicle rolling means connected to the vehicle body in order to allow movement of the vehicle along a first direction (X) within the storage system during use and a second set of vehicle rolling means connected to the vehicle body in order to allow movement of the vehicle along a second direction (Y) in the storage system during use. The second direction (Y) is oriented
15 perpendicular to the first direction (X).

The inventive vehicle is characterized in that the second section comprises a cavity arranged centrally within the vehicle body. This cavity has at least one bin receiving opening facing towards the underlying storage columns during use. In addition, at
20 least one of the two sets of vehicle rolling means is arranged fully within the vehicle body.

In order to allow easy entrance of the storage bin into the central cavity, its volume should be larger than the largest storage bin intended to be picked from the storage
25 system. Likewise, the cross sectional area of at least one of the at least one bin receiving opening should be larger than the cross sectional area of the storage bin walls oriented parallel to the cavity opening(s).

The vehicle may further comprise means for reversibly and selectively displacing
30 either the first set of vehicle rolling means or the second vehicle rolling means away from an underlying vehicle support within the storage system during a change of vehicle direction between the first direction (X) and the second direction (Y).

Furthermore, in an embodiment the first section may be arranged relative to the
35 second section in such a way that the cross section of the vehicle parallel to the underlying vehicle support deviates from a quadratic shape.

In a preferred embodiment the vehicle body covers less or equal to the lateral cross sectional area of one central storage column in the first direction (X) and covers the
40 lateral cross sectional area of more than one central storage column in the second direction (Y) during use. In a more specific example the vehicle body extends

beyond the lateral cross sectional area of the central storage column at both sides facing the second direction (Y), i.e. covering also some of the cross sectional areas of the adjacent storage columns extending in the second direction (Y). The degree of extension from the central storage column is preferably equal on both of these
5 sides. Central storage column is defined as the storage column which is immediately below a robot when the latter has reached a position allowing pick-up of a storage bin.

In order to inter alia allow high vehicle stability both sets of vehicle rolling means
10 is preferably arranged symmetrically around the cavity, for example near the lower corners of the vehicle. At least one, and most preferably both, set(s) of vehicle rolling means may comprise at least four wheels. Other embodiments such as the use two perpendicular oriented caterpillar belts may be envisaged. Furthermore, both sets have an exterior design matching a corresponding exterior design on
15 supporting rails constituting the vehicle support in order to provide increased lateral stability when interconnected. Such supporting rails would be arranged in a two dimensional matrix on top of a bin storing structure or grid, where the principal directions of both the matrix and the grid are congruent with the vehicle's first direction (X) and second direction (Y).

20 The vehicle may advantageously also include position sensing means to allow measurements of the vehicle position within the storage system during use. This position sensing means may comprise a plurality of position sensors arranged in at least some of the positions on the vehicle body which would transverse the locations
25 of vehicle support where the supporting rails are crossing, for example underneath the vehicle, close to its lower corners.

The present invention also concerns a storage system which comprises a remotely operated vehicle in accordance with the above mentioned features, a vehicle support
30 comprising a plurality of supporting rails forming a two dimensional matrix of guiding meshes, wherein the vehicle support is configured to guide the movements of the vehicle in the first direction (X) and the second direction (Y) during use, a bin storing structure or grid supporting the vehicle support comprising a plurality of storage columns, wherein each of the storage columns is arranged to accommodate a
35 vertical stack of storage bins and wherein the main part of the bin storing structure coincides with positions on the vehicle support where the supporting rails are crossing, and a bin lift device arranged to convey a vehicle delivered storage bin in a direction perpendicular to the lateral plane of the vehicle support between the vehicle support and a delivery station.

40 In a preferred embodiment at least some of the supporting rails arranged at the outer lateral border areas of the vehicle support form outer guiding meshes having

reduced average cross sectional areas compared to the average cross sectional area of the remaining guiding meshes in the vehicle support. For example, the average reduced cross sectional areas of the outer guiding meshes may be about half of the average cross sectional area of the remaining guiding meshes in the vehicle support.

- 5 In a particularly preferred embodiment these cross sectional areas of the outer guiding meshes are reduced only along the second direction (Y) of the vehicle support.

10 The central arrangement of the cavity in the vehicle body relative to the second direction (Y) effectively remove the undesired torque, thereby improving the stability of the robot or vehicle. This arrangement also results in a lifting and transporting process having a weight distribution with a high degree of symmetry. Furthermore, the novel design allows the same vehicle to be used for lifting and transporting storage bins of heights significantly less than the cavity height (i.e. the height extending from the suspension points of the lifting device and to the lower edge of the vehicle) since the framework / body surrounding at least part of the bin receiving cavity effectively hinders any undesired bin reeling / wobbling. The presence of the cavity surrounding body also allows maintaining full or nearly full lifting speed almost all the way to its end position within the cavity, as well as

15 20 initiation of stable bin transportations towards the delivery station prior to a fully completed bin lifting from a storage column. The protective body around the cavity also gives the possibility of starting a descent of the lifting device event prior to the time the vehicle has come to a final halt above the storage column in question. A significantly higher stability and time efficiency is thus achieved.

- 25 By arranging at least one set of vehicle rolling means fully within the vehicle or robot body additional stability is obtained during the lifting process since the rolling means is situated closer to the storage bin to be lifted. Of the same reason this arrangement reduces the total load on the lifting device. Furthermore, the arrangement is more space efficient relative to the prior art robot illustrated in figure 2 since the roller means does not give any additional extensions in at least one of the two robots moving directions (X and Y). Production of smaller sized robots / vehicles is also rendered possible.
- 30

These and other characteristics of the invention will be clear from the following description of a preferential form of embodiment, given as a non-restrictive example, with reference to the attached drawings wherein:

35

Fig. 1 is a perspective view of a prior art storage system;

Fig. 2 is a sectional view of a prior art robot or vehicle forming part of a storage system as illustrated in fig. 1;

- 40 Fig. 3 is a perspective base view of a remotely operated vehicle according to the present invention;

Fig. 4 is a perspective top view of a remotely operated vehicle according to the present invention;

Fig. 5 is a perspective top view of a robot assembly comprising a remotely operated vehicle according to the present invention, a storage bin and a fully enclosing cover,

5 Fig. 6 is a perspective top view of a bin storing grid and a vehicle support in accordance with the present invention;

Fig. 7 is a perspective side view of a bin storing grid and a vehicle support in accordance with the present invention;

10 Fig. 8 is a perspective side view of part of a storage system in accordance with the present invention including a bin storing grid, a vehicle support and a remotely operated vehicle; and

Fig. 9 is a schematic top view of a remotely operated vehicle moving on a two dimensional matrix of supporting rails.

15 Fig. 1 is a schematic, partly cut perspective view of a storage system according to the prior art, and fig. 2 is a sectional view of a corresponding prior art robot. Both figures have already been referred to earlier in the text.

Fig. 3 and 4 gives a perspective view in two different angles of the inventive robot 1 comprising a rectangular vehicle body or framework 4 with a cavity 7 centrally arranged within the body 4, a top lid 72 covering the top part of the body 4, a first set of four wheels 10 mounted inside the cavity 7 and in parallel to the interior walls of the body 4 and a second set of four wheels 11 mounted in parallel to the exterior walls of the body 4. The first and second set of wheels 10,11 are oriented perpendicular to each other. Further, the vehicle body 4 also includes side parts 5,5a,5b arranged on both sides of the cavity 7 along at least one of the robots 1 direction of movements. For the sake of clarity a Cartesian coordinate system is shown with its X, Y and Z axes aligned along the principal directions of the rectangular vehicle body 4. The size of the cavity 7 is adapted to contain necessary component for a lifting device 9 and to at least completely contain the largest storage bin 2 intended to be picked up by the robot 1.

30 Fig. 5 gives a perspective view of a robot assembly where the body 4 is completely covered by an enclosing cover 73 comprising handles 74 and transmission means / control panel 75. The design of the enclosing cover 73 is adapted to the particular shape given by the body 4 and the protruding wheels 10. Fig. 5 also shows a small part of a storage bin 2 arranged fully inside the cavity 7 and a small part of the lifting device 9. The latter is preferably composed of inter alia four vertically moveable metal bands suspended on the cavity facing side of the top lid 72 in their upper ends and steering rods at the lower ends capable of being steered and fastened into adapted cavities / areas in the storage bin 2 to be picked.

The structural principles of a grid assembly comprising a bin storing structure or grid 15, integrated supporting rails 13 constituting the vehicle support 14 and a grid supporting base 76 are illustrated in figs. 6 and 7. The grid 15 comprises a plurality of pillars being arranged with internal distances adapted to accommodate storage bins 2 to be stored in stacks inside the grid 15. The rectangular arrangements of four adjacent pillars therefore constitute a storage column 8. Both the pillars and the rails 13 may be made of Aluminium. As for fig. 3 and 4 a Cartesian coordinate system is shown aligned along the principal directions of the grid assembly to ease the understanding. The supporting rails 13 form a two dimensional matrix of rectangular meshes, and the cross sectional area of most of these meshes coincide with the cross sectional area of each storage columns 8 set up by the underlying grid 15. The meshes at the border area 17,18 of the vehicle support 14 (at both sides in direction Y) is illustrated with cross sectional areas smaller than the remaining meshes. The size of the border meshes 17,18 should preferably be adapted to the degree of extension beyond a central storage column 8a situated immediately below the cavity 7 of the robot 1 when the latter is in a position for initiating pick up of a storage bin 2 contained in the central storage column 8a (see fig. 8 and 9). In this way the robot 1 may reach all the storage columns 8 in the storage system 3, i.e. independently of the robot orientation in the Y direction. For example, if the robot 1 extends exactly over the cross sectional area of one central storage column 8a in the X direction and over $\frac{1}{2}$ of the cross sectional area of the adjacent storage column 8b in the Y direction, the cross sectional area of the meshes 17,18 at the border area in the Y direction should be approximately $\frac{1}{2}$ of the cross sectional area of the remaining meshes. The primary function of these border meshes 17,18 is thus to allow sufficient space for the robot 1 having the novel design.

Fig. 8 shows the robot 1 in a lifting position above the central storage column 8a adjacent to the border area 17,18 of the grid assembly. The vehicle lifting device 9 is in this embodiment lowered a distance into the central storage column 8a in order to hook onto and lift up the underlying storage bin 2. As seen in the exemplary situation in figs. 8 the robot 1, having the body 4 extended in the Y direction compared to the X direction, may be driven all the way to the edge of the grid 15 when the border area is designed with additional border meshes 17,18 with a Y directional width approximately $\frac{1}{2}$ of the Y directional widths of the remaining meshes in the grid 15.

To better illustrate the movement of the robot 1 on the supporting rails 13 constituting the vehicle support 14 some exemplary positions of robots 1 on a grid assembly is illustrated in fig. 9. The thick arrows drawn in the centre of the robots 1 indicate allowed moving directions. When the robot 1 is situated with its cavity 7 exactly above a central storage column 8a, as is the case for the top left and mid centred robot 1, the arrangement of the supporting rails 13 allow movement in both X and Y directions. Any other positions on the grid assembly restrict the robot's 1

- movement on the vehicle support 14 either in X direction (lower right robot 1) or in Y direction (top centered and bottom left robot 1). To allow determination of the robot position it is considered advantageous to equip each robot 1 with one or more position sensors 16, for example optical sensors. Such sensors should 16 preferably
- 5 be mounted in one or more areas of the robot 1 which ensures that the sensors 16 have both non-obstructed view to the underlying supporting rails 13 and that they pass directly above or close to the positions on the vehicle support 14 in which the rails 13 are crossing. The readings from the sensors 16 may inter alia dictate the further movement of the robot 1 and/or the operation of the vehicle lifting device 9.
- 10 All operations of the robot 1 are controlled by wireless communication means 75 and remote control units. This includes control of the robot movement, the vehicle lifting device and the position measurements.
- In the preceding description, various aspects of the apparatus according to the invention have been described with reference to the illustrative embodiment. For
- 15 purposes of explanation, specific numbers, systems and configurations were set forth in order to provide a thorough understanding of the apparatus and its workings. However, this description is not intended to be construed in a limiting sense. Various modifications and variations of the illustrative embodiment, as well as other embodiments of the apparatus, which are apparent to persons skilled in the
- 20 art to which the disclosed subject matter pertains, are deemed to lie within the scope of the present invention.

List of reference numerals / letters:

	1	Remotely operated vehicle / robot
	2	Storage bin
	3	Storage system
5	4	Vehicle body / framework
	5	First section (of vehicle body) / component section / side parts
	5a	First section, left
	5b	First section, right
	6	Vehicle driving means / motor unit
10	7	Vehicle storage space / second part / cavity / centrally arranged cavity
	8	Storage column
	8a	Central storage column
	8b	Adjacent storage column
	9	Vehicle lifting device
15	10	First set of vehicle rolling means / First set of wheels
	11	Second set of vehicle rolling means / Second set of wheels
	12	Bin receiving opening
	13	Supporting rail
	14	Vehicle support
20	15	Bin storing structure / grid
	16	Position sensing means / position sensor
	17	Left outer lateral border area of vehicle support / left border mesh
	18	Right outer lateral border area of vehicle support / right border mesh
	50	Bin lift device
25	60	Delivery station / port
	70	Yoke / overhang
	72	Top lid
	73	Enclosing cover
	74	Handles
30	75	Transmission means / control panel / wireless communication means
	76	Grid supporting base

CLAIMS

1. Remotely operated vehicle for picking up storage bins from a storage system, comprising

5 a vehicle body comprising a first section for storing vehicle driving means and a second section for receiving any storage bin stored in a storage column within the storage system,

the second section displaying a centrally arranged cavity within the vehicle body, the cavity having at least one bin receiving opening facing towards the storage columns during use,

10 a vehicle lifting device at least indirectly connected to the vehicle body for lifting the storage bin into the second section, and

a first set of vehicle rolling means connected to the vehicle body allowing movement of the vehicle along a first direction (X) within the storage system during use,

15 **characterized in that**

the vehicle further comprises

a second set of vehicle rolling means connected to the vehicle body allowing movement of the vehicle along a second direction (Y) in the storage system during use, the second direction (Y) being perpendicular to the first direction (X), wherein

20 at least one of the sets of vehicle rolling means is mounted onto the inner wall of the cavity.

2. Remotely operated vehicle in accordance with claim 1, **characterized in that** the vehicle rolling means is mounted in parallel to the interior walls of the body.

25

3. Remotely operated vehicle in accordance with claim 1 or 2, **characterized in that** the vehicle further comprising means for reversibly and selectively displacing either the first set of vehicle rolling means or the second vehicle rolling means away from an underlying vehicle support within the storage system during a change of vehicle direction between the first direction (X) and the second direction (Y).

30

4. Remotely operated vehicle in accordance with claim 1, **characterized in that** the vehicle body, when operated on the storage system comprising a plurality of storage columns, covers at most the lateral cross section of one central storage column in the first direction (X) and covers the lateral cross section of more than one central storage column in the second direction (Y).

35

5. Remotely operated vehicle in accordance with claim 4, **characterized in that** the vehicle body extends beyond the lateral cross section of the central storage column at both sides in the second direction (Y).
- 5 6. Remotely operated vehicle in accordance with claim 5, **characterized in that** the extension beyond the lateral cross section of the central storage column is equal on both sides in the second direction (Y).
- 10 7. Remotely operated vehicle in accordance with claim 1, **characterized in that** both sets of vehicle rolling means are symmetrically distributed around the centrally arranged cavity.
- 15 8. Remotely operated vehicle in accordance with claim 1, **characterized in that** at least one set of vehicle rolling means comprises at least four wheels.
- 20 9. Remotely operated vehicle in accordance with claim 1, **characterized in that**, when operated on the storage system comprising a plurality of supporting rails forming a two dimensional matrix of guiding meshes arranged on top of a bin storing structure, both sets of vehicle rolling means aligned in the first direction (X) and the second direction (Y), respectively, have an exterior design that is congruent with the matrix and the bin storing structure in order to provide increased lateral stability when interconnected.
- 25 10. Remotely operated vehicle in accordance with claim 1, **characterized in that** the vehicle comprises position sensing means to allow measurements of the vehicle position within the storage system during use.
- 30 11. Remotely operated vehicle in accordance with claim 10, **characterized in that** the position sensing means comprising a plurality of sensors arranged in at least some of the positions on the vehicle body which, during use, transverses the positions of vehicle support where the supporting rails are crossing.
- 35 12. Storage system, **characterized by** comprising
- a remotely operated vehicle in accordance with one of claims 1-11,
- a vehicle support comprising a plurality of supporting rails forming a two dimensional matrix of guiding meshes, the vehicle support being configured to guide the movements of the vehicle in the first direction (X) and the second direction (Y) during use,

- a bin storing structure supporting the vehicle support, the structure comprising a plurality of storage columns, wherein

each storage column is arranged to accommodate a vertical stack of storage bins, and

5 the main part of the bin storing structure coincides with positions on the vehicle support where the supporting rails are crossing, and

- a bin lift device arranged to convey a vehicle delivered storage bin in a direction perpendicular to the lateral plane of the vehicle support between the vehicle support and a delivery station.

10

13. Storage system in accordance with claim 12, **characterized in that** at least some of the supporting rails arranged at the outer lateral border areas of the vehicle support form outer guiding meshes having reduced average cross section compared to the average cross section of the remaining guiding meshes in the vehicle support.

15

14. Storage system in accordance with claim 13, **characterized in that** the average reduced cross section of the outer guiding meshes is about half of the average cross section of the remaining guiding meshes in the vehicle support.

20

15. Storage system in accordance with claims 13 or 14, **characterized in that** the size of the outer guiding meshes is reduced only along the second direction (Y) of the vehicle support.

25

16. A bin storage system comprising a three-dimensional bin storage structure and a plurality of robot vehicles which are movable on top of the bin storage structure to retrieve storage bins from the bin storage structure, which bin storage structure comprises:

30

- a plurality of pillars which are positioned with internal distances and in a rectangular arrangement adapted to accommodate the storage bins, where the rectangular arrangement of the pillars define storage columns for the storage bins,

- supporting rails, and

- a storage bin delivery station,

which plurality of robot vehicles each comprises a vehicle body which comprises:

35

- a first set of rolling means for moving the robot vehicle along the supporting rails in the first direction (X),

- a cavity for receiving a storage bin, and

- a lifting device for retrieving a storage bin from a storage column and storing the storage bin in the cavity,

wherein the cavity is arranged centrally within the vehicle body,

characterized in that

5 - the supporting rails are arranged in a two-dimensional matrix on top of the pillars and provide a vehicle support for the plurality of robot vehicles allowing each robot vehicle to travel across the bin storage structure in a first direction (X) and in a second direction (Y), which is orthogonal to the first direction (X), in that

10 - the bin storage structure comprises a bin lift device which is arranged to receive storage bins from the plurality of robot vehicles and transport the storage bins in a vertical direction from a top level of the bin storage structure to the delivery station, and in that

15 - the vehicle body comprises a second set of rolling means for moving the robot vehicle along the supporting rails in the second direction (Y).

17. The bin storage system according to claim 16, **characterized in that** the vehicle body surrounds at least part of the cavity.

20 18. The bin storage system according to claim 17, **characterized in that** the vehicle body comprises side parts arranged on both sides of the cavity along at least one of the robot vehicle's direction of movements (X, Y).

25 19. The bin storage system according to any one of claims 16 to 18, **characterized in that** the robot vehicle comprises a top lid covering the top part of the vehicle body.

20. The bin storage system according to any one of claims 16 to 19, **characterized in that** the cavity displays a downwardly facing opening for the storage bin.

30 21. The bin storage system according to any one of claims 16 to 20, **characterized in that** both sets of vehicle rolling means are arranged symmetrically around the cavity near the lower corners of the robot vehicle.

35 22. The bin storage system according to any one of claims 16 to 21, **characterized in that** said first and second sets of rolling means each comprises at least four wheels.

23. A method of operating a bin storage system comprising a three-dimensional bin storage structure and a plurality of robot vehicles which are movable on top of the bin storage structure to retrieve storage bins from the bin storage structure, which bin storage structure comprises:
- 5 - a plurality of pillars which are positioned with internal distances and in a rectangular arrangement adapted to accommodate the storage bins, where the rectangular arrangement of the pillars define storage columns for the storage bins,
 - supporting rails which are arranged in a two-dimensional matrix on top of the pillars and provide a vehicle support for the plurality of robot vehicles allowing
 - 10 each robot vehicle to travel across the bin storage structure in a first direction (X) and a second direction (Y), which is orthogonal to the first direction (X),
 - a storage bin delivery station, and
 - a bin lift device which is arranged to transport the storage bins, in a vertical direction, from a top level of the bin storage structure to the delivery station,
 - 15 and which plurality of robot vehicles each comprises a vehicle body which comprises:
 - a first set of rolling means for moving the robot vehicle along the supporting rails in the first direction (X),
 - a second set of rolling means for moving the robot vehicle along the
 - 20 supporting rails in the second direction (Y),
 - a cavity for receiving a storage bin, which cavity is arranged centrally within the vehicle body,
 - a lifting device for retrieving a storage bin from a storage column and storing the storage bin in the central cavity,
 - 25 which method comprises the steps of:
 - positioning one of the plurality of robot vehicles above one of said storage columns such that the central cavity of the vehicle body is aligned with the storage column,
 - using the lifting device of the vehicle body, retrieving a storage bin from the
 - 30 storage column and storing the storage bin inside the central cavity,
 - using the first and second sets of rolling means, moving the robot vehicle along the supporting rails to the bin lift device and transferring the storage bin to the bin lift device, and

- using the bin lift device, conveying the storage bin down in a vertical direction from the top level of the bin storage structure to the delivery station.
24. The method according to claim 23, wherein the vehicle body surrounds at least part of the central cavity.
25. The method according to claim 24, wherein the vehicle body comprises side parts arranged on both sides of the cavity along at least one of the robot vehicle's direction of movements (X, Y).
26. The method according to any one of claims 23-25, wherein the robot vehicle comprises a top lid covering the top part of the vehicle body.
27. The method according to any one of claims 23-26, wherein the central cavity displays a downwardly facing opening for the storage bin.
28. The method according to any one of claims 23-27, wherein both sets of vehicle rolling means are arranged symmetrically around the cavity near the lower corners of the robot vehicle.
29. The method according to any one of claims 23-28, wherein said first and second sets of rolling means each comprises at least four wheels.
30. A storage system comprising
- a remotely operated vehicle,
 - a vehicle support comprising a plurality of supporting rails forming a two dimensional matrix of guiding meshes, the vehicle support being configured to guide the movements of the remotely operated vehicle in a first direction (X) and a second direction (Y) during use,
 - a bin storing structure supporting the vehicle support, the structure comprising a plurality of storage columns, wherein each storage columns is arranged to accommodate a vertical stack of storage bins, and the main part of the bin storing structure coincides with positions on the vehicle support where the supporting rails are crossing,
 - a bin lift device arranged to convey a vehicle delivered storage bin in a direction perpendicular to the lateral plane of the vehicle support between the vehicle support and a delivery station,

wherein the remotely operated vehicle comprises

5 a vehicle body comprising a first section for storing vehicle driving means and a second section for receiving any storage bin stored in a storage column within the storage system, the second section comprising a centrally arranged cavity within the vehicle body, the cavity having at least one bin receiving opening facing towards the storage columns during use,

a vehicle lifting device at least indirectly connected to the vehicle body for lifting the storage bin into the second section,

10 a first set of vehicle rolling means connected to the vehicle body allowing movement of the vehicle along the first direction (X) within the storage system during use and a second set of vehicle rolling means connected to the vehicle body allowing movement of the vehicle along the second direction (Y) in the storage system during use, the second direction (Y) being perpendicular to the first direction (X), at least one of the sets of vehicle rolling means being arranged fully within the vehicle body.

20 31. Storage system in accordance with claim 30, characterized in that at least some of the supporting rails arranged at the outer lateral border areas of the vehicle support form outer guiding meshes having reduced average cross section compared to the average cross section of the remaining guiding meshes in the vehicle support.

25 32. Storage system in accordance with claim 31, characterized in that the average reduced cross section of the outer guiding meshes are about half of the average cross section of the remaining guiding meshes in the vehicle support.

33. Storage system in accordance with claims 31 or 32, characterized in that the size of the outer guiding meshes are reduced only along the second direction (Y) of the vehicle support.

30 34. Storage system in accordance with any one of claims 31 to 33, characterized in that the vehicle further comprising means for reversibly and selectively displacing either the first set of vehicle rolling means or the second vehicle rolling means away from an underlying vehicle support within the storage system during a change of vehicle direction between the first direction (X) and the second direction (Y).

35 35. Storage system in accordance with any one of claims 31 to 34, characterized in that the vehicle body covers at most the lateral cross section of one central storage

column in the first direction (X) and covers the lateral cross section of more than one central storage column in the second direction (Y) during use.

5 36. Storage system in accordance with any one of claims 31 to 35, characterized in that the vehicle body extends beyond the lateral cross section of the central storage column at both sides in the second direction (Y).

10 37. Storage system in accordance with claim 36, characterized in that the extension beyond the lateral cross section of the central storage column is equal on both sides in the second direction (Y).

15 38. Storage system in accordance with any one of claims 31 to 37, characterized in that both sets of vehicle rolling means are symmetrically distributed around the centrally arranged cavity.

39. Storage system in accordance with any one of claims 31 to 38, characterized in that at least one set of vehicle rolling means comprises at least four wheels.

20 40. Storage system in accordance with any one of claims 31 to 39, characterized in that both sets of vehicle rolling means have an exterior design matching a corresponding exterior design on supporting rails constituting the vehicle support in order to provide increased lateral stability when interconnected, wherein the supporting rails are arranged in a two dimensional matrix on top of a bin storing structure, the principal directions of the matrix and the bin storing structure being
25 congruent with the first direction (X) and second direction (Y) of the vehicle.

30 41. Storage system in accordance with any one of claims 31 to 40, characterized in that the vehicle comprises position sensing means to allow measurements of the vehicle position within the storage system during use.

42. Storage system in accordance with claim 41, characterized in that the position sensing means comprising a plurality of sensors arranged in at least some of the positions on the vehicle body which, during use, transverses the positions of vehicle support where the supporting rails are crossing.

35 43. Remotely operated vehicle for picking up storage bins from a storage system, comprising

a vehicle body comprising a first section for storing vehicle driving means and a second section for receiving any storage bin stored in a storage column within the storage system,

5 a vehicle lifting device at least indirectly connected to the vehicle body for lifting the storage bin into the second section,

a first set of vehicle rolling means connected to the vehicle body allowing movement of the vehicle along a first direction (X) within the storage system during use and

10 a second set of vehicle rolling means connected to the vehicle body allowing movement of the vehicle along a second direction (Y) in the storage system during use,

the second direction (Y) being perpendicular to the first direction (X),

characterized in that

15 the second section comprising a centrally arranged cavity within the vehicle body, the cavity having at least one bin receiving opening facing towards the storage columns during use, and

at least one of the sets of vehicle rolling means is arranged fully within the vehicle body.

20 44. Remotely operated vehicle in accordance with claim 43, **characterized in that** the vehicle further comprising means for reversibly and selectively displacing either the first set of vehicle rolling means or the second vehicle rolling means away from an underlying vehicle support within the storage system during a change of vehicle direction between the first direction (X) and the second direction (Y).

25

45. A robot vehicle for transporting storage bins in a bin storage system, comprising

a. a vehicle body,

b. a plurality of rolling members attached to the vehicle body, arranged

30 for traveling in a first and second directions along a plurality of rolling tracks of the bin storage system, said bin storage system being of the type comprising:

i. a three-dimensional storage structure comprising a plurality of pillars which are positioned with internal distances and in a rectangular arrangement, wherein the

35 rectangular arrangement of the pillars define storage columns for the storage of a plurality of vertically-stacked storage bins,

ii. supporting rails arranged in a two-dimensional matrix on top of the pillars, said supporting rails defining rolling tracks

arranged in a first direction and a second direction orthogonal to the first direction, the supporting rails further defining openings for the storage columns,

- 5 c. a cavity arranged internally within the vehicle body arranged to receive a storage bin from a storage column.

46. A robot vehicle according to claim 45, wherein the cavity comprises a downwardly facing opening of essentially the same width and length as the openings for the storage columns.

10

47. A robot vehicle according to claim 46, wherein the vehicle body has a width and length such that a single robot vehicle essentially covers a single opening while retrieving a storage bin, whereby a second robot vehicle can traverse an adjacent column unhindered by a first robot vehicle.

15

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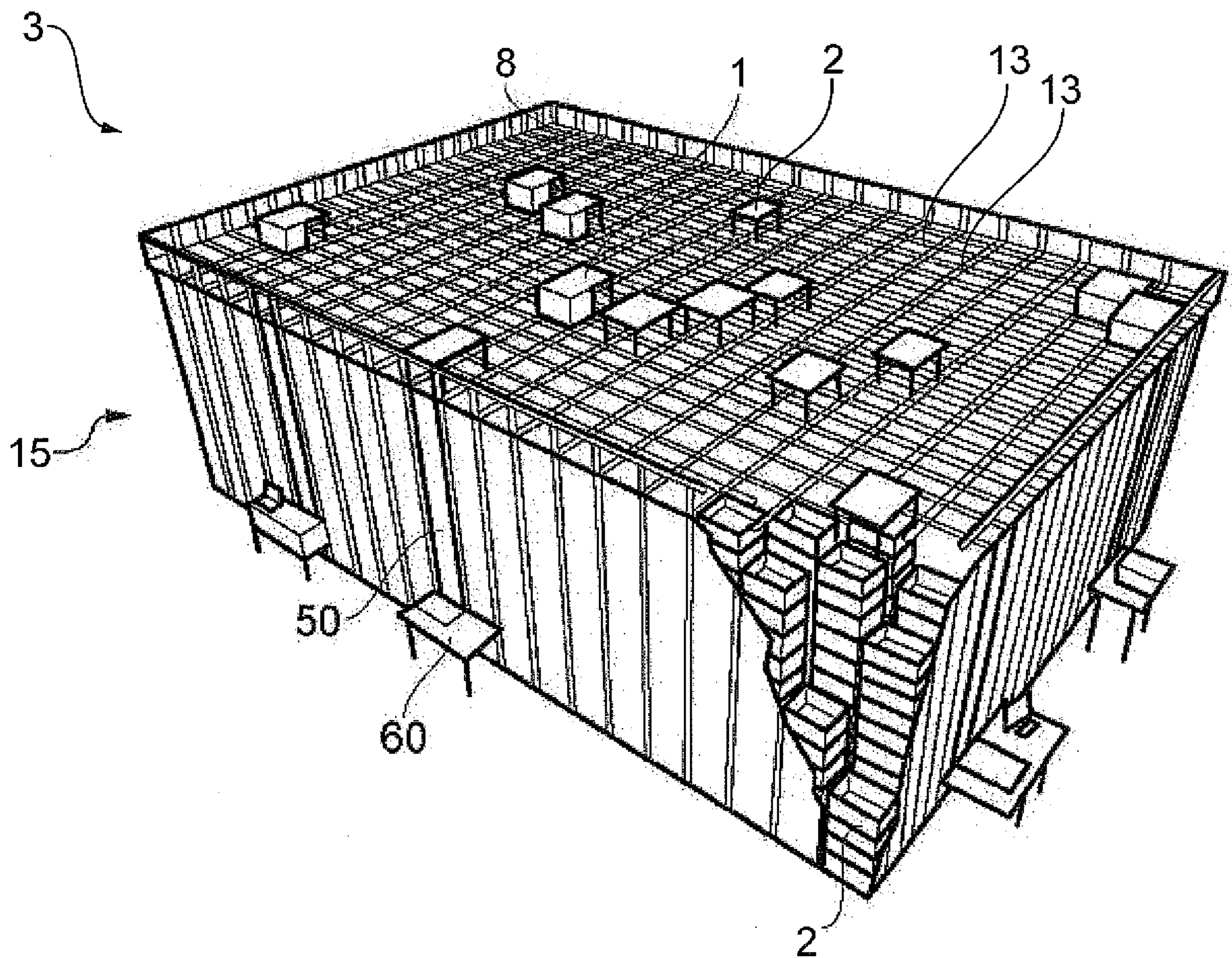


FIG. 1 (Prior Art)

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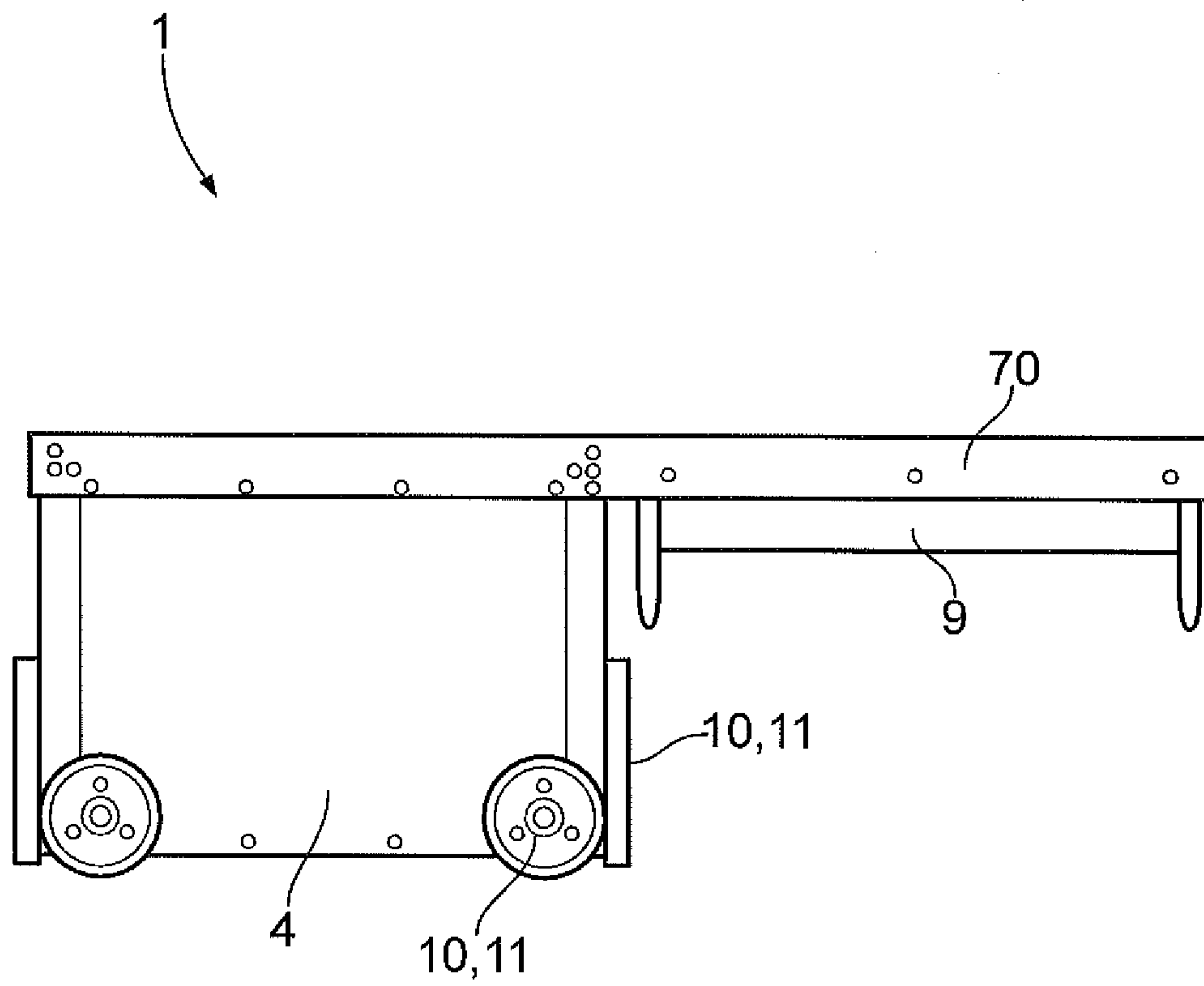


FIG. 2 (Prior Art)

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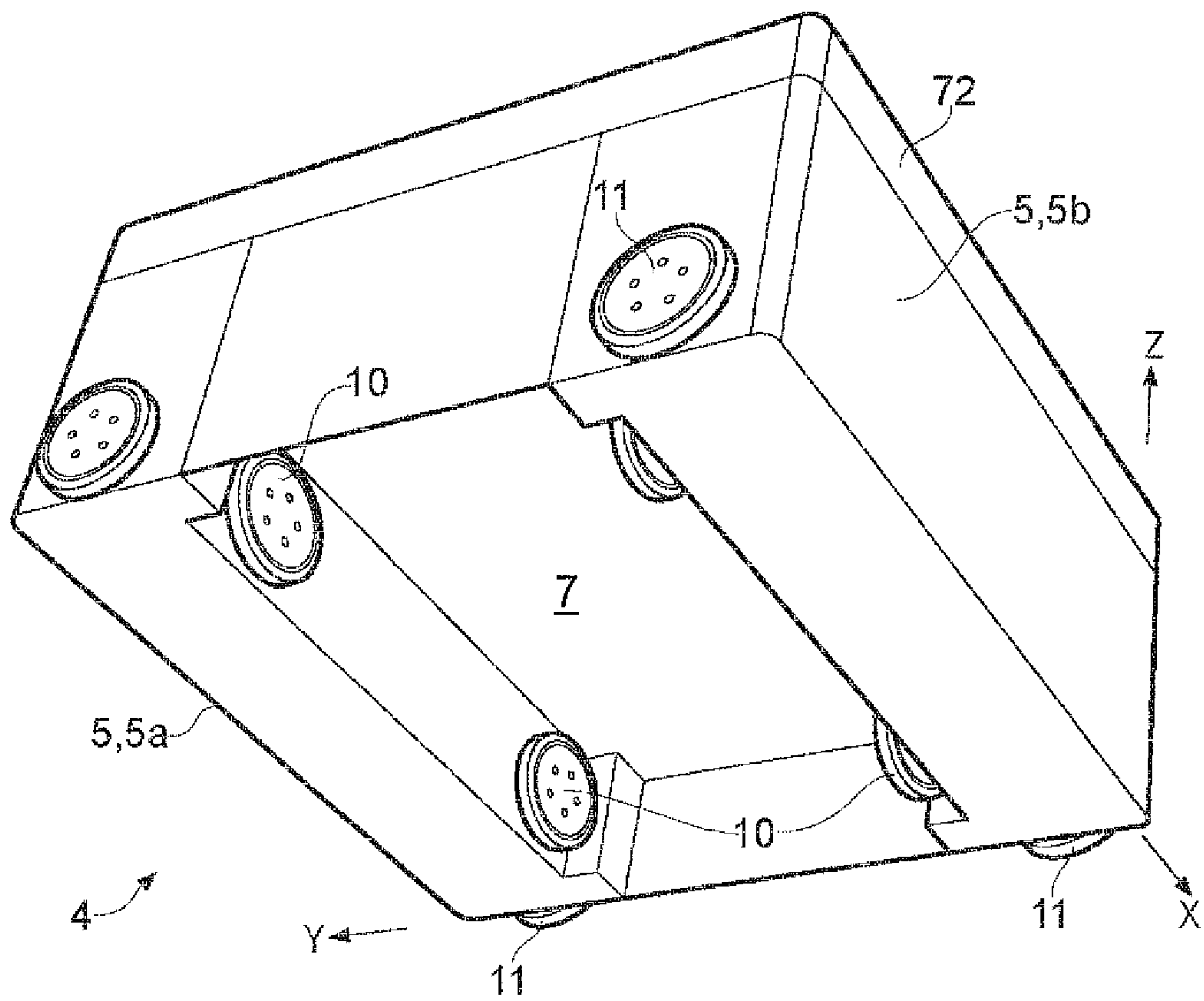


FIG. 3

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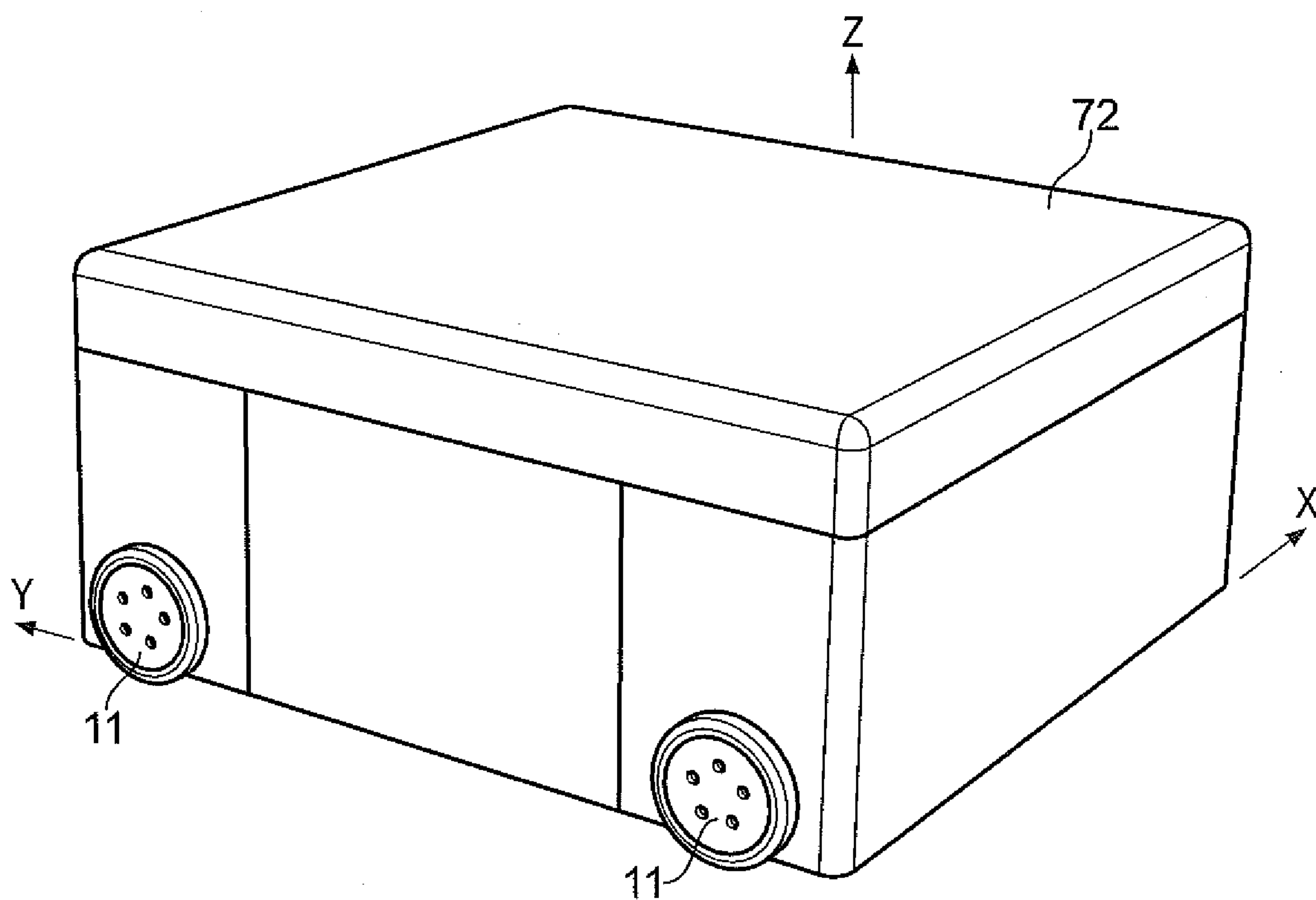


FIG. 4

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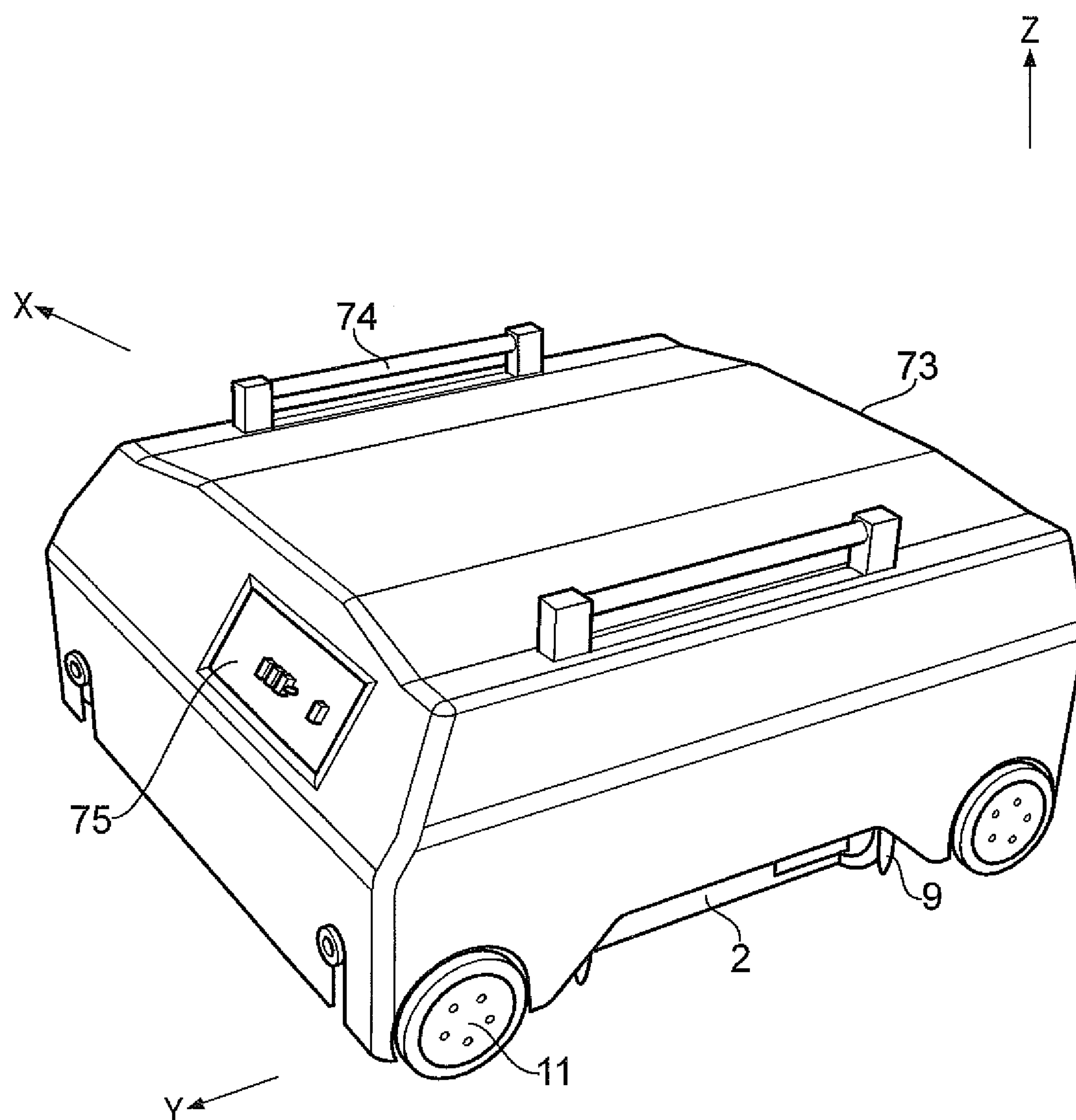


FIG. 5

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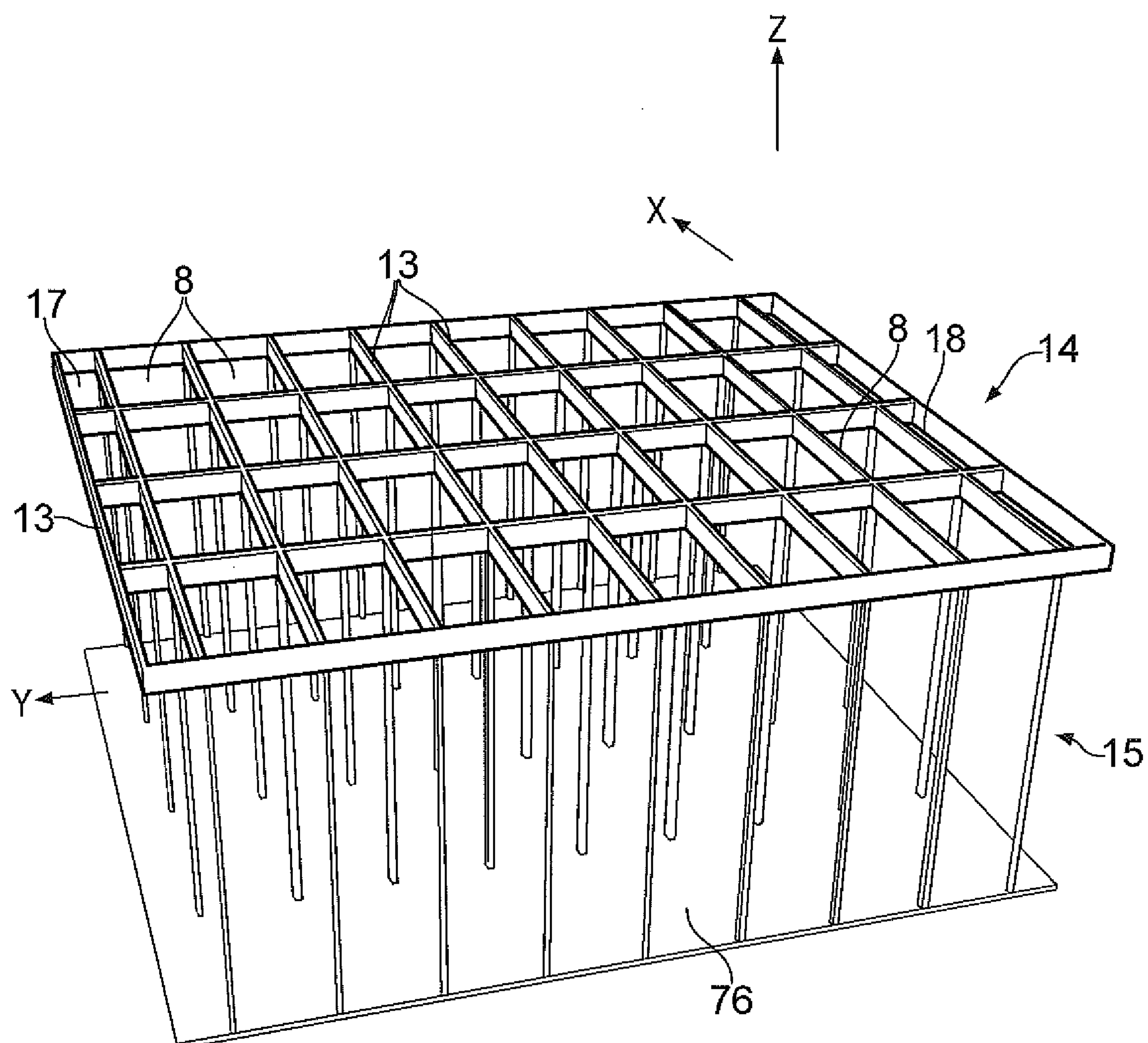


FIG. 6

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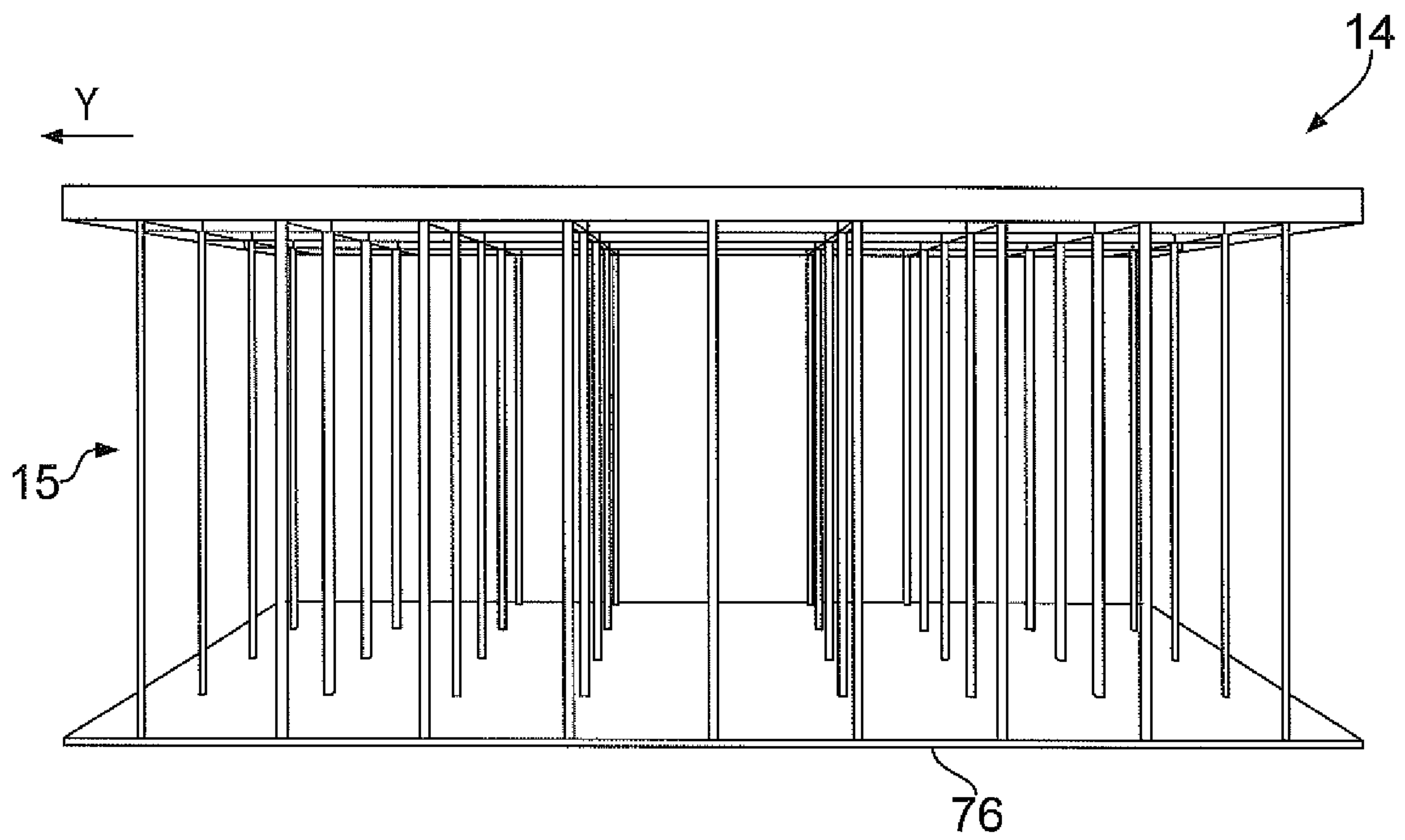


FIG. 7

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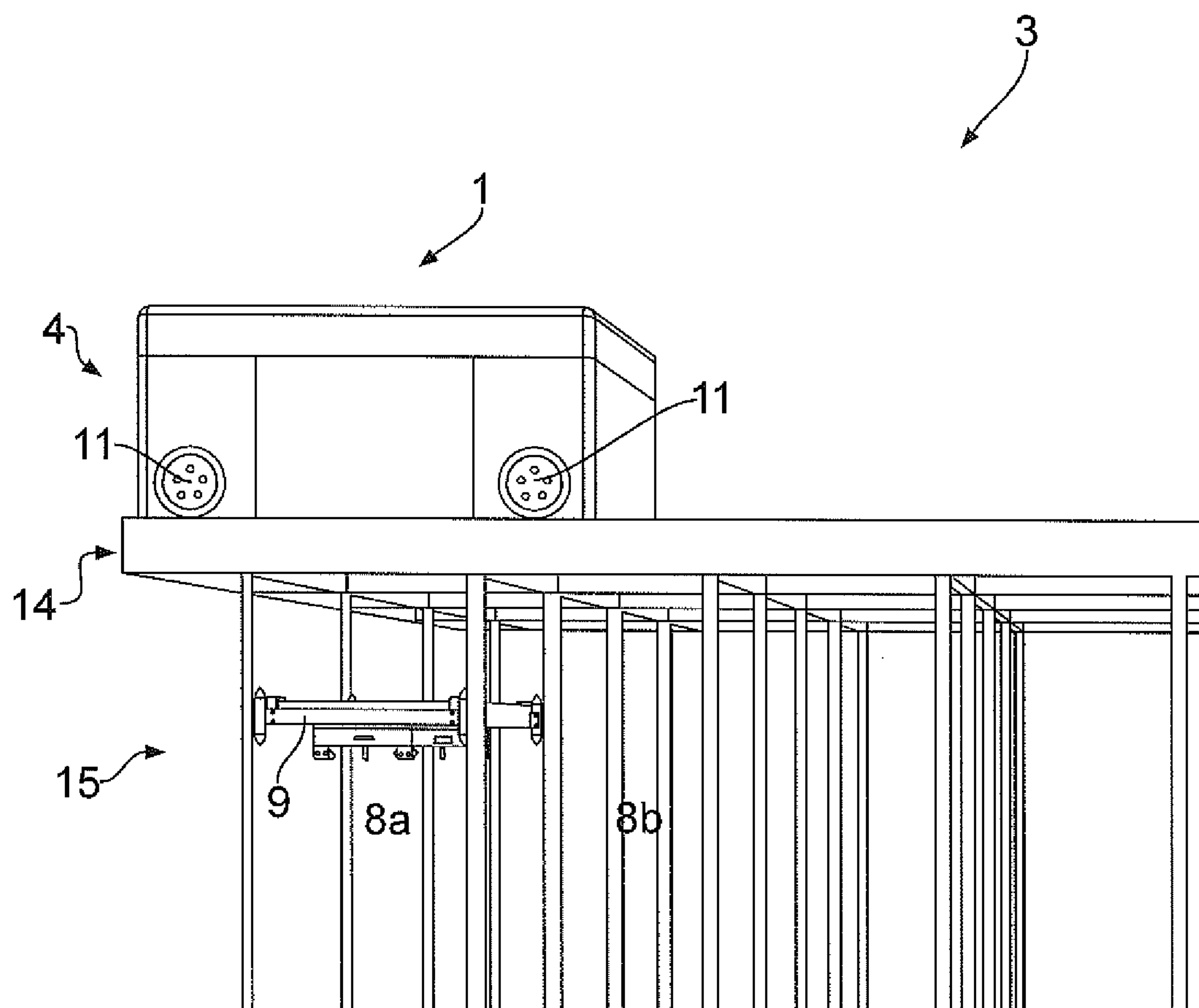


FIG. 8

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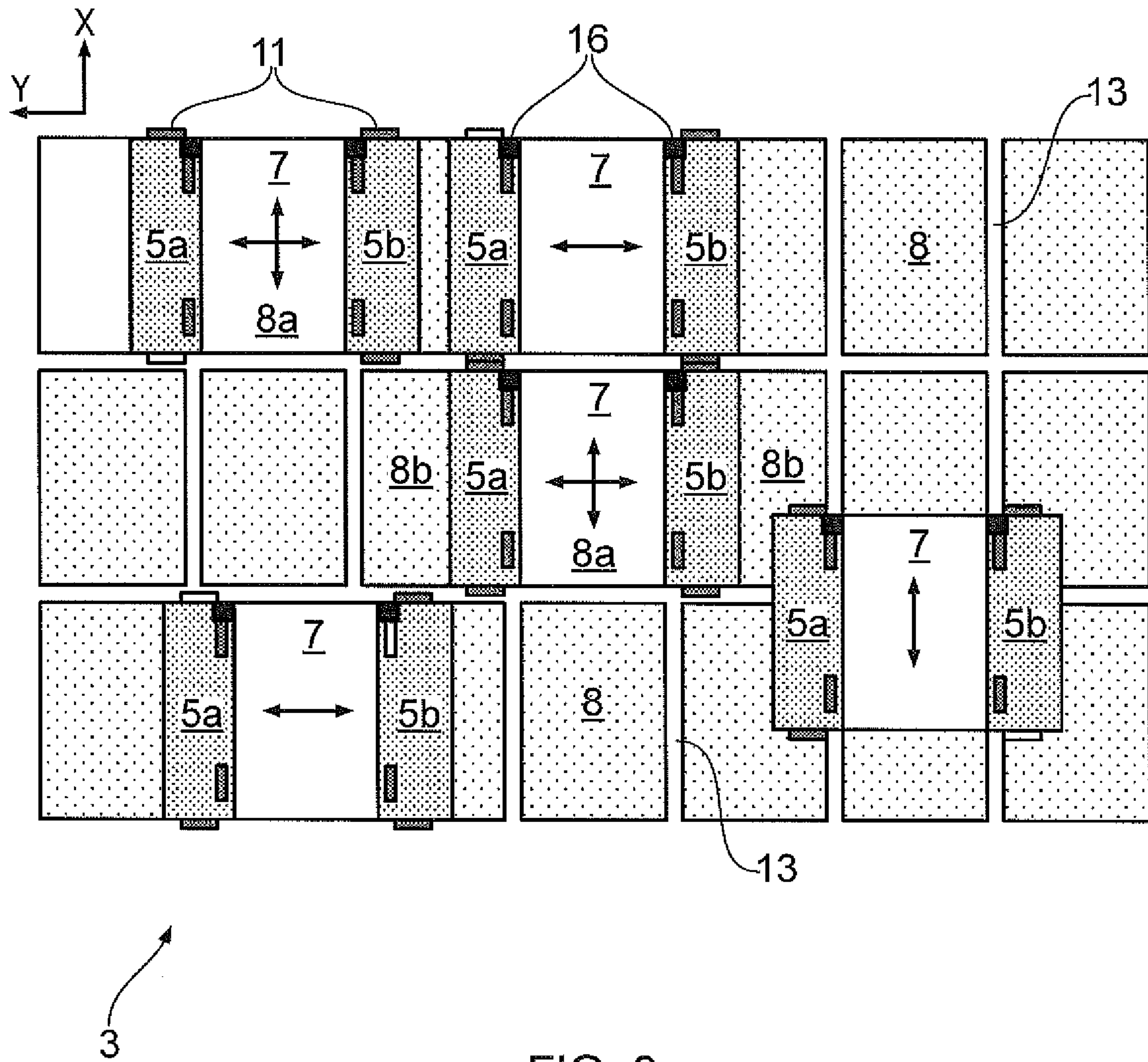


FIG. 9

